







Исходные данные

Коэф. запаса: safety = 1.3

Горючее: Fuel = "Керосин" turbine = "ТНД"

Высота движения (м): H\_v = 0

Массовый расход перед Т (кг/с):  
Массовый расход утечек Т (кг/с):  
Массовый расход на охл Т (кг/с):

G<sub>Г</sub>

G<sub>leak</sub>

G<sub>cooling</sub>

=

32.30

106.96·10<sup>-3</sup>

3240.8·10<sup>-3</sup>

if turbine = "ТВД"

=

|   |       |
|---|-------|
|   | 1     |
| 1 | 35.43 |
| 2 | 0.04  |
| 3 | 0.81  |

35.43

35.65·10<sup>-3</sup>

810.2·10<sup>-3</sup>

if turbine = "ТНД"

Мощность Т (Вт):

N<sub>Т</sub> = 10<sup>6</sup> ·

14.893 if turbine = "ТВД"

15.181 if turbine = "ТНД"

= 15.181·10<sup>6</sup>

Полное давление перед Т (Па):

P\*<sub>Г</sub> = 10<sup>3</sup> ·

2731.8 if turbine = "ТВД"

927.5 if turbine = "ТНД"

= 927.5·10<sup>3</sup>

Полная температура перед Т (К):

T\*<sub>Г</sub> =

1773 if turbine = "ТВД"

1368.9 if turbine = "ТНД"

= 1368.9

Коэф. избытка воздуха в Т:

α<sub>ох</sub> =

2.267 if turbine = "ТВД"

2.493 if turbine = "ТНД"

= 2.493

Полное давление отбора охлаждающего воздуха (К):

P\*<sub>cooling</sub> = 10<sup>3</sup> ·

2845.6 if turbine = "ТВД"

319.4 if turbine = "ТНД"

= 319.4·10<sup>3</sup>

Полная температура отбора охлаждающего воздуха (К):

T\*<sub>cooling</sub> =

806.9 if turbine = "ТВД"

418.2 if turbine = "ТНД"

= 418.2

Коэф. сохранения полного давления охлаждения:

σ<sub>cooling</sub> = 0.97

Подогрев охл. от КС [К]:

ΔТ<sub>охл.подогрев</sub> = 40

Газовая постоянная (Дж/кг/К):

R<sub>газ</sub>(α<sub>ох</sub>, Fuel) = 288.5

Допустимая температура Л (К):

Т<sub>Л,доп</sub> = 1373

4

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

[1, с.15]

$80 \leq c_T \leq 400 = 1$

Лопаточный КПД Т:

$\eta_{Л} = 88\%$

$88\% \leq \eta_{Л} \leq 95\% = 1$

Угол входа в Т:

$\alpha_T = 90.^{\circ}$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_T \\ c_T \end{pmatrix} = \begin{cases} \begin{pmatrix} 100 \\ 180 \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 180 \\ 260 \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 180.0 \\ \hline 2 & 260.0 \\ \hline \end{array}$$

$$u_T = \begin{cases} 520 & \text{if turbine = "ТВД"} \\ 260 & \text{if turbine = "ТНД"} \end{cases} = 260.0$$

$z = \text{ORIGIN}..N_T$

Полное давление отбора охлаждающего воздуха (К):  $P_{cooling}^* = P_{cooling}^* \cdot \sigma_{cooling} = 309.8 \cdot 10^3$

Полная температура отбора охлаждающего воздуха (К):  $T_{cooling}^* = T_{cooling}^* + \Delta T_{\text{охл.подогрев}} = 458.2$

Массовый расход перед Т (кг/с):  $G_{T_{in}} = G_T - G_{leak} = 35.4$

Массовый расход после Т (кг/с):  $G_T = G_T + G_{cooling} = 36.2$

Удельная работа Т (Дж/кг):  $L_T^* = \frac{N_T}{\text{mean}(G_T, G_T)} = 424.1 \cdot 10^3$

$L_T^* \leq 550 \cdot 10^3 = 1$

Располагаемый теплоперепад в Т (Дж/кг):  $H_T = \frac{L_T^* + 0.5c_T^2}{\eta_{\text{л}}} = 520.3 \cdot 10^3$

iteration

k<sub>Г</sub>

P<sub>Г</sub>

T<sub>Г</sub>

=

iteration = 0

k<sub>Г</sub> = k<sub>ад</sub>(Cp<sub>газ</sub>(P\*<sub>Г</sub>, T\*<sub>Г</sub>, α<sub>оx</sub>, Fuel), R<sub>газ</sub>(α<sub>оx</sub>, Fuel))

while 1 > 0

iteration = iteration + 1

Cp<sub>Г</sub> =  $\frac{k_{\Gamma}}{k_{\Gamma} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$

T<sub>Г</sub> =  $T_{\Gamma}^{*} - \frac{c_{\Gamma}^2}{2 \cdot Cp_{\Gamma}}$

P<sub>Г</sub> =  $P_{\Gamma}^{*} \cdot \left(\frac{T_{\Gamma}}{T_{\Gamma}^{*}}\right)^{\frac{k_{\Gamma}}{k_{\Gamma} - 1}}$

k'<sub>Г</sub> = k<sub>ад</sub>(Cp<sub>газ</sub>(P<sub>Г</sub>, T<sub>Г</sub>, α<sub>оx</sub>, Fuel), R<sub>газ</sub>(α<sub>оx</sub>, Fuel))

if |eps("rel", k<sub>Г</sub>, k'<sub>Г</sub>)| ≤ epsilon

k<sub>Г</sub> = k'<sub>Г</sub>

break

k<sub>Г</sub> = k'<sub>Г</sub>

(iteration k<sub>Г</sub> P<sub>Г</sub> T<sub>Г</sub>)<sup>T</sup>

1

1.0

1.3

890047.3

1356.0

Количество итераций: iteration = 1

Показатель адиабаты перед Т: k<sub>Г</sub> = 1.298

Статическое давление перед Т (Па): P<sub>Г</sub> = 890·10<sup>3</sup>

Статическая температура перед Т (K): T<sub>Г</sub> = 1356

Теплоемкость перед Т (Дж/кг/К): Cp<sub>Г</sub> = Cp<sub>газ</sub>(P<sub>Г</sub>, T<sub>Г</sub>, α<sub>оx</sub>, Fuel) = 1256

7

|                  |   |   |
|------------------|---|---|
| <u>iteration</u> |   |   |
| k <sub>T</sub>   | = | iteration = 0   |
| P <sub>T</sub>   |   | k <sub>T</sub> = k <sub>T</sub>   |
| T <sub>T</sub>   |   | while 1 > 0   |
|                  |   | iteration = iteration + 1   |
|                  |   | k <sub>cp</sub> = mean(k <sub>T</sub> , k <sub>T</sub> )  |
|                  |   | Cp = $\frac{k_{cp}}{k_{cp} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$   |
|                  |   | $P_T = P^*_{T} \cdot \left(1 - \frac{H_T}{Cp \cdot T^*_{T}}\right)^{\frac{k_{cp}}{k_{cp} - 1}}$   |
|                  |   | $T_T = T^*_{T} - \frac{H_T \cdot \eta_{л}}{Cp}$   |
|                  |   | k' <sub>T</sub> = k <sub>ад</sub> (Cp <sub>газ</sub> (P <sub>T</sub> , T <sub>T</sub> , α <sub>ox</sub> , Fuel), R <sub>газ</sub> (α <sub>ox</sub> , Fuel)) |
|                  |   | if  eps("rel", k <sub>T</sub> , k' <sub>T</sub> )  ≤ epsilon  |
|                  |   | k <sub>T</sub> = k' <sub>T</sub>  |
|                  |   | break   |
|                  |   | k <sub>T</sub> = k' <sub>T</sub>  |
|                  |   | (iteration k <sub>T</sub> P <sub>T</sub> T <sub>T</sub> ) <sup>T</sup>  |

|   |            |
|---|------------|
|   | 1          |
| 1 | 2          |
| 2 | 1.32       |
| 3 | 191463.061 |
| 4 | 994.672    |

Количество итераций: iteration = 2

Показатель адиабаты после T: k<sub>T</sub> = 1.320

Статическое давление после T (Па): P<sub>T</sub> = 191.5·10<sup>3</sup> P<sub>T</sub> ≥ P<sub>атм</sub>(H<sub>υ</sub>) = 1

Статическая температура после T (K): T<sub>T</sub> = 994.7

Теплоемкость после T (Дж/кг/К): Cp<sub>T</sub> = Cp<sub>газ</sub>(P<sub>T</sub>, T<sub>T</sub>, α<sub>ox</sub>, Fuel) = 1190.6



Ср. показатель адиабаты T:

$k = \text{mean}\left(k_{\Gamma}, k_T\right) = 1.309$

Ср. теплоемкость T (Дж/кг/К):

$C_p = \frac{k}{k-1} \cdot R_{\text{газ}}\left(\alpha_{\text{ox}}, \text{Fuel}\right) = 1222.3$

Степень понижения давления:

$\pi_T = \frac{P_{\Gamma}^*}{P_T} = 4.84$

Удельный объём перед T (м³/кг):

$\left(\begin{array}{c} v_{\Gamma} \\ v_T \end{array}\right) = R_{\text{газ}}\left(\alpha_{\text{ox}}, \text{Fuel}\right) \cdot \left(\begin{array}{c} \frac{T_{\Gamma}}{P_{\Gamma}} \\ \frac{T_T}{P_T} \end{array}\right) =$ 

|   |       |
|---|-------|
|   | 1     |
| 1 | 0.440 |
| 2 | 1.499 |

Удельный объём после T (м³/кг):

Площадь кольцевого сечения перед T (м²):

$\left(\begin{array}{c} F_{\Gamma} \\ F_T \end{array}\right) = \left(\begin{array}{c} \frac{G_{\Gamma} \cdot v_{\Gamma}}{c_{\Gamma}} \\ \frac{G_T \cdot v_T}{c_T} \end{array}\right) =$ 

|   |        |
|---|--------|
|   | 1      |
| 1 | 86421  |
| 2 | 208684 |

 $\cdot 10^{-6}$

Площадь кольцевого сечения после T (м²):

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

$$0.7 \leq \mu_c \leq 1 = 1$$

▼ Определение количества ступеней T

$$\begin{pmatrix} Z_{\text{recomend}} \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} =$$

$$c_{cp} = \text{mean}(c_T, c_T)$$

$$\alpha_{\text{ВОЗВ}} = 0.025$$
while 1 > 0

$$Z = \text{round} \left[ \frac{2 \cdot H_T \cdot \frac{(1 + \alpha_{\text{ВОЗВ}})}{(\mu_c \cdot c_{cp})^2} - 1}{\frac{u_T^2}{(\mu_c \cdot c_{cp})^2 \cdot y_0^2} - 1} \right]$$

break if  $\left| \text{eps} \left[ \text{"rel"}, \alpha_{\text{ВОЗВ}}, \frac{Z - 1}{2 \cdot Z} \cdot \left( \pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}}) \right] \right| < \text{epsilon}$

$$\alpha_{\text{ВОЗВ}} = \frac{Z - 1}{2 \cdot Z} \cdot \left( \pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}})$$

if  $\alpha_{\text{ВОЗВ}} = 0$ 

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

break

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix}$$

1

1

5.000

2

0.022

Рекомендуемое количество ступеней:  $Z_{\text{recomend}} = 5$

Количество ступеней:  $Z = \begin{cases} 1 & \text{if turbine = "ТВД"} \\ 4 & \text{if turbine = "ТНД"} \end{cases} = 4$

Дискретизация ступеней:  $i = 1 \dots Z$

Дискретизация сечений:  $ii = 1 \dots 2 \cdot Z + 1$

▲ Определение количества ступеней T

Выбранный материал Л:

$\text{material\_blade}_i = \begin{cases} \text{"ВКНА-1В"} & \text{if } 1523 \leq T^*_{\Gamma} \\ \text{"ВЖМ7"} & \text{if } 1323 \leq T^*_{\Gamma} < 1523 \\ \text{"ЖС-36"} & \text{if } 1123 \leq T^*_{\Gamma} < 1323 \end{cases}$

Плотность материала Л (кг/м^3):

$\rho_{\text{blade}_i} = \begin{cases} 7938 & \text{if material\_blade}_i = \text{"ВКНА-1В"} \\ 8390 & \text{if material\_blade}_i = \text{"ВЖМ7"} \\ 8760 & \text{if material\_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$

Предел длительной прочности Л РК (Па):

$\sigma_{\text{blade\_long}_i} = 10^6 \cdot \begin{cases} 205 & \text{if material\_blade}_i = \text{"ВКНА-1В"} \\ 120 & \text{if material\_blade}_i = \text{"ВЖМ7"} \\ 120 & \text{if material\_blade}_i = \text{"ЖС-36"} \\ \text{NaN} & \text{otherwise} \end{cases}$

material\_blade<sup>T</sup> =

|   |        |        |        |        |
|---|--------|--------|--------|--------|
|   | 1      | 2      | 3      | 4      |
| 1 | "ВЖМ7" | "ВЖМ7" | "ВЖМ7" | "ВЖМ7" |

ρ\_blade<sup>T</sup> =

|   |      |      |      |      |
|---|------|------|------|------|
|   | 1    | 2    | 3    | 4    |
| 1 | 8390 | 8390 | 8390 | 8390 |

σ\_blade\_long<sup>T</sup> =

|   |     |     |     |     |
|---|-----|-----|-----|-----|
|   | 1   | 2   | 3   | 4   |
| 1 | 120 | 120 | 120 | 120 |

· 10<sup>6</sup>

Коэф. формы:  $k_n = 6.8$

Модуль Юнга I рода материала Л (Па):  $E_{\text{blade}} = 210 \cdot 10^9$

Коэф. Пуассона материала Л():  $\mu_{\text{steel}} = 0.3$

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_{blade\_long}}{\sigma_{blade\_long}}}$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{max} = \sqrt{\frac{\sigma_{blade\_long}}{\sigma_{blade\_long}}}$$

Рекомендуемая ном. частота вращения (об/мин):

$$n = n_{max} \cdot 0.95 =$$

Ном. частота вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 555.0$$

Ср. диаметр перед Т (м):

$$\left( \begin{matrix} D_{г.ср} \\ D_{т.ср} \end{matrix} \right) = \frac{2}{\omega} \cdot \left( \begin{matrix} u_T \\ u_T \end{matrix} \right) =$$

Ср. диаметр после Т (м):

$$\left( \begin{matrix} D_{г.ср} \\ D_{т.ср} \end{matrix} \right) = \frac{2}{\omega} \cdot \left( \begin{matrix} u_T \\ u_T \end{matrix} \right) =$$

Длина Л первой ступени Т (м):

$$\left( \begin{matrix} l_T \\ l_T \end{matrix} \right) = \frac{1}{\pi} \cdot \left( \begin{matrix} \frac{F_T}{D_{г.ср}} \\ \frac{F_T}{D_{т.ср}} \end{matrix} \right) =$$

Длина Л последней ступени Т (м):

$$\left( \begin{matrix} l_T \\ l_T \end{matrix} \right) = \frac{1}{\pi} \cdot \left( \begin{matrix} \frac{F_T}{D_{г.ср}} \\ \frac{F_T}{D_{т.ср}} \end{matrix} \right) =$$

Диаметр периферии после Т (м):

$$\left( \begin{matrix} D_{т.пер} \\ D_{т.кор} \end{matrix} \right) = \left( \begin{matrix} D_{т.ср} + l_T \\ D_{т.ср} - l_T \end{matrix} \right) =$$

Диаметр корня после Т (м):

$$\left( \begin{matrix} D_{т.пер} \\ D_{т.кор} \end{matrix} \right) = \left( \begin{matrix} D_{т.ср} + l_T \\ D_{т.ср} - l_T \end{matrix} \right) =$$

$$n = \begin{cases} 15000 & \text{if turbine = "ТВД"} \\ 5300 & \text{if turbine = "ТНД"} \end{cases} = 5300$$

Равномерное распределение мощности Т по ступеням (Вт):

$$N_{\text{ст}_i} = \frac{N_T}{Z}$$

$$N_{\text{ст}}^T =$$

|   |      |      |      |      |
|---|------|------|------|------|
|   | 1    | 2    | 3    | 4    |
| 1 | 3.80 | 3.80 | 3.80 | 3.80 |

$$\cdot 10^6$$

Вид проточной части:

("const", "кор", "сп", "пер", "доля от предыдущего диаметра периферии")

$$\text{ЗППЧ} = \left( \begin{array}{l} \left| \begin{array}{llllll} \text{"const"} & \text{if } Z = 1 & \text{"1.07"} & \text{"1.065"} & \text{"1.03"} & \text{"пер"} & \text{"пер"} \end{array} \right. \\ \left| \begin{array}{llllll} \text{"кор"} & \text{otherwise} & & & & & \end{array} \right. \\ \left| \begin{array}{llllll} \text{"пер"} & \text{if } Z = 1 & \text{"1.07"} & \text{"1.05"} & \text{"кор"} & \text{"пер"} & \text{"пер"} \end{array} \right. \\ \left| \begin{array}{llllll} \text{"1.055"} & \text{otherwise} & & & & & \end{array} \right. \end{array} \right)^T$$

▼

Определение проточной части ОТ

Линейное распределение кольцевых площадей по сечениям:

$$\begin{array}{l} F_{\text{ww}} = \\ \text{for } i \in 1..2Z + 1 \\ \quad F_i = \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \cdot i + \left( F_\Gamma - \frac{F_T - F_\Gamma}{\text{st}(Z, 3) - 1} \right) \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 2..3 \\ \quad \quad F_{\text{st}(i, a)} = F_{\text{st}(i, a-1)} \text{ if } \text{ЗППЧ}_{i, a-1} = \text{"const"} \\ F \end{array}$$

$$F^T =$$

|   |       |        |        |        |        |        |        |        |        |
|---|-------|--------|--------|--------|--------|--------|--------|--------|--------|
|   | 1     | 2      | 3      | 4      | 5      | 6      | 7      | 8      | 9      |
| 1 | 86421 | 101704 | 116987 | 132270 | 147553 | 162836 | 178118 | 193401 | 208684 |

$$\cdot 10^{-6}$$

D =

for i ∈ 2Z + 1

for r ∈ 1..N<sub>r</sub>

D<sub>i,r</sub> =

D<sub>T.kop</sub> if r = 1

D<sub>T.cp</sub> if r = av(N<sub>r</sub>)

D<sub>T.nep</sub> if r = N<sub>r</sub>

for i ∈ Z..1

for a ∈ 2..1

for r ∈ 1..N<sub>r</sub>

D<sub>st(i,a),r</sub> =

if 3ΠΠΠΨ<sub>i,a</sub> = "const"

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> −  $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$  if r = 1

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> if r = av(N<sub>r</sub>)

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> +  $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$  if r = N<sub>r</sub>

if 3ΠΠΠΨ<sub>i,a</sub> = "kop"

D<sub>st(i,a+1),1</sub> if r = 1

$\frac{1}{2} \cdot \left[ D_{st(i,a+1),1} + \sqrt{\left( D_{st(i,a+1),1} \right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} \right]$  if r = av(N<sub>r</sub>)

$\sqrt{\left( D_{st(i,a+1),1} \right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}}$  if r = N<sub>r</sub>

if 3ΠΠΠΨ<sub>i,a</sub> = "cp"

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> −  $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$  if r = 1

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> if r = av(N<sub>r</sub>)

D<sub>st(i,a+1),av(N<sub>r</sub>)</sub> +  $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$  if r = N<sub>r</sub>

if 3ΠΠΠΨ<sub>i,a</sub> = "nep"

$\sqrt{\left( D_{st(i,a+1),N_r} \right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$  if r = 1

$\frac{1}{2} \cdot \left[ \sqrt{\left( D_{st(i,a+1),N_r} \right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + D_{st(i,a+1),N_r} \right]$  if r = av(N<sub>r</sub>)

D if r = N

D<sup>T</sup> =

|   |       |       |       |       |       |       |       |       |        |
|---|-------|-------|-------|-------|-------|-------|-------|-------|--------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9      |
| 1 | 620.7 | 620.7 | 651.1 | 698.2 | 750.4 | 802.7 | 843.9 | 866.0 | 866.0  |
| 2 | 662.2 | 669.0 | 704.0 | 754.0 | 808.5 | 862.8 | 906.5 | 932.1 | 936.9  |
| 3 | 703.7 | 717.4 | 756.9 | 809.9 | 866.6 | 922.9 | 969.0 | 998.1 | 1007.8 |

·10<sup>−</sup>

R<sub>ww</sub> =

$\frac{D}{2}$

R<sup>T</sup> =

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 310.3 | 310.3 | 325.6 | 349.1 | 375.2 | 401.4 | 422.0 | 433.0 | 433.0 |
| 2 | 331.1 | 334.5 | 352.0 | 377.0 | 404.2 | 431.4 | 453.2 | 466.0 | 468.5 |
| 3 | 351.9 | 358.7 | 378.4 | 404.9 | 433.3 | 461.4 | 484.5 | 499.1 | 503.9 |

·10<sup>−3</sup>

d̄ =

for i ∈ 1..Z

for a ∈ 1..3

$\bar{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_r}}$

d̄

d̄<sup>T</sup> =

|   |        |        |        |        |        |        |        |        |        |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8      | 9      |
| 1 | 0.8819 | 0.8651 | 0.8602 | 0.8621 | 0.8659 | 0.8698 | 0.8709 | 0.8677 | 0.8593 |

d̄<sup>T</sup> ≤ 0.9 =

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
|   | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

h =

for i ∈ 1..2Z + 1

$h_i = \frac{F_i}{\pi \cdot D_{i,av(N_r)}}$

h

h<sup>T</sup> =

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 41.54 | 48.39 | 52.90 | 55.84 | 58.09 | 60.07 | 62.55 | 66.05 | 70.90 |

·10<sup>−3</sup>

14

$$D_{st(i,a+1),N_r}^{u_i - v_i}$$
if  $\left(3\Pi\Pi\Pi_{i,a} \neq \text{"const"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"kop"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"cp"}\right) \wedge \left(3\Pi\Pi\Pi_{i,a} \neq \text{"nep"}\right)$ 

$$\sqrt{\left(\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$$
if  $r = 1$ 

$$\frac{1}{2} \cdot \left[\sqrt{\left(\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + \frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}\right]$$
if  $r = \text{av}\left(N_r\right)$ 

$$\frac{D_{st(i,a+1),N_r}}{\text{str2num}\left(3\Pi\Pi\Pi_{i,a}\right)}$$
if  $r = N_r$ 
NaN otherwise

D

$$u = \begin{cases} \text{for } i \in 1..2 \cdot Z + 1 \\ \text{for } r \in 1..N_r \\ u_{i,r} = \frac{\pi \cdot D_{i,r} \cdot n}{60} \end{cases}$$

u

$$u^T =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 172.2 | 172.2 | 180.7 | 193.8 | 208.2 | 222.8 | 234.2 | 240.3 | 240.3 |
| 2 | 183.8 | 185.7 | 195.4 | 209.3 | 224.4 | 239.4 | 251.6 | 258.7 | 260.0 |
| 3 | 195.3 | 199.1 | 210.0 | 224.7 | 240.5 | 256.1 | 268.9 | 277.0 | 279.7 |

$F^T =$ 

|   |       |        |        |        |        |        |        |        |        |
|---|-------|--------|--------|--------|--------|--------|--------|--------|--------|
|   | 1     | 2      | 3      | 4      | 5      | 6      | 7      | 8      | 9      |
| 1 | 86421 | 101704 | 116987 | 132270 | 147553 | 162836 | 178118 | 193401 | 208684 |

 $\cdot 10^{-6}$

$\overline{d}_1 = 0.8819$ 

$\overline{d}_1 \leq 0.9 = 1$

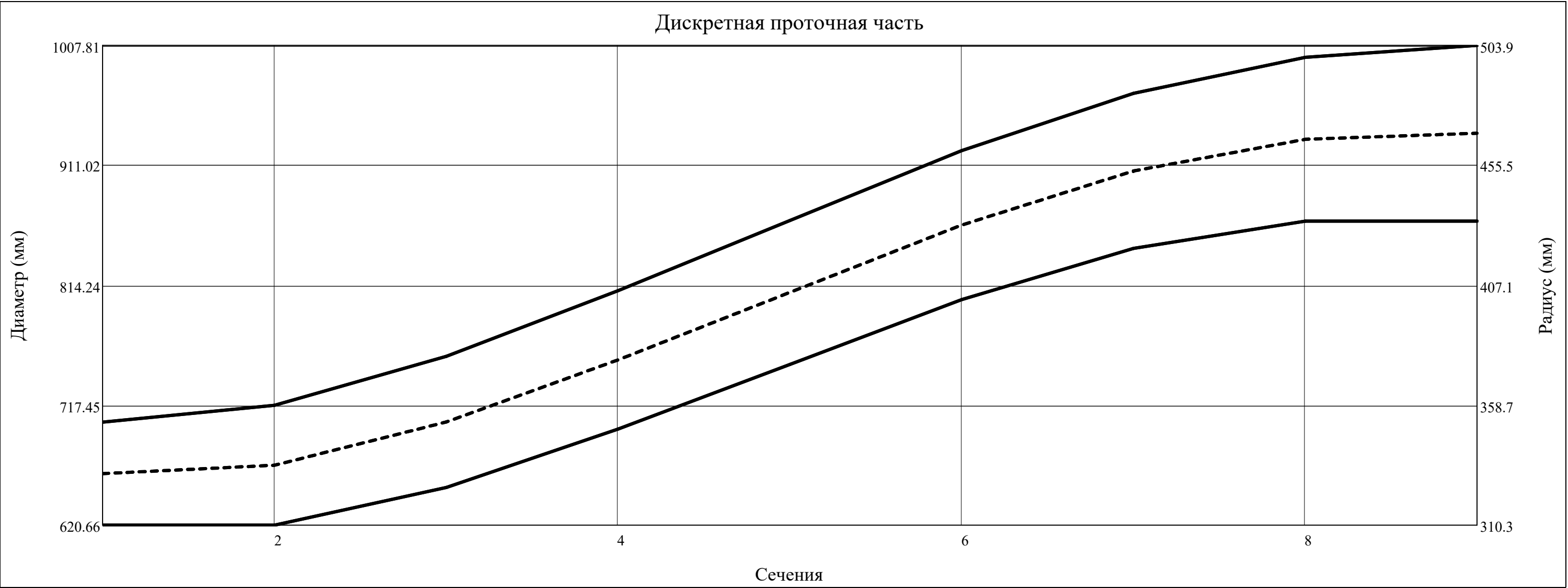
$\overline{d}^T =$ 

|   |        |        |        |        |        |        |        |        |        |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8      | 9      |
| 1 | 0.8819 | 0.8651 | 0.8602 | 0.8621 | 0.8659 | 0.8698 | 0.8709 | 0.8677 | 0.8593 |

$D^T =$ 

|   |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     |
| 1 | 620.7 | 620.7 | 651.1 | 698.2 | 750.4 | 802.7 | 843.9 | 866.0 |
| 2 | 662.2 | 669.0 | 704.0 | 754.0 | 808.5 | 862.8 | 906.5 | 932.1 |
| 3 | 703.7 | 717.4 | 756.9 | 809.9 | 866.6 | 922.9 | 969.0 | ...   |

 $\cdot 10^{-3}$



$h^T =$ 

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 41.54 | 48.39 | 52.90 | 55.84 | 58.09 | 60.07 | 62.55 | 66.05 | 70.90 |

 $\cdot 10^{-3}$





$$\begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in N_r \\ \quad \quad \left| \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \quad \quad \left( \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \right. \\ \quad \quad \left. \gamma_{\text{ПЧпер}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \right. \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \left| \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),N_r} - D_{\text{st}(i,1),N_r} \\ D_{\text{st}(i,2),1} - D_{\text{st}(i,1),1} \end{pmatrix} \text{ if } a = 1 \\ \quad \quad \left( \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),N_r} - D_{\text{st}(i,2),N_r} \\ D_{\text{st}(i,3),1} - D_{\text{st}(i,2),1} \end{pmatrix} \text{ if } a = 2 \right. \\ \quad \quad \left. \gamma_{\text{ПЧ}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \right. \\ \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..2 \\ \quad \quad \text{for } r \in 1 \\ \quad \quad \left| \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{CA_i}} \cdot \begin{pmatrix} D_{\text{st}(i,2),r} - D_{\text{st}(i,1),r} \\ 0 \end{pmatrix} \text{ if } a = 1 \\ \quad \quad \left( \begin{pmatrix} k2 \\ k1 \end{pmatrix} = \frac{0.5}{B_{PK_i}} \cdot \begin{pmatrix} D_{\text{st}(i,3),r} - D_{\text{st}(i,2),r} \\ 0 \end{pmatrix} \text{ if } a = 2 \right. \\ \quad \quad \left. \gamma_{\text{ПЧкор}_{\text{st}(i,a)}} = \text{atan}\left(\frac{k2 - k1}{1 + k2 \cdot k1}\right) \right. \\ \left. \begin{pmatrix} \gamma_{\text{ПЧпер}} \\ \gamma_{\text{ПЧ}} \\ \gamma_{\text{ПЧкор}} \end{pmatrix} \right. \end{cases}$$

$$\text{stack}\left(\gamma_{\text{ПЧпер}}^T, \gamma_{\text{ПЧ}}^T, \gamma_{\text{ПЧкор}}^T\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 9.70 & 33.92 & 30.41 & 40.08 & 28.58 & 31.42 & 14.59 & 7.08 \\ \hline 2 & 9.70 & 6.50 & 2.86 & 2.32 & 1.72 & 2.81 & 3.42 & 7.08 \\ \hline 3 & 0.00 & 27.43 & 27.56 & 37.76 & 26.86 & 28.61 & 11.18 & 0.00 \\ \hline \end{array} .^\circ$$

$$\gamma_{\text{ПЧ}}^T \leq 20.^\circ = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧ}}^T \leq 25.^\circ = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -12.^\circ = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\gamma_{\text{ПЧкор}}^T > -15.^\circ = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

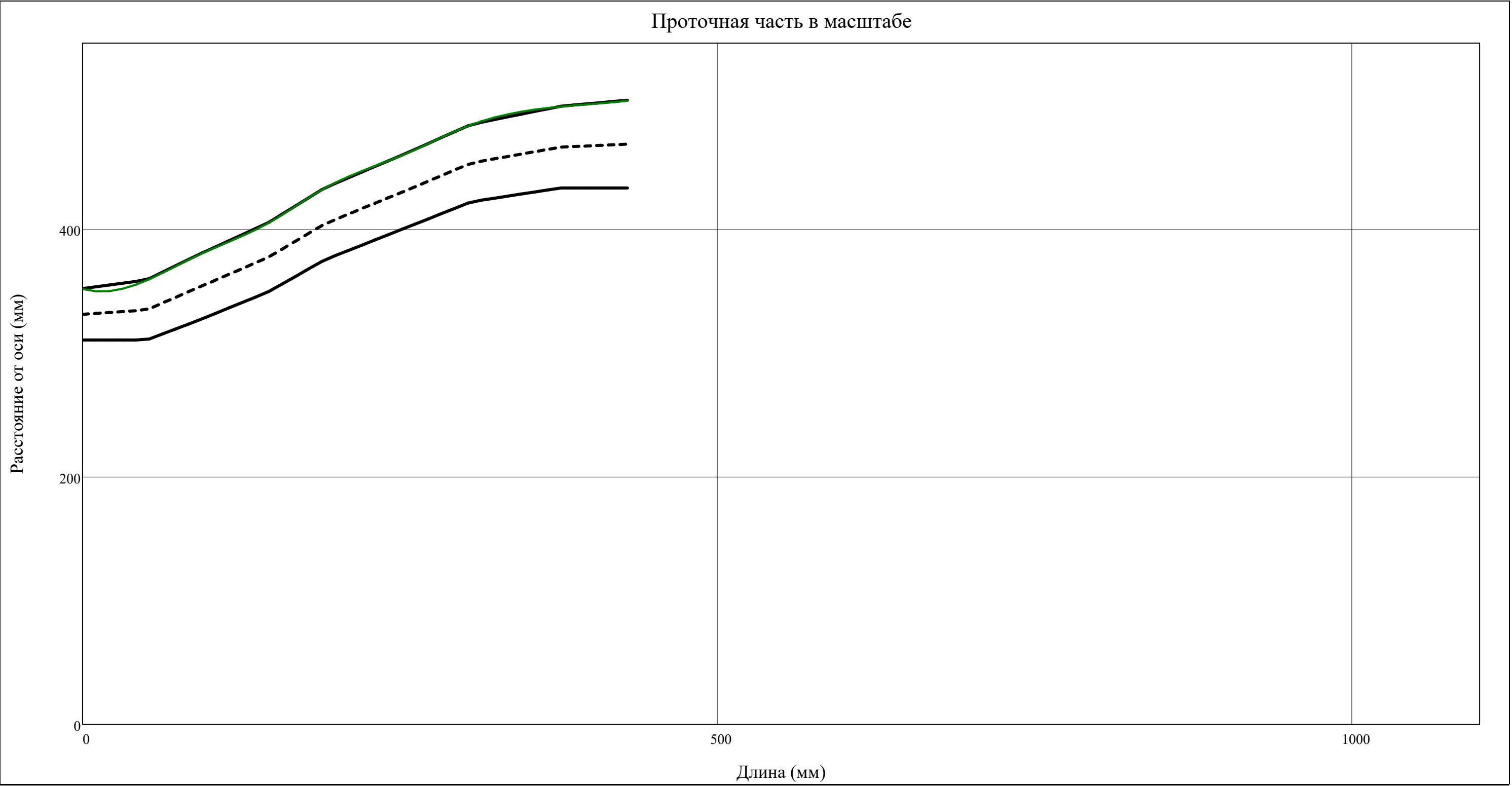
$$\begin{array}{l}
 \left( \begin{array}{l} x_{\text{ПЧ}} \\ y_{\text{ПЧпер}} \\ y_{\text{ПЧср}} \\ y_{\text{ПЧкор}} \\ y_{\text{Лпер}} \end{array} \right) = \left\{ \begin{array}{l} c = 1 \\ x_{\text{ПЧ}_c} = 0 \\ y_{\text{ПЧпер}_c} = D_{\text{st}(c, 1), N_r} \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_c} \\ y_{\text{ПЧср}_c} = D_{\text{st}(c, 1), \text{av}(N_r)} \\ y_{\text{ПЧкор}_c} = D_{\text{st}(c, 1), 1} \\ \text{for } i \in 1..Z \\ \quad c = c + 1 \\ \quad x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{CA_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \left( \begin{array}{l} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{array} \right) = \left( \begin{array}{l} D_{\text{st}(i, 2), N_r} \\ D_{\text{st}(i, 2), \text{av}(N_r)} \\ D_{\text{st}(i, 2), 1} \end{array} \right) \\ \quad y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_i} \\ \quad c = c + 1 \\ \quad x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{PK_i} + 0.5 \cdot \Delta_{a_i} \\ \quad \left( \begin{array}{l} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{array} \right) = \left( \begin{array}{l} D_{\text{st}(i+1, 1), N_r} \\ D_{\text{st}(i+1, 1), \text{av}(N_r)} \\ D_{\text{st}(i+1, 1), 1} \end{array} \right) \\ \quad y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_i} \\ \left( \begin{array}{l} x_{\text{ПЧ}} \\ y_{\text{ПЧпер}} \\ y_{\text{ПЧср}} \\ y_{\text{ПЧкор}} \\ y_{\text{Лпер}} \end{array} \right)
 \end{array} \right.
 \end{array}$$

$$\text{Length} = \sum_{i=1}^Z B_{CA_i} + \sum_{i=1}^Z \Delta_{a_i} + \sum_{i=1}^Z B_{PK_i} = 380.7 \cdot 10^{-3}$$

$$x = \min(x_{\text{ПЧ}}), \min(x_{\text{ПЧ}}) + \frac{\max(x_{\text{ПЧ}}) - \min(x_{\text{ПЧ}})}{N_{\text{dis}}} .. \max(x_{\text{ПЧ}})$$

