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▼ Исходные данные
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Коэф. запаса:
                   safety = 1.3
                                                                        turbine = "ТВД"
Горючее:
             Fuel = "Керосин"
Высота движения (м): H_{11} = 0
                                                                  32.30
Массовый расход перед Т (кг/с):
                                                                                                                 32.30
                                                                               if turbine = "ТВД"
Массовый расход утечек Т (кг/с):
                                                              106.96.10
                                                                                                                  0.11
                                          G<sub>cooling</sub>
Массовый расход на охл Т (кг/с):
                                                                              if turbine = "ТНД"
                       N_T = 10^6 \cdot 14.893 if turbine = "TBД" = 14.893 \cdot 10^6
Мощность Т (Вт):
                                      15.181 if turbine = "ТНД"
                                        P_{\Gamma}^* = 10^3 \cdot | 2731.8 \text{ if turbine} = "ТВД" = 2731.8 \cdot 10^3
Полное давление перед Т (Па):
                                                       927.5 if turbine = "ТНД"
                                         T^*_{\Gamma} = \begin{vmatrix} 1773 & \text{if turbine} = "ТВД" = 1773.0 \\ 1368.9 & \text{if turbine} = "ТНД" \end{vmatrix}
Полная температура перед Т (К):
                                \alpha_{\rm ox} = 2.267 if turbine = "ТВД" = 2.267
Коэф. избытка воздуха в Т:
                                           2.493 if turbine = "ТНД"
                                                                  P^*_{\text{cooling}} = 10^3 \cdot | 2845.6 \text{ if turbine} = "ТВД" = 2845.6 \cdot 10^3
Полное давление отбора охлаждающего воздуха (К):
                                                                                        319.4 if turbine = "ТНД"
                                                                                   806.9 if turbine = "ТВД" = 806.9
Полная температура отбора охлаждающего воздуха (К):
                                                                   T*cooling =
                                                                                    418.2 if turbine = "ТНД"
                                                          \sigma_{\text{cooling}} = 0.97
Коэф. сохранения полного давления охлаждения:
Подогрев охл. от КС [К]:
                               \Delta T_{\text{охл.подогрев}} = 40
Газовая постоянная (Дж/кг/К): R_{\Gamma a3}(\alpha_{ox}, Fuel) = 288.5
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 $T_{\Pi, \text{ДО}\Pi} = 1373$

Допустимая температура Л (К):

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

[1, c.15]

$$80 \le c_T \le 400 = 1$$

Лопаточный КПДТ: $\eta_{\Pi} = 88\%$

$$\eta_{\rm JI} = 88\%$$

$88\% \le \eta_{\rm JI} \le 95\% = 1$

Угол входа в Т: $\alpha_{\Gamma} = 90$. $^{\circ}$

$$\alpha_{\Gamma} = 90^{\circ}$$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_{\Gamma} \\ c_{T} \end{pmatrix} = \begin{pmatrix} 100 \\ 180 \end{pmatrix} \text{ if turbine} = "ТВД" = \begin{bmatrix} 1 \\ 1 \\ 100.0 \\ 2 \\ 180.0 \end{bmatrix}$$

$$\begin{pmatrix} 180 \\ 260 \end{pmatrix} \text{ if turbine} = "ТНД"$$

$$u_{\rm T} = \begin{bmatrix} 520 & \text{if turbine} = "ТВД" = 520.0 \\ 260 & \text{if turbine} = "ТНД" \end{bmatrix}$$



$$z = ORIGIN...N_r$$

 $P^*_{\text{cooling}} = P^*_{\text{cooling}} \cdot \sigma_{\text{cooling}} = 2760.2 \cdot 10^3$ Полное давление отбора охлаждающего воздуха (К):

 $T^*_{\text{cooling}} = T^*_{\text{cooling}} + \Delta T_{\text{охл.подогрев}} = 846.9$ Полная температура отбора охлаждающего воздуха (К):

 $G_{\Gamma} = G_{\Gamma} - G_{leak} = 32.2$ Массовый расход перед Т (кг/с):

 $G_{T} = G_{\Gamma} + G_{cooling} = 35.4$ Массовый расход после Т (кг/с):

Удельная работа T (Дж/кг): $L^*_T = \frac{N_T}{\text{mean} \left(G_\Gamma, G_T\right)} = 440.4 \cdot 10^3$ $L^*_T \leq 550 \cdot 10^3 = 1$ Располагаемый теплоперепад в T (Дж/кг): $H_T = \frac{L^*_T + 0.5c_T^2}{\eta_{_{I\!\!I}}} = 518.9 \cdot 10^3$

$$\begin{vmatrix} \text{iteration} \\ k_{\Gamma} \\ P_{\Gamma} \\ T_{\Gamma} \end{vmatrix} = \begin{vmatrix} \text{iteration} = 0 \\ k_{\Gamma} = k_{a,\Pi} \left(\text{Cp}_{\Gamma a3} \left(\text{P*}_{\Gamma}, \text{T*}_{\Gamma}, \alpha_{\text{OX}}, \text{Fuel} \right), \text{R}_{\Gamma a3} \left(\alpha_{\text{OX}}, \text{Fuel} \right) \right) \\ \text{while } 1 > 0 \end{vmatrix} = \begin{vmatrix} \frac{1}{1} & \frac{1.0}{2} & \frac{1.3}{3} & \frac{3}{2705198.4} \\ \text{while } 1 > 0 \end{vmatrix} \\ \begin{vmatrix} \text{Iteration} = \text{iteration} + 1 \\ \text{Cp}_{\Gamma} = \frac{k_{\Gamma}}{k_{\Gamma} - 1} \cdot \text{R}_{\Gamma a3} \left(\alpha_{\text{OX}}, \text{Fuel} \right) \end{vmatrix} \\ T_{\Gamma} = T^*_{\Gamma} - \frac{c_{\Gamma}^2}{2 \cdot \text{Cp}_{\Gamma}} \\ k^*_{\Gamma} = k_{a,\Pi} \left(\text{Cp}_{\Gamma a3} \left(\text{P}_{\Gamma}, \text{T}_{\Gamma}, \alpha_{\text{OX}}, \text{Fuel} \right), \text{R}_{\Gamma a3} \left(\alpha_{\text{OX}}, \text{Fuel} \right) \right) \\ \text{if } \left| \text{eps} \left(\text{"rel"}, k_{\Gamma}, k_{\Gamma}'_{\Gamma} \right) \right| \leq \text{epsilon} \\ k_{\Gamma} = k'_{\Gamma} \\ \text{break} \\ k_{\Gamma} = k'_{\Gamma} \\ \text{(iteration } k_{\Gamma}, \text{P}_{\Gamma}, \text{T}_{\Gamma} \right)^{\text{T}} \end{aligned}$$

Количество итераций: iteration = 1

Показатель адиабаты перед Т: $\mathbf{k}_{\Gamma} = 1.283$

Статическое давление перед Т (Па): $P_{\Gamma} = 2705.2 \cdot 10^3$

Статическая температура перед T(K): $T_{\Gamma} = 1769.2$

Теплоем кость перед Т (Дж/кг/К): $Cp_{\Gamma} = Cp_{\Gamma a3}(P_{\Gamma}, T_{\Gamma}, \alpha_{oX}, Fuel) = 1309$

$$\begin{vmatrix} \text{iteration} \\ k_T \\ P_T \\ T_T \end{vmatrix} = \begin{vmatrix} \text{iteration} = 0 \\ k_T = k_\Gamma \\ \text{while } 1 > 0 \\ \\ \text{iteration} = \text{iteration} + 1 \\ k_{Cp} = \text{mean}(k_\Gamma, k_T) \\ \\ Cp = \frac{k_{Cp}}{k_{Cp} - 1} \cdot R_{\text{ra3}}(\alpha_{\text{ox}}, \text{Fuel}) \\ \\ P_T = P^*_{\Gamma} \cdot \left(1 - \frac{H_T}{C_P \cdot T^*_{\Gamma}}\right)^{\frac{k_{Cp}}{k_{Cp} - 1}} \\ \\ T_T = T^*_{\Gamma} - \frac{H_T \cdot \eta_{\Pi}}{C_P} \\ k^*_T = k_{a,\Pi} \left(C_{P_{\text{ra3}}}(P_T, T_T, \alpha_{\text{ox}}, \text{Fuel}), R_{\text{ra3}}(\alpha_{\text{ox}}, \text{Fuel})\right) \\ \text{if } |\exp(\text{"rel"}, k_T, k_T'_T)| \leq \text{epsilon} \\ |k_T = k^*_T| \\ \text{break} \\ k_T = k^*_T \\ \text{(iteration } k_T \cdot P_T \cdot T_T)^T \\ \end{vmatrix}$$

Количество итераций: iteration = 1

Показатель адиабаты после Т: $k_{\rm T} = 1.293$

Статическое давление после T (Па): $P_{T} = 866.5 \cdot 10^{3}$ $P_{T} \geq P_{ATM}(H_{U}) = 1$

Статическая температура после T (K): $T_T = 1424.1$

Теплоем кость после Т (Дж/кг/К): $Cp_T = Cp_{\Gamma a3}(P_T, T_T, \alpha_{oX}, Fuel) = 1271.6$

Ср. показатель адиабаты Т:
$$k = mean(k_T, k_T) = 1.288$$

Ср. теплоемкость Т (Дж/кг/К): Ср
$$= \frac{k}{k-1} \cdot R_{\Gamma a3} (\alpha_{ox}, \text{Fuel}) = 1289.8$$

Степень понижения давления:
$$\pi_{T} = \frac{P^{*}_{\Gamma}}{P_{T}} = 3.15$$

Удельный объём перед Т (м³/кг):
$$\begin{pmatrix} v_{\Gamma} \\ v_{T} \end{pmatrix} = R_{\Gamma a 3} \Big(\alpha_{OX}, \text{Fuel} \Big) \cdot \begin{pmatrix} \frac{T_{\Gamma}}{P_{\Gamma}} \\ \frac{T_{T}}{P_{T}} \end{pmatrix} = \frac{1}{1 \quad 0.189}$$
 (С. 11)

Площадь кольцевого сечения перед T (м²):
$$\begin{pmatrix} F_{\Gamma} \\ F_{T} \end{pmatrix} = \begin{pmatrix} \frac{G_{\Gamma} \cdot v_{\Gamma}}{c_{\Gamma}} \\ \frac{G_{\Gamma} \cdot v_{T}}{c_{T}} \end{pmatrix} = \begin{pmatrix} \frac{1}{1 & 60741} \\ \frac{1}{2 & 93341} \end{pmatrix} \cdot 10^{-6}$$

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

 $0.7 \le \mu_{\rm c} \le 1 = 1$

▼ Определение количества ступеней Т

Рекомендуемое количество ступеней: $Z_{recomend} = 1$

Количество ступеней: $Z = \begin{bmatrix} 1 & \text{if turbine} = \text{"ТВД"} = 1 \\ 4 & \text{if turbine} = \text{"ТНД"} \end{bmatrix}$

Дискретизация ступеней: i = 1...Z

Дискретизация сечений: $ii = 1...2 \cdot Z + 1$

Плотность материала
$$J(\kappa r/m^3)$$
:
$$\rho_blade_i = 7938 \quad \text{if material_blade}_i = "BKHA-1B"$$

$$8390 \quad \text{if material_blade}_i = "BKM7"$$

$$8760 \quad \text{if material_blade}_i = "KC-36"$$
 NaN otherwise

$$\rho_{\text{blade}}^{\text{T}} = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 7938 \end{array}}$$

$$\sigma_blade_long^T = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 205 \end{array}} \cdot 10^6$$

Коэф. формы: $k_n = 6.8$

Модуль Юнга I рода материала Π (Π a): $E_blade = 210 \cdot 10^9$

Коэф. Пуассона материала Π (): μ steel = 0.3

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_{\text{blade_long}Z}}{\text{safety} \cdot k_{\text{n}} \cdot F_{\Gamma}}} = 19539$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{\text{max}} = \sqrt{\frac{\sigma_{\text{blade_long}Z}}{\text{safety} \cdot k_{\text{n}} \cdot F_{\text{T}}}} = 15762$$

Рекомендукмая ном. частота вращения (об/мин):

$$n = n_{\text{max}} \cdot 0.95 = 14974$$

$$_{\text{W}} = \begin{vmatrix} 15000 & \text{if turbine} = \text{"ТВД"} \\ 5300 & \text{if turbine} = \text{"ТНД"} \end{vmatrix} = 15000$$

Ном. частога вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 1570.8$$

Ср. диаметр перед Т (м):
$$\begin{pmatrix} D_{\Gamma.cp} \\ D_{T.cp} \end{pmatrix} = \frac{2}{\omega} \cdot \begin{pmatrix} u_T \\ u_T \end{pmatrix} = \begin{bmatrix} 1 \\ 1 & 662.1 \\ 2 & 662.1 \end{bmatrix} \cdot 10^{-3}$$

Длина Л первой ступени Т (м):

Длина Л последней ступени Т (м):

	$\begin{pmatrix} F_{\Gamma} \end{pmatrix}$				
$\begin{pmatrix} 1_{\Gamma} \end{pmatrix}$ 1	$D_{\Gamma,cp}$			1	– 3
$\begin{vmatrix} 1 \end{vmatrix} = \frac{1}{\pi}$	\mathbf{F}_{-}	=	1	29.20	.10
$\binom{1}{T}$	T		2	44.88	
	$\left(\mathrm{D}_{\mathrm{T.cp}}\right)$				

Диаметр периферии после
$$T(M)$$
:
$$\begin{pmatrix} D_{T.Пер} \\ D_{T.Кор} \end{pmatrix} = \begin{pmatrix} D_{T.cp} + l_T \\ D_{T.cp} - l_T \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 707.0 \\ 2 \\ 617.2 \end{bmatrix} \cdot 10^{-3}$$

$$\frac{l_{\rm T}}{D_{\rm T.cp}} = \frac{1}{14}$$

$$N_{cT_i} = \frac{N_T}{Z}$$

Вид проточной части:

("const", "кор", "cp", "пер", "доля от предыдушего диаметра периферии")

Определение проточной части ОТ

Линейное распределение кольцевых площадей по сечениям:

$$\begin{array}{ll} F_{w} = & \text{ for } i \in 1...2Z + 1 \\ & F_{i} = \frac{F_{T} - F_{\Gamma}}{\text{st}(Z,3) - 1} \cdot i + \left(F_{\Gamma} - \frac{F_{T} - F_{\Gamma}}{\text{st}(Z,3) - 1}\right) \\ & \text{ for } i \in 1...Z \\ & \text{ for } a \in 2...3 \\ & F_{\text{st}(i,a)} = F_{\text{st}(i,a-1)} \quad \text{if } 3\Pi\Pi \Psi_{i,a-1} = \text{"const"} \\ & F \end{array}$$

$F^{T} =$		1	2	3	4	5	6	7	8	9	10^{-6}
	1	60741	60741	93341							

$$\begin{array}{ll} D = & \text{ for } i \in 2Z + 1 \\ & \text{ for } r \in 1..N_r \\ & D_{i,r} = & \left| \begin{array}{l} D_{T,KOP} & \text{ if } r = 1 \\ D_{T,cop} & \text{ if } r = av(N_r) \\ D_{T,ncp} & \text{ if } r = N_r \end{array} \right. \\ & \text{ for } i \in Z..1 \\ & \text{ for } r \in 1..N_r \\ & D_{st(i,a),r} = & \left| \begin{array}{l} \text{ if } 3\Pi\Pi^t I_{i,a} = "const" \\ D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array} \right. \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "kop" \\ & D_{st(i,a+1),1} & \text{ if } r = 1 \\ & \frac{1}{2} \left[D_{st(i,a+1),1} + \sqrt{\left(D_{st(i,a+1),1}\right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} & \text{ if } r = N_r \end{array} \right. \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "cp" \\ & D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array} \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "cp" \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array}$$

$$D^{T} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 650.0 & 650.0 & 617.2 & & & & & \\ 2 & 678.5 & 678.5 & 662.1 & & & & & \\ 3 & 707.0 & 707.0 & 707.0 & & & & & & \end{bmatrix} \cdot 10^{-3}$$

$$R = \frac{D}{2}$$

$$\overline{d} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } a \in 1..3 \end{cases}$$

$$\overline{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$$

$$\overline{d}$$

$\overline{d}^T =$		1	2	3	4	5	6	7	8	9
	1	0.9194	0.9194	0.8730						

$$\begin{array}{|c|c|} h = & \text{for } i \in 1..2Z + 1 \\ \\ h_i = \frac{F_i}{\pi \cdot D_{i, av(N_r)}} \\ \\ h \end{array}$$

$$\begin{split} & \left[\frac{D}{st(i,a+1),N_r} \right]^{D-1-r} r \\ & \text{if } \left(3\Pi\Pi \Psi_{i,\,a} \neq \text{"const"} \right) \wedge \left(3\Pi\Pi \Psi_{i,\,a} \neq \text{"kop"} \right) \wedge \left(3\Pi\Pi \Psi_{i,\,a} \neq \text{"cp"} \right) \wedge \left(3\Pi\Pi \Psi_{i,\,a} \neq \text{"nep"} \right) \\ & \sqrt{\left(\frac{D}{st(i,a+1),N_r} \right)^2 - \frac{4 \cdot F_{st(i,\,a)}}{\pi}} \quad \text{if } r = 1 \\ & \frac{1}{2} \cdot \left[\sqrt{\left(\frac{D_{st(i,a+1),N_r}}{str2num \left(3\Pi\Pi \Psi_{i,\,a} \right)} \right)^2 - \frac{4 \cdot F_{st(i,\,a)}}{\pi}} + \frac{D_{st(i,a+1),N_r}}{str2num \left(3\Pi\Pi \Psi_{i,\,a} \right)} \right] \quad \text{if } r = av \left(N_r \right) \\ & \frac{D_{st(i,a+1),N_r}}{str2num \left(3\Pi\Pi \Psi_{i,\,a} \right)} \quad \text{if } r = N_r \end{split}$$

D

for
$$i \in 1...2 \cdot Z + 1$$

for $r \in 1...N_r$

$$u_{i,r} = \frac{\pi \cdot D_{i,r} \cdot n}{60}$$

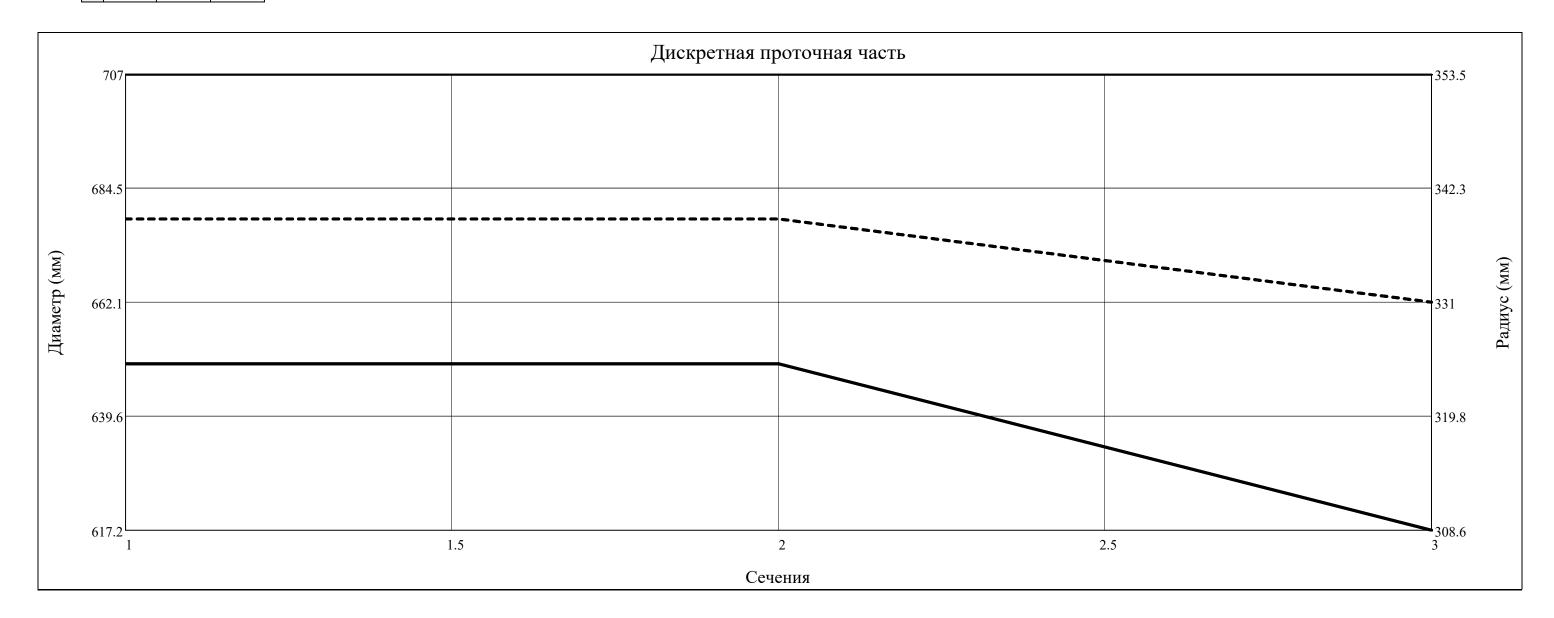
$$u$$

		1	2	3	4	5	6	7	8	9
$u^{T} =$	1	510.5	510.5	484.8						
-	2	532.9	532.9	520.0						
	3	555.2	555.2	555.2						

$$\overline{d}_{1} = 0.9194$$
 $\overline{d}_{1} \le 0.9 = 0$

$\overline{d}^T =$		1	2	3	4	5	6	7	8	9
	1	0.9194	0.9194	0.8730						

$$D^{T} = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 650.0 & 650.0 & 617.2 \\ 2 & 678.5 & 678.5 & 662.1 \\ 3 & 707.0 & 707.0 & 707.0 \end{bmatrix} \cdot 10^{-3}$$



Осевая ширина Л СА и РК [1, с.183]:

$$\begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix} = \begin{vmatrix} \text{for } i \in 1..Z \\ \begin{pmatrix} B_{CA}_i \\ B_{PK_i} \end{pmatrix} = \begin{pmatrix} \frac{D_{st(i,2),av(N_r)} - 0.25 \cdot h_{st(i,2)}}{16.4} \\ \frac{D_{st(i,3),av(N_r)}}{22} \end{vmatrix}$$

$$\begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix}$$

$$stack(B_{CA}^{T}, B_{PK}^{T}) = \begin{bmatrix} 1 & 1 \\ 1 & 40.9 \\ 2 & 30.1 \end{bmatrix} \cdot 10^{-3}$$

Радиальный зазор (м):

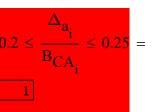
Осевой зазор (м):

(Лучше выбирать большее значение)

$$\begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix} = \begin{vmatrix} \text{for } i \in 1...Z \\ \text{for } a \in 1...3 \\ \begin{vmatrix} \Delta_{r_{st(i,a)}} = 0.001 \cdot D_{st(i,a)}, N_r \\ \Delta_{a_i} = 0.25 \cdot B_{CA_i} \\ \begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix}$$

$$\Delta_{\mathbf{r}}^{T} = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 0.707 & 0.707 & 0.707 \end{bmatrix} \cdot 10^{-3}$$

$$\Delta_a^T = \boxed{\begin{array}{c|c} 1 \\ \hline 1 & 10.234 \end{array}} \cdot 10^-$$



$$stack\left(\gamma_{\prod \text{V}}, \gamma_{\prod \text{V}}, \gamma_{\prod \text{V}}, \gamma_{\prod \text{V}}, \gamma_{\prod \text{V}}\right) = \begin{vmatrix} 1 & 2 \\ 1 & 0.00 & -28.56 \\ 2 & -0.00 & 28.56 \\ 3 & 0.00 & 0.00 \end{vmatrix} . \circ$$

$\gamma_{\prod q}^T \le 20 \cdot \circ =$	1	1	2	
$\gamma_{\Pi \Psi}^{T} \leq 25 \cdot \circ = 0$		1	2	
'11'1	1	1	0	

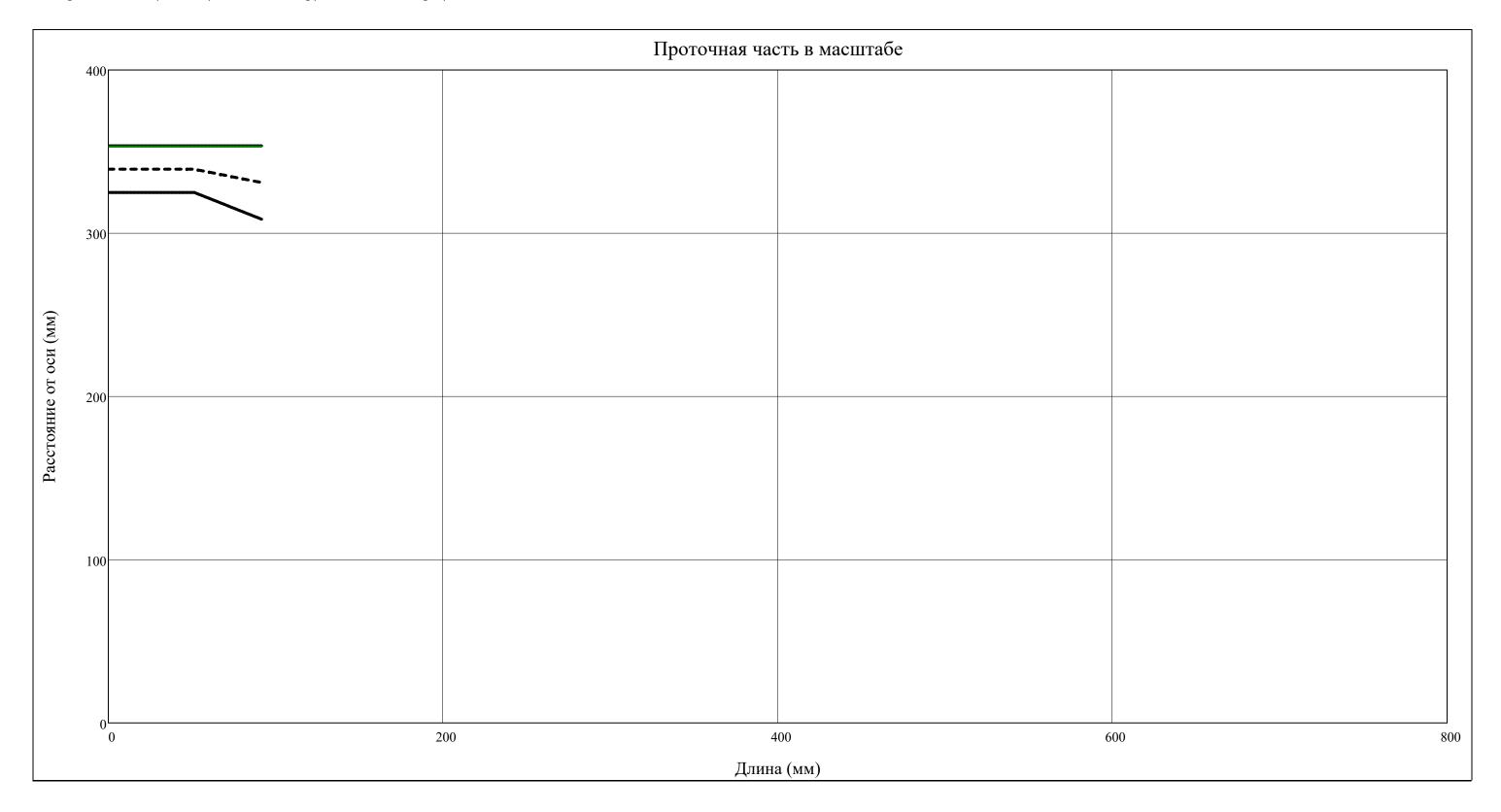
$\gamma_{\text{TIII}} = T > -12.$		1	2	
^ү ПЧкор > -12. –	1	1	0	
$\gamma_{\text{TIII}} > -15^{\circ} =$		1	2	
¹ ПЧкор > -13. –	1	1	0	

$$\begin{pmatrix} x_{\Pi \mathbf{q}} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \end{pmatrix} = \begin{vmatrix} c = 1 \\ x_{\Pi \mathbf{q}_c} = 0 \\ y_{\Pi \mathbf{q} nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_c} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), nep} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), nep} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), 1} \\ \text{for } i \in 1 ... \mathbf{Z} \\ \begin{vmatrix} c = c + 1 \\ x_{\Pi \mathbf{q}_c} = x_{\Pi \mathbf{q}_{c-1}} + 0.5 \cdot \Delta_{\mathbf{a}_i} + B_{\mathbf{C}} \mathbf{A}_i + 0.5 \cdot \Delta_{\mathbf{a}_i} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{vmatrix} = \begin{pmatrix} D_{st(i,2), N_r} \\ D_{st(i,2), 1} \end{pmatrix} \\ y_{J nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_i} \\ c = c + 1 \\ x_{\Pi \mathbf{q}_c} = x_{\Pi \mathbf{q}_{c-1}} + 0.5 \cdot \Delta_{\mathbf{a}_i} + B_{\mathbf{p}} \mathbf{K}_i + 0.5 \cdot \Delta_{\mathbf{a}_i} \\ \begin{pmatrix} y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{pmatrix} = \begin{pmatrix} D_{st(i+1,1), N_r} \\ D_{st(i+1,1), 1} \\ D_{st(i+1,1), 1} \end{pmatrix} \\ y_{J nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_i} \\ \begin{pmatrix} x_{\Pi \mathbf{q}} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{pmatrix} = \begin{pmatrix} T_{st(i+1,1), N_r} \\ T_{st(i+1,1), N_r} \\ T_{st(i+1,1), 1} \end{pmatrix} \\ y_{J nep_c} = y_{J \mathbf{q} nep_c} - \Delta_{r_i} \\ \begin{pmatrix} x_{\Pi \mathbf{q}} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{J \mathbf{q} nep_c} \end{pmatrix} = \begin{pmatrix} T_{st(i+1,1), N_r} \\ T$$

Length =
$$\sum_{i=1}^{Z} B_{CA_i} + \sum_{i=1}^{Z} \Delta_{a_i} + \sum_{i=1}^{Z} B_{PK_i} = 81.3 \cdot 10^{-3}$$

$$x = \min(x_{\Pi Y}), \min(x_{\Pi Y}) + \frac{\max(x_{\Pi Y}) - \min(x_{\Pi Y})}{N_{dis}} ... \max(x_{\Pi Y})$$

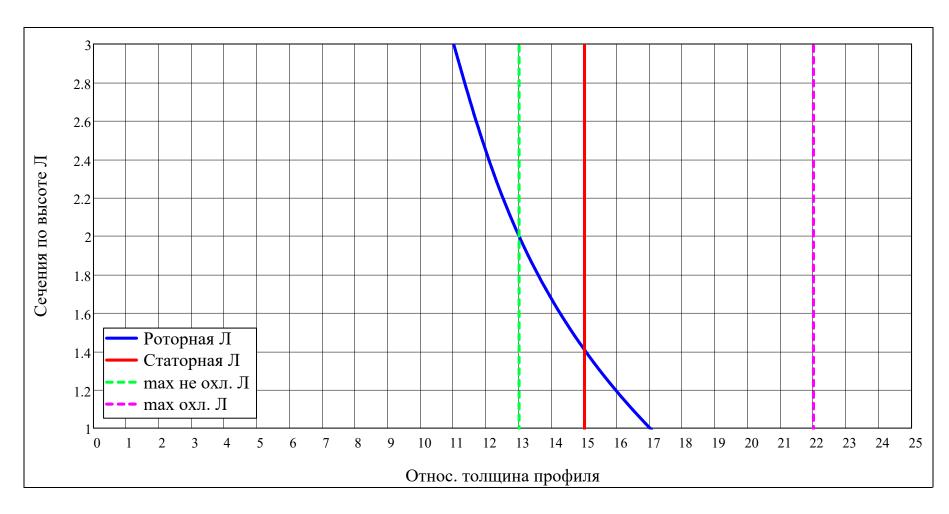
 $\begin{aligned} y_{\Pi \Pi nep}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi nep}, l\Big) & y_{\Pi \Pi cp}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi cp}, l\Big) & y_{\Pi \Pi kop}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi kop}, l\Big) \\ y_{\Pi nep}(l) &= interp\Big(cspline\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi nep}\Big), x_{\Pi \Pi}, 0.5 \cdot y_{\Pi nep}, l\Big) \end{aligned}$



