INSA Lyon ACM-ICPC Notebook 2018 (C++)

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1 Geometry

1.1 Convex Hull Algorithm

```
bool compare(PT a,PT b) {         return a.y<b.y || (a.y==b.y && a.x<b.x); }</pre>
double cross(PT o,PT a, PT b)
        return (a.x-o.x) * (b.y-o.y) - (a.y-o.y) * (b.x-o.x);
vector<PT> ConvexHull(vector<PT> p) {    int n=p.size();    int k=0;
    vector<PT> h(2*n);
    sort(p.begin(),p.end(),compare);
         //build lower hull
        for (int i=0; i < n; ++i)
                 while (k>=2 \&\& cross(h[k-2],h[k-1],p[i]) <=0) k--;
                 h[k++]=p[i];
         //build top hull
        for (int i=n-2, t=k+1; i>=0; --i)
                 while (k>=t \&\& cross(h[k-2],h[k-1],p[i]) <= 0) k--;
                 h[k++]=p[i];
        h.resize(k);
        return h;
```

1.2 Delaunay Triangulation

```
Stanford notebook
Delaunay Algorithm Does not handle degenerate cases
Running time: O(n^4)
INPUT: x[] = x-coordinates
           y[] = y-coordinates
OUTPUT: triples = a vector containing m triples
(indices corresponding to triangle vertices)
typedef double T;
struct triple {
        int i, j, k;
        triple() {}
        triple(\textbf{int i, int j, int }k) \ : \ i(i), \ j(j), \ k(k) \ \{\}
vector<triple> delaunayTriangulation(vector<T>& x, vector<T>& y)
        int n = x.size();
        vector<T> z(n);
        vector<triple> ret;
    for (int i = 0; i < n; i++)
        z[i] = x[i] * x[i] + y[i] * y[i];
    for (int i = 0; i < n-2; i++)
        for (int j = i+1; j < n; j++)
                 for (int k = i+1; k < n; k++)
                          if (j == k) continue;
                 double xn = (y[j]-y[i])*(z[k]-z[i]) - (y[k]-y[i])*(z[j]-z[i]);

double yn = (x[k]-x[i])*(z[j]-z[i]) - (x[j]-x[i])*(z[k]-z[i]);
                 double zn = (x[j]-x[i]) * (y[k]-y[i]) - (x[k]-x[i]) * (y[j]-y[i]);
                 bool flag = zn < 0;</pre>
                 for (int m = 0; flag && m < n; m++)</pre>
                          flag = flag && ((x[m]-x[i])*xn + (y[m]-y[i])*yn + (z[m]-z[i])*zn <= 0);
                 if (flag) ret.push_back(triple(i, j, k));
    return ret:
int main() {
        T xs[]={0, 0, 1, 0.9};
T ys[]={0, 1, 0, 0.9};
        vector<T> x(&xs[0], &xs[4]), y(&ys[0], &ys[4]);
        vector<triple> tri = delaunayTriangulation(x, y);
         //expected: 0 1 3
        int i;
        for(i = 0; i < tri.size(); i++)</pre>
                 printf("%d %d %d\n", tri[i].i, tri[i].j, tri[i].k);
        return 0;
```

1.3 Various Geometry Functions

```
// Stanford Notebook
double INF = 1e100;
double EPS = 1e-12;
struct PT {
       double x, y;
       PT(double x, double y) : x(x), y(y) {}
       PT (const PT &p) : x (p.x), y (p.y)
       PT operator + (const PT &p) const { return PT(x+p.x, y+p.y);
       PT operator - (const PT &p) const { return PT(x-p.x, y-p.y); }
       PT operator * (double c)
                                   const { return PT(x*c, y*c );
       PT operator / (double c)
                                    const { return PT(x/c, y/c ); }
1:
double dot(PT p, PT q)
                          { return p.x*q.x+p.y*q.y; }
double dist2(PT p, PT q)
                          { return dot(p-q,p-q); }
double cross(PT p, PT q) { return p.x*q.y-p.y*q.x; }
```

```
// rotate a point CCW or CW around the origin
PT RotateCCW90 (PT p) { return PT (-p.y,p.x); }
PT RotateCW90 (PT p)
                       { return PT(p.y,-p.x); }
PT RotateCCW(PT p, double t) {
                                  return PT(p.x*cos(t)-p.y*sin(t), p.x*sin(t)+p.y*cos(t)); }
  project point c onto line through a and b // assuming a != b
PT ProjectPointLine(PT a, PT b, PT c) { return a + (b-a)*dot(c-a, b-a)/dot(b-a, b-a); }
// project point c onto line segment through a and b
PT ProjectPointSegment (PT a, PT b, PT c)
       double r = dot(b-a,b-a);
if (fabs(r) < EPS) return a;</pre>
        r = dot(c-a, b-a)/r;
        if (r < 0) return a:
        if (r > 1) return b;
        return a + (b-a) *r;
// compute distance from c to segment between a and b
double DistancePointSegment (PT a, PT b, PT c)
        return sqrt(dist2(c, ProjectPointSegment(a, b, c)));
// compute distance between point (x,y,z) and plane ax+by+cz=d
return fabs(a*x+b*v+c*z-d)/sgrt(a*a+b*b+c*c);
// determine if lines from a to b and c to d are parallel or collinear
bool LinesParallel(PT a, PT b, PT c, PT d) { return fabs(cross(b-a, c-d)) < EPS; }</pre>
bool LinesCollinear(PT a, PT b, PT c, PT d)
        return LinesParallel(a, b, c, d)
        && fabs(cross(a-b, a-c)) < EPS
        && fabs(cross(c-d, c-a)) < EPS;
// determine if line segment from a to b intersects with
// line segment from c to d
bool SegmentsIntersect (PT a, PT b, PT c, PT d)
        if (LinesCollinear(a, b, c, d))
                if (dist2(a, c) < EPS || dist2(a, d) < EPS ||</pre>
                dist2(b, c) < EPS || dist2(b, d) < EPS) return true;
                if (dot(c-a, c-b) > 0 && dot(d-a, d-b) > 0 && dot(c-b, d-b) > 0)
                        return false:
                return true:
        if (cross(d-a, b-a) * cross(c-a, b-a) > 0)
               return false:
        if (cross(a-c, d-c) * cross(b-c, d-c) > 0)
               return false;
        return true;
// compute intersection of line passing through a and b
// with line passing through c and d, assuming that unique
// intersection exists; for segment intersection, check if
// segments intersect first
PT ComputeLineIntersection(PT a, PT b, PT c, PT d)
        b=b-a; d=c-d; c=c-a;
        assert (dot (b, b) > EPS && dot (d, d) > EPS);
        return a + b*cross(c, d)/cross(b, d);
// compute center of circle given three points
PT ComputeCircleCenter(PT a, PT b, PT c)
        b = (a+b)/2;
        c = (a+c)/2;
        return ComputeLineIntersection(b, b+RotateCW90(a-b), c, c+RotateCW90(a-c));
// determine if point is in a possibly non-convex polygon (by William
// Randolph Franklin); returns 1 for strictly interior points, 0 for
// strictly exterior points, and 0 or 1 for the remaining points.
// Note that it is possible to convert this into an *exact* test using
// integer arithmetic by taking care of the division appropriately
// (making sure to deal with signs properly) and then by writing exact
// tests for checking point on polygon boundary
bool PointInPolygon(const vector<PT> &p, PT q)
        bool c = 0;
        for (int i = 0; i < p.size(); i++)</pre>
```

```
int j = (i+1)%p.size();
                 if ((p[i].y <= q.y && q.y < p[j].y ||</pre>
                p[j].y \le q.y \&\& q.y < p[i].y) \&\&
                 q.x < p[i].x + (p[j].x - p[i].x) * (q.y - p[i].y) / (p[j].y - p[i].y))
        return c;
// determine if point is on the boundary of a polygon
bool PointOnPolygon(const vector<PT> &p, PT q)
        for (int i = 0; i < p.size(); i++)
    if (dist2(ProjectPointSegment(p[i], p[(i+1)%p.size()], q), q) < EPS)</pre>
                         return true:
        return false;
// compute intersection of line through points a and b with
 // circle centered at c with radius r > 0
 vector<PT> CircleLineIntersection(PT a, PT b, PT c, double r)
        vector<PT> ret:
        b = b-a; a = a-c;
double A = dot(b, b);
        double B = dot(a, b);
        double C = dot(a, a) - r*r;
        double D = B*B - A*C;
        if (D < -EPS) return ret;</pre>
        ret.push_back(c+a+b*(-B+sqrt(D+EPS))/A);
        if (D > EPS)
                ret.push_back(c+a+b*(-B-sqrt(D))/A);
        return ret;
// compute intersection of circle centered at a with radius r
// with circle centered at b with radius R
vector<PT> CircleCircleIntersection(PT a, PT b, double r, double R)
        vector<PT> ret:
        double d = sgrt(dist2(a, b));
        if (d > r+R || d+min(r, R) < max(r, R)) return ret;</pre>
        double x = (d*d-R*R+r*r)/(2*d);
        double y = sqrt(r*r-x*x);
        PT v = (b-a)/d;
        ret.push_back(a+v*x + RotateCCW90(v)*y);
        if (y > 0) ret.push_back(a+v*x - RotateCCW90(v)*y);
        return ret:
// This code computes the area or centroid of a (possibly nonconvex)
// polygon, assuming that the coordinates are listed in a clockwise or
// counterclockwise fashion. Note that the centroid is often known as
// the "center of gravity" or "center of mass".
double ComputeSignedArea(const vector<PT> &p)
        double area = 0;
        for(int i = 0; i < p.size(); i++)</pre>
                 int j = (i+1) % p.size();
                area += p[i].x*p[j].y - p[j].x*p[i].y;
        return area / 2.0;
double ComputeArea(const vector<PT> &p) {    return fabs(ComputeSignedArea(p)); }
PT ComputeCentroid(const vector<PT> &p)
        PT c(0,0);
        double scale = 6.0 * ComputeSignedArea(p);
        for (int i = 0; i < p.size(); i++)</pre>
                 int j = (i+1) % p.size();
                 c = c + (p[i]+p[j])*(p[i].x*p[j].y - p[j].x*p[i].y);
        return c / scale;
// tests whether or not a given polygon (in CW or CCW order) is simple
bool IsSimple(const vector<PT> &p)
        for (int i = 0; i < p.size(); i++)</pre>
                 for (int k = i+1; k < p.size(); k++)</pre>
                         int j = (i+1) % p.size();
                         int 1 = (k+1) % p.size();
                         if (i == 1 \mid \mid j == k) continue;
```

2 Graphs

2.1 Dijkstra's Algorithm

```
//Dijkstra Algorithm
int t,n,m,s,e;
vector<ii> edges[N];//pair<NodeEnd,dist>
int distances[N]; // =INF=0x3f3f3f3f
int parent[N]; // =-1
int Dijkstra()
        vector<ii>> :: iterator it;
        priority_queue< ii, vector<ii>, greater<ii> > pq;
        distances[s]=0;
        pg.push(ii(distances[s],s));
        while(!pq.empty())
                ii p = pq.top();
                pq.pop();
                int d=p.first;
                int a=p.second:
                for(it=edges[a].begin();it!=edges[a].end();++it)
                        if (distances[it->first]>distances[a]+it->second)
                            distances[it->first]=distances[a]+it->second;
                            parent[it->first]=a:
                            pq.push(ii(distances[it->first],it->first));
        return distances[e];
```

2.2 Max Flow (Dinic's Algorithm)

```
// Stanford Notebook
typedef long long LL;
struct Edge
        int from, to, cap, flow, index;
        Edge(int from, int to, int cap, int flow, int index) :
from(from), to(to), cap(cap), flow(flow), index(index) {}
        LL rcap() { return cap - flow; }
};
struct Dinic
        vector<vector<Edge> > G:
        vector<vector<Edge *> > Lf;
        vector<int> layer;
        vector<int> Q;
        Dinic(int N) : N(N), G(N), Q(N) {}
        void AddEdge(int from, int to, int cap)
                 if (from == to) return;
                 G[from].push_back(Edge(from, to, cap, 0, G[to].size()));
                 G[to].push_back(Edge(to, from, 0, 0, G[from].size() - 1));
        LL BlockingFlow(int s, int t)
                  layer.clear();
                 layer.resize(N, -1);
                 layer[s] = 0;
Lf.clear(); Lf.resize(N);
         int head = 0, tail = 0;
                 Q[tail++] = s;
         while (head < tail)</pre>
```

```
int x = Q[head++];
                 for (int i = 0; i < G[x].size(); i++)</pre>
                          Edge &e = G[x][i]; if (e.rcap() <= 0) continue;</pre>
                          if (layer[e.to] == -1)
                                  layer[e.to] = layer[e.from] + 1;
                                  Q[tail++] = e.to;
                          if (layer[e.to] > layer[e.from])
                                  Lf[e.from].push_back(&e);
if (layer[t] == -1) return 0;
LL totflow = 0;
        vector<Edge *> P;
        while (!Lf[s].empty())
                 int curr = P.empty() ? s : P.back()->to;
                 if (curr == t)
                          // Augment
                          LL amt = P.front()->rcap();
                         for (int i = 0; i < P.size(); ++i)
                                  amt = min(amt, P[i]->rcap());
                          totflow += amt;
                          for (int i = P.size() - 1; i >= 0; --i)
                                  P[i]->flow += amt;
                                  G[P[i]\rightarrow to][P[i]\rightarrow index].flow -= amt;
                                  if (P[i]->rcap() <= 0)
                                           Lf[P[i]->from].pop_back();
                                           P.resize(i);
                 else if (Lf[curr].empty())
                          // Retreat
                          P.pop_back();
                          for (int i = 0; i < N; ++i)
                                  for (int j = 0; j < Lf[i].size(); ++j)
    if (Lf[i][j]->to == curr)
                                                    Lf[i].erase(Lf[i].begin() + j);
                 else
                          // Advance
                          P.push_back(Lf[curr].back());
        return totflow;
LL GetMaxFlow(int s, int t)
        while (LL flow = BlockingFlow(s, t))
                 totflow += flow;
        return totflow;
```

