

Исходные данные

Коэф. запаса: safety = 1.3

Горючее: Fuel = "Керосин" turbine = "ТВД"

Высота движения (м): H_v = 0

Массовый расход перед Т (кг/с):
Массовый расход утечек Т (кг/с):
Массовый расход на охл Т (кг/с):

$$\begin{pmatrix} G_T \\ G_{\text{leak}} \\ G_{\text{cooling}} \end{pmatrix} = \begin{cases} \begin{pmatrix} 32.30 \\ 106.96 \cdot 10^{-3} \\ 3240.8 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 35.43 \\ 35.65 \cdot 10^{-3} \\ 810.2 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 32.30 \\ \hline 2 & 0.11 \\ \hline 3 & 3.24 \\ \hline \end{array}$$

Мощность Т (Вт):

$$N_T = 10^6 \cdot \begin{cases} 14.893 & \text{if turbine = "ТВД"} \\ 15.181 & \text{if turbine = "ТНД"} \end{cases} = 14.893 \cdot 10^6$$

Полное давление перед Т (Па):

$$P^*_T = 10^3 \cdot \begin{cases} 2731.8 & \text{if turbine = "ТВД"} \\ 927.5 & \text{if turbine = "ТНД"} \end{cases} = 2731.8 \cdot 10^3$$

Полная температура перед Т (К):

$$T^*_T = \begin{cases} 1773 & \text{if turbine = "ТВД"} \\ 1368.9 & \text{if turbine = "ТНД"} \end{cases} = 1773.0$$

Коэф. избытка воздуха в Т:

$$\alpha_{\text{ох}} = \begin{cases} 2.267 & \text{if turbine = "ТВД"} \\ 2.493 & \text{if turbine = "ТНД"} \end{cases} = 2.267$$

Полное давление отбора охлаждающего воздуха (К):

$$P^*_{\text{cooling}} = 10^3 \cdot \begin{cases} 2845.6 & \text{if turbine = "ТВД"} \\ 319.4 & \text{if turbine = "ТНД"} \end{cases} = 2845.6 \cdot 10^3$$

Полная температура отбора охлаждающего воздуха (К):

$$T^*_{\text{cooling}} = \begin{cases} 806.9 & \text{if turbine = "ТВД"} \\ 418.2 & \text{if turbine = "ТНД"} \end{cases} = 806.9$$

Коэф. сохранения полного давления охлаждения:

$$\sigma_{\text{cooling}} = 0.97$$

Подогрев охл. от КС [К]:

$$\Delta T_{\text{охл.подогрев}} = 40$$

Газовая постоянная (Дж/кг/К):

$$R_{\text{газ}}(\alpha_{\text{ох}}, \text{Fuel}) = 288.5$$

Допустимая температура Л (К):

$$T_{\text{Л,доп}} = 1373$$

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

[1, с.15]

$80 \leq c_T \leq 400 = 1$

Лопаточный КПД Т:

$\eta_{Л} = 88\%$

$88\% \leq \eta_{Л} \leq 95\% = 1$

Угол входа в Т:

$\alpha_T = 90.^{\circ}$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_T \\ c_T \end{pmatrix} = \begin{cases} \begin{pmatrix} 100 \\ 180 \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 180 \\ 260 \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 100.0 \\ \hline 2 & 180.0 \\ \hline \end{array}$$

$$u_T = \begin{cases} 520 & \text{if turbine = "ТВД"} \\ 260 & \text{if turbine = "ТНД"} \end{cases} = 520.0$$

$z = \text{ORIGIN}..N_T$

Полное давление отбора охлаждающего воздуха (K): $\overset{\text{cooling}}{P^*} = P^*_{\text{cooling}} \cdot \sigma_{\text{cooling}} = 2760.2 \cdot 10^3$

Полная температура отбора охлаждающего воздуха (K): $\overset{\text{cooling}}{T^*} = T^*_{\text{cooling}} + \Delta T_{\text{охл.подогрев}} = 846.9$

Массовый расход перед Т (кг/с): $\overset{\text{cooling}}{G_T} = G_T - G_{\text{leak}} = 32.2$

Массовый расход после Т (кг/с): $G_T = G_T + G_{\text{cooling}} = 35.4$

Удельная работа Т (Дж/кг): $L^*_T = \frac{N_T}{\text{mean}(G_T, G_T)} = 440.4 \cdot 10^3$

$L^*_T \leq 550 \cdot 10^3 = 1$

Располагаемый теплоперепад в Т (Дж/кг): $H_T = \frac{L^*_T + 0.5c_T^2}{\eta_{\text{л}}} = 518.9 \cdot 10^3$

iteration		
k _Г		
P _Г		
T _Г		
=	iteration = 0	=
	k _Г = k _{ад} (Cp _{газ} (P* _Г , T* _Г , α _{оx} , Fuel), R _{газ} (α _{оx} , Fuel))	
	while 1 > 0	
	iteration = iteration + 1	
	Cp _Г = $\frac{k_{Г}}{k_{Г} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$	
	T _Г = T* _Г - $\frac{c_{Г}^2}{2 \cdot Cp_{Г}}$	
	P _Г = P* _Г · $\left(\frac{T_{Г}}{T^{*}_{Г}}\right)^{\frac{k_{Г}}{k_{Г}-1}}$	
	k' _Г = k _{ад} (Cp _{газ} (P _Г , T _Г , α _{оx} , Fuel), R _{газ} (α _{оx} , Fuel))	
	if eps("rel", k _Г , k' _Г) ≤ epsilon	
	k _Г = k' _Г	
	break	
	k _Г = k' _Г	
	(iteration k _Г P _Г T _Г) ^T	

	1
1	1.0
2	1.3
3	2705198.4
4	1769.2

Количество итераций: iteration = 1

Показатель адиабаты перед Т: k_Г = 1.283

Статическое давление перед Т (Па): P_Г = 2705.2 · 10³

Статическая температура перед Т (К): T_Г = 1769.2

Теплоемкость перед Т (Дж/кг/К): Cp_Г = Cp_{газ}(P_Г, T_Г, α_{оx}, Fuel) = 1309

<u>iteration</u>		
k _T	=	iteration = 0
P _T		k _T = k _T
T _T		while 1 > 0
		iteration = iteration + 1
		k _{cp} = mean(k _T , k _T)
		Cp = $\frac{k_{cp}}{k_{cp} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$
		$P_T = P^*_{T} \cdot \left(1 - \frac{H_T}{Cp \cdot T^*_{T}}\right)^{\frac{k_{cp}}{k_{cp} - 1}}$
		$T_T = T^*_{T} - \frac{H_T \cdot \eta_{л}}{Cp}$
		k' _T = k _{ад} (Cp _{газ} (P _T , T _T , α _{ox} , Fuel), R _{газ} (α _{ox} , Fuel))
		if eps("rel", k _T , k' _T) ≤ epsilon
		k _T = k' _T
		break
		k _T = k' _T
		(iteration k _T P _T T _T) ^T

	1
1	1
2	1.293
3	866477.23
4	1424.088

Количество итераций: iteration = 1

Показатель адиабаты после T: k_T = 1.293

Статическое давление после T (Па): P_T = 866.5·10³ P_T ≥ P_{атм}(H_υ) = 1

Статическая температура после T (K): T_T = 1424.1

Теплоемкость после T (Дж/кг/К): Cp_T = Cp_{газ}(P_T, T_T, α_{ox}, Fuel) = 1271.6

Ср. показатель адиабаты T: $k = \text{mean}(k_{\Gamma}, k_T) = 1.288$

Ср. теплоемкость T (Дж/кг/К): $C_p = \frac{k}{k - 1} \cdot R_{\text{газ}}(\alpha_{\text{ox}}, \text{Fuel}) = 1289.8$

Степень понижения давления: $\pi_T = \frac{P_{\Gamma}^*}{P_T} = 3.15$

Удельный объём перед T (м³/кг): $\left(\begin{matrix} v_{\Gamma} \\ v_T \end{matrix} \right) = R_{\text{газ}}(\alpha_{\text{ox}}, \text{Fuel}) \cdot \left(\begin{matrix} \frac{T_{\Gamma}}{P_{\Gamma}} \\ \frac{T_T}{P_T} \end{matrix} \right) = \begin{matrix} & & 1 \\ \hline 1 & 0.189 \\ 2 & 0.474 \end{matrix}$

Площадь кольцевого сечения перед T (м²): $\left(\begin{matrix} F_{\Gamma} \\ F_T \end{matrix} \right) = \left(\begin{matrix} \frac{G_{\Gamma} \cdot v_{\Gamma}}{c_{\Gamma}} \\ \frac{G_T \cdot v_T}{c_T} \end{matrix} \right) = \begin{matrix} & & 1 \\ \hline 1 & 60741 \\ 2 & 93341 \end{matrix} \cdot 10^{-6}$

Площадь кольцевого сечения после T (м²):

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

$$0.7 \leq \mu_c \leq 1 = 1$$

▼ Определение количества ступеней T

$$\begin{pmatrix} Z_{\text{recomend}} \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} =$$

$$c_{cp} = \text{mean}(c_T, c_T)$$

$$\alpha_{\text{ВОЗВ}} = 0.025$$
while 1 > 0

$$Z = \text{round} \left[\frac{2 \cdot H_T \cdot \frac{(1 + \alpha_{\text{ВОЗВ}})}{(\mu_c \cdot c_{cp})^2} - 1}{\frac{u_T^2}{(\mu_c \cdot c_{cp})^2 \cdot y_0^2} - 1} \right]$$

break if $\left| \text{eps} \left[\text{"rel"}, \alpha_{\text{ВОЗВ}}, \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}}) \right] \right| < \text{epsilon}$

$$\alpha_{\text{ВОЗВ}} = \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}})$$

if $\alpha_{\text{ВОЗВ}} = 0$

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

break

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix}$$

1

1

1.000

2

0.000

Рекомендуемое количество ступеней: $Z_{\text{recomend}} = 1$

Количество ступеней: $Z = \begin{cases} 1 & \text{if turbine = "ТВД"} \\ 4 & \text{if turbine = "ТНД"} \end{cases} = 1$

Дискретизация ступеней: $i = 1 \dots Z$

Дискретизация сечений: $ii = 1 \dots 2 \cdot Z + 1$

▲ Определение количества ступеней T

Выбранный материал Л:

$\text{material_blade}_i = \begin{cases} \text{"ВКНА-1В"} & \text{if } 1523 \leq T^*_{\Gamma} \\ \text{"ВЖМ7"} & \text{if } 1323 \leq T^*_{\Gamma} < 1523 \\ \text{"ЖС-36"} & \text{if } 1123 \leq T^*_{\Gamma} < 1323 \end{cases}$

Плотность материала Л (кг/м^3):

$\rho_{\text{blade}_i} = \begin{cases} 7938 & \text{if material_blade}_i = \text{"ВКНА-1В"} \\ 8390 & \text{if material_blade}_i = \text{"ВЖМ7"} \\ 8760 & \text{if material_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$

Предел длительной прочности Л РК (Па):

$\sigma_{\text{blade_long}_i} = 10^6 \cdot \begin{cases} 205 & \text{if material_blade}_i = \text{"ВКНА-1В"} \\ 120 & \text{if material_blade}_i = \text{"ВЖМ7"} \\ 120 & \text{if material_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$

$\text{material_blade}^T = \begin{bmatrix} & 1 \\ 1 & \text{"ВКНА-1В"} \end{bmatrix}$

$\rho_{\text{blade}}^T = \begin{bmatrix} & 1 \\ 1 & 7938 \end{bmatrix}$

$\sigma_{\text{blade_long}}^T = \begin{bmatrix} & 1 \\ 1 & 205 \end{bmatrix} \cdot 10^6$

Коэф. формы: $k_n = 6.8$

Модуль Юнга I рода материала Л (Па): $E_{\text{blade}} = 210 \cdot 10^9$

Коэф. Пуассона материала Л(): $\mu_{\text{steel}} = 0.3$

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_blade_long}{safety \cdot k_n \cdot F_\Gamma}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 19539 \\ \hline \end{array}$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{max} = \sqrt{\frac{\sigma_blade_long}{safety \cdot k_n \cdot F_T}} = (15762)$$

Рекомендуюмая ном. частота вращения (об/мин):

$$n = n_{max} \cdot 0.95 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14974 \\ \hline \end{array}$$

$$n = \begin{cases} 15000 & \text{if turbine = "ТВД"} \\ 5300 & \text{if turbine = "ТНД"} \end{cases} = 15000$$

Ном. частота вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 1570.8$$

Ср. диаметр перед Т (м):

$$\begin{pmatrix} D_{\Gamma.cp} \\ D_{T.cp} \end{pmatrix} = \frac{2}{\omega} \cdot \begin{pmatrix} u_T \\ u_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 662.1 \\ \hline 2 & 662.1 \\ \hline \end{array} \cdot 10^{-3}$$

Ср. диаметр после Т (м):

Длина Л первой ступени Т (м):

$$\begin{pmatrix} l_\Gamma \\ l_T \end{pmatrix} = \frac{1}{\pi} \cdot \begin{pmatrix} \frac{F_\Gamma}{D_{\Gamma.cp}} \\ \frac{F_T}{D_{T.cp}} \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29.20 \\ \hline 2 & 44.88 \\ \hline \end{array} \cdot 10^{-3}$$

Длина Л последней ступени Т (м):

$$\frac{l_\Gamma}{D_{\Gamma.cp}} = \frac{1}{22}$$
$$\frac{l_T}{D_{T.cp}} = \frac{1}{14}$$

Диаметр периферии после Т (м):

$$\begin{pmatrix} D_{T.пер} \\ D_{T.кор} \end{pmatrix} = \begin{pmatrix} D_{T.cp} + l_T \\ D_{T.cp} - l_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 707.0 \\ \hline 2 & 617.2 \\ \hline \end{array} \cdot 10^{-3}$$

Диаметр корня после Т (м):

Равномерное распределение мощности Т по ступеням (Вт): $N_{\text{ст}_i} = \frac{N_T}{Z}$

$N_{\text{ст}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14.89 \\ \hline \end{array} \cdot 10^6$

Вид проточной части:
("const", "кор", "сп", "пер", "доля от предыдущего диаметра периферии")

$$\text{ЗППЧ} = \begin{pmatrix} \begin{array}{l} \text{"const" if } Z = 1 \\ \text{"кор" otherwise} \end{array} & \text{"1.07"} & \text{"1.065"} & \text{"1.03"} & \text{"пер"} & \text{"пер"} \end{pmatrix}^T$$

$$\begin{pmatrix} \text{"пер" if } Z = 1 \\ \text{"1.055" otherwise} \end{pmatrix} & \text{"1.07"} & \text{"1.05"} & \text{"кор"} & \text{"пер"} & \text{"пер"} \end{pmatrix}^T$$

▼ Определение проточной части ОТ

Линейное распределение кольцевых площадей по сечениям:

$$F_{\text{ww}} = \begin{array}{l} \text{for } i \in 1..2Z + 1 \\ F_i = \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \cdot i + \left(F_\Gamma - \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \right) \\ \text{for } i \in 1..Z \\ \text{for } a \in 2..3 \\ F_{\text{st}(i, a)} = F_{\text{st}(i, a-1)} \text{ if } \text{ЗППЧ}_{i, a-1} = \text{"const"} \end{array}$$

F

$F^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 60741 & 60741 & 93341 & & & & & & \\ \hline \end{array} \cdot 10^{-6}$

D =

for i ∈ 2Z + 1

for r ∈ 1..N_r

D_{i,r} =

D_{T.kop} if r = 1

D_{T.cp} if r = av(N_r)

D_{T.nep} if r = N_r

for i ∈ Z..1

for a ∈ 2..1

for r ∈ 1..N_r

D_{st(i,a),r} =

if 3ΠΠΠΨ_{i,a} = "const"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "kop"

D_{st(i,a+1),1} if r = 1

$\frac{1}{2} \cdot \left[D_{st(i,a+1),1} + \sqrt{(D_{st(i,a+1),1})^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} \right]$ if r = av(N_r)

$\sqrt{(D_{st(i,a+1),1})^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "cp"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "nep"

$\sqrt{(D_{st(i,a+1),N_r})^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = 1

$\frac{1}{2} \cdot \left[\sqrt{(D_{st(i,a+1),N_r})^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + D_{st(i,a+1),N_r} \right]$ if r = av(N_r)

D_{st(i,a+1),N_r} if r = N_r

D^T =

	1	2	3	4	5	6	7	8	9
1	650.0	650.0	617.2						
2	678.5	678.5	662.1						
3	707.0	707.0	707.0						

·10^{−3}

R_{av}

=

D

2

R^T =

	1	2	3	4	5	6	7	8	9
1	325.0	325.0	308.6						
2	339.2	339.2	331.0						
3	353.5	353.5	353.5						

·10^{−3}

d̄ =

for i ∈ 1..Z

for a ∈ 1..3

d̄_{st(i,a)} = $\frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$

d̄

d̄^T =

	1	2	3	4	5	6	7	8	9
1	0.9194	0.9194	0.8730						

d̄^T ≤ 0.9 =

	1	2	3
1	0	0	1

h =

for i ∈ 1..2Z + 1

h_i = $\frac{F_i}{\pi \cdot D_{i,av(N_r)}}$

h

h^T =

	1	2	3
1	28.50	28.50	44.88

·10^{−3}

$$D_{st(i,a+1),N_r}^{u_i - v_r}$$
if $\left(3\Pi\Pi\Pi_{i,a} \neq \text{"const"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"kop"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"cp"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"nep"}\right)$

$$\sqrt{\left(\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$$
if $r = 1$

$$\frac{1}{2} \cdot \left[\sqrt{\left(\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + \frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right]$$
if $r = \text{av}\left(N_r\right)$

$$\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}$$
if $r = N_r$
NaN otherwise

D

$$u =$$
for $i \in 1..2 \cdot Z + 1$
for $r \in 1..N_r$

$$u_{i,r} = \frac{\pi \cdot D_{i,r} \cdot n}{60}$$

u

$$u^T =$$

	1	2	3	4	5	6	7	8	9
1	510.5	510.5	484.8						
2	532.9	532.9	520.0						
3	555.2	555.2	555.2						

$F^T =$

	1	2	3	4	5	6	7	8	9
1	60741	60741	93341						

 $\cdot 10^{-6}$

$\overline{d}_1 = 0.9194$

$\overline{d}_1 \leq 0.9 = 0$

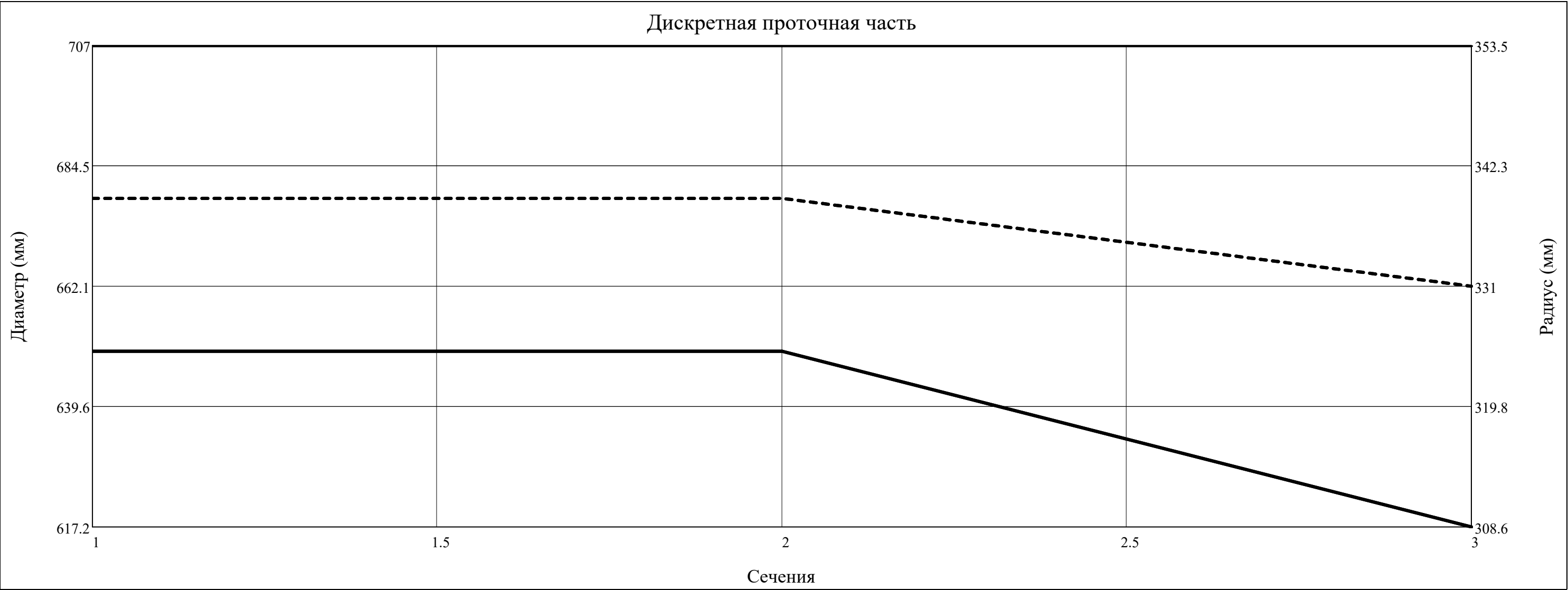
$\overline{d}^T =$

	1	2	3	4	5	6	7	8	9
1	0.9194	0.9194	0.8730						

$D^T =$

	1	2	3
1	650.0	650.0	617.2
2	678.5	678.5	662.1
3	707.0	707.0	707.0

 $\cdot 10^{-3}$



$h^T =$

	1	2	3
1	28.50	28.50	44.88

 $\cdot 10^{-3}$

$$\begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in N_r \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \\ \gamma_{\text{ПЧпер}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \end{array} \right. \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),N_r} - D_{\text{st}(i,1),N_r} \\ D_{\text{st}(i,2),1} - D_{\text{st}(i,1),1} \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),N_r} - D_{\text{st}(i,2),N_r} \\ D_{\text{st}(i,3),1} - D_{\text{st}(i,2),1} \end{pmatrix} \text{ if } a = 2 \\ \gamma_{\text{ПЧ}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \end{array} \right. \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in 1 \\ \quad \quad \left| \begin{array}{l} \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \\ \gamma_{\text{ПЧкор}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \end{array} \right. \\ \begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} \end{array}$$

$$\text{stack}\left(\gamma_{\text{ПЧкор}}^T, \gamma_{\text{ПЧ}}^T, \gamma_{\text{ПЧпер}}^T\right) = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 0.00 & -28.56 \\ \hline 2 & -0.00 & 28.56 \\ \hline 3 & 0.00 & 0.00 \\ \hline \end{array} .^\circ$$

$$\gamma_{\text{ПЧ}}^T \leq 20.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧ}}^T \leq 25.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -12.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -15.^\circ = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & 1 & 0 \\ \hline \end{array}$$

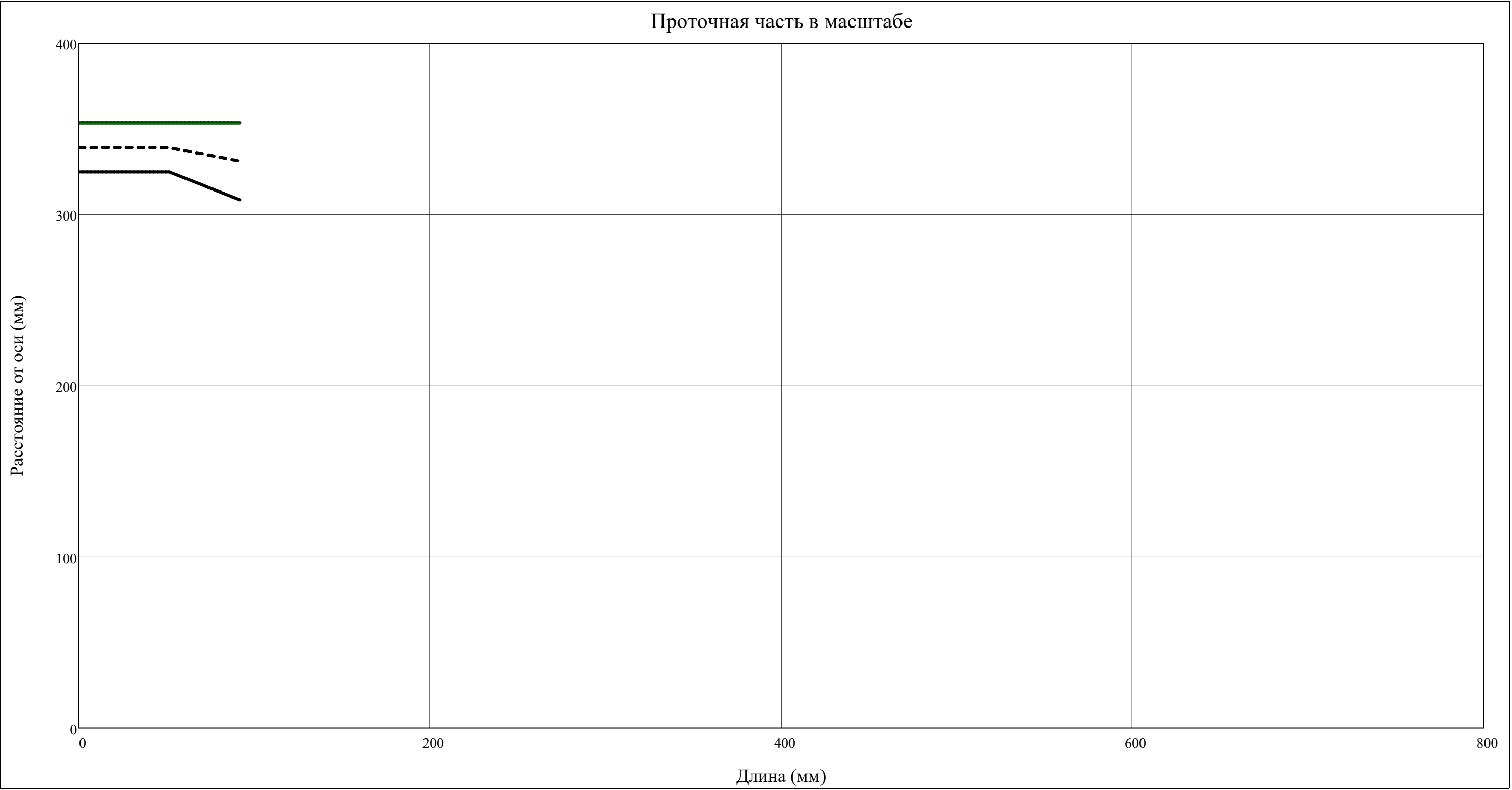
$$\begin{pmatrix} x_{\Pi\Upsilon} \\ y_{\Pi\Upsilon\text{пер}} \\ y_{\Pi\Upsilon\text{ср}} \\ y_{\Pi\Upsilon\text{кор}} \\ y_{\text{Лпер}} \end{pmatrix} = \begin{cases} c = 1 \\ x_{\Pi\Upsilon_c} = 0 \\ y_{\Pi\Upsilon\text{пер}_c} = D_{\text{st}(c, 1), N_r} \\ y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_c} \\ y_{\Pi\Upsilon\text{ср}_c} = D_{\text{st}(c, 1), \text{av}(N_r)} \\ y_{\Pi\Upsilon\text{кор}_c} = D_{\text{st}(c, 1), 1} \\ \text{for } i \in 1..Z \\ \quad c = c + 1 \\ \quad x_{\Pi\Upsilon_c} = x_{\Pi\Upsilon_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{CA_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \begin{pmatrix} y_{\Pi\Upsilon\text{пер}_c} \\ y_{\Pi\Upsilon\text{ср}_c} \\ y_{\Pi\Upsilon\text{кор}_c} \end{pmatrix} = \begin{pmatrix} D_{\text{st}(i, 2), N_r} \\ D_{\text{st}(i, 2), \text{av}(N_r)} \\ D_{\text{st}(i, 2), 1} \end{pmatrix} \\ \quad y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_i} \\ \quad c = c + 1 \\ \quad x_{\Pi\Upsilon_c} = x_{\Pi\Upsilon_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{PK_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \begin{pmatrix} y_{\Pi\Upsilon\text{пер}_c} \\ y_{\Pi\Upsilon\text{ср}_c} \\ y_{\Pi\Upsilon\text{кор}_c} \end{pmatrix} = \begin{pmatrix} D_{\text{st}(i+1, 1), N_r} \\ D_{\text{st}(i+1, 1), \text{av}(N_r)} \\ D_{\text{st}(i+1, 1), 1} \end{pmatrix} \\ \quad y_{\text{Лпер}_c} = y_{\Pi\Upsilon\text{пер}_c} - \Delta_{r_i} \\ \begin{pmatrix} x_{\Pi\Upsilon} \\ y_{\Pi\Upsilon\text{пер}} \\ y_{\Pi\Upsilon\text{ср}} \\ y_{\Pi\Upsilon\text{кор}} \\ y_{\text{Лпер}} \end{pmatrix} \end{cases}$$

$$\text{Length} = \sum_{i=1}^Z B_{CA_i} + \sum_{i=1}^Z \Delta_{a_i} + \sum_{i=1}^Z B_{PK_i} = 81.3 \cdot 10^{-3}$$

$$x = \min(x_{\Pi\Upsilon}), \min(x_{\Pi\Upsilon}) + \frac{\max(x_{\Pi\Upsilon}) - \min(x_{\Pi\Upsilon})}{N_{\text{dis}}} .. \max(x_{\Pi\Upsilon})$$

$y_{ПЧпер}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧпер}, l) \quad y_{ПЧср}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧср}, l) \quad y_{ПЧкор}(l) = \text{interp}(x_{ПЧ}, 0.5 \cdot y_{ПЧкор}, l)$

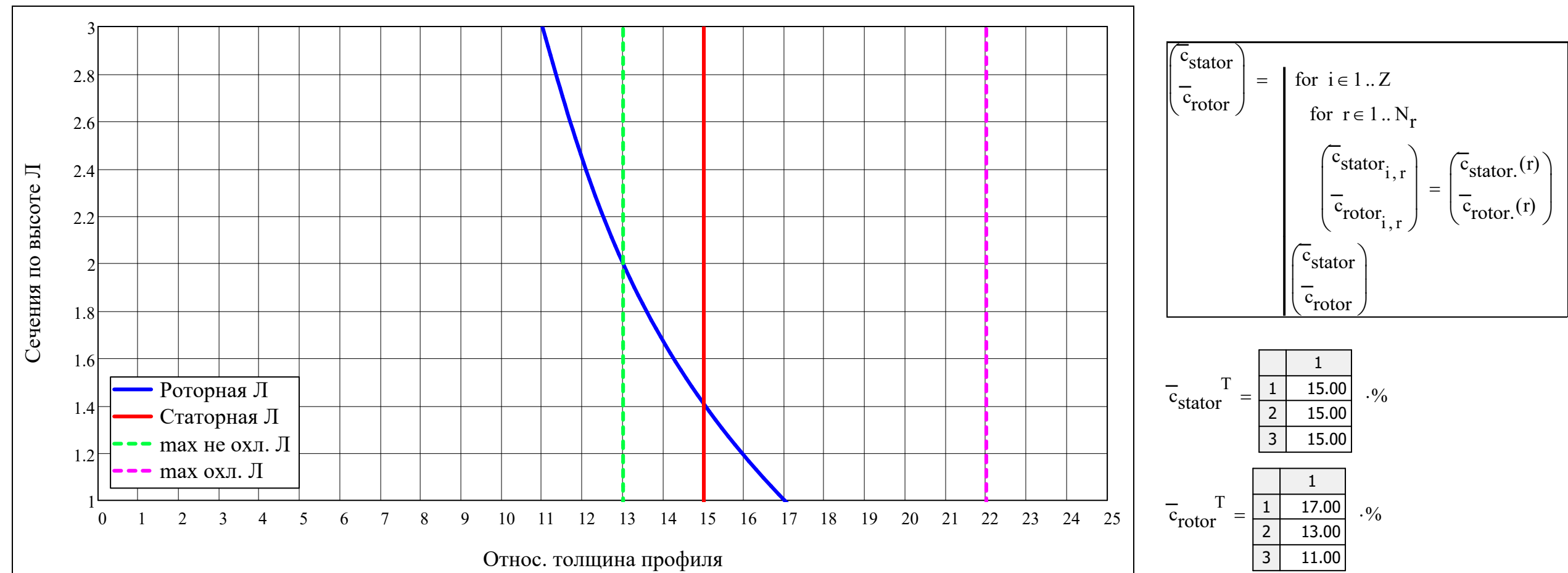
$y_{Лпер}(l) = \text{interp}(\text{cspline}(x_{ПЧ}, 0.5 \cdot y_{Лпер}), x_{ПЧ}, 0.5 \cdot y_{Лпер}, l)$



Относ. толщины ЛРК и СА:

$$\overline{c}_{\text{stator.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{Г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 8 \\ 10 \\ 12 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 8 \\ 10 \\ 12 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$

$$\overline{c}_{\text{rotor.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 13 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 13 \\ 11 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{Г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 14 \\ 9 \\ 7 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 14 \\ 9 \\ 7 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$



$$\begin{pmatrix} \overline{r}_{inlet_{rotor}} & \overline{r}_{inlet_{stator}} \\ \overline{r}_{outlet_{rotor}} & \overline{r}_{outlet_{stator}} \end{pmatrix} =$$

for i ∈ 1..Z

for r ∈ 1..N_r

$$\begin{pmatrix} \overline{r}_{inlet_{stator}_{i,r}} \\ \overline{r}_{outlet_{stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} 0.4 \\ 0.2 \end{pmatrix} \cdot \overline{c}_{stator.}(r)$$

$$\begin{pmatrix} \overline{r}_{inlet_{rotor}_{i,r}} \\ \overline{r}_{outlet_{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} 0.3 \\ 0.1 \end{pmatrix} \cdot \overline{c}_{rotor.}(r)$$

$$\begin{pmatrix} \overline{r}_{inlet_{rotor}} & \overline{r}_{inlet_{stator}} \\ \overline{r}_{outlet_{rotor}} & \overline{r}_{outlet_{stator}} \end{pmatrix}$$

