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# Linear Regression with Multiple Variables

## Multiple Features

# Multiple features (variables)

Size in feet <sup>2</sup> ( $x$ )	Price (\$) in 1000's ( $y$ )
2104	400
1416	232
1534	315
852	178
...	...

$$f_{w,b}(x) = wx + b$$

# Multiple features (variables)

$i=2$

Size in feet <sup>2</sup>	Number of bedrooms	Number of floors	Age of home in years	Price (\$) in \$1000's
$x_1$	$x_2$	$x_3$	$x_4$	
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178
...	...	...	...	...

$j=1 \dots 4$

$n=4$

$x_j = j^{th}$  feature

$n =$  number of features

$\vec{x}^{(i)}$  = features of  $i^{th}$  training example

$x_j^{(i)}$  = value of feature  $j$  in  $i^{th}$  training example

$$f_{\vec{w}, b}(\vec{x}) = w_1 x_1 + w_2 x_2 + \dots + w_n x_n + b$$

$\vec{w} = [w_1 \ w_2 \ w_3 \dots w_n]$  parameters  
of the model

vector  $\vec{x} = [x_1 \ x_2 \ x_3 \dots x_n]$

$$f_{\vec{w}, b}(\vec{x}) = \vec{w} \cdot \vec{x} + b = w_1 x_1 + w_2 x_2 + w_3 x_3 + \dots + w_n x_n + b$$

dot product

multiple linear regression

(not multivariate regression)

# Linear Regression with Multiple Variables

## Vectorization

## Parameters and features

$$\vec{w} = [w_1 \ w_2 \ w_3] \quad n=3$$

$b$  is a number

$$\vec{x} = [x_1 \ x_2 \ x_3]$$

linear algebra: count from 1

$$w[0] \quad w[1] \quad w[2]$$

```
w = np.array([1.0, 2.5, -3.3])
```

```
b = 4
```

$$x[0] \quad x[1] \quad x[2]$$

```
x = np.array([10, 20, 30])
```

code: count from 0

## Without vectorization $n=100,000$

$$f_{\vec{w}, b}(\vec{x}) = w_1 x_1 + w_2 x_2 + w_3 x_3 + b$$

```
f = w[0] * x[0] +
    w[1] * x[1] +
    w[2] * x[2] + b
```



## Without vectorization

$$f_{\vec{w}, b}(\vec{x}) = \left( \sum_{j=1}^n w_j x_j \right) + b \quad \sum_{j=1}^n \rightarrow j=1 \dots n \\ 1, 2, 3$$

$$\text{range}(0, n) \rightarrow j=0 \dots n-1$$

```
f = 0
for j in range(0, n):
    f = f + w[j] * x[j]
f = f + b
```

## Vectorization

$$f_{\vec{w}, b}(\vec{x}) = \vec{w} \cdot \vec{x} + b$$

```
f = np.dot(w, x) + b
```

## Without vectorization

```
for j in range(0,16):  
    f = f + w[j] * x[j]
```

$t_0$

$f + w[0] * x[0]$

$t_1$

$f + w[1] * x[1]$

...

$t_{15}$

$f + w[15] * x[15]$

## Vectorization

```
np.dot(w,x)
```

$t_0$

w[0]	w[1]	...	w[15]
------	------	-----	-------

in parallel \* \* ... \*

x[0]	x[1]	...	x[15]
------	------	-----	-------

$t_1$

$$w[0]*x[0] + w[1]*x[1] + \dots + w[15]*x[15]$$

efficient → scale to large datasets

Gradient descent

$$\vec{w} = (w_1 \quad w_2 \quad \cdots \quad w_{16}) \quad \cancel{b} \text{ parameters}$$

derivatives  $\vec{d} = (d_1 \quad d_2 \quad \cdots \quad d_{16})$

```
w = np.array([0.5, 1.3, ... 3.4])
```

```
d = np.array([0.3, 0.2, ... 0.4])
```

compute  $w_j = w_j - 0.1d_j$  for  $j = 1 \dots 16$

Without vectorization

$$w_1 = w_1 - 0.1d_1$$

$$w_2 = w_2 - 0.1d_2$$

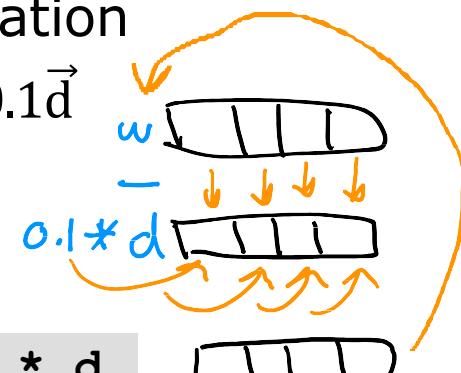
:

$$w_{16} = w_{16} - 0.1d_{16}$$

```
for j in range(0,16):  
    w[j] = w[j] - 0.1 * d[j]
```

With vectorization

$$\vec{w} = \vec{w} - 0.1\vec{d}$$



```
w = w - 0.1 * d
```

# Linear Regression with Multiple Variables

## Gradient Descent for Multiple Regression

## Previous notation

Parameters

$$w_1, \dots, w_n$$

$$b$$

Model  $f_{\vec{w}, b}(\vec{x}) \rightarrow w_1 x_1 + \dots + w_n x_n + b$

Cost function  $J(\underbrace{w_1, \dots, w_n, b}_{})$

Gradient descent

repeat {

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\underbrace{w_1, \dots, w_n, b}_{})$$

$$b = b - \alpha \frac{\partial}{\partial b} J(\underbrace{w_1, \dots, w_n, b}_{})$$

