Arrows for Parallel Computations

MARTIN BRAUN University Bayreuth, 95440 Bayreuth, Germany PHIL TRINDER Glasgow University, Glasgow, G12 8QQ, Scotland and OLEG LOBACHEV University Bayreuth, 95440 Bayreuth, Germany

Abstract

Arrows are a general interface for computation and therefore form an alternative to Monads for API design. We express parallelism using this concept in a novel way: We define an arrows-based language for parallelism and implement it using multiple parallel Haskells. In this manner we are able to bridge across various parallel Haskells.

Additionally, our way of writing parallel programs has the benefit of being portable across flavours of parallel Haskells. Furthermore, as each parallel computation is an arrow, which means that they can be composed and transformed as such. We introduce some syntactic sugar to provide parallelism-aware arrow combinators.

To show that our arrow-based language is on par with the existing parallel languages, we also define several parallel skeletons with our framework. Benchmarks show that our framework does not induce too much overhead performance-wise. OL: Summarize conclusions

MB: Jedes Kapitel soll einmal ins Abstract. Conclusions sollen mit ins Abstract

Contents

1	Intr	oduction	2
2	Bac	kground	3
	2.1	Short introduction to parallel Haskells	3
	2.2	Arrows	6
3	Rela	ated Work	7
4	Para	allel Arrows	9
	4.1	The ArrowParallel typeclass	9
	4.2	ArrowParallel instances	10
	4.3	Extending the Interface	11
5	Futi	ures	12
6	Maj	p-based Skeletons	14
7	Topological Skeletons		16
	7.1	Parallel pipe	16
	7.2	Ring skeleton	18
	7.3	Torus skeleton	19
8	Ben	chmarks	21

2 M. Braun, P. Trinder, and O. Lobachev

9	Conclusion	
	9.1 Future Work	22
A	Utility Arrows	27
В	Omitted Function Definitions	28
C	Syntactic Sugar	29

Contents

1 Introduction

OL: todo, reuse 5.5, and more

MB: Haskell is Spielwiese für Parallelität; verschiedene Ansätze (Par, Multicore, Eden); Orthogonale Ansätze; Verwenden höchstens eine Monade - manchmal auch nur intern; Wir wollen Parallelität mit Arrows abbilden, was noch niemand gemacht hat; Statt einer eigenen Implementierung definieren wir ein "shallow embedded DSL" (ACHTUNG, ist das der richtige Name? effektiv API); Umsetzung mit verschiedenen parallelen Haskells; We tame the zoo of parallel Haskells und vergewissern uns dass es nicht viel Overhead bringt

blablabla arrows, parallel, haskell.

Contribution OL: HIT HERE REALLY STRONG

MB: different, how? We wrap parallel Haskells inside of our ArrowParallel interface, but why do we aim to abstract parallelism this way and what does this approach do better than the other parallel Haskells?

- Arrow DSL benefits: With the ArrowParallel typeclass we do not lose any benefits of using arrows as parEvalN is a yet another Arrow combinator. The resulting Arrow can be used in the same way a potential serial version could be used. This is a big advantage of this approach, especially compared to the Monad solutions as we do not introduce any new types. We can just 'plug' in parallel parts into sequential Arrow-based programs without having to change anything.
- Abstraction: With the ArrowParallel typeclass, we abstract all parallel implementation logic away from the business logic. This leaves us in the beautiful situation of being able to write our code against the interface of the typeclass without being bound to any parallel Haskell. So as an example, during development, we can run the program in a simple GHC-compiled variant and afterwards deploy it on a cluster by converting it into an Eden version, by just replacing the actual ArrowParallel instance.

Structure The remaining text is structures as follows. Section 2 briefly introduces known parallel Haskell flavours (Sec. 2.1) and gives an overview of Arrows to the reader (Sec. 2.2). Section 3 discusses related work. Section 4 defines Parallel Arrows and presents a basic

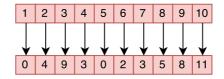


Figure 1: Schematic illustration of *parEvalN*.

interface. Section 5 defines Futures for Parallel Arrows, this concept enables better communication. Section 6 presents some basic algorithmic skeletons in our newly defined dialect: parallel map with and without load balancing. More advanced skeletons are showcased in Section 7 (pipe, ring, torus). Section 8 shows the benchmark results. Section 9 discusses future work and concludes.

2 Background

2.1 Short introduction to parallel Haskells

There are already several ways to write parallel programs in Haskell. As we base our parallel arrows on existing parallel Haskells, we will now give a short introduction to the ones we use as backends in this paper.

In its purest form, parallel computation (on functions) can be looked at as the execution of some functions $a \to b$ in parallel or parEvalN:: $[a \to b] \to [a] \to [b]$, as also Figure 1 symbolically shows. As a demonstration, we implement here the non-Arrows parEvalN in multiple parallel Haskells.

2.1.1 Multicore Haskell

Multicore Haskell (Marlow et al., 2009; Trinder et al., 1998) is a way to do parallel processing found in standard GHC. It ships with parallel evaluation strategies for several types which can be applied with using :: $a \rightarrow Strategy \ a \rightarrow a$. Let:

```
parEvalN :: (NFData\ b) \Rightarrow [a \rightarrow b] \rightarrow [a] \rightarrow [b]
parEvalN fs \ as = let \ bs = zipWith \ (\$) fs \ as
   in (bs 'using' parList rdeepseq) 'pseq' bs
```

In the above definition of parEvalN we just apply the list of functions $[a \rightarrow b]$ to the list of inputs [a] by zipping them with the application operator \$. We then evaluate this lazy list [b]according to a Strategy [b] with the using:: $a \to Strategy \ a \to a$ operator. We construct this strategy with parList:: Strategy $a \to Strategy[a]$ and rdeepseq:: NFData $a \Rightarrow Strategy[a]$ where the latter is a strategy which evalutes to normal form. To ensure that programs that use parEvalN have the correct evaluation order, we annotate the computation with $pseq: a \rightarrow b \rightarrow b$ which forces the compiler to not reorder multiple parEvalN computations.

¹ Multicore Haskell on Hackage is available under https://hackage.haskell.org/package/ parallel-3.2.1.0, compiler support is integrated in the stock GHC.

4

M. Braun, P. Trinder, and O. Lobachev

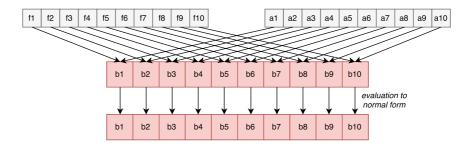


Figure 2: Dataflow of the Multicore Haskell parEvalN version.

This is particularly necessary in circular communication topologies like in the torus or ring (Chap. 7), where a wrong execution order would result in deadlock scenarios when executed without pseq. Fig. 2 shows a visual representation of this code.

2.1.2 Par Monad

The Par Monad² introduced by Marlow et al. (2011), is a Monad designed for composition of parallel programs. Let:

```
parEvalN :: (NFData\ b) \Rightarrow [a \rightarrow b] \rightarrow [a] \rightarrow [b]
parEvalN fs as = runPar $
   (sequenceA \$ map (spawnP) \$ zipWith (\$) fs as) \gg mapM get
```

The Par Monad version of our parallel evaluation function parEvalN is defined by zipping the list of $[a \rightarrow b]$ with the list of inputs [a] with the application operator \$ just like with Multicore Haskell. Then, we map over this not yet evaluated lazy list of results [b] with $spawnP: NFData \ a \Rightarrow a \rightarrow Par \ (IVar \ a)$ to transform them to a list of not yet evaluated forked away computations [Par (IVar b)], which we convert to Par [IVar b] with sequenceA. We wait for the computations to finish by mapping over the *IVar b* values inside the *Par* Monad with get. This results in Par[b]. We execute this process with runPar to finally get [b]. Fig. 3 shows a graphical representation.

2.1.3 Eden

Eden (Loogen et al., 2005; Loogen, 2012) is a parallel Haskell for distributed memory and comes with a MPI and a PVM backends.³ It is targeted towards clusters, but also functions well in a shared-memory setting with a further simple backend. However, in contrast to many other parallel Haskells, in Eden each process has its own heap. This seems to be a waste of memory, but with distributed programming paradigm and individual GC per process, Eden yields good performance results also on multicores (Berthold et al., 2009a; Aswad et al., 2009).

² It can be found in the monad-par package on hackage under https://hackage.haskell.org/ package/monad-par-0.3.4.8/.

See also http://www.mathematik.uni-marburg.de/~eden/ and https://hackage. ${\tt haskell.org/package/eden modules-1.2.0.0/}.$

Arrows for Parallel Computations

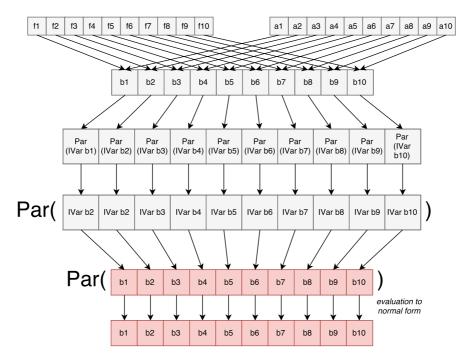


Figure 3: Dataflow of the Par Monad parEvalN version.

While Eden also comes with a Monad PA for parallel evaluation, it also ships with a completely functional interface that includes a spawnF:: $(Trans\ a, Trans\ b) \Rightarrow [a \rightarrow b] \rightarrow [a] \rightarrow [b]$ function that allows us to define parEvalN directly:

```
parEvalN :: (Trans\ a, Trans\ b) \Rightarrow [a \rightarrow b] \rightarrow [a] \rightarrow [b]

parEvalN = spawnF
```

Eden TraceViewer. To comprehend the efficiency and the lack thereof in a parallel program, an inspection of its execution is extremely helpful. While some large-scale solutions exist (Geimer *et al.*, 2010), the parallel Haskell community mainly utilises the tools Threadscope (Wheeler & Thain, 2009) and Eden TraceViewer⁴ (Berthold & Loogen, 2007). In the next sections we will present some *trace visualizations*, the post-mortem process diagrams of Eden processes and their activity.

