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Modelling volcanic processes: volcanic plumes

Dr. Eduardo Rossi

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Outline of the lesson

What can we learn from the observation of Volcanic plumes in Nature?

The momentum-driven region

The buoyancy-driven region

Exercise 1: win a duck using Archimedes' law!

Empirical relations for MER vs. H

Modelling volcanic plumes

1D vs. 3D models

An example of 1D steady-state model

**Exercise 2: roll up your sleeves!
It is time for Matlab**



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Volcanic plumes in Nature



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A volcanic eruption: what you were used to see before this lesson



Photo credits: The Atlantic

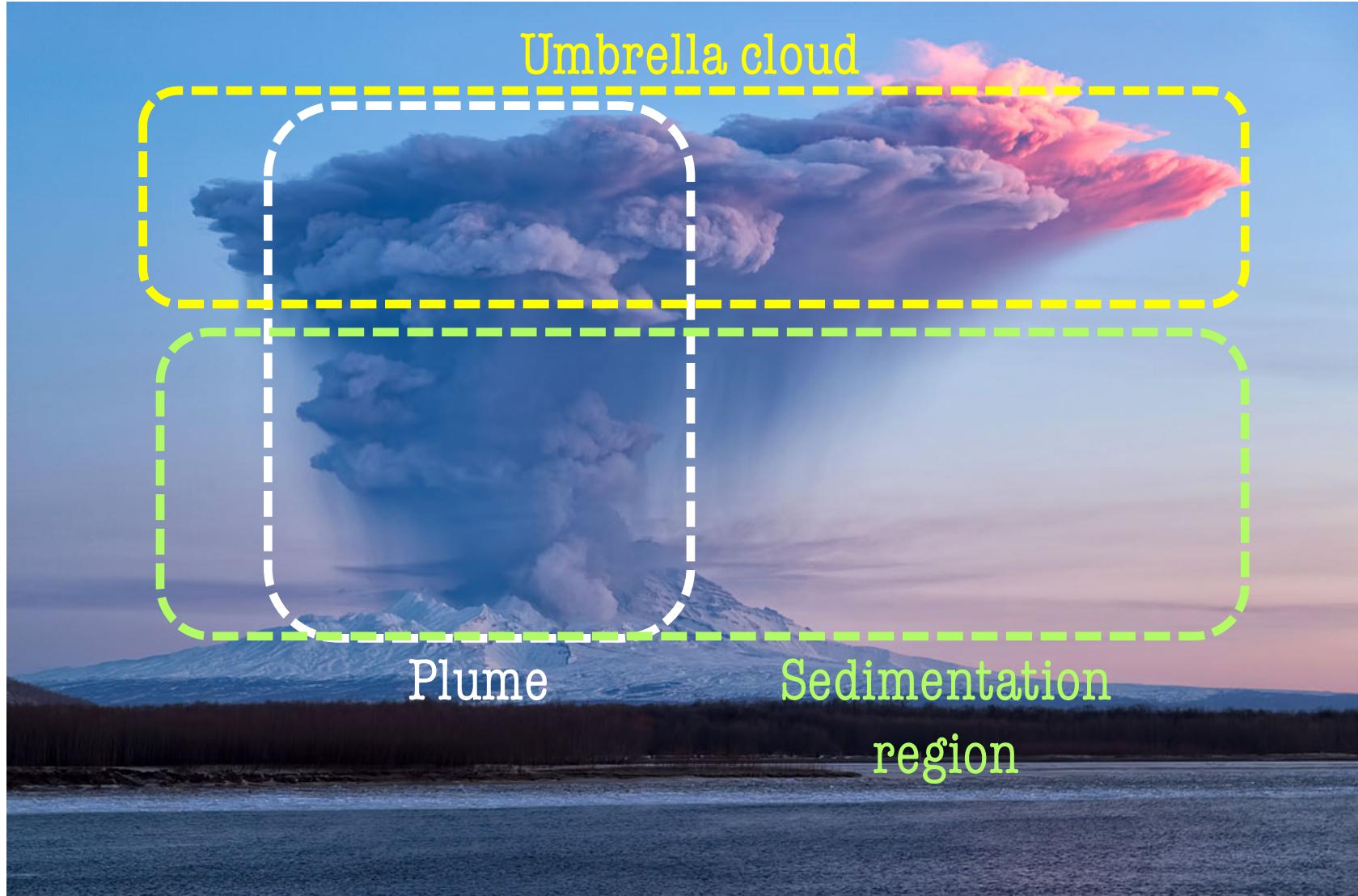
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A volcanic eruption: what you will see from now on!





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The focus of the present lesson: volcanic plumes

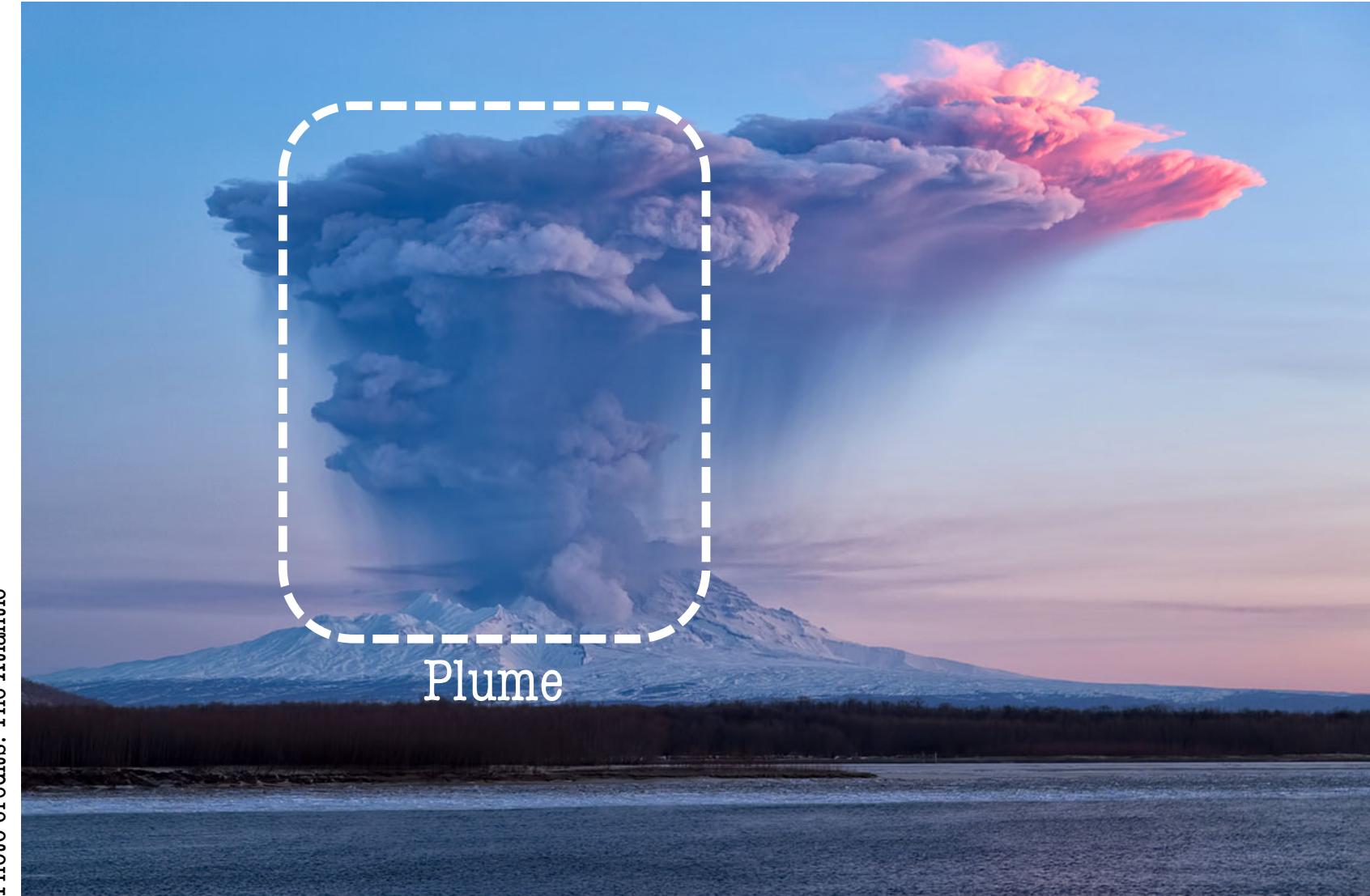


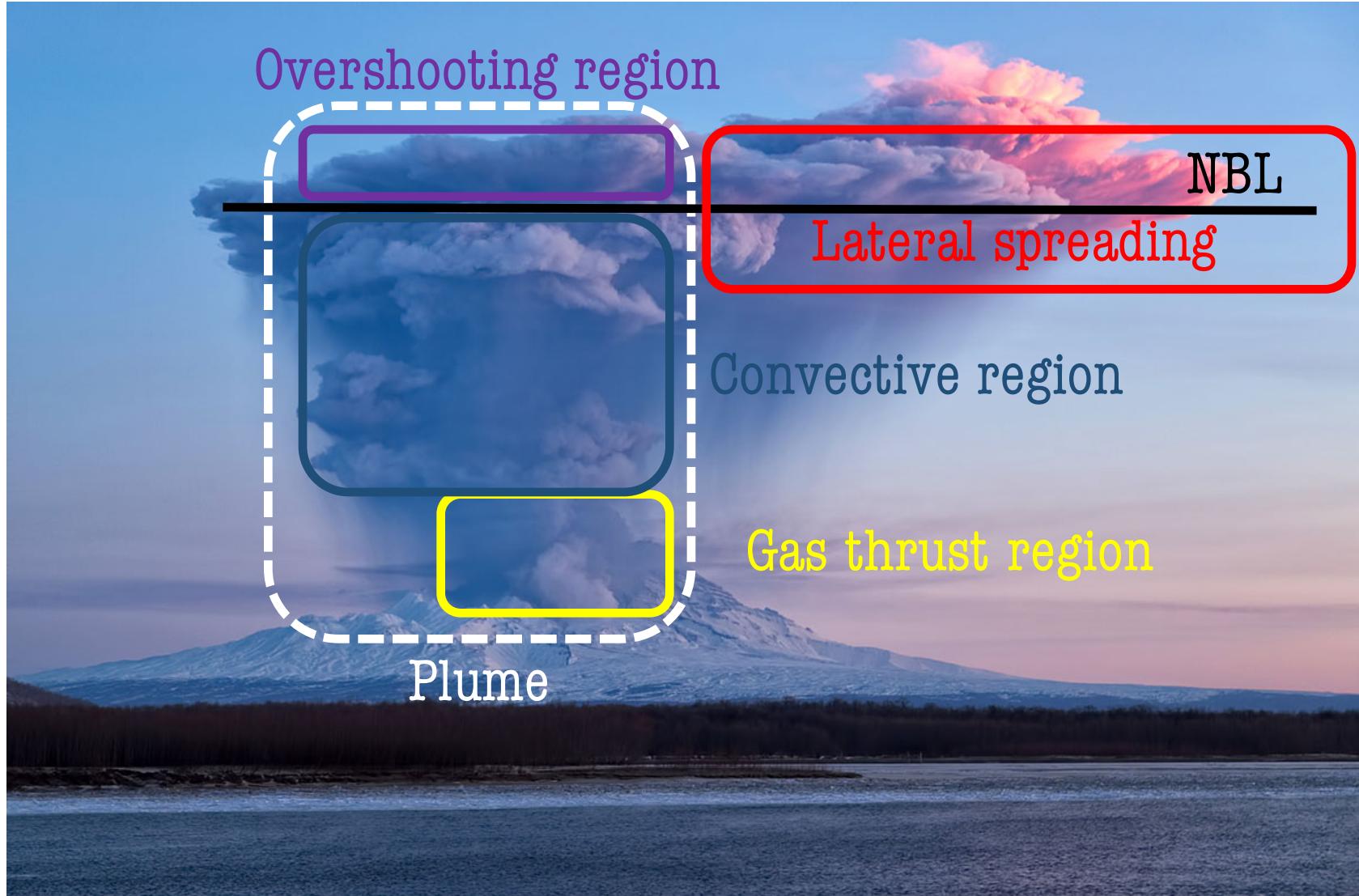
Photo credits: The Atlantic



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Three main regions: **gas thrust**, convective region, **overshooting**

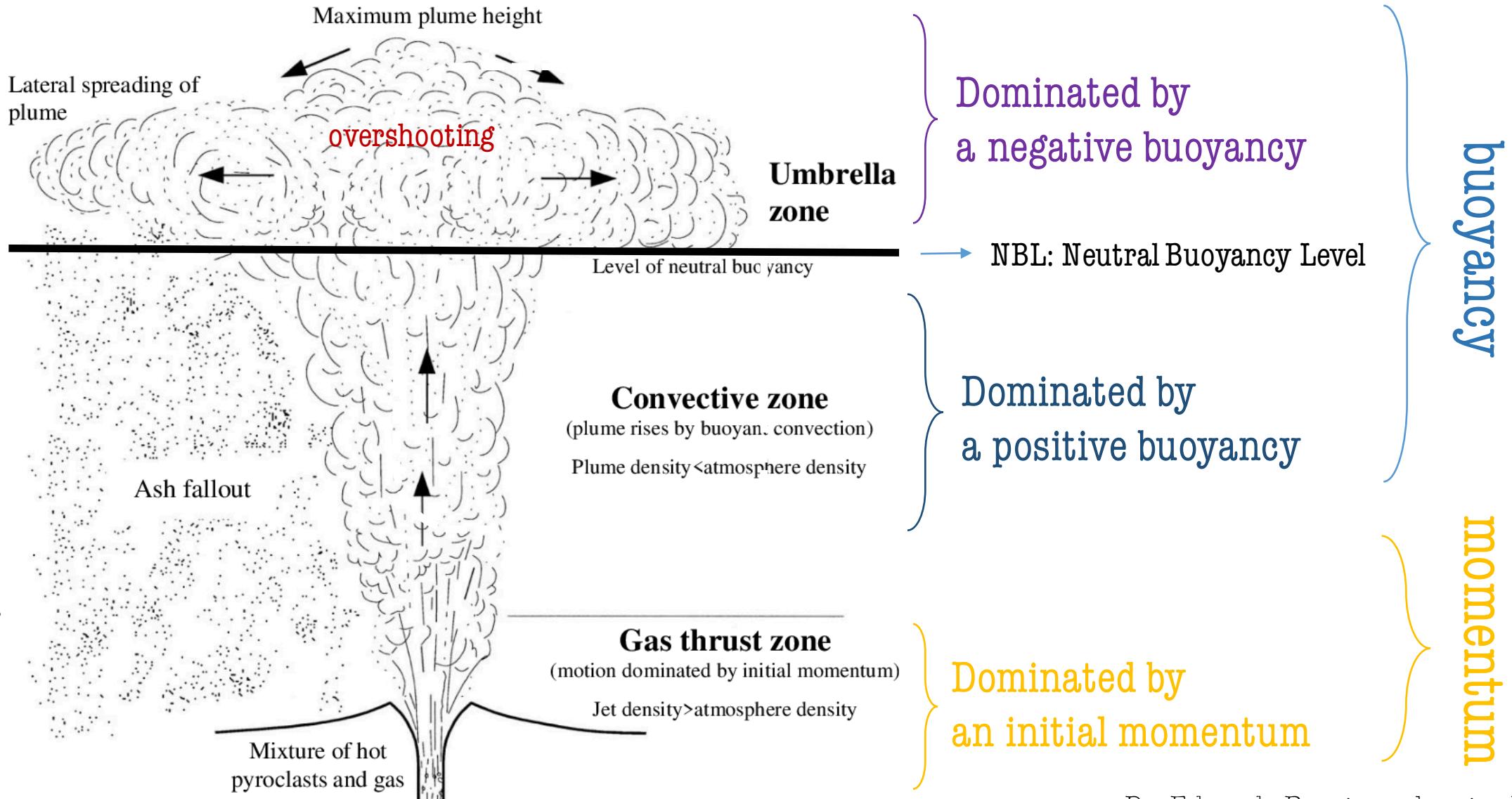




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Three main regions: **gas thrust**, **convective region**, **overshooting**

