

22-04-19

Defⁿs:

- $L = \text{SPACE}(\log n)$

- $NL = \text{NSPACE}(\log n)$

- $\text{Co-NL} = \{L \mid \bar{L} \in NL\}$

- A is NL -complete if

a.) $A \in NL$

b.) $\forall B \in NL \leq_L A$

↳ logarithmic space reducible

$n \rightarrow$ size of space

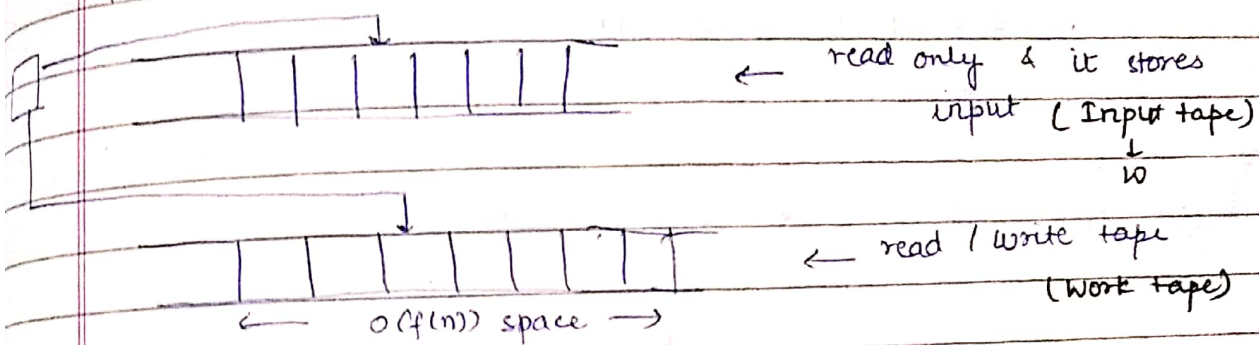
→ don't even store whole input. → Only $\log n$ space

⇓ move to new model

(lower than polynomial)

New Model:

T.M. consists of 2 tapes



* will take into account only work tape while calculating space complexity of the T.M.
 $O(\log n) \rightarrow$ ^{no. of} ~~spa~~ cells in work tape [in case of $O(\log n)$ space]

→ NL : if \exists a branch which accepts in $O(\log n)$ space
 if \forall branches \rightarrow rejects in " "

same like
NP.

→ To get $\Sigma_1 \rightarrow$ we need 1 more tape (in addⁿ to 2)



↳ $|f(w)|$ might be $> \log n$
 space complexity \rightarrow calculated wrt work tape only.

→ For 3-tape T.M. :

We'll try to find only:

- ↳ head of 1st tape
- ↳ head of 2nd tape
- ↳ work tape symbols

These will define the configⁿ of the T.M.

Suppose we have T.M. $N(w)$

no. of cells in workspace = $O(f(n))$

$$C = \Gamma \cup \Sigma \cup \{ \sqcup \} \cup \{ \sqcap \}$$

$$t = |C|$$

Total
no. of
configs

$$\Rightarrow t^{O(f(n))} \cdot O(f(n)) \cdot n$$

\downarrow \downarrow
 2nd head 1st head
 ptr ptr ($|w| = n$)
 (length of tape)

To store these many configs, total space needed :-

$$\log_2 [t^{O(f(n))} \cdot O(f(n)) \cdot n]$$

$$= \log_2(n) + \log_2(O(f(n))) + O(f(n)) \log_2(t)$$

Since we're trying to find upper bound,

$$O(f(n)) \log_2(t) < 2^{O(f(n))}$$

— (1)

$\Rightarrow t \rightarrow \text{const.}$

so,

$$t < 2^x \quad \text{for some } x \rightarrow \text{const.}$$

$$t^{O(f(n))} < 2^{x \cdot O(f(n))}$$

$$O(f(n)) < 2^{O(f(n))}$$

} \rightarrow multiply these two to get (1)

Max.

\Rightarrow Space needed = $O(\log(n) + O(f(n)) \log(t))$

Ex. PATH = $\{ \langle G, s, t \rangle \mid \exists \text{ a path from } s \text{ to } t \text{ in } G \}$

By guess \rightarrow we stored just 1 vertex (done earlier)

Work space = $O(\log_2 n)$ [G not stored here]

\Rightarrow PATH \in NL

$\Rightarrow \overline{\text{PATH}} \in \text{Co-NL}$

We'll prove that : $\overline{\text{PATH}} \in \text{NL}$ (later)

ex Prove that $\text{PATH} \in \text{NL-Complete}$.

1) $\text{PATH} \in \text{NL}$ ✓

2) $\forall B \in \text{NL} \leq_L \text{PATH}$ \rightarrow Taken NDTM M which creates configⁿ graph acc. to its own configⁿ.

