

Исходные данные

Коэф. запаса:

safety = 1.3

Степень двухконтурности:

m2 = 6

РТ: Воздух

compressor = "Вл"

Число Маха:

M = 0

Геометрическая высота работы (м):

H_{ww} = 0

Массовый расход (кг/с):

G_{ww} =

35.65 + 213.93 if compressor = "Вл" = 249.58

35.65 if compressor = "КНД"

34.81 if compressor = "КВД"

Полная температура на входе в К (К):

T*_{K1} =

418.2 if compressor = "КВД" = 288.2

288.2 otherwise

Полное давление на входе в К (Па):

P*_{K1} =

316.2·10³ if compressor = "КВД" = 101.3·10³

101325 otherwise

Степень повышения давления КВД:

π*_K =

1.6 if compressor = "Вл" = 1.600

3.2

1.6

 if compressor = "КНД"

9 if compressor = "КВД"

Ожидаемый адиабатический КПД ОК:	$\eta_K^* =$	0.86 if compressor = "Вл" = 86.00-%
		0.87 if compressor = "КНД"
		0.88 if compressor = "КВД"

Частота вращения ротора (с⁻¹):

$\omega =$	1570.8 if compressor = "КВД"	= 555.0
	555 otherwise	

$$\text{Относ. диаметр корня 1ой ступени [14, с.7]:} \quad \overline{d}_1 = \begin{cases} 0.40 & \text{if compressor = "Вл"} \\ 0.75 & \text{if compressor = "КНД"} \\ 0.65 & \text{if compressor = "КВД"} \end{cases} = 0.40$$

Частота вращения ротора (об/мин): $n = \frac{60 \cdot \omega}{2 \cdot \pi} = 5300$

Закон профилирования проточной части (ЗППЧ):

[illegible]

Относ. параметры по относительным ступеням:

$$\begin{pmatrix} z_{\sim} \\ R_{L\sim cp} \\ K_{\sim H} \\ \eta^*_{\sim} \\ \bar{c}_{\sim a1} \\ \bar{H}_{\sim T} \end{pmatrix} = \begin{bmatrix} (1 \ 2 \ 3 \ 4 \ 5 \ 6 \ 7 \ 8)^T \\ (0.5 \ 0.5 \ 0.5 \ 0.5 \ 0.5 \ 0.5 \ 0.5 \ 0.5)^T \\ (0.99 \ 0.98 \ 0.97 \ 0.96 \ 0.95 \ 0.95 \ 0.95 \ 0.95)^T \\ (0.88 \ 0.89 \ 0.905 \ 0.91 \ 0.91 \ 0.905 \ 0.89 \ 0.88)^T \\ (0.435 \ 0.425 \ 0.415 \ 0.405 \ 0.395 \ 0.385 \ 0.375 \ 0.365)^T \\ (0.25 \ 0.29 \ 0.32 \ 0.33 \ 0.35 \ 0.32 \ 0.29 \ 0.27)^T \end{bmatrix}$$

Тип компрессора	Номер ступени и $\bar{L}_{CT,i}$							
	I	II	III	IV	z_{CP}	$z - 2$	$z - 1$	z
Дозвуковой	0,18-0,20	0,24-0,25	0,24-0,25	0,29-0,30	0,30-0,32	0,28-0,29	0,27-0,28	0,26-0,27
Трансзвуковой	0,19-0,22	0,27-0,29	0,30-0,32	0,32-0,33	0,33-0,35	0,31-0,32	0,27-0,28	0,26-0,27
С одной св/зв ступенью	0,23-0,25	0,27-0,29	0,30-0,32	0,32-0,33	0,33-0,35	0,31-0,32	0,27-0,28	0,26-0,27
С 2-мя св/зв ступенями	0,23-0,25	0,27-0,29	0,30-0,32	0,32-0,33	0,33-0,35	0,31-0,32	0,27-0,28	0,26-0,27
С 3-мя св/зв ступенями	0,23-0,25	0,27-0,29	0,30-0,32	0,32-0,33	0,33-0,35	0,31-0,32	0,27-0,28	0,25-0,26

[16, c. 60]

[18, c. 24]

Уточнение параметров:

$$R_{L\sim cp} = R_{L\sim cp} + \left\{ \begin{array}{l} 0.0 \text{ if compressor} = \text{"Вл"} \\ 0.1 \text{ if compressor} = \text{"КНД"} \\ 0.2 \text{ if compressor} = \text{"КВД"} \end{array} \right.$$

увеличение несущественно увеличивает π

$$\eta^*_{\sim} = \eta^*_{\sim} + \left\{ \begin{array}{l} -0.020 \text{ if compressor} = \text{"Вл"} \\ -0.028 \text{ if compressor} = \text{"КНД"} \\ -0.017 \text{ if compressor} = \text{"КВД"} \end{array} \right.$$

увеличение несущественно увеличивает π

$$\overline{c}_{\sim a1} = \overline{c}_{\sim a1} - \left\{ \begin{array}{l} 0.100 \text{ if compressor} = \text{"Вл"} \\ 0.141 \text{ if compressor} = \text{"КНД"} \\ 0.203 \text{ if compressor} = \text{"КВД"} \end{array} \right.$$

понижение существенно увеличивает π

$$\overline{H}_{\sim T} = \overline{H}_{\sim T} + \left\{ \begin{array}{l} 0.0145 \text{ if compressor} = \text{"Вл"} \\ 0.0164 \text{ if compressor} = \text{"КНД"} \\ 0.0173 \text{ if compressor} = \text{"КВД"} \end{array} \right.$$

увеличение существенно увеличивает π

$$\text{stack}\left(R_{L\sim cp}^T, K_{\sim H}^T, \eta^{*}_{\sim}{}^T, \overline{c}_{\sim a1}^T, \overline{H}_{\sim T}^T\right) =$$

	1	2	3	4	5	6	7	8
1	0.500	0.500	0.500	0.500	0.500	0.500	0.500	0.500
2	0.990	0.980	0.970	0.960	0.950	0.950	0.950	0.950
3	0.860	0.870	0.885	0.890	0.890	0.885	0.870	0.860
4	0.335	0.325	0.315	0.305	0.295	0.285	0.275	0.265
5	0.265	0.305	0.335	0.345	0.365	0.335	0.305	0.285

$$0.15 \leq \overline{c}_{\sim a1}^T = (1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1)$$

$$\overline{c}_{\sim a1}^T \leq 0.65 = (1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1)$$

$$0.18 \leq \overline{H}_{\sim T}^T = (1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1 \quad 1)$$

$$\overline{H}_{\sim T}^T \leq 0.35 = (1 \quad 1 \quad 1 \quad 1 \quad 0 \quad 1 \quad 1 \quad 1)$$

Коэф. теор. напора "средней" ступени [14, с.11]:

$$\overline{H}_{Tcp} = \frac{\sum_{i=1}^{rows(z_{\sim})} \overline{H}_{\sim T_i}}{rows(z_{\sim})} = 0.317$$

$$0.25 \leq \overline{H}_{Tcp} \leq 0.32 = 1$$

Кинематическая степень реактивности: $\widetilde{R_{L\sim cp}}(i) = \text{interp}\left(\text{lspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, R_{L\sim cp}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, R_{L\sim cp}, i\right)$

Коэф. уменьшения теор. напора: $K_{\sim H}(i) = \text{interp}\left(\text{lspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, K_{\sim H}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, K_{\sim H}, i\right)$

Изоэнтропический КПД: $\widetilde{\eta^*_{\sim}}(i) = \text{interp}\left(\text{lspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, \eta^*_{\sim}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, \eta^*_{\sim}, i\right)$

Коэф. расхода: $\overline{\widetilde{c_{\sim a1}}}(i) = \text{interp}\left(\text{lspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, \overline{c_{\sim a1}}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, \overline{c_{\sim a1}}, i\right)$

Коэф. напора: $\overline{\widetilde{H_{\sim T}}}(i) = \text{interp}\left(\text{lspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, \overline{H_{\sim T}}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, \overline{H_{\sim T}}, i\right)$

$$\begin{pmatrix} R_{L.cp} \\ K_{.H} \\ \eta^*_{.} \\ \bar{c}_{.a1} \\ \bar{H}_{.T} \end{pmatrix} = \begin{pmatrix} R_{L.cp}(Z,i) \\ K_{.H}(Z,i) \\ \eta^*_{.}(Z,i) \\ \bar{c}_{.a1}(Z,i) \\ \bar{H}_{.T}(Z,i) \end{pmatrix} = \begin{cases} R_{L\sim cp}\left(\frac{1}{rows(z_{\sim})}\right) & \text{if } i < 1 \\ R_{L\sim cp}(1) & \text{if } i > Z \\ R_{L\sim cp}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$

$$\begin{cases} K_{\sim H}\left(\frac{1}{rows(z_{\sim})}\right) & \text{if } i < 1 \\ K_{\sim H}(1) & \text{if } i > Z \\ K_{\sim H}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$

$$\begin{cases} \eta^*_{\sim}\left(\frac{1}{rows(z_{\sim})}\right) & \text{if } i < 1 \\ \eta^*_{\sim}(1) & \text{if } i > Z \\ \eta^*_{\sim}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$

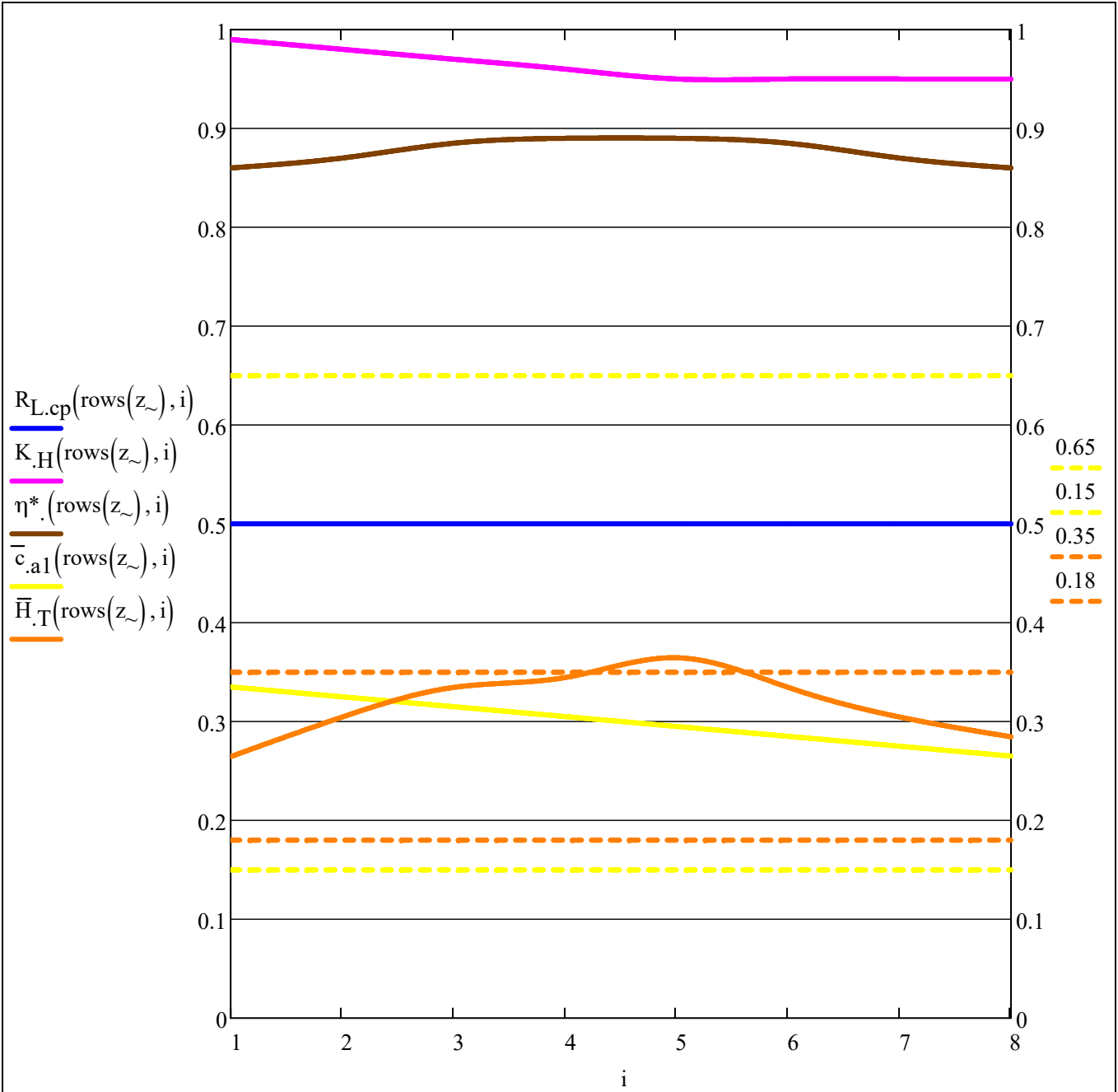
$$\begin{cases} \bar{c}_{\sim a1}\left(\frac{1}{rows(z_{\sim})}\right) & \text{if } i < 1 \\ \bar{c}_{\sim a1}(1) & \text{if } i > Z \\ \bar{c}_{\sim a1}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$

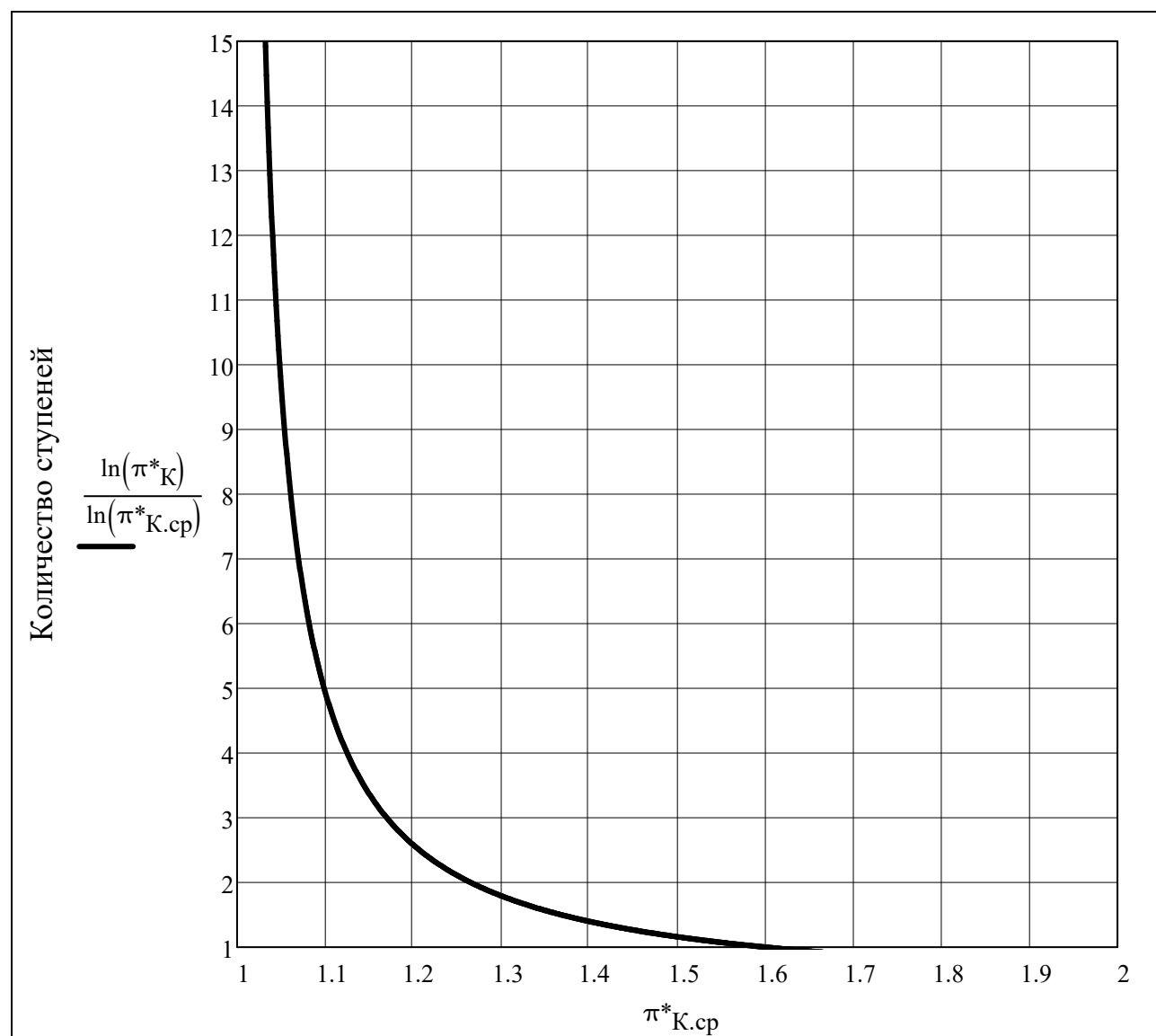
$$\begin{cases} \bar{H}_{\sim T}\left(\frac{1}{rows(z_{\sim})}\right) & \text{if } i < 1 \\ \bar{H}_{\sim T}(1) & \text{if } i > Z \\ \bar{H}_{\sim T}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$

$$\left(R_{L.cp} \ K_{.H} \ \eta^*_{.} \ \bar{c}_{.a1} \ \bar{H}_{.T}\right)^T$$

$$\begin{pmatrix} Z_{temp} \\ i_{temp} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} R_{L.cp}(Z_{temp},i_{temp}) \\ K_{.H}(Z_{temp},i_{temp}) \\ \eta^*_{.}(Z_{temp},i_{temp}) \\ \bar{c}_{.a1}(Z_{temp},i_{temp}) \\ \bar{H}_{.T}(Z_{temp},i_{temp}) \end{pmatrix} = \begin{pmatrix} 0.500 \\ 0.950 \\ 0.860 \\ 0.265 \\ 0.285 \end{pmatrix}$$





Показатель адиабаты перед K []: $k_{K1} = k_{\text{ад}}\left(C_{p_{\text{воздух}}}\left(P^*_{K1}, T^*_{K1}\right), R_B\right) = 1.401$

Полное давление после K [Па]: $P^*_{K3} = \pi^*_K \cdot P^*_{K1} = 162 \cdot 10^3$

iteration₃

T^{*}_{K3}

k_{K3}

=

iteration₃ = 0

k_{K3} = k_{K1}

while 0 < 1

iteration₃ = iteration₃ + 1

trace("iteration.3 = ", num2str(iteration₃))

k_{ср} = mean(k_{K1}, k_{K3})

$T^*_{K3} = T^*_{K1} \cdot \left(1 + \frac{\pi^*_K \cdot \frac{k_{ср}-1}{k_{ср}} - 1}{\eta^*_K}\right)$

C_p_{K3} = C_p_{воздух}(P^{*}_{K3}, T^{*}_{K3})

k'_{K3} = k_{ад}(C_p_{K3}, R_B)

if |eps("rel", k_{K3}, k'_{K3})| ≤ epsilon

k_{K3} = k'_{K3}

break

k_{K3} = k'_{K3}

iteration₃

T^{*}_{K3}

k_{K3}

Количество итераций []: iteration₃ = 1

Полная температура после K [K]: T^{*}_{K3} = 336.5

Показатель адиабаты после K []: k_{K3} = 1.399

Полная плотность перед и после K [кг/м³]: $\begin{pmatrix} \rho^*_{K1} \\ \rho^*_{K3} \end{pmatrix} = \frac{1}{R_B} \cdot \begin{pmatrix} \frac{P^*_{K1}}{T^*_{K1}} \\ \frac{P^*_{K3}}{T^*_{K3}} \end{pmatrix} = \begin{pmatrix} 1.224 \\ 1.678 \end{pmatrix}$

Критические скорости перед и после K [м/с]: $\begin{pmatrix} a^*_{с.вх} \\ a^*_{с.вых} \end{pmatrix} = \begin{pmatrix} a_{кр}(k_{K1}, R_B, T^*_{K1}) \\ a_{кр}(k_{K3}, R_B, T^*_{K3}) \end{pmatrix} = \begin{pmatrix} 310.8 \\ 335.7 \end{pmatrix}$

Ср. показатель адиабаты K []: k_{ср} = k_{ад}(C_p_{воздух.ср}(P^{*}_{K1}, P^{*}_{K3}, T^{*}_{K1}, T^{*}_{K3}), R_B) = 1.401

Теоретический напор [Дж/кг]: $H_{TK} = \frac{C_{p_{\text{воздух.ср}}}\left(P^*_{K1}, P^*_{K3}, T^*_{K1}, T^*_{K3}\right) \cdot T^*_{K1} \cdot \left(\pi^*_K \cdot \frac{k_{ср}-1}{k_{ср}} - 1\right)}{\eta^*_K} = 48.4 \cdot 10^3$

iteration _u	
u _{1пер}	
Z _{recomend}	=
c _{ВХ}	iteration _u = 0
λ _{ВХ}	ρ _{K1} = ρ* _{K1}
ρ _{K1}	while 0 < 1
	iteration _u = iteration _u + 1
	trace(concat("iteration.u = ", num2str(iteration _u)))
	$u_{1пер} = \sqrt[3]{\frac{\pi \cdot G \cdot n^2}{900 \cdot \bar{c}_{.a1}(1,0) \cdot \rho_{K1} \cdot [1 - (\bar{d}_1)^2]}}$
	$Z_{recomend} = \max\left(\text{round}\left(\frac{H_{TK}}{\bar{H}_{Tcp} \cdot u_{1пер}^2}\right), 1\right)$
	c _{ВХ} = $\bar{c}_{.a1}(Z_{recomend}, 0) \cdot u_{1пер}$
	$\lambda_{ВХ} = \frac{c_{ВХ}}{a^*_{c.ВХ}}$
	ρ' _{K1} = ρ* _{K1} · ГДФ("ρ", λ _{ВХ} , k _{K1})
	if eps("rel", ρ' _{K1} , ρ _{K1}) ≤ epsilon
	ρ _{K1} = ρ' _{K1}
	break
	ρ _{K1} = ρ' _{K1}
	(iteration _u
	u _{1пер}
	Z _{recomend}
	c _{ВХ}
	λ _{ВХ}
	ρ _{K1}

Количество итераций []: iteration_u = 2

Окружная скорость на перифкрии перед K [м/с]: u_{1пер} = 425.9

Рекомендуемое количество ступеней []: Z_{recomend} = 1

Абс. скорость перед K [м/с]: c_{ВХ} = 142.7

Приведенная скорость перед K []: λ_{ВХ} = 0.4591

Плотность перед K [кг/м^3]: ρ_{K1} = 1.120

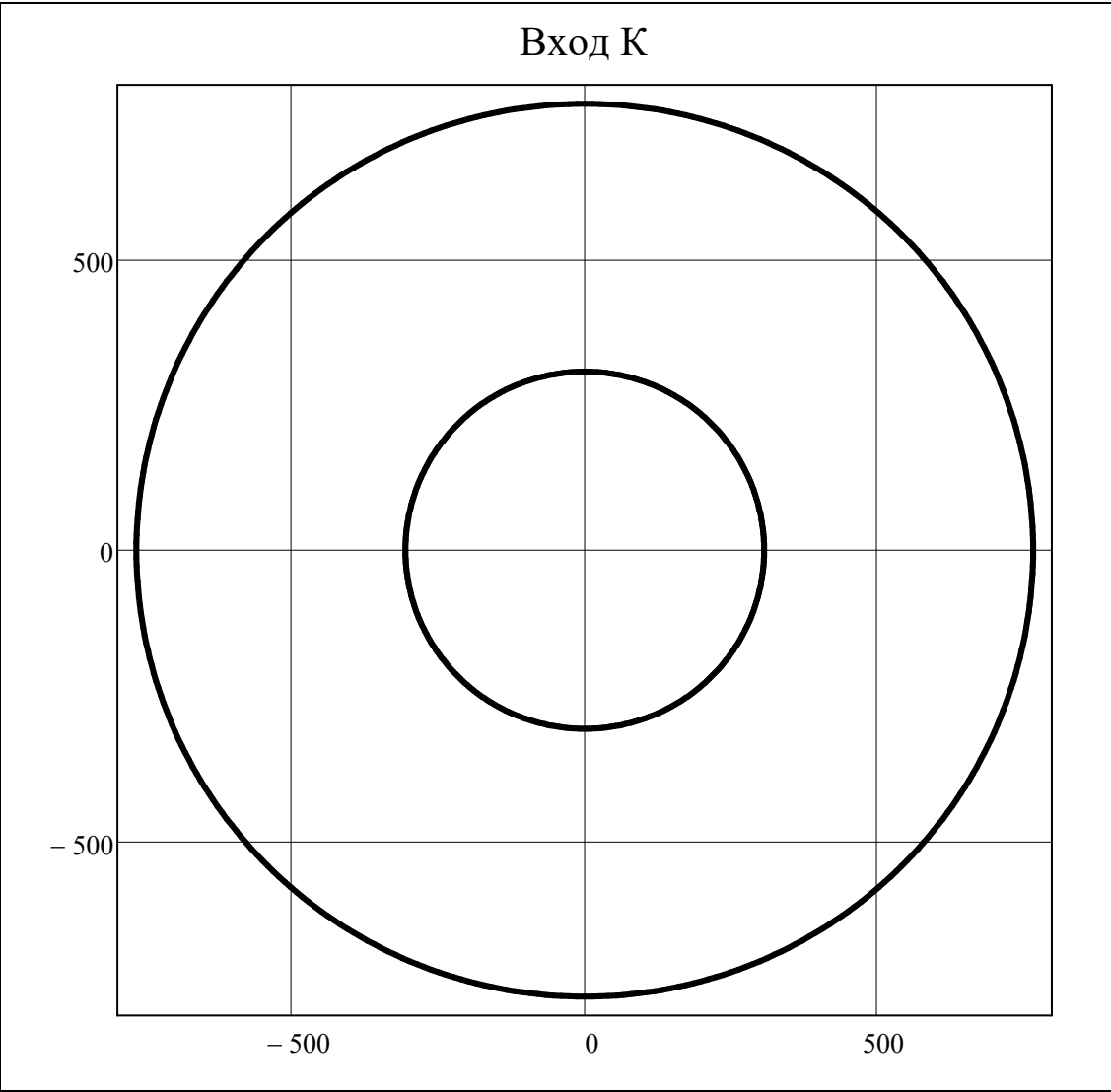
Кольцевая площадь перед K [м²]:
$$F_{ВХ} = \frac{G \cdot \sqrt{R_B \cdot T^*_{K1}}}{m_q(k_{K1}) \cdot P^*_{K1} \cdot \Gamma Д \Phi("G", \lambda_{ВХ}, k_{K1})} = 1.5621$$

$$D'_{пер1} = \frac{2 \cdot u_{1пер}}{\omega} = 1534.9 \cdot 10^{-3}$$

Диаметры перед K [м]: D'_{ср1} = $\bar{r}_{ср}(\bar{d}_1) \cdot D'_{пер1} = 1169 \cdot 10^{-3}$

$$D'_{кор1} = \bar{d}_1 \cdot D'_{пер1} = 614 \cdot 10^{-3}$$

$\varphi = 0, \frac{2 \cdot \pi}{360} .. 2 \cdot \pi$



Рекомендуемое количество ступеней []: $Z_{\text{recomend}} = 1$

Количество ступеней []:

$Z =$	1	if compressor = "Вл"	= 1
	3	if compressor = "КНД"	
	9	if compressor = "КВД"	

$$\text{BHA} = \begin{cases} 1 & \text{if compressor} = \text{"КВД"} \\ 0 & \text{otherwise} \end{cases} = 0$$

Расчет ВНА:

$$\left(\begin{array}{cc} \alpha_{1BHA} & \alpha_{3BHA} \\ \sigma_{BHA} & \sigma_{BHA} \\ \bar{d}_{1BHA} & \bar{d}_{3BHA} \\ T^*_{1BHA} & T^*_{3BHA} \\ P^*_{1BHA} & P^*_{3BHA} \\ \rho^*_{1BHA} & \rho^*_{3BHA} \\ k_{1BHA} & k_{3BHA} \\ a_{kp1BHA} & a_{kp3BHA} \\ \bar{c}_{a1BHA} & \bar{c}_{a3BHA} \\ \bar{c}_{u1BHA} & \bar{c}_{u3BHA} \\ c_{a1BHA} & c_{a3BHA} \\ c_{u1BHA} & c_{u3BHA} \\ c_{1BHA} & c_{3BHA} \\ \lambda_{c1BHA} & \lambda_{c3BHA} \\ F_{1BHA} & F_{3BHA} \\ \varepsilon_{BHA} & \varepsilon_{BHA} \end{array} \right) = \left\{ \begin{array}{l} \text{for } r \in \text{av}(N_r) \\ \alpha_{1BHA_r} = 90^\circ \\ \bar{d}_{1BHA} = \bar{d}_1 \\ \bar{d}_{3BHA} = \bar{d}_{1BHA} \\ T^*_{1BHA_r} = T^*_{K1} \\ T^*_{3BHA_r} = T^*_{1BHA_r} \\ P^*_{1BHA_r} = P^*_{K1} \\ \rho^*_{1BHA_r} = \frac{P^*_{1BHA_r}}{R_B \cdot T^*_{1BHA_r}} \\ k_{1BHA_r} = k_{ад} \left(C_{p_{воздух}}(P^*_{1BHA_r}, T^*_{1BHA_r}), R_B \right) \\ a_{kp1BHA_r} = a_{kp} \left(k_{1BHA_r}, R_B, T^*_{1BHA_r} \right) \\ \bar{c}_{a1BHA_r} = \bar{c}_{.a1}(Z, 0) \\ \bar{c}_{u1BHA_r} = \left\{ \begin{array}{l} \bar{r}_{cp}(\bar{d}_{1BHA}) \cdot (1 - R_{L.cp}(Z, 0)) - \frac{\bar{H}_{.T}(Z, 0)}{2 \cdot \bar{r}_{cp}(\bar{d}_{1BHA})} \quad \text{if } BHA = 1 \\ 0 \quad \text{otherwise} \end{array} \right. \\ c_{a1BHA_r} = \bar{c}_{a1BHA_r} \cdot u_{1пер} \end{array} \right.$$

$$\sigma_{\text{BHA}} = 1.0000$$

$$\text{submatrix}(\epsilon_{\text{BHA}}, \text{av}(\mathbf{N}_{\text{r}}), \text{av}(\mathbf{N}_{\text{r}}), 1, 1) = (0.00) \cdot \text{deg}$$

$$\text{submatrix}(\alpha_{1\text{BHA}}, \text{av}(\text{N}_r), \text{av}(\text{N}_r), 1, 1) = (90.00) \cdot \text{deg}$$

$$\text{submatrix}(\alpha_{3\text{BHA}}, \text{av}(\text{N}_r), \text{av}(\text{N}_r), 1, 1) = (90.00) \cdot \text{deg}$$

$$\begin{pmatrix} \bar{d}_{1\text{BHA}} \\ \bar{d}_{3\text{BHA}} \end{pmatrix} = \begin{pmatrix} 0.4000 \\ 0.4000 \end{pmatrix} \qquad \begin{pmatrix} F_{1\text{BHA}} \\ F_{3\text{BHA}} \end{pmatrix} = \begin{pmatrix} 1.5621 \\ 1.5621 \end{pmatrix}$$

$$c_{u1BHA_r} = \frac{c_{a1BHA_r}}{\tan(\alpha_{1BHA_r})}$$

$$c_{1BHA_r} = \frac{c_{a1BHA_r}}{\sin(\alpha_{1BHA_r})}$$

$$\lambda_{c1BHA_r} = \frac{c_{1BHA_r}}{a_{kp1BHA_r}}$$

$$\sigma_{BHA} = \begin{cases} \left[1 + \text{mean}(0.03, 0.06) \cdot \Gamma\text{Д}\Phi\left("p", \lambda_{c1BHA_r}, k_{1BHA_r}\right) \cdot \frac{k_{1BHA_r}}{k_{1BHA_r} + 1} \cdot \left(\lambda_{c1BHA_r}\right)^2 \right]^{-1} & \text{if } BHA = 1 \\ 1 & \text{otherwise} \end{cases}$$

$$P^*_{3BHA_r} = P^*_{1BHA_r} \cdot \sigma_{BHA}$$

$$\rho^*_{3BHA_r} = \frac{P^*_{3BHA_r}}{R_B \cdot T^*_{3BHA_r}}$$

$$k_{3BHA_r} = k_{ад}\left(C_{p\text{воздух}}\left(P^*_{3BHA_r}, T^*_{3BHA_r}\right), R_B\right)$$

$$a_{kp3BHA_r} = a_{kp}\left(k_{3BHA_r}, R_B, T^*_{3BHA_r}\right)$$

$$\bar{c}_{a3BHA_r} = \begin{cases} \bar{c}_{a1}(Z, 1) & \text{if } BHA = 1 \\ \bar{c}_{a1BHA_r} & \text{otherwise} \end{cases}$$

$$\bar{c}_{u3BHA_r} = \begin{cases} \bar{r}_{cp}(\bar{d}_{3BHA}) \cdot (1 - R_{L,cp}(Z, 1)) - \frac{\bar{H}_T(Z, 1)}{2 \cdot \bar{r}_{cp}(\bar{d}_{3BHA})} & \text{if } BHA = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\alpha_{3BHA_r} = \begin{cases} \text{triangle}\left(\bar{c}_{a1BHA_r}, \bar{c}_{u1BHA_r}\right) & \text{if } BHA = 1 \\ \frac{\pi}{2} & \text{otherwise} \end{cases}$$

$$c_{a3BHA_r} = \bar{c}_{a1BHA_r} \cdot u_{1\text{пер}}$$

$$c_{u3BHA_r} = \frac{c_{a3BHA_r}}{\tan(\alpha_{3BHA_r})}$$

$$c_{3BHA_r} = \frac{c_{a3BHA_r}}{\sin(\alpha_{3BHA_r})}$$

$$\lambda_{c3BHA_r} = \frac{c_{3BHA_r}}{a_{kp3BHA_r}}$$

$$\text{submatrix}\left(T^*_{1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (288.2)$$

$$\text{submatrix}\left(T^*_{3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (288.2)$$

$$\text{submatrix}\left(P^*_{1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (101.3) \cdot 10^3$$

$$\text{submatrix}\left(P^*_{3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (101.3) \cdot 10^3$$

$$\text{submatrix}\left(\rho^*_{1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.224)$$

$$\text{submatrix}\left(\rho^*_{3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.224)$$

$$\text{submatrix}\left(k_{1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.401)$$

$$\text{submatrix}\left(k_{3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.401)$$

$$\text{submatrix}\left(a_{kp1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (310.8)$$

$$\text{submatrix}\left(a_{kp3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (310.8)$$

$$\text{submatrix}\left(\bar{c}_{a1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.335)$$

$$\text{submatrix}\left(\bar{c}_{a3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.335)$$

$$\text{submatrix}\left(\bar{c}_{u1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.000)$$

$$\text{submatrix}\left(\bar{c}_{u3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.000)$$

$$\text{submatrix}\left(c_{a1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (142.7)$$

$$\text{submatrix}\left(c_{a3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (142.7)$$

$$\text{submatrix}\left(c_{u1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.0)$$

$$\text{submatrix}\left(c_{u3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.0)$$

$$\text{submatrix}\left(c_{1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (142.7)$$

$$\text{submatrix}\left(c_{3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (142.7)$$

$$\text{submatrix}\left(\lambda_{c1BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.459)$$

$$\text{submatrix}\left(\lambda_{c3BHA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.459)$$

		$\left(\begin{matrix} F_{1BHA} \\ F_{3BHA} \end{matrix} \right) = G \cdot \sqrt{R_B} \cdot \left(\begin{matrix} \frac{\sqrt{T^*_{1BHA_r}}}{m_q(k_{1BHA_r}) \cdot P^*_{1BHA_r} \cdot \Gamma \Delta \Phi("G", \lambda_{c1BHA_r}, k_{1BHA_r}) \cdot \sin(\alpha_{1BHA_r})} \\ \frac{\sqrt{T^*_{3BHA_r}}}{m_q(k_{3BHA_r}) \cdot P^*_{3BHA_r} \cdot \Gamma \Delta \Phi("G", \lambda_{c3BHA_r}, k_{3BHA_r}) \cdot \sin(\alpha_{3BHA_r})} \end{matrix} \right)$
		$\epsilon_{BHA_r} = -1 \cdot (\alpha_{3BHA_r} - \alpha_{1BHA_r})$
	$\left(\begin{matrix} \alpha_{1BHA} & \alpha_{3BHA} \\ \sigma_{BHA} & \sigma_{BHA} \\ \overline{d}_{1BHA} & \overline{d}_{3BHA} \\ T^*_{1BHA} & T^*_{3BHA} \\ P^*_{1BHA} & P^*_{3BHA} \\ \rho^*_{1BHA} & \rho^*_{3BHA} \\ k_{1BHA} & k_{3BHA} \\ a_{kp1BHA} & a_{kp3BHA} \\ \overline{c}_{a1BHA} & \overline{c}_{a3BHA} \\ \overline{c}_{u1BHA} & \overline{c}_{u3BHA} \\ c_{a1BHA} & c_{a3BHA} \\ c_{u1BHA} & c_{u3BHA} \\ c_{1BHA} & c_{3BHA} \\ \lambda_{c1BHA} & \lambda_{c3BHA} \\ F_{1BHA} & F_{3BHA} \\ \epsilon_{BHA} & \epsilon_{BHA} \end{matrix} \right)$	

R_L	π^*	
K_H	η^*	
C_p	k	
\bar{H}_T	H_T	
L^*	\underline{L}	
T^*	\underline{T}	
P^*	P	
ρ^*	ρ	
a^*_c	a_{3B}	
λ_c	λ_c	
\underline{F}	F	$= r = av(N_r)$
D	\underline{R}	$T^*_{st(1,1),r} = T^*_{3BHA_r}$
\bar{d}	h	$P^*_{st(1,1),r} = P^*_{3BHA_r}$
\bar{c}_a	\bar{c}_u	$\rho^*_{st(1,1),r} = \rho^*_{3BHA_r}$
c_a	c_u	$C_{p_{st(1,1),r}} = C_{p_{\text{БорзДyx}}}(P^*_{st(1,1),r}, T^*_{st(1,1),r})$
u	w_u	$k_{st(1,1),r} = k_{a\Delta}(C_{p_{st(1,1),r}}, R_B)$
\underline{c}	w	$a^*_{c_{st(1,1),r}} = a_{kp}(k_{st(1,1),r}, R_B, T^*_{st(1,1),r})$
M_c	M_w	$\bar{c}_{a_{st(1,1),r}} = \bar{c}_{a3BHA_r}$
α	β	$\bar{c}_{u_{st(1,1),r}} = \bar{c}_{u3BHA_r}$
ϵ_{rotor}	ϵ_{stator}	$c_{a_{st(1,1),r}} = c_{a3BHA_r}$
		$u_{st(1,1),N_r} = u_{1пер}$
		$\alpha_{st(1,1),r} = \alpha_{3BHA_r}$
		$c_{st(1,1),r} = \frac{c_{a_{st(1,1),r}}}{\sin(\alpha_{st(1,1),r})}$
		$\lambda_{c_{st(1,1),r}} = \frac{c_{st(1,1),r}}{a^*_{c_{st(1,1),r}}}$
		$F_{st(1,1)} = \frac{G \cdot \sqrt{R_B \cdot T^*_{st(1,1),r}}}{m_q(k_{st(1,1),r}) \cdot \Gamma \Delta \Phi("G", \lambda_{c_{st(1,1),r}}, k_{st(1,1),r}) \cdot \sin(\alpha_{st(1,1),r}) \cdot P^*_{st(1,1),r}}$

$$D_{\text{st}(1,1),N_r} = \frac{2 \cdot u_{\text{st}(1,1),N_r}}{\omega}$$

$$D_{\text{st}(1,1),1} = \sqrt{\left(D_{\text{st}(1,1),N_r}\right)^2 - \frac{4 \cdot F_{\text{st}(1,1)}}{\pi}}$$

$$D_{\text{st}(1,1),r} = \overline{r}_{\text{cp}}\left(\frac{D_{\text{st}(1,1),1}}{D_{\text{st}(1,1),N_r}}\right) \cdot D_{\text{st}(1,1),N_r}$$

$$\overline{d}_{\text{st}(1,1)} = \frac{D_{\text{st}(1,1),1}}{D_{\text{st}(1,1),N_r}}$$

for i ∈ 1..Z

 trace(concat("ступень i = ",num2str(i)))

$$\begin{pmatrix} \overline{H}_{T_i} \\ K_{H_i} \\ \eta^*_{i} \\ R_{L_{i,r}} \end{pmatrix} = \begin{pmatrix} \overline{H}_{.T}(Z,i) \\ K_{.H}(Z,i) \\ \eta^*_{.}(Z,i) \\ R_{L.cp}(Z,i) \end{pmatrix}$$

$$H_{T_{i,r}} = \overline{H}_{T_i} \cdot \left(u_{\text{st}(i,1),N_r}\right)^2$$

$$L_i = K_{H_i} \cdot H_{T_{i,r}}$$

$$L^*_{i} = L_i \cdot \eta^*_{i}$$

$$\text{iteration}_{12} = 0$$

$$k_{\text{st}(i,2),r} = k_{\text{st}(i,1),r}$$

while 0 < 1

$$\text{iteration}_{12} = \text{iteration}_{12} + 1$$

 trace\Big(concat\Big(" iteration.12 = ",num2str\Big(\text{iteration}_{12}\Big)\Big)\Big)

$$k_{12} = \text{mean}\Big(k_{\text{st}(i,1),r},k_{\text{st}(i,2),r}\Big)$$

$$Cp_{12} = \frac{k_{12}}{k_{12}-1} \cdot R_B$$

$$T^*_{\text{st}(i,2),r} = T^*_{\text{st}(i,1),r} + \frac{L_i}{Cp_{12}}$$

$$\pi^*_{i} = \left(1 + \frac{L^*_{i}}{Cp_{12} \cdot T^*_{\text{st}(i,1),r}}\right)^{\frac{k_{12}}{k_{12}-1}}$$

$$P^*_{\text{st}(i,2),r} = P^*_{\text{st}(i,1),r} \cdot \pi^*_{i}$$

$$Cp_{\text{st}(i,2),r} = Cp_{\text{medium}}\Big(P^*_{\text{st}(i,2),r},T^*_{\text{st}(i,2),r}\Big)$$

1 st(i, 2), r = k'2
1 BO3ДУХ\ st(i, 2), r = k'2
st(i, 2), r = k'2

$$k'_2 = k_{a\text{Д}}\left(C_{\text{Pst}(i, 2), r}, R_{\text{Б}}\right)$$

$$\text{if } \left| \text{eps}\left(\text{"rel"}, k_{\text{st}(i, 2), r}, k'_2\right) \right| < \text{epsilon}$$

$$k_{\text{st}(i, 2), r} = k'_2$$

break

$$k_{\text{st}(i, 2), r} = k'_2$$

$$a^*_{c_{\text{st}(i, 2), r}} = a_{\text{КП}}\left(k_{\text{st}(i, 2), r}, R_{\text{Б}}, T^*_{\text{st}(i, 2), r}\right)$$

$$T^*_{\text{st}(i, 3), r} = T^*_{\text{st}(i, 2), r}$$

$$P^*_{\text{st}(i, 3), r} = P^*_{\text{st}(i, 2), r}$$

$$C_{\text{Pst}(i, 3), r} = C_{\text{BO3ДУХ}}\left(P^*_{\text{st}(i, 3), r}, T^*_{\text{st}(i, 3), r}\right)$$

$$k_{\text{st}(i, 3), r} = k_{a\text{Д}}\left(C_{\text{Pst}(i, 3), r}, R_{\text{Б}}\right)$$

$$a^*_{c_{\text{st}(i, 3), r}} = a_{\text{КП}}\left(k_{\text{st}(i, 3), r}, R_{\text{Б}}, T^*_{\text{st}(i, 3), r}\right)$$

$$\overline{c}_{a_{\text{st}(i, 3), r}} = \overline{c}_{.a1}(Z, i + 1)$$

$$\text{iteration}_3 = 0$$

$$\begin{pmatrix} \alpha_{\text{st}(i, 3), r} \\ u_{\text{st}(i, 3), N_{\text{r}}} \end{pmatrix} = \begin{pmatrix} \alpha_{\text{st}(i, 1), r} \\ u_{\text{st}(i, 1), N_{\text{r}}} \end{pmatrix}$$

$$c_{a_{\text{st}(i, 3), r}} = \overline{c}_{a_{\text{st}(i, 3), r}} \cdot u_{\text{st}(i, 3), N_{\text{r}}}$$

$$c_{\text{st}(i, 3), r} = \frac{c_{a_{\text{st}(i, 3), r}}}{\sin\left(\alpha_{\text{st}(i, 3), r}\right)}$$

$$\lambda_{\text{c}_{\text{st}(i, 3), r}} = \frac{c_{\text{st}(i, 3), r}}{a^*_{c_{\text{st}(i, 3), r}}}$$

$$F_{\text{st}(i, 3)} = \frac{F_{\text{st}(i, 1)} \cdot m_{\text{q}}\left(k_{\text{st}(i, 1), r}\right) \cdot \Gamma \text{Д} \Phi\left(\text{"G"}, \lambda_{\text{c}_{\text{st}(i, 1), r}}, k_{\text{st}(i, 1), r}\right) \cdot \sin\left(\alpha_{\text{st}(i, 1), r}\right) \cdot P^*_{\text{st}(i, 1), r} \sqrt{T^*_{\text{st}(i, 3), r}}}{m_{\text{q}}\left(k_{\text{st}(i, 3), r}\right) \cdot \Gamma \text{Д} \Phi\left(\text{"G"}, \lambda_{\text{c}_{\text{st}(i, 3), r}}, k_{\text{st}(i, 3), r}\right) \cdot \sin\left(\alpha_{\text{st}(i, 3), r}\right) \cdot P^*_{\text{st}(i, 3), r} \sqrt{T^*_{\text{st}(i, 1), r}}}$$

while 0 < 1

$$\text{iteration}_3 = \text{iteration}_3 + 1$$

$$\text{trace}\left(\text{concat}\left(\text{" iteration.3 = "}, \text{num2str}\left(\text{iteration}_3\right)\right)\right)$$

$$\text{if } \left(3\Pi\Pi\Pi_i \neq \text{"пер"}\right) \wedge \left(3\Pi\Pi\Pi_i \neq \text{"кор"}\right) \wedge \left(3\Pi\Pi\Pi_i \neq \text{"cp"}\right)$$

$$D_{\text{st}(i, 3), N_{\text{r}}} = D_{\text{st}(i, 1), N_{\text{r}}} \cdot \text{str2num}\left(3\Pi\Pi\Pi_i\right)$$

$$D_{\text{st}(i, 3), 1} = \sqrt{\left(D_{\text{st}(i, 3), N_{\text{r}}}\right)^2 - \frac{4F_{\text{st}(i, 3)}}{\pi}}$$

$$\text{if } 3\Pi\Pi\Pi_i = \text{"пер"}$$

$$\left| \begin{array}{l} D_{\text{st}(i,3),N_r} = D_{\text{st}(i,1),N_r} \\ D_{\text{st}(i,3),1} = \sqrt{\left(D_{\text{st}(i,3),N_r}\right)^2 - \frac{4F_{\text{st}(i,3)}}{\pi}} \end{array} \right.$$

if $3\Pi\Pi\Pi_i = \text{"kop"}$

$$\left| \begin{array}{l} D_{\text{st}(i,3),1} = D_{\text{st}(i,1),1} \\ D_{\text{st}(i,3),N_r} = \sqrt{\left(D_{\text{st}(i,3),1}\right)^2 + \frac{4F_{\text{st}(i,3)}}{\pi}} \end{array} \right.$$

if $3\Pi\Pi\Pi_i = \text{"cp"}$

$$\left| \begin{array}{l} D_{\text{st}(i,3),N_r} = \sqrt{\left(D_{\text{st}(i,1),r}\right)^2 + \frac{2F_{\text{st}(i,3)}}{\pi}} \\ D_{\text{st}(i,3),1} = \sqrt{\left(D_{\text{st}(i,1),r}\right)^2 - \frac{2F_{\text{st}(i,3)}}{\pi}} \end{array} \right.$$

$$\overline{d}_{\text{st}(i,3)} = \frac{D_{\text{st}(i,3),1}}{D_{\text{st}(i,3),N_r}}$$

$$D_{\text{st}(i,3),r} = \overline{r}_{\text{cp}}(\overline{d}_{\text{st}(i,3)}) \cdot D_{\text{st}(i,3),N_r}$$

$$\overline{c}_{u_{\text{st}(i,3),r}} = \overline{r}_{\text{cp}}(\overline{d}_{\text{st}(i,3)}) \cdot \left(1 - R_{\text{L.cp}}(Z,i+1)\right) - \frac{\overline{H}.T(Z,i+1)}{2 \cdot \overline{r}_{\text{cp}}(\overline{d}_{\text{st}(i,3)})}$$

$$\alpha_{\text{st}(i,3),r} = \left| \begin{array}{l} \text{atan}\left(\frac{\overline{c}_{a_{\text{st}(i,3),r}}}{\overline{c}_{u_{\text{st}(i,3),r}}}\right) \quad \text{if } \text{atan}\left(\frac{\overline{c}_{a_{\text{st}(i,3),r}}}{\overline{c}_{u_{\text{st}(i,3),r}}}\right) \geq 0 \\ \text{atan}\left(\frac{\overline{c}_{a_{\text{st}(i,3),r}}}{\overline{c}_{u_{\text{st}(i,3),r}}}\right) + 2\pi \quad \text{otherwise} \end{array} \right.$$

$$u_{\text{st}(i,3),N_r} = u_{\text{st}(i,1),N_r} \cdot \frac{D_{\text{st}(i,3),N_r}}{D_{\text{st}(i,1),N_r}}$$

$$c_{a_{\text{st}(i,3),r}} = \overline{c}_{a_{\text{st}(i,3),r}} \cdot u_{\text{st}(i,3),N_r}$$

$$c_{\text{st}(i,3),r} = \frac{c_{a_{\text{st}(i,3),r}}}{\sin(\alpha_{\text{st}(i,3),r})}$$

$$\lambda_{c_{\text{st}(i,3),r}} = \frac{c_{\text{st}(i,3),r}}{a^* c_{\text{st}(i,3),r}}$$

$$F'_3 = \frac{G \cdot \sqrt{R_B \cdot T^*_{\text{st}(i,3),r}}}{m_q(k_{\text{st}(i,3),r}) \cdot \Gamma \mathcal{D} \Phi\left("G", \lambda_{c_{\text{st}(i,3),r}}, k_{\text{st}(i,3),r}\right) \cdot \sin(\alpha_{\text{st}(i,3),r}) \cdot P^*_{\text{st}(i,3),r}}$$

break if $\left(\left|\text{eps}(\text{"rel"}, F'_3, F_{\text{st}(i,3)})\right| < \text{epsilon}\right) \wedge \left(\text{iteration}_3 = 0\right)$