Относ. толщины ЛРК и СА:

$$\overline{c}_{stator.}(r) = \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 15 \\ 15 \\ 15 \end{bmatrix}, \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 15 \\ 15 \\ 15 \end{bmatrix}, w, r \end{bmatrix} \text{ if } T_{JI.JQOII} < T^*_{\Gamma} \\ \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ 11 \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ N_r \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ 11 \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ N_r \end{bmatrix}, w, r \end{bmatrix} \text{ otherwise}$$

$$\overline{c}_{rotor.}(r) = \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 17 \\ 13 \\ 11 \end{bmatrix}, \begin{bmatrix} 17 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 17 \\ 13 \\ 11 \end{bmatrix}$$



$$\begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor}
\end{bmatrix} = \begin{bmatrix}
for & i \in 1...Z \\
for & r \in 1...N_r
\end{bmatrix}$$

$$\begin{bmatrix}
\overline{c}_{stator}_{i,r} \\
\overline{c}_{rotor}_{i,r}
\end{bmatrix} = \begin{bmatrix}
\overline{c}_{stator.(r)} \\
\overline{c}_{rotor.(r)}
\end{bmatrix}$$

$$\begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor}
\end{bmatrix}$$

$$\frac{1}{c_{\text{stator}}}^{T} = \begin{vmatrix}
 & 1 \\
1 & 15.00 \\
2 & 15.00 \\
3 & 15.00
\end{vmatrix} .\%$$

$$\frac{T}{c_{rotor}} = \begin{vmatrix}
 & 1 & \\
1 & 17.00 \\
2 & 13.00 \\
3 & 11.00
\end{vmatrix}$$

$$\frac{T}{r} = \begin{bmatrix}
 & 1 & \\
 & 1 & 6.000 \\
 & 2 & 6.000 \\
 & 3 & 6.000
\end{bmatrix}$$

$$\frac{T}{r_outlet_{stator}}^{T} = \begin{bmatrix} & 1 \\ 1 & 3.000 \\ 2 & 3.000 \\ \hline 3 & 3.000 \end{bmatrix} .\%$$

$$\frac{T}{r_inlet_{rotor}}^{T} = \begin{bmatrix}
 & 1 \\
 & 1 & 5.950 \\
 & 2 & 4.550 \\
 & 3 & 3.850
\end{bmatrix}$$
.%

$$\frac{T}{r_outlet_{rotor}}^{T} = \begin{bmatrix}
 & 1 \\
1 & 2.550 \\
2 & 1.950 \\
3 & 1.650
\end{bmatrix} .\%$$

▲ Относ. толщины и радиусы профилей

$$R_{L.cp} = \begin{pmatrix} 0.16 & \text{if turbine} = \text{"TBД"} & 0.15 & 0.18 & 0.185 & 0.5 & 0.5 \\ 0.13 & \text{otherwise} & 0.18 & 0.18 & 0.185 & 0.5 & 0.5 \end{pmatrix}^{T}$$

▼ Поступенчатый расчет ОТ

```
(iteration<sub>CA</sub> iteration<sub>PK</sub>
                              R_{L}
         \frac{\mathbf{k}}{\mathbf{w}}
      H^*_{ct}
                             H_{cT}
    H_{\rm stator}
                           H_{rotor}
                             w<sub>ад</sub>
        сад
         P*
                               P
                               T_{\infty}
         <u>G</u>
                                \mathbf{V}
         ρ*
                                ρ
       <u>Q</u>
                             \boldsymbol{\alpha}_{ox}
                                β
         \alpha
     \epsilon_{
m stator}
                           \epsilon_{
m rotor}
     \theta_{\text{CA}}
                             \theta_{PK}
    g<sub>охл</sub>са
                          g<sub>охл</sub>рк
       a*c
                             a*w
       Тад
                             Тад
                             T^*_{\mathbf{w}}
        a_{3B}
                              a_{3B}
                                u
                                c
                              c_{u}
                               \mathbf{W}
                              \mathbf{w}_{\mathbf{u}}
        w_a
                              M_{c}
                                               = | r = av(N_r)
                             M_{W}
        \lambda_{
m W}
                                                      for i \in 1..Z
                           v_{
m rotor}
     v_{
m stator}
                                                         trace(concat("ступень i = "_num2str(i)))
```

chordstator	chordrotor	if	i = 1
^t oπTCA	т _{опт} РК		$\alpha_{\text{ox}_{\text{st}(i,1)}} = \alpha_{\text{ox}}$
t _{stator}	t _{rotor}		$k_{st(i,1),r} = k_{\Gamma}$
Z _{stator}	Z _{rotor}		$P^*_{st(i,1),r} = P^*_{\Gamma}$
$\overline{v}_{ m stator}$	$\overline{v}_{ m rotor}$		$P^*_{W_{st(i,1),r}} = 0$
ξ _{TpCA}	ξ _{TpPK}		
ξ _{кр} СА	ξкрРК		$P_{st(i,1),r} = P_{\Gamma}$
ξ _{ReCA}	ξ _{RePK}		$T^*_{st(i,1),r} = T^*_{\Gamma}$
$\xi_{\lambda CA}$	$\xi_{\lambda PK}$		$T^*_{W_{St(i,1),r}} = 0$
$\xi_{\Pi pCA}$	$\xi_{\Pi p P K}$		$T_{st(i,1),r} = T_{\Gamma}$
$\xi_{ m BTCA}$	ξ_{BTPK}		$v_{st(i,1),r} = \frac{R_{ras}(\alpha_{ox_{st(i,1)}}, Fuel) \cdot T_{st(i,1),r}}{P_{st(i,1),r}}$
ξ _{тд} СА	ξ _{тдРК}		$P_{st(i,1),r}$
ξ _{см} СА	ξсмРК		$G_{st(i,1)} = G_{\Gamma}$
$\xi_{\Delta r}$	$\xi_{ m BMX}$		$c_{st(i,1),r} = c_{\Gamma}$
ξ _{Τp.Β}	ξ _{Tp.B}		$\alpha_{\mathrm{st}(i,1),r} = \alpha_{\Gamma}$
L _{ct}	LucT		$\begin{pmatrix} c_{\mathbf{u}_{\mathrm{st}(i,1),r}} \end{pmatrix} \qquad \begin{pmatrix} \cos(\alpha_{\mathrm{st}(i,1),r}) \end{pmatrix}$
η _{мощь}	η _{ποπ}		$ \begin{pmatrix} c_{u_{st(i,1),r}} \\ c_{a_{st(i,1),r}} \end{pmatrix} = c_{st(i,1),r} \cdot \begin{pmatrix} \cos(\alpha_{st(i,1),r}) \\ \sin(\alpha_{st(i,1),r}) \end{pmatrix} $
$\eta^*_{ m cT}$	$\eta^*_{ ext{c}_{ ext{T}}}$		$\mathbf{w}_{st(i,1),r} = 0$
η_{u1}	η_{u2}		$\sqrt{k_{st(i,1),r} \cdot R_{\Gamma a3} (\alpha_{oX_{ot(i,1)}}, Fuel) \cdot T_{st(i,1),r}}$
ξCA	ξ _{PK}		$\begin{bmatrix} a_{3B} \\ st(i,1),r \end{bmatrix} \qquad \begin{bmatrix} v \\ 2\cdot k_{st(i,1)}, r \end{bmatrix}$
Lu _{нагрузка}	Lu _{нагрузка}		$\begin{vmatrix} a^*c_{st(i,1),r} \end{vmatrix} = \sqrt{\frac{-2st(i,1),i}{1+k_{st(i,1),r}}} \cdot R_{ra3} \left(\alpha_{ox_{st(i,1)}}, Fuel\right) \cdot T^*_{st(i,1)}$
			$ \begin{pmatrix} a_{3B}_{st(i,1),r} = 0 \\ a^*_{st(i,1),r} \\ a^*_{c_{st(i,1),r}} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,1),r} \cdot R_{\Gamma a3}(\alpha_{oX_{st(i,1)}}, Fuel) \cdot T_{st(i,1),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,1),r}}{1 + k_{st(i,1),r}} \cdot R_{\Gamma a3}(\alpha_{oX_{st(i,1)}}, Fuel) \cdot T^*_{st(i,1)}} \\ \sqrt{\frac{2 \cdot k_{st(i,1),r}}{1 + k_{st(i,1),r}} \cdot R_{\Gamma a3}(\alpha_{oX_{st(i,1)}}, Fuel) \cdot T^*_{w_{st(i,1)}}} \\ \begin{pmatrix} \lambda_{c_{st(i,1),r}} \\ \lambda_{c_{st(i,1),r}} \end{pmatrix} = \begin{pmatrix} \frac{c_{st(i,1),r}}{1 + k_{st(i,1),r}} \\ \sqrt{\frac{c_{st(i,1),r}}{1 + k_{st(i,1),r}}} \end{pmatrix} $
			$ \begin{pmatrix} \lambda_{c} \\ \lambda_{W} \\ st(i,1),r \end{pmatrix} = \begin{pmatrix} \frac{cst(i,1),r}{a^{*}c} \\ \frac{cst(i,1),r}{a^{*}c} \end{pmatrix} = \begin{pmatrix} \frac{cst(i,1),r}{a^{*}c} \\ 0 \end{pmatrix} $ $ \begin{pmatrix} M_{c} \\ st(i,1),r \end{pmatrix} = \frac{1}{a_{3B} \\ st(i,1),r} \cdot \begin{pmatrix} cst(i,1),r \\ W_{st}(i,1),r \end{pmatrix} $
			$\begin{bmatrix} \lambda_{\mathbf{W}} \\ \mathbf{st}(\mathbf{i}, 1), \mathbf{r} \end{bmatrix} \begin{bmatrix} \mathbf{st}(1, 1), \mathbf{r} \\ 0 \end{bmatrix}$
			$\begin{bmatrix} M_{c_{st(i,1),r}} \\ M \end{bmatrix} = \frac{1}{c_{st(i,1),r}} $
			$\begin{bmatrix} M_{W_{ct(i,1)},r} \end{bmatrix}$ $a_{3B_{st(i,1)},r} \begin{bmatrix} W_{st(i,1)},r \end{bmatrix}$

, 1), r (i,1),r $\begin{bmatrix} M_{W_{st(i,1),r}} - a_{3B_{st(i,1),r}} \\ w_{st(i,1),r} \end{bmatrix}$ $iteration_{CT_{i}} = 0$ while 1 > 0 $iteration_{CT_{i}} = iteration_{CT_{i}} + 1$

$$\begin{aligned} & \operatorname{trace} \left(\operatorname{concat} \left(" & \operatorname{iteration.cr} = " , \operatorname{num2str} (\operatorname{iteration.cr}_{CT_i}) \right) \right) \\ & H_{CT_i} = N_{CT_i} \cdot \left| \frac{1}{G_{st(i,1)} \cdot 0.9} & \operatorname{if} \left(\operatorname{iteration.cr}_{CT_i} = 1 \right) \right| \\ & = \frac{1}{\operatorname{mean} \left(G_{st(i,2)}, G_{st(i,3)} \right) \cdot \eta_{\text{Month}}} & \operatorname{otherwise} \end{aligned}$$

$$R_{L_{i,r}} = R_{L.cp_i}$$

$$c_{a,T_{st(i,1),r}} = \sqrt{2 \cdot H_{cT_i}} \\ H_{stator_i} = H_{cT_i} \cdot \left(1 - R_{L_{i,r}} \right) \\ c_{a,T_{st(i,2),r}} = \sqrt{2 \cdot H_{stator_i}} \\ v_{stator_i} = 1 \\ \operatorname{iteration.}_{CA_i} = 0 \end{aligned}$$
 while $1 > 0$
$$\left| \operatorname{iteration.}_{CA_i} = 0 \right| \\ \operatorname{while} 1 > 0 \\ \left| \operatorname{iteration.}_{CA_i} = \frac{1}{v_{stator_i}} \cdot \operatorname{ca.}_{x_{t(i,2),r}} \\ \theta_{CA_i} = \theta_{LMY \circ HHA} \left(T^*_{st(i,1),r}, T^*_{cooling}, T.J._{JOH} \right) \right) \\ c_{st(i,2),r} = \overline{v}_{stator_i} \cdot \operatorname{ca.}_{x_{t(i,2),r}} \\ \theta_{CA_i} = \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} \quad \operatorname{if} \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} \geq 0 \\ g_{oxn.CA_i} = \frac{0.035 \cdot \theta_{CA_i}}{0 \quad \operatorname{otherwise}} \\ G_{st(i,2)} = G_{st(i,1)} \cdot \left(1 + g_{oxn.CA_i} \right) \\ \alpha_{ox_{st(i,2)}} = \alpha_{ox_{st(i,1)}} + g_{oxn.CA_i} \\ \alpha_{ox.CA_i} = \operatorname{mean} \left(\alpha_{ox_{st(i,1)},r} \cdot \alpha_{ox_{st(i,2)}} \right) \\ k_{st(i,2),r} = k_{st(i,1),r} \\ k_{t(i,2),r} = k_{st(i,1),r} \\ v_{hilo} = 1 > 0 \\ k_{CA_i} = \operatorname{mean} \left(k_{st(i,1),r}, k_{st(i,2),r} \right) \\ H_{stator_i} \\ T_{a,T_{st(i,2),r}} = T^*_{st(i,1),r} - \frac{H_{stator_i}}{k_{CA_i}} \\ k_{CA_i} - 1 \cdot R_{ra3.cp} \left(\alpha_{ox_{st(i,1)},r}, \alpha_{ox_{st(i,2)},r} \right) \\ k_{CA_i} \\ \end{array}$$

$$\left[\begin{array}{c} \frac{\sqrt{\gamma_{1}}}{P_{at(i_{1},2),\tau}} = P^{a}_{at(i_{1},1),\tau} \left(\frac{T_{ad}_{at(i_{2},2),\tau}}{T^{a}_{at(i_{1},1),\tau}} \right) \\ + \frac{H_{stator_{i}} \left(\overline{v}_{stator_{i}} \right)^{2}}{k_{CA_{i}} - 1} \cdot \frac{H_{stator_{i}} \left(\overline{v}_{stator_{i}} \right)^{2}}{k_{c}} \cdot \frac{H_{stator_{i}} \left(\overline{v}_$$

$$\begin{cases} c_{x}^{-1} x_{1}(i,2),r \\ c_{x}^{-1} x_{2}(i,2),r \\ c_{x}^{-1} x_{3}(i,2),r \\ c_{x}^{-1} x_{4}(i,2),r \\ c_{x}^{-1} x_$$

$$\begin{vmatrix} \operatorname{cril} \left(\frac{\operatorname{articant}(\operatorname{adit}(1,1), \operatorname{cr}, \operatorname{adit}(2,1), \operatorname{cr})}{\operatorname{Correct}_{S}} \right) + 1 & \operatorname{otherwise} \\ \\ \text{for re 1...} N_r \\ \\ \frac{\operatorname{tricant}(\operatorname{adit}(1,1), \operatorname{cr}, \operatorname{adit}(2,1,r))}{\operatorname{Zuthor}_{I}} \\ \\ \frac{\operatorname{capCA}_{I}}{\operatorname{EspCA}_{I}} = \frac{\operatorname{Esponse}(\operatorname{Out(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{Zuthor}_{I}} \\ \\ \frac{\operatorname{CapCA}_{I}}{\operatorname{EspCA}_{I}} = \frac{\operatorname{Esponse}(\operatorname{Out(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{Eult(2,1)}} \\ \\ \frac{\operatorname{CapCA}_{I}}{\operatorname{EspCA}_{I}} = \frac{\operatorname{Esponse}(\operatorname{Out(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{Eult(2,1)}} \\ \\ \frac{\operatorname{CapCA}_{I}}{\operatorname{EspCA}_{I}} = \frac{\operatorname{Esponse}(\operatorname{Cout(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{EupCA}_{I}} \\ \\ \frac{\operatorname{EupCA}_{I}}{\operatorname{EupCA}_{I}} = \frac{\operatorname{Esponse}(\operatorname{Cout(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{EupCA}_{I}} \\ \\ \frac{\operatorname{EupCA}_{I}}{\operatorname{EupCA}_{I}} = \frac{\operatorname{Eupconse}(\operatorname{Cout(1,1)}, \operatorname{codit}(2,1,r))}{\operatorname{EupCA}_{I}} \\ \\ \frac{\operatorname{EupCA}_{I}}{\operatorname{EupCA}_{I}} \\ \\ \frac{\operatorname{Eup$$

$$\begin{split} &\theta_{PK_i} = \theta_{\text{ENYDGMHa}} \left(T^*_{w_{st(i,2),r}}, T^*_{cooling}, T_{JL,\text{ROT}} \right) \\ &g_{\text{OXnPK}_i} = \begin{vmatrix} 0.035 \cdot \theta_{PK_i} \\ 1 - \theta_{PK_i} \end{vmatrix} \text{ if } \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} \ge 0 \\ &0 \text{ otherwise} \end{vmatrix} \ge 0 \\ &G_{st(i,3)} = G_{st(i,2)} \cdot \left(1 + g_{\text{OXnPK}_i} \right) \\ &\alpha_{OX_{st(i,3)}} = \alpha_{OX_{st(i,2)}} + g_{\text{OXnPK}_i} \\ &k_{st(i,3),r} = k_{st(i,2),r} \\ &k_{pK_i} = mean \left(k_{st(i,2),r}, k_{st(i,3),r} \right) \\ &T_{aT_{st(i,3),r}} = T_{st(i,2),r} - \frac{H_{rotor_i}}{\frac{k_{PK_i}}{k_{PK_i} - 1}} \cdot R_{ras,cp} \left(\alpha_{OX_{st(i,2)}}, \alpha_{OX_{st(i,3)}}, Fucl \right) \\ &P_{st(i,3),r} = P_{st(i,2),r} - \frac{\left(x_{st(i,3),r} \right)^2 - \left(x_{st(i,2),r} \right)^2 - \left(x_{st(i,3),r} \right)^2 + \left(x_{st(i,2),r} \right)^2}{2 \cdot \frac{k_{PK_i}}{k_{PK_i} - 1}} \cdot R_{ras,cp} \left(\alpha_{OX_{st(i,3)}}, Fucl \right) \\ &Cp_3 = Cp_{ras} \left(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{OX_{st(i,3)}}, Fucl \right) \\ &k' = k_{ad} \left(Cp_3, R_{ras} \left(\alpha_{OX_{st(i,3)}}, Fucl \right) \right) \\ &k' = k_{ad} \left(Cp_3, R_{ras} \left(\alpha_{OX_{st(i,3)}}, Fucl \right) \right) \\ &k' = k_{st(i,3),r} = k' \\ &k_{st(i,3)} = k' \\ &k_{st(i,3),r} = asin \left(\frac{G_{st(i,3)}, V_{st(i,3),r}}{W_{st(i,3),r}, F_{st(i,3),r}} \right) - u_{st(i,3),r} \\ &c_u \\ &c_$$

$$\begin{cases} \left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right) & \left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right)^{2} \left(\left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right)^{2} \right) \\ \left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right) & \left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right)^{2} - \left(\sum_{s_{4}(i,3),r}^{s_{4}(i,3),r} \right)^{2} \\ \left(\sum_{s_{3}(i,3),r}^{s_{4}(i,3),r} \right) & \left(\sum_{s_{4}(i,3),r}^{s_{4}(i,3),r} \right) \\ \left(\sum_{s_{4}(i,3),r}^{s_{4}(i,3),r} \right) & \left(\sum_{s_{4}(i,3),r}^{s_{4}(i,3),r} \right) \\ \left(\sum_{s_{4}(i,3),r}^{$$

$$\begin{vmatrix} \lambda_{\text{vol}(1,3),\tau} \\ - \frac{\lambda_{\text{vol}(1,3),\tau}}{n^*} \\ - \frac{\lambda_{\text{wol}(1,3),\tau}}{n^*} \\ - \frac{\lambda_{\text{pol}(1,3),\tau}}{n^*} \\ - \frac{\lambda_{\text{po$$

$$\begin{vmatrix} \frac{1}{U_{TOLOT_i}} &= \int_{I-\xi_{CMP}K_i^-} \xi_{r_iP}K_i^- - \xi_{r_iP}K_i^-} \xi_{r_iP}K_i^- \xi_{r_iP}K_i^-} \\ Lu_{CT_i} &= c_{I_{MI(1,2)_i}} v_{MI(1,2)_i} r^+ c_{I_{MI(1,3)_i}} v_{MI(1,3)_i} r^- v_{MI(1,3)_i} r^- v_{MI(1,3)_i} r^- v_{MI(1,3)_i} r^- v_{MI(1,3)_i} r^- v_{MI(1,2)_i} r^-$$

$$\left| H^*_{cT_{\hat{i}}} = Cp_{\Gamma a3.cp} \left(P_{st(i,1),r}, P_{st(i,3),r}, T_{st(i,1),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,1)}}, \alpha_{ox_{st(i,3)}}, Fuel \right) \cdot T^*_{st(i,1),r} \cdot \left[1 - \left(\pi^*_{cT_{\hat{i}}} \right)^{\frac{-r}{k_{cp}}} \right] \right]$$

$$\left| \eta^*_{cT_{\hat{i}}} = \frac{L_{cT_{\hat{i}}}}{H^*_{cT_{\hat{i}}}} \right|$$

for $i \in 1...Z$

for $j \in 1...3$

$$\begin{split} \rho^*_{st(i,j),r} &= \frac{P^*_{st(i,j),r}}{R_{\Gamma a3} \left(\alpha_{oX_{st(i,j)}}, \operatorname{Fuel}\right) \cdot T^*_{st(i,j),r}} \\ \rho_{st(i,j),r} &= \left(v_{st(i,j),r}\right)^{-1} \\ \left(\varepsilon_{stator_{i,av\left(N_{r}\right)}}\right) &= \left(\alpha_{st(i,2),av\left(N_{r}\right)}^{-\alpha} - \alpha_{st(i,1),av\left(N_{r}\right)}^{-\alpha} \right) \\ \varepsilon_{rotor_{i,av\left(N_{r}\right)}}\right) &= \left(\beta_{st(i,3),av\left(N_{r}\right)}^{-\alpha} - \beta_{st(i,2),av\left(N_{r}\right)}^{-\alpha}\right) \end{split}$$

(iteration_{CA} iteration_{PK}

$$H^*_{cT}$$
 H_{cT}

$$c_{a\pi}$$
 $w_{a\pi}$

$$\varepsilon_{
m stator}$$
 $\varepsilon_{
m rotor}$

$$\theta_{\text{CA}}$$
 θ_{PK}

$g_{\text{ОХЛ}\text{CA}}$ $g_{\text{ОХЛ}\text{PK}}$

$$T_{a \perp}$$
 $T_{a \perp}$

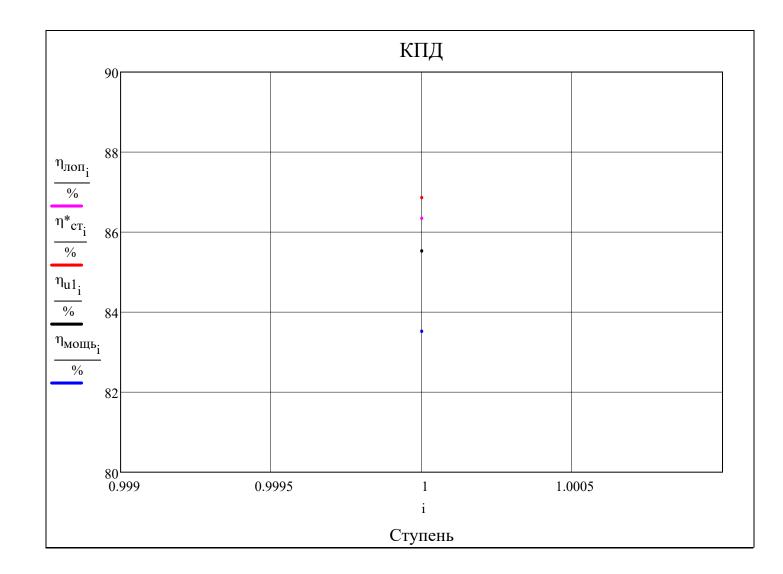
$$P_{W}^{*}$$
 T_{V}^{*}

$$a_{3B}$$
 a_{3I}

$$c_a$$
 c_u

w	W
w _a	$\mathbf{w}_{\mathbf{u}}$
$\lambda_{\rm c}$	M_{c}
λ_{w}	$ m M_W$
v _{stator}	$v_{ m rotor}$
chord _{stator}	
-toптCA	т toптРК
t _{stator}	trotor
Z _{stator}	Z _{rotor}
$\overline{v}_{\mathrm{stator}}$	$\overline{v}_{ m rotor}$
ξ_{TpCA}	ξ_{TpPK}
ξ_{kpCA}	ξ_{KPPK}
ξReCA	^ξ RePK
$\xi_{\lambda CA}$	$\xi_{\lambda PK}$
$\xi_{\Pi pCA}$	$\xi_{\Pi p P K}$
ξ_{BTCA}	ξ_{BTPK}
ξ _{тд} СА	$\xi_{TДPK}$
ξ _{cm} CA	ξ_{cMPK}
$\xi_{\Delta r}$	$\xi_{ m BMX}$
ξ _{Тр.В}	$\xi_{\mathrm{Tp.B}}$
L _{cT}	Lu_{CT}
η _{мощь}	$\eta_{ extit{JOH}}$
η^*_{cT}	η^*_{cT}
η_{u1}	η_{u2}
ξCA	$\xi_{ m PK}$
\Lu _{нагрузка}	Lu _{нагрузка}

▼ Параметры турбинь



$$\eta_{\Pi O \Pi}^{\quad T} = \boxed{ \begin{array}{c|c} 1 \\ 1 \\ 86.35 \end{array}} \cdot \%$$

$$\operatorname{stack}\!\left(\eta_{u1}^{T},\eta_{u2}^{T}\right) = \begin{array}{|c|c|c|c|}\hline & 1 \\ \hline 1 & 85.54 \\ \hline 2 & 86.83 \\ \hline \end{array} \cdot \%$$

$$\eta_{\text{MOIЦb}}^{T} = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 83.53 \end{array}} \cdot \%$$

$$\eta_{\text{MOIII}_{i}} \leq \eta_{u1_{i}} \leq \eta^{*}_{cT_{i}} \leq \eta_{\text{JO}\Pi_{i}} = 0$$

Теплоперепад по параметрам торможения (Дж/кг):
$$\begin{pmatrix} H^*_T \\ H_T \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^Z & H^*_{cT_i} \\ \vdots & \vdots & \vdots \\ \sum_{i=1}^Z & H_{cT_i} \end{pmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 516.1 \\ 2 & 536.7 \end{bmatrix} \cdot 10^3$$

Мощность T (Вт):
$$\sum_{i=1}^{Z} N_{cT_{i}} = 14.89 \cdot 10^{6}$$
 eps ("rel", N_{T} , $\sum_{i=1}^{Z} N_{cT_{i}}$) = 0.000 · %

Удельная поступенчатая работ а Т [Дж/кг]:
$$L_T = \sum_{i=1}^{Z} \frac{N_{cT_i}}{\text{mean}\big(G_{st(i,2)}, G_{st(i,3)}\big)} = 448.6 \cdot 10^3$$

$$k_{T.cp} = k_{ad} \left(Cp_{\Gamma a3.cp} \left(P_{st(1,1),av(N_r)}, P_{st(Z,3),av(N_r)}, T_{st(1,1),av(N_r)}, T_{st(Z,3),av(N_r)}, \alpha_{ox_{st(1,1)}}, \alpha_{ox_{st(Z,3)}}, Fuel \right), P_{ras.cp} \left(\alpha_{ox_{st(1,1)}}, \alpha_{ox_{st(Z,3)}}, Fuel \right) \right) = 1.289$$

Адиабатный КПДТ:
$$\eta^*_T = \frac{L_T}{H^*_T} = 86.92 \cdot \%$$

Политропический КПД Т:
$$\eta^*_{T,\Pi} = \eta^*_{n} ($$
"расширение", $\eta^*_{T}, \pi^*_{T}, k_{T,cp}) = 85.37 \cdot \%$

$$\text{Мощностной КПДТ:} \qquad \eta_{\text{Тмощь}} = \frac{\displaystyle\sum_{i=1}^{Z} \frac{N_{\text{CT}_{i}}}{\text{mean}\big(G_{\text{st}(i,2)},G_{\text{st}(i,3)}\big)}}{H_{\text{T}}} = 83.58 \cdot \%$$

$$L_{\text{CT}}^{T} = \boxed{ \begin{array}{c|c} 1 \\ \hline 1 & 448.3 \end{array}} \cdot 10^3$$

$H_{om}^{T} =$		1	1.10^3
CT	1	536.7	

$$\operatorname{stack}\left(\mathbf{H}_{\operatorname{stator}}^{\operatorname{T}}, \mathbf{H}_{\operatorname{rotor}}^{\operatorname{T}}\right) = \begin{bmatrix} & 1 \\ 1 & 450.9 \\ 2 & 87.0 \end{bmatrix} \cdot 10^{3}$$

$$submatrix \left(R_L^T, av(N_r), av(N_r), 1, Z \right) = \boxed{\begin{array}{c} 1 \\ 1 \\ \hline \end{array}}$$

$$\operatorname{stack}\!\left(\boldsymbol{\theta}_{CA}^{T},\boldsymbol{\theta}_{PK}^{T}\right) = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 0.432 \\ \hline 2 & 0.206 \\ \hline \end{array}$$

stack
$$\left(g_{\text{OX}}, g_{\text{OX}}, g_{\text{OX}}, g_{\text{OX}}\right) = \begin{bmatrix} 1 & 1 \\ 1 & 26.61 \\ 2 & 9.09 \end{bmatrix} \cdot 10^{-3}$$

$$G_{OXJICA_{i}} = g_{OXJICA_{i}} \cdot G_{st(i,1)}$$

$$G_{\text{OX},PK_i} = g_{\text{OX},PK_i} \cdot G_{\text{st}(i,2)}$$

$$\operatorname{stack}\left(G_{\text{OXJICA}}^{T},G_{\text{OXJIPK}}^{T}\right) = \begin{bmatrix} & 1\\ & 1 & 0.9\\ & 2 & 0.3 \end{bmatrix}$$

$$G_{cooling} = 3.2$$

$$\sum_{i=1}^{Z} G_{\text{oxnCA}_i} + \sum_{i=1}^{Z} G_{\text{oxnCA}_i} \leq G_{\text{cooling}} = 1$$

