

A white humanoid robot with large blue eyes and a simple face is shown from the waist up. It wears a black graduation cap and holds a silver laptop in its right arm. The laptop screen displays a 3D wireframe diagram of a neural network architecture, specifically a convolutional neural network (CNN) with multiple layers and nodes. The robot's left hand rests on its hip.

# Classification

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## Motivations

# Classification

Question

Is this email spam?

Is the transaction fraudulent?

Is the tumor malignant? no yes

Answer " $y$ "

no yes

no yes

yes

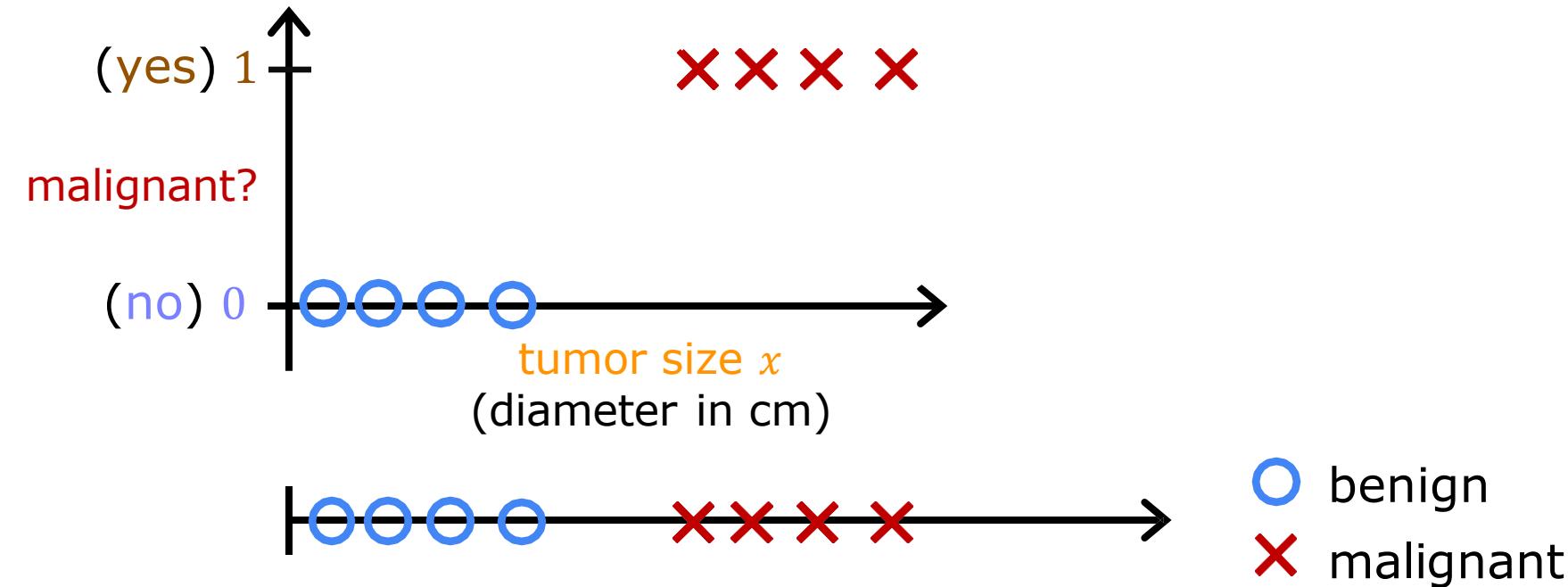
$y$  can only be one of two values

false true

0 1

"binary classification"

class = category

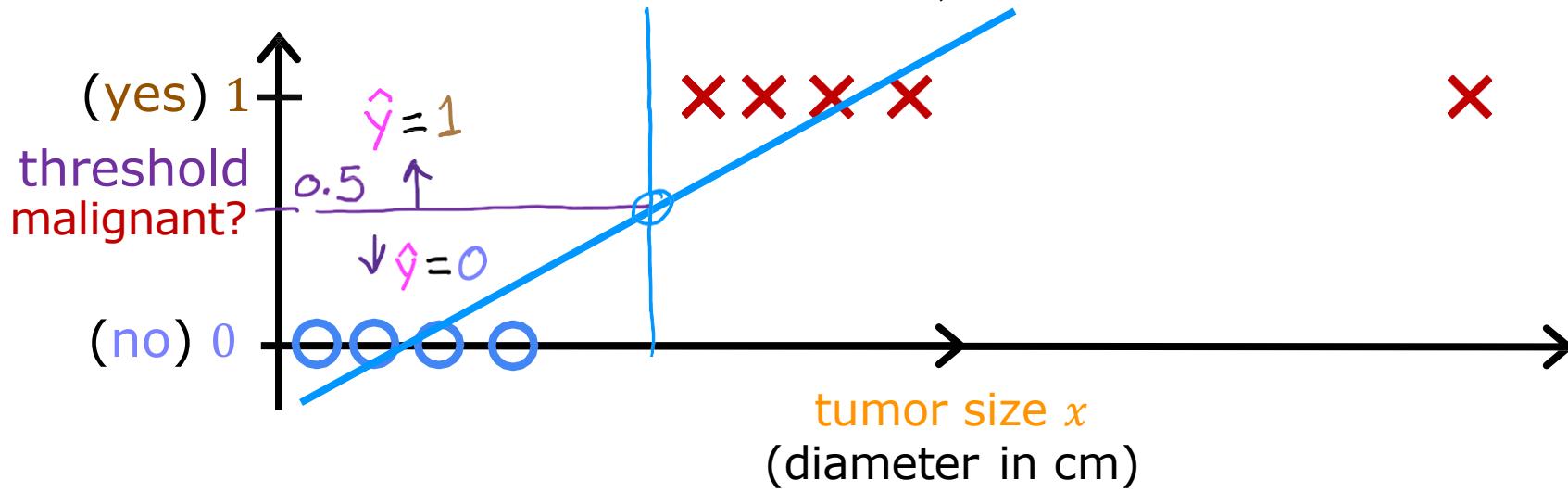


decision

boundary

$$f_{w,b}(x) = wx + b$$

$$f_{w,b}(x) = wx + b$$



if  $f_{w,b}( )$

$$x < 0.5 \rightarrow y = 0$$

if  $f_{w,b}( )$

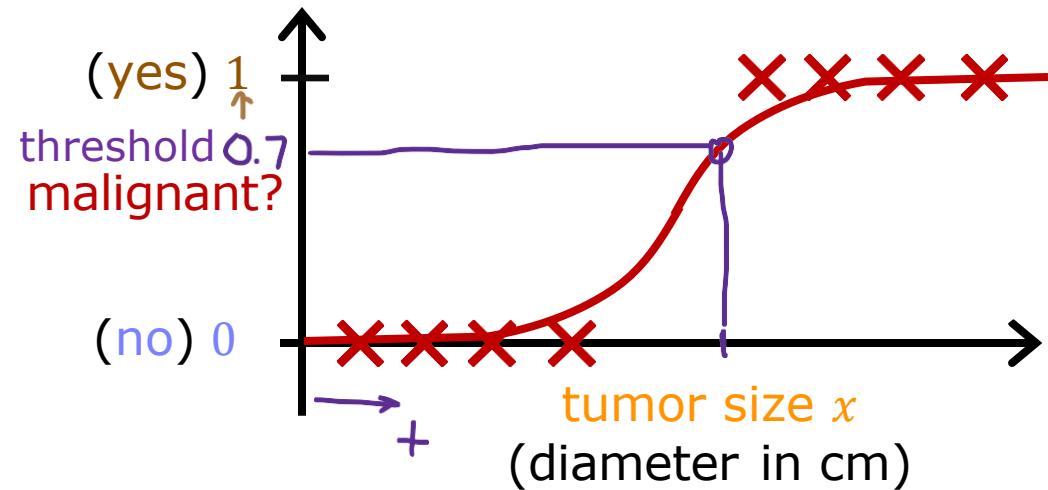
$$x \geq 0.5 \rightarrow \hat{y} = 1$$

A white humanoid robot with large blue eyes and a smiling mouth is wearing a black graduation cap. It is holding a silver laptop in its left arm and a white tablet in its right hand. The laptop screen shows a diagram of a neural network with multiple layers and arrows. The tablet screen shows a 3D perspective grid. The background is solid blue.

