### Class core values

- 1. Be **respect**ful to yourself and others
- 2. Be **confident** and believe in yourself
- 3. Always do your **best**
- 4. Be cooperative
- 5. Be **creative**
- 6. Have **fun**
- 7. Be **patient** with yourself while you learn
- 8. Don't be shy to **ask "stupid" questions**
- 9. Be **inclusive** and **accepting**





## Learning Objectives

- 1. Explain the challenges of 3D objects
- Describe the basic concepts of main methods for learning on 3D objects
- 3. Apply hyperparameter tuning to learning progblems



1. Simple input

SVM, random forest, dense neural net

```
protein_1 25 kDa pl=7.5 310 residues ... 2.5 hr half-life Stability<sub>1</sub> protein_2 10 kDa pl=4 50 residues ... 10 hr half-life Stability<sub>2</sub> protein_3 100 kDa pl=8 1200 residues ... 2 hr half-life Stability<sub>3</sub>
```

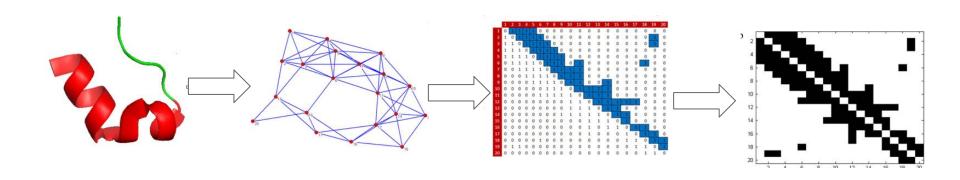


1. Simple input

SVM, Random Forest, dense neural net

2. 2D image

CNN





- 1. Simple input SVM, Random Forest, dense neural net
- 2. 2D image CNN
- 3. String of amino acids Natural language processing

```
ho_1 MGLTDILGFNREFDILAV...SPLFG s_1 MLKPTRVNMSERCGHITDENVCSR...TLVRF s_2 MIKRTVIHGRDFRWNYTSPL...GMNSWQ s_3 ...
```

Features: charge, pKa, size, functional groups, hydrogen bond status, ...

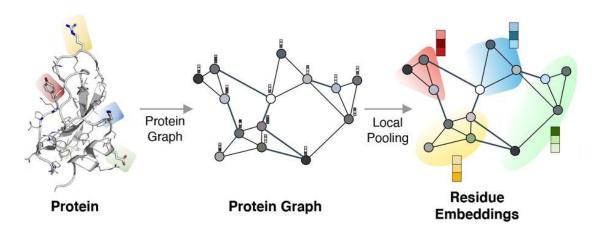


1. Simple input SVM, Random Forest, dense neural net

2. 2D image Convolutional neural nets

3. String of amino acids Natural language processing (RNN, LSTM, Transformers)

4. Graphs Graph Convolutional Neural nets





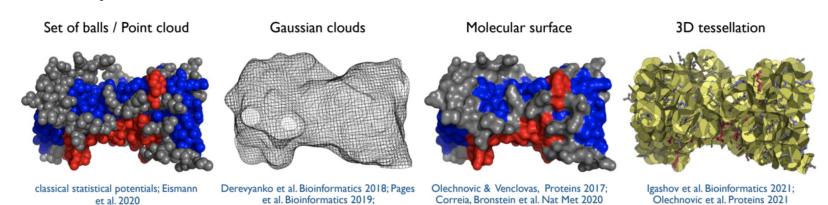
- Simple input
- 2D image
- Graphs
- 5. 3D objects

SVM, Random Forest, dense neural net

Convolutional neural nets

String of amino acids Natural language processing (RNN, LSTM, Transformers)