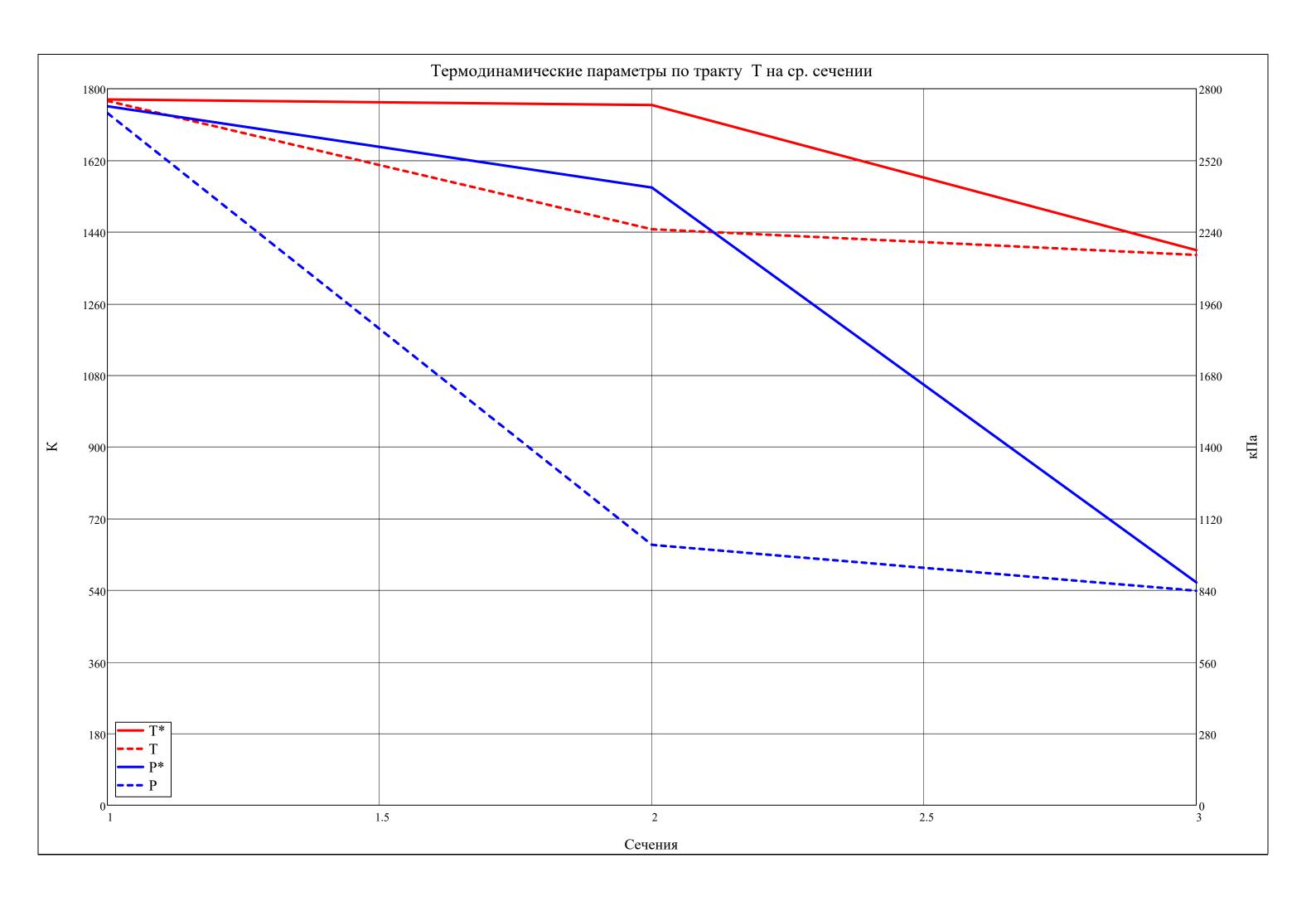
$$stack \left(iteration_{CA}^{T}, iteration_{PK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}$$

submatrix
$$(k^{T}, av(N_{r}), av(N_{r}), 1, 2Z + 1) = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 1.283 & 1.293 & 1.295 \end{bmatrix}$$

submatrix
$$\left(P^{*T}, av(N_r), av(N_r), 1, 2Z + 1\right) = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2731.8 & 2413.7 & 870.5 \end{bmatrix} \cdot 10^3$$

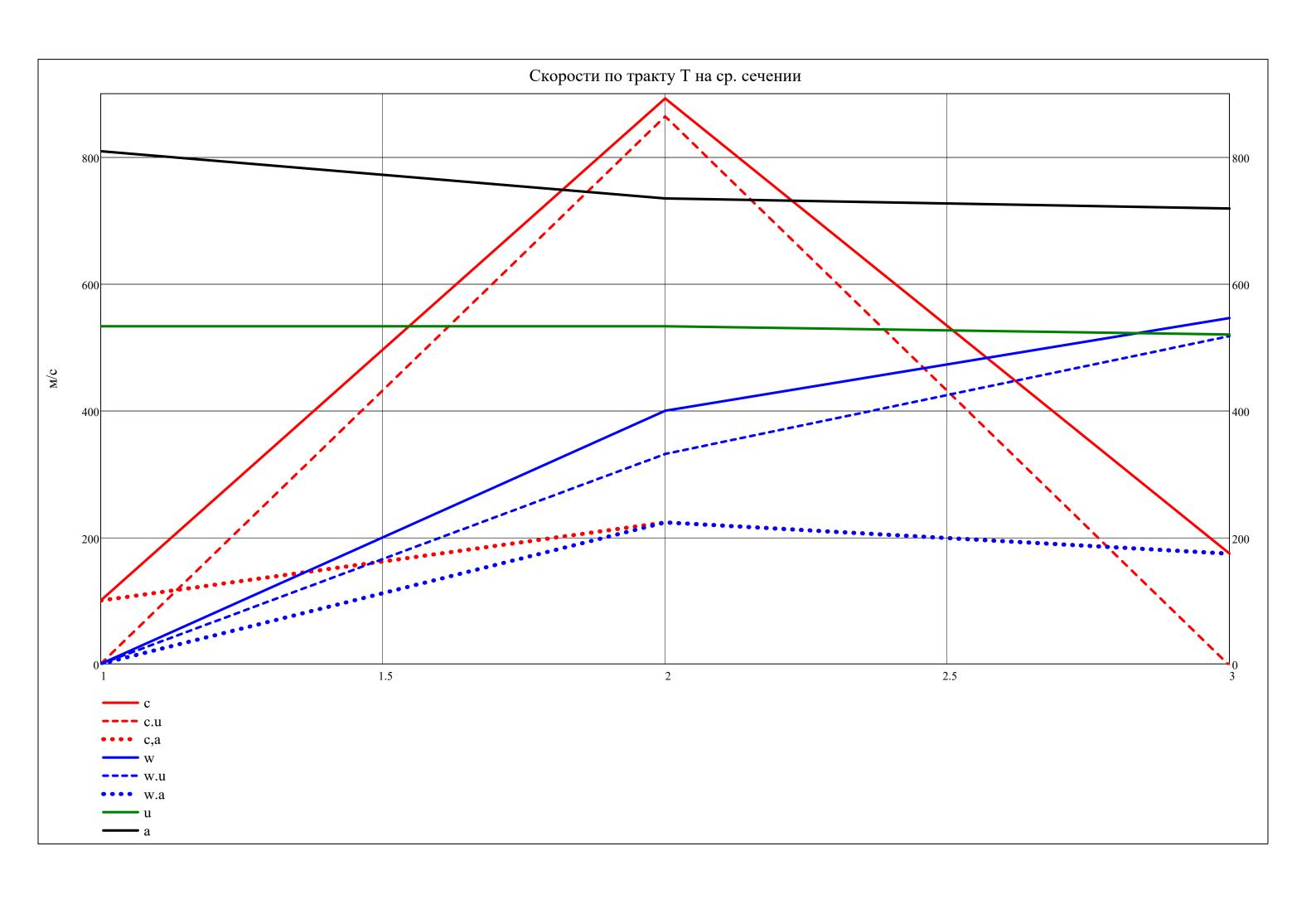
$$\operatorname{submatrix}\left(v^{T},\operatorname{av}\left(N_{r}\right),\operatorname{av}\left(N_{r}\right),1,2Z+1\right) = \begin{array}{|c|c|c|c|c|}\hline 1 & 2 & 3 \\\hline 1 & 0.189 & 0.410 & 0.487 \\\hline \end{array}$$

submatrix
$$\left(\rho^{*^{T}}, av(N_{r}), av(N_{r}), 1, 2Z + 1\right) = \boxed{\begin{array}{c|cccc} 1 & 2 & 3 \\ \hline 1 & 5.341 & 4.756 & 2.164 \end{array}}$$

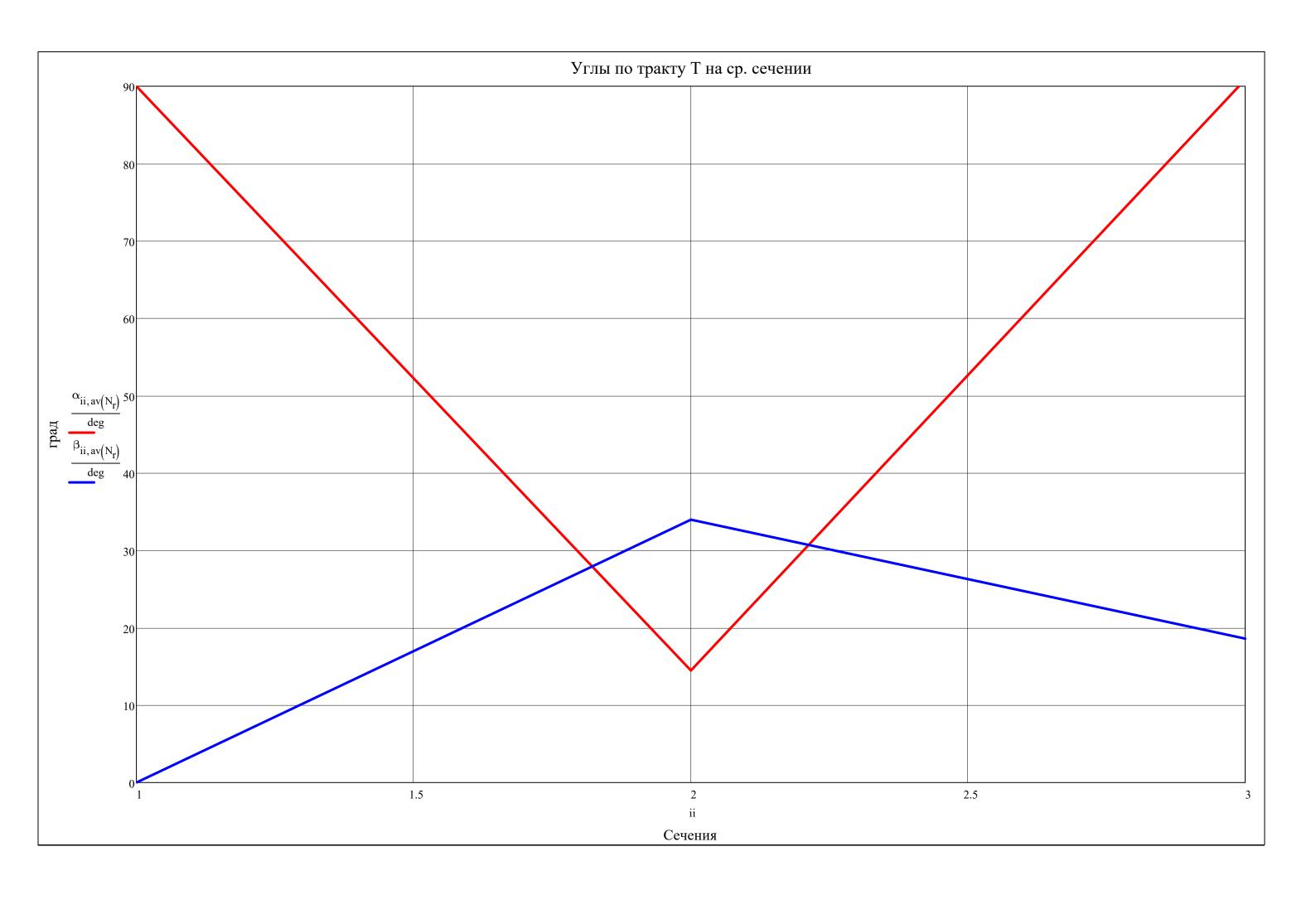


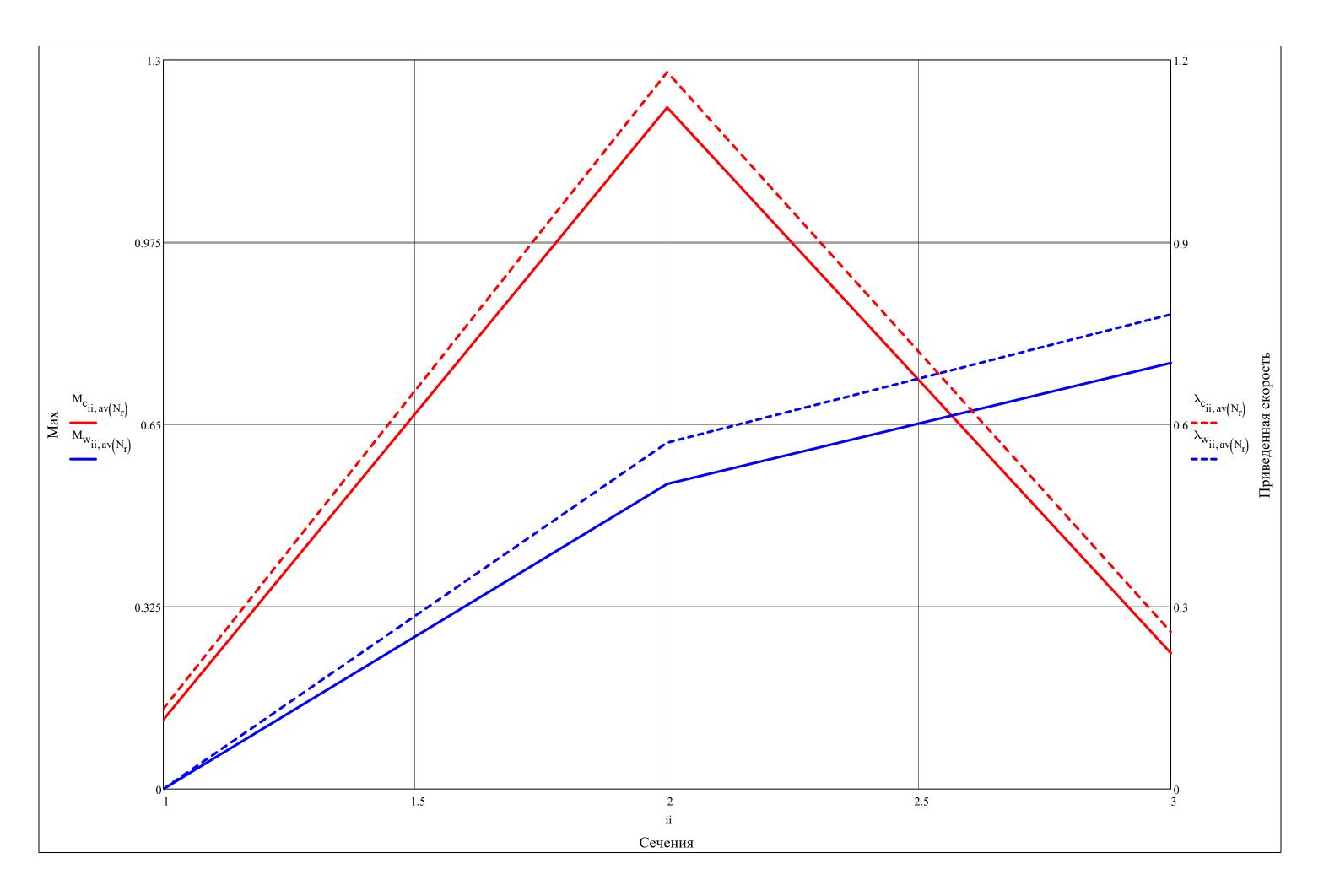
$$\begin{aligned} & \text{submatrix} \bigg(a_{3B}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 809.2 \end{array} }_{734.6} \underbrace{ \begin{array}{c} 3 \\ 718.7 \end{array}}_{734.6} \end{aligned} \\ & \text{submatrix} \bigg(a^*_{c}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 758.2 \end{array} }_{756.5} \underbrace{ \begin{array}{c} 3 \\ 756.5 \end{array} }_{756.5} \underbrace{ \begin{array}{c} 3 \\ 673.8 \end{array}}_{756.5} \end{aligned} \\ & \text{submatrix} \bigg(a^*_{w}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 2 \\ 3 \\ 1 \\ 10.00 \end{array} }_{802.5} \underbrace{ \begin{array}{c} 3 \\ 174.1 \end{array} }_{174.1} \end{aligned} \\ & \text{submatrix} \bigg(c_{u}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 100.0 \end{array} }_{864.2} \underbrace{ \begin{array}{c} 3 \\ -2.7 \end{array} }_{174.1} \end{aligned} \\ & \text{submatrix} \bigg(c_{u}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 100.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 174.0 \end{array} }_{174.0} \end{aligned} \\ & \text{submatrix} \bigg(w_{u}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{239.5} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{331.3} \underbrace{ \begin{array}{c} 3 \\ 517.3 \end{array} }_{517.3} \end{aligned} \\ & \text{submatrix} \bigg(w_{u}^{-T}, av \Big(N_r \big), av \Big(N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c} 3 \\ 2 \\ 3 \\ 1 \\ 0.0 \underbrace{ \begin{array}{c}$$

		1	2	3
$u^T =$	1	510.5	510.5	484.8
•	2	532.9	532.9	520.0
	3	555.2	555.2	555.2



 $\operatorname{submatrix}\left(\varepsilon_{stator}, 1, Z, \operatorname{av}\left(N_{r}\right), \operatorname{av}\left(N_{r}\right)\right)^{T} = \begin{array}{|c|c|c|c|c|c|}\hline 1 & 2 & 3 & 4 & 5 & 6 \\\hline 1 & -75.51 & & & & & \\\hline \end{array}$





$$t_{\text{stator}}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 56.7 \\ 2 & 59.2 \\ 3 & 61.7 \end{bmatrix} \cdot 10^{-3} \qquad t_{\text{rotor}}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 22.4 \\ 2 & 23.7 \\ 3 & 25.0 \end{bmatrix} \cdot 10^{-3}$$

submatrix
$$\left(\text{chord}_{\text{stator}}^T, \text{av}(N_r), \text{av}(N_r), 1, Z \right) = \begin{bmatrix} 1 \\ 1 \\ 68.0 \end{bmatrix} \cdot 10^{-3}$$

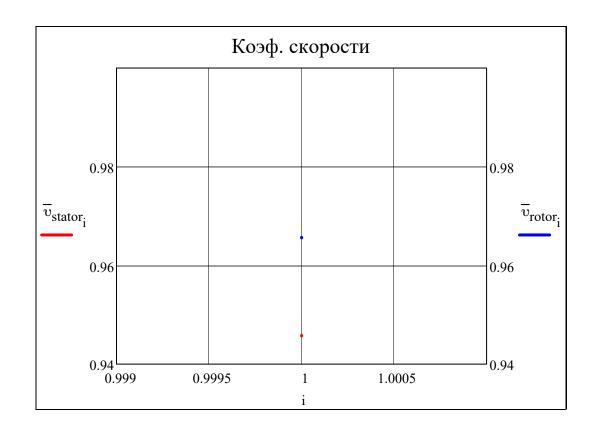
$$submatrix \left(chord_{rotor}^{T}, av(N_r), av(N_r), 1, Z \right) = \boxed{\frac{1}{1 \quad 32.7}} \cdot 10^{-3}$$

$$\operatorname{stack}\left(Z_{\operatorname{stator}}^{\operatorname{T}}, Z_{\operatorname{rotor}}^{\operatorname{T}}\right) = \begin{bmatrix} 1 \\ 1 & 36 \\ 2 & 89 \end{bmatrix}$$

$$stack\left(\overline{t}_{O\Pi TCA}^{T}, \overline{t}_{O\Pi TPK}^{T}\right) = \begin{bmatrix} & 1\\ & 1\\ & 1 & 0.872\\ & 2 & 0.724 \end{bmatrix}$$

$$\frac{t_{stator_{i, av\left(N_{r}\right)}}}{chord_{stator_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{stator_{i, av\left(N_{r}\right)}}}{chord_{stator_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)$$

. (- T - T)		1	
$\operatorname{stack}(v_{\operatorname{stator}}, v_{\operatorname{rotor}}) =$	1	0.9458	
	2	0.9657	



$$stack\left(\xi_{TpCA}^{T},\xi_{TpPK}^{T}\right) = \begin{bmatrix} & 1\\ & 1\\ & 1.398\\ 2 & 2.620 \end{bmatrix}.\%$$

$$stack \left(\xi_{KpCA}^{T}, \xi_{KpPK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ 2.753 \\ 2 \\ 1.689 \end{bmatrix} \cdot \%$$

$$stack \left(\xi_{ReCA}^{T}, \xi_{RePK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ -0.135 \\ 2 \\ 0.085 \end{bmatrix}$$
 .%

$$stack\left(\xi_{\lambda CA}^{T}, \xi_{\lambda PK}^{T}\right) = \begin{bmatrix} 1\\ 1\\ 2.434\\ 2 & 0.024 \end{bmatrix} \cdot \%$$

$$\operatorname{stack}\left(\xi_{\operatorname{BTCA}}^{\operatorname{T}}, \xi_{\operatorname{BTPK}}^{\operatorname{T}}\right) = \begin{array}{|c|c|c|c|}\hline 1 & 1.453 \\ \hline 1 & 1.453 \\ \hline 2 & 0.881 \\ \hline \end{array}$$

$$stack\left(\xi_{TДCA}^{T},\xi_{TДPK}^{T}\right) = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\\hline 1 & 1.856 \\\hline 2 & 1.200 \\\hline \end{array}$$

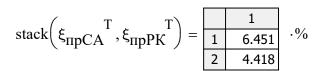
$$stack\left(\xi_{cMCA}^{T}, \xi_{cMPK}^{T}\right) = \begin{bmatrix} 1\\ 1\\ 0.784\\ 2\\ 0.248 \end{bmatrix} \cdot \%$$

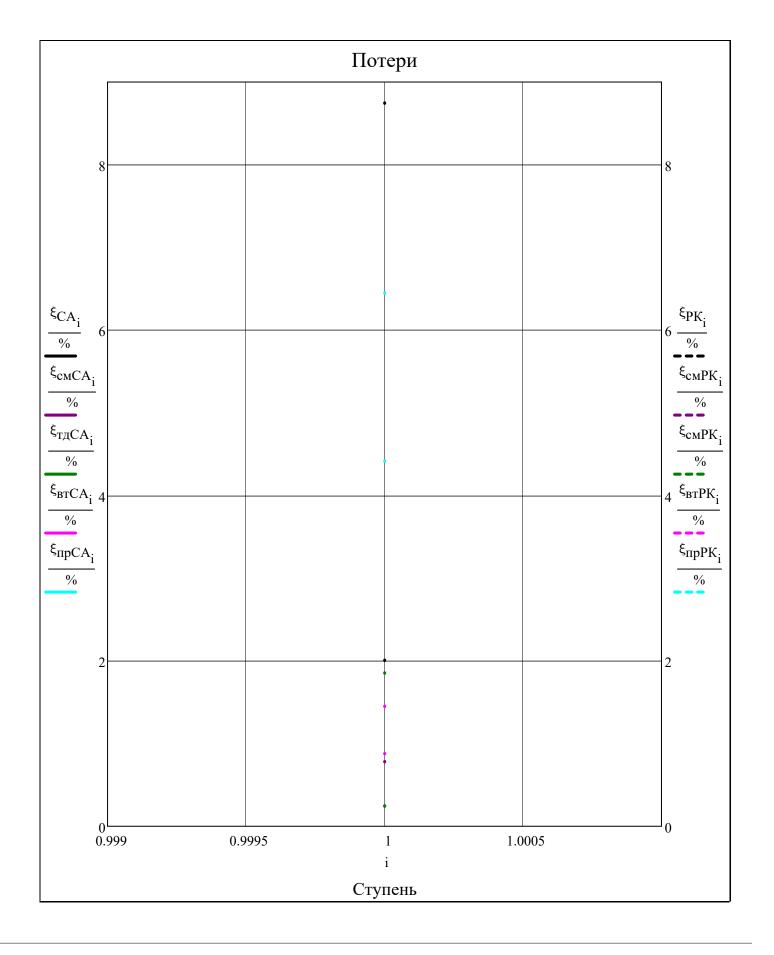
$$\operatorname{stack}\left(\xi_{CA}^{T},\xi_{PK}^{T}\right) = \begin{array}{|c|c|c|c|}\hline & 1 & \\ \hline 1 & 8.748 \\ \hline 2 & 2.008 \\ \hline \end{array}.\%$$

$$\xi_{B b I X}^{\quad T} = \boxed{ \quad \quad 1 \quad \quad } \cdot \%$$

$$\xi_{\Delta r}^{T} = \boxed{\begin{array}{c|c} 1 \\ 1 & 2.476 \end{array}} \cdot \%$$

$$\xi_{Tp.B}^{\quad T} = \boxed{ \begin{array}{c|c} 1 \\ \hline 1 & 0.831 \end{array}} \cdot \%$$





Вывод-результатов поступенчатого расчета-по-ср. сечению-ОТ в EXCEL:

▼ Выбор закона профилирования Л по высоте

$$\mathbf{m} = \begin{pmatrix} \overline{v}_{stator_1} \cdot \cos(\alpha_{st(1,2),av(N_r)})^2 & \text{if } Z = 1 \\ -0.5 & \text{otherwise} \\ & 0 \\ 0.25 \\ & 1 \\ & 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{"}\alpha.2 = const" \\ \text{"}\Gamma = const" \\ \text{"}m = const" \\ \text{"}R = const" \end{pmatrix} = \begin{pmatrix} cos(\alpha_{st(i,2),av(N_r)})^2 \cdot \overline{\upsilon}_{stator_i} \\ 1 \cdot \overline{\upsilon}_{stator_i} \\ 0.2 \\ -1 \cdot \overline{\upsilon}_{stator_i} \end{pmatrix}$$

$\mathbf{m}^{\mathrm{T}} =$		1	2	3	4	5	6
	1	0.8866	-0.2500	0.0000	0.2500	1.0000	1.0000

▲ Выбор закона профилирования Л по высоте

$$\begin{vmatrix} \text{if } m_i = \overline{\upsilon}_{\text{Stator}_i^{-i}} cos\left(Q_{\text{St}(i,2),\text{av}}(N_f)\right)^2 \\ \\ - \left(1 - \frac{\overline{\upsilon}_{\text{St}(i,a),\text{av}}(N_f)}{m_i}\right) \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^{2-m_i}}\right] \\ \\ - \left(c_{a_{\text{St}(i,a),\text{av}}(N_f)}\right)^2 + \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}\right] \\ \\ - \left(c_{a_{\text{St}(i,a),\text{av}}(N_f)}\right)^2 \cdot \dots \\ \\ + \left[1 - \left(\overline{\upsilon}_{\text{rotor}_i}\right)^2\right] \cdot \left[\left(u_{\text{st}(i,a),\text{av}}(N_f)\right)^2 \cdot \left[1 - \left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2\right] - 2 \cdot c_{u_{\text{St}(i,a),\text{av}}(N_f)} \cdot u_{\text{st}(i,a),\text{av}}(N_f)} \cdot \left[1 - \left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{st}(i,a),\text{av}}(N_f)}\right)^{1-m_i}\right] \right] \dots \\ \\ + \left[1 - \left(\overline{\upsilon}_{\text{rotor}_i}\right)^2\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{av}}(N_f)}\right)^2}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{r}}}\right)}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{r}}}}\right]}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{r}}}\right)}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{St}(i,a),\text{r}}}{R_{\text{St}(i,a),\text{r}}}\right)}}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{S$$

for $i \in 1...2 \cdot Z + 1$

for $r \in 1..N_r$

$$\begin{vmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{vmatrix} = c_{i,av(N_r)} \cdot \begin{pmatrix} cos(\alpha_{i,av(N_r)}) \\ sin(\alpha_{i,av(N_r)}) \end{pmatrix} \text{ if } (i = 1)$$

$$P^*_{i,r} = P^*_{i,av(N_r)}$$

$$T^*_{i,r} = T^*_{i,av(N_r)}$$

$$\rho^*_{i,r} = \frac{P^*_{i,r}}{R_{\Gamma 33}(\alpha_{ox_i}, Fuel) \cdot T^*_{i,r}}$$

$$\begin{aligned} k_{i,r} &= k_{ad} \Big(\text{Cp}_{\text{B03dyx}} \big(P^*_{i,r}, T^*_{i,r} \big), R_{\text{ra3}} \Big(\alpha_{\text{OX}_{1}}, \text{Fuel} \big) \Big) \\ a^*_{c_{i,r}} &= \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1}} \cdot R_{\text{ra3}} \Big(\alpha_{\text{OX}_{1}}, \text{Fuel} \big) \cdot T^*_{i,r} \\ \alpha_{i,r} &= \text{triangle} \Big(c_{a_{i,r}}, c_{u_{i,r}} \Big) \\ c_{i,r} &= \frac{c_{i,r}}{\sin(\alpha_{i,r})} \\ \lambda_{c_{i,r}} &= \frac{c_{i,r}}{a^*_{c_{i,r}}} \\ \Big(T^*_{i,r} \big) &= \begin{pmatrix} T^*_{i,r} \cdot T \mathcal{I} \mathcal{D} \Phi \big(T^*, \lambda_{c_{i,r}}, k_{i,r} \big) \\ P^*_{i,r} \cdot T \mathcal{I} \mathcal{D} \Phi \big(T^*, \lambda_{c_{i,r}}, k_{i,r} \big) \\ \rho^*_{i,r} \cdot T \mathcal{I} \mathcal{D} \Phi \big(T^*, \lambda_{c_{i,r}}, k_{i,r} \big) \Big) \\ a_{3B_{i,r}} &= \sqrt{k_{i,r} \cdot R_{\text{ra3}}} \Big(\alpha_{\text{OX}_{i}}, \text{Fuel} \Big) \cdot T_{i,r} \\ M_{c_{i,r}} &= \frac{c_{i,r}}{a_{3B_{i,r}}} \\ \beta_{i,r} &= \text{triangle} \Big(c_{a_{i,r}}, u_{i,r} - c_{u_{i,r}} \Big) \\ w_{i,r} &= \frac{c_{a_{i,r}}}{\sin(\beta_{i,r})} \\ T^*_{w_{i,r}} &= T^*_{i,r} - \frac{\left(c_{i,r} \right)^2 - \left(w_{i,r} \right)^2}{2 \cdot \frac{k_{i,r}}{k_{i,r} - 1}} \cdot R_{\text{ra3}} \Big(\alpha_{\text{OX}_{i}}, \text{Fuel} \Big) \cdot T^*_{w_{i,r}} \\ \lambda_{w_{i,r}} &= \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1}} \cdot R_{\text{ra3}} \Big(\alpha_{\text{OX}_{i}}, \text{Fuel} \Big) \cdot T^*_{w_{i,r}} \\ \lambda_{w_{i,r}} &= \frac{w_{i,r}}{a^*_{w_{i,r}}} \\ M_{w_{i,r}} &= \frac{w_{i,r}}{a^*_{w_{i,r}}} \\ \end{pmatrix}$$

for $i \in 1...Z$

$$\begin{vmatrix} \left(\frac{\Delta c}{\Delta c} a_{st(i,\,1)\,,r} \\ \Delta c a_{st(i,\,2)\,,r} \right) = \begin{pmatrix} c_{st(i,\,2)\,,r} - c_{a_{st(i,\,1)\,,r}} \\ c_{a_{st(i,\,2)\,,r}} - c_{a_{st(i,\,2)\,,r}} - c_{a_{st(i,\,2)\,,r}} \end{vmatrix}$$

$$R_{L_{i,\,r}} = 1 - \frac{c_{u_{st(i,\,2)\,,r}} - c_{u_{st(i,\,3)\,,r}} \\ u_{st(i,\,2)\,,r} + u_{st(i,\,3)\,,r} \\ \varepsilon_{stator_{i,\,r}} = \begin{vmatrix} \alpha_{st(i,\,2)\,,r} - \alpha_{st(i,\,1)\,,r} & \text{if } \alpha_{st(i,\,2)\,,r} \geq \frac{\pi}{2} \\ \alpha_{st(i,\,1)\,,r} - \alpha_{st(i,\,2)\,,r} & \text{otherwise} \end{vmatrix}$$

$$\varepsilon_{rotor_{i,\,r}} = \begin{vmatrix} \beta_{st(i,\,3)\,,r} - \beta_{st(i,\,2)\,,r} & \text{if } \beta_{st(i,\,3)\,,r} \geq \frac{\pi}{2} \\ \beta_{st(i,\,2)\,,r} - \beta_{st(i,\,3)\,,r} & \text{otherwise} \end{vmatrix}$$

$$\begin{pmatrix} P^* & T^* & T & \rho^* & k & a^*_{c} & a_{3B} & c & c_{u} & c_{a} & \Delta c_{a} & \alpha & \lambda_{c} & \lambda_{w} & \varepsilon_{stator} \\ P & T^*_{w} & T & \rho & R_{L} & a^*_{w} & a_{3B} & w & w_{u} & w_{a} & \Delta c_{a} & \beta & M_{c} & M_{w} & \varepsilon_{rotor} \end{pmatrix}^{T}$$