$\overline{r}_{inlet_{stator}}^T =$

	1
1	6.000
2	6.000
3	6.000

.%

$\overline{r}_{outlet_{stator}}^T =$

	1
1	3.000
2	3.000
3	3.000

.%

$\overline{r}_{inlet_{rotor}}^T =$

	1
1	5.100
2	3.900
3	3.300

.%

$\overline{r}_{outlet_{rotor}}^T =$

	1
1	1.700
2	1.300
3	1.100

.%

▶ Вывод результатов поступенчатого расчета продольной геометрии ОТ в EXCEL:

$$R_{L.cp} = \left(\begin{array}{l} 0.16 \text{ if turbine} = \text{"ТВД"} \quad 0.15 \quad 0.18 \quad 0.185 \quad 0.5 \quad 0.5 \\ 0.13 \text{ otherwise} \end{array} \right)^T$$

▼ Поступенчатый расчет ОТ

iteration _{CA}	iteration _{PK}	
\underline{k}	R_L	
$H^*_{ст}$	$H_{ст}$	
H_{stator}	H_{rotor}	
$c_{ад}$	$w_{ад}$	
P^*	P	
T^*	\underline{T}	
\underline{G}	v	
ρ^*	ρ	
$\underline{\alpha_{ox}}$	α_{ox}	
α	β	
ε_{stator}	ε_{rotor}	
θ_{CA}	θ_{PK}	
$\xi_{охлCA}$	$\xi_{охлPK}$	
a^*_c	a^*_w	
$T_{ад}$	$T_{ад}$	
P^*_w	T^*_w	
$a_{зв}$	$a_{зв}$	
u	u	
\underline{c}	c	
c_a	c_u	
w	w	
w_a	w_u	
λ_c	M_c	
λ_w	M_w	
v_{stator}	v_{rotor}	<div> <div>=</div> <div> <div>r = av(N_r)</div> <div>for i ∈ 1 .. Z</div> <div> trace(concat("стvпень i = " . num2str(i)))</div> </div> </div>

chord _{stator}	chord _{rotor}
$\bar{t}_{\text{оптCA}}$	$\bar{t}_{\text{оптPK}}$
t_{stator}	t_{rotor}
Z_{stator}	Z_{rotor}
\bar{v}_{stator}	\bar{v}_{rotor}
ξ_{TpCA}	ξ_{TpPK}
ξ_{kpCA}	ξ_{kpPK}
ξ_{ReCA}	ξ_{RePK}
$\xi_{\lambda\text{CA}}$	$\xi_{\lambda\text{PK}}$
$\xi_{\text{ппCA}}$	$\xi_{\text{ппPK}}$
ξ_{BTCA}	ξ_{BTPK}
$\xi_{\text{ТДCA}}$	$\xi_{\text{ТДPK}}$
ξ_{cmCA}	ξ_{cmPK}
$\xi_{\Delta r}$	$\xi_{\text{ВЫХ}}$
$\xi_{\text{Tp.B}}$	$\xi_{\text{Tp.B}}$
L_{CT}	Lu_{CT}
$\eta_{\text{мощь}}$	$\eta_{\text{люп}}$
η^*_{CT}	η^*_{CT}
η_{u1}	η_{u2}
ξ_{CA}	ξ_{PK}
$(Lu_{\text{нагрузка}} \quad Lu_{\text{нагрузка}})$	

if $i = 1$

$$\alpha_{\text{ox}_{\text{st}(i,1),r}} = \alpha_{\text{ox}}$$

$$k_{\text{st}(i,1),r} = k_{\Gamma}$$

$$P^*_{\text{st}(i,1),r} = P^*_{\Gamma}$$

$$P^*_{\text{w}_{\text{st}(i,1),r}} = 0$$

$$P_{\text{st}(i,1),r} = P_{\Gamma}$$

$$T^*_{\text{st}(i,1),r} = T^*_{\Gamma}$$

$$T^*_{\text{w}_{\text{st}(i,1),r}} = 0$$

$$T_{\text{st}(i,1),r} = T_{\Gamma}$$

$$v_{\text{st}(i,1),r} = \frac{R_{\text{газ}}(\alpha_{\text{ox}_{\text{st}(i,1),r}}, \text{Fuel}) \cdot T_{\text{st}(i,1),r}}{P_{\text{st}(i,1),r}}$$

$$G_{\text{st}(i,1)} = G_{\Gamma}$$

$$c_{\text{st}(i,1),r} = c_{\Gamma}$$

$$\alpha_{\text{st}(i,1),r} = \alpha_{\Gamma}$$

$$\begin{pmatrix} c_{\text{u}_{\text{st}(i,1),r}} \\ c_{\text{a}_{\text{st}(i,1),r}} \end{pmatrix} = c_{\text{st}(i,1),r} \cdot \begin{pmatrix} \cos(\alpha_{\text{st}(i,1),r}) \\ \sin(\alpha_{\text{st}(i,1),r}) \end{pmatrix}$$

$$w_{\text{st}(i,1),r} = 0$$

$$\begin{pmatrix} a_{3B_{\text{st}(i,1),r}} \\ a^*_{c_{\text{st}(i,1),r}} \\ a^*_{w_{\text{st}(i,1),r}} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{\text{st}(i,1),r} \cdot R_{\text{газ}}(\alpha_{\text{ox}_{\text{st}(i,1),r}}, \text{Fuel}) \cdot T_{\text{st}(i,1),r}} \\ \sqrt{\frac{2 \cdot k_{\text{st}(i,1),r}}{1 + k_{\text{st}(i,1),r}} \cdot R_{\text{газ}}(\alpha_{\text{ox}_{\text{st}(i,1),r}}, \text{Fuel}) \cdot T^*_{\text{st}(i,1),r}} \\ \sqrt{\frac{2 \cdot k_{\text{st}(i,1),r}}{1 + k_{\text{st}(i,1),r}} \cdot R_{\text{газ}}(\alpha_{\text{ox}_{\text{st}(i,1),r}}, \text{Fuel}) \cdot T^*_{w_{\text{st}(i,1),r}}} \end{pmatrix}$$

$$\begin{pmatrix} \lambda_{c_{\text{st}(i,1),r}} \\ \lambda_{w_{\text{st}(i,1),r}} \end{pmatrix} = \begin{pmatrix} \frac{c_{\text{st}(i,1),r}}{a^*_{c_{\text{st}(i,1),r}}} \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} M_{c_{\text{st}(i,1),r}} \\ M_{w_{\text{st}(i,1),r}} \end{pmatrix} = \frac{1}{a_{3B_{\text{st}(i,1),r}}} \cdot \begin{pmatrix} c_{\text{st}(i,1),r} \\ w_{\text{st}(i,1),r} \end{pmatrix}$$

iteration_{cT_i} = 0

while 1 > 0

$$\text{iteration}_{\text{cT}_i} = \text{iteration}_{\text{cT}_i} + 1$$

trace(concat(" iteration.ct = ", num2str(iteration_{CT_i}))))

$$H_{CT_i} = N_{CT_i} \cdot \begin{cases} \frac{1}{G_{st(i,1)} \cdot 0.9} & \text{if } (iteration_{CT_i} = 1) \\ \frac{1}{\text{mean}(G_{st(i,2)}, G_{st(i,3)}) \cdot \eta_{\text{МОШБ}_i}} & \text{otherwise} \end{cases}$$

$$R_{L_{i,r}} = R_{L.cp_i}$$

$$c_{a_{st(i,1),r}} = \sqrt{2 \cdot H_{CT_i}}$$

$$H_{stator_i} = H_{CT_i} \cdot (1 - R_{L_{i,r}})$$

$$c_{a_{st(i,2),r}} = \sqrt{2 \cdot H_{stator_i}}$$

$$\bar{v}_{stator_i} = 1$$

$$iteration_{CA_i} = 0$$

while 1 > 0

$$iteration_{CA_i} = iteration_{CA_i} + 1$$

trace(concat(" iteration.CA = ", num2str(iteration_{CA_i}))))

$$c_{st(i,2),r} = \bar{v}_{stator_i} \cdot c_{a_{st(i,2),r}}$$

$$\theta_{CA_i} = \theta_{\text{ГЛУБИНА}}(T^*_{st(i,1),r}, T^*_{\text{cooling}}, T_{\text{Л.ДОП}})$$

$$g_{\text{ОХЛ}CA_i} = \begin{cases} \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} & \text{if } \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{st(i,2)} = G_{st(i,1)} \cdot (1 + g_{\text{ОХЛ}CA_i})$$

$$\alpha_{\text{OX}_{st(i,2)}} = \alpha_{\text{OX}_{st(i,1)}} + g_{\text{ОХЛ}CA_i}$$

$$\alpha_{\text{OK}CA_i} = \text{mean}(\alpha_{\text{OX}_{st(i,1)}}, \alpha_{\text{OX}_{st(i,2)}})$$

$$k_{st(i,2),r} = k_{st(i,1),r}$$

while 1 > 0

$$k_{CA_i} = \text{mean}(k_{st(i,1),r}, k_{st(i,2),r})$$

$$T_{a_{st(i,2),r}} = T^*_{st(i,1),r} - \frac{H_{stator_i}}{\frac{k_{CA_i}}{k_{CA_i} - 1} \cdot R_{\text{ГАЗ.СР}}(\alpha_{\text{OX}_{st(i,1)}}, \alpha_{\text{OX}_{st(i,2)}}, \text{Fuel})}$$

$$\begin{aligned}
P_{st(i,2),r} &= P_{st(i,1),r}^* \left(\frac{T_{ad,st(i,2),r}}{T_{st(i,1),r}^*} \right)^{\frac{c_{pi}}{k_{CA_i}-1}} \\
T_{st(i,2),r} &= T_{st(i,1),r}^* - \frac{H_{stator_i} \cdot (\bar{v}_{stator_i})^2}{\frac{k_{CA_i}}{k_{CA_i}-1} \cdot R_{газ.cp}(\alpha_{ox,st(i,1)}, \alpha_{ox,st(i,2)}, Fuel)} \\
Cp_2 &= Cp_{газ}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox,st(i,2)}, Fuel) \\
k' &= k_{ад}(Cp_2, R_{газ}(\alpha_{ox,st(i,2)}, Fuel)) \\
\text{if } |\text{eps}("rel", k_{st(i,2),r}, k')| &\leq \text{epsilon} \\
&\quad k_{st(i,2),r} = k' \\
&\quad \text{break} \\
k_{st(i,2),r} &= k' \\
T_{ad,st(i,2),r}^* &= T_{st(i,2),r} + \frac{(c_{st(i,2),r})^2}{2 \cdot Cp_{газ}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox,st(i,2)}, Fuel)} \\
P_{ad,st(i,2),r}^* &= P_{st(i,2),r} \left(\frac{T_{ad,st(i,2),r}^*}{T_{st(i,2),r}} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r}-1}} \\
\begin{pmatrix} T_{cm,st(i,2),r}^* \\ P_{cm,st(i,2),r}^* \end{pmatrix} &= \begin{bmatrix} T_{смешение} \left[P_{ad,st(i,2),r}^*, T_{ad,st(i,2),r}^*, G_{st(i,1)}, \alpha_{ox,st(i,1)}, P_{cooling}^*, T_{cooling}^*, (g_{oxлCA_i} \cdot G_{st(i,1)}), \alpha_{ox,st(i,2)}, Fuel \right] \\ P_{смешение} \left[P_{ad,st(i,2),r}^*, G_{st(i,1)}, P_{cooling}^*, (g_{oxлCA_i} \cdot G_{st(i,1)}) \right] \end{bmatrix} \\
\begin{pmatrix} T_{st(i,2),r}^* \\ P_{st(i,2),r}^* \end{pmatrix} &= \begin{pmatrix} T_{cm,st(i,2),r}^* \\ P_{cm,st(i,2),r}^* \end{pmatrix} \\
T_{st(i,2),r} &= T_{st(i,2),r}^* - \frac{(c_{st(i,2),r})^2}{2 \cdot Cp_{газ}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox,st(i,2)}, Fuel)} \\
P_{st(i,2),r} &= P_{st(i,2),r}^* \left(\frac{T_{st(i,2),r}}{T_{st(i,2),r}^*} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r}-1}} \\
k_{st(i,2),r} &= k_{ад}(Cp_{газ}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox,st(i,2)}, Fuel), R_{газ}(\alpha_{ox,st(i,2)}, Fuel)) \\
v_{st(i,2),r} &= \frac{R_{газ}(\alpha_{ox,st(i,2)}, Fuel) \cdot T_{st(i,2),r}}{P_{st(i,2),r}} \\
\alpha_{st(i,2),r} &= \text{asin} \left(\frac{G_{st(i,2)} \cdot v_{st(i,2),r}}{P_{st(i,2),r}} \right)
\end{aligned}$$

$$c_{st(i,2),r} = \sqrt{F_{st(i,2),r} \cdot c_{st(i,2),r}}$$

$$\begin{pmatrix} c_{u_{st(i,2),r}} \\ c_{a_{st(i,2),r}} \end{pmatrix} = c_{st(i,2),r} \cdot \begin{pmatrix} \cos(\alpha_{st(i,2),r}) \\ \sin(\alpha_{st(i,2),r}) \end{pmatrix}$$

$$\beta_{st(i,2),r} = \text{triangle}(c_{a_{st(i,2),r}}, c_{u_{st(i,2),r}} - u_{st(i,2),r})$$

$$w_{st(i,2),r} = \sqrt{(c_{st(i,2),r})^2 + (u_{st(i,2),r})^2 - 2 \cdot c_{st(i,2),r} \cdot u_{st(i,2),r} \cdot \cos(\alpha_{st(i,2),r})}$$

$$\begin{pmatrix} w_{u_{st(i,2),r}} \\ w_{a_{st(i,2),r}} \end{pmatrix} = w_{st(i,2),r} \cdot \begin{pmatrix} \cos(\beta_{st(i,2),r}) \\ \sin(\beta_{st(i,2),r}) \end{pmatrix}$$

$$T^*_{w_{st(i,2),r}} = T_{st(i,2),r} + \frac{(w_{st(i,2),r})^2}{2 \cdot C_{p_{\Gamma a3}}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}} , Fuel)}$$

$$P^*_{w_{st(i,2),r}} = P_{st(i,2),r} \cdot \left(\frac{T^*_{w_{st(i,2),r}}}{T_{st(i,2),r}} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r} - 1}}$$

$$\begin{pmatrix} a_{3B_{st(i,2),r}} \\ a^*_{c_{st(i,2),r}} \\ a^*_{w_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,2),r} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T_{st(i,2),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,2),r}}{k_{st(i,2),r} + 1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T^*_{st(i,2),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,2),r}}{k_{st(i,2),r} + 1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T^*_{w_{st(i,2),r}}} \end{pmatrix}$$

$$\begin{pmatrix} \lambda_{c_{st(i,2),r}} \\ \lambda_{w_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} \frac{c_{st(i,2),r}}{a^*_{c_{st(i,2),r}}} \\ \frac{w_{st(i,2),r}}{a^*_{w_{st(i,2),r}}} \end{pmatrix}$$

$$\begin{pmatrix} M_{c_{st(i,2),r}} \\ M_{w_{st(i,2),r}} \end{pmatrix} = \frac{1}{a_{3B_{st(i,2),r}}} \cdot \begin{pmatrix} c_{st(i,2),r} \\ w_{st(i,2),r} \end{pmatrix}$$

$$v_{stator_i} = v_{установка}(\alpha_{st(i,1),r}, \alpha_{st(i,2),r})$$

$$chord_{stator_{i,r}} = \frac{B_{CA_i}}{\sin(v_{stator_i})}$$

$$\bar{t}_{оптCA_i} = \bar{t}_{опт}("CA", g_{охлаCA_i} > 0, \alpha_{st(i,1),r}, \alpha_{st(i,2),r}, \max(\text{submatrix}(\bar{c}_{stator}, i, i, 1, N_r)))$$

$$Z_{stator_i} = \left\lceil \frac{\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r})}{\bar{t}_{оптCA_i} \cdot chord_{stator_{i,r}}} \right\rceil \text{ if } \text{mod} \left(\left\lceil \frac{\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r})}{\bar{t}_{оптCA_i} \cdot chord_{stator_{i,r}}} \right\rceil, 2 \right) = 0$$

$$(\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r}))$$

```

        ceil( (pi * mean(D_st(1,1),r,D_st(1,2),r)) / (t_0птCA_i * chord_stator_i,r) ) + 1 otherwise
    for r ∈ 1..N_r
        t_stator_i,r = (pi * mean(D_st(i,1),r,D_st(i,2),r)) / Z_stator_i
        ξ_трCA_i = ξ_трение(α_st(i,1),r,α_st(i,2),r)
        ξ_крCA_i = ξ_кромка(r_outlet_stator_i,r * chord_stator_i,r, t_stator_i,r, α_st(i,2),r)
        ξ_ReCA_i = ξ_Re( (c_st(i,2),r * chord_stator_i,r) / (μ_газ(T_st(i,2),r,α_ox_st(i,2)) * v_st(i,2),r) )
        ξ_λCA_i = ξ_сжимаемость("CA", λ_c_st(i,2),r)
        ξ_прCA_i = ξ_трCA_i + ξ_крCA_i + ξ_ReCA_i + ξ_λCA_i
        ξ_втCA_i = ξ_вторичные(ξ_трCA_i, t_stator_i,r, α_st(i,2),r, h_st(i,2))
        ξ_тдCA_i = (ξ_тд("CA", T*_cm_st(i,2),r, T*_ад_st(i,2),r, P_st(i,2),r, Cp_газ(P_st(i,2),r, T_st(i,2),r, α_ox_st(i,2), Fuel), R_газ(α_ox_st(i,2), Fuel), G_st(i,2), F_st(i,2), α_st(i,2),r, 0)) / H_stator_i
        ξ_смCA_i = ξ_смешение("CA", g_охлCA_i)
        if |eps("rel", sqrt(1 - ξ_смCA_i - ξ_тдCA_i - ξ_втCA_i - ξ_прCA_i), v_stator_i)| ≤ epsilon
            v_stator_i = sqrt(1 - ξ_смCA_i - ξ_тдCA_i - ξ_втCA_i - ξ_прCA_i)
            break
        v_stator_i = sqrt(1 - ξ_смCA_i - ξ_тдCA_i - ξ_втCA_i - ξ_прCA_i)
    H_rotor_i = H_сT_i * R_L_i,av(N_r) * (T_st(i,2),r / T_ад_st(i,2),r)
    w_ад_st(i,3),r = sqrt((w_st(i,2),r)^2 + 2 * H_rotor_i + (u_st(i,3),r)^2 - (u_st(i,2),r)^2)
    v_rotor_i = 1
    iteration_пK_i = 0
    while 1 > 0
        iteration_пK_i = iteration_пK_i + 1
        trace(concat("    iteration.PK = ", num2str(iteration_пK_i))))
        w_st(i,3),r = v_rotor_i * w_ад_st(i,3),r

```

$$\theta_{PK_i} = \theta_{\text{глубина}}(T_{w_{st(i,2),r}}^*, T_{\text{cooling}}^*, T_{\text{Л.доп}})$$

$$g_{\text{охл}PK_i} = \begin{cases} \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} & \text{if } \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{st(i,3)} = G_{st(i,2)} \cdot (1 + g_{\text{охл}PK_i})$$

$$\alpha_{\text{ox}_{st(i,3)}} = \alpha_{\text{ox}_{st(i,2)}} + g_{\text{охл}PK_i}$$

$$k_{st(i,3),r} = k_{st(i,2),r}$$

while 1 > 0

$$k_{PK_i} = \text{mean}(k_{st(i,2),r}, k_{st(i,3),r})$$

$$T_{a\pi_{st(i,3),r}} = T_{st(i,2),r} - \frac{H_{\text{rotor}_i}}{\frac{k_{PK_i}}{k_{PK_i} - 1} \cdot R_{\text{газ.ср}}(\alpha_{\text{ox}_{st(i,2)}}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})}$$

$$P_{st(i,3),r} = P_{st(i,2),r} \cdot \left(\frac{T_{a\pi_{st(i,3),r}}}{T_{st(i,2),r}} \right)^{\frac{k_{PK_i}}{k_{PK_i} - 1}}$$

$$T_{st(i,3),r} = T_{st(i,2),r} - \frac{(w_{st(i,3),r})^2 - (w_{st(i,2),r})^2 - (u_{st(i,3),r})^2 + (u_{st(i,2),r})^2}{2 \cdot \frac{k_{PK_i}}{k_{PK_i} - 1} \cdot R_{\text{газ.ср}}(\alpha_{\text{ox}_{st(i,2)}}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})}$$

$$Cp_3 = Cp_{\text{газ}}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})$$

$$k' = k_{a\pi}(Cp_3, R_{\text{газ}}(\alpha_{\text{ox}_{st(i,3)}}, \text{Fuel}))$$

if $|\text{eps}(\text{"rel"}, k_{st(i,3),r}, k')| \leq \text{epsilon}$

$$k_{st(i,3),r} = k'$$

break

$$k_{st(i,3)} = k'$$

$$v_{st(i,3),r} = \frac{R_{\text{газ}}(\alpha_{\text{ox}_{st(i,3)}}, \text{Fuel}) \cdot T_{st(i,3),r}}{P_{st(i,3),r}}$$

$$\beta_{st(i,3),r} = \text{asin}\left(\frac{G_{st(i,3)} \cdot v_{st(i,3),r}}{w_{st(i,3),r} \cdot F_{st(i,3)}}\right)$$

$$\begin{pmatrix} c_{u_{st(i,3),r}} \\ c_a \end{pmatrix} = \begin{pmatrix} w_{st(i,3),r} \cdot \cos(\beta_{st(i,3),r}) - u_{st(i,3),r} \\ w_{st(i,3),r} \cdot \sin(\beta_{st(i,3),r}) \end{pmatrix}$$

$$\left(a_{st(i,3),r} \right) = \sqrt{c_{u_{st(i,3),r}}^2 + c_{a_{st(i,3),r}}^2}$$

$$\begin{pmatrix} w_{u_{st(i,3),r}} \\ w_{a_{st(i,3),r}} \end{pmatrix} = \begin{bmatrix} \sqrt{w_{st(i,3),r}^2 - c_{a_{st(i,3),r}}^2} \\ w_{st(i,3),r} \sin(\beta_{st(i,3),r}) \end{bmatrix}$$

$$\alpha_{st(i,3),r} = \text{triangle}(c_{a_{st(i,3),r}}, c_{u_{st(i,3),r}})$$

$$T_{a_{st(i,3),r}}^* = T_{st(i,3),r} + \frac{(c_{st(i,3),r})^2}{2 \cdot Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel)}$$

$$P_{a_{st(i,3),r}}^* = P_{st(i,3),r} \cdot \left(\frac{T_{a_{st(i,3),r}}^*}{T_{st(i,3),r}} \right)^{\frac{k_{st(i,3),r}}{k_{st(i,3),r}-1}}$$

$$\begin{pmatrix} T_{cm_{st(i,3),r}}^* \\ P_{cm_{st(i,3),r}}^* \end{pmatrix} = \begin{bmatrix} T_{смешение} \left[P_{a_{st(i,3),r}}^*, T_{a_{st(i,3),r}}^*, G_{st(i,2)}, \alpha_{ox_{st(i,2)}}, P_{cooling}^*, T_{cooling}^*, (g_{ox_{лПК_i}} \cdot G_{st(i,2)}), \alpha_{ox_{st(i,3)}} , Fuel \right] \\ P_{смешение} \left[P_{a_{st(i,3),r}}^*, G_{st(i,2)}, P_{cooling}^*, (g_{ox_{лПК_i}} \cdot G_{st(i,2)}) \right] \end{bmatrix}$$

$$\begin{pmatrix} T_{st(i,3),r}^* \\ P_{st(i,3),r}^* \end{pmatrix} = \begin{pmatrix} T_{cm_{st(i,3),r}}^* \\ P_{cm_{st(i,3),r}}^* \end{pmatrix}$$

$$T_{st(i,3),r} = T_{st(i,3),r}^* - \frac{(c_{st(i,3),r})^2}{2 \cdot Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel)}$$

$$P_{st(i,3),r} = P_{st(i,3),r}^* \cdot \left(\frac{T_{st(i,3),r}}{T_{st(i,3),r}^*} \right)^{\frac{k_{st(i,3),r}}{k_{st(i,3),r}-1}}$$

$$k_{st(i,3),r} = k_{a_{st(i,3),r}} \left(Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel), R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \right)$$

$$T_{w_{st(i,3),r}}^* = T_{st(i,3),r} + \frac{(w_{st(i,3),r})^2}{2 \cdot \frac{k_{st(i,3),r}}{k_{st(i,3),r}-1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel)}$$

$$\begin{pmatrix} a_{3B_{st(i,3),r}} \\ a_{c_{st(i,3),r}}^* \\ a_{w_{st(i,3),r}}^* \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,3),r} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{st(i,3),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,3),r}}{k_{st(i,3),r}+1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{st(i,3),r}^*} \\ \sqrt{\frac{2 \cdot k_{st(i,3),r}}{k_{st(i,3),r}+1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{w_{st(i,3),r}}^*} \end{pmatrix}$$

$$\left(\lambda_{c_{st(i,3),r}} \right) = \left(\frac{c_{st(i,3),r}}{a_{c_{st(i,3),r}}^*} \right)$$

$$\left(\lambda_{w_{st(i,3),r}} \right) \left(\frac{w_{st(i,3),r}}{a^*_{w_{st(i,3),r}}} \right)$$

$$\left(\frac{M_{c_{st(i,3),r}}}{M_{w_{st(i,3),r}}} \right) = \frac{1}{a_{3B_{st(i,3),r}}} \cdot \left(c_{st(i,3),r} \right)$$

$$v_{rotor_i} = v_{установка}(\beta_{st(i,2),r}, \beta_{st(i,3),r})$$

$$chord_{rotor_{i,r}} = \frac{B_{PK_i}}{\sin(v_{rotor_i})}$$

$$\bar{t}_{оптPK_i} = \bar{t}_{опт}("PK", g_{охлPK_i} > 0, \beta_{st(i,2),r}, \beta_{st(i,3),r}, \max(\text{submatrix}(\bar{c}_{rotor}, i, i, 1, N_r)))$$

$$Z_{rotor_i} = \left| \begin{array}{l} Z_{rotor_i} = \text{ceil} \left(\frac{\pi \cdot \text{mean}(D_{st(i,2),r}, D_{st(i,3),r})}{\bar{t}_{оптPK_i} \cdot chord_{rotor_{i,r}}} \right) \\ \text{while } \gcd(Z_{rotor_i}, Z_{stator_i}) \neq 1 \\ Z_{rotor_i} = Z_{rotor_i} + 1 \end{array} \right|$$

for $r \in 1..N_r$

$$t_{rotor_{i,r}} = \frac{\pi \cdot \text{mean}(D_{st(i,2),r}, D_{st(i,3),r})}{Z_{rotor_i}}$$

$$\xi_{трPK_i} = \xi_{трение}(\beta_{st(i,2),r}, \beta_{st(i,3),r})$$

$$\xi_{крPK_i} = \xi_{кромка}(\bar{r}_{outlet_{rotor_{i,r}}} \cdot chord_{rotor_{i,r}}, t_{rotor_{i,r}}, \beta_{st(i,3),r})$$

$$\xi_{RePK_i} = \xi_{Re} \left(\frac{w_{st(i,3),r} \cdot chord_{rotor_{i,r}}}{\mu_{газ}(T_{st(i,3),r}, \alpha_{ox_{st(i,3)}}) \cdot v_{st(i,3),r}} \right)$$

$$\xi_{\lambda PK_i} = \xi_{сжимаемость}("PK", \lambda_{w_{st(i,3),r}})$$

$$\xi_{прPK_i} = \xi_{трPK_i} + \xi_{крPK_i} + \xi_{RePK_i} + \xi_{\lambda PK_i}$$

$$\xi_{втPK_i} = \xi_{вторичные}(\xi_{трPK_i}, t_{rotor_{i,r}}, \beta_{st(i,3),r}, h_{st(i,3)})$$

$$\xi_{тдPK_i} = \frac{\xi_{тд}("PK", T^*_{cm_{st(i,3),r}}, T^*_{ад_{st(i,3),r}}, P_{st(i,3),r}, C_{pгаз}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}}), Fuel), R_{газ}(\alpha_{ox_{st(i,3)}}), Fuel), G_{st(i,3)}, F_{st(i,3)}, \beta_{st(i,3),r}, u_{st(i,3),r})}{H_{rotor_i}}$$

$$\xi_{смPK_i} = \xi_{смешение}("PK", g_{охлPK_i})$$

if $\left| \text{eps}("rel", \sqrt{1 - \xi_{смPK_i} - \xi_{тдPK_i} - \xi_{втPK_i} - \xi_{прPK_i}}, \bar{v}_{rotor_i}) \right| \leq \text{epsilon}$

$$\bar{v}_{rotor_i} = \sqrt{1 - \xi_{смPK_i} - \xi_{тдPK_i} - \xi_{втPK_i} - \xi_{прPK_i}}$$

break

$$\begin{aligned} \overline{v}_{\text{rotor}_i} &= \sqrt{1 - \xi_{\text{смпк}_i} - \xi_{\text{тдпк}_i} - \xi_{\text{втпк}_i} - \xi_{\text{пппк}_i}} \\ \text{Lu}_{\text{сТ}_i} &= c_{\text{u}_{\text{st}(i,2),r}} \cdot u_{\text{st}(i,2),r} + c_{\text{u}_{\text{st}(i,3),r}} \cdot u_{\text{st}(i,3),r} \\ \begin{pmatrix} \xi_{\text{CA}_i} \\ \xi_{\text{ПК}_i} \\ \xi_{\text{CAиПК}_i} \end{pmatrix} &= \frac{1}{H_{\text{сТ}_i}} \cdot \begin{pmatrix} \xi_{\text{Л}}(\overline{v}_{\text{stator}_i}, c_{\text{st}(i,2),r}) \\ \xi_{\text{Л}}(\overline{v}_{\text{rotor}_i}, w_{\text{st}(i,3),r}) \\ \xi_{\text{Л}}(\overline{v}_{\text{stator}_i}, c_{\text{st}(i,2),r}) \cdot \frac{T_{\text{ад}_{\text{st}(i,3),r}}}{T_{\text{st}(i,2),r}} \end{pmatrix} \\ \xi_{\text{ВЫХ}_i} &= \frac{\xi_{\text{ВЫХОД}}(c_{\text{st}(i,3),r})}{H_{\text{сТ}_i}} \\ \xi_{\Delta r_i} &= \frac{\xi_{\text{г.зазор}}(\Delta r_i, h_{\text{st}(i,3)}, D_{\text{st}(i,3),r}, R_{L_{i,r}}, \text{Lu}_{\text{сТ}_i})}{H_{\text{сТ}_i}} \\ \xi_{\text{тр.В}_i} &= \frac{\xi_{\text{трениеИвентиляция}} \left[D_{\text{st}(i,3),r}, h_{\text{st}(i,3)}, u_{\text{st}(i,3),r}, \left(\frac{v_{\text{st}(i,2),r} + v_{\text{st}(i,3),r}}{2 \cdot v_{\text{st}(i,2),r} \cdot v_{\text{st}(i,3),r}} \right), \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right]}{H_{\text{сТ}_i}} \\ \eta_{\text{u1}_i} &= \frac{\text{Lu}_{\text{сТ}_i}}{H_{\text{сТ}_i}} \\ \eta_{\text{лоп}_i} &= 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\Delta r_i} - \xi_{\text{тр.В}_i} \\ \eta_{\text{u2}_i} &= 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\text{ВЫХ}_i} \\ \eta_{\text{мощь}_i} &= 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\text{ВЫХ}_i} - \xi_{\Delta r_i} - \xi_{\text{тр.В}_i} \\ L_{\text{сТ}_i} &= H_{\text{сТ}_i} \cdot \eta_{\text{мощь}_i} \\ \text{trace} \left(\text{concat} \left(\text{"eps(N) = "}, \text{num2str} \left(\text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right) \right) \right) \\ \text{break if } \left(\left| \text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right| \leq \text{epsilon} \right) \wedge \left(\text{iteration}_{\text{сТ}_i} = 0 \right) \\ \text{iteration}_{\text{сТ}_i} = -1 \text{ if } \left| \text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right| \leq \text{epsilon} \\ \text{Lu}_{\text{нагрузка}_i} &= \frac{\text{Lu}_{\text{сТ}_i}}{\left(\text{mean}(u_{\text{st}(i,2),r}, u_{\text{st}(i,3),r}) \right)^2} \\ \begin{pmatrix} \pi^*_{\text{сТ}_i} \\ \pi_{\text{сТ}_i} \end{pmatrix} &= P^*_{\text{st}(i,1),r} \begin{bmatrix} (P^*_{\text{st}(i,3),r})^{-1} \\ (P_{\text{st}(i,3),r})^{-1} \end{bmatrix} \\ k_{\text{ср}} &= k_{\text{ад}} \left(\text{Cp}_{\text{газ.ср}} \left(P_{\text{st}(i,1),r}, P_{\text{st}(i,3),r}, T_{\text{st}(i,1),r}, T_{\text{st}(i,3),r}, \alpha_{\text{ox}_{\text{st}(i,1)}} \cdot \alpha_{\text{ox}_{\text{st}(i,3)}} \cdot \text{Fuel} \right), R_{\text{газ.ср}} \left(\alpha_{\text{ox}_{\text{st}(i,1)}} \cdot \alpha_{\text{ox}_{\text{st}(i,3)}} \cdot \text{Fuel} \right) \right) \end{aligned}$$

$$\left| \begin{array}{l} H_{cT_i}^* = C_{p_{\Gamma a3}} \cdot c_p \left(P_{st(i,1),r}, P_{st(i,3),r}, T_{st(i,1),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,1)}}, \alpha_{ox_{st(i,3)}} , Fuel \right) \cdot T_{st(i,1),r} \cdot \left[1 - \left(\pi_{cT_i}^* \right)^{\frac{-r}{k_{cp}}} \right] \\ \eta_{cT_i}^* = \frac{L_{cT_i}}{H_{cT_i}^*} \end{array} \right|$$

