

Исходные данные

Коэф. запаса: safety = 1.3

Горючее: Fuel = "Керосин" turbine = "ТВД"

Высота движения (м): H_v = 0

Массовый расход перед Т (кг/с):
Массовый расход утечек Т (кг/с):
Массовый расход на охл Т (кг/с):

$$\begin{pmatrix} G_T \\ G_{\text{leak}} \\ G_{\text{cooling}} \end{pmatrix} = \begin{cases} \begin{pmatrix} 32.30 \\ 106.96 \cdot 10^{-3} \\ 3240.8 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 35.43 \\ 35.65 \cdot 10^{-3} \\ 810.2 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 32.30 \\ \hline 2 & 0.11 \\ \hline 3 & 3.24 \\ \hline \end{array}$$

Мощность Т (Вт): $N_T = 10^6 \cdot \begin{cases} 14.893 & \text{if turbine = "ТВД"} \\ 15.181 & \text{if turbine = "ТНД"} \end{cases} = 14.893 \cdot 10^6$

Полное давление перед Т (Па): $P^*_T = 10^3 \cdot \begin{cases} 2731.8 & \text{if turbine = "ТВД"} \\ 927.5 & \text{if turbine = "ТНД"} \end{cases} = 2731.8 \cdot 10^3$

Полная температура перед Т (К): $T^*_T = \begin{cases} 1773 & \text{if turbine = "ТВД"} \\ 1368.9 & \text{if turbine = "ТНД"} \end{cases} = 1773.0$

Коэф. избытка воздуха в Т: $\alpha_{\text{ох}} = \begin{cases} 2.267 & \text{if turbine = "ТВД"} \\ 2.493 & \text{if turbine = "ТНД"} \end{cases} = 2.267$

Полное давление отбора охлаждающего воздуха (К): $P^*_{\text{cooling}} = 10^3 \cdot \begin{cases} 2845.6 & \text{if turbine = "ТВД"} \\ 319.4 & \text{if turbine = "ТНД"} \end{cases} = 2845.6 \cdot 10^3$

Полная температура отбора охлаждающего воздуха (К): $T^*_{\text{cooling}} = \begin{cases} 806.9 & \text{if turbine = "ТВД"} \\ 418.2 & \text{if turbine = "ТНД"} \end{cases} = 806.9$

Коэф. сохранения полного давления охлаждения: $\sigma_{\text{cooling}} = 0.97$

Подогрев охл. от КС [К]: $\Delta T_{\text{охл.подогрев}} = 40$

Газовая постоянная (Дж/кг/К): $R_{\text{газ}}(\alpha_{\text{ох}}, \text{Fuel}) = 288.5$

Допустимая температура Л (К): $T_{\text{Л,доп}} = 1373$

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

[1, с.15]

$80 \leq c_T \leq 400 = 1$

Лопаточный КПД Т:

$\eta_{ЛТ} = 88\%$

$88\% \leq \eta_{ЛТ} \leq 95\% = 1$

Угол входа в Т:

$\alpha_T = 90.^{\circ}$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_T \\ c_T \end{pmatrix} = \begin{cases} \begin{pmatrix} 100 \\ 180 \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 180 \\ 260 \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 100.0 \\ \hline 2 & 180.0 \\ \hline \end{array}$$

$$u_T = \begin{cases} 520 & \text{if turbine = "ТВД"} \\ 260 & \text{if turbine = "ТНД"} \end{cases} = 520.0$$

$z = \text{ORIGIN}..N_T$

Полное давление отбора охлаждающего воздуха (K): $\overset{\text{cooling}}{P^*} = P^*_{\text{cooling}} \cdot \sigma_{\text{cooling}} = 2760.2 \cdot 10^3$

Полная температура отбора охлаждающего воздуха (K): $\overset{\text{cooling}}{T^*} = T^*_{\text{cooling}} + \Delta T_{\text{охл.подогрев}} = 846.9$

Массовый расход перед Т (кг/с): $\overset{\text{cooling}}{G_T} = G_T - G_{\text{leak}} = 32.2$

Массовый расход после Т (кг/с): $G_T = G_T + G_{\text{cooling}} = 35.4$

Удельная работа Т (Дж/кг): $L^*_T = \frac{N_T}{\text{mean}(G_T, G_T)} = 440.4 \cdot 10^3$

$L^*_T \leq 550 \cdot 10^3 = 1$

Располагаемый теплоперепад в Т (Дж/кг): $H_T = \frac{L^*_T + 0.5c_T^2}{\eta_{\text{л}}} = 518.9 \cdot 10^3$

iteration		
k _Г	=	iteration = 0
P _Г		k _Г = k _{ад} (Cp _{газ} (P* _Г , T* _Г , α _{оx} , Fuel), R _{газ} (α _{оx} , Fuel))
T _Г		while 1 > 0
		iteration = iteration + 1
		Cp _Г = $\frac{k_{Г}}{k_{Г} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$
		T _Г = $T^*_{Г} - \frac{c_{Г}^2}{2 \cdot Cp_{Г}}$
		P _Г = $P^*_{Г} \cdot \left(\frac{T_{Г}}{T^*_{Г}}\right)^{\frac{k_{Г}}{k_{Г}-1}}$
		k' _Г = k _{ад} (Cp _{газ} (P _Г , T _Г , α _{оx} , Fuel), R _{газ} (α _{оx} , Fuel))
		if eps("rel", k _Г , k' _Г) ≤ epsilon
		k _Г = k' _Г
		break
		k _Г = k' _Г
		(iteration k _Г P _Г T _Г) ^T

	1
1	1.0
2	1.3
3	2705198.4
4	1769.2

Количество итераций: iteration = 1

Показатель адиабаты перед Т: k_Г = 1.283

Статическое давление перед Т (Па): P_Г = 2705.2·10³

Статическая температура перед Т (К): T_Г = 1769.2

Теплоемкость перед Т (Дж/кг/К): Cp_Г = Cp_{газ}(P_Г, T_Г, α_{оx}, Fuel) = 1309

<u>iteration</u>		
k _T	=	iteration = 0
P _T		k _T = k _T
T _T		while 1 > 0
		iteration = iteration + 1
		k _{cp} = mean(k _T , k _T)
		Cp = $\frac{k_{cp}}{k_{cp} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$
		$P_T = P^*_{\Gamma} \cdot \left(1 - \frac{H_T}{Cp \cdot T^*_{\Gamma}}\right)^{\frac{k_{cp}}{k_{cp} - 1}}$
		$T_T = T^*_{\Gamma} - \frac{H_T \cdot \eta_{л}}{Cp}$
		k' _T = k _{ад} (Cp _{газ} (P _T , T _T , α _{ox} , Fuel), R _{газ} (α _{ox} , Fuel))
		if eps("rel", k _T , k' _T) ≤ epsilon
		k _T = k' _T
		break
		k _T = k' _T
		(iteration k _T P _T T _T) ^T

	1
1	1
2	1.293
3	866477.23
4	1424.088

Количество итераций: iteration = 1

Показатель адиабаты после T: k_T = 1.293

Статическое давление после T (Па): P_T = 866.5·10³ P_T ≥ P_{атм}(H_υ) = 1

Статическая температура после T (K): T_T = 1424.1

Теплоемкость после T (Дж/кг/К): Cp_T = Cp_{газ}(P_T, T_T, α_{ox}, Fuel) = 1271.6

Ср. показатель адиабаты T: $k = \text{mean}(k_{\Gamma}, k_T) = 1.288$

Ср. теплоемкость T (Дж/кг/К): $C_p = \frac{k}{k - 1} \cdot R_{\text{газ}}(\alpha_{\text{ox}}, \text{Fuel}) = 1289.8$

Степень понижения давления: $\pi_T = \frac{P_{\Gamma}^*}{P_T} = 3.15$

Удельный объём перед T (м³/кг): $\left(\begin{matrix} v_{\Gamma} \\ v_T \end{matrix} \right) = R_{\text{газ}}(\alpha_{\text{ox}}, \text{Fuel}) \cdot \left(\begin{matrix} \frac{T_{\Gamma}}{P_{\Gamma}} \\ \frac{T_T}{P_T} \end{matrix} \right) = \begin{matrix} & & 1 \\ \begin{matrix} 1 \\ 2 \end{matrix} & \begin{matrix} 0.189 \\ 0.474 \end{matrix} \end{matrix}$

Площадь кольцевого сечения перед T (м²): $\left(\begin{matrix} F_{\Gamma} \\ F_T \end{matrix} \right) = \left(\begin{matrix} \frac{G_{\Gamma} \cdot v_{\Gamma}}{c_{\Gamma}} \\ \frac{G_T \cdot v_T}{c_T} \end{matrix} \right) = \begin{matrix} & & 1 \\ \begin{matrix} 1 \\ 2 \end{matrix} & \begin{matrix} 60741 \\ 93341 \end{matrix} \end{matrix} \cdot 10^{-6}$

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

$$0.7 \leq \mu_c \leq 1 = 1$$

▼ Определение количества ступеней T

$$\begin{pmatrix} Z_{\text{recomend}} \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} =$$

$$c_{cp} = \text{mean}(c_T, c_T)$$

$$\alpha_{\text{ВОЗВ}} = 0.025$$
while 1 > 0

$$Z = \text{round} \left[\frac{2 \cdot H_T \cdot \frac{(1 + \alpha_{\text{ВОЗВ}})}{(\mu_c \cdot c_{cp})^2} - 1}{\frac{u_T^2}{(\mu_c \cdot c_{cp})^2 \cdot y_0^2} - 1} \right]$$

break if $\left| \text{eps} \left[\text{"rel"}, \alpha_{\text{ВОЗВ}}, \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}}) \right] \right| < \text{epsilon}$

$$\alpha_{\text{ВОЗВ}} = \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}})$$

if $\alpha_{\text{ВОЗВ}} = 0$

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

break

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix}$$

1

1

1.000

2

0.000

Рекомендуемое количество ступеней: $Z_{\text{recomend}} = 1$

Количество ступеней: $Z = \begin{cases} 1 & \text{if turbine = "ТВД"} \\ 4 & \text{if turbine = "ТНД"} \end{cases} = 1$

Дискретизация ступеней: $i = 1 \dots Z$

Дискретизация сечений: $ii = 1 \dots 2 \cdot Z + 1$

▲ Определение количества ступеней T

Выбранный материал Л:

$$\text{material_blade}_i = \begin{cases} \text{"ВКНА-1В"} & \text{if } 1523 \leq T^*_{\Gamma} \\ \text{"ВЖМ7"} & \text{if } 1323 \leq T^*_{\Gamma} < 1523 \\ \text{"ЖС-36"} & \text{if } 1123 \leq T^*_{\Gamma} < 1323 \end{cases}$$

Плотность материала Л (кг/м^3):

$$\rho_{\text{blade}_i} = \begin{cases} 7938 & \text{if material_blade}_i = \text{"ВКНА-1В"} \\ 8390 & \text{if material_blade}_i = \text{"ВЖМ7"} \\ 8760 & \text{if material_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

Предел длительной прочности Л РК (Па):

$$\sigma_{\text{blade_long}_i} = 10^6 \cdot \begin{cases} 205 & \text{if material_blade}_i = \text{"ВКНА-1В"} \\ 120 & \text{if material_blade}_i = \text{"ВЖМ7"} \\ 120 & \text{if material_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$\text{material_blade}^T = \begin{bmatrix} & 1 \\ 1 & \text{"ВКНА-1В"} \end{bmatrix}$$

$$\rho_{\text{blade}}^T = \begin{bmatrix} & 1 \\ 1 & 7938 \end{bmatrix}$$

$$\sigma_{\text{blade_long}}^T = \begin{bmatrix} & 1 \\ 1 & 205 \end{bmatrix} \cdot 10^6$$

Коэф. формы: $k_n = 6.8$

Модуль Юнга I рода материала Л (Па): $E_{\text{blade}} = 210 \cdot 10^9$

Коэф. Пуассона материала Л(): $\mu_{\text{steel}} = 0.3$

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_blade_long}{safety \cdot k_n \cdot F_\Gamma}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 19539 \\ \hline \end{array}$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{max} = \sqrt{\frac{\sigma_blade_long}{safety \cdot k_n \cdot F_T}} = (15762)$$

Рекомендуюмая ном. частота вращения (об/мин):

$$n = n_{max} \cdot 0.95 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14974 \\ \hline \end{array}$$

$$n = \begin{cases} 15000 & \text{if turbine = "ТВД"} \\ 5300 & \text{if turbine = "ТНД"} \end{cases} = 15000$$

Ном. частота вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 1570.8$$

Ср. диаметр перед Т (м):

$$\begin{pmatrix} D_{\Gamma.cp} \\ D_{T.cp} \end{pmatrix} = \frac{2}{\omega} \cdot \begin{pmatrix} u_T \\ u_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 662.1 \\ \hline 2 & 662.1 \\ \hline \end{array} \cdot 10^{-3}$$

Ср. диаметр после Т (м):

Длина Л первой ступени Т (м):

$$\begin{pmatrix} l_\Gamma \\ l_T \end{pmatrix} = \frac{1}{\pi} \cdot \begin{pmatrix} \frac{F_\Gamma}{D_{\Gamma.cp}} \\ \frac{F_T}{D_{T.cp}} \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29.20 \\ \hline 2 & 44.88 \\ \hline \end{array} \cdot 10^{-3}$$

Длина Л последней ступени Т (м):

$$\frac{l_\Gamma}{D_{\Gamma.cp}} = \frac{1}{22}$$
$$\frac{l_T}{D_{T.cp}} = \frac{1}{14}$$

Диаметр периферии после Т (м):

$$\begin{pmatrix} D_{T.пер} \\ D_{T.кор} \end{pmatrix} = \begin{pmatrix} D_{T.cp} + l_T \\ D_{T.cp} - l_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 707.0 \\ \hline 2 & 617.2 \\ \hline \end{array} \cdot 10^{-3}$$

Диаметр корня после Т (м):

Равномерное распределение мощности Т по ступеням (Вт): $N_{\text{ст}_i} = \frac{N_T}{Z}$

$N_{\text{ст}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14.89 \\ \hline \end{array} \cdot 10^6$

Вид проточной части:
("const", "кор", "сп", "пер", "доля от предыдущего диаметра периферии")

$$\text{ЗППЧ} = \left(\begin{array}{l} \left| \begin{array}{l} \text{"const" if } Z = 1 \quad \text{"1.07" "1.065" "1.03" "пер" "пер"} \\ \text{"кор" otherwise} \end{array} \right. \\ \left| \begin{array}{l} \text{"пер" if } Z = 1 \quad \text{"1.07" "1.05" "кор" "пер" "пер"} \\ \text{"1.055" otherwise} \end{array} \right. \end{array} \right)^T$$

▼ Определение проточной части ОТ

Линейное распределение кольцевых площадей по сечениям:

$$\begin{array}{|l} F_{\text{ww}} = \\ \\ \\ F \end{array} \begin{array}{l} \text{for } i \in 1..2Z + 1 \\ \\ F_i = \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \cdot i + \left(F_\Gamma - \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \right) \\ \\ \text{for } i \in 1..Z \\ \text{for } a \in 2..3 \\ F_{\text{st}(i, a)} = F_{\text{st}(i, a-1)} \text{ if } \text{ЗППЧ}_{i, a-1} = \text{"const"} \end{array}$$

$F^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 60741 & 60741 & 93341 & & & & & & \\ \hline \end{array} \cdot 10^{-6}$

D =

for i ∈ 2Z + 1

for r ∈ 1..N_r

D_{i,r} =

D_{T.kop} if r = 1

D_{T.cp} if r = av(N_r)

D_{T.nep} if r = N_r

for i ∈ Z..1

for a ∈ 2..1

for r ∈ 1..N_r

D_{st(i,a),r} =

if 3ΠΠΠΨ_{i,a} = "const"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "kop"

D_{st(i,a+1),1} if r = 1

$\frac{1}{2} \cdot \left[D_{st(i,a+1),1} + \sqrt{(D_{st(i,a+1),1})^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} \right]$ if r = av(N_r)

$\sqrt{(D_{st(i,a+1),1})^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "cp"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "nep"

$\sqrt{(D_{st(i,a+1),N_r})^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = 1

$\frac{1}{2} \cdot \left[\sqrt{(D_{st(i,a+1),N_r})^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + D_{st(i,a+1),N_r} \right]$ if r = av(N_r)

D if r = N

D^T =

	1	2	3	4	5	6	7	8	9
1	650.0	650.0	617.2						
2	678.5	678.5	662.1						
3	707.0	707.0	707.0						

·10^{−3}

R_{av} =

D

2

R^T =

	1	2	3	4	5	6	7	8	9
1	325.0	325.0	308.6						
2	339.2	339.2	331.0						
3	353.5	353.5	353.5						

·10^{−3}

d̄ =

for i ∈ 1..Z

for a ∈ 1..3

d̄_{st(i,a)} = $\frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$

d̄

d̄^T =

	1	2	3	4	5	6	7	8	9
1	0.9194	0.9194	0.8730						

d̄^T ≤ 0.9 =

	1	2	3
1	0	0	1

h =

for i ∈ 1..2Z + 1

h_i = $\frac{F_i}{\pi \cdot D_{i,av(N_r)}}$

h

h^T =

	1	2	3
1	28.50	28.50	44.88

·10^{−3}

D

	u
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$$\mathbf{u}^T =$$

$F^T =$

	1	2	3	4	5	6	7	8	9
1	60741	60741	93341						

 $\cdot 10^{-6}$

$\overline{d}_1 = 0.9194$

$\overline{d}_1 \leq 0.9 = 0$

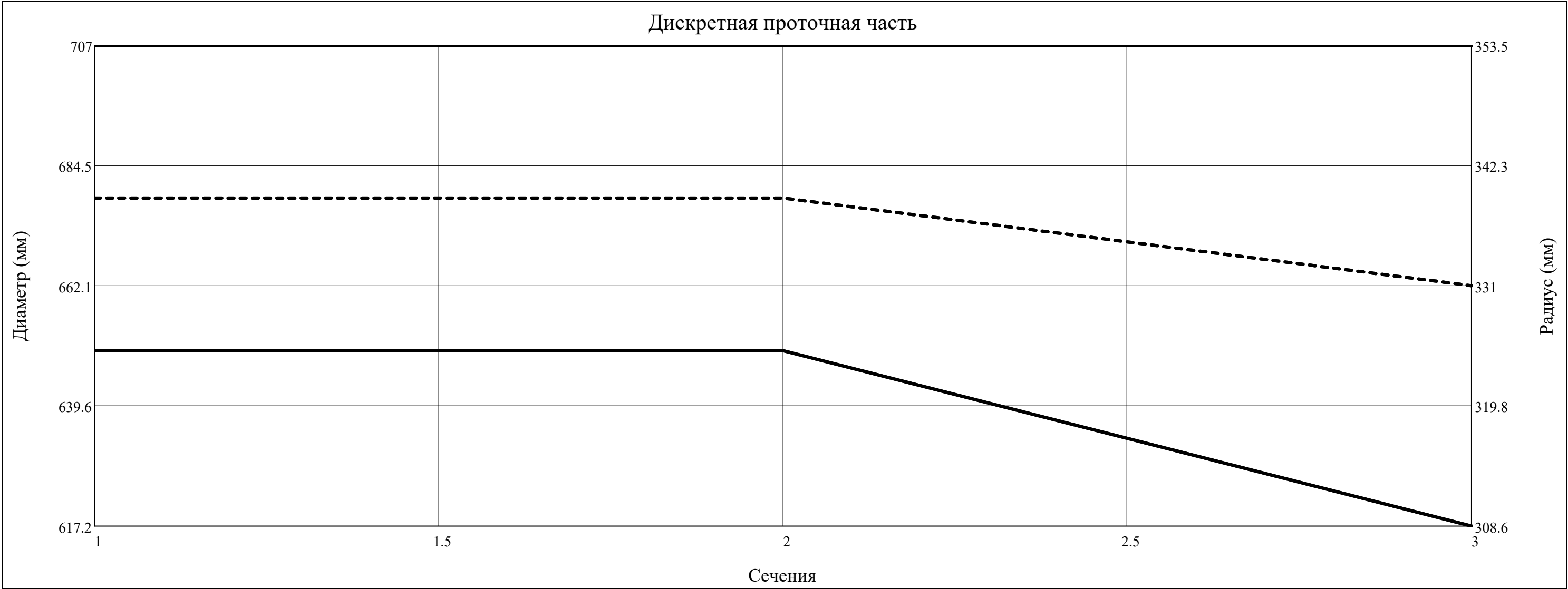
$\overline{d}^T =$

	1	2	3	4	5	6	7	8	9
1	0.9194	0.9194	0.8730						

$D^T =$

	1	2	3
1	650.0	650.0	617.2
2	678.5	678.5	662.1
3	707.0	707.0	707.0

 $\cdot 10^{-3}$



$h^T =$

	1	2	3
1	28.50	28.50	44.88

 $\cdot 10^{-3}$

$$\begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in N_r \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \end{array} \right. \\ \quad \quad \gamma_{\text{ПЧпер}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),N_r} - D_{\text{st}(i,1),N_r} \\ D_{\text{st}(i,2),1} - D_{\text{st}(i,1),1} \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),N_r} - D_{\text{st}(i,2),N_r} \\ D_{\text{st}(i,3),1} - D_{\text{st}(i,2),1} \end{pmatrix} \text{ if } a = 2 \end{array} \right. \\ \quad \quad \gamma_{\text{ПЧ}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in 1 \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \end{array} \right. \\ \quad \quad \gamma_{\text{ПЧкор}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \\ \begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} \end{array}$$

$$\text{stack}\left(\gamma_{\text{ПЧпер}}^T, \gamma_{\text{ПЧ}}^T, \gamma_{\text{ПЧкор}}^T\right) = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 0.00 & 0.00 \\ \hline 2 & -0.00 & 30.70 \\ \hline 3 & 0.00 & -30.70 \\ \hline \end{array} .^\circ$$

$$\gamma_{\text{ПЧ}}^T \leq 20.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧ}}^T \leq 25.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -12.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -15.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

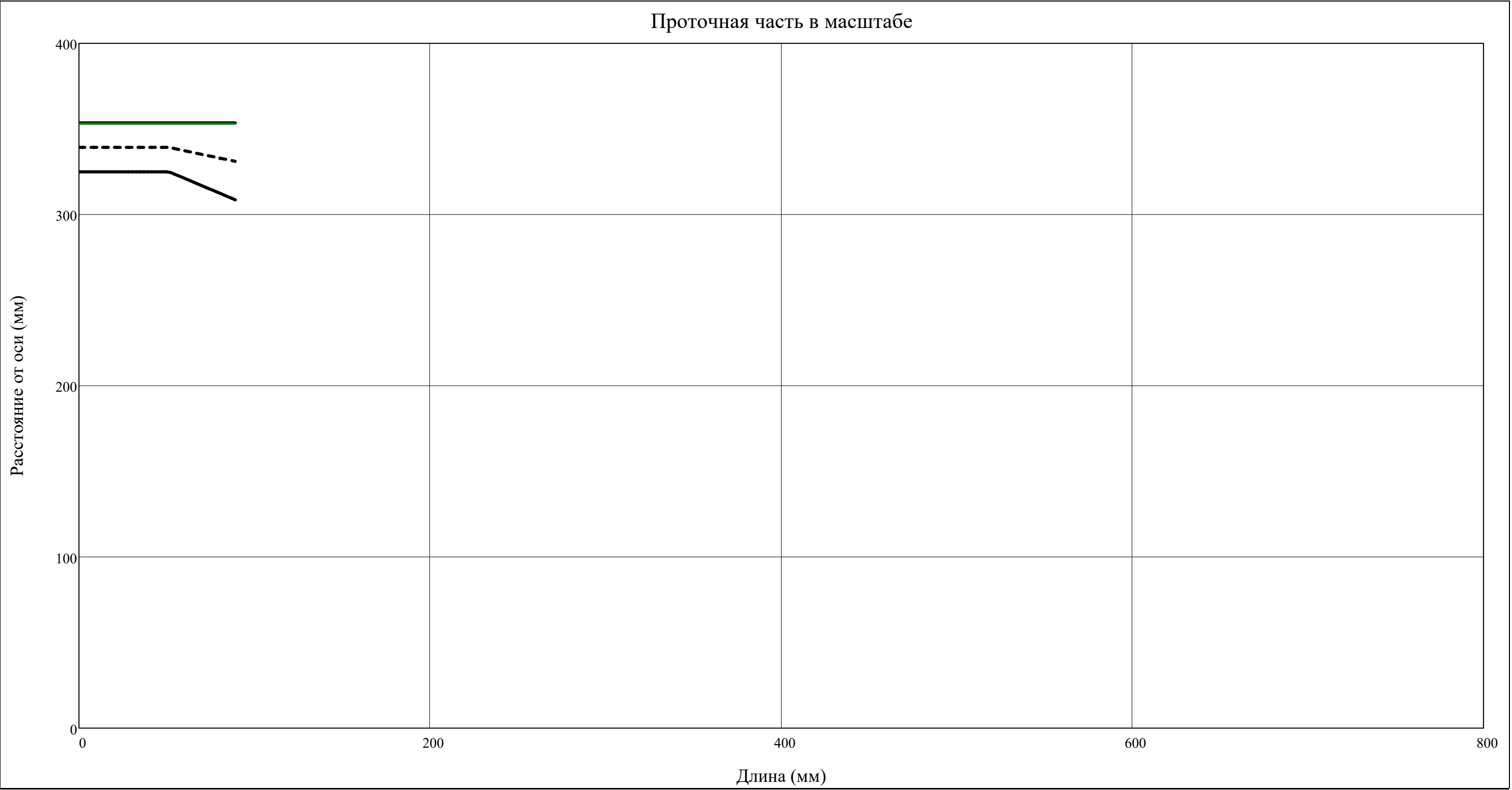
$$\begin{pmatrix} x_{\Pi\Upsilon} \\ y_{\Pi\Upsilon\text{пер}} \\ y_{\Pi\Upsilon\text{ср}} \\ y_{\Pi\Upsilon\text{кор}} \\ y_{\text{Лпер}} \end{pmatrix} = \begin{cases} c = 1 \\ x_{\Pi\Upsilon_c} = 0 \\ y_{\Pi\Upsilon\text{пер}_c} = D_{\text{st}(c, 1), N_r} \\ y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_c} \\ y_{\Pi\Upsilon\text{ср}_c} = D_{\text{st}(c, 1), \text{av}(N_r)} \\ y_{\Pi\Upsilon\text{кор}_c} = D_{\text{st}(c, 1), 1} \\ \text{for } i \in 1..Z \\ \quad c = c + 1 \\ \quad x_{\Pi\Upsilon_c} = x_{\Pi\Upsilon_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{CA_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \begin{pmatrix} y_{\Pi\Upsilon\text{пер}_c} \\ y_{\Pi\Upsilon\text{ср}_c} \\ y_{\Pi\Upsilon\text{кор}_c} \end{pmatrix} = \begin{pmatrix} D_{\text{st}(i, 2), N_r} \\ D_{\text{st}(i, 2), \text{av}(N_r)} \\ D_{\text{st}(i, 2), 1} \end{pmatrix} \\ \quad y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_i} \\ \quad c = c + 1 \\ \quad x_{\Pi\Upsilon_c} = x_{\Pi\Upsilon_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{PK_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \begin{pmatrix} y_{\Pi\Upsilon\text{пер}_c} \\ y_{\Pi\Upsilon\text{ср}_c} \\ y_{\Pi\Upsilon\text{кор}_c} \end{pmatrix} = \begin{pmatrix} D_{\text{st}(i+1, 1), N_r} \\ D_{\text{st}(i+1, 1), \text{av}(N_r)} \\ D_{\text{st}(i+1, 1), 1} \end{pmatrix} \\ \quad y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_i} \\ \begin{pmatrix} x_{\Pi\Upsilon} \\ y_{\Pi\Upsilon\text{пер}} \\ y_{\Pi\Upsilon\text{ср}} \\ y_{\Pi\Upsilon\text{кор}} \\ y_{\text{Лпер}} \end{pmatrix} \end{cases}$$

$$\text{Length} = \sum_{i=1}^Z B_{CA_i} + \sum_{i=1}^Z \Delta_{a_i} + \sum_{i=1}^Z B_{PK_i} = 78.8 \cdot 10^{-3}$$

$$x = \min(x_{\Pi\Upsilon}), \min(x_{\Pi\Upsilon}) + \frac{\max(x_{\Pi\Upsilon}) - \min(x_{\Pi\Upsilon})}{N_{\text{dis}}} .. \max(x_{\Pi\Upsilon})$$

$y_{ПЧпер}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧпер}, l) \quad y_{ПЧср}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧср}, l) \quad y_{ПЧкор}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧкор}, l)$

