```
▼ Исходные данные
```

Коэф. запаса: safety = 1.3turbine = "ТВД" Горючее: Fuel = "Керосин" Высота движения (м):  $H_{11} = 0$ 32.30 Массовый расход перед Т (кг/с): 32.30 if turbine = "ТВД" Массовый расход утечек Т (кг/с): 106.96.10 0.11 G<sub>cooling</sub> Массовый расход на охл Т (кг/с): 3.24 if turbine = "ТНД"  $N_T = 10^6 \cdot 14.893$  if turbine = "TBД" =  $14.893 \cdot 10^6$ Мощность Т (Вт): 15.181 if turbine = "ТНД"  $P_{\Gamma}^* = 10^3 \cdot |2731.8 \text{ if turbine} = "TBД" = 2731.8 \cdot 10^3$ Полное давление перед Т (Па): 927.5 if turbine = "ТНД"  $T^*_{\Gamma} = \begin{vmatrix} 1773 & \text{if turbine} = "ТВД" = 1773.0 \\ 1368.9 & \text{if turbine} = "ТНД" \end{vmatrix}$ Полная температура перед Т (К):  $\alpha_{\rm ox} = 2.267$  if turbine = "ТВД" = 2.267 Коэф. избытка воздуха в Т: 2.493 if turbine = "ТНД"  $P^*_{\text{cooling}} = 10^3 \cdot | 2845.6 \text{ if turbine} = "ТВД" = 2845.6 \cdot 10^3$ Полное давление отбора охлаждающего воздуха (К): 319.4 if turbine = "ТНД" 806.9 if turbine = "ТВД" = 806.9 Полная температура отбора охлаждающего воздуха (К): T\*cooling = 418.2 if turbine = "ТНД"  $\sigma_{\text{cooling}} = 0.97$ Коэф. сохранения полного давления охлаждения: Подогрев охл. от КС [К]:  $\Delta T_{\text{охл.подогрев}} = 40$ Газовая постоянная (Дж/кг/К):  $R_{\Gamma a3}(\alpha_{ox}, Fuel) = 288.5$ 

 $T_{\Pi, \text{ДО}\Pi} = 1373$ 

Допустимая температура Л (К):

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

$$80 \le c_T \le 400 = 1$$

Лопаточный КПДТ:  $\eta_{\Pi} = 88\%$ 

$$\eta_{\pi} = 88\%$$

# $88\% \le \eta_{\rm JI} \le 95\% = 1$

Угол входа в Т:  $\alpha_{\Gamma} = 90$ .  $^{\circ}$ 

$$\alpha_{\Gamma} = 90.^{\circ}$$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_{\rm T} \\ c_{\rm T} \end{pmatrix} = \begin{pmatrix} 100 \\ 180 \end{pmatrix}$$
 if turbine = "ТВД"  $= \begin{bmatrix} 1 \\ 1 \\ 100.0 \\ 2 \\ 180.0 \end{bmatrix}$   $\begin{pmatrix} 180 \\ 260 \end{pmatrix}$  if turbine = "ТНД"

$$u_{\rm T} = \begin{bmatrix} 520 & \text{if turbine} = "ТВД" = 520.0 \\ 260 & \text{if turbine} = "ТНД" \end{bmatrix}$$



$$z = ORIGIN...N_r$$

 $P^*_{\text{cooling}} = P^*_{\text{cooling}} \cdot \sigma_{\text{cooling}} = 2760.2 \cdot 10^3$ Полное давление отбора охлаждающего воздуха (К):

 $T^*_{\text{cooling}} = T^*_{\text{cooling}} + \Delta T_{\text{охл.подогрев}} = 846.9$ Полная температура отбора охлаждающего воздуха (К):

 $G_{\Gamma} = G_{\Gamma} - G_{leak} = 32.2$ Массовый расход перед Т (кг/с):

 $G_{T} = G_{\Gamma} + G_{cooling} = 35.4$ Массовый расход после Т (кг/с):

Удельная работа T (Дж/кг):  $L^*_T = \frac{N_T}{\text{mean} \left(G_\Gamma, G_T\right)} = 440.4 \cdot 10^3$   $L^*_T \leq 550 \cdot 10^3 = 1$  Располагаемый теплоперепад в T (Дж/кг):  $H_T = \frac{L^*_T + 0.5c_T^2}{\eta_{_{I\!\!I}}} = 518.9 \cdot 10^3$ 

$$\begin{vmatrix} \text{iteration} \\ k_{\Gamma} \\ P_{\Gamma} \\ T_{\Gamma} \end{vmatrix} = \begin{vmatrix} \text{iteration} = 0 \\ k_{\Gamma} = k_{a,\Pi} \left( \text{Cp}_{\Gamma a3} \left( \text{P*}_{\Gamma}, \text{T*}_{\Gamma}, \alpha_{\text{OX}}, \text{Fuel} \right), \text{R}_{\Gamma a3} \left( \alpha_{\text{OX}}, \text{Fuel} \right) \right) \\ \text{while } 1 > 0 \end{vmatrix} = \begin{vmatrix} \frac{1}{1} & \frac{1.0}{2} & \frac{1.3}{3} & \frac{3}{2705198.4} \\ \text{while } 1 > 0 \end{vmatrix} \\ \begin{vmatrix} \text{Iteration} = \text{iteration} + 1 \\ \text{Cp}_{\Gamma} = \frac{k_{\Gamma}}{k_{\Gamma} - 1} \cdot \text{R}_{\Gamma a3} \left( \alpha_{\text{OX}}, \text{Fuel} \right) \end{vmatrix} \\ T_{\Gamma} = T^*_{\Gamma} - \frac{c_{\Gamma}^2}{2 \cdot \text{Cp}_{\Gamma}} \\ k^*_{\Gamma} = k_{a,\Pi} \left( \text{Cp}_{\Gamma a3} \left( \text{P}_{\Gamma}, \text{T}_{\Gamma}, \alpha_{\text{OX}}, \text{Fuel} \right), \text{R}_{\Gamma a3} \left( \alpha_{\text{OX}}, \text{Fuel} \right) \right) \\ \text{if } \left| \text{eps} \left( \text{"rel"}, k_{\Gamma}, k_{\Gamma} \right) \right| \leq \text{epsilon} \\ k_{\Gamma} = k'_{\Gamma} \\ \text{break} \\ k_{\Gamma} = k'_{\Gamma} \\ \text{(iteration } k_{\Gamma} \mid \text{P}_{\Gamma} \mid \text{T}_{\Gamma} \right)^{T} \end{vmatrix}$$

Количество итераций: iteration = 1

Показатель адиабаты перед Т:  $\mathbf{k}_{\Gamma} = 1.283$ 

Статическое давление перед Т (Па):  $P_{\Gamma} = 2705.2 \cdot 10^3$ 

Статическая температура перед T(K):  $T_{\Gamma} = 1769.2$ 

Теплоем кость перед Т (Дж/кг/К):  $Cp_{\Gamma} = Cp_{\Gamma a3}(P_{\Gamma}, T_{\Gamma}, \alpha_{oX}, Fuel) = 1309$ 

$$\begin{vmatrix} k_{\rm T} \\ P_{\rm T} \\ T_{\rm T} \end{vmatrix} = \begin{vmatrix} \text{iteration} = 0 \\ k_{\rm T} = k_{\rm F} \\ \text{while } 1 > 0 \\ \\ | \text{iteration} = \text{iteration} + 1 \\ k_{\rm cp} = \text{mean}(k_{\rm F}, k_{\rm T}) \\ | C_{\rm P} = \frac{k_{\rm cp}}{k_{\rm cp} - 1} \cdot R_{\rm Fa3}(\alpha_{\rm ox}, \text{Fuel}) \\ | P_{\rm T} = P^*_{\Gamma} \cdot \left(1 - \frac{H_{\rm T}}{C_{\rm P} \cdot T^*_{\rm F}}\right)^{\frac{k_{\rm cp}}{k_{\rm cp} - 1}} \\ | T_{\rm T} = T^*_{\rm T} - \frac{H_{\rm T} \cdot \eta_{\rm II}}{C_{\rm p}} \\ | k^*_{\rm T} = k_{\rm ag} \left(C_{\rm Pra3}(P_{\rm T}, T_{\rm T}, \alpha_{\rm ox}, \text{Fuel}), R_{\rm Fa3}(\alpha_{\rm ox}, \text{Fuel})\right) \\ | \text{if } | \exp(\text{"rel"}, k_{\rm T}, k^*_{\rm T})| \leq \text{epsilon} \\ | k_{\rm T} = k^*_{\rm T} \\ | \text{break} \\ | k_{\rm T} = k^*_{\rm T} \\ | \text{(iteration } k_{\rm T} \cdot P_{\rm T} \cdot T_{\rm T})^{\rm T} \end{vmatrix}$$

Количество итераций: iteration = 1

Показатель адиабаты после Т:  $k_{\rm T} = 1.293$ 

Статическое давление после T (Па):  $P_{T} = 866.5 \cdot 10^{3}$   $P_{T} \geq P_{ATM}(H_{U}) = 1$ 

Статическая температура после T (K):  $T_T = 1424.1$ 

Теплоем кость после Т (Дж/кг/К):  $Cp_T = Cp_{\Gamma a3}(P_T, T_T, \alpha_{oX}, Fuel) = 1271.6$ 

Ср. показатель адиабаты Т: 
$$k = mean(k_T, k_T) = 1.288$$

Ср. теплоемкость Т (Дж/кг/К): Ср 
$$= \frac{k}{k-1} \cdot R_{\Gamma a3} (\alpha_{ox}, \text{Fuel}) = 1289.8$$

Степень понижения давления: 
$$\pi_{T} = \frac{P^{*}_{\Gamma}}{P_{T}} = 3.15$$

Удельный объём перед Т (м³/кг): 
$$\begin{pmatrix} v_{\Gamma} \\ v_{T} \end{pmatrix} = R_{\Gamma a 3} \Big( \alpha_{OX}, \text{Fuel} \Big) \cdot \begin{pmatrix} \frac{T_{\Gamma}}{P_{\Gamma}} \\ \frac{T_{T}}{P_{T}} \end{pmatrix} = \frac{1}{1 \quad 0.189}$$
 (С. 11)

Площадь кольцевого сечения перед T (м²): 
$$\begin{pmatrix} F_{\Gamma} \\ F_{T} \end{pmatrix} = \begin{pmatrix} \frac{G_{\Gamma} \cdot v_{\Gamma}}{c_{\Gamma}} \\ \frac{G_{T} \cdot v_{T}}{c_{T}} \end{pmatrix} = \begin{pmatrix} \frac{1}{1 & 60741} \\ \frac{1}{2 & 93341} \end{pmatrix} \cdot 10^{-6}$$

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

 $0.7 \le \mu_c \le 1 = 1$ 

▼ Определение количества ступеней Т

$$\begin{pmatrix} Z_{recomend} \\ \alpha_{BO3B} \end{pmatrix} = \begin{vmatrix} c_{cp} = mean \left( c_{r}, c_{T} \right) \\ \alpha_{BO3B} = 0.025 \\ \text{while } 1 > 0 \end{vmatrix}$$

$$\begin{vmatrix} Z_{recomend} \\ Z_{recomend} \\ Z_{recomend} \end{vmatrix} = \begin{vmatrix} c_{cp} = mean \left( c_{r}, c_{T} \right) \\ \alpha_{BO3B} = 0.025 \\ \frac{2 \cdot H_{T} \cdot \frac{\left( 1 + \alpha_{BO3B} \right)}{\left( \mu_{c} \cdot c_{cp} \right)^{2} - 1}}{\frac{u_{r}^{2}}{\left( \mu_{c} \cdot c_{cp} \right)^{2} \cdot y_{0}^{2}} - 1} \end{vmatrix}$$

$$\begin{vmatrix} b_{reak} & \text{if } \left| c_{ps} \right| \\ c_{ps} \left| \text{"rel"}, \alpha_{BO3B}, \frac{Z - 1}{2 \cdot Z} \cdot \left( \pi_{T} \frac{k - 1}{k} - 1 \right) \cdot \left( 1 - \eta_{\Pi} \right) \right| < c_{psilon}$$

$$\begin{vmatrix} \alpha_{BO3B} = \frac{Z - 1}{2 \cdot Z} \cdot \left( \pi_{T} \frac{k - 1}{k} - 1 \right) \cdot \left( 1 - \eta_{\Pi} \right) \right|$$

$$\begin{vmatrix} if \alpha_{BO3B} = 0 \\ \left| C_{\alpha_{BO3B}} \right| = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{vmatrix} D_{break} \\ C_{\alpha_{BO3B}} \end{vmatrix}$$

Рекомендуемое количество ступеней:  $Z_{recomend} = 1$ 

Количество ступеней:  $Z = \begin{bmatrix} 1 & \text{if turbine} = \text{"ТВД"} = 1 \\ 4 & \text{if turbine} = \text{"ТНД"} \end{bmatrix}$ 

Дискретизация ступеней: i = 1..Z

Дискретизация сечений:  $ii = 1...2 \cdot Z + 1$ 

Плотность материала 
$$J(\kappa r/m^3)$$
: 
$$\rho\_blade_i = 7938 \quad \text{if material\_blade}_i = "BKHA-1B"$$
 
$$8390 \quad \text{if material\_blade}_i = "BKM7"$$
 
$$8760 \quad \text{if material\_blade}_i = "KC-36"$$
 NaN otherwise

Предел длительной прочности Л РК (Па): 
$$\sigma_{blade\_long_i} = 10^6 \cdot 205 \text{ if material\_blade}_{i} = "BKHA-1B"$$
 
$$120 \text{ if material\_blade}_{i} = "BKM7"$$
 
$$120 \text{ if material\_blade}_{i} = "ЖC-36"$$
 NaN otherwise

$$\sigma\_blade\_long^T = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 205 \end{array}} \cdot 10^6$$

Коэф. формы:  $k_n = 6.8$ 

Модуль Юнга I рода материала  $\Pi$  ( $\Pi$ a):  $E_blade = 210 \cdot 10^9$ 

Коэф. Пуассона материала  $\Pi$  ():  $\mu$  steel = 0.3

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_{\text{blade\_long}Z}}{\text{safety} \cdot k_{\text{n}} \cdot F_{\Gamma}}} = 19539$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{\text{max}} = \sqrt{\frac{\sigma_{\text{blade\_long}Z}}{\text{safety} \cdot k_{\text{n}} \cdot F_{\text{T}}}} = 15762$$

Рекомендукмая ном. частота вращения (об/мин):

$$n = n_{\text{max}} \cdot 0.95 = 14974$$

Ном. частога вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 1570.8$$

Ср. диаметр перед Т (м): 
$$\begin{pmatrix} D_{\Gamma.cp} \\ D_{T.cp} \end{pmatrix} = \frac{2}{\omega} \cdot \begin{pmatrix} u_T \\ u_T \end{pmatrix} = \begin{bmatrix} 1 \\ 1 & 662.1 \\ 2 & 662.1 \end{bmatrix} \cdot 10^{-3}$$

Длина Л первой ступени Т (м):

Длина Л последней ступени Т (м):

	$\begin{pmatrix} F_{\Gamma} \end{pmatrix}$				
$\begin{pmatrix} 1_{\Gamma} \end{pmatrix}$ 1	$D_{\Gamma,cp}$			1	– 3
$\begin{vmatrix} 1 \end{vmatrix} = \frac{1}{\pi}$	F	=	1	29.20	.10
$\binom{1}{T}$	T		2	44.88	
	$\left( D_{\mathrm{T.cp}} \right)$				

Диаметр периферии после 
$$T(M)$$
: 
$$\begin{pmatrix} D_{T.Пер} \\ D_{T.Кор} \end{pmatrix} = \begin{pmatrix} D_{T.cp} + l_T \\ D_{T.cp} - l_T \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 707.0 \\ 2 \\ 617.2 \end{bmatrix} \cdot 10^{-3}$$

$$\frac{l_{\rm T}}{D_{\rm T.cp}} = \frac{1}{14}$$

$$N_{cT_i} = \frac{N_T}{Z}$$

$$N_{\rm CT}^{\rm T} = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 1 \\ \end{array}} \cdot 10^6$$

Вид проточной части:

("const", "кор", "cp", "пер", "доля от предыдушего диаметра периферии")

### Определение проточной части ОП

Линейное распределение кольцевых площадей по сечениям:

$$\begin{array}{c|c} F_{w} = & \text{for } i \in 1..2Z + 1 \\ F_{i} = \frac{F_{T} - F_{\Gamma}}{\text{st}(Z,3) - 1} \cdot i + \left(F_{\Gamma} - \frac{F_{T} - F_{\Gamma}}{\text{st}(Z,3) - 1}\right) \\ & \text{for } i \in 1..Z \\ & \text{for } a \in 2..3 \\ & F_{\text{st}(i,a)} = F_{\text{st}(i,a-1)} \quad \text{if } 3\Pi\Pi \Psi_{i,a-1} = \text{"const"} \\ F \end{array}$$

$F^{T} =$		1	2	3	4	5	6	7	8	9	$1.10^{-6}$
	1	60741	60741	93341							

$$\begin{array}{ll} D = & \text{ for } i \in 2Z + 1 \\ & \text{ for } r \in 1..N_r \\ & D_{i,r} = & \left| \begin{array}{l} D_{T,KOP} & \text{ if } r = 1 \\ D_{T,cop} & \text{ if } r = av(N_r) \\ D_{T,ncp} & \text{ if } r = N_r \end{array} \right. \\ & \text{ for } i \in Z..1 \\ & \text{ for } r \in 1..N_r \\ & D_{st(i,a),r} = & \left| \begin{array}{l} \text{ if } 3\Pi\Pi^t I_{i,a} = "const" \\ D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array} \right. \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "kop" \\ & D_{st(i,a+1),1} & \text{ if } r = 1 \\ & \frac{1}{2} \left[ D_{st(i,a+1),1} + \sqrt{\left(D_{st(i,a+1),1}\right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} & \text{ if } r = N_r \end{array} \right. \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "cp" \\ & D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} - \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array} \\ & \text{ if } 3\Pi\Pi^t I_{i,a} = "cp" \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = 1 \\ & D_{st(i,a+1),av(N_r)} + \frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}} & \text{ if } r = N_r \end{array}$$

$$D^{T} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 650.0 & 650.0 & 617.2 & & & & & \\ 2 & 678.5 & 678.5 & 662.1 & & & & & \\ 3 & 707.0 & 707.0 & 707.0 & & & & & & \end{bmatrix} \cdot 10^{-3}$$

$$R_{M} = \frac{D}{2}$$

$$\overline{d} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } a \in 1..3 \end{cases}$$

$$\overline{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$$

$\overline{d}^T =$		1	2	3	4	5	6	7	8	9
	1	0.9194	0.9194	0.8730						

$$\begin{array}{|c|c|} h = & \text{for } i \in 1..2Z + 1 \\ \\ h_i = \frac{F_i}{\pi \cdot D_{i, av(N_r)}} \\ \\ h \end{array}$$

$$\begin{split} & | \overset{D}{\text{st}(i,a+1),N_r} \overset{\text{if } r = r \cdot r}{\text{if } \left( 3\Pi\Pi \Psi_{i,\,a} \neq \text{"const"} \right) \wedge \left( 3\Pi\Pi \Psi_{i,\,a} \neq \text{"kop"} \right) \wedge \left( 3\Pi\Pi \Psi_{i,\,a} \neq \text{"cp"} \right) \wedge \left( 3\Pi\Pi \Psi_{i,\,a} \neq \text{"nep"} \right)} \\ & \sqrt{ \left( \frac{D_{\text{st}(i,a+1),N_r}}{\text{str2num} \left( 3\Pi\Pi \Psi_{i,\,a} \right)} \right)^2 - \frac{4 \cdot F_{\text{st}(i,a)}}{\pi}} & \text{if } r = 1 \\ & \frac{1}{2} \cdot \left[ \sqrt{ \left( \frac{D_{\text{st}(i,a+1),N_r}}{\text{str2num} \left( 3\Pi\Pi \Psi_{i,\,a} \right)} \right)^2 - \frac{4 \cdot F_{\text{st}(i,a)}}{\pi}} + \frac{D_{\text{st}(i,a+1),N_r}}{\text{str2num} \left( 3\Pi\Pi \Psi_{i,\,a} \right)}} & \text{if } r = \text{av} \left( N_r \right) \\ & \frac{D_{\text{st}(i,a+1),N_r}}{\text{str2num} \left( 3\Pi\Pi \Psi_{i,\,a} \right)} & \text{if } r = N_r \end{split}$$

D

for 
$$i \in 1...2 \cdot Z + 1$$
  
for  $r \in 1...N_r$   

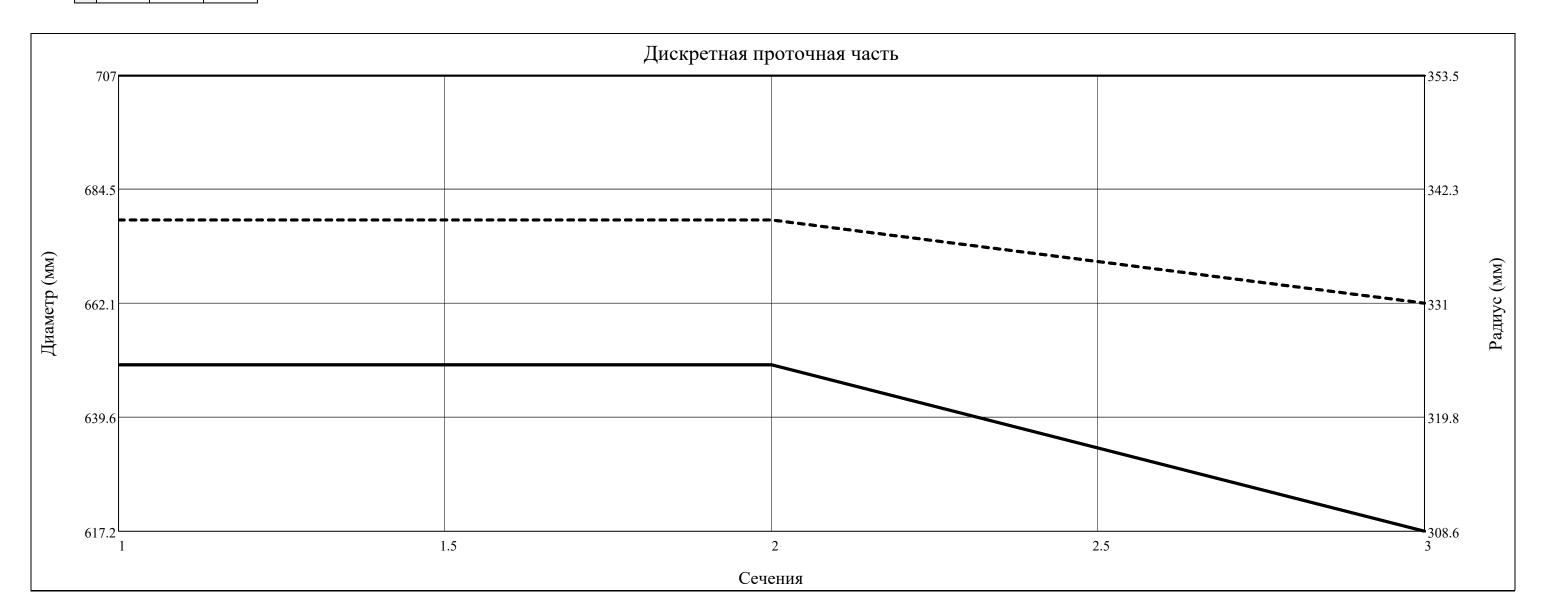
$$u_{i,r} = \frac{\pi \cdot D_{i,r} \cdot n}{60}$$

$$u$$

		1	2	3	4	5	6	7	8	9
$u^T =$	1	510.5	510.5	484.8						
•	2	532.9	532.9	520.0						
	3	555.2	555.2	555.2						

$$\overline{d}_{1} = 0.9194$$
  $\overline{d}_{1} \le 0.9 = 0$ 

$\overline{\mathbf{d}}^{\mathrm{T}} =$		1	2	3	4	5	6	7	8	9
	1	0.9194	0.9194	0.8730						



## Осевая ширина Л СА и РК [1, с.183]:

$$\begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix} = \begin{vmatrix} \text{for } i \in 1..Z \\ \begin{pmatrix} B_{CA}_i \\ B_{PK_i} \end{pmatrix} = \begin{pmatrix} \frac{D_{st(i,2),av(N_r)} - 0.25 \cdot h_{st(i,2)}}{16.4} \\ \frac{D_{st(i,3),av(N_r)}}{22} \end{vmatrix}$$

$$\begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix}$$

stack 
$$\left(B_{CA}^{T}, B_{PK}^{T}\right) = \begin{bmatrix} 1 & 1 \\ 1 & 40.9 \\ 2 & 30.1 \end{bmatrix} \cdot 10^{-3}$$

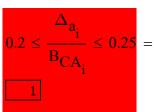
Радиальный зазор (м):

Осевой зазор (м):

(Лучше выбирать большее значение)

$$\begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix} = \begin{vmatrix} \text{for } i \in 1...Z \\ \text{for } a \in 1...3 \\ \begin{vmatrix} \Delta_{r_{st(i,a)}} = 0.001 \cdot D_{st(i,a), N_r} \\ \Delta_{a_i} = 0.25 \cdot B_{CA_i} \\ \begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix}$$

$$\Delta_a^T = \begin{bmatrix} 1 & 1 \\ 1 & 10.234 \end{bmatrix} \cdot 10^-$$



$$stack\left(\gamma_{\prod \text{$V$}} \overset{T}{,} \gamma_{\prod {$V$}} \overset{T}{,}$$

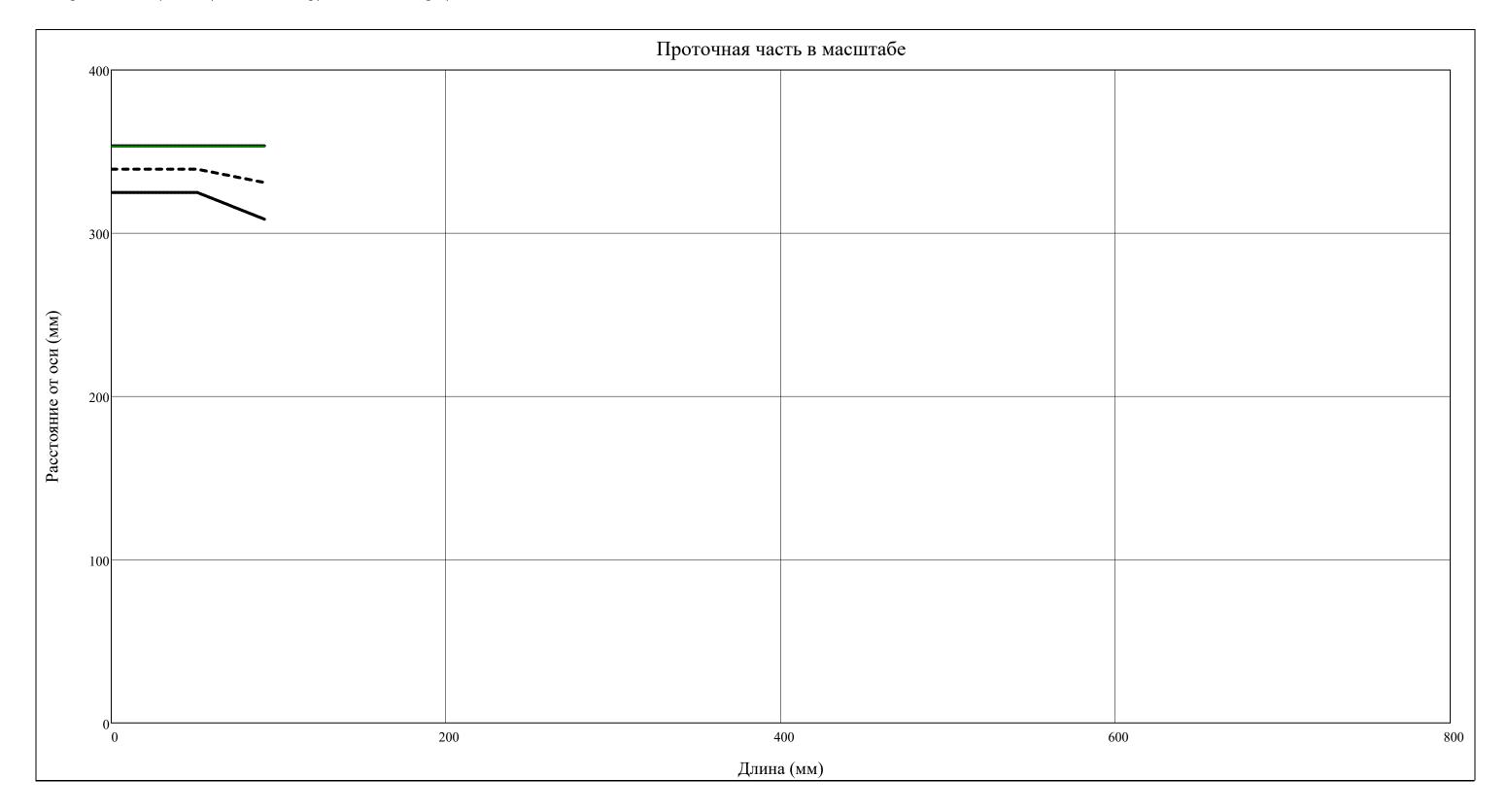
$\gamma_{\Pi \Pi}^{T} \leq 20.^{\circ} =$		1	2	
	1	1	0	
$\gamma_{\Pi \Pi}^{T} \leq 25 \cdot \circ =$		1	2	

$\gamma_{\text{TIII}_{\text{MOR}}}^{\text{T}} > -12^{\circ} =$		1	2
ПЧкор > -12	1	1	0
$\gamma_{\text{TIII}_{\text{NOD}}}^{\text{T}} > -15.^{\circ} =$		1	2
$\Pi \Pi \Pi \text{Kop} > -13.$			

$$\begin{pmatrix} x_{\Pi \mathbf{q}} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \\ y_{\Pi \mathbf{q} nep} \end{pmatrix} = \begin{vmatrix} c = 1 \\ x_{\Pi \mathbf{q}_c} = 0 \\ y_{\Pi \mathbf{q} nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_c} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), nep} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), nep} \\ y_{\Pi \mathbf{q} nep_c} = D_{st(c,1), 1} \\ \text{for } i \in 1 ... \mathbf{Z} \\ \begin{vmatrix} c = c + 1 \\ x_{\Pi \mathbf{q}_c} = x_{\Pi \mathbf{q}_{c-1}} + 0.5 \cdot \Delta_{\mathbf{a}_i} + B_{\mathbf{C}} \mathbf{A}_i + 0.5 \cdot \Delta_{\mathbf{a}_i} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{vmatrix} = \begin{pmatrix} D_{st(i,2), N_r} \\ D_{st(i,2), 1} \end{pmatrix} \\ y_{J nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_i} \\ c = c + 1 \\ x_{\Pi \mathbf{q}_c} = x_{\Pi \mathbf{q}_{c-1}} + 0.5 \cdot \Delta_{\mathbf{a}_i} + B_{\mathbf{p}} \mathbf{K}_i + 0.5 \cdot \Delta_{\mathbf{a}_i} \\ \begin{pmatrix} y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{pmatrix} = \begin{pmatrix} D_{st(i+1,1), N_r} \\ D_{st(i+1,1), 1} \\ D_{st(i+1,1), 1} \end{pmatrix} \\ y_{J nep_c} = y_{\Pi \mathbf{q} nep_c} - \Delta_{r_i} \\ \begin{pmatrix} x_{\Pi \mathbf{q}} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \\ y_{\Pi \mathbf{q} nep_c} \end{pmatrix} = \begin{pmatrix} T_{st(i+1,1), nep_c} \\ T_{st(i+1,1), 1} \\ T_{st(i+1$$

$$\begin{split} \text{Length} &= \sum_{i=1}^{Z} \ \text{B}_{\text{CA}_i} + \sum_{i=1}^{Z} \ \Delta_{a_i} + \sum_{i=1}^{Z} \ \text{B}_{\text{PK}_i} = 81.3 \cdot 10^{-3} \\ \\ &x = \min \left( x_{\Pi Y} \right), \min \left( x_{\Pi Y} \right) + \frac{\max \left( x_{\Pi Y} \right) - \min \left( x_{\Pi Y} \right)}{N_{\text{dis}}} ... \max \left( x_{\Pi Y} \right) \end{split}$$

