

**Advanced Image Processing HW1**  
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## 1 Question 1

For any  $s$ -sparse vector  $x$ ,

$$Ax = A_S x_S$$

where  $S$  is the set of indices with non zero value and  $|S| \leq s$

Consider the matrix  $B = A_S^T A_S$ , where  $b_{ij} = \langle a_i, a_j \rangle$  and  $b_{ii} = \|a_i^2\| = 1$  due to normalization of  $A$ .

By Gershgorin's Disk Theorem, every eigenvalue of the matrix  $A_S^T A_S$  lies in the the union of  $D(b_{ii}, r_i)$  where  $r_i$  is sum of absolute values of off-diagonal elements of the  $i$ -th row.

$$r_i = \sum_{j=1, j \neq i}^s \langle a_i, a_j \rangle \leq \mu(s-1)$$

Since the matrix  $A_S^T A_S$  is positive semidefinite, it has positive real eigenvalues and they lie in the range  $[1 - \mu(s-1), 1 + \mu(s-1)]$

Thus for every  $s$ -sparse vector  $x$ , we can say that

$$(1 - \mu(s-1))\|x\|^2 \leq \|Ax\|^2 \leq (1 + \mu(s-1))\|x\|^2$$

which implies  $\delta_s \leq \mu(s-1)$

## 2 Question 2

Given  $A \in \mathbb{R}^{m \times n}$  with order- $s$  isometry constant  $\delta_s$ , then:

$$\forall x, \|x\|_0 \leq s,$$

$$Ax = A_S x \text{ for some } S \subseteq [n], |S| = s$$

Given the isometry constant  $\delta_s$  of  $A$ , we have:

$$\forall s\text{-sparse } x, (1 - \delta_s) \leq \frac{\|Ax\|^2}{\|x\|^2} \leq (1 + \delta_s)$$

But for such  $x$ ,  $\|Ax\|^2 = \|A_S x\|^2 = x^T A_S^T A_S x$  and the minimum and maximum eigenvalues of  $A_S^T A_S$  ( $\lambda_{S\min}$  and  $\lambda_{S\max}$  respectively) are equal to:

$$\max_x \text{ and } \min_x \frac{\|A_S x\|^2}{\|x\|^2} \text{ respectively}$$

Therefore,

$$\lambda_{\min} = \min_{S, x} \frac{\|A_S x\|^2}{\|x\|^2} = \min_x \frac{\|Ax\|^2}{\|x\|^2} \text{ and hence } (1 - \delta_s) \leq \lambda_{\min}$$

Similarly,

$$\lambda_{\max} \leq (1 + \delta_s)$$

Hence,  $\delta_s \geq (1 - \lambda_{\min})$  as well as  $(\lambda_{\max} - 1)$ .  $\therefore \delta_s \geq \max(1 - \lambda_{\min}, \lambda_{\max} - 1)$ . But since  $\delta_s$  is the minimum such number, it is equal to  $\max(1 - \lambda_{\min}, \lambda_{\max} - 1)$

### 3 Question 3

Since not all subsets were checked, the  $\lambda$ s obtained are such that

$$\lambda_{\min} \geq \min_x \frac{\|Ax\|^2}{\|x\|^2}$$

and

$$\lambda_{\max} \leq \max_x \frac{\|Ax\|^2}{\|x\|^2}$$

Therefore,  $\lambda_{\min} \geq (1 - \delta_s)$  and  $\lambda_{\max} \leq (1 + \delta_s)$  or  $\delta_s \geq (1 - \lambda_{\min})$  and  $\delta_s \geq (\lambda_{\max} - 1)$  giving us  $\delta_s \geq \max(1 - \lambda_{\min}, \lambda_{\max} - 1)$  or

$$\delta_s \geq \hat{\delta}_s$$

### 4 Question 4

(1) Even though the values of  $\|\theta - \theta_S\|_1$  decreases as  $S$  increases, the constants  $C_1, C_2$  are increasing functions of  $S$  itself, and thus increasing  $S$  doesn't directly translate to decreasing error bound. Further, increasing  $S$  beyond the limit  $0.5(1 - 1/\mu)$  renders the Theorem 5 useless.

(2) Increasing measurements  $m$  decreases the value of  $\mu(\Phi\Psi)$  since we have more dimensions to fit  $n$  vectors and prevent them from being correlated too much. Decreasing  $\mu$  increases the value of  $S_{\max}$  and thus reduces the error bound.

(3) Theorem 5 is more useful since it has a higher value of  $S_{\max}$ . As per the theorem, as we can recover  $\theta$  which are  $S$ -sparse with a very high accuracy, a higher bound on  $S$  is more useful.

(4) If we are setting our  $\epsilon$  to below the actual noise value, we may not even obtain a solution to the P2 problem or obtain a solution that is completely useless, and the theorem doesn't help in that case. That is why it is preferred to keep  $\epsilon$  such that the noise  $\eta \leq \epsilon$  with a very high probability.

### 5 Question 5

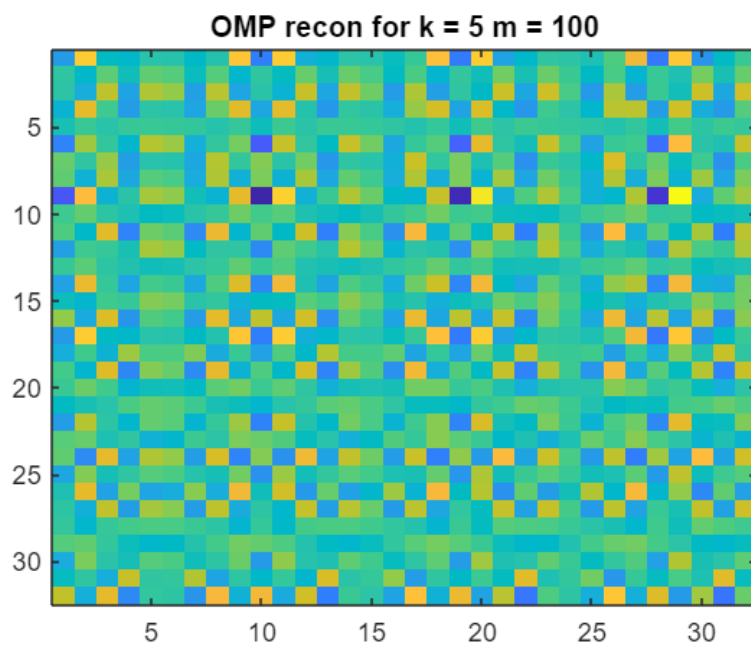
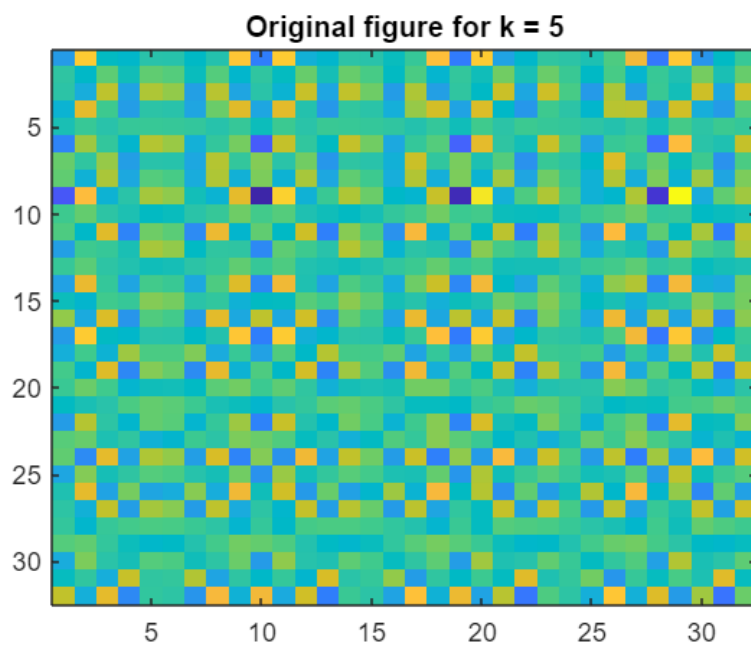
Title of the paper : Underwater Image Enhancement Using Deep Transfer Learning Based on a Color Restoration Model

Publication : IEEE Journal of Oceanic Engineering ( Volume: 48, Issue: 2, April 2023)

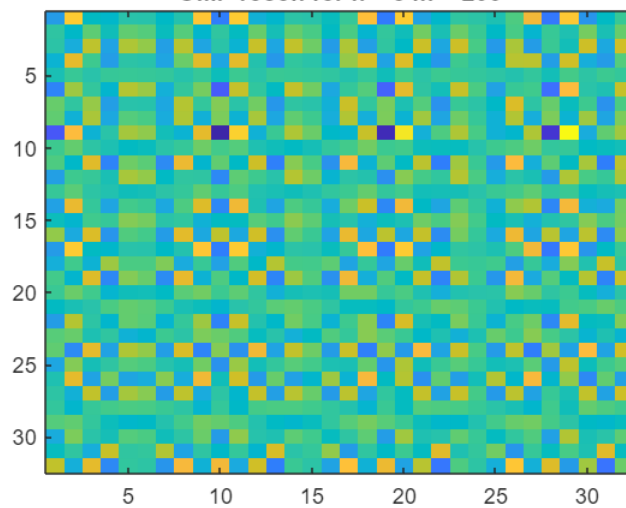
Due to the reflection and attenuation of light when propagating in water, the images captured by the visual system of an underwater vehicle in the complex underwater environment usually suffer from low visibility, blurred details, and color distortion. The paper aims to enhance and restore such underwater images using a Transfer Learning based model.

## 6 Question 6

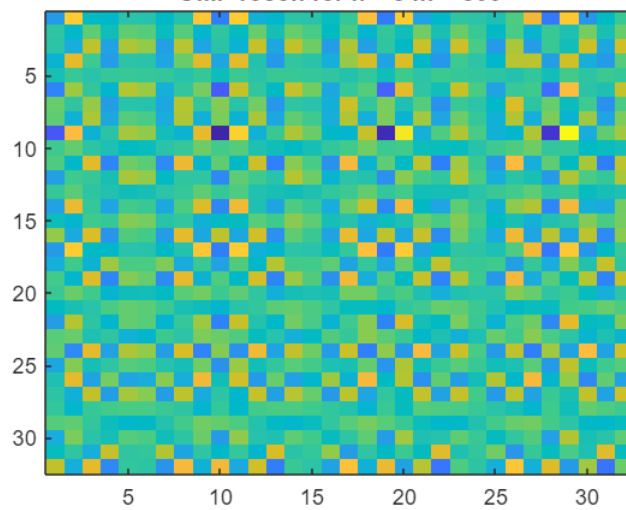
The following are the results for the **OMP** algorithm.



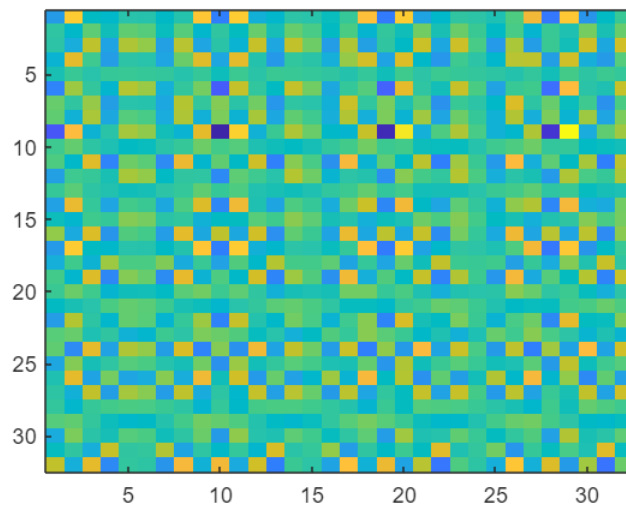
OMP recon for  $k = 5$   $m = 200$

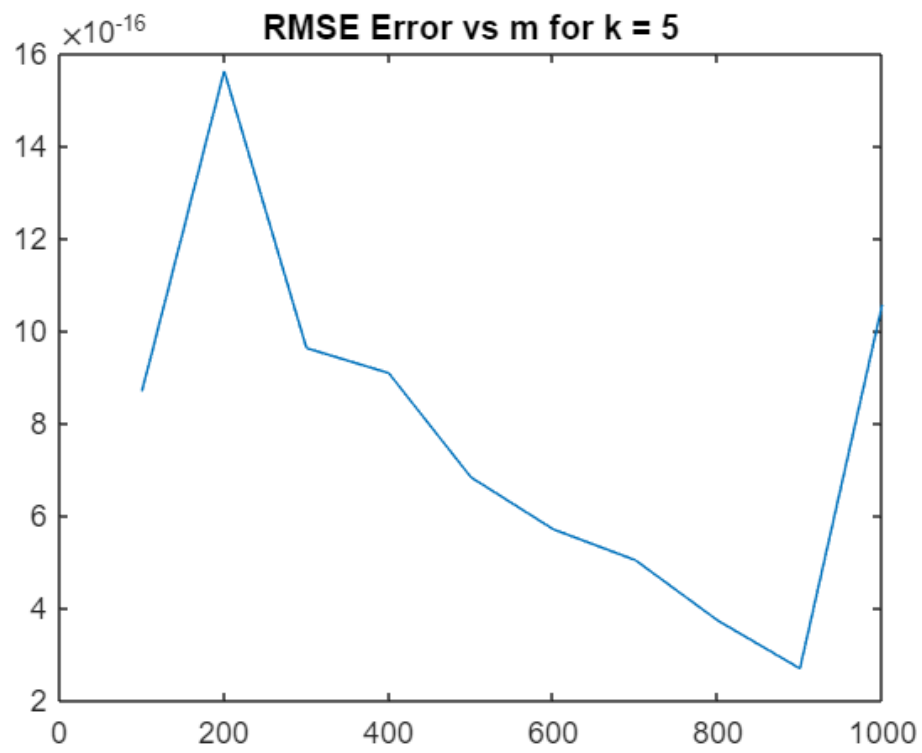
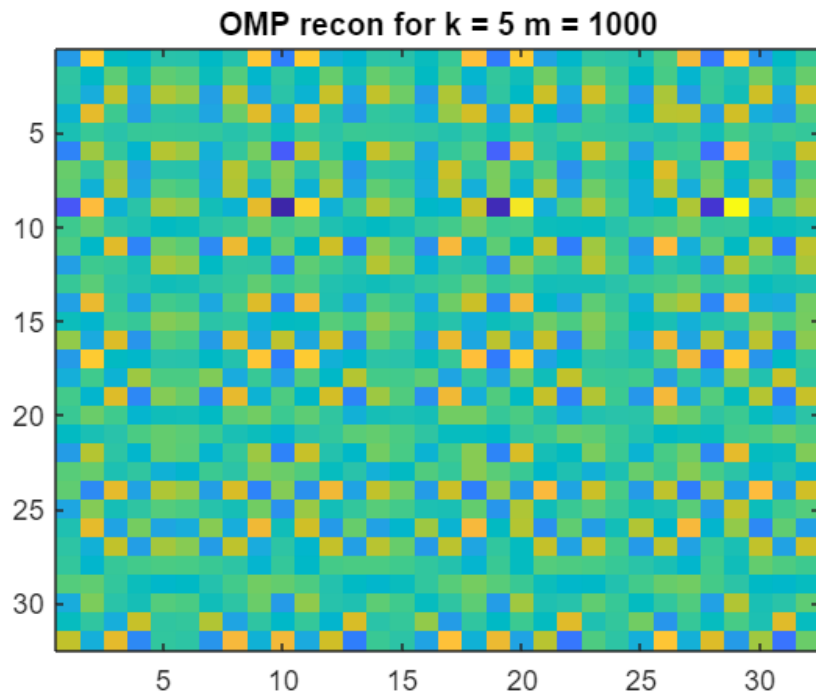


