

DS&A 3001.001
PROBABILISTIC TIME SERIES ANALYSIS
HOMEWORK 1

* PROBLEM 1 :

Considering Sample Mean as a Linear combination of Random Variables, we can find the variance in it.

$$\hat{\mu} = \frac{1}{T} \sum_{t=1}^T x_t$$

$$\text{Var}[\hat{\mu}] = \text{Var}\left[\frac{1}{T} \sum_t x_t\right]$$

$$= \frac{1}{T^2} \text{Var}\left[\sum_t x_t\right]$$

$$= \frac{1}{T^2} \sum_{i=1}^T \sum_{j=1}^T \text{Cov}(x_i, x_j)$$

Since this value is the sum of elements in the autocovariance matrix ($R(i,j)$) of size $T \times T$, and we know that

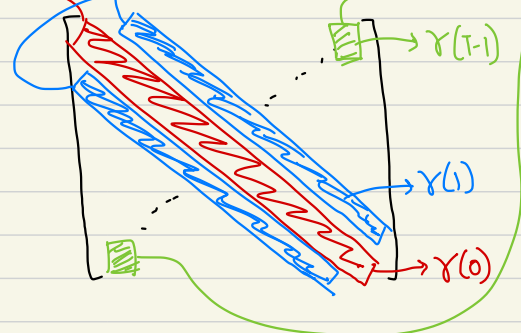
$$\textcircled{1} \text{Cov}(x_i, x_j) = \text{Cov}(x_j, x_i)$$

$$\textcircled{2} \gamma(h) = \text{Cov}(x_i, x_{i+h})$$

Since the series is stationary

$$\therefore \text{Var}[\hat{\mu}] = \frac{1}{T^2} \left[\underbrace{T \times \gamma(0)}_{\text{red}} + \underbrace{2 \times \gamma(1) \times (T-1)}_{\text{blue}} + \dots + \underbrace{2 \times \gamma(T-1) \times 1}_{\text{green}} \right]$$

$R(i,j) =$



$$\therefore \text{Var}[\hat{\mu}] = \frac{1}{T^2} \left[T \times \gamma(0) + \sum_{h=1}^{T-1} 2 \times \gamma(h) \times (T-h) \right]$$

$$= \frac{\gamma(0)}{T} + \frac{2}{T^2} \sum_{h=1}^{T-1} \gamma(h) \times (T-h)$$



[NEXT PAGE]

* Problem 2

Let $X_t = W_t$

This process satisfies the definition of linear process (1.12)

Definition 1.12 A linear process, x_t , is defined to be a linear combination of white noise variates w_t , and is given by

$$x_t = \mu + \sum_{j=-\infty}^{\infty} \psi_j w_{t-j}, \quad \sum_{j=-\infty}^{\infty} |\psi_j| < \infty. \quad (1.31)$$

where we can set $\mu = 0$ & $\psi_j = \begin{cases} 0 & ; j \neq 0 \\ 1 & ; j = 0 \end{cases}$

Hence, we can apply theorem A.7, which is

Theorem A.7 If x_t is a stationary linear process of the form (1.31) satisfying the fourth moment condition (A.49), then for fixed K ,

$$\begin{pmatrix} \hat{\rho}(1) \\ \vdots \\ \hat{\rho}(K) \end{pmatrix} \sim AN \left[\begin{pmatrix} \rho(1) \\ \vdots \\ \rho(K) \end{pmatrix}, n^{-1} W \right],$$

where W is the matrix with elements given by

$$\begin{aligned} w_{pq} &= \sum_{u=-\infty}^{\infty} \left[\rho(u+p)\rho(u+q) + \rho(u-p)\rho(u+q) + 2\rho(p)\rho(q)\rho^2(u) \right. \\ &\quad \left. - 2\rho(p)\rho(u)\rho(u+q) - 2\rho(q)\rho(u)\rho(u+p) \right] \\ &= \sum_{u=1}^{\infty} [\rho(u+p) + \rho(u-p) - 2\rho(p)\rho(u)] \\ &\quad \times [\rho(u+q) + \rho(u-q) - 2\rho(q)\rho(u)], \end{aligned} \quad (A.54)$$

where the last form is more convenient.

