#### Вывод ур-я относ. массового расхода горючего, отнесенного к массовому расходу на входе в І контур, через относ. массовый расход горючего, отнесенного к массовому расходу на входе в КС.

$$g_{\text{OXJ\_KC3}} = \frac{G_{\text{OXJ}}}{G_{\text{KC3}}} = \frac{G_{\text{OXJ}}}{G_{\text{I}} - G_{\text{OXJ}} - G_{\text{YT}} + G_{\text{rop}}}$$

$$\frac{G_{\text{OXJ}}}{G_{\text{KC3}}} = \frac{G_{\text{OXJ}}}{G_{\text{I}} - G_{\text{OXJ}} - G_{\text{YT}} + G_{\text{rop}}}$$

$$g_{\text{OXJ}}_{\text{KC3}} = \frac{G_{\text{OXJ}}}{G_{\text{I}} - G_{\text{OXJ}} - G_{\text{YT}} + G_{\text{rop}}} \text{ solve, } G_{\text{OXJ}} = \frac{g_{\text{OXJ}}_{\text{KC3}} \cdot \left(G_{\text{I}} - G_{\text{YT}} + G_{\text{rop}}\right)}{g_{\text{OXJ}}_{\text{KC3}} + 1}$$
(Тихонов)

$$\mathbf{g}_{\text{rop\_KC1}} = \frac{\mathbf{G}_{\text{rop}}}{\mathbf{G}_{\text{KC1}}} = \frac{\mathbf{G}_{\text{rop}}}{\mathbf{G}_{\text{I}} - \mathbf{G}_{\text{OXJI}} - \mathbf{G}_{\text{YT}}}$$

$$\mathbf{g}_{\text{rop\_KC1}} = \frac{\mathbf{G}_{\text{rop}}}{\mathbf{G}_{\text{KC1}}} = \frac{\mathbf{G}_{\text{rop}}}{\mathbf{G}_{\text{I}} - \mathbf{G}_{\text{oxn}} - \mathbf{G}_{\text{yT}}}$$

$$\mathbf{g}_{\text{rop\_KC1}} = \frac{\mathbf{G}_{\text{rop}}}{\mathbf{G}_{\text{I}} - \mathbf{G}_{\text{oxn}} - \mathbf{G}_{\text{yT}}} \text{ solve, } \mathbf{G}_{\text{rop}} = -\mathbf{g}_{\text{rop\_KC1}} \cdot \left(\mathbf{G}_{\text{yT}} - \mathbf{G}_{\text{I}} + \mathbf{G}_{\text{oxn}}\right)$$

$$g_{\text{rop\_KC1}} = \frac{G_{\text{rop}}}{G_{\text{I}} - G_{\text{ox}\pi} - G_{\text{yT}}} \text{ substitute,} G_{\text{ox}\pi} = \frac{g_{\text{ox}\pi\_KC3} \cdot \left(G_{\text{I}} - G_{\text{yT}} + G_{\text{rop}}\right)}{g_{\text{ox}\pi\_KC3} + 1} \\ = g_{\text{rop\_KC1}} = -\frac{G_{\text{rop}} \cdot \left(g_{\text{ox}\pi\_KC3} + 1\right)}{G_{\text{yT}} - G_{\text{I}} + G_{\text{rop}} \cdot g_{\text{ox}\pi\_KC3}}$$

$$g_{\text{rop\_KC1}} = -\frac{G_{\text{rop}} \cdot \left(g_{\text{OX}\Pi\_KC3} + 1\right)}{G_{\text{yT}} - G_{\text{I}} + G_{\text{rop}} \cdot g_{\text{OX}\Pi\_KC3}} \text{ solve, } G_{\text{rop}} = \frac{G_{\text{I}} \cdot g_{\text{rop\_KC1}} - G_{\text{yT}} \cdot g_{\text{rop\_KC1}}}{g_{\text{OX}\Pi\_KC3} + g_{\text{rop\_KC1}} \cdot g_{\text{OX}\Pi\_KC3} + 1}$$

$$G_{\text{rop}} = \frac{G_{\text{I}} \cdot g_{\text{rop\_KC1}} - G_{\text{yT}} \cdot g_{\text{rop\_KC1}}}{g_{\text{OXJ} \text{ KC3}} + g_{\text{rop} \text{ KC1}} \cdot g_{\text{OXJ} \text{ KC3}} + 1} = G_{\text{I}} \cdot \frac{g_{\text{rop\_KC1}} - g_{\text{yT}} \cdot g_{\text{rop\_KC1}}}{g_{\text{OXJ} \text{ KC3}} + g_{\text{rop} \text{ KC1}} \cdot g_{\text{OXJ} \text{ KC3}} + 1}$$

$$\mathbf{g}_{rop} = \frac{\mathbf{G}_{rop}}{\mathbf{G}_{I}} = \frac{\mathbf{G}_{I} \frac{\mathbf{g}_{rop\_KC1} - \mathbf{g}_{y_{I}} \cdot \mathbf{g}_{rop\_KC1}}{\mathbf{g}_{ox_{I}\_KC3} + \mathbf{g}_{rop\_KC1} \cdot \mathbf{g}_{ox_{I}\_KC3} + 1}}{\mathbf{G}_{I}} = \frac{\mathbf{g}_{rop\_KC1} - \mathbf{g}_{y_{I}} \cdot \mathbf{g}_{rop\_KC1}}{\mathbf{g}_{ox_{I}\_KC3} + \mathbf{g}_{rop\_KC1} \cdot \mathbf{g}_{ox_{I}\_KC3} + 1}$$