OMP recon for  $k = 5$   $m = 300$

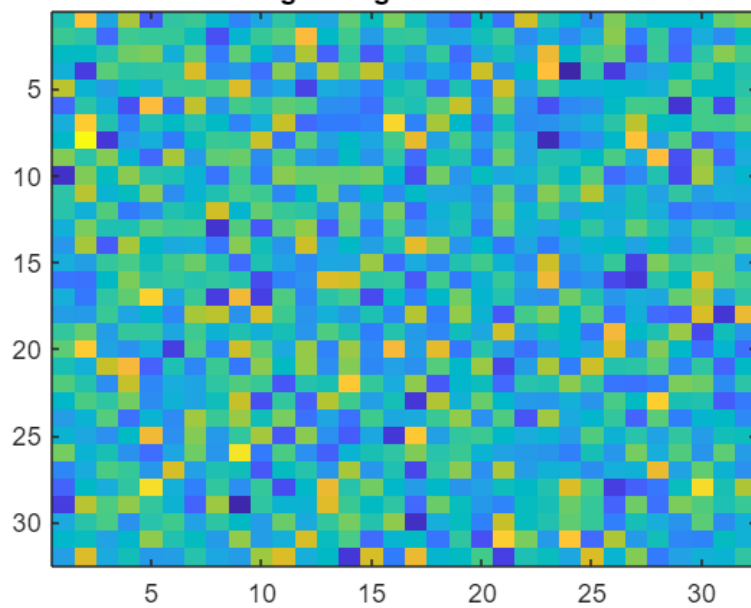


OMP recon for  $k = 5$   $m = 400$

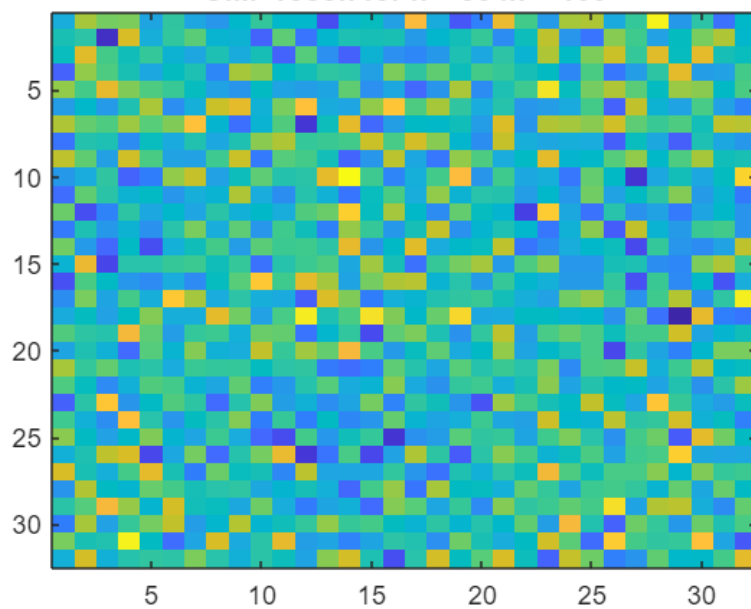


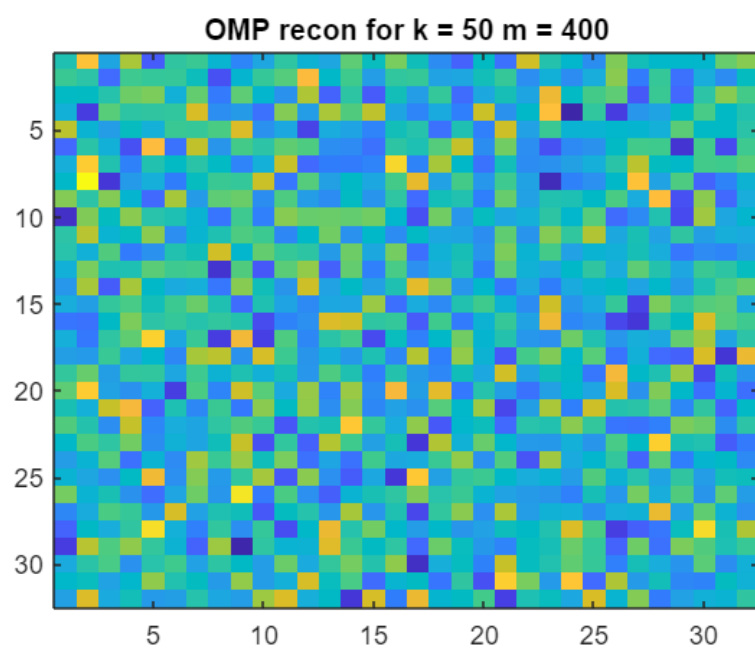
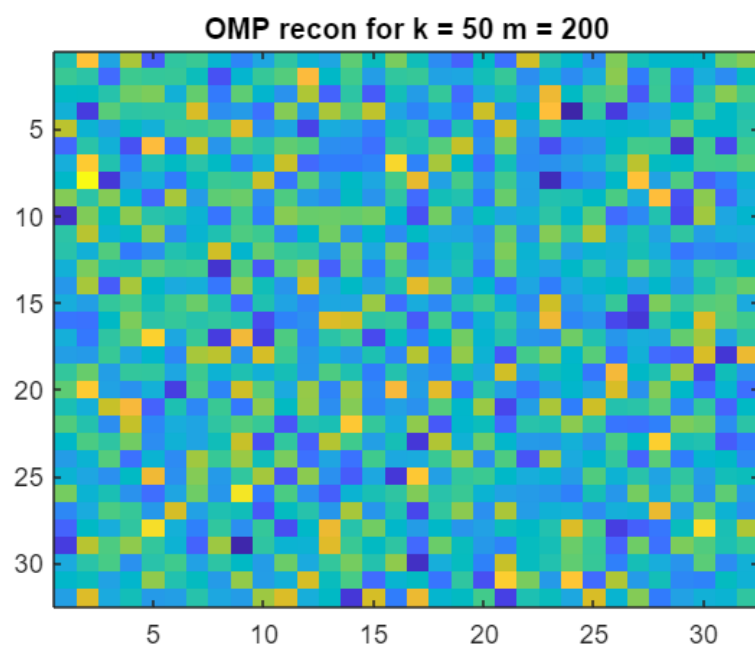


Original figure for  $k = 50$



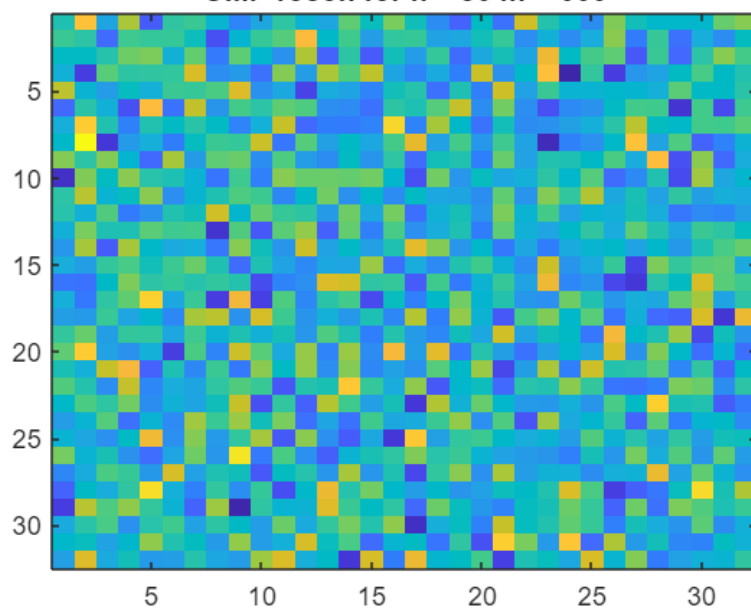
OMP recon for  $k = 50$   $m = 100$



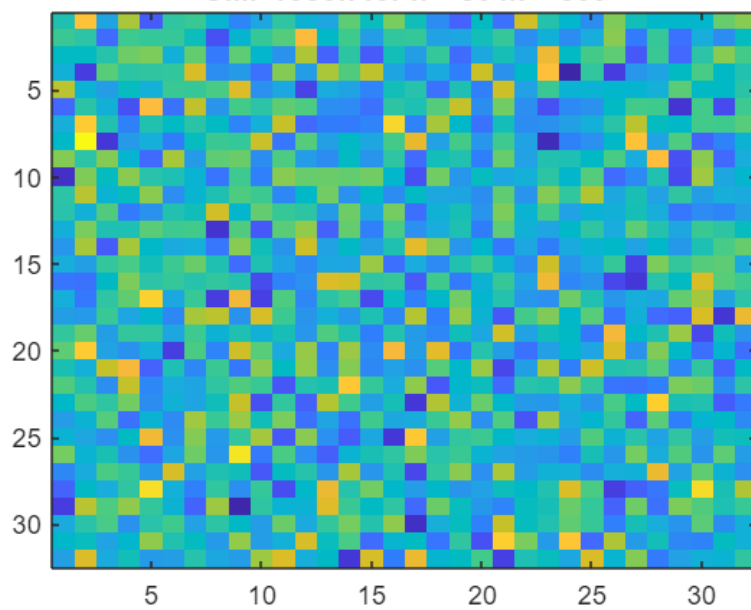


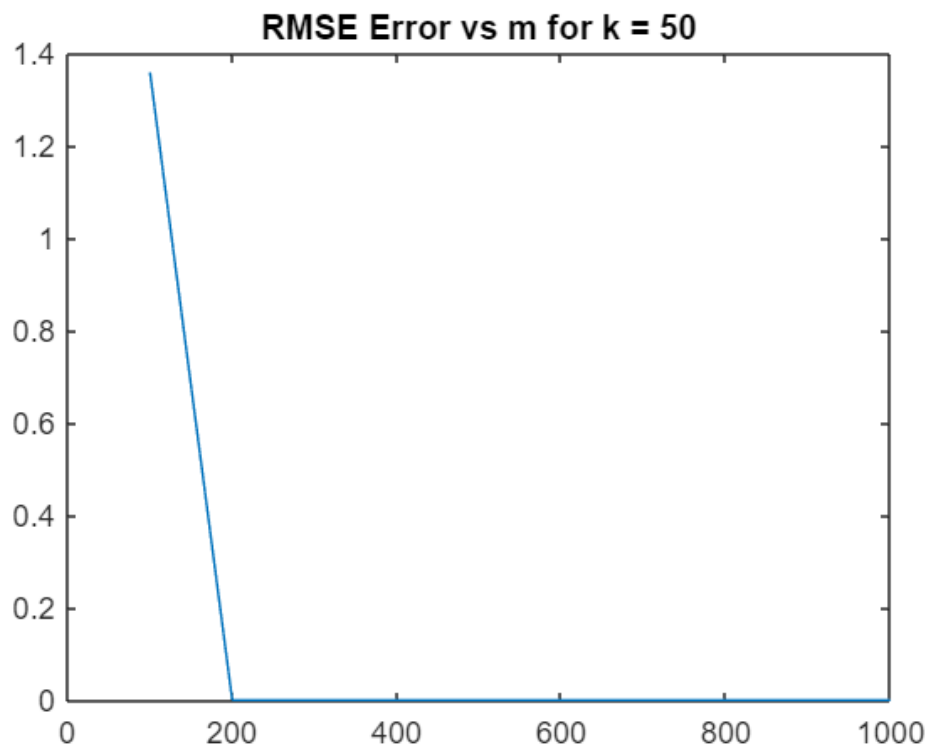
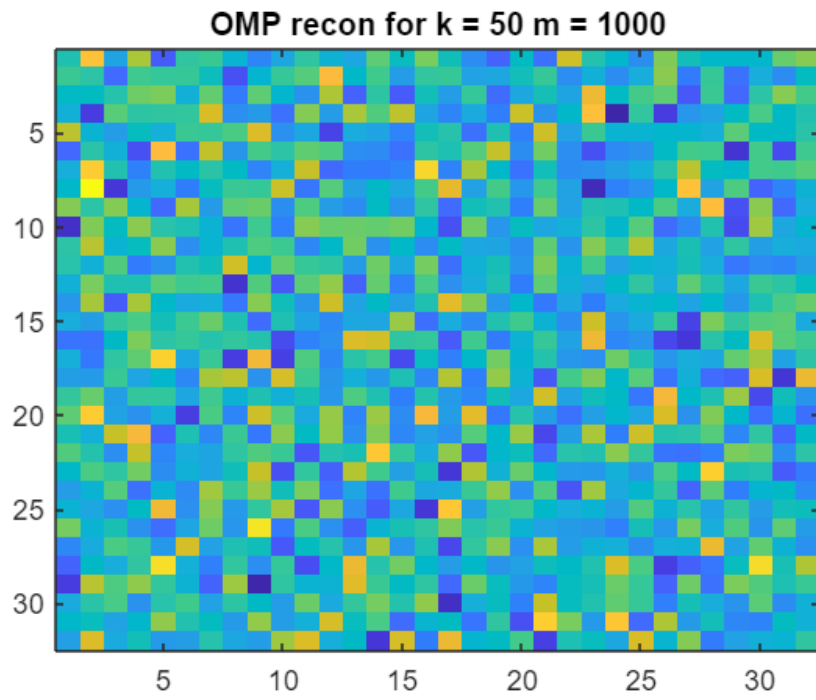


OMP recon for  $k = 50$   $m = 600$

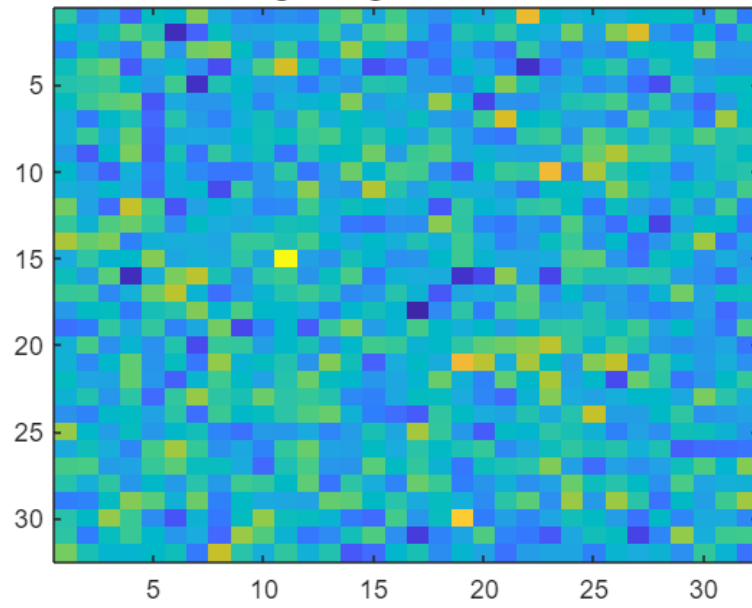


OMP recon for  $k = 50$   $m = 800$

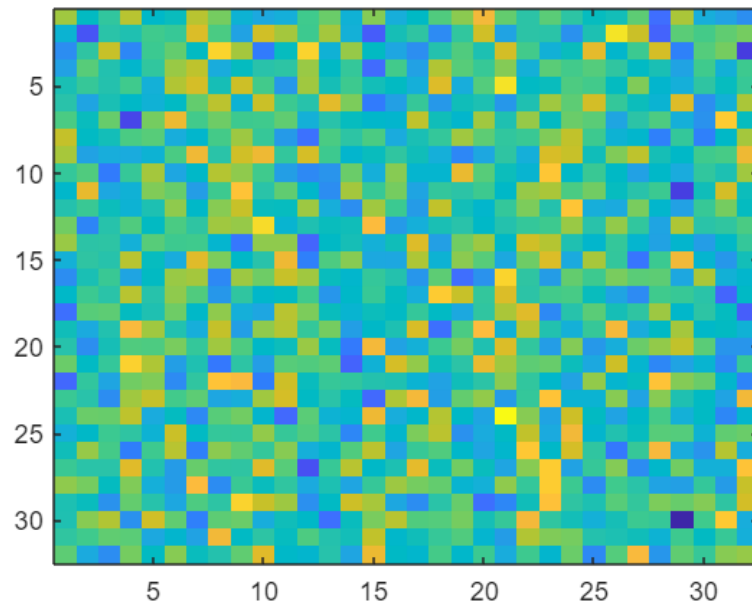


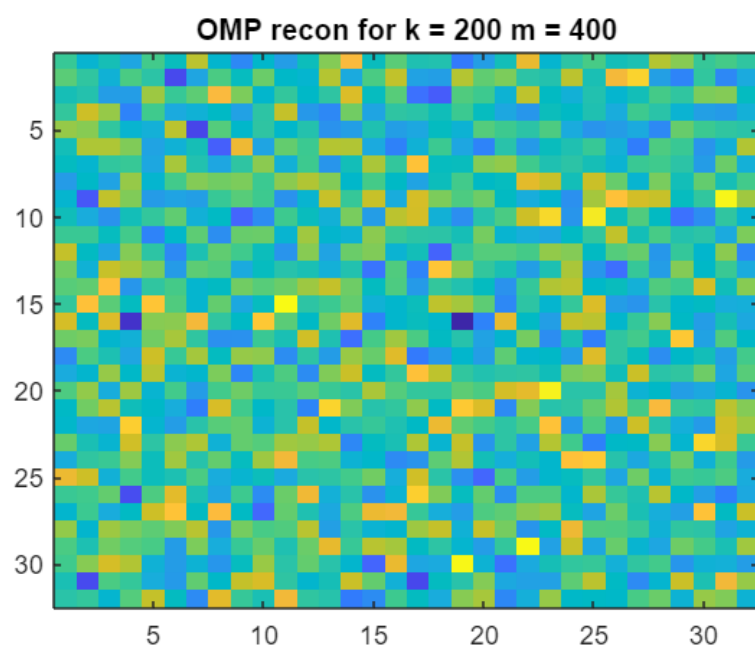
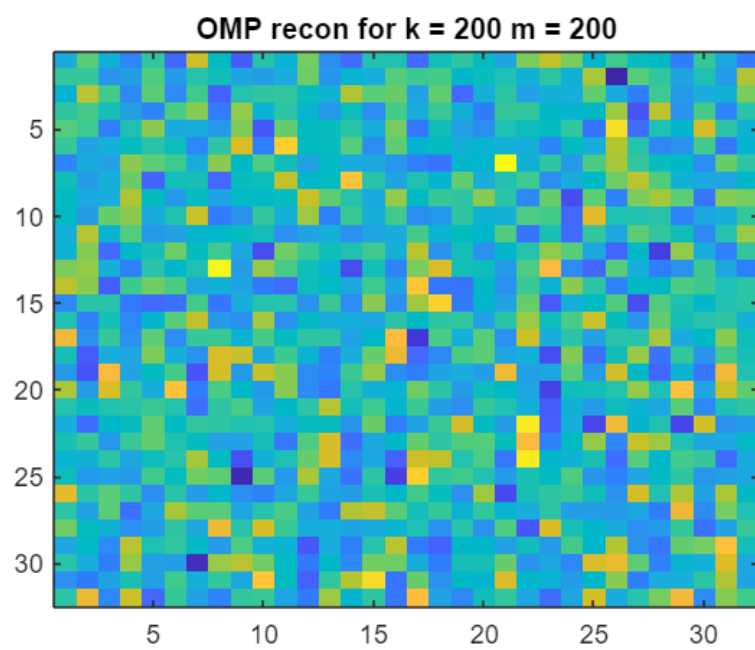


