Chapter 1 Neural Network: Learning

1.1 Cost Function and Backpropagation

1.1.1 Cost Function

Let's define symbols for n-class classification:

- the input feature and its class: $(x^{(1)}), y^{(1)}, (x^{(2)}), y^{(2)}, \cdots, (x^{(n)}), y^{(n)}$
- \bullet L is total number of layers
- s_l is the number of units in layer l

For logistic regression, the cost function is

$$J(\theta) = \frac{1}{2m} \left[\sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{i=1}^{n} \theta_i^2 \right]$$

For a neural network, it's:

$$J(\Theta) = -\frac{1}{m} \left[\sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} \log \left(h_{\Theta} \left(x^{(i)} \right) \right)_k + \left(1 - y_k^{(i)} \right) \log \left(1 - \left(h_{\Theta} \left(x^{(i)} \right) \right)_k \right) \right] + \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} \left(\Theta_{ji}^{(l)} \right)^2$$

where: $h_{\Theta}(x) \in \mathbb{R}^K$, $(h_{\Theta}(x))_i = i^{th}$ output

The first term is for all K dimension output, and the last is the regular term of all weight in the neural network.

1.1.2 Backpropagation Algorithm

Backpropagation algorithm is a way to minimize the cost.

To use gradient descent, we need $J(\theta)$ and $\frac{\partial J(\theta)}{\partial \Theta_{i,j}^{(l)}}$.

So we have to compute the partical terms. We define the error of the L layer's node j:

$$\delta_i^{(l)} = a_i^{(l)} - y_i$$

Then, for earlier layers:

$$\delta^{(l-1)} = (\Theta^{(l-1)})^T \delta^{(l)} \cdot * q'(z^{(l-1)})$$

Where:

$$g'(z^{(l)}) = a^{(l)} \cdot * (1 - a^{(l)})$$

Finally:

$$\frac{\partial}{\partial \Theta_{i,j}^{(l)}} J(\Theta) = a_j^{(l)} \delta_i^{(l+1)}, \text{ when } \lambda = 0$$

For a training set $(x^{(1)}), y^{(1)}, (x^{(2)}), y^{(2)}, \cdots, (x^{(m)}), y^{(m)}$:

```
Delta(l)(i,j) = 0

for i = 1 : m

set a(1) = x(i)

compute for a(l) for l = 2,3,..,L

with y(i), compute delta(L)

then compute delta(L-1), ...,delta(1)

Delta(l)(i,j) = Delta(l)(i,j) + a(l)(j) * delta(l+1)(i)

endfor
```

Or in vector form:

$$\Delta^{(l)} := \Delta^{(l)} + \delta^{(l+1)} (a^{(l)})^T$$

Then:

$$D_{i,j}^{(l)} = \frac{1}{m} \Delta_{i,j}^{(l)} + \lambda \Theta_{i,j}^{(i)}, \text{ if } j \neq 0$$
$$D_{i,j}^{(l)} = \frac{1}{m} \Delta_{i,j}^{(l)} + \lambda \Theta_{i,j}^{(i)}, \text{ if } j = 0$$

And:

$$\frac{\partial}{\partial \Theta_{i,j}^{(l)}} J(\Theta) 1 = D_{i,j}^{(l)}$$

1.1.3 Backpropagation Intuition

Backpropagation is more likely to be a blankbox than previous algorithm.

What do forward propagation do in the NNs? Doing non-linear matrix multiplication by introducing bias. And similarly, the former error is due to latter layers.

1.2 Backpropagation in Practice

1.2.1 Advanced Optimization

Learn to unroll parameters matrices into vectors.

```
thetaVec = [Theta1(:); Theta2(:)];
```

The unrolled weights could be passed into fminunc (@cost, initTheta, option), where the cost takes the unrolled vectors.

1.2.2 Gradient Checking

There could be some subtile bugs, so we need to check gradient.

We need to numerially compute the gradient at a point, and it just needs

$$\frac{\mathrm{d}}{\mathrm{d}\theta}J(\theta) \approx \frac{J(\theta+\epsilon) - J(\theta-\epsilon)}{2\epsilon}$$

1.3 Application of Neural Network

Word

subtile