}

## Vector notation

$\vec{w}$  *vector of length n*  
 $w_1 \dots w_n$   
 $b$  still a number  
 $f_{\vec{w}, b}(\vec{x}) = \vec{w} \cdot \vec{x} + b$   
 $J(\vec{w}, b)$  dot product

repeat {

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\vec{w}, b)$$

$$b = b - \alpha \frac{\partial}{\partial b} J(\vec{w}, b).$$

}

# Gradient descent

One feature

repeat {

$$\underline{w} = w - \alpha \frac{1}{m} \sum_{i=1}^m (f_{w,b}(x^{(i)}) - y^{(i)}) x^{(i)}$$

$$\frac{\partial}{\partial w} J(w, b)$$

$$b = b - \alpha \frac{1}{m} \sum_{i=1}^m (f_{w,b}(x^{(i)}) - y^{(i)})$$

simultaneously update  $w, b$

}

$n$  features ( $n \geq 2$ )

repeat {

$$\begin{aligned} j &= 1 \\ \underline{w}_1 &= w_1 - \alpha \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_1^{(i)} \end{aligned}$$

:

$$\frac{\partial}{\partial w_1} J(\vec{w}, b)$$

$$\begin{aligned} j &= n \\ w_n &= w_n - \alpha \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_n^{(i)} \end{aligned}$$

$$b = b - \alpha \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

simultaneously update  
 $w_j$  (for  $j = 1, \dots, n$ ) and  $b$

}

# An alternative to gradient descent

## Normal equation

- Only for linear regression
- Solve for  $w$ ,  $b$  without iterations

### Disadvantages

- Doesn't generalize to other learning algorithms.
- Slow when the number of features is large ( $> 10,000$ )

## What you need to know

- Normal equation method may be used in machine learning libraries that implement linear regression.
- Gradient descent is the recommended method for finding parameters  $w, b$

# Practical Tips for Linear Regression

## Feature Scaling

# Feature and parameter values

$$price = w_1 x_1 + w_2 x_2 + b$$

size #bedrooms

$x_1$ : size (feet<sup>2</sup>)

range: 300 – 2,000

$x_2$ : # bedrooms

range: 0 – 5

House:  $x_1 = 2000$ ,  $x_2 = 5$ ,  $price = \$500k$

one training example

size of the parameters  $w_1, w_2$ ?

$$w_1 = 50, \quad w_2 = 0.1, \quad b = 50$$

$$price = \underbrace{50 * 2000}_{100,000K} + \underbrace{0.1 * 5}_{0.5K} + \underbrace{50}_{50K}$$

$$price = \$100,050.5K$$

$$w_1 = 0.1, \quad w_2 = 50, \quad b = 50$$

small

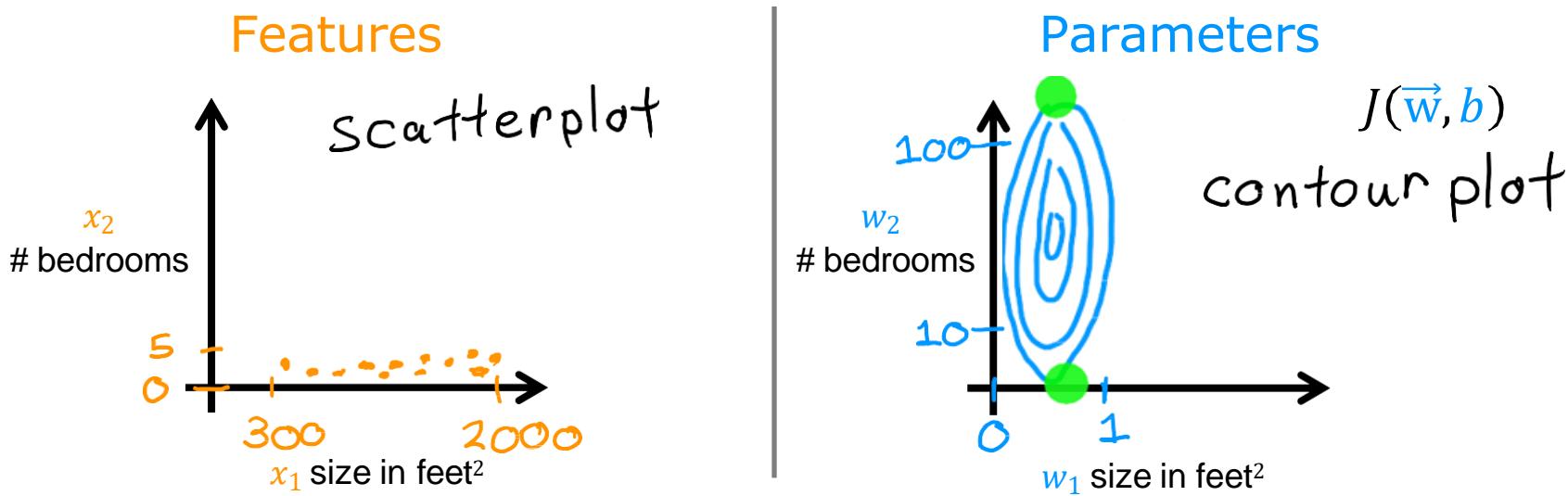
$$price = \underbrace{0.1 * 2000K}_{200K} + \underbrace{50 * 5}_{250K} + \underbrace{50}_{50K}$$

