

Lecture 1

$$R_{n+1}(x) = \frac{1}{n!} \int_0^x (x-t)^n f^{(n+1)}(t) dt = \frac{(x-x_0)^{n+1}}{(n+1)!} f^{(n+1)}(\xi), \xi \text{ between } x \text{ and } x_0$$

Lecture 3

$$L_n f(x) = \frac{\sum_{i=0}^n x - x_i^{f_i}}{\sum_{i=0}^n \frac{w_i}{x - x_i}},$$

$$f(x) - L_n f(x) = h^{n+1} \binom{s+n}{n+1} f^{(n+1)}(\xi_x), \quad (1.19)$$
$$b_i = 3(h_i f[x_{i-1}, x_i] + h_{i-1} f[x_i, x_{i+1}]).$$

1. Complete (clamped) splines. $m_1 = f'(a), m_n = f'(b).$		Finding cubic splines using the second derivatives		Lecture 6	
2. Endpoint second derivative splines. $2m_1 + m_2 = 3f[x_1, x_2] - \frac{1}{2}f''(a)h_1,$ $m_{n-1} + 2m_n = 3f[x_{n-1}, x_n] - \frac{1}{2}f''(b)h_{n-1}.$		$s_3 _{[x_i, x_{i+1}]} = p_i(x) \in \mathbb{P}_3, i = 1, 2, \dots, n-1,$ $s_3(f; x_i) = f_i, i = 1, 2, \dots, n,$ $s_3''(f; x_i) = M_i, i = 1, 2, \dots, n.$		$h_{i-1}M_{i-1} + 2(h_{i-1} + h_i)M_i + h_iM_{i+1} = 6(f[x_i, x_{i+1}] - f[x_{i-1}, x_i]),$ $2M_1 + M_2 = 6(f[x_1, x_2] - f'),$ $M_{n-1} + 2M_n = 6(f'_n - f[x_{n-1}, x_n]),$	
3. Natural cubic splines. $m_{n-1} + 2m_n = 3f[x_{n-1}, x_n].$					
4. “Not-a-knot” (deBoor) splines. $h_2^2 m_1 + (h_2^2 - h_1^2) m_2 - h_1^2 m_3 = \beta_1,$ $h_{n-1}^2 m_{n-2} + (h_{n-1}^2 - h_{n-2}^2) m_{n-1} - h_{n-2}^2 m_n = \beta_2,$ $\beta_1 = 2(h_2^2 f[x_1, x_2] - h_1^2 f[x_2, x_3]),$ $\beta_2 = 2(h_{n-1}^2 f[x_{n-2}, x_{n-1}] - h_{n-2}^2 f[x_{n-1}, x_n]).$		Least Squares Approximation $a \sum_{i=1}^n x_i^4 + b \sum_{i=1}^n x_i^3 + c \sum_{i=1}^n x_i^2 = \sum_{i=1}^n x_i^2 y_i,$ $a \sum_{i=1}^n x_i^2 + b \sum_{i=1}^n x_i = \sum_{i=1}^n x_i y_i$ $a \sum_{i=1}^n x_i + nb = \sum_{i=1}^n y_i.$			

A_i are called coefficients , $L(f) = \sum_{i=1}^m A_i L_i(f) + R(f), f \in X. \ker R = \mathbb{P}_d \iff \begin{cases} R(e_k) = 0, k = 0, 1, \dots, d, \\ R(e_{d+1}) \neq 0, \end{cases}$		Lecture 7
Numerical Differentiation $f^{(k)}(\alpha) = \sum_{i=0}^m A_i f(x_i) + R(f), \int_a^b f(x) dx = \sum_{k=0}^m \sum_{j \in I_k} A_{kj} f^{(j)}(x_k) + R(f),$	<i>forward difference</i> $f'(x) \approx \frac{f(x+h) - f(x)}{h} \equiv D_h f(x),$	
<i>numerical differentiation formula.</i> <i>numerical integration (quadrature) formula.</i>		$(RD_h f)(x) = f'(x) - D_h f(x) = -\frac{h}{2} f''(\xi), \xi \in (x, x+h).$
<i>backward difference</i> : $f'(x) \approx \frac{f(x) - f(x-h)}{h} \equiv \tilde{D}_h f(x), (R\tilde{D}_h f)(x) = f'(x) - \frac{f(x) - f(x-h)}{h} = \frac{h}{2} f''(\xi), \xi \in (x-h, x).$		
Method of Undetermined Coefficients $D_h^{(2)} f(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}. (RD_h^{(2)} f)(x) = f''(x) - D_h^{(2)} f(x) \approx -\frac{h^2}{12} f^{(4)}(x).$		

