

# StarGAN v2: Diverse Image Synthesis for Multiple Domains

CVPR 2020  
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# Results

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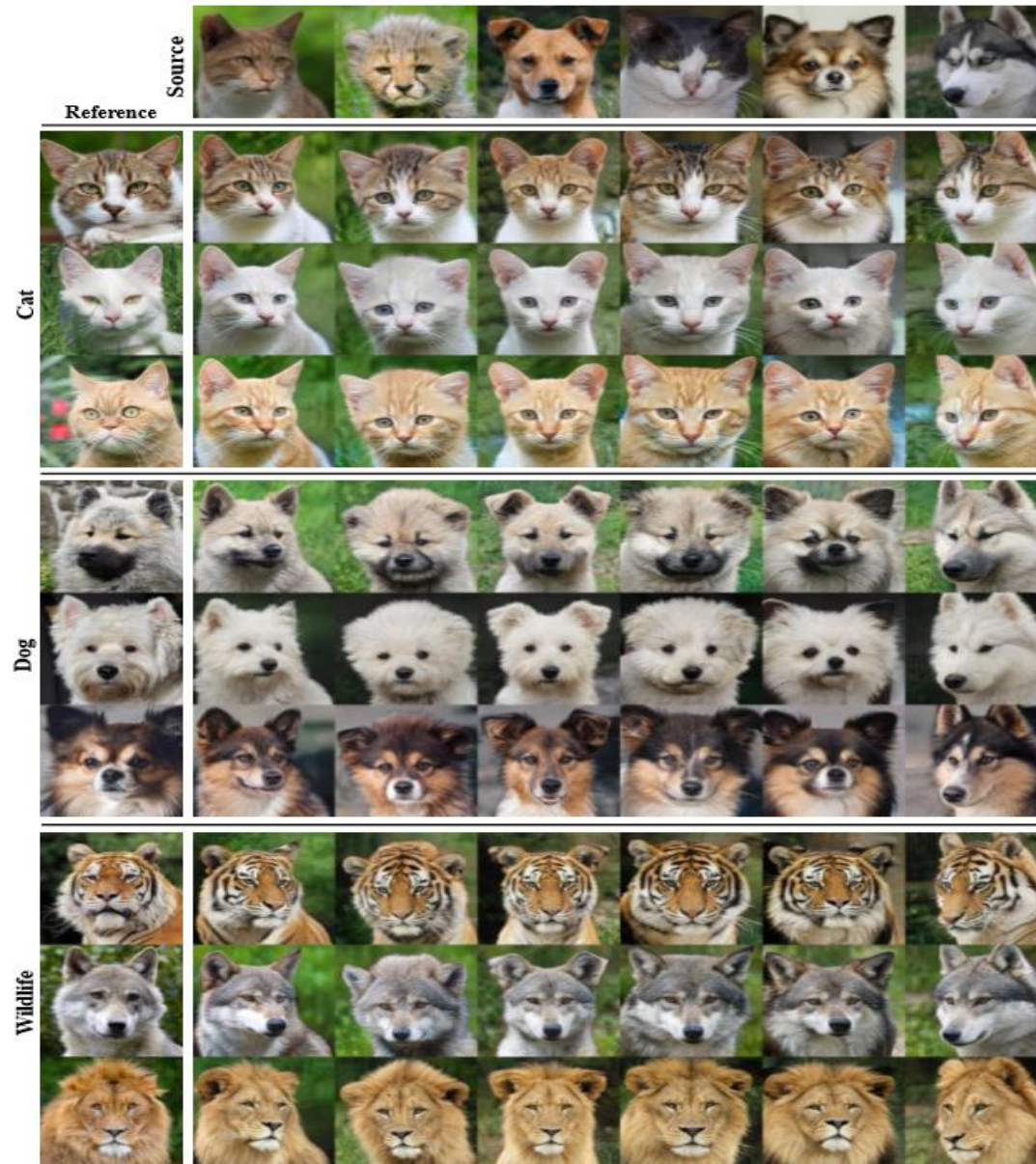


# Results





# Results



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# GAN

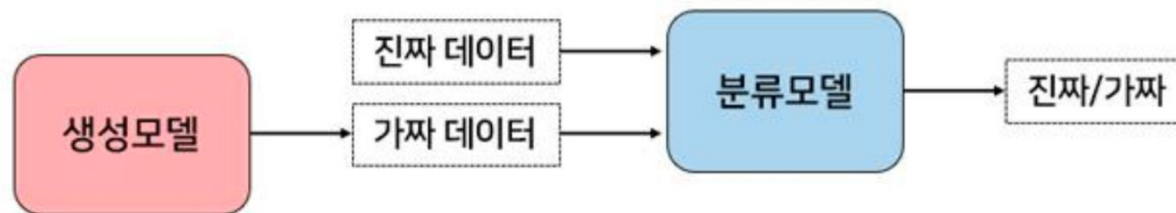
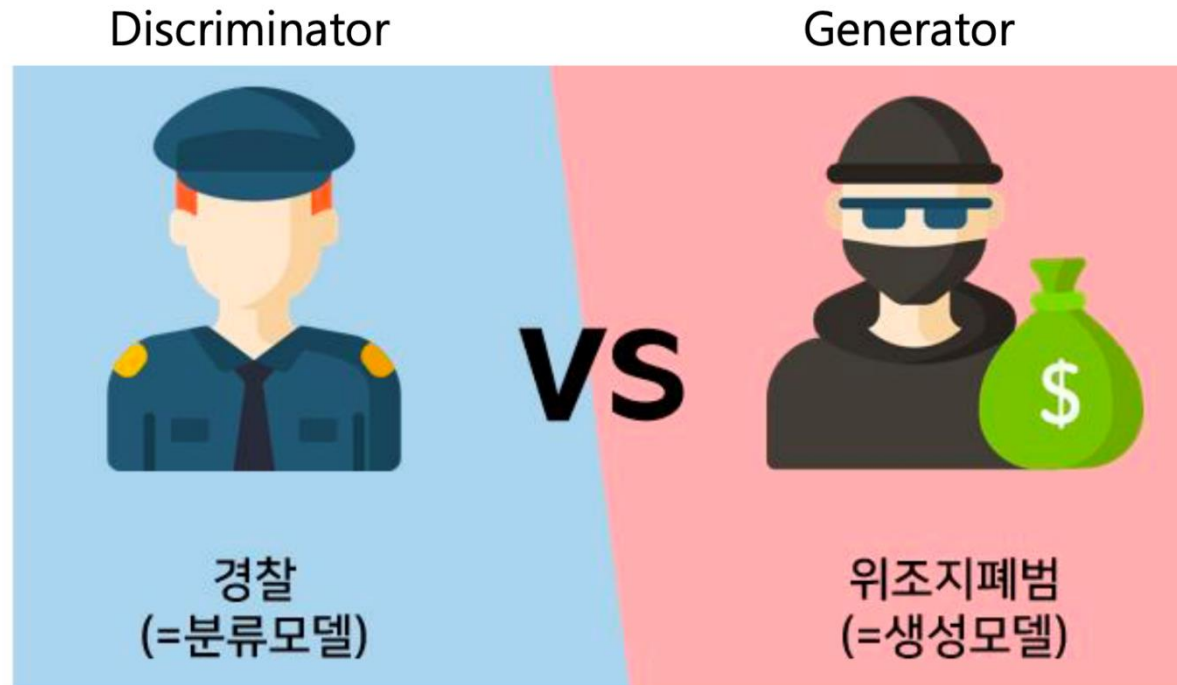
## Image to Image Translation