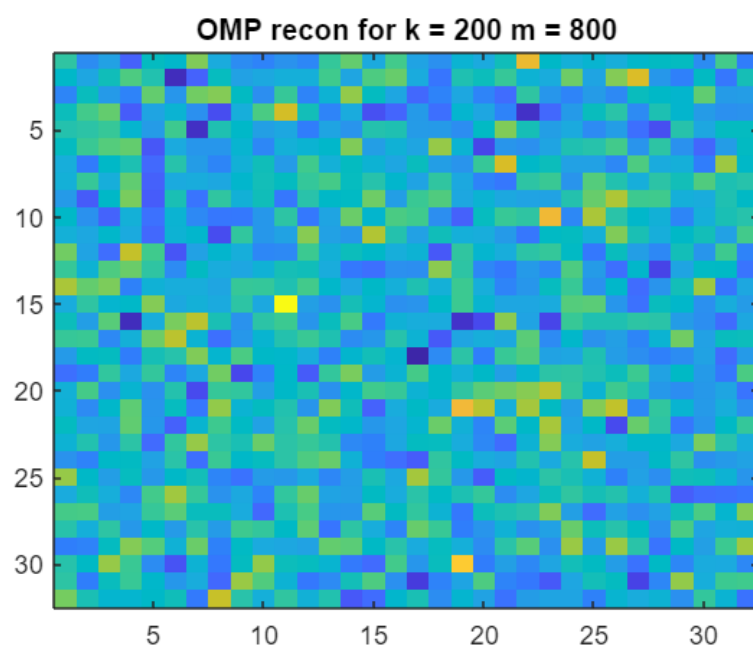
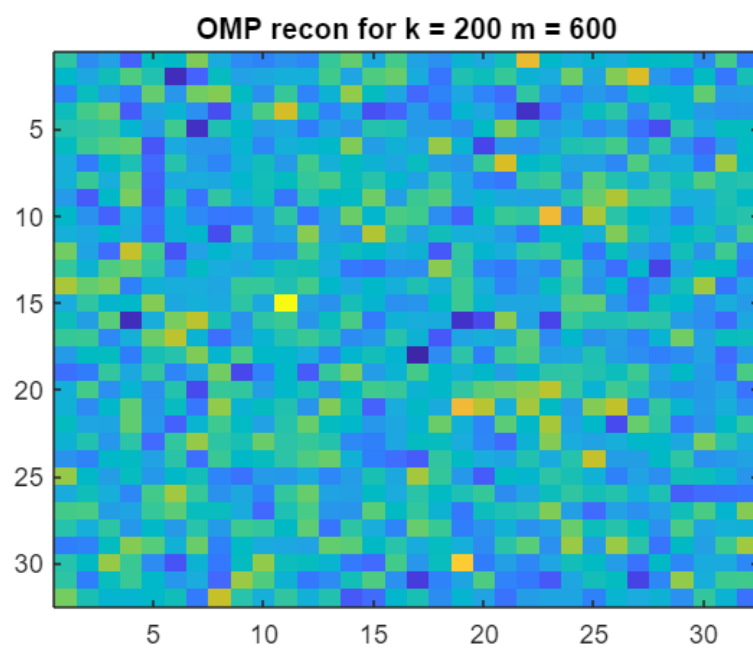
Original figure for  $k = 200$

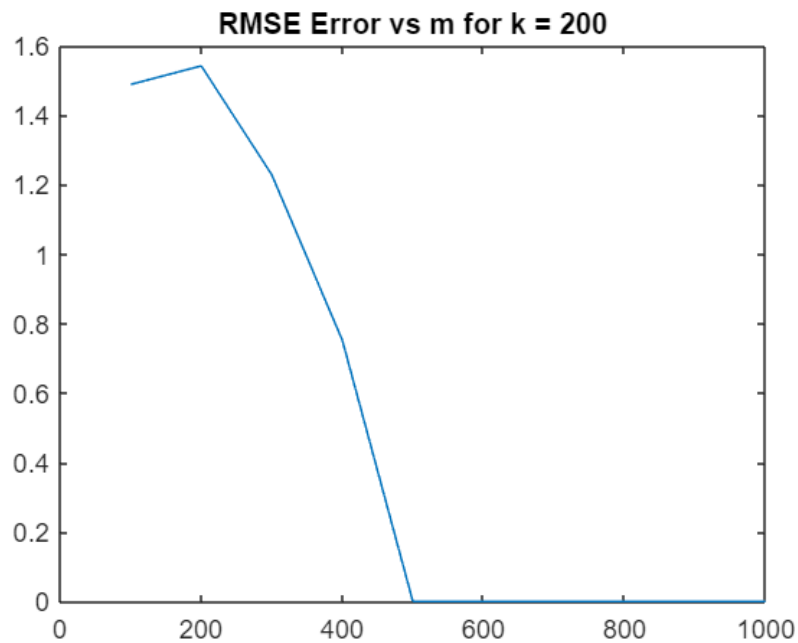
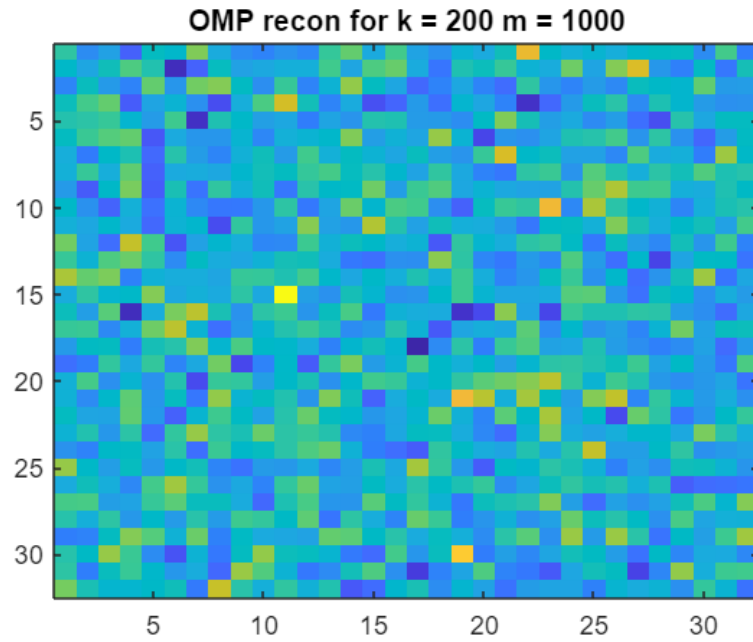


OMP recon for  $k = 200$   $m = 100$







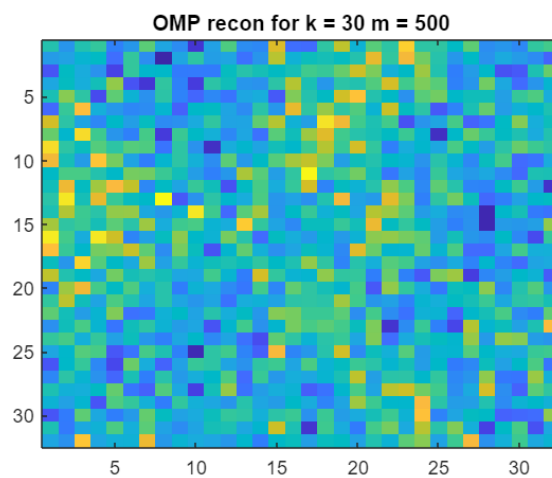
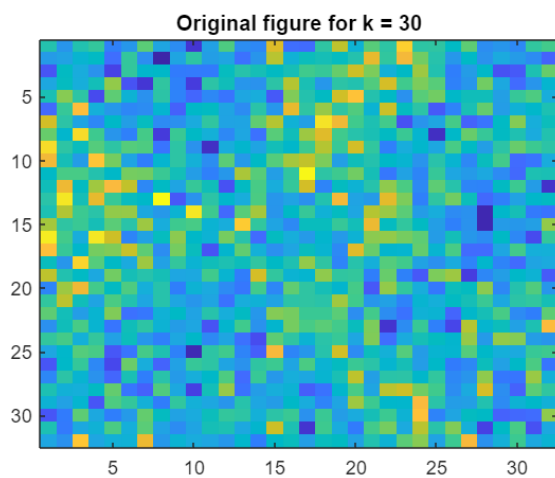
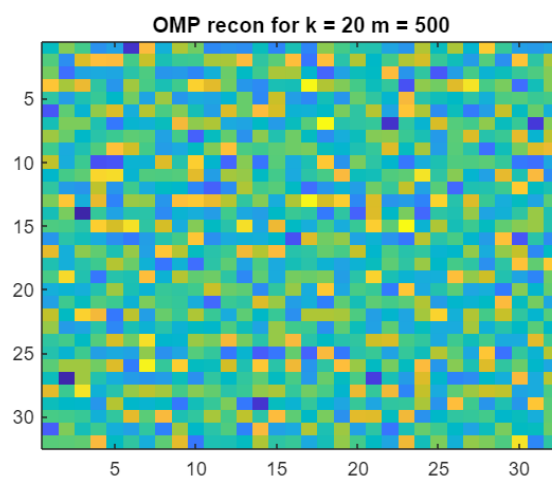
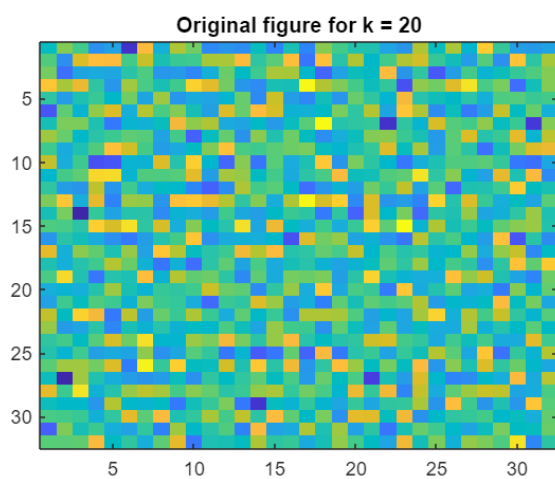
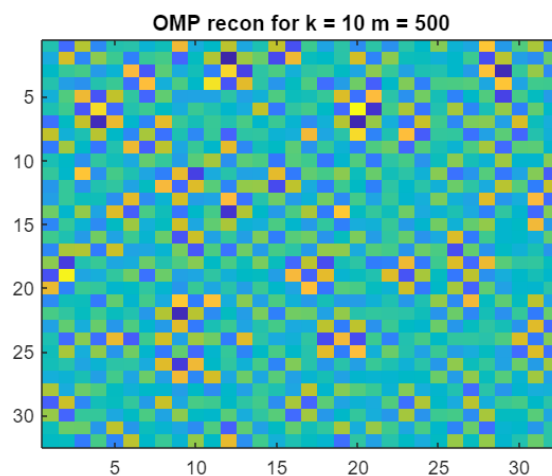
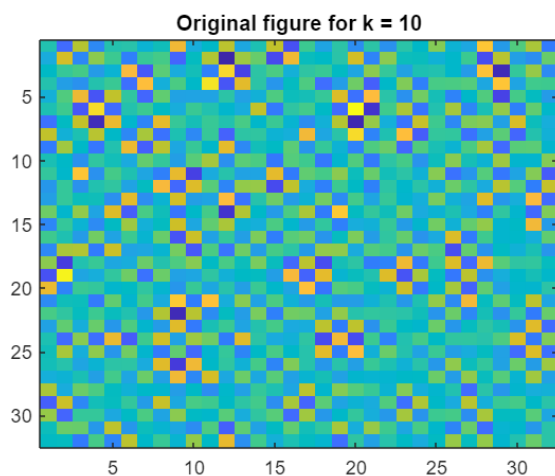
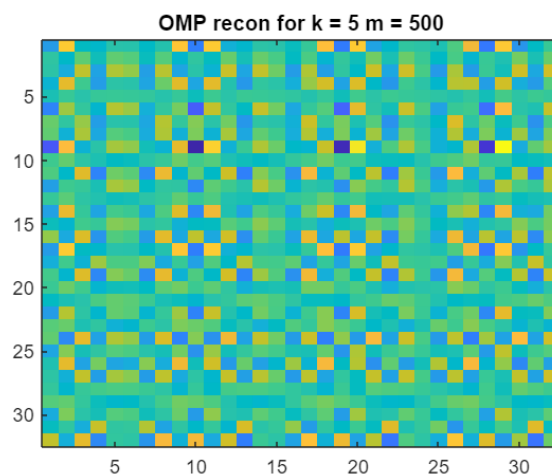
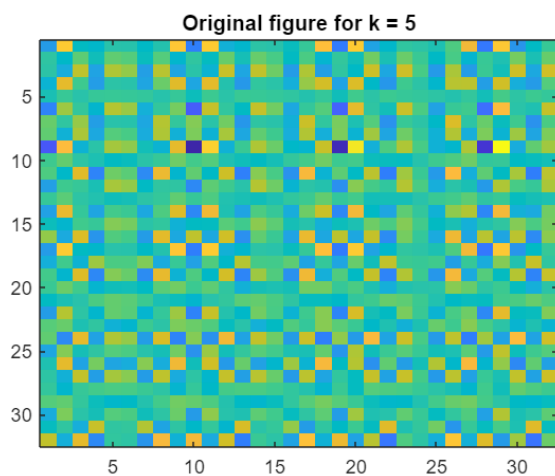


The above plots can be explained as follows:

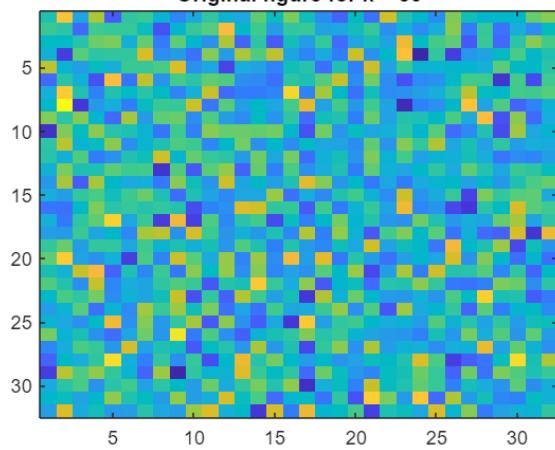
As  $m$  varies (increases), we see an increase in accuracy of the recovered images from compressed measurements. In particular, if

$$m \geq Cs \log n / \delta$$

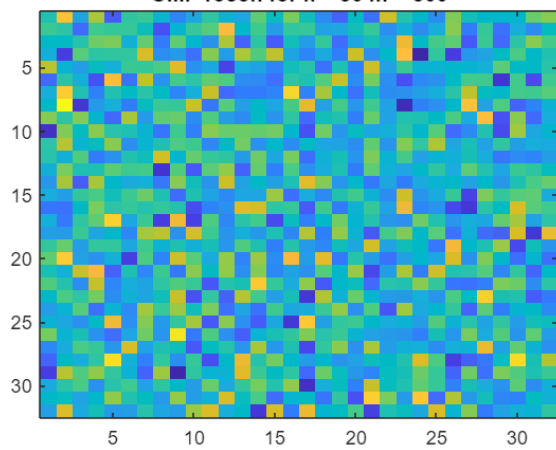
then an  $s$  sparse vector can be recovered exactly with probability  $\geq 1 - 2\delta$ . Thus a larger  $m$  allows for a smaller  $\delta$  and a higher probability of accurate recovery.



