

第8讲: 可微条件与高阶偏导数

(一) $z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处可微的条件:

Th1: 若 $z = f(x, y)$ 在 M_0 处可微, 则 $f'_x(M_0), f'_y(M_0)$ 必存在, 反之未必。

Th2: 若 $f(x, y)$ 在 M_0 处可微, 则 $z = f(x, y)$ 在 M_0 处必连续, 反之未必。

Th3: $z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处可微的充分条件:

$$\lim_{\rho \rightarrow 0} \frac{\Delta z - (f'_x(M_0)\Delta x + f'_y(M_0)\Delta y)}{\rho} = 0.$$

Th4: $z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处可微的充分条件:

$f'_x(x, y), f'_y(x, y)$ 在 $M_0(x_0, y_0)$ 处存在且连续。

证 Th1: 已知 $z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处可微 $\Rightarrow \Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0)$

$$= (A\Delta x + B\Delta y) + o(\rho), \text{ 令 } \Delta y = 0, \text{ 则 } \Delta z_x = f(x_0 + \Delta x, y_0) - f(x_0, y_0) =$$

$$A\Delta x + o(|\Delta x|) \Rightarrow f'_x(M_0) = \lim_{\Delta x \rightarrow 0} \frac{\Delta z_x}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{A\Delta x + o(|\Delta x|)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} (A + \frac{o(|\Delta x|)}{|\Delta x|}) = A + 0 = A, \text{ 同理 } f'_y(M_0) = B.$$

$$\text{即 } dz|_{M_0} = A\Delta x + B\Delta y = f'_x(M_0)\Delta x + f'_y(M_0)\Delta y \Rightarrow dz = f'_x\Delta x + f'_y\Delta y$$

$$= \frac{\partial z}{\partial x}\Delta x + \frac{\partial z}{\partial y}\Delta y = \frac{\partial z}{\partial x}dx + \frac{\partial z}{\partial y}dy = \left(\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}\right) \begin{pmatrix} dx \\ dy \end{pmatrix} \quad (1).$$

证法2: 已知 $\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0) = f'_x(M_0)\Delta x + f'_y(M_0)\Delta y + o(\rho)$

且 $\begin{cases} \Delta x \rightarrow 0 \\ \Delta y \rightarrow 0 \end{cases}$ 时, $\begin{cases} f'_x(M_0)\Delta x + f'_y(M_0)\Delta y \rightarrow 0 \\ o(\rho) \rightarrow 0 \end{cases}$ ($\rho = \sqrt{(\Delta x)^2 + (\Delta y)^2} \rightarrow 0$ 时), 从而

$\lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} \Delta z = 0 \Leftrightarrow z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处连续.

反例1: $z = f(x, y) = \sqrt{x^2 + y^2}$ 在 $O(0, 0)$ 处连续, 但因 $f'_x(0, 0), f'_y(0, 0)$

都不存在, 证法1, $f(x, y) = \sqrt{x^2 + y^2}$ 在 $O(0, 0)$ 处不可微.

反例2: $z = f(x, y) = \begin{cases} \frac{x^2 y}{x^2 + y^2}, & x^2 + y^2 > 0 \\ 0, & x^2 + y^2 = 0 \end{cases}$ 在 $O(0, 0)$ 处有

$f'_x(0, 0) = 0 = f'_y(0, 0)$, 但因 $\lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} f(x, y) \neq f(0, 0) = 0$. 因此,

$f(x, y)$ 在 $O(0, 0)$ 处不连续, 证法2, $f(x, y)$ 在 $O(0, 0)$ 处不可微.

证法3: 若 $z = f(x, y)$ 在 $M_0(x_0, y_0)$ 处可微, 则

$$\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0) = f'_x(M_0)\Delta x + f'_y(M_0)\Delta y + o(\rho), \Rightarrow$$

$$\lim_{\rho \rightarrow 0} \frac{\Delta z - (f'_x(M_0)\Delta x + f'_y(M_0)\Delta y)}{\rho} = \lim_{\rho \rightarrow 0} \frac{o(\rho)}{\rho} = 0$$

反之, 若 $\lim_{\rho \rightarrow 0} \frac{\Delta z - (f'_x(M_0)\Delta x + f'_y(M_0)\Delta y)}{\rho} = 0$ 则

$$\Delta z - (f'_x(M_0)\Delta x + f'_y(M_0)\Delta y) = o(\rho) \Rightarrow \Delta z = f'_x(M_0)\Delta x + f'_y(M_0)\Delta y + o(\rho) \quad (2).$$

$= (Ax + By) + o(\rho)$. 从而 $z = f(x, y)$ 在 M_0 处可微.

证法: 已知 $f'_x(x, y), f'_y(x, y)$ 在 $M_0(x_0, y_0)$ 处存在且连续.

