



MASTER 2 MICAS

Machine Learning Communications and Security

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Convex Optimization

Part I: Convex Analysis

Consider a strongly convex function, f(x), (with constant $\mu > 0$), defined over a convex set X Recall that it fulfills the following:

$$f(x_2) \ge f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{\mu}{2} \|x_2 - x_1\|_2^2, \forall (x_1, x_2) \in X$$
 (1)

Prove all the following statements

- (1) is equivalent to a minimum positive curvature $\nabla^2 f(x) \succeq \mu I_d, \forall x \in X$

Answer : We assume that f is twice continuously differentiable. According the Taylor-Lagrange's formula, we have :

$$\forall x, h \in X, \exists \epsilon \text{ a function define in } X, \lim_{h \to 0} \epsilon(h) = 0$$

$$f(a+h) = f(a) + \nabla f(a)^{T} h + \frac{1}{2} h^{T} \nabla^{2} f(a) h + ||h||_{2}^{2} \epsilon(h)$$

Let a, $h \in X$, using Taylor-Langrange's formula we have :

$$(1) \iff f(a) + \nabla f(a)^T h + \frac{1}{2} h^T \nabla^2 f(a) h + \|h\|_2^2 \epsilon(h) \geqslant f(a) + \nabla f(a)^T h + \frac{\mu}{2} \|h\|_2^2$$

$$\iff \frac{1}{2} h^T \nabla^2 f(a) h + \|h\|_2^2 \epsilon(h) \geqslant \frac{\mu}{2} \|h\|_2^2$$

$$\iff h^T \left[\nabla^2 f(a) + 2\epsilon(h) I_d - \mu I_d\right] h \geqslant 0$$

Since $\epsilon(h)$ converges to 0 when h approaches 0, the previous expression is equivalent to :

$$\iff h^T \left[\nabla^2 f(a) - \mu I_d \right] h \geqslant 0$$

This expression is true for all h and a in X, so we can say that :

$$(1) \Longleftrightarrow \forall a \in X, \nabla^2 f() \succeq \mu I_d$$

- (1) is equivalent to
$$(\nabla f(x_2) - \nabla f(x_1))^T (x_2 - x_1) \ge \mu \|x_2 - x_1\|_2^2$$

Answer: Let $x_1, x_2 \in X$, we have :

$$(1) \iff \begin{cases} f(x_1) \geqslant f(x_2) + \nabla f(x_2)^T (x_1 - x_2) + \frac{\mu}{2} \|x_1 - x_2\|_2^2 \\ f(x_2) \geqslant f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{\mu}{2} \|x_2 - x_1\|_2^2 \end{cases}$$

$$\iff f(x_2) + f(x_1) \geqslant f(x_1) + f(x_2) + \nabla f(x_1)^T (x_2 - x_1) + \nabla f(x_2)^T (x_1 - x_2) + \mu \|x_2 - x_1\|_2^2$$

$$\iff \nabla f(x_2)^T (x_2 - x_1) - \nabla f(x_1)^T (x_2 - x_1) \geqslant \mu \|x_2 - x_1\|_2^2$$

$$\iff (\nabla f(x_2) - \nabla f(x_1))^T (x_2 - x_1) \geqslant \mu \|x_2 - x_1\|_2^2$$

So we can say that:

$$(1) \iff (\nabla f(x_2) - \nabla f(x_1))^T (x_2 - x_1) \geqslant \mu \|x_2 - x_1\|_2^2$$

- (1) implies to
$$f(x) - f^* \leqslant \frac{1}{2\mu} \|\nabla f(x)\|_2^2, \forall x \in X$$

Answer: Let $x, y \in X$ we have :

$$\begin{split} &0 \leqslant \frac{\mu}{2} \left\| y - x + \frac{\nabla f(x)}{\mu} \right\|_{2}^{2} = \frac{\mu}{2} \left(y - x + \frac{\nabla f(x)}{\mu} \right)^{T} \left(y - x + \frac{\nabla f(x)}{\mu} \right) \\ &= \frac{\mu}{2} \left\| y - x \right\|_{2}^{2} + \frac{1}{2} \left(y - x \right)^{T} \nabla f(x) + \frac{1}{2} \nabla f(x)^{T} \left(y - x \right) + \frac{\left\| \nabla f(x) \right\|_{2}^{2}}{2\mu} \\ &= \frac{\mu}{2} \left\| y - x \right\|_{2}^{2} + \nabla f(x)^{T} \left(y - x \right) + \frac{\left\| \nabla f(x) \right\|_{2}^{2}}{2\mu} \end{split}$$

