
Data Structure

7. Heap

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Heaps

Date

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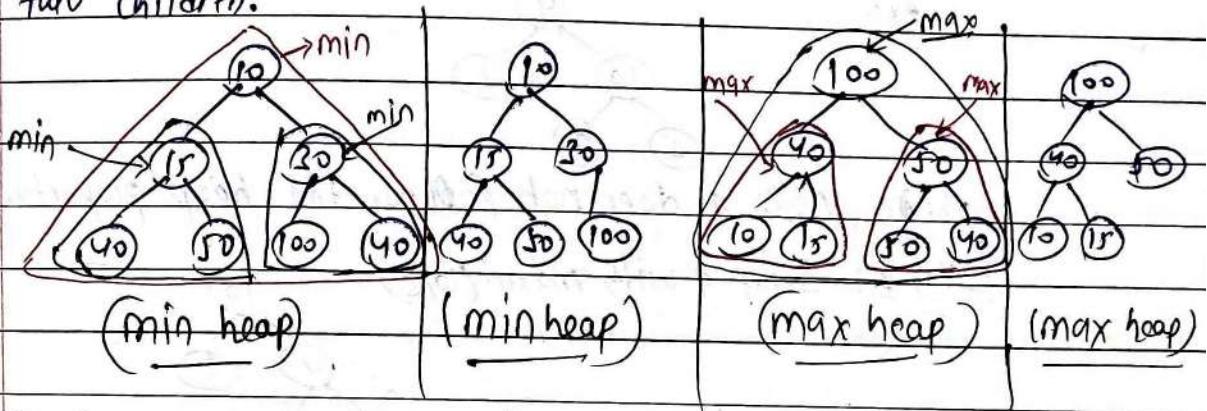
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① Introduction

- A Heap is a Tree-based ds. with condition
 - A Heap is a complete tree (A level are completely filled except possibly the last level and the last level has all keys as left as possible)
 - A Heap is either Min Heap or Max Heap. In a min-Heap, the key at root must be minimum among all keys present in the heap. The same property must be true for all nodes.

② Binary Heap:-

A Binary Heap is a Heap where each node can have at most two children.



③ Representing Binary Heaps:-

- since a Binary heap is a complete Binary Tree, it can be easily represented using array.
- The root element will be at $\text{Arr}[0]$.
- For any i^{th} node, i.e., $\text{Arr}[i]$:

$\text{Arr}[(i-1)/2]$ Return the parent node

$\text{Arr}[(2*i)+1]$ Return the left child node

$\text{Arr}[(2*i)+2]$ Return the right child node

Getting maxm element: the maxm element in a max heap is always at root i.e $\text{Arr}[0]$, can be accessed in $O(1)$ time.

Getting minm element: the minm element in a min heap is always at root i.e $\text{Arr}[0]$, can be accessed in $O(1)$ time.

Ex:-

$10/15/20/10/50/100/40$

(min heap)

Ex:-

$100/40/50/10/15/50/40$

(max heap)

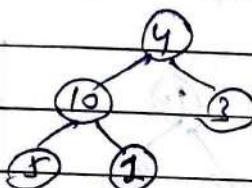
* Heapifying an element :-

- Generally, on inserting a new element onto a heap, it does not satisfy the property of Heap. the process of placing the element at the correct location so that it satisfies the heap property is known as heapify.

Heapifying in a Max Heap:-

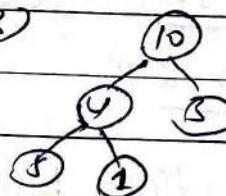
the max-heap says that every node's value must be greater than the values of its children nodes, so, to heapify a particular node swap the value of node with the maximum value of its children nodes and continue until become heap.

ex:-



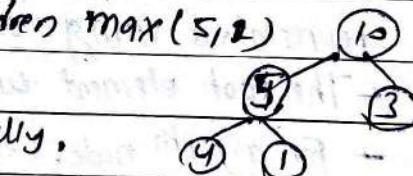
- here, Node 4 does not follow the heap property. let's

Step 1 :- swap 4 with max(10, 3)



Step 2 :- again node 4 does not heap property. swap 4 with maximum of its new children max(5, 1)

Node 4 is now heapified successfully.



Note :- Time complexity to heapify a single node is $O(h)$,
here $n =$ total no. of element in heap. $O(n \log n)$

(2) Insertion & Deletion in Heaps :-

* Deletion in Heap :-

- Given a Binary heap & an element present in the given heap. The task is to delete that element from heap.
- The standard deletion is to delete the max/min element present at root of heap.

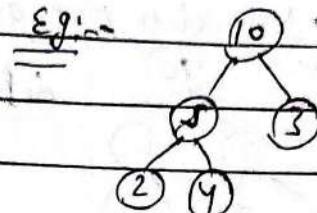
(O(logn))
(i) Process of root Deletion: Extract max, Extract min (O(1))

since deleting from intermediate position is costly from a heap,
so we can simply replace with last element & delete last.