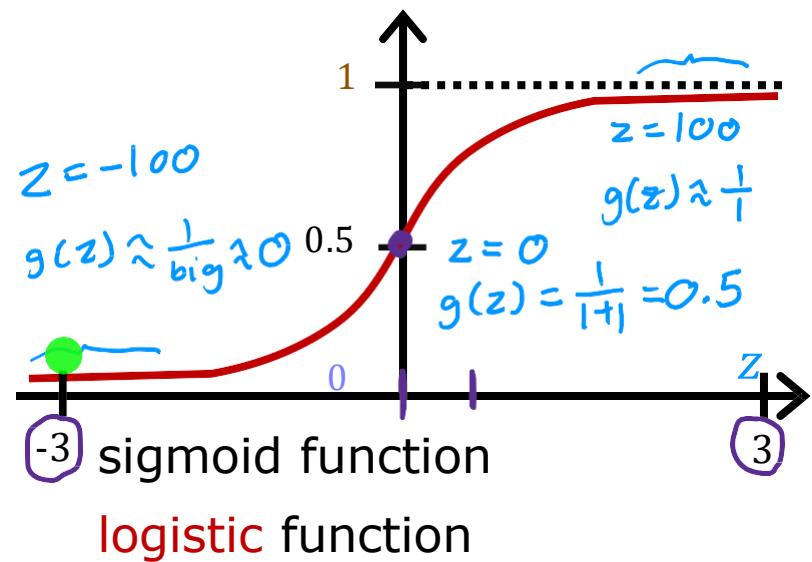
# Classification

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## Logistic Regression



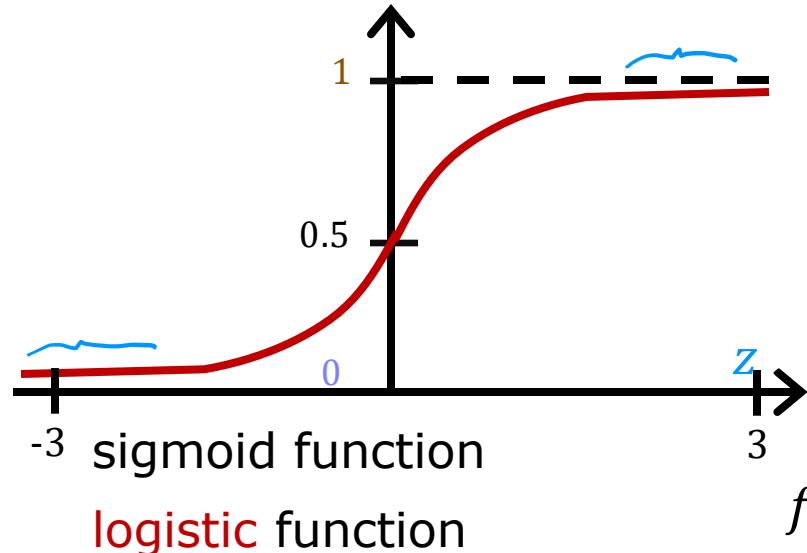
Want outputs between 0 and 1



outputs between 0 and 1

$$g(z) = \frac{1}{1+e^{-z}} \quad 0 < g(z) < 1$$

Want outputs between 0 and 1



outputs between 0 and 1

$$g(z) = \frac{1}{1+e^{-z}} \quad 0 < g(z) < 1$$

$$f_{\vec{w}, b}(\vec{x})$$

$$\vec{w} \cdot \vec{x} + b$$

$$\downarrow z$$

$$g(z) = \frac{1}{1+e^{-z}}$$

$$f_{\vec{w}, b}(\vec{x}) = g(\underbrace{\vec{w} \cdot \vec{x} + b}_z) = \frac{1}{1 + e^{-(\vec{w} \cdot \vec{x} + b)}}$$

"logistic regression"

1

$e \approx 2.7$

# Interpretation of logistic regression output

$$f_{\vec{w}, b}(\vec{x}) = \frac{1}{1 + e^{-(\vec{w} \cdot \vec{x} + b)}}$$

“probability” that class is 1

$$f_{\vec{w}, b}(\vec{x}) = P(y = 1 | \vec{x}; \vec{w}, b)$$

Probability that  $y$  is 1,  
given input  $\vec{x}$ , parameters  $\vec{w}, b$

Example:

$x$  is “tumor size”

$y$  is 0 (not malignant)  
or 1 (malignant)

$$P(y = 0) + P(y = 1) = 1$$

$$f_{\vec{w}, b}(\vec{x}) = 0.7$$

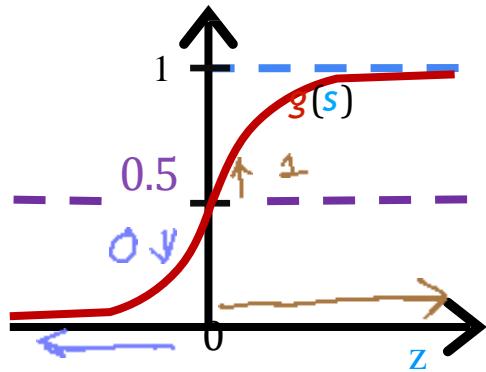
70% chance that  $y$  is 1

A white humanoid robot wearing a black graduation cap, holding a laptop displaying a neural network diagram, and a tablet showing a 3D grid.

# Classification

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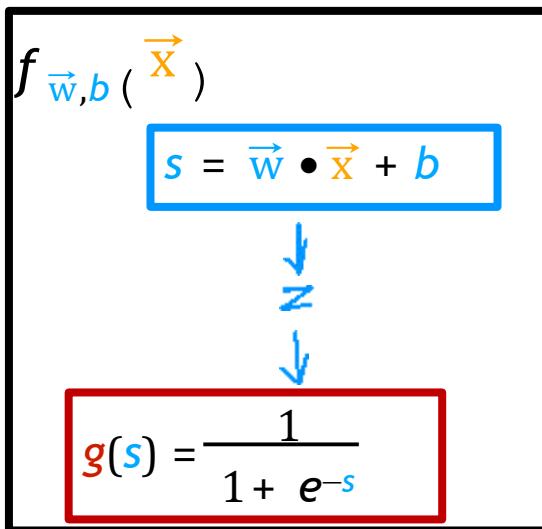
Decision Boundary



$$f_{\vec{w}, b}(\vec{x}) = \underbrace{g(\vec{w} \cdot \vec{x} + b)}_z \frac{1}{1 + e^{-(\vec{w} \cdot \vec{x} + b)}}$$

$$= P(y = 1 | x; \vec{w}, b) \quad 0.7 \quad 0.3$$

0 or 1? threshold



Is  $f_{\vec{w}, b}(\vec{x}) \geq 0.5$ ?

