



start with velocity  $\vec{v}$  on manifold  $\exp_p(\vec{v})$ ?  
location  $p$ .

Back to  $e^x$ . Consider  $e^x = g(t)$ ,  $g$  satisfies:  $\begin{cases} g(0) = 1 \\ g'(t) = x g(t) \end{cases} \Rightarrow g(t) = e^{tx}$

in diagram: start  $\xrightarrow{\text{initial velocity } x}$   $\bullet$   $\xrightarrow{\text{intermediate point } g(t)}$   $e^x$  g is used to describe point on manifold.

generally: start  $p \xrightarrow{\vec{v}}$   $\bullet$   $\xrightarrow{\text{intermediate point}}$   $\exp_p(\vec{v})$

consider  $f(x) \xrightarrow{\frac{df}{dx}}$   $\bullet$   $\xrightarrow{\text{intermediate point } g(t, x)}$   $\exp(\frac{d}{dx}) f(x)$  g satisfies:

$\begin{cases} g(0, x) = f(x) \\ \frac{\partial g}{\partial t} = \frac{\partial f}{\partial x} \end{cases}$

generally:  $\exp(\vec{a} \cdot \nabla) f(\vec{x}) = f(\vec{x} + \vec{a})$

$g(x, t) = f(x + t)$   
 $\Rightarrow \exp(t \frac{d}{dx}) f(x) = f(x + t)$   
shift spaster

Furthermore:  $f(x) \xrightarrow{\frac{d^2 f}{dx^2}}$   $\bullet$   $\xrightarrow{\text{intermediate point } g(t, x)}$   $\exp(\frac{d^2}{dx^2}) f(x)$

$\Rightarrow \begin{cases} g(0, x) = f(x) \\ \frac{\partial g}{\partial t} = \frac{\partial^2 g}{\partial x^2} \end{cases}$   $g(t, x) = \int_{\mathbb{R}} f(s) G(x, t; s) ds = \exp(t \frac{d^2}{dx^2}) f(x)$   
where  $G(x, t; s) = \frac{1}{\sqrt{2\pi t}} \exp[-\frac{(x-s)^2}{4t}]$

so  $p \xrightarrow{\text{vector at point } p}$   $\bullet$   $\xrightarrow{\text{vector to } g(t)}$   $\exp(\text{vector field})(p)$

Reduce:  $g(t) = \exp(\text{vector field})(p)$  vector field is linear  $\rightarrow A$   $\Rightarrow \exp(tA) \vec{v}$   
flow p =  $\vec{v}$  on manifold which is the trajectory of  $\vec{v}$