$\text{iteration}_3 = -1$ if $\left(\left|\text{eps}(\text{"rel"}, F'_3, F_{\text{st}(i,3)})\right| < \text{epsilon}\right)$

```

Fst(i,3) = F'3
 $\overline{c}_{a_{st(i,2)},r} = \text{mean}(\overline{c}_{a_{st(i,1)},r}, \overline{c}_{a_{st(i,3)},r})$ 
iteration2 = 0
Fst(i,2) = mean(Fst(i,1), Fst(i,3))
while 0 < 1
    iteration2 = iteration2 + 1
    trace(concat(" iteration.2 = ", num2str(iteration2)))
    if (ЗПППЧi ≠ "nep") ∧ (ЗПППЧi ≠ "kop") ∧ (ЗПППЧi ≠ "cp")
         $D_{st(i,2),N_r} = \text{mean}(D_{st(i,1),N_r}, D_{st(i,3),N_r})$ 
         $\overline{d}_{st(i,2)} = \sqrt{2 \cdot \text{mean}(\overline{r}_{cp}(\overline{d}_{st(i,1)}), \overline{r}_{cp}(\overline{d}_{st(i,3)}))^2 - 1}$ 
         $D_{st(i,2),r} = D_{st(i,2),N_r} \cdot \overline{r}_{cp}(\overline{d}_{st(i,2)})$ 
         $D_{st(i,2),l} = \overline{d}_{st(i,2)} \cdot D_{st(i,2),N_r}$ 
    if ЗПППЧi = "nep"
         $D_{st(i,2),N_r} = D_{st(i,1),N_r}$ 
         $\overline{d}_{st(i,2)} = \sqrt{2 \cdot \text{mean}(\overline{r}_{cp}(\overline{d}_{st(i,1)}), \overline{r}_{cp}(\overline{d}_{st(i,3)}))^2 - 1}$ 
         $D_{st(i,2),r} = D_{st(i,2),N_r} \cdot \overline{r}_{cp}(\overline{d}_{st(i,2)})$ 
         $D_{st(i,2),l} = \overline{d}_{st(i,2)} \cdot D_{st(i,2),N_r}$ 
    if ЗПППЧi = "kop"
         $D_{st(i,2),l} = D_{st(i,1),l}$ 
         $\overline{d}_{st(i,2)} = \sqrt{2 \cdot \text{mean}(\overline{r}_{cp}(\overline{d}_{st(i,1)}), \overline{r}_{cp}(\overline{d}_{st(i,3)}))^2 - 1}$ 
         $D_{st(i,2),N_r} = \frac{D_{st(i,2),l}}{\overline{d}_{st(i,2)}}$ 
         $D_{st(i,2),r} = D_{st(i,2),N_r} \cdot \overline{r}_{cp}(\overline{d}_{st(i,2)})$ 
    if ЗПППЧi = "cp"
         $D_{st(i,2),r} = D_{st(i,1),r}$ 
         $\overline{d}_{st(i,2)} = \sqrt{2 \cdot \text{mean}(\overline{r}_{cp}(\overline{d}_{st(i,1)}), \overline{r}_{cp}(\overline{d}_{st(i,3)}))^2 - 1}$ 
         $D_{st(i,2),N_r} = \frac{D_{st(i,2),r}}{\overline{r}_{cp}(\overline{d}_{st(i,2)})}$ 
         $D_{st(i,2),l} = \overline{d}_{st(i,2)} \cdot D_{st(i,2),N_r}$ 

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$$\overline{c}_{u_{st(i,2),r}} = \frac{1}{\overline{r}_{cp}(\overline{d}_{st(i,2)})} \left(\frac{\nu_{st(i,1),N_r}}{D_{st(i,2),N_r}} \right) \cdot \left(\overline{H}_{T_i} + \overline{c}_{u_{st(i,1),r}} \cdot \frac{D_{st(i,1),r}}{D_{st(i,1),N_r}} \right)$$

$$\alpha_{st(i,2),r} = \text{triangle}\Big(\overline{c}_{a_{st(i,2),r}}, \overline{c}_{u_{st(i,2),r}}\Big)$$

$$u_{st(i,2),N_r} = u_{st(i,1),N_r} \cdot \frac{D_{st(i,2),N_r}}{D_{st(i,1),N_r}}$$

$$c_{a_{st(i,2),r}} = \overline{c}_{a_{st(i,2),r}} \cdot u_{st(i,2),N_r}$$

$$c_{st(i,2),r} = \frac{c_{a_{st(i,2),r}}}{\sin(\alpha_{st(i,2),r})}$$

$$\lambda_{c_{st(i,2),r}} = \frac{c_{st(i,2),r}}{a^*_{c_{st(i,2),r}}}$$

$$F'_2 = \frac{G \cdot \sqrt{R_B \cdot T^*_{st(i,2),r}}}{m_q(k_{st(i,2),r}) \cdot \Gamma \mathcal{D} \Phi\Big("G", \lambda_{c_{st(i,2),r}}, k_{st(i,2),r} \Big) \cdot \sin(\alpha_{st(i,2),r}) \cdot P^*_{st(i,2),r}}$$

$$\text{break if } \Big(\left|\text{eps}\Big("rel", F'_2, F_{st(i,2)} \Big)\right| < \text{epsilon}\Big) \wedge \Big(\text{iteration}_2 = 0\Big)$$

$$\text{iteration}_2 = -1 \quad \text{if } \Big(\left|\text{eps}\Big("rel", F'_2, F_{st(i,2)} \Big)\right| < \text{epsilon}\Big)$$

$$F_{st(i,2)} = F'_2$$

for a ∈ 1 .. 3

$$\rho^*_{st(i,a),r} = \frac{P^*_{st(i,a),r}}{R_B \cdot T^*_{st(i,a),r}}$$

$$T_{st(i,a),r} = T^*_{st(i,a),r} \cdot \Gamma \mathcal{D} \Phi\Big("T", \lambda_{c_{st(i,a),r}}, k_{st(i,a),r} \Big)$$

$$P_{st(i,a),r} = P^*_{st(i,a),r} \cdot \Gamma \mathcal{D} \Phi\Big("P", \lambda_{c_{st(i,a),r}}, k_{st(i,a),r} \Big)$$

$$\rho_{st(i,a),r} = \rho^*_{st(i,a),r} \cdot \Gamma \mathcal{D} \Phi\Big(" \rho", \lambda_{c_{st(i,a),r}}, k_{st(i,a),r} \Big)$$

$$a_{3B_{st(i,a),r}} = \sqrt{k_{st(i,a),r} \cdot R_B \cdot T_{st(i,a),r}}$$

$$\beta_{st(i,a),r} = \text{triangle}\Big(\overline{c}_{a_{st(i,a),r}}, \overline{r}_{cp}(\overline{d}_{st(i,a)}) - \overline{c}_{u_{st(i,a),r}}\Big)$$

$$w_{st(i,a),r} = \frac{c_{a_{st(i,a),r}}}{\sin(\beta_{st(i,a),r})}$$

$$w_{u_{st(i,a),r}} = w_{st(i,a),r} \cdot \cos(\beta_{st(i,a),r})$$

$$c_{u_{st(i,a),r}} = c_{st(i,a),r} \cdot \cos(\alpha_{st(i,a),r})$$

$$M_{w_{st(i,a),r}} = \frac{w_{st(i,a),r}}{a_{3B_{st(i,a),r}}}$$

$$u_{st(i,a),r} = c_{st(i,a),r}$$

$$M_{c_{st(i,a),r}} = \overline{a_{3B_{st(i,a),r}}}$$

$$h_{st(i,a)} = 0.5 \cdot \left(D_{st(i,a),N_r} - D_{st(i,a),1} \right)$$

for radius $\in 1..N_r$

$$u_{st(i,a),radius} = \omega \cdot \frac{D_{st(i,a),radius}}{2}$$

$$\begin{pmatrix} \epsilon_{rotor_{i,av(N_r)}} \\ \epsilon_{stator_{i,av(N_r)}} \end{pmatrix} = \begin{pmatrix} \beta_{st(i,2),av(N_r)} - \beta_{st(i,1),av(N_r)} \\ \alpha_{st(i,3),av(N_r)} - \alpha_{st(i,2),av(N_r)} \end{pmatrix}$$

for i $\in 1..Z$

for a $\in 1..3$

for r $\in 1..N_r$

$$R_{st(i,a),r} = 0.5 \cdot D_{st(i,a),r}$$

$$\begin{pmatrix} R_L & K_H & C_p & \bar{H}_T & L^* & T^* & P^* & \rho^* & a^*_c & \lambda_c & F & D & \bar{d} & \bar{c}_a & c_a & u & c & M_c & \alpha & \epsilon_{rotor} \\ \pi^* & \eta^* & k & H_T & L & T & P & \rho & a_{3B} & \lambda_c & F & R & h & \bar{c}_u & c_u & w_u & w & M_w & \beta & \epsilon_{stator} \end{pmatrix}^T$$

$$\left(\rho^*_{3CA_r}\right) = \frac{1}{R_B} \cdot \left(\frac{P^*_{3CA_r}}{T^*_{3CA_r}}\right)$$

$$\begin{pmatrix} k_{1CA_r} \\ k_{3CA_r} \end{pmatrix} = \begin{pmatrix} k_{aд}\left(Cp_{\text{воздух}}\left(P^*_{1CA_r}, T^*_{1CA_r}\right), R_B\right) \\ k_{aд}\left(Cp_{\text{воздух}}\left(P^*_{3CA_r}, T^*_{3CA_r}\right), R_B\right) \end{pmatrix}$$

$$\begin{pmatrix} a_{kp1CA_r} \\ a_{kp3CA_r} \end{pmatrix} = \begin{pmatrix} a_{kp}\left(k_{1CA_r}, R_B, T^*_{1CA_r}\right) \\ a_{kp}\left(k_{3CA_r}, R_B, T^*_{3CA_r}\right) \end{pmatrix}$$

$$\overline{c}_{a1CA_r} = \overline{c}_{a_{st(Z,3)},r}$$

$$\overline{c}_{a3CA_r} = \overline{c}_{.a1}(Z, Z + 1)$$

$$\overline{c}_{u1CA_r} = \overline{c}_{u_{st(Z,3)},r}$$

$$\overline{c}_{u3CA_r} = \begin{cases} 0 & \text{if } CA = 1 \\ \overline{c}_{u1CA_r} & \text{otherwise} \end{cases}$$

$$c_{a1CA_r} = \overline{c}_{a3CA_r} \cdot u_{st(Z,3),N_r}$$

$$c_{a3CA_r} = c_{a1CA_r} - \begin{cases} 10 & \text{if } CA = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{pmatrix} c_{u1CA_r} \\ c_{u3CA_r} \end{pmatrix} = \begin{pmatrix} \frac{c_{a1CA_r}}{\tan(\alpha_{1CA_r})} \\ \frac{c_{a3CA_r}}{\tan(\alpha_{3CA_r})} \end{pmatrix}$$

$$\begin{pmatrix} c_{1CA_r} \\ c_{3CA_r} \end{pmatrix} = \begin{pmatrix} \frac{c_{a1CA_r}}{\sin(\alpha_{1CA_r})} \\ \frac{c_{a3CA_r}}{\sin(\alpha_{3CA_r})} \end{pmatrix}$$

$$\begin{pmatrix} \lambda_{1CA_r} \\ \lambda_{3CA_r} \end{pmatrix} = \begin{pmatrix} \frac{c_{1CA_r}}{a_{kp1CA_r}} \\ \frac{c_{3CA_r}}{a_{kp3CA_r}} \end{pmatrix}$$

$$\sigma'_{CA} = \begin{cases} 1 - \text{mean}(0.25, 0.5) \cdot \Gamma\text{Д}\Phi\left("p", \lambda_{3CA_r}, k_{3CA_r}\right) \cdot \frac{k_{3CA_r}}{k_{3CA_r} + 1} \cdot \left(\lambda_{3CA_r}\right)^2 & \text{if } CA = 1 \end{cases}$$

$$\text{submatrix}\left(T^*_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (337.1)$$

$$\text{submatrix}\left(T^*_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (337.1)$$

$$\text{submatrix}\left(P^*_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (163.0) \cdot 10^3$$

$$\text{submatrix}\left(P^*_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (163.0) \cdot 10^3$$

$$\text{submatrix}\left(\rho^*_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.684)$$

$$\text{submatrix}\left(\rho^*_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.684)$$

$$\text{submatrix}\left(k_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.399)$$

$$\text{submatrix}\left(k_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (1.399)$$

$$\text{submatrix}\left(a_{kp1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (336.0)$$

$$\text{submatrix}\left(a_{kp3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (336.0)$$

$$\text{submatrix}\left(\overline{c}_{a1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.265)$$

$$\text{submatrix}\left(\overline{c}_{a3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.265)$$

$$\text{submatrix}\left(\overline{c}_{u1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.211)$$

$$\text{submatrix}\left(\overline{c}_{u3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.211)$$

$$\text{submatrix}\left(c_{a1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (112.9)$$

$$\text{submatrix}\left(c_{a3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (112.9)$$

$$\text{submatrix}\left(c_{u1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (90.0)$$

$$\text{submatrix}\left(c_{u3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (90.0)$$

$$\text{submatrix}\left(c_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (144.4)$$

$$\text{submatrix}\left(c_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (144.4)$$

$$\text{submatrix}\left(\lambda_{1CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.430)$$

$$\text{submatrix}\left(\lambda_{3CA}, \text{av}\left(N_r\right), \text{av}\left(N_r\right), 1, 1\right) = (0.430)$$

$$\begin{array}{l} \quad \quad \quad | \quad 1 \quad \text{otherwise} \\ \text{break if } \left(\left| \text{eps}(\text{"rel"}, \sigma'_{CA}, \sigma_{CA}) \right| < \text{epsilon} \right) \wedge \left(\text{iterarion}_{CA} = 0 \right) \\ \text{iterarion}_{CA} = -1 \quad \text{if } \left(\left| \text{eps}(\text{"rel"}, \sigma'_{CA}, \sigma_{CA}) \right| < \text{epsilon} \right) \\ \sigma_{CA} = \sigma'_{CA} \end{array}$$

$$\begin{pmatrix} F_{1CA} \\ F_{3CA} \end{pmatrix} = \begin{pmatrix} F_{st}(Z, 3) \\ G \cdot \sqrt{R_B \cdot T^*_{3CA_r}} \\ \frac{m_q(k_{3CA_r}) \cdot P^*_{3CA_r} \cdot \Gamma_{\mathcal{D}} \Phi("G", \lambda_{3CA_r}, k_{3CA_r}) \cdot \sin(\alpha_{3CA_r})}{m_q(k_{3CA_r}) \cdot P^*_{3CA_r} \cdot \Gamma_{\mathcal{D}} \Phi("G", \lambda_{3CA_r}, k_{3CA_r}) \cdot \sin(\alpha_{3CA_r})} \end{pmatrix}$$

$$\left| \varepsilon_{CA_r} = \alpha_3 CA_r - \alpha_1 CA_r \right|$$

$$\left(\begin{array}{cc} \alpha_{1CA} & \alpha_{3CA} \\ \sigma_{CA} & \sigma_{CA} \\ \bar{d}_{1CA} & \bar{d}_{3CA} \\ T^*_{1CA} & T^*_{3CA} \\ P^*_{1CA} & P^*_{3CA} \\ \rho^*_{1CA} & \rho^*_{3CA} \\ k_{1CA} & k_{3CA} \\ a_{kp1CA} & a_{kp3CA} \\ \bar{c}_{a1CA} & \bar{c}_{a3CA} \\ \bar{c}_{u1CA} & \bar{c}_{u3CA} \\ c_{a1CA} & c_{a3CA} \\ c_{u1CA} & c_{u3CA} \\ c_{1CA} & c_{3CA} \\ \lambda_{1CA} & \lambda_{3CA} \\ F_{1CA} & F_{3CA} \\ \varepsilon_{CA} & \varepsilon_{CA} \end{array} \right)$$

Относ. погрешность расчета по массовому расходу (кг/с):

$\overline{\Delta G}$

=

for i ∈ 1..Z

for a ∈ 1..3

$\overline{\Delta G}_{st(i,a)} = \left| \text{eps}\left(\text{"rel"}, G, \rho_{st(i,a),av(N_r)} \cdot c_{a_{st(i,a),av(N_r)}} \cdot F_{st(i,a)} \right) \right|$

$\overline{\Delta G}$

$\overline{\Delta G}^T$ =

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
1	0.00	0.00	0.01																

.%

$\overline{\Delta G}^T < 1\%$ =

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
1	1	1	1																

Количество ступеней ОК:

Z = 1

Дискретизация сечений: ii = 1..2Z + 1

Дискретизация ступеней: i = 1..Z

π^{*T} =

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	1.609														

[16, с 114] $\pi^{*T} \leq 1.9$ =

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	1														

Полученная степень повышения полного давления []:

$$\prod_{i=1}^Z \pi^*_{i} = 1.609$$

Степень повышения давления в ЛА:

$$\pi^*_{\text{ЛА}} = \frac{P^*_{3CA_{av(N_r)}}}{P^*_{1BHA_{av(N_r)}} = 1.609$$

$$\pi^*_{\text{ЛА}} \geq \pi^*_{\text{К}} = 1$$

$H_T^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	51.62														
2	51.62														
3	51.62														

 $\cdot 10^3$

Действительная работа К (Дж/кг):
 $L_K = \sum_{i=1}^Z L_i = 49 \cdot 10^3$

Адиабатная работа К [Дж/кг]:
 $L^*_K = \sum_{i=1}^Z L^*_{i} = 42.2 \cdot 10^3$

Адиабатная КПД К []:

$\eta^*_K = \frac{L^*_K}{L_K} = 86.00\%$

Мощность К (Вт):
 $N_K = G \cdot L_K = 12.24 \cdot 10^6$

$\text{submatrix}\left(R_L, 1, Z, \text{av}\left(N_r\right), \text{av}\left(N_r\right)\right)^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.50														

$K_H^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.95														

$\eta^{*T} =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	86.00														

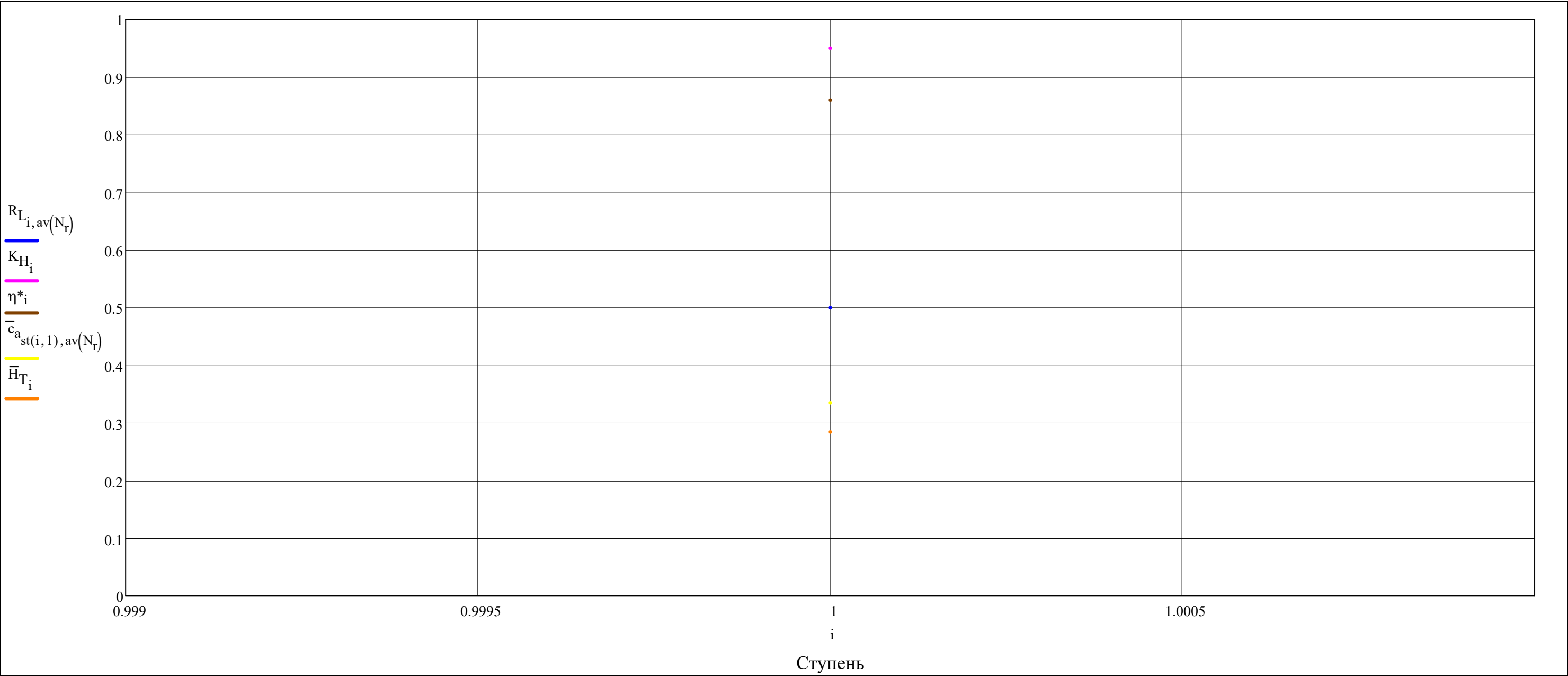
·%

$\text{submatrix}\left(\overline{c}_a, 1, 2Z + 1, \text{av}\left(N_r\right), \text{av}\left(N_r\right)\right)^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
1	0.335	0.300	0.265																	

$\overline{H}_T^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.28														



$$\text{submatrix}\Big(\text{Cp},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
1	1002.6	1006.0	1006.0																

$$\text{submatrix}\Big(\text{k},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
1	1.401	1.399	1.399																		

$$\text{submatrix}\Big(\text{T}^*,1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
1	288.2	337.1	337.1																		

$$\text{submatrix}\Big(\text{T},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
1	278	316.8	326.7																		

$$\text{submatrix}\Big(\text{P}^*,1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
1	101.3	163	163															

·10³

$$\text{submatrix}\Big(\text{P},1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
1	89.4	131.1	146.1															

·10³

$$\text{submatrix}\Big(\rho^*,1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

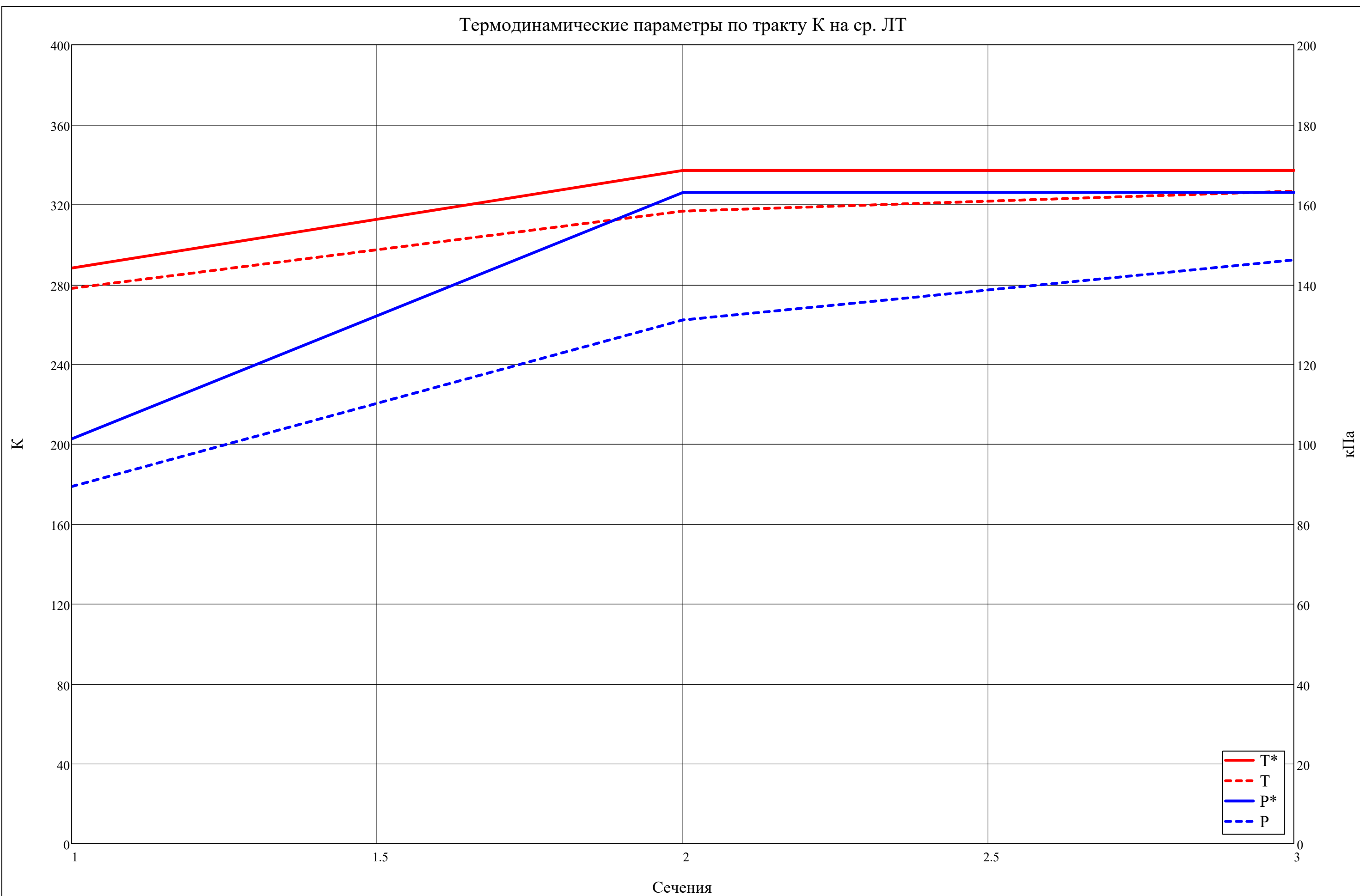
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
1	1.224	1.684	1.684																

$$\text{submatrix}\Big(\rho,1,2Z+1,\text{av}\Big(\text{N}_{\text{r}}\Big),\text{av}\Big(\text{N}_{\text{r}}\Big)\Big)^{\text{T}} =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
1	1.12	1.441	1.558																

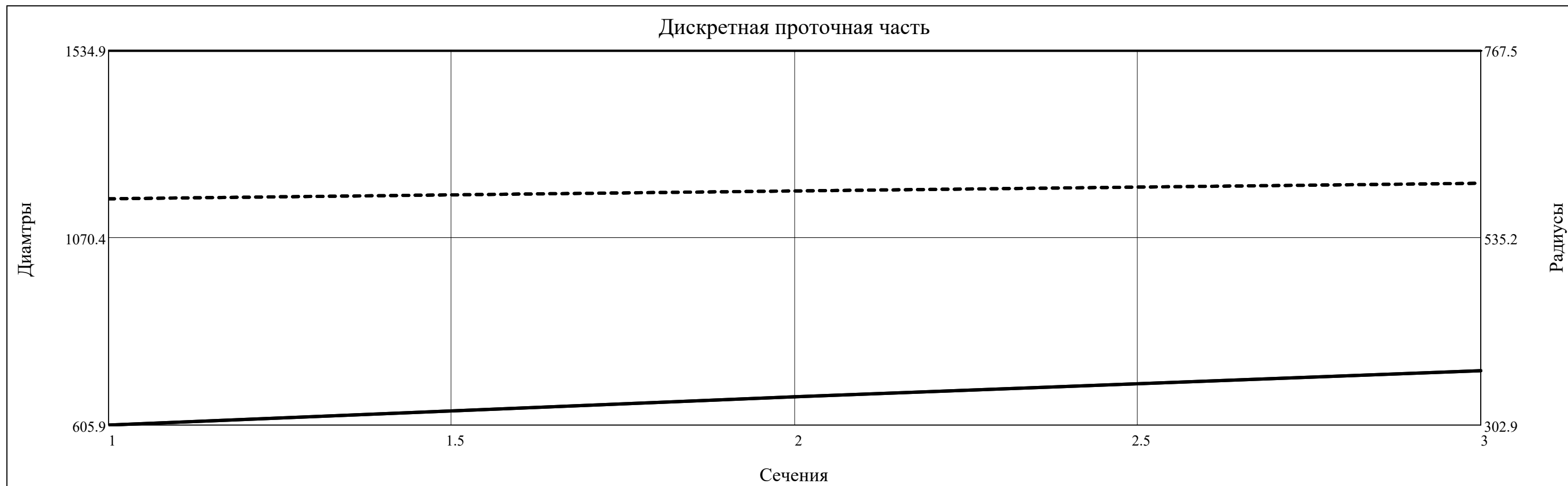
$$\textcolor{green}{k_{cp}} = k_{\text{ад}}\Big(\text{Cp}_{\text{воздух.ср}}\Big(\text{P}^*_{\text{st}(1,1)},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{P}^*_{\text{st}(Z,3)},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{T}^*_{\text{st}(1,1)},\text{av}\Big(\text{N}_{\text{r}}\Big),\text{T}^*_{\text{st}(Z,3)},\text{av}\Big(\text{N}_{\text{r}}\Big)\Big),\text{R}_{\text{B}}\Big) = 1.401$$

Термодинамические параметры по тракту К на ср. ЛТ



[illegible][illegible]
$$\overline{d}_{st}(Z, 3) = 0.4826$$
$$\overline{d}_{\text{st}}(Z, 3) \leq 0.9 = 1$$

$$\mathbf{D}^T = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 & 14 & 15 & 16 & 17 & 18 & 19 & 20 & 21 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{matrix} 605.9 & 676.2 & 740.8 & & & & & & & & & & & & & & & & & & & \end{matrix} \end{matrix} \cdot 10^{-3}$$

[illegible][illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

$$c_{a_{st}(Z,3),av(N_r)} = 112.87 \quad c_{a_{st}(Z,3),av(N_r)} \leq 130 = 1 \quad \text{Для КС}$$

[illegible]

[illegible]

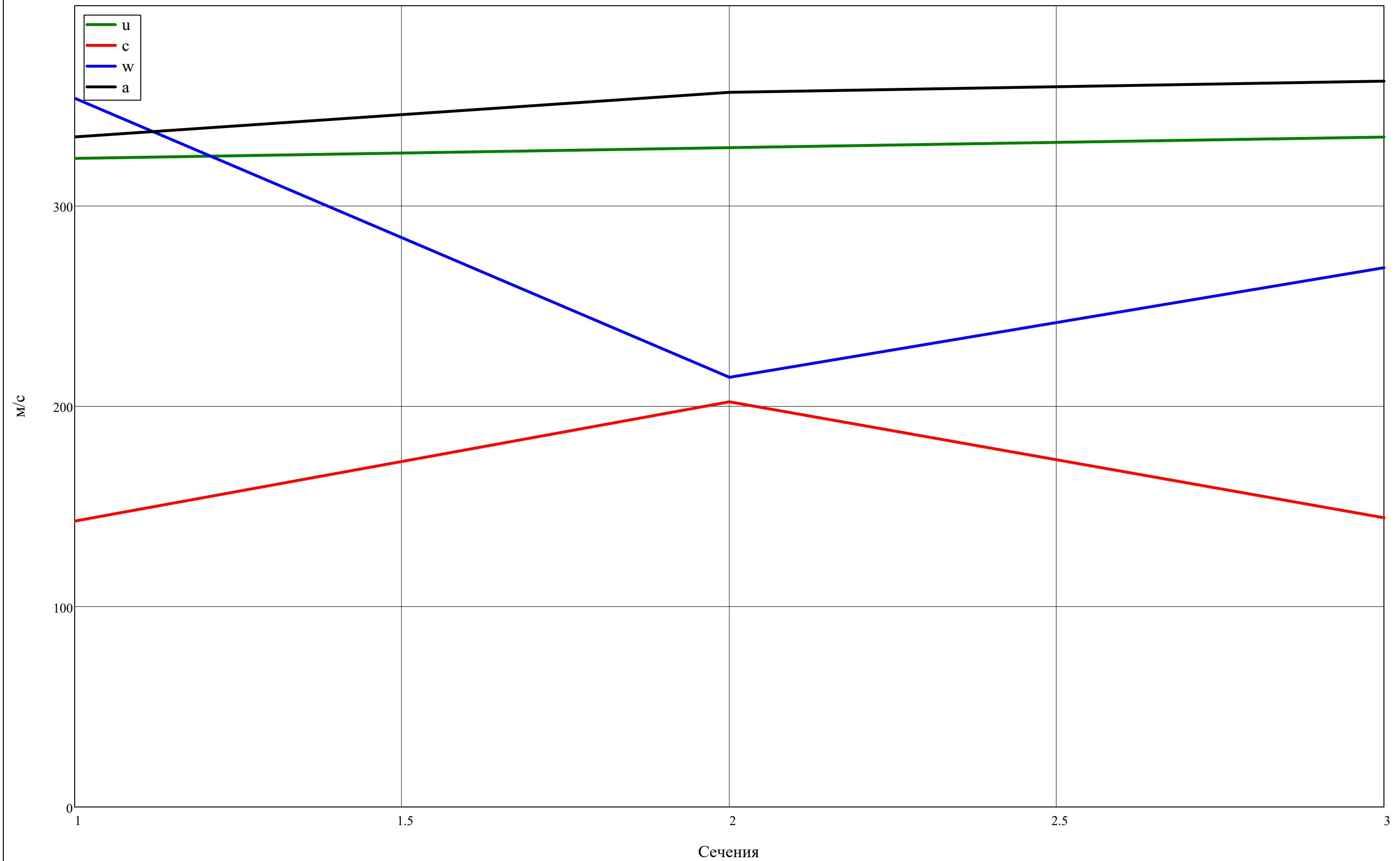
[illegible]

$$\Delta c_{a,i,av(N_r)} = \left(c_{a,st(i,2),av(N_r)} - c_{a,st(i,1),av(N_r)} \right)$$

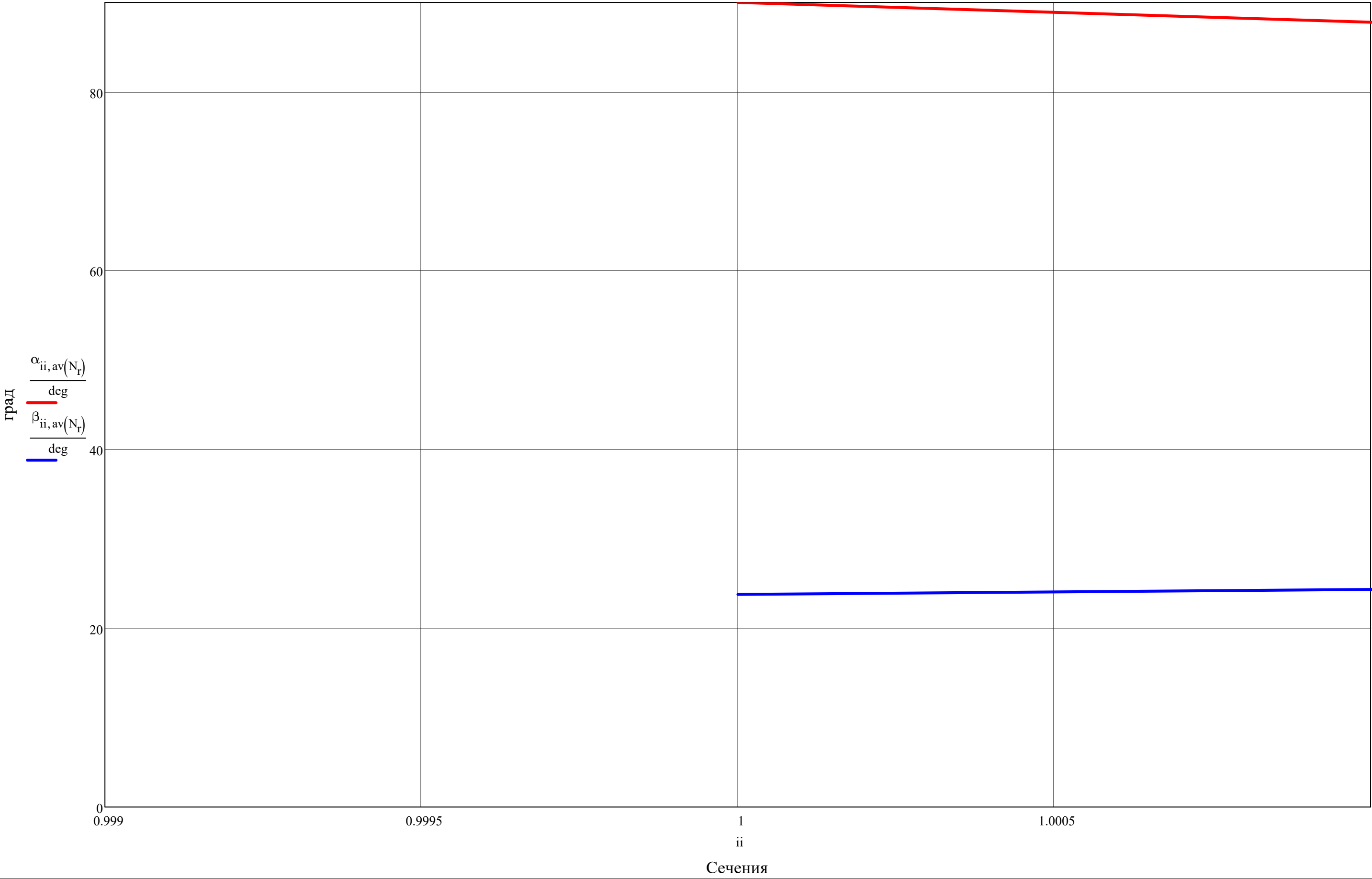
$$\text{submatrix}(\Delta c_a, 1, Z, \text{av}(N_r), \text{av}(N_r))^T = \begin{array}{c|cccccccccccc} & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ \hline 1 & -14.91 & & & & & & & & & & & \end{array}$$

[illegible]

Скорости по тракту К на ср. ЛТ



Углы по тракту К на ср. ЛТ



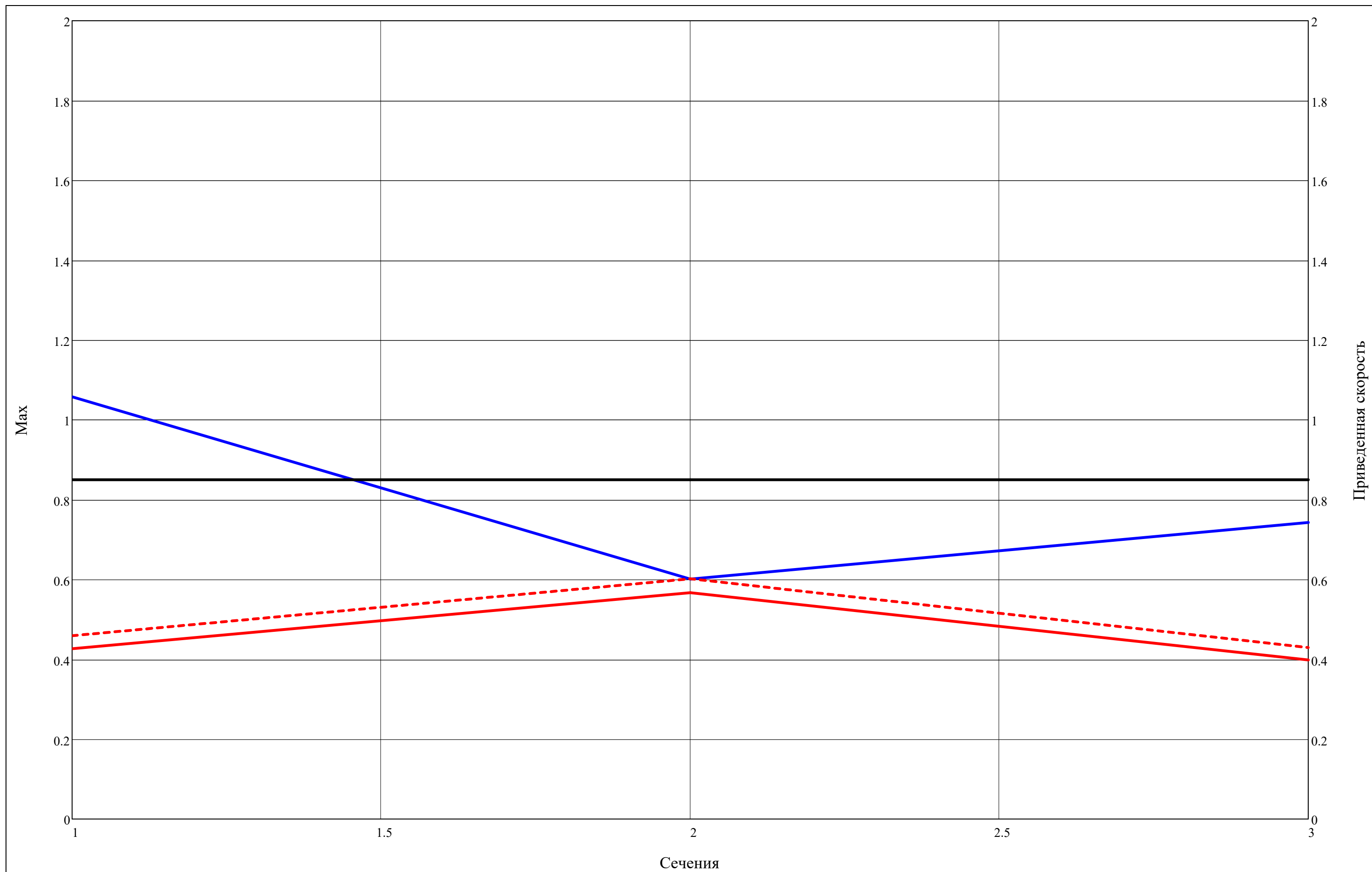
[illegible]

[16, c. 87] $\text{submatrix}(\lambda_{\mathbf{c}}, 1, 2Z + 1, \text{av}(\mathbf{N}_{\mathbf{r}}), \text{av}(\mathbf{N}_{\mathbf{r}}))^{\text{T}} \leq 0.85 =$

	1	2	3
1	1	1	1

[illegible]

[illegible]



$$\begin{pmatrix} T^*_{1BHA} & T^*_{3BHA} \\ P^*_{1BHA} & P^*_{3BHA} \\ \rho^*_{1BHA} & \rho^*_{3BHA} \\ C_{p1BHA} & C_{p3BHA} \\ k_{1BHA} & k_{3BHA} \\ a^*_{c1BHA} & a^*_{c3BHA} \\ c_{u1BHA} & c_{u3BHA} \\ c_{a1BHA} & c_{a3BHA} \\ \alpha_{1BHA} & \alpha_{3BHA} \\ c_{1BHA} & c_{3BHA} \\ \lambda_{c1BHA} & \lambda_{c3BHA} \\ \epsilon_{BHA} & \epsilon_{BHA} \end{pmatrix} = \begin{cases} \text{for } i \in 1 \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} T^*_{1BHA_r} \\ T^*_{3BHA_r} \end{pmatrix} = \begin{pmatrix} T^*_{1BHA_{av}(N_r)} \\ T^*_{3BHA_{av}(N_r)} \end{pmatrix} \\ \begin{pmatrix} P^*_{1BHA_r} \\ P^*_{3BHA_r} \end{pmatrix} = \begin{pmatrix} P^*_{1BHA_{av}(N_r)} \\ P^*_{3BHA_{av}(N_r)} \end{pmatrix} \\ \begin{pmatrix} \rho^*_{1BHA_r} \\ \rho^*_{3BHA_r} \end{pmatrix} = \begin{pmatrix} \rho^*_{1BHA_{av}(N_r)} \\ \rho^*_{3BHA_{av}(N_r)} \end{pmatrix} \\ \begin{pmatrix} C_{p1BHA_r} \\ C_{p3BHA_r} \end{pmatrix} = \begin{pmatrix} C_{p_{\text{воздух}}}(P^*_{1BHA_r}, T^*_{1BHA_r}) \\ C_{p_{\text{воздух}}}(P^*_{3BHA_r}, T^*_{3BHA_r}) \end{pmatrix} \\ \begin{pmatrix} k_{1BHA_r} \\ k_{3BHA_r} \end{pmatrix} = \begin{pmatrix} k_{ад}(C_{p1BHA_r}, R_B) \\ k_{ад}(C_{p3BHA_r}, R_B) \end{pmatrix} \\ \begin{pmatrix} a^*_{c1BHA_r} \\ a^*_{c3BHA_r} \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{2 \cdot k_{1BHA_r}}{k_{1BHA_r} + 1} \cdot R_B \cdot T^*_{1BHA_r}} \\ \sqrt{\frac{2 \cdot k_{3BHA_r}}{k_{3BHA_r} + 1} \cdot R_B \cdot T^*_{3BHA_r}} \end{pmatrix} \\ A = \left(1 - R_{L_{1, av}(N_r)}\right) \cdot \omega \cdot \left(R_{st(i, 1), av}(N_r)\right)^{m_i+1} \\ B = \frac{H_{T_{i, av}(N_r)}}{2 \cdot \omega} \\ \begin{pmatrix} c_{u1BHA_r} \\ c_{a1BHA_r} \end{pmatrix} = \begin{pmatrix} c_{u1BHA_{av}(N_r)} \\ c_{a1BHA_{av}(N_r)} \end{pmatrix} \end{cases}$$

$$\begin{aligned}
\begin{pmatrix} c_{1BHA_r} \\ c_{u3BHA_r} \end{pmatrix} &= \begin{bmatrix} \frac{A}{\left(R_{st(i,1),r}\right)^{m_i}} - \frac{B}{\left(R_{st(i,1),r}\right)} \text{ if } BHA = 1 \\ c_{u1BHA_{av}(N_r)} \text{ otherwise} \end{bmatrix} \\
\begin{pmatrix} c_{a1BHA_r} \\ c_{a3BHA_r} \end{pmatrix} &= \begin{bmatrix} c_{a1BHA_{av}(N_r)} \\ \begin{bmatrix} \text{if } BHA = 1 \\ \sqrt{\left(c_{a3BHA_{av}(N_r)}\right)^2 - 2 \cdot A^2 \cdot \left[\left(R_{st(i,1),r}\right)^2 - \left(R_{st(i,1),av(N_r)}\right)^2\right] + 4 \cdot A \cdot B \cdot \ln\left(\frac{R_{st(i,1),r}}{R_{st(i,1),av(N_r)}}\right)} \text{ if } m_i = -1 \\ \sqrt{\left(c_{a3BHA_{av}(N_r)}\right)^2 - 2 \cdot A^2 \cdot \ln\left(\frac{R_{st(i,1),r}}{R_{st(i,1),av(N_r)}}\right) - 2 \cdot A \cdot B \cdot \left(\frac{1}{R_{st(i,1),r}} - \frac{1}{R_{st(i,1),av(N_r)}}\right)} \text{ if } m_i = 0 \\ \sqrt{\left(c_{a3BHA_{av}(N_r)}\right)^2 + \frac{A \cdot (m_i - 1) \cdot \left[-A \cdot (m_i + 1) \cdot \left[\frac{1}{\left(R_{st(i,1),r}\right)^{2 \cdot m_i}} - \frac{1}{\left(R_{st(i,1),av(N_r)}\right)^{2 \cdot m_i}}\right] \dots}{+ 2 \cdot B \cdot m_i \cdot \left[\frac{1}{\left(R_{st(i,1),r}\right)^{m_i+1}} - \frac{1}{\left(R_{st(i,1),av(N_r)}\right)^{m_i+1}}\right]} } \text{ otherwise} \end{bmatrix} \\ c_{a1BHA_{av}(N_r)} \text{ otherwise} \end{bmatrix} \\
\begin{pmatrix} \alpha_{1BHA_r} \\ \alpha_{3BHA_r} \end{pmatrix} &= \begin{pmatrix} \text{triangle}(c_{a1BHA_r}, c_{u1BHA_r}) \\ \text{triangle}(c_{a3BHA_r}, c_{u3BHA_r}) \end{pmatrix} \\
\begin{pmatrix} c_{1BHA_r} \\ c_{3BHA_r} \end{pmatrix} &= \begin{pmatrix} \frac{c_{a1BHA_r}}{\sin(\alpha_{1BHA_r})} \\ \frac{c_{a3BHA_r}}{\sin(\alpha_{3BHA_r})} \end{pmatrix} \\
\begin{pmatrix} \lambda_{c1BHA_r} \\ \lambda_{c3BHA_r} \end{pmatrix} &= \begin{pmatrix} \frac{c_{1BHA_r}}{a^*_{c1BHA_r}} \\ \frac{c_{3BHA_r}}{a^*_{c3BHA_r}} \end{pmatrix} \\
\epsilon_{BHA_r} &= -1 \cdot (\alpha_{3BHA_r} - \alpha_{1BHA_r}) \\
\begin{pmatrix} T^*_{1BHA} & P^*_{1BHA} & \rho^*_{1BHA} & C_{P1BHA} & k_{1BHA} & a^*_{c1BHA} & c_{u1BHA} & c_{a1BHA} & \alpha_{1BHA} & c_{1BHA} & \lambda_{c1BHA} & \epsilon_{BHA} \\ T^*_{3BHA} & P^*_{3BHA} & \rho^*_{3BHA} & C_{P3BHA} & k_{3BHA} & a^*_{c3BHA} & c_{u3BHA} & c_{a3BHA} & \alpha_{3BHA} & c_{3BHA} & \lambda_{c3BHA} & \epsilon_{BHA} \end{pmatrix}^T
\end{aligned}$$

T^*	T	=	for $i \in 1..Z$	for $a \in 1..3$	for $r \in 1..N_r$	$T_{st(i,a),r}^* = T_{st(i,a),av(N_r)}^*$
P^*	P					$P_{st(i,a),r}^* = P_{st(i,a),av(N_r)}^*$
ρ^*	ρ					$\rho_{st(i,a),r}^* = \rho_{st(i,a),av(N_r)}^*$
C_p	k					$C_{p_{st(i,a),r}} = C_{p_{BO3DYX}}(P_{st(i,a),r}^*, T_{st(i,a),r}^*)$
a_c^*	a_{3B}					$k_{st(i,a),r} = k_{a\Delta}(C_{p_{st(i,a),r}}, R_B)$
c_u	c_a					$a_{c_{st(i,a),r}}^* = \sqrt{\frac{2 \cdot k_{st(i,a),r}}{k_{st(i,a),r} + 1}} \cdot R_B \cdot T_{st(i,a),r}^*$
α	β					if $\Delta H_{Tmax} = 0$
c	w					$A_{st(i,a)} = \left(1 - R_{L_{i,av(N_r)}}\right) \cdot \omega \cdot \left(R_{st(i,a),av(N_r)}\right)^{m_i+1}$
λ_c	w_u					$B_{st(i,a)} = \frac{H_{T_{i,av(N_r)}}}{2 \cdot \omega}$
M_w	M_c					$c_{u_{st(i,a),r}} = \begin{cases} c_{u_{st(i,a-1),r}} \cdot \frac{R_{st(i,a),r}}{R_{st(i,a-1),r}} + \frac{H_{T_{i,av(N_r)}}}{\omega \cdot R_{st(i,a),r}} & \text{if } a = 2 \\ \text{otherwise} \\ \begin{cases} 0 & \text{if } (a = 1) \wedge (i = 1) \wedge (BHA = 0) \\ \frac{A_{st(i,a)}}{\left(R_{st(i,a),r}\right)^{m_i}} - \frac{B_{st(i,a)}}{\left(R_{st(i,a),r}\right)} & \text{otherwise} \end{cases} \end{cases}$
R_L	R_L	$c_{a_{st(i,a),r}} = \begin{cases} c_{a3BHA_r} & \text{if } (a = 1) \wedge (i = 1) \wedge (BHA = 1) \\ \sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a)}\right)^2 \cdot \left[\left(R_{st(i,a),r}\right)^2 - \left(R_{st(i,a),av(N_r)}\right)^2\right] + 4 \cdot A_{st(i,a)} \cdot B_{st(i,a)} \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)} \cdot \begin{cases} -1 & \text{if } a = 2 \\ 1 & \text{otherwise} \end{cases} & \text{if } m_i = -1 \\ \sqrt{\left(c_{a_{st(i,a),av(N_r)}}\right)^2 - 2 \cdot \left(A_{st(i,a)}\right)^2 \cdot \ln\left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}}\right)} - 2 \cdot A_{st(i,a)} \cdot B_{st(i,a)} \cdot \left(\frac{1}{R_{st(i,a),av(N_r)}} - \frac{1}{R_{st(i,a),r}}\right) \cdot \begin{cases} -1 & \text{if } a = 2 \\ 1 & \text{otherwise} \end{cases} & \text{if } m_i = 0 \end{cases}$				
ϵ_{rotor}	ϵ_{stator}					

$$\sqrt{\left(\frac{c_{st(i,a),av(N_r)}}{A_{st(i,a)} \cdot (m_i - 1) \cdot \left[-A_{st(i,a)} \cdot (m_i + 1) \cdot \left[\frac{1}{(R_{st(i,a),r})^{2 \cdot m_i}} - \frac{1}{(R_{st(i,a),av(N_r)})^{2 \cdot m_i}} \right] \dots \right.} \right.} \left. \left. + 2 \cdot B_{st(i,a)} \cdot m_i \cdot \left[\frac{1}{(R_{st(i,a),r})^{m_i+1}} - \frac{1}{(R_{st(i,a),av(N_r)})^{m_i+1}} \right] \cdot \begin{cases} -1 & \text{if } a = 2 \\ 1 & \text{otherwise} \end{cases} \right] \right)^2 + \frac{1}{m_i \cdot (m_i + 1)}} \quad \text{otherwise}$$

if $\Delta H_{Tmax} \neq 0$

$$A_{st(i,a)} = \frac{1}{(R_{st(i,a),av(N_r)})^2 - (R_{st(i,a),l})^2} \cdot \left[\omega \cdot (R_{st(i,a),av(N_r)})^2 \cdot (1 - R_{L_{i,av(N_r)}}) - \omega \cdot (R_{st(i,a),l})^2 \cdot (1 - R_{L_{i,l}}) + \frac{H_{T_{i,l}} - H_{T_{i,av(N_r)}}}{2 \cdot \omega} \right]$$

$$B_{st(i,a)} = \frac{(R_{st(i,a),l}) \cdot (R_{st(i,a),av(N_r)})}{(R_{st(i,a),av(N_r)})^2 - (R_{st(i,a),l})^2} \cdot \left[\omega \cdot R_{st(i,a),l} \cdot R_{st(i,a),av(N_r)} \cdot (1 - R_{L_{i,l}}) - \omega \cdot R_{st(i,a),av(N_r)} \cdot R_{st(i,a),l} \cdot (1 - R_{L_{i,av(N_r)}}) \dots \right]$$

$$+ -\frac{1}{2 \cdot \omega} \cdot \left(\frac{H_{T_{i,l}} \cdot R_{st(i,a),av(N_r)}}{R_{st(i,a),l}} - \frac{H_{T_{i,av(N_r)}} \cdot R_{st(i,a),l}}{R_{st(i,a),av(N_r)}} \right)$$

$$c_{u_{st(i,a),r}} = \begin{cases} A_{st(i,a)} \cdot R_{st(i,a),r} + \frac{B_{st(i,a)}}{R_{st(i,a),r}} + \frac{H_{T_{i,r}}}{\omega \cdot R_{st(i,a),r}} & \text{if } a = 2 \\ \text{otherwise} \\ \begin{cases} 0 & \text{if } (a = 1) \wedge (i = 1) \wedge (BHA = 0) \\ A_{st(i,a)} \cdot R_{st(i,a),r} + \frac{B_{st(i,a)}}{R_{st(i,a),r}} & \text{otherwise} \end{cases} \end{cases}$$

$$k_{HT} = \frac{H_{T_{i,av(N_r)}} - H_{T_{i,l}}}{R_{st(i,a),av(N_r)} - R_{st(i,a),l}}$$

$$b_{HT} = H_{T_{i,av(N_r)}} - k_{HT} \cdot R_{st(i,a),av(N_r)}$$

$$c_{a_{st(i,a),r}} = \begin{cases} c_{a3BHA_r} & \text{if } (a = 1) \wedge (i = 1) \wedge (BHA = 1) \\ \sqrt{\left(c_{a_{st(i,a),av(N_r)}}^2 - 2 \cdot (A_{st(i,a)})^2 \cdot \left[(R_{st(i,a),r})^2 - (R_{st(i,a),av(N_r)})^2 \right] \dots \right.} & \text{if } a = 2 \\ \left. + -\left(6 \cdot \frac{A_{st(i,a)}}{\omega} - 2 \right) \cdot k_{HT} \cdot (R_{st(i,a),r} - R_{st(i,a),av(N_r)}) \dots \right. \\ \left. + -2 \cdot \frac{k_{HT}}{\omega} \cdot \left(B_{st(i,a)} + \frac{b_{HT}}{\omega} \right) \cdot \frac{R_{st(i,a),r} - R_{st(i,a),av(N_r)}}{R_{st(i,a),r} \cdot R_{st(i,a),av(N_r)}} - 2 \cdot \left[2 \cdot A_{st(i,a)} \cdot \left(B_{st(i,a)} + \frac{b_{HT}}{\omega} \right) + \frac{k_{HT}^2}{\omega^2} \right] \cdot \ln \left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}} \right) \right. \\ \left. \sqrt{\left(c_{a_{st(i,a),av(N_r)}}^2 - 2 \cdot (A_{st(i,a)})^2 \cdot \left[(R_{st(i,a),r})^2 - (R_{st(i,a),av(N_r)})^2 \right] - 4 \cdot A_{st(i,a)} \cdot B_{st(i,a)} \cdot \ln \left(\frac{R_{st(i,a),r}}{R_{st(i,a),av(N_r)}} \right) \right)} & \text{otherwise} \end{cases}$$

$$\alpha_{\text{st}(i,a),r} = \text{triangle}\left(c_{\text{a}_{\text{st}(i,a),r}}, c_{\text{u}_{\text{st}(i,a),r}}\right)$$

$$c_{\text{st}(i,a),r} = \frac{c_{\text{a}_{\text{st}(i,a),r}}}{\sin\left(\alpha_{\text{st}(i,a),r}\right)}$$

$$\lambda_{\text{c}_{\text{st}(i,a),r}} = \frac{c_{\text{st}(i,a),r}}{a^*_{\text{c}_{\text{st}(i,a),r}}}$$

$$\begin{pmatrix} T_{\text{st}(i,a),r} \\ P_{\text{st}(i,a),r} \\ \rho_{\text{st}(i,a),r} \end{pmatrix} = \begin{pmatrix} T^*_{\text{st}(i,a),r} \cdot \Gamma \mathcal{D} \Phi\left("T", \lambda_{\text{c}_{\text{st}(i,a),r}}, k_{\text{st}(i,a),r}\right) \\ P^*_{\text{st}(i,a),r} \cdot \Gamma \mathcal{D} \Phi\left("P", \lambda_{\text{c}_{\text{st}(i,a),r}}, k_{\text{st}(i,a),r}\right) \\ \rho^*_{\text{st}(i,a),r} \cdot \Gamma \mathcal{D} \Phi\left(" \rho", \lambda_{\text{c}_{\text{st}(i,a),r}}, k_{\text{st}(i,a),r}\right) \end{pmatrix}$$

$$a_{3B_{\text{st}(i,a),r}} = \sqrt{k_{\text{st}(i,a),r} \cdot R_B \cdot T_{\text{st}(i,a),r}}$$

$$\beta_{\text{st}(i,a),r} = \text{triangle}\left(c_{\text{a}_{\text{st}(i,a),r}}, u_{\text{st}(i,a),r} - c_{\text{u}_{\text{st}(i,a),r}}\right)$$

$$w_{\text{st}(i,a),r} = \frac{c_{\text{a}_{\text{st}(i,a),r}}}{\sin\left(\beta_{\text{st}(i,a),r}\right)}$$

$$w_{\text{u}_{\text{st}(i,a),r}} = w_{\text{st}(i,a),r} \cdot \cos\left(\beta_{\text{st}(i,a),r}\right)$$

$$\begin{pmatrix} M_{\text{w}_{\text{st}(i,a),r}} \\ M_{\text{c}_{\text{st}(i,a),r}} \end{pmatrix} = \frac{1}{a_{3B_{\text{st}(i,a),r}}} \cdot \begin{pmatrix} w_{\text{st}(i,a),r} \\ c_{\text{st}(i,a),r} \end{pmatrix}$$

for $r \in 1..N_r$

$$\left| \begin{aligned} R_{L_{i,r}} &= 1 - \frac{c_{\text{u}_{\text{st}(i,1),r}} + c_{\text{u}_{\text{st}(i,2),r}}}{u_{\text{st}(i,1),r} + u_{\text{st}(i,2),r}} \\ \begin{pmatrix} \varepsilon_{\text{rotor}_{i,r}} \\ \varepsilon_{\text{stator}_{i,r}} \end{pmatrix} &= \begin{pmatrix} \beta_{\text{st}(i,2),r} - \beta_{\text{st}(i,1),r} \\ \alpha_{\text{st}(i,3),r} - \alpha_{\text{st}(i,2),r} \end{pmatrix} \end{aligned} \right|$$

$$\begin{pmatrix} T^* & P^* & \rho^* & C_p & a^*_c & c_u & \alpha & c & \lambda_c & M_w & R_L & \varepsilon_{\text{rotor}} \\ T & P & \rho & k & a_{3B} & c_a & \beta & w & w_u & M_c & R_L & \varepsilon_{\text{stator}} \end{pmatrix}^T$$

$$\begin{pmatrix} T^*_{1CA} & T^*_{3CA} \\ P^*_{1CA} & P^*_{3CA} \\ \rho^*_{1CA} & \rho^*_{3CA} \\ C_{p1CA} & C_{p3CA} \\ k_{1CA} & k_{3CA} \\ a^*_{c1CA} & a^*_{c3CA} \\ c_{u1CA} & c_{u3CA} \\ c_{a1CA} & c_{a3CA} \\ \alpha_{1CA} & \alpha_{3CA} \\ c_{1CA} & c_{3CA} \\ \lambda_{c1CA} & \lambda_{c3CA} \\ \varepsilon_{CA} & \varepsilon_{CA} \end{pmatrix} =$$

$$\begin{array}{l} \text{for } i \in Z \\ \text{for } r \in 1..N_r \end{array}$$

$$\begin{pmatrix} T^*_{1CA_r} \\ T^*_{3CA_r} \end{pmatrix} = \begin{pmatrix} T^*_{st(i,3),r} \\ T^*_{3CA_{av}(N_r)} \end{pmatrix}$$

$$\begin{pmatrix} P^*_{1CA_r} \\ P^*_{3CA_r} \end{pmatrix} = \begin{pmatrix} P^*_{st(i,3),r} \\ P^*_{3CA_{av}(N_r)} \end{pmatrix}$$

$$\begin{pmatrix} \rho^*_{1CA_r} \\ \rho^*_{3CA_r} \end{pmatrix} = \begin{pmatrix} \rho^*_{st(i,3),r} \\ \rho^*_{3CA_{av}(N_r)} \end{pmatrix}$$

$$\begin{pmatrix} C_{p1CA_r} \\ C_{p3CA_r} \end{pmatrix} = \begin{pmatrix} C_{p_{\text{Боздyx}}}\left(P^*_{1CA_r},T^*_{1CA_r}\right) \\ C_{p_{\text{Боздyx}}}\left(P^*_{3CA_r},T^*_{3CA_r}\right) \end{pmatrix}$$

$$\begin{pmatrix} k_{1CA_r} \\ k_{3CA_r} \end{pmatrix} = \begin{pmatrix} k_{a\text{д}}\left(C_{p1CA_r},R_{\text{Б}}\right) \\ k_{a\text{д}}\left(C_{p3CA_r},R_{\text{Б}}\right) \end{pmatrix}$$

$$\begin{pmatrix} a^*_{c1CA_r} \\ a^*_{c3CA_r} \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{2 \cdot k_{1CA_r}}{k_{1CA_r} + 1} \cdot R_{\text{Б}} \cdot T^*_{1CA_r}} \\ \sqrt{\frac{2 \cdot k_{3CA_r}}{k_{3CA_r} + 1} \cdot R_{\text{Б}} \cdot T^*_{3CA_r}} \end{pmatrix}$$

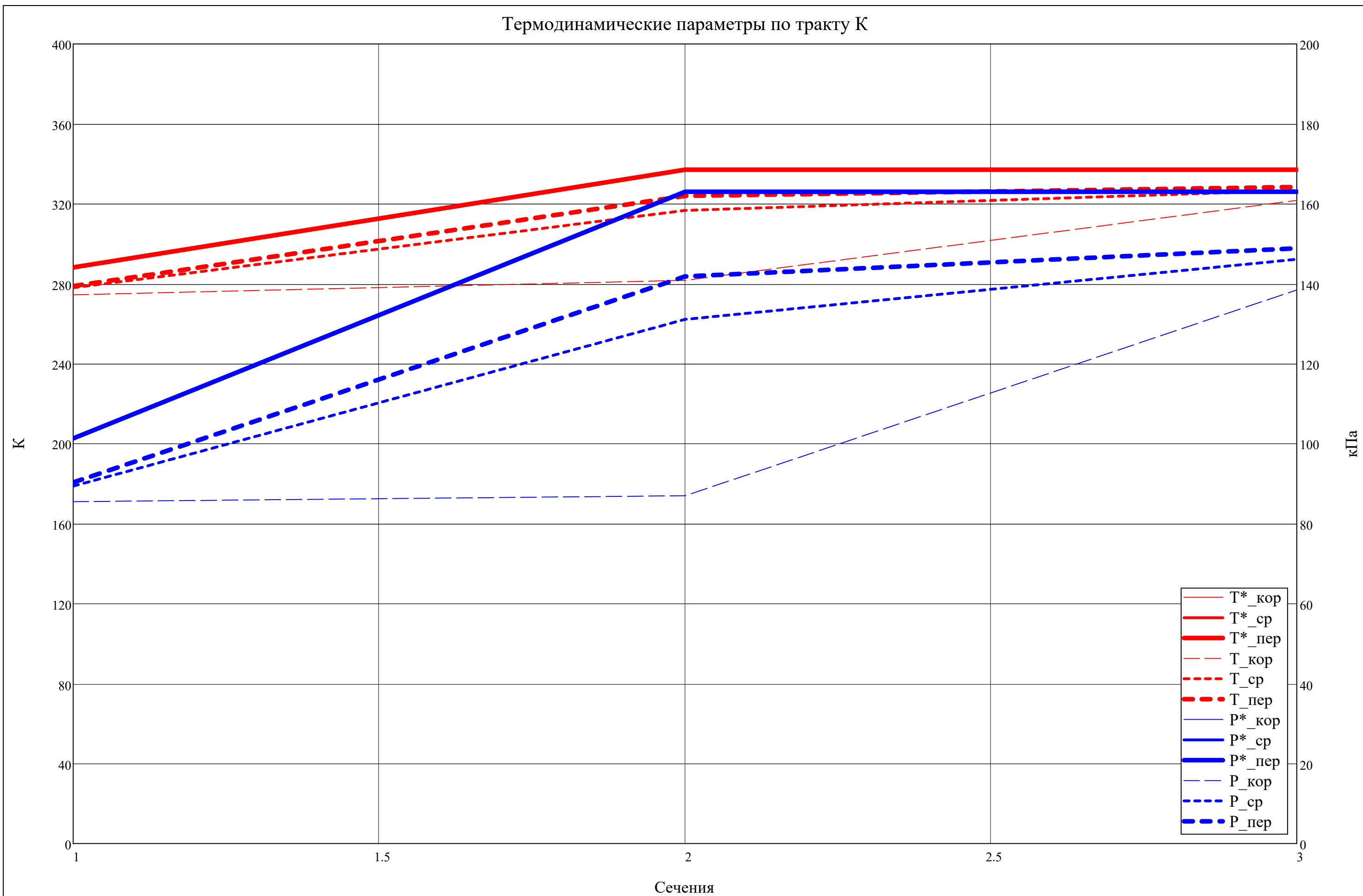
$$A = \left(1 - R_{L_i,av(N_r)}\right) \cdot \omega \cdot \left(R_{st(i,3),av(N_r)}\right)^{m_i+1}$$

$$B = \frac{H_{T_{i,av(N_r)}}}{2 \cdot \omega}$$

$$\begin{pmatrix} c_{u1CA_r} \\ c_{u3CA_r} \end{pmatrix} = \begin{pmatrix} c_{u_{st(i,3),r}} \\ c_{u3CA_{av}(N_r)} \text{ if } CA = 1 \end{pmatrix}$$

$T^*_{1BHA} = \begin{pmatrix} 288.2 \\ 288.2 \\ 288.2 \end{pmatrix}$	$T^*_{3BHA} = \begin{pmatrix} 288.2 \\ 288.2 \\ 288.2 \end{pmatrix}$	$a^*_{c1BHA} = \begin{pmatrix} 310.78 \\ 310.78 \\ 310.78 \end{pmatrix}$	$a^*_{c3BHA} = \begin{pmatrix} 310.78 \\ 310.78 \\ 310.78 \end{pmatrix}$	$\alpha_{1BHA} = \begin{pmatrix} 90.00 \\ 90.00 \\ 90.00 \end{pmatrix} \cdot ^\circ$	$\alpha_{3BHA} = \begin{pmatrix} 90.00 \\ 90.00 \\ 90.00 \end{pmatrix} \cdot ^\circ$
$P^*_{1BHA} = \begin{pmatrix} 101.3 \\ 101.3 \\ 101.3 \end{pmatrix} \cdot 10^3$	$P^*_{3BHA} = \begin{pmatrix} 101.3 \\ 101.3 \\ 101.3 \end{pmatrix} \cdot 10^3$	$c_{1BHA} = \begin{pmatrix} 142.7 \\ 142.7 \\ 142.7 \end{pmatrix}$	$c_{3BHA} = \begin{pmatrix} 142.7 \\ 142.7 \\ 142.7 \end{pmatrix}$	$\epsilon_{BHA} = \begin{pmatrix} 0.00 \\ 0.00 \\ 0.00 \end{pmatrix} \cdot ^\circ$	
$\rho^*_{1BHA} = \begin{pmatrix} 1.224 \\ 1.224 \\ 1.224 \end{pmatrix}$	$\rho^*_{3BHA} = \begin{pmatrix} 1.224 \\ 1.224 \\ 1.224 \end{pmatrix}$	$c_{u1BHA} = \begin{pmatrix} 0.0 \\ 0.0 \\ 0.0 \end{pmatrix}$	$c_{u3BHA} = \begin{pmatrix} 0.0 \\ 0.0 \\ 0.0 \end{pmatrix}$		
$Cp_{1BHA} = \begin{pmatrix} 1002.6 \\ 1002.6 \\ 1002.6 \end{pmatrix}$	$Cp_{3BHA} = \begin{pmatrix} 1002.6 \\ 1002.6 \\ 1002.6 \end{pmatrix}$	$c_{a1BHA} = \begin{pmatrix} 142.7 \\ 142.7 \\ 142.7 \end{pmatrix}$	$c_{a3BHA} = \begin{pmatrix} 142.7 \\ 142.7 \\ 142.7 \end{pmatrix}$	$\lambda_{c1BHA} = \begin{pmatrix} 0.459 \\ 0.459 \\ 0.459 \end{pmatrix}$	$\lambda_{c3BHA} = \begin{pmatrix} 0.459 \\ 0.459 \\ 0.459 \end{pmatrix}$
$k_{1BHA} = \begin{pmatrix} 1.401 \\ 1.401 \\ 1.401 \end{pmatrix}$	$k_{3BHA} = \begin{pmatrix} 1.401 \\ 1.401 \\ 1.401 \end{pmatrix}$				

Термодинамические параметры по тракту К



[illegible][illegible][illegible][illegible][illegible][illegible][illegible][illegible]

$$\Delta c_a = \begin{cases} \text{for } i \in 1..Z \\ \text{for } a \in 2..3 \\ \text{for } r \in 1..N_r \end{cases}$$

$$\Delta c_a$$

$$\Delta \mathbf{c}_a^T =$$

$$\Delta c_a^T \geq -25 =$$

[illegible]

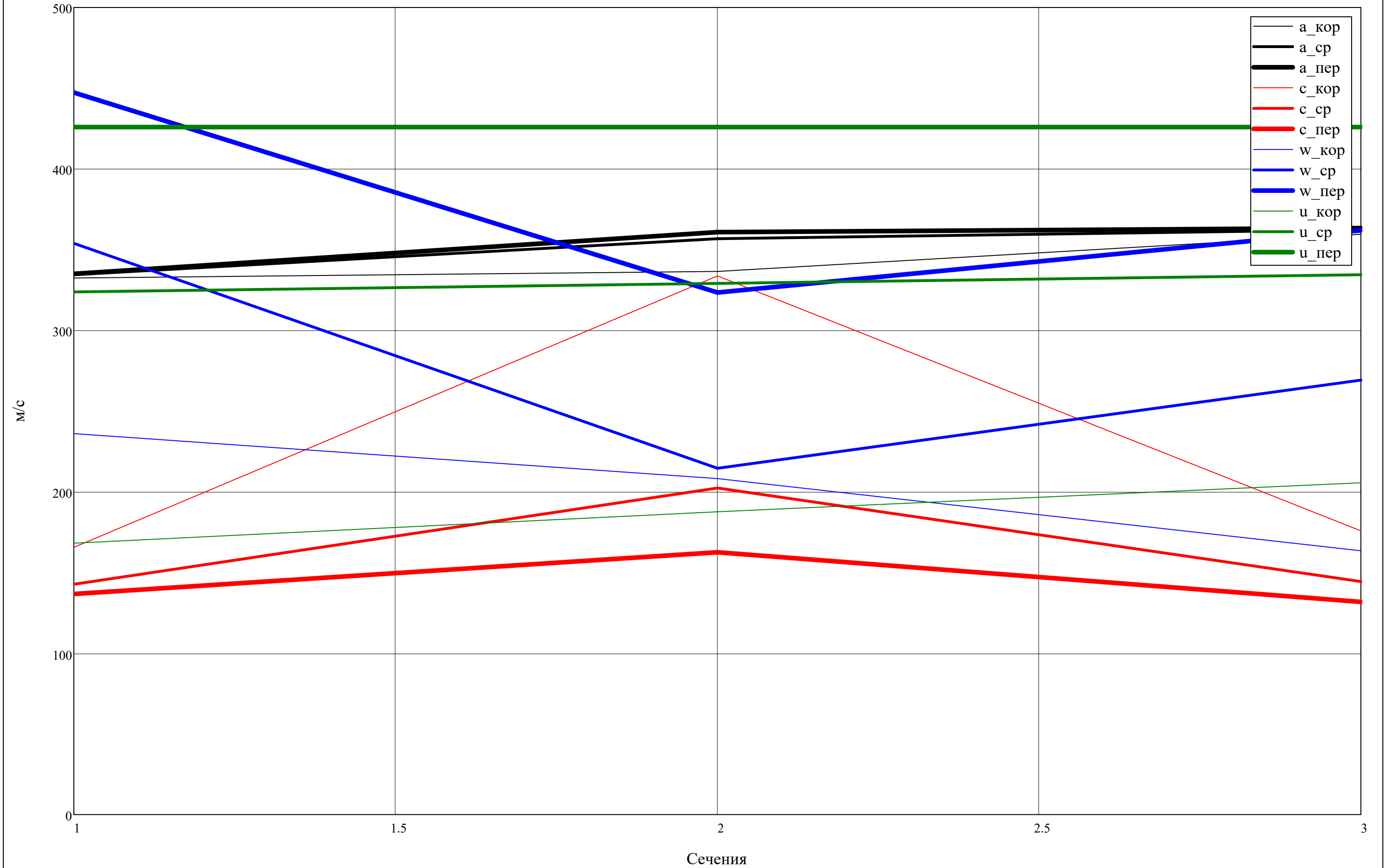
$$\mathbf{R}_L^T =$$

[illegible]

$$\mathbf{R}_L^T \geq 0 =$$

[illegible]

Скорости по тракту К

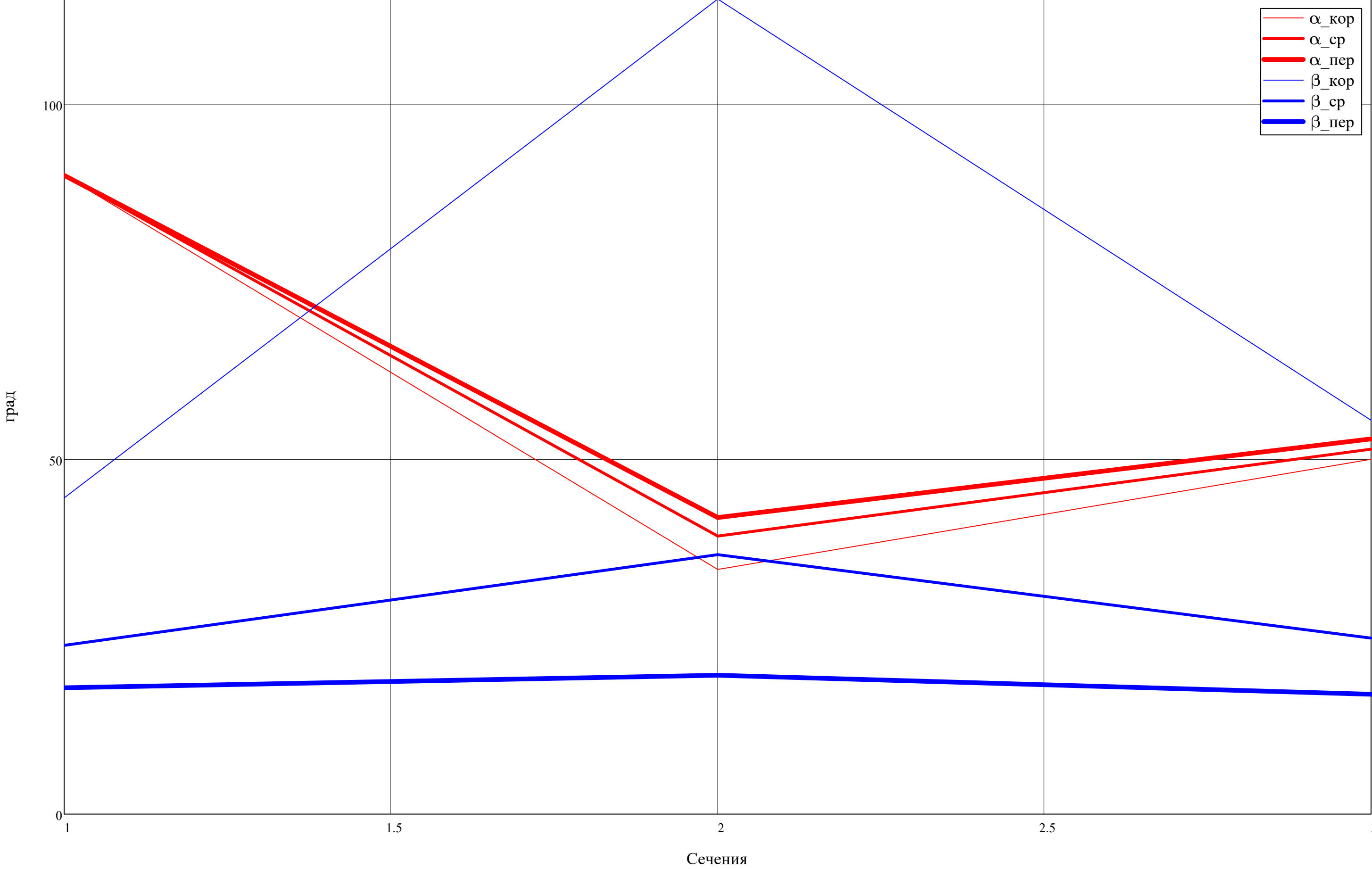


[illegible][illegible][illegible]

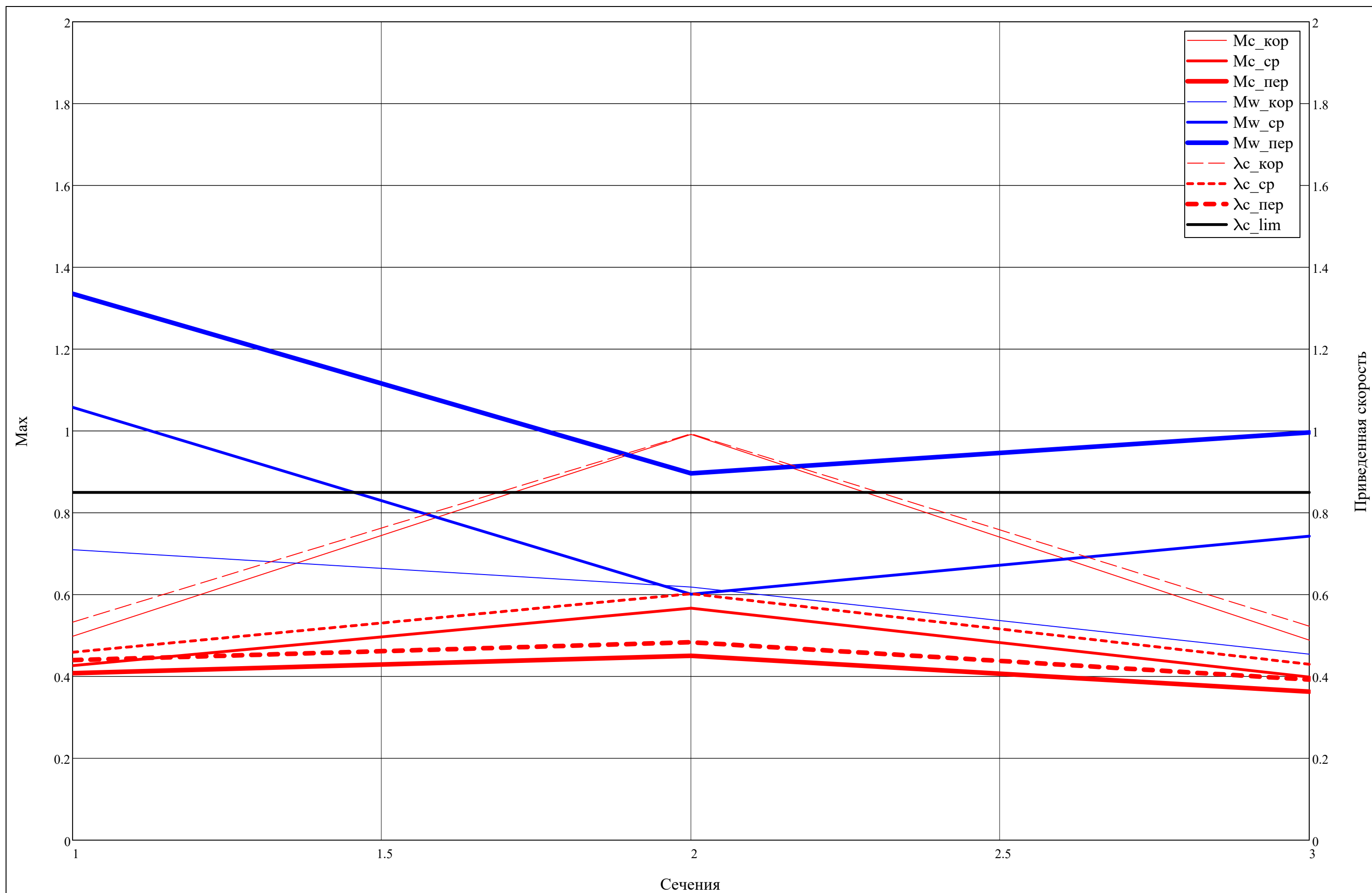
$\beta.2 > 91 \Rightarrow$ поменять 3-н профилирования

[illegible][illegible]

Углы по тракту К



[illegible][illegible][illegible][illegible]



$T^*_{1CA} = \begin{pmatrix} 337.1 \\ 337.1 \\ 337.1 \end{pmatrix}$	$T^*_{3CA} = \begin{pmatrix} 337.1 \\ 337.1 \\ 337.1 \end{pmatrix}$	$a^*_{c1CA} = \begin{pmatrix} 336.0 \\ 336.0 \\ 336.0 \end{pmatrix}$	$a^*_{c3CA} = \begin{pmatrix} 336.0 \\ 336.0 \\ 336.0 \end{pmatrix}$	$\alpha_{1CA} = \begin{pmatrix} 49.99 \\ 51.42 \\ 52.87 \end{pmatrix} \cdot ^\circ$	$\alpha_{3CA} = \begin{pmatrix} 49.99 \\ 51.42 \\ 52.87 \end{pmatrix} \cdot ^\circ$
$P^*_{1CA} = \begin{pmatrix} 163.0 \\ 163.0 \\ 163.0 \end{pmatrix} \cdot 10^3$	$P^*_{3CA} = \begin{pmatrix} 163.0 \\ 163.0 \\ 163.0 \end{pmatrix} \cdot 10^3$	$c_{1CA} = \begin{pmatrix} 175.8 \\ 144.4 \\ 131.8 \end{pmatrix}$	$c_{3CA} = \begin{pmatrix} 175.8 \\ 144.4 \\ 131.8 \end{pmatrix}$	$\varepsilon_{CA} = \begin{pmatrix} 0.00 \\ 0.00 \\ 0.00 \end{pmatrix} \cdot ^\circ$	
$\rho^*_{1CA} = \begin{pmatrix} 1.684 \\ 1.684 \\ 1.684 \end{pmatrix}$	$\rho^*_{3CA} = \begin{pmatrix} 1.684 \\ 1.684 \\ 1.684 \end{pmatrix}$	$c_{u1CA} = \begin{pmatrix} 113.0 \\ 90.0 \\ 79.6 \end{pmatrix}$	$c_{u3CA} = \begin{pmatrix} 113.0 \\ 90.0 \\ 79.6 \end{pmatrix}$		
$Cp_{1CA} = \begin{pmatrix} 1006.0 \\ 1006.0 \\ 1006.0 \end{pmatrix}$	$Cp_{3CA} = \begin{pmatrix} 1006.0 \\ 1006.0 \\ 1006.0 \end{pmatrix}$	$c_{a1CA} = \begin{pmatrix} 134.6 \\ 112.9 \\ 105.1 \end{pmatrix}$	$c_{a3CA} = \begin{pmatrix} 134.6 \\ 112.9 \\ 105.1 \end{pmatrix}$	$\lambda_{c1CA} = \begin{pmatrix} 0.523 \\ 0.430 \\ 0.392 \end{pmatrix}$	$\lambda_{c3CA} = \begin{pmatrix} 0.523 \\ 0.430 \\ 0.392 \end{pmatrix}$
$k_{1CA} = \begin{pmatrix} 1.399 \\ 1.399 \\ 1.399 \end{pmatrix}$	$k_{3CA} = \begin{pmatrix} 1.399 \\ 1.399 \\ 1.399 \end{pmatrix}$				

Рассматриваемая ступень:

j =

j = 1

j =

"Такой ступени не существует!" if (j < 1) ∨ (j > Z)

j otherwise

= 1

▼

Построение треугольников скоростей в 3х сечениях

Δ_c(v,i,j,r) =

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) ≥ 0 ∧ −|c_{st(i,j),r}·cos(α_{st(i,j),r})| ≤ v ≤ 0)

tan(α_{st(i,j),r})·v if (tan(α_{st(i,j),r}) < 0 ∧ 0 ≤ v ≤ |c_{st(i,j),r}·cos(α_{st(i,j),r})|)

Δ_w(v,i,j,r) =

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) ≥ 0) ∧ (−|w_{st(i,j),r}·cos(β_{st(i,j),r})| ≤ v ≤ 0) ∧ (j ≠ 3)

−tan(β_{st(i,j),r})·v if (−tan(β_{st(i,j),r}) < 0) ∧ (0 ≤ v ≤ |w_{st(i,j),r}·cos(β_{st(i,j),r})|) ∧ (j ≠ 3)

Δ_u(v,i,j,r) =

−c_{a_{st(i,j),r}} if (−c_{st(i,j),r}·cos(α_{st(i,j),r}) ≤ v ≤ w_{st(i,j),r}·cos(β_{st(i,j),r})) ∧ (j ≠ 3)

NaN otherwise

v_{lim} =

ceil

(

max(c,w,u)

)

·10² = 500

Дискретизация скорости:

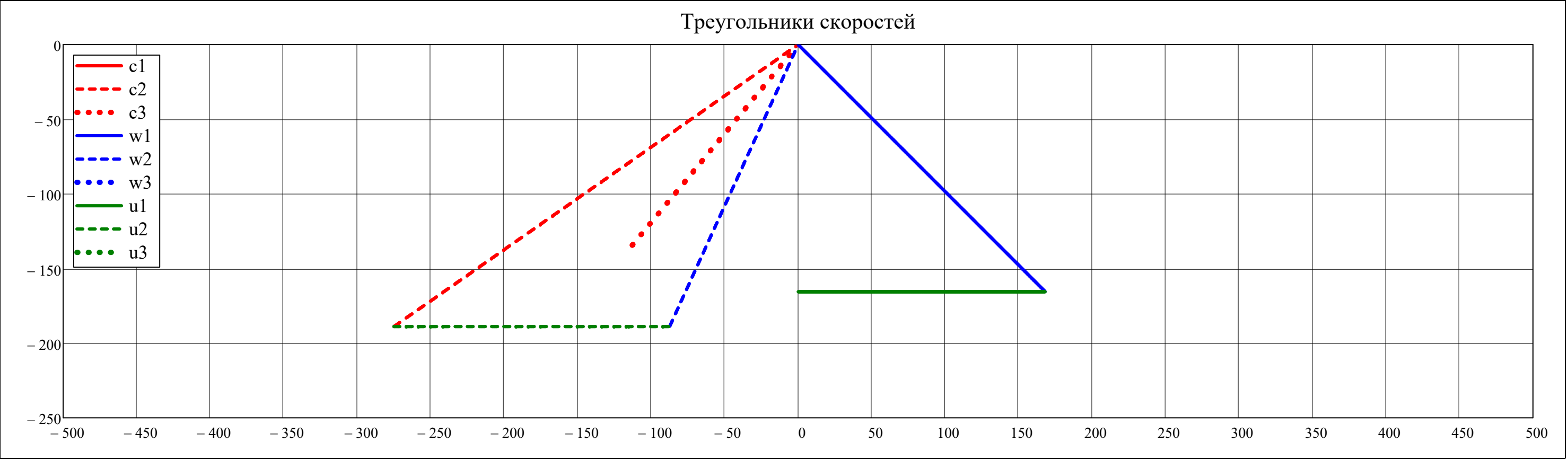
v = −v_{lim}, −v_{lim} +

v_{lim}

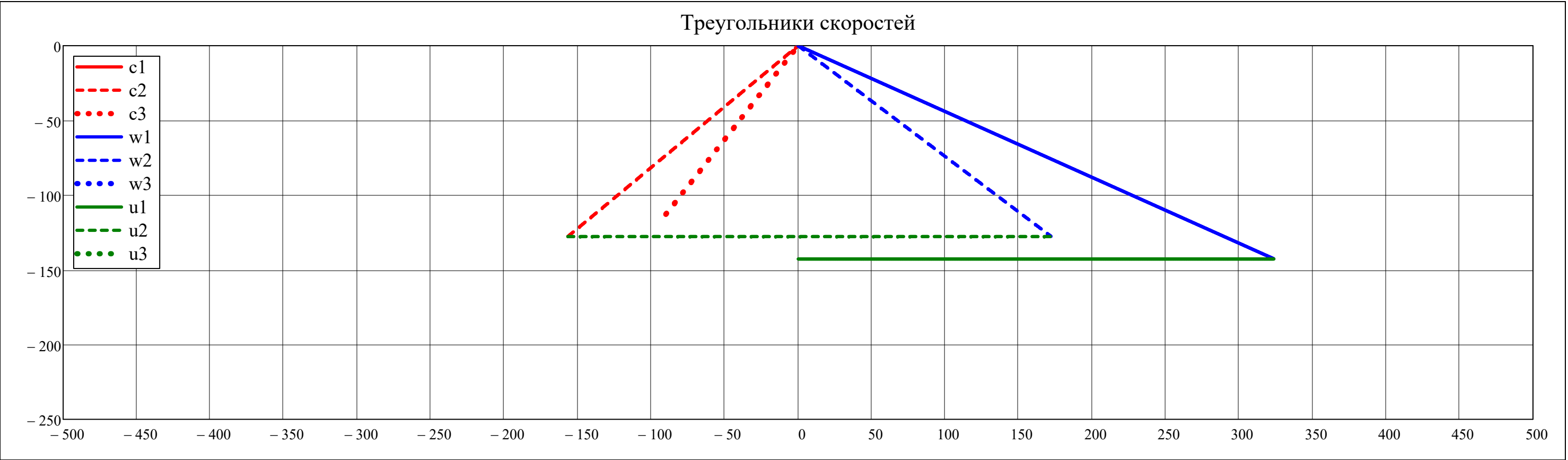
3000

.. v_{lim}

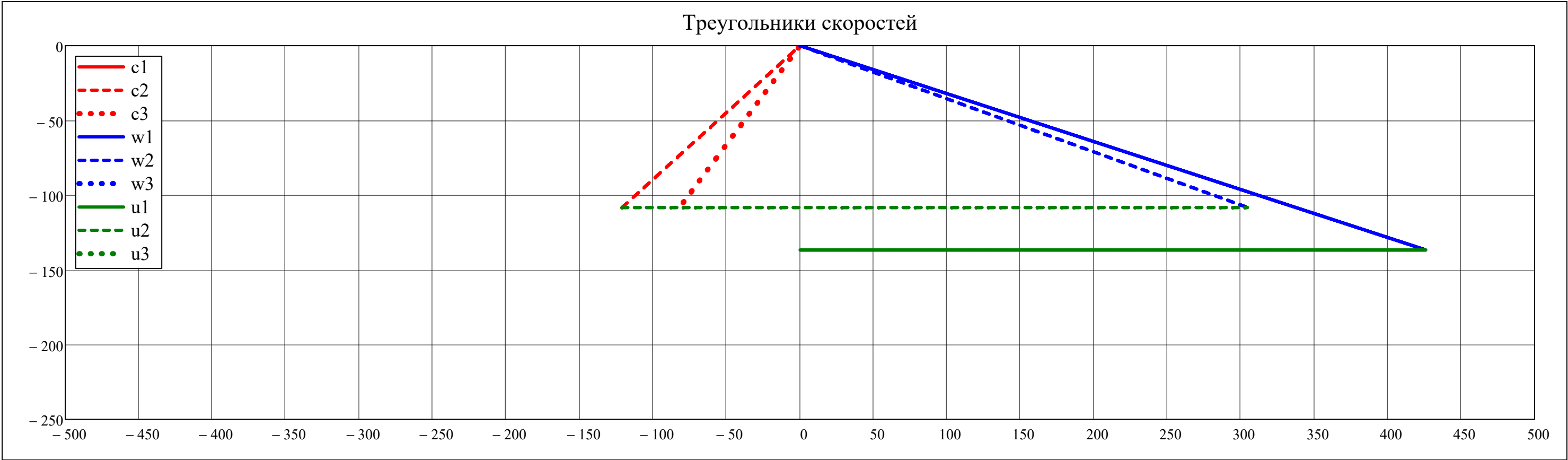
r = 1



$\bar{r}_w = \text{av}(N_r)$



$r_w = N_r$



Построение треугольников скоростей в 3х сечениях

$$\begin{pmatrix} F_I & F_{II} \\ D2 & R2 \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } a \in 1..3 \\ \quad \left| \begin{array}{l} \rho_{\cdot}(z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, \text{submatrix}\left(\rho, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, \text{submatrix}\left(\rho, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, z\right) \\ c_a(z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, \text{submatrix}\left(c_a, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, \text{submatrix}\left(c_a, \text{st}(i, a), \text{st}(i, a), 1, N_r\right)^T, z\right) \\ R2 = \sqrt{\frac{\left(R_{\text{st}(i, a), N_r}\right)^2 + m2 \cdot \left(R_{\text{st}(i, a), 1}\right)^2}{1 + m2}} \\ R2_{\text{st}(i, a)} = \text{root}\left[\frac{\rho_{\cdot}(R2) \cdot c_a(R2) \cdot \pi \cdot \left[\left(R_{\text{st}(i, a), N_r}\right)^2 - (R2)^2\right]}{\rho_{\cdot}(R2) \cdot c_a(R2) \cdot \pi \cdot \left[\left(R2\right)^2 - \left(R_{\text{st}(i, a), 1}\right)^2\right]} - m2, R2\right] \\ D2_{\text{st}(i, a)} = 2 \cdot R2_{\text{st}(i, a)} \\ \begin{pmatrix} F_{II_{\text{st}(i, a)}} \\ F_{I_{\text{st}(i, a)}} \end{pmatrix} = \pi \cdot \begin{bmatrix} \left(R_{\text{st}(i, a), N_r}\right)^2 - \left(R2_{\text{st}(i, a)}\right)^2 \\ \left(R2_{\text{st}(i, a)}\right)^2 - \left(R_{\text{st}(i, a), 1}\right)^2 \end{bmatrix} \end{array} \right| \\ \begin{pmatrix} F_I & F_{II} \\ D2 & R2 \end{pmatrix} \end{array}$$

Кольцевые площади (м²):

[illegible]

Радиус и диаметр двухконтурности (м):

[illegible]

$$\begin{pmatrix} \pi^*_{\Pi} \\ \pi^*_{\text{I}} \end{pmatrix} =$$

for i ∈ 1..Z

for a ∈ 1

$$\text{Cp}_{\cdot}(z) = \text{interp}\Big(\text{lspline}\Big(\text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{Cp}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}\Big), \text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{Cp}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, z\Big)$$

$$\text{k}_{\cdot}(z) = \text{interp}\Big(\text{lspline}\Big(\text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{k}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}\Big), \text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{k}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, z\Big)$$

$$\text{T}^*_{\cdot}(z) = \text{interp}\Big(\text{lspline}\Big(\text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{T}^*, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}\Big), \text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{T}^*, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, z\Big)$$

$$\text{H}_{\text{T}_{\cdot}}(z) = \text{interp}\Big(\text{lspline}\Big(\text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{H}_{\text{T}}, \text{i}, \text{i}, 1, \text{N}_{\text{r}}\Big)^{\text{T}}\Big), \text{submatrix}\Big(\text{R}, \text{st}(\text{i}, \text{a}), \text{st}(\text{i}, \text{a}), 1, \text{N}_{\text{r}}\Big)^{\text{T}}, \text{submatrix}\Big(\text{H}_{\text{T}}, \text{i}, \text{i}, 1, \text{N}_{\text{r}}\Big)^{\text{T}}, z\Big)$$

$$\pi^*_{\Pi_{\cdot \text{i}}} = \left\{ \begin{array}{ll} 1 & \text{if } m2 = 0 \\ \frac{2 \cdot \pi}{F_{\Pi_{\text{st}(\text{i}, \text{a})}}} \cdot \int_{R2_{\text{st}(\text{i}, \text{a})}}^{R_{\text{st}(\text{i}, \text{a}), N_{\text{r}}}} \left(1 + \frac{K_{H_{\cdot \text{i}}} \cdot \eta^*_{\cdot \text{i}} \cdot H_{\text{T}_{\cdot}}(r)}{Cp_{\cdot}(r) \cdot T^*_{\cdot}(r)} \right)^{\frac{k_{\cdot}(r)}{k_{\cdot}(r) - 1}} \cdot r \, dr & \text{otherwise} \end{array} \right.$$

$$\pi^*_{\text{I}_{\cdot \text{i}}} = \frac{2 \cdot \pi}{F_{\text{I}_{\text{st}(\text{i}, \text{a})}}} \cdot \int_{R_{\text{st}(\text{i}, \text{a}), 1}}^{R2_{\text{st}(\text{i}, \text{a})}} \left(1 + \frac{K_{H_{\cdot \text{i}}} \cdot \eta^*_{\cdot \text{i}} \cdot H_{\text{T}_{\cdot}}(r)}{Cp_{\cdot}(r) \cdot T^*_{\cdot}(r)} \right)^{\frac{k_{\cdot}(r)}{k_{\cdot}(r) - 1}} \cdot r \, dr$$

$$\begin{pmatrix} \pi^*_{\Pi} \\ \pi^*_{\text{I}} \end{pmatrix}$$

$$\text{stack}\Big(\pi^*_{\text{I}}^{\text{T}}, \pi^*_{\Pi}^{\text{T}}\Big) =$$

	1	2	3	4	5	6	7	8	9	10	11	12
1	1.609											
2	1.609											

$$\prod_{i = 1}^Z \pi^*_{\text{I}_{\cdot \text{i}}} = 1.609$$

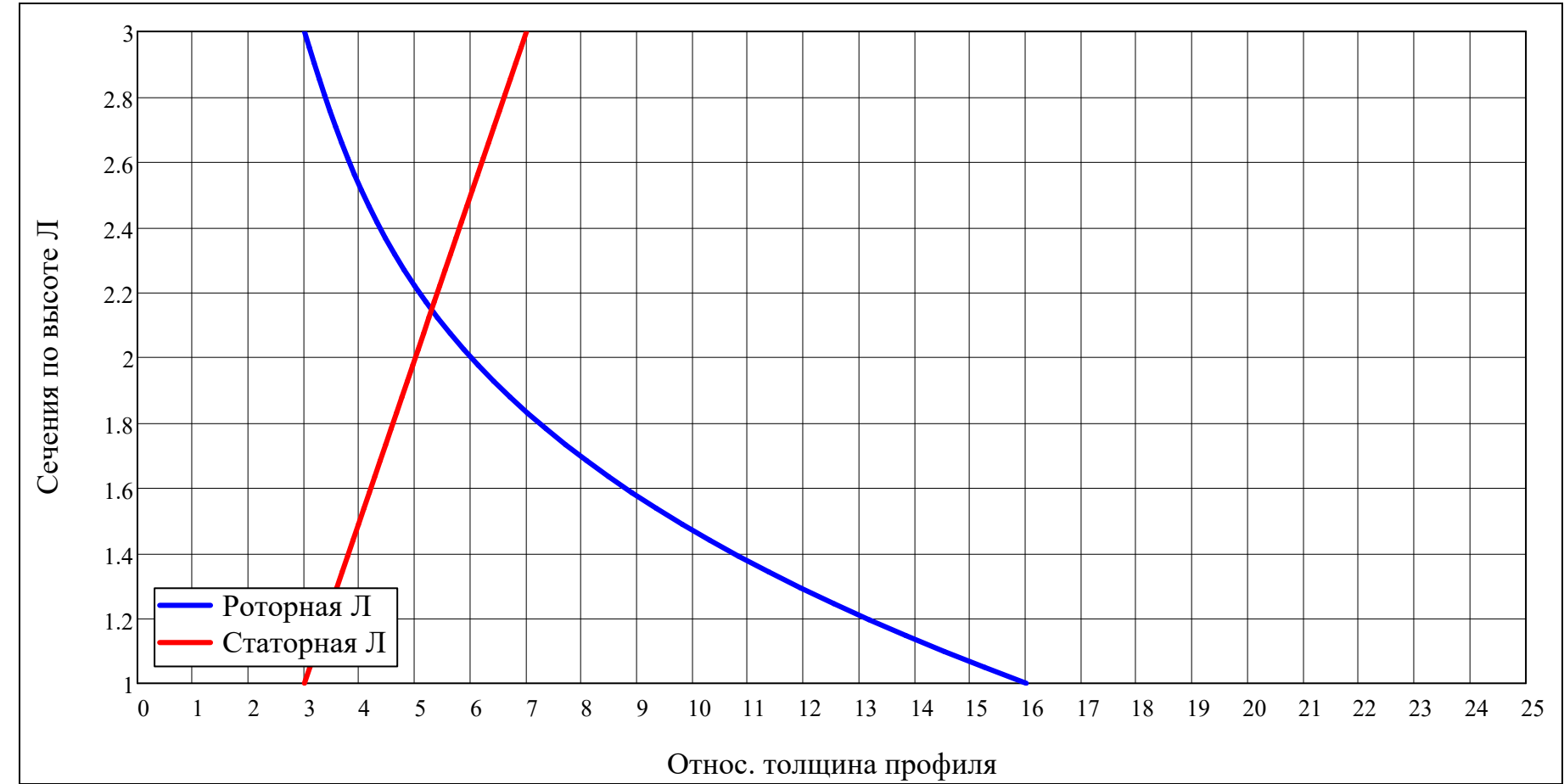
$$\prod_{i = 1}^Z \pi^*_{\Pi_{\cdot \text{i}}} = 1.609$$

Относ. толщины ЛРК и СА:

$$\overline{c}_{\text{rotor.}}(r) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 + \begin{cases} 3 & \text{if compressor} = \text{"Вл"} \\ -3 & \text{if compressor} = \text{"КНД"} \\ -1 & \text{otherwise} \end{cases} \\ 5 + \begin{cases} 1 & \text{if compressor} = \text{"Вл"} \\ -1 & \text{if compressor} = \text{"КНД"} \\ 0 & \text{otherwise} \end{cases} \\ 3 \end{pmatrix} \% , \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 13 + \begin{cases} 3 & \text{if compressor} = \text{"Вл"} \\ -3 & \text{if compressor} = \text{"КНД"} \\ -1 & \text{otherwise} \end{cases} \\ 5 + \begin{cases} 1 & \text{if compressor} = \text{"Вл"} \\ -1 & \text{if compressor} = \text{"КНД"} \\ 0 & \text{otherwise} \end{cases} \\ 3 \end{pmatrix} \% , r \right]$$

$$\overline{c}_{\text{stator.}}(r) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 3 \\ 5 \\ 7 \end{pmatrix} \% , \begin{pmatrix} 1 \\ \text{av}(N_r) \\ N_r \end{pmatrix}, \begin{pmatrix} 3 \\ 5 \\ 7 \end{pmatrix} \% , r \right]$$

$$\textcolor{green}{r} = \text{ORIGIN}, \text{ORIGIN} + \frac{N_r - \text{ORIGIN}}{N_{\text{dis}}} .. N_r$$



$$\overline{c}_{\text{BHA}} = \left| \begin{array}{l} \text{for } r \in 1..N_r \\ \overline{c}_{\text{BHA}_r} = \overline{c}_{\text{stator.}(r)} \\ \overline{c}_{\text{BHA}} \end{array} \right.$$

$$\overline{c}_{\text{BHA}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.00 \\ \hline 2 & 5.00 \\ \hline 3 & 7.00 \\ \hline \end{array} \cdot \%$$

$$\left(\begin{array}{c} \overline{c}_{\text{stator}} \\ \overline{c}_{\text{rotor}} \end{array} \right) = \left| \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left(\begin{array}{c} \overline{c}_{\text{stator}_{i,r}} \\ \overline{c}_{\text{rotor}_{i,r}} \end{array} \right) = \left(\begin{array}{c} \overline{c}_{\text{stator.}(r)} \\ \overline{c}_{\text{rotor.}(r)} \end{array} \right) \\ \left(\begin{array}{c} \overline{c}_{\text{stator}} \\ \overline{c}_{\text{rotor}} \end{array} \right) \end{array} \right.$$

$$\overline{c}_{\text{stator}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.00 \\ \hline 2 & 5.00 \\ \hline 3 & 7.00 \\ \hline \end{array} \cdot \%$$

$$\overline{c}_{\text{rotor}}^T = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 16.00 \\ \hline 2 & 6.00 \\ \hline 3 & 3.00 \\ \hline \end{array} \cdot \%$$

$$\overline{c}_{\text{CA}} = \left| \begin{array}{l} \text{for } r \in 1..N_r \\ \overline{c}_{\text{CA}_r} = \overline{c}_{\text{stator.}(r)} \\ \overline{c}_{\text{CA}} \end{array} \right.$$

$$\overline{c}_{\text{CA}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 3.00 \\ \hline 2 & 5.00 \\ \hline 3 & 7.00 \\ \hline \end{array} \cdot \%$$

$$\begin{pmatrix} \overline{r_inlet_{BHA}} \\ \overline{r_outlet_{BHA}} \end{pmatrix} = \begin{cases} \text{for } r \in 1..N_r & \text{if BHA} = 1 \\ \begin{pmatrix} \overline{r_inlet_{BHA_r}} \\ \overline{r_outlet_{BHA_r}} \end{pmatrix} = \begin{pmatrix} 0.2 \\ 0.1 \end{pmatrix} \cdot \overline{c_{stator.}(r)} \\ \begin{pmatrix} \overline{r_inlet_{BHA}} \\ \overline{r_outlet_{BHA}} \end{pmatrix} \end{cases}$$

$$\begin{pmatrix} \overline{r_inlet_{CA}} \\ \overline{r_outlet_{CA}} \end{pmatrix} = \begin{cases} \text{for } r \in 1..N_r & \text{if CA} = 1 \\ \begin{pmatrix} \overline{r_inlet_{CA_r}} \\ \overline{r_outlet_{CA_r}} \end{pmatrix} = \begin{pmatrix} 0.2 \\ 0.1 \end{pmatrix} \cdot \overline{c_{stator.}(r)} \\ \begin{pmatrix} \overline{r_inlet_{CA}} \\ \overline{r_outlet_{CA}} \end{pmatrix} \end{cases}$$

$$\overline{r_inlet_{BHA}} = 0.000 \cdot \%$$

	1
1	0.600
2	1.000
3	1.400

$$\overline{r_inlet_{stator}}^T = \cdot \%$$

	1
1	0.300
2	0.500
3	0.700

$$\overline{r_outlet_{stator}}^T = \cdot \%$$

$$\overline{r_outlet_{BHA}} = 0.000 \cdot \%$$

$$\begin{pmatrix} \overline{r_inlet_{rotor}} & \overline{r_inlet_{stator}} \\ \overline{r_outlet_{rotor}} & \overline{r_outlet_{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \overline{r_inlet_{stator_{i,r}}} \\ \overline{r_outlet_{stator_{i,r}}} \end{pmatrix} = \begin{pmatrix} 0.2 \\ 0.1 \end{pmatrix} \cdot \overline{c_{stator.}(r)} \\ \begin{pmatrix} \overline{r_inlet_{rotor_{i,r}}} \\ \overline{r_outlet_{rotor_{i,r}}} \end{pmatrix} = \begin{pmatrix} 0.2 \\ 0.1 \end{pmatrix} \cdot \overline{c_{rotor.}(r)} \\ \begin{pmatrix} \overline{r_inlet_{rotor}} & \overline{r_inlet_{stator}} \\ \overline{r_outlet_{rotor}} & \overline{r_outlet_{stator}} \end{pmatrix} \end{cases}$$

$$\overline{r_inlet_{CA}} = 0.000 \cdot \%$$

	1
1	3.200
2	1.200
3	0.600

$$\overline{r_inlet_{rotor}}^T = \cdot \%$$

	1
1	1.600
2	0.600
3	0.300

$$\overline{r_outlet_{rotor}}^T = \cdot \%$$

$$\overline{r_outlet_{CA}} = 0.000 \cdot \%$$

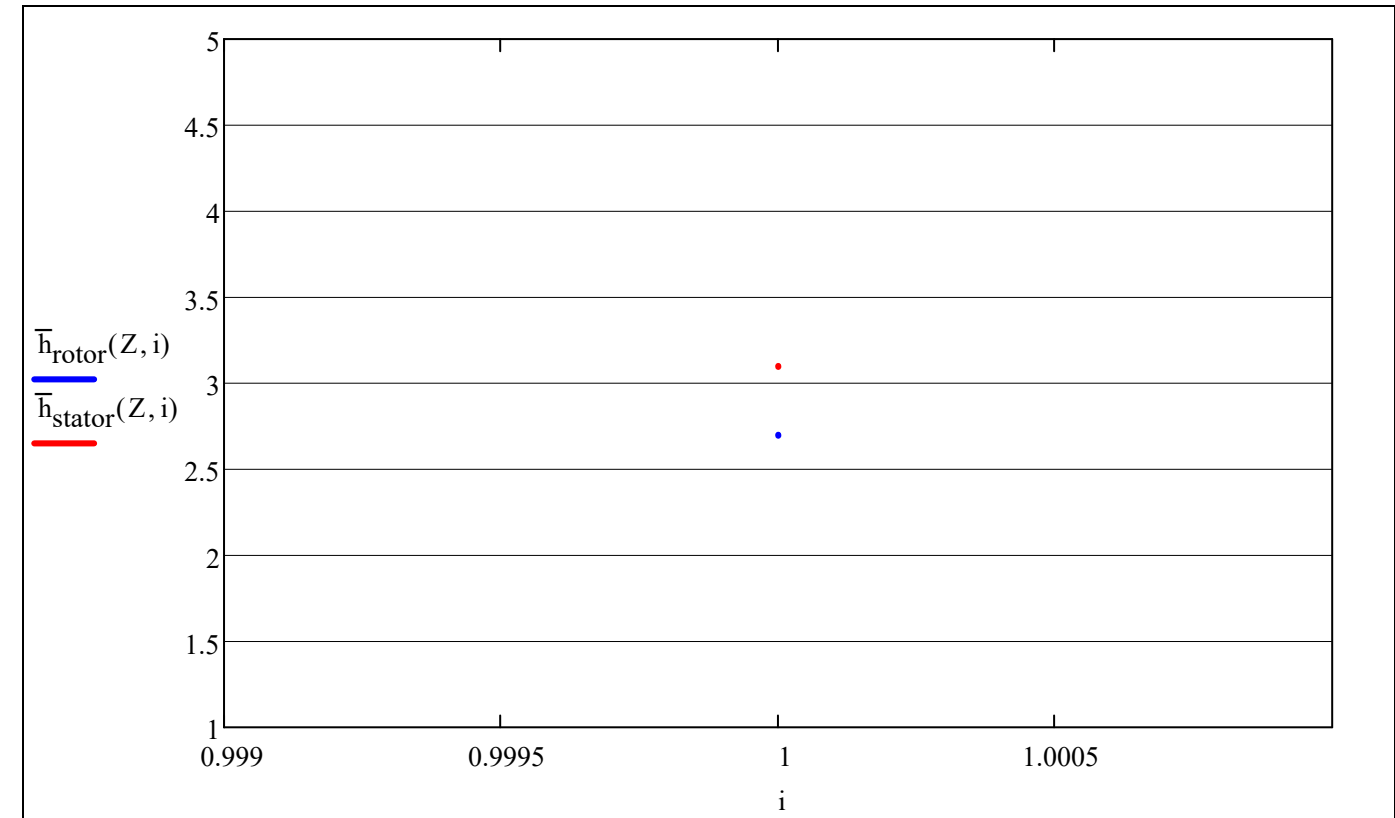
Относ. толщины и радиусы профилей

Относ. удлинение ЛРК и НА: [16, с. 244]

$$\bar{h}_{\sim \text{rotor}} = (2 \quad 1.9 \quad 1.85 \quad 1.8 \quad 1.75 \quad 1.7 \quad 1.65 \quad 1.6)^T + \begin{cases} 1.1 & \text{if compressor = "Вл"} \\ -0.1 & \text{if compressor = "КНД"} \\ -0.55 & \text{if compressor = "КВД"} \end{cases}$$

$$\bar{h}_{\sim \text{stator}} = (4 \quad 3.5 \quad 3.25 \quad 3 \quad 2.75 \quad 2.5 \quad 2.25 \quad 2)^T + \begin{cases} 1.1 & \text{if compressor = "Вл"} \\ -0.1 & \text{if compressor = "КНД"} \\ -0.7 & \text{if compressor = "КВД"} \end{cases}$$

$$\bar{h}_{\text{rotor}}(Z, i) = \begin{cases} \bar{h}_{\sim \text{rotor}}\left(\frac{1}{\text{rows}(z_{\sim})}\right) & \text{if } i < 1 \\ \bar{h}_{\sim \text{rotor}}(1) & \text{if } i > Z \\ \bar{h}_{\sim \text{rotor}}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases} \quad \bar{h}_{\text{stator}}(Z, i) = \begin{cases} \bar{h}_{\sim \text{stator}}\left(\frac{1}{\text{rows}(z_{\sim})}\right) & \text{if } i < 1 \\ \bar{h}_{\sim \text{stator}}(1) & \text{if } i > Z \\ \bar{h}_{\sim \text{stator}}\left(\frac{i}{Z}\right) & \text{otherwise} \end{cases}$$



$$\bar{h}_{\sim \text{rotor}}(i) = \text{interp}\left(\text{cspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, \bar{h}_{\sim \text{rotor}}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, \bar{h}_{\sim \text{rotor}}, i\right)$$

$$\bar{h}_{\sim \text{stator}}(i) = \text{interp}\left(\text{cspline}\left(\frac{z_{\sim}}{\text{rows}(z_{\sim})}, \bar{h}_{\sim \text{stator}}\right), \frac{z_{\sim}}{\text{rows}(z_{\sim})}, \bar{h}_{\sim \text{stator}}, i\right)$$

Для компрессора газогенератора

$$\frac{h_{PK}}{S_{PK}} = 2,5 \dots 4,5 \text{ – для первой дозвуковой ступени;}$$

$$\frac{h_{PK}}{S_{PK}} = 2,0 \dots 3,5 \text{ – для первой околзвуковой ступени;}$$

$$\frac{h_{PK}}{S_{PK}} = 1,7 \dots 3,0 \text{ – для первой сверхзвуковой ступени;}$$

$$\frac{h_{PK}}{S_{PK}} = 1,0 \dots 2,5 \text{ – для последней ступени.}$$

[16, с. 83-84]

Парусность:

$$\begin{pmatrix} \text{sail}_{\text{rotor}} \\ \text{sail}_{\text{stator}} \end{pmatrix} = \begin{pmatrix} 1.3 \\ 1.2 \end{pmatrix}$$

▼ Расчет длин хорд по высоте Л

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chordBHA = for i ∈ 1 if BHA = 1
| chordBHAav(Nr) =  $\frac{h_{\text{st}(i, 1)}}{\bar{h}_{\text{stator}}(Z, 0)}$ 
| sail =  $\frac{R_{\text{st}(1, 1), N_r} - R_{\text{st}(1, 1), 1}}{R_{\text{st}(1, 1), \text{av}(N_r)} - R_{\text{st}(1, 1), 1}}$ 
| for r ∈ 1 .. Nr
| |  $b_{\text{BHAkop}} = \frac{\text{chord}_{\text{BHA}_{\text{av}(N_r)}} \cdot \text{sail}}{\text{sail}_{\text{stator}} - 1 + \text{sail}}$ 
| | bBHAпер = bBHAkop · sailstator
| |  $b_{\text{BHA.}}(z) = \text{interp} \left[ \text{cspline} \left[ \begin{pmatrix} R_{\text{st}(i, 1), 1} \\ R_{\text{st}(i, 1), \text{av}(N_r)} \\ R_{\text{st}(i, 1), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{BHAkop}} \\ \text{chord}_{\text{BHA}_{\text{av}(N_r)}} \\ b_{\text{BHAпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i, 1), 1} \\ R_{\text{st}(i, 1), \text{av}(N_r)} \\ R_{\text{st}(i, 1), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{BHAkop}} \\ \text{chord}_{\text{BHA}_{\text{av}(N_r)}} \\ b_{\text{BHAпер}} \end{pmatrix}, z \right]$ 
| | chordBHAr = bBHA.(Rst(i, 1), r)
| chordBHA
```

