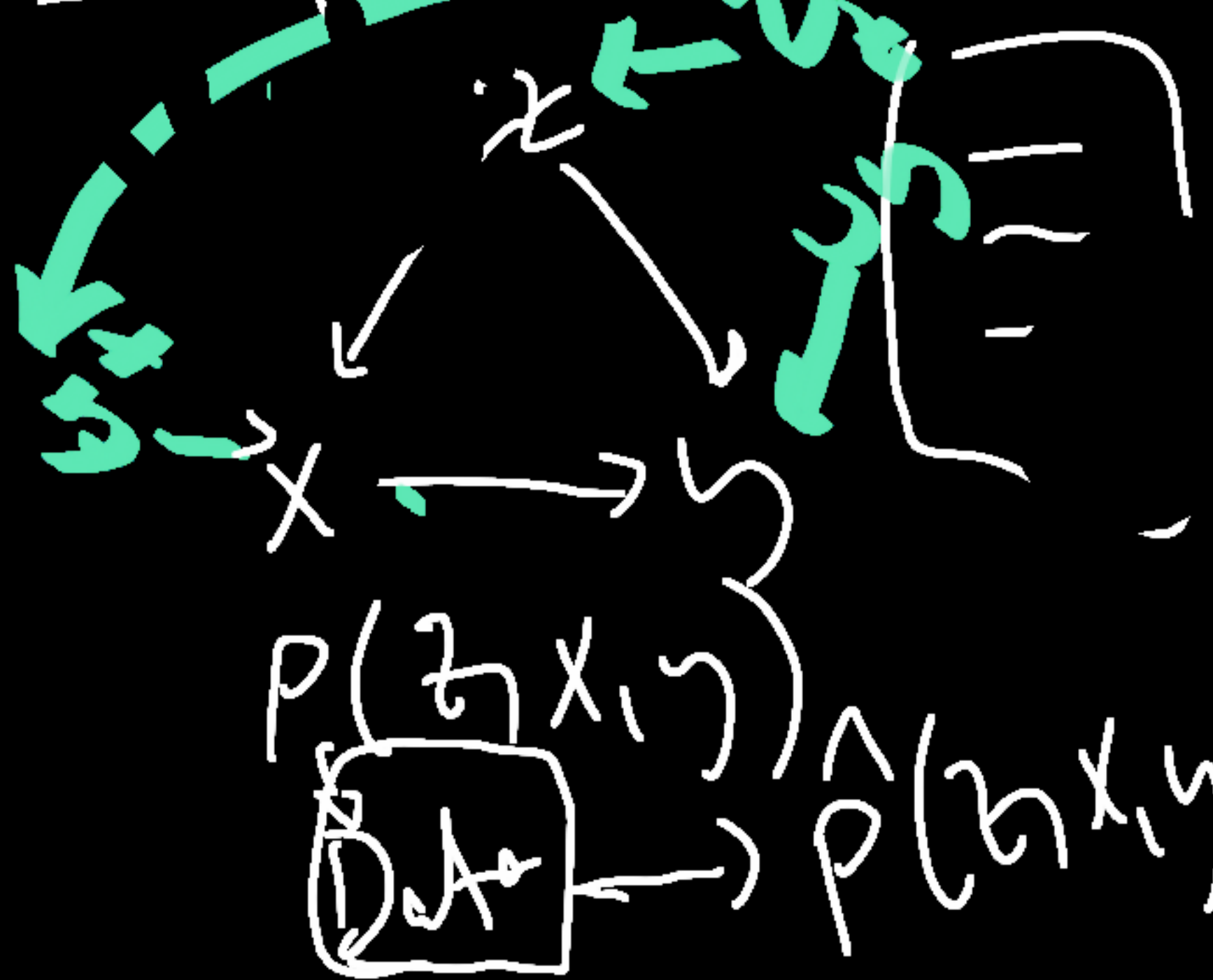


Obs/Natural (train)

