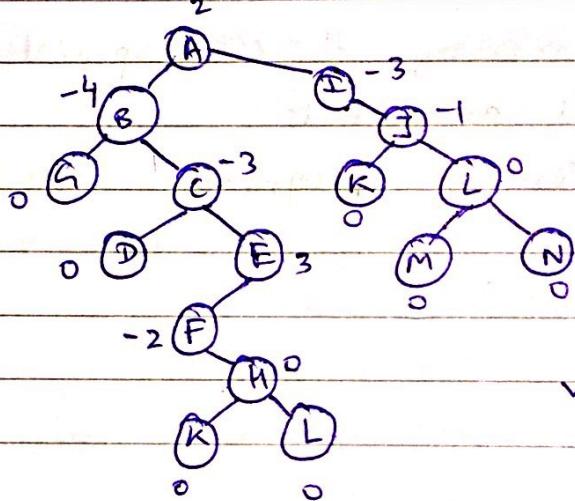


AVL Tree

Height Balanced Tree:

NOTE: Balance factor = height of left subtree - height of right subtree

Q.1

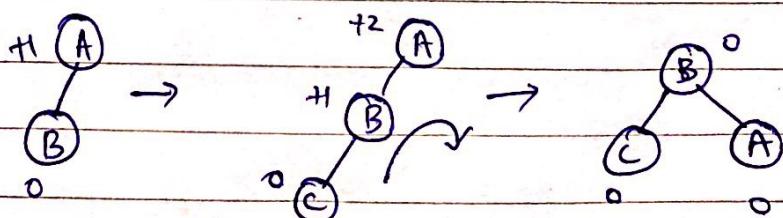


Fnd balance factor.

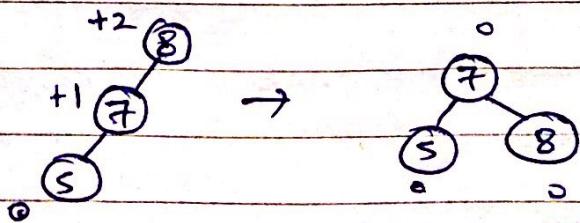
✓

NOTE: AVL tree has balance factor of +1, 0 or -1 for # nodes. If bf goes beyond this then rotation is done to maintain ~~bf~~ bf = +1, 0, -1

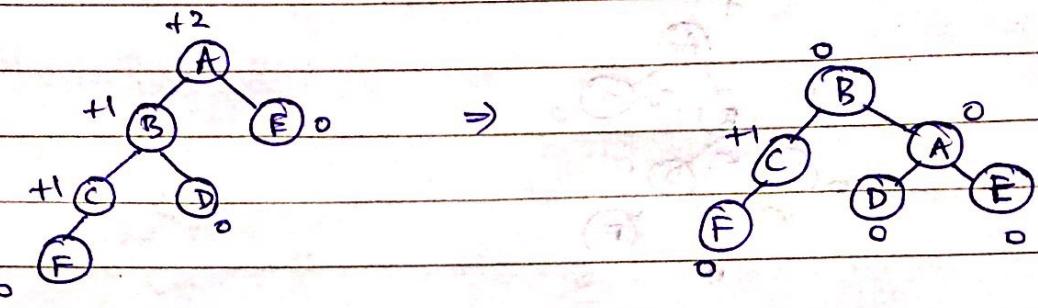
LL Rotation:



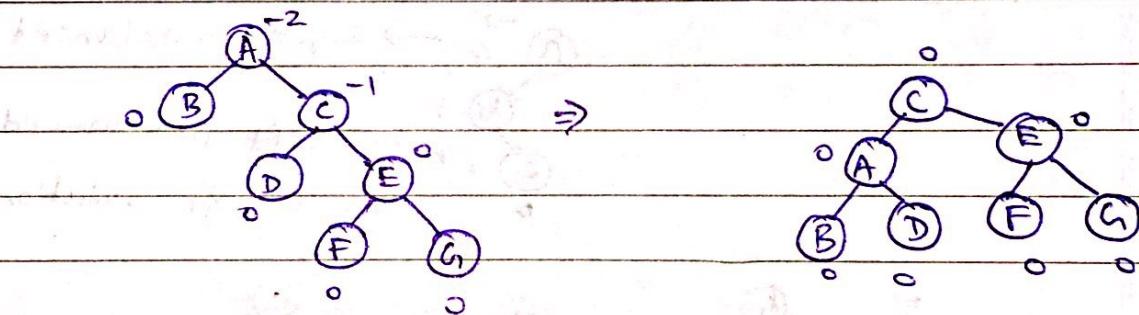
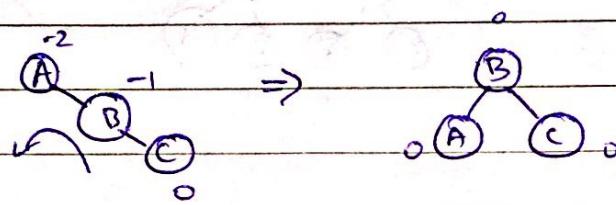
bst eg:



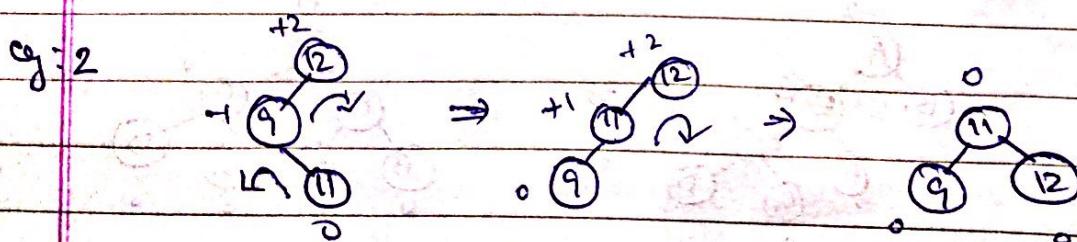
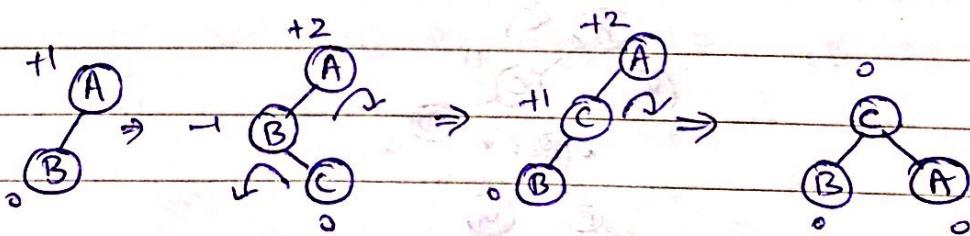
Teacher's Signature