▲ Расчет Л по высоте

▼ Результаты расчета Л по высот

		1	2	3	
$P^{*T} =$	1	2731.8	2413.7	870.5	$\cdot 10^3$
-	2	2731.8	2413.7	870.5	10
	3	2731.8	2413.7	870.5	

		1	2	3	4	5	6	7	8	9
$T^{*T} =$	1	1773.0	1759.0	1394.2						
-	2	1773.0	1759.0	1394.2						
	3	1773.0	1759.0	1394.2						

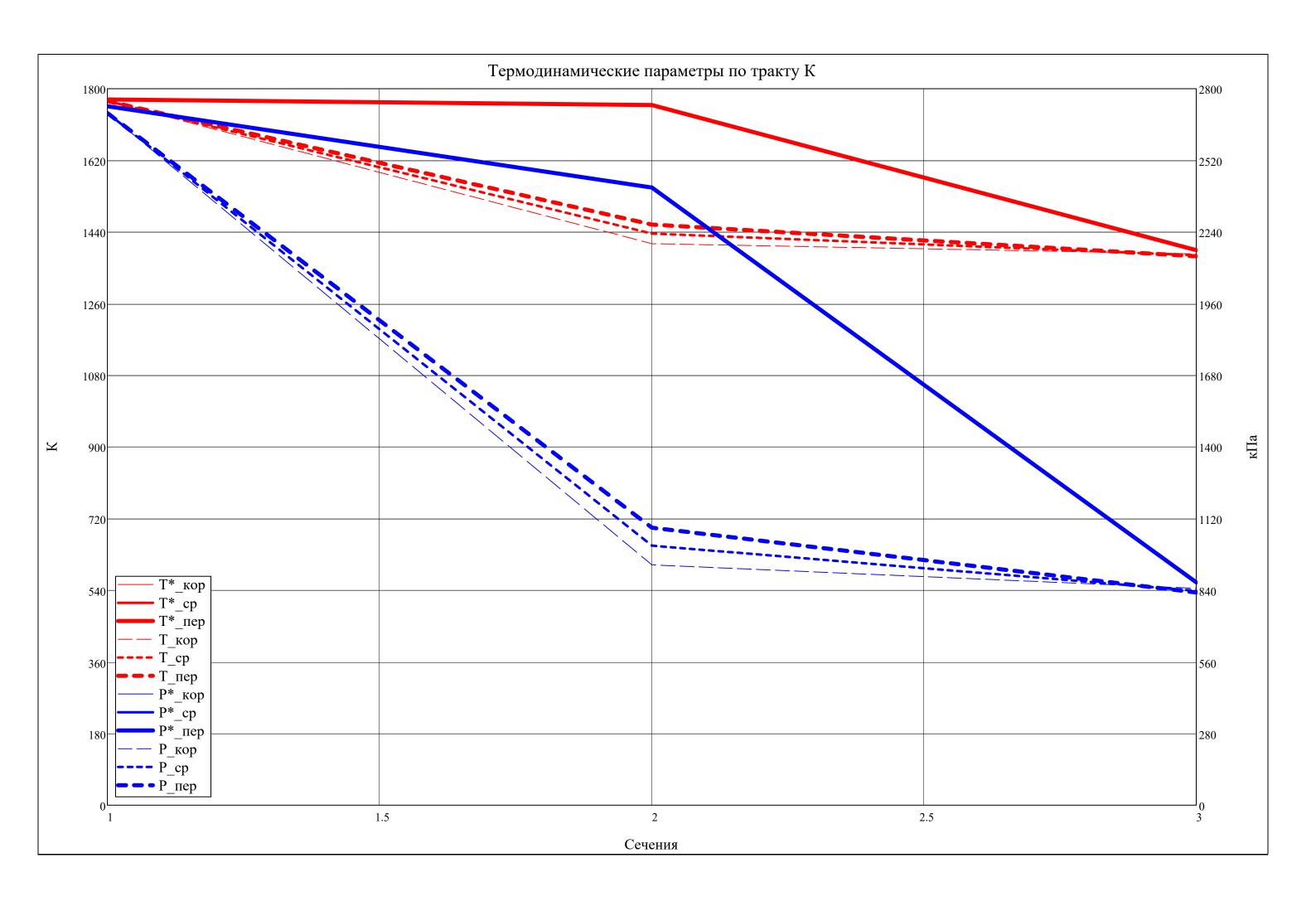
		1	2	3	4	5	6	7	8	9
T* =	1	1878.6	1493.1	1491.4						
1 W -	2	1888.0	1500.7	1508.0						
	3	1897.9	1508.9	1525.6						

$$\rho^{*^T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ 1 & 5.341 & 4.756 & 2.164 \\ \hline 2 & 5.341 & 4.756 & 2.164 \\ \hline 3 & 5.341 & 4.756 & 2.164 \\ \hline \end{array}$$

		1	2	3	
$\mathbf{P}^{\mathrm{T}} =$	1	2705.2	939.2	847.2	.10
-	2	2705.2	1014.0	838.1	
	3	2705.2	1084.4	831.3	

		1	2	3	4	5	6	7	8	9
$T^{T} =$	1	1768.9	1410.5	1385.1						
1	2	1768.9	1436.0	1381.6						
	3	1768.9	1458.8	1378.9						

		1	2	3
$o^{T} =$	1	5.301	2.308	2.120
٢	2	5.301	2.448	2.103
	3	5.301	2.577	2.090



$$k^T = \begin{array}{|c|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ 1 & 1.305 & 1.305 & 1.316 \\ 2 & 1.305 & 1.305 & 1.316 \\ \hline 3 & 1.305 & 1.305 & 1.316 \\ \hline \end{array}$$

		1
$R_{\tau}^{T} =$	1	0.0998
TL	2	0.1767
	3	0.2440

		1	
$R_{I}^{T} \ge 0.05 =$	1	1	
T. = 0.05	2	1	
	3	1	

$$a^*c^T = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 761.0 & 758.1 & 676.1 \\ 2 & 761.0 & 758.1 & 676.1 \\ 3 & 761.0 & 758.1 & 676.1 \end{bmatrix}$$

$$u^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 510.5 & 510.5 & 484.8 \\ \hline 2 & 532.9 & 532.9 & 520.0 \\ \hline 3 & 555.2 & 555.2 & 555.2 \\ \hline \end{array}$$

$$c^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 100.0 & 927.2 & 147.3 \\ \hline 2 & 100.0 & 892.5 & 174.1 \\ \hline 3 & 100.0 & 860.6 & 191.8 \\ \hline \end{array}$$

$$c_u^T = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 0.0 & 897.7 & 1.8 \\ 2 & 0.0 & 864.2 & -2.7 \\ 3 & 0.0 & 833.2 & -6.4 \end{bmatrix}$$

$$\mathbf{c_a}^{\mathrm{T}} = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 100.0 & 231.9 & 147.3 \\ 2 & 100.0 & 223.3 & 174.0 \\ 3 & 100.0 & 215.3 & 191.7 \end{bmatrix}$$

$$\Delta c_a^T = \begin{array}{|c|c|c|c|c|}\hline & 1 & 2 \\ \hline 1 & 131.9 & -84.7 \\ \hline 2 & 123.3 & -49.3 \\ \hline 3 & 115.3 & -23.6 \\ \hline \end{array}$$

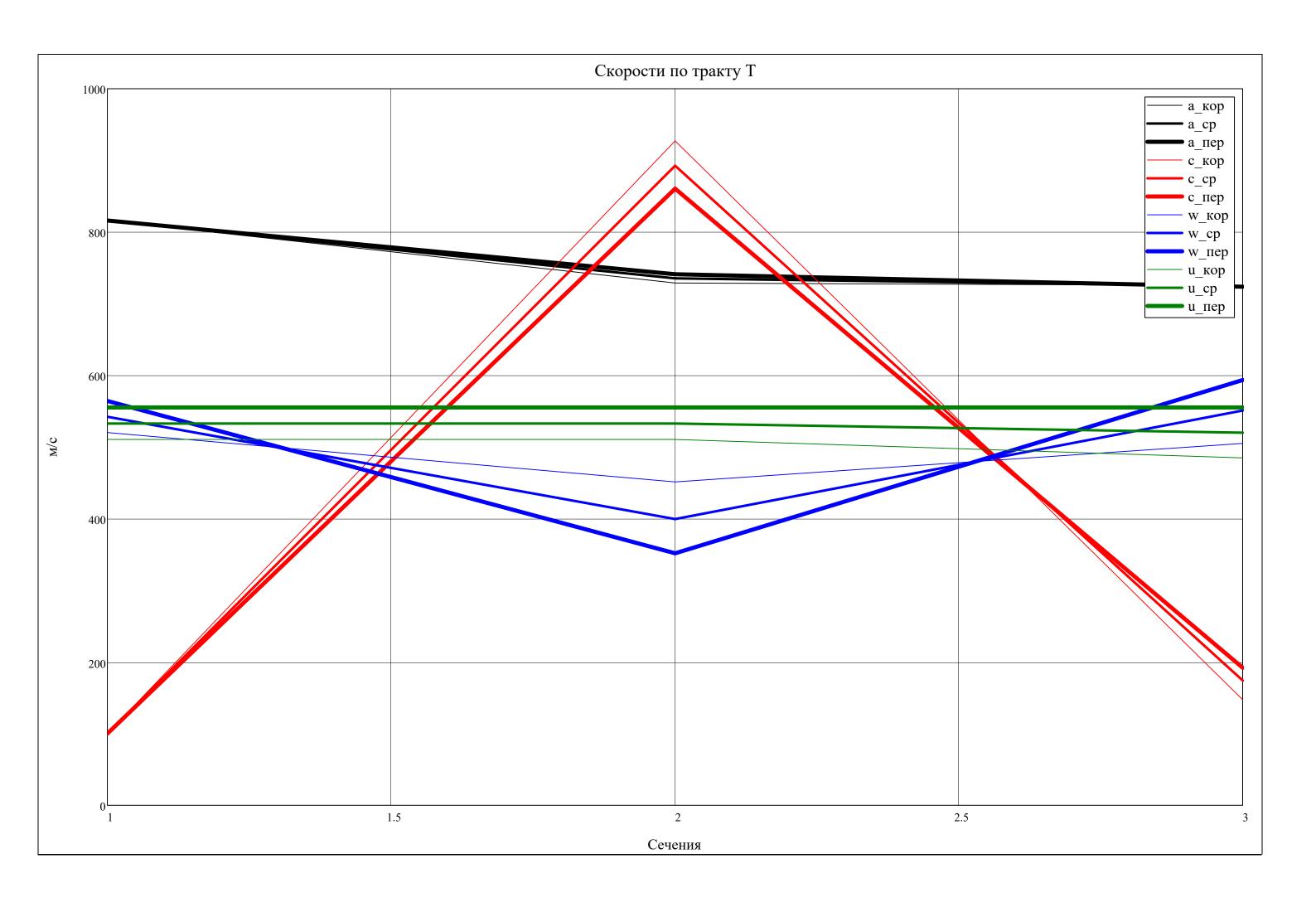
		1	2	3
$a^*_{\mathbf{x}} =$	1	783.4	698.4	699.3
w	2	785.3	700.2	703.2
	3	787.4	702.1	707.3

$$a_{3B}^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 816.1 & 728.8 & 725.3 \\ \hline 2 & 816.1 & 735.4 & 724.4 \\ \hline 3 & 816.1 & 741.2 & 723.7 \\ \hline \end{array}$$

$$w^{T} = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 520.2 & 451.4 & 504.9 \\ 2 & 542.2 & 399.5 & 550.9 \\ 3 & 564.2 & 351.6 & 593.4 \end{bmatrix}$$

$$w_u^T = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 510.5 & -387.2 & 483.0 \\ 2 & 532.9 & -331.3 & 522.7 \\ 3 & 555.2 & -278.0 & 561.6 \end{bmatrix}$$

		1	2	3
$\mathbf{w_a}^T =$	1	100.0	231.9	147.3
	2	100.0	223.3	174.0
	3	100.0	215.3	191.7



		1	2	3	
$\alpha^{T} =$	1	90.00	14.49	89.31	. 0
33	2	90.00	14.49	90.87	
	3	90.00	14.49	91.90	

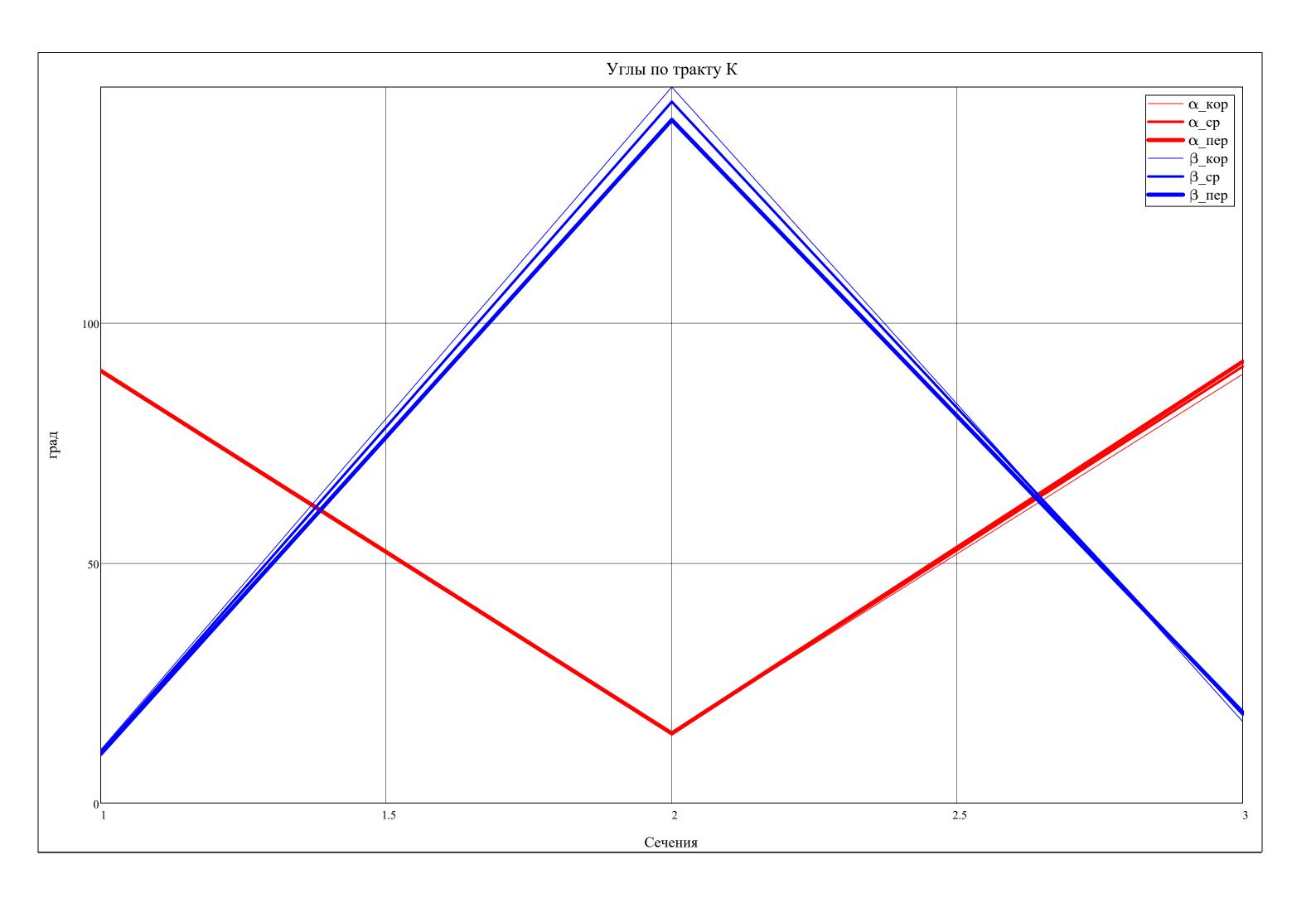
		1	2	3	
$80^{\circ} \leq \alpha^{T} =$	1	1	0	1	
	2	1	0	1	
	3	1	0	1	

		1	
$\varepsilon_{ m stator}^{ m T} =$	1	75.51	.0
stator	2	75.51	
	3	75.51	

[1, c.78]

Угол поворота потока:

$$\varepsilon_{\text{rotor}}^{\text{T}} = \begin{vmatrix}
 & 1 \\
1 & 132.12 \\
2 & 127.61 \\
3 & 123.40
\end{vmatrix}$$
. \circ

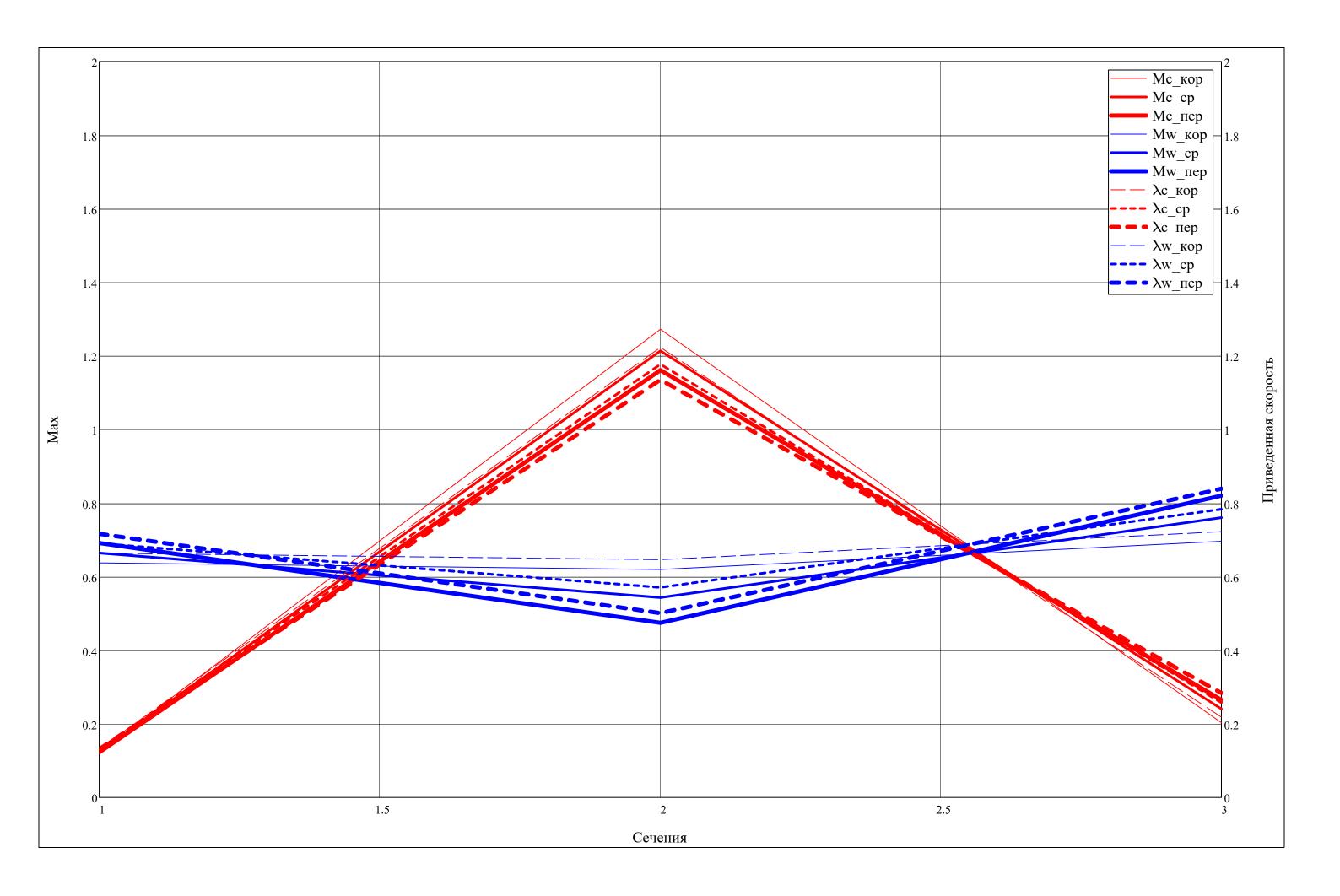


$$\lambda_{c}^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ 1 & 0.131 & 1.223 & 0.218 \\ \hline 2 & 0.131 & 1.177 & 0.257 \\ \hline 3 & 0.131 & 1.135 & 0.284 \\\hline \end{array}$$

$$\mathbf{M_c}^T = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.123 & 1.272 & 0.203 \\ \hline 2 & 0.123 & 1.214 & 0.240 \\ \hline 3 & 0.123 & 1.161 & 0.265 \\ \hline \end{array}$$

		1	2	3
$\lambda_{-} = T$	1	0.664	0.646	0.722
W	2	0.690	0.571	0.783
	3	0.717	0.501	0.839

		1	2	3
$M_{xx}^T =$	1	0.637	0.619	0.696
W	2	0.664	0.543	0.760
	3	0.691	0.474	0.820





Вывод результатов расчета параметров потока по высоте Л

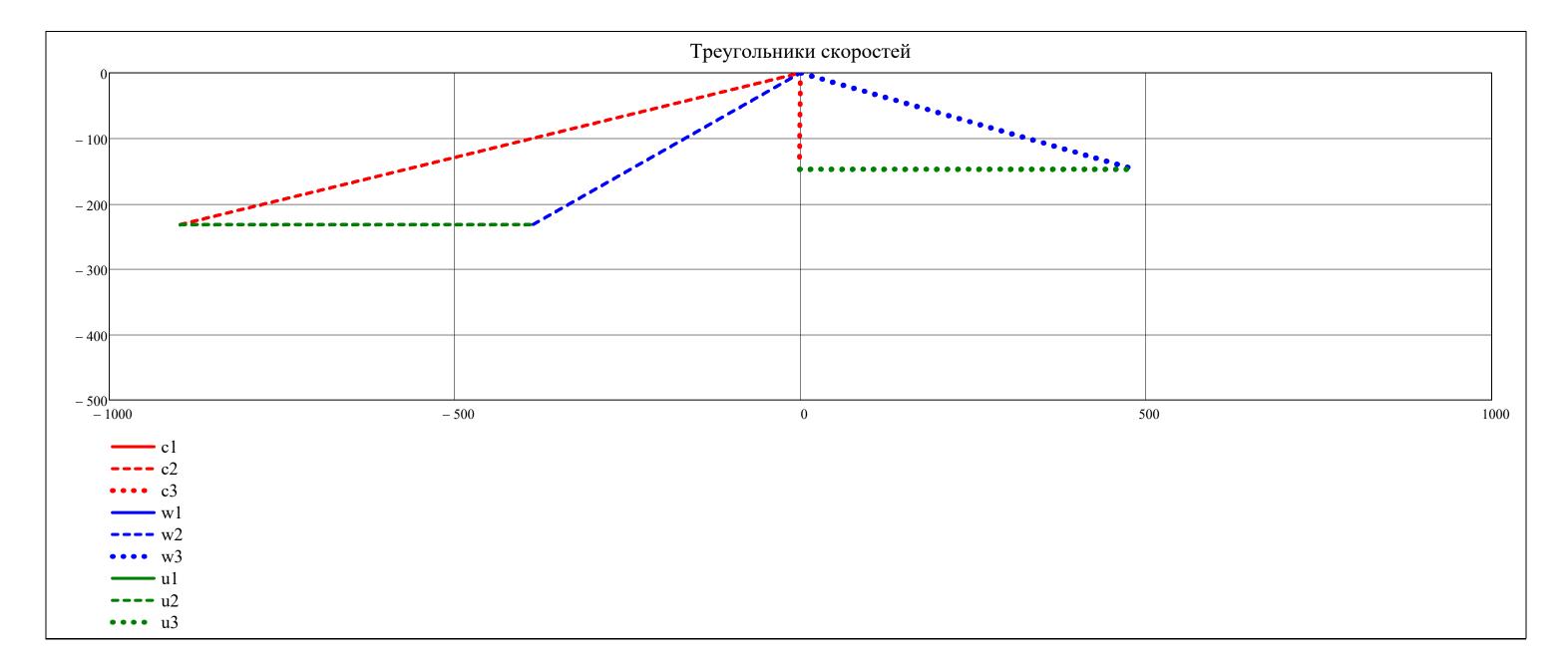
Рассматриваемая ступень:
$$j = \begin{cases} j = Z \\ j = \end{cases}$$
 "Такой ступени не существует!" if $(j < 1) \lor (j > Z)$ j otherwise

▼ Построение треугольников скоростей в 3х сечениях

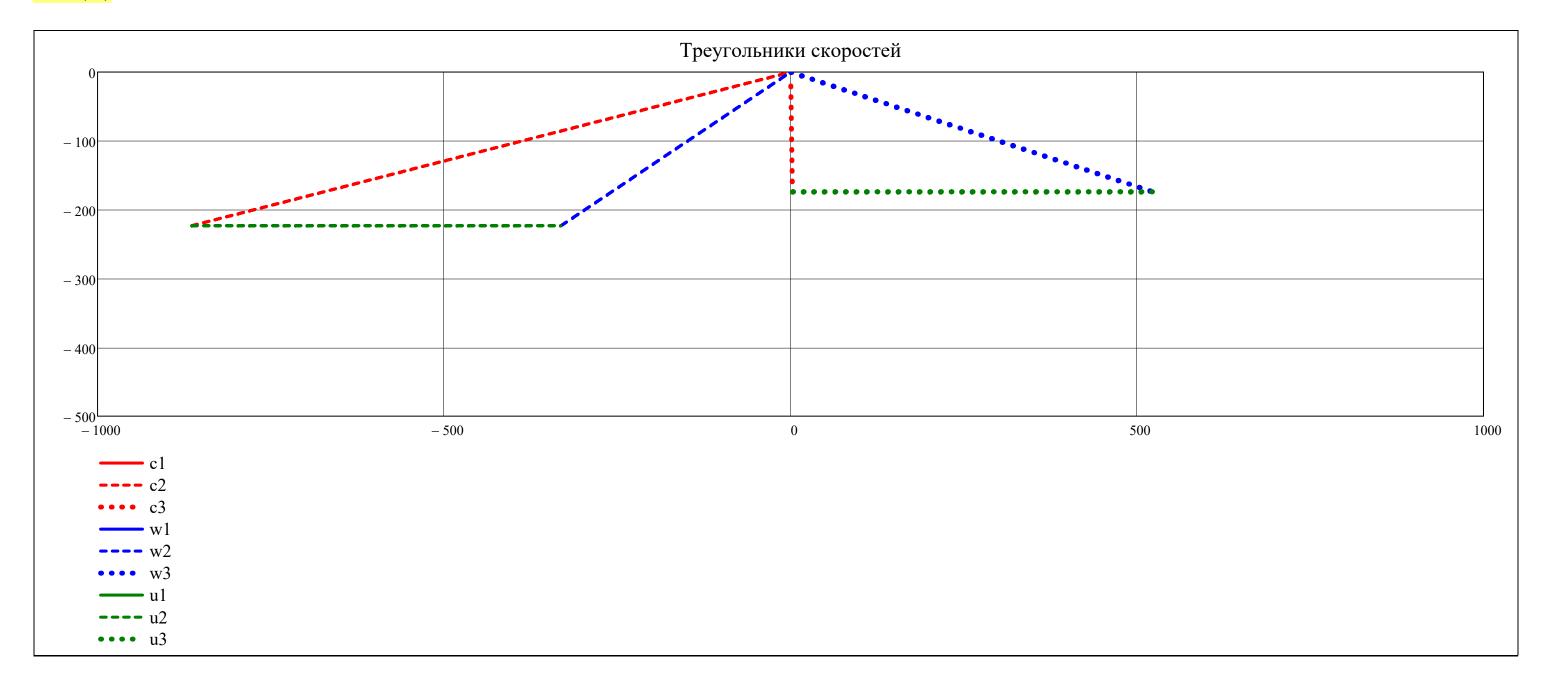
$$\begin{split} \Delta_c(v,i,j,r) &= \left| \begin{array}{l} \tan(\alpha_{st(i,j),r}) \cdot v & \text{if } \left(\tan(\alpha_{st(i,j),r}) \geq 0 \right) \wedge \left(-\left|c_{st(i,j),r} \cdot \cos(\alpha_{st(i,j),r})\right| \leq v \leq 0 \right) \\ & \tan(\alpha_{st(i,j),r}) \cdot v & \text{if } \left(\tan(\alpha_{st(i,j),r}) < 0 \right) \wedge \left(0 \leq v \leq \left|c_{st(i,j),r} \cdot \cos(\alpha_{st(i,j),r})\right| \right) \\ \Delta_W(v,i,j,r) &= \left| -\tan(\beta_{st(i,j),r}) \cdot v & \text{if } \left(-\tan(\beta_{st(i,j),r}) \geq 0 \right) \wedge \left(-\left|w_{st(i,j),r} \cdot \cos(\beta_{st(i,j),r})\right| \leq v \leq 0 \right) \wedge \left(j \neq 1 \right) \\ & -\tan(\beta_{st(i,j),r}) \cdot v & \text{if } \left(-\tan(\beta_{st(i,j),r}) < 0 \right) \wedge \left(0 \leq v \leq \left|w_{st(i,j),r} \cdot \cos(\beta_{st(i,j),r})\right| \right) \wedge \left(j \neq 1 \right) \\ \Delta_U(v,i,j,r) &= \left| -c_{a_{st(i,j),r}} & \text{if } \left(-c_{st(i,j),r} \cdot \cos(\alpha_{st(i,j),r}) \leq v \leq w_{st(i,j),r} \cdot \cos(\beta_{st(i,j),r}) \right) \wedge \left(j \neq 1 \right) \\ & \text{NaN otherwise} \end{split}$$