Graph convolutional neural nets

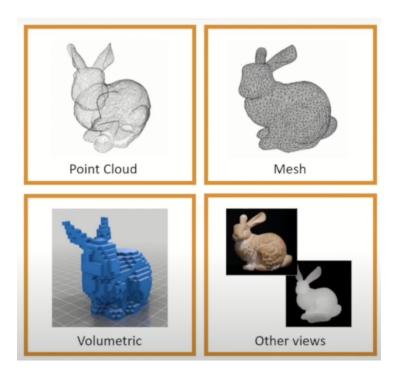


## We live in a 3D world and obtaining 3D data is becoming increasingly common



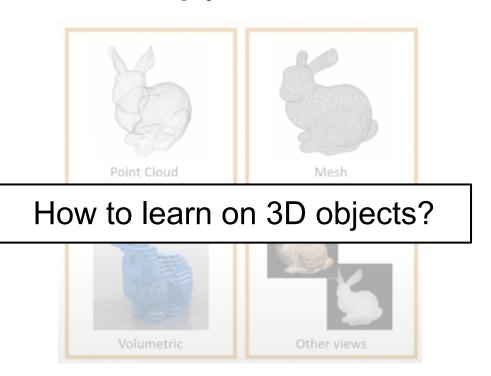


## We live in a 3D world and obtaining 3D data is becoming increasingly common

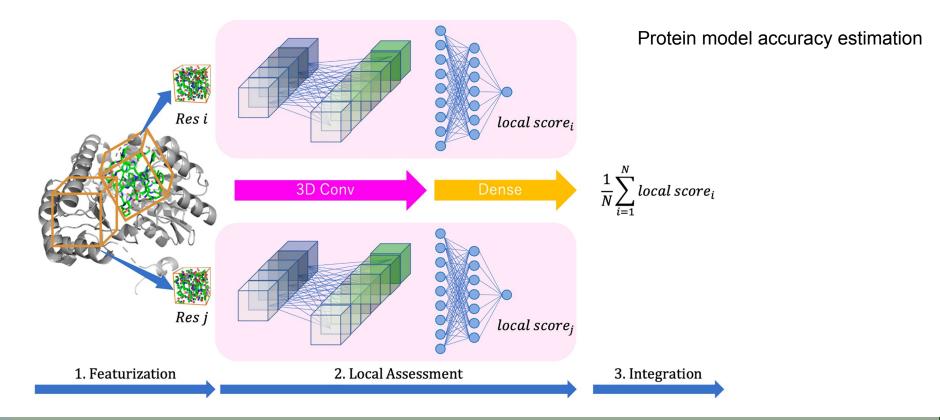


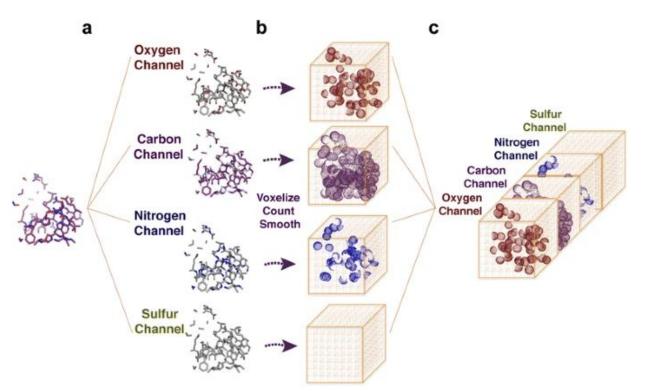


## We live in a 3D world and obtaining 3D data is becoming increasingly common

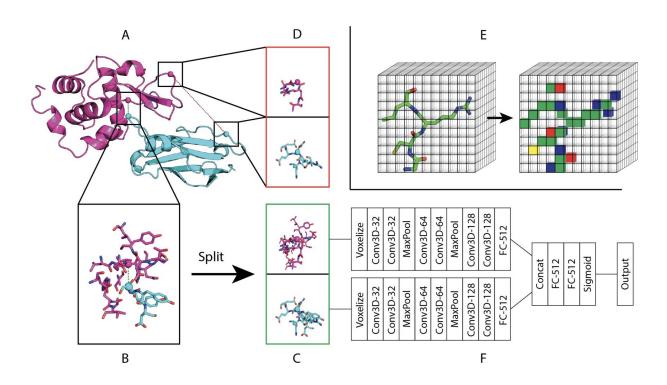






