ASSIGNMENT →3 SOFT COMPUTING

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import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
"""## Load the data: the Cats vs Dogs dataset
### Raw data download
First, let's download the 786M ZIP archive of the raw data:
!curl -O https://download.microsoft.com/download/3/E/1/3E1C3F21-ECDB-4869-
8368-6DEBA77B919F/kagglecatsanddogs_5340.zip
!unzip -q kagglecatsanddogs_5340.zip
"""Now we have a `PetImages` folder which contain two subfolders, `Cat` and
`Dog`. Each
subfolder contains image files for each category.
!ls PetImages
"""### Filter out corrupted images
When working with lots of real-world image data, corrupted images are a common
occurence. Let's filter out badly-encoded images that do not feature the
string "JFIF"
in their header.
import os
num_skipped = 0
for folder_name in ("Cat", "Dog"):
    folder_path = os.path.join("PetImages", folder_name)
   for fname in os.listdir(folder path):
```

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fpath = os.path.join(folder_path, fname)
        try:
            fobj = open(fpath, "rb")
            is_jfif = tf.compat.as_bytes("JFIF") in fobj.peek(10)
        finally:
            fobj.close()
        if not is_jfif:
            num_skipped += 1
            # Delete corrupted image
            os.remove(fpath)
print("Deleted %d images" % num_skipped)
"""## Generate a `Dataset`"""
image_size = (180, 180)
batch_size = 128
train_ds, val_ds = tf.keras.utils.image_dataset_from_directory(
    "PetImages",
   validation_split=0.2,
    subset="both",
    seed=1337,
    image_size=image_size,
   batch_size=batch_size,
"""## Visualize the data
Here are the first 9 images in the training dataset. As you can see, label 1
is "dog"
and label 0 is "cat".
import matplotlib.pyplot as plt
plt.figure(figsize=(10, 10))
for images, labels in train_ds.take(1):
    for i in range(9):
        ax = plt.subplot(3, 3, i + 1)
        plt.imshow(images[i].numpy().astype("uint8"))
       plt.title(int(labels[i]))
       plt.axis("off")
"""## Using image data augmentation
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When you don't have a large image dataset, it's a good practice to
artificially
introduce sample diversity by applying random yet realistic transformations to
training images, such as random horizontal flipping or small random rotations.
This
helps expose the model to different aspects of the training data while slowing
down
overfitting.
data_augmentation = keras.Sequential(
        layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.1),
    ]
"""Let's visualize what the augmented samples look like, by applying
data augmentation`
repeatedly to the first image in the dataset:
plt.figure(figsize=(10, 10))
for images, _ in train_ds.take(1):
    for i in range(9):
        augmented_images = data_augmentation(images)
        ax = plt.subplot(3, 3, i + 1)
        plt.imshow(augmented_images[0].numpy().astype("uint8"))
        plt.axis("off")
"""## Standardizing the data
Our image are already in a standard size (180x180), as they are being yielded
as
contiguous `float32` batches by our dataset. However, their RGB channel values
are in
the `[0, 255]` range. This is not ideal for a neural network;
in general you should seek to make your input values small. Here, we will
standardize values to be in the `[0, 1]` by using a `Rescaling` layer at the
start of
our model.
## Two options to preprocess the data
There are two ways you could be using the `data_augmentation` preprocessor:
**Option 1: Make it part of the model**, like this:
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``python
inputs = keras.Input(shape=input shape)
x = data_augmentation(inputs)
c = layers.Rescaling(1./255)(x)
... # Rest of the model
With this option, your data augmentation will happen *on device*,
synchronously
with the rest of the model execution, meaning that it will benefit from GPU
acceleration.
Note that data augmentation is inactive at test time, so the input samples
will only be
augmented during `fit()`, not when calling `evaluate()` or `predict()`.
If you're training on GPU, this may be a good option.
**Option 2: apply it to the dataset**, so as to obtain a dataset that yields
batches of