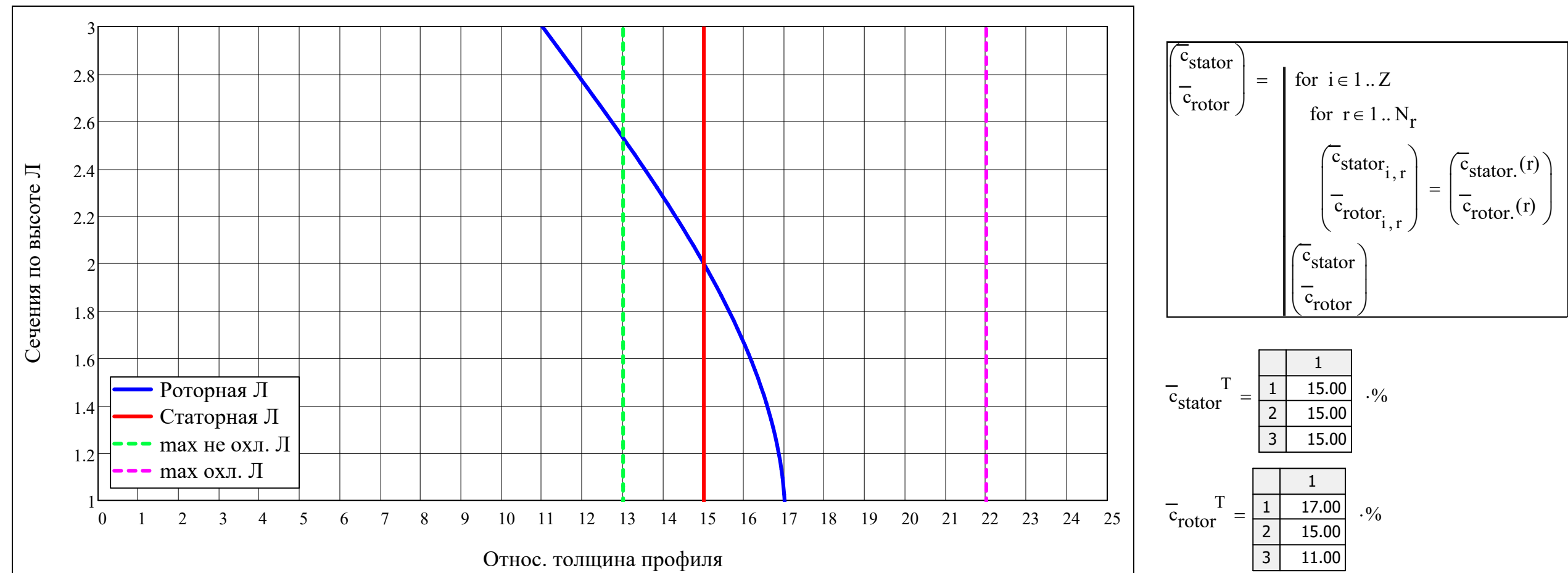
$y_{Лпер}(l) = \text{interp}(\text{cspline}(x_{ПЧ}, 0.5 \cdot y_{Лпер}), x_{ПЧ}, 0.5 \cdot y_{Лпер}, l)$



Относ. толщины ЛРК и СА:

$$\overline{c}_{\text{stator.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{Г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 11 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 11 \\ 11 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$

$$\overline{c}_{\text{rotor.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 11 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{Г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 \\ 7 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 \\ 7 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$



$$\begin{pmatrix} \overline{r_inlet}_{rotor} & \overline{r_inlet}_{stator} \\ \overline{r_outlet}_{rotor} & \overline{r_outlet}_{stator} \end{pmatrix} =$$

for i ∈ 1..Z

for r ∈ 1..N_r

$$\begin{pmatrix} \overline{r_inlet}_{stator_{i,r}} \\ \overline{r_outlet}_{stator_{i,r}} \end{pmatrix} = \begin{pmatrix} 0.4 \\ 0.2 \end{pmatrix} \cdot \overline{c}_{stator.(r)}$$

$$\begin{pmatrix} \overline{r_inlet}_{rotor_{i,r}} \\ \overline{r_outlet}_{rotor_{i,r}} \end{pmatrix} = \begin{pmatrix} 0.3 \\ 0.1 \end{pmatrix} \cdot \overline{c}_{rotor.(r)}$$

$$\begin{pmatrix} \overline{r_inlet}_{rotor} & \overline{r_inlet}_{stator} \\ \overline{r_outlet}_{rotor} & \overline{r_outlet}_{stator} \end{pmatrix}$$

$\overline{r_inlet}_{stator}^T =$

	1
1	6.000
2	6.000
3	6.000

 .%

$\overline{r_outlet}_{stator}^T =$

	1
1	3.000
2	3.000
3	3.000

 .%

$\overline{r_inlet}_{rotor}^T =$

	1
1	5.100
2	4.500
3	3.300

 .%

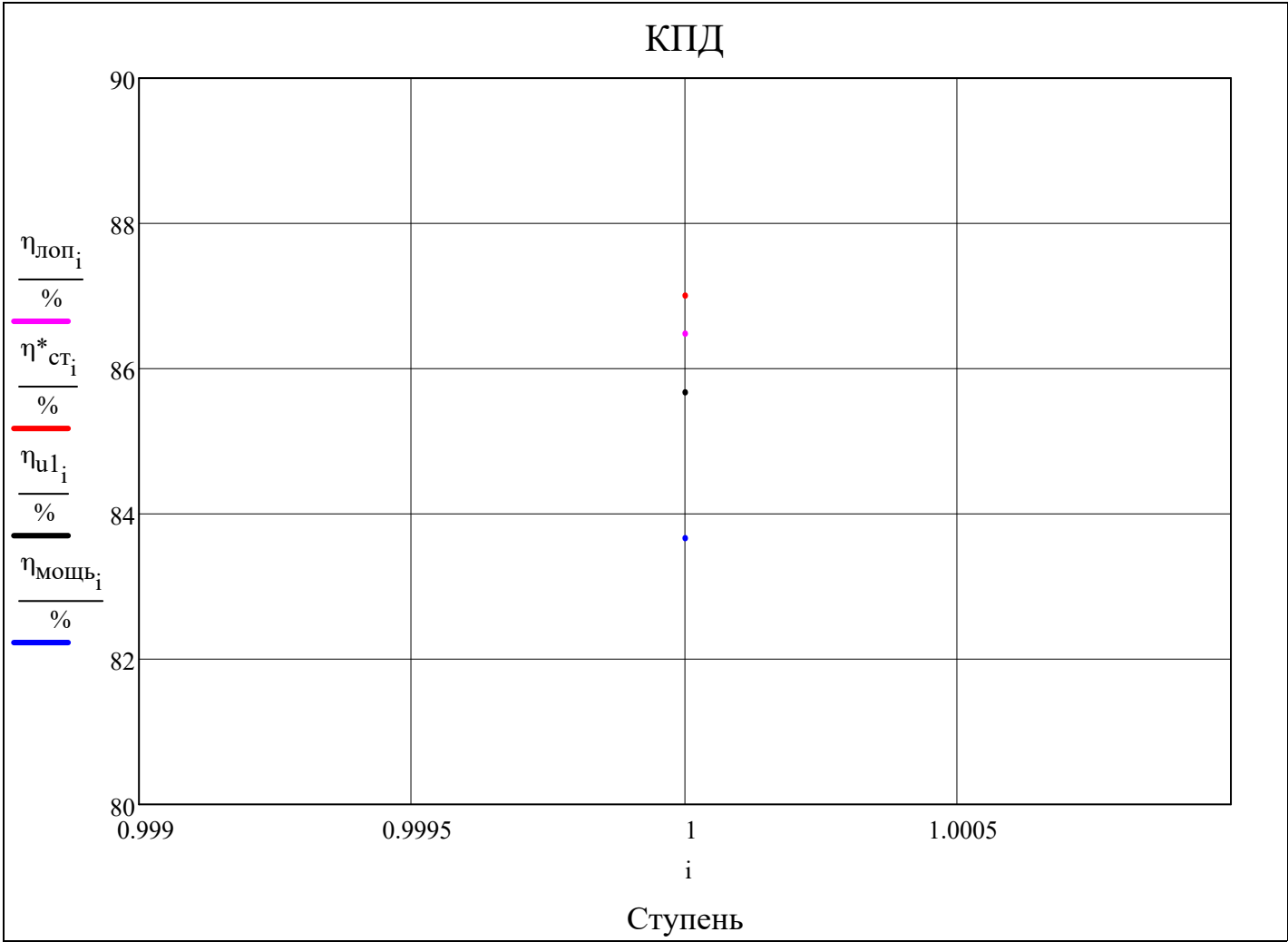
$\overline{r_outlet}_{rotor}^T =$

	1
1	1.700
2	1.500
3	1.100

 .%

▶ Вывод результатов поступенчатого расчета продольной геометрии ОТ в EXCEL:

$$R_{L.cp} = \left(\begin{array}{l} 0.16 \text{ if turbine} = \text{"ТВД"} \\ 0.13 \text{ otherwise} \end{array} \begin{array}{l} 0.15 \ 0.18 \ 0.185 \ 0.5 \ 0.5 \end{array} \right)^T$$



$$\eta_{\text{лoп}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 86.49 \\ \hline \end{array} \cdot \%$$

$$\eta^*_{\text{cт}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 87.01 \\ \hline \end{array} \cdot \%$$

$$\text{stack}\left(\eta_{\text{у1}}^T, \eta_{\text{у2}}^T\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 85.68 \\ \hline 2 & 86.99 \\ \hline \end{array} \cdot \%$$

$$\eta_{\text{мoщ}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 83.67 \\ \hline \end{array} \cdot \%$$

$$\eta_{\text{мoщ}_i} \leq \eta_{\text{у1}_i} \leq \eta^*_{\text{cт}_i} \leq \eta_{\text{лoп}_i} =$$

0

Степень понижения полного давления Т:
Степень понижения давления Т:

$$\left(\frac{\pi^*_{\text{Т}}}{\pi_{\text{Т}}}\right) = P^*_{\text{st}(1,1), \text{av}(N_{\text{r}})} \cdot \left[\frac{\left(P^*_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}}{\left(P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}} \right] =$$

	1
1	3.13
2	3.25

Температурный перепад по параметрам торможения (Дж/кг):
Располагаемый температурный перепад (Дж/кг):

$$\begin{pmatrix} H^*_{\text{Т}} \\ H_{\text{Т}} \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^Z H^*_{\text{сТ}_i} \\ \sum_{i=1}^Z H_{\text{сТ}_i} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 515.3 \\ 535.8 \end{pmatrix} \cdot 10^3$$

Мощность Т (Вт):

$$\sum_{i=1}^Z N_{\text{сТ}_i} = 14.89 \cdot 10^6$$

$$\text{eps}\left(\text{"rel"}, N_{\text{Т}}, \sum_{i=1}^Z N_{\text{сТ}_i}\right) = 0.000\cdot\%$$

Удельная поступенчатая работа Т [Дж/кг]:

$$L_{\text{Т}} = \sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} = 448.6 \cdot 10^3$$

Лопаточный КПД Т:

$$\eta_{\text{Тлоп}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} + \frac{\left(c_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^2}{2}}{H_{\text{Т}}} = 86.53\cdot\%$$

$$k_{\text{Т.ср}} = k_{\text{ад}}\left(C_{\text{рГаз.ср}}\left(P_{\text{st}(1,1), \text{av}(N_{\text{r}})}, P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, T_{\text{st}(1,1), \text{av}(N_{\text{r}})}, T_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, \alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right), R_{\text{Газ.ср}}\left(\alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right)\right) = 1.289$$

Адиабатный КПД Т:

$$\eta^*_{\text{Т}} = \frac{L_{\text{Т}}}{H^*_{\text{Т}}} = 87.06\cdot\%$$

Политропический КПД Т:

$$\eta^*_{\text{Т.п}} = \eta^*_{\text{н}}\left(\text{"расширение"}, \eta^*_{\text{Т}}, \pi^*_{\text{Т}}, k_{\text{Т.ср}}\right) = 85.53\cdot\%$$

Мощностной КПД Т:

$$\eta_{\text{Тмощь}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)}}{H_{\text{Т}}} = 83.72\cdot\%$$

$$L_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 448.3 \\ \hline \end{array} \cdot 10^3$$

$$N_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14.89 \\ \hline \end{array} \cdot 10^6$$

$$Lu_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 459.1 \\ \hline \end{array} \cdot 10^3$$

$$Lu_{\text{нагрузка}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.7 \\ \hline \end{array}$$

$$H_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 535.8 \\ \hline \end{array} \cdot 10^3$$

$$\text{stack}\Big(H_{\text{stator}}^T, H_{\text{rotor}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 450.1 \\ \hline 2 & 86.8 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\Big(R_L^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.2 \\ \hline \end{array}$$

$$G^T = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 32.193 & 33.050 & 33.351 \\ \hline \end{array}$$

$$\alpha_{\text{ox}}^T = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2.267 & 2.294 & 2.303 \\ \hline \end{array}$$

$$\text{stack}\Big(\theta_{\text{CA}}^T, \theta_{\text{PK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.432 \\ \hline 2 & 0.206 \\ \hline \end{array}$$

$$\text{stack}\Big(g_{\text{oxлCA}}^T, g_{\text{oxлPK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 26.61 \\ \hline 2 & 9.11 \\ \hline \end{array} \cdot 10^{-3}$$

$$G_{\text{oxлCA}_i} = g_{\text{oxлCA}_i} \cdot G_{\text{st}(i, 1)}$$

$$G_{\text{oxлPK}_i} = g_{\text{oxлPK}_i} \cdot G_{\text{st}(i, 2)}$$

$$\text{stack}\Big(G_{\text{oxлCA}}^T, G_{\text{oxлPK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.9 \\ \hline 2 & 0.3 \\ \hline \end{array}$$

$$G_{\text{cooling}} = 3.2$$

$$\sum_{i=1}^Z G_{\text{oxлCA}_i} + \sum_{i=1}^Z G_{\text{oxлCA}_i} \leq G_{\text{cooling}} = 1$$

$$\text{stack}\left(\text{iteration}_{\text{CA}}^{\text{T}}, \text{iteration}_{\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2 \\ \hline 2 & 2 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{k}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1.3 & 1.3 & 1.3 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{P}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2731.8 & 2414.3 & 872.3 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\left(\mathbf{P}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2705.2 & 1019.2 & 840.1 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\left(\mathbf{T}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1773.0 & 1759.0 & 1394.2 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{T}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1769.2 & 1447.5 & 1382.3 \\ \hline \end{array}$$

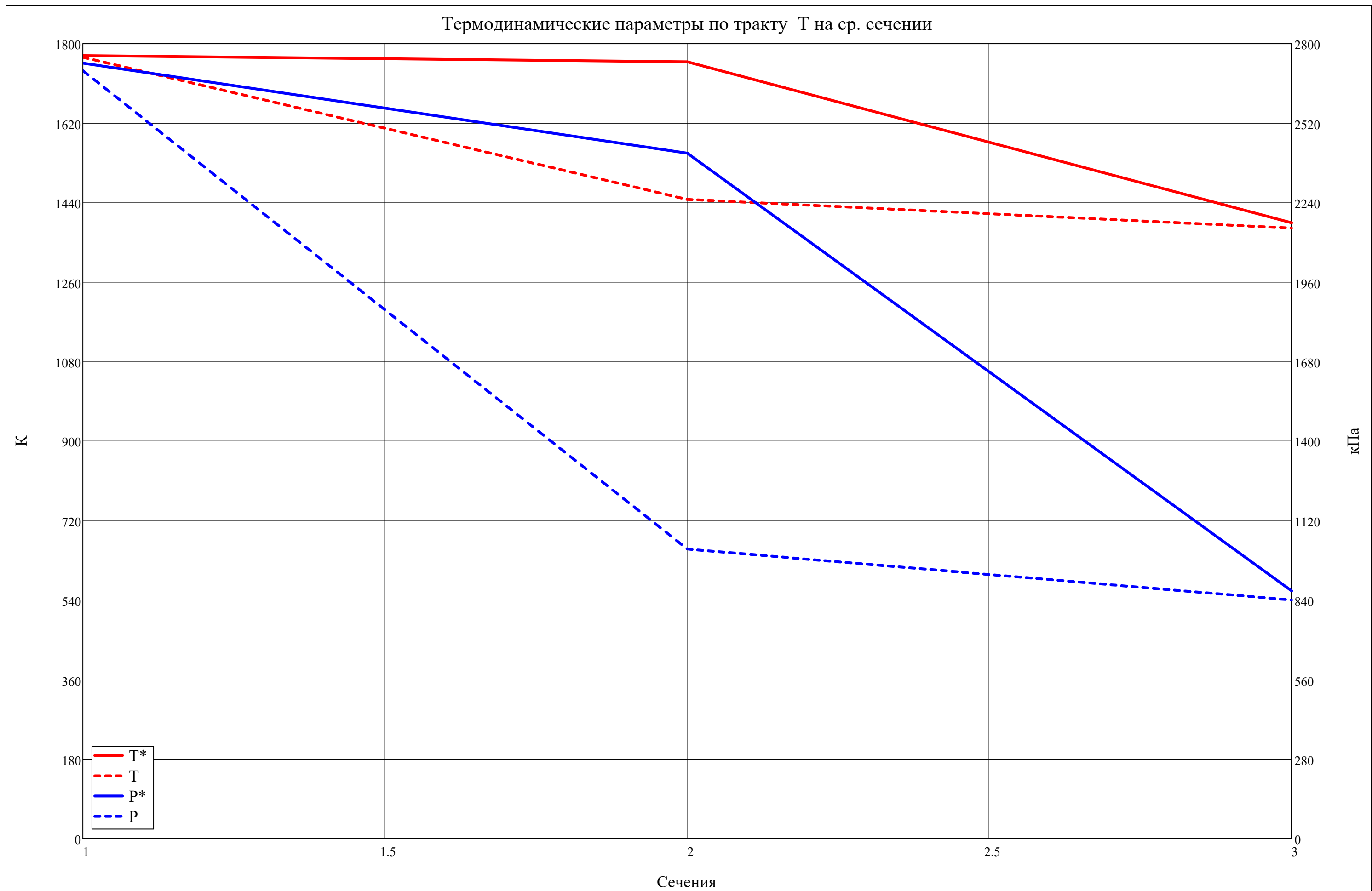
$$\text{submatrix}\left(\mathbf{T}^{*\text{wT}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 1509.9 & 1500.3 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{T}_{\text{a}\mathcal{I}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 1429.1 & 1379.3 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{v}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.189 & 0.410 & 0.486 \\ \hline \end{array}$$

$$\text{submatrix}\left(\boldsymbol{\rho}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.341 & 4.758 & 2.169 \\ \hline \end{array}$$

$$\text{submatrix}\left(\boldsymbol{\rho}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z+1\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.300 & 2.441 & 2.058 \\ \hline \end{array}$$



$$\text{submatrix}\left(\mathbf{a}_{3\text{B}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 809.2 & 734.8 & 718.8 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{a}^*\mathbf{c}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 758.2 & 756.5 & 673.8 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{a}^*\mathbf{w}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 700.9 & 699.0 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 100.0 & 891.8 & 173.6 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{u}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 863.5 & -1.9 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{a}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 100.0 & 222.9 & 173.6 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 398.7 & 546.4 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\text{u}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 330.6 & 518.1 \\ \hline \end{array}$$

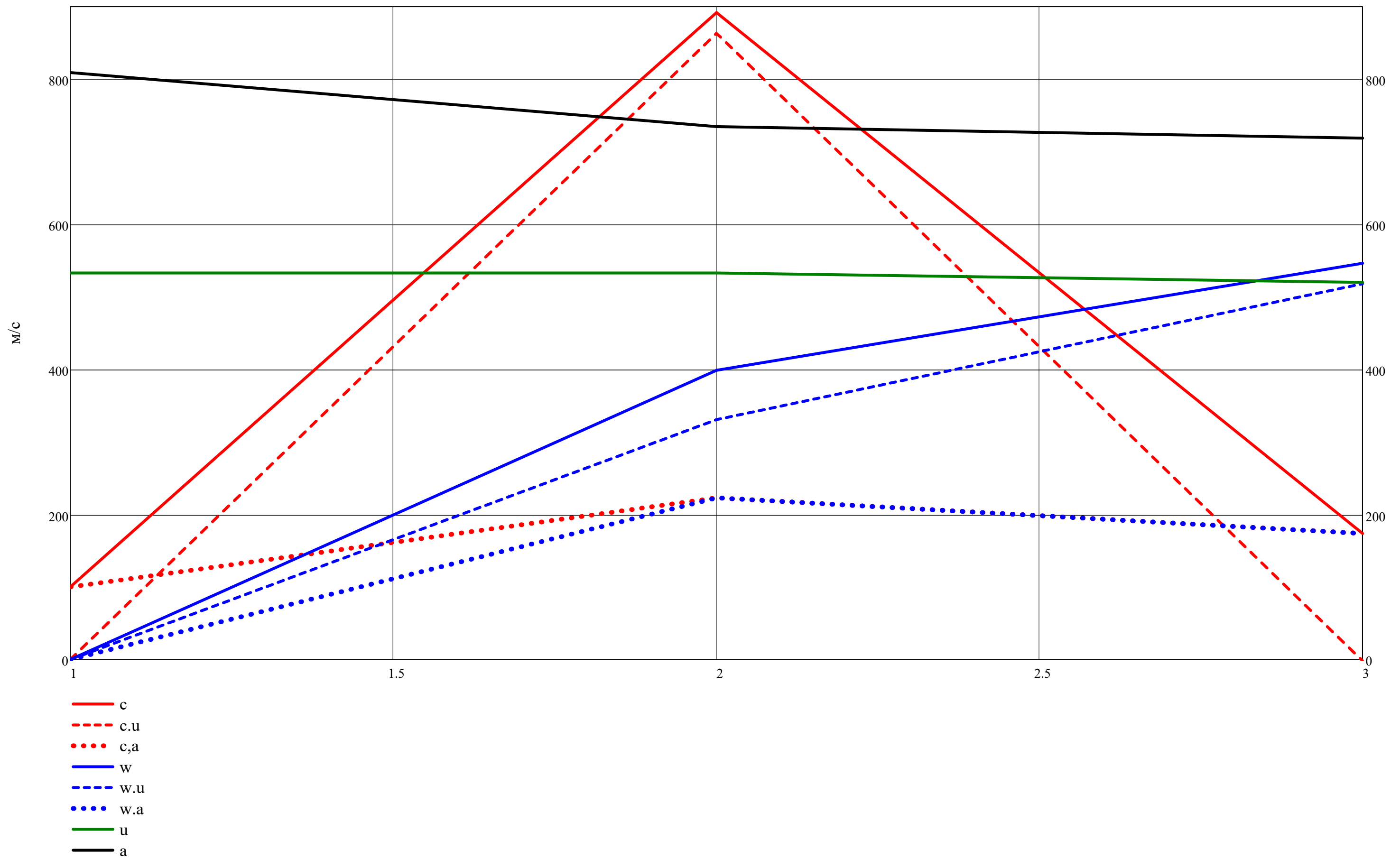
$$\text{submatrix}\left(\mathbf{w}_{\text{a}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 222.9 & 173.6 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{a}\text{I}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z\right)=\begin{array}{|c|c|c|}\hline & 1 & 2 \\ \hline 1 & 1035.2 & 948.8 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\text{a}\text{I}}^{\text{T}},\text{av}\left(\mathbf{N}_{\text{r}}\right),\text{av}\left(\mathbf{N}_{\text{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 0.0 & 564.9 \\ \hline \end{array}$$

$$\mathbf{u}^{\text{T}}=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 510.5 & 510.5 & 484.8 \\ \hline 2 & 532.9 & 532.9 & 520.0 \\ \hline 3 & 555.2 & 555.2 & 555.2 \\ \hline \end{array}$$

Скорости по тракту Т на ср. сечении



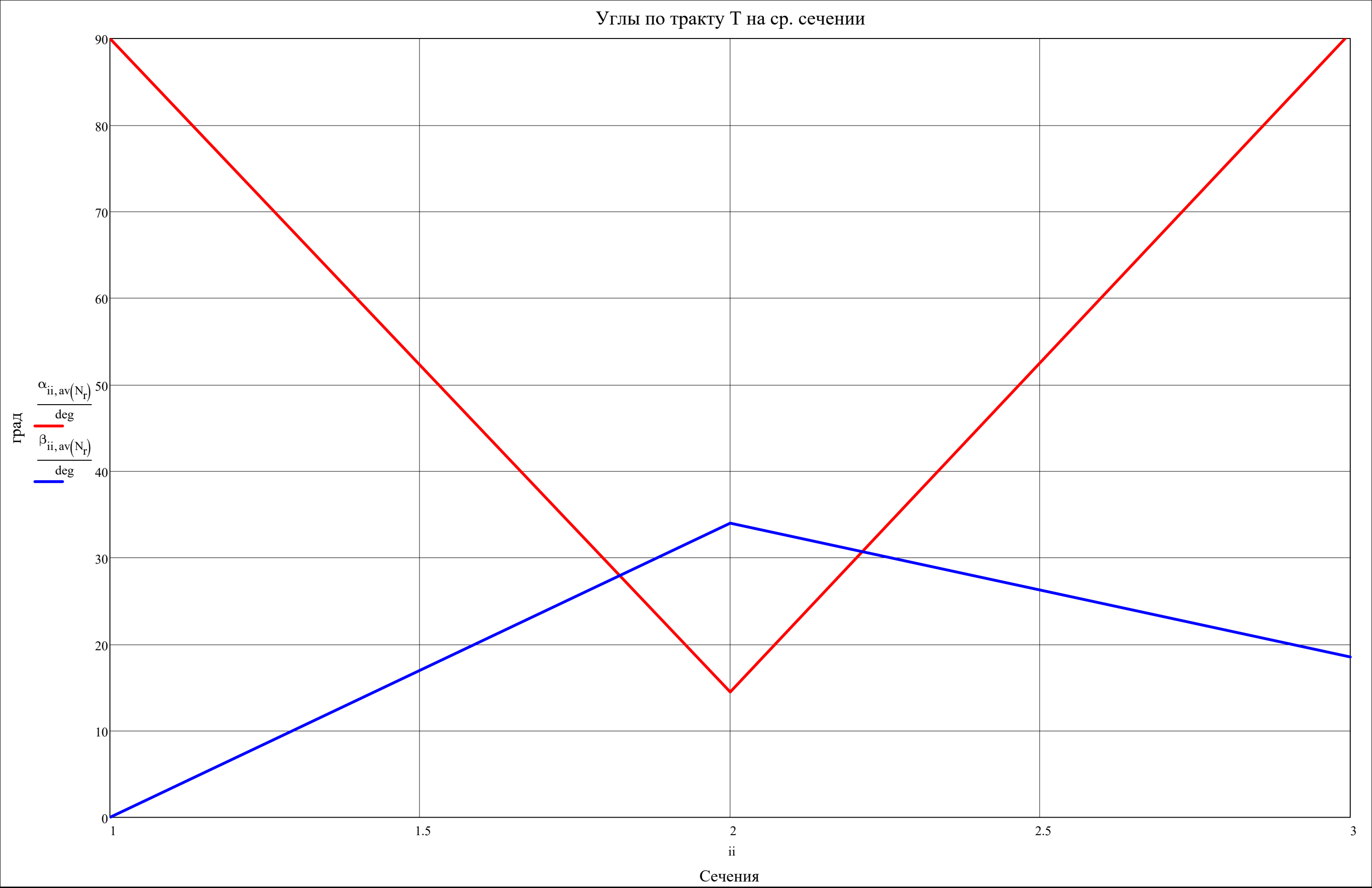
$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 90.00 & 14.48 & 90.64 & & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}\geq 11\cdot^{\circ}=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1 & 1 & 1 & & & & & & \\ \hline \end{array}$$

$$\text{submatrix}\Big(\beta,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 \\ \hline 1 & 0.00 & 33.99 & 18.53 & & & & & & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{stator}},1,Z,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -75.52 & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{rotor}},1,Z,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -15.47 & & & & & \\ \hline \end{array} \cdot^{\circ}$$



$$\text{submatrix}\Big(\lambda_{\mathbf{c}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.1319 & 1.1789 & 0.2577 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\lambda_{\mathbf{w}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0000 & 0.5689 & 0.7817 \\ \hline \end{array}$$