The trace visualizations are color-coded. In such a visualization (Fig. 13), the *x* axis shows the time, the *y* axis enumerates the machines and processes. The visualization shows a running process in green, a blocked process is red. If the process is 'runnable', i.e. it may run, but does not, it is yellow. The typical reason for thus is GC. An inactive machine, where no processes are started yet, or all are already terminated, shows as a blue bar. A comminication from one process to another is represented with a black arrow. A stream

⁴ See http://hackage.haskell.org/package/edentv on Hackage for the last available version of Eden TraceViewer.

```
class Arrow\ arr\ where arr::(a \rightarrow b) \rightarrow arr\ a\ b (>>>)::arr\ a\ b \rightarrow arr\ b\ c \rightarrow arr\ a\ c first::arr\ a\ b \rightarrow arr\ (a,c)\ (b,c) instance Arrow\ (\rightarrow) where arr\ f=f f>>>> g=g\circ f first\ f=\lambda(a,c) \rightarrow (f\ a,c) data Kleisli\ m\ a\ b=Kleisli\ \{run::a\rightarrow m\ b\} instance Monad\ m\Rightarrow Arrow\ (Kleisli\ m) where arr\ f=Kleisli\ (return\circ f) f>>>> g=Kleisli\ (\lambda a\rightarrow f\ a>=g) first\ f=Kleisli\ (\lambda(a,c)\rightarrow f\ a>=\lambda b\rightarrow return\ (b,c))
```

Figure 4: The definition of Arrow type class and its two most typical instances.

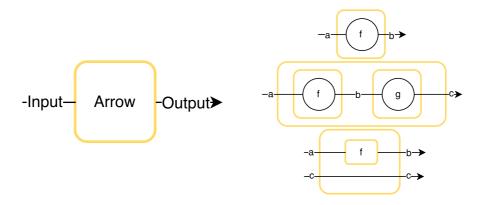


Figure 5: Schematic depiction of Arrow (left) and its basic combinators *arr*, >>> and *first* (right).

of communications, e.g. a transmitted list is shows as a dark shading between sender and receiver processes.

2.2 Arrows

Arrows were introduced by Hughes (2000) as a general interface for computation. An Arrow $arr\ a\ b$ represents a computation that converts an input a to an output b. This is defined in the Arrow type class shown in Fig. 4. Its arr operation is used to lift an ordinary function to the specified arrow type, similarly to the monadic return. The >>> operator is analogous to the monadic composition >>= and combines two arrows $arr\ a\ b$ and $arr\ b\ c$ by "wiring" the outputs of the first to the inputs to the second to get a new arrow $arr\ a\ c$. Lastly, the first operator takes the input arrow from b to c and converts it into an arrow on pairs with the second argument untouched. It allows us to to save input across arrows. Figure 5 shows a

graphical representation of the basic Arrow combinators. The most prominent instances of this interface are regular functions (\rightarrow) and the Kleisli type (Fig. 4).

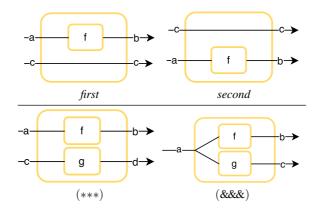


Figure 6: Visual depiction of syntactic sugar for Arrows.

With this typeclass in place, Hughes also defined some syntactic sugar (Fig. 6): The combinators *second*, *** and &&&. The combinator *second* is the mirrored version of *first* (Appendix A). The *** function combines *first* and *second* to handle two inputs in one arrow, is defined as

```
(***)::Arrow arr \Rightarrow arr a b \rightarrow arr c d \rightarrow arr (a,c) (b,d) f *** g = first f >>> second g
```

while the &&& combinator, that constructs an arrow which outputs two different values like ***, but takes only one input, is:

```
(&&&)::Arrow arr \Rightarrow arr\ a\ b \rightarrow arr\ a\ c \rightarrow a\ a\ (b,c)
f &&& g = arr\ (\lambda a \rightarrow (a,a)) >>> (f *** g)
```

A first short example given by Hughes on how to use arrows is addition with arrows:

```
add::Arrow arr \Rightarrow arr \ a \ Int \rightarrow arr \ a \ Int \rightarrow arr \ a \ Int add \ f \ g = (f \&\&\& g) >>> arr \ (\lambda(u,v) \rightarrow u+v)
```

The more restrictive interface of Arrows allows for more elaborate composition and transformation combinators—a Monad can be *anything*, an Arrow is a process of doing something, a *computation*. One of the major problems in parallel computing is, however, composition of parallel processes.

3 Related Work

Parallel Haskells. Of course, the three parallel Haskell flavours we have presented above: the GpH (Trinder *et al.*, 1996, 1998) parallel Haskell dialect and its multicore version (Marlow *et al.*, 2009), the *Par* Monad (Marlow *et al.*, 2011; Foltzer *et al.*, 2012), and Eden (Loogen *et al.*, 2005; Loogen, 2012) are related to this work. We use these languages as backends; our DSL can switch from one to other at user's command.

HdpH (Maier *et al.*, 2014; Stewart *et al.*, 2016) is an extension of *Par* Monad to heterogeneous clusters. LVish (Kuper *et al.*, 2014) is a communication-centred extension of *Par* Monad. Further parallel Haskell approaches include pH (Nikhil & Arvind, 2001), research work done on distributed variants of GpH (Trinder *et al.*, 1996; Aljabri *et al.*, 2014, 2015), and low-level Eden implementation (Berthold, 2008; Berthold *et al.*, 2016). Skeleton composition (Dieterle *et al.*, 2016), communication (Dieterle *et al.*, 2010a), and generation of process networks (Horstmeyer & Loogen, 2013) are recent in-focus research topics in Eden. This also includes the definitions of new skeletons (Hammond *et al.*, 2003; Berthold & Loogen, 2006; Berthold *et al.*, 2009b,c; Dieterle *et al.*, 2010b; de la Encina *et al.*, 2011; Dieterle *et al.*, 2013; Janjic *et al.*, 2013).

More different approaches include data parallelism (Chakravarty *et al.*, 2007; Keller *et al.*, 2010), GPU-based approaches (Mainland & Morrisett, 2010; Svensson, 2011), software transactional memory (Harris *et al.*, 2005; Perfumo *et al.*, 2008). The Haskell–GPU bridge Accelerate (Chakravarty *et al.*, 2011; Clifton-Everest *et al.*, 2014; McDonell *et al.*, 2015) deserves a special mention. Accelerate is completely orthogonal to our approach. Marlow authored a recent book in 2013 on parallel Haskells.

Algorithmic skeletons. Algorithmic skeletons were introduced by Cole (1989). Early publications on this topic include (Darlington *et al.*, 1993; Botorog & Kuchen, 1996; Danelutto *et al.*, 1997; Gorlatch, 1998; Lengauer *et al.*, 1997). Rabhi & Gorlatch (2003) consolidated early reports on high-level programming approaches. The effort is ongoing, including topological skeletons (Berthold & Loogen, 2006), special-purpose skeletons for computer algebra (Berthold *et al.*, 2009c; Lobachev, 2011, 2012; Janjic *et al.*, 2013), iteration skeletons (Dieterle *et al.*, 2013). The idea of Linton *et al.* (2010) is to use a parallel Haskell to orchestrate further software systems to run in parallel. Dieterle *et al.* (2016) compare the composition of skeletons to stable process networks.

Arrows. Arrows were introduced by Hughes (2000), basically they are a generalised function arrow \rightarrow . Hughes (2005a) presents a tutorial on Arrows. Some theoretical details on Arrows (Jacobs et al., 2009; Lindley et al., 2011; Atkey, 2011) are viable. Paterson (2001) introduced a new notation for Arrows. Arrows have applications in information flow research (Li & Zdancewic, 2006, 2010; Russo et al., 2008), invertible programming (Alimarine et al., 2005), and quantum computer simulation (Vizzotto et al., 2006). But probably most prominent application of Arrows is Arrow-based functional reactive programming, AFRP (?Hudak et al., 2003; ?). MB: reference not found!!! Liu et al. (2009) formally define a more special kind of Arrows that capsule the computation more than regular arrows do and thus enable optimizations. Their approach would allow parallel composition, as their special Arrows would not interfere with each other in concurrent execution. In contrast, we capture a whole parallel computation as a single entity: our main instantiation function parEvalN makes a single (parallel) Arrow out of list of Arrows. Huang et al. (2007) utilise Arrows for parallelism, but strikingly different from our approach. They basically use Arrows to orchestrate several tasks in robotics. We, however, propose a general interface for parallel programming, while remaining completely in Haskell.

Other languages. Although this work is centred on Haskell implementation of arrows, it is applicable to any functional programming language where parallel evaluation and arrows can be defined. Experiments with our approach in Frege language⁵ (which is basically Haskell on the JVM) were quite successful. However, it is beyond the scope of this work.

Achten *et al.* (2004, 2007) use an arrow implementation in Clean for better handling of typical GUI tasks. Dagand *et al.* (2009) used arrows in OCaml in the implementation of a distributed system.

4 Parallel Arrows

Arrows are a general interface to computation. Here we introduce special Arrows as general interface to *parallel computations*. First, we present the interface and explain the reasonings behind it. Then, we discuss some implementations using exisiting parallel Haskells. Finally, we explain why using Arrows for expressing parallelism is beneficial.