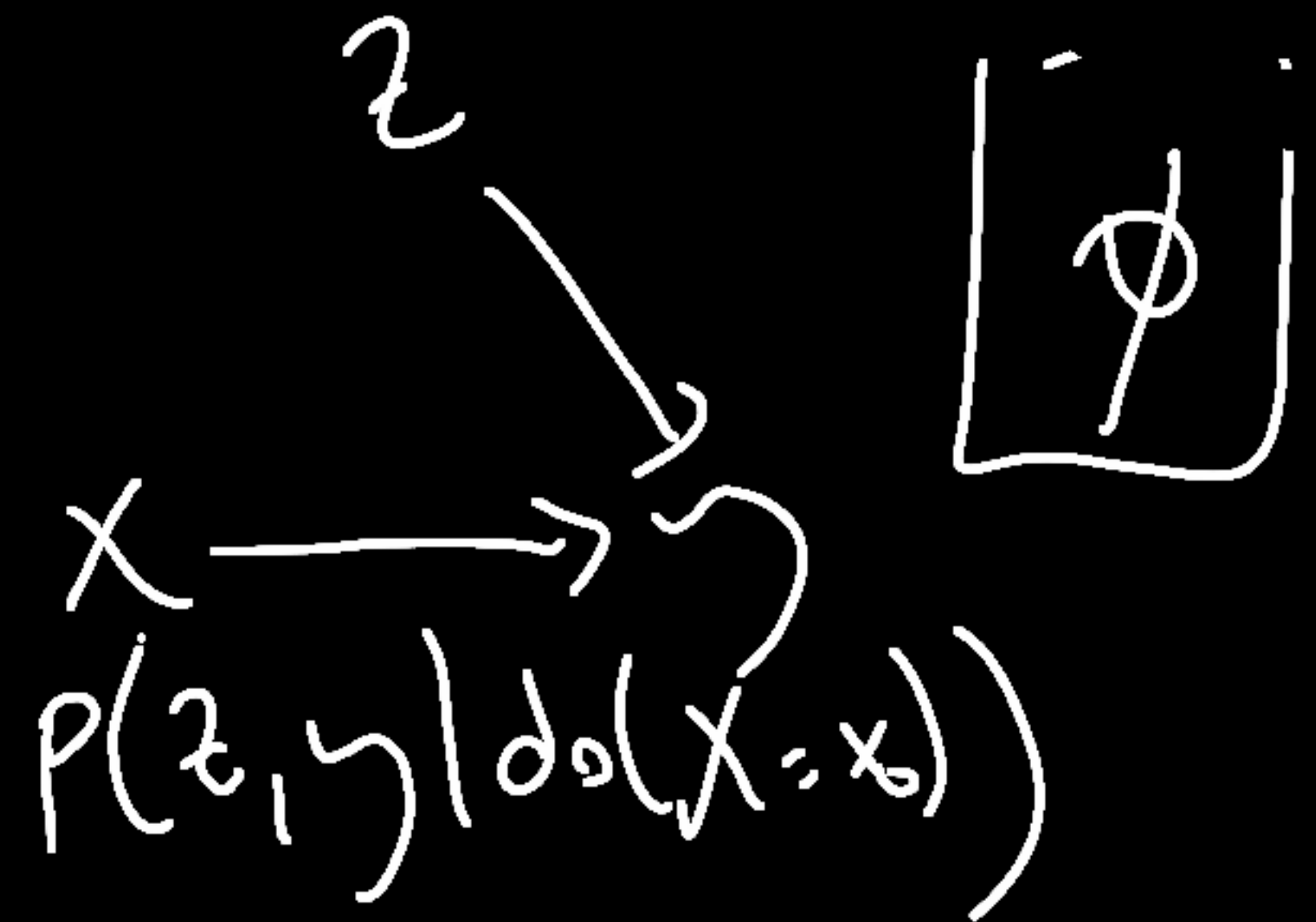
$$\Sigma \begin{cases} Z \leftarrow f_z(U_Z) \\ X \leftarrow f_x(Z, U_X) \\ Y \leftarrow f_y(X, Z, U_Y) \end{cases}$$

$p(U_X, U_Z, U_Y)$



Intervention/Causal

$$\begin{cases} Z \leftarrow f_z(U_Z) \\ X \leftarrow x_0 \\ Y \leftarrow f_y(X, Z, U_Y) \end{cases}$$



(11) of $Q = P(y|do(x))$

(1) V = set of Endo.

(2) U = set of Ex

(3) F
(4) $P(u)$

Def: Q is γ ID from G and $P(v)$

iff $\exists M_1, M_2$ s.t.

$G = G(M_1) = G(M_2)$,

$P_1(v) = P_2(v) \rightarrow Q_1 \neq Q_2$.