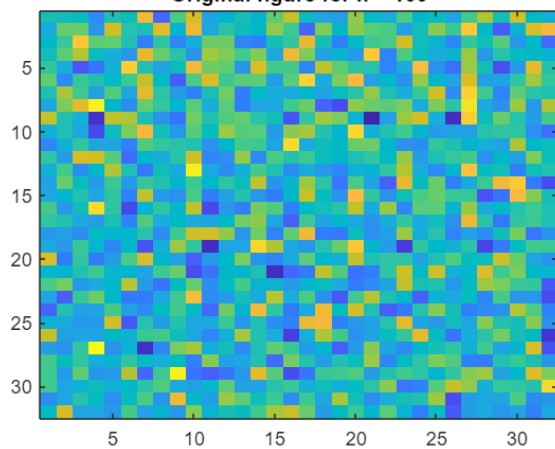
Original figure for  $k = 50$



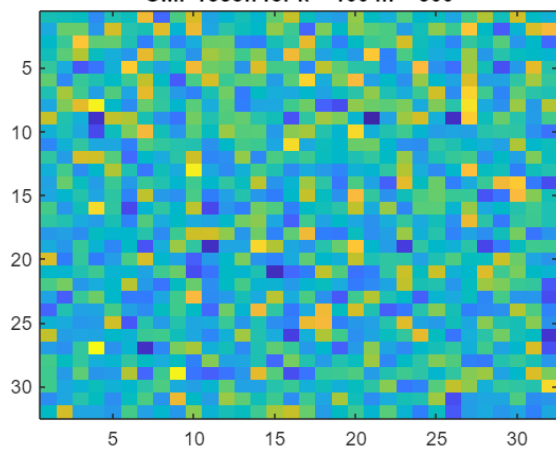
OMP recon for  $k = 50$   $m = 500$



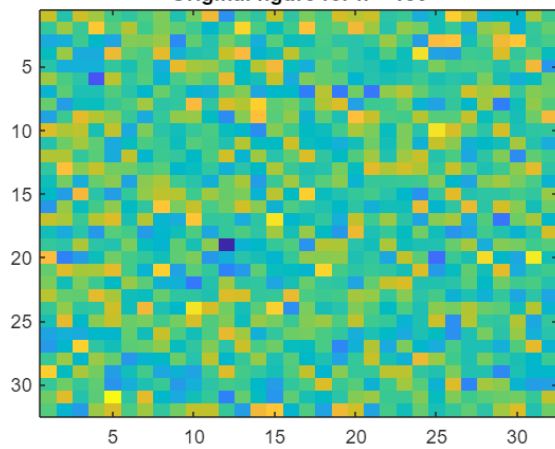
Original figure for  $k = 100$



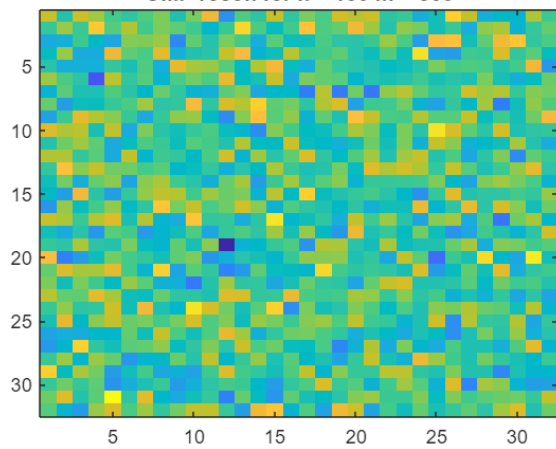
OMP recon for  $k = 100$   $m = 500$



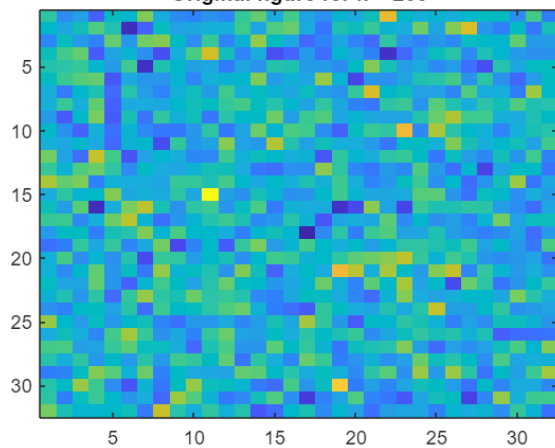
Original figure for  $k = 150$



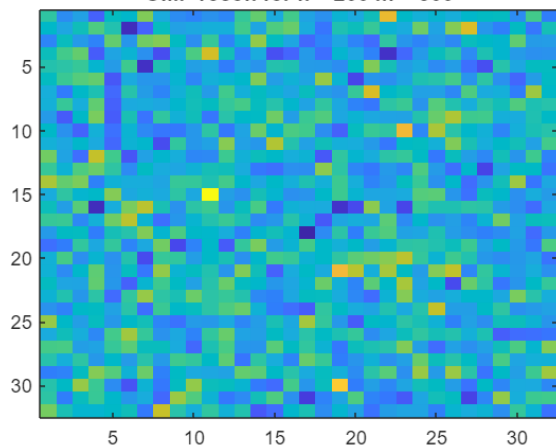
OMP recon for  $k = 150$   $m = 500$



Original figure for  $k = 200$



OMP recon for  $k = 200$   $m = 500$





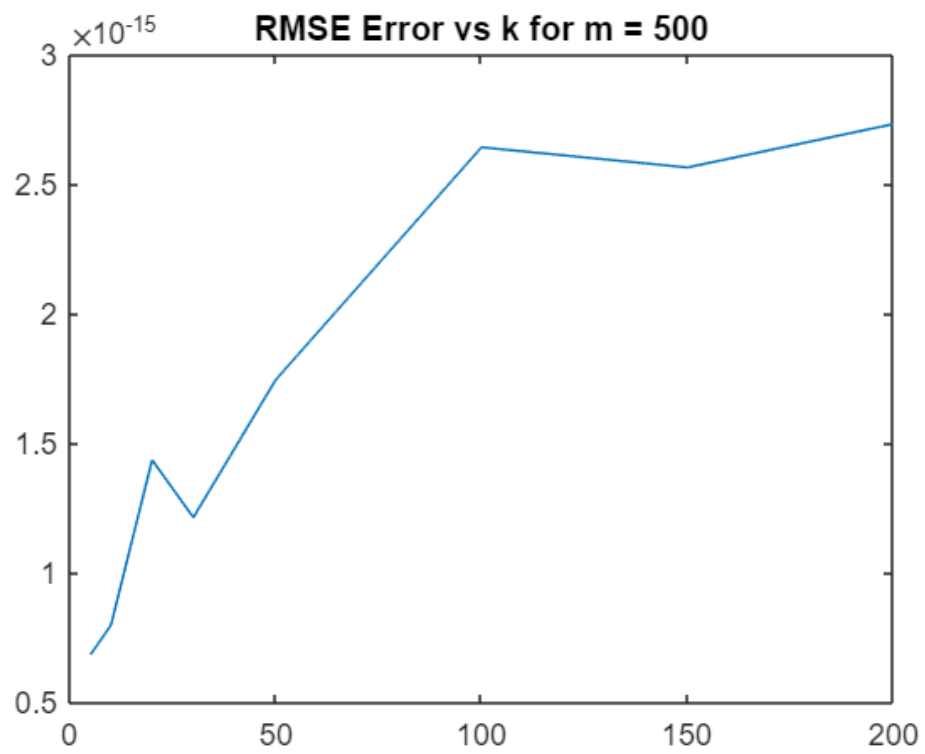
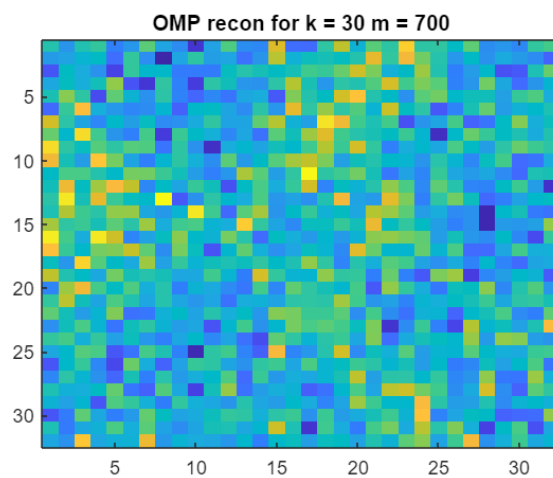
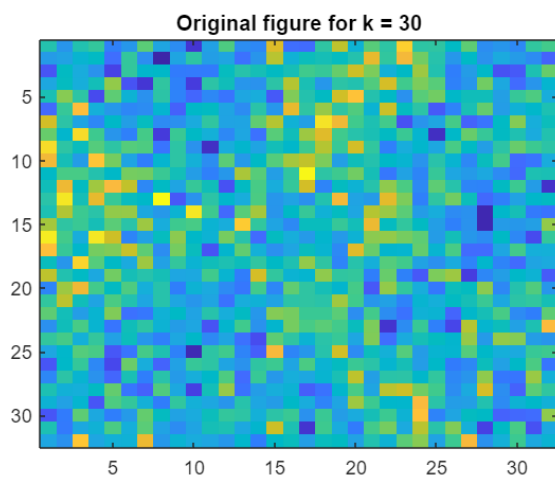
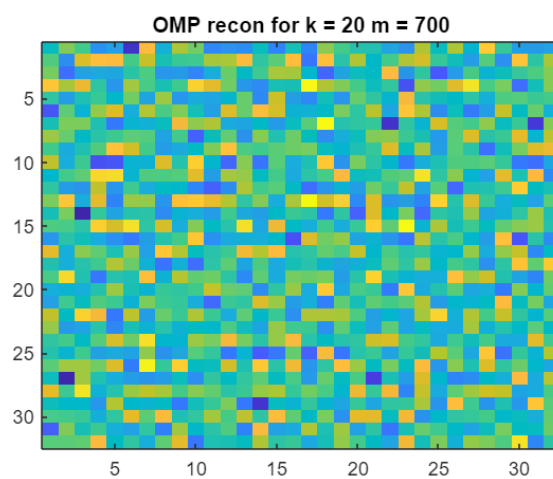
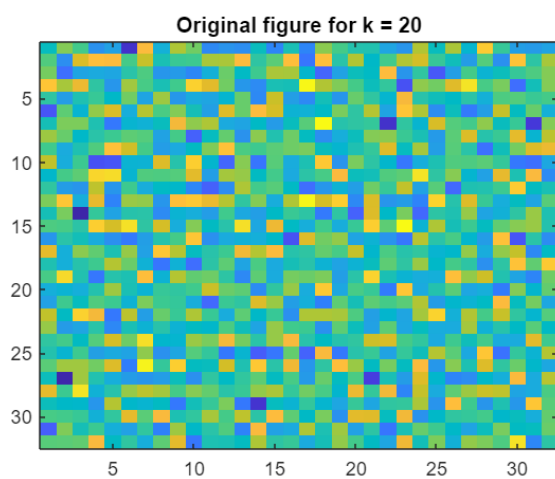
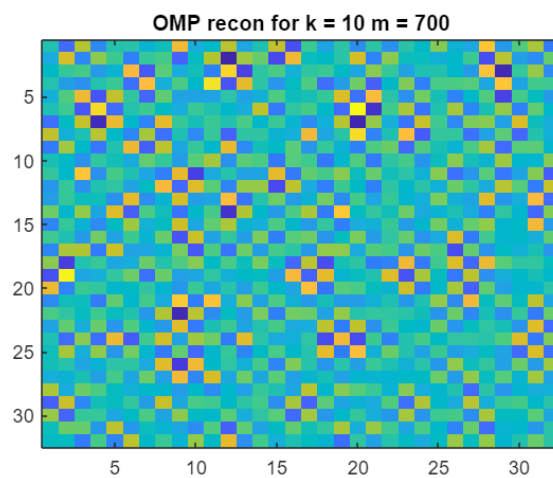
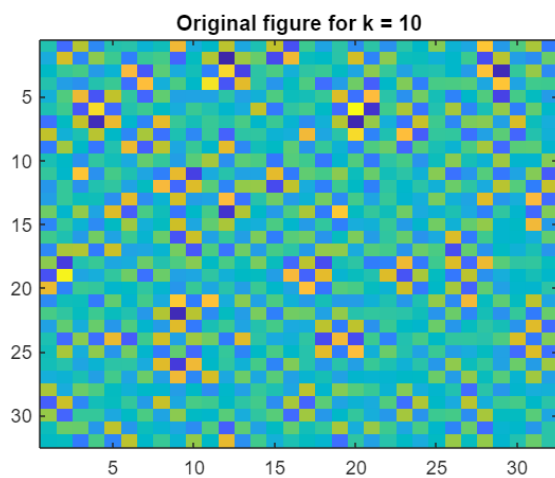
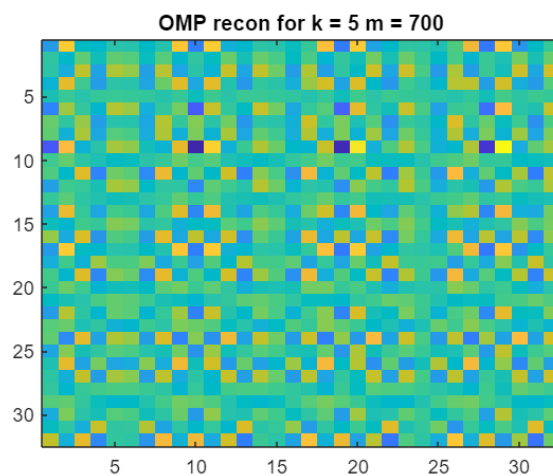
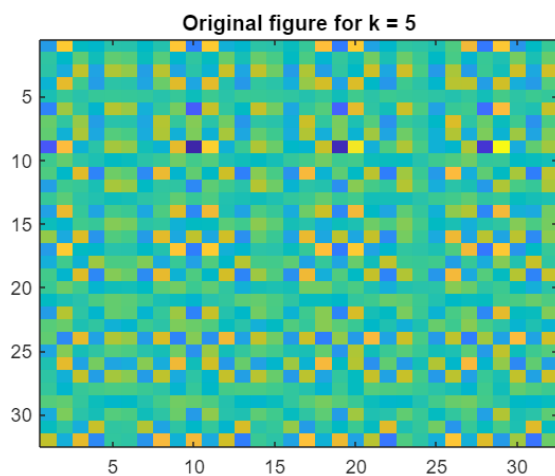
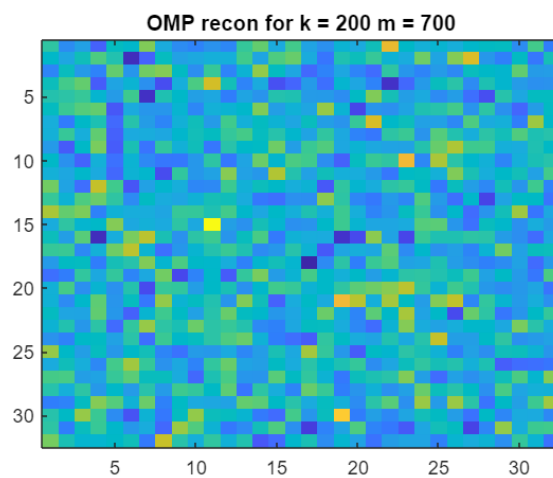
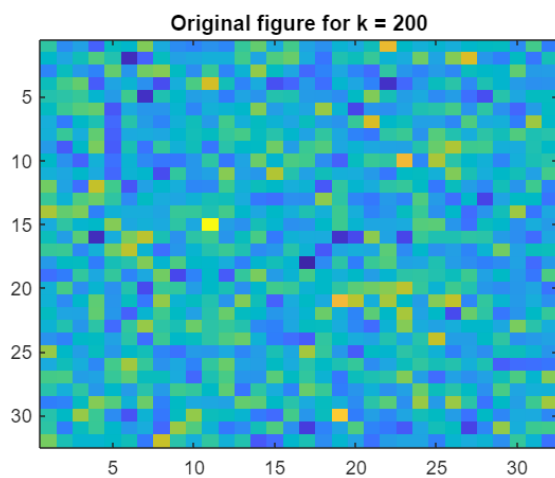
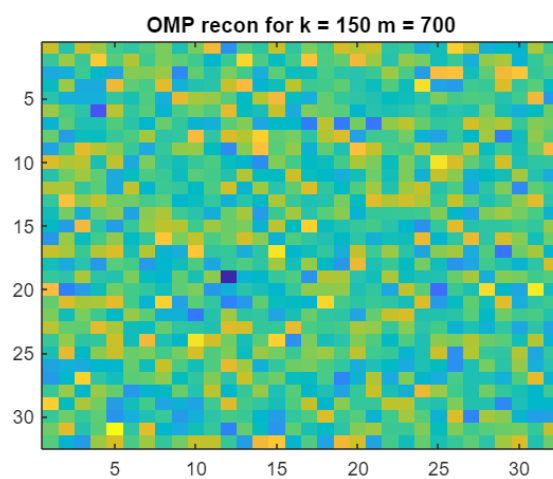
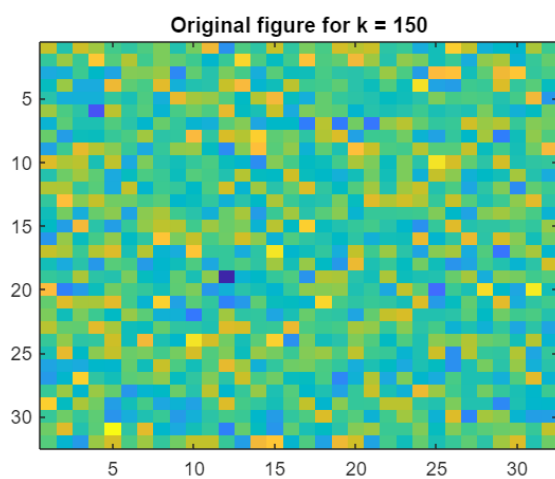
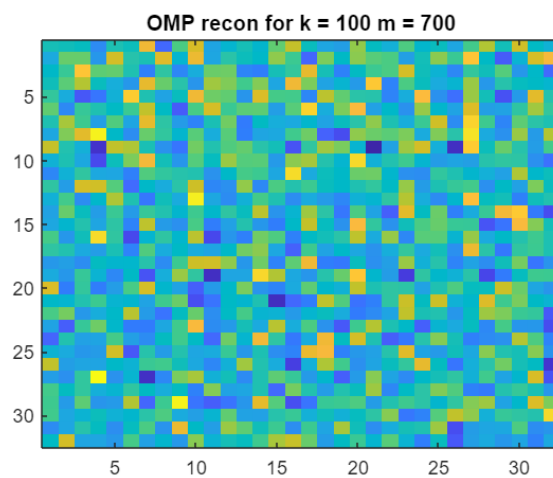
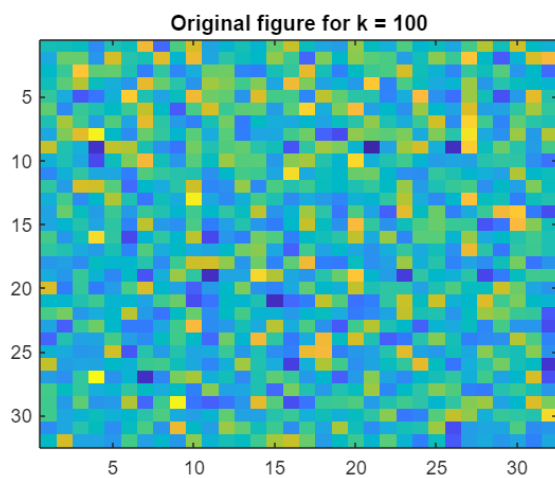
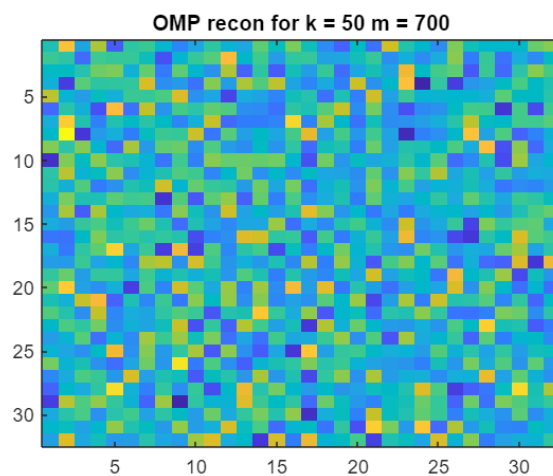
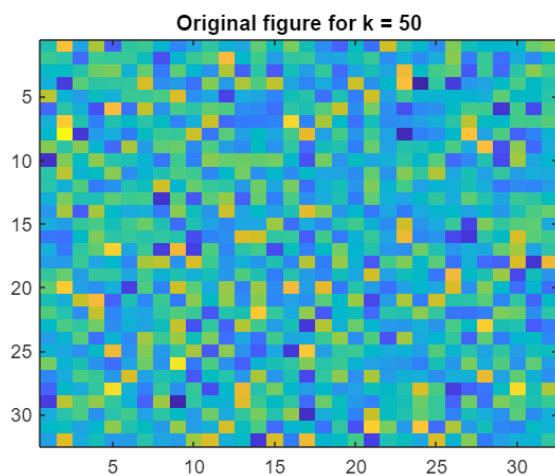


