

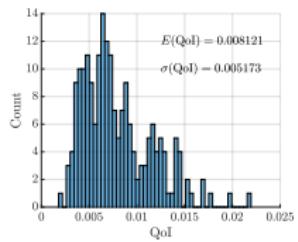
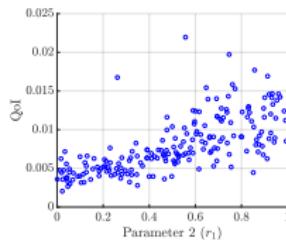
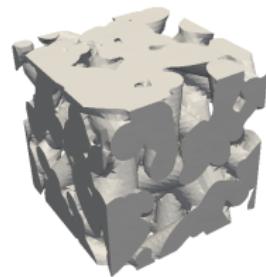
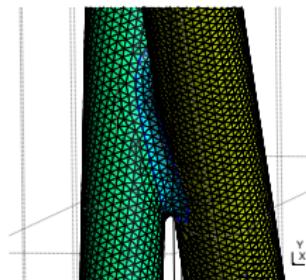
Uncertainty Quantification with Parsl in Composite Material Modeling

Kunkun Tang

The Center for Exascale-enabled Scramjet Design (CEESD)

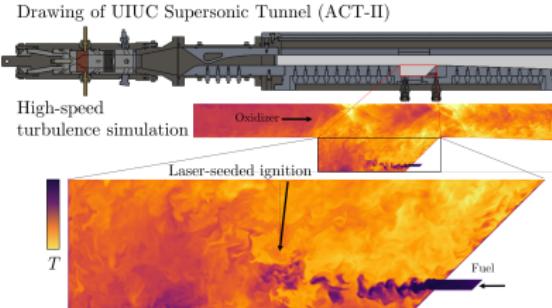
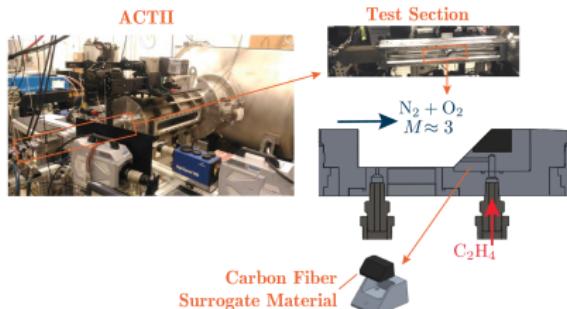
National Center for Supercomputing Applications (NCSA)

University of Illinois at Urbana–Champaign

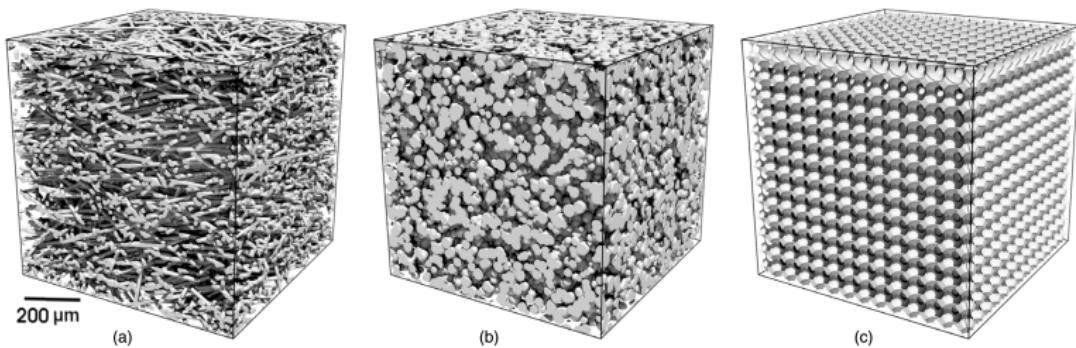


Some of CEESD Objectives

- ▶ New PSAAPIII Center (<http://ceesd.illinois.edu>) targeting scramjet design
- ▶ Establish predictive confidence using **UQ-based integration** of multi-scale/multi-physics models and exploiting HPC to resolve scales
- ▶ Advance a physics-based prediction capability for **novel carbon-composites** that will advance scramjet propulsion
- ▶ Initial studies focus on **carbon-fiber microstructure**, a common key feature of high- T composites
- ▶ Parsl will be employed to manage Workflow and provide Provenance



Uncertainties in Advanced Composite Materials



JOSEPH C. FERGUSON, FRANCESCO PANERAI, ARNAUD BORNER, NAGI N. MANSOUR, "PuMA: the Porous Microstructure Analysis software", *SoftwareX* 7, 81–87 (2018).

- ▶ Candidate models for material microstructure
 - Chemical composition
 - Random fibers — Simple cylinders, more complex geometry models
- ▶ Candidate models for material properties
 - Bilinear, Mises, Cohesive, Gurson, ...
 - Temperature-dependent, Strain rate-dependent
- ▶ Candidate models for crack models
 - Element death, Interface-Cohesive Elements, ...

