

```
% VoltageSolver.m
```

```
% Patrick Utz, 4/23/18, 13.1
```

```
% Description: Analyzing electric circuits can be accomplished by  
% solving sets of equations. For a particular circuit, the voltages V1,  
% V2, and V3 are found through the following linear equations:
```

$$V_1 = 5$$

$$-6V_1 + 10V_2 - 3V_3 = 0$$

$$-V_2 + 51V_3 = 0$$

```
Write a MATLAB program to solve for the voltages. Show your program and results.
```

```
% Variables: A = the constants of V1, V2, V3 respectively; B = the  
% answers to each equation; V1, V2, V3 = the answers to the system
```

```
clear
```

```
A = [1 0 0; -6 10 -3; 0 -1 51];
```

```
B = [5;0;0];
```

```
answer = A\B;
```

```
V1 = answer(1)
```

```
V2 = answer(2)
```

```
V3 = answer(3)
```

```
V1 =
```

```
5.0000
```

```
V2 =
```

```
3.0178
```

```
V3 =
```

```
0.0592
```

```
% VoltageSolverWithSym.m
```

```
% Patrick Utz, 4/23/18, 13.2
```

```
% Description: An electrical circuits with time-varying sources is being  
% analyzed to follow the following equations. Write a MATLAB program to use  
% the solve function to solve for the three voltages, Va, Vb, and Vc, each  
% is a function of time (t). Show your program and results.
```

$$2(V_a - V_b) + 5(V_a - V_c) - e^{-t} = 0$$
$$2(V_b - V_a) + 2V_b + 3(V_b - V_c) = 0$$
$$V_c = 2 \sin(t)$$

```
% Variables: Va, Vb, Vc = the voltages; eqX = the equations
```

```
clear  
syms t Va Vb Vc;  
eq1 = 2*(Va - Vb) + 5*(Va - Vc) - exp(-t) == 0;  
eq2 = 2*(Vb - Va) + 2*Vb + 3*(Vb - Vc) == 0;  
eq3 = Vc == 2*sin(t);  
s = solve(eq1,eq2,eq3,Va,Vb,Vc);  
disp('Using symbolic solve function');  
disp(s.Va);  
disp(s.Vb);  
disp(s.Vc);
```

```
>> VoltageSolverWithSym  
Using symbolic solve function  
(7*exp(-t))/45 + (82*sin(t))/45  
  
(2*exp(-t))/45 + (62*sin(t))/45  
  
2*sin(t)
```

```
% MovingObject.m
```

```
% Patrick Utz, 4/23/18, 13.3
```

```
% Description: An object starts to move at time 0, and its velocity is  
% measured at a sequence of time as below. Write and run a MATLAB program  
% that determine and plot its distance from its initial position at t=0  
% over this time period, the velocity versus time, and the acceleration  
% versus time using subplot(3, 1, n). Use the time interval from 0 to 10s  
% for all the plots. Use the central difference technique to compute the  
% acceleration and use the stairs for the acceleration versus time  
% curve. Show your program and curves.  
% Time (s) 0 1 2 3 4 5 6 7 8 9 10  
% Vel (m/s) 0 3 7 12 15 12 8 6 1 -2 -8
```

