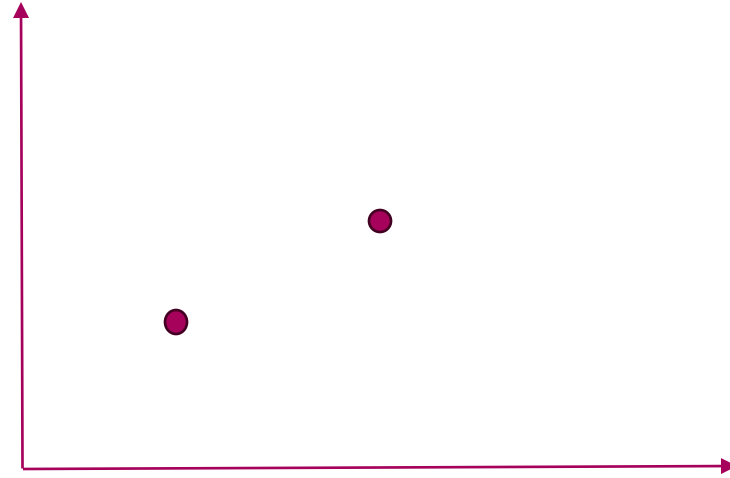


# Gaussian Processes

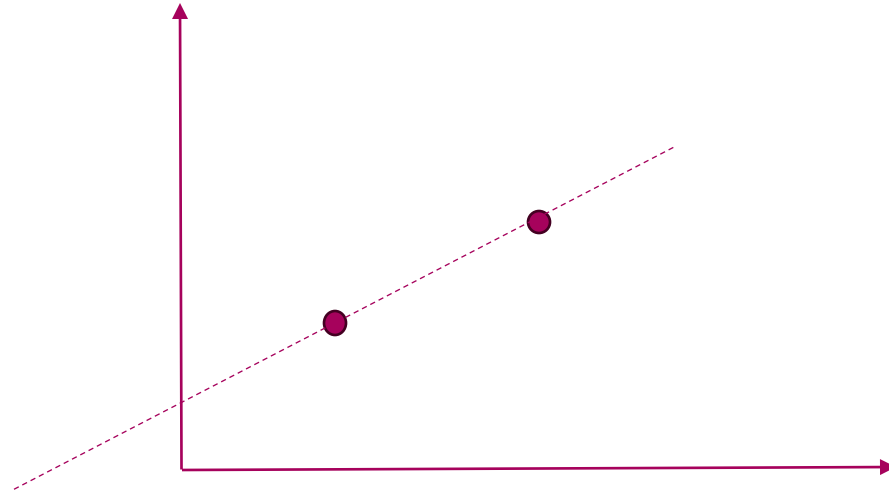
*Parsa Hariri*



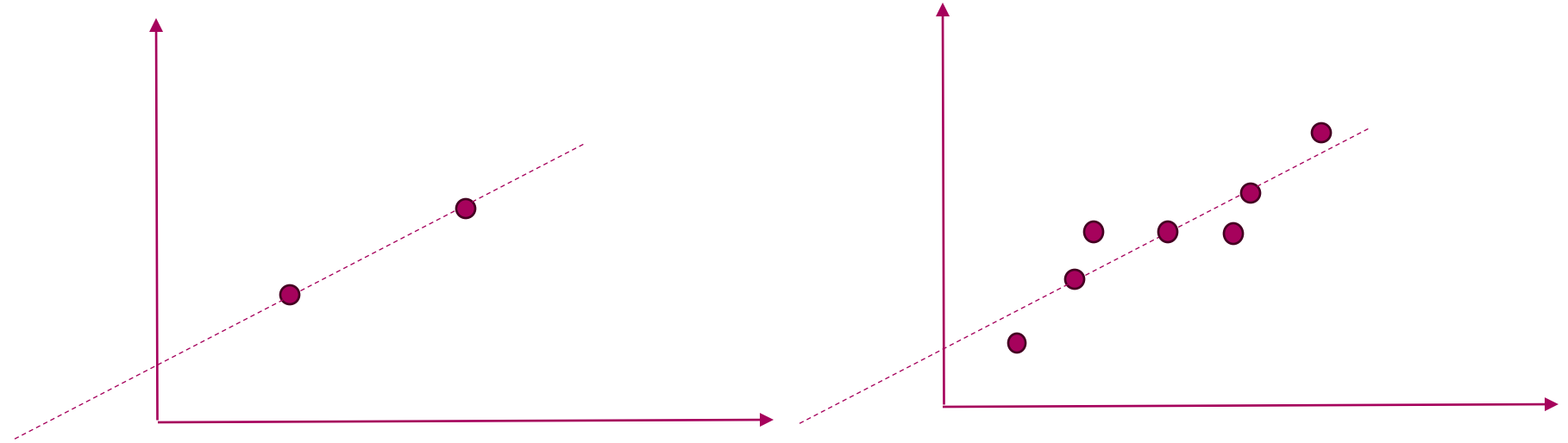
linear regression



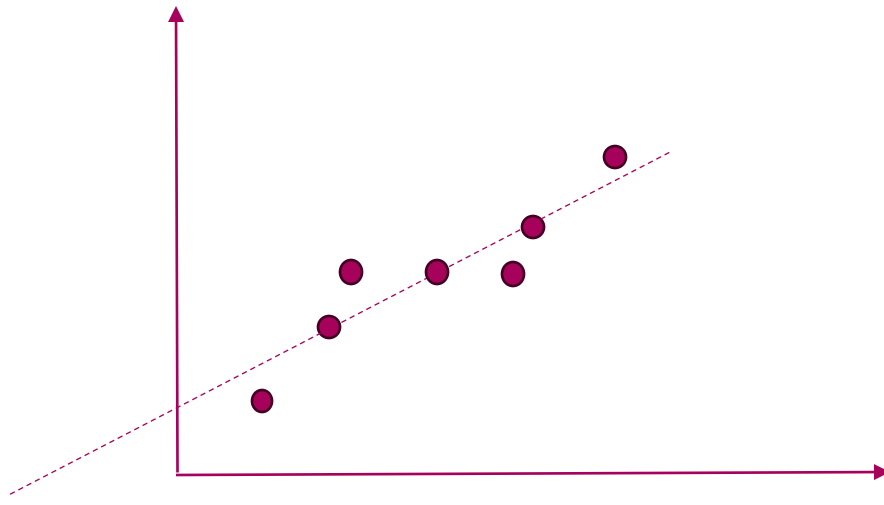
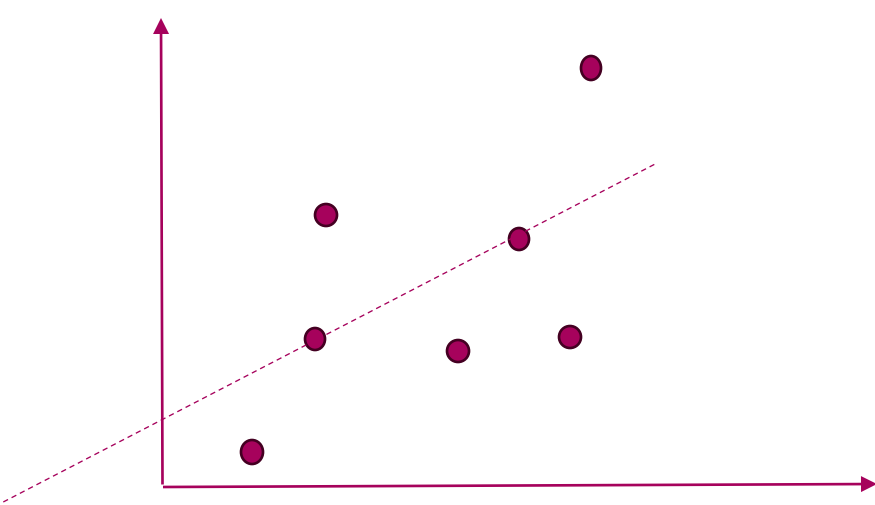
linear regression



# linear regression



## linear regression



Do you see  
any  
Problems?



## Definition & Intuition

$$P(y(\mathbf{x}) \mid \mathbf{t}_N, \mathbf{X}_N) = \frac{P(\mathbf{t}_N \mid y(\mathbf{x}), \mathbf{X}_N)P(y(\mathbf{x}))}{P(\mathbf{t}_N \mid \mathbf{X}_N)}$$

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$y(\mathbf{x})$

Find the parametrics  
function and then  
calculte the probbability



# Definition & Intuition

$$P(y(\mathbf{x}) \mid \mathbf{t}_N, \mathbf{X}_N) = \frac{P(\mathbf{t}_N \mid y(\mathbf{x}), \mathbf{X}_N) \underbrace{P(y(\mathbf{x}))}_{\text{prior}}}{P(\mathbf{t}_N \mid \mathbf{X}_N)}$$

$P(y(\mathbf{x}))$

Sum over finite number of  
functions, then no need  
for single function  
probability !



