

Conservation of mass

Conservation of momentum

Conservation of particles

Conservation of solute

# Finger formation at the base of ash clouds: A linear stability analysis

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Figure 1. a) Visible and b) infrared images of ash clouds from Vulcanian explosions of Sabancaya volcano, Peru. Fingers can be seen in both images.

### Introduction

Volcanic ash presents a hazard for infrastructure and human health. Understanding ash settling is therefore crucial for assessing the associated risk. Downard-propagating fingers(Figure 1), hypothesised to form from a gravitational instability at the base of the ash cloud (Figure 2) have been seen at many volcanoes, and in analogue experiments (Allan Fries) and numerical models (Jonathon Lemus). Here we present a linear stability analysis,

that predicits the initial growth rate of the fingers.

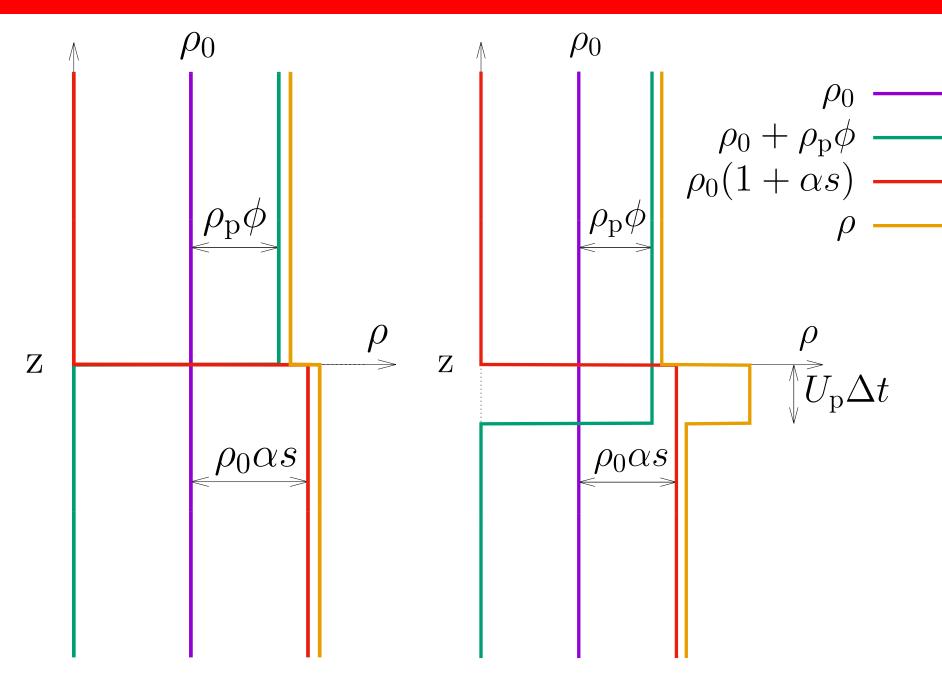


Figure 2. Despite an initial stable configuration, ash settling leads to the formation of a gravitationally unstable **particle boundary layer**.

Unknowns		Parameters	
$\mathbf{u}(\mathbf{x},t)$	Fluid velocity	$\rho_0$	Reference fluid density
$P(\mathbf{x},t)$	Pressure	$\nu$	Kinematic viscosity
$\phi(\mathbf{x},t)$	Particle volume	$oxed{U_{p}}$	Particle settling velocity
$s(\mathbf{x},t)$	Solute concentration	$ ho_{p}$	Particle density
Variables		$D_{p}$	Particle diffusivity
X	Position vector	$D_{s}$	Solute diffusivity
t	time	g	Gravity
$\hat{\mathbf{z}}$	Vertical unit vector	$\mid \alpha \mid$	Expansivity

### **Equations of motion**

### $\nabla \cdot \mathbf{u}(\mathbf{x}, t)$

$$\frac{\partial \mathbf{u}(\mathbf{x},t)}{\partial t} + [\mathbf{u}(\mathbf{x},t)] \cdot \nabla ]\mathbf{u}(\mathbf{x},t) = \frac{\nabla P(\mathbf{x},t)}{\rho_0} + \nu \nabla^2 \mathbf{u}(\mathbf{x},t) - g'\mathbf{\hat{z}} \quad P(\mathbf{x},t) = P^{(0)}(\mathbf{x},t) + \hat{P}(z)e^{i(kx-\omega t)}$$

$$\frac{\partial \phi(\mathbf{x}, t)}{\partial t} + [\mathbf{u}(\mathbf{x}, t)] - \mathbf{U}_{p}] \cdot \nabla \phi(\mathbf{x}, t) = D_{p} \nabla^{2} \phi(\mathbf{x}, t)$$

$$\frac{\partial s(\mathbf{x}, t)}{\partial t} + \mathbf{u}(\mathbf{x}, t)x \cdot \nabla s(\mathbf{x}, t) = D_{s} \nabla^{2} s(\mathbf{x}, t)$$

 $g' = g \left[ 1 + \alpha s(\mathbf{x}, t) + \frac{\rho_p \phi(\mathbf{x}, t)}{\rho_0} \right]$ 