Thus, using relation (1), we have:

$$(1) \Longrightarrow 0 \leqslant \frac{\mu}{2} \|y - x\|_{2}^{2} + \nabla f(x)^{T} (y - x) + \frac{\|\nabla f(x)\|_{2}^{2}}{2\mu} \leqslant f(y) - f(x) + \frac{\|\nabla f(x)\|_{2}^{2}}{2\mu}$$

$$\Longrightarrow f(x) - f(y) \leqslant \frac{\|\nabla f(x)\|_{2}^{2}}{2\mu}$$

$$\Longrightarrow f(x) - \inf_{y \in X} f(y) \leqslant \frac{\|\nabla f(x)\|_{2}^{2}}{2\mu}$$

So we have:

$$(1) \Longrightarrow f(x) - f^* \leqslant \frac{\|\nabla f(x)\|_2^2}{2\mu}$$

- (1) implies to f(x)+r(x) is strongly convex for any convex f and strongly convex r

Answer: Let f be a convex function and r a strongly convexe. We assume f and r is continously differentiable, then for $x, y \in X$ we have :

$$\begin{cases} f(y) \geqslant f(x) + \nabla f(x)^T (y - x) \\ r(y) \geqslant r(x) + \nabla r(x)^T (y - x) + \frac{\mu}{2} \|y - x\|_2^2 \end{cases}$$

$$\implies (f+r)(y) \ge (f+r)(x) + (\nabla f + \nabla r)(x)^T (y-x) + \frac{\mu}{2} \|y - x\|_2^2$$

So, we can say that f + r is strongly convex

A function $f: \mathbb{R}^d \to \mathbb{R}$ is L-smooth if it is differentiable and its gradient is L-Lipschitz-continuous (usually w.r.t. norm-2):

$$\forall x_1, x_2 \in \mathbb{R}^d, \|\nabla f(x_2) - \nabla f(x_1)\|_2 \leqslant L \|x_2 - x_1\|_2,$$
 (2)

Prove that (2) implies all the following statements (assume convexity if needed):

(a)
$$f(x_2) \leq f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{L}{2} ||x_2 - x_1||_2^2, \forall x_1, x_2 \in X$$

Answer: Let x_1 and $x_2 \in X$, we have:

$$f(x_2) = f(x_1) + \int_0^1 \langle \nabla f(x_1 + t(x_2 - x_1)), x_2 - x_1 \rangle dt$$

$$\implies f(x_2) = f(x_1) + \int_0^1 \langle \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1) + \nabla f(x_1), x_2 - x_1 \rangle$$

$$\implies f(x_2) = f(x_1) + \int_0^1 < \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 > dt + \int_0^1 < \nabla f(x_1), x_2 - x_1 > dt$$

$$\implies f(x_2) = f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \int_0^1 < \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 > dt$$

Using Cauchy-Sawartz inequality, we have for all $t \in [0,1]$,

$$|\langle \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 \rangle| \le ||\nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1)||_2 ||x_2 - x_1||_2$$

Using inequality (2), we have:

$$\|\nabla f\left(x_{1}+t\left(x_{2}-x_{1}\right)\right)-\nabla f(x_{1})\|_{2}\leqslant L\|x_{1}+t\left(x_{1}+x_{2}\right)-x_{1}\|_{2}=tL\|x_{2}-x_{1}\|_{2}$$

$$\implies | < \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 > | \leqslant tL ||x_2 - x_1||_2^2$$

$$\implies \int_{0}^{1} <\nabla f\left(x_{1}+t\left(x_{2}-x_{1}\right)\right)-\nabla f(x_{1}), x_{2}-x_{1}>dt \leqslant \int_{0}^{1} |<\nabla f\left(x_{1}+t\left(x_{2}-x_{1}\right)\right)-\nabla f(x_{1})| < \nabla f\left(x_{1}+t\left(x_{2}-x_{1}\right)\right) < \nabla f\left(x_{1}+t\left(x_{2}-x_{1}\right)\right) < \sum_{i=1}^{n} ||x_{i}|| < \sum_{i$$

$$\nabla f(x_1), x_2 - x_1 > |dt \leqslant \int_0^1 tL ||x_2 - x_1||_2^2 dt = \frac{L}{2} ||x_2 - x_1||_2^2$$

$$\implies f(x_2) = f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \int_0^1 < \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 > dt \leqslant f(x_1) + \nabla f(x_1)^T (x_2 - x_1) \int_0^1 |< \nabla f(x_1 + t(x_2 - x_1)) - \nabla f(x_1), x_2 - x_1 > |dt \leqslant f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{L}{2} ||x_2 - x_1||_2^2$$

$$\implies f(x_2) \leqslant f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{L}{2} ||x_2 - x_1||_2^2$$

(b)
$$f(x_2) \ge f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{1}{2L} \|\nabla f(x_2) - \nabla f(x_1)\|_2^2, \forall x_1, x_2 \in X$$

Answer: Let $x_1, x_2 \in X$,

Let $y \in X$,

$$f(x_1) - f(x_2) = f(x_1) - f(y) + f(y) - f(x_2)$$

Using (a) we have,

$$f(y) - f(x_2) \leqslant \nabla f(x_2)^T (y - x_2) + \frac{L}{2} \|y - x_2\|_2^2$$

$$\implies f(x_1) - f(x_2) \leqslant f(x_1) - f(y) + \nabla f(x_2)^T (y - x_2) + \frac{L}{2} \|y - x_2\|_2^2$$

If we assume f is convex, then we have

$$f(x_1) - f(y) \leqslant -\nabla f(x_1)^T (y - x_1)$$

$$\implies f(x_1) - f(x_2) \leqslant -\nabla f(x_1)^T (y - x_1) + \nabla f(x_2)^T (y - x_2) + \frac{L}{2} ||y - x_2||_2^2$$

$$\Longrightarrow f(x_1) - f(x_2) \leqslant -\nabla f(x_1)^T (y - x_2) - \nabla f(x_1)^T (x_2 - x_1) + \nabla f(x_2)^T (y - x_2) + \frac{L}{2} \|y - x_2\|_2^2$$

$$\implies f(x_1) - f(x_2) \leqslant -\nabla f(x_1)^T (x_2 - x_1) + (\nabla f(x_2) - \nabla f(x_1))^T (y - x_2) + \frac{L}{2} \|y - x_2\|_2^2$$

Let
$$y = x_2 - \frac{1}{L} \left(\nabla f(x_2) - \nabla f(x_1) \right)$$
 then $y - x_2 = -\frac{1}{L} \left(\nabla f(x_2) - \nabla f(x_1) \right)$

So we have:

$$f(x_1) - f(x_2) \leqslant -\nabla f(x_1)^T (x_2 - x_1) - \frac{1}{L} (\nabla f(x_2) - \nabla f(x_1))^T (\nabla f(x_2) - \nabla f(x_1)) + \frac{1}{L^2} * \frac{L}{2} \|\nabla f(x_2) - \nabla f(x_1)\|_2^2$$

$$\implies f(x_1) - f(x_2) \leqslant -\nabla f(x_1)^T (x_2 - x_1) - \frac{1}{2L} \|\nabla f(x_2) - \nabla f(x_1)\|_2^2$$

$$\Longrightarrow f(x_1) + \nabla f(x_1)^T (x_2 - x_1) + \frac{1}{2L} \|\nabla f(x_2) - \nabla f(x_1)\|_2^2 \leqslant f(x_2)$$

Part II: Convergence of plain GD

Consider the following optimization problem : $\min_{x \in \mathbb{R}^d} f(x)$ where f is strongly convex with conqtant mu, continuous with Lipschitz constant L. In other words, f is μ -strongly convex and L-smooth. Moreover, consider the Gradient descent (GD) with constant step-size

$$x_{k+1} = x_k - \alpha \nabla f(x_k), \alpha \ge 0 \tag{3}$$

We set the (constant) step-size as $\alpha = \frac{2}{L+\mu}$. This variant is known as plain/vanilla GD.

