HW5

白博臣,何骐多,夏营

1 section1

牛顿迭代法是一种经典的求解函数根的方法,它是一种迭代方法。其思想为沿着当地的切线方向不断移动计算点,使其不断逼近真实根值。假设初始值为 x_k ,函数为 f(x),则

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

其下一步预测的根就是 x_{k+1} 。然后逐次迭代,x值会越来越接近真实的根植。本题目中 $f=z^3-1$,其牛顿迭代求根的迭代方程为

$$x_{k+1} = x_k - \frac{x_k^3 - 1}{3x_k^2}$$

该方程有三个根,其实部与虚部都在[-2,2]区间内:

我们使用 Matlab 进行相关运算处理:

使用 parfor 循环来实现并行计算。parfor 循环是 MATLAB 中用于并行计算的一种机制,它会自动将循环迭代分配到多个处理器上并行执行,从而加速计算过程。

在循环内部,每次迭代都是独立的,不涉及对前一次迭代结果的依赖,这样可以确保并行计算的正确 性。

GPU 加速运算:

首先,需要将数据移动到 GPU 上进行计算。在代码中,使用 gpuArray 函数将复数网格 X 的一行数据 (X(i,:)) 移动到 GPU 上,以便后续在 GPU 上进行计算。

然后,利用 GPU 提供的并行计算能力,通过调用 arrayfun 函数对每个网格点进行计算。arrayfun 函数可以将一个函数应用到数组中的每个元素,并在 GPU 上并行执行这些函数调用,从而加速计算过程。

在这里, solve 函数被应用到 GPU 上的每个网格点上,以计算方程的解。

计算完成后,使用 gather 函数将计算结果从 GPU 移回 CPU,以便后续处理和可视化。

通过以上步骤,实现了在 GPU 上并行计算复平面上方程的根,大大加速了计算过程。

使用 Matlab 代码实现如下

```
1 clc; clear; close all;
2 N = 20000;
3 epsilon = 1e-3;
4 root1 = 1;
5 root2 = -1 / 2 + sqrt(3)/2i;
6 root3 = -1 / 2 - sqrt(3)/2i;
7 x = linspace(-2, 2, N);
8 y = linspace(-2, 2, N);
```

1 SECTION1 2

```
9 [xgrid, ygrid] = meshgrid(x, y);
10 X = xgrid + 1i*ygrid;
11
12 % 使用parfor循环并在循环内部利用GPU加速的函数
13 A = zeros(N);
14 tic; % 开始计时
15 parfor i = 1:N
      %将数据移动到GPU
       X_gpu = gpuArray(X(i, :));
18
     % 在每次迭代中,利用GPU加速计算结果
19
     A_gpu = arrayfun(@solve, X_gpu);
^{21}
22
     %将计算结果从GPU移回CPU
       A(i, :) = gather(A_gpu);
^{24}
25 end
26
27 % 对计算结果进行处理
28 A(abs(A - root1) < epsilon) = 0;
29 A(abs(A - root2) < epsilon) = 1;
30 A(abs(A - root3) < epsilon) = 2;
31
32
33 %绘制图像
34 % fig = figure('color',[1 1 1], 'position', [400,100,500*1.5,416*1.5], 'Visible', 'off');
35 % contourf(x, y, A, 'LineStyle', 'none');
36 % clim([0, 2])
37 % colormap("cool")
38 % colorbar;
39 % saveas(fig, 'plot.png');
40
41 toc;
43 % writematrix(A, "result.txt")
44
```