$y_{ПЧпер}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧпер}, 1) \quad y_{ПЧср}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧср}, 1) \quad y_{ПЧкор}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧкор}, 1)$

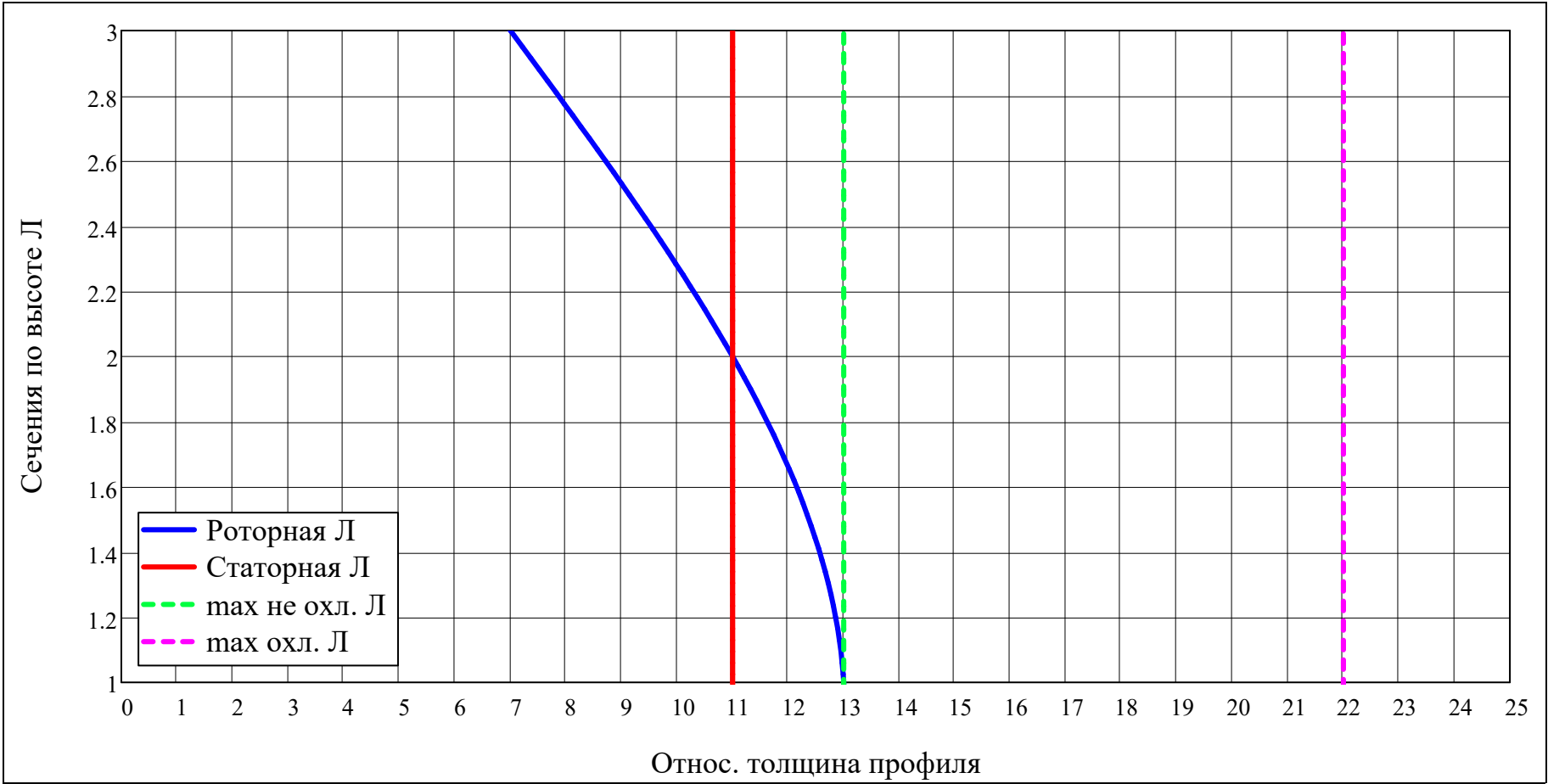
$y_{Лпер}(l) = \text{interp}(\text{cspline}(x_{ПЧ}, 0.5 \cdot y_{Лпер}), x_{ПЧ}, 0.5 \cdot y_{Лпер}, 1)$



Относ. толщины ЛРК и СА:

$$\overline{c}_{\text{stator.}}(r) = \begin{cases} \text{interp} \left[ \text{cspline} \left[ \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{г}} \\ \text{interp} \left[ \text{cspline} \left[ \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 11 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 11 \\ 11 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$

$$\overline{c}_{\text{rotor.}}(r) = \begin{cases} \text{interp} \left[ \text{cspline} \left[ \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 11 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{г}} \\ \text{interp} \left[ \text{cspline} \left[ \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 \\ 7 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 \\ 7 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$



$$\begin{pmatrix} \overline{c}_{\text{stator}} \\ \overline{c}_{\text{rotor}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \overline{c}_{\text{stator}_{i,r}} \\ \overline{c}_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{c}_{\text{stator.}}(r) \\ \overline{c}_{\text{rotor.}}(r) \end{pmatrix} \end{cases}$$

$\overline{c}_{\text{stator}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 11.00 | 11.00 | 11.00 | 11.00 |
| 2 | 11.00 | 11.00 | 11.00 | 11.00 |
| 3 | 11.00 | 11.00 | 11.00 | 11.00 |

 $\cdot \%$

$\overline{c}_{\text{rotor}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 13.00 | 13.00 | 13.00 | 13.00 |
| 2 | 11.00 | 11.00 | 11.00 | 11.00 |
| 3 | 7.00  | 7.00  | 7.00  | 7.00  |

 $\cdot \%$

$$\begin{pmatrix} \overline{r\_inlet\_rotor} & \overline{r\_inlet\_stator} \\ \overline{r\_outlet\_rotor} & \overline{r\_outlet\_stator} \end{pmatrix} =$$

for i ∈ 1..Z

for r ∈ 1..N<sub>r</sub>

$$\begin{pmatrix} \overline{r\_inlet\_stator}_{i,r} \\ \overline{r\_outlet\_stator}_{i,r} \end{pmatrix} = \begin{pmatrix} 0.4 \\ 0.2 \end{pmatrix} \cdot \overline{c}_{stator.(r)}$$

$$\begin{pmatrix} \overline{r\_inlet\_rotor}_{i,r} \\ \overline{r\_outlet\_rotor}_{i,r} \end{pmatrix} = \begin{pmatrix} 0.3 \\ 0.1 \end{pmatrix} \cdot \overline{c}_{rotor.(r)}$$

$$\begin{pmatrix} \overline{r\_inlet\_rotor} & \overline{r\_inlet\_stator} \\ \overline{r\_outlet\_rotor} & \overline{r\_outlet\_stator} \end{pmatrix}$$

$\overline{r\_inlet\_stator}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 4.400 | 4.400 | 4.400 | 4.400 |
| 2 | 4.400 | 4.400 | 4.400 | 4.400 |
| 3 | 4.400 | 4.400 | 4.400 | 4.400 |

.%

$\overline{r\_outlet\_stator}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 2.200 | 2.200 | 2.200 | 2.200 |
| 2 | 2.200 | 2.200 | 2.200 | 2.200 |
| 3 | 2.200 | 2.200 | 2.200 | 2.200 |

.%

$\overline{r\_inlet\_rotor}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 3.900 | 3.900 | 3.900 | 3.900 |
| 2 | 3.300 | 3.300 | 3.300 | 3.300 |
| 3 | 2.100 | 2.100 | 2.100 | 2.100 |

.%

$\overline{r\_outlet\_rotor}^T =$

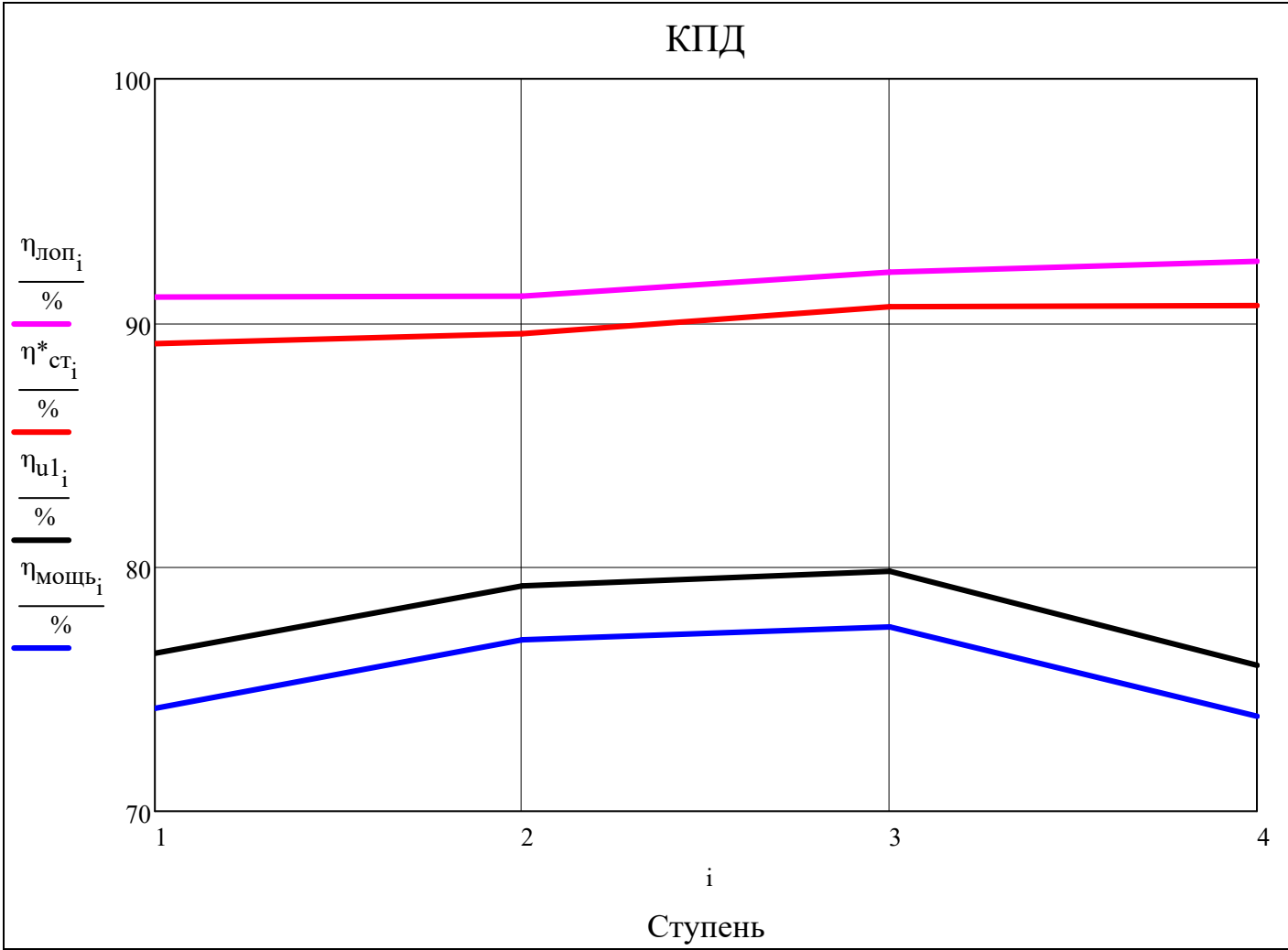
|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 1.300 | 1.300 | 1.300 | 1.300 |
| 2 | 1.100 | 1.100 | 1.100 | 1.100 |
| 3 | 0.700 | 0.700 | 0.700 | 0.700 |

.%

▶ Вывод результатов поступенчатого расчета продольной геометрии ОТ в EXCEL:

$$R_{L.cp} = \left( \begin{array}{l} 0.16 \text{ if turbine} = \text{"ТВД"} \\ 0.13 \text{ otherwise} \end{array} \begin{array}{l} 0.15 \ 0.18 \ 0.185 \ 0.5 \ 0.5 \end{array} \right)^T$$





$\eta_{\text{лoп}}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 91.06 | 91.09 | 92.08 | 92.53 |

·%

$\eta^*_{\text{cт}}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 89.16 | 89.56 | 90.67 | 90.72 |

·%

$\text{stack}(\eta_{u1}^T, \eta_{u2}^T) =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 76.46 | 79.22 | 79.83 | 75.98 |
| 2 | 76.16 | 79.02 | 79.67 | 75.79 |

·%

$\eta_{\text{мoщb}}^T =$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 74.21 | 77.02 | 77.55 | 73.89 |

·%

$\eta_{\text{мoщb}_i} \leq \eta_{u1_i} \leq \eta^*_{\text{cт}_i} \leq \eta_{\text{лoп}_i} =$

|   |
|---|
| 1 |
| 1 |
| 1 |
| 1 |

Степень понижения полного давления Т:  
Степень понижения давления Т:

$$\left(\frac{\pi^*_{\text{Т}}}{\pi_{\text{Т}}}\right) = P^*_{\text{st}(1,1), \text{av}(N_{\text{r}})} \cdot \left[ \frac{\left(P^*_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}}{\left(P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^{-1}} \right] =$$

|   |      |
|---|------|
|   | 1    |
| 1 | 4.06 |
| 2 | 4.46 |

Температурный перепад по параметрам торможения (Дж/кг):  
Располагаемый температурный перепад (Дж/кг):

$$\begin{pmatrix} H^*_{\text{Т}} \\ H_{\text{Т}} \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^Z H^*_{\text{сТ}_i} \\ \sum_{i=1}^Z H_{\text{сТ}_i} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 476.4 \\ 567.0 \end{pmatrix} \cdot 10^3$$

Мощность Т (Вт):

$$\sum_{i=1}^Z N_{\text{сТ}_i} = 15.18 \cdot 10^6$$

$$\text{eps}\left(\text{"rel"}, N_{\text{Т}}, \sum_{i=1}^Z N_{\text{сТ}_i}\right) = 0.000\cdot\%$$

Удельная поступенчатая работа Т [Дж/кг]:

$$L_{\text{Т}} = \sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} = 428.9 \cdot 10^3$$

Лопаточный КПД Т:

$$\eta_{\text{Тлоп}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} + \frac{\left(c_{\text{st}(Z,3), \text{av}(N_{\text{r}})}\right)^2}{2}}{H_{\text{Т}}} = 80.42\cdot\%$$

$$k_{\text{Т.ср}} = k_{\text{ад}}\left(C_{\text{рГаз.ср}}\left(P_{\text{st}(1,1), \text{av}(N_{\text{r}})}, P_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, T_{\text{st}(1,1), \text{av}(N_{\text{r}})}, T_{\text{st}(Z,3), \text{av}(N_{\text{r}})}, \alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right), R_{\text{Газ.ср}}\left(\alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right)\right) = 1.308$$

Адиабатный КПД Т:

$$\eta^*_{\text{Т}} = \frac{L_{\text{Т}}}{H^*_{\text{Т}}} = 90.04\cdot\%$$

Политропический КПД Т:

$$\eta^*_{\text{Т.п}} = \eta^*_{\text{n}}\left(\text{"расширение"}, \eta^*_{\text{Т}}, \pi^*_{\text{Т}}, k_{\text{Т.ср}}\right) = 88.42\cdot\%$$

Мощностной КПД Т:

$$\eta_{\text{Тмощь}} = \frac{\sum_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)}}{H_{\text{Т}}} = 75.65\cdot\%$$

$$L_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 107.1 & 107.2 & 107.2 & 107.2 \\ \hline \end{array} \cdot 10^3$$

$$N_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.8 & 3.8 & 3.8 & 3.8 \\ \hline \end{array} \cdot 10^6$$

$$Lu_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 110.4 & 110.3 & 110.4 & 110.3 \\ \hline \end{array} \cdot 10^3$$

$$Lu_{нагрузка}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.0 & 2.3 & 1.8 & 1.6 \\ \hline \end{array}$$

$$H_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 144.4 & 139.2 & 138.3 & 145.1 \\ \hline \end{array} \cdot 10^3$$

$$stack\left(H_{stator}^T,H_{rotor}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 125.6 & 118.3 & 113.4 & 118.3 \\ \hline 2 & 18.8 & 21.0 & 25.0 & 27.0 \\ \hline \end{array} \cdot 10^3$$

$$submatrix\left(R_L^T,av\left(N_r\right),av\left(N_r\right),1,Z\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.1 & 0.2 & 0.2 & 0.2 \\ \hline \end{array}$$

$$G^T = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & ... \\ \hline \end{array}$$

$$\alpha_{ox}^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 \\ \hline \end{array}$$

$$stack\left(\theta_{CA}^T,\theta_{PK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -0.005 & -0.112 & -0.246 & -0.420 \\ \hline 2 & -0.066 & -0.192 & -0.353 & -0.568 \\ \hline \end{array}$$

$$stack\left(g_{oxлCA}^T,g_{oxлPK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & 0.00 & 0.00 & 0.00 \\ \hline 2 & 0.00 & 0.00 & 0.00 & 0.00 \\ \hline \end{array} \cdot 10^{-3}$$

$$G_{oxлCA_i} = g_{oxлCA_i} \cdot G_{st(i,1)}$$

$$G_{oxлPK_i} = g_{oxлPK_i} \cdot G_{st(i,2)}$$

$$stack\left(G_{oxлCA}^T,G_{oxлPK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.0 & 0.0 & 0.0 & 0.0 \\ \hline 2 & 0.0 & 0.0 & 0.0 & 0.0 \\ \hline \end{array}$$

$$G_{cooling} = 0.8$$

$$\sum_{i=1}^Z G_{oxлCA_i} + \sum_{i=1}^Z G_{oxлCA_i} \leq G_{cooling} = 1$$

$$\text{stack}\left(\text{iteration}_{\text{CA}}^{\text{T}}, \text{iteration}_{\text{PK}}^{\text{T}}\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 2 & 2 & 2 & 2 \\ \hline 2 & 2 & 2 & 2 & 2 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{k}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1.3 & 1.3 & 1.3 & 1.3 & 1.3 & 1.3 & 1.3 & 1.3 & 1.3 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{P}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 927.5 & 914.5 & 676.5 & 665.4 & 483.0 & 475.7 & 337.5 & 332.0 & 228.6 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\left(\mathbf{P}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 890.0 & 666.6 & 633.1 & 485.0 & 456.1 & 342.7 & 316.7 & 228.6 & 208.2 \\ \hline \end{array} \cdot 10^3$$

$$\text{submatrix}\left(\mathbf{T}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1368.9 & 1369.9 & 1281.1 & 1282.0 & 1192.4 & 1193.4 & 1102.5 & ... \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{T}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 1356.0 & 1273.0 & 1261.5 & 1190.4 & 1176.4 & 1103.9 & 1085.9 & ... \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{T}_{\text{w}}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 0.0 & 1316.3 & 1317.8 & 1225.8 & 1228.5 & 1134.2 & 1136.8 & ... \\ \hline \end{array}$$

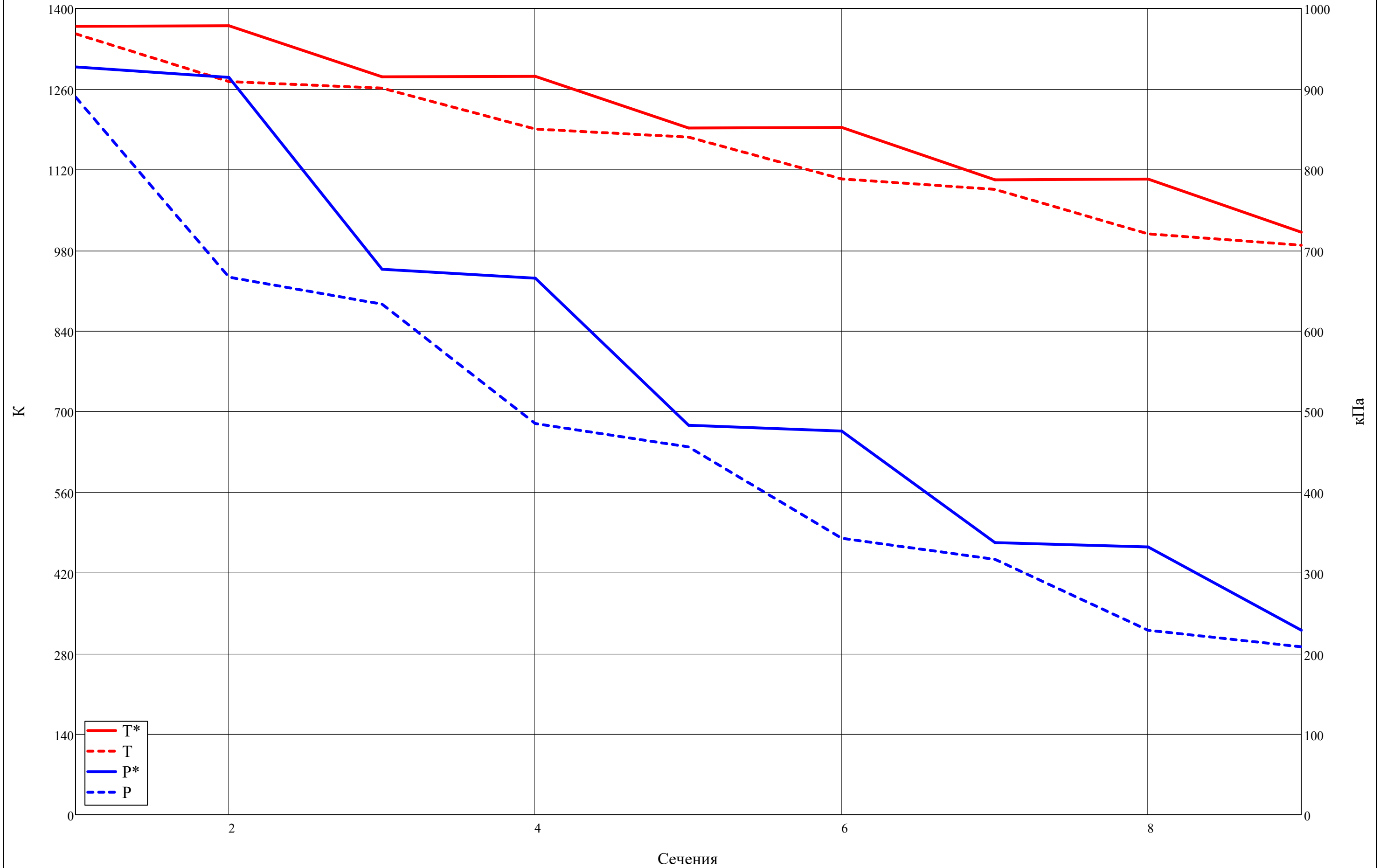
$$\text{submatrix}\left(\mathbf{T}_{\text{a}\mathcal{A}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 0.0 & 1268.9 & 1257.9 & 1185.9 & 1173.4 & 1100.0 & 1083.4 & ... \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{v}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.440 & 0.551 & 0.575 & 0.708 & 0.744 & 0.929 & 0.989 & 1.273 & 1.370 \\ \hline \end{array}$$

$$\text{submatrix}\left(\boldsymbol{\rho}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.349 & 2.314 & 1.830 & 1.799 & 1.404 & 1.382 & 1.061 & 1.043 & 0.784 \\ \hline \end{array}$$

$$\text{submatrix}\left(\boldsymbol{\rho}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.275 & 1.815 & 1.740 & 1.412 & 1.344 & 1.076 & 1.011 & 0.786 & 0.730 \\ \hline \end{array}$$

Термодинамические параметры по тракту Т на ср. сечении



$$\text{submatrix}\left(\mathbf{a}_{3\text{B}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 712.6 & 691.5 & 688.5 & 669.8 & 666.1 & 646.3 & 641.3 & 619.4 & 613.6 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{a}_{\text{c}}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 667.9 & 668.6 & 646.6 & 647.3 & 624.3 & 625.1 & 600.9 & 601.8 & 576.2 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{a}_{\text{w}}^{*\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 655.4 & 655.8 & 632.9 & 633.7 & 609.3 & 610.2 & 584.6 & 584.9 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 180.0 & 490.9 & 220.6 & 474.7 & 197.9 & 465.9 & 200.4 & 476.7 & 232.6 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{u}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 451.9 & 135.7 & 435.3 & 85.6 & 419.9 & 39.1 & 415.9 & 10.3 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{a}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 180.0 & 191.7 & 173.9 & 189.4 & 178.5 & 202.0 & 196.6 & 232.9 & 232.4 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 328.1 & 373.9 & 294.9 & 357.6 & 270.8 & 350.9 & 281.0 & 356.5 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\text{u}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 266.2 & 331.0 & 226.0 & 309.9 & 180.5 & 290.6 & 157.3 & 270.3 \\ \hline \end{array}$$

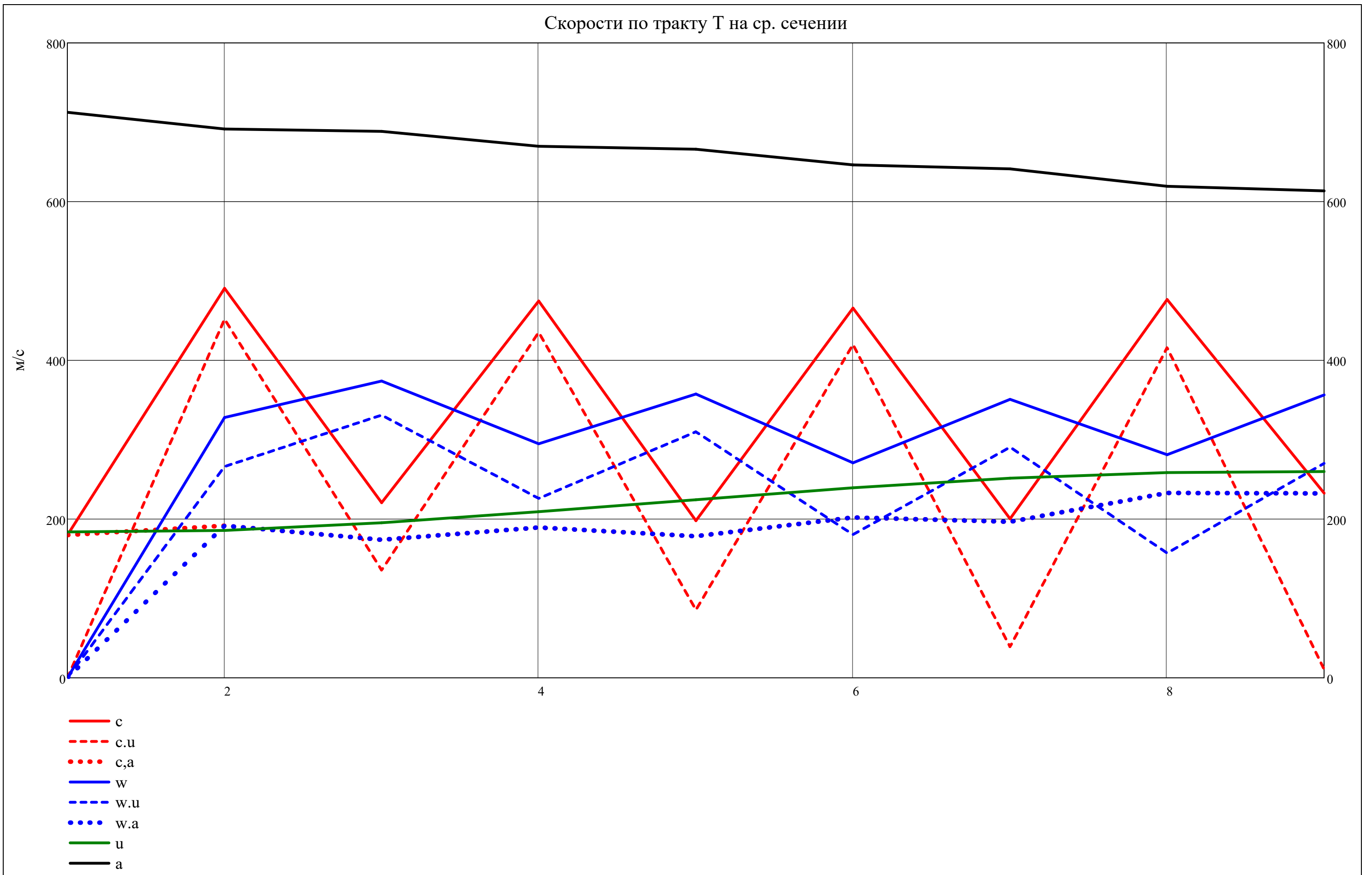
$$\text{submatrix}\left(\mathbf{w}_{\text{a}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 191.7 & 173.9 & 189.4 & 178.5 & 202.0 & 196.6 & 232.9 & 232.4 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{c}_{\text{aD}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \hline 1 & 537.4 & 501.2 & 527.6 & 486.5 & 525.9 & 476.2 & 538.7 & 486.4 \\ \hline \end{array}$$

$$\text{submatrix}\left(\mathbf{w}_{\text{aD}}^{\text{T}}, \text{av}\left(\mathbf{N}_{\text{r}}\right), \text{av}\left(\mathbf{N}_{\text{r}}\right), 1, 2Z + 1\right) = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 0.0 & 386.0 & 0.0 & 368.0 & 0.0 & 359.5 & 0.0 & 365.5 \\ \hline \end{array}$$

$$\mathbf{u}^{\text{T}} = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 172.2 & 172.2 & 180.7 & 193.8 & 208.2 & 222.8 & 234.2 & 240.3 & 240.3 \\ \hline 2 & 183.8 & 185.7 & 195.4 & 209.3 & 224.4 & 239.4 & 251.6 & 258.7 & 260.0 \\ \hline 3 & 195.3 & 199.1 & 210.0 & 224.7 & 240.5 & 256.1 & 268.9 & 277.0 & 279.7 \\ \hline \end{array}$$

Скорости по тракту Т на ср. сечении



$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_r\Big),\text{av}\Big(N_r\Big)\Big)^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 90.00 & 22.99 & 52.05 & 23.52 & 64.39 & 25.69 & 78.75 & 29.25 & 87.45 \\ \hline \end{array} \text{.}^\circ$$

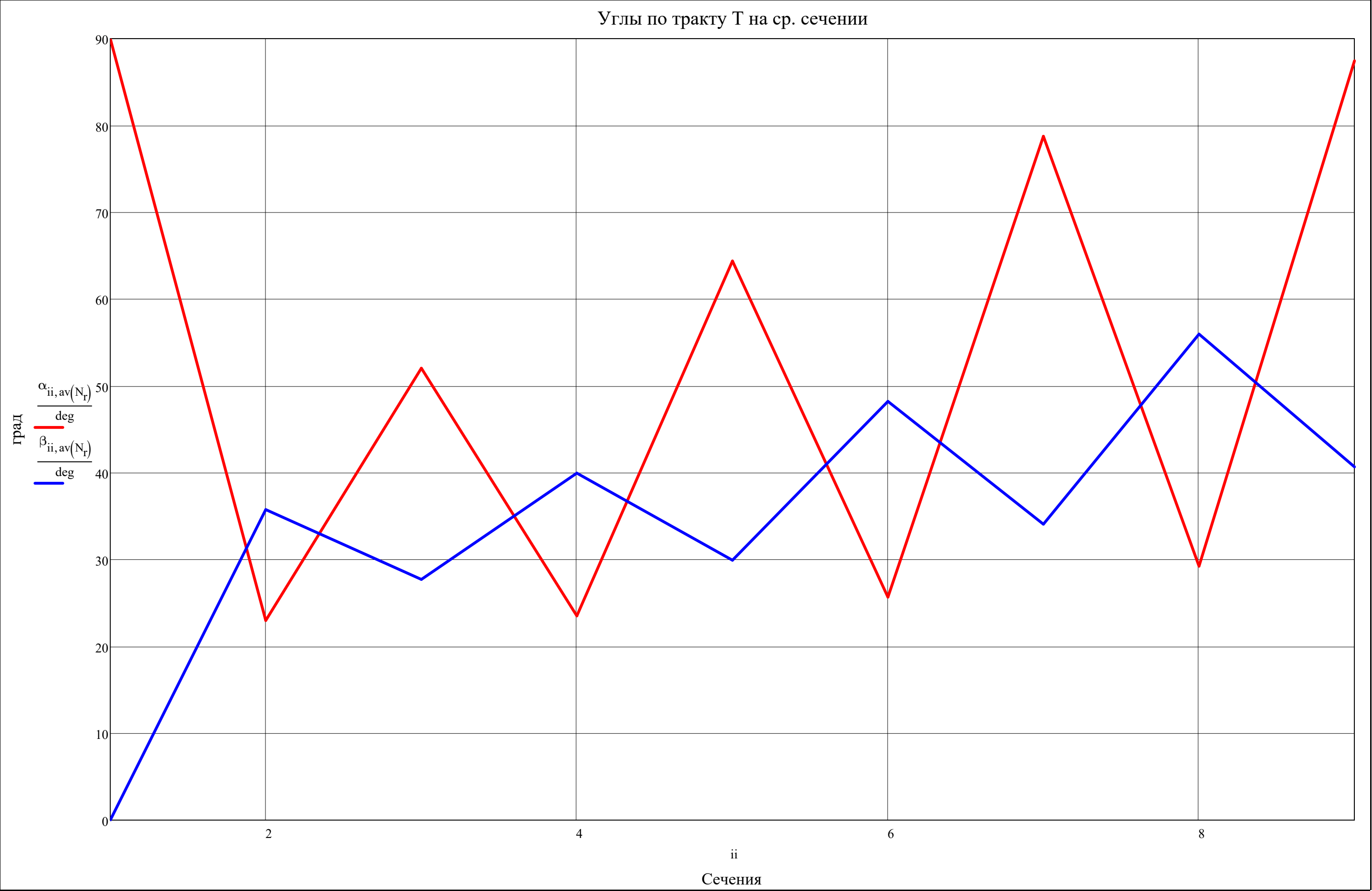
$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(N_r\Big),\text{av}\Big(N_r\Big)\Big)^T \geq 11\text{.}^\circ = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\beta,1,2\cdot Z+1,\text{av}\Big(N_r\Big),\text{av}\Big(N_r\Big)\Big)^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 \\ \hline 1 & 0.00 & 35.76 & 27.72 & 39.97 & 29.94 & 48.22 & 34.07 & 55.97 & 40.68 & & & & \\ \hline \end{array} \text{.}^\circ$$

$$\text{submatrix}\Big(\varepsilon_{\text{stator}},1,Z,\text{av}\Big(N_r\Big),\text{av}\Big(N_r\Big)\Big)^T = \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -67.01 & -28.53 & -38.7 & -49.51 & & \\ \hline \end{array} \text{.}^\circ$$

$$\text{submatrix}\Big(\varepsilon_{\text{rotor}},1,Z,\text{av}\Big(N_r\Big),\text{av}\Big(N_r\Big)\Big)^T = \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -8.04 & -10.03 & -14.14 & -15.29 & & \\ \hline \end{array} \text{.}^\circ$$





$$\text{submatrix}\Big(\lambda_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

|   |        |        |        |        |        |        |        |     |
|---|--------|--------|--------|--------|--------|--------|--------|-----|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8   |
| 1 | 0.2695 | 0.7342 | 0.3411 | 0.7334 | 0.3170 | 0.7454 | 0.3335 | ... |

$$\text{submatrix}\Big(\lambda_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

|   |        |        |        |        |        |        |        |     |
|---|--------|--------|--------|--------|--------|--------|--------|-----|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8   |
| 1 | 0.0000 | 0.5006 | 0.5702 | 0.4660 | 0.5643 | 0.4445 | 0.5750 | ... |

$$\text{submatrix}\Big(\text{M}_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

|   |        |        |        |        |        |        |        |     |
|---|--------|--------|--------|--------|--------|--------|--------|-----|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8   |
| 1 | 0.2526 | 0.7099 | 0.3204 | 0.7088 | 0.2972 | 0.7209 | 0.3125 | ... |

$$\text{submatrix}\Big(\text{M}_{\text{c}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} \leq 1 =$$