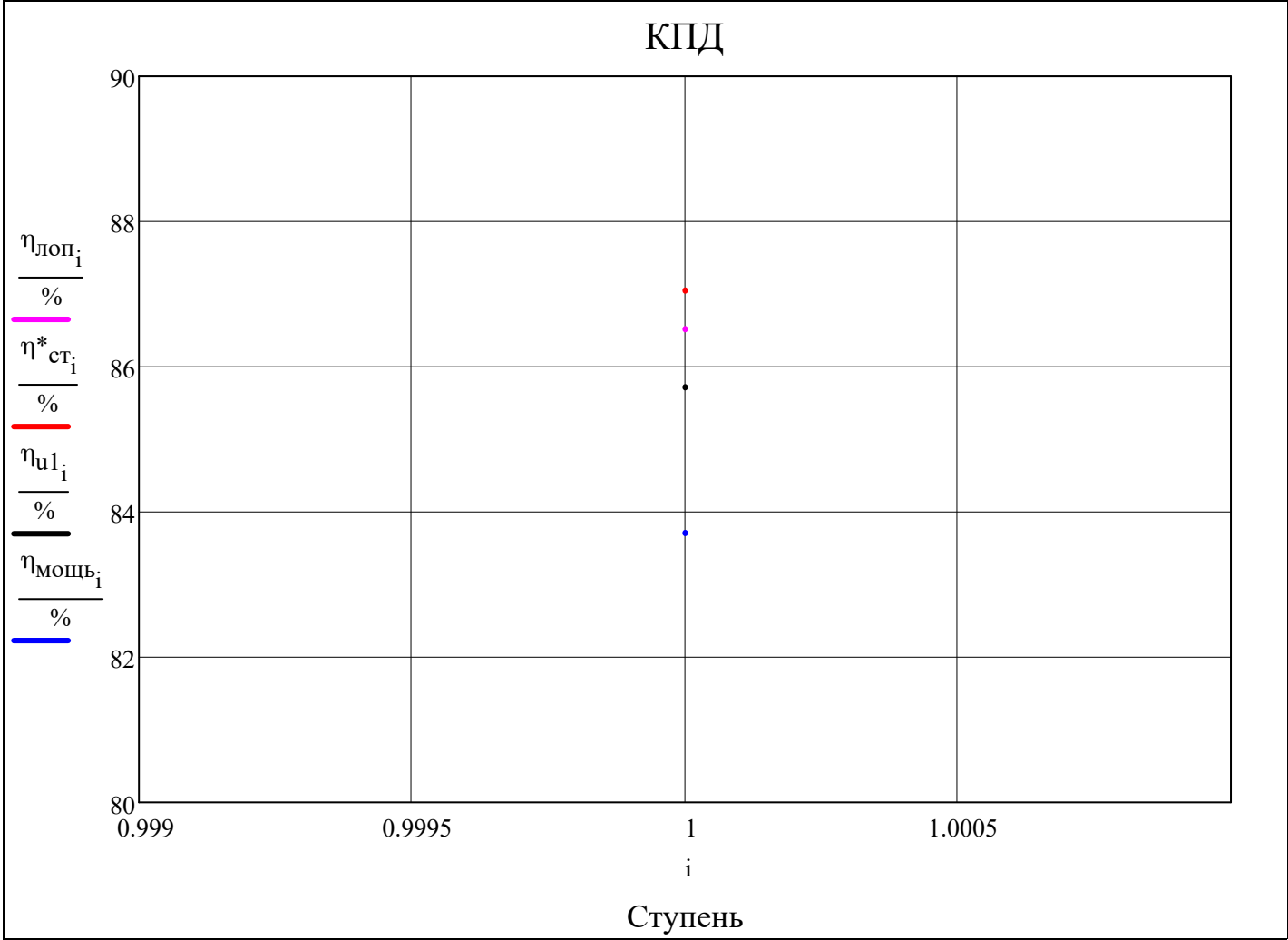
for i ∈ 1..Z

for j ∈ 1..3

$$\left| \begin{array}{l} \rho_{st(i,j),r}^* = \frac{P_{st(i,j),r}^*}{R_{\Gamma a3} \left(\alpha_{ox_{st(i,j)}} , Fuel \right) \cdot T_{st(i,j),r}^*} \\ \rho_{st(i,j),r} = \left(v_{st(i,j),r} \right)^{-1} \\ \left(\begin{array}{l} \varepsilon_{stator_{i,av}(N_r)} \\ \varepsilon_{rotor_{i,av}(N_r)} \end{array} \right) = \left(\begin{array}{l} \alpha_{st(i,2),av(N_r)} - \alpha_{st(i,1),av(N_r)} \\ \beta_{st(i,3),av(N_r)} - \beta_{st(i,2),av(N_r)} \end{array} \right) \end{array} \right|$$

iteration _{CA}	iteration _{PK}
k	R _L
H _{cT} [*]	H _{cT}
H _{stator}	H _{rotor}
c _{ад}	w _{ад}
P [*]	P
T [*]	T
G	v
ρ [*]	ρ
α _{ox}	α _{ox}
α	β
ε _{stator}	ε _{rotor}
θ _{CA}	θ _{PK}
g _{oxлCA}	g _{oxлPK}
a _c [*]	a _w [*]
T _{ад}	T _{ад}
P _w [*]	T _w [*]
a _{3B}	a _{3B}
u	u
c	c
c _a	c _u

	w	w
	w_a	w_u
	λ_c	M_c
	λ_w	M_w
	v_{stator}	v_{rotor}
	$\text{chord}_{\text{stator}}$	$\text{chord}_{\text{rotor}}$
	$\overline{t}_{\text{оптCA}}$	$\overline{t}_{\text{оптPK}}$
	t_{stator}	t_{rotor}
	Z_{stator}	Z_{rotor}
	$\overline{v}_{\text{stator}}$	$\overline{v}_{\text{rotor}}$
	$\xi_{\text{трCA}}$	$\xi_{\text{трPK}}$
	$\xi_{\text{крCA}}$	$\xi_{\text{крPK}}$
	$\xi_{\text{РеCA}}$	$\xi_{\text{РеPK}}$
	$\xi_{\lambda\text{CA}}$	$\xi_{\lambda\text{PK}}$
	$\xi_{\text{прCA}}$	$\xi_{\text{прPK}}$
	$\xi_{\text{втCA}}$	$\xi_{\text{втPK}}$
	$\xi_{\text{тдCA}}$	$\xi_{\text{тдPK}}$
	$\xi_{\text{смCA}}$	$\xi_{\text{смPK}}$
	$\xi_{\Delta r}$	$\xi_{\text{вых}}$
	$\xi_{\text{тр.в}}$	$\xi_{\text{тр.в}}$
	$L_{\text{ст}}$	$L_{u\text{ст}}$
	$\eta_{\text{мощь}}$	$\eta_{\text{лоп}}$
	$\eta^*_{\text{ст}}$	$\eta^*_{\text{ст}}$
	η_{u1}	η_{u2}
	ξ_{CA}	ξ_{PK}
	$L_{u\text{нагрузка}}$	$L_{u\text{нагрузка}}$



$$\eta_{\text{лoп}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 86.53 \\ \hline \end{array} \cdot \%$$

$$\eta^*_{\text{cт}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 87.05 \\ \hline \end{array} \cdot \%$$

$$\text{stack}\left(\eta_{\text{у1}}^T, \eta_{\text{у2}}^T\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 85.72 \\ \hline 2 & 87.03 \\ \hline \end{array} \cdot \%$$

$$\eta_{\text{мoщ}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 83.71 \\ \hline \end{array} \cdot \%$$

$\eta_{\text{мoщ}_i} \leq \eta_{\text{у1}_i} \leq \eta^*_{\text{cт}_i} \leq \eta_{\text{лoп}_i} =$

0

Степень понижения полного давления Т:
Степень понижения давления Т:

$$\left(\frac{\pi^*_{\text{T}}}{\pi_{\text{T}}}\right) = P^*_{\text{st}(1,1), \text{av}(N_{\text{r}})} \cdot \left[\frac{\left(P^*_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}}{\left(P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}} \right] =$$

	1
1	3.13
2	3.25

Температурный перепад по параметрам торможения (Дж/кг):
Располагаемый температурный перепад (Дж/кг):

$$\begin{pmatrix} H^*_{\text{T}} \\ H_{\text{T}} \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^Z H^*_{\text{сТ}_i} \\ \sum_{i=1}^Z H_{\text{сТ}_i} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 515.0 \\ 535.6 \end{pmatrix} \cdot 10^3$$

Мощность Т (Вт):

$$\sum_{i=1}^Z N_{\text{сТ}_i} = 14.89 \cdot 10^6$$

$$\text{eps}\left(\text{"rel"}, N_{\text{T}}, \sum_{i=1}^Z N_{\text{сТ}_i}\right) = 0.000\cdot\%$$

Удельная поступенчатая работа Т [Дж/кг]:

$$L_{\text{T}} = \sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} = 448.6 \cdot 10^3$$

Лопаточный КПД Т:

$$\eta_{\text{Тлоп}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} + \frac{\left(c_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^2}{2}}{H_{\text{T}}} = 86.57\cdot\%$$

$$k_{\text{T.ср}} = k_{\text{ад}}\left(C_{\text{рГаз.ср}}\left(P_{\text{st}(1,1), \text{av}(N_{\text{r}})}, P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, T_{\text{st}(1,1), \text{av}(N_{\text{r}})}, T_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, \alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right), R_{\text{Газ.ср}}\left(\alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right)\right) = 1.289$$

Адиабатный КПД Т:

$$\eta^*_{\text{T}} = \frac{L_{\text{T}}}{H^*_{\text{T}}} = 87.10\cdot\%$$

Политропический КПД Т:

$$\eta^*_{\text{T.п}} = \eta^*_{\text{n}}\left(\text{"расширение"}, \eta^*_{\text{T}}, \pi^*_{\text{T}}, k_{\text{T.ср}}\right) = 85.57\cdot\%$$

Мощностной КПД Т:

$$\eta_{\text{Тмощь}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)}}{H_{\text{T}}} = 83.76\cdot\%$$

$$L_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 448.3 \\ \hline \end{array} \cdot 10^3$$

$$N_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14.89 \\ \hline \end{array} \cdot 10^6$$

$$Lu_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 459.1 \\ \hline \end{array} \cdot 10^3$$

$$Lu_{\text{нагрузка}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.7 \\ \hline \end{array}$$

$$H_{\text{CT}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 535.6 \\ \hline \end{array} \cdot 10^3$$

$$\text{stack}\Big(H_{\text{stator}}^T, H_{\text{rotor}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 449.9 \\ \hline 2 & 86.8 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\Big(R_L^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.2 \\ \hline \end{array}$$

$$G^T = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 32.193 & 33.050 & 33.351 \\ \hline \end{array}$$

$$\alpha_{\text{ox}}^T = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2.267 & 2.294 & 2.303 \\ \hline \end{array}$$

$$\text{stack}\Big(\theta_{\text{CA}}^T, \theta_{\text{PK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.432 \\ \hline 2 & 0.207 \\ \hline \end{array}$$

$$\text{stack}\Big(g_{\text{oxлCA}}^T, g_{\text{oxлPK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 26.61 \\ \hline 2 & 9.11 \\ \hline \end{array} \cdot 10^{-3}$$

$$G_{\text{oxлCA}_i} = g_{\text{oxлCA}_i} \cdot G_{\text{st}(i, 1)}$$

$$G_{\text{oxлPK}_i} = g_{\text{oxлPK}_i} \cdot G_{\text{st}(i, 2)}$$

$$\text{stack}\Big(G_{\text{oxлCA}}^T, G_{\text{oxлPK}}^T\Big) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.9 \\ \hline 2 & 0.3 \\ \hline \end{array}$$

$$G_{\text{cooling}} = 3.2$$

$$\sum_{i=1}^Z G_{\text{oxлCA}_i} + \sum_{i=1}^Z G_{\text{oxлCA}_i} \leq G_{\text{cooling}} = 1$$

$$\text{stack}\Big(\text{iteration}_{\text{CA}}^{\text{T}},\text{iteration}_{\text{PK}}^{\text{T}}\Big)=\begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2 \\ \hline 2 & 2 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{k}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1.283 & 1.293 & 1.295 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{P}^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2731.8 & 2414.5 & 872.9 \\ \hline \end{array}\cdot 10^3$$

$$\text{submatrix}\Big(\text{P}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 2705.2 & 1019.7 & 840.7 \\ \hline \end{array}\cdot 10^3$$

$$\text{submatrix}\Big(\text{T}^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1773.0 & 1759.0 & 1394.2 & & & & & & \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{T}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1769.2 & 1447.6 & 1382.3 & & & & & & \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{T}^{*\text{wT}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 1510.0 & 1500.3 & & & & & & \\ \hline \end{array}$$

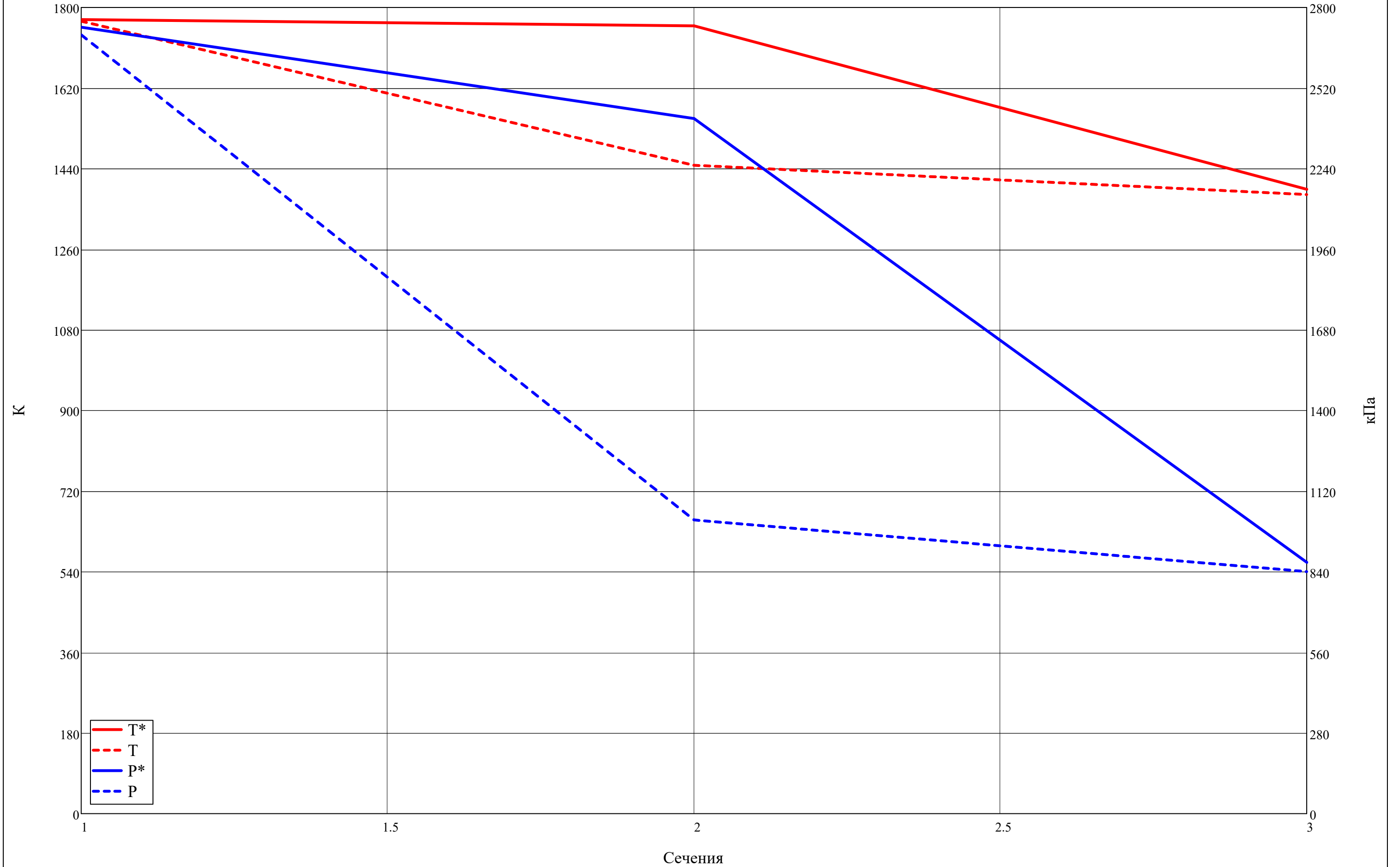
$$\text{submatrix}\Big(\text{T}_{\text{a}\mathcal{A}}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 1429.3 & 1379.5 & & & & & & \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{v}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.189 & 0.410 & 0.486 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\rho^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.341 & 4.758 & 2.170 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\rho^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 5.300 & 2.442 & 2.059 \\ \hline \end{array}$$

Термодинамические параметры по тракту Т на ср. сечении



$$\text{submatrix}\left(\mathbf{a}_{3\mathbf{B}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 809.2 & 734.8 & 718.8 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{a}^*\mathbf{c}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 758.2 & 756.5 & 673.8 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{a}^*\mathbf{w}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 700.9 & 699.0 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{c}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 100.0 & 891.5 & 173.5 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\mathbf{u}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 863.3 & -1.7 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\mathbf{a}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 100.0 & 222.8 & 173.5 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{w}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 398.5 & 546.5 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\mathbf{u}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 330.4 & 518.3 \\\hline\end{array}$$

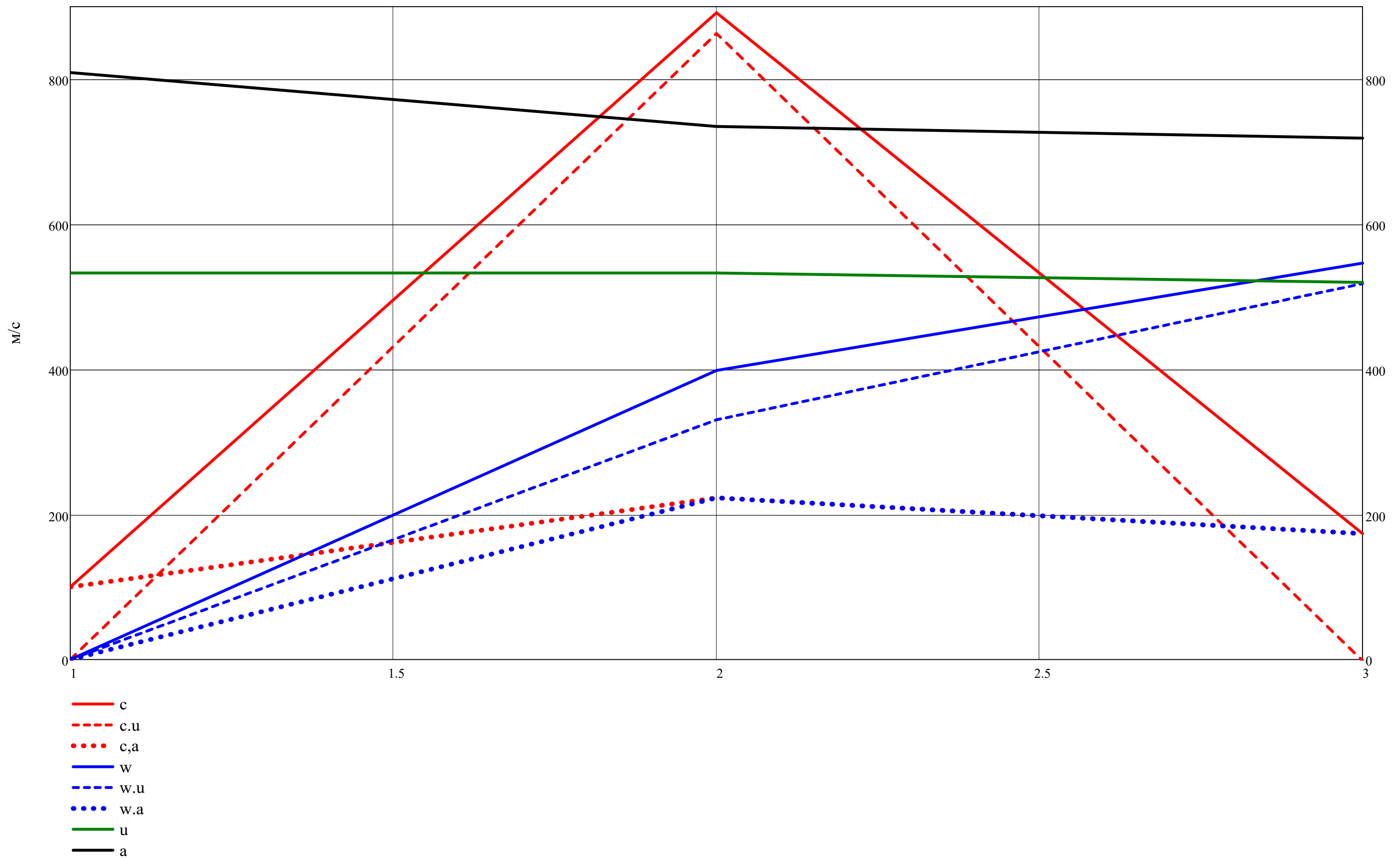
$$\text{submatrix}\left(\mathbf{w}_{\mathbf{a}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 222.8 & 173.5 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\mathbf{a}\mathbf{d}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z\right)=\begin{array}{|c|c|c|}\hline & 1 & 2 \\\hline 1 & 1034.9 & 948.5 \\\hline\end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\mathbf{a}\mathbf{d}}^{\text{T}},\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),\text{av}\left(\mathbf{N}_{\mathbf{r}}\right),1,2Z+1\right)=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 0.0 & 0.0 & 564.7 \\\hline\end{array}$$

$$\mathbf{u}^{\text{T}}=\begin{array}{|c|c|c|c|}\hline & 1 & 2 & 3 \\\hline 1 & 510.5 & 510.5 & 484.8 \\\hline 2 & 532.9 & 532.9 & 520.0 \\\hline 3 & 555.2 & 555.2 & 555.2 \\\hline\end{array}$$

Скорости по тракту Т на ср. сечении



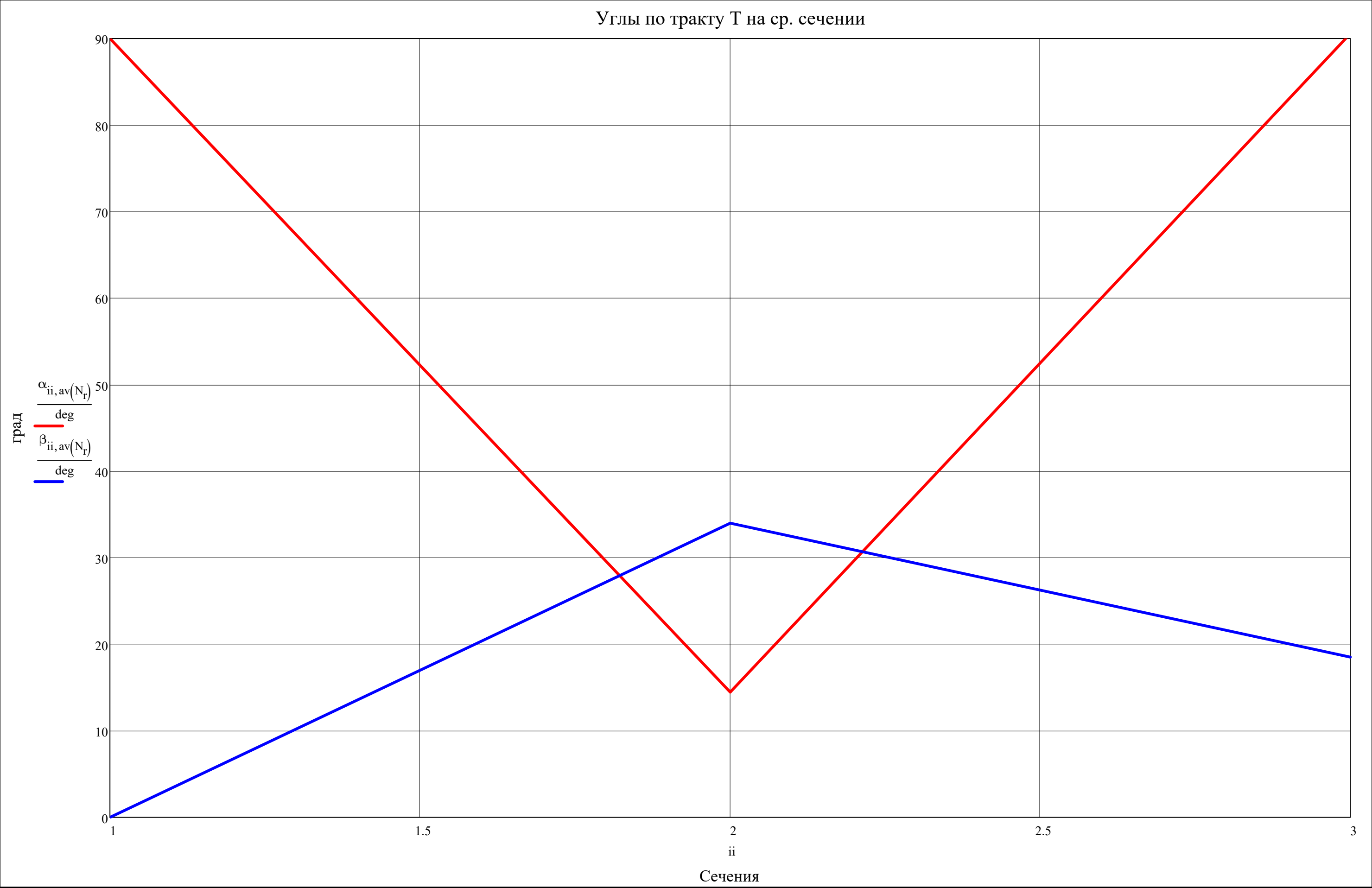
$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 90.00 & 14.47 & 90.57 & & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}\geq 11\cdot^{\circ}=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1 & 1 & 1 & & & & & & \\ \hline \end{array}$$

$$\text{submatrix}\Big(\beta,1,2\cdot Z+1,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \hline 1 & 0.00 & 34.00 & 18.51 & & & & & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{stator}},1,Z,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -75.53 & & & & & \\ \hline \end{array} \cdot^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{rotor}},1,Z,\text{av}\Big(N_{\text{r}}\Big),\text{av}\Big(N_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -15.49 & & & & & \\ \hline \end{array} \cdot^{\circ}$$



$$\text{submatrix}\Big(\lambda_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.1319 & 1.1786 & 0.2575 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\lambda_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0000 & 0.5686 & 0.7819 \\ \hline \end{array}$$

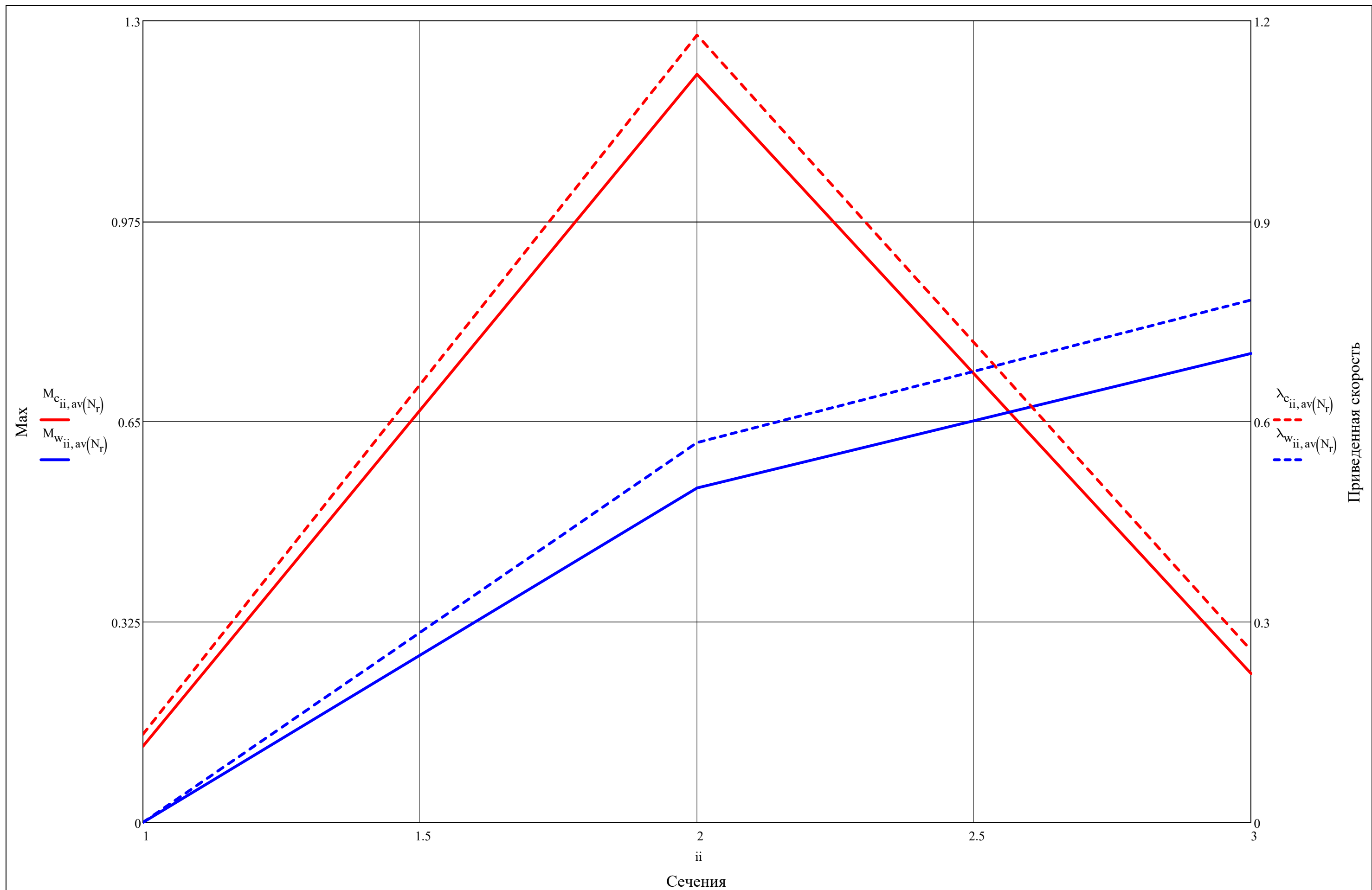
$$\text{submatrix}\Big(\text{M}_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.1236 & 1.2133 & 0.2414 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{M}_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}\leq 1 = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1 & 0 & 1 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{M}_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 0.0000 & 0.5424 & 0.7604 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\text{M}_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}\leq 1 = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\text{stack}\Big(v_{\text{stator}}^{\text{T}},v_{\text{rotor}}^{\text{T}}\Big)= \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 37.02 \\ \hline 2 & 67.05 \\ \hline \end{array} .^{\circ}$$



$$\mathbf{t}_{\text{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 56.7 \\ 2 & 59.2 \\ 3 & 61.7 \end{bmatrix} \cdot 10^{-3}$$

$$\mathbf{t}_{\text{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 22.4 \\ 2 & 23.7 \\ 3 & 25.0 \end{bmatrix} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{stator}}^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{bmatrix} & 1 \\ 1 & 68.0 \end{bmatrix} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{rotor}}^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{bmatrix} & 1 \\ 1 & 32.7 \end{bmatrix} \cdot 10^{-3}$$

