# Optimisation

ACTL3143 & ACTL5111 Deep Learning for Actuaries
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### **Lecture Outline**

- Dense Layers in Matrices
- Optimisation
- Loss and derivatives







# Logistic regression

Observations:  $\mathbf{x}_{i,\bullet} \in \mathbb{R}^2$ .

Target:  $y_i \in \{0, 1\}$ .

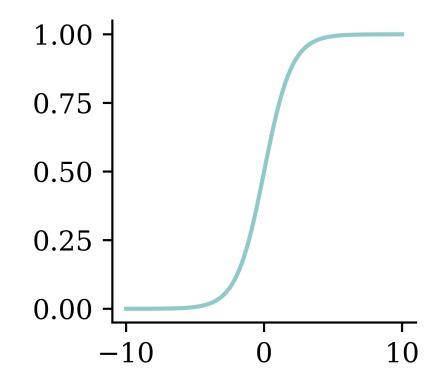
Predict:  $\hat{y}_i = \mathbb{P}(Y_i = 1)$ .

#### The model

For 
$$\mathbf{x}_{i,\bullet} = (x_{i,1}, x_{i,2})$$
:

$$z_i = x_{i,1}w_1 + x_{i,2}w_2 + b$$

$$\hat{y}_i = \sigma(z_i) = rac{1}{1+\mathrm{e}^{-z_i}}.$$







### Multiple observations

```
1 data = pd.DataFrame({"x_1": [1, 3, 5], "x_2": [2, 4, 6], "y": [0, 1, 1]})
2 data
```

Let  $w_1 = 1$ ,  $w_2 = 2$  and b = -10.

```
1 w_1 = 1; w_2 = 2; b = -10
2 data["x_1"] * w_1 + data["x_2"] * w_2 + b
```

```
0 -5
1 1
2 7
dtype: int64
```





### Matrix notation

Have  $\mathbf{X} \in \mathbb{R}^{3 \times 2}$ .

```
Let \mathbf{w} = (w_1, w_2)^{\top} \in \mathbb{R}^{2 \times 1}.
```

```
1 w = np.array([[1], [2]])
2 w
```

array([[1], [2]])

$$\mathbf{z} = \mathbf{X}\mathbf{w} + b, \quad \mathbf{a} = \sigma(\mathbf{z})$$

```
1 z = X.dot(w) + b
2 z

array([[-5],
       [ 1],
       [ 7]])
```





# Using a softmax output

Observations:  $\mathbf{x}_{i,\bullet} \in \mathbb{R}^2$ . Predict: Target:  $\mathbf{y}_{i,\bullet} \in \{(1,0),(0,1)\}$ .  $\hat{y}_{i,j} = \mathbb{P}(Y_i = j)$ .

The model: For  $\mathbf{x}_{i,\bullet} = (x_{i,1}, x_{i,2})$ 

$$egin{aligned} z_{i,1} &= x_{i,1}w_{1,1} + x_{i,2}w_{2,1} + b_1, \ z_{i,2} &= x_{i,1}w_{1,2} + x_{i,2}w_{2,2} + b_2. \end{aligned}$$

$$\hat{y}_{i,1} = ext{Softmax}_1(\mathbf{z}_i) = rac{\mathrm{e}^{z_{i,1}}}{\mathrm{e}^{z_{i,1}} + \mathrm{e}^{z_{i,2}}}, \ \hat{y}_{i,2} = ext{Softmax}_2(\mathbf{z}_i) = rac{\mathrm{e}^{z_{i,1}} + \mathrm{e}^{z_{i,2}}}{\mathrm{e}^{z_{i,1}} + \mathrm{e}^{z_{i,2}}}.$$





# Multiple observations

1 data

	X_1	X_2	<b>y_1</b>	<b>y_2</b>
О	1	2	1	O
1	3	4	O	1
2	5	6	O	1

#### Choose:

$$w_{1,1}=1,\,w_{2,1}=2,$$
  $w_{1,2}=3,\,w_{2,2}=4,\, ext{and}$ 

$$b_1 = -10, b_2 = -20.$$

```
1  w_11 = 1; w_21 = 2; b_1 = -10
2  w_12 = 3; w_22 = 4; b_2 = -20
3  data["x_1"] * w_11 + data["x_2"] * w_21 + b_1
```

```
0 -5
1 1
2 7
dtype: int64
```





