Chapter 1 Background

Professor Gwan-Hwan Hwang

Dept. Computer Science and Information Engineering

National Taiwan Normal University

Definition of System Software from Wiki

• System software (or systems software) is computer software designed to operate and control the computer hardware and to provide a platform for running application software

- System software includes the following:
 - The operating system (prominent examples being z/OS, Microsoft Windows, Mac OS X and Linux),
 - allows the parts of a computer to work together by performing tasks like transferring data between memory and disks or rendering output onto a display device. It also provides a platform to run high-level system software and application software.

- System software includes the following:
 - Utility software helps to analyze, configure,
 optimize, and maintain the computer.
 - Device drivers such as computer BIOS and device firmware provide basic functionality to operate and control the hardware connected to or built into the computer.

- System software includes the following:
 - Window systems are components of a graphical user interface (GUI), and more specifically of a desktop environment, which supports the implementation of window managers, and provides basic support for graphics hardware, pointing devices such as mouse, and keyboards. The mouse cursor is also generally drawn by the windowing system.

- System software includes the following:
 - In some publications, the term system software also includes software development tools (like a compiler, linker or debugger).
 - In contrast to system software, software that allows users to do things like create text documents, play games, listen to music, or surf the web is called application software.

Definition of System Programming from Wiki

- System programming (or systems programming) is the activity of computer programming system software.
- The primary distinguishing characteristic of systems programming when compared to application programming is that application programming aims to produce software which provides services to the user (e.g. word processor), whereas systems programming aims to produce software which provides services to the computer hardware (e.g. disk defragmenter).
- It requires a greater degree of hardware awareness

Definition from ChatGPT

- System software refers to a type of software designed to manage and control computer hardware, providing an environment for application software to run efficiently. Its primary function is to act as a bridge between the user and the hardware, ensuring the computer operates smoothly.
- The main types of system software include:
 - Operating Systems (OS): These manage the computer's resources and provide an environment for application software to run. Examples include Windows, macOS, and Linux.
 - Device Drivers: These help the operating system communicate with hardware devices such as graphic cards, network adapters, and printers.
 - Utility Programs: These are tools for system maintenance and management, such as disk management, backup software, and file compression utilities.
 - Firmware: Low-level software embedded in hardware devices that controls basic operations of the hardware.
- Together, these types of system software ensure that hardware and application software work in harmony, allowing the computer to function properly.

Outlines

- 1.1 Introduction
- 1.2 System Software and Machine Architecture
- 1.3 The Simplified Instructional Computer (SIC)
 - SIC Machine Architecture
 - SIC/XE Machine Architecture
 - SIC Programming Examples
- 1.4 Traditional (CISC) Machines
- 1.5 RISC Machines

Introduction

- Definition of System software
 - System software consists of a variety of programs that support the operation of a computer
- Examples
 - Text editor, compiler, loader or linker, debugger, macro processors, operating system, database management systems, software engineering tools, etc.

System Software and Machine Architecture

- One characteristic in which most system software differs from application software is *machine dependency*
- System programs are intended to support the operation and use of the computer itself, rather than any particular application.
 - E.g. Assemblers, compilers, operating systems

System Software and Machine Architecture (Cont'd)

- There are some aspects of system software that do not directly depend upon the type of computing system being supported
 - The second para. of Section 1.2

System Software and Machine Architecture (Cont'd)

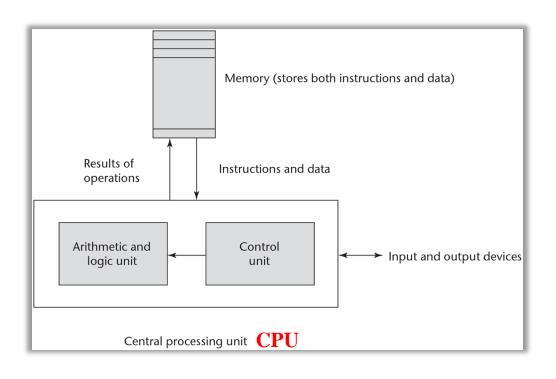
- Because most system software is machinedependent, we must include real machines and real pieces of software in our study.
- Simplified Instructional Computer (SIC)
 - SIC is a hypothetical computer that has been carefully designed to include the hardware features most often found on real machines, while avoiding unusual or irrelevant complexities

The Simplified Instructional Computer (SIC)

- Like many other products, SIC comes in two versions
 - The standard model
 - An XE version
 - "extra equipments", "extra expensive"
- The two versions has been designed to be *upward* compatible
 - An object program for the standard SIC machine will also execute properly on a SIC/XE system

Von Neumann architecture

 A computer architecture based on a 1945 description by John von Neumann



- A processing unit with both an arithmetic logic unit and a control unit
 - A control unit that includes an instruction register and a program counter
- Memory that stores <u>data</u> and instructions
- Input and output mechanisms
- Single bus system

