

Исходные данные

Коэф. запаса: $\text{safety} = 1.3$

Горючее: Fuel = "Керосин"

turbine = "ТНД"

Высота движения (м): $H_v = 0$

Массовый расход перед Т (кг/с):

Массовый расход утечек Т (кг/с):

Массовый расход на охл Т (кг/с):

$$\begin{pmatrix} G_T \\ G_{\text{leak}} \\ G_{\text{cooling}} \end{pmatrix} = \begin{cases} \begin{pmatrix} 32.30 \\ 106.96 \cdot 10^{-3} \\ 3240.8 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 35.43 \\ 35.65 \cdot 10^{-3} \\ 810.2 \cdot 10^{-3} \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 35.43 \\ \hline 2 & 0.04 \\ \hline 3 & 0.81 \\ \hline \end{array}$$

$$\text{Мощность Т (Вт): } N_T = 10^6 \cdot \begin{cases} 14.893 & \text{if turbine} = \text{"ТВД"} \\ 15.181 & \text{if turbine} = \text{"ТНД"} \end{cases} = 15.181 \cdot 10^6$$

Полное давление перед Т (Па): $P_{\Gamma}^* = 10^3 \cdot \begin{cases} 2731.8 & \text{if turbine} = \text{"ТВД"} \\ 927.5 & \text{if turbine} = \text{"ТНД"} \end{cases} = 927.5 \cdot 10^3$

| | | |
|---------------------------------|------------------|---|
| Полная температура перед Т (К): | $T^*_{\Gamma} =$ | 1773 if turbine = "ТВД" = 1368.9 1368.9 if turbine = "ТНД" |
|---------------------------------|------------------|---|

| | | | |
|----------------------------|-----------------|--------------------------|---------|
| Коэф. избытка воздуха в Т: | $\alpha_{OX} =$ | 2.267 if turbine = "ТВД" | = 2.493 |
| | | 2.493 if turbine = "ТНД" | |

Полное давление отбора охлаждающего воздуха (K):

$$P^*_{cooling} = 10^3 \cdot \begin{cases} 2845.6 & \text{if turbine} = \text{"ТВД"} \\ 319.4 & \text{if turbine} = \text{"ТНД"} \end{cases} = 319.4 \cdot 10^3$$

Полная температура отбора охлаждающего воздуха (K):

| | | | |
|-----------------|---|--------------------------|---------|
| $T^*_{cooling}$ | = | 806.9 if turbine = "ТВД" | = 418.2 |
| | | 418.2 if turbine = "ТНД" | |

Коэф. сохранения полного давления охлаждения: $\sigma_{cooling} = 0.97$

Подогрев охл. от КС [K]: $\Delta T_{\text{охл.подогрев}} = 40$

Газовая постоянная (Дж/кг/К): $R_{\text{газ}}(\alpha_{\text{OX}}, \text{Fuel}) = 288.5$

Допустимая температура Л (К): $T_{Л, доп} = 1373$

Абс. скорость перед Т (м/с):

Абс. скорость после Т (м/с):

[1, с.15]

$80 \leq c_T \leq 400 = 1$

Лопаточный КПД Т:

$\eta_{\text{Л}} = 88\%$

$88\% \leq \eta_{\text{Л}} \leq 95\% = 1$

Угол входа в Т:

$\alpha_T = 90.^{\circ}$

Окр. скорость Л последней ступени на ср. диаметре Т (м/с):

$$\begin{pmatrix} c_{\Gamma} \\ c_T \end{pmatrix} = \begin{cases} \begin{pmatrix} 100 \\ 180 \end{pmatrix} & \text{if turbine = "ТВД"} \\ \begin{pmatrix} 180 \\ 260 \end{pmatrix} & \text{if turbine = "ТНД"} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 180.0 \\ \hline 2 & 260.0 \\ \hline \end{array}$$

$$u_T = \begin{cases} 520 & \text{if turbine = "ТВД"} \\ 260 & \text{if turbine = "ТНД"} \end{cases} = 260.0$$

$z = \text{ORIGIN}..N_T$

Полное давление отбора охлаждающего воздуха (K):
 $P_{cooling}^* = P_{cooling}^* \cdot \sigma_{cooling} = 309.8 \cdot 10^3$

Полная температура отбора охлаждающего воздуха (K):
 $T_{cooling}^* = T_{cooling}^* + \Delta T_{\text{охл.подогрев}} = 458.2$

Массовый расход перед Т (кг/с):
 $G_{T_{in}} = G_T - G_{leak} = 35.4$

Массовый расход после Т (кг/с):
 $G_T = G_T + G_{cooling} = 36.2$

Удельная работа Т (Дж/кг):
 $L_T^* = \frac{N_T}{\text{mean}(G_T, G_T)} = 424.1 \cdot 10^3$

$L_T^* \leq 550 \cdot 10^3 = 1$

Располагаемый теплоперепад в Т (Дж/кг):
 $H_T = \frac{L_T^* + 0.5c_T^2}{\eta_{\text{л}}} = 520.3 \cdot 10^3$

iteration

k_Г

P_Г

T_Г

=

iteration = 0

k_Г = k_{ад}(Cp_{газ}(P*_Г, T*_Г, α_{оx}, Fuel), R_{газ}(α_{оx}, Fuel))

while 1 > 0

iteration = iteration + 1

Cp_Г = $\frac{k_{\Gamma}}{k_{\Gamma} - 1} \cdot R_{газ}(\alpha_{оx}, Fuel)$

T_Г = $T_{\Gamma}^{*} - \frac{c_{\Gamma}^2}{2 \cdot Cp_{\Gamma}}$

P_Г = $P_{\Gamma}^{*} \cdot \left(\frac{T_{\Gamma}}{T_{\Gamma}^{*}}\right)^{\frac{k_{\Gamma}}{k_{\Gamma} - 1}}$

k'_Г = k_{ад}(Cp_{газ}(P_Г, T_Г, α_{оx}, Fuel), R_{газ}(α_{оx}, Fuel))

if |eps("rel", k_Г, k'_Г)| ≤ epsilon

k_Г = k'_Г

break

k_Г = k'_Г

(iteration k_Г P_Г T_Г)^T

| | |
|---|----------|
| | 1 |
| 1 | 1.0 |
| 2 | 1.3 |
| 3 | 890047.3 |
| 4 | 1356.0 |

Количество итераций: iteration = 1

Показатель адиабаты перед Т: k_Г = 1.298

Статическое давление перед Т (Па): P_Г = 890·10³

Статическая температура перед Т (K): T_Г = 1356

Теплоемкость перед Т (Дж/кг/К): Cp_Г = Cp_{газ}(P_Г, T_Г, α_{оx}, Fuel) = 1256

iteration

k_T

P_T

T_T

=

iteration = 0

k_T = k_T

while 1 > 0

iteration = iteration + 1

k_{cp} = mean(k_T, k_T)

Cp = $\frac{k_{cp}}{k_{cp} - 1} \cdot R_{газ}(\alpha_{ox}, Fuel)$

P_T = $P^*_{\Gamma} \cdot \left(1 - \frac{H_T}{Cp \cdot T^*_{\Gamma}}\right)^{\frac{k_{cp}}{k_{cp} - 1}}$

T_T = $T^*_{\Gamma} - \frac{H_T \cdot \eta_{л}}{Cp}$

k'_T = k_{ад}(Cp_{газ}(P_T, T_T, α_{ox}, Fuel), R_{газ}(α_{ox}, Fuel))

if |eps("rel", k_T, k'_T)| ≤ epsilon

k_T = k'_T

break

k_T = k'_T

(iteration k_T P_T T_T)^T

| | |
|---|------------|
| | 1 |
| 1 | 2 |
| 2 | 1.32 |
| 3 | 191463.061 |
| 4 | 994.672 |

Количество итераций: iteration = 2

Показатель адиабаты после T: k_T = 1.320

Статическое давление после T (Па): P_T = 191.5·10³

P_T ≥ P_{атм}(H_υ) = 1

Статическая температура после T (K): T_T = 994.7

Теплоемкость после T (Дж/кг/К): Cp_T = Cp_{газ}(P_T, T_T, α_{ox}, Fuel) = 1190.6

Ср. показатель адиабаты T: $k = \text{mean}\Big(k_\Gamma,k_T\Big) = 1.309$

Ср. теплоемкость T (Дж/кг/К): $C_p = \frac{k}{k-1}\cdot R_{\text{газ}}\Big(\alpha_{\text{ox}},\text{Fuel}\Big) = 1222.3$

Степень понижения давления: $\pi_T = \frac{P_\Gamma^*}{P_T} = 4.84$

Удельный объём перед T (м³/кг): $\left(\begin{array}{c} v_\Gamma \\ v_T \end{array}\right) = R_{\text{газ}}\Big(\alpha_{\text{ox}},\text{Fuel}\Big)\cdot \left(\begin{array}{c} \frac{T_\Gamma}{P_\Gamma} \\ \frac{T_T}{P_T} \end{array}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 0.440 \\ \hline 2 & 1.499 \\ \hline \end{array}$

Площадь кольцевого сечения перед T (м²): $\left(\begin{array}{c} F_\Gamma \\ F_T \end{array}\right) = \left(\begin{array}{c} \frac{G_\Gamma\cdot v_\Gamma}{c_\Gamma} \\ \frac{G_T\cdot v_T}{c_T} \end{array}\right) = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 86421 \\ \hline 2 & 208684 \\ \hline \end{array} \cdot 10^{-6}$

Площадь кольцевого сечения после T (м²):

$$y_0 = 0.55$$

Коэф. использования скорости:

$$\mu_c = \text{mean}(0.7, 1) = 0.9$$

$$0.7 \leq \mu_c \leq 1 = 1$$

▼ Определение количества ступеней T

$$\begin{pmatrix} Z_{\text{recomend}} \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} =$$

$$c_{cp} = \text{mean}(c_T, c_T)$$

$$\alpha_{\text{ВОЗВ}} = 0.025$$
while 1 > 0

$$Z = \text{round} \left[\frac{2 \cdot H_T \cdot \frac{(1 + \alpha_{\text{ВОЗВ}})}{(\mu_c \cdot c_{cp})^2} - 1}{\frac{u_T^2}{(\mu_c \cdot c_{cp})^2 \cdot y_0^2} - 1} \right]$$

break if $\left| \text{eps} \left[\text{"rel"}, \alpha_{\text{ВОЗВ}}, \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}}) \right] \right| < \text{epsilon}$

$$\alpha_{\text{ВОЗВ}} = \frac{Z - 1}{2 \cdot Z} \cdot \left(\pi_T^{\frac{k-1}{k}} - 1 \right) \cdot (1 - \eta_{\text{л}})$$

if $\alpha_{\text{ВОЗВ}} = 0$

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

break

$$\begin{pmatrix} Z \\ \alpha_{\text{ВОЗВ}} \end{pmatrix}$$

| | |
|---|-------|
| | 1 |
| 1 | 5.000 |
| 2 | 0.022 |

Рекомендуемое количество ступеней: $Z_{\text{recomend}} = 5$

Количество ступеней:

$$Z = \begin{cases} 1 & \text{if turbine = "ТВД"} \\ 4 & \text{if turbine = "ТНД"} \end{cases} = 4$$

Дискретизация ступеней: $i = 1 \dots Z$

Дискретизация сечений: $ii = 1 \dots 2 \cdot Z + 1$

▲ Определение количества ступеней T

Выбранный материал Л:

material_blade_i =

"ВКНА-1В" if 1523 ≤ T*_г

"ВЖМ7" if 1323 ≤ T*_г < 1523

"ЖС-36" if 1123 ≤ T*_г < 1323

Плотность материала Л (кг/м^3):

ρ_{blade_i} =

7938 if material_blade_i = "ВКНА-1В"

8390 if material_blade_i = "ВЖМ7"

8760 if material_blade_i = "ЖС-36"

NaN otherwise

Предел длительной прочности Л РК (Па):

σ_{blade_long_i} = 10⁶ ·

205 if material_blade_i = "ВКНА-1В"

120 if material_blade_i = "ВЖМ7"

120 if material_blade_i = "ЖС-36"

NaN otherwise

material_blade^T =

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | "ВЖМ7" | "ВЖМ7" | "ВЖМ7" | "ВЖМ7" |

ρ_{blade}^T =

| | | | | |
|---|------|------|------|------|
| | 1 | 2 | 3 | 4 |
| 1 | 8390 | 8390 | 8390 | 8390 |

σ_{blade_long}^T =

| | | | | |
|---|-----|-----|-----|-----|
| | 1 | 2 | 3 | 4 |
| 1 | 120 | 120 | 120 | 120 |

·10⁶

Коэф. формы:

k_n = 6.8

Модуль Юнга I рода материала Л (Па):

E_{blade} = 210·10⁹

Коэф. Пуассона материала Л():

μ_{steel} = 0.3

Мах частота вращения ротора на входе (об/мин):

$$\sqrt{\frac{\sigma_blade_longZ}{safety \cdot k_n \cdot F_{\Gamma}}} = 12533$$

Мах частота вращения ротора на выходе (об/мин):

$$n_{max} = \sqrt{\frac{\sigma_blade_longZ}{safety \cdot k_n \cdot F_T}} = 8065$$

Рекомендуюмая ном. частота вращения (об/мин):

$$n = n_{max} \cdot 0.95 = 7662$$

Ном. частота вращения (рад/с):

$$\omega = \frac{2 \cdot \pi \cdot n}{60} = 555.0$$

$$n_{\omega} = \begin{cases} 15000 & \text{if turbine = "ТВД"} \\ 5300 & \text{if turbine = "ТНД"} \end{cases} = 5300$$

Ср. диаметр перед Т (м):

$$\begin{pmatrix} D_{\Gamma.cp} \\ D_{T.cp} \end{pmatrix} = \frac{2}{\omega} \cdot \begin{pmatrix} u_T \\ u_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 936.9 \\ \hline 2 & 936.9 \\ \hline \end{array} \cdot 10^{-3}$$

Длина Л первой ступени Т (м):

$$\begin{pmatrix} l_{\Gamma} \\ l_T \end{pmatrix} = \frac{1}{\pi} \cdot \begin{pmatrix} \frac{F_{\Gamma}}{D_{\Gamma.cp}} \\ \frac{F_T}{D_{T.cp}} \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 29.36 \\ \hline 2 & 70.90 \\ \hline \end{array} \cdot 10^{-3}$$

Длина Л последней ступени Т (м):

$$\frac{l_{\Gamma}}{D_{\Gamma.cp}} = \frac{1}{31}$$

$$\frac{l_T}{D_{T.cp}} = \frac{1}{13}$$

Диаметр периферии после Т (м):

$$\begin{pmatrix} D_{T.пер} \\ D_{T.кор} \end{pmatrix} = \begin{pmatrix} D_{T.cp} + l_T \\ D_{T.cp} - l_T \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 1007.8 \\ \hline 2 & 866.0 \\ \hline \end{array} \cdot 10^{-3}$$

Равномерное распределение мощности Т по ступеням (Вт):

$$N_{\text{сТ}_i} = \frac{N_{\text{T}}}{Z}$$

$N_{\text{сТ}}^{\text{T}} =$

| | | | | |
|---|------|------|------|------|
| | 1 | 2 | 3 | 4 |
| 1 | 3.80 | 3.80 | 3.80 | 3.80 |

$\cdot 10^6$

Вид проточной части:
("const", "кор", "сп", "пер", "доля от предыдущего диаметра периферии")

$$\text{ЗППЧ} = \left(\begin{array}{l} \left| \begin{array}{llllll} \text{"const"} & \text{if } Z = 1 & \text{"1.07"} & \text{"1.065"} & \text{"1.03"} & \text{"пер"} & \text{"пер"} \end{array} \right. \\ \left| \begin{array}{l} \text{"кор"} & \text{otherwise} \end{array} \right. \\ \left| \begin{array}{llllll} \text{"пер"} & \text{if } Z = 1 & \text{"1.07"} & \text{"1.05"} & \text{"кор"} & \text{"пер"} & \text{"пер"} \end{array} \right. \\ \left| \begin{array}{l} \text{"1.055"} & \text{otherwise} \end{array} \right. \end{array} \right)^{\text{T}}$$

▼ Определение проточной части ОТ

Линейное распределение кольцевых площадей по сечениям:

$\overset{\text{ww}}{F} =$

| |
|---|
| for $i \in 1..2Z + 1$ |
| $F_i = \frac{F_{\text{T}} - F_{\text{Г}}}{\text{st}(Z, 3) - 1} \cdot i + \left(F_{\text{Г}} - \frac{F_{\text{T}} - F_{\text{Г}}}{\text{st}(Z, 3) - 1} \right)$ |
| for $i \in 1..Z$ |
| for $a \in 2..3$ |
| $F_{\text{st}(i, a)} = F_{\text{st}(i, a-1)} \text{ if } \text{ЗППЧ}_{i, a-1} = \text{"const"}$ |
| F |

$F^{\text{T}} =$

| | | | | | | | | | |
|---|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 86421 | 101704 | 116987 | 132270 | 147553 | 162836 | 178118 | 193401 | 208684 |

$\cdot 10^{-6}$

D =

for i ∈ 2Z + 1

for r ∈ 1..N_r

D_{i,r} =

D_{T.kop} if r = 1

D_{T.cp} if r = av(N_r)

D_{T.nep} if r = N_r

for i ∈ Z..1

for a ∈ 2..1

for r ∈ 1..N_r

D_{st(i,a),r} =

if 3ΠΠΠΨ_{i,a} = "const"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "kop"

D_{st(i,a+1),1} if r = 1

$\frac{1}{2} \cdot \left[D_{st(i,a+1),1} + \sqrt{\left(D_{st(i,a+1),1} \right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}} \right]$ if r = av(N_r)

$\sqrt{\left(D_{st(i,a+1),1} \right)^2 + \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "cp"

D_{st(i,a+1),av(N_r)} − $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = 1

D_{st(i,a+1),av(N_r)} if r = av(N_r)

D_{st(i,a+1),av(N_r)} + $\frac{F_{st(i,a)}}{\pi \cdot D_{st(i,a+1),av(N_r)}}$ if r = N_r

if 3ΠΠΠΨ_{i,a} = "nep"

$\sqrt{\left(D_{st(i,a+1),N_r} \right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}}$ if r = 1

$\frac{1}{2} \cdot \left[\sqrt{\left(D_{st(i,a+1),N_r} \right)^2 - \frac{4 \cdot F_{st(i,a)}}{\pi}} + D_{st(i,a+1),N_r} \right]$ if r = av(N_r)

D if r = N_r

D^T =

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 620.7 | 620.7 | 651.1 | 698.2 | 750.4 | 802.7 | 843.9 | 866.0 | 866.0 |
| 2 | 662.2 | 669.0 | 704.0 | 754.0 | 808.5 | 862.8 | 906.5 | 932.1 | 936.9 |
| 3 | 703.7 | 717.4 | 756.9 | 809.9 | 866.6 | 922.9 | 969.0 | 998.1 | 1007.8 |

·10^{−3}

R_{ww}

=

D

2

R^T =

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 310.3 | 310.3 | 325.6 | 349.1 | 375.2 | 401.4 | 422.0 | 433.0 | 433.0 |
| 2 | 331.1 | 334.5 | 352.0 | 377.0 | 404.2 | 431.4 | 453.2 | 466.0 | 468.5 |
| 3 | 351.9 | 358.7 | 378.4 | 404.9 | 433.3 | 461.4 | 484.5 | 499.1 | 503.9 |

·10^{−3}

d̄ =

for i ∈ 1..Z

for a ∈ 1..3

d̄_{st(i,a)} =

D_{st(i,a),1}

D_{st(i,a),N_r}

d̄

d̄^T =

| | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.8819 | 0.8651 | 0.8602 | 0.8621 | 0.8659 | 0.8698 | 0.8709 | 0.8677 | 0.8593 |

d̄^T ≤ 0.9 =

| | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

h =

for i ∈ 1..2Z + 1

h_i =

F_i

π · D_{i,av(N_r)}

h

h^T =

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 41.54 | 48.39 | 52.90 | 55.84 | 58.09 | 60.07 | 62.55 | 66.05 | 70.90 |

·10^{−3}

D

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 172.2 | 172.2 | 180.7 | 193.8 | 208.2 | 222.8 | 234.2 | 240.3 | 240.3 |
| 2 | 183.8 | 185.7 | 195.4 | 209.3 | 224.4 | 239.4 | 251.6 | 258.7 | 260.0 |
| 3 | 195.3 | 199.1 | 210.0 | 224.7 | 240.5 | 256.1 | 268.9 | 277.0 | 279.7 |

$F^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 86421 | 101704 | 116987 | 132270 | 147553 | 162836 | 178118 | 193401 | 208684 |

$\cdot 10^{-6}$

$\overline{d}_1 = 0.8819$

$\overline{d}_1 \leq 0.9 = 1$

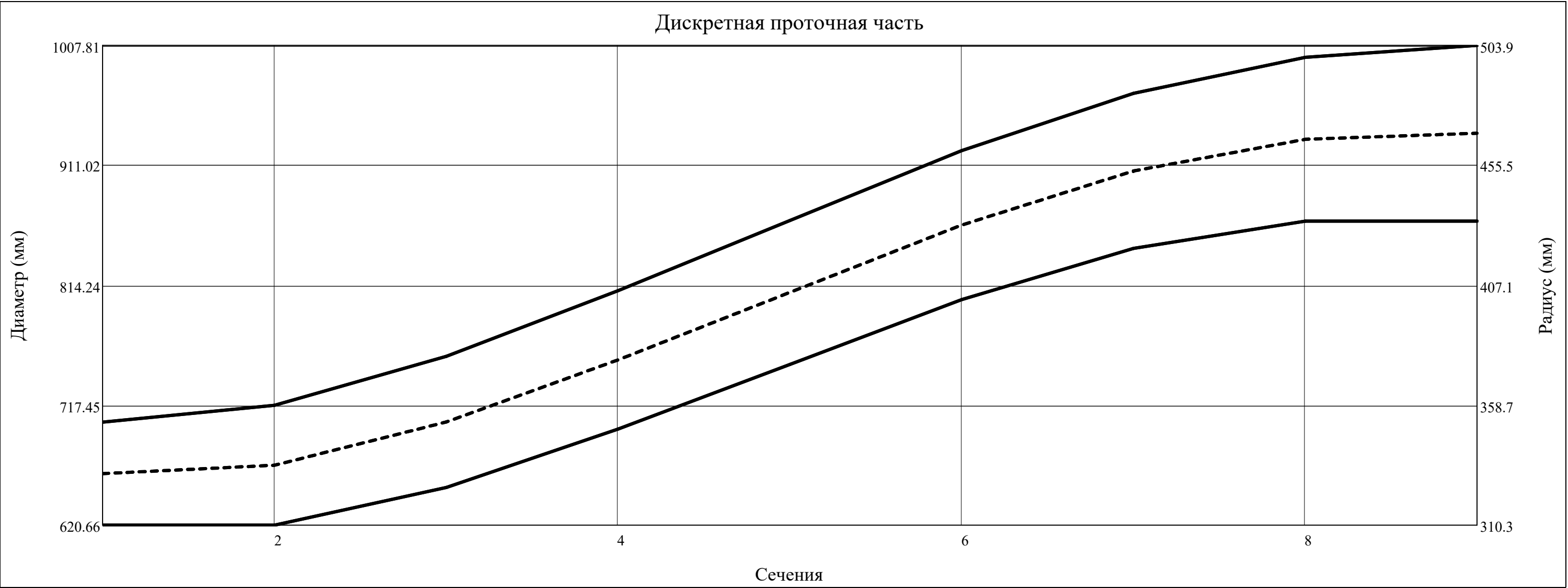
$\overline{d}^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 0.8819 | 0.8651 | 0.8602 | 0.8621 | 0.8659 | 0.8698 | 0.8709 | 0.8677 | 0.8593 |

$D^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|--------|
| 1 | 620.7 | 620.7 | 651.1 | 698.2 | 750.4 | 802.7 | 843.9 | 866.0 | 866.0 |
| 2 | 662.2 | 669.0 | 704.0 | 754.0 | 808.5 | 862.8 | 906.5 | 932.1 | 936.9 |
| 3 | 703.7 | 717.4 | 756.9 | 809.9 | 866.6 | 922.9 | 969.0 | 998.1 | 1007.8 |

$\cdot 10^{-3}$



$h^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 41.54 | 48.39 | 52.90 | 55.84 | 58.09 | 60.07 | 62.55 | 66.05 | 70.90 |

$\cdot 10^{-3}$

Осевая ширина ЛСА и РК [1, с.183]:

$$\begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix} = \left| \begin{array}{l} \text{for } i \in 1..Z \\ \begin{pmatrix} B_{CA_i} \\ B_{PK_i} \end{pmatrix} = \begin{pmatrix} \frac{D_{st(i,2),av(N_r)} - 0.25 \cdot h_{st(i,2)}}{16.4} \\ \frac{D_{st(i,3),av(N_r)}}{22} \end{pmatrix} \end{array} \right| \begin{pmatrix} B_{CA} \\ B_{PK} \end{pmatrix}$$

$$\text{stack}\left(B_{CA}^T, B_{PK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 40.1 & 45.1 & 51.7 & 55.8 \\ \hline 2 & 32.0 & 36.7 & 41.2 & 42.6 \\ \hline \end{array} \cdot 10^{-3}$$

Радиальный зазор (м):

Осевой зазор (м):

(Лучше выбирать большее значение)

$$\begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix} = \left| \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \text{for } a \in 1..3 \\ \left| \begin{array}{l} \Delta_{r_{st(i,a)}} = 0.001 \cdot D_{st(i,a),N_r} \\ \Delta_{a_i} = 0.25 \cdot B_{CA_i} \end{array} \right| \end{array} \end{array} \right| \begin{pmatrix} \Delta_r \\ \Delta_a \end{pmatrix}$$

$$\Delta_r^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.704 & 0.717 & 0.757 & 0.810 & 0.867 & 0.923 & 0.969 & 0.998 & 1.008 \\ \hline \end{array} \cdot 10^{-3}$$

$$\Delta_a^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 10.014 & 11.282 & 12.924 & 13.957 \\ \hline \end{array} \cdot 10^{-3}$$

$$0.2 \leq \frac{\Delta_{a_i}}{B_{CA_i}} \leq 0.25 =$$

| |
|---|
| 1 |
| 1 |
| 1 |
| 1 |

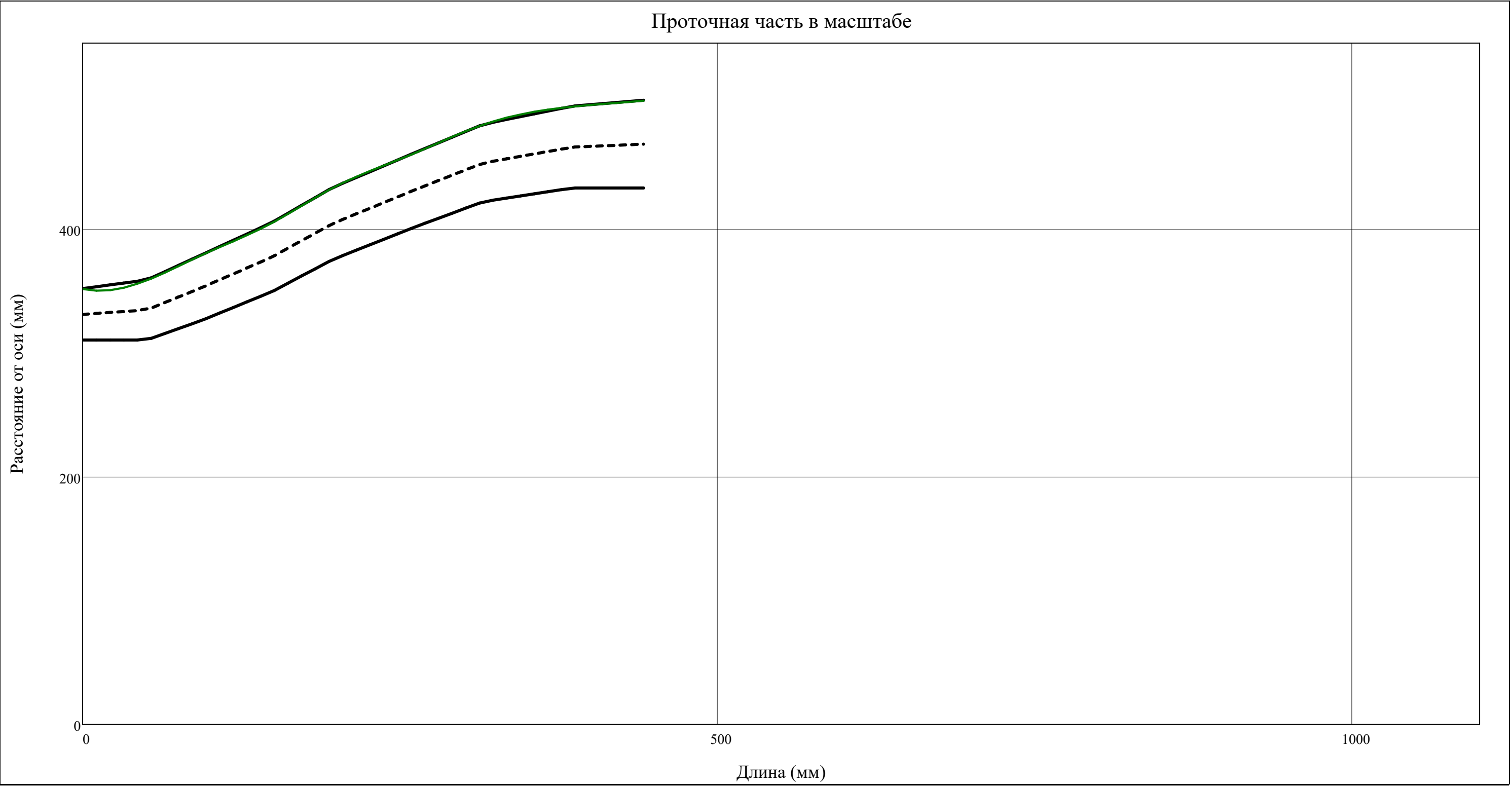
$$\begin{array}{l}
\left(\begin{array}{l} x_{\text{ПЧ}} \\ y_{\text{ПЧпер}} \\ y_{\text{ПЧср}} \\ y_{\text{ПЧкор}} \\ y_{\text{Лпер}} \end{array} \right) = \left\{ \begin{array}{l} c = 1 \\ x_{\text{ПЧ}_c} = 0 \\ y_{\text{ПЧпер}_c} = D_{\text{st}(c, 1), N_r} \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_c} \\ y_{\text{ПЧср}_c} = D_{\text{st}(c, 1), \text{av}(N_r)} \\ y_{\text{ПЧкор}_c} = D_{\text{st}(c, 1), 1} \\ \text{for } i \in 1..Z \\ \left\{ \begin{array}{l} c = c + 1 \\ x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{CA_i} + 0.5 \cdot \Delta_{a_i} \\ \left(\begin{array}{l} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{array} \right) = \left(\begin{array}{l} D_{\text{st}(i, 2), N_r} \\ D_{\text{st}(i, 2), \text{av}(N_r)} \\ D_{\text{st}(i, 2), 1} \end{array} \right) \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_i} \\ c = c + 1 \\ x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta_{a_i} + B_{PK_i} + 0.5 \cdot \Delta_{a_i} \\ \left(\begin{array}{l} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{array} \right) = \left(\begin{array}{l} D_{\text{st}(i+1, 1), N_r} \\ D_{\text{st}(i+1, 1), \text{av}(N_r)} \\ D_{\text{st}(i+1, 1), 1} \end{array} \right) \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta_{r_i} \end{array} \right. \\ \left(\begin{array}{l} x_{\text{ПЧ}} \\ y_{\text{ПЧпер}} \\ y_{\text{ПЧср}} \\ y_{\text{ПЧкор}} \\ y_{\text{Лпер}} \end{array} \right)
\end{array}
\right.
\end{array}$$

$$\text{Length} = \sum_{i=1}^Z B_{CA_i} + \sum_{i=1}^Z \Delta_{a_i} + \sum_{i=1}^Z B_{PK_i} = 393.4 \cdot 10^{-3}$$

$$x = \min(x_{\Pi Q}), \min(x_{\Pi Q}) + \frac{\max(x_{\Pi Q}) - \min(x_{\Pi Q})}{N_{\text{dis}}} .. \max(x_{\Pi Q})$$

$y_{ПЧпер}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧпер}, 1) \quad y_{ПЧср}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧср}, 1) \quad y_{ПЧкор}(l) = \text{linterp}(x_{ПЧ}, 0.5 \cdot y_{ПЧкор}, 1)$

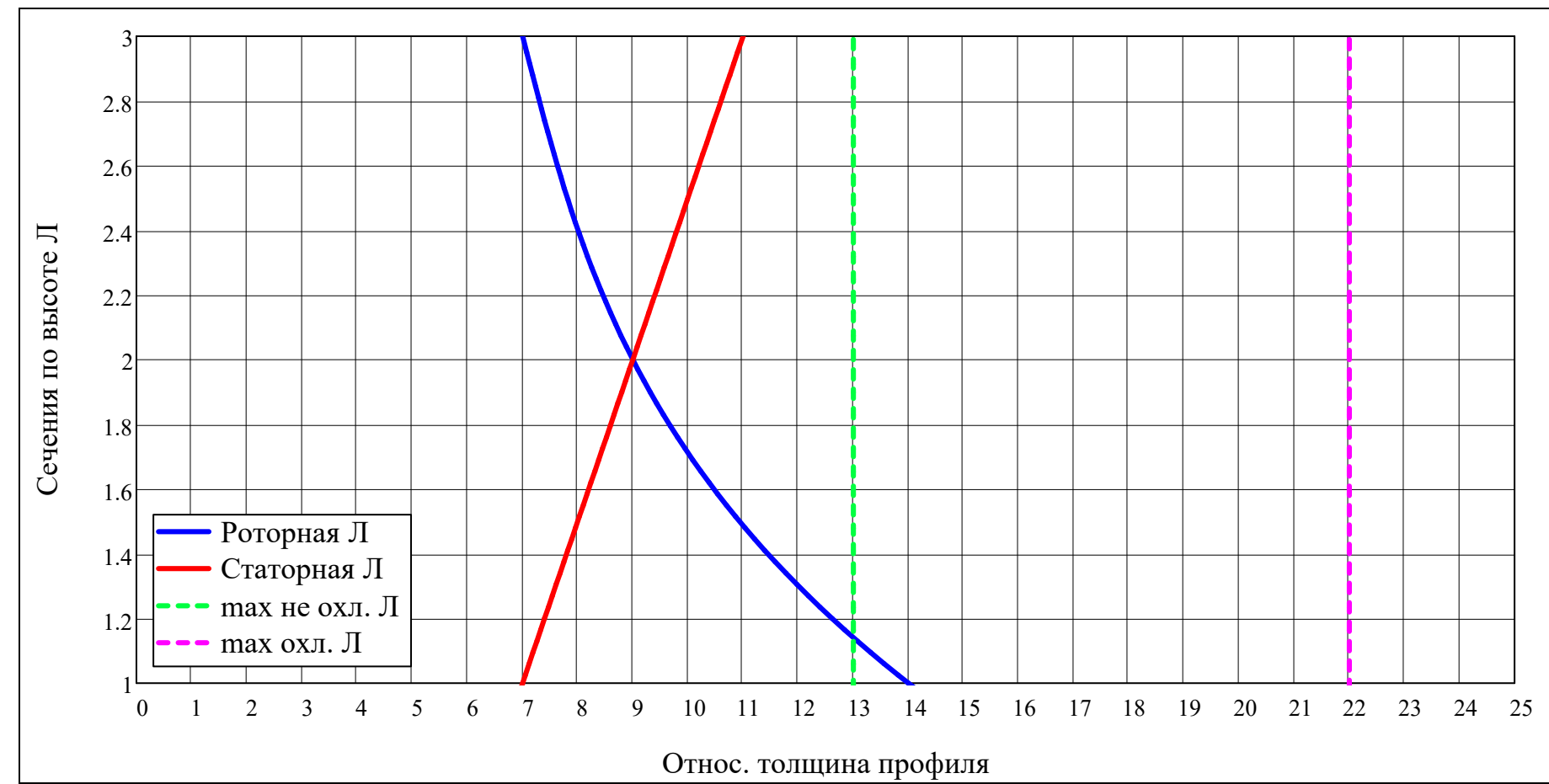
$y_{Лпер}(l) = \text{interp}(\text{cspline}(x_{ПЧ}, 0.5 \cdot y_{Лпер}), x_{ПЧ}, 0.5 \cdot y_{Лпер}, 1)$



Относ. толщины ЛРК и СА:

$$\overline{c}_{\text{stator.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \\ 15 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 15 \\ 15 \\ 15 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 7 \\ 9 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 7 \\ 9 \\ 11 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$

$$\overline{c}_{\text{rotor.}}(r) = \begin{cases} \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 13 \\ 11 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 17 \\ 13 \\ 11 \end{pmatrix} \% , r \right] & \text{if } T_{\text{Л.доп}} < T^*_{\text{г}} \\ \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 14 \\ 9 \\ 7 \end{pmatrix} \% \right], \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 14 \\ 9 \\ 7 \end{pmatrix} \% , r \right] & \text{otherwise} \end{cases}$$



$$\begin{pmatrix} \overline{c}_{\text{stator}} \\ \overline{c}_{\text{rotor}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \overline{c}_{\text{stator}_{i,r}} \\ \overline{c}_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{c}_{\text{stator.}}(r) \\ \overline{c}_{\text{rotor.}}(r) \end{pmatrix} \end{cases}$$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 7.00 | 7.00 | 7.00 | 7.00 |
| 2 | 9.00 | 9.00 | 9.00 | 9.00 |
| 3 | 11.00 | 11.00 | 11.00 | 11.00 |

·%

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 14.00 | 14.00 | 14.00 | 14.00 |
| 2 | 9.00 | 9.00 | 9.00 | 9.00 |
| 3 | 7.00 | 7.00 | 7.00 | 7.00 |

·%

$$\begin{pmatrix} \overline{r}_{inlet_{rotor}} & \overline{r}_{inlet_{stator}} \\ \overline{r}_{outlet_{rotor}} & \overline{r}_{outlet_{stator}} \end{pmatrix} =$$

for i ∈ 1..Z

for r ∈ 1..N_r

$$\begin{pmatrix} \overline{r}_{inlet_{stator}_{i,r}} \\ \overline{r}_{outlet_{stator}_{i,r}} \end{pmatrix} = \overline{c}_{stator.(r)} \cdot \begin{pmatrix} 0.4 \\ 0.2 \end{pmatrix}$$

$$\begin{pmatrix} \overline{r}_{inlet_{rotor}_{i,r}} \\ \overline{r}_{outlet_{rotor}_{i,r}} \end{pmatrix} = \overline{c}_{rotor.(r)} \cdot \begin{pmatrix} 0.35 \\ 0.15 \end{pmatrix}$$

$$\begin{pmatrix} \overline{r}_{inlet_{rotor}} & \overline{r}_{inlet_{stator}} \\ \overline{r}_{outlet_{rotor}} & \overline{r}_{outlet_{stator}} \end{pmatrix}$$

$\overline{r}_{inlet_{stator}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 2.800 | 2.800 | 2.800 | 2.800 |
| 2 | 3.600 | 3.600 | 3.600 | 3.600 |
| 3 | 4.400 | 4.400 | 4.400 | 4.400 |

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$\overline{r}_{outlet_{stator}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 1.400 | 1.400 | 1.400 | 1.400 |
| 2 | 1.800 | 1.800 | 1.800 | 1.800 |
| 3 | 2.200 | 2.200 | 2.200 | 2.200 |

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$\overline{r}_{inlet_{rotor}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 4.900 | 4.900 | 4.900 | 4.900 |
| 2 | 3.150 | 3.150 | 3.150 | 3.150 |
| 3 | 2.450 | 2.450 | 2.450 | 2.450 |

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$\overline{r}_{outlet_{rotor}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 2.100 | 2.100 | 2.100 | 2.100 |
| 2 | 1.350 | 1.350 | 1.350 | 1.350 |
| 3 | 1.050 | 1.050 | 1.050 | 1.050 |

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▶ Вывод результатов поступенчатого расчета продольной геометрии ОТ в EXCEL:

$$R_{L.cp} = \left(\begin{array}{l} 0.16 \text{ if turbine} = \text{"ТВД"} \quad 0.15 \quad 0.18 \quad 0.185 \quad 0.5 \quad 0.5 \\ 0.13 \text{ otherwise} \end{array} \right)^T$$