#### Matrix notation

Have  $\mathbf{X} \in \mathbb{R}^{3 \times 2}$ .

```
1 X
array([[1, 2],
       [3, 4],
       [5, 6]])
```

$$\mathbf{Z} = \mathbf{XW} + \mathbf{b},$$

 $1 Z = X \odot W + b$ 

[ 7, 19]])

$$\mathbf{W} \in \mathbb{R}^{2 \times 2}, \, \mathbf{b} \in \mathbb{R}^2$$

```
1 W = np.array([[1, 3], [2, 4]])
  2 b = np.array([-10, -20])
  3 display(W); b
array([[1, 3],
      [2, 4]])
array([-10, -20])
```

$$\mathbf{Z} = \mathbf{XW} + \mathbf{b}, \quad \mathbf{A} = \operatorname{Softmax}(\mathbf{Z}).$$

```
1 np.exp(Z) / np.sum(np.exp(Z),
       axis=1, keepdims=True)
array([[9.82e-01, 1.80e-02],
       [1.80e-02, 9.82e-01],
```

[6.14e-06, 1.00e+00]])





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# Gradient-based learning

Make a guess: ——— 50

Show derivatives: 

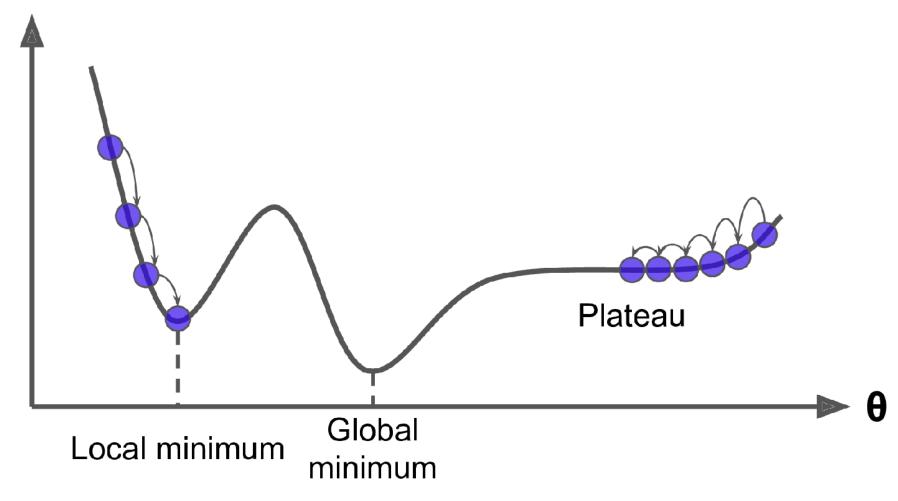
Reveal function:





# Gradient descent pitfalls

#### Cost



Potential problems with gradient descent.





# Go over all the training data

Called batch gradient descent.

```
for i in range(num_epochs):
    gradient = evaluate_gradient(loss_function, data, weights)
    weights = weights - learning_rate * gradient
```





# Pick a random training example

Called stochastic gradient descent.

```
for i in range(num_epochs):
    rnd.shuffle(data)

for example in data:
    gradient = evaluate_gradient(loss_function, example, weights)
    weights = weights - learning_rate * gradient
```





### Take a group of training examples

Called mini-batch gradient descent.

```
for i in range(num_epochs):
    rnd.shuffle(data)

for b in range(num_batches):
    batch = data[b * batch_size : (b + 1) * batch_size]
    gradient = evaluate_gradient(loss_function, batch, weights)
    weights = weights - learning_rate * gradient
```

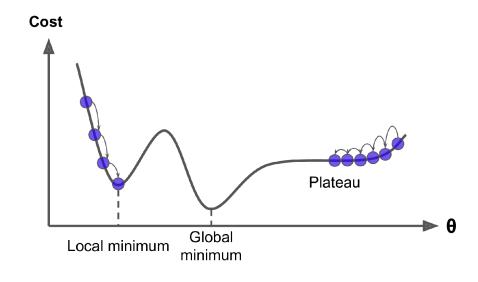




### Mini-batch gradient descent

#### Why?

- 1. Because we have to (data is too big)
- 2. Because it is faster (lots of quick noisy steps > a few slow super accurate steps)
- 3. The noise helps us jump out of local minima

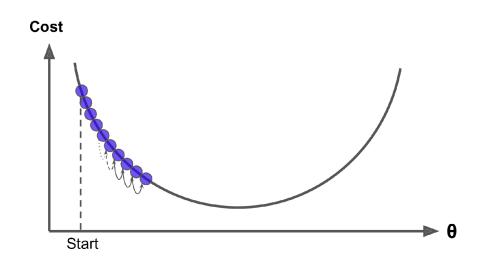


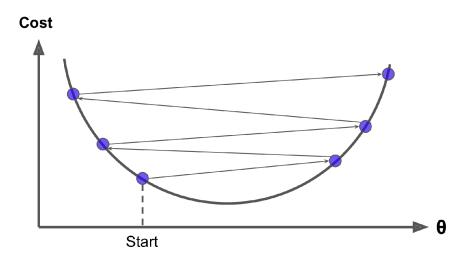
Example of jumping from local minima.