Yes:  $\hat{y} = 1$

No:  $\hat{y} = 0$

When is

$$f_{\vec{w}, b}(\vec{x}) \geq 0 \quad g(s) \geq 0.5$$

$$s \geq 0$$

$$\vec{w} \cdot \vec{x} + b \geq 0$$

$$\hat{y} = 1$$

$$\vec{w} \cdot \vec{x} + b < 0$$

$$\hat{y} = 0$$

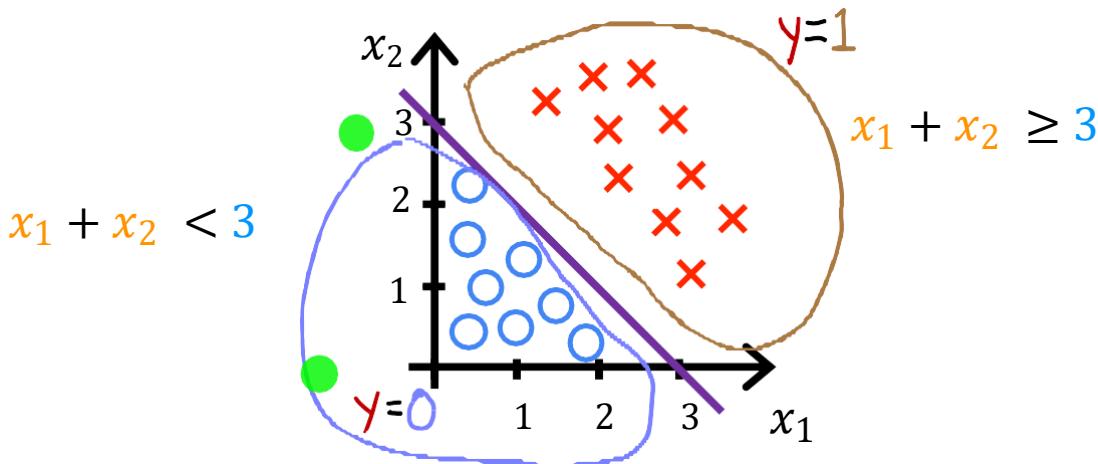
# Decision boundary

$$f_{\vec{w}, b}(\vec{x}) = g(z) = g(\underbrace{w_1 x_1 + w_2 x_2}_{1} + \underbrace{b}_{-3})$$

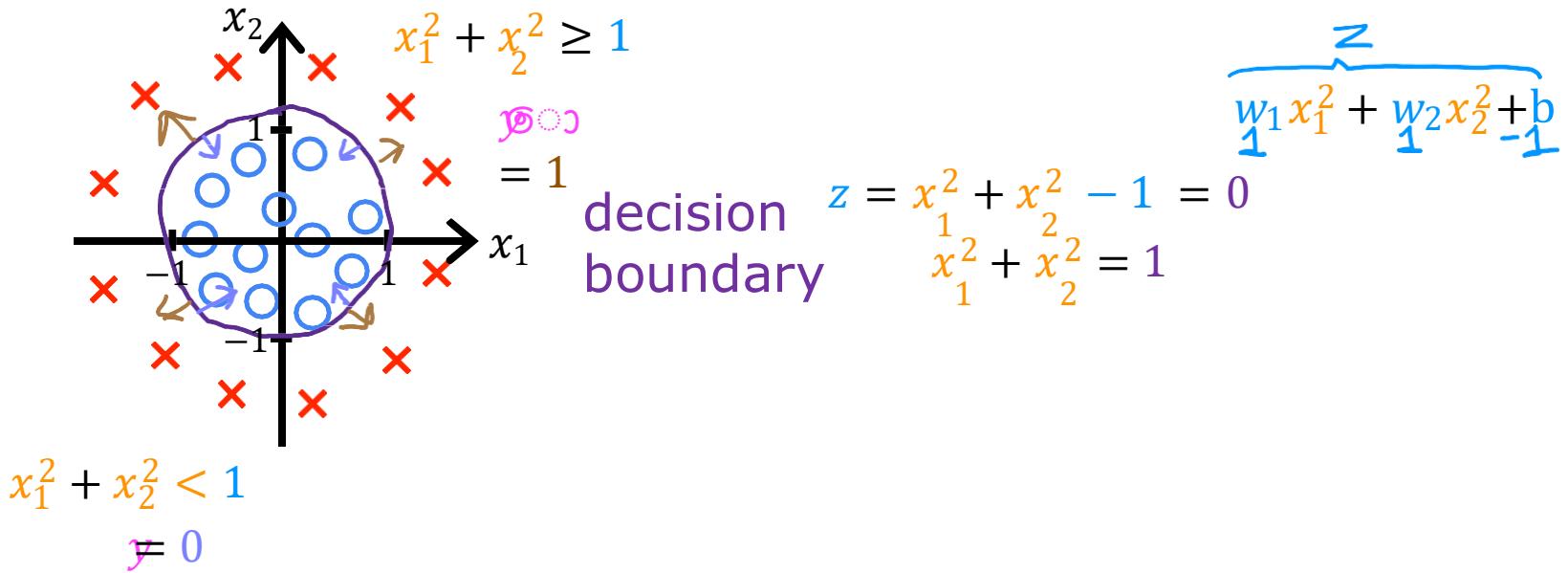
Decision boundary  $z = \vec{w} \cdot \vec{x} + b = 0$

$$z = x_1 + x_2 - 3 = 0$$

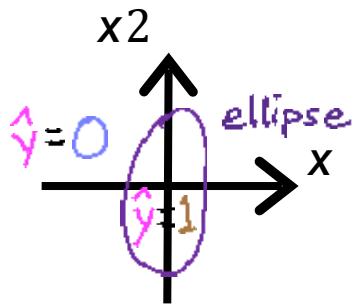
$$x_1 + x_2 = 3$$



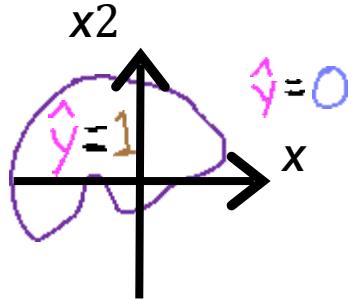
# Non-linear decision boundaries



# Non-linear decision boundaries



$$f_{\vec{w}, b}(\vec{x}) = g(s) = g(r_1 x_1 + r_2 x_2 + r_3 x_1^2 + r_4 x_1 x_2 + r_5 x_2^2 + r_6 x_1^3 + \dots + b)$$



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# Cost Function

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## Cost Function for Logistic Regression

# Training set

	tumor size (cm) $x_1$	...	patient's age $x_n$	malignant? $y$	$i = 1, \dots, m$ ↪ training examples
$i=1$	10		52	1	target $y$ is 0 or 1
:	2		73	0	
:	5		55	0	
$i=m$	12		49	1	
	...		...	...	

$$f_{\vec{w}, b}(\vec{x}) = \frac{1}{1 + e^{-(\vec{w} \cdot \vec{x} + b)}}$$

How to choose  $\vec{w} = [w_1 \ w_2 \ \cdots \ w_n]$  and  $b$ ?