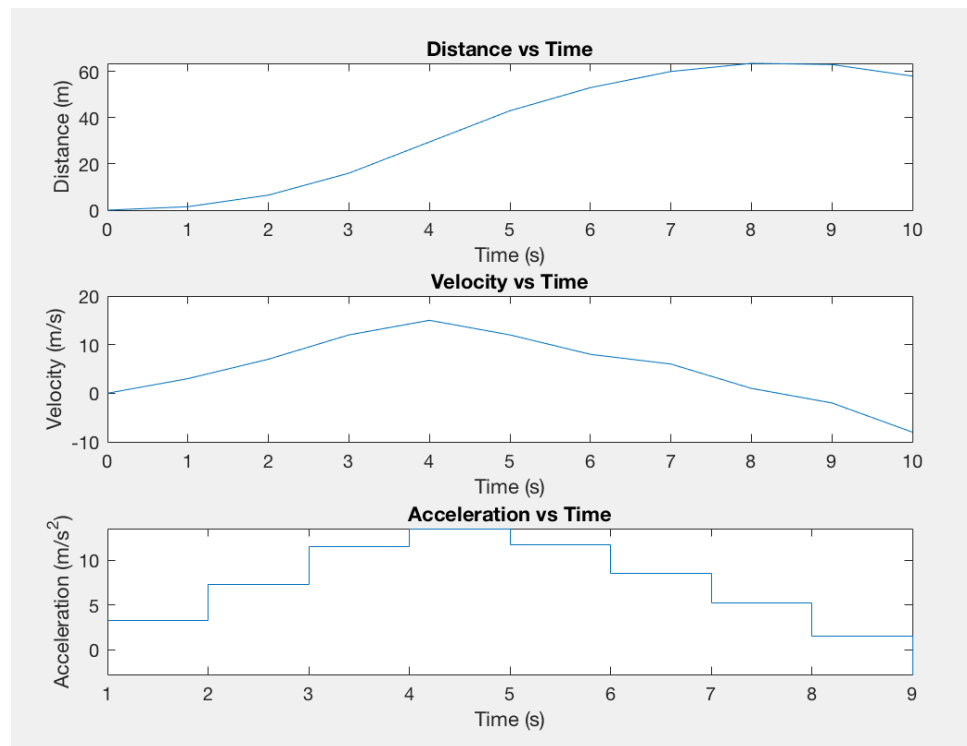
```
% Variables: all names are self-explanatory
```

```
clear  
time = 0:10;  
velocity = [0 3 7 12 15 12 8 6 1 -2 -8];  
distance = cumtrapz(time,velocity);  
dx = diff(time);  
dy = diff(distance);  
acceleration = (dy(1:end-1)+dy(2:end))./(dx(1:end-1)+dx(2:end));
```

```
subplot(3,1,1)  
plot(time, distance);  
title('Distance vs Time');  
xlabel('Time (s)');  
ylabel('Distance (m)')
```

```
subplot(3,1,2)  
plot(time, velocity);  
title('Velocity vs Time');  
xlabel('Time (s)');  
ylabel('Velocity (m/s)');
```

```
subplot(3,1,3)  
stairs(acceleration);  
title('Acceleration vs Time');  
xlabel('Time (s)');  
ylabel('Acceleration (m/s^2)');
```



```

% Mathing_A_Function.m
% Patrick Utz, 4/23/18, 13.4

% Description: Write one program to find the following for the function
%       $4x^2 + 3$ .
% (1) Find the indefinite integral of the function using the symbolic
%      int function.
% (2) Find the definite integral of this function from  $x=-1$  to  $x=3$  using
%      the symbolic int function.
% (3) Find the definite integral of this function from  $x = -1$  to  $x = 3$  using
%      the trapz function with 100 evenly spaced data points.
% (4) Find the definite integral of this function from  $x = -1$  to  $x = 3$  using
%      the integral function.
% Show your program and results. Compare the results in (3) and (4), which
% one is more accurate? Why?

% Variables: all names are self-explanatory

clear
syms x;
eq1 = 4*x^2 + 3;
eq1Integral = int(eq1);
fprintf('Indefinite Integral With Symbolic Int Function: ');
disp(eq1Integral);
eq1DefiniteIntegral = int(eq1,-1,3);
fprintf('Definite Integral With Symbolic Int Function: ');
disp(eq1DefiniteIntegral);

x2 = linspace(-1,3,100);
eq2 = 4.*(x2).^2 + 3;
eq2DefiniteIntegralTrapz = trapz(x2,eq2);
fprintf('Definite Integral With Trapz Function: ');
disp(eq2DefiniteIntegralTrapz);

fun = @(x3) 4.*(x3).^2 + 3;
eq3DefiniteIntegral = integral(fun,-1,3);
fprintf('Definite Integral With Integral Function: ');
disp(eq3DefiniteIntegral);