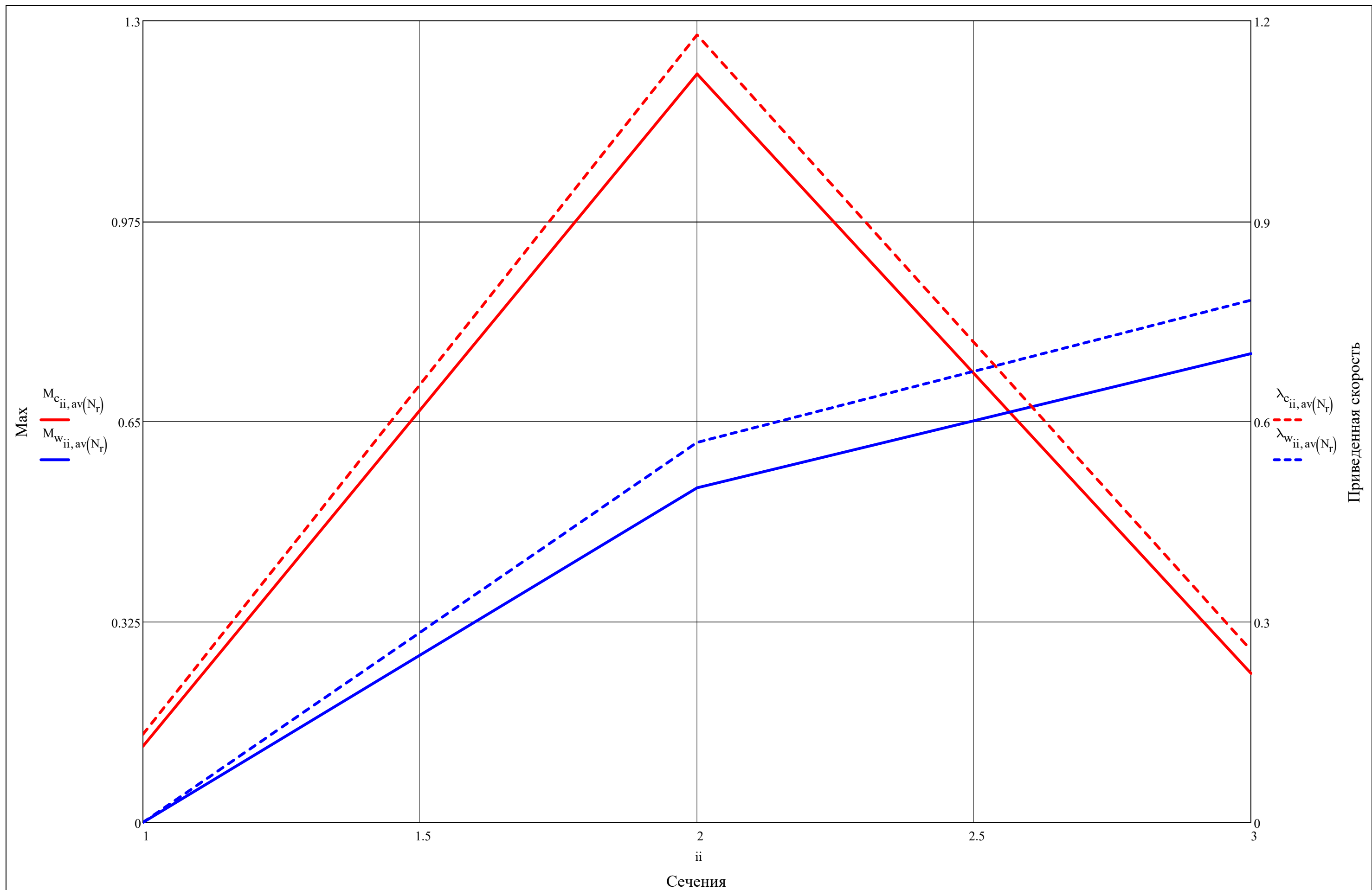
$$\text{submatrix}\Big(\mathbf{M}_{\mathbf{c}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.1236 & 1.2137 & 0.2416 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\mathbf{M}_{\mathbf{c}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} \leq 1 = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1 & 0 & 1 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\mathbf{M}_{\mathbf{w}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0000 & 0.5427 & 0.7602 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\mathbf{M}_{\mathbf{w}},1,2Z+1,\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big),\text{av}\Big(\mathbf{N}_{\mathbf{r}}\Big)\Big)^{\text{T}} \leq 1 = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\text{stack}\Big(v_{\text{stator}}^{\text{T}},v_{\text{rotor}}^{\text{T}}\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 37.02 \\ \hline 2 & 67.06 \\ \hline \end{array} .^{\circ}$$



$$\mathbf{t}_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 56.7 \\ \hline 2 & 59.2 \\ \hline 3 & 61.7 \\ \hline \end{array} \cdot 10^{-3}$$

$$\mathbf{t}_{\text{rotor}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 20.5 \\ \hline 2 & 21.7 \\ \hline 3 & 22.9 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{stator}}^{\text{T}},\text{av}\big(\text{N}_{\text{r}}\big),\text{av}\big(\text{N}_{\text{r}}\big),1,Z\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 68.0 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{rotor}}^{\text{T}},\text{av}\big(\text{N}_{\text{r}}\big),\text{av}\big(\text{N}_{\text{r}}\big),1,Z\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 30.0 \\ \hline \end{array} \cdot 10^{-3}$$

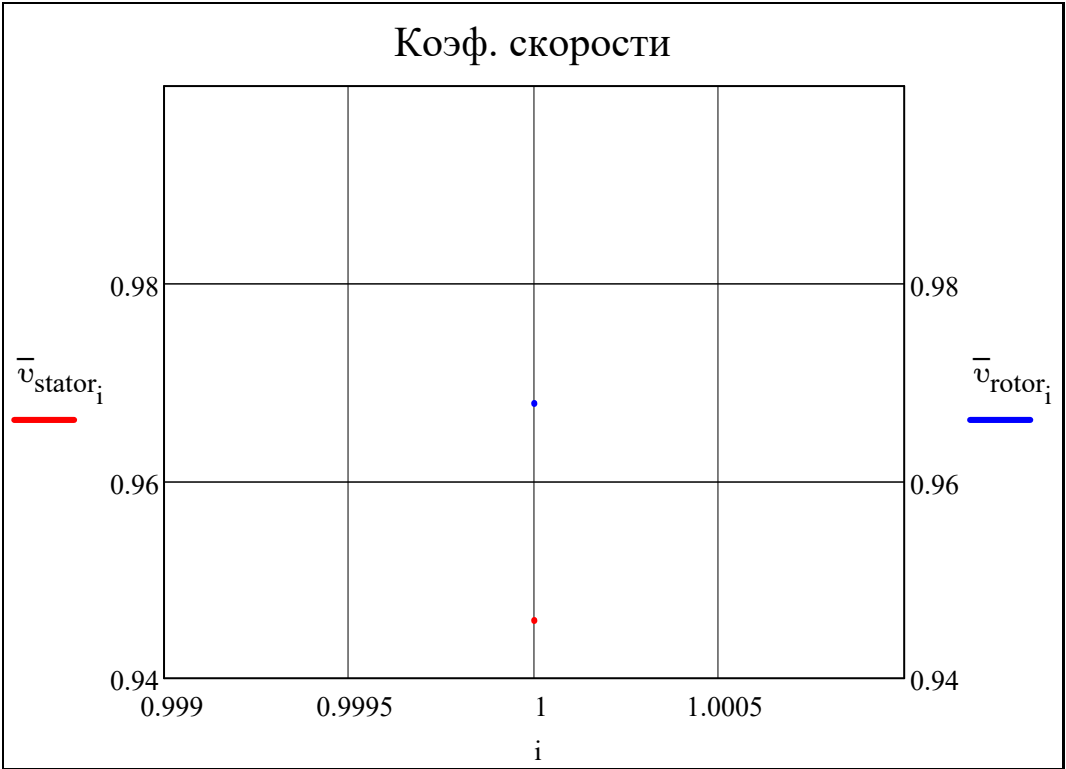
$$\text{stack}\Big(\mathbf{Z}_{\text{stator}}^{\text{T}},\mathbf{Z}_{\text{rotor}}^{\text{T}}\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 36 \\ \hline 2 & 97 \\ \hline \end{array}$$

$$\text{stack}\Big(\overline{\mathbf{t}}_{\text{OPII} \text{CA}}^{\text{T}},\overline{\mathbf{t}}_{\text{OPII} \text{PK}}^{\text{T}}\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.872 \\ \hline 2 & 0.725 \\ \hline \end{array}$$

$$\frac{\mathbf{t}_{\text{stator}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}}{\text{chord}_{\text{stator}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}} = \boxed{0.871} \leq \frac{\mathbf{t}_{\text{stator}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}}{\boxed{1}} \leq 1 = \frac{\mathbf{t}_{\text{rotor}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}}{\text{chord}_{\text{rotor}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}} = \boxed{0.725} \leq \frac{\mathbf{t}_{\text{rotor}_{\text{i},\text{av}\big(\text{N}_{\text{r}}\big)}}}{\boxed{1}} \leq 1 =$$

$$\text{stack}\left(\overline{v}_{\text{stator}}^T, \overline{v}_{\text{rotor}}^T\right) =$$

	1
1	0.9459
2	0.9679



$$\text{stack}\left(\xi_{\text{TpCA}}^{\text{T}}, \xi_{\text{TpPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.398 \\ \hline 2 & 2.622 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{KpCA}}^{\text{T}}, \xi_{\text{KpPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.756 \\ \hline 2 & 1.303 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ReCA}}^{\text{T}}, \xi_{\text{RePK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -0.135 \\ \hline 2 & 0.111 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\lambda\text{CA}}^{\text{T}}, \xi_{\lambda\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.415 \\ \hline 2 & 0.023 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{BTCA}}^{\text{T}}, \xi_{\text{BTPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.452 \\ \hline 2 & 0.806 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{TDCA}}^{\text{T}}, \xi_{\text{TDPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.857 \\ \hline 2 & 1.207 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{сmCA}}^{\text{T}}, \xi_{\text{сmPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.784 \\ \hline 2 & 0.249 \\ \hline \end{array} \cdot\%$$

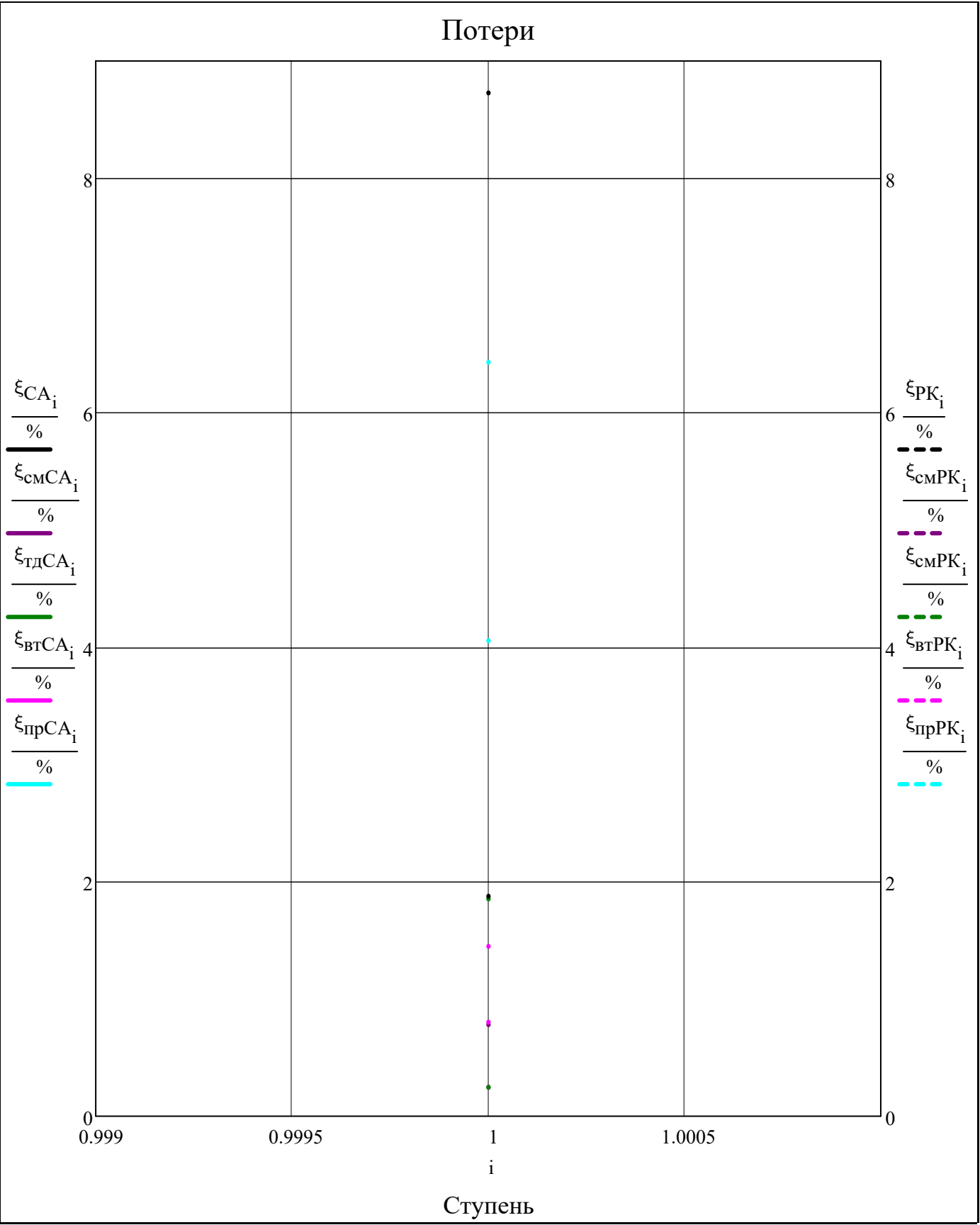
$$\text{stack}\left(\xi_{\text{CA}}^{\text{T}}, \xi_{\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 8.731 \\ \hline 2 & 1.880 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{ВЫХ}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.814 \\ \hline \end{array} \cdot\%$$

$$\xi_{\Delta\text{r}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.480 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{Гр.В}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.834 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ппCA}}^{\text{T}}, \xi_{\text{ппPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6.434 \\ \hline 2 & 4.059 \\ \hline \end{array} \cdot\%$$



$$m_{\text{ww}} = \begin{pmatrix} \overline{v}_{\text{stator}_1} \cdot \cos\left(\alpha_{\text{st}(1,2), \text{av}(N_r)}\right)^2 \text{ if } Z = 1 \\ -0.5 \text{ otherwise} \\ -0.25 \\ 0 \\ 0.25 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{"}\alpha.2=\text{const"}\\ \text{"}\Gamma=\text{const"}\\ \text{"}m=\text{const"}\\ \text{"}R=\text{const"}\end{pmatrix} = \begin{pmatrix} \cos\left(\alpha_{\text{st}(i,2), \text{av}(N_r)}\right)^2 \cdot \overline{v}_{\text{stator}_i} \\ 1 \cdot \overline{v}_{\text{stator}_i} \\ 0.2 \\ -1 \cdot \overline{v}_{\text{stator}_i} \end{pmatrix}$$

m^T =

	1	2	3	4	5	6
1	0.8868	-0.2500	0.0000	0.2500	1.0000	1.0000

P*	P	
T*	T*_w	
T	T	
ρ*	ρ	
k	R_L	
a*_c	a*_w	
a_3B	a_3B	
c	w	=
c_u	w_u	for i ∈ 1..Z
c_a	w_a	for a ∈ 2..3
Δc_a	Δc_a	for r ∈ 1..N_r
α	β	$A_{st(i,a),r} = \left(1 - R_{L_{i,av}(N_r)}\right) \cdot \omega \cdot \left(R_{st(i,a),av(N_r)}\right)^{m_i+1}$
λ_c	M_c	$B_{st(i,a),r} = \frac{Lu_{cT_i}}{2 \cdot \omega}$
λ_w	M_w	$c_{u_{st(i,a),r}} =$
ε_stator	ε_rotor	<div><div><div><div><div><div>$\text{if } m_i = \overline{v}_{stator_i} \cdot \cos\left(\alpha_{st(i,2),av(N_r)}\right)^2$</div><div>$c_{u_{st(i,a),av(N_r)}} \cdot \left(\frac{R_{st(i,a),av(N_r)}}{R_{st(i,a),r}}\right)^{m_i}$</div><div>$\frac{u_{st(i,a-1),av(N_r)} \cdot c_{u_{st(i,a-1),av(N_r)}} + u_{st(i,a),av(N_r)} \cdot c_{u_{st(i,a),av(N_r)}} - u_{st(i,a-1),r} \cdot c_{u_{st(i,a-1),r}}}{u_{st(i,a),r}}$</div><div>$\text{if } (a = 1) \vee (a = 3)$</div></div></div><div><div>otherwise</div><div>$\frac{A_{st(i,a),r}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a),r}}{\left(R_{st(i,a),r}\right)}$</div><div>$-\frac{A_{st(i,a),r}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a),r}}{\left(R_{st(i,a),r}\right)}$</div><div>$\text{if } (a = 1) \vee (a = 3)$</div></div></div></div></div> <div>$c_{a_{st(i,a),r}} =$</div> <div><div><div><div>$\text{if } m_i = -1$</div><div>$\sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a),r}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] - 4 \cdot A_{st(i,a),r} \cdot B_{st(i,a),r} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)}$</div><div>$\sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a),r}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] + 4 \cdot A_{st(i,a),r} \cdot B_{st(i,a),r} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)}$</div><div>$\text{if } (a = 1) \vee (a = 3)$</div></div></div></div>

$$\begin{aligned}
& \text{if } m_i = 0 \\
& \quad \sqrt{\left(c_{a_{st(i,a), av(N_r)}} \right)^2 - 2 \cdot (A_{st(i,a), r})^2 \cdot \left(\ln(R_{st(i,a), r}) - \ln(R_{st(i,a), av(N_r)}) \right) + 2 \cdot A_{st(i,a), r} \cdot B_{st(i,a), r} \cdot \left(\frac{1}{R_{st(i,a), r}} - \frac{1}{R_{st(i,a), av(N_r)}} \right)} \quad \text{if } (a = 2) \\
& \quad \sqrt{\left(c_{a_{st(i,a), av(N_r)}} \right)^2 - 2 \cdot (A_{st(i,a), r})^2 \cdot \left(\ln(R_{st(i,a), r}) - \ln(R_{st(i,a), av(N_r)}) \right) - 2 \cdot A_{st(i,a), r} \cdot B_{st(i,a), r} \cdot \left(\frac{1}{R_{st(i,a), r}} - \frac{1}{R_{st(i,a), av(N_r)}} \right)} \quad \text{if } (a = 1) \vee (a = 3) \\
& \text{if } m_i = \bar{v}_{stator_i} \cdot \cos(\alpha_{st(i,2), av(N_r)})^2 \\
& \quad c_{a_{st(i,a), av(N_r)}} \cdot \sqrt{1 + \frac{\left(\frac{\bar{v}_{stator_i}}{1 - \frac{\bar{v}_{stator_i}}{m_i}} \right) \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{2 \cdot m_i}} \right]}{\tan(\alpha_{st(i,2), av(N_r)})^2}} \quad \text{if } (a = 2) \\
& \quad \sqrt{\left(c_{a_{st(i,a), av(N_r)}} \right)^2 \dots \quad \text{if } (a = 1) \vee (a = 3) \\
& \quad + \left[1 - (\bar{v}_{rotor_i})^2 \right] \cdot \left(u_{st(i,a), av(N_r)} \right)^2 \cdot \left[1 - \left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^2 \right] - 2 \cdot c_{u_{st(i,a), av(N_r)}} \cdot u_{st(i,a), av(N_r)} \cdot \left[1 - \left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{1-m_i} \right] \dots \\
& \quad + \left[1 - (\bar{v}_{rotor_i})^2 \right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^2} \right] \cdot \left(c_{u_{st(i,a-1), av(N_r)}} + c_{u_{st(i,a), av(N_r)}} \right)^2 \dots \\
& \quad + -2 \cdot c_{u_{st(i,a-1), av(N_r)}} \cdot \left(c_{u_{st(i,a-1), av(N_r)}} + c_{u_{st(i,a), av(N_r)}} \right) \cdot \left[1 - \frac{2}{m_i + 1} \cdot (\bar{v}_{rotor_i})^2 \right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{m_i+1}} \right] \dots \\
& \quad + \left(c_{u_{st(i,a-1), av(N_r)}} \right)^2 \cdot \left[1 - \frac{(\bar{v}_{stator_i})^2 \cdot (\bar{v}_{rotor_i})^2}{m_i} \right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{2 \cdot m_i}} \right] \\
& \text{otherwise} \\
& \quad \sqrt{\left(c_{a_{st(i,a), av(N_r)}} \right)^2 + \frac{A_{st(i,a), r} \cdot (m_i - 1) \cdot \left[A_{st(i,a), r} \cdot (1 + m_i) \cdot \left[(R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)}) - (R_{st(i,a), r}) \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right] \dots \right.}{+ 2 \cdot B_{st(i,a), r} \cdot m_i \cdot \left[(R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)})^{m_i} - (R_{st(i,a), r})^{m_i} \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right]} \quad \text{if } (a = 2) \\
& \quad m_i \cdot (m_i + 1) \cdot (R_{st(i,a), r} \cdot R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \\
& \quad \left. \left(c_{a_{st(i,a), av(N_r)}} \right)^2 + \frac{A_{st(i,a), r} \cdot (m_i - 1) \cdot \left[A_{st(i,a), r} \cdot (1 + m_i) \cdot \left[(R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)}) - (R_{st(i,a), r}) \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right] \dots \right.}{+ -2 \cdot B_{st(i,a), r} \cdot m_i \cdot \left[(R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)})^{m_i} - (R_{st(i,a), r})^{m_i} \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right]} \quad \text{if } (a = 1) \vee (a = 3) \\
& \quad \left. \left(c_{a_{st(i,a), av(N_r)}} \right)^2 + \dots \right]
\end{aligned}$$

$$\begin{aligned}
& \left| \left| \left| \left(\frac{c_{a_{i,r}}}{c_{u_{i,r}}} \right) \right| \right| \right| \left(\frac{c_{a_{i,r}}}{c_{u_{i,r}}} \right) \\
& \text{for } i \in 1..2 \cdot Z + 1 \\
& \text{for } r \in 1..N_r \\
& \begin{pmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{pmatrix} = c_{i,av(N_r)} \cdot \begin{pmatrix} \cos(\alpha_{i,av(N_r)}) \\ \sin(\alpha_{i,av(N_r)}) \end{pmatrix} \quad \text{if } (i = 1) \\
& P_{i,r}^* = P_{i,av(N_r)}^* \\
& T_{i,r}^* = T_{i,av(N_r)}^* \\
& \rho_{i,r}^* = \frac{P_{i,r}^*}{R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}^*} \\
& k_{i,r} = k_{\text{aД}} \left(C_{\text{pBO3Дyx}}(P_{i,r}^*, T_{i,r}^*), R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \right) \\
& a_{c_{i,r}}^* = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}^*} \\
& \alpha_{i,r} = \text{triangle}(c_{a_{i,r}}, c_{u_{i,r}}) \\
& c_{i,r} = \frac{c_{a_{i,r}}}{\sin(\alpha_{i,r})} \\
& \lambda_{c_{i,r}} = \frac{c_{i,r}}{a_{c_{i,r}}^*} \\
& \begin{pmatrix} T_{i,r} \\ P_{i,r} \\ \rho_{i,r} \end{pmatrix} = \begin{pmatrix} T_{i,r}^* \cdot \Gamma_{\text{Д}} \Phi("T", \lambda_{c_{i,r}}, k_{i,r}) \\ P_{i,r}^* \cdot \Gamma_{\text{Д}} \Phi("P", \lambda_{c_{i,r}}, k_{i,r}) \\ \rho_{i,r}^* \cdot \Gamma_{\text{Д}} \Phi("P", \lambda_{c_{i,r}}, k_{i,r}) \end{pmatrix} \\
& a_{3B_{i,r}} = \sqrt{k_{i,r} \cdot R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}} \\
& M_{c_{i,r}} = \frac{c_{i,r}}{a_{3B_{i,r}}} \\
& \beta_{i,r} = \text{triangle}(c_{a_{i,r}}, u_{i,r} - c_{u_{i,r}}) \\
& w_{i,r} = \frac{c_{a_{i,r}}}{\sin(\beta_{i,r})} \\
& \begin{pmatrix} w_{u_{i,r}} \\ w_{a_{i,r}} \end{pmatrix} = w_{i,r} \cdot \begin{pmatrix} \cos(\beta_{i,r}) \\ \sin(\beta_{i,r}) \end{pmatrix} \\
& T_{i,r}^* = \sqrt{(c_{i,r})^2 - (w_{i,r})^2}
\end{aligned}$$

$$m_i \cdot (m_i + 1) \cdot \left(R_{\text{st}(i,a)}, r \cdot R_{\text{st}(i,a),av(N_r)} \right)^{2 \cdot m_i + 1}$$

$$\begin{aligned}
T_{w_{i,r}}^* &= T_{i,r} - \frac{k_{i,r}}{k_{i,r} - 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \\
a_{w_{i,r}}^* &= \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \cdot T_{w_{i,r}}^*} \\
\lambda_{w_{i,r}} &= \frac{w_{i,r}}{a_{w_{i,r}}^*} \\
M_{w_{i,r}} &= \frac{w_{i,r}}{a_{3B_{i,r}}}
\end{aligned}$$

for $i \in 1..Z$

for $r \in 1..N_r$

$$\begin{aligned}
&\begin{pmatrix} \Delta c_{a_{st(i,1),r}} \\ \Delta c_{a_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} c_{a_{st(i,2),r}} - c_{a_{st(i,1),r}} \\ c_{a_{st(i,3),r}} - c_{a_{st(i,2),r}} \end{pmatrix} \\
R_{L_{i,r}} &= 1 - \frac{c_{u_{st(i,2),r}} - c_{u_{st(i,3),r}}}{u_{st(i,2),r} + u_{st(i,3),r}} \\
\varepsilon_{stator_{i,r}} &= \begin{cases} \alpha_{st(i,2),r} - \alpha_{st(i,1),r} & \text{if } \alpha_{st(i,2),r} \geq \frac{\pi}{2} \\ \alpha_{st(i,1),r} - \alpha_{st(i,2),r} & \text{otherwise} \end{cases} \\
\varepsilon_{rotor_{i,r}} &= \begin{cases} \beta_{st(i,3),r} - \beta_{st(i,2),r} & \text{if } \beta_{st(i,3),r} \geq \frac{\pi}{2} \\ \beta_{st(i,2),r} - \beta_{st(i,3),r} & \text{otherwise} \end{cases}
\end{aligned}$$

$$\begin{pmatrix} P^* & T^* & T & \rho^* & k & a_c^* & a_{3B} & c & c_u & c_a & \Delta c_a & \alpha & \lambda_c & \lambda_w & \varepsilon_{stator} \end{pmatrix}^T$$

$$\begin{pmatrix} P & T_w^* & T & \rho & R_L & a_w^* & a_{3B} & w & w_u & w_a & \Delta c_a & \beta & M_c & M_w & \varepsilon_{rotor} \end{pmatrix}^T$$

$$\mathbf{p}^{*\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2731.8 & 2414.3 & 872.3 \\ \hline 2 & 2731.8 & 2414.3 & 872.3 \\ \hline 3 & 2731.8 & 2414.3 & 872.3 \\ \hline \end{array} \cdot 10^3$$

$$\mathbf{T}^{*\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1773 & 1759 & 1394 \\ \hline 2 & 1773 & 1759 & 1394 \\ \hline 3 & 1773 & 1759 & 1394 \\ \hline \end{array}$$

$$\mathbf{T}^{*\text{T}}_{\text{w}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1878.6 & 1493.4 & 1491.1 \\ \hline 2 & 1888.0 & 1501.0 & 1507.7 \\ \hline 3 & 1897.9 & 1509.2 & 1525.3 \\ \hline \end{array}$$

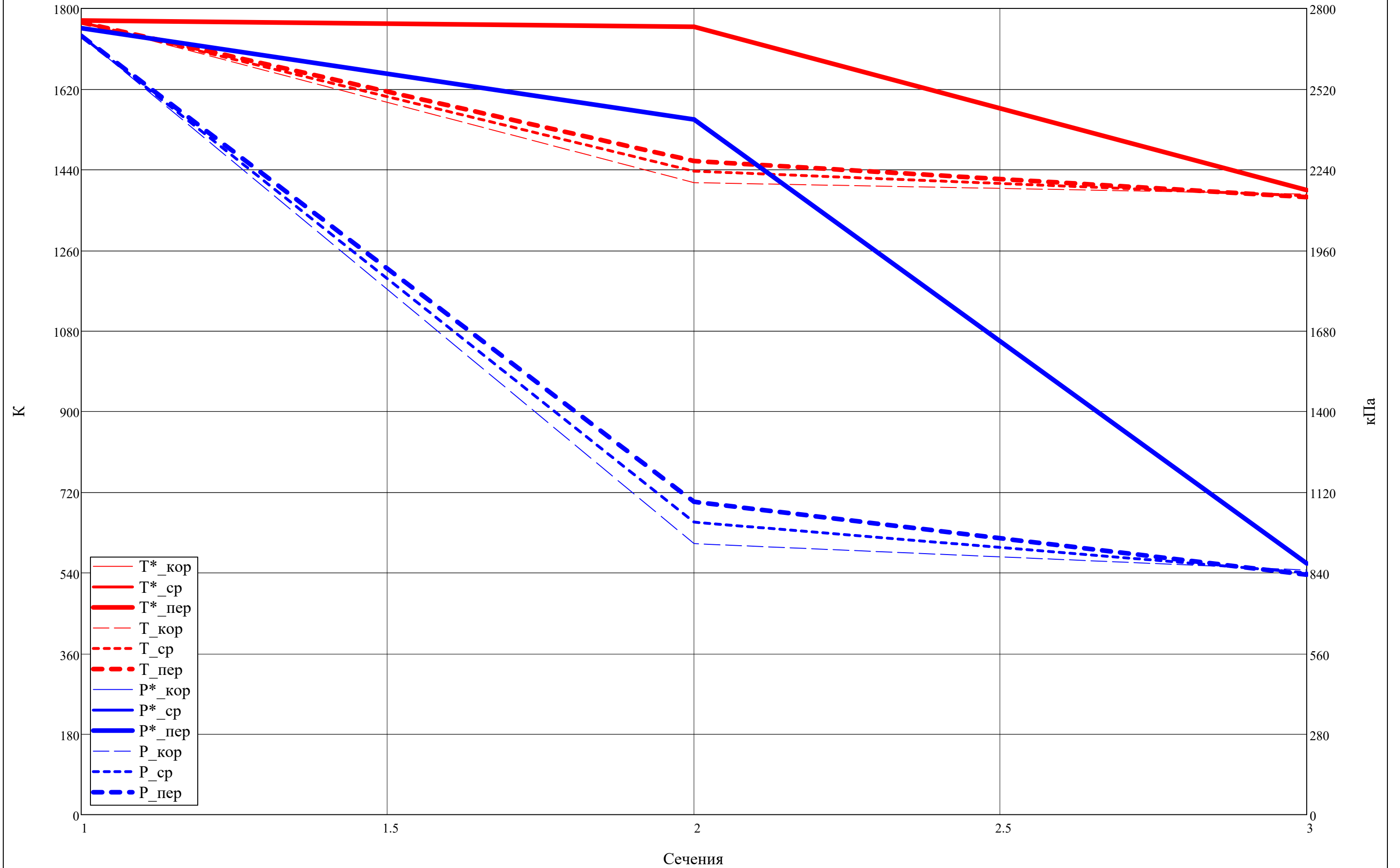
$$\boldsymbol{\rho}^{*\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.341 & 4.758 & 2.169 \\ \hline 2 & 5.341 & 4.758 & 2.169 \\ \hline 3 & 5.341 & 4.758 & 2.169 \\ \hline \end{array}$$

$$\mathbf{p}^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2705.2 & 941.1 & 849.4 \\ \hline 2 & 2705.2 & 1016.0 & 840.1 \\ \hline 3 & 2705.2 & 1086.4 & 833.1 \\ \hline \end{array} \cdot 10^3$$

$$\mathbf{T}^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1769 & 1411 & 1385 \\ \hline 2 & 1769 & 1437 & 1382 \\ \hline 3 & 1769 & 1459 & 1379 \\ \hline \end{array}$$

$$\boldsymbol{\rho}^{\text{T}} = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.301 & 2.312 & 2.125 \\ \hline 2 & 5.301 & 2.451 & 2.108 \\ \hline 3 & 5.301 & 2.580 & 2.094 \\ \hline \end{array}$$