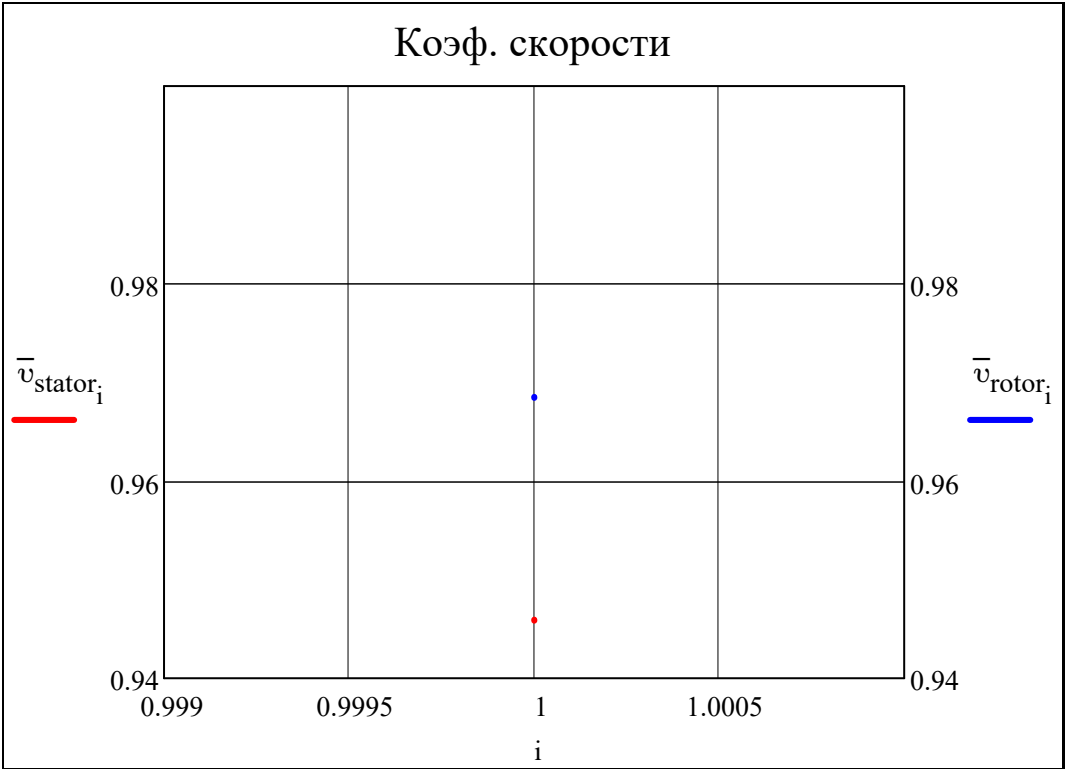
$$\text{stack}\Big(Z_{\text{stator}}^T, Z_{\text{rotor}}^T\Big) = \begin{bmatrix} & 1 \\ 1 & 36 \\ 2 & 89 \end{bmatrix}$$

$$\text{stack}\Big(\overline{\mathbf{t}}_{\text{OITCA}}^T, \overline{\mathbf{t}}_{\text{OITPK}}^T\Big) = \begin{bmatrix} & 1 \\ 1 & 0.872 \\ 2 & 0.725 \end{bmatrix}$$

$$\frac{\mathbf{t}_{\text{stator}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{stator}_{i, \text{av}(N_r)}}} = \boxed{0.7} \leq \frac{\mathbf{t}_{\text{stator}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{stator}_{i, \text{av}(N_r)}}} \leq \boxed{1} = \frac{\mathbf{t}_{\text{rotor}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{rotor}_{i, \text{av}(N_r)}}} = \boxed{0.724} \leq \frac{\mathbf{t}_{\text{rotor}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{rotor}_{i, \text{av}(N_r)}}} \leq \boxed{1} =$$

$$\text{stack}\left(\overline{v}_{\text{stator}}^T, \overline{v}_{\text{rotor}}^T\right) =$$

	1
1	0.9459
2	0.9685



$$\text{stack}\left(\xi_{\text{TpCA}}^{\text{T}}, \xi_{\text{TpPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.398 \\ \hline 2 & 2.622 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{KpCA}}^{\text{T}}, \xi_{\text{KpPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.756 \\ \hline 2 & 1.131 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ReCA}}^{\text{T}}, \xi_{\text{RePK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -0.135 \\ \hline 2 & 0.084 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\lambda\text{CA}}^{\text{T}}, \xi_{\lambda\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.410 \\ \hline 2 & 0.023 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{BTCA}}^{\text{T}}, \xi_{\text{BTPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.452 \\ \hline 2 & 0.878 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{TDCA}}^{\text{T}}, \xi_{\text{TDPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.857 \\ \hline 2 & 1.209 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{сmCA}}^{\text{T}}, \xi_{\text{сmPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.784 \\ \hline 2 & 0.249 \\ \hline \end{array} \cdot\%$$

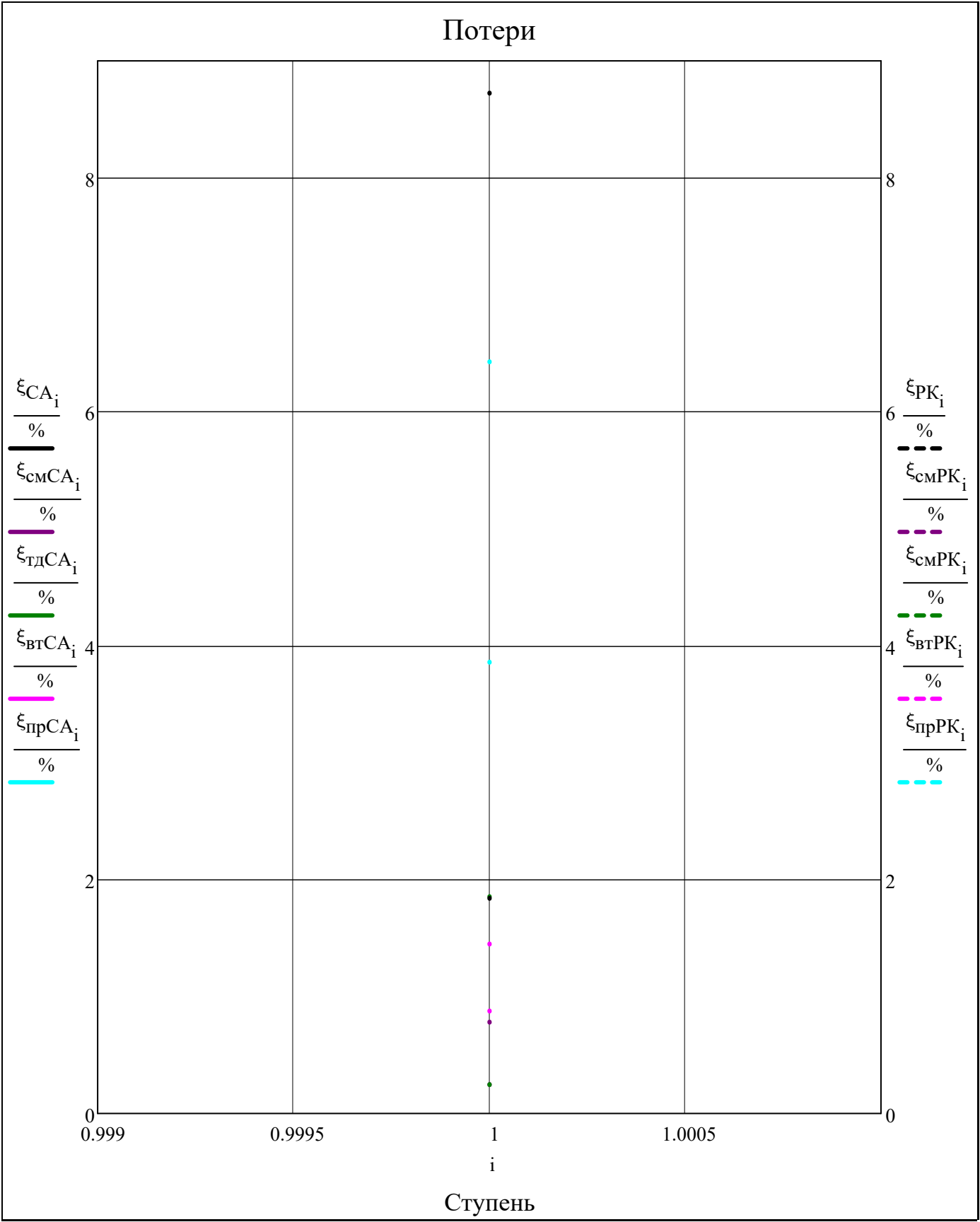
$$\text{stack}\left(\xi_{\text{CA}}^{\text{T}}, \xi_{\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 8.727 \\ \hline 2 & 1.842 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{ВЫХ}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.811 \\ \hline \end{array} \cdot\%$$

$$\xi_{\Delta\text{r}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.481 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{Гр.В}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.835 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ппCA}}^{\text{T}}, \xi_{\text{ппPK}}^{\text{T}}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6.429 \\ \hline 2 & 3.861 \\ \hline \end{array} \cdot\%$$



$$m_{\text{ww}} = \begin{pmatrix} \overline{v}_{\text{stator}_1} \cdot \cos\left(\alpha_{\text{st}(1,2), \text{av}(N_r)}\right)^2 \text{ if } Z = 1 \\ -0.5 \text{ otherwise} \\ -0.25 \\ 0 \\ 0.25 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{"}\alpha.2=\text{const" } \\ \text{"}\Gamma=\text{const" } \\ \text{"}m=\text{const" } \\ \text{"}R=\text{const" } \end{pmatrix} = \begin{pmatrix} \cos\left(\alpha_{\text{st}(i,2), \text{av}(N_r)}\right)^2 \cdot \overline{v}_{\text{stator}_i} \\ 1 \cdot \overline{v}_{\text{stator}_i} \\ 0.2 \\ -1 \cdot \overline{v}_{\text{stator}_i} \end{pmatrix}$$

m^T =

	1	2	3	4	5	6
1	0.8868	-0.2500	0.0000	0.2500	1.0000	1.0000

P*	P	=	<div> <div>for i ∈ 1..Z</div> <div> <div>for a ∈ 2..3</div> <div> <div>for r ∈ 1..N_r</div> <div> <div> $A_{st(i,a)} = \left(1 - R_{L_{i,av}(N_r)}\right) \cdot \omega \cdot \left(R_{st(i,a),av(N_r)}\right)^{m_i+1}$ $B_{st(i,a)} = \frac{Lu_{cT_i}}{2 \cdot \omega}$ $c_{u_{st(i,a),r}} = \left \begin{array}{l} \text{if } m_i = \overline{v}_{stator,i} \cdot \cos\left(\alpha_{st(i,2),av(N_r)}\right)^2 \\ \left \begin{array}{l} c_{u_{st(i,a),av(N_r)}} \cdot \left(\frac{R_{st(i,a),av(N_r)}}{R_{st(i,a),r}}\right)^{m_i} \text{ if } a = 2 \\ \frac{u_{st(i,a-1),av(N_r)} \cdot c_{u_{st(i,a-1),av(N_r)}} + u_{st(i,a),av(N_r)} \cdot c_{u_{st(i,a),av(N_r)}} - u_{st(i,a-1),r} \cdot c_{u_{st(i,a-1),r}}}{u_{st(i,a),r}} \text{ otherwise} \end{array} \right. \\ \text{otherwise} \\ \left \begin{array}{l} \frac{A_{st(i,a)}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a)}}{\left(R_{st(i,a),r}\right)} \text{ if } a = 2 \\ -\frac{A_{st(i,a)}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a)}}{\left(R_{st(i,a),r}\right)} \text{ otherwise} \end{array} \right. \end{array} \right$ $c_{a_{st(i,a),r}} = \left \begin{array}{l} \sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a)}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] + 4 \cdot A_{st(i,a)} \cdot B_{st(i,a)} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)} \cdot \left \begin{array}{l} -1 \text{ if } a = 2 \\ 1 \text{ otherwise} \end{array} \right. \text{ if } m_i = -1 \\ \sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a)}\right)^2 \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right) - 2 \cdot A_{st(i,a)} \cdot B_{st(i,a)} \cdot \left(\frac{1}{R_{st(i,a),r}} - \frac{1}{R_{st(i,a),av(N_r)}}\right)} \cdot \left \begin{array}{l} -1 \text{ if } a = 2 \\ 1 \text{ otherwise} \end{array} \right. \text{ if } m_i = 0 \end{array} \right$ </div> </div> </div> </div> </div>
----	---	---	---

$$\begin{aligned}
& \text{if } m_i = \bar{v}_{\text{stator}_i} \cdot \cos(\alpha_{\text{st}(i,2), \text{av}(N_r)})^2 \\
& \quad c_{a_{\text{st}(i,a), \text{av}(N_r)}} \cdot \sqrt{1 + \frac{\left(1 - \frac{\bar{v}_{\text{stator}_i}}{m_i}\right) \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^{2 \cdot m_i}}\right]}{\tan(\alpha_{\text{st}(i,2), \text{av}(N_r)})^2}} \quad \text{if } a = 2 \\
& \quad \left[\left(c_{a_{\text{st}(i,a), \text{av}(N_r)}}\right)^2 \dots \right. \\
& \quad + \left[1 - (\bar{v}_{\text{rotor}_i})^2\right] \cdot \left(u_{\text{st}(i,a), \text{av}(N_r)}\right)^2 \cdot \left[1 - \left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^2\right] - 2 \cdot c_{u_{\text{st}(i,a), \text{av}(N_r)}} \cdot u_{\text{st}(i,a), \text{av}(N_r)} \cdot \left[1 - \left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^{1-m_i}\right] \dots \\
& \quad + \left[1 - (\bar{v}_{\text{rotor}_i})^2\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^2}\right] \cdot \left(c_{u_{\text{st}(i,a-1), \text{av}(N_r)}} + c_{u_{\text{st}(i,a), \text{av}(N_r)}}\right)^2 \dots \\
& \quad + -2 \cdot c_{u_{\text{st}(i,a-1), \text{av}(N_r)}} \cdot \left(c_{u_{\text{st}(i,a-1), \text{av}(N_r)}} + c_{u_{\text{st}(i,a), \text{av}(N_r)}}\right) \cdot \left[1 - \frac{2}{m_i + 1} \cdot (\bar{v}_{\text{rotor}_i})^2\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^{m_i+1}}\right] \dots \\
& \quad + \left(c_{u_{\text{st}(i,a-1), \text{av}(N_r)}}\right)^2 \cdot \left[1 - \frac{(\bar{v}_{\text{stator}_i})^2 \cdot (\bar{v}_{\text{rotor}_i})^2}{m_i}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{\text{st}(i,a),r}}{R_{\text{st}(i,a), \text{av}(N_r)}}\right)^{2 \cdot m_i}}\right] \\
& \quad \left. \right] \\
& \quad \sqrt{\left(c_{a_{\text{st}(i,a), \text{av}(N_r)}}\right)^2 + \frac{A_{\text{st}(i,a)} \cdot (m_i - 1) \cdot \left[-A_{\text{st}(i,a)} \cdot (m_i + 1) \cdot \left[\frac{1}{(R_{\text{st}(i,a),r})^{2 \cdot m_i}} - \frac{1}{(R_{\text{st}(i,a), \text{av}(N_r)})^{2 \cdot m_i}}\right] \dots \right.}{m_i \cdot (m_i + 1)} \cdot \left. \left[\frac{1}{(R_{\text{st}(i,a),r})^{m_i+1}} - \frac{1}{(R_{\text{st}(i,a), \text{av}(N_r)})^{m_i+1}}\right] \cdot \begin{cases} -1 & \text{if } a = 2 \\ 1 & \text{otherwise} \end{cases} \right]} \quad \text{otherwise}
\end{aligned}$$

for $i \in 1..2 \cdot Z + 1$

for $r \in 1..N_r$

$$\begin{pmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{pmatrix} = c_{i, \text{av}(N_r)} \begin{pmatrix} \cos(\alpha_{i, \text{av}(N_r)}) \\ \sin(\alpha_{i, \text{av}(N_r)}) \end{pmatrix} \quad \text{if } (i = 1)$$

$$P_{i,r}^* = P_{i, \text{av}(N_r)}^*$$

$$T_{i,r}^* = T_{i, \text{av}(N_r)}^*$$

$$\rho_{i,r}^* = \frac{P_{i,r}^*}{R_{\text{ra3}}(\alpha_{\text{ox}_i}, \text{Fuel}) \cdot T_{i,r}^*}$$

$$k_{i,r} = k_{ад} \left(C_{p_{\text{воздух}}} (P_{i,r}^*, T_{i,r}^*), R_{\text{газ}} (\alpha_{\text{ox}_i}, \text{Fuel}) \right)$$

$$a_{c_{i,r}}^* = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{\text{газ}} (\alpha_{\text{ox}_i}, \text{Fuel}) \cdot T_{i,r}^*}$$

$$\alpha_{i,r} = \text{triangle} (c_{a_{i,r}}, c_{u_{i,r}})$$

$$c_{i,r} = \frac{c_{a_{i,r}}}{\sin(\alpha_{i,r})}$$

$$\lambda_{c_{i,r}} = \frac{c_{i,r}}{a_{c_{i,r}}^*}$$

$$\begin{pmatrix} T_{i,r} \\ P_{i,r} \\ \rho_{i,r} \end{pmatrix} = \begin{pmatrix} T_{i,r}^* \cdot \Gamma \Delta \Phi ("T", \lambda_{c_{i,r}}, k_{i,r}) \\ P_{i,r}^* \cdot \Gamma \Delta \Phi ("P", \lambda_{c_{i,r}}, k_{i,r}) \\ \rho_{i,r}^* \cdot \Gamma \Delta \Phi ("P", \lambda_{c_{i,r}}, k_{i,r}) \end{pmatrix}$$

$$a_{3B_{i,r}} = \sqrt{k_{i,r} \cdot R_{\text{газ}} (\alpha_{\text{ox}_i}, \text{Fuel}) \cdot T_{i,r}}$$

$$M_{c_{i,r}} = \frac{c_{i,r}}{a_{3B_{i,r}}}$$

$$\beta_{i,r} = \text{triangle} (c_{a_{i,r}}, u_{i,r} - c_{u_{i,r}})$$

$$w_{i,r} = \frac{c_{a_{i,r}}}{\sin(\beta_{i,r})}$$

$$\begin{pmatrix} w_{u_{i,r}} \\ w_{a_{i,r}} \end{pmatrix} = w_{i,r} \cdot \begin{pmatrix} \cos(\beta_{i,r}) \\ \sin(\beta_{i,r}) \end{pmatrix}$$

$$T_{w_{i,r}}^* = T_{i,r}^* - \frac{(c_{i,r})^2 - (w_{i,r})^2}{2 \cdot \frac{k_{i,r}}{k_{i,r} - 1} \cdot R_{\text{газ}} (\alpha_{\text{ox}_i}, \text{Fuel})}$$

$$a_{w_{i,r}}^* = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{\text{газ}} (\alpha_{\text{ox}_i}, \text{Fuel}) \cdot T_{w_{i,r}}^*}$$

$$\lambda_{w_{i,r}} = \frac{w_{i,r}}{a_{w_{i,r}}^*}$$

$$M_{w_{i,r}} = \frac{w_{i,r}}{a_{3B_{i,r}}}$$

for $i \in 1..Z$

for $r \in 1..N_r$

$$\begin{pmatrix} \Delta c_{a_{st(i,1),r}} \\ \Delta c_{a_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} c_{a_{st(i,2),r}} - c_{a_{st(i,1),r}} \\ c_{a_{st(i,3),r}} - c_{a_{st(i,2),r}} \end{pmatrix}$$

$$R_{L_{i,r}} = 1 - \frac{c_{u_{st(i,2),r}} - c_{u_{st(i,3),r}}}{u_{st(i,2),r} + u_{st(i,3),r}}$$

$$\epsilon_{stator_{i,r}} = \begin{cases} \alpha_{st(i,2),r} - \alpha_{st(i,1),r} & \text{if } \alpha_{st(i,2),r} \geq \frac{\pi}{2} \\ \alpha_{st(i,1),r} - \alpha_{st(i,2),r} & \text{otherwise} \end{cases}$$

$$\epsilon_{rotor_{i,r}} = \begin{cases} \beta_{st(i,3),r} - \beta_{st(i,2),r} & \text{if } \beta_{st(i,3),r} \geq \frac{\pi}{2} \\ \beta_{st(i,2),r} - \beta_{st(i,3),r} & \text{otherwise} \end{cases}$$

$$\begin{pmatrix} P^* & T^* & T & \rho^* & k & a_c^* & a_{3B} & c & c_u & c_a & \Delta c_a & \alpha & \lambda_c & \lambda_w & \epsilon_{stator} \\ P & T_w^* & T & \rho & R_L & a_w^* & a_{3B} & w & w_u & w_a & \Delta c_a & \beta & M_c & M_w & \epsilon_{rotor} \end{pmatrix}^T$$

$$\mathbf{p}^{*T} =$$

	1	2	3
1	2731.8	2414.5	872.9
2	2731.8	2414.5	872.9
3	2731.8	2414.5	872.9

$$\cdot 10^3$$

$$\mathbf{T}^{*T} =$$

	1	2	3	4	5	6	7	8	9
1	1773.0	1759.0	1394.2						
2	1773.0	1759.0	1394.2						
3	1773.0	1759.0	1394.2						

$$\mathbf{T}^{*T}_w =$$

	1	2	3	4	5	6	7	8	9
1	1878.6	1493.4	1491.0						
2	1888.0	1501.1	1507.6						
3	1897.9	1509.2	1525.1						

$$\boldsymbol{\rho}^{*T} =$$

	1	2	3
1	5.341	4.758	2.170
2	5.341	4.758	2.170
3	5.341	4.758	2.170

$$\mathbf{p}^T =$$

	1	2	3
1	2705.2	941.6	850.0
2	2705.2	1016.5	840.7
3	2705.2	1086.9	833.6

$$\cdot 10^3$$

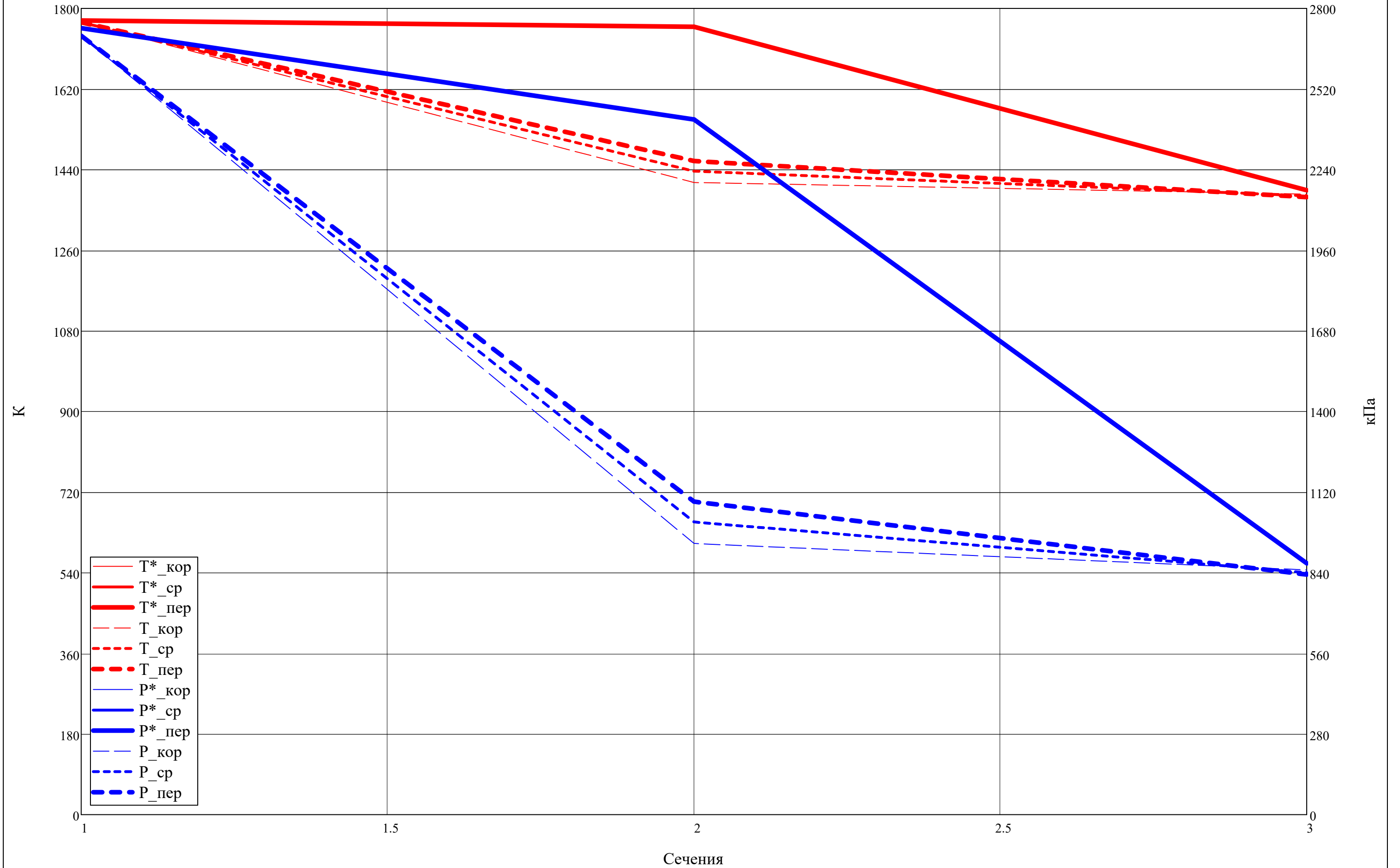
$$\mathbf{T}^T =$$

	1	2	3	4	5	6	7	8	9
1	1768.9	1411.2	1385.3						
2	1768.9	1436.7	1381.6						
3	1768.9	1459.4	1378.8						

$$\boldsymbol{\rho}^T =$$

	1	2	3
1	5.301	2.313	2.127
2	5.301	2.452	2.109
3	5.301	2.582	2.096

Термодинамические параметры по тракту К



$k^T =$

	1	2	3
1	1.305	1.305	1.316
2	1.305	1.305	1.316
3	1.305	1.305	1.316

$R_L^T =$

	1
1	0.1017
2	0.1784
3	0.2456

$R_L^T \geq 0.05 =$

	1
1	1
2	1
3	1

$$a^*_c{}^T =$$

	1	2	3
1	761.0	758.1	676.1
2	761.0	758.1	676.1
3	761.0	758.1	676.1

$$u^T =$$

	1	2	3
1	510.5	510.5	484.8
2	532.9	532.9	520.0
3	555.2	555.2	555.2

$$c^T =$$

	1	2	3
1	100.0	926.1	145.9
2	100.0	891.5	173.5
3	100.0	859.6	191.9

$$c_u^T =$$

	1	2	3
1	0.0	896.7	2.7
2	0.0	863.3	-1.7
3	0.0	832.3	-5.5

$$c_a^T =$$

	1	2	3
1	100.0	231.5	145.9
2	100.0	222.8	173.5
3	100.0	214.9	191.9

$$\Delta c_a^T =$$

	1	2
1	131.5	-85.6
2	122.8	-49.3
3	114.9	-23.0

$$a^*_w{}^T =$$

	1	2	3
1	783.4	698.5	699.2
2	785.3	700.3	703.1
3	787.4	702.2	707.2

$$a_{3B}^T =$$

	1	2	3
1	816.1	729.0	725.3
2	816.1	735.6	724.4
3	816.1	741.3	723.6

$$w^T =$$

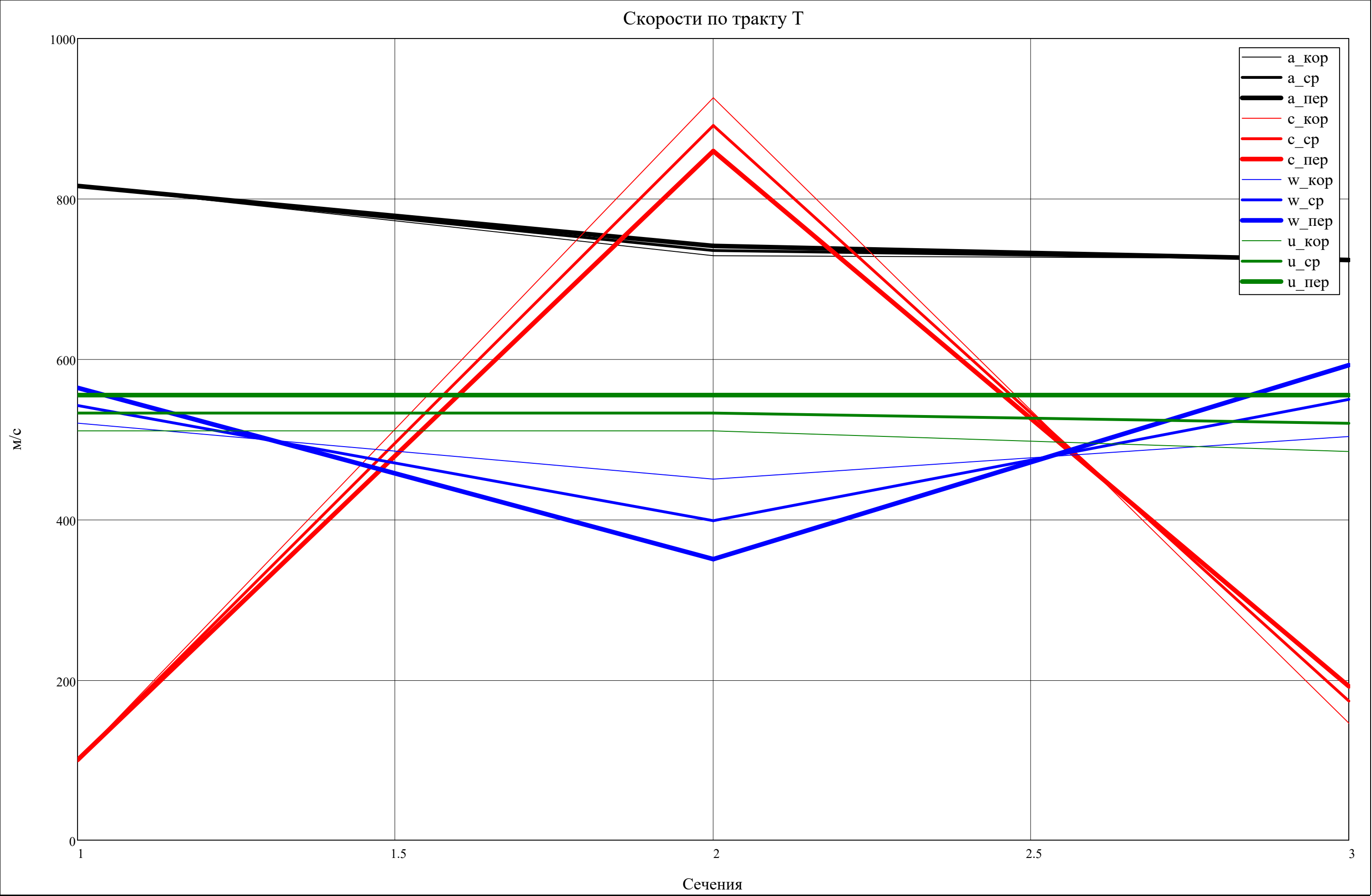
	1	2	3
1	520.2	450.3	503.6
2	542.2	398.5	549.8
3	564.2	350.6	592.6

$$w_u^T =$$

	1	2	3
1	510.5	-386.3	482.0
2	532.9	-330.4	521.7
3	555.2	-277.1	560.7

$$w_a^T =$$

	1	2	3
1	100.0	231.5	145.9
2	100.0	222.8	173.5
3	100.0	214.9	191.9



$\alpha^T =$

	1	2	3
1	90.00	14.47	88.92
2	90.00	14.47	90.57
3	90.00	14.47	91.64

 $^{\circ}$

$80^{\circ} \leq \alpha^T =$

	1	2	3
1	1	0	1
2	1	0	1
3	1	0	1

$\epsilon_{\text{stator}}^T =$

	1
1	75.53
2	75.53
3	75.53

 $^{\circ}$

Угол поворота потока:

[1, с.78]

$\beta^T =$

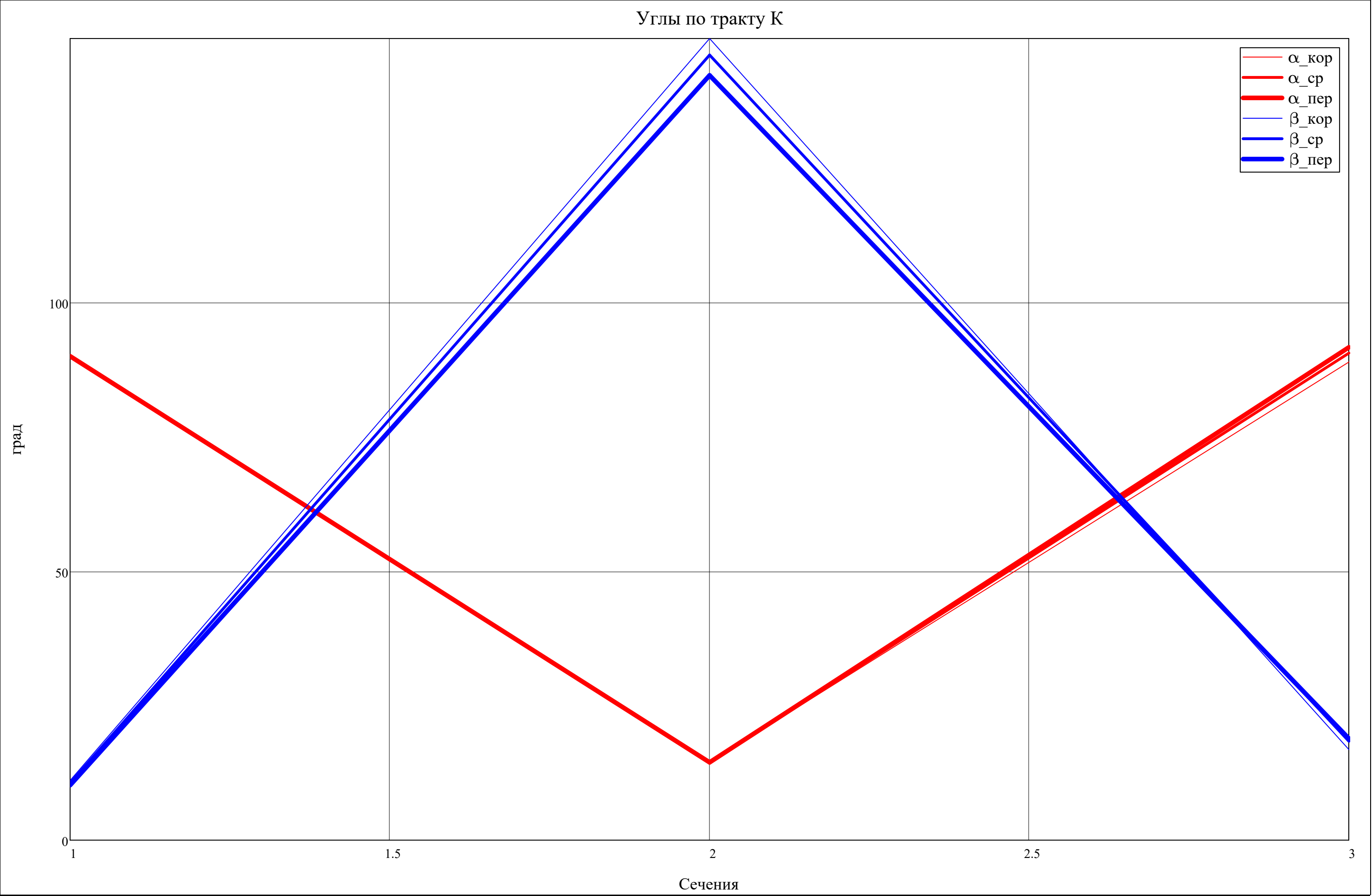
	1	2	3
1	11.08	149.07	16.84
2	10.63	146.00	18.40
3	10.21	142.21	18.89

