0-1 Knapsack Problem

Informal Description: We have n precomputed data files that we want to store, and W bytes of storage available.

```
File i has two parameters:
size w_i (bytes)
time v_i (minutes); time needed to recompute File i.
```

Our goal is to use storage space to minimize recomputation time; we want to find a subset of files to store such that

- The files have combined size at most W.
- The total recomputation time of the stored files is as large as possible.

We can not store parts of files, it is the whole file or nothing. (This is why it is called **0-1**.)

How should we select the files?

0-1 Knapsack Problem

Formal description:

Given W > 0, and two *n*-tuples of positive numbers

$$\langle v_1, v_2, \dots, v_n \rangle$$
 and $\langle w_1, w_2, \dots, w_n \rangle$,

we wish to determine the subset

$$T \subseteq \{1, 2, \dots, n\}$$
 (of files to store) that

subject to
$$\sum_{i \in T} w_i \leq W$$
.

Remark: This is an optimization problem. The *Brute* Force solution is to try all 2^n possible subsets T.

Question: Is there a better way?

Yes. Dynamic Programming!

General Schema of a DP Solution

- **Step1:** Structure: Characterize the structure of an optimal solution by showing that it can be decomposed into *optimal* subproblems
- **Step2:** Recursively define the value of an optimal solution by expressing it in terms of optimal solutions for smaller problems (usually using min and/or max).
- **Step 3:** Bottom-up computation: Compute the value of an optimal solution in a bottom-up fashion by using a table structure.
- **Step 4:** Construction of optimal solution: Construct an optimal solution from computed information.

Remarks on the Dynamic Programming Approach

- Steps 1-3 form the basis of a dynamic-programming solution to a problem.
- Step 4 can be omitted if only the value of an optimal solution is required.

Developing a DP Algorithm for Knapsack

Step 1: Decompose the problem into smaller problems.

We construct an array V[0..n, 0..W]. For $1 \le i \le n$, and $0 \le w \le W$, the entry V[i, w] will store the maximum (combined) computing time of any subset of files $\{1, 2, ..., i\}$ of (combined) size at most w.

That is

$$V[i,w] = \max \left\{ \sum_{j \in T} v_j : T \subseteq \{1,2,\ldots,i\}, \sum_{j \in T} w_j \le w \right\}.$$

If we can compute all the entries of this array, then the array entry V[n,W] will contain the solution to our problem.

Note: In what follows we will say that T is a solution for [i, w] if $T \subseteq \{1, 2, ..., i\}$ and $\sum_{j \in T} w_j \le w$ and that T is an optimal solution for [i, w] if T is a solution and $\sum_{j \in T} v_j = V[i, w]$.

Developing a DP Algorithm for Knapsack

Step 2: Recursively define the value of an optimal solution in terms of solutions to smaller problems.

Initial Settings: Set

$$V[0,w]=0$$
 for $0 \le w \le W$, no item $V[i,w]=-\infty$ for $w < 0$, illegal

Recursive Step: Use

$$V[i,w] = \max(V[i-1,w],v_i+V[i-1,w-w_i])$$
 for $1 \le i \le n, \ 0 \le w \le W.$

Developing a DP Algorithm for Knapsack

Step 3: Bottom-up computation of V[i, w] (using iteration, not recursion).

Bottom: V[0, w] = 0 for all $0 \le w \le W$.

Bottom-up computation: Computing the table using

$$V[i, w] = \max(V[i-1, w], v_i + V[i-1, w-w_i])$$

row by row.

w=0	1	2	3	•••	•••	W	
0	0	0	0	•••	•••	0	bottom
						>	
						>	
						>	
						>	\bigcup
	w=0 0	w=0 1 0 0			0 0 0 0	0 0 0 0	

up

Example of the Bottom-up computation

Let W = 10 and

$$egin{array}{c|cccc} i & 1 & 2 & 3 & 4 \\ \hline v_i & 10 & 40 & 30 & 50 \\ w_i & 5 & 4 & 6 & 3 \\ \hline \end{array}$$

V[i,w]	0	1	2	3	4	5	6	7	8	9	10
i = 0	0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	10	10	10	10	10	10
2	0	0	0	0	40	40	40	40	40	50	50
3	0	0	0	0	40	40	40	40	40	50	70
4	0	0	0	50	50	50	50	90	90	90	90

Remarks:

- The fi nal output is V[4, 10] = 90.
- The method described does not tell which subset gives the optimal solution. (It is {2, 4} in this example).

The Dynamic Programming Algorithm

```
 \begin{cases} & \text{for } (w = 0 \text{ to } W) \ V[0, w] = 0; \\ & \text{for } (w = 0 \text{ to } W) \ V[0, w] = 0; \\ & \text{for } (i = 1 \text{ to } n) \\ & \text{for } (w = 0 \text{ to } W) \\ & \text{if } (w[i] \leq w) \\ & V[i, w] = \max\{V[i-1, w], v[i] + V[i-1, w-w[i]]\}; \\ & \text{else} \\ & V[i, w] = V[i-1, w]; \\ & \text{return } V[n, W]; \end{cases}
```

Time complexity: Clearly, O(nW).

Constructing the Optimal Solution

Question: How do we use the values keep[i, w] to determine the subset T of items having the maximum computing time?

If keep[n,W] is 1, then $n \in T$. We can now repeat this argument for $\text{keep}[n-1,W-w_n]$. If keep[n,W] is 0, the $n \notin T$ and we repeat the argument for keep[n-1,W].

Therefore, the following partial program will output the elements of T:

```
K=W; for (i=n \text{ downto 1}) if (\text{keep}[i,K]==1) \{ output i; K=K-w[i]; \}
```

The Complete Algorithm for the Knapsack Problem

```
\mathsf{KnapSack}(v,w,n,W)
   for (w = 0 \text{ to } W) V[0, w] = 0;
   for (i = 1 \text{ to } n)
       for (w = 0 \text{ to } W)
           if ((w[i] \le w)) and (v[i] + V[i-1, w-w[i]] > V[i-1, w]))
               V[i, w] = v[i] + V[i - 1, w - w[i]];
               keep[i, w] = 1;
           else
               V[i, w] = V[i - 1, w];
               \text{keep}[i, w] = 0;
   K = W:
   for (i = n \text{ downto } 1)
       if (\text{keep}[i, K] == 1)
           output i;
           K = K - w[i];
   return V[n, W];
}
```

Dynamic Programming vs. Divide-and-Conquer

The Dynamic Programming algorithm developed runs in O(nW) time.

We started by deriving a recurrence relation for solving the problem

$$V[0, w] = 0$$

 $V[i, w] = \max(V[i-1, w], v_i + V[i-1, w-w_i])$

Question: why can't we simply write a top-down divideand-conquer algorithm based on this recurrence? Answer: we could, but it could run in time as bad as $\Theta(2^n)$ since it might have to recompute the same values many times.

Dynamic programming saves us from having to recompute previously calculated subsolutions!