▼ Поступенчатый расчет ОТ

| iteration _{CA} | iteration _{PK} | |
|---------------------------|-------------------------|--|
| \underline{k} | R_L | |
| $H^*_{ст}$ | $H_{ст}$ | |
| H_{stator} | H_{rotor} | |
| $c_{ад}$ | $w_{ад}$ | |
| P^* | P | |
| T^* | \underline{T} | |
| \underline{G} | v | |
| ρ^* | ρ | |
| $\underline{\alpha_{ox}}$ | α_{ox} | |
| α | β | |
| ϵ_{stator} | ϵ_{rotor} | |
| θ_{CA} | θ_{PK} | |
| $g_{охлCA}$ | $g_{охлPK}$ | |
| a^*_c | a^*_w | |
| $T_{ад}$ | $T_{ад}$ | |
| P^*_w | T^*_w | |
| $a_{зв}$ | $a_{зв}$ | |
| u | u | |
| \underline{c} | c | |
| c_a | c_u | |
| w | w | |
| w_a | w_u | |
| λ_c | M_c | |
| λ_w | M_w | |
| v_{stator} | v_{rotor} | <div><div>=</div><div><div>$r = av(N_r)$</div><div>for $i \in 1..Z$</div><div>$trace(concat("ст\text{v}пень i = " . num2str(i)))$</div></div></div> |

| | |
|---|-------------------------------|
| chord _{stator} | chord _{rotor} |
| $\overline{t}_{\text{оптCA}}$ | $\overline{t}_{\text{оптPK}}$ |
| t_{stator} | t_{rotor} |
| Z_{stator} | Z_{rotor} |
| $\overline{v}_{\text{stator}}$ | $\overline{v}_{\text{rotor}}$ |
| ξ_{TpCA} | ξ_{TpPK} |
| ξ_{kpCA} | ξ_{kpPK} |
| ξ_{ReCA} | ξ_{RePK} |
| $\xi_{\lambda\text{CA}}$ | $\xi_{\lambda\text{PK}}$ |
| $\xi_{\text{ппCA}}$ | $\xi_{\text{ппPK}}$ |
| ξ_{BTCA} | ξ_{BTPK} |
| $\xi_{\text{ТДCA}}$ | $\xi_{\text{ТДPK}}$ |
| ξ_{cmCA} | ξ_{cmPK} |
| $\xi_{\Delta\text{r}}$ | $\xi_{\text{ВЫХ}}$ |
| $\xi_{\text{Tp.B}}$ | $\xi_{\text{Tp.B}}$ |
| L_{CT} | Lu_{CT} |
| $\eta_{\text{МОЩЬ}}$ | $\eta_{\text{ЛОП}}$ |
| η^*_{CT} | η^*_{CT} |
| η_{u1} | η_{u2} |
| ξ_{CA} | ξ_{PK} |
| $(Lu_{\text{нагрузка}} \quad Lu_{\text{нагрузка}})$ | |

if i = 1

$$\alpha_{\text{ox}_{\text{st}(\text{i},1),\text{r}}} = \alpha_{\text{ox}}$$

$$k_{\text{st}(\text{i},1),\text{r}} = k_{\Gamma}$$

$$P^*_{\text{st}(\text{i},1),\text{r}} = P^*_{\Gamma}$$

$$P^*_{\text{w}_{\text{st}(\text{i},1),\text{r}}} = 0$$

$$P_{\text{st}(\text{i},1),\text{r}} = P_{\Gamma}$$

$$T^*_{\text{st}(\text{i},1),\text{r}} = T^*_{\Gamma}$$

$$T^*_{\text{w}_{\text{st}(\text{i},1),\text{r}}} = 0$$

$$T_{\text{st}(\text{i},1),\text{r}} = T_{\Gamma}$$

$$v_{\text{st}(\text{i},1),\text{r}} = \frac{R_{\text{газ}}\Big(\alpha_{\text{ox}_{\text{st}(\text{i},1)}}^{\text{Fuel}}\Big)\cdot T_{\text{st}(\text{i},1),\text{r}}}{P_{\text{st}(\text{i},1),\text{r}}}$$

$$G_{\text{st}(\text{i},1)} = G_{\Gamma}$$

$$c_{\text{st}(\text{i},1),\text{r}} = c_{\Gamma}$$

$$\alpha_{\text{st}(\text{i},1),\text{r}} = \alpha_{\Gamma}$$

$$\begin{pmatrix} c_{\text{u}_{\text{st}(\text{i},1),\text{r}}} \\ c_{\text{a}_{\text{st}(\text{i},1),\text{r}}} \end{pmatrix} = c_{\text{st}(\text{i},1),\text{r}} \cdot \begin{pmatrix} \cos\Big(\alpha_{\text{st}(\text{i},1),\text{r}}\Big) \\ \sin\Big(\alpha_{\text{st}(\text{i},1),\text{r}}\Big) \end{pmatrix}$$

$$w_{\text{st}(\text{i},1),\text{r}} = 0$$

$$\begin{pmatrix} a_{3\text{B}_{\text{st}(\text{i},1),\text{r}}} \\ a^*c_{\text{st}(\text{i},1),\text{r}} \\ a^*w_{\text{st}(\text{i},1),\text{r}} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{\text{st}(\text{i},1),\text{r}}\cdot R_{\text{газ}}\Big(\alpha_{\text{ox}_{\text{st}(\text{i},1)}}^{\text{Fuel}}\Big)\cdot T_{\text{st}(\text{i},1),\text{r}}} \\ \sqrt{\frac{2\cdot k_{\text{st}(\text{i},1),\text{r}}}{1+k_{\text{st}(\text{i},1),\text{r}}}\cdot R_{\text{газ}}\Big(\alpha_{\text{ox}_{\text{st}(\text{i},1)}}^{\text{Fuel}}\Big)\cdot T^*_{\text{st}(\text{i},1),\text{r}}} \\ \sqrt{\frac{2\cdot k_{\text{st}(\text{i},1),\text{r}}}{1+k_{\text{st}(\text{i},1),\text{r}}}\cdot R_{\text{газ}}\Big(\alpha_{\text{ox}_{\text{st}(\text{i},1)}}^{\text{Fuel}}\Big)\cdot T^*_{\text{w}_{\text{st}(\text{i},1),\text{r}}}} \end{pmatrix}$$

$$\begin{pmatrix} \lambda_{\text{c}_{\text{st}(\text{i},1),\text{r}}} \\ \lambda_{\text{w}_{\text{st}(\text{i},1),\text{r}}} \end{pmatrix} = \begin{pmatrix} \frac{c_{\text{st}(\text{i},1),\text{r}}}{a^*c_{\text{st}(\text{i},1),\text{r}}} \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} M_{\text{c}_{\text{st}(\text{i},1),\text{r}}} \\ M_{\text{w}_{\text{st}(\text{i},1),\text{r}}} \end{pmatrix} = \frac{1}{a_{3\text{B}_{\text{st}(\text{i},1),\text{r}}}} \cdot \begin{pmatrix} c_{\text{st}(\text{i},1),\text{r}} \\ w_{\text{st}(\text{i},1),\text{r}} \end{pmatrix}$$

iteration_{cT_i} = 0

while 1 > 0

$$\text{iteration}_{\text{cT}_i} = \text{iteration}_{\text{cT}_i} + 1$$

trace(concat(" iteration.ct = ", num2str(iteration_{CT_i}))))

$$H_{CT_i} = N_{CT_i} \cdot \begin{cases} \frac{1}{G_{st(i,1)} \cdot 0.9} & \text{if } (iteration_{CT_i} = 1) \\ \frac{1}{\text{mean}(G_{st(i,2)}, G_{st(i,3)}) \cdot \eta_{\text{мощь}_i}} & \text{otherwise} \end{cases}$$

$$R_{L_{i,r}} = R_{L.cp_i}$$

$$c_{a_{st(i,1),r}} = \sqrt{2 \cdot H_{CT_i}}$$

$$H_{stator_i} = H_{CT_i} \cdot (1 - R_{L_{i,r}})$$

$$c_{a_{st(i,2),r}} = \sqrt{2 \cdot H_{stator_i}}$$

$$\bar{v}_{stator_i} = 1$$

$$iteration_{CA_i} = 0$$

while 1 > 0

$$iteration_{CA_i} = iteration_{CA_i} + 1$$

trace(concat(" iteration.CA = ", num2str(iteration_{CA_i}))))

$$c_{st(i,2),r} = \bar{v}_{stator_i} \cdot c_{a_{st(i,2),r}}$$

$$\theta_{CA_i} = \theta_{\text{глубина}}(T^*_{st(i,1),r}, T^*_{\text{cooling}}, T_{\text{Л.доп}})$$

$$g_{\text{охл}CA_i} = \begin{cases} \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} & \text{if } \frac{0.035 \cdot \theta_{CA_i}}{1 - \theta_{CA_i}} \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{st(i,2)} = G_{st(i,1)} \cdot (1 + g_{\text{охл}CA_i})$$

$$\alpha_{\text{ox}_{st(i,2)}} = \alpha_{\text{ox}_{st(i,1)}} + g_{\text{охл}CA_i}$$

$$\alpha_{\text{ок}CA_i} = \text{mean}(\alpha_{\text{ox}_{st(i,1)}}, \alpha_{\text{ox}_{st(i,2)}})$$

$$k_{st(i,2),r} = k_{st(i,1),r}$$

while 1 > 0

$$k_{CA_i} = \text{mean}(k_{st(i,1),r}, k_{st(i,2),r})$$

$$T_{a_{st(i,2),r}} = T^*_{st(i,1),r} - \frac{H_{stator_i}}{\frac{k_{CA_i}}{k_{CA_i} - 1} \cdot R_{\text{раз.cp}}(\alpha_{\text{ox}_{st(i,1)}}, \alpha_{\text{ox}_{st(i,2)}}, \text{Fuel})}$$

k_{CA} .

$$P_{st(i,2),r} = P_{st(i,1),r}^{*} \cdot \left(\frac{T_{ad_{st(i,2),r}}}{T_{st(i,1),r}^{*}} \right)^{\frac{\gamma_{r,i}}{k_{CA_i}-1}}$$

$$T_{st(i,2),r} = T_{st(i,1),r}^{*} - \frac{H_{stator_i} \cdot \left(\overline{v}_{stator_i} \right)^2}{\frac{k_{CA_i}}{k_{CA_i}-1} \cdot R_{газ.cp} \left(\alpha_{ox_{st(i,1)}}, \alpha_{ox_{st(i,2)}}, Fuel \right)}$$

$$Cp_2 = Cp_{газ} \left(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}}, Fuel \right)$$

$$k' = k_{ад} \left(Cp_2, R_{газ} \left(\alpha_{ox_{st(i,2)}}, Fuel \right) \right)$$

$$\text{if } \left| \text{eps}("rel", k_{st(i,2),r}, k') \right| \leq \text{epsilon}$$

$$\left| k_{st(i,2),r} = k' \right.$$

$$\left| \text{break} \right.$$

$$k_{st(i,2),r} = k'$$

$$T_{ad_{st(i,2),r}}^{*} = T_{st(i,2),r} + \frac{\left(c_{st(i,2),r} \right)^2}{2 \cdot Cp_{газ} \left(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}}, Fuel \right)}$$

$$P_{ad_{st(i,2),r}}^{*} = P_{st(i,2),r} \cdot \left(\frac{T_{ad_{st(i,2),r}}^{*}}{T_{st(i,2),r}} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r}-1}}$$

$$\left(\begin{array}{c} T_{cm_{st(i,2),r}}^{*} \\ P_{cm_{st(i,2),r}}^{*} \end{array} \right) = \left[\begin{array}{c} T_{смешение} \left[P_{ad_{st(i,2),r}}^{*}, T_{ad_{st(i,2),r}}^{*}, G_{st(i,1)}, \alpha_{ox_{st(i,1)}}, P_{cooling}^{*}, T_{cooling}^{*}, \left(g_{oxлCA_i} \cdot G_{st(i,1)} \right), \alpha_{ox_{st(i,2)}}, Fuel \right] \\ P_{смешение} \left[P_{ad_{st(i,2),r}}^{*}, G_{st(i,1)}, P_{cooling}^{*}, \left(g_{oxлCA_i} \cdot G_{st(i,1)} \right) \right] \end{array} \right]$$

$$\left(\begin{array}{c} T_{st(i,2),r}^{*} \\ P_{st(i,2),r}^{*} \end{array} \right) = \left(\begin{array}{c} T_{cm_{st(i,2),r}}^{*} \\ P_{cm_{st(i,2),r}}^{*} \end{array} \right)$$

$$T_{st(i,2),r} = T_{st(i,2),r}^{*} - \frac{\left(c_{st(i,2),r} \right)^2}{2 \cdot Cp_{газ} \left(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}}, Fuel \right)}$$

$$P_{st(i,2),r} = P_{st(i,2),r}^{*} \cdot \left(\frac{T_{st(i,2),r}}{T_{st(i,2),r}^{*}} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r}-1}}$$

$$k_{st(i,2),r} = k_{ад} \left(Cp_{газ} \left(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}}, Fuel \right), R_{газ} \left(\alpha_{ox_{st(i,2)}}, Fuel \right) \right)$$

$$v_{st(i,2),r} = \frac{R_{газ} \left(\alpha_{ox_{st(i,2)}}, Fuel \right) \cdot T_{st(i,2),r}}{P_{st(i,2),r}}$$

$$\alpha_{st(i),r} = \text{asin} \left(\frac{G_{st(i,2)} \cdot v_{st(i,2),r}}{\dots} \right)$$

$$F_{st(i,2),r} = \sqrt{F_{st(i,2)}^2 + c_{st(i,2),r}^2 - 2 \cdot F_{st(i,2)} \cdot c_{st(i,2),r} \cdot \cos(\alpha_{st(i,2),r})}$$

$$\begin{pmatrix} c_{u_{st(i,2),r}} \\ c_{a_{st(i,2),r}} \end{pmatrix} = c_{st(i,2),r} \cdot \begin{pmatrix} \cos(\alpha_{st(i,2),r}) \\ \sin(\alpha_{st(i,2),r}) \end{pmatrix}$$

$$\beta_{st(i,2),r} = \text{triangle}(c_{a_{st(i,2),r}}, c_{u_{st(i,2),r}} - u_{st(i,2),r})$$

$$w_{st(i,2),r} = \sqrt{(c_{st(i,2),r})^2 + (u_{st(i,2),r})^2 - 2 \cdot c_{st(i,2),r} \cdot u_{st(i,2),r} \cdot \cos(\alpha_{st(i,2),r})}$$

$$\begin{pmatrix} w_{u_{st(i,2),r}} \\ w_{a_{st(i,2),r}} \end{pmatrix} = w_{st(i,2),r} \cdot \begin{pmatrix} \cos(\beta_{st(i,2),r}) \\ \sin(\beta_{st(i,2),r}) \end{pmatrix}$$

$$T^*_{w_{st(i,2),r}} = T_{st(i,2),r} + \frac{(w_{st(i,2),r})^2}{2 \cdot C_{p_{\Gamma a3}}(P_{st(i,2),r}, T_{st(i,2),r}, \alpha_{ox_{st(i,2)}} , Fuel)}$$

$$P^*_{w_{st(i,2),r}} = P_{st(i,2),r} \cdot \left(\frac{T^*_{w_{st(i,2),r}}}{T_{st(i,2),r}} \right)^{\frac{k_{st(i,2),r}}{k_{st(i,2),r}-1}}$$

$$\begin{pmatrix} a_{3B_{st(i,2),r}} \\ a^*_{c_{st(i,2),r}} \\ a^*_{w_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,2),r} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T_{st(i,2),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,2),r}}{k_{st(i,2),r} + 1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T^*_{st(i,2),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,2),r}}{k_{st(i,2),r} + 1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,2)}} , Fuel) \cdot T^*_{w_{st(i,2),r}}} \end{pmatrix}$$

$$\begin{pmatrix} \lambda_{c_{st(i,2),r}} \\ \lambda_{w_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} \frac{c_{st(i,2),r}}{a^*_{c_{st(i,2),r}}} \\ \frac{w_{st(i,2),r}}{a^*_{w_{st(i,2),r}}} \end{pmatrix}$$

$$\begin{pmatrix} M_{c_{st(i,2),r}} \\ M_{w_{st(i,2),r}} \end{pmatrix} = \frac{1}{a_{3B_{st(i,2),r}}} \cdot \begin{pmatrix} c_{st(i,2),r} \\ w_{st(i,2),r} \end{pmatrix}$$

$$v_{stator_i} = v_{установка}(\alpha_{st(i,1),r}, \alpha_{st(i,2),r})$$

$$chord_{stator_{i,r}} = \frac{B_{CA_i}}{\sin(v_{stator_i})}$$

$$\overline{t}_{оптCA_i} = \overline{t}_{опт}("CA", g_{охлCA_i} > 0, \alpha_{st(i,1),r}, \alpha_{st(i,2),r}, \max(\text{submatrix}(\overline{c}_{stator}, i, i, 1, N_r)))$$

$$Z_{stator_i} = \left\lceil \frac{\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r})}{\overline{t}_{оптCA_i} \cdot chord_{stator_{i,r}}} \right\rceil \text{ if } \text{mod} \left(\left\lceil \frac{\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r})}{\overline{t}_{оптCA_i} \cdot chord_{stator_{i,r}}} \right\rceil, 2 \right) = 0$$

$$Z_{stator_i} = \left\lceil \frac{\pi \cdot \text{mean}(D_{st(i,1),r}, D_{st(i,2),r})}{\overline{t}_{оптCA_i} \cdot chord_{stator_{i,r}}} \right\rceil$$

$$\left\lceil \frac{\pi \cdot \text{mean}(D_{\text{st}(1,1),r}, D_{\text{st}(1,2),r})}{\bar{t}_{\text{оттCA}_i} \cdot \text{chord}_{\text{stator}_{i,r}}} \right\rceil + 1 \quad \text{otherwise}$$

for $r \in 1..N_r$

$$t_{\text{stator}_{i,r}} = \frac{\pi \cdot \text{mean}(D_{\text{st}(i,1),r}, D_{\text{st}(i,2),r})}{Z_{\text{stator}_i}}$$

$$\xi_{\text{трCA}_i} = \xi_{\text{трение}}(\alpha_{\text{st}(i,1),r}, \alpha_{\text{st}(i,2),r})$$

$$\xi_{\text{крCA}_i} = \xi_{\text{кромка}}(\bar{r}_{\text{outlet}_{\text{stator}_{i,r}}} \cdot \text{chord}_{\text{stator}_{i,r}}, t_{\text{stator}_{i,r}}, \alpha_{\text{st}(i,2),r})$$

$$\xi_{\text{РеCA}_i} = \xi_{\text{Ре}}\left(\frac{c_{\text{st}(i,2),r} \cdot \text{chord}_{\text{stator}_{i,r}}}{\mu_{\text{газ}}(T_{\text{st}(i,2),r}, \alpha_{\text{ox}_{\text{st}(i,2)}}) \cdot v_{\text{st}(i,2),r}}\right)$$

$$\xi_{\lambda\text{CA}_i} = \xi_{\text{сжимаемость}}("CA", \lambda_{c_{\text{st}(i,2),r}})$$

$$\xi_{\text{прCA}_i} = \xi_{\text{трCA}_i} + \xi_{\text{крCA}_i} + \xi_{\text{РеCA}_i} + \xi_{\lambda\text{CA}_i}$$

$$\xi_{\text{втCA}_i} = \xi_{\text{вторичные}}(\xi_{\text{трCA}_i}, t_{\text{stator}_{i,r}}, \alpha_{\text{st}(i,2),r}, h_{\text{st}(i,2)})$$

$$\xi_{\text{тдCA}_i} = \frac{\xi_{\text{тд}}("CA", T_{\text{см}_{\text{st}(i,2),r}}^*, T_{\text{ад}_{\text{st}(i,2),r}}^*, P_{\text{st}(i,2),r}, C_{p_{\text{газ}}}(P_{\text{st}(i,2),r}, T_{\text{st}(i,2),r}, \alpha_{\text{ox}_{\text{st}(i,2)}}), \text{Fuel}), R_{\text{газ}}(\alpha_{\text{ox}_{\text{st}(i,2)}}), \text{Fuel}), G_{\text{st}(i,2)}, F_{\text{st}(i,2)}, \alpha_{\text{st}(i,2),r}, 0)}{H_{\text{stator}_i}}$$

$$\xi_{\text{смCA}_i} = \xi_{\text{смешение}}("CA", g_{\text{охлCA}_i})$$

$$\text{if } \left| \text{eps}("rel", \sqrt{1 - \xi_{\text{смCA}_i} - \xi_{\text{тдCA}_i} - \xi_{\text{втCA}_i} - \xi_{\text{прCA}_i}}, \bar{v}_{\text{stator}_i}) \right| \leq \text{epsilon}$$

$$\left| \bar{v}_{\text{stator}_i} = \sqrt{1 - \xi_{\text{смCA}_i} - \xi_{\text{тдCA}_i} - \xi_{\text{втCA}_i} - \xi_{\text{прCA}_i}} \right|$$

break

$$\bar{v}_{\text{stator}_i} = \sqrt{1 - \xi_{\text{смCA}_i} - \xi_{\text{тдCA}_i} - \xi_{\text{втCA}_i} - \xi_{\text{прCA}_i}}$$

$$H_{\text{rotor}_i} = H_{\text{ср}_i} \cdot R_{L_{i,\text{av}}(N_r)} \cdot \frac{T_{\text{st}(i,2),r}}{T_{\text{ад}_{\text{st}(i,2),r}}}$$

$$w_{\text{ад}_{\text{st}(i,3),r}} = \sqrt{(w_{\text{st}(i,2),r})^2 + 2 \cdot H_{\text{rotor}_i} + (u_{\text{st}(i,3),r})^2 - (u_{\text{st}(i,2),r})^2}$$

$$\bar{v}_{\text{rotor}_i} = 1$$

$$\text{iteration}_{\text{пК}_i} = 0$$

while $1 > 0$

$$\text{iteration}_{\text{пК}_i} = \text{iteration}_{\text{пК}_i} + 1$$

$$\text{trace}\left(\text{concat}\left(" \quad \text{iteration.PK} = ", \text{num2str}(\text{iteration}_{\text{пК}_i})\right)\right)$$

$$w_{\text{st}(i,3),r} = \bar{v}_{\text{rotor}_i} \cdot w_{\text{ад}_{\text{st}(i,3),r}}$$

$$\theta_{PK_i} = \theta_{\text{глубина}}(T_{w_{st(i,2),r}}^*, T_{cooling}^*, T_{\text{Л.доп}})$$

$$g_{\text{охл}PK_i} = \begin{cases} \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} & \text{if } \frac{0.035 \cdot \theta_{PK_i}}{1 - \theta_{PK_i}} \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{st(i,3)} = G_{st(i,2)} \cdot (1 + g_{\text{охл}PK_i})$$

$$\alpha_{\text{ox}_{st(i,3)}} = \alpha_{\text{ox}_{st(i,2)}} + g_{\text{охл}PK_i}$$

$$k_{st(i,3),r} = k_{st(i,2),r}$$

while 1 > 0

$$k_{PK_i} = \text{mean}(k_{st(i,2),r}, k_{st(i,3),r})$$

$$T_{a_{st(i,3),r}} = T_{st(i,2),r} - \frac{H_{\text{rotor}_i}}{\frac{k_{PK_i}}{k_{PK_i} - 1} \cdot R_{\text{газ.ср}}(\alpha_{\text{ox}_{st(i,2)}}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})}$$

$$P_{st(i,3),r} = P_{st(i,2),r} \cdot \left(\frac{T_{a_{st(i,3),r}}}{T_{st(i,2),r}} \right)^{\frac{k_{PK_i}}{k_{PK_i} - 1}}$$

$$T_{st(i,3),r} = T_{st(i,2),r} - \frac{(w_{st(i,3),r})^2 - (w_{st(i,2),r})^2 - (u_{st(i,3),r})^2 + (u_{st(i,2),r})^2}{2 \cdot \frac{k_{PK_i}}{k_{PK_i} - 1} \cdot R_{\text{газ.ср}}(\alpha_{\text{ox}_{st(i,2)}}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})}$$

$$Cp_3 = Cp_{\text{газ}}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{\text{ox}_{st(i,3)}}, \text{Fuel})$$

$$k' = k_{\text{ад}}(Cp_3, R_{\text{газ}}(\alpha_{\text{ox}_{st(i,3)}}, \text{Fuel}))$$

if $|\text{eps}(\text{"rel"}, k_{st(i,3),r}, k')| \leq \text{epsilon}$

$$k_{st(i,3),r} = k'$$

break

$$k_{st(i,3)} = k'$$

$$v_{st(i,3),r} = \frac{R_{\text{газ}}(\alpha_{\text{ox}_{st(i,3)}}, \text{Fuel}) \cdot T_{st(i,3),r}}{P_{st(i,3),r}}$$

$$\beta_{st(i,3),r} = \text{asin}\left(\frac{G_{st(i,3)} \cdot v_{st(i,3),r}}{w_{st(i,3),r} \cdot F_{st(i,3)}}\right)$$

$$\begin{pmatrix} c_{u_{st(i,3),r}} \\ c_a \end{pmatrix} = \begin{pmatrix} w_{st(i,3),r} \cdot \cos(\beta_{st(i,3),r}) - u_{st(i,3),r} \\ w_{st(i,3),r} \cdot \sin(\beta_{st(i,3),r}) \end{pmatrix}$$

$$c_{st(i,3),r} = \sqrt{c_{u_{st(i,3),r}}^2 + c_{a_{st(i,3),r}}^2}$$

$$\begin{pmatrix} w_{u_{st(i,3),r}} \\ w_{a_{st(i,3),r}} \end{pmatrix} = \begin{bmatrix} \sqrt{w_{st(i,3),r}^2 - c_{a_{st(i,3),r}}^2} \\ w_{st(i,3),r} \sin(\beta_{st(i,3),r}) \end{bmatrix}$$

$$\alpha_{st(i,3),r} = \text{triangle}(c_{a_{st(i,3),r}}, c_{u_{st(i,3),r}})$$

$$T_{a_{st(i,3),r}}^* = T_{st(i,3),r} + \frac{(c_{st(i,3),r})^2}{2 \cdot Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel)}$$

$$P_{a_{st(i,3),r}}^* = P_{st(i,3),r} \cdot \left(\frac{T_{a_{st(i,3),r}}^*}{T_{st(i,3),r}} \right)^{\frac{k_{st(i,3),r}}{k_{st(i,3),r}-1}}$$

$$\begin{pmatrix} T_{cm_{st(i,3),r}}^* \\ P_{cm_{st(i,3),r}}^* \end{pmatrix} = \begin{bmatrix} T_{\text{смешение}}[P_{a_{st(i,3),r}}^*, T_{a_{st(i,3),r}}^*, G_{st(i,2)}, \alpha_{ox_{st(i,2)}} , P^*_{cooling}, T^*_{cooling}, (g_{ox_{\text{ЛПК}_i}} \cdot G_{st(i,2)}), \alpha_{ox_{st(i,3)}} , Fuel] \\ P_{\text{смешение}}[P_{a_{st(i,3),r}}^*, G_{st(i,2)}, P^*_{cooling}, (g_{ox_{\text{ЛПК}_i}} \cdot G_{st(i,2)})] \end{bmatrix}$$

$$\begin{pmatrix} T_{st(i,3),r}^* \\ P_{st(i,3),r}^* \end{pmatrix} = \begin{pmatrix} T_{cm_{st(i,3),r}}^* \\ P_{cm_{st(i,3),r}}^* \end{pmatrix}$$

$$T_{st(i,3),r} = T_{st(i,3),r}^* - \frac{(c_{st(i,3),r})^2}{2 \cdot Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel)}$$

$$P_{st(i,3),r} = P_{st(i,3),r}^* \cdot \left(\frac{T_{st(i,3),r}}{T_{st(i,3),r}^*} \right)^{\frac{k_{st(i,3),r}}{k_{st(i,3),r}-1}}$$

$$k_{st(i,3),r} = k_{a_{st(i,3),r}} \left(Cp_{\Gamma a3}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}} , Fuel), R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \right)$$

$$T_{w_{st(i,3),r}}^* = T_{st(i,3),r} + \frac{(w_{st(i,3),r})^2}{2 \cdot \frac{k_{st(i,3),r}}{k_{st(i,3),r}-1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel)}$$

$$\begin{pmatrix} a_{3B_{st(i,3),r}} \\ a_{c_{st(i,3),r}}^* \\ a_{w_{st(i,3),r}}^* \end{pmatrix} = \begin{pmatrix} \sqrt{k_{st(i,3),r} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{st(i,3),r}} \\ \sqrt{\frac{2 \cdot k_{st(i,3),r}}{k_{st(i,3),r}+1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{st(i,3),r}^*} \\ \sqrt{\frac{2 \cdot k_{st(i,3),r}}{k_{st(i,3),r}+1} \cdot R_{\Gamma a3}(\alpha_{ox_{st(i,3)}} , Fuel) \cdot T_{w_{st(i,3),r}}^*} \end{pmatrix}$$

$$\left(\lambda_{c_{st(i,3),r}} \right) = \left(\frac{c_{st(i,3),r}}{a_{c_{st(i,3),r}}^*} \right)$$

$$\begin{aligned}
& \left(\lambda_{w_{st(i,3),r}} \right) \quad \left(\frac{w_{st(i,3),r}}{a^*_{w_{st(i,3),r}}} \right) \\
& \left(\frac{M_{c_{st(i,3),r}}}{M_{w_{st(i,3),r}}} \right) = \frac{1}{a_{3B_{st(i,3),r}}} \cdot \left(c_{st(i,3),r} \right) \\
& v_{rotor_i} = v_{установка}(\beta_{st(i,2),r}, \beta_{st(i,3),r}) \\
& chord_{rotor_{i,r}} = \frac{B_{PK_i}}{\sin(v_{rotor_i})} \\
& \bar{t}_{оптPK_i} = \bar{t}_{опт} \left("PK", g_{охлPK_i} > 0, \beta_{st(i,2),r}, \beta_{st(i,3),r}, \max \left(submatrix(\bar{c}_{rotor}, i, i, 1, N_r) \right) \right) \\
& Z_{rotor_i} = \left| \begin{array}{l} Z_{rotor_i} = \text{ceil} \left(\frac{\pi \cdot \text{mean}(D_{st(i,2),r}, D_{st(i,3),r})}{\bar{t}_{оптPK_i} \cdot chord_{rotor_{i,r}}} \right) \\ \text{while } \gcd(Z_{rotor_i}, Z_{stator_i}) \neq 1 \\ \quad Z_{rotor_i} = Z_{rotor_i} + 1 \end{array} \right. \\
& \text{for } r \in 1..N_r \\
& \quad t_{rotor_{i,r}} = \frac{\pi \cdot \text{mean}(D_{st(i,2),r}, D_{st(i,3),r})}{Z_{rotor_i}} \\
& \quad \xi_{трPK_i} = \xi_{трение}(\beta_{st(i,2),r}, \beta_{st(i,3),r}) \\
& \quad \xi_{крPK_i} = \xi_{кромка} \left(\bar{r}_{outlet_{rotor_{i,r}}} \cdot chord_{rotor_{i,r}}, t_{rotor_{i,r}}, \beta_{st(i,3),r} \right) \\
& \quad \xi_{RePK_i} = \xi_{Re} \left(\frac{w_{st(i,3),r} \cdot chord_{rotor_{i,r}}}{\mu_{газ}(T_{st(i,3),r}, \alpha_{ox_{st(i,3)}}) \cdot v_{st(i,3),r}} \right) \\
& \quad \xi_{\lambda PK_i} = \xi_{сжимаемость}("PK", \lambda_{w_{st(i,3),r}}) \\
& \quad \xi_{прPK_i} = \xi_{трPK_i} + \xi_{крPK_i} + \xi_{RePK_i} + \xi_{\lambda PK_i} \\
& \quad \xi_{втPK_i} = \xi_{вторичные}(\xi_{трPK_i}, t_{rotor_{i,r}}, \beta_{st(i,3),r}, h_{st(i,3)}) \\
& \quad \xi_{ТДPK_i} = \frac{\xi_{ТД} \left("PK", T^*_{см_{st(i,3),r}}, T^*_{ад_{st(i,3),r}}, P_{st(i,3),r}, C_{p_{газ}}(P_{st(i,3),r}, T_{st(i,3),r}, \alpha_{ox_{st(i,3)}}^{Fuel}), R_{газ}(\alpha_{ox_{st(i,3)}}^{Fuel}), G_{st(i,3)}, F_{st(i,3)}, \beta_{st(i,3),r}, u_{st(i,3),r} \right)}{H_{rotor_i}} \\
& \quad \xi_{смPK_i} = \xi_{смешение}("PK", g_{охлPK_i}) \\
& \quad \text{if } \left| \text{eps} \left("rel", \sqrt{1 - \xi_{смPK_i} - \xi_{ТДPK_i} - \xi_{втPK_i} - \xi_{прPK_i}}, \bar{v}_{rotor_i} \right) \right| \leq \text{epsilon} \\
& \quad \quad \left| \bar{v}_{rotor_i} = \sqrt{1 - \xi_{смPK_i} - \xi_{ТДPK_i} - \xi_{втPK_i} - \xi_{прPK_i}} \right. \\
& \quad \quad \text{break}
\end{aligned}$$

$$\left| \overline{v}_{\text{rotor}_i} = \sqrt{1 - \xi_{\text{смпк}_i} - \xi_{\text{тдпк}_i} - \xi_{\text{втпк}_i} - \xi_{\text{ппк}_i}} \right.$$

$$\text{Lu}_{\text{сТ}_i} = c_{u_{\text{st}(i,2),r}} \cdot u_{\text{st}(i,2),r} + c_{u_{\text{st}(i,3),r}} \cdot u_{\text{st}(i,3),r}$$

$$\begin{pmatrix} \xi_{\text{CA}_i} \\ \xi_{\text{ПК}_i} \\ \xi_{\text{CAиПК}_i} \end{pmatrix} = \frac{1}{H_{\text{сТ}_i}} \cdot \begin{pmatrix} \xi_{\text{Л}}(\overline{v}_{\text{stator}_i}, c_{\text{st}(i,2),r}) \\ \xi_{\text{Л}}(\overline{v}_{\text{rotor}_i}, w_{\text{st}(i,3),r}) \\ \xi_{\text{Л}}(\overline{v}_{\text{stator}_i}, c_{\text{st}(i,2),r}) \cdot \frac{T_{\text{ад}_{\text{st}(i,3),r}}}{T_{\text{st}(i,2),r}} \end{pmatrix}$$

$$\xi_{\text{ВЫХ}_i} = \frac{\xi_{\text{ВЫХОД}}(c_{\text{st}(i,3),r})}{H_{\text{сТ}_i}}$$

$$\xi_{\Delta r_i} = \frac{\xi_{\text{г.зазор}}(\Delta_{r_i}, h_{\text{st}(i,3)}, D_{\text{st}(i,3),r}, R_{L_{i,r}}, \text{Lu}_{\text{сТ}_i})}{H_{\text{сТ}_i}}$$

$$\xi_{\text{тр.в}_i} = \frac{\xi_{\text{трениеИвентиляция}} \left[D_{\text{st}(i,3),r}, h_{\text{st}(i,3)}, u_{\text{st}(i,3),r}, \left(\frac{v_{\text{st}(i,2),r} + v_{\text{st}(i,3),r}}{2 \cdot v_{\text{st}(i,2),r} \cdot v_{\text{st}(i,3),r}} \right), \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right]}{H_{\text{сТ}_i}}$$

$$\eta_{u1_i} = \frac{\text{Lu}_{\text{сТ}_i}}{H_{\text{сТ}_i}}$$

$$\eta_{\text{лоп}_i} = 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\Delta r_i} - \xi_{\text{тр.в}_i}$$

$$\eta_{u2_i} = 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\text{ВЫХ}_i}$$

$$\eta_{\text{мощь}_i} = 1 - \xi_{\text{CAиПК}_i} - \xi_{\text{ПК}_i} - \xi_{\text{ВЫХ}_i} - \xi_{\Delta r_i} - \xi_{\text{тр.в}_i}$$

$$L_{\text{сТ}_i} = H_{\text{сТ}_i} \cdot \eta_{\text{мощь}_i}$$

$$\text{trace} \left(\text{concat} \left(\text{"eps(N) = "}, \text{num2str} \left(\text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right) \right) \right)$$

$$\text{break if } \left(\left| \text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right| \leq \text{epsilon} \right) \wedge \left(\text{iteration}_{\text{сТ}_i} = 0 \right)$$

$$\text{iteration}_{\text{сТ}_i} = -1 \text{ if } \left| \text{eps} \left(\text{"rel"}, N_{\text{сТ}_i}, L_{\text{сТ}_i} \cdot \text{mean}(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}) \right) \right| \leq \text{epsilon}$$

$$\text{Lu}_{\text{нагрузка}_i} = \frac{\text{Lu}_{\text{сТ}_i}}{\left(\text{mean}(u_{\text{st}(i,2),r}, u_{\text{st}(i,3),r}) \right)^2}$$

$$\begin{pmatrix} \pi^*_{\text{сТ}_i} \\ \pi_{\text{сТ}_i} \end{pmatrix} = P^*_{\text{st}(i,1),r} \begin{bmatrix} (P^*_{\text{st}(i,3),r})^{-1} \\ (P_{\text{st}(i,3),r})^{-1} \end{bmatrix}$$

$$k_{\text{ср}} = k_{\text{ад}} \left(C_{\text{гaз.ср}} \left(P_{\text{st}(i,1),r}, P_{\text{st}(i,3),r}, T_{\text{st}(i,1),r}, T_{\text{st}(i,3),r}, \alpha_{\text{ox}_{\text{st}(i,1)}}^{\cdot}, \alpha_{\text{ox}_{\text{st}(i,3)}}^{\cdot}, \text{Fuel} \right), R_{\text{гaз.ср}} \left(\alpha_{\text{ox}_{\text{st}(i,1)}}^{\cdot}, \alpha_{\text{ox}_{\text{st}(i,3)}}^{\cdot}, \text{Fuel} \right) \right) \left[\frac{\quad}{1 - k_{\text{ср}}} \right]$$

$$\left| \begin{array}{l} H^*_{cT_i} = C_{p_{\Gamma a3, cp}} \left(P_{st(i, 1), r}, P_{st(i, 3), r}, T_{st(i, 1), r}, T_{st(i, 3), r}, \alpha_{ox_{st(i, 1)}}, \alpha_{ox_{st(i, 3)}} , Fuel \right) \cdot T^*_{st(i, 1), r} \cdot \left[1 - \left(\pi^*_{cT_i} \right)^{\overline{k_{cp}}} \right] \\ \eta^*_{cT_i} = \frac{L_{cT_i}}{H^*_{cT_i}} \end{array} \right|$$