 $^{\circ}$

$\epsilon_{\text{rotor}}^T =$

	1
1	132.23
2	127.60
3	123.32

 $^{\circ}$



$\lambda_c^T =$

	1	2	3
1	0.131	1.222	0.216
2	0.131	1.176	0.257
3	0.131	1.134	0.284

 $M_c^T =$

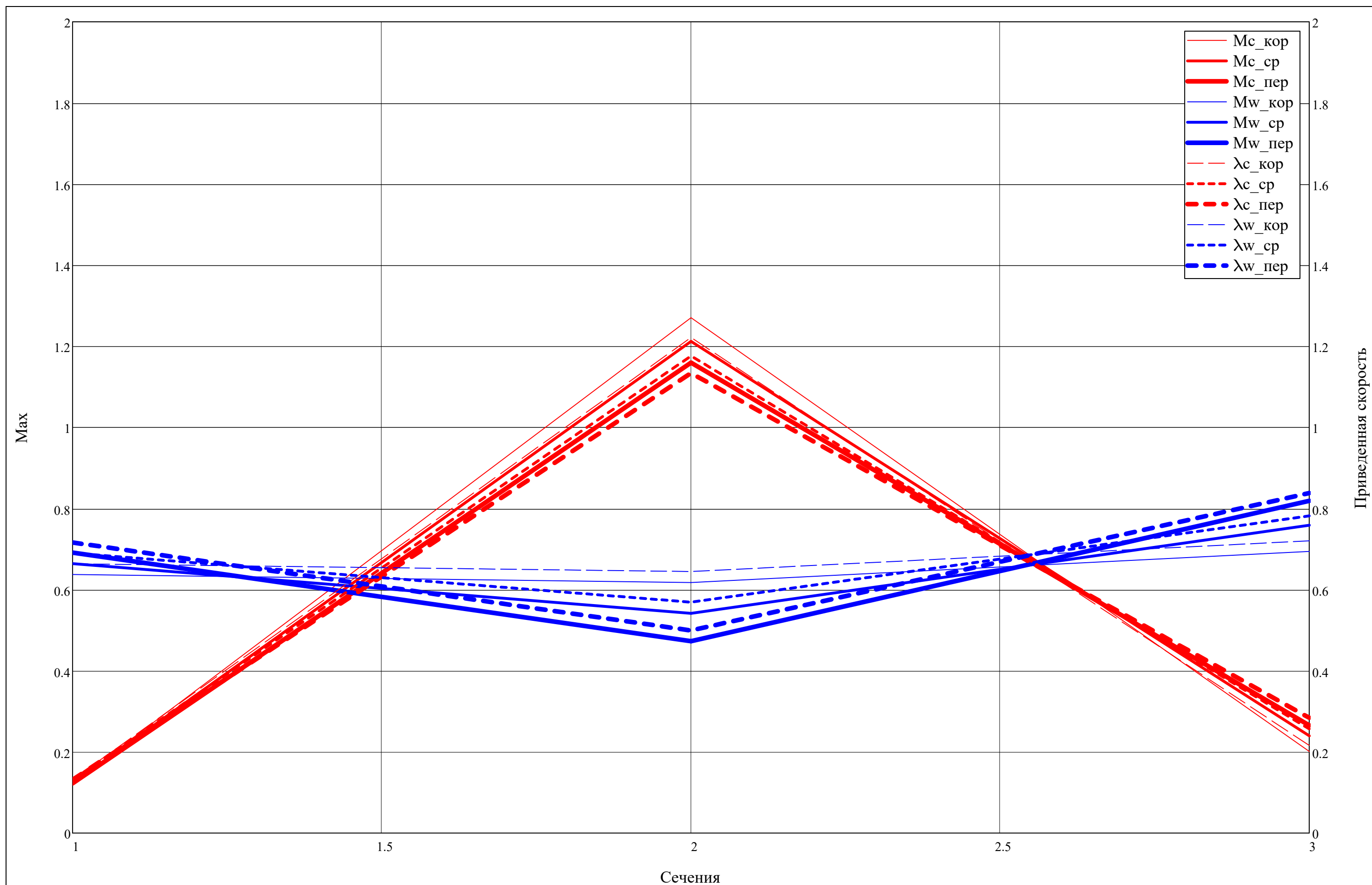
	1	2	3
1	0.123	1.270	0.201
2	0.123	1.212	0.240
3	0.123	1.160	0.265

 $\lambda_w^T =$

	1	2	3
1	0.664	0.645	0.720
2	0.690	0.569	0.782
3	0.717	0.499	0.838

 $M_w^T =$

	1	2	3
1	0.637	0.618	0.694
2	0.664	0.542	0.759
3	0.691	0.473	0.819



Рассматриваемая ступень:

j =

j = Z

j =

"Такой ступени не существует!" if (j < 1) ∨ (j > Z)

j otherwise

= 1

▼

Построение треугольников скоростей в 3х сечениях

Δ_c(v,i,j,r) =

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) ≥ 0) ∧ (−|c_{st(i,j),r}·cos(α_{st(i,j),r})| ≤ v ≤ 0)

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |c_{st(i,j),r}·cos(α_{st(i,j),r})|)

Δ_w(v,i,j,r) =

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) ≥ 0) ∧ (−|w_{st(i,j),r}·cos(β_{st(i,j),r})| ≤ v ≤ 0) ∧ (j ≠ 1)

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |w_{st(i,j),r}·cos(β_{st(i,j),r})|) ∧ (j ≠ 1)

Δ_u(v,i,j,r) =

−c_{a_{st(i,j),r}} if (−c_{st(i,j),r}·cos(α_{st(i,j),r}) ≤ v ≤ w_{st(i,j),r}·cos(β_{st(i,j),r})) ∧ (j ≠ 1)

NaN otherwise

v_{lim} =

ceil

⎛

max(c,w,u)

10²

⎞

·10² = 1000.0

v =

−max(c,w,u), −max(c,w,u) +

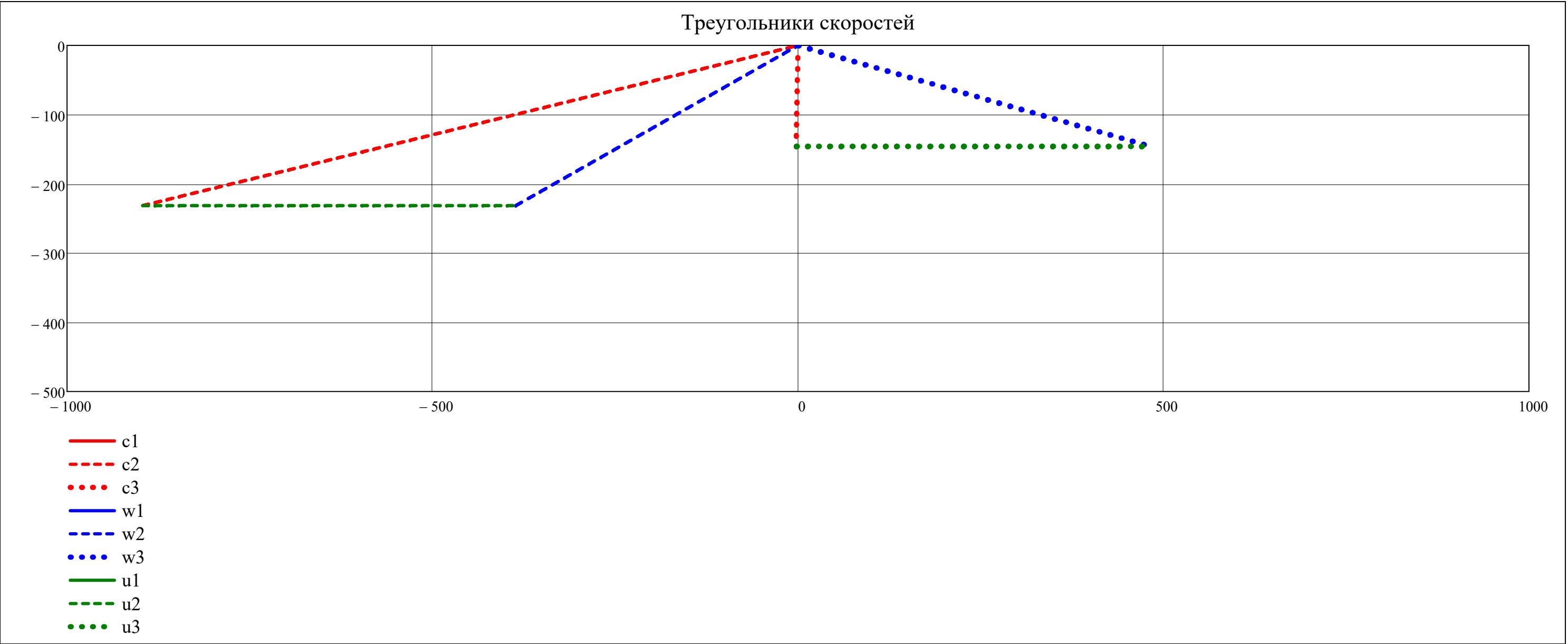
max(c,w,u)

3000

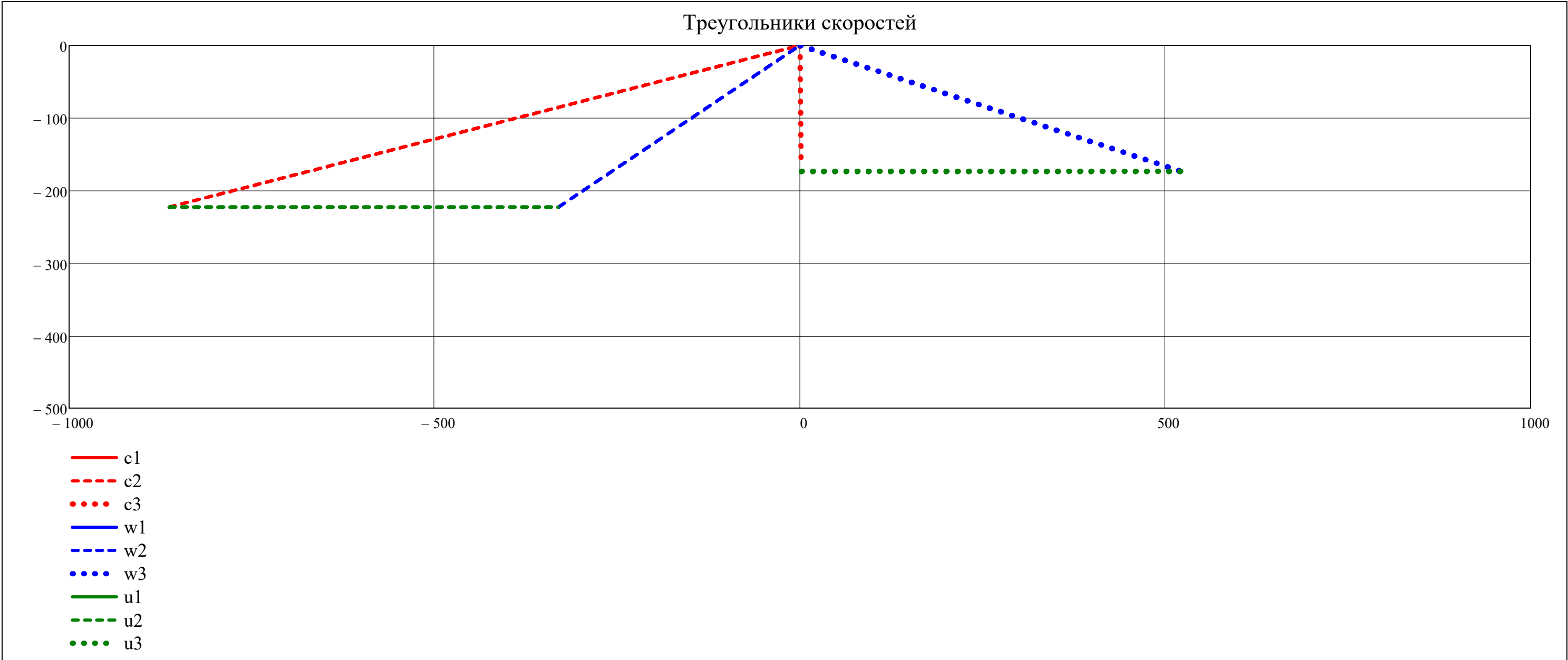
.. max(c,w,u)

67

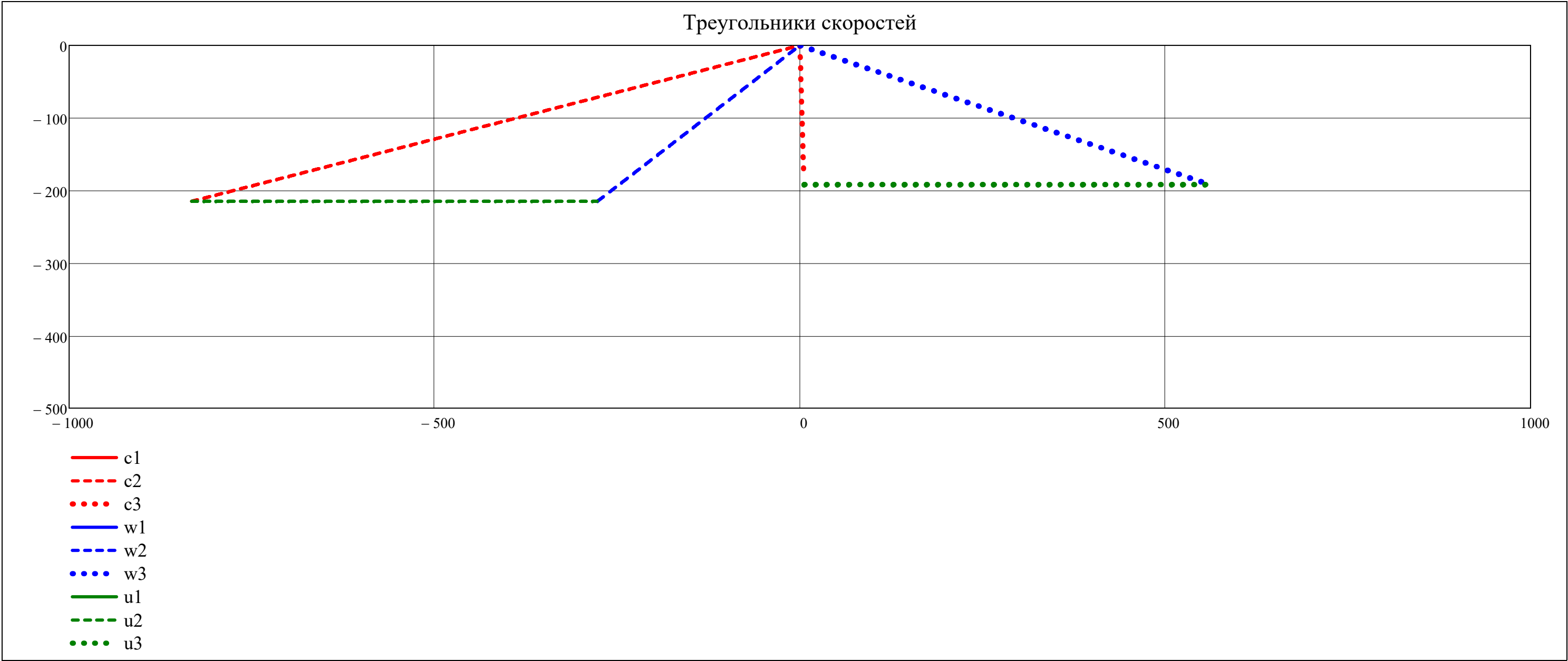
r = 1



$\bar{r}_w = \text{av}(N_r)$



$r_w = N_r$



Построение треугольников скоростей в 3х сечениях

Парусность:

$$\begin{pmatrix} \text{sail}_{\text{stator}} \\ \text{sail}_{\text{rotor}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0.85 \end{pmatrix}$$

▼

Расчет хорд Л по парусности

$$\begin{pmatrix} \text{chord}_{\text{stator}} \\ \text{chord}_{\text{rotor}} \end{pmatrix} =$$

for i ∈ 1..Z

$$\text{sail} = \frac{R_{\text{st}(i,2),N_r} - R_{\text{st}(i,2),1}}{R_{\text{st}(i,2),\text{av}(N_r)} - R_{\text{st}(i,2),1}}$$

for r ∈ 1..N_r

$$b_{\text{CAkop}} = \frac{\text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \cdot \text{sail}}{\text{sail}_{\text{stator}} - 1 + \text{sail}}$$

$$b_{\text{PKkop}} = \frac{\text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \cdot \text{sail}}{\text{sail}_{\text{rotor}} - 1 + \text{sail}}$$

$$\begin{pmatrix} b_{\text{CAпер}} \\ b_{\text{PKпер}} \end{pmatrix} = \begin{pmatrix} b_{\text{CAkop}} \cdot \text{sail}_{\text{stator}} \\ b_{\text{PKkop}} \cdot \text{sail}_{\text{rotor}} \end{pmatrix}$$

$$\text{chord}_{\text{stator.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{CAkop}} \\ \text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \\ b_{\text{CAпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{CAkop}} \\ \text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \\ b_{\text{CAпер}} \end{pmatrix}, z \right]$$

$$\text{chord}_{\text{rotor.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \\ b_{\text{PKпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \\ b_{\text{PKпер}} \end{pmatrix}, z \right]$$

$$\begin{pmatrix} \text{chord}_{\text{stator}_{i,r}} \\ \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \text{chord}_{\text{stator.}}(R_{\text{st}(i,2),r}) \\ \text{chord}_{\text{rotor.}}(R_{\text{st}(i,3),r}) \end{pmatrix}$$

$$\begin{pmatrix} \text{chord}_{\text{stator}} \\ \text{chord}_{\text{rotor}} \end{pmatrix}$$

Длины хорд РК и СА (м):

$$\text{chord}_{\text{stator}}^T =$$

	1
1	68.0
2	68.0
3	68.0

$$\cdot 10^{-3}$$

$$\text{chord}_{\text{rotor}}^T =$$

	1
1	38.4
2	34.2
3	31.4

$$\cdot 10^{-3}$$

▲

Расчет хорд Л по парусности

Ср. линия профиля:
0.5 - дуга окружности
0.45 - парабола

$\overline{x_f} = 0.45$

Расчет параметров решетки

t_{sator} t_{rotor} $r_{\text{inlet}}_{\text{sator}}$ $r_{\text{inlet}}_{\text{rotor}}$ $r_{\text{outlet}}_{\text{sator}}$ $r_{\text{outlet}}_{\text{rotor}}$ c_{sator} c_{rotor} v_{sator} v_{rotor}

=

for i ∈ 1..Z

for r ∈ 1..N_r

$\begin{pmatrix} t_{\text{sator}_{i,r}} \\ t_{\text{rotor}_{i,r}} \end{pmatrix} = \pi \cdot \frac{\frac{\text{mean}(D_{\text{st}(i,1)},r,D_{\text{st}(i,2)},r)}{Z_{\text{sator}_i}}}{\frac{\text{mean}(D_{\text{st}(i,2)},r,D_{\text{st}(i,3)},r)}{Z_{\text{rotor}_i}}}$ $\begin{pmatrix} r_{\text{inlet}}_{\text{sator}_{i,r}} & r_{\text{outlet}}_{\text{sator}_{i,r}} \\ r_{\text{inlet}}_{\text{rotor}_{i,r}} & r_{\text{outlet}}_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{r}_{\text{inlet}}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}} & \overline{r}_{\text{outlet}}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}} \\ \overline{r}_{\text{inlet}}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}} & \overline{r}_{\text{outlet}}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix}$ $\begin{pmatrix} c_{\text{sator}_{i,r}} \\ c_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{c}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}} \\ \overline{c}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix}$ $\begin{pmatrix} v_{\text{sator}_{i,r}} \\ v_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} v_{\text{installation}}(0.5,\alpha_{\text{st}(i,1)},r,\alpha_{\text{st}(i,2)},r) \\ v_{\text{installation}}(0.5,\beta_{\text{st}(i,2)},r,\beta_{\text{st}(i,3)},r) \end{pmatrix} + \frac{\pi}{2}$

t_{sator} t_{rotor} $r_{\text{inlet}}_{\text{sator}}$ $r_{\text{inlet}}_{\text{rotor}}$ $r_{\text{outlet}}_{\text{sator}}$ $r_{\text{outlet}}_{\text{rotor}}$ c_{sator} c_{rotor} v_{sator} v_{rotor}

$\begin{pmatrix} v_{\text{установки}}(\alpha_{\text{st}(i,1)},r,\alpha_{\text{st}(i,2)},r) \\ v_{\text{установки}}(\beta_{\text{st}(i,2)},r,\beta_{\text{st}(i,3)},r) \end{pmatrix}$

$\frac{\pi}{2}$ добавляется в виду поворота рисунка на 90 град

Расчет параметров решетки

72

Относительные радиусы профилей ():

$$\overline{r}_{\text{inlet}_{\text{stator}}}^T =$$

	1
1	6.000
2	6.000
3	6.000

.%

$$\overline{r}_{\text{outlet}_{\text{stator}}}^T =$$

	1
1	3.000
2	3.000
3	3.000

.%

$$\overline{r}_{\text{inlet}_{\text{rotor}}}^T =$$

	1
1	5.100
2	3.900
3	3.300

.%

$$\overline{r}_{\text{outlet}_{\text{rotor}}}^T =$$

	1
1	1.700
2	1.300
3	1.100

.%

Относительная толщина профиля ():

$$\overline{c}_{\text{stator}}^T =$$

	1
1	15.00
2	15.00
3	15.00

.%

$$\overline{c}_{\text{rotor}}^T =$$

	1
1	17.00
2	13.00
3	11.00

.%

Относительный шаг решетки ():

$$\left(\frac{t_{\text{stator}}}{\text{chord}_{\text{stator}}}\right)^T =$$

	1
1	0.8343
2	0.8709
3	0.9075

$$\left(\frac{t_{\text{rotor}}}{\text{chord}_{\text{rotor}}}\right)^T =$$

	1
1	0.5828
2	0.6917
3	0.7939

Относительная густота решетки ():

$$\left(\frac{\text{chord}_{\text{stator}}}{t_{\text{stator}}}\right)^T =$$

	1
1	1.199
2	1.148
3	1.102

$$\left(\frac{\text{chord}_{\text{rotor}}}{t_{\text{rotor}}}\right)^T =$$

	1
1	1.716
2	1.446
3	1.260

Длина хорды профиля [м]:

$$\text{chord}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 68.0 \\ \hline 2 & 68.0 \\ \hline 3 & 68.0 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{chord}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 38.4 \\ \hline 2 & 34.2 \\ \hline 3 & 31.4 \\ \hline \end{array} \cdot 10^{-3}$$

Радиусы профилей:

$$\text{r_inlet}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 4.08 \\ \hline 2 & 4.08 \\ \hline 3 & 4.08 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_inlet}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.96 \\ \hline 2 & 1.33 \\ \hline 3 & 1.04 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.04 \\ \hline 2 & 2.04 \\ \hline 3 & 2.04 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.65 \\ \hline 2 & 0.44 \\ \hline 3 & 0.35 \\ \hline \end{array} \cdot 10^{-3}$$

Толщина профиля [м]:

$$\text{c}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 10.20 \\ \hline 2 & 10.20 \\ \hline 3 & 10.20 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{c}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6.52 \\ \hline 2 & 4.45 \\ \hline 3 & 3.46 \\ \hline \end{array} \cdot 10^{-3}$$

Шаг решетки [м]:

$$\text{t}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 56.7 \\ \hline 2 & 59.2 \\ \hline 3 & 61.7 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{t}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 22.4 \\ \hline 2 & 23.7 \\ \hline 3 & 25.0 \\ \hline \end{array} \cdot 10^{-3}$$

Угол поворота потока:

$\epsilon_{\text{stator}}^T =$

	1
1	75.53
2	75.53
3	75.53

.°

$\epsilon_{\text{rotor}}^T =$

	1
1	132.23
2	127.60
3	123.32

.°

Угол установки профиля:

$\upsilon_{\text{stator}}^T =$

	1
1	117.3
2	117.3
3	117.3

.°

$\upsilon_{\text{rotor}}^T =$

	1
1	111.9
2	114.0
3	115.4

.°

Угол изгиба профиля:

$\pi - \epsilon_{\text{stator}}^T =$

	1
1	104.5
2	104.5
3	104.5

.°

$\pi - \epsilon_{\text{rotor}}^T =$

	1
1	47.8
2	52.4
3	56.7

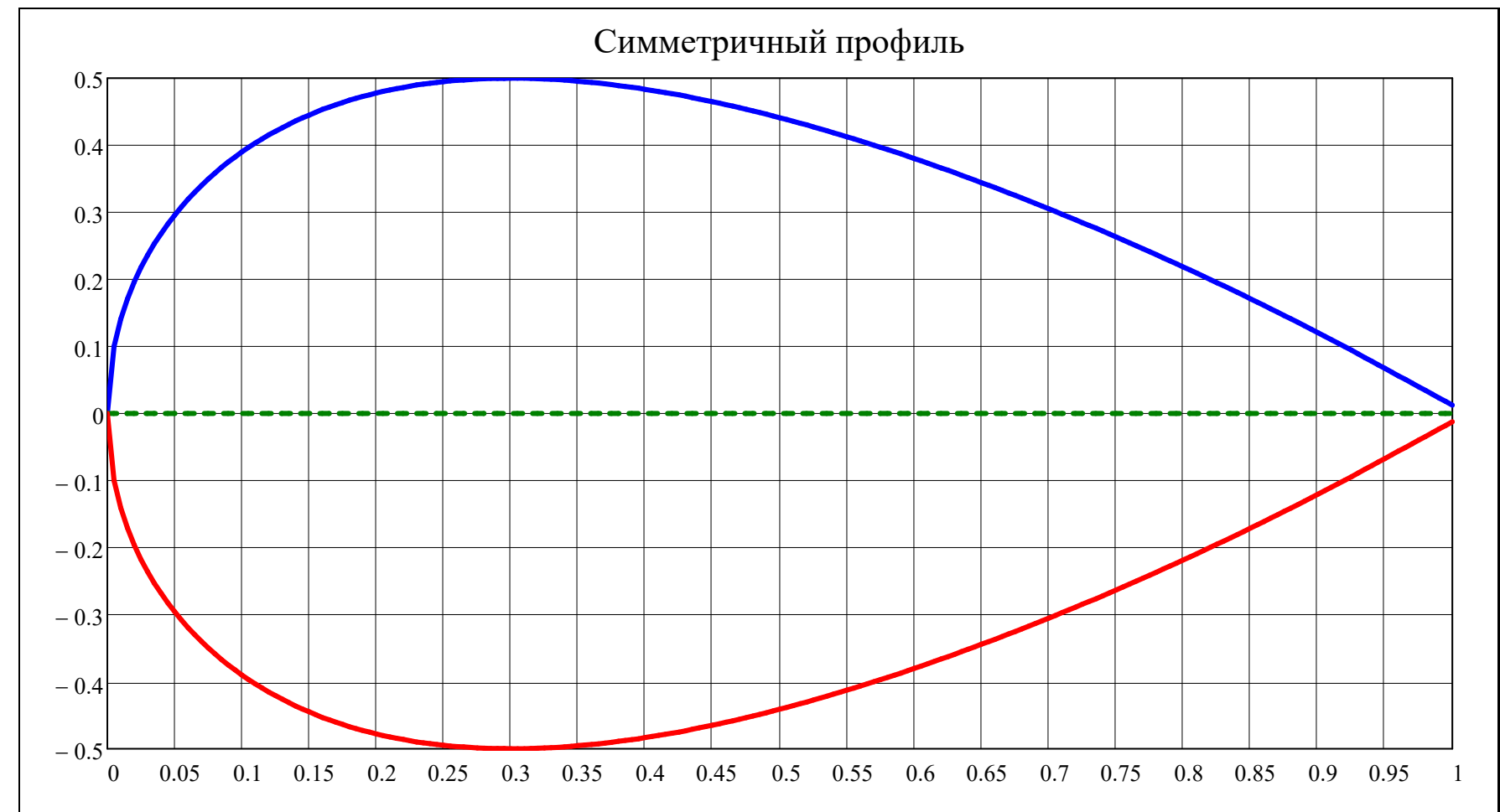
.°

$$\begin{pmatrix} X_U & Y_U \\ X_L & Y_L \end{pmatrix} = \text{NACA}(0,0,100\%,1)$$

Относ. координаты профиля РК и СА:

$$\text{AIRFOIL}_0(x, \text{line}, \overline{f}, \overline{x_f}, \overline{c}) = \begin{cases} \text{if } 0 \leq x \leq 1 \\ \begin{cases} \text{linterp}(X_U, Y_U, x) & \text{if line = "+"} \\ \frac{\text{linterp}(X_U, Y_U, x) + \text{linterp}(X_L, Y_L, x)}{2} & \text{if line = "0"} \\ \text{linterp}(X_L, Y_L, x) & \text{if line = "-"} \end{cases} \\ \text{NaN otherwise} \end{cases}$$

$x = 0, 0.005 \dots 1$



AIRFOIL(x,line,c̄,θ) =

$\text{interp}\left(X_U,y/b_{\text{ср.л}}\left(X_U,\theta\right)+Y_U\cdot\overline{c},x\right)$

if line = "+"

$\frac{\text{interp}\left(X_U,y/b_{\text{ср.л}}\left(X_U,\theta\right)+Y_U\cdot\overline{c},x\right)+\text{interp}\left(X_L,y/b_{\text{ср.л}}\left(X_L,\theta\right)+Y_L\cdot\overline{c},x\right)}{2}$

if line = "0"

$\text{interp}\left(X_L,y/b_{\text{ср.л}}\left(X_L,\theta\right)+Y_L\cdot\overline{c},x\right)$

if line = "-"

NaN

otherwise

Профиль СА на ср. сечении

Профиль РК на ср. сечении

Подключение симметричного профиля

77

$$l_{upper_stator}^T =$$

	1
1	78.09
2	78.09
3	78.09

$$\cdot 10^{-3}$$

$$l_{lower_stator}^T =$$

	1
1	70.66
2	70.66
3	70.66

$$\cdot 10^{-3}$$

$$area_{stator}^T =$$

	1
1	474.07
2	474.07
3	474.07

$$\cdot 10^{-6}$$

$$Sx_{stator}^T =$$

	1
1	4235.7
2	4235.7
3	4235.7

$$\cdot 10^{-9}$$

$$Sy_{stator}^T =$$

	1
1	13572.3
2	13572.3
3	13572.3

$$\cdot 10^{-9}$$

$$x0_{stator}^T =$$

	1
1	28.6
2	28.6
3	28.6

$$\cdot 10^{-3}$$

$$y0_{stator}^T =$$

	1
1	8.9
2	8.9
3	8.9

$$\cdot 10^{-3}$$

$$l_{upper_rotor}^T =$$

	1
1	52.03
2	44.79
3	40.21

$$\cdot 10^{-3}$$

$$l_{lower_rotor}^T =$$

	1
1	44.28
2	39.56
3	36.21

$$\cdot 10^{-3}$$

$$area_{rotor}^T =$$

	1
1	171.21
2	104.00
3	74.31

$$\cdot 10^{-6}$$

$$Sx_{rotor}^T =$$

	1
1	1714.5
2	883.8
3	554.1

$$\cdot 10^{-9}$$

$$Sy_{rotor}^T =$$

	1
1	2766.9
2	1498.0
3	983.5

$$\cdot 10^{-9}$$

$$x0_{rotor}^T =$$

	1
1	16.2
2	14.4
3	13.2

$$\cdot 10^{-3}$$

$$y0_{rotor}^T =$$

	1
1	10.0
2	8.5
3	7.5

$$\cdot 10^{-3}$$

$$J_{x_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 44318 \\ \hline 2 & 44318 \\ \hline 3 & 44318 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 509156 \\ \hline 2 & 509156 \\ \hline 3 & 509156 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 128683 \\ \hline 2 & 128683 \\ \hline 3 & 128683 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6472 \\ \hline 2 & 6472 \\ \hline 3 & 6472 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 120593 \\ \hline 2 & 120593 \\ \hline 3 & 120593 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 7417 \\ \hline 2 & 7417 \\ \hline 3 & 7417 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.70 \\ \hline 2 & 3.70 \\ \hline 3 & 3.70 \\ \hline \end{array} \cdot ^\circ$$

$$J_{x_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 18828 \\ \hline 2 & 8190 \\ \hline 3 & 4501 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 58593 \\ \hline 2 & 28273 \\ \hline 3 & 17058 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29177 \\ \hline 2 & 13416 \\ \hline 3 & 7736 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1659 \\ \hline 2 & 680 \\ \hline 3 & 369 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 13878 \\ \hline 2 & 6697 \\ \hline 3 & 4040 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1468 \\ \hline 2 & 687 \\ \hline 3 & 402 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 6.76 \\ \hline 2 & 6.43 \\ \hline 3 & 6.17 \\ \hline \end{array} \cdot ^\circ$$

$$J_{u_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 5992 \\ \hline 2 & 5992 \\ \hline 3 & 5992 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 121073.3 \\ \hline 2 & 121073.3 \\ \hline 3 & 121073.3 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -0 \\ \hline 2 & -0 \\ \hline 3 & -0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 127065 \\ \hline 2 & 127065 \\ \hline 3 & 127065 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3148.5 \\ \hline 2 & 3148.5 \\ \hline 3 & 3148.5 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{stator}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 11350.7 \\ \hline 2 & 11350.7 \\ \hline 3 & 11350.7 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{u_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1485 \\ \hline 2 & 602 \\ \hline 3 & 326 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 14052 \\ \hline 2 & 6774 \\ \hline 3 & 4084 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0 \\ \hline 2 & 0 \\ \hline 3 & -0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 15536 \\ \hline 2 & 7376 \\ \hline 3 & 4410 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 637.5 \\ \hline 2 & 342.3 \\ \hline 3 & 224.3 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{rotor}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1677.8 \\ \hline 2 & 473.4 \\ \hline 3 & 204.5 \\ \hline \end{array} \cdot 10^{-12}$$