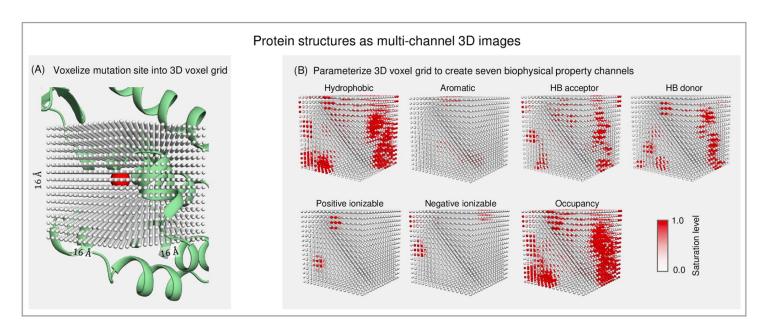


Amino acid environment similarity analysis



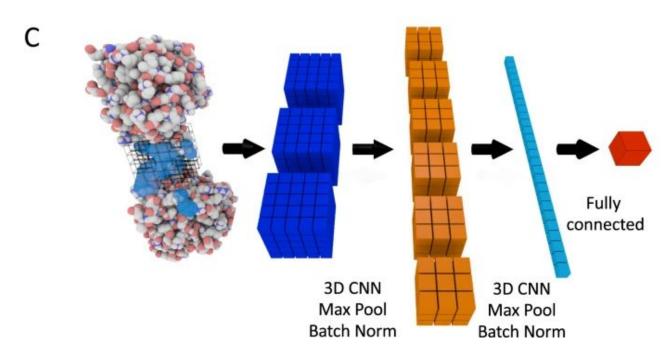
Interface prediction

Changes in stability upon point mutation





Data mining 3D protein-protein interfaces

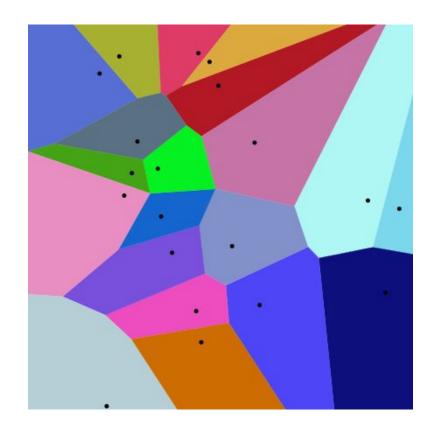




### Method 2. Tessellation combined with GNN



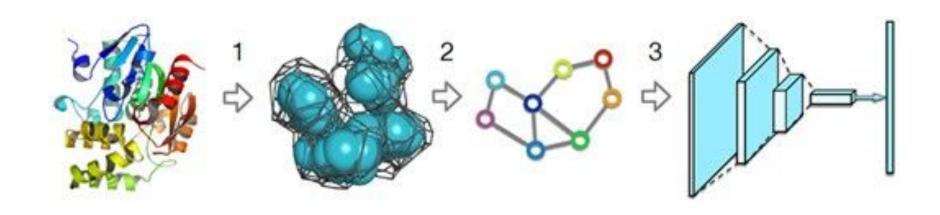
### Method 2. Tessellation combined with GNN





