

1. Check all the problem(s) that admit sparse solution(s):

1 point

- ☒ $\min_{\mathbf{x}} \|\mathbf{x}\|_1 \text{ subject to } A\mathbf{x} = \mathbf{b}$
- ☐ $\min_{\mathbf{x}} \|\mathbf{x}\|_2 \text{ subject to } A\mathbf{x} = \mathbf{b}$
- ☒ $\min_{\mathbf{x}} \|\mathbf{x}\|_0 \text{ subject to } A\mathbf{x} = \mathbf{b}$
- ☒ $\min_{\mathbf{x}} \|\mathbf{x}\|_p \text{ subject to } A\mathbf{x} = \mathbf{b}$ (p is between 0 and 1)

2. Natural image patches (unlike random noise) cannot be sparsely represented over a DCT dictionary.

1 point

- ☐ True
- ☒ False

3. In video surveillance applications, background is modeled as a _____ matrix and moving parts are modeled via a _____ matrix.

1 point

- ☐ sparse, low-rank
- ☐ low-rank, low-rank
- ☐ sparse, sparse
- ☒ low-rank, sparse

4. Which one of the greedy algorithms discussed in class is designed to solve the following problem?

1 point

$$\min_{A, X} \|AX - B\|_F$$
$$\text{subject to } \|X(:, i)\|_0 \leq k \forall i$$

- ☐ Matching Pursuit
- ☒ Method of Optimal Directions
- ☐ This problem has a closed form solution and hence doesn't need to be solved in a greedy fashion.
- ☐ Orthogonal Matching Pursuit

5. Check all the norms that are convex functions.

1 point

- ☐ The L0 norm ($f(\mathbf{x}) = \|\mathbf{x}\|_0$)
- ☒ The L1 norm ($f(\mathbf{x}) = \|\mathbf{x}\|_1$)
- ☐ The Lp norm ($f(\mathbf{x}) = \|\mathbf{x}\|_p$ where p is between 0 and 1.
- ☒ The L2 norm ($f(\mathbf{x}) = \|\mathbf{x}\|_2$)

6. Which one of the following statements is true regarding the basis pursuit problem given by

$$\mathbf{x}^* = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{x}\|_1 \quad \text{subject to } \mathbf{A}\mathbf{x} = \mathbf{b}?$$

- ☐ If one of the columns in \mathbf{A} is identical to $\mathbf{b} \neq \mathbf{0}$, then $\|\mathbf{x}^*\|_1 = 1$.
- ☐ If $\mathbf{b} = \mathbf{0}$ and \mathbf{A} is full rank, then the problem has no solution since the constraint set becomes empty.
- ☐ \mathbf{x}^* also minimizes the corresponding LASSO problem given by $\min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2 + \lambda \|\mathbf{x}\|_1$.
- ☒ none of the above.

1 point

7. The singular value decomposition of the $n \times n$ square matrix \mathbf{A} is given by $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$. Check all correct statements.

- ☐ The nuclear norm of \mathbf{A} (given by the sum of absolute values of entries on the diagonal of $\mathbf{\Sigma}$) is an upper bound on the rank of \mathbf{A} .
- ☒ If $\mathbf{\Sigma}$ has only one non-zero entry, then \mathbf{A} is definitely a rank-1 matrix.
- ☐ Only square matrices (such as \mathbf{A}) have singular value decomposition.
- ☒ Matrices \mathbf{U} and \mathbf{V} are orthonormal bases for the n -dimensional space.

1 point

8. In this MATLAB assignment you will code-up the orthogonal matching pursuit (OMP) algorithm, as discussed in the lecture, to solve the following optimization problem:

$$\min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2 \quad \text{subject to } \|\mathbf{x}\|_0 \leq S.$$

1 point

In this exercise $\mathbf{A} = \mathbf{D} + \mathbf{I}$, where $D_{ij} = \sin(i + j)$ for $1 \leq i, j \leq 10$ and \mathbf{I} is the 10×10 identity matrix. Use \mathbf{A} along with $\mathbf{b} = [-2, -6, -9, 1, 8, 10, 1, -9, -4, -3]^T$, and $S = 3$ to find the solution to the problem given above.

Your solution \mathbf{x}^* uses three columns of \mathbf{A} in order to approximate \mathbf{b} . Type in the sum of the indices of these three columns. For example, if you find that your solution uses the first, third, and fifth columns of \mathbf{A} then you must enter 9. (Hint: `normc(A)` normalizes the columns of \mathbf{A} to a length of 1 in MATLAB.)

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