### What is good I2I Translation model?

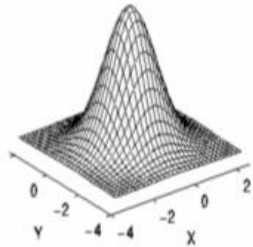
### Trends / History

# GAN

- Main Idea



# Image to Image Translation



**Image Generation**



**Image Translation**



**Image Transfer**



Source : <https://deview.kr/2019/schedule/279>

# What is good GAN model?

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- Photo-realism

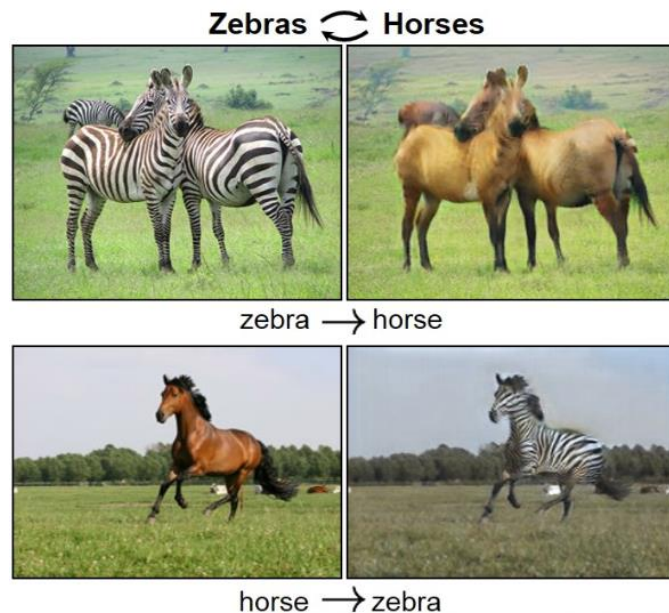


- Diversity
  - multi-modal is better than uni-modal
  - multi-domain is better than paired-domain



# What is good GAN model?

- Photo-realism
- Diversity
  - multi-modal is better than uni-modal
  - multi-domain is better than uni-domain



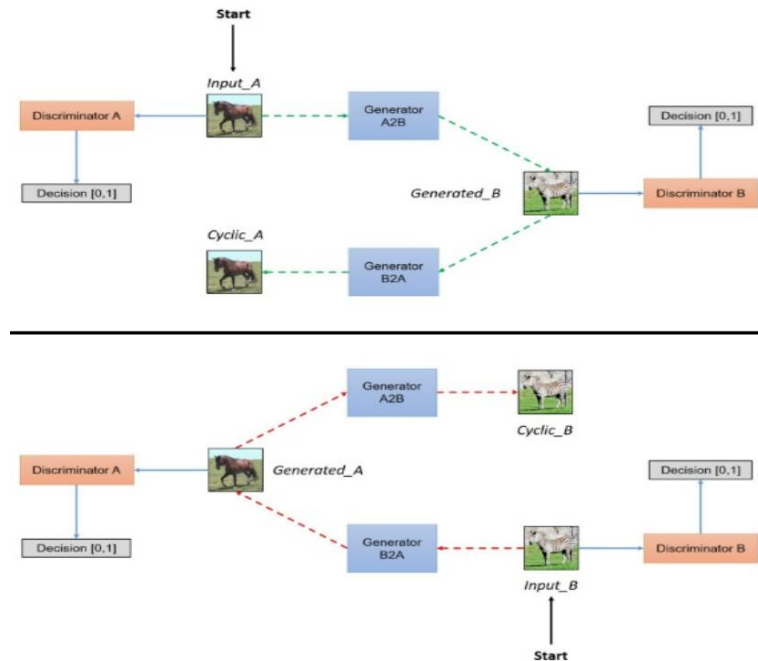
Uni-modal(cycleGAN)



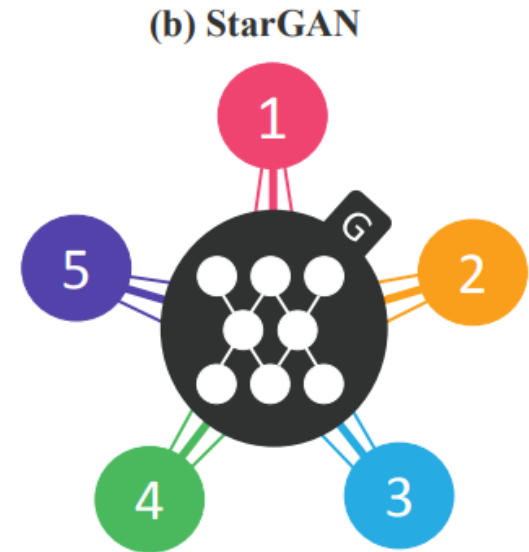
Multi-modal(MUNIT)

# What is good GAN model?

- Photo-realism
- Diversity
  - multi-modal is better than uni-modal
  - multi-domain is better than uni-domain