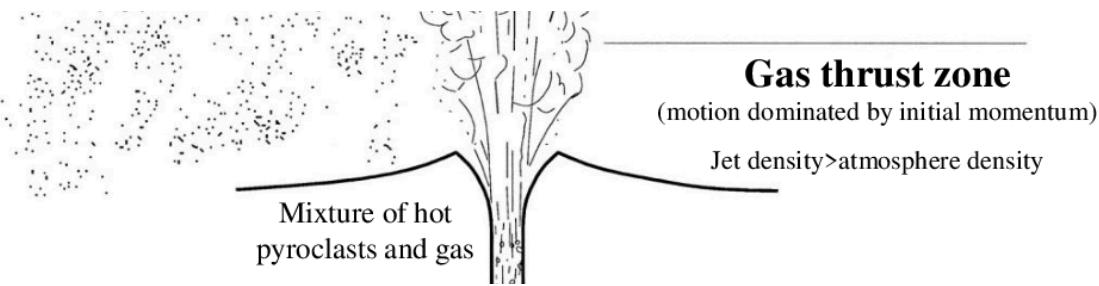




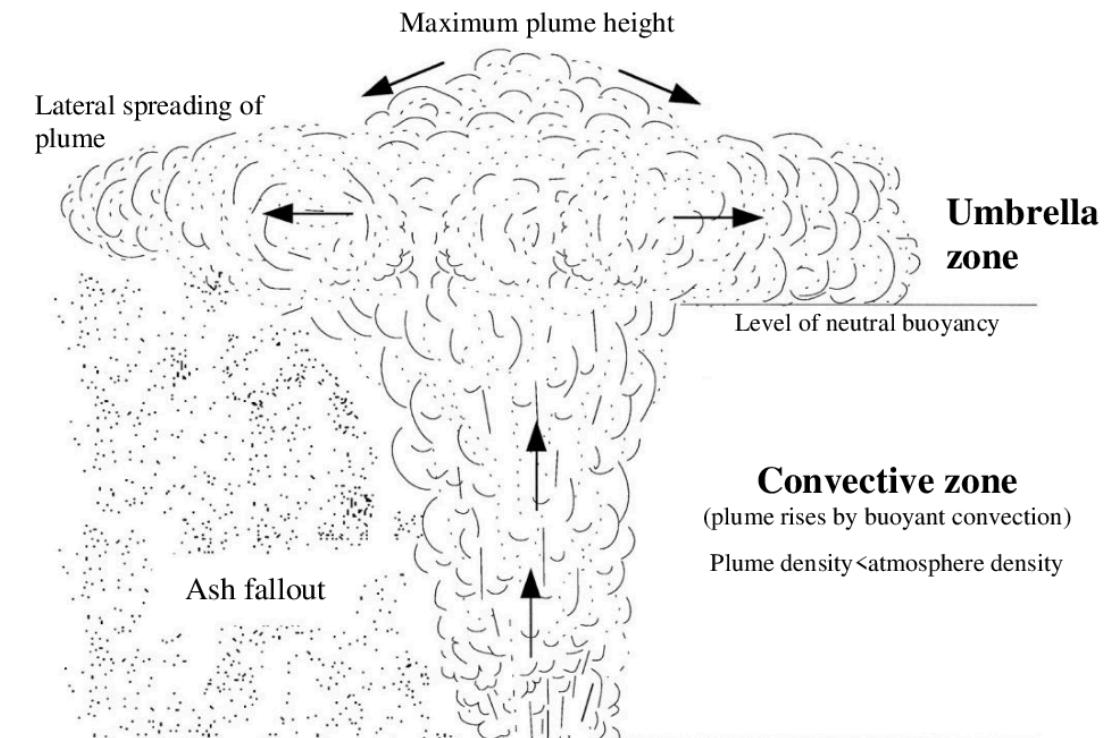
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Momentum



Buoyancy





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Momentum

Let me give you a practical example of what « momentum » is...



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Momentum

Let me give you a practical example of what « momentum » is...

$$\vec{p} = m \vec{v}$$



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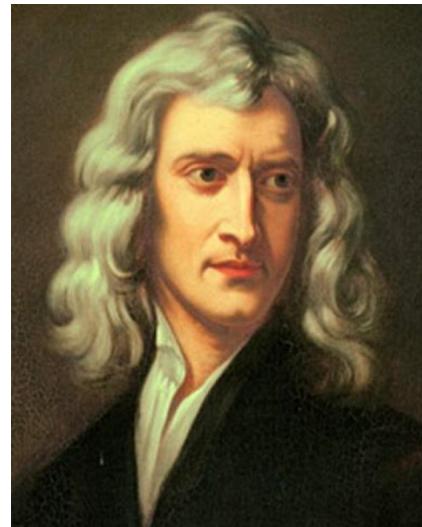
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Momentum

Let me give you a practical example of what « momentum » is...

$$\vec{p} = m \vec{v}$$
$$\frac{d\vec{p}}{dt} = \vec{F}_e$$

↑





Momentum

Let me give you a practical example of what « momentum » is...

$$\vec{p} = m \vec{v}$$
$$\frac{d\vec{p}}{dt} = \vec{F}_e$$

↑

if $\vec{F}_e = 0 \rightarrow \frac{d\vec{p}}{dt} = 0 \rightarrow \vec{p} = \text{const}$



$$m_{\text{before}} \vec{v}_{\text{before}} = m_{\text{after}} \vec{v}_{\text{after}}$$



Momentum

Something that will be important for volcanic plumes: what if the mass changes?

$$\vec{p} = m \vec{v} \quad \frac{d\vec{p}}{dt} = \vec{F}_e$$

Some algebra and derivatives later...

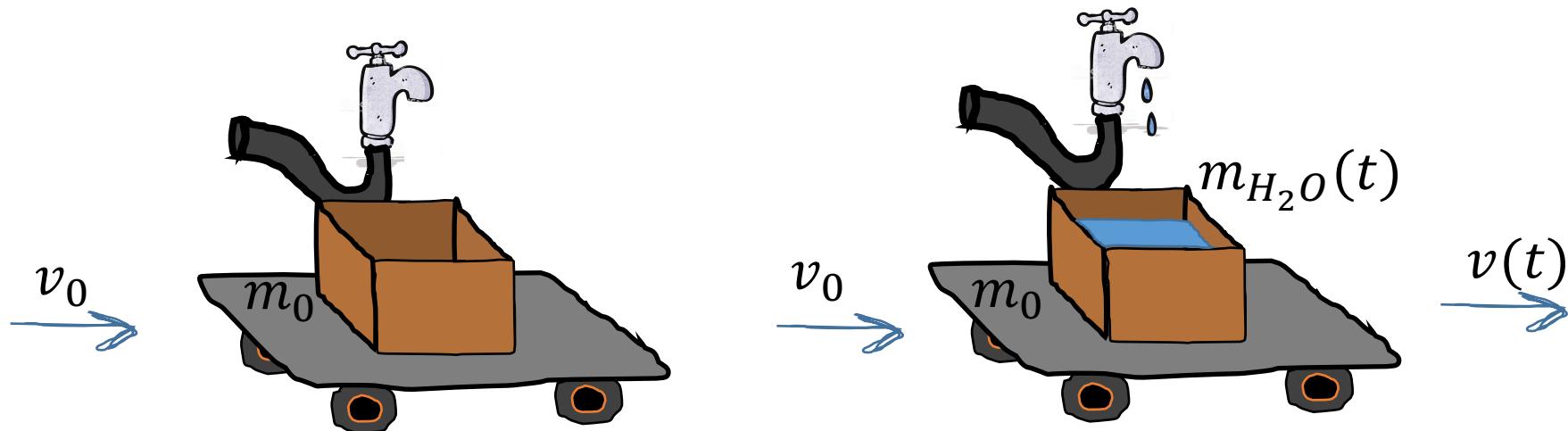
$$\frac{d\vec{p}}{dt} = \frac{d(m \vec{v})}{dt} = \frac{d(m \vec{v})}{dt} = \vec{v} \frac{d(m)}{dt} + m \frac{d(\vec{v})}{dt} = \vec{v} \frac{d(m)}{dt} + m \vec{a}$$

$$\frac{d\vec{p}}{dt} = \vec{F}_e \rightarrow \boxed{\vec{v} \frac{d(m)}{dt} + m \vec{a} = \vec{F}_e}$$



Momentum

$$\frac{d\vec{p}}{dt} = \vec{F}_e \rightarrow \vec{v} \frac{d(m)}{dt} + m\vec{a} = \vec{F}_e$$



Let assume no friction on the wheels and a given law for the water flow (i.e. $\frac{d(m)}{dt} = \lambda$)

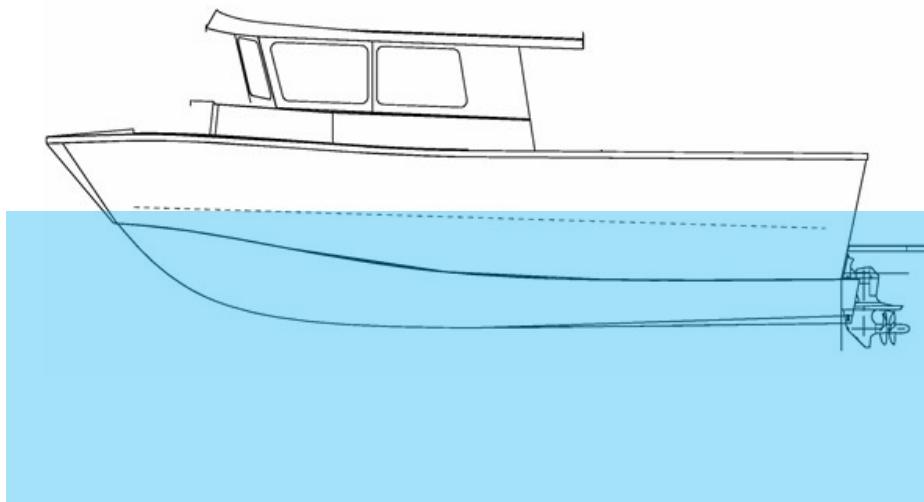
$$\vec{v} \frac{d(m)}{dt} + m \frac{d(\vec{v})}{dt} = 0 \rightarrow \frac{v}{v_0} = \frac{m_0}{(m_0 + \lambda \cdot t)}$$



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Buoyancy

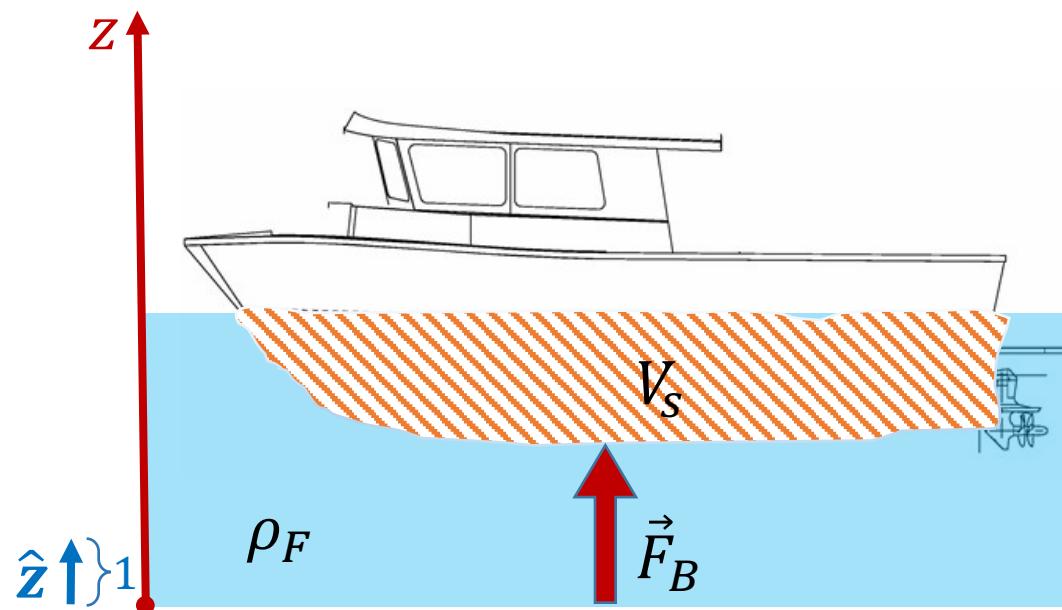




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Buoyancy

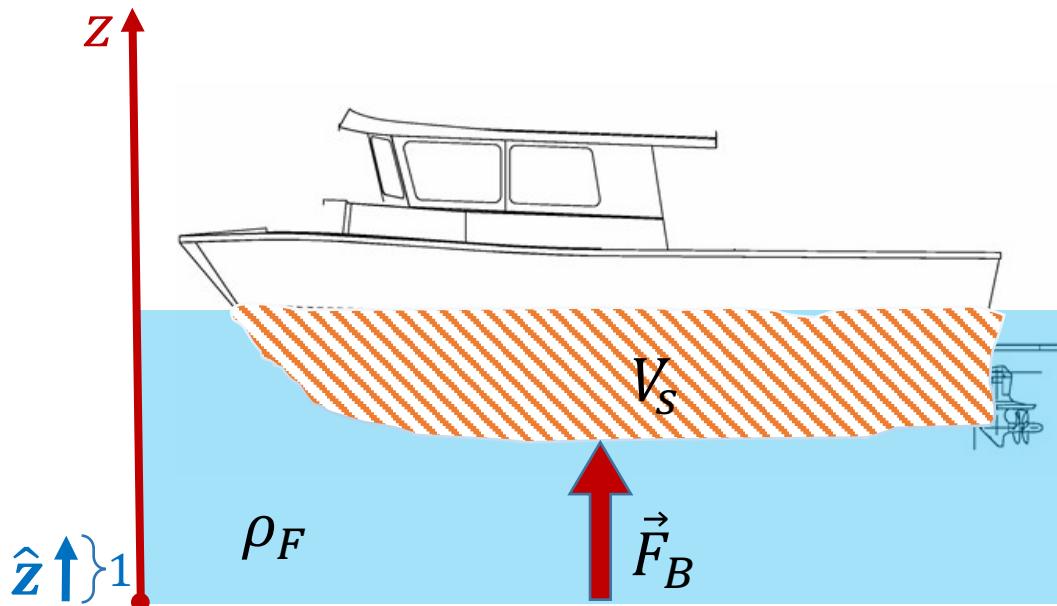




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Buoyancy

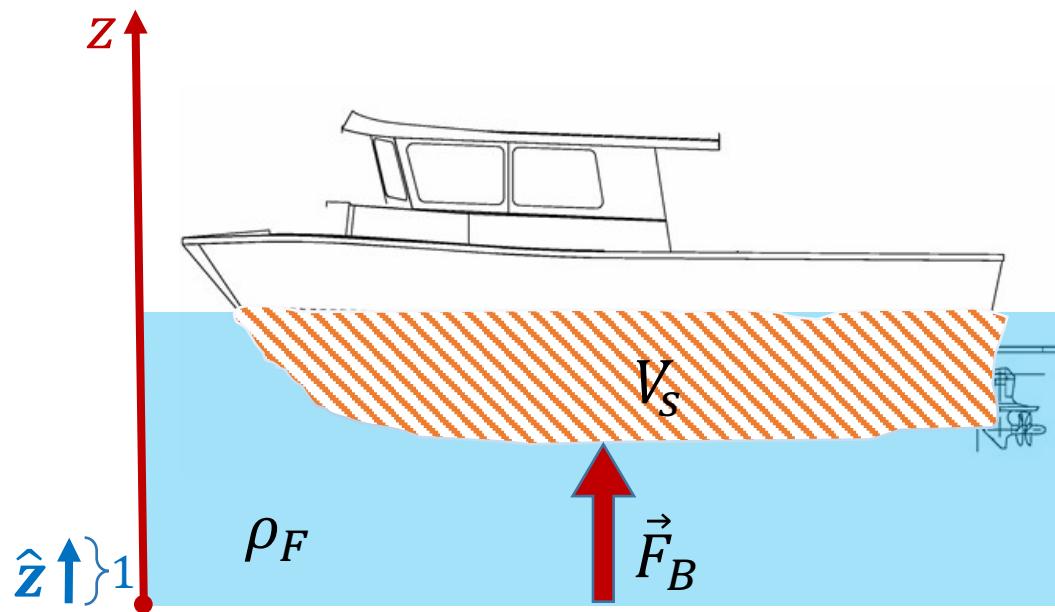


Archimedes' principle

$$\vec{F}_B = F_B \hat{\mathbf{z}} = V_s \rho_F g \hat{\mathbf{z}}$$



Buoyancy



Archimedes' principle

$$\vec{F}_B = F_B \hat{\mathbf{z}} = V_s \rho_F g \hat{\mathbf{z}}$$

Buoyancy

$$a \hat{\mathbf{z}} = -g \left[1 - \frac{\rho_F}{\rho_p} \right] \hat{\mathbf{z}}$$

Buoyancy is the force related to a difference in density between the fluid and the surroundings. It can be upward or downward!



Buoyancy

Newton's law
of motion
(on a fluid element)

No acceleration
within the fluid

Hydrostatic pressure

$$\frac{\partial P}{\partial z} \hat{\mathbf{z}} = -\rho_F(z) \cdot g \hat{\mathbf{z}}$$

Barometric decay

$$\rho_F = f(P, T) \\ (\text{perfect gas})$$

Stevin's law
 ρ_F is constant

Pressure gradient in the fluid $\Delta P = \rho_F \cdot g \cdot h$

Newton's law
of motion
(on an object)

The acceleration
of the body
is unknown

Archimede's principle

$$\vec{F}_B = F_B \hat{\mathbf{z}} = V_s \rho_F g \hat{\mathbf{z}}$$

Buoyancy

$$\rightarrow a \hat{\mathbf{z}} = -g \left[1 - \frac{\rho_F}{\rho_p} \right] \hat{\mathbf{z}}$$



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Exercise 1: raffling a duck



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Buoyancy

Let me tell you a story...Do you know Banksy, the famous graffiti artist?



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Buoyancy

The Banksy raffle for Christmas 2018: this masterpiece is yours if you guess its...weight!