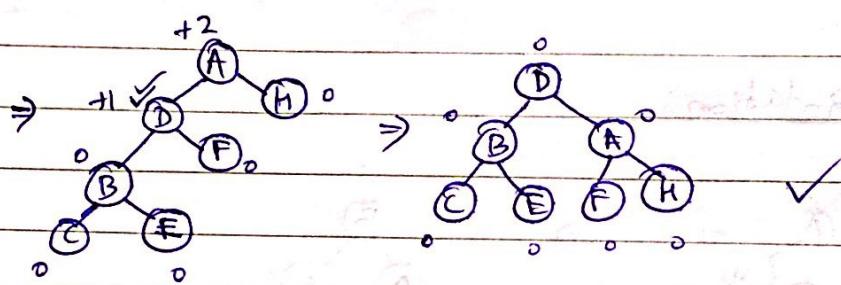
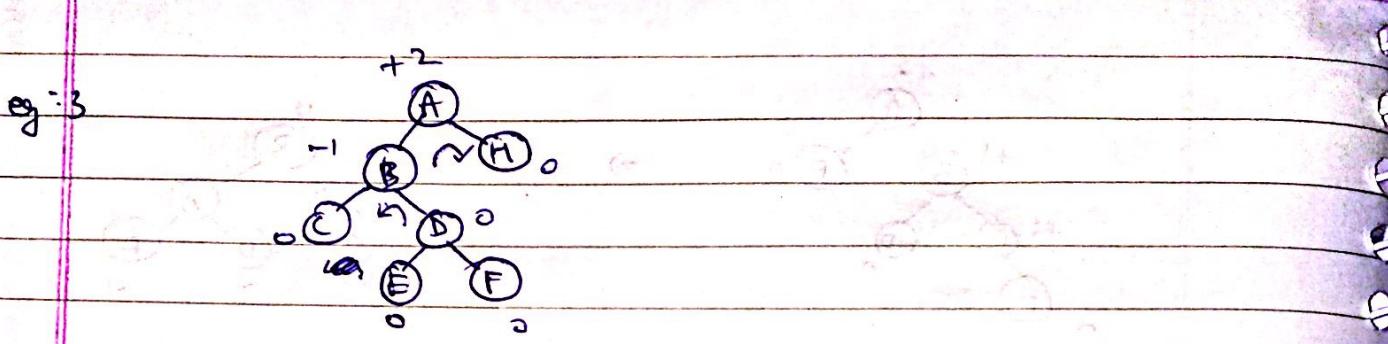


RR Rotation:

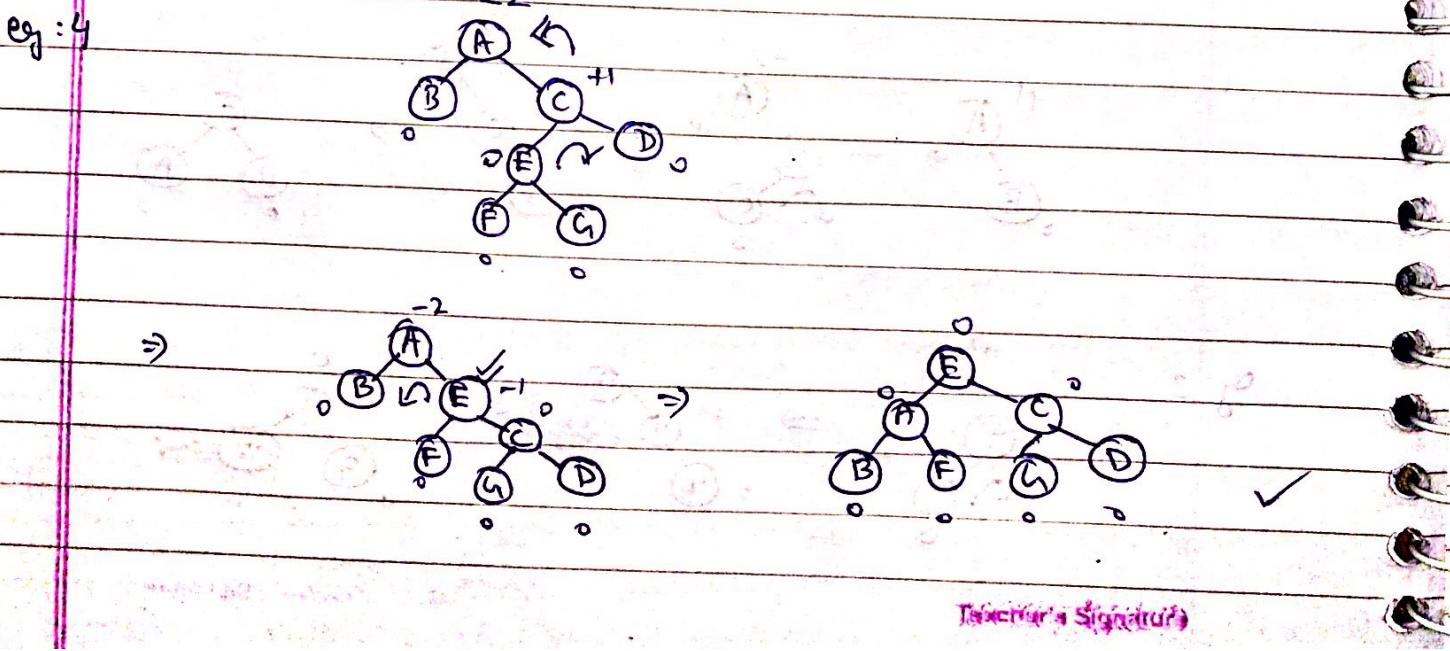
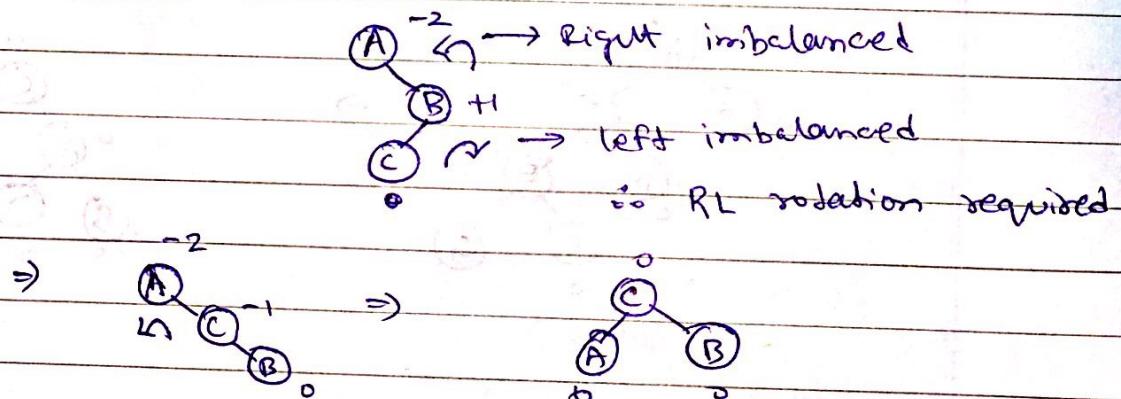


LR Rotation:





RL Rotation:

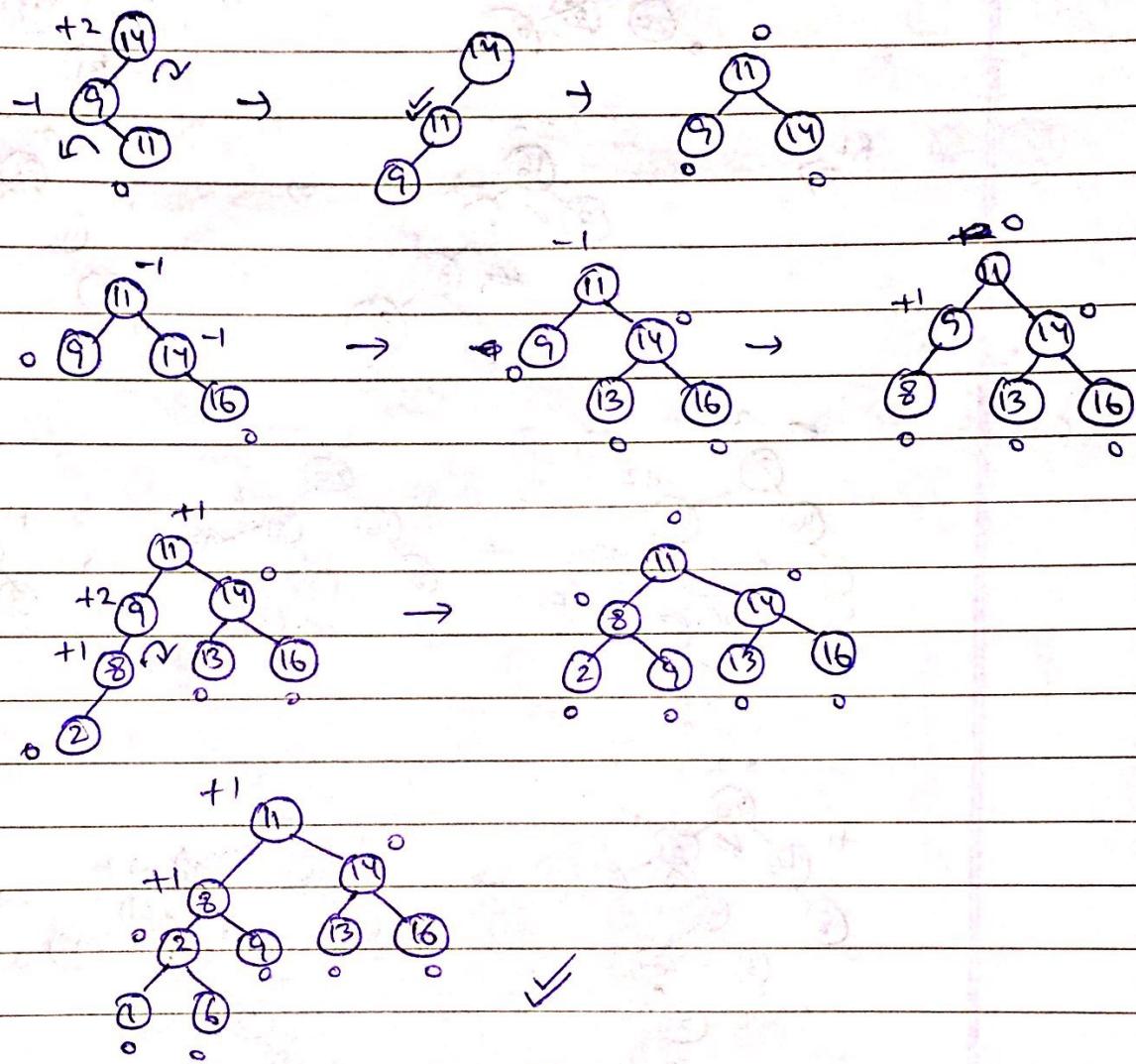


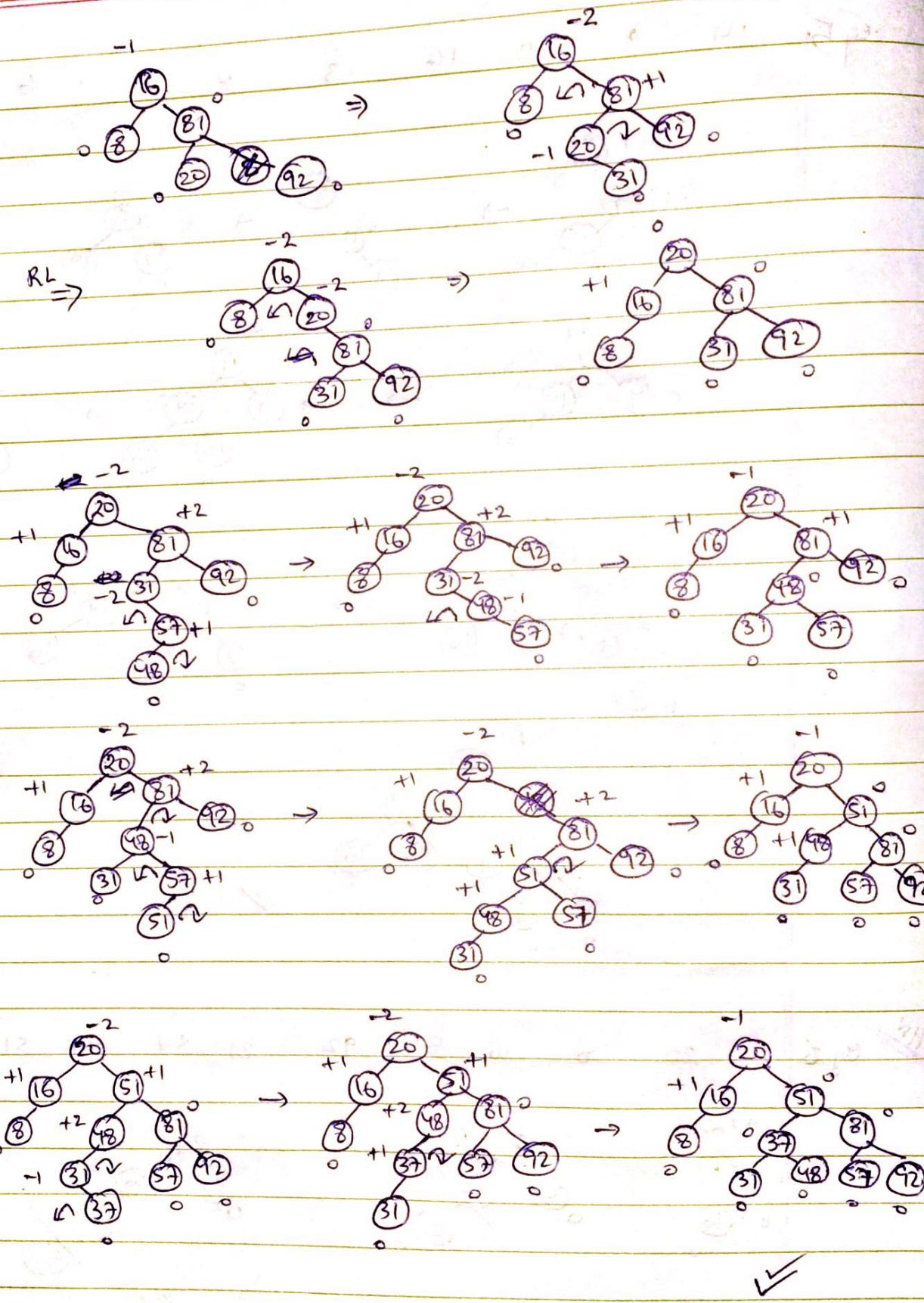
Delecting Signature?

