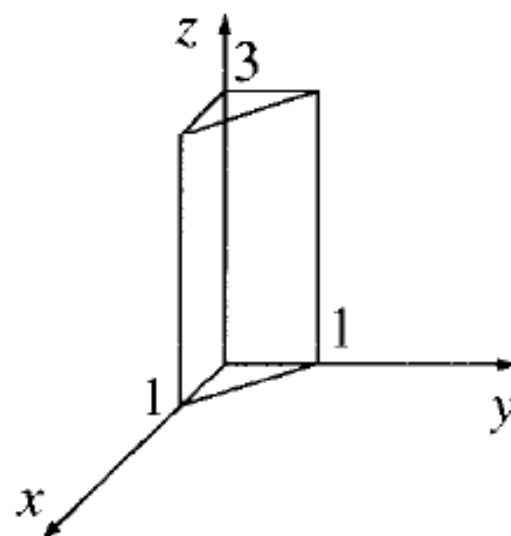
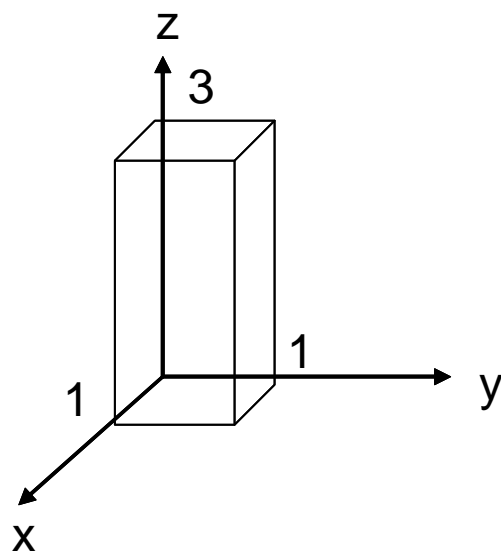


# Volume Integral

$$\int_V T d\tau \quad d\tau = dx dy dz$$

Calculate the volume integral of  $T = xyz^2$  over the prism in Fig.



$$\int T d\tau = \int_0^3 z^2 \left\{ \int_0^1 y \left[ \int_0^{1-y} x dx \right] dy \right\} dz =$$

$$\frac{1}{2} \int_0^3 z^2 dz \int_0^1 (1-y)^2 y dy = \frac{1}{2} (9) \left( \frac{1}{12} \right) = \frac{3}{8}.$$

## The Fundamental Theorem for Gradients

The integral of a derivative over a region is equal to the value of the function at the boundary

$$\int_{\mathcal{P}}^{\mathbf{b}} (\nabla T) \cdot d\mathbf{l} = T(\mathbf{b}) - T(\mathbf{a}).$$

$$dT = (\nabla T) \cdot d\mathbf{l}_1$$

Difference of function's value at b and a

**Corollary 1:**  $\int_{\mathbf{a}}^{\mathbf{b}} (\nabla T) \cdot d\mathbf{l}$  is independent of path taken from **a** to **b**.

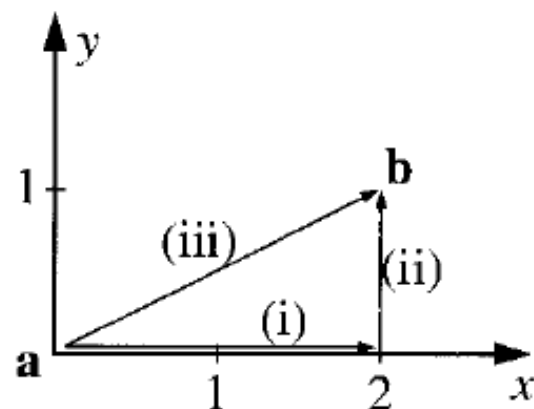
**Corollary 2:**  $\oint (\nabla T) \cdot d\mathbf{l} = 0$ , since the beginning and end points are identical, and hence  $T(\mathbf{b}) - T(\mathbf{a}) = 0$ .

$$\vec{\nabla} \times \vec{\nabla} T = 0$$

$$\vec{\nabla} \times \vec{F} = 0$$

F conservative field

Let  $T = xy^2$ , and take point **a** to be the origin  $(0, 0, 0)$  and **b** the point  $(2, 1, 0)$ . Check the fundamental theorem for gradients.