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
|   | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

$$\text{submatrix}\Big(\text{M}_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

|   |        |        |        |        |        |        |        |     |
|---|--------|--------|--------|--------|--------|--------|--------|-----|
|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8   |
| 1 | 0.0000 | 0.4744 | 0.5431 | 0.4403 | 0.5369 | 0.4190 | 0.5471 | ... |

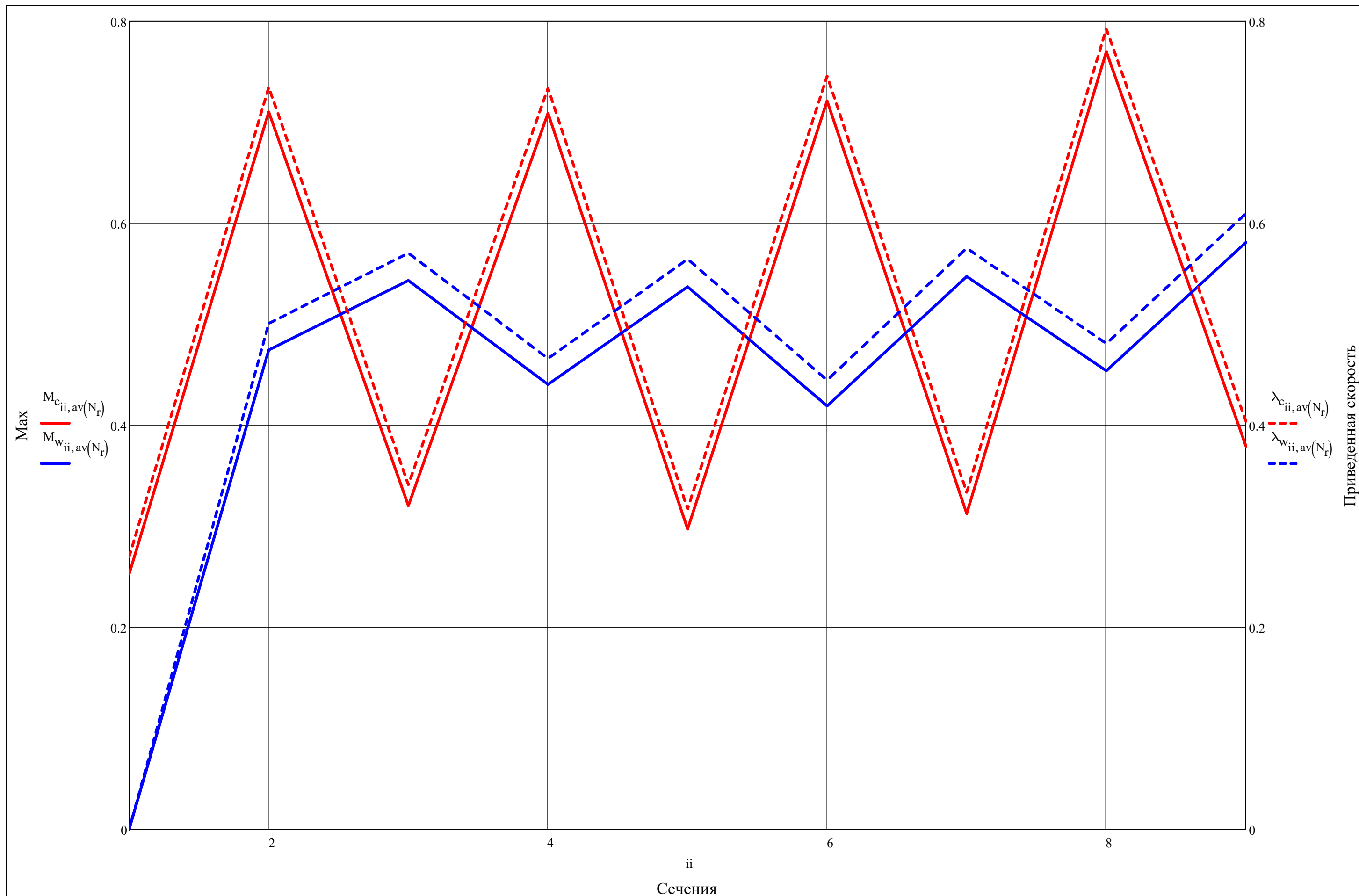
$$\text{submatrix}\Big(\text{M}_{\text{w}},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} \leq 1 =$$

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
|   | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

$$\text{stack}\Big(v_{\text{stator}}^{\text{T}},v_{\text{rotor}}^{\text{T}}\Big) =$$

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 43.08 | 63.04 | 58.94 | 53.66 |
| 2 | 68.71 | 68.31 | 67.38 | 67.10 |

$$.\circ$$



$$\mathbf{t}_{\text{stator}}^T = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 40.6 & 27.9 & 35.9 & 43.3 \\ 2 & 43.6 & 30.1 & 38.6 & 46.6 \\ 3 & 46.5 & 32.4 & 41.3 & 49.8 \end{bmatrix} \quad \mathbf{t}_{\text{rotor}}^T = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 18.7 & 22.1 & 26.7 & 28.6 \\ 2 & 20.2 & 23.8 & 28.7 & 30.9 \\ 3 & 21.6 & 25.6 & 30.6 & 33.2 \end{bmatrix} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{stator}}^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 58.6 & 50.6 & 60.3 & 69.3 \end{bmatrix} \cdot 10^{-3}$$

$$\text{submatrix}\Big(\text{chord}_{\text{rotor}}^T, \text{av}\big(N_r\big), \text{av}\big(N_r\big), 1, Z\Big) = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 31.5 & 36.3 & 40.9 & 42.4 \end{bmatrix} \cdot 10^{-3}$$

$$\text{stack}\Big(Z_{\text{stator}}^T, Z_{\text{rotor}}^T\Big) = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 48 & 76 & 68 & 62 \\ 2 & 107 & 103 & 97 & 95 \end{bmatrix}$$

$$\text{stack}\Big(\overline{\mathbf{t}}_{\text{OITCA}}^T, \overline{\mathbf{t}}_{\text{OITPK}}^T\Big) = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 0.762 & 0.603 & 0.644 & 0.686 \\ 2 & 0.651 & 0.669 & 0.704 & 0.731 \end{bmatrix}$$

$$\frac{\mathbf{t}_{\text{stator}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{stator}_{i, \text{av}(N_r)}}} = 0.7 \leq \frac{\mathbf{t}_{\text{stator}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{stator}_{i, \text{av}(N_r)}}} \leq 1 = \frac{\mathbf{t}_{\text{rotor}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{rotor}_{i, \text{av}(N_r)}}} = 0.7 \leq \frac{\mathbf{t}_{\text{rotor}_{i, \text{av}(N_r)}}}{\text{chord}_{\text{rotor}_{i, \text{av}(N_r)}}} \leq 1 =$$

|       |
|-------|
| 0.743 |
| 0.595 |
| 0.640 |
| 0.672 |

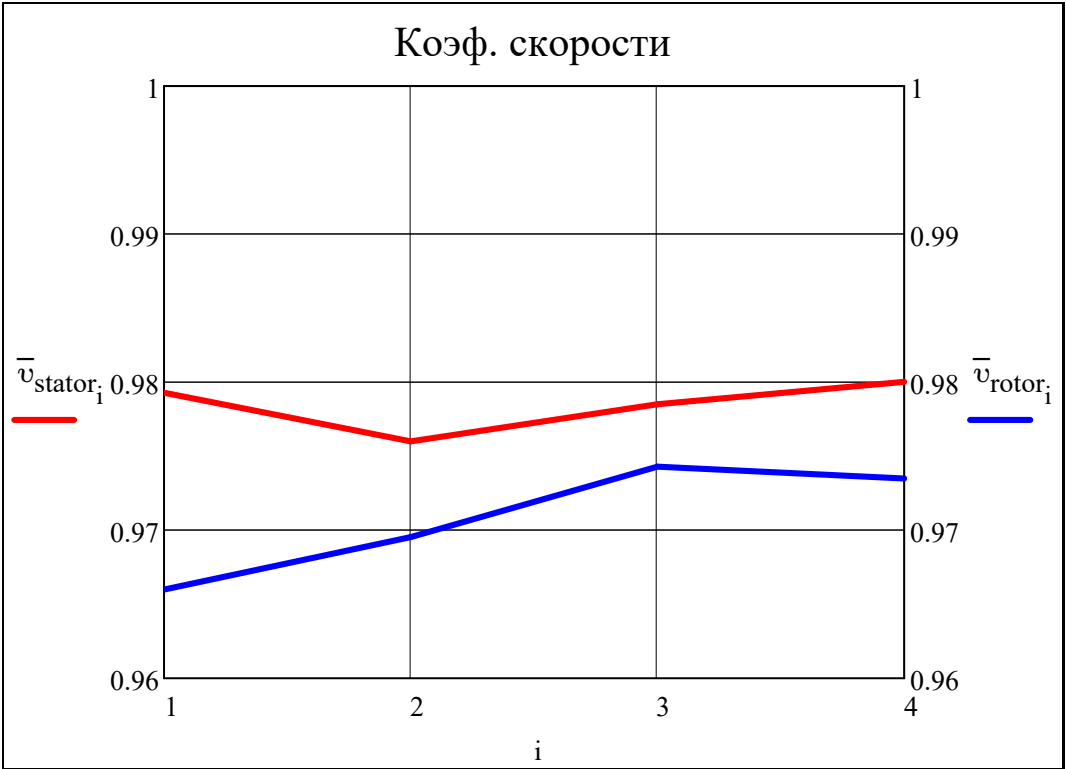
|   |
|---|
| 1 |
| 0 |
| 0 |
| 0 |

|       |
|-------|
| 0.640 |
| 0.657 |
| 0.700 |
| 0.729 |

|   |
|---|
| 0 |
| 0 |
| 1 |
| 1 |

$\text{stack}\left(\overline{v}_{\text{stator}}^T, \overline{v}_{\text{rotor}}^T\right) =$ 

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | 0.9793 | 0.9760 | 0.9785 | 0.9800 |
| 2 | 0.9660 | 0.9695 | 0.9743 | 0.9735 |



$$\text{stack}\left(\xi_{\text{TpCA}}^T, \xi_{\text{TpPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 1.396 & 1.811 & 1.520 & 1.394 \\ \hline 2 & 3.905 & 3.265 & 2.464 & 2.488 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{kpCA}}^T, \xi_{\text{kpPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 1.517 & 1.852 & 1.587 & 1.340 \\ \hline 2 & 0.739 & 0.671 & 0.561 & \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ppCA}}^T, \xi_{\text{ppPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 3.117 & 3.961 & 3.405 & 2.995 \\ \hline 2 & 5.301 & 4.665 & 3.809 & 3.818 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ReCA}}^T, \xi_{\text{RePK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & -0.014 & 0.079 & 0.097 & 0.127 \\ \hline 2 & 0.287 & 0.348 & 0.424 & 0.572 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\lambda\text{CA}}^T, \xi_{\lambda\text{PK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.218 & 0.219 & 0.201 & 0.134 \\ \hline 2 & 0.370 & 0.381 & 0.360 & 0.295 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{BTCA}}^T, \xi_{\text{BTPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.982 & 0.780 & 0.847 & 0.961 \\ \hline 2 & 1.384 & 1.337 & 1.265 & 1.414 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{TDCA}}^T, \xi_{\text{TDPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.000 & 0.000 & 0.000 & 0.000 \\ \hline 2 & 0.000 & 0.000 & 0.000 & 0.000 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{cmCA}}^T, \xi_{\text{cmPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.000 & 0.000 & 0.000 & 0.000 \\ \hline 2 & 0.000 & 0.000 & 0.000 & 0.000 \\ \hline \end{array} \cdot\%$$

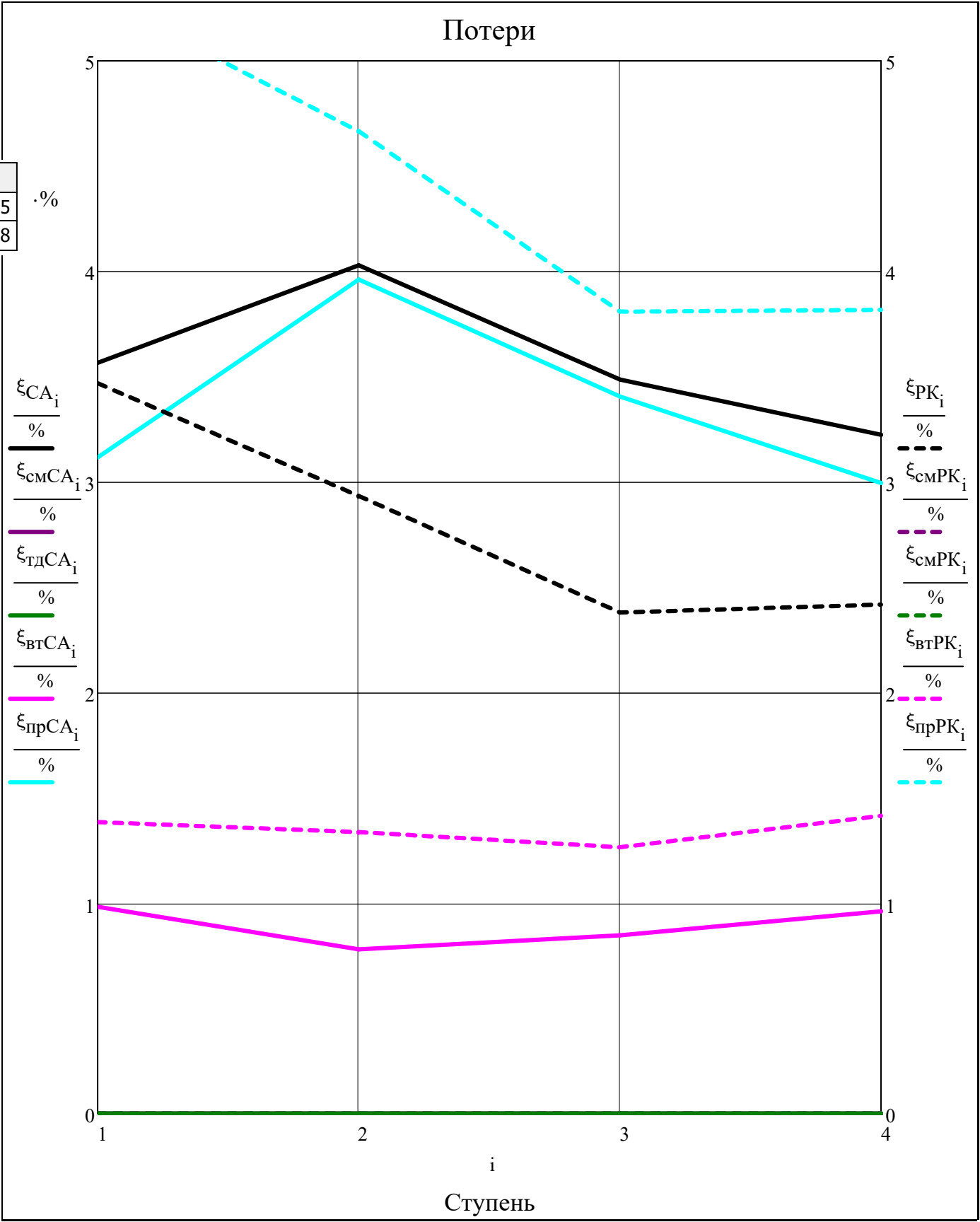
$$\text{stack}\left(\xi_{\text{CA}}^T, \xi_{\text{PK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 3.566 & 4.029 & 3.486 & 3.224 \\ \hline 2 & 3.469 & 2.933 & 2.379 & 2.417 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{ВЫХ}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 16.848 & 14.071 & 14.525 & 18.643 \\ \hline \end{array} \cdot\%$$

$$\xi_{\Delta r}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 1.810 & 1.782 & 1.822 & 1.658 \\ \hline \end{array} \cdot\%$$

$$\xi_{\text{Tp.В}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.138 & 0.221 & 0.298 & 0.244 \\ \hline \end{array} \cdot\%$$

$$\text{stack}\left(\xi_{\text{ppCA}}^T, \xi_{\text{ppPK}}^T\right) = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 3.117 & 3.961 & 3.405 & 2.995 \\ \hline 2 & 5.301 & 4.665 & 3.809 & 3.818 \\ \hline \end{array} \cdot\%$$





$$\underline{m} = \begin{pmatrix} \overline{v}_{stator_1} \cdot \cos\left(\alpha_{st(1,2),av(N_r)}\right)^2 \text{ if } Z = 1 \\ -0.5 \text{ otherwise} \\ -0.25 \\ 0 \\ 0.25 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{"}\alpha.2=\text{const" } \\ \text{"}\Gamma=\text{const" } \\ \text{"}m=\text{const" } \\ \text{"}R=\text{const" } \end{pmatrix} = \begin{pmatrix} \cos\left(\alpha_{st(i,2),av(N_r)}\right)^2 \cdot \overline{v}_{stator_i} \\ 1 \cdot \overline{v}_{stator_i} \\ 0.2 \\ -1 \cdot \overline{v}_{stator_i} \end{pmatrix}$$

$m^T =$

|   | 1       | 2       | 3      | 4      | 5      | 6      |
|---|---------|---------|--------|--------|--------|--------|
| 1 | -0.5000 | -0.2500 | 0.0000 | 0.2500 | 1.0000 | 1.0000 |



|          |         |  |
|----------|---------|--|
| P*       | P       |  |
| T*       | T*_w    |  |
| T        | T       |  |
| ρ*       | ρ       |  |
| k        | R_L     |  |
| a*_c     | a*_w    |  |
| a_3B     | a_3B    |  |
| c        | w       | =  |
| c_u      | w_u     | for i ∈ 1..Z   |
| c_a      | w_a     | for a ∈ 2..3   |
| Δc_a     | Δc_a    | for r ∈ 1..N_r   |
| α        | β       | $A_{st(i,a),r} = \left(1 - R_{L_{i,av}(N_r)}\right) \cdot \omega \cdot \left(R_{st(i,a),av(N_r)}\right)^{m_i+1}$   |
| λ_c      | M_c     | $B_{st(i,a),r} = \frac{Lu_{cT_i}}{2 \cdot \omega}$   |
| λ_w      | M_w     | $c_{u_{st(i,a),r}} =$  |
| ε_stator | ε_rotor | <div><div><div><div><div><div><math>\text{if } m_i = \overline{v}_{stator_i} \cdot \cos\left(\alpha_{st(i,2),av(N_r)}\right)^2</math></div><div><math>c_{u_{st(i,a),av(N_r)}} \cdot \left(\frac{R_{st(i,a),av(N_r)}}{R_{st(i,a),r}}\right)^{m_i}</math></div><div><math>\frac{u_{st(i,a-1),av(N_r)} \cdot c_{u_{st(i,a-1),av(N_r)}} + u_{st(i,a),av(N_r)} \cdot c_{u_{st(i,a),av(N_r)}} - u_{st(i,a-1),r} \cdot c_{u_{st(i,a-1),r}}}{u_{st(i,a),r}}</math></div><div><math>\text{if } (a = 1) \vee (a = 3)</math></div></div></div><div><div>otherwise</div><div><math>\frac{A_{st(i,a),r}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a),r}}{\left(R_{st(i,a),r}\right)}</math></div><div><math>-\frac{A_{st(i,a),r}}{\left(R_{st(i,a),r}\right)^{m_i}} + \frac{B_{st(i,a),r}}{\left(R_{st(i,a),r}\right)}</math></div><div><math>\text{if } (a = 1) \vee (a = 3)</math></div></div></div></div></div> <div><math>c_{a_{st(i,a),r}} =</math></div> <div><div><div><div><math>\text{if } m_i = -1</math></div><div><math>\sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a),r}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] - 4 \cdot A_{st(i,a),r} \cdot B_{st(i,a),r} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)}</math></div><div><math>\sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a),r}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] + 4 \cdot A_{st(i,a),r} \cdot B_{st(i,a),r} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)}</math></div><div><math>\text{if } (a = 1) \vee (a = 3)</math></div></div></div></div> |

$$\begin{aligned}
& \text{if } m_i = 0 \\
& \sqrt{\left( c_{a_{st(i,a), av(N_r)}} \right)^2 - 2 \cdot (A_{st(i,a), r})^2 \cdot \left( \ln(R_{st(i,a), r}) - \ln(R_{st(i,a), av(N_r)}) \right) + 2 \cdot A_{st(i,a), r} \cdot B_{st(i,a), r} \cdot \left( \frac{1}{R_{st(i,a), r}} - \frac{1}{R_{st(i,a), av(N_r)}} \right)} \quad \text{if } (a = 2) \\
& \sqrt{\left( c_{a_{st(i,a), av(N_r)}} \right)^2 - 2 \cdot (A_{st(i,a), r})^2 \cdot \left( \ln(R_{st(i,a), r}) - \ln(R_{st(i,a), av(N_r)}) \right) - 2 \cdot A_{st(i,a), r} \cdot B_{st(i,a), r} \cdot \left( \frac{1}{R_{st(i,a), r}} - \frac{1}{R_{st(i,a), av(N_r)}} \right)} \quad \text{if } (a = 1) \vee (a = 3) \\
& \text{if } m_i = \bar{v}_{stator_i} \cdot \cos(\alpha_{st(i,2), av(N_r)})^2 \\
& c_{a_{st(i,a), av(N_r)}} \cdot \sqrt{1 + \frac{\left( \frac{\bar{v}_{stator_i}}{1 - \frac{\bar{v}_{stator_i}}{m_i}} \right) \cdot \left[ 1 - \frac{1}{\left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{2 \cdot m_i}} \right]}{\tan(\alpha_{st(i,2), av(N_r)})^2}} \quad \text{if } (a = 2) \\
& \sqrt{\left( c_{a_{st(i,a), av(N_r)}} \right)^2 \dots \quad \text{if } (a = 1) \vee (a = 3) \\
& + \left[ 1 - (\bar{v}_{rotor_i})^2 \right] \cdot \left( u_{st(i,a), av(N_r)} \right)^2 \cdot \left[ 1 - \left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^2 \right] - 2 \cdot c_{u_{st(i,a), av(N_r)}} \cdot u_{st(i,a), av(N_r)} \cdot \left[ 1 - \left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{1-m_i} \right] \dots \\
& + \left[ 1 - (\bar{v}_{rotor_i})^2 \right] \cdot \left[ 1 - \frac{1}{\left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^2} \right] \cdot \left( c_{u_{st(i,a-1), av(N_r)}} + c_{u_{st(i,a), av(N_r)}} \right)^2 \dots \\
& + -2 \cdot c_{u_{st(i,a-1), av(N_r)}} \cdot \left( c_{u_{st(i,a-1), av(N_r)}} + c_{u_{st(i,a), av(N_r)}} \right) \cdot \left[ 1 - \frac{2}{m_i + 1} \cdot (\bar{v}_{rotor_i})^2 \right] \cdot \left[ 1 - \frac{1}{\left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{m_i+1}} \right] \dots \\
& + \left( c_{u_{st(i,a-1), av(N_r)}} \right)^2 \cdot \left[ 1 - \frac{(\bar{v}_{stator_i})^2 \cdot (\bar{v}_{rotor_i})^2}{m_i} \right] \cdot \left[ 1 - \frac{1}{\left( \frac{R_{st(i,a), r}}{R_{st(i,a), av(N_r)}} \right)^{2 \cdot m_i}} \right] \\
& \text{otherwise} \\
& \sqrt{\left( c_{a_{st(i,a), av(N_r)}} \right)^2 + \frac{A_{st(i,a), r} \cdot (m_i - 1) \cdot \left[ A_{st(i,a), r} \cdot (1 + m_i) \cdot \left[ (R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)}) - (R_{st(i,a), r}) \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right] \dots \right.}{+ 2 \cdot B_{st(i,a), r} \cdot m_i \cdot \left[ (R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)})^{m_i} - (R_{st(i,a), r})^{m_i} \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right]} \quad \text{if } (a = 2) \\
& m_i \cdot (m_i + 1) \cdot (R_{st(i,a), r} \cdot R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \\
& \left. \left( c_{a_{st(i,a), av(N_r)}} \right)^2 + \frac{A_{st(i,a), r} \cdot (m_i - 1) \cdot \left[ A_{st(i,a), r} \cdot (1 + m_i) \cdot \left[ (R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)}) - (R_{st(i,a), r}) \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right] \dots \right.}{+ -2 \cdot B_{st(i,a), r} \cdot m_i \cdot \left[ (R_{st(i,a), r})^{2 \cdot m_i+1} \cdot (R_{st(i,a), av(N_r)})^{m_i} - (R_{st(i,a), r})^{m_i} \cdot (R_{st(i,a), av(N_r)})^{2 \cdot m_i+1} \right]} \quad \text{if } (a = 1) \vee (a = 3) \\
& \left. \left( c_{a_{st(i,a), av(N_r)}} \right)^2 + \dots \right]
\end{aligned}$$

$$\begin{aligned}
& \left| \left| \left| \left( \frac{c_{a_{i,r}}}{c_{u_{i,r}}} \right) \right| \right| \right| \left( \frac{c_{a_{i,r}}}{c_{u_{i,r}}} \right) \\
& \text{for } i \in 1..2 \cdot Z + 1 \\
& \text{for } r \in 1..N_r \\
& \begin{pmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{pmatrix} = c_{i,av(N_r)} \cdot \begin{pmatrix} \cos(\alpha_{i,av(N_r)}) \\ \sin(\alpha_{i,av(N_r)}) \end{pmatrix} \quad \text{if } (i = 1) \\
& P_{i,r}^* = P_{i,av(N_r)}^* \\
& T_{i,r}^* = T_{i,av(N_r)}^* \\
& \rho_{i,r}^* = \frac{P_{i,r}^*}{R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}^*} \\
& k_{i,r} = k_{\text{aд}} \left( C_{\text{pBO3Дyx}}(P_{i,r}^*, T_{i,r}^*), R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \right) \\
& a_{c_{i,r}}^* = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}^*} \\
& \alpha_{i,r} = \text{triangle}(c_{a_{i,r}}, c_{u_{i,r}}) \\
& c_{i,r} = \frac{c_{a_{i,r}}}{\sin(\alpha_{i,r})} \\
& \lambda_{c_{i,r}} = \frac{c_{i,r}}{a_{c_{i,r}}^*} \\
& \begin{pmatrix} T_{i,r} \\ P_{i,r} \\ \rho_{i,r} \end{pmatrix} = \begin{pmatrix} T_{i,r}^* \cdot \Gamma \Delta \Phi("T", \lambda_{c_{i,r}}, k_{i,r}) \\ P_{i,r}^* \cdot \Gamma \Delta \Phi("P", \lambda_{c_{i,r}}, k_{i,r}) \\ \rho_{i,r}^* \cdot \Gamma \Delta \Phi("P", \lambda_{c_{i,r}}, k_{i,r}) \end{pmatrix} \\
& a_{3B_{i,r}} = \sqrt{k_{i,r} \cdot R_{\text{Гa3}}(\alpha_{\text{OX}_i}, \text{Fuel}) \cdot T_{i,r}} \\
& M_{c_{i,r}} = \frac{c_{i,r}}{a_{3B_{i,r}}} \\
& \beta_{i,r} = \text{triangle}(c_{a_{i,r}}, u_{i,r} - c_{u_{i,r}}) \\
& w_{i,r} = \frac{c_{a_{i,r}}}{\sin(\beta_{i,r})} \\
& \begin{pmatrix} w_{u_{i,r}} \\ w_{a_{i,r}} \end{pmatrix} = w_{i,r} \cdot \begin{pmatrix} \cos(\beta_{i,r}) \\ \sin(\beta_{i,r}) \end{pmatrix} \\
& T_{i,r}^* = T_{i,av(N_r)}^* - (c_{i,r})^2 - (w_{i,r})^2
\end{aligned}$$

$$m_i \cdot (m_i + 1) \cdot \left( R_{\text{st}(i,a)}, r \cdot R_{\text{st}(i,a),av(N_r)} \right)^{2 \cdot m_i + 1}$$

$$\begin{aligned}
T_{w_{i,r}}^* &= T_{i,r} - \frac{k_{i,r}}{k_{i,r} - 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \\
a_{w_{i,r}}^* &= \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \cdot T_{w_{i,r}}^*} \\
\lambda_{w_{i,r}} &= \frac{w_{i,r}}{a_{w_{i,r}}^*} \\
M_{w_{i,r}} &= \frac{w_{i,r}}{a_{3B_{i,r}}}
\end{aligned}$$

for  $i \in 1..Z$

for  $r \in 1..N_r$

$$\begin{aligned}
&\begin{pmatrix} \Delta c_{a_{st(i,1),r}} \\ \Delta c_{a_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} c_{a_{st(i,2),r}} - c_{a_{st(i,1),r}} \\ c_{a_{st(i,3),r}} - c_{a_{st(i,2),r}} \end{pmatrix} \\
R_{L_{i,r}} &= 1 - \frac{c_{u_{st(i,2),r}} - c_{u_{st(i,3),r}}}{u_{st(i,2),r} + u_{st(i,3),r}} \\
\varepsilon_{stator_{i,r}} &= \begin{cases} \alpha_{st(i,2),r} - \alpha_{st(i,1),r} & \text{if } \alpha_{st(i,2),r} \geq \frac{\pi}{2} \\ \alpha_{st(i,1),r} - \alpha_{st(i,2),r} & \text{otherwise} \end{cases} \\
\varepsilon_{rotor_{i,r}} &= \begin{cases} \beta_{st(i,3),r} - \beta_{st(i,2),r} & \text{if } \beta_{st(i,3),r} \geq \frac{\pi}{2} \\ \beta_{st(i,2),r} - \beta_{st(i,3),r} & \text{otherwise} \end{cases}
\end{aligned}$$

$$\begin{pmatrix} P^* & T^* & T & \rho^* & k & a_c^* & a_{3B} & c & c_u & c_a & \Delta c_a & \alpha & \lambda_c & \lambda_w & \varepsilon_{stator} \end{pmatrix}^T$$

$$\begin{pmatrix} P & T_w^* & T & \rho & R_L & a_w^* & a_{3B} & w & w_u & w_a & \Delta c_a & \beta & M_c & M_w & \varepsilon_{rotor} \end{pmatrix}^T$$

$\rho^{*T}$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 927.5 | 914.5 | 676.5 | 665.4 | 483.0 | 475.7 | 337.5 | 332.0 | 228.6 |
| 2 | 927.5 | 914.5 | 676.5 | 665.4 | 483.0 | 475.7 | 337.5 | 332.0 | 228.6 |
| 3 | 927.5 | 914.5 | 676.5 | 665.4 | 483.0 | 475.7 | 337.5 | 332.0 | 228.6 |

$\cdot 10^3$

$T^{*T}$

|   | 1    | 2    | 3    | 4    | 5    | 6    | 7    | 8    | 9    |
|---|------|------|------|------|------|------|------|------|------|
| 1 | 1369 | 1370 | 1281 | 1282 | 1192 | 1193 | 1102 | 1104 | 1011 |
| 2 | 1369 | 1370 | 1281 | 1282 | 1192 | 1193 | 1102 | 1104 | 1011 |
| 3 | 1369 | 1370 | 1281 | 1282 | 1192 | 1193 | 1102 | 1104 | 1011 |

$T^{*T}_w$

|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8      |
|---|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 1381.3 | 1313.8 | 1273.3 | 1222.9 | 1197.1 | 1130.2 | 1120.2 | 1036.6 |
| 2 | 1383.0 | 1313.1 | 1278.7 | 1222.6 | 1203.3 | 1130.7 | 1126.9 | 1038.0 |
| 3 | 1384.8 | 1312.5 | 1284.4 | 1222.5 | 1209.8 | 1131.5 | 1133.9 | ...    |

$\rho^{*T}$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 2.349 | 2.314 | 1.830 | 1.799 | 1.404 | 1.382 | 1.061 | 1.043 | 0.784 |
| 2 | 2.349 | 2.314 | 1.830 | 1.799 | 1.404 | 1.382 | 1.061 | 1.043 | 0.784 |
| 3 | 2.349 | 2.314 | 1.830 | 1.799 | 1.404 | 1.382 | 1.061 | 1.043 | 0.784 |

$\rho^T$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 890.0 | 631.4 | 635.8 | 459.5 | 458.6 | 325.0 | 317.3 | 215.2 | 208.2 |
| 2 | 890.0 | 660.5 | 638.1 | 481.1 | 459.0 | 339.4 | 317.3 | 225.8 | 208.2 |
| 3 | 890.0 | 686.7 | 639.3 | 500.3 | 459.2 | 352.3 | 317.3 | 235.2 | 208.2 |