$(\text{chord}_{\text{rotor}} \quad \text{chord}_{\text{stator}}) =$	<div>for $i \in 1 \dots Z$</div> <div> $\begin{pmatrix} \text{chord}_{\text{rotor}_{i, \text{av}}(N_r)} \\ \text{chord}_{\text{stator}_{i, \text{av}}(N_r)} \end{pmatrix} = \begin{pmatrix} \frac{\text{mean}(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2))}{\bar{h}_{\text{rotor}}(Z, i)} \\ \frac{\text{mean}(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3))}{\bar{h}_{\text{stator}}(Z, i)} \end{pmatrix}$ </div> <div> $\text{sail} = \frac{R_{\text{st}(i, 2), N_r} - R_{\text{st}(i, 2), 1}}{R_{\text{st}(i, 2), \text{av}}(N_r) - R_{\text{st}(i, 2), 1}}$ </div> <div>for $r \in 1 \dots N_r$</div> <div> $b_{\text{PKkop}} = \frac{\text{chord}_{\text{rotor}_{i, \text{av}}(N_r)} \cdot \text{sail}}{\text{sail}_{\text{rotor}} - 1 + \text{sail}}$ </div> <div> $b_{\text{HAKop}} = \frac{\text{chord}_{\text{stator}_{i, \text{av}}(N_r)} \cdot \text{sail}}{\text{sail}_{\text{stator}} - 1 + \text{sail}}$ </div> <div> $\begin{pmatrix} b_{\text{PKпер}} \\ b_{\text{HAпер}} \end{pmatrix} = \begin{pmatrix} b_{\text{PKkop}} \cdot \text{sail}_{\text{rotor}} \\ b_{\text{HAKop}} \cdot \text{sail}_{\text{stator}} \end{pmatrix}$ </div> <div> $\text{chord}_{\text{rotor.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i, 2), 1} \\ R_{\text{st}(i, 2), \text{av}}(N_r) \\ R_{\text{st}(i, 2), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i, \text{av}}(N_r)} \\ b_{\text{PKпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i, 2), 1} \\ R_{\text{st}(i, 2), \text{av}}(N_r) \\ R_{\text{st}(i, 2), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{PKkop}} \\ \text{chord}_{\text{rotor}_{i, \text{av}}(N_r)} \\ b_{\text{PKпер}} \end{pmatrix}, z \right]$ </div> <div> $\text{chord}_{\text{stator.}}(z) = \text{interp} \left[\text{cspline} \left[\begin{pmatrix} R_{\text{st}(i, 2), 1} \\ R_{\text{st}(i, 2), \text{av}}(N_r) \\ R_{\text{st}(i, 2), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{HAKop}} \\ \text{chord}_{\text{stator}_{i, \text{av}}(N_r)} \\ b_{\text{HAпер}} \end{pmatrix} \right], \begin{pmatrix} R_{\text{st}(i, 2), 1} \\ R_{\text{st}(i, 2), \text{av}}(N_r) \\ R_{\text{st}(i, 2), N_r} \end{pmatrix}, \begin{pmatrix} b_{\text{HAKop}} \\ \text{chord}_{\text{stator}_{i, \text{av}}(N_r)} \\ b_{\text{HAпер}} \end{pmatrix}, z \right]$ </div> <div> $\text{chord}_{\text{rotor}_{i, r}} = \text{chord}_{\text{rotor.}}(R_{\text{st}(i, 2), r})$ </div> <div> $\text{chord}_{\text{stator}_{i, r}} = \text{chord}_{\text{stator.}}(R_{\text{st}(i, 2), r})$ </div> <div>$(\text{chord}_{\text{rotor}} \quad \text{chord}_{\text{stator}})$</div>
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Ср. линия профиля:
0.5 - дуга окружности
0.45 - парабола