 $\begin{aligned} y_{\Pi \Pi nep}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi nep}, l\Big) & y_{\Pi \Pi cp}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi cp}, l\Big) & y_{\Pi \Pi kop}(l) &= linterp\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi \Pi kop}, l\Big) \\ y_{\Pi nep}(l) &= interp\Big(cspline\Big(x_{\Pi \Pi}, 0.5 \cdot y_{\Pi nep}\Big), x_{\Pi \Pi}, 0.5 \cdot y_{\Pi nep}, l\Big) \end{aligned}$ 

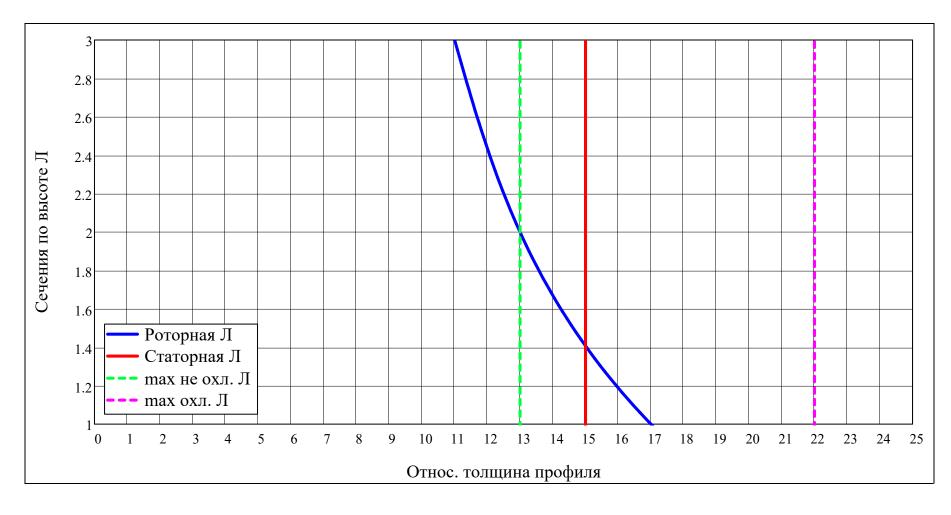


Относ. толщины ЛРК и СА:

$$\overline{c}_{stator.}(r) = \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 15 \\ 15 \\ 15 \end{bmatrix}, \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 15 \\ 15 \\ 15 \end{bmatrix}, K, r \end{bmatrix} \text{ if } T_{JI.JQOII} < T^*_{\Gamma}$$

$$\begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ 11 \end{bmatrix}, \begin{bmatrix} 7 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 7 \\ 9 \\ 11 \end{bmatrix}, K, r \end{bmatrix} \text{ otherwise}$$

$$\overline{c}_{rotor.}(r) = \begin{bmatrix} 1 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 17 \\ 13 \\ 11 \end{bmatrix}, \begin{bmatrix} 17 \\ av(N_r) \\ N_r \end{bmatrix}, \begin{bmatrix} 17 \\ 13 \\ 11 \end{bmatrix}$$



$$\begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor}
\end{bmatrix} = \begin{bmatrix}
for & i \in 1...Z \\
for & r \in 1...N_r
\end{bmatrix}$$

$$\begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor} \\
\overline{c}_{rotor} \\
\overline{c}_{rotor}
\end{bmatrix} = \begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor} \\
\overline{c}_{rotor}
\end{bmatrix}$$

$$\begin{bmatrix}
\overline{c}_{stator} \\
\overline{c}_{rotor}
\end{bmatrix}$$

$$\frac{-}{c_{stator}}^{T} = \begin{vmatrix}
 & 1 \\
1 & 15.00 \\
2 & 15.00 \\
3 & 15.00
\end{vmatrix}$$
.%

$$\frac{T}{c_{rotor}} = \begin{vmatrix}
 & 1 & \\
1 & 17.00 \\
2 & 13.00 \\
3 & 11.00
\end{vmatrix}$$

$$\frac{T}{\text{r_inlet}_{\text{stator}}} = \begin{vmatrix}
 & 1 & \\
 & 1 & 6.000 \\
 & 2 & 6.000 \\
 & 3 & 6.000
\end{vmatrix} \cdot \%$$

$$\frac{T}{r\_outlet_{stator}}^{T} = \begin{bmatrix} & 1 \\ 1 & 3.000 \\ 2 & 3.000 \\ \hline 3 & 3.000 \end{bmatrix} .\%$$

$$\frac{T}{r\_inlet_{rotor}}^{T} = \begin{bmatrix}
 & 1 \\
1 & 5.950 \\
2 & 4.550 \\
3 & 3.850
\end{bmatrix}$$
.%

$$R_{L.cp} = \begin{pmatrix} 0.16 & \text{if turbine} = "TBД" & 0.15 & 0.18 & 0.185 & 0.5 & 0.5 \\ 0.13 & \text{otherwise} \end{pmatrix}^{T}$$

## ▼ Поступенчатый расчет ОТ

<i>7</i> ··	••
iteration <sub>CA</sub>	
<u>k</u> .	$R_{L}$
Н*ст	$H_{CT}$
H <sub>stator</sub>	$H_{rotor}$
сад	w <sub>ад</sub>
P*	P
T*	$T_{\infty}$
.G.,	V
ρ*	ρ
, CA CONTRACT	$\alpha_{ox}$
α	β
$arepsilon_{ ext{stator}}$	$\epsilon_{ m rotor}$
$\theta_{CA}$	$\theta_{ ext{PK}}$
g <sub>охл</sub> са	g <sub>охл</sub> РК
a* <sub>c</sub>	a* <sub>W</sub>
Тад	$T_{a\mu}$
P* <sub>w</sub>	T* <sub>w</sub>
a <sub>3B</sub>	a <sub>3B</sub>
и и	u u
u £	c c
c <sub>a</sub>	$c_{\mathbf{u}}$
w w	W
w <sub>a</sub>	w <sub>u</sub>
$\lambda_{ m c}$	$M_c$
$\lambda_{\rm w}$	$M_{ m W}$
	$v_{ m rotor}$
<sup>v</sup> stator	rotor

chordstator	chord <sub>rotor</sub>	
т <sub>опт</sub> СА	т <sub>оптРК</sub>	
t <sub>stator</sub>	t <sub>rotor</sub>	$\alpha_{\text{oX}} = \alpha_{\text{oX}}$
Z <sub>stator</sub>	Z <sub>rotor</sub>	$\begin{vmatrix} k_{\text{St}(i,1),r} = k_{\Gamma} \\ p_{\text{total}} = p_{\text{total}} \end{vmatrix}$
$\overline{v}_{ m stator}$	$\overline{v}_{ m rotor}$	$P^*_{st(i,1),r} = P^*_{\Gamma}$ $P^*_{rt(i,1),r} = P^*_{rt(i,1),r}$
ξ <sub>TpCA</sub>	ξтрРК	$P^*_{W_{St(i,1),r}} = 0$
ξ <sub>κpCA</sub>	ξ <sub>кр</sub> РК	$P_{st(i,1),r} = P_{\Gamma}$
ξReCA	ξ <sub>RePK</sub>	$T^*_{st(i,1),r} = T^*_{\Gamma}$
$\xi_{\lambda CA}$	$\xi_{\lambda PK}$	$T^*_{W_{\operatorname{st}(i,1),r}} = 0$
$\xi_{\Pi p C A}$	$\xi_{\Pi p P K}$	$T_{st(i,1),r} = T_{\Gamma}$
$\xi_{\mathrm{BTCA}}$	$\xi_{\mathrm{BTPK}}$	$v_{st(i,1),r} = \frac{R_{\Gamma a3}(\alpha_{oX_{st(i,1)}}, Fuel) \cdot T_{st(i,1),r}}{P_{st(i,1),r}}$
$\xi_{ m TДCA}$	ξ <sub>тдРК</sub>	
ξсмСА	ξсмРК	$G_{st(i,1)} = G_{\Gamma}$
$\xi_{\Delta r}$	$\xi_{ m BMX}$	$c_{st(i,1),r} = c_{\Gamma}$
ξ <sub>тр.в</sub>	ξ <sub>Тр.В</sub>	$\alpha_{st(i,1),r} = \alpha_{\Gamma}$
L <sub>ct</sub>	Lu <sub>ct</sub>	$\begin{bmatrix} c_{u_{st(i,1),r}} \\ = c_{ot(i,1),r} \end{bmatrix} = c_{ot(i,1),r} \begin{pmatrix} cos(\alpha_{st(i,1),r}) \\ \\ = c_{ot(i,1),r} \end{pmatrix}$
$\eta_{ ext{мощь}}$	$\eta_{ m JO\Pi}$	$\begin{bmatrix} c_{u_{st(i,1),r}} \\ c_{a_{st(i,1),r}} \end{bmatrix} = c_{st(i,1),r} \cdot \begin{pmatrix} \cos(\alpha_{st(i,1),r}) \\ \sin(\alpha_{st(i,1),r}) \end{pmatrix}$
$\eta^*_{ m cT}$	$\eta^*_{\mathrm{cT}}$	$\mathbf{w}_{\mathrm{st}(i,1),r} = 0$
$\eta_{u1}$	$\eta_{u2}$	$\left( \sqrt{k_{st(i,1),r} \cdot R_{\Gamma a3}} \left( \alpha_{oX_{st(i,1)}}, Fuel \right) \cdot T_{st(i,1),r} \right)$
ξCA	ξ <sub>PK</sub>	$ \begin{array}{c c}  & a_{3B} \\ \hline  & 2 \cdot k_{st(i,1),r} \\ \hline  & 3 \cdot k_{st(i,1),r} \\ \hline  & 4 \cdot k_{st(i,1),r} \\ \hline  & 3 \cdot k_{st(i,1),r} \\ \hline  & 4 \cdot k_{st(i,1),r} \\$
Lu <sub>нагрузка</sub>	Lu <sub>нагрузка</sub>	$ \left  \begin{array}{c} a^*c_{\operatorname{st}(i,1),r} \end{array} \right  = \left  \begin{array}{c} \sqrt{\frac{1+k_{\operatorname{st}(i,1),r}}{1+k_{\operatorname{st}(i,1),r}}} \cdot R_{\operatorname{\Gamma}a3} \left( \alpha_{\operatorname{ox}_{\operatorname{st}(i,1)}}, \operatorname{Fuel} \right) \cdot \Gamma^* \operatorname{st}(i,1), r \end{array} \right  $
		$ \begin{pmatrix} a_{3B_{st(i,1),r}} \\ a^*c_{st(i,1),r} \\ a^*w_{st(i,1),r} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,1),r} \cdot R_{\Gamma a3} \left(\alpha_{ox_{st(i,1)}}, Fuel\right) \cdot T_{st(i,1),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,1),r}}{1 + k_{st(i,1),r}} \cdot R_{\Gamma a3} \left(\alpha_{ox_{st(i,1)}}, Fuel\right) \cdot T^*_{st(i,1),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,1),r}}{1 + k_{st(i,1),r}} \cdot R_{\Gamma a3} \left(\alpha_{ox_{st(i,1)}}, Fuel\right) \cdot T^*_{w_{st(i,1),r}}} \\ \sqrt{\frac{2 \cdot k_{st(i,1),r}}{1 + k_{st(i,1),r}} \cdot R_{\Gamma a3} \left(\alpha_{ox_{st(i,1)}}, Fuel\right) \cdot T^*_{w_{st(i,1),r}}} \end{pmatrix} $
		$\begin{pmatrix} \lambda_{c} \\ \lambda_{w} \\ st(i,1),r \end{pmatrix} = \begin{pmatrix} \frac{c_{st(i,1),r}}{a^{*}c_{st(i,1),r}} \\ 0 \end{pmatrix}$ $\begin{pmatrix} M_{c} \\ st(i,1),r \\ M_{w} \\ st(i,1),r \end{pmatrix} = \frac{1}{a_{3B_{st(i,1),r}}} \begin{pmatrix} c_{st(i,1),r} \\ w_{st(i,1),r} \end{pmatrix}$
		$\begin{bmatrix} & & & & & & & & & & & & & & & & & & &$
		$ \left  \begin{array}{c} \mathbf{c}^{\mathbf{c}} \mathbf{st}(\mathbf{i}, 1), \mathbf{r} \\ \mathbf{c}^{\mathbf{c}} \mathbf{st}(\mathbf{i}, 1), \mathbf{r} \end{array} \right  = \frac{1}{\mathbf{c}^{\mathbf{c}} \mathbf{st}(\mathbf{i}, 1), \mathbf{r}} $
		$\left[\begin{array}{c} M_{\text{W}} \\ \text{st(i,1),r} \end{array}\right] = a_{3B} \\ \text{st(i,1),r} \qquad \left(\begin{array}{c} w_{\text{st(i,1),r}} \\ \end{array}\right)$
		$iteration_{CT_{\dot{i}}} = 0$
		while $1 > 0$ $  \text{iteration}_{CT_{i}} = \text{iteration}_{CT_{i}} + 1$
		$         iteration_{CT_i} = iteration_{CT_i} + 1 $

$$\begin{aligned} & \operatorname{trace} \left( \operatorname{concat} \left( ^{*} \quad \operatorname{iteration.er} - ^{*}, \operatorname{num2str} \left( \operatorname{iteration}_{CT_i} - 1 \right) \right) \\ & \frac{1}{\operatorname{mean} \left( G_{St(i,1)} \cdot 0.9 \right)} \quad \operatorname{if} \left( \operatorname{iteration}_{CT_i} - 1 \right) \\ & \frac{1}{\operatorname{mean} \left( G_{St(i,2)} \cdot G_{St(i,3)} \right) \cdot \eta_{Month_{ij}}} \quad \operatorname{otherwise} \end{aligned}$$
 
$$R_{L_{i,r}} = R_{L.cp_{i}}$$
 
$$c_{at_{St(i,1),r}} = \sqrt{2 \cdot H_{cT_{i}}} \\ H_{Stator_{i}} = H_{cT_{i}} \cdot \left( 1 - R_{L_{i,r}} \right) \\ c_{at_{St(i,2),r}} = \sqrt{2 \cdot H_{Stator_{i}}} \\ \overline{v}_{stator_{i}} = 1 \\ \operatorname{iteration}_{CA_{i}} = 0 \\ \text{while } 1 > 0 \\ & \operatorname{iteration}_{CA_{i}} = \operatorname{iteration}_{CA_{i}} + 1 \\ \operatorname{trace} \left( \operatorname{concat} \left( ^{**} \quad \operatorname{iteration}_{CA_{i}} + 1 \right) \\ c_{st(i,2),r} = \overline{v}_{stator_{i}} \cdot \overline{v}_{at_{St(i,2),r}} \\ \theta_{CA_{i}} = \theta_{TJY} \delta_{HHa} \left( T^{*}_{st(i,1),r}, T^{*}_{cooling}, T_{JL,non} \right) \\ g_{ox_{J}CA_{i}} = \frac{0.035 \cdot \theta_{CA_{i}}}{1 - \theta_{CA_{i}}} \quad \operatorname{if} \frac{0.035 \cdot \theta_{CA_{i}}}{1 - \theta_{CA_{i}}} \geq 0 \\ g_{ox_{J}CA_{i}} = \frac{0.035 \cdot \theta_{CA_{i}}}{0 \quad \operatorname{otherwise}} \\ G_{st(i,2)} = G_{st(i,1)} \cdot \left( 1 + g_{ox_{J}CA_{i}} \right) \\ \alpha_{ox_{St(i,2)}} = \alpha_{ox_{St(i,1)}} + g_{ox_{J}CA_{i}} \\ \alpha_{ox_{CA_{i}}} = \operatorname{mean} \left( \alpha_{ox_{St(i,1)},r} \right) \\ k_{St(i,2),r} = k_{st(i,1),r} \\ k_{St(i,2),r} = k_{st(i,1),r} \\ while 1 > 0 \\ k_{CA_{i}} = \operatorname{mean} \left( k_{st(i,1),r}, k_{st(i,2),r} \right) \\ H_{Stator_{i}} \\ H_{Stator_{i}} \\ T_{a_{J}^{*}_{St(i,2),r}} = T^{*}_{st(i,1),r}, r \\ k_{CA_{i}} - 1 \\ k$$

$$\begin{aligned} & P_{sd(i,2),r} = P^{s}_{sd(i,1),r} \left( \frac{T_{aX_{sd(i,2),r}}}{T^{s}_{sd(i,1),r}} \right) \\ & T_{a(i,2),r} = T^{s}_{sd(i,1),r} \left( \frac{T_{aX_{sd(i,2),r}}}{K_{CA_{i}}} \right) \frac{H_{stator_{i}} \left[ \overline{V}_{stator_{i}} \right]^{2}}{K_{CA_{i}}} \\ & T_{a(i,2),r} = T^{s}_{sd(i,2),r} \left[ \frac{T_{aX_{sd(i,2),r}}}{K_{CA_{i}}} \right] R_{ras,cp} \left( u_{cx_{sd(i,2)},r} T_{sud} \right) \\ & C_{P_{2}} = C_{P_{70}} \left\{ P_{sd(i,2),r}, T_{sd(i,2),r} \cdot P_{cx_{sd(i,2),r}} \right\} \\ & C_{P_{2}} = C_{P_{70}} \left\{ P_{sd(i,2),r}, T_{sd(i,2),r} \cdot P_{cx_{sd(i,2),r}} \right\} \\ & \left\{ V^{s}_{aX_{sd(i,2),r}} \left[ \frac{T_{aX_{sd(i,2),r}}}{T_{sd(i,2),r}} \right] \right\} \\ & \left\{ V^{s}_{aX_{sd(i,2),r}} = T_{sd(i,2),r} \cdot \frac{T_{sd(i,2),r}}{T_{sd(i,2),r}} \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ \frac{T_{cx_{sd(i,2),r}}}{T_{sd(i,2),r}} \right] \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ V^{s}_{cx_{sd(i,2),r}} \right] \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ V^{s}_{cx_{sd(i,2),r}} \right] \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right] \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ V^{s}_{cx_{sd(i,2),r}} \right] \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left[ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{sd(i,2),r}} \right) \right\} \\ & \left\{ V^{s}_{cx_{sd(i,2),r}} \left( V^{s}_{cx_{$$

$$\begin{vmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{vmatrix} = c_{st(i,2),r} \begin{pmatrix} c_{st(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = c_{st(i,2),r} \begin{pmatrix} c_{st(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = c_{st(i,2),r} \begin{pmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = u_{st(i,2),r} \begin{pmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = w_{st(i,2),r} \begin{pmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = w_{st(i,2),r} \begin{pmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} = w_{st(i,2),r} \begin{pmatrix} c_{u_{3}(i,2),r} \\ c_{u_{3}(i,2),r} \end{pmatrix} + \frac{(w_{st(i,2),r} c_{u_{3}(i,2),r})^{2}}{2 \cdot C p_{ras}(P_{st(i,2),r} s_{st(i,2),r} c_{u_{3}(i,2),r})} \\ V^*w_{st(i,2),r} &= P_{st(i,2),r} \begin{pmatrix} T^*w_{st(i,2),r} \\ T_{st(i,2),r} \end{pmatrix} \\ \frac{k_{st(i,2),r}}{2 \cdot C p_{ras}(P_{st(i,2),r} s_{st(i,2),r} c_{u_{3}(i,2),r} c_{u_{3}(i,2),r}$$

$$\begin{vmatrix} \operatorname{cril} \left( \frac{\operatorname{common}_{\operatorname{cont}}(x_{1}, x_{1}, x_{1}, x_{2}, x_{1}, x_{1}, x_{2})}{\operatorname{ContCa}_{\operatorname{cont}}(x_{1}, x_{2}, x_{2}, x_{2}, x_{2})} + 1 \text{ otherwise} \\ \\ \operatorname{for } r = 1 . N_{\Gamma} \\ \operatorname{Istanor}_{i, t} = \frac{\pi \cdot \operatorname{mean} \left( \operatorname{D}_{\operatorname{st}(i, 1), t}, \operatorname{D}_{\operatorname{st}(i, 2), t} \right)}{2 \operatorname{Subor}_{i, t}} \\ \\ \operatorname{SpCA}_{i} = \operatorname{Special}_{i} \left[ \operatorname{Soute-lailor}_{i, t}, \operatorname{chend-subor}_{i, t}, \operatorname{Juster}_{i, t}, \operatorname{Osg}(i, 2), t \right) \\ \\ \operatorname{SpCA}_{i} = \operatorname{Special}_{i} \left[ \operatorname{Soute-lailor}_{i, t}, \operatorname{Chend-subor}_{i, t}, \operatorname{Juster}_{i, t}, \operatorname{Osg}(i, 2), t \right) \\ \\ \operatorname{SpCA}_{i} = \operatorname{Special}_{i} \left[ \operatorname{Subor}_{i, t}, \operatorname{SpCA}_{i} + \operatorname{SpCA}_{i} + \operatorname{SpCA}_{i} + \operatorname{SpCA}_{i} + \operatorname{SpCA}_{i} \right] \\ \\ \operatorname{SpCA}_{i} = \operatorname{SppCA}_{i} + \operatorname{SppCA}_{i} + \operatorname{SpCA}_{i} + \operatorname{SpCA}_{$$

$$\begin{split} & | \Phi_{PK_i} = \theta_{TIIJOHHa} \Big( T^* \mathbf{w}_{st(i,2),r}, T^* \mathbf{cooling}, TJL.aon \Big) \\ & | \mathbf{g}_{OXIIPK_i} = \left| \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} \right| \text{ if } \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} \ge 0 \\ & | \mathbf{g}_{st(i,3)} = \mathbf{G}_{st(i,2)} \cdot \Big( 1 + \mathbf{g}_{OXIIPK_i} \Big) \\ & | \mathbf{G}_{oX_{st(i,3)}} = \mathbf{G}_{oX_{st(i,2)}} + \mathbf{g}_{OXIIPK_i} \Big) \\ & | \mathbf{G}_{oX_{st(i,3)},r} = \mathbf{g}_{st(i,2),r} \cdot \mathbf{g}_{oXIIPK_i} \\ & | \mathbf{g}_{oX_{st(i,3),r}} = \mathbf{g}_{st(i,2),r} \cdot \mathbf{g}_{oXIIPK_i} \\ & | \mathbf{g}_{oX_{st(i,3),r}} = \mathbf{g}_{st(i,2),r} \cdot \mathbf{g}_{oX_{st(i,3),r}} \\ & | \mathbf{g}_{oX_{st(i,3),r}} - \mathbf{g}_{st(i,2),r} \cdot \mathbf{g}_{oX_{st(i,3),r}} \Big| \mathbf{g}_{oX_{st(i,3),r}} \\ & | \mathbf{g}_{oX_{st(i,3),r}} - \mathbf{g}_{oX_{st(i,2),r}} \cdot \mathbf{g}_{oX_{st(i,3),r}} \Big| \mathbf{g}_{oX_{st(i,3),r}} \\ & | \mathbf{g}_{oX_{st(i,3),r}} - \mathbf{g}_{oX_{st(i,3),r}} \Big| \mathbf{g}_{oX_{st(i$$

$$\begin{pmatrix} v_{s(i,3),r} = \sqrt{\left(c_{s_{s(i,3),r}}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2}} \\ w_{a_{l(i,3),r}} = \sqrt{\left(w_{s(i,3),r}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2}} \\ w_{a_{l(i,3),r}} = \sqrt{\left(w_{s(i,3),r}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2}} \\ w_{a_{l(i,3),r}} = \sqrt{\left(c_{s_{s(i,3),r}}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2}} \\ v_{a_{l(i,3),r}} = \sqrt{\left(c_{s_{s(i,3),r}}^{2}\right)^{2} + \left(c_{s_{s(i,3),r}}^{2}\right)^{2}} \\ v_{a_{l(i,3),r}} = \sqrt{\left(c_{s_{l(i,3),r}}^{2}\right)^{2} + \left(c_{s_{l(i,3),r}}^{2}\right)^{2}} \\ v_{a_{l(i,3),r}} = \sqrt{\left(c_{s_{l(i,3),r}}^{2}\right)^{2}} \\ v_$$

$$\begin{vmatrix} \left\langle \frac{N_{c}}{N_{c}}(i,3),i \right\rangle & \frac{N_{c}}{a^{*}N_{c}} \frac{N_{c}(i,3),i}{a^{*}N_{c}} \right\rangle \\ \left\langle \frac{N_{c}}{a^{*}N_{c}}(i,3),i \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{S_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}}(i,3),i \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{S_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}}(i,3),i \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{S_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{S_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{S_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}(i,3),i}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a_{n}(i,3),i} \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle \\ \left\langle \frac{N_{c}}{N_{c}(i,3),i} \right\rangle & = \frac{1}{a_{n}} \frac{1}{a$$

$$\begin{vmatrix} | \overline{v}_{rotot_{i}} | = \sqrt{1 - \xi_{cal} v_{K_{i}}^{-} - \xi_{Ta} p_{K_{i}}^{-} - \xi_{BT} v_{K_{i}}^{-} - \xi_{BT} p_{K_{i}}^{-} - \xi_{BT} p_{$$

$$\left[ H^*_{cT_{\hat{i}}} = Cp_{\Gamma a3.cp} \left( P_{st(i,1),r}, P_{st(i,3),r}, T_{st(i,1),r}, T_{st(i,3),r}, \alpha_{oX_{st(i,1)}}, \alpha_{oX_{st(i,3)}}, Fuel \right) \cdot T^*_{st(i,1),r} \cdot \left[ 1 - \left( \pi^*_{cT_{\hat{i}}} \right)^{\frac{1}{k_{cp}}} \right] \right]$$

$$\left[ \eta^*_{cT_{\hat{i}}} = \frac{L_{cT_{\hat{i}}}}{H^*_{cT_{\hat{i}}}} \right]$$

for  $i \in 1...Z$ 

for  $j \in 1...3$ 

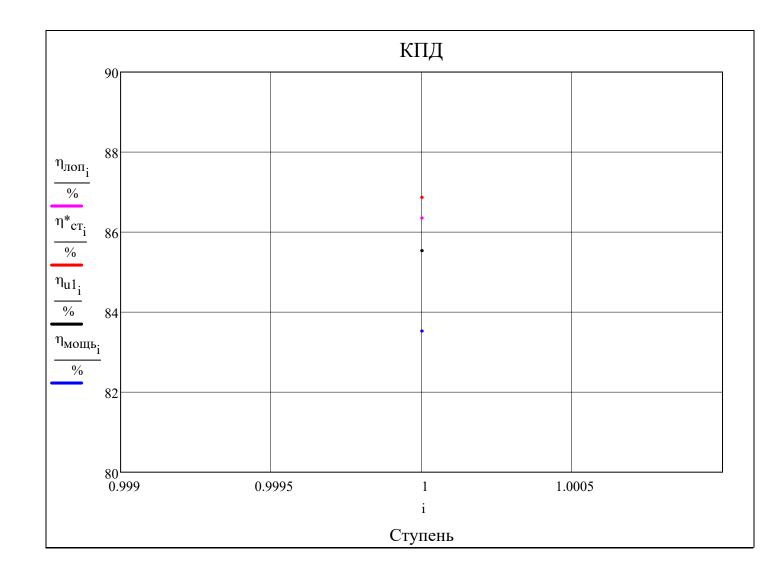
$$\begin{vmatrix} \rho^*_{st(i,j),r} = \frac{P^*_{st(i,j),r}}{R_{\Gamma a3} \left(\alpha_{oX_{st(i,j)}}, Fuel\right) \cdot T^*_{st(i,j),r}} \\ \rho_{st(i,j),r} = \left(v_{st(i,j),r}\right)^{-1} \\ \left(\varepsilon_{stator_{i,av}\left(N_r\right)}\right) = \begin{pmatrix} \alpha_{st(i,2),av\left(N_r\right)} - \alpha_{st(i,1),av\left(N_r\right)} \\ \beta_{st(i,3),av\left(N_r\right)} - \beta_{st(i,2),av\left(N_r\right)} \end{pmatrix}$$

(iteration<sub>CA</sub> iteration<sub>PK</sub>)

β  $\varepsilon_{
m stator}$  $\epsilon_{rotor}$ 

 $g_{\text{ОХЛРК}}$ 

▼ Параметры турбины



$$\eta_{\Pi O\Pi}^{\quad T} = \boxed{ \begin{array}{c|c} & 1 \\ \hline 1 & 86.35 \end{array}} \cdot \%$$

$$\operatorname{stack}\!\left(\eta_{u1}^{\phantom{u1}T},\eta_{u2}^{\phantom{u2}T}\right) = \begin{array}{|c|c|c|c|}\hline & 1 \\ \hline 1 & 85.54 \\ \hline 2 & 86.83 \\ \hline \end{array} \cdot \%$$

$$\eta_{\text{MOIЦb}}^{T} = \boxed{\begin{array}{c|c} 1 \\ 1 \\ 83.53 \end{array}} \cdot \%$$

$$\eta_{\text{MOIII}_{i}} \leq \eta_{\text{ul}_{i}} \leq \eta^*_{\text{cT}_{i}} \leq \eta_{\text{ЛОП}_{i}} = 0$$

Теплоперепад по параметрам торможения (Дж/кг): 
$$\begin{pmatrix} H^*_T \\ H_T \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^Z & H^*_{cT_i} \\ \vdots & \vdots & \vdots \\ \sum_{i=1}^Z & H_{cT_i} \end{pmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 516.1 \\ 2 & 536.7 \end{bmatrix} \cdot 10^3$$

Мощность Т (Вт): 
$$\sum_{i=1}^{Z} N_{\text{ст}_{i}} = 14.89 \cdot 10^{6}$$
 eps "rel",  $N_{\text{T}}$ ,  $\sum_{i=1}^{Z} N_{\text{ст}_{i}} = 0.000 \cdot \%$ 

Удельная поступенчатая рабога Т [Дж/кг]: 
$$L_T = \sum_{i=1}^{Z} \frac{N_{cT_i}}{\text{mean}\big(G_{st(i,2)},G_{st(i,3)}\big)} = 448.6 \cdot 10^3$$

$$k_{T.cp} = k_{ad} \left( Cp_{\Gamma a3.cp} \left( P_{st(1,1),av(N_r)}, P_{st(Z,3),av(N_r)}, T_{st(1,1),av(N_r)}, T_{st(Z,3),av(N_r)}, \alpha_{ox_{st(1,1)}}, \alpha_{ox_{st(Z,3)}}, Fuel \right), P_{ra3.cp} \left( \alpha_{ox_{st(1,1)}}, \alpha_{ox_{st(Z,3)}}, Fuel \right) \right) = 1.289$$

Адиабатный КПДТ: 
$$\eta^*_T = \frac{L_T}{H^*_T} = 86.92 \cdot \%$$

Политропический КПД Т: 
$$\eta^*_{T,\Pi} = \eta^*_{n} ($$
"расширение", $\eta^*_{T}, \pi^*_{T}, k_{T,cp} ) = 85.37 \cdot \%$ 

$$M$$
ощностной КПДТ:  $\eta_{T$ Мощь  $= \frac{\displaystyle\sum_{i=1}^{Z} \frac{N_{c_{T_i}}}{\mathrm{mean}\left(G_{\mathrm{st}(i,2)},G_{\mathrm{st}(i,3)}
ight)}}{H_{\mathrm{T}}} = 83.58 \cdot \%$ 

$$Lu_{\text{нагрузка}}^{T} = \boxed{ \begin{array}{c} 1 \\ 1 \end{array} }$$

$H_{or}^T =$		1	$10^3$
CT	1	536.7	

$$\operatorname{stack}\left(\mathbf{H}_{\operatorname{stator}}^{\operatorname{T}}, \mathbf{H}_{\operatorname{rotor}}^{\operatorname{T}}\right) = \begin{bmatrix} & 1 \\ 1 & 450.9 \\ 2 & 87.0 \end{bmatrix} \cdot 10^{3}$$

submatrix 
$$\left(R_L^T, av(N_r), av(N_r), 1, Z\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$stack \left(\theta_{CA}^{T}, \theta_{PK}^{T}\right) = \begin{bmatrix} & 1 \\ 1 & 0.432 \\ 2 & 0.206 \end{bmatrix}$$

$$\operatorname{stack}\left(g_{\text{OX}}, g_{\text{OX}}, g_{\text{OX}}, g_{\text{OX}}\right) = \begin{bmatrix} & 1 & 1 \\ 1 & 26.61 \\ 2 & 9.09 \end{bmatrix} \cdot 10^{-3}$$

$$G_{OXJICA_{i}} = g_{OXJICA_{i}} \cdot G_{st(i,1)}$$

$$G_{OX \Pi PK_i} = g_{OX \Pi PK_i} \cdot G_{st(i,2)}$$

$$\operatorname{stack}\left(G_{\text{OXJICA}}^{T},G_{\text{OXJIPK}}^{T}\right) = \begin{bmatrix} & 1\\ & 1 & 0.9\\ & 2 & 0.3 \end{bmatrix}$$

$$G_{cooling} = 3.2$$

$$\sum_{i=1}^{Z} G_{\text{oxnCA}_i} + \sum_{i=1}^{Z} G_{\text{oxnCA}_i} \leq G_{\text{cooling}} = 1$$

$$stack \left( iteration_{CA}^{T}, iteration_{PK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}$$

