

Salient Object Detection in 360 videos

#	Title	Year	Venue	Description
1	Salient Object Detection: A Survey [8]	2014	Computational Visual Media	A review of SOD methods before 2014.
2	A Review of Eye Gaze in Virtual Agents, Social Robotics and HCI: Behaviour Generation, User Interaction and Perception [47]	2015	Comput.Graph.Forum	A report introduces exhaustive concepts of human eye; a review of eye-gaze-related researches edifies future CV development.
3	Saliency Prediction in the Deep Learning Era: Successes and Limitations [7]	2019	TPAMI	A review of deep learning-based models and datasets/metrics for 2D saliency prediction.
4	Salient Object Detection in the Deep Learning Era: An In-Depth Survey [55]	2020	arXiv	A review of SOD methods before 2020.
5	VR content creation and exploration with deep learning: a survey [53]	2020	Computational Visual Media	A review of deep learning-based methods for VR images/videos processing.
6	On the Synergies between Machine Learning and Stereo: a survey [42]	2020	arXiv CVPR2019(tutorial)	A review of deep learning-based models for monocular depth estimation in panoramas.
7	Deep Audio-Visual Learning: A Survey [75]	2020	arXiv	A review of audio-visual learning methods before 2019.

Table 1: Summary of previous reviews.

No.	Model	Year	Pub.	Task	SL	Base	Label	Loss	Metric	Training Set	# training	code
1	360-spatialization [38]	2018	NIPS	SS	Sel.	STFT/UNet	Non	STFT-distance	STFT/ENV/EMD	REC-STREET YT-ALL	123k 0.1s samples 3976k samples	py-o
2	AVE/AVOL-Net [4]	2018	ECCV	cmR/L	Sel.	CNN/FC	Non	AVC [3]	nDCG/heatmap [39]	AudioSet [23]	263K 10s clips	py-n/o
3	DMRFE/AVDLN [51]	2018	ECCV	EL/cmL	S/W	CNN/LSTM	Tem.	MCE/ L_c	heatmap/accuracy	AVE [51]	4K(T.) $\geq 2s$ clips	py-o
4	PixelPlayer [72]	2018	ECCV	SS/L	Sel.	ResNet/STFT	Non	SCE/L1	NSDR/SIR/SAR	MUSIC [72]	500 videos	py-o
5	SoundLoc [48]	2018	CVPR	L	W	CNN/FC	bbox	SSL [48]	cIoU [48]	Flickr-SoundNet [5]	144K frames	Non
6	A/V-CoSeg [46]	2019	ICASSP	Seg/SS	Sel.	UNet/ResNet	pol.	BCE	IoU/SDR/SIR	AVE [51]	3,339 $\geq 2s$ clips	Non
7	VehicleTrack [18]	2019	ICCV	Track	Sel.	YOLOv2	bbox	Rank [6]/OD [45]	AP	AudioVideoTrack [18]	227K 1s clips	Non
8	DDT [71]	2019	ICCV	L/SS	Sel.	I3D [9]	Non	BCE(on spec.)	SDR/SIR/SAR/HE	MUSIC-21 [71, 72]	1,065 videos	Non
9	CO-SEPARATION [21]	2019	ICCV	SS	Sel.	UNet/STFT	Non	CE [21]/L1	SDR/SIR/SAR	[23, 72]/AVBench [19]	122K 10s clips	py
10	MONO2BINAURAL [20]	2019	CVPR	m2b/SS	Sel.	UNet/STFT	Non	L2/L1	STFT/ENV-Dis. SDR/SIR/SAR	FAIR-Play [20]	1,497 10s clip	py-o
11	VSLNet [68]	2020	ACL	NLVL	S	CNN	mom.	CE	IoU	[68]	60K moments	py-o
12	IMGAUD2VID [22]	2020	CVPR	AR	U	LSTM/R21D distillation	cls	L1/KL	mAP	Kinetics [25]	300K 10s clips	py-o
13	Music-Gesture [17]	2020	CVPR	SS	U	CNN/GCN	KP	SCE	SDR/SIR	MUSIC	mix-2/3 samples	-

Table 2: **Summary of recently proposed models for audio-visual learning.** cmR = cross-modal retrieval. L = (sound source) localization. EL = event localization. cmL = cross-modal localization. SL = supervision level. S = supervised. W = weakly supervised. U = un-supervised. Sel. = self supervised. T = traditional method. CNN = convolutional neural network. FC = fully connected layer. py = python. n/o = non official. Tem. = temporally labeled segments (visual/audio). MCE = multi-class cross-entropy loss. L_c = contrastive loss function. SS = sound separation. STFT = Short- Time Fourier Transform. NSDR = Normalized Signal-to-Distortion Ratio. SIR = Signal-to-Interference Ratio. SAR = Signal-to-Artifact Ratio. SCE = sigmoid cross entropy. SSL = semi-supervised loss. frm = frames. BCE = binary cross entropy. pol. = polygon. OD = object detection. HE = human evaluation. CE = cross entropy. m2b = mono to binaural. AR = action recognition. cls = class. NLVL = natural language video localization. mom. = moments annotations. KP = key points.