Figure 3: Caption





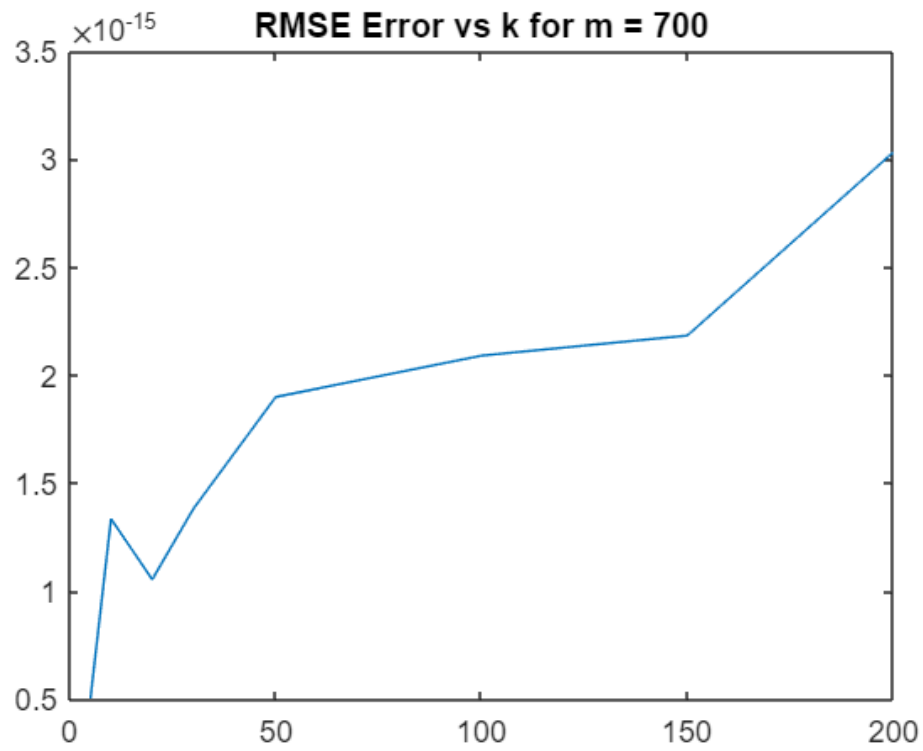
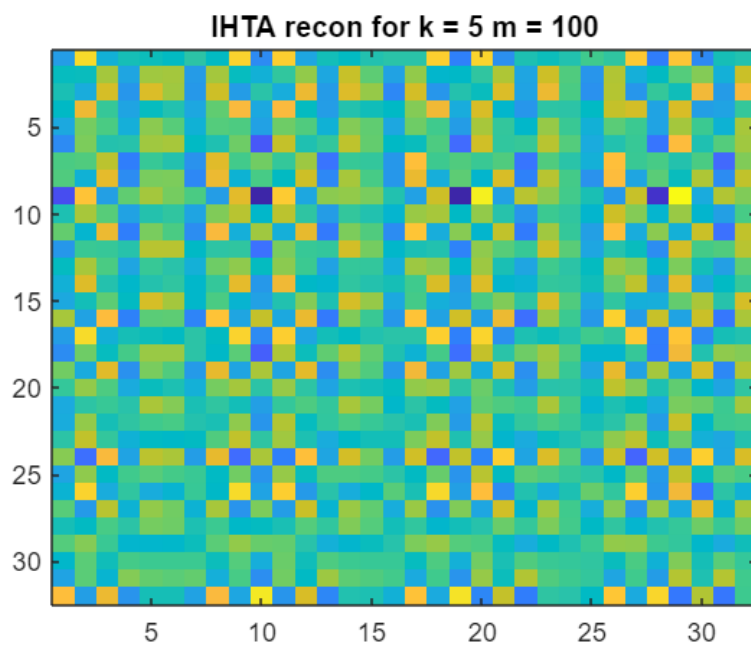
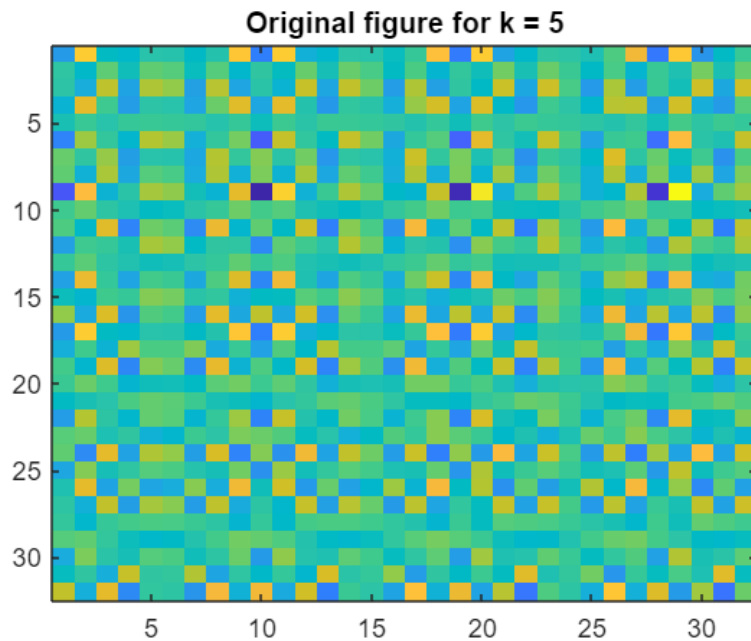


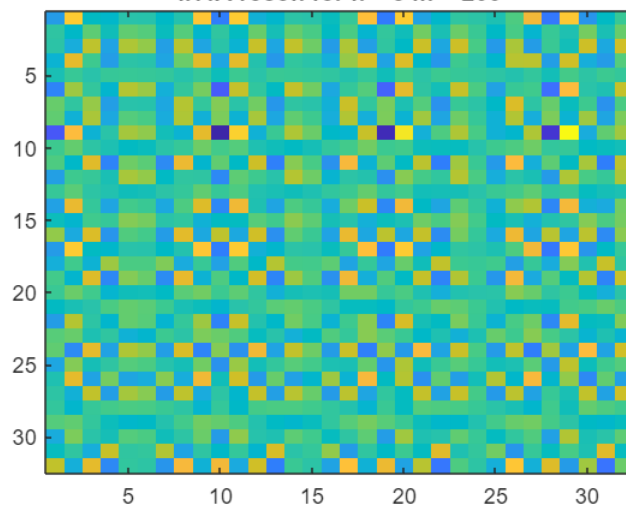
Figure 6: Caption

This relation between error vs  $k$  is explained easily by the fact that a higher  $k$  implies a lower sparsity. Thus sparser vectors have better reconstructions.

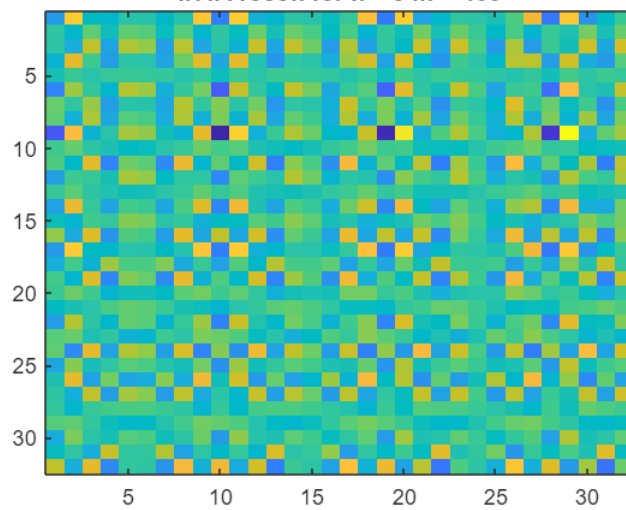
The following are the results for IHTA:



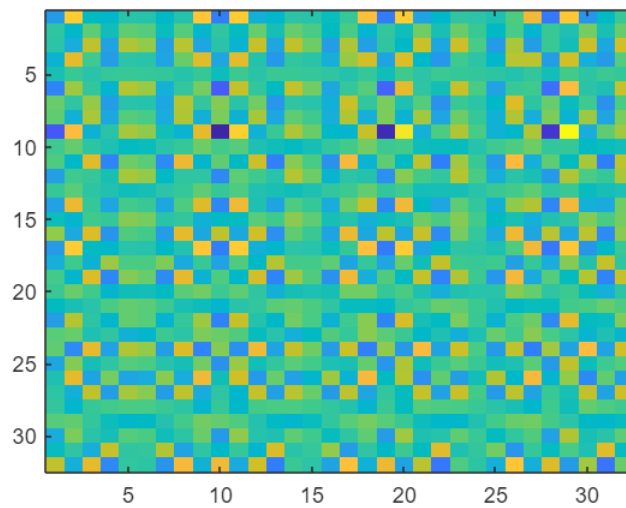
IHTA recon for  $k = 5$   $m = 200$

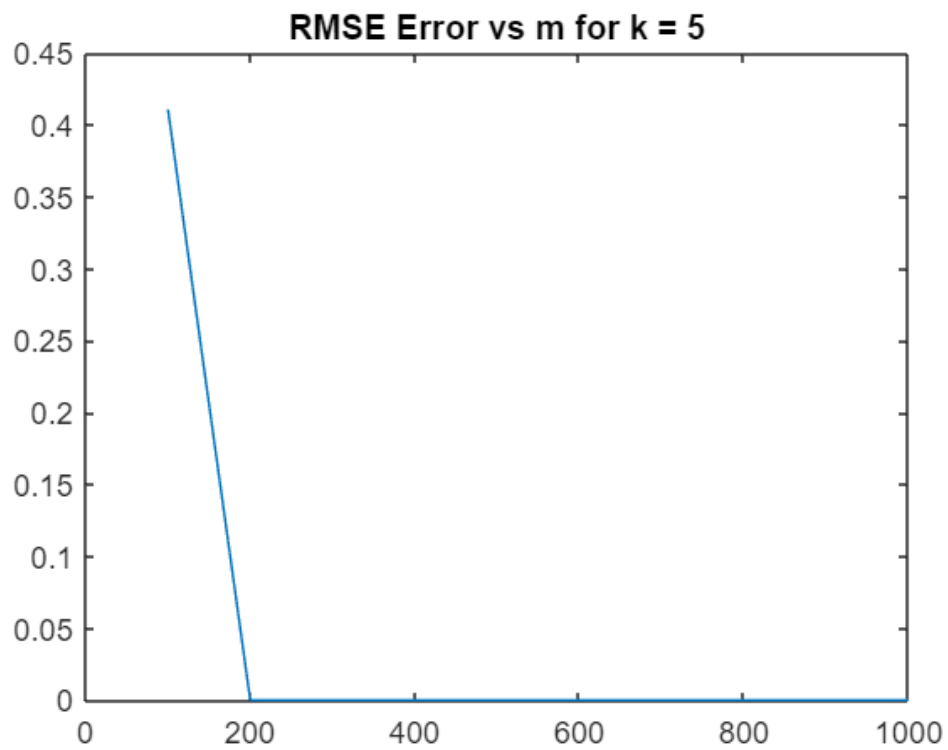
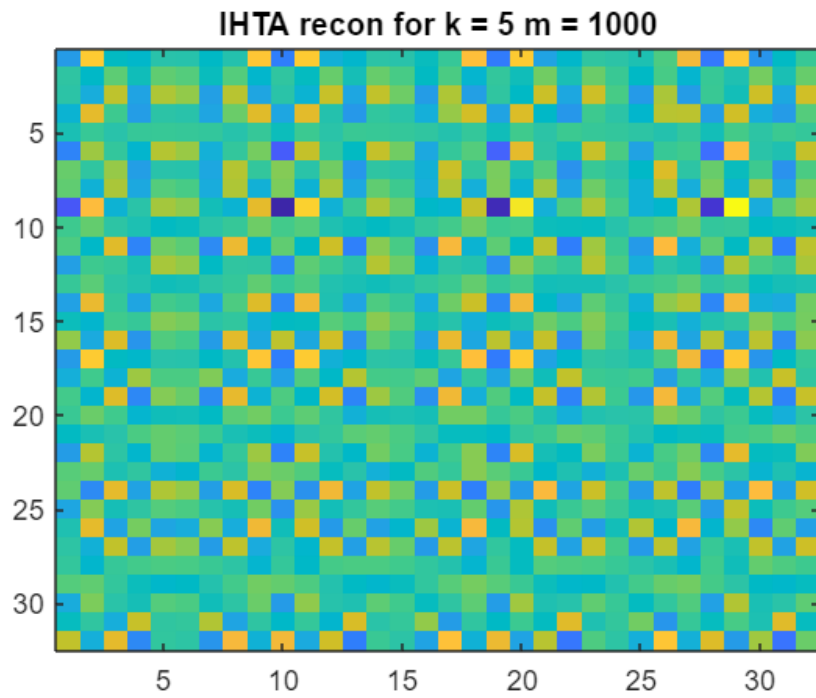