#### Вывод ур-я Тихонова относ. массового расхода на охлаждение, отнесенного к массовому расходу на входе в І контур, через относ. массовый расход на охлаждение, онесенного к массовому расходу на выходе из КС.

$$g_{\text{OXJI}} = \frac{G_{\text{OXJI}}}{G_{\text{I}}} = \frac{\frac{g_{\text{OXJI\_KC3}} \cdot \left(G_{\text{I}} - G_{\text{yT}} + G_{\text{rop}}\right)}{g_{\text{OXJI\_KC3}} + 1}}{G_{\text{I}}} = \frac{G_{\text{I}} \cdot \frac{g_{\text{OXJI\_KC3}} \cdot \left(1 - g_{\text{yT}} + g_{\text{rop}}\right)}{g_{\text{OXJI\_KC3}} + 1}}{G_{\text{I}}} = \frac{g_{\text{OXJI\_KC3}} \cdot \left(1 - g_{\text{yT}} + g_{\text{rop}}\right)}{g_{\text{OXJI\_KC3}} \cdot \left(1 - g_{\text{yT}} + g_{\text{rop}}\right)}}{g_{\text{OXJI\_KC3}} \cdot \left(1 - g_{\text{yT}} + g_{\text{rop}}\right)}$$

## Вывод термодинамических парамтеров смешения

Ур-е теплового баланса:

$$Q + Q_{add} = Q_{CM}$$

$$G \cdot Cp \cdot T + G_{add} \cdot Cp_{add} \cdot T_{add} = G_{CM} \cdot Cp_{CM} \cdot T_{CM} = (G + G_{add}) \cdot Cp_{CM} \cdot T_{CM}$$

Температура СМ [К]:

$$G \cdot Cp \cdot T + G_{add} \cdot Cp_{add} \cdot T_{add} = \left(G + G_{add}\right) \cdot Cp_{CM} \cdot T_{CM} \text{ solve, } T_{CM} = \frac{Cp \cdot G \cdot T + Cp_{add} \cdot G_{add} \cdot T_{add}}{Cp_{CM} \cdot \left(G + G_{add}\right)}$$

$$T_{CM} = \frac{Cp \cdot g \cdot T + Cp_{add} \cdot g_{add} \cdot T_{ad}}{Cp_{CM} \cdot (g + g_{add})}$$

Давление СМ [Па] как среднемассовое:

$$P_{CM} = \frac{G \cdot P + G_{add} \cdot P_{add}}{G + G_{add}} = \frac{g \cdot P + g_{add} \cdot P_{add}}{g + g_{add}}$$

$$\alpha_{\text{CM}} = \frac{G_{\text{OK}\Sigma}}{G_{\text{rop}\Sigma}} = \frac{G_{\text{OK}} + G_{\text{add}}}{G_{\text{rop}} \cdot l_0(\text{Fuel})} = \frac{g_{\text{OK}} + g_{\text{add}}}{g_{\text{rop}} \cdot l_0(\text{Fuel})}$$

## Вывод оптимальной скорости выхода из С І контура

$$L_{e} = \frac{L_{B}}{\eta_{PB} \cdot \eta_{MeX}} + \frac{c_{CI}^{2} - \upsilon^{2}}{2} + \frac{c_{CII}^{2} - \upsilon^{2}}{2} \text{ solve, } L_{B} \rightarrow \eta_{PB} \cdot \eta_{MeX} \cdot \left(\upsilon^{2} - \frac{c_{CI}^{2}}{2} - \frac{c_{CII}^{2}}{2} + L_{e}\right)$$

$$L_{\text{TMT}}\left(\upsilon,c_{CI},c_{CII},L_{e},\eta_{\text{Mex}},\eta_{PB},\eta_{B},L_{B}\right) = L_{B}\cdot\eta_{B} + \left(c_{CI}-\upsilon\right)\cdot\upsilon + \left(c_{CII}-\upsilon\right)\cdot\upsilon +$$

$$\frac{\mathrm{d}}{\mathrm{d} c_{CI}} L_{\text{TMT}} \! \left( \upsilon, c_{CI}, c_{CII}, L_e, \eta_{\text{MeX}}, \eta_{PB}, \eta_B, L_B \right) \rightarrow \upsilon - c_{CI} \cdot \eta_B \cdot \eta_{PB} \cdot \eta_{\text{MeX}}$$

$$\frac{\text{d}}{\text{dc}_{CI}} \textbf{L}_{\text{TMT}} \Big( \upsilon, \textbf{c}_{CI}, \textbf{c}_{CII}, \textbf{L}_{e}, \eta_{\text{Mex}}, \eta_{PB}, \eta_{B}, \textbf{L}_{B} \Big) = 0 \text{ solve}, \textbf{c}_{CI} = \frac{\upsilon}{\eta_{B} \cdot \eta_{PB} \cdot \eta_{\text{Mex}}}$$

$$L_{e}(\upsilon,c_{\text{CI}},c_{\text{CII}},\text{m2},L_{\text{B\pi II}}) = \text{m2} \cdot L_{\text{B\pi II}} + \frac{c_{\text{CI}}(L_{\text{B\pi II}})^{2} - \upsilon^{2}}{2}$$