(1) Prove the convergence of GD with constant step size. Specifically, show that the iterations in (3) are such that:

$$||x_k - x^*||_2^2 \le \left(1 - \frac{2}{1 + \frac{L}{2}}\right)^{2k} ||x_0 - x^*||_2^2$$

Hints: you may use these observations.

From smoothness and vanishing gradient of the optimal point, conclude

$$f(x_k) - f(x^*) \leqslant \frac{L}{2} ||x_k - x^*||_2^2$$
 (*)

Use the coercivity of the gradient:

$$(\nabla f(x) - \nabla f(y))^{T} (x - y) \geqslant \frac{\mu L}{\mu + L} \|x - y\|_{2}^{2} + \frac{1}{\mu + L} \|\nabla f(x) - \nabla f(y)\|_{2}^{2}$$

Iterate over k and use (*) to obtain :

$$f(x_k) - f(x^*) \leqslant \frac{L}{2} \prod_{i \in [k]} \left(1 - 2\alpha \frac{\mu L}{\mu + L} \right) \|x_0 - x^*\|_2^2$$

Answer: We have

$$||x_{k+1} - x^*||_2^2 = ||x_k - \alpha \nabla f(x_k) - x^*||_2^2 = ||(x_k - x^*) - \alpha \nabla f(x_k)||_2^2$$

$$\implies ||x_{k+1} - x^*||_2^2 = ||x_k - x^*||_2^2 - 2\alpha < \nabla f(x_k), x_k - x^* > +\alpha^2 ||\nabla f(x_k)||_2^2$$

We have $\nabla f(x^*) = 0$ so, we can write :

$$\Longrightarrow \|x_{k+1} - x^*\|_2^2 = \|x_k - x^*\|_2^2 - 2\alpha < \nabla f(x_k) - \nabla f(x^*), x_k - x^* > +\alpha^2 \|\nabla f(x_k) - \nabla f(x^*)\|_2^2$$

Using the coercivity of the gradient of f, we have :

$$\left(\nabla f(x) - \nabla f(y)\right)^T(x - y) \geqslant \frac{\mu L}{\mu + L} \|x - y\|_2^2 + \frac{1}{\mu + L} \|\nabla f(x) - \nabla f(y)\|_2^2 \ \forall x, y \in X$$

we have:

$$\begin{aligned} &\|x_{k+1} - x^*\|_2^2 \leqslant \|x_k - x^*\|_2^2 - 2\alpha \left(\frac{\mu L}{\mu + L} \|x_k - x^*\|_2^2 + \frac{1}{\mu + L} \|\nabla f(x_k) - \nabla f(x^*)\|_2^2\right) + \alpha^2 \|\nabla f(x_k) - \nabla f(x^*)\|_2^2 \end{aligned}$$

$$\implies \|x_{k+1} - x^*\|_2^2 \leqslant \left(1 - 2\alpha \frac{\mu L}{\mu + L}\right) \|x_k - x^*\|_2^2 + \left(\alpha^2 - \frac{2\alpha}{\mu + L}\right) \|\nabla f(x_k) - \nabla f(x^*)\|^2$$

We have:

$$\alpha^2 - \frac{2\alpha}{\mu + L} = 0$$

so, we have:

$$||x_{k+1} - x^*||_2^2 \le \left(1 - 2\alpha \frac{\mu L}{\mu + L}\right) ||x_k - x^*||_2^2$$

$$||x_{k+1} - x^*||_2^2 \le \left(\frac{L-\mu}{\mu+L}\right)^2 ||x_k - x^*||_2^2$$

$$\implies ||x_{k+1} - x^*||^2 \le (1 - \alpha \mu)^2 ||x_k - x^*||^2$$

When we iterate over k on the right side, we get:

$$\implies ||x_{k+1} - x^*||_2^2 \le (1 - \alpha \mu)^{2(k+1)} ||x_0 - x^*||_2^2$$

we can conclude that:

$$||x_k - x^*||_2^2 \le \left(1 - \frac{2}{1 + \frac{L}{\mu}}\right)^{2k} ||x_0 - x^*||_2^2$$

2) What is the convergence rate of this variant, in the $\mathcal{O}(-)$ sense?