2.3 Max Flow (Edmonds-Karp Algorithm)

};

```
/*
Stanford Notebook
MinCostMaxFlow (adjacency matrix, Edmonds and Karp 1972)
This implementation keeps track of forward and reverse edges separately
(so you can set cap[i][j] != cap[j][i]). For a regular max flow, set all edge costs to 0.
Running time, O(|V|^2) cost per augmentation

max flow: O(|V|^3) augmentations

min cost max flow: O(|V|^4 * MAX_EDGE_COST) augmentations

INPUT: - graph, constructed using AddEdge()

- source

- sink

OUTPUT: - (maximum flow value, minimum cost value)

- To obtain the actual flow, look at positive values only.

*/

typedef vector<int> VI;
```

```
typedef vector<VI> VVI;
typedef long long L;
typedef vector<L> VL;
typedef vector<VL> VVL;
typedef pair<int, int> PII;
typedef vector<PII> VPII;
const L INF = numeric_limits<L>::max() / 4;
struct MinCostMaxFlow {
        int N;
        VVL cap, flow, cost;
        VI found;
        VL dist, pi, width;
        VPII dad:
    MinCostMaxFlow(int N) :
    N(N), cap(N, VL(N)), flow(N, VL(N)), cost(N, VL(N)),
    found(N), dist(N), pi(N), width(N), dad(N) {}
    void AddEdge(int from, int to, L cap, L cost)
        this->cap[from][to] = cap;
        this->cost[from][to] = cost;
    void Relax(int s, int k, L cap, L cost, int dir)
        L val = dist[s] + pi[s] - pi[k] + cost;
if (cap && val < dist[k])</pre>
                 dist[k] = val;
                 dad[k] = make_pair(s, dir);
width[k] = min(cap, width[s]);
    L Dijkstra(int s, int t)
         fill(found.begin(), found.end(), false);
        fill(dist.begin(), dist.end(), INF);
        fill(width.begin(), width.end(), 0);
        dist[s] = 0:
        width[s] = INF;
        while (s != -1)
                 int best = -1;
                 found[s] = true;
                 for (int k = 0; k < N; k++)
                          if (found[k]) continue;
                          Relax(s, k, cap[s][k] - flow[s][k], cost[s][k], 1);
Relax(s, k, flow[k][s], -cost[k][s], -1);
if (best == -1 || dist[k] < dist[best]) best = k;
             s = best:
        for (int k = 0; k < N; k++)
                 pi[k] = min(pi[k] + dist[k], INF);
    pair<L, L> GetMaxFlow(int s, int t)
        L totflow = 0, totcost = 0;
        while (L amt = Dijkstra(s, t))
                 totflow += amt:
                 for (int x = t; x != s; x = dad[x].first)
                          if (dad[x].second == 1)
                                   flow[dad[x].first][x] += amt;
                                   totcost += amt * cost[dad[x].first][x];
                          else
                                   flow[x][dad[x].first] -= amt;
                                   totcost -= amt * cost[x][dad[x].first];
        return make_pair(totflow, totcost);
};
```

2.4 Eulerian Path

```
struct Edge;
typedef list<Edge>::iterator iter;
struct Edge
        int next_vertex;
        iter reverse_edge;
    Edge(int next_vertex) :next_vertex(next_vertex) { }
};
const int max_vertices = ;
int num_vertices;
list<Edge> adj[max_vertices]; // adjacency list
vector<int> path;
void find_path(int v)
        while(adj[v].size() > 0)
                int vn = adj[v].front().next_vertex;
        adj[vn].erase(adj[v].front().reverse_edge);
        adj[v].pop_front();
        find_path(vn);
    path.push_back(v);
void add_edge(int a, int b)
        adj[a].push_front(Edge(b));
        iter ita = adj[a].begin();
        adj[b].push_front(Edge(a));
        iter itb = adj[b].begin();
        ita->reverse_edge = itb;
        itb->reverse_edge = ita;
```

2.5 Hopcroft-Karp Algorithm

```
#include <vector>
vector<int> g[N];
int r[N], l[N], n, m, e, a, b;
// generate g;
bool dfs(int v)
         if(vis[v]) return false;
         vis[v] = true;
         for(int u=0; u<g[v].size(); ++u)</pre>
                  \textbf{if}(!r[g[v][u]])
                            1[v]=g[v][u];
                            r[g[v][u]]=v;
         for(int u=0; u<g[v].size(); ++u)</pre>
                  if(dfs(r[g[v][u]]))
                            1[v]=g[v][u];
r[g[v][u]]=v;
                            return true:
         return false;
void hopcroft_karp()
         bool change = true;
         while (change)
                  change = false;
                  fill(vis, vis+n+1, false);
for(int i=1; i<=n; ++i)</pre>
                           if(!1[i])
                                     change |= dfs(i);
```

_

2.6 Lowest Common Ancestor

```
const int max_nodes, log_max_nodes;
int num_nodes, log_num_nodes, root;
vector<int> children[max_nodes];
// children[i] contains the children of node i int A[max_nodes][log_max_nodes+1]; // A[i][j] is
      the 2^{\circ}j-th ancestor of node i, or -1 if that ancestor does not exist int L[\max_{i}];
                             // L[i] is the distance between node i and the root
// floor of the binary logarithm of n
int lb (unsigned int n)
        if(n==0) return -1;
        int p = 0:
        if (n >= 1<<16) { n >>= 16; p += 16; }
        if (n >= 1<< 8) { n >>= 8; p += 8; }
if (n >= 1<< 4) { n >>= 4; p += 4; }
        if (n >= 1<< 2) { n >>= 2; p += 2; }
        if (n >= 1<< 1) {
        return p;
void DFS(int i, int 1)
        L[i] = 1;
        for(int j = 0; j < children[i].size(); j++)</pre>
                 DFS(children[i][j], 1+1);
int LCA(int p, int q) {
         // ensure node p is at least as deep as node q
        if(L[p] < L[q]) swap(p, q);
         // "binary search" for the ancestor of node p situated on the same level as {
m q}
        for(int i = log_num_nodes; i >= 0; i--)
                 if(L[p] - (1<<i) >= L[q])
         p = A[p][i];
        if(p == q) return p;
        // "binary search" for the LCA
for(int i = log_num_nodes; i >= 0; i--)
                 if(A[p][i] != -1 && A[p][i] != A[q][i])
                          p = A[p][i];
                          q = A[q][i];
    return A[p][0];
int main(int argc,char* argv[])
         // read num_nodes, the total number of nodes
        log_num_nodes=1b(num_nodes);
        for(int i = 0; i < num nodes; i++)</pre>
                 // read p, the parent of node i or -1 if node i is the root
        A[i][0] = p;

if(p!=-1) children[p].push_back(i);
        else root = i;
     // precompute A using dynamic programming
    for(int j = 1; j <= log_num_nodes; j++)</pre>
        for(int i = 0; i < num_nodes; i++)
    if(A[i][j-1] != -1) A[i][j] = A[A[i][j-1]][j-1];</pre>
                else A[i][j] = -1;
    // precompute L
        DFS(root, 0);
        return 0:
```

2.7 Strongly Connected Components

```
#include <memory.h>
struct edge
{
    int e, nxt;
};
int V, E;
edge e[MAXE], er[MAXE];
```

```
int sp[MAXV], spr[MAXV];
int group_cnt, group_num[MAXV];
bool v[MAXV];
int stk[MAXV];
void fill_forward(int x)
        int i;
         v[x]=true;
        for(i=sp[x];i;i=e[i].nxt)
                if(!v[e[i].e]) fill_forward(e[i].e);
        stk[++stk[0]]=x;
void fill backward(int x)
        v[x]=false;
         group_num[x]=group_cnt;
        for(i=spr[x];i;i=er[i].nxt)
                 if(v[er[i].e])
                          fill_backward(er[i].e);
void add_edge(int v1, int v2) //add edge v1->v2
        e[++E].e=v2;
        e[E].nxt=sp [v1];
        sp[v1]=E:
        er[E].e=v1;
        er[E].nxt=spr[v2];
        spr[v2]=E;
void SCC()
        int i;
        stk[0]=0;
        \texttt{memset} \; (\texttt{v}, \; \; \texttt{false}, \; \; \texttt{sizeof} \; (\texttt{v}) \; ) \; ;
        for(i=1;i<=V;i++)
                 if(!v[i])
                          fill_forward(i);
         group_cnt=0;
        for(i=stk[0];i>=1;i--)
                 if(v[stk[i]]){group_cnt++; fill_backward(stk[i]);}
```

2.8 Union-Find Set

```
struct Edge // MST
        bool operator < (const Edge &E) const{
        return this->d <E.d;
int ranks[M]; int c[N];
int Find(int x)
        while (y!=c[y])
               y=c[y];
        while (x!=c[x])
                int aux=c[x];
                c[x]=y;
                x=aux;
        return y;
void Union(int x,int y)
        if(ranks[x]>ranks[y])
                c[x]=y;
        if(ranks[x] == ranks[y])
                ranks[y]++;
```

3 Tree

3.1 Cartesian Tree

```
struct Tr
        Tr *1, *r;
        int key,pr,cnt,val,rev;
        long long sum;
        Tr(int new_key,int new_pr,int new_val)
                rev=0:
                key=new_key;
                cnt=1;
                l=r=NULL;
                pr=new_pr;
                val=new_val;
                sum=new_val;
};
#define T Tr*
T R=NULL;
int cnt(T t)
        if(!t) return 0;
        return t->cnt;
void upd_cnt(T &t)
        if(t) t->cnt=cnt(t->1)+cnt(t->r)+1;
long long sum(T t)
        if(!t) return 0;
        return t->sum:
void upd_sum(T &t)
    if(t) t->sum=sum(t->1)+sum(t->r)+t->val;
void push(T &t)
        if(t && t->rev)
                t->rev=0;
                swap(t->1,t->r);
                upd_sum(t);
                if(t->1) t->1->rev^=1;
if(t->r) t->r->rev^=1;
void split(T t,T &l,T &r,int key,int add)
                return void(l=r=NULL);
        push(t);
        upd_cnt(t);
        int current_key=add+cnt(t->1)+1;
        if(key<=current_key)</pre>
                split (t->1,1,t->1,key,add),r=t;
    else
                split(t->r,t->r,r,key,current_key),l=t;
        upd_cnt(t);
        upd_sum(t);
void merge(T &t,T 1,T r)
        push(1);
        push(r);
        if(!l || !r)
                t=1?1:r;
        else if(l->pr>r->pr)
                merge(1->r,1->r,r), t=1;
        else
                merge(r->1,1,r->1), t=r;
        upd_cnt(t);
        upd_sum(t);
```

```
void insert(T &t,T it,int add)
        push(t);
        if(!t)
                upd_cnt(t);
                return;
        upd_sum(t);
        insert(t->r, it, add+cnt(t->1)+1);
                insert(t->1,it,add);
        upd_sum(t);
        upd_cnt(t);
void print(T t)
        if(!t) return;
        print(t->1);
        cout<<t->val<<" ";
        print(t->r);
void reverse(int left,int right)
        Tr *t1, *t2, *t3;
        t1=t2=t3=NULL;
        split(R,t1,t2,left,0);
        split(t2,t2,t3,right-left+2,0);
        t2->rev^=1;
        merge(R,t1,t2);
        merge(R,R,t3);
void get_sum(int left,int right)
        Tr *t1, *t2, *t3;
        t1=t2=t3=NULL;
        split(R,t1,t2,left,0);
split(t2,t2,t3,right-left+2,0);
        cout << t2->sum << "\n";
        merge(R,t1,t2);
        merge(R,R,t3);
int n,m, q,a,b;
void example()
        ios_base::sync_with_stdio(0);
        cin.tie(0);
        freopen("reverse.in", "r", stdin);
        freopen("reverse.out", "w", stdout);
        srand(time(0));
        cin>>n>>m;
        for(int i=1;i<=n;++i)</pre>
                cin>>a;
                T it=new Tr(i,rand()+1,a);
                insert(R,it,0);
        for (int i=0; i < m; ++i)</pre>
                cin>>g>>a>>b;
                if(q) reverse(a,b);
                else get_sum(a,b);
        return 0;
```