$\cdot 10^3$

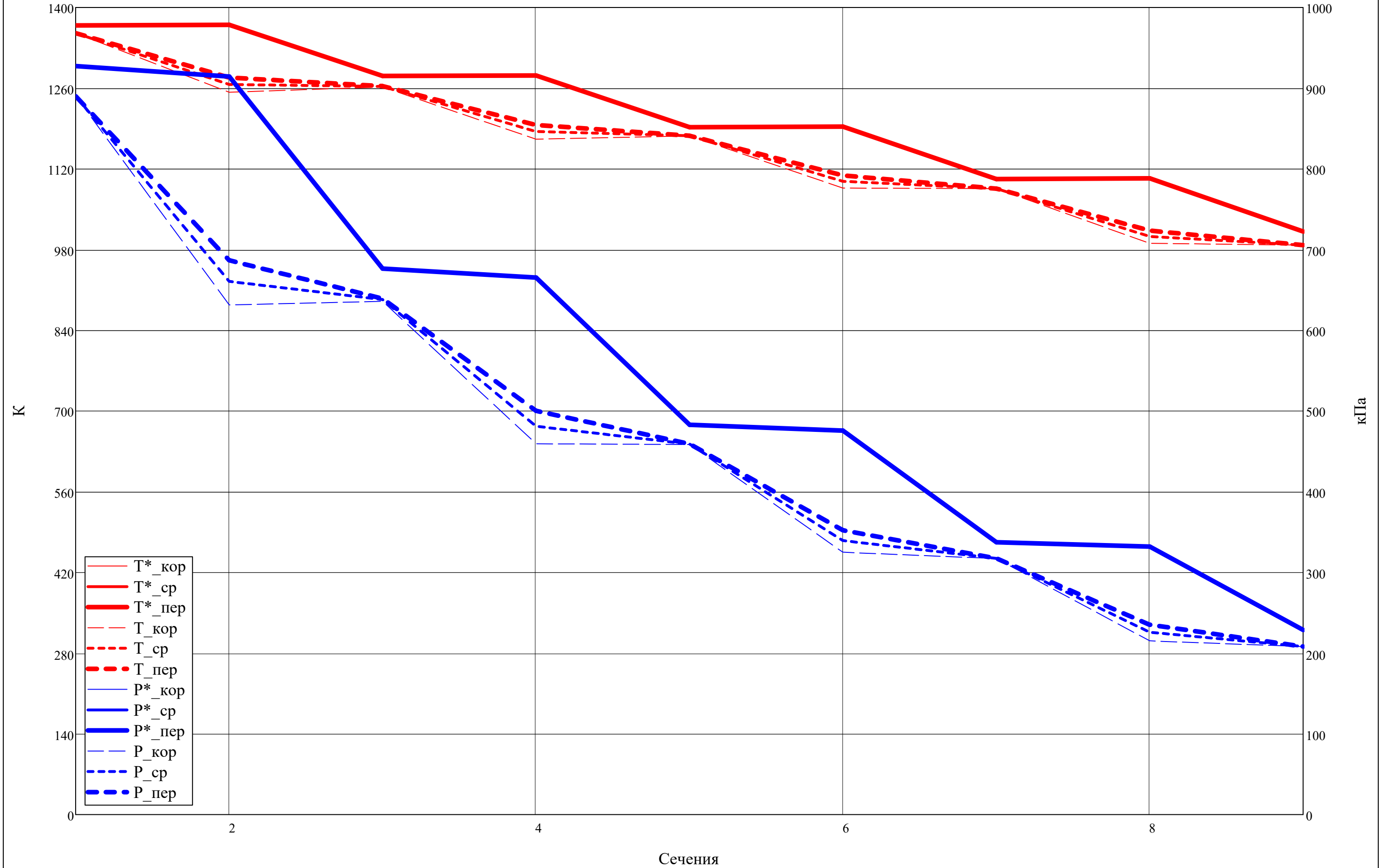
$T^T$

|   | 1    | 2    | 3    | 4    | 5    | 6    | 7    | 8    | 9   |
|---|------|------|------|------|------|------|------|------|-----|
| 1 | 1355 | 1253 | 1262 | 1172 | 1177 | 1087 | 1086 | 991  | 988 |
| 2 | 1355 | 1267 | 1263 | 1185 | 1178 | 1098 | 1086 | 1003 | 988 |
| 3 | 1355 | 1278 | 1264 | 1196 | 1178 | 1108 | 1086 | 1013 | 988 |

$\rho^T$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 2.276 | 1.747 | 1.747 | 1.360 | 1.350 | 1.037 | 1.013 | 0.753 | 0.731 |
| 2 | 2.276 | 1.808 | 1.751 | 1.408 | 1.351 | 1.071 | 1.013 | 0.781 | 0.731 |
| 3 | 2.276 | 1.862 | 1.754 | 1.450 | 1.352 | 1.102 | 1.013 | 0.805 | 0.731 |

Термодинамические параметры по тракту К



$k^T =$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |
| 2 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |
| 3 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |

$R_L^T =$

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | 0.0536 | 0.0511 | 0.0925 | 0.1037 |
| 2 | 0.0913 | 0.1091 | 0.1574 | 0.1829 |
| 3 | 0.1251 | 0.1592 | 0.2136 | 0.2505 |

$R_L^T \geq 0.05 =$

|   | 1 | 2 | 3 | 4 |
|---|---|---|---|---|
| 1 | 1 | 1 | 1 | 1 |
| 2 | 1 | 1 | 1 | 1 |
| 3 | 1 | 1 | 1 | 1 |

$$a_c^* =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |
| 2 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |
| 3 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |

$$u =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 172.2 | 172.2 | 180.7 | 193.8 | 208.2 | 222.8 | 234.2 | 240.3 | 240.3 |
| 2 | 183.8 | 185.7 | 195.4 | 209.3 | 224.4 | 239.4 | 251.6 | 258.7 | 260.0 |
| 3 | 195.3 | 199.1 | 210.0 | 224.7 | 240.5 | 256.1 | 268.9 | 277.0 | 279.7 |

$$c =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 529.2 | 213.2 | 511.7 | 188.5 | 500.3 | 197.2 | 511.5 | 232.4 |
| 2 | 180.0 | 497.3 | 207.2 | 480.3 | 186.8 | 472.2 | 197.0 | 483.7 | 232.4 |
| 3 | 180.0 | 467.8 | 203.7 | 451.5 | 186.0 | 446.4 | 197.0 | 458.7 | 232.4 |

$$c_u =$$

|   | 1   | 2     | 3     | 4     | 5    | 6     | 7    | 8     | 9     |
|---|-----|-------|-------|-------|------|-------|------|-------|-------|
| 1 | 0.0 | 476.1 | 142.0 | 459.1 | 77.6 | 444.1 | 29.4 | 444.1 | 13.3  |
| 2 | 0.0 | 458.8 | 112.6 | 441.4 | 55.1 | 426.8 | 13.1 | 424.0 | 0.2   |
| 3 | 0.0 | 444.5 | 86.6  | 426.4 | 35.3 | 411.8 | -1.1 | 406.3 | -10.9 |

$$c_a =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 231.2 | 159.0 | 226.1 | 171.8 | 230.5 | 195.0 | 253.8 | 232.0 |
| 2 | 180.0 | 191.7 | 173.9 | 189.4 | 178.5 | 202.0 | 196.6 | 232.9 | 232.4 |
| 3 | 180.0 | 145.6 | 184.4 | 148.3 | 182.6 | 172.4 | 197.0 | 212.9 | 232.1 |

$$\Delta c_a =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7    | 8     |
|---|-------|-------|-------|-------|-------|-------|------|-------|
| 1 | 51.2  | -72.2 | 67.1  | -54.3 | 58.7  | -35.5 | 58.8 | -21.8 |
| 2 | 11.7  | -17.8 | 15.5  | -11.0 | 23.5  | -5.4  | 36.3 | -0.5  |
| 3 | -34.4 | 38.7  | -36.1 | 34.4  | -10.3 | 24.6  | 15.9 | 19.2  |

$$a_w^* =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 673.1 | 656.4 | 646.6 | 633.7 | 627.5 | 609.7 | 607.5 | 584.4 | 584.3 |
| 2 | 673.5 | 656.3 | 648.0 | 633.7 | 629.1 | 609.8 | 609.4 | 584.8 | 586.3 |
| 3 | 674.0 | 656.1 | 649.5 | 633.6 | 630.8 | 610.0 | 611.2 | 585.3 | 588.3 |

$$a_{3B} =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 717.7 | 690.0 | 693.6 | 668.3 | 671.1 | 644.7 | 645.8 | 616.9 | 617.4 |
| 2 | 717.7 | 693.8 | 693.9 | 672.0 | 671.1 | 648.2 | 645.8 | 620.6 | 617.4 |
| 3 | 717.7 | 697.0 | 694.0 | 675.2 | 671.2 | 651.1 | 645.8 | 623.7 | 617.5 |

$$w =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 249.1 | 381.8 | 163.6 | 348.6 | 215.8 | 319.5 | 282.8 | 325.5 | 324.6 |
| 2 | 257.2 | 333.7 | 192.6 | 299.6 | 246.0 | 275.5 | 309.0 | 285.6 | 348.6 |
| 3 | 265.6 | 285.4 | 221.9 | 250.3 | 274.7 | 232.3 | 334.2 | 249.1 | 371.9 |

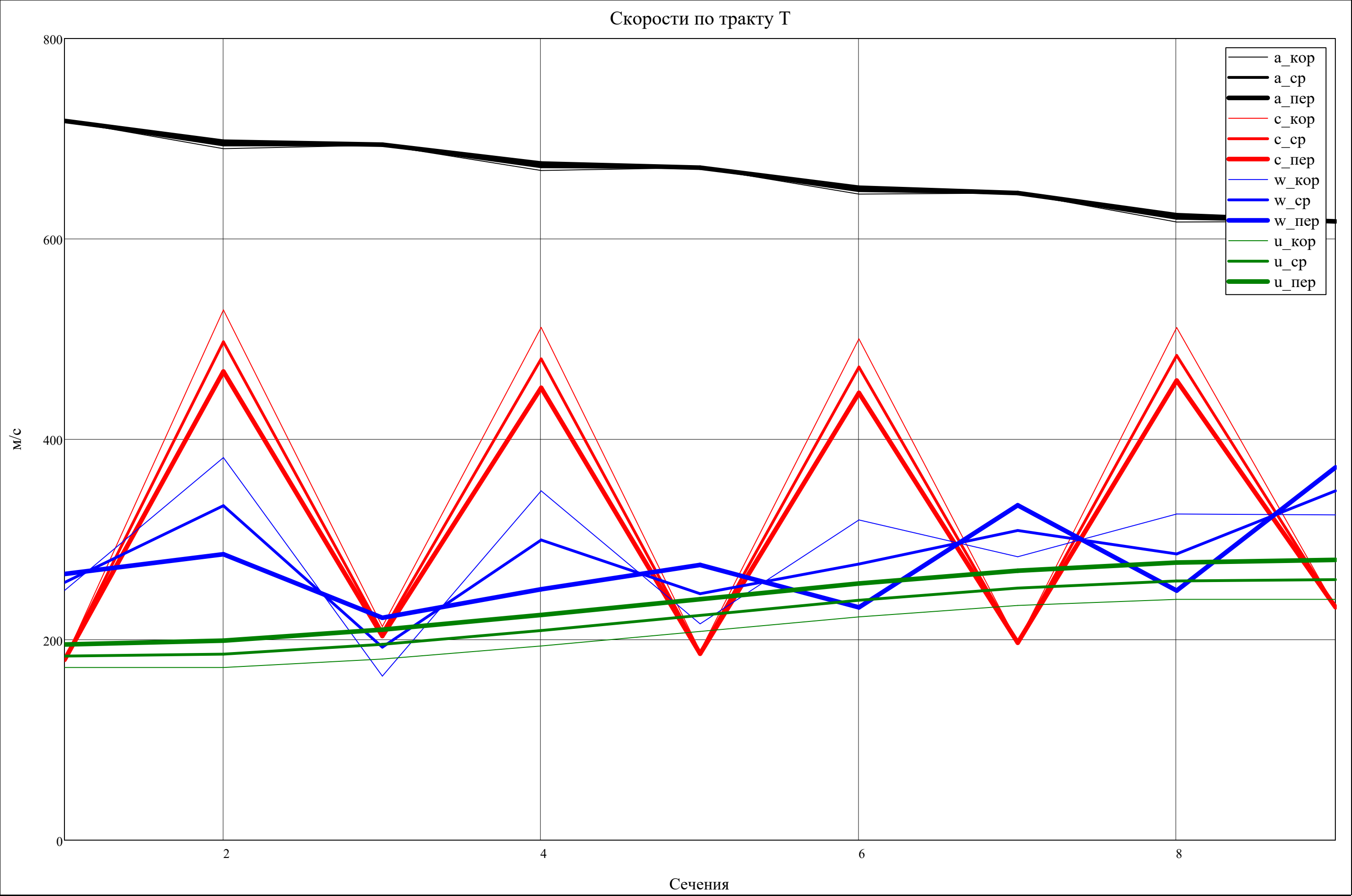
$$w_u =$$

|   | 1     | 2      | 3     | 4      | 5     | 6      | 7     | 8      |
|---|-------|--------|-------|--------|-------|--------|-------|--------|
| 1 | 172.2 | -303.8 | 38.6  | -265.3 | 130.6 | -221.3 | 204.8 | -203.8 |
| 2 | 183.8 | -273.2 | 82.8  | -232.1 | 169.3 | -187.4 | 238.5 | -165.3 |
| 3 | 195.3 | -245.4 | 123.5 | -201.7 | 205.2 | -155.7 | 270.0 | ...    |

$$w_a =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 231.2 | 159.0 | 226.1 | 171.8 | 230.5 | 195.0 | 253.8 | 232.0 |
| 2 | 180.0 | 191.7 | 173.9 | 189.4 | 178.5 | 202.0 | 196.6 | 232.9 | 232.4 |
| 3 | 180.0 | 145.6 | 184.4 | 148.3 | 182.6 | 172.4 | 197.0 | 212.9 | 232.1 |





$\alpha^T =$ 

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 90.00 | 25.90 | 48.23 | 26.23 | 65.69 | 27.43 | 81.44 | 29.75 | 86.72 |
| 2 | 90.00 | 22.68 | 57.09 | 23.23 | 72.85 | 25.32 | 86.19 | 28.78 | 89.96 |
| 3 | 90.00 | 18.14 | 64.85 | 19.18 | 79.08 | 22.71 | 90.31 | 27.66 | 92.70 |

$\alpha^T =$

$80^{\circ} \leq \alpha^T =$ 

|   |   |   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|---|---|
|   | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 2 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 3 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |

$80^{\circ} \leq \alpha^T =$

[1, c.78]

Угол поворота потока:

$\epsilon_{\text{stator}}^T =$ 

|   |       |       |       |       |
|---|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     |
| 1 | 64.10 | 22.00 | 38.26 | 51.69 |
| 2 | 67.32 | 33.86 | 47.53 | 57.40 |
| 3 | 71.86 | 45.67 | 56.37 | 62.65 |

$\epsilon_{\text{stator}}^T =$

$\epsilon_{\text{stator}}^T =$

$\beta^T =$ 

|   |       |        |       |        |       |        |       |        |
|---|-------|--------|-------|--------|-------|--------|-------|--------|
|   | 1     | 2      | 3     | 4      | 5     | 6      | 7     | 8      |
| 1 | 46.26 | 142.73 | 76.34 | 139.56 | 52.76 | 133.84 | 43.59 | 128.76 |
| 2 | 44.41 | 144.94 | 64.54 | 140.78 | 46.51 | 132.86 | 39.50 | 125.36 |
| 3 | 42.67 | 149.32 | 56.19 | 143.67 | 41.67 | 132.10 | 36.12 | ...    |

$\beta^T =$

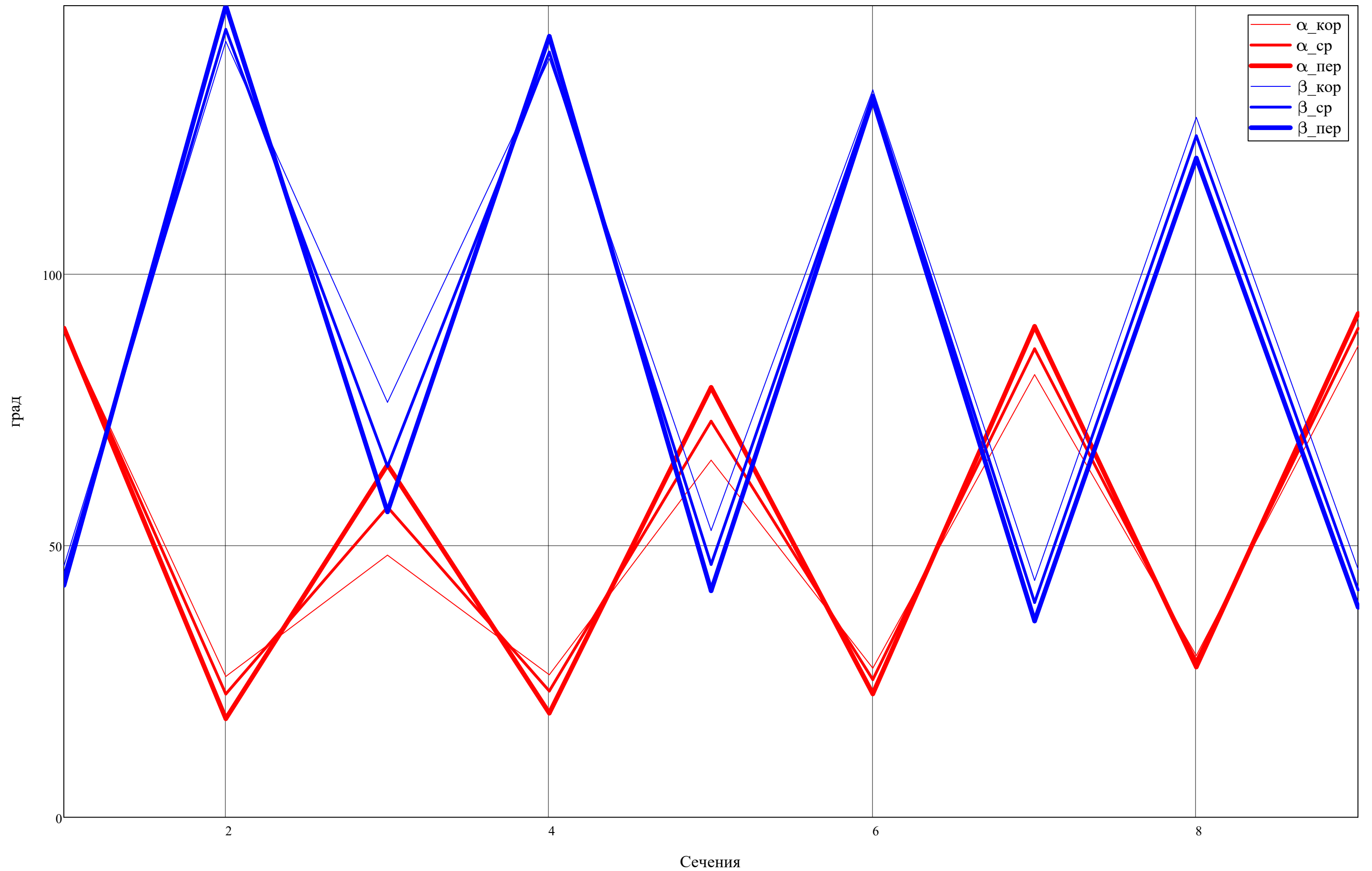
$\epsilon_{\text{rotor}}^T =$ 

|   |       |        |       |       |
|---|-------|--------|-------|-------|
|   | 1     | 2      | 3     | 4     |
| 1 | 66.39 | 86.80  | 90.25 | 83.14 |
| 2 | 80.39 | 94.27  | 93.36 | 83.56 |
| 3 | 93.13 | 102.01 | 95.98 | 82.65 |

$\epsilon_{\text{rotor}}^T =$

$\epsilon_{\text{rotor}}^T =$

Углы по тракту К



$\lambda_c^T =$ 

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 0.269 | 0.790 | 0.329 | 0.789 | 0.301 | 0.799 | 0.327 | 0.848 | 0.402 |
| 2 | 0.269 | 0.742 | 0.319 | 0.740 | 0.298 | 0.754 | 0.327 | 0.802 | 0.402 |
| 3 | 0.269 | 0.698 | 0.314 | 0.696 | 0.297 | 0.713 | 0.327 | 0.761 | 0.402 |

$M_c^T =$ 

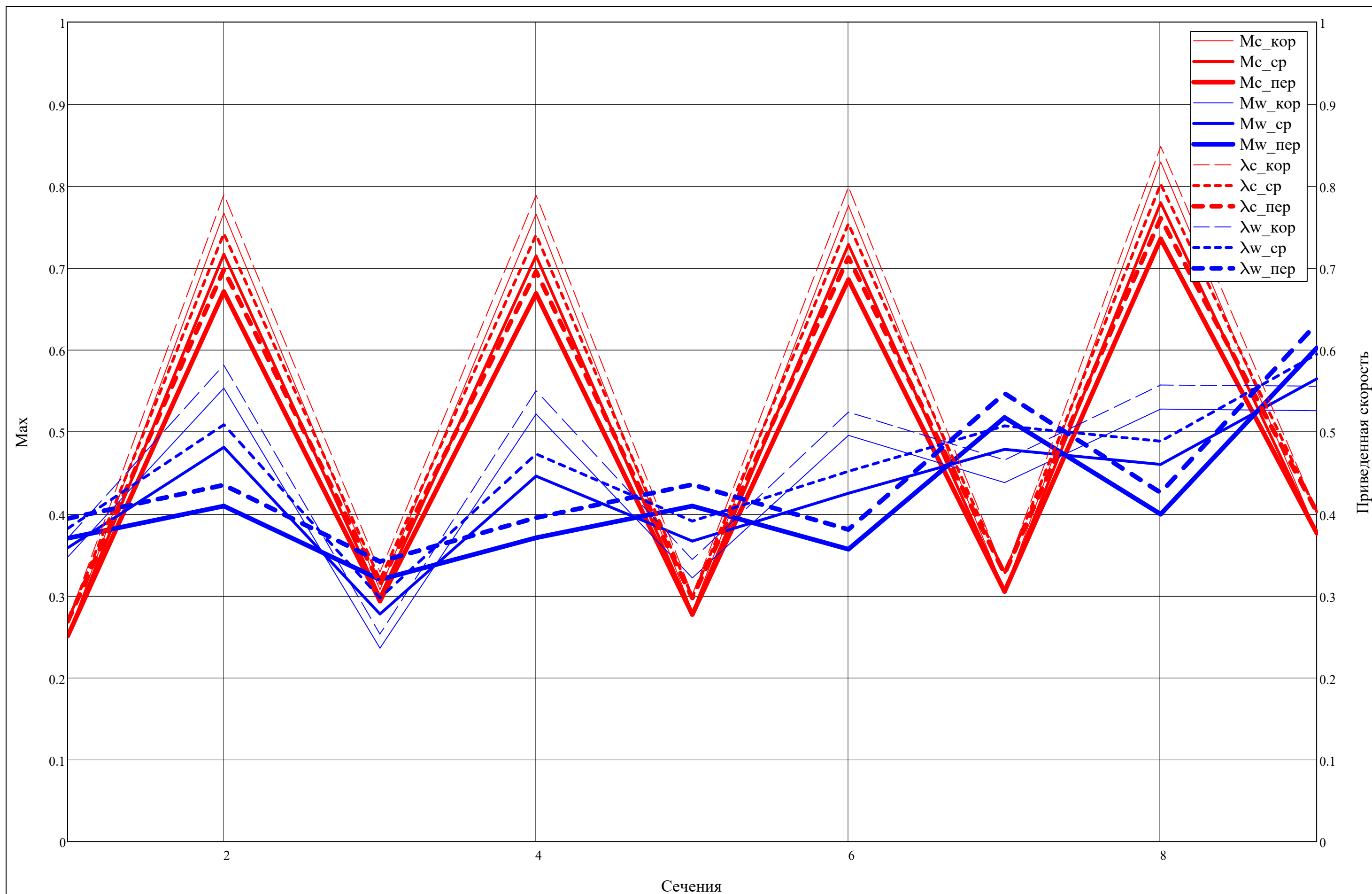
|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 0.251 | 0.767 | 0.307 | 0.766 | 0.281 | 0.776 | 0.305 | 0.829 | 0.376 |
| 2 | 0.251 | 0.717 | 0.299 | 0.715 | 0.278 | 0.728 | 0.305 | 0.779 | 0.376 |
| 3 | 0.251 | 0.671 | 0.293 | 0.669 | 0.277 | 0.686 | 0.305 | 0.735 | 0.376 |

$\lambda_w^T =$ 

|   |       |       |       |       |       |       |       |       |       |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     | 9     |
| 1 | 0.370 | 0.582 | 0.253 | 0.550 | 0.344 | 0.524 | 0.465 | 0.557 | 0.556 |
| 2 | 0.382 | 0.509 | 0.297 | 0.473 | 0.391 | 0.452 | 0.507 | 0.488 | 0.595 |
| 3 | 0.394 | 0.435 | 0.342 | 0.395 | 0.436 | 0.381 | 0.547 | 0.426 | 0.632 |

$M_w^T =$ 

|   |     |     |     |     |     |     |     |     |     |
|---|-----|-----|-----|-----|-----|-----|-----|-----|-----|
|   | 1   | 2   | 3   | 4   | 5   | 6   | 7   | 8   | 9   |
| 1 | 0.3 | 0.6 | 0.2 | 0.5 | 0.3 | 0.5 | 0.4 | 0.5 | 0.5 |
| 2 | 0.4 | 0.5 | 0.3 | 0.4 | 0.4 | 0.4 | 0.5 | 0.5 | 0.6 |
| 3 | 0.4 | 0.4 | 0.3 | 0.4 | 0.4 | 0.4 | 0.5 | 0.4 | 0.6 |







Рассматриваемая ступень:

j =

j = Z

j =

"Такой ступени не существует!" if (j < 1) ∨ (j > Z)

j otherwise

= 4

▼Построение треугольников скоростей в 3х сечениях

Δ<sub>c</sub>(v,i,j,r) =

tan(α<sub>st(i,j),r</sub>)·v if (tan(α<sub>st(i,j),r</sub>) ≥ 0) ∧ (−|c<sub>st(i,j),r</sub>·cos(α<sub>st(i,j),r</sub>)| ≤ v ≤ 0)

tan(α<sub>st(i,j),r</sub>)·v if (tan(α<sub>st(i,j),r</sub>) < 0) ∧ (0 ≤ v ≤ |c<sub>st(i,j),r</sub>·cos(α<sub>st(i,j),r</sub>)|)

Δ<sub>w</sub>(v,i,j,r) =

−tan(β<sub>st(i,j),r</sub>)·v if (−tan(β<sub>st(i,j),r</sub>) ≥ 0) ∧ (−|w<sub>st(i,j),r</sub>·cos(β<sub>st(i,j),r</sub>)| ≤ v ≤ 0) ∧ (j ≠ 1)

−tan(β<sub>st(i,j),r</sub>)·v if (−tan(β<sub>st(i,j),r</sub>) < 0) ∧ (0 ≤ v ≤ |w<sub>st(i,j),r</sub>·cos(β<sub>st(i,j),r</sub>)|) ∧ (j ≠ 1)

Δ<sub>u</sub>(v,i,j,r) =

−c<sub>a<sub>st(i,j),r</sub></sub> if (−c<sub>st(i,j),r</sub>·cos(α<sub>st(i,j),r</sub>) ≤ v ≤ w<sub>st(i,j),r</sub>·cos(β<sub>st(i,j),r</sub>)) ∧ (j ≠ 1)

NaN otherwise

v<sub>lim</sub> =

ceil

max(c,w,u)

10<sup>2</sup>

·10<sup>2</sup> = 600.0

v =

−max(c,w,u), −max(c,w,u) +

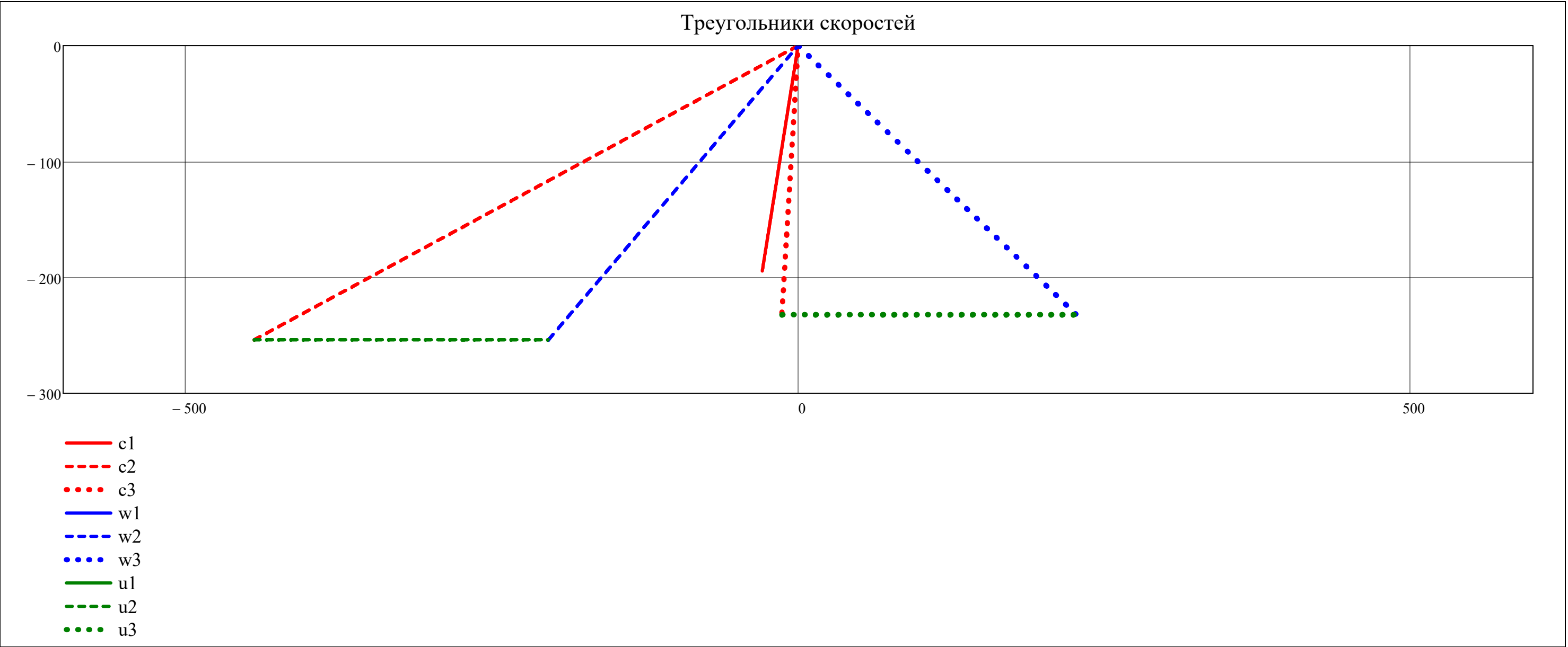
max(c,w,u)

3000

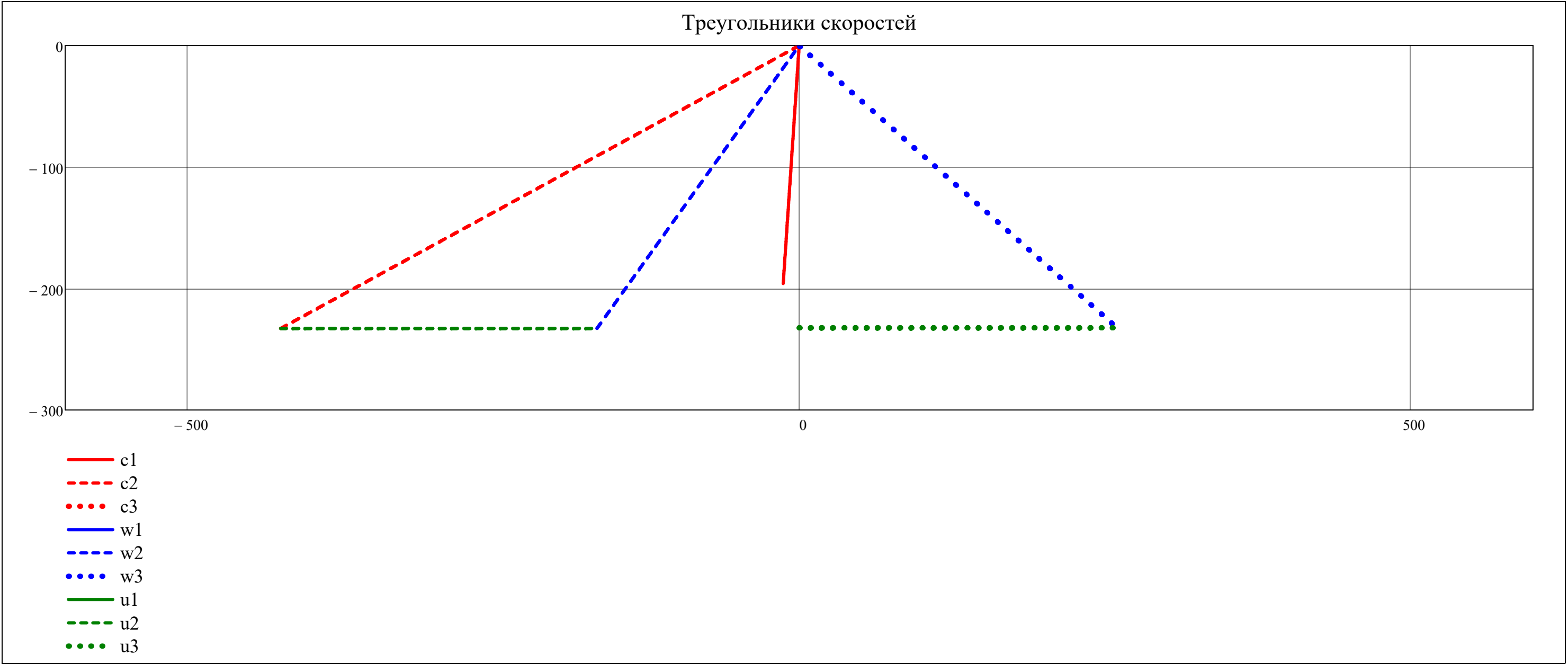
.. max(c,w,u)



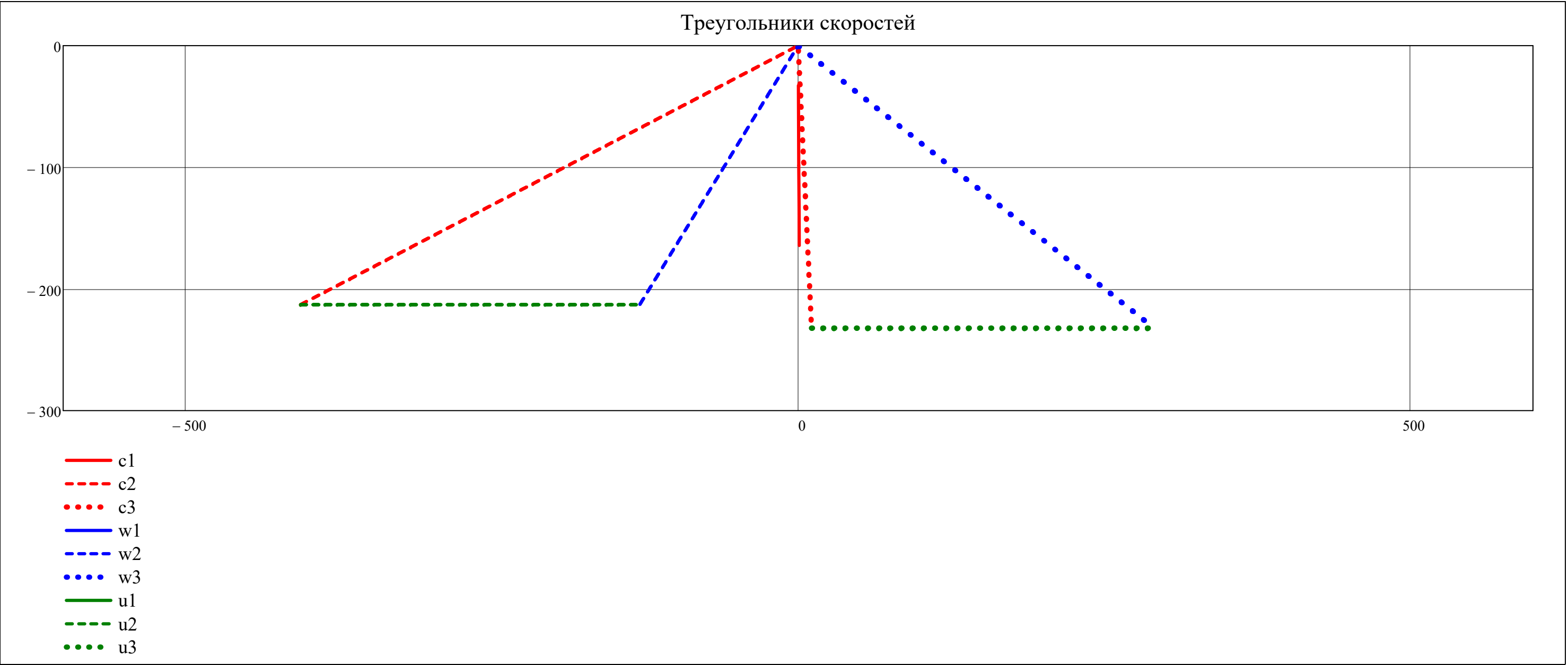
r = 1



$\bar{r}_w = \text{av}(N_r)$



$r_w = N_r$



Построение треугольников скоростей в 3х сечениях

Парусность:

sail<sub>stator</sub>

sail<sub>rotor</sub>

=

1

0.85

▼ Расчет хорд Л по парусности

chord<sub>stator</sub>

chord<sub>rotor</sub>

=

for i ∈ 1..Z

sail =  $\frac{R_{st(i,2),N_r} - R_{st(i,2),1}}{R_{st(i,2),av(N_r)} - R_{st(i,2),1}}$

for r ∈ 1..N<sub>r</sub>

chord<sub>stator</sub><sub>i,av(N<sub>r</sub>)</sub> · sail

b<sub>CAkop</sub> =  $\frac{\hspace{1.5cm}}{sail_{stator} - 1 + sail}$

chord<sub>rotor</sub><sub>i,av(N<sub>r</sub>)</sub> · sail

b<sub>PKkop</sub> =  $\frac{\hspace{1.5cm}}{sail_{rotor} - 1 + sail}$

(b<sub>CAпер</sub>)