$\rightarrow P(v), G \models P(y|do(x))$
 $F, P(v) \models P(y, do(x))$

$\rightarrow \forall v_i \in V, \quad p(y/x) = p_1 + p_2 + p_3 + p_4$
 $v_i \leftarrow f_i(p_{a_i}, v_i),$
 $p_{a_i} \in V.$

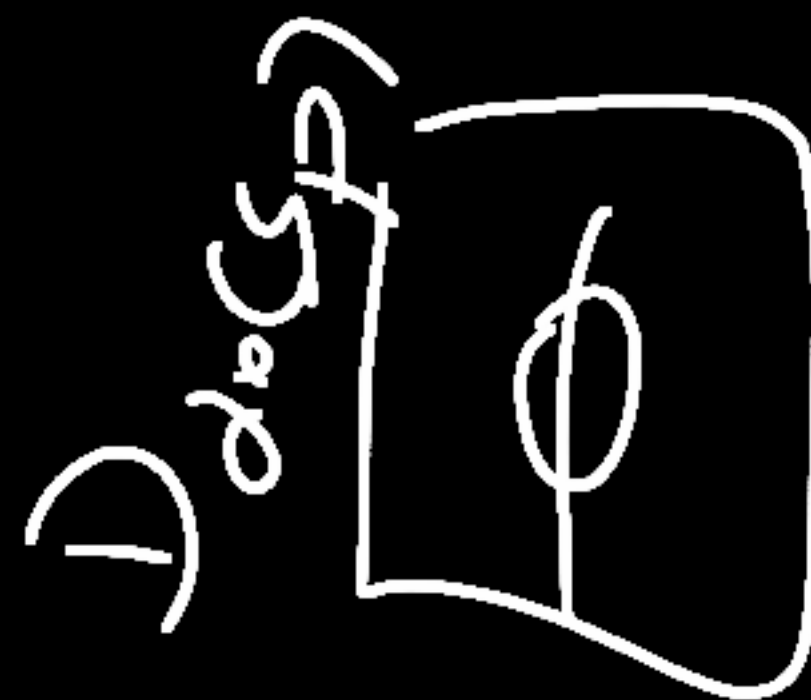
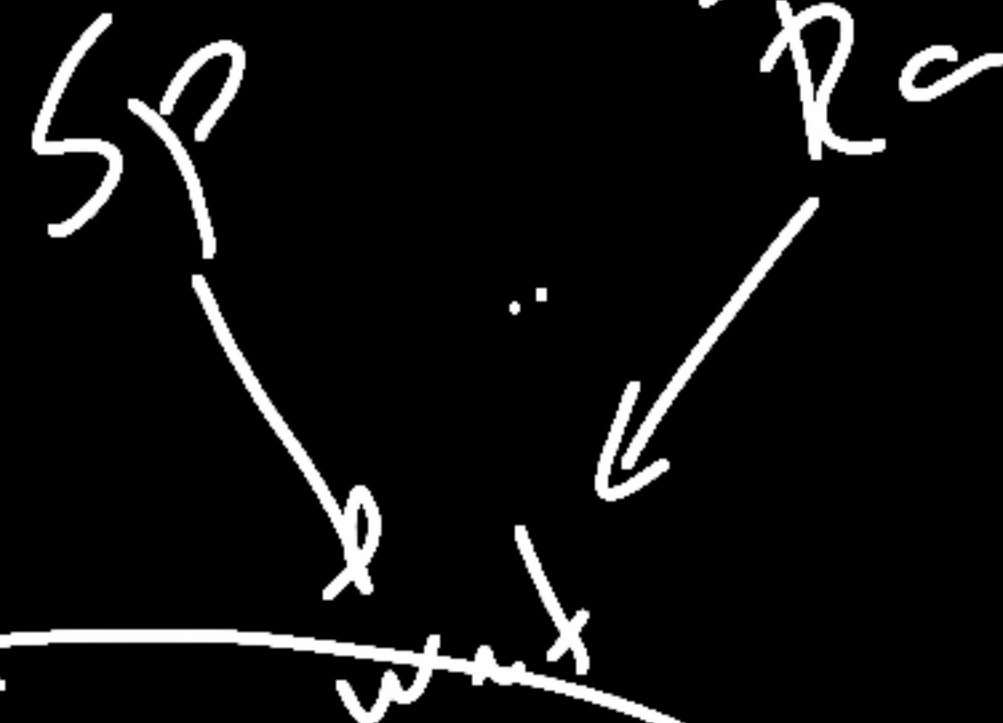
$U_i \in V.$