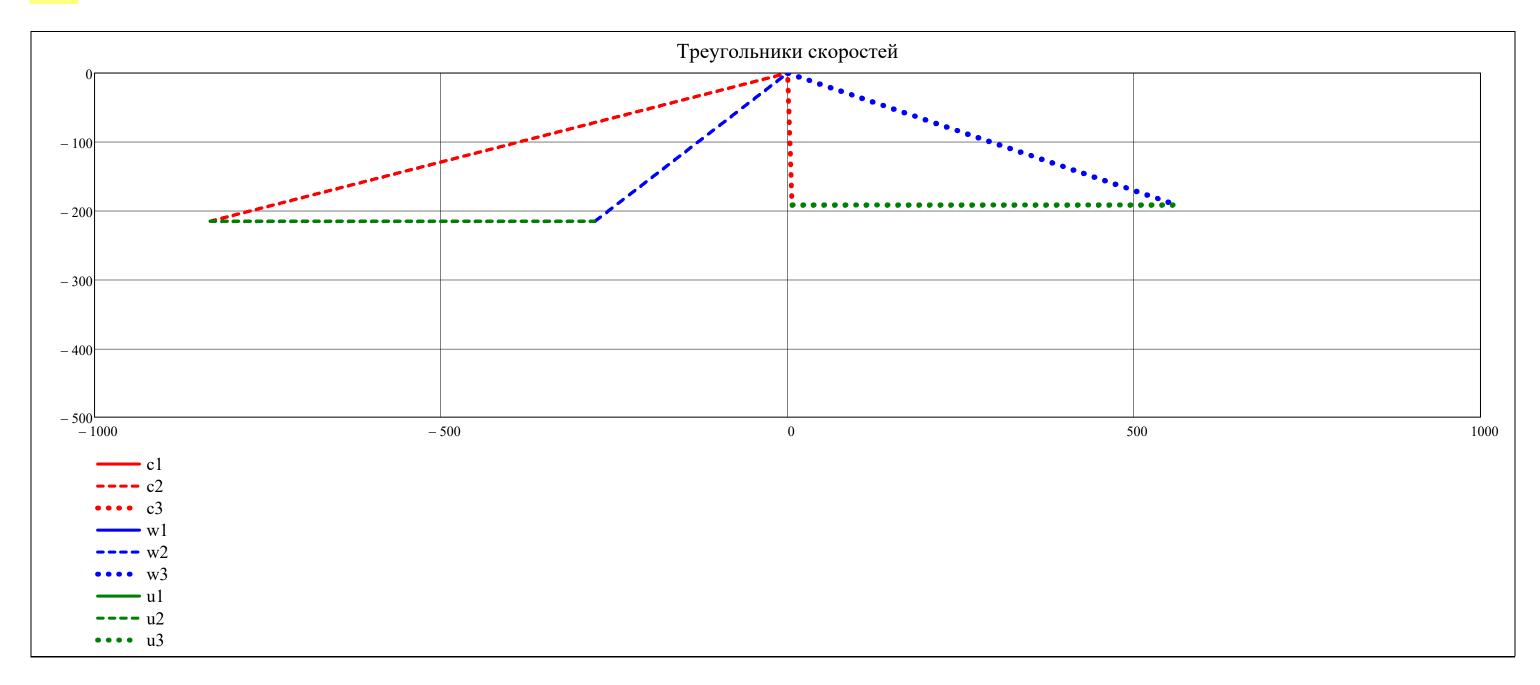
$$v_{lim} = ceil \left(\frac{max(c, w, u)}{10^2} \right) \cdot 10^2 = 1000.0$$

$$v = -max(c, w, u), -max(c, w, u) + \frac{max(c, w, u)}{3000} ... max(c, w, u)$$









■ Построение треугольников скоростей в 3х сечениях

Парусность:
$$\begin{pmatrix} sail_{stator} \\ sail_{rotor} \end{pmatrix} = \begin{pmatrix} sail_{stator} \\ sail_{rotor} \end{pmatrix}$$

▼ Расчет хорд Л по парусности

$$\begin{pmatrix} \text{chord}_{\text{fattor}} \\ \text{chord}_{\text{rotor}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \\ \text{sail} = \frac{R_{\text{st}(i,2), N_f} - R_{\text{st}(i,2), 1}}{R_{\text{st}(i,2), av(N_f)} - R_{\text{st}(i,2), 1}} \\ \text{for } r \in 1..N_r \end{cases}$$

$$\begin{pmatrix} \text{for } r \in 1..N_r \\ \\ \text{b}_{\text{CAxop}} = \frac{\text{chord}_{\text{stator}} - 1 + \text{sail}}{\text{stil}_{\text{rotor}} - 1 + \text{sail}} \\ \text{b}_{\text{CAxop}} = \frac{\text{chord}_{\text{stator}}}{\text{stil}_{\text{rotor}} - 1 + \text{sail}} \\ \begin{pmatrix} \text{b}_{\text{CAnep}} \\ \text{bpKnep} \end{pmatrix} = \begin{pmatrix} \text{b}_{\text{CAxop}} & \text{ssiil}_{\text{stator}} \\ \text{bpKnep} & \text{stil}_{\text{rotor}} - 1 + \text{sail} \\ \end{pmatrix} \\ \text{chord}_{\text{stator}} & \text{chord}_{\text{stator}} \end{pmatrix} \begin{pmatrix} \text{b}_{\text{CAxop}} & \text{ssiil}_{\text{stator}} \\ \text{bpKnep} & \text{below} & \text{stil}_{\text{rotor}} \end{pmatrix} \begin{pmatrix} \text{b}_{\text{CAxop}} & \text{stil}_{\text{rotor}} \\ \text{bpKnep} & \text{stil}_{\text{rotor}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{R}_{\text{st}(i,2),1} \\ \text{R}_{\text{st}(i,2),3} & \text{h}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{h}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_f)} \\ \text{b}_{\text{CAxop}} \end{pmatrix} \end{pmatrix} \begin{pmatrix} \text{chord}_{\text{stator}, av(N_$$

Длины хорд РК и СА (м):

$$chord_{rotor}^{T} = \begin{array}{|c|c|c|c|}\hline 1 & 38.4 \\ \hline 2 & 34.2 \\ \hline 3 & 31.4 \\ \hline \end{array} \cdot 10^{-3}$$

$$\bar{x}_{f} = 0.45$$

▼ Расчет параметров решетки

$$\begin{bmatrix} \frac{t_{stator}}{r_{-}inlet_{stator}} & \frac{t_{-}inlet_{rotor}}{r_{-}outlet_{stator}} & \frac{t_{-}inlet_{rotor}}{r_{-}outlet_{stator}} \\ \frac{t_{-}inlet_{stator}}{r_{-}outlet_{stator}} & \frac{t_{-}inlet_{rotor}}{r_{-}outlet_{stator}} \\ \frac{t_{-}inlet_{-}inl$$

$$\begin{pmatrix} v_{\text{установки}}(\alpha_{\text{st(i,1),r}},\alpha_{\text{st(i,2),r}}) \\ v_{\text{установки}}(\beta_{\text{st(i,2),r}},\beta_{\text{st(i,3),r}}) \end{pmatrix}$$

 $\frac{\pi}{2}$ добавляется в виду поворота рисунка на 90 град

Относительные радиусы профилей ():

$$\frac{T}{\text{r_inlet}_{\text{stator}}} = \begin{vmatrix}
 & 1 & \\
 & 1 & 6.000 \\
 & 2 & 6.000 \\
 & 3 & 6.000
\end{vmatrix} .\%$$

$$\frac{T}{r_inlet_{rotor}} = \begin{bmatrix}
 & 1 \\
1 & 5.950 \\
2 & 4.550 \\
3 & 3.850
\end{bmatrix} .\%$$

$$\frac{T}{r_{outlet}} = \begin{vmatrix}
 & 1 & \\
 & 1 & 2.550 \\
 & 2 & 1.950 \\
 & 3 & 1.650
\end{vmatrix}$$

Относительная толщина профиля ():

$$\overline{c}_{stator}^{T} = \begin{bmatrix}
 & 1 \\
1 & 15.00 \\
2 & 15.00 \\
3 & 15.00
\end{bmatrix}$$

$$\overline{c}_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 17.00\\ 2 & 13.00\\ \hline 3 & 11.00 \end{bmatrix} \cdot \%$$

Относительный шаг решетки ():

$$\left(\frac{t_{stator}}{chord_{stator}}\right)^{T} = \begin{vmatrix} 1\\ 1 & 0.8345\\ 2 & 0.8711\\ 3 & 0.9076 \end{vmatrix}$$

$$\left(\frac{t_{rotor}}{chord_{rotor}}\right)^{T} = \begin{vmatrix} 1 & 1 \\ 1 & 0.5829 \\ 2 & 0.6918 \\ \hline 3 & 0.7941 \end{vmatrix}$$

Относительная густота решетки ():

$$\left(\frac{\text{chord}_{\text{rotor}}}{t_{\text{rotor}}}\right)^{\text{T}} = \begin{bmatrix} & 1\\ 1 & 1.716\\ 2 & 1.445\\ \hline 3 & 1.259 \end{bmatrix}$$

Длина хорды профиля [м]:

$$chord_{stator}^{T} = \begin{bmatrix} 1 \\ 1 \\ 68.0 \\ 2 \\ 68.0 \\ 3 \\ 68.0 \end{bmatrix} \cdot 10^{-3}$$

$$chord_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 38.4\\ 2 & 34.2\\ \hline 3 & 31.4 \end{bmatrix} \cdot 10^{-3}$$

Радиусы профилей:

$$r_{inlet_{rotor}}^{T} = \begin{bmatrix} & 1 \\ 1 & 2.28 \\ 2 & 1.56 \\ \hline 3 & 1.21 \end{bmatrix} \cdot 10^{-3}$$

$$r_outlet_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 2.04 \\ 2 & 2.04 \\ 3 & 2.04 \end{bmatrix} \cdot 10^{-3}$$

$$r_outlet_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0.67 \\ 3 \\ 0.52 \end{bmatrix} \cdot 10^{-3}$$

Толщина профиля [м]:

$$c_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1 \\ 1 & 10.20 \\ 2 & 10.20 \\ 3 & 10.20 \end{bmatrix} \cdot 10^{-3}$$

$$c_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 6.52\\ 2 & 4.45\\ \hline 3 & 3.46 \end{bmatrix} \cdot 10^{-3}$$

Шаг решетки [м]:

$$t_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1\\1&56.7\\2&59.2\\3&61.7 \end{bmatrix} \cdot 10^{-3}$$

$$t_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 22.4\\ 2 & 23.7\\ \hline 3 & 25.0 \end{bmatrix} \cdot 10^{-3}$$

Угол поворота потока:	$\varepsilon_{\text{stator}}^{\text{T}} = \begin{bmatrix} & & 1 & \\ & 1 & 75.51 \\ & 2 & 75.51 \\ \hline & 3 & 75.51 \end{bmatrix} \cdot \circ$	$\varepsilon_{\text{rotor}}^{\text{T}} = \begin{bmatrix} & & 1 & \\ & 1 & 132.12 \\ & 2 & 127.61 \\ & 3 & 123.40 \end{bmatrix} . \circ$
Угол установки профиля:	$v_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 117.3 \\ \hline 3 \\ 117.3 \end{bmatrix} . \circ$	$v_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 112.0 \\ 2 & 114.0 \\ 3 & 115.4 \end{bmatrix} \cdot \circ$
Угол изгиба профиля:	$\pi - \varepsilon_{stator}^{T} = \begin{bmatrix} & 1 & \\ 1 & 104.5 \\ \hline 2 & 104.5 \\ \hline 3 & 104.5 \end{bmatrix} \cdot \circ$	$\pi - \varepsilon_{\text{rotor}}^{\text{T}} = \begin{bmatrix} 1 \\ 1 \\ 47.9 \\ 2 \\ 52.4 \\ 3 \\ 56.6 \end{bmatrix}$

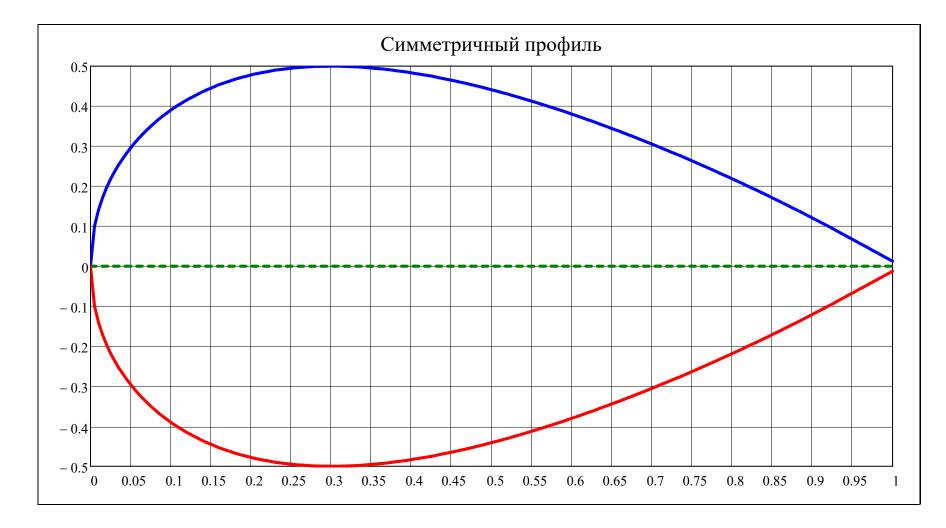
.0

▼ Подключение симметричного профиля

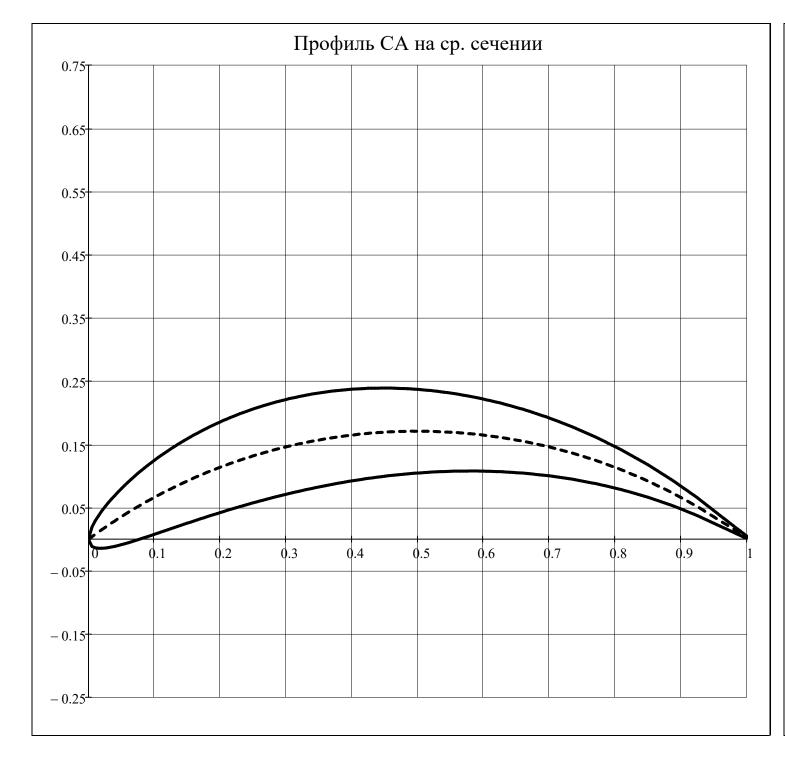
$$\begin{pmatrix} X_{U} & Y_{U} \\ X_{L} & Y_{L} \end{pmatrix} = NACA(0, 0, 100\%, 1)$$

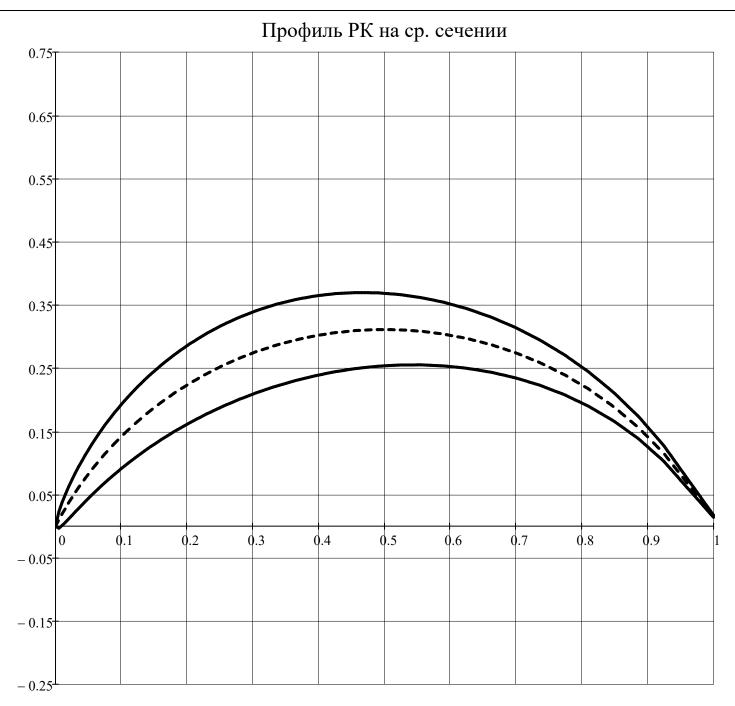
Относ. координаты профиля РК и СА:

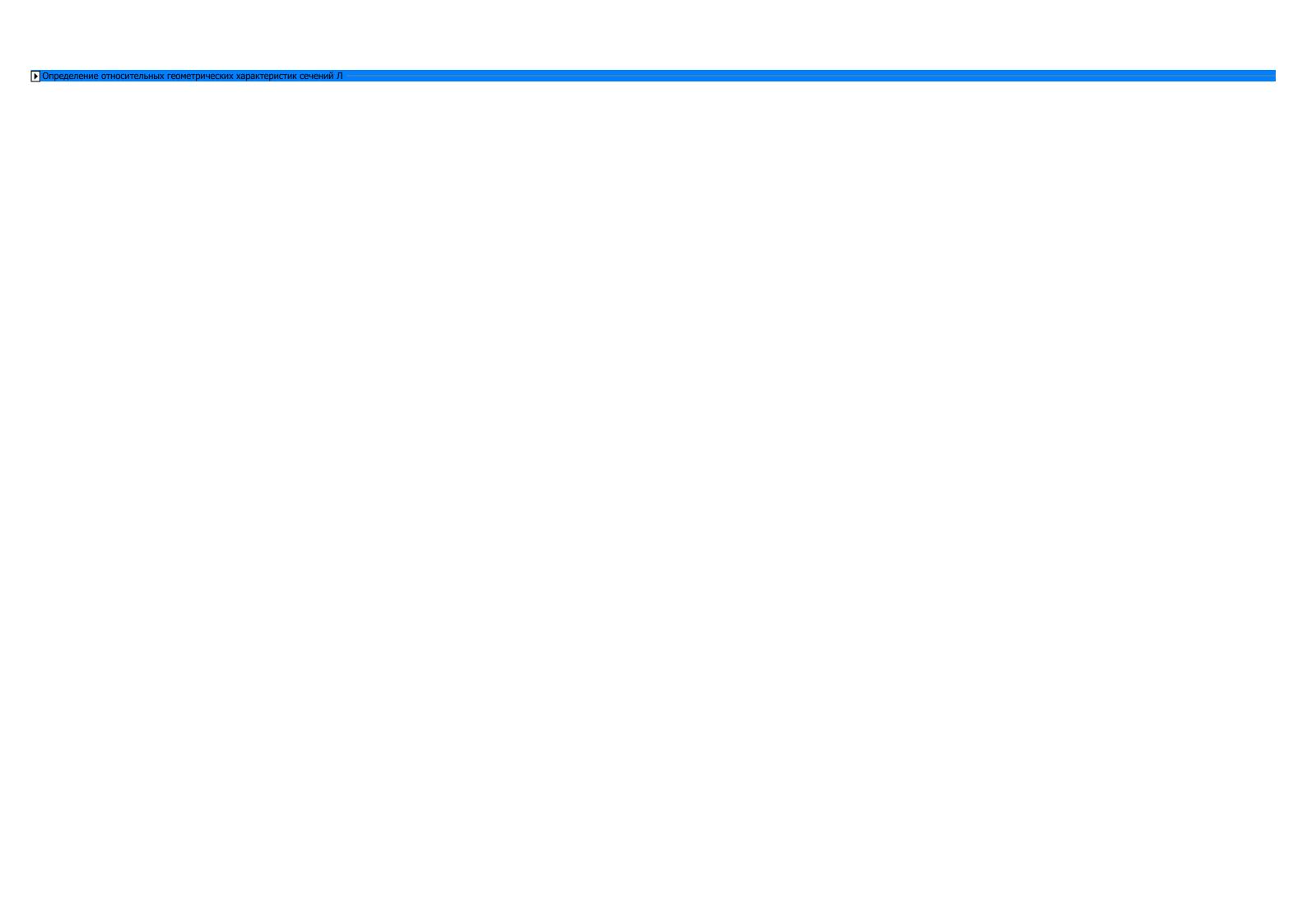
$$\begin{split} \text{AIRFOIL}_0\Big(x, \text{line}\,\overline{,f}\,, \overline{x}_f, \overline{c}\,\Big) &= & \text{if } 0 \leq x \leq 1 \\ & & \text{linterp}\big(X_U, Y_U, x\big) \text{ if line} = "+" \\ & \frac{\text{linterp}\big(X_U, Y_U, x\big) + \text{linterp}\big(X_L, Y_L, x\big)}{2} \text{ if line} = "0" \\ & & \text{linterp}\big(X_L, Y_L, x\big) \text{ if line} = "-" \\ & & \text{NaN otherwise} \end{split}$$



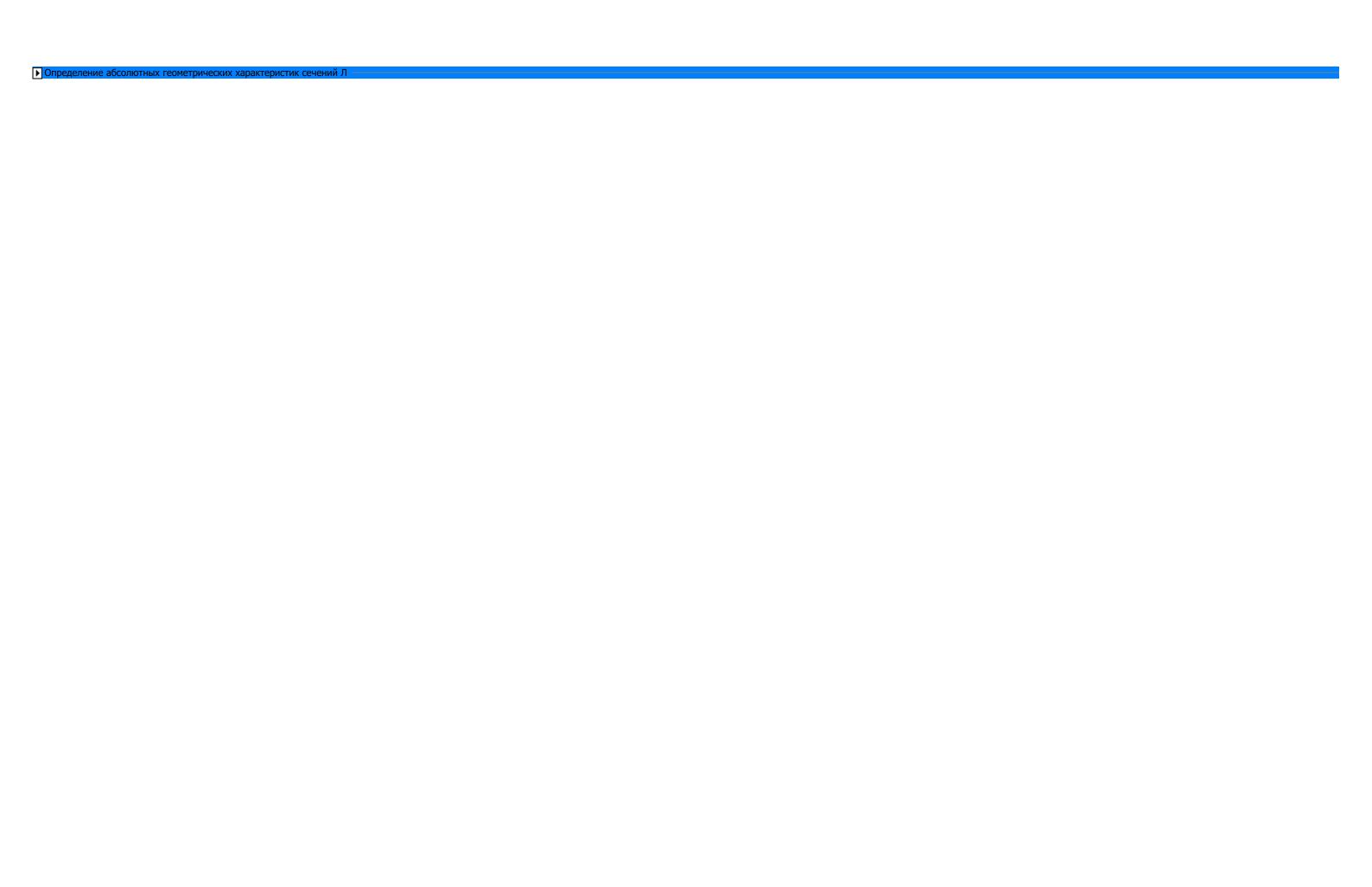
$$\begin{split} \text{AIRFOIL}(x,\text{line},\overline{c}^-,\theta) &= \begin{vmatrix} \text{linterp}\big(X_U,y/b_{cp.\Pi}\big(X_U,\theta\big) + Y_U\cdot\overline{c}^-,x\big) & \text{if line} = "+" \\ \frac{\text{linterp}\big(X_U,y/b_{cp.\Pi}\big(X_U,\theta\big) + Y_U\cdot\overline{c}^-,x\big) + \text{linterp}\big(X_L,y/b_{cp.\Pi}\big(X_L,\theta\big) + Y_L\cdot\overline{c}^-,x\big)}{2} & \text{if line} = "0" \\ \frac{\text{linterp}\big(X_L,y/b_{cp.\Pi}\big(X_L,\theta\big) + Y_L\cdot\overline{c}^-,x\big) + \text{linterp}\big(X_L,y/b_{cp.\Pi}\big(X_L,\theta\big) + Y_L\cdot\overline{c}^-,x\big)}{2} & \text{if line} = "-" \\ \text{NaN otherwise} & \end{aligned}$$







▶ Результат расчета абсолютных геометрических характеристик сечений Л



▼ Результат расчета абсолютных геометрических характеристик сечений Л

$$1_lower_{stator}^{T} = \begin{bmatrix} & 1 \\ 1 & 70.64 \\ 2 & 70.64 \\ \hline 3 & 70.64 \end{bmatrix} \cdot 10^{-3}$$

$$\operatorname{area}_{\text{stator}}^{\text{T}} = \begin{bmatrix} & 1\\ 1 & 473.87\\ 2 & 473.87\\ 3 & 473.87 \end{bmatrix} \cdot 10^{-6}$$

$$Sx_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 4232.2 \\ 2 & 4232.2 \\ 3 & 4232.2 \end{bmatrix} \cdot 10^{-9}$$

$$Sy_{\text{stator}}^{\text{T}} = \begin{bmatrix} & 1\\ 1 & 13563.5\\ \hline 2 & 13563.5\\ \hline 3 & 13563.5 \end{bmatrix} \cdot 10^{-9}$$

$$x0_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ 1 & 28.6 \\ \hline 2 & 28.6 \\ \hline 3 & 28.6 \\ \hline \end{array} \cdot 10^{-3}$$

$$y0_{\text{stator}}^{\text{T}} = \frac{\begin{vmatrix} 1 \\ 1 & 8.9 \\ 2 & 8.9 \\ 3 & 8.9 \end{vmatrix}}{2 & 8.9} \cdot 10^{-3}$$

$$1_upper_{rotor}^{T} = \begin{bmatrix} & & 1 \\ 1 & 52.01 \\ 2 & 44.78 \\ \hline 3 & 40.21 \end{bmatrix} \cdot 10^{-3}$$

$$1_lower_{rotor}^{T} = \begin{array}{|c|c|c|c|}\hline & 1 \\ \hline 1 & 44.26 \\ \hline 2 & 39.55 \\ \hline 3 & 36.21 \\ \hline \end{array} \cdot 10^{-3}$$

$$area_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 171.14\\ 2 & 103.96\\ \hline 3 & 74.28 \end{bmatrix} \cdot 10^{-6}$$

$$Sx_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 & 1711.6 \\ 2 & 883.3 \\ 3 & 554.2 \end{bmatrix} \cdot 10^{-9}$$

$$Sy_{rotor}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 2765.3 \\ \hline 2 & 1497.1 \\ \hline 3 & 983.0 \\ \hline \end{array} \cdot 10^{-9}$$

$$x0_{rotor}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\\hline 1 & 16.2 \\\hline 2 & 14.4 \\\hline 3 & 13.2 \\\hline \end{array} \cdot 10^{-3}$$

$$y0_{rotor}^{T} = \begin{array}{|c|c|c|c|}\hline & 1 & \\ \hline 1 & 10.0 \\ \hline 2 & 8.5 \\ \hline 3 & 7.5 \\ \hline \end{array} \cdot 10^{-3}$$

$$Jx_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 44264 \\ 2 & 44264 \\ \hline 3 & 44264 \end{bmatrix} \cdot 10^{-12}$$

$$Jy_{\text{stator}}^{\text{T}} = \begin{vmatrix} 1 \\ 1 & 508717 \\ 2 & 508717 \\ \hline 3 & 508717 \end{vmatrix} \cdot 10^{-12}$$

$$Jxy_{stator}^{T} = \begin{array}{|c|c|c|}\hline 1 & 1 \\\hline 1 & 128548 \\\hline 2 & 128548 \\\hline 3 & 128548 \\\hline \end{array} \cdot 10^{-12}$$

$$Jx0_{stator}^{T} = \begin{vmatrix} 1 & 1 \\ 1 & 6465 \\ 2 & 6465 \\ \hline 3 & 6465 \end{vmatrix} \cdot 10^{-12}$$

$$Jy0_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ \hline 1 & 120489 \\ \hline 2 & 120489 \\ \hline 3 & 120489 \\ \hline \end{array} \cdot 10^{-12}$$

$$Jxy0_{stator}^{T} = \begin{bmatrix} & 1\\ 1 & 7409\\ 2 & 7409\\ \hline 3 & 7409 \end{bmatrix} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^{\text{T}} = \begin{vmatrix}
 & 1 \\
 & 1 & 3.70 \\
 & 2 & 3.70 \\
 & 3 & 3.70
\end{vmatrix}$$

$$Jx_{rotor}^{T} = \begin{bmatrix} 1\\1\\1\\2\\8184\\3\\4505 \end{bmatrix} \cdot 10^{-12}$$

$$Jy_{rotor}^{T} = \begin{bmatrix} 1\\1\\58548\\2\\28251\\3&17045 \end{bmatrix} \cdot 10^{-12}$$

$$Jxy_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 & 29122 \\ 2 & 13406 \\ \hline 3 & 7736 \end{bmatrix} \cdot 10^{-12}$$

$$Jy0_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \\ 6691 \\ 3 \\ 4037 \end{bmatrix} \cdot 10^{-12}$$

$$Jxy0_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 & 1466 \\ 2 & 686 \\ \hline 3 & 402 \end{bmatrix} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^{\text{T}} = \begin{vmatrix}
 & 1 \\
 & 1 & 6.75 \\
 & 2 & 6.43 \\
 & 3 & 6.18
\end{vmatrix}$$
.