IHTA recon for  $k = 5$   $m = 400$

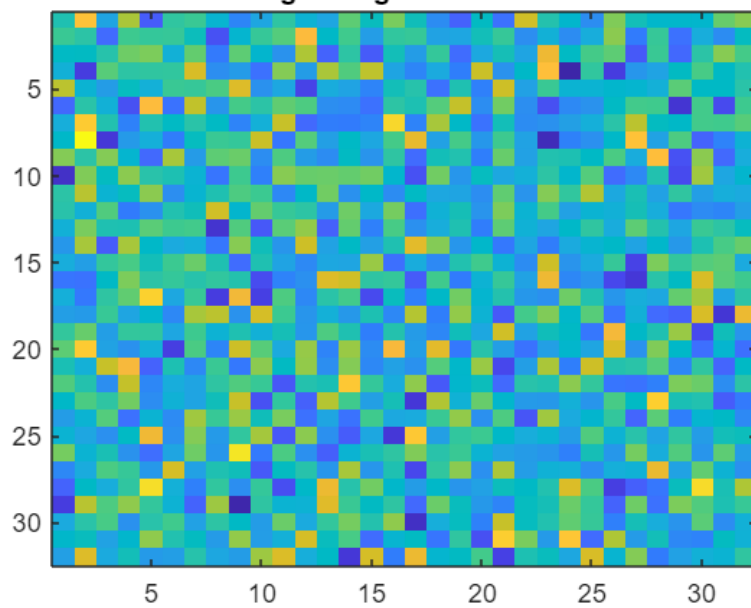


IHTA recon for  $k = 5$   $m = 600$

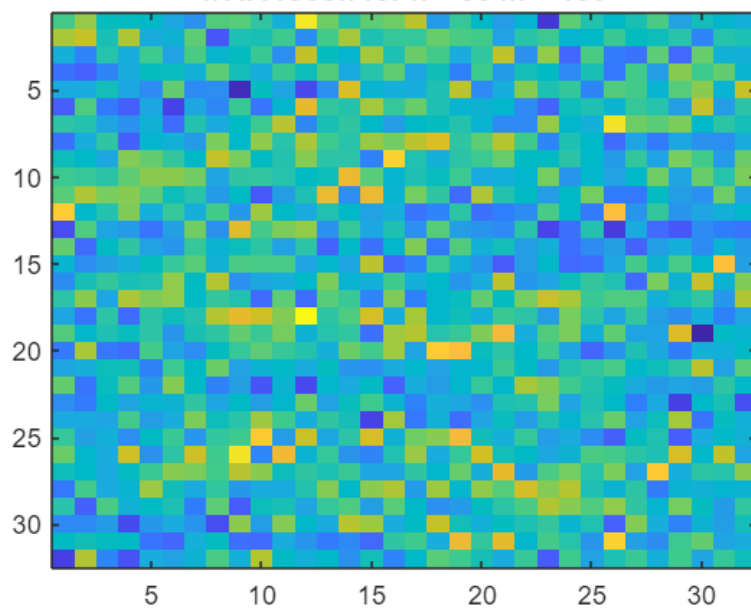




Original figure for  $k = 50$

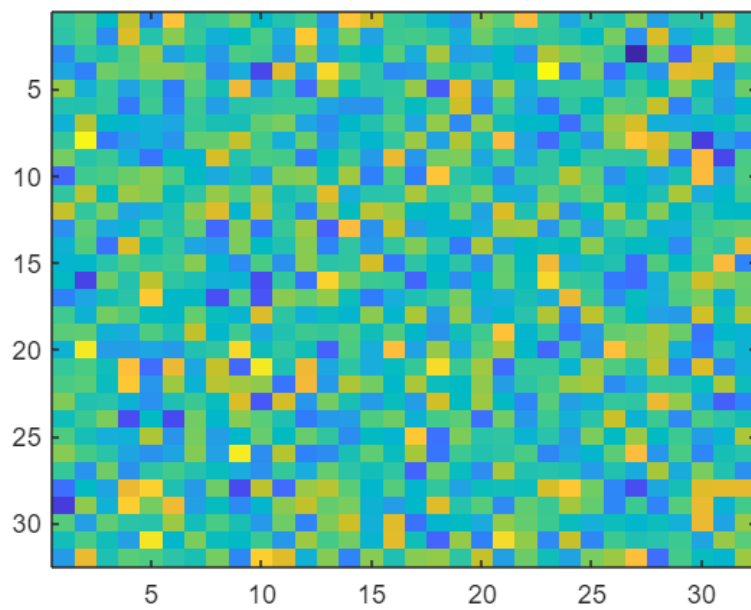


IHTA recon for  $k = 50$   $m = 100$

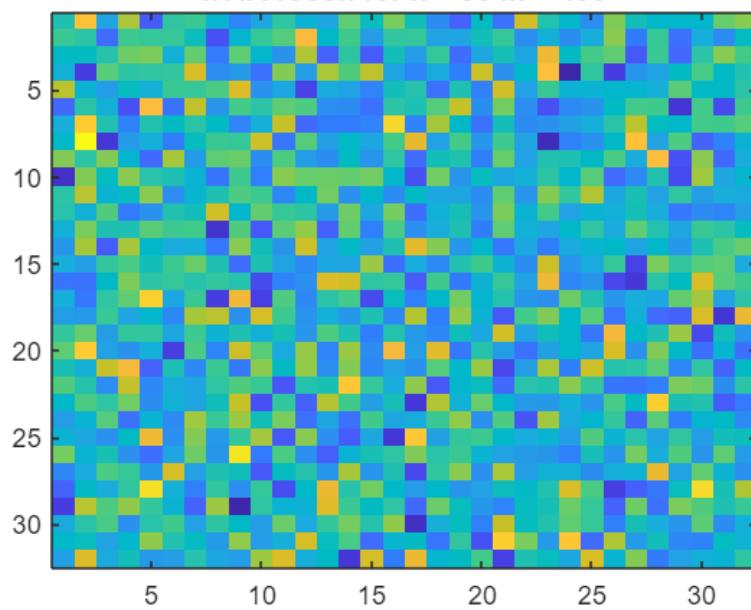


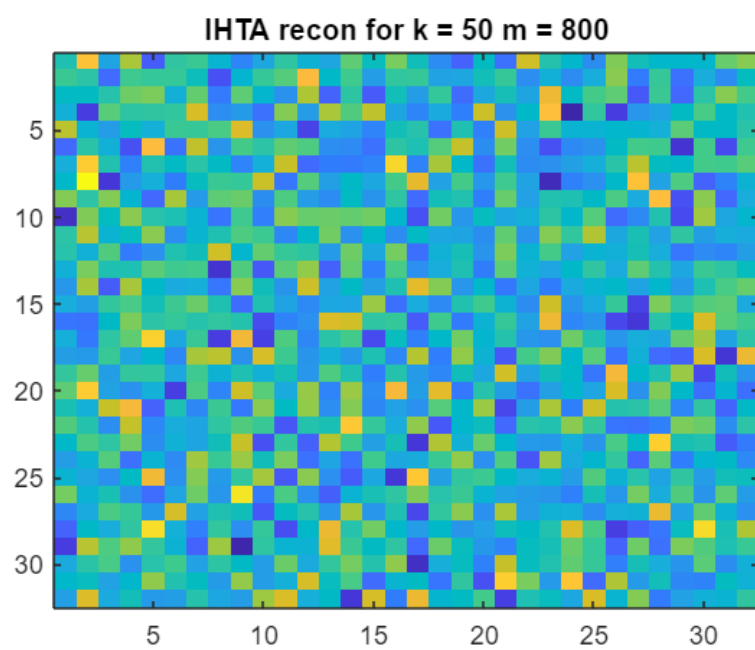
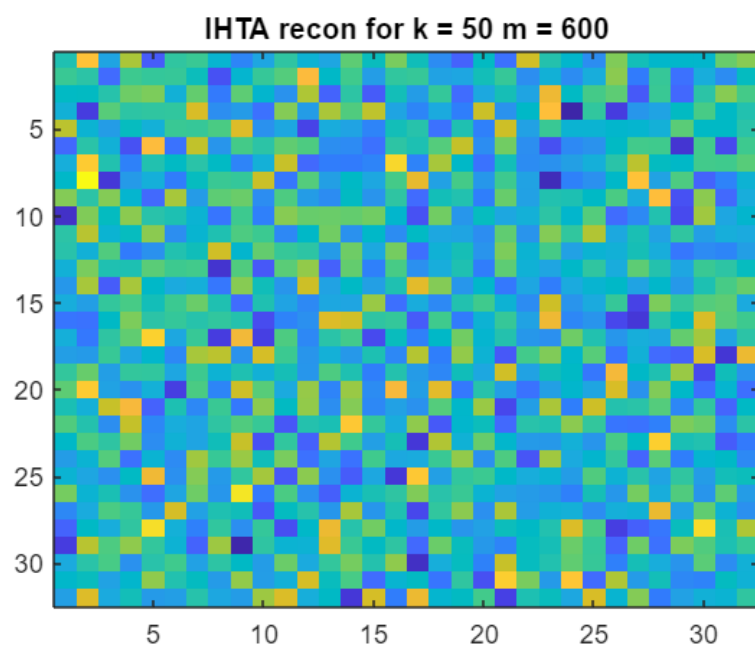


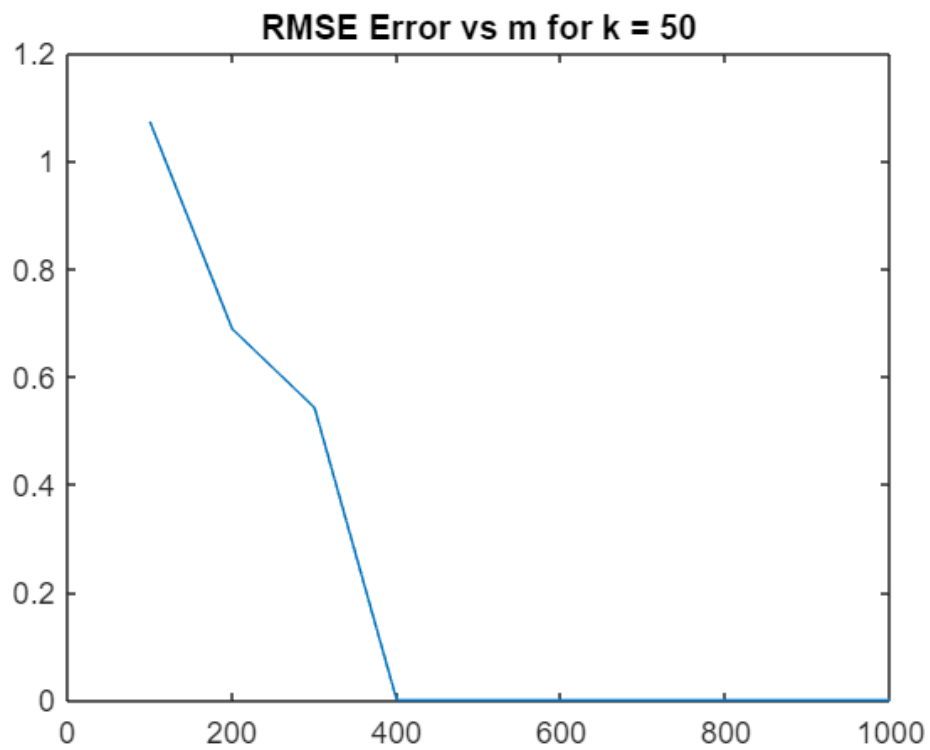
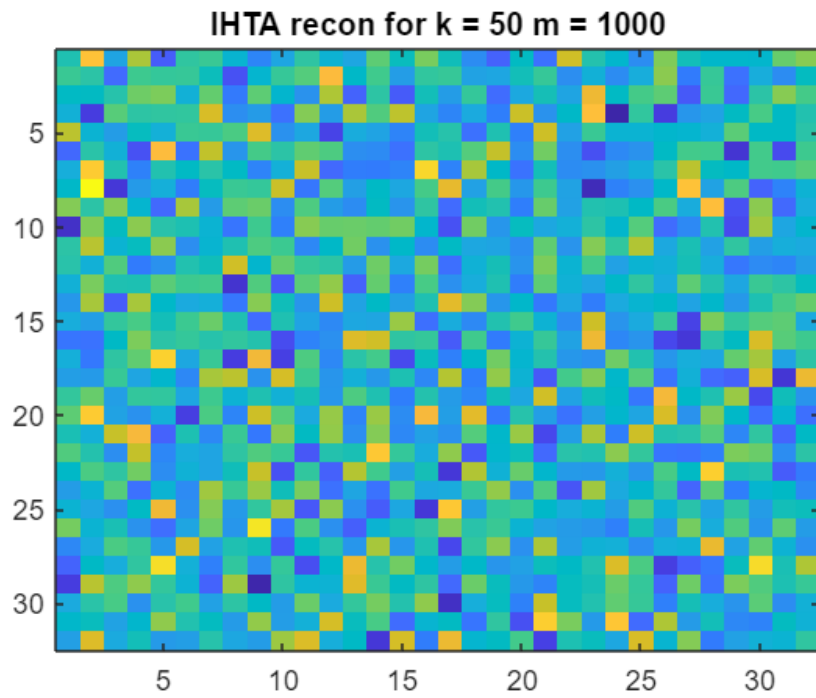
IHTA recon for  $k = 50$   $m = 200$



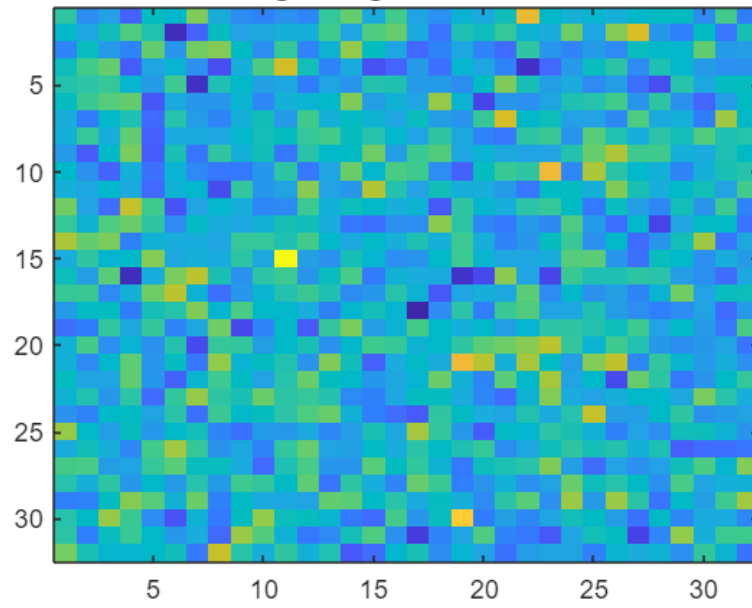
IHTA recon for  $k = 50$   $m = 400$



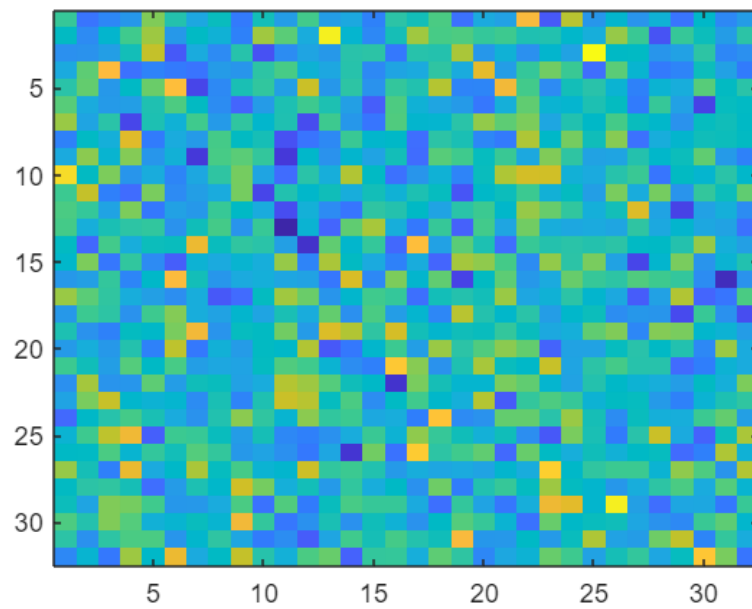


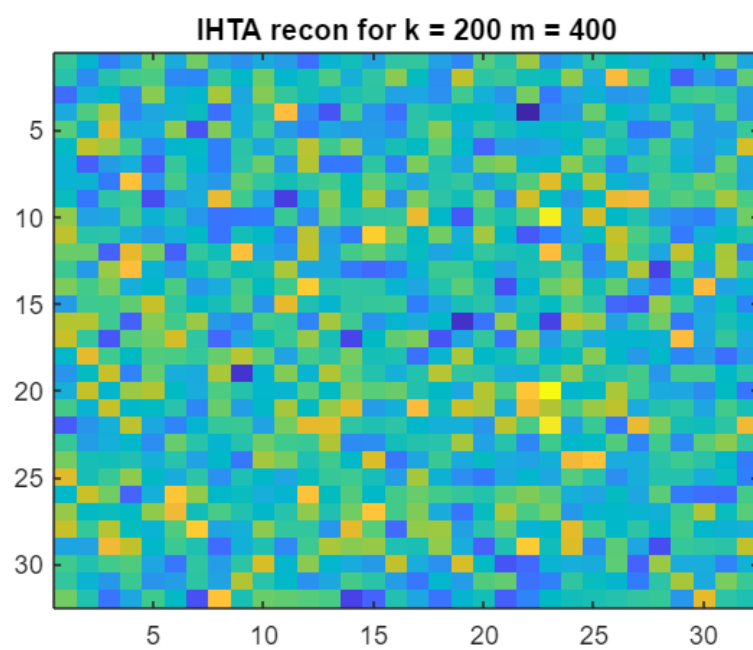
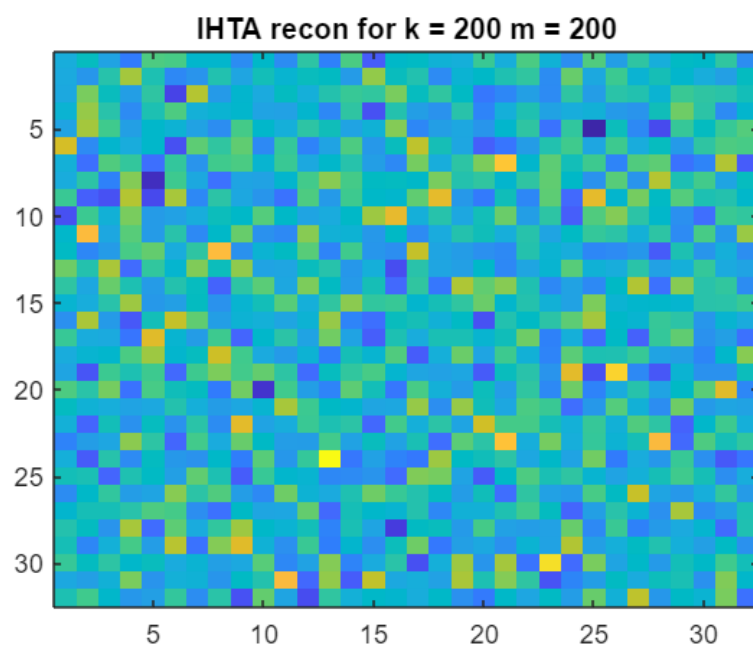


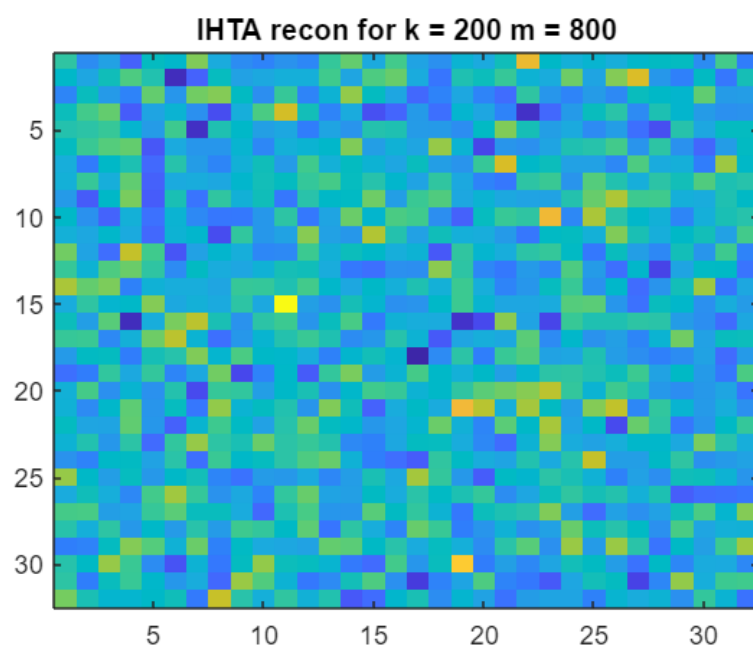
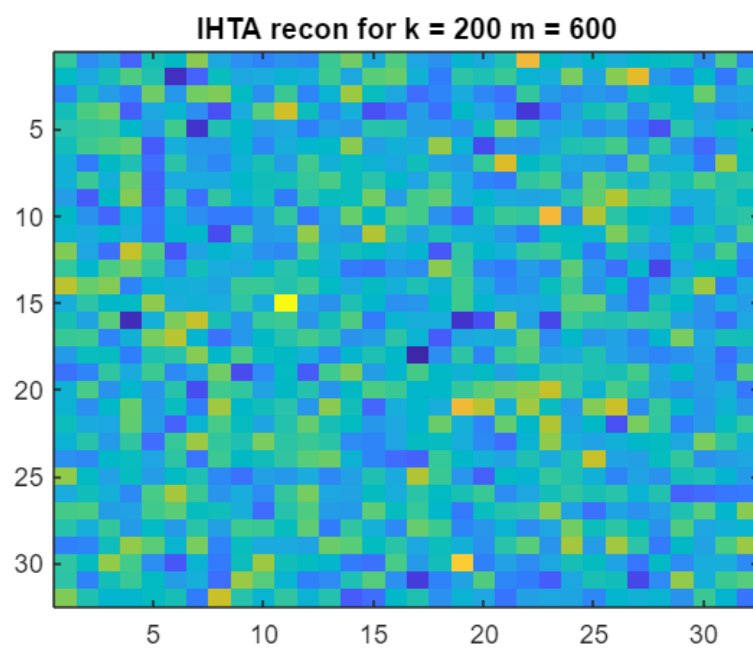
Original figure for  $k = 200$

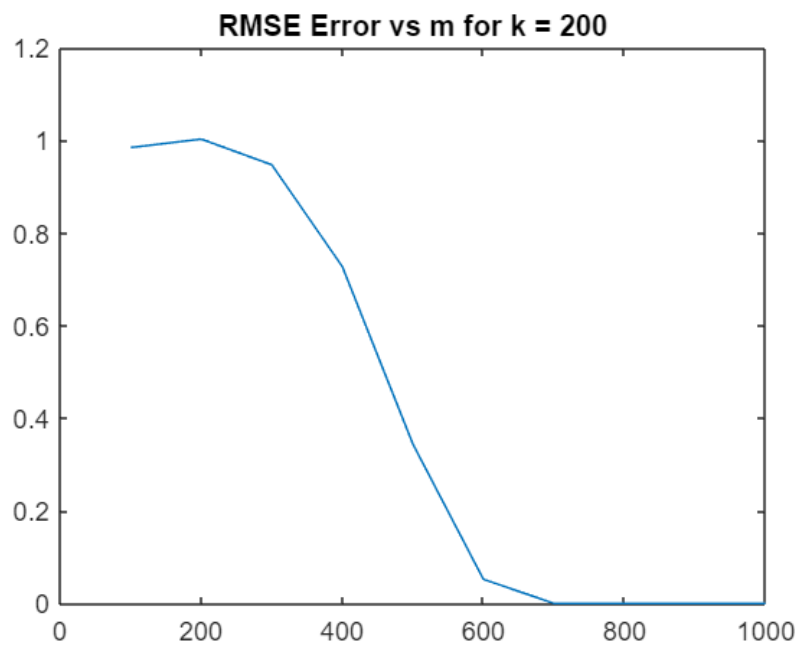
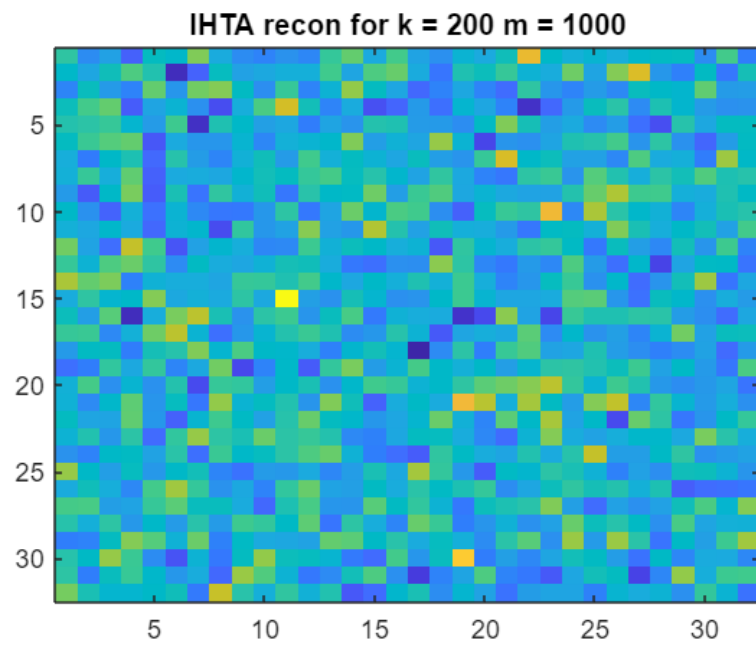


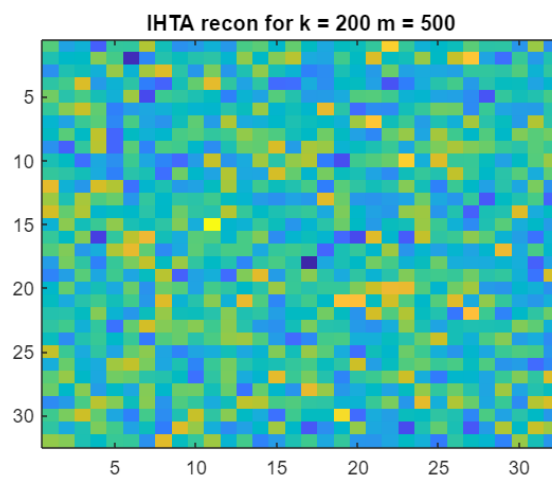
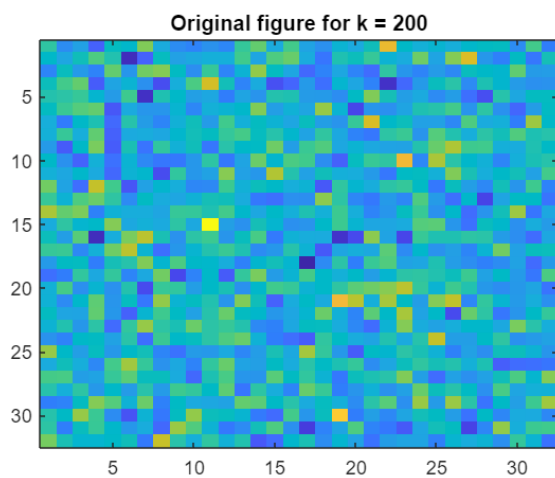
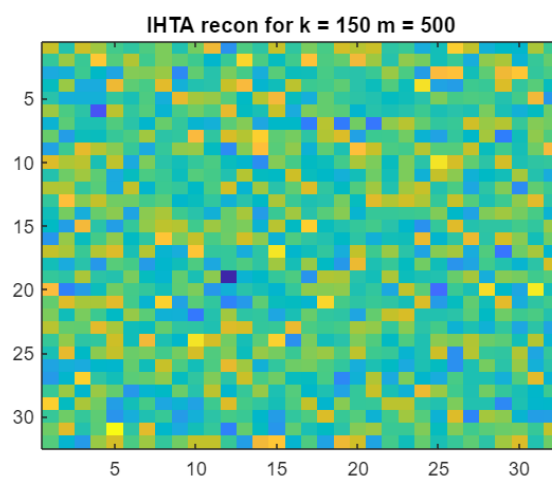
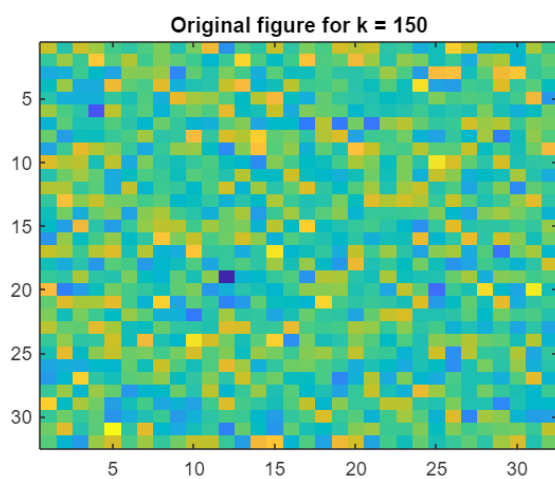
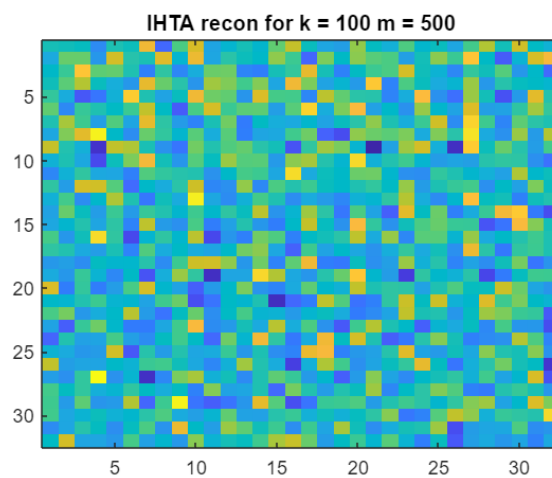
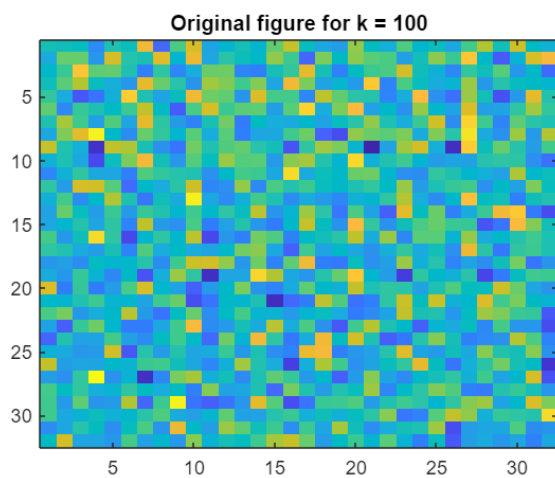
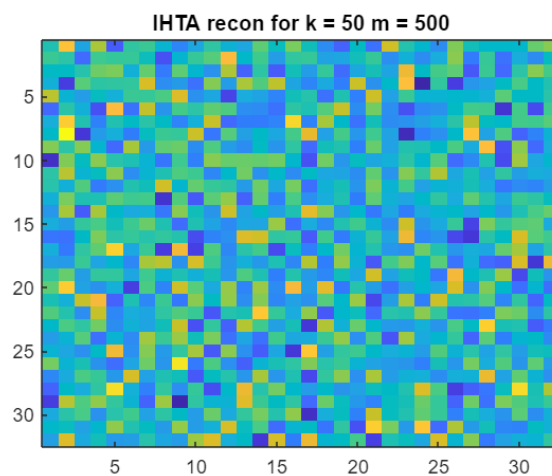
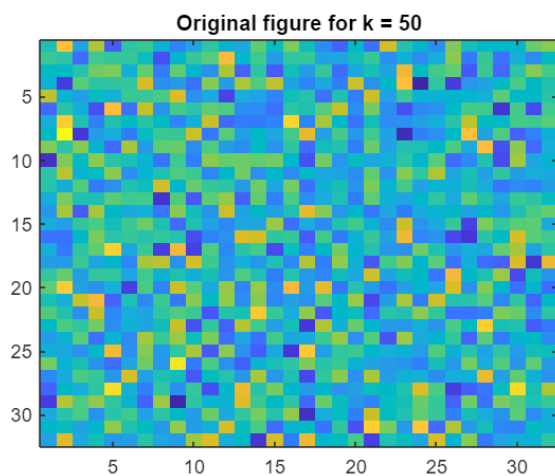
IHTA recon for  $k = 200$   $m = 100$