INSERTION IN AVL

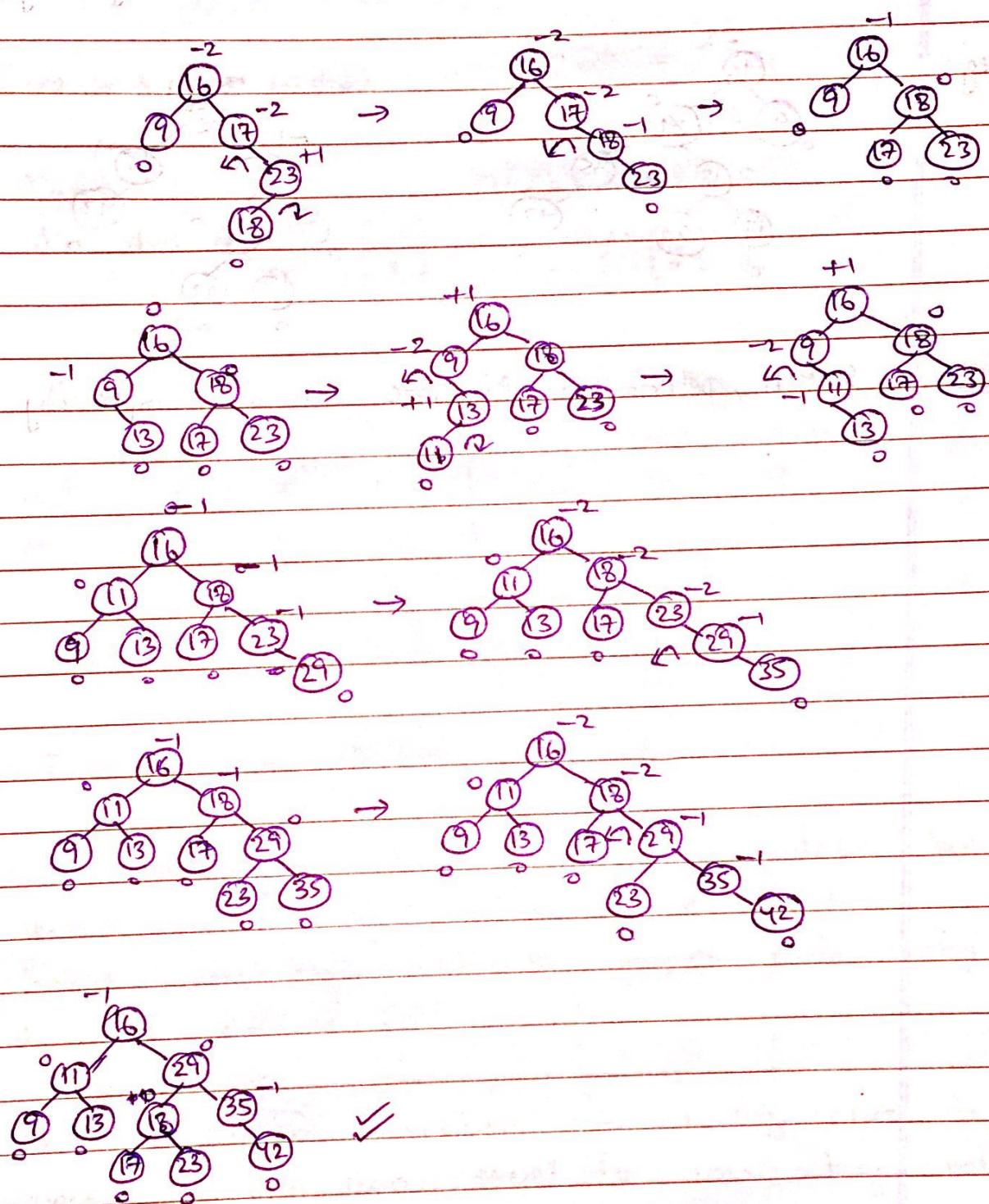
DATE : / /
PAGE NO.:

eg 5 14 9 11 16 13 8 2 1 6





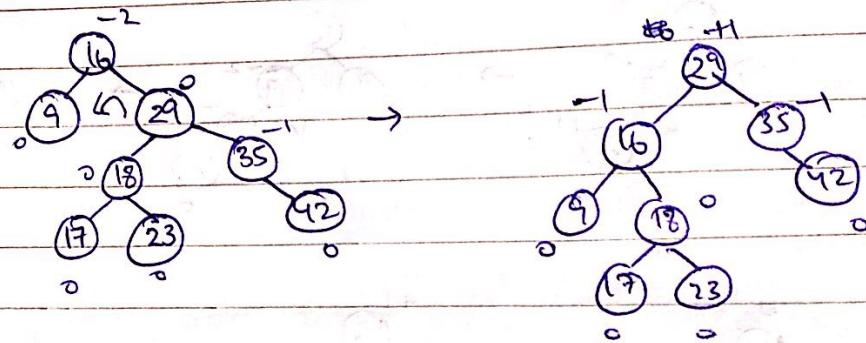
eg 3: 16, 9, 17, 23, 18, 13, 11, 29, 35, 42



Note:

Insertion in AVL tree is of complexity $\log_2 n$

e.g.



Note:

Search, Deletion in AVL tree is of complexity $\log_2 n$

B-Tree (Multiway Tree) :-

m-way (m paths)

Rule: Max. child = m Max Key = m-1

Min child = $\lceil \frac{m}{2} \rceil$ Min key = $\lfloor \frac{m-1}{2} \rfloor$

e.g.

5 way	
child	key
Max.	5 4
Min	(3) 2

8 way	
child	key
Max.	8 7
Min	4 3

NOTE: Only root can have 1 value

Insertion in B-Tree:

Each node in B-Tree contains multiple key values and they are in sorted order.

Insert new key value in proper node using the same process of BST.

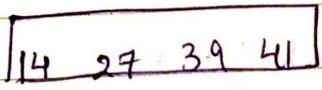
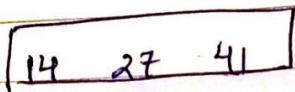
Case I: If after doing insertion no. of key values in the node is less than equal to max. key values, it is okay (no modification req.)

Else, split the node by making middle node as parent node. All key values at left as left child and all key values at right as right child.

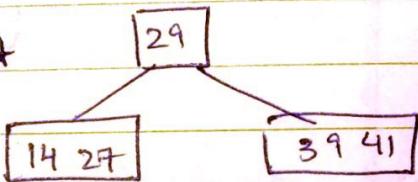
Teacher's Signature

eg:

5-way



→ split



eg: 14, 5, 21, 1, 6, 8, 9, 11, 13, 27, 3, 18, 19, 15, 34, 39

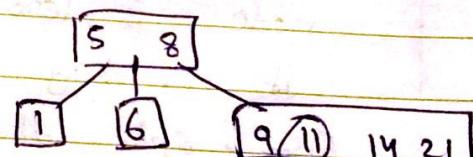
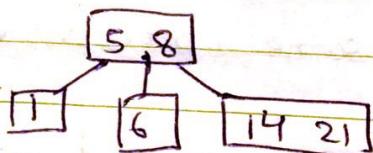
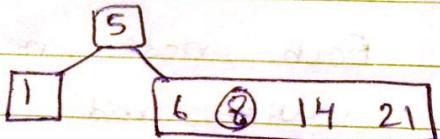
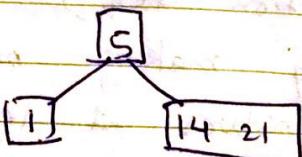
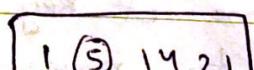
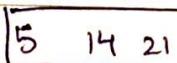
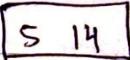
sol:

4-Way

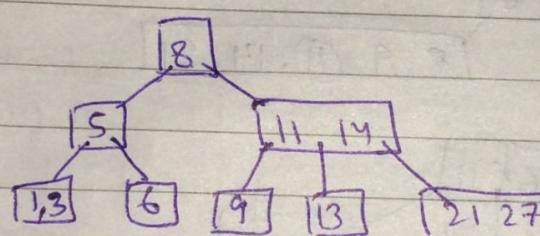
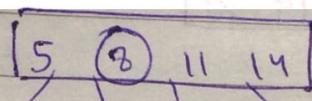
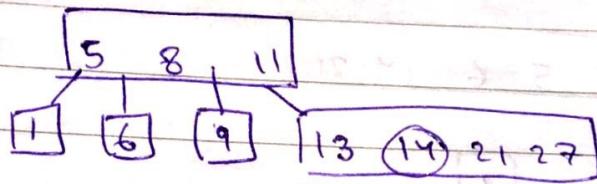
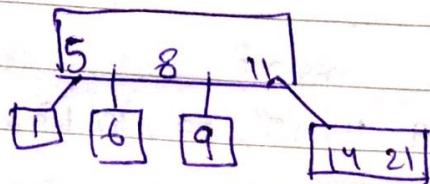
Max: 4 3