$$Ju_{stator}^{T} = \begin{bmatrix} & 1 \\ 1 & 5986 \\ 2 & 5986 \\ \hline 3 & 5986 \end{bmatrix} \cdot 10^{-12}$$

$$Jv_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|}\hline & 1 & \\ \hline 1 & 120968.8 \\ \hline 2 & 120968.8 \\ \hline 3 & 120968.8 \\ \hline \end{array} \cdot 10^{-12}$$

$$Juv_{stator}^{T} = \begin{vmatrix} & 1 \\ 1 & -0 \\ 2 & -0 \\ \hline 3 & -0 \end{vmatrix} \cdot 10^{-12}$$

$$Jp_{stator}^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ 1 & 126955 \\ \hline 2 & 126955 \\ \hline 3 & 126955 \\ \hline \end{array} \cdot 10^{-12}$$

$$Wp_{stator}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 3146.4 \\ \hline 2 & 3146.4 \\ \hline 3 & 3146.4 \\ \hline \end{array} \cdot 10^{-9}$$

$$Ju_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 1482 \\ 2 & 602 \\ 3 & 326 \end{bmatrix} \cdot 10^{-12}$$

$$Jv_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 14041 \\ 2 & 6769 \\ \hline 3 & 4081 \end{bmatrix} \cdot 10^{-12}$$

$$Juv_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \cdot 10^{-12}$$

$$Jp_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 15522\\ 2 & 7371\\ 3 & 4407 \end{bmatrix} \cdot 10^{-12}$$

$$Wp_{rotor}^{T} = \begin{bmatrix} 1\\1&637.2\\2&342.1\\3&224.1 \end{bmatrix} \cdot 10^{-9}$$

stiffness_{rotor}^T =
$$\begin{vmatrix} 1 & 1 \\ 1 & 1676.5 \\ 2 & 473.1 \\ 3 & 204.3 \end{vmatrix} \cdot 10^{-12}$$

		1	
$CPx_{stator}^{T} =$	1	23.790	$\cdot 10^{-3}$
Stator	2	23.790	10
	3	23.790	

$$CPx_{rotor}^{T} = \begin{bmatrix} & 1 & \\ 1 & 13.430 \\ \hline 2 & 11.969 \\ \hline 3 & 10.999 \end{bmatrix} \cdot 10^{-3}$$

$$CPy_{stator}^{T} = \begin{bmatrix} & 1 & \\ 1 & 0.0000 \\ \hline 2 & 0.0000 \\ \hline 3 & 0.0000 \end{bmatrix} \cdot 10^{-3}$$

$$CPy_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 0.0000\\ \hline 2 & 0.0000\\ \hline 3 & 0.0000 \end{bmatrix} \cdot 10^{-3}$$

Результат расчета абсолютных геометрических характеристик сечений Л

Вывод результатов расчета геометрических хар-к сечений Л

▼ Профилирование решеток

Абс. координаты профиля:

▲ Профилирование решеток

Рассматриваемая ступень: j = j = Z

$$j_w = \begin{cases} j = Z \end{cases}$$
 = 1
$$j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \lor (j > Z) \end{cases}$$

$$j = \begin{cases} j = Z \end{cases}$$

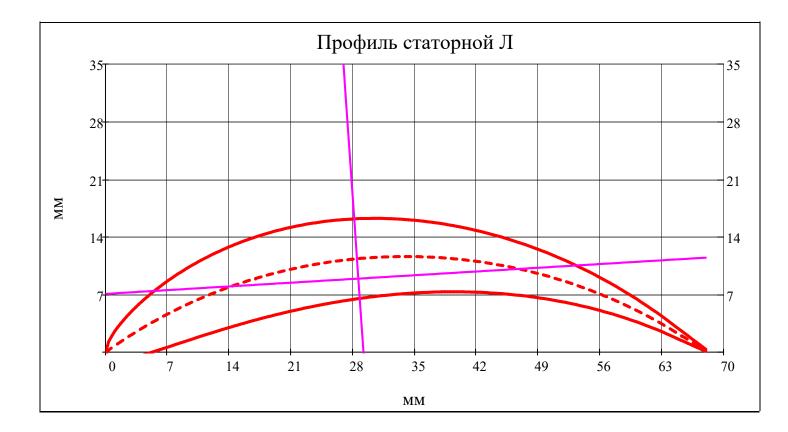
▼ Построение профилей Л РК и НА

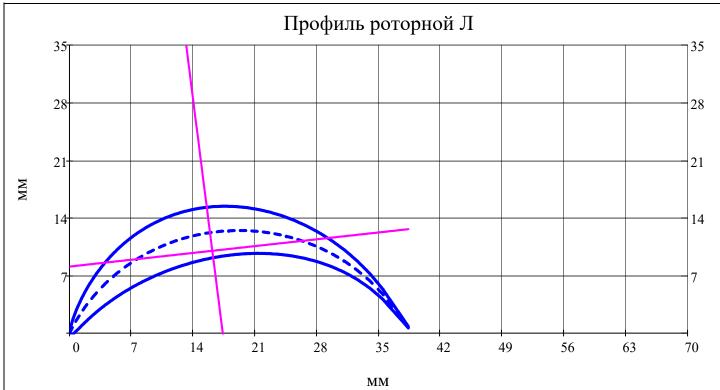
NaN otherwise

$$\begin{aligned} \text{AXLE0(type}, \mathbf{x}, \mathbf{i}, \mathbf{r}) &= \frac{y0_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}} + \tan\left(\alpha_{-}\text{major}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}\right) \cdot \left(\mathbf{x} - \frac{\mathbf{x}0_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}\right) & \text{if type} = \text{"rotor"} \\ \frac{y0_{stator_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{stator_{\hat{\mathbf{i}}, \mathbf{r}}}} + \tan\left(\alpha_{-}\text{major}_{stator_{\hat{\mathbf{i}}, \mathbf{r}}}\right) \cdot \left(\mathbf{x} - \frac{\mathbf{x}0_{stator_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{stator_{\hat{\mathbf{i}}, \mathbf{r}}}}\right) & \text{if type} = \text{"stator"} \\ \text{NaN otherwise} \end{aligned}$$

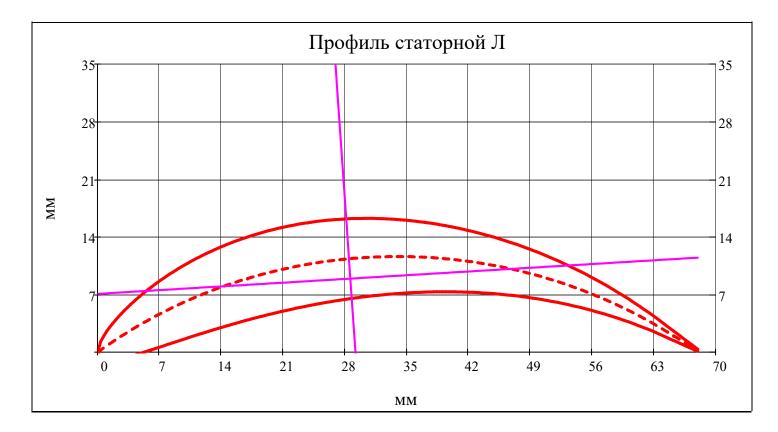
$$\text{AXLE90(type}, \mathbf{x}, \mathbf{i}, \mathbf{r}) &= \frac{y0_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}} + \tan\left(\alpha_{-}\text{major}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}} + \frac{\pi}{2}\right) \cdot \left(\mathbf{x} - \frac{\mathbf{x}0_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}{\text{chord}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}}\right) & \text{if (type} = \text{"rotor"}) \land \left|\alpha_{-}\text{major}_{rotor_{\hat{\mathbf{i}}, \mathbf{r}}}\right| \geq 1.^{\circ} \\ y0_{stator} &= \sqrt{(\mathbf{x}0_{stator}, \mathbf{r})} & \sqrt{(\mathbf$$

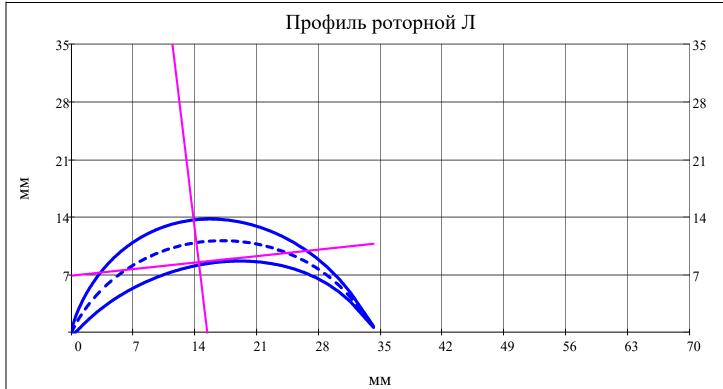
$$b_{lim} = \frac{\text{ceil}\left(\text{max}\left(\text{chord}_{rotor_{j,N_r}}, \text{chord}_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$



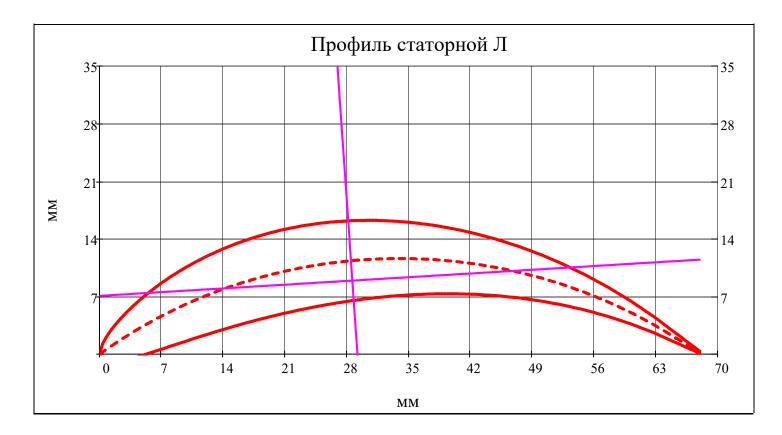


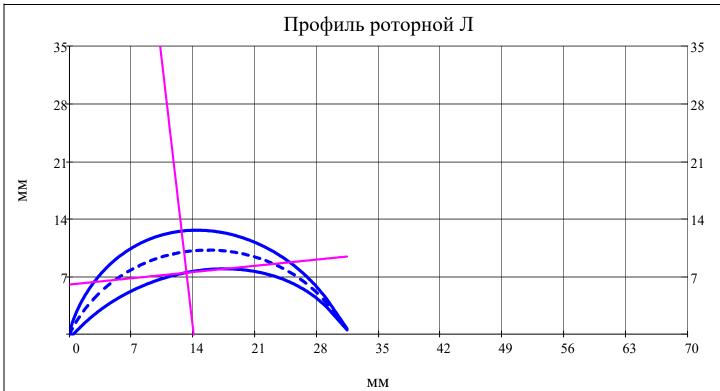
$rac{r}{m} = av(N_r)$











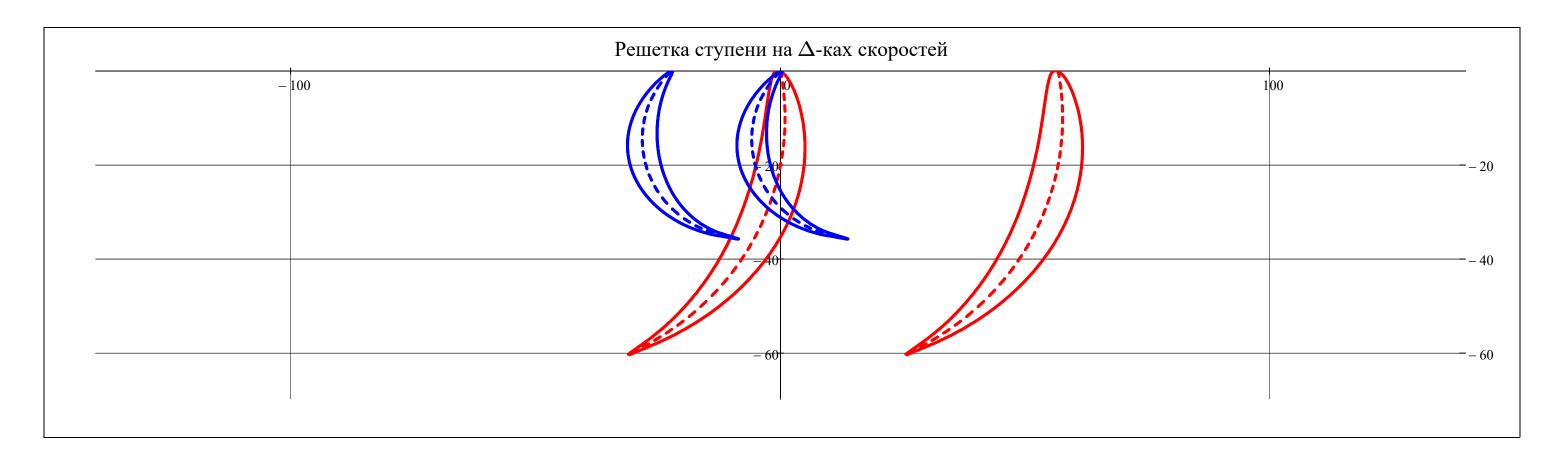
■ Построение профилей Л РК и НА

Рассматриваемая ступень:
$$j = Z$$
 = $j = Z$ = $j = Z$ | $j = Z$ | "Такой ступени не существует!" if $(j < 1) \lor (j > Z)$ | j otherwise

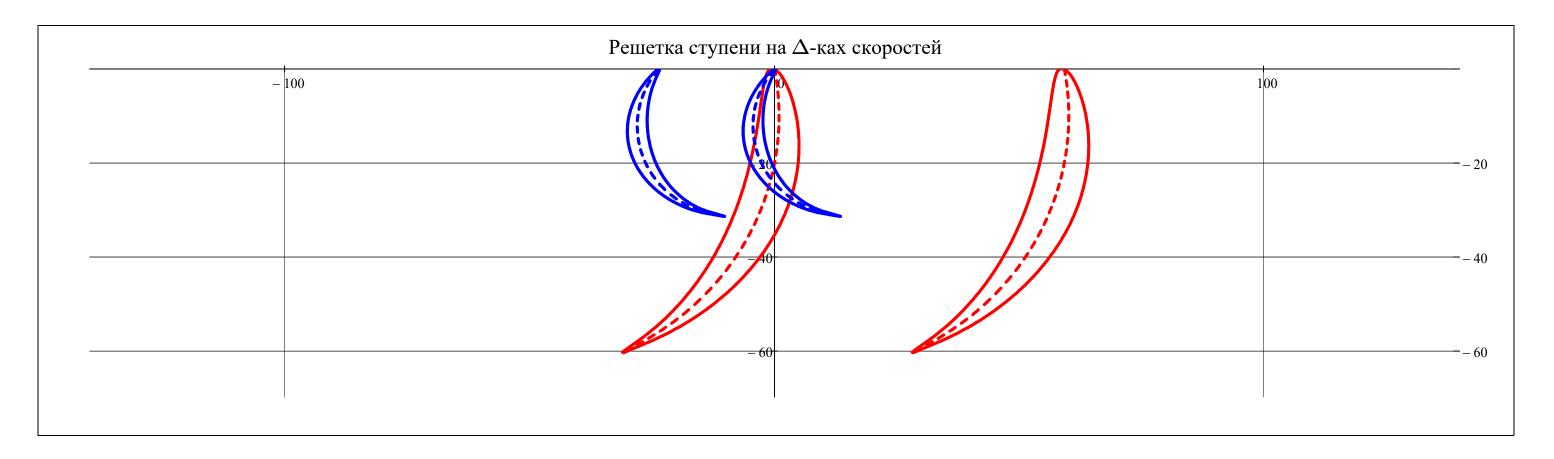
$$b_{\text{Line}} = \frac{\text{ceil}\left(\text{max}\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

▼ Построение плоских решеток профилей Л на треугольниках скоростей

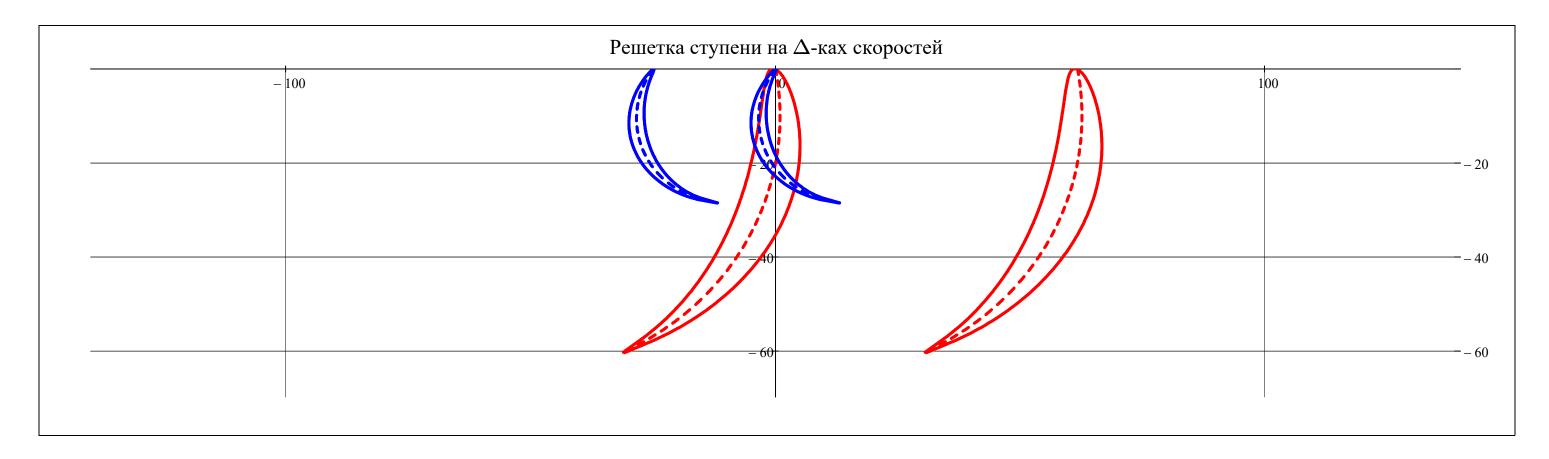




 $r = av(N_r)$







▲ Построение плоских решеток профилей Л на треугольниках скоростей

$$j =$$
 $j = Z$ $= 1$ $j =$ "Такой ступени не существует!" if $(j < 1) \lor (j > Z)$ j otherwise

▼ Поперечная часть ступени

$$\mathbf{r} = \min(\mathbf{D}), \min(\mathbf{D}) + \frac{\max(\mathbf{D}) - \min(\mathbf{D})}{N_{dis}} ... \max(\mathbf{D})$$

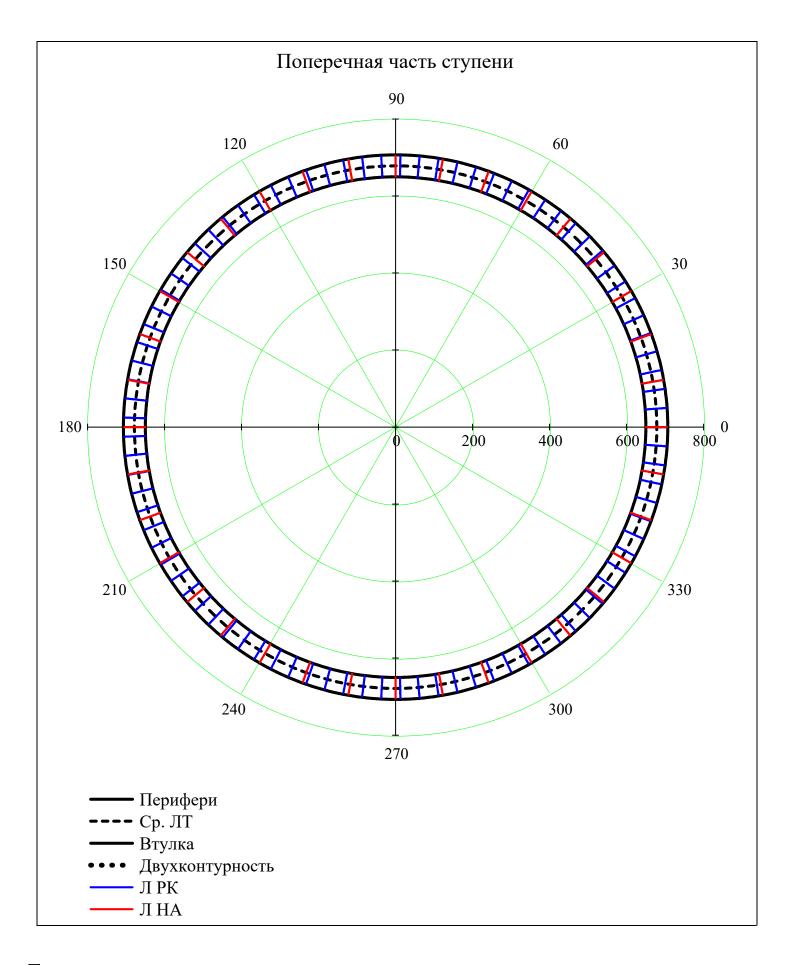
$$\mathbf{i}_{rotor} = 1 ... Z_{rotor_{j}}$$

$$\mathbf{i}_{stator} = 1 ... Z_{stator_{j}}$$

$$\varphi = 0, \frac{2 \cdot \pi}{360} ... 2 \cdot \pi$$

$$\Pi_{PK}(r,j) = \begin{bmatrix} \frac{2 \cdot \pi}{Z_{rotor_{j}}} & \text{if } D_{st(j,1),1} < r < D_{st(j,1),N_{r}} \\ NaN & \text{otherwise} \end{bmatrix}$$

$$\Pi_{\text{HA}}(r,j) = \begin{cases}
\frac{2 \cdot \pi}{Z_{\text{stator}_{j}}} & \text{if } D_{\text{st}(j,2),1} < r < D_{\text{st}(j,2),N_{r}} \\
NaN & \text{otherwise}
\end{cases}$$



```
\nu 0_{\rm M3\Gamma.stator}
                                                                                                                                                                                                                                                                                                                                                                           \nu 0_{\rm M3\Gamma,rotor}
                                                             \nu 0_{
m yr.n.stator}
                                                                                                                                                                                                                                                                                                                                                                           ν0<sub>угл.rotor</sub>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           for i \in 1...Z
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                for r \in av(N_r)

u^0угл.stator_bondage 
u^0угл.rotor_bondage
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            for mode \in 1...6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \nu 0_{\text{M3}\Gamma.\text{stator}_{\hat{1},\,\text{mode}}} = \nu 0_{\text{M3}\Gamma\text{M}\tilde{0}} \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big)\,, \\ E\_\text{blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ Ju_{\text{stator}_{\hat{1},\,r}} \Big) \Big( m_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \Big) \Big( m_{\text{st}(\hat{1},\,2)} \Big) \Big( m_{\text{s
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   \nu 0_{\text{M3}\Gamma.\text{rotor}_{\hat{i}\,,\,\text{mode}}} = \nu 0_{\text{M3}\Gamma\text{M}\delta} \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big)\,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) \Big) \Big( h_{\text{st}(\hat{i}\,,\,3)} \Big) 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  \nu 0_{\text{yrn.stator}_{i,\,\text{mode}}} = \nu 0_{\text{yrn}} \left( \text{mode}\,, 0\,, \text{mean} \left( h_{\text{st}(i,\,1)}\,, h_{\text{st}(i,\,2)} \right), \text{Jung}(2\,, \mu\_\text{steel}\,, E\_\text{blade})\,, \rho\_\text{blade}_i\,, \text{stiffness}_{\text{stator}_{i,\,r}}\,, \text{Jp}_{\text{stator}_{i,\,r}} \right) \right)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \nu 0_{y_{\Gamma JI}.rotor_{\hat{1}},\,mode} = \nu 0_{y_{\Gamma JI}} \left(mode,0,mean\left(h_{st(\hat{1},2)},h_{st(\hat{1},3)}\right),Jung(2,\mu\_steel,E\_blade),\rho\_blade_{\hat{1}},stiffness_{rotor_{\hat{1},r}},Jp_{rotor_{\hat{1},r}}\right) \right)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \nu 0_{\text{YFJI.stator\_bondage}_{i, \, mode}} = \nu 0_{\text{YFJI}} \left( \text{mode} , 1, \text{mean} \left( h_{\text{st}(i, 1)}, h_{\text{st}(i, 2)} \right), \text{Jung}(2, \mu\_\text{steel}, E\_\text{blade}), \rho\_\text{blade}_i, \text{stiffness}_{\text{stator}_{i, r}}, \text{Jp}_{\text{stator}_{i, r}}, \text{Jp}_{\text{stator}_{i,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \nu 0_{\text{YFJI.rotor\_bondage}_{\hat{1}, \, mode}} = \nu 0_{\text{YFJ}} \left( \text{mode} \,, 1 \,, \text{mean} \left( h_{st(\hat{1}, 2)} \,, h_{st(\hat{1}, 3)} \right) \,, \\ \text{Jung}(2 \,, \mu\_\text{steel} \,, E\_\text{blade}) \,, \rho\_\text{blade}_{\hat{1}} \,, \\ \text{stiffness}_{rotor_{\hat{1}, \, r}} \,, \\ \text{Jp}_{rotor_{\hat{1}, \, r}} \,, \\ \text{Jp}_{rotor
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        \nu 0_{\text{изг.rotor}}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \nu 0_{\rm M3\Gamma.stator}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                \nu 0_{y_{\Gamma JI}.stator}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          ν0<sub>угл.rotor</sub>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     \nu_0^0угл.stator bondage \nu_0^0угл.rotor bondage
```

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\operatorname{stack} \left(\nu 0_{\operatorname{M3\Gamma.stator}}, \nu 0_{\operatorname{M3\Gamma.rotor}}\right)^{\mathrm{T}} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 1 & 12595 & 5145 & & & & & \\ 2 & 78937 & 32248 & & & & & \\ 3 & 221049 & 90305 & & & & & \\ 4 & 433492 & 177095 & & & & & \\ 5 & 716300 & 292630 & & & & & \\ 6 & 1069752 & 437026 & & & & & & \\ \end{bmatrix}$$

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\operatorname{stack} \left(\nu 0_{\text{угл.stator}}, \nu 0_{\text{угл.rotor}}\right)^{\text{T}} = \begin{bmatrix} & 1 & 2 \\ 1 & 8364 & 5507 \\ 2 & 25091 & 16521 \\ 3 & 41819 & 27535 \\ 4 & 58546 & 38548 \\ 5 & 75274 & 49562 \\ 6 & 92001 & 60576 \end{bmatrix}$$

$$\mathrm{stack} \Big(\nu 0_{\mathrm{YLT.stator_bondage}}, \nu 0_{\mathrm{YLT.rotor_bondage}}\Big)^{\mathrm{T}} = \begin{bmatrix} & 1 & 2 \\ 1 & 16727 & 11014 \\ 2 & 33455 & 22028 \\ 3 & 50182 & 33041 \\ 4 & 66910 & 44055 \\ 5 & 83637 & 55069 \\ 6 & 100365 & 66083 \\ \end{bmatrix}$$

Вывод результатов расчета собственных частот колебаний Л

Pасчетный узел: type = "turbine"

Объем бандажной полки (м 3): $V_{6\pi} =$

Радиус положения ЦМ бандажной полки (м): $R_{\delta\Pi} = 0$

▶ Расчет Л на прочность —

$$\text{neutral_line(type, x, i, r)} = \begin{vmatrix} y0_{rotor_{i, r}} \\ \frac{y0_{rotor_{i, r}}}{\text{chord}_{rotor_{i, r}}} + \tan\left(\left(\alpha_{major_{rotor_{i, r}}} + \phi_{neutral_{rotor}}(i, R_{st(i, 2), r})\right)\right) \cdot \left(x - \frac{x0_{rotor_{i, r}}}{\text{chord}_{rotor_{i, r}}}\right) \text{ if type} = "rotor"$$

$$\frac{y0_{stator_{i, r}}}{\text{chord}_{stator_{i, r}}} + \tan\left(\left(\alpha_{major_{stator_{i, r}}} + \phi_{neutral_{stator}}(i, R_{st(i, 2), r})\right)\right) \cdot \left(x - \frac{x0_{stator_{i, r}}}{\text{chord}_{stator_{i, r}}}\right) \text{ if type} = "stator"$$

$$\frac{y0_{rotor_{i, r}}}{\text{chord}_{stator_{i, r}}} + \frac{-1}{(x_{major_{stator_{i, r}}})} = \frac{y0_{rotor_{i, r}}}{(x_{major_{stator_{i, r}}})} = \frac{y0_{rotor_{i, r}}}{(x_{ma$$

$$\begin{aligned} & \text{epure(type,x,i,r)} = \boxed{\frac{y0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}} + \frac{-1}{\text{tan}\left(\alpha_\text{major}_{rotor_{i,r}} + \varphi_\text{neutral}_{rotor}\left(i,R_{st(i,2),r}\right) - \frac{\pi}{4}\right)} \cdot \left(x - \frac{x0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}}\right) \text{ if type = "rotor"} \\ & \frac{y0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}} + \frac{-1}{\text{tan}\left(\alpha_\text{major}_{stator_{i,r}} + \varphi_\text{neutral}_{stator}\left(i,R_{st(i,2),r}\right) - \frac{\pi}{4}\right)} \cdot \left(x - \frac{x0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}}\right) \text{ if type = "stator"} \end{aligned}$$

■Определение координат точек профиля Л, наиболее удаленных от НП

Наиболее удаленные точки от НЛ (мм):

$$u_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & -0.218\\ \hline 2 & 0.395\\ \hline 3 & -5.994 \end{bmatrix} \cdot 10^{-3}$$

$$u_{-l_{rotor}}^{T} = \begin{bmatrix} & 1 & \\ 1 & 21.030 \\ \hline 2 & 18.832 \\ \hline 3 & -8.994 \end{bmatrix} \cdot 10^{-3}$$

$$u_{-}u_{stator}^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & & \\ \hline 1 & -7.064 & \\ \hline 2 & 8.165 & \\ \hline 3 & 8.161 & \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{stator}}^{T} = \begin{bmatrix} & 1 & \\ 1 & -11.363 \\ 2 & -25.857 \\ \hline 3 & -25.850 \end{bmatrix} \cdot 10^{-3}$$

$$v_{-}u_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 4.047 \\ \hline 3 \\ 13.959 \end{bmatrix} \cdot 10^{-3}$$

$$v_{-1}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & -11.789 \\ 2 & -10.076 \\ \hline 3 & -17.325 \end{bmatrix} \cdot 10^{-3}$$

$$v_{u_{stator}}^{T} = \begin{bmatrix} & 1\\ 1 & 29.140\\ \hline 2 & 8.190\\ \hline 3 & 8.194 \end{bmatrix} \cdot 10^{-3}$$

$$v_{l_{stator}}^{T} = \begin{bmatrix} 1 \\ 1 \\ -38.695 \\ 2 \\ -14.465 \\ 3 \\ -14.477 \end{bmatrix} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{-Protor} & \sigma_{-n}rotor \\ \sigma_{-Dstator} & \sigma_{-n}rotor \\ \sigma_{-Dstator}$$

$$\begin{pmatrix} \sigma_{-} P_{rotor.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{stator.} \end{pmatrix} = \begin{bmatrix} \text{for } i \in 1 ... Z \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{stator.} \end{bmatrix} = \begin{bmatrix} \text{for } i \in 1 ... Z \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{stator.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{stator.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{stator.} & \sigma_{-} P_{stator.} \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{rotor.} & \sigma_{-} P_{rotor.} \\ \sigma_{-} P_{rotor.} & \sigma_{-} P_{rotor.} & \sigma_{-} P_{rotor.} &$$

$$\sigma_{p_{rotor}}^{T} = \begin{array}{|c|c|}\hline & 1 \\\hline 1 & -18.45 \\\hline 2 & -8.87 \\\hline 3 & 0.00 \\\hline \end{array} \cdot 10^{6}$$

$$\sigma_{-n_{rotor}}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 40.41 \\ 2 & 21.85 \\ \hline 3 & 0.00 \end{bmatrix} \cdot 10^{6}$$