(b<sub>PKпер</sub>)

=

b<sub>CAkop</sub> · sail<sub>stator</sub>

b<sub>PKkop</sub> · sail<sub>rotor</sub>

chord<sub>stator</sub>.(z) = interp

cspline

R<sub>st(i,2),1</sub>

R<sub>st(i,2),av(N<sub>r</sub>)</sub>

R<sub>st(i,2),N<sub>r</sub></sub>

b<sub>CAkop</sub>

chord<sub>stator</sub><sub>i,av(N<sub>r</sub>)</sub>

b<sub>CAпер</sub>

R<sub>st(i,2),1</sub>

R<sub>st(i,2),av(N<sub>r</sub>)</sub>

R<sub>st(i,2),N<sub>r</sub></sub>

b<sub>CAkop</sub>

chord<sub>stator</sub><sub>i,av(N<sub>r</sub>)</sub>

b<sub>CAпер</sub>

,z

chord<sub>rotor</sub>.(z) = interp

cspline

R<sub>st(i,2),1</sub>

R<sub>st(i,2),av(N<sub>r</sub>)</sub>

R<sub>st(i,2),N<sub>r</sub></sub>

b<sub>PKkop</sub>

chord<sub>rotor</sub><sub>i,av(N<sub>r</sub>)</sub>

b<sub>PKпер</sub>

R<sub>st(i,2),1</sub>

R<sub>st(i,2),av(N<sub>r</sub>)</sub>

R<sub>st(i,2),N<sub>r</sub></sub>

b<sub>PKkop</sub>

chord<sub>rotor</sub><sub>i,av(N<sub>r</sub>)</sub>

b<sub>PKпер</sub>

,z

chord<sub>stator</sub><sub>i,r</sub>

chord<sub>rotor</sub><sub>i,r</sub>

=

chord<sub>stator</sub>.(R<sub>st(i,2),r</sub>)

chord<sub>rotor</sub>.(R<sub>st(i,3),r</sub>)

chord<sub>stator</sub>

chord<sub>rotor</sub>

Длины хорд РК и СА (м):

chord<sub>stator</sub><sup>T</sup> =

|   |      |      |      |      |
|---|------|------|------|------|
|   | 1    | 2    | 3    | 4    |
| 1 | 58.6 | 50.6 | 60.3 | 69.3 |
| 2 | 58.6 | 50.6 | 60.3 | 69.3 |
| 3 | 58.6 | 50.6 | 60.3 | 69.3 |

·10<sup>−3</sup>

chord<sub>rotor</sub><sup>T</sup> =

|   |      |      |      |      |
|---|------|------|------|------|
|   | 1    | 2    | 3    | 4    |
| 1 | 32.4 | 36.4 | 42.0 | 45.8 |
| 2 | 29.6 | 33.4 | 38.5 | 42.1 |
| 3 | 25.3 | 27.9 | 33.0 | 38.2 |

·10<sup>−3</sup>

▲ Расчет хорд Л по парусности

60

Ср. линия профиля:  
0.5 - дуга окружности  
0.45 - парабола

$\overline{x_f} = 0.45$

Расчет параметров решетки

$t_{\text{sator}}$

$r_{\text{inlet}}_{\text{sator}}$

$r_{\text{outlet}}_{\text{sator}}$

$c_{\text{sator}}$

$v_{\text{sator}}$

$t_{\text{rotor}}$

$r_{\text{inlet}}_{\text{rotor}}$

$r_{\text{outlet}}_{\text{rotor}}$

$c_{\text{rotor}}$

$v_{\text{rotor}}$

=

for i ∈ 1..Z

for r ∈ 1..N<sub>r</sub>

$t_{\text{sator}}_{i,r}$

$t_{\text{rotor}}_{i,r}$

$= \pi \cdot \frac{\frac{\text{mean}(D_{\text{st}(i,1)},r,D_{\text{st}(i,2)},r)}{Z_{\text{sator}_i}}}{\frac{\text{mean}(D_{\text{st}(i,2)},r,D_{\text{st}(i,3)},r)}{Z_{\text{rotor}_i}}}$

$r_{\text{inlet}}_{\text{sator}_{i,r}}$

$r_{\text{outlet}}_{\text{sator}_{i,r}}$

$= \left( \frac{r_{\text{inlet}}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}}}{r_{\text{inlet}}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}}} \cdot \frac{r_{\text{outlet}}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}}}{r_{\text{outlet}}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}}} \right)$

$c_{\text{sator}_{i,r}}$

$c_{\text{rotor}_{i,r}}$

$= \left( \frac{\overline{c}_{\text{sator}_{i,r}} \cdot \text{chord}_{\text{sator}_{i,r}}}{\overline{c}_{\text{rotor}_{i,r}} \cdot \text{chord}_{\text{rotor}_{i,r}}} \right)$

$v_{\text{sator}_{i,r}}$

$v_{\text{rotor}_{i,r}}$

$= \left( \frac{v_{\text{installation}}(0.5, \alpha_{\text{st}(i,1)},r, \alpha_{\text{st}(i,2)},r)}{v_{\text{installation}}(0.5, \beta_{\text{st}(i,2)},r, \beta_{\text{st}(i,3)},r)} \right) + \frac{\pi}{2}$

$t_{\text{sator}}$

$r_{\text{inlet}}_{\text{sator}}$

$r_{\text{outlet}}_{\text{sator}}$

$c_{\text{sator}}$

$v_{\text{sator}}$

$t_{\text{rotor}}$

$r_{\text{inlet}}_{\text{rotor}}$

$r_{\text{outlet}}_{\text{rotor}}$

$c_{\text{rotor}}$

$v_{\text{rotor}}$

$v_{\text{установки}}(\alpha_{\text{st}(i,1)},r, \alpha_{\text{st}(i,2)},r)$

$v_{\text{установки}}(\beta_{\text{st}(i,2)},r, \beta_{\text{st}(i,3)},r)$

$\frac{\pi}{2}$  добавляется в виду поворота рисунка на 90 град

Расчет параметров решетки

61

Относительные радиусы профилей (°):

|                                      |   |       |       |       |       |    |
|--------------------------------------|---|-------|-------|-------|-------|----|
| $\overline{r}_{inlet_{stator}}^T =$  |   | 1     | 2     | 3     | 4     | .% |
|                                      | 1 | 4.400 | 4.400 | 4.400 | 4.400 |    |
|                                      | 2 | 4.400 | 4.400 | 4.400 | 4.400 |    |
|                                      | 3 | 4.400 | 4.400 | 4.400 | 4.400 |    |
| $\overline{r}_{outlet_{stator}}^T =$ |   | 1     | 2     | 3     | 4     | .% |
|                                      | 1 | 2.200 | 2.200 | 2.200 | 2.200 |    |
|                                      | 2 | 2.200 | 2.200 | 2.200 | 2.200 |    |
|                                      | 3 | 2.200 | 2.200 | 2.200 | 2.200 |    |
| $\overline{r}_{inlet_{rotor}}^T =$   |   | 1     | 2     | 3     | 4     | .% |
|                                      | 1 | 3.900 | 3.900 | 3.900 | 3.900 |    |
|                                      | 2 | 3.300 | 3.300 | 3.300 | 3.300 |    |
|                                      | 3 | 2.100 | 2.100 | 2.100 | 2.100 |    |
| $\overline{r}_{outlet_{rotor}}^T =$  |   | 1     | 2     | 3     | 4     | .% |
|                                      | 1 | 1.300 | 1.300 | 1.300 | 1.300 |    |
|                                      | 2 | 1.100 | 1.100 | 1.100 | 1.100 |    |
|                                      | 3 | 0.700 | 0.700 | 0.700 | 0.700 |    |

Относительная толщина профиля (°):

|                             |   |       |       |       |       |    |
|-----------------------------|---|-------|-------|-------|-------|----|
| $\overline{c}_{stator}^T =$ |   | 1     | 2     | 3     | 4     | .% |
|                             | 1 | 11.00 | 11.00 | 11.00 | 11.00 |    |
|                             | 2 | 11.00 | 11.00 | 11.00 | 11.00 |    |
|                             | 3 | 11.00 | 11.00 | 11.00 | 11.00 |    |
| $\overline{c}_{rotor}^T =$  |   | 1     | 2     | 3     | 4     | .% |
|                             | 1 | 13.00 | 13.00 | 13.00 | 13.00 |    |
|                             | 2 | 11.00 | 11.00 | 11.00 | 11.00 |    |
|                             | 3 | 7.00  | 7.00  | 7.00  | 7.00  |    |

Относительный шаг решетки (°):

|  |   |        |        |        |        |
|--|---|--------|--------|--------|--------|
| $\left(\frac{t_{stator}}{chord_{stator}}\right)^T =$ |   | 1      | 2      | 3      | 4      |
|  | 1 | 0.6926 | 0.5508 | 0.5945 | 0.6251 |
|  | 2 | 0.7428 | 0.5952 | 0.6398 | 0.6721 |
|  | 3 | 0.7930 | 0.6396 | 0.6850 | 0.7192 |
| $\left(\frac{t_{rotor}}{chord_{rotor}}\right)^T =$   |   | 1      | 2      | 3      | 4      |
|  | 1 | 0.5757 | 0.6062 | 0.6355 | 0.6251 |
|  | 2 | 0.6801 | 0.7137 | 0.7441 | 0.7336 |
|  | 3 | 0.8563 | 0.9153 | 0.9288 | 0.8681 |

Относительная густота решетки (°):

|  |   |       |       |       |       |
|--|---|-------|-------|-------|-------|
| $\left(\frac{chord_{stator}}{t_{stator}}\right)^T =$ |   | 1     | 2     | 3     | 4     |
|  | 1 | 1.444 | 1.815 | 1.682 | 1.600 |
|  | 2 | 1.346 | 1.680 | 1.563 | 1.488 |
|  | 3 | 1.261 | 1.563 | 1.460 | 1.391 |
| $\left(\frac{chord_{rotor}}{t_{rotor}}\right)^T =$   |   | 1     | 2     | 3     | 4     |
|  | 1 | 1.737 | 1.650 | 1.574 | 1.600 |
|  | 2 | 1.470 | 1.401 | 1.344 | 1.363 |
|  | 3 | 1.168 | 1.092 | 1.077 | 1.152 |

Длина хорды профиля [м]:

$$\text{chord}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 58.6 & 50.6 & 60.3 & 69.3 \\ \hline 2 & 58.6 & 50.6 & 60.3 & 69.3 \\ \hline 3 & 58.6 & 50.6 & 60.3 & 69.3 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{chord}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 32.4 & 36.4 & 42.0 & 45.8 \\ \hline 2 & 29.6 & 33.4 & 38.5 & 42.1 \\ \hline 3 & 25.3 & 27.9 & 33.0 & 38.2 \\ \hline \end{array} \cdot 10^{-3}$$

Радиусы профилей:

$$\text{r\_inlet}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 2.58 & 2.23 & 2.66 & 3.05 \\ \hline 2 & 2.58 & 2.23 & 2.66 & 3.05 \\ \hline 3 & 2.58 & 2.23 & 2.66 & 3.05 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r\_inlet}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1.26 & 1.42 & 1.64 & 1.79 \\ \hline 2 & 0.98 & 1.10 & 1.27 & 1.39 \\ \hline 3 & 0.53 & 0.59 & 0.69 & 0.80 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r\_outlet}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1.29 & 1.11 & 1.33 & 1.52 \\ \hline 2 & 1.29 & 1.11 & 1.33 & 1.52 \\ \hline 3 & 1.29 & 1.11 & 1.33 & 1.52 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r\_outlet}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.42 & 0.47 & 0.55 & 0.60 \\ \hline 2 & 0.33 & 0.37 & 0.42 & 0.46 \\ \hline 3 & 0.18 & 0.20 & 0.23 & 0.27 \\ \hline \end{array} \cdot 10^{-3}$$

Толщина профиля [м]:

$$\text{c}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 6.45 & 5.57 & 6.64 & 7.62 \\ \hline 2 & 6.45 & 5.57 & 6.64 & 7.62 \\ \hline 3 & 6.45 & 5.57 & 6.64 & 7.62 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{c}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 4.22 & 4.74 & 5.45 & 5.96 \\ \hline 2 & 3.26 & 3.67 & 4.24 & 4.63 \\ \hline 3 & 1.77 & 1.96 & 2.31 & 2.67 \\ \hline \end{array} \cdot 10^{-3}$$

Шаг решетки [м]:

$$\text{t}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 40.6 & 27.9 & 35.9 & 43.3 \\ \hline 2 & 43.6 & 30.1 & 38.6 & 46.6 \\ \hline 3 & 46.5 & 32.4 & 41.3 & 49.8 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{t}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 18.7 & 22.1 & 26.7 & 28.6 \\ \hline 2 & 20.2 & 23.8 & 28.7 & 30.9 \\ \hline 3 & 21.6 & 25.6 & 30.6 & 33.2 \\ \hline \end{array} \cdot 10^{-3}$$

Угол поворота потока:

$\epsilon_{\text{stator}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 64.10 | 22.00 | 38.26 | 51.69 |
| 2 | 67.32 | 33.86 | 47.53 | 57.40 |
| 3 | 71.86 | 45.67 | 56.37 | 62.65 |

 $\text{.}^\circ$

$\epsilon_{\text{rotor}}^T =$ 

|   | 1     | 2      | 3     | 4     |
|---|-------|--------|-------|-------|
| 1 | 66.39 | 86.80  | 90.25 | 83.14 |
| 2 | 80.39 | 94.27  | 93.36 | 83.56 |
| 3 | 93.13 | 102.01 | 95.98 | 82.65 |

 $\text{.}^\circ$

Угол установки профиля:

$\upsilon_{\text{stator}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 134.2 | 124.4 | 130.1 | 136.5 |
| 2 | 129.9 | 123.9 | 129.5 | 136.7 |
| 3 | 123.2 | 120.9 | 127.8 | 136.3 |

 $\text{.}^\circ$

$\upsilon_{\text{rotor}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 142.1 | 136.0 | 134.8 | 138.3 |
| 2 | 136.5 | 132.6 | 133.1 | 137.6 |
| 3 | 130.3 | 128.8 | 131.3 | 137.1 |

 $\text{.}^\circ$

Угол изгиба профиля:

$\pi - \epsilon_{\text{stator}}^T =$ 

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 115.9 | 158.0 | 141.7 | 128.3 |
| 2 | 112.7 | 146.1 | 132.5 | 122.6 |
| 3 | 108.1 | 134.3 | 123.6 | 117.4 |

 $\text{.}^\circ$

$\pi - \epsilon_{\text{rotor}}^T =$ 

|   | 1     | 2    | 3    | 4    |
|---|-------|------|------|------|
| 1 | 113.6 | 93.2 | 89.8 | 96.9 |
| 2 | 99.6  | 85.7 | 86.6 | 96.4 |
| 3 | 86.9  | 78.0 | 84.0 | 97.3 |

 $\text{.}^\circ$



$$\begin{pmatrix} X_U & Y_U \\ X_L & Y_L \end{pmatrix} = \text{NACA}(0,0,100\%,1)$$

Относ. координаты профиля РК и СА:

$$\text{AIRFOIL}_0(x, \text{line}, \overline{f}, \overline{x_f}, \overline{c}) =$$

if  $0 \leq x \leq 1$ 

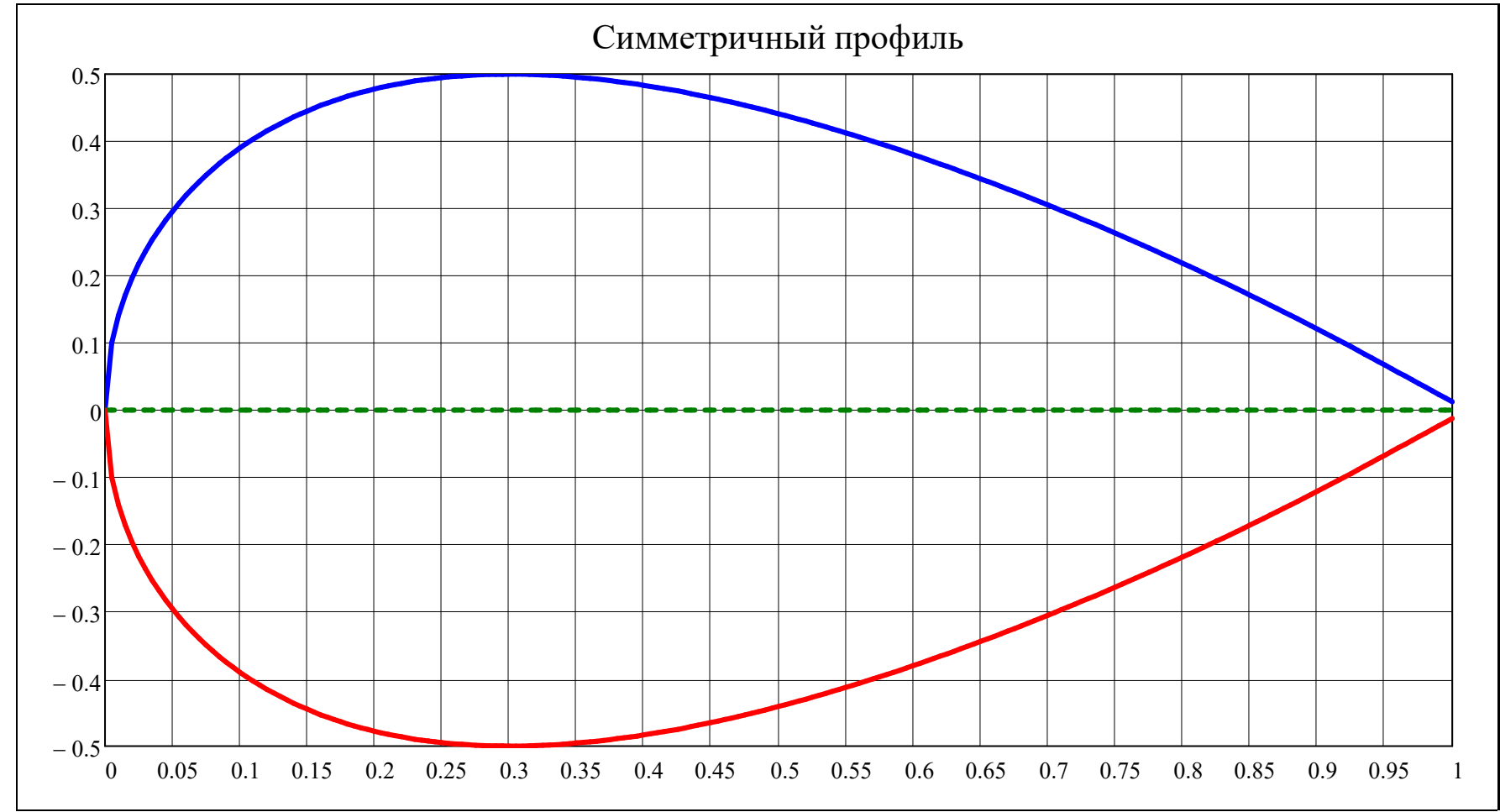
$$\text{linterp}(X_U, Y_U, x)$$
 if line = "+"

$$\frac{\text{linterp}(X_U, Y_U, x) + \text{linterp}(X_L, Y_L, x)}{2}$$
 if line = "0"

$$\text{linterp}(X_L, Y_L, x)$$
 if line = "-"

NaN otherwise

$x = 0, 0.005 \dots 1$



AIRFOIL(x,line,c̄,θ) =

$\text{interp}\left(X_U,y/b_{\text{cp.л}}\left(X_U,\theta\right)+Y_U\cdot\overline{c},x\right)$ 

if line = "+"

$\frac{\text{interp}\left(X_U,y/b_{\text{cp.л}}\left(X_U,\theta\right)+Y_U\cdot\overline{c},x\right)+\text{interp}\left(X_L,y/b_{\text{cp.л}}\left(X_L,\theta\right)+Y_L\cdot\overline{c},x\right)}{2}$ 

if line = "0"

$\text{interp}\left(X_L,y/b_{\text{cp.л}}\left(X_L,\theta\right)+Y_L\cdot\overline{c},x\right)$ 

if line = "-"

NaN

otherwise

Профиль СА на ср. сечении

| x   | y (solid top) | y (dashed) | y (solid bottom) |
|-----|---------------|------------|------------------|
| 0.0 | 0.00          | 0.00       | 0.00             |
| 0.1 | 0.08          | 0.05       | 0.02             |
| 0.2 | 0.14          | 0.08       | 0.04             |
| 0.3 | 0.16          | 0.10       | 0.05             |
| 0.4 | 0.17          | 0.12       | 0.06             |
| 0.5 | 0.18          | 0.13       | 0.07             |
| 0.6 | 0.17          | 0.12       | 0.07             |
| 0.7 | 0.14          | 0.10       | 0.06             |
| 0.8 | 0.08          | 0.05       | 0.04             |
| 0.9 | 0.02          | 0.01       | 0.01             |
| 1.0 | 0.00          | 0.00       | 0.00             |

Профиль РК на ср. сечении

| x   | y (solid top) | y (dashed) | y (solid bottom) |
|-----|---------------|------------|------------------|
| 0.0 | 0.00          | 0.00       | 0.00             |
| 0.1 | 0.12          | 0.08       | 0.04             |
| 0.2 | 0.18          | 0.12       | 0.08             |
| 0.3 | 0.22          | 0.15       | 0.11             |
| 0.4 | 0.24          | 0.17       | 0.13             |
| 0.5 | 0.24          | 0.18       | 0.14             |
| 0.6 | 0.22          | 0.17       | 0.14             |
| 0.7 | 0.18          | 0.15       | 0.13             |
| 0.8 | 0.12          | 0.08       | 0.08             |
| 0.9 | 0.04          | 0.02       | 0.02             |
| 1.0 | 0.00          | 0.00       | 0.00             |

Подключение симметричного профиля

66







$$l_{upper\_stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 64.56 & 52.34 & 63.63 & 74.60 \\ \hline 2 & 64.97 & 53.07 & 64.52 & 75.34 \\ \hline 3 & 65.58 & 53.97 & 65.48 & 76.07 \\ \hline \end{array} \cdot 10^{-3}$$

$$l_{lower\_stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 60.35 & 51.07 & 61.02 & 70.56 \\ \hline 2 & 60.56 & 51.13 & 61.28 & 70.87 \\ \hline 3 & 60.88 & 51.36 & 61.66 & 71.26 \\ \hline \end{array} \cdot 10^{-3}$$

$$area_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 258.72 & 192.80 & 273.90 & 361.23 \\ \hline 2 & 258.72 & 192.80 & 273.90 & 361.23 \\ \hline 3 & 258.72 & 192.80 & 273.90 & 361.23 \\ \hline \end{array} \cdot 10^{-6}$$

$$Sx_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1665.7 & 355.1 & 1055.4 & 2185.0 \\ \hline 2 & 1756.8 & 549.9 & 1321.3 & 2441.5 \\ \hline 3 & 1887.1 & 748.6 & 1581.0 & 2681.1 \\ \hline \end{array} \cdot 10^{-9}$$

$$Sy_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 6389.6 & 4110.4 & 6960.2 & 10541.9 \\ \hline 2 & 6389.6 & 4110.4 & 6960.2 & 10541.9 \\ \hline 3 & 6389.6 & 4110.4 & 6960.2 & 10541.9 \\ \hline \end{array} \cdot 10^{-9}$$

$$x0_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 24.7 & 21.3 & 25.4 & 29.2 \\ \hline 2 & 24.7 & 21.3 & 25.4 & 29.2 \\ \hline 3 & 24.7 & 21.3 & 25.4 & 29.2 \\ \hline \end{array} \cdot 10^{-3}$$

$$y0_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 6.4 & 1.8 & 3.9 & 6.0 \\ \hline 2 & 6.8 & 2.9 & 4.8 & 6.8 \\ \hline 3 & 7.3 & 3.9 & 5.8 & 7.4 \\ \hline \end{array} \cdot 10^{-3}$$

$$l_{upper\_rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 36.19 & 42.56 & 49.41 & 53.03 \\ \hline 2 & 33.76 & 39.33 & 45.25 & 48.34 \\ \hline 3 & 29.12 & 32.92 & 38.27 & 42.93 \\ \hline \end{array} \cdot 10^{-3}$$

$$l_{lower\_rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 33.41 & 38.53 & 44.61 & 48.17 \\ \hline 2 & 31.13 & 35.90 & 41.33 & 44.46 \\ \hline 3 & 27.43 & 30.92 & 36.02 & 40.64 \\ \hline \end{array} \cdot 10^{-3}$$

$$area_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 93.47 & 118.07 & 156.50 & 186.58 \\ \hline 2 & 66.07 & 83.84 & 111.52 & 133.48 \\ \hline 3 & 30.58 & 37.34 & 52.08 & 69.88 \\ \hline \end{array} \cdot 10^{-6}$$

$$Sx_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 345.7 & 662.1 & 1057.2 & 1251.8 \\ \hline 2 & 276.0 & 474.3 & 719.3 & 828.2 \\ \hline 3 & 129.1 & 194.3 & 297.4 & 388.4 \\ \hline \end{array} \cdot 10^{-9}$$

$$Sy_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1276.4 & 1812.0 & 2765.3 & 3599.6 \\ \hline 2 & 824.6 & 1178.8 & 1808.3 & 2367.8 \\ \hline 3 & 325.4 & 439.2 & 723.4 & 1124.3 \\ \hline \end{array} \cdot 10^{-9}$$

$$x0_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 13.7 & 15.3 & 17.7 & 19.3 \\ \hline 2 & 12.5 & 14.1 & 16.2 & 17.7 \\ \hline 3 & 10.6 & 11.8 & 13.9 & 16.1 \\ \hline \end{array} \cdot 10^{-3}$$

$$y0_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.7 & 5.6 & 6.8 & 6.7 \\ \hline 2 & 4.2 & 5.7 & 6.5 & 6.2 \\ \hline 3 & 4.2 & 5.2 & 5.7 & 5.6 \\ \hline \end{array} \cdot 10^{-3}$$

$$J_{x_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 12406 & 1067 & 5183 & 15768 \\ \hline 2 & 13721 & 2076 & 7721 & 19367 \\ \hline 3 & 15720 & 3549 & 10739 & 23084 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 206780 & 114833 & 231764 & 403124 \\ \hline 2 & 206780 & 114833 & 231764 & 403124 \\ \hline 3 & 206780 & 114833 & 231764 & 403124 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 43693 & 8055 & 28524 & 67776 \\ \hline 2 & 46072 & 12470 & 35696 & 75706 \\ \hline 3 & 49471 & 16968 & 42691 & 83109 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1681 & 413 & 1116 & 2551 \\ \hline 2 & 1791 & 508 & 1347 & 2866 \\ \hline 3 & 1955 & 642 & 1613 & 3185 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 48976 & 27198 & 54893 & 95480 \\ \hline 2 & 48976 & 27198 & 54893 & 95480 \\ \hline 3 & 48976 & 27198 & 54893 & 95480 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 2554 & 485 & 1704 & 4010 \\ \hline 2 & 2683 & 747 & 2119 & 4456 \\ \hline 3 & 2865 & 1009 & 2515 & 4866 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.1 & 1.0 & 1.8 & 2.5 \\ \hline 2 & 3.2 & 1.6 & 2.3 & 2.7 \\ \hline 3 & 3.5 & 2.2 & 2.7 & 3.0 \\ \hline \end{array} \cdot ^\circ$$

$$J_{x_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1500 & 4209 & 8062 & 9567 \\ \hline 2 & 1303 & 2990 & 5174 & 5785 \\ \hline 3 & 600 & 1107 & 1866 & 2390 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 22840 & 36441 & 64025 & 90998 \\ \hline 2 & 13485 & 21716 & 38421 & 55040 \\ \hline 3 & 4539 & 6769 & 13166 & 23704 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 5013 & 10772 & 19795 & 25610 \\ \hline 2 & 3654 & 7064 & 12356 & 15579 \\ \hline 3 & 1455 & 2419 & 4374 & 6627 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 221 & 496 & 921 & 1168 \\ \hline 2 & 150 & 306 & 534 & 646 \\ \hline 3 & 55 & 96 & 168 & 231 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 5410 & 8631 & 15164 & 21553 \\ \hline 2 & 3194 & 5143 & 9100 & 13036 \\ \hline 3 & 1075 & 1603 & 3118 & 5614 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 292 & 610 & 1115 & 1460 \\ \hline 2 & 209 & 395 & 692 & 887 \\ \hline 3 & 82 & 133 & 244 & 378 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.2 & 4.3 & 4.4 & 4.1 \\ \hline 2 & 3.9 & 4.6 & 4.6 & 4.1 \\ \hline 3 & 4.5 & 5.0 & 4.7 & 4.0 \\ \hline \end{array} \cdot ^\circ$$

$$J_{u_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1544 & 404 & 1063 & 2378 \\ \hline 2 & 1639 & 487 & 1263 & 2652 \\ \hline 3 & 1781 & 604 & 1495 & 2929 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 49113.3 & 27206.9 & 54947.2 & 95652.3 \\ \hline 2 & 49127.8 & 27219.0 & 54977.0 & 95693.5 \\ \hline 3 & 49149.7 & 27236.4 & 55011.7 & 95735.4 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -0 & 0 & 0 & 0 \\ \hline 2 & 0 & 0 & 0 & 0 \\ \hline 3 & -0 & 0 & -0 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 50657 & 27611 & 56010 & 98030 \\ \hline 2 & 50767 & 27706 & 56240 & 98346 \\ \hline 3 & 50931 & 27841 & 56507 & 98664 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1465.9 & 940.2 & 1593.7 & 2416.2 \\ \hline 2 & 1466.3 & 940.9 & 1594.8 & 2417.3 \\ \hline 3 & 1466.7 & 941.7 & 1595.9 & 2418.3 \\ \hline \end{array} \cdot 10^{-9}$$

$$\text{stiffness}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 2479.0 & 1376.7 & 2778.6 & 4832.9 \\ \hline 2 & 2479.0 & 1376.7 & 2778.6 & 4832.9 \\ \hline 3 & 2479.0 & 1376.7 & 2778.6 & 4832.9 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{u_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 205 & 451 & 834 & 1064 \\ \hline 2 & 135 & 274 & 479 & 583 \\ \hline 3 & 48 & 84 & 148 & 205 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 5426 & 8676 & 15251 & 21657 \\ \hline 2 & 3208 & 5175 & 9155 & 13099 \\ \hline 3 & 1081 & 1615 & 3138 & 5641 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -0 & 0 & 0 & -0 \\ \hline 2 & -0 & 0 & 0 & -0 \\ \hline 3 & 0 & 0 & 0 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 5631 & 9127 & 16085 & 22721 \\ \hline 2 & 3343 & 5450 & 9634 & 13682 \\ \hline 3 & 1130 & 1699 & 3286 & 5846 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 294.3 & 418.1 & 638.0 & 830.5 \\ \hline 2 & 189.3 & 270.6 & 415.2 & 543.7 \\ \hline 3 & 74.2 & 100.1 & 164.9 & 256.3 \\ \hline \end{array} \cdot 10^{-9}$$

$$\text{stiffness}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 382.4 & 610.2 & 1072.1 & 1523.7 \\ \hline 2 & 161.7 & 260.3 & 460.6 & 659.9 \\ \hline 3 & 22.0 & 32.9 & 63.9 & 115.1 \\ \hline \end{array} \cdot 10^{-12}$$



$$\text{CP}_{\text{stator}}^T = \begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 20.527 & 17.720 & 21.121 & 24.255 \\ 2 & 20.527 & 17.720 & 21.121 & 24.255 \\ 3 & 20.527 & 17.720 & 21.121 & 24.255 \end{array} \cdot 10^{-3}$$

$$\text{CPy}_{\text{stator}}^T = \begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \\ 2 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \\ 3 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \end{array} \cdot 10^{-3}$$

|   |   |        |        |        |        |
|---|---|--------|--------|--------|--------|
|   | 1 | 2      | 3      | 4      |        |
| CP <sub>x</sub> <sub>rotor</sub> <sup>T</sup> | 1 | 11.350 | 12.756 | 14.686 | 16.035 |
|   | 2 | 10.373 | 11.685 | 13.477 | 14.744 |
|   | 3 | 8.846  | 9.776  | 11.545 | 13.373 |

$\cdot 10^{-3}$

$$\text{CPy}_{\text{rotor}}^T = \begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \\ 2 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \\ 3 & 0.0000 & 0.0000 & 0.0000 & 0.0000 \end{array} \cdot 10^{-3}$$



Абс. координаты профиля:

|                            |   |
|----------------------------|---|
| Airfoil(type,x,line,i,r) = | $\begin{aligned} & \text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{stator}_{i,r}}, \varepsilon_{\text{stator}_{i,r}}\right) \text{ if type = "stator"} \\ & \text{AIRFOIL}\left(x, \text{line}, \overline{c}_{\text{rotor}_{i,r}}, \varepsilon_{\text{rotor}_{i,r}}\right) \text{ if type = "rotor"} \end{aligned}$ |
|----------------------------|---|

Рассматриваемая ступень:

$$j_v = \begin{cases} j = 1 & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