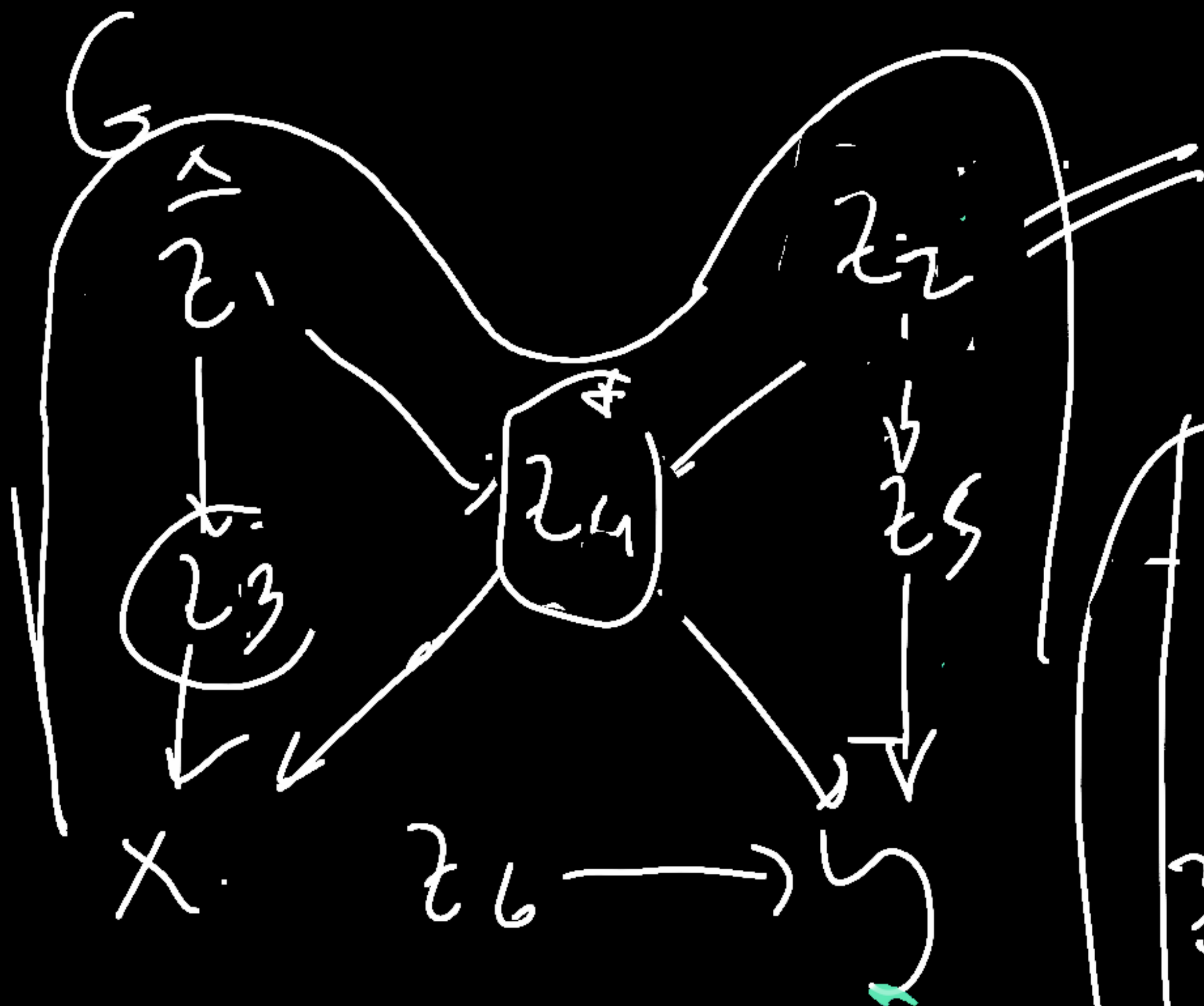
$$p(y|do(x)) = \sum_{p_{a_y}} p(y|p_{a_y}, x) \underbrace{p(p_{a_y})}_{p_y}$$

6: Sensor



$Q_i = P(wait | do(S_p)) \quad Q_i = P(w | do(S_p), do(R_a))$





$\{z_4, z_3\}?$ yes
 $\{z_4, z_2\}?$ yes
 $\{z_4\}?$ No!