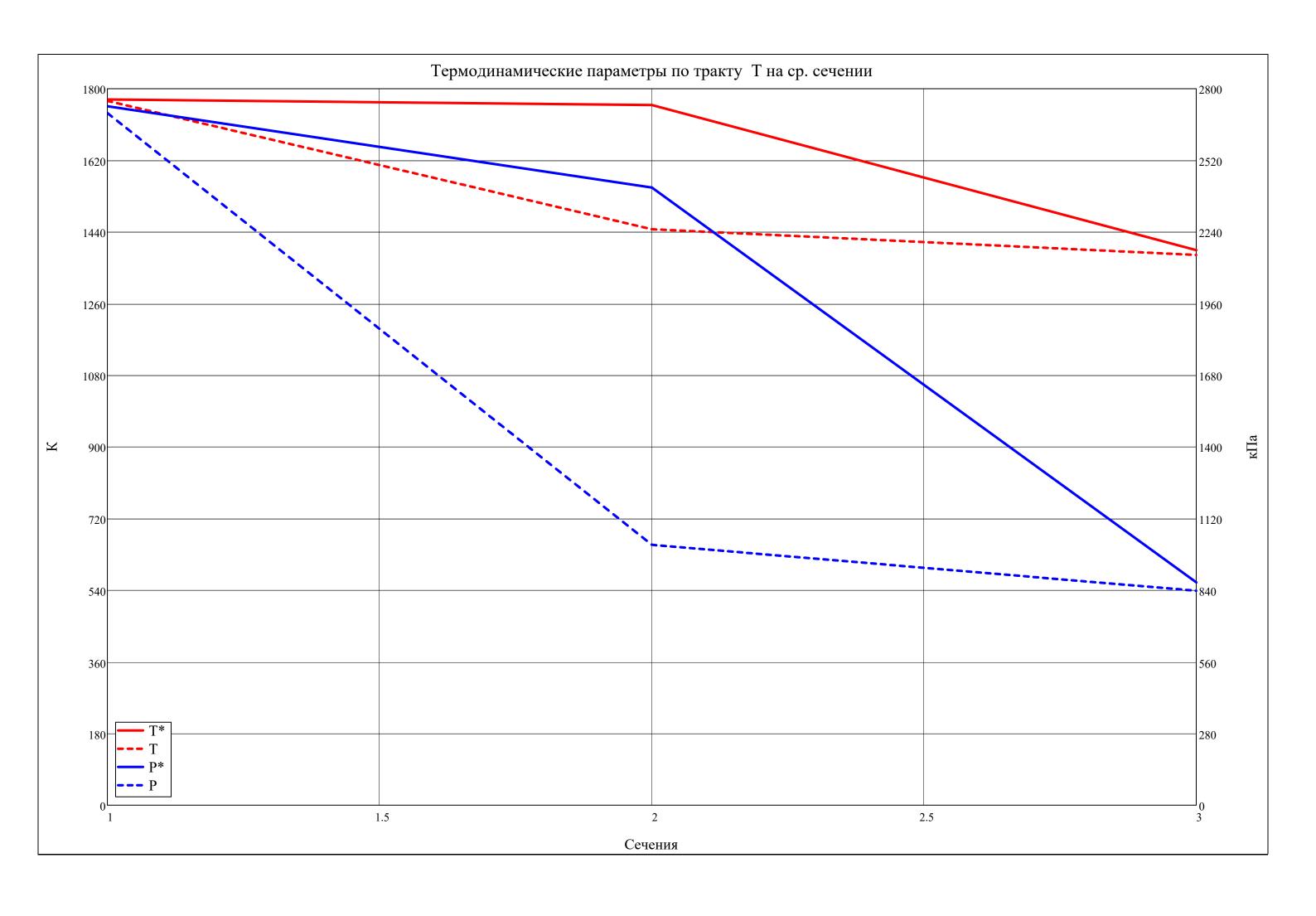
submatrix 
$$\left(P^{*T}, av(N_r), av(N_r), 1, 2Z + 1\right) = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2731.8 & 2413.7 & 870.5 \end{bmatrix} \cdot 10^{\frac{1}{2}}$$

submatrix 
$$\left(P^{T}, av(N_{r}), av(N_{r}), 1, 2Z + 1\right) = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2705.2 & 1017.3 & 838.1 \end{bmatrix} \cdot 10^{3}$$

$$\operatorname{submatrix}\left(v^{T},\operatorname{av}\left(N_{r}\right),\operatorname{av}\left(N_{r}\right),1,2Z+1\right) = \begin{array}{|c|c|c|c|c|}\hline 1 & 2 & 3 \\\hline 1 & 0.189 & 0.410 & 0.487 \\\hline \end{array}$$

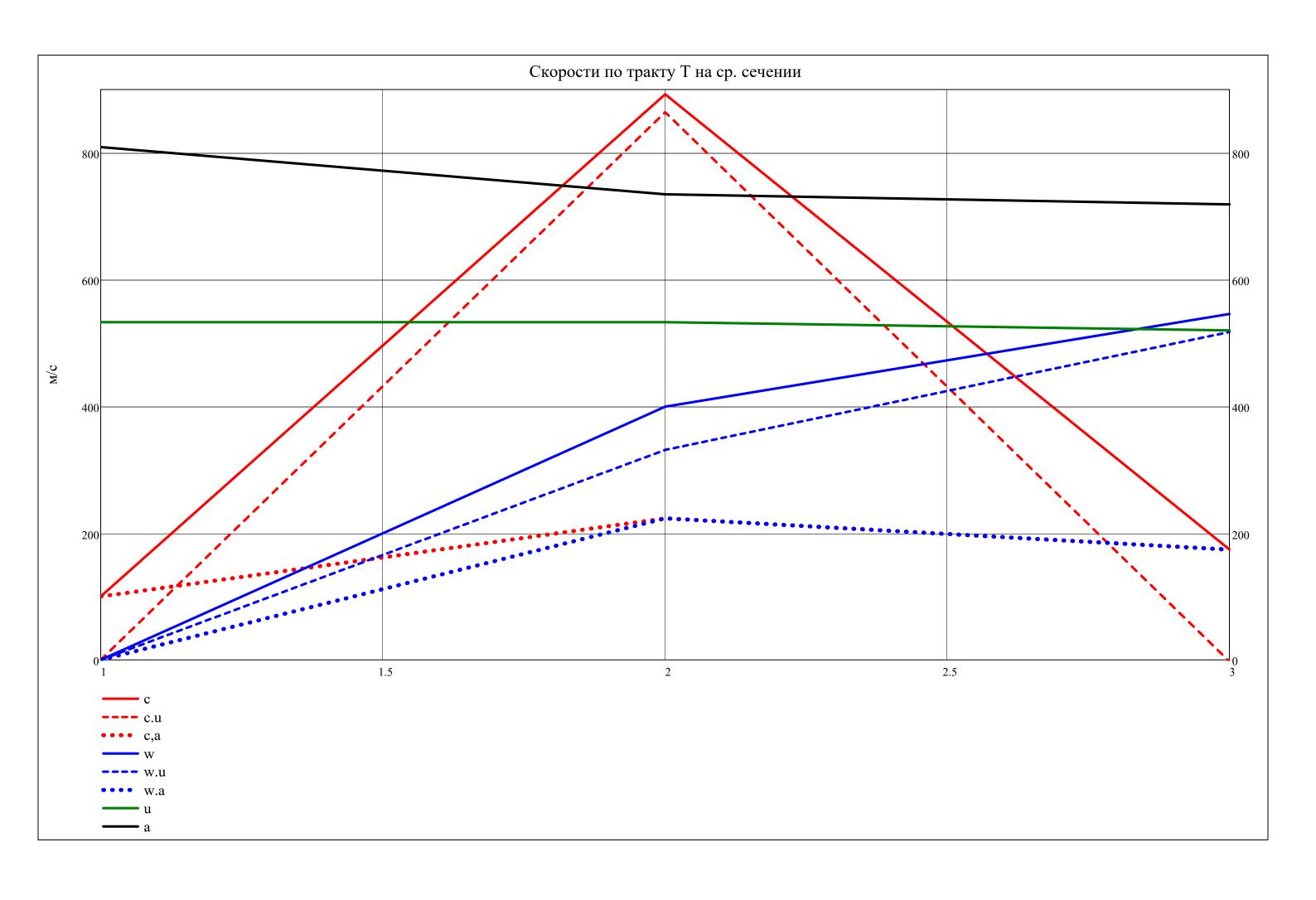
submatrix 
$$\left(\rho^{*^{T}}, av(N_{r}), av(N_{r}), 1, 2Z + 1\right) = \boxed{\begin{array}{c|cccc} 1 & 2 & 3 \\ \hline 1 & 5.341 & 4.756 & 2.164 \end{array}}$$

submatrix 
$$\left(\rho^{T}, av(N_{r}), av(N_{r}), 1, 2Z + 1\right) = \boxed{\begin{array}{c|c} 1 & 2 & 3 \\\hline 1 & 5.300 & 2.437 & 2.053 \end{array}}$$



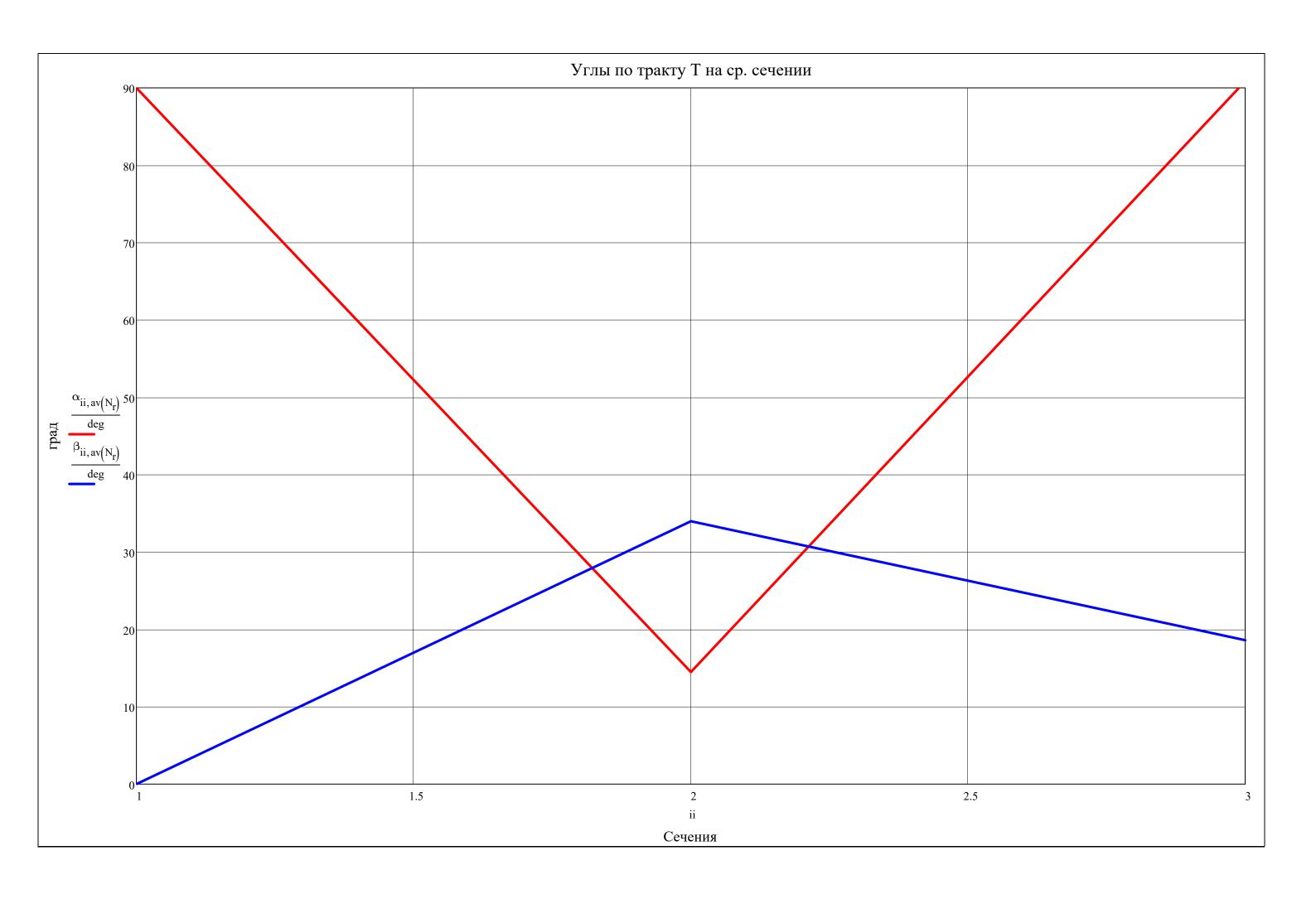
$$\begin{aligned} & \text{submatrix} \bigg( a_{3B}^{-T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 809.2 \end{array} }_{734.6} \underbrace{ \begin{array}{c} 3 \\ 718.7 \end{array}}_{734.6} \end{aligned} \\ & \text{submatrix} \bigg( a_{C}^{*T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 758.2 \end{array} }_{756.5} \underbrace{ \begin{array}{c} 3 \\ 758.2 \end{array} }_{756.5} \underbrace{ \begin{array}{c} 3 \\ 673.8 \end{array}}_{736.8} \end{aligned} \\ & \text{submatrix} \bigg( a_{W}^{*T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 0.0 \end{array} }_{700.8} \underbrace{ \begin{array}{c} 698.9 \\ 698.9 \end{array}}_{698.9} \\ & \text{submatrix} \bigg( c_{U}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 0.0 \end{array} }_{864.2} \underbrace{ \begin{array}{c} 3 \\ 2.7 \end{array} }_{2.7} \\ & \text{submatrix} \bigg( c_{U}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 3 \\ 1 \\ 0.0 \end{array} }_{399.5} \underbrace{ \begin{array}{c} 3 \\ 174.0 \end{array} }_{174.0} \\ & \text{submatrix} \bigg( w_{U}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{399.5} \underbrace{ \begin{array}{c} 3 \\ 545.8 \end{array} }_{174.0} \\ & \text{submatrix} \bigg( w_{U}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 0.0 \end{array} }_{331.3} \underbrace{ \begin{array}{c} 3 \\ 517.3 \end{array} }_{174.0} \\ & \text{submatrix} \bigg( c_{A,T}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 0.0 \end{array} }_{1} \underbrace{ \begin{array}{c} 2 \\ 3 \\ 1 \\ 0.0 \end{array} }_{223.3} \underbrace{ \begin{array}{c} 3 \\ 174.0 \end{array} }_{174.0} \\ & \text{submatrix} \bigg( c_{A,T}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{200.23.3} \underbrace{ \begin{array}{c} 3 \\ 174.0 \end{array} }_{174.0} \\ & \text{submatrix} \bigg( c_{A,T}^{T}, \text{av} \big( N_r \big), \text{av} \big( N_r \big), \text{av} \big( N_r \big), 1, 2Z+1 \bigg) = \underbrace{ \begin{array}{c} 1 \\ 1 \\ 1 \\ 0.0 \end{array} }_{200.23.3} \underbrace{ \begin{array}{c} 3 \\ 174.0 \end{array} }_{23.3} \\ & 1 \\ \underbrace{ \begin{array}{c} 3 \\ 1 \\ 0.0 \end{array} }_{200.0} \underbrace{ \begin{array}{c} 3 \\ 20.2 \\ 3 \\ 1 \\ 1 \\ 0.0 \end{array} }_{200.0} \underbrace{ \begin{array}{c} 3 \\ 20.2 \\ 3 \\ 1 \\ 1 \\ 0.0 \\ 0.$$

		1	2	3
$\mathbf{u}^{\mathrm{T}} =$	1	510.5	510.5	484.8
	2	532.9	532.9	520.0
	3	555.2	555.2	555.2

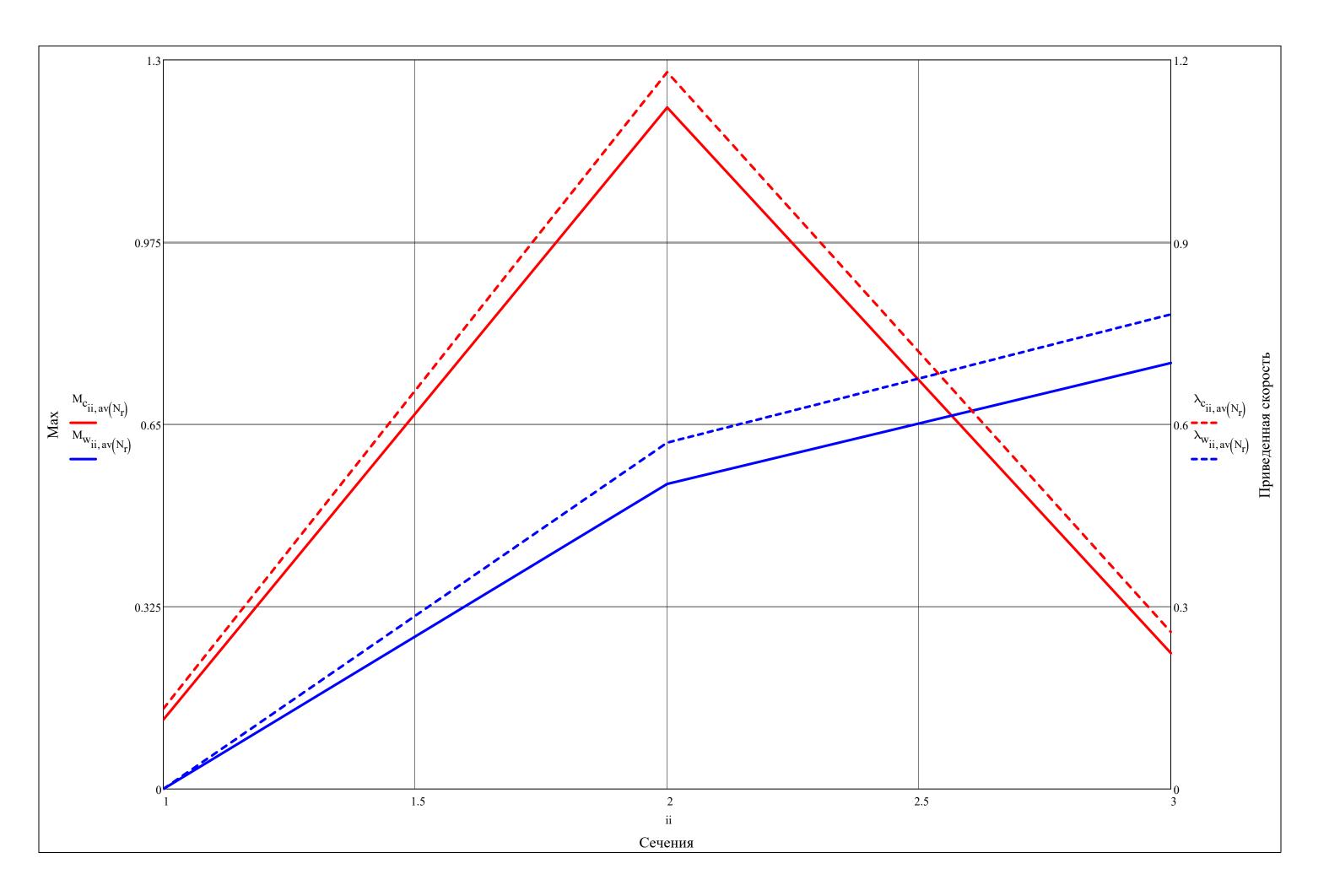


 $\operatorname{submatrix}\left(\varepsilon_{stator}, 1, Z, \operatorname{av}\left(N_{r}\right), \operatorname{av}\left(N_{r}\right)\right)^{T} = \begin{array}{|c|c|c|c|c|c|}\hline 1 & 2 & 3 & 4 & 5 & 6 \\\hline 1 & -75.51 & & & & & \\\hline\end{array}$ 

 $\text{submatrix} \left( \varepsilon_{rotor}, 1, Z, \text{av} \left( N_r \right), \text{av} \left( N_r \right) \right)^T = \begin{array}{|c|c|c|c|c|c|}\hline 1 & 2 & 3 & 4 & 5 & 6 \\\hline 1 & -15.39 & & & & \\\hline \end{array} \ .$ 



$$\operatorname{stack}\left(\upsilon_{\operatorname{stator}}^{\operatorname{T}},\upsilon_{\operatorname{rotor}}^{\operatorname{T}}\right) = \begin{array}{|c|c|c|c|}\hline & 1 \\ \hline 1 & 37.03 \\ \hline 2 & 67.08 \end{array} \cdot^{\circ}$$



$$t_{\text{stator}}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 56.7 \\ 2 & 59.2 \\ 3 & 61.7 \end{bmatrix} \cdot 10^{-3} \qquad t_{\text{rotor}}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 22.4 \\ 2 & 23.7 \\ 3 & 25.0 \end{bmatrix} \cdot 10^{-3}$$

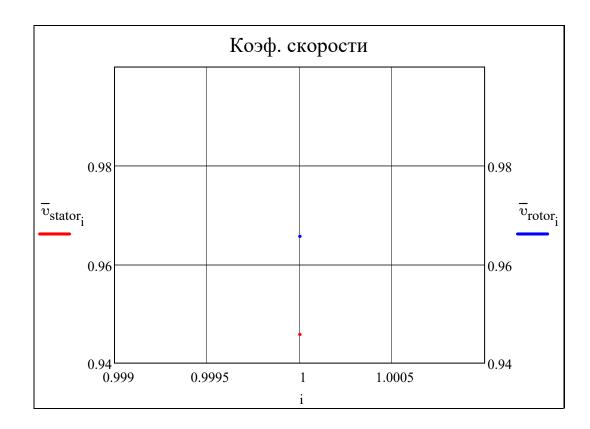
submatrix 
$$\left( \text{chord}_{\text{stator}}^T, \text{av}(N_r), \text{av}(N_r), 1, Z \right) = \begin{bmatrix} 1 \\ 1 \\ 68.0 \end{bmatrix} \cdot 10^{-3}$$

$$submatrix \left( chord_{rotor}^{T}, av(N_r), av(N_r), 1, Z \right) = \boxed{ 1 \\ 1 \quad 32.7 } \cdot 10^{-3}$$

$$stack\left(\overline{t}_{O\Pi TCA}^{T}, \overline{t}_{O\Pi TPK}^{T}\right) = \begin{bmatrix} & 1\\ & 1\\ & 1 & 0.872\\ & 2 & 0.724 \end{bmatrix}$$

$$\frac{t_{stator_{i, av\left(N_{r}\right)}}}{chord_{stator_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{stator_{i, av\left(N_{r}\right)}}}{chord_{stator_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} \le 1 = \frac{t_{rotor_{i, av\left(N_{r}\right)}}}{chord_{rotor_{i, av\left(N_{r}\right)}}} = 0.7 \le \frac{t_{rotor_{i, av\left(N_{r}\right)$$

	T - T			1	
stack	$v_{\text{stator}}$ , $v_{\text{rotor}}$	=	1	0.9458	
		_	2	0.9657	



$$stack\left(\xi_{TpCA}^{T},\xi_{TpPK}^{T}\right) = \begin{bmatrix} & 1\\ & 1\\ & 1.398\\ & 2 & 2.620 \end{bmatrix}.\%$$

$$stack \left( \xi_{KpCA}^{T}, \xi_{KpPK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ 2.753 \\ 2 \\ 1.689 \end{bmatrix} \cdot \%$$

$$stack \left( \xi_{ReCA}^{T}, \xi_{RePK}^{T} \right) = \begin{bmatrix} 1 \\ 1 \\ -0.135 \\ 2 \\ 0.085 \end{bmatrix} \cdot \%$$

$$stack\left(\xi_{\lambda CA}^{T}, \xi_{\lambda PK}^{T}\right) = \begin{bmatrix} 1\\ 1\\ 2.434\\ 2 & 0.024 \end{bmatrix} \cdot \%$$

$$stack\left(\xi_{BTCA}^{T},\xi_{BTPK}^{T}\right) = \begin{array}{|c|c|c|c|c|}\hline 1 & 1 & 1.453 \\\hline 1 & 1.453 & 2 & 0.881 \\\hline \end{array}$$

$$stack\left(\xi_{TДCA}^{T},\xi_{TДPK}^{T}\right) = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ \hline 1 & 1.856 \\ \hline 2 & 1.200 \\ \hline \end{array}$$

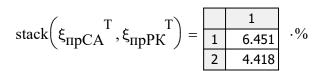
$$stack\left(\xi_{cMCA}^{T}, \xi_{cMPK}^{T}\right) = \begin{bmatrix} 1\\1\\0.784\\2\\0.248 \end{bmatrix}.\%$$

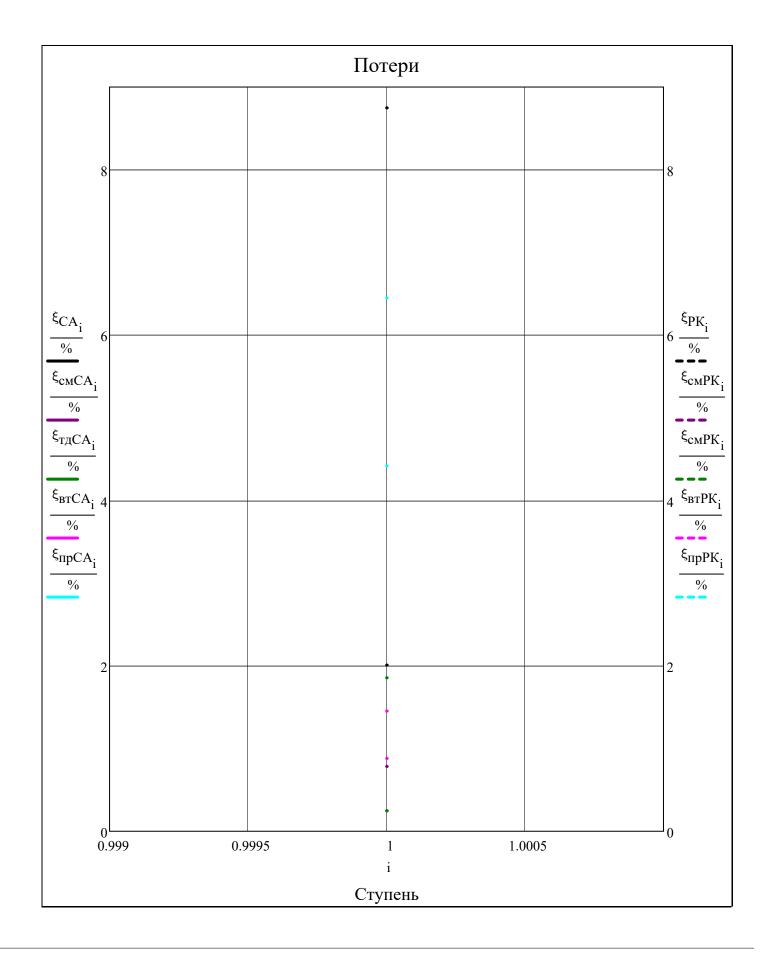
$$\operatorname{stack}\left(\xi_{CA}^{T},\xi_{PK}^{T}\right) = \begin{array}{|c|c|c|c|}\hline & 1 & \\ \hline 1 & 8.748 \\ \hline 2 & 2.008 \\ \hline \end{array}.\%$$

$$\xi_{B b I X}^{\quad T} = \boxed{ \quad \quad 1 \quad \quad } \cdot \%$$

$$\xi_{\Delta r}^{T} = \boxed{\begin{array}{c|c} 1 \\ 1 & 2.476 \end{array}} \cdot \%$$

$$\xi_{Tp.B}^{\quad T} = \boxed{ \begin{array}{c|c} 1 \\ \hline 1 & 0.831 \end{array}} \cdot \%$$





▼ Выбор закона профилирования Л по высоте

$$\mathbf{m} = \begin{pmatrix} \overline{v}_{\text{stator}_1} \cdot \cos(\alpha_{\text{st}(1,2), \text{av}(N_r)})^2 & \text{if } Z = 1 \\ -0.5 & \text{otherwise} \end{pmatrix}$$

$$0$$

$$0.25$$

$$1$$

$$1$$

$$\begin{pmatrix} \text{"}\alpha.2 = \text{const"} \\ \text{"}\Gamma = \text{const"} \\ \text{"}m = \text{const"} \\ \text{"}R = \text{const"} \end{pmatrix} = \begin{pmatrix} \cos\left(\alpha_{\text{st(i,2),av(N_r)}}\right)^2 \cdot \overline{\upsilon}_{\text{stator}_i} \\ 1 \cdot \overline{\upsilon}_{\text{stator}_i} \\ 0.2 \\ -1 \cdot \overline{\upsilon}_{\text{stator}_i} \end{pmatrix}$$

$\mathbf{m}^{\mathrm{T}} =$		1	2	3	4	5	6
	1	0.8866	-0.2500	0.0000	0.2500	1.0000	1.0000

