

# Chapter 1 Neural Network: Learning

## 1.1 Cost Function and Backpropagation

### 1.1.1 Cost Function

Let's define symbols for n-class classification:

- the input feature and its class:  $(x^{(1)}, y^{(1)}, (x^{(2)}, y^{(2)}, \dots, (x^{(n)}, y^{(n)})$
- $L$  is total number of layers
- $s_l$  is the number of units in layer  $l$

For logistic regression, the cost function is

$$J(\theta) = \frac{1}{2m} \left[ \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{i=1}^n \theta_i^2 \right]$$

For a neural network, it's:

$$J(\Theta) = -\frac{1}{m} \left[ \sum_{i=1}^m \sum_{k=1}^K y_k^{(i)} \log \left( h_{\Theta} \left( x^{(i)} \right) \right)_k + \left( 1 - y_k^{(i)} \right) \log \left( 1 - \left( h_{\Theta} \left( x^{(i)} \right) \right)_k \right) \right] \\ + \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} \left( \Theta_{ji}^{(l)} \right)^2$$

where:  $h_{\Theta}(x) \in \mathbb{R}^K$ ,  $(h_{\Theta}(x))_i = i^{th}$  output

The first term is for all  $K$  dimension output, and the last is the regular term of all weight in the neural network.

### 1.1.2 Backpropagation Algorithm

Backpropagation algorithm is a way to minimize the cost.

To use gradient descent, we need  $J(\theta)$  and  $\frac{\partial J(\theta)}{\partial \Theta_{i,j}^{(l)}}$ .

So we have to compute the partial terms. We define the error of the  $L$  layer's node  $j$ :

$$\delta_j^{(l)} = a_j^{(l)} - y_j$$

Then, for earlier layers:

$$\delta^{(l-1)} = (\Theta^{(l-1)})^T \delta^{(l)} \cdot * g'(z^{(l-1)})$$

Where:

$$g'(z^{(l)}) = a^{(l)} \cdot * (1 - a^{(l)})$$

Finally:

$$\frac{\partial}{\partial \Theta_{i,j}^{(l)}} J(\Theta) = a_j^{(l)} \delta_i^{(l+1)}, \text{ when } \lambda = 0$$

For a training set  $(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})$ :

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1 Delta(l)(i,j) = 0
2 for i = 1 : m
3     set a(1) = x(i)
4     compute for a(l) for l = 2,3,...,L
5     with y(i), compute delta(L)
6     then compute delta(L-1), ..., delta(1)
7     Delta(l)(i,j) = Delta(l)(i,j) + a(l)(j) * delta(l+1)(i)
8 endfor

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Or in vector form:

$$\Delta^{(l)} := \Delta^{(l)} + \delta^{(l+1)}(a^{(l)})^T$$

Then:

$$D_{i,j}^{(l)} = \frac{1}{m} \Delta_{i,j}^{(l)} + \lambda \Theta_{i,j}^{(i)}, \text{ if } j \neq 0$$

$$D_{i,j}^{(l)} = \frac{1}{m} \Delta_{i,j}^{(l)} + \lambda \Theta_{i,j}^{(i)}, \text{ if } j = 0$$

And:

$$\frac{\partial}{\partial \Theta_{i,j}^{(l)}} J(\Theta) = D_{i,j}^{(l)}$$