Normal:

$X \rightarrow [y] \rightarrow z$ X

$X \leftarrow [y] \leftarrow z$

3 $X \leftarrow [y] \rightarrow z$

Abnormal

$X \rightarrow [y] \leftarrow z$

Q, $P(y|do(x)) = \sum_z P(y|x,z) P(z)$ (1)

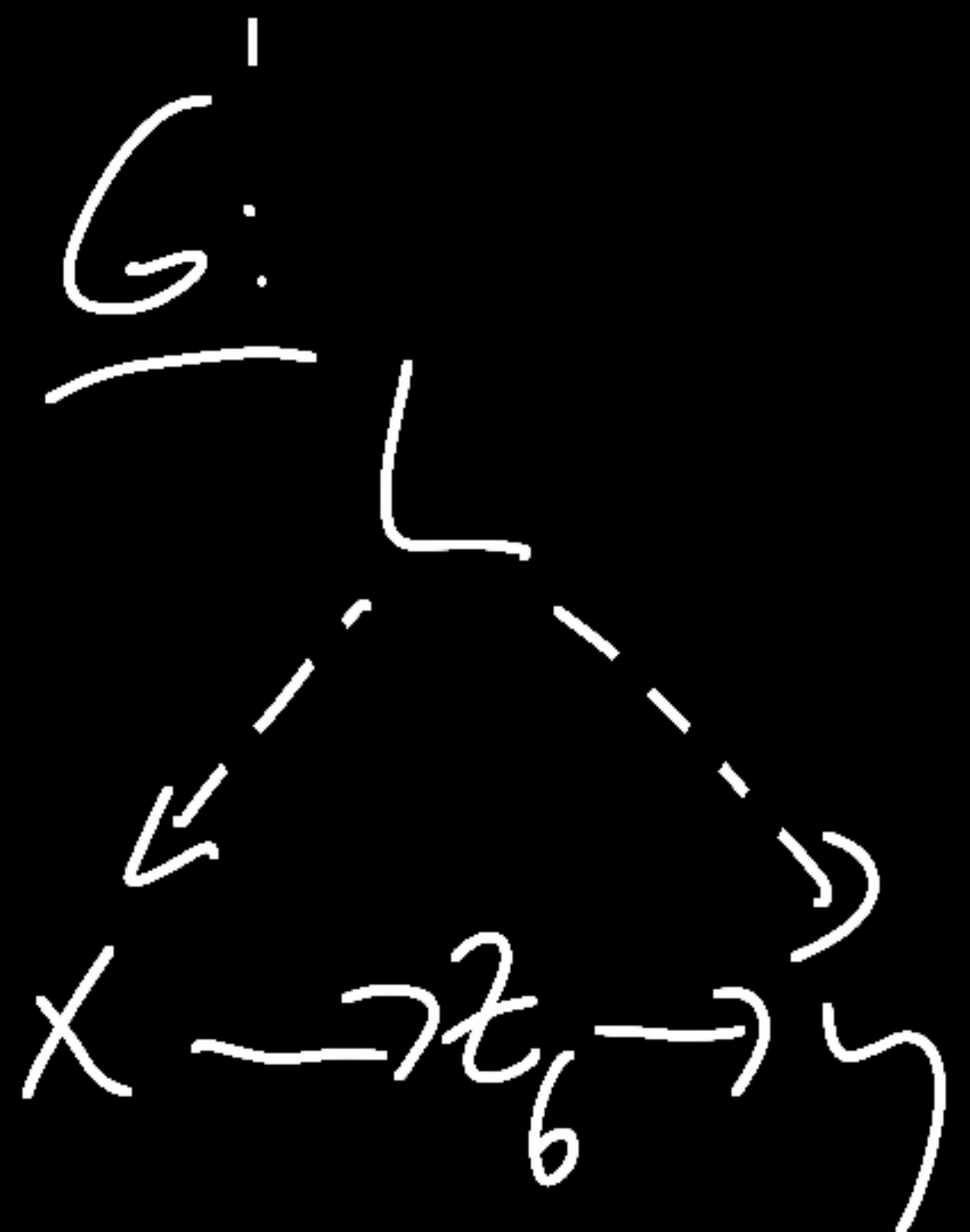
