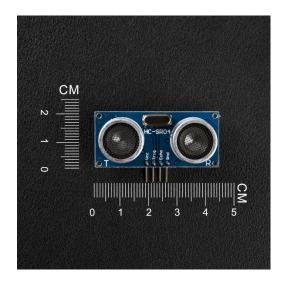
# **Dual Ultrasonic Sensor Module(ST1099/ME140)**



#### 1.Instructions

The HC-SR04 is an inexpensive ultrasonic sensor that can sense not only if an object presents itself, like a PIR sensor, but can also sense and relay the distance to that object.

# **Features:**

Power Supply :+5V DC
 Quiescent Current : <2mA</li>
 Working Currnt: 15mA
 Effectual Angle: <15°</li>

• Ranging Distance : 2cm - 400 cm/1" - 13ft

• Resolution : 0.3 cm

Measuring Angle: 30 degreeTrigger Input Pulse width: 10uS

### 2. Pin Instruction

| Pin Name | Description                   |
|----------|-------------------------------|
| "Vcc"    | Power (5V DC)                 |
| "Trig"   | Trigger the transmit signal   |
| "Echo"   | Echo the received echo signal |
| "Gnd"    | Gnd                           |

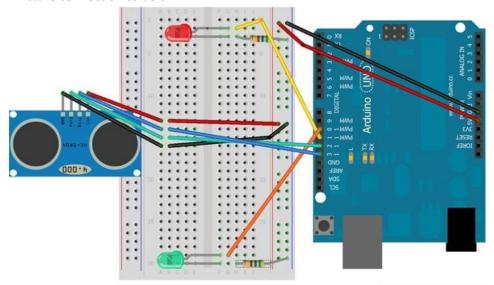
# 3. Example

This example allows you display the defect distance on your ARDUIN's Serial window.

### Pin connection:

Vcc====== Power(5V DC)
Trig======= 12
Echo====== 13
Gnd======Gnd

#### Picture connection as below:



Made with Fritzing.org

#### Example code:

```
************Code begin******
#define trigPin 13
#define echoPin 12
#define led 11
#define led2 10
void setup() {
 Serial.begin (9600);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
 pinMode(led, OUTPUT);
 pinMode(led2, OUTPUT);
}
void loop() {
 long duration, distance;
 digitalWrite(trigPin, LOW); // Added this line
 delayMicroseconds(2); // Added this line
 digitalWrite(trigPin, HIGH);
// delayMicroseconds(1000); - Removed this line
 delayMicroseconds(10); // Added this line
 digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 distance = (duration/2) / 29.1;
 if (distance < 4) { // This is where the LED On/Off happens
   digitalWrite(led,HIGH); // When the Red condition is met, the Green
LED should turn off
```

```
digitalWrite(led2,LOW);
}
else {
    digitalWrite(led,LOW);
    digitalWrite(led2,HIGH);
}
if (distance >= 200 || distance <= 0){
    Serial.println("Out of range");
}
else {
    Serial.print(distance);
    Serial.println(" cm");
}
delay(500);
}</pre>
```

\*\*\*\*\*\*\*\*\*\*Code end\*\*\*\*\*\*