

16:332:573 - DATA STRUCTURES AND ALGORITHMS

COMPARISON BETWEEN PATH A* ALGORITHMS

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INTRODUCTION

- ❖ Path finding algorithms are an essential component of any modern system.
- ❖ These algorithms are basically used to help us find the shortest or the fastest between the source node and the destination node.
- ❖ In this presentation, we will be studying the implementation of A* algorithm, its variants Repetitive Forward A* algorithm and Adaptive A* algorithm.
- ❖ We will also be comparing Forward A* and Adaptive A* algorithm and study which one of these is more efficient and the key factors involved with them.
- ❖ The goal is to provide a comprehensive and unbiased comparison that can be used to solve the grid problem.

SEARCH ALGORITHM

- ❖ Search algorithms are computational techniques which are used to find an optimal path or search space.
- ❖ Search algorithms are commonly classified as uniformed or informed search algorithm depending upon whether they use domain knowledge or the heuristic search to guide the search process.
- ❖ It is a method to find solutions to problems by exploring various states of the problem domain.
- ❖ Search algorithm starts with an initial state in search of the solution of the problem, while searching for solutions it uses various data-structures such as breadth-first-search, depth-first search, or a heuristic search.
- ❖ There are various types of search algorithms and the A* algorithm is one of them.

A* ALGORITHM

- ❖ A* is a type of search algorithm also known as Heuristic search algorithms.
- ❖ A* algorithm is a popular informed search algorithm widely used for path-finding in a 2D or 3D environment.
- ❖ It is used to find the shortest distance or the optimal path between the source node and the destination node.
- ❖ A* algorithm works by expanding the nodes with lowest cost or the distance from the source node and a heuristic estimate of the distance to the destination node.
- ❖ The heuristic estimate is usually on Euclidean distance or the Manhattan distance between the node and the destination node.

ISSUE WITH A*

ALGORITHM

- A* algorithm is not an adaptive algorithm (by which I mean to say - The agent needs to know the environment before it starts)
 - What if the agent doesn't know about the environment and it needs to figure it out as it traverses.
 - So, to inculcate this capability we use the Repetitive Forward A* algorithm and the Adaptive A* algorithm
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REPETITIVE FORWARD A* ALGORITHM

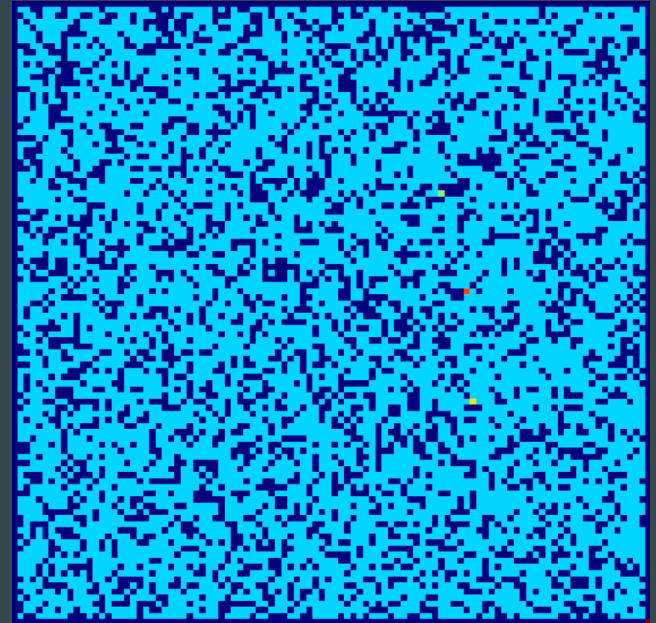
- ❖ Repetitive Forward A* algorithm is an extension of the Forward A* algorithm and is particularly designed to handle the uncertainty in the environment.
- ❖ The idea behind implementing this algorithm is it runs the Forward A* multiple times from its current node to the destination node by always finding a new path when the previous path is found to be incorrect.
- ❖ If the path is found to be incorrect, a new A* algorithm search is started from the current node.
- ❖ The grid agent here does not know about the environment and figures it out while it is traversing the environment.