SIC Machine Architecture

Memory

- Memory consists of 8-bit bytes
- Any 3 consecutive bytes form a word (24 bits)
- Total of 32768 (2¹⁵) bytes in the computer memory

Registers

- Five registers
- Each register is 24 bits in length

Mnemonic	Number	Special use
A	0	Accumulator
X	1	Index register
L	2	Linkage register
PC	8	Program counter
SW	9	Status word

Data Formats

- Integers are stored as 24-bit binary number
- 2's complement representation for negative values
- Characters are stored using 8-bit ASCII codes
- No floating-point hardware on the standard version of SIC

- Instruction Formats
 - Standard version of SIC
 - 24 bits

8	1	15
opcode	X	address

The flag bit x is used to indicate indexed-addressing mode

- Addressing Modes
 - There are two addressing modes available
 - Indicated by x bit in the instruction

Mode	Indication	Target address calculation
Direct	x=0	TA=address
Indexed	x=1	TA=address+(X)

(X): the contents of register X

- Instruction Set
 - Load and store registers
 - LDA, LDX, STA, STX, etc.
 - Integer arithmetic operations
 - ADD, SUB, MUL, DIV
 - All arithmetic operations involve register A and a word in memory, with the result being left in A
 - COMP
 - Conditional jump instructions
 - JLT, JEQ, JGT
 - Subroutine linkage
 - JSUB, RSUB
- See appendix A, Pages 495-498

- Input and Output
 - Input and output are performed by transferring
 1 byte at a time to or from the rightmost 8 bits
 of register A
 - Test Device TD instruction
 - Read Data (RD)
 - Write Data (WD)

SIC/XE Machine Architecture

Memory

Maximum memory available on a SIC/XE system is 1 megabyte (2²⁰ bytes)

- Registers
 - Additional registers are provided by SIC/XE

Mnemonic	Number	Special use
В	3	Base register
S	4	General working register
T	5	General working register
F	6	Floating-point accumulator (48 bits)

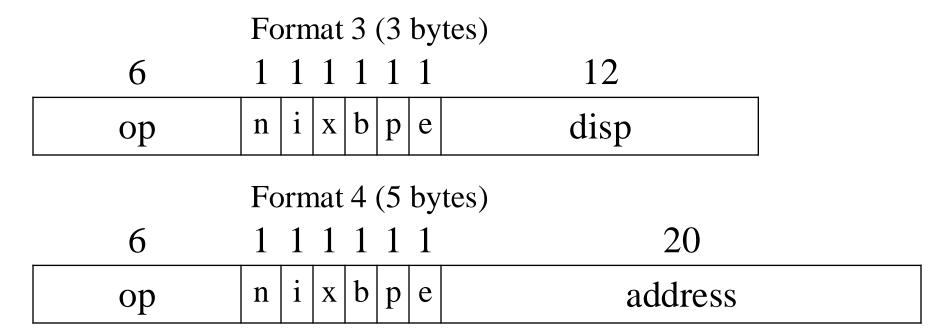
• There is a 48-bit floating-point data type

1	11	36
S	exponent	fraction

$$F*2^{(e-1024)}$$

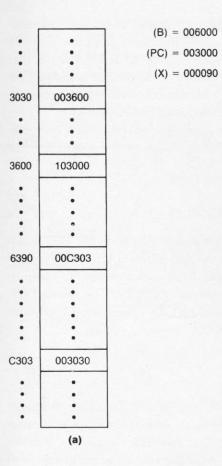
- Instruction Formats
 - 15 bits in (SIC), 20 bits in (SIC/XE)

Formats 1 and 2 are instructions that do not reference memory at all



Mode	Indication	Target add	dress calculation
Base relative	b=1,p=0	TA=(B)+disp	(0≤disp ≤4095)
Program-counter relative	b=0,p=1	TA=(PC)+disp	(-2048≤disp ≤2047)

- Instruction Formats
 - See Figure 1.1, P. 11.



Machine instruction							Value			
Hex						Bi	nary			loaded into Target register address A
	ор	n	i	x	b	р	е	disp/address		
032600	000000	1	1	0	0	1	0	0110 0000 0000	3600	103000
03C300	000000	1	1	1	1	0	0	0011 0000 0000	6390	00C3O3
022030	000000	1	0	0	0	1	0	0000 0011 0000	3030	103000
010030	000000	0	1	0	0	0	0	0000 0011 0000	30	000030
003600	000000	0	0	0	0	1	1	0110 0000 0000	3600	103000
0310C303	000000	1	1	0	0	0	1	0000 1100 0011 0000 0011	C303	003030
								(b)		

Figure 1.1 Examples of SIC/XE instructions and addressing modes.