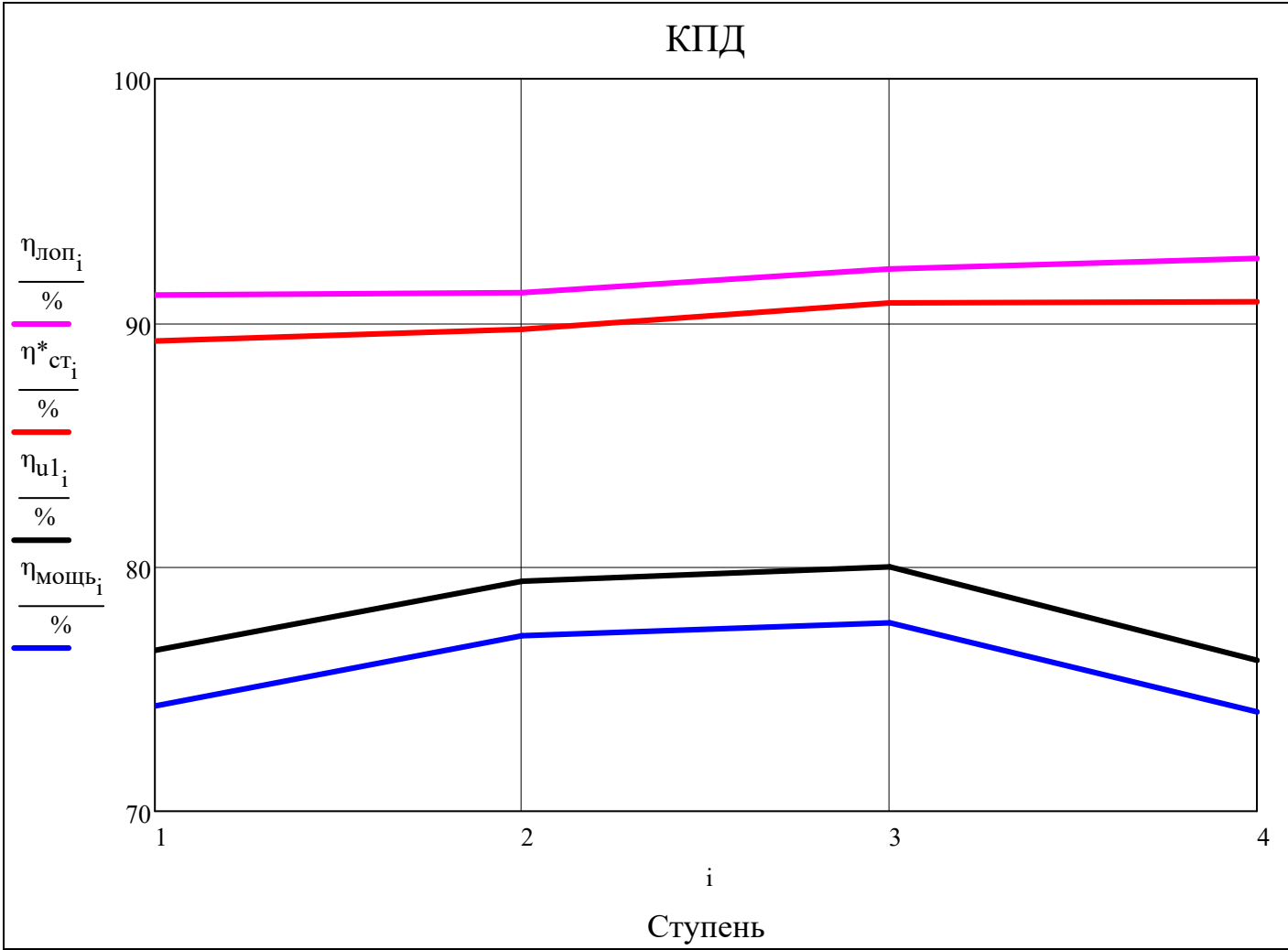
for i ∈ 1 .. Z

for j ∈ 1 .. 3

$$\left| \begin{array}{l} \rho^*_{st(i, j), r} = \frac{P^*_{st(i, j), r}}{R_{\Gamma a3} \left(\alpha_{ox_{st(i, j)}} , Fuel \right) \cdot T^*_{st(i, j), r}} \\ \rho_{st(i, j), r} = \left(v_{st(i, j), r} \right)^{-1} \\ \left(\begin{array}{l} \varepsilon_{stator_{i, av(N_r)}} \\ \varepsilon_{rotor_{i, av(N_r)}} \end{array} \right) = \left(\begin{array}{l} \alpha_{st(i, 2), av(N_r)} - \alpha_{st(i, 1), av(N_r)} \\ \beta_{st(i, 3), av(N_r)} - \beta_{st(i, 2), av(N_r)} \end{array} \right) \end{array} \right|$$

| iteration _{CA} | iteration _{PK} |
|------------------------------|-----------------------------|
| k | R _L |
| H [*] _{cT} | H _{cT} |
| H _{stator} | H _{rotor} |
| c _{ад} | w _{ад} |
| P [*] | P |
| T [*] | T |
| G | v |
| ρ [*] | ρ |
| α _{ox} | α _{ox} |
| α | β |
| ε _{stator} | ε _{rotor} |
| θ _{CA} | θ _{PK} |
| g _{охлCA} | g _{охлPK} |
| a [*] _c | a [*] _w |
| T _{ад} | T _{ад} |
| P [*] _w | T [*] _w |
| a _{3B} | a _{3B} |
| u | u |
| c | c |
| c _a | c _u |

| | | |
|--|--------------------------------|-------------------------------|
| | w | w |
| | w_a | w_u |
| | λ_c | M_c |
| | λ_w | M_w |
| | v_{stator} | v_{rotor} |
| | $\text{chord}_{\text{stator}}$ | $\text{chord}_{\text{rotor}}$ |
| | $\overline{t}_{\text{оптCA}}$ | $\overline{t}_{\text{оптPK}}$ |
| | t_{stator} | t_{rotor} |
| | Z_{stator} | Z_{rotor} |
| | $\overline{v}_{\text{stator}}$ | $\overline{v}_{\text{rotor}}$ |
| | $\xi_{\text{трCA}}$ | $\xi_{\text{трPK}}$ |
| | $\xi_{\text{крCA}}$ | $\xi_{\text{крPK}}$ |
| | $\xi_{\text{РеCA}}$ | $\xi_{\text{РеPK}}$ |
| | $\xi_{\lambda\text{CA}}$ | $\xi_{\lambda\text{PK}}$ |
| | $\xi_{\text{прCA}}$ | $\xi_{\text{прPK}}$ |
| | $\xi_{\text{вТCA}}$ | $\xi_{\text{вТПK}}$ |
| | $\xi_{\text{ТДCA}}$ | $\xi_{\text{ТДPK}}$ |
| | $\xi_{\text{смCA}}$ | $\xi_{\text{смPK}}$ |
| | $\xi_{\Delta\Gamma}$ | $\xi_{\text{ВЫХ}}$ |
| | $\xi_{\text{тр.в}}$ | $\xi_{\text{тр.в}}$ |
| | $L_{\text{СТ}}$ | $L_u_{\text{СТ}}$ |
| | $\eta_{\text{МОЩЬ}}$ | $\eta_{\text{ЛОП}}$ |
| | $\eta^*_{\text{СТ}}$ | $\eta^*_{\text{СТ}}$ |
| | η_{u1} | η_{u2} |
| | ξ_{CA} | ξ_{PK} |
| | $L_{u_{\text{нагрузка}}}$ | $L_{u_{\text{нагрузка}}}$ |



$\eta_{\text{лoп}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 91.14 | 91.24 | 92.21 | 92.64 |

·%

$\eta^*_{\text{cт}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 89.26 | 89.74 | 90.83 | 90.86 |

·%

$\text{stack}\left(\eta_{u1}^T, \eta_{u2}^T\right) =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 76.58 | 79.42 | 80.00 | 76.17 |
| 2 | 76.26 | 79.19 | 79.84 | 75.97 |

·%

$\eta_{\text{мoщb}}^T =$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 74.31 | 77.19 | 77.72 | 74.06 |

·%

$\eta_{\text{мoщb}_i} \leq \eta_{u1_i} \leq \eta^*_{\text{cт}_i} \leq \eta_{\text{лoп}_i} =$

| |
|---|
| 1 |
| 1 |
| 1 |
| 1 |

Степень понижения полного давления Т:
Степень понижения давления Т:

$$\left(\pi^*_{\text{T}}\right) = P^*_{\text{st}(1,1),\text{av}\left(N_{\text{r}}\right)} \cdot \left[\frac{\left(P^*_{\text{st}(Z,3),\text{av}\left(N_{\text{r}}\right)}\right)^{-1}}{\left(P_{\text{st}(Z,3),\text{av}\left(N_{\text{r}}\right)}\right)^{-1}}\right] =$$

| | |
|---|------|
| | 1 |
| 1 | 4.05 |
| 2 | 4.44 |

Теплоперепад по параметрам торможения (Дж/кг):
Располагаемый теплоперепад (Дж/кг):

$$\left(\begin{matrix} H^*_{\text{T}} \\ H_{\text{T}} \end{matrix}\right) = \left(\begin{matrix} \sum\limits_{i=1}^Z H^*_{\text{сТ}_i} \\ \sum\limits_{i=1}^Z H_{\text{сТ}_i} \end{matrix}\right) =$$

| | |
|---|-------|
| | 1 |
| 1 | 475.6 |
| 2 | 565.8 |

$\cdot 10^3$

Мощность Т (Вт):

$$\sum\limits_{i=1}^Z N_{\text{сТ}_i} = 15.18 \cdot 10^6$$

$$\text{eps}\left(\text{"rel"}, N_{\text{T}}, \sum\limits_{i=1}^Z N_{\text{сТ}_i}\right) = 0.000\cdot\%$$

Удельная поступенчатая работа Т [Дж/кг]:

$$L_{\text{T}} = \sum\limits_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} = 428.9 \cdot 10^3$$

Лопаточный КПД Т:

$$\eta_{\text{Тлоп}} = \frac{\sum\limits_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)} + \frac{\left(c_{\text{st}(Z,3),\text{av}\left(N_{\text{r}}\right)}\right)^2}{2}}{H_{\text{T}}} = 80.55\cdot\%$$

$$k_{\text{T.ср}} = k_{\text{ад}}\left(\text{Cp}_{\text{Газ.ср}}\left(P_{\text{st}(1,1),\text{av}\left(N_{\text{r}}\right)}, P_{\text{st}(Z,3),\text{av}\left(N_{\text{r}}\right)}, T_{\text{st}(1,1),\text{av}\left(N_{\text{r}}\right)}, T_{\text{st}(Z,3),\text{av}\left(N_{\text{r}}\right)}, \alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right), R_{\text{Газ.ср}}\left(\alpha_{\text{ox}_{\text{st}(1,1)}}, \alpha_{\text{ox}_{\text{st}(Z,3)}}, \text{Fuel}\right)\right) = 1.308$$

Адиабатный КПД Т:

$$\eta^*_{\text{T}} = \frac{L_{\text{T}}}{H^*_{\text{T}}} = 90.18\cdot\%$$

Полиτροπический КПД Т:

$$\eta^*_{\text{T.п}} = \eta^*_{\text{n}}\left(\text{"расширение"}, \eta^*_{\text{T}}, \pi^*_{\text{T}}, k_{\text{T.ср}}\right) = 88.59\cdot\%$$

Мощностной КПД Т:

$$\eta_{\text{Тмощь}} = \frac{\sum\limits_{i=1}^Z \frac{N_{\text{сТ}_i}}{\text{mean}\left(G_{\text{st}(i,2)}, G_{\text{st}(i,3)}\right)}}{H_{\text{T}}} = 75.80\cdot\%$$

$$L_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 107.1 & 107.2 & 107.2 & 107.2 \\ \hline \end{array} \cdot 10^3$$

$$N_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.8 & 3.8 & 3.8 & 3.8 \\ \hline \end{array} \cdot 10^6$$

$$Lu_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 110.4 & 110.3 & 110.4 & 110.3 \\ \hline \end{array} \cdot 10^3$$

$$Lu_{нагрузка}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 3.0 & 2.3 & 1.8 & 1.6 \\ \hline \end{array}$$

$$H_{ct}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 144.2 & 138.9 & 138.0 & 144.8 \\ \hline \end{array} \cdot 10^3$$

$$stack\left(H_{stator}^T,H_{rotor}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 125.4 & 118.1 & 113.1 & 118.0 \\ \hline 2 & 18.8 & 20.9 & 24.9 & 26.9 \\ \hline \end{array} \cdot 10^3$$

$$submatrix\left(R_L^T,av\left(N_r\right),av\left(N_r\right),1,Z\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.1 & 0.2 & 0.2 & 0.2 \\ \hline \end{array}$$

$$G^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 & 35.394 \\ \hline \end{array}$$

$$\alpha_{ox}^T = \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 & 2.493 \\ \hline \end{array}$$

$$stack\left(\theta_{CA}^T,\theta_{PK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -0.005 & -0.112 & -0.246 & -0.420 \\ \hline 2 & -0.066 & -0.192 & -0.354 & -0.568 \\ \hline \end{array}$$

$$stack\left(g_{oxлCA}^T,g_{oxлPK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & 0.00 & 0.00 & 0.00 \\ \hline 2 & 0.00 & 0.00 & 0.00 & 0.00 \\ \hline \end{array} \cdot 10^{-3}$$

$$G_{oxлCA_i} = g_{oxлCA_i} \cdot G_{st(i,1)}$$

$$G_{oxлPK_i} = g_{oxлPK_i} \cdot G_{st(i,2)}$$

$$stack\left(G_{oxлCA}^T,G_{oxлPK}^T\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.0 & 0.0 & 0.0 & 0.0 \\ \hline 2 & 0.0 & 0.0 & 0.0 & 0.0 \\ \hline \end{array}$$

$$G_{cooling} = 0.8$$

$$\sum_{i=1}^Z G_{oxлCA_i} + \sum_{i=1}^Z G_{oxлCA_i} \leq G_{cooling} = 1$$

$$\text{stack}\Big(\text{iteration}_{\text{CA}}^{\text{T}},\text{iteration}_{\text{PK}}^{\text{T}}\Big)=\begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 2 & 2 & 2 & 2 \\ \hline 2 & 2 & 2 & 2 & 2 \end{array}$$

$$\text{submatrix}\Big(\text{k}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1.298 & 1.302 & 1.303 & 1.306 & 1.307 & 1.312 & 1.313 & 1.319 & 1.320 \end{array}$$

$$\text{submatrix}\Big(\text{P}^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 927.5 & 915.4 & 676.8 & 666.5 & 483.6 & 476.7 & 338.0 & 332.9 & 229.2 \end{array}\cdot 10^3$$

$$\text{submatrix}\Big(\text{P}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 890.0 & 666.9 & 633.4 & 485.6 & 456.7 & 343.4 & 317.3 & 229.2 & 208.8 \end{array}\cdot 10^3$$

$$\text{submatrix}\Big(\text{T}^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1368.9 & 1369.9 & 1281.1 & 1282.0 & 1192.3 & 1193.3 & 1102.4 & 1103.7 & 1011.4 \end{array}$$

$$\text{submatrix}\Big(\text{T}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1356.0 & 1272.9 & 1261.6 & 1190.2 & 1176.4 & 1103.8 & 1085.9 & 1008.5 & 988.8 \end{array}$$

$$\text{submatrix}\Big(\text{T}^{*\text{wT}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 1316.2 & 1317.8 & 1225.7 & 1228.4 & 1134.0 & 1136.6 & 1041.5 & 1042.0 \end{array}$$

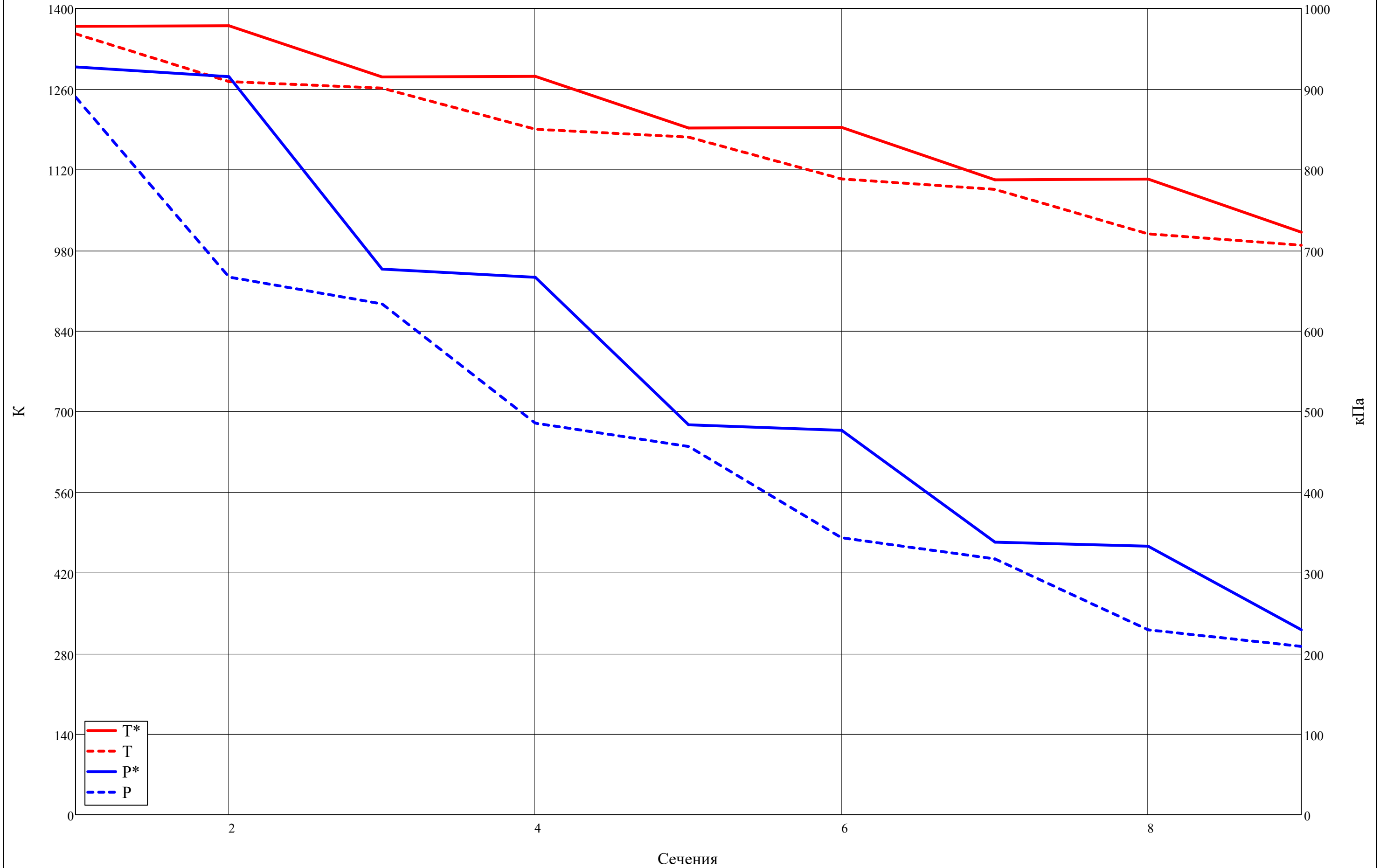
$$\text{submatrix}\Big(\text{T}_{\text{a}\mathcal{A}}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.0 & 1269.1 & 1257.7 & 1186.0 & 1173.2 & 1100.2 & 1083.3 & 1004.9 & 986.0 \end{array}$$

$$\text{submatrix}\Big(\text{v}^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 0.440 & 0.551 & 0.575 & 0.707 & 0.743 & 0.927 & 0.987 & 1.269 & 1.366 \end{array}$$

$$\text{submatrix}\Big(\rho^{*\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.349 & 2.316 & 1.831 & 1.802 & 1.406 & 1.385 & 1.063 & 1.046 & 0.785 \end{array}$$

$$\text{submatrix}\Big(\rho^{\text{T}},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big),1,2\text{Z}+1\Big)=\begin{array}{c|c|c|c|c|c|c|c|c|c} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 2.275 & 1.816 & 1.741 & 1.414 & 1.346 & 1.078 & 1.013 & 0.788 & 0.732 \end{array}$$

Термодинамические параметры по тракту Т на ср. сечении



submatrix $\left(\mathbf{a}_{3B}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 712.6 | 691.4 | 688.5 | 669.8 | 666.1 | 646.3 | 641.3 | 619.4 | 613.7 |

submatrix $\left(\mathbf{a}_{\mathbf{c}}^{*\text{T}}, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 667.9 | 668.6 | 646.6 | 647.3 | 624.3 | 625.0 | 600.9 | 601.8 | 576.2 |

submatrix $\left(\mathbf{a}_{\mathbf{w}}^{*\text{T}}, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 655.4 | 655.8 | 632.9 | 633.7 | 609.3 | 610.1 | 584.6 | 584.9 |

submatrix $\left(\mathbf{c}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 180.0 | 491.2 | 220.3 | 475.1 | 197.6 | 466.2 | 200.0 | 476.7 | 231.9 |

submatrix $\left(\mathbf{c}_{\mathbf{u}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-------|-------|-------|------|-------|------|-------|------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 452.3 | 135.3 | 435.8 | 85.3 | 420.3 | 38.7 | 416.3 | 10.0 |

submatrix $\left(\mathbf{c}_{\mathbf{a}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 180.0 | 191.6 | 173.8 | 189.2 | 178.3 | 201.6 | 196.2 | 232.3 | 231.7 |

submatrix $\left(\mathbf{w}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 328.4 | 373.6 | 295.2 | 357.3 | 270.8 | 350.4 | 280.7 | 355.8 |

submatrix $\left(\mathbf{w}_{\mathbf{u}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 266.7 | 330.7 | 226.5 | 309.6 | 180.9 | 290.3 | 157.7 | 270.0 |

submatrix $\left(\mathbf{w}_{\mathbf{a}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 191.6 | 173.8 | 189.2 | 178.3 | 201.6 | 196.2 | 232.3 | 231.7 |

submatrix $\left(\mathbf{c}_{\mathbf{aD}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z\right) =$

| | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| 1 | 537.0 | 500.9 | 527.1 | 485.9 | 525.3 | 475.7 | 538.1 | 485.8 |

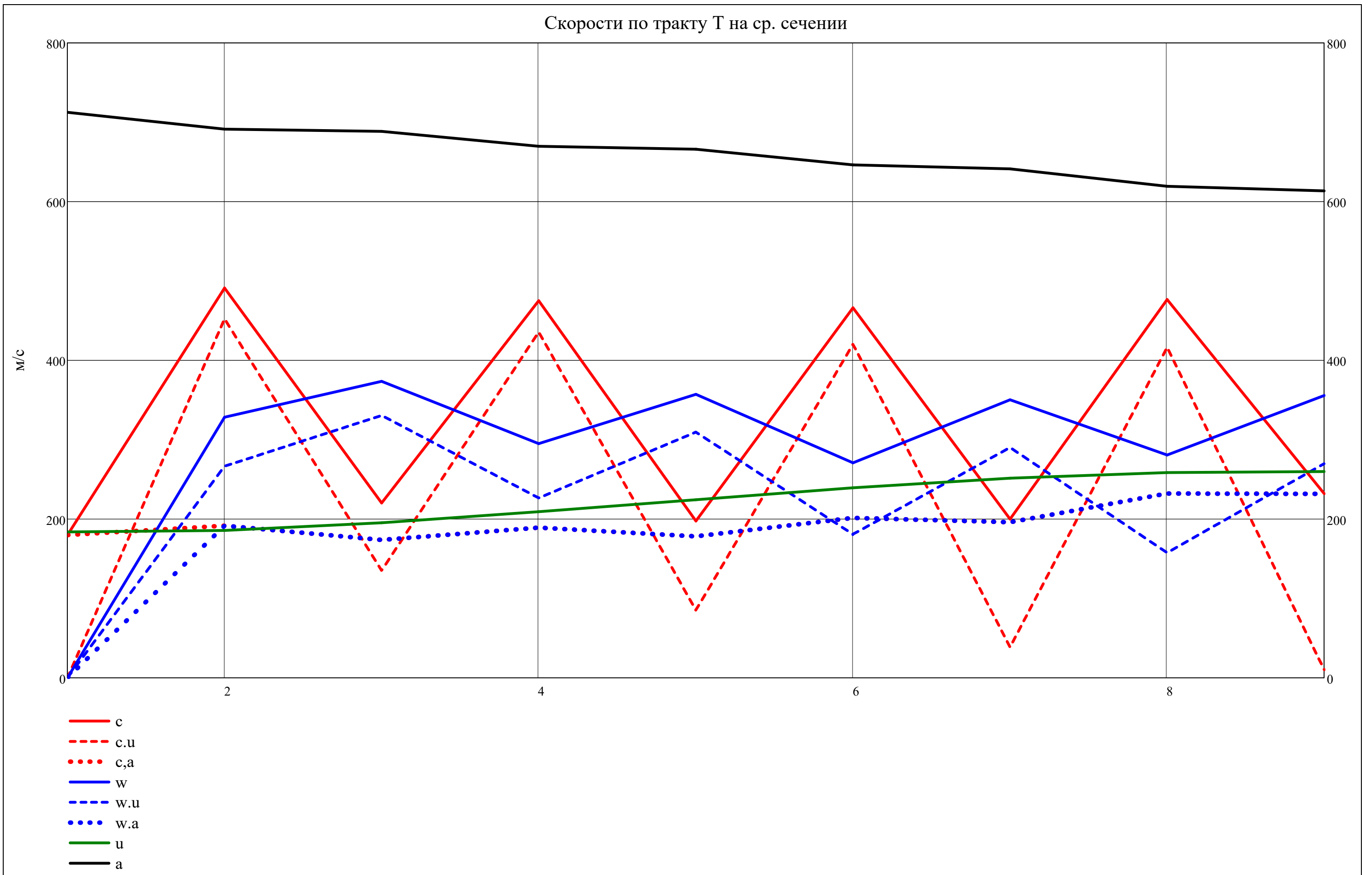
submatrix $\left(\mathbf{w}_{\mathbf{aD}}^T, \text{av}\left(\mathbf{N}_r\right), \text{av}\left(\mathbf{N}_r\right), 1, 2Z + 1\right) =$

| | | | | | | | | | |
|---|-----|-----|-------|-----|-------|-----|-------|-----|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0 | 0.0 | 386.2 | 0.0 | 368.1 | 0.0 | 359.4 | 0.0 | 365.1 |

$\mathbf{u}^T =$

| | | | | | | | | | |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 172.2 | 172.2 | 180.7 | 193.8 | 208.2 | 222.8 | 234.2 | 240.3 | 240.3 |
| 2 | 183.8 | 185.7 | 195.4 | 209.3 | 224.4 | 239.4 | 251.6 | 258.7 | 260.0 |
| 3 | 195.3 | 199.1 | 210.0 | 224.7 | 240.5 | 256.1 | 268.9 | 277.0 | 279.7 |

Скорости по тракту Т на ср. сечении



$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 90.00 & 22.96 & 52.10 & 23.47 & 64.44 & 25.62 & 78.83 & 29.16 & 87.53 \\ \hline \end{array} \text{.}^{\circ}$$

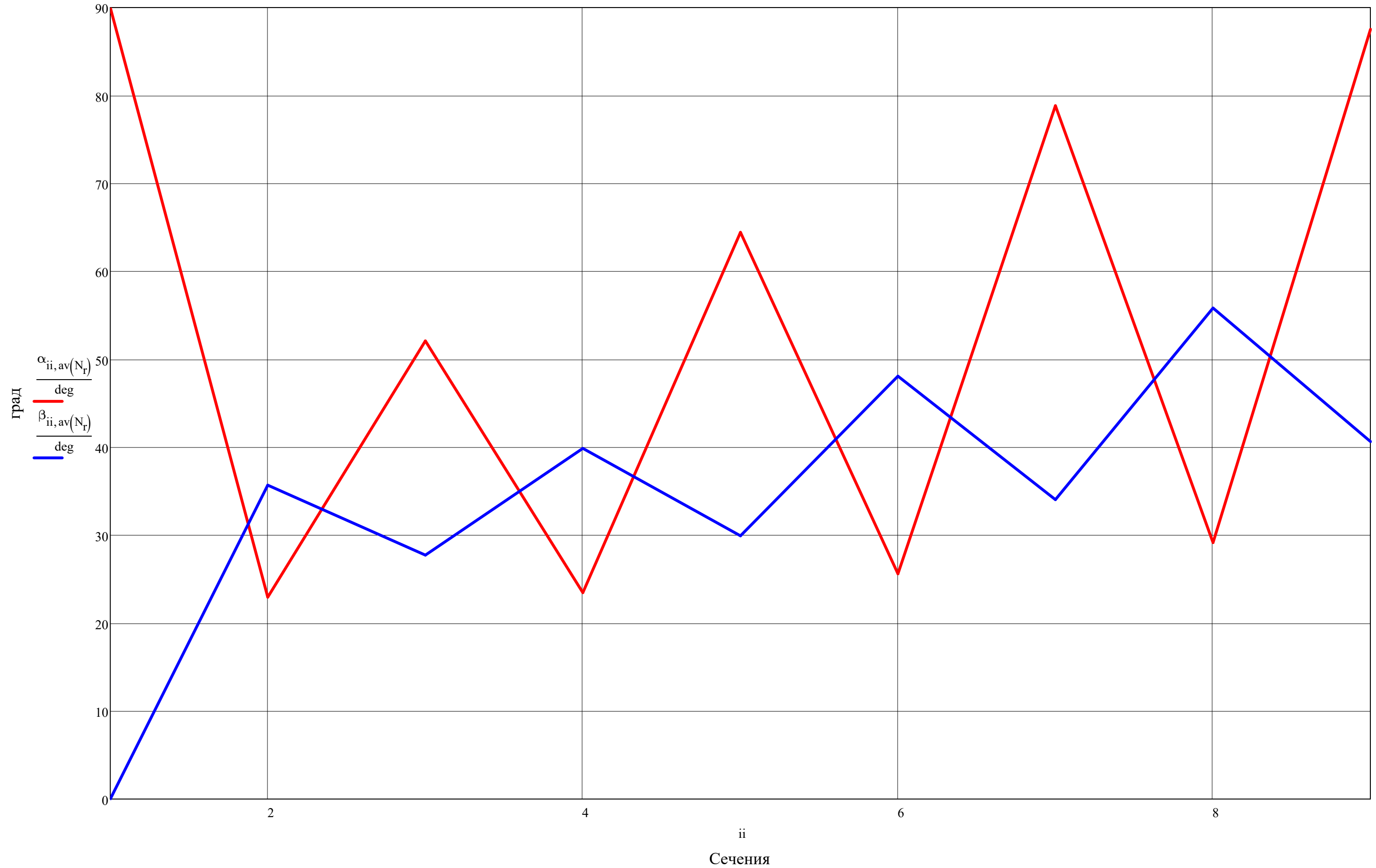
$$\text{submatrix}\Big(\alpha,1,2\cdot Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}\geq 11\text{.}^{\circ}=\begin{array}{|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \hline 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\text{submatrix}\Big(\beta,1,2\cdot Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \hline 1 & 0.00 & 35.70 & 27.73 & 39.87 & 29.93 & 48.09 & 34.05 & 55.83 & 40.64 & & & \\ \hline \end{array} \text{.}^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{stator}},1,Z,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -67.04 & -28.63 & -38.82 & -49.68 & & \\ \hline \end{array} \text{.}^{\circ}$$

$$\text{submatrix}\Big(\varepsilon_{\text{rotor}},1,Z,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}}= \begin{array}{|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline 1 & -7.97 & -9.94 & -14.04 & -15.19 & & \\ \hline \end{array} \text{.}^{\circ}$$

Углы по тракту Т на ср. сечении



submatrix $\left(\lambda_{\text{c}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}=$

| | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.2695 | 0.7348 | 0.3407 | 0.7340 | 0.3165 | 0.7458 | 0.3328 | 0.7922 | 0.4025 |

submatrix $\left(\lambda_{\text{w}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}=$

| | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0000 | 0.5011 | 0.5697 | 0.4664 | 0.5638 | 0.4445 | 0.5742 | 0.4802 | 0.6084 |

submatrix $\left(M_{\text{c}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}=$

| | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.2526 | 0.7105 | 0.3200 | 0.7093 | 0.2967 | 0.7213 | 0.3118 | 0.7697 | 0.3780 |

submatrix $\left(M_{\text{c}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}\leq 1=$

| | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

submatrix $\left(M_{\text{w}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}=$

| | | | | | | | | | |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 0.0000 | 0.4749 | 0.5426 | 0.4407 | 0.5364 | 0.4191 | 0.5463 | 0.4533 | 0.5798 |

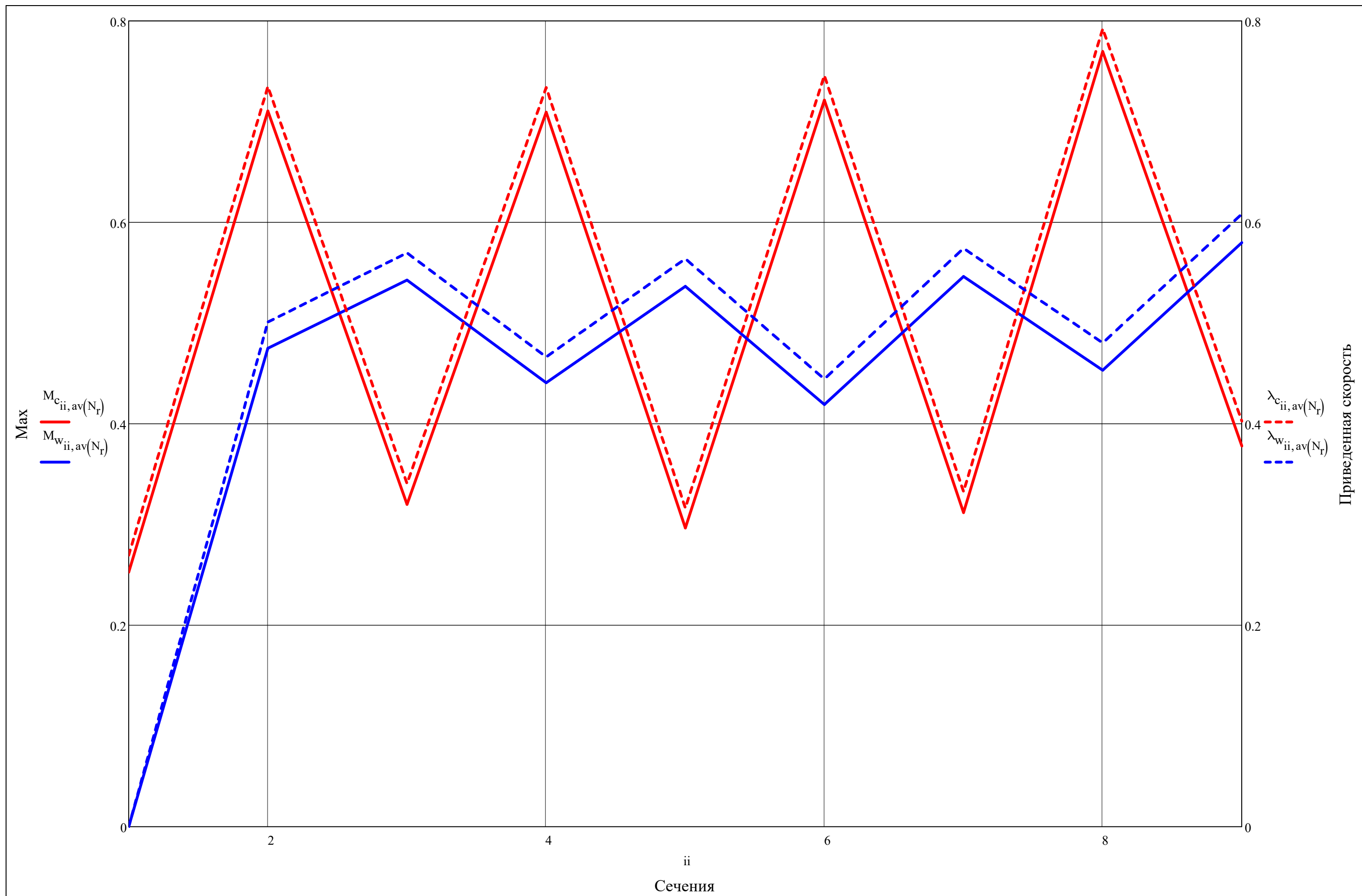
submatrix $\left(M_{\text{w}},1,2Z+1,\text{av}\left(N_{\text{r}}\right),\text{av}\left(N_{\text{r}}\right)\right)^{\text{T}}\leq 1=$

| | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

stack $\left(v_{\text{stator}}^{\text{T}},v_{\text{rotor}}^{\text{T}}\right)=$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 43.06 | 63.00 | 58.89 | 53.57 |
| 2 | 68.73 | 68.33 | 67.41 | 67.12 |

°.



$$\mathbf{t}_{\text{stator}}^T = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 40.6 & 27.9 & 35.9 & 43.3 \\ 2 & 43.6 & 30.1 & 38.6 & 46.6 \\ 3 & 46.5 & 32.4 & 41.3 & 49.8 \end{bmatrix} \cdot 10^{-3} \quad \mathbf{t}_{\text{rotor}}^T = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 19.8 & 23.5 & 28.4 & 30.6 \\ 2 & 21.4 & 25.3 & 30.5 & 33.0 \\ 3 & 22.9 & 27.1 & 32.7 & 35.4 \end{bmatrix} \cdot 10^{-3}$$

$$\text{submatrix}\left(\text{chord}_{\text{stator}}^T, \text{av}(\mathbf{N}_r), \text{av}(\mathbf{N}_r), 1, Z\right) = \begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 58.7 & 50.6 & 60.4 & 69.4 \end{array} \cdot 10^{-3}$$

$$\text{submatrix}\left(\text{chord}_{\text{rotor}}^T, \text{av}(N_r), \text{av}(N_r), 1, Z\right) = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 34.3 & 39.5 & 44.6 & 46.2 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{stack}\left(\mathbf{Z}_{\text{stator}}^{\text{T}}, \mathbf{Z}_{\text{rotor}}^{\text{T}}\right) = \begin{array}{c|cccc} & 1 & 2 & 3 & 4 \\ \hline 1 & 48 & 76 & 68 & 62 \\ \hline 2 & 101 & 97 & 91 & 89 \\ \hline \end{array}$$

| | | | | | |
|---|---|-------|-------|-------|-------|
| $\text{stack}\left(\tau_{\text{OITCA}}^T, \tau_{\text{OITPK}}^T\right) =$ | | 1 | 2 | 3 | 4 |
| | 1 | 0.762 | 0.603 | 0.645 | 0.686 |
| | 2 | 0.643 | 0.661 | 0.695 | 0.722 |

$$\frac{t_{\text{stator}_{i, \text{av}}(N_r)}}{\text{chord}_{\text{stator}_{i, \text{av}}(N_r)}} = 0.7 \leq \frac{t_{\text{stator}_{i, \text{av}}(N_r)}}{\text{chord}_{\text{stator}_{i, \text{av}}(N_r)}} \leq 1 = \frac{t_{\text{rotor}_{i, \text{av}}(N_r)}}{\text{chord}_{\text{rotor}_{i, \text{av}}(N_r)}} = 0.7 \leq \frac{t_{\text{rotor}_{i, \text{av}}(N_r)}}{\text{chord}_{\text{rotor}_{i, \text{av}}(N_r)}} \leq 1 =$$

| |
|-------|
| 0.743 |
| 0.595 |
| 0.639 |
| 0.671 |

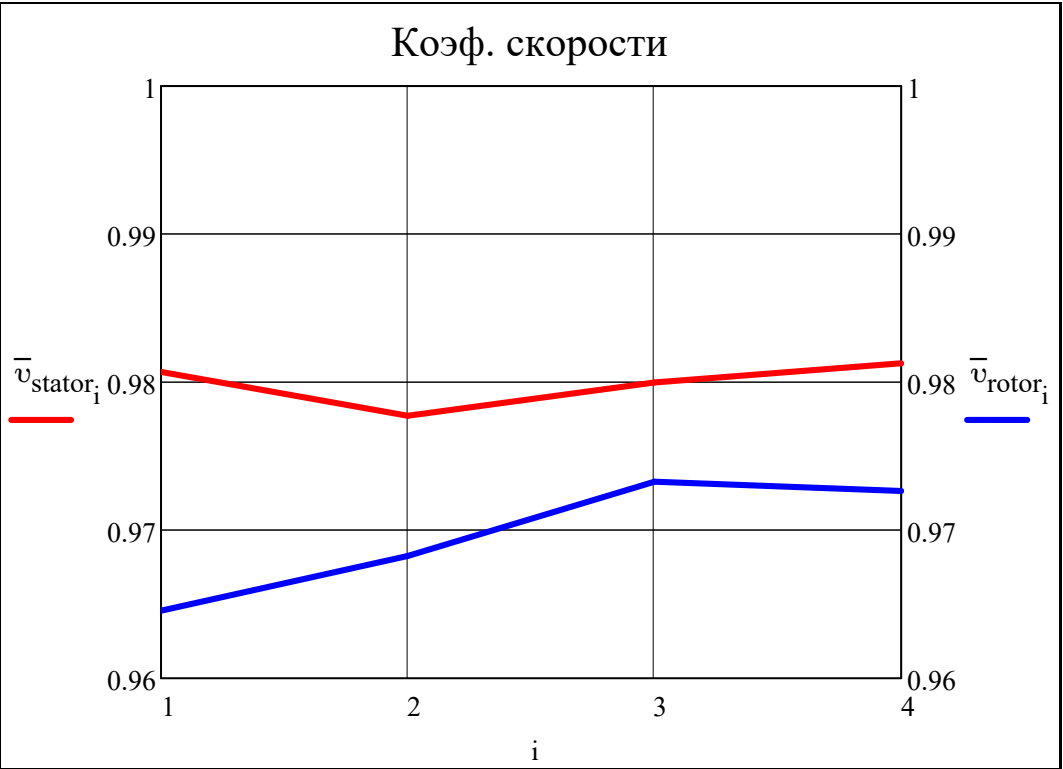
| |
|---|
| 1 |
| 0 |
| 0 |
| 0 |

| |
|-------|
| 0.622 |
| 0.640 |
| 0.684 |
| 0.714 |

| |
|---|
| 0 |
| 0 |
| 0 |
| 1 |

$$\text{stack}\left(\overline{v}_{\text{stator}}^T, \overline{v}_{\text{rotor}}^T\right) =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 0.9807 | 0.9777 | 0.9800 | 0.9813 |
| 2 | 0.9646 | 0.9683 | 0.9733 | 0.9727 |



$$\text{stack}\left(\xi_{\text{TpCA}}^{\text{T}}, \xi_{\text{TpPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 1.396 | 1.811 | 1.520 | 1.394 |
| 2 | 3.932 | 3.289 | 2.480 | 2.497 |

·%

$$\text{stack}\left(\xi_{\text{крCA}}^{\text{T}}, \xi_{\text{крPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 1.243 | 1.519 | 1.302 | 1.101 |
| 2 | 0.933 | 0.846 | 0.705 | |

·%

$$\text{stack}\left(\xi_{\text{ReCA}}^{\text{T}}, \xi_{\text{RePK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|--------|-------|-------|-------|
| 1 | -0.014 | 0.078 | 0.097 | 0.126 |
| 2 | 0.246 | 0.301 | 0.371 | 0.507 |

·%

$$\text{stack}\left(\xi_{\text{ппCA}}^{\text{T}}, \xi_{\text{ппPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 2.842 | 3.626 | 3.119 | 2.754 |
| 2 | 5.483 | 4.819 | 3.917 | 3.881 |

·%

$$\text{stack}\left(\xi_{\lambda\text{CA}}^{\text{T}}, \xi_{\lambda\text{PK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 0.217 | 0.219 | 0.201 | 0.134 |
| 2 | 0.371 | 0.382 | 0.362 | 0.297 |

·%

$$\text{stack}\left(\xi_{\text{BTCA}}^{\text{T}}, \xi_{\text{BTPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 0.980 | 0.778 | 0.845 | 0.958 |
| 2 | 1.477 | 1.430 | 1.356 | 1.513 |