augmented images, like this:
 ``python
augmented_train_ds = train_ds.map(
   lambda x, y: (data_augmentation(x, training=True), y))
With this option, your data augmentation will happen **on CPU**,
asynchronously, and will
be buffered before going into the model.
If you're training on CPU, this is the better option, since it makes data
augmentation
asynchronous and non-blocking.
In our case, we'll go with the second option. If you're not sure
which one to pick, this second option (asynchronous preprocessing) is always a
solid choice.
## Configure the dataset for performance
Let's apply data augmentation to our training dataset,
and let's make sure to use buffered prefetching so we can yield data from disk
without
having I/O becoming blocking:
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```
# Apply `data_augmentation` to the training images.
train ds = train ds.map(
    lambda img, label: (data_augmentation(img), label),
    num_parallel_calls=tf.data.AUTOTUNE,
# Prefetching samples in GPU memory helps maximize GPU utilization.
train_ds = train_ds.prefetch(tf.data.AUTOTUNE)
val ds = val ds.prefetch(tf.data.AUTOTUNE)
"""## Build a model
We'll build a small version of the Xception network. We haven't particularly
tried to
optimize the architecture; if you want to do a systematic search for the best
model
configuration, consider using
[KerasTuner](https://github.com/keras-team/keras-tuner).
Note that:
 We start the model with the `data_augmentation` preprocessor, followed by a
`Rescaling` layer.
 We include a `Dropout` layer before the final classification layer.
def make_model(input_shape, num_classes):
    inputs = keras.Input(shape=input_shape)
   # Entry block
   x = layers.Rescaling(1.0 / 255)(inputs)
   x = layers.Conv2D(128, 3, strides=2, padding="same")(x)
   x = layers.BatchNormalization()(x)
   x = layers.Activation("relu")(x)
    previous_block_activation = x # Set aside residual
   for size in [256, 512, 728]:
        x = layers.Activation("relu")(x)
        x = layers.SeparableConv2D(size, 3, padding="same")(x)
        x = layers.BatchNormalization()(x)
        x = layers.Activation("relu")(x)
        x = layers.SeparableConv2D(size, 3, padding="same")(x)
       x = layers.BatchNormalization()(x)
        x = layers.MaxPooling2D(3, strides=2, padding="same")(x)
        # Project residual
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residual = layers.Conv2D(size, 1, strides=2, padding="same")(
            previous block activation
        x = layers.add([x, residual]) # Add back residual
        previous_block_activation = x # Set aside next residual
    x = layers.SeparableConv2D(1024, 3, padding="same")(x)
    x = layers.BatchNormalization()(x)
    x = layers.Activation("relu")(x)
    x = layers.GlobalAveragePooling2D()(x)
    if num classes == 2:
        activation = "sigmoid"
       units = 1
    else:
        activation = "softmax"
        units = num classes
    x = layers.Dropout(0.5)(x)
    outputs = layers.Dense(units, activation=activation)(x)
    return keras.Model(inputs, outputs)
model = make model(input shape=image size + (3,), num classes=2)
keras.utils.plot_model(model, show_shapes=True)
"""## Train the model"""
epochs = 25
callbacks = [
    keras.callbacks.ModelCheckpoint("save_at_{epoch}.keras"),
model.compile(
    optimizer=keras.optimizers.Adam(1e-3),
    loss="binary_crossentropy",
   metrics=["accuracy"],
model.fit(
   train ds,
   epochs=epochs,
   callbacks=callbacks,
   validation_data=val_ds,
"""We get to >90% validation accuracy after training for 25 epochs on the full
(in practice, you can train for 50+ epochs before validation performance
starts degrading).
```

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## Run inference on new data

Note that data augmentation and dropout are inactive at inference time.
"""

img = keras.utils.load_img(
    "PetImages/Cat/6778.jpg", target_size=image_size
)
plt.imshow(img)

img_array = keras.utils.img_to_array(img)
img_array = tf.expand_dims(img_array, 0) # Create batch axis

predictions = model.predict(img_array)
score = float(predictions[0])
print(f"This image is {100 * (1 - score):.2f}% cat and {100 * score:.2f}% dog.")
```