Термодинамические параметры по тракту К



$k^T =$

	1	2	3
1	1.305	1.305	1.316
2	1.305	1.305	1.316
3	1.305	1.305	1.316

$R_L^T =$

	1
1	0.1013
2	0.1780
3	0.2452

$R_L^T \geq 0.05 =$

	1
1	1
2	1
3	1

$$a^*_c{}^T =$$

	1	2	3
1	761.0	758.1	676.1
2	761.0	758.1	676.1
3	761.0	758.1	676.1

$$u^T =$$

	1	2	3
1	510.5	510.5	484.8
2	532.9	532.9	520.0
3	555.2	555.2	555.2

$$c^T =$$

	1	2	3
1	100.0	926.4	146.2
2	100.0	891.8	173.6
3	100.0	859.8	191.9

$$c_u^T =$$

	1	2	3
1	0.0	896.9	2.5
2	0.0	863.5	-1.9
3	0.0	832.5	-5.7

$$c_a^T =$$

	1	2	3
1	100.0	231.6	146.2
2	100.0	222.9	173.6
3	100.0	215.0	191.8

$$\Delta c_a^T =$$

	1	2
1	131.6	-85.4
2	122.9	-49.3
3	115.0	-23.1

$$a^*_w{}^T =$$

	1	2	3
1	783.4	698.5	699.2
2	785.3	700.3	703.1
3	787.4	702.2	707.2

$$a_{3B}^T =$$

	1	2	3
1	816.1	729.0	725.3
2	816.1	735.5	724.4
3	816.1	741.3	723.7

$$w^T =$$

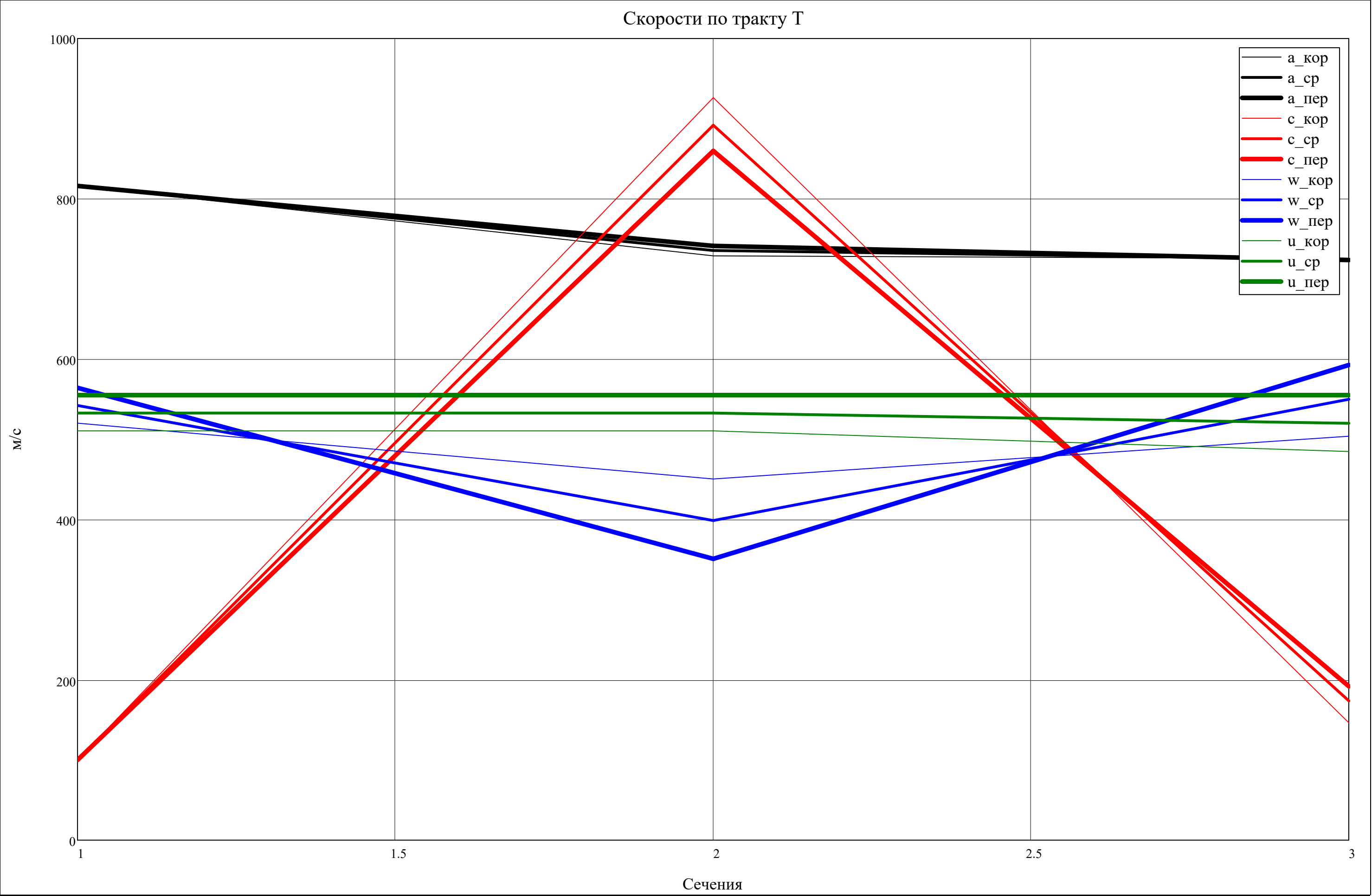
	1	2	3
1	520.2	450.5	503.9
2	542.2	398.7	550.1
3	564.2	350.8	592.8

$$w_u^T =$$

	1	2	3
1	510.5	-386.5	482.2
2	532.9	-330.6	521.9
3	555.2	-277.3	560.9

$$w_a^T =$$

	1	2	3
1	100.0	231.6	146.2
2	100.0	222.9	173.6
3	100.0	215.0	191.8



$\alpha^T =$

	1	2	3
1	90.00	14.48	89.02
2	90.00	14.48	90.64
3	90.00	14.48	91.70

 $^{\circ}$

$80^{\circ} \leq \alpha^T =$

	1	2	3
1	1	0	1
2	1	0	1
3	1	0	1

$\epsilon_{\text{stator}}^T =$

	1
1	75.52
2	75.52
3	75.52

 $^{\circ}$

Угол поворота потока:

[1, с.78]

$\beta^T =$

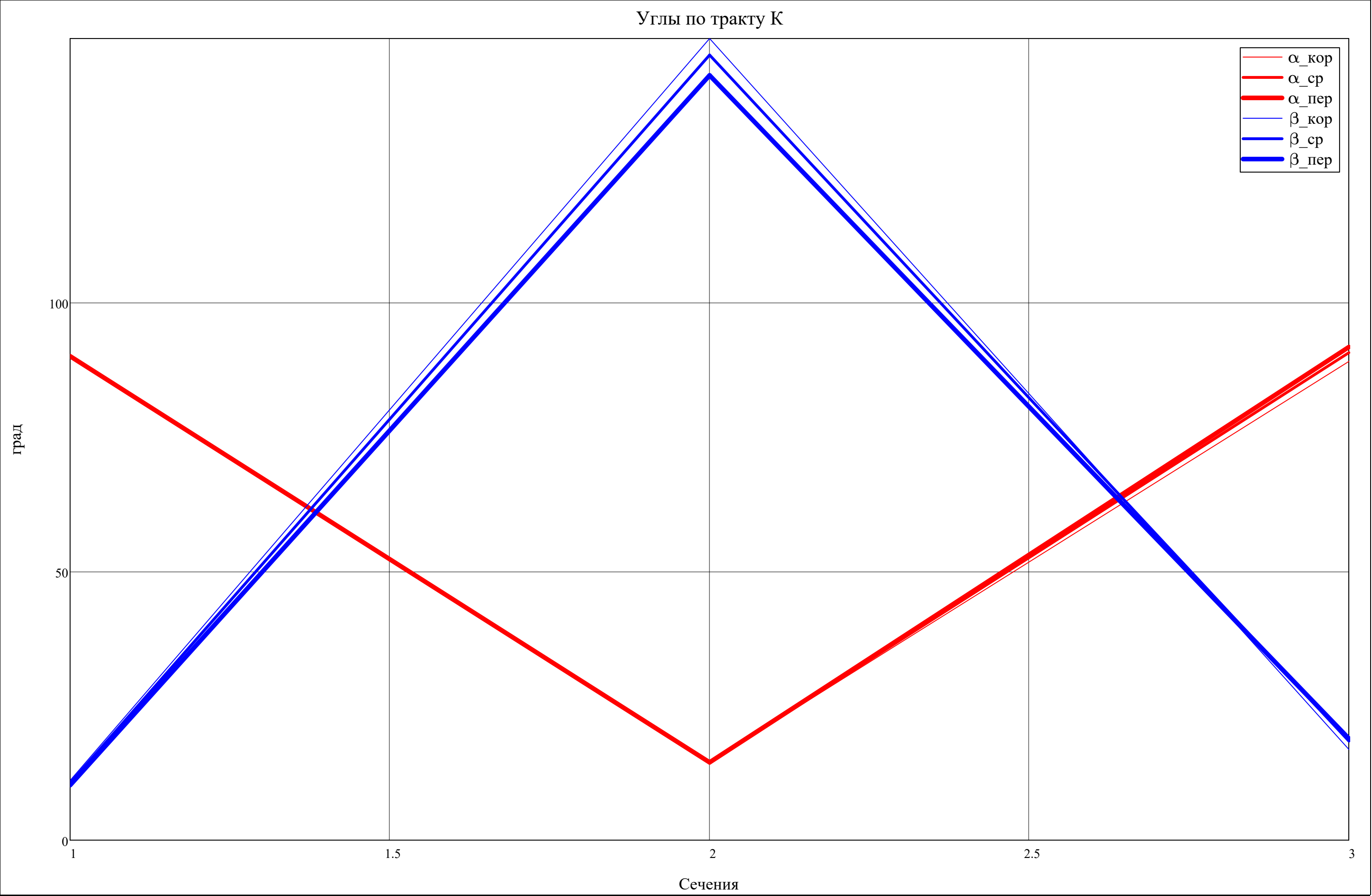
	1	2	3
1	11.08	149.07	16.87
2	10.63	146.01	18.40
3	10.21	142.22	18.88

 $^{\circ}$

$\epsilon_{\text{rotor}}^T =$

	1
1	132.20
2	127.61
3	123.34

 $^{\circ}$



$\lambda_c^T =$

	1	2	3
1	0.131	1.222	0.216
2	0.131	1.176	0.257
3	0.131	1.134	0.284

 $M_c^T =$

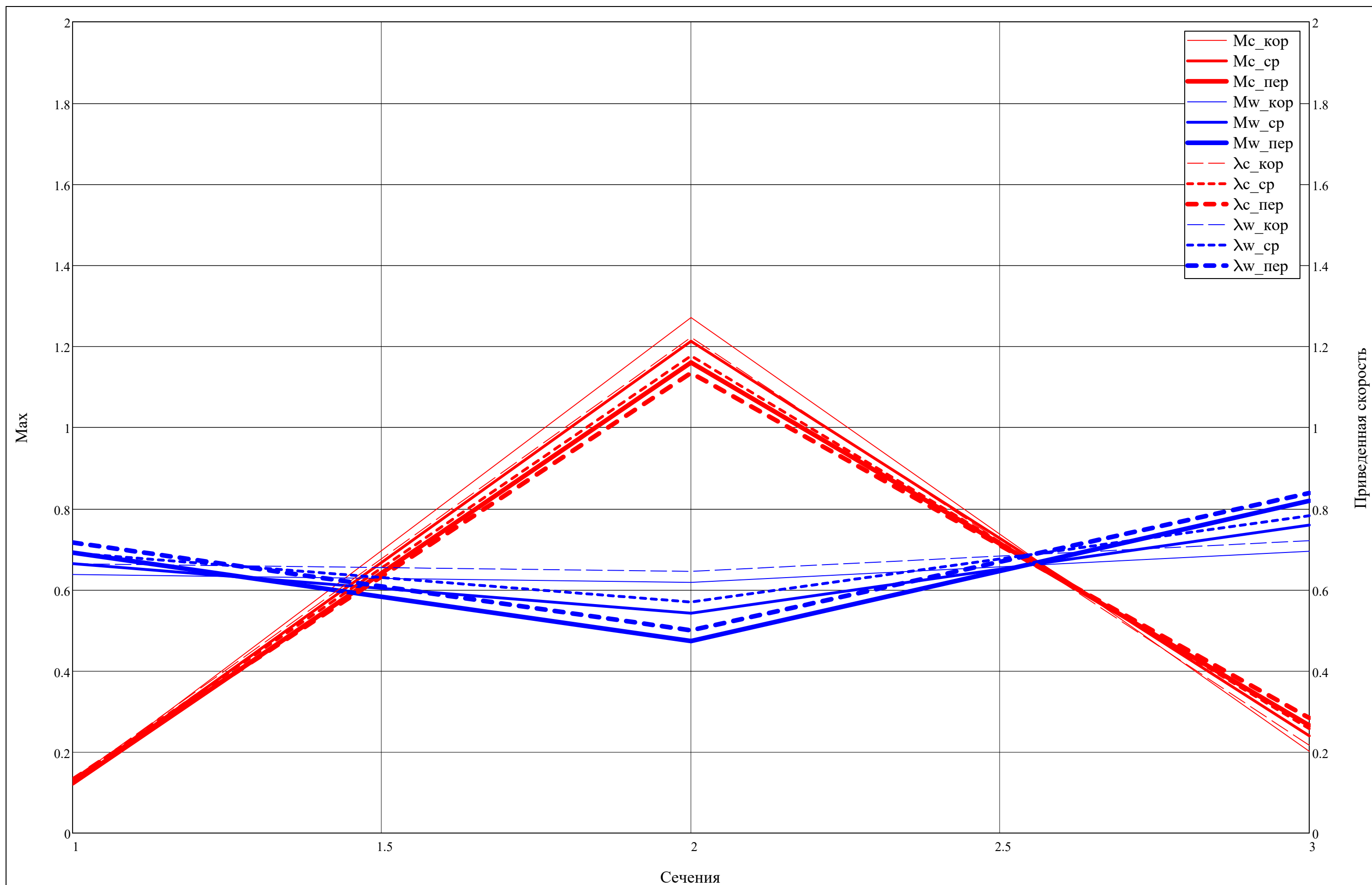
	1	2	3
1	0.123	1.271	0.202
2	0.123	1.212	0.240
3	0.123	1.160	0.265

 $\lambda_w^T =$

	1	2	3
1	0.664	0.645	0.721
2	0.690	0.569	0.782
3	0.717	0.500	0.838

 $M_w^T =$

	1	2	3
1	0.6	0.6	0.7
2	0.7	0.5	0.8
3	0.7	0.5	0.8



Рассматриваемая ступень:

j =

j = Z

j =

"Такой ступени не существует!" if (j < 1) ∨ (j > Z)

j otherwise

= 1

▼

Построение треугольников скоростей в 3х сечениях

Δ_c(v,i,j,r) =

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) ≥ 0) ∧ (−|c_{st(i,j),r}·cos(α_{st(i,j),r})| ≤ v ≤ 0)

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |c_{st(i,j),r}·cos(α_{st(i,j),r})|)

Δ_w(v,i,j,r) =

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) ≥ 0) ∧ (−|w_{st(i,j),r}·cos(β_{st(i,j),r})| ≤ v ≤ 0) ∧ (j ≠ 1)

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |w_{st(i,j),r}·cos(β_{st(i,j),r})|) ∧ (j ≠ 1)

Δ_u(v,i,j,r) =

−c_{a_{st(i,j),r}} if (−c_{st(i,j),r}·cos(α_{st(i,j),r}) ≤ v ≤ w_{st(i,j),r}·cos(β_{st(i,j),r})) ∧ (j ≠ 1)

NaN otherwise

v_{lim} =

ceil

max(c,w,u)

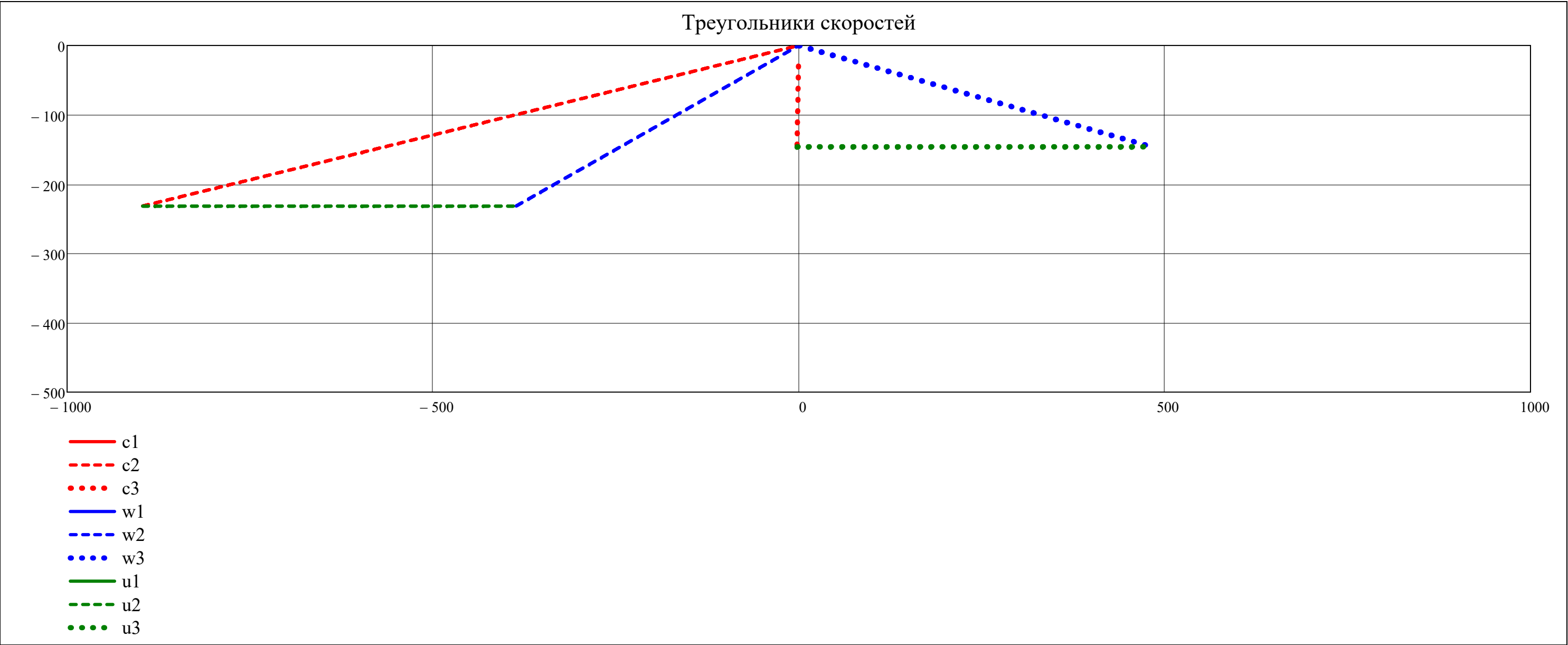
10²

·10² = 1000.0

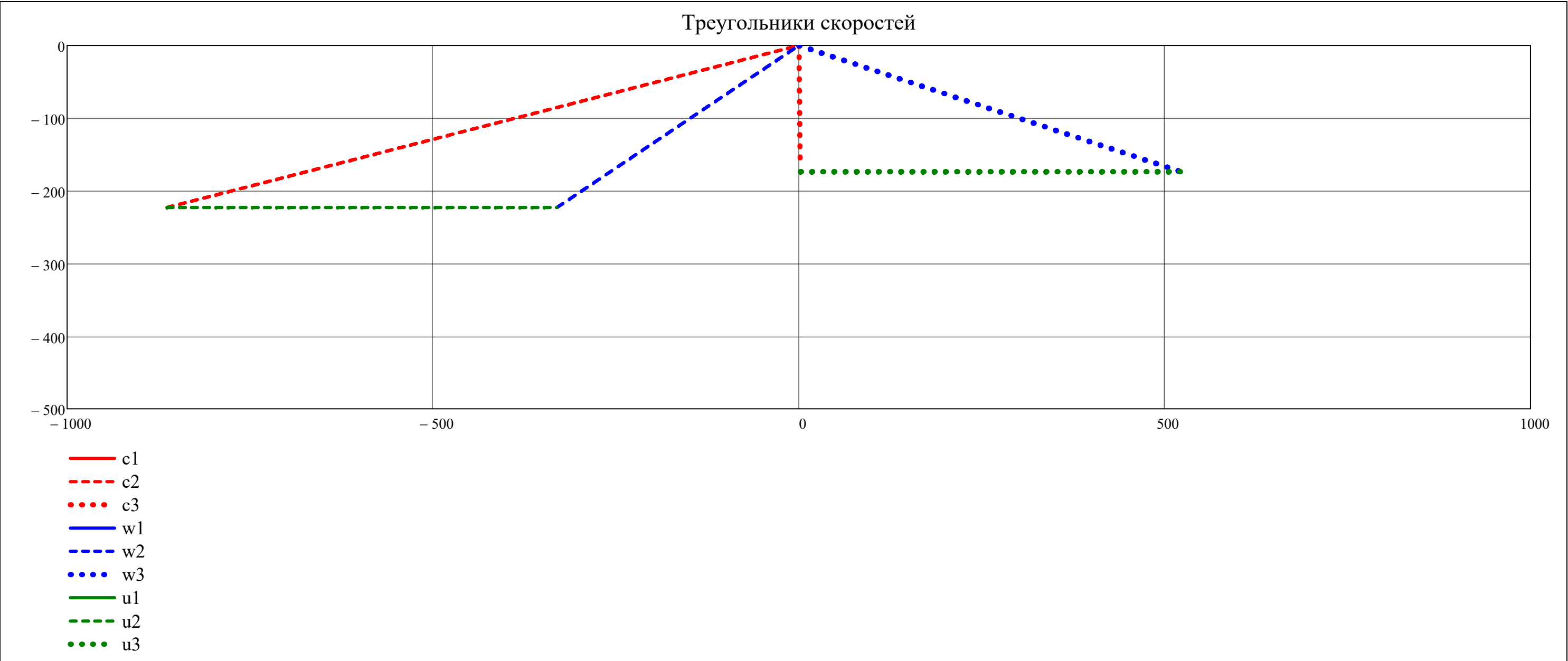
v = −max(c,w,u), −max(c,w,u) + $\frac{\max(c,w,u)}{3000}$.. max(c,w,u)

56

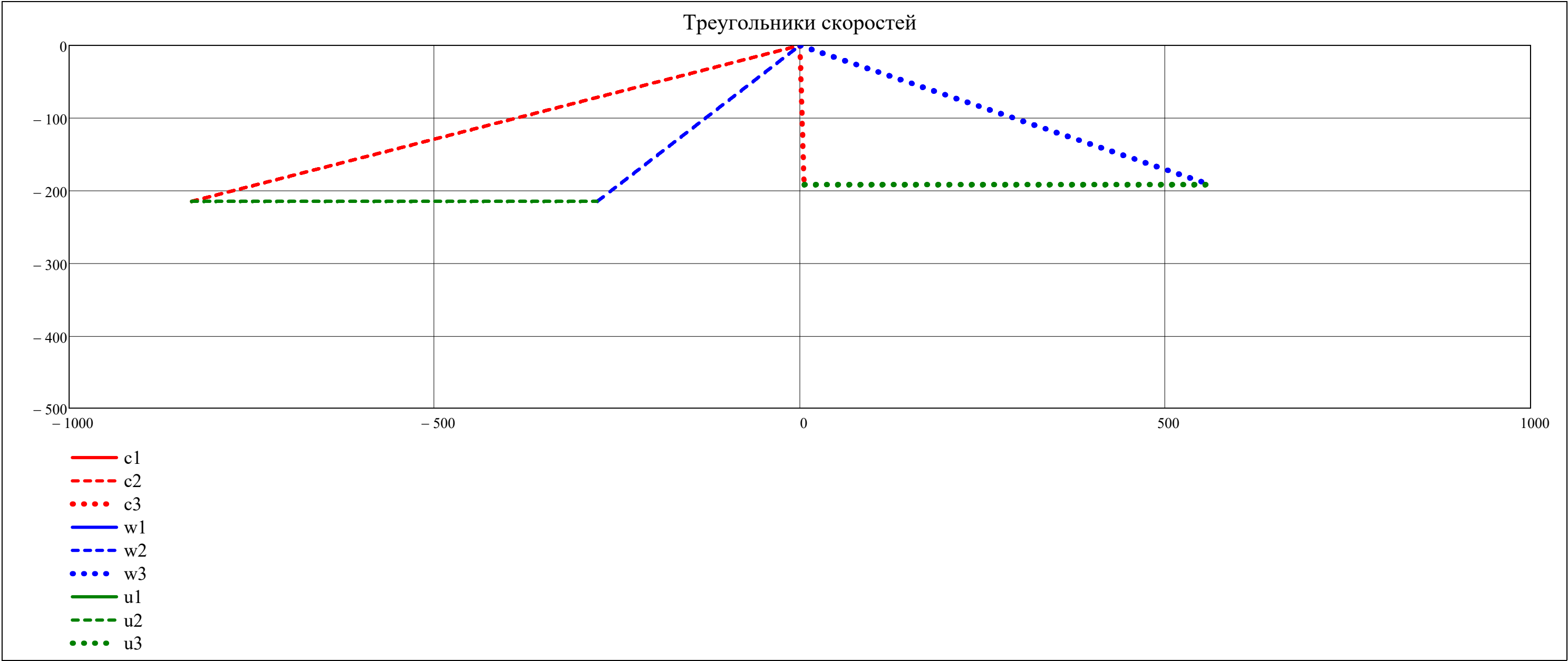
r = 1



$\bar{r}_w = \text{av}(N_r)$



$r_w = N_r$



Построение треугольников скоростей в 3х сечениях

Парусность:

sail_{stator}

sail_{rotor}

=

1

0.85

Расчет хорд Л по парусности

chord_{stator}

chord_{rotor}

=

for i ∈ 1..Z

sail = $\frac{R_{st(i,2),N_r} - R_{st(i,2),1}}{R_{st(i,2),av(N_r)} - R_{st(i,2),1}}$

for r ∈ 1..N_r

chord_{stator}_{i,av(N_r)} · sail

b_{CAkop} = $\frac{\hspace{1.5cm}}{sail_{stator} - 1 + sail}$

chord_{rotor}_{i,av(N_r)} · sail

b_{PKkop} = $\frac{\hspace{1.5cm}}{sail_{rotor} - 1 + sail}$

(b_{CAпер})

(b_{PKпер})