→ Replace the root by last

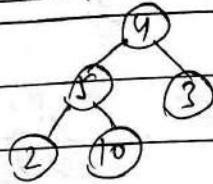
→ Delete last from the heap

→ since now last element position
is changed so heapify them

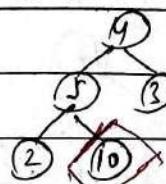


delete: 10

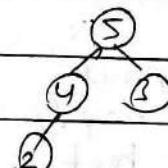
① Replace with last



② Delete last



③ heapify Root(4)



Code:-

~~#include <iostream.h>~~

void heapify(int arr[], int n, int i); // Heapify

int largest = i;

int l = 2 * i + 1;

int r = 2 * i + 2;

if (l < n && arr[l] > arr[largest])

largest = l;

if (r < n && arr[r] > arr[largest])

largest = r;

if (largest != i) { swap(arr[i], arr[largest]);

heapify(arr, n, largest);

}

void deleteRoot(int arr[], int &n); // delete root.

int lastElement = arr[n - 1];

arr[0] = lastElement;

n = n - 1;

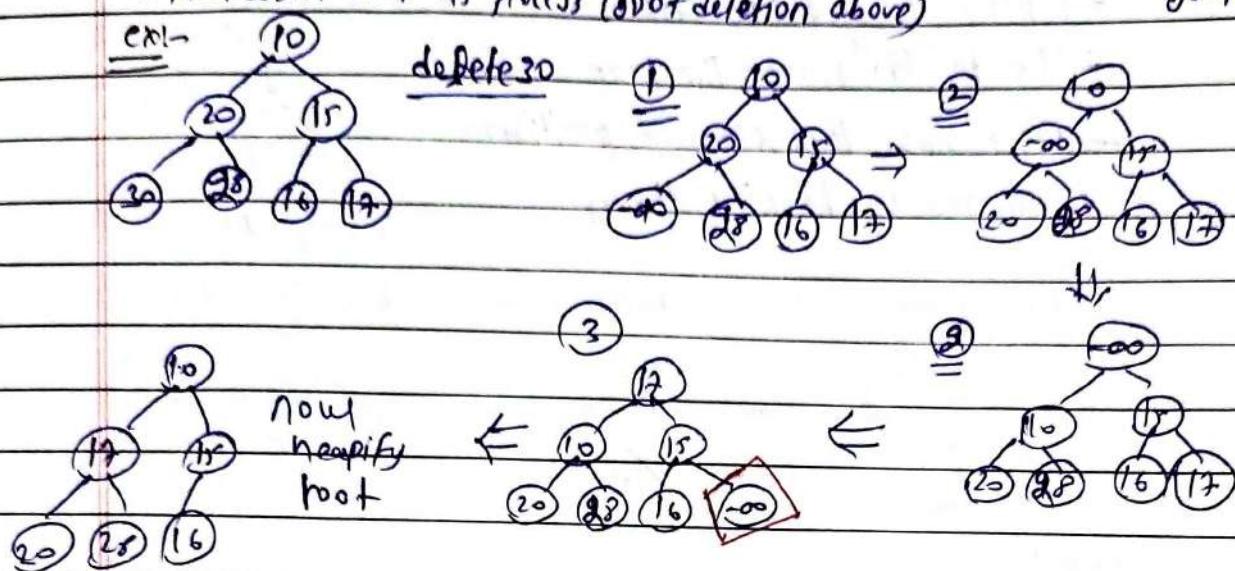
heapify(arr, n, 0);

$O(h) = O(\log n)$

{

(iii) delete non-root element at given index in min heap

- Replace the element to be deleted with minus infinite.
- keep swapping the minus infinite value with parent until it reaches root
- Now delete root as process (root deletion above)