Answer : The rate of convergence of this variant is $(c)^k = \mathcal{O}((c)^{2k})$ where $c = 1 - \frac{2}{1 + \frac{L}{\mu}}$

- 3) Recall: μ and L are upper and lower bounds on the largest and smallest eigenvalues of the Hessian of a μ -strongly convex and L-smooth, respectively
- a) Wath happens to the convergence rate (question 1) when $L/\mu \to 1$? Explain to which scenario does this correspond. Discuss the pratical implications of this scenario for DG.

Answer: When $\frac{L}{\mu} \to 1$, the convergence constant $c = 1 - \frac{2}{1 + \frac{L}{\mu}} \to 0$ so the convergence rate $(c)^k$ decreases quickly: We have a fastest convergence for GD.

b) What happens to the convergence rate (question 1) when $L/\mu \to \infty$? Explain to which scenario does this correspond. Discuss the practical implications of this scenario for GD.

Answer: When $\frac{L}{\mu} \to \infty$, the convergence constant $c = 1 - \frac{2}{1 + \frac{L}{\mu}} \to 1$ so the convergence rate $(c)^k$ decreases slowly: We have a slowest convergence for GD.

Part III : Finding L and μ

Consider a linear ridge regression : $\min_{w} f(w) = \frac{1}{N} \sum_{i \in [N]} f_i(w) + \lambda ||w||_2^2$ where

the loss for sample i is given by : $f_i(w) = (y_i - w^T x_i)^2$. Use the Bodyfat dataset (available in the ML toolbox in MATLAB)

a) Is f Lipschitz continuous? If so, find a small Lipschitz constant L?

Answer: We have for all w:

$$f(w) = \frac{1}{N} \sum_{i \in [N]} f_i(w) + \lambda ||w||_2^2$$

$$\Longrightarrow f(w) = \frac{1}{N} \sum_{i \in [N]} \left(f_i(w) + \lambda ||w||_2^2 \right)$$

Let
$$g_i(w) = f_i(w) + \lambda ||w||_2^2$$

then we have:

$$f(w) = \frac{1}{N} \sum_{i \in [N]} g_i(w)$$

NB : we consider the functions g_i thus defined in the other questions

Let B > 0 and
$$\mathcal{H} = \left\{ w \in \mathbb{R}^d : \|w\|_2 \leqslant B \right\}$$

Let $w \in \mathcal{H}$ then we have :

$$g_i(w) = (y_i - w^T x_i)^2 + \lambda ||w||_2^2$$

$$\Longrightarrow \nabla g_i(w) = -2x_i (y_i - w^T x_i) + 2\lambda w$$

$$\Longrightarrow \nabla g_i(w) = -2x_iy_i + 2(x_ix_i^T + \lambda I_d)w$$

$$\implies \|\nabla g_i(w)\|_2 = \|-2x_iy_i + 2(x_ix_i^T + \lambda I_d)w\|_2 \leqslant 2\|x_iy_i\|_2 + 2\|(x_ix_i^T + \lambda I_d)\|_2 B$$

$$\implies \|\nabla f_i(w)\|_2 = \|\frac{1}{N} \sum_{i \in [N]} \nabla g_i(w)\|_2 \leqslant \frac{1}{N} \sum_{i \in [N]} \|\nabla g_i(w)\|_2 \leqslant \frac{2}{N} \sum_{i \in [N]} \|x_i y_i\|_2 + \frac{1}{N} \sum_{i \in [N]} \|\nabla g_i(w)\|_2 \leqslant \frac{1}{N} \sum_{i \in [N]} \|x_i y_i\|_2 + \frac{1}{N} \sum_{i \in [N]} \|\nabla g_i(w)\|_2 \leqslant \frac{1}{N} \sum_{i \in [N]} \|x_i y_i\|_2 + \frac{1}{N} \sum_{i \in [N]} \|\nabla g_i(w)\|_2 \leqslant \frac{1}{N} \sum_{i \in [N]} \|\nabla g_i(w)\|_2 \leqslant$$

$$\frac{2B}{N} \sum_{i \in [N]} \| \left(x_i x_i^T + \lambda I_d \right) \|_2$$

$$\implies \|\nabla f_i(w)\|_2 \leqslant \frac{2}{N} \sum_{i \in [N]} \|x_i y_i\|_2 + \frac{2B}{N} \sum_{i \in [N]} \|(x_i x_i^T + \lambda I_d)\|_2$$