$\overline{x_f} = 0.5$

Определение количества Л РК и НА

$$\left(\begin{array}{l} \varepsilon_{BHA(b/t)=1} \\ Z_{BHA} \\ r_{inlet_{BHA}} \\ r_{outlet_{BHA}} \\ t_{BHA} \\ i_{BHA} \\ m_{BHA} \\ \theta_{BHA} \\ \delta_{BHA} \\ \chi_{BHA} \\ v_{BHA} \\ R_{CЛ.BHA} \\ K_{BHA} \\ D_{BHA} \end{array} \right)$$

= if BHA = 1

for $r \in av(N_r)$

$$\varepsilon_{BHA(b/t)=1_r} = \varepsilon_{(b/t)=1}(\alpha_{3BHA_r})$$

$$b/t_{BHA_r} = b/t=1 \left(\frac{\varepsilon_{BHA_r}}{\varepsilon_{BHA(b/t)=1_r}} \right)$$

$$t_{BHA_r} = \frac{chord_{BHA_r}}{b/t_{BHA_r}}$$

$$Z_{BHA} = \left\{ \begin{array}{l} \text{round}\left(\frac{\pi \cdot D_{st(1,1),r}}{t_{BHA_r}}\right) \text{ if } \text{mod}\left(\text{round}\left(\frac{\pi \cdot D_{st(1,1),r}}{t_{BHA_r}}\right), 2\right) = 0 \\ \text{round}\left(\frac{\pi \cdot D_{st(1,1),r}}{t_{BHA_r}}\right) + 1 \text{ otherwise} \end{array} \right.$$

for $r \in 1..N_r$

$$\left(r_{inlet_{BHA_r}} \ r_{outlet_{BHA_r}} \right) = chord_{BHA_r} \cdot \left(\overline{r}_{inlet_{BHA_r}} \ \overline{r}_{outlet_{BHA_r}} \right)$$

$$t_{BHA_r} = \frac{D_{st(1,1),r}}{Z_{BHA}}$$

$$i_{BHA_r} = 2.5 \cdot \left(\frac{chord_{BHA_r}}{t_{BHA_r}} - 2 \right) \cdot ^\circ$$

$$m_{BHA} = 0.23 \cdot \left(2 \cdot \overline{x_f} \right)^2 + 0.18 - \frac{0.002}{1 + \overline{x_f}} \cdot \left(\alpha_{3BHA} \right)$$

$$\theta_{\text{BHA}_r} = \frac{\epsilon_{\text{BHA}_r} - i_{\text{BHA}_r}}{1 - m_{\text{BHA}_r} \cdot \sqrt{\frac{t_{\text{BHA}_r}}{\text{chord}_{\text{BHA}_r}}}}$$

$$\begin{pmatrix}
\epsilon_{\text{PK}(\text{b/t})=1} & \epsilon_{\text{HA}(\text{b/t})=1} \\
Z_{\text{rotor}} & Z_{\text{stator}} \\
r_{\text{inlet}_{\text{rotor}}} & r_{\text{inlet}_{\text{stator}}} \\
r_{\text{outlet}_{\text{rotor}}} & r_{\text{outlet}_{\text{stator}}} \\
t_{\text{rotor}} & t_{\text{stator}} \\
i_{\text{rotor}} & i_{\text{stator}} \\
m_{\text{rotor}} & m_{\text{stator}} \\
\theta_{\text{rotor}} & \theta_{\text{stator}} \\
\delta_{\text{rotor}} & \delta_{\text{stator}} \\
\chi_{\text{rotor}} & \chi_{\text{stator}} \\
v_{\text{rotor}} & v_{\text{stator}} \\
R_{\text{CJL.rotor}} & R_{\text{CJL.stator}} \\
K_{\text{rotor}} & K_{\text{stator}} \\
D_{\text{rotor}} & D_{\text{stator}} \\
\zeta_{\text{rotor}} & \zeta_{\text{stator}} \\
\text{quality}_{\text{rotor}} & \text{quality}_{\text{stator}} \\
\eta_{\text{stage}} & \eta_{\text{stage}}
\end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \quad \text{for } r \in \text{av}(N_r) \\ \quad \left(\begin{array}{l} \epsilon_{\text{PK}(\text{b/t})=1_{i,r}} \\ \epsilon_{\text{HA}(\text{b/t})=1_{i,r}} \end{array} \right) = \left(\begin{array}{l} \epsilon_{(\text{b/t})=1}(\beta_{\text{st}(i,2),r}) \\ \epsilon_{(\text{b/t})=1}(\alpha_{\text{st}(i,3),r}) \end{array} \right) \\ \quad \left(\begin{array}{l} \text{b/t}_{\text{PK}_{i,r}} \\ \text{b/t}_{\text{HA}_{i,r}} \end{array} \right) = \left(\begin{array}{l} \text{b/t}=1 \left(\frac{\epsilon_{\text{rotor}_{i,r}}}{\epsilon_{\text{PK}(\text{b/t})=1_{i,r}}} \right) \\ \text{b/t}=1 \left(\frac{\epsilon_{\text{stator}_{i,r}}}{\epsilon_{\text{HA}(\text{b/t})=1_{i,r}}} \right) \end{array} \right) \\ \quad \left(\begin{array}{l} t_{\text{rotor}_{i,r}} \\ t_{\text{stator}_{i,r}} \end{array} \right) = \left(\begin{array}{l} \frac{\text{chord}_{\text{rotor}_{i,r}}}{\text{b/t}_{\text{PK}_{i,r}}} \\ \frac{\text{chord}_{\text{stator}_{i,r}}}{\text{b/t}_{\text{HA}_{i,r}}} \end{array} \right) \\ \quad \left(\begin{array}{l} t_{\text{rotor}_{i,r}} \\ t_{\text{stator}_{i,r}} \end{array} \right) = \frac{2}{3} \left(\begin{array}{l} \text{chord}_{\text{rotor}_{i,r}} \cdot \cos(\beta_{\text{st}(i,1),r}) \\ \text{chord}_{\text{stator}_{i,r}} \cdot \cos(\alpha_{\text{st}(i,2),r}) \end{array} \right) \\ \quad Z_{\text{stator}_i} = \left| \begin{array}{l} \text{round} \left(\frac{\pi \cdot \text{mean}(D_{\text{st}(i,2),r}, D_{\text{st}(i,3),r})}{t_{\text{stator}_{i,r}}} \right) \text{ if } \text{mod} \left(\text{round} \left(\frac{\pi \cdot \text{mean}(D_{\text{st}(i,2),r}, D_{\text{st}(i,3),r})}{t_{\text{stator}_{i,r}}} \right), 2 \right) = 0 \\ \text{round} \left(\frac{\pi \cdot \text{mean}(D_{\text{st}(i,2),r}, D_{\text{st}(i,3),r})}{t_{\text{stator}_{i,r}}} \right) + 1 \text{ otherwise} \end{array} \right. \\ \quad Z_{\text{rotor}_i} = \left| \begin{array}{l} Z_{\text{rotor}_i} = \text{round} \left(\frac{\pi \cdot \text{mean}(D_{\text{st}(i,1),r}, D_{\text{st}(i,2),r})}{t_{\text{rotor}_{i,r}}} \right) \end{array} \right.
\end{array}$$

while $\gcd(Z_{\text{rotor}_i}, Z_{\text{stator}_i}) \neq 1$

$$Z_{\text{rotor}_i} = Z_{\text{rotor}_i} + 1$$

for $r \in 1 \dots N_r$

$$\begin{pmatrix} r_{\text{inlet}_{\text{stator}_i, r}} & r_{\text{outlet}_{\text{stator}_i, r}} \\ r_{\text{inlet}_{\text{rotor}_i, r}} & r_{\text{outlet}_{\text{rotor}_i, r}} \end{pmatrix} = \begin{pmatrix} \bar{r}_{\text{inlet}_{\text{stator}_i, r}} \cdot \text{chord}_{\text{stator}_i, r} & \bar{r}_{\text{outlet}_{\text{stator}_i, r}} \cdot \text{chord}_{\text{stator}_i, r} \\ \bar{r}_{\text{inlet}_{\text{rotor}_i, r}} \cdot \text{chord}_{\text{rotor}_i, r} & \bar{r}_{\text{outlet}_{\text{rotor}_i, r}} \cdot \text{chord}_{\text{rotor}_i, r} \end{pmatrix}$$

$$\begin{pmatrix} t_{\text{rotor}_i, r} \\ t_{\text{stator}_i, r} \end{pmatrix} = \pi \cdot \begin{pmatrix} \frac{\text{mean}(D_{\text{st}(i, 1), r}, D_{\text{st}(i, 2), r})}{Z_{\text{rotor}_i}} \\ \frac{\text{mean}(D_{\text{st}(i, 2), r}, D_{\text{st}(i, 3), r})}{Z_{\text{stator}_i}} \end{pmatrix}$$

$$\begin{pmatrix} i_{\text{rotor}_i, r} \\ i_{\text{stator}_i, r} \end{pmatrix} = 2.5 \cdot \begin{pmatrix} \frac{\text{chord}_{\text{rotor}_i, r} - 1}{t_{\text{rotor}_i, r}} \\ \frac{\text{chord}_{\text{stator}_i, r} - 2}{t_{\text{stator}_i, r}} \end{pmatrix} \cdot \circ$$

$$\begin{pmatrix} m_{\text{rotor}_i, r} \\ m_{\text{stator}_i, r} \end{pmatrix} = 0.23 \cdot (2 \cdot \bar{x}_f)^2 + 0.18 - \frac{0.002}{\text{deg}} \cdot \begin{pmatrix} \beta_{\text{st}(i, 2), r} \\ \alpha_{\text{st}(i, 3), r} \end{pmatrix}$$

$$\begin{pmatrix} \theta_{\text{rotor}_i, r} \\ \theta_{\text{stator}_i, r} \end{pmatrix} = \begin{pmatrix} \frac{\epsilon_{\text{rotor}_i, r} - i_{\text{rotor}_i, r}}{1 - m_{\text{rotor}_i, r} \cdot \sqrt{\frac{t_{\text{rotor}_i, r}}{\text{chord}_{\text{rotor}_i, r}}}} \\ \frac{\epsilon_{\text{stator}_i, r} - i_{\text{stator}_i, r}}{1 - m_{\text{stator}_i, r} \cdot \sqrt{\frac{t_{\text{stator}_i, r}}{\text{chord}_{\text{stator}_i, r}}}} \end{pmatrix}$$

$$\begin{pmatrix} \delta_{\text{rotor}_i, r} \\ \delta_{\text{stator}_i, r} \end{pmatrix} = \begin{pmatrix} m_{\text{rotor}_i, r} \cdot \theta_{\text{rotor}_i, r} \cdot \sqrt{\frac{t_{\text{rotor}_i, r}}{\text{chord}_{\text{rotor}_i, r}}} \\ m_{\text{stator}_i, r} \cdot \theta_{\text{stator}_i, r} \cdot \sqrt{\frac{t_{\text{stator}_i, r}}{\text{chord}_{\text{stator}_i, r}}} \end{pmatrix}$$

$$\begin{pmatrix} \chi_{\text{rotor}_i, r} \\ \chi_{\text{stator}_i, r} \end{pmatrix} = \begin{pmatrix} \theta_{\text{rotor}_i, r} \\ \theta_{\text{stator}_i, r} \end{pmatrix} \cdot \frac{1 + 2 \cdot (1 - 2 \cdot \bar{x}_f)}{2}$$

$$\begin{pmatrix} v_{\text{rotor}_i, r} \\ v_{\text{stator}_i, r} \end{pmatrix} = \begin{pmatrix} \chi_{\text{rotor}_i, r} + \beta_{\text{st}(i, 1), r} + i_{\text{rotor}_i, r} \\ \chi_{\text{stator}_i, r} + \beta_{\text{st}(i, 2), r} + i_{\text{stator}_i, r} \end{pmatrix}$$

