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## **B.Tech DEGREE EXAMINATION, DECEMBER 2023**

Fifth to Seventh Semester

## 18CSE353T - DIGITAL IMAGE PROCESSING.

(For the candidates admitted during the academic year 2020 - 2021 & 2021 - 2022)

## Note:

i. Part - A should be answered in OMR sheet within first 40 minutes and OMR sheet should be handed over to hall invigilator at the end of 40<sup>th</sup> minute.
 ii. Part - B and Part - C should be answered in answer booklet.

Time: 3 Hours					Max. Marks: 100			
PART - A $(20 \times 1 = 20 \text{ Marks})$ Answer all Questions			Marks	s BL	СО			
1.	What is the first and foremost step in Image (A) Image restoration (C) Image acquisition	Processing? (B) Image enhancement (D) Segmentation	1	1	1			
2.	1024 X 1024 image has resolution of (A) 1348576 (C) 1148576	(B) 1248576 (D) 1048573	.1	2	1			
3.	An image is considered to be a function of a (A) Height of image (C) Amplitude of image	(x,y), where a represents:  (B) Width of image  (D) Resolution of image	1	1	1			
4.	A pixel p at coordinates (x, y) has neighbors y+1), (x+1, y-1), (x-1, y+1), (x-1, y-1) This s (A) 4-neighbors of p (C) Diagonal neighbors	ors whose coordinates are given by:(x+1 set of pixels is called (B) 8-neighbors (D) Column neighbors	, 1	2	1			
5.	If s and r are the pixel values of the output then formula for Logarithmic transformation (A) $s = clog(255+r)$ (C) $s = clog(r+1)$	and the input image and c is a constant is given as? (B) s = clogr (D) s = log(r)	, 1	2	2			
6.	What is the sum of all components of a norm (A) 1 (C) 0	nalized histogram? (B) -1 (D) 10	1	2	2			
7.	In linear spatial filtering, what is the pixel of the mask coefficient w (1, -1), assuming a 3 (A) f (x, -y) (C) f (x, y-1)	f the image under mask corresponding to *3 mask?  (B) f (x+1, y)  (D) f (x+1, y-1)	0 1	2	2			
8.	The output of a smoothing, linear spatial contained in the neighborhood of the filter n (A) Sum (C) Dot Product	filtering is of the pixel nask.  (B) Average  (D) Product	s 1	1	2			
9.	Gradient computation equation is(A)  Gx - Gy  (C)  Gx X Gy	(B)  Gx / Gy  (D)  Gx + Gy	1 7	2	3			
10.	Band reject filters are used where the noise (A) Known (C) Taken	components are usually (B) Unknown (D) Reject	1	1	3			

11.	Gaussian Noise is referred to as (A) red noise (C) normal noise	<ul><li>(B) white noise</li><li>(D) black noise</li></ul>	1	1	3
12.	Power spectra and noise of undegraded image (A) Notch filter (C) Band pass filter	ge must be known as  (B) Wiener filter  (D) Band Reject filter	1	1	3
13.	Which of the following is the abbreviation of (A) Joint Photographs Expansion Group  (C) Lint Photographic Expanded Control	(B) Joint Photographic Experts Group	1	1	3
	(C) Joint Photographic Expanded Group	(D) Joint Photographic Expansion Group			
14.	In the formula 1-(1/c), C is the (A) complex ratio (C) constant	<ul><li>(B) compression ratio</li><li>(D) condition</li></ul>	1	2	4
15.	Image compression comprised of (A) Encoder (C) Frames	<ul><li>(B) Decoder</li><li>(D) Both Encoder and Decoder</li></ul>	1	2	4
16	Formula $pr = n/MN$ represents the		1	2	4
10.	(A) coding redundancy (C) temporal redundancy	<ul><li>(B) spatial redundancy</li><li>(D) irrelevant info</li></ul>			
17.	Based on the 4-directional code, the first das:	ifference of smallest magnitude is called	1	2	5
	(A) Shape number (C) Difference	<ul><li>(B) Chain number</li><li>(D) Difference number</li></ul>			
18.	Which of the following technique of b interpretation of boundary shape?  (A) Fourier transform  (C) Laplace transform	oundary descriptions has the physical  (B) Statistical moments (D) Curvature	1	2	5
19.	Which of the following measures are not use (A) Mean and median of grey values	ed to describe a region?  (B) Minimum and maximum of grey values	1	2	5
	(C) Number of pixels alone	(D) Number of pixels above and below mean			
20.	What is the order of the shape number of a r of 3×3?	ectangular boundary with the dimensions	1	1	5
	(A) 3 (C) 9	(B) 6 (D) 12			
	$PART - B (5 \times 4 = 20)$	) Marks)	Mark	s BL	СО
	Answer any 5 Que				
21.	Draw one example for 4-adjacency and 8-ad	ljacency and briefly explain.	4	3	1
22.	Illustrate the following transformations 1. Log transformation [ 2 marks] 2. Power law transformation [2 marks]		4	2	2
23.	Compare the following noise models  1. Gaussian noise [ 2 marks]  2. Salt and pepper noise [ 2 marks]		4	4	3
24.	Differentiate the following coding technique  1. Lossy predictive coding [ 2 marks ]  2. Run Length coding [ 2 marks ]	es	4	4	4
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25.	Describe Fourier descriptors	4	2	5
26.	What are the coding systems in JPEG?	4	2	3
27.	and the second of the second o	4	2	3
	PART - C ( $5 \times 12 = 60$ Marks) Answer all Questions	Marl	ks BL	CO
28.	(a) How is an image quantized? Explain. What is the effect on the image quantization levels if it is reduced?  (OR)	12	2	1
	(b) Describe the following  1. 4-adjacency [3 marks]  2. 8-adjacency [3 marks]  3. m-adjacency [3 marks]  4. Euclidean distance [3 marks]			
29.	(a) Explain gray level transformations in Digital Image Processing with an example  (OR)	12	2	2
	(b) Describe Histogram equalization with a sample input image			
30.	(a) Derive a Weiner filter for image restoration and specify its advantages over inverse filter.	12	3	3
	(OR)  (b) How do you perform Watershed segmentation algorithm and list out its applications.			
31.	coding and calculate the final bits (OR)	12	3	4
	<ul> <li>(b) Encode the following using Arithmetic coding message: went.</li> <li>Probability: e - 0.3, n-0.3, t-0.2, w-0.1,0.1</li> </ul>			_
32.	(a) Explain about Polygonal approximation with an example (OR)	12	2	5
	<ul> <li>(b) Write short notes on the following</li> <li>1. Signatures [ 6 marks ]</li> <li>2. Boundary segments [ 6 marks ]</li> </ul>			

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