Usage Manual for MATLAB Script: Object Detection with Feature Matching

Purpose:

This MATLAB script performs object detection using geometric properties of binary images from the Kimia99_DB dataset. It focuses on:

- 1. Training with a set of binary images.
- 2. Testing the trained model for object classification.
- 3. Evaluating the recognition accuracy by comparing image features.

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1. Requirements:

- MATLAB software with Image Processing Toolbox.
- A dataset directory (Kimia99_DB) containing binary images of objects.
- Input images should have white foreground objects on a black background.

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2. Functional Workflow

2.1. Initialization

Code Segment:

```
matlab
```

```
clc
clear all
close all
```

Clears the workspace, command window, and closes all figures to ensure a clean environment.

Directory and Variable Setup:

```
matlab
```

```
listing = dir('Kimia99_DB');
num_rec = zeros(9,11);
```

- Scans the dataset directory (Kimia99_DB) for image files.
- Initializes num rec to track classification results.

3. Training Phase

Main Loop: Iterates through images for training and extracts geometric features.

matlab

```
for train_no = 1:11
for class_indx = 1:9
```

Image Processing:

Reads and resizes each training image:

matlab

```
filename = listing(tmp_indx).name;
bw = im2bw(imread(sprintf('Kimia99_DB/%s', filename)), 0);
tmp_bw = imresize(bw, [256 256]);
```

Stores the resized image for later processing.

Feature Extraction:

Extracts region properties (e.g., centroid, axes, orientation):

matlab

```
s = regionprops(bw1{class_indx}, {'Centroid', 'MajorAxisLength',
'MinorAxisLength', 'Orientation', 'Area'});
```

Identifies the largest region (ellipse) based on area to avoid noise:

matlab

```
[max_area, max_indx] = max(size_ellipse);
```

• **Geometric Vertex Calculation:** Computes the coordinates of major and minor axis endpoints for the largest ellipse:

matlab

```
vertex(1,1) = s(max_indx).Centroid(1) - (s(max_indx).MinorAxisLength/2)
* sind(s(max_indx).Orientation);
vertex(1,5) = s(max_indx).Centroid(1) + (s(max_indx).MajorAxisLength/2)
* cosd(s(max_indx).Orientation);
```

4. Testing Phase

Main Loop: Tests images not used in the training phase.

matlab

```
for tst_indx = 1:11
```

• Image Processing: Processes test images similarly to training images:

matlab

```
bw = im2bw(imread(sprintf('Kimia99_DB/%s', filename)), 0);
tmp_bw = imresize(bw, [256 256]);
```

Region Properties: Extracts features for test images:

matlab

```
s = regionprops(bw2{tst_no}, {'Centroid', 'MajorAxisLength',
'MinorAxisLength', 'Orientation', 'Area'});
```

• **Transformation Matrix Calculation:** Aligns test image vertices with training image vertices using a transformation matrix:

```
matlab
```

```
M = coor_im2 * inv(coor_im1);
```

 Overlap Rate Calculation: Projects and compares white pixels of test and training images to calculate the overlap rate:

```
matlab
```

```
ln_pro = length(PL_pro);
cntr = sum(PL(:,1) == PL_pro(:,1) & PL(:,2) == PL_pro(:,2));
overlap_rate(org_class_indx, tst_no) = cntr / ln_pro;
```

5. Recognition and Evaluation

Recognition Index:

```
matlab
```

```
rec_indx(class_indx, tst_indx) = max_cls_indx;
```

Assigns the test image to the class with the highest overlap rate.

Accuracy Tracking:

matlab

```
num_rec(class_indx, train_no) = num_rec(class_indx, train_no) + 1;
```

Tracks the number of correctly classified images for each class.

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6. Visualization

• Ellipse and Vertex Display: Plots detected ellipse boundaries and vertices:

matlab

```
plot(x, y, 'r', 'LineWidth', 5);
```

Projected Points: Displays projected white pixels for comparison:

matlab

```
plot(PL_pro(:,1), PL_pro(:,2), 'r.');
```

7. Output

- Overlap Rate Matrix: Stores overlap rates between test and training images for each class.
- Recognition Matrix: Provides classification results for all test images.
- Elapsed Time:

matlab

```
elapsed_time = toc;
```

Displays the total execution time for training and testing.

8. Practical Applications

- Object detection and classification in binary image datasets.
- Evaluating geometric feature-based recognition systems.

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9. Notes

- Ensure all images in Kimia99_DB are compatible binary files.
- Adjust loop parameters (train_no, class_indx) based on dataset requirements.
- Visualization steps (imshow) can be commented out to improve execution speed.

This manual outlines each script component for efficient use in object recognition tasks.