$$\frac{d}{dL_{B\pi II}}L_{e}\!\!\left(\upsilon,c_{CI},c_{CII},m2,L_{B\pi II}\right) = m2 + c_{CI}\!\!\left(L_{B\pi II}\right) \cdot \frac{d}{dL_{B\pi II}}c_{CI}\!\!\left(L_{B\pi II}\right) \\ \text{ solve,} \\ \frac{d}{dL_{B\pi II}}c_{CI}\!\!\left(L_{B\pi II}\right) = -\frac{m2}{c_{CI}\!\!\left(L_{B\pi II}\right)} \cdot \frac{d}{dL_{B\pi II}}c_{CI}\!\!\left(L_{B\pi II}\right) \\ = -\frac{m2}{c_{CI}\!\!\left(L_{B\pi II}\right)}c_{CI}\!\!\left(L_{B\pi II}\right) \\$$

Баланс энергии II контура: 
$$L_{B\pi II} \cdot \eta_{II} = \frac{c_{CII} \left(\upsilon, \eta_{II}, L_{B\pi II}\right)^2 - \upsilon^2}{2} \text{ solve, } c_{CII} \left(\upsilon, \eta_{II}, L_{B\pi II}\right) \\ = \begin{pmatrix} \sqrt{\upsilon^2 + 2 \cdot \eta_{II} \cdot L_{B\pi II}} \\ -\sqrt{\upsilon^2 + 2 \cdot \eta_{II} \cdot L_{B\pi II}} \end{pmatrix}$$

$$c_{CII}(\upsilon, \eta_{II}, L_{B\pi II}) = \sqrt{\upsilon^2 + 2 \cdot \eta_{II} \cdot L_{B\pi II}}$$

$$\frac{d}{dL_{B\pi II}}c_{CII}\!\!\left(\upsilon,\eta_{II},L_{B\pi II}\right) \,=\, \frac{\eta_{II}}{\sqrt{\upsilon^2 + 2\!\cdot\!\eta_{II}\!\cdot\! L_{B\pi II}}}$$

$$\text{Удельная тяга двигателя:} \quad R_{\text{уд}}\!\!\left(\upsilon,c_{\text{CII}},m_2,L_{\text{ВлII}},\eta_{\text{II}}\right) = \frac{R_{\text{удI}} + m_2 \cdot R_{\text{удII}}}{1 + m_2} \quad \begin{vmatrix} \text{substitute},R_{\text{удII}} = c_{\text{CII}}\!\left(L_{\text{ВлII}},m_2\right) - \upsilon \\ \text{substitute},R_{\text{удII}} = c_{\text{CII}}\!\left(\upsilon,\eta_{\text{II}},L_{\text{ВлII}}\right) - \upsilon \end{vmatrix} = -\frac{\upsilon - m_2 \cdot c_{\text{CII}}\!\left(\upsilon,\eta_{\text{II}},L_{\text{ВлII}}\right) + \upsilon \cdot m_2 - c_{\text{CI}}\!\left(L_{\text{ВлII}},m_2\right)}{m_2 + 1}$$

Условие получения max тяги: 
$$\frac{\mathrm{d}}{\mathrm{d}L_{\mathrm{BnII}}}R_{\mathrm{y}\mathrm{J}}\!\!\left(\upsilon,c_{\mathrm{CI}},c_{\mathrm{CII}},m2,L_{\mathrm{BnII}},\eta_{\mathrm{II}}\right)=0$$

$$\frac{d}{dL_{B\pi II}}R_{y\pi}\!\!\left(\upsilon,c_{CI},c_{CII},m2,L_{B\pi II},\eta_{II}\right) = \frac{\frac{d}{dL_{B\pi II}}c_{CI}\!\!\left(L_{B\pi II},m2\right) + \frac{m2\cdot\eta_{II}}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}}}{m2 + 1} \\ = \frac{\frac{d}{dL_{B\pi II}}c_{CI}\!\!\left(L_{B\pi II},m2\right) + \frac{m2\cdot\eta_{II}}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}}}{m2 + 1} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}} \\ = \frac{m2\cdot\left(\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}} - \eta_{II}\cdot c_{CI}\!\!\left(L_{B\pi II},m2\right)\right)}{\sqrt{\upsilon^2 + 2\cdot\eta_{II}\cdot L_{B\pi II}}}$$

## Вывод общего ур-я профилирования Л цилиндрической и конической ступени К

$$\frac{d}{dr}H_T = \frac{d}{dr}\left(\frac{c_a^2}{2}\right) + c_u\cdot\left(\frac{d}{dr}c_u\right) + \frac{c_u^2}{r} = 0$$
  $\Rightarrow \frac{d}{dr}\left(\frac{c_a^2}{2}\right) = -c_u\cdot\left(\frac{d}{dr}c_u\right) - \frac{c_u^2}{r}$  (00) Домножим на  $2 \Rightarrow \frac{d}{dr}\left(c_a^2\right) = -2 \cdot c_u\cdot\left(\frac{d}{dr}c_u\right) - \frac{2 \cdot c_u^2}{r}$ 