# Definition & Intuition

$$P(y(\mathbf{x}) \mid \mathbf{t}_N, \mathbf{X}_N) = \frac{P(\mathbf{t}_N \mid y(\mathbf{x}), \mathbf{X}_N) \underbrace{P(y(\mathbf{x}))}_{\text{prior}}}{P(\mathbf{t}_N \mid \mathbf{X}_N)}$$

$$P(y(\mathbf{x}))$$

One of the most simple  
functions we can use is  
Gaussian process model

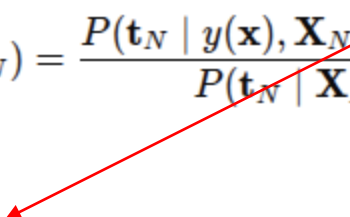
$$f(x) \sim \mathcal{GP}(m(x), k(x, x'))$$

mean  
function


$$m(x) = \mathbb{E}[f(x)]$$

# Definition & Intuition

$$P(y(\mathbf{x}) \mid \mathbf{t}_N, \mathbf{X}_N) = \frac{P(\mathbf{t}_N \mid y(\mathbf{x}), \mathbf{X}_N) \underbrace{P(y(\mathbf{x}))}_{\text{prior}}}{P(\mathbf{t}_N \mid \mathbf{X}_N)}$$

$$P(y(\mathbf{x}))$$


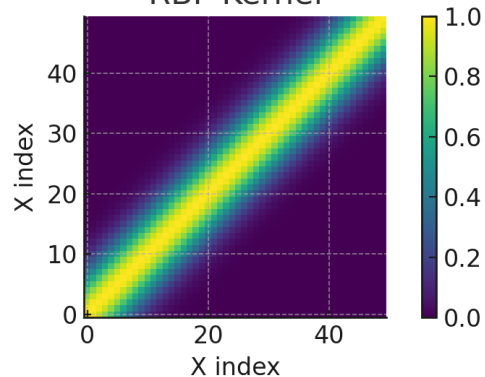
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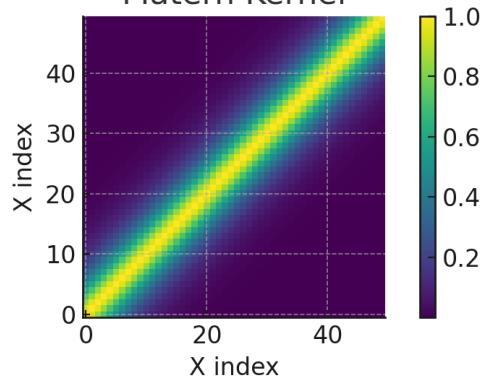
covariance  
function (kernel)

