

```

function t_f = stallTorqueFriction(n, n_b, n_n)
    u = 0.16; % Dynamic friction coefficient
    l_b=6.6E-3; %m
    l_c=9.9E-3; %m
    r_s=2E-3; %m
    g=9.801; %m/s^2
    f_d = 1.18 / 1000 * 100^3; % kg/m^3
    f_t = 0.18 * 0.0254; % m
    f_r = 4.5/2 * 0.0254; % m
    b_r = 0.25 * 0.0254; % m
    a_r = (pi*(f_r^2))-(pi*12*(b_r^2)); %m^2
    m_acrylc=a_r*f_d*f_t; % kg
    n_n = n_n * n_b; % define number of nuts on flywheel
    m_b = 7.09 / 1000; % kg
    m_n = 3.02 / 1000; % kg
    m_hub = 65 / 1000; % kg
    m_nb = (m_b*n_b)+(m_n*n_n)+m_hub; % mass in kg of parts on flywheel
    m_fw = m_acrylc+m_nb;
    t_f = u*r_s*m_fw*g*(1+(2*(l_c/l_b)))*(1/n);
end

```

Not enough input arguments.  
 Error in stallTorqueFriction (line 13)  
 n\_n = n\_n \* n\_b; % define number of nuts on flywheel