=

b_{CAkop} · sail_{stator}

b_{PKkop} · sail_{rotor}

chord_{stator}.(z) = interp

cspline

R_{st(i,2),1}

R_{st(i,2),av(N_r)}

R_{st(i,2),N_r}

b_{CAkop}

chord_{stator}_{i,av(N_r)}

b_{CAпер}

R_{st(i,2),1}

R_{st(i,2),av(N_r)}

R_{st(i,2),N_r}

b_{CAkop}

chord_{stator}_{i,av(N_r)}

b_{CAпер}

,z

chord_{rotor}.(z) = interp

cspline

R_{st(i,2),1}

R_{st(i,2),av(N_r)}

R_{st(i,2),N_r}

b_{PKkop}

chord_{rotor}_{i,av(N_r)}

b_{PKпер}

R_{st(i,2),1}

R_{st(i,2),av(N_r)}

R_{st(i,2),N_r}

b_{PKkop}

chord_{rotor}_{i,av(N_r)}

b_{PKпер}

,z

chord_{stator}_{i,r}

chord_{rotor}_{i,r}

=

chord_{stator}.(R_{st(i,2),r})

chord_{rotor}.(R_{st(i,3),r})

chord_{stator}

chord_{rotor}

Длины хорд РК и СА (м):

chord_{stator}^T

=

	1
1	68.0
2	68.0
3	68.0

· 10^{−3}

chord_{rotor}^T

=

	1
1	35.2
2	31.4
3	28.8

· 10^{−3}

Расчет хорд Л по парусности

60

Ср. линия профиля:
0.5 - дуга окружности
0.45 - парабола

$$\bar{x}_f = 0.45$$

▼ Расчет параметров решетки

$$\begin{pmatrix} t_{\text{stator}} & t_{\text{rotor}} \\ r_{\text{inlet}_{\text{stator}}} & r_{\text{inlet}_{\text{rotor}}} \\ r_{\text{outlet}_{\text{stator}}} & r_{\text{outlet}_{\text{rotor}}} \\ c_{\text{stator}} & c_{\text{rotor}} \\ v_{\text{stator}} & v_{\text{rotor}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{array}{l} \begin{pmatrix} t_{\text{stator}_{i,r}} \\ t_{\text{rotor}_{i,r}} \end{pmatrix} = \pi \cdot \begin{pmatrix} \frac{\text{mean}(D_{\text{st}}(i,1),r,D_{\text{st}}(i,2),r)}{Z_{\text{stator}_i}} \\ \frac{\text{mean}(D_{\text{st}}(i,2),r,D_{\text{st}}(i,3),r)}{Z_{\text{rotor}_i}} \end{pmatrix} \\ \begin{pmatrix} r_{\text{inlet}_{\text{stator}_{i,r}}} & r_{\text{outlet}_{\text{stator}_{i,r}}} \\ r_{\text{inlet}_{\text{rotor}_{i,r}}} & r_{\text{outlet}_{\text{rotor}_{i,r}}} \end{pmatrix} = \begin{pmatrix} \overline{r_{\text{inlet}_{\text{stator}_{i,r}}}} \cdot \text{chord}_{\text{stator}_{i,r}} & \overline{r_{\text{outlet}_{\text{stator}_{i,r}}}} \cdot \text{chord}_{\text{stator}_{i,r}} \\ \overline{r_{\text{inlet}_{\text{rotor}_{i,r}}}} \cdot \text{chord}_{\text{rotor}_{i,r}} & \overline{r_{\text{outlet}_{\text{rotor}_{i,r}}}} \cdot \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix} \\ \begin{pmatrix} c_{\text{stator}_{i,r}} \\ c_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{c_{\text{stator}_{i,r}}} \cdot \text{chord}_{\text{stator}_{i,r}} \\ \overline{c_{\text{rotor}_{i,r}}} \cdot \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix} \\ \begin{pmatrix} v_{\text{stator}_{i,r}} \\ v_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} v_{\text{installation}}(0.5, \alpha_{\text{st}}(i,1),r, \alpha_{\text{st}}(i,2),r) \\ v_{\text{installation}}(0.5, \beta_{\text{st}}(i,2),r, \beta_{\text{st}}(i,3),r) \end{pmatrix} + \frac{\pi}{2} \end{array} \right| \\ \begin{pmatrix} t_{\text{stator}} & t_{\text{rotor}} \\ r_{\text{inlet}_{\text{stator}}} & r_{\text{inlet}_{\text{rotor}}} \\ r_{\text{outlet}_{\text{stator}}} & r_{\text{outlet}_{\text{rotor}}} \\ c_{\text{stator}} & c_{\text{rotor}} \\ v_{\text{stator}} & v_{\text{rotor}} \end{pmatrix} \end{array}$$

$$\begin{pmatrix} v_{\text{установки}}(\alpha_{\text{st}(i,1),r}, \alpha_{\text{st}(i,2),r}, r) \\ v_{\text{установки}}(\beta_{\text{st}(i,2),r}, \beta_{\text{st}(i,3),r}, r) \end{pmatrix}$$

$\frac{\pi}{2}$ добавляется в виду поворота рисунка на 90 град

▲ Расчет параметров решетки

Относительные радиусы профилей ():

$\overline{r}_{inlet_{stator}}^T =$

	1
1	6.000
2	6.000
3	6.000

 $\cdot\%$

$\overline{r}_{outlet_{stator}}^T =$

	1
1	3.000
2	3.000
3	3.000

 $\cdot\%$

$\overline{r}_{inlet_{rotor}}^T =$

	1
1	5.100
2	4.500
3	3.300

 $\cdot\%$

$\overline{r}_{outlet_{rotor}}^T =$

	1
1	1.700
2	1.500
3	1.100

 $\cdot\%$

Относительная толщина профиля ():

$\overline{c}_{stator}^T =$

	1
1	15.00
2	15.00
3	15.00

 $\cdot\%$

$\overline{c}_{rotor}^T =$

	1
1	17.00
2	15.00
3	11.00

 $\cdot\%$

Относительный шаг решетки ():

$\left(\frac{t_{stator}}{chord_{stator}}\right)^T =$

	1
1	0.8343
2	0.8709
3	0.9075

$\left(\frac{t_{rotor}}{chord_{rotor}}\right)^T =$

	1
1	0.5833
2	0.6924
3	0.7947

Относительная густота решетки ():

$\left(\frac{chord_{stator}}{t_{stator}}\right)^T =$

	1
1	1.199
2	1.148
3	1.102

$\left(\frac{chord_{rotor}}{t_{rotor}}\right)^T =$

	1
1	1.714
2	1.444
3	1.258

Длина хорды профиля [м]:

$$\text{chord}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 68.0 \\ \hline 2 & 68.0 \\ \hline 3 & 68.0 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{chord}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 35.2 \\ \hline 2 & 31.4 \\ \hline 3 & 28.8 \\ \hline \end{array} \cdot 10^{-3}$$

Радиусы профилей:

$$\text{r_inlet}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 4.08 \\ \hline 2 & 4.08 \\ \hline 3 & 4.08 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_inlet}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.79 \\ \hline 2 & 1.41 \\ \hline 3 & 0.95 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.04 \\ \hline 2 & 2.04 \\ \hline 3 & 2.04 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.60 \\ \hline 2 & 0.47 \\ \hline 3 & 0.32 \\ \hline \end{array} \cdot 10^{-3}$$

Толщина профиля [м]:

$$\text{c}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 10.20 \\ \hline 2 & 10.20 \\ \hline 3 & 10.20 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{c}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 5.98 \\ \hline 2 & 4.70 \\ \hline 3 & 3.17 \\ \hline \end{array} \cdot 10^{-3}$$

Шаг решетки [м]:

$$\text{t}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 56.7 \\ \hline 2 & 59.2 \\ \hline 3 & 61.7 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{t}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 20.5 \\ \hline 2 & 21.7 \\ \hline 3 & 22.9 \\ \hline \end{array} \cdot 10^{-3}$$

Угол поворота потока:

$\epsilon_{\text{stator}}^T =$

	1
1	75.52
2	75.52
3	75.52

.°

$\epsilon_{\text{rotor}}^T =$

	1
1	132.20
2	127.61
3	123.34

.°

Угол установки профиля:

$v_{\text{stator}}^T =$

	1
1	117.3
2	117.3
3	117.3

.°

$v_{\text{rotor}}^T =$

	1
1	111.9
2	114.0
3	115.4

.°

Угол изгиба профиля:

$\pi - \epsilon_{\text{stator}}^T =$

	1
1	104.5
2	104.5
3	104.5

.°

$\pi - \epsilon_{\text{rotor}}^T =$

	1
1	47.8
2	52.4
3	56.7

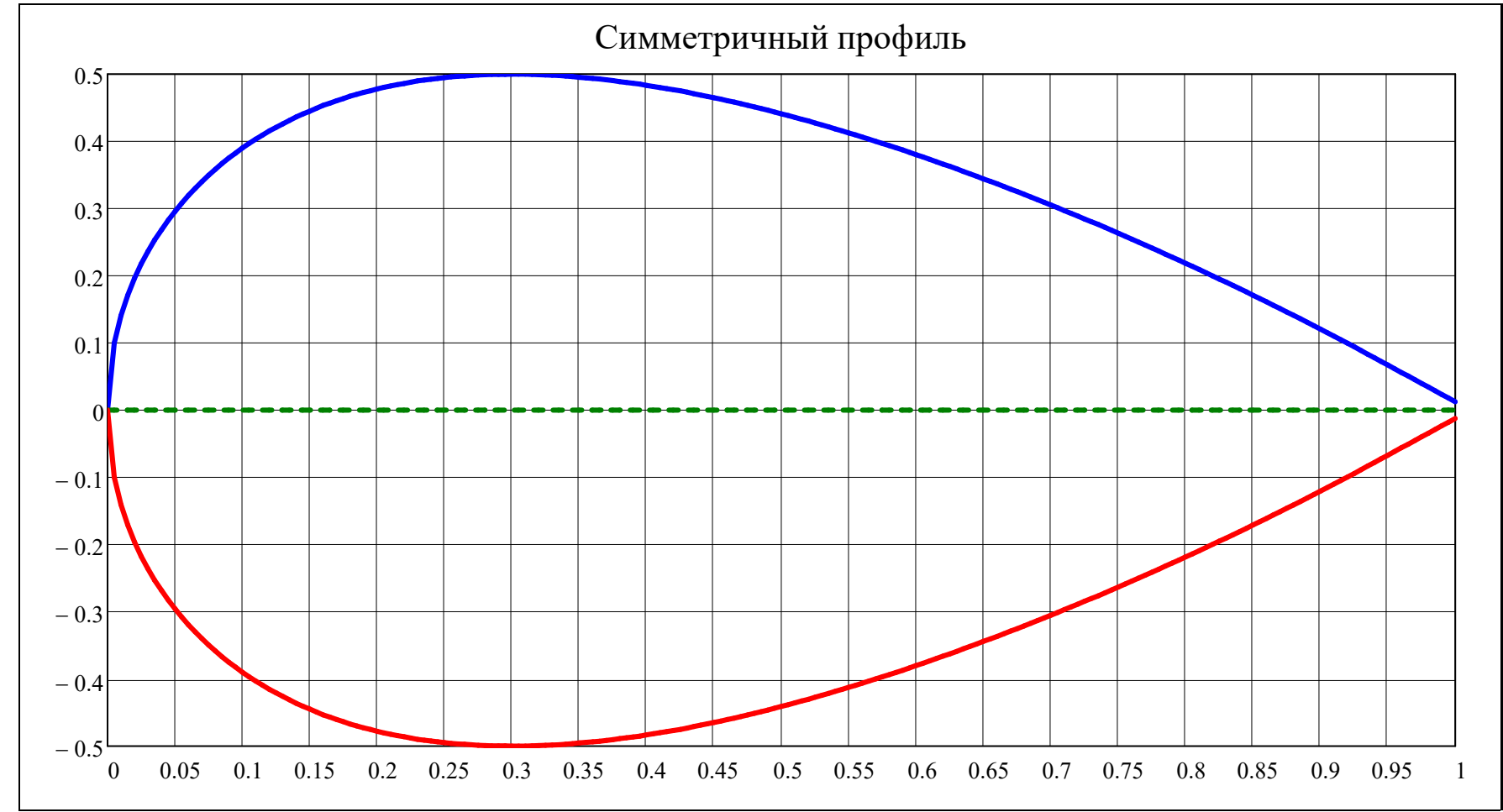
.°

$$\begin{pmatrix} X_U & Y_U \\ X_L & Y_L \end{pmatrix} = \text{NACA}(0,0,100\%,1)$$

Относ. координаты профиля РК и СА:

$$\text{AIRFOIL}_0(x, \text{line}, \overline{f}, \overline{x_f}, \overline{c}) = \begin{cases} \text{if } 0 \leq x \leq 1 \\ \begin{cases} \text{linterp}(X_U, Y_U, x) & \text{if line = "+"} \\ \frac{\text{linterp}(X_U, Y_U, x) + \text{linterp}(X_L, Y_L, x)}{2} & \text{if line = "0"} \\ \text{linterp}(X_L, Y_L, x) & \text{if line = "-"} \end{cases} \\ \text{NaN otherwise} \end{cases}$$

$x = 0, 0.005 \dots 1$



AIRFOIL(x,line, c̄, θ) =

linterp(X_U, y/b_{ср.л}(X_U, θ) + Y_U· c̄, x)

if line = "+"

linterp(X_U, y/b_{ср.л}(X_U, θ) + Y_U· c̄, x)

+ linterp(X_L, y/b_{ср.л}(X_L, θ) + Y_L· c̄, x)

2

if line = "0"

linterp(X_L, y/b_{ср.л}(X_L, θ) + Y_L· c̄, x)

if line = "-"

NaN otherwise

Профиль СА на ср. сечении

Профиль РК на ср. сечении

Подключение симметричного профиля

66

$$l_{upper_stator}^T =$$

	1
1	78.09
2	78.09
3	78.09

$$\cdot 10^{-3}$$

$$l_{lower_stator}^T =$$

	1
1	70.65
2	70.65
3	70.65

$$\cdot 10^{-3}$$

$$area_{stator}^T =$$

	1
1	474.02
2	474.02
3	474.02

$$\cdot 10^{-6}$$

$$Sx_{stator}^T =$$

	1
1	4234.9
2	4234.9
3	4234.9

$$\cdot 10^{-9}$$

$$Sy_{stator}^T =$$

	1
1	13570.3
2	13570.3
3	13570.3

$$\cdot 10^{-9}$$

$$x0_{stator}^T =$$

	1
1	28.6
2	28.6
3	28.6

$$\cdot 10^{-3}$$

$$y0_{stator}^T =$$

	1
1	8.9
2	8.9
3	8.9

$$\cdot 10^{-3}$$

$$l_{upper_rotor}^T =$$

	1
1	47.69
2	41.47
3	36.86

$$\cdot 10^{-3}$$

$$l_{lower_rotor}^T =$$

	1
1	40.59
2	35.98
3	33.19

$$\cdot 10^{-3}$$

$$area_{rotor}^T =$$

	1
1	143.85
2	100.82
3	62.43

$$\cdot 10^{-6}$$

$$Sx_{rotor}^T =$$

	1
1	1320.1
2	785.3
3	426.8

$$\cdot 10^{-9}$$

$$Sy_{rotor}^T =$$

	1
1	2130.9
2	1331.2
3	757.5

$$\cdot 10^{-9}$$

$$x0_{rotor}^T =$$

	1
1	14.8
2	13.2
3	12.1

$$\cdot 10^{-3}$$

$$y0_{rotor}^T =$$

	1
1	9.2
2	7.8
3	6.8

$$\cdot 10^{-3}$$

$$J_{x_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 44306 \\ \hline 2 & 44306 \\ \hline 3 & 44306 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 509058 \\ \hline 2 & 509058 \\ \hline 3 & 509058 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 128653 \\ \hline 2 & 128653 \\ \hline 3 & 128653 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6470 \\ \hline 2 & 6470 \\ \hline 3 & 6470 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 120570 \\ \hline 2 & 120570 \\ \hline 3 & 120570 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 7415 \\ \hline 2 & 7415 \\ \hline 3 & 7415 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.7 \\ \hline 2 & 3.7 \\ \hline 3 & 3.7 \\ \hline \end{array} \cdot ^\circ$$

$$J_{x_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 13285 \\ \hline 2 & 6703 \\ \hline 3 & 3179 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 41363 \\ \hline 2 & 23030 \\ \hline 3 & 12042 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 20592 \\ \hline 2 & 10928 \\ \hline 3 & 5462 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1171 \\ \hline 2 & 586 \\ \hline 3 & 261 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 9797 \\ \hline 2 & 5455 \\ \hline 3 & 2852 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1036 \\ \hline 2 & 559 \\ \hline 3 & 284 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6.8 \\ \hline 2 & 6.5 \\ \hline 3 & 6.2 \\ \hline \end{array} \cdot ^\circ$$

$$J_{u_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 5991 \\ \hline 2 & 5991 \\ \hline 3 & 5991 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 121049.8 \\ \hline 2 & 121049.8 \\ \hline 3 & 121049.8 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0 \\ \hline 2 & 0 \\ \hline 3 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 127040 \\ \hline 2 & 127040 \\ \hline 3 & 127040 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3148.0 \\ \hline 2 & 3148.0 \\ \hline 3 & 3148.0 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{stator}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 11348.5 \\ \hline 2 & 11348.5 \\ \hline 3 & 11348.5 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{u_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1048 \\ \hline 2 & 522 \\ \hline 3 & 230 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 9920 \\ \hline 2 & 5518 \\ \hline 3 & 2883 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0 \\ \hline 2 & 0 \\ \hline 3 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 10967 \\ \hline 2 & 6040 \\ \hline 3 & 3113 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 491.0 \\ \hline 2 & 305.8 \\ \hline 3 & 172.7 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{rotor}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1184.4 \\ \hline 2 & 513.4 \\ \hline 3 & 144.4 \\ \hline \end{array} \cdot 10^{-12}$$

Абс. координаты профиля:

$\text{Airfoil}(\text{type}, x, \text{line}, i, r) =$	$\text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{stator}_{i,r}}, \varepsilon_{\text{stator}_{i,r}}\right) \text{ if type = "stator"}$
	$\text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{rotor}_{i,r}}, \varepsilon_{\text{rotor}_{i,r}}\right) \text{ if type = "rotor"}$

Рассматриваемая ступень:

$$j_v = \begin{cases} j = 1 & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

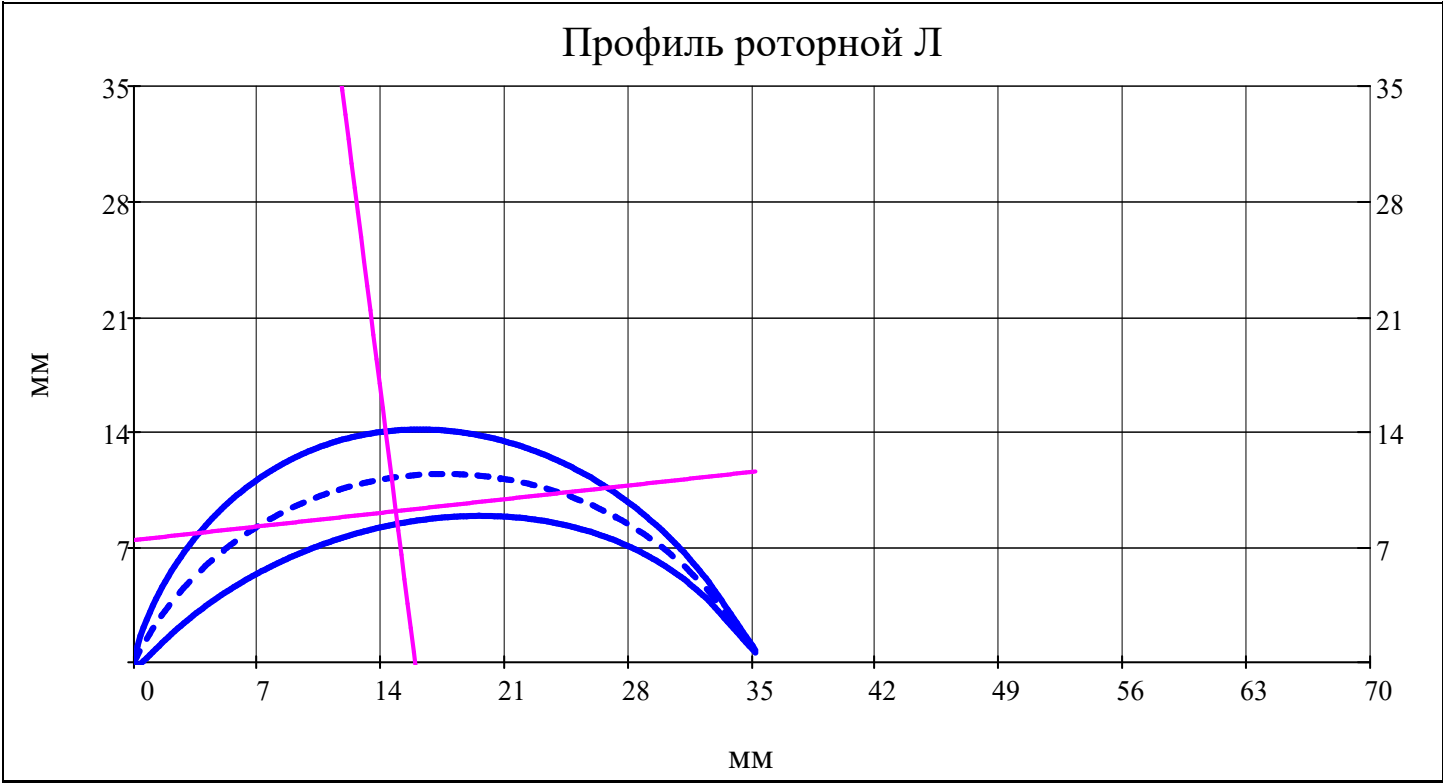
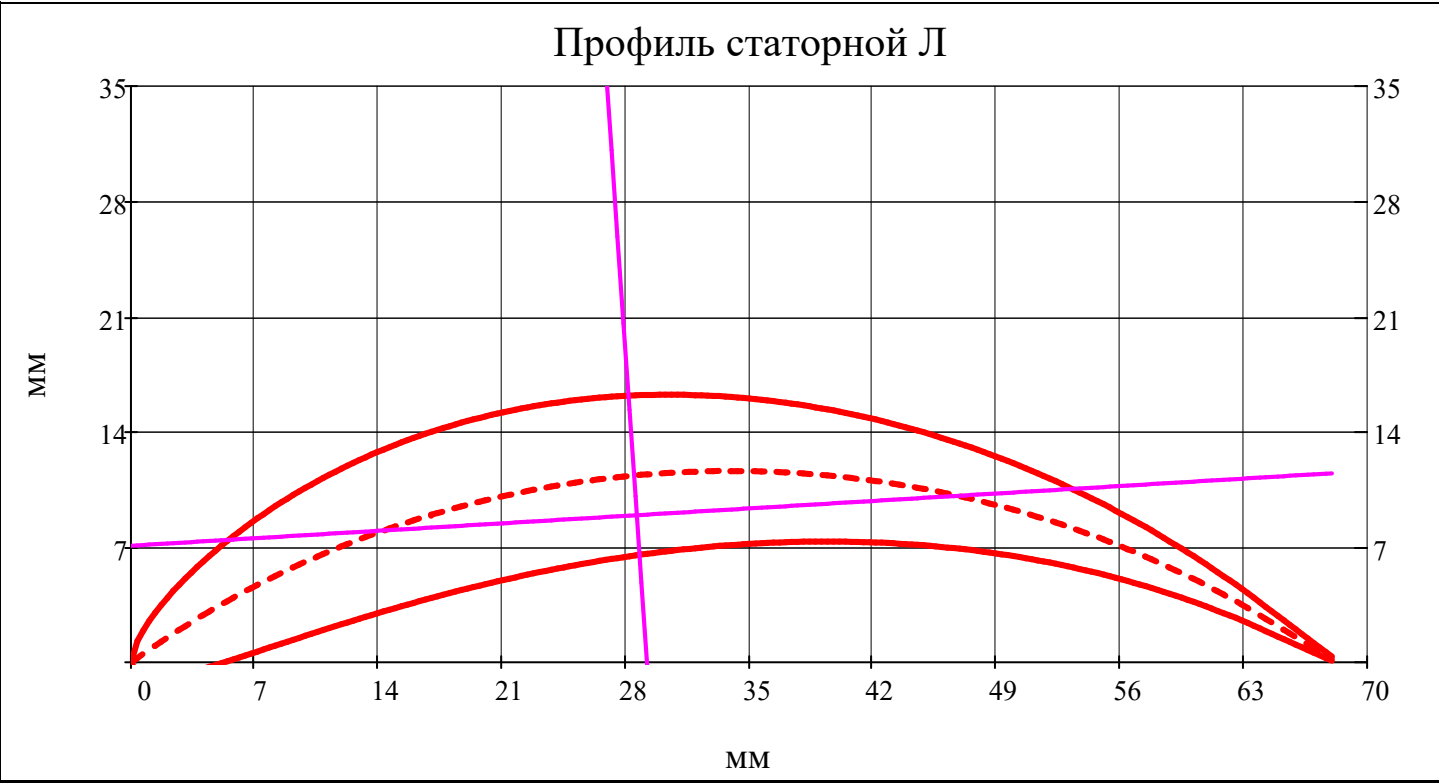
Построение профилей Л РК и НА

$$\text{AXLE0}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if type = "stator"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

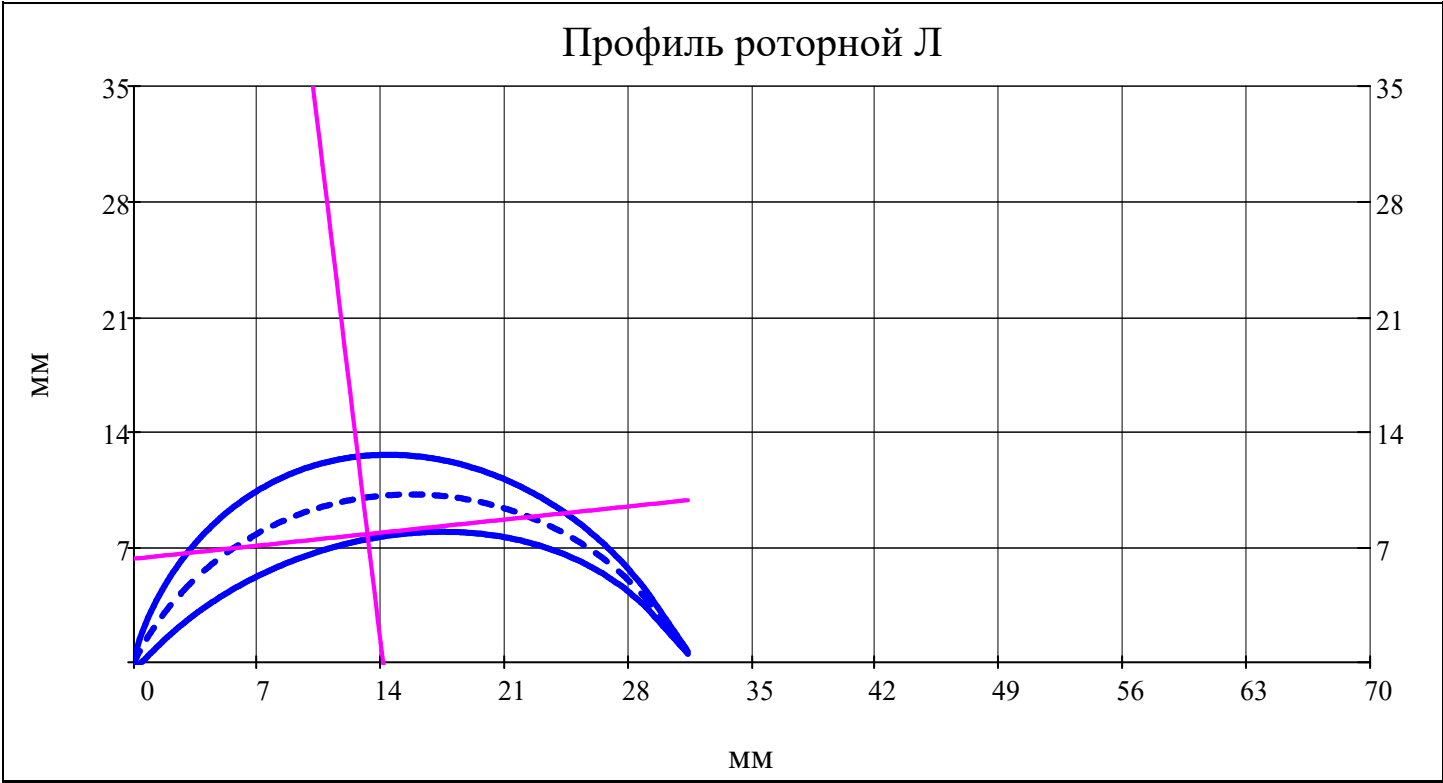
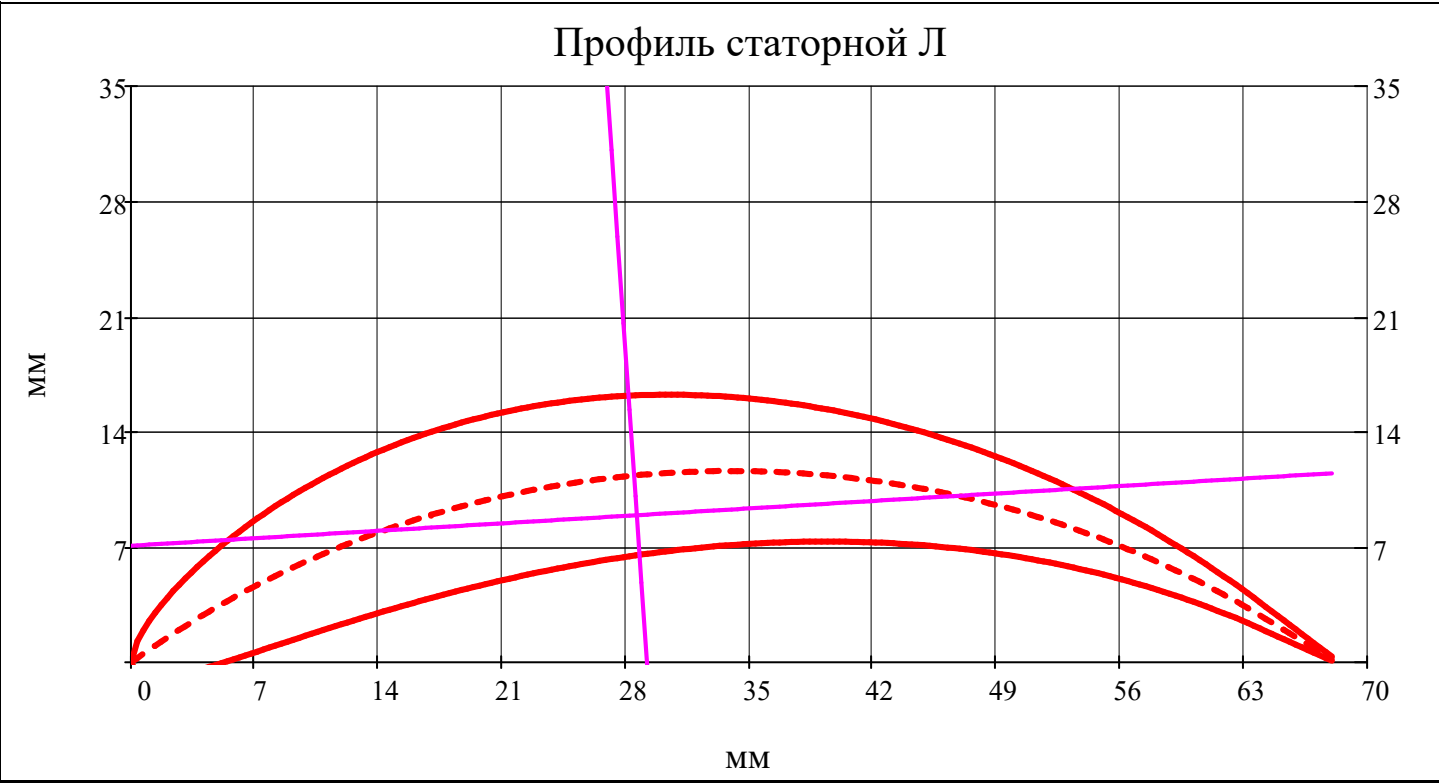
$$\text{AXLE90}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if (type = "rotor") } \wedge \left|\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right| \geq 1^\circ \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if (type = "stator") } \wedge \left|\alpha_{\text{major}_{\text{stator}_{i,r}}}\right| \geq 1^\circ \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$b_{\text{lim}} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