3.2 Segment Tree

```
//Segment Tree
#include <iostream>
#define N (1<<18)

using namespace std;
//int find(vector <int>& C, int x) {return (C[x]==x) ? x : C[x]=find(C, C[x]);} C++
//int find(int x) {return (C[x]==x) ?x:C[x]=find(C[x]);}
```

```
typedef pair<int, int> ii;
ii arb[N]={{0,0}};
int n,m,a,b,v;
char type;
void update(int node,int 1,int r,int a,int b,int val,int p)
        if(a<=1 && r<=b)
                arb[node].first=val;
                arb[node].second=p;
        else
                int mid=(1+r)/2;
                if(a<=mid)
                        update(node*2,1,mid,a,b,val,p);
                if(b>mid)
                        update(2*node+1,mid+1,r,a,b,val,p);
pair<int,int> search(int node,int 1,int r,int a)
        if(a==1 && a==r)
                return arb[node];
        else
                int mid=(1+r)/2;
                ii cur:
                if(a<=mid)
                        cur=search(2*node,1,mid,a);
                        cur=search(2*node+1, mid+1, r, a);
                if(cur.second<arb[node].second)</pre>
                        return arb[node];
                else
                        return cur;
```

4 Math

4.1 Extended Euclid's Algorithm

```
#include "GcdLcm.h"

// returns d = gcd(a,b); find x, y such that d = ax + by
int extended_euclid(int a, int b, int &x, int &y) {
    int current_x = y = 0;
    int current_y = x = 1;
    while(b)
    {
        int q = a/b;
        int t = b;
        b = a&b;
        a = t;
        t = current_x; current_x = x-q*current_x; x = t;
        t = current_y; current_y = y-q*current_y; y = t;
    }
    return a;
}
```

4.2 Fast Prime Number Sieve

```
// compute prime numbers to N really fast (Sieve)
#define N 10000100
vector<int> primes;
char p[N/8];

void GeneratePrimes()
{
    primes.push_back(2);
    int i,;;
    for(i=1;((i*i)<<1)+(i<<1)<N;++i)
    {
        if((p[i>>3]&(1<<(i&7)))==0)</pre>
```

4.3 Fast Fourier Transform

```
struct cpx
        cpx(){}
        cpx(double aa): a(aa){}
        cpx(double aa, double bb): a(aa), b(bb){}
        double a;
        double b;
        double modsq(void) const{ return a*a+b*b; }
        cpx bar(void) const {return cpx(a,-b);}
cpx b[N+100],c[N+100],B[N+100],C[N+100];
int a[N+100], int x[N+100];
double coss[N+100], sins[N+100];
cpx operator +(cpx a,cpx b) {
                                return cpx(a.a+b.a,a.b+b.b); }
cpx operator *(cpx a,cpx b) {
                                return cpx(a.a*b.a-a.b*b.b,a.a*b.b+a.b*b.a); }
const double two_pi = 4 * acos(0);
void FFT(cpx *in,cpx *out,int step,int size,int dir)
        if(size<1) return;</pre>
        if(size==1)
                out[0]=in[0];
        FFT(in,out,step*2,size/2,dir);
        FFT(in+step,out+size/2,step*2,size/2,dir);
        for(int i=0;i<size/2;++i)</pre>
                cpx even=out[i];
               cpx odd=out[i+size/2];
out[i] = even+EXP(i*step,dir)*odd;
                out[i+size/2]=even+EXP((i+size/2)*step,dir)*odd;
void exemple
        for(int i=0;i<=N;++i)</pre>
                coss[i]=cos(two_pi*i/N);
                sins[i]=sin(two_pi*i/N);
        while (scanf ("%d", &n) ==1)
                fill(x,x+N+100,0);
                fill(a,a+N+100,0);
                for (int i=0; i < n; ++i)</pre>
                        scanf("%d",&p);
                       x[p]=1;
                for(int i=0;i<N+100;++i)</pre>
                       b[i] = cpx(x[i],0);
                scanf("%d", &m);
                for(int i=0;i<m;++i)</pre>
                       scanf("%d",&a[i]);
```

```
FFT(b,B,1,N,1);
    for(int i=0;i<N;++i)
        C[i=B[i]*B[i];
    FFT(C,c,1,N,-1);
    for(int i=0;i<N;++i)
        c[i]=c[i]/N;
    int cnt=0;
    for(int i=0;i<16;++i)
        cout<<c[i].a<<"";
    for(int i=0;i<m;+i)
        if(c[a[i]].a>0.5 || x[a[i]])
        cnt++;
    printf("%d\n",cnt);
}
```

4.4 Gauss-Jordan Elimination

```
Stanford notebook
GaussJordan Algorithm (elimination with full pivoting)
(1) solving systems of linear equations (AX=B)
(2) inverting matrices (AX=I)
(3) computing determinants of square matrices
Running time: O(n^3)

INPUT: a[][] = an nxn matrix
b[][] = an nxm matrix
                  = an nxm matrix (stored in b[][])
                    A^{-1} = an nxn matrix (stored in a[][])
                    returns determinant of a[][]
const double EPS = 1e-10;
typedef vector<int> VI;
typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;
T GaussJordan(VVT &a, VVT &b)
         const int n = a.size();
         const int m = b[0].size();
         VI irow(n), icol(n), ipiv(n);
    for (int i = 0; i < n; i++)
         int pj = -1, pk = -1;
    for (int j = 0; j < n; j++)</pre>
                           if (!ipiv[j])
                                     for (int k = 0; k < n; k++)
                                              if (!ipiv[k])
                                                      if (pj == -1 || fabs(a[j][k]) > fabs(a[pj][pk])) { pj
                                                             = j; pk = k; }
                  if (fabs(a[pj][pk]) < EPS)</pre>
                            cerr << "Matrix is singular." << endl;</pre>
                           exit(0);
         ipiv[pk]++;
         swap(a[pj], a[pk]);
         swap(b[pj], b[pk]);
         if (pj != pk) det *= -1;
irow[i] = pj;
icol[i] = pk;
         T c = 1.0 / a[pk][pk];
det *= a[pk][pk];
         a[pk][pk] = 1.0;
         for (int p = 0; p < n; p++)
                 a[pk][p] *= c;
         for (int p = 0; p < m; p++)
                 b[pk][p] *= c;
         for (int p = 0; p < n; p++)
                  if (p != pk)
                           c = a[p][pk];
                           a[p][pk] = 0;

for (int q = 0; q < n; q++)

a[p][q] -= a[pk][q] * c;

for (int q = 0; q < m; q++)
                                    b[p][q] -= b[pk][q] * c;
```

```
for (int p = n-1; p >= 0; p--)
                if (irow[p] != icol[p])
                        for (int k = 0; k < n; k++)
                                swap(a[k][irow[p]], a[k][icol[p]]);
        return det;
int main()
        const int n = 4;
        const int m = 2;
        double A[n][n] = \{ \{1,2,3,4\}, \{1,0,1,0\}, \{5,3,2,4\}, \{6,1,4,6\} \};
        double B[n][m] = \{ \{1,2\}, \{4,3\}, \{5,6\}, \{8,7\} \};
        VVT a(n), b(n);
        for (int i = 0; i < n; i++)
                a[i] = VT(A[i], A[i] + n);
                b[i] = VT(B[i], B[i] + m);
        double det = GaussJordan(a, b);
        // expected: 60
        cout << "Determinant: " << det << endl;</pre>
        // expected: -0.233333 0.166667 0.133333 0.0666667
                    0.166667 0.166667 0.333333 -0.333333
                     0.233333 0.833333 -0.133333 -0.0666667
        // 0.05 -0.75 -0.1 0.2 cout << "Inverse: " << endl;
        for (int i = 0; i < n; i++)
                for (int j = 0; j < n; j++)
                       cout << a[i][j] << ' ';
                cout << endl;</pre>
        // expected: 1.63333 1.3
                     -0.166667 0.5
                     2.36667 1.7
                     -1.85 -1.35
        cout << "Solution: " << endl;</pre>
        for (int i = 0; i < n; i++)</pre>
                cout << endl;
```

4.5 GCD and LCM

```
// return a8b
int mod(int a, int b)
{
    return ((a%b)+b)%b;
}

// computes gcd(a,b)
int gcd(int a, int b)
{
    int tmp;
    while(b)
    {
        a %= b;
        tmp = a;
        a = b;
        b = tmp;
    }
    return a;
}

// computes lcm(a,b)
int lcm(int a, int b)
{
    return a/gcd(a,b)*b;
}
```

4.6 Modular Linear Equation Solver

```
// Stanford Notebook
#include <vector>
#include "ExtendedEuclid.h"
// find all solutions to ax = b \pmod{n}
vector<int> modular_linear_equation_solver(int a, int b, int n)
        vector<int> sol;
        int d = extended_euclid(a, n, x, y);
        if(!(b%d)) {
                x = mod(x%(b/d), n);
                for(int i=0; i < d; ++i)
                        sol.push_back(mod(x + i*(n/d),n));
        return sol;
// computes b such tath ab = 1 \pmod{n}, returs -1 on failure
int mod_inverse(int a, int n)
        int d = extended_euclid(a, n, x, y);
        if(d>1) return -1;
        return mod(x,n);
// computes x and y such that ax + by = c; on failure, x = y = -1
void linear_diophantine(int a, int b, int c, int &x, int &y)
        int d = \gcd(a,b);
        if (c%d) x = y = -1;
                x = c/d * mod_inverse(a/d,b/d);
                y = (c-a*x)/b;
```

5 Strings

5.1 Aho-Corasick Algorithm

```
Implementation - Benoit Chabod
Aho Corasick algorithm
struct node
        int f;
        map<char, int> q;
        vector<short> out;
        node(int fail = -1): f(fail) {}
};
vector<node> nodes;
void add_str(const string & s, int num)
        int cur = 0;
        int n = s.size();
        for (int i = 0; i < n; i++)
                auto it = nodes[cur].g.find(s[i]);
                if(it == nodes[cur].g.end())
                        nodes[cur].g[s[i]] = nodes.size();
                        cur = nodes.size();
                        nodes.push_back(node());
                else
                        cur = it->second:
        nodes[cur].out.push_back(num);
void init fail()
        int cur = 0;
```

```
queue<int> q;
      q.push(cur);
   while( !q.empty() )
      cur = q.front();
      map<char, int>::iterator it;
      for(it = nodes[cur].g.begin(); it != nodes[cur].g.end(); it++)
             int child = it->second;
int pfail = nodes[cur].f;
char ch = it->first;
              map<char, int>::iterator f;
              pfail = nodes[pfail].f;
              nodes[child].f = (pfail == -1)? 0 : f->second;
              pfail = nodes[child].f;
              nodes[child].out.insert(nodes[child].out.end(), nodes[pfail].out.begin(), nodes[pfail].
                  out.end());
              q.push(child);
      q.pop();
// Usage
void usage()
       nodes.push_back(node());
      for [each word] add_str(word,i)
       for [each letter]
              map<char, int>::iterator f;
             if( cur == -1 )
                     cur = 0;
                    continue:
      cur = f->second;
      for(auto v : nodes[cur].out)
              // Word v was found
```

5.2 Knuth-Morris-Pratt Algorithm

```
/ *
KMP/Pi function
Note: cin >> (s+1) (the operations in the pi-function start at 1)
void preKmp()
        int k;
        k=kmpNext[1]=0;
        for(int i=2;i<=n;++i)</pre>
                 while(k && p[k+1]!=p[i]) k=kmpNext[k];
                 if(p[k+1] == p[i])
                 kmpNext[i]=k;
void KMP()
        int k=0;
        for (int i=1; i <= m; ++i)</pre>
                 while (k \& \& p[k+1]!=s[i])
                         k=kmpNext[k];
                 if(p[k+1]==s[i])
                         k++;
                 if(k==n)
                          // here we have a match
                         k=kmpNext[k];
```

5.3 Suffix Array

```
//Suffix Array
struct SuffixArray
        const int L:
        string s:
        vector<vector<int> > P;
        vector<pair<pair<int,int>,int> > M;
        SuffixArray(const string &s): L(s.length()), s(s), P(1, vector<int>(L, 0)), M(L)
                 for (int i = 0; i < L; i++)
                P.push_back(vector<int>(L, 0));
                         for (int i = 0; i < L; i++)
                                  \texttt{M[i]} = \texttt{make\_pair(make\_pair(P[level-1][i], i + skip < L ? P[level-1][i])}
                                       + skip] : -1000), i);
                         sort(M.begin(), M.end());
for (int i = 0; i < L; i++)
    P[level][M[i].second] = (i > 0 && M[i].first == M[i-1].first) ? P[
                                        level] [M[i-1].second] : i;
    vector<int> GetSuffixArray()
        return P.back();
        // returns the length of the longest common prefix of s[i...L-1] and s[j...L-1]
        int LongestCommonPrefix(int i, int j)
                 int len = 0;
                 if (i == j) return L - i;
                 for (int k = P.size() - 1; k >= 0 && i < L && j < L; k--)
                         if (P[k][i] == P[k][j])
                              i += 1 << k;
                              j += 1 << k;
                              len += 1 << k;
                 return len;
};
int main()
         // bobocel is the O'th suffix
           obocel is the 5'th suffix
             bocel is the 1'st suffix
              ocel is the 6'th suffix cel is the 2'nd suffix
                el is the 3'rd suffix
                 1 is the 4'th suffix
        SuffixArray suffix("bobocel");
        vector<int> v = suffix.GetSuffixArray();
// Expected output: 0 5 1 6 2 3 4
        for (int i = 0; i < v.size(); i++)</pre>
                cout << v[i] << " ";
        cout << endl;
        cout << suffix.LongestCommonPrefix(0, 2) << endl;</pre>
```