$$\begin{aligned}
\begin{pmatrix} v_{\text{stator}_{i,r}}^{1,r} \end{pmatrix} &= \begin{pmatrix} x_{\text{stator}_{i,r}}^{1,r} + \alpha_{\text{st}(i,2),r} + i_{\text{stator}_{i,r}}^{1,r} \end{pmatrix} \\
\begin{pmatrix} R_{\text{CJL.rotor}_{i,r}} \\ R_{\text{CJL.stator}_{i,r}} \end{pmatrix} &= \frac{1}{2} \cdot \begin{pmatrix} \frac{\text{chord}_{\text{rotor}_{i,r}}}{\sin(0.5 \cdot \theta_{\text{rotor}_{i,r}})} \\ \frac{\text{chord}_{\text{stator}_{i,r}}}{\sin(0.5 \cdot \theta_{\text{stator}_{i,r}})} \end{pmatrix} \\
\begin{pmatrix} K_{\text{rotor}_{i,r}} \\ K_{\text{stator}_{i,r}} \end{pmatrix} &= \begin{pmatrix} \frac{c_{a_{\text{st}(i,2),r}}}{c_{a_{\text{st}(i,1),r}}} \\ \frac{c_{a_{\text{st}(i,3),r}}}{c_{a_{\text{st}(i,2),r}}} \end{pmatrix} \\
\begin{pmatrix} D_{\text{rotor}_{i,r}} \\ D_{\text{stator}_{i,r}} \end{pmatrix} &= \begin{bmatrix} \left(1 - K_{\text{rotor}_{i,r}} \cdot \frac{\sin(\beta_{\text{st}(i,1),r})}{\sin(|\beta_{\text{st}(i,2),r}|)} \right) + \left(\frac{1}{\tan(\beta_{\text{st}(i,1),r})} - K_{\text{rotor}_{i,r}} \cdot \frac{1}{\tan(\beta_{\text{st}(i,2),r})} \right) \cdot \frac{\sin(\beta_{\text{st}(i,1),r})}{2 \cdot \frac{\text{chord}_{\text{rotor}_{i,r}}}{t_{\text{rotor}_{i,r}}}} \\ \left(1 - K_{\text{stator}_{i,r}} \cdot \frac{\sin(\alpha_{\text{st}(i,2),r})}{\sin(\alpha_{\text{st}(i,3),r})} \right) + \left(\frac{1}{\tan(\alpha_{\text{st}(i,2),r})} - K_{\text{stator}_{i,r}} \cdot \frac{1}{\tan(\alpha_{\text{st}(i,3),r})} \right) \cdot \frac{\sin(\alpha_{\text{st}(i,2),r})}{2 \cdot \frac{\text{chord}_{\text{stator}_{i,r}}}{t_{\text{stator}_{i,r}}}} \end{bmatrix} \\
\begin{pmatrix} \zeta_{\text{rotor}_{i,r}} \\ \zeta_{\text{stator}_{i,r}} \end{pmatrix} &= \begin{pmatrix} \frac{\zeta \cdot \sin(\beta_3) / (2b/t) \left(D_{\text{rotor}_{i,r}} \right) \cdot 2 \cdot \frac{\text{chord}_{\text{rotor}_{i,r}}}{t_{\text{rotor}_{i,r}}}}{\sin(\beta_{\text{st}(i,2),r})} \\ \frac{\zeta \cdot \sin(\beta_3) / (2b/t) \left(D_{\text{stator}_{i,r}} \right) \cdot 2 \cdot \frac{\text{chord}_{\text{stator}_{i,r}}}{t_{\text{stator}_{i,r}}}}{\sin(\alpha_{\text{st}(i,3),r})} \end{pmatrix} \\
\begin{pmatrix} \beta_{\text{cp}_{i,r}} \\ \alpha_{\text{cp}_{i,r}} \end{pmatrix} &= \begin{pmatrix} \text{atan} \left(\frac{c_{a_{\text{st}(i,1),r}}}{\text{mean}(w_{u_{\text{st}(i,1),r}}, w_{u_{\text{st}(i,2),r}})} \right) \\ \text{atan} \left(\frac{c_{a_{\text{st}(i,2),r}}}{\text{mean}(c_{u_{\text{st}(i,2),r}}, c_{u_{\text{st}(i,3),r}})} \right) \end{pmatrix} \\
\begin{pmatrix} \text{quality}_{\text{rotor}_{i,r}} \\ \text{quality}_{\text{stator}_{i,r}} \end{pmatrix} &= \begin{bmatrix} \frac{2}{\zeta_{\text{rotor}_{i,r}}} \cdot \left(\frac{1}{\tan(\beta_{\text{st}(i,1),r})} - \frac{1}{\tan(\beta_{\text{st}(i,2),r})} \right) \cdot \left(\frac{\sin(\beta_{\text{st}(i,1),r})}{\sin(\beta_{\text{cp}_{i,r}})} \right)^2 - \frac{1}{\tan(\beta_{\text{cp}_{i,r}})} \\ \frac{2}{\zeta_{\text{stator}_{i,r}}} \cdot \left(\frac{1}{\tan(\alpha_{\text{st}(i,2),r})} - \frac{1}{\tan(\alpha_{\text{st}(i,3),r})} \right) \cdot \left(\frac{\sin(\alpha_{\text{st}(i,2),r})}{\sin(\alpha_{\text{cn}})} \right)^2 - \frac{1}{\tan(\alpha_{\text{cn}})} \end{bmatrix}
\end{aligned}$$

$$\eta_{\text{stage}_{i,r}} = 1 - \frac{\left(\frac{c_{a_{\text{st}(i,1),r}}}{u_{\text{st}(i,1),r}} \right)^2 + (R_{L_{i,r}})^2}{\text{quality}_{\text{rotor}_{i,r}} \cdot \frac{c_{a_{\text{st}(i,1),r}}}{u_{\text{st}(i,1),r}} + R_{L_{i,r}}} + \frac{\left(\frac{c_{a_{\text{st}(i,2),r}}}{u_{\text{st}(i,2),r}} \right)^2 + (1 - R_{L_{i,r}})^2}{\text{quality}_{\text{stator}_{i,r}} \cdot \frac{c_{a_{\text{st}(i,2),r}}}{u_{\text{st}(i,2),r}} + (1 - R_{L_{i,r}})}$$

$$\left(\begin{array}{c} \varepsilon_{\text{PK(b/t)=1}} \\ \varepsilon_{\text{HA(b/t)=1}} \end{array} \begin{array}{c} Z_{\text{rotor}} \\ Z_{\text{stator}} \end{array} \begin{array}{c} r_{\text{inlet}_{\text{rotor}}} \\ r_{\text{inlet}_{\text{stator}}} \end{array} \begin{array}{c} r_{\text{outlet}_{\text{rotor}}} \\ r_{\text{outlet}_{\text{stator}}} \end{array} \begin{array}{c} t_{\text{rotor}} \\ t_{\text{stator}} \end{array} \begin{array}{c} i_{\text{rotor}} \\ i_{\text{stator}} \end{array} \begin{array}{c} m_{\text{rotor}} \\ m_{\text{stator}} \end{array} \begin{array}{c} \theta_{\text{rotor}} \\ \theta_{\text{stator}} \end{array} \begin{array}{c} \delta_{\text{rotor}} \\ \delta_{\text{stator}} \end{array} \begin{array}{c} \chi_{\text{rotor}} \\ \chi_{\text{stator}} \end{array} \begin{array}{c} v_{\text{rotor}} \\ v_{\text{stator}} \end{array} \begin{array}{c} R_{\text{CJL.rotor}} \\ R_{\text{CJL.stator}} \end{array} \begin{array}{c} K_{\text{rotor}} \\ K_{\text{stator}} \end{array} \begin{array}{c} D_{\text{rotor}} \\ D_{\text{stator}} \end{array} \begin{array}{c} \zeta_{\text{rotor}} \\ \zeta_{\text{stator}} \end{array} \begin{array}{c} \text{quality}_{\text{rotor}} \\ \text{quality}_{\text{stator}} \end{array} \begin{array}{c} \eta_{\text{stage}} \\ \eta_{\text{stage}} \end{array} \right)^T$$

$$\begin{pmatrix} \varepsilon_{CA(b/t)=1} \\ Z_{CA} \\ r_{inlet_{CA}} \\ r_{outlet_{CA}} \\ t_{CA} \\ i_{CA} \\ m_{CA} \\ \theta_{CA} \\ \delta_{CA} \\ \chi_{CA} \\ v_{CA} \\ R_{CJL,CA} \\ K_{CA} \\ D_{CA} \end{pmatrix} = \begin{cases} \text{if } CA = 1 \\ \quad \text{for } r \in av(N_r) \\ \quad \left| \begin{array}{l} \varepsilon_{CA(b/t)=1_r} = \varepsilon_{(b/t)=1}(\alpha_{3CA_r}) \\ b/t_{CA_r} = b/t=1 \left(\frac{\varepsilon_{CA_r}}{\varepsilon_{CA(b/t)=1_r}} \right) \\ t_{CA_r} = \frac{chord_{CA_r}}{b/t_{CA_r}} \\ Z_{CA} = \begin{cases} \text{round}\left(\frac{\pi \cdot D_{st}(Z,3),r}{t_{CA_r}}\right) & \text{if } \text{mod}\left(\text{round}\left(\frac{\pi \cdot D_{st}(Z,3),r}{t_{CA_r}}\right), 2\right) = 0 \\ \text{round}\left(\frac{\pi \cdot D_{st}(Z,3),r}{t_{CA_r}}\right) + 1 & \text{otherwise} \end{cases} \end{array} \right. \\ \quad \text{for } r \in 1..N_r \\ \quad \left| \begin{array}{l} (r_{inlet_{CA_r}} \ r_{outlet_{CA_r}}) = chord_{CA_r} \cdot (\bar{r}_{inlet_{CA_r}} \ \bar{r}_{outlet_{CA_r}}) \\ t_{CA_r} = \frac{D_{st}(Z,3),r}{Z_{CA}} \\ i_{CA_r} = 2.5 \cdot \left(\frac{chord_{CA_r}}{t_{CA_r}} - 2 \right) \cdot ^\circ \\ m_{CA_r} = 0.23 \cdot (2 \cdot \bar{x}_f)^2 + 0.18 - \frac{0.002}{deg} \cdot (\alpha_{3CA_r}) \\ \theta_{CA_r} = \frac{\varepsilon_{CA_r} - i_{CA_r}}{1 - m_{CA_r} \cdot \sqrt{\frac{t_{CA_r}}{chord_{CA_r}}}} \end{array} \right. \end{cases}
\end{pmatrix}$$

$$\delta_{CA_r} = m_{CA_r} \cdot \theta_{CA_r} \cdot \sqrt{\frac{r_{CA_r}}{\text{chord}_{CA_r}}}$$

$$\chi_{\text{CA}_r} = \theta_{\text{CA}_r} \cdot \frac{1 + 2 \cdot (1 - 2 \cdot \bar{x}_f)}{2}$$

$$v_{\text{CA}_r} = \chi_{\text{CA}_r} + \alpha_{1\text{CA}_r} + i_{\text{CA}_r}$$

$$R_{CJL,CA_r} = \frac{\text{chord}_{CA_r}}{2 \cdot \sin\left(0.5 \cdot \theta_{CA_r}\right)}$$

$$K_{CA_r} = \frac{c_{a3CA_r}}{c_{a1CA_r}}$$

$$D_{CA_r} = \left(1 - K_{CA_r} \cdot \frac{\sin(\alpha_{1CA_r})}{\sin(\alpha_{3CA_r})} \right) + \left(\frac{1}{\tan(\alpha_{1CA_r})} - K_{CA_r} \cdot \frac{1}{\tan(\alpha_{3CA_r})} \right) \cdot \frac{\sin(\alpha_{1CA_r})}{2 \cdot \frac{\text{chord}_{CA_r}}{t_{CA_r}}}$$

$$\left(\varepsilon_{CA(b/t)=1} \quad Z_{CA} \quad r_{inlet_CA} \quad r_{outlet_CA} \quad t_{CA} \quad i_{CA} \quad m_{CA} \quad \theta_{CA} \quad \delta_{CA} \quad \chi_{CA} \quad v_{CA} \quad R_{CJ,CA} \quad K_{CA} \quad D_{CA} \right)^T$$

$\text{chord}_{\text{BHA}} = 0.00 \cdot 10^{-3}$

$\text{chord}_{\text{rotor}}^{\text{T}} =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	140.51														
2	165.54														
3	182.66														

$\cdot 10^{-3}$

Длина хорды Л (м):

$\text{chord}_{\text{stator}}^{\text{T}} =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	119.15														
2	133.30														
3	142.98														

$\cdot 10^{-3}$

$\text{chord}_{\text{CA}} = 0.00 \cdot 10^{-3}$

Радисы входных и выходных кромок профилей Л (мм):

$\text{r_inlet}_{\text{BHA}} = 0.00 \cdot 10^{-3}$

$\text{r_outlet}_{\text{BHA}} = 0.00 \cdot 10^{-3}$

$\text{r_inlet}_{\text{rotor}}^{\text{T}} =$

	1
1	4.50
2	1.99
3	1.10

$\cdot 10^{-3}$

$\text{r_inlet}_{\text{stator}}^{\text{T}} =$

	1
1	0.71
2	1.33
3	2.00

$\cdot 10^{-3}$

$\text{r_outlet}_{\text{rotor}}^{\text{T}} =$

	1
1	2.25
2	0.99
3	0.55

$\cdot 10^{-3}$

$\text{r_outlet}_{\text{stator}}^{\text{T}} =$

	1
1	0.36
2	0.67
3	1.00

$\cdot 10^{-3}$

$\text{r_inlet}_{\text{CA}} = 0.00 \cdot 10^{-3}$

$\text{r_outlet}_{\text{CA}} = 0.00 \cdot 10^{-3}$

$\epsilon_{\text{BHA}(\text{b/t})=1_{\text{av}(\text{N}_r)}} = \blacksquare \cdot ^\circ$

Угол поворота потока:

$\text{submatrix}\left(\epsilon_{\text{PK}(\text{b/t})=1}, 1, Z, \text{av}\left(\text{N}_r\right), \text{av}\left(\text{N}_r\right)\right)^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	9.86														

 $\cdot ^\circ$

$\text{submatrix}\left(\epsilon_{\text{HA}(\text{b/t})=1}, 1, Z, \text{av}\left(\text{N}_r\right), \text{av}\left(\text{N}_r\right)\right)^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	15.65														

 $\cdot ^\circ$

$\epsilon_{\text{CA}(\text{b/t})=1_{\text{av}(\text{N}_r)}} = \blacksquare \cdot ^\circ$

$\frac{\text{chord}_{\text{BHA}}}{t_{\text{BHA}}} = \blacksquare$

Густота решетки:

$\left(\frac{\text{chord}_{\text{rotor}}}{t_{\text{rotor}}}\right)^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	2.582														
2	1.657														
3	1.402														

$\left(\frac{\text{chord}_{\text{stator}}}{t_{\text{stator}}}\right)^T =$

	1
1	2.998
2	1.987
3	1.660

$\frac{\text{chord}_{\text{CA}}}{t_{\text{CA}}} = \blacksquare$

$Z_{\text{BHA}} = 0$

Количество Л:

$Z_{\text{rotor}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	37														

$Z_{\text{stator}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	56														

$Z_{\text{CA}} = 0$

Значения округляются до целого в большую сторону так, чтобы при разъемном корпусе количество Л НА было четным, а количества Л РК и НА были взаимно простыми

$t_{BHA} = 0.00 \cdot 10^{-3}$

$t_{rotor}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	54.43														
2	99.89														
3	130.33														

$\cdot 10^{-3}$

Шаг решетки (м):

$t_{stator}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	39.75														
2	67.07														
3	86.11														

$\cdot 10^{-3}$

$t_{CA} = 0.00 \cdot 10^{-3}$

$i_{BHA} = 0.000 \cdot ^\circ$

$i_{rotor}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	3.954														
2	1.643														
3	1.004														

$\cdot ^\circ$

Угол атаки:

$i_{stator}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	2.494														
2	-0.032														
3	-0.849														

$\cdot ^\circ$

$i_{CA} = 0.000 \cdot ^\circ$

$m_{BHA} = 0.0000$

$m_{rotor}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.1803														
2	0.3369														
3	0.3709														

Коэф. формы ср. линии профиля по Ховеллу:

$m_{stator}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.3100														
2	0.3072														
3	0.3043														

$m_{CA} = 0.0000$

$\theta_{BHA} = 0.00 \cdot ^\circ$

$\theta_{rotor}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	74.71														
2	15.09														
3	1.13														

 $\cdot ^\circ$

Угол изгиба ср. линии профиля:

$\theta_{stator}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	15.86														
2	15.70														
3	15.61														

 $\cdot ^\circ$

$\theta_{CA} = 0.00 \cdot ^\circ$

$\delta_{\text{BHA}} = 0.000 \cdot ^\circ$

$\delta_{\text{rotor}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 8.384 \\ \hline 2 & 3.948 \\ \hline 3 & 0.353 \\ \hline \end{array} \cdot ^\circ$

Угол отставания:

$\delta_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 2.840 \\ \hline 2 & 3.421 \\ \hline 3 & 3.685 \\ \hline \end{array} \cdot ^\circ$

$\delta_{\text{CA}} = 0.000 \cdot ^\circ$

$v_{\text{BHA}} = 0.00 \cdot ^\circ$

$v_{\text{rotor}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 85.87 \\ \hline 2 & 32.97 \\ \hline 3 & 19.36 \\ \hline \end{array} \cdot ^\circ$

Угол установки Л:

$v_{\text{stator}}^{\text{T}} = \begin{array}{|c|c|} \hline & 1 \\ \hline 1 & 44.90 \\ \hline 2 & 46.99 \\ \hline 3 & 48.75 \\ \hline \end{array} \cdot ^\circ$

$v_{\text{CA}} = 0.00 \cdot ^\circ$

$R_{\text{СЛ.ВНА}} = 0.00 \cdot 10^{-3}$

Радиус дуги ср. линии (м):

$R_{\text{СЛ.rotor}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	115.79														
2	630.45														
3	9298.59														

$\cdot 10^{-3}$

$R_{\text{СЛ.stator}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	431.76														
2	488.01														
3	526.55														

$\cdot 10^{-3}$

$R_{\text{СЛ.СА}} = 0.00 \cdot 10^{-3}$

$K_{\text{ВНА}} = 0.0000$

Фактор диффузорности решетки:

$K_{\text{rotor}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	1.1408														
2	0.8955														
3	0.7926														

$K_{\text{stator}}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.7127														
2	0.8833														
3	0.9699														

$K_{\text{СА}} = 0.0000$

$D_{BHA} = 0.0000$

$D_{rotor}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.3277														
2	0.5230														
3	0.3736														

Диффузорность решетки:

$D_{stator}^T =$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.5543														
2	0.3693														
3	0.2663														

$D_{CA} = 0.0000$

$D_{BHA} \leq 0.6 = 1$

$D_{rotor}^T \leq 0.6 =$

	1
1	1
2	1
3	1

[18, с. 71]

$D_{stator}^T \leq 0.6 =$

	1
1	1
2	1
3	1

$D_{CA} \leq 0.6 = 1$

Коэф. потерь полного давления:

Качество профилей решеток РК и НА:

[illegible]

Результаты расчета количества Л и параметров решеток РК и НА

EXCEL_{AIRFOIL.subsonic} =
...\\A40.xlsx

$$X/B_{\text{subsonic}} = \text{submatrix}\left(\text{EXCEL}_{\text{AIRFOIL.subsonic}}, 2, \text{rows}\left(\text{EXCEL}_{\text{AIRFOIL.subsonic}}\right), \text{ORIGIN} + 0, \text{ORIGIN} + 0\right)$$
$$Y/B_{\text{subsonic}} = \text{submatrix}\left(\text{EXCEL}_{\text{AIRFOIL.subsonic}}, 2, \text{rows}\left(\text{EXCEL}_{\text{AIRFOIL.subsonic}}\right), \text{ORIGIN} + 1, \text{ORIGIN} + 1\right)$$

EXCEL_{AIRFOIL.supersonic} =
...\\Емин сверхзвуковой профиль.xlsx

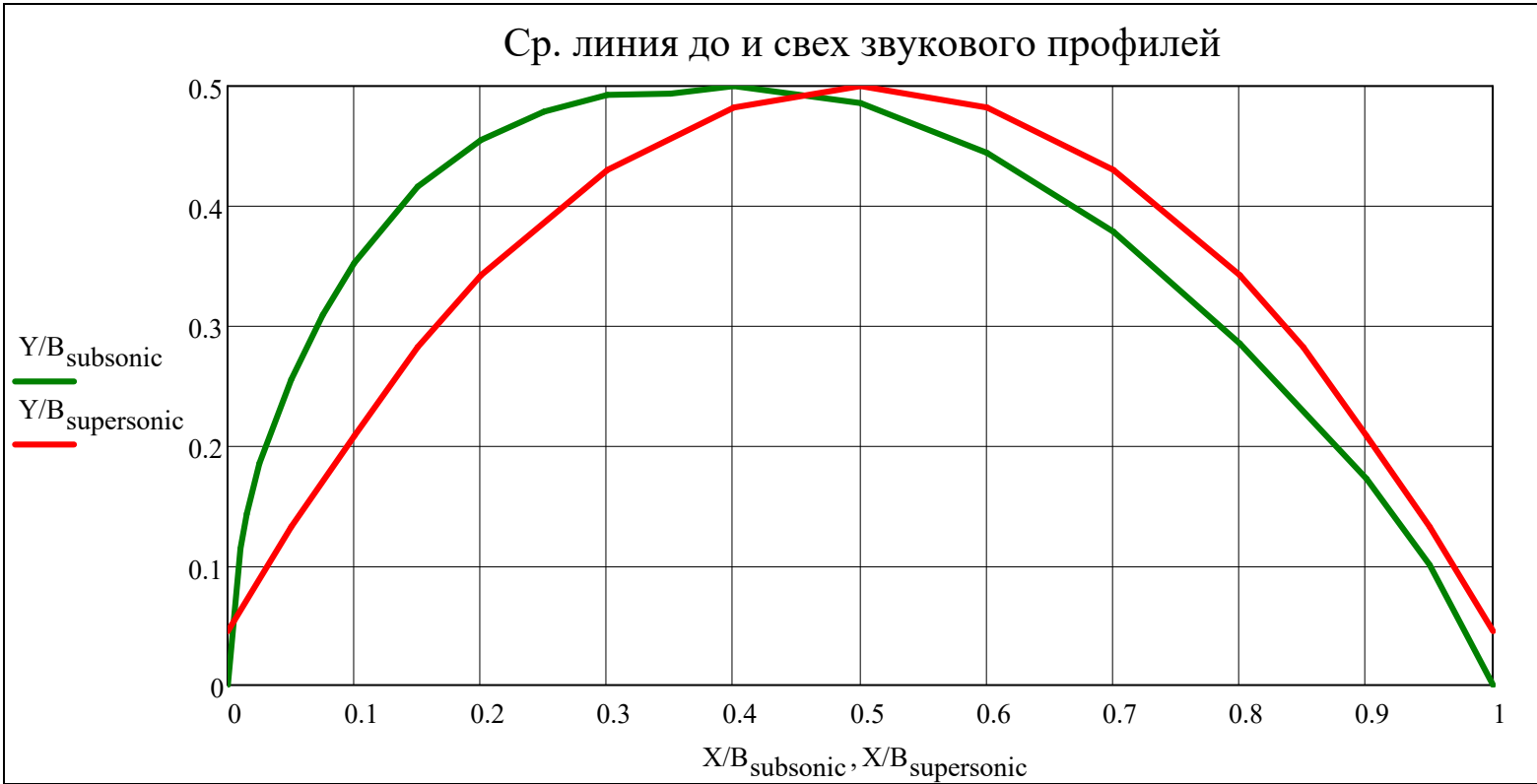
$$X/B_{\text{supersonic}} = \text{submatrix}\left(\text{EXCEL}_{\text{AIRFOIL.supersonic}}, 2, \text{rows}\left(\text{EXCEL}_{\text{AIRFOIL.supersonic}}\right), \text{ORIGIN} + 0, \text{ORIGIN} + 0\right)$$
$$Y/B_{\text{supersonic}} = \text{submatrix}\left(\text{EXCEL}_{\text{AIRFOIL.supersonic}}, 2, \text{rows}\left(\text{EXCEL}_{\text{AIRFOIL.supersonic}}\right), \text{ORIGIN} + 1, \text{ORIGIN} + 1\right)$$

$$\text{augment}\left(X/B_{\text{subsonic}}, Y/B_{\text{subsonic}}\right)^T =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
1	0.000	0.010	0.015	0.025	0.050	0.075	0.100	0.150	0.200	0.250	0.300	0.350	0.400	0.500	0.600	0.700	0.800	0.900	0.950	1.000
2	0.000	0.114	0.143	0.185	0.255	0.309	0.352	0.416	0.455	0.479	0.493	0.494	0.500	0.486	0.444	0.378	0.285	0.172	0.100	0.000

$$\text{augment}\left(X/B_{\text{supersonic}}, Y/B_{\text{supersonic}}\right)^T =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	0.000	0.050	0.100	0.150	0.200	0.300	0.400	0.500	0.600	0.700	0.800	0.850	0.900	0.950	1.000
2	0.045	0.132	0.208	0.282	0.342	0.430	0.482	0.500	0.482	0.430	0.342	0.282	0.208	0.132	0.045



$$l_{upper_stator}^T =$$

	1
1	120.00
2	134.48
3	144.74

$$\cdot 10^{-3}$$

$$l_{lower_stator}^T =$$

	1
1	119.30
2	133.46
3	143.38

$$\cdot 10^{-3}$$

$$area_{stator}^T =$$

	1
1	311.49
2	649.75
3	1046.61

$$\cdot 10^{-6}$$

$$Sx_{stator}^T =$$

	1
1	960.3
2	1767.3
3	2759.9

$$\cdot 10^{-9}$$

$$Sy_{stator}^T =$$

	1
1	16761.6
2	39115.4
3	67582.7

$$\cdot 10^{-9}$$

$$x0_{stator}^T =$$

	1
1	53.81
2	60.20
3	64.57

$$\cdot 10^{-3}$$

$$y0_{stator}^T =$$

	1
1	3.08
2	2.72
3	2.64

$$\cdot 10^{-3}$$

$$l_{upper_rotor}^T =$$

	1
1	161.30
2	166.88
3	182.81

$$\cdot 10^{-3}$$

$$l_{lower_rotor}^T =$$

	1
1	143.99
2	165.54
3	182.71

$$\cdot 10^{-3}$$

$$area_{rotor}^T =$$

	1
1	2310.37
2	1151.87
3	701.28

$$\cdot 10^{-6}$$

$$Sx_{rotor}^T =$$

	1
1	39814.7
2	4165.0
3	388.4

$$\cdot 10^{-9}$$

$$Sy_{rotor}^T =$$

	1
1	146612.4
2	95338.5
3	64049.4

$$\cdot 10^{-9}$$

$$x0_{rotor}^T =$$

	1
1	63.46
2	82.77
3	91.33

$$\cdot 10^{-3}$$

$$y0_{rotor}^T =$$

	1
1	17.23
2	3.62
3	0.55

$$\cdot 10^{-3}$$

$J_{x_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 3497 \\ 2 & 7040 \\ 3 & 14379 \end{bmatrix} \cdot 10^{-12}$

$J_{y_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 1153935 \\ 2 & 3012608 \\ 3 & 5583399 \end{bmatrix} \cdot 10^{-12}$

$J_{xy_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 53733 \\ 2 & 110632 \\ 3 & 185320 \end{bmatrix} \cdot 10^{-12}$

$J_{x0_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 536.41 \\ 2 & 2233.62 \\ 3 & 7101.42 \end{bmatrix} \cdot 10^{-12}$

$J_{y0_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 251977 \\ 2 & 657843 \\ 3 & 1219368 \end{bmatrix} \cdot 10^{-12}$

$J_{xy0_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 2058.42 \\ 2 & 4240.94 \\ 3 & 7105.43 \end{bmatrix} \cdot 10^{-12}$

$\alpha_{major_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 0.47 \\ 2 & 0.37 \\ 3 & 0.34 \end{bmatrix} \cdot \circ$

$J_{x_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 819752 \\ 2 & 22926 \\ 3 & 1449 \end{bmatrix} \cdot 10^{-12}$

$J_{y_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 11903414 \\ 2 & 9610401 \\ 3 & 7124382 \end{bmatrix} \cdot 10^{-12}$

$J_{xy_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 2623407 \\ 2 & 344732 \\ 3 & 35473 \end{bmatrix} \cdot 10^{-12}$

$J_{x0_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 133622.41 \\ 2 & 7865.54 \\ 3 & 1234.18 \end{bmatrix} \cdot 10^{-12}$

$J_{y0_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 2599607 \\ 2 & 1719392 \\ 3 & 1274619 \end{bmatrix} \cdot 10^{-12}$

$J_{xy0_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 96824.41 \\ 2 & -0.99 \\ 3 & -0.10 \end{bmatrix} \cdot 10^{-12}$

$\alpha_{major_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 2.25 \\ 2 & -0.00 \\ 3 & -0.00 \end{bmatrix} \cdot \circ$

$$\mathbf{J_{u_{stator}}}^T = \begin{bmatrix} & 1 \\ 1 & 519.56 \\ 2 & 2206.19 \\ 3 & 7059.77 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{v_{stator}}}^T = \begin{bmatrix} & 1 \\ 1 & 251994 \\ 2 & 657871 \\ 3 & 1219410 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{uv_{stator}}}^T = \begin{bmatrix} & 1 \\ 1 & 0.00 \\ 2 & 0.00 \\ 3 & 0.00 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{p_{stator}}}^T = \begin{bmatrix} & 1 \\ 1 & 252513 \\ 2 & 660077 \\ 3 & 1226469 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{W_{p_{stator}}}^T = \begin{bmatrix} & 1 \\ 1 & 3860.4 \\ 2 & 9024.0 \\ 3 & 15633.8 \end{bmatrix} \cdot 10^{-9}$$

$$\mathbf{stiffness_{stator}}^T = \begin{bmatrix} & 1 \\ 1 & 968.09 \\ 2 & 7020.61 \\ 3 & 25501.84 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{u_{rotor}}}^T = \begin{bmatrix} & 1 \\ 1 & 129826.54 \\ 2 & 7865.54 \\ 3 & 1234.18 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{v_{rotor}}}^T = \begin{bmatrix} & 1 \\ 1 & 2603403 \\ 2 & 1719392 \\ 3 & 1274619 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{uv_{rotor}}}^T = \begin{bmatrix} & 1 \\ 1 & 0.00 \\ 2 & 0.00 \\ 3 & 0.00 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{J_{p_{rotor}}}^T = \begin{bmatrix} & 1 \\ 1 & 2733229 \\ 2 & 1727257 \\ 3 & 1275853 \end{bmatrix} \cdot 10^{-12}$$

$$\mathbf{W_{p_{rotor}}}^T = \begin{bmatrix} & 1 \\ 1 & 34617.3 \\ 2 & 20848.7 \\ 3 & 13969.1 \end{bmatrix} \cdot 10^{-9}$$

$$\mathbf{stiffness_{rotor}}^T = \begin{bmatrix} & 1 \\ 1 & 284045.72 \\ 2 & 26233.50 \\ 3 & 4861.85 \end{bmatrix} \cdot 10^{-12}$$

$$CP_{x_{stator}}^T =$$

	1
1	41.702
2	46.654
3	50.042

$$\cdot 10^{-3}$$

$$CP_{y_{stator}}^T =$$

	1
1	0.0000
2	0.0000
3	0.0000

$$\cdot 10^{-3}$$

$$CP_{x_{rotor}}^T =$$

	1
1	49.179
2	57.938
3	63.932

$$\cdot 10^{-3}$$

$$CP_{y_{rotor}}^T =$$

	1
1	0.0000
2	0.0000
3	0.0000

$$\cdot 10^{-3}$$

Абс. координаты профиля:

Airfoil(type,x,line,i,r) =	<div><div>if type = "BHA"<div><div>AIRFOIL_{subsonic}$\left(x, \text{line}, \overline{c}_{\text{BHA}_r}, \varepsilon_{\text{BHA}_r}\right)$ if $M_{c_{\text{st}(1,1),r}} < 1$</div><div>AIRFOIL_{supersonic}$\left(x, \text{line}, \overline{c}_{\text{BHA}_r}, \varepsilon_{\text{BHA}_r}\right)$ otherwise</div></div></div><div>if type = "rotor"<div><div>AIRFOIL_{subsonic}$\left(x, \text{line}, \overline{c}_{\text{rotor}_{i,r}}, \varepsilon_{\text{rotor}_{i,r}}\right)$ if $M_{w_{\text{st}(i,1),r}} < 1$</div><div>AIRFOIL_{supersonic}$\left(x, \text{line}, \overline{c}_{\text{rotor}_{i,r}}, \varepsilon_{\text{rotor}_{i,r}}\right)$ otherwise</div></div></div><div>if type = "stator"<div><div>AIRFOIL_{subsonic}$\left(x, \text{line}, \overline{c}_{\text{stator}_{i,r}}, \varepsilon_{\text{stator}_{i,r}}\right)$ if $M_{c_{\text{st}(i,2),r}} < 1$</div><div>AIRFOIL_{supersonic}$\left(x, \text{line}, \overline{c}_{\text{stator}_{i,r}}, \varepsilon_{\text{stator}_{i,r}}\right)$ otherwise</div></div></div><div>if type = "CA"<div><div>AIRFOIL_{subsonic}$\left(x, \text{line}, \overline{c}_{\text{CA}_r}, \varepsilon_{\text{CA}_r}\right)$ if $M_{c_{\text{st}(Z,3),r}} < 1$</div><div>AIRFOIL_{supersonic}$\left(x, \text{line}, \overline{c}_{\text{CA}_r}, \varepsilon_{\text{CA}_r}\right)$ otherwise</div></div></div></div>
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Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & \\ j = \begin{cases} \text{"Такой ступени не существует!"} & \text{if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} & \end{cases} = 1$$

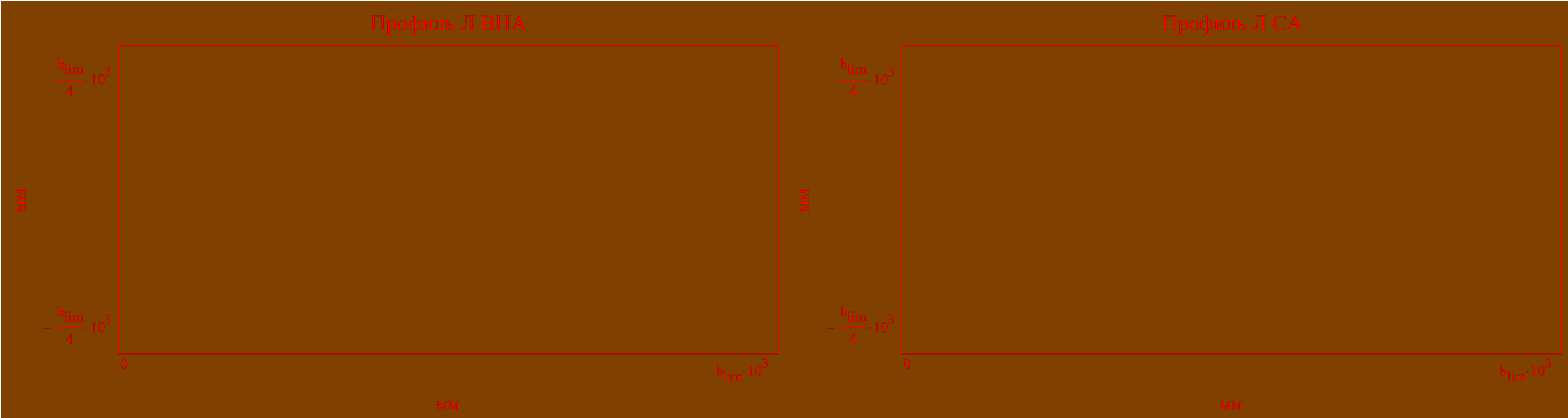
▼ Построение профилей Л РК и НА

$$\text{AXLE0}(\text{type}, \text{x}, \text{i}, \text{r}) = \begin{cases} \frac{y0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} + \tan(\alpha_{\text{major}_{\text{rotor}_{\text{i}, \text{r}}}}) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i}, \text{r}}}}{\text{chord}_{\text{rotor}_{\text{i}, \text{r}}}} \right) & \text{if type = "rotor"} \\ \frac{y0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} + \tan(\alpha_{\text{major}_{\text{stator}_{\text{i}, \text{r}}}}) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i}, \text{r}}}}{\text{chord}_{\text{stator}_{\text{i}, \text{r}}}} \right) & \text{if type = "stator"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

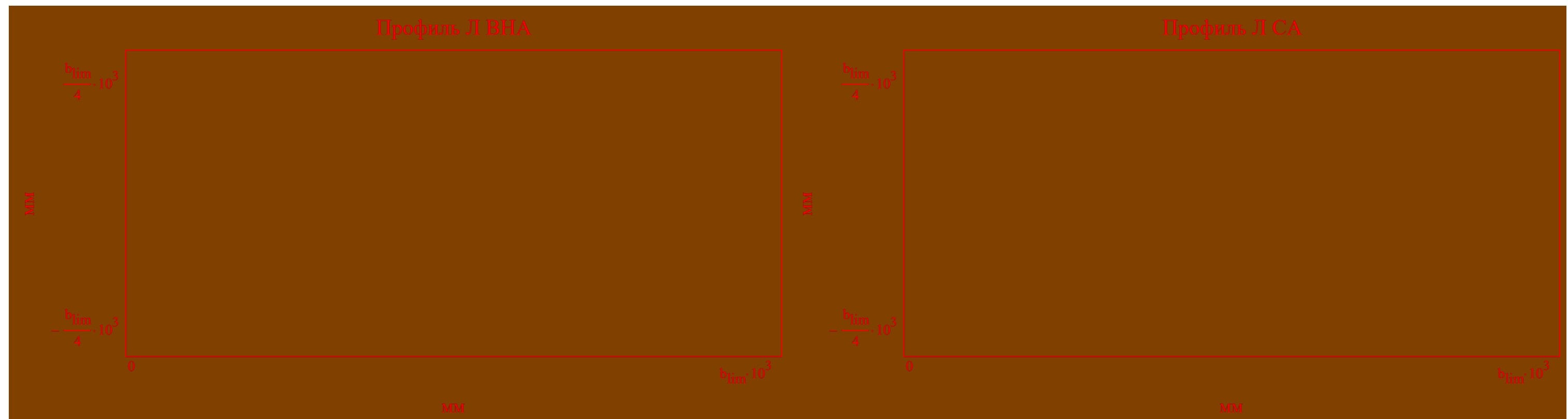
$$\text{AXLE90}(\text{type}, x, i, r) = \begin{cases} \frac{y0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{rotor}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{rotor}_{i,r}}}{\text{chord}_{\text{rotor}_{i,r}}}\right) & \text{if } (\text{type} = \text{"rotor"}) \wedge \left|\alpha_{\text{major}_{\text{rotor}_{i,r}}}\right| \geq 1^\circ \\ \frac{y0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}} + \tan\left(\alpha_{\text{major}_{\text{stator}_{i,r}}} + \frac{\pi}{2}\right) \cdot \left(x - \frac{x0_{\text{stator}_{i,r}}}{\text{chord}_{\text{stator}_{i,r}}}\right) & \text{if } (\text{type} = \text{"stator"}) \wedge \left|\alpha_{\text{major}_{\text{stator}_{i,r}}}\right| \geq 1^\circ \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$b_{\text{lim}} = \frac{\text{ceil}\left(\max\left(\text{chord}_{\text{rotor}_{j, N_r}}, \text{chord}_{\text{stator}_{j, N_r}}\right) \cdot 10^2\right)}{10^2} = 190 \cdot 10^{-3}$$

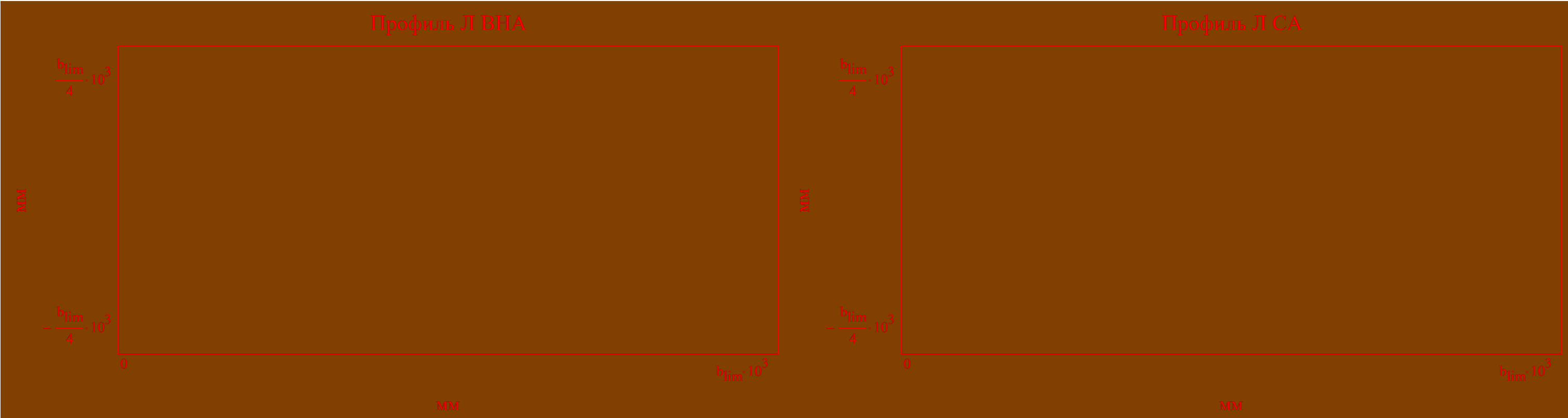
$r = 1$



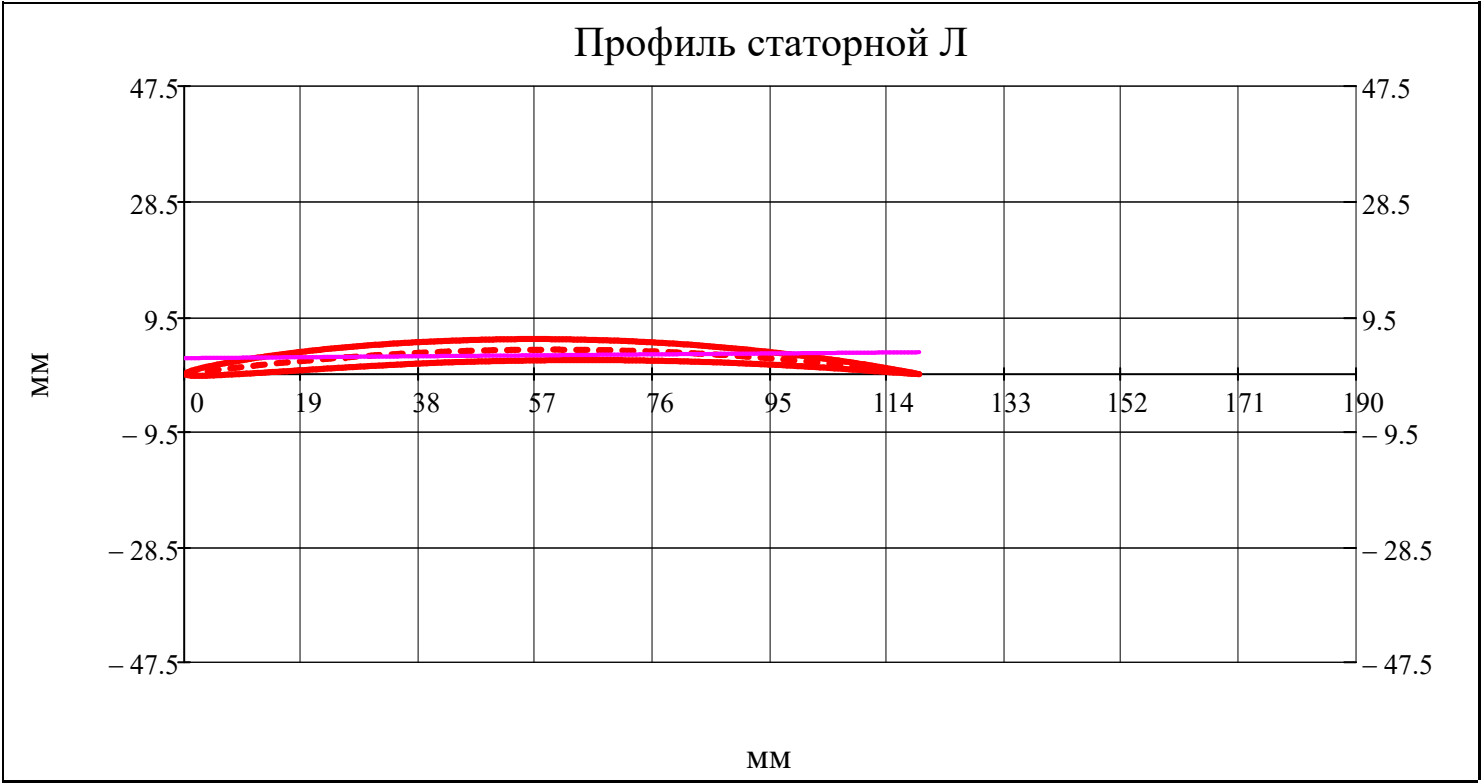
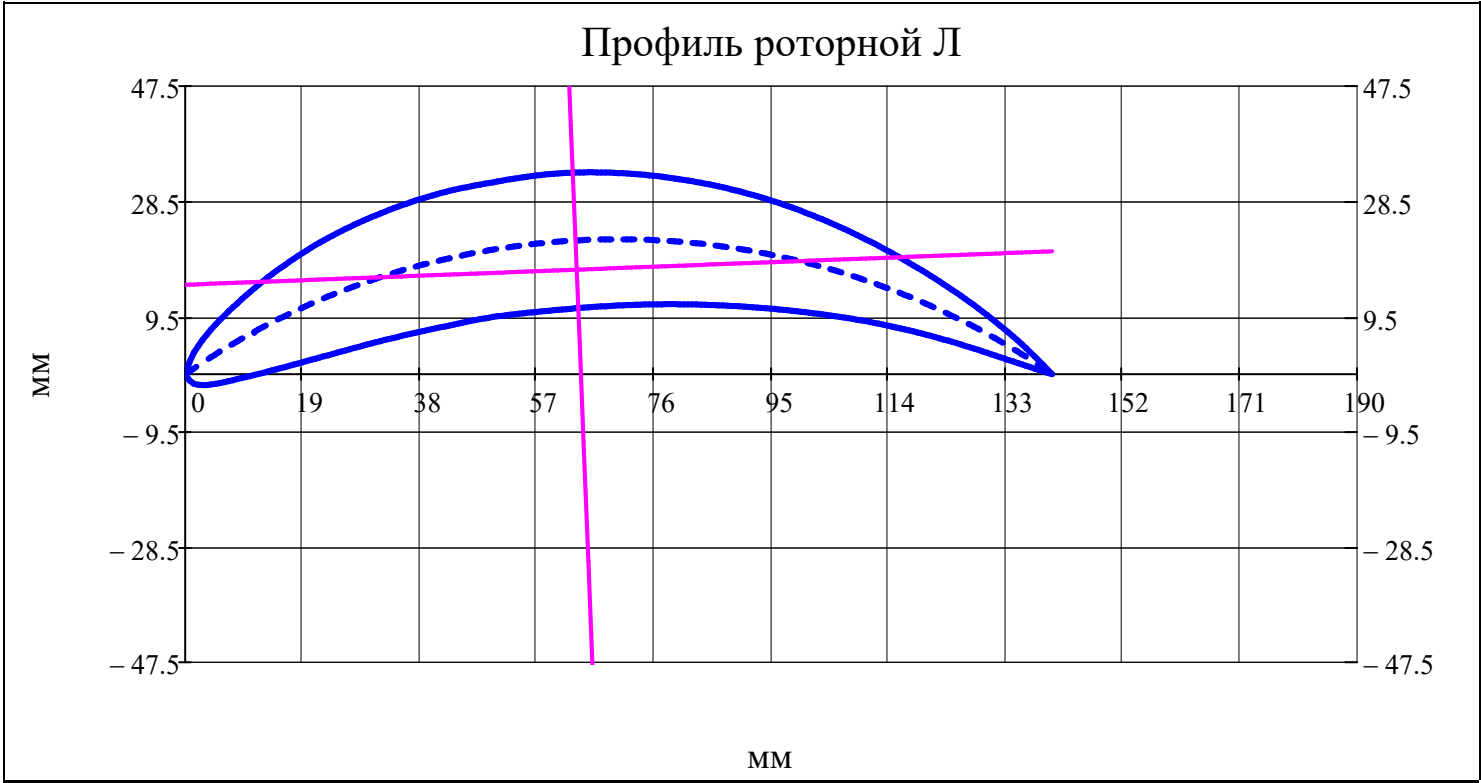
$$\underline{r} = \text{av}(\mathbf{N}_r)$$