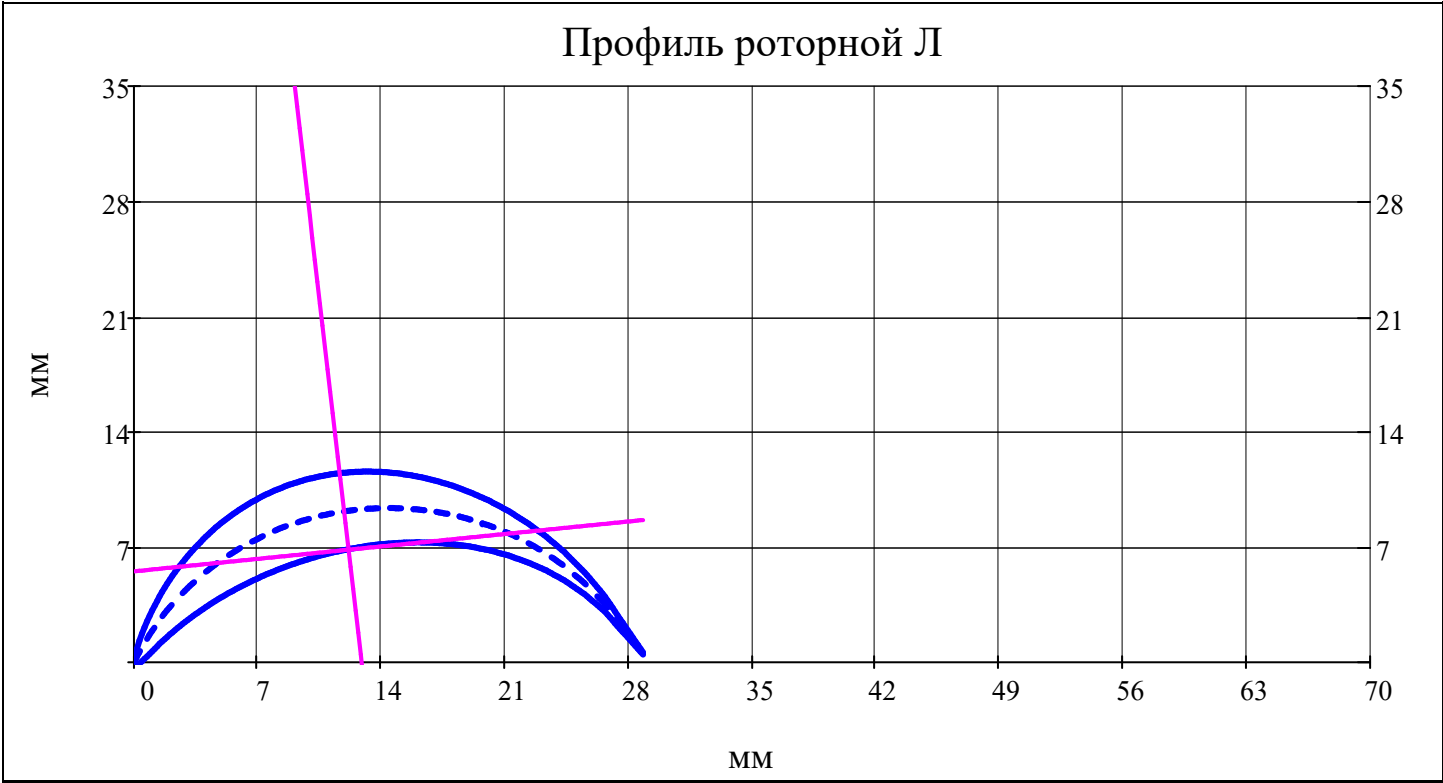
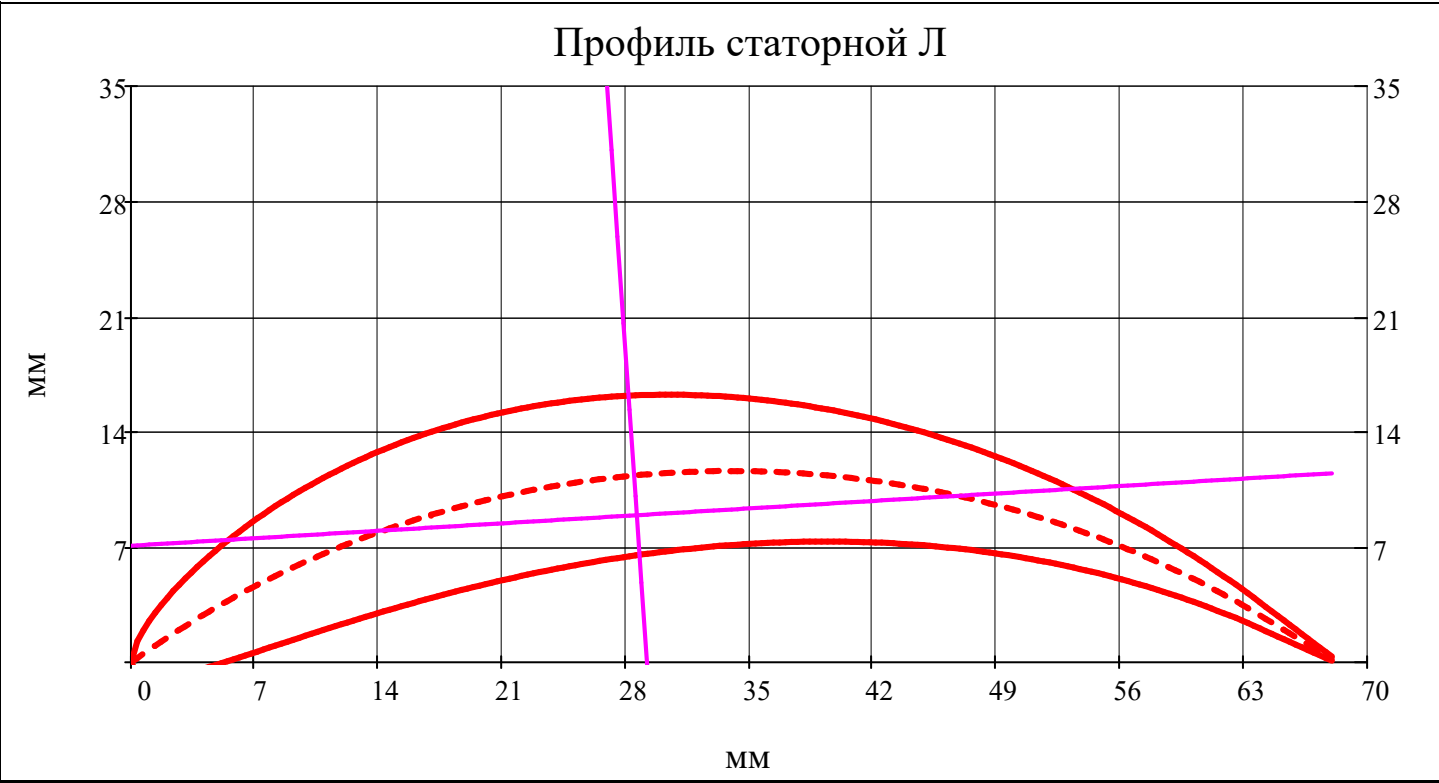
$r_w = 1$



$r_w = av(N_r)$



$r_w = N_r$





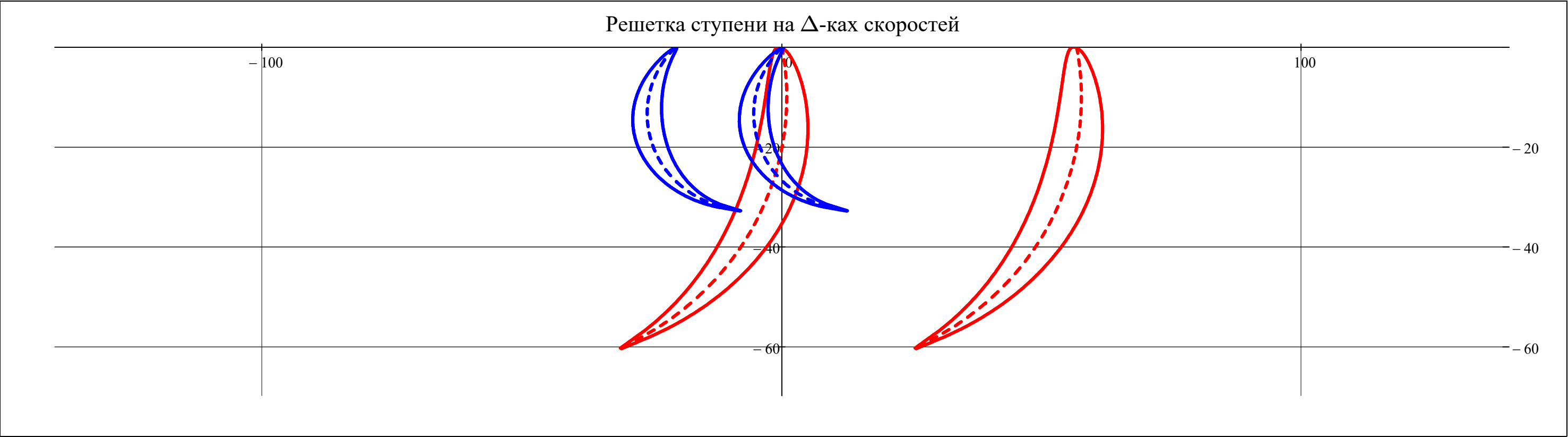
Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

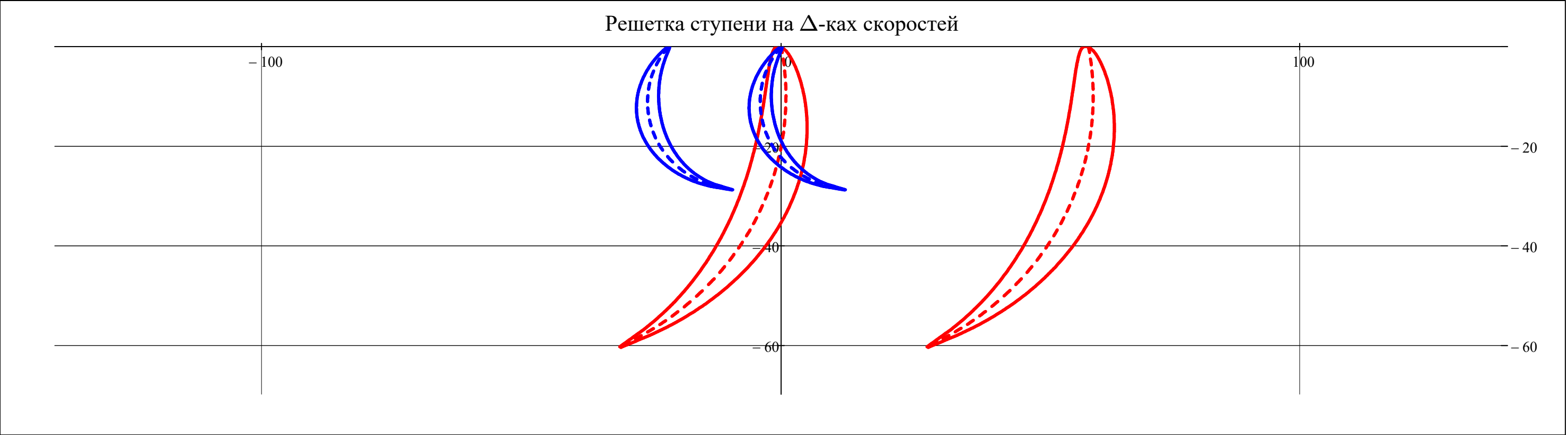
$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Построение плоских решеток профилей Л на треугольниках скоростей

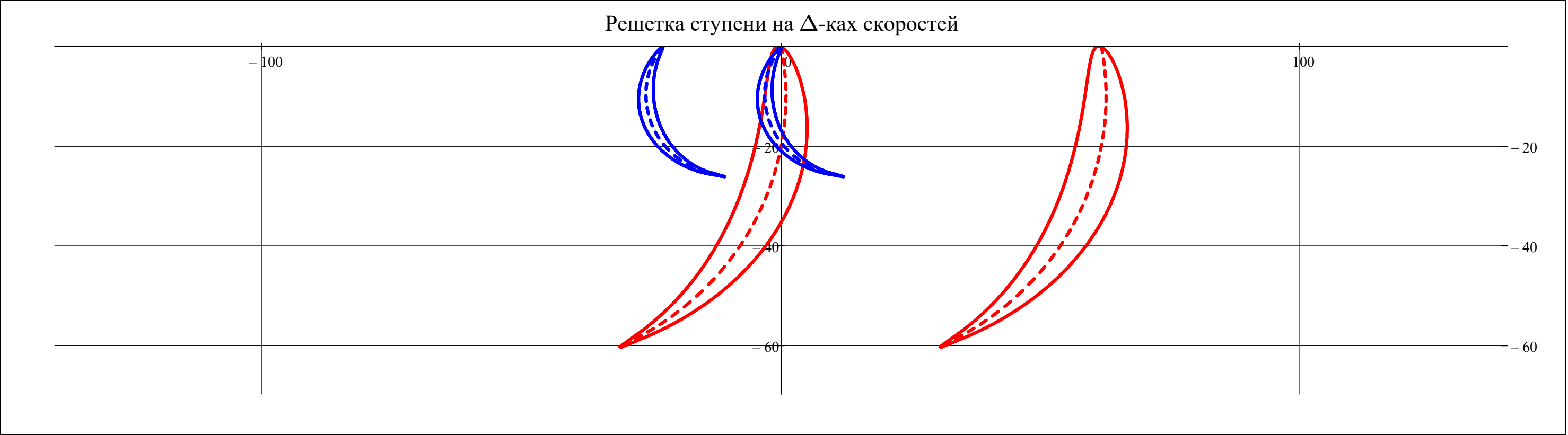
$$r_w = 1$$



$r_w = \text{av}(N_r)$



$r_w = N_r$



Построение плоских решеток профилей Л на треугольниках скоростей

Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

▼ Поперечная часть ступени

$$r_w = \min(D), \min(D) + \frac{\max(D) - \min(D)}{N_{\text{dis}}} \dots \max(D)$$

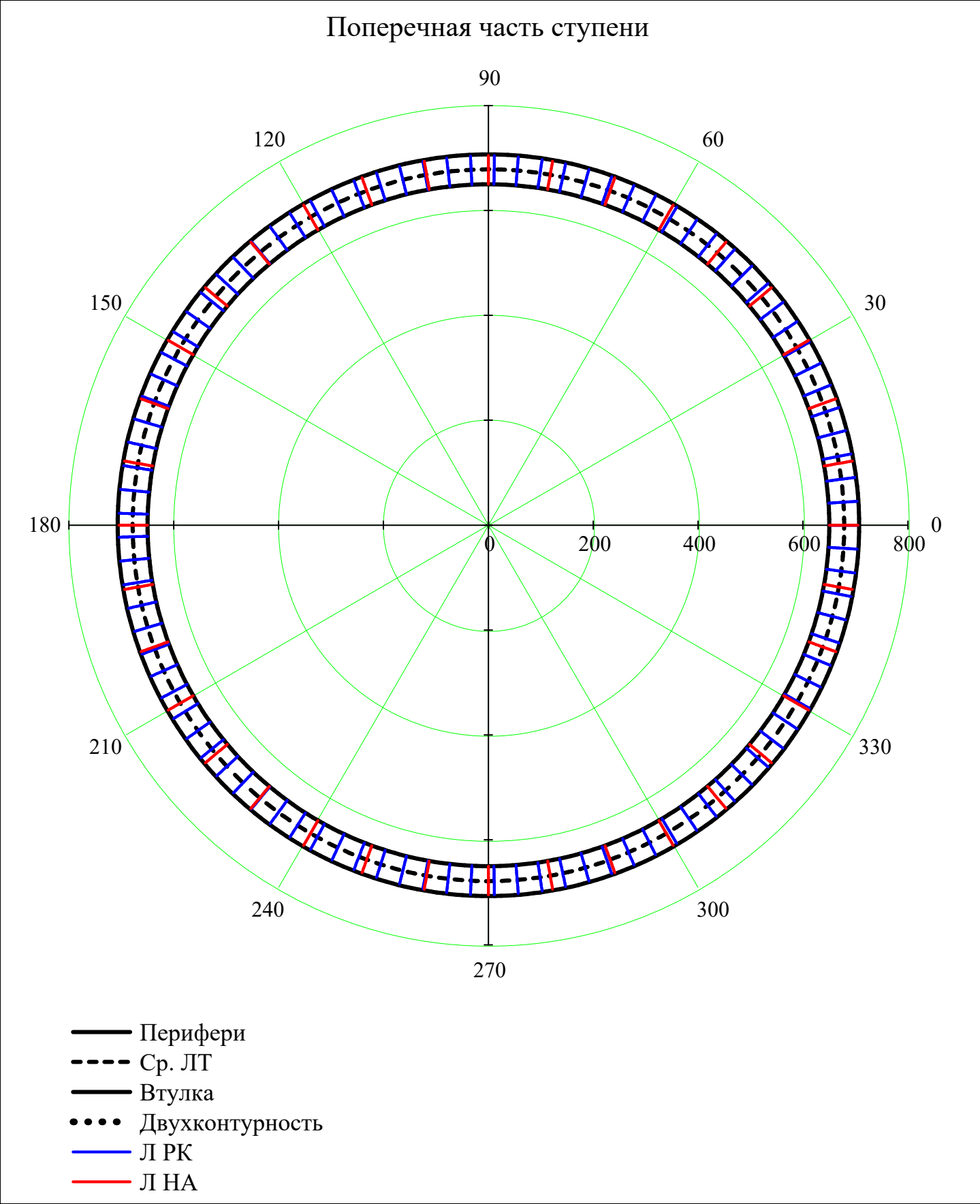
$$i_{\text{rotor}} = 1 \dots Z_{\text{rotor}_j}$$

$$i_{\text{stator}} = 1 \dots Z_{\text{stator}_j}$$

$$\varphi = 0, \frac{2 \cdot \pi}{360} \dots 2 \cdot \pi$$

$$Л_{PK}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{rotor}_j}} & \text{if } D_{\text{st}(j,1)}, 1 < r < D_{\text{st}(j,1)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$Л_{HA}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{stator}_j}} & \text{if } D_{\text{st}(j,2)}, 1 < r < D_{\text{st}(j,2)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$



▲ Поперечная часть ступени

$$\begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } r \in \text{av}(N_r) \\ \quad \quad \text{for } \text{mode} \in 1..6 \\ \quad \quad \quad \left| \begin{array}{l} \nu_{0\text{изГ.stator}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{stator}_{i,r}}, J_{u\text{stator}_{i,r}}) \\ \nu_{0\text{изГ.rotor}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{rotor}_{i,r}}, J_{u\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \end{array} \right. \\ \quad \quad \quad \begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix} \end{array}$$

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\text{stack}\left(\nu_{0_{\text{изг.stator}}}, \nu_{0_{\text{изг.rotor}}}\right)^T =$$

	1	2	3	4	5	6	7	8
1	12598	4867						
2	78956	30501						
3	221101	85411						
4	433594	167497						
5	716468	276772						
6	1070004	413343						

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\text{stack}\left(\nu_{0_{\text{угл.stator}}}, \nu_{0_{\text{угл.rotor}}}\right)^T =$$

	1	2
1	8364	6337
2	25091	19012
3	41819	31686
4	58546	44361
5	75273	57036
6	92001	69710

$$\text{stack}\left(\nu_{0_{\text{угл.stator_bondage}}}, \nu_{0_{\text{угл.rotor_bondage}}}\right)^T =$$

	1	2
1	16727	12675
2	33455	25349
3	50182	38024
4	66910	50698
5	83637	63373
6	100365	76048

Расчетный узел: type = "turbine"

Объем бандажной полки (м³): $V_{\text{бп}} = 0$

Радиус положения ЦМ бандажной полки (м): $R_{\text{бп}} = 0$

► Расчет Л на прочность

$$\text{neutral_line}(\text{type}, \text{x}, \text{i}, \text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) \text{ if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) \text{ if type = "stator"} \end{array} \right.$$

$$\text{epure}(\text{type}, \text{x}, \text{i}, \text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) \text{ if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) \text{ if type = "stator"} \end{array} \right.$$

Наиболее удаленные точки от НЛ (мм):

$$u_{u_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -0.201 \\ \hline 2 & 0.395 \\ \hline 3 & -5.492 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 19.281 \\ \hline 2 & 17.261 \\ \hline 3 & -8.241 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{u_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -7.067 \\ \hline 2 & 8.163 \\ \hline 3 & 8.159 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -11.366 \\ \hline 2 & -25.855 \\ \hline 3 & -25.848 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{u_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 4.881 \\ \hline 2 & 4.007 \\ \hline 3 & 12.797 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{l_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -10.812 \\ \hline 2 & -9.250 \\ \hline 3 & -15.884 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{u_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29.145 \\ \hline 2 & 8.195 \\ \hline 3 & 8.199 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{l_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -38.701 \\ \hline 2 & -14.480 \\ \hline 3 & -14.491 \\ \hline \end{array} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \sigma_{\text{p_rotor}_{i,r}} & \sigma_{\text{n_rotor}_{i,r}} \\ \sigma_{\text{p_stator}_{i,r}} & \sigma_{\text{n_stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_u}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_u}_{\text{rotor}_{i,r}} & \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_l}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_l}_{\text{rotor}_{i,r}} \\ \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_u}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_u}_{\text{stator}_{i,r}} & \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_l}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_l}_{\text{stator}_{i,r}} \end{pmatrix} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix}
\end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \sigma_{\text{p_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{p_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T, z\right) \end{array} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix}
\end{pmatrix}$$

$$\sigma_{\text{p}_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -21.92 \\ \hline 2 & -9.28 \\ \hline 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{rotor}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 48.01 \\ \hline 2 & 21.17 \\ \hline 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{rotor}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{p}_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ \hline 2 & 3.46 \\ \hline 3 & 13.83 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{stator}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ \hline 2 & -7.05 \\ \hline 3 & -28.20 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{stator}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \sigma_{\text{rotor}_{i,r}} &= \sqrt{\left(\sigma_{\text{Zrotor}}(i, R_{\text{st}}(i, 2), r) + \max(\sigma_{\text{Protor}_{i,r}}, \sigma_{\text{nrotor}_{i,r}}) \right)^2 + \tau_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)^2} \\ \sigma_{\text{stator}_{i,r}} &= \sqrt{\left(0 + \max(\sigma_{\text{Pstator}_{i,r}}, \sigma_{\text{nstator}_{i,r}}) \right)^2 + \tau_{\text{stator}}(i, R_{\text{st}}(i, 2), r)^2} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \left| \begin{aligned} \sigma_{\text{rotor.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{stator.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix}$$

$$\sigma_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 180.98 \\ 2 & 98.93 \\ 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ 2 & 5.60 \\ 3 & 16.40 \\ \hline \end{array} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \text{safety}_{\text{rotor}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}_i}}{\sigma_{\text{rotor}_{i,r}}} & \text{if } \sigma_{\text{rotor}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \\ \text{safety}_{\text{stator}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}_i}}{\sigma_{\text{stator}_{i,r}}} & \text{if } \sigma_{\text{stator}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix}$$

$$\text{safety}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.13 \\ 2 & 2.07 \\ 3 & 000000000000000000000000000000 \\ \hline \end{array}$$

$$\text{safety}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 000000000000000000000000000000 \\ 2 & 36.59 \\ 3 & 12.5 \\ \hline \end{array}$$

$$\text{safety}_{\text{rotor}}^T \geq \text{safety} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0 \\ 2 & 1 \\ 3 & 1 \\ \hline \end{array}$$

$$\text{safety}_{\text{stator}}^T \geq \text{safety} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ \hline \end{array}$$

Рассматриваемая ступень:

$$j_w = \begin{cases} j = \begin{cases} 1 & \text{if type = "compressor"} \\ Z & \text{if type = "turbine"} \end{cases} \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases} = 1$$

$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

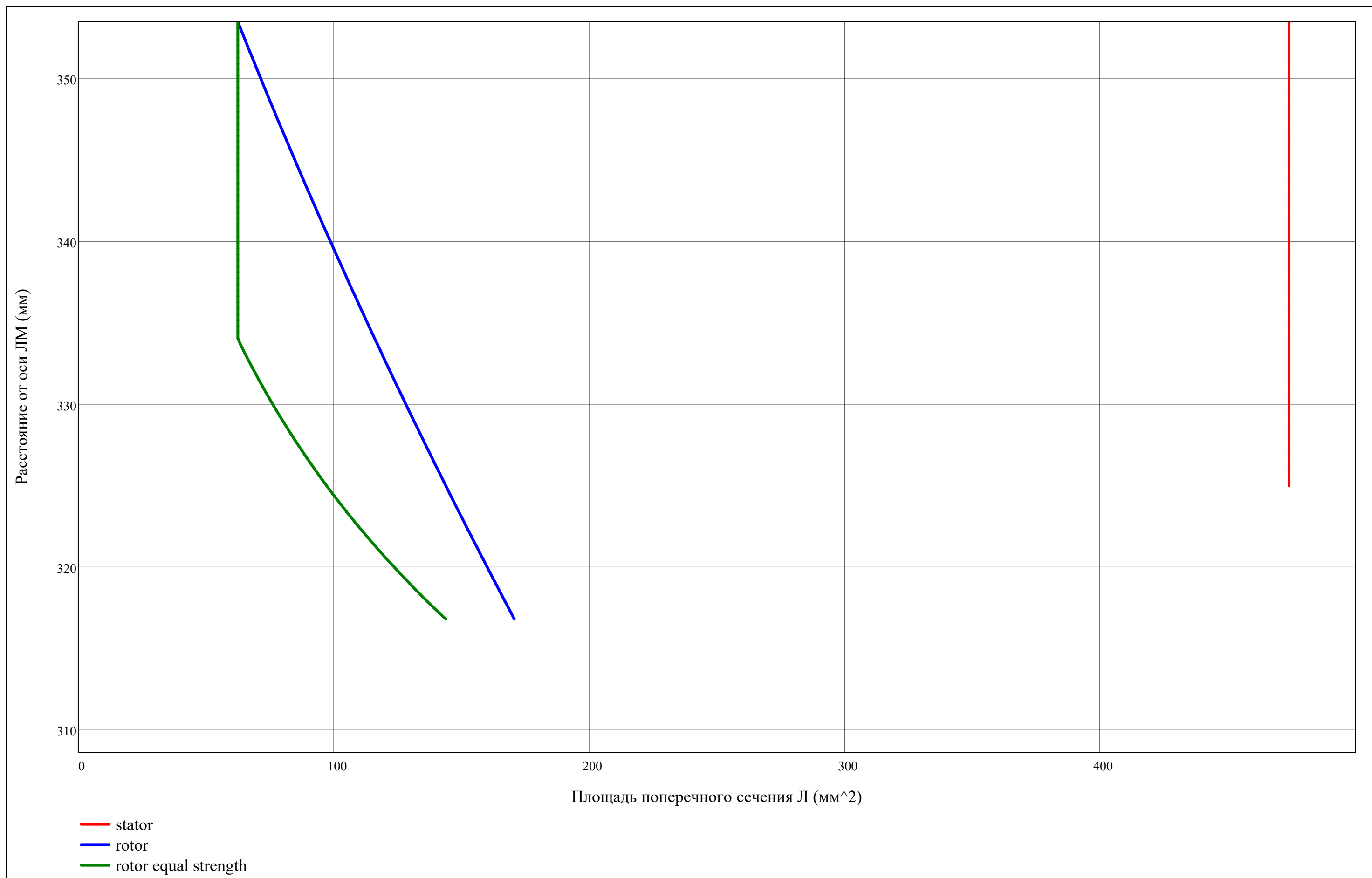
$$R_j = \text{submatrix}\left(R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 325.0 & 339.2 & 353.5 \\ \hline 2 & 325.0 & 339.2 & 353.5 \\ \hline 3 & 308.6 & 331.0 & 353.5 \\ \hline \end{array} \cdot 10^{-3}$$