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Buoyancy

The Banksy raffle for Christmas 2018: this masterpiece is yours if you guess its...weight!

Actual mass 11.7 kg

My guess 13.2 kg

I lost 😞



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Buoyancy

The “Rossi raffle for Christmas 2019”: this floating duck is yours if you guess its...total weight!



$m_{duck?}$

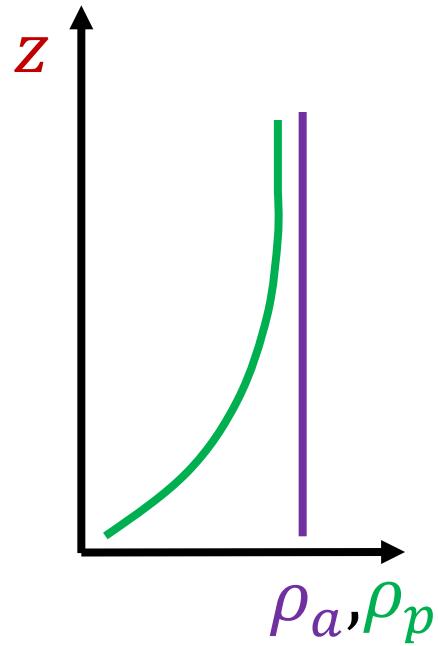


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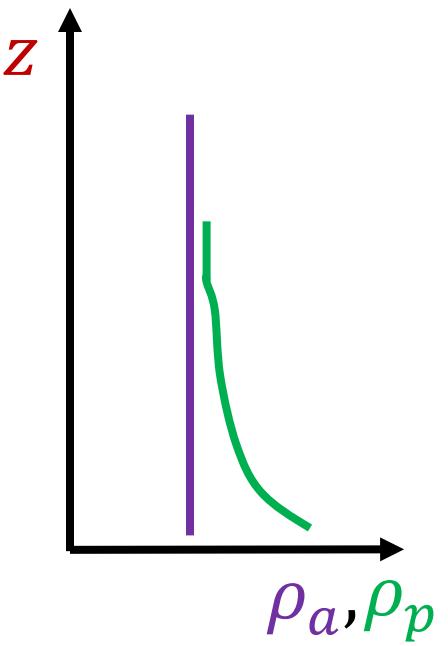
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Plume density vs. atmospheric density

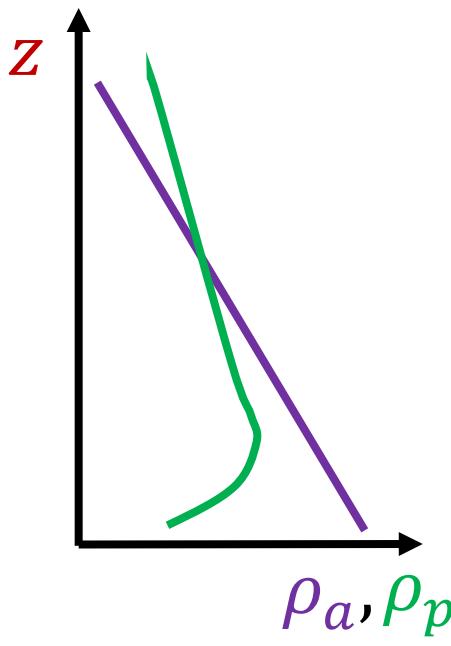
If you understood buoyancy...what can you say about these five profiles?



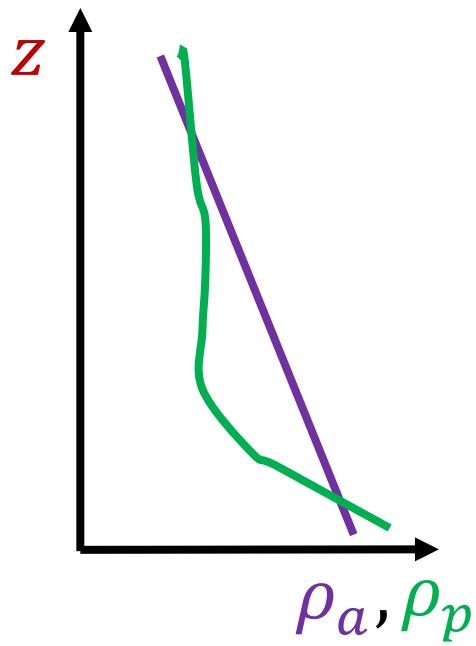
(a)



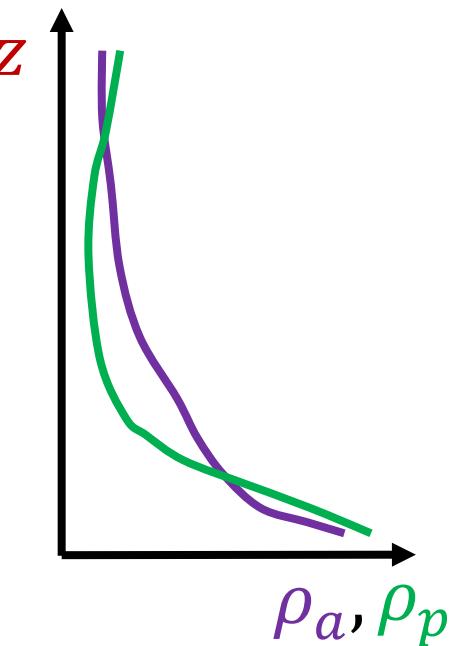
(b)



(c)



(d)



(e)

Atmospheric
density



Volcanic plume
density



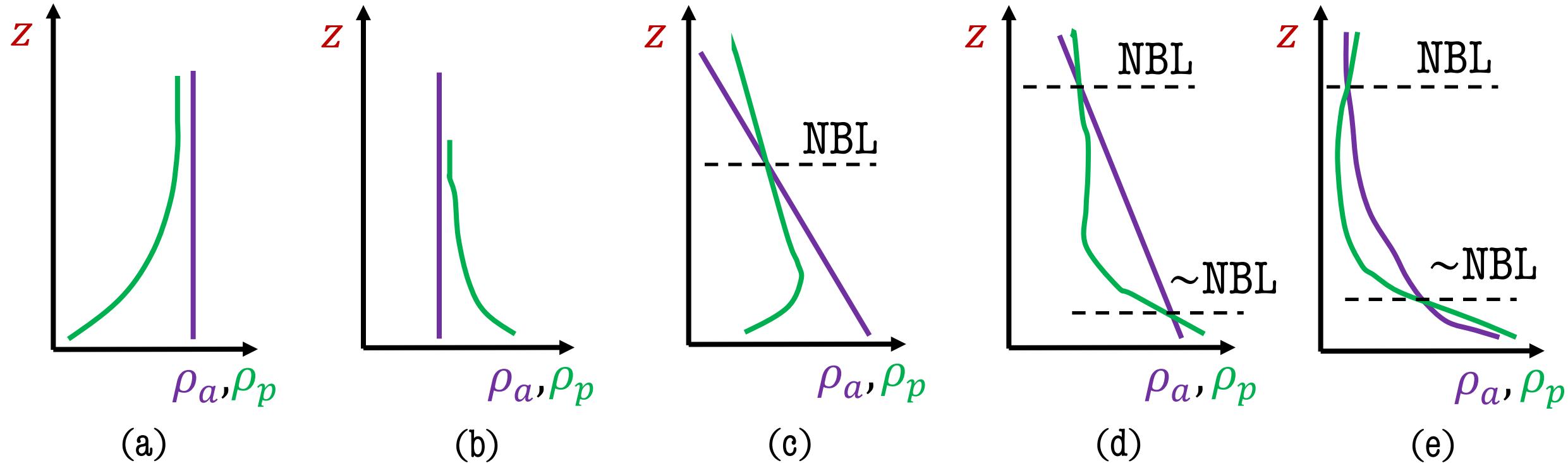


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Plume density vs. atmospheric density

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Atmospheric
density



Volcanic plume
density

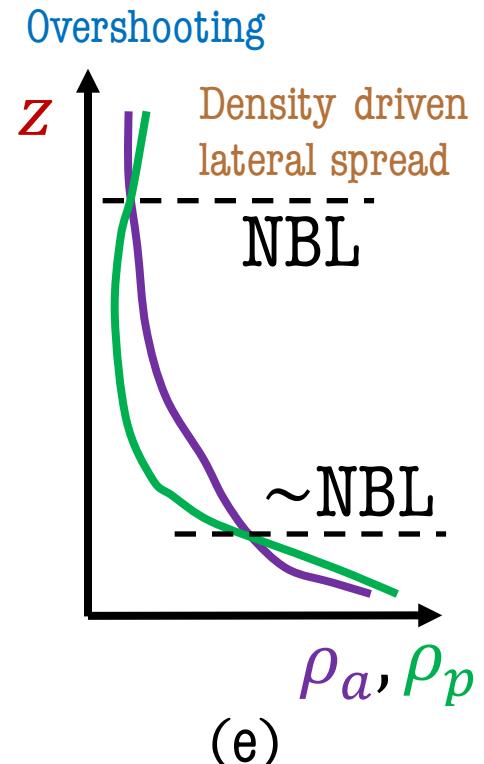
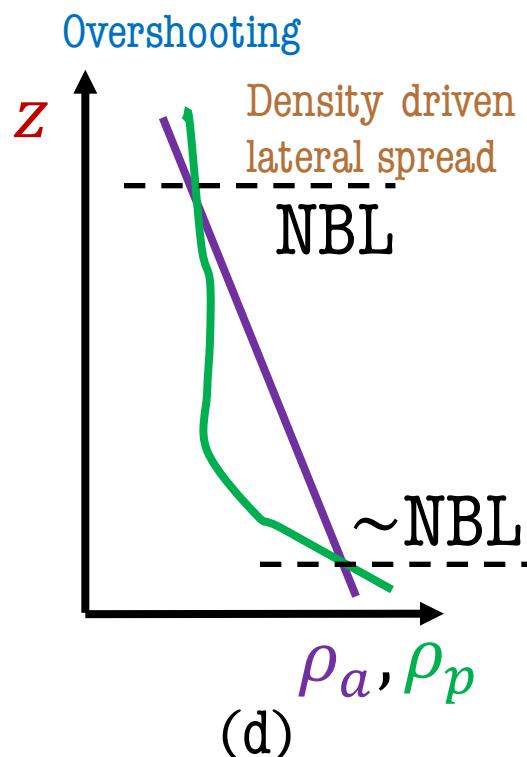


NBL: $\rho_a = \rho_p$



Plume density vs. atmospheric density

Overshooting and lateral spreading driven by density differences (cloud)

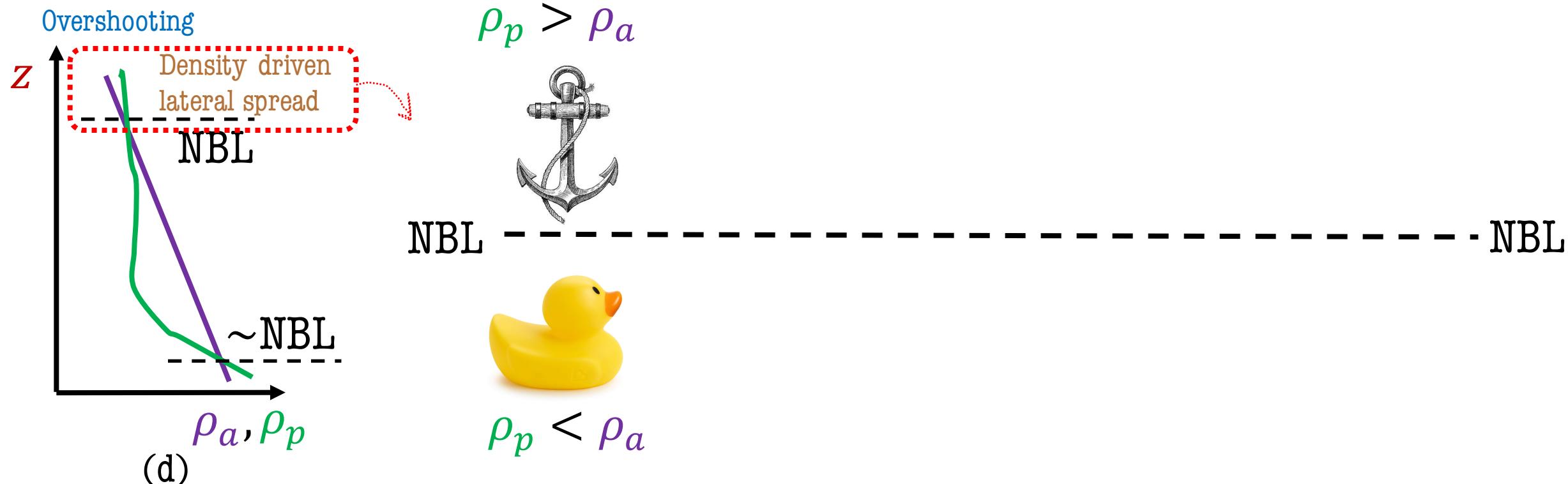


Atmospheric density NBL: $\rho_a = \rho_p$
Volcanic plume density



Plume density vs. atmospheric density

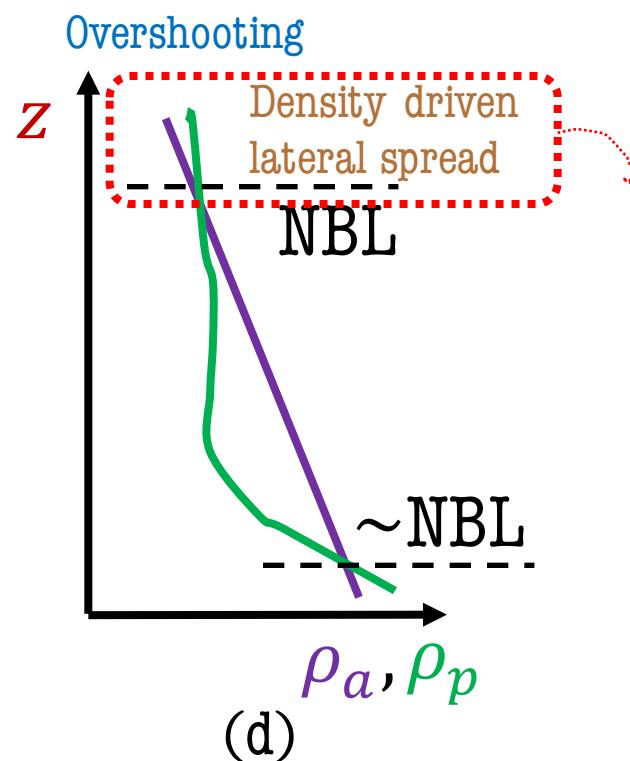
Overshooting and lateral spreading driven by density differences (cloud)





