# **Creating New Vehicles**

I've written some editor scripts to simplify creating new vehicles. Creating and configurating the vehicle with 100% progress would take only five minutes if your vehicle model has corrected axes and pivot positions.

# **Warning**

Script and behavior depend on vehicle's X, Y, Z axis orientation and pivots. So, your vehicle model and wheel models transform directions **should MUST** be correct. Unity has updated EULA about it in 2018, and any models with improper axes and directions will be rejected from the Asset Store.

# **Important**

Be sure you are in PIVOT and LOCAL mode while checking axes of your model.



X should be Right,

Y should be Up,

Z should be Forward.



Some designers are making models with wrong directions or wrong pivot positions or both. This is painful if you don't know how to fix the directions of the models. But there is an editor script to fix this. While adding main controller to the vehicle, it will ask you to fix pivot position of the vehicle if it's wrong. Choose "Yes" if your vehicle has wrong pivot position. However, scripts can't know vehicle model direction. X, Y, Z directions must be correct at least by your side.

Also, the scale of your vehicle must not be oversized or miniature. Even if you are developing a toy car game, vehicle size should be nearly same as demo vehicles. Physics engine calculates the shape and size of the collider too. So, you have checked inputs, your vehicle and wheel models pivot positions, and their X, Y, Z directions. Everything is OK, right? Then...

### Drag and drop your vehicle model to your scene and let's get started!

There are three ways to add the controller to the vehicle.

- Quick Vehicle Setup Wizard from Tools → BCG → RCC
- Add Main Controllers from Tools → BCG → RCC
- Add RCC\_CarControllerV4 directly to the root of the vehicle

### **Quick Vehicle Setup Wizard**

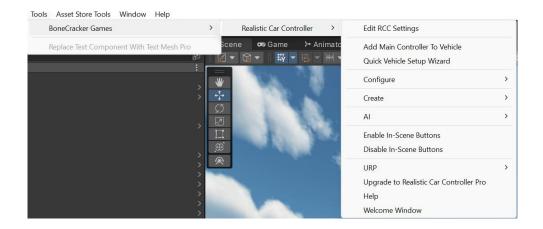
This is the fastest way to create new vehicles. Just select the root of the vehicle and open the wizard from  $Tools \rightarrow BCG \rightarrow RCC \rightarrow Quick Vehicle Setup Wizard$ . Follow the instructions and create your vehicle within a few seconds!

#### Add Main Controller

This is the regular way to create new vehicles. Just select the root of the vehicle and add the main controller from  $Tools \rightarrow BCG \rightarrow RCC \rightarrow Add$  Main Controller. Follow the editor instructions and create your vehicle within a few seconds. After adding the main controller to the vehicle, you'll need to select the wheels and create their wheelcolliders. Editor will guide you to complete setup.

### Add RCC\_CarControllerV4 Directly

This is the old and not recommended way to create new vehicles. Just select the root of the vehicle and add RCC\_CarControllerV4 script. Follow the editor instructions and create your vehicle within a few minutes. Adding the script directly to the vehicle will bypass the editor assistances.



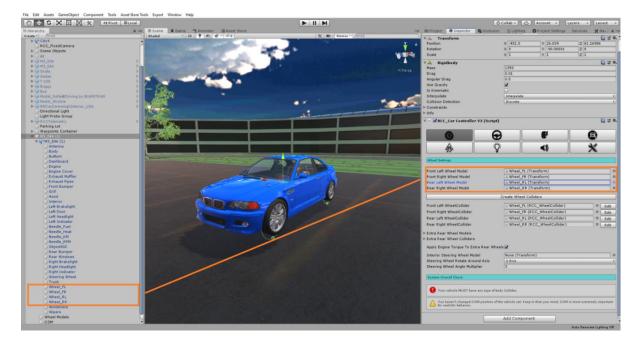
It will ask you to fix pivot position of the vehicle if it's wrong. Choose "Yes" if your vehicle has wrong pivot position. RCC\_Bounds will calculate the total bounds and find the center position of the model.