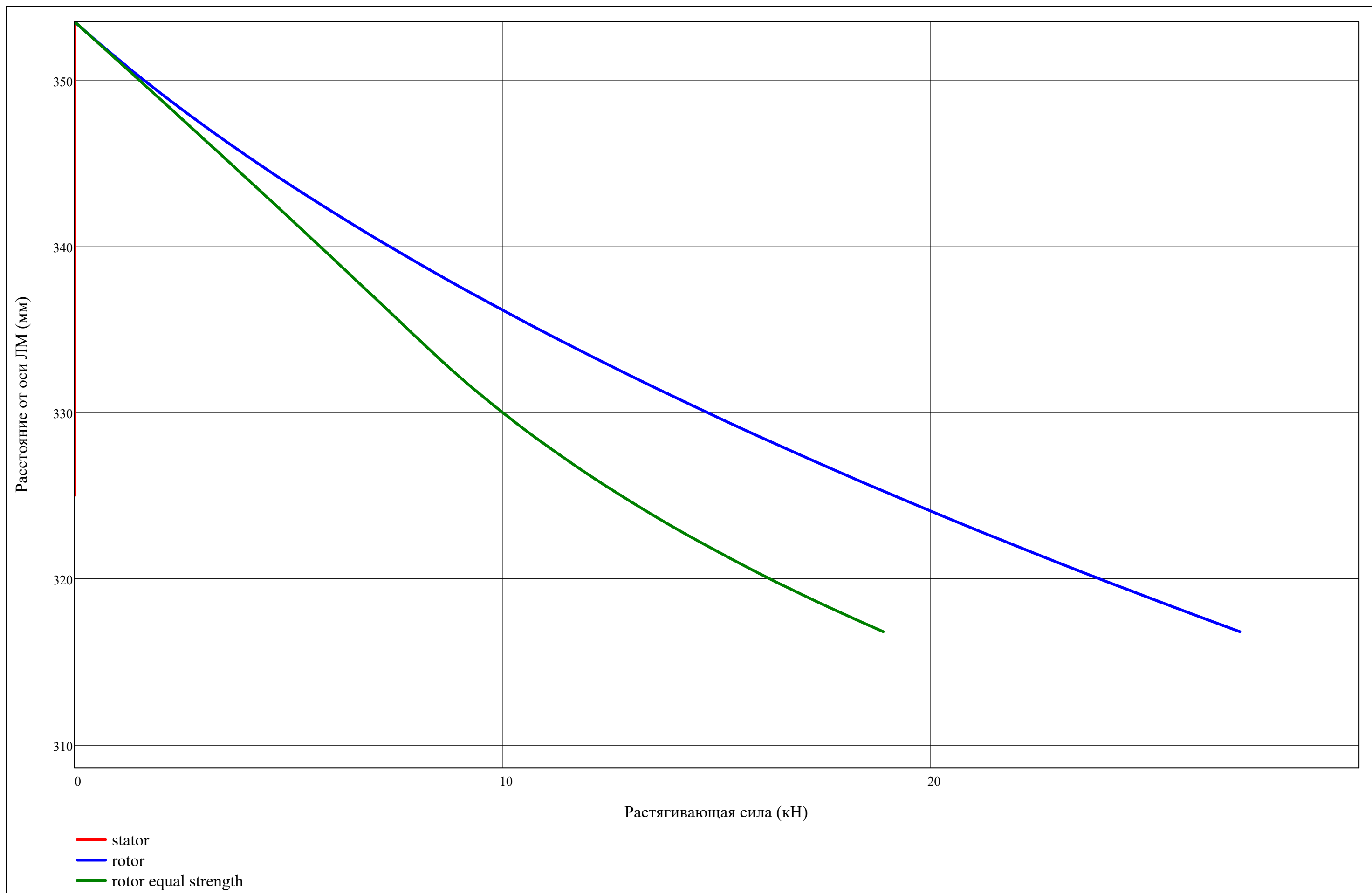
Дискретизация по высоте Л:

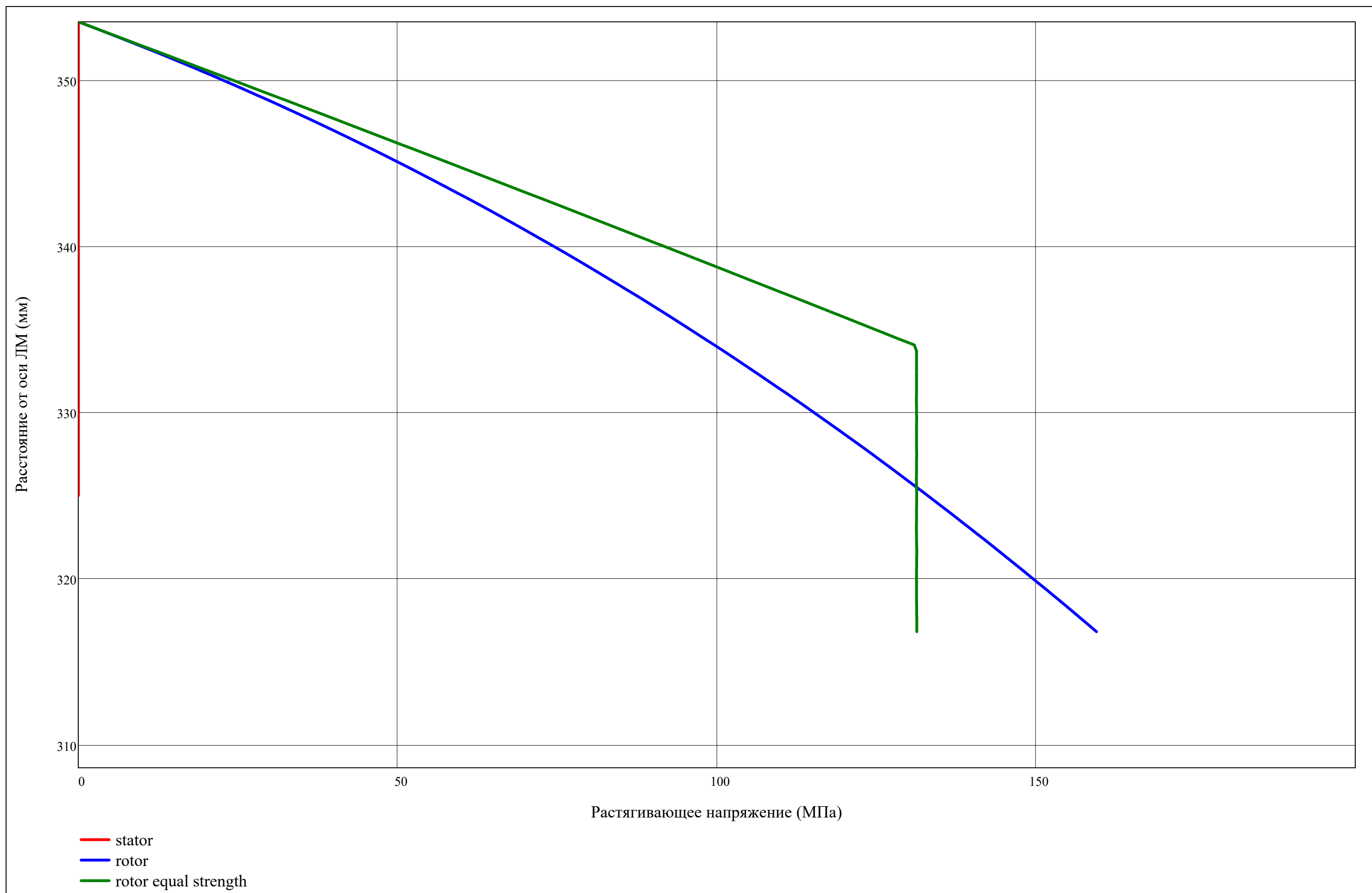
$$z = \min(R_j), \min(R_j) + \frac{\max(R_j) - \min(R_j)}{100} .. \max(R_j)$$

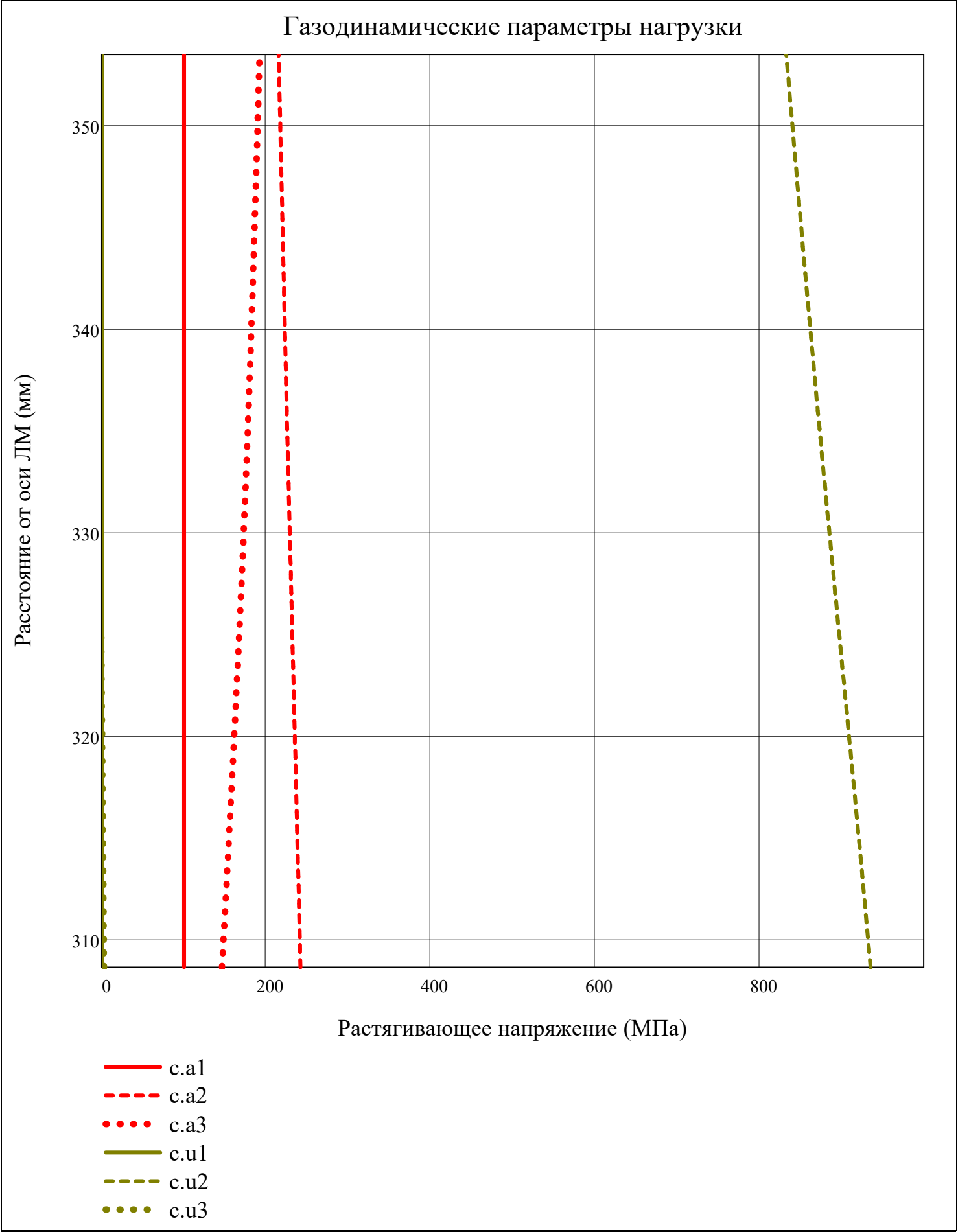
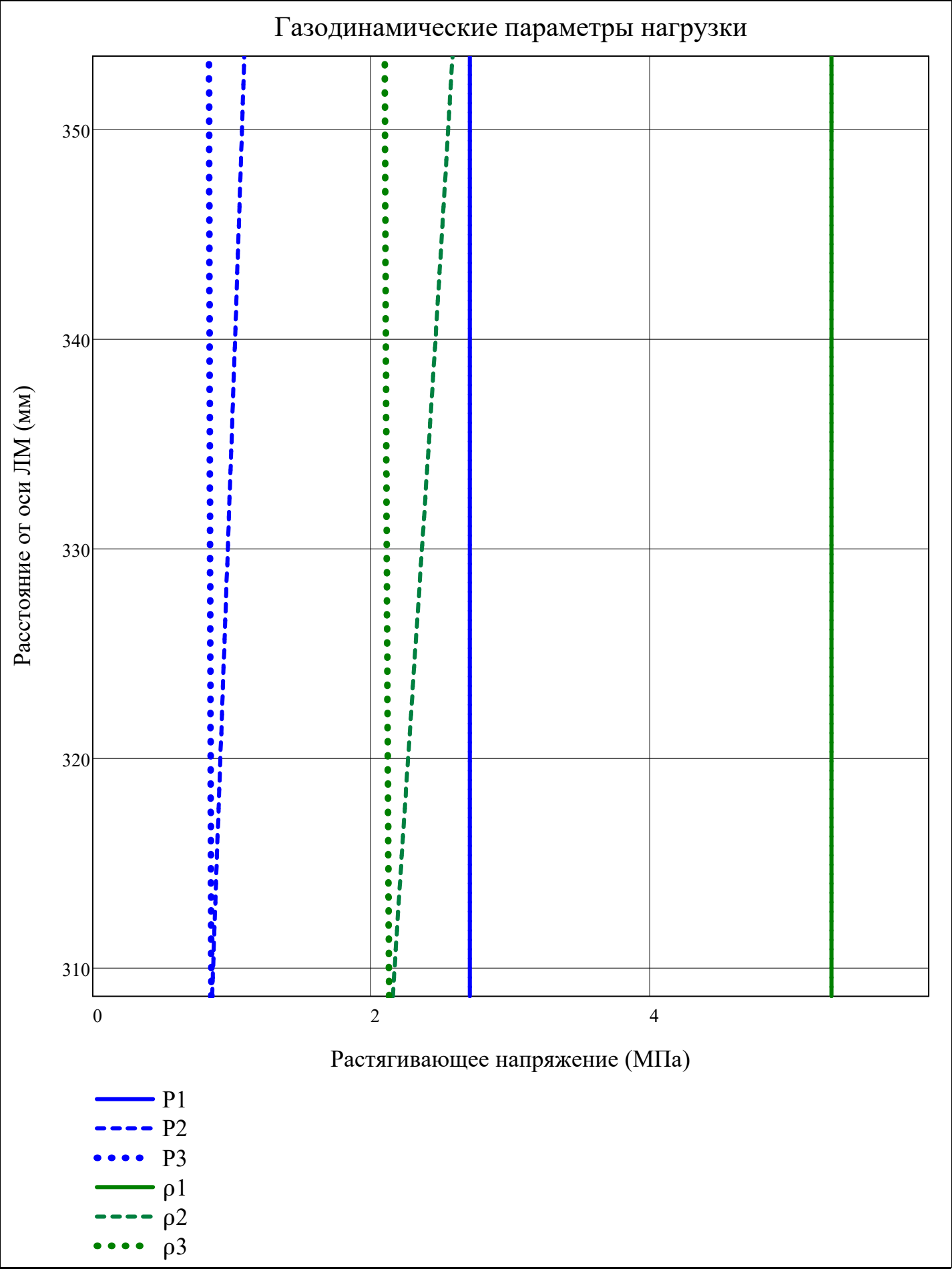
$$z_{\text{rotor}} = \begin{cases} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) & \text{if type = "compressor"} \\ \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) & \text{if type = "turbine"} \end{cases}$$

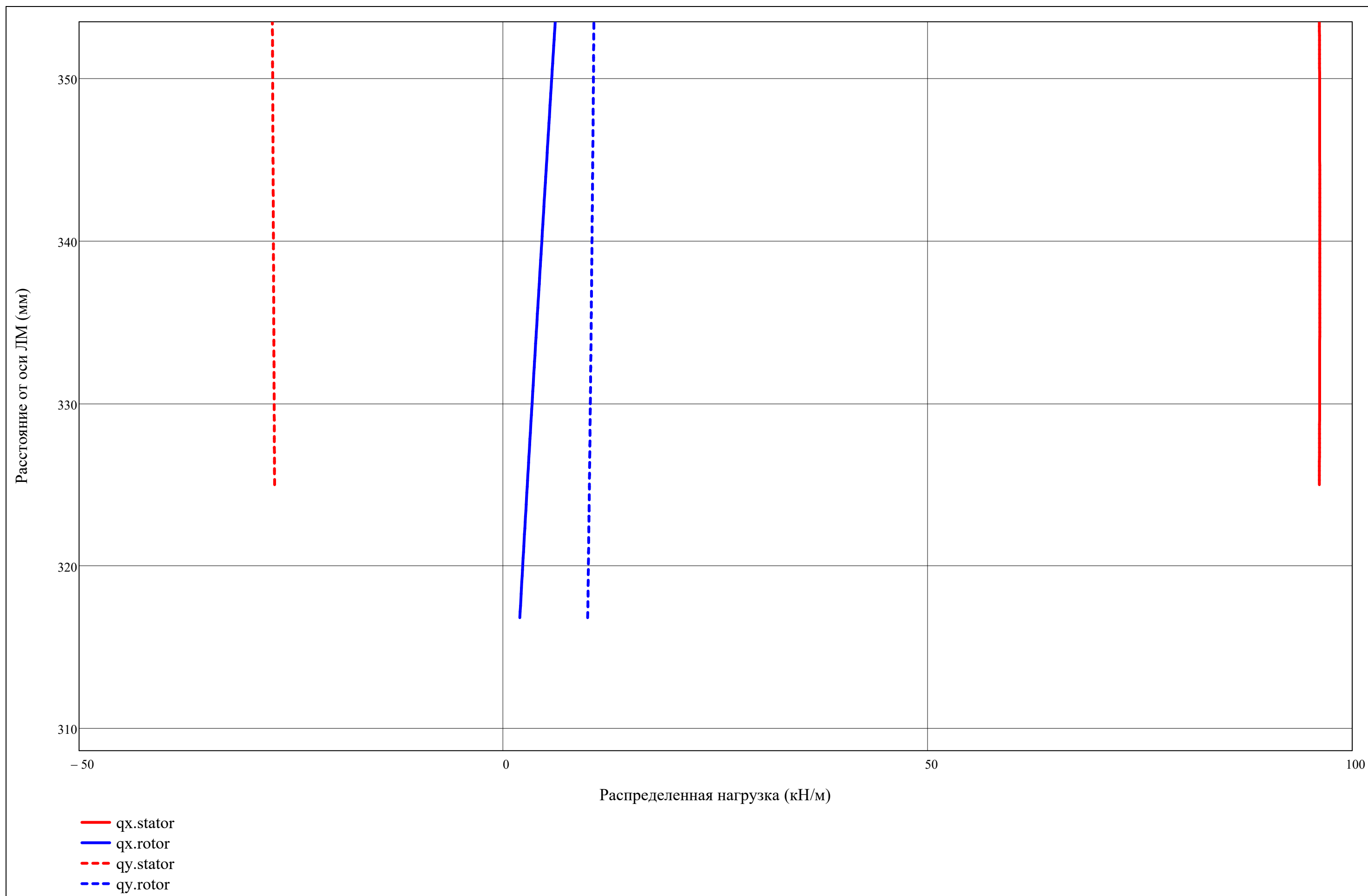
$$z_{\text{stator}} = \begin{cases} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) & \text{if type = "compressor"} \\ \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) & \text{if type = "turbine"} \end{cases}$$