Numerical Integration $\int_a^b f(x) dx = \sum_{k=0}^m A_k f(x_k) + R(f),$		Trapezoidal Rule $\int_a^b f(x) dx = \frac{b-a}{2} (f(a) + f(b)) - \frac{(b-a)^3}{12} f''(\xi), \xi \in (a, b),$	
interpolatory quadrature. $d_{\max} = 2m + 1.$		n subintervals $h = \frac{b-a}{n}.$ composite (repeated) $\int_a^b f(x) dx = \frac{h}{2} [f(a) + 2(f_1 + \dots + f_{n-1}) + f(b)] - \frac{h^2(b-a)}{12} f''(\xi), \xi \in (a, b).$	
$\int_a^b f(x) dx = (b-a) f\left(\frac{a+b}{2}\right) + R(f),$		Simpson’s Rule $\int_a^b f(x) dx = \frac{b-a}{6} \left[f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right] - \frac{(b-a)^5}{2880} f^{(4)}(\xi), \xi \in (a, b).$	
Rectangle (Midpoint) Rule $R(f) = \frac{f''(\xi)}{2!} \int \left(x - \frac{a+b}{2}\right)^2 dx = \frac{(b-a)^3}{24} f''(\xi), \xi \in (a, b).$		$\left[h = \frac{b-a}{2m}, n = 2m \right], \int_a^b f(x) dx = \frac{h}{3} \left[f(a) + 4 \sum_{i=1}^m f_{2i-1} + 2 \sum_{i=1}^{m-1} f_{2i} + f(b) \right]$	
$\int_a^b f(x) dx = h \sum_{i=0}^{n-1} f\left(a + \left(i + \frac{1}{2}\right)h\right) + \frac{h^2(b-a)}{24} f''(\xi), \xi \in (a, b),$		composite (repeated) $-\frac{h^4(b-a)}{180} f^{(4)}(\xi), \xi \in (a, b).$	

Gaussian Elimination Lecture 9 $x_n = \frac{b_n}{u_{nn}},$ backward substitution: $x_i = \frac{1}{u_{ii}} \left(b_i - \sum_{j=i+1}^n u_{ij} x_j \right), i = \overline{n-1, 1}$		$x_1 = \frac{b_1}{l_{11}},$ forward $x_i = \frac{1}{l_{ii}} \left(b_i - \sum_{j=1}^{i-1} l_{ij} x_j \right), i = \overline{2, n}.$		LU Factorization <i>no row interchanges are necessary</i> Schur complement $A' = vw^*/a_{11} = L'U'.$ $A = \begin{bmatrix} a_{11} & w^* \\ v & A' \end{bmatrix}$ $Ly = b$ $\begin{bmatrix} 1 & 0 \\ v/a_{11} & I_{n-1} \end{bmatrix} \begin{bmatrix} a_{11} & w^* \\ 0 & A' - vw^*/a_{11} \end{bmatrix}$ $Ux = y.$	
partial pivoting (maximal pivoting on columns). $ a_{pk}^{(k)} = \max_{k \leq l \leq n} a_{lk}^{(k)} .$		total (maximal) pivoting. $ a_{pq} = \max\{ a_{ij} , i, j = \overline{k, n}\}$		LUP Factorization $PA = LU.$ $Ly = Pb$ QR Factorization Lecture 10 $Ux = y.$ $A = QR, Q$ orthogonal and R upper triangular $r_{ii} > 0,$ $Rx = Q^T b.$ Cholesky factorization $A = R^T R,$ $\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ & a_{22} & \dots & a_{2n} \\ & & \ddots & \vdots \\ 0 & & & a_{nn} \end{bmatrix}$	
$(R_i) \longleftrightarrow (R_p)$ scaled pivoting on columns: $\frac{ a_{pi} }{s_i} = \max_{1 \leq j \leq n} \frac{ a_{ji} }{s_j}$		$(R_k) \longleftrightarrow (R_p), (C_k) \longleftrightarrow (C_q).$ $x' = [x_3 \ x_2 \ x_1]^T.$			
$s_i = \max_{j=1, n} a_{ij} $ or $s_i = \sum_{j=1}^n a_{ij} , i = \overline{1, n}.$					

Orthogonal polynomials and recurrence coefficients

Name	Notation	Polynomial	Weight fn.	Interval	α_k	β_k
Legendre	l_m	$[(x^2 - 1)^m]^{(m)}$	1	$[-1, 1]$	0	$\beta_0 = 2,$ $\beta_k = (4 - k^{-2})^{-1}, k \geq 1$
Chebyshev 1 st	T_m	$\cos(m \arccos x)$	$(1 - x^2)^{-\frac{1}{2}}$	$[-1, 1]$	0	$\beta_0 = \pi,$ $\beta_1 = \frac{1}{2},$ $\beta_k = \frac{1}{4}, k \geq 2$
Chebyshev 2 nd	Q_m	$\frac{\sin[(m+1) \arccos x]}{\sqrt{1-x^2}}$	$(1 - x^2)^{\frac{1}{2}}$	$[-1, 1]$	0	$\beta_0 = \frac{\pi}{2},$ $\beta_k = \frac{1}{4}, k \geq 1$
Laguerre	L_m^a	$x^{-a} e^x (x^{m+a} e^{-x})^{(m)}$	$x^a e^{-x}, a > -1$	$[0, \infty)$	$2k + a + 1$	$\beta_0 = \Gamma(1 + a),$ $\beta_k = k(k + a), k \geq 1$
Hermite	H_m	$(-1)^m e^{x^2} (e^{-x^2})^{(m)}$	e^{-x^2}	\mathbb{R}	0	$\beta_0 = \sqrt{\pi},$ $\beta_k = \frac{k}{2}, k \geq 1$