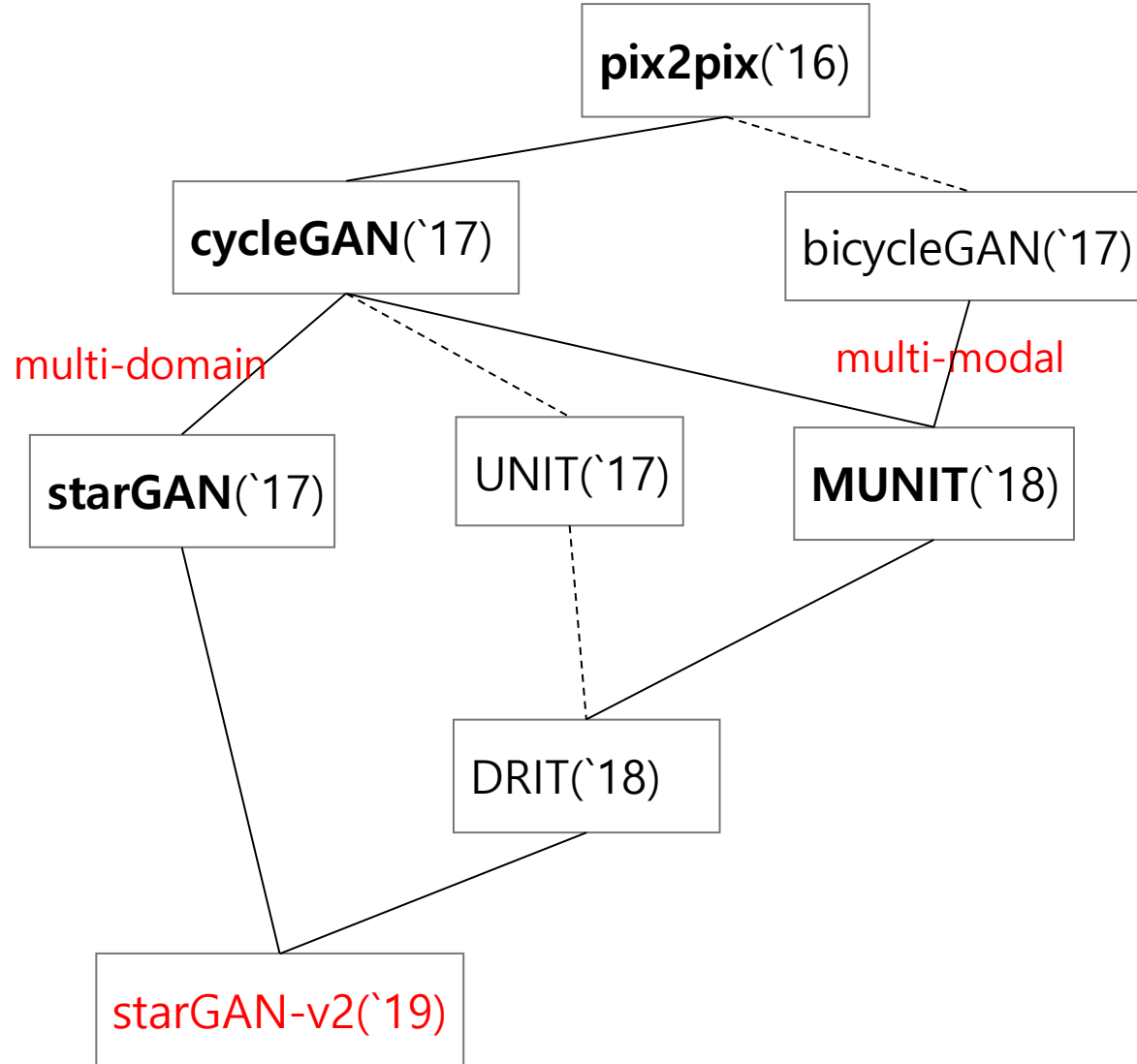
Uni-domain(cycleGAN)



Multi-domain (starGAN v1)

# Image to Image Translation

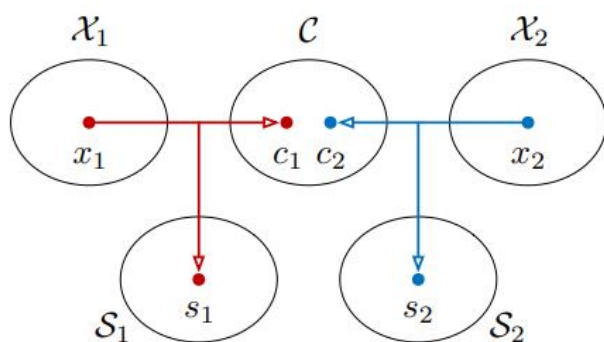
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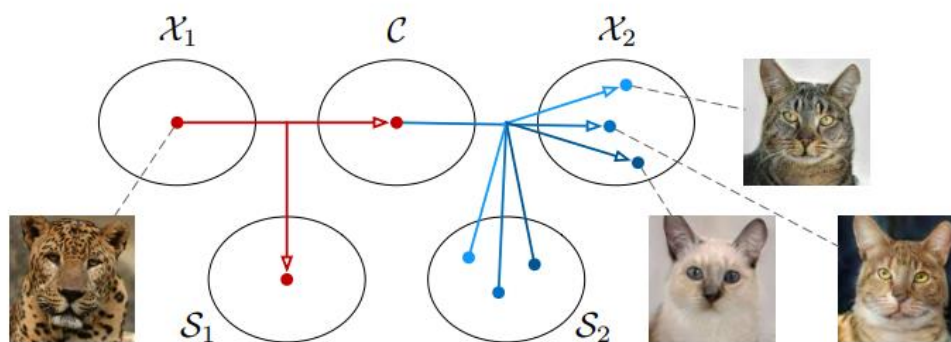
Source : <https://deview.kr/2019/schedule/279>

# Trends of multi-modal and multi-domain (1)

- Image can be decomposed with content and style
  - content : domain invariant, e.g. pose
  - style: domain specific
- Encoder – Decoder
  - if style can be sampled from prior
    - > generate diverse style
    - > multi-modal



(a) Auto-encoding



(b) Translation

# Trends of multi-modal and multi-domain (2)

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- ( Decoding style using Adain )

$$\text{AdaIN}(z, \gamma, \beta) = \gamma \left( \frac{z - \mu(z)}{\sigma(z)} \right) + \beta$$

- ( Reconstruction / Cycle Consistency Loss )
- Unified(Single) Model for various domain  
-> multi-domain



# Main Idea

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- Both Multi-modal and Multi-domain
  - Diverse image of multiple domain within single framework
- How?
  - Multi-modal -> Encoder – Decoder

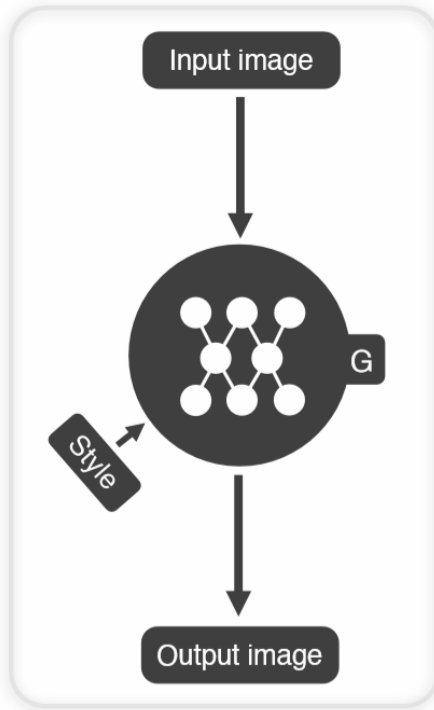
# Main Idea

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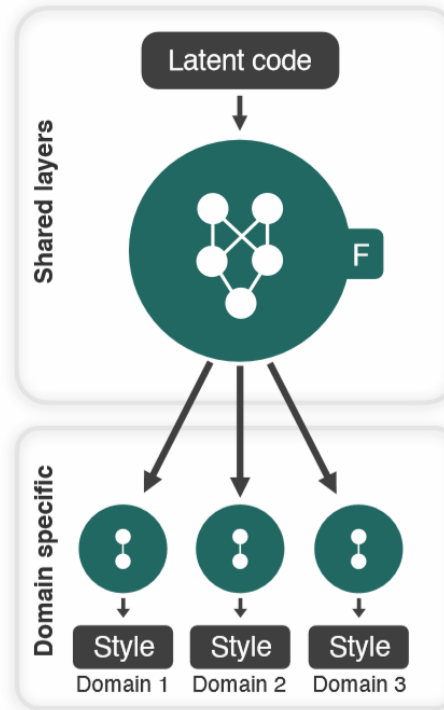
- Both Multi-modal and Multi-domain
  - Diverse image of multiple domain within single framework
- How?
  - Multi-modal -> Encoder – Decoder
  - Multi-domain -> Single Encoder and Decoder