从而 $\Delta z = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0) = [f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0 + \Delta y)] +$

$[f(x_0, y_0 + \Delta y) - f(x_0, y_0)] \xrightarrow[\text{中值定理}]{\text{Lagrange 公式}} f'_x(x_0 + \theta_1 \Delta x, y_0 + \Delta y) \Delta x +$

$f'_y(x_0, y_0 + \theta_2 \Delta y) \Delta y$, 其中 $\theta_1, \theta_2 \in (0, 1)$. 利用 $f'_x(x, y), f'_y(x, y)$ 在

$M_0(x_0, y_0)$ 处连续可知: $\begin{cases} \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} f'_x(x_0 + \theta_1 \Delta x, y_0 + \Delta y) = f'_x(x_0, y_0) \\ \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} f'_y(x_0, y_0 + \theta_2 \Delta y) = f'_y(x_0, y_0) \end{cases}$

从而 $\begin{cases} f'_x(x_0 + \theta_1 \Delta x, y_0 + \Delta y) = f'_x(x_0, y_0) + \alpha_1, \alpha_1 \rightarrow 0 \text{ (} \Delta x \rightarrow 0, \Delta y \rightarrow 0 \text{)} \\ f'_y(x_0, y_0 + \theta_2 \Delta y) = f'_y(x_0, y_0) + \alpha_2, \alpha_2 \rightarrow 0 \text{ (} \Delta x \rightarrow 0, \Delta y \rightarrow 0 \text{)}. \end{cases}$

即 $\Delta z = (f'_x(M_0) + \alpha_1) \Delta x + (f'_y(M_0) + \alpha_2) \Delta y = f'_x(M_0) \Delta x + f'_y(M_0) \Delta y + \alpha_1 \Delta x + \alpha_2 \Delta y$

且 $\lim_{\rho \rightarrow 0} \frac{\alpha_1 \Delta x + \alpha_2 \Delta y}{\rho} = \lim_{\rho \rightarrow 0} (\alpha_1 \cos \theta + \alpha_2 \sin \theta) = 0 + 0 = 0$

$\therefore \alpha_1 \Delta x + \alpha_2 \Delta y = o(\rho)$. 故有:

$\Delta z = f'_x(M_0) \Delta x + f'_y(M_0) \Delta y + o(\rho) = (Ax + By) + o(\rho)$. 即

$z = f(x, y)$ 在 M_0 处可微.

例3. $z = f(x, y) = \begin{cases} (x^2 + y^2) \sin \frac{1}{\sqrt{x^2 + y^2}}, & x^2 + y^2 > 0, \\ 0, & x^2 + y^2 = 0, \end{cases}$

在 $O(0,0)$ 处可微. 且 $f'_x(x, y), f'_y(x, y)$ 在 $O(0,0)$ 处不连续.

(二) 高阶偏导数 (higher order partial derivative)

设 $z = f(x, y) = x^2 + xy + y^2 + x^y + 3x + 4y, (x > 0, y \in \mathbb{R}).$

则 $\begin{cases} \frac{\partial z}{\partial x} = 2x + y + yx^{y-1} + 3 \\ \frac{\partial z}{\partial y} = x + 2y + x^y \ln x + 4. \end{cases} \Rightarrow$

$\frac{\partial^2 z}{\partial y \partial x} = \left(\frac{\partial z}{\partial x} \right)'_y = (2x + y + yx^{y-1} + 3)'_y = 0 + 1 + 1 \cdot x^{y-1} + yx^{y-1} \ln x + 0$

$\frac{\partial^2 z}{\partial x \partial y} = \left(\frac{\partial z}{\partial y} \right)'_x = (x + 2y + x^y \ln x + 4)'_x = 1 + 0 + yx^{y-1} \ln x + x^{y-1} + 0$

$\frac{\partial^3 z}{\partial x \partial y \partial x} = \left(\frac{\partial^2 z}{\partial y \partial x} \right)'_x = (1 + x^{y-1} + yx^{y-1} \ln x)'_x = (y-1)x^{y-2} + y(y-1)x^{y-2} \ln x + yx^{y-2}$

$\frac{\partial^3 z}{\partial x^2 \partial y} = \left(\frac{\partial^2 z}{\partial x \partial y} \right)'_x = (1 + yx^{y-1} \ln x + x^{y-1})'_x = y(y-1)x^{y-2} \ln x + yx^{y-2} + (y-1)x^{y-2}$

显然, $\frac{\partial^2 z}{\partial y \partial x}, \frac{\partial^2 z}{\partial x \partial y}, \frac{\partial^3 z}{\partial x \partial y \partial x}, \frac{\partial^3 z}{\partial x^2 \partial y}$ 在区域 $D: x > 0$ 中