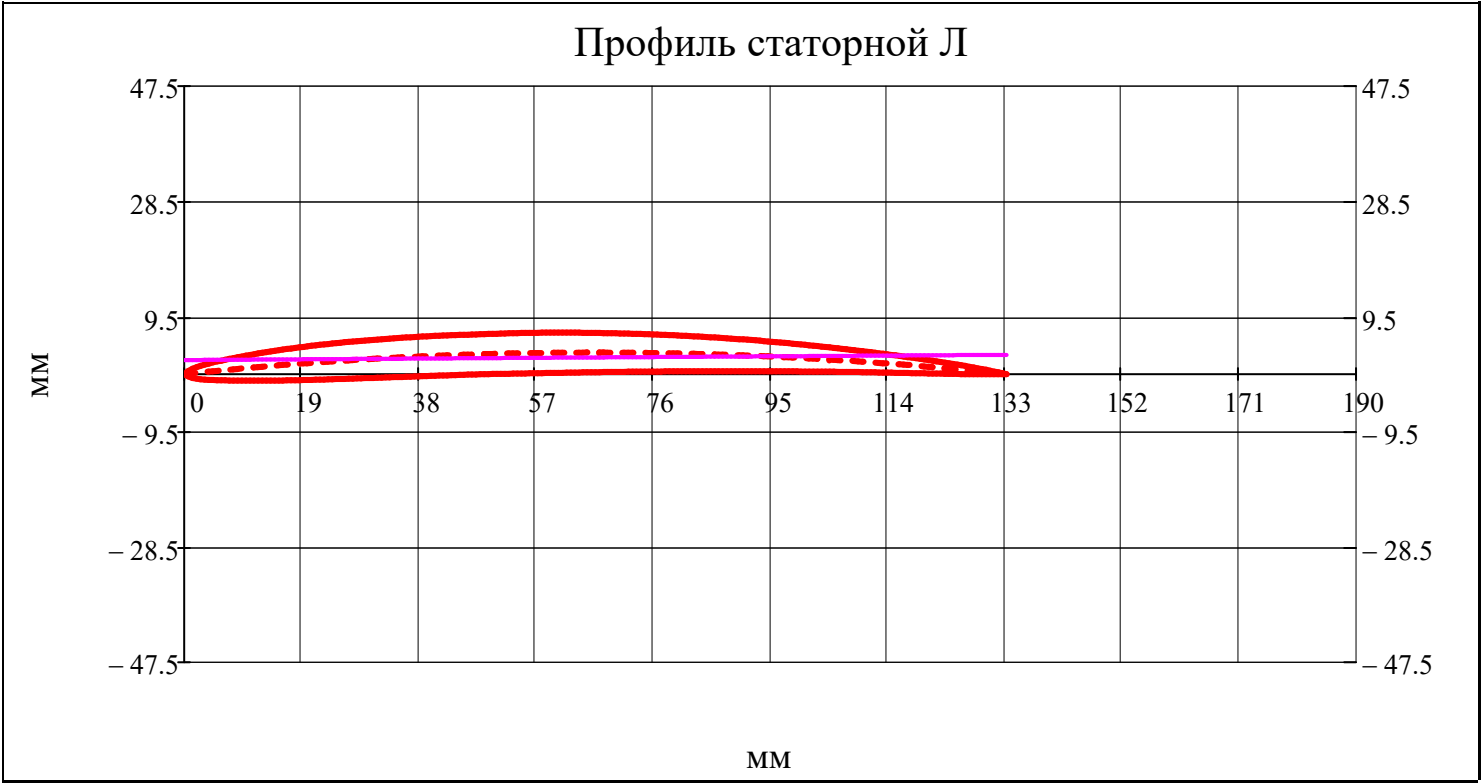
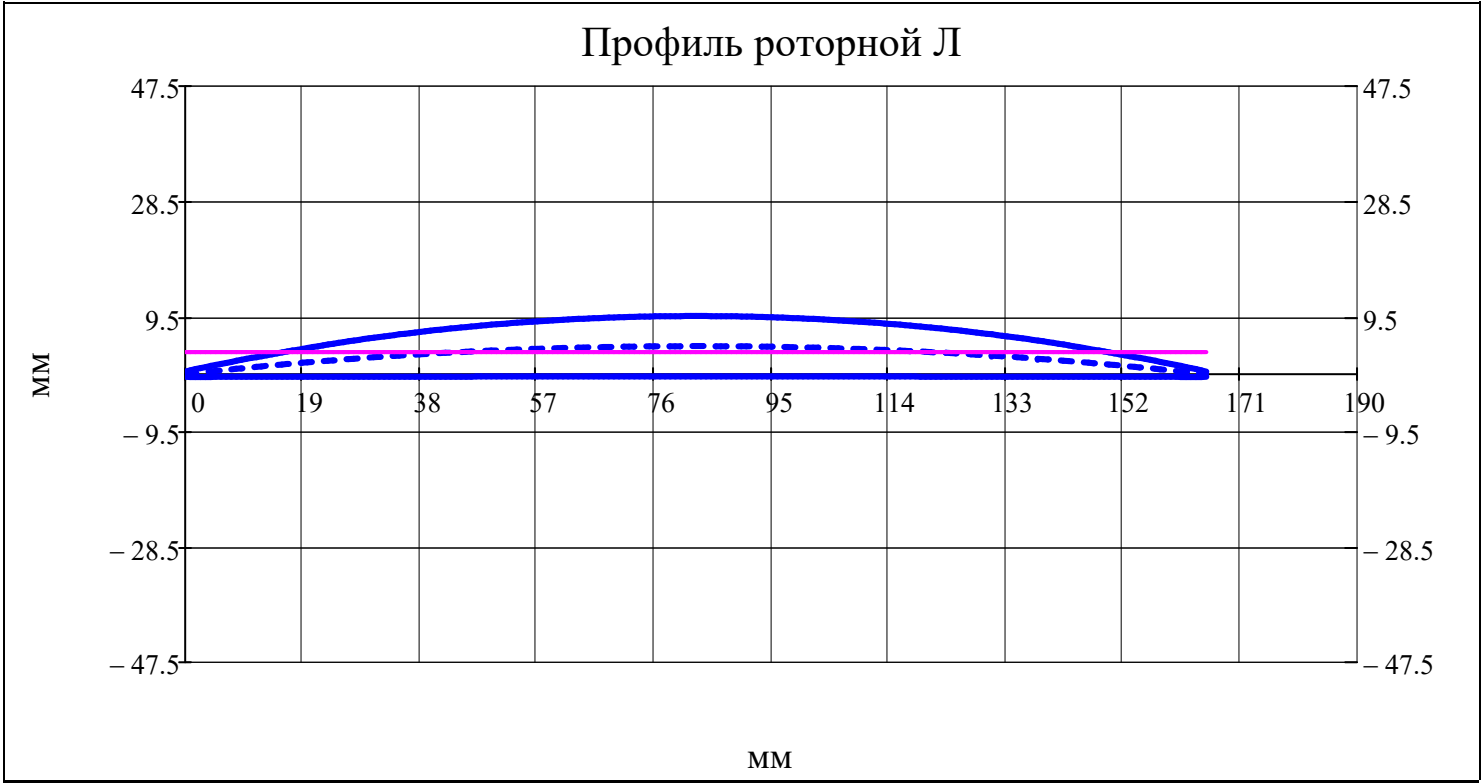
$r_w = N_r$



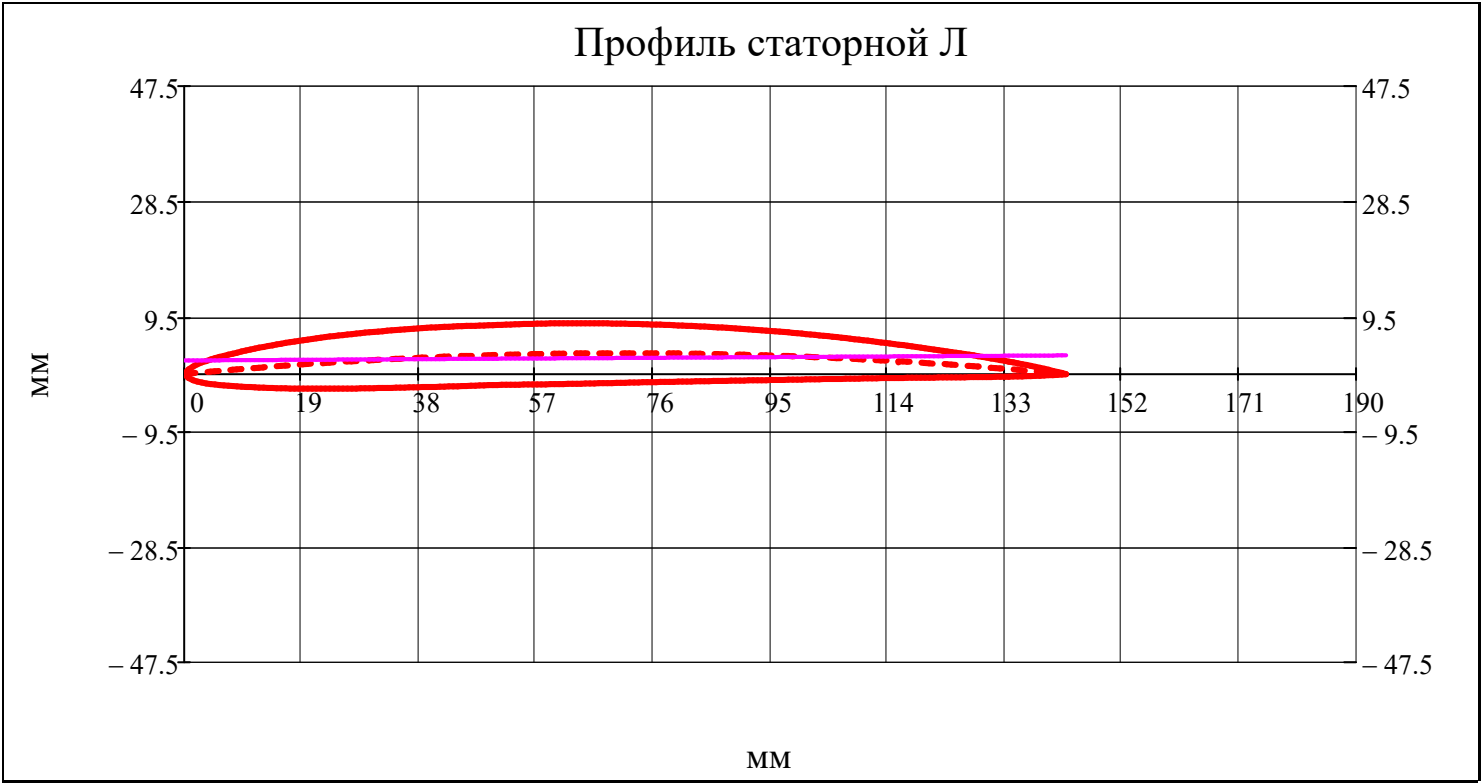
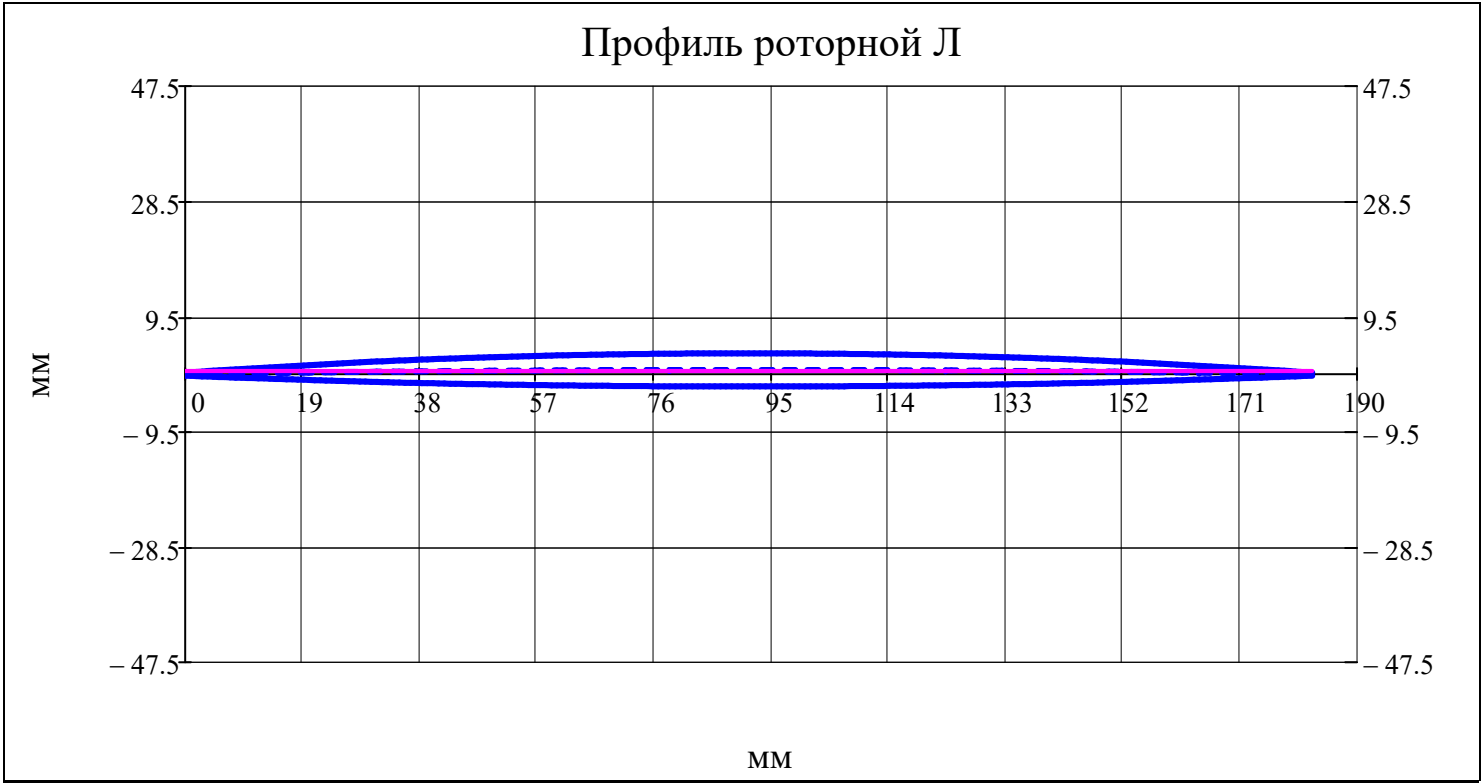
$r_w = 1$



$r_w = av(N_r)$



$r_w = N_r$



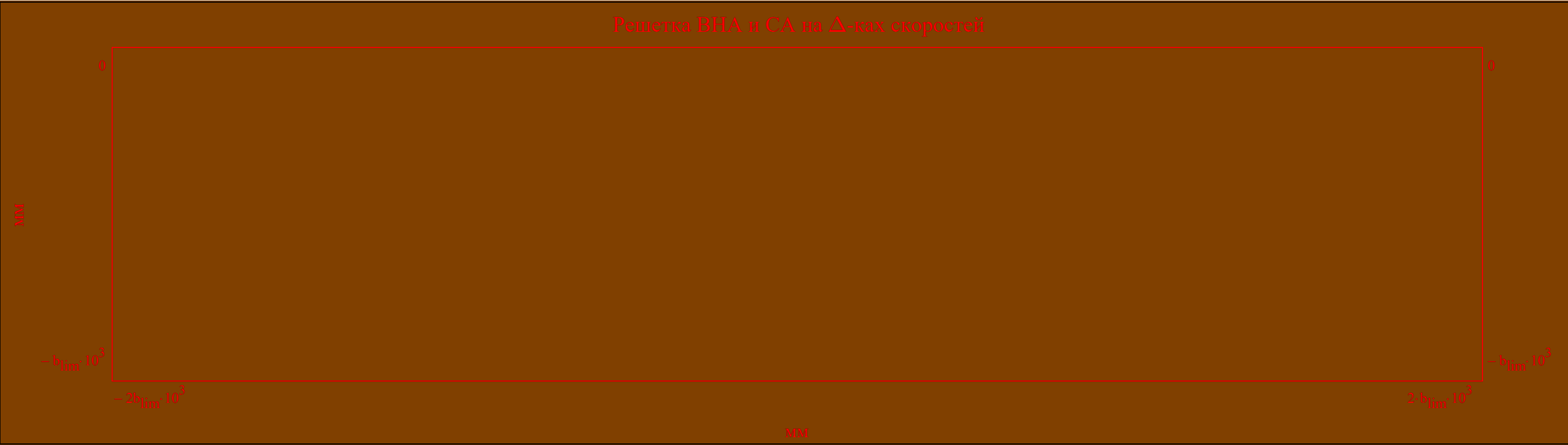
Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases} = 1$$

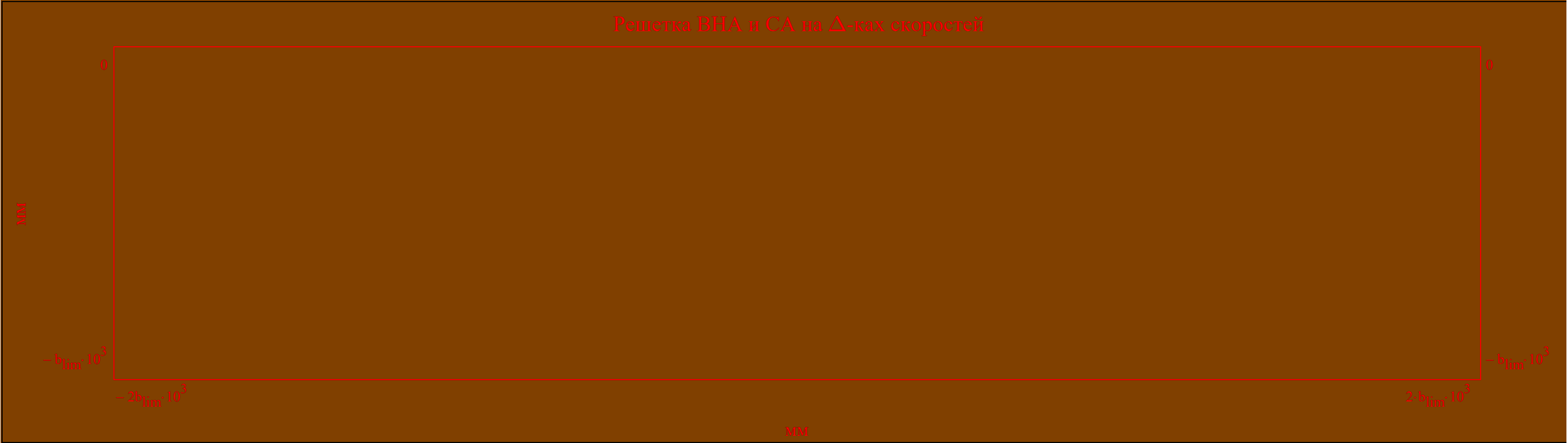
$$b_{lim} = \frac{ceil\left(\max\left(chord_{rotor_{j,N_r}}, chord_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 190 \cdot 10^{-3}$$

Построение плоских решеток профилей Л РК и НА (+ ВНА и СА) на треугольниках скоростей

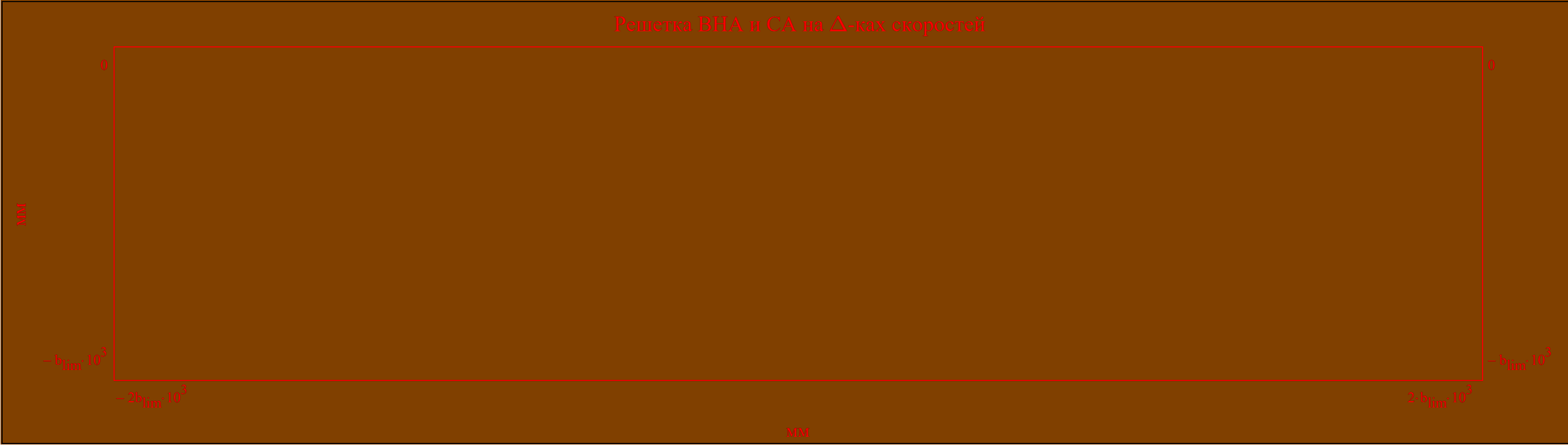
$$r_w = 1$$



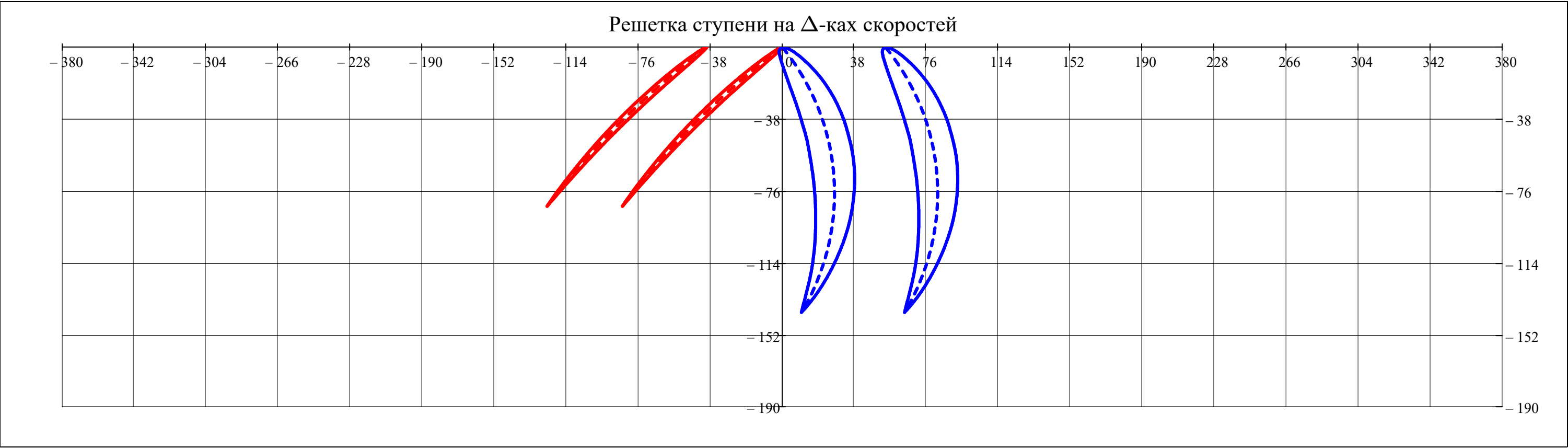
$$\tilde{r}_w = \text{av}\left(N_r\right)$$



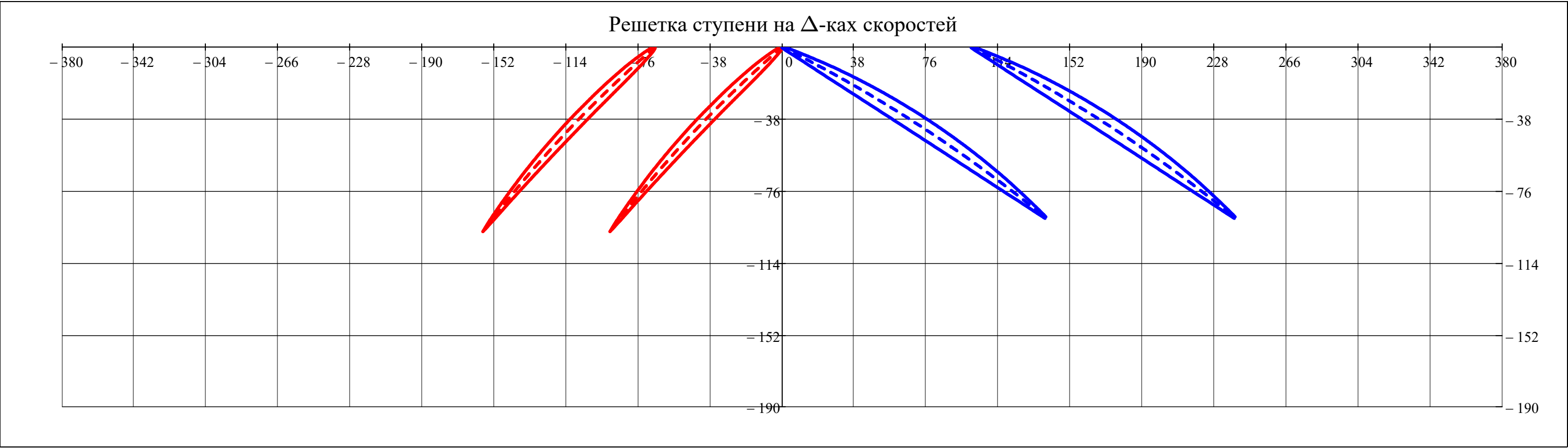
$\tilde{r}_w = N_r$



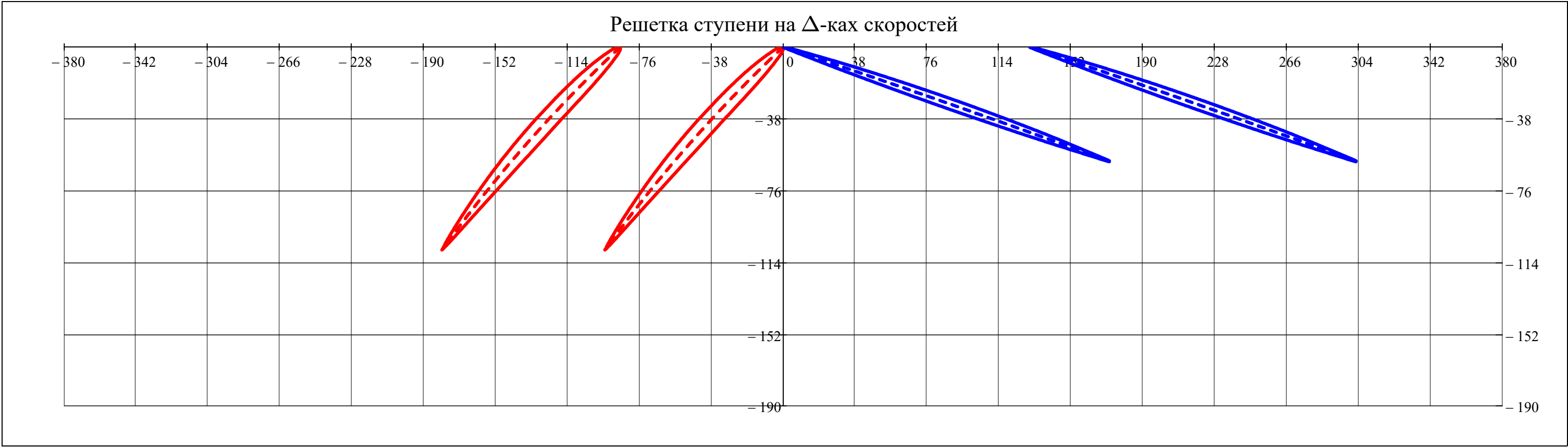
$r_w = 1$



$r_w = \text{av}(N_r)$



$r_w = N_r$



Радиальный зазор (м)
[с.64 казаджан]:

$\overline{\Delta}_r = 0.0025$

$0.0015 \leq \overline{\Delta}_r \leq 0.0035 = 1$

$\Delta_{r_i} = \overline{\Delta}_r \cdot D_{st(i, 2), N_r}$

$\Delta_r^T = \begin{bmatrix} & 1 \\ 1 & 3.84 \end{bmatrix} \cdot 10^{-3}$

Относительный осевой зазор () [16, с. 245]:

$\overline{\Delta}_a = 0.17$

$0.1 \leq \overline{\Delta}_a \leq 0.2 = 1$

Осевой зазор (м):
 $\Delta a_i = \overline{\Delta}_a \cdot chord_{rotor_{i, av}(N_r)}$

$\Delta a^T = \begin{bmatrix} & 1 \\ 1 & 28.14 \end{bmatrix} \cdot 10^{-3}$

Односторонний осевой зазор (м):

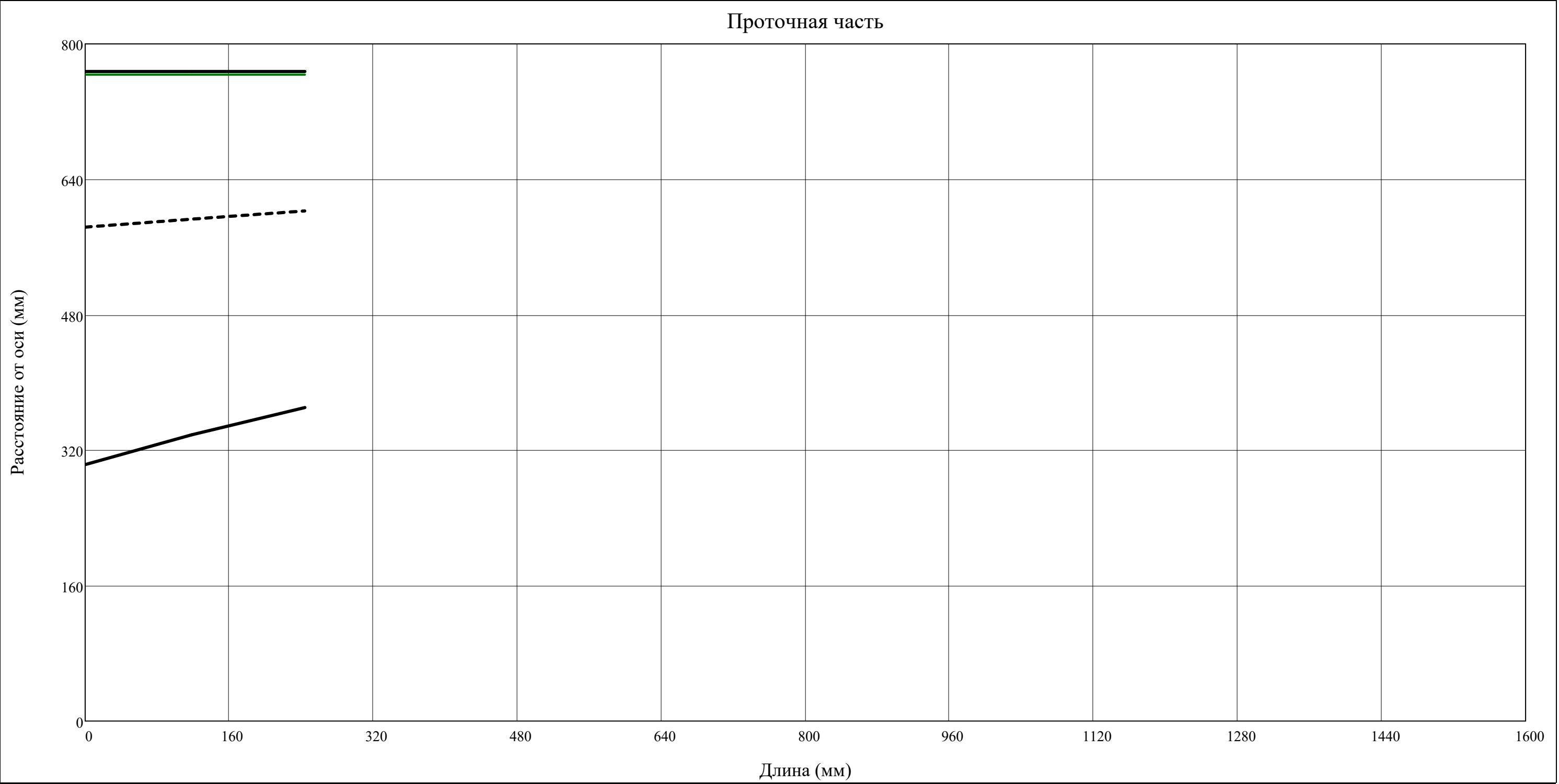
$\frac{\Delta a^T}{2} = \begin{bmatrix} & 1 \\ 1 & 14.07 \end{bmatrix} \cdot 10^{-3}$

Длина ОК (м):

$Length = \left[\begin{aligned} &\Delta a_1 + \begin{cases} chord_{BHA_{av}(N_r)} \cdot \sin\left(v_{BHA_{av}(N_r)}\right) & \text{if } BHA = 1 \quad \dots \\ 0 & \text{otherwise} \end{cases} \\ &+ \sum_{i=1}^Z \left(chord_{rotor_{i, av}(N_r)} \cdot \sin\left(v_{rotor_{i, av}(N_r)}\right) \right) + 2 \cdot \sum_{i=1}^Z \Delta a_i + \sum_{i=1}^Z \left(chord_{stator_{i, av}(N_r)} \cdot \sin\left(v_{stator_{i, av}(N_r)}\right) \right) \dots \\ &+ \begin{cases} chord_{CA_{av}(N_r)} \cdot \sin\left(v_{CA_{av}(N_r)}\right) & \text{if } CA = 1 \quad + \Delta a_Z \\ 0 & \text{otherwise} \end{cases} \end{aligned} \right] = 300.1 \cdot 10^{-3}$

$$\begin{pmatrix} x_{\text{ПЧ}} \\ y_{\text{ПЧпер}} \\ y_{\text{ПЧср}} \\ y_{\text{ПЧкор}} \\ y_{\text{Лпер}} \end{pmatrix} = \begin{cases} c = 1 \\ x_{\text{ПЧ}_c} = \begin{cases} \text{chord}_{\text{BHA}_{\text{av}}(N_r)} \cdot \sin(v_{\text{BHA}_{\text{av}}(N_r)}) & \text{if } \text{BHA} = 1 \\ 0 & \text{otherwise} \end{cases} \\ y_{\text{ПЧпер}_c} = R_{\text{st}(c, 1), N_r} \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta r_c \\ y_{\text{ПЧср}_c} = R_{\text{st}(c, 1), \text{av}(N_r)} \\ y_{\text{ПЧкор}_c} = R_{\text{st}(c, 1), \text{ORIGIN}} \\ \text{for } i \in 1..Z \\ \begin{cases} c = c + 1 \\ x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta a_i + \text{chord}_{\text{rotor}_i, \text{av}(N_r)} \cdot \sin(v_{\text{rotor}_i, \text{av}(N_r)}) + 0.5 \cdot \Delta a_i \\ \begin{pmatrix} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{pmatrix} = \begin{pmatrix} R_{\text{st}(i, 2), N_r} \\ R_{\text{st}(i, 2), \text{av}(N_r)} \\ R_{\text{st}(i, 2), \text{ORIGIN}} \end{pmatrix} \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta r_i \\ c = c + 1 \\ x_{\text{ПЧ}_c} = x_{\text{ПЧ}_{c-1}} + 0.5 \cdot \Delta a_i + \text{chord}_{\text{stator}_i, \text{av}(N_r)} \cdot \sin(v_{\text{stator}_i, \text{av}(N_r)}) + 0.5 \cdot \Delta a_i \\ \begin{pmatrix} y_{\text{ПЧпер}_c} \\ y_{\text{ПЧср}_c} \\ y_{\text{ПЧкор}_c} \end{pmatrix} = \begin{pmatrix} R_{\text{st}(i, 3), N_r} \\ R_{\text{st}(i, 3), \text{av}(N_r)} \\ R_{\text{st}(i, 3), \text{ORIGIN}} \end{pmatrix} \\ y_{\text{Лпер}_c} = y_{\text{ПЧпер}_c} - \Delta r_i \end{cases} \end{cases} \\ \begin{pmatrix} x_{\text{ПЧ}} & y_{\text{ПЧпер}} & y_{\text{ПЧср}} & y_{\text{ПЧкор}} & y_{\text{Лпер}} \end{pmatrix}^T
\end{cases}$$

$$\begin{aligned} y_{\text{ПЧпер}}(l) &= \text{interp}\left(\text{cspline}(x_{\text{ПЧ}}, y_{\text{ПЧпер}}), x_{\text{ПЧ}}, y_{\text{ПЧпер}}, l\right) \\ y_{\text{ПЧср}}(l) &= \text{interp}\left(\text{cspline}(x_{\text{ПЧ}}, y_{\text{ПЧср}}), x_{\text{ПЧ}}, y_{\text{ПЧср}}, l\right) \\ y_{\text{ПЧкор}}(l) &= \text{interp}\left(\text{cspline}(x_{\text{ПЧ}}, y_{\text{ПЧкор}}), x_{\text{ПЧ}}, y_{\text{ПЧкор}}, l\right) \\ y_{\text{Лпер}}(l) &= \text{interp}\left(\text{cspline}(x_{\text{ПЧ}}, y_{\text{Лпер}}), x_{\text{ПЧ}}, y_{\text{Лпер}}, l\right) \end{aligned}$$



Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & = 1 \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases}$$

⌵ Поперечная часть ступени

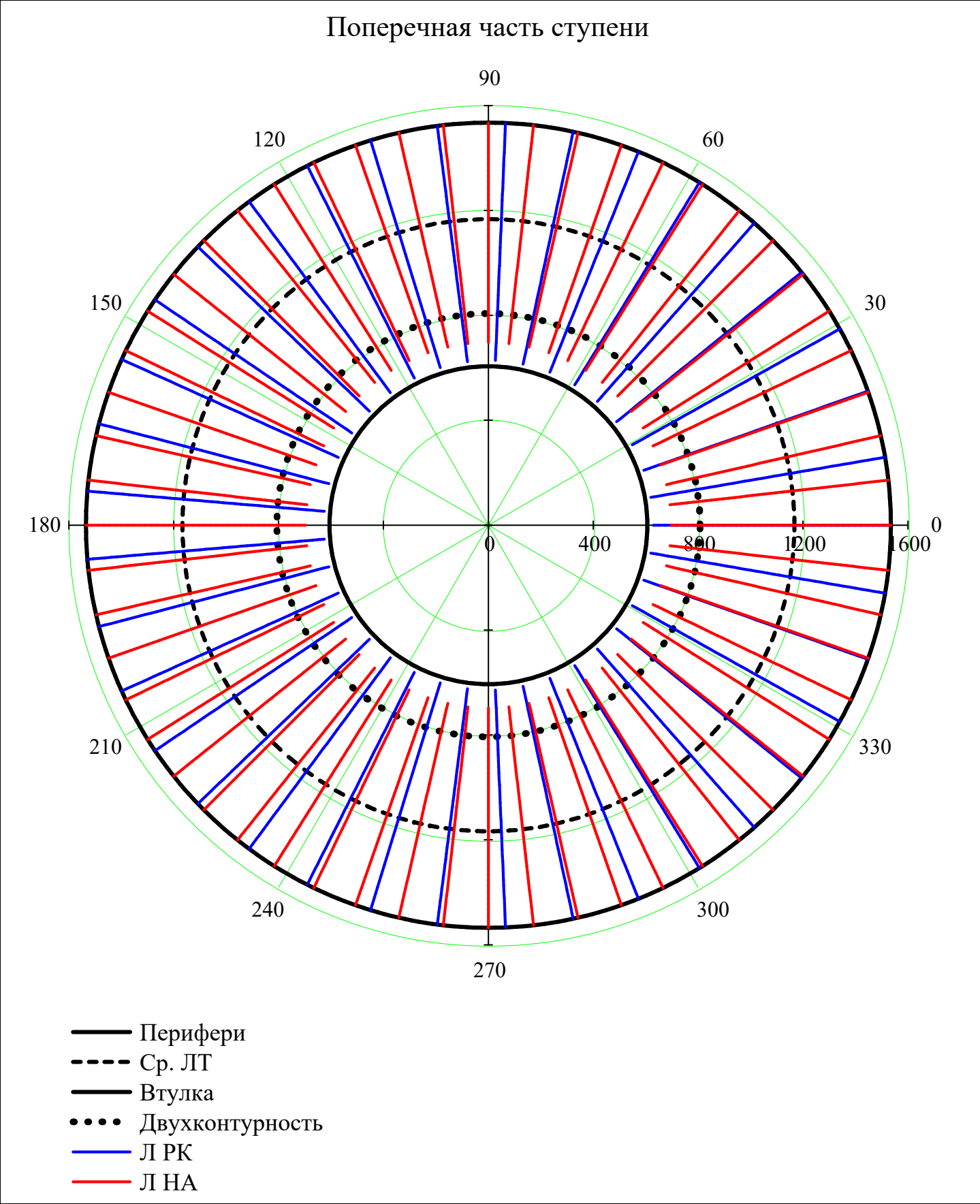
$$r_w = \min(D), \min(D) + \frac{\max(D) - \min(D)}{N_{\text{dis}}} \dots \max(D)$$

$$i_{\text{rotor}} = 1 \dots Z_{\text{rotor}_j}$$

$$i_{\text{stator}} = 1 \dots Z_{\text{stator}_j}$$

$$L_{\text{PK}}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{rotor}_j}} & \text{if } D_{\text{st}(j,1)}, 1 < r < D_{\text{st}(j,1)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$L_{\text{HA}}(r,j) = \begin{cases} \frac{2 \cdot \pi}{Z_{\text{stator}_j}} & \text{if } D_{\text{st}(j,2)}, 1 < r < D_{\text{st}(j,2)}, N_r \\ \text{NaN} & \text{otherwise} \end{cases}$$



Запас по температуре (K):

$\Delta T_{\text{safety}} = 50$

Выбранный материал Л:

$$\text{material_blade}_i = \begin{cases} \text{"ЖС-6K"} & \text{if } 1123 \leq T_{\text{st}(i, 2), \text{av}(N_r)}^* + \Delta T_{\text{safety}} \\ \text{"BT41"} & \text{if } 873 \leq T_{\text{st}(i, 2), \text{av}(N_r)}^* + \Delta T_{\text{safety}} < 1123 \\ \text{"BT25"} & \text{if } 753 \leq T_{\text{st}(i, 2), \text{av}(N_r)}^* + \Delta T_{\text{safety}} < 873 \\ \text{"BT9"} & \text{otherwise} \end{cases}$$

$$\text{material_blade}_i = \begin{cases} \text{"BT23"} & \text{if compressor = "Бл"} \\ \text{"BT6"} & \text{if compressor = "КНД"} \\ \text{material_blade}_i & \text{otherwise} \end{cases}$$

Плотность материала Л (кг/м^3):

$$\rho_{\text{blade}_i} = \begin{cases} 8393 & \text{if material_blade}_i = \text{"ЖС-6K"} \\ 7900 & \text{if material_blade}_i = \text{"BT41"} \\ 4500 & \text{if material_blade}_i = \text{"BT25"} \\ 4570 & \text{if material_blade}_i = \text{"BT23"} \\ 4510 & \text{if material_blade}_i = \text{"BT9"} \\ 4430 & \text{if material_blade}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

Коэф. формы:

$k_n = 6.8$

Модуль Юнга Грода материала Л (Па):

$E_{\text{blade}} = 210 \cdot 10^9$

Предел длительной прочности Л РК (Па):

$$\sigma_{\text{blade_long}_i} = 10^6 \cdot \begin{cases} 125 & \text{if material_blade}_i = \text{"ЖС-6K"} \\ 123 & \text{if material_blade}_i = \text{"BT41"} \\ 150 & \text{if material_blade}_i = \text{"BT25"} \\ 230 & \text{if material_blade}_i = \text{"BT23"} \\ 200 & \text{if material_blade}_i = \text{"BT9"} \\ 210 & \text{if material_blade}_i = \text{"BT6"} \\ \text{NaN} & \text{otherwise} \end{cases}$$

Коэф. Пуассона материала Л():

$\mu_{\text{steel}} = 0.3$

$\text{material_blade}^T =$

	1	2	3	4	5	6	7	8	9
1	"BT23"								

$\rho_{\text{blade}}^T =$

	1
1	4570

$\sigma_{\text{blade_long}}^T =$

	1
1	230.0

$\cdot 10^6$

$\nu_{0\text{изГ.stator}}$ $\nu_{0\text{изГ.rotor}}$

$\nu_{0\text{угЛ.stator}}$ $\nu_{0\text{угЛ.rotor}}$

$\nu_{0\text{угЛ.stator_bondage}}$ $\nu_{0\text{угЛ.rotor_bondage}}$

=

for i ∈ 1..Z

for r ∈ av(N_r)

for mode ∈ 1..6

$\nu_{0\text{изГ.stator}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}\Big(\text{mode}, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{stator}_{i,r}}, J_{\text{u}_{\text{stator}_{i,r}}}\Big)$

$\nu_{0\text{изГ.rotor}_{i,\text{mode}}} = \nu_{0\text{изГИБ}}\Big(\text{mode}, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), E_{\text{blade}}, \rho_{\text{blade}_i}, \text{area}_{\text{rotor}_{i,r}}, J_{\text{u}_{\text{rotor}_{i,r}}}\Big)$

$\nu_{0\text{угЛ.stator}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 0, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{\text{p}_{\text{stator}_{i,r}}}\Big)$

$\nu_{0\text{угЛ.rotor}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 0, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{\text{p}_{\text{rotor}_{i,r}}}\Big)$

$\nu_{0\text{угЛ.stator_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 1, \text{mean}\big(h_{\text{st}}(i, 2), h_{\text{st}}(i, 3)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{stator}_{i,r}}, J_{\text{p}_{\text{stator}_{i,r}}}\Big)$

$\nu_{0\text{угЛ.rotor_bondage}_{i,\text{mode}}} = \nu_{0\text{угЛ}}\Big(\text{mode}, 1, \text{mean}\big(h_{\text{st}}(i, 1), h_{\text{st}}(i, 2)\big), \text{Jung}(2, \mu_{\text{steel}}, E_{\text{blade}}), \rho_{\text{blade}_i}, \text{stiffness}_{\text{rotor}_{i,r}}, J_{\text{p}_{\text{rotor}_{i,r}}}\Big)$