As soon as you add RCC\_CarControllerV4 script to your car, rigidbody component will be added automatically. Set your mass to around 1250-1500 for this type of vehicle. Interpolate Mode = Interpolate, Angular drag is around 0.25 – 0.50 for medium angular velocity. These rigidbody settings are applied when you create your vehicle automatically.

The first thing we want to do is create the wheel colliders (<u>Do this step only if your vehicle doesn't have the wheelcolliders</u>). Click "Wheel" tab in the editor script. Select all your

wheels. After selecting your wheel models, click the "Create Wheel Colliders" for creating wheel colliders with proper radius, suspension, damper, and friction curves automatically. Check the radius and position of the wheel colliders after creating them.



Generated wheel colliders settings are fine for **1250 - 1500** mass vehicles. If you have heavy vehicles such as bus or truck, you must increase wheel colliders mass, spring, damp forces.

Your vehicle <u>MUST</u> have any kind of <u>Colliders</u> (Such as <u>Box Collider</u>, or <u>Mesh Collider</u> etc...) for the body. Otherwise, physics won't work.

Editor script of the RCC\_CarControllerV4 will find any issues and inform you if persists. In some cases, some models have sphere colliders attached to the wheels, some models have trigger enabled mesh colliders, some models have rigidbodies on some child gameobjects, etc... I was having many emails about "my car is bouncing, falling through the ground, won't move, etc.". An informer of the RCC will assist you in this case.

At this point, your vehicle model is ready to go. Wheel colliders, colliders, and rigidbody are the essential components. All other components are optional and not required.

# Creating Lights, Exhausts, Cameras, Sounds, Skidmarks, Smoke Effects, And Other Features

These effects are optional. And can be created with In - Scene GUI buttons with the fastest way. To enable buttons, simply go to Tools -> BCG -> RCC -> Enable In - Scene GUI Buttons. It will enable UI panel at the left side of your editor scene window. To use them, select your vehicle in your scene and you will be able to create lights, exhausts, cameras, mirrors, UI canvas, and vehicle camera with one click.

However, you may not use the panel. In this case, you can create them with the tabs explained below.

You can create point lights for braking and reverse gear, spotlights for headlights from the Tools → BoneCracker Games → Realistic Car Controller → Create → Lights. Or with In - Scene GUI Button. Place them correctly on your vehicle model.

You can create hood and wheel cameras from the Tools → BoneCracker Games → Realistic Car Controller → Create → Cameras → Hood Camera / Wheel Camera. Or with In - Scene GUI Buttons. Place them correctly on your vehicle model.

You can create exhaust effects from the Tools → BoneCracker Games → Realistic Car Controller → Create → Misc. Or with In - Scene GUI Buttons. Place them correctly on your model.

Scripts don't instantiate and destroy any smoke particles, or any kind of stuff. Just enabling/disabling particle emitters to avoid garbage memory.

## **Wheel Smoke Particle Effects**

You will find "RCC\_WheelSlipAsphalt", "RCC\_WheelSlipGrass" and "RCC\_WheelSlipSand" prefabs under the "Prefabs" folder. You can use your own smoke prefabs as you wish. These wheel particles have been selected in the Tools → BCG → RCC → Configure Ground Materials. Corresponding particles will be used on each ground material. If slippage of the wheel passes the target slip value in the ground materials panel, emissions will be enabled.

# **Engine Sound Effects**

Engine sounds can be selected or changed at the sound tab of the RCC\_CarControllerV4. RCC has three engine sound types. Modern games use six audio clips per engine at least. Low, middle, and high RPM while pushing throttle, and same without pushing the throttle. If you have these audioclips, you can select all of them for realistic engine sound effects. But if you have only one audio clip, you can still use it by selecting one source type.

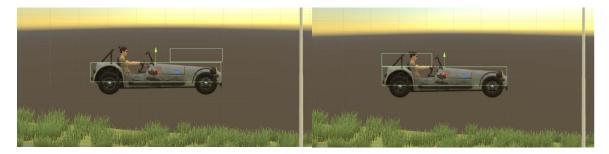
### **Skidmarks**

Skidmarks are managed by the RCC\_SkidmarksManager.cs. Draws meshes on the collider if slippage of the wheel collider is high enough with proper intensity. Different skidmarks can be drawn on each surface. To select, or edit them, go to Tools > BCG > RCC > Configure Ground Materials. You will see each material has unique skidmarks. Double click to edit them, or just duplicate one of them in the project folder and customize.