运行结果如下

1 SECTION1 3

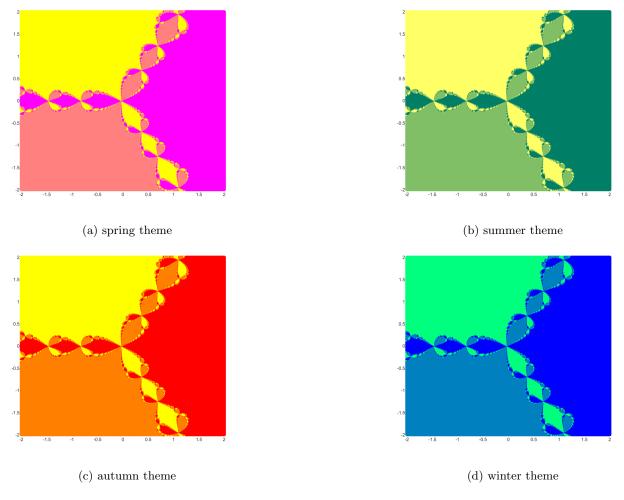


图 1: NB 运行结果

2 Problem2

利用 Desmos 作图 利用 NR-Bisection 求解方程 $4\cos(x) - e^x = 0$, 使用 Java 代码实现如下

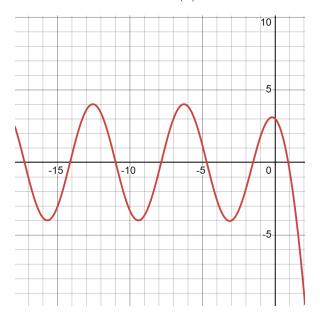


图 2: 函数图像绘制

```
* This class demonstrates the numerical methods of finding roots using a combination of NR and
        \hookrightarrow Bisection methods.
3
   import java.util.Scanner;
   import static java.lang.StrictMath.*;
   public class NRBisection {
       static double epsilon = 1e-10;
11
       public static void main(String[] args) {
12
13
           Scanner scanner = new Scanner(System.in);
14
           System.out.println("Enter the lower bound");
15
           double xl = scanner.nextDouble();
16
           System.out.println("Enter the upper bound");
17
           double xu = scanner.nextDouble();
18
           int num = 100;
19
           int n = (int) ((xu - xl) * num);
20
21
           System.out.printf("In \%.3f to \%.3f, there are rootsn", x1, xu);
22
           for (int i = 0; i <= n; i++) {</pre>
                double x1 = xl + (double) i / num;
24
                double x2 = x1 + (double) (i + 1) / num;
^{25}
```

```
if (function(x1) * function(x2) < 0) {</pre>
26
                    findRoot(x1, x2);
27
                }
28
           }
29
       }
30
31
32
         * Finds the root of the function within the given range.
33
34
35
         * Oparam x1 The lower bound of the range
         * Oparam x2 The upper bound of the range
36
37
         */
       private static void findRoot(double x1, double x2) {
38
           double x0;
39
           if (abs(function(x1)) < abs(function(x2))) {</pre>
                x0 = x1;
41
           } else {
42
                x0 = x2;
           double root = solve(x1, x2, x0);
45
           System.out.printf("%.3f\t", root);
       }
48
        /**
49
         * Defines the function for which the root is to be found.
51
         * @param x The input value
52
         * Oreturn The value of the function at x
53
54
       private static double function(double x) {
55
           return 4 * cos(x) - exp(x);
57
58
         * Computes the derivative of the function at a given point.
60
61
         * Oparam x The point at which the derivative is to be computed
         * Oreturn The value of the derivative at x
63
64
       private static double derivative(double x) {
           return -4 * sin(x) - exp(x);
       }
67
68
       /**
69
         st Implements the NR method to find a new approximation for the root.
70
71
72
         * Oparam x The current approximation for the root
         * Oreturn The new approximation using the NR method
73
```

```
74
        private static double xNR(double x) {
75
             return x - function(x) / derivative(x);
76
77
78
        /**
          * Recursively applies the combined NR and Bisection methods to find the root.
80
81
          * Oparam x1 The lower bound of the range
82
          * @param x2 The upper bound of the range
83
          * Oparam x The current approximation for the root
84
          * @return The calculated root
86
        private static double solve(double x1, double x2, double x) {
87
             if (abs(function(x)) < epsilon) {</pre>
88
                 return x;
89
             } else {
90
                 double xN = xNR(x);
91
92
                 if (x1 < xN && x2 > xN) {
93
                     return solve(x1, x2, xN);
94
                 } else {
                     xN = (x1 + x2) / 2;
96
                     if (function(x1) * function(xN) <= 0) {</pre>
97
                          // Update parameter
                          if (abs(function(x1)) < abs(function(xN))) {</pre>
99
                              return solve(x1, xN, x1);
100
                          } else {
101
102
                              return solve(x1, xN, xN);
                          }
103
                     } else {
104
                          if (abs(function(x2)) < abs(function(xN))) {</pre>
105
                              return solve(x2, xN, x2);
106
                          } else {
107
                              return solve(x2, xN, xN);
108
                          }
109
                     }
110
                 }
111
             }
112
        }
113
114 }
115
```

运行结果如下

```
Enter the lower bound
-20 2
Enter the upper bound
In -20.000 to 2.000, there are roots
-17.279 -14.137 -10.996 -7.854 -4.715 -1.516 0.905
```

图 3: NRBisection 运行结果

3 Problem3

利用 Desmos 绘制函数图像,观察 h 的变化对根的影响.