$$k(x, x') = \mathbb{E}[(f(x) - m(x))(f(x') - m(x')))]$$

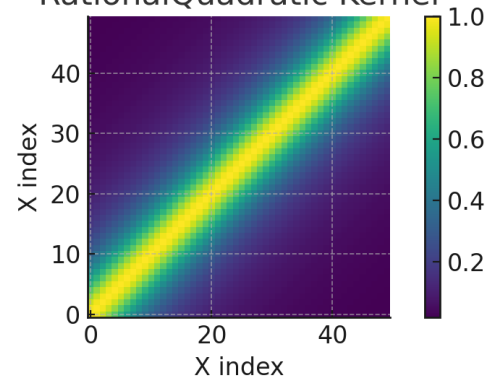
RBF Kernel



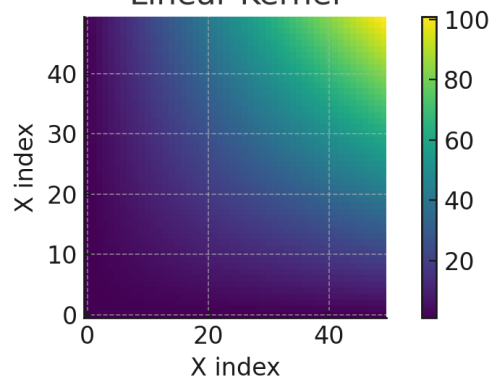
Matern Kernel



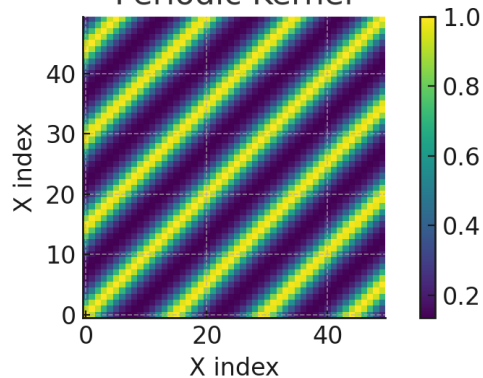
RationalQuadratic Kernel



Linear Kernel



Periodic Kernel



Constant :  $K_C(x, x') = C$

Linear:  $K_L(x, x') = x^\top x'$

white Gaussian noise:  $K_{GN}(x, x') = \sigma^2 \delta_{x, x'}$

Squared exponential:  $K_{SE}(x, x') = \exp\left(-\frac{d^2}{2\ell^2}\right)$

Ornstein-Uhlenbeck:  $K_{OU}(x, x') = \exp\left(-\frac{d}{\ell}\right)$

Matérn:  $K_{\text{Matern}}(x, x') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{\sqrt{2\nu}d}{\ell}\right)^\nu K_\nu\left(\frac{\sqrt{2\nu}d}{\ell}\right)$

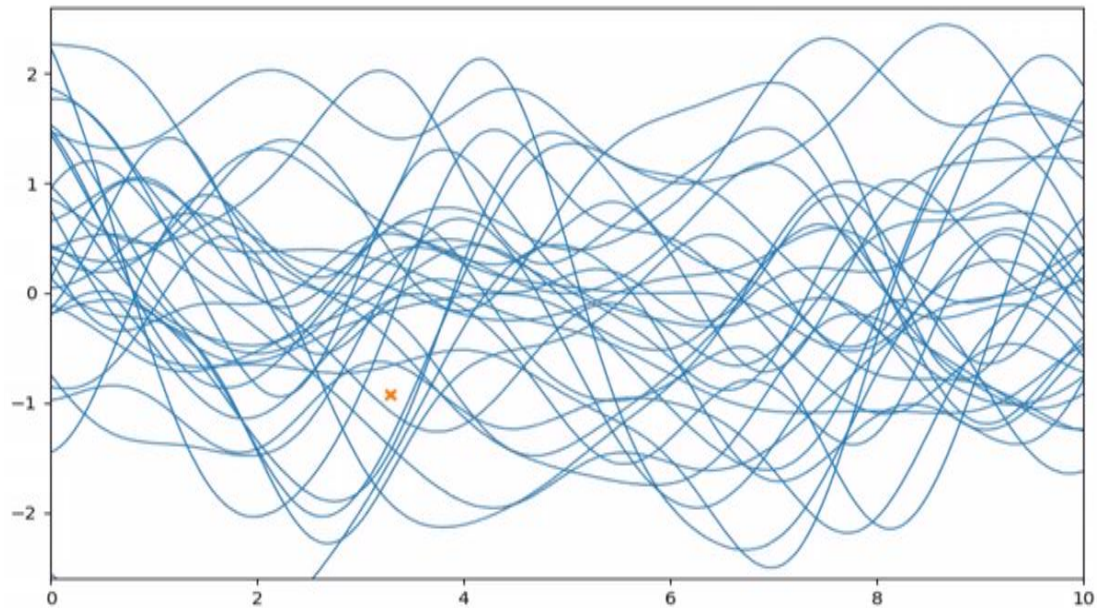
Periodic:  $K_P(x, x') = \exp\left(-\frac{2}{\ell^2} \sin^2(d/2)\right)$

Rational quadratic:  $K_{RQ}(x, x') = (1 + d^2)^{-\alpha}$ ,  $\alpha \geq 0$

# How to use it in Python?

```
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import DotProduct, WhiteKernel
>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = DotProduct() + WhiteKernel()
>>> gpr = GaussianProcessRegressor(kernel=kernel,
...                               random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.3680...
>>> gpr.predict(X[:2,:], return_std=True)
(array([653.0, 592.1]), array([316.6, 316.6]))
```

Thank you for your attention!



# Key Papers & Further Reading

- Brown (1827) observed jittering pollen grains
- Einstein & Smoluchowski (1905–1906) explained Brownian motion
- Perrin (1908–1909) validated atomic hypothesis
- Wiener & Kolmogorov (1920s–1940s) formalised GPs
- Mandelbrot & Van Ness (1968) introduced fractional Brownian motion
- Rasmussen & Williams (2006) popularised GPs in ML
- Metzler & Klafter (2000) reviewed anomalous diffusion
- Randomly scaled GPs model sub/superdiffusion
- Biophysical studies reveal anomalous transport
- Sohl-Dickstein et al. (2015) introduced diffusion models
- Ho et al. (2020) proposed denoising diffusion probabilistic models
- Song et al. (2021) developed score-based models