# Model Architecture

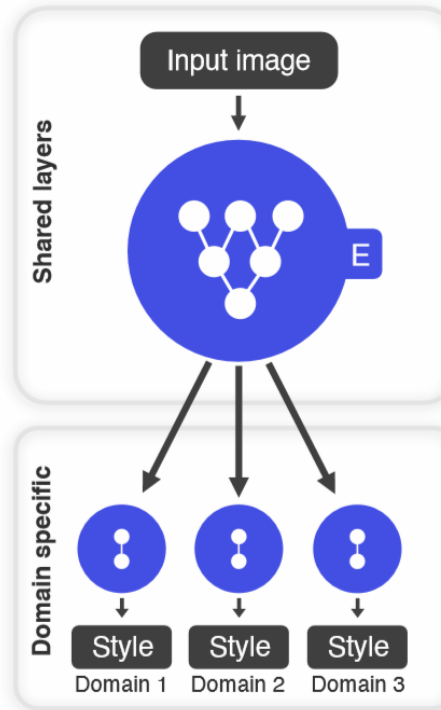
- How?
  - Multi-modal -> Encoder – Decoder
  - Multi-domain -> Single Encoder and Decoder



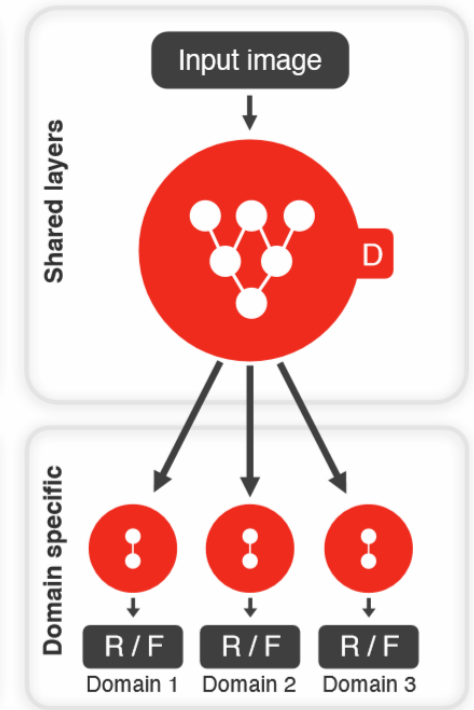
(a) Generator



(b) Mapping network

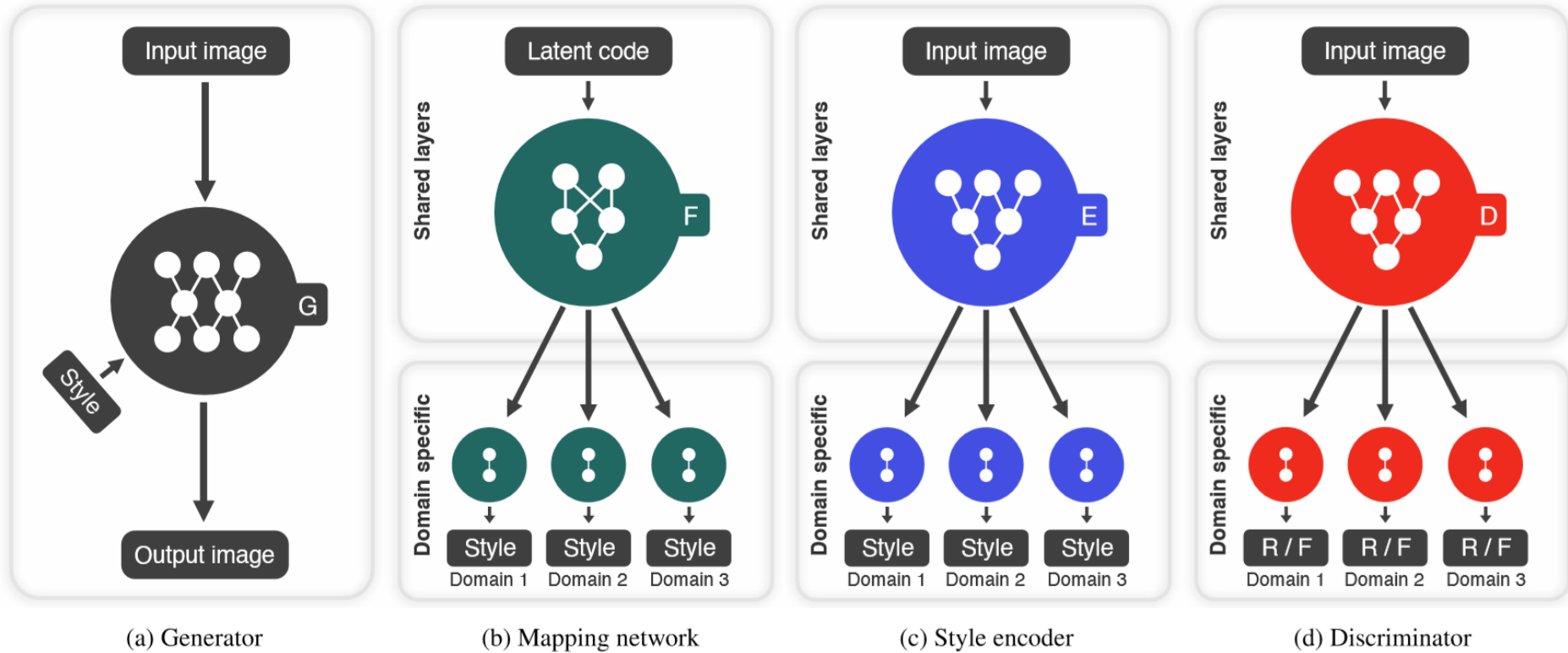


(c) Style encoder



(d) Discriminator

# Model Architecture



## How to Generate Image?

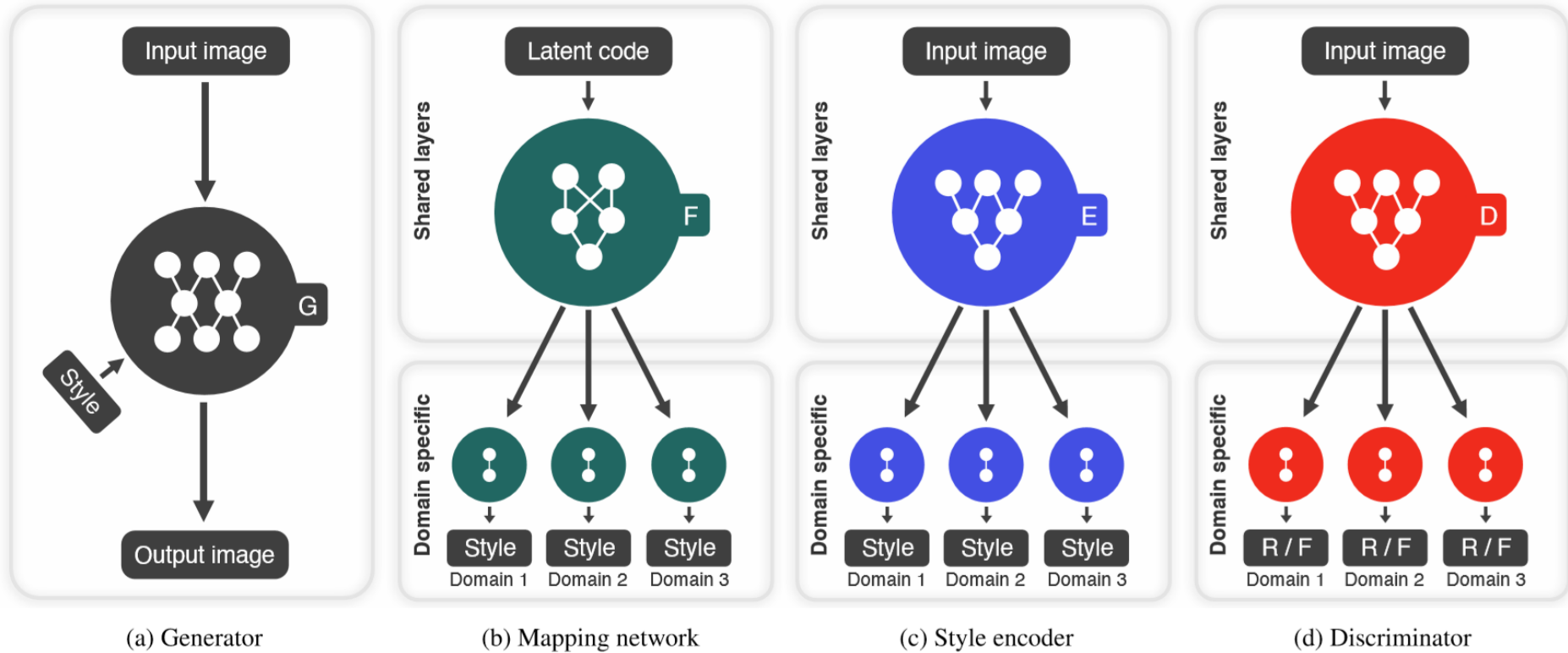