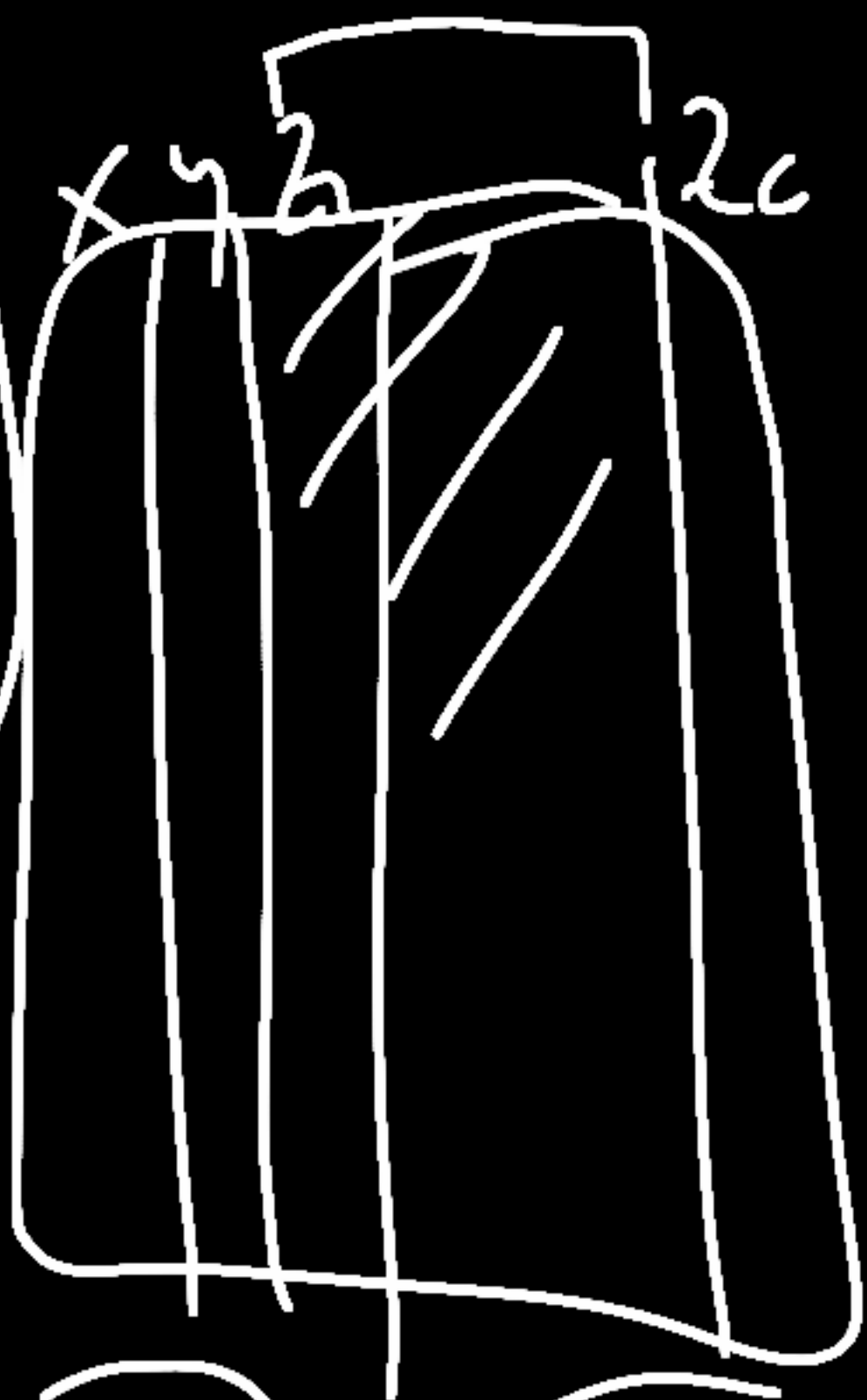
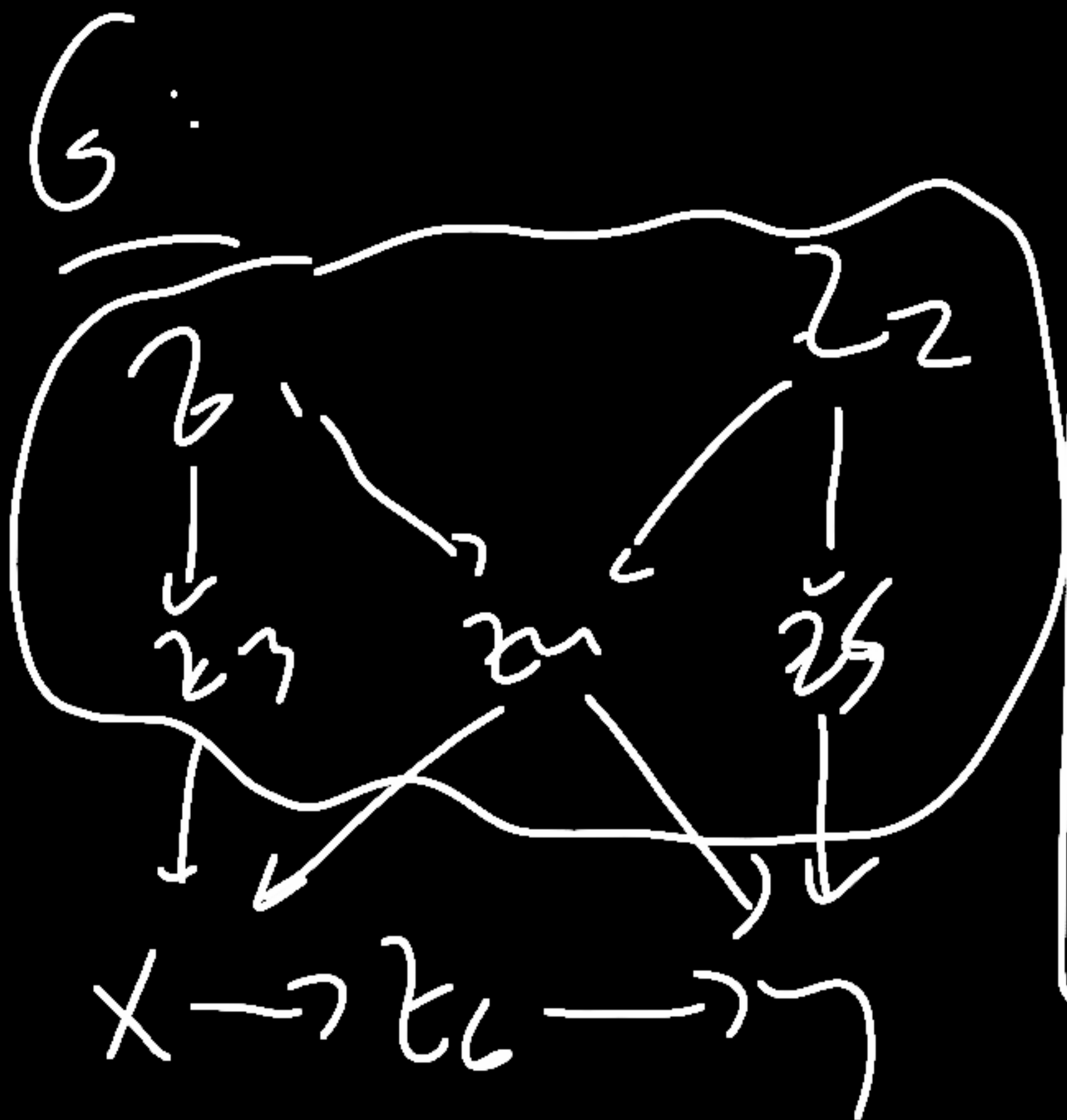
~~$P(x,y,z)$~~ 1953

$P(y|x,x) = \sum_z P(y|x,z) P(z|x)$ (2)

$z|y$

$x \neq z|y$
 $x \neq z$





$$P(x, y, zc) \rightarrow P(y | do(x)) \neq P(y)$$



$$p(y|x, z_c) p(z_c)$$

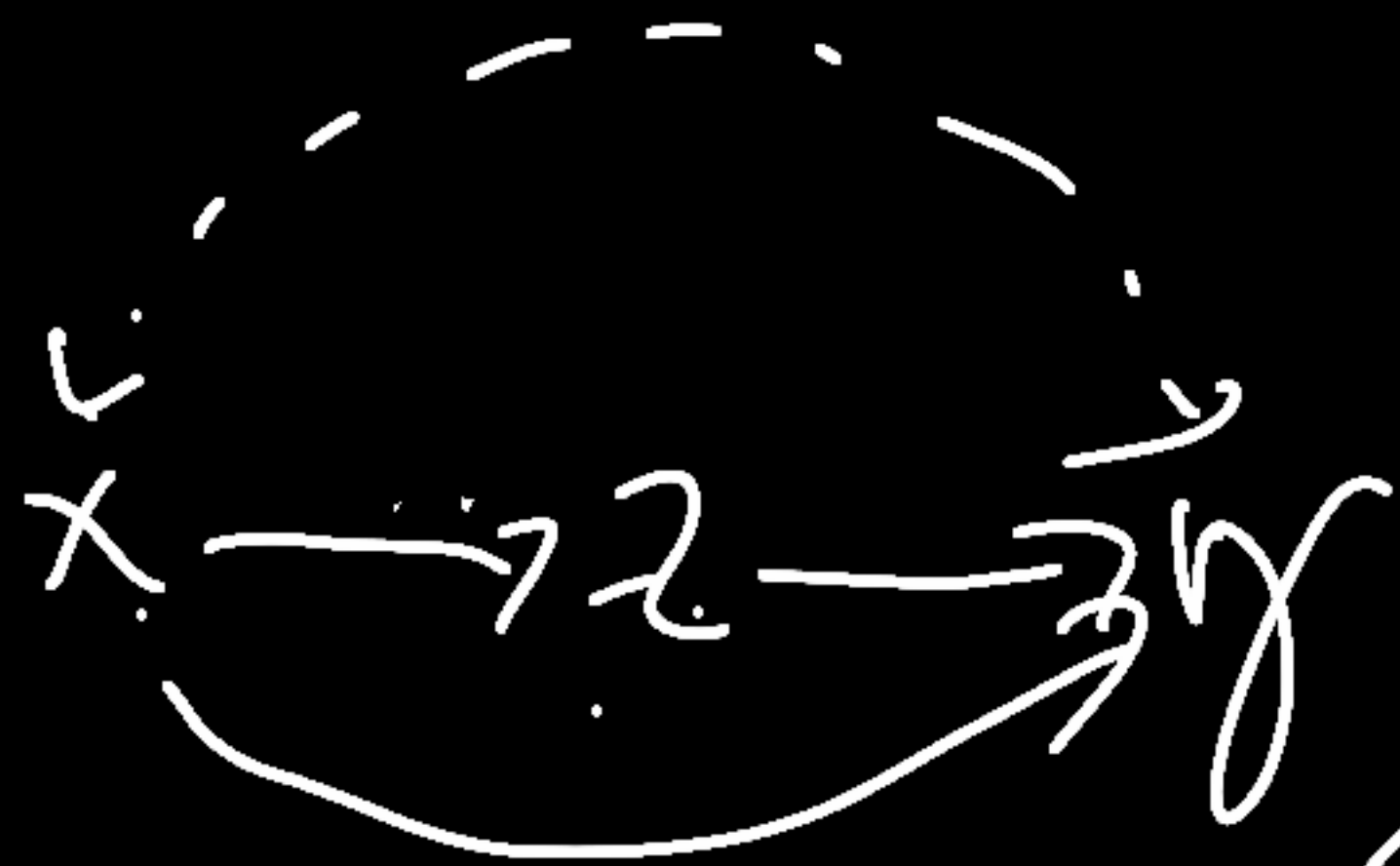
fd.c linear:

If z set fd.c has

$$p(y|z(x))$$

$$= \sum_z p(z|x) \left(\sum_{x'} p(y|z, x') p(x') \right)$$

$$= \sum_z p(z|x) \left(\sum_u p(y|z, u) p(u) \right)$$



6. $\bar{x}z$

~~$\bar{z}x$~~
 ~~$z\bar{z}$~~

$$P(y|x_0) = \sum_z P(z|x) \sum_{x'} P(y|z, x') P(x')$$

$$\sum_z P(z|do(x)) P(y|do(z))$$

~~$P(z|x)$~~

⑤

①

②