$$price = \$500k$$

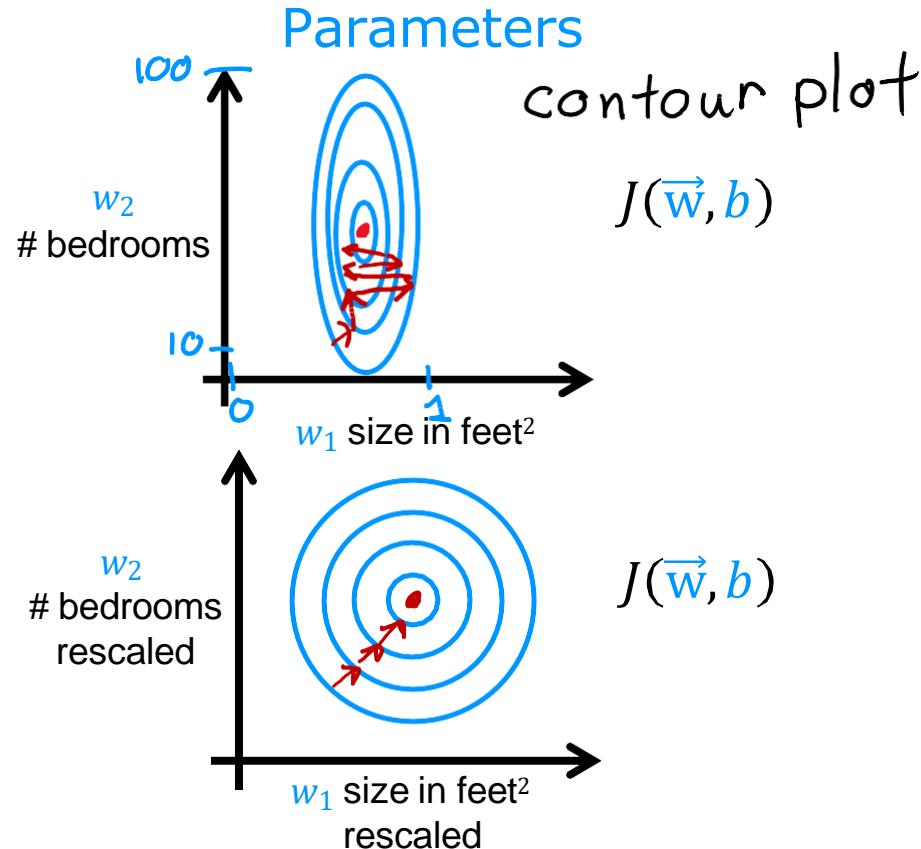
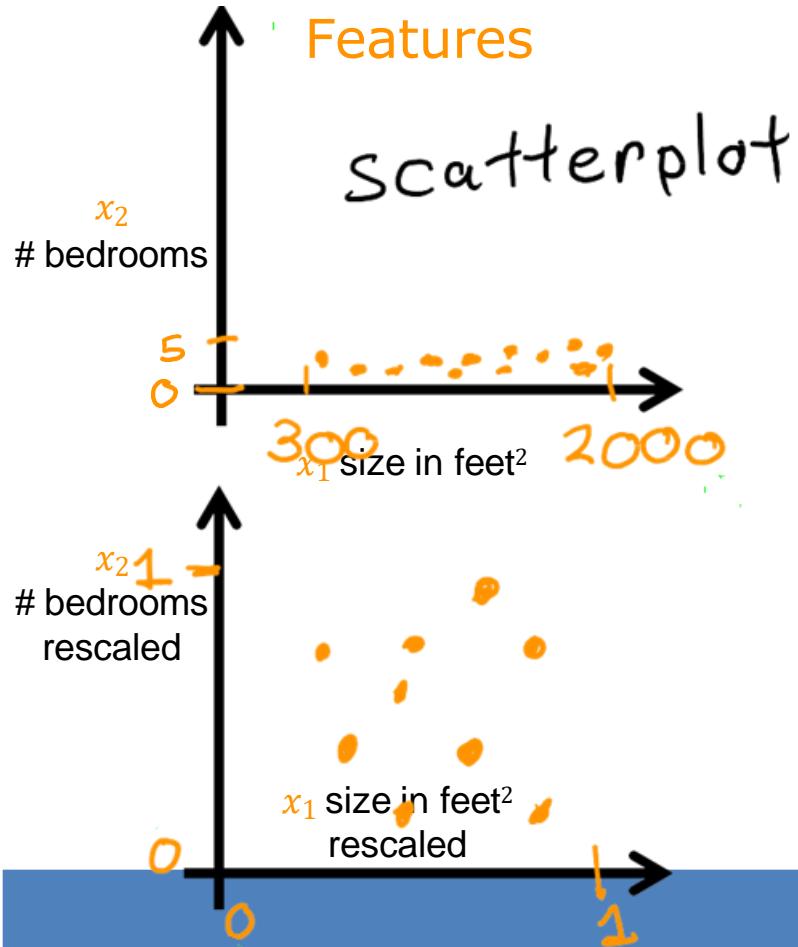
more reasonable