**Divergence**

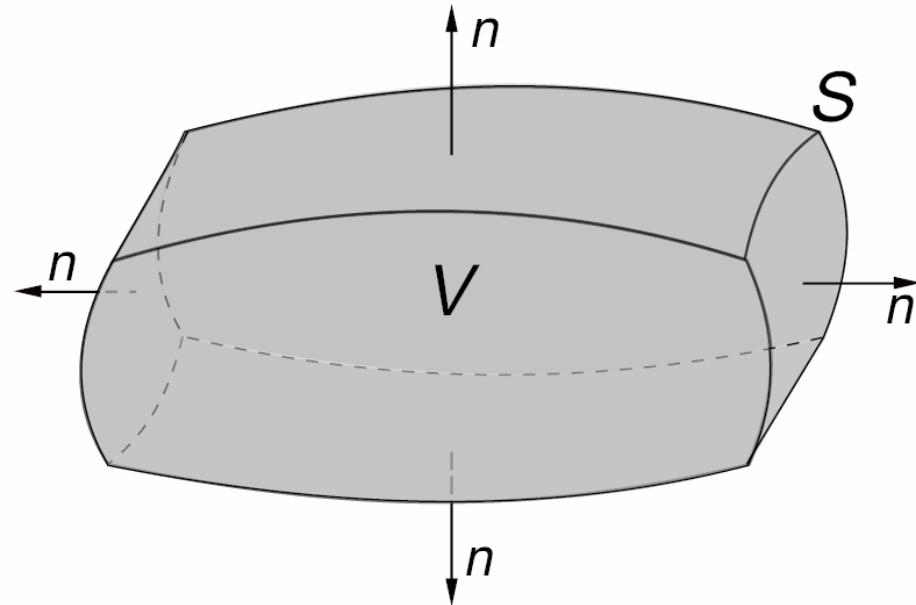
$$\operatorname{div} \vec{F} = \lim_{\Delta v \rightarrow 0} \frac{\oiint_S \vec{F} \cdot d\vec{s}}{\Delta v}$$

**Curl**

$$\lim_{\Delta S \rightarrow 0} \frac{\oint \vec{F} \cdot d\vec{l}}{\Delta S} = (\operatorname{curl} F) \cdot \hat{n}$$

# The Fundamental Theorem for Divergences

$$\int_V (\nabla \cdot \mathbf{v}) d\tau = \oint_S \mathbf{v} \cdot d\mathbf{a}.$$

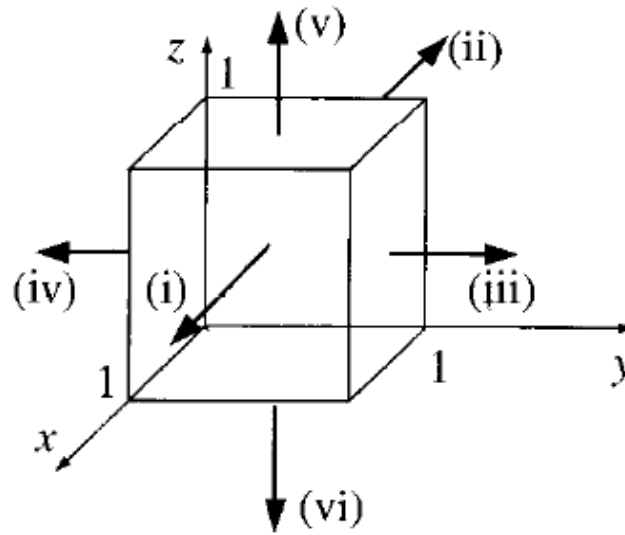


The integral of a derivative over a region is equal to the value of the function at the boundary

$$\nabla \cdot \vec{V} = \text{outflow} - \text{inflow} \longrightarrow \begin{array}{ll} +\text{ve} & (\text{source}) \\ -\text{ve} & (\text{sink}) \end{array}$$

$$\int (\text{faucets within the volume}) = \oint (\text{flow out through the surface})$$

Check the divergence theorem using the function  $\mathbf{v} = y^2 \hat{\mathbf{x}} + (2xy + z^2) \hat{\mathbf{y}} + (2yz) \hat{\mathbf{z}}$



$$(iii) \quad \int \mathbf{v} \cdot d\mathbf{a} = \int_0^1 \int_0^1 (2x + z^2) dx dz = \frac{4}{3}.$$