Covariance Matrix of ACF is given by

$$n^{-1} W = \frac{1}{T} W \quad (\because \text{we have } T \text{ data points})$$

$$\begin{aligned} w_{pq} &= \sum_{u=1}^{\infty} [\rho(u+p) + \rho(u-p) - 2\rho(p)\rho(u)] \\ &\quad \times [\rho(u+q) + \rho(u-q) - 2\rho(q)\rho(u)] \end{aligned}$$

For the given stationary process, we know that

$$\rho(h) = \begin{cases} 1 & ; h = 0 \\ 0 & ; \text{otherwise} \end{cases}$$

Using the above conditions on A.54
we get

$$w_{pq} = \begin{cases} 1 & ; p = q \\ 0 & ; \text{otherwise} \end{cases}$$

$$\therefore W = Id_T$$

\therefore Covariance matrix of ACF

$$= \frac{1}{T} W = \frac{1}{T} Id_T$$

$$\therefore \text{Cov}(\text{ACF}(i), \text{ACF}(j)) = \begin{cases} \frac{1}{T} & ; i = j \\ 0 & ; \text{otherwise} \end{cases}$$

$$\therefore \text{Var}(\text{ACF}(i)) = \frac{1}{T} \quad \forall i$$

PROOF:

$$X_t = W_t \sim N(0, \sigma^2)$$

$$\text{Cov}(X_i, X_j) = \begin{cases} \sigma^2 & ; i = j \\ 0 & ; \text{otherwise} \end{cases}$$

$$\rho_X(i, j) = \begin{cases} \frac{\sigma^2}{\sigma^2} & ; i = j \\ 0 & ; \text{otherwise} \end{cases}$$

$$\text{ACF}(h) = \begin{cases} 1 & ; h = 0 \\ 0 & ; \text{otherwise} \end{cases}$$

```
In [1]: import numpy as np
from statsmodels.tsa.stattools import acf
from statsmodels.graphics.tsaplots import plot_acf
import matplotlib.pyplot as plt
```

```
In [2]: ts = []
var_acfs = []
by_ts = []

for t in range(500, 2500, 3):
    acfs = []
    for i in range(500):
        y = np.random.normal(0, 1, t)
        acfs.append(acf(y))

    acfs = np.array(acfs)
    var_acfs.append(np.var(acfs, axis=0))

    by_ts.append(1/t)
    ts.append(t)
```

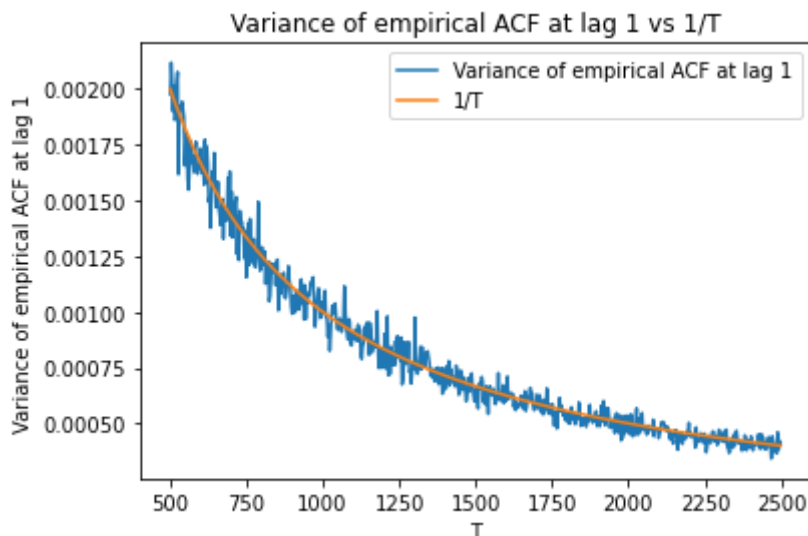
```
/usr/local/anaconda3/envs/pTSA/lib/python3.8/site-packages/statsmodels/
tsa/stattools.py:652: FutureWarning: The default number of lags is chan
ging from 40 to min(int(10 * np.log10(nobs)), nobs - 1) after 0.12 is rel
eased. Set the number of lags to an integer to silence this warning.
    warnings.warn(
/usr/local/anaconda3/envs/pTSA/lib/python3.8/site-packages/statsmodels/
tsa/stattools.py:662: FutureWarning: fft=True will become the default a
fter the release of the 0.12 release of statsmodels. To suppress this w
arning, explicitly set fft=False.
    warnings.warn(
```

```
In [3]: np.array(var_acfs).shape
```

```
Out[3]: (667, 41)
```