$$\implies \frac{d}{dr} \left( \frac{c_a^2}{2} \right) = -c_u \cdot \left( \frac{d}{dr} c_u \right) - \frac{c_u}{r}$$

$$\frac{d}{dr}\left(c_a^2\right) = -2 \cdot c_u \cdot \left(\frac{d}{dr}c_u\right) - \frac{2 \cdot c_u^2}{r}$$

$$\frac{c_{1u} + c_{2u}}{2} \cdot r^{m} = con$$

(2) 
$$H_T = (c_{2u} \cdot u_2 - c_{1u} \cdot u_1) = (c_{2u} - c_{1u})u$$

$$\mathbf{u} = \boldsymbol{\omega} \cdot \mathbf{r}$$

$$\omega = \text{const}$$
  $\frac{u_1}{r_1} = \frac{u_2}{r_2}$ 

$$R = 1 - \frac{c_{1u} + c_{2u}}{2 \cdot u} - \frac{c_{a2}^{2} - c_{a1}^{2}}{2 \cdot H_{T}}$$
 без допущений

$$R = 1 - \frac{1u - 2u}{u_1 + u_2} = 1 - \frac{1u - 2u}{2 \cdot u}$$

Вывод:

$$c_{1u} = (1 - R) \cdot \omega \cdot r - \frac{F}{2}$$

$$c_{1u} = (1 - R) \cdot \omega \cdot r - \frac{H_T}{2 \cdot \omega \cdot r}$$

$$c_{2u} = (1 - R) \cdot \omega \cdot r + \frac{H_T}{2 \cdot \omega \cdot r}$$

$$\frac{c_{1u} + c_{2u}}{2} = (1 - R) \cdot \omega \cdot r$$

(1): const = 
$$\frac{c_{1u} + c_{2u}}{2} \cdot r^m = (3) = [(1 - R)\omega \cdot r] \cdot r^m = (1 - R)\omega \cdot r^{m+1} = (1 - R_{cp})\omega \cdot r_{cp}^{m+1}$$

$$\Rightarrow (1 - R)\omega = \frac{\left[\left(1 - R_{cp}\right) \cdot \omega \cdot r_{cp}^{m+1}\right]}{r^{m+1}}$$

$$\mathbf{c}_{1\mathbf{u}} = (1 - \mathbf{R}) \cdot \boldsymbol{\omega} \cdot \mathbf{r} - \frac{\mathbf{H}_{\mathbf{T}}}{2 \cdot \boldsymbol{\omega} \cdot \mathbf{r}} = \frac{\left[ \left( 1 - \mathbf{R}_{\mathbf{c}\mathbf{p}} \right) \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{\mathbf{c}\mathbf{p}}^{\mathbf{m}+1} \right]}{\mathbf{r}^{\mathbf{m}+1}} \cdot \mathbf{r} - \frac{\mathbf{H}_{\mathbf{T}}}{2 \cdot \boldsymbol{\omega} \cdot \mathbf{r}} = \frac{\left[ \left( 1 - \mathbf{R}_{\mathbf{c}\mathbf{p}} \right) \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{\mathbf{c}\mathbf{p}}^{\mathbf{m}+1} \right]}{\mathbf{r}^{\mathbf{m}}} - \frac{\left( \frac{\mathbf{H}_{\mathbf{T}}}{2 \cdot \boldsymbol{\omega}} \right)}{\mathbf{r}^{\mathbf{m}}} = \frac{\mathbf{H}_{\mathbf{T}}}{\mathbf{r}^{\mathbf{m}}} = \frac{\mathbf{H}_{\mathbf{T}}}{\mathbf{r}^{\mathbf{m}}}$$

$$A = \left[ \left( 1 - R_{cp} \right) \cdot \omega \cdot r_{cp}^{m+1} \right]$$

$$c_{1u}(r, m, A, B) = \frac{(A)}{r} - \frac{(B)}{r}$$

$$2\mathbf{u} = (1 - R) \cdot \boldsymbol{\omega} \cdot \mathbf{r} + \frac{\mathbf{H_T}}{2 \cdot \boldsymbol{\omega} \cdot \mathbf{r}} = \frac{\left[ \left( 1 - R_{cp} \right) \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{cp}^{-m+1} \right]}{m+1} \cdot \mathbf{r} + \frac{\mathbf{H_T}}{2 \cdot \boldsymbol{\omega} \cdot \mathbf{r}} = \frac{\left[ \left( 1 - R_{cp} \right) \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{cp}^{-m+1} \right]}{m} + \frac{\left( \frac{\mathbf{H_T}}{2 \cdot \boldsymbol{\omega}} \right)}{\mathbf{r}}$$

(AB2) 
$$B = \left(\frac{H_T}{2 \cdot \omega}\right)$$

$$c_{2u}(r, m, A, B) = \frac{(A)}{r} + \frac{(B)}{r}$$

 $c_{2u}(r, m, A, B) = \frac{(A)}{r} + \frac{(B)}{r}$  Для цилиндрической ступени

$$c_{2u} = \frac{H_T + c_{1u} \cdot u_1}{u_2} = \frac{H_T + c_{1u}}{r_2}$$

 $c_{2u} = \frac{H_T + c_{1u} \cdot u_1}{u_2} = \frac{H_T + c_{1u} \cdot r_1}{r_2}$  Для конической ступни ступени (см. (3))

(0000)