# Learning rates





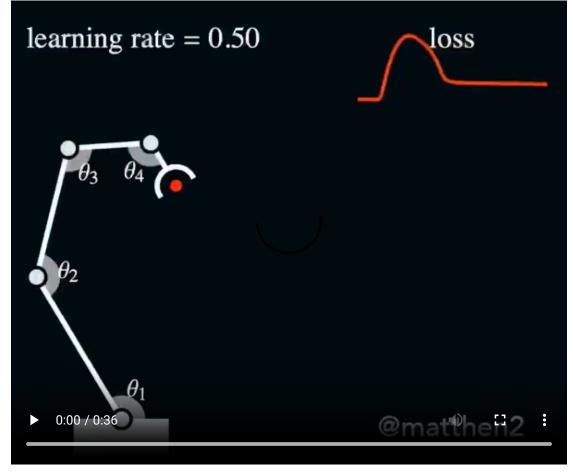
The learning rate is too small

The learning rate is too large





# Learning rates #2

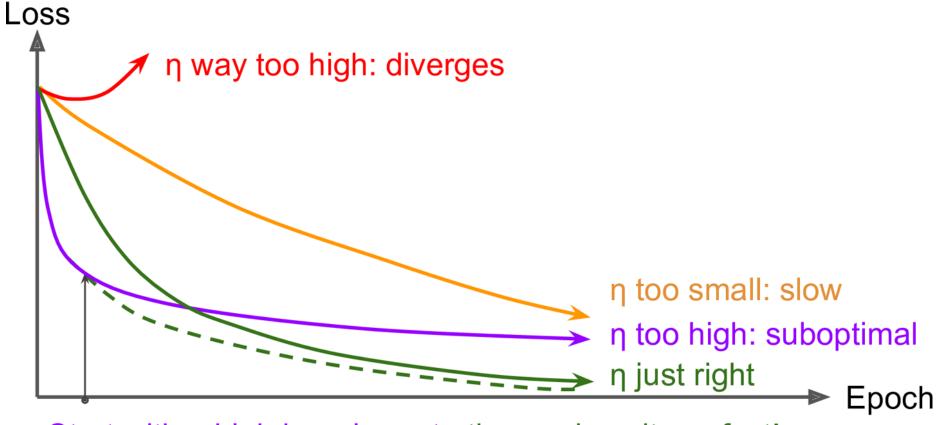


Changing the learning rates for a robot arm.





# Learning rate schedule



Start with a high learning rate then reduce it: perfect!

Learning curves for various learning rates η

In training the learning rate may be tweaked manually.





# We need non-zero derivatives

This is why can't use accuracy as the loss function for classification.

Also why we can have the *dead ReLU* problem.

Neu	al Networks Part 5: ArgMax and SoftMax







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### Example: linear regression

$$\hat{y}(x) = wx + b$$

For some observation  $\{x_i, y_i\}$ , the (MSE) loss is

$$\mathrm{Loss}_i = (\hat{y}(x_i) - y_i)^2$$

For a batch of the first *n* observations the loss is

$$ext{Loss}_{1:n} = rac{1}{n} \sum_{i=1}^n (\hat{y}(x_i) - y_i)^2$$





### Derivatives

Since  $\hat{y}(x) = wx + b$ ,

$$rac{\partial \hat{y}(x)}{\partial w} = x ext{ and } rac{\partial \hat{y}(x)}{\partial b} = 1.$$

As  $\operatorname{Loss}_i = (\hat{y}(x_i) - y_i)^2$ , we know

$$rac{\partial \mathrm{Loss}_i}{\partial \hat{y}(x_i)} = 2(\hat{y}(x_i) - y_i).$$





### Chain rule

$$rac{\partial \mathrm{Loss}_i}{\partial \hat{y}(x_i)} = 2(\hat{y}(x_i) - y_i), \ rac{\partial \hat{y}(x)}{\partial w} = x, \ ext{and} \ rac{\partial \hat{y}(x)}{\partial b} = 1.$$

Putting this together, we have

$$rac{\partial \mathrm{Loss}_i}{\partial w} = rac{\partial \mathrm{Loss}_i}{\partial \hat{y}(x_i)} imes rac{\partial \hat{y}(x_i)}{\partial w} = 2(\hat{y}(x_i) - y_i)\,x_i$$

and

$$rac{\partial \mathrm{Loss}_i}{\partial b} = rac{\partial \mathrm{Loss}_i}{\partial \hat{y}(x_i)} imes rac{\partial \hat{y}(x_i)}{\partial b} = 2(\hat{y}(x_i) - y_i).$$





# Stochastic gradient descent (SGD)

Start with  $\theta_0 = (w, b)^{\top} = (0, 0)^{\top}$ .