# Feature size and parameter size

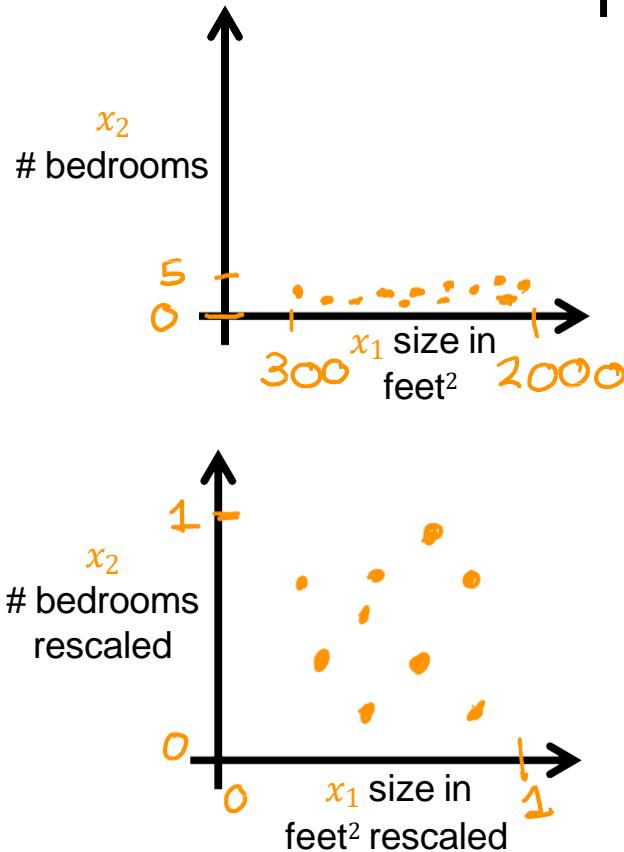
	size of feature $x_j$	size of parameter $w_j$
size in feet <sup>2</sup>	↔	↔
#bedrooms	↔	↔