Min: 2 1

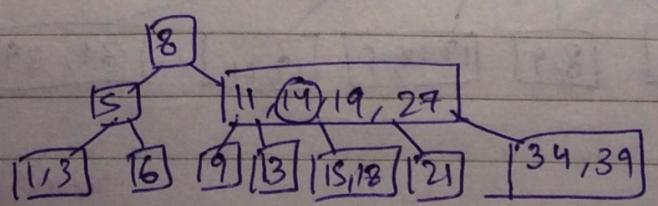
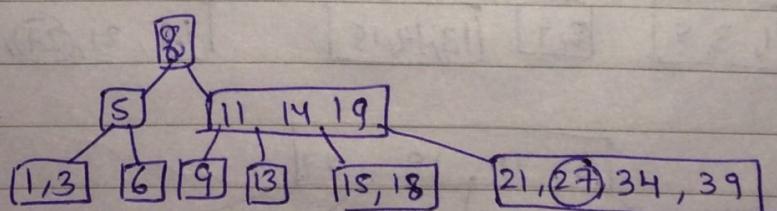
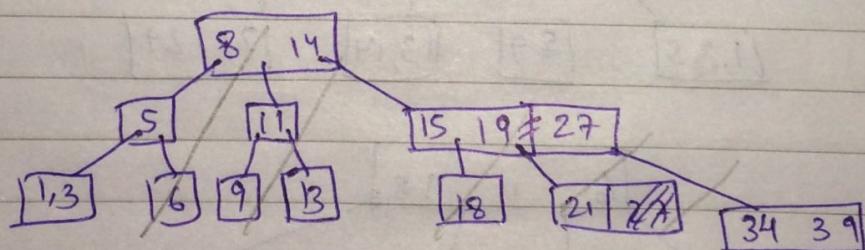
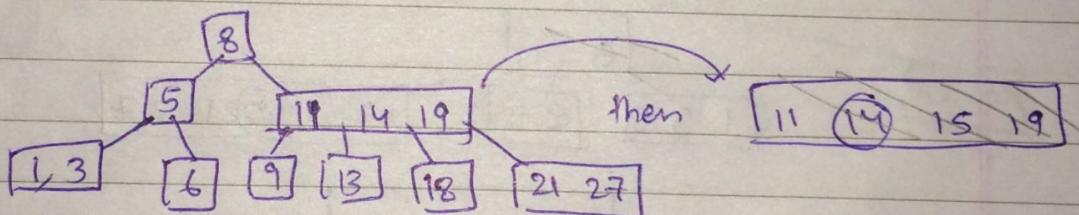
mid key



Teacher's Signature



then → [18, 19, 21, 27]

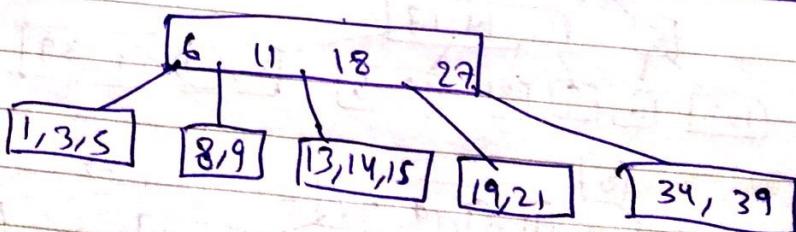
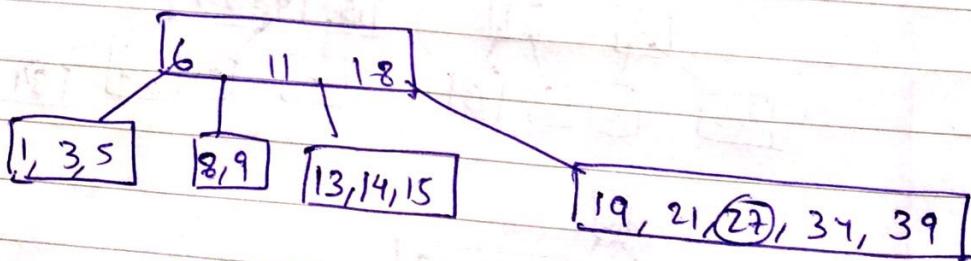
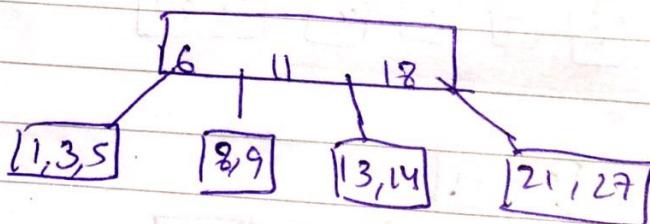
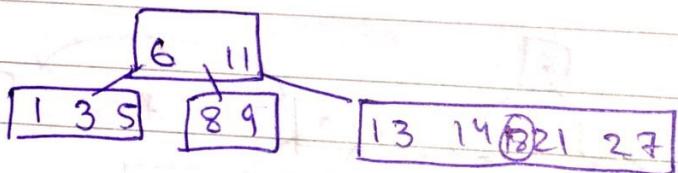
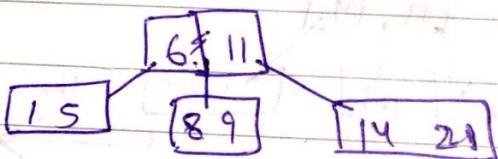
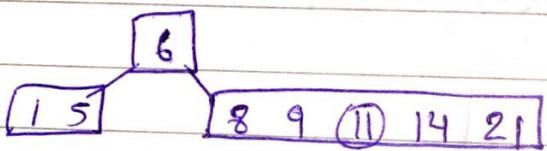
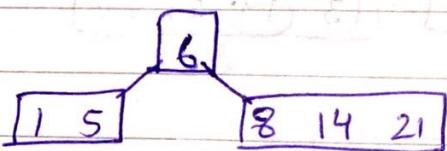
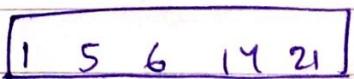


→ Teacher's Signature
✓

eg: Using 5-way tree insert

19, 5, 21, 1, 6, 8, 9, 11, 13, 27, 31, 18, 19, 15, 34, 39

Sol:



Teacher's Signature

Deletion in B-tree

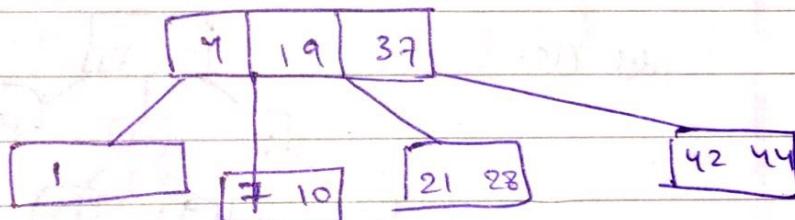
- * leaf node: → If node contains more than min key value then simply delete the value
- * Non-leaf node: If node contains min keys then replace it with its inorder predecessor or successor who ever is containing more than min key values. If none is having so, then merge them.

e.g:-

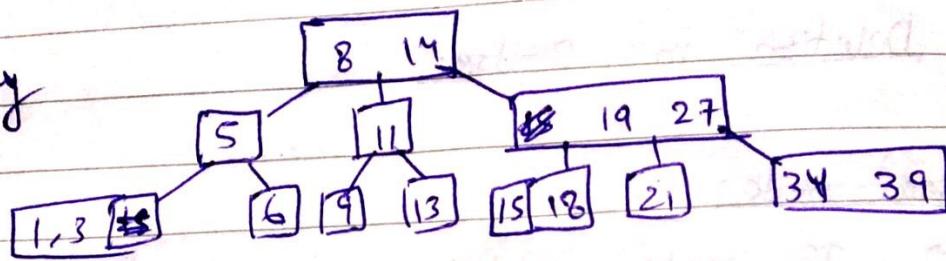
4-way

min key = 1

max keys = 3



eg : 4-way



Delete (1)

del (39)