·%

$$\text{stack}\left(\xi_{\text{ТДCA}}^{\text{T}}, \xi_{\text{ТДPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 0.000 | 0.000 | 0.000 | 0.000 |
| 2 | 0.000 | 0.000 | 0.000 | 0.000 |

·%

$$\text{stack}\left(\xi_{\text{смCA}}^{\text{T}}, \xi_{\text{смPK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 0.000 | 0.000 | 0.000 | 0.000 |
| 2 | 0.000 | 0.000 | 0.000 | 0.000 |

·%

$$\text{stack}\left(\xi_{\text{CA}}^{\text{T}}, \xi_{\text{PK}}^{\text{T}}\right) =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 3.326 | 3.743 | 3.250 | 3.026 |
| 2 | 3.621 | 3.062 | 2.476 | 2.493 |

·%

$$\xi_{\text{ВЫХ}}^{\text{T}} =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 16.829 | 14.054 | 14.491 | 18.579 |

·%

$$\xi_{\Delta\text{r}}^{\text{T}} =$$

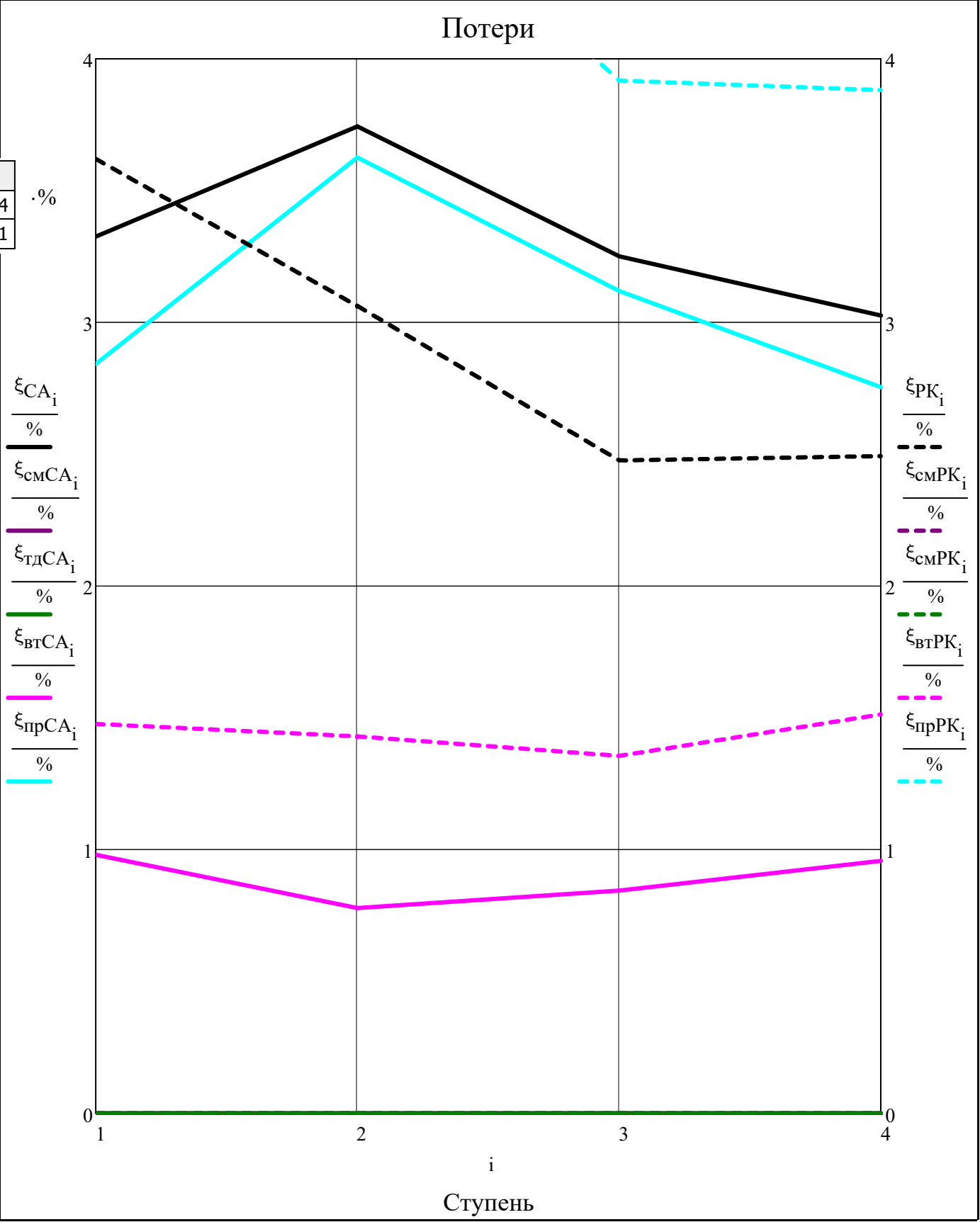
| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 1.813 | 1.786 | 1.826 | 1.662 |

·%

$$\xi_{\text{тр.в}}^{\text{T}} =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 0.138 | 0.222 | 0.300 | 0.245 |

·%



$$\overline{m} = \begin{pmatrix} \overline{v}_{\text{stator}_1} \cdot \cos\left(\alpha_{\text{st}(1,2), \text{av}(N_r)}\right)^2 \text{ if } Z = 1 \\ -0.5 \text{ otherwise} \\ -0.25 \\ 0 \\ 0.25 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} \text{"}\alpha.2=\text{const"}\\ \text{"}\Gamma=\text{const"}\\ \text{"}m=\text{const"}\\ \text{"}R=\text{const"}\end{pmatrix} = \begin{pmatrix} \cos\left(\alpha_{\text{st}(i,2), \text{av}(N_r)}\right)^2 \cdot \overline{v}_{\text{stator}_i} \\ 1 \cdot \overline{v}_{\text{stator}_i} \\ 0.2 \\ -1 \cdot \overline{v}_{\text{stator}_i} \end{pmatrix}$$

m^T =

| | 1 | 2 | 3 | 4 | 5 | 6 |
|---|---------|---------|--------|--------|--------|--------|
| 1 | -0.5000 | -0.2500 | 0.0000 | 0.2500 | 1.0000 | 1.0000 |

$$\begin{aligned}
& u_{st(i,2),av(N_r)} = \bar{v}_{stator_i} \cdot \cos(\alpha_{st(i,2),av(N_r)}) \\
& c_{a_{st(i,a),av(N_r)}} = c_{a_{st(i,a),av(N_r)}} \cdot \sqrt{1 + \frac{\left(1 - \frac{\bar{v}_{stator_i}}{m_i}\right) \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^{2 \cdot m_i}}\right]}{\tan(\alpha_{st(i,2),av(N_r)})^2}} \quad \text{if } a = 2 \\
& \left[\left(c_{a_{st(i,a),av(N_r)}}\right)^2 \dots \right. \\
& + \left[1 - \left(\bar{v}_{rotor_i}\right)^2\right] \cdot \left(u_{st(i,a),av(N_r)}\right)^2 \cdot \left[1 - \left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^2\right] - 2 \cdot c_{u_{st(i,a),av(N_r)}} \cdot u_{st(i,a),av(N_r)} \cdot \left[1 - \left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^{1-m_i}\right] \dots \\
& + \left[1 - \left(\bar{v}_{rotor_i}\right)^2\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^2}\right] \cdot \left(c_{u_{st(i,a-1),av(N_r)}} + c_{u_{st(i,a),av(N_r)}}\right)^2 \dots \\
& + -2 \cdot c_{u_{st(i,a-1),av(N_r)}} \cdot \left(c_{u_{st(i,a-1),av(N_r)}} + c_{u_{st(i,a),av(N_r)}}\right) \cdot \left[1 - \frac{2}{m_i + 1} \cdot \left(\bar{v}_{rotor_i}\right)^2\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^{m_i+1}}\right] \dots \\
& + \left(c_{u_{st(i,a-1),av(N_r)}}\right)^2 \cdot \left[1 - \frac{\left(\bar{v}_{stator_i}\right)^2 \cdot \left(\bar{v}_{rotor_i}\right)^2}{m_i}\right] \cdot \left[1 - \frac{1}{\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)^{2 \cdot m_i}}\right] \\
& \left. \right] \sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 + \frac{A_{st(i,a)} \cdot (m_i - 1) \cdot \left[-A_{st(i,a)} \cdot (m_i + 1) \cdot \left[\frac{1}{\left(R_{st(i,a),r}\right)^{2 \cdot m_i}} - \frac{1}{\left(R_{st(i,a),av(N_r)}\right)^{2 \cdot m_i}}\right] \dots \right.}{m_i \cdot (m_i + 1)} \left. + 2 \cdot B_{st(i,a)} \cdot m_i \cdot \left[\frac{1}{\left(R_{st(i,a),r}\right)^{m_i+1}} - \frac{1}{\left(R_{st(i,a),av(N_r)}\right)^{m_i+1}}\right] \cdot \begin{cases} -1 & \text{if } a = 2 \\ 1 & \text{otherwise} \end{cases} \right]} \quad \text{otherwise}
\end{aligned}$$

for $i \in 1..2 \cdot Z + 1$

for $r \in 1..N_r$

$$\begin{pmatrix} c_{u_{i,r}} \\ c_{a_{i,r}} \end{pmatrix} = c_{i,av(N_r)} \cdot \begin{pmatrix} \cos(\alpha_{i,av(N_r)}) \\ \sin(\alpha_{i,av(N_r)}) \end{pmatrix} \quad \text{if } (i = 1)$$

$$P_{i,r}^* = P_{i,av(N_r)}^*$$

$$T_{i,r}^* = T_{i,av(N_r)}^*$$

$$\rho_{i,r}^* = \frac{P_{i,r}^*}{R_{fa3}(\alpha_{ox_i}, Fuel) \cdot T_{i,r}^*}$$

$$k_{i,r} = k_{ад} \left(C_{p_{воздух}}(P^*_{i,r}, T^*_{i,r}), R_{газ}(\alpha_{ox_i}, Fuel) \right)$$

$$a^*_{c_{i,r}} = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \cdot T^*_{i,r}}$$

$$\alpha_{i,r} = \text{triangle}(c_{a_{i,r}}, c_{u_{i,r}})$$

$$c_{i,r} = \frac{c_{a_{i,r}}}{\sin(\alpha_{i,r})}$$

$$\lambda_{c_{i,r}} = \frac{c_{i,r}}{a^*_{c_{i,r}}}$$

$$\begin{pmatrix} T_{i,r} \\ P_{i,r} \\ \rho_{i,r} \end{pmatrix} = \begin{pmatrix} T^*_{i,r} \cdot \Gamma \Delta \Phi("T", \lambda_{c_{i,r}}, k_{i,r}) \\ P^*_{i,r} \cdot \Gamma \Delta \Phi("P", \lambda_{c_{i,r}}, k_{i,r}) \\ \rho^*_{i,r} \cdot \Gamma \Delta \Phi(" \rho ", \lambda_{c_{i,r}}, k_{i,r}) \end{pmatrix}$$

$$a_{3B_{i,r}} = \sqrt{k_{i,r} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \cdot T_{i,r}}$$

$$M_{c_{i,r}} = \frac{c_{i,r}}{a_{3B_{i,r}}}$$

$$\beta_{i,r} = \text{triangle}(c_{a_{i,r}}, u_{i,r} - c_{u_{i,r}})$$

$$w_{i,r} = \frac{c_{a_{i,r}}}{\sin(\beta_{i,r})}$$

$$\begin{pmatrix} w_{u_{i,r}} \\ w_{a_{i,r}} \end{pmatrix} = w_{i,r} \cdot \begin{pmatrix} \cos(\beta_{i,r}) \\ \sin(\beta_{i,r}) \end{pmatrix}$$

$$T^*_{w_{i,r}} = T^*_{i,r} - \frac{(c_{i,r})^2 - (w_{i,r})^2}{2 \cdot \frac{k_{i,r}}{k_{i,r} - 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel)}$$

$$a^*_{w_{i,r}} = \sqrt{\frac{2 \cdot k_{i,r}}{k_{i,r} + 1} \cdot R_{газ}(\alpha_{ox_i}, Fuel) \cdot T^*_{w_{i,r}}}$$

$$\lambda_{w_{i,r}} = \frac{w_{i,r}}{a^*_{w_{i,r}}}$$

$$M_{w_{i,r}} = \frac{w_{i,r}}{a_{3B_{i,r}}}$$

for i ∈ 1..Z

for r ∈ 1..N_r

$$|(\Delta c_{a_{i,r}}) - (c_{a_{i,r}} - c_{a_{i,r}})|$$

$$\begin{pmatrix} \widetilde{c}_{st(i,1),r} \\ \Delta c_{a_{st(i,2),r}} \end{pmatrix} = \begin{pmatrix} \widetilde{c}_{st(i,2),r} & \widetilde{c}_{st(i,1),r} \\ c_{a_{st(i,3),r}} - c_{a_{st(i,2),r}} \end{pmatrix}$$

$$R_{L_{i,r}} = 1 - \frac{c_{u_{st(i,2),r}} - c_{u_{st(i,3),r}}}{u_{st(i,2),r} + u_{st(i,3),r}}$$

$$\varepsilon_{stator_{i,r}} = \begin{cases} \alpha_{st(i,2),r} - \alpha_{st(i,1),r} & \text{if } \alpha_{st(i,2),r} \geq \frac{\pi}{2} \\ \alpha_{st(i,1),r} - \alpha_{st(i,2),r} & \text{otherwise} \end{cases}$$

$$\varepsilon_{rotor_{i,r}} = \begin{cases} \beta_{st(i,3),r} - \beta_{st(i,2),r} & \text{if } \beta_{st(i,3),r} \geq \frac{\pi}{2} \\ \beta_{st(i,2),r} - \beta_{st(i,3),r} & \text{otherwise} \end{cases}$$

$$\begin{pmatrix} P^* & T^* & T & \rho^* & k & a_c^* & a_{3B} & c & c_u & c_a & \Delta c_a & \alpha & \lambda_c & \lambda_w & \varepsilon_{stator} \\ P & T_w^* & T & \rho & R_L & a_w^* & a_{3B} & w & w_u & w_a & \Delta c_a & \beta & M_c & M_w & \varepsilon_{rotor} \end{pmatrix}^T$$

$$p^{*T} =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 927.5 | 915.4 | 676.8 | 666.5 | 483.6 | 476.7 | 338.0 | 332.9 | 229.2 |
| 2 | 927.5 | 915.4 | 676.8 | 666.5 | 483.6 | 476.7 | 338.0 | 332.9 | 229.2 |
| 3 | 927.5 | 915.4 | 676.8 | 666.5 | 483.6 | 476.7 | 338.0 | 332.9 | 229.2 |

·10³

$$T^{*T} =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 1368.9 | 1369.9 | 1281.1 | 1282.0 | 1192.3 | 1193.3 | 1102.4 | 1103.7 | 1011.4 |
| 2 | 1368.9 | 1369.9 | 1281.1 | 1282.0 | 1192.3 | 1193.3 | 1102.4 | 1103.7 | 1011.4 |
| 3 | 1368.9 | 1369.9 | 1281.1 | 1282.0 | 1192.3 | 1193.3 | 1102.4 | 1103.7 | 1011.4 |

$$T^{*T}_w =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 1381.3 | 1313.8 | 1273.2 | 1222.8 | 1197.0 | 1130.2 | 1120.2 | 1036.5 | 1033.9 |
| 2 | 1383.0 | 1313.1 | 1278.7 | 1222.6 | 1203.2 | 1130.7 | 1126.9 | 1038.0 | 1041.0 |
| 3 | 1384.8 | 1312.5 | 1284.4 | 1222.5 | 1209.7 | 1131.4 | 1133.9 | 1039.7 | 1048.3 |

$$\rho^{*T} =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 2.349 | 2.316 | 1.831 | 1.802 | 1.406 | 1.385 | 1.063 | 1.046 | 0.785 |
| 2 | 2.349 | 2.316 | 1.831 | 1.802 | 1.406 | 1.385 | 1.063 | 1.046 | 0.785 |
| 3 | 2.349 | 2.316 | 1.831 | 1.802 | 1.406 | 1.385 | 1.063 | 1.046 | 0.785 |

$$k^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |
| 2 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |
| 3 | 1.317 | 1.317 | 1.321 | 1.321 | 1.326 | 1.326 | 1.331 | 1.331 | 1.338 |

$$R_L^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 0.0536 | 0.0511 | 0.0925 | 0.1037 |
| 2 | 0.0913 | 0.1091 | 0.1574 | 0.1829 |
| 3 | 0.1251 | 0.1592 | 0.2136 | 0.2505 |

$$p^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 890.0 | 632.0 | 636.1 | 460.2 | 459.1 | 325.8 | 317.9 | 215.9 | 208.8 |
| 2 | 890.0 | 661.2 | 638.3 | 481.8 | 459.5 | 340.2 | 318.0 | 226.6 | 208.8 |
| 3 | 890.0 | 687.3 | 639.6 | 501.1 | 459.7 | 353.1 | 318.0 | 235.9 | 208.8 |

·10³

$$T^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|--------|--------|--------|--------|--------|--------|--------|--------|-------|
| 1 | 1355.4 | 1252.9 | 1262.0 | 1171.6 | 1177.2 | 1086.7 | 1085.7 | 990.9 | 987.9 |
| 2 | 1355.4 | 1266.6 | 1263.0 | 1184.8 | 1177.5 | 1098.4 | 1085.7 | 1002.9 | 987.9 |
| 3 | 1355.4 | 1278.5 | 1263.6 | 1196.1 | 1177.6 | 1108.5 | 1085.8 | 1013.1 | 987.9 |

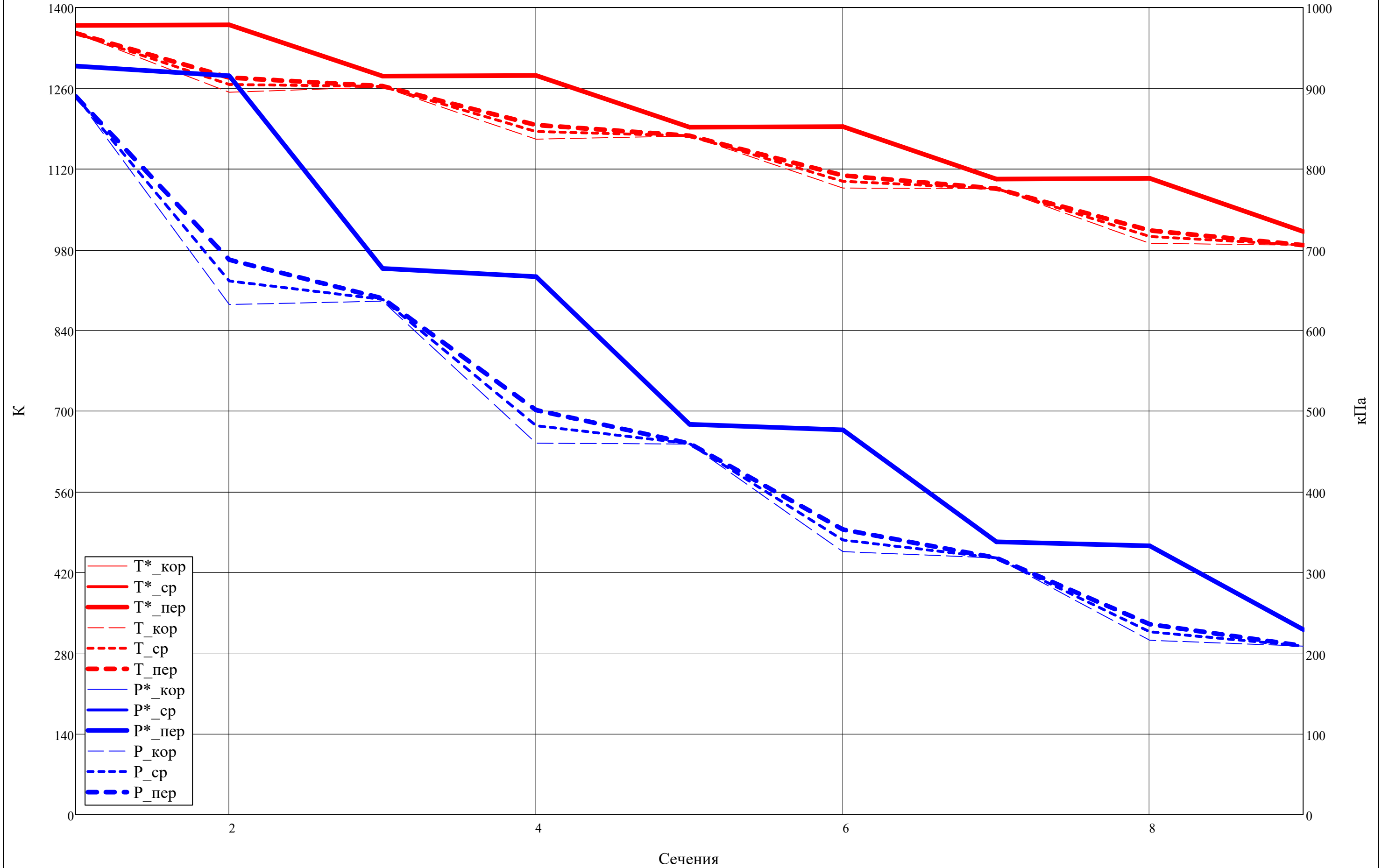
$$\rho^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 2.276 | 1.749 | 1.747 | 1.362 | 1.352 | 1.039 | 1.015 | 0.755 | 0.733 |
| 2 | 2.276 | 1.810 | 1.752 | 1.410 | 1.353 | 1.074 | 1.015 | 0.783 | 0.733 |
| 3 | 2.276 | 1.864 | 1.755 | 1.452 | 1.353 | 1.104 | 1.015 | 0.807 | 0.733 |

$$R_L^T \geq 0.05 =$$

| | 1 | 2 | 3 | 4 |
|---|---|---|---|---|
| 1 | 1 | 1 | 1 | 1 |
| 2 | 1 | 1 | 1 | 1 |
| 3 | 1 | 1 | 1 | 1 |

Термодинамические параметры по тракту К



$$\mathbf{a_c^*}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |
| 2 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |
| 3 | 670.1 | 670.3 | 648.6 | 648.9 | 626.2 | 626.5 | 602.7 | 603.0 | 577.9 |

$$\mathbf{u}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 172.2 | 172.2 | 180.7 | 193.8 | 208.2 | 222.8 | 234.2 | 240.3 | 240.3 |
| 2 | 183.8 | 185.7 | 195.4 | 209.3 | 224.4 | 239.4 | 251.6 | 258.7 | 260.0 |
| 3 | 195.3 | 199.1 | 210.0 | 224.7 | 240.5 | 256.1 | 268.9 | 277.0 | 279.7 |

$$\mathbf{c}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 529.2 | 213.2 | 511.7 | 188.4 | 500.2 | 196.8 | 511.3 | 231.7 |
| 2 | 180.0 | 497.3 | 207.1 | 480.3 | 186.6 | 472.1 | 196.6 | 483.5 | 231.7 |
| 3 | 180.0 | 467.8 | 203.6 | 451.4 | 185.8 | 446.3 | 196.6 | 458.4 | 231.7 |

$$\mathbf{c_u}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-----|-------|-------|-------|------|-------|------|-------|-------|
| 1 | 0.0 | 476.1 | 142.1 | 459.2 | 77.7 | 444.1 | 29.4 | 444.2 | 13.3 |
| 2 | 0.0 | 458.9 | 112.6 | 441.5 | 55.1 | 426.9 | 13.1 | 424.0 | 0.2 |
| 3 | 0.0 | 444.6 | 86.6 | 426.5 | 35.3 | 411.8 | -1.0 | 406.3 | -10.9 |

$$\mathbf{c_a}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 231.1 | 158.9 | 225.9 | 171.6 | 230.1 | 194.6 | 253.2 | 231.4 |
| 2 | 180.0 | 191.6 | 173.8 | 189.2 | 178.3 | 201.6 | 196.2 | 232.3 | 231.7 |
| 3 | 180.0 | 145.5 | 184.3 | 148.0 | 182.4 | 171.9 | 196.6 | 212.2 | 231.5 |

$$\Delta \mathbf{c_a}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|---|-------|-------|-------|-------|-------|-------|------|-------|
| 1 | 51.1 | -72.2 | 67.0 | -54.4 | 58.6 | -35.6 | 58.7 | -21.9 |
| 2 | 11.6 | -17.8 | 15.4 | -11.0 | 23.3 | -5.4 | 36.1 | -0.5 |
| 3 | -34.5 | 38.8 | -36.3 | 34.5 | -10.5 | 24.7 | 15.6 | 19.2 |

$$\mathbf{a_w^*}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 673.1 | 656.4 | 646.6 | 633.7 | 627.5 | 609.7 | 607.5 | 584.4 | 584.3 |
| 2 | 673.5 | 656.3 | 648.0 | 633.6 | 629.1 | 609.8 | 609.3 | 584.8 | 586.2 |
| 3 | 674.0 | 656.1 | 649.5 | 633.6 | 630.8 | 610.0 | 611.2 | 585.3 | 588.3 |

$$\mathbf{a_{3B}}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 717.7 | 690.0 | 693.6 | 668.3 | 671.0 | 644.7 | 645.8 | 616.9 | 617.5 |
| 2 | 717.7 | 693.8 | 693.9 | 672.0 | 671.1 | 648.2 | 645.8 | 620.6 | 617.5 |
| 3 | 717.7 | 697.0 | 694.0 | 675.2 | 671.2 | 651.1 | 645.8 | 623.8 | 617.5 |

$$\mathbf{w}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 249.1 | 381.8 | 163.5 | 348.6 | 215.6 | 319.3 | 282.5 | 325.1 | 324.1 |
| 2 | 257.2 | 333.7 | 192.5 | 299.5 | 245.8 | 275.2 | 308.8 | 285.1 | 348.1 |
| 3 | 265.6 | 285.4 | 221.8 | 250.2 | 274.5 | 232.0 | 334.0 | 248.5 | 371.5 |

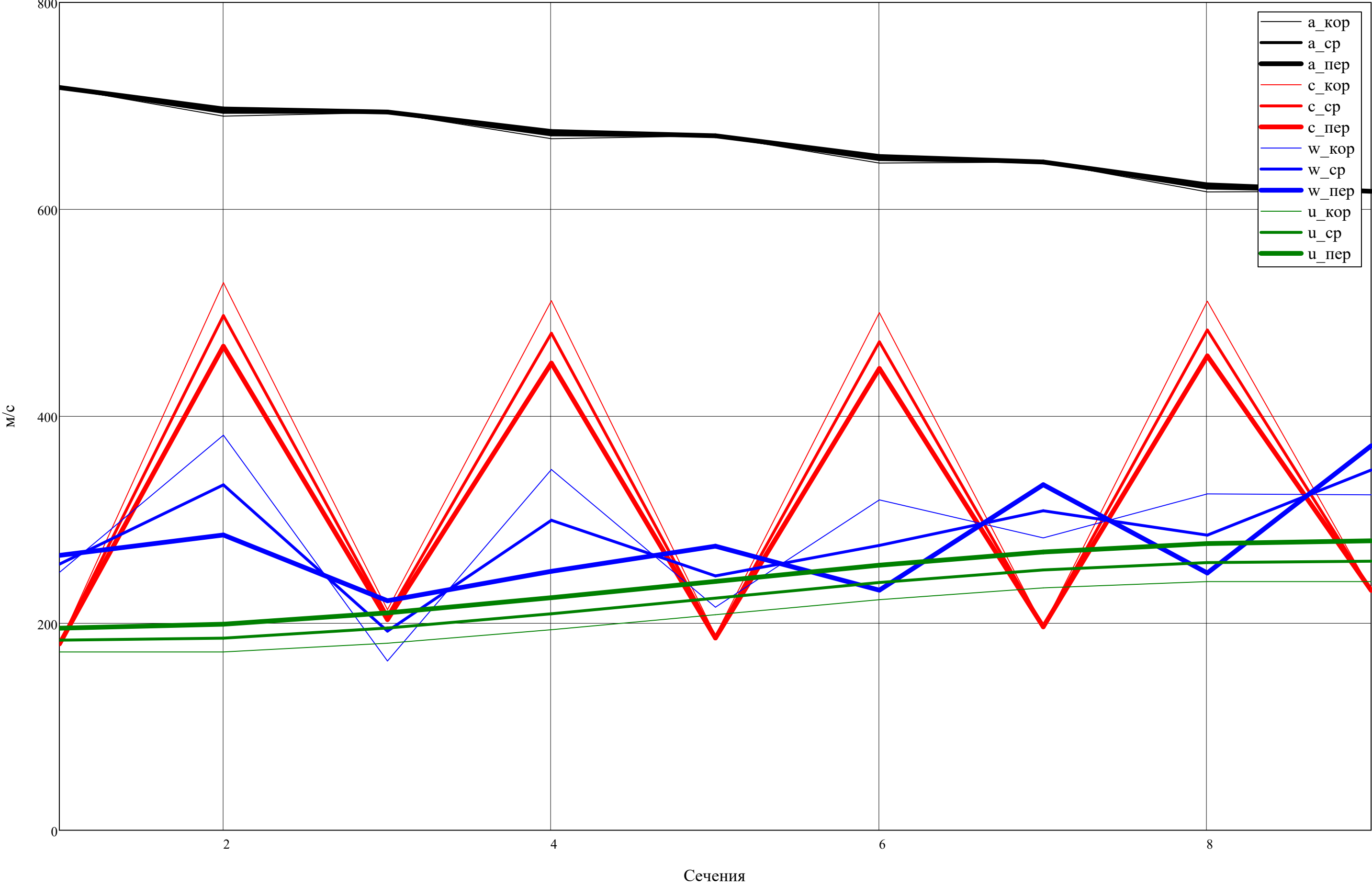
$$\mathbf{w_u}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|--------|-------|--------|-------|--------|-------|--------|-------|
| 1 | 172.2 | -303.9 | 38.6 | -265.4 | 130.5 | -221.3 | 204.8 | -203.8 | 227.0 |
| 2 | 183.8 | -273.2 | 82.7 | -232.2 | 169.2 | -187.4 | 238.4 | -165.3 | 259.8 |
| 3 | 195.3 | -245.5 | 123.4 | -201.7 | 205.2 | -155.7 | 269.9 | -129.3 | 290.6 |

$$\mathbf{w_a}^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 180.0 | 231.1 | 158.9 | 225.9 | 171.6 | 230.1 | 194.6 | 253.2 | 231.4 |
| 2 | 180.0 | 191.6 | 173.8 | 189.2 | 178.3 | 201.6 | 196.2 | 232.3 | 231.7 |
| 3 | 180.0 | 145.5 | 184.3 | 148.0 | 182.4 | 171.9 | 196.6 | 212.2 | 231.5 |

Скорости по тракту Т



$\alpha^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 90.00 | 25.89 | 48.19 | 26.20 | 65.64 | 27.39 | 81.41 | 29.69 | 86.70 |
| 2 | 90.00 | 22.66 | 57.06 | 23.20 | 72.81 | 25.28 | 86.17 | 28.72 | 89.95 |
| 3 | 90.00 | 18.12 | 64.82 | 19.13 | 79.04 | 22.65 | 90.30 | 27.58 | 92.70 |

$\alpha^T =$

$80^{\circ} \leq \alpha^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|---|---|---|---|---|---|---|---|---|
| 1 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 2 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 3 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |

$80^{\circ} \leq \alpha^T =$

[1, c.78]

Угол поворота потока:

$\epsilon_{\text{stator}}^T =$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 64.11 | 21.99 | 38.24 | 51.72 |
| 2 | 67.34 | 33.86 | 47.53 | 57.46 |
| 3 | 71.88 | 45.69 | 56.39 | 62.72 |

$\epsilon_{\text{stator}}^T =$

$\beta^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|--------|-------|--------|-------|--------|-------|--------|-------|
| 1 | 46.26 | 142.75 | 76.35 | 139.59 | 52.74 | 133.88 | 43.53 | 128.83 | 45.55 |
| 2 | 44.41 | 144.96 | 64.55 | 140.83 | 46.49 | 132.92 | 39.45 | 125.44 | 41.73 |
| 3 | 42.67 | 149.35 | 56.19 | 143.74 | 41.64 | 132.18 | 36.07 | 121.36 | 38.54 |

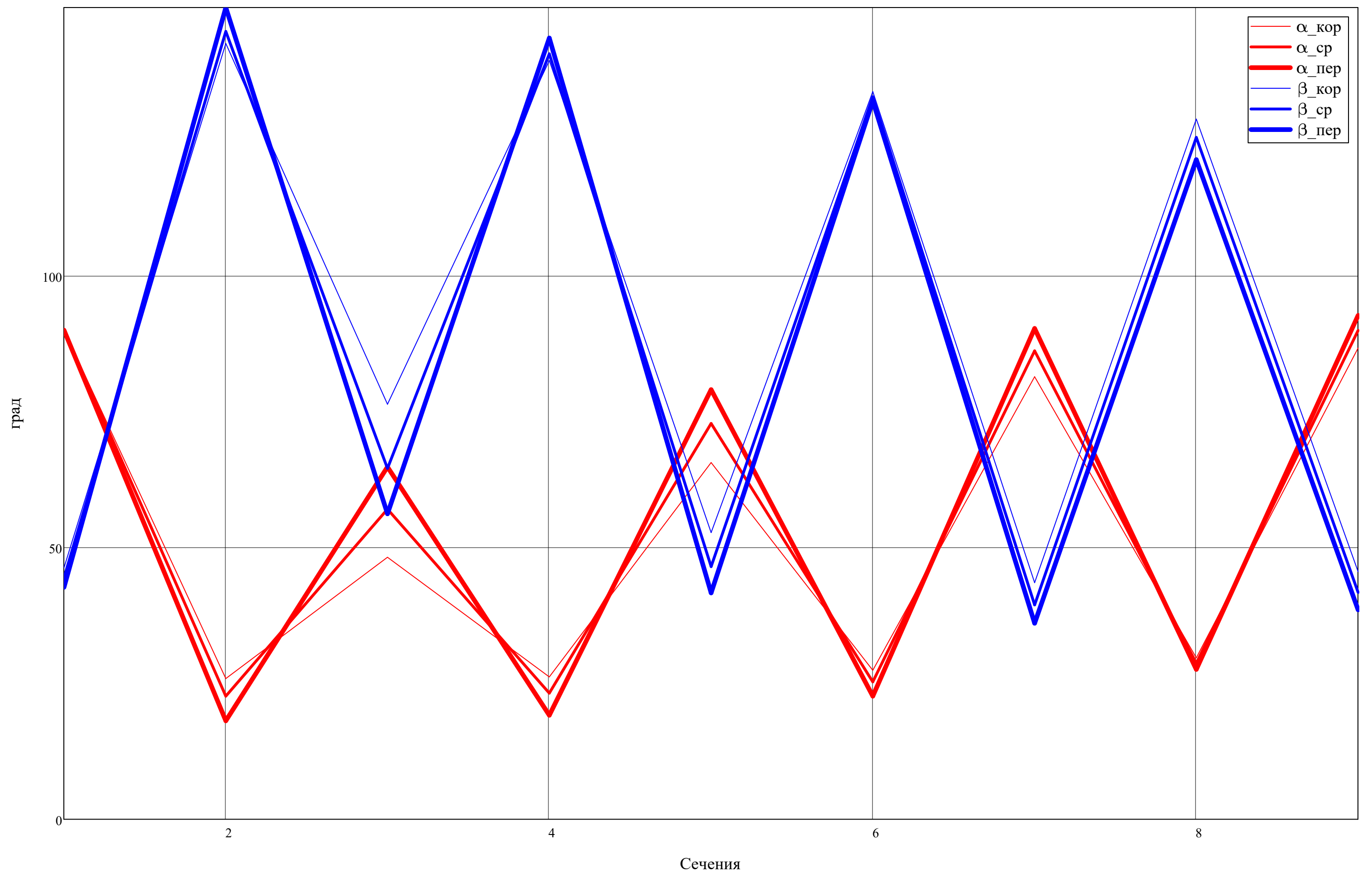
$\beta^T =$

$\epsilon_{\text{rotor}}^T =$

| | 1 | 2 | 3 | 4 |
|---|-------|--------|-------|-------|
| 1 | 66.40 | 86.85 | 90.35 | 83.28 |
| 2 | 80.41 | 94.34 | 93.47 | 83.71 |
| 3 | 93.16 | 102.10 | 96.11 | 82.82 |

$\epsilon_{\text{rotor}}^T =$

УГЛЫ по тракту К



$\lambda_c^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0.269 | 0.790 | 0.329 | 0.789 | 0.301 | 0.798 | 0.327 | 0.848 | 0.401 |
| 2 | 0.269 | 0.742 | 0.319 | 0.740 | 0.298 | 0.753 | 0.326 | 0.802 | 0.401 |
| 3 | 0.269 | 0.698 | 0.314 | 0.696 | 0.297 | 0.712 | 0.326 | 0.760 | 0.401 |

$M_c^T =$

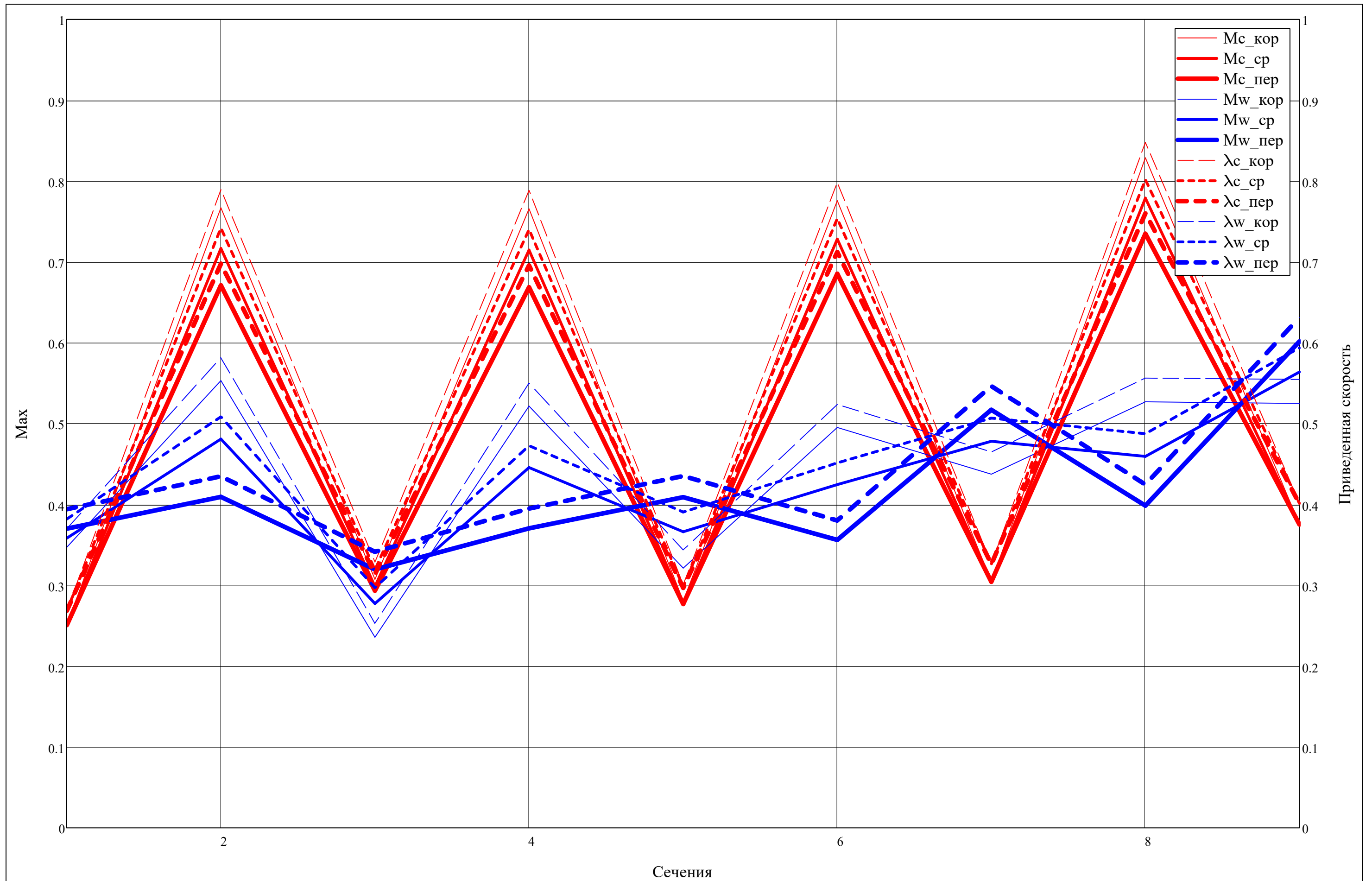
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0.251 | 0.767 | 0.307 | 0.766 | 0.281 | 0.776 | 0.305 | 0.829 | 0.375 |
| 2 | 0.251 | 0.717 | 0.299 | 0.715 | 0.278 | 0.728 | 0.304 | 0.779 | 0.375 |
| 3 | 0.251 | 0.671 | 0.293 | 0.669 | 0.277 | 0.685 | 0.304 | 0.735 | 0.375 |