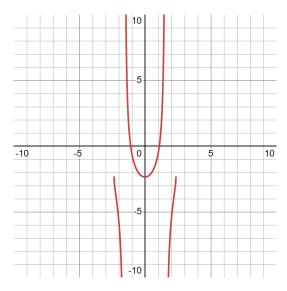


图 4: y = f(x) 的图像

观察可得,对 f(x) 而言在 $n\pi < h < (n+1)\pi(n=0,1,...)$ 时,有 (n+1) 个根。根的范围

$$k\pi < x_k < \left(k + \frac{1}{x}\right)\pi$$

$$-\left(k + \frac{1}{x}\right)\pi < x_k < -k\pi \quad (k = 1, 2, ..., n)$$
(1)

而对于 g(x),在 $\left(n+\frac{1}{x}\right)\pi < h < \left(n+\frac{3}{2}\right)\pi (n=0,1,\ldots)$ 时,有 (n+1) 个根。根的范围

$$\left(k + \frac{1}{x}\right)\pi < x_k < (k+1)\pi
-(k+1)\pi < x_k < -\left(k + \frac{1}{x}\right)\pi \quad (k = 1, 2, ..., n)$$
(2)

利用 full Muller-Brent 求解根,使用 Java 代码实现如下

```
import java.util.Scanner;
import java.util.function.Function;

import static java.lang.StrictMath.*;
```

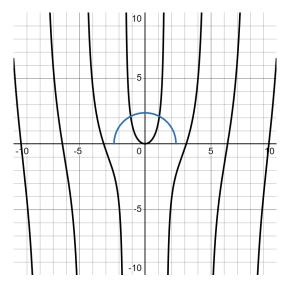


图 5: $y = x \tan x$ 和 $y = sqrth^2 - x^2$ 的图像

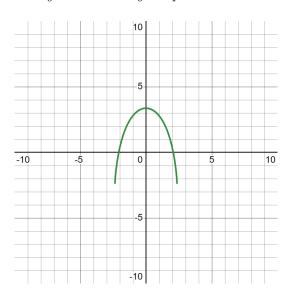


图 6: y = g(x) 的图像

```
5
6  /**
7  * This class implements the Muller's Bisection method to find roots of transcendental equations.
8  */
9  public class FullMB {
10
11     static int N = 100;
12     static double epsilon = 1e-10;
13
14     public static void main(String[] args) {
15
16         System.out.println("Enter the h");
17         Scanner scanner = new Scanner(System.in);
18         double h = scanner.nextDouble();
```

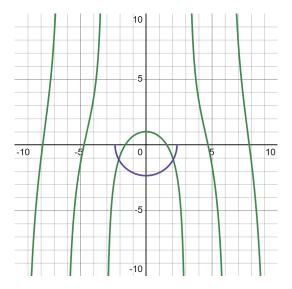


图 7: $y = x \cot x$ 和 $y = -sqrth^2 - x^2$ 的图像

```
19
            Function \langle Double \rangle f = (x) \rightarrow x * tan(x) - sqrt(h * h - x * x);
20
            Function<Double, Double> g = (x) \rightarrow x / tan(x) + sqrt(h * h - x * x);
21
22
            System.out.println("Root of x tan(x) - sqrt(h^2 - x^2) = 0");
23
            int n = (int) (abs(h / PI));
            for (int i = n; i >= 0; i--) {
25
                double xl = -(i + 1.0 / 2) * PI;
26
                double xu = -i * PI;
                rank(x1, xu, f);
28
            }
29
            for (int i = 0; i <= n; i++) {</pre>
                double xl = i * PI;
31
                double xu = (i + 1.0 / 2) * PI;
32
                rank(x1, xu, f);
33
            }
34
35
            System.out.println();
            System.out.println("Root of x cot(x) + sqrt(h^2 - x^2) = 0");
            n = (int) (abs(h / PI) - 1.0 / 2);
37
            for (int i = n; i >= 0; i--) {
38
                double xl = -(i + 1) * PI;
                double xu = -(i + 1.0 / 2) * PI;
40
                rank(x1, xu, g);
41
            }
42
            for (int i = 0; i <= n; i++) {</pre>
                double x1 = (i + 1.0 / 2) * PI;
44
                double xu = (i + 1) * PI;
45
                rank(x1, xu, g);
46
            }
47
       }
48
49
```

```
50
         * Find roots within a given range using the Muller's Bisection method.
51
52
        * @param xl Lower bound of the range
53
         * Oparam xu Upper bound of the range
54
        * Oparam f The function for which roots are to be found
56
       public static void rank(double x1, double xu, Function<Double, Double> f) {
57
           double step = 0.001;
           double n = (xu - xl) / step;
59
           for (int i = 0; i < n - 3; i++) {</pre>
60
                double x = xl + i * step;
                if (f.apply(x) * f.apply(x + step) < 0) {
62
                    double root = fullMB(x, x + step, x + 2 * step, f);
63
                    System.out.printf("%.3f\t", root);
                }
65
           }
66
67
       }
68
69
        * Muller's Bisection method to find a root of a function within a given interval.
70
72
        * @param x0
                           Initial point 1
        * @param x1
                           Initial point 2
73
         * @param x2
                           Initial point 3
75
        * Oparam function The function for which the root is to be found
        * Oreturn The estimated root
76
       public static double fullMB(double x0, double x1, double x2, Function<Double, Double>
78
        → function) {
           double x = 0;
80
           for (int i = 0; i < N; i++) {</pre>
81
                double f0 = function.apply(x0);
                double f1 = function.apply(x1);
83
                double f2 = function.apply(x2);
84
                double h1 = x1 - x0;
86
                double h2 = x2 - x1;
87
                double delta1 = (f1 - f0) / h1;
                double delta2 = (f2 - f1) / h2;
                double d = (delta2 - delta1) / (h1 + h2);
90
91
                double b = delta2 + h2 * d;
92
                double D = Math.sqrt(b * b - 4 * f2 * d);
93
94
                double denominator = b + ((b \ge 0) ? 1 : -1) * D;
96
```

```
double dx = -2 * f2 / denominator;
97
                  x = x2 + dx;
98
                  if (Math.abs(dx) < epsilon) {</pre>
100
                       break;
101
102
                  }
103
                  x0 = x1;
104
                  x1 = x2;
106
                  x2 = x;
             }
107
108
109
             return x;
110
111 }
112
```

运行结果如下

```
Root of 1.0x<sup>3</sup> + -70.5x<sup>2</sup> + 1533.54x + -10082.44 = 0
12.400000+0.0000001 34.600000+0.0000001 23.500000+0.0000001
```