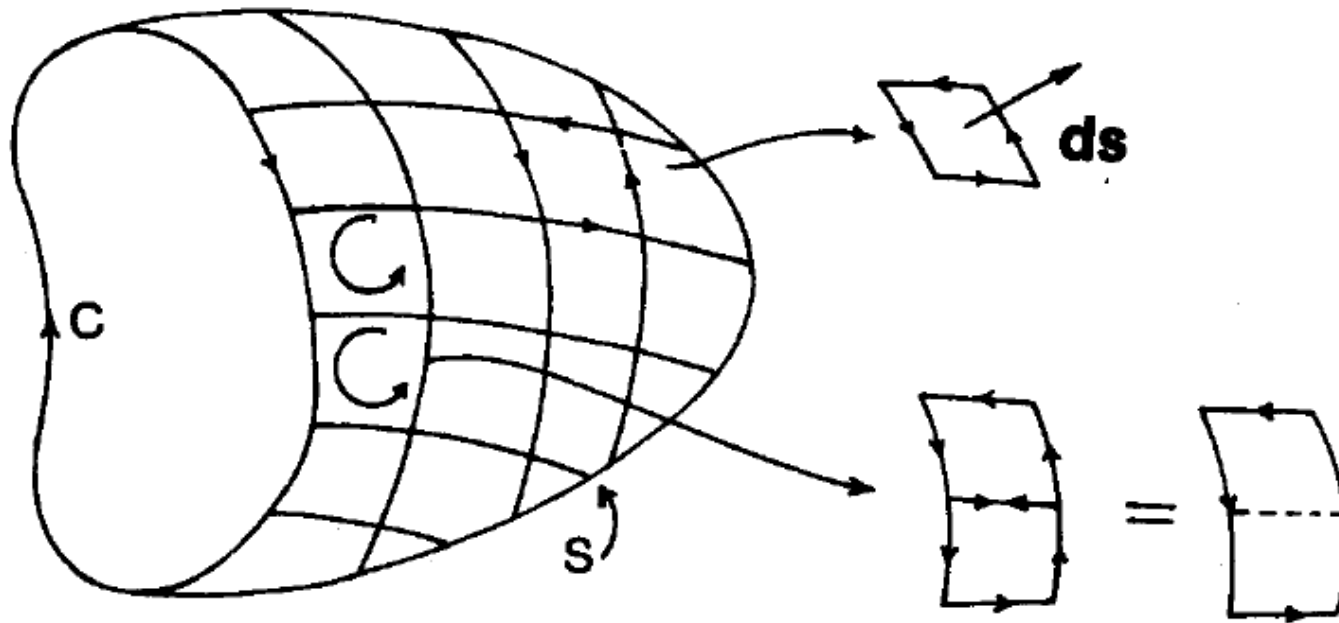
$$(iv) \quad \int \mathbf{v} \cdot d\mathbf{a} = - \int_0^1 \int_0^1 z^2 dx dz = -\frac{1}{3}.$$

$$(v) \quad \int \mathbf{v} \cdot d\mathbf{a} = \int_0^1 \int_0^1 2y dx dy = 1.$$

## The Fundamental Theorem for Curls Stokes' theorem

$$\int_S (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \oint_P \mathbf{v} \cdot d\mathbf{l}.$$

The integral of a derivative over a region is equal to the value of the function at the boundary



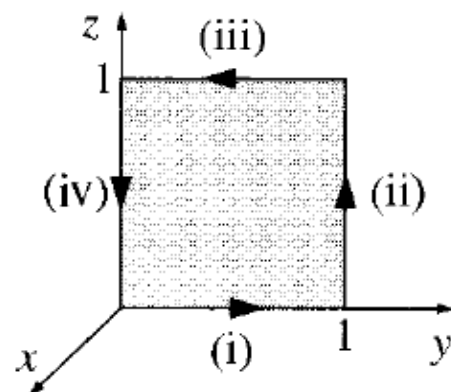
rotational force field / non-conservative force field

**Corollary 1:**  $\int (\nabla \times \mathbf{v}) \cdot d\mathbf{a}$  depends only on the boundary line, not on the particular surface used.

**Corollary 2:**  $\oint (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = 0$  for any closed surface



Suppose  $\mathbf{v} = (2xz + 3y^2)\hat{\mathbf{y}} + (4yz^2)\hat{\mathbf{z}}$ . Check Stokes' theorem for the square surface



$$\nabla \times \mathbf{v} = (4z^2 - 2x)\hat{\mathbf{x}} + 2z\hat{\mathbf{z}} \quad \text{and} \quad d\mathbf{a} = dy dz \hat{\mathbf{x}}.$$

$$\int (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \int_0^1 \int_0^1 4z^2 dy dz = \frac{4}{3}.$$

$$(i) \quad x = 0, \quad z = 0, \quad \mathbf{v} \cdot d\mathbf{l} = 3y^2 dy, \quad \int \mathbf{v} \cdot d\mathbf{l} = \int_0^1 3y^2 dy = 1,$$