Абс. координаты профиля:

$\text{Airfoil}(\text{type}, x, \text{line}, i, r) =$	$\text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{stator}_{i,r}}, \varepsilon_{\text{stator}_{i,r}}\right) \text{ if type = "stator"}$
	$\text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{rotor}_{i,r}}, \varepsilon_{\text{rotor}_{i,r}}\right) \text{ if type = "rotor"}$

Рассматриваемая ступень:

$$j_v = \begin{cases} j = Z & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

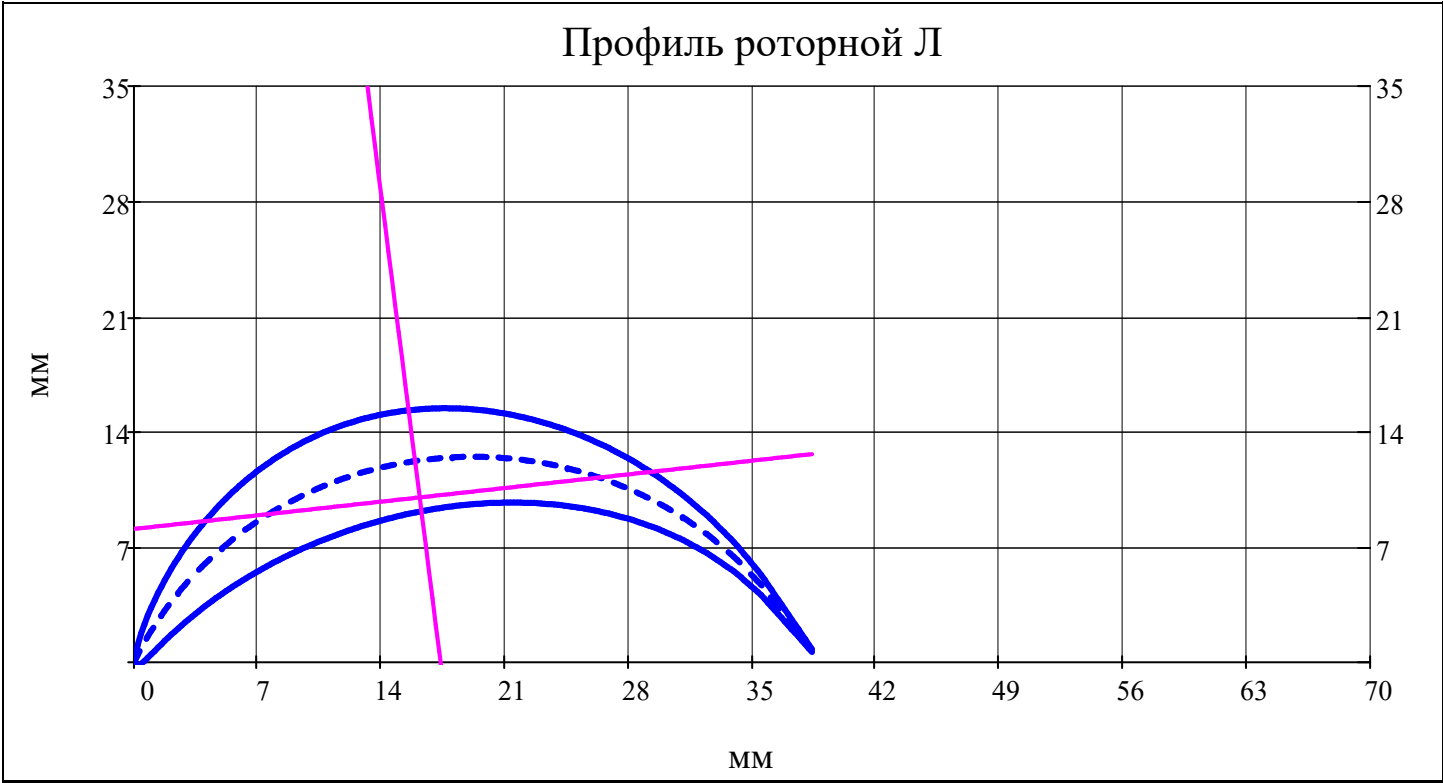
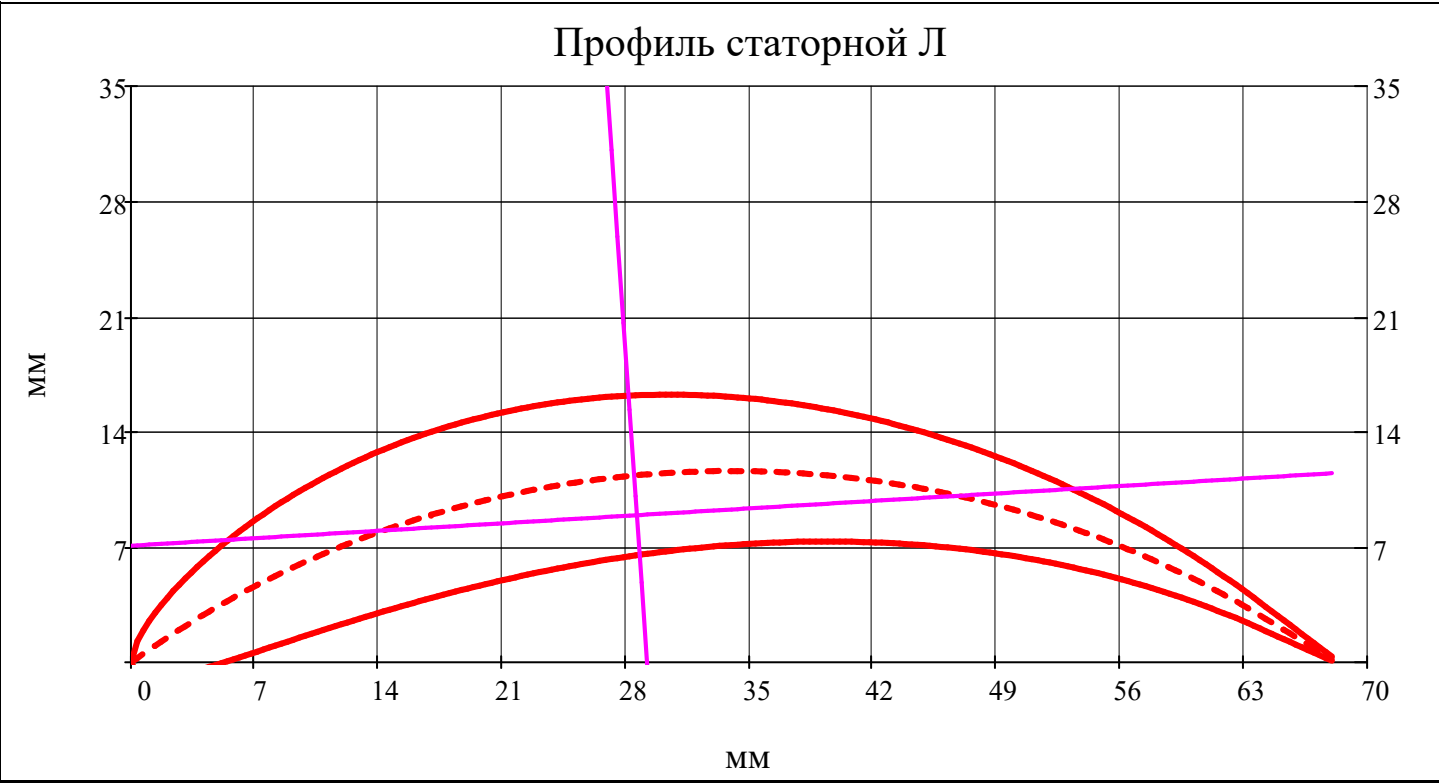
Построение профилей Л РК и НА

$$\text{AXLE0}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if type = "stator"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

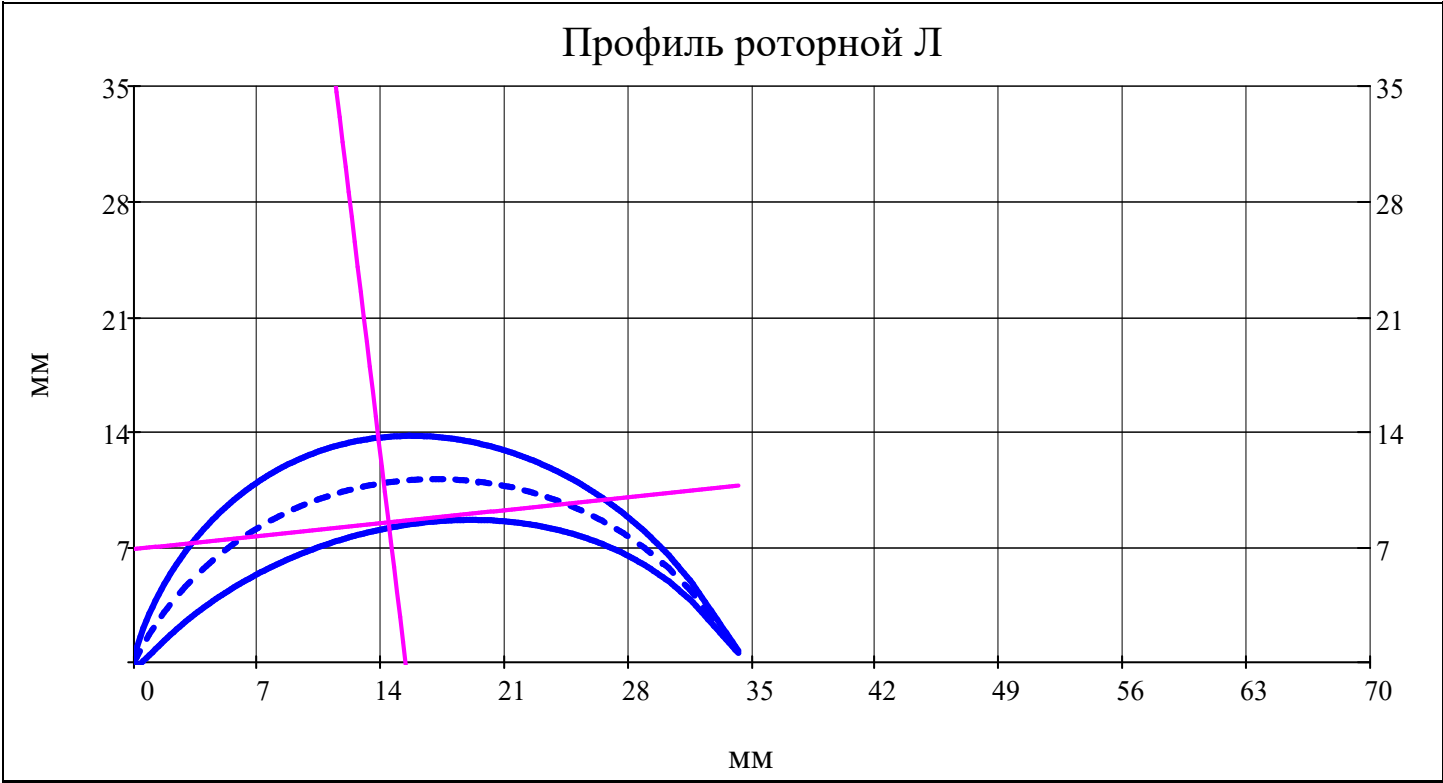
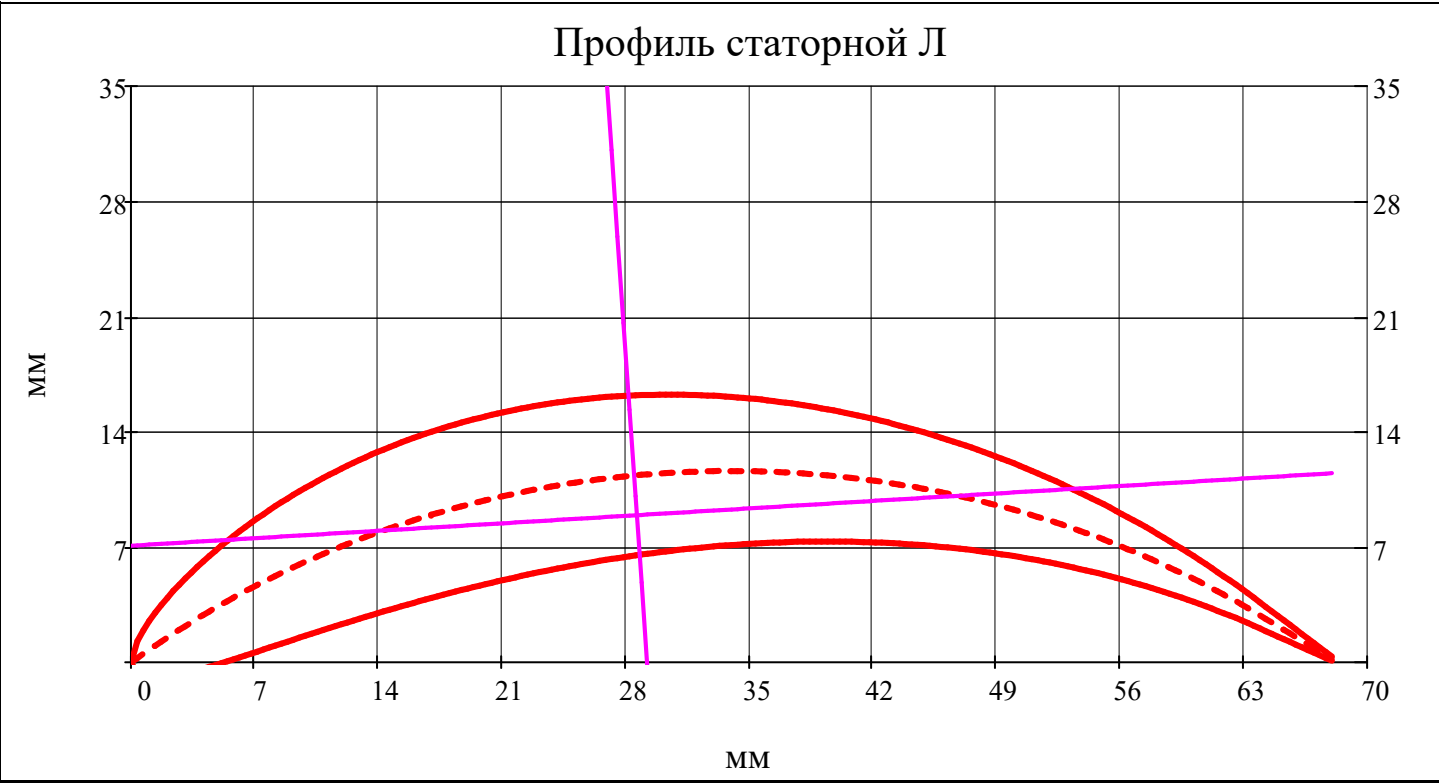
$$\text{AXLE90}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if (type = "rotor") } \wedge \left|\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right| \geq 1^\circ \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if (type = "stator") } \wedge \left|\alpha_{\text{major}_{\text{stator}_{i,r}}}\right| \geq 1^\circ \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$b_{\text{lim}} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

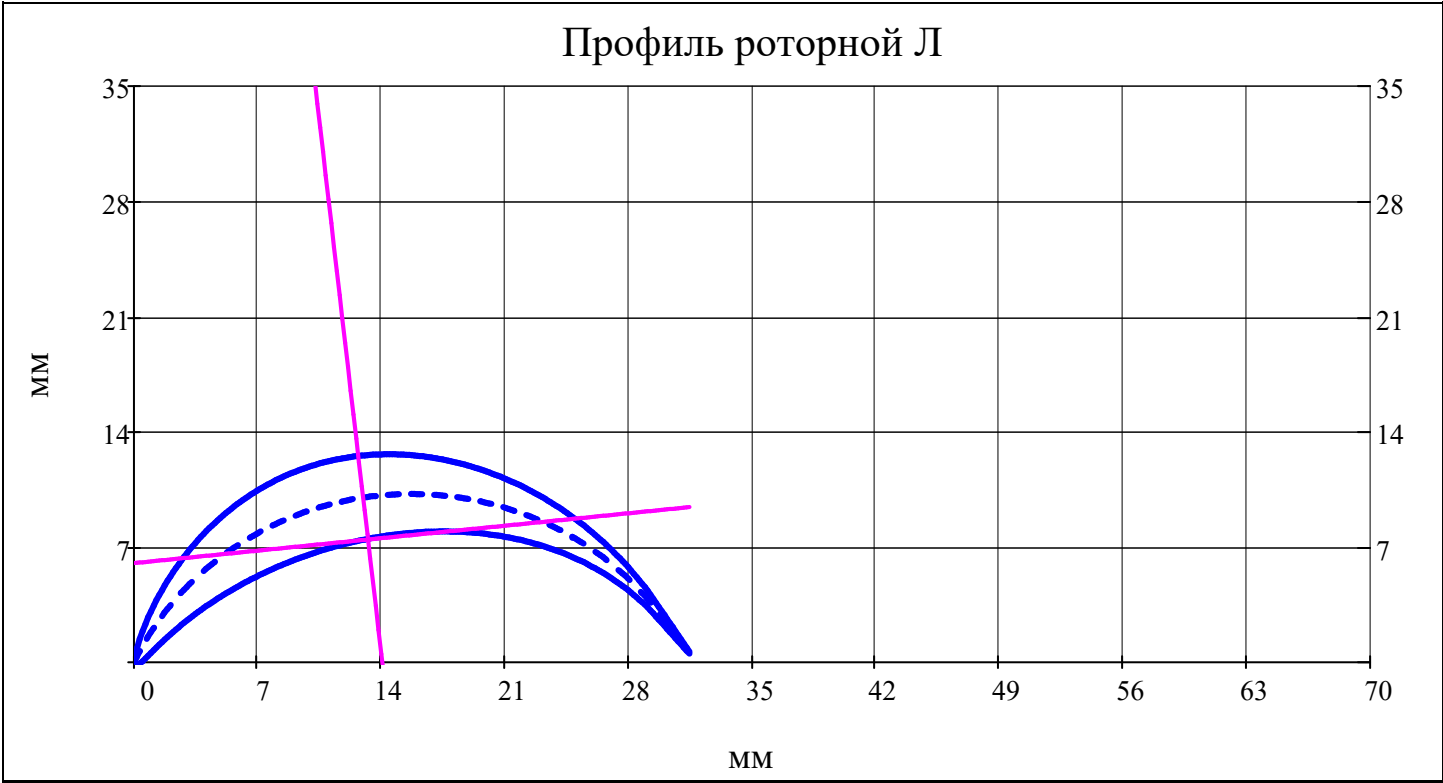
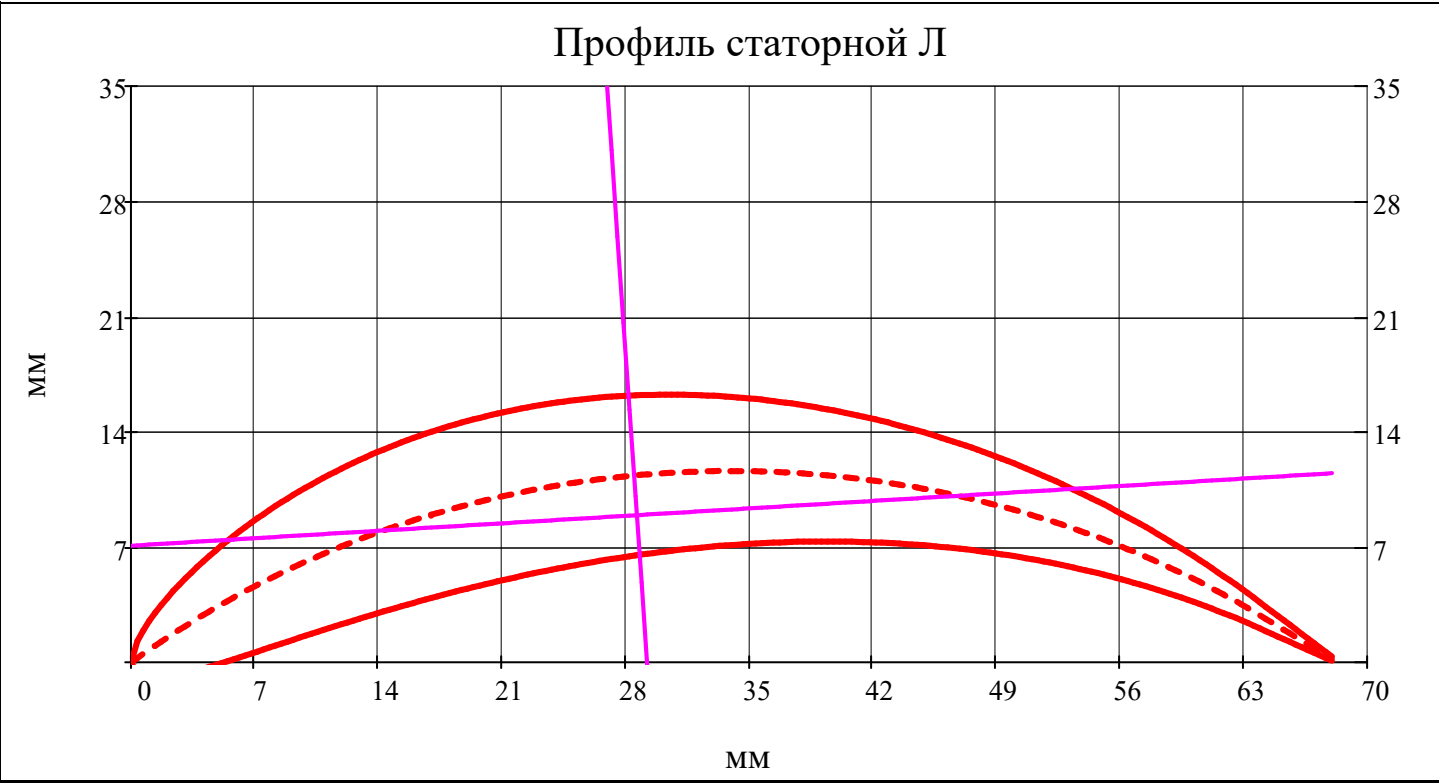
$r_w = 1$



$$r_w = av(N_r)$$



$r_w = N_r$





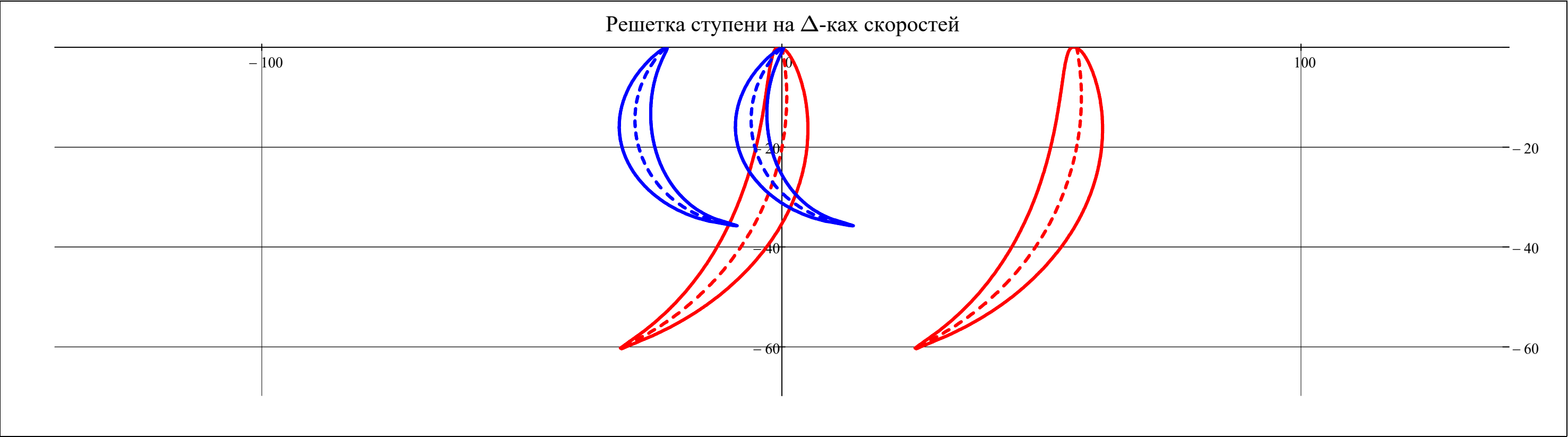
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = & \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases} = 1$$

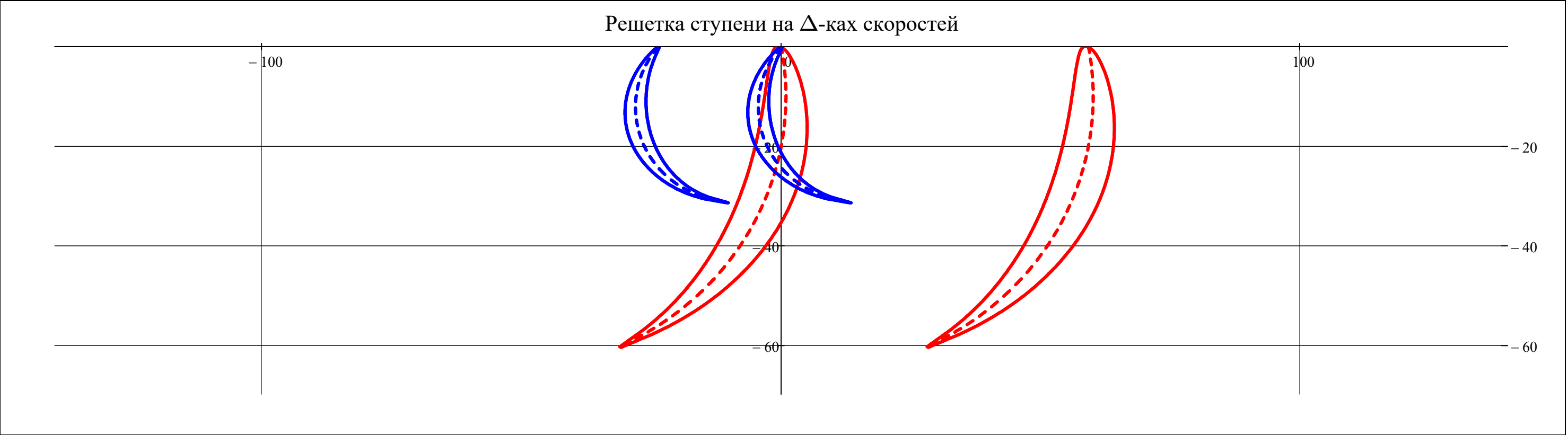
$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Построение плоских решеток профилей Л на треугольниках скоростей

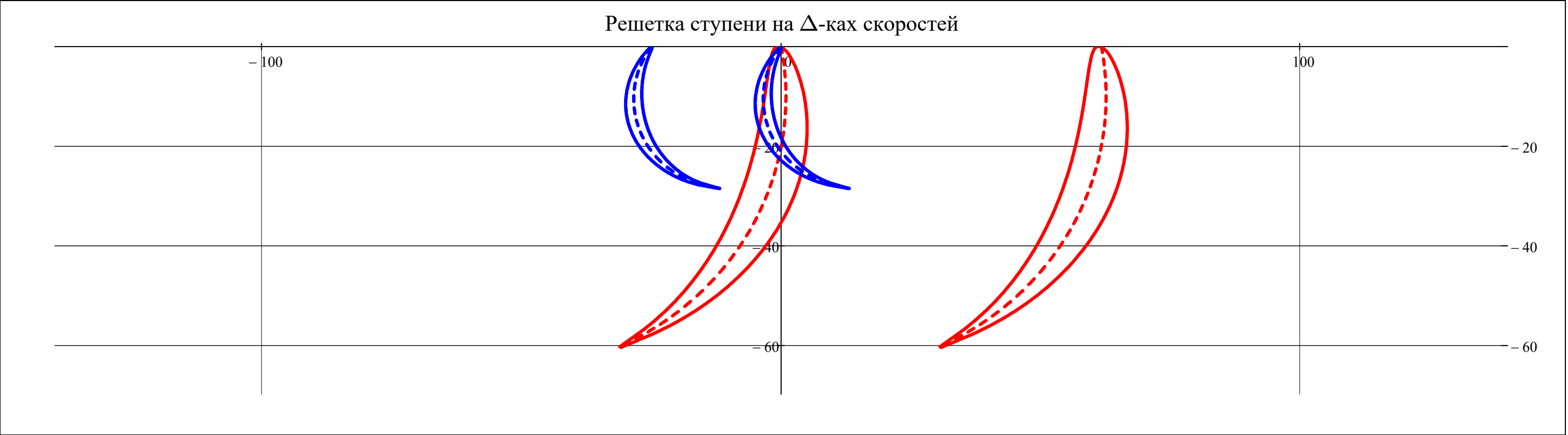
$$r_w = 1$$



$r_w = \text{av}(N_r)$



$r_w = N_r$



Построение плоских решеток профилей Л на треугольниках скоростей

Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 1$$

▼ Поперечная часть ступени

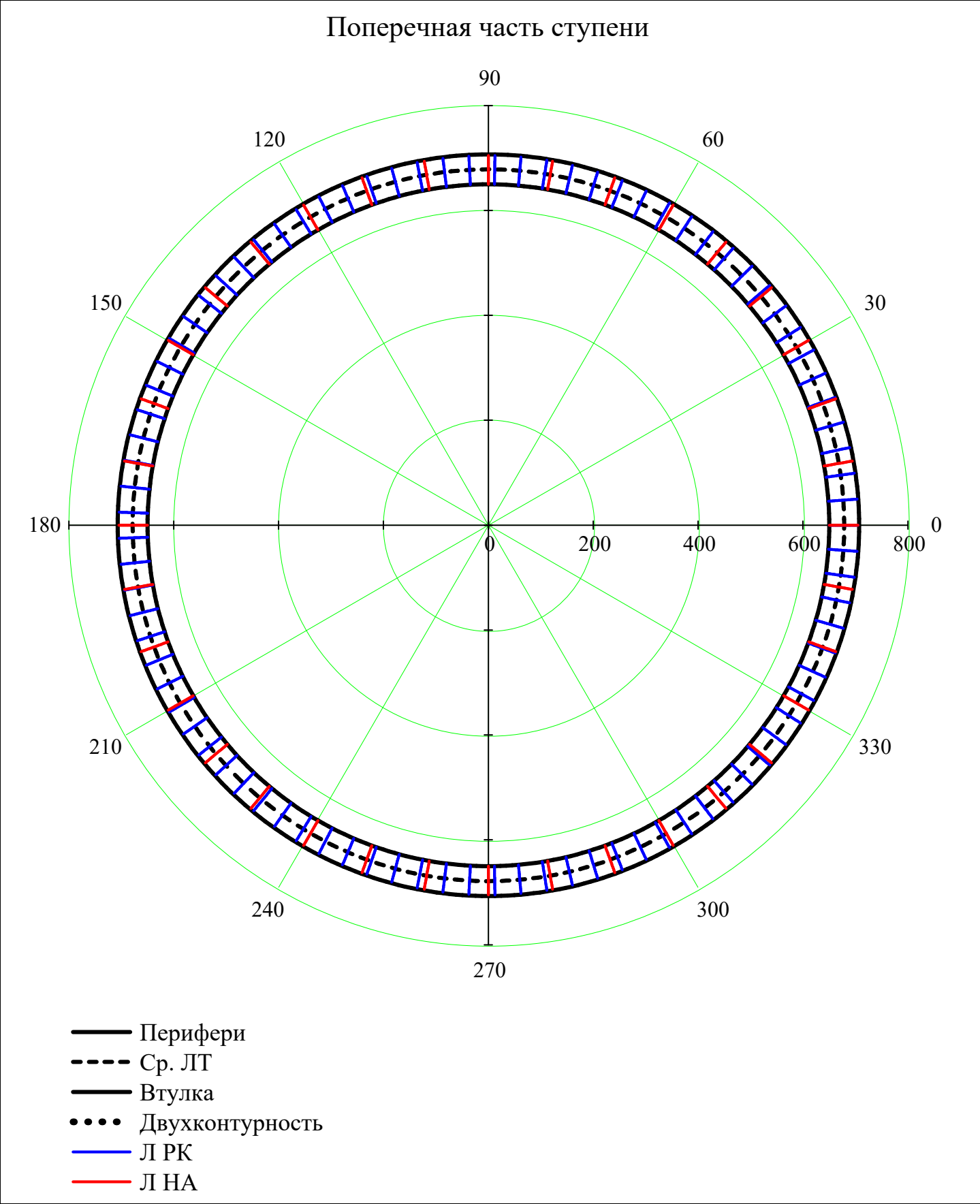
$$r_w = \min(D), \min(D) + \frac{\max(D) - \min(D)}{N_{\text{dis}}} \dots \max(D)$$

$$\begin{matrix} i_{\text{rotor}} = 1 \dots Z_{\text{rotor}_j} \\ i_{\text{stator}} = 1 \dots Z_{\text{stator}_j} \end{matrix}$$

$$\varphi = 0, \frac{2 \cdot \pi}{360} \dots 2 \cdot \pi$$

$\text{Л}_{\text{ПК}}(r,j) =$	$\frac{2 \cdot \pi}{Z_{\text{rotor}_j}} \quad \text{if } D_{\text{st}(j,1)}, 1 < r < D_{\text{st}(j,1)}, N_r$
	NaN otherwise