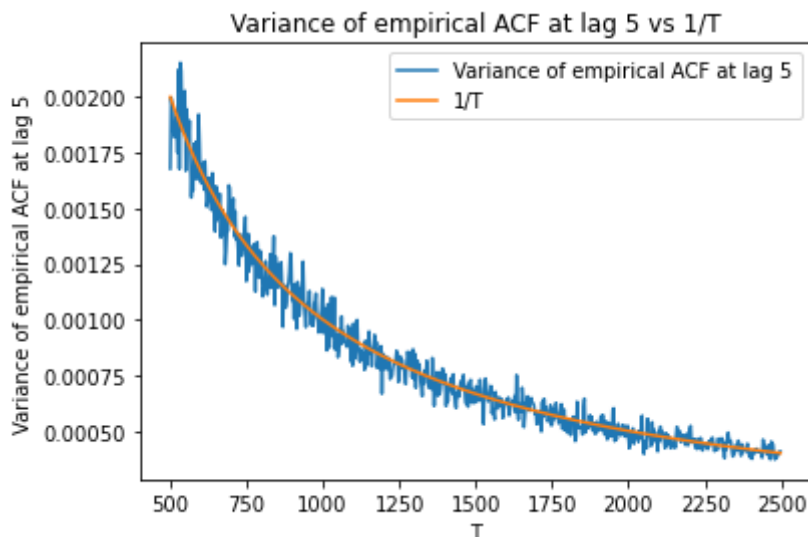
```
In [4]: h=1
plt.plot(ts, np.array(var_acfs).T[h], label=f'Variance of empirical ACF
        at lag {h}')
plt.plot(ts, by_ts, label='1/T')
plt.title(f'Variance of empirical ACF at lag {h} vs 1/T')
plt.xlabel('T')
plt.ylabel(f'Variance of empirical ACF at lag {h}')
plt.legend()
```

Out[4]: <matplotlib.legend.Legend at 0x7f8ee4cc9d90>



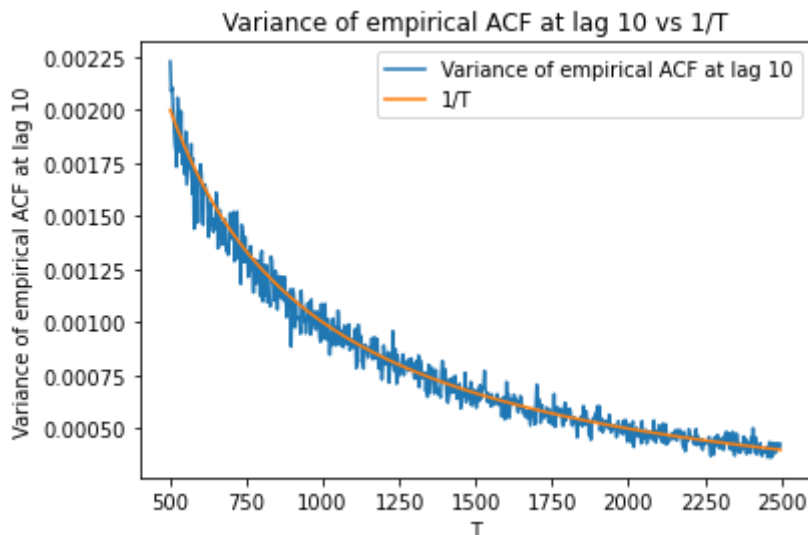
```
In [5]: h=5
plt.plot(ts, np.array(var_acfs).T[h], label=f'Variance of empirical ACF
        at lag {h}')
plt.plot(ts, by_ts, label='1/T')
plt.title(f'Variance of empirical ACF at lag {h} vs 1/T')
plt.xlabel('T')
plt.ylabel(f'Variance of empirical ACF at lag {h}')
plt.legend()
```

