

# Computer Architecture Laboratory

## *ToyRISC* Specification

## 1 Specification

### 1.1 Memory Model

The memory space is of 256kB. Each word is 4 bytes long, and the memory is word-addressable. That is, a total of  $2^{16}$  words may be stored. These include the program instructions, the static data, and the stack.

### 1.2 Register

There are a total of 32 registers: **x0** to **x31**. Each register is 4 bytes wide.

Table 1: Registers in the custom ISA

Register	Purpose
<b>x0</b>	Zero Register
<b>x1</b>	Stack Pointer
<b>x2</b>	Frame Pointer
<b>x3 to x30</b>	General purpose
<b>x31</b>	Special behavior, according to particular instruction
<b>PC</b>	Program Counter

### Encoding

32 registers require 5 bits for encoding. **x0** is encoded as 00000, **x1** as 00001, and so on.

### 1.3 Instruction Formats

Table 2 lists the 3 instruction formats in our custom ISA.

#### 1.3.1 Arithmetic Instructions

Table 3 lists the different arithmetic instructions.

#### 1.3.2 Memory Instructions

Table 4 lists the different memory instructions in our custom ISA.

Table 2: Instruction formats in the custom ISA

R3-Type				
opcode	rs1	rs2	rd	unused
5 bits	5 bits	5 bits	5 bits	12 bits

  

R2I-Type			
opcode	rs1	rd	immediate
5 bits	5 bits	5 bits	17 bits

  

RI-Type		
opcode	rd	immediate
5 bits	5 bits	22 bits

Table 3: Arithmetic instructions in the custom ISA

Operation	Opcode	Format	Description
add	00000	R3-Type	$rd = rs1 + rs2$
addi	00001	R2I-Type	$rd = rs1 + imm$
sub	00010	R3-Type	$rd = rs1 - rs2$
subi	00011	R2I-Type	$rd = rs1 - imm$
mul	00100	R3-Type	$rd = rs1 * rs2$
muli	00101	R2I-Type	$rd = rs1 * imm$
div	00110	R3-Type	$rd = rs1 / rs2$
divi	00111	R2I-Type	$rd = rs1 / imm$
and	01000	R3-Type	$rd = rs1 \& rs2$
andi	01001	R2I-Type	$rd = rs1 \& imm$
or	01010	R3-Type	$rd = rs1   rs2$
ori	01011	R2I-Type	$rd = rs1   imm$
xor	01100	R3-Type	$rd = rs1 \text{ (xor) } rs2$
xori	01101	R2I-Type	$rd = rs1 \text{ (xor) } imm$
slt	01110	R3-Type	$rd = 1 \text{ if } rs1 < rs2, 0 \text{ otherwise}$
slti	01111	R2I-Type	$rd = 1 \text{ if } rs1 < imm, 0 \text{ otherwise}$
sll	10000	R3-Type	$rd = rs1$ logically left shifted by $rs2$ bits
slli	10001	R2I-Type	$rd = rs1$ logically left shifted by $imm$ bits
srl	10010	R3-Type	$rd = rs1$ logically right shifted by $rs2$ bits
srlr	10011	R2I-Type	$rd = rs1$ logically right shifted by $imm$ bits
sra	10100	R3-Type	$rd = rs1$ arithmetically right shifted by $rs2$ bits
srai	10101	R2I-Type	$rd = rs1$ arithmetically right shifted by $imm$ bits
Note: If the result is greater than 32 bits, the higher bits (63 to 32) are stored in <code>x31</code> . In case of division operation, the remainder is stored in <code>x31</code> . In case of shift operations, the bits shifted out are stored in <code>x31</code> .			
Note: <code>imm</code> values are placed in <code>sourceOperand2</code> in <code>ParsedProgram</code>			

### 1.3.3 Control Flow Instructions

Table 5 lists the different control instructions in our custom ISA.

Control flow instructions are slightly more involved. The assembly notation, and the corresponding binary code have a subtle but important difference.

Table 4: Memory instructions in the custom ISA

Operation	Opcode	Format	Description
load	10110	R2I-Type	$rd = \text{word at } [rs1 + imm]$
store	10111	R2I-Type	$\text{word at } [rd + imm] = rs1$
Note: <code>imm</code> values can be specified as label or absolute value			
Note: <code>imm</code> values are placed in <code>sourceOperand2</code> in <code>ParsedProgram</code>			

Table 5: Control Flow instructions in the custom ISA

Operation	Opcode	Format	Description
jmp	11000	RI-Type	$PC = PC + rd + imm$
beq	11001	R2I-Type	If $rs1 = rd$ , $PC = PC + imm$
bne	11010	R2I-Type	If $rs1 \neq rd$ , $PC = PC + imm$
blt	11011	R2I-Type	If $rs1 < rd$ , $PC = PC + imm$
bgt	11100	R2I-Type	If $rs1 > rd$ , $PC = PC + imm$
Note: for <code>jmp</code> , while writing the assembly program, we follow the convention that either <code>rd</code> or <code>imm</code> is used. In machine code, the unused one is set to zero. In <code>ParsedProgram</code> , the used one is placed in the <code>destinationOperand</code> field of the <code>Instruction</code> class.			
Note: in <code>ParsedProgram</code> , for conditional branches, the two registers that are compared are placed in <code>sourceOperand1</code> and <code>sourceOperand2</code> . The <code>imm</code> value is placed in <code>destinationOperand</code> .			

