## CHAPTER-7 COORDINATE GEOMETRY

## Excercise 7.4

Q4. The two opposite vertices of a square are (-1,2) and (3,2). Find the coordinates of the other two vertices.

## Solution:

Given points

$$\mathbf{A} = \begin{pmatrix} -1\\2 \end{pmatrix}, \mathbf{C} = \begin{pmatrix} 3\\2 \end{pmatrix} \tag{1}$$

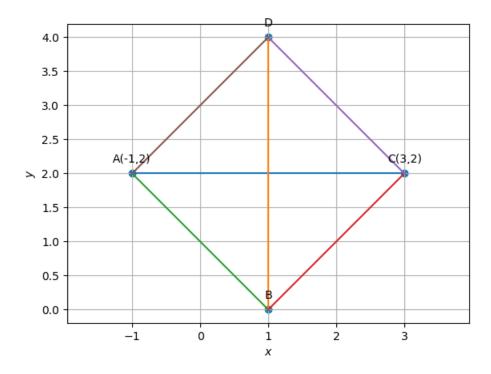


Figure 1:

Shifting  ${\bf A}$  to origin with refrence to Figure 2

$$\mathbf{A}' = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \mathbf{C}' = \mathbf{C} - \mathbf{A} = \begin{pmatrix} 4 \\ 0 \end{pmatrix} \tag{2}$$

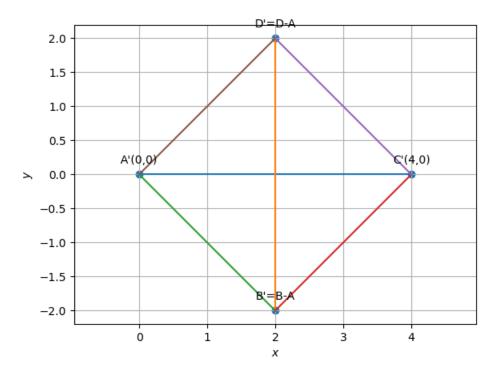


Figure 2:

For a generalised case, the angle made by AC on the x-axis will be  $\theta+45^{\circ}$ , where  $\theta$  is the angle made by AB on the x-axis. Hence, we can calculate the angle made by AB on the x-axis as.

direction vector is given as

$$\mathbf{C} - \mathbf{A} = \begin{pmatrix} 4 \\ 0 \end{pmatrix} \tag{3}$$

However in this particular case, angle made by AC on the x-axis

$$\tan \beta = \frac{0}{4} \implies \sin \beta = \frac{0}{4} \tag{4}$$

$$\beta = 0^{\circ} \tag{5}$$

Therefore, here  $\theta = -45^{\circ}$ 

We know the rotation matrix for CW rotation is given as

$$\mathbf{P}^{\top} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \tag{6}$$

Since the angle here is negative so ultimately the coordinates will be rotated in ACW direction. Now the transformed(rotated) coordinates are with refrence to Figure 3.

$$\mathbf{C}'' = \mathbf{P}(\mathbf{C} - \mathbf{A}) = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 4 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{4}{\sqrt{2}} \\ \frac{4}{\sqrt{2}} \end{pmatrix}$$
(7)

$$\mathbf{B}'' = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \mathbf{C}'' = \begin{pmatrix} \frac{4}{\sqrt{2}} \\ 0 \end{pmatrix}, \mathbf{D}'' = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{C}'' = \begin{pmatrix} 0 \\ \frac{4}{\sqrt{2}} \end{pmatrix} \text{ and } \mathbf{A}'' = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
 (8)

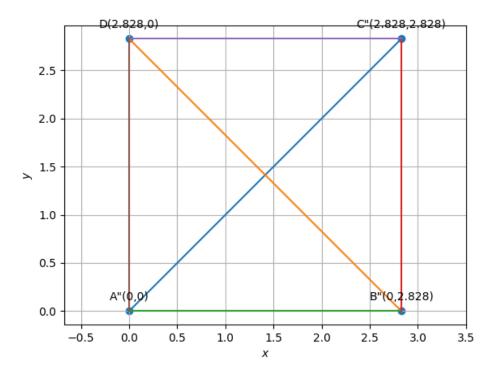


Figure 3:

Again tranforming(rotating) the coordinates back to the original axis. We know for anti-clockwise direction the rotation matrix is given as

$$\mathbf{P} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \tag{9}$$

Again we know that the angle is negative so the rotation will be in clockwise direction. So now the transformed(rotated) coordinates  ${\bf B}$  and  ${\bf D}$  are with refrence to Figure 4

$$\mathbf{B}' = \mathbf{P}\mathbf{B}' = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{4}{\sqrt{2}} \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \end{pmatrix}$$
(10)

$$\mathbf{D}' = \mathbf{P}\mathbf{D}'' = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 \\ \frac{4}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$
 (11)

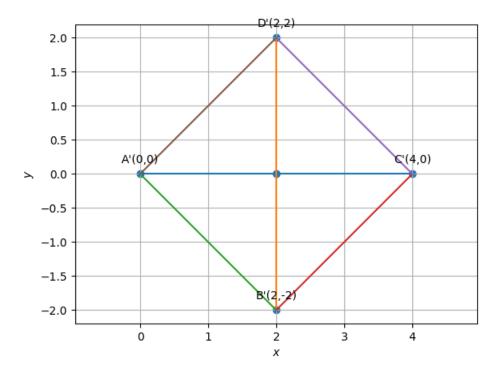


Figure 4:

Again transforming (shifting) the axis back to the original with refrence to Figure  $5\,$ 

$$\mathbf{B} = \mathbf{B}' + \mathbf{A} = \begin{pmatrix} 2 \\ -2 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \tag{12}$$

$$\mathbf{D} = \mathbf{D}' + \mathbf{A} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix} \tag{13}$$

Hence, the other two vertices are  $\mathbf{B}(1,0)$  and  $\mathbf{D}(1,4)$ The direct formula for calculation of the vertices is:

$$\mathbf{B} = \mathbf{A} + \mathbf{P} \begin{pmatrix} \mathbf{e_1} & \mathbf{0} \end{pmatrix} \mathbf{P}^{\top} (\mathbf{C} - \mathbf{A})$$
 (14)

$$\mathbf{D} = \mathbf{A} + \mathbf{P} \begin{pmatrix} \mathbf{0} & \mathbf{e_2} \end{pmatrix} \mathbf{P}^{\mathsf{T}} (\mathbf{C} - \mathbf{A}) \tag{15}$$

(16)

where  $\mathbf{P}$  is the rotation matrix and  $\mathbf{A}$  and  $\mathbf{C}$  are the position vectors of opposite vertices.

Verification of the above formula for the given question

$$\mathbf{B} = \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 1 & 0\\0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}}\\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 4\\0 \end{pmatrix}$$
(17)

$$= \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 1 & 0\\0 & 0 \end{pmatrix} \begin{pmatrix} \frac{4}{\sqrt{2}}\\ \frac{4}{\sqrt{2}} \end{pmatrix}$$
(18)

$$= \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{4}{\sqrt{2}}\\0 \end{pmatrix} \tag{19}$$

$$= \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} 2\\-2 \end{pmatrix} \tag{20}$$

$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \tag{21}$$

$$\mathbf{D} = \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 0\\0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}}\\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 4\\0 \end{pmatrix}$$
(22)

$$= \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 0\\0 & 1 \end{pmatrix} \begin{pmatrix} \frac{4}{\sqrt{2}}\\ \frac{4}{\sqrt{2}} \end{pmatrix}$$
(23)

$$= \begin{pmatrix} -1\\2 \end{pmatrix} + \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0\\ \frac{4}{\sqrt{2}} \end{pmatrix} \tag{24}$$

$$= \binom{-1}{2} + \binom{2}{2} \tag{25}$$

$$= \begin{pmatrix} 1 \\ 4 \end{pmatrix} \tag{26}$$

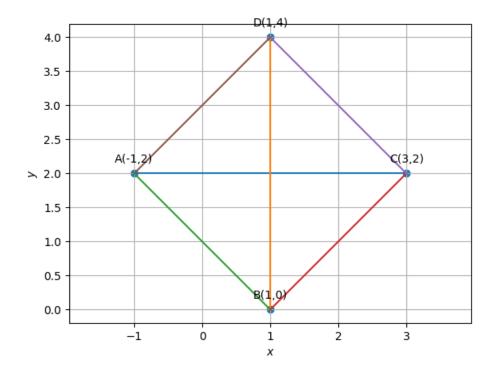


Figure 5: