

Assignment 1

□ Show that a Poisson distribution converges to a Gaussian in the limit of large λ

Poisson distribution is $P_p = \frac{e^{-\lambda} \lambda^k}{k!}$

for $\lambda =$ expected # of events in an interval
 $k =$ actual # of events in an interval

So effectively, we would like to show that for large λ :

$$P_p \rightarrow \frac{e^{-(k-\lambda)^2/2\lambda}}{\sqrt{2\pi\lambda}}$$

For large λ , $k \sim$ continuous, so we can express it as
 $k = \lambda(1+\delta)$ with a deviation from the mean $\delta \ll 1$

Stirling's approximation: $n! \approx n^n e^{-n} \sqrt{2\pi n}$

$$\begin{aligned} \Rightarrow P_p &= \frac{e^{-\lambda} \lambda^k}{k!} = \frac{e^{-\lambda} \lambda^k}{\sqrt{2\pi k} e^{-k} k^k} \\ &= \frac{e^{-\lambda} \lambda^{\lambda(1+\delta)}}{\sqrt{2\pi \lambda(1+\delta)} e^{-\lambda(1+\delta)} (\lambda(1+\delta))^{\lambda(1+\delta)}} \\ &= \frac{e^{-\lambda} \lambda^{\lambda(1+\delta)}}{\sqrt{2\pi \lambda} e^{-\lambda} e^{-\lambda\delta} \lambda^{\lambda(1+\delta)} (1+\delta)^{\lambda(1+\delta) + \frac{1}{2}}} \\ &= \frac{e^{\lambda\delta} (1+\delta)^{-\lambda(1+\delta) + \frac{1}{2}}}{\sqrt{2\pi \lambda}} \end{aligned}$$

• Take log expansion:

$$\ln(P_p) = \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda(1+s) + \frac{1}{2}\right) \ln(1+s)$$

• For small s , $\ln(1+s) \approx s - \frac{s^2}{2} + \underbrace{\theta(s^3)}_{\text{negligible}}$

$$\Rightarrow \ln(P_p) = \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda(1+s) + \frac{1}{2}\right) \left(s - \frac{s^2}{2}\right)$$

$$= \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda + \lambda s + \frac{1}{2}\right) \left(s - \frac{s^2}{2}\right)$$

$$= \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda s - \frac{\lambda s^2}{2} + \lambda s^2 - \frac{\lambda s^3}{2} + \frac{s}{2} - \frac{s^2}{2}\right)$$

$$= \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda s - \frac{\lambda s^2}{2} + \lambda s^2\right) \quad \text{negligible}$$

$$= \ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda s + \frac{\lambda s^2}{2}\right)$$

• Take exponential:

$$P_p = e^{\ln\left(\frac{e^{\lambda s}}{\sqrt{2\pi\lambda}}\right) - \left(\lambda s + \frac{\lambda s^2}{2}\right)}$$

$$= \frac{e^{\lambda s}}{\sqrt{2\pi\lambda}} e^{-\left(\lambda s + \frac{\lambda s^2}{2}\right)}$$

$$= \frac{e^{\lambda s}}{\sqrt{2\pi\lambda}} e^{-\lambda s} e^{-\frac{\lambda s^2}{2}}$$

$$= \frac{e^{-\frac{\lambda s^2}{2}}}{\sqrt{2\pi\lambda}}$$

$$\Rightarrow P_p = \frac{e^{-\lambda \left(\frac{k-\lambda}{\lambda}\right)^2 / 2}}{\sqrt{2\pi\lambda}}$$

$$\Rightarrow P_p = \frac{e^{-(k-\lambda)^2 / 2\lambda}}{\sqrt{2\pi\lambda}} \quad \text{mean} = \text{var} \sim \lambda$$

$$\begin{aligned} k &= \lambda(1+s) \\ \Rightarrow s &= \frac{k-\lambda}{\lambda} \end{aligned}$$

[2]

The gold standard for a believable result is usually 5σ .
 Let's define the Gaussian approximation as "good enough" if it agrees with the Poisson to within a factor of 2.
 How large does n need to be for the Gaussian to be good enough @ 5σ ? 3σ ?

• If λ is large enough, then the expected # of events \sim # of observed events
 i.e. $\lambda \sim n$

• We can set $P_P = 2 P_G$ with $k = \mu + \sigma^*$ & solve for λ
 with $\sigma^* = 3\sigma$ & 5σ

for which we would have $\mu \sim \lambda$
 $\sigma^2 \sim \lambda \Rightarrow \sigma = \sqrt{\lambda}$

$$\Rightarrow \frac{e^{-\lambda} \lambda^k}{k!} = 2 \frac{e^{-(k-\mu)^2/2\sigma^2}}{\sqrt{2\pi\sigma^2}}$$

$$\Rightarrow \frac{e^{-\lambda} \lambda^{\lambda+\sigma^*}}{(\lambda+\sigma^*)!} = 2 \frac{e^{-(\lambda+\sigma^*-\lambda)^2/2\lambda}}{\sqrt{2\pi\lambda}}$$

$$\Rightarrow \frac{e^{-\lambda} \lambda^{\lambda+\sigma^*}}{(\lambda+\sigma^*)!} = 2 \frac{e^{-(\sigma^*)^2/2\lambda}}{\sqrt{2\pi\lambda}}$$

Take first $\sigma^* = 3\sigma = 3\sqrt{\lambda}$

$$\Rightarrow \frac{e^{-\lambda} \lambda^{\lambda+3\sqrt{\lambda}}}{(\lambda+3\sqrt{\lambda})!} = 2 \frac{e^{-(3\sqrt{\lambda})^2/2\lambda}}{\sqrt{2\pi\lambda}}$$

$$\Rightarrow \frac{e^{-\lambda} \lambda^{\lambda+3\sqrt{\lambda}}}{(\lambda+3\sqrt{\lambda})!} = 2 \frac{e^{-9/2}}{\sqrt{2\pi\lambda}}$$

We can plug e.g. in Wolfram & we find $\lambda = 8,217...$

$$\lambda \approx 9 = n$$

So for 3σ , we need $n \approx 9$

• Now take $\sigma^* = 5\sigma = 5\sqrt{\lambda}$

$$\Rightarrow \frac{e^{-\lambda} \lambda^{\lambda+5\sqrt{\lambda}}}{(\lambda+5\sqrt{\lambda})!} = 2 \frac{e^{-25/2}}{\sqrt{2\pi\lambda}}$$

Again with Wolfram, we find $\lambda = ...$

Actually, Wolfram cannot solve it. Use Mathematica instead!

we find $\lambda \sim 575...$

So for 5σ , we need $n = 576$

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n Gaussian-distributed data points; identical σ ; same μ
Find error on max likelihood estimate of the mean

• Probability of observing n data points is

$$P = \prod_{i=1}^n P_i = \left(\frac{1}{\sigma \sqrt{2\pi}} \right)^n e^{-\frac{1}{2} \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma} \right)^2} \quad (1)$$

• Best estimate of μ maximizes P . Minimize exponent :

$$\frac{d}{d\mu} \left(-\frac{1}{2} \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma} \right)^2 \right) = 0 \quad (2)$$

$$\Rightarrow -\frac{1}{2} \sum_{i=1}^n \frac{d}{d\mu} \left(\frac{x_i - \mu}{\sigma} \right)^2 = 0$$

$$\Rightarrow -\frac{1}{2} (-2) \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma^2} \right) = 0$$

$$\Rightarrow \sum_{i=1}^n x_i - \sum_{i=1}^n \mu = 0$$

$$\Rightarrow n\mu = \sum_{i=1}^n x_i$$

$$\Rightarrow \boxed{\mu = \frac{1}{n} \sum_{i=1}^n x_i} \quad \text{standard expression for the mean}$$

$$\text{Variance on } \mu \text{ is } \sigma_\mu^2 = \sum_{i=1}^n \sigma^2 \left(\frac{\partial \mu}{\partial x_i} \right)^2$$

$$= \sum_{i=1}^n \sigma^2 \left(\frac{\partial}{\partial x_i} \left(\frac{1}{n} \sum_{i=1}^n x_i \right) \right)^2$$

$$= \sum_{i=1}^n \sigma^2 \cdot \frac{1}{n^2}$$

$$= n \frac{\sigma^2}{n^2}$$

$$\Rightarrow \boxed{\sigma_\mu^2 = \frac{\sigma^2}{n} \quad \text{or} \quad \sigma_\mu = \frac{\sigma}{\sqrt{n}}}$$

Now we got the errors on $\frac{1}{2}$ the data wrong by a factor of $\sqrt{2}$
 What is the error on the new mean estimate?