Plume density vs. atmospheric density

Overshooting and lateral spreading driven by density differences (cloud)



$$\rho_p > \rho_a$$



NBL

NBL



$$\rho_p < \rho_a$$



Continuous
injection
of mass

Atmospheric density



Volcanic plume density

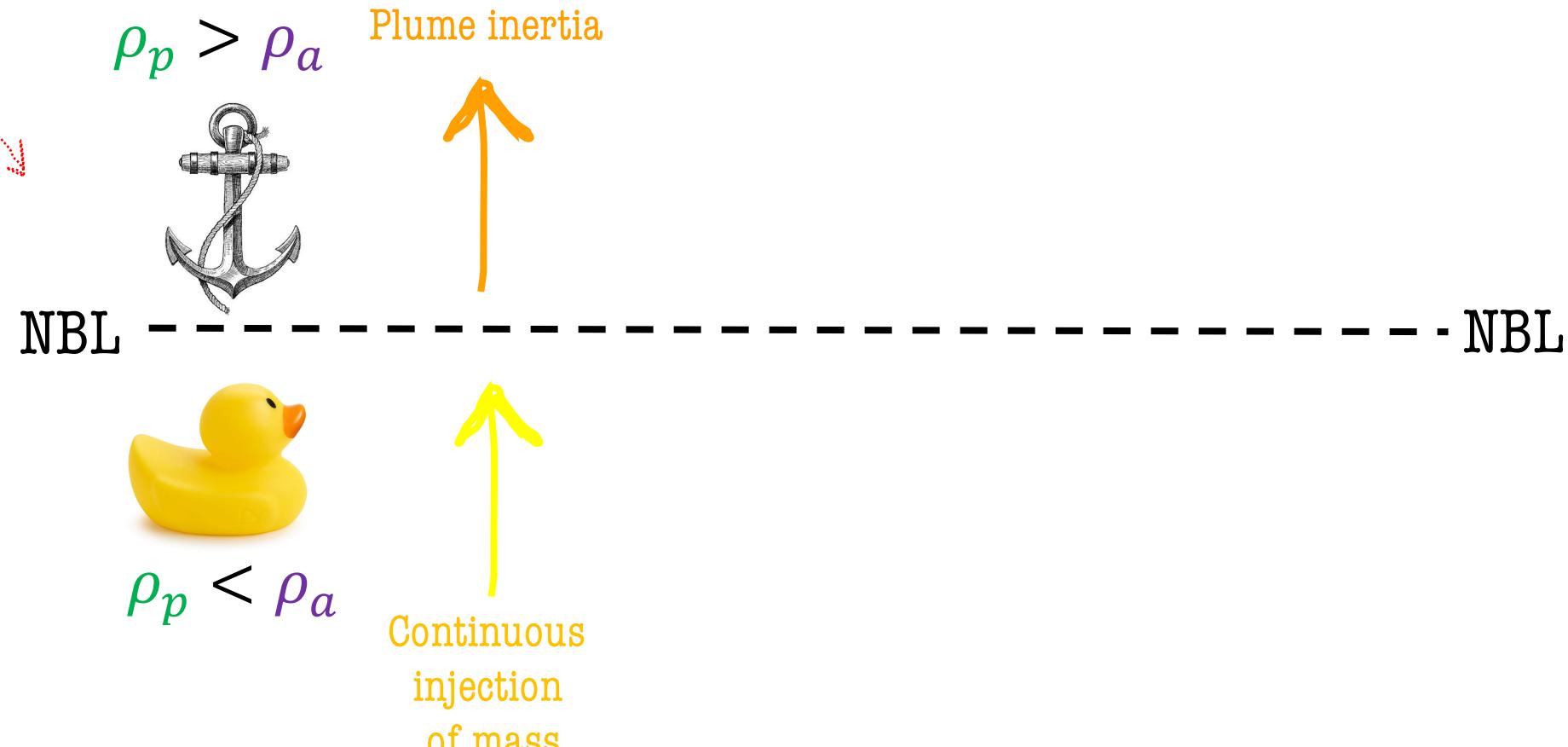
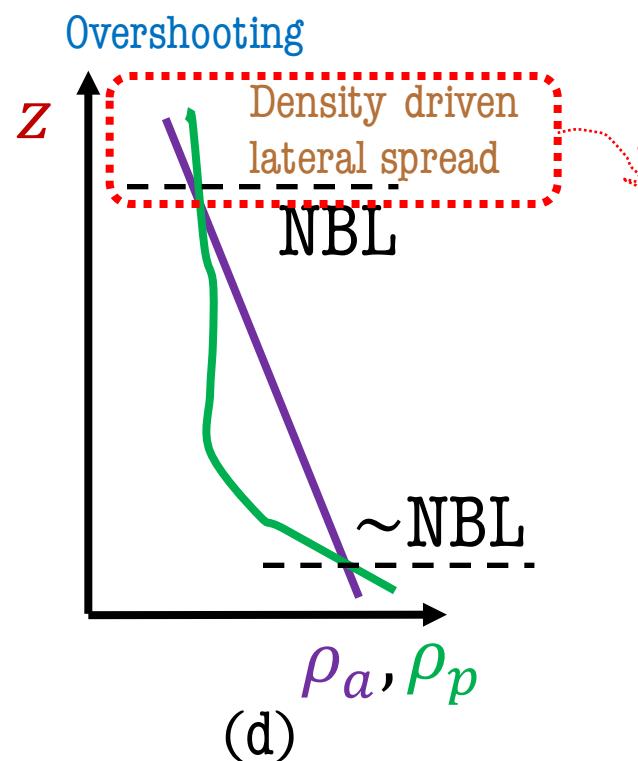


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Volcanic plume density

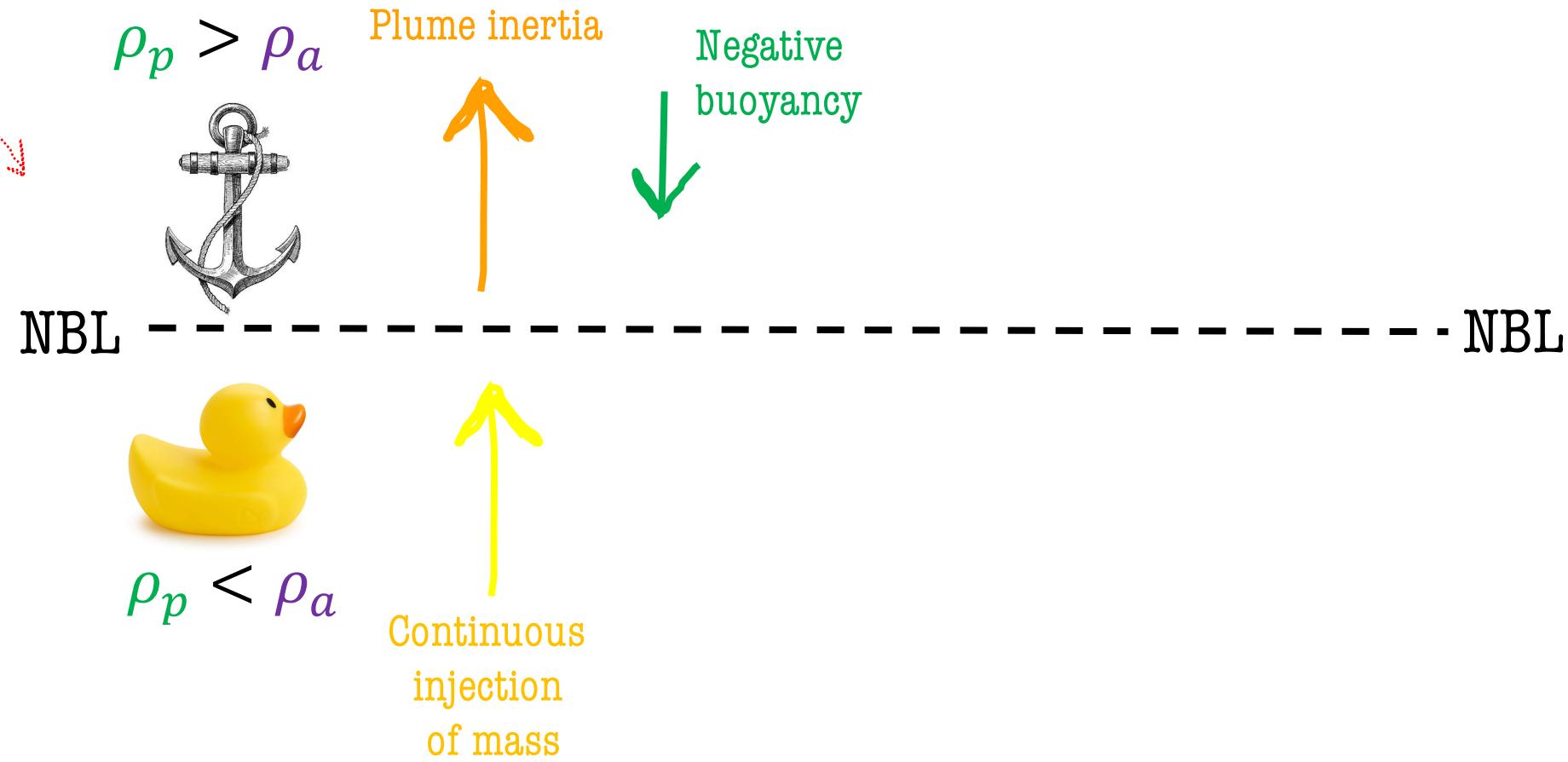
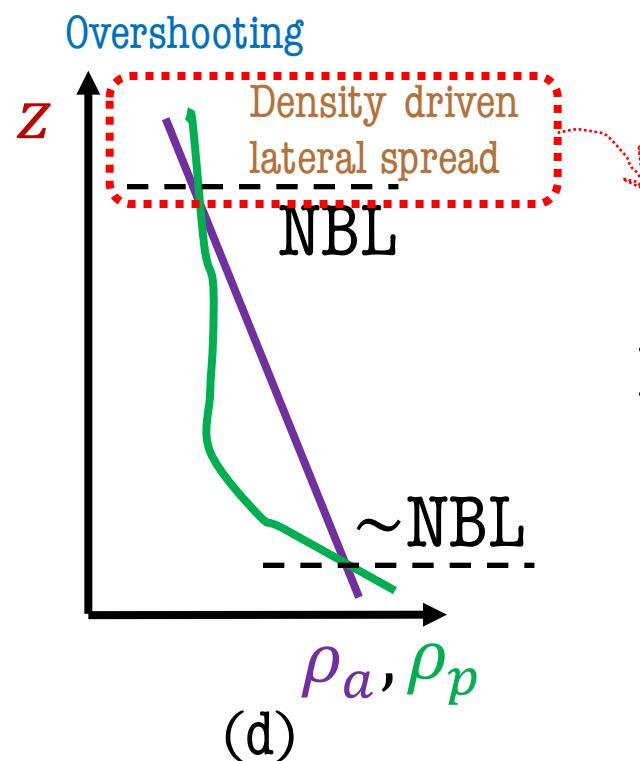


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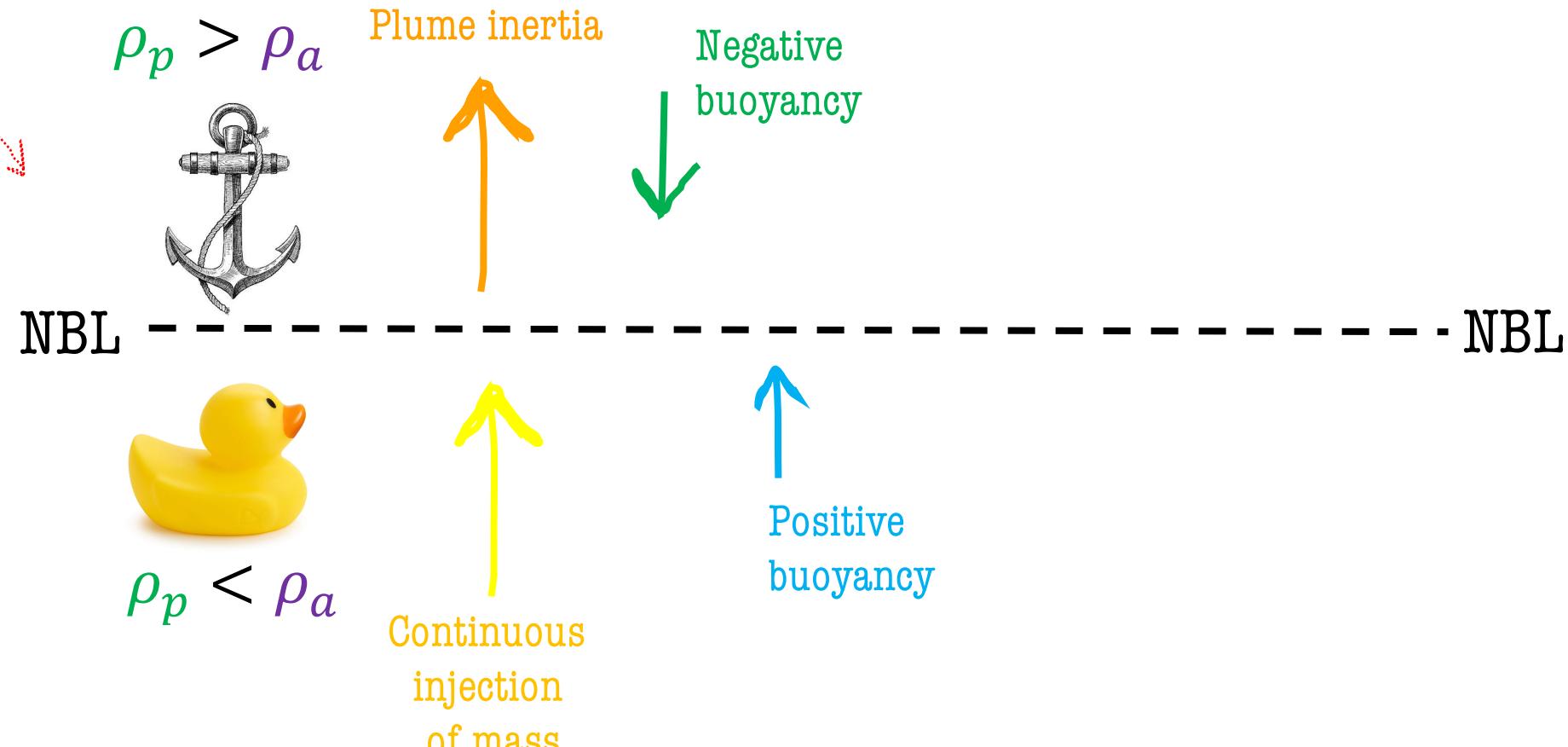
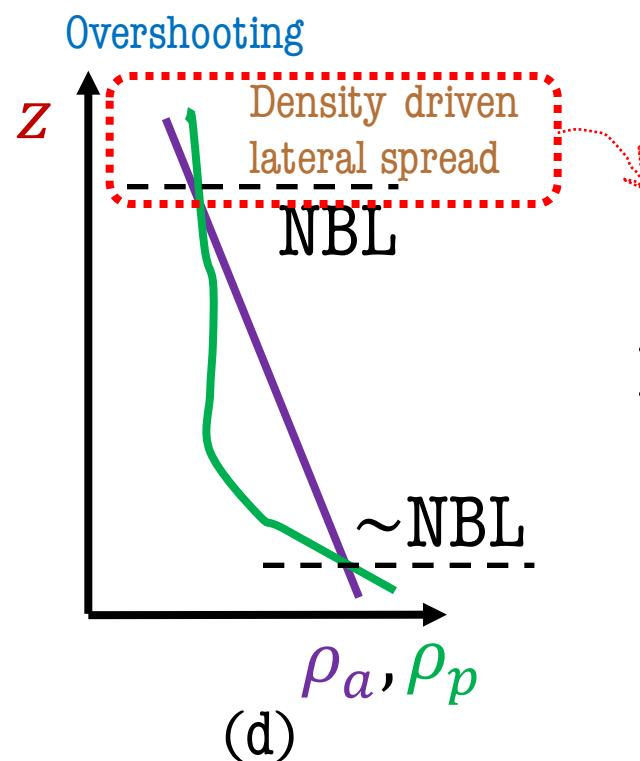
Atmospheric density
Volcanic plume density

$$\text{NBL: } \rho_a = \rho_p$$



Plume density vs. atmospheric density

Overshooting and lateral spreading driven by density differences (cloud)



Atmospheric density



Volcanic plume density

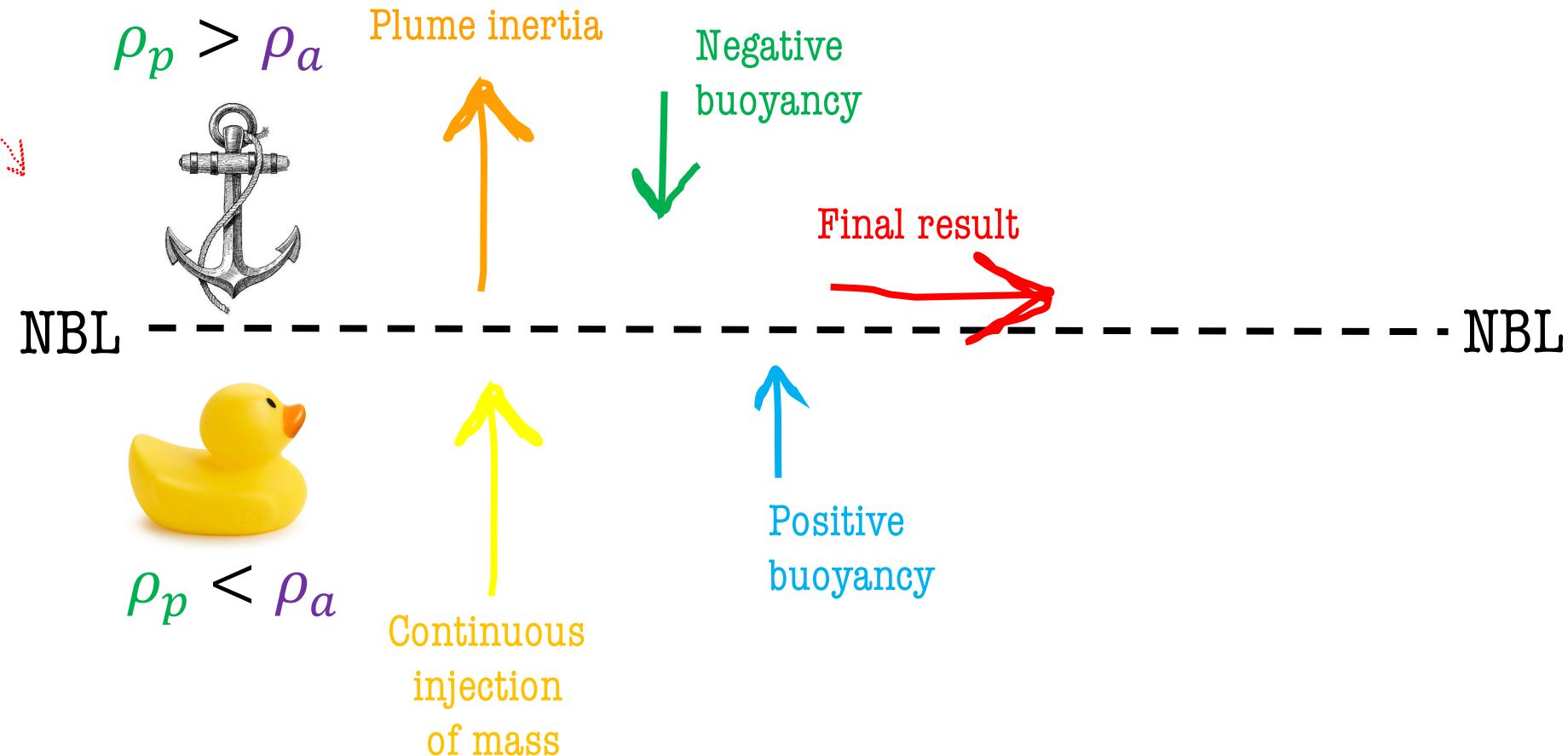
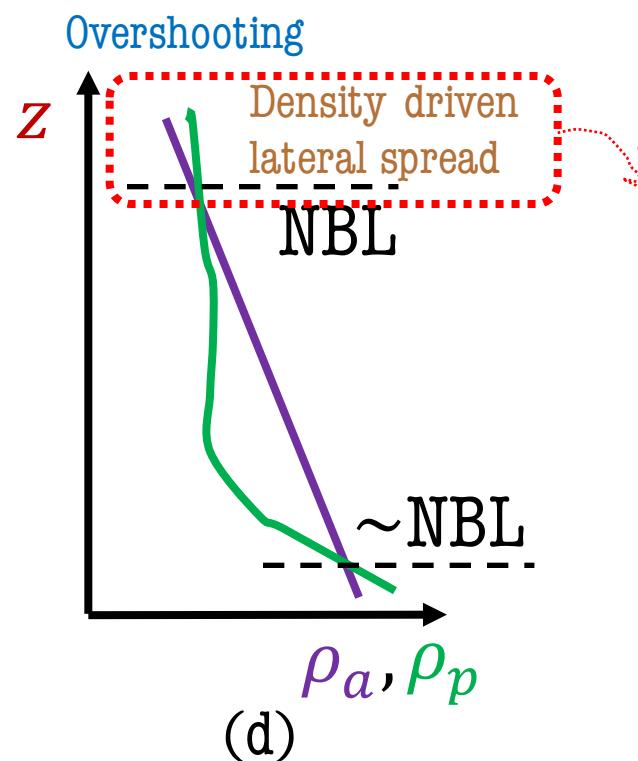