# Feature size and gradient descent



# Feature scaling



$$300 \leq x_1 \leq 2000$$

$$x_{1,scaled} = \frac{x_1}{2000 \max}$$

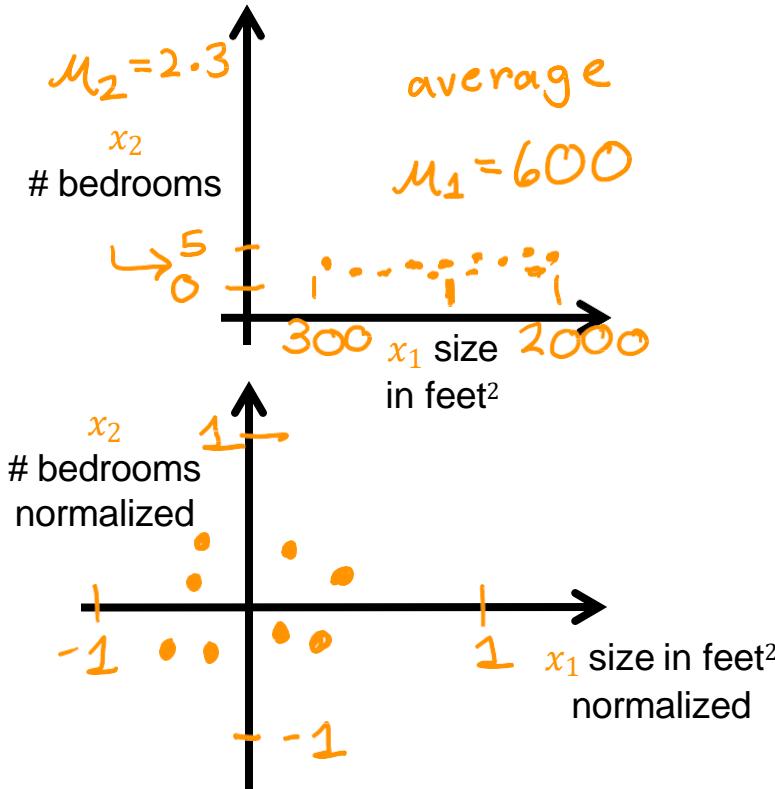
$$0 \leq x_2 \leq 5$$

$$x_{2,scaled} = \frac{x_2}{5 \max}$$

$$0.15 \leq x_{1,scaled} \leq 1$$

$$0 \leq x_{2,scaled} \leq 1$$

# Mean normalization



$$300 \leq x_1 \leq 2000$$

$$x_1 = \frac{x_1 - \mu_1}{2000 - 300}$$

max-min

$$-0.18 \leq x_1 \leq 0.82$$

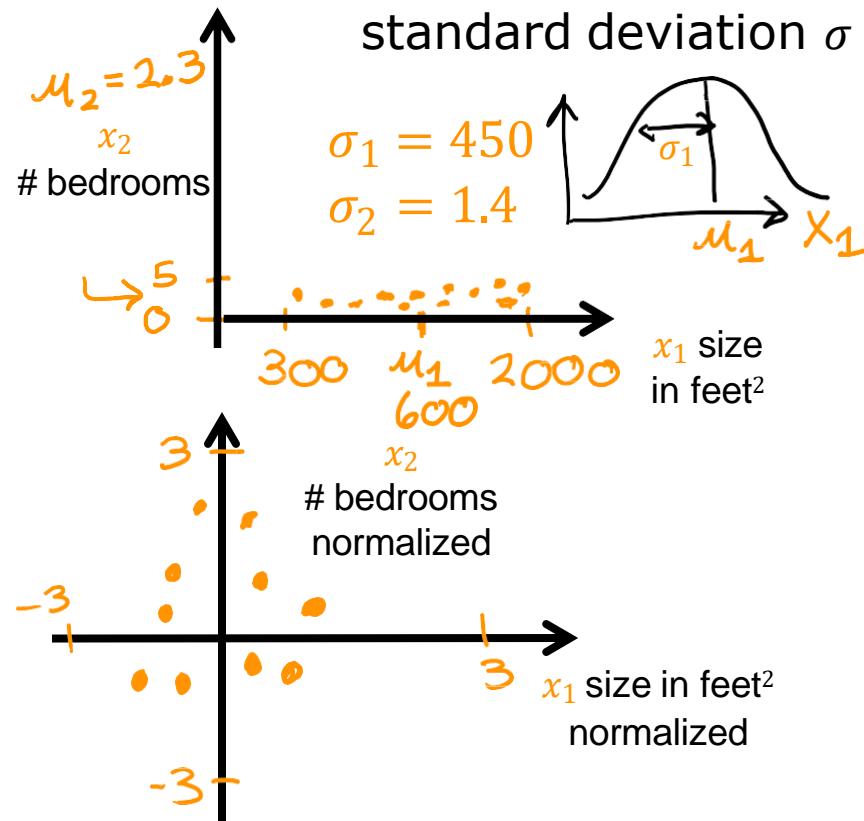
$$0 \leq x_2 \leq 5$$

$$x_2 = \frac{x_2 - \mu_2}{5 - 0}$$

max-min

$$-0.46 \leq x_2 \leq 0.54$$

# Z-score normalization



$$300 \leq x_1 \leq 2000$$

$$x_1 = \frac{x_1 - \mu_1}{\sigma_1}$$

$$-0.67 \leq x_1 \leq 3.1$$

$$0 \leq x_2 \leq 5$$

$$x_2 = \frac{x_2 - \mu_2}{\sigma_2}$$

$$-1.6 \leq x_2 \leq 1.9$$

# Feature scaling

aim for about  $-1 \leq x_j \leq 1$  for each feature  $x_j$

$$-3 \leq x_j \leq 3$$

$$-0.3 \leq x_j \leq 0.3$$

$$0 \leq x_1 \leq 3$$

$$-2 \leq x_2 \leq 0.5$$

$$-100 \leq x_3 \leq 100$$

$$-0.001 \leq x_4 \leq 0.001$$

$$98.6 \leq x_5 \leq 105$$

# Feature scaling

aim for about  $-1 \leq x_j \leq 1$  for each feature  $x_j$

$$\begin{array}{l} -3 \leq x_j \leq 3 \\ -0.3 \leq x_j \leq 0.3 \end{array} \quad \left. \right\} \text{acceptable ranges}$$

$$0 \leq x_1 \leq 3$$

Okay, no rescaling

$$-2 \leq x_2 \leq 0.5$$

Okay, no rescaling

$$-100 \leq x_3 \leq 100$$

too large  $\rightarrow$  rescale

$$-0.001 \leq x_4 \leq 0.001$$

too small  $\rightarrow$  rescale

$$98.6 \leq x_5 \leq 105$$

too large  $\rightarrow$  rescale

# Practical Tips for Linear Regression

Checking Gradient Descent  
for Convergence

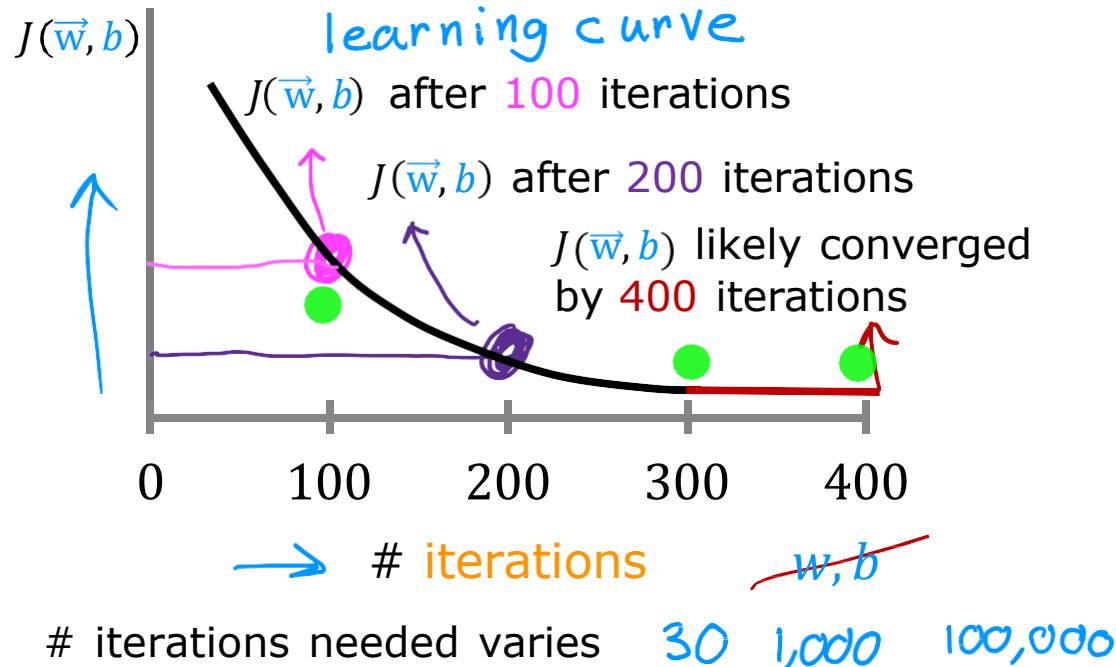
# Gradient descent

$$w_j = w_j - \textcolor{purple}{\alpha} \frac{\partial}{\partial w_j} J(\vec{w}, b)$$

$$b = b - \textcolor{purple}{\alpha} \frac{\partial}{\partial b} J(\vec{w}, b)$$

# Make sure gradient descent is working correctly

objective:  $\min_{\vec{w}, b} J(\vec{w}, b)$        $J(\vec{w}, b)$  should decrease  
after every iteration