PuMA → Gmsh → WARP3D Workflow

- ▶ **PuMA** (Porous Microstructure Analysis, https://gitlab.com/jcfergus/PuMA_V3) has been developed to compute effective material properties and perform material response simulations on digitized microstructures of porous media. [Ferguson et al. 2018]
- ▶ **Gmsh** (<https://gmsh.info>) is a three-dimensional finite element mesh generator. We use it to make STL → Nastran/(Patran) conversion by creating a volume mesh (tet4).
- ▶ **WARP3D** (<http://www.warp3d.net>) is an open source code for 3D nonlinear finite element analysis of solids (static/dynamic).

PuMA & Surface Mesh Generation

► INPUT – test_projCEESD.cpp

- This source cpp file contains all “hard-coded” parameters (for now), e.g. domain size, fiber diameter, etc.

► OUTPUT – RandomFibers_straightCircle.stl

- A single STL surface mesh file

INPUT

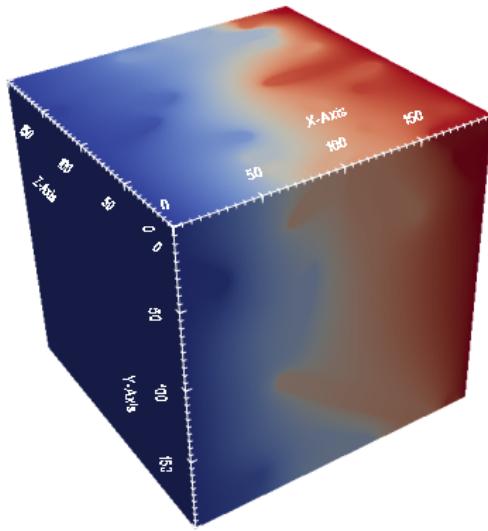
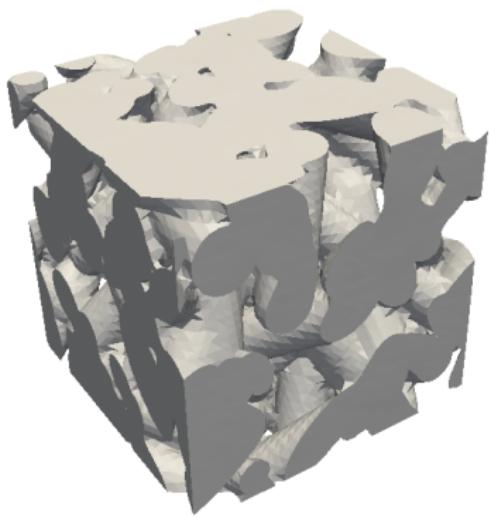
- test_projCEESD.cpp
 - “input.straightCircle
(40, 40, 40, 3, 1,
40, 0, 90, 90, 60,
true, 0.35, 999);”
 - Domain size
 - Fiber diameter +
uncertainty
 - Fiber length +
uncertainty
 - Orientation
 - Porosity



OUTPUT

- STL surface mesh:
RandomFibers_straightCircle.stl
- “puma::export_STL”
- An STL file describes
a raw,
unstructured triangulated
surface by
the unit normal and
vertices (ordered by
the right-hand rule)
of the triangles
using a three-
dimensional Cartesian
coordinate system.

Example: A Random Fiber Configuration (PuMA)



- ▶ QoI: Effective thermal conductivity (k_{xx} , k_{yy} , k_{zz})
- ▶ Goal: How microstructure properties and uncertainties affect QoI

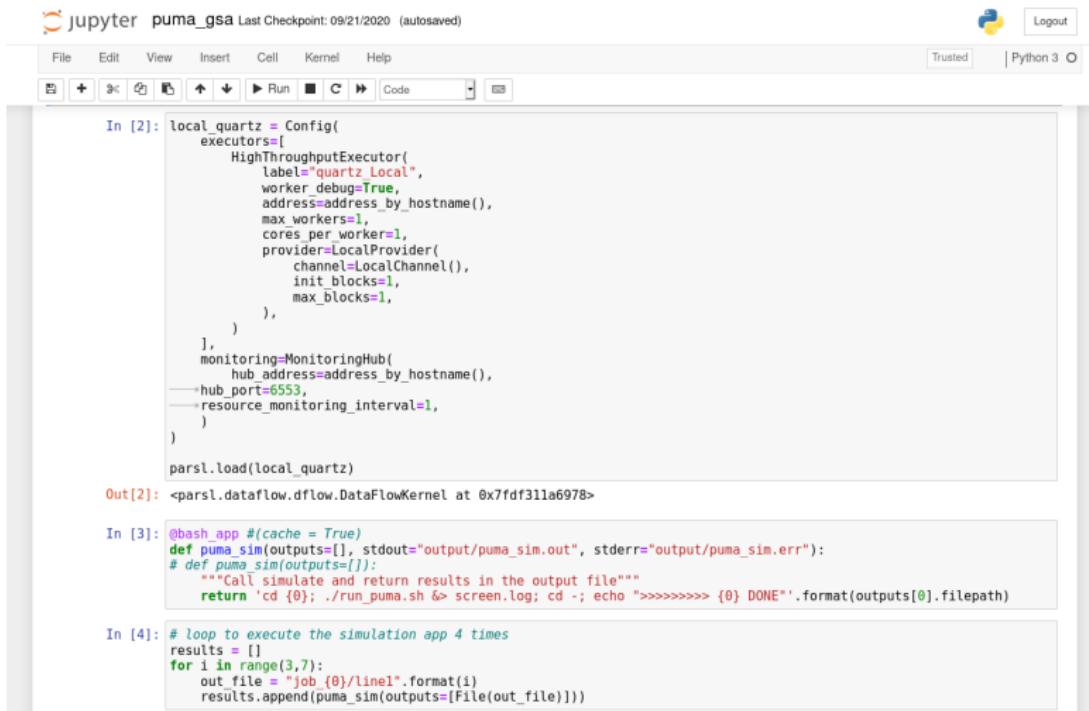
Uncertain Parameters — Random-Fiber Model

