

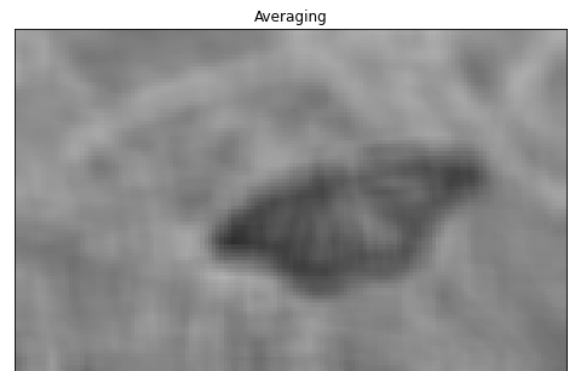
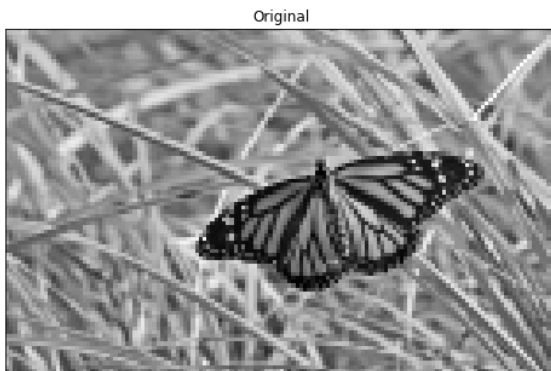
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Index No -190095C

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In [ ]: # Averaging using Box filter
%matplotlib inline
import cv2 as cv
import matplotlib.pyplot as plt
import numpy as np

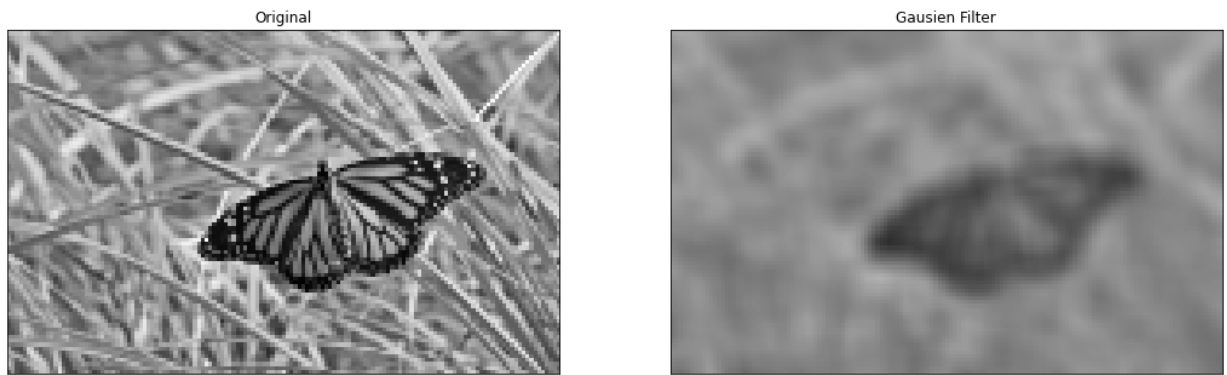
img = cv.imread(r"C:\Users\Sureka\Desktop\Lectures\Img_P\Ex2\butterfly.jpg", cv.IMREAD_GRAYSCALE)
assert img is not None
kernel_Box = np.ones((9,9),np.float32)/81
imgc = cv.filter2D(img,-1, kernel_Box)