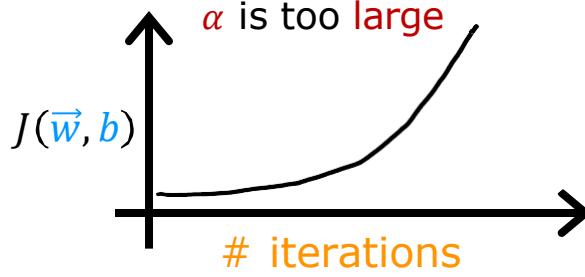
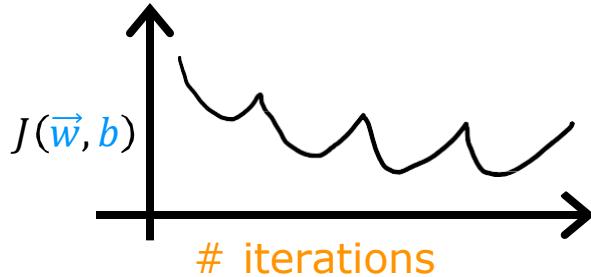
Automatic convergence test  
Let  $\varepsilon$  "epsilon" be  $10^{-3}$ .  
**0.001**

If  $J(\vec{w}, b)$  decreases by  $\leq \varepsilon$  in one iteration,  
declare **convergence**.  
(found parameters  $\vec{w}, b$   
to get close to  
global minimum)

# Practical Tips for Linear Regression

Choosing the  
Learning Rate

# Identify problem with gradient descent



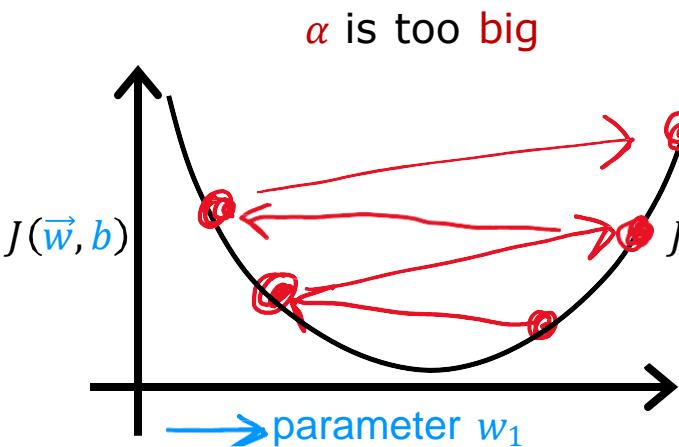
or learning rate is too large

$$w_1 = w_1 + \alpha d_1$$

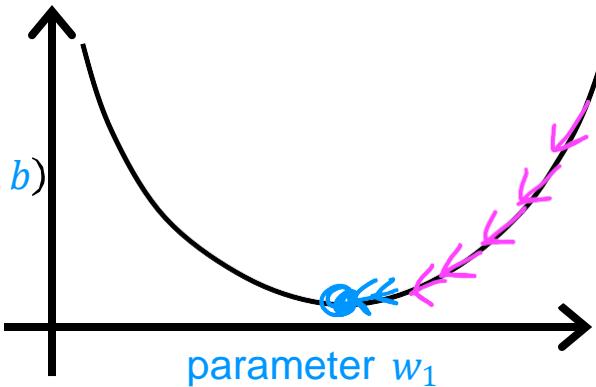
use a minus sign

$$w_1 = w_1 - \alpha d_1$$

## Adjust learning rate



Use smaller  $\alpha$

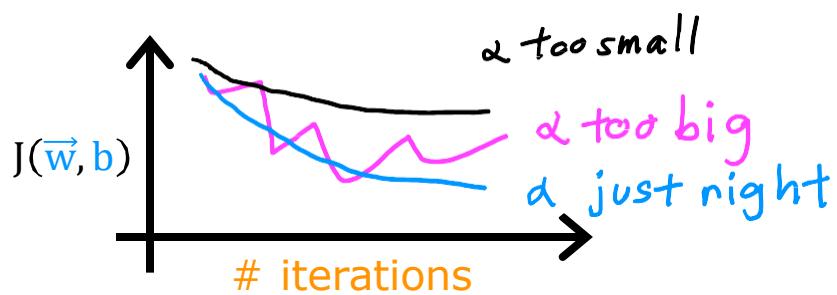
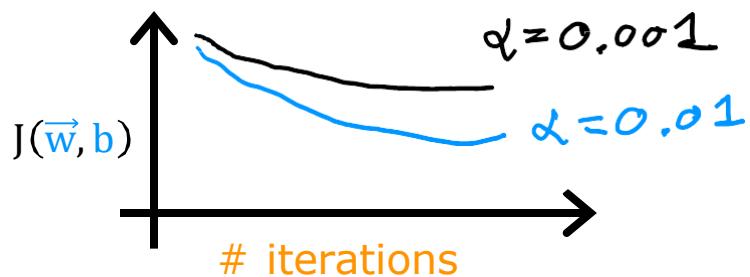