▲ Выбор закона профилирования Л по высоте

$$\begin{vmatrix} \mathbf{r}_{i} & \mathbf{m}_{i} & - \mathbf{v}_{stator_{i}}^{-v_{stator_{i}}} \\ \mathbf{c}_{a_{st(i,\,a),\,av}(N_{r})} \\ \mathbf{c}_{a_{st(i,\,a),\,av}(N_{r})} \end{vmatrix} + \frac{\left(1 - \frac{\overline{v}_{stator_{i}}}{R_{st(i,\,a),\,av}(N_{r})}\right)^{2}}{tan\left(\alpha_{st(i,\,2),\,av(N_{r})}\right)^{2}} \quad \text{if } a = 2$$
 
$$\begin{vmatrix} \mathbf{c}_{a_{st(i,\,a),\,av(N_{r})}} \\ \mathbf{c}_{a_{st(i,\,a),\,av(N_{r})}} \end{vmatrix}^{2} \\ + \left[1 - (\overline{v}_{rotor_{i}})^{2}\right] \cdot \left(\mathbf{u}_{st(i,\,a),\,av(N_{r})}\right)^{2} \left[1 - \left(\frac{R_{st(i,\,a),\,r}}{R_{st(i,\,a),\,av(N_{r})}}\right)^{2}\right] - 2 \cdot \mathbf{c}_{\mathbf{u}_{st(i,\,a),\,av(N_{r})}} \\ + \left[1 - (\overline{v}_{rotor_{i}})^{2}\right] \cdot \left(\mathbf{u}_{st(i,\,a),\,av(N_{r})}\right)^{2} \left[1 - \left(\frac{R_{st(i,\,a),\,r}}{R_{st(i,\,a),\,av(N_{r})}}\right)^{2}\right] - 2 \cdot \mathbf{c}_{\mathbf{u}_{st(i,\,a),\,av(N_{r})}} \\ + \left[1 - (\overline{v}_{rotor_{i}})^{2}\right] \cdot \left(\mathbf{u}_{st(i,\,a),\,av(N_{r})}\right) \cdot \left(\mathbf{u}_{st(i,\,a,\,av(N_{r}))}\right)^{2} \cdot \left(\mathbf{u}_{st(i,\,a-1),\,av(N_{r})}\right) + \mathbf{c}_{\mathbf{u}_{st(i,\,a),\,av(N_{r})}} \\ + \left(\mathbf{u}_{st(i,\,a-1),\,av(N_{r})}\right) \cdot \left(\mathbf{u}_{st(i,\,a-1),\,av(N_{r})}\right) + \mathbf{c}_{\mathbf{u}_{st(i,\,a),\,av(N_{r})}}\right) \left[1 - \frac{2}{m_{i+1}} \cdot (\overline{v}_{rotor_{i}})^{2}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,\,a),\,r}}{R_{st(i,\,a),\,av(N_{r})}}\right)^{m_{i+1}}}\right] \cdots \\ + \left(\mathbf{c}_{\mathbf{u}_{st(i,\,a)},\,av(N_{r})}\right)^{2} \cdot \left[1 - \frac{(\overline{v}_{stator_{i}})^{2} \cdot (\overline{v}_{rotor_{i}})^{2}}{m_{i}}\right] \left[1 - \frac{1}{\left(\frac{R_{st(i,\,a),\,r}}{R_{st(i,\,a),\,av(N_{r})}}\right)^{2-m_{i}}}}\right] - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}} \cdots \\ + \left(\mathbf{c}_{\mathbf{u}_{st(i,\,a)},\,av(N_{r})}\right)^{2} \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,\,a),\,r}}{R_{st(i,\,a),\,av(N_{r})}}\right)^{2-m_{i}}}}\right] - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}}\right] - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} - \frac{1}{\left(R_{st(i,\,a),\,av(N_{r})}\right)^{2-m_{i}}}} -$$

for  $i \in 1...2 \cdot Z + 1$ 

for  $r \in 1..N_r$ 

$$\begin{vmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{vmatrix} = c_{i,av(N_r)} \cdot \begin{pmatrix} cos(\alpha_{i,av(N_r)}) \\ sin(\alpha_{i,av(N_r)}) \end{pmatrix}$$
 if  $(i = 1)$ 

$$P^*_{i,r} = P^*_{i,av(N_r)}$$

$$T^*_{i,r} = T^*_{i,av(N_r)}$$

$$\rho^*_{i,r} = \frac{P^*_{i,r}}{R_{\Gamma a3}(\alpha_{oX_i}, Fuel) \cdot T^*_{i,r}}$$

$$\begin{vmatrix} k_{i,\,r} = k_{aa} \left( Cp_{Bo3,Jyx} \left( P^*_{i,\,r}, T^*_{i,\,r} \right), R_{ra3} \left( \alpha_{oX_i}, Fuel \right) \right) \\ a^*_{c_{i,\,r}} = \sqrt{\frac{2 \cdot k_{i,\,r}}{k_{i,\,r} + 1}} \cdot R_{ra3} \left( \alpha_{oX_i}, Fuel \right) \cdot T^*_{i,\,r} \\ \alpha_{i,\,r} = \operatorname{triangle} \left( c_{a_{i,\,r}}, c_{u_{i,\,r}} \right) \\ c_{i,\,r} = \frac{c_{a_{i,\,r}}}{\sin(\alpha_{i,\,r})} \\ \lambda_{c_{i,\,r}} = \frac{c_{i,\,r}}{a^*_{c_{i,\,r}}} \\ \begin{pmatrix} T_{i,\,r} \\ P_{i,\,r} \end{pmatrix} = \begin{pmatrix} T^*_{i,\,r} \cdot \Gamma \mathcal{H} \Phi \left( ^{"}T^{"}, \lambda_{c_{i,\,r}}, k_{i,\,r} \right) \\ P^*_{i,\,r} \cdot \Gamma \mathcal{H} \Phi \left( ^{"}P^{"}, \lambda_{c_{i,\,r}}, k_{i,\,r} \right) \end{pmatrix} \\ a_{3B_{i,\,r}} = \sqrt{k_{i,\,r}} \cdot R_{ra3} \left( \alpha_{oX_i}, Fuel \right) \cdot T_{i,\,r} \\ M_{c_{i,\,r}} = \frac{c_{i,\,r}}{a_{3B_{i,\,r}}} \\ \beta_{i,\,r} = \operatorname{triangle} \left( c_{a_{i,\,r}}, u_{i,\,r} - c_{u_{i,\,r}} \right) \\ w_{i,\,r} = \frac{c_{a_{i,\,r}}}{\sin(\beta_{i,\,r})} \\ \begin{pmatrix} w_{u_{i,\,r}} \\ w_{a_{i,\,r}} \end{pmatrix} = w_{i,\,r} \cdot \begin{pmatrix} \cos(\beta_{i,\,r}) \\ \sin(\beta_{i,\,r}) \end{pmatrix} \\ T^*_{w_{i,\,r}} = T^*_{i,\,r} - \frac{\left( c_{i,\,r} \right)^2 - \left( w_{i,\,r} \right)^2}{2 \cdot \frac{k_{i,\,r}}{k_{i,\,r} - 1}} \cdot R_{ra3} \left( \alpha_{oX_i}, Fuel \right) \cdot T^*_{w_{i,\,r}} \\ \lambda_{w_{i,\,r}} = \frac{w_{i,\,r}}{a^*_{w_{i,\,r}}} \\ \lambda_{w_{i,\,r}} = \frac{w_{i,\,r}}{a^*_{w_{i,\,r}}} \\ M_{w_{i,\,r}} = \frac{w_{i,\,r}}{a^*_{w_{i,\,r}}} \\ for \ i \in 1 ... Z \\ for \ r \in 1 ... N_r \\ \end{cases}$$

 $\left(\Delta c_a\right) \left(c_a\right) - c_a$ 

$$\begin{vmatrix} \begin{bmatrix} \mathbf{w}_{st(i,1),r} \\ \Delta \mathbf{c}_{a_{st(i,2),r}} \end{bmatrix} = \begin{bmatrix} \mathbf{w}_{st(i,2),r} & \mathbf{w}_{st(i,1),r} \\ \mathbf{c}_{a_{st(i,2),r}} - \mathbf{c}_{a_{st(i,2),r}} \end{bmatrix} \\ \mathbf{R}_{\mathbf{L}_{i,r}} = 1 - \frac{\mathbf{c}_{\mathbf{u}_{st(i,2),r}} - \mathbf{c}_{\mathbf{u}_{st(i,3),r}} \\ \mathbf{u}_{st(i,2),r} + \mathbf{u}_{st(i,3),r} \end{vmatrix} \\ \boldsymbol{\varepsilon}_{stator_{i,r}} = \begin{bmatrix} \alpha_{st(i,2),r} - \alpha_{st(i,1),r} & \text{if } \alpha_{st(i,2),r} \geq \frac{\pi}{2} \\ \alpha_{st(i,1),r} - \alpha_{st(i,2),r} & \text{otherwise} \end{bmatrix} \\ \boldsymbol{\varepsilon}_{rotor_{i,r}} = \begin{bmatrix} \beta_{st(i,3),r} - \beta_{st(i,2),r} & \text{otherwise} \\ \beta_{st(i,2),r} - \beta_{st(i,3),r} & \text{otherwise} \end{bmatrix} \\ \begin{pmatrix} \mathbf{P}^* & \mathbf{T}^* & \mathbf{T} & \boldsymbol{\rho}^* & \mathbf{k} & \mathbf{a}^*_{\mathbf{c}} & \mathbf{a}_{3\mathbf{B}} & \mathbf{c} & \mathbf{c}_{\mathbf{u}} & \mathbf{c}_{\mathbf{a}} & \boldsymbol{\Delta}_{\mathbf{c}} & \boldsymbol{\lambda}_{\mathbf{w}} & \boldsymbol{\varepsilon}_{stator} \\ \mathbf{P} & \mathbf{T}^*_{\mathbf{w}} & \mathbf{T} & \boldsymbol{\rho} & \mathbf{R}_{\mathbf{L}} & \mathbf{a}^*_{\mathbf{w}} & \mathbf{a}_{3\mathbf{B}} & \mathbf{w} & \mathbf{w}_{\mathbf{u}} & \mathbf{w}_{\mathbf{u}} & \mathbf{w}_{\mathbf{u}} & \boldsymbol{\omega}_{\mathbf{a}} & \boldsymbol{\beta} & \mathbf{M}_{\mathbf{c}} & \mathbf{M}_{\mathbf{w}} & \boldsymbol{\varepsilon}_{rotor} \end{bmatrix}^{T}$$

▲ Расчет Л по высоте

#### ▼ Результаты расчета Л по высоте

		1	2	3	
$P^{*T} =$	1	2731.8	2413.7	870.5	$\cdot 10^3$
-	2	2731.8	2413.7	870.5	10
	3	2731.8	2413.7	870.5	

		1	2	3	4	5	6	7	8	9
$T^{*T} =$	1	1773.0	1759.0	1394.2						
-	2	1773.0	1759.0	1394.2						
	3	1773.0	1759.0	1394.2						

		1	2	3	4	5	6	7	8	9
$T^*$ $T = $	1	1878.6	1493.1	1491.4						
1 W -	2	1888.0	1500.7	1508.0						
	3	1897.9	1508.9	1525.6						

$$\rho^{*^T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ 1 & 5.341 & 4.756 & 2.164 \\ 2 & 5.341 & 4.756 & 2.164 \\ \hline 3 & 5.341 & 4.756 & 2.164 \\ \hline \end{array}$$

		1	2	3
$k^{T} =$	1	1.305	1.305	1.316
	2	1.305	1.305	1.316
	3	1.305	1.305	1.316

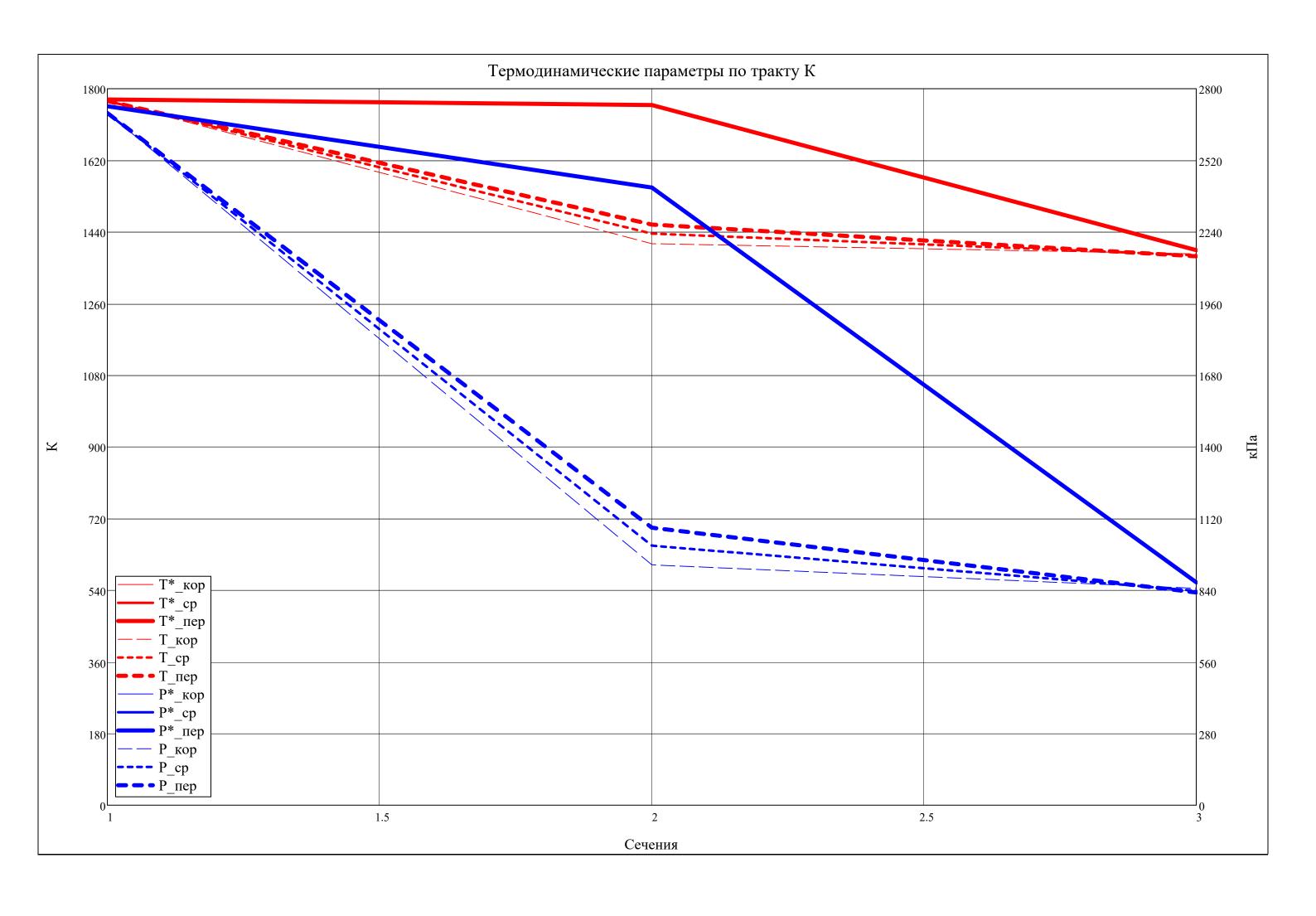
		1
$\mathbf{R}_{\tau}^{\mathrm{T}} =$	1	0.0998
'`L	2	0.1767
	3	0.2440

$$P^{T} = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 2705.2 & 939.2 & 847.2 \\ 2 & 2705.2 & 1014.0 & 838.1 \\ 3 & 2705.2 & 1084.4 & 831.3 \end{bmatrix} \cdot 10^{3}$$

		1	2	3	4	5	6	7	8	9
$T^{T} =$	1	1768.9	1410.5	1385.1						
-	2	1768.9	1436.0	1381.6						
	3	1768.9	1458.8	1378.9						

		1	2	3
$o^{T} =$	1	5.301	2.308	2.120
۲	2	5.301	2.448	2.103
	3	5.301	2.577	2.090

		1
$R_{1}^{T} \ge 0.05 =$	1	1
TL = 0.05	2	1
	3	1



$$a^*c^T = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 761.0 & 758.1 & 676.1 \\ 2 & 761.0 & 758.1 & 676.1 \\ 3 & 761.0 & 758.1 & 676.1 \end{bmatrix}$$

$$\mathbf{u}^{\mathrm{T}} = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 510.5 & 510.5 & 484.8 \\ 2 & 532.9 & 532.9 & 520.0 \\ 3 & 555.2 & 555.2 & 555.2 \end{bmatrix}$$

$$c^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ 1 & 100.0 & 927.2 & 147.3 \\ \hline 2 & 100.0 & 892.5 & 174.1 \\ \hline 3 & 100.0 & 860.6 & 191.8 \\ \hline \end{array}$$

$$c_u^T = \begin{array}{|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.0 & 897.7 & 1.8 \\ \hline 2 & 0.0 & 864.2 & -2.7 \\ \hline 3 & 0.0 & 833.2 & -6.4 \\ \hline \end{array}$$

$$c_a^{T} = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 100.0 & 231.9 & 147.3 \\\hline 2 & 100.0 & 223.3 & 174.0 \\\hline 3 & 100.0 & 215.3 & 191.7 \\\hline \end{array}$$

$$\Delta c_a^T = \begin{bmatrix} & 1 & 2 \\ 1 & 131.9 & -84.7 \\ 2 & 123.3 & -49.3 \\ 3 & 115.3 & -23.6 \end{bmatrix}$$

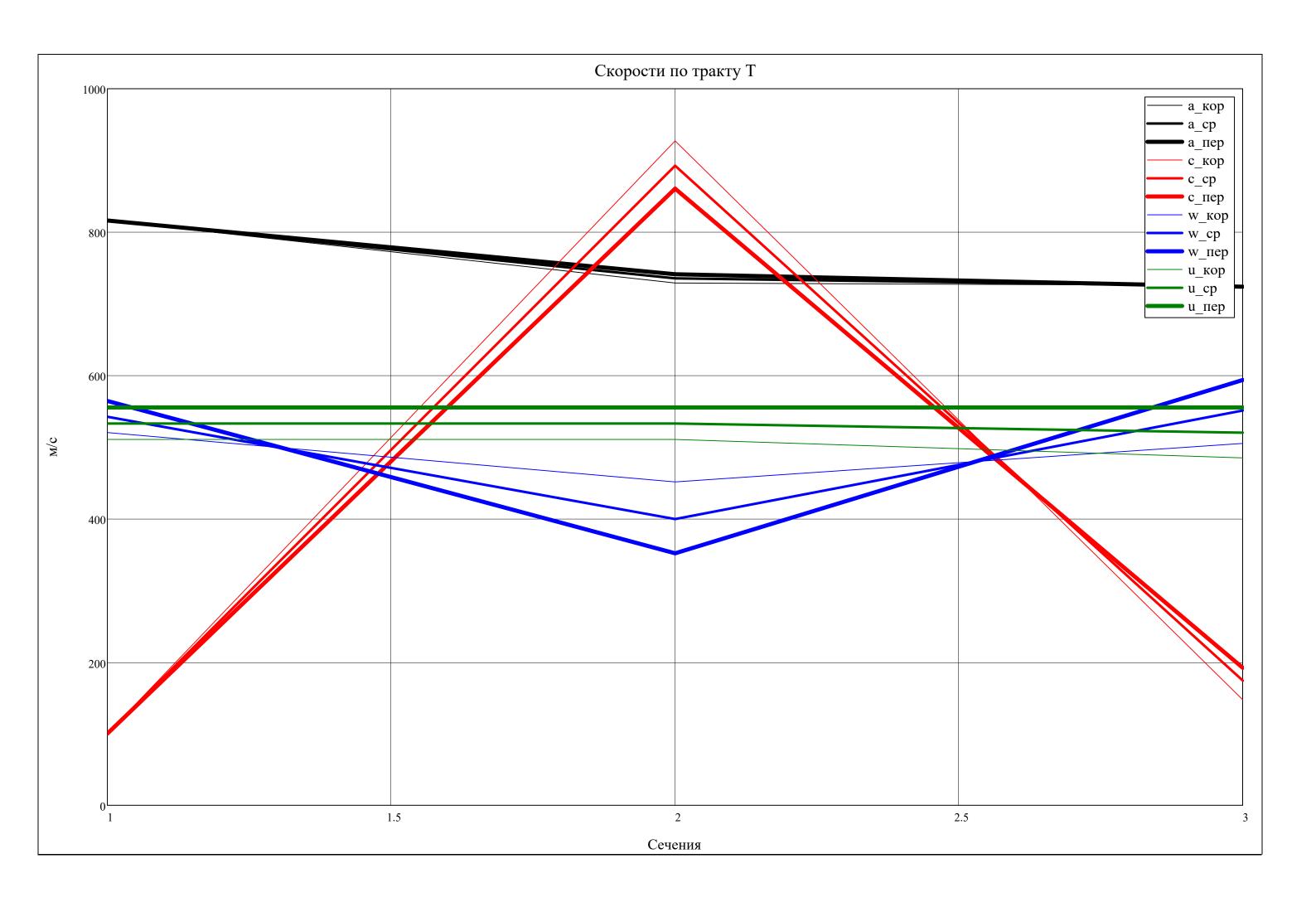
		1	2	3
$a^*_{\mathbf{w}} = \begin{bmatrix} T \\ -1 \end{bmatrix}$	1	783.4	698.4	699.3
W	2	785.3	700.2	703.2
	3	787.4	702.1	707.3

$$\mathbf{a_{3B}}^{T} = \begin{bmatrix} & 1 & 2 & 3 \\ 1 & 816.1 & 728.8 & 725.3 \\ 2 & 816.1 & 735.4 & 724.4 \\ 3 & 816.1 & 741.2 & 723.7 \end{bmatrix}$$

		1	2	3
$\mathbf{w}^{\mathrm{T}} =$	1	520.2	451.4	504.9
••	2	542.2	399.5	550.9
	3	564.2	351.6	593.4

		1	2	3
$\mathbf{w}_{-}^{T} =$	1	510.5	-387.2	483.0
·· u	2	532.9	-331.3	522.7
	3	555.2	-278.0	561.6

		1	2	3
$\mathbf{w}_{0}^{T} =$	1	100.0	231.9	147.3
'' a	2	100.0	223.3	174.0
	3	100.0	215.3	191.7



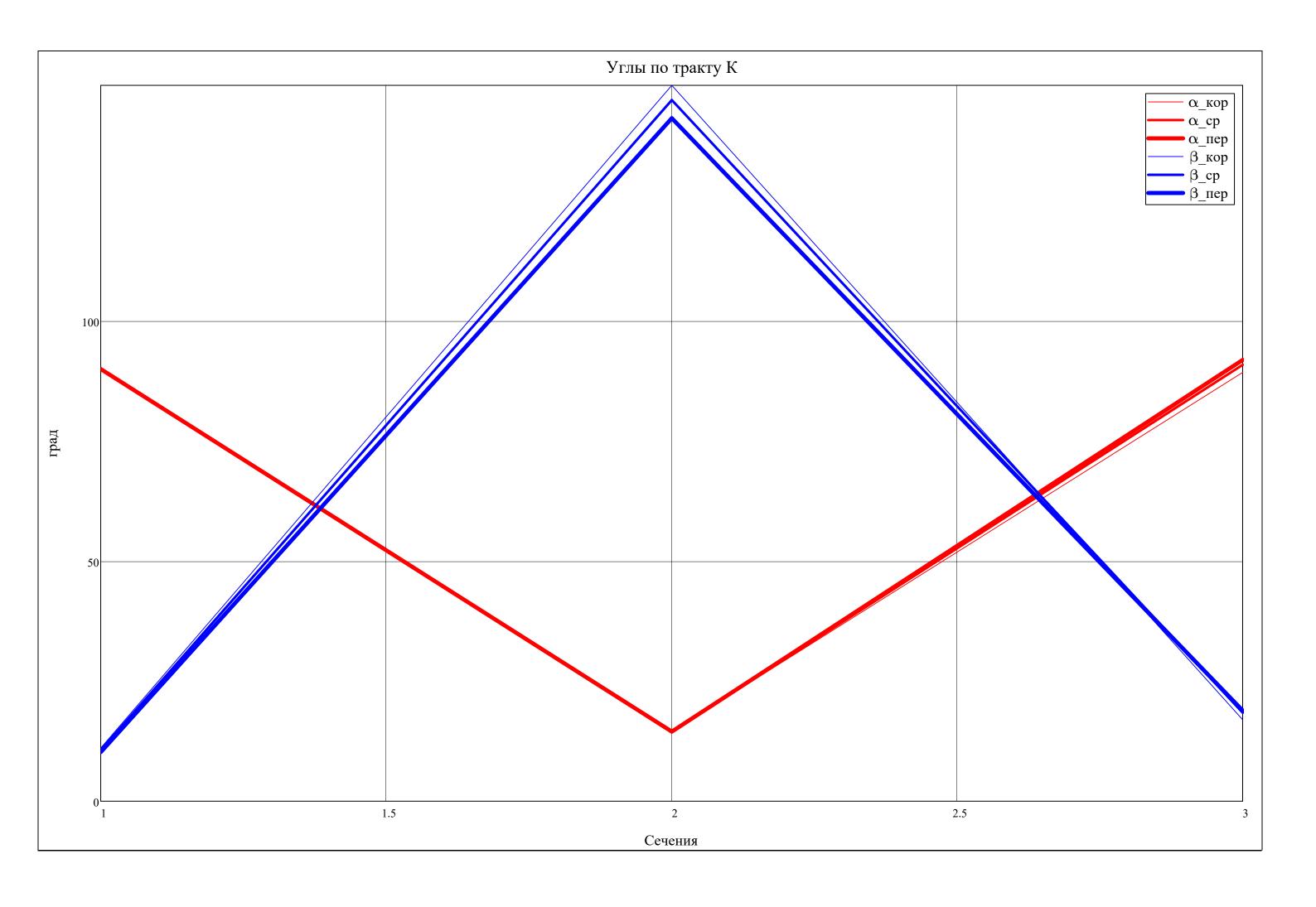
		1	2	3	
$\alpha^{T} =$	1	90.00	14.49	89.31	. 0
	2	90.00	14.49	90.87	
	3	90.00	14.49	91.90	

		1	2	3	
$80^{\circ} \leq \alpha^{T} =$	1	1	0	1	
ου <u> </u>	2	1	0	1	
	3	1	0	1	

		1	
ε., <sup>T</sup> =	1	75.51	.0
$\epsilon_{ m stator} =$	2	75.51	
	3	75.51	

[1, c.78]

$$\varepsilon_{\text{rotor}}^{\text{T}} = \begin{bmatrix}
 & 1 \\
1 & 132.12 \\
2 & 127.61 \\
3 & 123.40
\end{bmatrix}$$

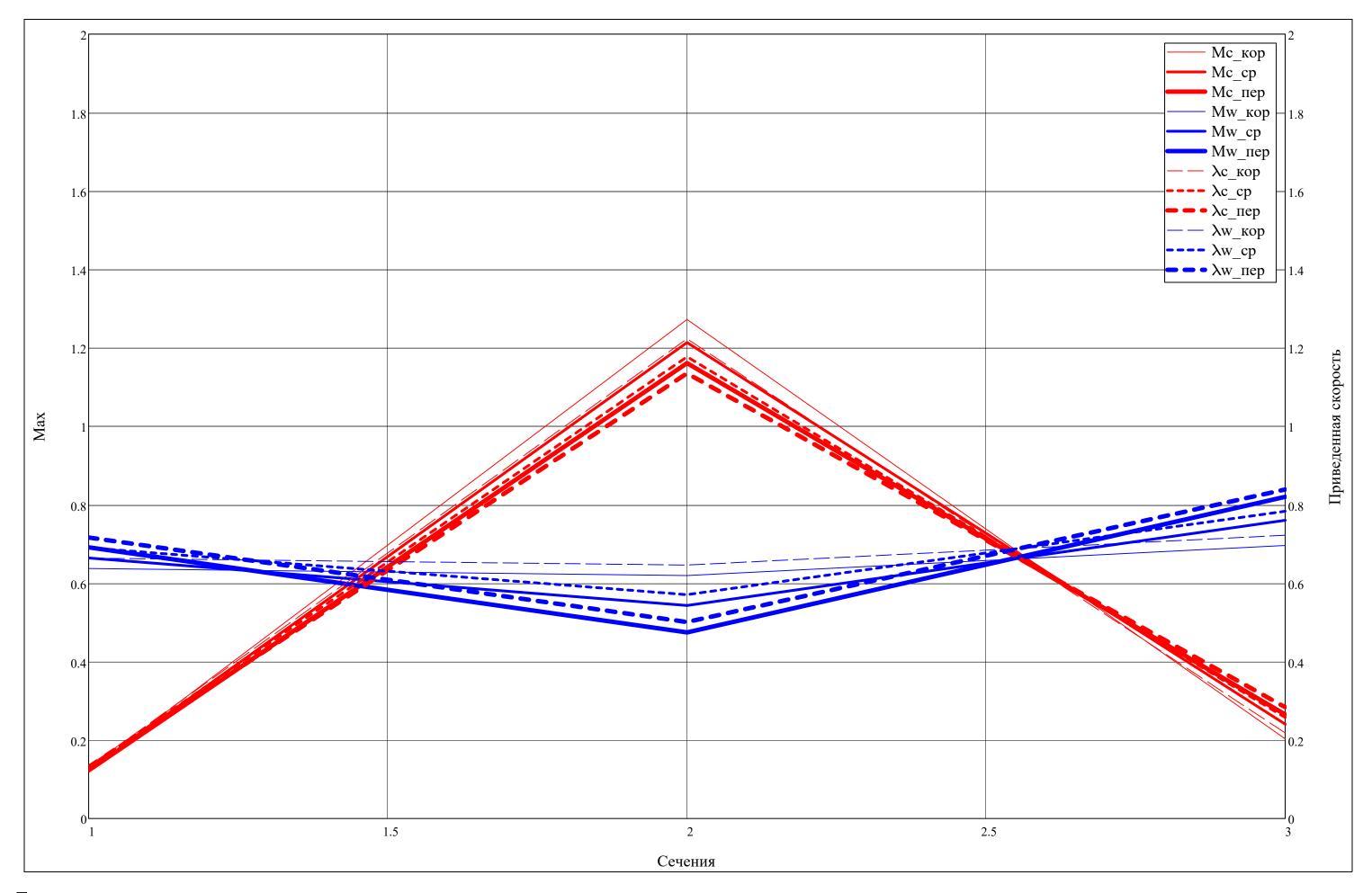


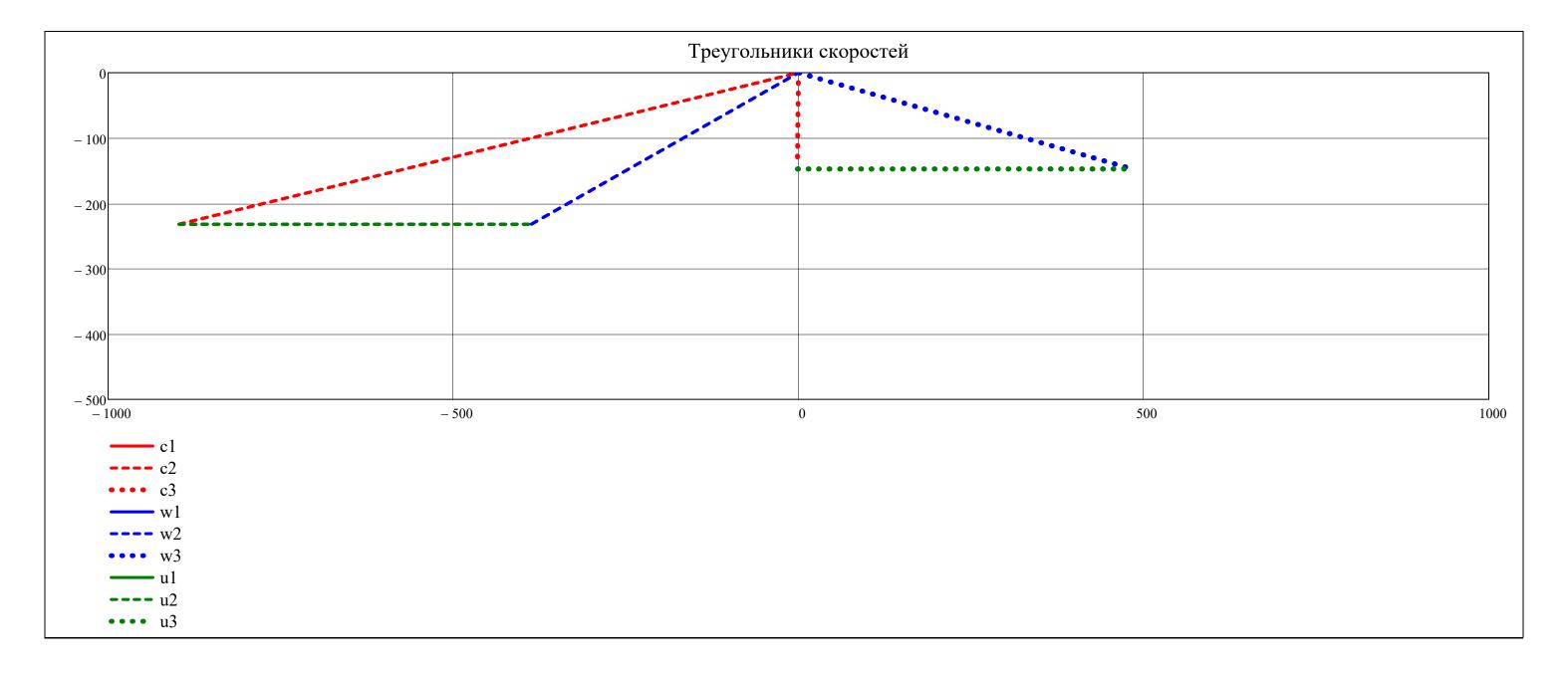
$$\lambda_c^T = \begin{array}{|c|c|c|c|c|c|}\hline & 1 & 2 & 3 \\ \hline 1 & 0.131 & 1.223 & 0.218 \\ \hline 2 & 0.131 & 1.177 & 0.257 \\ \hline 3 & 0.131 & 1.135 & 0.284 \\ \hline \end{array}$$