(000) 
$$\int_{r_{cp}}^{r} \frac{d}{dr} \left(c_{a}^{2}\right) dr = c_{a}^{2} - c_{a.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u} \cdot \left(\frac{d}{dr}c_{u}\right) - \frac{2 \cdot c_{u}^{2}}{r} dr$$

$$c_{a1}^{2} - c_{a1.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u1} \cdot \left(\frac{d}{dr}c_{u1}\right) - \frac{2 \cdot c_{u1}^{2}}{r} dr$$

$$c_{a2}^{2} - c_{a2.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u2} \cdot \left(\frac{d}{dr}c_{u2}\right) - \frac{2 \cdot c_{u2}^{2}}{r} dr$$

$$c_{a1}^{2} - c_{a1.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u1} \cdot \left(\frac{d}{dr}c_{u1}\right) - \frac{2 \cdot c_{u1}^{2}}{r} dr$$

$$\Rightarrow c_{a1} = \int_{r_{cp}}^{r} -2 \cdot c_{u1} \cdot \left(\frac{d}{dr}c_{u1}\right) - \frac{2 \cdot c_{u1}^{2}}{r} dr$$

$$\Rightarrow c_{a2}^{2} - c_{a2.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u2} \cdot \left(\frac{d}{dr}c_{u2}\right) - \frac{2 \cdot c_{u2}^{2}}{r} dr$$

$$c_{a2} = \int_{r_{cp}}^{r} -2 \cdot c_{u2} \cdot \left(\frac{d}{dr}c_{u2}\right) - \frac{2 \cdot c_{u2}^{2}}{r} dr$$

$$c_{a2} = \sqrt{c_{a2.cp}^2 + \int_{r_{cp}}^{r} -2 \cdot c_{u2} \cdot \left(\frac{d}{dr}c_{u2}\right) - \frac{2 \cdot c_{u2}^2}{r}} c_{u2}$$

$$\begin{cases} c_{a1.cp}^2 + \int_{r_{cp}}^r -2 \, c_{1u}(r,m,A,B) \cdot \left(\frac{d}{dr} c_{1u}(r,m,A,B)\right) - \frac{2 \, c_{1u}(r,m,A,B)^2}{r} \, dr \\ substitute, m = -1 \end{cases} = \sqrt{c_{a1.cp}^2 - 2 \cdot A^2 \cdot r^2 + 2 \cdot A^2 \cdot r_{cp}^2 + 4 \cdot A \cdot B \cdot \ln(r) - 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 + 4 \cdot A \cdot B \cdot \ln(r) - 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 2 \cdot A^2 \cdot r^2 + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B \cdot \ln(r_{cp}^2 - 2 \cdot A^2 \cdot r^2) + 2 \cdot A^2 \cdot r_{cp}^2 - 4 \cdot A \cdot B \cdot \ln(r) + 4 \cdot A \cdot B$$

$$\sqrt{c_{a1.cp}^{2} + \int_{r_{cp}}^{r} -2 \, c_{1u}(r, m, A, B) \cdot \left(\frac{d}{dr} \, c_{1u}(r, m, A, B)\right) - \frac{2 \, c_{1u}(r, m, A, B)^{2}}{r} \, dr \, assume, \\ r_{cp} > 0, \\ r \ge 0, \\ m = 0 = \sqrt{2 \cdot A^{2} \cdot \ln \left(r_{cp}\right) - 2 \cdot A^{2} \cdot \ln \left(r\right) + c_{a1.cp}^{2} - \frac{2 \cdot A \cdot B}{r} + \frac{2 \cdot A \cdot B}{r_{cp}} }$$

$$\sqrt{c_{a2.cp}^{2} + \int_{r_{cp}}^{r} -2 \, c_{2u}(r, m, A, B) \cdot \left(\frac{d}{dr} \, c_{2u}(r, m, A, B)\right) - \frac{2 \, c_{2u}(r, m, A, B)^{2}}{r} \, dr \, assume, \\ r_{cp} > 0, \\ r \ge 0, \\ m = 0 = \sqrt{2 \cdot A^{2} \cdot \ln \left(r_{cp}\right) - 2 \cdot A^{2} \cdot \ln \left(r\right) + c_{a2.cp}^{2} + \frac{2 \cdot A \cdot B}{r} - \frac{2 \cdot A \cdot B}{r_{cp}} }$$

$$\sqrt{c_{a1.cp}^{2} + \int_{r_{cp}}^{r} -2 \, c_{1u}(r,m,A,B) \cdot \left(\frac{d}{dr} \, c_{1u}(r,m,A,B)\right) - \frac{2 \, c_{1u}(r,m,A,B)^{2}}{r}} \, dr \, assume, r_{cp} > 0, r \ge 0, -1 < m \le 1, m \ne 0 \\ = \sqrt{c_{a1.cp}^{2} + \frac{A \cdot (m-1) \cdot \left(A \cdot r_{1} \cdot r_{1} \cdot r_{1} \cdot r_{2} \cdot r_{2}$$