Instruction Set

- Instructions to load and store the new registers
 - LDB, STB, etc.
- Floating-point arithmetic operations
 - ADDF, SUBF, MULF, DIVF
- Register move instruction
 - RMO
- Register-to-register arithmetic operations
 - ADDR, SUBR, MULR, DIVR
- Supervisor call instruction
 - SVC

Input and Output

 There are I/O channels that can be used to perform input and output while the CPU is executing other instructions

SIC Programming Examples

- Figure 1.2
 - Sample data movement operations
- Figure 1.3
 - Sample arithmetic operations
- Figure 1.4
 - Sample looping and indexing operations
- Figure 1.5
 - Sample looping and indexing operations
- Figure 1.6
 - I/O
- Figure 1.7
 - Subroutine call

	LDA STA LDCH STCH	FIVE ALPHA CHARZ C1	LOAD CONSTANT 5 INTO REGISTER A STORE IN ALPHA LOAD CHARACTER 'Z' INTO REGISTER A STORE IN CHARACTER VARIABLE C1
ALPHA	RESW	1	ONE-WORD VARIABLE
FIVE	WORD	5	ONE-WORD CONSTANT
CHARZ	BYTE	C'Z'	ONE-BYTE CONSTANT
C1	RESB	1	ONE-BYTE VARIABLE
			(a)
	LDA	#5	LOAD VALUE 5 INTO REGISTER A
	STA	ALPHA	STORE IN ALPHA
	LDA	#90	LOAD ASCII CODE FOR 'Z' INTO REG A
	STCH	C1	STORE IN CHARACTER VARIABLE C1
ALPHA	RESW	1	ONE-WORD VARIABLE
C1	RESB	1	ONE-BYTE VARIABLE
			(b)

Figure 1.2 Sample data movement operations for (a) SIC and (b) SIC/XE.

	LIDA ADD SUB STA LIDA ADD SUB STA	ALPHA INCR ONE BETA GAMMA INCR ONE DELTA	LOAD ALPHA INTO REGISTER A ADD THE VALUE OF INCR SUBTRACT 1 STORE IN BETA LOAD GAMMA INTO REGISTER A ADD THE VALUE OF INCR SUBTRACT 1 STORE IN DELTA
ONE	WORD	1	ONE-WORD CONSTANT
			ONE-WORD VARIABLES
ALPHA	RESW	1	
BETA	RESW	1	
GAMMA	RESW	1	
DELTA	RESW	1	
INCR	RESW	1	
-			
			(a)
	LDS	INCR	LOAD VALUE OF INCR INTO REGISTER S
	LDA	ALPHA	LOAD ALPHA INTO REGISTER A
	ADDR	S,A	ADD THE VALUE OF INCR
	SUB	#1	SUBTRACT 1
	STA	BETA	STORE IN BETA
	LDA	GAMMA	LOAD GAMMA INTO REGISTER A
	ADDR	S,A	ADD THE VALUE OF INCR
	SUB	#1	SUBTRACT 1
	STA	DELTA	STORE IN DELTA
			ONE WORD VARIABLES
ALPHA	RESW	1	
BETA	RESW	1	
GAMMA	RESW	1	
DELTA	RESW	1	
INCR	PEGE	1	
TIVOIC	RESW	1	

Figure 1.3 Sample arithmetic operations for (a) SIC and (b) SIC/XE.

(b)

MOVECH	LDX LDCH STCH TIX JLT	ZERO STR1,X STR2,X ELEVEN MOVECH	LOAD CHARACTE STORE CHARACT ADD 1 TO INDE	IDEX REGISTER TO 0 ER FROM STR1 INTO REG TER INTO STR2 EX, COMPARE RESULT TO K IS LESS THAN 11	
STR1 STR2 ZERO ELEVEN	BYTE RESB WORD WORD	C'TEST STRI 11 0 11	11-BYTE	STRING CONSTANT VARIABLE CONSTANTS	
			(a)		
MOVECH	LDT LDX LDCH STCH TIXR	#11 #0 STR1,X STR2,X	INITIALIZE IN LOAD CHARACTI STORE CHARACT	EGISTER T TO 11 NDEX REGISTER TO 0 ER FROM STR1 INTO REG IER INTO STR2 EX, COMPARE RESULT TO	
	JLT	MOVECH	LOOP IF INDEX	X IS LESS THAN 11	
STR1	BYTE	C'TEST STR	G' 11-BYTE	STRING CONSTANT	
STR2	RESB	11	11-BYTE	VARIABLE	
			(b)		

Figure 1.4 Sample looping and indexing operations for (a) SIC and (b) SIC/XE.

