

Feb. 2nd, 2026. DM halos #1

Questions:

#1) collisional \Rightarrow strong gravitational interactions between individual stars are important
collisionless \Rightarrow individual interactions, even close encounters, are not important

(a)

#2) $t_{\text{relax}} =$ time required to change a star's velocity by 100% $\approx N_{\text{relax}} t_{\text{cross}}$
 $t_{\text{dyn}} =$ crossing time for individual stars $\approx t_{\text{cross}}$

$$\text{where } N_{\text{relax}} = \frac{N}{8 \ln N} ; t_{\text{cross}} \approx \frac{2\pi R}{v}$$

with $R =$ galaxy size & $v =$ star velocity

(b)

For a typical galaxy, $N \approx 10^{11}$ & $t_{\text{cross}} \sim 100 \text{ Myr}$

$\Rightarrow t_{\text{relax}} \sim 5 \times 10^{10} \text{ yr} \sim 5 \text{ million times the age of our Universe!}$

\hookrightarrow two-body relaxation cannot be the mechanism through which galaxies reach equilibrium; otherwise they would be far from equilibrium today!

#3) (a)

The fundamental assumption of the virial theorem is

that the system is in equilibrium, or $\frac{dG}{dt} = 0$

$$\text{where } G = \text{virial quantity} = \sum_{i=1}^N w_i \vec{x}_i \cdot \vec{v}_i \quad (b) 2K + W = 0$$

virial theorem

#4) Collisionless Boltzmann eqⁿ: $\frac{\partial f(\vec{x}, \vec{v}, t)}{\partial t} + \vec{x} \cdot \frac{\partial f(\vec{x}, \vec{v}, t)}{\partial \vec{x}} + \vec{v} \cdot \frac{\partial f(\vec{x}, \vec{v}, t)}{\partial \vec{v}} = 0$

describes the behavior of the distribution $f(\vec{x}, \vec{v}, t)$ under the influence of grav.

#5) Terms eqⁿ are the collisionless Boltzmann eqⁿ multiplied by powers of \vec{x} or \vec{v} and integrated over a part of phase space.

They are moment equations of the Boltzmann eqⁿ.

They are useful in astronomy because astro observations are usually performed at fixed \vec{x} / location in the sky. Thus, multiplying the collisionless Boltzmann eqⁿ by \vec{v} and integrating over all components of the velocity connects to observables.

#6) β = orbital anisotropy = difference in the velocity distribution in different directions.

$$= 1 - \frac{\sigma_\theta^2 + \sigma_\phi^2}{2\sigma_r^2}$$

$\beta = 0$: if the spread of motion in r, θ, ϕ are all the same
 \Rightarrow isotropic

$\beta \rightarrow 1$: if the spread of motion in $r \gg \sigma_\theta \approx \sigma_\phi$
 \Rightarrow radially biased

$\beta \rightarrow -\infty$: if all orbits are circular: $\sigma_r = 0$
 \Rightarrow tangentially biased

#7) Given a certain mass model and $\beta(r)$ profile, one can calculate the solutions to Jeans equations, which connect back to velocity dispersions (ie, observables).

↳ one can then do forward modeling: given a certain physical model for DM halo structure (eg, NFW profile), what is the expected stellar velocity dispersion? And how does it compare to data?

↳ (inverse modeling: given the data, how can I fit my physical model to it?)