### Method 2. Tessellation combined with GNN

#### VoroCNN

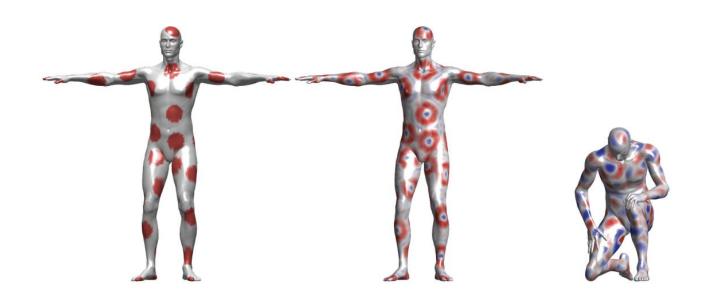




## Method 3. Geometric learning

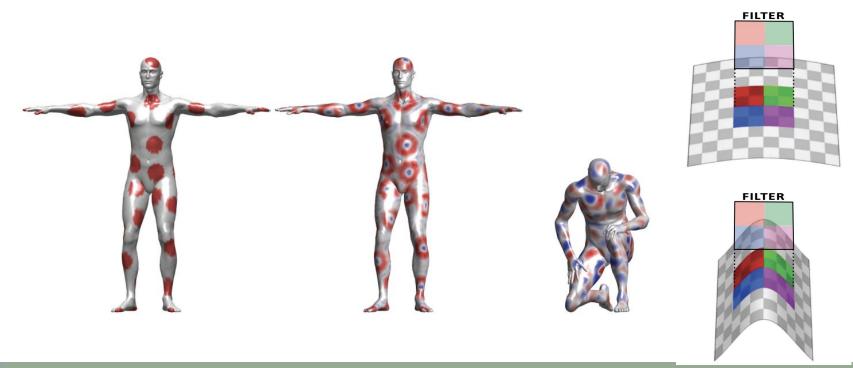


## The challenge with 3D data is their non-euclidean distance



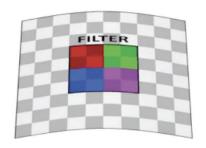


## The conventional convolution layers don't work well when dealing with non-euclidean distances





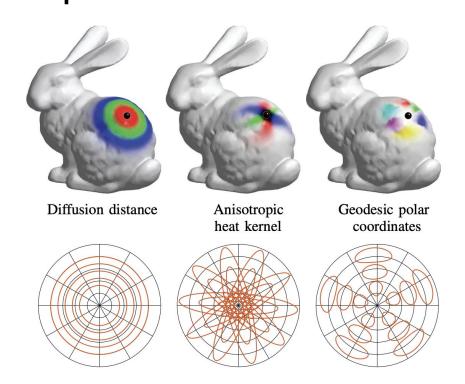
## To solve this problem, geometric filters were developed