- We can find our new mean estimate from eq. (2) with independent errors σ_i :

$$\frac{d}{d\mu} \left(-\frac{1}{2} \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma_i} \right)^2 \right) = 0$$

$$\Rightarrow -\frac{1}{2} \sum_{i=1}^n \frac{d}{d\mu} \left(\left(\frac{x_i - \mu}{\sigma_i} \right)^2 \right) = 0$$

$$\Rightarrow -\frac{1}{2} (-2) \sum_{i=1}^n \frac{x_i - \mu}{\sigma_i^2} = 0$$

$$\Rightarrow \sum_{i=1}^n \frac{x_i}{\sigma_i^2} - \sum_{i=1}^n \frac{\mu}{\sigma_i^2} = 0$$

$$\Rightarrow \sum_{i=1}^n \frac{x_i}{\sigma_i^2} = \sum_{i=1}^n \frac{\mu}{\sigma_i^2}$$

$$\Rightarrow \boxed{\mu = \frac{\sum_{i=1}^n x_i / \sigma_i^2}{\sum_{i=1}^n 1 / \sigma_i^2}} \quad (\text{weighted average})$$

Variance on μ here is $\sigma_\mu^2 = \sum_{i=1}^n \sigma_i^2 \left(\frac{\partial \mu}{\partial x_i} \right)^2$

$$= \sum_{i=1}^n \sigma_i^2 \left(\frac{\partial}{\partial x_i} \left(\frac{\sum_{j=1}^n x_j / \sigma_j^2}{\sum_{j=1}^n 1 / \sigma_j^2} \right) \right)^2$$

$$= \sum_{i=1}^n \sigma_i^2 \left(\frac{1 / \sigma_i^2}{\sum_{j=1}^n 1 / \sigma_j^2} \right)^2$$

$$= \sum_{i=1}^n \sigma_i^2 \left(\frac{1 / \sigma_i^4}{\left(\sum_{j=1}^n 1 / \sigma_j^2 \right)^2} \right)$$

$$= \frac{\sum_{i=1}^n 1 / \sigma_i^2}{\left(\sum_{j=1}^n 1 / \sigma_j^2 \right)^2}$$

$$\Rightarrow \boxed{\sigma_\mu^2 = \frac{1}{\sum_{i=1}^n 1 / \sigma_i^2}} \quad \text{or} \quad \sigma_\mu = \sqrt{\frac{1}{\sum_{i=1}^n 1 / \sigma_i^2}}$$

• Consider the "accurate" variance $\sigma_A^2 = \frac{1}{\sum_{i=1}^n 1/\sigma_i^2} = \frac{1}{n \cdot \frac{1}{\sigma^2}} = \frac{\sigma^2}{n}$

& the "off" variance $\sigma_B^2 = \frac{1}{\sum_{i=1}^{n/2} 1/\sigma_i^2 + \sum_{i=n/2+1}^n 1/2\sigma_i^2}$

$\Rightarrow \sigma_A = \frac{\sigma}{\sqrt{n}}$

$$= \frac{1}{\frac{n}{2} \left(\frac{1}{\sigma^2} \right) + \frac{n}{2} \left(\frac{1}{2\sigma^2} \right)}$$

$$= \frac{1}{\frac{n}{2\sigma^2} \left(1 + \frac{1}{2} \right)}$$

$$\sigma_B^2 = \frac{4\sigma^2}{3n} \Rightarrow \sigma_B = \frac{2}{\sqrt{3}} \frac{\sigma}{\sqrt{n}}$$

• So the error on our estimate would be off by a factor of

$$\frac{\sigma_B}{\sigma_A} = \frac{2}{\sqrt{3}} \sim 1.155$$

• Weights = $w_i \equiv \frac{1}{\sigma_i^2}$

• What if 1% of the data is underweighted by a factor of 100?