# Вывод общего ур-я профилирования Л цилиндрической и конической ступени Т

$$\frac{c_{1u} + c_{2u}}{2} \cdot r^{m} = const$$

$$const = \frac{c_{1u} + c_{2u}}{2} \cdot r^{m} = (3) = (1 - R)\omega \cdot r \cdot r^{m} = (1 - R)\omega \cdot r^{m+1} = (1 - R_{cp})\omega \cdot r_{cp}^{m+1} \implies (1 - R)\omega \cdot r = \frac{\left[\left(1 - R_{cp}\right) \cdot \omega \cdot r_{cp}^{m+1}\right]}{r^{m}}$$

$$A = \left[\left(1 - R_{cp}\right) \cdot \omega \cdot r_{cp}^{m+1}\right]$$

$$(1 - R)\omega \cdot r = \frac{\left[\left(1 - R_{cp}\right) \cdot \omega \cdot r_{cp}^{m+1}\right]}{r^{m}}$$

$$A = \left[ \left( 1 - R_{cp} \right) \cdot \omega \cdot r_{cp}^{m+1} \right]$$

(2) 
$$L_u = c_{2u} \cdot u_2 + c_{1u} \cdot u_1 = (c_{2u} + c_{1u})u$$

$$u = \omega \cdot r$$

$$\mathbf{L}_{u} = \mathbf{c}_{2u} \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{2} + \mathbf{c}_{1u} \cdot \boldsymbol{\omega} \cdot \mathbf{r}_{1} = \left(\mathbf{c}_{2u} + \mathbf{c}_{1u}\right) \boldsymbol{\omega} \cdot \mathbf{r}_{1}$$

$$c_{2u} = c_{1u} + \frac{L_u}{\omega \cdot r}$$

$$c_{1u} = c_{2u} + \frac{L_{u}}{\omega \cdot r}$$

$$c_{2u} = c_{1u} + \frac{L_{u}}{\omega \cdot r}$$

$$c_{1u} = (1 - R) \cdot \omega \cdot r + \frac{L_{u}}{2 \cdot \omega \cdot r} = (1 - R) \cdot \omega \cdot r + \frac{\left(\frac{L_{u}}{2 \cdot \omega}\right)}{r}$$

$$B = \left(\frac{L_{u}}{2 \cdot \omega}\right)$$

$$B = \left(\frac{L_u}{2 \cdot \omega}\right)$$

$$\operatorname{Color}(r, m, A, B) = \frac{(A)}{r} + \frac{(B)}{r}$$

$$c_{\text{NM}}(r, m, A, B) = -\frac{A}{r} + \frac{(B)}{r}$$

(3) 
$$R = 1 - \frac{c_{1u} - c_{2u}}{2 \cdot u}$$

$$u = \omega \cdot r$$

$$R = 1 - \frac{c_{1u} - c_{2u}}{2 \cdot \omega \cdot r}$$

$$c_{1u} = (1 - R) \cdot 2 \cdot \omega \cdot r - c_{2u}$$

$$c_{2u} = -(1 - R) \cdot 2 \cdot \omega \cdot r - c_{1u}$$

$$c_{2u} = -(1 - R) \cdot \omega \cdot r + \frac{L_u}{2 \cdot \omega \cdot r} = -(1 - R) \cdot \omega \cdot r + \frac{\left(\frac{L_u}{2 \cdot \omega}\right)}{r}$$

Работа сил трения: 
$$L_{\text{тр}} = \left(\frac{1}{\varphi^2} - 1\right) \cdot \frac{c_1^2}{2} = \frac{c_1^2}{2 \cdot \varphi^2} - \frac{c_1^2}{2}$$

$$L_{\Gamma \mathcal{U} \mathcal{I}} = \left(\frac{1}{\varphi^2} - 1\right) \cdot \frac{c_1^2}{2} + \left(\frac{1}{\psi^2} - 1\right) \cdot \frac{w_2^2}{2} = \left(\frac{1}{\varphi^2} - 1\right) \cdot \frac{c_{a1}^2 + c_{u1}^2}{2} + \left(\frac{1}{\psi^2} - 1\right) \cdot \frac{\left(c_{2u} + u_2\right)^2 + c_{2a}^2}{2}$$

Ур-е радиадьного равновесия: 
$$\frac{1}{0} \cdot \frac{d}{dr} P = \frac{c_u^2}{r}$$

$$\frac{1}{\rho} \cdot \frac{d}{dr} P = \frac{c_u^2}{r}$$

$$\frac{1}{\rho} \cdot dP + d \left( \frac{c_1^2}{2} \right) + d \left( L_{Tp} \right) = d \left( H_T \right)$$

$$\begin{split} \frac{1}{\rho} \cdot \mathrm{dP} + \mathrm{d} \left( \frac{c_1^2}{2} \right) + \mathrm{d} \big( L_{\mathrm{T}p} \big) &= \mathrm{d} \big( H_{\mathrm{T}} \big) \\ \\ \frac{1}{\rho} \cdot \mathrm{dP} + \mathrm{d} \left( \frac{c_2^2}{2} \right) + \mathrm{d} \big( L_{\mathrm{\Gamma M} \Pi} \big) + \mathrm{d} \big( L_{\mathrm{CT}} \big) &= \mathrm{d} \big( H_{\mathrm{T}} \big) \end{split} \qquad 0 = \frac{c_1^2}{2} + \int_0^1 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_2^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{CT}} \\ \\ 0 = \frac{c_2^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{CT}} \\ \\ 0 = \frac{c_2^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{CT}} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{CT}} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} + L_{\mathrm{T} \mu} \\ \\ 0 = \frac{c_1^2}{2} + \int_0^2 \frac{1}{\rho} \, \mathrm{dP} + L_{\mathrm{T} \mu} + L_{\mathrm{T}$$

$$0 = \frac{c_1^2}{2} + \int_0^1 \frac{1}{\rho} \, dP + L_{TP}$$

$$0 = \frac{c_2^2}{2} + \int_0^2 \frac{1}{\rho} dP + L_{\Gamma \text{ИД}} + L_{\text{C}}$$