	LDA STA	ZERO INDEX	INITIALIZE INDEX VALUE TO 0
ADDLP	LDX	INDEX	LOAD INDEX VALUE INTO REGISTER X
TIDDEL	LDA	ALPHA, X	LOAD WORD FROM ALPHA INTO REGISTER A
	ADD	BETA, X	ADD WORD FROM BETA
	STA	GAMMA, X	STORE THE RESULT IN A WORD IN GAMMA
	LDA	INDEX	ADD 3 TO INDEX VALUE
	ADD	THREE	
	STA	INDEX	
	COMP	K300	COMPARE NEW INDEX VALUE TO 300
	JLT	ADDLP	LOOP IF INDEX IS LESS THAN 300
		TEDEL	DOOL IT INDEX IS DESS THAN 300
	B1		
	Marine I		
INDEX	RESW	1	ONE-WORD VARIABLE FOR INDEX VALUE
			ARRAY VARIABLES100 WORDS EACH
ALPHA	RESW	100	
BETA	RESW	100	
GAMMA	RESW	100	
			ONE-WORD CONSTANTS
ZERO	WORD	0	
K300	WORD	300	
THREE	WORD	3	
			(a)
	LDS	#3	INITIALIZE REGISTER S TO 3
	LDT	#300	INITIALIZE REGISTER T TO 300
	LDX	#0	INITIALIZE INDEX REGISTER TO 0
ADDLP	LDA	ALPHA, X	LOAD WORD FROM ALPHA INTO REGISTER A
	ADD	BETA, X	ADD WORD FROM BETA
	STA	GAMMA, X	STORE THE RESULT IN A WORD IN GAMMA
	ADDR	S,X	ADD 3 TO INDEX VALUE
	COMPR	X,T	COMPARE NEW INDEX VALUE TO 300
	JLT	ADDLP	LOOP IF INDEX VALUE IS LESS THAN 300
			ARRAY VARIABLES100 WORDS EACH
ALPHA	RESW	100	
BETA	RESW	100	
GAMMA	RESW	100	*

(b)

Figure 1.5 Sample indexing and looping operations for (a) SIC and (b) SIC/XE.

INLOOP	TD JEQ RD STCH	INDEV INLOOP INDEV DATA	TEST INPUT DEVICE LOOP UNTIL DEVICE IS READY READ ONE BYTE INTO REGISTER A STORE BYTE THAT WAS READ
OUTLP	TD JEQ LDCH WD .	OUTDEV OUTLP DATA OUTDEV	TEST OUTPUT DEVICE LOOP UNTIL DEVICE IS READY LOAD DATA BYTE INTO REGISTER A WRITE ONE BYTE TO OUTPUT DEVICE
INDEV OUTDEV DATA	BYTE BYTE RESB	X'F1' X'05' 1	INPUT DEVICE NUMBER OUTPUT DEVICE NUMBER ONE-BYTE VARIABLE

Figure 1.6 Sample input and output operations for SIC.

	JSUB	READ	CALL READ SUBROUTINE
			SUBROUTINE TO READ 100-BYTE RECORD
READ	LDX	ZERO	INITIALIZE INDEX REGISTER TO 0
RLOOP	TD	INDEV	TEST INPUT DEVICE
	JEQ	RLOOP	LOOP IF DEVICE IS BUSY
	RD	INDEV	READ ONE BYTE INTO REGISTER A
	STCH	RECORD, X	STORE DATA BYTE INTO RECORD
	TIX	K100	ADD 1 TO INDEX AND COMPARE TO 100
	JLT	RLOOP	LOOP IF INDEX IS LESS THAN 100
	RSUB		EXIT FROM SUBROUTINE
INDEV	BYTE	X'F1'	INPUT DEVICE NUMBER
RECORD	RESB	100	100-BYTE BUFFER FOR INPUT RECORD
			ONE-WORD CONSTANTS
ZERO	WORD	0	
K100	WORD	100	
			(a)
	JSUB	READ	CALL READ SUBROUTINE
			SUBROUTINE TO READ 100-BYTE RECORD
READ	LDX	#0	INITIALIZE INDEX REGISTER TO 0
	LDT	#100	INITIALIZE REGISTER T TO 100
RLOOP	TD	INDEV	TEST INPUT DEVICE
	JEQ	RLOOP	LOOP IF DEVICE IS BUSY
	RD	INDEV	READ ONE BYTE INTO REGISTER A
	STCH	RECORD, X	STORE DATA BYTE INTO RECORD
	TIXR	T	ADD 1 TO INDEX AND COMPARE TO 100
	JLT	RLOOP	LOOP IF INDEX IS LESS THAN 100
	RSUB		EXIT FROM SUBROUTINE
INDEV	BYTE	X'F1'	INPUT DEVICE NUMBER
RECORD	RESB	100	100-BYTE BUFFER FOR INPUT RECORD
			45

(b)

Figure 1.7 Sample subroutine call and record input operations for (a) SIC and (b) SIC/XE.