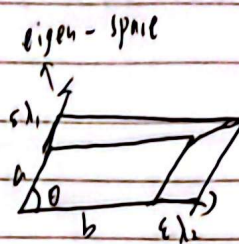


1st $\text{Tr} A = \text{divergence}$
 let vector field $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ $f(x) = Ax = \begin{pmatrix} f_1 \\ \vdots \\ f_n \end{pmatrix}$
 $A = \nabla f(x) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \cdots & \frac{\partial f_n}{\partial x_n} \end{pmatrix}$, $\text{Tr}(A) = \text{div}(f)$

2nd: One can see Divergence = $\frac{\text{rate of } V \text{ change}}{\text{area}}$

3rd (1) $\text{Tr}(A) = \sum_i \lambda_i(A)$ If: 

new area: $a(1+\epsilon\lambda_1) \cdot b(1+\epsilon\lambda_2) \sin\theta$

divergence = $\lim_{\epsilon \rightarrow 0} \frac{\text{rate of area change}}{\text{area}} = \frac{ab \sin\theta (1+\epsilon\lambda_1)(1+\epsilon\lambda_2) - ab \sin\theta}{ab \sin\theta}$

$= (1+\epsilon\lambda_1)(1+\epsilon\lambda_2) - 1 = \lambda_1 + \lambda_2 + \epsilon^2 \lambda_1 \lambda_2 \xrightarrow{\epsilon \rightarrow 0} \lambda_1 + \lambda_2$

(2) $\det(e^{tA}) = e^{t \text{Tr}(A)}$, let $\det(e^{tA}) = S(t)$ be area at time t

$\text{Tr}(A) = \frac{S'(t)}{S(t)} \Rightarrow (e^{t \text{Tr}(A)})' = S'(t)$, $t=0$, $(= S(0) = 1)$
 $\Rightarrow \det(e^{tA}) = S(t) = e^{\text{Tr}(A)t}$

(3) $\text{Tr}(A) = \text{Tr}(P^{-1}AP)$: For vector field: $\vec{x} \rightarrow \vec{x} + A\vec{x}$

apply u $u\vec{x} \rightarrow u\vec{x} + uA\vec{x}$
 $\text{Tr}(uAu^{-1}) = \frac{\text{rate Area det}(u)}{\text{Area det}(u)} = \text{Tr}(A)$ $\vec{y} = u\vec{x}$ $\vec{y} \rightarrow \vec{y} + (uAu^{-1})\vec{y}$

(4) $\text{Tr}(AB) = \text{Tr}(BA)$: let $B \in GL_n(\mathbb{R})$, $\text{Tr}(AB) = \text{Tr}(B^{-1}(BA)B) = \text{Tr}(BA)$



(5) for $A \in GL_n(\mathbb{R})$, $\frac{d \det(A(t))}{dt} = \det(A(t)) \operatorname{Tr} \left[A^{-1}(t) \frac{dA(t)}{dt} \right]$ - Q

If A may not invertible: $\frac{d \det(A(t))}{dt} = \operatorname{Tr} [\operatorname{adj}(A(t)) \frac{dA(t)}{dt}]$

For Q: Let $\delta(t) = \det(A(t))$, for vector field generated by M :

$\operatorname{Tr} M = \frac{\delta'(t)}{\delta(t)}$ w.r.t. M ; For $A(t)$ acts on basis vector

$(1, 0)^T, (0, 1)^T \rightarrow A(t)(1, 0)^T, A(t)(0, 1)^T \xrightarrow{M} A'(t)(1, 0)^T, A'(t)(0, 1)^T$

Since $A(t) \in GL_n(\mathbb{R}) \Rightarrow A'(t) A^{-1}(t) A(t) = A'(t) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = A'(t) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$?

$\Rightarrow \operatorname{Tr}(A^{-1}(t) A'(t)) = \frac{d \det(A(t))}{dt}$