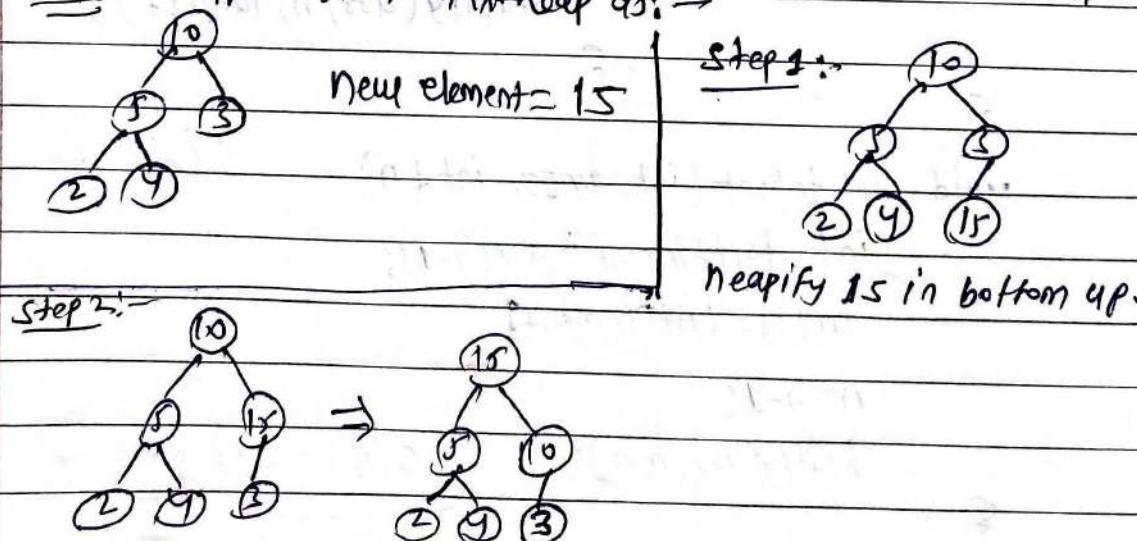
* Insertion in Heaps:-

- Insert a given element to the given heap maintaining the properties of Heap,

process of insertion :-

- increase the heap size by 1. to store new element.
- insert new element at end of the heap.
- this new element may distort properties of Heap for its parent, so heapify this newly inserted element following a bottom up approach.

Ex:- Suppose given max-heap as:-



Code:-

n2size, key = element insert

```

→ ① void heapify(int arr[], int n, int i) {
    int parent = (i-1)/2;
    if (parent >= 0) {
        if (arr[i] > arr[parent]) {
            swap(arr[i], arr[parent]);
            heapify(arr, n, parent);
        }
    }
}
  
```

```

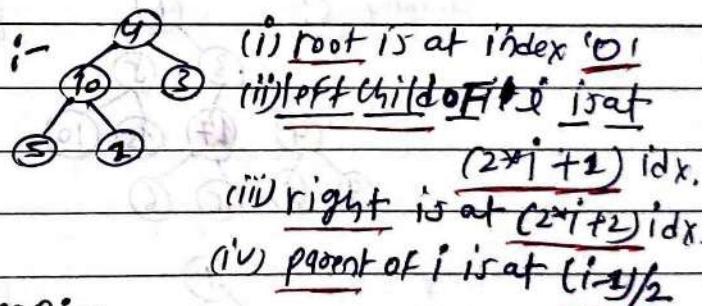
→ ② void insertNode(int arr[], int n, int key) {
    n = n + 1;
    arr[n-1] = key;
    heapify(arr, n, n-1); TR: O(log n)
}
  
```

③ Building Heap:-

- Given N elements the task is to build a Binary Heap from the given array. Heap can be max Heap or min Heap.

Ex:- Given elements are [4, 10, 3, 5, 1].

complete binary tree will be :-



Process to make Max-Heap:-

- The idea is to make heapify the complete binary tree formed from the array in reverse level order following top-down approach.
- That is first heapify the last node in level order traversal of tree, then heapify the second last node & so on.

Time complexity:- Heap a single node take $O(1 \log N)$, so heapify total N nodes will take $O(N * \log N)$ time.

①

$$\begin{aligned} & \therefore \text{maxm no. of nodes at height } h = \left\lceil \frac{N}{2^{h+1}} \right\rceil \rightarrow \text{Proof of } O(N) \text{ time.} \\ & \therefore \text{total time for level } h \text{ to heapify} = \left\lceil \frac{N}{2^{h+1}} \right\rceil \cdot O(h) \rightarrow \text{we have to go } h \text{ elements above.} \\ & \therefore \text{for all nodes at each level } T_C = \sum_{h=0}^{\log N} \left\lceil \frac{N}{2^{h+1}} \right\rceil \cdot O(h) = O(N) \end{aligned}$$

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Optimized approach :- ($T: O(N)$)

- the leaf node need not to be heapified as they already follow the heap property. Also, the array representation of complete binary tree contains the level order traversal.
- So the idea is to find the position of the last non-leaf node and perform the heapify operation of each non-leaf node in reverse level order.

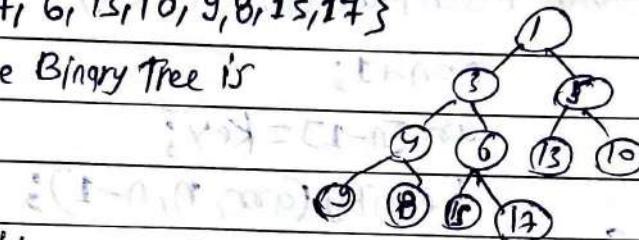
last non-leaf node = parent of last.node($n-1$)

$$= ((n-1)-1)/2 = (n-2)/2$$

Ex:-

$$\text{array} = \{1, 3, 5, 4, 6, 13, 10, 9, 8, 15, 17\}$$

corresponding complete Binary Tree is



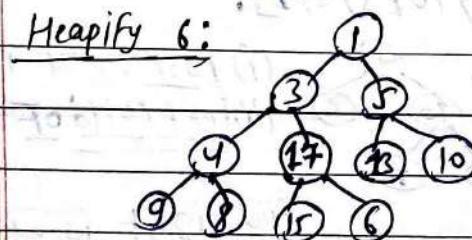
* The task is to build a max-heap from above array.