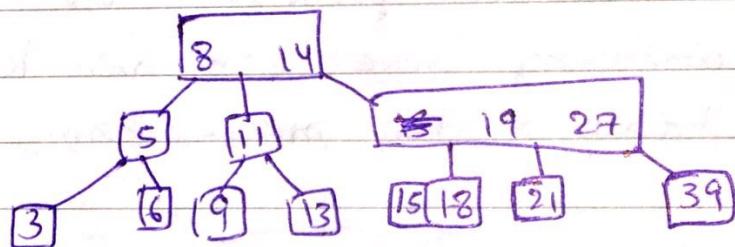
~~del (15)~~

~~del (18)~~

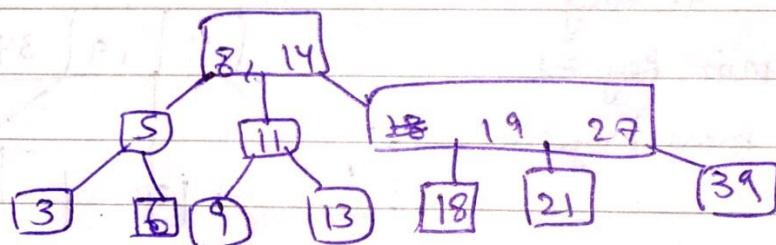
Sol:

del (1)

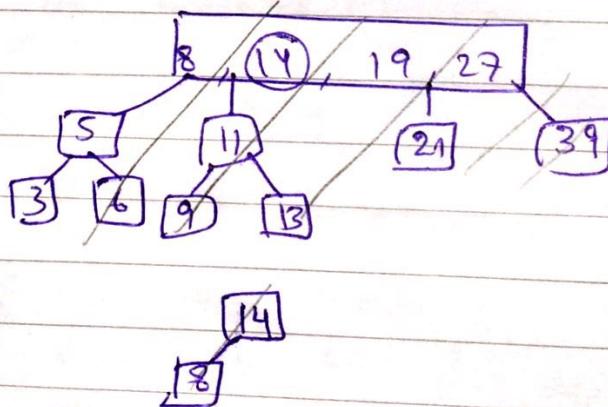
del (34)



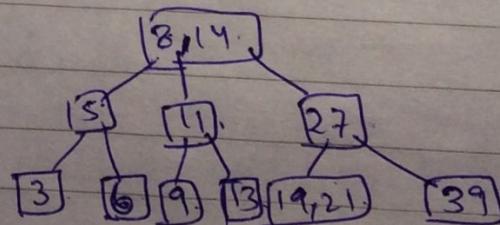
del (15)



~~del (18)~~



del (13)



NOTE: 2-3 tree (3 Way)

SORTING ALGORITHMS:

(I) Selection Sort:

Min. value is selected and placed in its proper place.

		After pass I	II	III	IV	V
0	14	1	1	1	1	1
1	9	9	3	3	3	3
2	17	17	17	6	6	6
3	3	3	9	9	9	9
4	6	6	6	17	17	14
5	1	14	14	14	14	17

for ($i=0$; $i < n$; $i++$)

```
void selection (int a[], int n)
{
    int i, j, min, p;
    for (i=0 ; i < n-1 ; i++)
    {
        min = a[i]; p=i;
        for (j=i+1 ; j < n ; j++)
        {
            if (a[j] < min)
            {
                p=j;
                min = a[j];
            }
        }
        swap (a[i], min, p);
    }
}
```

Teacher's Signature

// swap (a[i], min)

a[p] = a[i];

a[i] = min;

} // i loop

} // selection

Note: Time complexity of selection sort is $O(n^2)$ // possible case

② Insertion sort: Insert an ele in already sorted array

0	14	9	9	3	3	1
1	9	<u>14</u>	14	9	6	3
2	17	17	<u>17</u>	14	9	6
3	3	3	3	<u>17</u>	14	9
4	6	6	6	6	<u>17</u>	14
5	1	1	1	1	1	<u>17</u>

void insertion (int a[], int n)

{ int i, j, ele;

for (i=1; i<=n-1; i++)

{ ele = a[i];

j = i-1;

while ((j >= 0) && (a[j] > ele))

{ a[j+1] = a[j];

j = j-1;

y a[j+1] = ele;

Teacher's Signature

2-3 TREES

2-3 Trees:

- Every internal node is either a 2-node or a 3-node.
- A 2-node has one key and 2 children / subtrees.
- A 3-node has 2 keys and 3 children / subtrees.
- A 2-3 tree doesn't resemble a full binary tree.
- If a 2-3 tree does not contain 3-nodes, it is like a full binary tree since all its internal nodes have 2 children and all its leaves are at the same level.
- If a 2-3 tree does have 3 children, the tree will contain more nodes than a full binary tree of same height.
- So, a 2-3 tree of height h at least $2^h - 1$ nodes.

③ Bubble sort :

0	14	9	9	3	1
1	9	14	14 9 3	9 1	3
2	17	17 3	17 1	9	9
3	3	17 1	14	14	14
4	1	17	17	17	17

void bubbleSort (int a[], int n)

{ int i, j, flag;

for (i=0; i<n-1; i++)

{ flag = 0;

for (j=0; j<n-i-1; j++)

{ if (a[j] > a[j+1])

{ swap (a[j], a[j+1]); flag = 1; }

} → if (flag == 0) break;

}

}

Complexity = $O(n)$ + best, worst, avg. case
= $O(n^2)$ + worst, avg. case

④ Merging:

It takes 2 sorted arrays as input and outputs a sorted array.

void Merge (int a[], int n, int b[], int m)

int c[20], i, j, k; i=0; j=0; k=0;

while ((i < n) && (j < m))

{

if (a[i] < b[j])

{ c[k] = a[i];

i++;

}

else { c[k] = b[j];

j++;

}

c[k+1:k+1]; }

if (i == n)

{ for (; j < m; j++)

c[k+j] = b[j]; }

}

else { for (; i < n; i++)

c[i+k] = a[i];

}

}

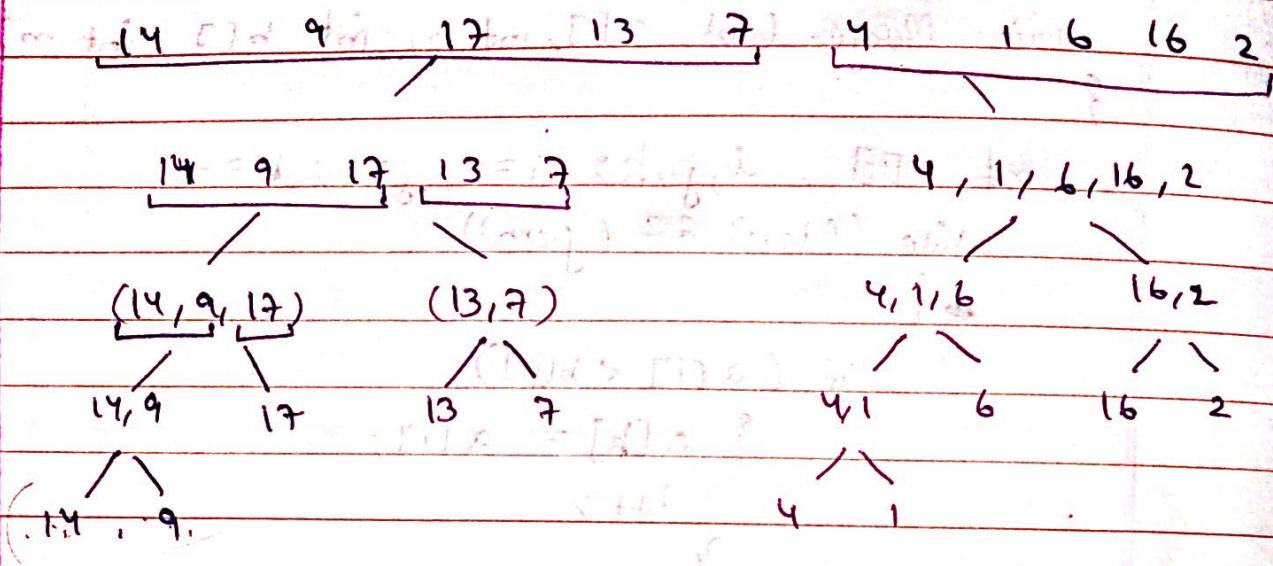
⑤

Merge Sort:

0	1	2	3	4	5	6	7	8	9
14	9	17	13	7	4	1	6	16	2

Divide & conquer: l=0, h=9, m= $\frac{0+9}{2} = 4$

Teacher's Signature



void Mergesort (int a[], int n)

{ void Mergesort (int low, int high)

```

    int mid;
    if (low < high)
    {
        mid = (low + high) / 2;
        Mergesort (low, mid);
        Mergesort (mid + 1, high);
        Merge (low, mid, high);
    }
}

```

void Merge (int low, int mid, int high)

```

{
    int b[20], i, j, k;
    i = low; j = mid + 1; k = low;
    while ((i <= mid) && (j <= high))
    {
        if (a[i] < a[j])

```

Teacher's Signature

```
{ c[k] = a[i];  
    i++;  
}
```

```
else { c[k] = a[j];
```

```
    j++;  
}
```

```
k++;
```

```
}
```

```
if (i == n)
```

```
{ // copy b's elements)
```

```
for ( ; j < m; j++)
```

```
c[k++] = a[j];
```

```
}
```

```
else {
```

```
for ( ; i < n; i++)
```

```
c[k++] = a[i];
```

```
for (i = low; i <= high; i++)
```

```
a[i] = c[i];
```

Complexity:

$$T(n) = T(n/2) + T(n/2) + n$$

$$T(n) = 2T(n/2) + n$$

$$T(n) = 2T(n/2) + n$$

$$= 2[2T(n/4) + n/2] + n$$

$$= 4T(n/4) + n + n = 4T(n/4) + 2n$$

$$= 4(2 \cdot T(n/8) + n/4) + 2n = 8T(n/8) + 3n$$

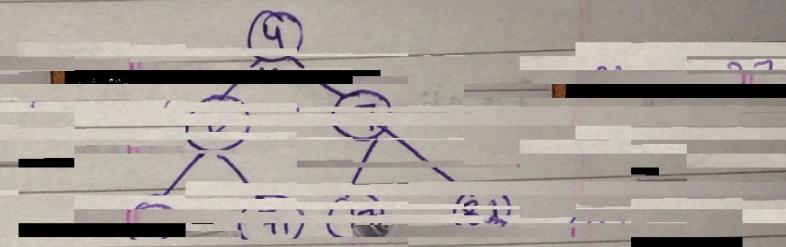
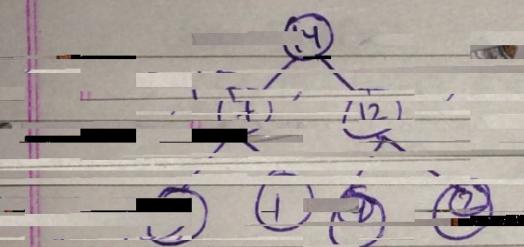
$$T(n) = \dots$$

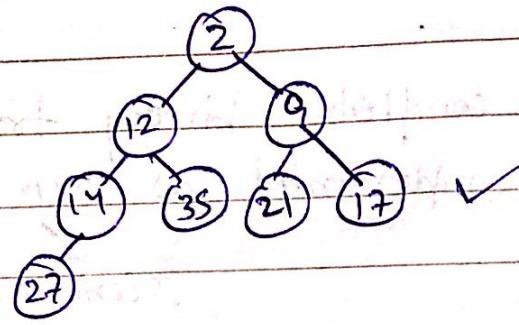
Teacher's Signature

$$\begin{aligned}
 T(n) &= 2^i T\left(\frac{n}{2^i}\right) + i \times n \\
 &= n \cdot T(1) + n \times \log_2 n \\
 &= n + n \log_2 n \\
 T(n) &= O(n \log_2 n)
 \end{aligned}
 \quad \left. \begin{array}{l} \frac{n}{2^i} = 1 \\ n = 2^i \\ i = \log_2 n \end{array} \right\}$$

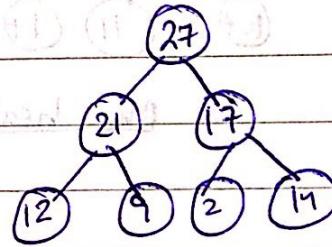
HEAP:

- It's almost complete binary tree
- It can be implemented as MIN heap / MAX heap
 - parent < child
 - parent > child

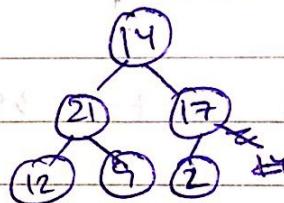




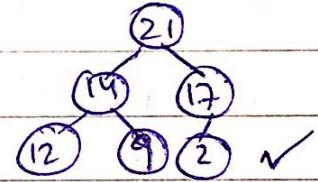
II. Deletion :



del (27)



\leftrightarrow



Insertion in Heap (Algorithm by H.M.S) Hansi & Sahni

```
insert(a,n)
{
```

i=n;

item = a[n];

while ((i>=1) && (a[i/2] < item))

```
{ a[i] = a[i/2];
```

i = i/2;

```
}
```

a[i]=item;

```
}
```

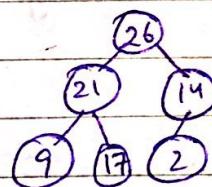
for (n=1; n<=b; n++)

```
{
```

sf("1.d", a[n])

adjust(a,n)

```
}
```



1	2	3	4	5	6
26	21	14	9	17	2

Delmax (a, n, x)

```
{ if (n==0)
```

if ("Heap empty");

else

```
{ x = a[i];
```

a[i] = a[n];

adjust (a, 1, n-1)

```
}
```

Teacher's Signature

adjust (a, i, n)

{

J = $2^* i$;

item = a[i];

while (J <= n)

{

if ((J < n) and (a[J] < a[J+1])) J = J + 1;

if (item > a[J])

break;

a[J/2] = a[J];

J = $2^* J$;

}

a[J/2] = item;

}

Q1: Implement 3-way heap.

Q1: Which one of the following is valid sequence of elements in an array representing 3-way heap.

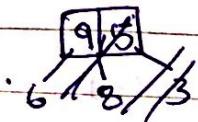
(A) 1, 3, 5, 6, 8, 9

(B) 9, 6, 3, 1, 8, 5

(C) 9, 3, 6, 8, 5, 1

(D) 9, 5, 6, 8, 3, 1

Q2: Insert 7, 2, 10, 4 in (D)



Q.3. In a binary max heap what is the time complexity to find min element?

Ans: O(n)

Q.4. Complexity of converting an array to heap.

(A) O(n)

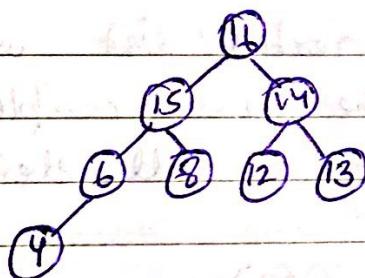
(B) O(log n)

~~(C) O(n log n)~~

(D) None of these

Q.5. How many swaps are required to extract max-element from max-heap.