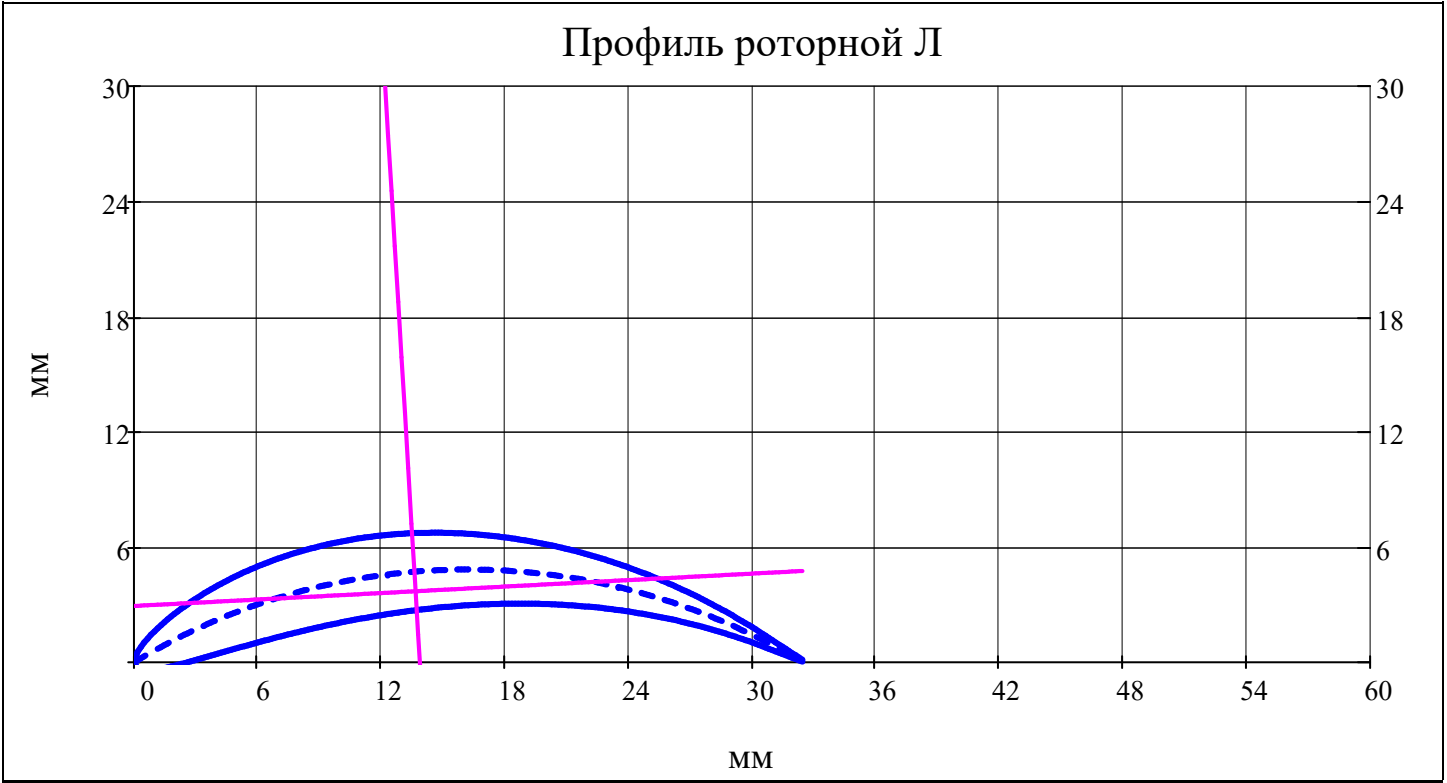
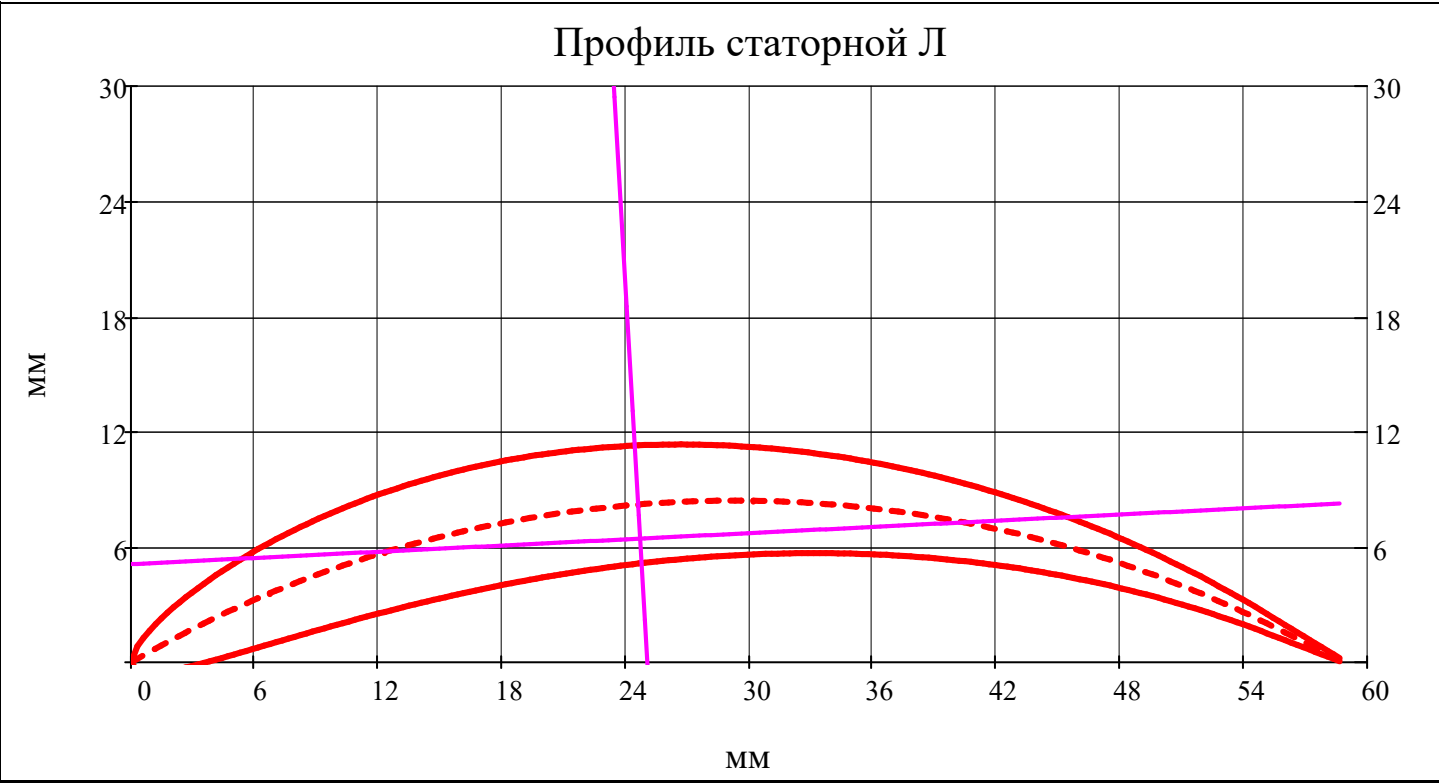
Построение профилей Л РК и НА

$$\text{AXLE0}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if type = "stator"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

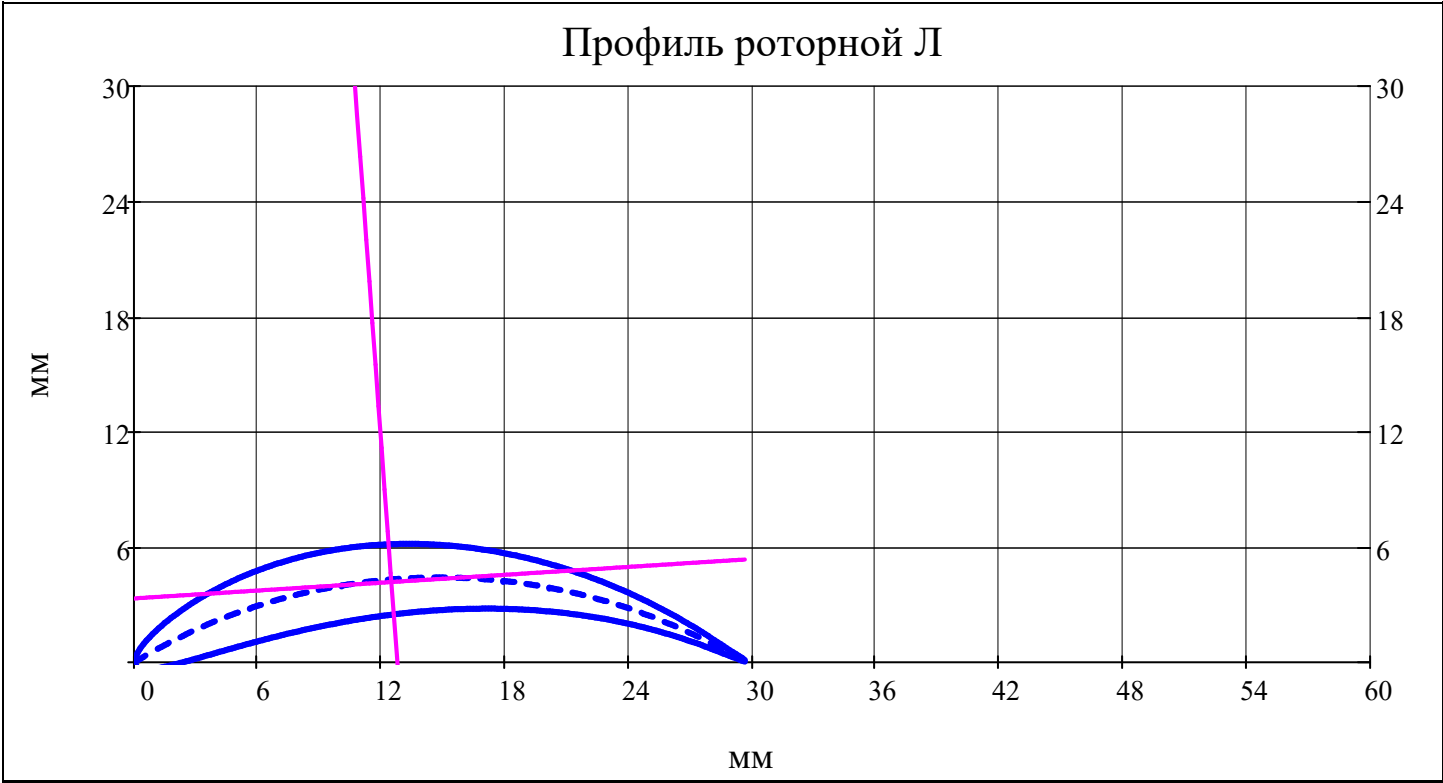
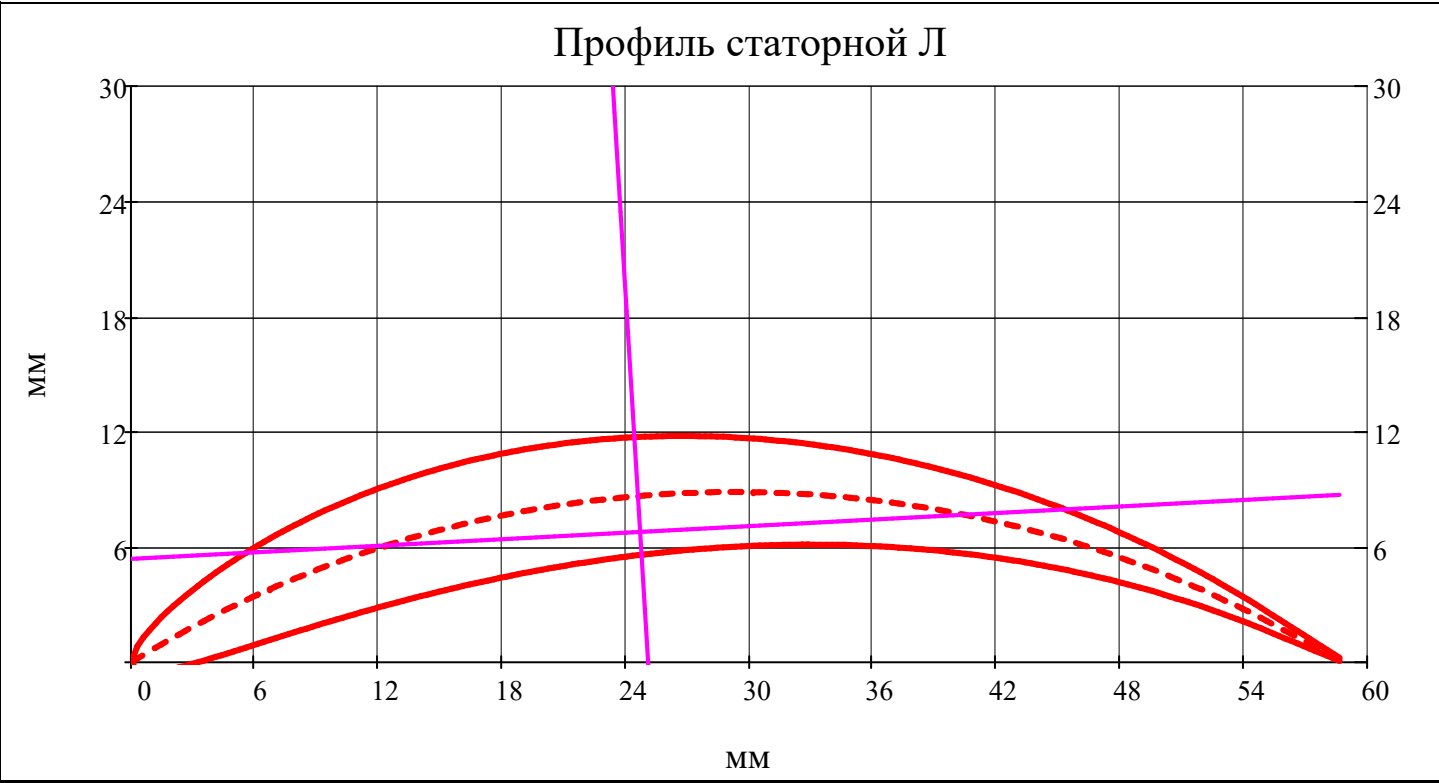
$$\text{AXLE90}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if (type = "rotor") } \wedge \left|\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right| \geq 1^\circ \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if (type = "stator") } \wedge \left|\alpha_{\text{major}_{\text{stator}_{i,r}}}\right| \geq 1^\circ \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$b_{\text{lim}} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 60.0 \cdot 10^{-3}$$

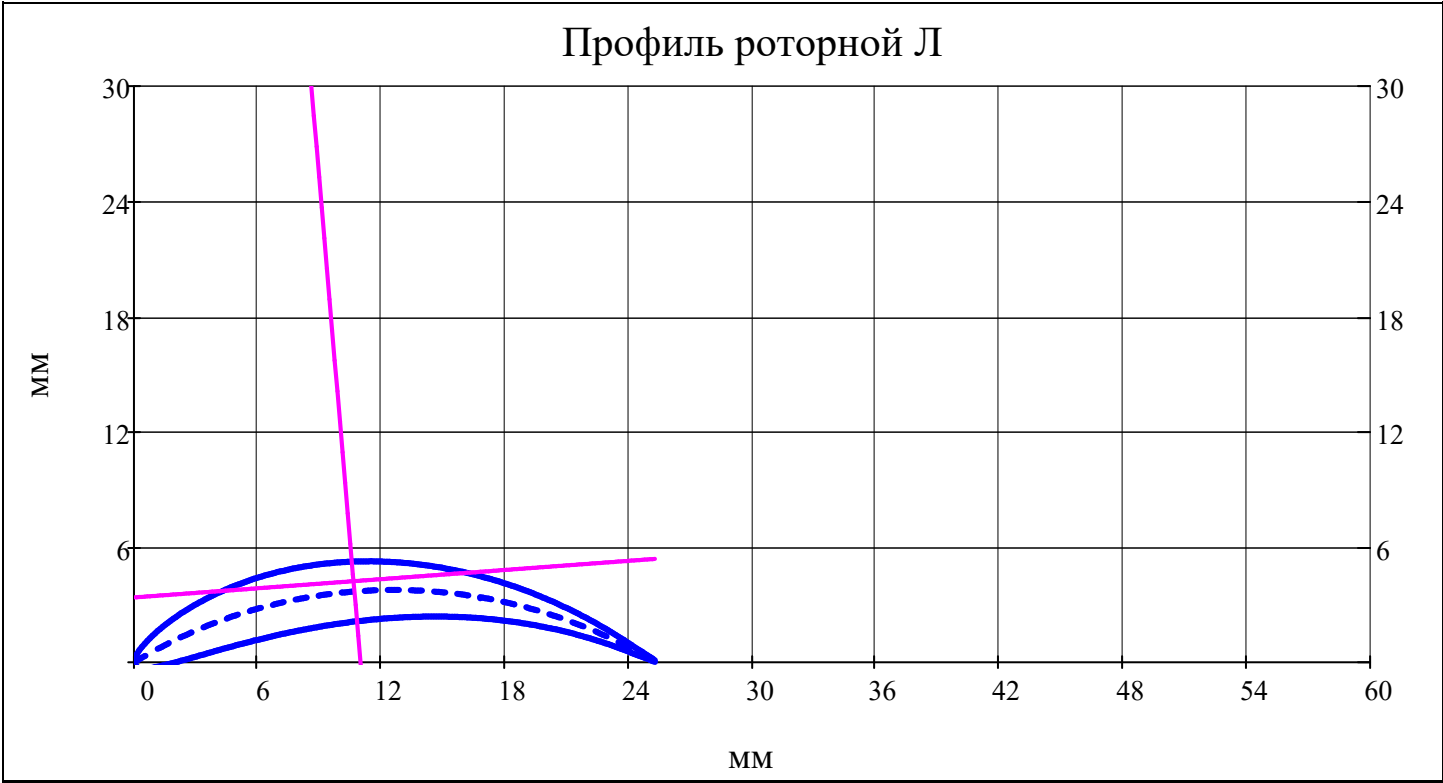
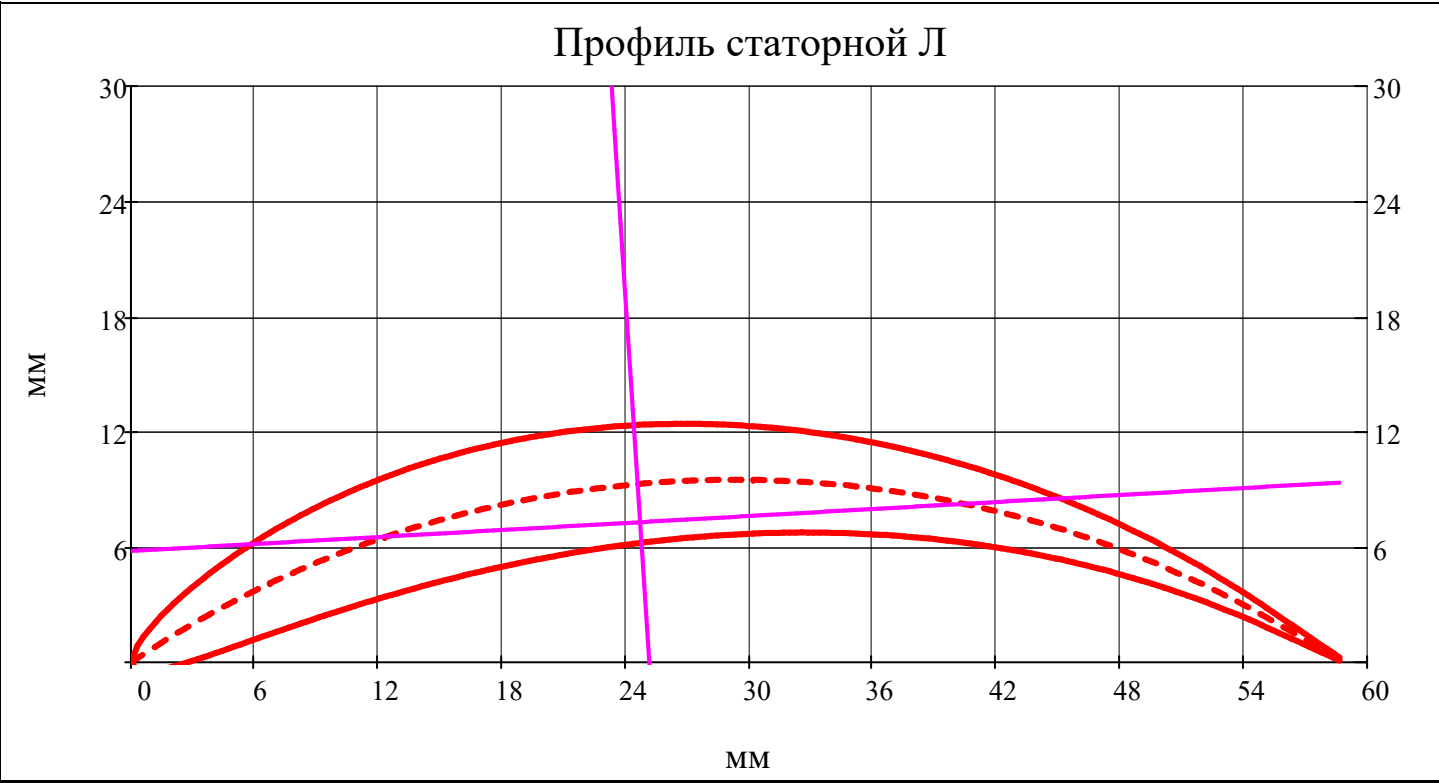
$r_w = 1$



$r_w = av(N_r)$



$r_w = N_r$







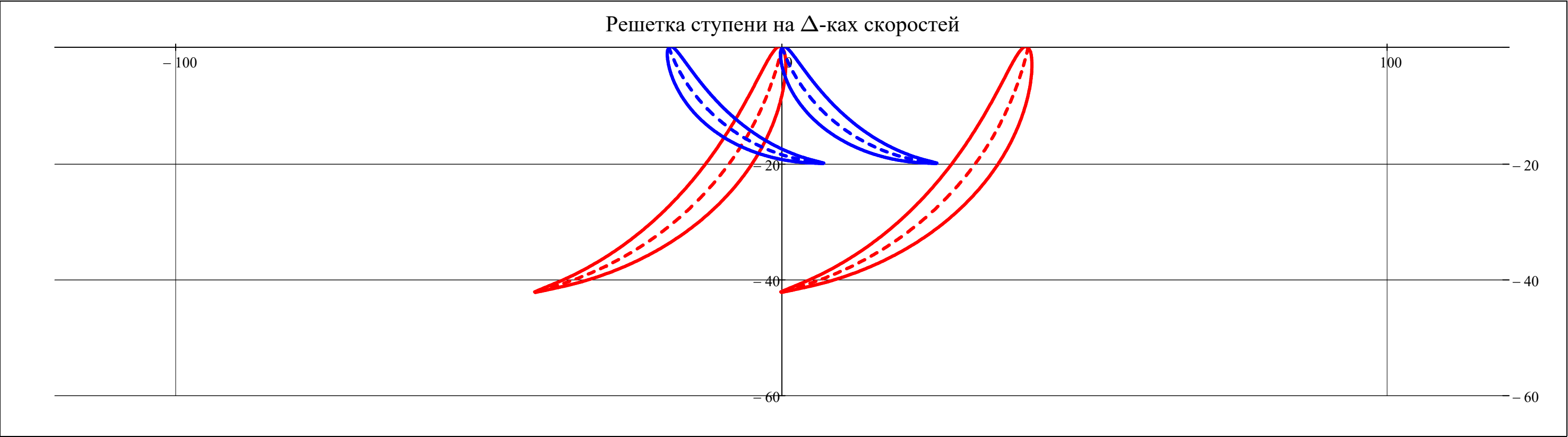
Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 \\ j = \\ j \end{cases} = \begin{cases} 1 \\ \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j \text{ otherwise} \end{cases} = 1$$

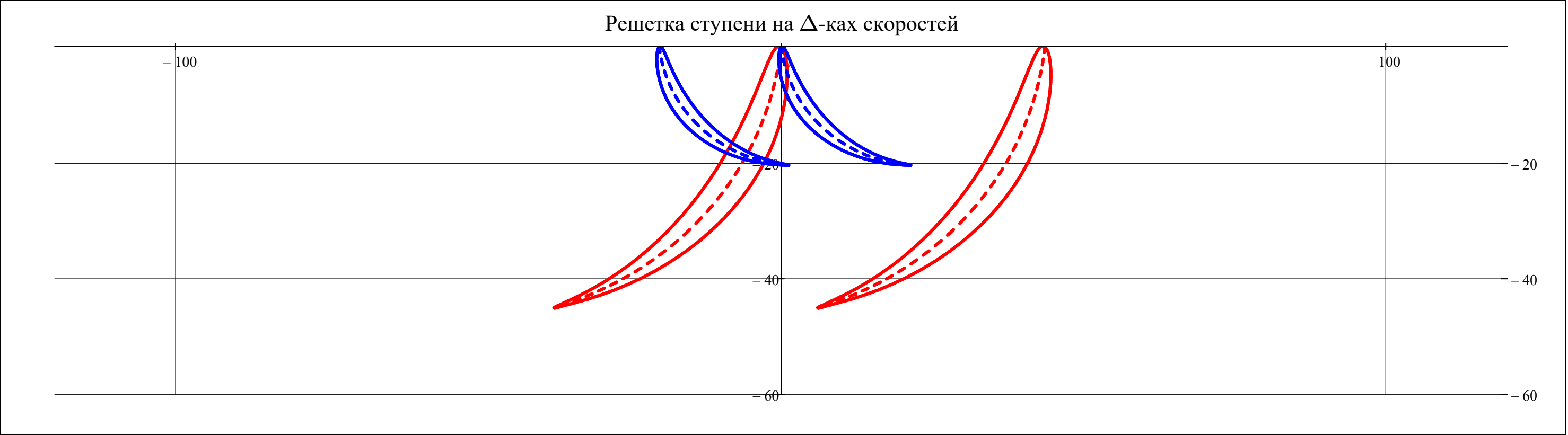
$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 60.0 \cdot 10^{-3}$$

Построение плоских решеток профилей Л на треугольниках скоростей

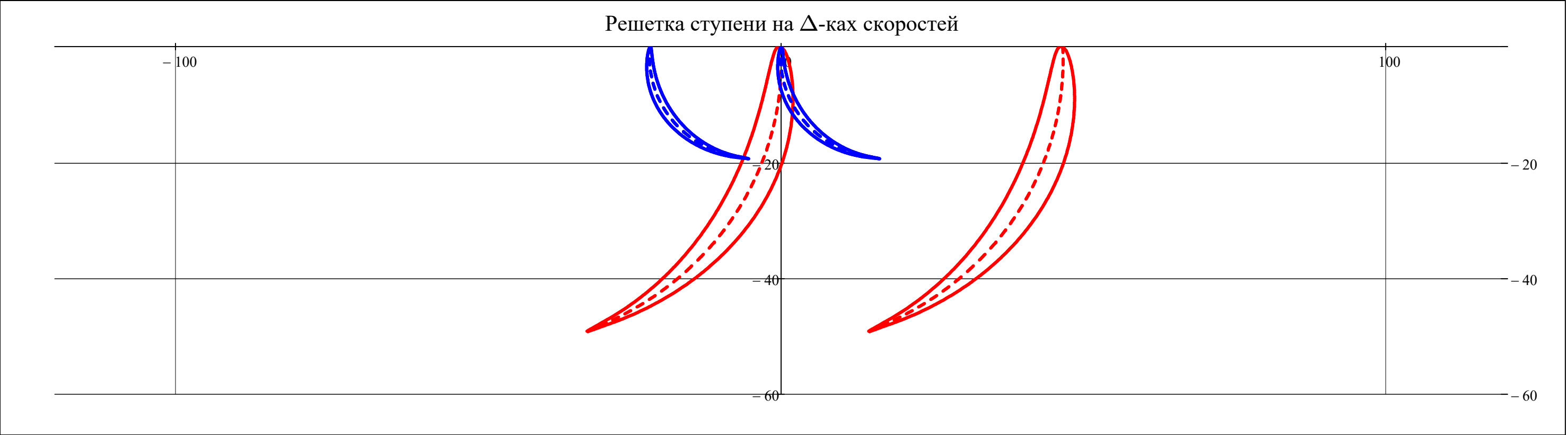
$$r_w = 1$$



$r_w = \text{av}(N_r)$



$r_w = N_r$



▲ Построение плоских решеток профилей Л на треугольниках скоростей



Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & \\ j = & \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases} = 1$$

▼ Поперечная часть ступени

$$r_w = \min(D), \min(D) + \frac{\max(D) - \min(D)}{N_{\text{dis}}} \dots \max(D)$$

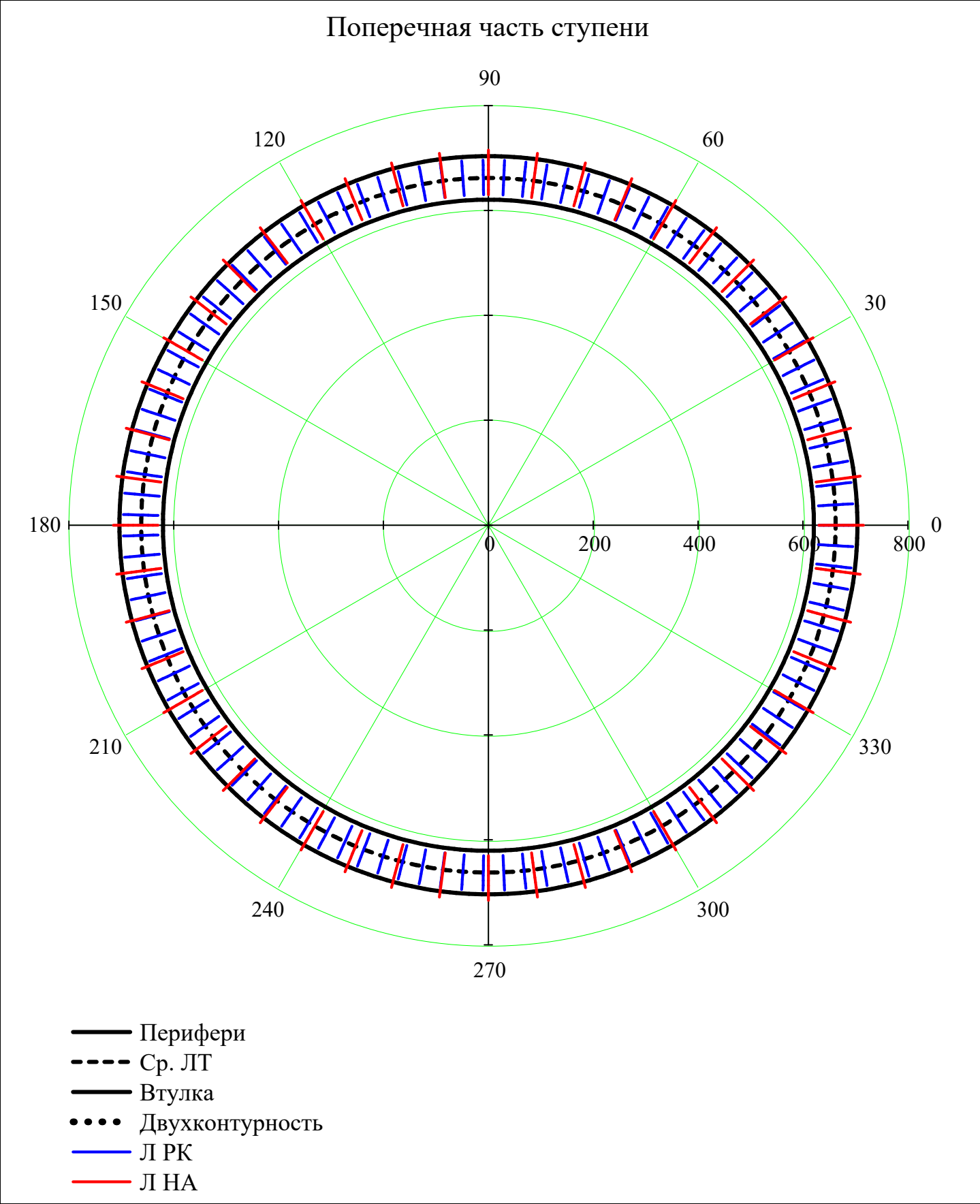
$$i_{\text{rotor}} = 1 \dots Z_{\text{rotor}_j}$$

$$i_{\text{stator}} = 1 \dots Z_{\text{stator}_j}$$

$$\varphi = 0, \frac{2 \cdot \pi}{360} \dots 2 \cdot \pi$$

|                 |  |
|-----------------|--|
| $Л_{PK}(r,j) =$ | $\begin{cases} \frac{2 \cdot \pi}{Z_{\text{rotor}_j}} & \text{if } D_{\text{st}(j,1)}, 1 < r < D_{\text{st}(j,1)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$ |
|-----------------|--|

|                 |   |
|-----------------|---|
| $Л_{HA}(r,j) =$ | $\begin{cases} \frac{2 \cdot \pi}{Z_{\text{stator}_j}} & \text{if } D_{\text{st}(j,2)}, 1 < r < D_{\text{st}(j,2)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$ |
|-----------------|---|



▲ Поперечная часть ступени

$$\begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator\_bondage}} & \nu_{0\text{угЛ.rotor\_bondage}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in \text{av}(N_r) \\ \text{for } \text{mode} \in 1..6 \\ \left| \begin{array}{l} \nu_{0\text{изГ.stator}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{stator}_{i,r}}, J_{u\text{stator}_{i,r}}) \\ \nu_{0\text{изГ.rotor}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}(\text{mode}, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{rotor}_{i,r}}, J_{u\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 0, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \\ \nu_{0\text{угЛ.stator\_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{p\text{stator}_{i,r}}) \\ \nu_{0\text{угЛ.rotor\_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}(\text{mode}, 1, \text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{p\text{rotor}_{i,r}}) \end{array} \right. \\ \begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator\_bondage}} & \nu_{0\text{угЛ.rotor\_bondage}} \end{pmatrix} \end{array}$$

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\text{stack}\left(\nu_{0_{\text{изг.stator}}}, \nu_{0_{\text{изг.rotor}}}\right)^T =$$

|   | 1      | 2      | 3      | 4      | 5      | 6      | 7      | 8      |
|---|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 3485   | 1505   | 1722   | 1835   | 1562   | 1561   | 1543   | 1248   |
| 2 | 21843  | 9432   | 10793  | 11499  | 9787   | 9782   | 9669   | 7819   |
| 3 | 61166  | 26413  | 30223  | 32200  | 27406  | 27392  | 27076  | 21896  |
| 4 | 119951 | 51798  | 59268  | 63146  | 53745  | 53718  | 53097  | 42939  |
| 5 | 198206 | 85591  | 97935  | 104342 | 88808  | 88764  | 87737  | 70952  |
| 6 | 296010 | 127826 | 146260 | 155829 | 132630 | 132564 | 131031 | 105963 |

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\text{stack}\left(\nu_{0_{\text{угл.stator}}}, \nu_{0_{\text{угл.rotor}}}\right)^T =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 3812  | 3180  | 2918  | 2674  | 3368  | 2976  | 2766  | 2488  |
| 2 | 11436 | 9541  | 8754  | 8023  | 10104 | 8928  | 8299  | 7463  |
| 3 | 19060 | 15902 | 14591 | 13372 | 16841 | 14881 | 13832 | 12439 |
| 4 | 26685 | 22263 | 20427 | 18721 | 23577 | 20833 | 19365 | 17414 |
| 5 | 34309 | 28624 | 26263 | 24069 | 30313 | 26785 | 24898 | 22390 |
| 6 | 41933 | 34985 | 32099 | 29418 | 37050 | 32738 | 30431 | 27365 |

$$\text{stack}\left(\nu_{0_{\text{угл.stator\_bondage}}}, \nu_{0_{\text{угл.rotor\_bondage}}}\right)^T =$$

|   | 1     | 2     | 3     | 4     | 5     | 6     | 7     | 8     |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 7624  | 6361  | 5836  | 5349  | 6736  | 5952  | 5533  | 4975  |
| 2 | 15248 | 12722 | 11672 | 10697 | 13473 | 11905 | 11066 | 9951  |
| 3 | 22873 | 19083 | 17509 | 16046 | 20209 | 17857 | 16599 | 14926 |
| 4 | 30497 | 25444 | 23345 | 21395 | 26945 | 23809 | 22132 | 19902 |
| 5 | 38121 | 31805 | 29181 | 26744 | 33682 | 29762 | 27665 | 24877 |
| 6 | 45745 | 38166 | 35017 | 32092 | 40418 | 35714 | 33197 | 29853 |





