

$$\begin{aligned}
\sigma(x_i, y_j, t_{k+1}) &= -\frac{\tau}{\varphi} \left(\frac{u_1(x_{i+1}, y_j, t_k) - u_1(x_i, y_j, t_k)}{h} \right. \\
&\quad \left. + \frac{u_2(x_i, y_{j+1}, t_k) - u_2(x_i, y_j, t_k)}{H} \right) + \sigma(x_i, y_j, t_k) \\
\sigma(x_i, y_j, t_{k+1}) &= \frac{\tau}{\varphi} \left(\frac{w_1(x_{i+1}, y_j, t_k) - w_1(x_i, y_j, t_k)}{h} \right. \\
&\quad \left. + \frac{w_2(x_i, y_{j+1}, t_k) - w_2(x_i, y_j, t_k)}{H} \right) + \sigma(x_i, y_j, t_k)
\end{aligned}$$

$$\begin{aligned}
&u_1(x_{i+1}, y_j, t_k) - u_1(x_i, y_j, t_k) = \\
&-h \left(\frac{u_2(x_i, y_{j+1}, t_k) - u_2(x_i, y_j, t_k)}{H} \right) + \frac{\varphi}{\tau} (\sigma(x_i, y_j, t_{k+1}) - \sigma(x_i, y_j, t_k)) \\
&u_2(x_i, y_{j+1}, t_k) - u_2(x_i, y_j, t_k) = \\
&-H \left(\frac{u_1(x_{i+1}, y_j, t_k) - u_1(x_i, y_j, t_k)}{h} \right) + \frac{\varphi}{\tau} (\sigma(x_i, y_j, t_{k+1}) - \sigma(x_i, y_j, t_k))
\end{aligned}$$

$$P(x_{i+1}, y_j, t_k) = -h \left(\frac{\mu_2 * w_1(x_i, y_j, t_k)}{k * k_2(s_2, T, C)} \right) + \frac{\gamma * w_1(x_i, y_j, t_k)}{\sqrt{w_1^2(x_i, y_j, t_k) + w_2^2(x_i, y_j, t_k)}} +$$

$$P(x_i, y_{j+1}, t_k) = -H \left(\frac{\mu_2 * w_2(x_i, y_j, t_k)}{k * k_2(s_2, T, C)} + \frac{\frac{P(x_i, y_j, t_k) \gamma * w_2(x_i, y_j, t_k)}{\sqrt{w_1^2(x_i, y_j, t_k) + w_2^2(x_i, y_j, t_k)}}}{P(x_i, y_j, t_k)} \right) +$$

$$w_1 \equiv w_2 \equiv 0, \left(\frac{P(x_{i+1}, y_j, t_k) - P(x_i, y_j, t_k)}{h} \right)^2 + \left(\frac{P(x_i, y_{j+1}, t_k) - P(x_i, y_j, t_k)}{H} \right)^2 < \gamma$$

$$\sqrt{w_1^2(x_i, y_j, t_k) + w_2^2(x_i, y_j, t_k)} =$$

$$w_1(x_i, y_j, t_k) \sqrt{1 + \frac{H^2(P^2(x_{i+1}, y_j, t_k) - 2P(x_{i+1}, y_j, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}{h^2(P^2(x_i, y_{j+1}, t_k) - 2P(x_i, y_{j+1}, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}}$$

$$w_1(x_i, y_j, t_k) = \frac{k * k_2(s_2, T, C)}{h * \mu_2} * (P(x_i, y_j, t_k) - P(x_{i+1}, y_j, t_k) -$$

$$\begin{aligned}
& - \frac{h * \gamma}{\sqrt{1 + \frac{H^2(P^2(x_{i+1}, y_j, t_k) - 2P(x_{i+1}, y_j, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}{h^2(P^2(x_i, y_{j+1}, t_k) - 2P(x_i, y_{j+1}, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}}} \\
w_2(x_i, y_j, t_k) \\
= & \frac{P(x_i, y_{j+1}, t_k) - P(x_i, y_j, t_k)}{H * (\frac{\mu_2}{k * k_2(s_2, T, C)} + \frac{\gamma}{\sqrt{1 + \frac{H^2(P^2(x_{i+1}, y_j, t_k) - 2P(x_{i+1}, y_j, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}{h^2(P^2(x_i, y_{j+1}, t_k) - 2P(x_i, y_{j+1}, t_k)P(x_i, y_j, t_k) + P^2(x_i, y_j, t_k))}}})}
\end{aligned}$$