16, 15, 14, 6, 8, 12, 13, 4 - Heap structure



Sol: 2 swaps

[Note: 4 is just copied to 16 not swapped]

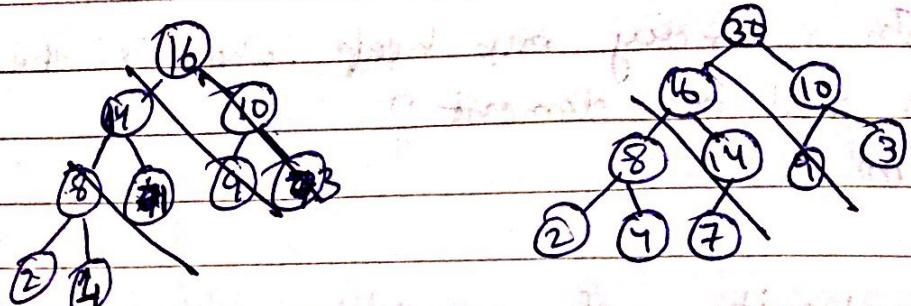
15 is swapped with 14,
4 is swapped with 8]

Q.6. Consider a max-heap whose Inorder traversal is:

2, 8, 4, 14, 1, 7, 16, 9, 10, 3

Insert 30 in this heap. Write Inorder traversal for new heap.

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Ans: 2, 8, 4, 16, 1, 14, 7, 30, 9, 10, 3 ✓

Solutions:

Q. 7 Suppose there are $\log n$ rooted list with $n/\log n$ elements. Find the time complexity of producing a sorted list of all elements.

Sol:

$$\Theta\left(\frac{n}{\log n} \cdot \log n\right) = O(n)$$

Hashing: Used to search an element in min. no. of comparison.

NOTE: Time complexity of hashing is $O(1)$.
The hash func: $h(x) = x \mod 10$ is called Division Remainder Method.

Mid-Square Method:

$h(x) = x^2$ pick middle y digits
 $y \rightarrow$ is defined based on array size

$$x = 12$$

$$x^2 = \underline{144}$$

$$x = 1632$$

$$x^2 = \underline{\underline{26632}4}$$

Folding Method:

- x is partitioned \rightarrow into equal size part x_1, x_2, \dots, x_m
- Add the subpart
- Ignore carry

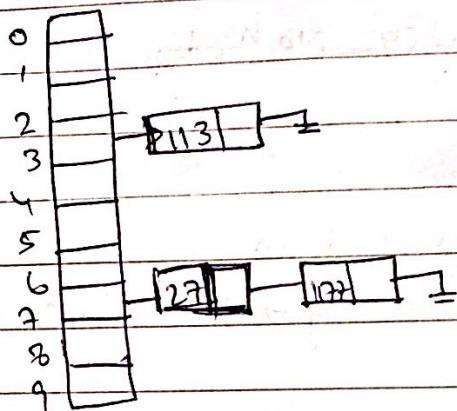
eg $x = \underline{17}, \underline{23}, \underline{11}, \underline{1} , y = 17 + 23 + 11 + 1 = 41$

$$x = \underline{92}, \underline{17}, \underline{13}, \quad y = 92 + 17 + 13 = 122$$

Hash collisions: When 2 or more values are generated through same hash function, it's called hash collision.

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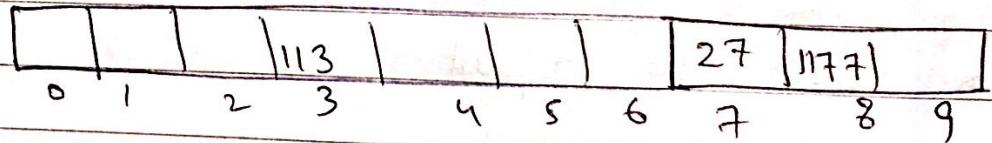
To solve the above problem linked list can be created. But it's not efficient as time complexity again becomes $O(n)$.



Open addressing:

→ "Linear probing"

$$y' = (y+i) \cdot 10$$



"Quadratic probing":

$$y' = (y + c_1 i^2 + c_2 i + c_3) \cdot 10$$

Double Hashing:

$$y = h(x), \quad y' = h'(x)$$

two diff. hash functions

$$l = h, h+h', h+2h', h+3h'$$

\hookrightarrow location value

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Rehashing : Increasing the storage space for data and performing hashing again on the elements.

Q1. A hash table of length 10 uses open addressing with hash function $h(k) = k \cdot 10$ and use linear probing to resolve collision. After inserting 6 values your hash table is as follows:-

0	1	2	3	4	5	6	7	8	9
		42	23	34	52	46	33		

(i) Which one of the following gives a possible order in which key values could have inserted in table

- (a) 46, 42, 34, 52, 23, 33
- (b) 34, 42, 23, 52, 33, 46
- (c) 46, 34, 42, 23, 52, 33
- (d) 42, 46, 33, 23, 34, 52

A - 52

B - 33

C - 33

(ii) How many different insertion seq. of key val(s) using the same hash func and linear probing are possible?

- (a) 10
- (b) 20
- (c) 30
- (d) 40

Q2. Consider hash table of size 7 (starting index 0)
 $h(x) = (3x + 4) \% 7$

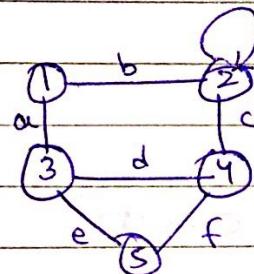
Hash table is initially empty. Insert 1, 3, 8, 10. If collision use linear probing

0	1	2	3	4	5	6
61	8	10		3		3

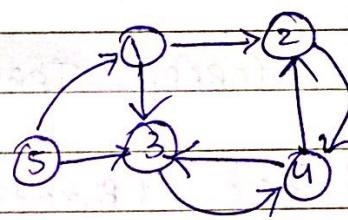
- (a) 8 — 10
- (b) 1 — 3
- (c) 1 8 10 — 3
- (d) 1 10 8 — 3

GRAPH:

- It's a non-linear data structure
- Graph is tree with cycle
- Graph can be represented by (V, E)
 - $V \rightarrow$ set of vertices
 - $E \rightarrow$ " edges



Undirected graph



Directed graph

Graph can be represented through two methods:

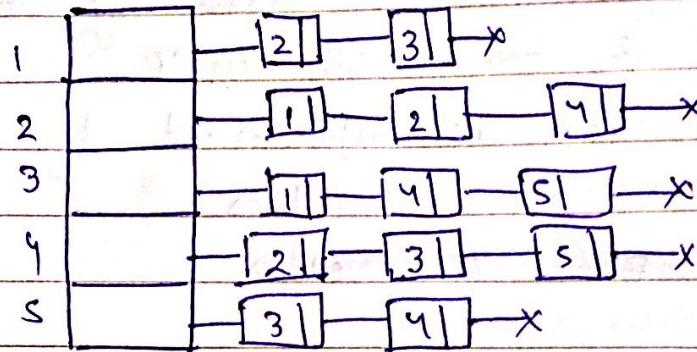
I. Adjacency Matrix: $(V \times V)$

	1	2	3	4	5
1	0	1	1	0	0
2	1	0	0	1	0
3	1	0	0	1	0
4	0	1	1	0	1
5	0	0	1	1	0

If there is an edge b/w vertex i and vertex j then $G[i][j] = 1$ else entry is 0

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II. Adjacency list:



GRAPH TRAVERSAL:

- I. BFS (Breadth First Search) - (Queue)
- II. DFS (Depth ") - (Stack)

I. BFS (V)

{ visited [1:v] initialized to zero

insert_grevue (v)

while (grevue not empty)

{ w = delete_grevue()

if visited [w] == 0

{ print w;

visited [w] = 1

insert all adj of w }

→ w = delete_grevue

visited [w] = 1

print w

ins k adj to w grevue
if visited [w] == 0

- II. DFS - Just replace insert () by push() and delete () by pop().

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