

# Python API for Mobile Robot Control

## Progress Presentation-1

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# Objective

- 1 A Python API to control the different peripherals of the  $\mu$ controller
- 2 Provide the user with a option of register level access of the  $\mu$ controller
- 3 Allow the user to design an application without learning a new language and thoroughly knowing the architecture of the controller.

# Block Diagram

# Milestone Achieved

# Future Work