Out[5]: <matplotlib.legend.Legend at 0x7f8ee4e58b80>



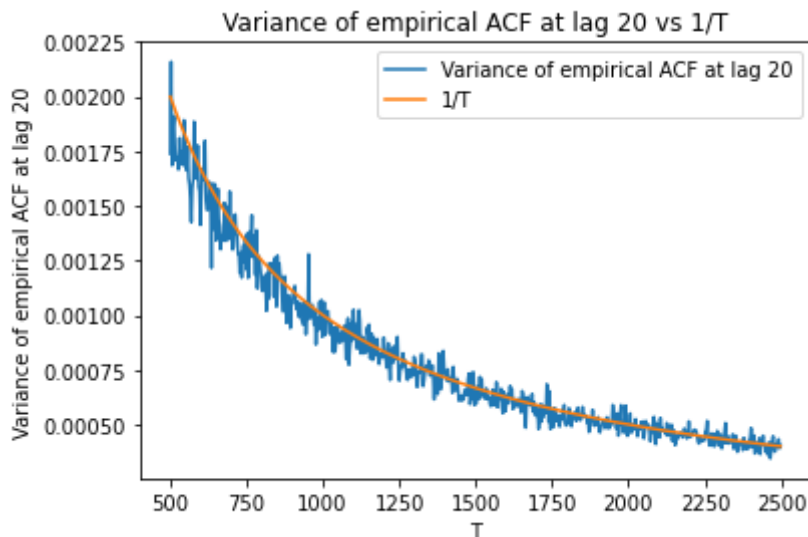
```
In [6]: h=10
plt.plot(ts, np.array(var_acfs).T[h], label=f'Variance of empirical ACF
        at lag {h}')
plt.plot(ts, by_ts, label='1/T')
plt.title(f'Variance of empirical ACF at lag {h} vs 1/T')
plt.xlabel('T')
plt.ylabel(f'Variance of empirical ACF at lag {h}')
plt.legend()
```

Out[6]: <matplotlib.legend.Legend at 0x7f8ee4e6c700>



```
In [7]: h=20
plt.plot(ts, np.array(var_acfs).T[h], label=f'Variance of empirical ACF
        at lag {h}')
plt.plot(ts, by_ts, label='1/T')
plt.title(f'Variance of empirical ACF at lag {h} vs 1/T')
plt.xlabel('T')
plt.ylabel(f'Variance of empirical ACF at lag {h}')
plt.legend()
```

Out[7]: <matplotlib.legend.Legend at 0x7f8ee523d8e0>



* PROBLEM 3

$$MA(1) : x_t = w_t + \theta w_{t-1}$$

Now

$$\begin{aligned} \text{Var}(x_t) &= E[(x_t - E[x_t])^2] \\ &= E[x_t^2] \\ &= E[(w_t + \theta w_{t-1})^2] \\ &= E[w_t^2 + 2\theta w_t w_{t-1} + \theta^2 w_{t-1}^2] \\ &= E[w_t^2] + 2\theta E[w_t w_{t-1}] + \theta^2 E[w_{t-1}^2] \\ &= \text{Var}(w_t) - E^2[w_t] + 2\theta E[w_t]E[w_{t-1}] + \theta^2 (\text{Var}(w_{t-1}) - E^2[w_{t-1}]) \\ &= \sigma^2 - 0^2 + 2\theta(0)(0) + \theta^2 (\sigma^2 - 0^2) \\ &= \sigma^2 + \theta^2 \sigma^2 = (1 + \theta^2) \sigma^2 \end{aligned}$$

$$\begin{aligned} \text{Cov}(x_t, x_u) &= E[(x_t - E[x_t])(x_u - E[x_u])] \\ &= E[(x_t - 0)(x_u - 0)] = E[x_t x_u] \\ &= E[(w_t + \theta w_{t-1})(w_u + \theta w_{u-1})] \\ &= E[w_t w_u + \theta w_t w_{u-1} + \theta w_{t-1} w_u + \theta^2 w_{t-1} w_{u-1}] \\ &= E[w_t w_u] + \theta E[w_t w_{u-1}] + \theta E[w_{t-1} w_u] + \theta^2 E[w_{t-1} w_{u-1}] \end{aligned}$$

$$\therefore \text{Cov}(x_t, x_u) = \begin{cases} E[w_t^2] + 0 + 0 + \theta^2 E[w_{t-1}^2] & ; t = u \\ 0 + \theta E[w_t^2] + 0 + 0 & ; t = u-1 \\ 0 + 0 + \theta E[w_u^2] + 0 & ; t = u+1 \\ 0 + 0 + 0 + 0 & ; \text{otherwise} \end{cases}$$