Допущения:

$$H_{T}(r) = const$$
  $\Rightarrow$   $\frac{d}{dr}H_{T}(r) =$ 

$$\varphi(\mathbf{r}) = \mathbf{const}$$
  $\frac{\mathrm{d}}{\mathrm{d}\mathbf{r}}\varphi(\mathbf{r}) = 0$ 

$$\frac{d}{dr}\psi(r) = const$$
  $\frac{d}{dr}\psi(r) = 0$ 

Вывол:

$$0 = \frac{c_1^2}{2} + \int_0^1 \frac{1}{\rho} \, dP + L_{Tp} = \frac{c_1^2}{2} + \int_0^1 \frac{1}{\rho} \, dP + \frac{c_1^2}{2 \cdot \phi^2} - \frac{c_1^2}{2} = \frac{c_1^2}{2 \cdot \phi^2} + \int_0^1 \frac{1}{\rho} \, dP = \frac{c_{a1}^2 + c_{u1}^2}{2 \cdot \phi^2} + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}\right) + \int_0^1 \frac{1}{\rho} \, dP = \frac{1}{\phi^2} \cdot \left(\frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2} + \frac{c_{u1}^2}{2}$$

$$0 = \frac{d}{dr} \left[ \frac{1}{\varphi^2} \cdot \left( \frac{c_{a1}^2}{2} + \frac{c_{u1}^2}{2} \right) + \int_0^1 \frac{1}{\rho} dP \right] = \frac{1}{\varphi^2} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{1}{\rho} \cdot \frac{d}{dr} P = \frac{1}{\varphi^2} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} \cdot \left( c_{u1} \cdot \frac{d}{dr} c_{u1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right)$$

$$\frac{1}{\phi^2} \cdot \left( c_{a1} \cdot \frac{d}{dr} c_{a1} + c_{u1} \cdot \frac{d}{dr} c_{u1} \right) + \frac{c_{u1}^2}{r} = 0 \qquad \qquad \frac{d}{dr} \left( \frac{c_{a1}^2}{2} \right) = -c_{u1} \cdot \left( \frac{d}{dr} c_{u1} \right) - \phi^2 \cdot \frac{c_{u1}^2}{r} \qquad \qquad \frac{d}{dr} c_{a1}^2 = -2 \cdot c_{u1} \cdot \left( \frac{d}{dr} c_{u1} \right) - 2 \cdot \phi^2 \cdot \frac{c_{u1}^2}{r} = 0$$

$$\int_{r_{cp}}^{r} \frac{d}{dr} c_{a1}^{2} dr = c_{a1}^{2} - c_{a1.cp}^{2} = \int_{r_{cp}}^{r} -2 \cdot c_{u1} \cdot \left(\frac{d}{dr} c_{u1}\right) - 2 \cdot \phi^{2} \cdot \frac{c_{u1}^{2}}{r} dr$$

$$c_{a1} = \int_{r_{cp}}^{r} -2 \cdot c_{u1} \cdot \left(\frac{d}{dr} c_{u1}\right) - 2 \cdot \phi^{2} \cdot \frac{c_{u1}^{2}}{r} dr$$
(c.a1)

$$0 = \frac{d}{dr}c_{a2}^{2} + \frac{d}{dr}c_{u2}^{2} + \left(\frac{1}{\phi^{2}} - 1\right)\cdot\psi^{2}\cdot\left(\frac{d}{dr}c_{a1}^{2} + \frac{d}{dr}c_{u1}^{2}\right) + \psi^{2}\cdot\frac{2\cdot c_{u2}^{2}}{r} + \left(1 - \psi^{2}\right)\cdot\frac{d}{dr}\left(2\cdot c_{u2}\cdot u + u^{2}\right)$$

$$\frac{d}{dr}c_{a2}^{2} = \frac{d}{dr}c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right)\cdot\psi^{2}\cdot\left(\frac{d}{dr}c_{a1}^{2} + \frac{d}{dr}c_{u1}^{2}\right) - \psi^{2}\cdot\frac{2\cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right)\cdot\frac{d}{dr}\left(2\cdot c_{u2}\cdot u + u^{2}\right)$$

$$\frac{d}{dr}c_{a2}^{2} = \frac{d}{dr}c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right)\cdot\psi^{2}\cdot\left(\frac{d}{dr}c_{a1}^{2} + \frac{d}{dr}c_{u1}^{2}\right) - \psi^{2}\cdot\frac{2\cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right)\cdot\frac{d}{dr}\left(2\cdot c_{u2}\cdot u + u^{2}\right)$$