$\nu_{0\text{изГ.stator}}$ $\nu_{0\text{изГ.rotor}}$

$\nu_{0\text{угЛ.stator}}$ $\nu_{0\text{угЛ.rotor}}$

$\nu_{0\text{угЛ.stator_bondage}}$ $\nu_{0\text{угЛ.rotor_bondage}}$

Частота собственных изгибных колебаний (Гц) [9, с.240]:

$$\text{stack}\left(\nu_{0_{\text{угл.stator}}}, \nu_{0_{\text{угл.rotor}}}\right)^T =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
1	262	290																
2	787	869																
3	1312	1449																
4	1836	2029																
5	2361	2608																
6	2885	3188																

Частота собственных угловых колебаний (Гц) [9, с.243] без и с бандажом:

$$\text{stack}\left(\nu_{0_{\text{изг.stator}}}, \nu_{0_{\text{изг.rotor}}}\right)^T =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
1	41	50																
2	257	311																
3	718	871																
4	1409	1708																
5	2328	2822																
6	3477	4214																

$$\text{stack}\left(\nu_{0_{\text{угл.stator_bondage}}}, \nu_{0_{\text{угл.rotor_bondage}}}\right)^T =$$

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
1	525	580																
2	1049	1159																
3	1574	1739																
4	2098	2318																
5	2623	2898																
6	3148	3478																

Расчетный узел: type = "compressor"

Объем бандажной полки (м³): V_бп = 0

Радиус положения ЦМ бандажной полки (м): R_бп = 0

Расчет Л на прочность

R0_rotor	area0_rotor	
N0_rotor	σ0_z_rotor	
area_rotor.	area_stator.	
N_rotor	σ_z_rotor	
P1	ρ1	
P2	ρ2	
P3	ρ3	
ca1	cu1	
ca2	cu2	
ca3	cu3	
qx_rotor	qx_stator	
qy_rotor	qy_stator	
Mx_rotor	Mx_stator	
My_rotor	My_stator	
shift_x_rotor	shift_y_rotor	
x0_rotor.	x0_stator.	=
y0_rotor.	y0_stator.	
α_major_rotor.	α_major_stator.	
Ju_rotor.	Ju_stator.	$\chi_{\text{rotor}}(i,z) = \frac{\text{area}_{\text{rotor}_i, N_r}}{\text{area}_{\text{rotor}_i, 1}}$
Jv_rotor.	Jv_stator.	
CPx_rotor.	CPx_stator.	
CPy_rotor.	CPy_stator.	$R0_{\text{rotor}}(i,z) = \frac{1}{\sqrt{1 - \ln(\chi_{\text{rotor}}(i,z))}} \cdot \begin{cases} \sqrt{\text{mean}(R_{\text{st}}(i,1), 1, R_{\text{st}}(i,2), 1)^2 - \text{mean}(R_{\text{st}}(i,1), N_r, R_{\text{st}}(i,2), N_r)^2 \cdot \ln(\chi_{\text{rotor}}(i,z))} & \text{if type = "compressor"} \\ \sqrt{\text{mean}(R_{\text{st}}(i,2), 1, R_{\text{st}}(i,3), 1)^2 - \text{mean}(R_{\text{st}}(i,2), N_r, R_{\text{st}}(i,3), N_r)^2 \cdot \ln(\chi_{\text{rotor}}(i,z))} & \text{if type = "turbine"} \end{cases}$
CPx_rotor.axis	CPx_stator.axis	
CPy_rotor.axis	CPy_stator.axis	
		$\sigma0_{\text{rotor.max}}(i,z) = \frac{\rho_{\text{blade}_i} \cdot \omega^2}{2} \cdot \begin{cases} \left[\text{mean}(R_{\text{st}}(i,1), N_r, R_{\text{st}}(i,2), N_r)^2 - (R0_{\text{rotor}}(i,z))^2 \right] & \text{if type = "compressor"} \\ \left[\text{mean}(R_{\text{st}}(i,2), N_r, R_{\text{st}}(i,3), N_r)^2 - (R0_{\text{rotor}}(i,z))^2 \right] & \text{if type = "turbine"} \end{cases}$
		$\left(\rho_{\text{blade}_i} \cdot \omega^2 \quad R0_{\text{rotor}}(i,z) \right)$

$$\begin{aligned}
c_{u2}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^1, \text{submatrix}\left(c_u, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^1\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^1, \text{submatrix}\left(c_u, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^1, z\right) \\
c_{u3}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, \text{submatrix}\left(c_u, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, \text{submatrix}\left(c_u, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, z\right) \\
w_{u1}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,1), \text{st}(i,1), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,1), \text{st}(i,1), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,1), \text{st}(i,1), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,1), \text{st}(i,1), 1, N_r\right)^T, z\right) \\
w_{u2}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, z\right) \\
w_{u3}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, \text{submatrix}\left(w_u, \text{st}(i,3), \text{st}(i,3), 1, N_r\right)^T, z\right) \\
q_{x_{\text{rotor}}}(i,z) &= -\frac{2\pi z}{Z_{\text{rotor}_i}} \cdot \begin{cases} \left[\left(P_2(i,z) - P_1(i,z) \right) + \rho_1(i,z) \cdot c_{a1}(i,z) \cdot \left(c_{a2}(i,z) - c_{a1}(i,z) \right) \right] & \text{if type = "compressor"} \\ \left[\left(P_3(i,z) - P_2(i,z) \right) + \rho_2(i,z) \cdot c_{a2}(i,z) \cdot \left(c_{a3}(i,z) - c_{a2}(i,z) \right) \right] & \text{if type = "turbine"} \end{cases} \\
q_{x_{\text{stator}}}(i,z) &= -\frac{2\pi z}{Z_{\text{stator}_i}} \cdot \begin{cases} \left[\left(P_3(i,z) - P_2(i,z) \right) + \rho_2(i,z) \cdot c_{a2}(i,z) \cdot \left(c_{a3}(i,z) - c_{a2}(i,z) \right) \right] & \text{if type = "compressor"} \\ \left[\left(P_2(i,z) - P_1(i,z) \right) + \rho_1(i,z) \cdot c_{a1}(i,z) \cdot \left(c_{a2}(i,z) - c_{a1}(i,z) \right) \right] & \text{if type = "turbine"} \end{cases} \\
q_{y_{\text{rotor}}}(i,z) &= \frac{2\pi z}{Z_{\text{rotor}_i}} \cdot \begin{cases} \left[\rho_1(i,z) \cdot c_{a1}(i,z) \cdot \left(w_{u2}(i,z) - w_{u1}(i,z) \right) \right] & \text{if type = "compressor"} \\ \left[\rho_2(i,z) \cdot c_{a2}(i,z) \cdot \left(w_{u3}(i,z) - w_{u2}(i,z) \right) \right] & \text{if type = "turbine"} \end{cases} \\
q_{y_{\text{stator}}}(i,z) &= -\frac{2\pi z}{Z_{\text{stator}_i}} \cdot \begin{cases} \left[\rho_2(i,z) \cdot c_{a2}(i,z) \cdot \left(c_{u3}(i,z) - c_{u2}(i,z) \right) \right] & \text{if type = "compressor"} \\ \left[\rho_1(i,z) \cdot c_{a1}(i,z) \cdot \left(c_{u2}(i,z) - c_{u1}(i,z) \right) \right] & \text{if type = "turbine"} \end{cases} \\
M_{x_{\text{rotor}}}(i,z) &= -\int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,1), N_r}, R_{\text{st}(i,2), N_r}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,2), N_r}, R_{\text{st}(i,3), N_r}\right) & \text{if type="turbine"} \end{cases} q_{y_{\text{rotor}}}(i,z1) \cdot (z1 - z) dz1 \\
M_{x_{\text{stator}}}(i,z) &= \int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,2), 1}, R_{\text{st}(i,3), 1}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,1), 1}, R_{\text{st}(i,2), 1}\right) & \text{if type="turbine"} \end{cases} q_{y_{\text{stator}}}(i,z1) \cdot (z1 - z) dz1 \\
M_{y_{\text{rotor}}}(i,z) &= \int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,1), N_r}, R_{\text{st}(i,2), N_r}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,2), N_r}, R_{\text{st}(i,3), N_r}\right) & \text{if type="turbine"} \end{cases} q_{x_{\text{rotor}}}(i,z1) \cdot (z1 - z) dz1 \\
M_{y_{\text{stator}}}(i,z) &= -\int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,2), 1}, R_{\text{st}(i,3), 1}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,1), 1}, R_{\text{st}(i,2), 1}\right) & \text{if type="turbine"} \end{cases} q_{x_{\text{stator}}}(i,z1) \cdot (z1 - z) dz1 \\
\int_z^z & \begin{cases} \text{mean}\left(R_{\text{st}(i,1), N_r}, R_{\text{st}(i,2), N_r}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,2), N_r}, R_{\text{st}(i,3), N_r}\right) & \text{if type="turbine"} \end{cases} q_{x_{\text{stator}}}(i,z) dz
\end{aligned}$$

$$\begin{aligned} \text{shift_x}_{\text{rotor}}(i,z) &= \int_z^z \frac{\left[\begin{array}{l} \text{mean}(R_{st(i,1),1}, R_{st(i,2),1}) \quad \text{if type="compressor"} \\ \text{mean}(R_{st(i,2),1}, R_{st(i,3),1}) \quad \text{if type="turbine"} \end{array} \right]}{N_{\text{rotor}}(i,z)} dz \\ \text{shift_y}_{\text{rotor}}(i,z) &= z \cdot \int_z^z \frac{\left[\begin{array}{l} \text{mean}(R_{st(i,1),N_r}, R_{st(i,2),N_r}) \quad \text{if type="compressor"} \\ \text{mean}(R_{st(i,2),N_r}, R_{st(i,3),N_r}) \quad \text{if type="turbine"} \end{array} \right] \cdot qY_{\text{rotor}}(i,z) \cdot z}{N_{\text{rotor}}(i,z) \cdot z^2} dz \\ x0_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(x0_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(x0_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ x0_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(x0_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(x0_{\text{stator}}, i, i, 1, N_r)^T\right) \\ y0_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(y0_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(y0_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ y0_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(y0_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(y0_{\text{stator}}, i, i, 1, N_r)^T\right) \\ \alpha_{\text{major}_{\text{rotor}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(\alpha_{\text{major}_{\text{rotor}}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(\alpha_{\text{major}_{\text{rotor}}}, i, i, 1, N_r)^T\right) \\ \alpha_{\text{major}_{\text{stator}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(\alpha_{\text{major}_{\text{stator}}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(\alpha_{\text{major}_{\text{stator}}}, i, i, 1, N_r)^T\right) \\ Ju_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Ju_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Ju_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ Ju_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Ju_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Ju_{\text{stator}}, i, i, 1, N_r)^T\right) \\ Jv_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Jv_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Jv_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ Jv_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Jv_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(Jv_{\text{stator}}, i, i, 1, N_r)^T\right) \\ CPx_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPx_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPx_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ CPx_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPx_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPx_{\text{stator}}, i, i, 1, N_r)^T\right) \\ CPy_{\text{rotor}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPy_{\text{rotor}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPy_{\text{rotor}}, i, i, 1, N_r)^T\right) \\ CPy_{\text{stator}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPy_{\text{stator}}, i, i, 1, N_r)^T\right), \text{submatrix}(R, st(i,2), st(i,2), 1, N_r)^T, \text{submatrix}(CPy_{\text{stator}}, i, i, 1, N_r)^T\right) \\ CPx_{\text{rotor.axis}}(i,z) &= \text{axis}_x(CPx_{\text{rotor}}(i,z), CPy_{\text{rotor}}(i,z), x0_{\text{rotor}}(i,z), y0_{\text{rotor}}(i,z), \alpha_{\text{major}_{\text{rotor}}}(i,z), 1) \\ CPx_{\text{stator.axis}}(i,z) &= \text{axis}_x(CPx_{\text{stator}}(i,z), CPy_{\text{stator}}(i,z), x0_{\text{stator}}(i,z), y0_{\text{stator}}(i,z), \alpha_{\text{major}_{\text{stator}}}(i,z), 1) \\ CPy_{\text{rotor.axis}}(i,z) &= \text{axis}_y(CPx_{\text{rotor}}(i,z), CPy_{\text{rotor}}(i,z), x0_{\text{rotor}}(i,z), y0_{\text{rotor}}(i,z), \alpha_{\text{major}_{\text{rotor}}}(i,z), 1) \\ CPy_{\text{stator.axis}}(i,z) &= \text{axis}_y(CPx_{\text{stator}}(i,z), CPy_{\text{stator}}(i,z), x0_{\text{stator}}(i,z), y0_{\text{stator}}(i,z), \alpha_{\text{major}_{\text{stator}}}(i,z), 1) \end{aligned}$$

$$\begin{aligned}
W_{p_{\text{rotor.}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(W_{p_{\text{rotor.}}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(W_{p_{\text{rotor.}}}, i, i, 1, N_r\right)^T, z\right) \\
W_{p_{\text{stator.}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(W_{p_{\text{stator.}}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(W_{p_{\text{stator.}}}, i, i, 1, N_r\right)^T, z\right) \\
M\tau_{\text{rotor}}(i,z) &= \int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,1), N_r}, R_{\text{st}(i,2), N_r}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,2), N_r}, R_{\text{st}(i,3), N_r}\right) & \text{if type="turbine"} \end{cases} \left(q_{x_{\text{rotor}}}(i,z1) \cdot CP_{y_{\text{rotor.axis}}}(i,z1) - q_{y_{\text{rotor}}}(i,z1) \cdot CP_{x_{\text{rotor.axis}}}(i,z1)\right) dz1 \\
M\tau_{\text{stator}}(i,z) &= \int_z \begin{cases} \text{mean}\left(R_{\text{st}(i,2), 1}, R_{\text{st}(i,3), 1}\right) & \text{if type="compressor"} \\ \text{mean}\left(R_{\text{st}(i,1), 1}, R_{\text{st}(i,2), 1}\right) & \text{if type="turbine"} \end{cases} \left(q_{x_{\text{stator}}}(i,z1) \cdot CP_{y_{\text{stator.axis}}}(i,z1) - q_{y_{\text{stator}}}(i,z1) \cdot CP_{x_{\text{stator.axis}}}(i,z1)\right) dz1 \\
\tau_{\text{rotor}}(i,z) &= \frac{M\tau_{\text{rotor}}(i,z)}{W_{p_{\text{rotor.}}}(i,z)} \\
\tau_{\text{stator}}(i,z) &= \frac{M\tau_{\text{stator}}(i,z)}{W_{p_{\text{stator.}}}(i,z)} \\
\varphi_{uv_{\text{rotor}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(\frac{\pi}{2} - v_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(\frac{\pi}{2} - v_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\
\varphi_{uv_{\text{stator}}}(i,z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(\frac{\pi}{2} - v_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i,2), \text{st}(i,2), 1, N_r\right)^T, \text{submatrix}\left(\frac{\pi}{2} - v_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \\
Mu_{\text{rotor}}(i,z) &= \text{axis}_x\left(Mx_{\text{rotor}}(i,z), My_{\text{rotor}}(i,z), 0, 0, \varphi_{uv_{\text{rotor}}}(i,z), 1\right) \\
Mu_{\text{stator}}(i,z) &= \text{axis}_x\left(Mx_{\text{stator}}(i,z), My_{\text{stator}}(i,z), 0, 0, \varphi_{uv_{\text{stator}}}(i,z), 1\right) \\
Mv_{\text{rotor}}(i,z) &= \text{axis}_y\left(Mx_{\text{rotor}}(i,z), My_{\text{rotor}}(i,z), 0, 0, \varphi_{uv_{\text{rotor}}}(i,z), 1\right) \\
Mv_{\text{stator}}(i,z) &= \text{axis}_y\left(Mx_{\text{stator}}(i,z), My_{\text{stator}}(i,z), 0, 0, \varphi_{uv_{\text{stator}}}(i,z), 1\right) \\
\varphi_{\text{neutral}_{\text{rotor}}}(i,z) &= \begin{cases} \text{atan}\left(\frac{Mv_{\text{rotor}}(i,z) \cdot Ju_{\text{rotor.}}(i,z)}{Mu_{\text{rotor}}(i,z) \cdot Jv_{\text{rotor.}}(i,z)}\right) & \text{if } Mu_{\text{rotor}}(i,z) \cdot Jv_{\text{rotor.}}(i,z) \neq 0 \\ \frac{\pi}{2} & \text{otherwise} \end{cases} \\
\varphi_{\text{neutral}_{\text{stator}}}(i,z) &= \begin{cases} \text{atan}\left(\frac{Mv_{\text{stator}}(i,z) \cdot Ju_{\text{stator.}}(i,z)}{Mu_{\text{stator}}(i,z) \cdot Jv_{\text{stator.}}(i,z)}\right) & \text{if } Mu_{\text{stator}}(i,z) \cdot Jv_{\text{stator.}}(i,z) \neq 0 \\ \frac{\pi}{2} & \text{otherwise} \end{cases} \\
\left(\begin{array}{cc} R0_{\text{rotor}} & \text{area}0_{\text{rotor}} \\ N0_{\text{rotor}} & \sigma0_z_{\text{rotor}} \\ \text{area}_{\text{rotor.}} & \text{area}_{\text{stator.}} \\ N_{\text{rotor}} & \sigma_Z_{\text{rotor}} \end{array} \right)
\end{aligned}$$

	P_1	ρ_1
	P_2	ρ_2
	P_3	ρ_3
	c_{a1}	c_{u1}
	c_{a2}	c_{u2}
	c_{a3}	c_{u3}
	$q_{x_{rotor}}$	$q_{x_{stator}}$
	$q_{y_{rotor}}$	$q_{y_{stator}}$
	$M_{x_{rotor}}$	$M_{x_{stator}}$
	$M_{y_{rotor}}$	$M_{y_{stator}}$
	$shift_x_{rotor}$	$shift_y_{rotor}$
	$x0_{rotor.}$	$x0_{stator.}$
	$y0_{rotor.}$	$y0_{stator.}$
	$\alpha_major_{rotor.}$	$\alpha_major_{stator.}$
	$J_u_{rotor.}$	$J_u_{stator.}$
	$J_v_{rotor.}$	$J_v_{stator.}$
	$CP_{x_{rotor.}}$	$CP_{x_{stator.}}$
	$CP_{y_{rotor.}}$	$CP_{y_{stator.}}$
	$CP_{x_{rotor.axis}}$	$CP_{x_{stator.axis}}$
	$CP_{y_{rotor.axis}}$	$CP_{y_{stator.axis}}$
	$W_{p_{rotor.}}$	$W_{p_{stator.}}$
	$M\tau_{rotor}$	$M\tau_{stator}$
	τ_{rotor}	τ_{stator}
	$\varphi_{uv_{rotor}}$	$\varphi_{uv_{stator}}$
	M_u_{rotor}	M_u_{stator}
	M_v_{rotor}	M_v_{stator}
	$\varphi_neutral_{rotor}$	$\varphi_neutral_{stator}$

$$\text{neutral_line}(\text{type},\text{x},\text{i},\text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{rotor}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right)\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}}\right) \quad \text{if type = "rotor"} \\ \\ \frac{y0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}} + \tan\left(\left(\alpha_{\text{major}_{\text{stator}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right)\right)\right) \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}}\right) \quad \text{if type = "stator"} \end{array} \right.$$

$$\text{epure}(\text{type},\text{x},\text{i},\text{r}) = \left\{ \begin{array}{l} \frac{y0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{rotor}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{rotor}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right) - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{rotor}_{\text{i},\text{r}}}}{\text{chord}_{\text{rotor}_{\text{i},\text{r}}}}\right) \quad \text{if type = "rotor"} \\ \\ \frac{y0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}} + \frac{-1}{\tan\left(\alpha_{\text{major}_{\text{stator}_{\text{i},\text{r}}}} + \varphi_{\text{neutral}_{\text{stator}}}\left(\text{i},\text{Rst}(\text{i},2),\text{r}\right) - \frac{\pi}{4}\right)} \cdot \left(\text{x} - \frac{x0_{\text{stator}_{\text{i},\text{r}}}}{\text{chord}_{\text{stator}_{\text{i},\text{r}}}}\right) \quad \text{if type = "stator"} \end{array} \right.$$

Наиболее удаленные точки от НЛ (мм):

$u_{u_{\text{rotor}}}^T =$

	1	2	3	4	5	6	7	8	9
1	7.216								
2	-3.269								
3	-0.307								

$\cdot 10^{-3}$

$v_{u_{\text{rotor}}}^T =$

	1
1	16.326
2	5.980
3	91.332

$\cdot 10^{-3}$

$u_{l_{\text{rotor}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-59.370								
2	82.737								
3	-0.800								

$\cdot 10^{-3}$

$v_{l_{\text{rotor}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-22.714								
2	-4.647								
3	-91.332								

$\cdot 10$

$u_{u_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-0.171								
2	-1.522								
3	-3.055								

$\cdot 10^{-3}$

$v_{u_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	2.698								
2	4.132								
3	5.778								

$\cdot 10^{-3}$

$u_{l_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	65.310								
2	-46.896								
3	-40.299								

$\cdot 10^{-3}$

$v_{l_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-3.631								
2	-3.463								
3	-4.764								

$\cdot 10^{-3}$

$$\begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \begin{pmatrix} \sigma_{\text{p_rotor}_{i,r}} & \sigma_{\text{n_rotor}_{i,r}} \\ \sigma_{\text{p_stator}_{i,r}} & \sigma_{\text{n_stator}_{i,r}} \end{pmatrix} = \begin{pmatrix} \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_u}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_u}_{\text{rotor}_{i,r}} & \frac{\text{Mu}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{rotor}_{i,r}}} \cdot \text{v_l}_{\text{rotor}_{i,r}} - \frac{\text{Mv}_{\text{rotor}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{rotor}_{i,r}}} \cdot \text{u_l}_{\text{rotor}_{i,r}} \\ \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_u}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_u}_{\text{stator}_{i,r}} & \frac{\text{Mu}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Ju}_{\text{stator}_{i,r}}} \cdot \text{v_l}_{\text{stator}_{i,r}} - \frac{\text{Mv}_{\text{stator}}(i, \text{Rst}(i, 2), r)}{\text{Jv}_{\text{stator}_{i,r}}} \cdot \text{u_l}_{\text{stator}_{i,r}} \end{pmatrix} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor}} & \sigma_{\text{n_rotor}} \\ \sigma_{\text{p_stator}} & \sigma_{\text{n_stator}} \end{pmatrix} \end{array}$$

$$\begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} = \begin{array}{l} \text{for } i \in 1..Z \\ \begin{array}{l} \sigma_{\text{p_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{p_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{p_stator}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_rotor.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{n_stator.}}(i, z) = \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(\text{R}, \text{st}(i, 1), \text{st}(i, 1), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{n_stator}}, i, i, 1, N_r\right)^T, z\right) \end{array} \end{array} \\ \begin{pmatrix} \sigma_{\text{p_rotor.}} & \sigma_{\text{p_stator.}} \\ \sigma_{\text{n_rotor.}} & \sigma_{\text{n_stator.}} \end{pmatrix} \end{array}$$

$\sigma_{\text{p}_{\text{rotor}}}^T =$

	1	2	3	4	5	6	7	8	9
1	26.78								
2	-37.79								
3	0.00								

 $\cdot 10^6$

$\sigma_{\text{p}_{\text{rotor}}}^T \leq 70 \cdot 10^6 =$

	1
1	1
2	1
3	1

$\sigma_{\text{n}_{\text{rotor}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-45.07								
2	32.94								
3	0.00								

 $\cdot 10^6$

$\sigma_{\text{n}_{\text{rotor}}}^T \leq 70 \cdot 10^6 =$

	1
1	1
2	1
3	1

$\sigma_{\text{p}_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	1.31								
2	92.34								
3	106.71								

 $\cdot 10^6$

$\sigma_{\text{p}_{\text{stator}}}^T \leq 70 \cdot 10^6 =$

	1
1	1
2	0
3	0

$\sigma_{\text{n}_{\text{stator}}}^T =$

	1	2	3	4	5	6	7	8	9
1	-1.77								
2	-77.00								
3	-87.42								

 $\cdot 10^6$

$\sigma_{\text{n}_{\text{stator}}}^T \leq 70 \cdot 10^6 =$

	1
1	1
2	1
3	1

$$\begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \text{for } r \in 1..N_r \\ \left| \begin{aligned} \sigma_{\text{rotor}_{i,r}} &= \sqrt{\left(\sigma_{-Z_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)} + \max\left(\sigma_{-p_{\text{rotor}_{i,r}}}, \sigma_{-n_{\text{rotor}_{i,r}}}\right)\right)^2 + \tau_{\text{rotor}}(i, R_{\text{st}}(i, 2), r)^2} \\ \sigma_{\text{stator}_{i,r}} &= \sqrt{\left(0 + \max\left(\sigma_{-p_{\text{stator}_{i,r}}}, \sigma_{-n_{\text{stator}_{i,r}}}\right)\right)^2 + \tau_{\text{stator}}(i, R_{\text{st}}(i, 2), r)^2} \end{aligned} \right. \\ \begin{pmatrix} \sigma_{\text{rotor}} \\ \sigma_{\text{stator}} \end{pmatrix} \end{cases}$$

$$\begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} = \begin{cases} \text{for } i \in 1..Z \\ \left| \begin{aligned} \sigma_{\text{rotor.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{rotor}}, i, i, 1, N_r\right)^T, z\right) \\ \sigma_{\text{stator.}}(i, z) &= \text{interp}\left(\text{lspline}\left(\text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T\right), \text{submatrix}\left(R, \text{st}(i, 2), \text{st}(i, 2), 1, N_r\right)^T, \text{submatrix}\left(\sigma_{\text{stator}}, i, i, 1, N_r\right)^T, z\right) \end{aligned} \right. \\ \begin{pmatrix} \sigma_{\text{rotor.}} \\ \sigma_{\text{stator.}} \end{pmatrix} \end{cases}$$

$\sigma_{\text{rotor}}^T =$		1	2	3	4	5	6	7	8	9
	1	209.18								
	2	162.56								
	3	0.00								

$\cdot 10^6$

$\sigma_{\text{stator}}^T =$

	1	2	3	4	5	6	7	8	9
1	1.31								
2	92.34								
3	106.72								

$\cdot 10^6$

Рассматриваемая ступень:

$$j_w = \left\{ \begin{array}{l} j = \left\{ \begin{array}{l} 1 \text{ if type = "compressor"} \\ Z \text{ if type = "turbine"} \end{array} \right. = 1 \\ j = \left\{ \begin{array}{l} \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j \text{ otherwise} \end{array} \right. \end{array} \right.$$

$$b_{lim} = \frac{ceil\left(\max\left(chord_{rotor_{j,N_r}}, chord_{stator_{j,N_r}}\right) \cdot 10^2\right)}{10^2} = 190 \cdot 10^{-3}$$

Расстояния от оси ЛМ до рассматриваемой ступени (м):

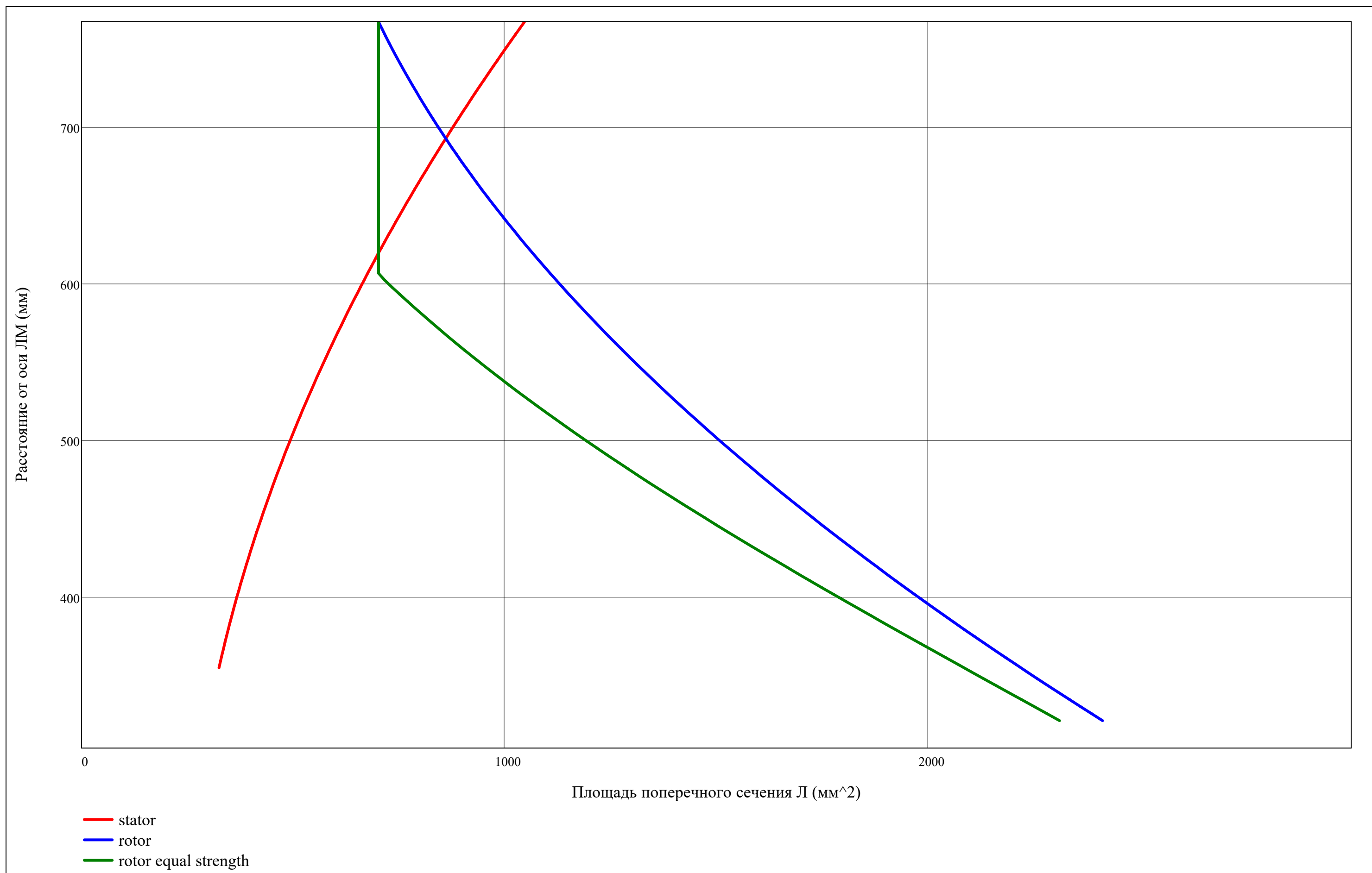
$$R_j = \text{submatrix}\left(R, 2 \cdot j - 1, 2 \cdot j + 1, 1, N_r\right) = \begin{array}{|c|c|c|c|} \hline & 1 & 2 & 3 \\ \hline 1 & 302.9 & 583.4 & 767.5 \\ \hline 2 & 338.1 & 593.0 & 767.5 \\ \hline 3 & 370.4 & 602.6 & 767.5 \\ \hline \end{array} \cdot 10^{-3}$$

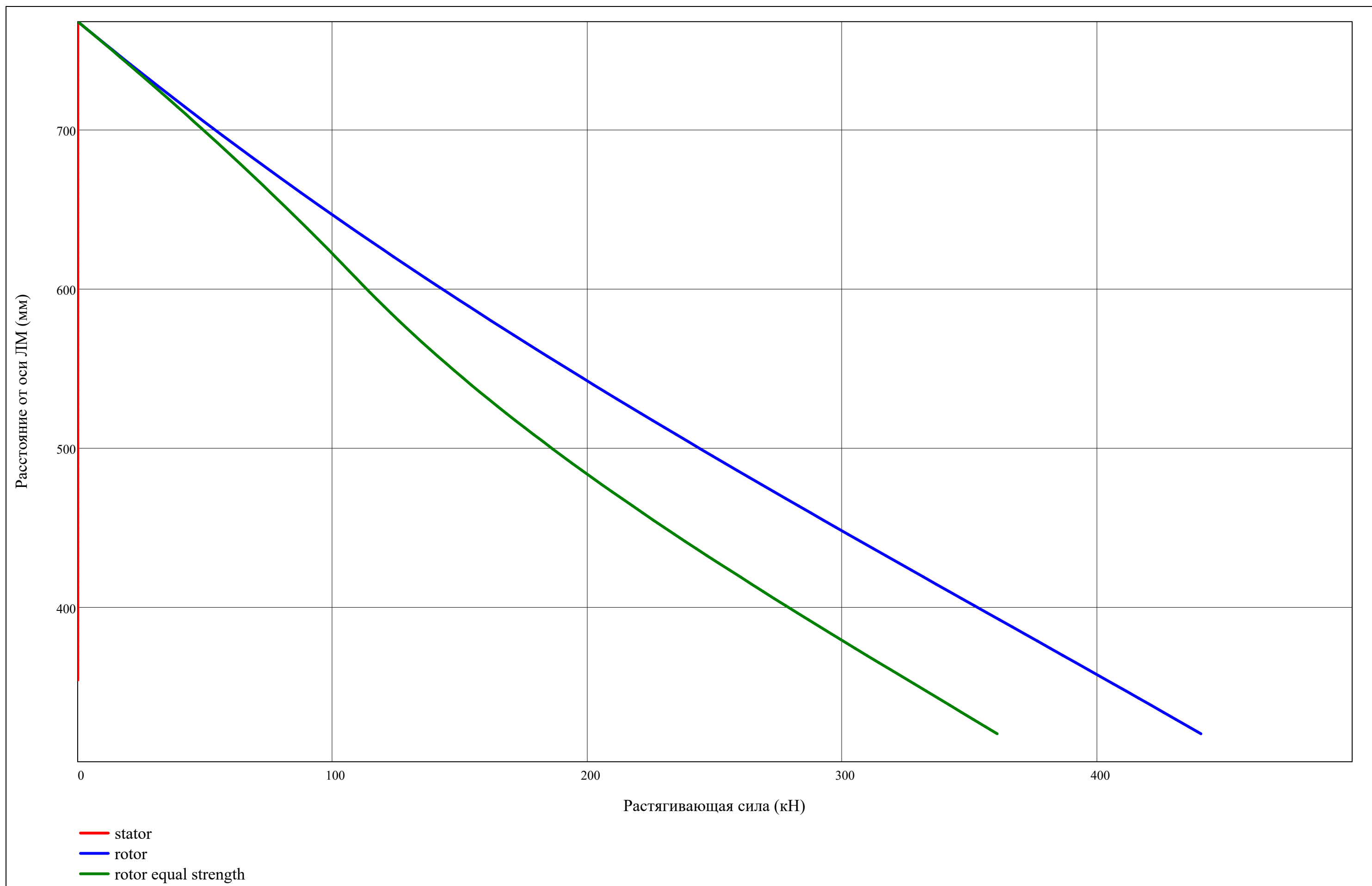
Дискретизация по высоте Л:

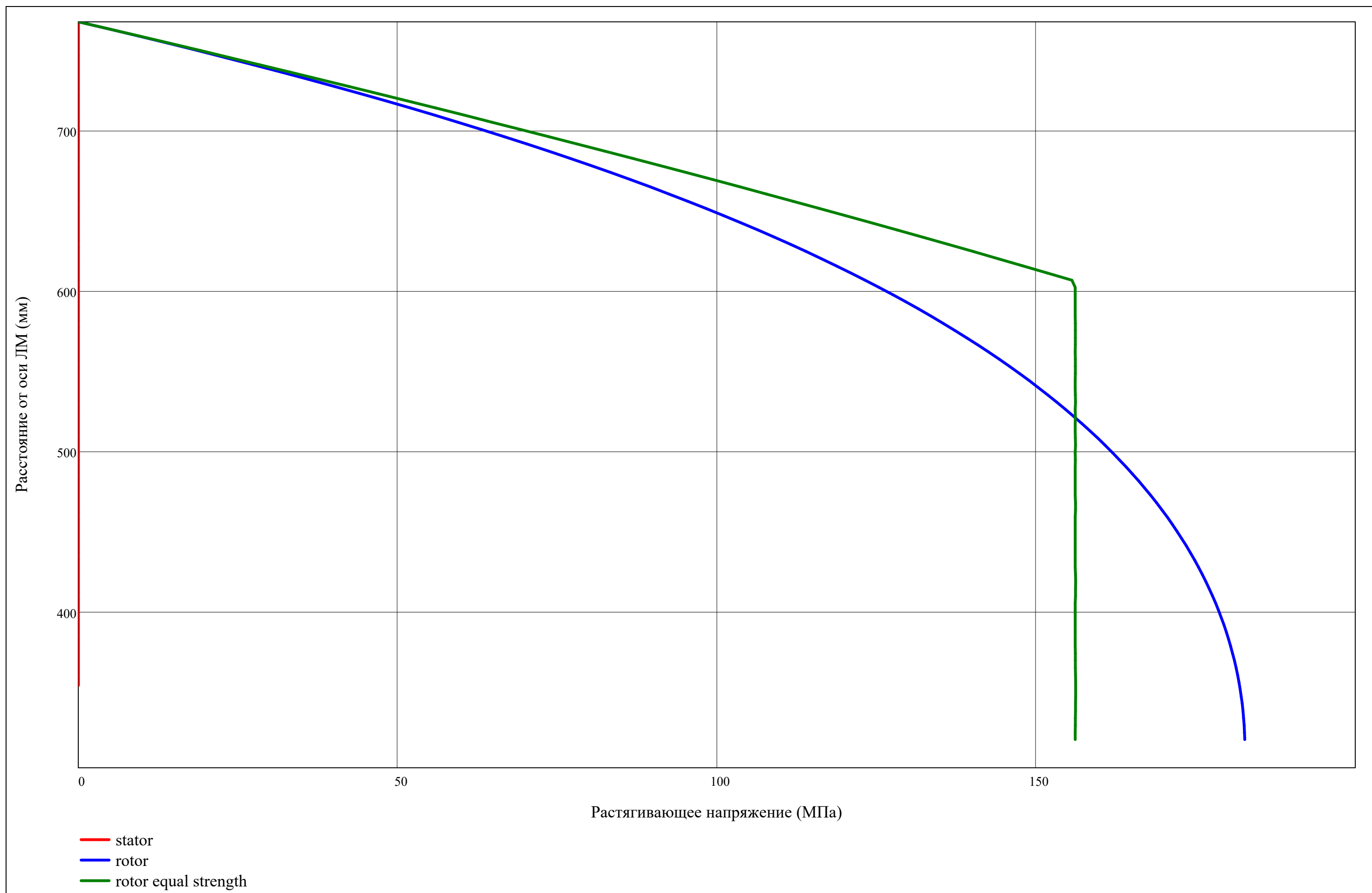
$$z = \min(R_j), \min(R_j) + \frac{\max(R_j) - \min(R_j)}{100} .. \max(R_j)$$

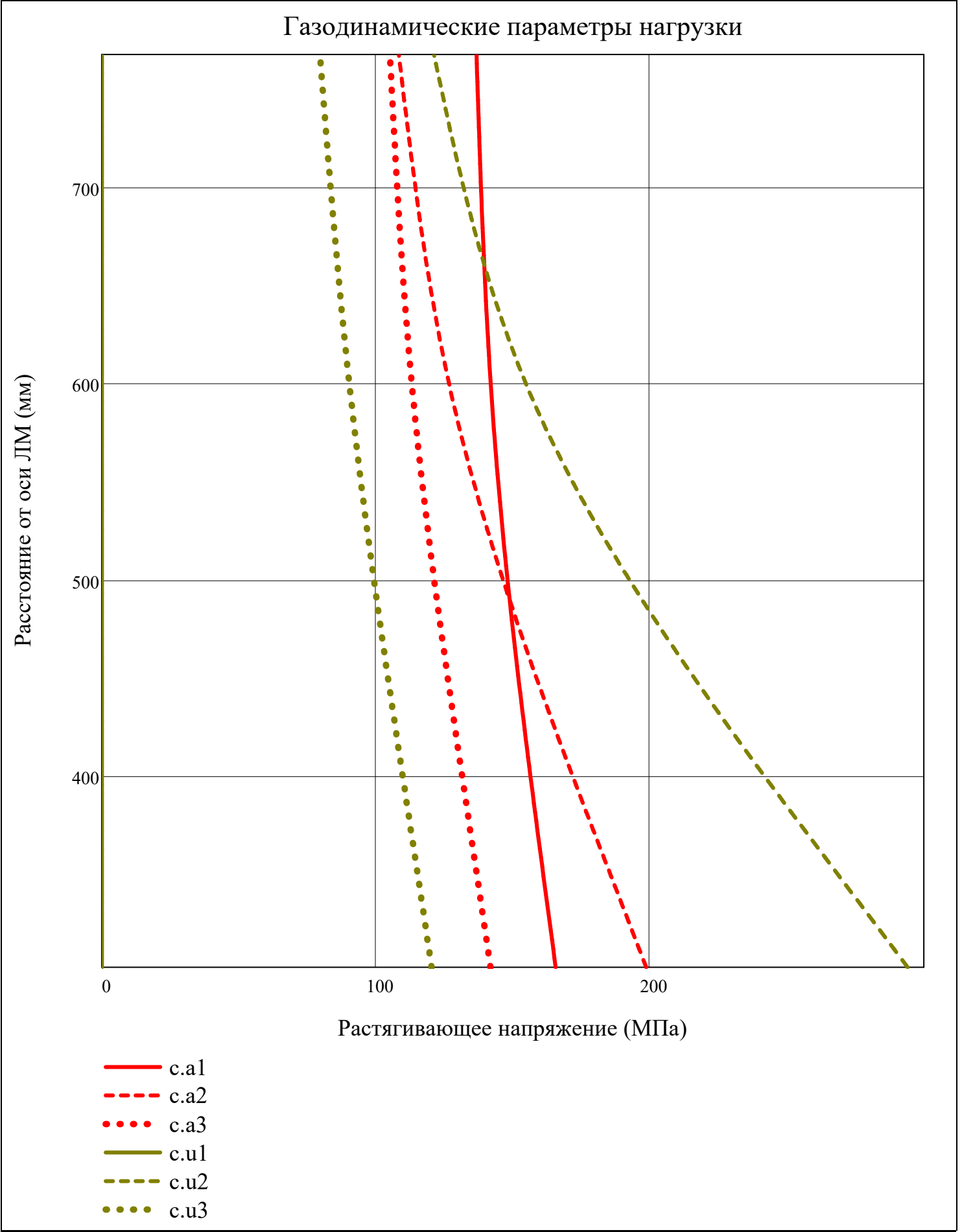
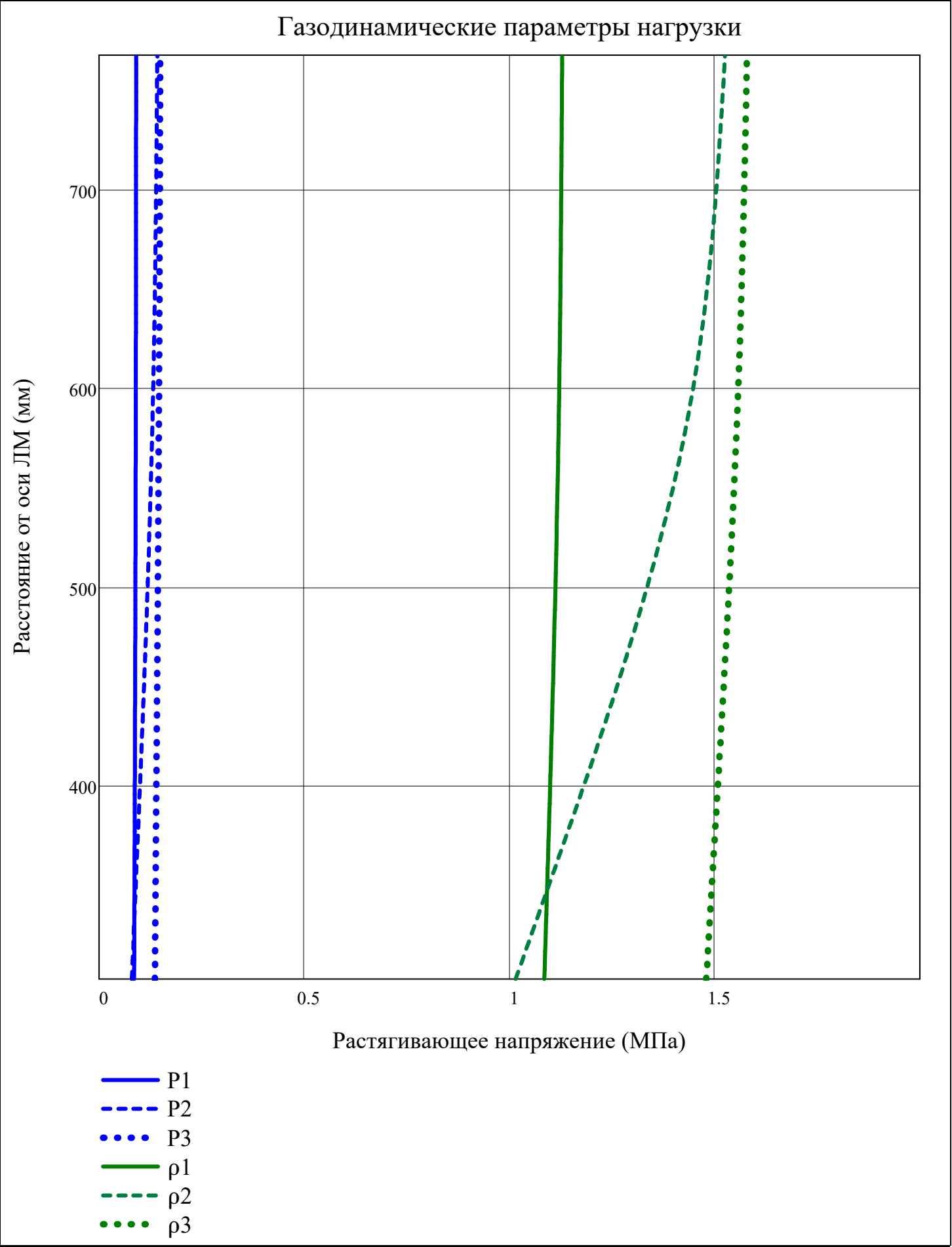
$$z_{rotor} = \left\{ \begin{array}{l} \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \text{ if type = "compressor"} \\ \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \text{ if type = "turbine"} \end{array} \right.$$