### 1. Latent-guided synthesis

- random noise  $\rightarrow$  mapping network  $\rightarrow$  style code
- translate image using style code

$$\tilde{\mathbf{s}} = F_{\tilde{y}}(\mathbf{z})$$

$$G(\mathbf{x}, \tilde{\mathbf{s}})$$

# Model Architecture



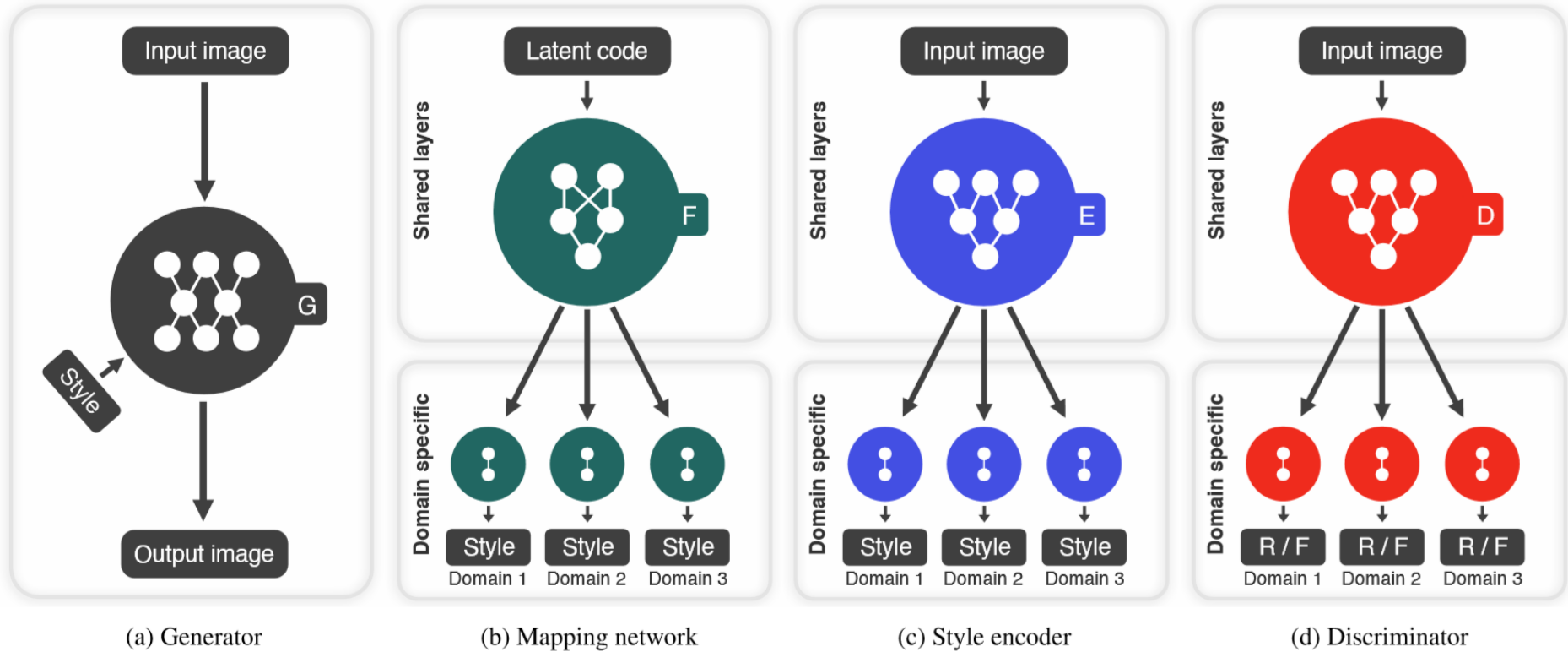
2. Reference-guided synthesis
- extract style code from reference image
  - translate image using style code