```

—————>

>> Mathing\_A\_Function

Indefinite Integral With Symbolic Int Function:  $(4x^3)/3 + 3x$

Definite Integral With Symbolic Int Function:  $148/3$

Definite Integral With Trapz Function: 49.3377

Definite Integral With Integral Function: 49.3333

\*\*\* The last result is more accurate than the trapz function result since a greater number of sample data points is used to estimate the integral as opposed to the 100 linearly spaced data points used in the trapz function\*\*\*

```

% TemperatureProblem.m
% Patrick Utz, 4/23/18, 13.5

% Description: Write a MATLAB program to solve the following problem
% The temperature (in degrees Fahrenheit) was recorded every 3 hours for
% a day at a particular location. Using a 24 hour clock where midnight is
% 0, the measured data is shown below:

% Time:0 3 6 9 12 15 18 21
% Temp: 55.5 52.4 52.6 55.7 75.6 77.7 70.3 66.6

% 1. plot the data points as black circles
% 2. plot linear inter/extrapolation of the temperature using blue dashed
% line and spline inter/extrapolation using red dot-dashed line, in the
% same figure window as that in 1.
% 3. find the temperature at 10:30am and 11:00pm during the day from both
% curves in 2, and plot the points in the figure as blue squares(for
% linear) and red stars(for spline), respectively.
% 4. in a new figure window, repeat 1, curve-fitting the data with a third-
% order polynomial, plot the smooth fitted curve as blue dashed line,
% and a fifth-order polynomial plotted in red dot dashed line.
% 5. find the time during the day when temperature is 60 and 65 degree,
% from both polynomials in 4, and plot those points in the figure
% as blue squares(for 3rd order) and red stars(5th order).
% Properly label and title your figures, use legends if necessary.

% Variables: all names are self-explanatory (for the most part)

clear
time = [0:3:21];
temp = [55.5 52.4 52.6 55.7 75.6 77.7 70.3 66.6];
time1 = 0:1:21

hold on
plot(time,temp,'ko')
title('Temperature vs Time');
xlabel('Time (hours)');
ylabel('Temperature (F)');

temp2 = interp1(time,temp,time1,'linear')
temp2_1030AM = temp2(time1 == 10.500);
temp2_1100PM = temp2(time1 == 21.000);
plot(time1,temp2,'b--');
plot(10.500,temp2_1030AM,'bs');
plot(21.000,temp2_1100PM,'bs');

```

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temp3 = interp1(time,temp,time1,'spline');
temp3_1030AM = temp3(time1 == 10.500);
temp3_1100PM = temp3(time1 == 21.000);
plot(time1,temp3,'r-');
plot(10.500,temp3_1030AM,'r*');
plot(21.000,temp3_1100PM,'r*');

Lin1030 = sprintf('Temp @ 10:30 AM is %.3f F (linear)', temp2_1030AM);
Lin1100 = sprintf('Temp @ 11:00 PM is %.3f F (linear)', temp2_1100PM);
Spli1030 = sprintf('Temp @ 10:30 AM is %.3f F (spline)', temp3_1030AM);
Spli1100 = sprintf('Temp @ 11:00 PM is %.3f F (spline)', temp3_1100PM);

legend('Data Points','Linear Interpolation',Lin1030,Lin1100,...
      'Spline Interpolation',Spli1030,Spli1100);

hold off

hold on
plot(time,temp,'ko')
title('Temperature vs Time');
xlabel('Time (hours)');
ylabel('Temperature (F)');

p3 = polyfit(time,temp,3);
temp4 = polyval(p3,time1);
temp4_60_time = time1(temp4 == 60.133505194805210);
temp4_65_time1 = time1(temp4 == 65.190458425525110);
temp4_65_time2 = time1(temp4 == 65.319716001282600);
plot(time1,temp4,'b--');
plot(temp4_60_time,60.133505194805210,'bs');
plot(temp4_65_time1,65.190458425525110,'bs');
plot(temp4_65_time2,65.319716001282600,'bs');

p5 = polyfit(time,temp,5);
temp5 = polyval(p5,time1);
temp5_60_time = time1(temp5 == 60.472017920512840);
temp5_65_time1 = time1(temp5 == 65.385637097035910);
temp5_65_time2 = time1(temp5 == 65.006782524317100);
temp5_65_time3 = time1(temp5 == 65.105937685596690);
plot(time1,temp5,'r-');
plot(temp5_60_time,60.472017920512840,'r*');
plot(temp5_65_time1,65.385637097035910,'r*');
plot(temp5_65_time2,65.006782524317100,'r*');
plot(temp5_65_time3,65.105937685596690,'r*');

Poly3_60 = sprintf('60 F Occur @ time %.3f (poly 3)', temp4_60_time);
Poly3_65_1 = sprintf('65 F Occur @ time %.3f (poly 3)', temp4_65_time1);

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Poly3_65_2 = sprintf('65 F Occur @ time %.3f (poly 3)', temp4_65_time2);
Poly5_60 = sprintf('60 F Occur @ time %.3f (poly 5)', temp5_60_time);
Poly5_65_1 = sprintf('65 F Occur @ time %.3f (poly 5)', temp5_65_time1);
Poly5_65_2 = sprintf('65 F Occur @ time %.3f (poly 5)', temp5_65_time2);
Poly5_65_3 = sprintf('65 F Occur @ time %.3f (poly 5)', temp5_65_time3);

```

```

legend('Data Points','Third-Order Polynomial',Poly3_60,Poly3_65_1,...
    Poly3_65_2,'Fifth-Order Polynomial',Poly5_60,Poly5_65_1,...
    Poly5_65_2,Poly5_65_3);

```

hold off