连续且 $\frac{\partial^2 z}{\partial y \partial x} = \frac{\partial^2 z}{\partial x \partial y}, \frac{\partial^3 z}{\partial x \partial y \partial x} = \frac{\partial^3 z}{\partial x^2 \partial y}, \forall (x, y) \in D.$

Th5: 若 $z = f(x, y)$ 在区域 D 中的高阶偏导数连续, 则

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高阶偏导数与求偏导的顺序无关。

证：设 $f(x,y) \in C^2(D)$ ，且 $M_0(x_0, y_0)$ 为 D 中任一点，设

$M_1(x_0+h, y_0+k)$, $M_2(x_0+h, y_0)$, $M_3(x_0, y_0+k) \in D$, $h, k \neq 0$.

则必有： $f'_{xy}(M_0) = f'_{yx}(M_0)$ ，再由 M_0 在 D 中任意性，

即可得： $f''_{xy}(x,y) = f''_{yx}(x,y)$ 或 $\frac{\partial^2 z}{\partial y \partial x} = \frac{\partial^2 z}{\partial x \partial y}$, $\forall (x,y) \in D$.

$$\begin{cases} m(x) = f(x, y_0+k) - f(x, y_0) \\ n(y) = f(x_0+h, y) - f(x_0, y) \end{cases} \quad \text{则有}$$

$$\begin{cases} m(x_0+h) - m(x_0) = f(x_0+h, y_0+k) - f(x_0+h, y_0) - f(x_0, y_0+k) + f(x_0, y_0) \\ n(y_0+k) - n(y_0) = f(x_0+h, y_0+k) - f(x_0, y_0+k) - f(x_0+h, y_0) + f(x_0, y_0) \end{cases}$$

即对 $\forall h, k \neq 0$ ，有 $m(x_0+h) - m(x_0) = n(y_0+k) - n(y_0)$ 。利用

Lagrange 中值定理知： $m'(x_0+\theta_1 h)h = n'(y_0+\theta_2 k)k$

且 $\theta_1, \theta_2 \in (0,1)$ 。即有：

$$(f'_x(x_0+\theta_1 h, y_0+k) - f'_x(x_0+\theta_1 h, y_0))h = (f'_y(x_0+h, y_0+\theta_2 k) - f'_y(x_0, y_0+\theta_2 k))k$$

对 f'_x, f'_y 这两组函数再次使用 Lagrange 中值定理：

$$f''_{xy}(x_0+\theta_1 h, y_0+\theta_2 k)hk = f''_{yx}(x_0+\theta_4 h, y_0+\theta_2 k)hk, \theta_3, \theta_4 \in (0,1).$$

(5).

" $f \in C^2(D)$. \therefore 在式中含 $h \rightarrow 0, k \rightarrow 0$, 则有

$f''_{xy}(x_0, y_0) = f''_{yx}(x_0, y_0)$. 由 $M(x_0, y_0)$ 在 D 中的任意性:

即有 $f''_{xy}(x, y) = f''_{yx}(x, y) \Leftrightarrow \frac{\partial^2 z}{\partial y \partial x} = \frac{\partial^2 z}{\partial x \partial y}, \forall (x, y) \in D$.

同理可证, 若 $z = f(x, y) \in C^3(D)$, 则必有

$$\frac{\partial^3 z}{\partial x^2 \partial y} = \frac{\partial^3 z}{\partial x \partial y \partial x} = \frac{\partial^3 z}{\partial y \partial x^2}, \text{ 证法同上.}$$

(E) 例题:

例1. 证明函数 $u = \frac{1}{r}, r = \sqrt{x^2 + y^2 + z^2} > 0$ 满足 Laplace

方程 (即调和方程): $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0, \forall (x, y, z) \neq (0, 0, 0)$.

例2. 证明 $u = \frac{1}{2a\sqrt{\pi t}} e^{-\frac{x^2}{4at}}, (x > 0, t > 0, a > 0 \text{ 常数})$

满足热传导方程: $\frac{\partial u}{\partial t} = a^2 \frac{\partial^2 u}{\partial x^2}$.

例3. 对 $\forall \varphi, \psi \in C^2(I)$, $u = \varphi(x-at) + \psi(x+at)$ 满足

波动方程: $\frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} \quad (a > 0, \text{常数}), t > 0, x \in (-\infty, +\infty)$.