6 Techniques

6.1 Various algorithm techniques

Recursion Divide and conquer

```
Finding interesting points in N log N
Greedy algorithm
        Scheduling
        Max contigous subvector sum
        Invariants
        Huffman encoding
Graph theory
        Dynamic graphs (extra book-keeping)
        Breadth first search
        Depth first search
        * Normal trees / DFS trees
       Dijkstra's algoritm
MST: Prim's algoritm
        Bellman-Ford
        Konig's theorem and vertex cover
        Min-cost max flow
        Lovasz toggle
        Maximal matching, general graphs
        Hopcroft-Karp
        Hall's marriage theorem
        Graphical sequences
        Floyd-Warshall
        Eulercvkler
        Flow networks
        * Augumenting paths
        * Edmonds-Karp
        Bipartite matching
        Min. path cover
        Topological sorting
        Strongly connected components
        Cutvertices, cutedges och biconnected components
        Edge coloring
        Vertex coloring
        * Bipartite graphs (=> trees)
        * 3^n (special case of set cover)
        Diameter and centroid
        K'th shortest path
        Shortest cycle
Dynamic programmering
        Knapsack
        Coin change
        Longest common subsequence
        Longest increasing subsequence
        Number of paths in a dag
        Shortest path in a dag
        Dynprog over intervals
        Dynprog over subsets
        Dynprog over probabilities
        Dynprog over trees
        3^n set cover
        Divide and conquer
        Knuth optimization
        Convex hull optimizations
        RMQ (sparse table a.k.a 2^k-jumps)
        Bitonic cycle
        Log partitioning (loop over most restricted)
Combinatorics
        Computation of binomial coefficients
        Pigeon-hole principle
        Inclusion/exclusion
        Catalan number
        Pick's theorem
Number theory
        Integer parts
        Divisibility
        Euklidean algorithm
        Modular arithmetic
        * Modular multiplication
        * Modular inverses
        * Modular exponentiation by squaring
        Chinese remainder theorem
        Fermat's small theorem
        Euler's theorem
        Phi function
        Frobenius number
        Quadratic reciprocity
        Pollard-Rho
        Miller-Rabin
        Hensel lifting
        Vieta root jumping
Game theory
       Combinatorial games
        Game trees
        Mini-max
        Nim
        Games on graphs
        Games on graphs with loops
```

Bipartite games without repetition

```
INSA Lyon
```

```
Probability theory
Optimization
         Binary search
         Ternary search
        Unimodality and convex functions
Binary search on derivative
Numerical methods
         Numeric integration
        Newton's method
Root-finding with binary/ternary search
        Golden section search
Matrices
        Gaussian elimination
Exponentiation by squaring
Sorting
        Radix sort
Geometry
         Coordinates and vectors
         * Cross product
         * Scalar product
         Convex hull
        Polygon cut
         Closest pair
        Coordinate-compression
         Ouadtrees
         KD-trees
        All segment-segment intersection
Sweeping
         Discretization (convert to events and sweep)
         Angle sweeping
         Line sweeping
```

General games without repetition

Alpha-beta pruning

```
Strings
         Longest common substring
          Palindrome subsequences
          Knuth-Morris-Pratt
          Rolling polynom hashes
          Suffix array
          Suffix tree
         Aho-Corasick
Manacher's algorithm
Letter position lists
Combinatorial search
          Meet in the middle
         Brute-force with pruning
          Best-first (A*)
         Bidirectional search
          Iterative deepening DFS / A*
Data structures
          LCA (2^k-jumps in trees in general)
          Pull/push-technique on trees
         Heavy-light decomposition
         Centroid decomposition
         Lazy propagation
          Self-balancing trees
         Self-balancing trees
Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
Monotone queues / monotone stacks / sliding queues
Sliding queue using 2 stacks
         Persistent segment tree
```

Discrete second derivatives

| f(n) = O(g(n)) | iff \exists positive c, n_0 such that | $n = n(n+1)$ $n = n(n+1)(2n+1)$ $n = n(2(n+1))^2$ |
|--|---|--|
| | $0 \le f(n) \le cg(n) \ \forall n \ge n_0.$ | $\sum_{i=1}^{n} i = \frac{n(n+1)}{2}, \sum_{i=1}^{n} i^2 = \frac{n(n+1)(2n+1)}{6}, \sum_{i=1}^{n} i^3 = \frac{n^2(n+1)^2}{4}.$ |
| $f(n) = \Omega(g(n))$ | iff \exists positive c, n_0 such that $f(n) \geq cg(n) \geq 0 \ \forall n \geq n_0$. | In general: |
| $f(n) = \Theta(g(n))$ | iff $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$. | $\sum_{i=1}^{n} i^{m} = \frac{1}{m+1} \left[(n+1)^{m+1} - 1 - \sum_{i=1}^{n} \left((i+1)^{m+1} - i^{m+1} - (m+1)i^{m} \right) \right]$ |
| f(n) = o(g(n)) | iff $\lim_{n\to\infty} f(n)/g(n) = 0$. | $\sum_{i=1}^{n-1} i^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k n^{m+1-k}.$ |
| $\lim_{n \to \infty} a_n = a$ | iff $\forall \epsilon > 0$, $\exists n_0$ such that $ a_n - a < \epsilon$, $\forall n \ge n_0$. | Geometric series: |
| $\sup S$ | least $b \in \mathbb{R}$ such that $b \geq s$, $\forall s \in S$. | $\sum_{i=0}^{n} c^{i} = \frac{c^{n+1} - 1}{c - 1}, c \neq 1, \sum_{i=0}^{\infty} c^{i} = \frac{1}{1 - c}, \sum_{i=1}^{\infty} c^{i} = \frac{c}{1 - c}, c < 1,$ |
| $\inf S$ | greatest $b \in \mathbb{R}$ such that $b \le s$, $\forall s \in S$. | $\sum_{i=0}^{n} ic^{i} = \frac{nc^{n+2} - (n+1)c^{n+1} + c}{(c-1)^{2}}, c \neq 1, \sum_{i=0}^{\infty} ic^{i} = \frac{c}{(1-c)^{2}}, c < 1.$ |
| $ \liminf_{n \to \infty} a_n $ | $\lim_{n \to \infty} \inf \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$ | Harmonic series: $n = n + n = n + n = n = n = n = n = n = $ |
| $\limsup_{n \to \infty} a_n$ | $\lim_{n \to \infty} \sup \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$ | $H_n = \sum_{i=1}^n \frac{1}{i}, \qquad \sum_{i=1}^n iH_i = \frac{n(n+1)}{2}H_n - \frac{n(n-1)}{4}.$ |
| $\binom{n}{k}$ | Combinations: Size k subsets of a size n set. | $\sum_{i=1}^{n} H_i = (n+1)H_n - n, \sum_{i=1}^{n} {i \choose m} H_i = {n+1 \choose m+1} \left(H_{n+1} - \frac{1}{m+1} \right).$ |
| $\begin{bmatrix} n \\ k \end{bmatrix}$ | Stirling numbers (1st kind): Arrangements of an n element set into k cycles. | 1. $\binom{n}{k} = \frac{n!}{(n-k)!k!}$, 2. $\sum_{k=0}^{n} \binom{n}{k} = 2^{n}$, 3. $\binom{n}{k} = \binom{n}{n-k}$, |
| $\binom{n}{k}$ | Stirling numbers (2nd kind): Partitions of an n element set into k non-empty sets. | $4. \binom{n}{k} = \frac{n}{k} \binom{n-1}{k-1}, \qquad \qquad 5. \binom{n}{k} = \binom{n-1}{k} + \binom{n-1}{k-1}, \\ 6. \binom{n}{m} \binom{m}{k} = \binom{n}{k} \binom{n-k}{m-k}, \qquad \qquad 7. \sum_{k=0}^{n} \binom{r+k}{k} = \binom{r+n+1}{n},$ |
| $\langle {n \atop k} \rangle$ | 1st order Eulerian numbers: Permutations $\pi_1\pi_2\pi_n$ on $\{1,2,,n\}$ with k ascents. | 8. $\sum_{k=0}^{n} {k \choose m} = {n+1 \choose m+1},$ 9. $\sum_{k=0}^{n} {r \choose k} {s \choose n-k} = {r+s \choose n},$ |
| $\langle\!\langle {n \atop k} \rangle\!\rangle$ | 2nd order Eulerian numbers. | 10. $\binom{n}{k} = (-1)^k \binom{k-n-1}{k}$, 11. $\binom{n}{1} = \binom{n}{n} = 1$, |
| C_n | Catalan Numbers: Binary trees with $n+1$ vertices. | 12. $\binom{n}{2} = 2^{n-1} - 1$, 13. $\binom{n}{k} = k \binom{n-1}{k} + \binom{n-1}{k-1}$, |
| $14. \begin{bmatrix} n \\ 1 \end{bmatrix} = (n-1)$ | 15. $\begin{bmatrix} n \\ 2 \end{bmatrix} = (n - 1)^n$ | $16. \begin{bmatrix} n \\ n \end{bmatrix} = 1, \qquad \qquad 17. \begin{bmatrix} n \\ k \end{bmatrix} \ge \begin{Bmatrix} n \\ k \end{Bmatrix},$ |
| 18. $\begin{bmatrix} n \\ k \end{bmatrix} = (n-1)$ | $\binom{n-1}{k} + \binom{n-1}{k-1}, 19. \ \binom{n}{n-1}$ | |
| $22. \left\langle {n \atop 0} \right\rangle = \left\langle {n \atop n-1} \right\rangle$ | $\binom{n}{-1} = 1,$ 23. $\binom{n}{k} = \binom{n}{k}$ | $\binom{n}{n-1-k}$, $24. \left\langle \binom{n}{k} \right\rangle = (k+1) \left\langle \binom{n-1}{k} \right\rangle + (n-k) \left\langle \binom{n-1}{k-1} \right\rangle$, |
| 25. $\left\langle {0\atop k}\right\rangle = \left\{ {1\atop 0}\right\}$ | if $k = 0$, otherwise 26. $\begin{cases} r \\ 1 \end{cases}$ | $\binom{n}{2} = 2^n - n - 1,$ 27. $\binom{n}{2} = 3^n - (n+1)2^n + \binom{n+1}{2},$ |
| 28. $x^n = \sum_{k=0}^n \binom{n}{k}$ | $\left\langle {x+k \choose n}, \qquad $ 29. $\left\langle {n \atop m} \right\rangle = \sum_{k=1}^m$ | |
| | | 32. $\left\langle \left\langle \begin{array}{c} n \\ 0 \end{array} \right\rangle = 1,$ 33. $\left\langle \left\langle \begin{array}{c} n \\ n \end{array} \right\rangle = 0$ for $n \neq 0$, |
| $34. \; \left\langle \!\! \left\langle \!\! \begin{array}{c} n \\ k \end{array} \!\! \right\rangle = (k + 1)^n$ | -1 $\left\langle \left\langle \begin{pmatrix} n-1 \\ k \end{pmatrix} \right\rangle + (2n-1-k) \left\langle \left\langle \begin{pmatrix} n-1 \\ k \end{pmatrix} \right\rangle \right\rangle$ | |
| $36. \left\{ \begin{array}{c} x \\ x-n \end{array} \right\} = \sum_{k}^{n} \left\{ \begin{array}{c} x \\ x \end{array} \right\}$ | $\sum_{k=0}^{n} \left\langle \!\! \left\langle n \atop k \right\rangle \!\! \right\rangle \!\! \binom{x+n-1-k}{2n},$ | 37. $\binom{n+1}{m+1} = \sum_{k} \binom{n}{k} \binom{k}{m} = \sum_{k=0}^{n} \binom{k}{m} (m+1)^{n-k},$ |

38.
$$\binom{n+1}{m+1} = \sum_{k} \binom{n}{k} \binom{k}{m} = \sum_{k=0}^{n} \binom{k}{m} n^{\frac{n-k}{m}} = n! \sum_{k=0}^{n} \frac{1}{k!} \binom{k}{m}$$
, 39. $\binom{x}{x-n} = \sum_{k=0}^{n} \binom{n}{k} \binom{x+k}{2n}$, 40. $\binom{n}{m} = \sum_{k} \binom{n}{k} \binom{k+1}{m+1} (-1)^{n-k}$, 41. $\binom{n}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, 42. $\binom{m+n+1}{m} = \sum_{k=0}^{m} k \binom{n+k}{k}$, 43. $\binom{m+n+1}{m} = \sum_{k=0}^{m} k(n+k) \binom{n+k}{k}$, 44. $\binom{n}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, 45. $\binom{n-m}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, for $n \ge m$,

$$\mathbf{46.} \ \, \left\{ \begin{matrix} n \\ n-m \end{matrix} \right\} = \sum_{k} \binom{m-n}{m+k} \binom{m+n}{n+k} \binom{m+k}{k}, \qquad \mathbf{47.} \ \, \left[\begin{matrix} n \\ n-m \end{matrix} \right] = \sum_{k} \binom{m-n}{m+k} \binom{m+n}{n+k} \binom{m+k}{k},$$

48.
$${n \choose \ell+m} {\ell+m \choose \ell} = \sum_{k} {k \choose \ell} {n-k \choose m} {n \choose k},$$
 49.
$${n \choose \ell+m} {\ell+m \choose \ell} = \sum_{k} {k \choose \ell} {n-k \choose m} {n \choose k}.$$

$$\mathbf{49.} \begin{bmatrix} n \\ \ell + m \end{bmatrix} \begin{pmatrix} \ell + m \\ \ell \end{pmatrix} = \sum_{k} \begin{bmatrix} k \\ \ell \end{bmatrix} \begin{bmatrix} n - k \\ m \end{bmatrix} \begin{pmatrix} n \\ k \end{pmatrix}.$$

Every tree with nvertices has n-1edges.