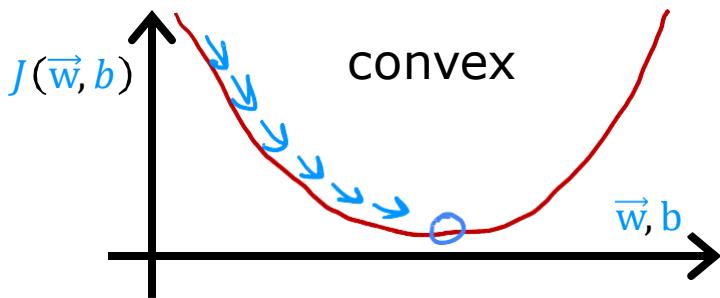
# Squared error cost

$$J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m \frac{1}{2} (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})^2 \quad \text{average of training set}$$

loss  $L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)})$

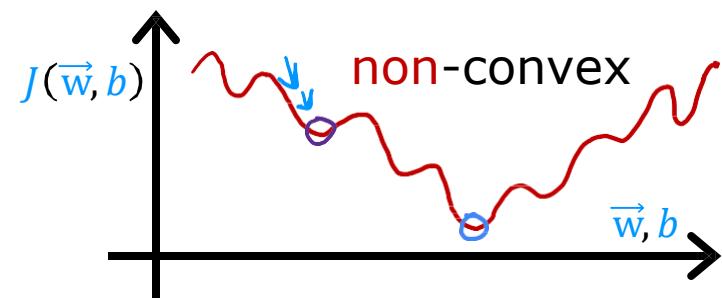
linear regression

$$f_{\vec{w}, b}(\vec{x}) = \vec{w} \cdot \vec{x} + b$$



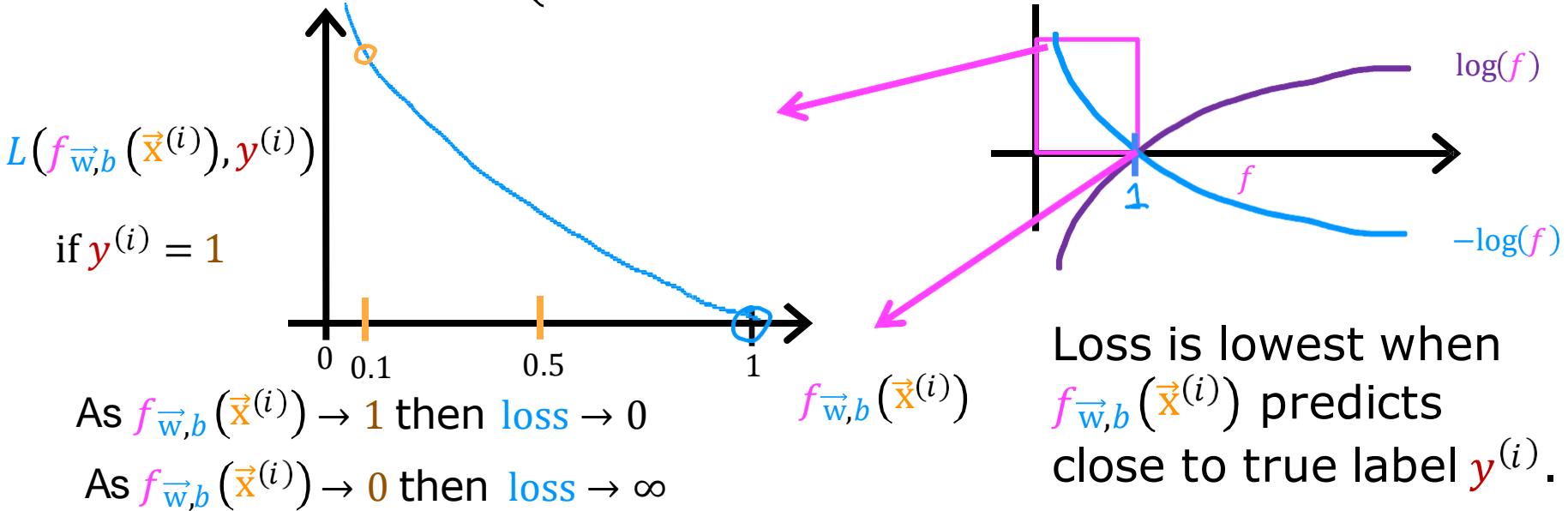
logistic regression

$$f_{\vec{w}, b}(\vec{x}) = \frac{1}{1 + e^{-(\vec{w} \cdot \vec{x} + b)}}$$



# Logistic loss function

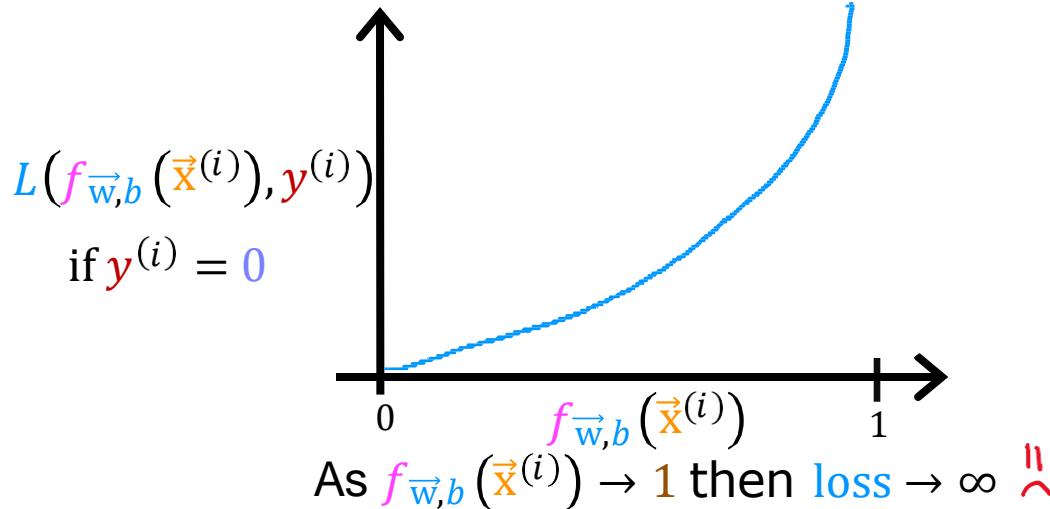
$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = \begin{cases} -\log(f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 1 \\ -\log(1 - f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$



# Logistic loss function

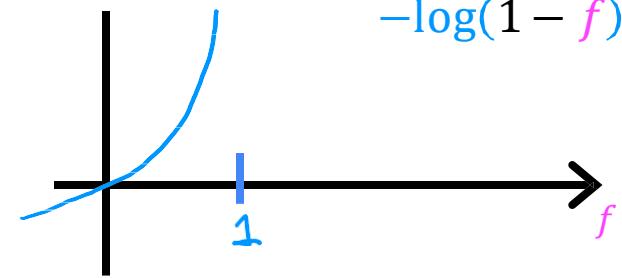
$$L(f_{\vec{w},b}(\vec{x}^{(i)}), y^{(i)}) = \begin{cases} -\log(f_{\vec{w},b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 1 \\ -\log(1 - f_{\vec{w},b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$

As  $f_{\vec{w},b}(\vec{x}^{(i)}) \rightarrow 0$  then loss  $\rightarrow 0$  



if  $y^{(i)} = 0$

As  $f_{\vec{w},b}(\vec{x}^{(i)}) \rightarrow 1$  then loss  $\rightarrow \infty$  



The further prediction  $f_{\vec{w},b}(\vec{x}^{(i)})$  is from target  $y^{(i)}$ , the higher the loss.