$$(ii) \quad x = 0, \quad y = 1, \quad \mathbf{v} \cdot d\mathbf{l} = 4z^2 dz, \quad \int \mathbf{v} \cdot d\mathbf{l} = \int_0^1 4z^2 dz = \frac{4}{3},$$

$$(iii) \quad x = 0, \quad z = 1, \quad \mathbf{v} \cdot d\mathbf{l} = 3y^2 dy, \quad \int \mathbf{v} \cdot d\mathbf{l} = \int_1^0 3y^2 dy = -1,$$

$$(iv) \quad x = 0, \quad y = 0, \quad \mathbf{v} \cdot d\mathbf{l} = 0, \quad \int \mathbf{v} \cdot d\mathbf{l} = \int_1^0 0 dz = 0.$$

$$\oint \mathbf{v} \cdot d\mathbf{l} = 1 + \frac{4}{3} - 1 + 0 = \frac{4}{3}$$

- **Concepts of Vector Field**
- **Gradient [converts scalar field to a vector field]**
- **Divergence [A measure of change of flux per unit volume]**
- **Curl [measure of rotational nature of a vector field]**
- **Line integration**
- **Surface integration**
- **Volume integration**
- **Fundamental theorem for Gradient**
- **Fundamental theorem for Divergence**
- **Fundamental theorem for Curl**

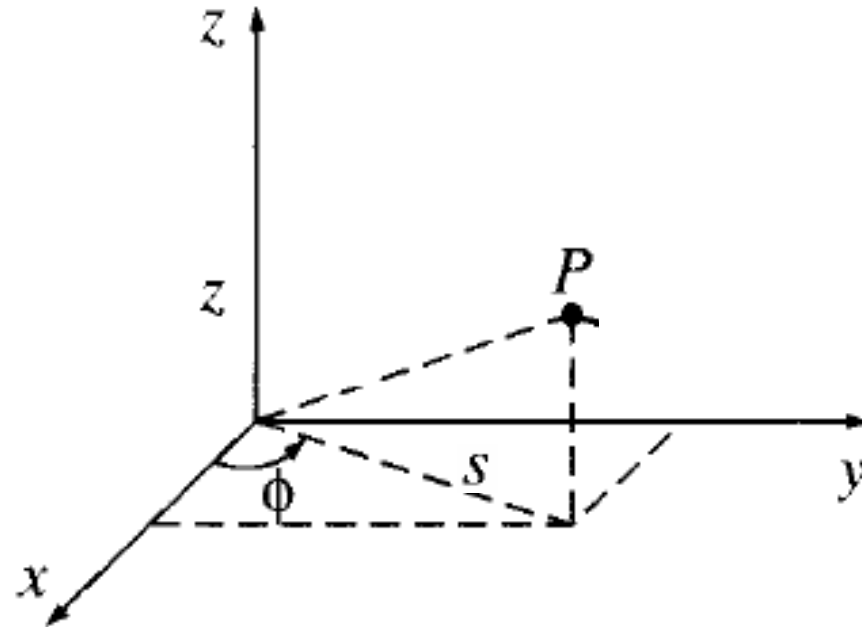
# Cylindrical and spherical co-ordinate system

# Cylindrical Coordinates

$$0 \leq s \leq \infty$$

$$0 \leq \varphi \leq 2\pi$$

$$-\infty \leq z \leq \infty$$



$s$

$\varphi$

$z$

$$x = s \cos \phi, \quad y = s \sin \phi, \quad z = z$$

$$s = \sqrt{x^2 + y^2} \quad \varphi = \tan^{-1} \left( \frac{y}{x} \right) \quad z = z$$

## Unit Vectors

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\hat{s} = \frac{\frac{\partial \vec{r}}{\partial s}}{\left| \frac{\partial \vec{r}}{\partial s} \right|} \quad \hat{\phi} = \frac{\frac{\partial \vec{r}}{\partial \phi}}{\left| \frac{\partial \vec{r}}{\partial \phi} \right|} \quad \hat{z} = \frac{\frac{\partial \vec{r}}{\partial z}}{\left| \frac{\partial \vec{r}}{\partial z} \right|}$$

$$\vec{r} = s \cos \phi \hat{i} + s \sin \phi \hat{j} + z\hat{k}$$

$$\hat{s} = \cos \phi \hat{i} + \sin \phi \hat{j}$$

$$\hat{\phi} = -\sin \phi \hat{i} + \cos \phi \hat{j}$$

$$\hat{z} = \hat{k}$$