$$\tilde{s} = E_{\hat{y}}(\hat{x})$$

$$G(\mathbf{x}, \tilde{\mathbf{s}})$$



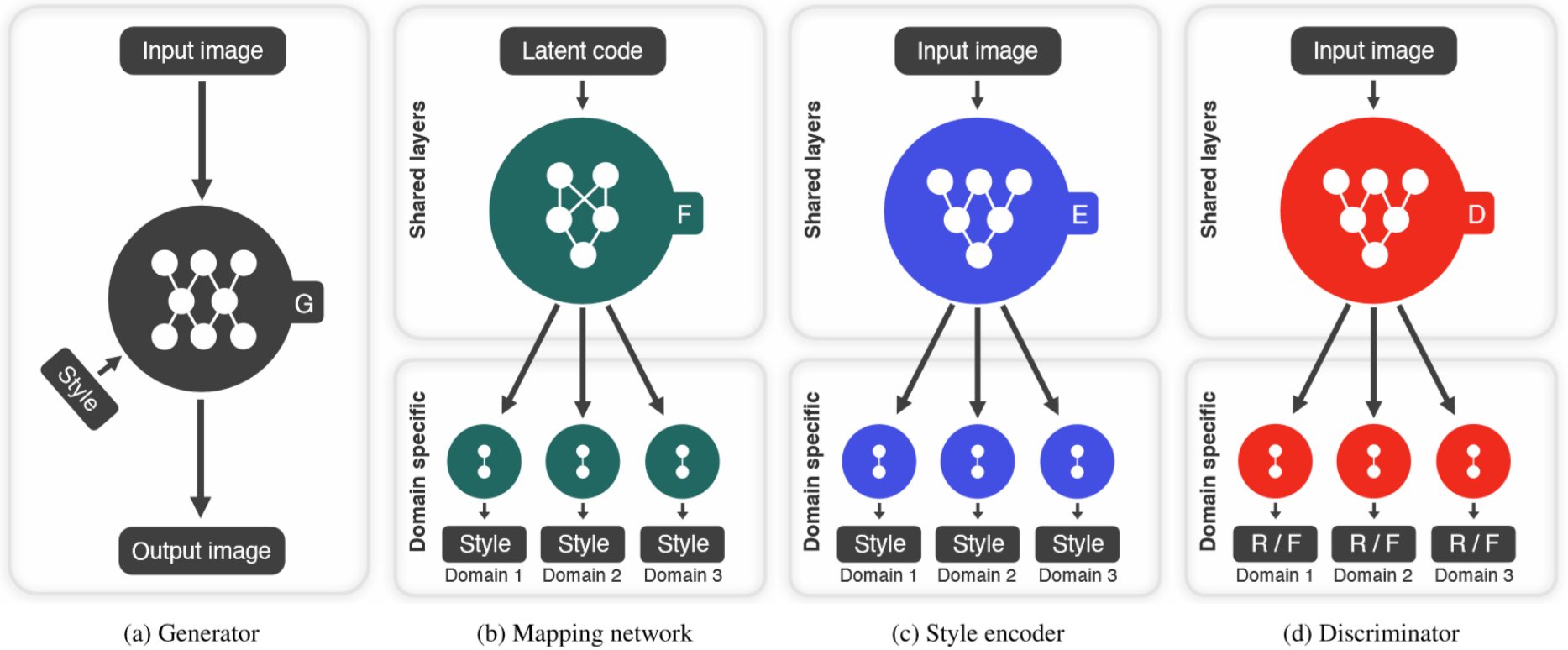
# Model Architecture



## - Adversarial Loss

$$\mathcal{L}_{adv} = \mathbb{E}_{\mathbf{x}, y} [\log D_y(\mathbf{x})] + \mathbb{E}_{\mathbf{x}, \tilde{y}, \mathbf{z}} [\log (1 - D_{\tilde{y}}(G(\mathbf{x}, \tilde{\mathbf{s}})))],$$

# Model Architecture



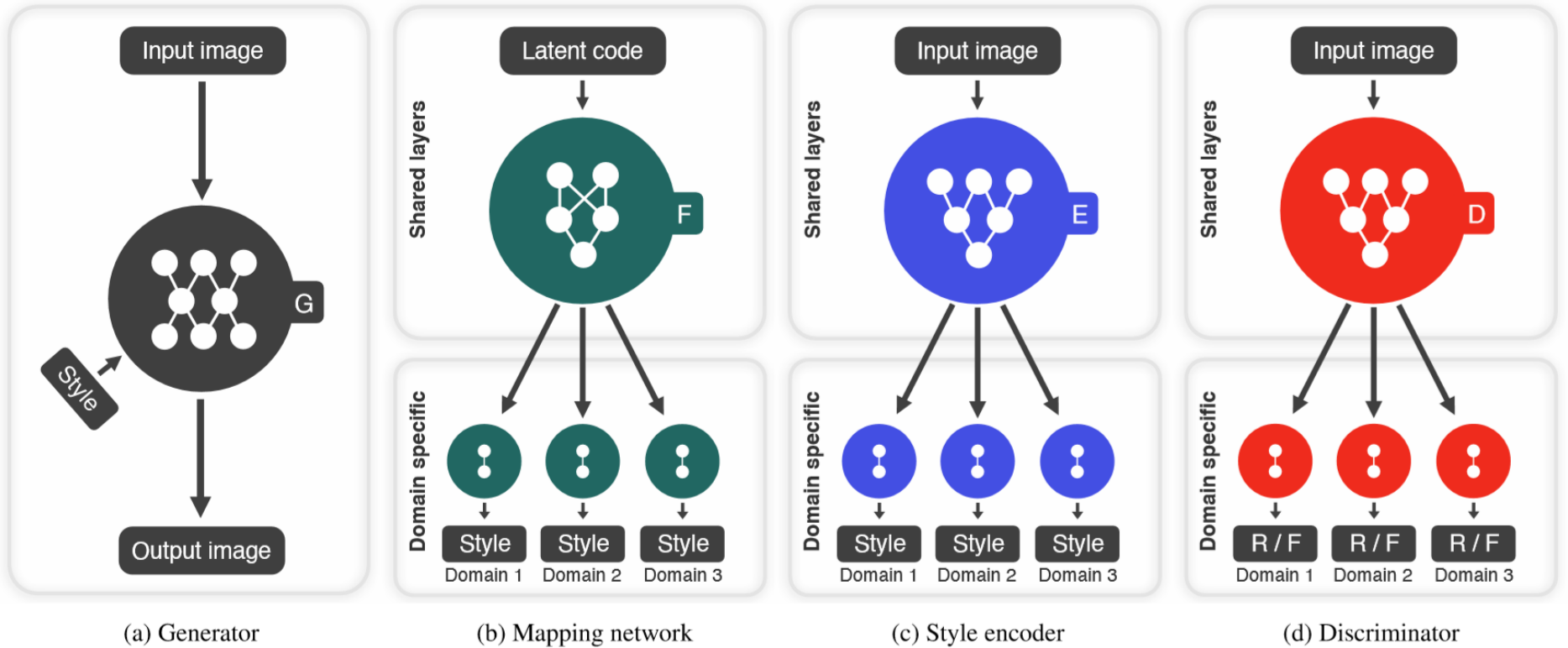
- Style Reconstruction Loss

$$\mathcal{L}_{sty} = \mathbb{E}_{\mathbf{x}, \tilde{y}, \mathbf{z}} [||\tilde{\mathbf{s}} - E_{\tilde{y}}(G(\mathbf{x}, \tilde{\mathbf{s}}))||_1]$$

