

IT UNIVERSITY OF COPENHAGEN

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# Internet Of Things Report

Master of Science in Computer Science  
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# 1 Q1 — Networked Sensor Device for tracking

We need a sensor device to track assets (vehicles and animals) in two wildlife parks:

- **Knuthenborg Safari Park**, Denmark
- **Mpala Research Center**, Kenya

The parks are large, and the devices must be able to track the location of the assets with a high degree of accuracy. The devices will be used to monitor the animals' movements and behavior, as well as to track the vehicles used for research and conservation efforts. The parks are located in different parts of the world, and the devices must be able to operate in different environments. The devices must be able to withstand harsh weather conditions, including extreme temperatures, rain, and dust. The devices must also be able to operate in remote areas with limited access to power and communication networks.

## 1.1 Functional requirements

- Location tracking (GPS)
- Measure acceleration (motion state)
- Measure particulate matter concentration
- Record data every hour (preferably real-time reporting)

## 1.2 Non-functional requirements

The devices must have an accuracy of at least 500 meters. Apart from that we need to consider environmental conditions, battery life, size, and cost.

Given that the devices will be used in wildlife parks, they must be able to withstand extreme temperatures, rain, and dust. Knuthenborg Safari Park is located in Denmark, where temperatures in worst case can drop to -20 degrees Celsius in winter and have hot humid summers. Mpala Research Center is located in Kenya, where temperatures can reach close to 40 degrees Celsius in summer.

Because the device needs to be able to track animals as many types of animals are present in the parks, the size of the device must be small enough to be attached to the animals without causing discomfort.

- Accuracy:  $\geq 500$  m or more
- Withstand extreme temperatures (e.g., -20 to 40 degrees Celsius)
- Withstand rain and dust (IP67 or better)
- Battery life: 0.5 years or more
- Track animals and vehicles
- Size has to be Small
- Cost: \$100 or less

### 1.2.1 Device selection

**Acceleration** For the acceleration we can would want to use a accelerometer. An accelerometer is small and does not consume much power. It can measure the acceleration of the device in three dimensions so vertical movement of birds can be detected too if needed. An example of a sensor could be the ADXL345, which measures at 3mm x 5mm x 1mm, has an Ultra-low power consumption down to 2  $\mu$ Am, can measure acceleration in three dimensions. It has a range of up to  $\pm 16g$  and can operate in temperatures from -40 to +85 degrees Celsius.

**Particulate matter concentration** For the particulate matter concentration we can use a laser particle counter. The laser particle counter is a small device that can measure the concentration of particulate matter in the air. It uses a laser to detect particles in the air and can provide real-time data on the concentration of particulate matter.

**Location tracking and Embedded board** For the location tracking we can use a GPS module. The GPS module is a small device that can provide real-time location data. It uses satellite signals to determine the location of the device and can provide accurate location data even in remote areas, like Mpala. An example of a GPS module is the U-Blox NEO-6M.

For the embedded board we could consider using something existing like the TTGO T-Beam. The TTGO T-Beam is a small, low-power embedded board that can be used for IoT applications. It has a built-in GPS module and LoRaWAN connectivity, making it ideal for tracking applications. The board is small (16mm x 12mm x 2.5mm) and has a low power consumption of 50mA at 3.3V. It also has an accuracy of 2.5m, which is sufficient for our needs.

### **1.2.2 Power supply**

The device will mainly be powered by a rechargeable lithium-ion battery. The battery should be able to provide power for at least 0.5 years of operation.

For additional power supply, we can consider energy harvesting. A common source would be using a solar panel. A possible issue would be that the device is not always exposed to sunlight, especially in the case of animals that might cover the cell from the sun with their body, fur or dirt.

The device will also have a solar panel to recharge the battery when it is exposed to sunlight. The solar panel will be able to provide enough power to keep the battery charged even in low-light conditions.

## 2 Question 2

### 3 Question 3

## 4 Sensor precision VS sensor accuracy

Sensor **precision** refers to the degree to which repeated measurements under unchanged conditions show the same results. In other words, it indicates how consistent the measurements are. For example, if a sensor consistently measures the same value for a given input, it is considered precise.

Sensor **accuracy**, on the other hand, refers to how close a measured value is to the true value or the actual value of the quantity being measured. A sensor can be precise but not accurate if it consistently gives the same incorrect measurement. Conversely, a sensor can be accurate but not precise if it gives varying measurements that are close to the true value.

### 4.1 MQTT and it's role in IoT

MQTT (Message Queuing Telemetry Transport) is a lightweight messaging protocol designed for low-bandwidth, high-latency, on unreliable networks[3]. It is a publish-subscribe messaging protocol that theoretically can run over any transport protocol that ensures ordered, lossless, bi-directional connections. However, it is most commonly used over TCP/IP.

MQTT plays a crucial role in IoT by providing efficient communication for resource-constrained devices. Its lightweight design minimizes bandwidth usage and power consumption, making it ideal for battery-operated sensors and actuators. The protocol's small header size and minimal network overhead allow for effective operation on unreliable networks with limited bandwidth. MQTT's quality of service options ensure message delivery even in unstable connections, while its last will feature helps detect device disconnections. These characteristics make MQTT particularly valuable in situations like smart home applications, where it reduces network noise and enables reliable communication between numerous low-power devices.

### 4.2 All relevant layers of Wi-Fi, Bluetooth, LoRa and LoRaWan and their use in IoT

WiFi and Bluetooth are relevant for the OSI model layers 1 (physical) and 2 (data link), while LoRa and LoRaWAN are relevant for the OSI model layers 1, 2, and 3 (network).

WiFi and Bluetooth operate in the 2.4 GHz frequency band which is the physical network layer. The data link layer is responsible for the MAC

protocol, which is used to control access to the physical medium. Bluetooth uses a frequency-hopping spread spectrum (FHSS) which also belongs to the data link layer[2, 1].

LoRa and LoRaWAN operate in the sub-GHz frequency bands (e.g., 433 MHz, 868 MHz, 915 MHz) which is the physical network layer. The data link layer is responsible for the MAC protocol, which is used to control access to the physical medium. LoRa uses a chirp spread spectrum (CSS) which also belongs to the data link layer. The network layer is responsible for routing packets between devices and gateways.

WiFi and Bluetooth are short-range communication technologies, while LoRa and LoRaWAN are long-range communication technologies.

They are used for high-bandwidth applications, such as video streaming and file transfer. WiFi has a range of up to 100 meters, while Bluetooth has a range of up to 10 meters.

### **4.3 Security features of the LoRaWAN protocol**



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