NBL: $\rho_a = \rho_p$



Plume density vs. atmospheric density

Overshooting and lateral spreading driven by density differences (cloud)



Atmospheric density



Volcanic plume density

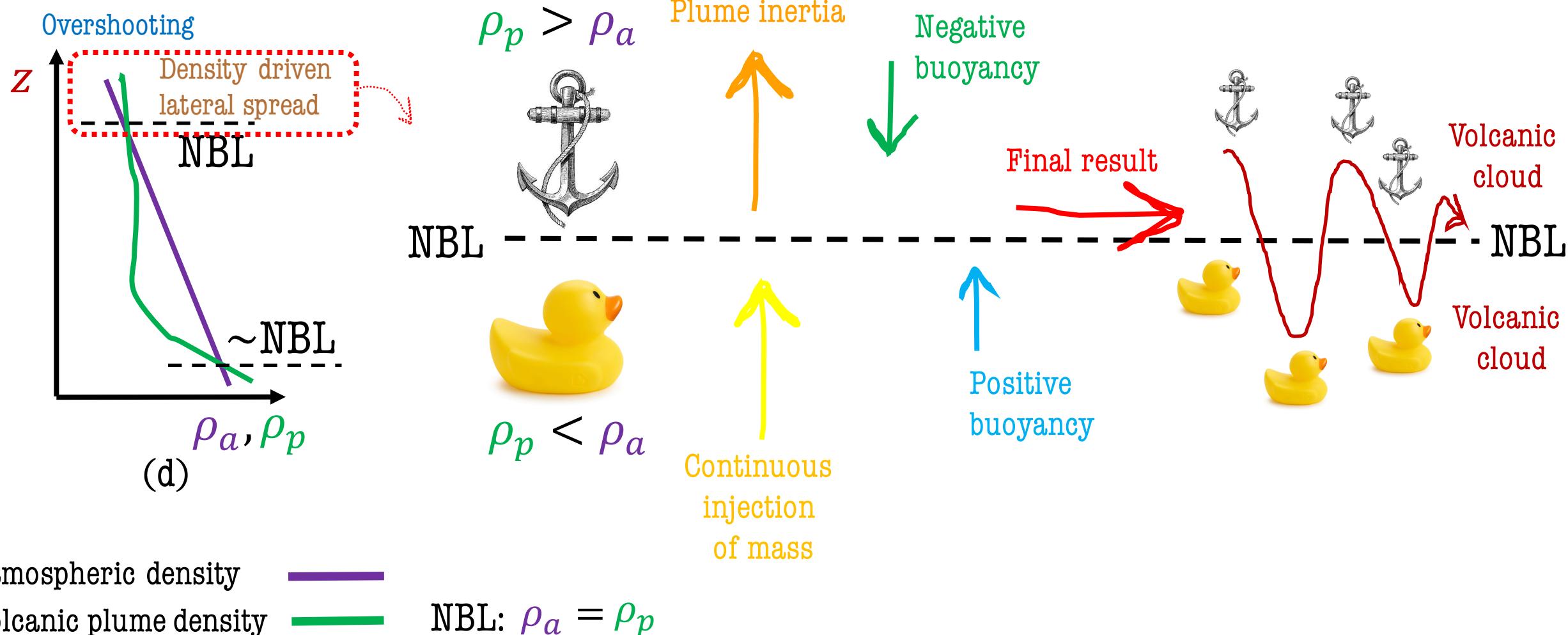


NBL: $\rho_a = \rho_p$



Plume density vs. atmospheric density

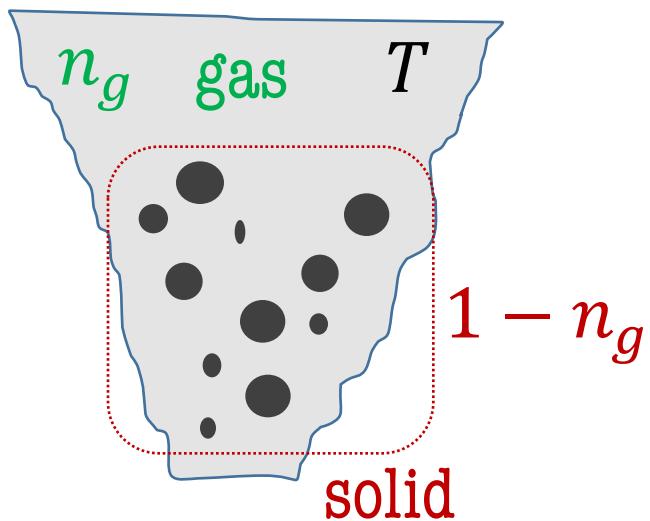
Overshooting and lateral spreading driven by density differences (cloud)





Plume density vs. atmospheric density

What are the important parameters affecting the volcanic gas mixture in the plume?



$$\rho_{plume} = \left(\frac{1 - n_g}{\rho_s} + \frac{n_g R_g T}{P_g} \right)^{-1}$$

n_g = Mass fraction of gas phase

R_g = Gas constant for perfect gases

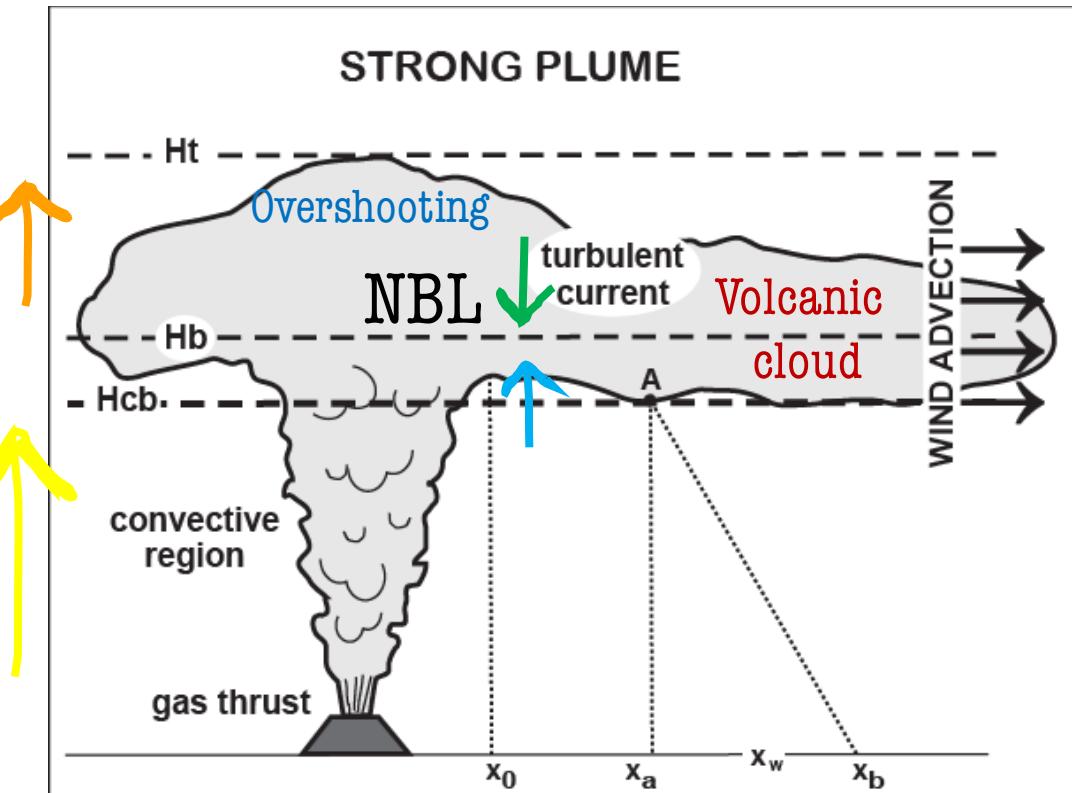
P_g = Pressure of the mixture

ρ_s = Solid particles density



Plume density vs. atmospheric density

The effect of the wind: strong plumes vs. weak plumes

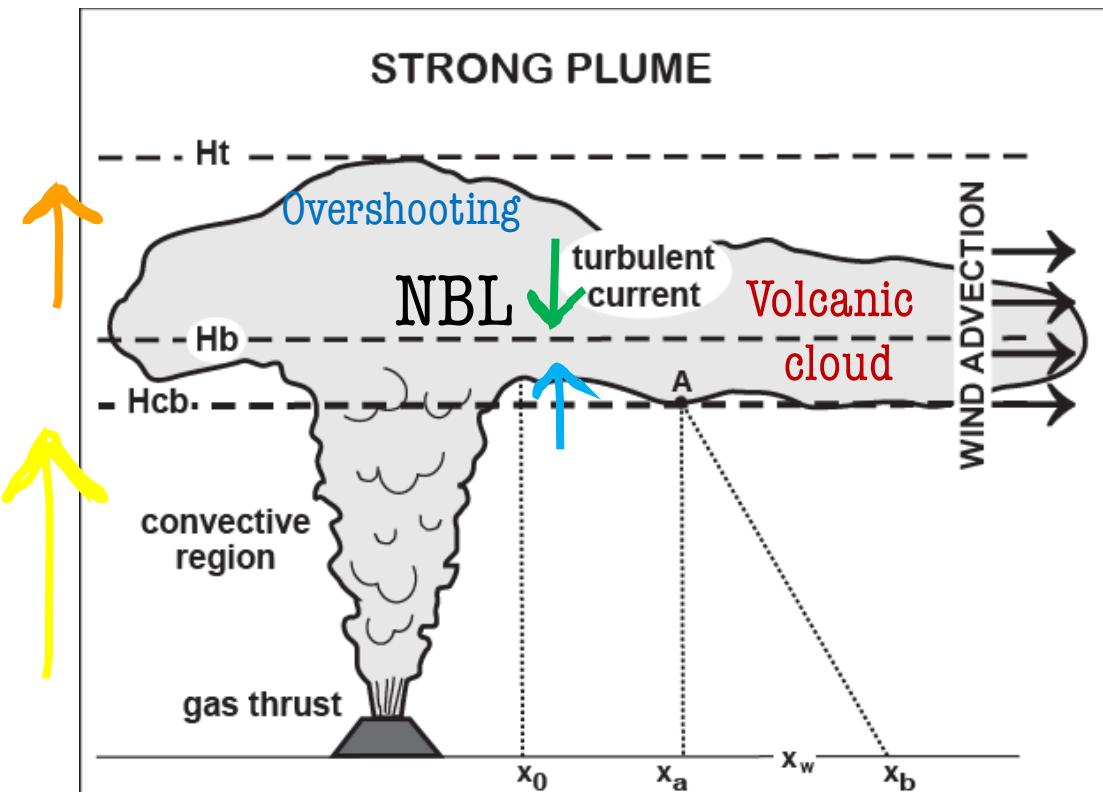


PLUME > wind

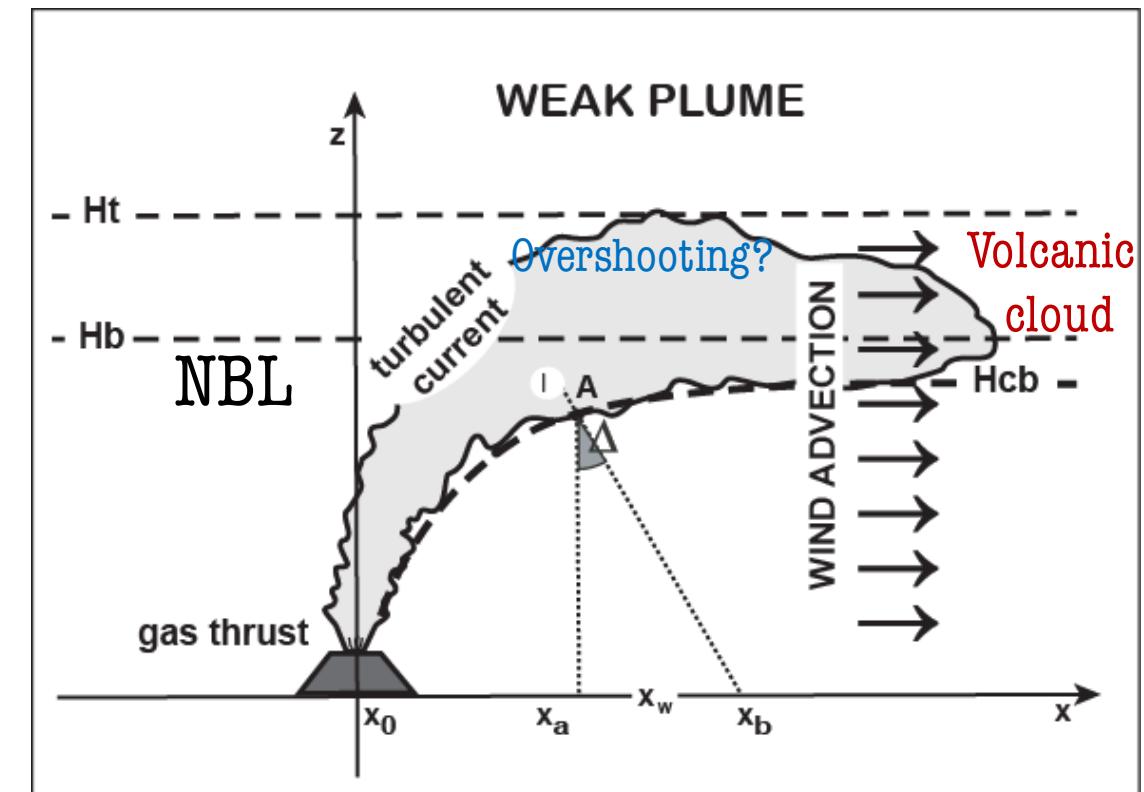


Plume density vs. atmospheric density

The effect of the wind: strong plumes vs. weak plumes



PLUME > wind



Plume < WIND



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Plume tipologies

An instantaneous release of positive buoyancy (Vulcanian explosion)



Anak Krakatau volcano (Indonesia)



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Plume typologies

A continuous release of positive buoyancy (steady-state eruptions)



Eyafjatljokull (Iceland)