Расчетный узел: type = "turbine"

Объем бандажной полки (м³):  $V_{\text{бп}} = 0$

Радиус положения ЦМ бандажной полки (м):  $R_{\text{бп}} = 0$

► Расчет Л на прочность

$$\text{neutral\_line}(\text{type}, \text{x}, \text{i}, \text{r}) = \begin{cases} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})}\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) & \text{if type = "stator"} \end{cases}$$

$$\text{epure}(\text{type}, \text{x}, \text{i}, \text{r}) = \begin{cases} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}(\text{i}, \text{Rst}(\text{i}, 2), \text{r})} - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}}\right) & \text{if type = "stator"} \end{cases}$$



Наиболее удаленные точки от НЛ (мм):

$$u_{-u_{\text{rotor}}}^T =$$

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | -0.771 | -0.359 | -0.336 | -0.674 |
| 2 | -0.397 | -0.347 | -0.341 | -0.363 |
| 3 | 0.146  | 0.170  | 0.163  | 0.135  |

$$\cdot 10^{-3}$$

$$u_{-l_{\text{rotor}}}^T =$$

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | 18.423 | 18.198 | 18.139 | 18.190 |
| 2 | 16.738 | 16.589 | 16.580 | 16.658 |
| 3 | 14.203 | 14.117 | 14.152 | 14.251 |

$$\cdot 10^{-3}$$

$$u_{-u_{\text{stator}}}^T =$$

|   | 1      | 2       | 3       | 4      |
|---|--------|---------|---------|--------|
| 1 | -5.101 | 26.620  | 19.884  | 16.746 |
| 2 | 13.579 | 27.702  | 31.315  | 19.244 |
| 3 | -9.445 | -16.428 | -13.947 | 27.195 |

$$\cdot 10^{-3}$$

$$u_{-l_{\text{stator}}}^T =$$

|   | 1      | 2       | 3       | 4       |
|---|--------|---------|---------|---------|
| 1 | -8.197 | -21.916 | -21.919 | -21.412 |
| 2 | 1.424  | -15.550 | -17.773 | -20.198 |
| 3 | 29.069 | 29.084  | 6.733   | -16.908 |

$$\cdot 10^{-3}$$

$$v_{-u_{\text{rotor}}}^T =$$

|   | 1     | 2     | 3     | 4     |
|---|-------|-------|-------|-------|
| 1 | 3.038 | 3.324 | 3.372 | 3.279 |
| 2 | 2.669 | 2.844 | 2.834 | 2.713 |
| 3 | 1.934 | 2.027 | 1.964 | 1.819 |

$$\cdot 10^{-3}$$

$$v_{-l_{\text{rotor}}}^T =$$

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | -5.143 | -6.725 | -7.040 | -6.584 |
| 2 | -5.576 | -6.572 | -6.555 | -5.938 |
| 3 | -5.408 | -5.963 | -5.647 | -4.892 |

$$\cdot 10^{-3}$$

$$v_{-u_{\text{stator}}}^T =$$

|   | 1      | 2      | 3      | 4      |
|---|--------|--------|--------|--------|
| 1 | 25.008 | 6.901  | 7.009  | 7.208  |
| 2 | 31.802 | 19.883 | 13.873 | 8.592  |
| 3 | 6.651  | 7.953  | 21.140 | 12.770 |

$$\cdot 10^{-3}$$

$$v_{-l_{\text{stator}}}^T =$$

|   | 1       | 2       | 3       | 4       |
|---|---------|---------|---------|---------|
| 1 | -33.559 | -9.119  | -10.986 | -12.486 |
| 2 | -25.574 | -18.863 | -17.146 | -14.602 |
| 3 | -18.963 | -18.084 | -33.741 | -18.499 |

$$\cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{\text{p\_rotor}} & \sigma_{\text{n\_rotor}} \\ \sigma_{\text{p\_stator}} & \sigma_{\text{n\_stator}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \sigma_{\text{p\_rotor}_{i,r}} & \sigma_{\text{n\_rotor}_{i,r}} \\ \sigma_{\text{p\_stator}_{i,r}} & \sigma_{\text{n\_stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v\_u}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u\_u}_{\text{rotor}_{i,r}} & \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v\_l}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u\_l}_{\text{rotor}_{i,r}} \\ \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v\_u}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u\_u}_{\text{stator}_{i,r}} & \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v\_l}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u\_l}_{\text{stator}_{i,r}} \end{pmatrix} \end{array} \\ \begin{pmatrix} \sigma_{\text{p\_rotor}} & \sigma_{\text{n\_rotor}} \\ \sigma_{\text{p\_stator}} & \sigma_{\text{n\_stator}} \end{pmatrix}
\end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{p\_rotor.}} & \sigma_{\text{p\_stator.}} \\ \sigma_{\text{n\_rotor.}} & \sigma_{\text{n\_stator.}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \sigma_{\text{p\_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p\_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p\_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{p\_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p\_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p\_stator}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n\_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n\_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n\_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n\_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n\_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n\_stator}}, i, i, 1, N_r\right)^T, z\right) \end{array} \end{array} \\ \begin{pmatrix} \sigma_{\text{p\_rotor.}} & \sigma_{\text{p\_stator.}} \\ \sigma_{\text{n\_rotor.}} & \sigma_{\text{n\_stator.}} \end{pmatrix}
\end{pmatrix}$$

$$\sigma_{\text{p}_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -47.11 & -36.12 & -23.18 & -14.88 \\ \hline 2 & -22.35 & -18.72 & -11.72 & -6.22 \\ \hline 3 & -3.87 & -4.94 & -2.06 & -0.06 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{rotor}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{rotor}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 85.83 & 77.66 & 51.55 & 32.33 \\ \hline 2 & 49.10 & 45.13 & 28.47 & 14.57 \\ \hline 3 & 11.15 & 14.91 & 6.14 & 0.16 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{rotor}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0 & 0 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{p}_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & 0.70 & 0.36 & 0.03 \\ \hline 2 & 1.39 & 7.96 & 5.00 & 1.63 \\ \hline 3 & -9.13 & -17.30 & -6.49 & 6.71 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p}_{\text{stator}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n}_{\text{stator}}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & -0.74 & -0.48 & -0.05 \\ \hline 2 & -0.20 & -5.82 & -4.17 & -2.24 \\ \hline 3 & 26.68 & 35.35 & 5.99 & -6.41 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n}_{\text{stator}}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \sigma_{\text{rotor}_{i,r}} &= \sqrt{\left(\sigma_{\text{Zrotor}}(i, R_{\text{st}}(i, 2), r) + \max(\sigma_{\text{Protor}_{i,r}}, \sigma_{\text{nrotor}_{i,r}})\right)^2 + \tau_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)^2} \\ \sigma_{\text{stator}_{i,r}} &= \sqrt{\left(0 + \max(\sigma_{\text{Pstator}_{i,r}}, \sigma_{\text{nstator}_{i,r}})\right)^2 + \tau_{\text{stator}}(i, R_{\text{st}}(i, 2), r)^2} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \left| \begin{aligned} \sigma_{\text{rotor.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{stator.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix}$$

$$\sigma_{\text{rotor}}^T = \begin{array}{c|ccccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 116.67 & 117.88 & 101.19 & 89.04 \\ 2 & 68.23 & 69.97 & 59.02 & 47.69 \\ 3 & 17.89 & 24.36 & 16.54 & 3.18 \end{array} \cdot 10^6$$

$$\sigma_{\text{stator}}^T = \begin{array}{c|ccccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & 0.73 & 0.44 & 0.10 \\ 2 & 2.14 & 8.01 & 5.08 & 1.77 \\ 3 & 26.89 & 35.40 & 6.22 & 6.85 \end{array} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \text{safety}_{\text{rotor}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade\_long}_i}}{\sigma_{\text{rotor}_{i,r}}} & \text{if } \sigma_{\text{rotor}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \\ \text{safety}_{\text{stator}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade\_long}_i}}{\sigma_{\text{stator}_{i,r}}} & \text{if } \sigma_{\text{stator}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix}$$

$$\text{safety}_{\text{rotor}}^T = \begin{array}{c|ccccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 1.03 & 1.02 & 1.19 & 1.35 \\ 2 & 1.76 & 1.71 & 2.03 & 2.52 \\ 3 & 6.71 & 4.93 & 7.26 & 37.69 \end{array}$$

$$\text{safety}_{\text{stator}}^T = \begin{array}{c|cc} & 1 & 2 \\ \hline 1 & 00000000000000000000000000000000 & \\ 2 & & 56.01 \\ 3 & & 4.46 \end{array}$$

$$\text{safety}_{\text{rotor}}^T \geq \text{safety} = \begin{array}{c|ccccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 0 & 0 & 0 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 3 & 1 & 1 & 1 & 1 \end{array}$$

$$\text{safety}_{\text{stator}}^T \geq \text{safety} = \begin{array}{c|ccccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ 2 & 1 & 1 & 1 & 1 \\ 3 & 1 & 1 & 1 & 1 \end{array}$$



Рассматриваемая ступень:

$$j = \begin{cases} j = \begin{cases} 1 & \text{if type = "compressor"} \\ Z & \text{if type = "turbine"} \end{cases} \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} \end{cases} = 4$$

$$b_{lim} = \frac{ceil\left(\max\left(chord_{rotor_{j,N_r}}, chord_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

$$R_j = submatrix\left(R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r\right) =$$

|   |       |       |       |
|---|-------|-------|-------|
|   | 1     | 2     | 3     |
| 1 | 422.0 | 453.2 | 484.5 |
| 2 | 433.0 | 466.0 | 499.1 |
| 3 | 433.0 | 468.5 | 503.9 |

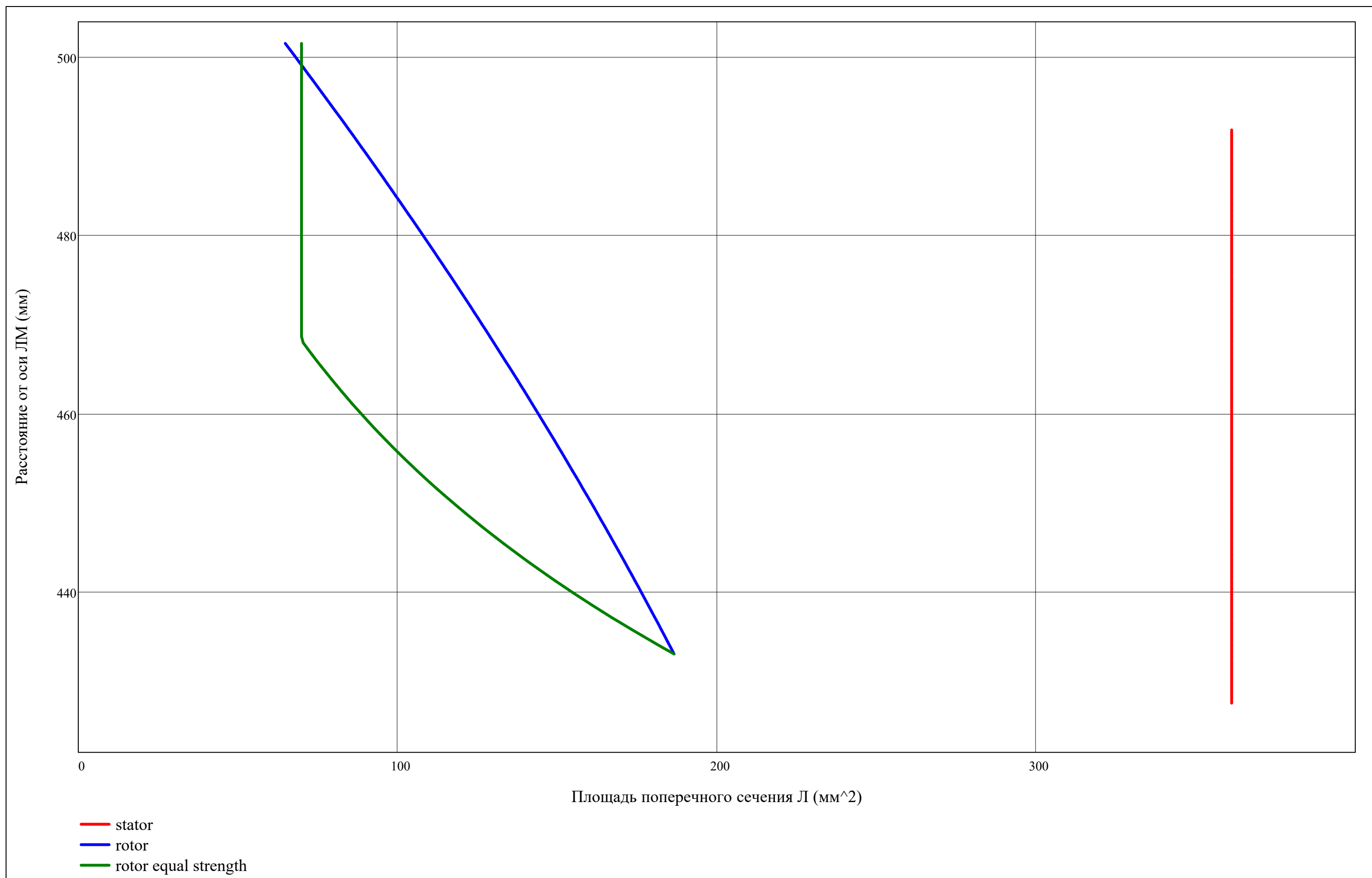
· 10<sup>−3</sup>

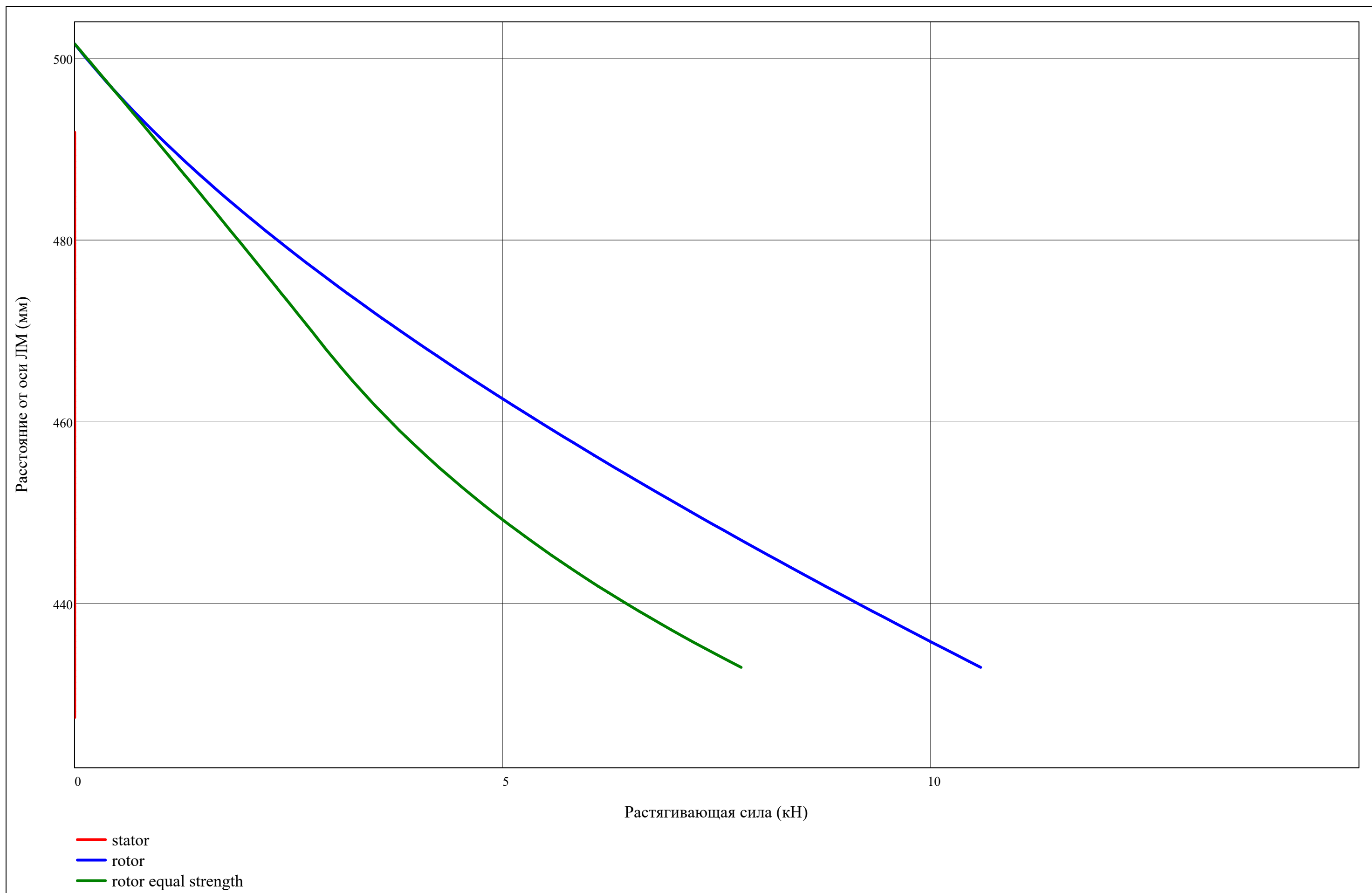
Дискретизация по высоте Л:

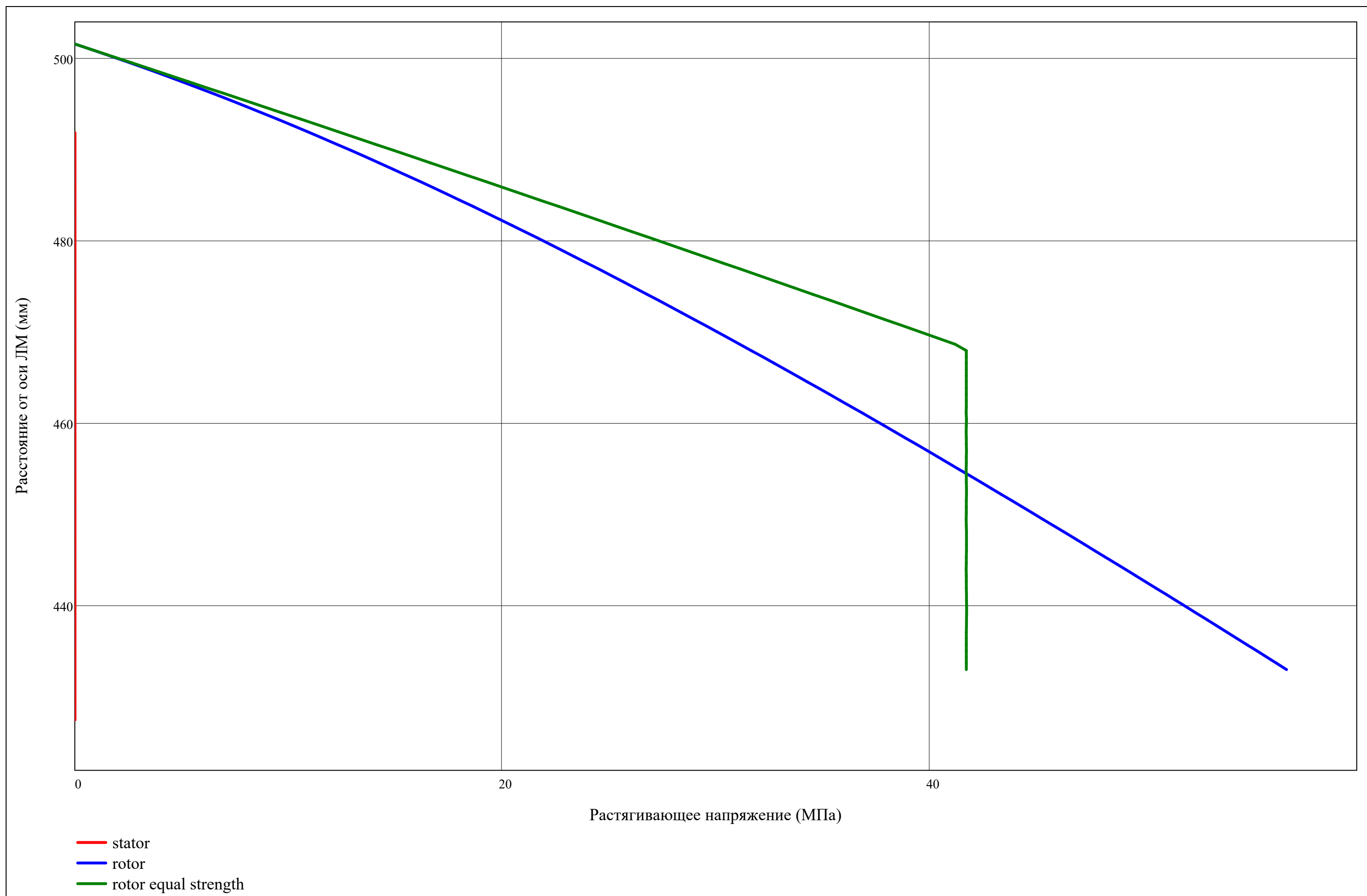
$$z = \min(R_j), \min(R_j) + \frac{\max(R_j) - \min(R_j)}{100} .. \max(R_j)$$

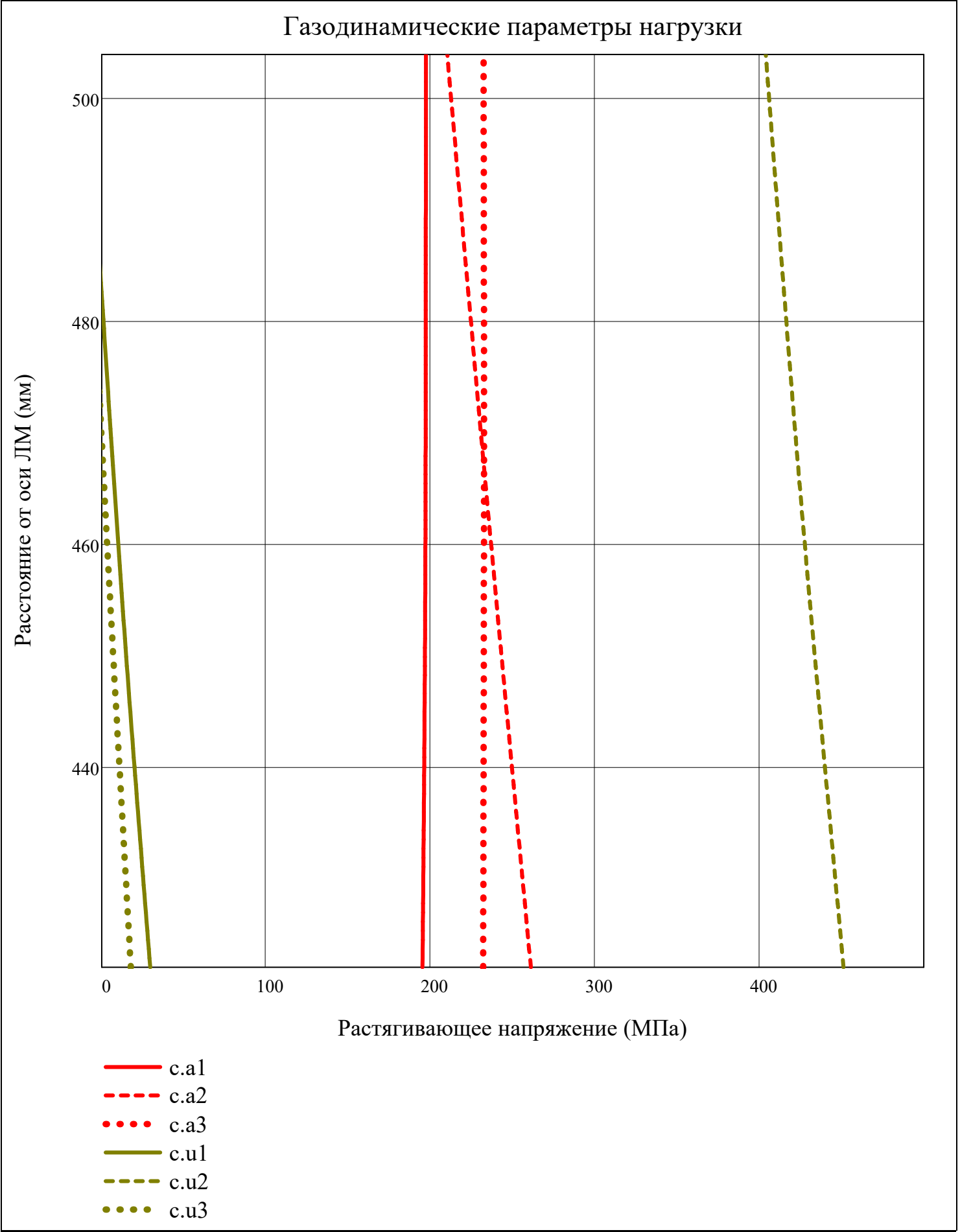
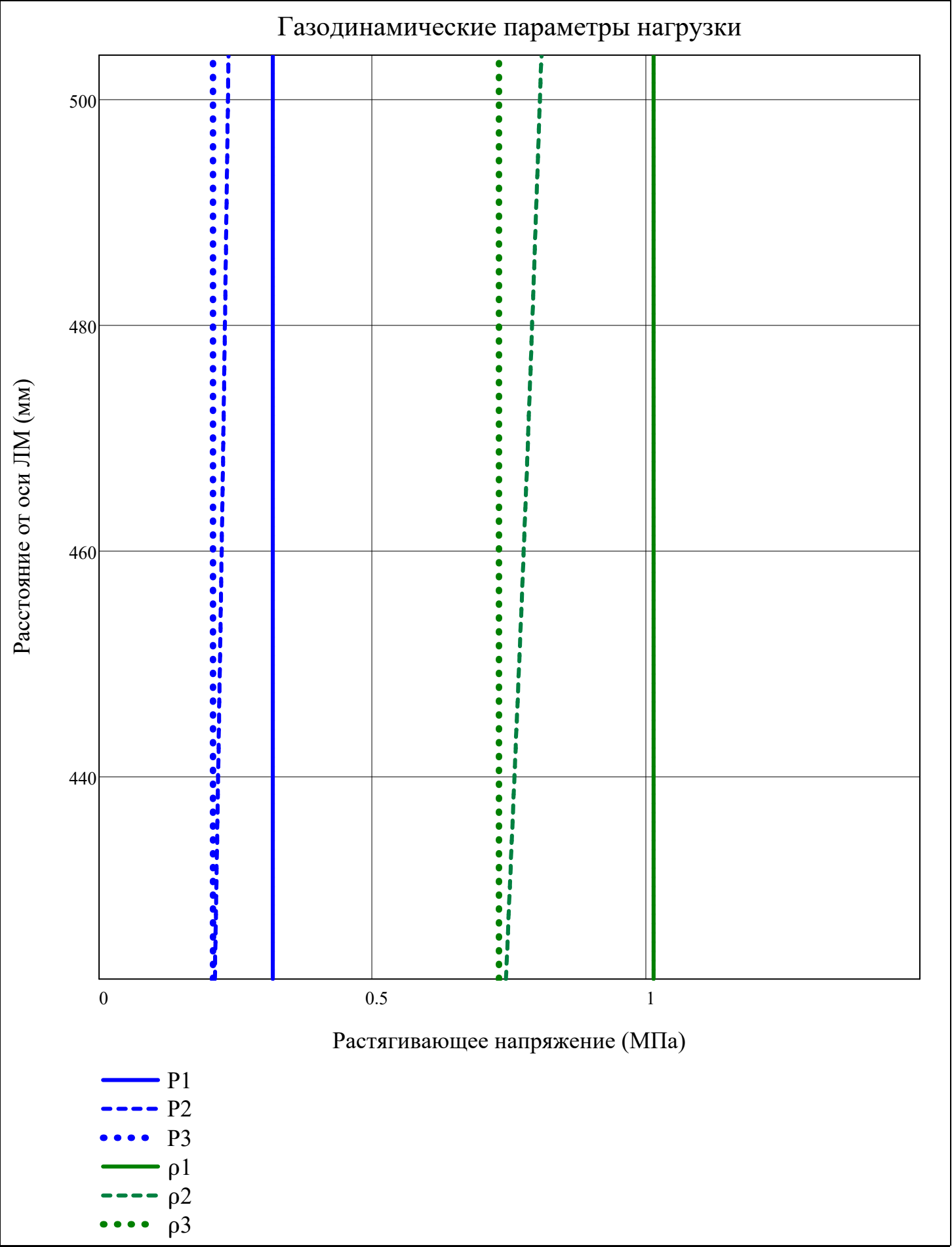
$$z_{rotor} = \begin{cases} \begin{matrix} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \end{matrix} & \text{if type = "compressor"} \\ \begin{matrix} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \end{matrix} & \text{if type = "turbine"} \end{cases}$$

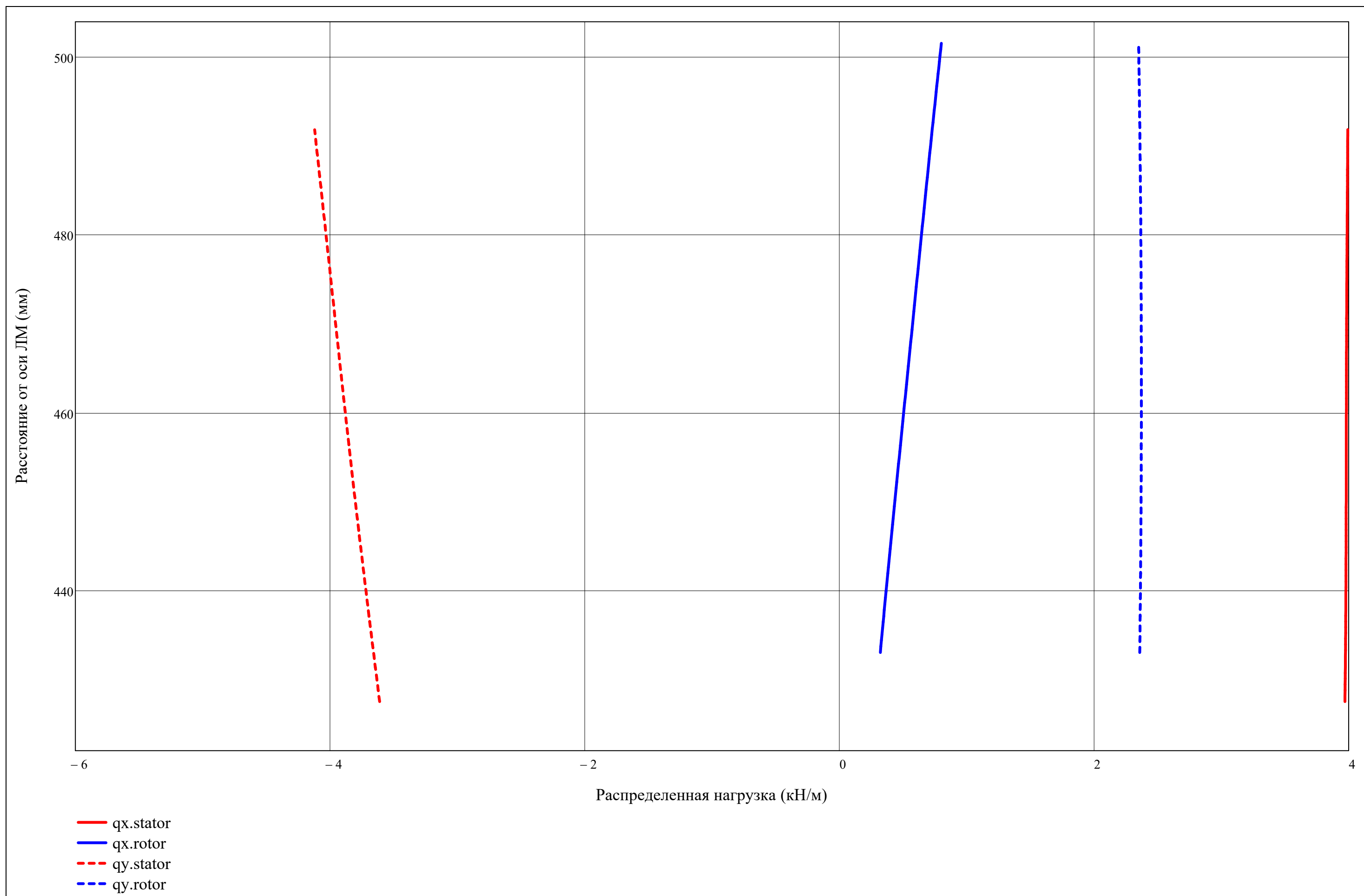
$$z_{stator} = \begin{cases} \begin{matrix} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \end{matrix} & \text{if type = "compressor"} \\ \begin{matrix} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \end{matrix} & \text{if type = "turbine"} \end{cases}$$