$\text{Л}_{\text{HA}}(r,j) =$	$\frac{2 \cdot \pi}{Z_{\text{stator}_j}} \quad \text{if } D_{\text{st}(j,2)}, 1 < r < D_{\text{st}(j,2)}, N_r$
	NaN otherwise



▲ Поперечная часть ступени

$$\begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } r \in \text{av}(N_r) \\ \quad \quad \text{for } \text{mode} \in 1..6 \\ \quad \quad \quad \left| \begin{array}{l} \nu_{0\text{изГ.stator}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{stator}_{i,r}}, J_{u\text{stator}_{i,r}}) \\ \nu_{0\text{изГ.rotor}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{rotor}_{i,r}}, J_{u\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \end{array} \right. \\ \quad \quad \quad \begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix} \end{array}$$

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\text{stack}\left(\nu_{0_{\text{изг.stator}}}, \nu_{0_{\text{изг.rotor}}}\right)^T =$$

	1	2	3	4	5	6	7	8
1	12599	5146						
2	78961	32254						
3	221116	90322						
4	433623	177128						
5	716516	292685						
6	1070076	437108						

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\text{stack}\left(\nu_{0_{\text{угл.stator}}}, \nu_{0_{\text{угл.rotor}}}\right)^T =$$

	1	2
1	8364	5507
2	25091	16521
3	41819	27535
4	58546	38548
5	75273	49562
6	92001	60576

$$\text{stack}\left(\nu_{0_{\text{угл.stator_bondage}}}, \nu_{0_{\text{угл.rotor_bondage}}}\right)^T =$$

	1	2
1	16727	11014
2	33455	22028
3	50182	33041
4	66910	44055
5	83637	55069
6	100364	66083

Расчетный узел: type = "turbine"

Объем бандажной полки (м³): $V_{\text{бп}} = 0$

Радиус положения ЦМ бандажной полки (м): $R_{\text{бп}} = 0$

► Расчет Л на прочность

$$\text{neutral_line}(\text{type}, \text{x}, \text{i}, \text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) \quad \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) \quad \text{if type = "stator"} \end{array} \right.$$

$$\text{epure}(\text{type}, \text{x}, \text{i}, \text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) \quad \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) \quad \text{if type = "stator"} \end{array} \right.$$

Наиболее удаленные точки от НЛ (мм):

$$u_{u_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -0.219 \\ \hline 2 & 0.395 \\ \hline 3 & -5.990 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 21.035 \\ \hline 2 & 18.836 \\ \hline 3 & -8.989 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{u_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -7.067 \\ \hline 2 & 8.162 \\ \hline 3 & 8.158 \\ \hline \end{array} \cdot 10^{-3}$$

$$u_{l_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -11.367 \\ \hline 2 & -25.854 \\ \hline 3 & -25.848 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{u_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 5.326 \\ \hline 2 & 4.047 \\ \hline 3 & 13.961 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{l_{\text{rotor}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -11.797 \\ \hline 2 & -10.076 \\ \hline 3 & -17.329 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{u_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29.147 \\ \hline 2 & 8.196 \\ \hline 3 & 8.200 \\ \hline \end{array} \cdot 10^{-3}$$

$$v_{l_{\text{stator}}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -38.703 \\ \hline 2 & -14.484 \\ \hline 3 & -14.496 \\ \hline \end{array} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \sigma_{\text{p_rotor}_{i,r}} & \sigma_{\text{n_rotor}_{i,r}} \\ \sigma_{\text{p_stator}_{i,r}} & \sigma_{\text{n_stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_u}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_u}_{\text{rotor}_{i,r}} & \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_l}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_l}_{\text{rotor}_{i,r}} \\ \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_u}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_u}_{\text{stator}_{i,r}} & \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_l}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_l}_{\text{stator}_{i,r}} \end{pmatrix} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix}
\end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \sigma_{\text{p_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{p_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T, z\right) \end{array} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix}
\end{pmatrix}$$

$$\sigma_{\text{p}_{\text{rotor}}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & -18.39 \\ \hline 2 & -8.85 \\ \hline 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{rotor}}}^{\text{T}} \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{rotor}}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 40.27 \\ \hline 2 & 21.79 \\ \hline 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{rotor}}}^{\text{T}} \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{p}_{\text{stator}}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ \hline 2 & 3.46 \\ \hline 3 & 13.82 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{stator}}}^{\text{T}} \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{stator}}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ \hline 2 & -7.05 \\ \hline 3 & -28.18 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{stator}}}^{\text{T}} \leq 70 \cdot 10^6 = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ \hline 2 & 1 \\ \hline 3 & 1 \\ \hline \end{array}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \sigma_{\text{rotor}_{i,r}} &= \sqrt{\left(\sigma_{\text{Zrotor}}(i, R_{\text{st}}(i, 2), r) + \max(\sigma_{\text{Protor}_{i,r}}, \sigma_{\text{nrotor}_{i,r}})\right)^2 + \tau_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)^2} \\ \sigma_{\text{stator}_{i,r}} &= \sqrt{\left(0 + \max(\sigma_{\text{Pstator}_{i,r}}, \sigma_{\text{nstator}_{i,r}})\right)^2 + \tau_{\text{stator}}(i, R_{\text{st}}(i, 2), r)^2} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \left| \begin{aligned} \sigma_{\text{rotor.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{stator.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix}$$

$$\sigma_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 161.45 \\ 2 & 101.66 \\ 3 & 0.00 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.00 \\ 2 & 5.60 \\ 3 & 16.39 \\ \hline \end{array} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \text{safety}_{\text{rotor}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}_i}}{\sigma_{\text{rotor}_{i,r}}} & \text{if } \sigma_{\text{rotor}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \\ \text{safety}_{\text{stator}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}_i}}{\sigma_{\text{stator}_{i,r}}} & \text{if } \sigma_{\text{stator}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix}$$

$$\text{safety}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1.27 \\ 2 & 2.02 \\ 3 & 000000000000000000000000000000 \\ \hline \end{array}$$

$$\text{safety}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 000000000000000000000000000000 \\ 2 & 36.61 \\ 3 & 12.51 \\ \hline \end{array}$$

$$\text{safety}_{\text{rotor}}^T \geq \text{safety} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0 \\ 2 & 1 \\ 3 & 1 \\ \hline \end{array}$$

$$\text{safety}_{\text{stator}}^T \geq \text{safety} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ \hline \end{array}$$

Рассматриваемая ступень:

$$j_w = \begin{cases} j = \begin{cases} 1 & \text{if type = "compressor"} \\ Z & \text{if type = "turbine"} \end{cases} \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases} = 1$$

$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

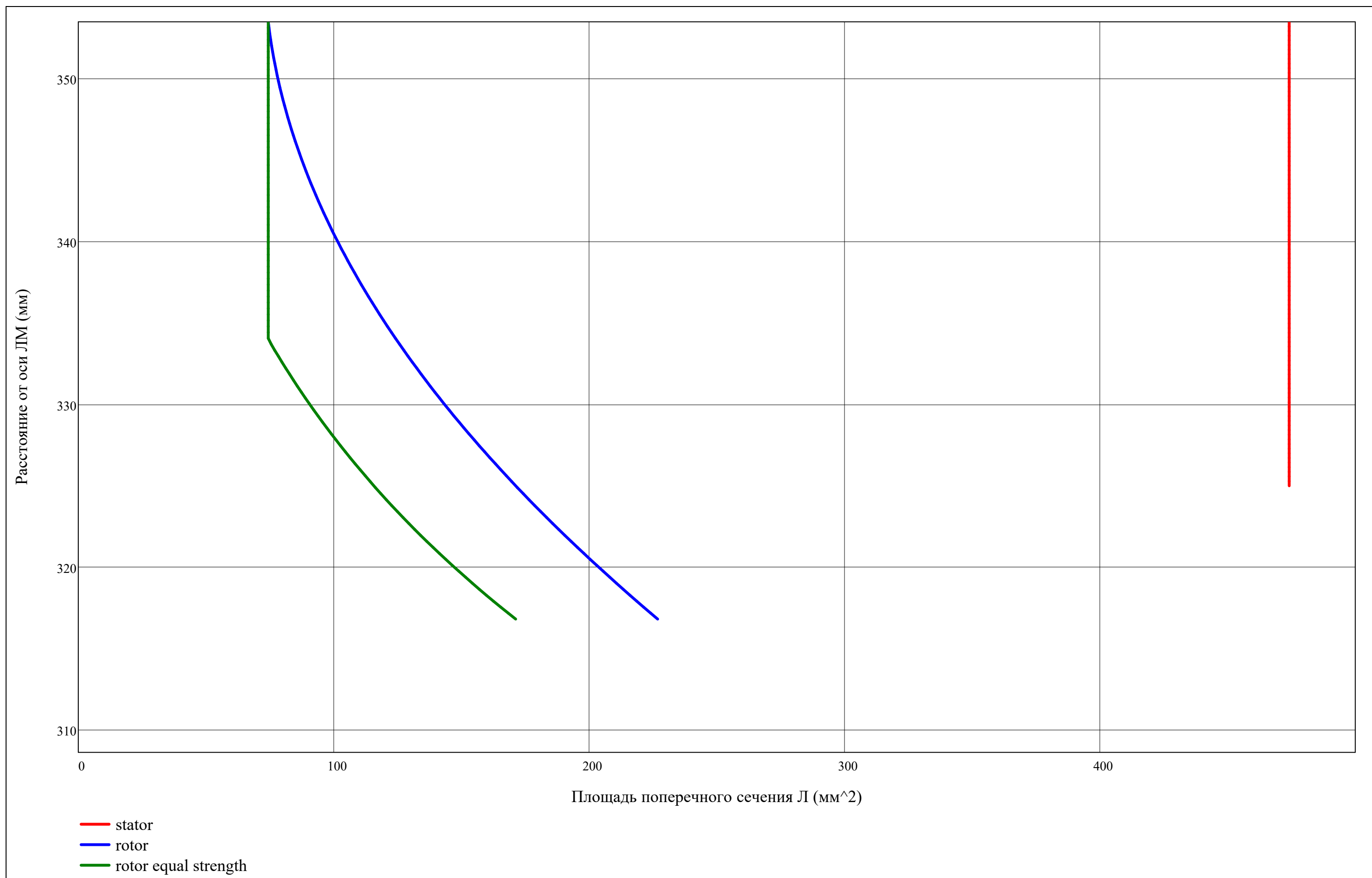
$$R_j = \text{submatrix}\left(R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 325.0 & 339.2 & 353.5 \\ \hline 2 & 325.0 & 339.2 & 353.5 \\ \hline 3 & 308.6 & 331.0 & 353.5 \\ \hline \end{array} \cdot 10^{-3}$$

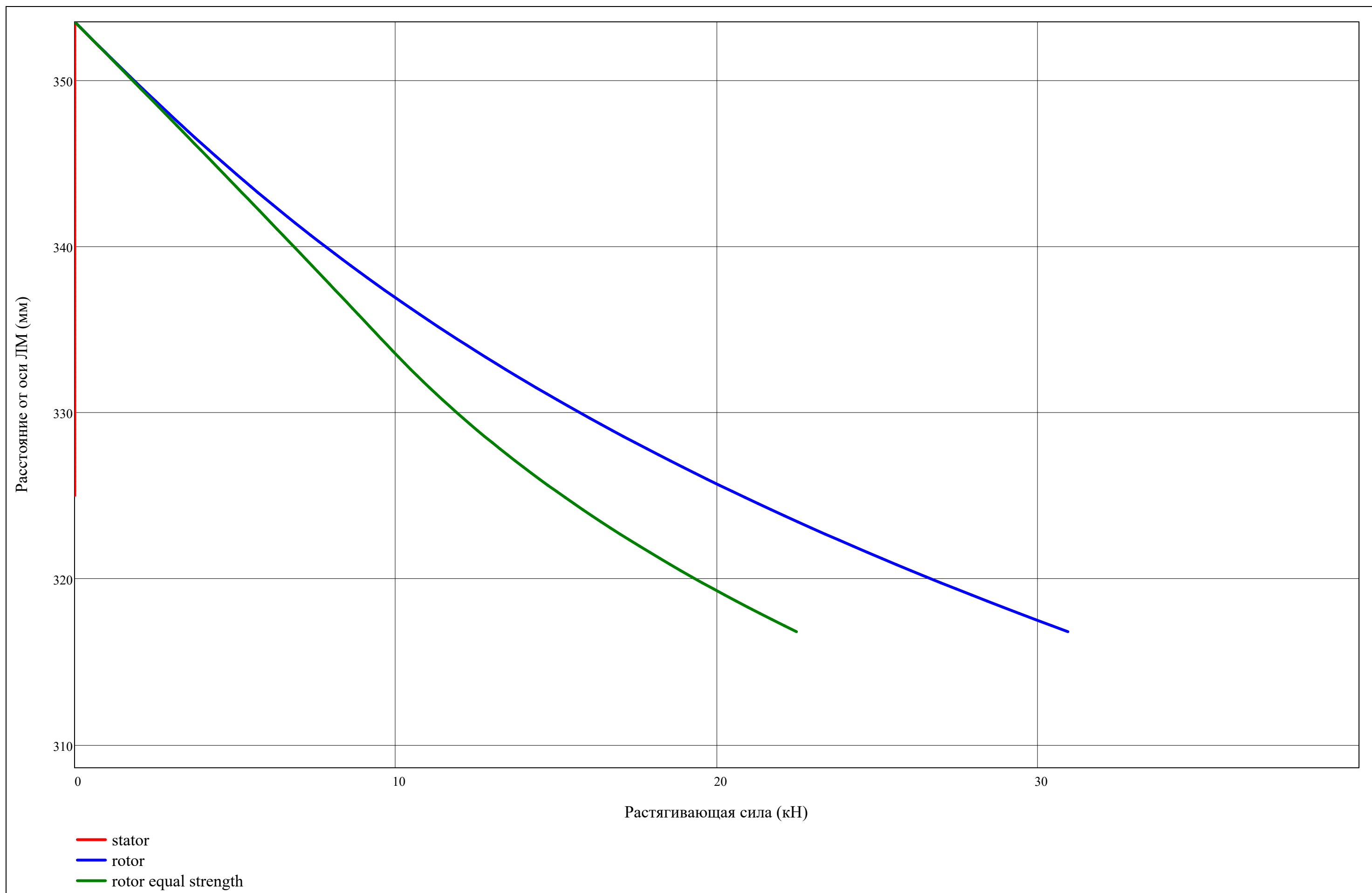
Дискретизация по высоте Л:

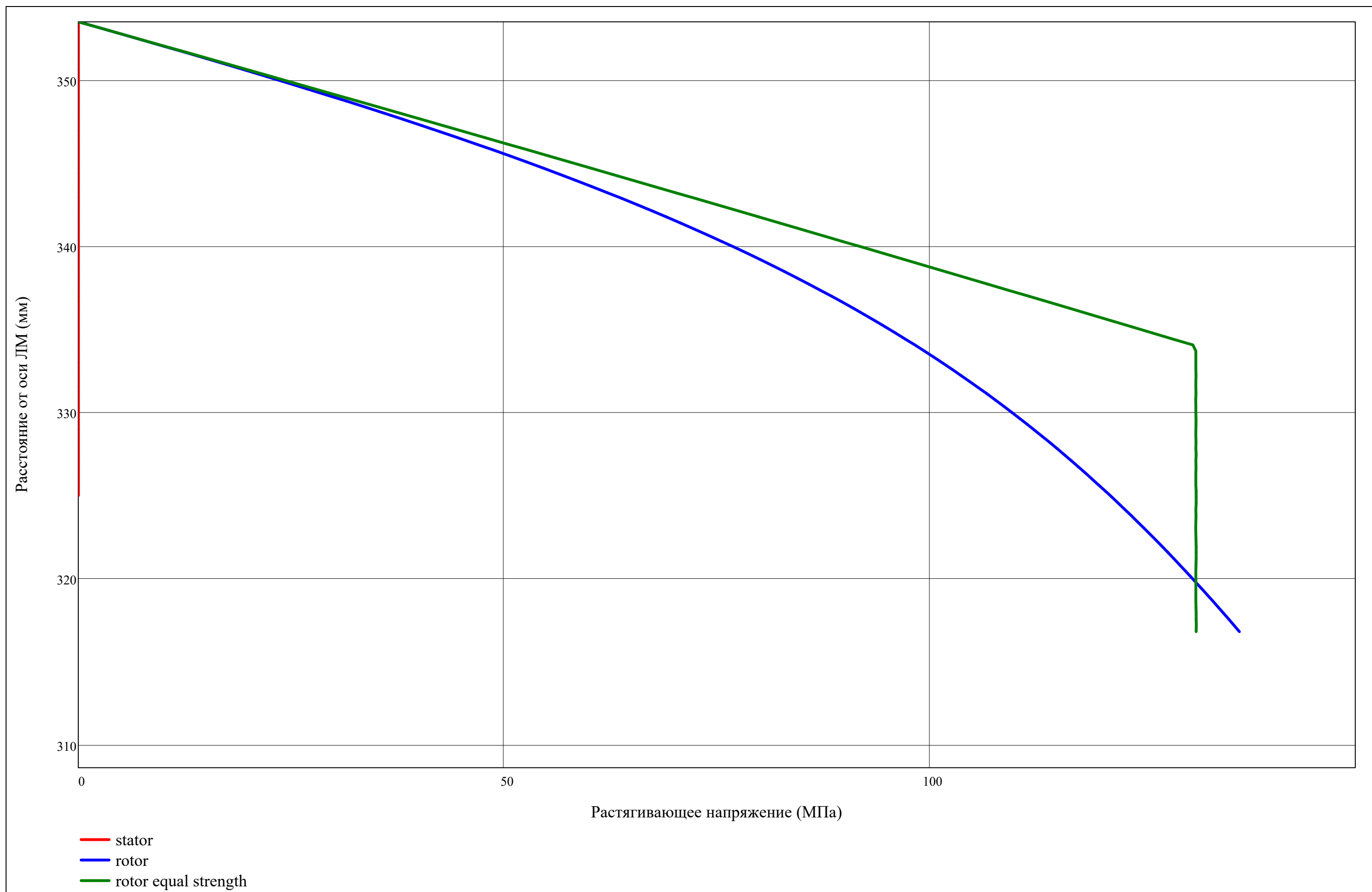
$$z = \min(R_j), \min(R_j) + \frac{\max(R_j) - \min(R_j)}{100} .. \max(R_j)$$

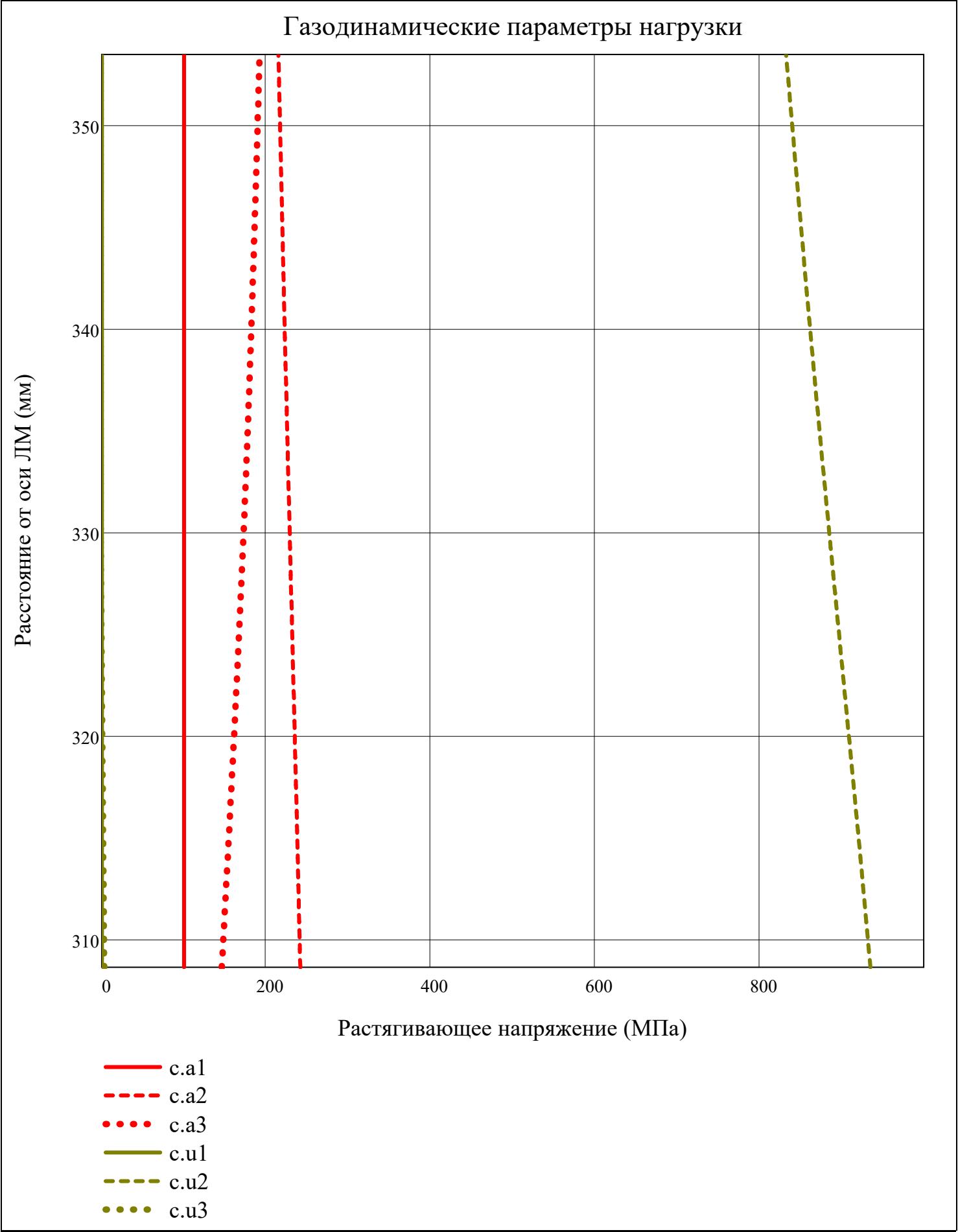
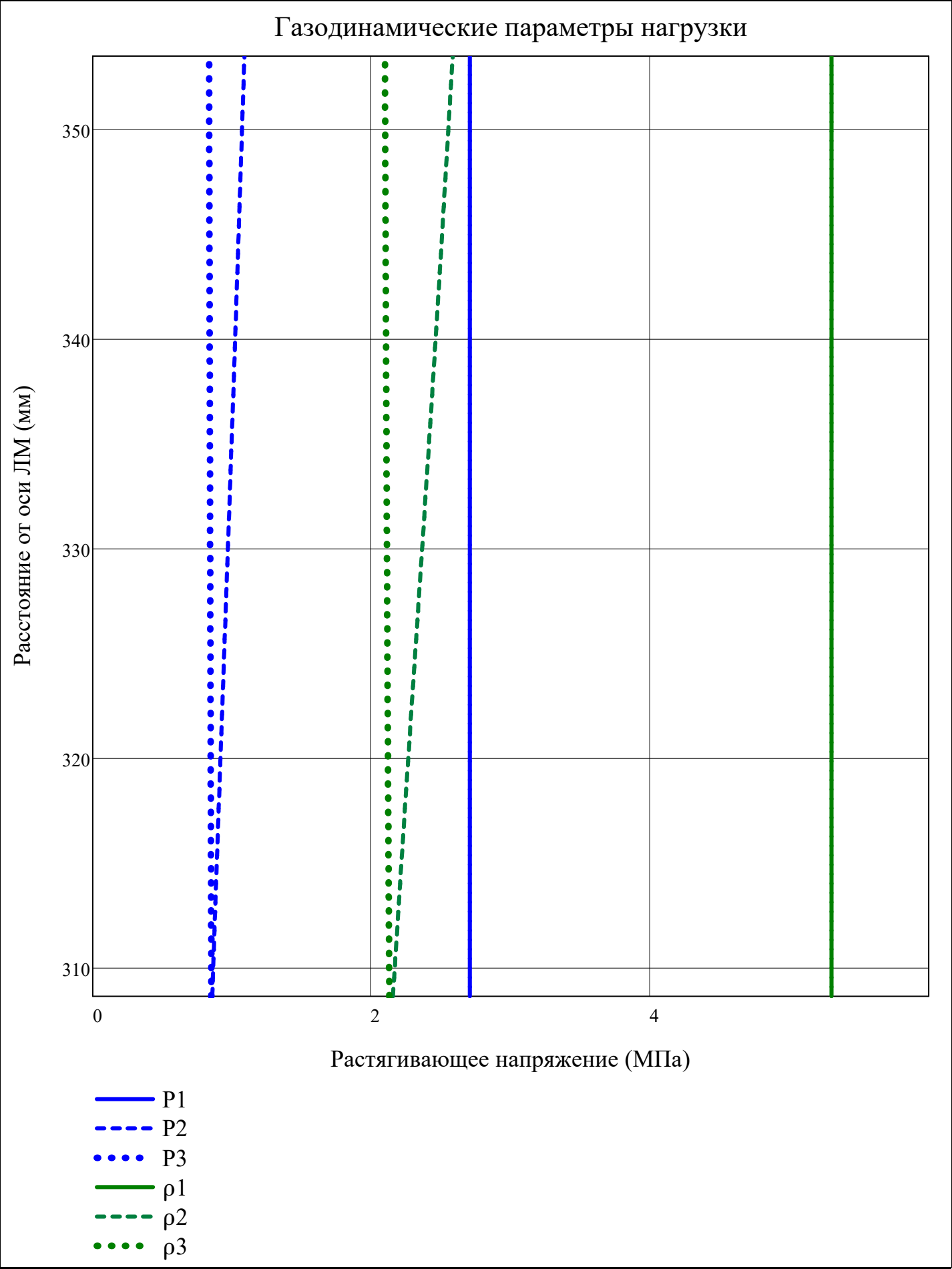
$$z_{\text{rotor}} = \begin{cases} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) & \text{if type = "compressor"} \\ \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) & \text{if type = "turbine"} \end{cases}$$

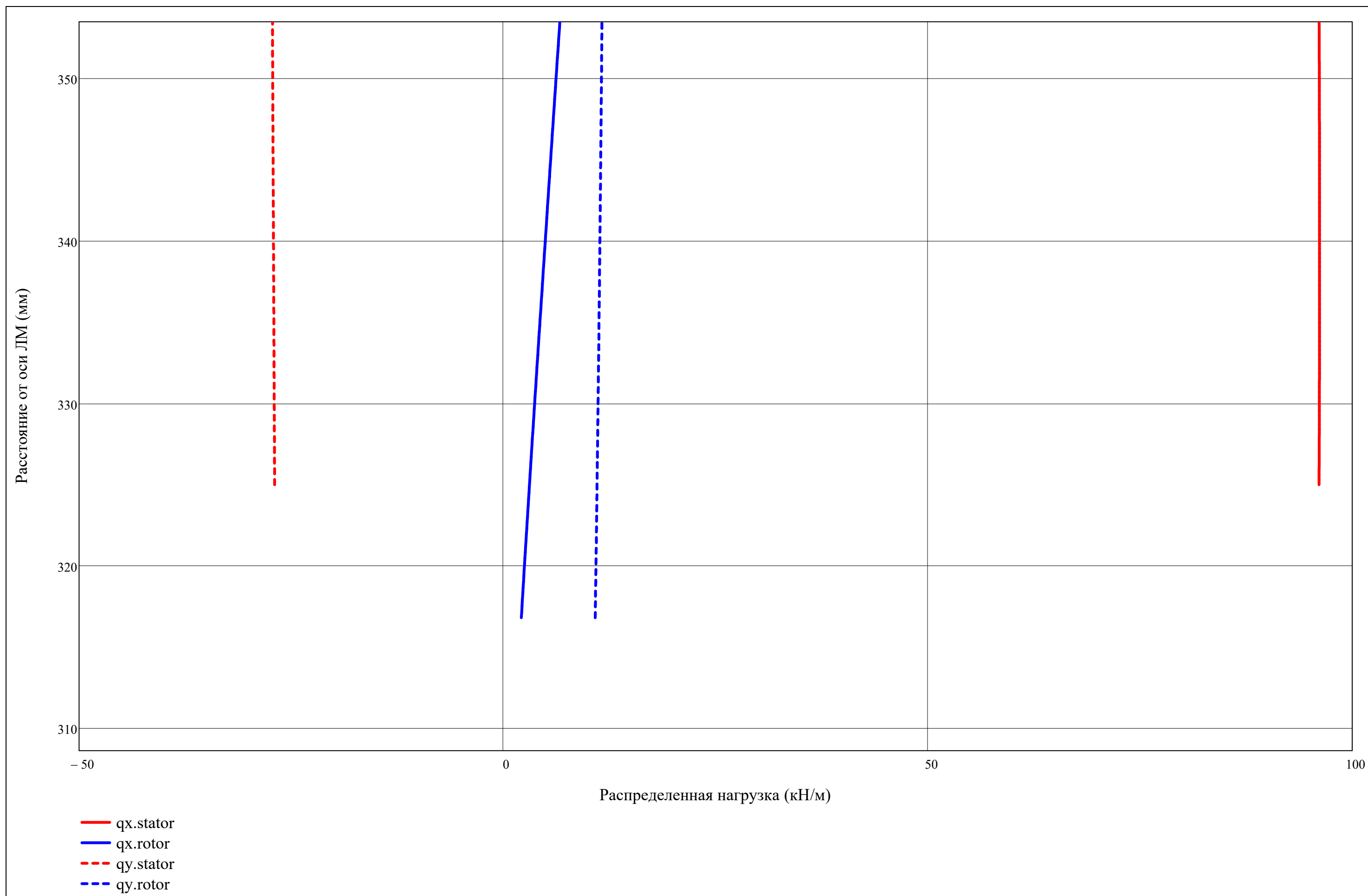
$$z_{\text{stator}} = \begin{cases} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) & \text{if type = "compressor"} \\ \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) & \text{if type = "turbine"} \end{cases}$$