4.1 The ArrowParallel typeclass

A parallel computation (on functions) in its purest form can be seen as execution of some functions $a \to b$ in parallel, as our parEvalN prototype shows (Sec. 2.1). Translating this into arrow terms gives us a new operator parEvalN that lifts a list of arrows $[arr\ a\ b]$ to a parallel arrow $arr\ [a]\ [b]$. This combinator is similar to our utility function listApp from Appendix A, but does parallel instead of serial evaluation.

```
parEvalN :: (Arrow arr) \Rightarrow [arr a b] \rightarrow arr [a] [b]
```

With this definition of *parEvalN*, parallel execution is yet another arrow combinator. But as the implementation may differ depending on the actual type of the arrow *arr* and we want this to be an interface for different backends, we introduce a new typeclass *ArrowParallel arr a b*:

```
class Arrow \ arr \Rightarrow Arrow Parallel \ arr \ a \ b where parEvalN :: [arr \ a \ b] \rightarrow arr \ [a] \ [b]
```

Sometimes parallel Haskells require or allow for additional configuration parameters, e.g. an information about the execution environment or the level of evaluation (weak head normal form vs. normal form). For this reason we also introduce an additional *conf* parameter to the function. We also do not want *conf* to be a fixed type, as the configuration parameters can differ for different instances of *ArrowParallel*.

```
class Arrow \ arr \Rightarrow Arrow Parallel \ arr \ a \ b \ conf where parEvalN :: conf \rightarrow [arr \ a \ b] \rightarrow arr \ [a] \ [b]
```

We do not require the *conf* parameter in every implementation. If it is not needed, we usually just default the *conf* type parameter to () and even blank it out in the parameter list of the implemented *parEvalN*.

⁵ GitHub project page at https://github.com/Frege/frege

```
data Conf a = Conf (Strategy a)
instance (NFData b, ArrowApply arr, ArrowChoice arr) \Rightarrow ArrowParallel arr a b () where
  parEvalN \_fs =
    listApp fs >>>
    arr (withStrategy (parList rdeepseq)) &&& arr id >>>
    arr (uncurry pseq)
```

Figure 7: Fully evaluating ArrowParallel instance for the Multicore Haskell backend.

```
instance (NFData b, ArrowApply arr, ArrowChoice arr) \Rightarrow
  ArrowParallel arr a b (Conf b) where
  parEvalN (Conf strat) fs =
     listApp fs >>>
     arr (withStrategy (parList strat)) &&& arr id >>>
     arr (uncurry pseq)
```

Figure 8: Configurable ArrowParallel instance for the Multicore Haskell backend.

4.2 ArrowParallel instances

4.2.1 Multicore Haskell

The Multicore Haskell implementation of ArrowParallel is implemented in a straightforward manner by using *listApp* (Appendix A) combined with the *withStrategy*:: Strategy $a \rightarrow a \rightarrow a$ and $pseq: a \rightarrow b \rightarrow b$ combinators from Multicore Haskell, where with Strategy is the same as $using :: a \rightarrow Strategy \ a \rightarrow a$ but with flipped parameters. For most cases a fully evaluating version like in Fig. 7 would probably suffice, but as the Multicore Haskell interface allows the user to specify the level of evaluation to be done via the Strategy interface, our DSL should allow for this. We therefore introduce the Conf a data-type that simply wraps a Strategy a.

4.2.2 Par Monad

OL: introduce a newcommand for par-monad, "arrows", "parrows" and replace all mentions to them to ensure uniform typesetting done!, we write Arrows. also "Monad"? done! The Par Monad implementation (Fig. 9) makes use of Haskells laziness and Par Monad's spawnP:: NFData $a \Rightarrow a \rightarrow Par$ (IVar a) function. The latter forks away the computation of a value and returns an *IVar* containing the result in the *Par* Monad.

We therefore apply each function to its corresponding input value with and then fork the computation away with arr spawnP inside a zipWithArr (Fig. A 3) call. This yields a list [Par(IVar b)], which we then convert into Par[IVar b] with arr sequence A. In order to wait for the computation to finish, we map over the IVars inside the Par Monad with arr (>= mapM get). The result of this operation is a Par [b] from which we can finally remove the Monad again by running arr runPar to get our output of [b].

17:35

```
instance (NFData b, ArrowApply arr, ArrowChoice arr) \Rightarrow
  ArrowParallel arr a b conf where
     parEvalN _fs =
       (arr \$ \lambda as \rightarrow (fs, as)) >>>
       zipWithArr (app >>> arr spawnP) >>>
       arr sequenceA >>>
       arr (> = mapM get) >>>
       arr runPar
```

Figure 9: ArrowParallel instance for the Par Monad backend.

```
4.2.3 Eden
```

For both the Multicore Haskell and Par Monad implementations we could use general instances of ArrowParallel that just require the ArrowApply and ArrowChoice typeclasses. With Eden this is not the case as we can only spawn a list of functions and we cannot extract simple functions out of arrows. While we could still manage to have only one class in the module by introducing a typeclass:

```
class (Arrow arr) \Rightarrow Arrow Unwrap arr where
   arr\ a\ b \rightarrow (a \rightarrow b)
```

However, we avoid doing so for aesthetic resons. For now, we just implement ArrowParallel for normal functions:

```
instance (Trans\ a, Trans\ b) \Rightarrow ArrowParallel\ (\rightarrow)\ a\ b\ conf\ where
   parEvalN \_fs \ as = spawnF \ fs \ as
and the Kleisli type:
   instance (Monad m, Trans a, Trans b, Trans (m b)) \Rightarrow
      ArrowParallel (Kleisli m) a b conf where
   parEvalN conf fs =
      (arr \, parEvalN \, conf \, (map \, (\lambda(Kleislif) \rightarrow f) \, fs)) >>>
      (Kleisli $ sequence)
```

4.3 Extending the Interface

With the ArrowParallel typeclass in place and implemented, we can now implement some further basic parallel interface functions. These are algorithmic skeletons that, however, mostly serve as a foundation to further, more specific algorithmic skeletons.

```
4.3.1 Lazy parEvalN
```

The function parEvalN is 100% strict, which means that it fully evaluates all passed arrows. Sometimes this might not be feasible, as it will not work on infinite lists of functions like e.g. $map(arr \circ (+)) [1..]$ or just because we need the arrows evaluated in chunks. parEvalNLazy (Figs. 10, 11) fixes this. It works by first chunking the input from [a] to [[a]]

12

main

M. Braun, P. Trinder, and O. Lobachev

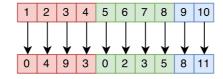


Figure 10: Schematic depiction of parEvalNLazy.

```
parEvalNLazy :: (ArrowParallel\ arr\ a\ b\ conf\ , ArrowChoice\ arr\ , ArrowApply\ arr) \Rightarrow
   conf \rightarrow ChunkSize \rightarrow [arr\ a\ b] \rightarrow (arr\ [a]\ [b])
parEvalNLazy\ conf\ chunkSize\ fs =
   arr (chunksOf chunkSize) >>>
   listApp fchunks >>>
   arr concat
   where fchunks = map (parEvalN conf) \$ chunksOf chunkSize fs
```

Figure 11: Definition of *parEvalNLazy*.

with the given ChunkSize in arr (chunksOf chunkSize). These chunks are then fed into a list [arr [a] [b]] of parallel arrows created by feeding chunks of the passed ChunkSize into the regular parEvalN by using *listApp*. The resulting [[b]] is lastly converted into [b] with arr concat.

4.3.2 Heterogenous tasks

We have only talked about the paralellization arrows of the same type until now. But sometimes we want to paralellize heterogenous types as well. However, we can implement such a parEval2 combinator (Figs. 12, B 11) which combines two arrows arr a b and arr c d into a new parallel arrow arr(a,c)(b,d) quite easily with the help of the ArrowChoice typeclass. The idea is to use the +++ combinator which combines two arrows arr a b and arr c d and transforms them into arr (Either a c) (Either b d) to get a common arrow type that we can then feed into parEvalN.

5 Futures

Consider a mock-up parallel arrow combinator:

```
someCombinator :: (Arrow arr) \Rightarrow [arr \ a \ b] \rightarrow [arr \ b \ c] \rightarrow arr \ [a] \ [c]
someCombinator fs1 fs2 = parEvalN () fs1 >>> rightRotate >>> parEvalN () fs2
```



Figure 12: Schematic depiction of parEval2.

While the above example could be rewritten into only one *parEvalN* call by directly wiring the arrows properly together, it illustrates an important problem. When using a *ArrowParallel* backend that resides on multiple computers, all communication between the nodes is done via the master node, as shown in the Eden trace in Figure 13. This can become a serious bottleneck for larger amount of data and number of processes (as e.g. Berthold *et al.*, 2009c, showcases).

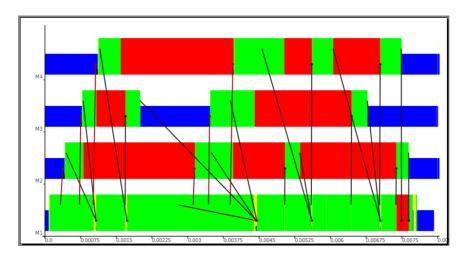


Figure 13: Communication between 4 Eden processes without Futures. All communication goes through the master node. Each bar represents one process. Black lines between processes represent communication. Colors: blue $\hat{=}$ idle, green $\hat{=}$ running, red $\hat{=}$ blocked, yellow $\hat{=}$ suspended.

OL: more practical and heavy-weight example! fft (I have the code)?

MB: Depends... Are the communications easy to read in such an example?

MB: Keep the description for the different colours, or link to the EdenTV description in 2.1.3

OL: ok as is OL: use the fft example (when it works)?

We should allow the nodes to communicate directly with each other. Eden already ships with "remote data" that enable this (Alt & Gorlatch, 2003; Dieterle *et al.*, 2010a). But as we want code with our DSL to be implementation agnostic, we have to wrap this context. We do this with the *Future* typeclass (Fig. 14). Since *RD* is only a type synonym for a communication type that Eden uses internally, we have to use some wrapper classes to fit that definition, though, as Fig. B 5 shows. Technical details are in Appendix, in Section B.