	Symbol	Value	Uncertainty/Status	Description
	d_{fiber}	4	$\mathcal{U}(3, 5)$	Fiber diameter
	Δd_{fiber}	1	$\mathcal{U}(0, 2)$	Fiber diameter variation
	l_{fiber}	40	$\mathcal{U}(30, 50)$	Fiber length
Material topology	Δl_{fiber}	5	$\mathcal{U}(0, 10)$	Fiber length variation
[K. Tang et al.]	θ_x	45	$\mathcal{U}(0, 90)$	Orientation wrt x -normal plane
	θ_y	45	$\mathcal{U}(0, 90)$	Orientation wrt y -normal plane
	θ_z	15	$\mathcal{U}(0, 30)$	Orientation wrt z -normal plane
	ϕ	0.75	$\mathcal{U}(0.65, 0.85)$	Porosity
Material properties	k_a	12	$\mathcal{U}(10, 500)$	Fiber conductivity (axial)
[K. Tang et al.]	k_r	1.25	$\mathcal{U}(1, 50)$	Fiber conductivity (radial)
	k_{air}	0.0257	$\mathcal{U}(0.009, 5)$	Air conductivity (isotropic)

- ▶ 11 uncertain parameters typically require hundreds–thousands of simulations

Workflow by Parsl + Jupyter Notebook

- The starting point workflow is simple: Conductivity simulation + UQ analysis



The screenshot shows a Jupyter Notebook interface with the title "jupyter puma_gsa Last Checkpoint: 09/21/2020 (autosaved)". The toolbar includes File, Edit, View, Insert, Cell, Kernel, Help, Run, Cell, Code, and a Trusted Python 3 logo.

In [2]:

```
local_quartz = Config(
    executors=[

        HighThroughputExecutor(
            label="quartz Local",
            worker_debug=True,
            address=address_by_hostname(),
            max_workers=1,
            cores_per_worker=1,
            provider=LocalProvider(
                channel=LocalChannel(),
                init_blocks=1,
                max_blocks=1,
            ),
        ),
        monitoring=MonitoringHub(
            hub.address=address_by_hostname(),
            hub_port=6553,
            resource_monitoring_interval=1,
        )
    )
parsl.load(local_quartz)
```

Out[2]:

```
<parsl.dataflow.dflow.DataFlowKernel at 0x7fd311a6978>
```

In [3]:

```
@bash_app #(cache = True)
def puma_sim(outputs=[], stdout="output/puma_sim.out", stderr="output/puma_sim.err"):
    # def puma_sim(outputs=[]):
        """Call simulate and return results in the output file"""
        return 'cd {0}; ./run_puma.sh &> screen.log; cd -; echo ">>>>> {0} DONE".format(outputs[0].filepath)
```

In [4]:

```
# loop to execute the simulation app 4 times
results = []
for i in range(3,7):
    out_file = "job_{0}/line1".format(i)
    results.append(puma_sim(outputs=[file(out_file)]))
```