Kraft inequality: If the depths of the leaves of a binary tree are

$$d_1, \dots, d_n$$
:

$$\sum_{i=1}^{n} 2^{-d_i} \le 1,$$

and equality holds only if every internal node has 2 sons.

Recurrences

Master method:

$$T(n) = aT(n/b) + f(n), \quad a \ge 1, b > 1$$

If $\exists \epsilon > 0$ such that $f(n) = O(n^{\log_b a - \epsilon})$

$$T(n) = \Theta(n^{\log_b a}).$$

If
$$f(n) = \Theta(n^{\log_b a})$$
 then $T(n) = \Theta(n^{\log_b a} \log_2 n)$.

If $\exists \epsilon > 0$ such that $f(n) = \Omega(n^{\log_b a + \epsilon})$, and $\exists c < 1$ such that $af(n/b) \leq cf(n)$ for large n, then

$$T(n) = \Theta(f(n)).$$

Substitution (example): Consider the following recurrence

$$T_{i+1} = 2^{2^i} \cdot T_i^2, \quad T_1 = 2.$$

Note that T_i is always a power of two. Let $t_i = \log_2 T_i$. Then we have

$$t_{i+1} = 2^i + 2t_i, \quad t_1 = 1.$$

Let $u_i = t_i/2^i$. Dividing both sides of the previous equation by 2^{i+1} we get

$$\frac{t_{i+1}}{2^{i+1}} = \frac{2^i}{2^{i+1}} + \frac{t_i}{2^i}$$

Substituting we find

$$u_{i+1} = \frac{1}{2} + u_i, \qquad u_1 = \frac{1}{2},$$

which is simply $u_i = i/2$. So we find that T_i has the closed form $T_i = 2^{i2^{i-1}}$. Summing factors (example): Consider the following recurrence

$$T(n) = 3T(n/2) + n$$
, $T(1) = 1$.

Rewrite so that all terms involving Tare on the left side

$$T(n) - 3T(n/2) = n.$$

Now expand the recurrence, and choose a factor which makes the left side "telescope"

$$1(T(n) - 3T(n/2) = n)$$

$$3(T(n/2) - 3T(n/4) = n/2)$$

$$\vdots \quad \vdots \quad \vdots$$

$$3^{\log_2 n - 1}(T(2) - 3T(1) = 2)$$

Let $m = \log_2 n$. Summing the left side we get $T(n) - 3^m T(1) = T(n) - 3^m =$ $T(n) - n^k$ where $k = \log_2 3 \approx 1.58496$.

Summing the right side we get
$$\sum_{i=0}^{m-1} \frac{n}{2^i} 3^i = n \sum_{i=0}^{m-1} \left(\frac{3}{2}\right)^i.$$

Let
$$c = \frac{3}{2}$$
. Then we have
$$n \sum_{i=0}^{m-1} c^i = n \left(\frac{c^m - 1}{c - 1} \right)$$
$$= 2n(c^{\log_2 n} - 1)$$
$$= 2n(c^{(k-1)\log_c n} - 1)$$
$$= 2n^k - 2n.$$

and so $T(n) = 3n^k - 2n$. Full history recurrences can often be changed to limited history ones (example): Consider

$$T_i = 1 + \sum_{j=0}^{i-1} T_j, \quad T_0 = 1.$$

Note that

$$T_{i+1} = 1 + \sum_{j=0}^{i} T_j.$$

Subtracting we find

$$T_{i+1} - T_i = 1 + \sum_{j=0}^{i} T_j - 1 - \sum_{j=0}^{i-1} T_j$$

= T_i .

And so $T_{i+1} = 2T_i = 2^{i+1}$.

Generating functions:

- 1. Multiply both sides of the equation by x^i .
- 2. Sum both sides over all i for which the equation is valid.
- 3. Choose a generating function G(x). Usually $G(x) = \sum_{i=0}^{\infty} x^i g_i$.
- 3. Rewrite the equation in terms of the generating function G(x).
- 4. Solve for G(x).
- 5. The coefficient of x^i in G(x) is q_i . Example:

$$g_{i+1} = 2g_i + 1, \quad g_0 = 0.$$

$$\sum_{i \geq 0} \operatorname{Multiply} \text{ and sum:} \\ \sum_{i \geq 0} 2g_i x^i + \sum_{i \geq 0} x^i.$$

We choose $G(x) = \sum_{i \geq 0} x^i g_i$. Rewrite in terms of G(x):

$$\frac{G(x) - g_0}{x} = 2G(x) + \sum_{i \ge 0} x^i.$$

Simplify

$$\frac{G(x)}{x} = 2G(x) + \frac{1}{1-x}.$$

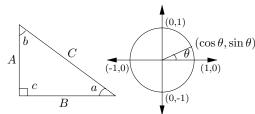
Solve for
$$G(x)$$
:

$$G(x) = \frac{x}{(1-x)(1-2x)}.$$

Expand this using partial fractions:
$$G(x) = x \left(\frac{2}{1 - 2x} - \frac{1}{1 - x} \right)$$
$$= x \left(2 \sum_{i \geq 0} 2^i x^i - \sum_{i \geq 0} x^i \right)$$
$$= \sum_{i \geq 0} (2^{i+1} - 1) x^{i+1}.$$

So
$$g_i = 2^i - 1$$
.

| 1 | $n \sim 0.17100$, | € ~ 2.1 | 1020, $I \sim 0.01121$, $\varphi = \frac{1}{2} \sim$ | 1.01000, $\psi = \frac{1}{2} \sim 0.01000$ |
|-------------------------------------|--------------------|----------------|--|---|
| i | 2^i | p_i | General | Probability |
| 1 | 2 | 2 | Bernoulli Numbers ($B_i = 0$, odd $i \neq 1$): | Continuous distributions: If |
| 2 | 4 | 3 | $B_0 = 1, B_1 = -\frac{1}{2}, B_2 = \frac{1}{6}, B_4 = -\frac{1}{30},$ | $\Pr[a < X < b] = \int_{a}^{b} p(x) dx,$ |
| 3 | 8 | 5 | $B_6 = \frac{1}{42}, B_8 = -\frac{1}{30}, B_{10} = \frac{5}{66}.$ | J a |
| 4 | 16 | 7 | Change of base, quadratic formula: | then p is the probability density function of X . If |
| 5 | 32 | 11 | $\log_b x = \frac{\log_a x}{\log_a b}, \qquad \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$ | $\Pr[X < a] = P(a),$ |
| 6 | 64 | 13 | 34 | then P is the distribution function of X . If |
| 7 | 128 | 17 | Euler's number e: | P and p both exist then |
| 8 | 256 | 19 | $e = 1 + \frac{1}{2} + \frac{1}{6} + \frac{1}{24} + \frac{1}{120} + \cdots$ | $P(a) = \int_{-a}^{a} p(x) dx.$ |
| 9 | 512 | 23 | $\lim_{n\to\infty} \left(1+\frac{x}{n}\right)^n = e^x.$ | $J-\infty$ |
| 10 | 1,024 | 29 | $(1+\frac{1}{x})^n < e < (1+\frac{1}{x})^{n+1}$. | Expectation: If X is discrete |
| 11 | 2,048 | 31 | (11) (11) | $E[g(X)] = \sum_{x} g(x) \Pr[X = x].$ |
| 12 | 4,096 | 37 | $\left(1 + \frac{1}{n}\right)^n = e - \frac{e}{2n} + \frac{11e}{24n^2} - O\left(\frac{1}{n^3}\right).$ | If X continuous then |
| 13 | 8,192 | 41 | Harmonic numbers: | |
| 14 | 16,384 | 43 | $1, \frac{3}{2}, \frac{11}{6}, \frac{25}{12}, \frac{137}{60}, \frac{49}{20}, \frac{363}{140}, \frac{761}{280}, \frac{7129}{2520}, \dots$ | $\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x)p(x) dx = \int_{-\infty}^{\infty} g(x) dP(x).$ |
| 15 | 32,768 | 47 | / 2/ 6/ 12/ 60/ 20/ 140/ 280/ 2520/ | Variance, standard deviation: |
| 16 | 65,536 | 53 | $ \ln n < H_n < \ln n + 1, $ | $VAR[X] = E[X^2] - E[X]^2,$ |
| 17 | 131,072 | 59 | $H_n = \ln n + \gamma + O\left(\frac{1}{n}\right).$ | $\sigma = \sqrt{\text{VAR}[X]}.$ |
| 18 | 262,144 | 61 | (10) | For events A and B : |
| 19 | 524,288 | 67 | Factorial, Stirling's approximation: | $\Pr[A \vee B] = \Pr[A] + \Pr[B] - \Pr[A \wedge B]$ |
| 20 | 1,048,576 | 71 | $1, 2, 6, 24, 120, 720, 5040, 40320, 362880, \dots$ | $\Pr[A \wedge B] = \Pr[A] \cdot \Pr[B],$ |
| 21 | 2,097,152 | 73 | $-(n)^n$ | iff A and B are independent. |
| 22 | 4,194,304 | 79 | $n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta\left(\frac{1}{n}\right)\right).$ | $\Pr[A B] = \frac{\Pr[A \land B]}{\Pr[B]}$ |
| 23 | 8,388,608 | 83 | Ackermann's function and inverse: | |
| 24 | 16,777,216 | 89 | $a(i,j) = \begin{cases} 2^j & i = 1\\ a(i-1,2) & j = 1\\ a(i-1,a(i,j-1)) & i,j \ge 2 \end{cases}$ | For random variables X and Y : $E[X \cdot Y] = E[X] \cdot E[Y],$ |
| 25 | 33,554,432 | 97 | $a(i,j) = \begin{cases} a(i-1,2) & j=1\\ a(i-1,a(i-i-1)) & i \neq 2 \end{cases}$ | if X and Y are independent. |
| 26 | 67,108,864 | 101 | | $\mathrm{E}[X+Y]=\mathrm{E}[X]+\mathrm{E}[Y],$ |
| 27 | 134,217,728 | 103 | $\alpha(i) = \min\{j \mid a(j,j) \ge i\}.$ | $\operatorname{E}[cX] = c\operatorname{E}[X].$ |
| 28 | 268,435,456 | 107 | Binomial distribution: | Bayes' theorem: |
| 29 | 536,870,912 | 109 | $\Pr[X=k] = \binom{n}{k} p^k q^{n-k}, \qquad q = 1 - p,$ | |
| 30 | 1,073,741,824 | 113 | | $\Pr[A_i B] = \frac{\Pr[B A_i]\Pr[A_i]}{\sum_{j=1}^n \Pr[A_j]\Pr[B A_j]}.$ |
| 31 | 2,147,483,648 | 127 | $E[X] = \sum_{k=1}^{n} k \binom{n}{k} p^k q^{n-k} = np.$ | Inclusion-exclusion: |
| 32 | 4,294,967,296 | 131 | k=1 Poisson distribution: | $\Pr\left[\bigvee_{i=1}^{n} X_i\right] = \sum_{i=1}^{n} \Pr[X_i] +$ |
| | Pascal's Triangl | e | | $\begin{bmatrix} \mathbf{V} & \mathbf{I} & \mathbf{I} \\ i & \mathbf{I} \end{bmatrix} \sum_{i=1}^{r} \mathbf{I} \begin{bmatrix} \mathbf{I} & \mathbf{I} \end{bmatrix}$ |
| | 1 | | $\Pr[X = k] = \frac{e^{-\lambda} \lambda^k}{k!}, E[X] = \lambda.$ | $\sum_{k=1}^{n} (x_k)^{k+1} \sum_{k=1}^{n} \sum_{k=1}^{n} [A, Y_k]$ |
| 11 | | | Normal (Gaussian) distribution: | $\sum_{k=2}^{n} (-1)^{k+1} \sum_{i_i < \dots < i_k} \Pr\left[\bigwedge_{j=1}^{k} X_{i_j}\right].$ |
| 1 2 1 | | | $p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}, E[X] = \mu.$ | Moment inequalities: |
| 1 3 3 1 | | | $\sqrt{2\pi\sigma}$ The "coupon collector": We are given a | $\Pr\left[X \ge \lambda \operatorname{E}[X]\right] \le \frac{1}{\lambda},$ |
| 1 4 6 4 1 1 5 10 10 5 1 | | | random coupon each day, and there are n | ^ _ |
| 1 6 15 20 15 6 1 | | | different types of coupons. The distribu- | $\Pr\left[\left X - \mathrm{E}[X]\right \ge \lambda \cdot \sigma\right] \le \frac{1}{\sqrt{2}}.$ |
| | | | tion of coupons is uniform. The expected | Geometric distribution: |
| 1 7 21 35 35 21 7 1 | | | number of days to pass before we to collect all n types is | $\Pr[X = k] = pq^{k-1}, \qquad q = 1 - p,$ |
| 1 8 28 56 70 56 28 8 1 | | | nH_n . | \sim |
| 1 9 36 84 126 126 84 36 9 1 | | | ····n. | $E[X] = \sum_{k=1}^{\infty} kpq^{k-1} = \frac{1}{p}.$ |
| 1 10 45 120 210 252 210 120 45 10 1 | | | | $\kappa=1$ |