$\lambda_w^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0.370 | 0.582 | 0.253 | 0.550 | 0.344 | 0.524 | 0.465 | 0.556 | 0.555 |
| 2 | 0.382 | 0.509 | 0.297 | 0.473 | 0.391 | 0.451 | 0.507 | 0.488 | 0.594 |
| 3 | 0.394 | 0.435 | 0.341 | 0.395 | 0.435 | 0.380 | 0.546 | 0.425 | 0.631 |

$M_w^T =$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 0.347 | 0.553 | 0.236 | 0.522 | 0.321 | 0.495 | 0.437 | 0.527 | 0.525 |
| 2 | 0.358 | 0.481 | 0.277 | 0.446 | 0.366 | 0.425 | 0.478 | 0.459 | 0.564 |
| 3 | 0.370 | 0.409 | 0.320 | 0.371 | 0.409 | 0.356 | 0.517 | 0.398 | 0.602 |



Рассматриваемая ступень:

j =

j = Z

j =

"Такой ступени не существует!" if (j < 1) ∨ (j > Z)

j otherwise

= 4

▼

Построение треугольников скоростей в 3х сечениях

Δ_c(v,i,j,r) =

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) ≥ 0) ∧ (−|c_{st(i,j),r}·cos(α_{st(i,j),r})| ≤ v ≤ 0)

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |c_{st(i,j),r}·cos(α_{st(i,j),r})|)

Δ_w(v,i,j,r) =

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) ≥ 0) ∧ (−|w_{st(i,j),r}·cos(β_{st(i,j),r})| ≤ v ≤ 0) ∧ (j ≠ 1)

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |w_{st(i,j),r}·cos(β_{st(i,j),r})|) ∧ (j ≠ 1)

Δ_u(v,i,j,r) =

−c_{a_{st(i,j),r}} if (−c_{st(i,j),r}·cos(α_{st(i,j),r}) ≤ v ≤ w_{st(i,j),r}·cos(β_{st(i,j),r})) ∧ (j ≠ 1)

NaN otherwise

v_{lim} =

ceil

⎛

max(c,w,u)

10²

⎞

·10² = 600.0

v =

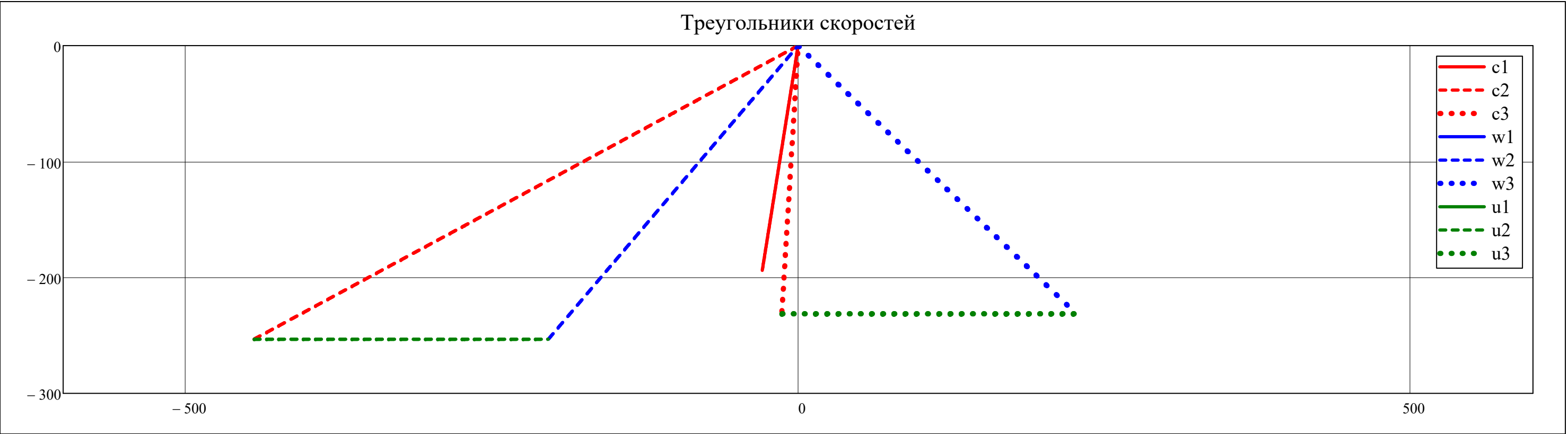
−max(c,w,u), −max(c,w,u) +

max(c,w,u)

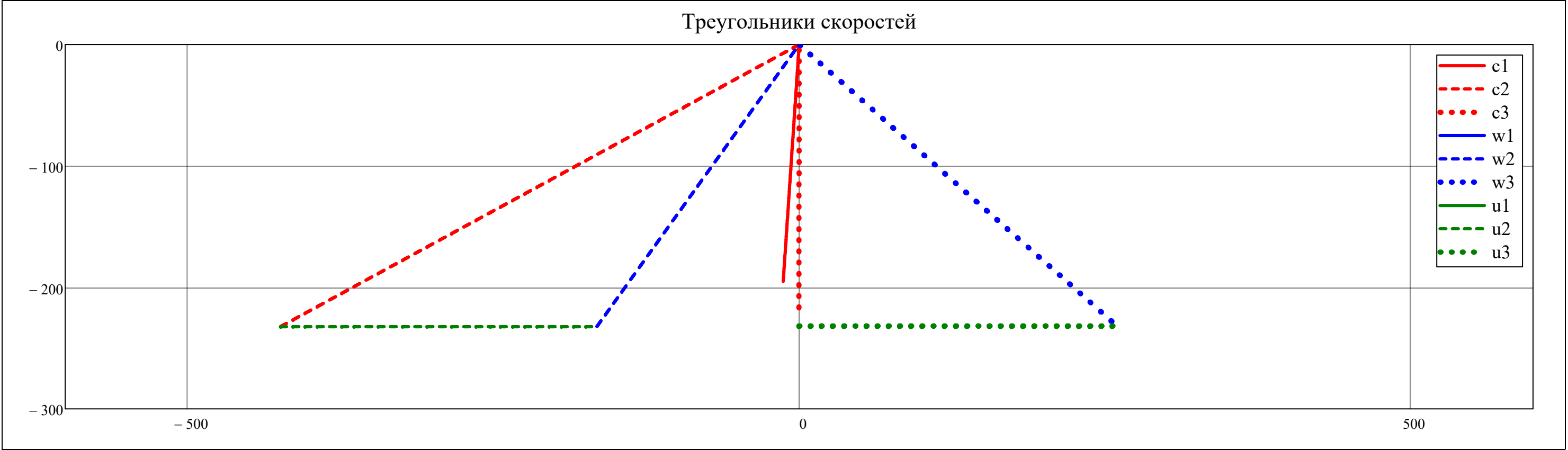
3000

.. max(c,w,u)

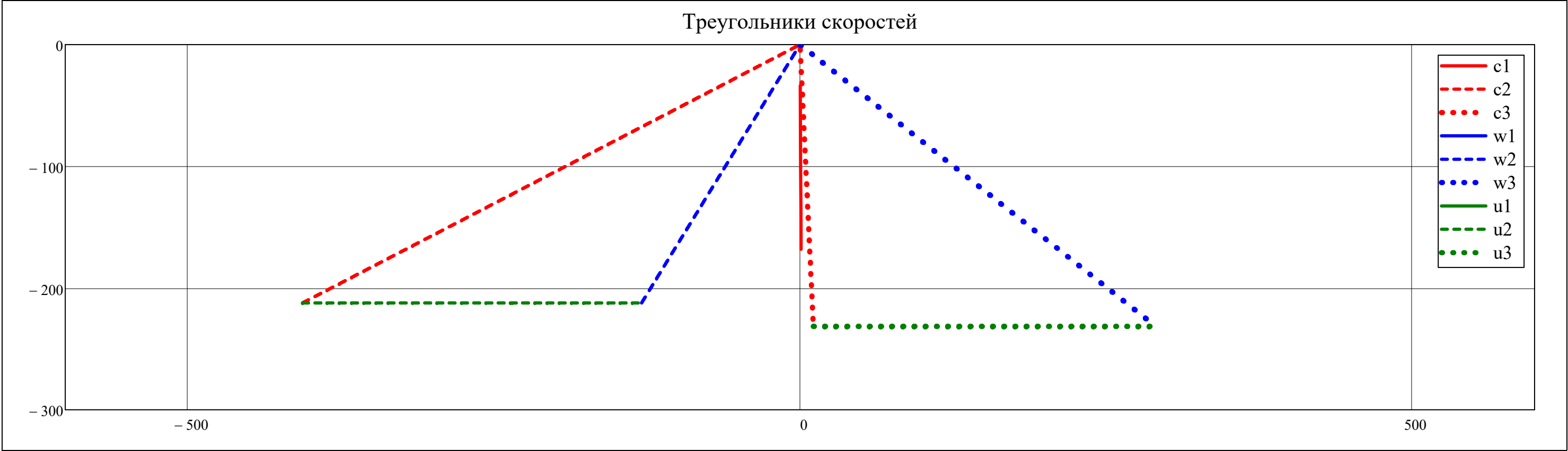
r = 1



$\bar{r}_w = \text{av}(N_r)$



$r_w = N_r$



Построение треугольников скоростей в 3х сечениях

Парусность:

$$\begin{pmatrix} \text{sail}_{\text{stator}} \\ \text{sail}_{\text{rotor}} \end{pmatrix} = \begin{pmatrix} 1 \\ 0.85 \end{pmatrix}$$

▼ Расчет хорд Л по парусности

$$\begin{pmatrix} \text{chord}_{\text{stator}} \\ \text{chord}_{\text{rotor}} \end{pmatrix} =$$

for i ∈ 1..Z

$$\text{sail} = \frac{R_{\text{st}(i,2),N_r} - R_{\text{st}(i,2),1}}{R_{\text{st}(i,2),\text{av}(N_r)} - R_{\text{st}(i,2),1}}$$

for r ∈ 1..N_r

$$b_{\text{CAkop}} = \frac{\text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \cdot \text{sail}}{\text{sail}_{\text{stator}} - 1 + \text{sail}}$$

$$b_{\text{PKkop}} = \frac{\text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \cdot \text{sail}}{\text{sail}_{\text{rotor}} - 1 + \text{sail}}$$

$$\begin{pmatrix} b_{\text{CAпер}} \\ b_{\text{PKпер}} \end{pmatrix} = \begin{pmatrix} b_{\text{CAkop}} \cdot \text{sail}_{\text{stator}} \\ b_{\text{PKkop}} \cdot \text{sail}_{\text{rotor}} \end{pmatrix}$$

$$\text{chord}_{\text{stator.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{CAkop}} \\ \text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \\ b_{\text{CAпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{CAkop}} \\ \text{chord}_{\text{stator}_{i,\text{av}(N_r)}} \\ b_{\text{CAпер}} \end{pmatrix}, z \right]$$

$$\text{chord}_{\text{rotor.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \\ b_{\text{PKпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i,2),1} \\ R_{\text{st}(i,2),\text{av}(N_r)} \\ R_{\text{st}(i,2),N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i,\text{av}(N_r)}} \\ b_{\text{PKпер}} \end{pmatrix}, z \right]$$

$$\begin{pmatrix} \text{chord}_{\text{stator}_{i,r}} \\ \text{chord}_{\text{rotor}_{i,r}} \end{pmatrix} = \begin{pmatrix} \text{chord}_{\text{stator.}}(R_{\text{st}(i,2),r}) \\ \text{chord}_{\text{rotor.}}(R_{\text{st}(i,3),r}) \end{pmatrix}$$

$$\begin{pmatrix} \text{chord}_{\text{stator}} \\ \text{chord}_{\text{rotor}} \end{pmatrix}$$

Длины хорд РК и СА (м):

$$\text{chord}_{\text{stator}}^T =$$

| | 1 | 2 | 3 | 4 |
|---|------|------|------|------|
| 1 | 58.7 | 50.6 | 60.4 | 69.4 |
| 2 | 58.7 | 50.6 | 60.4 | 69.4 |
| 3 | 58.7 | 50.6 | 60.4 | 69.4 |

$\cdot 10^{-3}$

$$\text{chord}_{\text{rotor}}^T =$$

| | 1 | 2 | 3 | 4 |
|---|------|------|------|------|
| 1 | 35.4 | 39.8 | 45.8 | 50.0 |
| 2 | 32.3 | 36.4 | 42.0 | 45.9 |
| 3 | 27.6 | 30.5 | 36.0 | 41.7 |

$\cdot 10^{-3}$

▲ Расчет хорд Л по парусности

Ср. линия профиля:
0.5 - дуга окружности
0.45 - парабола

$\overline{x_f} = 0.45$

t_{sator} t_{rotor}

$r_{\text{inlet}}_{\text{sator}}$ $r_{\text{inlet}}_{\text{rotor}}$

$r_{\text{outlet}}_{\text{sator}}$ $r_{\text{outlet}}_{\text{rotor}}$

c_{sator} c_{rotor}

v_{sator} v_{rotor}

=

for i ∈ 1..Z

for r ∈ 1..N_r

$t_{\text{sator}}_{i,r}$ $t_{\text{rotor}}_{i,r}$

$r_{\text{inlet}}_{\text{sator}}_{i,r}$ $r_{\text{inlet}}_{\text{rotor}}_{i,r}$

$r_{\text{outlet}}_{\text{sator}}_{i,r}$ $r_{\text{outlet}}_{\text{rotor}}_{i,r}$

$c_{\text{sator}}_{i,r}$ $c_{\text{rotor}}_{i,r}$

$v_{\text{sator}}_{i,r}$ $v_{\text{rotor}}_{i,r}$

$\left(\begin{array}{l} t_{\text{sator}}_{i,r} \\ t_{\text{rotor}}_{i,r} \end{array}\right) = \pi \cdot \left(\frac{\text{mean}\left(D_{\text{st}}(i,1),r,D_{\text{st}}(i,2),r\right)}{Z_{\text{sator}}_i} \right. \\ \left. \frac{\text{mean}\left(D_{\text{st}}(i,2),r,D_{\text{st}}(i,3),r\right)}{Z_{\text{rotor}}_i} \right)$

$\left(\begin{array}{l} r_{\text{inlet}}_{\text{sator}}_{i,r} \quad r_{\text{outlet}}_{\text{sator}}_{i,r} \\ r_{\text{inlet}}_{\text{rotor}}_{i,r} \quad r_{\text{outlet}}_{\text{rotor}}_{i,r} \end{array}\right) = \left(\begin{array}{l} \overline{r}_{\text{inlet}}_{\text{sator}}_{i,r} \cdot \text{chord}_{\text{sator}}_{i,r} \quad \overline{r}_{\text{outlet}}_{\text{sator}}_{i,r} \cdot \text{chord}_{\text{sator}}_{i,r} \\ \overline{r}_{\text{inlet}}_{\text{rotor}}_{i,r} \cdot \text{chord}_{\text{rotor}}_{i,r} \quad \overline{r}_{\text{outlet}}_{\text{rotor}}_{i,r} \cdot \text{chord}_{\text{rotor}}_{i,r} \end{array}\right)$

$\left(\begin{array}{l} c_{\text{sator}}_{i,r} \\ c_{\text{rotor}}_{i,r} \end{array}\right) = \left(\begin{array}{l} \overline{c}_{\text{sator}}_{i,r} \cdot \text{chord}_{\text{sator}}_{i,r} \\ \overline{c}_{\text{rotor}}_{i,r} \cdot \text{chord}_{\text{rotor}}_{i,r} \end{array}\right)$

$\left(\begin{array}{l} v_{\text{sator}}_{i,r} \\ v_{\text{rotor}}_{i,r} \end{array}\right) = \left(\begin{array}{l} v_{\text{installation}}\left(0.5,\alpha_{\text{st}}(i,1),r,\alpha_{\text{st}}(i,2),r\right) \\ v_{\text{installation}}\left(0.5,\beta_{\text{st}}(i,2),r,\beta_{\text{st}}(i,3),r\right) \end{array}\right) + \frac{\pi}{2}$

t_{sator} t_{rotor}

$r_{\text{inlet}}_{\text{sator}}$ $r_{\text{inlet}}_{\text{rotor}}$

$r_{\text{outlet}}_{\text{sator}}$ $r_{\text{outlet}}_{\text{rotor}}$

c_{sator} c_{rotor}

v_{sator} v_{rotor}

$\left(\begin{array}{l} v_{\text{установки}}\left(\alpha_{\text{st}}(i,1),r,\alpha_{\text{st}}(i,2),r\right) \\ v_{\text{установки}}\left(\beta_{\text{st}}(i,2),r,\beta_{\text{st}}(i,3),r\right) \end{array}\right)$

$\frac{\pi}{2}$ добавляется в виду поворота рисунка на 90 град

Расчет параметров решетки

Относительные радиусы профилей ():

| | | | | | | |
|--------------------------------------|---|-------|-------|-------|-------|----|
| $\overline{r}_{inlet_{stator}}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 2.800 | 2.800 | 2.800 | 2.800 | |
| | 2 | 3.600 | 3.600 | 3.600 | 3.600 | |
| | 3 | 4.400 | 4.400 | 4.400 | 4.400 | |
| $\overline{r}_{outlet_{stator}}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 1.400 | 1.400 | 1.400 | 1.400 | |
| | 2 | 1.800 | 1.800 | 1.800 | 1.800 | |
| | 3 | 2.200 | 2.200 | 2.200 | 2.200 | |
| $\overline{r}_{inlet_{rotor}}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 4.900 | 4.900 | 4.900 | 4.900 | |
| | 2 | 3.150 | 3.150 | 3.150 | 3.150 | |
| | 3 | 2.450 | 2.450 | 2.450 | 2.450 | |
| $\overline{r}_{outlet_{rotor}}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 2.100 | 2.100 | 2.100 | 2.100 | |
| | 2 | 1.350 | 1.350 | 1.350 | 1.350 | |
| | 3 | 1.050 | 1.050 | 1.050 | 1.050 | |

Относительная толщина профиля ():

| | | | | | | |
|-----------------------------|---|-------|-------|-------|-------|----|
| $\overline{c}_{stator}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 7.00 | 7.00 | 7.00 | 7.00 | |
| | 2 | 9.00 | 9.00 | 9.00 | 9.00 | |
| | 3 | 11.00 | 11.00 | 11.00 | 11.00 | |
| $\overline{c}_{rotor}^T =$ | | 1 | 2 | 3 | 4 | .% |
| | 1 | 14.00 | 14.00 | 14.00 | 14.00 | |
| | 2 | 9.00 | 9.00 | 9.00 | 9.00 | |
| | 3 | 7.00 | 7.00 | 7.00 | 7.00 | |

Относительный шаг решетки ():

| | | | | | |
|--|---|--------|--------|--------|--------|
| $\left(\frac{t_{stator}}{chord_{stator}}\right)^T =$ | | 1 | 2 | 3 | 4 |
| | 1 | 0.6923 | 0.5507 | 0.5942 | 0.6244 |
| | 2 | 0.7425 | 0.5950 | 0.6394 | 0.6714 |
| | 3 | 0.7927 | 0.6394 | 0.6846 | 0.7183 |
| $\left(\frac{t_{rotor}}{chord_{rotor}}\right)^T =$ | | 1 | 2 | 3 | 4 |
| | 1 | 0.5592 | 0.5901 | 0.6211 | 0.6117 |
| | 2 | 0.6605 | 0.6948 | 0.7272 | 0.7179 |
| | 3 | 0.8317 | 0.8911 | 0.9077 | 0.8495 |

Относительная густота решетки ():

| | | | | | |
|--|---|-------|-------|-------|-------|
| $\left(\frac{chord_{stator}}{t_{stator}}\right)^T =$ | | 1 | 2 | 3 | 4 |
| | 1 | 1.444 | 1.816 | 1.683 | 1.602 |
| | 2 | 1.347 | 1.681 | 1.564 | 1.490 |
| | 3 | 1.262 | 1.564 | 1.461 | 1.392 |
| $\left(\frac{chord_{rotor}}{t_{rotor}}\right)^T =$ | | 1 | 2 | 3 | 4 |
| | 1 | 1.788 | 1.695 | 1.610 | 1.635 |
| | 2 | 1.514 | 1.439 | 1.375 | 1.393 |
| | 3 | 1.202 | 1.122 | 1.102 | 1.177 |

Длина хорды профиля [м]:

$$\text{chord}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 58.7 & 50.6 & 60.4 & 69.4 \\ \hline 2 & 58.7 & 50.6 & 60.4 & 69.4 \\ \hline 3 & 58.7 & 50.6 & 60.4 & 69.4 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{chord}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 35.4 & 39.8 & 45.8 & 50.0 \\ \hline 2 & 32.3 & 36.4 & 42.0 & 45.9 \\ \hline 3 & 27.6 & 30.5 & 36.0 & 41.7 \\ \hline \end{array} \cdot 10^{-3}$$

Радиусы профилей:

$$\text{r_inlet}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1.64 & 1.42 & 1.69 & 1.94 \\ \hline 2 & 2.11 & 1.82 & 2.17 & 2.50 \\ \hline 3 & 2.58 & 2.23 & 2.66 & 3.05 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_inlet}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1.73 & 1.95 & 2.24 & 2.45 \\ \hline 2 & 1.02 & 1.15 & 1.32 & 1.45 \\ \hline 3 & 0.68 & 0.75 & 0.88 & 1.02 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.82 & 0.71 & 0.85 & 0.97 \\ \hline 2 & 1.06 & 0.91 & 1.09 & 1.25 \\ \hline 3 & 1.29 & 1.11 & 1.33 & 1.53 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{r_outlet}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.74 & 0.83 & 0.96 & 1.05 \\ \hline 2 & 0.44 & 0.49 & 0.57 & 0.62 \\ \hline 3 & 0.29 & 0.32 & 0.38 & 0.44 \\ \hline \end{array} \cdot 10^{-3}$$

Толщина профиля [м]:

$$\text{c}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 4.11 & 3.55 & 4.23 & 4.86 \\ \hline 2 & 5.28 & 4.56 & 5.43 & 6.24 \\ \hline 3 & 6.45 & 5.57 & 6.64 & 7.63 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{c}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 4.95 & 5.57 & 6.41 & 7.00 \\ \hline 2 & 2.91 & 3.28 & 3.78 & 4.14 \\ \hline 3 & 1.93 & 2.13 & 2.52 & 2.92 \\ \hline \end{array} \cdot 10^{-3}$$

Шаг решетки [м]:

$$\text{t}_{\text{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 40.6 & 27.9 & 35.9 & 43.3 \\ \hline 2 & 43.6 & 30.1 & 38.6 & 46.6 \\ \hline 3 & 46.5 & 32.4 & 41.3 & 49.8 \\ \hline \end{array} \cdot 10^{-3}$$

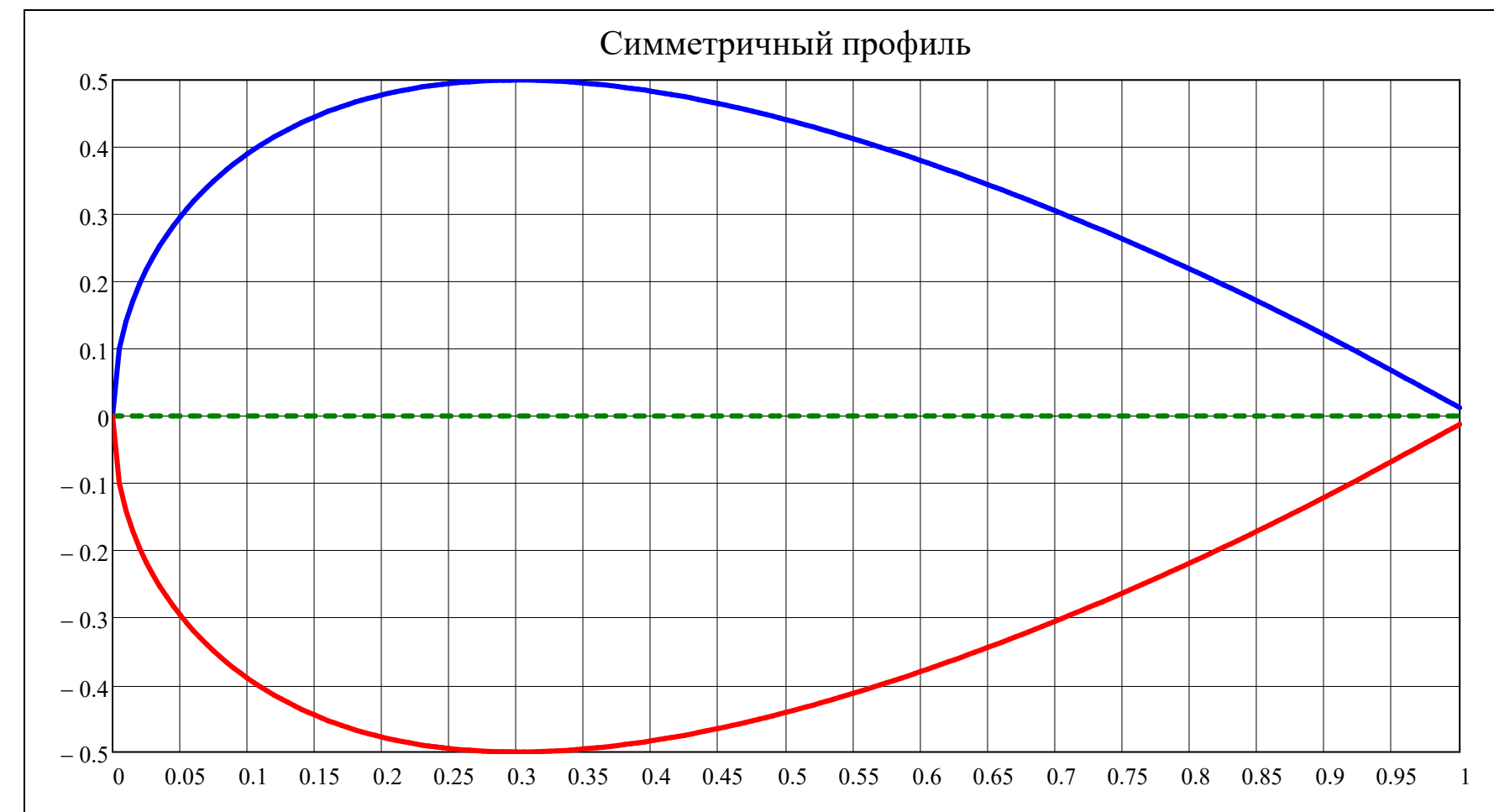
$$\text{t}_{\text{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 19.8 & 23.5 & 28.4 & 30.6 \\ \hline 2 & 21.4 & 25.3 & 30.5 & 33.0 \\ \hline 3 & 22.9 & 27.1 & 32.7 & 35.4 \\ \hline \end{array} \cdot 10^{-3}$$

| | | | | | | | | | | | | | | |
|-------------------------|--------------------------------------|---|-------|-------|-------|-------|----|-------------------------------------|---|-------|--------|-------|-------|----|
| Угол поворота потока: | $\epsilon_{\text{stator}}^T =$ | | 1 | 2 | 3 | 4 | .° | $\epsilon_{\text{rotor}}^T =$ | | 1 | 2 | 3 | 4 | .° |
| | | 1 | 64.11 | 21.99 | 38.24 | 51.72 | | | 1 | 66.40 | 86.85 | 90.35 | 83.28 | |
| | | 2 | 67.34 | 33.86 | 47.53 | 57.46 | | | 2 | 80.41 | 94.34 | 93.47 | 83.71 | |
| | | 3 | 71.88 | 45.69 | 56.39 | 62.72 | | | 3 | 93.16 | 102.10 | 96.11 | 82.82 | |
| Угол установки профиля: | $\upsilon_{\text{stator}}^T =$ | | 1 | 2 | 3 | 4 | .° | $\upsilon_{\text{rotor}}^T =$ | | 1 | 2 | 3 | 4 | .° |
| | | 1 | 134.1 | 124.4 | 130.0 | 136.4 | | | 1 | 142.1 | 135.9 | 134.8 | 138.2 | |
| | | 2 | 129.9 | 123.9 | 129.5 | 136.6 | | | 2 | 136.4 | 132.6 | 133.0 | 137.5 | |
| | | 3 | 123.2 | 120.8 | 127.7 | 136.2 | | | 3 | 130.3 | 128.8 | 131.3 | 137.0 | |
| Угол изгиба профиля: | $\pi - \epsilon_{\text{stator}}^T =$ | | 1 | 2 | 3 | 4 | .° | $\pi - \epsilon_{\text{rotor}}^T =$ | | 1 | 2 | 3 | 4 | .° |
| | | 1 | 115.9 | 158.0 | 141.8 | 128.3 | | | 1 | 113.6 | 93.1 | 89.7 | 96.7 | |
| | | 2 | 112.7 | 146.1 | 132.5 | 122.5 | | | 2 | 99.6 | 85.7 | 86.5 | 96.3 | |
| | | 3 | 108.1 | 134.3 | 123.6 | 117.3 | | | 3 | 86.8 | 77.9 | 83.9 | 97.2 | |

$$\begin{pmatrix} X_U & Y_U \\ X_L & Y_L \end{pmatrix} = \text{NACA}(0,0,100\%,1)$$

Относ. координаты профиля РК и СА:

| | | |
|---|--|------------------------|
| $\text{AIRFOIL}_0(x, \text{line}, \bar{f}, \bar{x}_f, \bar{c}) =$ | $\begin{cases} \text{if } 0 \leq x \leq 1 \\ \left \begin{array}{ll} \text{lininterp}(X_U, Y_U, x) & \text{if line} = "+" \\ \frac{\text{lininterp}(X_U, Y_U, x) + \text{lininterp}(X_L, Y_L, x)}{2} & \text{if line} = "0" \\ \text{lininterp}(X_L, Y_L, x) & \text{if line} = "-" \end{array} \right. \\ \text{NaN} & \text{otherwise} \end{cases}$ | $x = 0, 0.005 \dots 1$ |
|---|--|------------------------|



AIRFOIL(x,line,¯c ,θ) =

linterp(X_U,y/b_{ср.л}(X_U,θ) + Y_U·¯c ,x)

if line = "+"

linterp(X_U,y/b_{ср.л}(X_U,θ) + Y_U·¯c ,x)

+ linterp(X_L,y/b_{ср.л}(X_L,θ) + Y_L·¯c ,x)

2

if line = "0"

linterp(X_L,y/b_{ср.л}(X_L,θ) + Y_L·¯c ,x)

if line = "-"

NaN otherwise

Профиль СА на ср. сечении

Профиль РК на ср. сечении

Подключение симметричного профиля

$$l_{upper_stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 63.47 | 51.71 | 62.74 | 73.48 |
| 2 | 64.41 | 52.70 | 64.03 | 74.79 |
| 3 | 65.61 | 53.99 | 65.52 | 76.17 |

$$\cdot 10^{-3}$$

$$l_{lower_stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 60.67 | 50.86 | 60.98 | 70.78 |
| 2 | 60.72 | 51.07 | 61.31 | 71.03 |
| 3 | 60.91 | 51.38 | 61.69 | 71.35 |

$$\cdot 10^{-3}$$

$$area_{stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 164.78 | 122.77 | 174.49 | 230.41 |
| 2 | 211.86 | 157.85 | 224.34 | 296.25 |
| 3 | 258.93 | 192.93 | 274.19 | 362.08 |

$$\cdot 10^{-6}$$

$$Sx_{stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|-------|--------|--------|
| 1 | 1061.6 | 226.1 | 672.4 | 1396.3 |
| 2 | 1439.6 | 450.4 | 1082.8 | 2006.5 |
| 3 | 1890.1 | 749.6 | 1584.1 | 2693.9 |

$$\cdot 10^{-9}$$

$$Sy_{stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|---------|
| 1 | 4071.3 | 2618.3 | 4436.4 | 6732.1 |
| 2 | 5234.5 | 3366.4 | 5703.9 | 8655.5 |
| 3 | 6397.7 | 4114.5 | 6971.5 | 10579.0 |

$$\cdot 10^{-9}$$

$$x0_{stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 24.71 | 21.33 | 25.43 | 29.22 |
| 2 | 24.71 | 21.33 | 25.43 | 29.22 |
| 3 | 24.71 | 21.33 | 25.43 | 29.22 |

$$\cdot 10^{-3}$$

$$y0_{stator}^T =$$

| | 1 | 2 | 3 | 4 |
|---|------|------|------|------|
| 1 | 6.44 | 1.84 | 3.85 | 6.06 |
| 2 | 6.80 | 2.85 | 4.83 | 6.77 |
| 3 | 7.30 | 3.89 | 5.78 | 7.44 |

$$\cdot 10^{-3}$$

$$l_{upper_rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 39.66 | 46.66 | 54.18 | 58.15 |
| 2 | 36.48 | 42.49 | 48.89 | 52.24 |
| 3 | 31.76 | 35.92 | 41.76 | 46.84 |

$$\cdot 10^{-3}$$

$$l_{lower_rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 36.43 | 41.97 | 48.58 | 52.49 |
| 2 | 34.08 | 39.38 | 45.33 | 48.71 |
| 3 | 29.93 | 33.74 | 39.30 | 44.33 |

$$\cdot 10^{-3}$$

$$area_{rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 119.78 | 151.28 | 200.50 | 239.04 |
| 2 | 64.32 | 81.62 | 108.55 | 129.92 |
| 3 | 36.38 | 44.43 | 61.95 | 83.13 |

$$\cdot 10^{-6}$$

$$Sx_{rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|--------|--------|
| 1 | 483.2 | 926.0 | 1479.2 | 1752.8 |
| 2 | 293.2 | 504.1 | 764.8 | 881.1 |
| 3 | 167.6 | 252.5 | 386.5 | 505.1 |

$$\cdot 10^{-9}$$

$$Sy_{rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|--------|--------|--------|--------|
| 1 | 1784.1 | 2532.5 | 3864.1 | 5030.0 |
| 2 | 875.6 | 1251.6 | 1919.7 | 2513.8 |
| 3 | 422.4 | 570.0 | 938.6 | 1458.9 |

$$\cdot 10^{-9}$$

$$x0_{rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|-------|-------|-------|-------|
| 1 | 14.90 | 16.74 | 19.27 | 21.04 |
| 2 | 13.61 | 15.34 | 17.69 | 19.35 |
| 3 | 11.61 | 12.83 | 15.15 | 17.55 |

$$\cdot 10^{-3}$$

$$y0_{rotor}^T =$$

| | 1 | 2 | 3 | 4 |
|---|------|------|------|------|
| 1 | 4.03 | 6.12 | 7.38 | 7.33 |
| 2 | 4.56 | 6.18 | 7.05 | 6.78 |
| 3 | 4.61 | 5.68 | 6.24 | 6.08 |

$$\cdot 10^{-3}$$

$$J_{x_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 7676 & 549 & 3039 & 9634 \\ \hline 2 & 11083 & 1608 & 6143 & 15621 \\ \hline 3 & 15756 & 3556 & 10770 & 23247 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 131811 & 73173 & 147804 & 257737 \\ \hline 2 & 169471 & 94079 & 190034 & 331377 \\ \hline 3 & 207131 & 114986 & 232263 & 405016 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 27857 & 5131 & 18182 & 43361 \\ \hline 2 & 37769 & 10217 & 29269 & 62292 \\ \hline 3 & 49570 & 16997 & 42799 & 83602 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 837 & 133 & 448 & 1172 \\ \hline 2 & 1301 & 323 & 916 & 2030 \\ \hline 3 & 1960 & 644 & 1617 & 3204 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 31219 & 17331 & 35007 & 61045 \\ \hline 2 & 40139 & 22283 & 45009 & 78486 \\ \hline 3 & 49059 & 27234 & 55011 & 95928 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 1628 & 309 & 1086 & 2565 \\ \hline 2 & 2200 & 612 & 1737 & 3666 \\ \hline 3 & 2871 & 1010 & 2522 & 4894 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{stator}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 3.06 & 1.03 & 1.80 & 2.45 \\ \hline 2 & 3.23 & 1.59 & 2.25 & 2.74 \\ \hline 3 & 3.48 & 2.17 & 2.70 & 3.01 \\ \hline \end{array} \cdot ^\circ$$

$$J_{x_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 2310 & 6463 & 12383 & 14730 \\ \hline 2 & 1494 & 3444 & 5964 & 6663 \\ \hline 3 & 850 & 1571 & 2649 & 3398 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 34823 & 55552 & 97582 & 138694 \\ \hline 2 & 15620 & 25151 & 44488 & 63733 \\ \hline 3 & 6426 & 9583 & 18633 & 33548 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 7643 & 16433 & 30208 & 39111 \\ \hline 2 & 4234 & 8188 & 14327 & 18078 \\ \hline 3 & 2061 & 3427 & 6201 & 9401 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{x0_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 361 & 794 & 1471 & 1878 \\ \hline 2 & 158 & 330 & 575 & 687 \\ \hline 3 & 78 & 136 & 238 & 329 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{y0_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 8248 & 13158 & 23112 & 32850 \\ \hline 2 & 3700 & 5957 & 10537 & 15095 \\ \hline 3 & 1522 & 2270 & 4413 & 7946 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{xy0_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 446 & 931 & 1701 & 2229 \\ \hline 2 & 242 & 458 & 802 & 1029 \\ \hline 3 & 115 & 188 & 345 & 536 \\ \hline \end{array} \cdot 10^{-12}$$

$$\alpha_{\text{major}_{\text{rotor}}}^T = \begin{array}{c|c|c|c|c} & 1 & 2 & 3 & 4 \\ \hline 1 & 3.22 & 4.28 & 4.47 & 4.09 \\ \hline 2 & 3.90 & 4.62 & 4.57 & 4.07 \\ \hline 3 & 4.54 & 5.01 & 4.70 & 4.01 \\ \hline \end{array} \cdot ^\circ$$

$$J_{u_{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 750 & 127 & 414 & 1063 \\ \hline 2 & 1176 & 306 & 848 & 1855 \\ \hline 3 & 1785 & 605 & 1499 & 2946 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 31306.3 & 17336.5 & 35041.3 & 61154.6 \\ \hline 2 & 40263.3 & 22299.6 & 45077.7 & 78661.7 \\ \hline 3 & 49233.3 & 27272.6 & 55130.2 & 96185.3 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0 & 0 & -0 & 0 \\ \hline 2 & 0 & 0 & 0 & -0 \\ \hline 3 & 0 & 0 & 0 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 32056 & 17464 & 35455 & 62217 \\ \hline 2 & 41440 & 22605 & 45925 & 80516 \\ \hline 3 & 51018 & 27878 & 56629 & 99132 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 927.3 & 594.5 & 1008.3 & 1531.7 \\ \hline 2 & 1196.3 & 767.4 & 1301.6 & 1976.7 \\ \hline 3 & 1468.5 & 942.6 & 1598.5 & 2426.8 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{stator}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 639.9 & 355.2 & 717.6 & 1251.3 \\ \hline 2 & 1360.1 & 755.0 & 1525.1 & 2659.5 \\ \hline 3 & 2483.2 & 1378.5 & 2784.5 & 4855.6 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{u_{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 336 & 725 & 1338 & 1718 \\ \hline 2 & 141 & 293 & 511 & 614 \\ \hline 3 & 68 & 120 & 209 & 291 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{v_{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 8273 & 13227 & 23245 & 33009 \\ \hline 2 & 3716 & 5994 & 10601 & 15168 \\ \hline 3 & 1531 & 2286 & 4442 & 7983 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{uv_{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0 & 0 & 0 & 0 \\ \hline 2 & 0 & 0 & -0 & 0 \\ \hline 3 & 0 & -0 & 0 & 0 \\ \hline \end{array} \cdot 10^{-12}$$

$$J_{p_{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 8609 & 13952 & 24583 & 34727 \\ \hline 2 & 3857 & 6288 & 11113 & 15782 \\ \hline 3 & 1599 & 2406 & 4651 & 8275 \\ \hline \end{array} \cdot 10^{-12}$$

$$W_{p_{rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 412.5 & 585.9 & 893.9 & 1163.7 \\ \hline 2 & 200.3 & 286.2 & 439.0 & 575.0 \\ \hline 3 & 96.3 & 129.8 & 213.9 & 332.6 \\ \hline \end{array} \cdot 10^{-9}$$

$$stiffness_{rotor}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 676.2 & 1078.8 & 1895.0 & 2693.4 \\ \hline 2 & 125.4 & 201.9 & 357.0 & 511.5 \\ \hline 3 & 31.2 & 46.5 & 90.5 & 162.9 \\ \hline \end{array} \cdot 10^{-12}$$

CP_x_{stator}^T =

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 20.536 | 17.726 | 21.132 | 24.284 |
| 2 | 20.536 | 17.726 | 21.132 | 24.284 |
| 3 | 20.536 | 17.726 | 21.132 | 24.284 |

·10⁻³

CP_y_{stator}^T =

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| 2 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| 3 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |

·10⁻³

CP_x_{rotor}^T =

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 12.380 | 13.914 | 16.018 | 17.490 |
| 2 | 11.315 | 12.746 | 14.699 | 16.082 |
| 3 | 9.649 | 10.663 | 12.592 | 14.586 |

·10⁻³

CP_y_{rotor}^T =

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| 2 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| 3 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |

·10⁻³

Абс. координаты профиля:

| | |
|----------------------------|--|
| Airfoil(type,x,line,i,r) = | <div><div><div>$\text{AIRFOIL}\left(x,\text{line},\overline{c}_{\text{stator}_{i,r}},\varepsilon_{\text{stator}_{i,r}}\right)$</div><div>if type = "stator"</div></div><div><div>$\text{AIRFOIL}\left(x,\text{line},\overline{c}_{\text{rotor}_{i,r}},\varepsilon_{\text{rotor}_{i,r}}\right)$</div><div>if type = "rotor"</div></div></div> |
|----------------------------|--|

Рассматриваемая ступень:

$$j_v = \begin{cases} j = Z & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 4$$

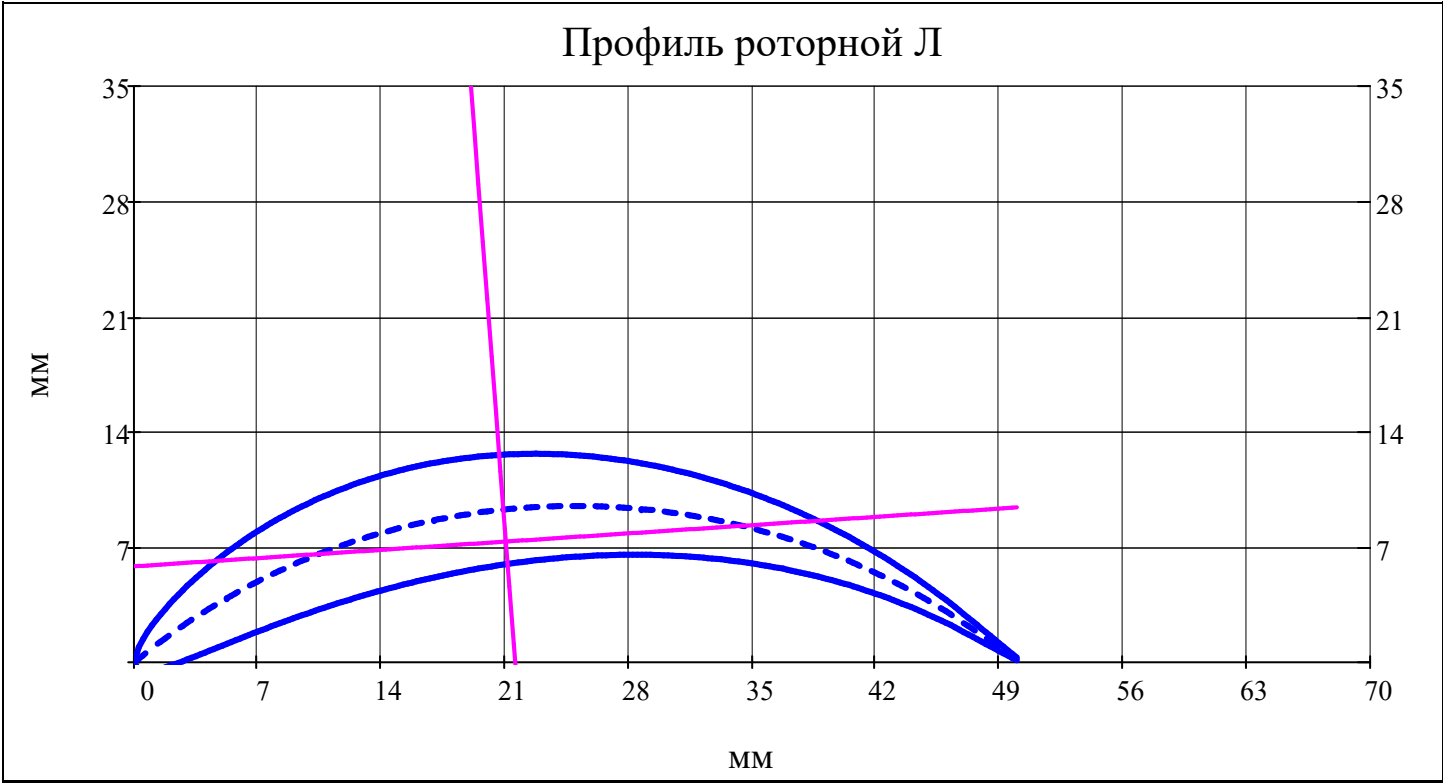
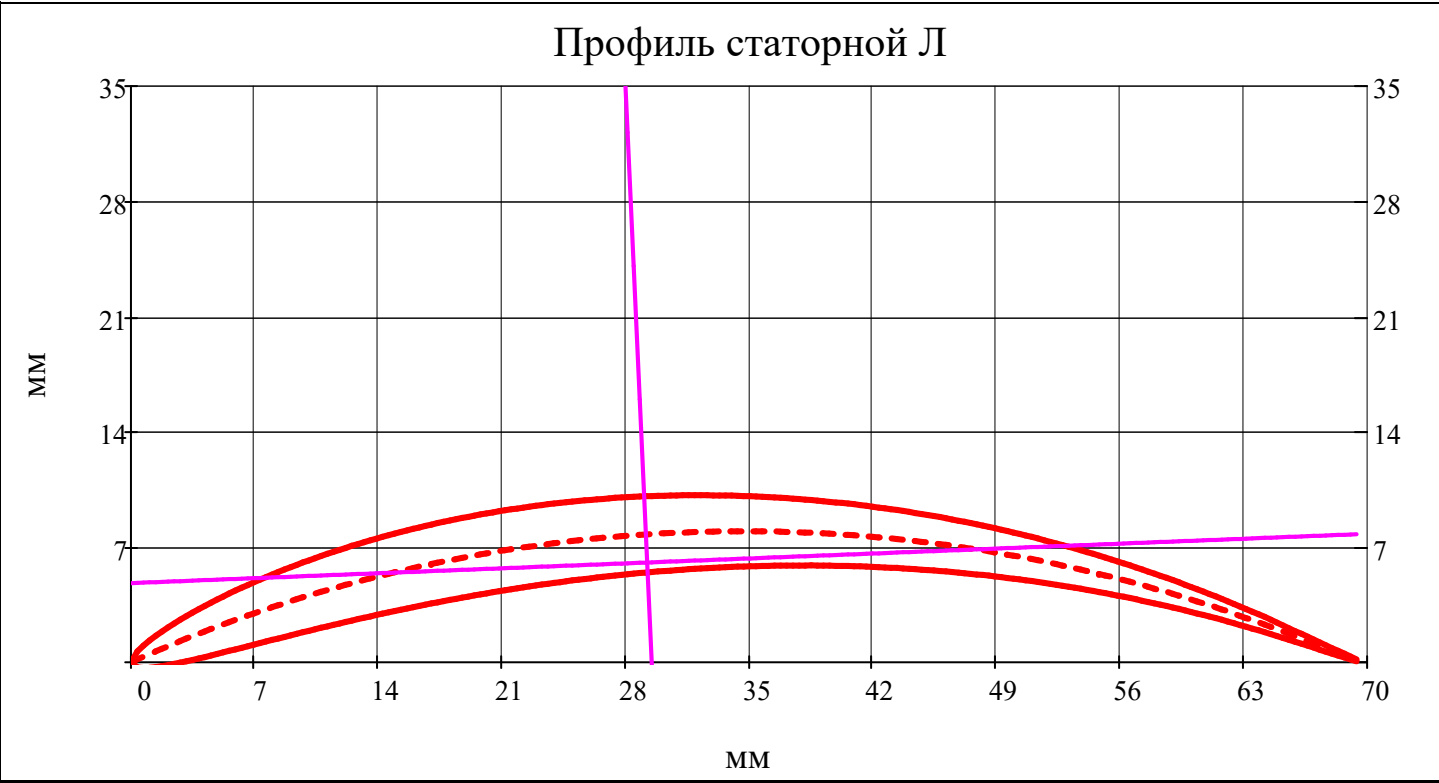
Построение профилей Л РК и НА

$$\text{AXLE0}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if type = "stator"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

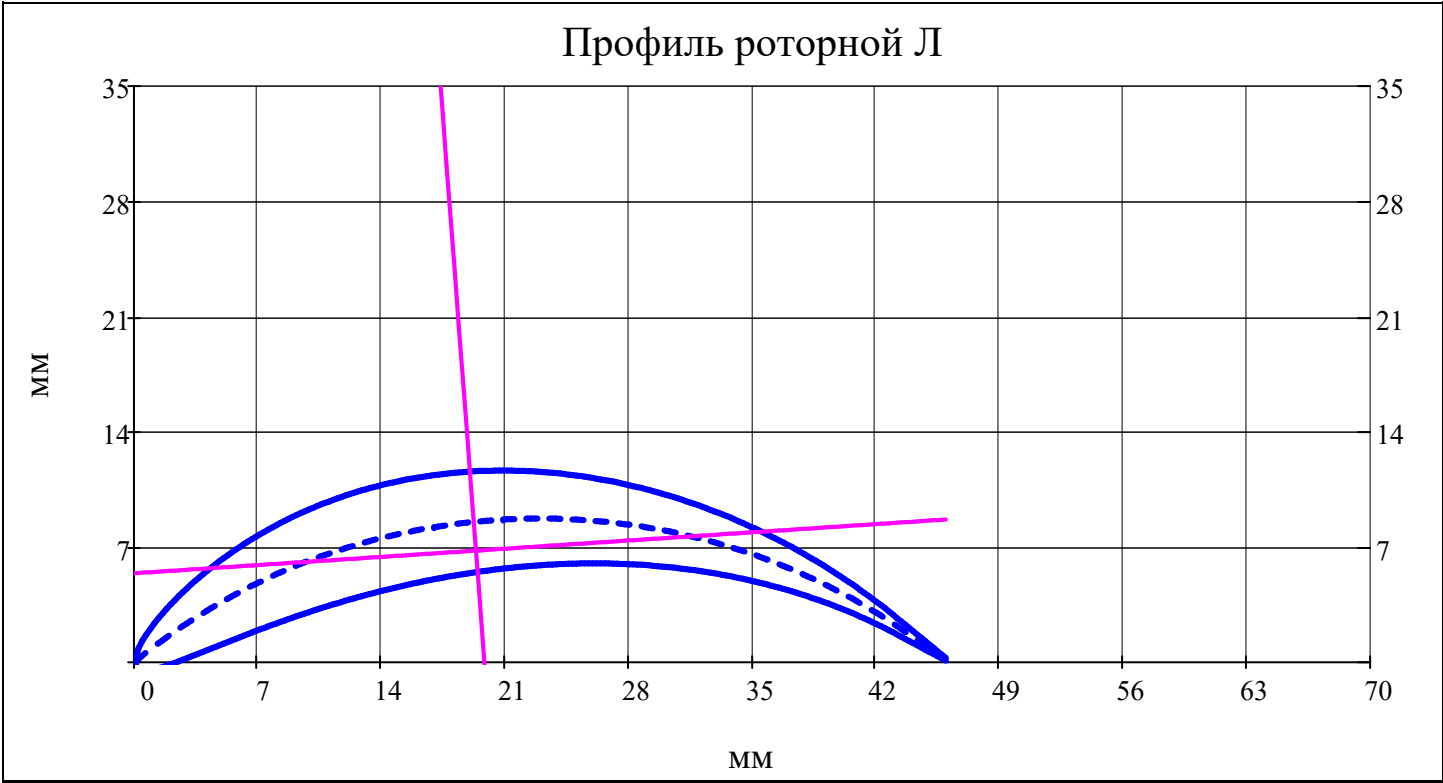
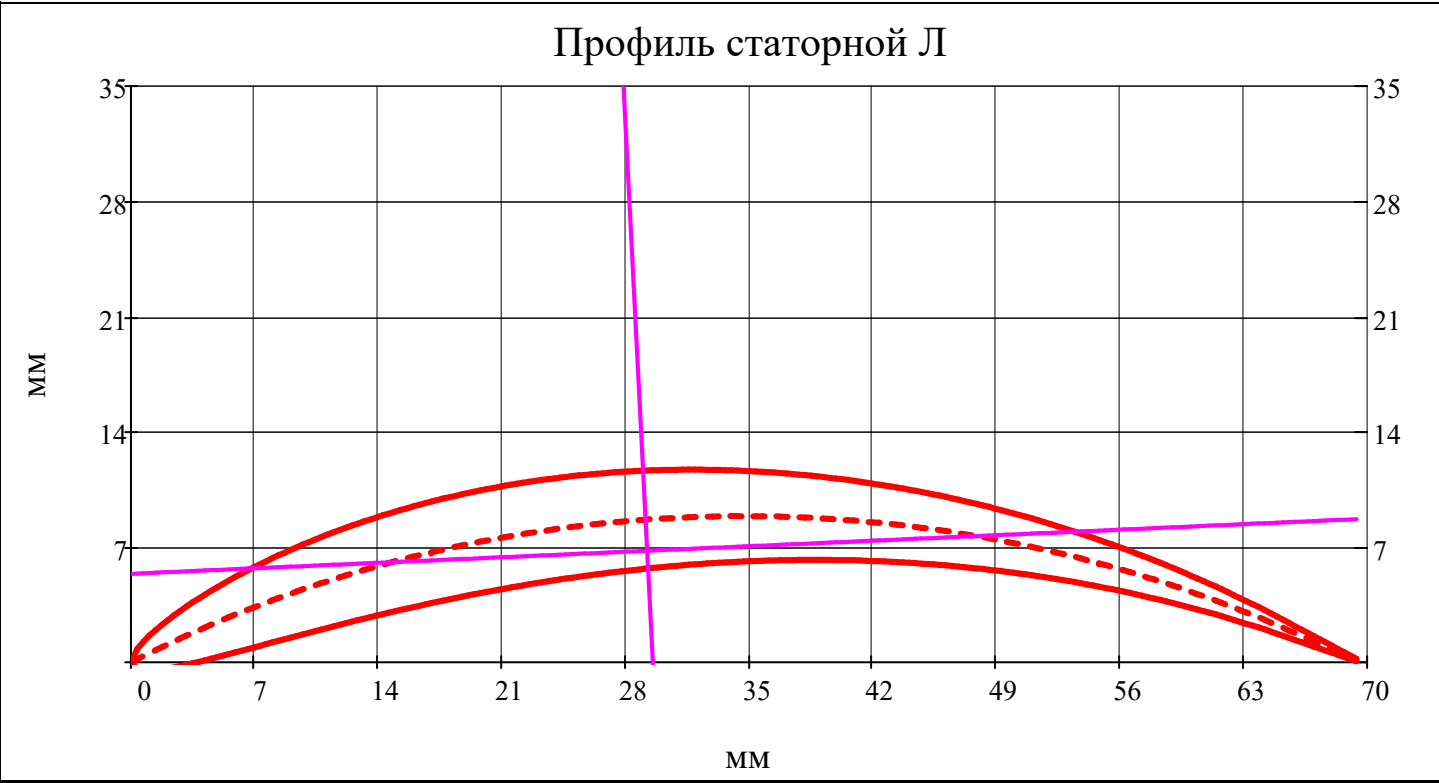
$$\text{AXLE90}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if (type = "rotor") } \wedge \left|\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right| \geq 1^\circ \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if (type = "stator") } \wedge \left|\alpha_{\text{major}_{\text{stator}_{i,r}}}\right| \geq 1^\circ \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$b_{\text{lim}} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

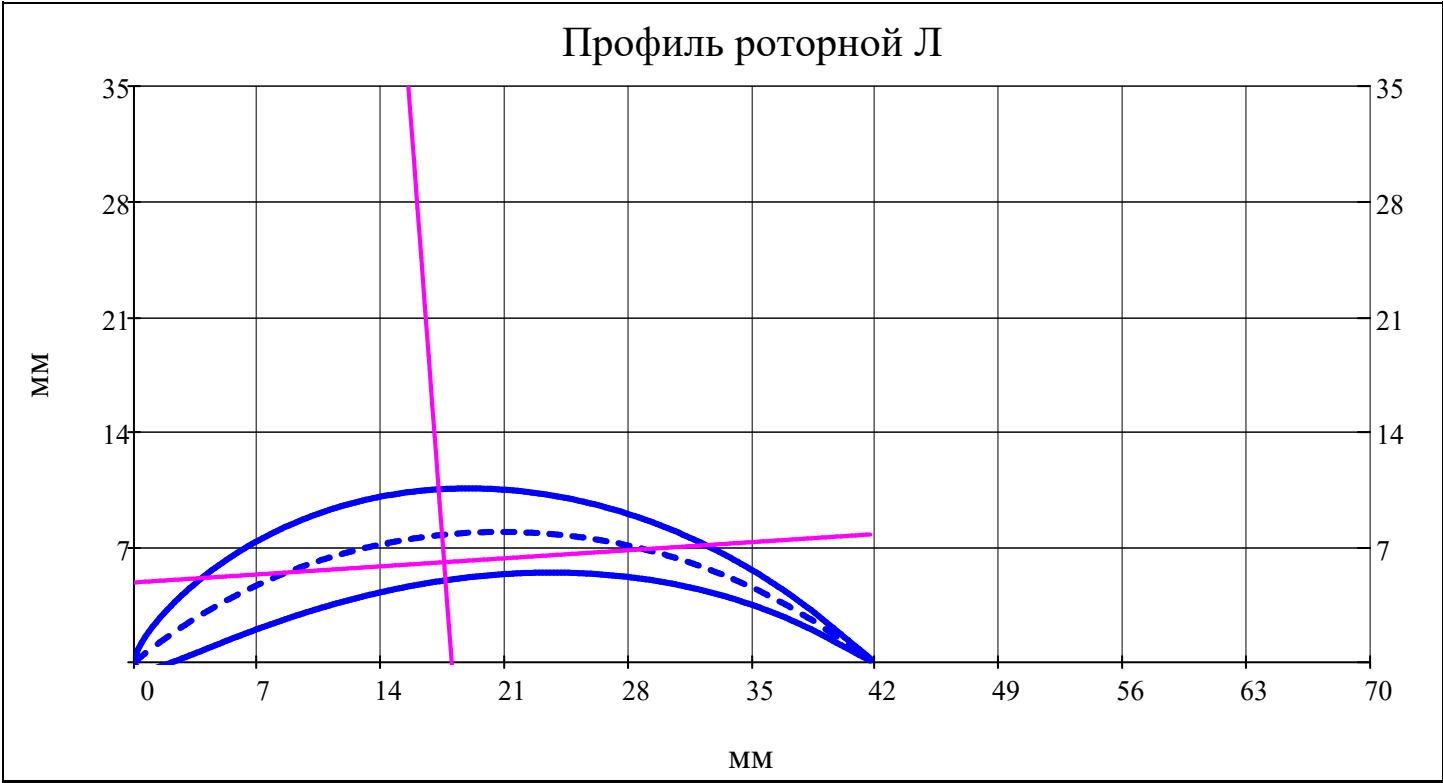
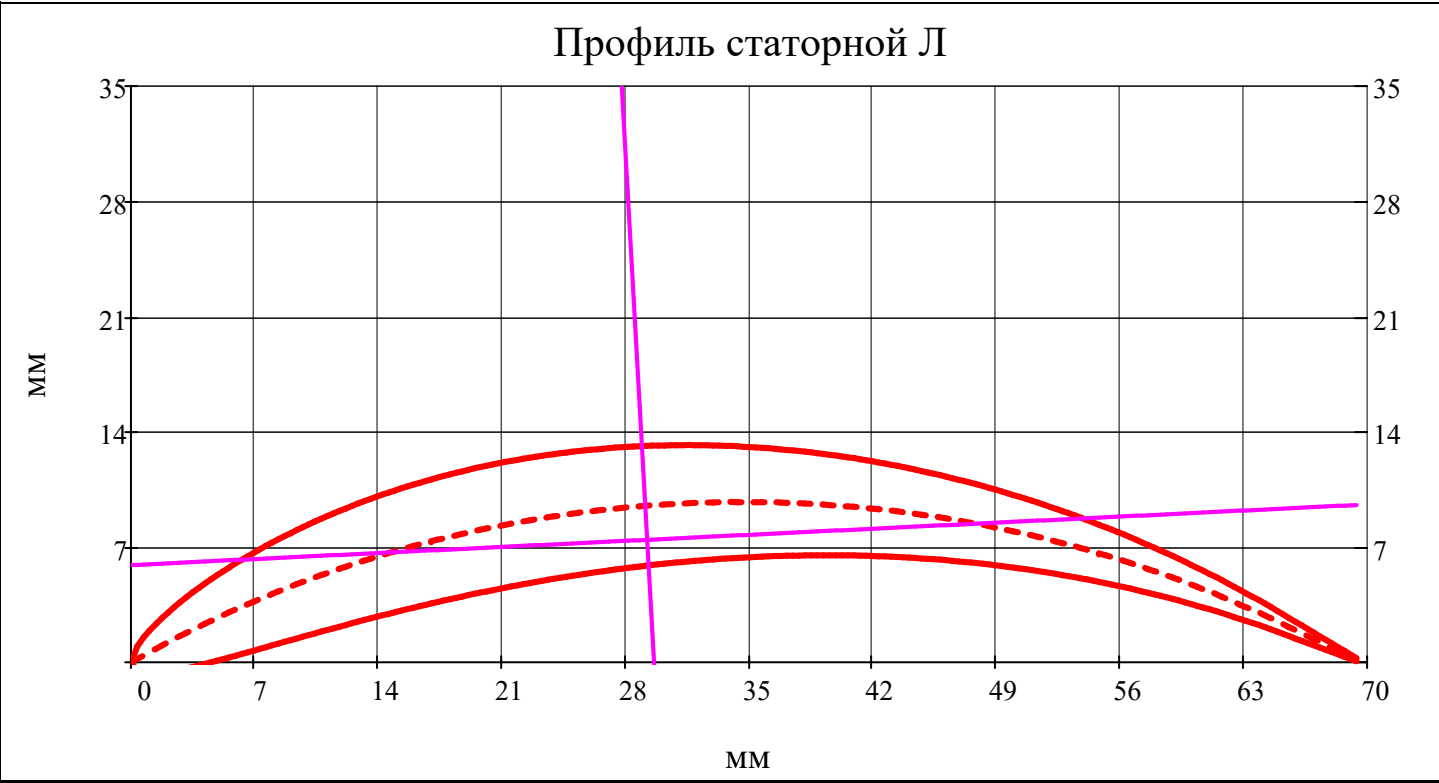
$r_w = 1$



$r_w = av(N_r)$



$r_w = N_r$





Вывод координат для построения профиля Л

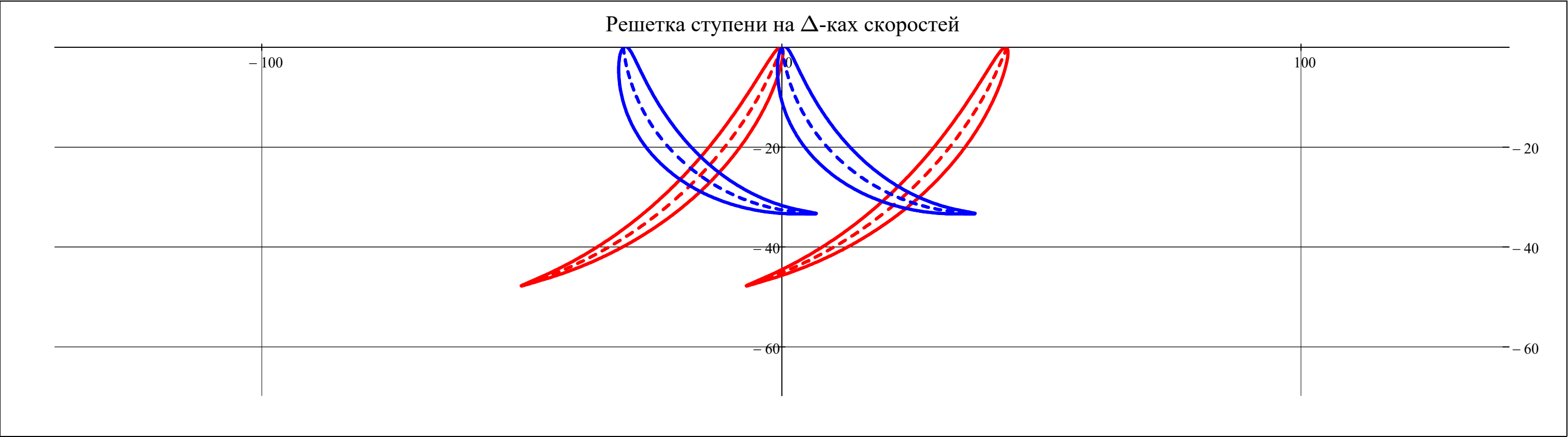
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 4$$

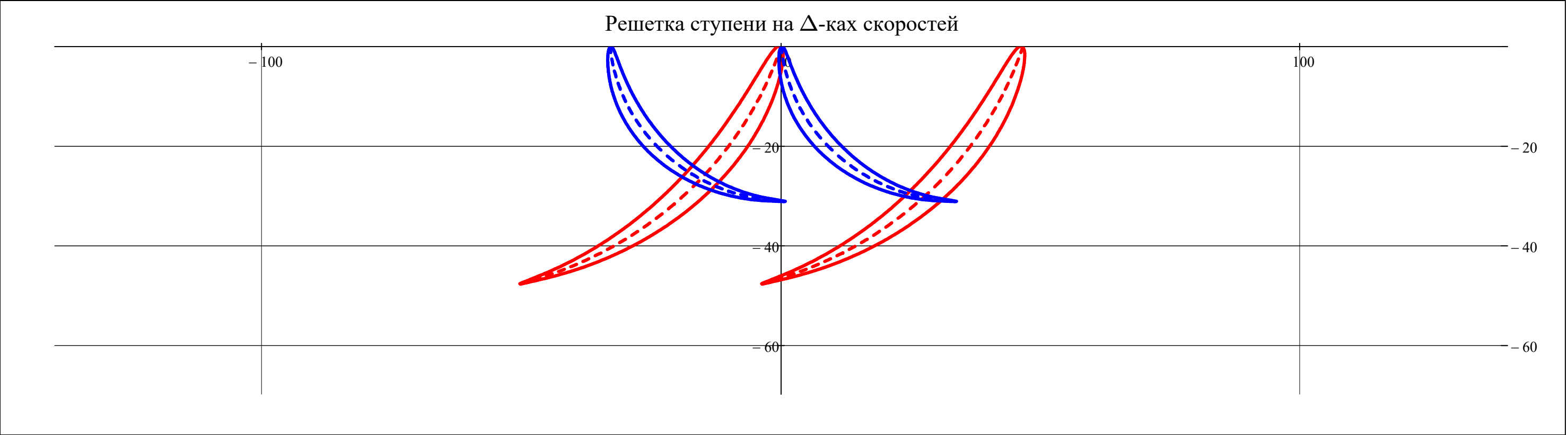
$$b_{lim} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j,N_r}}, \text{chord}_{\text{stator}_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Построение плоских решеток профилей Л на треугольниках скоростей

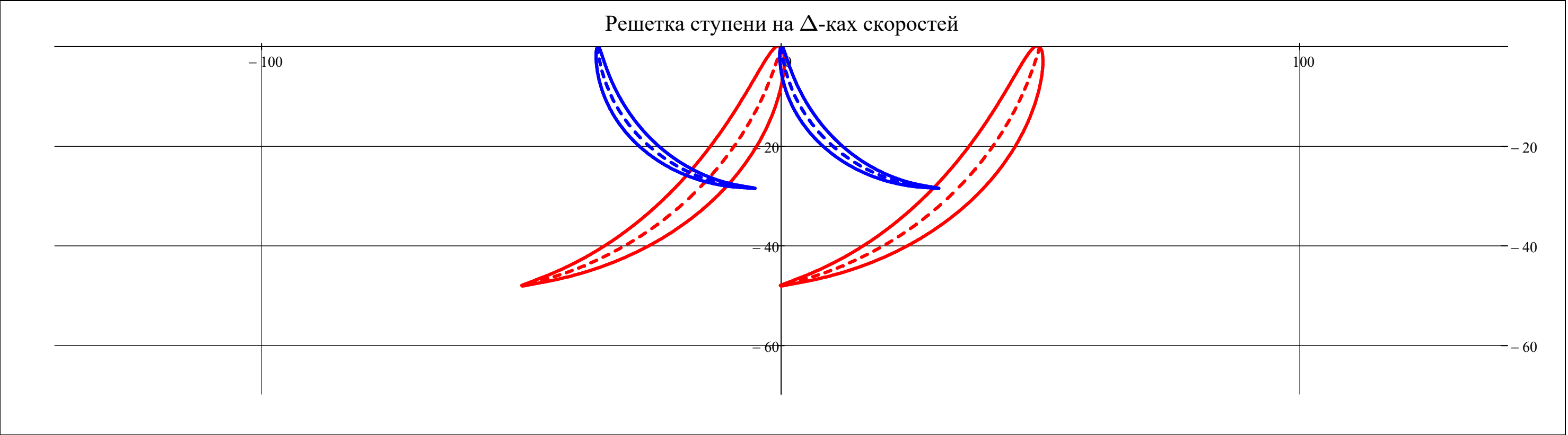
$$r_w = 1$$



$r_w = \text{av}(N_r)$



$r_w = N_r$



▲ Построение плоских решеток профилей Л на треугольниках скоростей

Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 4$$

▼ Поперечная часть ступени

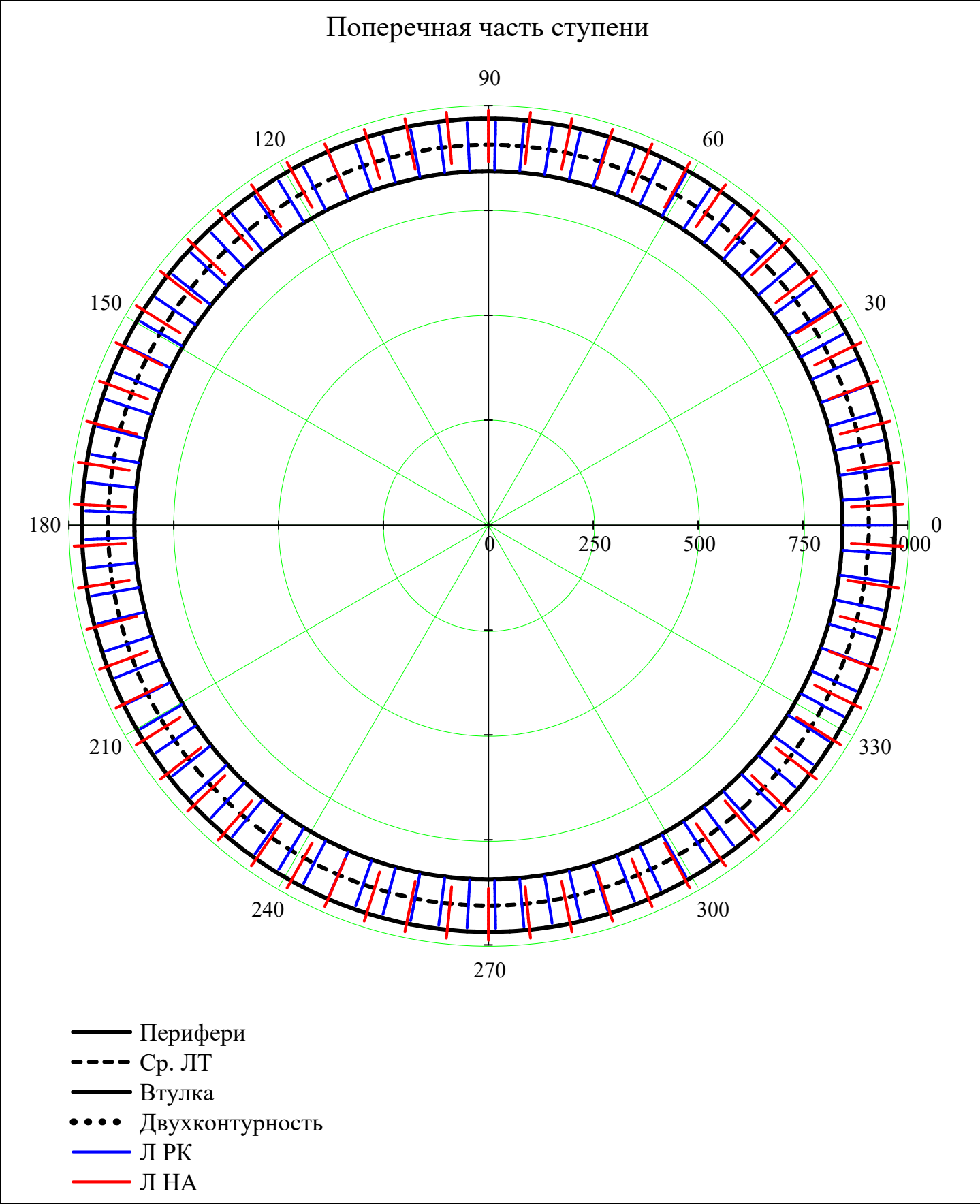
$$r_w = \min(D), \min(D) + \frac{\max(D) - \min(D)}{N_{\text{dis}}} \dots \max(D)$$

$$\begin{aligned} i_{\text{rotor}} &= 1 \dots Z_{\text{rotor}_j} \\ i_{\text{stator}} &= 1 \dots Z_{\text{stator}_j} \end{aligned}$$

$$\varphi = 0, \frac{2 \cdot \pi}{360} \dots 2 \cdot \pi$$

$$Л_{PK}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{rotor}_j}} & \text{if } D_{\text{st}(j,1)}, 1 < r < D_{\text{st}(j,1)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$Л_{HA}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{stator}_j}} & \text{if } D_{\text{st}(j,2)}, 1 < r < D_{\text{st}(j,2)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$



$$\begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix}$$

=

for i ∈ 1..Z

for r ∈ av(N_r)

for mode ∈ 1..6

$$\nu_{0\text{изГ.stator}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}\Big(\text{mode}, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{stator}_{i,r}}, J_{\text{u}_{\text{stator}_{i,r}}}\Big)$$

$$\nu_{0\text{изГ.rotor}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}\Big(\text{mode}, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{rotor}_{i,r}}, J_{\text{u}_{\text{rotor}_{i,r}}}\Big)$$

$$\nu_{0\text{угЛ.stator}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 0, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{\text{p}_{\text{stator}_{i,r}}}\Big)$$

$$\nu_{0\text{угЛ.rotor}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 0, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{\text{p}_{\text{rotor}_{i,r}}}\Big)$$

$$\nu_{0\text{угЛ.stator_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 1, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{\text{p}_{\text{stator}_{i,r}}}\Big)$$

$$\nu_{0\text{угЛ.rotor_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 1, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{\text{p}_{\text{rotor}_{i,r}}}\Big)$$

$$\begin{pmatrix} \nu_{0\text{изГ.stator}} & \nu_{0\text{изГ.rotor}} \\ \nu_{0\text{угЛ.stator}} & \nu_{0\text{угЛ.rotor}} \\ \nu_{0\text{угЛ.stator_bondage}} & \nu_{0\text{угЛ.rotor_bondage}} \end{pmatrix}$$

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\text{stack}\left(\nu_{0_{\text{изг.stator}}}, \nu_{0_{\text{изг.rotor}}}\right)^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|---|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 3263 | 1318 | 1559 | 1694 | 1618 | 1636 | 1616 | 1298 |
| 2 | 20449 | 8261 | 9769 | 10618 | 10139 | 10252 | 10130 | 8134 |
| 3 | 57262 | 23133 | 27357 | 29734 | 28391 | 28708 | 28368 | 22777 |
| 4 | 112296 | 45365 | 53649 | 58311 | 55677 | 56299 | 55632 | 44667 |
| 5 | 185556 | 74961 | 88649 | 96353 | 92001 | 93028 | 91925 | 73807 |
| 6 | 277118 | 111950 | 132392 | 143897 | 137398 | 138932 | 137285 | 110226 |

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\text{stack}\left(\nu_{0_{\text{угл.stator}}}, \nu_{0_{\text{угл.rotor}}}\right)^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 3125 | 2608 | 2392 | 2193 | 2761 | 2440 | 2268 | 2039 |
| 2 | 9376 | 7823 | 7177 | 6578 | 8284 | 7319 | 6803 | 6118 |
| 3 | 15626 | 13038 | 11962 | 10963 | 13806 | 12199 | 11339 | 10197 |
| 4 | 21877 | 18253 | 16747 | 15348 | 19329 | 17078 | 15875 | 14275 |
| 5 | 28128 | 23468 | 21532 | 19733 | 24851 | 21958 | 20410 | 18354 |
| 6 | 34378 | 28683 | 26317 | 24118 | 30374 | 26838 | 24946 | 22433 |

$$\text{stack}\left(\nu_{0_{\text{угл.stator_bondage}}}, \nu_{0_{\text{угл.rotor_bondage}}}\right)^T =$$

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|---|-------|-------|-------|-------|-------|-------|-------|-------|
| 1 | 6251 | 5215 | 4785 | 4385 | 5523 | 4880 | 4536 | 4079 |
| 2 | 12501 | 10430 | 9570 | 8770 | 11045 | 9759 | 9071 | 8157 |
| 3 | 18752 | 15645 | 14355 | 13155 | 16568 | 14639 | 13607 | 12236 |
| 4 | 25002 | 20860 | 19140 | 17540 | 22090 | 19518 | 18143 | 16315 |
| 5 | 31253 | 26076 | 23924 | 21925 | 27613 | 24398 | 22678 | 20394 |
| 6 | 37503 | 31291 | 28709 | 26310 | 33135 | 29277 | 27214 | 24472 |

Расчетный узел: type = "turbine"

Объем бандажной полки (м³): $V_{\text{бп}} = 0$

Радиус положения ЦМ бандажной полки (м): $R_{\text{бп}} = 0$

$$\text{neutral_line}(\text{type},\text{x},\text{i},\text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{rotor}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right)\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}}\right) \text{ if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{stator}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right)\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}}\right) \text{ if type = "stator"} \end{array} \right.$$

$$\text{epure}(\text{type},\text{x},\text{i},\text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{rotor}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right) - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}}\right) \text{ if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{stator}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right) - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}}\right) \text{ if type = "stator"} \end{array} \right.$$

Наиболее удаленные точки от НЛ (мм):

$$u_{-u_{\text{rotor}}}^T =$$

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | -1.160 | -1.024 | -0.986 | -1.003 |
| 2 | 0.261 | 0.336 | 0.342 | -0.616 |
| 3 | 0.241 | 0.281 | 0.268 | 0.223 |

$$\cdot 10^{-3}$$

$$u_{-l_{\text{rotor}}}^T =$$

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 28.375 | 28.028 | 27.933 | 28.008 |
| 2 | 25.969 | 25.738 | 25.725 | 25.849 |
| 3 | 23.420 | 23.278 | 23.334 | 23.497 |

$$\cdot 10^{-3}$$

$$u_{-u_{\text{stator}}}^T =$$

| | | | | |
|---|---------|---------|---------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | -6.048 | 18.972 | 16.627 | 15.685 |
| 2 | 14.809 | 34.565 | 38.064 | 22.591 |
| 3 | -11.210 | -18.804 | -18.046 | 37.611 |

$$\cdot 10^{-3}$$

$$u_{-l_{\text{stator}}}^T =$$

| | | | | |
|---|--------|---------|---------|---------|
| | 1 | 2 | 3 | 4 |
| 1 | -9.648 | -27.201 | -27.296 | -26.659 |
| 2 | 2.702 | -20.244 | -22.418 | -24.751 |
| 3 | 34.492 | 34.701 | 10.465 | -19.527 |

$$\cdot 10^{-3}$$

$$v_{-u_{\text{rotor}}}^T =$$

| | | | | |
|---|-------|-------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 4.927 | 5.365 | 5.441 | 5.299 |
| 2 | 3.698 | 3.973 | 3.956 | 3.765 |
| 3 | 3.189 | 3.344 | 3.240 | 3.002 |

$$\cdot 10^{-3}$$

$$v_{-l_{\text{rotor}}}^T =$$

| | | | | |
|---|--------|---------|---------|---------|
| | 1 | 2 | 3 | 4 |
| 1 | -7.980 | -10.413 | -10.906 | -10.223 |
| 2 | -8.576 | -10.135 | -10.108 | -9.138 |
| 3 | -8.916 | -9.837 | -9.322 | -8.081 |

$$\cdot 10^{-3}$$

$$v_{-u_{\text{stator}}}^T =$$

| | | | | |
|---|--------|--------|--------|--------|
| | 1 | 2 | 3 | 4 |
| 1 | 29.582 | 4.200 | 5.221 | 6.027 |
| 2 | 38.137 | 20.800 | 13.898 | 8.774 |
| 3 | 7.817 | 9.146 | 23.918 | 15.820 |

$$\cdot 10^{-3}$$

$$v_{-l_{\text{stator}}}^T =$$

| | | | | |
|---|---------|---------|---------|---------|
| | 1 | 2 | 3 | 4 |
| 1 | -39.707 | -6.703 | -9.605 | -12.000 |
| 2 | -30.181 | -20.609 | -18.668 | -15.935 |
| 3 | -22.276 | -20.913 | -39.336 | -22.312 |

$$\cdot 10^{-3}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \sigma_{\text{p_rotor}_{i,r}} & \sigma_{\text{n_rotor}_{i,r}} \\ \sigma_{\text{p_stator}_{i,r}} & \sigma_{\text{n_stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_u}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_u}_{\text{rotor}_{i,r}} & \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_l}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_l}_{\text{rotor}_{i,r}} \\ \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_u}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_u}_{\text{stator}_{i,r}} & \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_l}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_l}_{\text{stator}_{i,r}} \end{pmatrix} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} \end{array}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \sigma_{\text{p_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{p_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T, z\right) \end{array} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} \end{array}$$

$$\sigma_{\text{p_rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & -49.58 & -38.69 & -24.96 & -15.94 \\ \hline 2 & -31.38 & -25.94 & -16.28 & -8.77 \\ \hline 3 & -4.79 & -6.12 & -2.55 & -0.07 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p_rotor}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n_rotor}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 86.83 & 79.81 & 53.31 & 33.39 \\ \hline 2 & 76.42 & 69.01 & 43.71 & 22.64 \\ \hline 3 & 13.77 & 18.44 & 7.63 & 0.20 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n_rotor}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0 & 0 & 1 & 1 \\ \hline 2 & 0 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{p_stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & 1.03 & 0.58 & 0.05 \\ \hline 2 & 1.78 & 12.03 & 7.28 & 2.32 \\ \hline 3 & -10.85 & -20.23 & -8.47 & 8.70 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{p_stator}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\sigma_{\text{n_stator}}^T = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 0.00 & -1.58 & -1.01 & -0.10 \\ \hline 2 & -0.09 & -9.17 & -6.42 & -3.38 \\ \hline 3 & 31.68 & 42.27 & 8.54 & -7.36 \\ \hline \end{array} \cdot 10^6$$

$$\sigma_{\text{n_stator}}^T \leq 70 \cdot 10^6 = \begin{array}{|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 \\ \hline 1 & 1 & 1 & 1 & 1 \\ \hline 2 & 1 & 1 & 1 & 1 \\ \hline 3 & 1 & 1 & 1 & 1 \\ \hline \end{array}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \sigma_{\text{rotor}_{i,r}} &= \sqrt{\left(\sigma_{\text{Zrotor}}(i, R_{\text{st}}(i, 2), r) + \max(\sigma_{\text{Protor}_{i,r}}, \sigma_{\text{nrotor}_{i,r}})\right)^2 + \tau_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)^2} \\ \sigma_{\text{stator}_{i,r}} &= \sqrt{\left(0 + \max(\sigma_{\text{Pstator}_{i,r}}, \sigma_{\text{nstator}_{i,r}})\right)^2 + \tau_{\text{stator}}(i, R_{\text{st}}(i, 2), r)^2} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \left| \begin{aligned} \sigma_{\text{rotor.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{stator.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix}$$

| | | | | |
|---|--------|--------|-------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 113.20 | 114.67 | 95.63 | 80.56 |
| 2 | 97.50 | 97.27 | 77.14 | 56.67 |
| 3 | 22.50 | 32.20 | 20.77 | 3.32 |