## Non-dimensionalisation and generalised eigenvalue problem

# We nondimensionalise the system using the characteristic length and velocity scales

$$L_{\mathsf{c}} = L_{\mathsf{p}}$$

$$U_{\mathsf{c}} = rac{g L_{\mathsf{p}}^2}{U_{\mathsf{p}}}$$

**Expansion** 

 $\mathbf{u}(\mathbf{x},t) = \mathbf{\hat{u}}(z)e^{i(k_x x + k_y y - \omega t)}$ 

 $\phi(\mathbf{x},t) = \phi^{(0)}(\mathbf{x},t) + \hat{\phi}(z)e^{i(kx-\omega t)}$ 

 $s(\mathbf{x},t) = s^{(0)}(\mathbf{x},t) + \hat{s}(z)e^{i(kx-\omega t)}$ 

 $\hat{P} \ll P^{(0)}, \hat{\phi} \ll \phi^{(0)}, \hat{s} \ll s^{(0)}$ 

### This gives seven dimensionless parameters

$$Re = rac{gL_{
m p}^{
m s}}{
u^2}, \qquad U_{
m p}' = rac{
u U_{
m p}}{gL_{
m p}^2} \qquad L_{
m s}' = rac{L_{
m s}}{L_{
m p}} \ A_{
m g} = rac{\Delta s_0 
u^2}{gL_{
m p}^3}, \qquad A_{
m g} = rac{
ho_{
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u^2}{gL_{
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ho_0} \qquad Sc_{
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u}{D_{
m s}}, \qquad Sc_{
m p} = rac{
u}{D}$$

Can express problem as a generalised eigenvalue equation

$$\begin{pmatrix} \frac{1}{\textit{Re}} \left( \frac{\mathrm{d}^4}{\mathrm{d}z'^4} - 2k'^2 \frac{\mathrm{d}^2}{\mathrm{d}z'^2} + k'^4 \right) & k'^2 A_\beta & k'^2 A_\gamma \\ \frac{\partial s^{(0)}}{\partial z'} & \frac{1}{\textit{ReSc}_s} \left( k'^2 - \frac{\mathrm{d}^2}{\mathrm{d}z'^2} \right) & 0 \\ \frac{\partial \phi^{(0)}}{\partial z'} & 0 & \frac{1}{\textit{ReSc}_p} \left( k'^2 - \frac{\mathrm{d}^2}{\mathrm{d}z'^2} \right) - U'_{\mathsf{p}} \frac{\mathrm{d}}{\mathrm{d}z'} \end{pmatrix} \begin{pmatrix} \hat{u}_z \\ \hat{s} \\ \hat{\phi} \end{pmatrix} = i\omega \begin{pmatrix} \left( \frac{\mathrm{d}^2}{k'^2 - \mathrm{d}z'^2} \right) & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \hat{u}_z \\ \hat{s} \\ \hat{\phi} \end{pmatrix}$$

This is a generalised eigenvalue problem and is solved for the eigenvalue  $\omega=\Omega+i\sigma$ . Solutions where  $\sigma<0$  are unstable, and the associated growth rate is  $|\sigma|$ . We can therefore predict the fastest growing perturbation wavelength  $\lambda_{\max}=2\pi/k_{\max}$  which maximises  $|\sigma|$  for different values of the dimensionless parameters.

**Special case:** Rayleigh-Taylor instability

### Base states

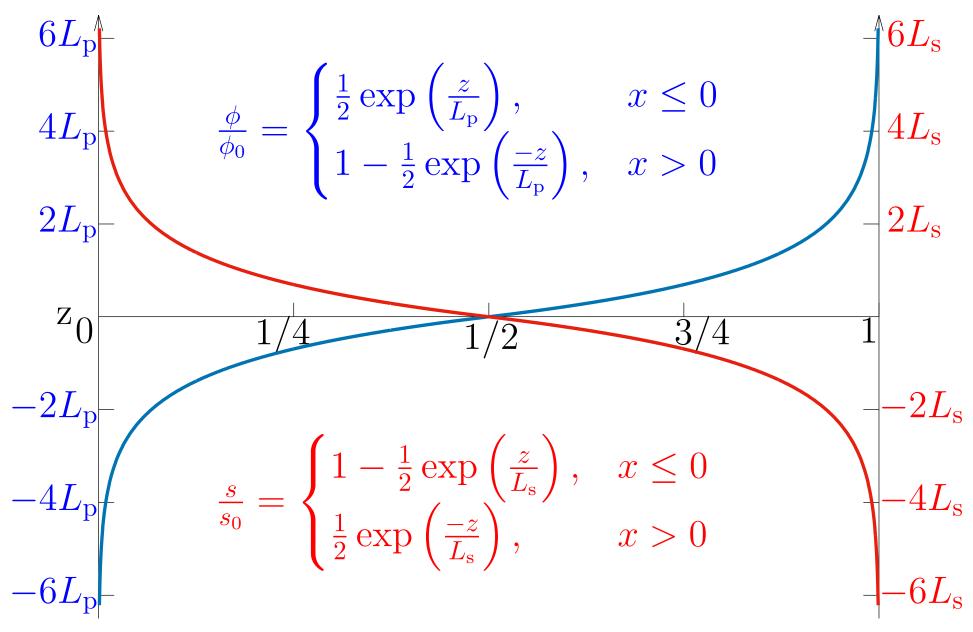


Figure 3. Choice of base states for the particle and solute concentrations. The transitions have length scales  $L_p$  and  $L_s$  respectively.