		1	2	3
$M^T =$	1	0.123	1.272	0.203
···c	2	0.123	1.214	0.240
	3	0.123	1.161	0.265

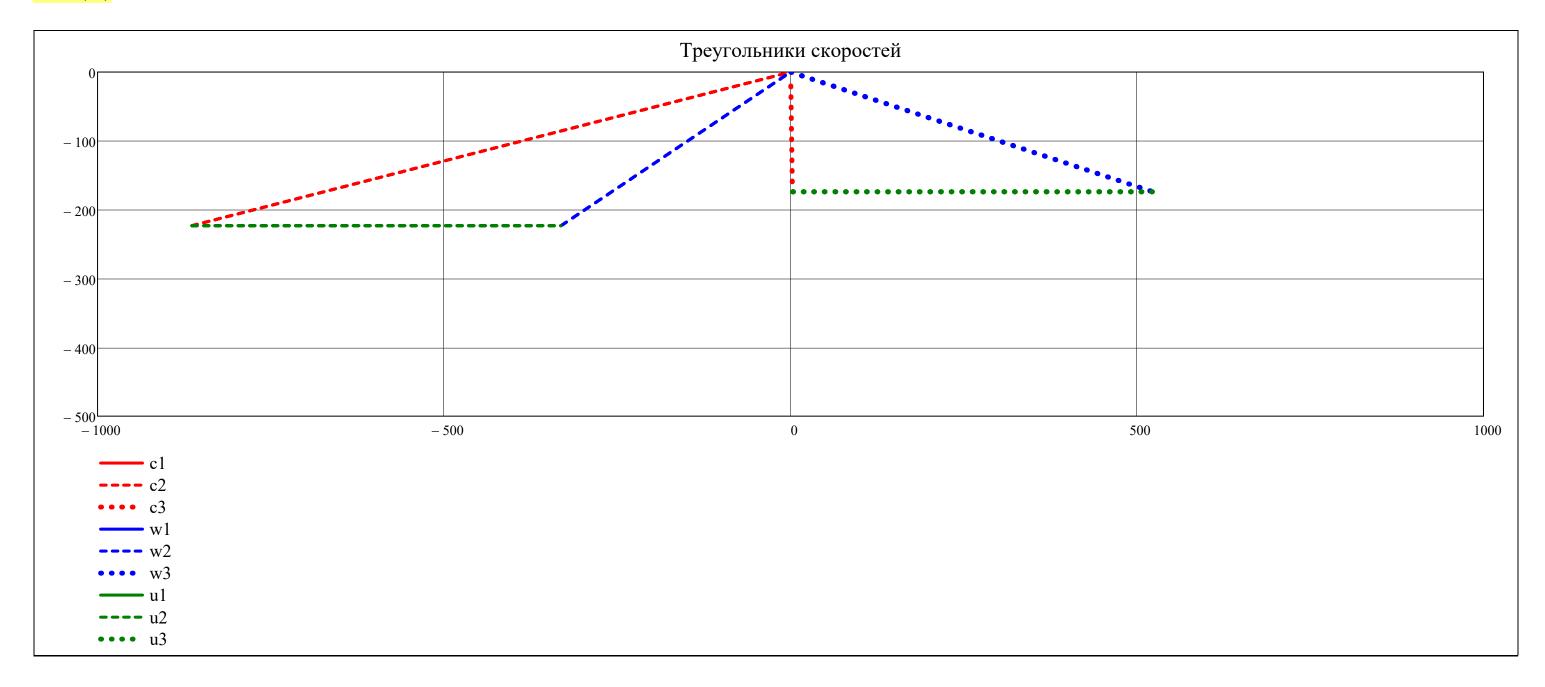
		1	2	3
$\lambda_{-} = T$	1	0.664	0.646	0.722
W	2	0.690	0.571	0.783
	3	0.717	0.501	0.839

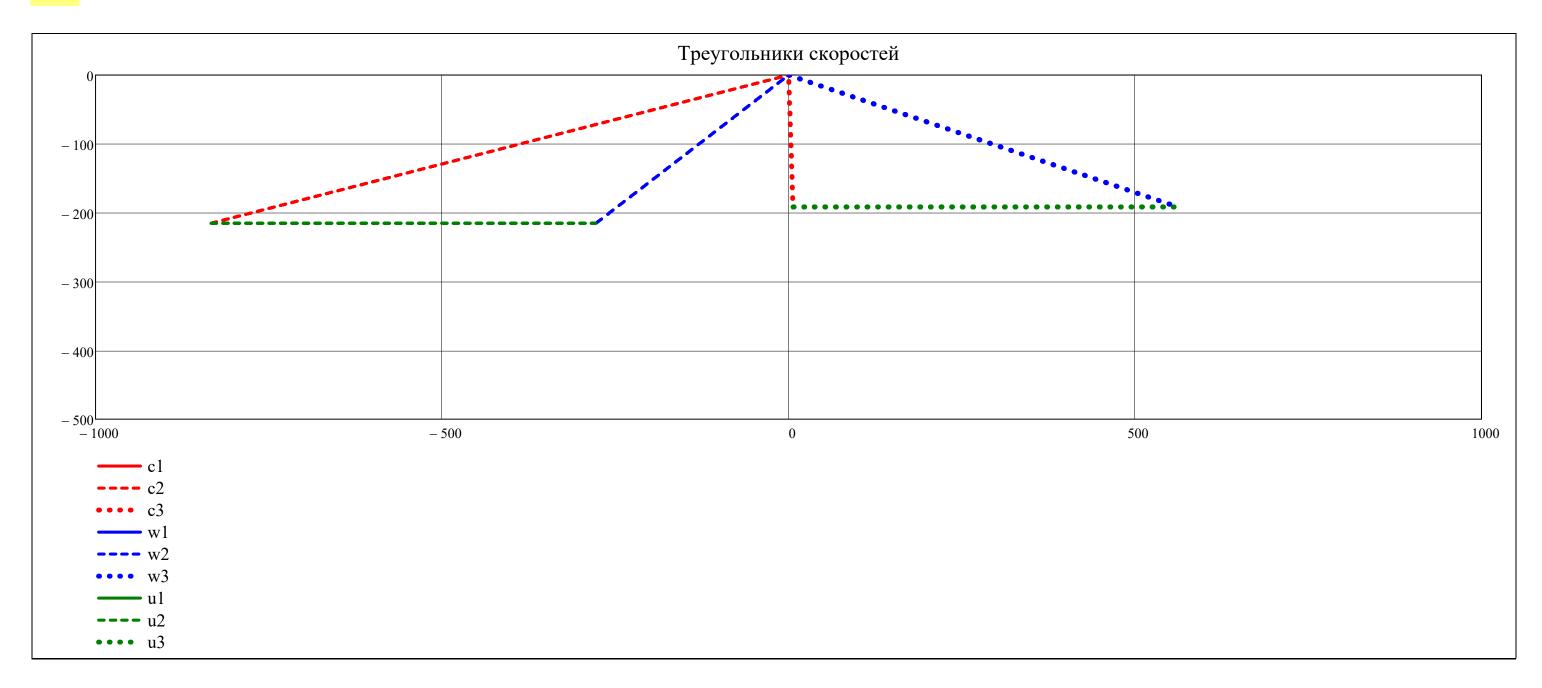
		1	2	3
$M_{xx}^T =$	1	0.637	0.619	0.696
W	2	0.664	0.543	0.760
	3	0.691	0.474	0.820











■ Построение треугольников скоростей в 3х сечениях

▼ Расчет хорд Л по парусности

$$\begin{vmatrix} \text{chord}_{votor} \\ \text{chord}_{votor} \\ \end{vmatrix} = \begin{vmatrix} \text{for } i = 1...Z \\ \text{sail} = \frac{R_{\pi(i,2), N_{i}} - R_{\pi(i,2), 1}}{R_{\pi(i,2), N_{i}} - R_{\pi(i,2), 1}} \\ \text{for } t = 1...N_{f} \\ \text{b}_{CArop} = \frac{\text{chord}_{stator}}{\text{sail}_{stator}} \frac{1 + \text{sail}}{1 + \text{sail}} \\ \text{b}_{CArop} = \frac{\text{chord}_{stator}}{\text{sail}_{stator}} \frac{1 + \text{sail}}{1 + \text{sail}} \\ \text{b}_{pKrop} = \frac{\text{chord}_{stator}}{\text{sail}_{rotor}} \frac{1 + \text{sail}}{\text{sail}_{rotor}} \\ \text{chord}_{stator} = \frac{\text{chord}_{stator}}{\text{b}_{pKrop}} \frac{1 + \text{chord}_{stator}}{\text{b}_{pKrop}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1 + \frac{1}{880}}}{1 + \frac{10}{1 + \frac{3}{1}}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1 + \frac{1}{1}}}{1 + \frac{1}{1 + \frac{1}{1}}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1 + \frac{1}{1}}}{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1 + \frac{1}{1}}}{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}}{1 + \frac{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}}{1 + \frac{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}} \\ \text{chord}_{stator} = \frac{1 + \frac{1}{1}} \\ \text{chord}_{stator} = \frac{$$

Длины хорд РК и СА (м):

$$chord_{stator}^{T} = \begin{vmatrix} 1 & 1 \\ 1 & 68.0 \\ 2 & 68.0 \\ \hline 3 & 68.0 \end{vmatrix} \cdot 10^{-3}$$

$$chord_{rotor}^{T} = \begin{array}{|c|c|} \hline 1 \\ \hline 1 & 38.4 \\ \hline 2 & 34.2 \\ \hline 3 & 31.4 \\ \hline \end{array} \cdot 10^{-3}$$

▼ Расчет параметров решетки

$$\begin{bmatrix} \frac{1}{r_{i}} \text{Inter} & \frac{1}{r_{o}} \text{totor} \\ \frac{1}{r_{o}} \text{tator} & \frac{1}{r_{o}} \text{totor} \\ \frac{1}{r_{o}} \text{totor}_{i,r} \end{bmatrix} = \pi \begin{bmatrix} \frac{m can \left(D_{st(i,1),r}, D_{st(i,2),r}\right)}{Z_{stator}_{i,r}} \\ \frac{m can \left(D_{st(i,2),r}, D_{st(i,3),r}\right)}{Z_{rotor}_{i,r}} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{i}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{i}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} = \pi \begin{bmatrix} \frac{m can \left(D_{st(i,1),r}, D_{st(i,2),r}\right)}{Z_{rotor}_{i,r}} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{i}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} = \begin{bmatrix} \frac{r_{i}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \end{bmatrix} \\ \end{bmatrix} \\ \begin{bmatrix} \frac{r_{o}}{r_{o}} \text{totor}_{i,r} \\ \frac{r_{o}}{r_{o}$$

$$\begin{pmatrix} v_{\text{установки}}(\alpha_{\text{st(i,1),r}},\alpha_{\text{st(i,2),r}}) \\ v_{\text{установки}}(\beta_{\text{st(i,2),r}},\beta_{\text{st(i,3),r}}) \end{pmatrix}$$

 $\frac{\pi}{2}$  добавляется в виду поворота рисунка на 90 град

## Относительные радиусы профилей ():

$$\frac{T}{r\_inlet_{stator}} = \begin{bmatrix}
 & 1 & \\
 & 1 & 6.000 \\
 & 2 & 6.000 \\
 & 3 & 6.000
\end{bmatrix}
 .\%$$

$$\frac{T}{r} = \begin{bmatrix}
 & 1 & \\
 & 1 & 5.950 \\
 & 2 & 4.550 \\
 & 3 & 3.850
\end{bmatrix}$$

$$\frac{T}{r_{outlet}} = \begin{bmatrix}
 & 1 \\
 & 1 \\
 & 2.550 \\
 & 2 \\
 & 1.950 \\
 & 3 \\
 & 1.650
\end{bmatrix}$$

### Относительная толщина профиля ():

$$\frac{\overline{c}_{\text{stator}}^{\text{T}}}{c_{\text{stator}}} = \frac{\boxed{\begin{array}{c|c} 1 \\ 1 & 15.00 \\ \hline 2 & 15.00 \\ \hline 3 & 15.00 \\ \end{array}} .\%$$

$$\frac{\overline{c}_{rotor}^{T}}{c_{rotor}^{T}} = \begin{vmatrix}
 & 1 & 17.00 \\
 & 1 & 17.00 \\
 & 2 & 13.00 \\
 & 3 & 11.00
\end{vmatrix} .\%$$

# Относительный шаг решетки ():

$$\left(\frac{t_{stator}}{chord_{stator}}\right)^{T} = \begin{vmatrix} 1\\ 1 & 0.8345\\ 2 & 0.8711\\ 3 & 0.9076 \end{vmatrix}$$

$$\left(\frac{t_{rotor}}{chord_{rotor}}\right)^{T} = \begin{vmatrix} 1 & 1 \\ 1 & 0.5829 \\ 2 & 0.6918 \\ \hline 3 & 0.7941 \end{vmatrix}$$

# Относительная густота решетки ():

$$\left(\frac{\text{chord}_{\text{rotor}}}{t_{\text{rotor}}}\right)^{\text{T}} = \begin{bmatrix} & 1\\ 1 & 1.716\\ 2 & 1.445\\ \hline 3 & 1.259 \end{bmatrix}$$

#### Длина хорды профиля [м]:

$$chord_{stator}^{T} = \begin{bmatrix} 1 \\ 1 & 68.0 \\ 2 & 68.0 \\ 3 & 68.0 \end{bmatrix} \cdot 10^{-3}$$

$$chord_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 38.4\\ 2 & 34.2\\ \hline 3 & 31.4 \end{bmatrix} \cdot 10^{-3}$$

#### Радиусы профилей:

$$r_{inlet_{rotor}}^{T} = \begin{bmatrix} & 1 \\ 1 & 2.28 \\ 2 & 1.56 \\ \hline 3 & 1.21 \end{bmatrix} \cdot 10^{-3}$$

$$r\_outlet_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 2.04 \\ 2 & 2.04 \\ 3 & 2.04 \end{bmatrix} \cdot 10^{-3}$$

$$r\_outlet_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 0.67 \\ 3 \\ 0.52 \end{bmatrix} \cdot 10^{-3}$$

## Толщина профиля [м]:

$$c_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1 \\ 1 & 10.20 \\ 2 & 10.20 \\ 3 & 10.20 \end{bmatrix} \cdot 10^{-3}$$

$$c_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 6.52\\ 2 & 4.45\\ 3 & 3.46 \end{bmatrix} \cdot 10^{-3}$$

# Шаг решетки [м]:

$$t_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1 \\ 1 \\ 56.7 \\ 2 \\ 59.2 \\ 3 \\ 61.7 \end{bmatrix} \cdot 10^{-3}$$

$$t_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 22.4\\ 2 & 23.7\\ \hline 3 & 25.0 \end{bmatrix} \cdot 10^{-3}$$

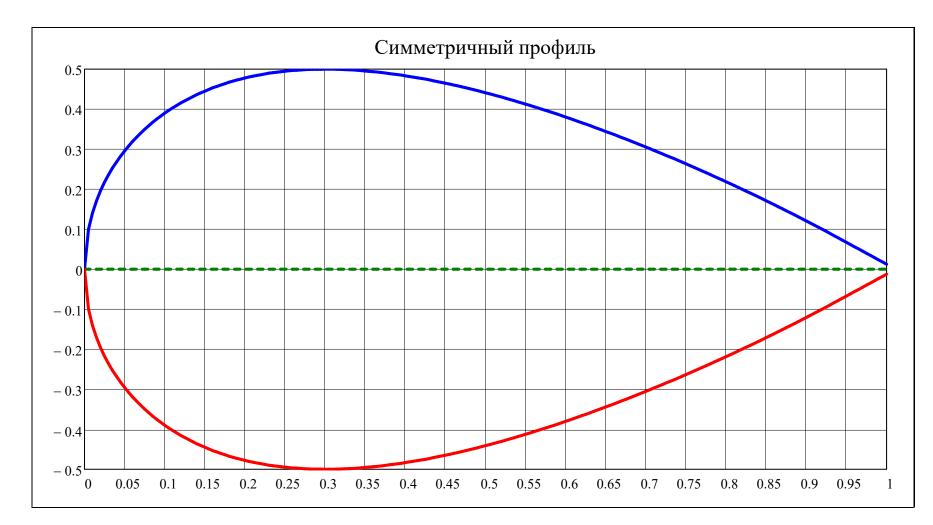
Угол поворота потока:	$ \varepsilon_{\text{stator}}^{\text{T}} = \begin{bmatrix}  & 1 \\  & 1 & 75.51 \\  & 2 & 75.51 \\  & 3 & 75.51 \end{bmatrix} $ . $\circ$	$ \varepsilon_{\text{rotor}}^{\text{T}} =  \begin{vmatrix}  & 1 & \\  & 1 & 132.12 \\  & 2 & 127.61 \\  & 3 & 123.40 \end{vmatrix} $ . $\circ$
Угол установки профиля:	$v_{\text{stator}}^{\text{T}} = \begin{bmatrix} 1 & 1 \\ 1 & 117.3 \\ 2 & 117.3 \\ \hline 3 & 117.3 \end{bmatrix} \cdot \circ$	$v_{\text{rotor}}^{\text{T}} = \begin{bmatrix} & 1 & \\ 1 & 112.0 \\ \hline 2 & 114.0 \\ \hline 3 & 115.4 \end{bmatrix} \cdot ^{\circ}$
Угол изгиба профиля:	$\pi - \varepsilon_{\text{stator}}^{\text{T}} = \begin{bmatrix} & 1 & \\ 1 & 104.5 \\ \hline 2 & 104.5 \\ \hline 3 & 104.5 \end{bmatrix} . \circ$	$\pi - \varepsilon_{\text{rotor}}^{\text{T}} = \begin{bmatrix} & 1 & \\ 1 & 47.9 \\ 2 & 52.4 \\ 3 & 56.6 \end{bmatrix} \cdot \circ$

#### ▼ Подключение симметричного профиля

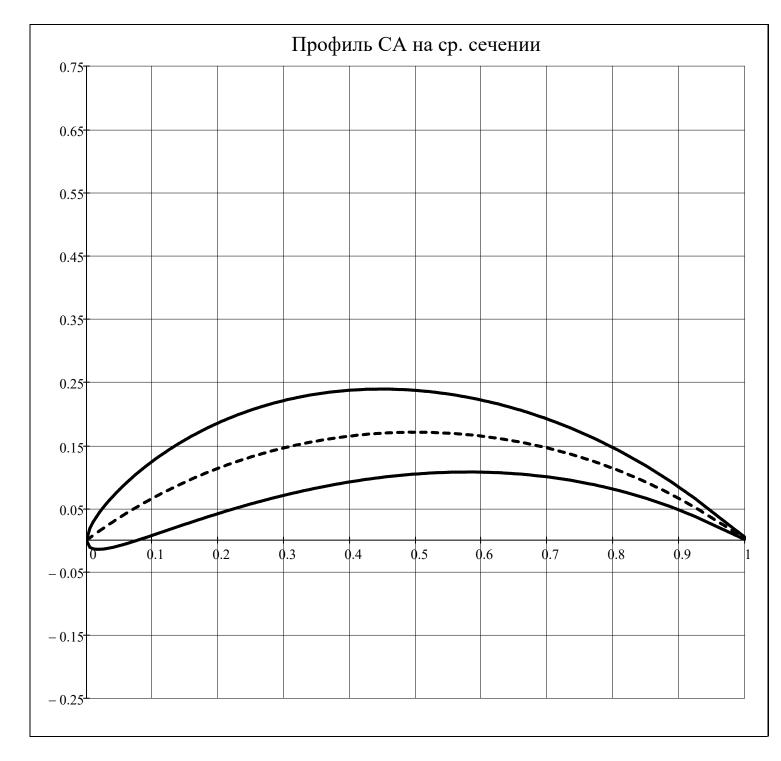
$$\begin{pmatrix} X_{U} & Y_{U} \\ X_{L} & Y_{L} \end{pmatrix} = NACA(0, 0, 100\%, 1)$$

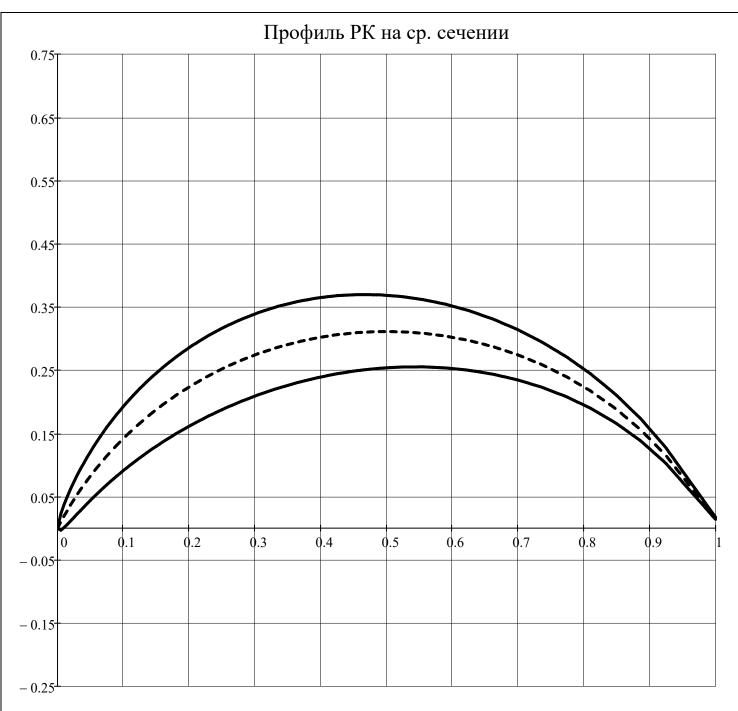
Относ. координаты профиля РК и СА:

$$\begin{split} \text{AIRFOIL}_0\Big(x, \text{line}\,\overline{,f}\,\overline{,x}_f, \overline{c}\,\Big) &= & \text{if } 0 \leq x \leq 1 \\ & & \text{linterp}\big(X_U, Y_U, x\big) \text{ if line} = \text{"+"} \\ & \frac{\text{linterp}\big(X_U, Y_U, x\big) + \text{linterp}\big(X_L, Y_L, x\big)}{2} \text{ if line} = \text{"0"} \\ & & \text{linterp}\big(X_L, Y_L, x\big) \text{ if line} = \text{"-"} \\ & & \text{NaN otherwise} \end{split}$$



$$\begin{split} \text{AIRFOIL}(x,\text{line},\overline{c}^-,\theta) &= \begin{vmatrix} \text{linterp}\big(X_U,y/b_{cp.J}\!\left(X_U,\theta\right) + Y_U\cdot\overline{c}^-,x\big) & \text{if line} = "+" \\ \frac{\text{linterp}\big(X_U,y/b_{cp.J}\!\left(X_U,\theta\right) + Y_U\cdot\overline{c}^-,x\big) + \text{linterp}\big(X_L,y/b_{cp.J}\!\left(X_L,\theta\right) + Y_L\cdot\overline{c}^-,x\big)}{2} & \text{if line} = "0" \\ \frac{\text{linterp}\big(X_L,y/b_{cp.J}\!\left(X_L,\theta\right) + Y_L\cdot\overline{c}^-,x\big) + \text{linterp}\big(X_L,y/b_{cp.J}\!\left(X_L,\theta\right) + Y_L\cdot\overline{c}^-,x\big)}{2} & \text{if line} = "-" \\ \text{NaN otherwise} & \end{aligned}$$





#### ▼ Результат расчета абсолютных геометрических характеристик сечений Л

$$1\_lower_{stator}^{T} = \begin{bmatrix} & 1 \\ 1 & 70.64 \\ 2 & 70.64 \\ \hline 3 & 70.64 \end{bmatrix} \cdot 10^{-3}$$

$$\operatorname{area}_{\text{stator}}^{\text{T}} = \begin{bmatrix} & 1\\ 1 & 473.87\\ 2 & 473.87\\ 3 & 473.87 \end{bmatrix} \cdot 10^{-6}$$

$$Sx_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 4232.2 \\ 2 & 4232.2 \\ 3 & 4232.2 \end{bmatrix} \cdot 10^{-9}$$

$$Sy_{stator}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 13563.5 \\ \hline 2 & 13563.5 \\ \hline 3 & 13563.5 \\ \hline \end{array} \cdot 10^{-9}$$

$$x0_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ 1 & 28.6 \\ \hline 2 & 28.6 \\ \hline 3 & 28.6 \\ \hline \end{array} \cdot 10^{-3}$$

$$y0_{\text{stator}}^{\text{T}} = \frac{\begin{vmatrix} 1 \\ 1 & 8.9 \\ 2 & 8.9 \\ 3 & 8.9 \end{vmatrix}}{2 \cdot 10^{-3}}$$

$$1\_upper_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 52.01\\ 2 & 44.78\\ \hline 3 & 40.21 \end{bmatrix} \cdot 10^{-3}$$

$$1\_lower_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 44.26\\ 2 & 39.55\\ \hline 3 & 36.21 \end{bmatrix} \cdot 10^{-3}$$

$$area_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 171.14\\ 2 & 103.96\\ \hline 3 & 74.28 \end{bmatrix} \cdot 10^{-6}$$

$$Sx_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 1711.6 \\ 2 & 883.3 \\ 3 & 554.2 \end{bmatrix} \cdot 10^{-9}$$

$$Sy_{rotor}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 2765.3 \\ \hline 2 & 1497.1 \\ \hline 3 & 983.0 \\ \hline \end{array} \cdot 10^{-9}$$

$$x0_{rotor}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\\hline 1 & 16.2 \\\hline 2 & 14.4 \\\hline 3 & 13.2 \\\hline \end{array} \cdot 10^{-3}$$

$$y0_{rotor}^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ \hline 1 & 10.0 \\ \hline 2 & 8.5 \\ \hline 3 & 7.5 \\ \hline \end{array} \cdot 10^{-3}$$

$$Jx_{stator}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 44264 \\ 2 & 44264 \\ \hline 3 & 44264 \end{bmatrix} \cdot 10^{-12}$$

$$Jy_{\text{stator}}^{\text{T}} = \begin{vmatrix} 1 \\ 1 & 508717 \\ 2 & 508717 \\ \hline 3 & 508717 \end{vmatrix} \cdot 10^{-12}$$

$$Jxy_{stator}^{T} = \begin{array}{|c|c|c|}\hline 1 & 1 \\\hline 1 & 128548 \\\hline 2 & 128548 \\\hline 3 & 128548 \\\hline \end{array} \cdot 10^{-12}$$

$$Jx0_{stator}^{T} = \begin{vmatrix} 1 & 1 \\ 1 & 6465 \\ 2 & 6465 \\ \hline 3 & 6465 \end{vmatrix} \cdot 10^{-12}$$

$$Jy0_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ \hline 1 & 120489 \\ \hline 2 & 120489 \\ \hline 3 & 120489 \\ \hline \end{array} \cdot 10^{-12}$$

$$Jxy0_{stator}^{T} = \begin{array}{|c|c|c|}\hline 1\\\hline 1\\\hline 2\\\hline 7409\\\hline 3\\\hline 7409\\\hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^{\text{T}} = \begin{vmatrix}
 & 1 \\
 & 1 & 3.70 \\
 & 2 & 3.70 \\
 & 3 & 3.70
\end{vmatrix}$$

$$Jx_{rotor}^{T} = \begin{bmatrix} 1\\1\\1\\2\\8184\\3\\4505 \end{bmatrix} \cdot 10^{-12}$$

$$Jy_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 58548 \\ 2 \\ 28251 \\ 3 \\ 17045 \end{bmatrix} \cdot 10^{-12}$$

$$Jxy_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 & 29122 \\ 2 & 13406 \\ \hline 3 & 7736 \end{bmatrix} \cdot 10^{-12}$$

$$Jx0_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 1656 \\ 2 & 679 \\ \hline 3 & 370 \end{bmatrix} \cdot 10^{-12}$$

$$Jy0_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \\ 6691 \\ 3 \\ 4037 \end{bmatrix} \cdot 10^{-12}$$

$$Jxy0_{rotor}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ 1 & 1466 \\ \hline 2 & 686 \\ \hline 3 & 402 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^{\text{T}} = \begin{vmatrix}
 & 1 \\
 & 1 & 6.75 \\
 & 2 & 6.43 \\
 & 3 & 6.18
\end{vmatrix}$$
.

$$Ju_{stator}^{T} = \begin{bmatrix} & 1 \\ 1 & 5986 \\ 2 & 5986 \\ \hline 3 & 5986 \end{bmatrix} \cdot 10^{-12}$$

$$Jv_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|c|c|}\hline & 1 & \\ \hline 1 & 120968.8 \\ \hline 2 & 120968.8 \\ \hline 3 & 120968.8 \\ \hline \end{array} \cdot 10^{-12}$$

$$Juv_{stator}^{T} = \begin{vmatrix} & 1 \\ 1 & -0 \\ 2 & -0 \\ \hline 3 & -0 \end{vmatrix} \cdot 10^{-12}$$

$$Jp_{stator}^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & \\ 1 & 126955 \\ \hline 2 & 126955 \\ \hline 3 & 126955 \\ \hline \end{array} \cdot 10^{-12}$$

$$Wp_{stator}^{T} = \begin{array}{|c|c|c|}\hline & 1 \\ \hline 1 & 3146.4 \\ \hline 2 & 3146.4 \\ \hline 3 & 3146.4 \\ \hline \end{array} \cdot 10^{-9}$$

$$Ju_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 1482 \\ 2 & 602 \\ 3 & 326 \end{bmatrix} \cdot 10^{-12}$$

$$Jv_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 14041\\ 2 & 6769\\ \hline 3 & 4081 \end{bmatrix} \cdot 10^{-12}$$

$$Juv_{rotor}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \cdot 10^{-12}$$

$$Jp_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 15522\\ 2 & 7371\\ 3 & 4407 \end{bmatrix} \cdot 10^{-12}$$

$$Wp_{rotor}^{T} = \begin{bmatrix} 1\\1&637.2\\2&342.1\\3&224.1 \end{bmatrix} \cdot 10^{-9}$$

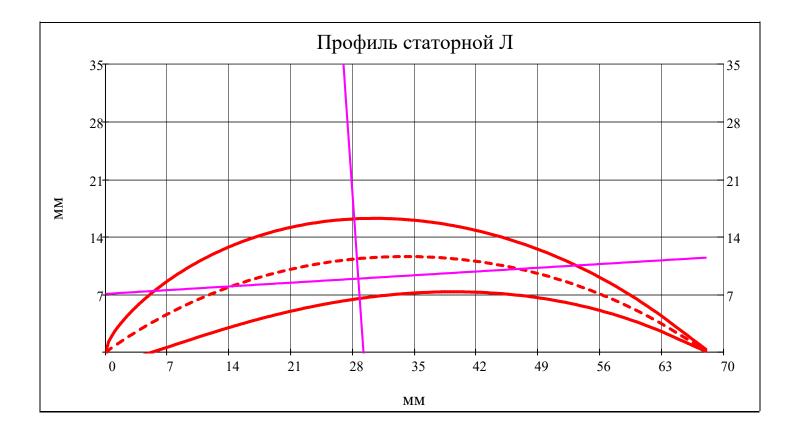
		1	
$CPx_{stator}^{T} =$	1	23.790	$\cdot 10^{-3}$
Stator	2	23.790	10
	3	23.790	

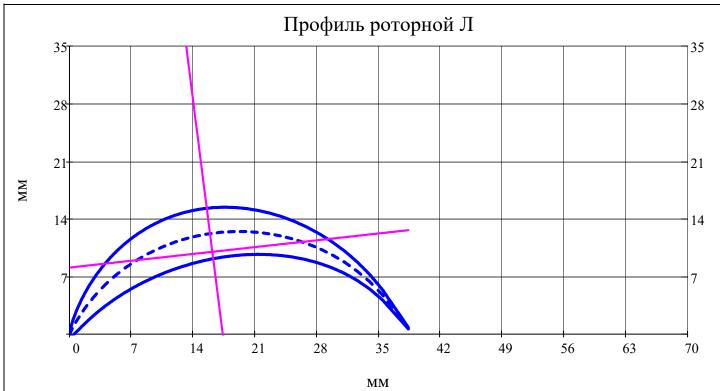
$$CPx_{rotor}^{T} = \begin{bmatrix} & 1 & \\ 1 & 13.430 \\ \hline 2 & 11.969 \\ \hline 3 & 10.999 \end{bmatrix} \cdot 10^{-3}$$

$$CPy_{stator}^{T} = \begin{bmatrix} & 1 & \\ 1 & 0.0000 \\ \hline 2 & 0.0000 \\ \hline 3 & 0.0000 \end{bmatrix} \cdot 10^{-3}$$

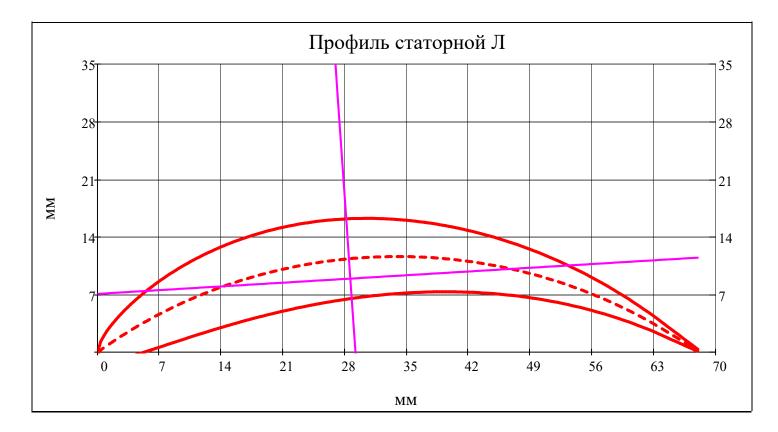
$$CPy_{rotor}^{T} = \begin{bmatrix} & 1\\ 1 & 0.0000\\ \hline 2 & 0.0000\\ \hline 3 & 0.0000 \end{bmatrix} \cdot 10^{-3}$$