For our *Par* Monad and Multicore Haskell backends, we can simply use *MVars* (Jones *et al.*, 1996) (Fig. 15), as in a shared memory setting we do not require Eden's sophisticated communication channels. **MB: explain MVars**

```
class Future fut a \mid a \rightarrow fut where
   put :: (Arrow \ arr) \Rightarrow arr \ a \ (fut \ a)
   get :: (Arrow arr) \Rightarrow arr (fut a) a
```

Figure 14: Definition of the *Future* typeclass.

```
{-# NOINLINE putUnsafe #-}
putUnsafe :: a \rightarrow MVar \ a
putUnsafe\ a = unsafePerformIO \$ do
  mVar \leftarrow newEmptyMVar
  putMVar mVar a
  return mVar
instance (NFData \ a) \Rightarrow Future \ MVar \ a \ where
  put = arr putUnsafe
  get = arr takeMVar >>> arr unsafePerformIO
```

Figure 15: A MVar instance of the Future typeclass for the Par Monad and Multicore Haskell backends.

In our communication example we can use this Future concept for direct communications between the nodes as shown in Fig. 16. In a distributed environment, this gives us a

```
someCombinator :: (Arrow arr) \Rightarrow [arr \ a \ b] \rightarrow [arr \ b \ c] \rightarrow arr \ [a] \ [c]
someCombinator fs1 fs2 =
  parEvalN()(map(>>>put)fs1)>>>
  rightRotate >>>
  parEvalN()(map(get>>>)fs2)
```

Figure 16: The mock-up combinator in parallel.

communication scheme with messages going through the master node only if it is needed similar to what is shown in the trace visualization in Fig. 17.OL: Fig. is not really clear. Do Figs with a lot of load? — fft?

6 Map-based Skeletons

Now we have developed Parallel Arrows far enough to define some useful algorithmic skeletons that abstract typical parallel computations.

Parallel map and laziness. The parMap skeleton (Figs. B 1, B 2) is probably the most common skeleton for parallel programs. We can implement it with ArrowParallel by repeating an arrow $arr\ a\ b$ and then passing it into parEvalN to obtain an arrow $arr\ [a]\ [b]$. Just like parEvalN, parMap is 100% strict. As parMap is 100% strict it has the same restrictions as parEvalN compared to parEvalNLazy. So it makes sense to also have a

Arrows for Parallel Computations

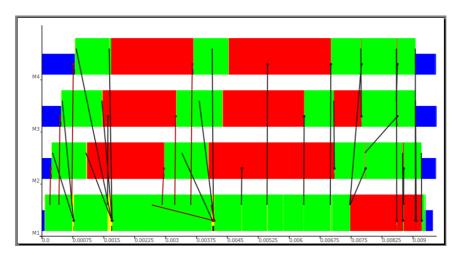


Figure 17: Communication between 4 Eden processes with Futures. Other than in Fig. 13, processes communicate directly (black lines between the bars) instead of always going through the master node (bottom bar).

parMapStream (Figs. B 3, B 4) which behaves like parMap, but uses parEvalNLazy instead of parEvalN. The code is quite straightforward, we show it in Appendix.

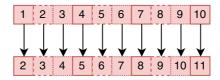


Figure 18: Schematic depiction of a farm, a statically load-balanced parMap.

```
\begin{array}{l} \textit{farm} :: (\textit{ArrowParallel arr a b conf}, \\ \textit{ArrowParallel arr } [a] \, [b] \, \textit{conf}, \\ \textit{ArrowChoice arr}) \Rightarrow \\ \textit{conf} \rightarrow \textit{NumCores} \rightarrow \textit{arr a b} \rightarrow \textit{arr } [a] \, [b] \\ \textit{farm conf numCores} \, f = \\ \textit{unshuffle numCores} \, >>> \\ \textit{parEvalN conf (repeat (mapArrf))} \, >>> \\ \textit{shuffle} \end{array}
```

Figure 19: The definition of *farm*.

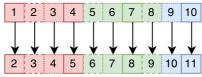


Figure 20: Schematic depiction of farmChunk.

Statically load-balancing parallel *map.* Our *parMap* spawns every single computation in a new thread (at least for the instances of *ArrowParallel* we gave in this paper). This can be quite wasteful and a statically load-balancing *farm* (Figs. 18, 19) that equally distributes the workload over *numCores* workers seems useful. The definitions of the helper functions *unshuffle*, *takeEach*, *shuffle* (Fig. B 6) originate from an Eden skeleton⁶.

Since a *farm* is basically just *parMap* with a different work distribution, it is, again, 100% strict. So we can define *farmChunk* (Figs. 20, B 9) which uses *parEvalNLazy* instead of *parEvalN*. It is basically the same definition as for *farm*, with *parEvalN* replaced with *parEvalNLazy*.

7 Topological Skeletons

Even though many algorithms can be expressed by parallel maps, some problems require more sophisticated skeletons. The Eden library leverages this problem and already comes with more predefined skeletons⁷, among them a *pipe*, a *ring*, and a *torus* implementations (Loogen, 2012). These seem like reasonable candidates to be ported to our Arrow-based parallel Haskell. We aim to showcase that we can express more sophisticated skeletons with Parallel Arrows as well.

7.1 Parallel pipe

The parallel *pipe* skeleton is semantically equivalent to folding over a list $[arr\ a\ a]$ of arrows with >>>, but does this in parallel, meaning that the arrows do not have to reside on the same thread/machine. We implement this skeleton using the ArrowLoop typeclass which gives us the $loop::arr\ (a,b)\ (c,b) \to arr\ a\ c$ combinator which allows us to express recursive fix-point computations in which output values are fed back as input. For example

$$loop (arr (\lambda(a,b) \rightarrow (b,a:b)))$$

which is the same as

loop (arr snd &&& arr (uncurry (:)))

defines an arrow that takes its input a and converts it into an infinite stream [a] of it. Using this to our advantage gives us a first draft of a pipe implementation (Fig. 21) by plugging in the parallel evaluation call parEvalN conf fs inside the second argument of && and then only picking the first element of the resulting list with arr last.

However, using this definition directly will make the master node a potential bottleneck in distributed environments as described in Section 5. Therefore, we introduce a more sophisticated version that internally uses Futures and obtain the final definition of *pipe* in Fig. 22.

⁶ Available on Hackage under https://hackage.haskell.org/package/edenskel-2.1.0.0/docs/src/Control-Parallel-Eden-Map.html.

Available on Hackage: https://hackage.haskell.org/package/edenskel-2.1.0.0/docs/Control-Parallel-Eden-Topology.html.

```
pipeSimple :: (ArrowLoop arr, ArrowParallel arr \ a \ a \ conf) \Rightarrow
  conf \rightarrow [arr\ a\ a] \rightarrow arr\ a\ a
pipeSimple conf fs =
  loop (arr snd &&&
      (arr (uncurry (:) >>> lazy) >>> parEvalN conf fs)) >>>
  arr last
```

Figure 21: A first implementation of the *pipe* skeleton expressed with Parallel Arrows. Note that the use of lazy (Fig. B 7) is essential as without it programs using this definition would never halt. We need to enforce that the evaluation of the input [a] terminates before passing it into parEvalN.

```
pipe :: (ArrowLoop\ arr, ArrowParallel\ arr\ (fut\ a)\ (fut\ a)\ conf\ , Future\ fut\ a) \Rightarrow
   conf \rightarrow [arr\ a\ a] \rightarrow arr\ a\ a
pipe conf fs = unliftFut (pipeSimple conf (map liftFut fs))
```

Figure 22: Final definition of the *pipe* skeleton with Futures.

```
pipe2 :: (ArrowLoop\ arr, ArrowChoice\ arr, Future\ fut\ (([a], [b]), [c]),
   ArrowParallel arr (fut (([a],[b]),[c])) (fut (([a],[b]),[c])) conf) \Rightarrow
   conf \rightarrow arr\ a\ b \rightarrow arr\ b\ c \rightarrow arr\ a\ c
pipe2 conf f g =
   (arr return &&& arr (const [])) &&& arr (const []) >>>
   pipe conf (replicate 2 (unify f(g)) >>>
   arr snd >>> arr head where
      unify:: (ArrowChoice\ arr) \Rightarrow arr\ a\ b \rightarrow arr\ b\ c \rightarrow arr\ (([a],[b]),[c])\ (([a],[b]),[c])
      unify f g =
         (mapArrf***mapArrg)***arr(\_ \rightarrow [\ ])>>>
         arr (\lambda((a,b),c) \rightarrow ((c,a),b))
(|>>>|):: (ArrowLoop\ arr, ArrowChoice\ arr, Future\ fut\ (([a],[b]),[c]),
    \textit{ArrowParallel arr (fut (([a],[b]),[c])) (fut (([a],[b]),[c])) ())} \Rightarrow \\
   arr\ a\ b \rightarrow arr\ b\ c \rightarrow arr\ a\ c
(|>>>|) = pipe2()
```

Figure 23: Definition of *pipe2* and a parallel >>>.

Sometimes, this pipe definition can be a bit inconvenient, especially if we want to pipe arrows of mixed types together, i.e. arr a b and arr b c. By wrapping these two arrows inside a common type we obtain pipe2 (Fig. 23).

Note that extensive use of *pipe2* over *pipe* with a hand-written combination data type will probably result in worse performance because of more communication overhead from the many calls to parEvalN. Nonetheless, we can define a version of parallel piping operator | >>> |, which is semantically equivalent to >>> similarly to other parallel syntactic sugar from Appendix C.

```
Another version of >>> is:
f parparcomp g = (f \circ put) >>> (get \circ g)
```

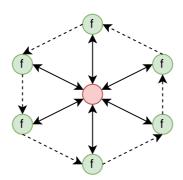


Figure 24: Schematic depiction of the ring skeleton.