# Cost

$$J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m \underbrace{L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)})}_{\text{loss}}$$

$$\rightarrow = \begin{cases} -\log(f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 1 \\ -\log(1 - f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$

*convex  
can reach a global minimum*

find  $w, b$  that minimize cost  $J$

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# Cost Function

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Simplified Cost  
Function for Logistic  
Regression

# Simplified loss function

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = \begin{cases} -\log(f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 1 \\ -\log(1 - f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = -y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) - (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))$$

if  $y^{(i)} = 1$ :

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = \underbrace{-1 \log(f(x))}_{\Theta} \quad \frac{1}{(1 - |)}$$

# Simplified loss function

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = \begin{cases} -\log(f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 1 \\ -\log(1 - f_{\vec{w}, b}(\vec{x}^{(i)})) & \text{if } y^{(i)} = 0 \end{cases}$$

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = -y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) - (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))$$

if  $y^{(i)} = 1$ :

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = -1 \log(f(\vec{x}))$$

if  $y^{(i)} = 0$ :

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) =$$

# Simplified cost function

*loss*

$$L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)}) = -y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) - (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))$$

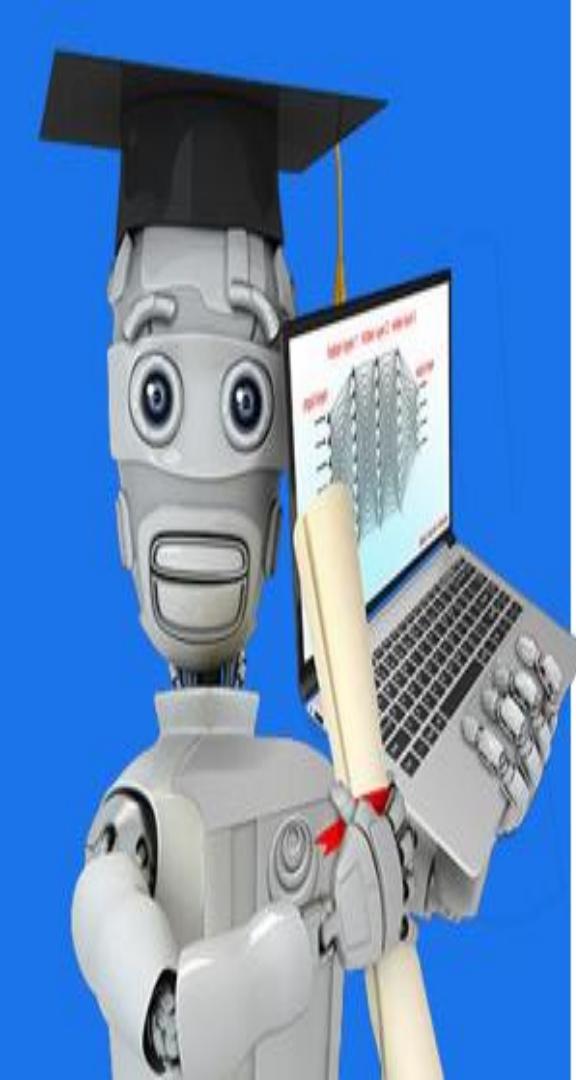
*cost*

$$J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m [L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)})]$$

↑ convex  
(single global minimum)

$$= -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) + (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))]$$

maximum likelihood

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# Gradient Descent

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## Gradient Descent Implementation

# Training logistic regression

Find  $\vec{w}, b$

Given new  $\vec{x}$ , output  $f_{\vec{w}, b}(\vec{x}) = \frac{1}{1+e^{-(\vec{w} \cdot \vec{x} + b)}}$

$$P(y=1|\vec{x}; \vec{w}, b)$$

# Gradient descent

$$J(\vec{w}, b) = -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) + (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))]$$

repeat {

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(w, b)$$

$$b = b - \alpha \frac{\partial}{\partial b} J(w, b)$$

} simultaneous updates

$$\frac{\partial}{\partial w_j} J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)} x^{(i)}$$

$$\frac{\partial}{\partial b} J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

# Gradient descent for logistic regression

repeat {

looks like linear regression!

$$w_j = w_j - \alpha \left[ \frac{1}{m} \sum_{i=1}^m (\mathbf{f}_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) \mathbf{x}^{(i)} \right]$$

$$b = b - \alpha \left[ \frac{1}{m} \sum_{i=1}^m (\mathbf{f}_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) \right]$$

} simultaneous updates

- Same concepts:
- Monitor gradient descent (learning curve)
  - Vectorized implementation
  - Feature scaling

Linear regression       $f_{\vec{w}, b}(\vec{x}) = \vec{w} \cdot \vec{x} + b$

Logistic regression       $\mathbf{f}_{\vec{w}, b}(\vec{x}) = \frac{1}{1 + e^{(-\vec{w} \cdot \vec{x} + b)}}$

Logistic regression hypothesis:

$$h_{\theta}(x) = g(\theta^T x)$$

$$g(z) = \frac{1}{1 + e^{-z}}$$

Cost function in logistic regression is:

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m [y^i \log(h_{\theta}(x^i)) + (1 - y^i) \log(1 - h_{\theta}(x^i))]$$

Vectorized implementation:

$$h = g(X\theta)$$

$$J(\theta) = \frac{1}{m} (-y^T \log(h) - (1 - y)^T \log(1 - h))$$

The gradient of the cost is a vector of the same length as  $\theta$  where  $j^{th}$  element (for  $j = 0, 1, \dots, n$ ) is defined as follows:

$$\nabla J(\theta) = \frac{1}{m} \sum_{i=1}^m ((h_{\theta}(x^i) - y^i) \cdot x_j^i)$$

# **Newton's Method for parameter optimization:**

**Advantages :**

**Fast Convergence:** Newton's method converges faster than gradient descent, especially for convex and well-behaved functions.

It typically achieves **quadratic convergence** near the optimum, meaning the error shrinks exponentially with each iteration.

**Adaptability to Curvature:** By using the Hessian, Newton's method adjusts the step size based on the curvature of the function, preventing overshooting or undershooting the minimum.

**Precise Steps:** The inclusion of second-order information allows for more precise updates, especially in regions where the function's curvature changes rapidly.

# Newton's Method for Parameter Optimization:

- **Hessian Calculation:** Computing the Hessian matrix can be expensive, especially for functions with many parameters (large-scale optimization problems).  
The Hessian is an  $n \times n$  matrix, where  $n$  is the number of parameters.
- **Hessian Inversion:** Newton's method requires inverting the Hessian matrix, which can be computationally expensive and numerically unstable if the Hessian is not well-conditioned (i.e., close to singular, i.e. eigenvalues are very small, or the determinant is close to zero).
- **Local Minimum:** Like gradient descent, Newton's method can get stuck in local minima if the function is not convex

# Modified or Truncated Newton Methods

- Due to the computational cost of calculating and inverting the Hessian matrix, several modified versions of Newton's method are commonly used in practice.
- These methods make Newton's method more efficient for large-scale problems.

## Quasi-Newton Methods:

- Instead of calculating the Hessian matrix explicitly, quasi-Newton methods approximate the Hessian using only first-order information (gradients).
- **BFGS (Broyden-Fletcher-Goldfarb-Shanno)** and **L-BFGS (Limited-memory BFGS)** are popular quasi-Newton methods.
  - They approximate the Hessian based on gradient evaluations, making them much more efficient for large problems.

## Truncated Newton (TNC):

- TNC uses a **conjugate gradient approach** to solve the optimization problem. It only computes an approximation of the Hessian and "truncates" the step when necessary to avoid going too far or using too much computational effort.

- This makes it more scalable for large problems while maintaining the benefits of second-order methods.

- For machine learning applications, Newton's methods are often used in training models like **logistic regression**, where the optimization problem involves minimizing a log-likelihood function.
- In these cases, algorithms like **BFGS** or **TNC** are used for efficient optimization especially in large-scale optimization.

# Summary of Solvers in Scikit-learn Logistic Regression

Solver	Type	Key Characteristics	Use Case
lbfgs	Quasi-Newton	Efficient for large datasets, default solver	Binary and multinomial classification
newton-cg	Newton-based	High precision, better for multinomial problems	Multinomial logistic regression
sag	Gradient descent	Efficient for large datasets, supports L2 regularization	Large datasets with L2 regularization
saga	Gradient descent	Supports L1, L2, and elastic net regularization	Large datasets, sparse data, high-dimensional problems
liblinear	Coordinate descent	Good for small datasets, L1/L2 regularization	Binary classification, L1 regularization

A white humanoid robot with large blue eyes and a black graduation cap is standing on the left side of the slide. It is holding a yellow rolled-up diploma in its right arm and a silver laptop in its left hand. The laptop screen shows a 3D diagram of a neural network with multiple layers and arrows indicating data flow. The background behind the robot is a solid blue.