Pythagorean theorem:

$$C^2 = A^2 + B^2.$$

Definitions:

$$\sin a = A/C, \quad \cos a = B/C,$$

$$\csc a = C/A, \quad \sec a = C/B,$$

$$\tan a = \frac{\sin a}{\cos a} = \frac{A}{B}, \quad \cot a = \frac{\cos a}{\sin a} = \frac{B}{A}.$$

Area, radius of inscribed circle:

$$\frac{1}{2}AB$$
, $\frac{AB}{A+B+C}$

Identities:

$$\sin x = \frac{1}{\csc x}, \qquad \cos x = \frac{1}{\sec x},$$

$$\tan x = \frac{1}{\cot x}, \qquad \sin^2 x + \cos^2 x = 1,$$

$$1 + \tan^2 x = \sec^2 x, \qquad 1 + \cot^2 x = \csc^2 x,$$

$$\sin x = \cos\left(\frac{\pi}{2} - x\right), \qquad \sin x = \sin(\pi - x),$$

$$\cos x = -\cos(\pi - x), \qquad \tan x = \cot\left(\frac{\pi}{2} - x\right),$$

$$\cot x = -\cot(\pi - x), \qquad \csc x = \cot\frac{x}{2} - \cot x,$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y,$$

 $\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$,

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y},$$
$$\cot(x \pm y) = \frac{\cot x \cot y \mp 1}{\cot x \pm \cot y},$$

$$\sin 2x = 2 \sin x \cos x,$$
 $\sin 2x = \frac{2 \tan x}{1 + \tan^2 x},$
 $\cos 2x = \cos^2 x - \sin^2 x,$ $\cos 2x = 2 \cos^2 x - 1,$
 $\cos 2x = 1 - 2 \sin^2 x,$ $\cos 2x = \frac{1 - \tan^2 x}{1 + \tan^2 x},$

$$\cos 2x = 1 - 2\sin^2 x,$$
 $\cos 2x = \frac{1 + \tan^2 x}{1 + \tan^2 x},$ $\cot 2x = \frac{\cot^2 x - 1}{2\cot x},$

$$\sin(x+y)\sin(x-y) = \sin^2 x - \sin^2 y,$$

$$\cos(x+y)\cos(x-y) = \cos^2 x - \sin^2 y.$$

Euler's equation:

$$e^{ix} = \cos x + i\sin x, \qquad e^{i\pi} = -$$

v2.02 ©1994 by Steve Seiden sseiden@acm.org http://www.csc.lsu.edu/~seiden Multiplication:

$$C = A \cdot B, \quad c_{i,j} = \sum_{k=1}^{n} a_{i,k} b_{k,j}.$$

Determinants: $\det A \neq 0$ iff A is non-singular.

$$\det A \cdot B = \det A \cdot \det B,$$

$$\det A = \sum_{\pi} \prod_{i=1}^{n} \operatorname{sign}(\pi) a_{i,\pi(i)}.$$

 2×2 and 3×3 determinant:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc,$$

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = g \begin{vmatrix} b & c \\ e & f \end{vmatrix} - h \begin{vmatrix} a & c \\ d & f \end{vmatrix} + i \begin{vmatrix} a & b \\ d & e \end{vmatrix}$$

aei + bfg + cdh

-ceq - fha - ibd.

Permanents:

$$\operatorname{perm} A = \sum_{\pi} \prod_{i=1}^{n} a_{i,\pi(i)}.$$

Hyperbolic Functions

Definitions:

$$\begin{aligned} \sinh x &= \frac{e^x - e^{-x}}{2}, & \cosh x &= \frac{e^x + e^{-x}}{2}, \\ \tanh x &= \frac{e^x - e^{-x}}{e^x + e^{-x}}, & \operatorname{csch} x &= \frac{1}{\sinh x}, \\ \operatorname{sech} x &= \frac{1}{\cosh x}, & \operatorname{coth} x &= \frac{1}{\tanh x}. \end{aligned}$$

Identities:

$$\cosh^2 x - \sinh^2 x = 1, \qquad \tanh^2 x + \operatorname{sech}^2 x = 1,$$

$$\coth^2 x - \operatorname{csch}^2 x = 1, \qquad \sinh(-x) = -\sinh x,$$

$$\cosh(-x) = \cosh x, \qquad \tanh(-x) = -\tanh x,$$

$$\sinh(x+y) = \sinh x \cosh y + \cosh x \sinh y,$$

$$\cosh(x+y) = \cosh x \cosh y + \sinh x \sinh y,$$

$$\sinh 2x = 2\sinh x \cosh x,$$

$$\cosh 2x = \cosh^2 x + \sinh^2 x,$$

$$\cosh x + \sinh x = e^x, \qquad \cosh x - \sinh x = e^{-x}.$$

| | * | |
|--------------------------------------|---|----------------------|
| $\cosh x + \sinh x = e^x,$ | $\cosh x - \sinh$ | $x = e^{-x}$ |
| $(\cosh x + \sinh x)^n = \cosh$ | $nnx + \sinh nx$, | $n \in \mathbb{Z}$, |
| $2\sinh^2\frac{x}{2} = \cosh x - 1,$ | $2\cosh^2\frac{x}{2} = \cot^2\frac{x}{2}$ | $\sinh x + 1$ |

| θ | $\sin \theta$ | $\cos \theta$ | $\tan \theta$ |
|---------------------------------|----------------------|----------------------|----------------------|
| 0 | 0 | 1 | 0 |
| $\frac{\pi}{6}$ | $\frac{1}{2}$ | $\frac{\sqrt{3}}{2}$ | $\frac{\sqrt{3}}{3}$ |
| $\frac{\pi}{4}$ | $\frac{\sqrt{2}}{2}$ | $\frac{\sqrt{2}}{2}$ | 1 |
| | $\frac{\sqrt{3}}{2}$ | $\frac{1}{2}$ | $\sqrt{3}$ |
| $\frac{\pi}{3}$ $\frac{\pi}{2}$ | $\overline{1}$ | 0 | ∞ |
| | | | |

... in mathematics you don't understand things, you just get used to them.

– J. von Neumann



Law of cosines: $c^2 = a^2 + b^2 - 2ab \cos C.$ Area:

$$\begin{split} A &= \frac{1}{2}hc, \\ &= \frac{1}{2}ab\sin C, \\ &= \frac{c^2\sin A\sin B}{2\sin C}. \end{split}$$

Heron's formula:

$$A = \sqrt{s \cdot s_a \cdot s_b \cdot s_c},$$

$$s = \frac{1}{2}(a+b+c),$$

$$s_a = s-a,$$

$$s_b = s-b,$$

$$s_c = s-c.$$

More identities:

whose identities.
$$\sin \frac{x}{2} = \sqrt{\frac{1 - \cos x}{2}},$$

$$\cos \frac{x}{2} = \sqrt{\frac{1 + \cos x}{2}},$$

$$\tan \frac{x}{2} = \sqrt{\frac{1 - \cos x}{1 + \cos x}},$$

$$= \frac{1 - \cos x}{\sin x},$$

$$= \frac{\sin x}{1 + \cos x},$$

$$\cot \frac{x}{2} = \sqrt{\frac{1 + \cos x}{1 - \cos x}},$$

$$= \frac{1 + \cos x}{\sin x},$$

$$= \frac{\sin x}{1 - \cos x},$$

$$\sin x = \frac{e^{ix} - e^{-ix}}{2i},$$

$$\cos x = \frac{e^{ix} + e^{-ix}}{2},$$

$$\tan x = -i\frac{e^{ix} - e^{-ix}}{e^{ix} + e^{-ix}},$$

$$= -i\frac{e^{2ix} - 1}{2i},$$

 $\sin x = \frac{\sinh ix}{i}$

 $\cos x = \cosh ix$,

 $\tan x = \frac{\tanh ix}{i}$

The Chinese remainder theorem: There exists a number C such that:

 $C \equiv r_1 \mod m_1$

: : :

 $C \equiv r_n \mod m_n$

if m_i and m_j are relatively prime for $i \neq j$. Euler's function: $\phi(x)$ is the number of positive integers less than x relatively prime to x. If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x then

$$\phi(x) = \prod_{i=1}^{n} p_i^{e_i - 1} (p_i - 1).$$

Euler's theorem: If a and b are relatively prime then

$$1 \equiv a^{\phi(b)} \bmod b$$
.

Fermat's theorem:

$$1 \equiv a^{p-1} \bmod p.$$

The Euclidean algorithm: if a > b are integers then

$$gcd(a, b) = gcd(a \mod b, b).$$

If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x

$$S(x) = \sum_{d|x} d = \prod_{i=1}^{n} \frac{p_i^{e_i+1} - 1}{p_i - 1}.$$

Perfect Numbers: x is an even perfect number iff $x = 2^{n-1}(2^n - 1)$ and $2^n - 1$ is prime. Wilson's theorem: n is a prime iff

$$(n-1)! \equiv -1 \bmod n.$$

$$\mu(i) = \begin{cases} (n-1)! = -1 \mod n. \\ \text{M\"obius inversion:} \\ \mu(i) = \begin{cases} 1 & \text{if } i = 1. \\ 0 & \text{if } i \text{ is not square-free.} \\ (-1)^r & \text{if } i \text{ is the product of} \\ r & \text{distinct primes.} \end{cases}$$
 If

 If

$$G(a) = \sum_{d|a} F(d),$$

$$F(a) = \sum_{d|a} \mu(d) G\left(\frac{a}{d}\right).$$

Prime numbers:

$$p_n = n \ln n + n \ln \ln n - n + n \frac{\ln \ln n}{\ln n}$$

$$+O\left(\frac{n}{\ln n}\right),$$

$$\pi(n) = \frac{n}{\ln n} + \frac{n}{(\ln n)^2} + \frac{2!n}{(\ln n)^3} + O\left(\frac{n}{(\ln n)^4}\right).$$

Definitions:

Loop An edge connecting a vertex to itself.

Directed Each edge has a direction. SimpleGraph with no loops or multi-edges.

WalkA sequence $v_0e_1v_1\ldots e_\ell v_\ell$. TrailA walk with distinct edges. Pathtrail with distinct

vertices.

ConnectedA graph where there exists a path between any two

vertices.

connected ComponentΑ maximal

subgraph. TreeA connected acyclic graph. Free tree A tree with no root. DAGDirected acyclic graph. EulerianGraph with a trail visiting each edge exactly once.

Hamiltonian Graph with a cycle visiting each vertex exactly once.

CutA set of edges whose removal increases the number of components.

Cut-setA minimal cut. Cut edge A size 1 cut.

k-Connected A graph connected with the removal of any k-1vertices.

k-Tough $\forall S \subseteq V, S \neq \emptyset$ we have $k \cdot c(G - S) \le |S|$.

A graph where all vertices k-Regular have degree k.

k-Factor Α k-regular spanning subgraph.

Matching A set of edges, no two of which are adjacent.

CliqueA set of vertices, all of which are adjacent.

Ind. set A set of vertices, none of which are adjacent.

Vertex cover A set of vertices which cover all edges.

Planar graph A graph which can be embeded in the plane.

Plane graph An embedding of a planar

$$\sum_{v \in V} \deg(v) = 2m.$$

If G is planar then n - m + f = 2, so

$$f \le 2n - 4, \quad m \le 3n - 6.$$

Any planar graph has a vertex with degree ≤ 5 .