It does not launch both arrows f and g in parallel, but allows for more smooth data communication between them. Basically, it is a *Future*-lifted *sequential* >>>>, a way to compose parallel Arrows efficiently.

7.2 Ring skeleton

Eden comes with a ring skeleton⁸ (Fig. 24) implementation that allows the computation of a function $[i] \rightarrow [o]$ with a ring of nodes that communicate in a ring topology with each other. Its input is a node function $i \rightarrow r \rightarrow (o,r)$ in which r serves as the intermediary output that gets send to the neighbour of each node. This data is sent over direct communication channels, the so called 'remote data'. We depict it in Appendix, Fig. B 10.

We can rewrite this functionality easily with the use of *loop* as the definition of the node function, arr(i,r)(o,r), after being transformed into an arrow, already fits quite neatly into the *loop*'s $arr(a,b)(c,b) \rightarrow arr\ a\ c$. In each iteration we start by rotating the intermediary input from the nodes $[fut\ r]$ with $second\ (rightRotate >>> lazy)$ (Fig. B 7). Similarly to the pipe from Section 7.1 (Fig. 21), we have to feed the intermediary input into our lazy (Fig. B 7) arrow here, or the evaluation would fail to terminate. The reasoning is explained by Loogen (2012) as a demand problem.

Next, we zip the resulting $([i],[fut\,r])$ to $[(i,fut\,r)]$ with $arr\ (uncurry\,zip)$ so we can feed that into a our input arrow $arr\ (i,r)\ (o,r)$, which we transform into $arr\ (i,fut\,r)\ (o,fut\,r)$ before lifting it to $arr\ [(i,fut\,r)]\ [(o,fut\,r)]$ to get a list $[(o,fut\,r)]$. Finally we unzip this list into $([o],[fut\,r])$. Plugging this arrow $arr\ ([i],[fut\,r])\ ([o],fut\,r)$ into the definition of loop from earlier gives us $arr\ [i]\ [o]$, our ring arrow (Fig. 25). This combinator can, for example, be used to calculate the shortest paths in a graph using Warshall's algorithm.

Note that the Par Monad version of the *ArrowParallel* version presented in this paper (Fig. 9) does not work with the looping behaviour in the *ring* skeletons. Whenever *runPar* is invoked, strictness is enforced, which means that the *lazy* operation in the definition of *ring* will not work.

⁸ Available on Hackage: https://hackage.haskell.org/package/edenskel-2.1.0.0/docs/Control-Parallel-Eden-Topology.html

17:35

```
ring :: (ArrowLoop\ arr, Future\ fut\ r, ArrowParallel\ arr\ (i, fut\ r)\ (o, fut\ r)\ conf) \Rightarrow
  conf \rightarrow arr(i,r)(o,r) \rightarrow arr[i][o]
ring conf f =
  loop (second (rightRotate >>> lazy) >>> arr (uncurry zip) >>>
  parMap\ conf\ (second\ get >>> f >>> second\ put) >>> arr\ unzip)
```

Figure 25: Final definition of the *ring* skeleton.

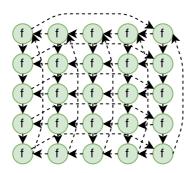


Figure 26: Schematic depiction of the *torus* skeleton.

7.3 Torus skeleton

If we take the concept of a ring from Section 7.2 one dimension further, we obtain a torus skeleton (Fig. 26, 27). Every node sends ands receives data from horizontal and vertical neighbours in each communication round. With our Parallel Arrows we re-implement the torus combinator⁹ from Eden—yet again with the help of the ArrowLoop typeclass.

Similar to the ring, we once again start by rotating the input (Fig. B 7), but this time not only in one direction, but in two. This means that the intermediary input from the neighbour nodes has to be stored in a tuple ($[[fut \, a]], [[fut \, b]]$) in the second argument (loop only allows for two arguments) of our looped arrow arr([[c]],([[fut a]],[[fut b]]))([[d]],([[fut a]],[[fut b]]))and our rotation arrow becomes

```
second ((mapArr rightRotate >>> lazy) *** (arr rightRotate >>> lazy))
```

instead of the singular rotation in the ring as we rotate $[[fut \ a]]$ horizontally and $[[fut \ b]]$ vertically. Then, we once again zip the inputs for the input arrow with

```
arr (uncurry3 zipWith3 lazyzip3)
```

from ([[c]], ([[fut a]], [[fut b]])) to [[(c, fut a, fut b)]], which we then feed into our parallel execution.

This action is, however, more complicated than in the ring case as we have one more dimension of inputs to be transformed. We first have to shuffle all the inputs to then pass it into parMap conf(ptorus f) which yields $[(d, fut \ a, fut \ b)]$. We can then unpack this shuffled

 $^{^9 \ \} Available \ \ on \ \ Hackage: \ \ https://hackage.haskell.org/package/edenskel-2.1.0.0/$ docs/Control-Parallel-Eden-Topology.html.

```
torus:: (ArrowLoop arr, ArrowChoice arr, ArrowApply arr, Future fut a, Future fut b,
   ArrowParallel\ arr\ (c, fut\ a, fut\ b)\ (d, fut\ a, fut\ b)\ conf) \Rightarrow
   conf \rightarrow arr(c,a,b)(d,a,b) \rightarrow arr[[c]][[d]]
torus conf f =
   loop (second ((mapArr rightRotate >>> lazy) *** (arr rightRotate >>> lazy)) >>>
   arr (uncurry3 (zipWith3 lazyzip3)) >>>
   (arr length >>> arr unshuffle) &&& (shuffle >>> parMap conf (ptorus f)) >>> app >>>
   arr (map unzip3) >>> arr unzip3 >>> threetotwo)
ptorus :: (Arrow arr, Future fut a, Future fut b) \Rightarrow
   arr(c,a,b)(d,a,b) \rightarrow arr(c,fut\ a,fut\ b)(d,fut\ a,fut\ b)
ptorus f = arr (\lambda \sim (c, a, b) \rightarrow (c, get \ a, get \ b)) >>> f >>> arr (\lambda \sim (d, a, b) \rightarrow (d, put \ a, put \ b))
```

Figure 27: Definition of the torus skeleton. The definitions of lazyzip3, uncurry3 and threetotwo have been omitted and can be found in Fig. B 8

```
nodefunction :: Int \rightarrow ((Matrix, Matrix), [Matrix], [Matrix]) \rightarrow ([Matrix], [Matrix], [Matrix])
nodefunction\ n\ ((bA,bB),rows,cols) = ([bSum],bA:nextAs,bB:nextBs)
  where bSum = foldl' matAdd (matMult bA bB) (zipWith matMult nextAs nextBs)
    nextAs = take (n-1) rows
    nextBs = take (n-1) cols
```

Figure 28: Adapted nodefunction for matrix multiplication with the torus from Fig. 27.

list back to its original ordering by feeding it into the specific unshuffle arrow we created one step earlier with arr length >>> arr unshuffle with the use of app :: arr $(arr \ a \ b, a)$ c from the ArrowApply typeclass. Finally, we unpack this matrix [[(d, fut a, fut b)]] with $arr (map \ unzip3) >>> arr \ unzip3 >>> threetotwo \ to get ([[d]], ([[fut \ a]], [[fut \ b]])).$

As an example of using this skeleton (Loogen, 2012) showed the matrix multiplication using the Gentleman algorithm (1978). Their instantiation of the skeleton nodefunction can be adapted as shown in Fig. 28. If we compare the trace from a call using our arrow definition of the torus (Fig. 29) with the Eden version (Fig. 30) we can see that the behaviour of the arrow version and execution times are comparable. We discuss further examples on larger clusters and in a more detail in the next section.

Again, the implementation of the Par Monad version prevents this definition of the torus skeleton to work due to the reasons explained in the section about the ring skeleton in section 7.2.

Arrows for Parallel Computations

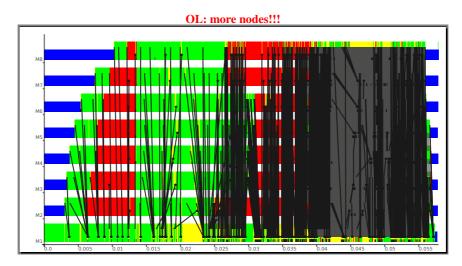


Figure 29: Matrix Multiplication with torus (PArrows).

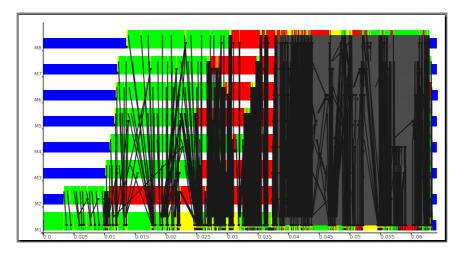
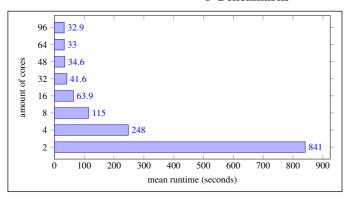
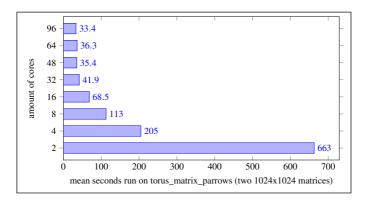


Figure 30: Matrix Multiplication with torus (Eden).

8 Benchmarks





9 Conclusion

Arrows are a generic concept that allows for powerful composition combinators. To our knowledge we are the first ones to represent parallel computation with arrows.OL: that strange arrows-based robot interaction paper from 1993 or so! clearly discuss in related work done!