Global Sensitivities – Ranking of Importances

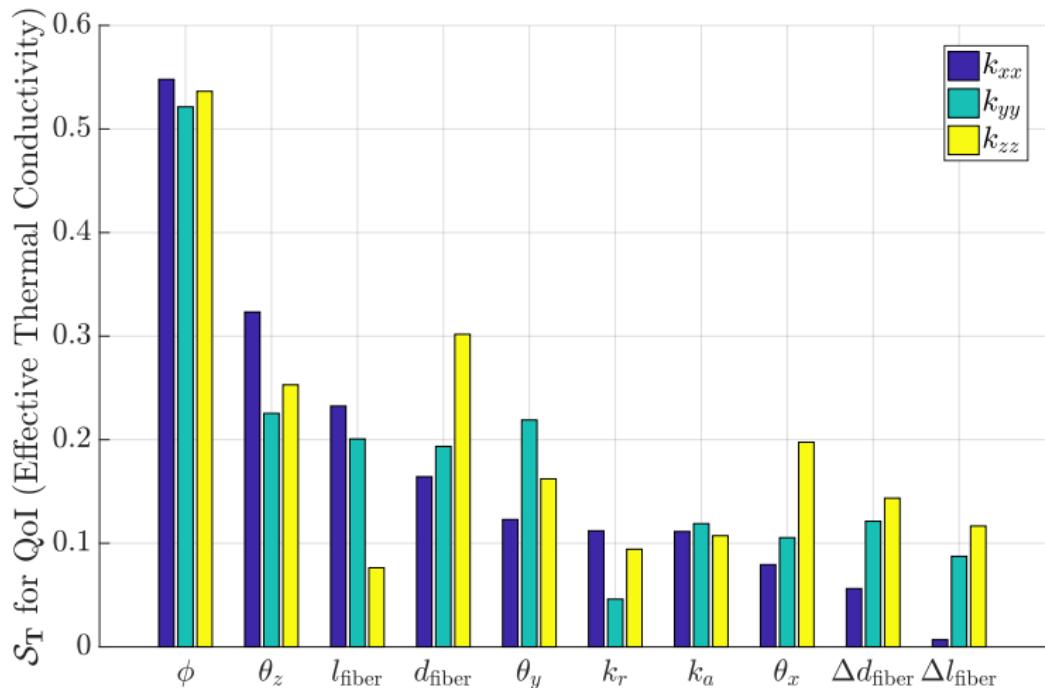
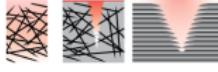


Figure: Parameters sorted in descending order wrt to values of k_{xx} .

Multi-scale/Multi-physics

PHYSICS/SCALE	CODE(S)	ESSENTIAL PHYSICS	ANTICIPATED PHYSICS	POTENTIAL PHYSICS	
FULL	 ~ m	<i>MIRGE-Com</i> <i>{Nek5000-DG}</i> <i>Cantera</i> <i>Prometheus</i>	Turbulent mixing Shocks Combustion Complex geom.	Radiation Flexible wall Wall texture Wall transpiration	Particle trajectories Radicals
		Needs: Wall conditions T , (maybe Y_i , geom.); Provides: Gas T , Y_i , (maybe σ)			
MACRO	 ~ m × cm	<i>WARP3D</i> <i>{RAPtor}</i>	Thermal conductivity	Fracture Fragmentation Recession Elastic response	Vibration
		Needs: Local mechanical degradation, local Y_O , traction separation prms.; Provides: Cracking, regression, failure.			
MESO	 ~ mm	<i>PuMA</i> <i>{Cedar}</i>	Oxidation Transport	Micro-cracking Recession Detailed porous transport Porous material radiation	Sublimation Evaporation Wetting
		Provides: Thermal conductivity, convective transport, local concentrations, microstructure geometry.			
MICRO	 ~ μm	<i>SPARTA</i> <i>WARP3D</i> <i>{RAPtor}</i>	Surface kinetics	Stress-coupled reaction De-bonding	Grain-scale pitting
		Provides: Local surface chemical kinetics.			
NANO	 ~ nm	<i>LAMMPS</i>	Solid-state diff. Traction-separation Phonon-kinetic models		Quantum (DFT) potentials
		Provides: O diffusion, O-dependent traction separation.			



Plans and Challenges

- ▶ We plan to use Parsl to manage **complex workflow** involving UQ-based integration of multi-scale/multi-physics models
- ▶ **Primary Goals**
 - Coupled material modeling codes including mesh generation capability: PuMA, WARP3D, etc.
 - **End-to-end UQ analysis:** Sampling, surrogate polynomial approximation, sensitivity analysis, parameter estimation.
- ▶ **Challenge** encountered
 - Multi-cores performance issues have been observed in the coupling between Parsl and certain application code (e.g., PuMA to compute porous microstructure properties); reported on GitLab.

This material is based in part upon work supported by the Department of Energy, National Nuclear Security Administration, under Award Number DE-NA0003963.