$$= \begin{cases} \sigma^2 (1 + \theta^2) & ; t = u \\ \theta \sigma^2 & ; t = u-1 \\ \theta \sigma^2 & ; t = u+1 \\ 0 & ; \text{otherwise} \end{cases}$$

$$= \begin{cases} \sigma^2(1+\theta^2) & ; t=u \\ \theta \sigma^2 & ; |t-u|=1 \\ 0 & ; \text{otherwise.} \end{cases}$$

$$\therefore p_x(h) = \begin{cases} \sigma^2(1+\theta^2) / \sigma^2(1+\theta^2) & ; h=0 \\ \theta \sigma^2 / \sigma^2(1+\theta^2) & ; |h|=1 \\ 0 & ; \text{otherwise} \end{cases}$$

$$= \begin{cases} 1 & ; h=0 \\ \theta / (1+\theta^2) & ; |h|=1 \\ 0 & ; \text{otherwise.} \end{cases}$$

Now we have to prove :

$$|p_x(h)| \leq 0.5$$

$$-0.5 \leq p_x(h) \leq 0.5$$

$$-0.5 \leq \frac{\theta}{1+\theta^2} \leq 0.5$$

$$\text{OR } \theta^2 - 2\theta + 1 \geq 0 \quad \text{AND} \quad \theta^2 + 2\theta + 1 \geq 0$$

$$(\theta-1)^2 \geq 0 \quad \text{AND} \quad (\theta+1)^2 \geq 0$$

Both these conditions are always true, hence proved! □

argmax / argmin of $p(i)$ = ?

$$p(i) = \frac{\theta}{1+\theta^2}$$

To find maximizers / minimizers

$$\frac{dp(i)}{d\theta} = 0$$

$$\therefore \frac{d\left(\frac{\theta}{1+\theta^2}\right)}{d\theta} = 0$$

$$\frac{(1+\theta^2)(1) - \theta(2\theta)}{(1+\theta^2)^2} = 0$$

$$\therefore 1 - \theta^2 = 0 \quad [\text{since } (1 + \theta^2)^2 \text{ cannot be equal to } 0]$$

$$\therefore \theta^2 = 1$$

$$\therefore \theta = \pm 1$$

$$p_{x|\theta=1}(1) = \frac{1}{1+1^2} = 0.5$$

$$p_{x|\theta=-1}(1) = \frac{-1}{1+(-1)^2} = -0.5$$

$\therefore p_x(1)$ is maximum at $\theta = 1$ & minimum at $\theta = -1$

* PROBLEM 4

$$i) \quad x_t = 0.8x_{t-1} - 0.15x_{t-2} + w_t - 0.3w_{t-1}$$

$$x_t - 0.8x_{t-1} + 0.15x_{t-2} = w_t - 0.3w_{t-1}$$

$$\therefore (1 - 0.8B + 0.15B^2)x_t = (1 - 0.3B)w_t$$

$$\therefore \theta(B) = (1 - 0.3B)$$

$$\phi(B) = (1 - 0.8B + 0.15B^2) = (1 - 0.3B)(1 - 0.5B)$$

After eliminating common factors

$$\theta(B) = 1$$

$$\phi(B) = (1 - 0.5B)$$

$$\therefore (1 - 0.5B)x_t = w_t$$

$$x_t - 0.5x_{t-1} = w_t$$

$$x_t = 0.5x_{t-1} + w_t$$

$$\therefore \text{ARMA}(1, 0)$$

$$ii) \quad x_t = x_{t-1} - 0.5x_{t-2} + w_t - w_{t-1}$$

$$\therefore x_t - x_{t-1} + 0.5x_{t-2} = w_t - w_{t-1}$$

$$(1 - B + 0.5B^2)x_t = (1 - B)w_t$$

↪ Complex roots

\therefore No common factors.

$$\therefore \text{ARMA}(2, 1)$$

* PROBLEM 5

a) MA(3)

$$x_t = \omega_t + \phi_1 \omega_{t-1} + \phi_2 \omega_{t-2} + \phi_3 \omega_{t-3}$$

Given: $\{x_1, x_2, \dots, x_t\}$

Assume that we know $\omega_{-2}, \omega_{-1}, \omega_0$ & parameters of model (ϕ_i)

$$\text{then } \omega_1 = x_1 - \phi_1 \omega_0 - \phi_2 \omega_{-1} - \phi_3 \omega_{-2}$$

$$\omega_2 = x_2 - \phi_1 \omega_1 - \phi_2 \omega_0 - \phi_3 \omega_{-1}$$

\vdots

$$\omega_t = x_t - \phi_1 \omega_{t-1} - \phi_2 \omega_{t-2} - \phi_3 \omega_{t-3}$$

$$E[x_{t+1} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= E[\omega_{t+1} + \phi_1 \omega_t + \phi_2 \omega_{t-1} + \phi_3 \omega_{t-2} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= 0 + \phi_1 \omega_t + \phi_2 \omega_{t-1} + \phi_3 \omega_{t-2}$$

Similarly,

$$\Rightarrow E[x_{t+2} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= E[\omega_{t+2} + \phi_1 \omega_{t+1} + \phi_2 \omega_t + \phi_3 \omega_{t-1} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= 0 + \phi_1(0) + \phi_2 \omega_t + \phi_3 \omega_{t-1} = \phi_2 \omega_t + \phi_3 \omega_{t-1}$$

$$\Rightarrow E[x_{t+3} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= E[\omega_{t+3} + \phi_1 \omega_{t+2} + \phi_2 \omega_{t+1} + \phi_3 \omega_t | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= 0 + \phi_1(0) + \phi_2(0) + \phi_3 \omega_t = \phi_3 \omega_t$$

$$\Rightarrow E[x_{t+4} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= E[\omega_{t+4} + \phi_1 \omega_{t+3} + \phi_2 \omega_{t+2} + \phi_3 \omega_{t+1} | \{x_1, \dots, x_t; \omega_1, \dots, \omega_t\}]$$

$$= 0 + \phi_1(0) + \phi_2(0) + \phi_3(0) = 0$$

$$\text{Error} = x_{t+h} - E[x_{t+h} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]$$

Variances in error for different h :

$$\begin{aligned} \therefore \Rightarrow \text{Var}(x_{t+1} - E[x_{t+1} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]) \\ = \text{Var}((w_{t+1} + \phi_1 w_t + \phi_2 w_{t-1} + \phi_3 w_{t-2}) - (\phi_1 w_t + \phi_2 w_{t-1} + \phi_3 w_{t-2})) \\ = \text{Var}(w_{t+1}) \\ = \sigma^2 \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{Var}(x_{t+2} - E[x_{t+2} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]) \\ = \text{Var}((w_{t+2} + \phi_1 w_{t+1} + \phi_2 w_t + \phi_3 w_{t-1}) - (\phi_2 w_t + \phi_3 w_{t-1})) \\ = \text{Var}(w_{t+2} + \phi_1 w_{t+1}) \\ = \sigma^2 + \phi_1^2 \sigma^2 \\ = (1 + \phi_1^2) \sigma^2 \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{Var}(x_{t+3} - E[x_{t+3} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]) \\ = \text{Var}((w_{t+3} + \phi_1 w_{t+2} + \phi_2 w_{t+1} + \phi_3 w_t) - (\phi_3 w_t)) \\ = (1 + \phi_1^2 + \phi_2^2) \sigma^2 \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{Var}(x_{t+4} - E[x_{t+4} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]) \\ = \text{Var}(w_{t+4} + \phi_1 w_{t+3} + \phi_2 w_{t+2} + \phi_3 w_{t+1}) \\ = (1 + \phi_1^2 + \phi_2^2 + \phi_3^2) \sigma^2 \end{aligned}$$

$$\therefore \text{Var}(x_{t+h} - E[x_{t+h} | \{x_1, \dots, x_t; w_1, \dots, w_t\}]) = \begin{cases} \sigma^2 & ; h=1 \\ (1 + \sum_{u=1}^{h-1} \phi_u^2) \sigma^2 & ; 1 < h \leq 4 \\ (1 + \sum_{u=1}^3 \phi_u^2) \sigma^2 & ; \text{otherwise} \end{cases}$$

\therefore As h increases, uncertainty in our prediction increases (prediction power decreases), because of increase in variance of the error. For $h \in \{5, 6, \dots, \infty\}$, variance in error is constant but very high.

b) AR(1) model

$$x_t = \lambda x_{t-1} + w_t$$

$$\text{Given : } \{x_1, x_2, \dots, x_t\}$$

$$\begin{aligned} E[x_{t+1} | \{x_1, x_2, \dots, x_t; \lambda\}] &= E[\lambda x_t + w_{t+1} | \{x_1, \dots, x_t; \lambda\}] \\ &= E[\lambda x_t] + 0 = \lambda x_t \end{aligned}$$

$$\begin{aligned} E[x_{t+2} | \{x_1, \dots, x_t; \lambda\}] &= E[\lambda x_{t+1} + w_{t+2} | \{x_1, \dots, x_t; \lambda\}] \\ &= \lambda E[x_{t+1} | \{x_1, \dots, x_t; \lambda\}] + 0 \\ &= \lambda^2 x_t \end{aligned}$$

$$\begin{aligned} E[x_{t+3} | \{x_1, \dots, x_t; \lambda\}] &= E[\lambda x_{t+2} + w_{t+3} | \{x_1, \dots, x_t; \lambda\}] \\ &= \lambda E[x_{t+2} | \{x_1, \dots, x_t; \lambda\}] + 0 \\ &= \lambda^3 x_t \end{aligned}$$

$$\therefore E[x_{t+h} | \{x_1, \dots, x_t; \lambda\}] = \lambda^h x_t, \quad h \geq 1$$

$$\text{Error} = x_{t+h} - E[x_{t+h} | \{x_1, \dots, x_t; \lambda\}]$$

Var(Error) for different h :

$$\Rightarrow h = 1$$

$$\begin{aligned} \text{Var(Error)} &= \text{Var}(x_{t+1} - E[x_{t+1} | \{x_1, \dots, x_t\}]) \\ &= \text{Var}(\lambda x_t + w_{t+1} - \lambda x_t) \\ &= \text{Var}(w_{t+1}) \\ &= \sigma^2 \end{aligned}$$

$$\Rightarrow h = 2$$

$$\begin{aligned}
\text{Var}(\text{error}) &= \text{Var}(x_{t+2} - E[x_{t+2} | \{x_1, \dots, x_t; \lambda\}]) \\
&= \text{Var}(\lambda(\lambda x_t + w_{t+1}) + w_{t+2} - \lambda^2 x_t) \\
&= \text{Var}(\lambda w_{t+1} + w_{t+2}) \\
&= \lambda^2 \sigma^2 + \sigma^2 \\
&= (1 + \lambda^2) \sigma^2
\end{aligned}$$

$$\Rightarrow h = 3$$

$$\begin{aligned}
\text{Var}(\text{error}) &= \text{Var}(x_{t+3} - E[x_{t+3} | \{x_1, \dots, x_t; \lambda\}]) \\
&= \text{Var}(\lambda^3 x_t + \lambda^2 w_{t+1} + \lambda w_{t+2} + w_{t+3} - \lambda^3 x_t) \\
&= \text{Var}(\lambda^2 w_{t+1} + \lambda w_{t+2} + w_{t+3}) \\
&= (1 + \lambda^2 + \lambda^4) \sigma^2
\end{aligned}$$

$$\therefore \text{Var}(\text{error}) = \sigma^2 \sum_{u=0}^{h-1} (\lambda^u)^2, \quad h \geq 1$$

It converges to :

$$\text{Var}(\text{error}) = \frac{\sigma^2}{1 - \lambda^2} \quad [\text{By sum of } \infty \text{ geometric series \& since } |\lambda| < 1]$$

Again, the predictive power decrease with a bigger h since the variance in error increases and it converges to $\frac{\sigma^2}{1 - \lambda^2}$ for

a very big h .