ADAPTIVE A* ALGORITHM

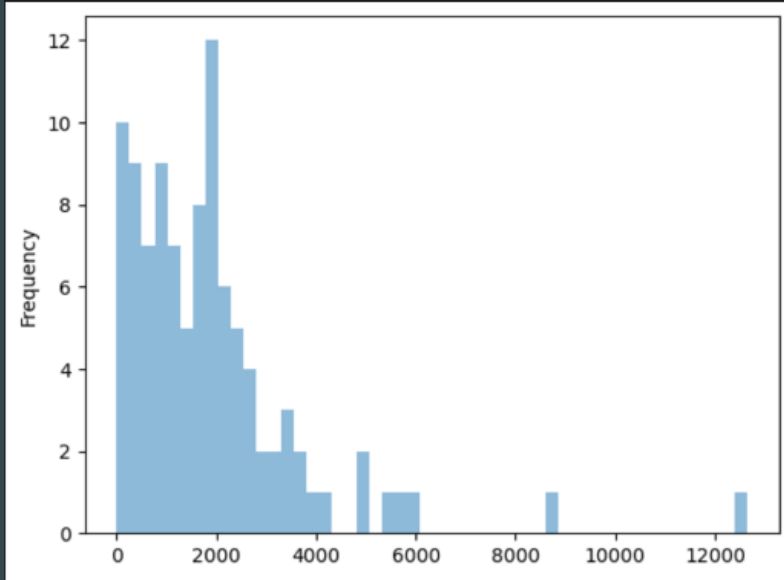
- ❖ Adaptive A* algorithm is another type of A* algorithm aimed to improve the efficiency as well as the accuracy of the algorithm by adjusting the heuristic function during every search.
- ❖ The idea behind using Adaptive A* algorithm is to use the information of its previous search and refine the heuristic estimate of the remaining cost from a node to the destination node.
- ❖ This method helps us to improve accuracy of the heuristic function and can help us achieve a better performance.
- ❖ The heuristic function is updated after every search iteration based on the actual cost of the node to the destination node.
- ❖ The implementation is based on the previous search experiences.

EXPERIMENTAL SETUP

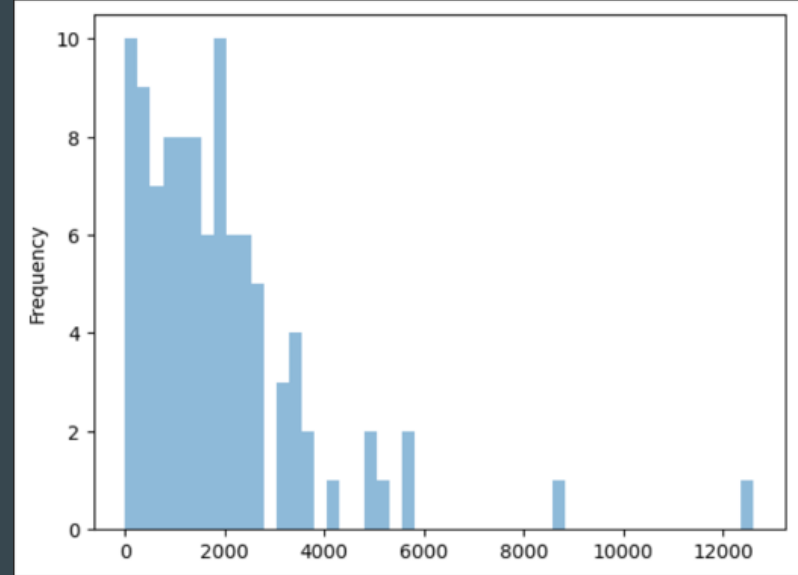
- ❖ To compare the Repetitive Forward A* and the Adaptive A* we would be creating 100 grid environments of size 100 x 100.
- ❖ We would be checking the total number of expanded cells in both the algorithms for all A* searches in a particular environment.
- ❖ The idea is to create a distribution of both algorithms and map out the total number of search based expanded cells.
- ❖ Using this information, we will run a “T-test” and generate a p value to prove our hypothesis of the difference between the two algorithms



GRAPHICAL REPRESENTATION



REPETITIVE FORWARD A* ALGORITHM



ADAPTIVE A* ALGORITHM

COMPARISON BETWEEN ALGORITHMS

T-statistic: 0.09014738195527473

P-value: 0.46482865030341813

- ❖ Generating t-test provides a significant value, but the p-value does not provide an accurate representation based on our confidence interval of 0.05. Hence, we cannot prove that our means are significantly different.

THE NUMBER OF TIMES ADAPTIVE IS BETTER THAN FORWARD: 67

THE NUMBER OF TIMES FORWARD AND ADAPTIVE HAD A TIE: 22

THE NUMBER OF TIME FORWARD IS BETTER THAN ADAPTIVE: 11

- ❖ We use an assumption – the difference in individual expanded cell computations could theoretically tell which algorithm is more efficient. We prove through this method that Adaptive A* algorithm takes fewer computations, is therefore more efficient.

CONCLUSION

- ❖ In this project, I have experimented and compared to variants of the A* algorithm – Repetitive Forward A* Algorithm and the Adaptive A* Algorithm.
- ❖ Through the computations we tried to prove which one was more efficient than other.
- ❖ We tried two different methods to prove this, while implementing the first method we generated p-values to determine statistical differences between the algorithms. This method did not help us provide with a significant result.
- ❖ The other method which we employed was a simpler one, wherein we just calculated the difference between both the expanded cell computation.
- ❖ Through this methodology, we can come to significant result that Adaptive A* Algorithm is better in most of the instances