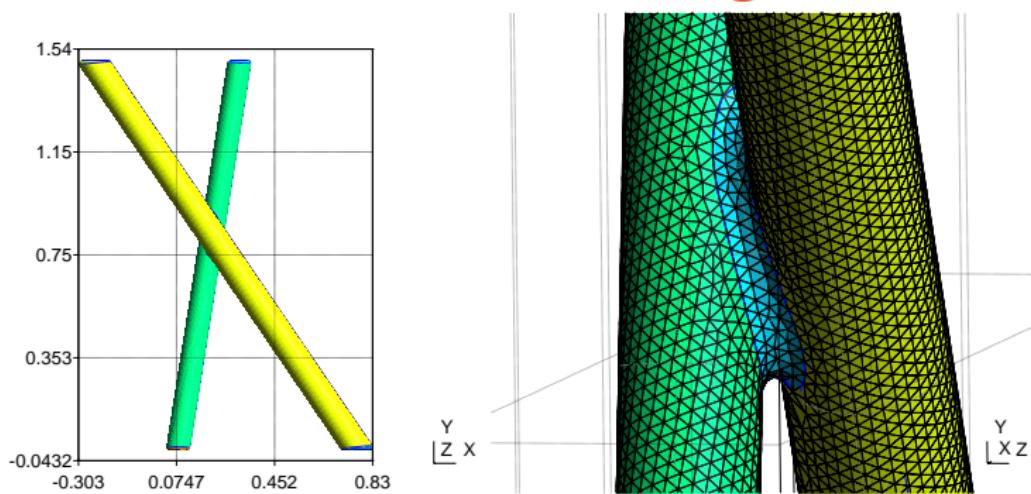
Acknowledgements

- ▶ Daniel Katz
- ▶ Kyle Chard
- ▶ Kelly Stephani
- ▶ Francesco Panerai
- ▶ Joseph Ferguson
- ▶ Harley Johnson
- ▶ Marco Panesi
- ▶ Jonathan Freund

Example 2:

Gmsh + WARP3D

Example: A Cross-Fiber Model Configuration



- ▶ Gmsh + WARP3D
- ▶ Only mechanical loading applied
- ▶ Bottom ends fixed
- ▶ Space and time (load steps) distributed force on top ends ($+x, -y$)
- ▶ This crack model (element death) requires a fracture threshold of the plastic strain value
- ▶ Currently learning to use interface-cohesive elements model