To validate the model, we consider the special case of a single phase  $(s_0=0)$  in the absense of a settling velocity  $(U_{\rm p}'=0)$ . This reduces the problem to that of the well studied Rayleigh-Taylor problem.

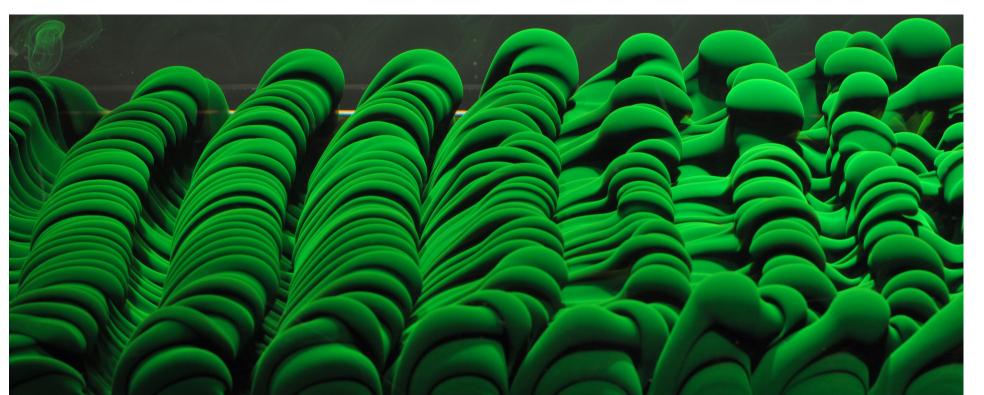
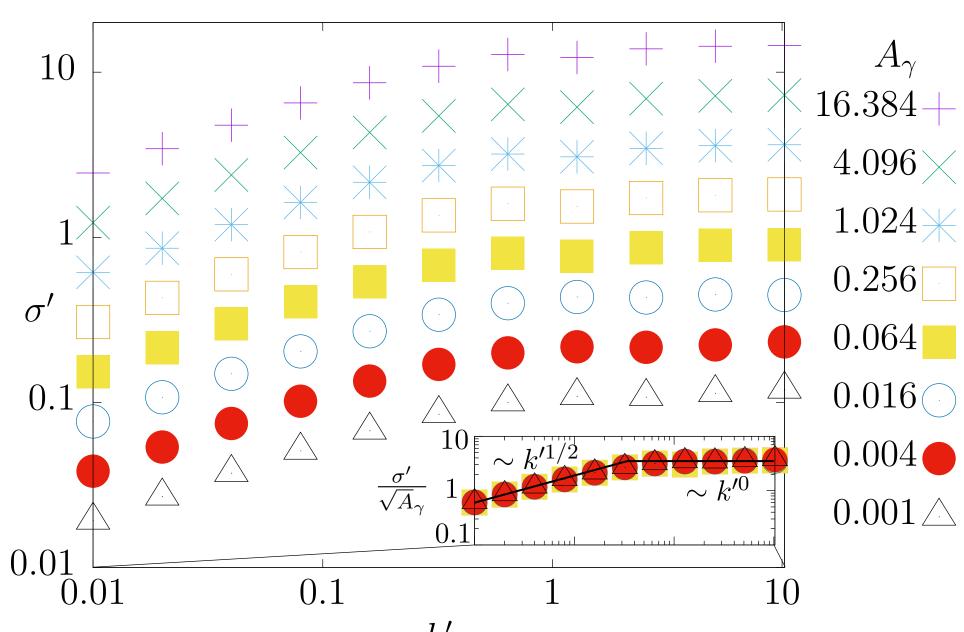


Figure 4. Experimentally produced Rayleigh-Taylor instability. The green fluid is lighter than the overlying clear fluid. Credit: Megan Davies Wykes

Choose sufficiently large  $Re(10^4)$  and  $Sc_{\rm p}(10^3)$  that system becomes independent of them



k' Figure 5. Dispersion relation showing that  $\sigma \sim A_{\gamma}$ . There are two regimes of k' dependence, when k' < 1,  $\sigma \sim k'^{1/2}$  and when k' > 1,  $\sigma \sim k'^0$ .

$$k' < 1 \quad (\lambda > 2\pi L_p)$$

$$k' > 1 \quad (\lambda < 2\pi L_{\mathsf{p}})$$

Wavelength is larger than the transition region. Scaling behaviour the same as for an infinitesimally thin transition zone.

Wavelength is shorter than the transition region. Growth rate independent of wavenumber.

$$\omega \sim \left( rac{gk
ho_{ extsf{p}}}{
ho_0} 
ight)^1$$

$$\omega \sim \left(\frac{g 
ho_{
m p}}{L_{
m p} 
ho_0}
ight)^{1/2}$$