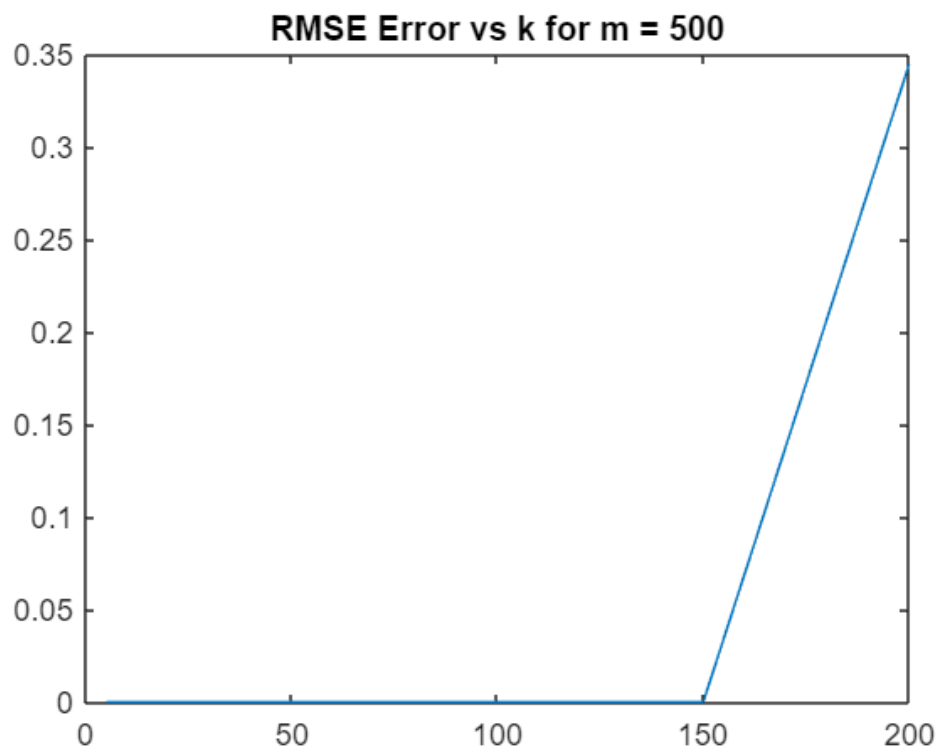
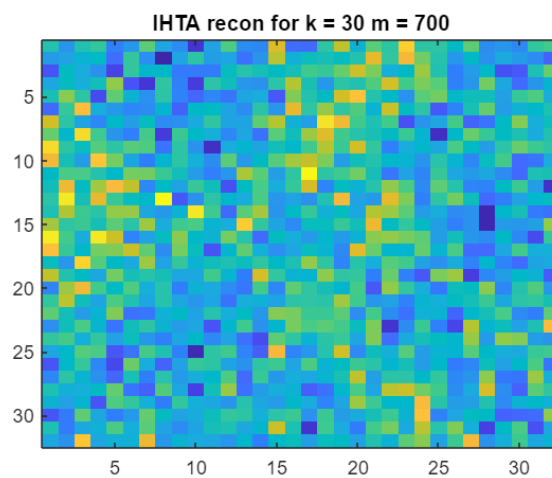
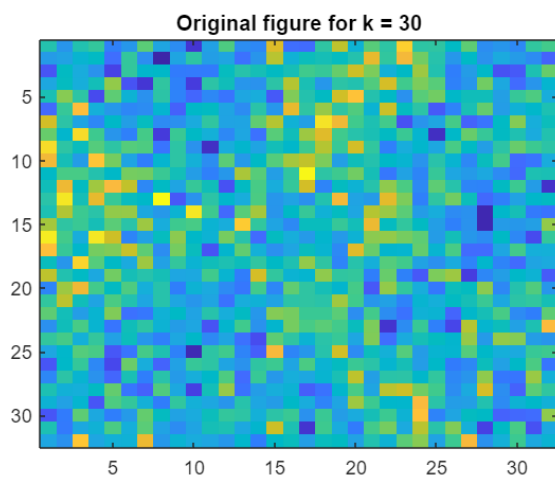
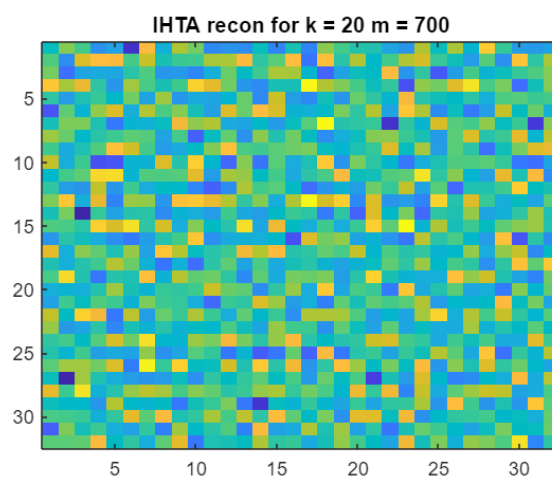
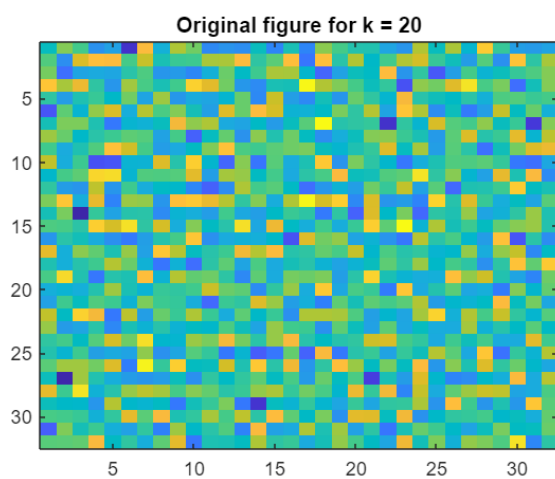
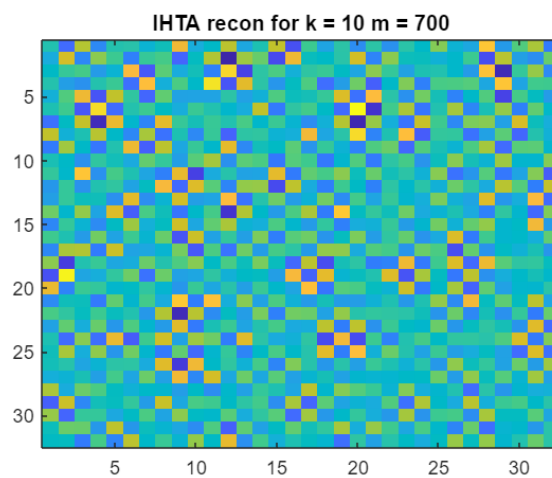
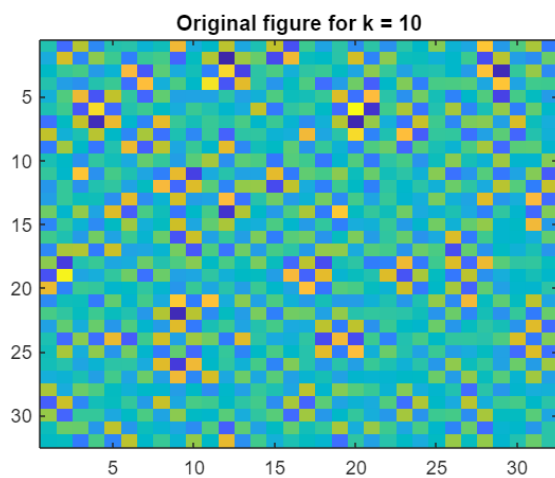
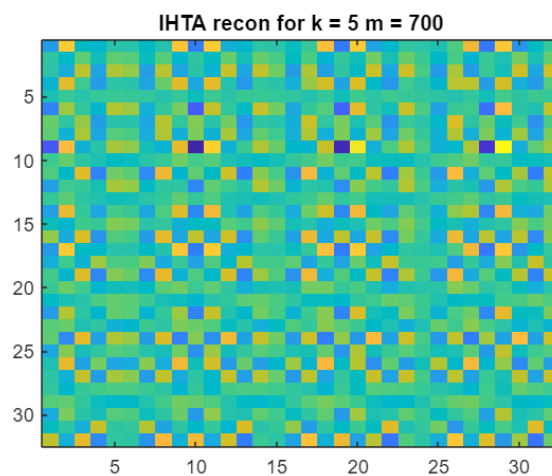
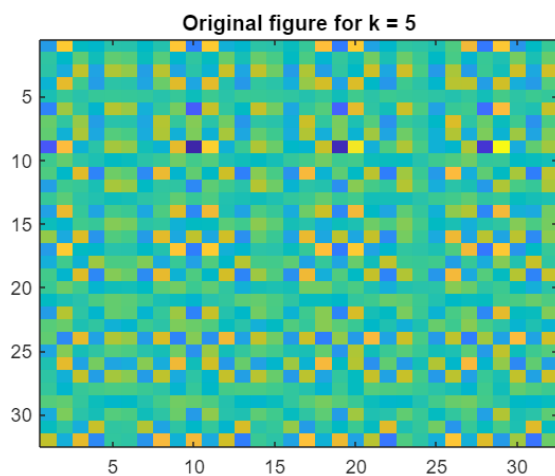
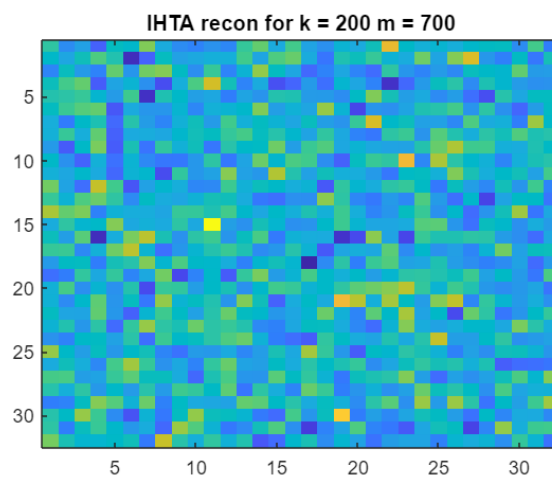
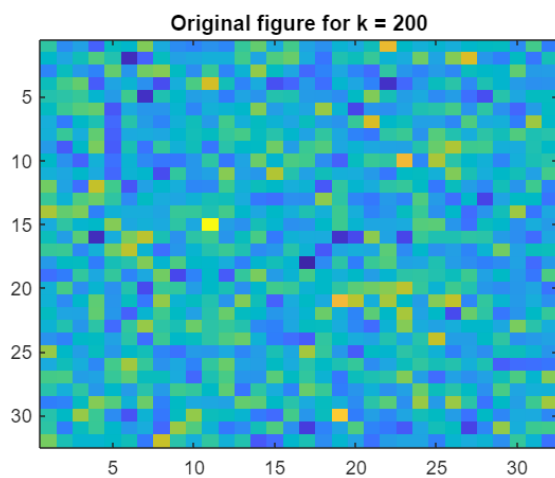
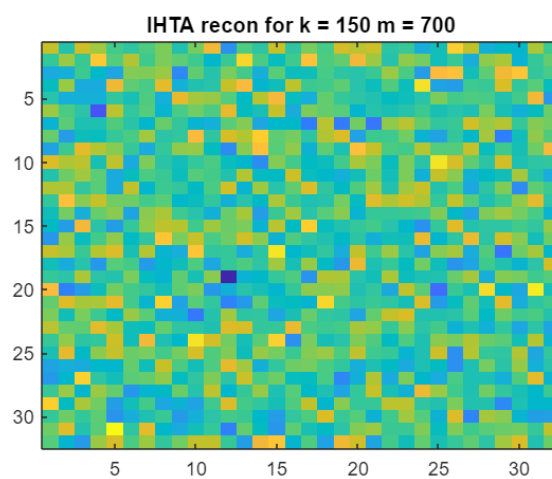
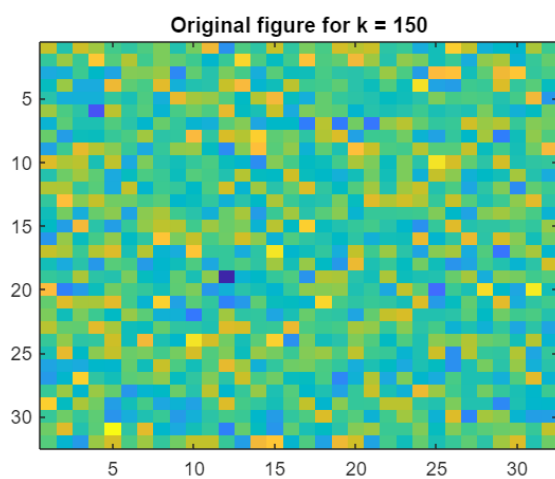
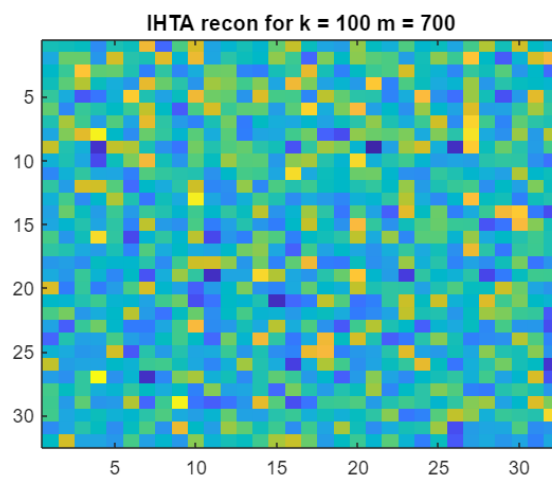
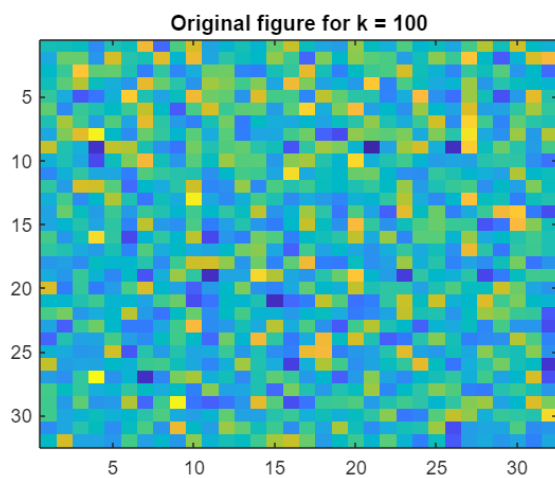
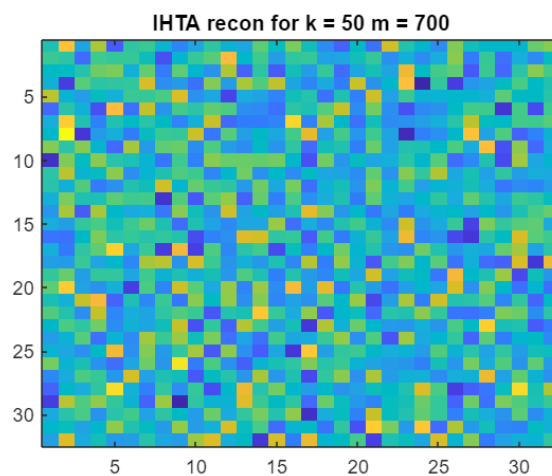
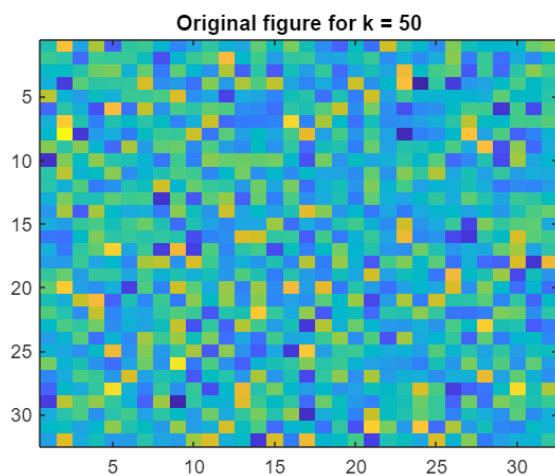


Figure 8: Caption





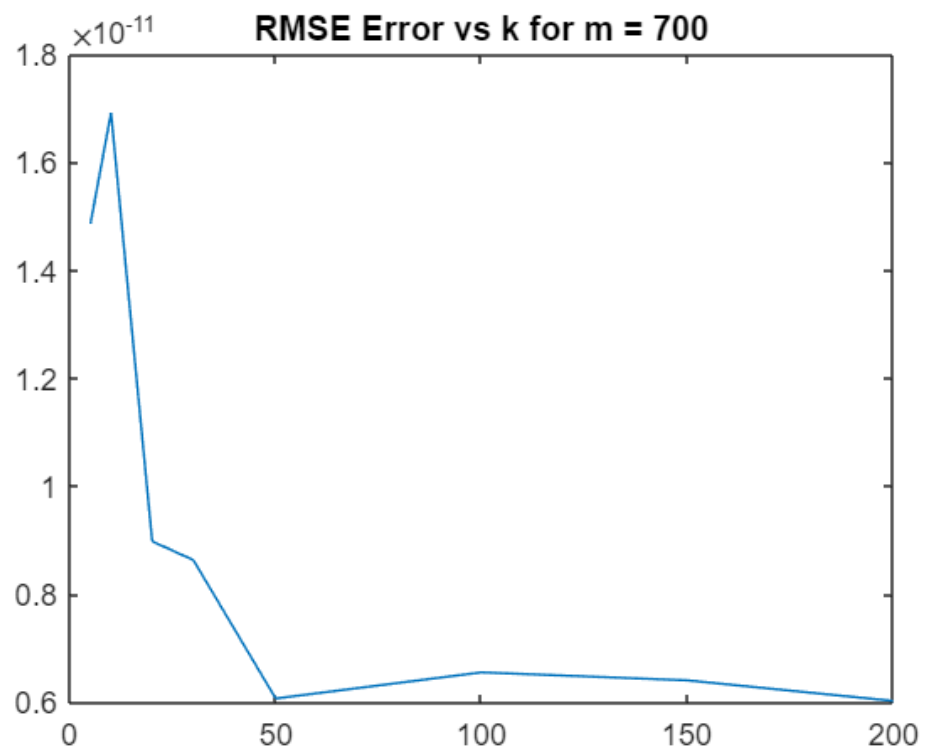


Figure 11: Caption