Limiting Cases for Parameters $\tan \theta_1$ & d_2

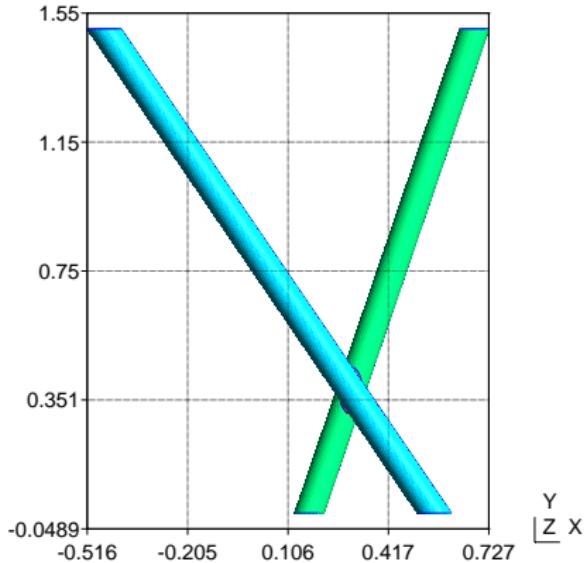


Figure: $\tan \theta_{1,\max}$ & $d_{2,\min}$

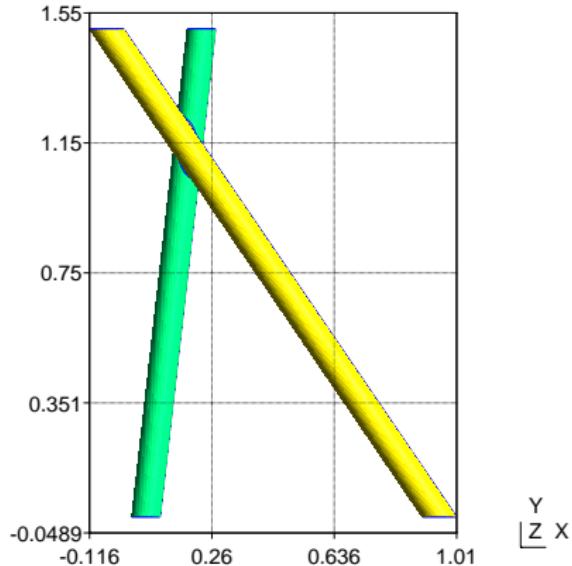


Figure: $\tan \theta_{1,\min}$ & $d_{2,\max}$

10 Uncertain Parameters — Cross-Fiber Model

	Symbol	Value	Uncertainty/Status	Description
Material topology [K. Tang et al.]	$\tan \theta_1$	$\Delta x_1 / \Delta y_1$	$\mathcal{U}\left(\frac{0.25}{2.2}, \frac{0.75}{2.2}\right)$	Fiber1 orientation angle
	r_1	0.05	$\mathcal{U}(0.04, 0.06)$	Fiber1 radius
	d_2	$d((x_1, 0), (x_2, 0))$	$\mathcal{U}(0.90, 1.30)$	Distance between center bases
	r_2	0.05	$\mathcal{U}(0.04, 0.06)$	Fiber2 radius
Material properties (Fillet) [K. Tang et al.]	E	10000	$\mathcal{U}(5000, 25000)$	Young's modulus
	ν	0.3	$\mathcal{U}(0.20, 0.50)$	Poisson's ratio
	(ρ)	0.00		Mass density
	(α)	0.0001		Thermal expansion coefficient
	σ_y	30	$\mathcal{U}(10, 60)$	Yield stress
	(E_T)	100		Hardening modulus
	(Curve param.)	Multiple		Stress–plastic strain curve
	(k)	{12, 1.2}		Thermal conductivity
Material properties (Fiber) [K. Tang et al.]	E	30000	$\mathcal{U}(25000, 35000)$	Young's modulus
	ν	0.3	$\mathcal{U}(0.20, 0.50)$	Poisson's ratio
	(ρ)	0.00		Mass density
	(α)	0.0001		Thermal expansion coefficient
	σ_y	70	$\mathcal{U}(60, 90)$	Yield stress
	(E_T)	100		Hardening modulus
	(Curve param.)	Multiple		Stress–plastic strain curve
	(k)	{12, 1.2}		Thermal conductivity

► QoI: Fracture toughness (K_c)