i.e. $w_{i,A} \rightarrow w_{i,C} = \frac{w_{i,A}}{100} \Rightarrow \sigma_{i,C}^2 = 100 \sigma_{i,A}^2$

$$\Rightarrow \sigma_C^2 = \frac{1}{\sum_{i=1}^{n/100} \frac{1}{100\sigma^2} + \sum_{i=n/100+1}^n \frac{1}{\sigma^2}}$$

$$= \frac{1}{\frac{n}{100} \left(\frac{1}{100\sigma^2} \right) + \frac{99n}{100} \left(\frac{1}{\sigma^2} \right)}$$

$$= \frac{1}{\frac{n}{100\sigma^2} \left(\frac{1}{100} + 99 \right)}$$

$$\sigma_C^2 \approx 1.01 \frac{\sigma^2}{n} = 1.01 \sigma_A^2$$

• So the error on our estimate would be off by a factor of $\sqrt{1.01} \sim 1.005$

• What if 1% of the data is overweighted by a factor of 100?

i.e. $w_{i,A} \rightarrow w_{i,D} = 100 w_{i,A} \Rightarrow \sigma_{i,D}^2 = \frac{\sigma_{i,A}^2}{100}$

$$\Rightarrow \sigma_D^2 = \frac{1}{\sum_{i=1}^{n/100} \frac{100}{\sigma^2} + \sum_{i=\frac{n}{100}}^n \frac{1}{\sigma^2}}$$

$$= \frac{1}{\frac{n}{100} \left(\frac{100}{\sigma^2} \right) + \frac{99n}{100} \left(\frac{1}{\sigma^2} \right)}$$

$$= \frac{1}{\frac{n}{100\sigma^2} (100 + 99)}$$

$$\sigma_D^2 \approx \frac{1}{2} \frac{\sigma^2}{n} = \frac{1}{2} \sigma_A^2$$

• So the error on our estimate would be off by a factor of $\sqrt{1/2} \sim 0.71$

★ I should be more concerned about overweighting than underweighting my data! ★

[4]

c.f. Jupyter Notebook

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Show that in the new rotated space, $\tilde{N}_{ij} = \langle \tilde{n}_i \tilde{n}_j \rangle$

$$\begin{aligned} \chi^2 &= (d - A(m))^T V V^T N^{-1} V V^T (d - A(m)) \\ &= (d^T V - A(m)^T V) (V^T N^{-1} V) (V^T d - V^T A(m)) \end{aligned}$$

The noise matrix in our rotated space is $\tilde{N}^{-1} = V^T N^{-1} V$ so that

$$\tilde{N} = (V^T N^{-1} V)^{-1}$$

$$\tilde{N} = V^T N V \quad \text{as } V^T V = I \text{ since } V \text{ orthogonal}$$

Our noise $n_i = d_i - d_{t_i}$ becomes $\tilde{n}_i = \tilde{d}_i - \tilde{d}_{t_i}$

for which the observed & true data are

$$\hat{d}_i = V_{ij}^T d_j$$

$$\tilde{d}_{t_i} = V_{ij}^T d_{t_j}$$

$$\therefore \tilde{N}_{ij} = V_{ij}^T N_{ij} V_{ij} \quad (3)$$

The noise becomes

$$\tilde{n}_i = V_{ij}^T (d_j - d_{t_j})$$

$$\Rightarrow \langle \tilde{n}_i \tilde{n}_j \rangle = \langle V_{ij}^T (d_j - d_{t_j}) (V_{ji}^T (d_i - d_{t_i}))^T \rangle$$

$$= \langle V_{ij}^T (d_j - d_{t_j}) (d_i - d_{t_i})^T V_{ji} \rangle$$

$$= \langle V_{ij}^T \rangle \langle (d_j - d_{t_j}) (d_i - d_{t_i})^T \rangle \langle V_{ji} \rangle$$

$$= V_{ij}^T \langle n_i n_j \rangle V_{ji}$$

$$= V_{ij}^T N_{ij} V_{ji}$$

$$= \tilde{N}_{ij} \text{ from eq (3)}$$

$$\therefore \tilde{N}_{ij} = \langle \tilde{n}_i \tilde{n}_j \rangle$$