$$\int_{r_{cp}}^{r} \frac{d}{dr} c_{a2}^{2} dr = c_{a2}^{2} - c_{a2.cp}^{2} = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{a1}^{2} + \frac{d}{dr} c_{u1}^{2}\right) - \psi^{2} \cdot \frac{2 \cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{a1}^{2} + \frac{d}{dr} c_{u1}^{2}\right) - \psi^{2} \cdot \frac{2 \cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{a1}^{2} + \frac{d}{dr} c_{u1}^{2}\right) - \psi^{2} \cdot \frac{2 \cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u1}^{2} + \frac{d}{dr} c_{u1}^{2}\right) - \psi^{2} \cdot \frac{2 \cdot c_{u2}^{2}}{r} - \left(1 - \psi^{2}\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u1}^{2} + \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u1}^{2} + \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u1}^{2} + \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u1}^{2} + \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{1}{\phi^{2}} - 1\right) \cdot \psi^{2} \cdot \left(\frac{d}{dr} c_{u2}^{2} - \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^{2}\right] dr \\ = \int_{r_{cp}}^{r} \frac{d}{dr} c_{u2}^{2} - \left(\frac{d}{dr} c_{u2}^{2} - \frac{d}{dr} c_{u2}^{2}\right) - \psi^{2} \cdot \frac{d}{dr} c_{u2}^{2} - \frac{d}{dr}$$

$$c_{a2} = \sqrt{c_{a2.cp}^2 + \int_{r_{cp}}^r \frac{d}{dr} c_{u2}^2 - \left(\frac{1}{\varphi^2} - 1\right) \cdot \psi^2 \cdot \left(\frac{d}{dr} c_{a1}^2 + \frac{d}{dr} c_{u1}^2\right) - \psi^2 \cdot \frac{2 \cdot c_{u2}^2}{r} - \left(1 - \psi^2\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^2\right] dr} = \left[c_{a2.cp}^2 + \int_{r_{cp}}^r \frac{d}{dr} c_{u2}^2 - \left(\frac{1}{\varphi^2} - 1\right) \cdot \psi^2 \cdot \left(\frac{d}{dr} c_{u1}\right) - 2 \cdot \varphi^2 \cdot \frac{c_{u1}^2}{r} dr\right] + \frac{d}{dr} c_{u1}^2 - \psi^2 \cdot \frac{2 \cdot c_{u2}^2}{r} - \left(1 - \psi^2\right) \cdot \frac{d}{dr} \left[2 \cdot c_{u2} \cdot \omega \cdot r + (\omega \cdot r)^2\right] dr$$

(c.a2)

$$\begin{bmatrix} a_{1} a_{2}^{2} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x, m, A, B) \left( \frac{d}{d} v_{1} d(x, m, A, B) - 2 v_{2}^{2} \frac{v_{1} d(x, m, A, B)}{c_{0} d(x_{0}, m_{0}, A, B)} \right) \\ = a_{0} \begin{bmatrix} a_{1} a_{2}^{2} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x, m, A, B) \left( \frac{d}{d} v_{1} d(x, m, A, B) - 2 v_{2}^{2} \frac{v_{1} d(x, m, A, B)}{c_{0}} \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x, m, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x, m, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \right) \\ = a_{0} \begin{bmatrix} a_{0} a_{1} + \int_{\tau_{0}}^{\tau_{0}} -2 v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A, B) \left( \frac{d}{d} v_{1} d(x_{0}, m_{0}, A,$$

$$\frac{1}{m \cdot r_{cp}^{2-2 \cdot m} + A^{2} \cdot \phi^{2} \cdot r_{cp}^{2} \cdot \left(\frac{1}{r^{2}}\right)^{m} - A^{2} \cdot m^{2} \cdot r_{cp}^{2} \cdot \left(\frac{1}{r^{2}}\right)^{m} - \frac{B^{2} \cdot m^{2} \cdot r_{cp}^{2}}{r^{2}} + 2 \cdot A \cdot B \cdot m^{2} \cdot r_{cp}^{1-m} - A^{2} \cdot m \cdot r_{cp}^{2} \cdot \left(\frac{1}{r^{2}}\right)^{m} - \frac{B^{2} \cdot m \cdot r_{cp}^{2}}{r^{2}} - \frac{2 \cdot A \cdot B \cdot m \cdot r_{cp}^{2}}{r^{2}} - \frac{2 \cdot A \cdot B \cdot m^{2} \cdot r_{cp}^{2}}{r^{2}} -$$

$$\frac{e^{-2\pi i} + A^2 \cdot \varphi^2 \cdot r_{cp}^2 \cdot \left(\frac{1}{2}\right)^m - A^2 \cdot m^2 \cdot r_{cp}^2 \cdot \left(\frac{1}{2}\right)^m - \frac{B^2 \cdot m^2 \cdot r_{cp}^2}{r^2} - 2 \cdot A \cdot B \cdot m^2 \cdot r_{cp}^{1-m} - A^2 \cdot m \cdot r_{cp}^2 \cdot \left(\frac{1}{2}\right)^m - \frac{B^2 \cdot m \cdot r_{cp}^2}{r^2} + \frac{2 \cdot A \cdot B \cdot m \cdot r_{cp}^2}{r^2} + \frac{2 \cdot A \cdot B \cdot m \cdot r_{cp}^2}{r^2} + \frac{2 \cdot A \cdot B \cdot m \cdot r_{cp}^2}{r^2} + \frac{2 \cdot A \cdot B \cdot m^2 \cdot r_{cp}^2}{r^2} + \frac{2 \cdot A \cdot B \cdot m$$

r<sub>cp</sub>