证例1: $u = (x^2 + y^2 + z^2)^{-\frac{1}{2}} \Rightarrow \frac{\partial u}{\partial x} = -\frac{1}{2}(x^2 + y^2 + z^2)^{-\frac{3}{2}} \cdot 2x$

(6).

$$\Rightarrow \frac{\partial u}{\partial x} = -x(x^2+y^2+z^2)^{-\frac{3}{2}} \Rightarrow$$

$$\frac{\partial^2 u}{\partial x^2} = -1(x^2+y^2+z^2)^{-\frac{3}{2}} + (-x)\left(-\frac{3}{2}\right)(x^2+y^2+z^2)^{-\frac{5}{2}} \cdot 2x$$

$$= -(x^2+y^2+z^2)^{-\frac{5}{2}}(x^2+y^2+z^2) + 3x^2(x^2+y^2+z^2)^{-\frac{5}{2}} = -\frac{(x^2+y^2+z^2) - 3x^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}$$

因为 $u = (x^2+y^2+z^2)^{-\frac{1}{2}}$ 是 x, y, z 的对称函数, 因此, 有:

$$\frac{\partial^2 u}{\partial y^2} = -\frac{(x^2+y^2+z^2) - 3y^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}, \quad \frac{\partial^2 u}{\partial z^2} = -\frac{(x^2+y^2+z^2) - 3z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}$$

$$\text{故 } \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = -\frac{3(x^2+y^2+z^2) - 3(x^2+y^2+z^2)}{(x^2+y^2+z^2)^{\frac{5}{2}}} = 0, \quad \forall (x, y, z) \neq (0, 0, 0)$$

$$\text{证例2: } \because \frac{\partial u}{\partial t} = \frac{(t^{-\frac{1}{2}})'}{2a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} + \frac{1}{2a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(-\frac{x^2}{4a^2t}\right)' t$$

$$= \frac{1}{4a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(-1 + \frac{x^2}{2a^2t}\right), \text{ 且}$$

$$\frac{\partial u}{\partial x} = \frac{1}{2a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(-\frac{x^2}{4a^2t}\right)' x = \frac{1}{2a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(-\frac{x}{2a^2t}\right) \Rightarrow$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{2a\sqrt{t}} \left[e^{-\frac{x^2}{4a^2t}} \left(-\frac{x}{2a^2t}\right)' + e^{-\frac{x^2}{4a^2t}} \left(-\frac{1}{2a^2t}\right) \right]$$

$$= \frac{1}{4a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(\frac{x^2}{2a^4t} - \frac{1}{a^2t} \right) \Rightarrow$$

$$a^2 \frac{\partial^2 u}{\partial x^2} = \frac{1}{4a\sqrt{t}} e^{-\frac{x^2}{4a^2t}} \left(\frac{x^2}{2a^2t} - 1 \right) = \frac{\partial u}{\partial t}, \quad \forall t > 0, x \in \mathbb{R}^+$$

$$\text{证例3: 令 } \begin{cases} v = xat \\ w = x^2at \end{cases}, \text{ 则 } u = g(v) + \psi(w)$$

(1).

$$\Rightarrow \frac{\partial u}{\partial x} = g'(v) \frac{\partial v}{\partial x} + \varphi'(w) \frac{\partial w}{\partial x} = g'(v) \cdot 1 + \varphi'(w) \cdot 1 \Rightarrow$$

$$\frac{\partial u}{\partial x^2} = g''(v) \frac{\partial v}{\partial x} + \varphi''(w) \frac{\partial w}{\partial x} = g''(v) \cdot 1 + \varphi''(w) \cdot 1 \quad \text{且}$$

$$\frac{\partial u}{\partial t} = g'(v) \frac{\partial v}{\partial t} + \varphi'(w) \frac{\partial w}{\partial t} = g'(v)(-a) + \varphi'(w)a \Rightarrow$$

$$\frac{\partial^2 u}{\partial t^2} = g''(v) \frac{\partial v}{\partial t}(-a) + \varphi''(w) \frac{\partial w}{\partial t}(a) = g''(v)(-a)^2 + \varphi''(w)a^2$$

$$= a^2(g''(v) + \varphi''(w)) = a^2 \frac{\partial^2 u}{\partial x^2}, \quad \forall t > 0, x \in \mathbb{R}.$$

四) 例: ex 9, 2

2/11; 8; 11; 15; 26; 27; 28.

附微分向量算子: $\nabla = (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z})$, $u = f(x, y, z) \in C^2(D)$,

$\vec{A}(x, y, z) = (P(x, y, z), Q(x, y, z), R(x, y, z)) \in C^2(D)$. 则

1). $\nabla u = (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z})u = (\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z})$ 为 $u = f(x, y, z)$ 的梯度;

2). $\nabla \cdot \vec{A} = (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}) \cdot (P, Q, R) = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$ 为 $\vec{A}(x, y, z)$ 的散度

3). $\nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} = (\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z})\hat{i} + (\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x})\hat{j} + (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y})\hat{k}$

是 \vec{A} 的旋度。

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