Can have ND T.M. $M(w)$: \rightarrow configⁿ graph (M runs in $O(\log n)$ space)

if M accepts $w \leftarrow \exists$ a path from starting configⁿ to accepting configⁿ

rejects \leftarrow if doesn't exist

$\langle G, C_0, C_{\text{accept}} \rangle \in \text{PATH}$

$M(w) \leftrightarrow \langle G, C_0, C_{\text{accept}} \rangle \in \text{PATH}$

$C_0, C_1, C_2, \dots, C_{\text{accept}} \Rightarrow$ possible configⁿs $\log n$
Total space taken by these configⁿs : $\log n + O(\log n)$
 $= O(\log n)$

In o/p tape. \rightarrow put these configⁿs
 \downarrow check
if \exists an edge b/w 2 configⁿs

o/p tape

#	C ₀	#	C ₁	#	...	#	#	C ₀	,	C ₁	#
---	----------------	---	----------------	---	-----	---	---	----------------	---	----------------	---

 \downarrow
if \exists edge b/w C_0 & C_1

put 2 configⁿs C_i & C_j in work table & check if \exists an edge or not. If $\exists \rightarrow$ put it in o/p table.

so, workspace : $O(\log_2 n)$

PATH \in NL

1. \exists a path from s to t in $G \rightarrow$ accept
2. \forall ~~non~~ s, t \nexists no path $\sim \rightarrow$ reject

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OR

graph
 \rightarrow Instead of storing whole o/p in o/p tape,
 each time we'll generate symbol at i th tape in o/p tape

Ignore all symbols before i .

Run for as many times as you want \rightarrow don't take care of time

o/p
tape



store this i th symbol in workspace.

Th^m

Ex.

Prove : $\overline{\text{PATH}} \in \text{NL}$ & $\text{PATH} \in \text{co-NL}$
 $\text{PATH} \in \text{co-NL}$

- \Rightarrow
1. \forall non-path from s to t in $G \rightarrow$ accept
 2. \exists a path $\sim \rightarrow$ reject
- \rightarrow Difficult to prove (PATH \in NL: easy to prove).

We've to use guess mechanism \rightarrow Have to reject all paths from s to t .

1st theory: If ensure 2nd part, 1st part not ensured (unlike PATH \in NL proof)

24/04/19

Th^m

Ex. $\overline{\text{PATH}} = \{ \langle G, s, t \rangle \mid \text{node } t \text{ is not reachable from node } s \text{ in } G \}$ $\in \text{NL}$

$A_i = \{ v \mid \text{node } v \text{ is reachable from } s \text{ in } G \text{ within } i\text{-steps} \}$
 $C_i = |A_i|$ $0 \leq i \leq |V(G)|$

\rightarrow no. of vertices in G

$C_{|V(G)|} \rightarrow$ no. of vertices reachable from s in at most $|V(G)|$ steps.

If $C_{|V(G)|}$ is given, we can check $A_{|V(G)|}$
 $d=0$

$A_{|V(G)|}$: 1. for each u in $V(G)$, guess a path from s to u .

If guess is correct $\rightarrow d++$
 else \rightarrow reject
~~else~~ \rightarrow reject

2. If t is reachable \rightarrow reject

3. If $d \neq C_{|V(G)|} \rightarrow$ reject [not able to find correct size of $A_{|V(G)|}$]

4. Otherwise \rightarrow accept [correctness of $C_{|V(G)|}$ means correctness of our algo]

\hookrightarrow if $d = C_{|V(G)|} \rightarrow C_{|V(G)|}$ provided to us was correct.

$\rightarrow C_0 = |\{s\}| \rightarrow$ this we know, is correct

Assume that C_i is correct.

We'll try to find correct value of C_{i+1} from correctness of C_i

By doing this, if we reach
 $i = |V(G)| - 1 \rightarrow$ Our algo is correct

For calc. C_i , we will ~~per~~ execute the algorithm [use C_i instead of $C_{|V(G)|}$]

* suppose, we get some $C_i = \{i+1, \dots\}$

for $\forall u \in V(G)$

for $u \in C_i$ $d = C_i$
 \rightarrow check if u is reachable from C_i or not in at most d steps
 \rightarrow if ~~reach~~ \exists an edge

if $(u, v) \in E(G)$:

$C_{i+1}++$

→ 1 - for each $v \in V[G]$

2. Assume we have correct value of G , we're checking by a for loop
 $u \in V[G]$

3. if $(u, v) \in E[G] \Rightarrow C_{i+1}++;$ → go to 1;

↳ checking every pair

→ given : A_i

you want to calculate : A_{i+1}

for each u in $V[G]$

for each v in A_i

if $(v, u) \in E[G]$

$A_{i+1} = A_i \cup \{u\}$

→ If you maintain set, it'll take more space → using counter
 $\Downarrow C_i$

Here, we're starting from A_i to get A_{i+1}

→ ~~Suppose C_i is given.~~

→

Space taken = $O(\log n)$ → only storing variables.