

RobotDockCenter

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Abstract

1 Introduction

According to Author [2020], robot docking is a critical task in autonomous systems. Recent studies [Author, 2019, 2021] have shown significant improvements in docking accuracy using monocular vision.

2 Related Work

The work of Author [2018] provides a comprehensive review of existing docking methods.

3 Methodology

4 Experimental Results

5 Discussion

6 Conclusion

References

A. Author. Title of the article. *Journal Name*, 10:100–110, 2020.

B. Author. Another article title. *Another Journal*, 5:50–60, 2019.

C. Author. Yet another article title. *Yet Another Journal*, 15:150–160, 2021.

D. Author. Review article title. *Review Journal*, 8:80–90, 2018.