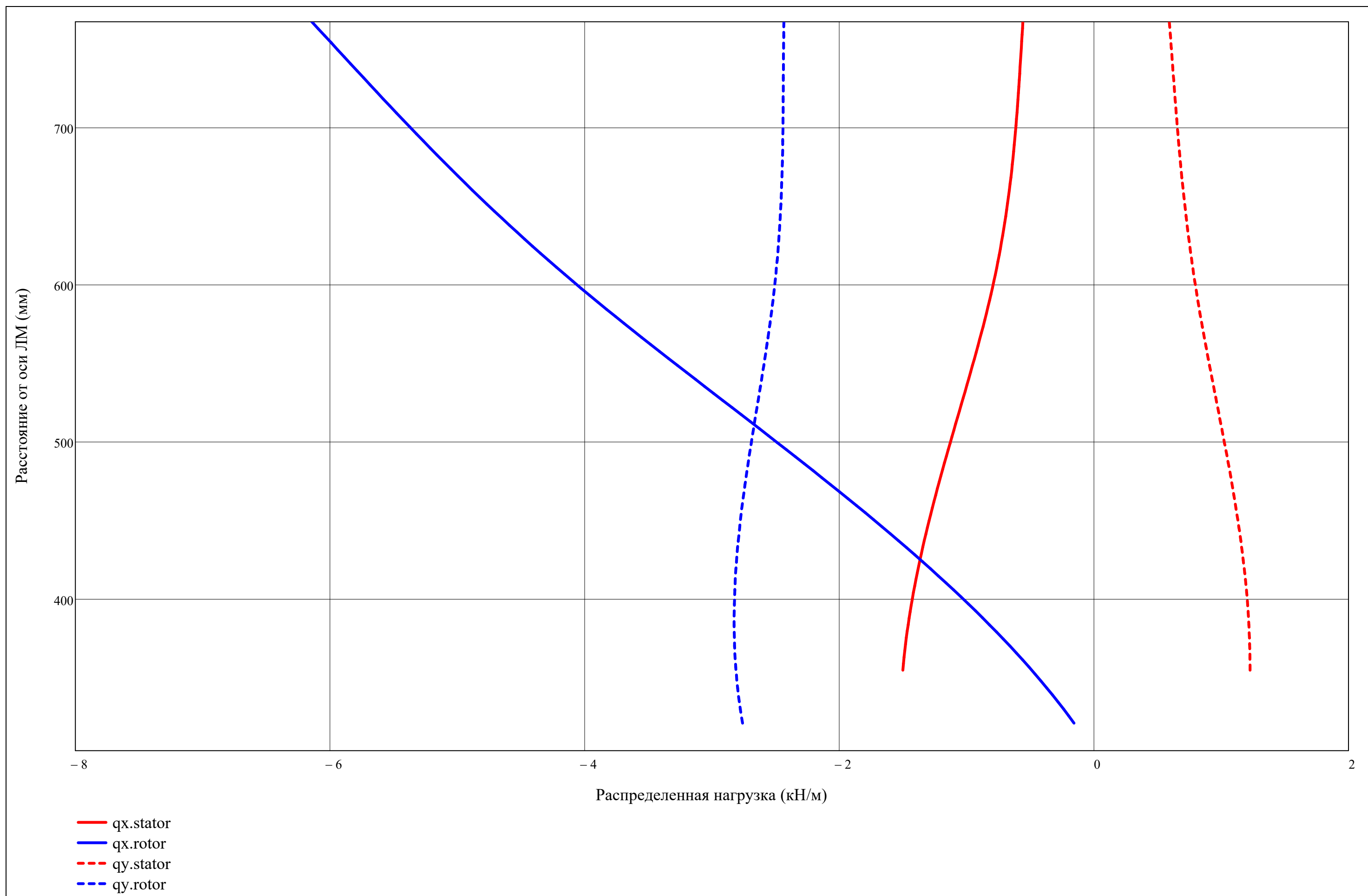
$$z_{stator} = \left\{ \begin{array}{l} \text{mean}\left(R_{j2,1}, R_{j3,1}\right), \text{mean}\left(R_{j2,1}, R_{j3,1}\right) + \frac{\text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) - \text{mean}\left(R_{j2,1}, R_{j3,1}\right)}{100} .. \text{mean}\left(R_{j2,N_r}, R_{j3,N_r}\right) \text{ if type = "compressor"} \\ \text{mean}\left(R_{j1,1}, R_{j2,1}\right), \text{mean}\left(R_{j1,1}, R_{j2,1}\right) + \frac{\text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) - \text{mean}\left(R_{j1,1}, R_{j2,1}\right)}{100} .. \text{mean}\left(R_{j1,N_r}, R_{j2,N_r}\right) \text{ if type = "turbine"} \end{array} \right.$$

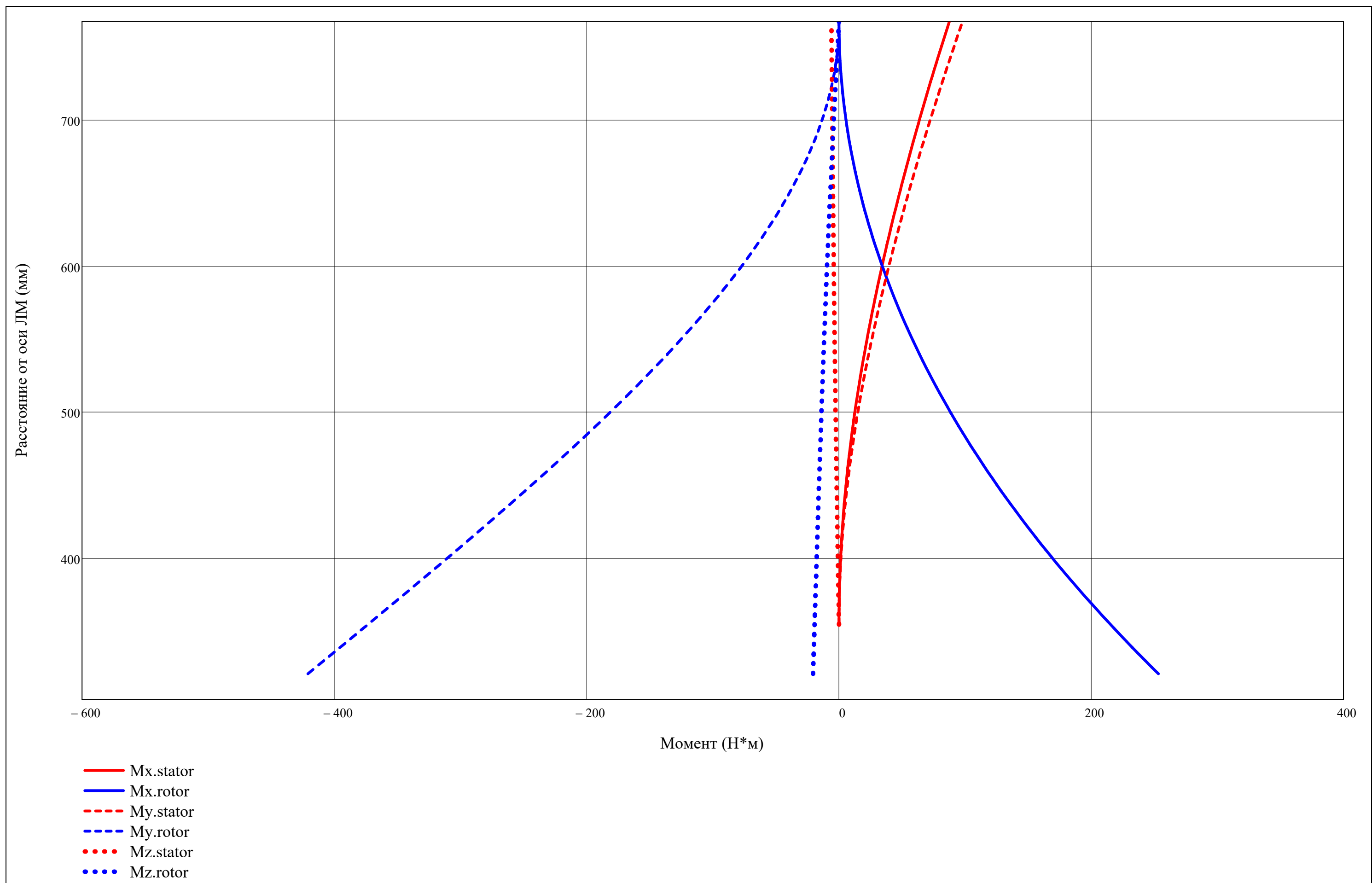


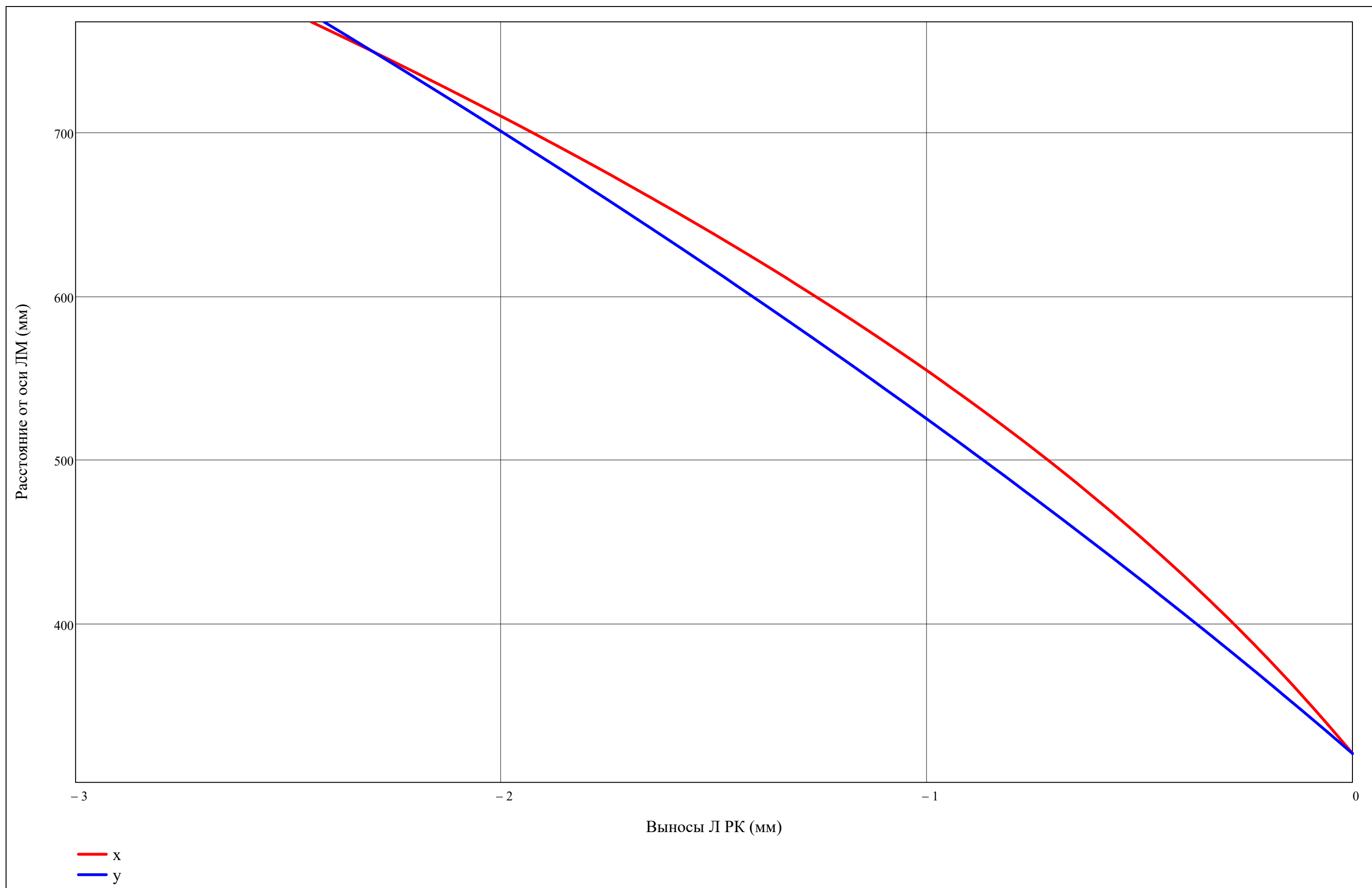


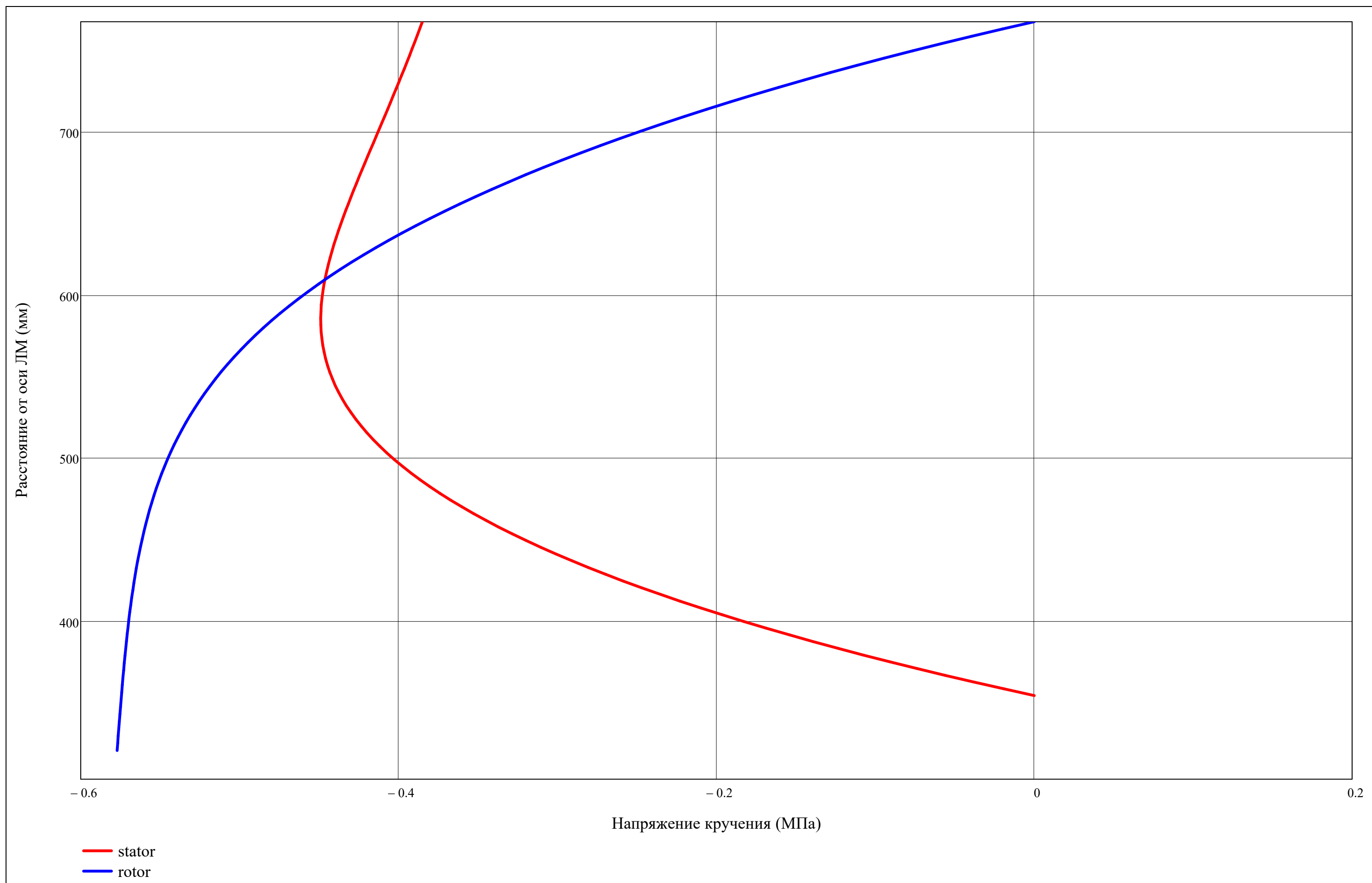


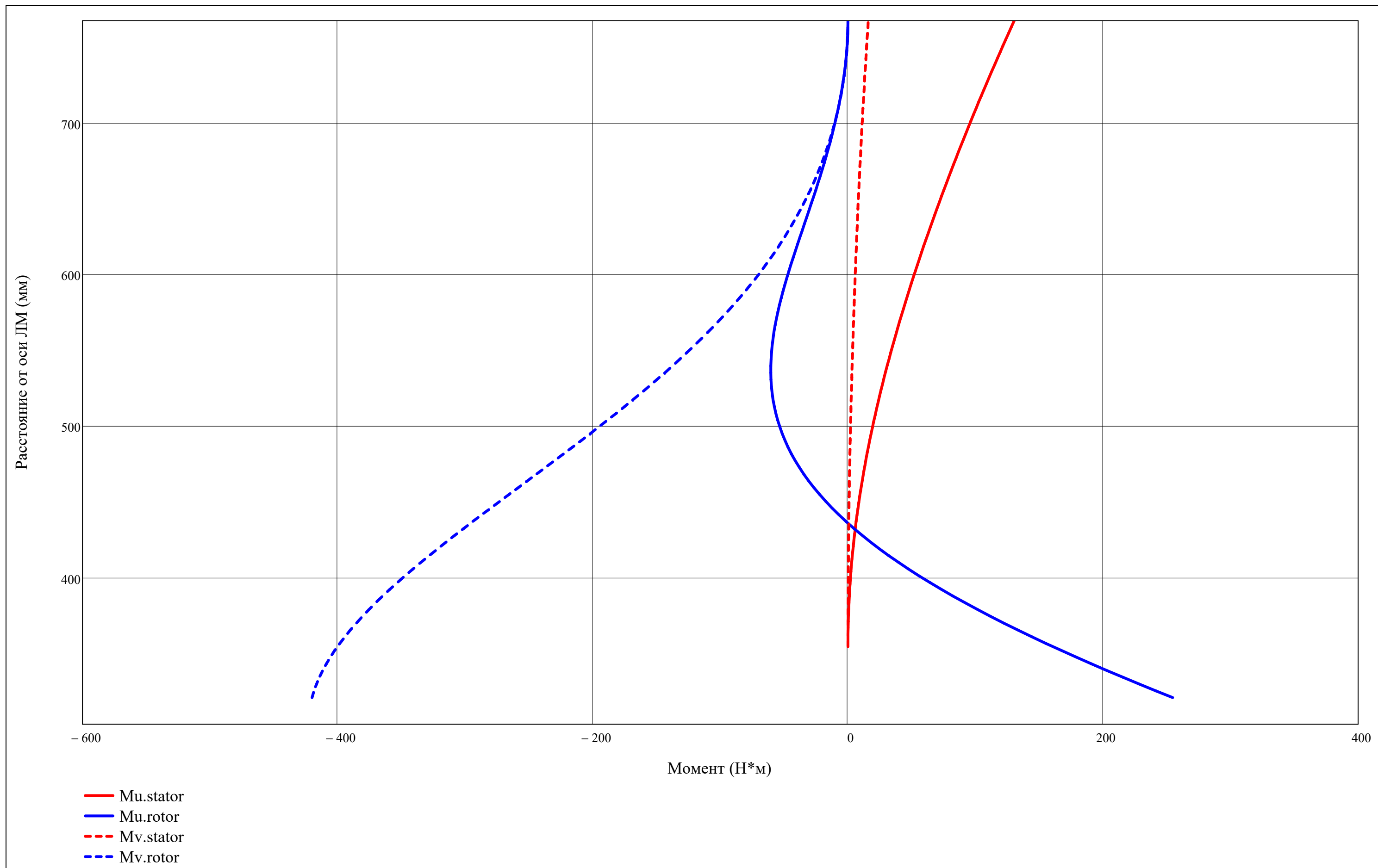


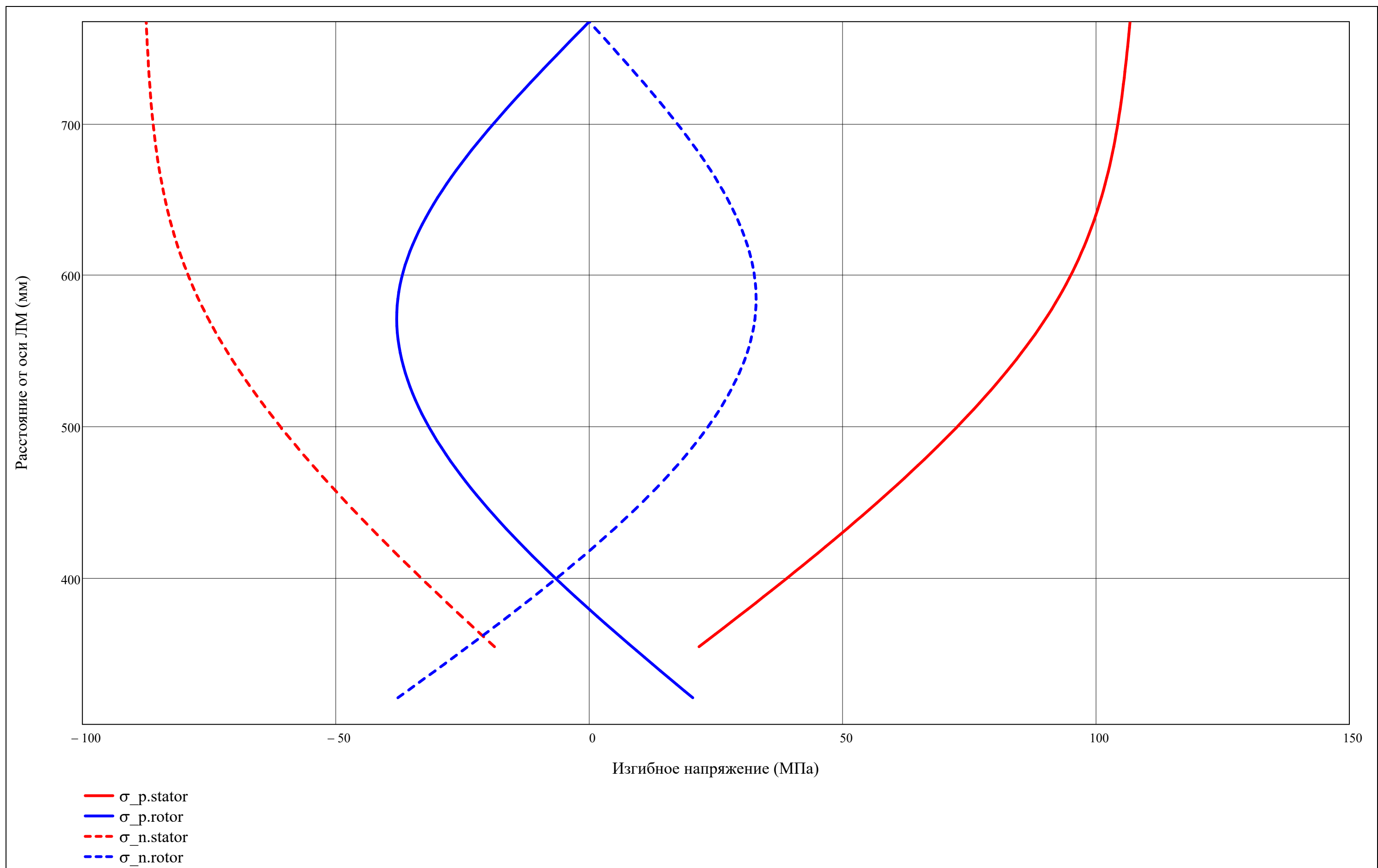


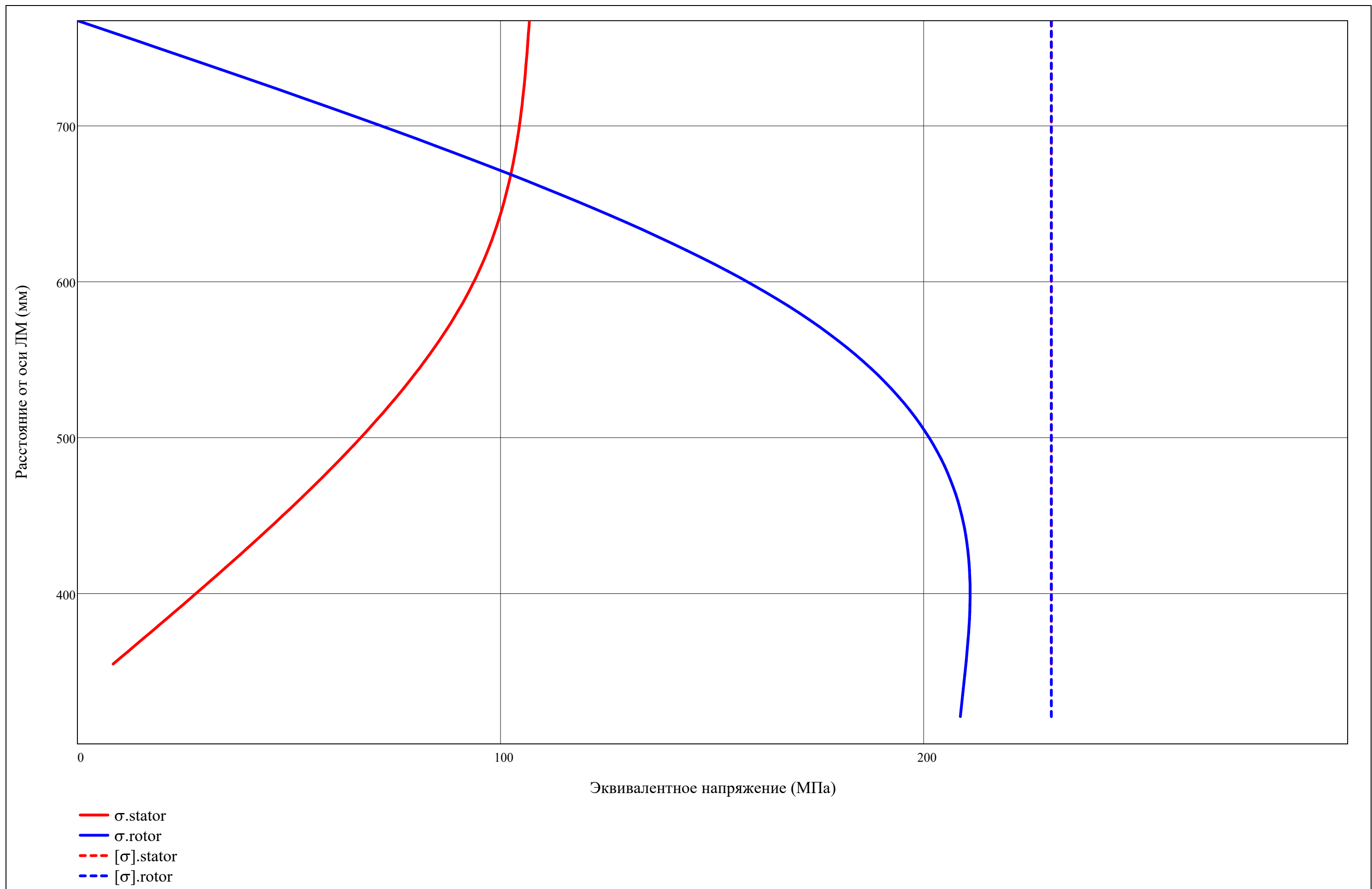


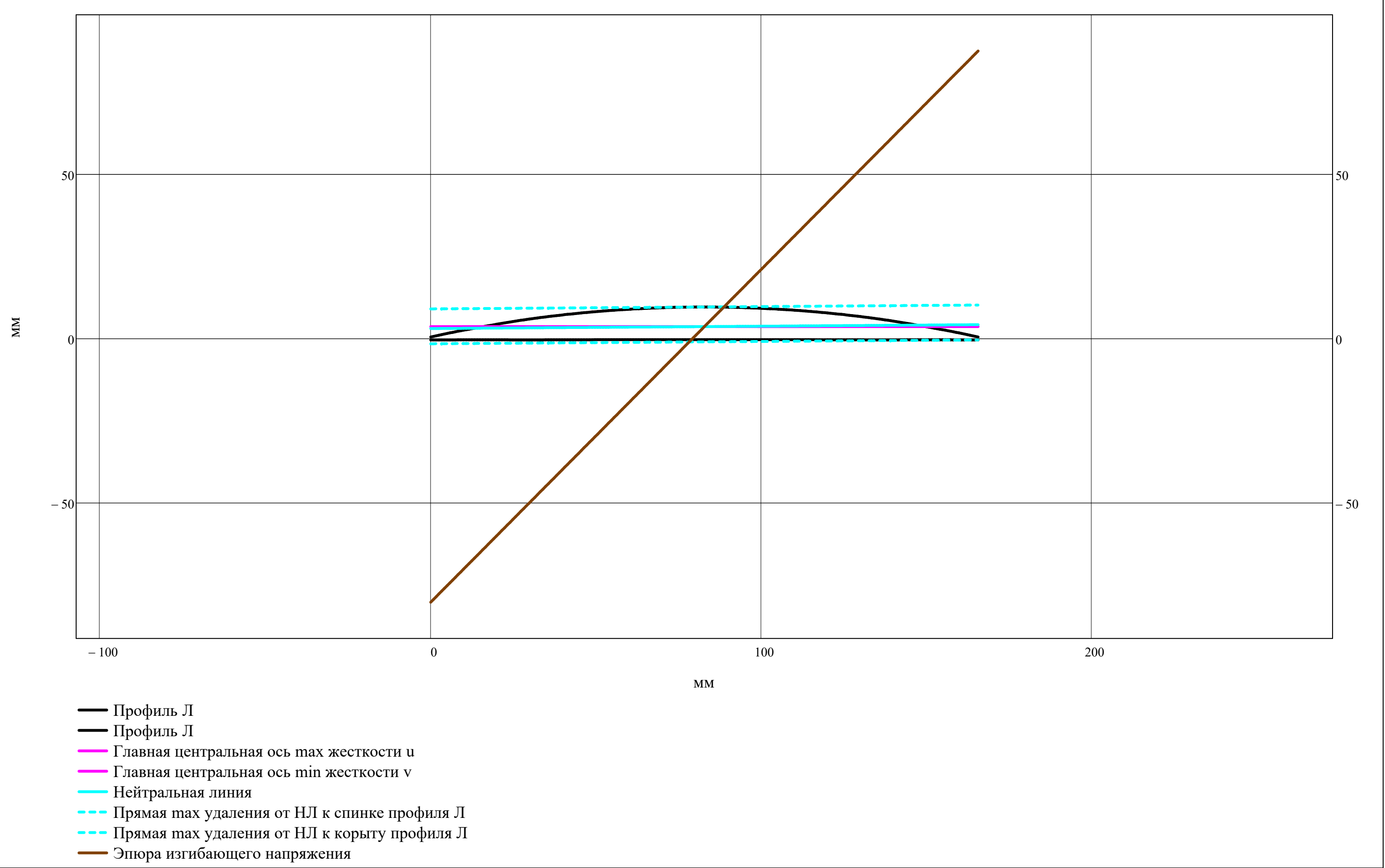












Наиболее удаленные точки от НЛ (мм):

$$\begin{pmatrix} u_{-u_{\text{rotor}_{j,r}}} & v_{-u_{\text{rotor}_{j,r}}} \\ u_{-l_{\text{rotor}_{j,r}}} & v_{-l_{\text{rotor}_{j,r}}} \\ u_{-u_{\text{stator}_{j,r}}} & v_{-u_{\text{stator}_{j,r}}} \\ u_{-l_{\text{stator}_{j,r}}} & v_{-l_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{table} \tr> | 1 | 2 || 1 | -3.27 | 5.98 |
| 2 | 82.74 | -4.65 |
| 3 | -1.52 | 4.13 |
| 4 | -46.90 | -3.46 |$$

$$\begin{pmatrix} \sigma_{-p_{\text{rotor}_{j,r}}} & \sigma_{-p_{\text{stator}_{j,r}}} \\ \sigma_{-n_{\text{rotor}_{j,r}}} & \sigma_{-n_{\text{stator}_{j,r}}} \end{pmatrix} = \begin{pmatrix} -37.79 & 92.34 \\ 32.94 & -77.00 \end{pmatrix} \cdot 10^6$$

$$\begin{pmatrix} \sigma_{\text{stator}_{j,r}} \\ \sigma_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{pmatrix} 92.34 \\ 162.56 \end{pmatrix} \cdot 10^6$$

$$\begin{pmatrix} \text{safety}_{\text{stator}_{j,r}} \\ \text{safety}_{\text{rotor}_{j,r}} \end{pmatrix} = \begin{table} \tr> | 1 || 1 | 2.491 |
| 2 | 1.415 |$$

Запас по температуре (K):

$\Delta T_{safety} = 0$

Выбранный материал Д:

material_disk_i =

"BT23" if compressor = "Вл"
"BT6" if compressor = "КНД"
"BT9" if compressor = "КВД"

Плотность материала Д (кг/м^3):

ρ_{disk_i} =

8266 if material_disk_i = "ВЖ175"
8320 if material_disk_i = "ЭП742"
8393 if material_disk_i = "ЖС-6К"
7900 if material_disk_i = "BT41"
4500 if material_disk_i = "BT25"
4570 if material_disk_i = "BT23"
4510 if material_disk_i = "BT9"
4430 if material_disk_i = "BT6"
NaN otherwise

Предел длительной прочности Д (Па):

σ_{disk_long_i} = 10⁶ ·

620 if material_disk_i = "ВЖ175"
680 if material_disk_i = "ЭП742"
125 if material_disk_i = "ЖС-6К"
123 if material_disk_i = "BT41"
150 if material_disk_i = "BT25"
230 if material_disk_i = "BT23"
200 if material_disk_i = "BT9"
210 if material_disk_i = "BT6"
NaN otherwise

material_disk^T =

	1	2	3	4	5	6	7	8	9
1	"BT23"								

ρ_{disk}^T =

	1
1	4570

σ_{disk_long}^T =

	1
1	230

· 10⁶

▲ Выбор материала Д

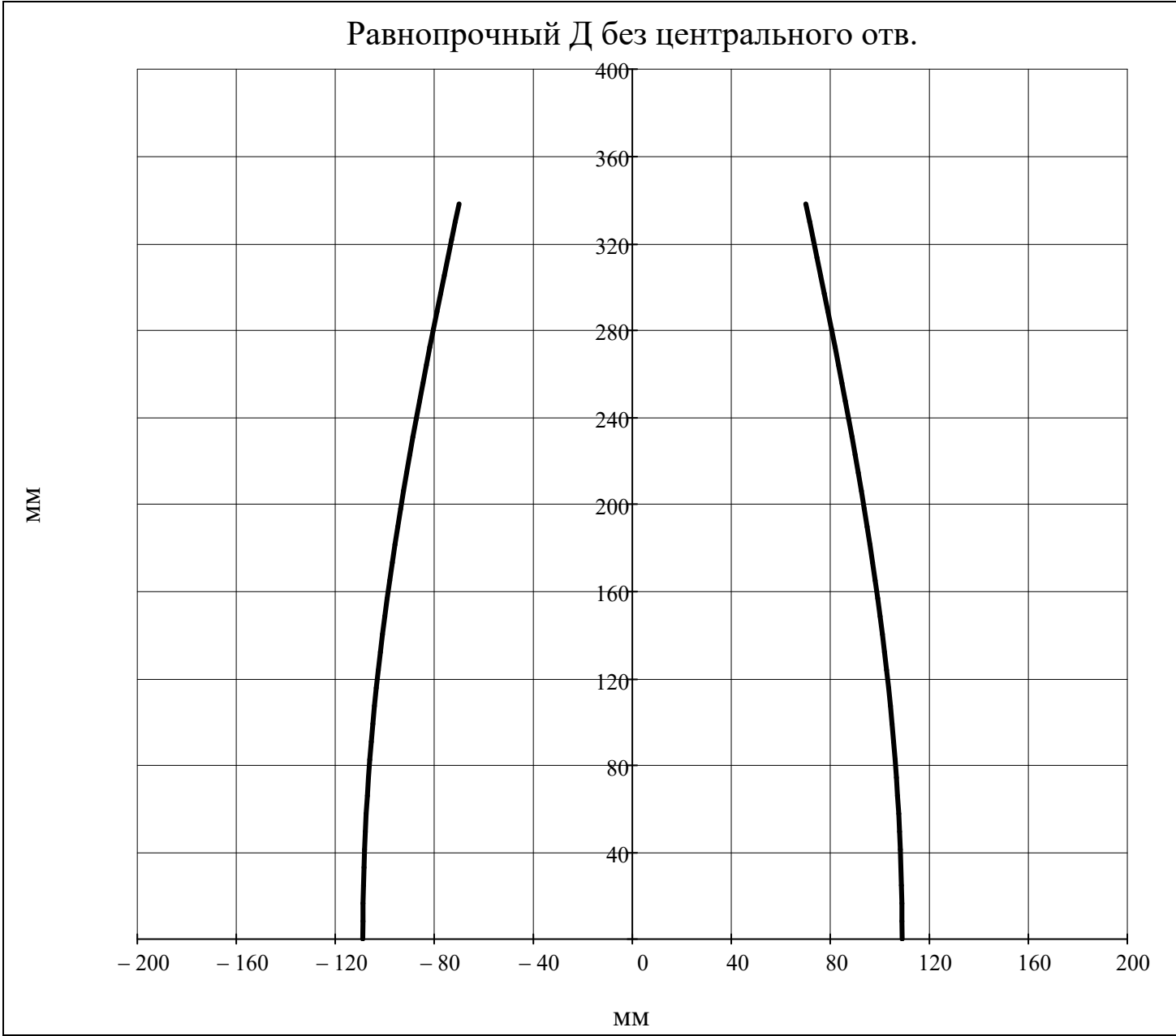
Рассматриваемая ступень:

$$j_w = \begin{cases} j = 1 & = 1 \\ j = & \text{"Такой ступени не существует!" if } (j < 1) \vee (j > Z) \\ j & \text{otherwise} \end{cases}$$

▼ Профилирование равнопрочного Д без центрального отв.

$$h(i,z) = \begin{cases} \left(\text{chord}_{\text{rotor}_i, \text{ORIGIN}} \cdot \sin \left(v_{\text{rotor}_i, \text{ORIGIN}} \right) \right) \cdot e^{\frac{\rho_{\text{disk}_i} \cdot \omega^2}{2} \cdot \frac{1}{\sigma_{z_{\text{rotor}}(i, R_{\text{st}}(i, 2), \text{ORIGIN})}} \cdot \left[\left(R_{\text{st}}(i, 2), \text{ORIGIN} \right)^2 - z^2 \right]} & \text{if } z \leq R_{\text{st}}(i, 2), \text{ORIGIN} \\ \text{NaN} & \text{otherwise} \end{cases}$$

$$z = 0, \frac{R_{\text{st}}(j, 2), \text{ORIGIN}}{N_{\text{dis}}} .. R_{\text{st}}(j, 2), \text{ORIGIN}$$



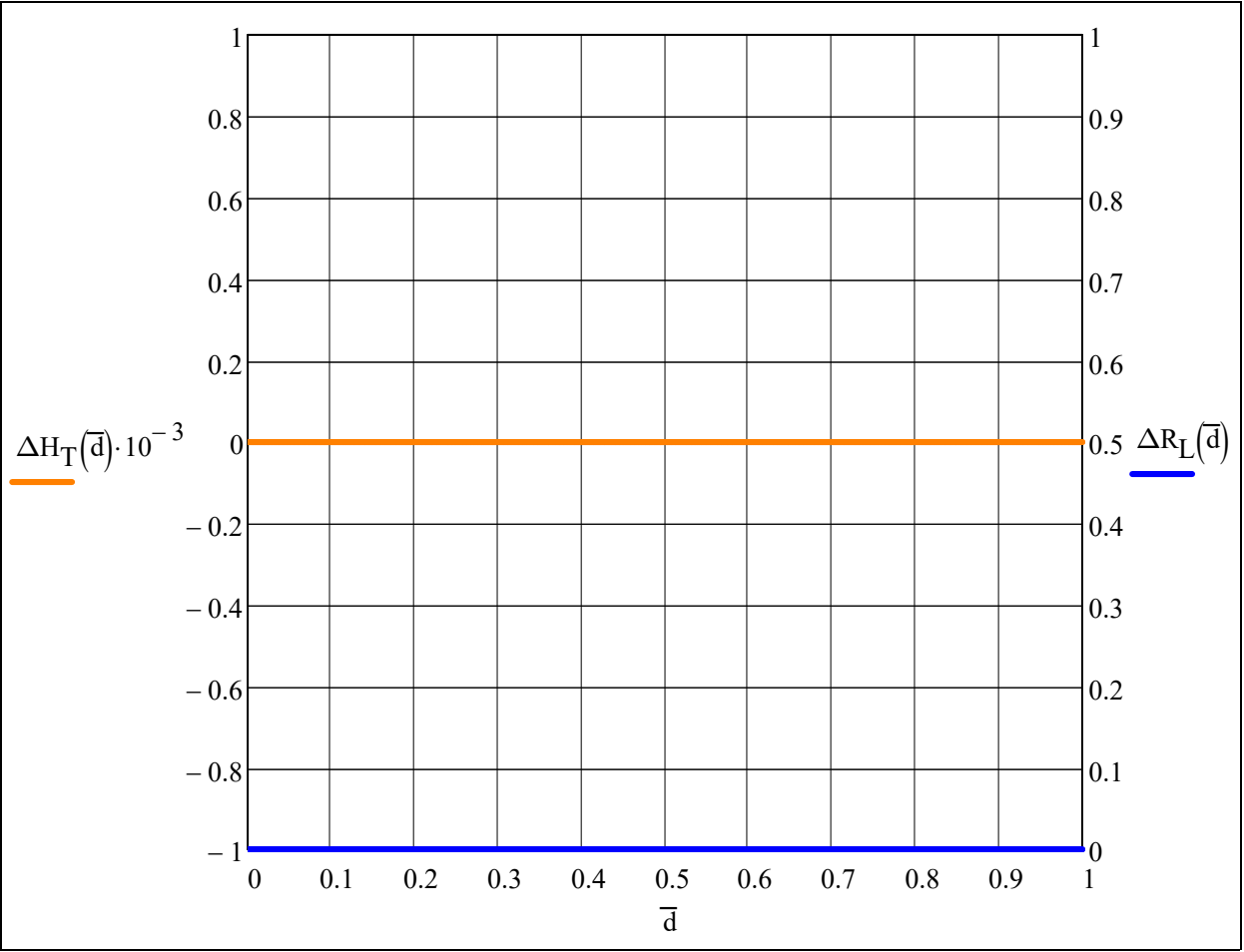
▲ Профилирование равнопрочного Д без центрального отв.

Мах разлика теор. напора ступени и реактивности
от периферии к корню по высоте Л (Дж/кг)
[16, с.118-119]:

$$\Delta H_{Tmax} = 0 \cdot 10^3$$

$$\Delta R_{Lmax} = 0.0$$

$$\Delta H_T(\bar{d}) = -\Delta H_{Tmax} \cdot \bar{d} + \Delta H_{Tmax}$$
$$\Delta R_L(\bar{d}) = -\Delta R_{Lmax} \cdot \bar{d} + \Delta R_{Lmax}$$



$$\begin{pmatrix} c_{\text{st}(\text{j},1),\text{r}} \\ c_{\text{st}(\text{j},2),\text{r}} \\ c_{\text{st}(\text{j},3),\text{r}} \end{pmatrix} = \begin{pmatrix} 165.58 \\ 333.69 \\ 175.76 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{\text{st}(\text{j},1),\text{r}} \\ \alpha_{\text{st}(\text{j},2),\text{r}} \\ \alpha_{\text{st}(\text{j},3),\text{r}} \end{pmatrix} = \begin{pmatrix} 90.00 \\ 34.48 \\ 49.99 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{\text{stator}_{\text{j},\text{r}}} = 15.52 \cdot ^\circ$$

$$\begin{pmatrix} c_{\text{a}_{\text{st}(\text{j},1),\text{r}}} \\ c_{\text{a}_{\text{st}(\text{j},2),\text{r}}} \\ c_{\text{a}_{\text{st}(\text{j},3),\text{r}}} \end{pmatrix} = \begin{pmatrix} 165.58 \\ 188.89 \\ 134.63 \end{pmatrix}$$

$$\begin{pmatrix} u_{\text{st}(\text{j},1),\text{r}} \\ u_{\text{st}(\text{j},2),\text{r}} \\ u_{\text{st}(\text{j},3),\text{r}} \end{pmatrix} = \begin{pmatrix} 168.13 \\ 187.64 \\ 205.57 \end{pmatrix}$$

$$\begin{pmatrix} w_{\text{st}(\text{j},1),\text{r}} \\ w_{\text{st}(\text{j},2),\text{r}} \\ w_{\text{st}(\text{j},3),\text{r}} \end{pmatrix} = \begin{pmatrix} 235.98 \\ 208.15 \\ 163.39 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{\text{st}(\text{j},1),\text{r}} \\ \beta_{\text{st}(\text{j},2),\text{r}} \\ \beta_{\text{st}(\text{j},3),\text{r}} \end{pmatrix} = \begin{pmatrix} 44.56 \\ 114.84 \\ 55.48 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{\text{rotor}_{\text{j},\text{r}}} = 70.28 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 142.69 \\ 202.3 \\ 144.39 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90 \\ 39.17 \\ 51.42 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 12.25 \cdot ^\circ$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 142.69 \\ 127.78 \\ 112.87 \end{pmatrix}$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 323.8 \\ 329.11 \\ 334.43 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 353.85 \\ 214.5 \\ 269.19 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 23.78 \\ 36.56 \\ 24.79 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 12.78 \cdot ^\circ$$

$$\begin{pmatrix} c_{st(j,1),r} \\ c_{st(j,2),r} \\ c_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 136.69 \\ 162.54 \\ 131.80 \end{pmatrix}$$

$$\begin{pmatrix} c_{a_{st(j,1),r}} \\ c_{a_{st(j,2),r}} \\ c_{a_{st(j,3),r}} \end{pmatrix} = \begin{pmatrix} 136.69 \\ 108.33 \\ 105.08 \end{pmatrix}$$

$$\begin{pmatrix} w_{st(j,1),r} \\ w_{st(j,2),r} \\ w_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 447.33 \\ 323.44 \\ 361.97 \end{pmatrix}$$

$$\begin{pmatrix} \alpha_{st(j,1),r} \\ \alpha_{st(j,2),r} \\ \alpha_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 90 \\ 41.8 \\ 52.87 \end{pmatrix} \cdot ^\circ$$

$$\begin{pmatrix} u_{st(j,1),r} \\ u_{st(j,2),r} \\ u_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 425.94 \\ 425.94 \\ 425.94 \end{pmatrix}$$

$$\begin{pmatrix} \beta_{st(j,1),r} \\ \beta_{st(j,2),r} \\ \beta_{st(j,3),r} \end{pmatrix} = \begin{pmatrix} 17.79 \\ 19.57 \\ 16.88 \end{pmatrix} \cdot ^\circ$$

$$\epsilon_{stator_{j,r}} = 11.07 \cdot ^\circ$$

$$\epsilon_{rotor_{j,r}} = 1.78 \cdot ^\circ$$











$$\begin{pmatrix} \cdot \\ \vdots \\ z^T \end{pmatrix}$$



7	8	9