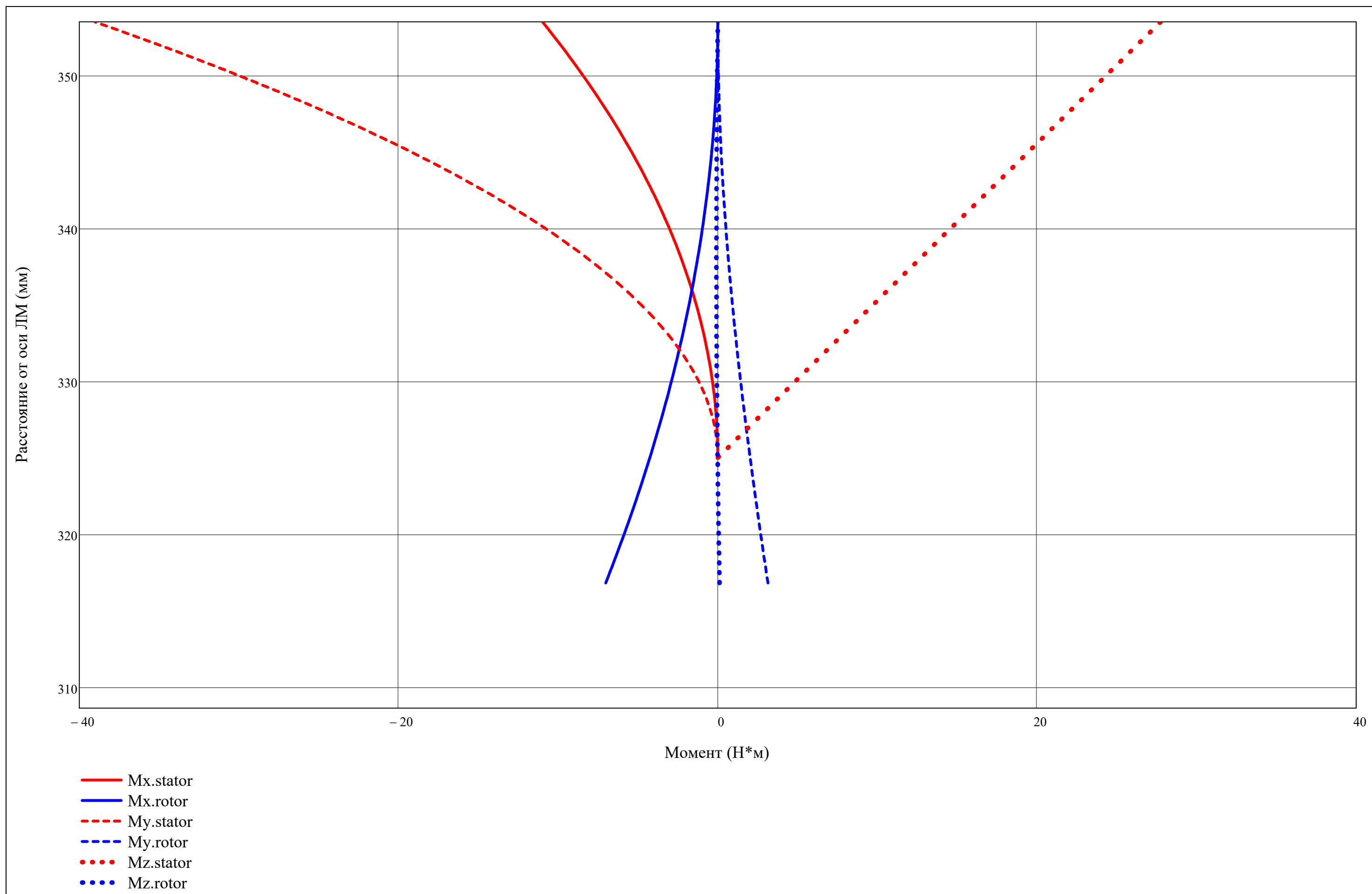


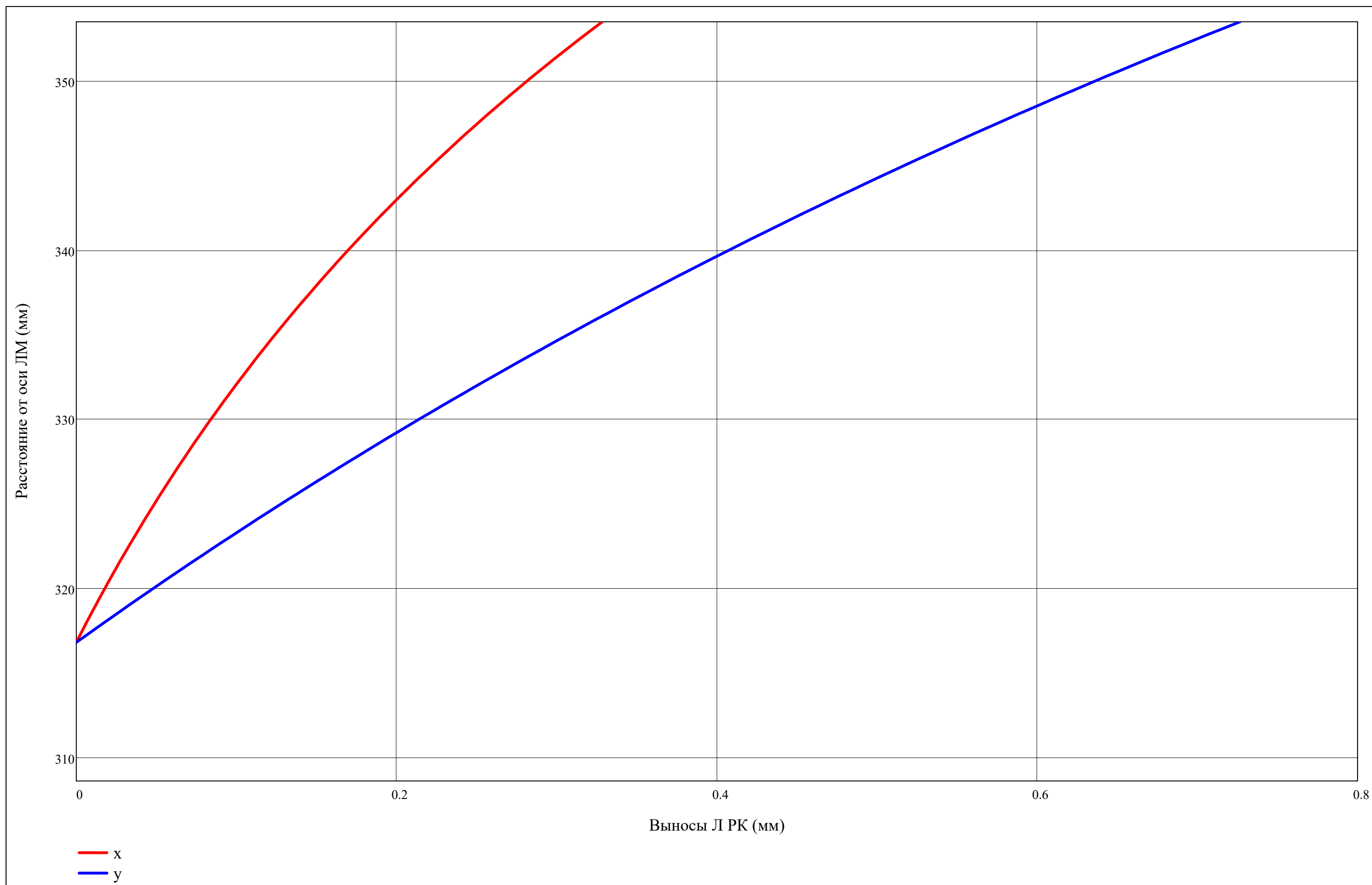


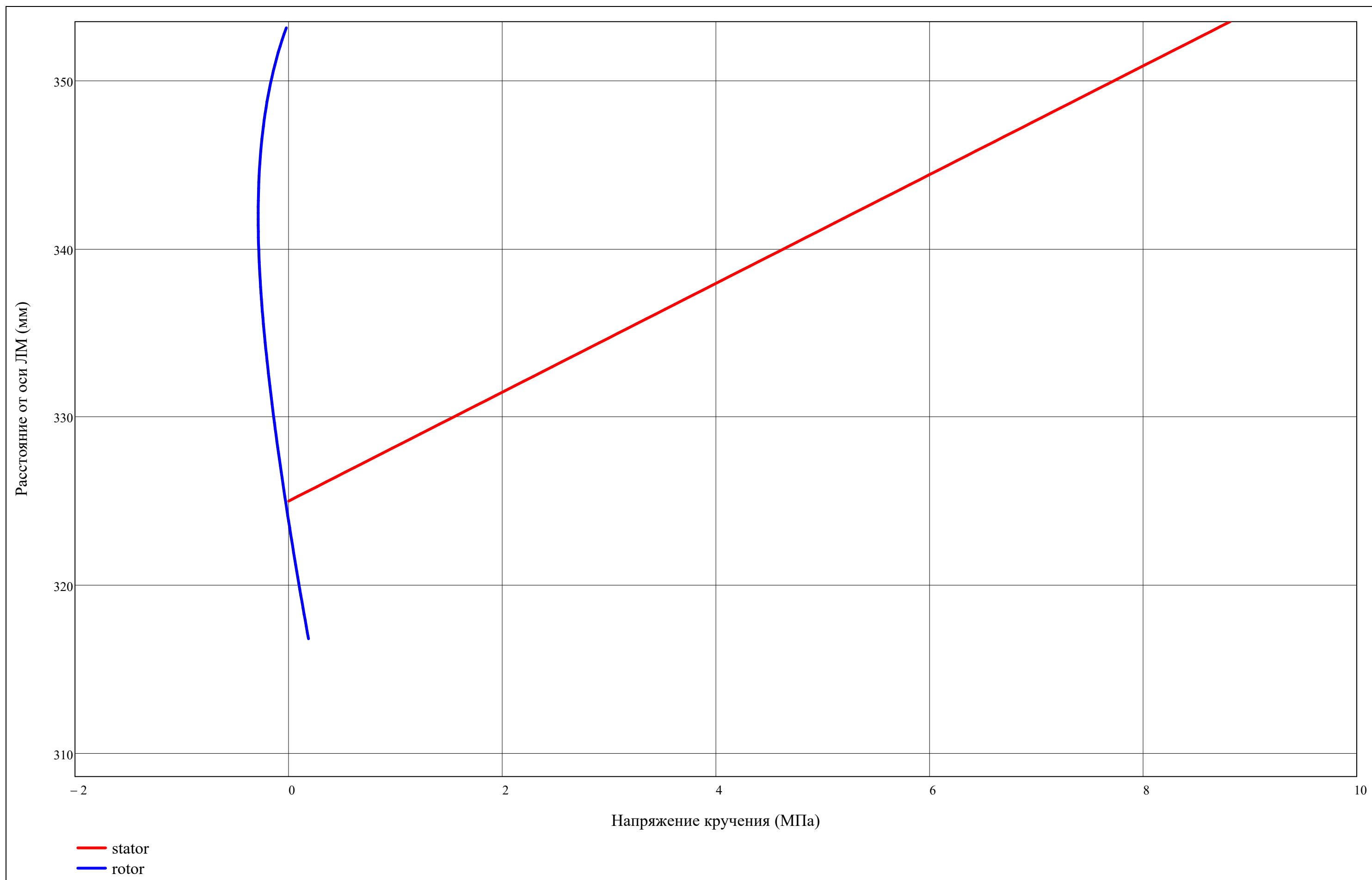


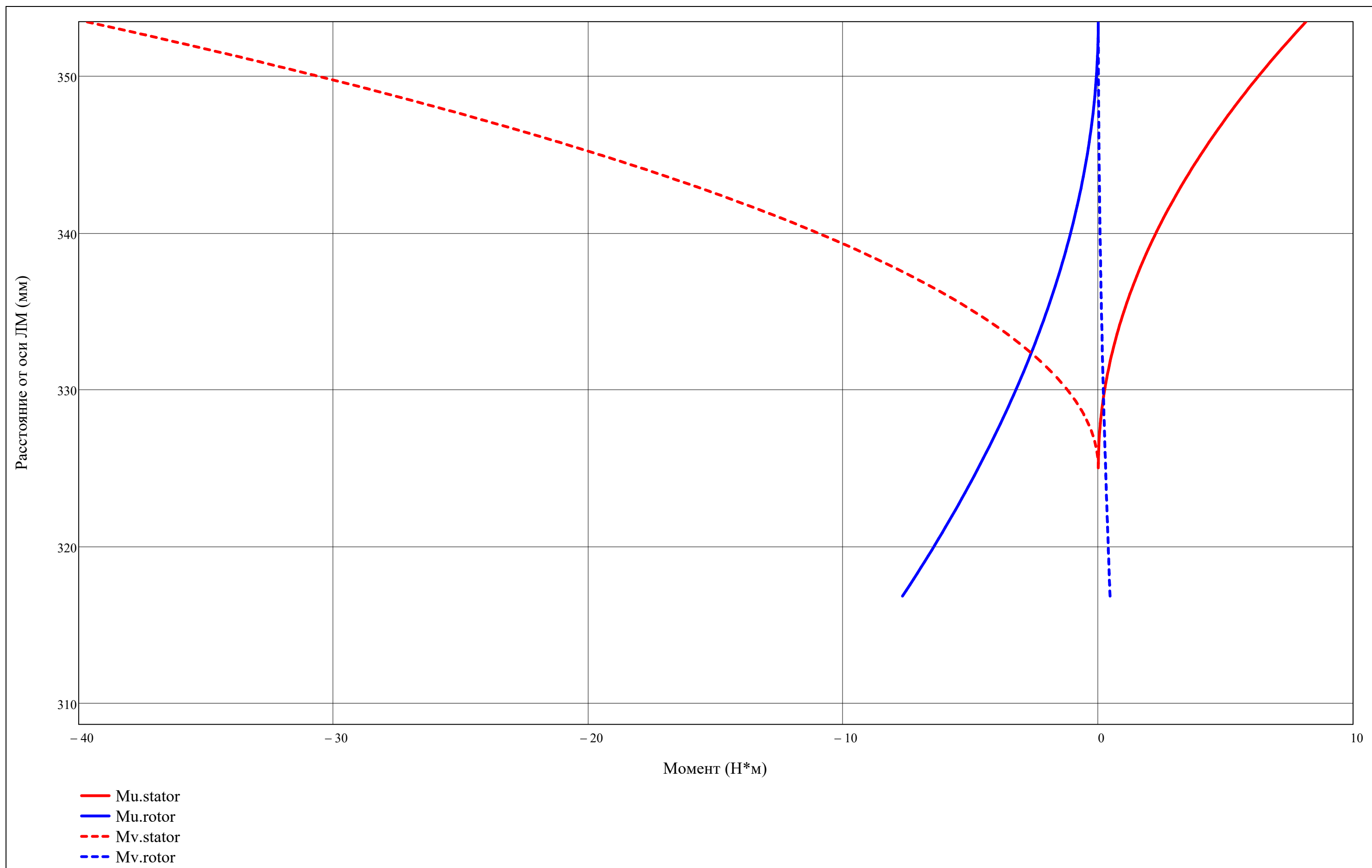


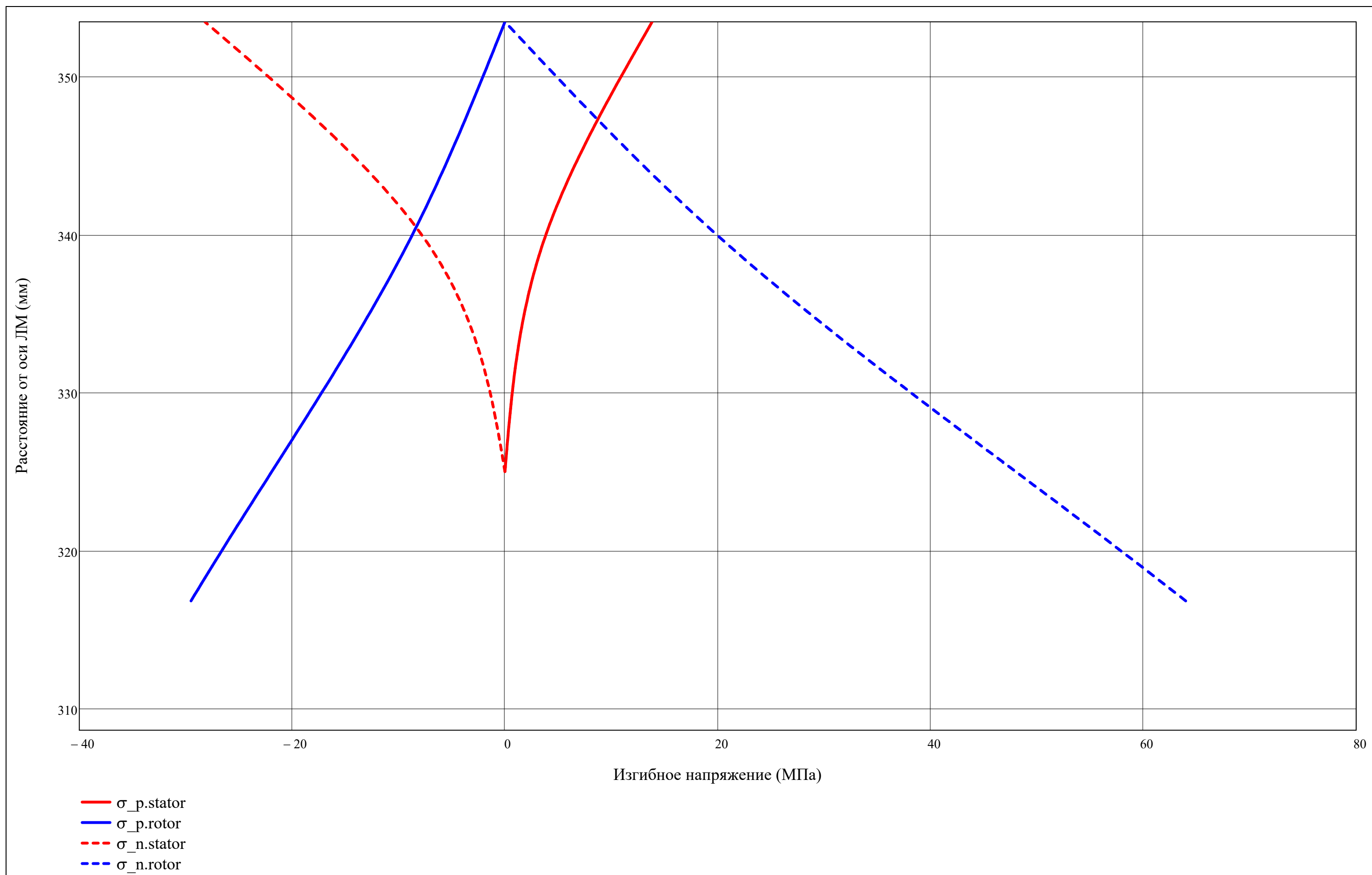


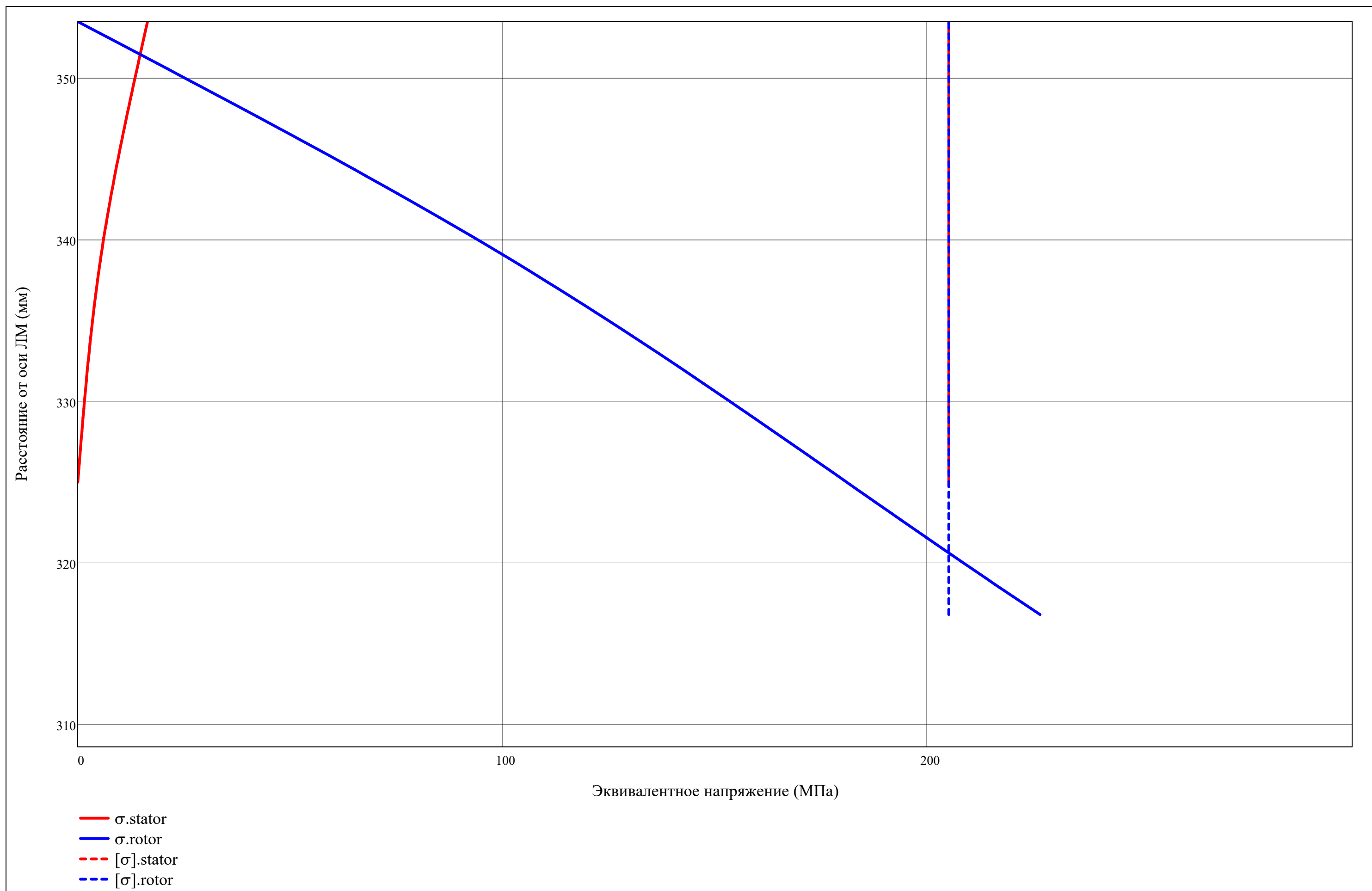










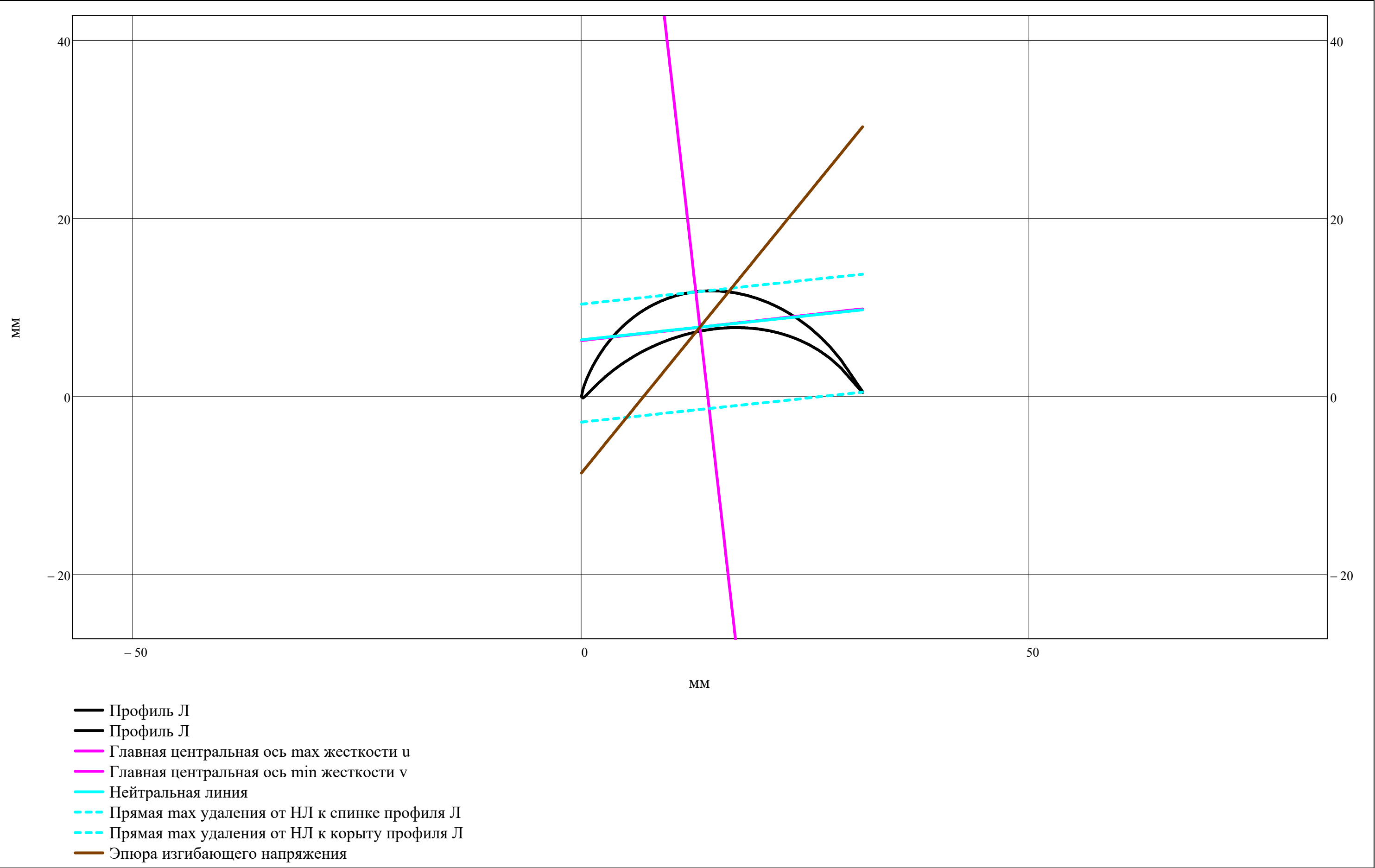


$$\begin{pmatrix} \text{blade} \\ r \end{pmatrix} = \begin{pmatrix} \text{"rotor"} \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} v_p \\ v_n \end{pmatrix} = \begin{cases} \begin{pmatrix} v_{-u_{rotor_j,r}} \\ v_{-l_{rotor_j,r}} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} v_{-u_{stator_j,r}} \\ v_{-l_{stator_j,r}} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 4.007 \\ \hline 2 & -9.250 \\ \hline \end{array} \cdot 10^{-3}$$

$$\begin{pmatrix} x0 \\ y0 \end{pmatrix} = \begin{cases} \begin{pmatrix} x0_{rotor_j,r} \\ y0_{rotor_j,r} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} x0_{stator_j,r} \\ y0_{stator_j,r} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 13.203 \\ \hline 2 & 7.789 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{chord} = \begin{cases} \text{chord}_{rotor_j,r} & \text{if blade = "rotor"} \\ \text{chord}_{stator_j,r} & \text{if blade = "stator"} \end{cases} = 31.4 \cdot 10^{-3}$$



Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{-u_{\text{rotor}_{j,r}}} & v_{-u_{\text{rotor}_{j,r}}} \\ u_{-l_{\text{rotor}_{j,r}}} & v_{-l_{\text{rotor}_{j,r}}} \\ u_{-u_{\text{stator}_{j,r}}} & v_{-u_{\text{stator}_{j,r}}} \\ u_{-l_{\text{stator}_{j,r}}} & v_{-l_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \tr \end{table} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{-p_{\text{rotor}_{j,r}}} & \sigma_{-p_{\text{stator}_{j,r}}} \\ \sigma_{-n_{\text{rotor}_{j,r}}} & \sigma_{-n_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{stator}_{j,r}} \\ \text{safety}_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table}$$

Запас по температуре (K):

$\Delta T_{\text{safety}} = 0$

Выбранный материал Д:

$\text{material_disk}_i = \begin{cases} \text{"ВЖ175"} & \text{if turbine = "ТВД"} \\ \text{"ЭП742"} & \text{if turbine = "ТНД"} \end{cases}$

Плотность материала Д (кг/м^3):

$\rho_{\text{disk}_i} =$	8266	if	$\text{material_disk}_i = \text{"ВЖ175"}$
	8320	if	$\text{material_disk}_i = \text{"ЭП742"}$
	8393	if	$\text{material_disk}_i = \text{"ЖС-6К"}$
	7900	if	$\text{material_disk}_i = \text{"BT41"}$
	4500	if	$\text{material_disk}_i = \text{"BT25"}$
	4570	if	$\text{material_disk}_i = \text{"BT23"}$
	4510	if	$\text{material_disk}_i = \text{"BT9"}$
	4430	if	$\text{material_disk}_i = \text{"BT6"}$
	NaN	otherwise	

Предел длительной прочности Д (Па):

$\sigma_{\text{disk_long}_i} = 10^6 \cdot$	620	if	$\text{material_disk}_i = \text{"ВЖ175"}$
	680	if	$\text{material_disk}_i = \text{"ЭП742"}$
	125	if	$\text{material_disk}_i = \text{"ЖС-6К"}$
	123	if	$\text{material_disk}_i = \text{"BT41"}$
	150	if	$\text{material_disk}_i = \text{"BT25"}$
	230	if	$\text{material_disk}_i = \text{"BT23"}$
	200	if	$\text{material_disk}_i = \text{"BT9"}$
	210	if	$\text{material_disk}_i = \text{"BT6"}$
	NaN	otherwise	

$\text{material_disk}^T =$		1
	1	"ВЖ175"

$\rho_{\text{disk}}^T =$		1
	1	8266

$\sigma_{\text{disk_long}}^T =$		1
	1	620

$\cdot 10^6$

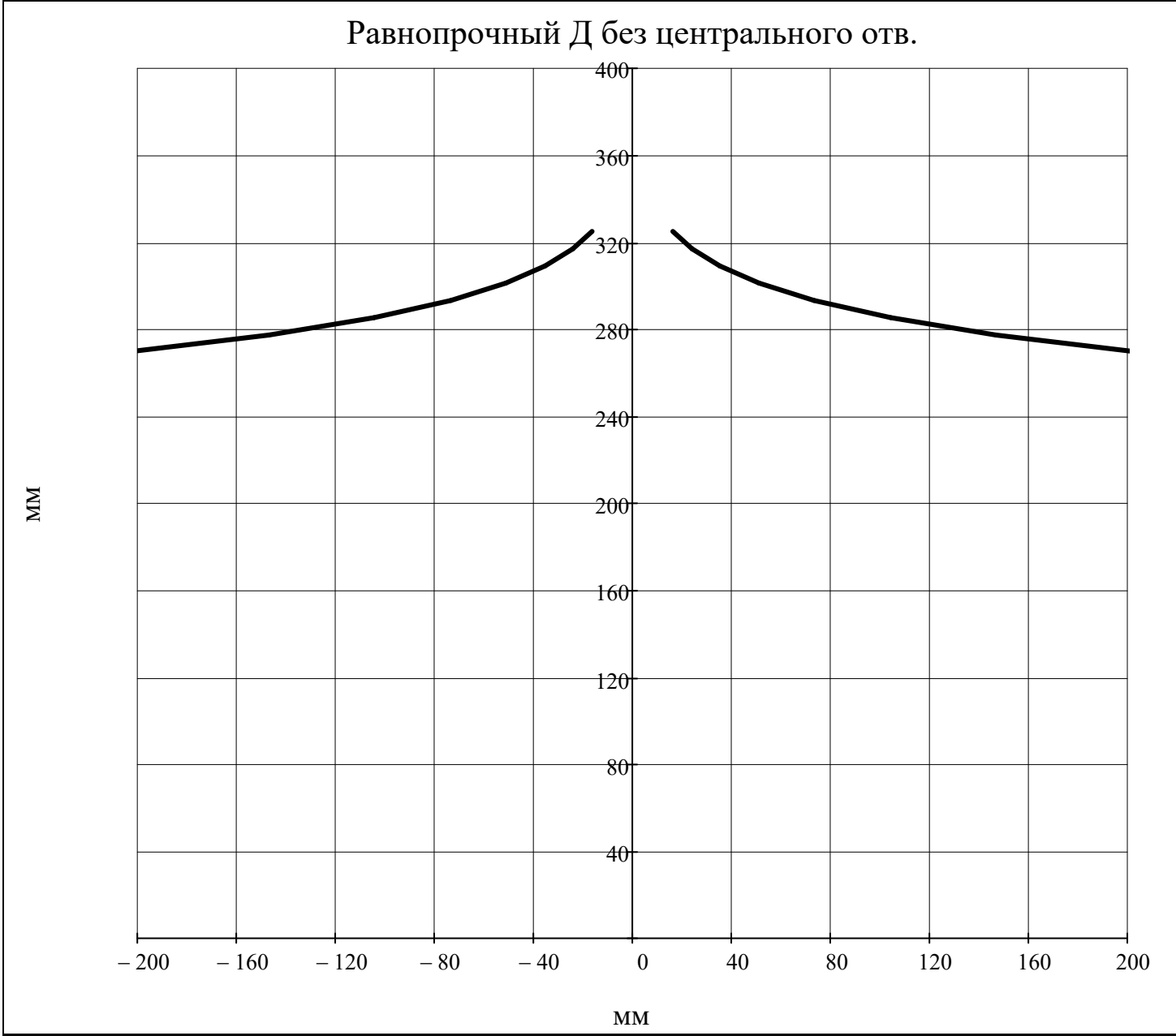
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & = 1 \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases}$$

Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{cases} \left(\text{chord}_{\text{rotor}_{i, \text{ORIGIN}}} \cdot \sin\left(v_{\text{rotor}_{i, \text{ORIGIN}}}\right) \right) \cdot e^{\frac{\rho_{\text{disk}_i} \cdot \omega^2}{2} \cdot \frac{1}{\sigma_{z_{\text{rotor}}(i, R_{\text{st}}(i, 2), \text{ORIGIN})}} \cdot \left[\left(R_{\text{st}}(i, 2), \text{ORIGIN} \right)^2 - z^2 \right]} & \text{if } z \leq R_{\text{st}}(i, 2), \text{ORIGIN} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$z = 0, \frac{R_{\text{st}}(j, 2), \text{ORIGIN}}{N_{\text{dis}}} .. R_{\text{st}}(j, 2), \text{ORIGIN}$$



Профилирование равнопрочного Д без центрального отв.

$$type = \begin{cases} type = "stator" & \\ type = \begin{cases} "Нет такого типа!" & \text{if } type \neq "stator" \wedge type \neq "rotor" \\ type & \text{otherwise} \end{cases} & \end{cases} = "stator"$$

Рассматриваемая ступень:

$$j = \begin{cases} j = 1 & \\ j = \begin{cases} "Такой ступени не существует!" & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 1$$







$$D^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 650.0 & 650.0 & 617.2 & & & & & & \\ 2 & 678.5 & 678.5 & 662.1 & & & & & & \\ 3 & 707.0 & 707.0 & 707.0 & & & & & & \end{array} \cdot 10^{-3}$$

$$\underline{\underline{R}} = \frac{D}{2}$$

$$R^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 325.0 & 325.0 & 308.6 & & & & & & \\ 2 & 339.2 & 339.2 & 331.0 & & & & & & \\ 3 & 353.5 & 353.5 & 353.5 & & & & & & \end{array} \cdot 10^{-3}$$

$$\bar{d} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..3 \\ \quad \quad \bar{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_f}} \\ \bar{d} \end{array}$$

$$\bar{d}^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.9194 & 0.9194 & 0.8730 & & & & & & \end{array}$$

$$\bar{d}^T \leq 0.9 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 0 & 1 \end{array}$$

$$h = \begin{array}{l} \text{for } i \in 1..2Z+1 \\ \quad h_i = \frac{F_i}{\pi \cdot D_{i,av}(N_f)} \\ h \end{array}$$

$$h^T = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 28.50 & 28.50 & 44.88 \end{array} \cdot 10^{-3}$$



$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 926.4 \\ 146.2 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 231.6 \\ 146.2 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 520.2 \\ 450.5 \\ 503.9 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.48 \\ 89.02 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 510.5 \\ 510.5 \\ 484.8 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 11.08 \\ 149.07 \\ 16.87 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 75.52 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 132.2 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 891.8 \\ 173.6 \end{pmatrix}$$

$$\begin{pmatrix} c_{ast(j,1),r} \\ c_{ast(j,2),r} \\ c_{ast(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 222.9 \\ 173.6 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 542.2 \\ 398.7 \\ 550.1 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.48 \\ 90.64 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 532.9 \\ 532.9 \\ 520.0 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 10.63 \\ 146.01 \\ 18.40 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 75.52 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 127.61 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 859.8 \\ 191.9 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.0 \\ 215.0 \\ 191.8 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 564.2 \\ 350.8 \\ 592.8 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.48 \\ 91.70 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 555.2 \\ 555.2 \\ 555.2 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 10.21 \\ 142.22 \\ 18.88 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 75.52 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 123.34 \cdot ^\circ$$

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