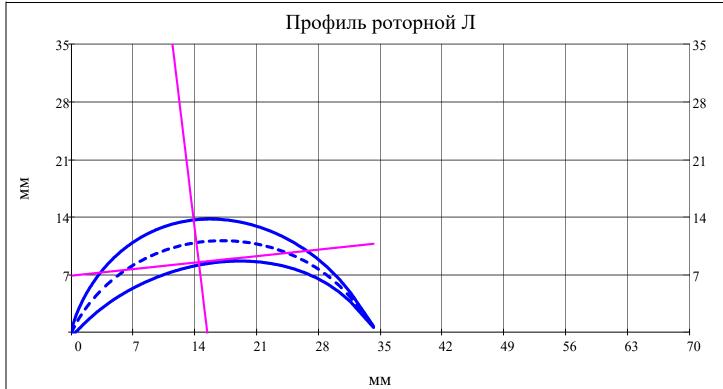
Результат расчета абсолютных геометрических характеристик сечений Л



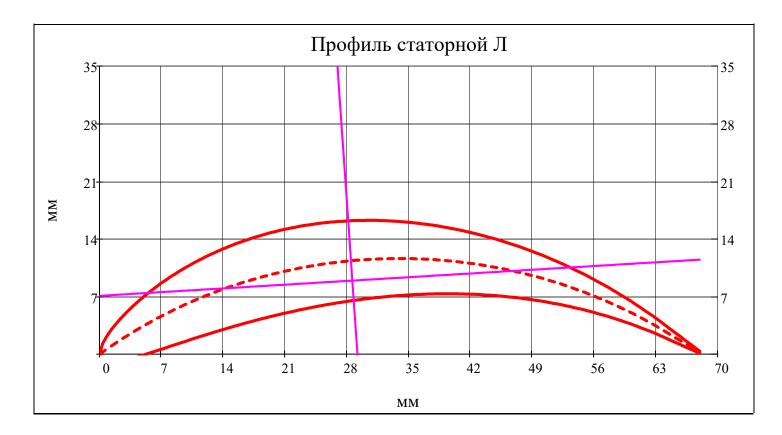


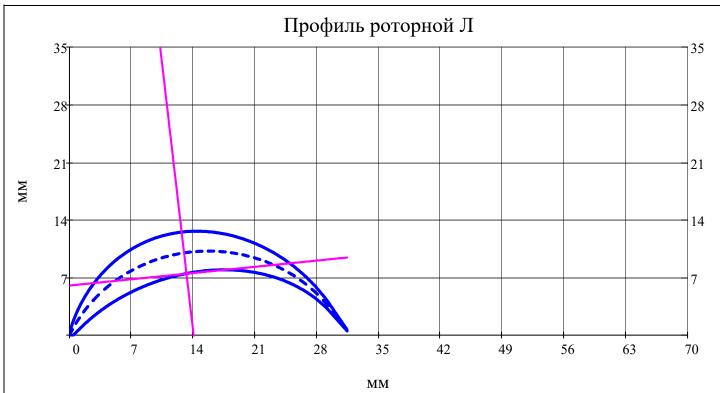
## $rac{r}{m} = av(N_r)$











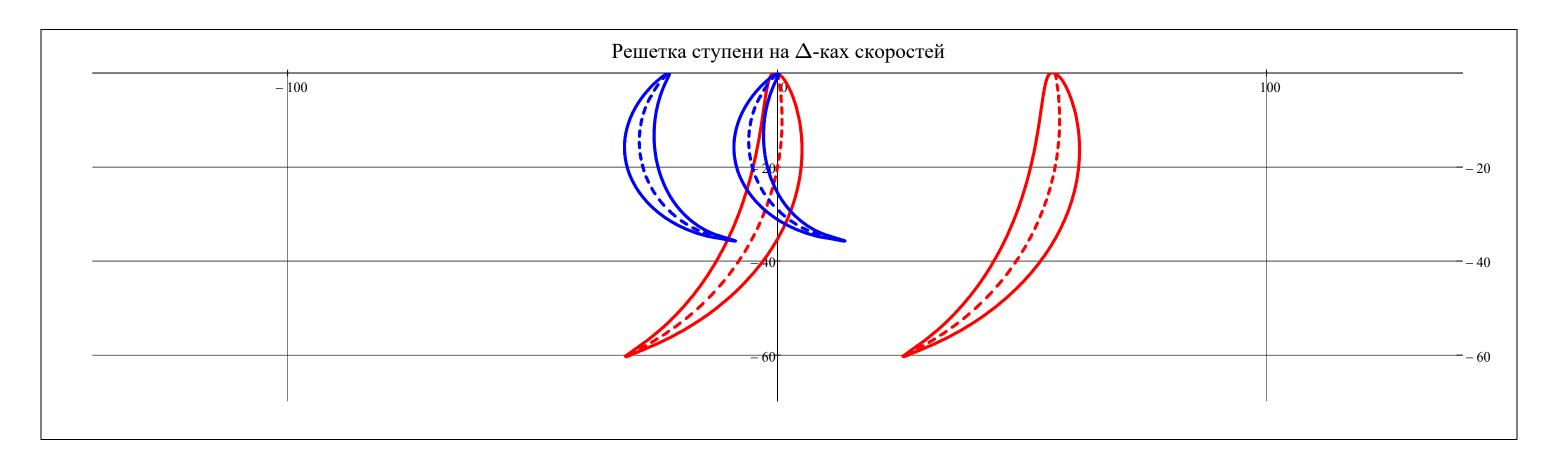
■ Построение профилей Л РК и НА

Рассматриваемая ступень: 
$$j = Z$$
 =  $j = Z$  =  $j = Z$  |  $j = Z$  | "Такой ступени не существует!" if  $(j < 1) \lor (j > Z)$  |  $j$  otherwise

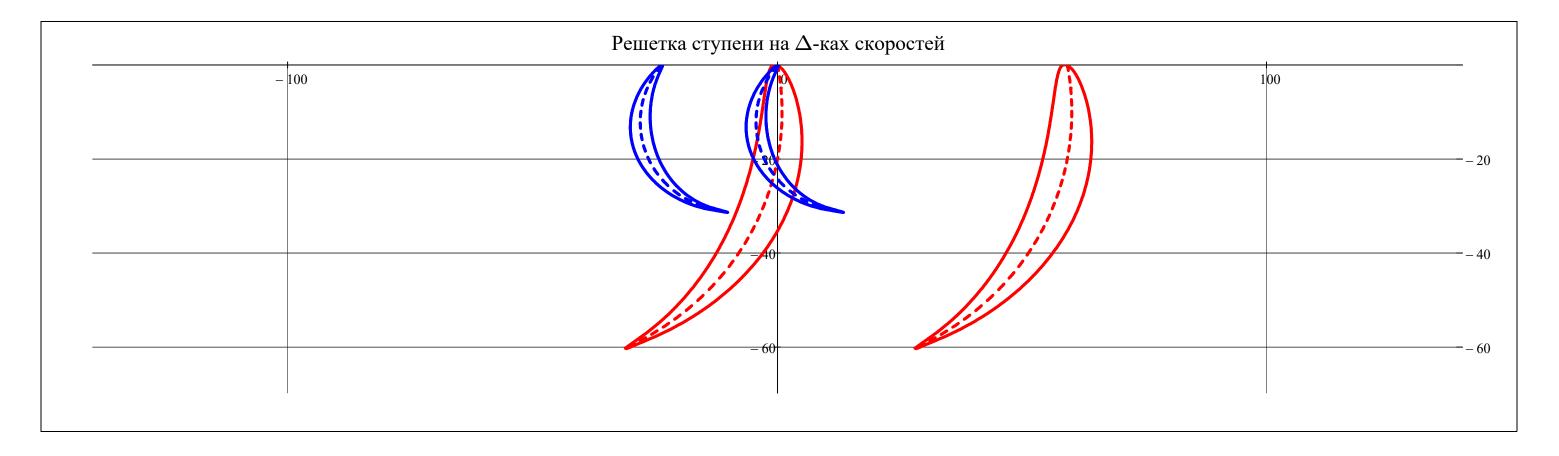
$$b_{\text{Line}} = \frac{\text{ceil}\left(\text{max}\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

▼ Построение плоских решеток профилей Л на треугольниках скоростей

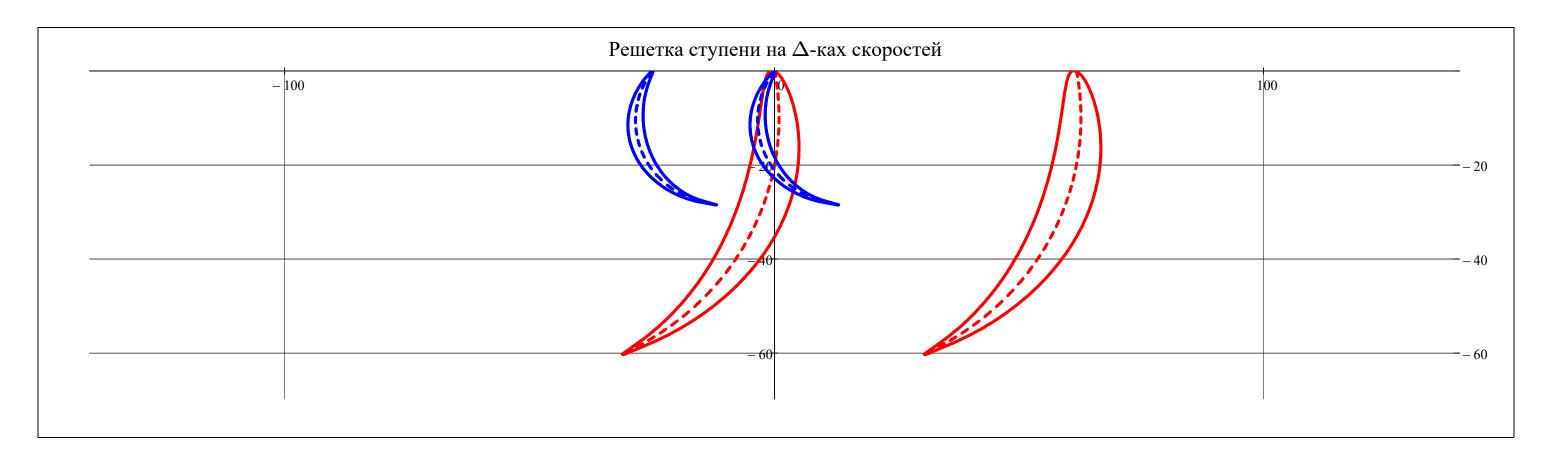




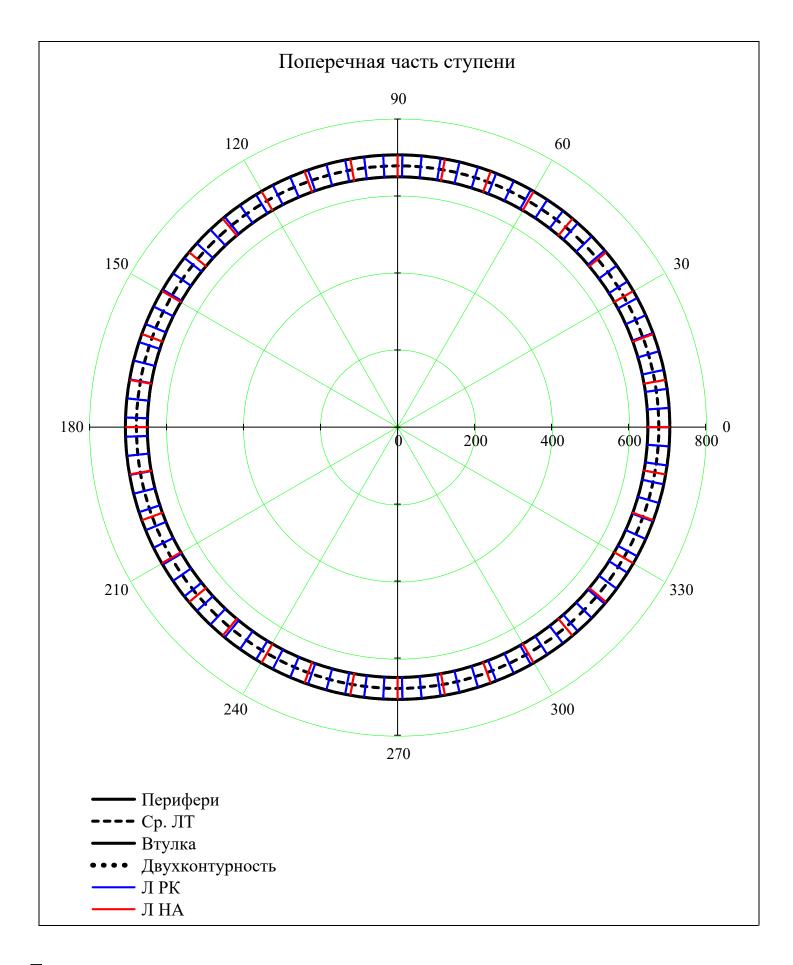
 $r = av(N_r)$ 







▲ Построение плоских решеток профилей Л на треугольниках скоростей



```
\nu 0_{\rm M3\Gamma.stator}
                                                                                                                                                                                                                                                                                                                                                                   \nu 0_{\rm M3\Gamma,rotor}
                                                           \nu 0_{
m yr.n.stator}
                                                                                                                                                                                                                                                                                                                                                                   ν0<sub>угл.rotor</sub>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             for i \in 1...Z
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  for r \in av(N_r)

u^0угл.stator_bondage 
u^0угл.rotor_bondage
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             for mode \in 1...6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      \nu 0_{\text{M3}\Gamma.\text{stator}_{\hat{1},\,\text{mode}}} = \nu 0_{\text{M3}\Gamma\text{M}} \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,1)}\,, h_{\text{st}(\hat{1},\,2)} \Big) \,, \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{1}}\,, \text{area}_{\text{stator}_{\hat{1},\,r}}\,, \\ \text{Ju}_{\text{stator}_{\hat{1},\,r}} \Big) \Big( \text{mode}\,, \text{mean} \Big( h_{\text{st}(\hat{1},\,2)} \,, h_{\text{st}(\hat{1},\,2)}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   \nu 0_{\text{M3}\Gamma.\text{rotor}_{\hat{i}\,,\,\text{mode}}} = \nu 0_{\text{M3}\Gamma\text{M}} \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \right) \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \right) \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \right) \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \right) \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Ju}_{\text{rotor}_{\hat{i}\,,\,r}} \right) \left( \text{mode}\,, \text{mean} \left( h_{\text{st}(\hat{i}\,,\,2)}\,, h_{\text{st}(\hat{i}\,,\,3)} \right), \\ \text{E\_blade}\,, \rho\_\text{blade}_{\hat{i}}\,, \text{area}_{\text{rotor}_{\hat{i}\,,\,r}}\,, \\ \text{Mode}\,, \text{Mode}\,, \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \\ \text{Mode}\,, \\ \text{Mode}\,, \text{Mode}\,, \\ \text{Mod}\,, \\ \text{Mode}\,, \\ \text{Mode}\,, \\ \text{Mode}\,, \\ \text{Mode}\,, \\ \text{Mode}\,, \\
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  \nu 0_{\text{yrn.stator}_{i,\,\text{mode}}} = \nu 0_{\text{yrn}} \left( \text{mode}\,, 0\,, \text{mean} \left( h_{\text{st}(i,\,1)}\,, h_{\text{st}(i,\,2)} \right), \text{Jung}(2\,, \mu\_\text{steel}\,, E\_\text{blade})\,, \rho\_\text{blade}_i\,, \text{stiffness}_{\text{stator}_{i,\,r}}\,, \text{Jp}_{\text{stator}_{i,\,r}} \right) \right)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      \nu 0_{y_{\Gamma JI}.rotor_{\hat{1}},\,mode} = \nu 0_{y_{\Gamma JI}} \left(mode,0,mean\left(h_{st(\hat{1},2)},h_{st(\hat{1},3)}\right),Jung(2,\mu\_steel,E\_blade),\rho\_blade_{\hat{1}},stiffness_{rotor_{\hat{1},r}},Jp_{rotor_{\hat{1},r}}\right) \right)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      \nu 0_{\text{YFJI.stator\_bondage}_{i, \, mode}} = \nu 0_{\text{YFJI}} \left( \text{mode} , 1, \text{mean} \left( h_{\text{st}(i, 1)}, h_{\text{st}(i, 2)} \right), \text{Jung}(2, \mu\_\text{steel}, E\_\text{blade}), \rho\_\text{blade}_i, \text{stiffness}_{\text{stator}_{i, r}}, \text{Jp}_{\text{stator}_{i, r}}, \text{Jp}_{\text{stator}_{i,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      \nu 0_{\text{YFJI.rotor\_bondage}_{\hat{1}, \, mode}} = \nu 0_{\text{YFJ}} \left( \text{mode} \,, 1 \,, \text{mean} \left( h_{st(\hat{1}, 2)} \,, h_{st(\hat{1}, 3)} \right) \,, \\ \text{Jung}(2 \,, \mu\_\text{steel} \,, E\_\text{blade}) \,, \rho\_\text{blade}_{\hat{1}} \,, \\ \text{stiffness}_{rotor_{\hat{1}, \, r}} \,, \\ \text{Jp}_{rotor_{\hat{1}, \, r}} \,, \\ \text{Jp}_{rotor
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   \nu 0_{\text{изг.rotor}}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \nu 0_{\rm M3\Gamma.stator}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 \nu 0_{y_{\Gamma JI}.stator}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     ν0<sub>угл.rotor</sub>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       \nu_0^0угл.stator bondage \nu_0^0угл.rotor bondage
```

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\operatorname{stack} \left(\nu 0_{\operatorname{M3\Gamma.stator}}, \nu 0_{\operatorname{M3\Gamma.rotor}}\right)^{\mathrm{T}} = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 1 & 12595 & 5145 & & & & & \\ 2 & 78937 & 32248 & & & & & \\ 3 & 221049 & 90305 & & & & & \\ 4 & 433492 & 177095 & & & & & \\ 5 & 716300 & 292630 & & & & & & \\ 6 & 1069752 & 437026 & & & & & & & \\ \end{bmatrix}$$

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\operatorname{stack} \left(\nu 0_{\text{угл.stator}}, \nu 0_{\text{угл.rotor}}\right)^{\text{T}} = \begin{bmatrix} & 1 & 2 \\ 1 & 8364 & 5507 \\ 2 & 25091 & 16521 \\ 3 & 41819 & 27535 \\ 4 & 58546 & 38548 \\ 5 & 75274 & 49562 \\ 6 & 92001 & 60576 \end{bmatrix}$$

$$\operatorname{stack} \left(\nu 0_{\text{УГЛ.stator\_bondage}}, \nu 0_{\text{УГЛ.rotor\_bondage}}\right)^{\text{T}} = \begin{bmatrix} & 1 & 2 \\ 1 & 16727 & 11014 \\ 2 & 33455 & 22028 \\ 3 & 50182 & 33041 \\ 4 & 66910 & 44055 \\ 5 & 83637 & 55069 \\ 6 & 100365 & 66083 \\ \end{bmatrix}$$

Pасчетный узел: type = "turbine"

Объем бандажной полки (м<sup>3</sup>):

Радиус положения ЦМ бандажной полки (м):

▶ Расчет Л на прочность —

$$\begin{aligned} \text{neutral\_line(type,x,i,r)} &= \frac{y0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}} + \text{tan}\Big(\Big(\alpha\_\text{major}_{rotor_{i,r}} + \varphi\_\text{neutral}_{rotor}\Big(i,R_{st(i,2),r}\Big)\Big)\Big) \cdot \left(x - \frac{x0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}}\right) & \text{if type} = \text{"rotor"} \\ \frac{y0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}} + \text{tan}\Big(\Big(\alpha\_\text{major}_{stator_{i,r}} + \varphi\_\text{neutral}_{stator}\Big(i,R_{st(i,2),r}\Big)\Big)\Big) \cdot \left(x - \frac{x0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}}\right) & \text{if type} = \text{"stator"} \\ \text{epure(type,x,i,r)} &= \frac{y0_{rotor_{i,r}}}{\text{chord}_{stator_{i,r}}} + \frac{-1}{(x - \frac{x0_{rotor_{i,r}}}{\text{chord}_{stator_{i,r}}})} & \text{if type} = \text{"rotor"} \end{aligned}$$

$$\begin{aligned} & \text{epure(type}, \textbf{x}, \textbf{i}, \textbf{r}) = \boxed{\frac{y0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}} + \frac{-1}{\text{tan}\left(\alpha\_{major_{rotor_{i,r}}} + \phi\_{neutral_{rotor}}\left(\textbf{i}, \textbf{R}_{st(i,2),r}\right) - \frac{\pi}{4}\right)} \cdot \left(\textbf{x} - \frac{\textbf{x}0_{rotor_{i,r}}}{\text{chord}_{rotor_{i,r}}}\right) & \text{if type} = "rotor" \\ \hline \frac{y0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}} + \frac{-1}{\text{tan}\left(\alpha\_{major_{stator_{i,r}}} + \phi\_{neutral_{stator}}\left(\textbf{i}, \textbf{R}_{st(i,2),r}\right) - \frac{\pi}{4}\right)} \cdot \left(\textbf{x} - \frac{\textbf{x}0_{stator_{i,r}}}{\text{chord}_{stator_{i,r}}}\right) & \text{if type} = "stator" \\ \hline \end{array}$$

$$u_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ -0.218 \\ 2 \\ 0.395 \\ \hline 3 \\ -5.994 \end{bmatrix} \cdot 10^{-3}$$

$$u_{-l_{rotor}}^{T} = \begin{bmatrix} & 1 & \\ 1 & 21.030 \\ \hline 2 & 18.832 \\ \hline 3 & -8.994 \end{bmatrix} \cdot 10^{-3}$$

$$u_{-}u_{stator}^{T} = \begin{array}{|c|c|c|c|c|}\hline & 1 & & \\ \hline 1 & -7.064 & \\ \hline 2 & 8.165 & \\ \hline 3 & 8.161 & \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{stator}}^{T} = \begin{bmatrix} & 1 & \\ 1 & -11.363 \\ 2 & -25.857 \\ \hline 3 & -25.850 \end{bmatrix} \cdot 10^{-3}$$

$$v_{-}u_{rotor}^{T} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 4.047 \\ \hline 3 \\ 13.959 \end{bmatrix} \cdot 10^{-3}$$

$$v_{-1}^{T} = \begin{bmatrix} 1 & 1 \\ 1 & -11.789 \\ 2 & -10.076 \\ \hline 3 & -17.325 \end{bmatrix} \cdot 10^{-3}$$

$$v_{u_{stator}}^{T} = \begin{bmatrix} & 1\\ 1 & 29.140\\ \hline 2 & 8.190\\ \hline 3 & 8.194 \end{bmatrix} \cdot 10^{-3}$$

$$v_{l_{stator}}^{T} = \begin{bmatrix} 1 \\ 1 \\ -38.695 \\ 2 \\ -14.465 \\ 3 \\ -14.477 \end{bmatrix} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{-Protor} & \sigma_{-n}rotor \\ \sigma_{-Dstator} & \sigma_{-n}rotor \\ \sigma_{-Dstator}$$

$$\begin{pmatrix} \sigma_{-} p_{rotor.} & \sigma_{-} p_{stator.} \\ \sigma_{-} p_{rotor.} & \sigma_{-} p_{stator.} \end{pmatrix} = \begin{bmatrix} \text{for } i \in 1 ... Z \\ \sigma_{-} p_{rotor.}(i,z) &= \text{interp} \Big( \text{lspline} \Big( \text{submatrix} \Big( R, \text{st}(i,1), \text{st}(i,1), 1, N_r \Big)^T, \text{submatrix} \Big( \sigma_{-} p_{rotor}, i, i, 1, N_r \Big)^T \Big), \text{submatrix} \Big( R, \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), N_r \Big)^T, \text{submatrix} \Big( \sigma_{-} p_{rotor}, i, i, 1, N_r \Big)^T \Big), \text{submatrix} \Big( R, \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), \text{st}(i,1), N_r \Big)^T, \text{submatrix} \Big( \sigma_{-} p_{stator}, i, i, 1, N_r \Big)^T \Big), \text{submatrix} \Big( R, \text{st}(i,1), \text{$$

$$\sigma_{p_{rotor}}^{T} = \begin{vmatrix} 1 & 1 \\ 1 & -18.45 \\ 2 & -8.87 \\ 3 & 0.00 \end{vmatrix} \cdot 10^{6}$$

$$\sigma_{-n_{rotor}}^{T} = \begin{array}{|c|c|c|c|}\hline & 1 \\ \hline 1 & 40.41 \\ \hline 2 & 21.85 \\ \hline 3 & 0.00 \\ \hline \end{array} \cdot 10^{6}$$

		1	
$\sigma n_{\text{max}} < 70.10^6 = $	1	1	
$\sigma_{\text{rotor}} \le 70.10^{\circ} = 1$	2	1	
	3	1	

$$\sigma_{p_{stator}}^{T} = \begin{bmatrix} 1 \\ 1 \\ 0.00 \\ 2 \\ 3.47 \\ 3 \\ 13.87 \end{bmatrix} \cdot 10^{6}$$

		1
$\sigma p_{\text{ototor}} \leq 70 \cdot 10^6 = 1$	1	1
$\sigma_{\text{pstator}} \leq 70.10 =$	2	1
	3	1

$$\sigma_{\text{nstator}}^{\text{T}} = \begin{bmatrix} & 1 \\ 1 & 0.00 \\ 2 & -7.07 \\ \hline 3 & -28.26 \end{bmatrix} \cdot 10^{6}$$

		1	
$\sigma = 0.10^6 = 0.00$	1	1	
$\sigma_{\text{nstator}} \leq 70.10^{\circ} =$	2	1	
	3	1	

$$\begin{pmatrix} \sigma_{rotor} \\ \sigma_{stator} \end{pmatrix} = \begin{cases} \text{for } i \in 1...Z \\ \text{for } r \in 1...N_r \end{cases}$$
 
$$\begin{vmatrix} \sigma_{rotor_{i,r}} = \sqrt{\left(\sigma_{-}z_{rotor}(i,R_{st(i,2),r}) + \max\left(\sigma_{-}p_{rotor_{i,r}},\sigma_{-}n_{rotor_{i,r}})\right)^2 + \tau_{rotor}(i,R_{st(i,2),r})^2}$$
 
$$\begin{vmatrix} \sigma_{stator_{i,r}} = \sqrt{\left(0 + \max\left(\sigma_{-}p_{stator_{i,r}},\sigma_{-}n_{stator_{i,r}}\right)\right)^2 + \tau_{stator}(i,R_{st(i,2),r})^2} \\ \begin{pmatrix} \sigma_{rotor} \\ \sigma_{stator} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{rotor.} \\ \sigma_{stator.} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \\ \sigma_{rotor.}(i,z) = \text{interp} \Big( \text{lspline} \Big( \text{submatrix} \Big( R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big( \sigma_{rotor}, i, i, 1, N_r \Big)^T \Big), \text{submatrix} \Big( R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big( \sigma_{rotor}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big( R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big( R, \text{st}(i,2), \text{st}(i,2), 1, N_r \Big)^T, \text{submatrix} \Big( \sigma_{stator}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big( \sigma_{rotor}, i, i, 1, N_r \Big)^T, \text{submatrix} \Big$$

$$\sigma_{\text{rotor}}^{\text{T}} = \begin{vmatrix} & 1 \\ 1 & 161.59 \\ 2 & 101.72 \\ \hline 3 & 0.00 \end{vmatrix} \cdot 10$$

$$\sigma_{\text{stator}}^{\text{T}} = \begin{bmatrix} & 1 & \\ 1 & 0.00 \\ 2 & 5.61 \\ \hline 3 & 16.44 \end{bmatrix} \cdot 10^{6}$$

$$\begin{vmatrix} safety_{rotor} \\ safety_{stator} \end{vmatrix} = \begin{vmatrix} for \ i \in 1...Z \\ for \ r \in 1...N_r \end{vmatrix}$$
 
$$\begin{vmatrix} safety_{rotor}_{i,\,r} \\ safety_{rotor}_{i,\,r} \end{vmatrix} = \begin{vmatrix} \frac{\sigma\_blade\_long_i}{\sigma_{rotor}_{i,\,r}} & if \ \sigma_{rotor}_{i,\,r} \neq 0 \\ \infty & otherwise \end{vmatrix}$$
 
$$safety_{stator}_{i,\,r} = \begin{vmatrix} \frac{\sigma\_blade\_long_i}{\sigma_{stator}_{i,\,r}} & if \ \sigma_{stator}_{i,\,r} \neq 0 \\ \infty & otherwise \end{vmatrix}$$
 
$$\begin{vmatrix} safety_{rotor} \\ safety_{stator} \end{vmatrix}$$
 
$$otherwise$$
 
$$\begin{vmatrix} safety_{rotor} \\ safety_{stator} \end{vmatrix}$$

		1
$safety_{rotor}^{T} =$	1	1.27
rotor	2	2.02
	3	000000000000000000000000000000000000000

		1
safety T	1	000000000000000000000000000000000000000
safety <sub>stator</sub> =	2	36.53
	3	12.47

		1	
$safety_{rotor}^{T} \ge safety =$	1	0	
rotor = surety	2	1	
	3	1	

		1
$safety_{stator}^{T} \ge safety =$	1	1
stator = surety	2	1
	3	1

Рассматриваемая ступень: 
$$j=1$$
 if type = "compressor" = 1 Z if type = "turbine"  $j=1$  "Такой ступени не существует!" if  $(j<1)\vee(j>Z)$   $j$  otherwise

$$b_{\text{line}} = \frac{\text{ceil}\left(\text{max}\left(\text{chord}_{rotor_{j,N_r}}, \text{chord}_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

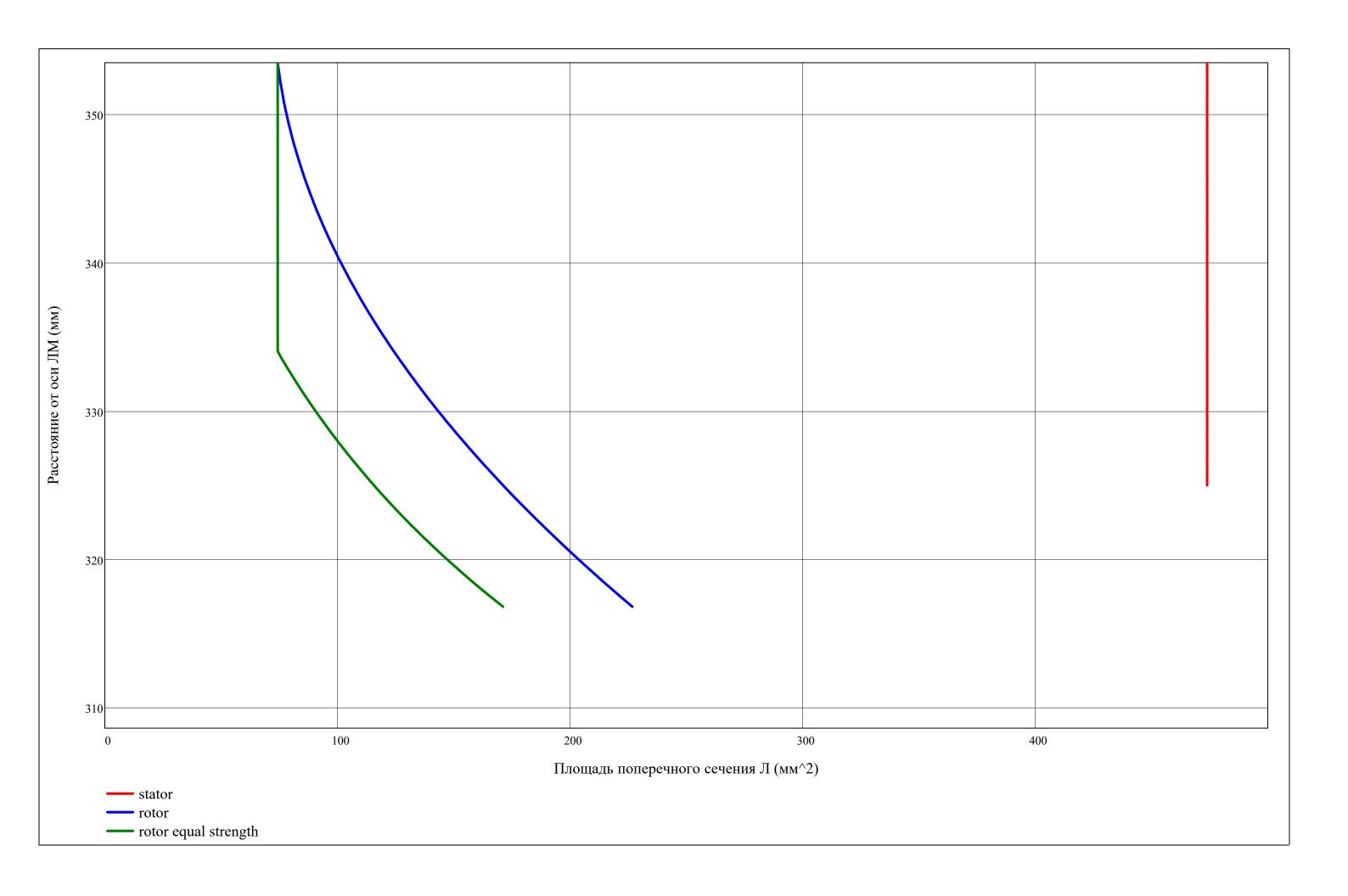
$$Rj = submatrix (R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r) = \begin{vmatrix} 1 & 2 & 3 \\ 1 & 325.0 & 339.2 & 353.5 \\ 2 & 325.0 & 339.2 & 353.5 \\ 3 & 308.6 & 331.0 & 353.5 \end{vmatrix} \cdot 10^{-3}$$