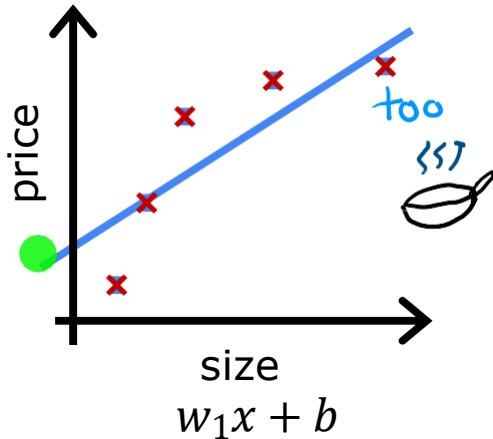
# Regularization to Reduce Overfitting

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The Problem of  
Overfitting



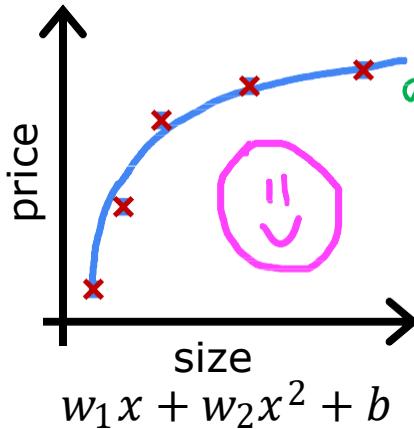
# Regression example



Under fit

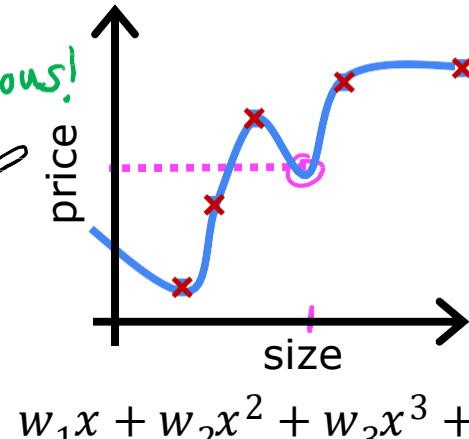
- Does not fit the training set well

high bias



- Fits training set pretty well

generalization

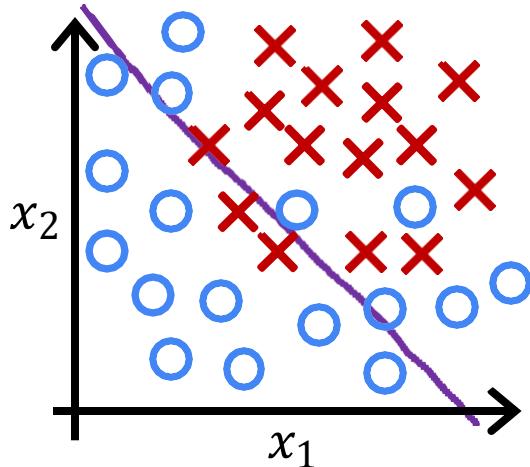


overfit

- Fits the training set extremely well

High variance

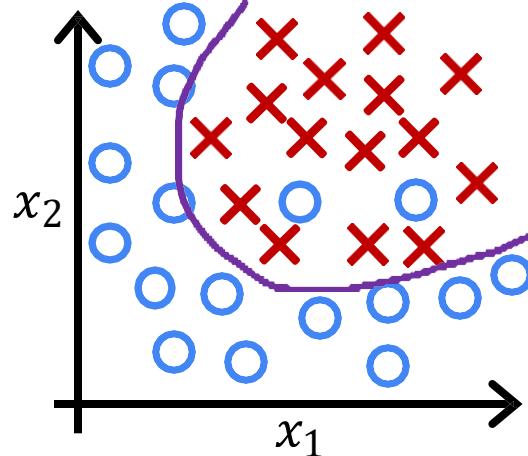
# Classification



$$z = w_1x_1 + w_2x_2 + b$$

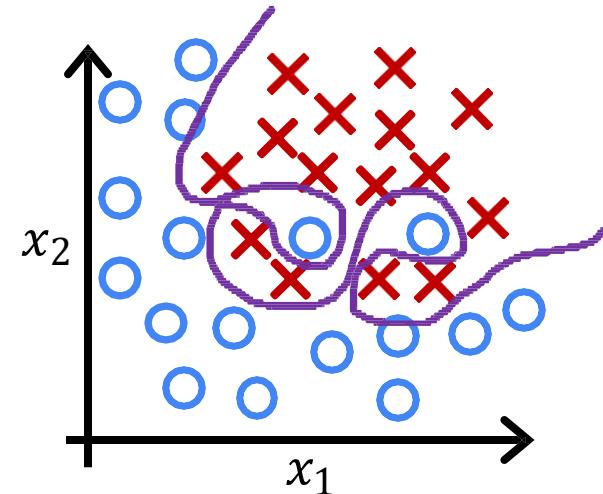
$$f_{\vec{w}, b}(\vec{x}) = g(z)$$

$g$  is the sigmoid function  
underfit      high bias



$$\begin{aligned} z = & w_1x_1 + w_2x_2 \\ & + w_3x_1^2 + w_4x_2^2 \\ & + w_5x_1x_2 + b \end{aligned}$$

just right



$$\begin{aligned} z = & w_1x_1 + w_2x_2 \\ & + w_3x_1^2x_2 + w_4x_1^2x_2^2 \\ & + w_5x_1^2x_2^3 + w_6x_1^3x_2 \\ & + \dots + b \end{aligned}$$

Overfit

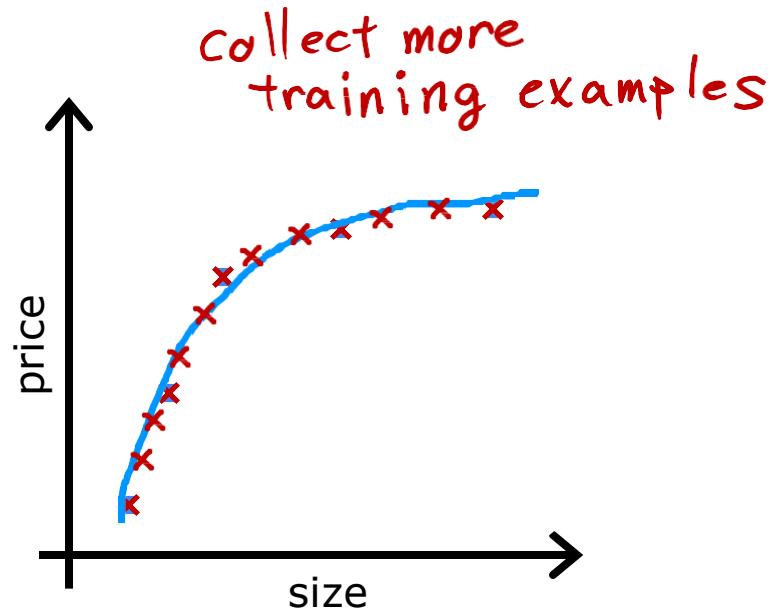
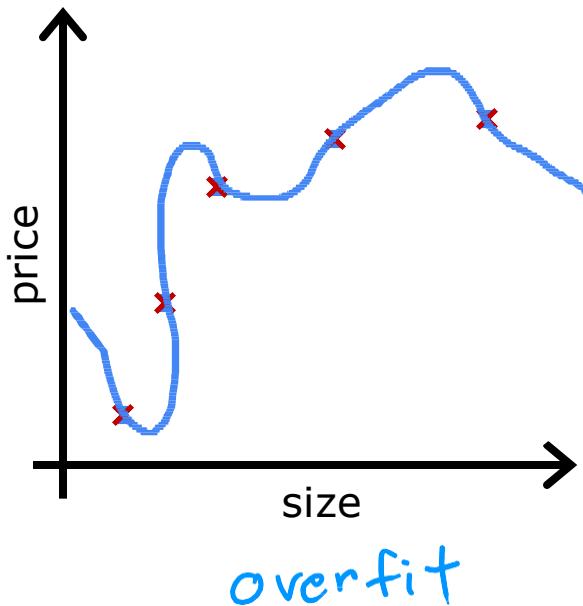
A white humanoid robot with large blue eyes and a simple face is shown from the waist up. It wears a black graduation cap and holds a silver laptop in its left arm. A yellow rolled-up diploma or certificate is tucked under the laptop's keyboard. The robot's right hand is visible at the bottom left, showing a red circular sensor or button. The background is a solid blue.