Each wheel can have a different skidmark width. Simply select your wheelcolliders and set their skidmark width. And also, you can disable skidmark of any wheel too.

## **Collider Shapes of The Vehicle**

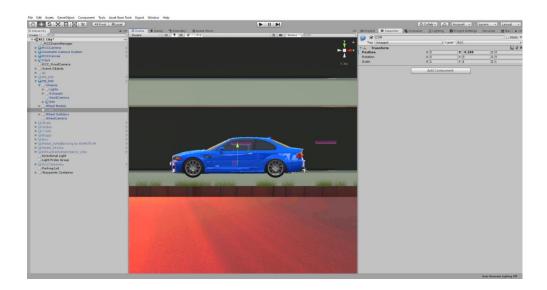
This is one of the most important things for physics behavior. Most developers are using mesh colliders for their vehicles. Remember that the shape of your vehicle collider will affect physics behavior directly. Let me explain how.



This vehicle has two box colliders. Second box collider is placed at front of the vehicle here on the first screenshot. This will bring you more controllable and stable vehicles. At the second image, the second box collider is placed at rear of the vehicle. This will bring you more unstable and slippy vehicle. Differences between first colliders and second colliders are noticeable. Just remember that collider shapes are affecting vehicle behavior directly. If

you want to make your cars stable, keep that in mind. And be sure to use proper mesh colliders, and box colliders on your vehicles.

After ending up with wheel models and wheel colliders configurations, place your COM to the correct place. This is our Center of Mass. And COM's position is affecting whole behavior. Usually, the COM of the vehicle is at just below about gearbox. Engine and transmission are at front of the vehicle, and they are heavy. This model is RWD. It has shaft at middle and differential at back of the vehicle. So, I'll just set it to just like this;



Running perfectly after just few clicks.



Configurate your vehicle as you wish. If you want to use manual gear, you need to set it from RCC Settings. Also, you can select which key to shift up and shift down here.

## **Driving Assistances**

Main Controller has ABS, TCS, ESP, Steering Assistance, and Traction Assistance. Threshold means, if wheel slippage is equal or higher than this threshold value, corresponding assistance will be engaged immediately.

**ABS** = The **anti-lock braking system** (ABS). Its purpose is to keep the vehicle safe by preventing the wheels from locking when you use the brakes. You can keep control over the steering and your vehicle won't skid as a result of the wheels locking up.

**ESP** = The **electronic stability program** supports the vehicle in nearly all critical driving situations. It comprises the functions of the antilock braking system (ABS) and the traction control system but can do considerably more. It detects vehicle skidding movements, and actively counteracts them by applying individual brake forces to each wheel.

**TCS** = The **traction control system** detects if a loss of traction occurs among the car's wheels. Upon identifying a wheel that is losing its grip on the road, the system automatically applies the brakes to that individual one or cut down the car's engine power to the slipping wheel.

**Steering Helper** = The **Steering helper** will apply local Y axis torque to vehicles for more easily turns. But it results in more unrealistic turns like arcade games. 0.1f would be good for all vehicles. (0.2f can be used if behavior type is Racing, Arcade, or Semi-Arcade.)

**Traction Helper** = The **Traction helper** will reduce stiffness of the front right or front left wheels if vehicle is skidding sideways. It will take the steering angle as reference while doing this and keep the vehicle in control.

# **Damage**

Your vehicle body mesh wireframe topology must be reliable for realistic mesh deformation. If your vehicle body mesh has broken (unwelded) vertices or bad wireframe topology, mesh will deform buggy and unrealistically. RCC takes all the meshes of the vehicle if you haven't select them specifically. If you want to select specific meshes, RCC won't take them all. Damage radius, multiplier, maximum damage and more stuff can be customized at damage tab of the RCC CarControllerV3.



**Deformation mode** = Fast for instant mesh deformation, and accurate for smooth time-based mesh deformation. Accurate mode is heavier.

**Damage Filter** = Vehicle will take damage from the colliders with these layers. You can choose specific layers from here.