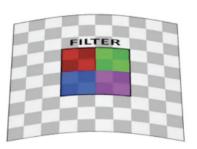






## To solve this problem, geometric filters were developed

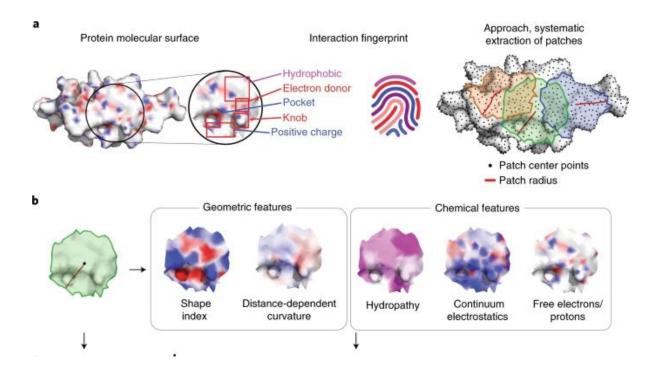








## To solve this problem, geometric filters were developed

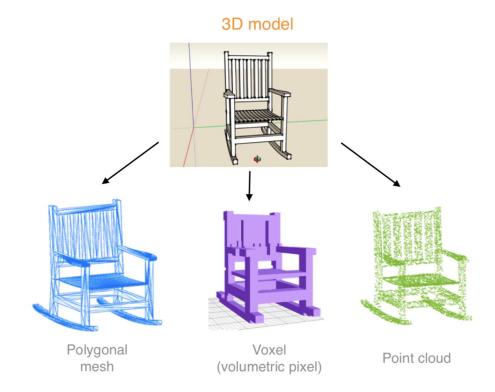




## Method 4. Learning on point clouds

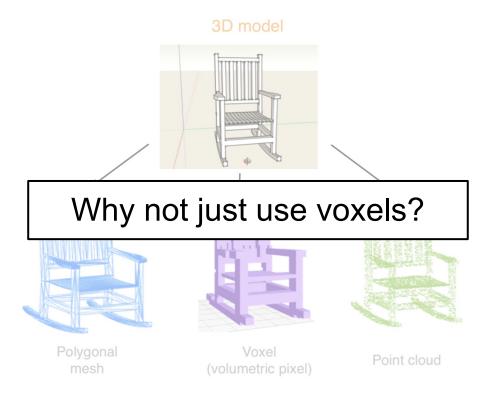


## Method 4. Learning on point clouds





### Method 4. Learning on point clouds





## Main challenges with point clouds

1. Unordered → invariant to permutation



## Main challenges with point clouds

- 1. Unordered → invariant to permutation
- 2. Invariant to rigid transformation



## Main challenges with point clouds

- 1. Unordered → invariant to permutation
- 2. Invariant to rigid transformation
- 3. Should capture interactions among points



## PointNet++ is a leading algorithm that addresses all these challenges

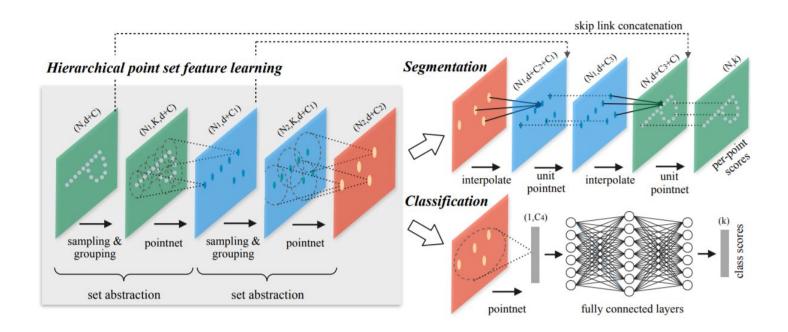
Use of symmetric functions

```
x + y + z = y + z + x = z + y + x = ...

or

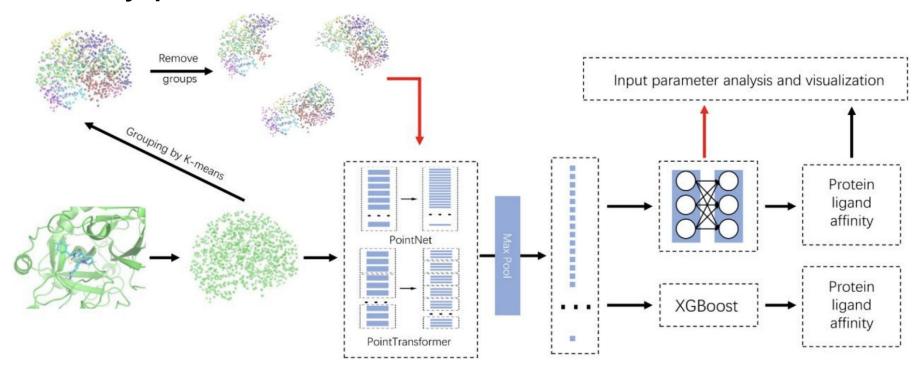
max(x, y, z)
```