# Regularization to Reduce Overfitting

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## Addressing Overfitting

# Collect more training examples



# Select features to include/exclude

size	bedrooms	floors	age	avg income	...	distance to coffee shop	price
$x_1$	$x_2$	$x_3$	$x_4$	$x_5$		$x_{100}$	$y$

## all features



## insufficient data



## overfit

## selected features

size  
bedrooms  
age  
just right  
feature

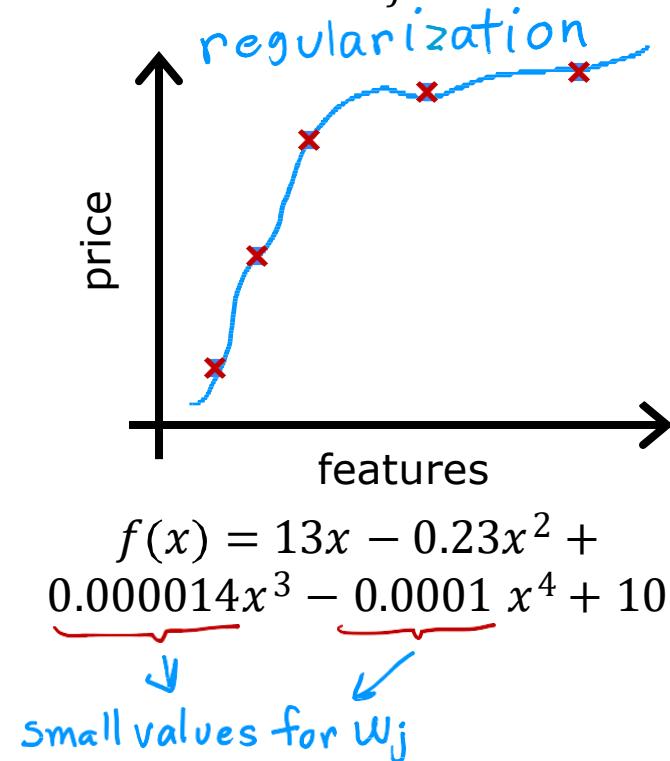
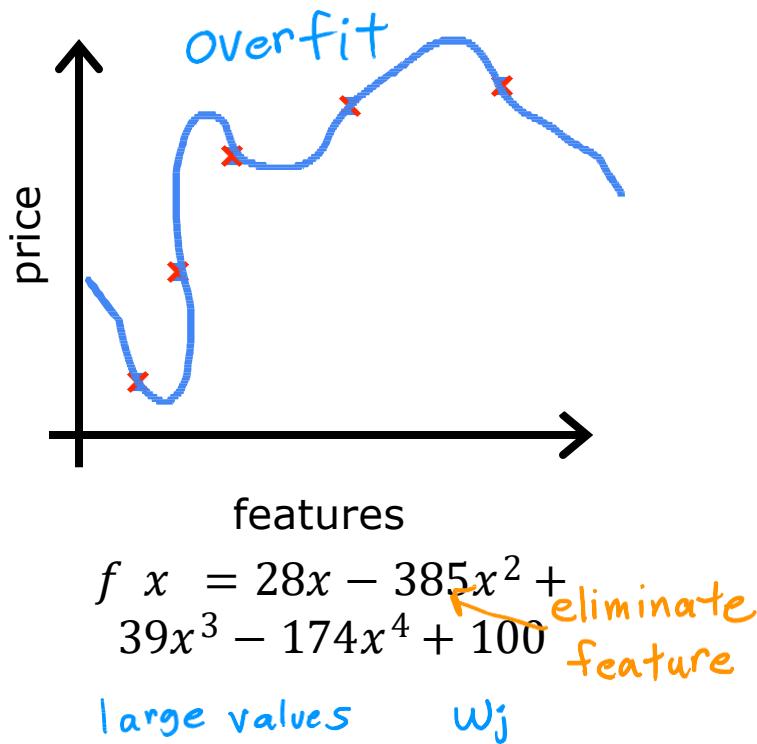
## disadvantage



## useful features could be lost

# Regularization

Reduce the size of parameters  $w_j$



# Addressing overfitting

## Options

1. Collect more data
2. Select features
  - Feature selection
3. Reduce size of parameters
  - “Regularization”

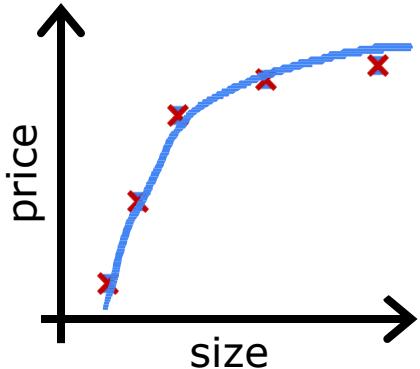
A white humanoid robot with large blue eyes and a simple face is shown from the waist up. It wears a black academic mortarboard. In its left arm, it holds a silver laptop open. The laptop screen displays a 3D diagram of a neural network with multiple layers of nodes. The robot's right hand rests on its hip.

# Regularization to Reduce Overfitting

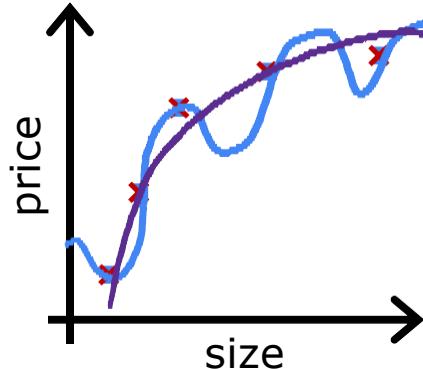
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## Cost Function with Regularization

# Intuition



$$w_1x + w_2x^2 + b$$



$$w_1x + w_2x^2 + \underbrace{w_3x^3}_{\approx 0} + \underbrace{w_4x^4}_{\approx 0} + b$$

make  $w_3, w_4$  really small ( $\approx 0$ )

$$\min_{w,b} \frac{1}{2m} \sum_{i=1}^m \left( f_{\vec{w},b}(\vec{x}^{(i)}) - y^{(i)} \right)^2 + 1000 \underbrace{w_3^2}_{0.001} + 1000 \underbrace{w_4^2}_{0.002}$$