No.	Dim.	Model	Year	Pub.	Task	Base	Training Set	Label	# training	F_β	F_β^ω	M	S_α	E_ξ	code
1	360-RGB	DDS [32]	2020	JSTSP	SOD	CNNs	360SOD [32]	o-pw	400 images	.650	.652	.023	-	-	py-o
2	2D-RGBD	UCNet [69]	2020	CVPR	SOD	CVAE [49]	AugedGT [69]	o-pw	-	.855~.919	-	.019~.066	.864~.934	.901~.967	-
3	2D-RGBD	JLDCF [15]	2020	CVPR	SOD	VGG16 ResNet101	NLPR NJU2K	o-pw	2,2K images	.862~.919	-	.022~.078	.854~.929	.893~.968	-
4	2D-RGBD	SSF [70]	2020	CVPR	SOD	CIM CAU/BSU	DUT-RGBD NLPR	o-pw	1,485 images 700 images	.867~.915	-	.025~.044	.859~.915	-	-
5	2D-RGB	F^3 Net [58]	2020	AAAI	SOD	CFD/CFM MLS	DUTS-TR	o-pw	10,533 images	.766~.925	-	.028~.062	.838~.924	.859~.953	-
6	2D-RGB	DFI [34]	2020	arXiv	SOD ed./sk.	CNNs PPM [73]	DUTS-TR [52]	o-pw	10,533 images	.829~.945	-	.031~.100	.802~.921	-	-
7	2D-RGB	SISO [27]	2019	WACV	SOD	3D FCN [26]	SESIV [27]	i-pw	58 videos (3,944 frames)	-	-	-	-	-	m.-o
8	2D-RGB	SVSNet [57]	2019	ACM MM	r-SOD	FCN	RVSOD [57]	o-pw	242 videos (7140 frames) DAVIS [41]/DUT [66]	.816 .745(DAVIS)	-	.089 .047(DAVIS)	-	-	py-o
9	2D-RGB	RSDNet [2]	2018	CVPR	r-SOD	ResNet101	Pascal-S [33]	o-pw	425 images	.880	-	.090	-	-	ca-o

Table 3: **Summary of recently proposed models for salient object detection.** SOD = salient object detection. F_β = F-measure [1]. F_β^ω = weighted F-measure [35]. M = mean absolute error [40]. S_α = S-measure [13]. E_ξ = E-measure [14]. (n)/o = (non) official. o(i)-pw = object(instance)-level pixel-wise annotations. m. = matlab. ca = caffe. py = python. ed. = edge detection. sk. = skeleton detection. r-SOD = ranking SOD.

No.	Dim.	Model	Year	Pub.	Base	Training Set	# Training	Label	Code	Key Issue
1	360	MT-DNN [43]	2020	TMM	CNNs/convLSTM	[65]	65 videos (3,501 viewports)	SalMap	py-o	viewports influence fixations
2	2D	UVA-Net [16]	2020	AAAI	knowledge distillation	AVS1K...	1K aerial videos	SalMap	-	accelerating SP
3	360	DHP [65]	2019	TPAMI	DRL [37]	PVS-HM [65]	61 videos	HM map	py-o	-
4	2D	DAVE [50]	2019	arXiv	3D ResNet log mel-spectrogram	AVE [50]	150 videos	SalMap	py-o	visual-audio SP
5	2D	SKD-DVA [31]	2019	TIP	knowledge distillation	-	-	SalMap	-	accelerating SP
6	2D	TASED-Net [36]	2019	ICCV	3D FCN (S3D [64])	DHF1K [56]	700 videos	Fixations	-	3D-FCN for video SP
7	360	E/H-SalPredict [76]	2019	TMM	EMP, HMP	Salient360! [44]	85 images	SalMap	-	-

Table 4: **Summary of recently proposed models for saliency prediction.** SP = saliency prediction. HM = head movement.

No.	Task	Method	Year	Pub.	Components	Training Set	#Training	Label
1	Classification	tangent-360 [12]	2020	CVPR	-	-	-	-
2	Semantic Segmentation	(waiting for paper...) [28]	2020	CVPR	-	-	-	-
3	D-epth Estimation	OmniMVS [59]	2020	TPAMI	uncertainty prior	Weather/House/Thing	700/2048/9216 images	-
4	Depth Estimation	360SD-Net [54]	2020	ICRA	ASPP [10]	MP3D/SF3D	1602/800 images	-
5	Classification	SGCN [67]	2020	CVPR	GConv, HPool	ModelNet40 [62]	9843 samples	cls
6	VP	MDN [60]	2020	AAAI	s2cnn [60]	PanoUCF101 [60]	35 users records	cls
7	OD Evaluation	Rep R-CNN [74]	2020	AAAI	SphBB, SphIoU	ImageNet	-	bbox
8	VQA	V-CNN [30]	2019	CVPR	VP/VQ-Net	VQA-ODV [29]	432 impired videos	HM info.
9	OD/IS/SS	Pano-BlitzNet [24]	2019	arXiv	BlitzNet [11]	SUN360 [63]	400 images	i-pw
10	VQA	FAST-VQA [61]	2019	TMM	spatial quality degradation	-	-	tra.

Table 5: **Summary of recent methods for 360 processing.** OD = object detection. IS = instance segmentation. SS= semantic segmentation. o(i)-pw = object(instance)-level pixel-wise annotations. cls = class. VP = viewport prediction. VQA = video quality assessment. tra. = salient trajectories.

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