图 8: CubicEquationSolver 运行结果

4 Problem4

利用范盛金公式求解根,使用 Java 代码实现如下

```
1 import static java.lang.StrictMath.*;
2
    * This class solves a cubic equation of the form ax^3 + bx^2 + cx + d = 0 using Cardano's
        \hookrightarrow method.
  public class CubicEquationSolver {
         st Main method to solve a specific cubic equation and print the roots.
9
         * Oparam args Command line arguments (not used)
         */
11
       public static void main(String[] args) {
12
           double a = 1.0;
13
           double b = -70.5;
14
           double c = 1533.54;
15
           double d = -10082.44;
16
17
           System.out.println("Root of "+a+"x^3 + "+b+"x^2 + "+c+"x + "+d+" = 0");
           for (double[] root : solve(a, b, c, d)) {
18
```

```
System.out.printf("%f+%fi\t", root[0], root[1]);
19
           }
20
       }
21
22
       /**
23
        * Solves the cubic equation given the coefficients a, b, c, and d.
        * {\it Oparam\ a\ Coefficient\ of\ x^3}
25
        * @param b Coefficient of x^2
26
        * Oparam c Coefficient of x
27
         * @param d Constant term
28
         * Creturn Array of arrays containing the real and imaginary parts of the roots
29
        */
       private static double[][] solve(double a, double b, double c, double d) {
31
           double A = b * b - 3 * a * c;
32
           double B = b * c - 9 * a * d;
33
           double C = c * c - 3 * b * d;
34
           double delta = B * B - 4 * A * C;
35
           if (A == 0 && B == 0) {
                return new double[][]{{-b / 3 / a, 0}, {-c / b, 0}, {-3 * d / c, 0}};
37
           } else {
38
                if (delta > 0) {
                    double Y1 = A * b + 3 * a * ((-b + sqrt(B * B - 4 * a * c)) / 2);
                    double Y2 = A * b + 3 * a * ((-b + sqrt(B * B + 4 * a * c)) / 2);
41
                    double t1 = pow(Y1, 1.0 / 3) + pow(Y2, 1.0 / 3);
42
                    double t2 = pow(Y1, 1.0 / 3) - pow(Y2, 1.0 / 3);
                    return new double[][]{{(-b - t1) / 3 / a, 0}, {(-b + t1 / 2) / 3 / a, (-b + t2 *
44

→ sqrt(3) / 2) / 3 / a}, {(-b + t1 / 2) / 3 / a, -(-b + t2 * sqrt(3) / 2) / 3 / a}};
                } else if (delta == 0) {
45
                    double K = B / A;
46
47
                    return new double[][]{{-b / a + K, 0}, {-K / 2, 0}, {-K / 2, 0}};
               } else {
                    double T = (2 * A * b - 3 * a * B) / 2 / sqrt(A * A * A);
49
                    double theta = acos(T);
50
                    double t1 = cos(theta / 3);
                    double t2 = sqrt(3) * sin(theta / 3);
52
                    return new double[][]{{(-b - 2 * sqrt(A) * t1) / 3 / a, 0}, {(-b + sqrt(A) * (t1
53
        \hookrightarrow + t2)) / 3 / a, 0}, {(-b + sqrt(A) * (t1 - t2)) / 3 / a, 0}};
54
           }
55
       }
56
57 }
58
```

运行结果如下

```
Enter the h

10

Root of x tan(x) - sqrt(h^2 - x^2) = 0

-9.679 -7.069 -4.271 -1.428 1.428 4.271 7.069 9.679

Root of x cot(x) + sqrt(h^2 - x^2) = 0

-8.423 -5.679 -2.852 2.852 5.679 8.423
```

图 9: FullMB 运行结果

5 Problem5

对于这一题,应首先注意到所求的拉格朗日点是位于两个天体之间的拉格朗日点,同时,因为此时地球的质量远大于月球,所以为了使卫星满足相对平衡运动的条件,其所处的位置会更为靠近月球。由此可以给出拉格朗日点大致的范围应该在 $[1.9\times10^8,3.8\times10^8]$,故而可取起点 $r_0=1.9\times10^8$ (对于牛顿法则只取这一个点即可)和终点 $r_1=3.8\times10^8$ 以此便可以确定 Newton's Method 和 Secant Method 的起点与终点。这两种算法均以 while 循环实现。

具体代码如下:

```
1 # 定义需求解的函数
2 def func(x):
       G = 6.674e-11
       M = 5.974e24
      m = 7.348e22
      R = 3.844e8
       w = 2.662e-6
       y = G * M / (x * x) - G * m / ((R - x) * (R - x)) - w * w * x
      return y
11
12 def dfunc(x):
      G = 6.674e-11
       M = 5.974e24
      m = 7.348e22
      R = 3.844e8
       w = 2.662e-6
17
       y = -2 * G * M / (x * x * x) - 2 * G * m / ((R - x) * (R - x) * (R - x)) - w * w
19
       return y
21
22 # 实现牛顿迭代法求解
23 def func1(x, z):
       while abs(func(x)) > z:
24
           x = x - func(x) / dfunc(x)
25
       return x
27
28
```

```
29 # 实现截断法求解
30 def func2(x, y, z):
31
       while abs(x - y) > z:
           temp = y - func(y) * (y - x) / (func(y) - func(x))
32
           x = y
33
           y = temp
       return y
35
36
38 # 代入预设初始范围
39 	 x1 = 1.9e8
40 \text{ y1} = 3.8e8
41 \text{ root1} = \text{func1}(x1, 0.000001)
42 root3 = func2(x1, y1, 0.000001)
43 print('Newton Method求得根为: ', '\n%.6e' % root1)
44 print('Secant Method求得根为: ', '\n%.6e' % root3)
```

运行结果如下

Newton Method求得根为: 3.260451e+08 Secant Method求得根为: 3.260451e+08

图 10: lagrange_point 运行结果