Zijiang Yan

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Bio

I am a researcher specializing in wireless networks and AI-driven vehicular communication. I earned my BSc with an Honors degree in Computer Science and Statistics from York University, where I researched in the Next Generation Wireless Networks Lab under Prof. Hina Tabassum. My work focuses on optimizing beyond 5G/6G networks, deep reinforcement learning for autonomous driving, and AI-enabled vehicular communication. I aim to develop scalable, efficient solutions to enhance safety and performance in vehicular networks. Currently, I am exploring resource-aware communication, quantum-enhanced user association, and hybrid language models for optimizing driving and telecommunication policies, combining technical expertise with impactful research.

Education

York University Toronto, Canada

B.Sc., Hons. Dbl. Maj. in Computer Science & Statistics

Sep 2016 to Aug 2021

o Advisor: Prof. Hina Tabassum

o Project: Optimizing V2I Communication for Self-Driving Vehicles: A Reinforcement Learning Approach

Experience

Cloud Engineer Toronto, Canada
Bell Media Oct 2021 to present

- Strengthened CI/CD pipeline stability by integrating GitLab and Jenkins, improving infra performance.
- Led the Lighthouse project with *Ansible*, enhancing system reliability and visibility across teams.
- o Contributed to the CRNA DNS project with *Terraform*, ensuring robust and secure connectivity.
- Migrated Satellite systems to Bell's Centralized Satellite platform, boosting scalability and efficiency.
- Transitioned GitLab runners to AWS shared runners and maintained Jenkins pipelines for the Mobile App team, improving build efficiency by 27%.

Machine Learning Researcher

Toronto, Canada Mar 2021 to present

York University

Mar 2021 to present

- Developed a reinforcement learning framework to optimize autonomous driving and network policies, enhancing decision-making efficiency.
- \circ Designed a quantum-enhanced user association model for handoff-aware vehicular networks, applicable to both autonomous vehicles and drones.
- Created a simulation environment to integrate multi-agent communication and autonomous driving policies, fostering robust collaboration.
- Modeled vehicle-to-infrastructure (V2I) networks to maximize data rates while minimizing collisions and communication disruptions.

Software Developer Intern

Toronto, Canada

Bell Canada

May 2021 to Aug 2021

- Utilized machine learning and deep learning techniques on AWS to analyze customer data, uncovering trends and improving marketing strategies.
- Designed and implemented predictive models for customer churn and lifetime value, driving data-informed decision-making.

Publications

Optimizing Vehicular Networks with Variational Quantum Circuits-based Reinforcement Learning

May 2024

Zijiang Yan, Ramsundar Tanikella, Hina Tabassum

10.1109/INFOCOMWKSHPS61880.2024.10620888 ☑ (IEEE International Conference on Computer Communications (INFOCOM'24 Poster))

Multi-UAV Speed Control with Collision Avoidance and Handover-Aware Cell Association - DRL with Action Branching

 $\mathrm{Dec}\ 2023$

Zijiang Yan, Wael Jaafar, Bassant Selim, Hina Tabassum

10.1109/GLOBECOM54140.2023.10436730 C (IEEE Global Communications Conference (GLOBECOM'23))

Reinforcement Learning for Joint V2I Network Selection and Autonomous Driving Policies

Dec 2022

Zijiang Yan, Hina Tabassum

10.1109/GLOBECOM48099.2022.10001396 C (IEEE Global Communications Conference (GLOBECOM'22))

CVaR-Based Variational Quantum Optimization for User Association in Handoff-Aware Vehicular Networks

May 2025

Zijiang Yan, Hao Zhou, Jianhua Pei, Aryan Kaushik, Hina Tabassum, Ping Wang

IEEE International Conference on Communications (ICC'25 Under Review)

Hybrid LLM-DDQN based Joint Optimization of V2I Communication and Autonomous Driving

Oct 2024

Zijiang Yan, Hao Zhou, Hina Tabassum, Xue Liu

10.48550/arXiv.2410.08854 ☑ (IEEE Wireless Communications Letters (Under Review))

Generalized Multi-Objective Reinforcement Learning with Envelope Updates in URLLC-enabled Vehicular Networks

May 2024

Zijiang Yan, Hina Tabassum

10.48550/arXiv.2405.11331 ☑ (IEEE Transactions on Vehicular Technology (Under Review))

Projects

RF TeraHertz Highway Environment

RF-THz-Highway-env ✓

- Developed a multi- objective simulation environment for autonomous driving and vehicular communication.
- o Tools Used: Python, OpenAI Gym

Skills

Programming Languages: Python, Java, C++, SAS, R, SQL, Bash

Tools and Platforms: AWS, Terraform, GitLab, Jenkins, Kafka, MariaDB

Specialized Areas: Generative Artificial Intelligence, Large language Model, Deep Learning, Quantum Computing, Vehicular Communication, Autonomous Driving

Professional Activities

Conference Session Chair: GLOBECOM'23

 $\textbf{Technical Program Reviewer:} \ \text{ICC, GLOBECOM, WCNC, VTC, DySPAN}$

Journal Reviewer: TWC, TCOM, TCCN, OJ-COMS, COMML, IoTM

Honors and Awards

- o 11th China Youth Creative Competition (Science and Technology Track) Silver Award, 2024
- o Bell Geekfest Best Presentation, Bell Canada, 2023
- o Lassonde Undergraduate Research Award (LURA), York University, 2021
- York University International Award of Merit, York University, 2021
- o Dean's List, Lassonde School of Engineering, York University, 2018