Randomly pick i = 5, say  $x_i = 5$  and  $y_i = 5$ .





### SGD, first iteration

Start with  $\theta_0 = (w, b)^{\top} = (0, 0)^{\top}$ .

Randomly pick i = 5, say  $x_i = 5$  and  $y_i = 5$ .

The gradient is  $\nabla \text{Loss}_i = (-50, -10)^{\top}$ .

Use learning rate  $\eta = 0.01$  to update

$$egin{aligned} oldsymbol{ heta}_1 &= oldsymbol{ heta}_0 - \eta 
abla \mathrm{Loss}_i \ &= egin{pmatrix} 0 \ 0 \end{pmatrix} - 0.01 egin{pmatrix} -50 \ -10 \end{pmatrix} \ &= egin{pmatrix} 0 \ 0 \end{pmatrix} + egin{pmatrix} 0.5 \ 0.1 \end{pmatrix} = egin{pmatrix} 0.5 \ 0.1 \end{pmatrix}. \end{aligned}$$





### SGD, second iteration

Start with  $\theta_1 = (w, b)^{\top} = (0.5, 0.1)^{\top}$ .

Randomly pick i = 9, say  $x_i = 9$  and  $y_i = 17$ .

The gradient is  $\nabla \text{Loss}_i = (-223.2, -24.8)^{\top}$ .

Use learning rate  $\eta = 0.01$  to update

$$egin{aligned} m{ heta}_2 &= m{ heta}_1 - \eta 
abla \mathrm{Loss}_i \ &= egin{pmatrix} 0.5 \ 0.1 \end{pmatrix} - 0.01 egin{pmatrix} -223.2 \ -24.8 \end{pmatrix} \ &= egin{pmatrix} 0.5 \ 0.1 \end{pmatrix} + egin{pmatrix} 2.232 \ 0.248 \end{pmatrix} = egin{pmatrix} 2.732 \ 0.348 \end{pmatrix}. \end{aligned}$$





# Batch gradient descent (BGD)

For the first *n* observations  $Loss_{1:n} = \frac{1}{n} \sum_{i=1}^{n} Loss_i$  so

$$egin{aligned} rac{\partial ext{Loss}_{1:n}}{\partial w} &= rac{1}{n} \sum_{i=1}^n rac{\partial ext{Loss}_i}{\partial w} = rac{1}{n} \sum_{i=1}^n rac{\partial ext{Loss}_i}{\hat{y}(x_i)} rac{\partial \hat{y}(x_i)}{\partial w} \ &= rac{1}{n} \sum_{i=1}^n 2(\hat{y}(x_i) - y_i) \, x_i. \end{aligned}$$

$$egin{aligned} rac{\partial ext{Loss}_{1:n}}{\partial b} &= rac{1}{n} \sum_{i=1}^n rac{\partial ext{Loss}_i}{\partial b} = rac{1}{n} \sum_{i=1}^n rac{\partial ext{Loss}_i}{\hat{y}(x_i)} rac{\partial \hat{y}(x_i)}{\partial b} \ &= rac{1}{n} \sum_{i=1}^n 2(\hat{y}(x_i) - y_i). \end{aligned}$$





# BGD, first iteration ( $\boldsymbol{\theta}_0 = \mathbf{0}$ )

	X	y	y_hat	loss	dL/dw	dL/db
0	1	0.99	0	0.98	-1.98	-1.98
1	2	3.00	0	9.02	-12.02	-6.01
2	3	5.01	O	25.15	-30.09	-10.03

#### So $\nabla \text{Loss}_{1:3}$ is

```
1 nabla = np.array([df["dL/dw"].mean(), df["dL/db"].mean()])  
2 nabla  
array([-14.69, -6. ])  
So with \eta=0.1 then \pmb{\theta}_1 becomes
```

```
1 theta_1 = theta_0 - 0.1 * nabla
2 theta_1
```

```
array([1.47, 0.6])
```





# BGD, second iteration

	X	y	y_hat	loss	dL/dw	dL/db
0	1	0.99	2.07	1.17	2.16	2.16
1	2	3.00	3.54	0.29	2.14	1.07
2	3	5.01	5.01	0.00	-0.04	-0.01

#### So $\nabla \text{Loss}_{1:3}$ is

```
1 nabla = np.array([df["dL/dw"].mean(), df["dL/db"].mean()])
2 nabla
```

array([1.42, 1.07])

so with  $\eta = 0.1$  then  $\theta_2$  becomes

```
1 theta_2 = theta_1 - 0.1 * nabla
2 theta_2
```

array([1.33, 0.49])





# Glossary

- batches, batch size
- gradient-based learning, hill-climbing
- stochastic (mini-batch) gradient descent