Arrows turn out to be a useful tool for composing in parallel programs. We do not have to introduce new monadic types that wrap the computation. Instead use arrows just like regular sequential pure functions. This work features multiple parallel backends: the already available parallel Haskell flavours. Parallel Arrows feature an implementation of the ArrowParallel interface for Multicore Haskell, Par Monad, and Eden. With our approach parallel programs can be ported across these flavours with little to no effort. Performancewise, Parallel Arrows are on par with existing parallel Haskells, as they do not introduce any notable overhead.

The strictness problems of the Par Monad backend materializes with ArrowLoop. Additional work is required to ensure correct behaviour of the Par Monad in this context.

MB: mention ArrowLoop in Torus and Ring chapters OL: Parrows + accelerate = love? Metion port to Frege.

9.1 Future Work

Our PArrows DSL can be expanded to futher parallel Haskells. More specifically we target HdpH (Maier et al., 2014), a modern distributed Haskell that would benefit from our Arrows notation. More Future-aware versions of Arrow combinators can be defined and existing can be further improved. We would look into more transparency of the DSL, it should basically infuse as little overhead as possible.

We are looking into more experiences with seamless porting of parallel PArrow-based programs across the backends. Of course, we are working on expanding both our skeleton library and the number of skeleton-based parallel programs that use our DSL to be portable across flavours of parallel Haskells. It would also be interesting to see a hybrid of PArrows and Accelerate. Ports of our approach to other languages like Frege or Java directly are in an early development stage.

References

- Achten, Peter, van Eekelen, Marko, de Mol, Maarten, & Plasmeijer, Rinus. (2007). An arrow based semantics for interactive applications. *Draft Proceedings of the Symposium on Trends in Functional Programming*. TFP '07.
- Achten, PM, van Eekelen, Marko CJD, Plasmeijer, MJ, & Weelden, A van. (2004). *Arrows for generic graphical editor components*. Tech. rept. Nijmegen Institute for Computing and Information Sciences, Faculty of Science, University of Nijmegen, The Netherlands. Technical Report NIII-R0416.
- Alimarine, Artem, Smetsers, Sjaak, van Weelden, Arjen, van Eekelen, Marko, & Plasmeijer, Rinus. (2005). There and back again: Arrows for invertible programming. *Pages 86–97 of: Proceedings of the 2005 ACM SIGPLAN Workshop on Haskell*. Haskell '05. ACM.
- Aljabri, Malak, Loidl, Hans-Wolfgang, & Trinder, Phil W. (2014). The design and implementation of GUMSMP: A multilevel parallel haskell implementation. *Pages* 37:37–37:48 of: Proceedings of the 25th Symposium on Implementation and Application of Functional Languages. IFL '13. ACM.
- Aljabri, Malak, Loidl, Hans-Wolfgang, & Trinder, Phil. (2015). *Balancing shared and distributed heaps on NUMA architectures*. Springer. Pages 1–17.
- Alt, Martin, & Gorlatch, Sergei. (2003). Future-Based RMI: Optimizing compositions of remote method calls on the Grid. *Pages 682–693 of:* Kosch, Harald, Böszörményi, László, & Hellwagner, Hermann (eds), *Euro-Par 2003*. LNCS 2790. Springer-Verlag.
- Aswad, Mustafa, Trinder, Phil, Al Zain, Abdallah, Michaelson, Greg, & Berthold, Jost. (2009). Low pain vs no pain multi-core Haskells. *Pages 49–64 of: Trends in Functional Programming*.
- Atkey, Robert. (2011). What is a categorical model of arrows? *Electronic notes in theoretical computer science*, **229**(5), 19–37.
- Berthold, Jost. (2008). *Explicit and implicit parallel functional programming concepts and implementation*. Ph.D. thesis, Philipps-Universität Marburg.
- Berthold, Jost, & Loogen, Rita. (2006). Skeletons for recursively unfolding process topologies. Joubert, Gerhard R., Nagel, Wolfgang E., Peters, Frans J., Plata, Oscar G., Tirado, P., & Zapata, Emilio L. (eds), *Parallel Computing: Current & Future Issues of High-End Computing, ParCo 2005, Malaga, Spain.* NIC Series 33. Central Institute for Applied Mathematics, Jülich, Germany.
- Berthold, Jost, & Loogen, Rita. (2007). Visualizing Parallel Functional Program Executions: Case Studies with the Eden Trace Viewer. *ParCo '07. Parallel Computing: Architectures, Algorithms and Applications*. IOS Press.
- Berthold, Jost, Dieterle, Mischa, Lobachev, Oleg, & Loogen, Rita. (2009a). Distributed Memory Programming on Many-Cores A Case Study Using Eden Divide-&-Conquer Skeletons. *Pages 47–55 of:* Großpitsch, K.-E., Henkersdorf, A., Uhrig, S., Ungerer, T., & Hähner, J. (eds), *Workshop on Many-Cores at ARCS '09 22nd International Conference on Architecture of Computing Systems 2009*. VDE-Verlag.
- Berthold, Jost, Dieterle, Mischa, & Loogen, Rita. (2009b). Implementing parallel Google map-reduce in Eden. *Pages 990–1002 of:* Sips, Henk, Epema, Dick, & Lin, Hai-Xiang (eds), *Euro-Par 2009 Parallel Processing*. LNCS 5704. Springer Berlin Heidelberg.
- Berthold, Jost, Dieterle, Mischa, Lobachev, Oleg, & Loogen, Rita. (2009c). *Parallel FFT with Eden skeletons*. PaCT '09. Springer. Pages 73–83.

- Berthold, Jost, Loidl, Hans-Wolfgang, & Hammond, Kevin. (2016). PAEAN: Portable and scalable runtime support for parallel Haskell dialects. *Journal of functional programming*, **26**.
- Botorog, G. H., & Kuchen, H. (1996). *Euro-Par'96 Parallel Processing*. LNCS 1123. Springer-Verlag. Chap. Efficient parallel programming with algorithmic skeletons, pages 718–731.
- Chakravarty, Manuel M. T., Leshchinskiy, Roman, Peyton Jones, Simon L., Keller, Gabriele, & Marlow, Simon. (2007). Data Parallel Haskell: a status report. *Pages 10–18 of: DAMP '07*. ACM Press.
- Chakravarty, Manuel M.T., Keller, Gabriele, Lee, Sean, McDonell, Trevor L., & Grover, Vinod. (2011). Accelerating Haskell array codes with multicore GPUs. *Pages 3–14 of: Proceedings of the 6th Workshop on Declarative Aspects of Multicore Programming*. DAMP '11. ACM.
- Clifton-Everest, Robert, McDonell, Trevor L, Chakravarty, Manuel M T, & Keller, Gabriele. (2014). Embedding Foreign Code. *PADL '14: The 16th International Symposium on Practical Aspects of Declarative Languages*. LNCS. Springer-Verlag.
- Cole, M. I. (1989). Algorithmic skeletons: Structured management of parallel computation. *Research Monographs in Parallel and Distributed Computing*. Pitman.
- Dagand, Pierre-Évariste, Kostić, Dejan, & Kuncak, Viktor. (2009). Opis: Reliable distributed systems in OCaml. *Pages 65–78 of: Proceedings of the 4th International Workshop on Types in Language Design and Implementation*. TLDI '09. ACM.
- Danelutto, M., Pasqualetti, F., & Pelagatti, S. (1997). Skeletons for Data Parallelism in P³L. *Pages 619–628 of*: Lengauer, C., Griebl, M., & Gorlatch, S. (eds), *Euro-Par'97*. LNCS 1300. Springer-Verlag.
- Darlington, J., Field, AJ, Harrison, PG, Kelly, PHJ, Sharp, DWN, Wu, Q., & While, RL. (1993). Parallel programming using skeleton functions. *Pages 146–160 of: Parallel architectures and languages Europe*. Springer-Verlag.
- de la Encina, Alberto, Hidalgo-Herrero, Mercedes, Rabanal, Pablo, & Rubio, Fernando. (2011). *A parallel skeleton for genetic algorithms*. IWANN '11. Springer. Pages 388–395.
- Dieterle, M., Horstmeyer, T., & Loogen, R. (2010a). Skeleton composition using remote data. *Pages 73–87 of:* Carro, M., & Peña, R. (eds), 12th International Symposium on Practical Aspects of Declarative Languages. PADL '10, vol. 5937. Springer-Verlag.
- Dieterle, M., Horstmeyer, T., Loogen, R., & Berthold, J. (2016). Skeleton composition versus stable process systems in Eden. *Journal of functional programming*, **26**.
- Dieterle, Mischa, Berthold, Jost, & Loogen, Rita. (2010b). A skeleton for distributed work pools in Eden. FLOPS '10. Springer. Pages 337–353.
- Dieterle, Mischa, Horstmeyer, Thomas, Berthold, Jost, & Loogen, Rita. (2013). *Iterating skeletons*. IFL '12. Springer. Pages 18–36.
- Foltzer, Adam, Kulkarni, Abhishek, Swords, Rebecca, Sasidharan, Sajith, Jiang, Eric, & Newton, Ryan. (2012). A meta-scheduler for the Par-monad: Composable scheduling for the heterogeneous cloud. *Sigplan not.*, **47**(9), 235–246.
- Geimer, M., Wolf, F., Wylie, B. J. N., Ábrahám, E., Becker, D., & Mohr, B. (2010). The Scalasca performance toolset architecture. *Concurrency and computation: Practice and experience*, **22**(6).
- Gentleman, W. Morven. (1978). Some complexity results for matrix computations on parallel processors. *Journal of the acm*, **25**(1), 112–115.