.10⁶

| | | | | |
|---|-------|-------|------|------|
| | 1 | 2 | 3 | 4 |
| 1 | 0.00 | 1.09 | 0.70 | 0.16 |
| 2 | 2.67 | 12.08 | 7.36 | 2.47 |
| 3 | 31.86 | 42.31 | 8.71 | 8.81 |

.10⁶

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \text{safety}_{\text{rotor}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}i}}{\sigma_{\text{rotor}_{i,r}}} & \text{if } \sigma_{\text{rotor}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \\ \text{safety}_{\text{stator}_{i,r}} &= \begin{cases} \frac{\sigma_{\text{blade_long}i}}{\sigma_{\text{stator}_{i,r}}} & \text{if } \sigma_{\text{stator}_{i,r}} \neq 0 \\ \infty & \text{otherwise} \end{cases} \end{aligned} \right. \end{cases}$$

$$\begin{pmatrix} \text{safety}_{\text{rotor}} \\ \text{safety}_{\text{stator}} \end{pmatrix}$$

safety_{rotor}^T =

| | | | | |
|---|------|------|------|-------|
| | 1 | 2 | 3 | 4 |
| 1 | 1.06 | 1.05 | 1.25 | 1.49 |
| 2 | 1.23 | 1.23 | 1.56 | 2.12 |
| 3 | 5.33 | 3.73 | 5.78 | 36.17 |

safety_{stator}^T =

| | | |
|---|----------------------------------|---|
| | 1 | 2 |
| 1 | 00000000000000000000000000000000 | |
| 2 | 44.88 | |
| 3 | 3.77 | |

safety_{rotor}^T ≥ safety =

| | | | | |
|---|---|---|---|---|
| | 1 | 2 | 3 | 4 |
| 1 | 0 | 0 | 0 | 1 |
| 2 | 0 | 0 | 1 | 1 |
| 3 | 1 | 1 | 1 | 1 |

safety_{stator}^T ≥ safety =

| | | | | |
|---|---|---|---|---|
| | 1 | 2 | 3 | 4 |
| 1 | 1 | 1 | 1 | 1 |
| 2 | 1 | 1 | 1 | 1 |
| 3 | 1 | 1 | 1 | 1 |

Рассматриваемая ступень:

$$j_w = \left\{ \begin{array}{l} j = \left\{ \begin{array}{l} 1 \text{ if type = "compressor"} \\ Z \text{ if type = "turbine"} \end{array} \right. \\ j = \left\{ \begin{array}{l} \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j \text{ otherwise} \end{array} \right. \end{array} \right. = 4$$

$$b_{lim} = \frac{ceil\left(\max\left(chord_{rotor_{j,N_r}}, chord_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 70.0 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

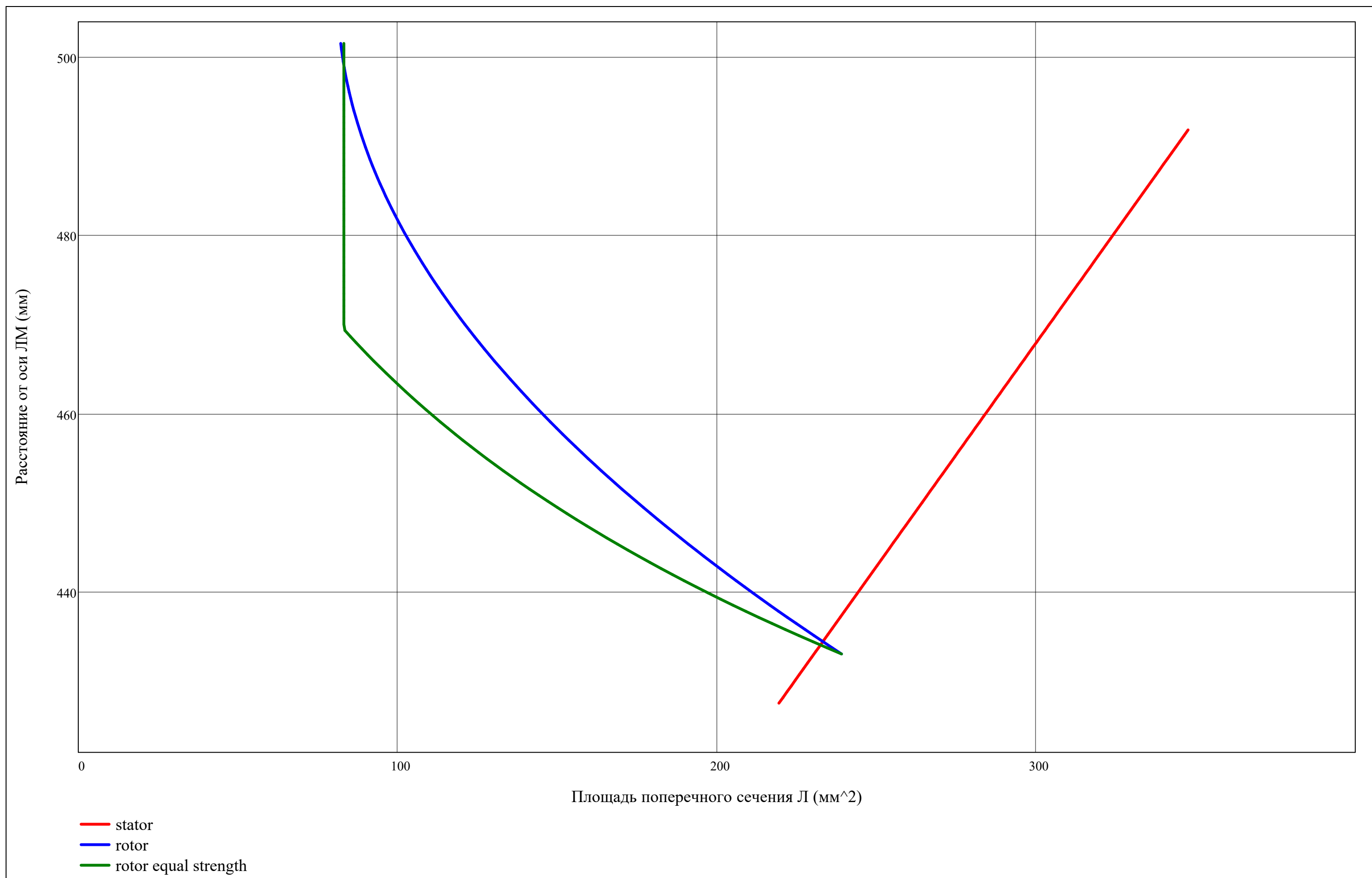
$$R_j = \text{submatrix}\left(R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 422.0 & 453.2 & 484.5 \\ 2 & 433.0 & 466.0 & 499.1 \\ 3 & 433.0 & 468.5 & 503.9 \\ \hline \end{array} \cdot 10^{-3}$$

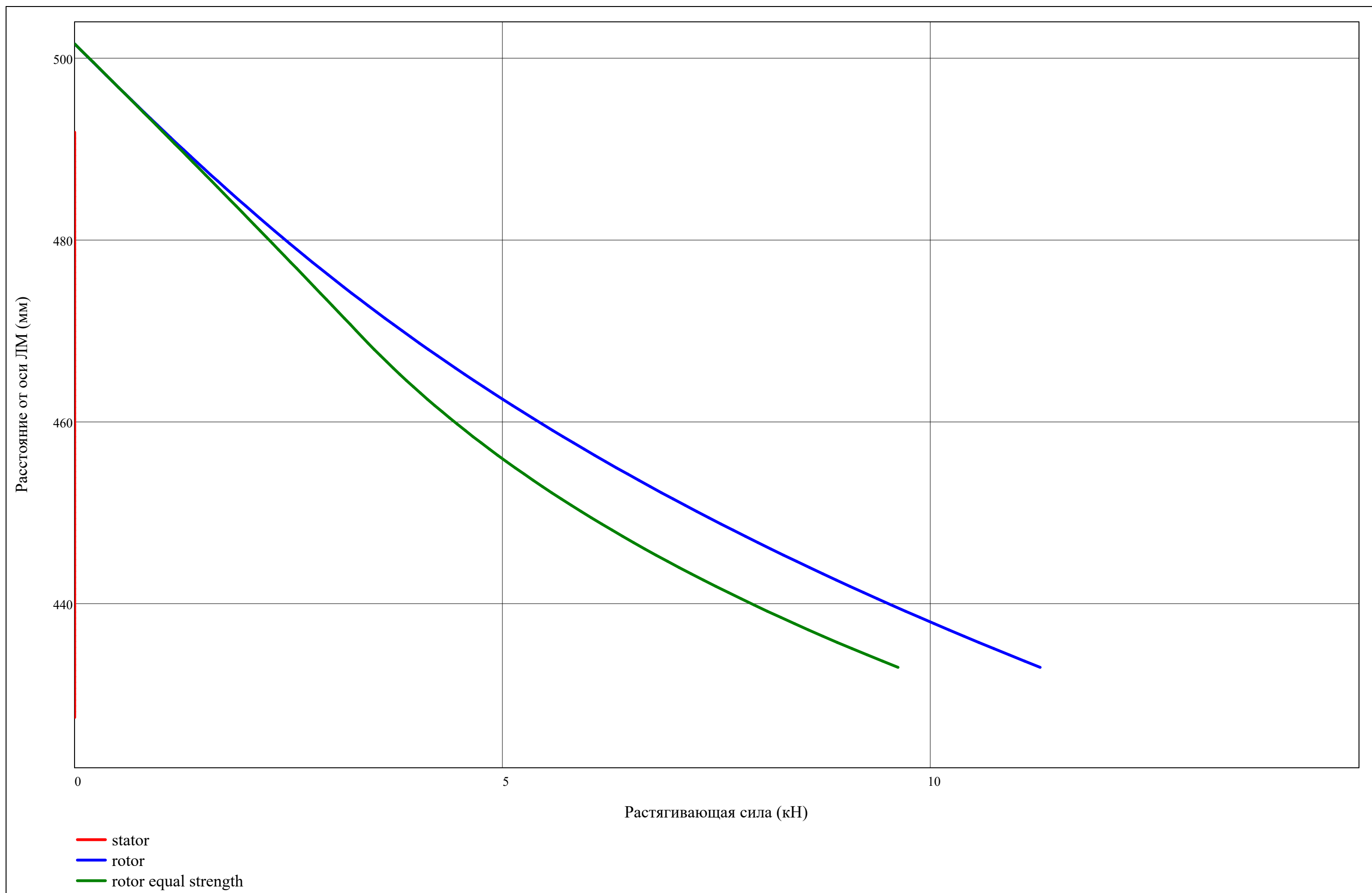
Дискретизация по высоте Л:

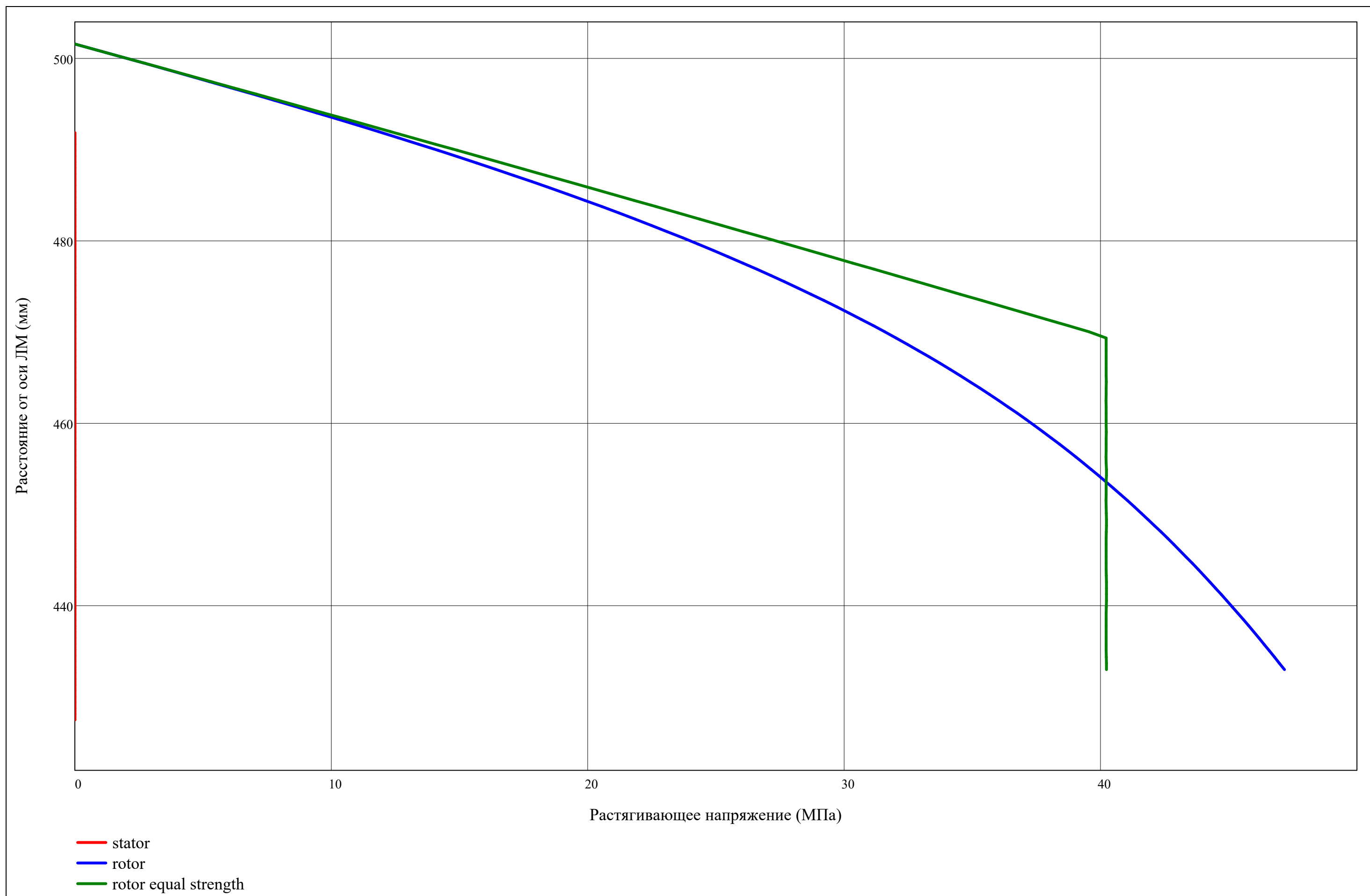
$$z = \min(R_j), \min(R_j) + \frac{\max(R_j) - \min(R_j)}{100} .. \max(R_j)$$

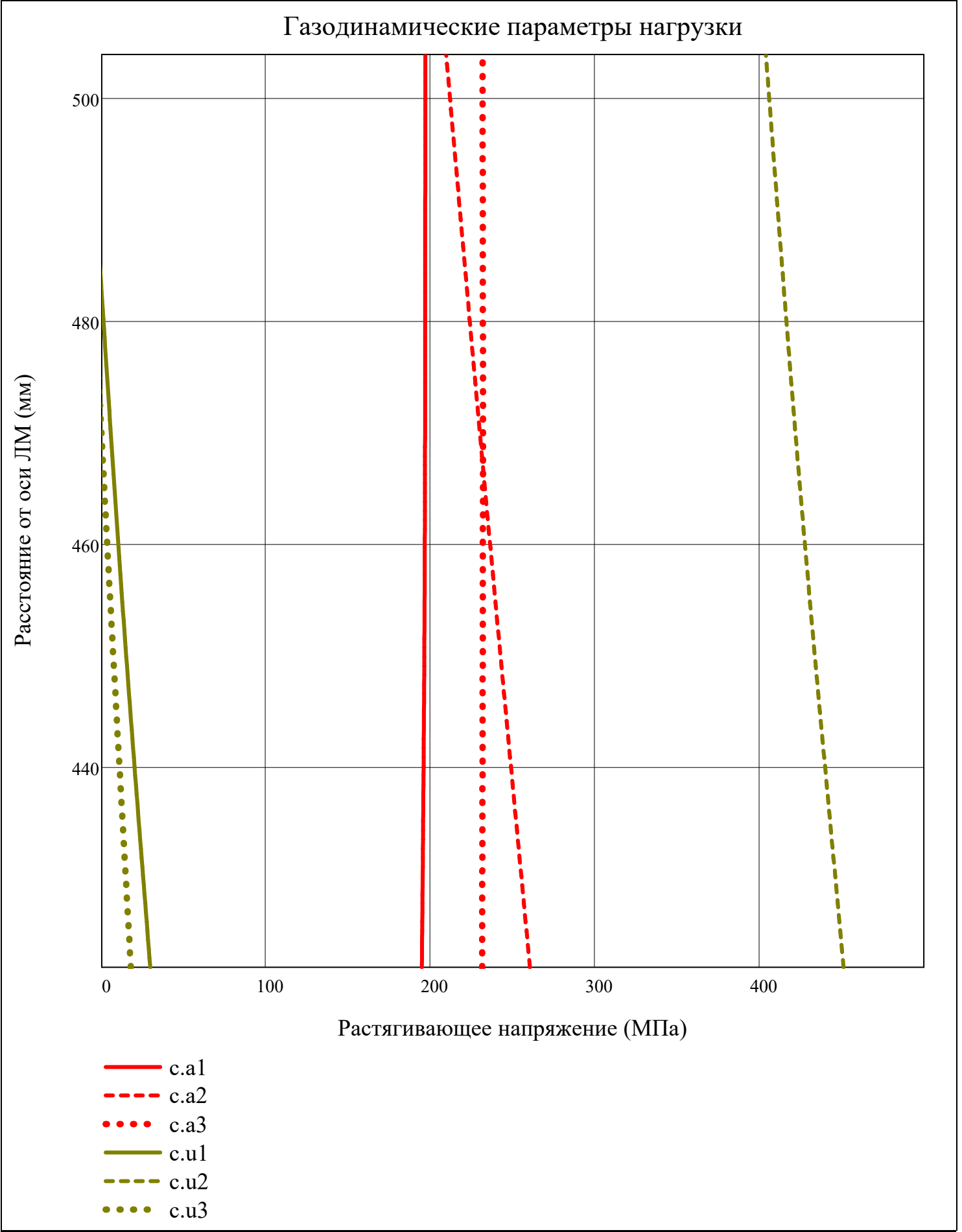
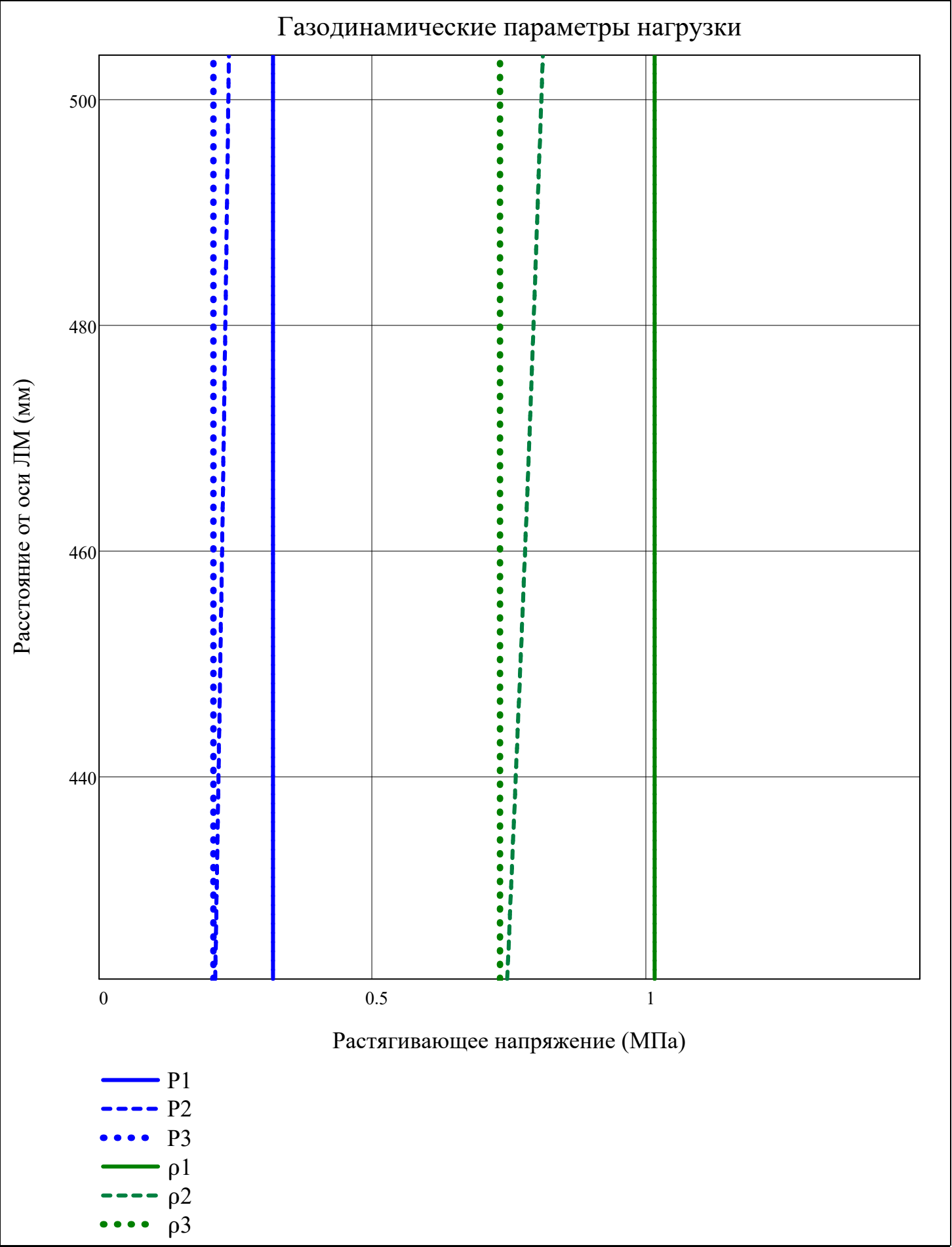
$$z_{rotor} = \left\{ \begin{array}{l} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \text{ if type = "compressor"} \\ \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \text{ if type = "turbine"} \end{array} \right.$$

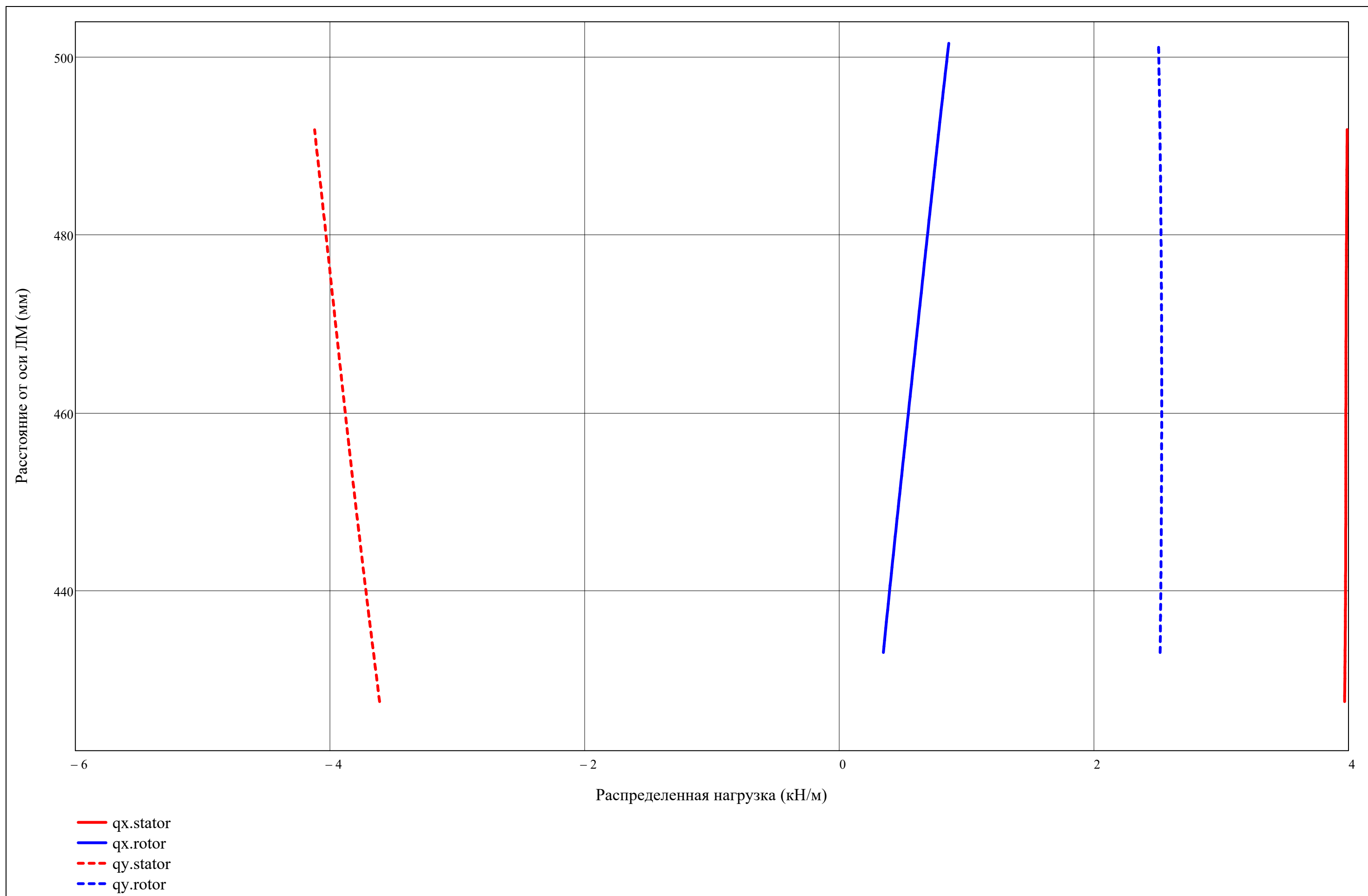
$$z_{stator} = \left\{ \begin{array}{l} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \text{ if type = "compressor"} \\ \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \text{ if type = "turbine"} \end{array} \right.$$