With a small enough  $\alpha$ ,  $J(\vec{w}, b)$  should decrease on every iteration

If  $\alpha$  is too small, gradient descent takes a lot more iterations to converge

Values of  $\alpha$  to try:

... 0.001 0.003 0.01 0.03 0.1 0.3 1 ...  
3X  $\approx 3X$  3X  $\approx 3X$  3X  $\approx 3X$



# Practical Tips for Linear Regression

## Feature Engineering

# Feature engineering

$$f_{\vec{w}, b}(\vec{x}) = w_1 \underline{x_1} + w_2 \underline{x_2} + b$$

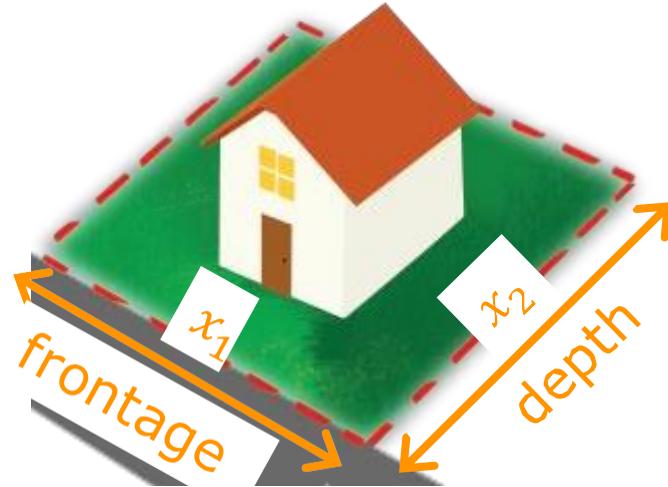
frontage      depth

$$\text{area} = \text{frontage} \times \text{depth}$$

$$x_3 = x_1 x_2$$

new feature

$$f_{\vec{w}, b}(\vec{x}) = \underline{w_1} \underline{x_1} + \underline{w_2} \underline{x_2} + \underline{w_3} \underline{x_3} + b$$



Feature engineering:  
Using **intuition** to design  
**new features**, by  
transforming or combining  
original features.

# Important notes

- Sci-kit learn library `LinearRegression()` model uses Ordinary Least Squares (OLS) Method with no involvement of optimization
- Stochastic Gradient Descent (SGD) regressor in sci-kit learning uses a stochastic gradient descent algorithm to optimize the cost function.

# Ordinary Least Squares (OLS) Method

The **ordinary Least Squares (OLS)** estimator for linear regression is derived by minimizing the sum of squared errors between the observed values and the predicted values of a linear model.

The goal of OLS is to minimize the sum of the squared residuals (errors) between the actual values  $\mathbf{y}$  and the predicted values  $\hat{\mathbf{y}}$ :

$$\mathbf{y} - \hat{\mathbf{y}} = \mathbf{y} - \mathbf{X}\boldsymbol{\beta}$$

We define the sum of squared errors (SSE) as:

$$S(\boldsymbol{\beta}) = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^\top (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$

This function,  $S(\boldsymbol{\beta})$ , is the **objective function** we aim to minimize with respect to  $\boldsymbol{\beta}$ .

# Expanding the Objective Function:

Let's expand the SSE to make it easier to differentiate:

$$S(\beta) = (\mathbf{y} - \mathbf{X}\beta)^\top (\mathbf{y} - \mathbf{X}\beta)$$

Using the distributive property of the transpose operation, we get:

$$S(\beta) = \mathbf{y}^\top \mathbf{y} - 2\mathbf{y}^\top \mathbf{X}\beta + \beta^\top \mathbf{X}^\top \mathbf{X}\beta$$

This expression represents the sum of squared errors that we need to minimize with respect to  $\beta$ .

# Minimization by Taking the Derivative:

To find the value of  $\beta$  that minimizes  $S(\beta)$ , we take the derivative of  $S(\beta)$  with respect to  $\beta$  and set it equal to zero.

The derivative of  $S(\beta)$  with respect to  $\beta$  is:

$$\frac{\partial S(\beta)}{\partial \beta} = -2\mathbf{X}^\top \mathbf{y} + 2\mathbf{X}^\top \mathbf{X}\beta$$

Now, set the derivative equal to zero to find the minimum:

$$-2\mathbf{X}^\top \mathbf{y} + 2\mathbf{X}^\top \mathbf{X}\beta = 0$$

Simplifying the equation:

$$\mathbf{X}^\top \mathbf{X}\beta = \mathbf{X}^\top \mathbf{y}$$

# OLS Estimator

To solve for  $\beta$ , we multiply both sides of the equation by  $(\mathbf{X}^\top \mathbf{X})^{-1}$ , assuming  $\mathbf{X}^\top \mathbf{X}$  is invertible:

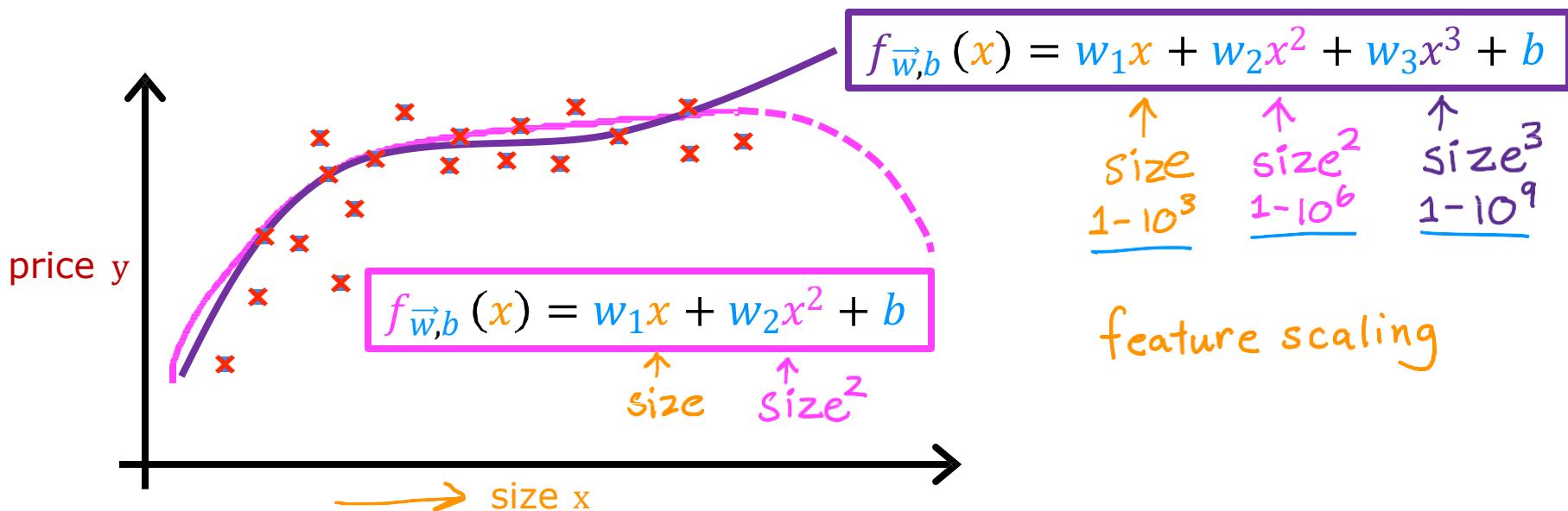
$$\beta = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

The above expression is the **OLS estimator** for  $\beta$ , which gives the coefficients that minimize the sum of squared residuals:

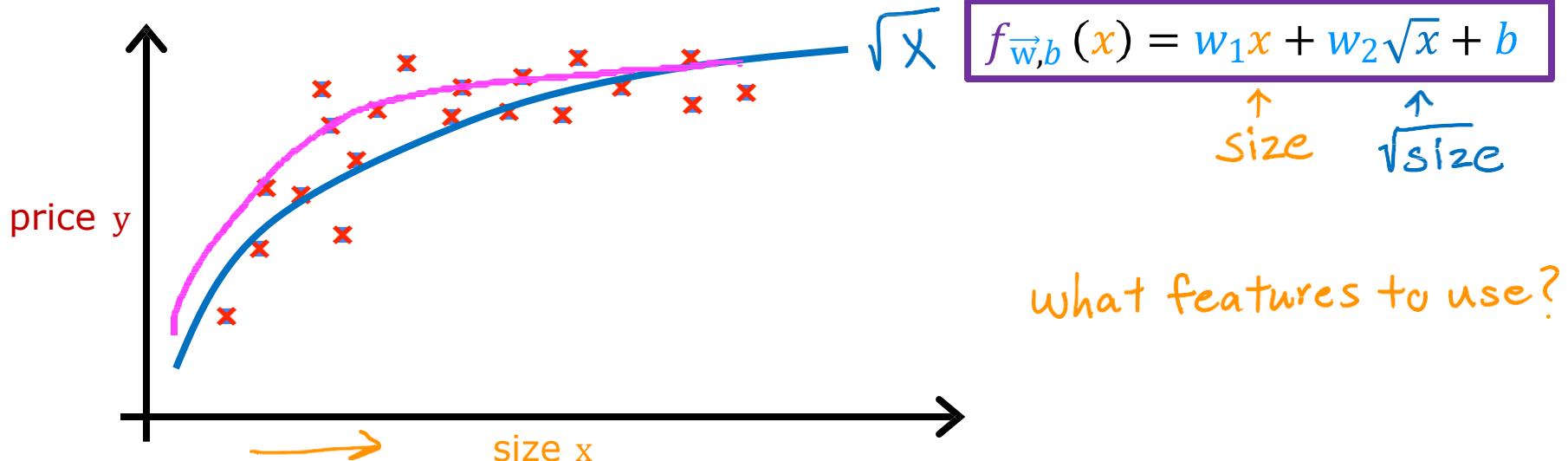
$$\hat{\beta} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

This is the closed-form solution for the OLS estimator.

# Polynomial regression



# Choice of features



# Assumptions for Lines Regression

## 1. Linear relationship:

### 1. Little or no multi-collinearity:

- It is assumed that there is little or no multicollinearity in the data.
- Multicollinearity occurs when the features (or independent variables) are not independent of each other.

### 2. Little or no autocorrelation:

- Another assumption is that there is little or no autocorrelation in the data.
- Autocorrelation occurs when the residual errors are not independent of each other.

# Assumptions for LR

- **No outliers:**

- We assume that there are no outliers in the data. Outliers are data points that are far away from the rest of the data. Outliers can affect the results of the analysis.

- **Homoscedasticity:**

- Homoscedasticity describes a situation in which the error term (that is, the “noise” or random disturbance in the relationship between the independent variables and the dependent variable) is the same across all values of the independent variables.