So we can say that f is L-lipschitz and we can takes

$$L = \frac{2}{N} \sum_{i \in [N]} \|x_i y_i\|_2 + \frac{2B}{N} \sum_{i \in [N]} \| (x_i x_i^T + \lambda I_d) \|_2$$

as lipschitz constant

b) Is f strongly convex? If so, find a large μ ?

Answer : Consider this function : $h(w) = \lambda ||w||_2^2$ then :

$$\nabla h(w) = 2\lambda w$$

$$\Longrightarrow \nabla^2 h(w) = 2\lambda I_d$$

$$\Longrightarrow \nabla^2 h(w) \succ 2\lambda I_d$$

So, the h function is 2λ -strongly convex (**)

For $i \in [N]$, we have

$$f_i(w) = (y_i - w^T x_i)^2$$

$$\Longrightarrow \nabla f_i(w) = -2x_i \left(y_i - w^T x_i \right)$$

$$\Longrightarrow \nabla^2 f_i(w) = 2x_i x_i^T$$

$$\Longrightarrow \nabla^2 f_i(w) \succcurlyeq 0$$

so we can say that the function f_i is convex (***)

(**) and (***)
$$\Longrightarrow g_i(w) = f_i(w) + h(w)$$
 is 2λ -strongly convex

So,
$$f(w) = \frac{1}{N} \sum_{i \in [N]} g_i(w)$$
 is 2λ -strongly convex and we can choose

$$\mu = 2\lambda$$

c) There is a simple way (trick) to find L and μ , for the optimization problem considered here.

Express, mathematically, the steps for doing so, and derive the expressions for L, μ , and their ratio L/ μ

What inherent properties of the dataset impact (and determine) the ratio L/μ ?

Answer : We can find the values of L and μ by calculating the eigenvalues of the Hessian matrix of f. Indeed μ and L are respectively the min and the max of the eigenvalues of the Hessian matrix of f.

step 1 : We compute the matrix
$$\nabla^2 f(w) = \frac{2}{N} \sum_{i \in [N]} x_i x_i^T + 2\lambda I_d$$

step 2 : Compute the eigenvalues $\{\lambda_i\}_{i\in[N]}$ of $\nabla^2 f(w)$

step 3 : compute the values of L and μ

$$L = \max \{\lambda_i\}_{i \in [N]}$$

$$\mu = \min \{\lambda_i\}_{i \in [N]}$$

To calculate μ and L, we need to determine the eigenvalues of $\nabla^2 f(w) = \frac{2}{N} \sum_{i \in [N]} x_i x_i^T + 2\lambda I_d$.

So, the larger our dataset, i.e. N is big , more we need times to calculate $\frac{2}{N}\sum_{i\in[N]}x_ix_i^T$.

Thus, we can say that the size of our data set (N) impacts the calculation of the ratio $\frac{L}{\mu}$

d) What can you say about the ratio L/μ for the Bodyfat dataset? is it a 'good' or 'bad' setup for a plain GD method

Answer: The bodyfat dataset contains 252 items, so the number of items is relatively small. So this is a good dataset for GD method

Part IV : Duality and Optimality for Equality Constrained Quadratic Program

Consider the following Equality Constrained Quadratic Program (ECQP).

$$ECQP: x^* := \begin{cases} arg \min f_0(x) = x^T S x \\ x \in \mathbb{R}^d \\ s.t. \quad Ax = b \end{cases}$$

where $\mathbf{S} \in \mathbb{R}^{d \times d} \succ 0$ is a positive definite matrix, $\mathbf{A} \in \mathbb{R}^{d \times d}$ and $\mathbf{b} \in \mathbb{R}^d$