Input–Output (K_c) Sampling Data Examples

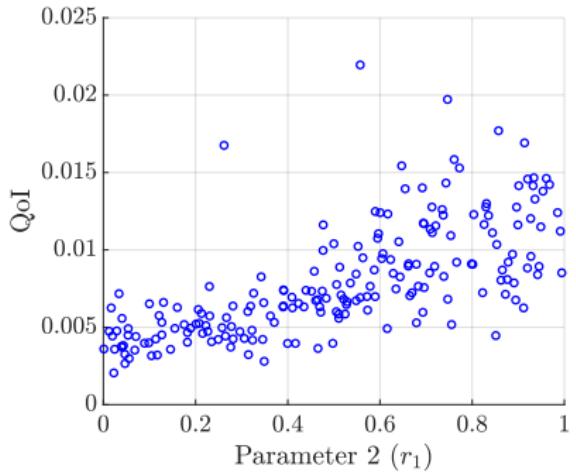


Figure: **Important** param. r_1

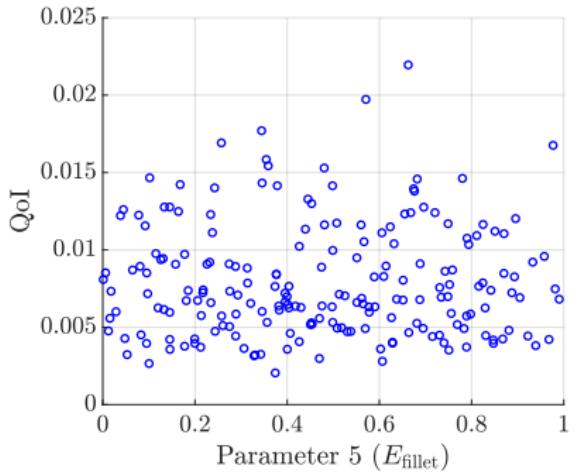
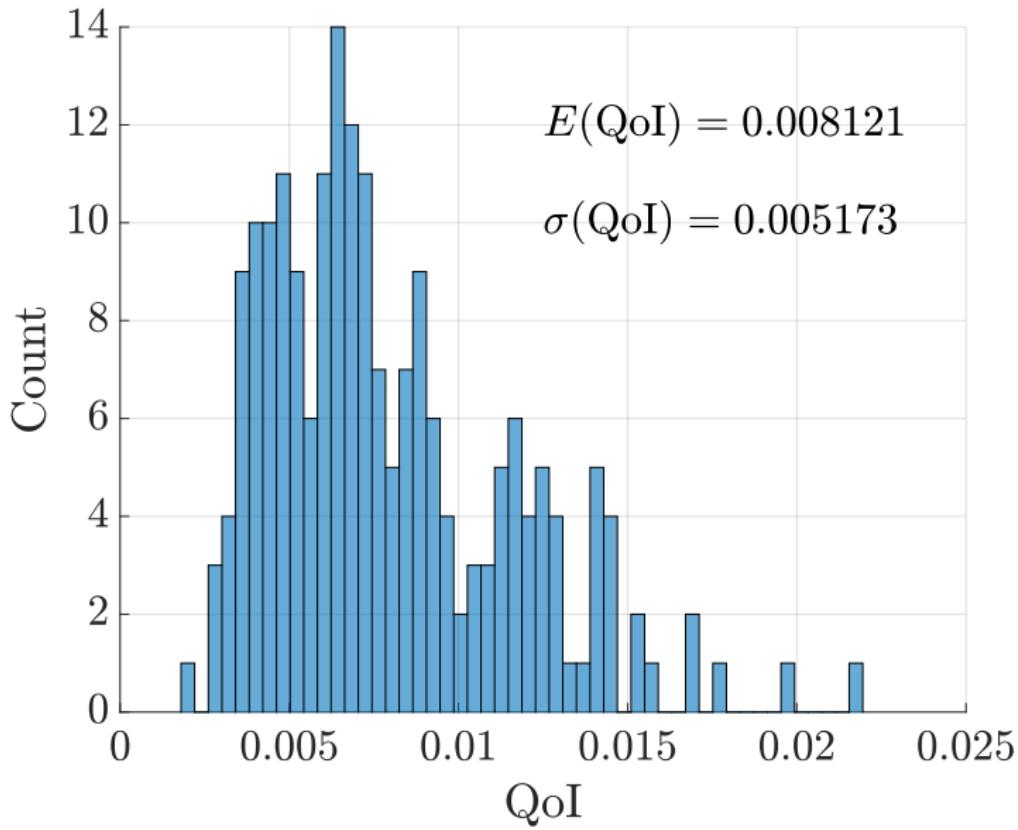
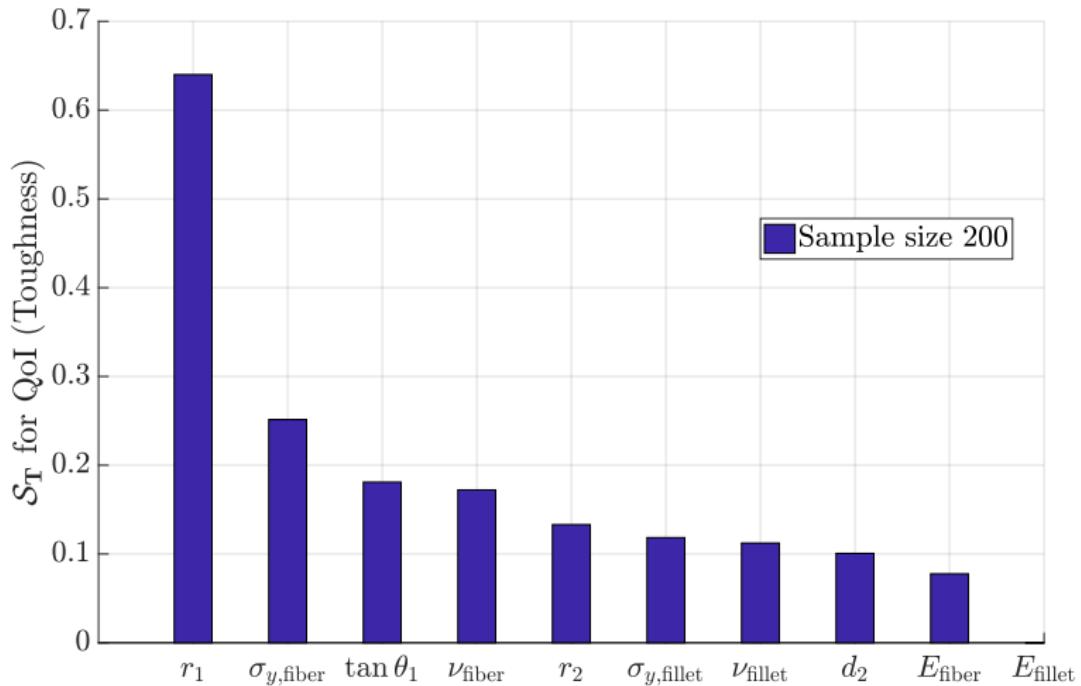


Figure: **Unimportant** param. E_{fillet}

Distribution and Moments of QoI (K_c)



Global Sensitivities – Ranking of Importances



PuMA → Pointwise → WARP3D Workflow

PuMA

- ▶ PuMA (Porous Microstructure Analysis) has been developed to compute effective material properties and perform material response simulations on digitized microstructures of porous media. [Ferguson et al. 2018]
- ▶ NASA software under a US & Foreign release
- ▶ Free research code: https://gitlab.com/jcfergus/PuMA_V3 (**Access needs to be granted**)
- ▶ UNIX operating systems required
- ▶ Typically runs remotely on NNSA clusters
- ▶ GCC version 4.4.7 or later
- ▶ Default Installation Option: Full installation of PuMA C++ Library
- ▶ Recommended Computer Specifications: 8gb of ram for small simulations (600^3 or smaller) 16-32gb of ram for medium simulations (800^3 range) 32+gb of ram for large simulations (above 1000^3)
- ▶ Simulation time varies
 - It takes ~ secs - mins to generate a medium-sized random fiber structure (single processor)
 - Anticipate much longer time for large simulations

PuMA & surface mesh generation

► INPUT - test_projCEESD.cpp

- This source cpp file contains all “hard-coded” parameters (for now), e.g. domain size, fiber diameter, etc.