Total Nodes = 11. \therefore Last Non-leaf node index = $(9/2) = 4$

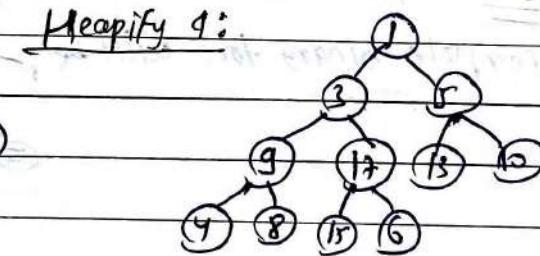
\therefore , Last non-leaf node = arr[4] = 6.

To build the heap; heapify only the nodes: [1, 3, 5, 4, 6] in reverse.

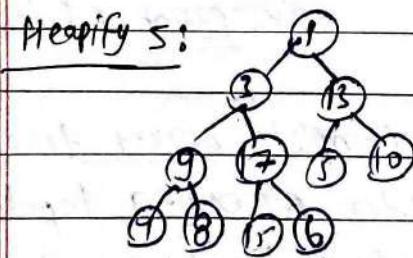
Heapify 6:



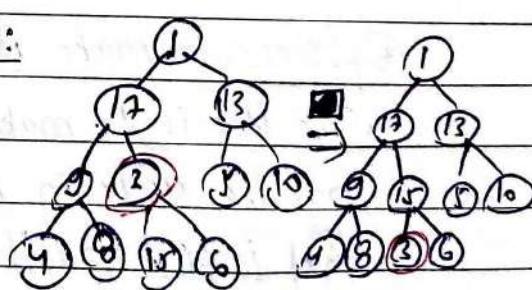
Heapify 4:



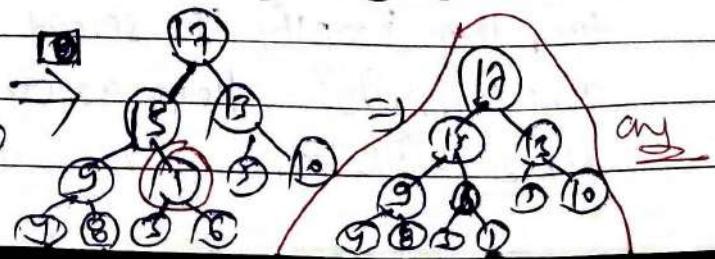
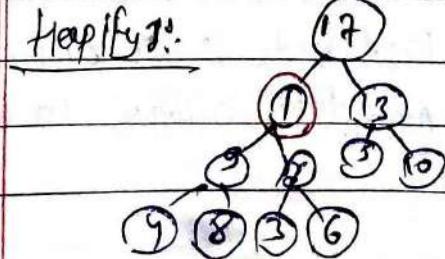
Heapify 5:



Heapify 3:



Heapify 1:



$$\begin{aligned}
 \text{(ii)} \quad & \sum_{h=0}^{\log N} \left\lceil \frac{N}{2^{h+1}} \right\rceil \cdot O(h) = \sum_{h=0}^{\log N} \left\lceil \frac{N}{2^{h+1}} \right\rceil \cdot (Ch) \\
 & = \frac{N}{2} \sum_{h=0}^{\log N} \left(\frac{N}{2^h} \right) = \frac{N}{2} \times 2 = O(N) = O(N)
 \end{aligned}$$

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Code:-

```
#include <bits/stdc++.h>
using namespace std;
```

void heapify (int arr[], int n, int i) {

```
    int largest = i;
```

```
    int l = 2 * i + 1;
```

```
    int r = 2 * i + 2;
```

```
    if (l < n && arr[l] > arr[largest]) largest = l;
```

```
    if (r < n && arr[r] > arr[largest]) largest = r;
```

```
    if (largest != i) {
```

```
        swap (arr[i], arr[largest]);
```

```
        heapify (arr, n, largest);
```

```
}
```

```
{
```

void buildHeap (int arr[], int n) {

```
    int startIdx = (n - 2) / 2;
```

```
    for (int i = startIdx; i >= 0; i--) { heapify (arr, n, i); }
```

```
}
```

```
int main () {
```

```
    int arr[] = {1, 3, 5, 4, 6, 13, 10, 9, 8, 15, 17};
```

```
    int n = sizeof (arr) / sizeof (arr[0]);
```

```
    buildHeap (arr, n);
```

```
    for (int i = 0; i < n; i++) cout << arr[i] << " ";
```

```
    return 0;
```

```
1 17 15 13 9 6 5 20 48 3 1
```

```
{
```

4. Heaps in C++ (using built-in class/priority queue):-

- in C++ the priority_queue container can be used to implement Heaps.

- priority_queue is built-in container used to implement priority queue.

- This container uses max-heap internally to implement a priority queue efficiently. Therefore it can be used in-place of max-heaps.