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Plume typologies

A completely/partially negative buoyant plume

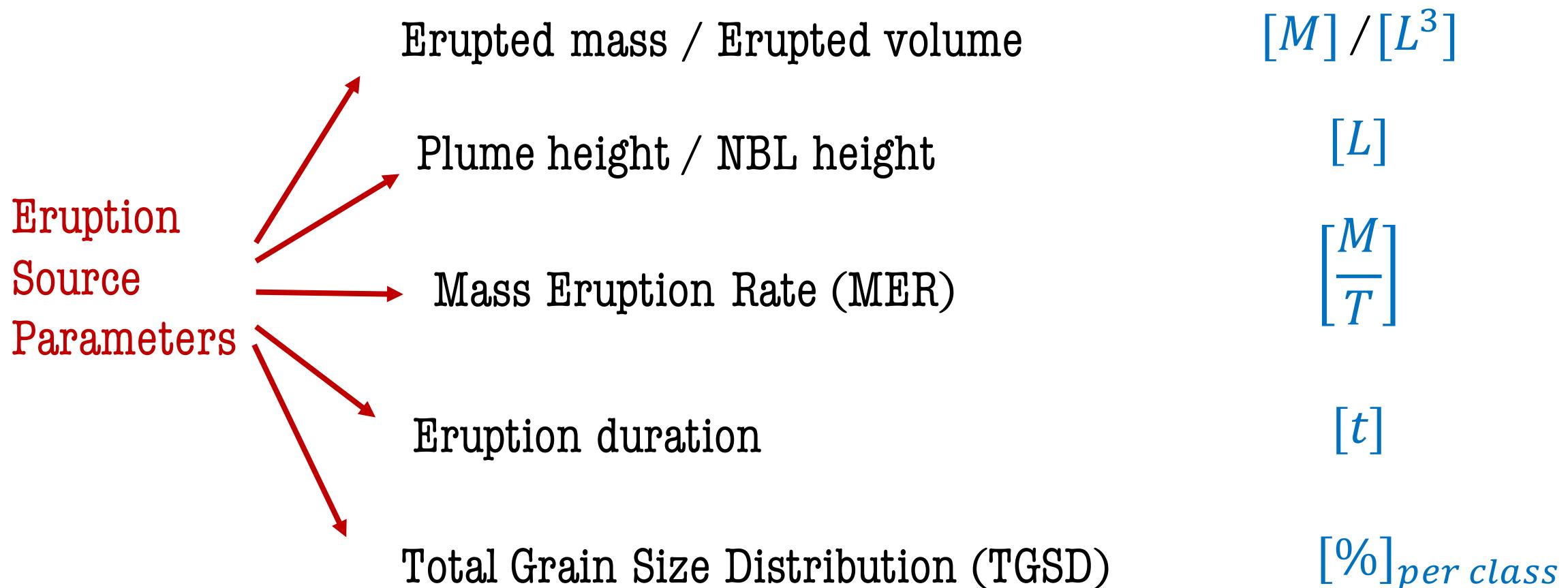


Mount Merapi (Indonesia)



Eruption Source Parameters (ESP)

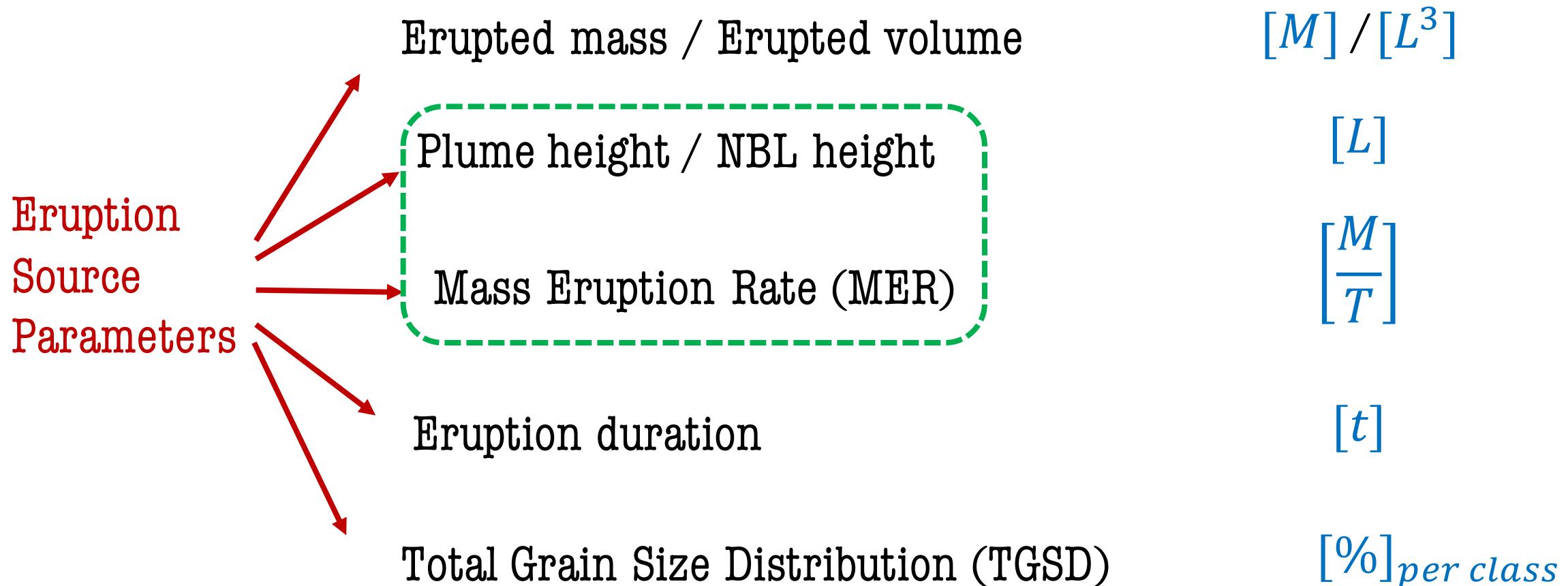
What are the most important source parameters that fully characterize a volcanic eruption?





Eruption Source Parameters (ESP)

What are the most important source parameters that fully characterize a volcanic eruption?





MER vs. Plume height: empirical relations

Empirical relations between MER and plume height

Important for modelling
tephra dispersal

$$MER = \mathcal{F}(H_p)$$

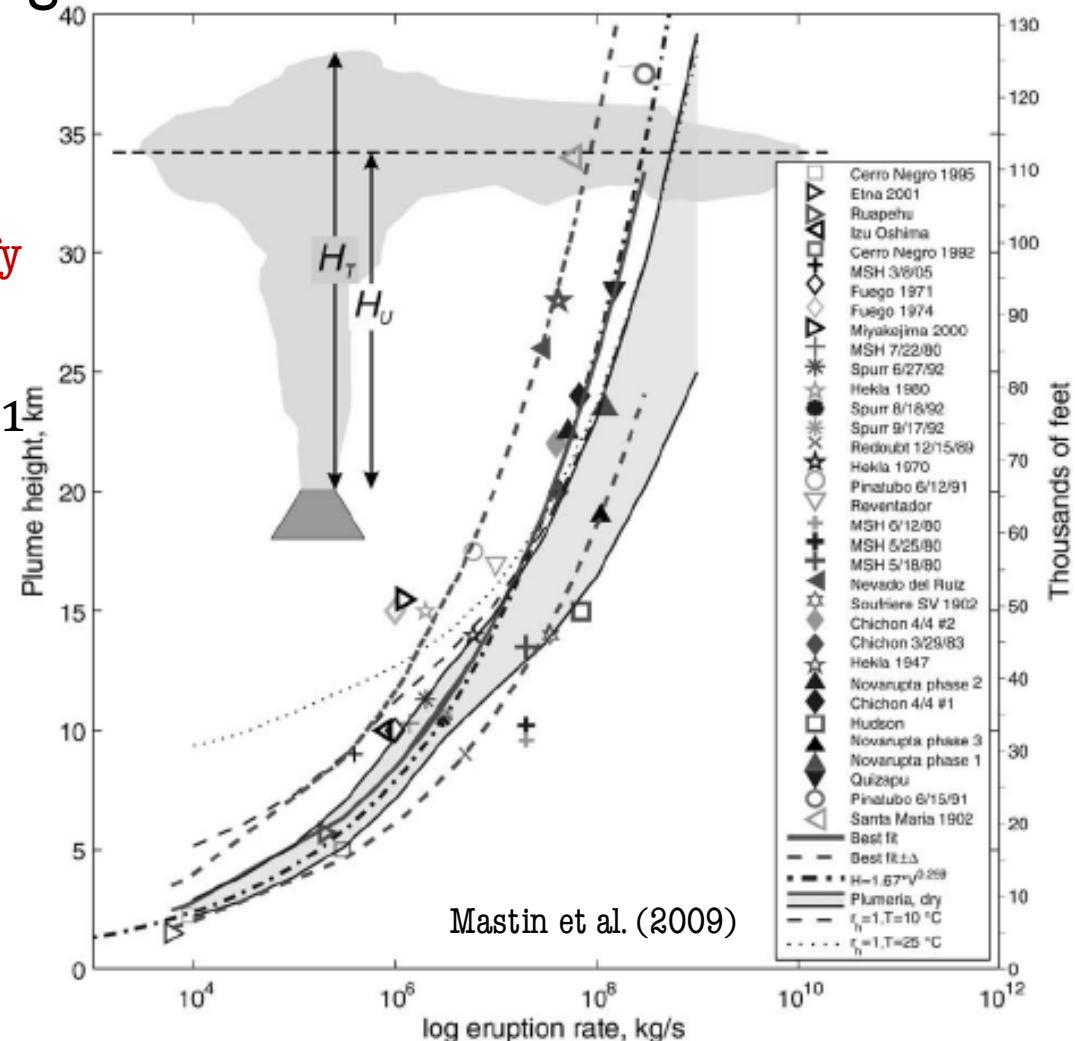
“Easy” to observe or quantify

$$H_p = 0.236 \cdot MER^{1/4}$$

Wilson and Walker (1987)

$$H_p = 0.304 \cdot MER^{0.241}$$

Mastin et al. (2009)





MER vs. Plume height: empirical relations

Empirical relations between MER and plume height

Important for modelling
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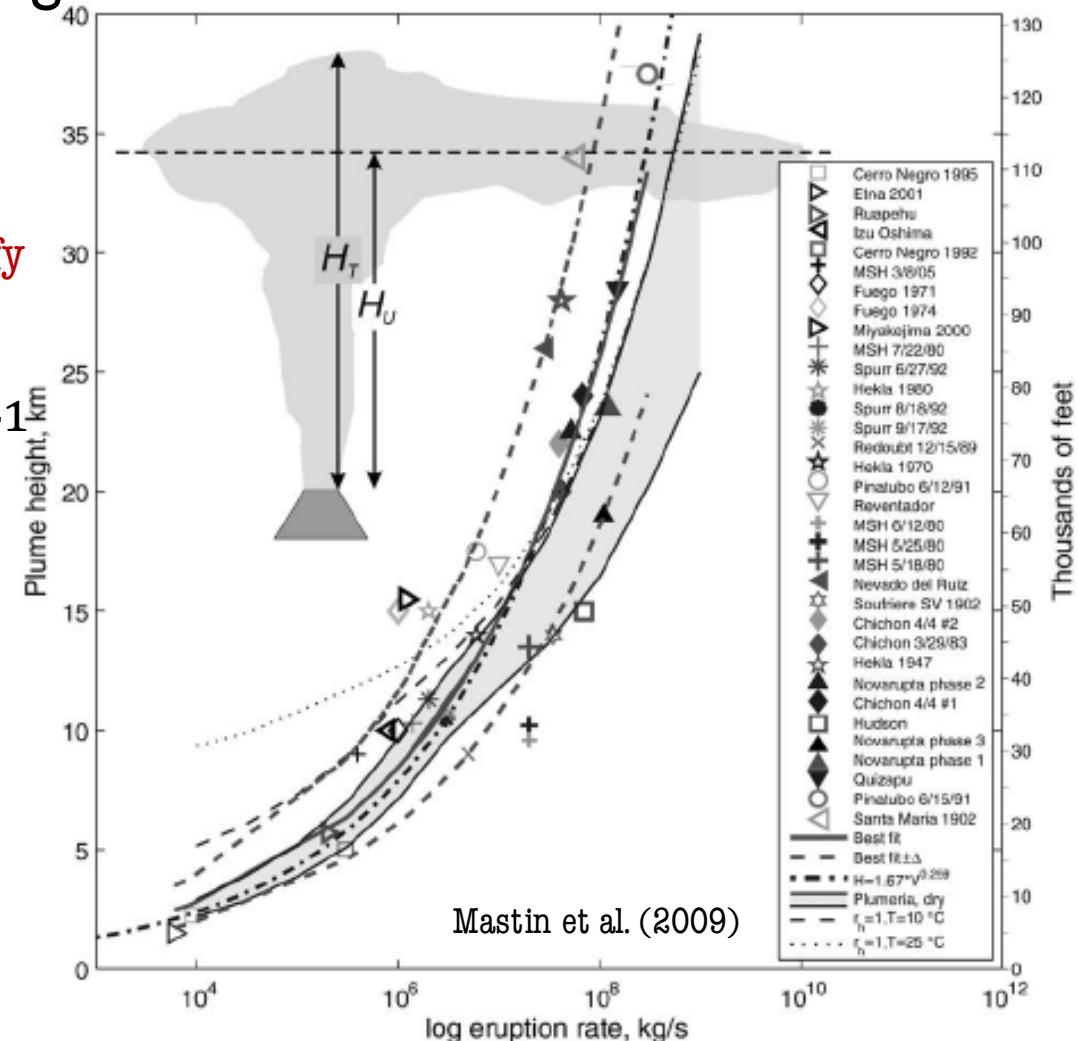
$$H_p = 0.236 \cdot MER^{1/4}$$

Wilson and Walker (1987)

$$H_p = 0.304 \cdot MER^{0.241}$$

Mastin et al. (2009)

No influence of the wind!





MER vs. Plume height: empirical relations

Empirical relations between MER and plume height

$$MER = \mathcal{F}(H_p)$$

Important for modelling tephra dispersal

“Easy” to observe or quantify

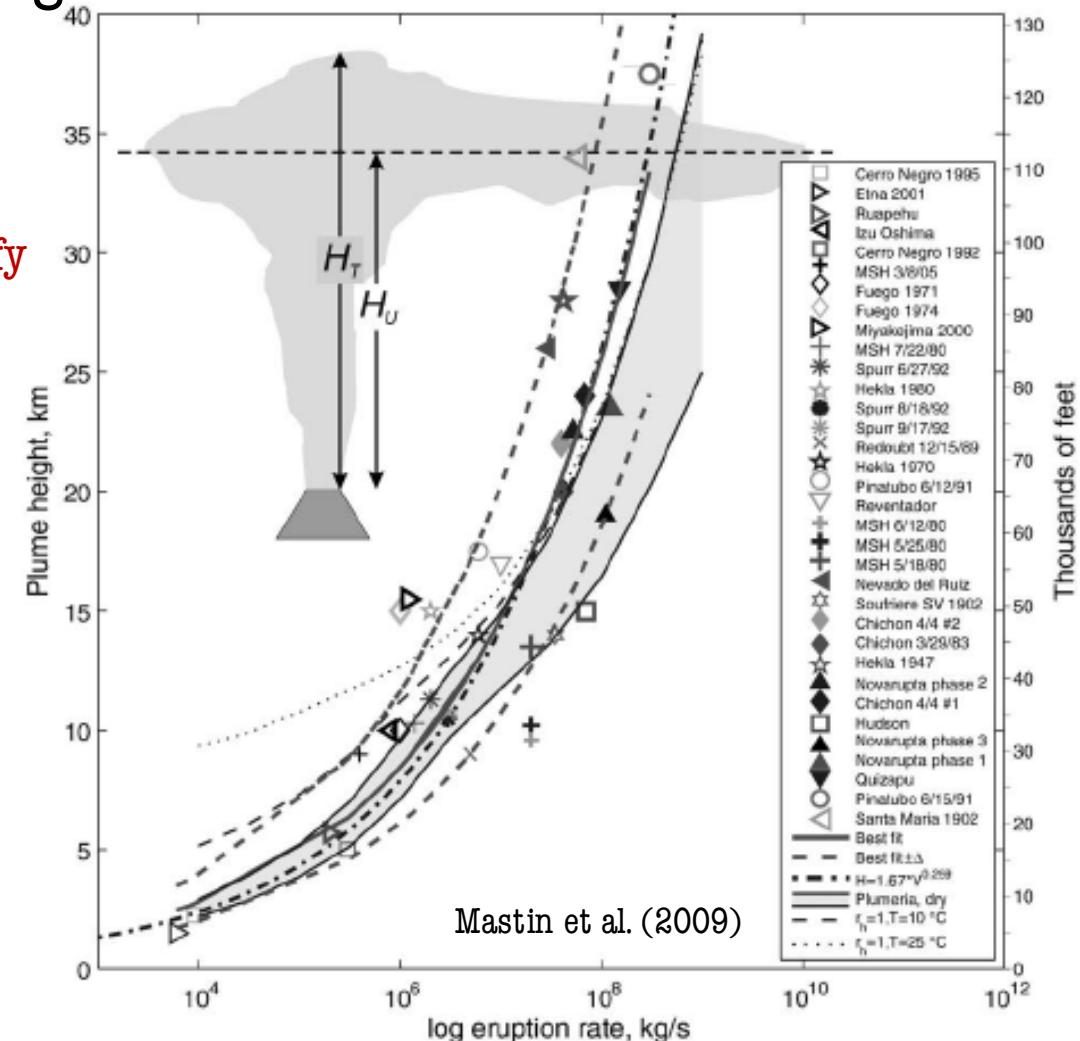
$$MER = \pi \frac{\rho_{a0}}{g'} \left(\frac{\alpha^2 \bar{N}^3}{10.9} H^4 + \frac{\beta^2 \bar{N}^2 v}{6} H^3 \right)$$