Notation:

E(G)Edge set Vertex set V(G)

c(G)Number of components

G[S]Induced subgraph

deg(v)Degree of v

Maximum degree $\Delta(G)$ $\delta(G)$ Minimum degree

 $\chi(G)$ Chromatic number

 $\chi_E(G)$ Edge chromatic number G^c Complement graph

 K_n Complete graph K_{n_1,n_2} Complete bipartite graph

Ramsev number

Geometry

Projective coordinates: (x, y, z), not all x, y and z zero.

$$(x, y, z) = (cx, cy, cz) \quad \forall c \neq 0.$$

Cartesian Projective (x, y)(x, y, 1)

y = mx + b(m, -1, b)x = c(1,0,-c)

Distance formula, L_p and L_{∞}

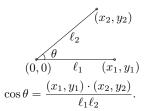
$$\sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2},$$
$$[|x_1 - x_0|^p + |y_1 - y_0|^p]^{1/p},$$

$$\lim_{x \to \infty} \left[|x_1 - x_0|^p + |y_1 - y_0|^p \right]^{1/p}.$$

Area of triangle $(x_0, y_0), (x_1, y_1)$ and (x_2, y_2) :

$$\frac{1}{2} \operatorname{abs} \begin{vmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{vmatrix}.$$

Angle formed by three points:



Line through two points (x_0, y_0) and (x_1, y_1) :

$$\begin{vmatrix} x & y & 1 \\ x_0 & y_0 & 1 \\ x_1 & y_1 & 1 \end{vmatrix} = 0.$$

Area of circle, volume of sphere:

$$A = \pi r^2, \qquad V = \frac{4}{3}\pi r^3.$$

If I have seen farther than others, it is because I have stood on the shoulders of giants.

- Issac Newton

Wallis' identity:
$$\pi = 2 \cdot \frac{2 \cdot 2 \cdot 4 \cdot 4 \cdot 6 \cdot 6 \cdots}{1 \cdot 3 \cdot 3 \cdot 5 \cdot 5 \cdot 7 \cdots}$$

Brouncker's continued fraction expansion:

$$\frac{\pi}{4} = 1 + \frac{1^2}{2 + \frac{3^2}{2 + \frac{5^2}{2 + \frac{7^2}{2 + \dots}}}}$$

Gregrory's series:
$$\frac{\pi}{4} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \frac{1}{9} - \cdots$$

Newton's series:

$$\frac{\pi}{6} = \frac{1}{2} + \frac{1}{2 \cdot 3 \cdot 2^3} + \frac{1 \cdot 3}{2 \cdot 4 \cdot 5 \cdot 2^5} + \cdots$$

Sharp's series:

$$\frac{\pi}{6} = \frac{1}{\sqrt{3}} \left(1 - \frac{1}{3^1 \cdot 3} + \frac{1}{3^2 \cdot 5} - \frac{1}{3^3 \cdot 7} + \cdots \right)$$

Euler's series:

$$\frac{\pi^2}{6} = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \frac{1}{5^2} + \cdots$$

$$\frac{\pi^2}{8} = \frac{1}{1^2} + \frac{1}{3^2} + \frac{1}{5^2} + \frac{1}{7^2} + \frac{1}{9^2} + \cdots$$

$$\frac{\pi^2}{12} = \frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} + \frac{1}{5^2} - \cdots$$

Partial Fractions

Let N(x) and D(x) be polynomial functions of x. We can break down N(x)/D(x) using partial fraction expansion. First, if the degree of N is greater than or equal to the degree of D, divide N by D, obtaining

$$\frac{N(x)}{D(x)} = Q(x) + \frac{N'(x)}{D(x)},$$

where the degree of N' is less than that of D. Second, factor D(x). Use the following rules: For a non-repeated factor:

$$\frac{N(x)}{(x-a)D(x)} = \frac{A}{x-a} + \frac{N'(x)}{D(x)},$$

$$A = \left[\frac{N(x)}{D(x)}\right]_{x=a}.$$

For a repeated factor:

$$\frac{N(x)}{(x-a)^m D(x)} = \sum_{k=0}^{m-1} \frac{A_k}{(x-a)^{m-k}} + \frac{N'(x)}{D(x)},$$

$$A_k = \frac{1}{k!} \left[\frac{d^k}{dx^k} \left(\frac{N(x)}{D(x)} \right) \right]_{x=a}.$$

The reasonable man adapts himself to the world; the unreasonable persists in trying to adapt the world to himself. Therefore all progress depends on the unreasonable. George Bernard Shaw

Derivatives:

1.
$$\frac{d(cu)}{dx} = c\frac{du}{dx}$$
, 2. $\frac{d(u+v)}{dx} = \frac{du}{dx} + \frac{dv}{dx}$, 3. $\frac{d(uv)}{dx} = u\frac{dv}{dx} + v\frac{du}{dx}$

4.
$$\frac{d(u^n)}{dx} = nu^{n-1}\frac{du}{dx}, \quad \textbf{5.} \quad \frac{d(u/v)}{dx} = \frac{v\left(\frac{du}{dx}\right) - u\left(\frac{dv}{dx}\right)}{v^2}, \quad \textbf{6.} \quad \frac{d(e^{cu})}{dx} = ce^{cu}\frac{du}{dx}$$

$$\frac{du}{dx} = nu^{n-1}\frac{du}{dx}, \qquad 5. \quad \frac{du}{dx} = -\frac{du}{dx} \qquad \frac{du}{dx}$$

$$=\frac{v\left(\frac{du}{dx}\right)-u\left(\frac{dv}{dx}\right)}{v^2}, \quad \mathbf{6.} \quad \frac{d(e^{cu})}{dx}=ce^{cu}\frac{du}{dx},$$

7.
$$\frac{d(c^u)}{dx} = (\ln c)c^u \frac{du}{dx},$$

$$8. \ \frac{d(\ln u)}{dx} = \frac{1}{u} \frac{du}{dx},$$

$$9. \ \frac{d(\sin u)}{dx} = \cos u \frac{du}{dx},$$

$$10. \ \frac{d(\cos u)}{dx} = -\sin u \frac{du}{dx},$$

11.
$$\frac{d(\tan u)}{dx} = \sec^2 u \frac{du}{dx}$$

$$12. \ \frac{d(\cot u)}{dx} = \csc^2 u \frac{du}{dx},$$

$$\mathbf{13.} \ \frac{d(\sec u)}{dx} = \tan u \ \sec u \frac{du}{dx},$$

$$\mathbf{14.} \ \frac{d(\csc u)}{dx} = -\cot u \, \csc u \, \frac{du}{dx},$$

15.
$$\frac{d(\arcsin u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$$

16.
$$\frac{d(\arccos u)}{dx} = \frac{-1}{\sqrt{1-u^2}} \frac{du}{dx}$$

17.
$$\frac{d(\arctan u)}{dx} = \frac{1}{1+u^2} \frac{du}{dx}$$

18.
$$\frac{d(\operatorname{arccot} u)}{dx} = \frac{-1}{1+u^2} \frac{du}{dx}$$

19.
$$\frac{d(\operatorname{arcsec} u)}{dx} = \frac{1}{u\sqrt{1-u^2}} \frac{du}{dx}$$

$$20. \ \frac{d(\arccos u)}{dx} = \frac{-1}{u\sqrt{1-u^2}} \frac{du}{dx}$$

21.
$$\frac{d(\sinh u)}{dx} = \cosh u \frac{du}{dx}$$

23.
$$\frac{d(\tanh u)}{dx} = \operatorname{sech}^2 u \frac{du}{dx}$$

24.
$$\frac{d(\coth u)}{dx} = -\operatorname{csch}^2 u \frac{du}{dx}$$

25.
$$\frac{d(\operatorname{sech} u)}{dx} = -\operatorname{sech} u \tanh u \frac{du}{dx}$$

26.
$$\frac{d(\operatorname{csch} u)}{dx} = -\operatorname{csch} u \operatorname{coth} u \frac{du}{dx}$$

27.
$$\frac{d(\operatorname{arcsinh} u)}{dx} = \frac{1}{\sqrt{1+u^2}} \frac{du}{dx},$$

28.
$$\frac{d(\operatorname{arccosh} u)}{dx} = \frac{1}{\sqrt{u^2 - 1}} \frac{du}{dx}$$

29.
$$\frac{d(\operatorname{arctanh} u)}{dx} = \frac{1}{1 - u^2} \frac{du}{dx}$$

30.
$$\frac{d(\operatorname{arccoth} u)}{dx} = \frac{1}{u^2 - 1} \frac{du}{dx}$$

31.
$$\frac{d(\operatorname{arcsech} u)}{dx} = \frac{-1}{u\sqrt{1-u^2}}\frac{du}{dx}$$

32.
$$\frac{d(\operatorname{arccsch} u)}{dx} = \frac{-1}{|u|\sqrt{1+u^2}} \frac{du}{dx}$$

Integrals:

$$1. \int cu \, dx = c \int u \, dx,$$

$$2. \int (u+v) dx = \int u dx + \int v dx,$$

3.
$$\int x^n dx = \frac{1}{n+1} x^{n+1}, \quad n \neq -1$$

3.
$$\int x^n dx = \frac{1}{n+1}x^{n+1}$$
, $n \neq -1$, 4. $\int \frac{1}{x} dx = \ln x$, 5. $\int e^x dx = e^x$,

6.
$$\int \frac{dx}{1+x^2} = \arctan x,$$

7.
$$\int u \frac{dv}{dx} dx = uv - \int v \frac{du}{dx} dx,$$

8.
$$\int \sin x \, dx = -\cos x,$$

$$9. \int \cos x \, dx = \sin x,$$

$$\mathbf{10.} \int \tan x \, dx = -\ln|\cos x|,$$

11.
$$\int \cot x \, dx = \ln|\cos x|,$$

$$\mathbf{12.} \int \sec x \, dx = \ln|\sec x + \tan x|,$$

12.
$$\int \sec x \, dx = \ln|\sec x + \tan x|$$
, **13.** $\int \csc x \, dx = \ln|\csc x + \cot x|$,

14.
$$\int \arcsin \frac{x}{a} dx = \arcsin \frac{x}{a} + \sqrt{a^2 - x^2}, \quad a > 0,$$

60. $\int x\sqrt{x^2 \pm a^2} \, dx = \frac{1}{3}(x^2 \pm a^2)^{3/2},$

61. $\int \frac{dx}{x\sqrt{x^2 + a^2}} = \frac{1}{a} \ln \left| \frac{x}{a + \sqrt{a^2 + x^2}} \right|,$

$$62. \int \frac{dx}{x\sqrt{x^2 - a^2}} = \frac{1}{a} \arccos \frac{a}{|x|}, \quad a > 0, \qquad 63. \int \frac{dx}{x^2\sqrt{x^2 \pm a^2}} = \mp \frac{\sqrt{x^2 \pm a^2}}{a^2 x},$$

$$64. \int \frac{x \, dx}{\sqrt{x^2 \pm a^2}} = \sqrt{x^2 \pm a^2}, \qquad 65. \int \frac{\sqrt{x^2 \pm a^2}}{x^4} \, dx = \mp \frac{(x^2 + a^2)^{3/2}}{3a^2 x^3},$$

$$66. \int \frac{dx}{ax^2 + bx + c} = \begin{cases} \frac{1}{\sqrt{b^2 - 4ac}} \ln \left| \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right|, & \text{if } b^2 > 4ac, \\ \frac{2}{\sqrt{4ac - b^2}} \arctan \frac{2ax + b}{\sqrt{4ac - b^2}}, & \text{if } b^2 < 4ac, \end{cases}$$

67.
$$\int \frac{dx}{\sqrt{ax^2 + bx + c}} = \begin{cases} \frac{1}{\sqrt{a}} \ln \left| 2ax + b + 2\sqrt{a}\sqrt{ax^2 + bx + c} \right|, & \text{if } a > 0, \\ \frac{1}{\sqrt{-a}} \arcsin \frac{-2ax - b}{\sqrt{b^2 - 4ac}}, & \text{if } a < 0, \end{cases}$$

68.
$$\int \sqrt{ax^2 + bx + c} \, dx = \frac{2ax + b}{4a} \sqrt{ax^2 + bx + c} + \frac{4ax - b^2}{8a} \int \frac{dx}{\sqrt{ax^2 + bx + c}},$$

69.
$$\int \frac{x \, dx}{\sqrt{ax^2 + bx + c}} = \frac{\sqrt{ax^2 + bx + c}}{a} - \frac{b}{2a} \int \frac{dx}{\sqrt{ax^2 + bx + c}},$$

70.
$$\int \frac{dx}{x\sqrt{ax^2 + bx + c}} = \begin{cases} \frac{-1}{\sqrt{c}} \ln \left| \frac{2\sqrt{c}\sqrt{ax^2 + bx + c} + bx + 2c}{x} \right|, & \text{if } c > 0, \\ \frac{1}{\sqrt{-c}} \arcsin \frac{bx + 2c}{|x|\sqrt{b^2 - 4ac}}, & \text{if } c < 0, \end{cases}$$

71.
$$\int x^3 \sqrt{x^2 + a^2} \, dx = \left(\frac{1}{3}x^2 - \frac{2}{15}a^2\right)(x^2 + a^2)^{3/2}$$

72.
$$\int x^n \sin(ax) \, dx = -\frac{1}{a} x^n \cos(ax) + \frac{n}{a} \int x^{n-1} \cos(ax) \, dx,$$

73.
$$\int x^n \cos(ax) \, dx = \frac{1}{a} x^n \sin(ax) - \frac{n}{a} \int x^{n-1} \sin(ax) \, dx$$

