

Linear Algebra

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1 Definitions

1.1 Vectors and Vector Spaces

- The *span* of \mathbf{u} and \mathbf{v} is the set of all *linear combinations*:

$$a\mathbf{u} + b\mathbf{v}$$

- When \mathbf{u} is a linear combination of the others basis vectors, then it's *linearly dependent*
- The basis \mathbf{B} of a *vector space* V is a set of *linearly independent* vectors that *span* the full space

2 Linear Algebra Intuition

Notes from the 3B1B video series.

2.1 Vectors and Vector Spaces

- Vectors $\mathbf{x} = (x_1, \dots, x_n)$ can be viewed interchangeably as **ordered lists** or as objects with length and direction, i.e. an arrow
- Vectors are points in L.A., sometimes it's easier to think of them as arrows, sometimes as points (when you have many), sometimes as lists (when you're programming)
- Vectors live in a **vector space** V that has certain properties
- in Linear Algebra (L.A.) vectors always start at the origin $\mathbf{0} = (0, \dots, 0)$
- Vectors are almost always represented as column vectors
- Vectors have a sum $+$ and a scalar multiplication \cdot
- Vector sum can be viewed as a translation to the vector space, similarly to how real numbers translate the \mathbb{R}
- Scalar multiplication can be viewed as *scaling* the vector by the magnitude of the scalar.
- Any vector \mathbf{x} can be viewed as the *linear combination* of the basis vectors (on a given space). e.g. for \mathbb{R}^2

$$\mathbf{x} = 3\hat{\mathbf{i}} - 2\hat{\mathbf{j}} = (3, -2)$$

- When you think of a vector space, you have to think about the basis of it \mathbf{B} , in the previous example $\hat{\mathbf{i}}$ and $\hat{\mathbf{j}}$ *span* \mathbb{R}^2

3 Useful Properties

3.1 Matrices

- 2×2 **matrices** $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$- \text{Inverse If } \det(A) = ad - bc \neq 0 \Rightarrow A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$