		1	
$\sigma_{\text{ntor}}^{\text{T}} \le 70 \cdot 10^6 =$	1	1	
-rotor - / s 13	2	1	
	3	1	

$$\sigma_{p_{stator}}^{T} = \begin{bmatrix} 1 \\ 1 \\ 0.00 \\ 2 \\ 3.47 \\ 3 \end{bmatrix} \cdot 10^{6}$$

		1
$\sigma p_{\text{ototor}} \leq 70 \cdot 10^6 =$	1	1
$\sigma_p_{\text{stator}} \leq /0.10 =$	2	1
	3	1

$$\sigma_{\text{nstator}}^{\text{T}} = \begin{bmatrix} 1 & 1 \\ 1 & 0.00 \\ 2 & -7.07 \\ \hline 3 & -28.26 \end{bmatrix} \cdot 10^{6}$$

		1
$\sigma = 0.410^6 = 0.001$	1	1
$\sigma_{\text{nstator}} \leq /0.10 =$	2	1
	3	1

$$\begin{pmatrix} \sigma_{rotor} \\ \sigma_{stator} \end{pmatrix} = \begin{cases} \text{for } i \in 1...Z \\ \text{for } r \in 1...N_r \end{cases}$$

$$\begin{pmatrix} \sigma_{rotor_{i,r}} = \sqrt{\left(\sigma_{rotor}(i,R_{st(i,2),r}) + \max\left(\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}}\right)\right)^2 + \tau_{rotor}(i,R_{st(i,2),r})^2}$$

$$\begin{pmatrix} \sigma_{stator_{i,r}} = \sqrt{\left(0 + \max\left(\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}}\right)\right)^2 + \tau_{stator}(i,R_{st(i,2),r})^2} \\ \begin{pmatrix} \sigma_{rotor} \\ \sigma_{stator} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{rotor_{i,r}} = \sqrt{\left(0 + \max\left(\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}}\right)\right)^2 + \tau_{stator_{i,r}}(i,R_{st(i,2),r})^2} \\ \begin{pmatrix} \sigma_{rotor_{i,r}} = \sqrt{\left(0 + \max\left(\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}},\sigma_{rotor_{i,r}}\right)\right)^2 + \tau_{stator_{i,r}}(i,R_{st(i,2),r})^2} \\ \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{rotor.} \\ \sigma_{stator.} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \\ \sigma_{rotor.}(i,z) = \text{interp} \Big(\text{lspline} \Big(\text{submatrix} \Big(R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big(\sigma_{rotor}, i, i, 1, N_r \Big)^T \Big), \text{submatrix} \Big(R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big(\sigma_{rotor}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big(R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big(R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big(\sigma_{stator.}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big(\sigma_{rotor.}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big(\sigma_{stator.}, i, i, 1, N_r$$

$$\sigma_{\text{rotor}}^{\text{T}} = \begin{vmatrix} & 1 \\ 1 & 161.59 \\ 2 & 101.72 \\ \hline 3 & 0.00 \end{vmatrix} \cdot 10$$

$$\sigma_{\text{stator}}^{\text{T}} = \begin{vmatrix} 1 & 1 \\ 1 & 0.00 \\ 2 & 5.61 \\ 3 & 16.44 \end{vmatrix} \cdot 10^{6}$$

$$\begin{vmatrix} safety_{rotor} \\ safety_{stator} \end{vmatrix} = \begin{vmatrix} for \ i \in 1...Z \\ for \ r \in 1...N_r \end{vmatrix}$$

$$\begin{vmatrix} safety_{rotor} \\ i,r \end{vmatrix} = \begin{vmatrix} \frac{\sigma_blade_long_i}{\sigma_{rotor}} & if \ \sigma_{rotor} \\ \infty & otherwise \end{vmatrix}$$

$$safety_{stator} \\ i,r \end{vmatrix} = \begin{vmatrix} \frac{\sigma_blade_long_i}{\sigma_{stator}} & if \ \sigma_{stator} \\ \infty & otherwise \end{vmatrix}$$

$$\begin{vmatrix} safety_{rotor} \\ safety_{stator} \end{vmatrix}$$

$$contact$$

$$contact$$

		1
safety T	1	000000000000000000000000000000000000000
safety _{stator} =	2	36.53
	3	12.47

		1	
$safety_{rotor}^{T} \ge safety =$	1	0	
rotor = surety	2	1	
	3	1	

		1	
$safety_{stator}^{T} \ge safety =$	1	1	
salety stator – salety	2	1	
	3	1	

Рассматриваемая ступень:
$$j=1$$
 if type = "compressor" = 1 Z if type = "turbine" $j=1$ "Такой ступени не существует!" if $(j<1)\vee(j>Z)$ j otherwise

$$b_{\text{Line}} = \frac{\text{ceil}\left(\text{max}\left(\text{chord}_{rotor_{j,N_r}}, \text{chord}_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

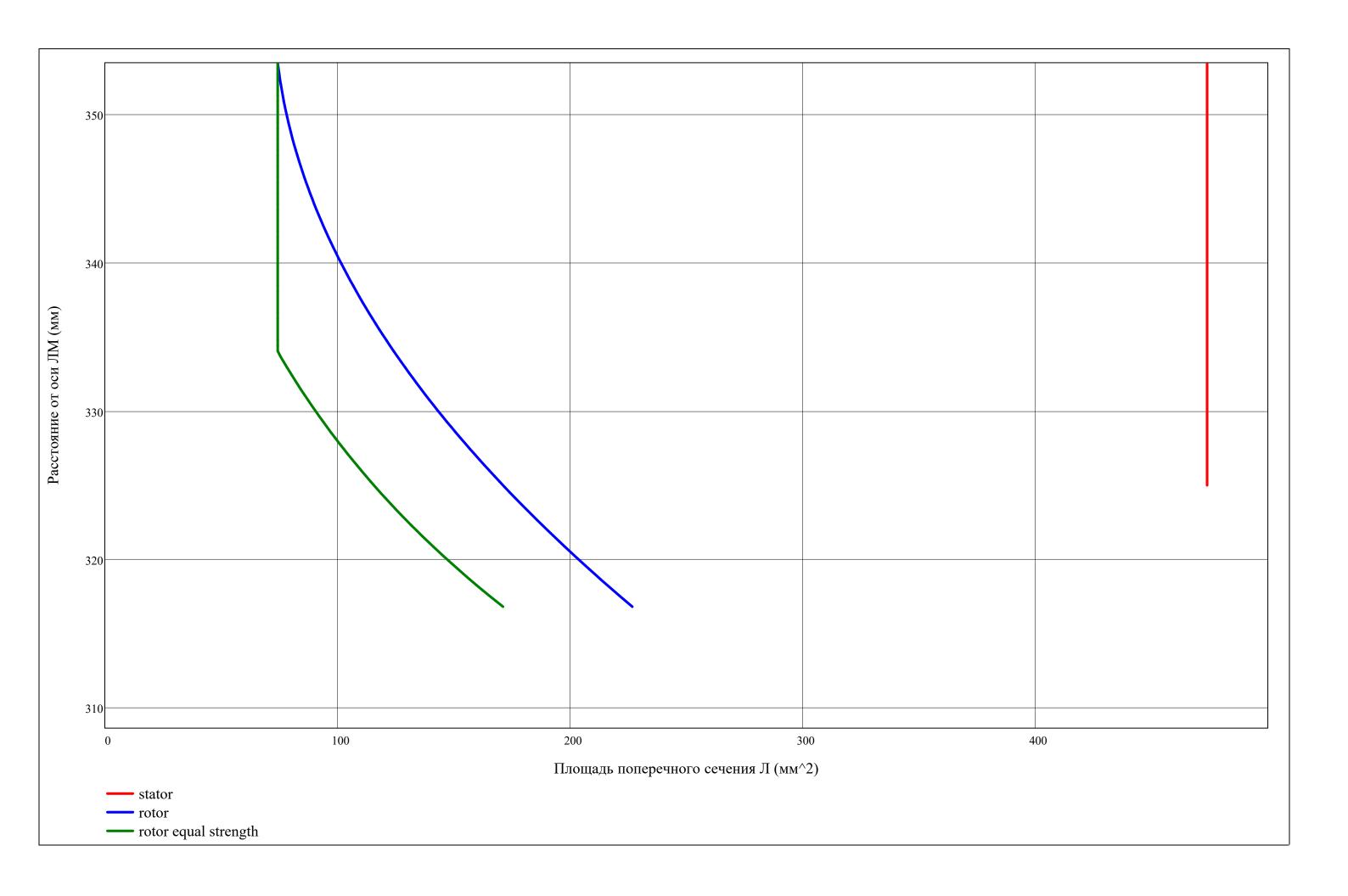
$$Rj = submatrix (R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r) = \begin{vmatrix} 1 & 2 & 3 \\ 1 & 325.0 & 339.2 & 353.5 \\ 2 & 325.0 & 339.2 & 353.5 \\ 3 & 308.6 & 331.0 & 353.5 \end{vmatrix} \cdot 10^{-3}$$

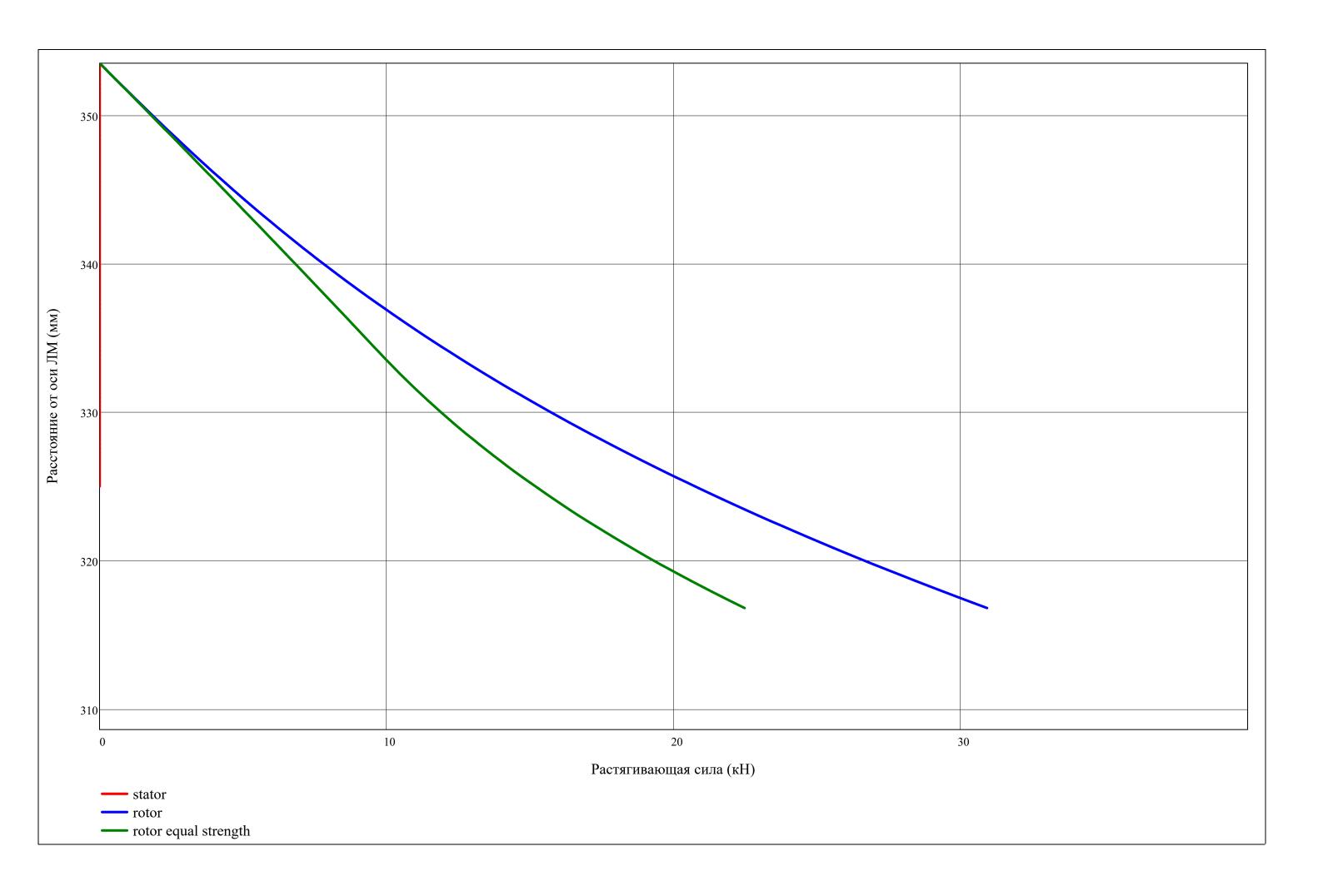
Дискретизация по высоте Л:

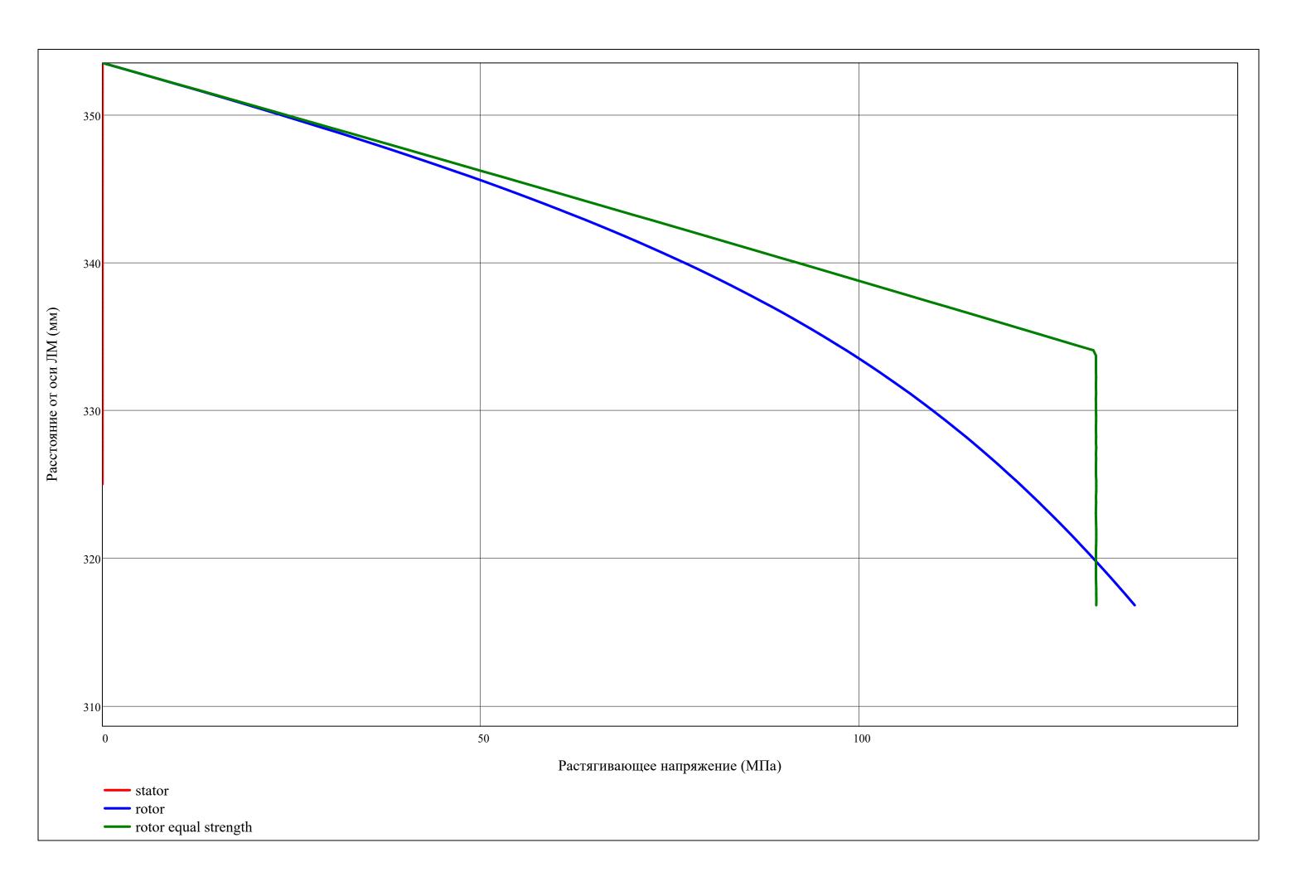
$$z = min(Rj), min(Rj) + \frac{max(Rj) - min(Rj)}{100} ... max(Rj)$$

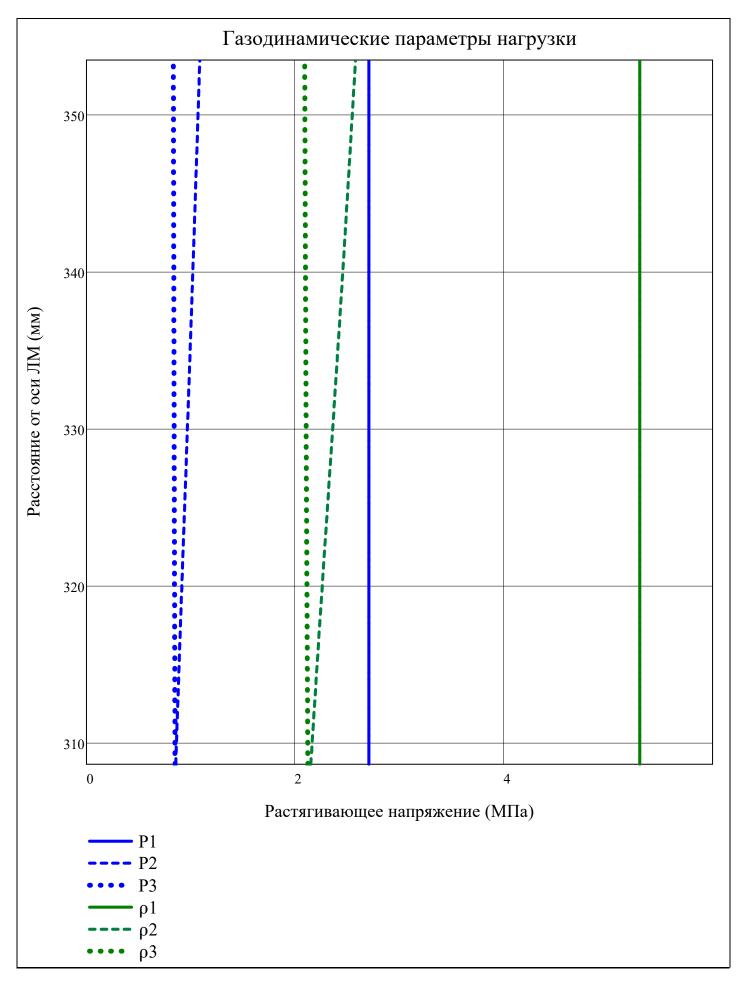
$$z_{rotor} = \begin{vmatrix} mean \left(Rj_{1,1}, Rj_{2,1}\right), mean \left(Rj_{1,1}, Rj_{2,1}\right) + \frac{mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) - mean \left(Rj_{1,1}, Rj_{2,1}\right)}{100} ... mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) \text{ if type = "compressor"} \\ mean \left(Rj_{2,1}, Rj_{3,1}\right), mean \left(Rj_{2,1}, Rj_{3,1}\right) + \frac{mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) - mean \left(Rj_{2,1}, Rj_{3,1}\right)}{100} ... mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) \text{ if type = "turbine"} \\ 100 \end{aligned}$$

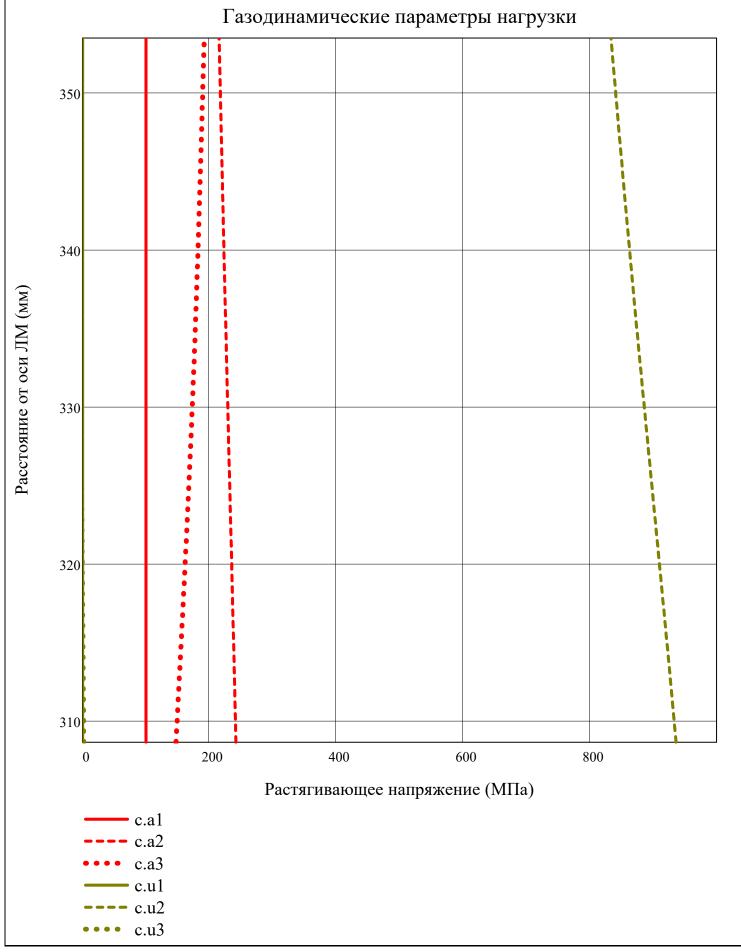
$$z_{stator} = \begin{bmatrix} mean \left(Rj_{2,1}, Rj_{3,1}\right), mean \left(Rj_{2,1}, Rj_{3,1}\right) + \frac{mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) - mean \left(Rj_{2,1}, Rj_{3,1}\right)}{100} ... mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) & \text{if type} = "compressor" \\ mean \left(Rj_{1,1}, Rj_{2,1}\right), mean \left(Rj_{1,1}, Rj_{2,1}\right) + \frac{mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) - mean \left(Rj_{1,1}, Rj_{2,1}\right)}{100} ... mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) & \text{if type} = "turbine" \\ \end{bmatrix}$$