1) Derive the Lagrangian $\mathcal{L}()$, the Lagrange function g(), and the dual problem, that correspond to the above ECQP

Answer: We have

$$\mathcal{L}(x, v) = f_0(x) + v^T (Ax - b)$$

$$\Longrightarrow \mathcal{L}(x, v) = x^T S x + v^T (Ax - b)$$

Nothing that for all v, the function $x \to \mathcal{L}(x,v)$ is strongly convex and continuously differentiable. So, we have :

$$\hat{x} = \underset{x \in \mathbb{R}^d}{arg \min} \, \mathcal{L}(x, v) \in \{x \in \nabla \mathcal{L}_x(x, v) = 0\}$$

We have:

$$\nabla \mathcal{L}_x(x, v) = \nabla_x \left(x^T S x + v^T (A x - b) \right)$$

$$\Longrightarrow \nabla \mathcal{L}_x(x, v) = 2S x + A^T v$$

$$\Longrightarrow \nabla \mathcal{L}_x(x, v) = 0 \Longleftrightarrow 2S x + A^T v = 0$$

$$\Longrightarrow x = -(2S)^{-1} A^T v \text{ So we have}$$

$$\hat{x} = -(2S)^{-1}A^Tv$$

We have
$$g(v) = \inf_{x \in \mathbb{R}^d} \mathcal{L}(x, v) = \mathcal{L}(\hat{x}, v)$$

$$\implies g(v) = \mathcal{L}(-(2S)^{-1}A^Tv, v)$$

$$\Longrightarrow g(v) = \left[-(2S)^{-1}A^Tv \right]^T S \left[-(2S)^{-1}A^Tv \right] + v^T \left(A \left[-(2S)^{-1}A^Tv \right] - b \right)$$

$$\Longrightarrow g(\upsilon) = \tfrac{1}{4} \left[A^T \upsilon \right]^T S^{-1} \left[A^T \upsilon \right] - \tfrac{1}{2} \left[A^T \upsilon \right]^T S^{-1} \left[A^T \upsilon \right] - \upsilon^T b$$

$$g(v) = -\frac{1}{4} [A^T v]^T S^{-1} [A^T v] - v^T b$$

The Lagragian dual problem D is define by:

$$\max_{v} g(v) = \min_{v} - g(v) = \min_{v} \left\{ \frac{1}{4} \left[A^{T} v \right]^{T} S^{-1} \left[A^{T} v \right] + v^{T} b \right\}$$

As S > 0 then S^{-1} > 0, \Longrightarrow the dual problem is trongly convex QP in v. So we have :

$$-\nabla g(v) = \frac{1}{2}AS^{-1}A^{T}v + b$$

$$\Longrightarrow -\nabla g(v) = 0 \Longleftrightarrow \frac{1}{2}AS^{-1}A^{T}v + b = 0$$

$$\Longrightarrow -\nabla g(v) = 0 \Longleftrightarrow v = -2\left(AS^{-1}A^{T}\right)b$$

So we have:

$$\hat{v} = \arg\max_{v} g(v) = -2 \left(A S^{-1} A^{T} \right) b$$

$$\implies \hat{x} = S^{-1} A^{T} \left(A S^{-1} A^{T} \right) b$$

$$\implies \hat{x} = \left(S^{-1} A^{T} \right) A \left(S^{-1} A^{T} \right) b$$

2) Derive the KKT conditions that correspond to the above ECQP. Use these KKT condition to derive a closed-form analytical solution, x^* ?, as a function of optimal dual variables, μ^* ?

Answer: We have:

- 1- The ECQP problem is strongly convex
- 2- $\nabla \mathcal{L}(\hat{x}, \hat{v}) = 0$
- 3- The contrain function (Ax-b) is affine

So using the KKT condition, we can say: the close form analytical solution

of ECQP problem is given by : $\,$

$$\hat{x} = (S^{-1}A^T) A (S^{-1}A^T) b$$

we have also:

$$\hat{x} = \left(S^{-1}A^{T}\right)A\left(S^{-1}A^{T}\right)b$$

$$\hat{v} = \underset{v}{arg\ max\ g(v)} = -2\left(AS^{-1}A^{T}\right)b$$