$$\tilde{\mathbf{s}} = F_{\tilde{y}}(\mathbf{z})$$

$$\tilde{s} = E_{\hat{y}}(\hat{x})$$

# Model Architecture



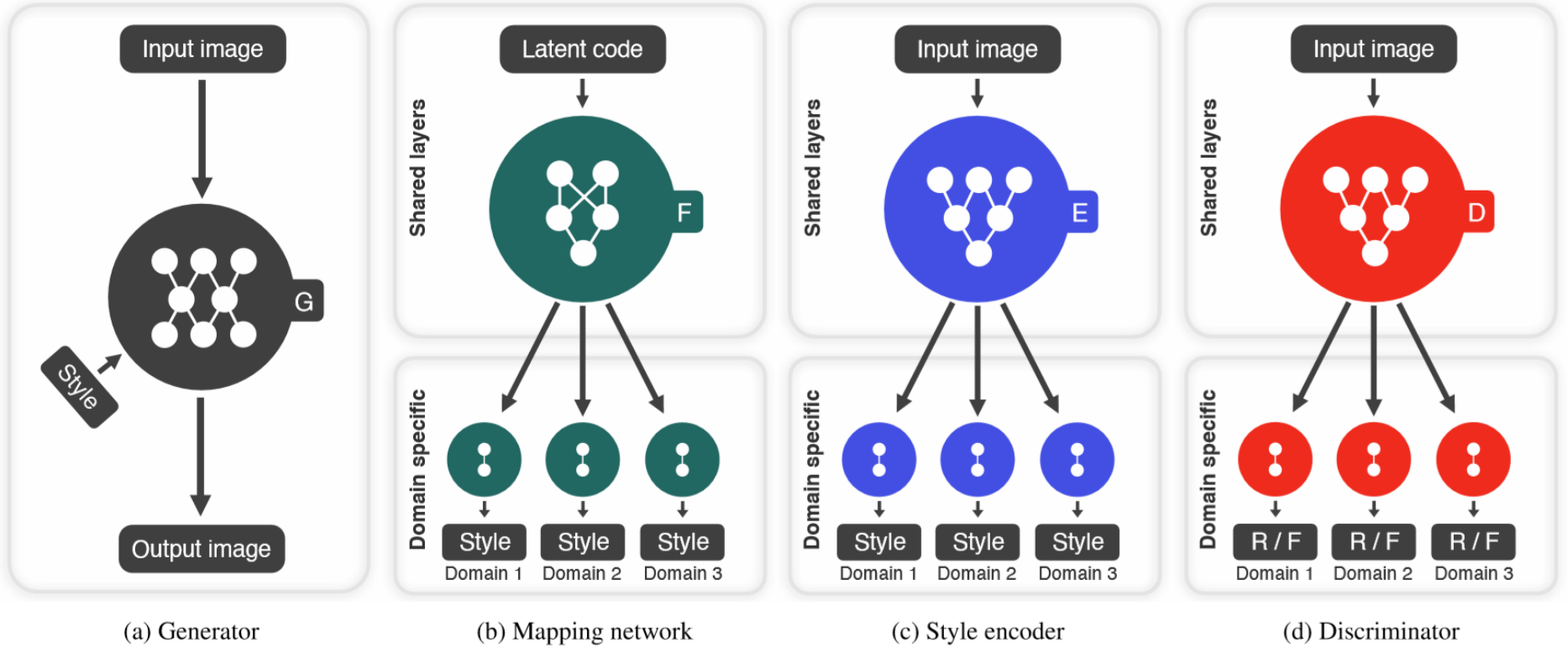
- Cycle Consistency Loss

$$\mathcal{L}_{cyc} = \mathbb{E}_{\mathbf{x}, y, \tilde{y}, \mathbf{z}} [||\mathbf{x} - G(G(\mathbf{x}, \tilde{\mathbf{s}}), \hat{\mathbf{s}})||_1]$$

$$\tilde{\mathbf{s}} = F_{\tilde{y}}(\mathbf{z})$$

$$\tilde{\mathbf{s}} = E_{\hat{y}}(\hat{\mathbf{x}})$$

# Model Architecture



- Style Diversification Loss

$$\mathcal{L}_{ds} = \mathbb{E}_{\mathbf{x}, \tilde{\mathbf{y}}, \mathbf{z}_1, \mathbf{z}_2} [\|G(\mathbf{x}, \tilde{\mathbf{s}}_1) - G(\mathbf{x}, \tilde{\mathbf{s}}_2)\|_1]$$

$$\tilde{\mathbf{s}} = F_{\tilde{\mathbf{y}}}(\mathbf{z})$$

$$\tilde{\mathbf{s}} = E_{\hat{\mathbf{y}}}(\hat{\mathbf{x}})$$

# Objective

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- Adversarial Loss

$$\mathcal{L}_{adv} = \mathbb{E}_{\mathbf{x}, y} [\log D_y(\mathbf{x})] + \mathbb{E}_{\mathbf{x}, \tilde{y}, \mathbf{z}} [\log (1 - D_{\tilde{y}}(G(\mathbf{x}, \tilde{\mathbf{s}})))],$$

- Style Reconstruction Loss

$$\mathcal{L}_{sty} = \mathbb{E}_{\mathbf{x}, \tilde{y}, \mathbf{z}} [\|\tilde{\mathbf{s}} - E_{\tilde{y}}(G(\mathbf{x}, \tilde{\mathbf{s}}))\|_1]$$

- Cycle Consistency Loss

$$\mathcal{L}_{cyc} = \mathbb{E}_{\mathbf{x}, y, \tilde{y}, \mathbf{z}} [\|\mathbf{x} - G(G(\mathbf{x}, \tilde{\mathbf{s}}), \hat{\mathbf{s}})\|_1]$$

- Style Diversification Loss

$$\mathcal{L}_{ds} = \mathbb{E}_{\mathbf{x}, \tilde{y}, \mathbf{z}_1, \mathbf{z}_2} [\|G(\mathbf{x}, \tilde{\mathbf{s}}_1) - G(\mathbf{x}, \tilde{\mathbf{s}}_2)\|_1]$$