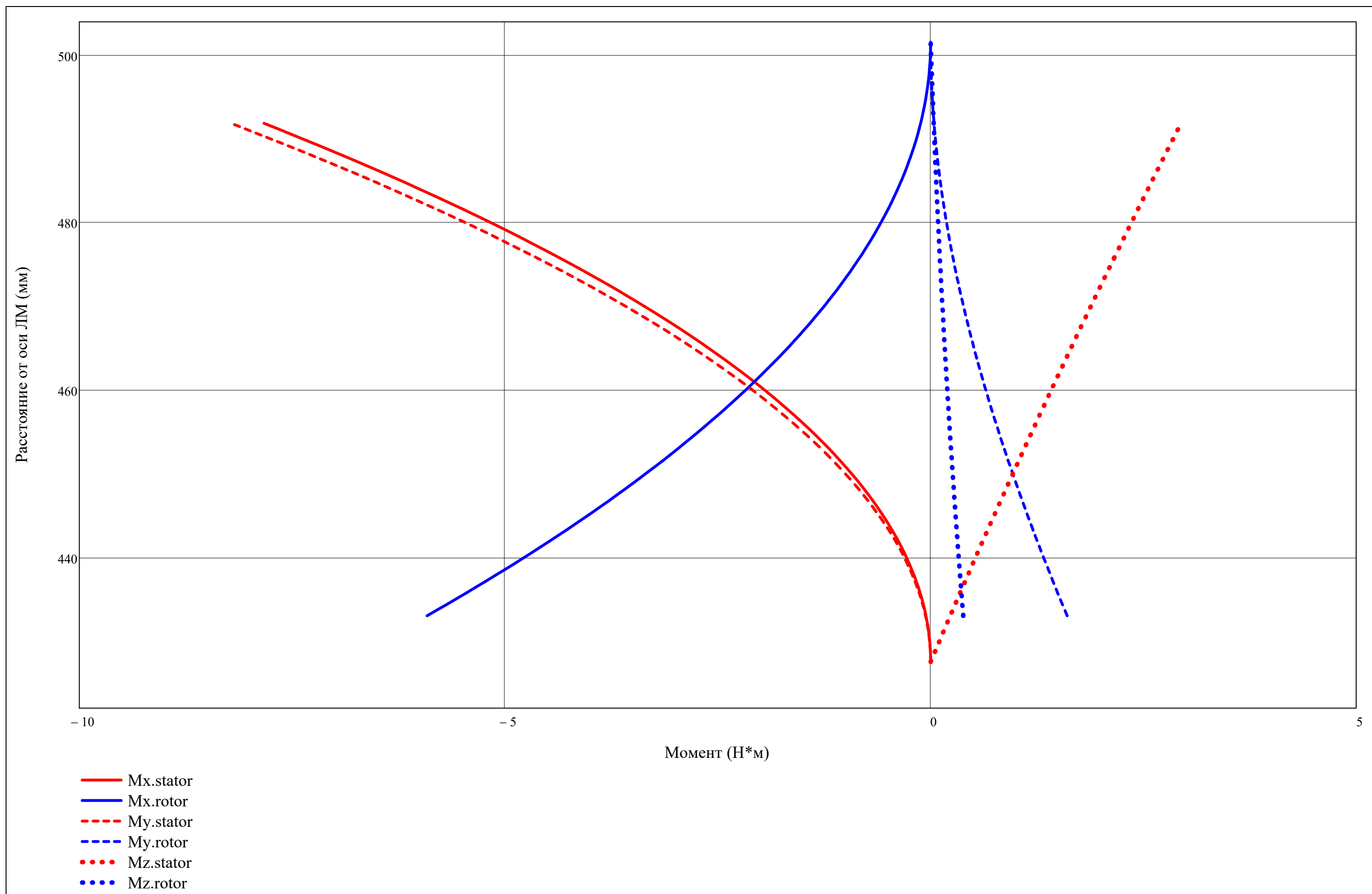


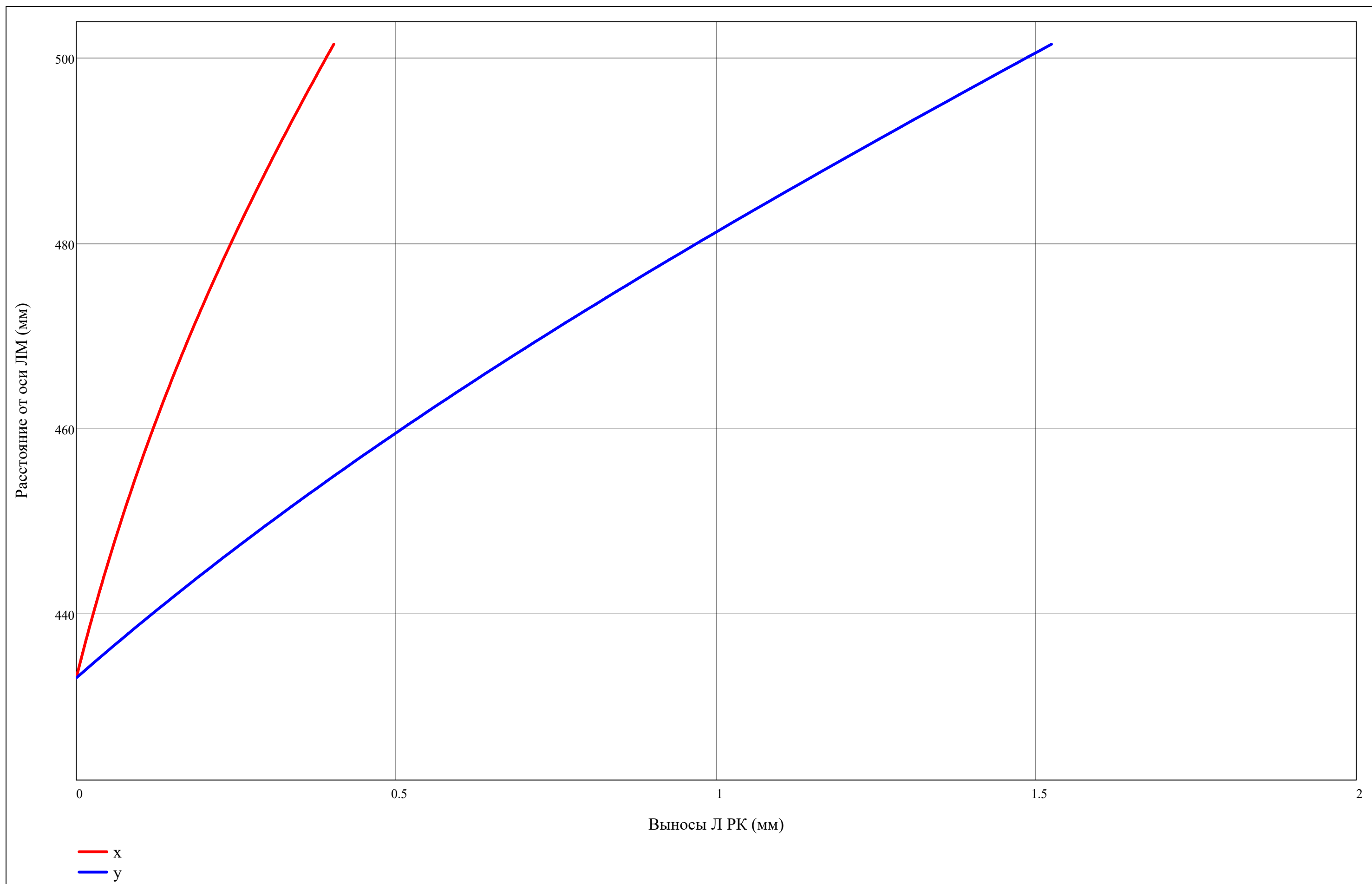


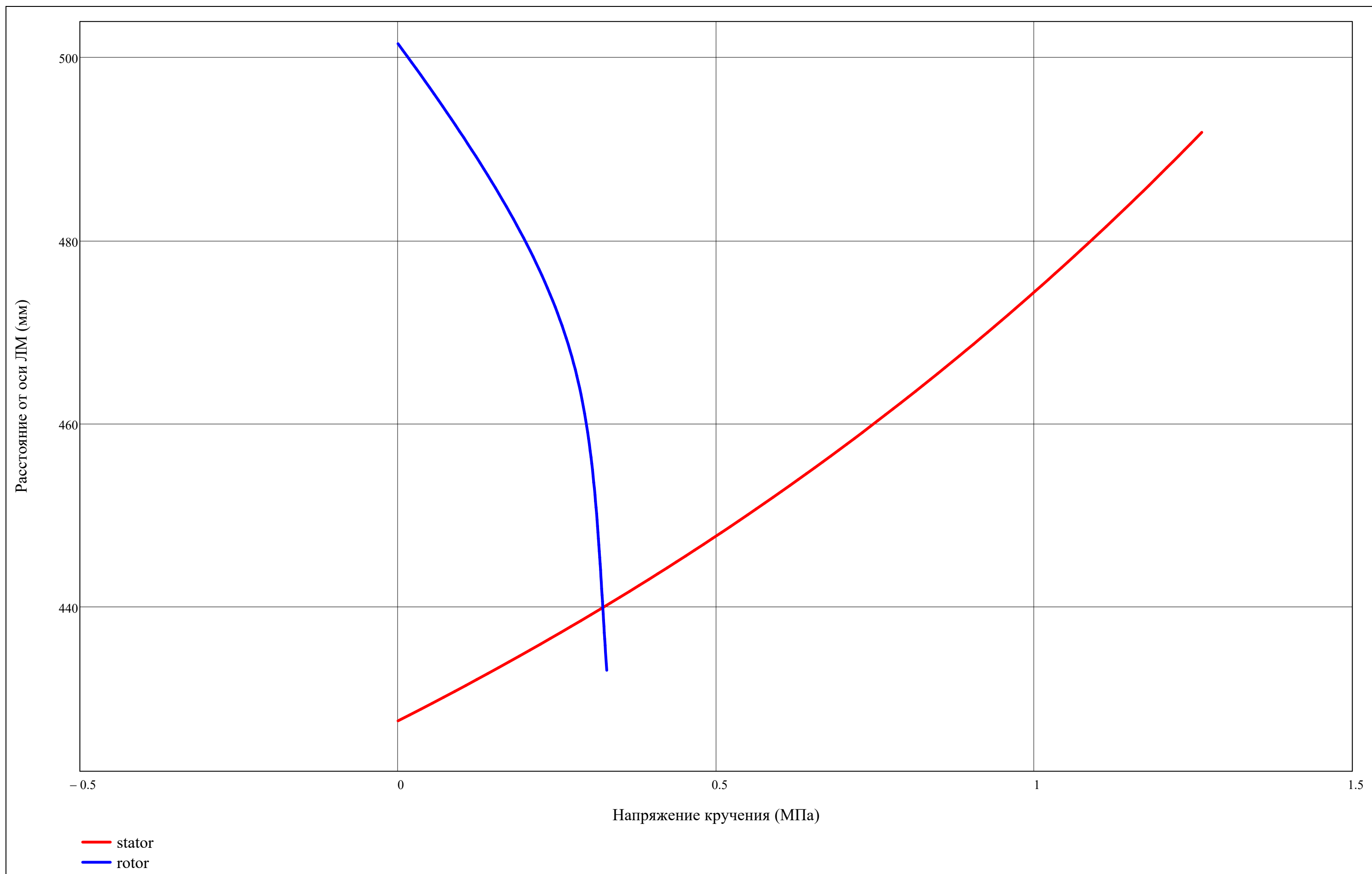


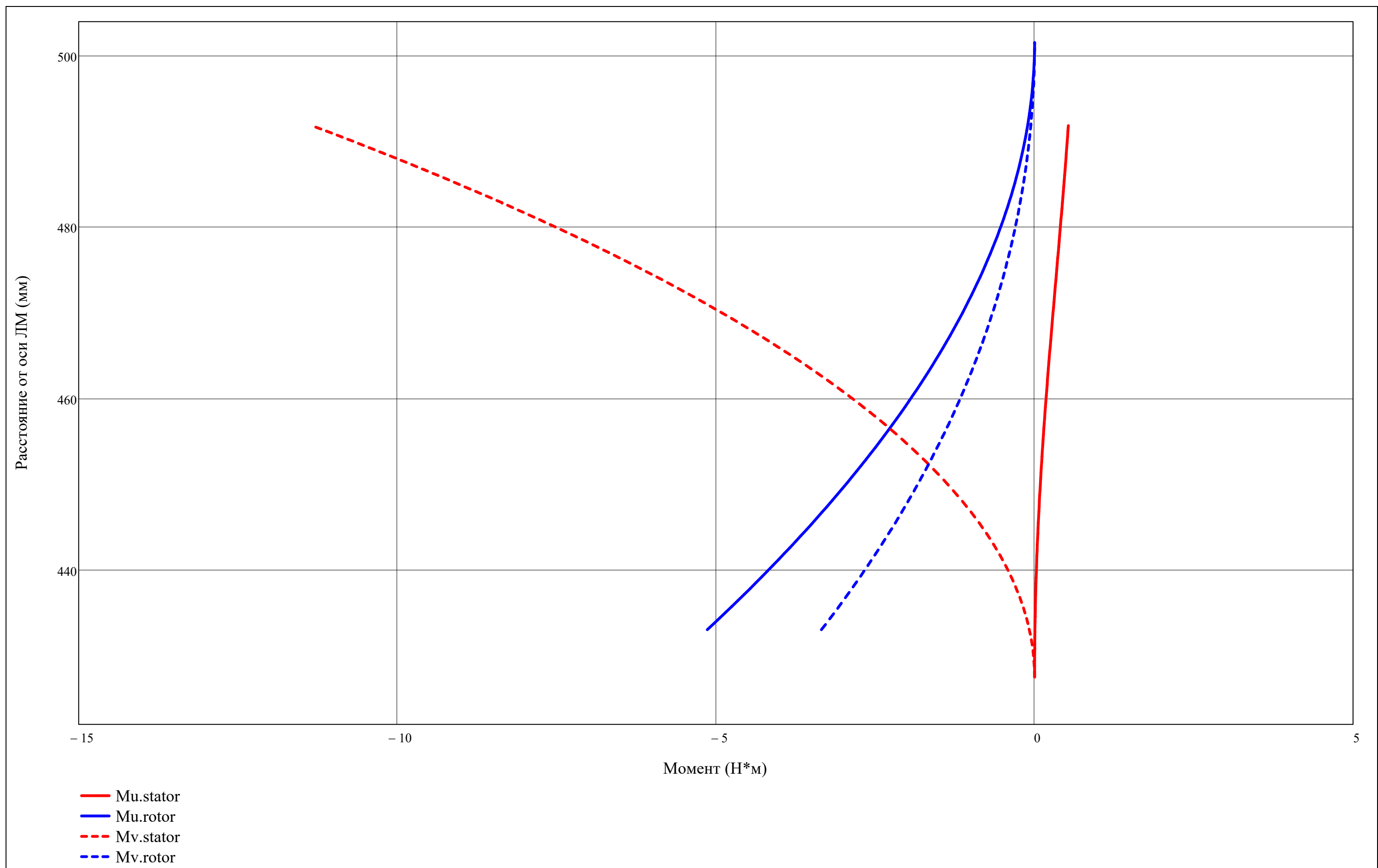


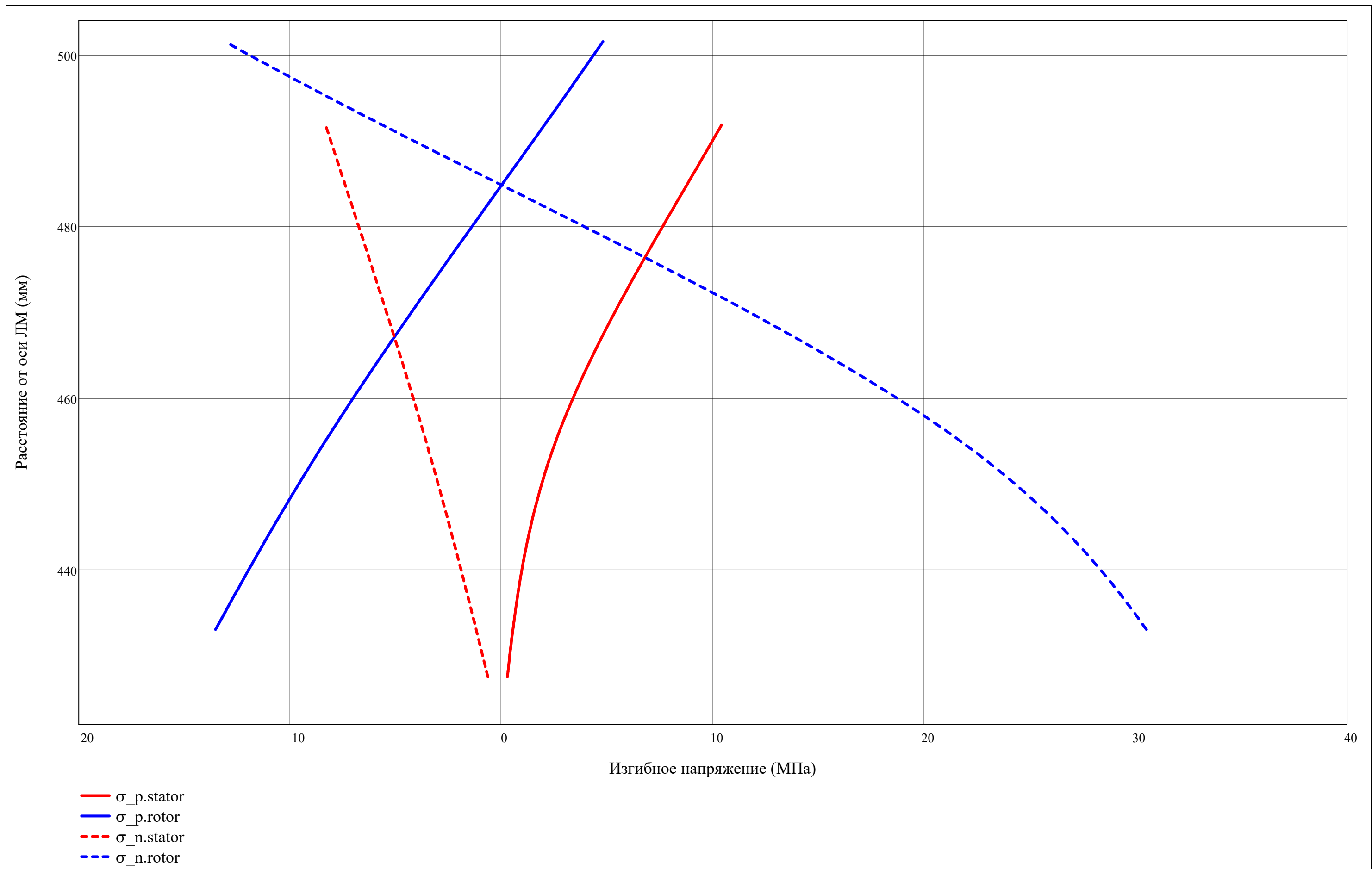


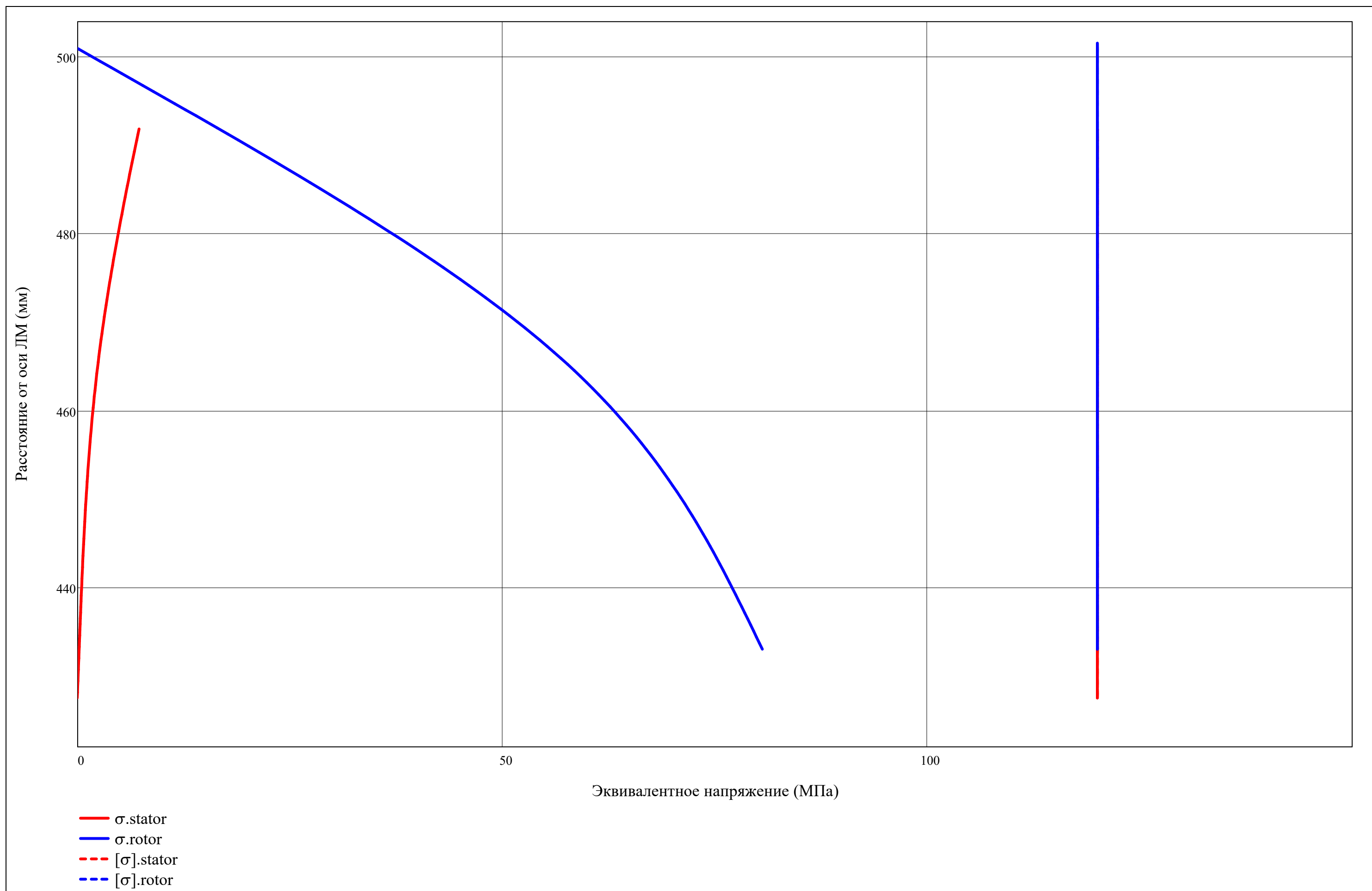












blade

r

=

"stator"

2

Наиболее удаленные точки от НЛ (мм):

u_urotor_{j,r}

v_urotor_{j,r}

u_lrotor_{j,r}

v_lrotor_{j,r}

u_u_{stator_{j,r}}

v_u_{stator_{j,r}}

u_l_{stator_{j,r}}

v_l_{stator_{j,r}}

=

| | | |
|---|--------|--------|
| | 1 | 2 |
| 1 | -0.62 | 3.77 |
| 2 | 25.85 | -9.14 |
| 3 | 22.59 | 8.77 |
| 4 | -24.75 | -15.93 |

·10⁻³

Изгибные напряжения (Па):

σ_protor_{j,r}

σ_pstator_{j,r}

σ_nrotor_{j,r}

σ_nstator_{j,r}

=

| | | |
|---|------|------|
| | 1 | 2 |
| 1 | -8.8 | 2.3 |
| 2 | 22.6 | -3.4 |

·10⁶

Эквивалентные напряжения (Па):

σ_{stator_{j,r}}

σ_{rotor_{j,r}}

=

| | |
|---|------|
| | 1 |
| 1 | 2.5 |
| 2 | 56.7 |

·10⁶

Коэф. запаса:

safety_{stator_{j,r}}

safety_{rotor_{j,r}}

=

| | |
|---|--------|
| | 1 |
| 1 | 48.515 |
| 2 | 2.117 |

v_p

v_n

=

v_urotor_{j,r}

v_lrotor_{j,r}

v_u_{stator_{j,r}}

v_l_{stator_{j,r}}

if blade = "rotor"

=

| | |
|---|---------|
| | 1 |
| 1 | 8.774 |
| 2 | -15.935 |

·10⁻³

otherwise

x0rotor_{j,r}

y0rotor_{j,r}

x0_{stator_{j,r}}

y0_{stator_{j,r}}

if blade = "rotor"

=

| | |
|---|--------|
| | 1 |
| 1 | 29.217 |
| 2 | 6.773 |

·10⁻³

otherwise

chord =

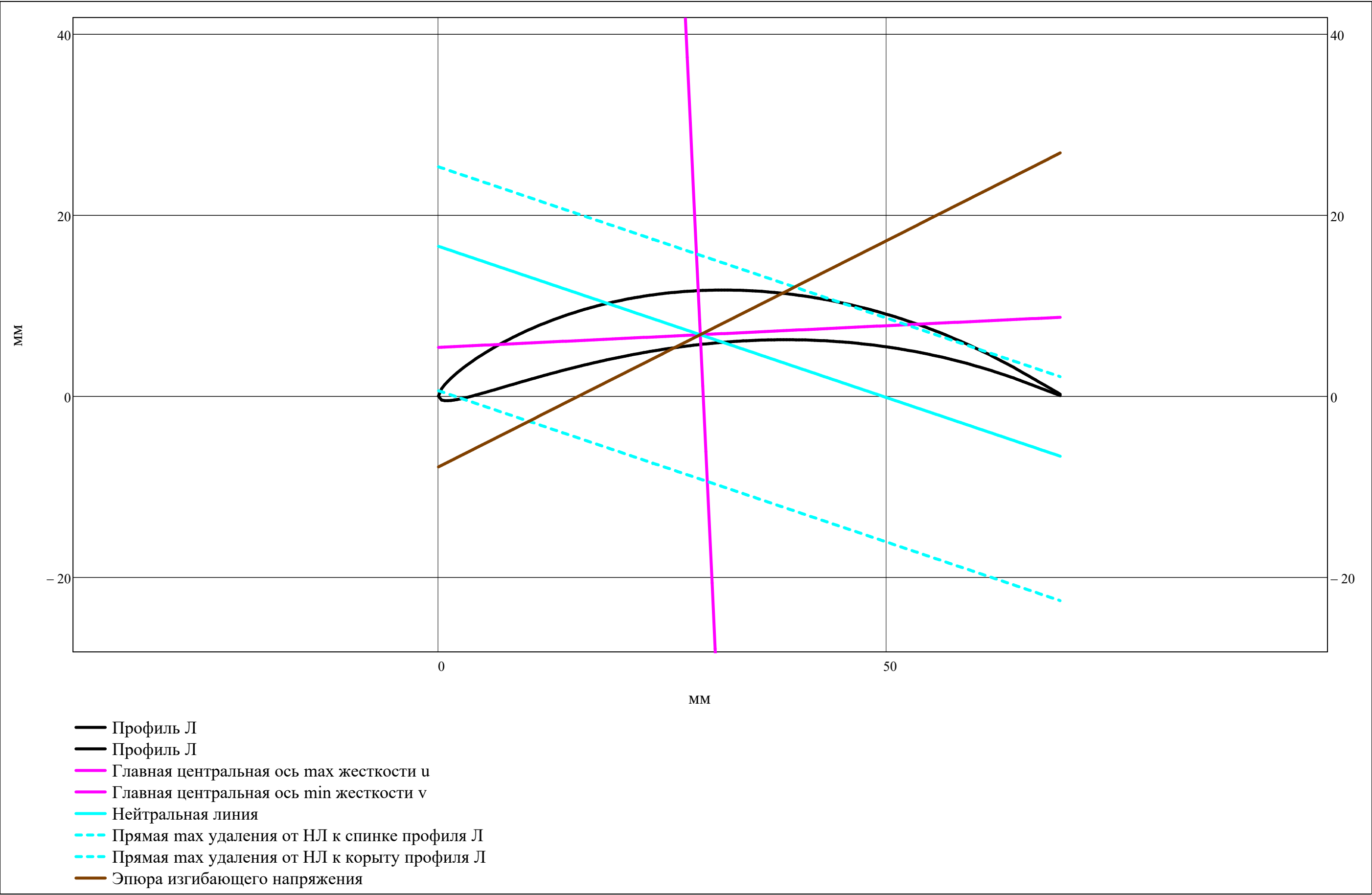
chord_{rotor_{j,r}}

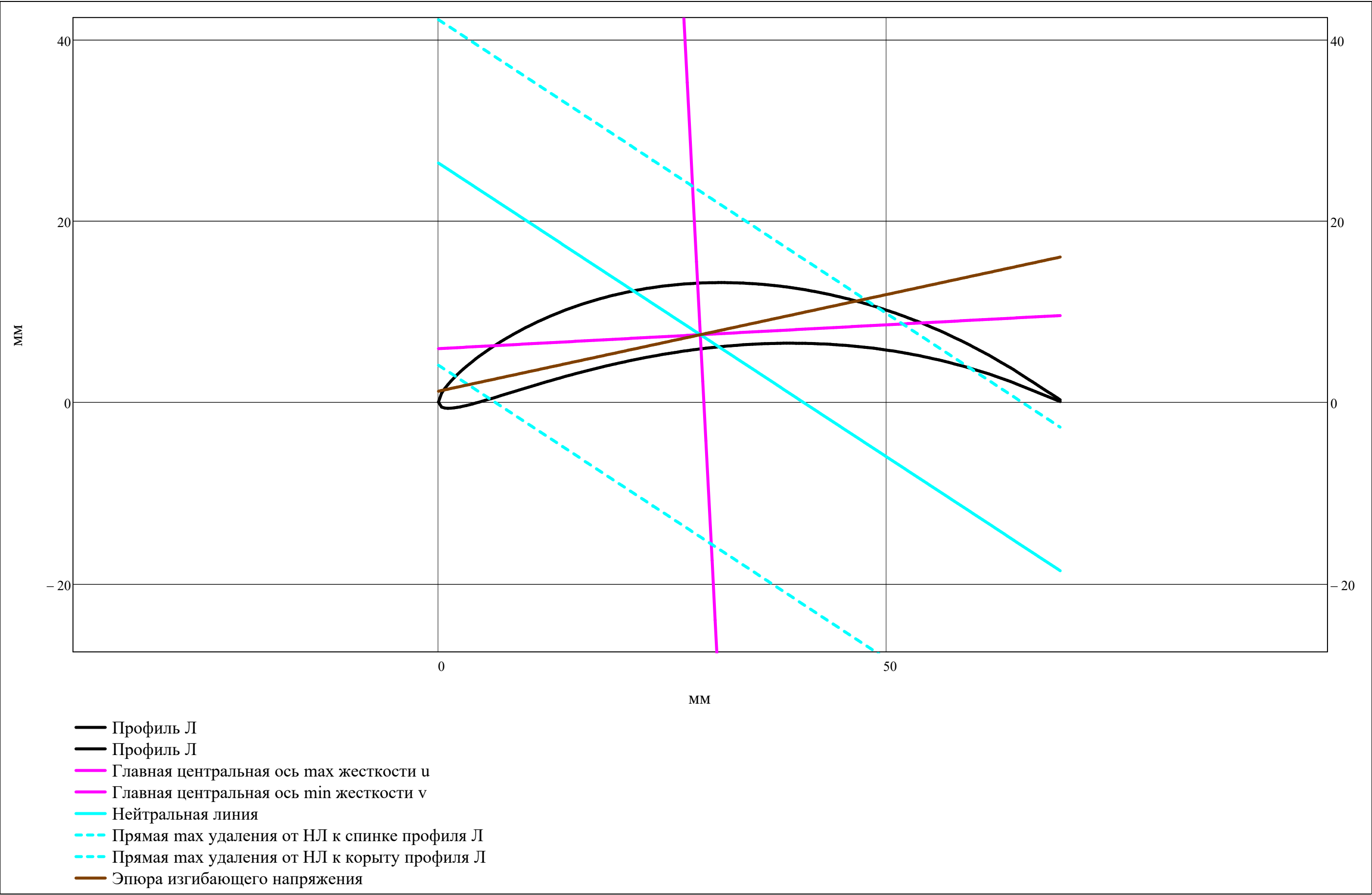
chord_{stator_{j,r}}

if blade = "rotor"

if blade = "stator"

= 69.4·10⁻³





blade

rw

=

"rotor"

1

Наиболее удаленные точки от НЛ (мм):

u_urotorj,r

v_urotorj,r

u_lrotorj,r

v_lrotorj,r

u_ustatorj,r

v_ustatorj,r

u_lstatorj,r

v_lstatorj,r

=

| | | |
|---|--------|--------|
| | 1 | 2 |
| 1 | -1.00 | 5.30 |
| 2 | 28.01 | -10.22 |
| 3 | 15.69 | 6.03 |
| 4 | -26.66 | -12.00 |

·10⁻³

Изгибные напряжения (Па):

σ_protorj,r

σ_pstatorj,r

σ_nrotorj,r

σ_nstatorj,r

=

| | | |
|---|-------|------|
| | 1 | 2 |
| 1 | -15.9 | 0.1 |
| 2 | 33.4 | -0.1 |

·10⁶

Эквивалентные напряжения (Па):

σ_statorj,r

σ_rotorj,r

=

| | |
|---|------|
| | 1 |
| 1 | 0.2 |
| 2 | 80.6 |

·10⁶

Коэф. запаса:

safety_statorj,r

safety_rotorj,r

=

| | |
|---|---------|
| | 1 |
| 1 | 751.571 |
| 2 | 1.490 |

v_p

v_n

=

v_urotorj,r

v_lrotorj,r

v_ustatorj,r

v_lstatorj,r

if blade = "rotor"

=

| | |
|---|---------|
| | 1 |
| 1 | 5.299 |
| 2 | -10.223 |

·10⁻³

otherwise

x0

y0

=

x0_rotorj,r

y0_rotorj,r

x0_statorj,r

y0_statorj,r

if blade = "rotor"

=

| | |
|---|--------|
| | 1 |
| 1 | 21.043 |
| 2 | 7.333 |

·10⁻³

otherwise

chord

=

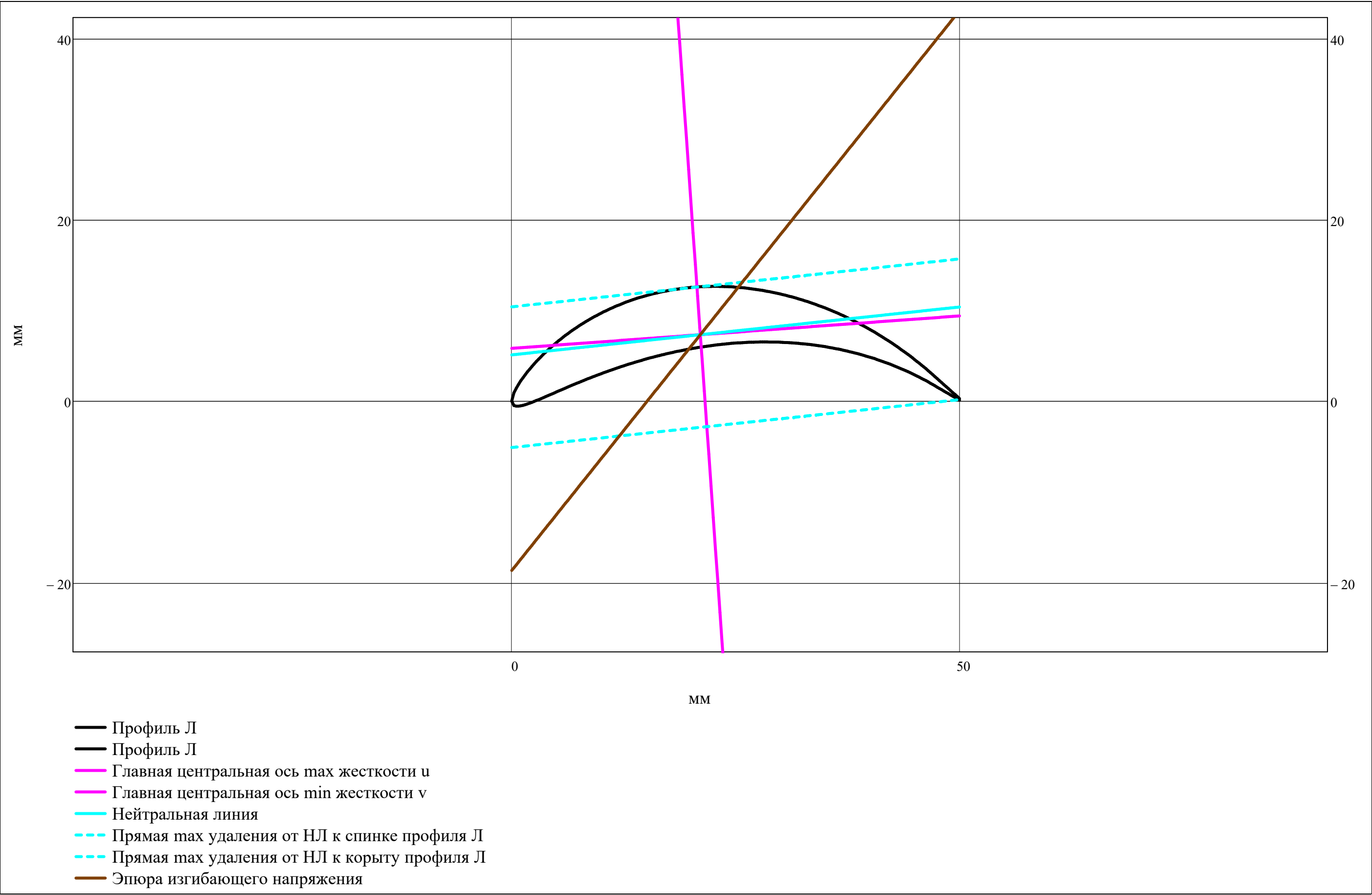
chord_rotorj,r

chord_statorj,r

if blade = "rotor"

if blade = "stator"

= 50.0·10⁻³



$$\begin{pmatrix} \text{blade} \\ \text{r} \end{pmatrix} = \begin{pmatrix} \text{"rotor"} \\ 2 \end{pmatrix}$$

Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{u_{\text{rotor}_{j,r}}} & v_{u_{\text{rotor}_{j,r}}} \\ u_{l_{\text{rotor}_{j,r}}} & v_{l_{\text{rotor}_{j,r}}} \\ u_{u_{\text{stator}_{j,r}}} & v_{u_{\text{stator}_{j,r}}} \\ u_{l_{\text{stator}_{j,r}}} & v_{l_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & -0.62 & 3.77 \\ \hline 2 & 25.85 & -9.14 \\ \hline 3 & 22.59 & 8.77 \\ \hline 4 & -24.75 & -15.93 \\ \hline \end{array} \cdot 10^{-3}$$

$$\text{Коэф. запаса: } \begin{pmatrix} \text{safety}_{\text{stator}_{j,r}} \\ \text{safety}_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 48.515 \\ \hline 2 & 2.117 \\ \hline \end{array}$$

$$\begin{pmatrix} \text{v}_{\text{p}} \\ \text{v}_{\text{n}} \end{pmatrix} = \begin{cases} \begin{pmatrix} v_{u_{\text{rotor}_{j,r}}} \\ v_{l_{\text{rotor}_{j,r}}} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} v_{u_{\text{stator}_{j,r}}} \\ v_{l_{\text{stator}_{j,r}}} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.765 \\ \hline 2 & -9.138 \\ \hline \end{array} \cdot 10^{-3}$$

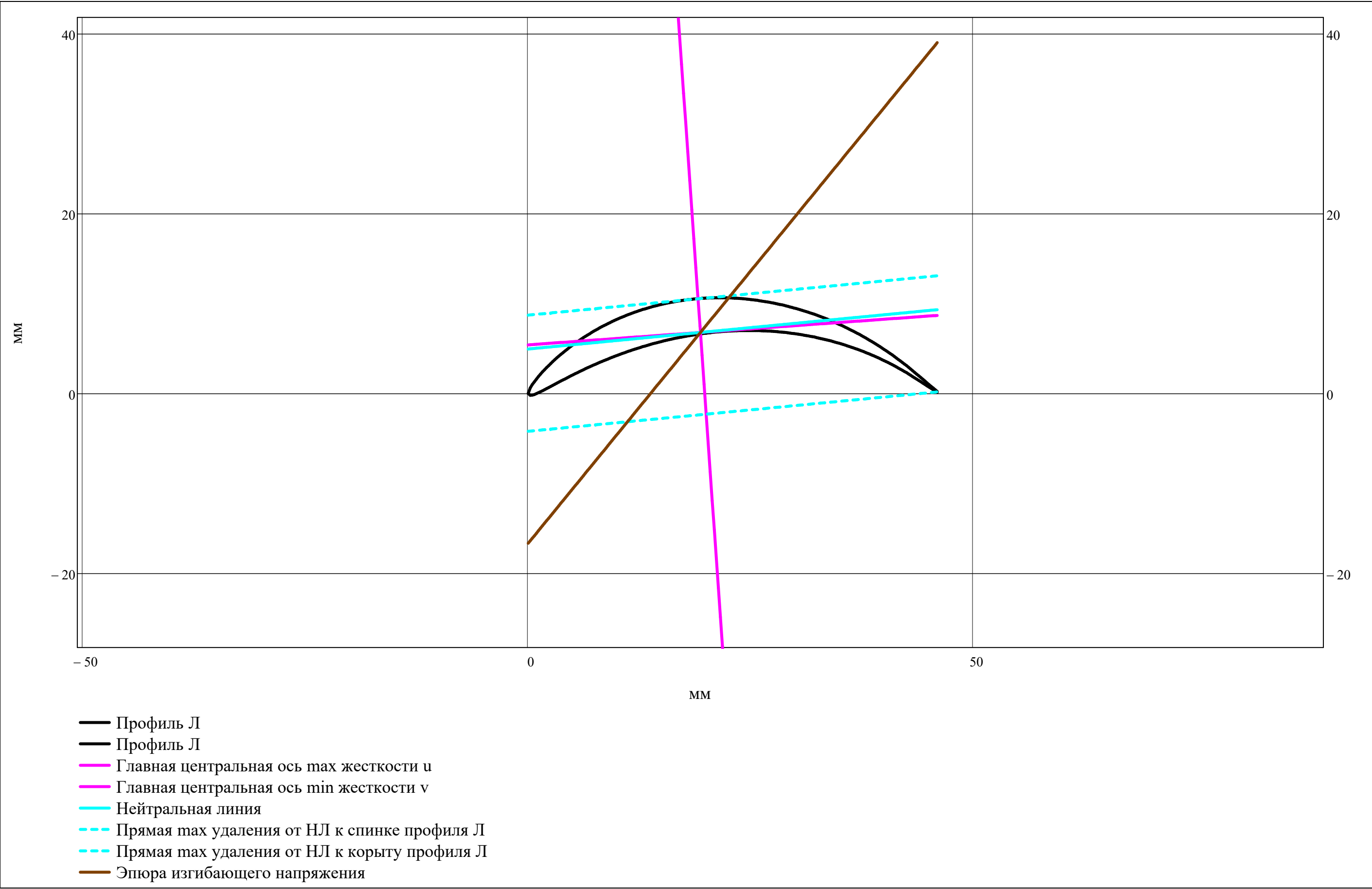
Изгибные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{p}_{\text{rotor}_{j,r}}} & \sigma_{\text{p}_{\text{stator}_{j,r}}} \\ \sigma_{\text{n}_{\text{rotor}_{j,r}}} & \sigma_{\text{n}_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{array}{|c|c|c|} \hline & 1 & 2 \\ \hline 1 & -8.8 & 2.3 \\ \hline 2 & 22.6 & -3.4 \\ \hline \end{array} \cdot 10^6$$

Эквивалентные напряжения (Па):

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.5 \\ \hline 2 & 56.7 \\ \hline \end{array} \cdot 10^6$$

$$\begin{pmatrix} \text{x0} \\ \text{y0} \end{pmatrix} = \begin{cases} \begin{pmatrix} x0_{\text{rotor}_{j,r}} \\ y0_{\text{rotor}_{j,r}} \end{pmatrix} & \text{if blade = "rotor"} \\ \begin{pmatrix} x0_{\text{stator}_{j,r}} \\ y0_{\text{stator}_{j,r}} \end{pmatrix} & \text{otherwise} \end{cases} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 19.349 \\ \hline 2 & 6.782 \\ \hline \end{array} \cdot 10^{-3} \quad \text{chord} = \begin{cases} \text{chord}_{\text{rotor}_{j,r}} & \text{if blade = "rotor"} \\ \text{chord}_{\text{stator}_{j,r}} & \text{if blade = "stator"} \end{cases} = 45.9 \cdot 10^{-3}$$



Запас по температуре (K):

$\Delta T_{\text{safety}} = 0$

Выбранный материал Д:

$\text{material_disk}_i = \begin{cases} \text{"ВЖ175"} & \text{if turbine = "ТВД"} \\ \text{"ЭП742"} & \text{if turbine = "ТНД"} \end{cases}$

Плотность материала Д (кг/м^3):

$\rho_{\text{disk}}_i = \begin{cases} 8266 & \text{if material_disk}_i = \text{"ВЖ175"} \\ 8320 & \text{if material_disk}_i = \text{"ЭП742"} \\ 8393 & \text{if material_disk}_i = \text{"ЖС-6К"} \\ 7900 & \text{if material_disk}_i = \text{"BT41"} \\ 4500 & \text{if material_disk}_i = \text{"BT25"} \\ 4570 & \text{if material_disk}_i = \text{"BT23"} \\ 4510 & \text{if material_disk}_i = \text{"BT9"} \\ 4430 & \text{if material_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

Предел длительной прочности Д (Па):

$\sigma_{\text{disk_long}}_i = 10^6 \cdot \begin{cases} 620 & \text{if material_disk}_i = \text{"ВЖ175"} \\ 680 & \text{if material_disk}_i = \text{"ЭП742"} \\ 125 & \text{if material_disk}_i = \text{"ЖС-6К"} \\ 123 & \text{if material_disk}_i = \text{"BT41"} \\ 150 & \text{if material_disk}_i = \text{"BT25"} \\ 230 & \text{if material_disk}_i = \text{"BT23"} \\ 200 & \text{if material_disk}_i = \text{"BT9"} \\ 210 & \text{if material_disk}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$

material_disk^T =

| | | | | |
|---|---------|---------|---------|---------|
| | 1 | 2 | 3 | 4 |
| 1 | "ЭП742" | "ЭП742" | "ЭП742" | "ЭП742" |

ρ_disk^T =

| | | | | |
|---|------|------|------|------|
| | 1 | 2 | 3 | 4 |
| 1 | 8320 | 8320 | 8320 | 8320 |

σ_disk_long^T =

| | | | | |
|---|-----|-----|-----|-----|
| | 1 | 2 | 3 | 4 |
| 1 | 680 | 680 | 680 | 680 |

·10⁶

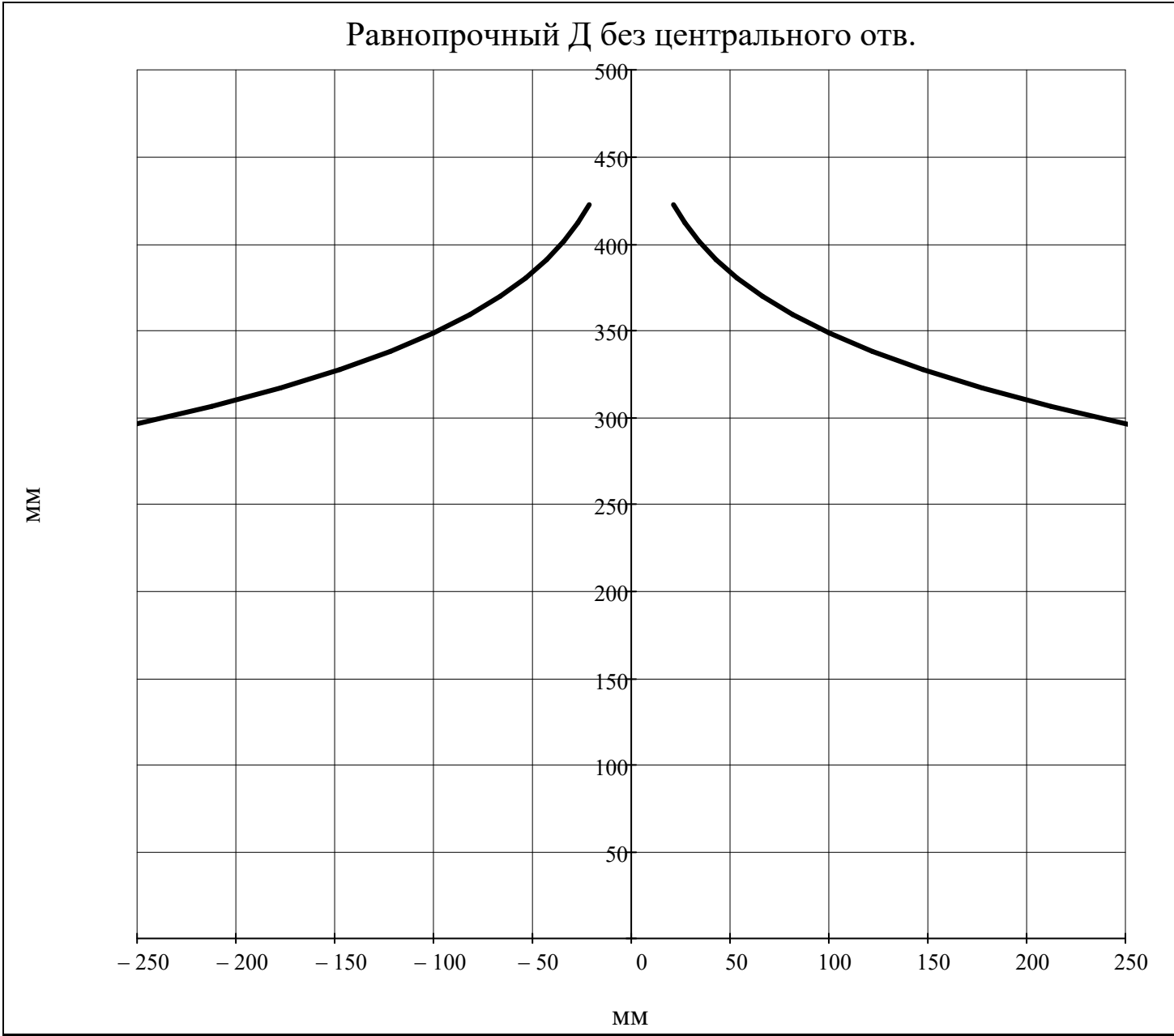
Рассматриваемая ступень:

$$j_w = \begin{cases} j = Z & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 4$$

Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{cases} \left(\text{chord}_{\text{rotor}_{i, \text{ORIGIN}}} \cdot \sin\left(v_{\text{rotor}_{i, \text{ORIGIN}}}\right)\right) \cdot e^{\frac{\rho_{\text{disk}_i} \cdot \omega^2}{2} \cdot \frac{1}{\sigma_{z_{\text{rotor}}(i, R_{\text{st}}(i, 2), \text{ORIGIN})}} \cdot \left[\left(R_{\text{st}}(i, 2), \text{ORIGIN}\right)^2 - z^2\right]} & \text{if } z \leq R_{\text{st}}(i, 2), \text{ORIGIN} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$z = 0, \frac{R_{\text{st}}(j, 2), \text{ORIGIN}}{N_{\text{dis}}} \dots R_{\text{st}}(j, 2), \text{ORIGIN}$$

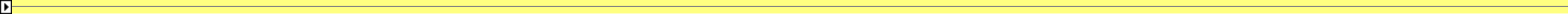


Профилирование равнопрочного Д без центрального отв.

$$type = \begin{cases} type = "stator" & \\ type = \begin{cases} "Нет\ такого\ типа!" & \text{if } type \neq "stator" \wedge type \neq "rotor" \\ type & \text{otherwise} \end{cases} & \\ \end{cases} = "stator"$$

Рассматриваемая ступень:

$$j = \begin{cases} j = 1 & \\ j = \begin{cases} "Такой\ ступени\ не\ существует!" & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \\ \end{cases} = 1$$







$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 196.80 \\ 511.29 \\ 231.75 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 194.59 \\ 253.24 \\ 231.37 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 282.51 \\ 325.09 \\ 324.12 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 81.41 \\ 29.69 \\ 86.70 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 234.20 \\ 240.32 \\ 240.32 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 43.53 \\ 128.83 \\ 45.55 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 51.72 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 83.28 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 196.62 \\ 483.45 \\ 231.73 \end{pmatrix}$$

$$\begin{pmatrix} c_{ast(j,1),r} \\ c_{ast(j,2),r} \\ c_{ast(j,3),r} \end{pmatrix} = \begin{pmatrix} 196.19 \\ 232.28 \\ 231.73 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 308.77 \\ 285.12 \\ 348.14 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 86.17 \\ 28.72 \\ 89.95 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 251.56 \\ 258.65 \\ 260.00 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 39.45 \\ 125.44 \\ 41.73 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator,j,r} = 57.46 \cdot ^\circ$$

$$\epsilon_{rotor,j,r} = 83.71 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 196.61 \\ 458.40 \\ 231.72 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 196.60 \\ 212.23 \\ 231.46 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 333.95 \\ 248.53 \\ 371.50 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90.30 \\ 27.58 \\ 92.70 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 268.92 \\ 276.98 \\ 279.68 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 36.07 \\ 121.36 \\ 38.54 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 62.72 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 82.82 \cdot ^\circ$$