### Overall architecture of PointNet++





## PointNet on proteins for protein-ligand binding affinity prediction







Week 9, Lecture 1

# Tips and tricks of deep learning

1. Check to make sure that your data is balanced



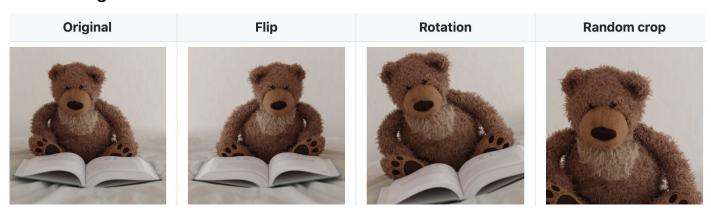
- 1. Check to make sure that your data is balanced
- 2. Remove outliers and noisy points



- 1. Check to make sure that your data is balanced
- 2. Remove outliers and noisy points
- 3. Replace missing points using median or 0



- 1. Check to make sure that your data is balanced
- 2. Remove outliers and noisy points
- 3. Replace missing points using median or 0
- 4. Use data augmentation





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- 5. Think about your task and make sure your data matches your taks



- 1. Check to make sure that your data is balanced
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- 5. Think about your task and make sure your data matches your taks
- 6. Normalize features if your learning method is sensitive to it



- 1. Check to make sure that your data is balanced
- 2. Remove outliers and noisy points
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- 4. Use data augmentation
- 5. Think about your task and make sure your data matches your taks
- 6. Normalize features if your learning method is sensitive to it

Spend more time to get better data!!



1. Take advantage of pre-trained models. Use transfer learning!



- Take advantage of pre-trained models. Use transfer learning!
- 2. Check your initialization. Sometimes method other than random initialization help, such as *Xavier initialization*



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- 2. Check your initialization. Sometimes method other than random initialization help, such as *Xavier initialization*
- 3. Change learning rate. Use Adam as initial guess
- 4. Use *regularization* to avoid overfitting:
  - a. Dropout
  - b. Weight regularization



L1 Regularization aka Lasso

Cost = 
$$\sum_{i=0}^{N} (y_i - \sum_{j=0}^{M} x_{ij} W_j)^2 + \lambda \sum_{j=0}^{M} |W_j|$$

L2 Regularization aka Ridge

Cost = 
$$\sum_{i=0}^{N} (y_i - \sum_{j=0}^{M} x_{ij} W_j)^2 + \lambda \sum_{j=0}^{M} W_j^2$$
Loss function Regularization
Term

- Take advantage of pre-trained models. Use transfer learning!
- 2. Check your initialization. Sometimes method other than random initialization help, such as *Xavier initialization*
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- Take advantage of pre-trained models. Use transfer learning!
- 2. Check your initialization. Sometimes method other than random initialization help, such as *Xavier initialization*

Test

Train

- 3. Change learning rate. Use Adam as initial guess
- 4. Use *regularization* to avoid overfitting:
  - a. Dropout
  - b. Weight regularization
- 5. Use early stopping



### Good practices

1. Use mini-batch overfitting



### Good practices

- 1. Use mini-batch overfitting
- 2. Check gradients



Hyperparameter:

A parameter whose value is used to control the learning process



Hyperparameter:

A parameter whose value is used to control the learning process Unlearnable at times



1. Choose parameters to tune



- 1. Choose parameters to tune
- 2. Set grids for each parameter

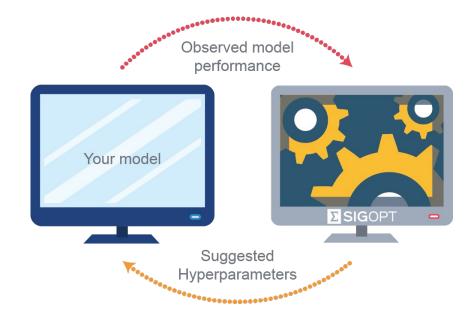


- 1. Choose parameters to tune
- 2. Set grids for each parameter
- 3. Run an automated tuner



#### In-class activity

#### Hyperparameter tuning





## Next lecture: Responsible Al