# Objective

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- Full Objective

$$\min_{G,F,E} \max_D \mathcal{L}_{adv} + \lambda_{sty} \mathcal{L}_{sty} \\ - \lambda_{ds} \mathcal{L}_{ds} + \lambda_{cyc} \mathcal{L}_{cyc},$$

# Results

- Latent-guided Synthesis

Method	CelebA-HQ		AFHQ	
	FID	LPIPS	FID	LPIPS
MUNIT [16]	31.4	0.363	41.5	0.511
DRIT [28]	52.1	0.178	95.6	0.326
MSGAN [34]	33.1	0.389	61.4	<b>0.517</b>
StarGAN v2	<b>13.7</b>	<b>0.452</b>	<b>16.2</b>	0.450
Real images	14.8	-	12.9	-



(b) Latent-guided synthesis on AFHQ

# Results

## - Reference-guided Synthesis

Method	CelebA-HQ		AFHQ	
	FID	LPIPS	FID	LPIPS
MUNIT [16]	107.1	0.176	223.9	0.199
DRIT [28]	53.3	0.311	114.8	0.156
MSGAN [34]	39.6	0.312	69.8	0.375
StarGAN v2	<b>23.8</b>	<b>0.388</b>	<b>19.8</b>	<b>0.432</b>
Real images	14.8	-	12.9	-



(b) Reference-guided synthesis on AFHQ

# Contribution

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- **Diverse** image of **multiple domain** within **single** framework
  - multi-modal + multi-domain model
- **Visual Quality**
- **AFHQ Dataset**
  - new high quality dataset of animal faces
  - with large inter-intra domain variation

# Contribution

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- **Diverse** image of **multiple domain** within **single** framework
  - well benchmarking other papers
  - (I think..) not perfect single encoder
- **Visual Quality**
  - (I guess..) that is not because of new proposed architecture but of highly optimized training methods (styleGAN?)
- **AFHQ Dataset**
  - thank you so much, I love you. sincerely



# Contribution

LAYER	ACTVATION	NORM	OUTPUT SHAPE
Latent z	-	-	16
Linear	ReLU	-	512
Linear	ReLU	-	512
Linear	ReLU	-	512
Linear	ReLU	-	512
Linear	ReLU	-	512
Linear	ReLU	-	512
Linear * N	-	-	64 * N

Table 6. Mapping network architecture.

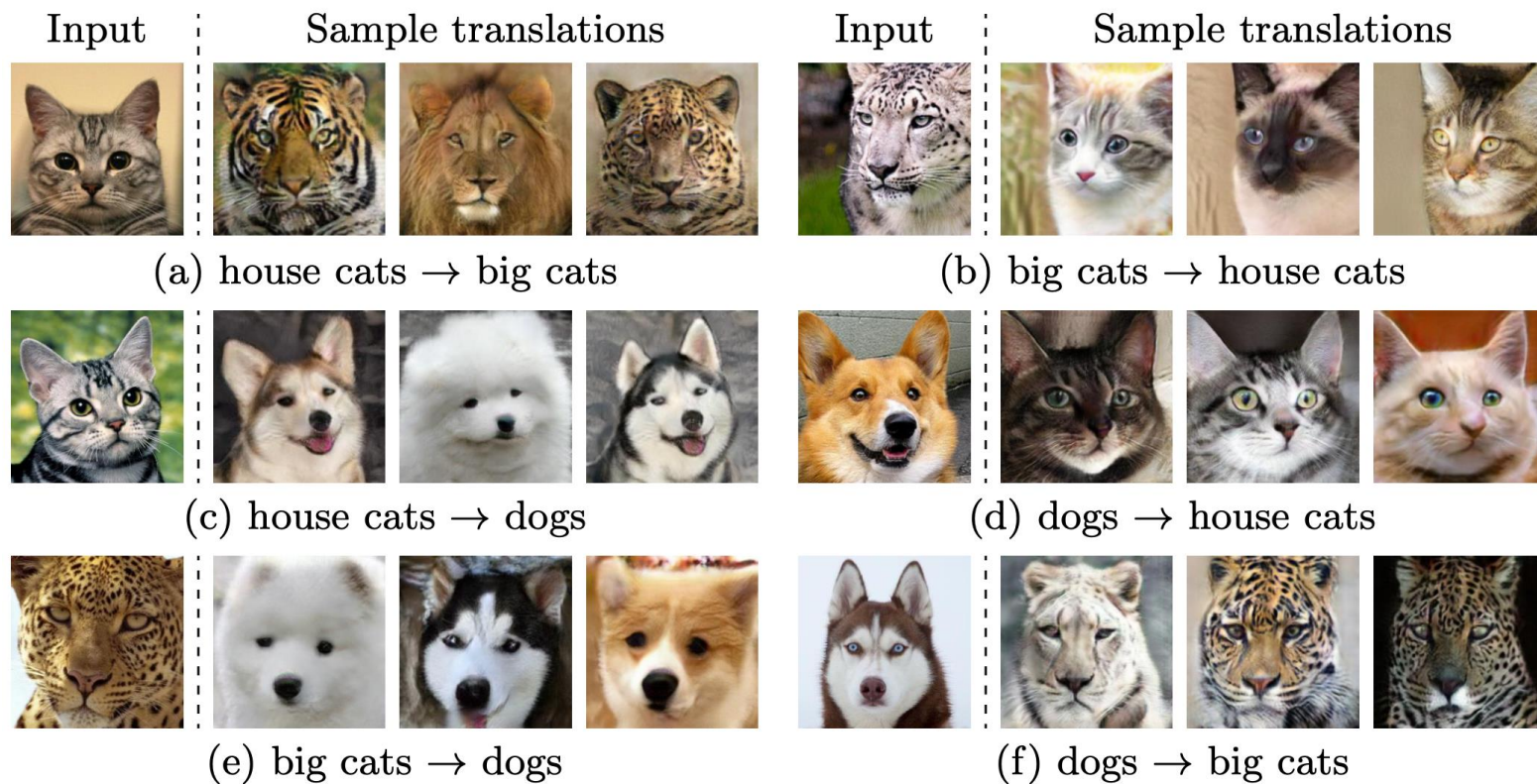
Init paper(2019.12)

TYPE	LAYER	ACTVATION	OUTPUT SHAPE
Shared	Latent z	-	16
Shared	Linear	ReLU	512
Shared	Linear	ReLU	512
Shared	Linear	ReLU	512
Shared	Linear	ReLU	512
Unshared	Linear	ReLU	512
Unshared	Linear	ReLU	512
Unshared	Linear	ReLU	512
Unshared	Linear	-	64

Table 6. Mapping network architecture.

Current

# Contribution



**Fig. 6.** Example results of animal image translation.

From MUNIT

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# Q & A

감사합니다.

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