# Regularization

small values  $w_1, w_2, \dots, w_n, b$

simpler model

$$w_3 \approx 0$$

less likely to overfit

$$w_4 \approx 0$$

size	bedrooms	floors	age	avg income	...	distance to coffee shop	price
$x_1$	$x_2$	$x_3$	$x_4$	$x_5$		$x_{100}$	$y$

$w_1, w_2, \dots, w_{100}, b$       *n features*       $n = 100$

$$J(\vec{w}, b) = \frac{1}{2m} \left[ \sum_{i=1}^m \left( f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)} \right)^2 + \underbrace{\frac{\lambda}{2m} \sum_{j=1}^n w_j^2}_{\text{"lambda"} \quad \text{regularization parameter}} + \underbrace{\frac{\lambda}{2m} b^2}_{\lambda > 0} \right]$$

regularization term

can include or exclude  $b$

# Regularization

$$\min_{\vec{w}, b} J(\vec{w}, b) = \min_{\vec{w}, b} \left[ \underbrace{\frac{1}{2m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})^2}_{\text{mean squared error}} + \underbrace{\frac{\lambda}{2m} \sum_{j=1}^n w_j^2}_{\text{regularization term}} \right]$$

fit data

Keep  $w_j$  small

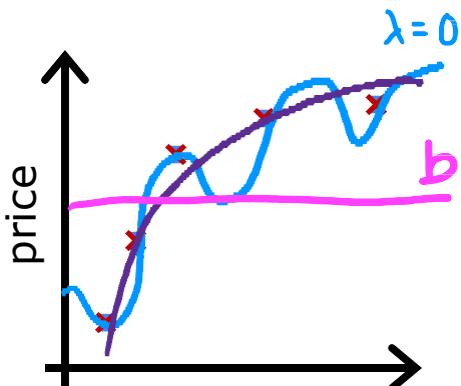
$\lambda$  balances both goals

choose  $\lambda = 10^{10}$

$$f_{\vec{w}, b}(\vec{x}) = \underbrace{w_1 x}_\approx + \underbrace{w_2 x^2}_\approx + \underbrace{w_3 x^3}_\approx + \underbrace{w_4 x^4}_\approx + b$$

$$f(x) = b$$

Choose  $\lambda$



A white humanoid robot with large blue eyes and a simple face is shown from the waist up. It wears a black academic mortarboard. In its right arm, it holds a silver laptop open. The laptop screen displays a 3D diagram of a neural network with multiple layers of nodes. The robot's left hand rests on its hip.

# Regularization to Reduce Overfitting

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## Regularized Linear Regression

# Regularized linear regression

$$\min_{\vec{w}, b} J(\vec{w}, b) = \min_{\vec{w}, b} \left[ \frac{1}{2m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})^2 + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2 \right]$$

Gradient descent

repeat {

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\vec{w}, b)$$

$\downarrow$

$$= \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} w_j$$

$\downarrow$

$$b = b - \alpha \frac{\partial}{\partial b} J(\vec{w}, b)$$

$\downarrow$

$$= \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

} simultaneous update

# Implementing gradient descent

repeat {

$$w_j = \textcolor{blue}{w}_j - \alpha \left[ \frac{1}{m} \sum_{i=1}^{\textcolor{blue}{m}} \left[ (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) \textcolor{orange}{x}_j^{(i)} \right] + \frac{\lambda}{m} \textcolor{blue}{w}_j \right]$$

$$b = \textcolor{blue}{b} - \alpha \frac{1}{m} \sum_{i=1}^{\textcolor{blue}{m}} (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

} simultaneous update  $j = 1 \dots n$

# Implementing gradient descent

repeat {

$$w_j = w_j - \alpha \left[ \frac{1}{m} \sum_{i=1}^m \left[ (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} \right] + \frac{\lambda}{m} w_j \right]$$

$$b = b - \alpha \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

} simultaneous update  $j = 1 \dots n$

$$w_j = \underbrace{w_j - \alpha \frac{\lambda}{m} w_j}_{w_j \left( 1 - \alpha \frac{\lambda}{m} \right)} - \underbrace{\alpha \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)}}_{\text{usual update}}$$

shrink  $w_j$

$$\alpha \frac{\lambda}{m}$$
$$0.01 \frac{1}{50} = 0.0002$$
$$w_j \left( 1 - 0.0002 \right)$$
$$0.9998$$

# How we get the derivative term (optional)

$$\begin{aligned}\frac{\partial}{\partial w} J(\vec{w}, b) &= \frac{\partial}{\partial w_j} \left[ \frac{1}{2m} \sum_{i=1}^m \underbrace{\left( f(\vec{x}^{(i)}) - y^{(i)} \right)^2}_{\vec{w} \cdot \vec{x}^{(i)} + b} + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2 \right] \\ &= \frac{1}{2m} \sum_{i=1}^m \left[ (\vec{w} \cdot \vec{x}^{(i)} + b - y^{(i)}) \cancel{x_j^{(i)}} \right] + \frac{\lambda}{2m} \cancel{\sum_{j=1}^n w_j} \quad \text{No } \sum_{j=1}^n \\ &= \frac{1}{m} \sum_{i=1}^m \left[ \underbrace{(\vec{w} \cdot \vec{x}^{(i)} + b - y^{(i)})}_{f(\vec{x})} x_j^{(i)} \right] + \frac{\lambda}{m} w_j \\ &= \frac{1}{m} \sum_{i=1}^m \left[ (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} \right] + \frac{\lambda}{m} w_j\end{aligned}$$

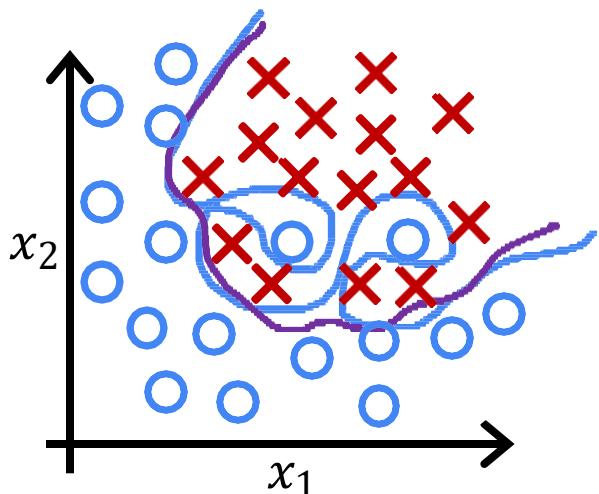
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# Regularization to Reduce Overfitting

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## Regularized Logistic Regression

# Regularized logistic regression



$$z = w_1x_1 + w_2x_2 + w_3x_1^2x_2 + w_4x_1^2x_2^2 + w_5x_1^2x_2^3 + \dots + b$$
$$f_{\vec{w}, b}(\vec{x}) = \frac{1}{1 + e^{-z}}$$

Cost function

$$J(\vec{w}, b) = -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) + (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))] + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2$$

$\min_{\vec{w}, b} J(\vec{w}, b) \rightarrow w_j \downarrow$



# Regularized logistic regression

$$J(\vec{w}, b) = -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log(f_{\vec{w}, b}(\vec{x}^{(i)})) + (1 - y^{(i)}) \log(1 - f_{\vec{w}, b}(\vec{x}^{(i)}))] + \frac{\lambda}{2m} \sum_{j=1}^n w_j^2$$
$$\min_{\vec{w}, b}$$

## Gradient descent

repeat {

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\vec{w}, b)$$

j = 1 ... n

$$b = b - \alpha \frac{\partial}{\partial b} J(\vec{w}, b)$$

}

$$= \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} w_j$$

logistic regression

$$= \frac{1}{m} \sum_{i=1}^m (f_{\vec{w}, b}(\vec{x}^{(i)}) - y^{(i)})$$

don't have to regularize b