Degruyter and Bonadonna (2012)

Where the effect of the wind is summarised in the parameter Π

$$\Pi = \frac{\bar{N}H}{1.8v} \left(\frac{\alpha}{\beta} \right)^2$$

Wind dominant if
 $\Pi < 1$





Limits of the empirical approach

However...

$$H_p \propto \text{MER}^{1/4}$$

Important for modelling
tephra dispersal

$$\text{MER} = \mathcal{F}(H_p)$$

“Easy” to observe or quantify

$$\text{MER} \propto H_p^4$$

A small error in height produces a
large error in MER

Moreover...

$$[H_p] = L$$

$$[\text{MER}] = MT^{-1}$$

No way of making $H_p = \mathcal{F}(\text{MER})$
dimensionally constant without
other dimensional quantities



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Limits of the empirical approach

1. Something missing in the physical description



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Limits of the empirical approach

1. Something missing in the physical description
2. Real scenarios can be complex (e.g. wind)



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Limits of the empirical approach

1. Something missing in the physical description
2. Real scenarios can be complex (e.g. wind)
3. Real scenarios can be complex (e.g. atmospheric profiles)



Limits of the empirical approach

1. Something missing in the physical description
2. Real scenarios can be complex (e.g. wind)
3. Real scenarios can be complex (e.g. atmospheric profiles)
4. Real scenarios can be complex (e.g. multiphase plume mixture)



Limits of the empirical approach

1. Something missing in the physical description
2. Real scenarios can be complex (e.g. wind)
3. Real scenarios can be complex (e.g. atmospheric profiles)
4. Real scenarios can be complex (e.g. multiphase plume mixture)
5. We can be interested in second order phenomena for plumes but first order for what concerns sedimentation (e.g. aggregation)



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Modelling volcanic plumes

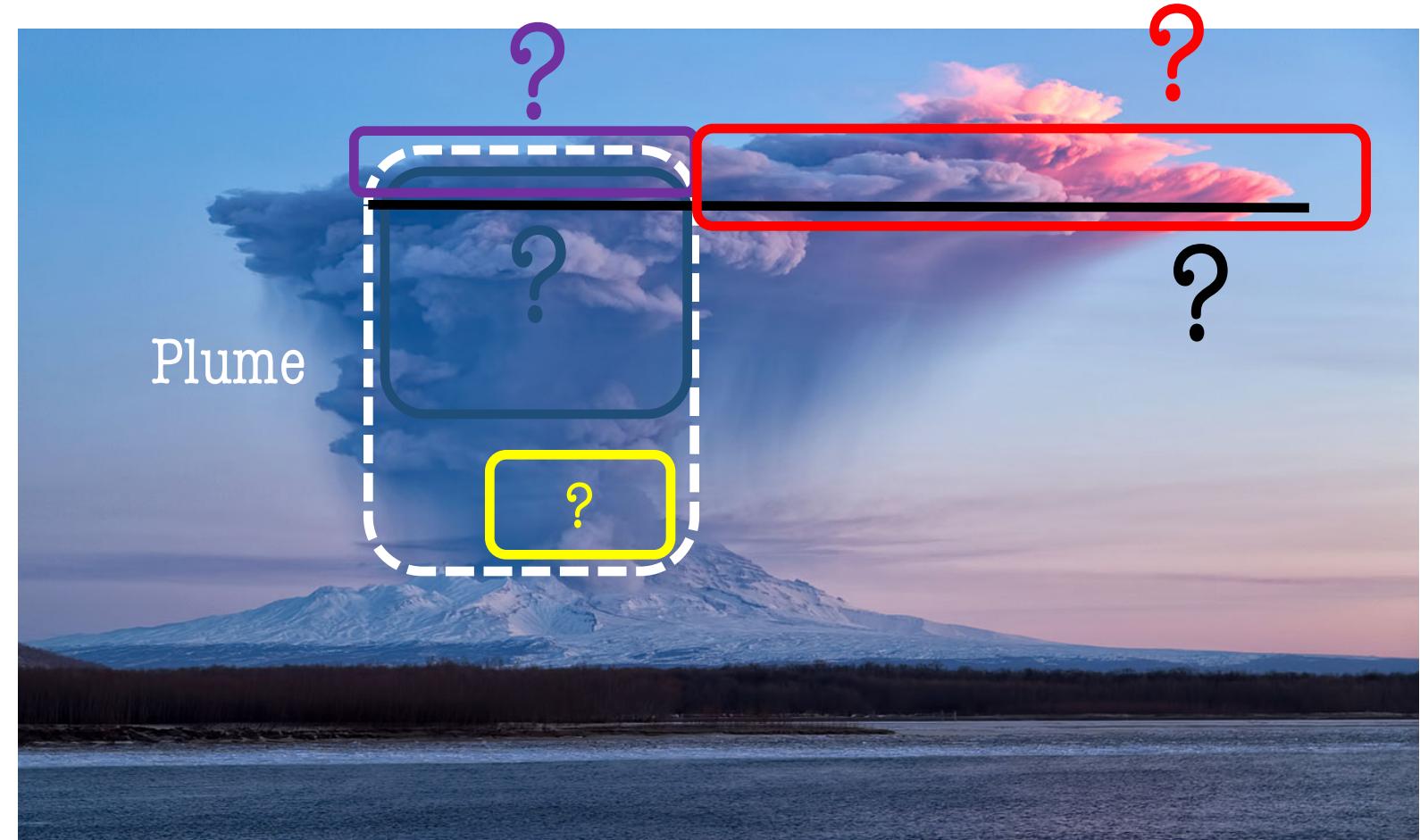


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Your first steps in modelling volcanic plumes

What have we seen so far?



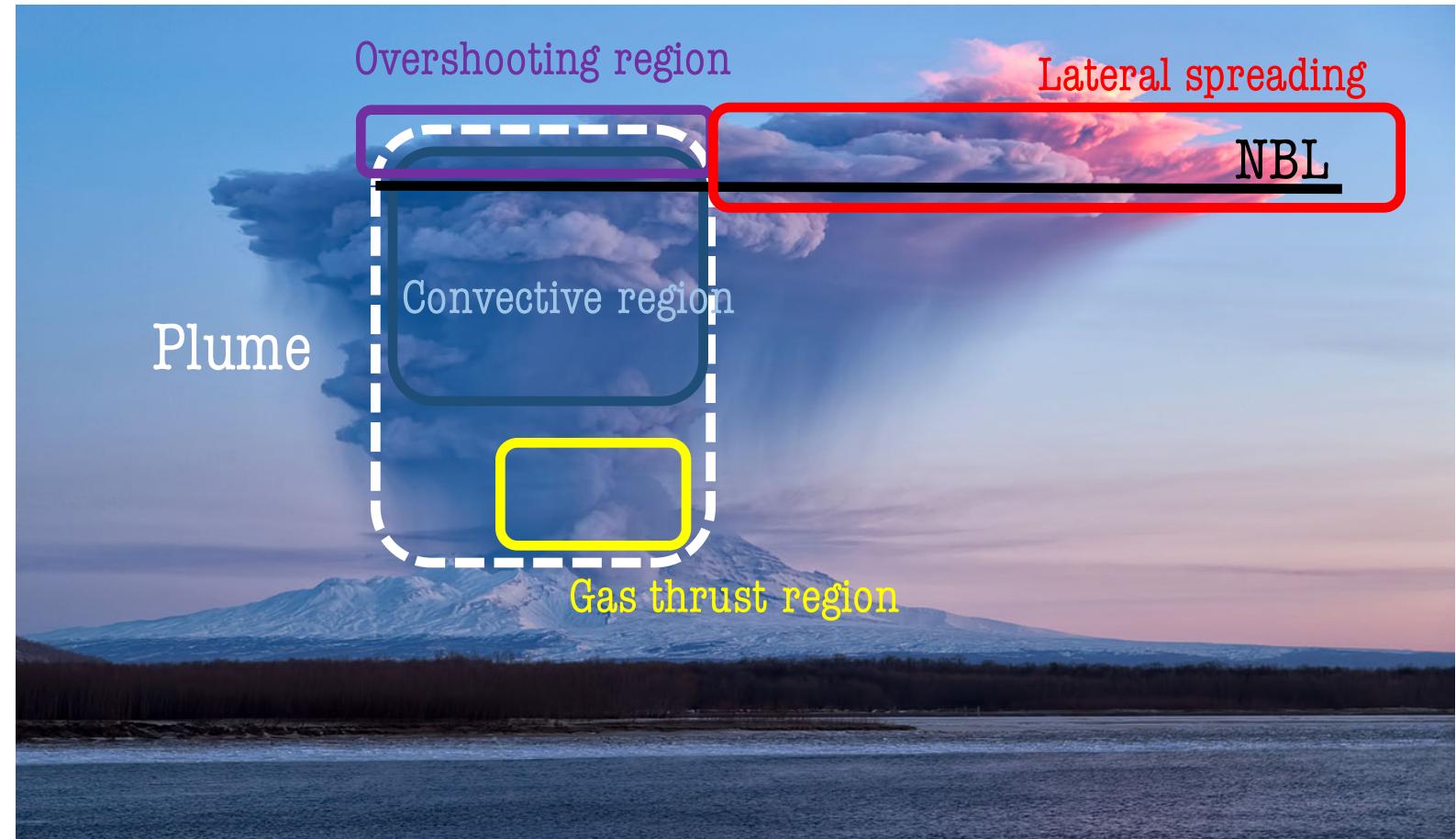


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Your first steps in modelling volcanic plumes

What we have seen so far



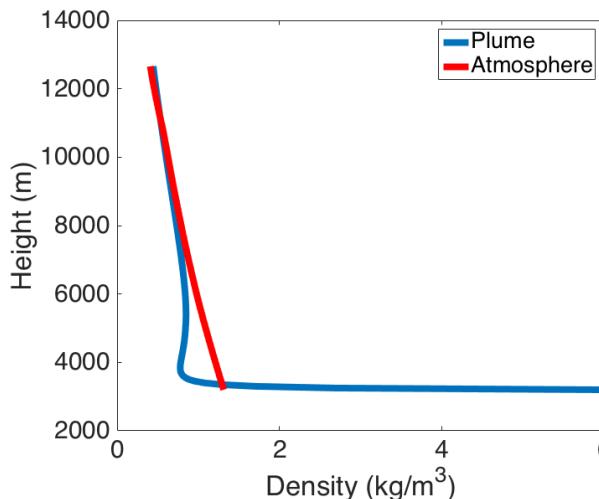


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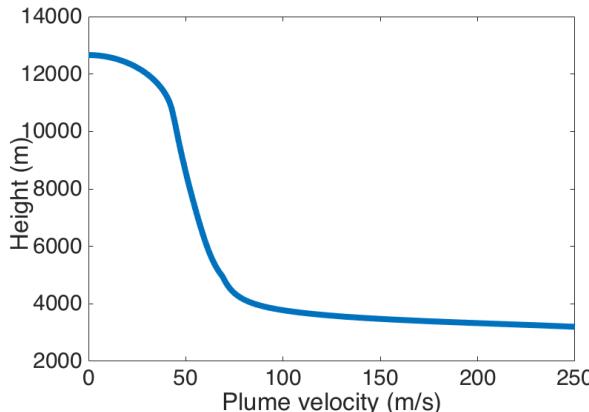
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Modelling volcanic plumes

1-D Models

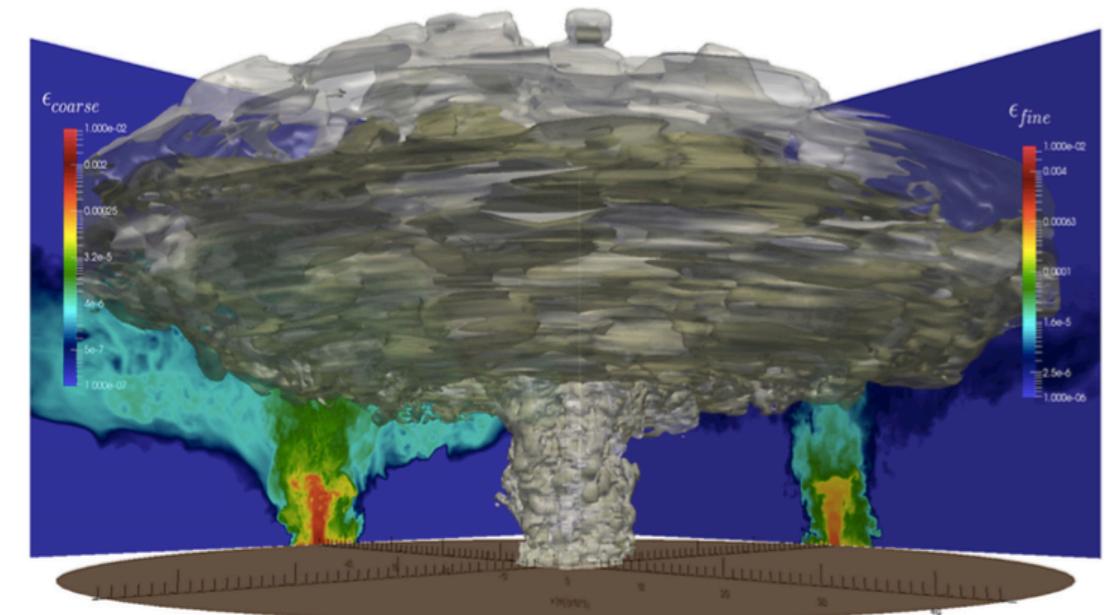


- Morton et al. (1956)
- Wilson et al. (1978)
- Sparks (1986)
- Woods (1988)
- Woods and Kienle (1994)
- Woods (1995)
- Glaze & Baloga (1996)



- Bursik (2001)
- Clarke et al. (2002)
- Degruyter & Bonadonna (2012)

3-D Models

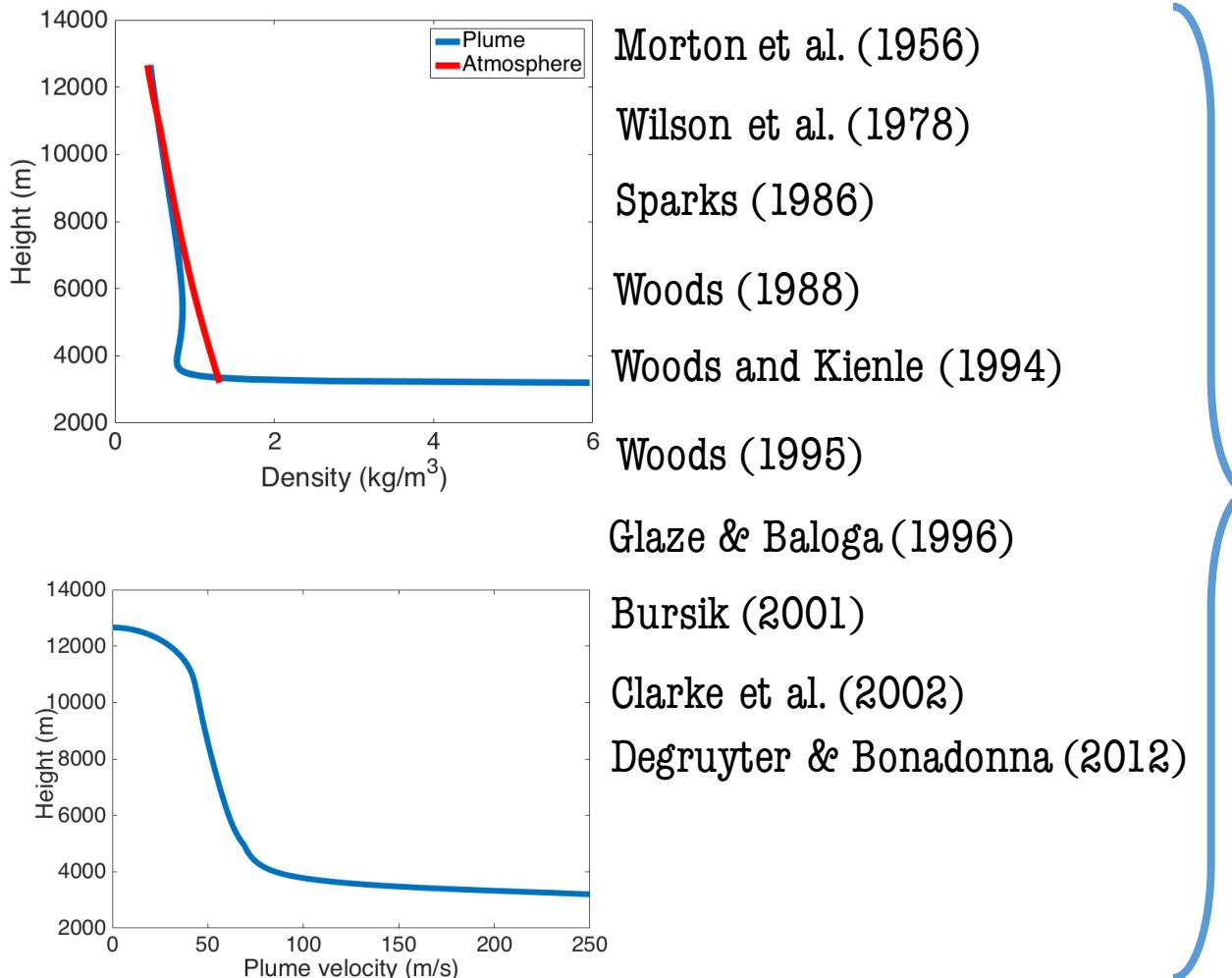


ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
SK-3D	Suzuki et al. (2005)
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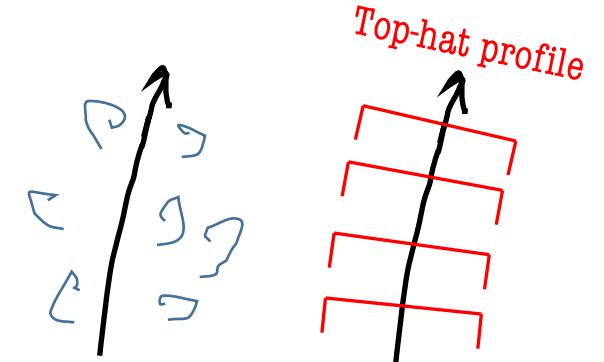


