

## 14) Find eigenvector decomposition

14.1) Find eigenvalues: use 8

14.2) Find eigenvectors: use 13

14.3) Put eigenvalues into diagonal matrix:  $D = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix}$

14.4) Put eigenvectors (as columns and in the same order as eigenvalues in  $D$ ) in matrix  $T$   
 $T = \begin{pmatrix} \text{evec1} & \text{evec2} & \dots & \text{evecn} \\ \vdots & \vdots & & \vdots \end{pmatrix}$

14.5) Find  $T^{-1}$  use 2

14.6)  $A = TDT^{-1}$

## 15) Create orthonormal system from $\{v_1, \dots, v_n\}$

15.1) Use Gram-Schmidt orthogonalization process:

$$\begin{cases} 15.1.1) & n_1 = v_1 \\ 15.1.2) & n_2 = v_2 - \frac{\langle v_2, n_1 \rangle}{\langle n_1, n_1 \rangle} n_1 \\ \vdots & \vdots \\ 15.1.3) & n_k = v_k - \frac{\langle v_k, n_1 \rangle}{\langle n_1, n_1 \rangle} n_1 - \dots - \frac{\langle v_k, n_{k-1} \rangle}{\langle n_{k-1}, n_{k-1} \rangle} n_{k-1} \end{cases}$$

15.2) Normalize  $n_i$ :  $\frac{n_i}{\|n_i\|} \rightarrow \text{normalized}$

## MATHS 1 Calculation Algorithms

### 16) Calculate inner product:

$$\langle \vec{x}, \vec{y} \rangle = x^T y$$

### 17) Find projection $\vec{x}$ on $\vec{y}$

$$P_{\vec{y}}(x) = \frac{\langle x, y \rangle}{\langle y, y \rangle} \cdot y$$

### 18) Compute $\nabla f$ (Gradient)

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$$

### 19) Compute $Hf$ (Hessian)

$$Hf = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1} & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \vdots & & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & & \frac{\partial^2 f}{\partial x_n \partial x_n} \end{pmatrix}$$

## 20) ODE

20.1) Separable case:

20.1.1)  $y'(t) = \frac{dy}{dt}$

20.1.2) Separate  $y$  and  $t$

20.1.3) Integrate both parts

20.1.4) Find constant from

## 21) Find max/min of a function with equality constraint

21.1) Create  $L(x, \lambda) = f(x) + \lambda n_i$ , where  $n_i \rightarrow$  constraint type equality

21.2) Solve  $\nabla L(x, \lambda) = 0$  use 18

this gives you stationary points

21.3) Find  $Hf$  use 19 in  $\vec{V}_{\text{stat. point}}$

21.4) Define definiteness of  $Hf$  in  $\vec{V}_{\text{stat. point}}$ ; use 22

21.5) Conclude if it max or min or nothing

22)  $A$  is positive definite <sup>intuitively</sup>  $\checkmark$  if and only if all eigenvalues  $\lambda_i > 0$

or  $\Leftrightarrow m_i > 0$ , where  $m_i$  - principal minors [min & convex]

$A$  is positive-semi-definite  $\Leftrightarrow$

$\lambda_i \geq 0$  [min & convex]

$A$  is negative definite  $\Leftrightarrow \lambda_i < 0$

$A$  is negative semi-definite  $\Leftrightarrow \lambda_i \leq 0$   
 [max & concave]

20.2) Other cases; use link