- Gorlatch, Sergei. (1998). Programming with divide-and-conquer skeletons: A case study of FFT. *Journal of supercomputing*, **12**(1-2), 85–97.
- Gorlatch, Sergei, & Bischof, Holger. (1998). A generic MPI implementation for a dataparallel skeleton: Formal derivation and application to FFT. *Parallel processing letters*, **8**(4).
- Hammond, Kevin, Berthold, Jost, & Loogen, Rita. (2003). Automatic skeletons in Template Haskell. *Parallel processing letters*, **13**(03), 413–424.
- Harris, Tim, Marlow, Simon, Peyton Jones, Simon, & Herlihy, Maurice. (2005). Composable memory transactions. *Pages 48–60 of: Proceedings of the 10th ACM SIGPLAN Symposium on Principles and Practice of Parallel Programming*. PPoPP '05. ACM.
- Horstmeyer, Thomas, & Loogen, Rita. (2013). Graph-based communication in Eden. *Higher-order and symbolic computation*, **26**(1), 3–28.
- Huang, Liwen, Hudak, Paul, & Peterson, John. (2007). *HPorter: Using arrows to compose parallel processes*. Berlin, Heidelberg: Springer Berlin Heidelberg. Pages 275–289.
- Hudak, Paul, Courtney, Antony, Nilsson, Henrik, & Peterson, John. (2003). *Arrows, robots, and functional reactive programming*. Springer. Pages 159–187.
- Hughes, John. (2000). Generalising monads to arrows. *Science of computer programming*, **37**(1–3), 67–111.
- Hughes, John. (2005a). Programming with arrows. AFP '04. Springer. Pages 73-129.
- Hughes, John. (2005b). *Programming with arrows*. Berlin, Heidelberg: Springer Berlin Heidelberg. Pages 73–129.
- Jacobs, Bart, Heunen, Chris, & Hasuo, Ichiro. (2009). Categorical semantics for arrows. *Journal of functional programming*, **19**(3-4), 403–438.
- Janjic, Vladimir, Brown, Christopher Mark, Neunhoeffer, Max, Hammond, Kevin, Linton, Stephen Alexander, & Loidl, Hans-Wolfgang. (2013). Space exploration using parallel orbits: a study in parallel symbolic computing. *Parallel computing*.
- Jones, Simon Peyton, Gordon, Andrew, & Finne, Sigbjorn. (1996). Concurrent haskell. *Pages 295–308 of: POPL*, vol. 96.
- Keller, Gabriele, Chakravarty, Manuel M.T., Leshchinskiy, Roman, Peyton Jones, Simon, & Lippmeier, Ben. (2010). Regular, shape-polymorphic, parallel arrays in haskell. *Sigplan not.*, **45**(9), 261–272.
- Kuper, Lindsey, Todd, Aaron, Tobin-Hochstadt, Sam, & Newton, Ryan R. (2014). Taming the parallel effect zoo: Extensible deterministic parallelism with LVish. *Sigplan not.*, **49**(6), 2–14.
- Lengauer, Christian, Gorlatch, Sergei, & Herrmann, Christoph. (1997). The static parallelization of loops and recursions. *The journal of supercomputing*, **11**(4), 333–353.
- Li, Peng, & Zdancewic, S. (2006). Encoding information flow in Haskell. *Pages 12–16 of:* 19th IEEE Computer Security Foundations Workshop. CSFW '06.
- Li, Peng, & Zdancewic, Steve. (2010). Arrows for secure information flow. *Theoretical computer science*, **411**(19), 1974–1994.
- Lindley, Sam, Wadler, Philip, & Yallop, Jeremy. (2011). Idioms are oblivious, arrows are meticulous, monads are promiscuous. *Electronic notes in theoretical computer science*, **229**(5), 97–117.

- Linton, S., Hammond, K., Konovalov, A., Al Zain, A. D., Trinder, P., Horn, P., & Roozemond, D. (2010). Easy composition of symbolic computation software: a new lingua franca for symbolic computation. Pages 339-346 of: Proceedings of the 2010 International Symposium on Symbolic and Algebraic Computation. ISSAC '10. ACM Press.
- Liu, Hai, Cheng, Eric, & Hudak, Paul. (2009). Causal commutative arrows and their optimization. Sigplan not., 44(9), 35-46.
- Lobachev, Oleg. (2011). Implementation and evaluation of algorithmic skeletons: Parallelisation of computer algebra algorithms. Ph.D. thesis, Philipps-Universität Marburg.
- Lobachev, Oleg. (2012). Parallel computation skeletons with premature termination property. FLOPS 2012. Springer. Pages 197-212.
- Loogen, Rita. (2012). Eden parallel functional programming with Haskell. Springer. Pages 142–206.
- Loogen, Rita, Ortega-Mallén, Yolanda, & Peña-Marí, Ricardo. (2005). Parallel Functional Programming in Eden. Journal of Functional Programming, 15(3), 431–475. Special Issue on Functional Approaches to High-Performance Parallel Programming.
- Maier, Patrick, Stewart, Robert, & Trinder, Phil. (2014). The HdpH DSLs for scalable reliable computation. Sigplan not., 49(12), 65–76.
- Mainland, Geoffrey, & Morrisett, Greg. (2010). Nikola: Embedding compiled GPU functions in Haskell. Sigplan not., **45**(11), 67–78.
- Marlow, S., Peyton Jones, S., & Singh, S. (2009). Runtime support for multicore Haskell. Acm sigplan notices, 44(9), 65–78.
- Marlow, Simon. (2013). Parallel and concurrent programming in Haskell: Techniques for multicore and multithreaded programming. "O'Reilly Media, Inc.".
- Marlow, Simon, Newton, Ryan, & Peyton Jones, Simon. (2011). A monad for deterministic parallelism. *Sigplan not.*, **46**(12), 71–82.
- McDonell, Trevor L., Chakravarty, Manuel M. T., Grover, Vinod, & Newton, Ryan R. (2015). Type-safe runtime code generation: Accelerate to LLVM. Sigplan not., 50(12), 201-212.
- Nikhil, R., & Arvind, L. A. (2001). Implicit parallel programming in pH. Morgan Kaufmann.
- Paterson, Ross. (2001). A new notation for arrows. Sigplan not., 36(10), 229–240.
- Perfumo, Cristian, Sönmez, Nehir, Stipic, Srdjan, Unsal, Osman, Cristal, Adrián, Harris, Tim, & Valero, Mateo. (2008). The limits of software transactional memory (STM): Dissecting Haskell STM applications on a many-core environment. Pages 67-78 of: Proceedings of the 5th Conference on Computing Frontiers. CF '08. ACM.
- Rabhi, F. A., & Gorlatch, S. (eds). (2003). Patterns and Skeletons for Parallel and Distributed Computing. Springer-Verlag.
- Russo, Alejandro, Claessen, Koen, & Hughes, John. (2008). A library for light-weight information-flow security in Haskell. Pages 13-24 of: Proceedings of the 1st ACM SIGPLAN Symposium on Haskell. Haskell '08. ACM.
- Stewart, Robert, Maier, Patrick, & Trinder, Phil. (2016). Transparent fault tolerance for scalable functional computation. Journal of functional programming, 26.
- Svensson, Joel. (2011). Obsidian: Gpu kernel programming in haskell. Ph.D. thesis, Chalmers University of Technology.

Trinder, Phil W., Hammond, Kevin, Mattson Jr., James S., Partridge, Andrew S., & Peyton Jones, Simon L. (1996). GUM: a Portable Parallel Implementation of Haskell. PLDI'96. ACM Press.

Trinder, P.W., Hammond, K., Loidl, H-W., & Peyton Jones, S. (1998). Algorithm + Strategy = Parallelism. *Journal of functional programming*, **8**(1), 23–60.

Vizzotto, Juliana, Altenkirch, Thorsten, & Sabry, Amr. (2006). Structuring quantum effects: superoperators as arrows. Mathematical structures in computer science, 16(3), 453–468.

Wheeler, K. B., & Thain, D. (2009). Visualizing massively multithreaded applications with ThreadScope. Concurrency and computation: Practice and experience, 22(1), 45–67.

A Utility Arrows

MB: Text außenrum bauen, siehe Omitted Function Definitions The second combinator:

```
second :: Arrow \ arr \Rightarrow arr \ a \ b \rightarrow arr \ (c,a) \ (c,b)
second f = arr swap >>> first f >>> arr swap
   where swap (x, y) = (y, x)
```

is a mirrored version of *first*, used, e.g. in definition of ***.

Utility combinators for Parallel Arrows follow. We define map, foldl and zipWith on Arrows. The mapArr combinator (Fig. A 1) lifts any arrow arr a b to an arrow arr [a] [b](Hughes, 2005b). Similarly, we can also define foldlArr (Fig. A 2) that lifts any arrow arr(b,a) b with a neutral element b to arr[a] b.

```
mapArr :: Arrow Choice \ arr \Rightarrow arr \ a \ b \rightarrow arr \ [a] \ [b]
mapArrf =
  arr listcase >>>
  arr (const []) \parallel (f *** mapArr f >>> arr (uncurry (:)))
listcase [] = Left ()
listcase(x:xs) = Right(x,xs)
```

Figure A 1: The definition of *map* over Arrows and the *listcase* helper function.

```
foldlArr :: (ArrowChoice\ arr, ArrowApply\ arr) \Rightarrow arr\ (b,a)\ b \rightarrow b \rightarrow arr\ [a]\ b
foldlArrfb =
   arr listcase >>>
   arr(const b) \parallel
       (first (arr (\lambda a \rightarrow (b,a)) >>> f >>> arr (foldlArr f)) >>> app)
```

Figure A 2: The definition of *foldl* over Arrows.

Finally, with the help of mapArr (Fig. A 1), we can define zipWithArr (Fig. A 3) that lifts any arrow arr(a,b) c to an arrow arr([a],[b]) [c].

main

```
zipWithArr::ArrowChoice\ arr\Rightarrow arr\ (a,b)\ c \to arr\ ([a],[b])\ [c] zipWithArr\ f=(arr\ \lambda(as,bs)\to zipWith\ (,)\ as\ bs)>>> mapArr\ f
```

Figure A 3: *zipWith* over arrows.