Common Rootfinding Methods Lecture 11 Bisection Method <i>two-point method,</i> $c_n = \frac{a_n + b_n}{2}$		Newton’s Method for Multiple Roots Lecture 12 $x_{n+1} = x_n - m \frac{f(x_n)}{f'(x_n)}.$	
Secant Method $x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})}, n = 1, 2, \dots,$		Newton’s Method for Nonlinear Systems $x_{n+1} = x_n - (J_f(x_n))^{-1} f(x_n), n \geq 0,$	
Newton’s Method $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, n = 0, 1, \dots$ <i>one-step</i>		$J_{f(x_n)} = \begin{bmatrix} \frac{\partial f_1(x)}{\partial x_1} & \frac{\partial f_1(x)}{\partial x_2} \\ \frac{\partial f_2(x)}{\partial x_1} & \frac{\partial f_2(x)}{\partial x_2} \end{bmatrix} J_f(x_n) \delta_{n+1} = -f(x_n),$ $x_{n+1} = x_n + \delta_{n+1}.$	

Adaptive Quadratures Lecture 8 $I \approx \frac{2^p I_{2n} - I_n}{2^p - 1} = I_{2n} + \frac{I_{2n} - I_n}{2^p - 1} \stackrel{\text{not}}{=} R_{2n}$		Richardson’s extrapolation formula. $I - I_{2n} \approx \frac{I_{2n} - I_n}{2^p - 1},$ error estimate	
Iterated Quadratures Romberg’s Method $R_{k,j} = \frac{4^{j-1} R_{k,j-1} - R_{k-1,j-1}}{4^{j-1} - 1}, k = \overline{2, n}, j = \overline{2, k}.$		stopping $\begin{matrix} R_{2,1} & R_{2,2} \\ R_{3,1} & R_{3,2} & R_{3,3} \end{matrix} R_{n-1,n-1} - R_{n,n} < \varepsilon.$	
		$\begin{matrix} \vdots & \vdots & \vdots & \ddots \\ R_{n,1} & R_{n,2} & R_{n,3} & \dots & R_{n,n} \end{matrix} S_{k,1} = R_{k,2}.$	
Gaussian Quadratures $\int_a^b w(x) f(x) dx = \sum_{k=1}^m A_k f(x_k) + R_m(f)$		$\mu_j = \int_a^b w(x) x^j dx$	
		<i>maximum degree of precision, $d = 2m - 1.$</i>	

Iterative Methods Lecture 10 Jacobi and Gauss-Seidel Methods $A = D - L - U, x^{(k+1)} = T x^{(k)} + c$		Jacobi iteration, $A = M - N.$ $M = D, N = L + U,$ so $T_J = D^{-1}(L + U), c_J = D^{-1}b.$	
		$x^{(k+1)} = D^{-1}(L + U)x^{(k)} + D^{-1}b, k \in \mathbb{N},$	
Gauss-Seidel iteration, $M = D - L, N = U,$ so $T_{GS} = (D - L)^{-1}U, c_{GS} = (D - L)^{-1}b.$		$x^{(k+1)} = (D - L)^{-1}Ux^{(k)} + (D - L)^{-1}b,$	
Acceleration methods; SOR Method $M = \frac{D}{\omega} - L, N = \left(\frac{1-\omega}{\omega} D + U\right),$ so $T_\omega = \left(\frac{D}{\omega} - L\right)^{-1} \left(\frac{1-\omega}{\omega} D + U\right), c_\omega = \left(\frac{D}{\omega} - L\right)^{-1} b.$		$D = \begin{bmatrix} a_{11} & & 0 \\ & a_{22} & \\ 0 & & \ddots & \\ & & & a_{nn} \end{bmatrix} -U = \begin{bmatrix} 0 & a_{12} & \dots & a_{1n} \\ & 0 & \dots & a_{2n} \\ & & \ddots & \vdots \\ 0 & & & 0 \end{bmatrix}$	
		$-L = \begin{bmatrix} 0 & & 0 \\ a_{21} & 0 & \\ \vdots & & \ddots \\ a_{n1} & a_{n2} & \dots & 0 \end{bmatrix}$	

$f: [a, b] \rightarrow \mathbf{R}$ is continuous c in (a, b) g is an integrable function that does not change sian on $[a, b].$		$\int_a^b f(x) g(x) dx = f(c) \int_a^b g(x) dx$	
$\text{tr}(A) = \sum_{i=1}^n a_{ii} = \sum_{i=1}^n \lambda_i = \lambda_1 + \lambda_2 + \dots + \lambda_n$		$\det(A) = \prod_{i=1}^n \lambda_i = \lambda_1 \lambda_2 \dots \lambda_n$	
[Banach] (3.2) $g \in C[a, b],$ with $g([a, b]) \subseteq [a, b]$ <i>there exists $0 < \lambda < 1$</i> $ g(x) - g(y) \leq \lambda x - y , \forall x, y \in [a, b]$ g has a unique fixed point $\alpha \in [a, b]$			