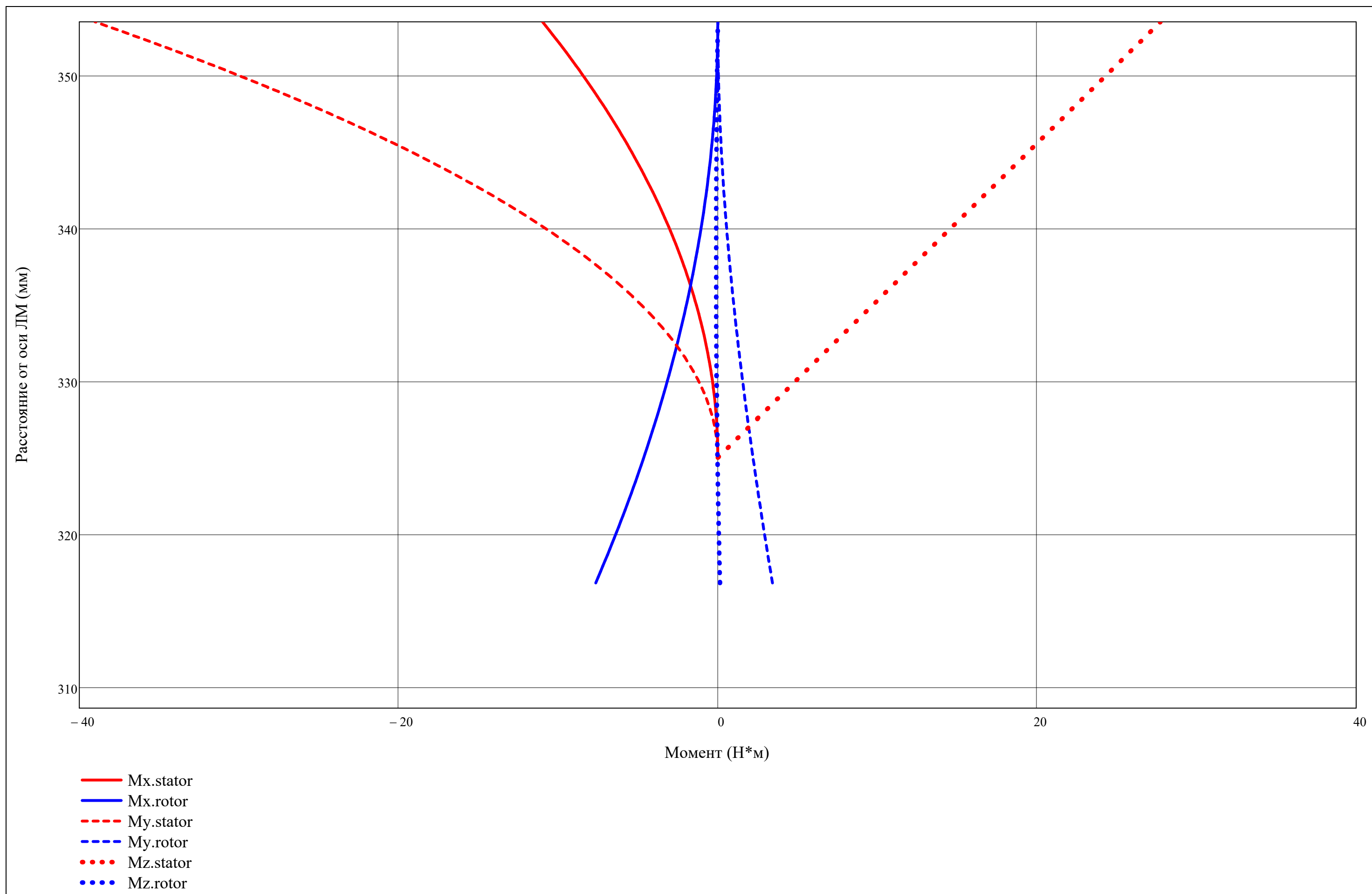


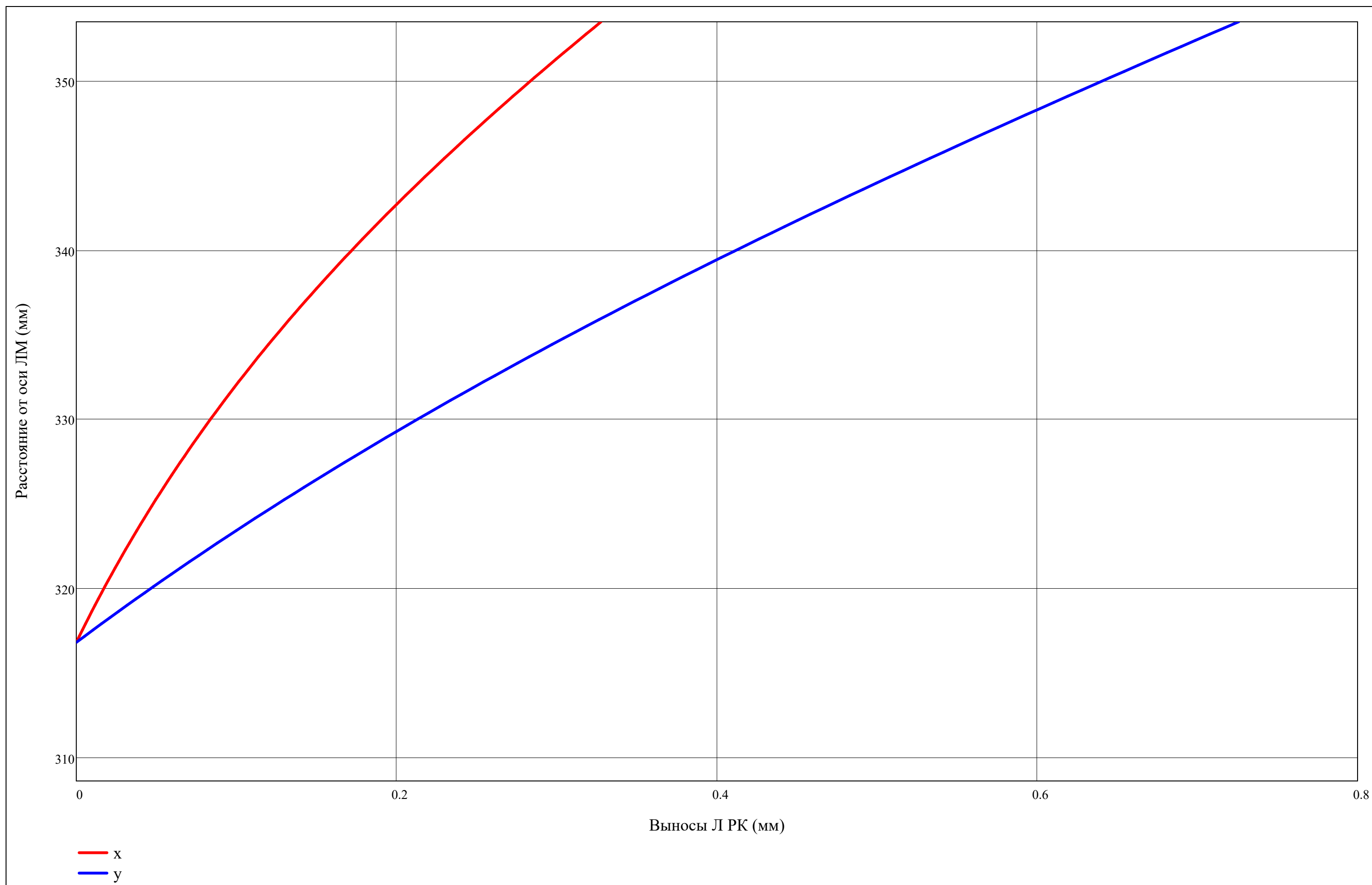


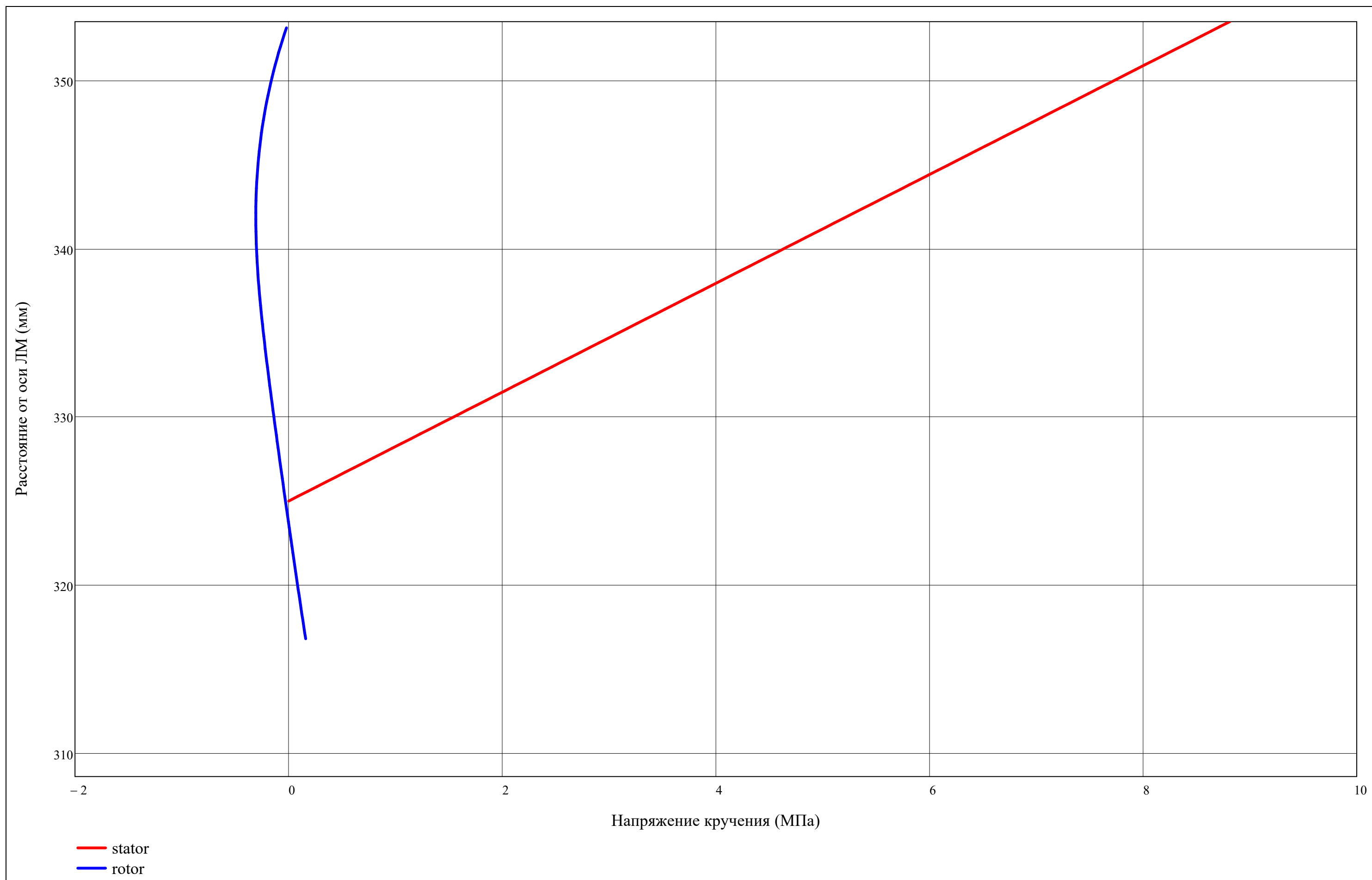


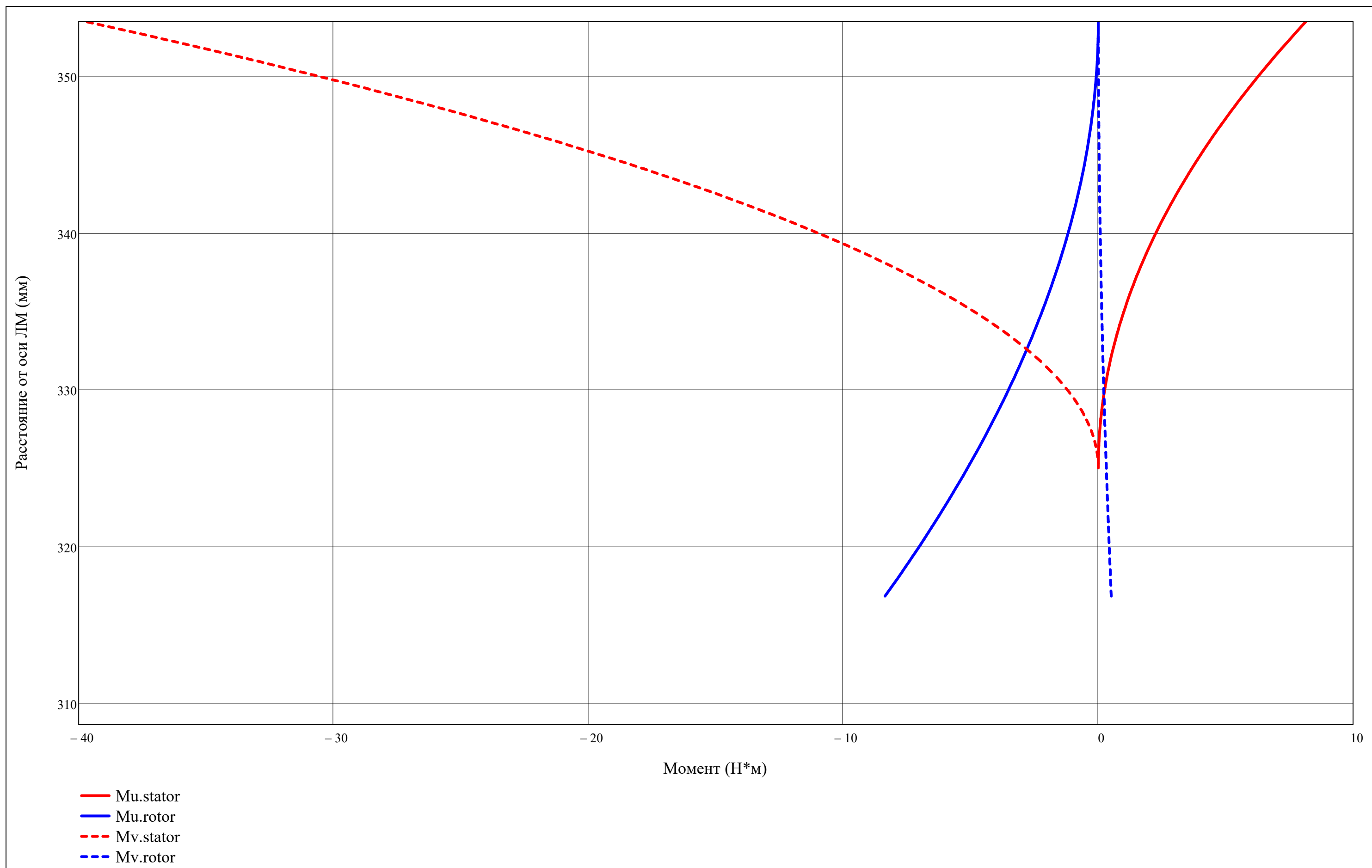


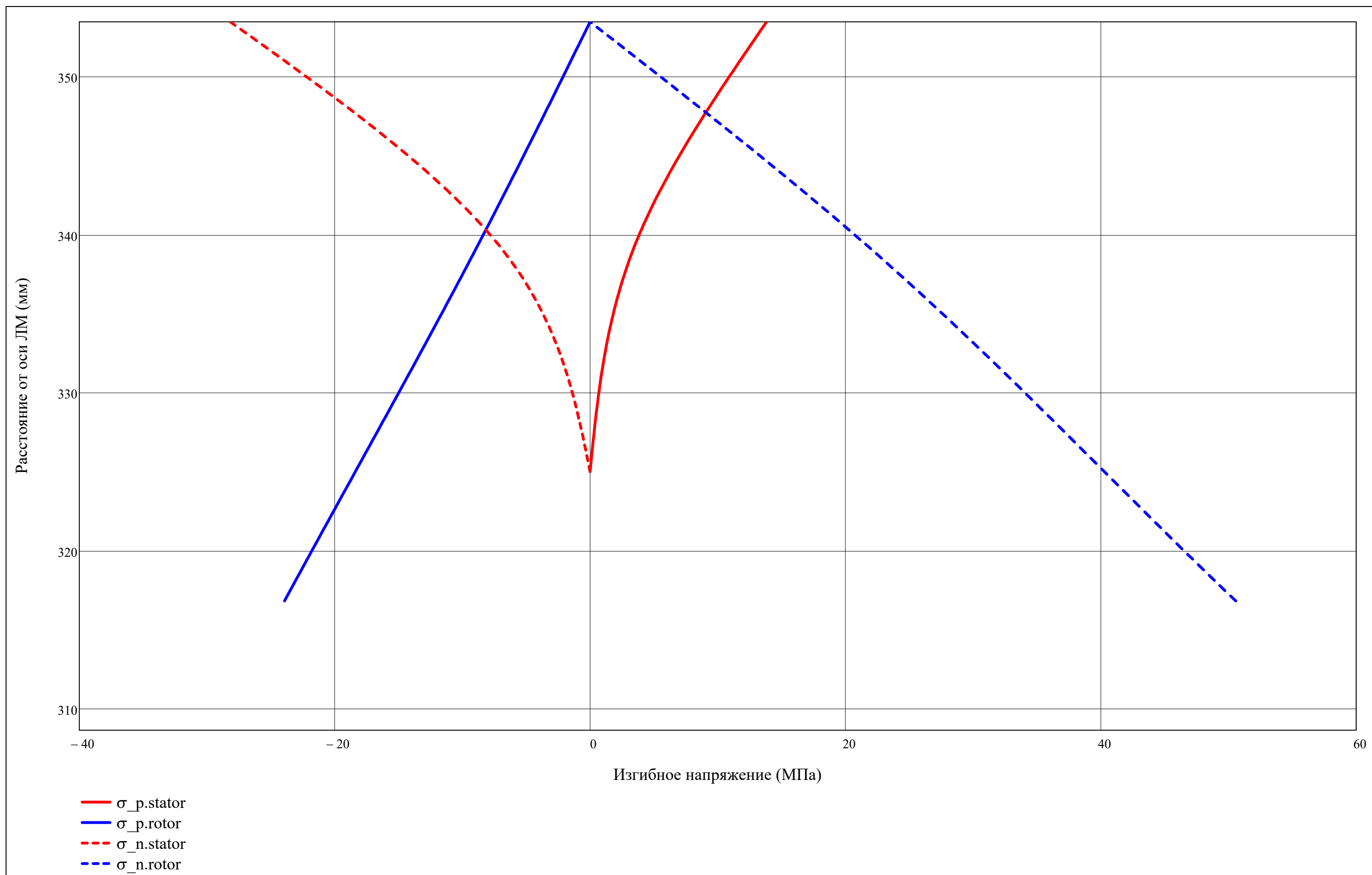


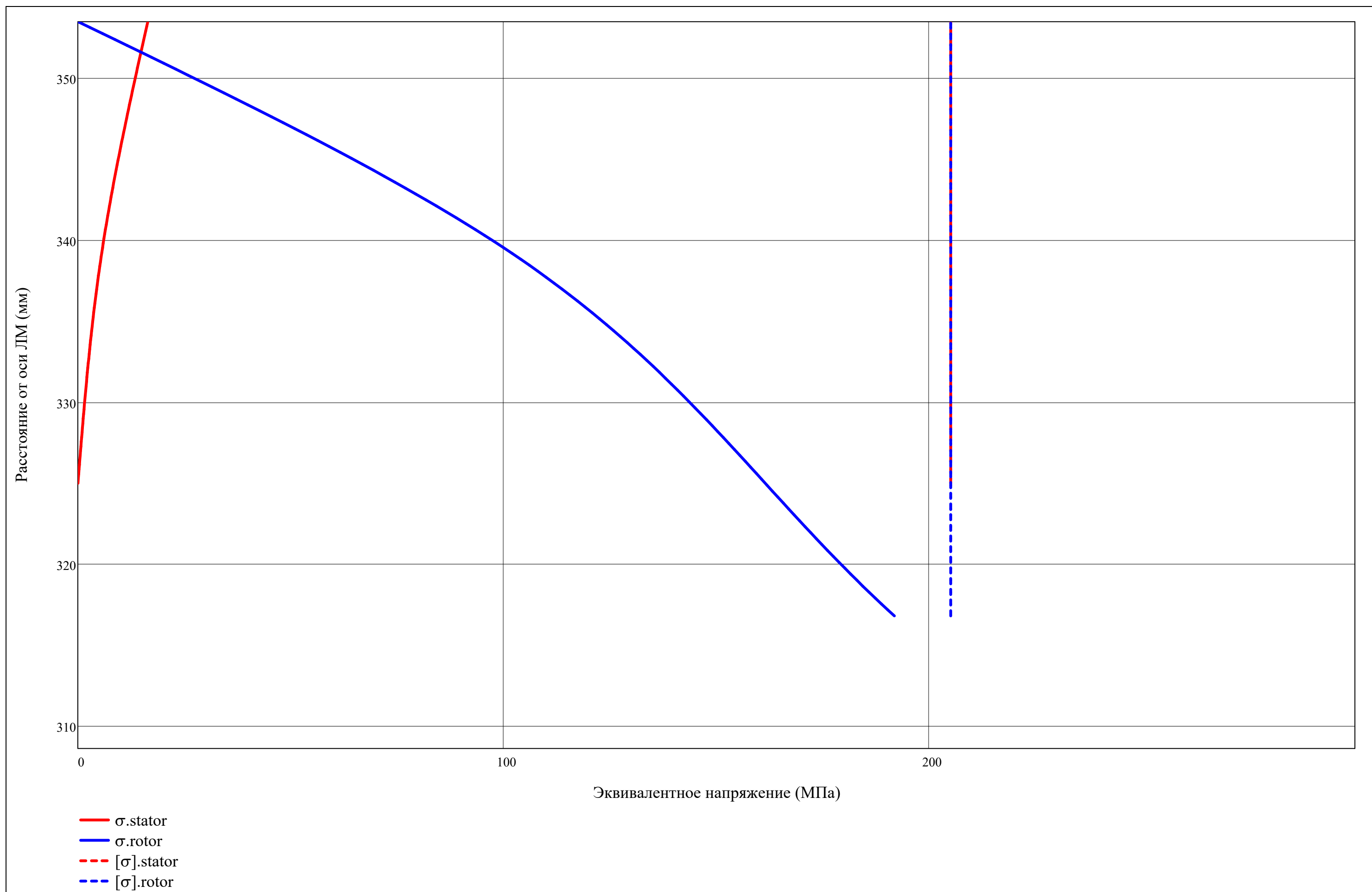






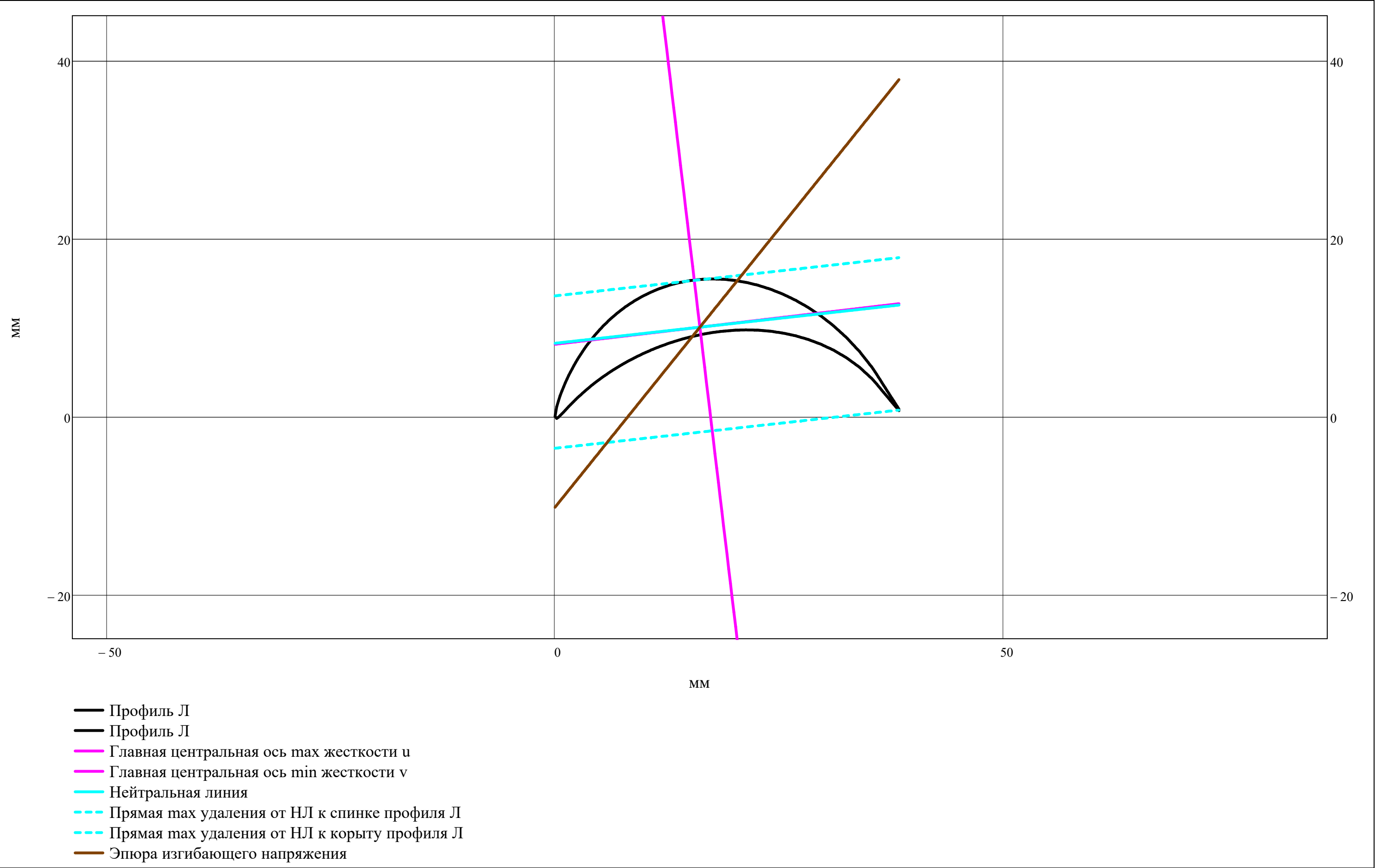






$$\begin{pmatrix} \text{blade} \\ \text{r} \end{pmatrix} = \begin{pmatrix} \text{"rotor"} \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{v_p} \\ \text{v_n} \end{pmatrix} = \begin{cases} \begin{pmatrix} \text{v_u}_{\text{rotor}_{\text{j},\text{r}}} \\ \text{v_l}_{\text{rotor}_{\text{j},\text{r}}} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} \text{v_u}_{\text{stator}_{\text{j},\text{r}}} \\ \text{v_l}_{\text{stator}_{\text{j},\text{r}}} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 5.326 \\ \hline 2 & -11.797 \\ \hline \end{array} \cdot 10^{-3} \qquad \begin{pmatrix} \text{x0} \\ \text{y0} \end{pmatrix} = \begin{cases} \begin{pmatrix} \text{x0}_{\text{rotor}_{\text{j},\text{r}}} \\ \text{y0}_{\text{rotor}_{\text{j},\text{r}}} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} \text{x0}_{\text{stator}_{\text{j},\text{r}}} \\ \text{y0}_{\text{stator}_{\text{j},\text{r}}} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 16.161 \\ \hline 2 & 10.014 \\ \hline \end{array} \cdot 10^{-3} \qquad \text{chord} = \begin{cases} \text{chord}_{\text{rotor}_{\text{j},\text{r}}} & \text{if blade = "rotor"} \\ \text{chord}_{\text{stator}_{\text{j},\text{r}}} & \text{if blade = "stator"} \end{cases} = 38.4 \cdot 10^{-3}$$



Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{-u_{\text{rotor}_{j,r}}} & v_{-u_{\text{rotor}_{j,r}}} \\ u_{-l_{\text{rotor}_{j,r}}} & v_{-l_{\text{rotor}_{j,r}}} \\ u_{-u_{\text{stator}_{j,r}}} & v_{-u_{\text{stator}_{j,r}}} \\ u_{-l_{\text{stator}_{j,r}}} & v_{-l_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \tr \end{table} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{-p_{\text{rotor}_{j,r}}} & \sigma_{-p_{\text{stator}_{j,r}}} \\ \sigma_{-n_{\text{rotor}_{j,r}}} & \sigma_{-n_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{stator}_{j,r}} \\ \text{safety}_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \tr \end{table}$$

Запас по температуре (K):

$\Delta T_{\text{safety}} = 0$

Выбранный материал Д:

$\text{material_disk}_i = \begin{cases} \text{"ВЖ175"} & \text{if turbine = "ТВД"} \\ \text{"ЭП742"} & \text{if turbine = "ТНД"} \end{cases}$

Плотность материала Д (кг/м^3):

$\rho_{\text{disk}_i} = \begin{cases} 8266 & \text{if material_disk}_i = \text{"ВЖ175"} \\ 8320 & \text{if material_disk}_i = \text{"ЭП742"} \\ 8393 & \text{if material_disk}_i = \text{"ЖС-6К"} \\ 7900 & \text{if material_disk}_i = \text{"BT41"} \\ 4500 & \text{if material_disk}_i = \text{"BT25"} \\ 4570 & \text{if material_disk}_i = \text{"BT23"} \\ 4510 & \text{if material_disk}_i = \text{"BT9"} \\ 4430 & \text{if material_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

Предел длительной прочности Д (Па):

$\sigma_{\text{disk_long}_i} = 10^6 \cdot \begin{cases} 620 & \text{if material_disk}_i = \text{"ВЖ175"} \\ 680 & \text{if material_disk}_i = \text{"ЭП742"} \\ 125 & \text{if material_disk}_i = \text{"ЖС-6К"} \\ 123 & \text{if material_disk}_i = \text{"BT41"} \\ 150 & \text{if material_disk}_i = \text{"BT25"} \\ 230 & \text{if material_disk}_i = \text{"BT23"} \\ 200 & \text{if material_disk}_i = \text{"BT9"} \\ 210 & \text{if material_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

$\text{material_disk}^T =$

	1
1	"ВЖ175"

$\rho_{\text{disk}}^T =$

	1
1	8266

$\sigma_{\text{disk_long}}^T =$

	1
1	620

$\cdot 10^6$

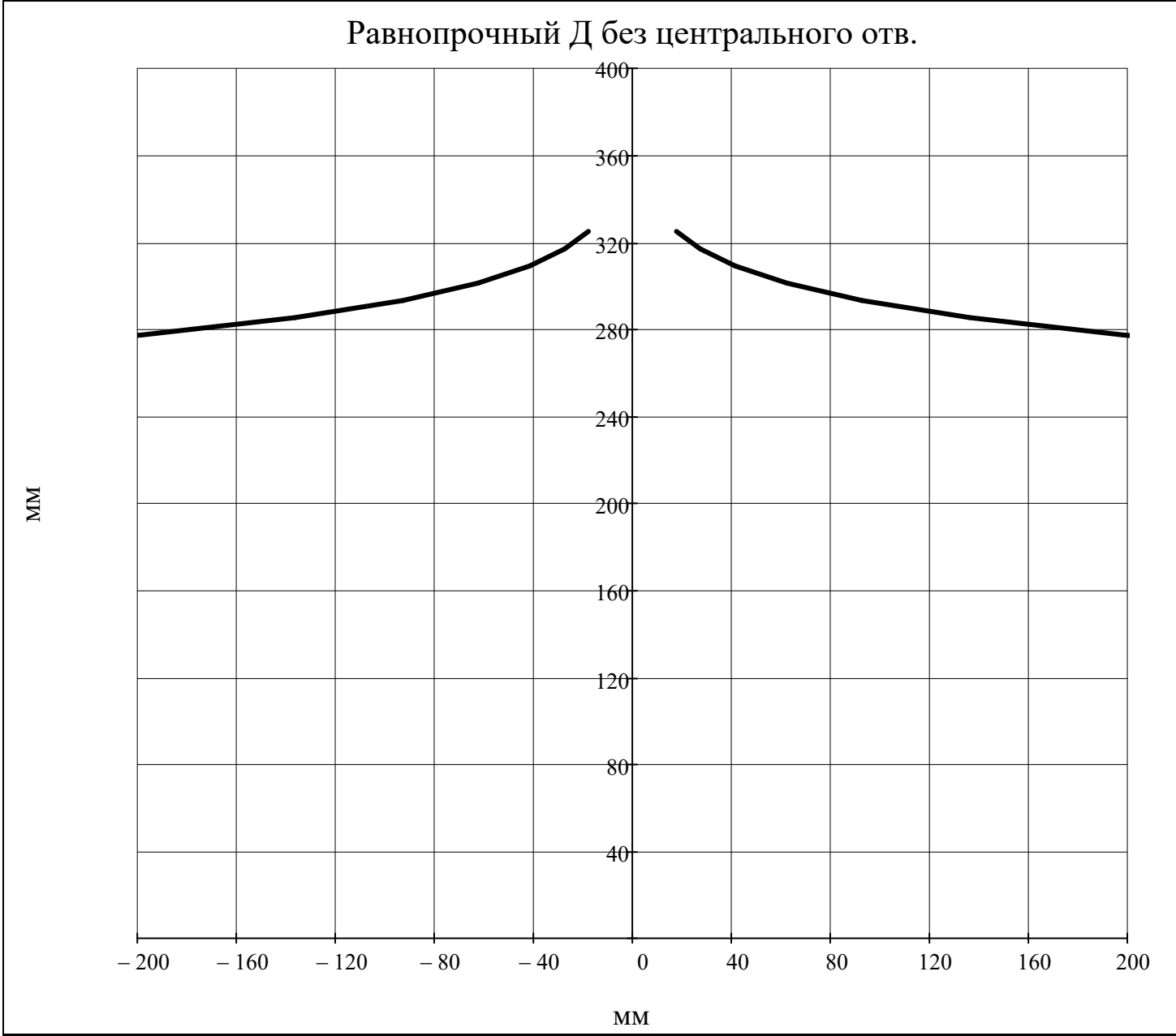
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & = 1 \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases}$$

Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{cases} \left(\text{chord}_{\text{rotor}_i, \text{ORIGIN}} \cdot \sin\left(v_{\text{rotor}_i, \text{ORIGIN}}\right) \right) \cdot e^{\frac{\rho_{\text{disk}_i} \cdot \omega^2}{2} \cdot \frac{1}{\sigma_{z_{\text{rotor}}(i, R_{\text{st}(i,2), \text{ORIGIN}})}} \cdot \left[\left(R_{\text{st}(i,2), \text{ORIGIN}} \right)^2 - z^2 \right]} & \text{if } z \leq R_{\text{st}(i,2), \text{ORIGIN}} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$z = 0, \frac{R_{\text{st}(j,2), \text{ORIGIN}}}{N_{\text{dis}}} .. R_{\text{st}(j,2), \text{ORIGIN}}$$



Профилирование равнопрочного Д без центрального отв.

$$type = \begin{cases} type = "stator" & \\ type = \begin{cases} "Нет такого типа!" & \text{if } type \neq "stator" \wedge type \neq "rotor" \\ type & \text{otherwise} \end{cases} & \end{cases} = "stator"$$

Рассматриваемая ступень:

$$j = \begin{cases} j = 1 & \\ j = \begin{cases} "Такой ступени не существует!" & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 1$$







$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 926.13 \\ 145.91 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 231.49 \\ 145.88 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 520.18 \\ 450.31 \\ 503.61 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.47 \\ 88.92 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 510.48 \\ 510.48 \\ 484.75 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 11.08 \\ 149.07 \\ 16.84 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 75.53 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 132.23 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 891.55 \\ 173.52 \end{pmatrix}$$

$$\begin{pmatrix} c_{ast(j,1),r} \\ c_{ast(j,2),r} \\ c_{ast(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 222.84 \\ 173.52 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 542.17 \\ 398.52 \\ 549.83 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.47 \\ 90.57 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 532.86 \\ 532.86 \\ 520.00 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 10.63 \\ 146.00 \\ 18.40 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 75.53 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 127.6 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 859.60 \\ 191.93 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 100.00 \\ 214.86 \\ 191.85 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 564.18 \\ 350.62 \\ 592.65 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 14.47 \\ 91.64 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 555.25 \\ 555.25 \\ 555.25 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 10.21 \\ 142.21 \\ 18.89 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 75.53 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 123.32 \cdot ^\circ$$

0000000.0
1.270