These combinators make use of the ArrowChoice type class which provides the \parallel combinator. It takes two arrows $arr\ a\ c$ and $arr\ b\ c$ and combines them into a new arrow $arr\ (Either\ a\ b)\ c$ which pipes all $Left\ a$'s to the first arrow and all $Right\ b$'s to the second arrow:

```
(\parallel):: Arrow Choice arr a c \rightarrow arr b c \rightarrow arr (Either a b) c
```

With the zipWithArr combinator we can also write a combinator listApp, that lifts a list of arrows $[arr\ a\ b]$ to an arrow $arr\ [a]\ [b]$.

```
listApp :: (ArrowChoice\ arr, ArrowApply\ arr) \Rightarrow [arr\ a\ b] \rightarrow arr\ [a]\ [b]
listApp\ fs = (arr\ \lambda as \rightarrow (fs, as)) >>> zipWithArr\ app
```

Note that this additionally makes use of the ArrowApply typeclass that allows us to evaluate arrows with $app :: arr(arr \ a \ b, a) \ c$.

B Omitted Function Definitions

We have omitted some function definitions in the main text for brevity, and redeem this here. We warp Eden's build-in Futures in PArrows as in Figure B 5, where *rd* is the accessor function for the *RD* wrapped inside *RemoteData*. Furthermore, in order for these *Future* types to fit with the *ArrowParallel* instances we gave earlier, we have to give the necessary *NFData* and *Trans* instances, the latter are only needed in Eden. The *Trans* instance does not have any functions declared as the default implementation suffices here. Furthermore, because *MVar* already ships with a *NFData* instance, we only have to supply a simple delegating *NFData* instance for our *RemoteData* type, where *rd* simply unwraps *RD*. The *Trans* instance does not have any functions declared as the default implementation suffices:

```
instance NFData (RemoteData a) where rnf = rnf \circ rd instance Trans (RemoteData a)
```

Figures B 1–B 4 show the definitions and a visualizations of two parallel *map* variants, defined using *parEvalN* and its lazy counterpart.

Arrow versions of Eden's *shuffle*, *unshuffle* and the definition of *takeEach* are in Figure B 6. Similarly, Figure B 7 contains the definition of arrow versions of Eden's *lazy* and *rightRotate* utility functions. Fig. B 8 contains Eden's definition of *lazyzip3* together with the utility functions *uncurry3* and *threetotwo*. The full definition of *farmChunk* is in Figure B 9. Eden definition of *ring* skeleton is in Figure B 10. It follows Loogen (2012).

The parEval2 skeleton is defined in Figure B 11. We start by transforming the (a,c) input into a two-element list $[Either\ a\ c]$ by first tagging the two inputs with Left and Right and wrapping the right element in a singleton list with return so that we can combine them

Arrows for Parallel Computations

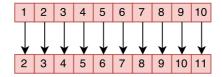


Figure B 1: Schematic depiction of parMap.

 $parMap :: (ArrowParallel \ arr \ a \ b \ conf) \Rightarrow conf \rightarrow (arr \ a \ b) \rightarrow (arr \ [a] \ [b])$ $parMap\;conf\;f=parEvalN\;conf\;(repeat\,f)$

Figure B 2: Definition of parMap.

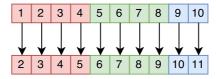


Figure B 3: Schematic depiction of parMapStream.

```
parMapStream :: (ArrowParallel\ arr\ a\ b\ conf\ , ArrowChoice\ arr\ , ArrowApply\ arr) \Rightarrow
   conf \rightarrow ChunkSize \rightarrow arr\ a\ b \rightarrow arr\ [a]\ [b]
parMapStream\ conf\ chunkSize\ f = parEvalNLazy\ conf\ chunkSize\ (repeat\ f)
```

Figure B 4: Definition of parMapStream.

```
data RemoteData\ a = RD\ \{rd::RD\ a\}
instance (Trans\ a) \Rightarrow Future\ RemoteData\ a\ where
  put = arr (\lambda a \rightarrow RD \{ rd = release a \})
  get = arr rd >>> arr fetch
```

Figure B 5: RD-based RemoteData version of Future for the Eden backend.

with arr (uncurry (:)). Next, we feed this list into a parallel arrow running on two instances of f + ++ g as described above. After the calculation is finished, we convert the resulting [Either b d] into ([b], [d]) with arr partition Eithers. The two lists in this tuple contain only one element each by construction, so we can finally just convert the tuple to (b,d) in the last step.

C Syntactic Sugar

For basic arrows, we have the *** combinator (Fig. 6) which allows us to combine two arrows $arr\ a\ b$ and $arr\ c\ d$ into an arrow $arr\ (a,c)\ (b,d)$ which does both computations at once. This can easily be translated into a parallel version *** with the use of parEval2, but for this we require a backend which has an implementation that does not require any configuration (hence the () as the *conf* parameter):

```
shuffle:: (Arrow\ arr) \Rightarrow arr\ [[a]]\ [a]

shuffle = arr\ (concat\circ transpose)

unshuffle:: (Arrow\ arr) \Rightarrow Int \rightarrow arr\ [a]\ [[a]]

unshuffle n = arr\ (\lambda xs \rightarrow [takeEach\ n\ (drop\ i\ xs)\ |\ i \leftarrow [0..n-1]])

takeEach\ n: [Int \rightarrow [a] \rightarrow [a]

takeEach\ n\ (x:xs) = x:takeEach\ n\ (drop\ (n-1)\ xs)
```

Figure B 6: Definitions of shuffle, unshuffle, takeEach.

```
\begin{aligned} &lazy :: (Arrow\ arr) \Rightarrow arr\ [a]\ [a] \\ &lazy = arr\ (\lambda \sim (x:xs) \to x: lazy\ xs) \\ &rightRotate :: (Arrow\ arr) \Rightarrow arr\ [a]\ [a] \\ &rightRotate = arr\ \lambda list \to \mathbf{case}\ list\ \mathbf{of} \\ &[\ ] \to [\ ] \\ &xs \to last\ xs: init\ xs \end{aligned}
```

Figure B 7: Definitions of *lazy* and *rightRotate*.

```
(|***|):: (ArrowChoice\ arr, ArrowParallel\ arr\ (Either\ a\ c)\ (Either\ b\ d)\ ())) \Rightarrow arr\ a\ b \to arr\ c\ d \to arr\ (a,c)\ (b,d) (|***|) = parEval2\ ()
```

We define the parallel &&& in a similar manner to its sequential pendant &&& (Fig. 6):

```
(|\&\&\&|) :: (ArrowChoice\ arr, ArrowParallel\ arr\ (Either\ a\ a)\ (Either\ b\ c)\ ()) \Rightarrow \\ arr\ a\ b \to arr\ a\ c \to arr\ a\ (b,c) \\ (|\&\&\&|)f\ g = (arr\,\$\,\lambda a \to (a,a)) >>> f\ |***|g
```

17:35

Arrows for Parallel Computations

```
lazyzip3::[a] \rightarrow [b] \rightarrow [c] \rightarrow [(a,b,c)]
lazyzip3 as bs cs = zip3 as (lazy bs) (lazy cs)
uncurry3:: (a \rightarrow b \rightarrow c \rightarrow d) \rightarrow (a, (b, c)) \rightarrow d
uncurry3f(a,(b,c)) = f a b c
threetotwo::(Arrow\ arr)\Rightarrow arr\ (a,b,c)\ (a,(b,c))
threetotwo = arr \$ \lambda \sim (a,b,c) \rightarrow (a,(b,c))
```

Figure B 8: Definitions of lazyzip3, uncurry3 and threetotwo.

```
farmChunk::(ArrowParallel arr a b conf, ArrowParallel arr [a] [b] conf,
   ArrowChoice\ arr, ArrowApply\ arr) \Rightarrow
   conf \rightarrow ChunkSize \rightarrow NumCores \rightarrow arr\ a\ b \rightarrow arr\ [a]\ [b]
farmChunk conf chunkSize numCores f =
   unshuffle numCores >>>
   parEvalNLazy conf chunkSize (repeat (mapArr f)) >>>
   shuffle
```

Figure B 9: Definition of farmChunk.

```
ringSimple :: (Trans \ i, Trans \ o, Trans \ r) \Rightarrow (i \rightarrow r \rightarrow (o, r)) \rightarrow [i] \rightarrow [o]
ringSimple f is = os
   where (os, ringOuts) = unzip (parMap (toRD \$ uncurry f) (zip is \$ lazy ringIns))
      ringIns = rightRotate \ ringOuts
toRD:: (Trans\ i, Trans\ o, Trans\ r) \Rightarrow ((i, r) \rightarrow (o, r)) \rightarrow ((i, RD\ r) \rightarrow (o, RD\ r))
toRD f(i, ringIn) = (o, release ringOut)
   where (o, ringOut) = f(i, fetch ringIn)
rightRotate :: [a] \rightarrow [a]
rightRotate[] = []
rightRotate \ xs = last \ xs : init \ xs
lazy::[a] \rightarrow [a]
lazy \sim (x:xs) = x: lazy xs
```

Figure B 10: Eden's definition of the *ring* skeleton.

```
parEval2::(ArrowChoice arr,
  ArrowParallel\ arr\ (Either\ a\ c)\ (Either\ b\ d)\ conf) \Rightarrow
  conf \rightarrow arr\ a\ b \rightarrow arr\ c\ d \rightarrow arr\ (a,c)\ (b,d)
parEval2 \ conf f \ g =
  arr Left *** (arr Right >>> arr return) >>>
  arr (uncurry (:)) >>>
  parEvalN \ conf \ (replicate 2 \ (f +++ g)) >>>
  arr partitionEithers >>>
  arr head *** arr head
```

Figure B 11: Definition of parEval2.

ZU064-05-FPR main 8th July 2017 17:35