fig,ax= plt.subplots(1,2, sharex='all', sharey='all', figsize=(18,18))
ax[0].imshow(img,cmap='gray')
ax[0].set_title('Original')
ax[0].set_xticks([]), ax[0].set_yticks([])
ax[1].imshow(imgc,cmap='gray',vmin=0, vmax=255)
ax[1].set_title('Averaging')
ax[1].set_xticks([]), ax[1].set_yticks([])
plt.show()
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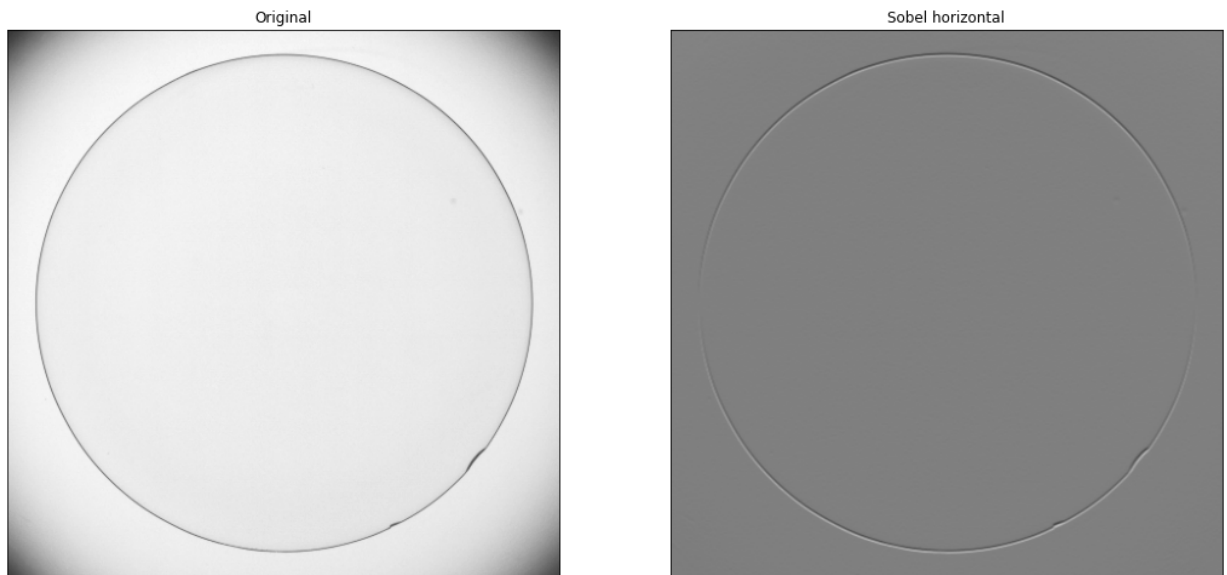
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In [ ]: #Averaging using Gaussian filter
sigma = 4
kernel= cv.getGaussianKernel(9,sigma)
blurred = cv.sepFilter2D(img, -1,kernel,kernel,anchor=(-1,-1),delta=0,borderType=cv.BORDER_REPLICATE)

fig,ax= plt.subplots(1,2, sharex='all', sharey='all', figsize=(18,18))
ax[0].imshow(img,cmap='gray')
ax[0].set_title('Original')
ax[0].set_xticks([]), ax[0].set_yticks([])
ax[1].imshow(blurred,cmap='gray',vmin=0, vmax=255)
ax[1].set_title('Gaussian Filter')
ax[1].set_xticks([]), ax[1].set_yticks([])
plt.show()
```



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In [ ]: #Sobel Horizontal
img = cv.imread(r"C:\Users\Sureka\Desktop\Lectures\Img_P\Ex2\contact_lens.tif", cv.IMF
assert img is not None
kernel_hori = np.array([[-1,-2,-1),(0,0,0),(1,2,1]], dtype='float')
img_h = cv.filter2D(img,-1, kernel_hori)

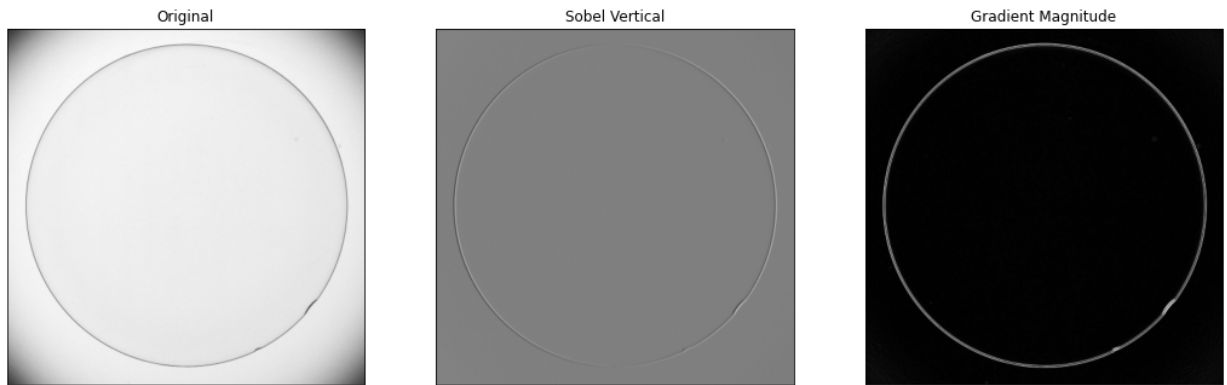
fig,ax= plt.subplots(1,2, sharex='all', sharey='all', figsize=(18,18))
ax[0].imshow(img,cmap='gray',vmin=0, vmax=255)
ax[0].set_title('Original')
ax[0].set_xticks([]), ax[0].set_yticks([])
ax[1].imshow(img_h,cmap='gray',vmin=-1020,vmax=1020)
ax[1].set_title('Sobel horizontal')
ax[1].set_xticks([]), ax[1].set_yticks([])
plt.show()
```