* PROBLEM 6

$$\text{AR}(2) \text{ process} \rightarrow P(B) = (1 - 0.2B)(1 - 0.5B)$$

$$\begin{aligned} \therefore P(B) &= 1 - 0.5B - 0.2B + 0.1B^2 \\ &= 1 - 0.7B + 0.1B^2 \end{aligned}$$

$$\therefore \text{AR}(2) \text{ process} \mapsto x_t - 0.7x_{t-1} + 0.1x_{t-2} = w_t$$

$$\therefore x_t = 0.7x_{t-1} - 0.1x_{t-2} + w_t$$

$$\therefore x_t x_{t-h} = 0.7x_{t-1}x_{t-h} - 0.1x_{t-2}x_{t-h} + w_t x_{t-h}$$

$$E[x_t x_{t-h}] = 0.7 E[x_{t-1} x_{t-h}] - 0.1 E[x_{t-2} x_{t-h}] + E[w_t x_{t-h}]$$

$$\therefore \gamma(h) = 0.7 \gamma(h-1) - 0.1 \gamma(h-2) + 0$$

$$\therefore \rho(h) = 0.7 \rho(h-1) - 0.1 \rho(h-2)$$

OR

$$\rho(h) - 0.7 \rho(h-1) + 0.1 \rho(h-2) = 0$$

$$\therefore \rho(1) - 0.7 \rho(0) + 0.1 \rho(-1) = 0 \rightarrow (1)$$

$$\rho(2) - 0.7 \rho(1) + 0.1 \rho(0) = 0 \rightarrow (2)$$

We know that $\rho(0) = 1$ & $\rho(-h) = \rho(h)$

\therefore From (1)

$$1.1 \rho(1) - 0.7 = 0 \rightarrow \rho(1) = \frac{0.7}{1.1} = 0.6363$$

\therefore From (2)

$$\rho(2) - (0.7)(0.6363) + 0.1 = 0$$

$$\begin{aligned} \rho(2) &= (0.7)(0.6363) - 0.1 \\ &= 0.34541 \end{aligned}$$

$$x_t = 0.7 * x_{t-1} - 0.1 * x_{t-2} + w_t$$

```
In [1]: import numpy as np
from statsmodels.tsa.stattools import acf
from statsmodels.graphics.tsaplots import plot_acf
import matplotlib.pyplot as plt
```

```
In [2]: def acf_impl(x, nlags):
        """
        TODO
        @param x: a 1-d numpy array (data)
        @param nlags: an integer indicating how far back to compute the ACF
        @return a 1-d numpy array with (nlags+1) elements.
                Where the first element denotes the acf at lag = 0 (1.0 by d
        e finition).
        """
        mean_x = x.mean()
        acfs = []

        acf_0 = 0
        for i in range(0, len(x)):
            acf_0 = acf_0 + ((x[i] - mean_x) * (x[i] - mean_x))
        acf_0 = acf_0 / len(x)

        for j in range(nlags+1):
            total = 0
            for i in range(0, len(x)-j):
                total = total + ((x[i+j] - mean_x) * (x[i] - mean_x))
            total = total / len(x)
            total = total / acf_0
            acfs.append(total)

        return acfs
```

```

In [3]: # Analytical ACF calculations
phi_1 = 0.7
phi_2 = -0.1

rho_1 = phi_1 / (1 - phi_2)
rho_2 = ((phi_1 * phi_1)/(1 - phi_2)) + phi_2

print(f"Analytical -> rho_1 = {rho_1}, rho_2 = {rho_2}")

# Data simulation for empirical ACF
x_a, x_b = np.random.normal(0, 1), np.random.normal(0, 1) # Initially series equal to white noise with variance 1

n = 10000
x = []
for i in range(n):
    x.append(0.7 * x_a - 0.1 * x_b + np.random.normal(0, 1))
    x_b = x_a
    x_a = x[-1]
x = np.array(x)
transient = 1000
x = x[transient::]

# Estimated ACF calculation
acf_val = acf_impl(x=x, nlags=2)

# Plots
print(f"Empirical -> rho_1 = {acf_val[1]}, rho_2 = {acf_val[2]}")
plt.figure()
plt.plot(acf_val, 'or', label='statsmodels empirical acf')
plt.plot([1, rho_1, rho_2], 'xb', label='own acf')
plt.legend();
plt.title('Empirical ACF vs Analytical ACF')

```

Analytical -> rho_1 = 0.6363636363636362, rho_2 = 0.34545454545454535
 Empirical -> rho_1 = 0.6291197014298906, rho_2 = 0.33906375999370325

Out[3]: Text(0.5, 1.0, 'Empirical ACF vs Analytical ACF')