74.
$$\int x^n e^{ax} dx = \frac{x^n e^{ax}}{a} - \frac{n}{a} \int x^{n-1} e^{ax} dx,$$

75.
$$\int x^n \ln(ax) \, dx = x^{n+1} \left(\frac{\ln(ax)}{n+1} - \frac{1}{(n+1)^2} \right),$$

76.
$$\int x^n (\ln ax)^m \, dx = \frac{x^{n+1}}{n+1} (\ln ax)^m - \frac{m}{n+1} \int x^n (\ln ax)^{m-1} \, dx.$$

Difference, shift operators:

$$\Delta f(x) = f(x+1) - f(x),$$

 E $f(x) = f(x+1).$

Fundamental Theorem:

$$f(x) = \Delta F(x) \Leftrightarrow \sum_{i} f(x)\delta x = F(x) + C.$$
$$\sum_{i}^{b} f(x)\delta x = \sum_{i}^{b-1} f(i).$$

$$\Delta(cu) = c\Delta u, \qquad \Delta(u+v) = \Delta u + \Delta v,$$

$$\Delta(uv) = u\Delta v + E v\Delta u,$$

$$\Delta(x^{\underline{n}}) = nx^{\underline{n}-1},$$

$$\Delta(H_x) = x^{-1}, \qquad \Delta(2^x) = 2^x,$$

$$\Delta(H_x) = x \xrightarrow{x}, \qquad \Delta(2^x) = 2^x,$$

$$\Delta(c^x) = (c-1)c^x, \qquad \Delta\binom{x}{m} = \binom{x}{m-1}.$$

Sums:

$$\sum cu \, \delta x = c \sum u \, \delta x,$$

$$\sum (u+v)\,\delta x = \sum u\,\delta x + \sum v\,\delta x,$$

$$\sum u \Delta v \, \delta x = uv - \sum \mathbf{E} \, v \Delta u \, \delta x,$$

$$\sum x^{\underline{n}} \, \delta x = \frac{x^{\underline{n+1}}}{m+1}, \qquad \qquad \sum x^{\underline{-1}} \, \delta x = H_x,$$

$$\sum c^x \, \delta x = \frac{c^x}{c-1}, \qquad \sum \binom{x}{m} \, \delta x = \binom{x}{m+1}.$$

Falling Factorial Powers:

$$x^{\underline{n}} = x(x-1)\cdots(x-n+1), \quad n > 0,$$

 $x^{\underline{0}} = 1,$

$$x^{\underline{n}} = \frac{1}{(x+1)\cdots(x+|n|)}, \quad n < 0,$$

$$x^{\underline{n+m}} = x^{\underline{m}}(x-m)^{\underline{n}}.$$

Rising Factorial Powers:

$$x^{\overline{n}} = x(x+1)\cdots(x+n-1), \quad n > 0,$$

$$x^{\overline{0}} = 1,$$

$$x^{\overline{n}} = \frac{1}{(x-1)\cdots(x-|n|)}, \quad n < 0,$$

$$x^{\overline{n+m}} = x^{\overline{m}} (x+m)^{\overline{n}}.$$

$$x^{\underline{n}} = (-1)^n (-x)^{\overline{n}} = (x - n + 1)^{\overline{n}}$$

= $1/(x + 1)^{\overline{-n}}$,

$$x^{\overline{n}} = (-1)^n (-x)^{\underline{n}} = (x+n-1)^{\underline{n}}$$

$$x^n = \sum_{k=1}^n \binom{n}{k} x^{\underline{k}} = \sum_{k=1}^n \binom{n}{k} (-1)^{n-k} x^{\overline{k}},$$

$$x^{\underline{n}} = \sum_{k=0}^{n} \begin{bmatrix} n \\ k \end{bmatrix} (-1)^{n-k} x^k,$$

$$x^{\overline{n}} = \sum_{k=1}^{n} \begin{bmatrix} n \\ k \end{bmatrix} x^k.$$

Taylor's series:

$$f(x) = f(a) + (x - a)f'(a) + \frac{(x - a)^2}{2}f''(a) + \dots = \sum_{i=0}^{\infty} \frac{(x - a)^i}{i!}f^{(i)}(a).$$
sions:

Expansions:

Expansions:
$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-x^n} = 1 + x^n + x^{2n} + x^{3n} + \cdots = \sum_{i=0}^{\infty} x^{ni},$$

$$\frac{x}{(1-x)^2} = x + 2x^2 + 3x^3 + 4x^4 + \cdots = \sum_{i=0}^{\infty} i x^i,$$

$$x^k \frac{d^n}{dx^n} \left(\frac{1}{1-x}\right) = x + 2^n x^2 + 3^n x^3 + 4^n x^4 + \cdots = \sum_{i=0}^{\infty} i^n x^i,$$

$$e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\ln(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 - \frac{1}{4}x^4 - \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\sin x = x - \frac{1}{3}x^3 + \frac{1}{6}x^5 - \frac{1}{17}x^7 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\cos x = 1 - \frac{1}{2}x^2 + \frac{1}{4}x^4 - \frac{1}{6!}x^6 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\frac{1}{(1-x)^{n+1}} = 1 + (n+1)x + \binom{n+2}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{i}{i}x^i,$$

$$\frac{1}{x^i} = 1 + x + 2x^2 + 5x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + x + 2x^2 + 6x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + (2+n)x + \binom{4+n}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{1-x} \ln \frac{1}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{1}{2}\left(\ln \frac{1}{1-x}\right)^2 = \frac{1}{2}x^2 + \frac{3}{4}x^3 + \frac{11}{24}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x^2 + x^2 + 2x^3 + 3x^4 + \cdots = \sum_{i=0}^{\infty} F_{i}x^i.$$

Ordinary power series:

$$A(x) = \sum_{i=0}^{\infty} a_i x^i.$$

Exponential power series:

$$A(x) = \sum_{i=0}^{\infty} a_i \frac{x^i}{i!}.$$

Dirichlet power series:

$$A(x) = \sum_{i=1}^{\infty} \frac{a_i}{i^x}.$$

Binomial theorem

$$(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k.$$

$$x^{n} - y^{n} = (x - y) \sum_{k=0}^{n-1} x^{n-1-k} y^{k}.$$

For ordinary power se

$$\alpha A(x) + \beta B(x) = \sum_{i=0}^{\infty} (\alpha a_i + \beta b_i) x^i,$$

$$x^k A(x) = \sum_{i=k}^{\infty} a_{i-k} x^i,$$

$$\frac{A(x) - \sum_{i=0}^{k-1} a_i x^i}{x^k} = \sum_{i=0}^{\infty} a_{i+k} x^i,$$

$$A(cx) = \sum_{i=0}^{\infty} c^i a_i x^i,$$

$$A'(x) = \sum_{\infty}^{i=0} (i+1)a_{i+1}x^{i},$$

$$xA'(x) = \sum_{i=1}^{\infty} ia_i x^i,$$

$$\int A(x) dx = \sum_{i=1}^{\infty} \frac{a_{i-1}}{i} x^{i},$$

$$\frac{A(x) + A(-x)}{2} = \sum_{i=1}^{\infty} a_{2i} x^{2i},$$

$$\frac{A(x) - A(-x)}{2} = \sum_{i=0}^{\infty} a_{2i+1} x^{2i+1}.$$

Summation: If $b_i = \sum_{i=0}^i a_i$ then

$$B(x) = \frac{1}{1-x}A(x).$$

Convolution:

$$A(x)B(x) = \sum_{i=0}^{\infty} \left(\sum_{j=0}^{i} a_j b_{i-j}\right) x^i.$$

God made the natural numbers; all the rest is the work of man. Leopold Kronecker

Expansions:

$$\frac{1}{(1-x)^{n+1}} \ln \frac{1}{1-x} = \sum_{i=0}^{\infty} (H_{n+i} - H_n) \binom{n+i}{i} x^i, \qquad \left(\frac{1}{x}\right)^{\frac{n}{n}} = \sum_{i=0}^{\infty} \binom{i}{n} x^i, \\ x^{\overline{n}} = \sum_{i=0}^{\infty} \binom{n}{i} x^i, \qquad (e^x - 1)^n = \sum_{i=0}^{\infty} \binom{i}{n} \frac{n! x^i}{i!}, \\ \left(\ln \frac{1}{1-x}\right)^n = \sum_{i=0}^{\infty} \binom{n}{i} \frac{n! x^i}{i!}, \qquad x \cot x = \sum_{i=0}^{\infty} \frac{(-4)^i B_{2i} x^{2i}}{(2i)!}, \\ \tan x = \sum_{i=1}^{\infty} (-1)^{i-1} \frac{2^{2i} (2^{2i} - 1) B_{2i} x^{2i-1}}{(2i)!}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) =$$

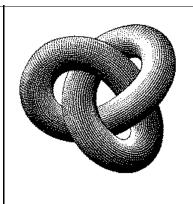
$$\left(\frac{1}{x}\right)^{\overline{-n}} = \sum_{i=0}^{\infty} \begin{Bmatrix} i \\ n \end{Bmatrix} x^{i},$$

$$\left(e^{x} - 1\right)^{n} = \sum_{i=0}^{\infty} \begin{Bmatrix} i \\ n \end{Bmatrix} \frac{n! x^{i}}{i!},$$

$$x \cot x = \sum_{i=0}^{\infty} \frac{(-4)^{i} B_{2i} x^{2i}}{(2i)!},$$

$$\zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^{x}},$$

$$\frac{\zeta(x-1)}{\zeta(x)} = \sum_{i=1}^{\infty} \frac{\phi(i)}{i^{x}},$$



Stieltjes Integration

If G is continuous in the interval [a, b] and F is nondecreasing then

$$\int_{a}^{b} G(x) \, dF(x)$$

exists. If a < b < c then

$$\int_{a}^{c} G(x) \, dF(x) = \int_{a}^{b} G(x) \, dF(x) + \int_{b}^{c} G(x) \, dF(x).$$

$$\int_{a}^{b} (G(x) + H(x)) dF(x) = \int_{a}^{b} G(x) dF(x) + \int_{a}^{b} H(x) dF(x),$$

$$\int_{a}^{b} G(x) d(F(x) + H(x)) = \int_{a}^{b} G(x) dF(x) + \int_{a}^{b} G(x) dH(x),$$

$$\int_{a}^{b} c \cdot G(x) dF(x) = \int_{a}^{b} G(x) d(c \cdot F(x)) = c \int_{a}^{b} G(x) dF(x),$$

$$\int_{a}^{b} G(x) dF(x) = G(b)F(b) - G(a)F(a) - \int_{a}^{b} F(x) dG(x).$$

If the integrals involved exist, and F possesses a derivative F' at every point in [a, b] then

$$\int_a^b G(x) dF(x) = \int_a^b G(x)F'(x) dx.$$

If we have equations:

$$a_{1,1}x_1 + a_{1,2}x_2 + \dots + a_{1,n}x_n = b_1$$

$$a_{2,1}x_1 + a_{2,2}x_2 + \dots + a_{2,n}x_n = b_2$$

$$\vdots \qquad \vdots$$

$$a_{n,1}x_1 + a_{n,2}x_2 + \dots + a_{n,n}x_n = b_n$$

Let $A = (a_{i,j})$ and B be the column matrix (b_i) . Then there is a unique solution iff $\det A \neq 0$. Let A_i be Awith column i replaced by B. Then

$$x_i = \frac{\det A_i}{\det A}.$$

Improvement makes strait roads, but the crooked roads without Improvement, are roads of Genius.

William Blake (The Marriage of Heaven and Hell)

 $00 \ \ 47 \ \ 18 \ \ 76 \ \ 29 \ \ 93 \ \ 85 \ \ 34 \ \ 61 \ \ 52$ 86 11 57 28 70 39 94 45 02 63 37 08 75 19 92 84 66 23 50 41 14 25 36 40 51 62 03 77 88 99 21 32 43 54 65 06 10 89 97 78 42 53 64 05 16 20 31 98 79 87

The Fibonacci number system: Every integer n has a unique representation

$$n = F_{k_1} + F_{k_2} + \dots + F_{k_m},$$

where $k_i \ge k_{i+1} + 2$ for all i ,
 $1 \le i < m$ and $k_m \ge 2$.

Fibonacci Numbers

 $1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, \dots$ Definitions:

$$F_{i} = F_{i-1} + F_{i-2}, \quad F_{0} = F_{1} = 1,$$

$$F_{-i} = (-1)^{i-1} F_{i},$$

$$F_{i} = \frac{1}{\sqrt{5}} \left(\phi^{i} - \hat{\phi}^{i} \right),$$

Cassini's identity: for i > 0:

$$F_{i+1}F_{i-1} - F_i^2 = (-1)^i.$$

Additive rule:

$$F_{n+k} = F_k F_{n+1} + F_{k-1} F_n,$$

$$F_{2n} = F_n F_{n+1} + F_{n-1} F_n.$$

Calculation by matrices:

$$\begin{pmatrix} F_{n-2} & F_{n-1} \\ F_{n-1} & F_n \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^n.$$