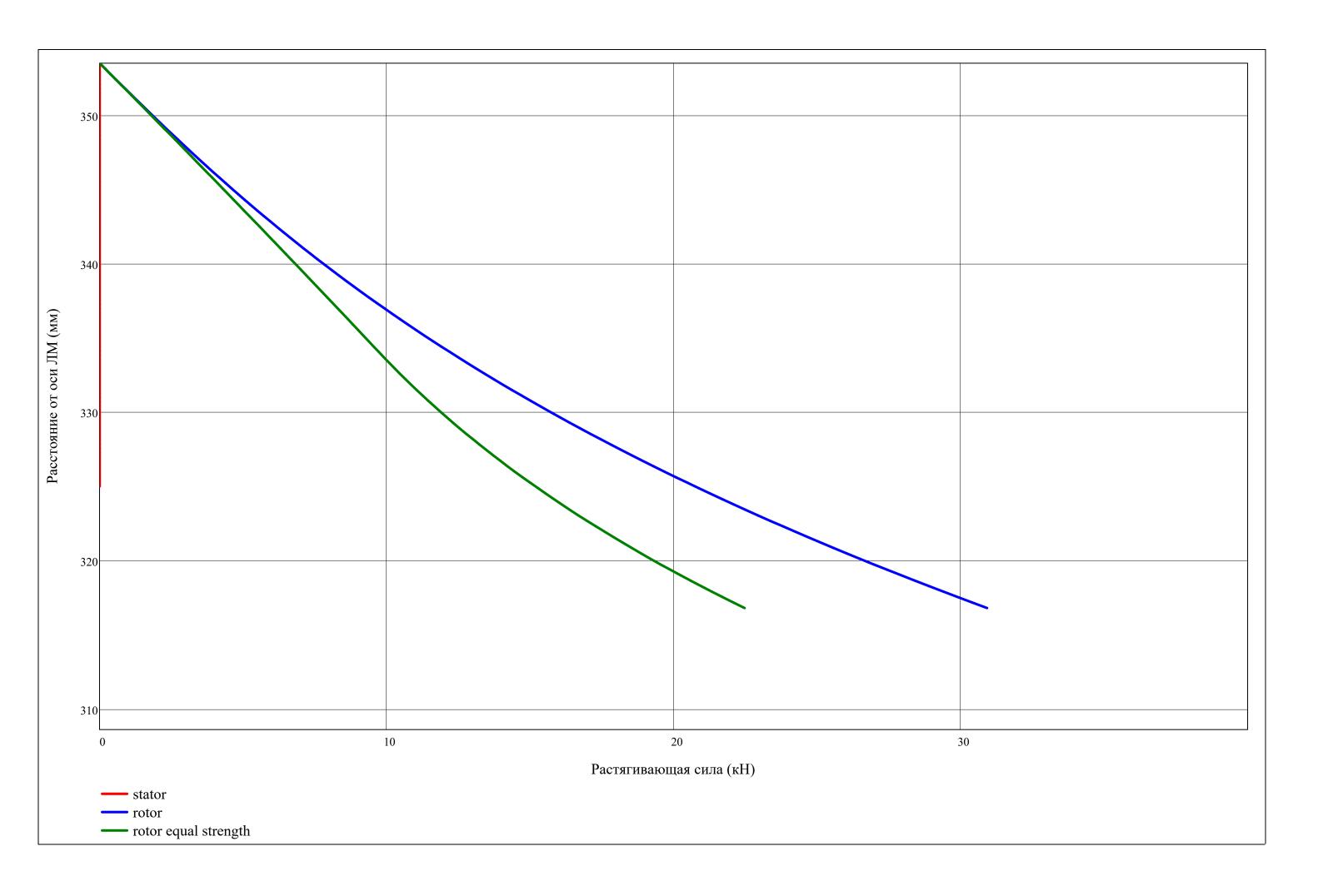
Дискретизация по высоте Л:

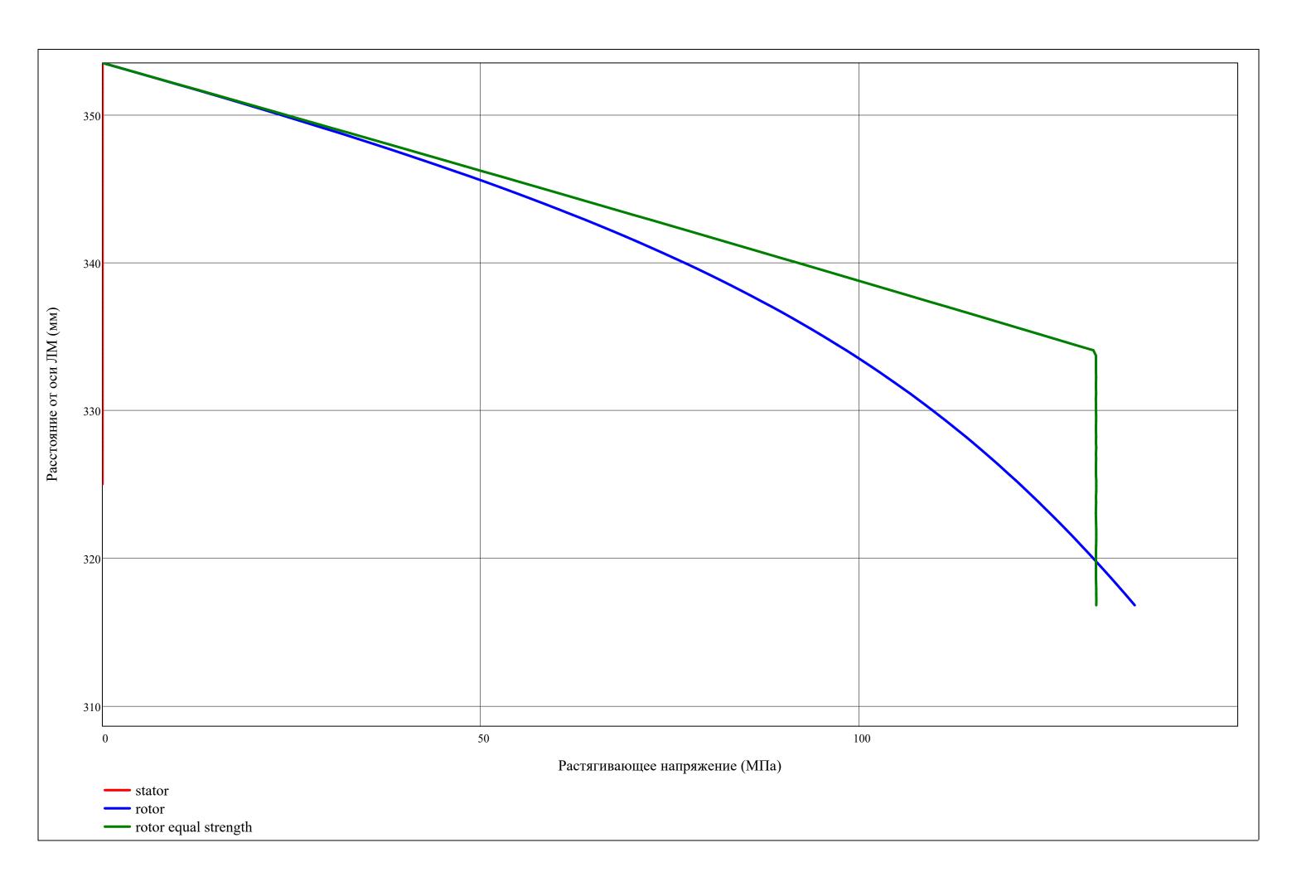
$$z = min(Rj), min(Rj) + \frac{max(Rj) - min(Rj)}{100}...max(Rj)$$

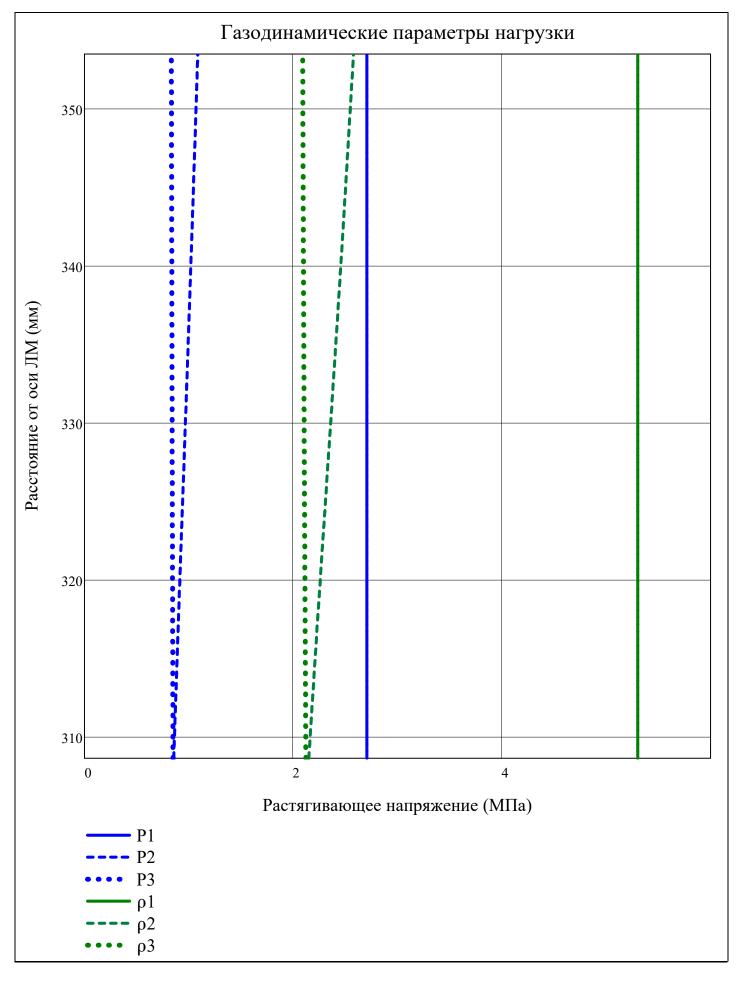
$$z_{rotor} = \begin{vmatrix} mean \left(Rj_{1,1}, Rj_{2,1}\right), mean \left(Rj_{1,1}, Rj_{2,1}\right) + \frac{mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) - mean \left(Rj_{1,1}, Rj_{2,1}\right)}{100} ... mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) \text{ if type = "compressor"} \\ mean \left(Rj_{2,1}, Rj_{3,1}\right), mean \left(Rj_{2,1}, Rj_{3,1}\right) + \frac{mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) - mean \left(Rj_{2,1}, Rj_{3,1}\right)}{100} ... mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) \text{ if type = "turbine"} \\ 100 \end{aligned}$$

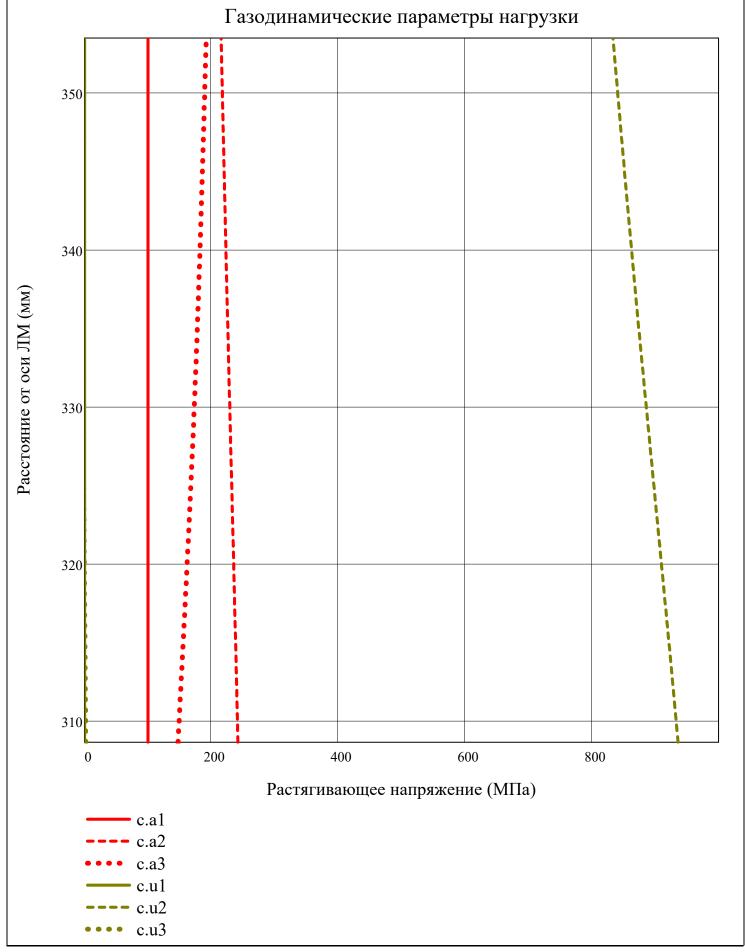
$$z_{stator} = \begin{bmatrix} mean \left(Rj_{2,1}, Rj_{3,1}\right), mean \left(Rj_{2,1}, Rj_{3,1}\right) + \frac{mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) - mean \left(Rj_{2,1}, Rj_{3,1}\right)}{100} ... mean \left(Rj_{2,N_r}, Rj_{3,N_r}\right) & \text{if type} = "compressor" \\ mean \left(Rj_{1,1}, Rj_{2,1}\right), mean \left(Rj_{1,1}, Rj_{2,1}\right) + \frac{mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) - mean \left(Rj_{1,1}, Rj_{2,1}\right)}{100} ... mean \left(Rj_{1,N_r}, Rj_{2,N_r}\right) & \text{if type} = "turbine" \\ \end{bmatrix}$$

