H35ignment - 3 < f, g> = \(\) f(t)g(t) dt a) f(t) = t + 2 $g(t) = t^2 - 3t + 4$ a = -1, b = 1a) < pf+9, h> = b ((pf(t)+g(t)) ht) = 5p f(+) h(+) + 5g(+) h(+) = P<f,h>+ <g,h> (ii) $\langle f, g \rangle = \int_{a}^{\infty} f(t)g(t) dt$ $\langle g, f \rangle = \int g(t) f(t)$ $\langle f, q \rangle = \int (t+2)(t^2-3t+4)dt$ = \(\(\(\) 2t^2 + 16 \) dt = 16-2

 $(t+2)^2 dt$ (t2-3t+4) dt 129,9> = 1<f, g>1 < /11 /1911 a) <x, B> = 20141 - 20142 - 20241 + 420242 (i) <ax+B, r> = < (a>(1+y1, a>(2+y2), (21)) $= (ax_1+y_1)z_1 - (ax_1+y_1)z_2 - (ax_2+y_2)z_1$ $+ 4(ax_2+y_2)z_2$ $= a (x_1z_1 - x_1z_2 - x_2z_1 + 4x_2z_2)$ + 4,2, - 4,22 - 422, + 44222 a < 00, 75 > + < B, r>

LB, a> = 91301 - 30142 - 224, +430242 (x, B) = < B, X . . < x, B > 18 a inner product. Q = (01, 202) B= (4, 42) \(\alpha \, \beta \) = \(\omega \, \omega \, \omega \, \omega \) = \(\omega \, \omega \, \omega \, \omega \, \omega \) = \(\omega \, \omega \) LPX+B, V>= L(pocity, px2+42), (z1, 22)> = $(p_{3(1+y_1)}z_1 - 3(p_{3(1+y_1)}z_2 - 3(p_{3(2+y_2)}z_1 + a(p_{3(2+y_2)}z_2)$ $= \rho \left(3(121 - 3012 - 3012 - 1 + a)(122) + 4(12) - 34(12) + a)(122) + 4(12)(12) + a)(12) + a$ PKX, r> + KB, r> => ber

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\mathcal{E}(1,1,1,1), (1,-1,2,2), (1,2,-3,-4)
5>
       20 W1 = V1
          ω2 = V2 - < V2, ω, > ω,
                                  (W1,01)
        \omega_3 = v_3 - \langle v_3, \omega_1 \rangle \omega_1 - \langle v_3, \omega_2 \rangle \omega_2
\langle \omega_1, \omega_1 \rangle = \langle \omega_2, \omega_2 \rangle
   \omega_1 = (1, 1, 1, 1)

\omega_2 = (1, -1, 2, 2) - (1-1+2+2)(1, 1, 1, 1)
   \omega_3 = (1,2,-3,-4) - (1+2-3-4)(1,1,1,1)
                                           (0-4-3-4)(0,-2,1,1)
     \omega_2 = (1, -1, 2, 2) - (1, 1, 1, 1)
    \omega_{2} = (1, 2, -3, -4) + (1, 1, 1, 1) + 11 (0, -2, 1, 1)
           = (2,3,-2,-3) + (0,-4,4,4)
             = \begin{pmatrix} 2, -2, -1, -7 \\ \hline 3, 6, 6 \end{pmatrix}
```

Osithogonal basis
$$3$$
 (1,1,1,1); $(0,-2,1,1)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-1,-7)$; $(2,-2,-2,-1,-7)$; $(2,-2,-2,-1,-7)$; $(2,-2,-2,-7)$; $(2,-2,-$

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V_3 - \langle v_3, \omega_1 \rangle \omega_1 - \langle v_3, \omega_2 \rangle \omega_2
\langle \omega_1, \omega_2 \rangle = \langle \omega_2, \omega_2 \rangle
      =(0,3,4)-(0+0+12)(1,0,1)
                                 (0+0-6)(\frac{3}{2},0,\frac{-1}{2})
   =(0,3,4)-(3,0,3)-(6,0,-2)
Outhonosimal = \begin{cases} \frac{1}{2}(1,0,1); \frac{2}{3}(\frac{3}{2},0,\frac{-1}{2}) \end{cases}
      \{21, t, t^2 \}

\{f, g\} = \{f(t)g(t) dt\}
                      -. <u, 0,> w,
                            \langle \omega, \omega, \omega \rangle
                               Sdt
```