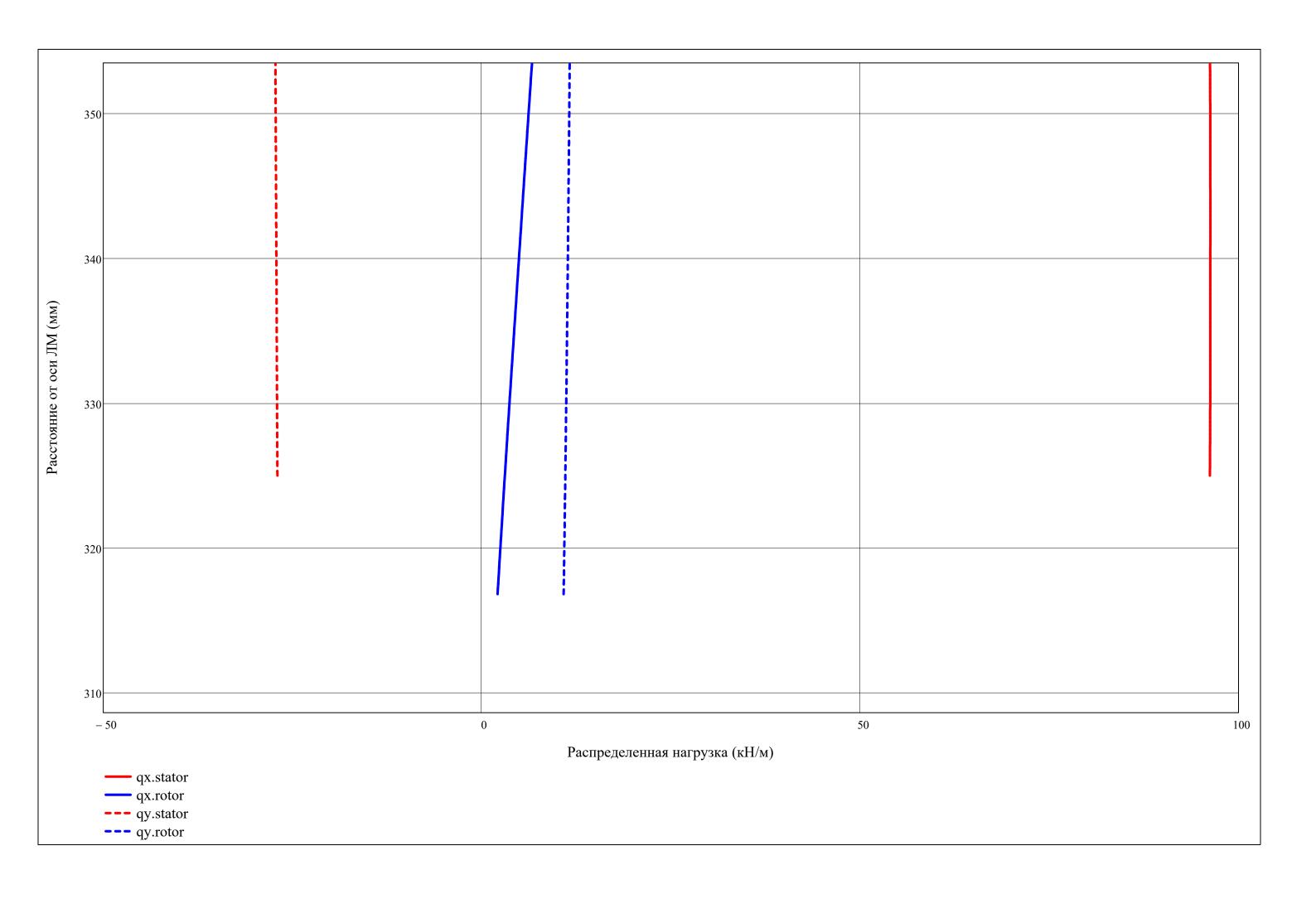


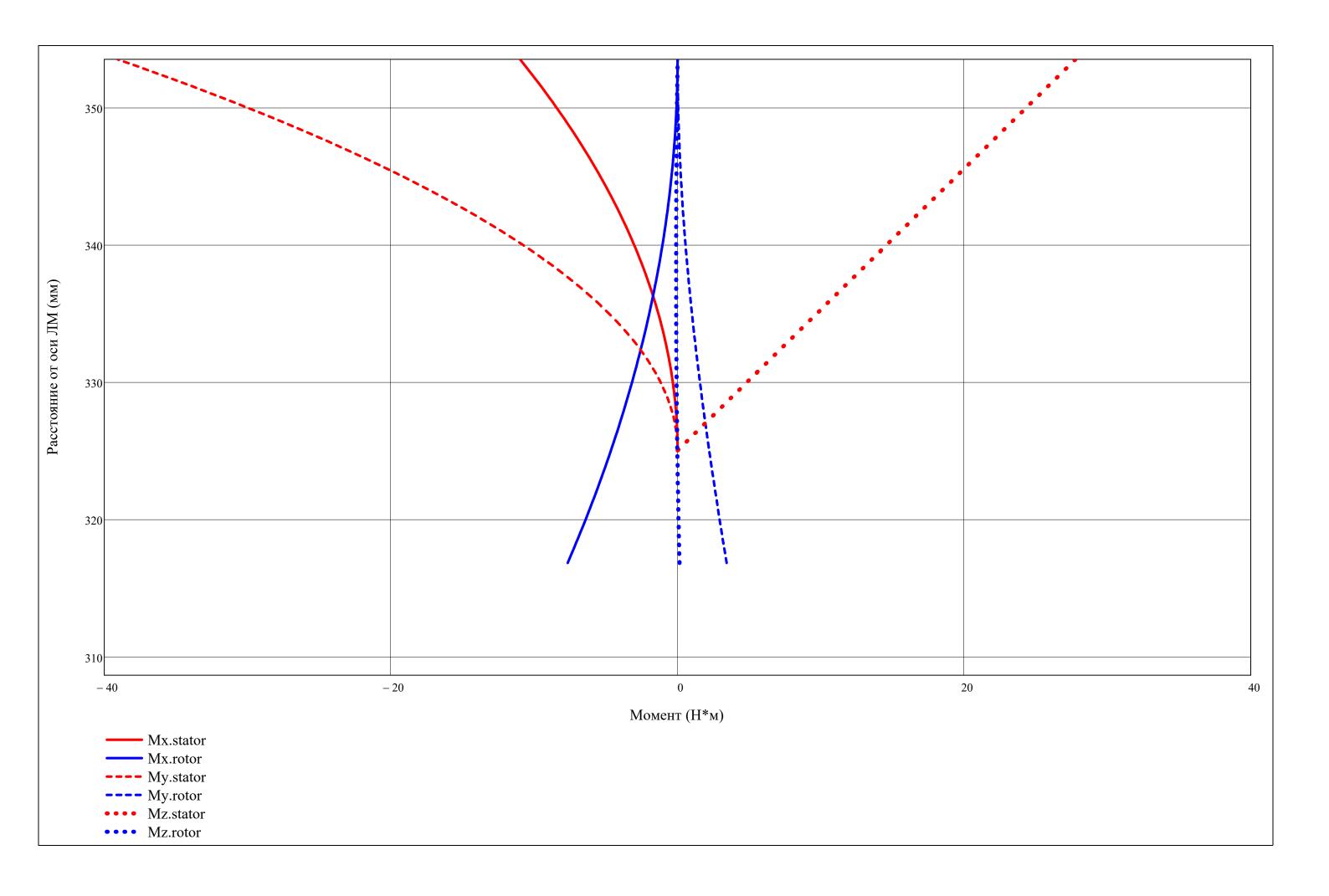


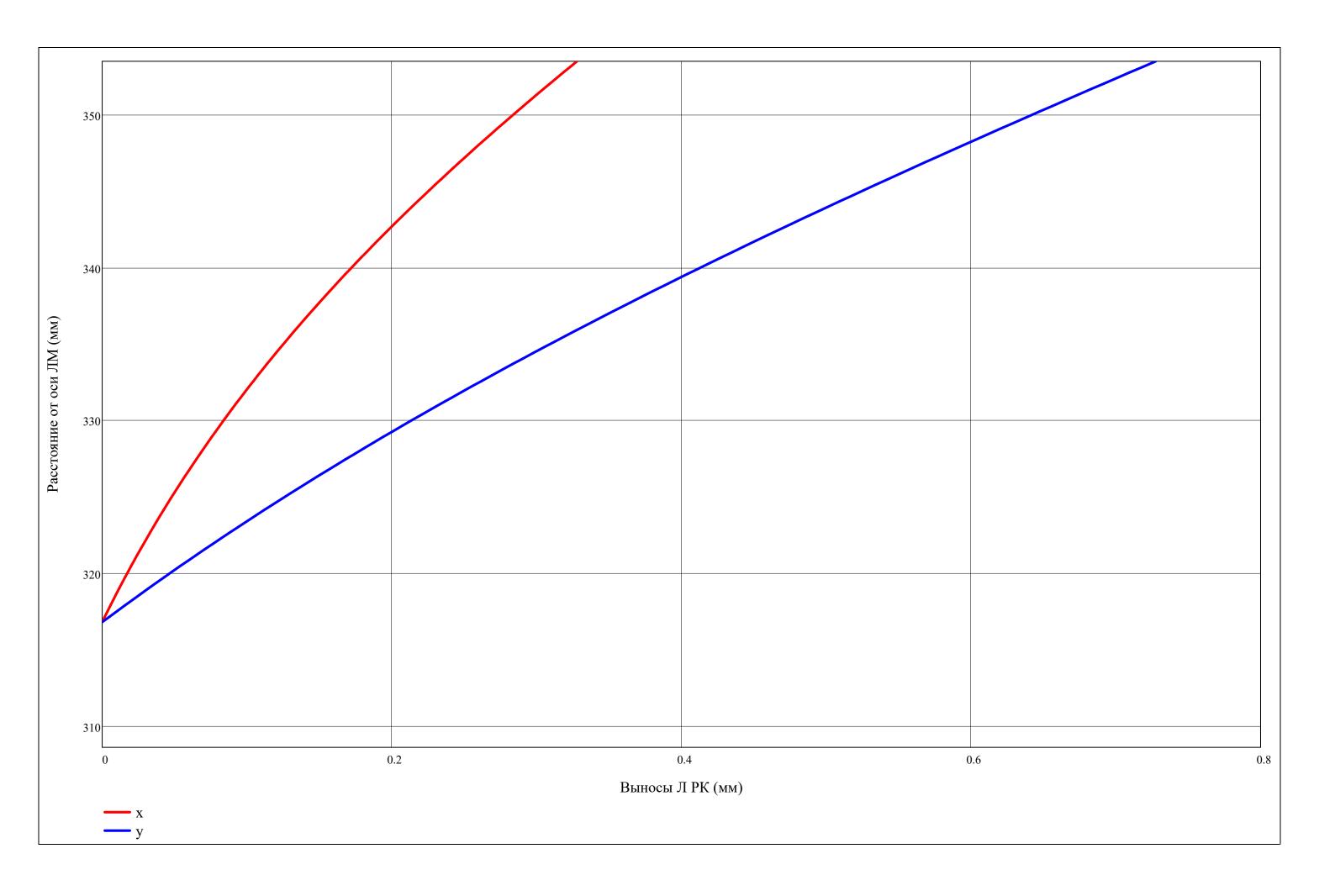


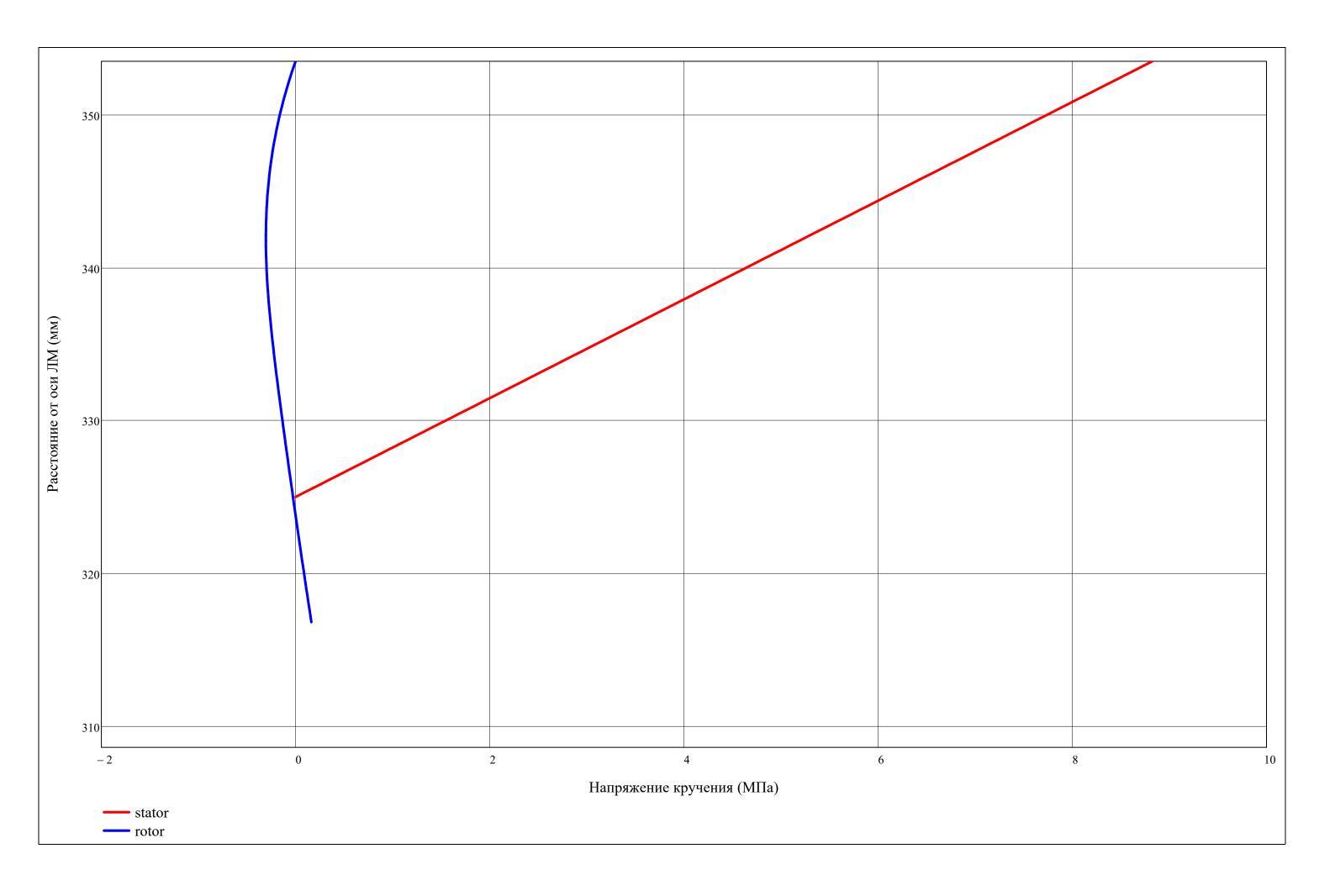


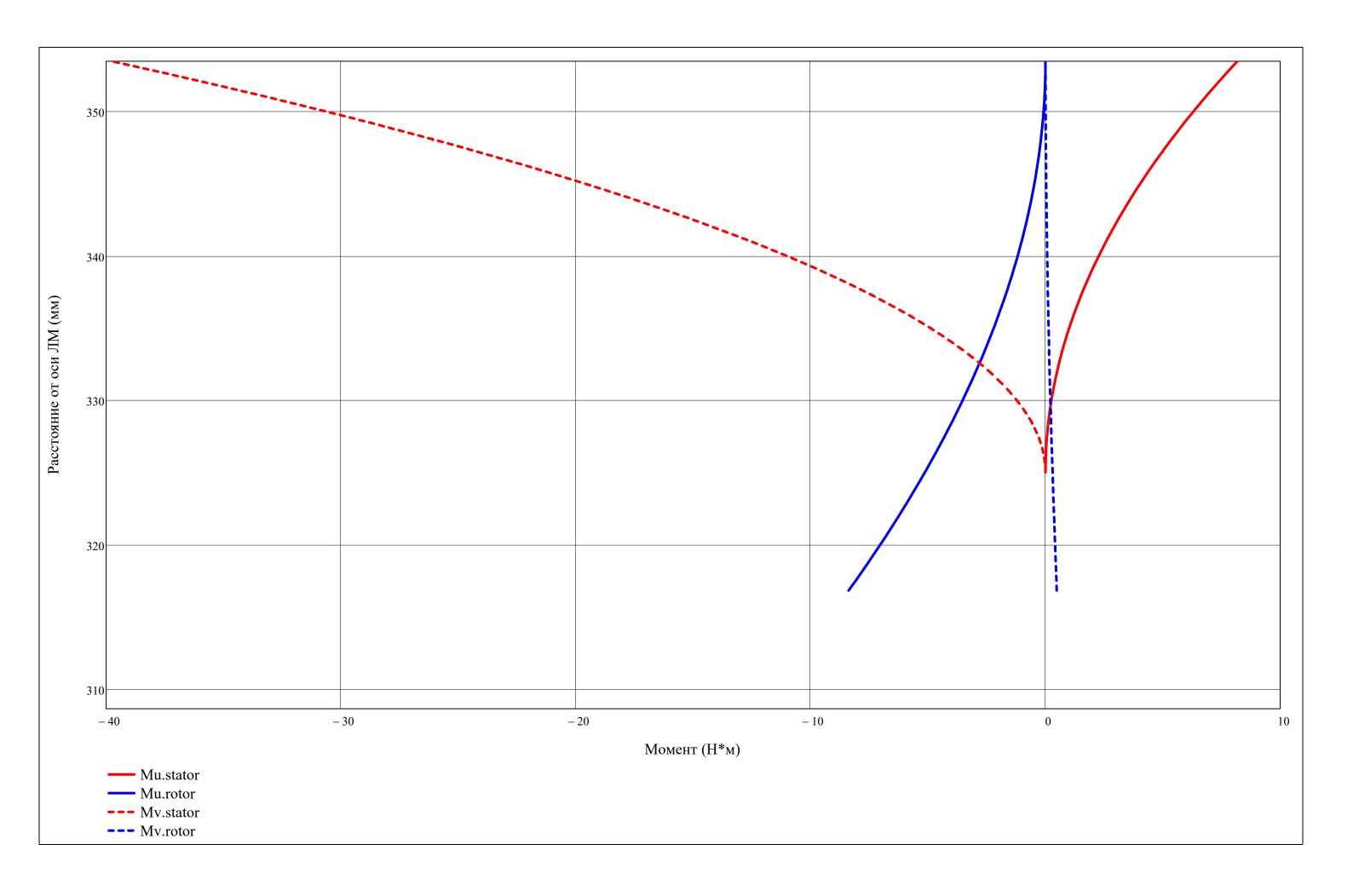


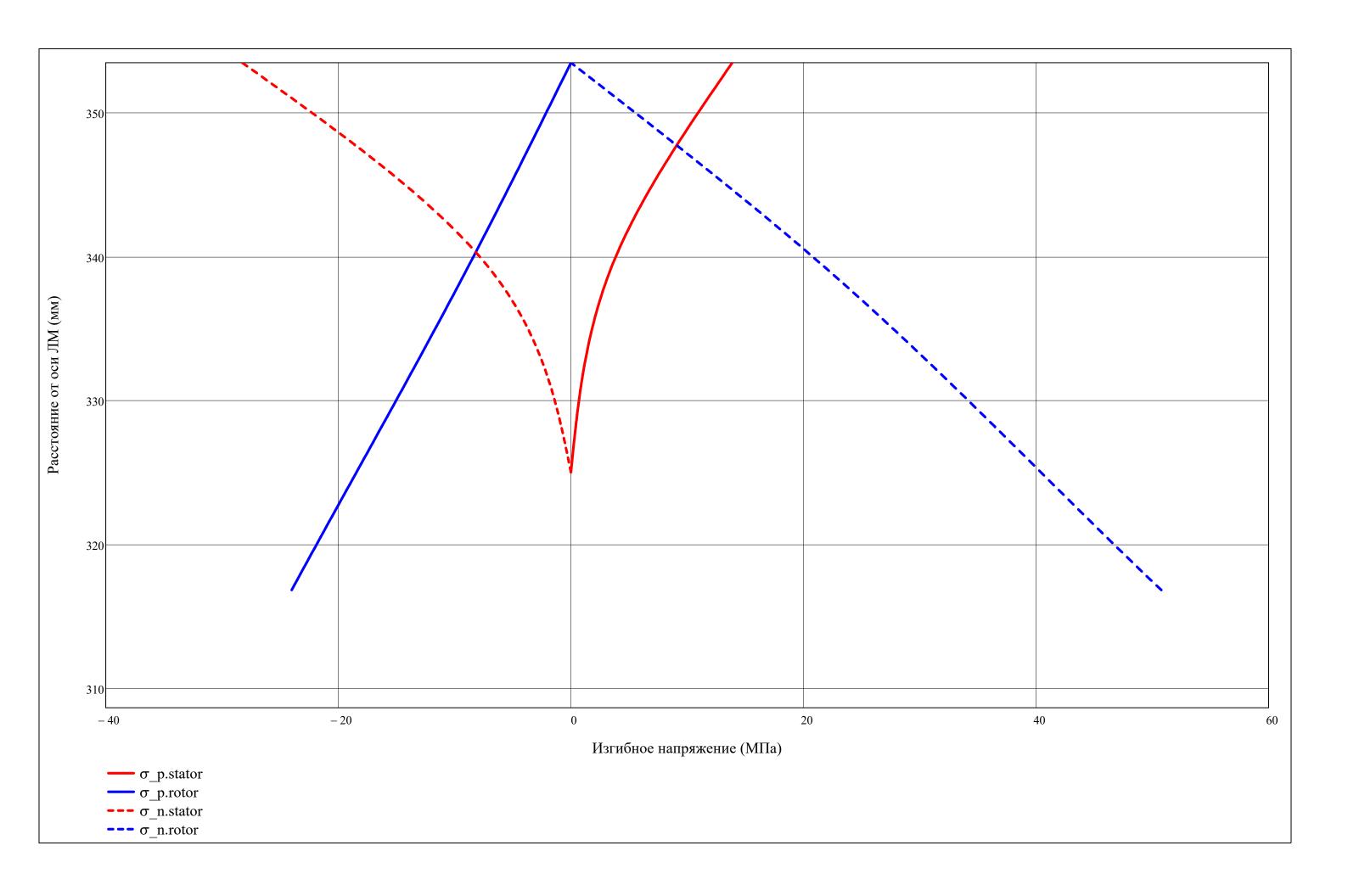


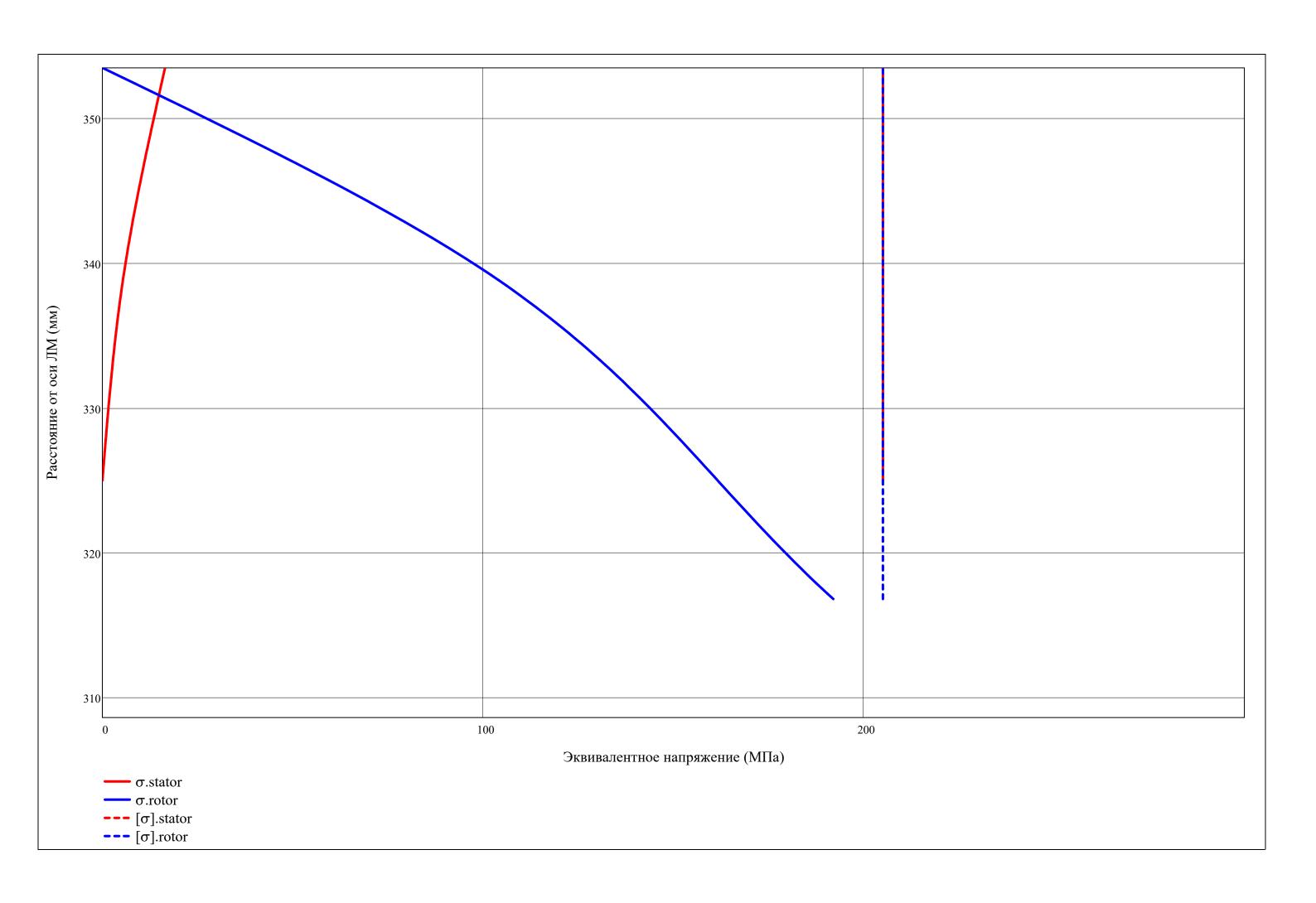








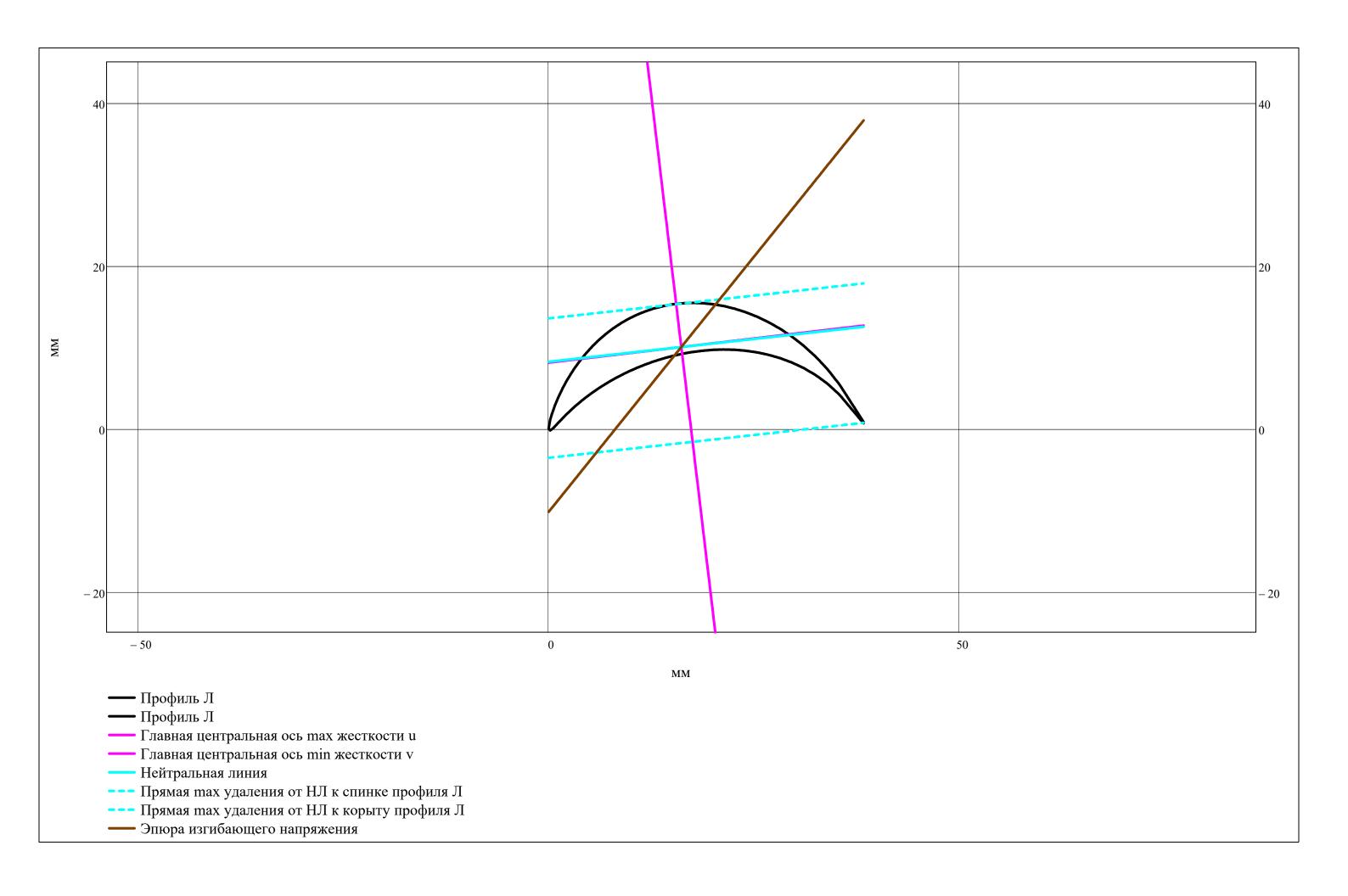




$$\begin{pmatrix} blade \\ r \end{pmatrix} = \begin{pmatrix} "rotor" \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} v_{-}p \\ v_{-}n \end{pmatrix} = \begin{pmatrix} v_{-}u_{rotor_{j},r} \\ v_{-}l_{rotor_{j},r} \\ v_{-}l_{stator_{j},r} \end{pmatrix} \text{ if blade = "rotor" } = \begin{bmatrix} \frac{1}{1} & 5.323 \\ \frac{1}{2} & -11.789 \end{bmatrix} \cdot 10^{-3} \qquad \begin{pmatrix} x_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \\ y_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \\ y_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \\ y$$

chord =
$$\begin{vmatrix} \text{chord}_{\text{rotor}_{j,r}} & \text{if blade} = \text{"rotor"} \\ \text{chord}_{\text{stator}_{j,r}} & \text{if blade} = \text{"stator"} \end{vmatrix}$$



Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{-} v_{rotor_{j},r} & v_{-} v_{rotor_{j},r} \\ u_{-} v_{rotor_{j},r} & v_{-} v_{rotor_{j},r} \\ u_{-} v_{stator_{j},r} & v_{-} v_{stator_{j},r} \\ u_{-} v_{stator_{j},r} & v_{-} v_{stator_{j},r} \\ u_{-} v_{stator_{j},r} & v_{-} v_{stator_{j},r} \\ v_{-} v_{-} v_{stator_{j},r} & v_{-} v_{stator_{j},r} \\ v_{-} v$$

Вывод результатов расчета Л на прочность

▼ Выбор материала Д

Запас по температуре (K): $\Delta T_{\text{safety}} = 0$

Выбранный материал Д: material_disk_i = "ВЖ175" if turbine = "ТВД" "ЭП742" if turbine = "ТНД"

Плотность материала Д (кг/м^3):

$$\rho_disk_i = \begin{bmatrix} 8266 & if material_disk_i = "BЖ175" \\ 8320 & if material_disk_i = "ЭП742" \\ 8393 & if material_disk_i = "ЖС-6К" \\ 7900 & if material_disk_i = "BT41" \\ 4500 & if material_disk_i = "BT25" \\ 4570 & if material_disk_i = "BT23" \\ 4510 & if material_disk_i = "BT9" \\ 4430 & if material_disk_i = "BT6" \\ NaN & otherwise \\ \end{bmatrix}$$

$$\rho_{disk}^T = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 8266 \end{array}}$$

$$\sigma_disk_long^T = \boxed{\begin{array}{c|c} 1 \\ \hline 1 \\ \hline \end{array}} \cdot 10^6$$

Предел длительной прочности Д (Па):

$$\sigma_{disk_long_i} = 10^6 \cdot \begin{vmatrix} 620 & \text{if material_disk}_i = "BK175" \\ 680 & \text{if material_disk}_i = "ЭП742" \\ 125 & \text{if material_disk}_i = "KC-6K" \\ 123 & \text{if material_disk}_i = "BT41" \\ 150 & \text{if material_disk}_i = "BT25" \\ 230 & \text{if material_disk}_i = "BT23" \\ 200 & \text{if material_disk}_i = "BT9" \\ 210 & \text{if material_disk}_i = "BT6" \\ NaN & \text{otherwise} \end{vmatrix}$$

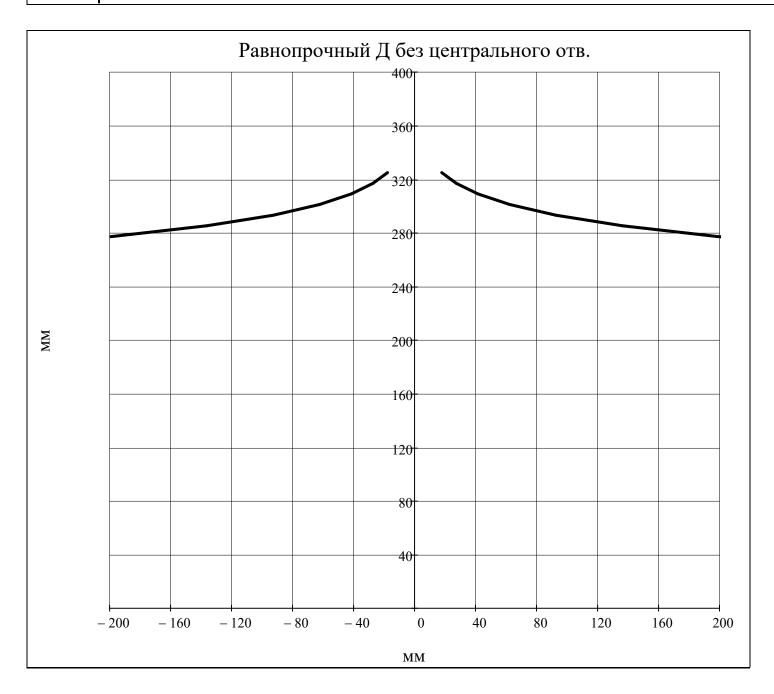
Рассматриваемая ступень:
$$j_w = \begin{cases} j = Z \\ j = \end{cases}$$
 "Такой ступени не существует!" if $(j < 1) \lor (j > Z)$

▼ Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{pmatrix} chord_{rotor_{i},ORIGIN} \cdot sin \Big(\upsilon_{rotor_{i},ORIGIN}\Big) \Big) \cdot e^{\frac{\rho_{-}disk_{i} \cdot \omega^{2}}{2} \cdot \frac{1}{\sigma_{-}z_{rotor}(i,R_{st(i,2),ORIGIN})} \cdot \Big[\big(R_{st(i,2),ORIGIN}\big)^{2} - z^{2} \big]} \\ \text{if } z \leq R_{st(i,2),ORIGIN} \end{pmatrix}$$

$$NaN \quad otherwise$$

$$z = 0, \frac{R_{st(j,2),ORIGIN}}{N_{dis}} .. R_{st(j,2),ORIGIN}$$



Рассматриваемая ступень: j = j = 1

$$j = 1$$
 = 1 $j = 1$ = 1 $j = 1$ Taкой ступени не существует!" if $(j < 1) \lor (j > Z)$ j otherwise

▶-

Приведенная скорость по профилю Л

D.... Общие параметры охлаждения

— В параметры охлаждения

— В параметры охлаждения

— В параметры охлаждения

Конвективное охлаждение ——



▶ Результаты конвективного охлаждения		

ГКонвективно-пленочное охлаждение —

▶ Результат конвективно-пленочного охлаждения ———

Вывод результатов охлаждения

		1	2	3	4
$D^{T} =$	1	650.0	650.0	617.2	
	2	678.5	678.5	662.1	
	3	707.0	707.0	707.0	

$$R = \frac{D}{2}$$

$$R^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 & 4 \\ \hline 1 & 325.0 & 325.0 & 308.6 \\ \hline 2 & 339.2 & 339.2 & 331.0 \\ \hline 3 & 353.5 & 353.5 & 353.5 \\ \hline \end{array}$$

$$\overline{d} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } a \in 1..3 \end{cases}$$

$$\overline{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$$

$$\overline{d}$$

$\overline{d}^T \leq 0.9 =$		1	2	3
	1	0	0	1

$$\mathbf{h} = \begin{bmatrix} \text{for } i \in 1 ... 2Z + 1 \\ \\ \mathbf{h}_i = \frac{F_i}{\pi \cdot D_{i, av(N_r)}} \end{bmatrix}$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 927.16 \\ 147.28 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 231.94 \\ 147.27 \end{pmatrix}$$

$$\begin{pmatrix} W_{st(j,1),r} \\ W_{st(j,2),r} \\ W_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 520.18 \\ 451.35 \\ 504.94 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.49 \\ 89.31 \end{pmatrix} \cdot \circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 510.48 \\ 510.48 \\ 484.75 \end{pmatrix}$$

$$\begin{pmatrix}
\beta_{st(j,1),r} \\
\beta_{st(j,2),r} \\
\beta_{st(j,3),r}
\end{pmatrix} = \begin{pmatrix}
11.08 \\
149.08 \\
16.96
\end{pmatrix}$$

$$\varepsilon_{\mathrm{stator}_{j,r}} = 75.51^{\circ}$$

$$\varepsilon_{\text{rotor}_{j,r}} = 132.12^{\circ}$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 892.55 \\ 174.05 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 223.28 \\ 174.03 \end{pmatrix}$$

$$\begin{pmatrix} W_{st(j,1),r} \\ W_{st(j,2),r} \\ W_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 542.17 \\ 399.52 \\ 550.87 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.49 \\ 90.87 \end{pmatrix}$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 532.86 \\ 532.86 \\ 520.00 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 10.63 \\ 146.02 \\ 18.42 \end{pmatrix} \cdot \circ$$

$$\varepsilon_{\mathrm{stator}_{j,r}} = 75.51^{\circ}$$

$$\varepsilon_{\text{rotor}_{j,r}} = 127.61^{\circ}$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 860.58 \\ 191.81 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 215.28 \\ 191.70 \end{pmatrix}$$

$$\begin{pmatrix} W_{st(j,1),r} \\ W_{st(j,2),r} \\ W_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 564.18 \\ 351.59 \\ 593.43 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.49 \\ 91.90 \end{pmatrix} \cdot \circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 555.25 \\ 555.25 \\ 555.25 \end{pmatrix}$$

$$\begin{pmatrix}
\beta_{st(j,1),r} \\
\beta_{st(j,2),r} \\
\beta_{st(j,3),r}
\end{pmatrix} = \begin{pmatrix}
10.21 \\
142.24 \\
18.85
\end{pmatrix}$$

$$\varepsilon_{\mathrm{stator}_{j,r}} = 75.51^{\circ}$$

$$\varepsilon_{\text{rotor}_{j,r}} = 123.4^{\circ}$$

00000000.0