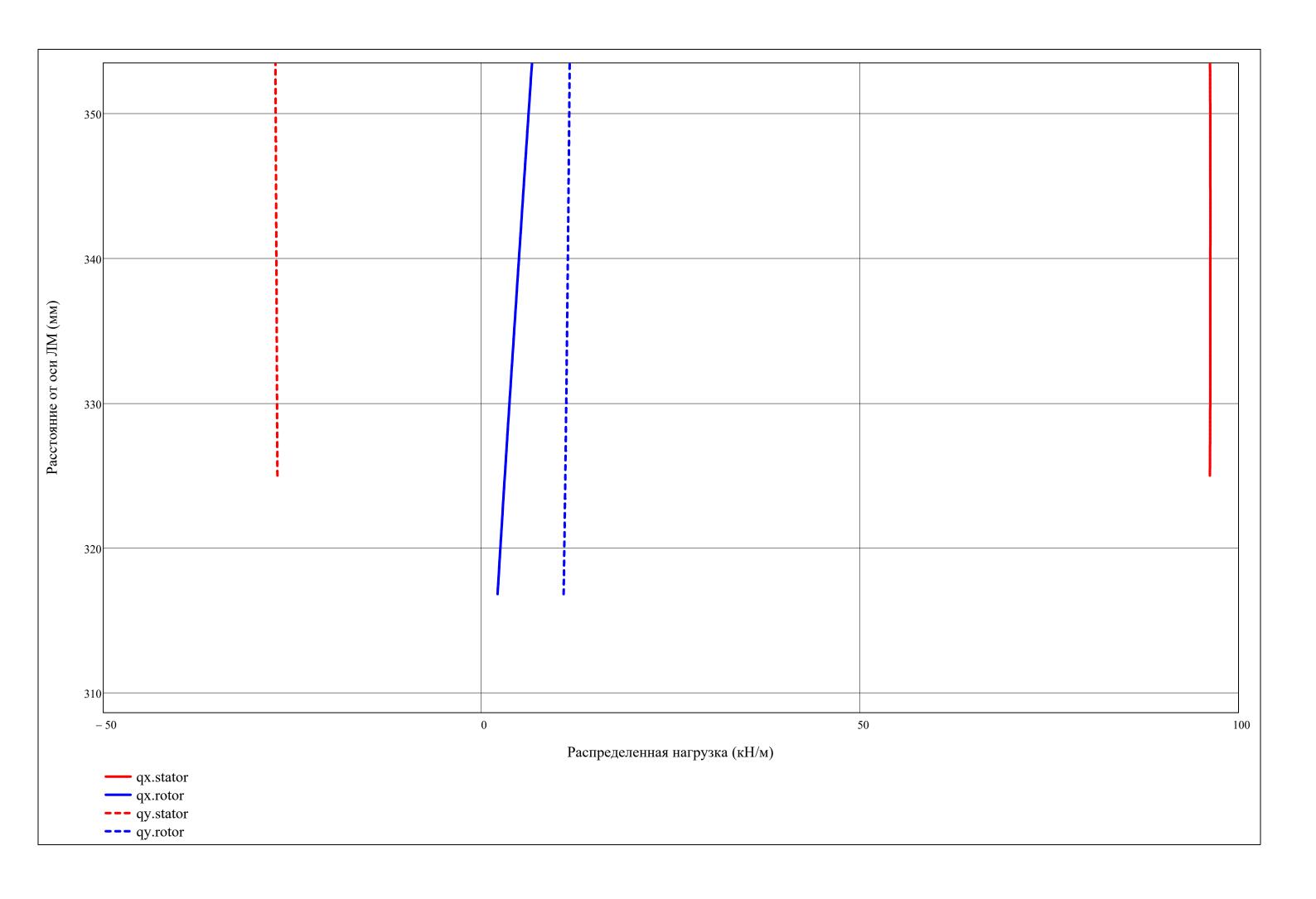


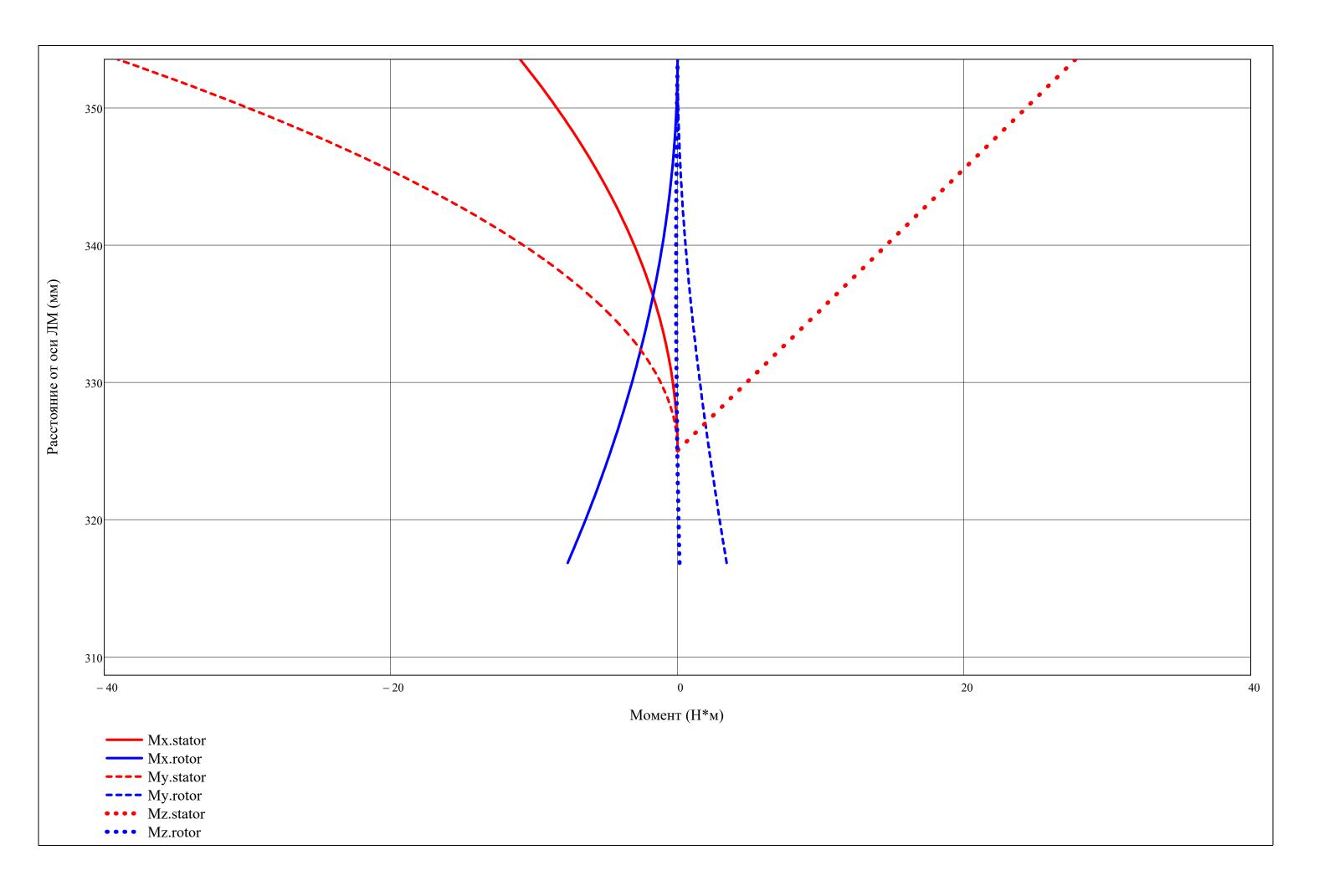


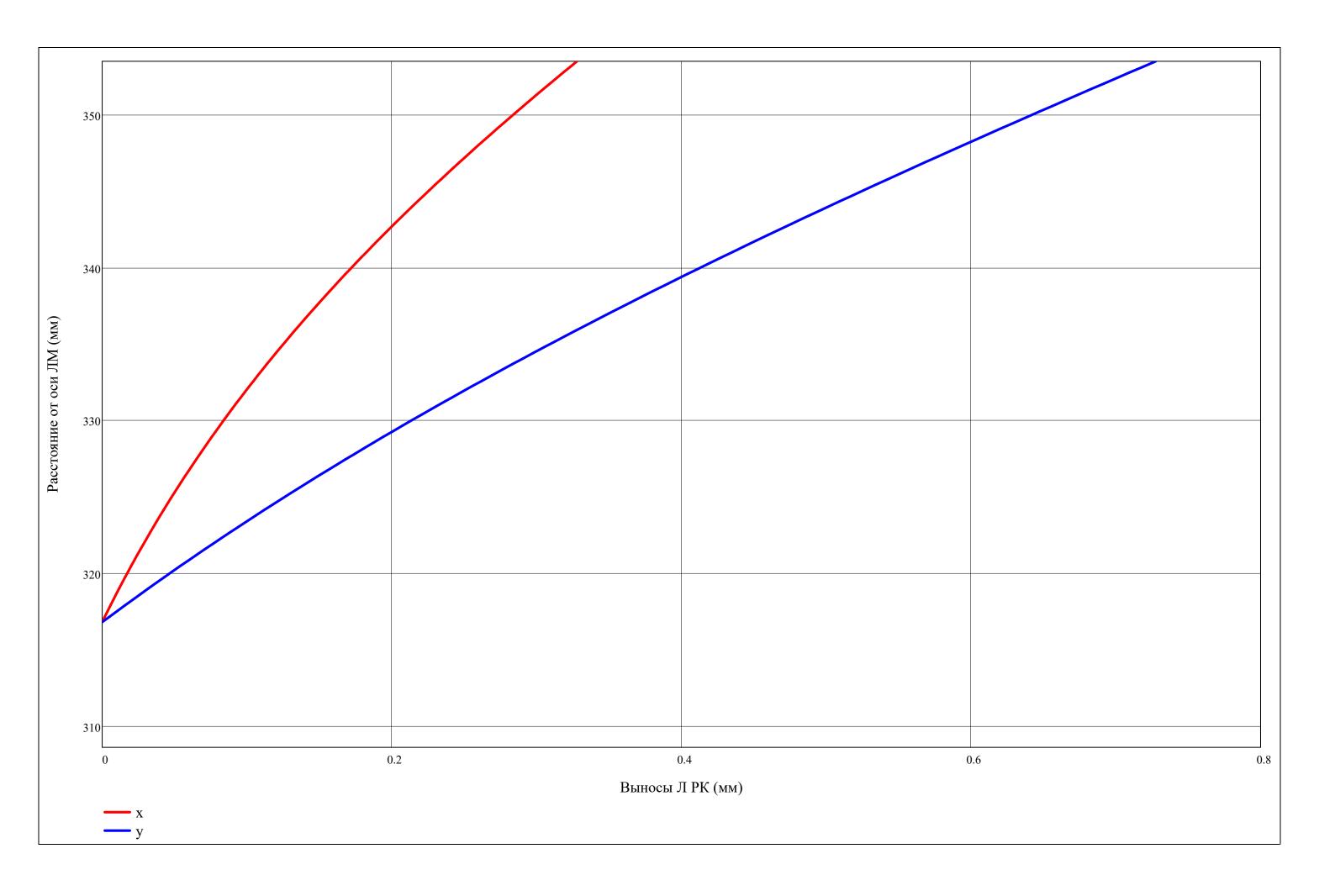


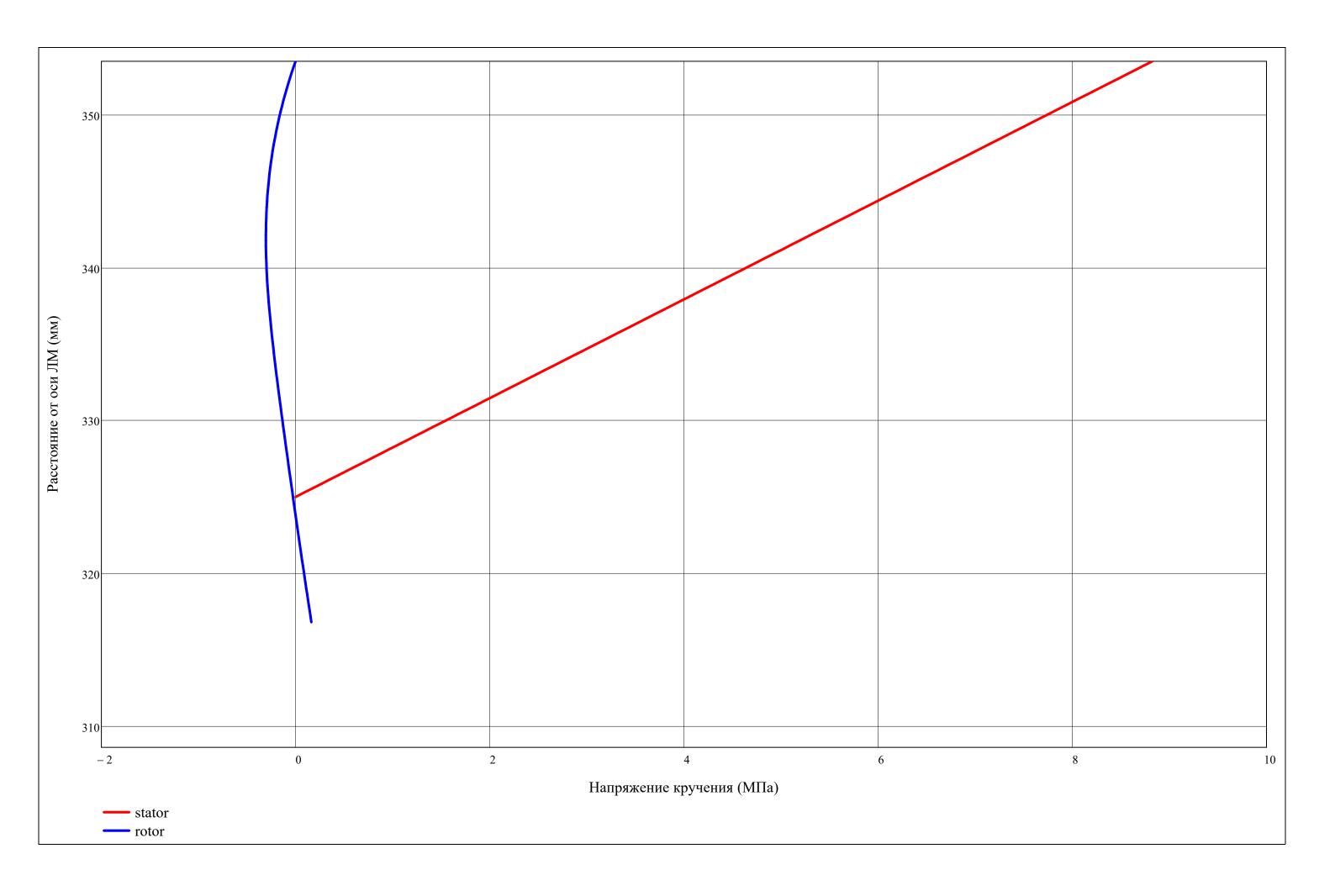


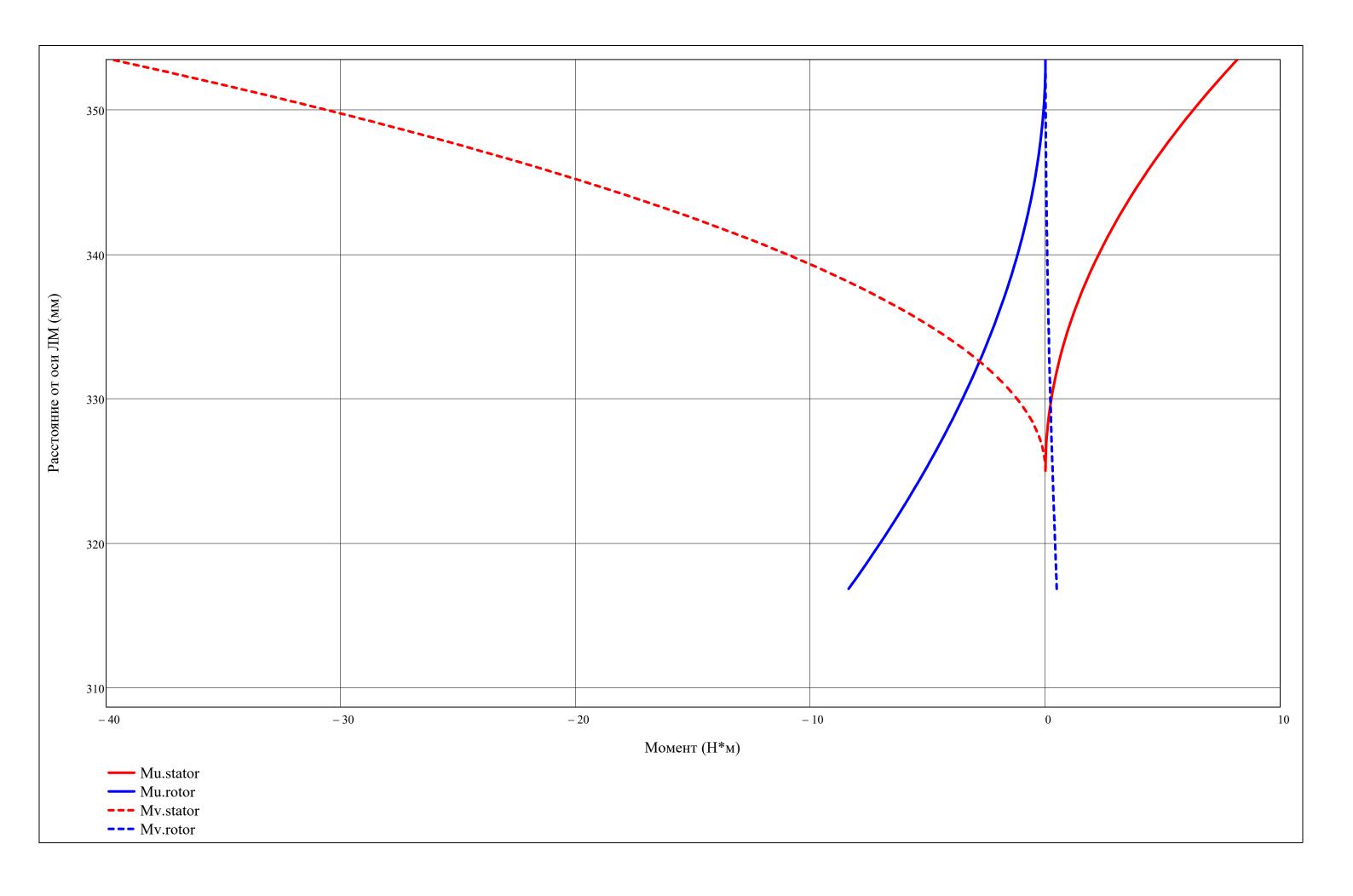


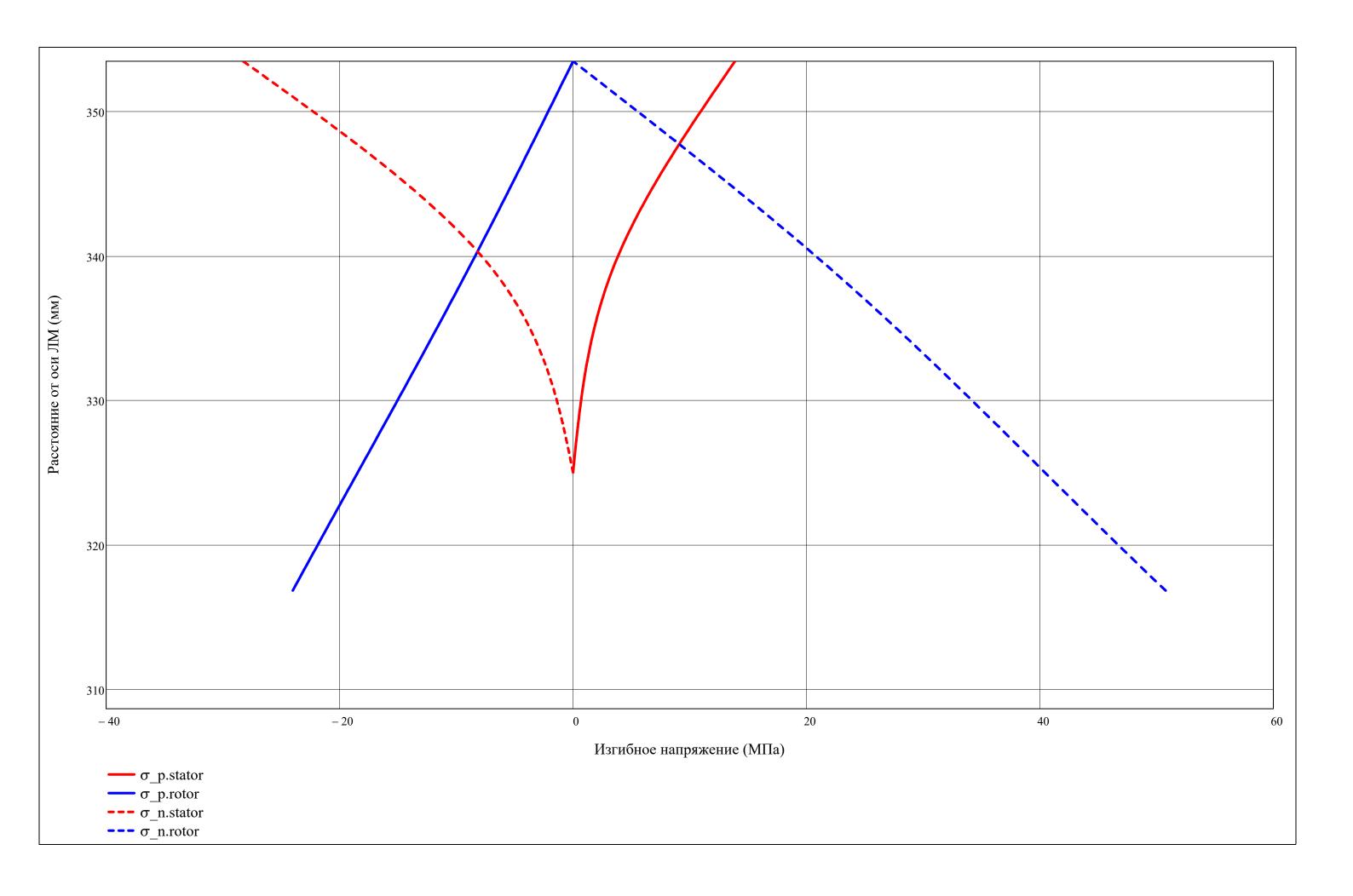


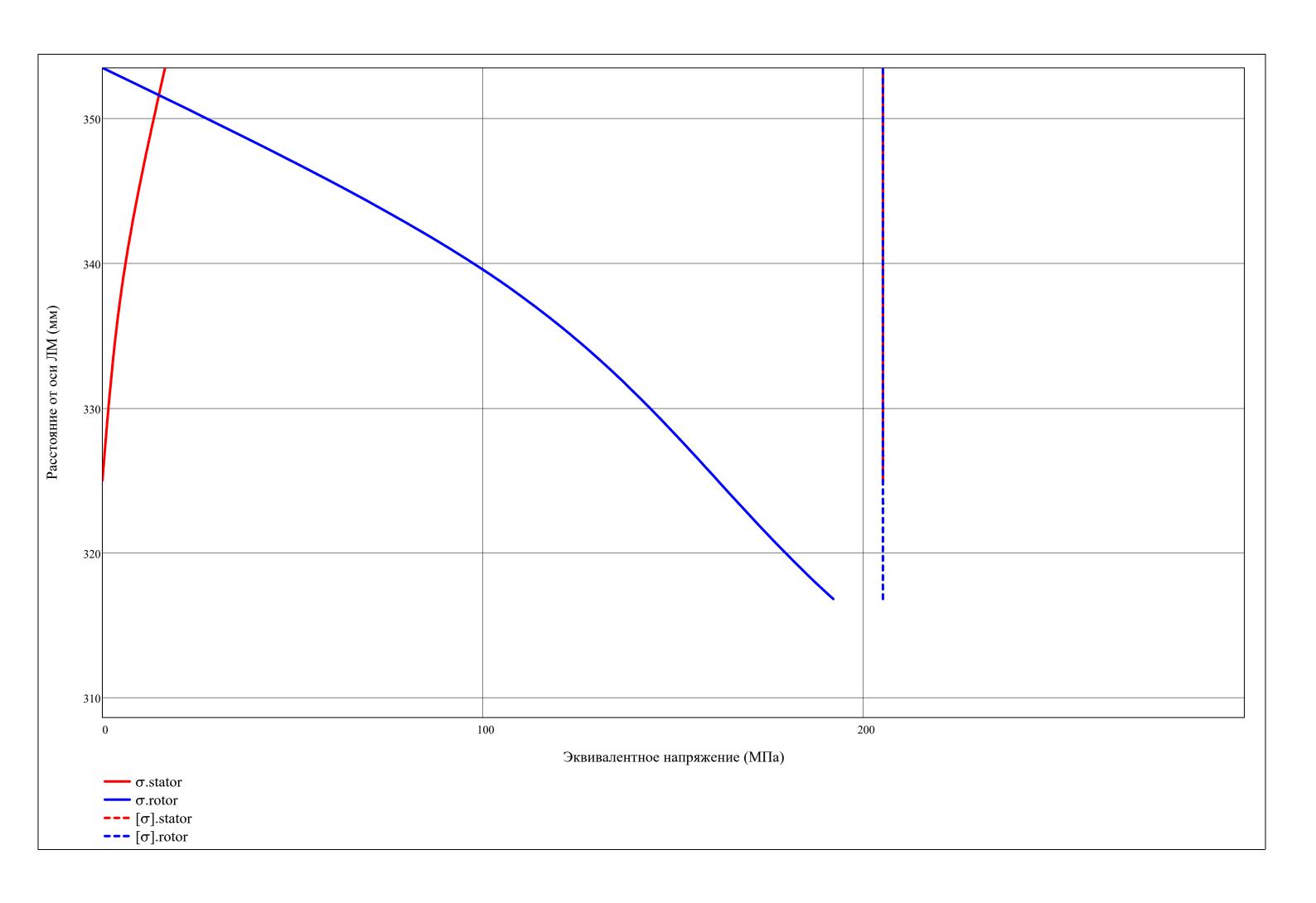












$$\begin{pmatrix} blade \\ r \end{pmatrix} = \begin{pmatrix} "stator" \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} u_{-}u_{rotor_{j},r} & v_{-}u_{rotor_{j},r} \\ u_{-}l_{rotor_{j},r} & v_{-}l_{rotor_{j},r} \\ u_{-}u_{stator_{j},r} & v_{-}u_{stator_{j},r} \\ u_{-}l_{stator_{j},r} & v_{-}l_{stator_{j},r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & 0.40 & 4.05 \\ 2 & 18.83 & -10.08 \\ 3 & 8.16 & 8.19 \\ 4 & -25.86 & -14.47 \end{pmatrix} \cdot 10^{-3}$$

Изгибные напряжения (Па):

$$\begin{pmatrix} \sigma_{-}p_{rotor_{j},r} & \sigma_{-}p_{stator_{j},r} \\ \sigma_{-}n_{rotor_{j},r} & \sigma_{-}n_{stator_{j},r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & -8.9 & 3.5 \\ 2 & 21.9 & -7.1 \end{pmatrix} \cdot 10^{6}$$

Эквивалентные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \cdot 10^{6}$$

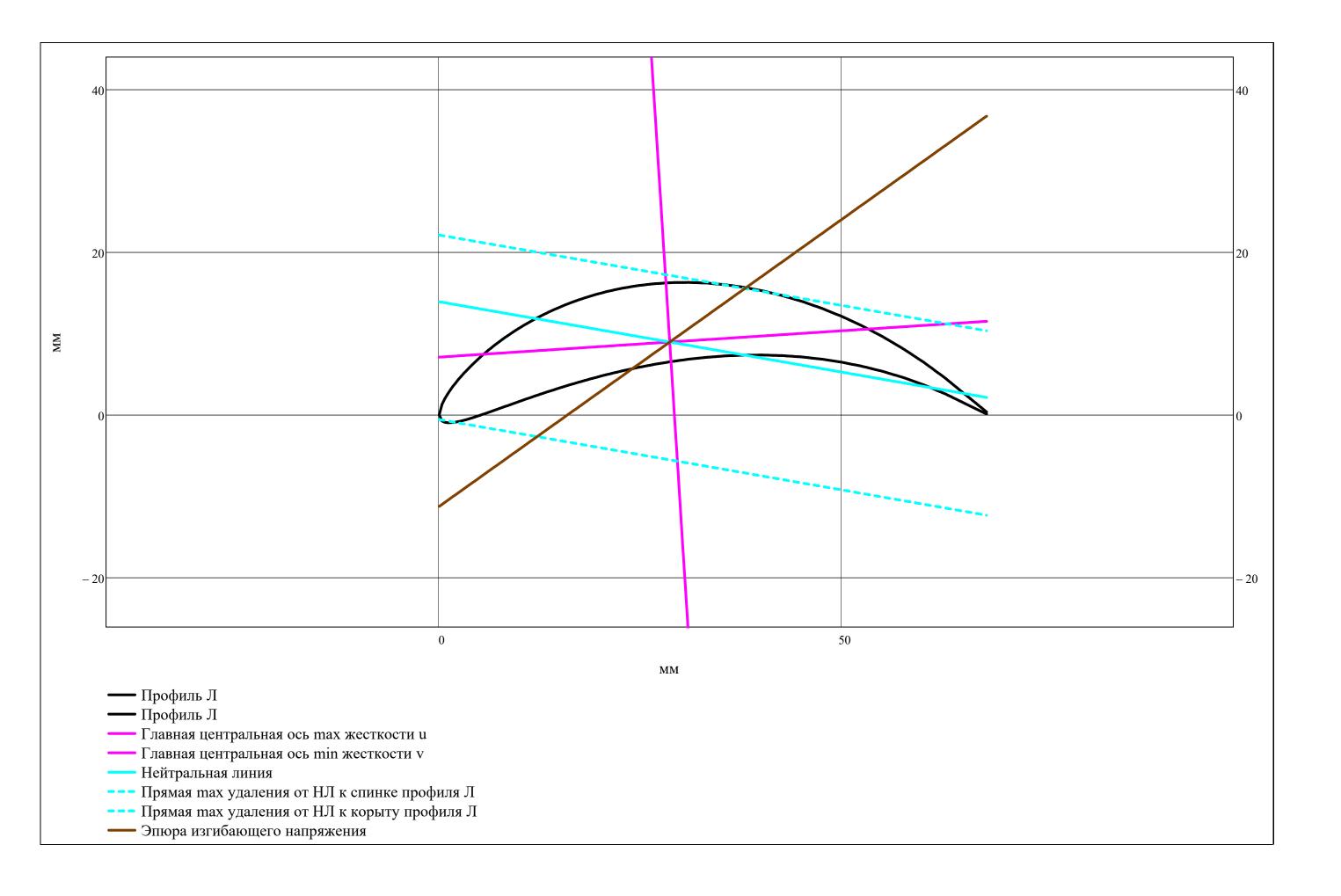
Коэф. запаса: 
$$\begin{pmatrix} safety_{stator_{j,r}} \\ safety_{rotor_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 36.526 \\ 2 \\ 2.015 \end{bmatrix}$$

$$\begin{pmatrix} v_{-}p \\ v_{-} \end{pmatrix} = \begin{pmatrix} v_{-}u_{rotor_{j},r} \\ v_{-}l_{rotor_{j},r} \end{pmatrix} \text{ if blade = "rotor"} = \begin{pmatrix} x_{0} \\ 1 & 8.190 \\ 2 & -14.465 \end{pmatrix} \cdot 10^{-3} \quad \begin{pmatrix} x_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \end{pmatrix} = \begin{pmatrix} x_{0} \\ y_{0} \\ y_{0} \end{pmatrix} \text{ if blade = "rotor"} = \begin{pmatrix} x_{0} \\ 1 & 28.623 \\ 2 & 8.931 \end{pmatrix} \cdot 10^{-3} \quad \text{chord} = \begin{pmatrix} \text{chord}_{rotor_{j},r} \\ \text{chord}_{stator_{j},r} \\ \text{chord}_{stator_{j},r} \end{pmatrix} \text{ otherwise}$$

$$\begin{pmatrix} v_{-}u_{stator_{j},r} \\ v_{-}l_{stator_{j},r} \end{pmatrix} \text{ otherwise}$$

$$\begin{pmatrix} x_{0} \\ y_{0} \\ \text{stator}_{j},r \end{pmatrix} \text{ otherwise}$$

$$\begin{pmatrix} x_{0} \\ y_{0} \\ \text{stator}_{j},r \end{pmatrix} \text{ otherwise}$$



$$\begin{pmatrix} \text{blade} \\ \text{stator} \end{pmatrix} = \begin{pmatrix} \text{"stator"} \\ 3 \end{pmatrix}$$

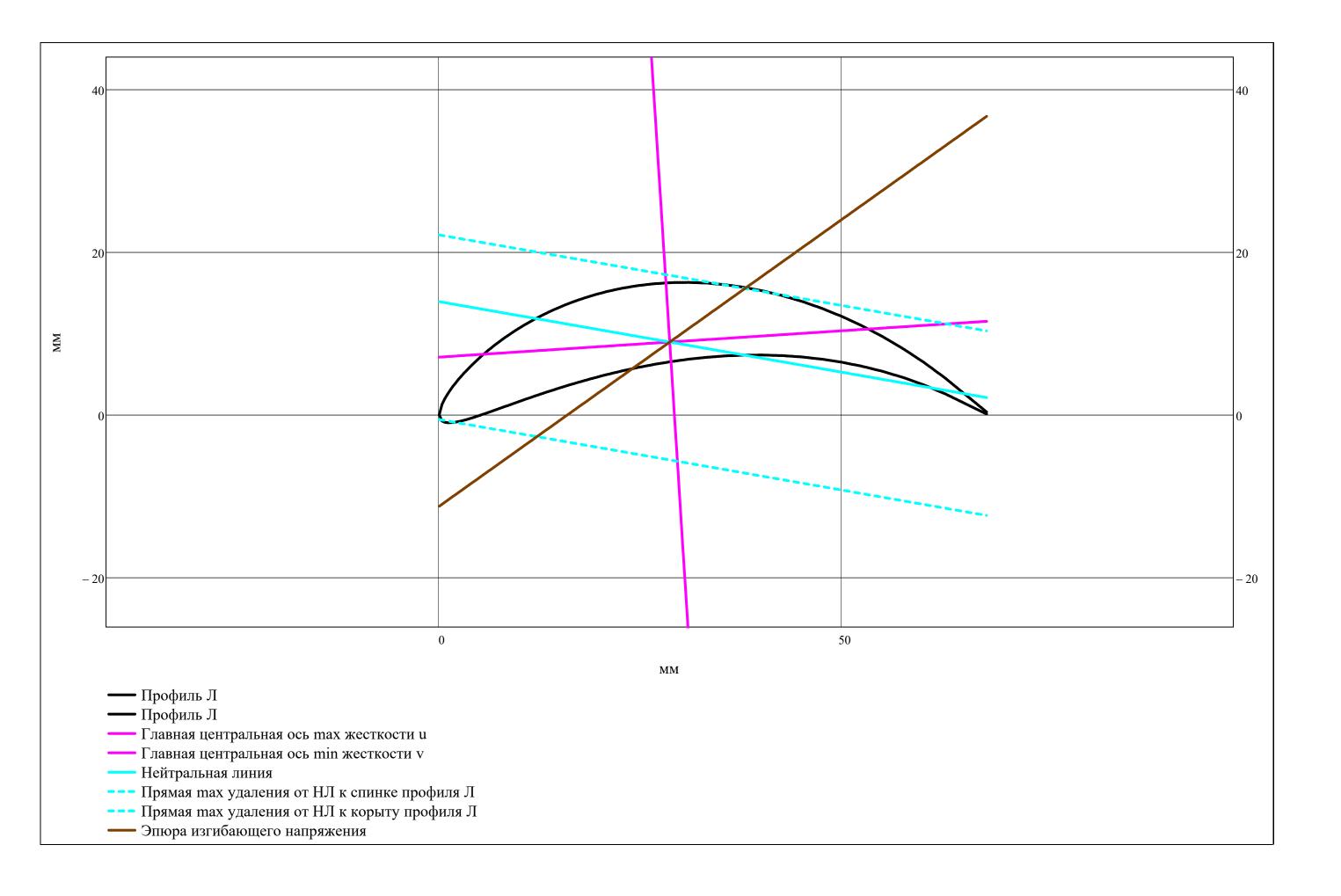
Эквивалентные напряжения (Па):

$$\begin{pmatrix} u_{-}u_{rotor_{j},r} & v_{-}u_{rotor_{j},r} \\ u_{-}l_{rotor_{j},r} & v_{-}l_{rotor_{j},r} \\ u_{-}u_{stator_{j},r} & v_{-}u_{stator_{j},r} \\ u_{-}l_{stator_{j},r} & v_{-}l_{stator_{j},r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & -5.99 & 13.96 \\ 2 & -8.99 & -17.32 \\ 3 & 8.16 & 8.19 \\ 4 & -25.85 & -14.48 \end{pmatrix} \cdot 10^{-1}$$

$$\begin{pmatrix} \sigma_{p_{rotor_{j},r}} & \sigma_{p_{stator_{j},r}} \\ \sigma_{n_{rotor_{j},r}} & \sigma_{n_{stator_{j},r}} \end{pmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 0.0 & 13.9 \\ 2 & 0.0 & -28.3 \end{bmatrix} \cdot 10^{6}$$

Изгибные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \cdot 10$$



$$\begin{pmatrix} \text{blade} \\ \text{min} \\ \text{r} \end{pmatrix} = \begin{pmatrix} \text{"rotor"} \\ 1 \end{pmatrix}$$

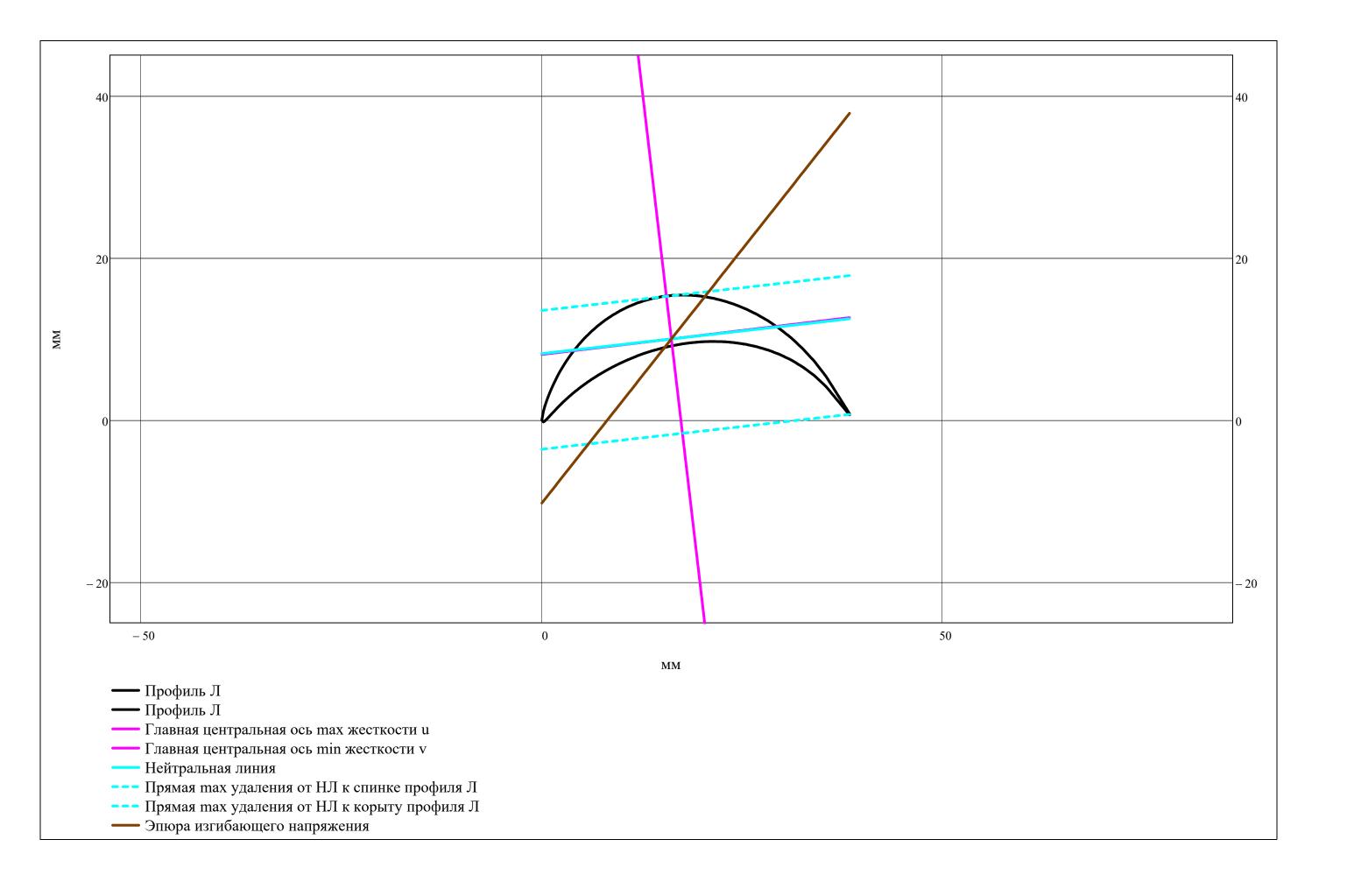
$$\begin{pmatrix} u_{-}u_{rotor_{j},r} & v_{-}u_{rotor_{j},r} \\ u_{-}l_{rotor_{j},r} & v_{-}l_{rotor_{j},r} \\ u_{-}u_{stator_{j},r} & v_{-}u_{stator_{j},r} \\ u_{-}l_{stator_{j},r} & v_{-}l_{stator_{j},r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & -0.22 & 5.32 \\ 2 & 21.03 & -11.79 \\ 3 & -7.06 & 29.14 \\ 4 & -11.36 & -38.70 \end{pmatrix} .$$

Изгибные напряжения (Па):

$$\begin{pmatrix} \sigma_{-}p_{rotor_{j}, r} & \sigma_{-}p_{stator_{j}, r} \\ \sigma_{-}n_{rotor_{j}, r} & \sigma_{-}n_{stator_{j}, r} \end{pmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & -18.4 & 0.0 \\ 2 & 40.4 & 0.0 \end{bmatrix} \cdot 10^{6}$$

Эквивалентные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0.0 \\ 2 \end{bmatrix} \cdot 10$$



$$\begin{pmatrix} \text{blade} \\ \text{max} \end{pmatrix} = \begin{pmatrix} \text{"rotor"} \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} u_{-}u_{rotor_{j},r} & v_{-}u_{rotor_{j},r} \\ u_{-}l_{rotor_{j},r} & v_{-}l_{rotor_{j},r} \\ u_{-}u_{stator_{j},r} & v_{-}u_{stator_{j},r} \\ u_{-}l_{stator_{j},r} & v_{-}l_{stator_{j},r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & 0.40 & 4.05 \\ 2 & 18.83 & -10.08 \\ 3 & 8.16 & 8.19 \\ 4 & -25.86 & -14.47 \end{pmatrix} \cdot 10^{-3}$$

Изгибные напряжения (Па):

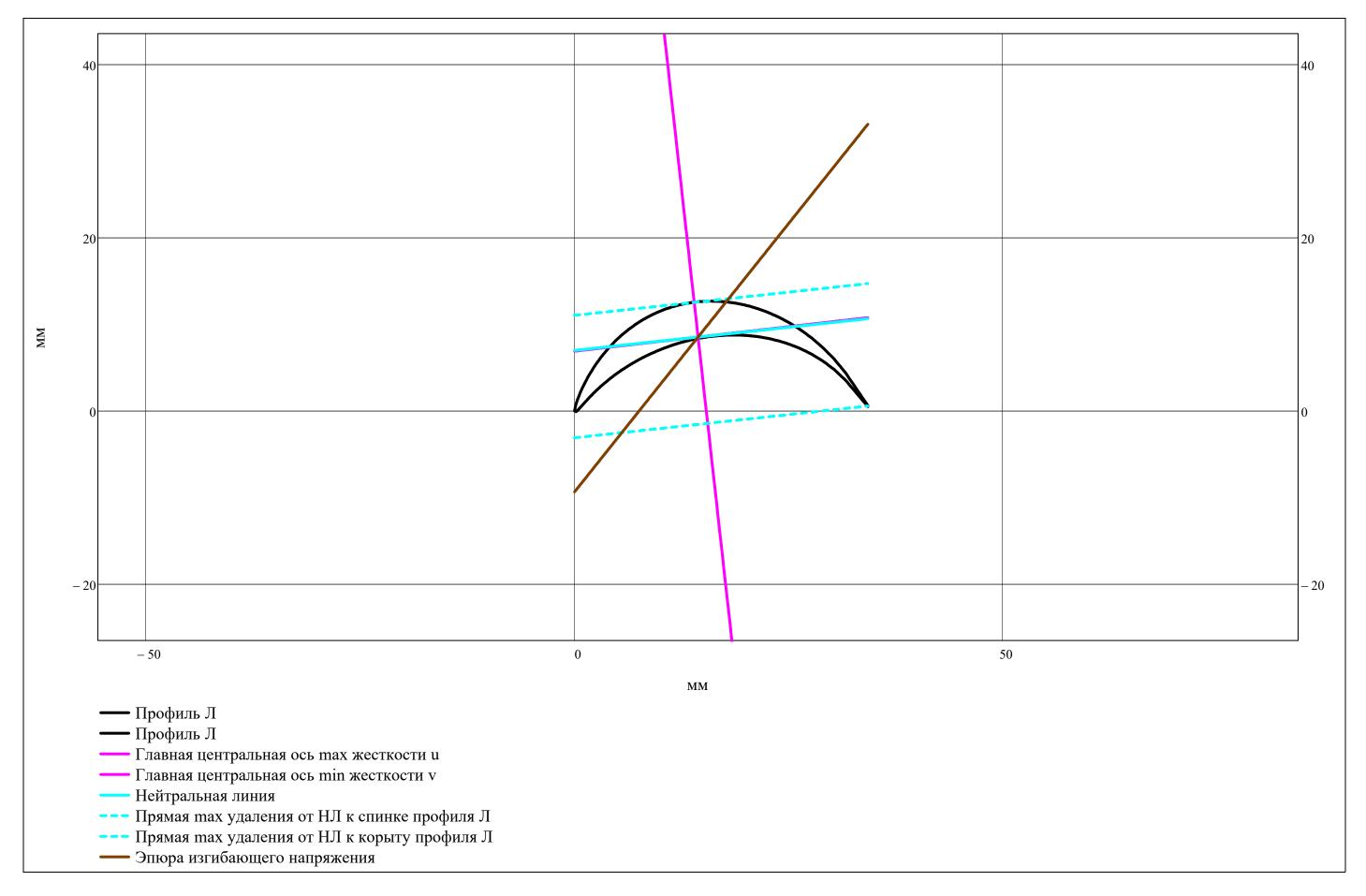
$$\begin{pmatrix} \sigma_{-}p_{rotor_{j}, r} & \sigma_{-}p_{stator_{j}, r} \\ \sigma_{-}n_{rotor_{j}, r} & \sigma_{-}n_{stator_{j}, r} \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & -8.9 & 3.5 \\ 2 & 21.9 & -7.1 \end{pmatrix} \cdot 10^{6}$$

Эквивалентные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 5.6 \\ 2 \end{bmatrix} \cdot 10^6$$

Коэф. запаса: 
$$\begin{pmatrix} safety_{stator_{j,r}} \\ safety_{rotor_{j,r}} \end{pmatrix} = \begin{bmatrix} 1 \\ 1 \\ 36.526 \\ 2 \\ 2.015 \end{bmatrix}$$

$$\begin{pmatrix} v_{u} \\ v_{r} \\ v$$



## ▼ Выбор материала Д

Запас по температуре (K):  $\Delta T_{\text{safety}} = 0$ 

Выбранный материал Д: material\_disk<sub>i</sub> = "ВЖ175" if turbine = "ТВД" "ЭП742" if turbine = "ТНД"

## Плотность материала Д (кг/м^3):

$$\rho\_disk_i = \begin{bmatrix} 8266 & if material\_disk_i = "BЖ175" \\ 8320 & if material\_disk_i = "ЭП742" \\ 8393 & if material\_disk_i = "ЖС-6К" \\ 7900 & if material\_disk_i = "BT41" \\ 4500 & if material\_disk_i = "BT25" \\ 4570 & if material\_disk_i = "BT23" \\ 4510 & if material\_disk_i = "BT9" \\ 4430 & if material\_disk_i = "BT6" \\ NaN & otherwise \\ \end{bmatrix}$$

$$\sigma\_disk\_long^T = \boxed{\begin{array}{c|c} 1 \\ \hline 1 \\ \hline \end{array}} \cdot 10^6$$

## Предел длительной прочности Д (Па):

$$\sigma_{disk\_long_i} = 10^6 \cdot \begin{vmatrix} 620 & \text{if material\_disk}_i = "BK175" \\ 680 & \text{if material\_disk}_i = "ЭП742" \\ 125 & \text{if material\_disk}_i = "KC-6K" \\ 123 & \text{if material\_disk}_i = "BT41" \\ 150 & \text{if material\_disk}_i = "BT25" \\ 230 & \text{if material\_disk}_i = "BT23" \\ 200 & \text{if material\_disk}_i = "BT9" \\ 210 & \text{if material\_disk}_i = "BT6" \\ NaN & \text{otherwise} \end{vmatrix}$$

Рассматриваемая ступень: 
$$j = Z$$
 =  $j = Z$  = "Такой ступени не существует!" if  $(j < 1) \lor (j > Z)$   $j$  otherwise

▼ Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{pmatrix} chord_{rotor_{i},ORIGIN} \cdot sin \Big(\upsilon_{rotor_{i},ORIGIN}\Big) \Big) \cdot e^{\frac{\rho_{-}disk_{i} \cdot \omega^{2}}{2} \cdot \frac{1}{\sigma_{-}z_{rotor}(i,R_{st(i,2),ORIGIN})} \cdot \Big[ \big(R_{st(i,2),ORIGIN}\big)^{2} - z^{2} \big]} \\ \text{if } z \leq R_{st(i,2),ORIGIN} \end{pmatrix}$$

$$NaN \quad otherwise$$

$$z = 0, \frac{R_{st(j,2),ORIGIN}}{N_{dis}} .. R_{st(j,2),ORIGIN}$$

