Python API for Mobile Robot Control

Progress Presentation-1

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Objective

- lacksquare A Python API to control the different peripherals of the μ controller
- 2 Provide the user with a option of register level access of the $\mu {\rm controller}$
- 3 Allow the user to design an application without learning a new language and thoroughly knowing the architecture of the controller.

System Architecture



Milestone Achieved

- 1 Robot-end firmware written in embedded C
- Serial Communication between Raspberry Pi and Robot
- 3 Function for configuring all IO Ports and Pins of microcontroller
- 4 Implemented and tested code for Buzzer and BarLED.
- 5 Test code for Port and Pin configuration function

User code snippet

```
from set_register import *
import time
import serial_connection as sc
sc.serial_open()
###Configure ports###
#set port pin direction
config_register(DDRJ, PIN1 | PIN2 | PIN3, set_pins)
#intial value logic 0
config_register(PORTJ, PIN1 | PIN2 | PIN3, reset_pins)
for i in range (0,5):
        #turn on Leds
         config_register (PORTJ, PIN1 | PIN2 | PIN3, set_pins)
         time. sleep(0.5)
        #turn off leds
         config_register (PORTJ, PIN1 | PIN2 | PIN3, reset_pins)
         time. sleep(0.5)
sc.serial_close()
```

Implementation

Data Packet Format

ĺ	set/rest	Function id	Register id	Pin value
	1-bit	7-bit	8-bit	8-bit

set/reset (1-bit): This bit decides whether value a register bit is set high or reset to low

Function id (7-bit): These bits select various μ controller peripherals Example: IO,ADC,Timers,I2C etc

Register id (8-bit): These bits select registers present to access μ controller peripherals. Example: DDRA,PORTA, ADCSRA,ADMUX etc

Pin Value (8-bit): These bits select value to be written on 8-bit registers

Future Work

- Develop and test object-oriented implementation
- Access following peripherals for μ controller
 - Timers
 - ADC
 - Interrupt
 - 12C
- Improve data packet by incorporating checksum, end of packet payload to existing system.
- Design PyQT GUI for making SFTP connection to Raspberry Pi from PC
- Provide higher level abstraction for peripheral devices