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In [ ]: #Sobel Vertical and Gradient Magnitude
kernel_ver = np.array([[-1,0,1),(-2,0,2),(-1,0,1)], dtype='float')
img_v = cv.filter2D(img,-1, kernel_ver)
grad_mag = np.sqrt(img_v**2 + img_h**2)

fig,ax= plt.subplots(1,3, sharex='all', sharey='all', figsize=(18,18))
ax[0].imshow(img,cmap='gray',vmin=0, vmax=255)
ax[0].set_title('Original')
ax[0].set_xticks([]), ax[0].set_yticks([])
ax[1].imshow(img_v,cmap='gray',vmin=-1020,vmax=1020)
ax[1].set_title('Sobel Vertical')
ax[1].set_xticks([]), ax[1].set_yticks([])
ax[2].imshow(grad_mag,cmap='gray')
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ax[2].set_title('Gradient Magnitude')
ax[2].set_xticks([]), ax[2].set_yticks([])
plt.show()
```



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In [ ]: # surface plot of Gaussian Kernel
from matplotlib import cm
from mpl_toolkits.mplot3d import Axes3D
from matplotlib.ticker import LinearLocator, FormatStrFormatter
fig = plt.figure(figsize=(10,10))
ax = fig.add_subplot(111, projection='3d')

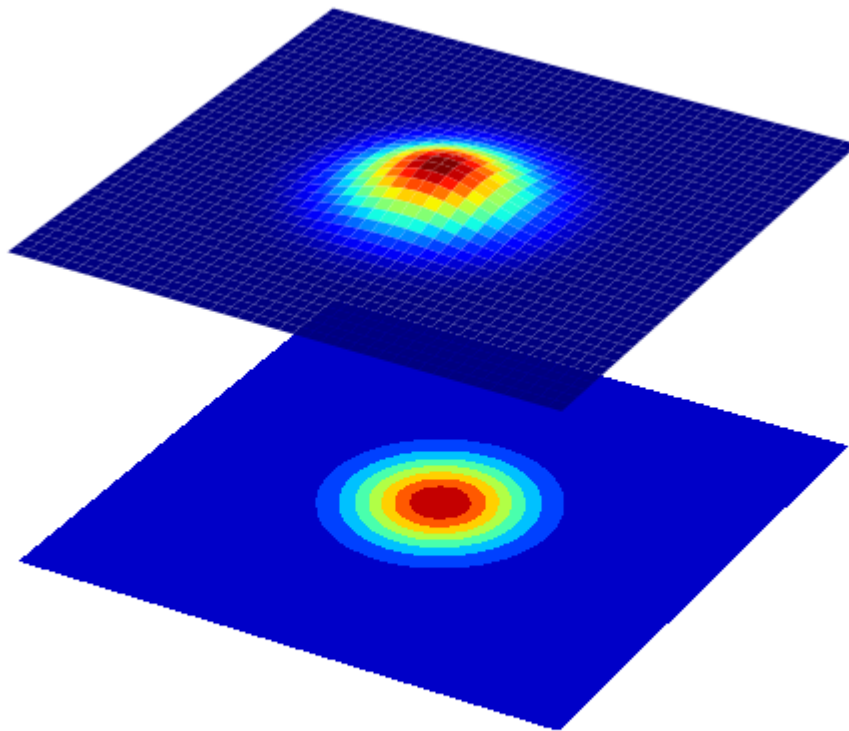
x = np.arange(-5,5.25,0.25)
y = np.arange(-5,5.25,0.25)
X,Y = np.meshgrid(x,y)

sigma = 1
Z = np.exp(-(X**2+Y**2)/(2*sigma**2))/(2*np.pi*sigma**2)

surf=ax.plot_surface(X,Y,Z, cmap = cm.jet, linewidth=0,antialiased=True)
ax.zaxis.set_major_locator(LinearLocator(10))
ax.zaxis.set_major_formatter(FormatStrFormatter('%0.1f'))

cset = ax.contourf(X,Y,Z,zdir='z',offset=np.min(Z)-1.5, cmap=cm.jet)
ax.set_zlim(np.min(Z)-2, np.max(Z))

plt.axis('off')
plt.show()
```



```
In [ ]: img = cv.imread(r"C:\Users\Sureka\Desktop\Lectures\Img_P\Ex2\tom.jpg", cv.IMREAD_REDUCED_COLOR_8)
assert img is not None

sigma = 2
gaussian_1d = cv.getGaussianKernel(5, sigma)
f_lp = cv.sepFilter2D(img, -1, gaussian_1d, gaussian_1d)
f_hp = img - f_lp
f_sharpened = cv.addWeighted(img, 3.0, f_hp, 2.0, 1)

fig, ax = plt.subplots(1, 4, sharex='all', sharey='all', figsize=(18, 18))
ax[0].imshow(img, cmap='gray', vmin=0, vmax=255)
ax[0].set_title('Original')
ax[0].set_xticks([]), ax[0].set_yticks([])
ax[1].imshow(f_lp, cmap='gray')
ax[1].set_title('Low pass filter')
ax[1].set_xticks([]), ax[1].set_yticks([])
ax[2].imshow(f_hp, cmap='gray')
ax[2].set_title('highpass filter')
ax[2].set_xticks([]), ax[2].set_yticks([])
ax[3].imshow(f_sharpened, cmap='gray')
ax[3].set_title('sharpened')
```

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ax[3].set_xticks([]), ax[3].set_yticks([])  
plt.show()
```

Original



Low pass filter



highpass filter



sharpened