- This container can also be modified by passing some additional parameters to be used as a min heap.

Syntax: For implementing Max Heap.

priority_queue<type-of-data> name_of_heap;

Syntax: For implementing Min Heap.

priority_queue<type, vector<type>, greater<type>> name_of_heap;

* Methods of Priority Queue:

$O(1)$ // priority_queue::empty():- return whether the queue is empty or not.

$O(1)$ // priority_queue::size():- return size of the queue.

$O(1)$ // priority_queue::top():- return reference to the top most element

$O(\log n)$ // priority_queue::push():- The push(g) will add 'g' to end of queue.

$O(\log n)$ // priority_queue::pop():- delete first element of queue.

• priority_queue::swap():- swap content of two priority queue.

* Code:

```
#include <iostream>
#include <queue>
```

```
using namespace std;
```

```
int main() {
```

```
    priority_queue<int> max_heap; // max heap
    max_heap.push(10);
    max_heap.push(30); ] (Add element to the max Heap
    max_heap.push(20); in any order) O(N)
    max_heap.push(5);
    max_heap.push(1);
```

```
    while (!max_heap.empty())
```

```
        cout << max_heap.top() << " ";
```

```
        max_heap.pop();
```

```
{
```

(print element at top
of heap & remove
element every time from
top until become
empty)

// 30 20 20 5 1

```

// min Heap
priority_queue<int, vector<int>, greater<int>> min-heap;
min-heap.push(10);
min-heap.push(30);
min-heap.push(20);
min-heap.push(5);
min-heap.push(1);

while(!min-heap.empty()) {
    cout << min-heap.top() << " ";
    min-heap.pop();
}
return 0;
}

```

1 5 10 20 30

5) Heap Implementation (Push | Pop) :-

```

#include <bits/stdc++.h>
using namespace std;
#define SIZE 2002

```

```

int heap[SIZE];
int heapSize;
void heapPush(int val) {
    if (heapSize == SIZE) {
        cout << "Overflow" << endl;
        return;
    }

```

```

    heap[heapSize] = val;

```

```

    int curr = heapSize;

```

```

    while (curr > 0 and heap[(curr - 1) / 2] < heap[curr]) {

```

```

        int temp = heap[(curr - 1) / 2];

```

```

        heap[(curr - 1) / 2] = heap[curr];

```

```

        heap[curr] = temp;

```

```

        curr = (curr - 1) / 2;
    }

```

```

    heapSize++;
}

```

```
int heap_pop() {
```

```
    if (heapSize <= 0) {
```

```
        cout << "Underflow in";
```

```
        return -1;
```

```
    int curr = 0;
```

```
    int popped = heap[0];
```

```
    heap[0] = heap[heapSize - 1];
```

```
    heapSize -= 1;
```

```
    while ((2 * curr + 1) < heapSize) {
```

```
        int largest = heap[curr];
```

```
        if (l = 2 * curr + 1;
```

```
        int r = 2 * curr + 2;
```

```
        if (l < heapSize && heap[l] > heap[largest])
```

```
            largest = l;
```

```
        if (r < heapSize && heap[r] > heap[largest])
```

```
            largest = r;
```

```
        if (largest != curr) {
```

```
            int temp = heap[curr];
```

```
            heap[curr] = heap[largest];
```

```
            heap[largest] = temp;
```

```
            curr = largest;
```

```
}
```

```
        else break;
```

```
    return popped;
```

```
}
```

```
void show_heap() {
```

```
    for (int i = 0; i < heapSize; ++i) cout << heap[i] << "
```

```
    cout << endl;
```

```
}
```

```

int main()
{
    heapSize = 0;
    while(1)
    {
        cout << "1: Push... 2: Pop... 3: Show Heap... 4: Terminate";
        int option, element;
        cin >> option;
        switch(option)
        {
            case 1:
                cout << "Enter Element In ";
                cin >> element;
                heapPush(element);
                break;
            case 2:
                cout << "Popped " << heapPop() << "\n";
                break;
            case 3:
                showHeap();
                break;
            default:
                return 0;
        }
    }
}

```

Note :- Similarly min heap can be implemented with min heap properties.

(6) Heap Sort (Ascending Order):-

- it is comparison based sorting technique based on Binary Heap DS.
- it is similar to selection sort where we first find the maxm element and place the maximum element at the end. we repeat the same process for remaining element.

Code:-

```

void heapify(arr[], n, i)
{
    largest = i;
    l = 2 * i + 1;
    r = 2 * i + 2;
    if(l < n && arr[largest] < arr[l])
        largest = l;
    if(r < n && arr[largest] < arr[r])
        largest = r;
    if(largest != i)
    {
        swap(arr[i], arr[largest]);
        heapify(arr, n, largest);
    }
}

```

if ($i < n$ && $arr[largest] < arr[i]$) $largest = i$;

if ($largest \neq i$) {

swap ($arr[i]$, $arr[largest]$)

heapify ($arr, n, largest$)

$\text{O}(\log n)$

}

void heapSort($arr[], n$) {

for (int $i = \lfloor n/2 \rfloor - 1$; $i \geq 0$; $i--$) // build heap
 heapify (arr, n, i); // $O(n)$

for (int $i = n-1$; $i \geq 0$; $i--$) {

swap ($arr[0]$, $arr[i]$); // move root to the end

heapify ($arr, i, 0$); // heapify swapped root.

$\text{O}(n)$

$T: O(n \log n)$

⑦ k^{th} Smallest / Largest Element in Unsorted Array:

Given an array and a number k where k is smaller than size of array. we need to find the k^{th} smallest element in the given array. it is given that elements are distinct

Approach:- Create min heap and extract k element from the element, k^{th} extracted element will be the k^{th} smallest element in the array.

Code:-

~~visit Data Structures and~~
~~discrete mathematics;~~

#include <iostream>

using namespace std;

class minHeap{

int* harr;

int capacity;

int heap_size;

public:

minHeap (int ac[], int size);

void minHeapify (int i);

int parent (int i) { return (i-1)/2; }

int left (int i) { return (2*i+1); }

int right (int i) { return (2*i+2); }

int extractMin();

int getMin() { return harr[0]; }

};

minHeap::minHeap (int ac[], int size) {

heap_size = size;

harr = ac;

int i = (heap_size - 1)/2;

while (i >= 0) {

minHeapify (i);

};

int minHeap::extractMin() {

if (heap_size == 0) return INT_MAX;

int root = harr[0];

if (heap_size > 1) {

harr[0] = harr[heap_size - 1];

minHeapify (0);

};

heap_size--;

return root;

};

```

void minHeap::minHeapify (int i) {
    int l = left(i);
    int r = right(i);
    int smallest = i;
    if (l < heap_size && heap[l] < heap[i]) smallest = l;
    if (r < heap_size && heap[r] < heap[smallest]) smallest = r;
    if (smallest != i) {
        swap(heap[i], heap[smallest]);
        minHeapify(smallest);
    }
}

```

```

int kthSmallest (int arr[], int n, int k) {
    minHeap mh(arr, n);
    for (int i=0; i<k-1; i++) mh.extractMin();
    return mh.getMin();
}

```

```

int main() {
    int arr[] = {12, 3, 5, 7, 25};
    int n = sizeof(arr) / sizeof(arr[0]), k=2;
    cout << "kth smallest element is" << kthSmallest(arr, n, k);
    return 0;
}

```

TC : O(n + k log n)

② using min-heap STL priority queues:

```

int findKthLargest (vector<int>& nums, int k) {
    priority_queue<int, vector<int>, greater<int> pq;
    for (int num : nums) {
        pq.push(num);
        if (pq.size() > k) {
            pq.pop();
        }
    }
    return pq.top();
}

```

③ max-heap using priority queue:

```
int findKthLargest(vector<int> &nums, int k) {
    priority_queue<int> pq(nums.begin(), nums.end());
    for (int i = 0; i < k - 1; i++) {
        pq.pop();
    }
    return pq.top();
}
```

⑧ Find Median From data stream:

The median is the middle value in an ordered integer list, if the size of the list is even, there is no middle value and the median is the mean of the two middle values.

- ex: for arr = [2, 3, 4], the median is 3.
- for arr = [2, 3], the median is $(2+3)/2 = 2.5$

Implement the MedianFinder class:

- MedianFinder(): initializes the MedianFinder object
- void addNum(int num): adds the integer num from the data stream to OJ
- double findMedian(): return the median of element so far in OJ.

Process:-

① Create two heaps. One max heap to maintain element of lower half and one min heap to maintain element of higher half at any point of time

② For every newly adding element, insert it into either max heap or min, if there is odd element then one of them will be greater size ^{lets} so take max heap as one greater.

case (i) - if, max heap size is zero add element in max heap.

case (ii) - else if, both heap size are equal the compare from top of min heap if, number is less than top of min heap then add into max heap. else, pop from min heap and popped element into max heap and add new element to min heap.

Case (iii) If both size are not equal i.e max-heap greater

- else, if min-heap size is zero but max-heap is not zero:-
IF, (^{new} inserted) element is greater than max-heap ^{top} element
push/add new element to min-heap.
- else, pop element from max-heap and pushed into min-heap and add new element to max-heap.
- else, if new > min-heap.top() push into min-heap.
else num < max-heap.top(), pop from max-heap push into min-heap and push new element to max-heap.
- else, push new element to min-heap.

(3) To calculate median if no. is odd take max-heap top if even take top from both and calculate average.

Code :-

Class MedianFinder

public:

priority-queue<int> maxheap;

priority-queue<int, vector<int>, greater<int>> minheap;

medianFinder();

void addNum(int num){

int lsize = maxheap.size();

int rsize = minheap.size();

Case (i) if (lsize == 0) maxheap.push(num);

Case (ii) else if (lsize == rsize) if

if (num < minheap.top()) maxheap.push(num);

else if

int temp = minheap.top();

minheap.pop();

minheap.push(num);

maxheap.push(temp);

}

{

case (iii) else

```

; if (minheap.size() == 0) {
;   ; if (num > maxheap.top()) minheap.push(num);
;   ; else
;     ;   int temp = maxheap.top();
;     ;   maxheap.pop();
;     ;   maxheap.push(num);
;     ;   minheap.push(temp);
;   ;
; } else if (num >= minheap.top()) minheap.push(num)
; else
;   ; if (num < maxheap.top()) {
;     ;   int temp = maxheap.pop();
;     ;   maxheap.pop();
;     ;   maxheap.push(num);
;     ;   minheap.push(temp);
;   ;
; } else minheap.push(num);
;
}

```

double findMedian()

int lsize = maxheap.size();

int rsize = minheap.size();

if (lsize > rsize) return double(maxheap.top());

else return (double(maxheap.top()) + double(minheap.top())) / 2;

};

TC: $O(n \log n)$ | SC: $O(n)$

⑨ Return k largest element in array.

push the all element one by one in min-heap when min-heap size become greater than k, pop the top element i.e. min element at that time. at last we have k size min-heap which is k largest element.

```

void findKlargest (vector<int> &nums, int k) {
    priority_queue<int, vector<int>, greater<int>> min-heap;
    for (int num : nums) {
        min-heap.push (num);
        if (min-heap.size () > k)
            min-heap.pop ();
    }
    for (auto num : min-heap)
        cout << num << " ";
}
    
```

$O(n) \neq O(2\log k)$ or
 ~~$T.C.: O(n\log n)$~~ $O(n\log k)$
~~and $O(n\log n)$~~

⑩ Sort a k-sorted Array / Nearly Sorted

- Given an array of n elements, where each element is at most k away from its target position. sort them.

Ex:- $\text{arr}[] = \{6, 5, 3, 2, 8, 10, 9\}$, $k=3$

i.e 6 will be at any index (0, 1, 2),
~~1, 2, 3, 4~~

i.e 5 will be at any index (1, 2, 3, 4)

i.e 3 element can be before k distance or, after k -distance

..... 6, 1, 5, 3, 2, 8, 10, 9

$\leftarrow \leftarrow \rightarrow \rightarrow$

2 can be at any index in range ($k+k$)

Q/P $\{2, 3, 5, 6, 8, 9, 10\}$

Approach 1:- use insertion sort

$T.C.: O(nk)$, The inner-loop (For insertion) will ~~loop~~ at most k times.

Code:-

```

void insertionSort (int A[], int size) {
    for (int i=1; i<size; i++) {
        int key = A[i], j = i-1;
        while (j >= 0 && A[j] > key) {
            A[j+1] = A[j];
            j = j-1;
        }
        A[j+1] = key;
    }
}
    
```

Approach 2 : Using heap

```

void sortKClosest(int arr[], int n, int k) {
    int size = (n <= k) ? k : n - k;
    priority_queue<int, vector<int>, greater<int> pq(arr, arr + size);
    int index = 0;
    for (int i = k + 1; i < n; i++) {
        arr[index++] = pq.top();
        pq.pop();
        pq.push(arr[i]);
    }
    while (pq.empty() == false) {
        arr[index++] = pq.top();
        pq.pop();
    }
}
    
```

$T.C: O(k) + O(m) * \log(k)$
here, $m = n - k$
 $S.C: O(k)$

(1) Find k closest numbers in an array.

Given an array and two numbers x and k , find k closest values to x .

Input: $arr[] = \{10, 2, 14, 4, 7, 6\}$, $x = 5$, $k = 3$

Output: $4, 6, 7$ (closest value of 5 is $4, 6, 7$) here.

Process: ① Make a max heap of differences with first k elements.

② For every starting from $(k+1)$ th element do following.

- (i) Find difference of current element with x .
- (ii) If difference is more than root of heap, ignore current ele.
- (iii) Else, insert the current element after removing the top

③ Finally the heap have k closest elements.

Code:

```

void printKClosest(int arr[], int n, int x, int k) {
    priority_queue<pair<int, int>> pq;
    for (int i = 0; i < k; i++) {
        pq.push({abs(arr[i] - x), arr[i]});
    }
}
    
```

```

for (int i = k; i < n; i++) {
    int diff = abs(qarr[i] - x);
    if (diff > pq.top().first)
        continue;
    pq.pop();
    pq.push({diff, qarr[i]});
}

```

```

while (!pq.empty() == true) {
    cout << pq.top().second << " ";
    pq.pop();
}

```

TC: O(n log k)

(a) Top k Frequent Elements :-

Given an integer array `nums` and an integer `k`, return the `k` most frequent elements.

