```
#include <Arduino.h>
 2 #include "../vars/constants.h"
 3
 4 #define LED_BLINK_DELAY 100
 5
 6 class Led
 7 {
 8
       private:
 9
       TaskHandle_t blinkLEDsTask = NULL;
10
       static void BlinkLEDsTask(void * parameter)
11
12
13
            bool topLedFlag = false;
            while(!false)
14
15
            {
                led_1_on();
16
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
17
18
                if(topLedFlag)
19
                    led_top_on();
20
                led_1_off();
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
21
22
                led_1_on();
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
23
24
                if(topLedFlag)
25
                    led_top_off();
                led_1_off();
26
27
28
                vTaskDelay((LED_BLINK_DELAY * 2) / portTICK_PERIOD_MS);
29
                led_2_on();
30
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
31
32
                if(!topLedFlag)
33
                    led_top_on();
34
                led_2_off();
35
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
36
                led_2_on();
                vTaskDelay(LED_BLINK_DELAY / portTICK_PERIOD_MS);
37
                if(!topLedFlag)
38
39
                    led_top_off();
40
                led_2_off();
41
                vTaskDelay((LED_BLINK_DELAY * 2) / portTICK_PERIOD_MS);
42
43
44
                topLedFlag = !topLedFlag;
            }
45
46
       }
47
48
       public:
49
       bool isBlinking()
50
        {
            if(blinkLEDsTask == NULL)
51
52
                return false;
53
```

```
E:\School\CREO\CREO_5AHME\KOP_Mechatron\Code\src\led\led.h
```

```
-
```

```
54
             auto taskState = eTaskGetState(blinkLEDsTask);
55
 56
             return taskState != eDeleted && taskState != eReady &&
               taskState != eSuspended;
 57
        }
 58
 59
        static void led_top_on()
 60
             digitalWrite(constants::pins::led::Top, HIGH);
 61
 62
        static void led_1_on()
 63
 64
 65
             digitalWrite(constants::pins::led::Led1, HIGH);
         }
 66
        static void led_2_on()
 67
 68
             digitalWrite(constants::pins::led::Led2, HIGH);
 69
70
71
        static void led_top_off()
 72
             digitalWrite(constants::pins::led::Top, LOW);
73
74
75
         static void led_1_off()
 76
         {
             digitalWrite(constants::pins::led::Led1, LOW);
77
        }
78
79
        static void led_2_off()
80
             digitalWrite(constants::pins::led::Led2, LOW);
 81
 82
        }
 83
 84
        Led()
 85
             pinMode(constants::pins::led::Top, OUTPUT);
 86
 87
             pinMode(constants::pins::led::Led1, OUTPUT);
             pinMode(constants::pins::led::Led2, OUTPUT);
 88
 89
             led_top_off();
 90
             led_1_off();
 91
             led_2_off();
        }
 92
93
        void StartBlink()
 94
 95
         {
 96
             if(isBlinking())
 97
                 return;
 98
             xTaskCreatePinnedToCore(
 99
100
                 BlinkLEDsTask,
                 "BlinkLEDsTask",
101
102
                 1000,
                 NULL,
103
104
                 0,
                 &blinkLEDsTask,
105
```

```
{\tt E:\CREO\CREO\_5AHME\KOP\_Mechatron\Code\src\led\led.h}
```

127 };

```
3
106
                 0);
        }
107
108
        void StopBlink()
109
110
111
             if(isBlinking())
112
             {
                 vTaskDelete(blinkLEDsTask);
113
114
             led_top_off();
115
             led_1_off();
116
117
             led_2_off();
        }
118
119
120
        void Toggle()
121
122
             if(isBlinking())
123
                 StopBlink();
124
             else
125
                 StartBlink();
126
        }
```