### 1.3.4 Special Instruction: end

The `end` instruction is used to indicate the end of the program.

Table 6: End instruction

Assembly Notation			
Operation	Description		
end	terminate execution		
Binary Code			
Operation	Opcode	Format	Description
end	11101	RI-Type	rd and imm are unused

## 1.4 Address Space Layout

Addresses 0 to  $N_d$  correspond to the static data. Addresses  $N_d$  to  $N_t$  correspond to the text segment or the code segment. These lines contain the instructions of the program –  $N_t - N_d$  instructions, one instruction per line. The stack grows in the reverse direction – the top of the stack has a lower address than the bottom. The stack begin growing from address  $2^{16} - 1$  onwards.

Table 7: Address space layout

address 0		
1		
.	static data segment	
.		
$N_d$		
$N_d + 1$		
.	text / code segment	
.		
$N_t$		
	local variables	x1: stack pointer
		x2: frame pointer
	old frame pointer	
	return address	
	function arguments	
	caller saved registers	
	local variables	
.	.	
.	.	
$2^{16} - 2$		
$2^{16} - 1$		

## 1.5 Function Calling Convention

All function arguments are passed through the stack. Return values are also passed through the stack.

### Caller Behavior

- The caller function first pushes onto the stack all registers whose values it wishes to preserve for use *after* the function call.

Pushing a value means decrementing the stack pointer by one, and then performing a store to the address pointed to by the stack pointer. Similarly, popping a value means performing a load from the address pointed

to by the stack pointer, and then incrementing the stack pointer by one. Note that the typical behavior is explained – you may optimize the number of additions and subtractions.

- It then pushes all the arguments onto the stack.
- It then pushes the return address (address of the instruction following the jump to the function).
- It sets the stack pointer **x1** to point to the top of the stack.
- It then performs the jump.
- Once the called function returns, it finds the return values in the addresses starting from the stack pointer **x1** (address smaller than **x1**).
- It then pops out all the register values it had earlier preserved.

#### **Callee Behavior**

- The callee first pushes **x2** onto the stack.
- It then updates the value of the frame pointer: **x2** takes the value of **x1** subtracted by 1.
- It then performs its work. To access the arguments, it does so relatively based on the value of the frame pointer **x2**. As part of its work, it may perform further memory operations in the stack space, but only in addresses strictly lesser than the frame pointer **x2**.
- Once it is done with its work, it copies **x2** to **x1**.
- It pops out the earlier stored value of **x2** into **x2**.
- It then pushes all the values to be returned onto the stack.
- It then jumps to the return address, which is accessed using the stack pointer **x1**.

#### **Note**

Be very meticulous in updating the value of the frame pointer and the stack pointer.

## **2 Example Assembly Programs**

### **2.1 Adding Two Numbers**

The syntax will be described using the following example program, written in our custom ISA, to add two numbers ‘123’ and ‘234’ and place the result in a certain register location:

```

                                .data
a:
                                123
                                234

                                .text
main:
    load %x0, $a, %x4
    addi %x0, 1, %x3
    load %x3, $a, %x5
    add %x4, %x5, %x6
    end

```

- “.data” is a directive used to signify the beginning of the global data segment.
- “a” and “main” are descriptive names for memory addresses. Here **a** refers to memory address 0, **main** refers to memory address 2. They are not essential – their only purpose is to make writing, understanding and reasoning about assembly programs easier.
- Global data are simply listed one after the other (after the .data directive). Value 123 is stored at memory address 0, value 234 at address 1.
- “.text” is a directive used to signify the beginning of the text or the code segment.
- “main” is a special name. It indicates where the execution will commence from (program counter will be set to this value when the program is loaded).
- Destination operands are always written last. `load %x0, $a, %x4` denotes a load operation that writes the read value to register **x4**.
- In instructions, named addresses are prefixed by a “\$”. `load $a` denotes a load operation that reads from memory address 0 (recall that **a** refers to address 0).
- Registers are prefixed by a “%”. `load %x0, $a, %x4` denotes a load operation that writes the read value to register **x4**.
- Immediate values are written simply.
- `end` is a special instruction type used to denote the end of the program.

## 2.2 Linear Search

Consider the following program to search for **number** in an array **a** of size **n**. If found, ‘1’ is written to **x10**. Else, ‘-1’ is written.

```

        .data
a:
    5
    6
    30
    24
    10
    7
n:
    6
number:
    88
        .text
main:
    add %x0, %x0, %x3
    load %x0, $n, %x6
    load %x0, $number, %x5
loop:
    load %x3, $a, %x4
    beq %x4, %x5, success
    addi %x3, 1, %x3
    bgt %x3, %x6, endl
    jmp loop
success:
    addi %x0, 1, %x10
    end
endl:
    subi %x0, 1, %x10
    end

```