► OUTPUT - RandomFibers_straightCircle.stl

- A single STL surface mesh file

INPUT

- test_projCEESD.cpp
 - "input.straightCircle
(40, 40, 40, 3, 1,
40, 0, 90, 90, 60,
true, 0.35, 999);"
 - Domain size
 - Fiber diameter + uncertainty
 - Fiber length + uncertainty
 - Orientation
 - Porosity

PuMA

OUTPUT

- STL surface mesh:
RandomFibers_straightCircle.stl
 - "puma::export_STL"
 - An STL file describes a raw, unstructured triangulated surface by the unit normal and vertices (ordered by the right-hand rule) of the triangles using a three-dimensional Cartesian coordinate system

Pointwise

- ▶ Mesh generation software
- ▶ Commercial: <https://www.pointwise.com>
- ▶ We use it to make STL->Patran conversion by creating a volume mesh (tet4)
- ▶ Available for Windows, Linux, and Mac
- ▶ Typically runs locally on laptops using GUI
- ▶ Scriptable?
- ▶ Processing time can be long
 - It takes me ~ an hour to just import an STL file with 3–4M nodes
- ▶ Gmsh is faster (open source and scriptable). However, does not support Patran as export format
 - (I used Gmsh to create/optimize a tet4 volume mesh and export it in a Nastran format, then used Pointwise to convert from Nastran to Patran)
- ▶ We are currently looking for (and will ultimately need) a scriptable meshing tool that can be used remotely as part of automated UQ analyses on clusters

Pointwise & volume mesh generation

- ▶ **INPUT** - RandomFibers_straightCircle.stl
 - A single STL surface mesh file
- ▶ **OUTPUT** - RandomFibers_straightCircle.pat
 - A single Patran volume mesh file (ASCII)

INPUT

- STL surface mesh:
RandomFibers_straightCircl
e.stl

OUTPUT

- Patran volume mesh:
RandomFibers_straightCircl
e.pat (tet4)

Pointwise/
Gmsh

WARP3D

- ▶ 3D Nonlinear Finite Element Analysis of Solids (Static/Dynamic)
- ▶ Open source code: <https://github.com/rhdodds/warp3d>
- ▶ Available for Windows, Linux, and Mac
- ▶ Typically runs remotely on NNSA clusters
 - To recompile the threads-only version from source, it requires
 - Intel Fortran 18.0.# OR Intel Fortran 19.0.2 (or newer), ** OR **
 - GNU gfortran 7.3 (or newer)
 - To recompile the MPI + threads (hybrid) version, it requires
 - Intel Fortran 19.0.3 (or newer) ** AND ** the (free) Intel MPI 19.0.3 (or newer)
- ▶ Simulation time varies
 - It takes mins to simulate 1k loading steps for a 145477-element problem (single processor)
 - Anticipate much longer time for large simulations
- ▶ WARP3D contains
 - Patran neutral file-to-WARP3D translator program (pre-processing via “patwarp.go”, only works with Intel compilers)
 - WARP3D results-to-ParaView program (post-processing via “python warp3d2exii”)

WARP3D pre-processing

- ▶ **INPUT** - RandomFibers_straightCircle.pat
 - A single ASCII Patran volume mesh file (limited to 4M nodes)
- ▶ **OUTPUT** - All necessary ASCII input files of a WARP3D simulation
 - warp3d_input – Main input file (we will need to specify material definitions, loading patterns, finite element analysis parameters, etc.)
 - coords.inp – Mesh node ID & coordinates
 - incid.inp – Mesh element ID & related nodes ID
 - constraints.inp – Boundary conditions, e.g. fixed nodes, fixed planes

INPUT

- Patran volume mesh:
RandomFibers_straightCircle.pat (tet4)
 - Limited to 4M nodes

WARP3D -
patwarp.go

OUTPUT

- warp3d_input
 - Add material
 - Add loading etc.
- coords.inp
 - Node coordinates
- incid.inp
 - Element-NodeID
- constraints.inp
 - Add boundary conditions

WARP3D static/dynamic finite element analysis

INPUT

- warp3d_input
 - Material properties
 - Stress-strain curve
 - Element type (tet, hex, linear/nonlinear)
 - Element integration order
 - Initial conditions (T, stress, etc.)
 - Loading pattern (force, T, constraints, etc.)
 - crack growth parameters
 - nonlinear analysis parameters
- coords.inp
 - Node coordinates
- incid.inp
 - Element-NodeID
- constraints.inp
 - Boundary conditions

WARP3D

OUTPUT

- Series of stream files
 - wee0000100_stream (strain @ element)
 - wes0000100_stream (stress @ element)
 - wnd0000100_stream (displacement @ node)
 - wnt0000100_stream (temp @ node)
- RandomFibers_straightCircle.text (flat text file - mesh)

WARP3D post-processing

INPUT

- Series of stream files
 - wee0000100_stream
(strain @ element)
 - wes0000100_stream
(stress @ element)
 - wnd0000100_stream
(displacement @ node)
 - wnt0000100_stream
(temp @ node)
- RandomFibers_straightCircl
e.text (flat text file -
mesh)

OUTPUT

- RandomFibers_straightCircl
e.exo (Exodus format)

Python
warp3d2exii