Ex:- `nums = [1, 1, 1, 2, 2, 3]; k=2` Ans:- `nums = [1, 2], k=2`
O/P = [1, 2] O/P = [1, 2]

process :-

- ① Use Hashing technique to count frequency of every number by using map. (O(n) time)
- ② Use priority queue (heap concept) for Frequency. keep the highest frequency '`k`' element in heap, (by using min heap we can pop all other element at each step of insertion)

Code :-

```

vector<int> topKFrequent (vector<int> & nums, int k) {
    unordered_map<int, int> m;

```

~~map<int, int>~~

```

    for (int i : nums) m[i]++;

```

```

    priority_queue<pair<int, int>, vector<pair<int, int>>, greater<pair<int, int>> p;

```

```

for (auto it : m) {
    p.push({it.second, it.first});
    if (p.size() > k) p.pop();
}

vector<int> ans;
while (k--) {
    ans.push_back (p.top().second);
    p.pop();
}

return ans;
}

```

$T.C.: O(n) + O(n \log k)$
 $S.C.: O(n) + O(n) + O(n)$

Note:- To find top/greater use min heap and to find smaller use max heap.

(13) Frequency Sort:-

point the elements of an array in the decreasing frequency
 If 2 numbers have same frequency then point the one which came first.

arr :- arr = {2, 5, 2, 8, 5, 6, 8, 8}

O/P :- 8, 8, 8, 2, 2, 5, 5, 6.

process :-

- ① Take the arr and use unordered-map to have VALUE: FREQUENCY Table
- ② Then make a HEAP such that high Frequency remains at top and when frequency is same, just keep in ascending order (smaller at top)
- ③ Then After full insertion into Heap, pop one by one and copy it into the array.

~~$T.C.: O(d \log d)$ Dominating factor $O(n + d \log d)$~~

here, $d \leq$ No. of Distinct element

~~$S.C.: O(d)$~~

$\underbrace{\text{map}}_{\text{insertion}} \underbrace{\text{heap / insertion}}_{\text{deletions}}$

Code:-

```

class Compare {
public:
    bool operator() (pair<int, int> a, pair<int, int> b) {
        if (a.first == b.first)
            return a.second > b.second;
        return a.first < b.first;
    }
}

```

S:

```

void FrequencySort (vector<int> &arr) {
    int N = arr.size();
    unordered_map<int, int> mp;
    for (int a: arr) mp[a]++;
}

priority_queue<pair<int, int>, vector<pair<int, int>>,
               Compare> pq;
for (auto m: mp)
    pq.push({m.second, m.first});
int i=0;
while (pq.size() > 0) {
    int val = pq.top().second;
    int freq = pq.top().first;
    pq.pop();
    while (freq--) {
        arr[i] = val;
        i++;
    }
}

```

S

(4) K Closest points to Origin :-

- Given an array of points where $points[i] = [x_i, y_i]$ represents a point on the XY plane and an integer k , return the k closest points to the origin.

The distance b/w two points on X-Y plane is Euclidean dist.

$$l^2 = (x_1 - x_2)^2 + (y_1 - y_2)^2 \text{ or, } l^2 = (x_1 - x_2)^2 + (y_1 - y_2)^2$$

Q:- points = [[3, 3], [5, -1], [-2, 4]], k=2

O/P: [[3, 3], [-2, 4]]

process:-

- calculate distance from origin for every point i.e $d^2 = x^2 + y^2$ and make a heap according to d^2 as priority.

code:-

```
vector<vector<int>> kClosest(vector<vector<int>> &points, int k)
```

priority-queue<vector<int>> maxHeap;

for (auto &p : points) {

int x=p[0], y=p[1]

maxHeap.push({x*x + y*y, x, y});

if (maxHeap.size() > k) { maxHeap.pop(); }

}

vector<vector<int>> ans (k);

for (int i=0; i < k; i++) {

vector<int> top = maxHeap.top();

maxHeap.pop();

ans[i] = {top[1], top[2]};

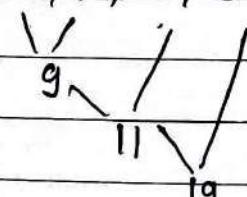
}

return ans;

15

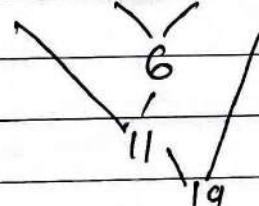
Connect 'n' ropes with minimal cost.

5, 4, 2, 8



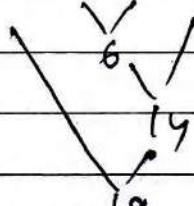
$$9+11+19 = \underline{\underline{39}}$$

5 4 2 8



$$6+11+19 = \underline{\underline{36}} \\ (\text{minm})$$

5 4 2 8



$$6+14+9 = \underline{\underline{39}}$$

Code:-

```
int findMinCost (vector<int> const & prices) {
```

priority-queue<int>, vector<int>, greater<int>> pq (prices.begin(),

prices.end());

```
while (pq.size() > 1) {  
    int x = pq.top();  
    pq.pop();  
    int y = pq.top();  
    pq.pop();  
    int sum = x + y;  
    pq.push(sum);  
    cost += sum;  
}  
return cost;
```