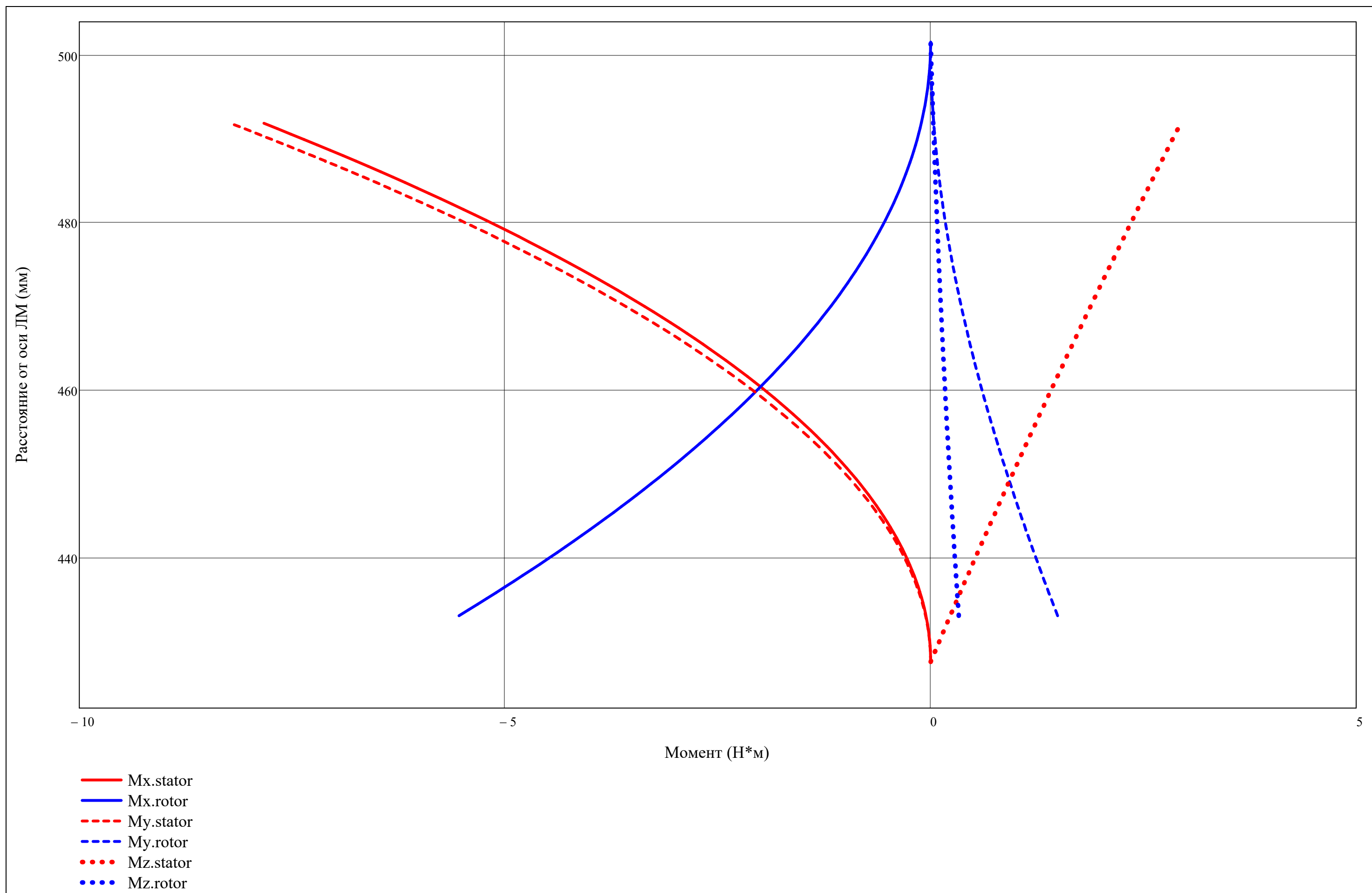


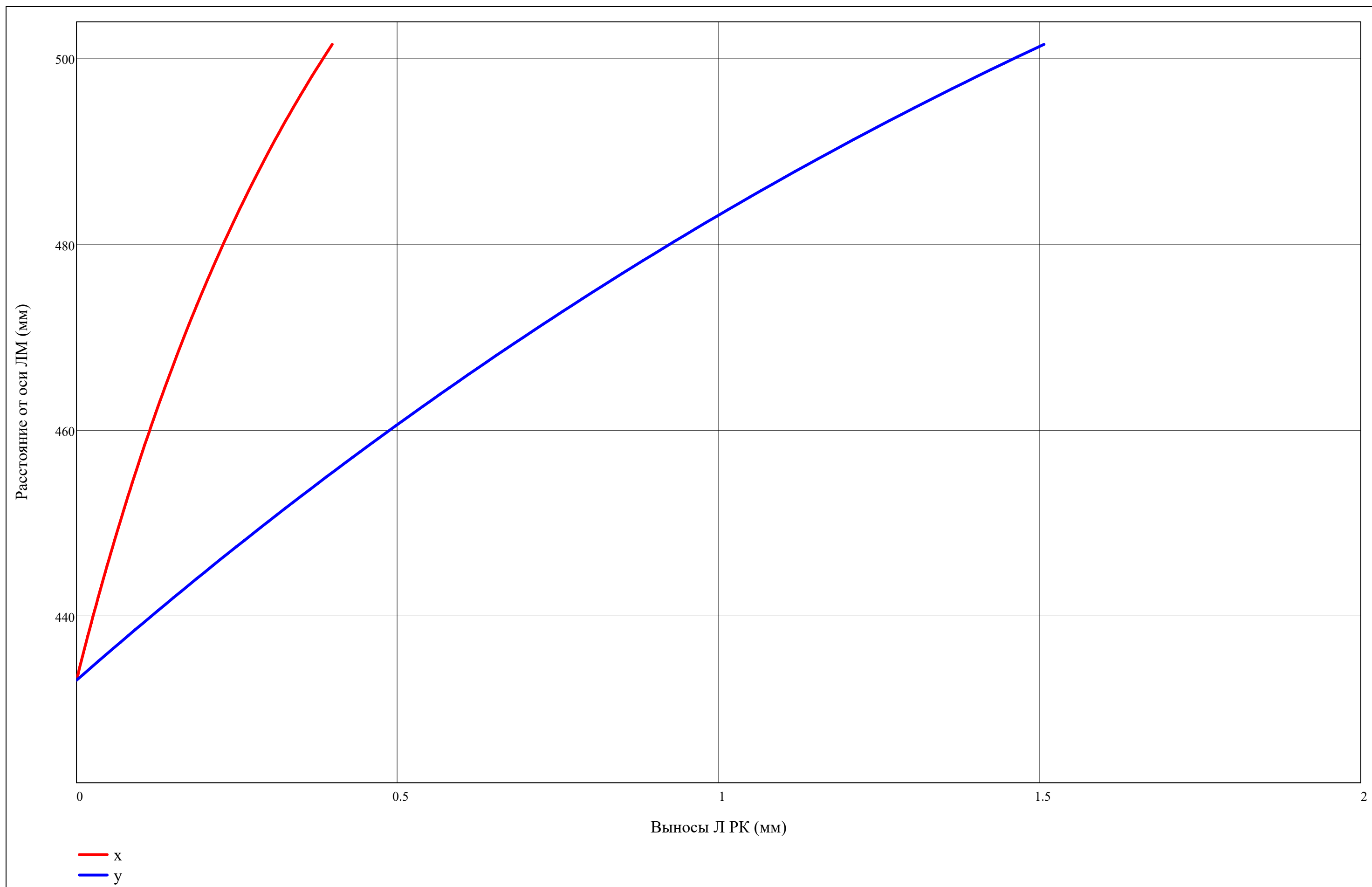




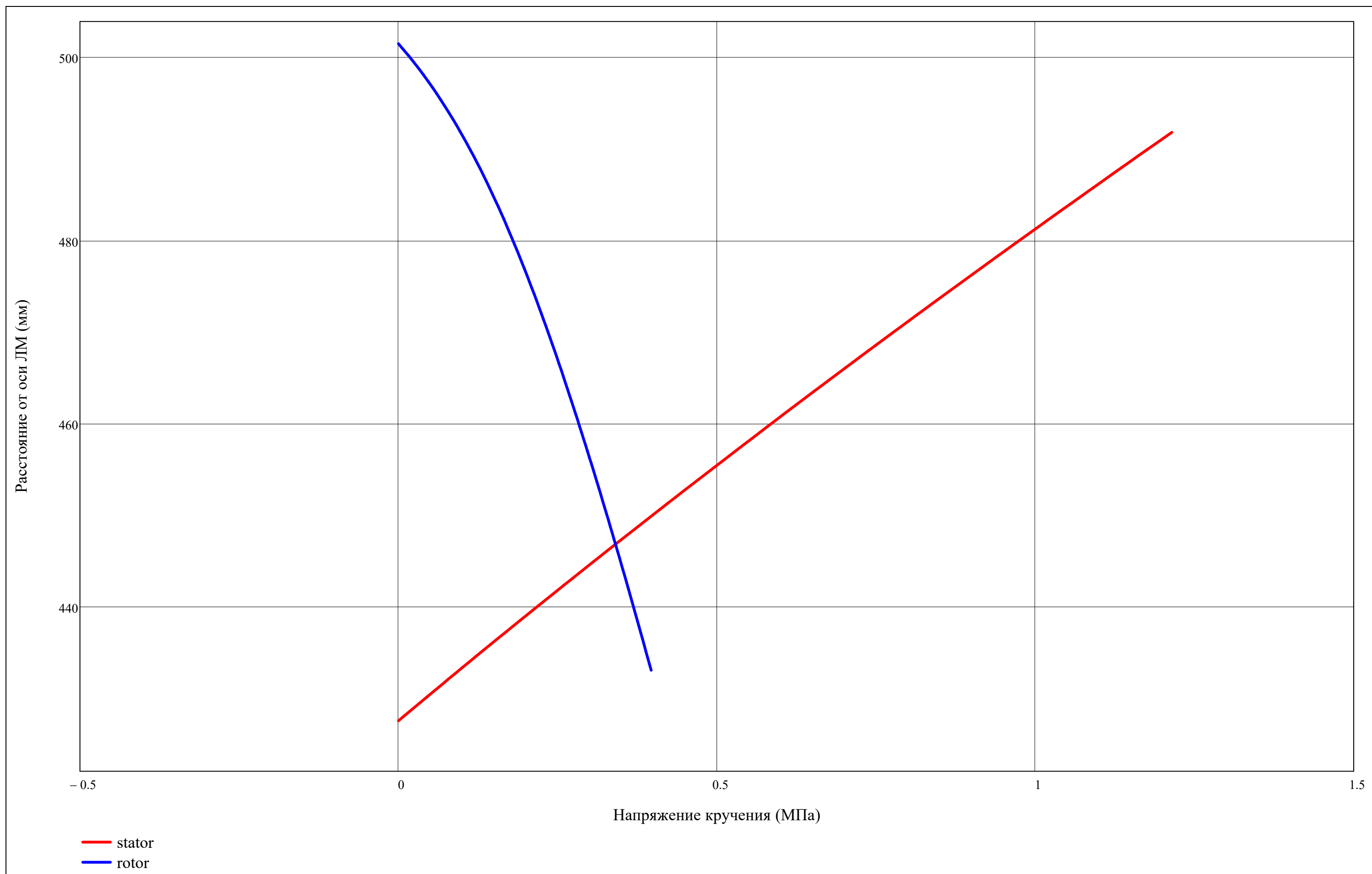


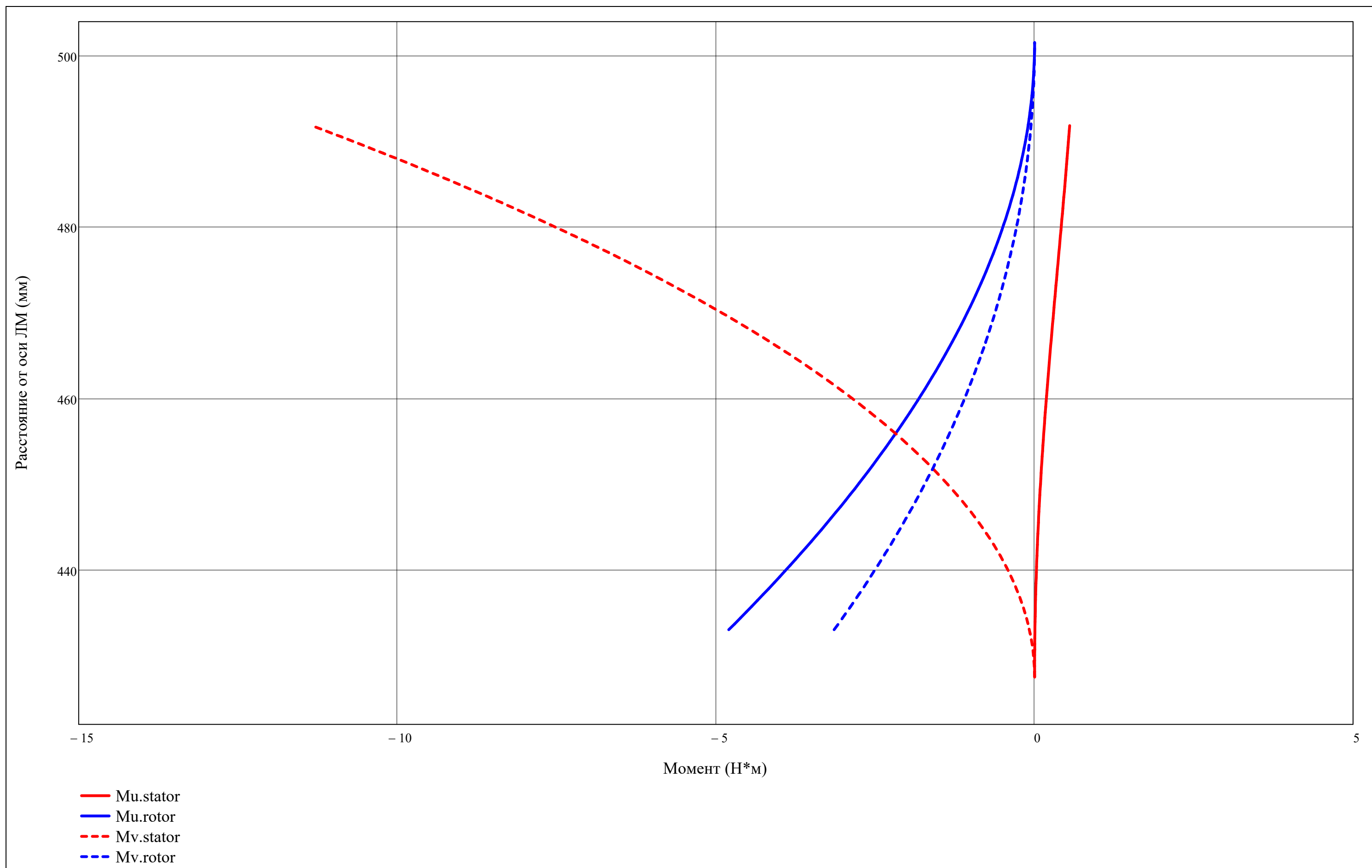


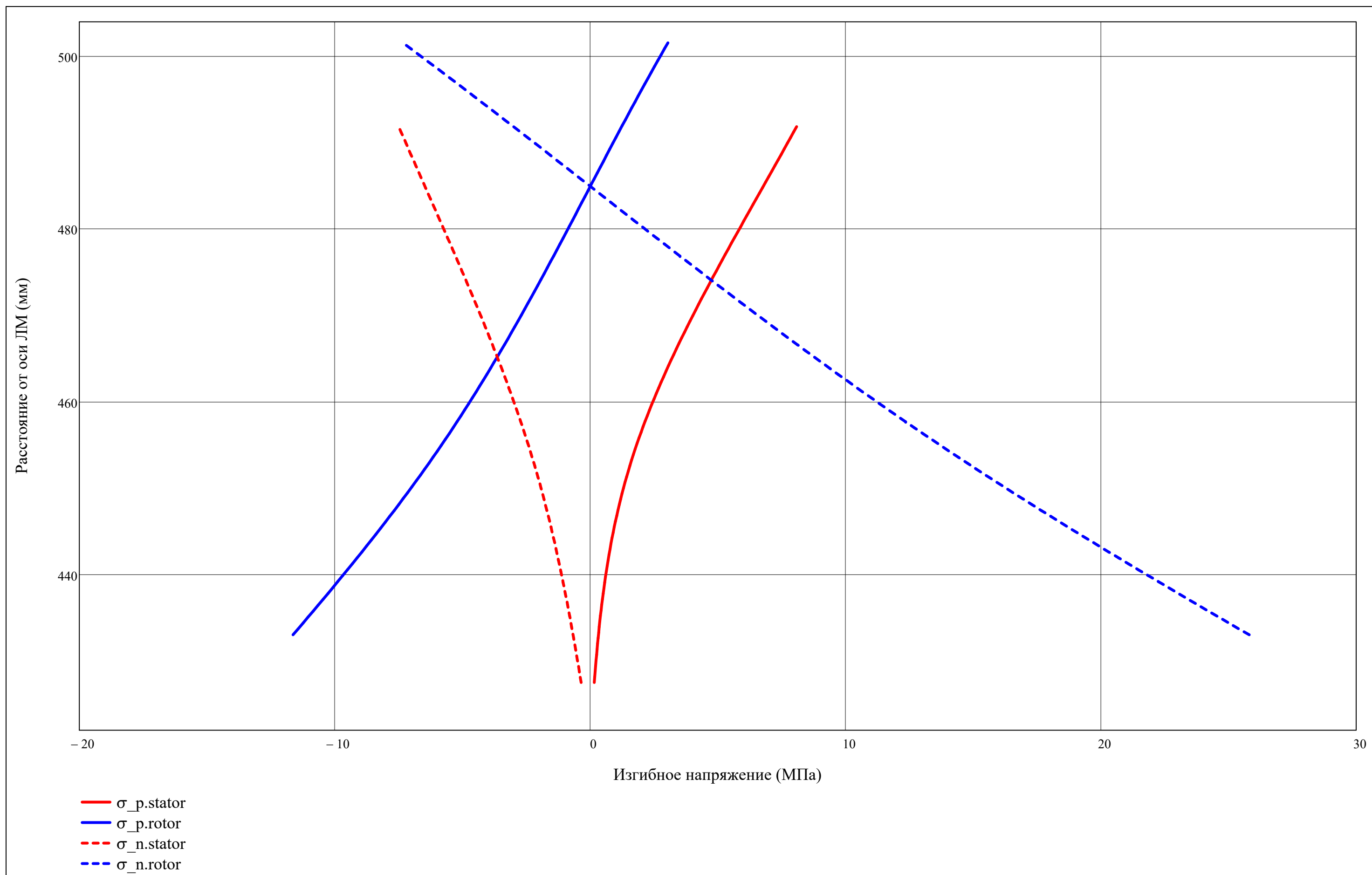


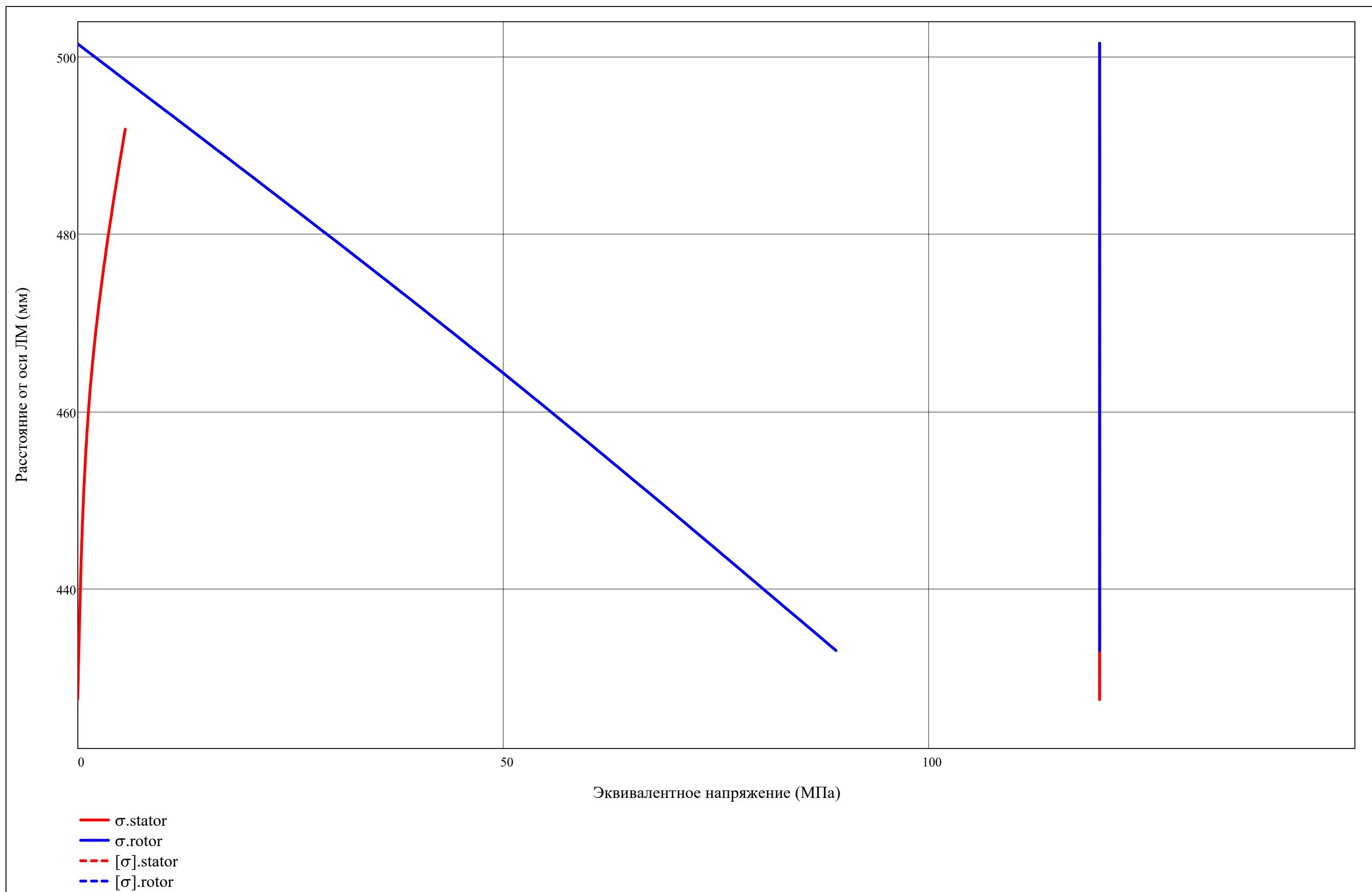




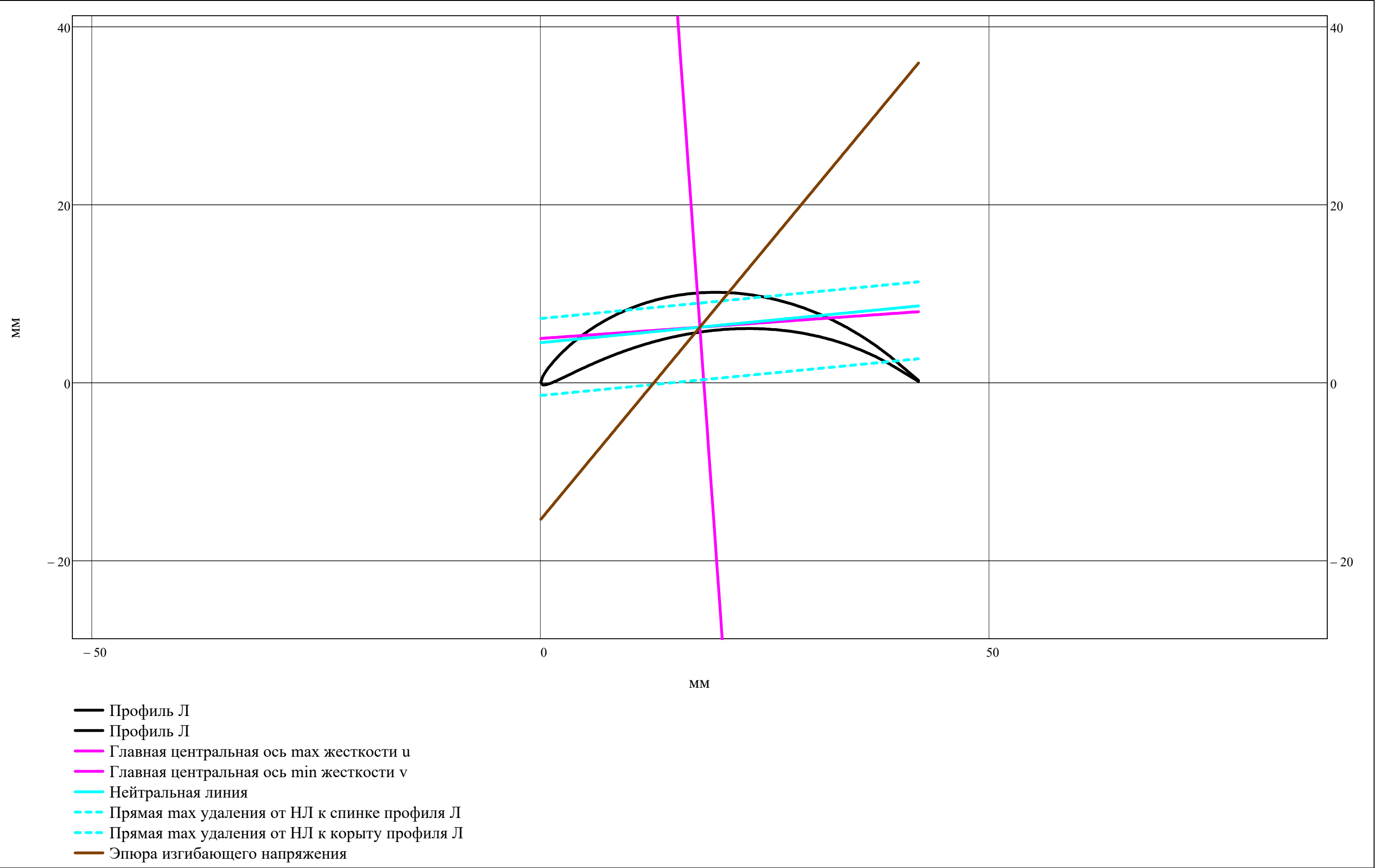












Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{-u_{\text{rotor}_{j,r}}} & v_{-u_{\text{rotor}_{j,r}}} \\ u_{-l_{\text{rotor}_{j,r}}} & v_{-l_{\text{rotor}_{j,r}}} \\ u_{-u_{\text{stator}_{j,r}}} & v_{-u_{\text{stator}_{j,r}}} \\ u_{-l_{\text{stator}_{j,r}}} & v_{-l_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \tr \end{table} \cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{-p_{\text{rotor}_{j,r}}} & \sigma_{-p_{\text{stator}_{j,r}}} \\ \sigma_{-n_{\text{rotor}_{j,r}}} & \sigma_{-n_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{stator}_{j,r}} \\ \text{safety}_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr \tr \tr \tr \end{table}$$





Запас по температуре (K):

$\Delta T_{\text{safety}} = 0$

Выбранный материал Д:

$\text{material\_disk}_i = \begin{cases} \text{"ВЖ175"} & \text{if turbine = "ТВД"} \\ \text{"ЭП742"} & \text{if turbine = "ТНД"} \end{cases}$

Плотность материала Д (кг/м^3):

$\rho_{\text{disk}_i} = \begin{cases} 8266 & \text{if material\_disk}_i = \text{"ВЖ175"} \\ 8320 & \text{if material\_disk}_i = \text{"ЭП742"} \\ 8393 & \text{if material\_disk}_i = \text{"ЖС-6К"} \\ 7900 & \text{if material\_disk}_i = \text{"BT41"} \\ 4500 & \text{if material\_disk}_i = \text{"BT25"} \\ 4570 & \text{if material\_disk}_i = \text{"BT23"} \\ 4510 & \text{if material\_disk}_i = \text{"BT9"} \\ 4430 & \text{if material\_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

Предел длительной прочности Д (Па):

$\sigma_{\text{disk\_long}_i} = 10^6 \cdot \begin{cases} 620 & \text{if material\_disk}_i = \text{"ВЖ175"} \\ 680 & \text{if material\_disk}_i = \text{"ЭП742"} \\ 125 & \text{if material\_disk}_i = \text{"ЖС-6К"} \\ 123 & \text{if material\_disk}_i = \text{"BT41"} \\ 150 & \text{if material\_disk}_i = \text{"BT25"} \\ 230 & \text{if material\_disk}_i = \text{"BT23"} \\ 200 & \text{if material\_disk}_i = \text{"BT9"} \\ 210 & \text{if material\_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

$\text{material\_disk}^T =$ 

|   |         |         |         |         |
|---|---------|---------|---------|---------|
|   | 1       | 2       | 3       | 4       |
| 1 | "ЭП742" | "ЭП742" | "ЭП742" | "ЭП742" |

$\rho_{\text{disk}}^T =$ 

|   |      |      |      |      |
|---|------|------|------|------|
|   | 1    | 2    | 3    | 4    |
| 1 | 8320 | 8320 | 8320 | 8320 |

$\sigma_{\text{disk\_long}}^T =$ 

|   |     |     |     |     |
|---|-----|-----|-----|-----|
|   | 1   | 2   | 3   | 4   |
| 1 | 680 | 680 | 680 | 680 |

$\cdot 10^6$

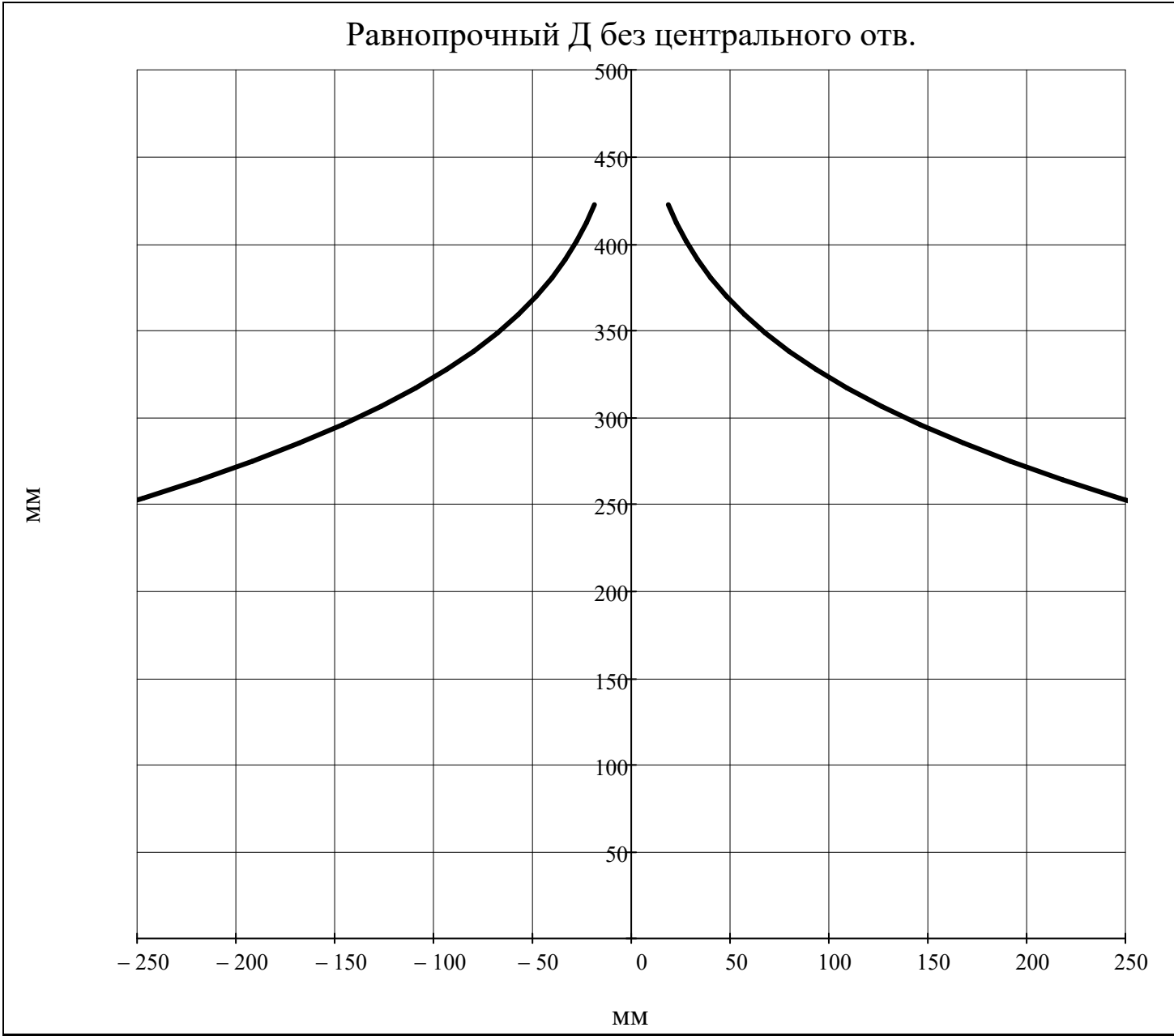
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 4$$

Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{cases} \left(\text{chord}_{\text{rotor}_{i,\text{ORIGIN}}} \cdot \sin\left(v_{\text{rotor}_{i,\text{ORIGIN}}}\right)\right) \cdot e^{\frac{\rho_{\text{disk}_i} \cdot \omega^2}{2} \cdot \frac{1}{\sigma_{z_{\text{rotor}}(i, R_{\text{st}(i,2), \text{ORIGIN}})}} \cdot \left[\left(R_{\text{st}(i,2), \text{ORIGIN}}\right)^2 - z^2\right]} & \text{if } z \leq R_{\text{st}(i,2), \text{ORIGIN}} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$z = 0, \frac{R_{\text{st}(j,2), \text{ORIGIN}}}{N_{\text{dis}}} .. R_{\text{st}(j,2), \text{ORIGIN}}$$



Профилирование равнопрочного Д без центрального отв.

$$type = \begin{cases} type = "stator" & \\ type = \begin{cases} "Нет такого типа!" & \text{if } type \neq "stator" \wedge type \neq "rotor" \\ type & \text{otherwise} \end{cases} & \end{cases} = "stator"$$

Рассматриваемая ступень:

$$j = \begin{cases} j = 1 & \\ j = \begin{cases} "Такой ступени не существует!" & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 1$$























3

$$D^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 650.0 & 650.0 & 617.2 & & & & & & \\ 2 & 678.5 & 678.5 & 662.1 & & & & & & \\ 3 & 707.0 & 707.0 & 707.0 & & & & & & \end{array} \cdot 10^{-3}$$

$$\underline{\underline{R}} = \frac{D}{2}$$

$$R^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 325.0 & 325.0 & 308.6 & & & & & & \\ 2 & 339.2 & 339.2 & 331.0 & & & & & & \\ 3 & 353.5 & 353.5 & 353.5 & & & & & & \end{array} \cdot 10^{-3}$$

$$\bar{d} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..3 \\ \quad \quad \bar{d}_{st(i,a)} = \frac{D_{st(i,a),1}}{D_{st(i,a),N_f}} \\ \bar{d} \end{array}$$

$$\bar{d}^T = \begin{array}{c|cccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.9194 & 0.9194 & 0.8730 & & & & & & \end{array}$$

$$\bar{d}^T \leq 0.9 = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 0 & 0 & 1 \end{array}$$

$$h = \begin{array}{l} \text{for } i \in 1..2Z+1 \\ \quad h_i = \frac{F_i}{\pi \cdot D_{i,av}(N_f)} \\ h \end{array}$$

$$h^T = \begin{array}{c|ccc} & 1 & 2 & 3 \\ \hline 1 & 28.50 & 28.50 & 44.88 \end{array} \cdot 10^{-3}$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 197.2 \\ 511.5 \\ 232.4 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 195.0 \\ 253.8 \\ 232.0 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 282.8 \\ 325.5 \\ 324.6 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 81.44 \\ 29.75 \\ 86.72 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 234.2 \\ 240.3 \\ 240.3 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 43.59 \\ 128.76 \\ 45.62 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 51.69 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 83.14 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 197.0 \\ 483.7 \\ 232.4 \end{pmatrix}$$

$$\begin{pmatrix} c_{ast(j,1),r} \\ c_{ast(j,2),r} \\ c_{ast(j,3),r} \end{pmatrix} = \begin{pmatrix} 196.6 \\ 232.9 \\ 232.4 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 309.0 \\ 285.6 \\ 348.6 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 86.19 \\ 28.78 \\ 89.96 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 251.6 \\ 258.7 \\ 260.0 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 39.50 \\ 125.36 \\ 41.81 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 57.4 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 83.56 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 197.0 \\ 458.7 \\ 232.4 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 197.0 \\ 212.9 \\ 232.1 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 334.2 \\ 249.1 \\ 371.9 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.31 \\ 27.66 \\ 92.70 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 268.9 \\ 277.0 \\ 279.7 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 36.12 \\ 121.27 \\ 38.62 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 62.65 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 82.65 \cdot ^\circ$$



=  
■