Modelling volcanic plumes

1-D Models



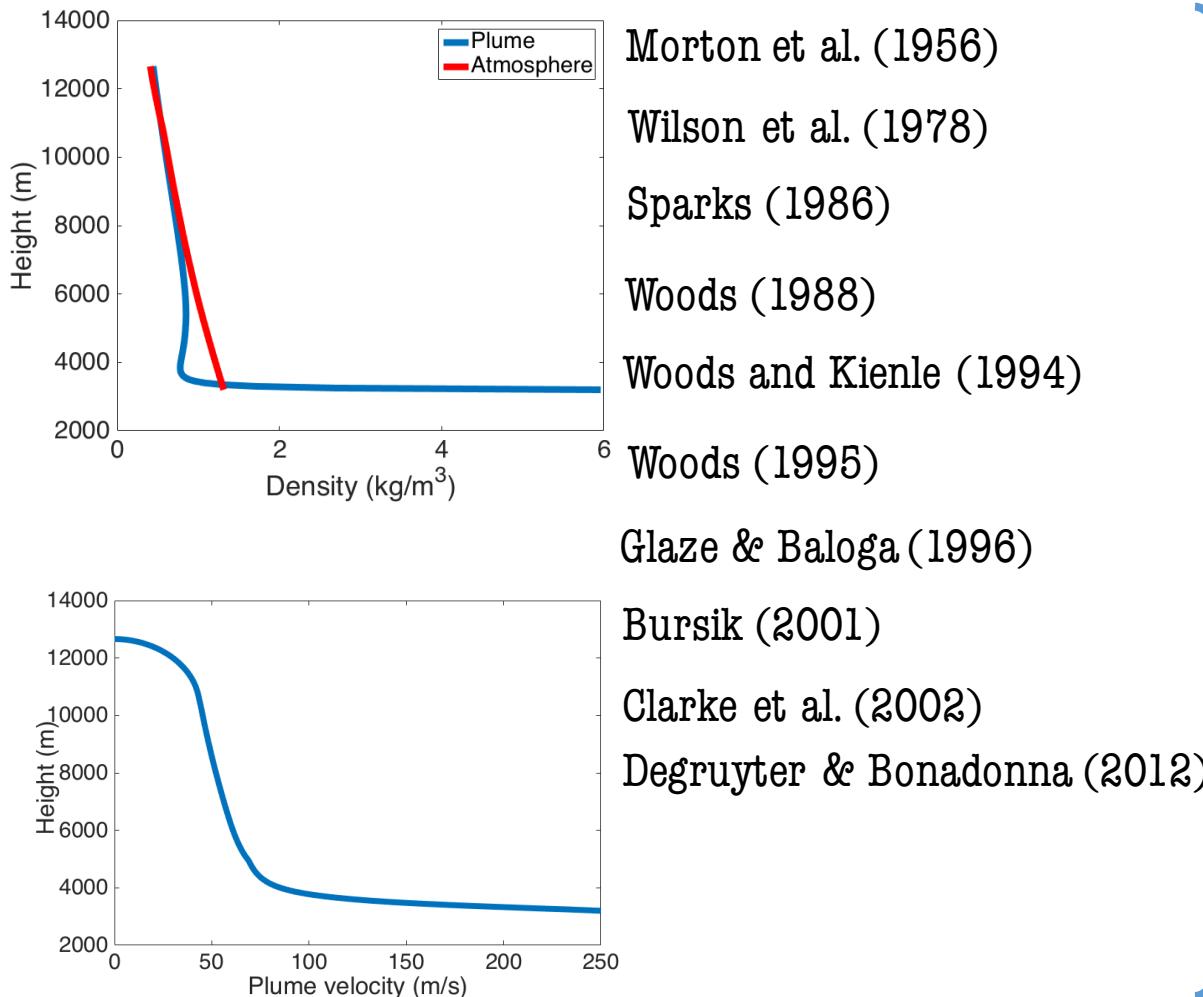
1. Integral steady-state models





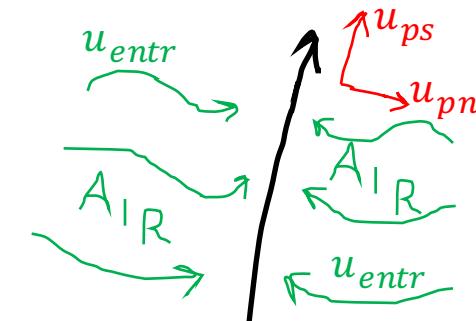
Modelling volcanic plumes

1-D Models



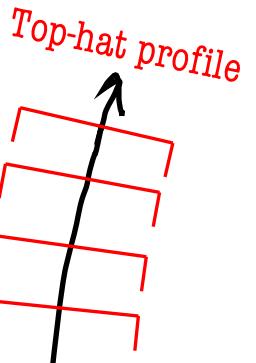
1. Integral models
(steady-state/thermals)

2. Based on the “*entrainment assumption*”



$$u_{entr} \propto \alpha u_{ps} + \beta u_{pn}$$

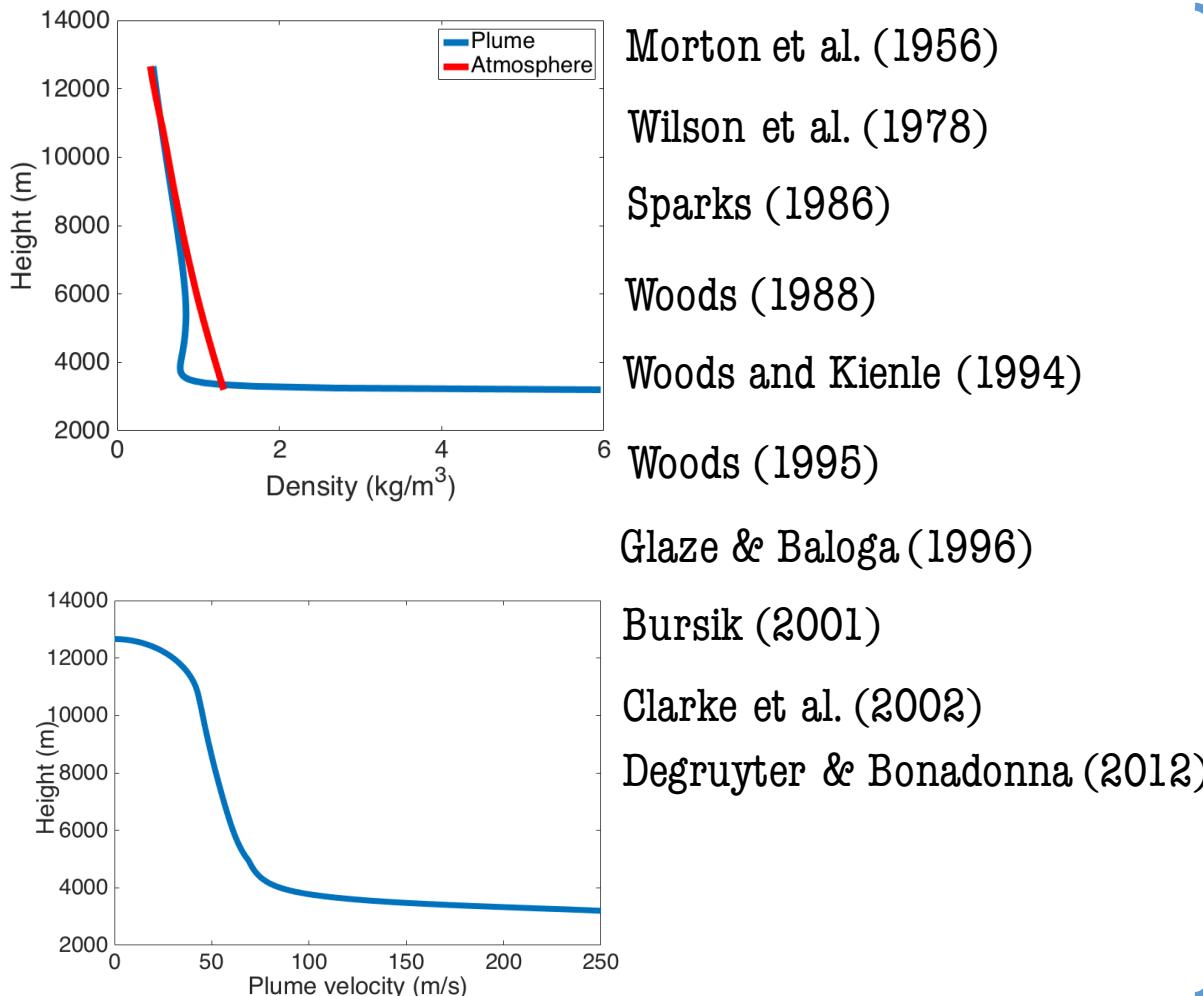
It affects the buoyancy!



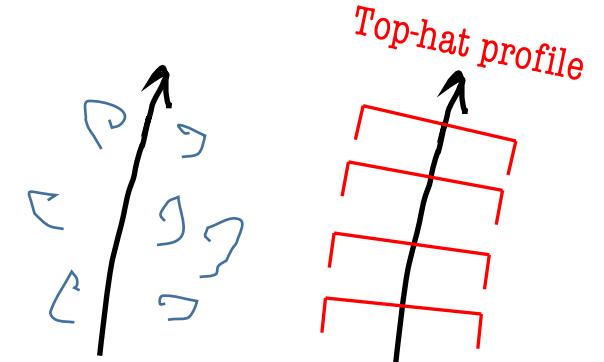


Modelling volcanic plumes

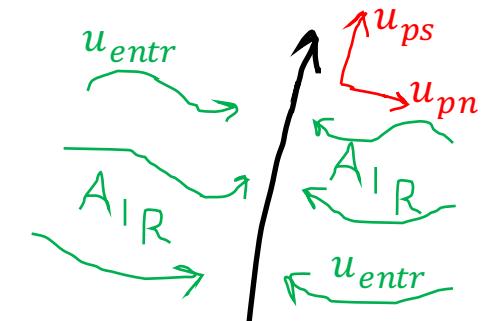
1-D Models



1. Integral models
(steady-state/thermals)



2. Based on the “*entrainment assumption*”



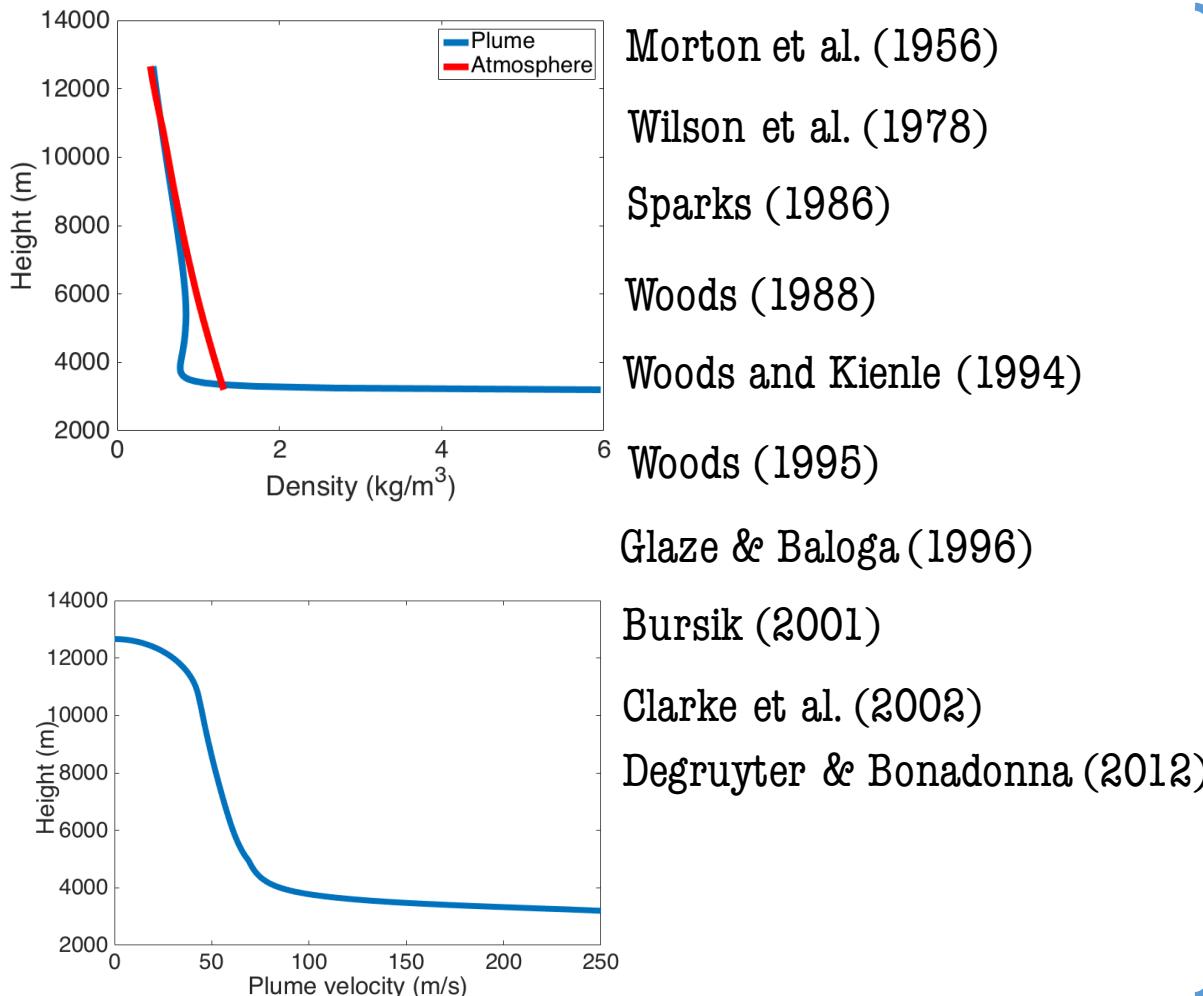
$$u_{entr} \propto \alpha u_{ps} + \beta u_{pn}$$

3. Low computational cost

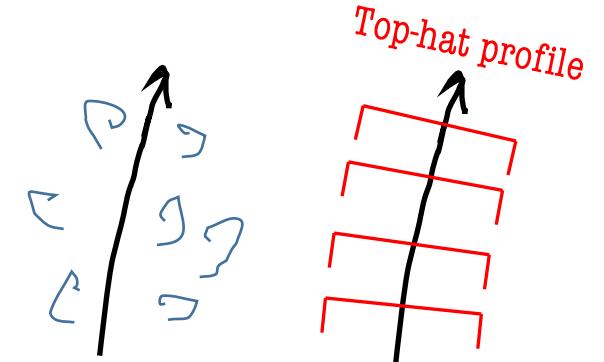


Modelling volcanic plumes

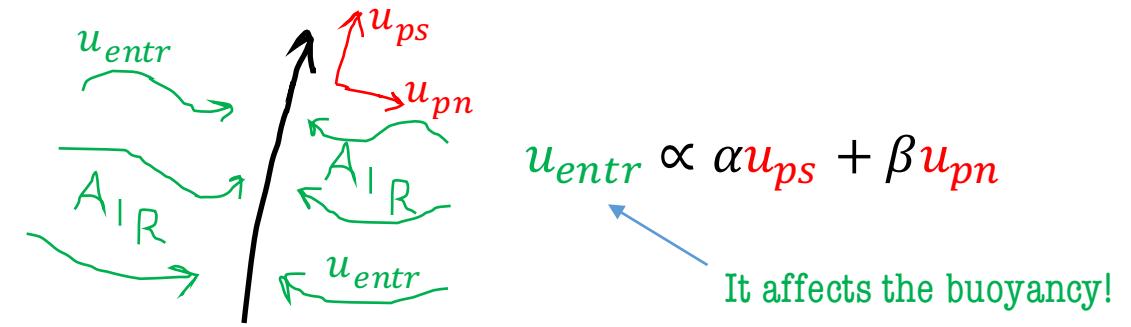
1-D Models



1. Integral models
(steady-state/thermals)



2. Based on the “*entrainment assumption*”



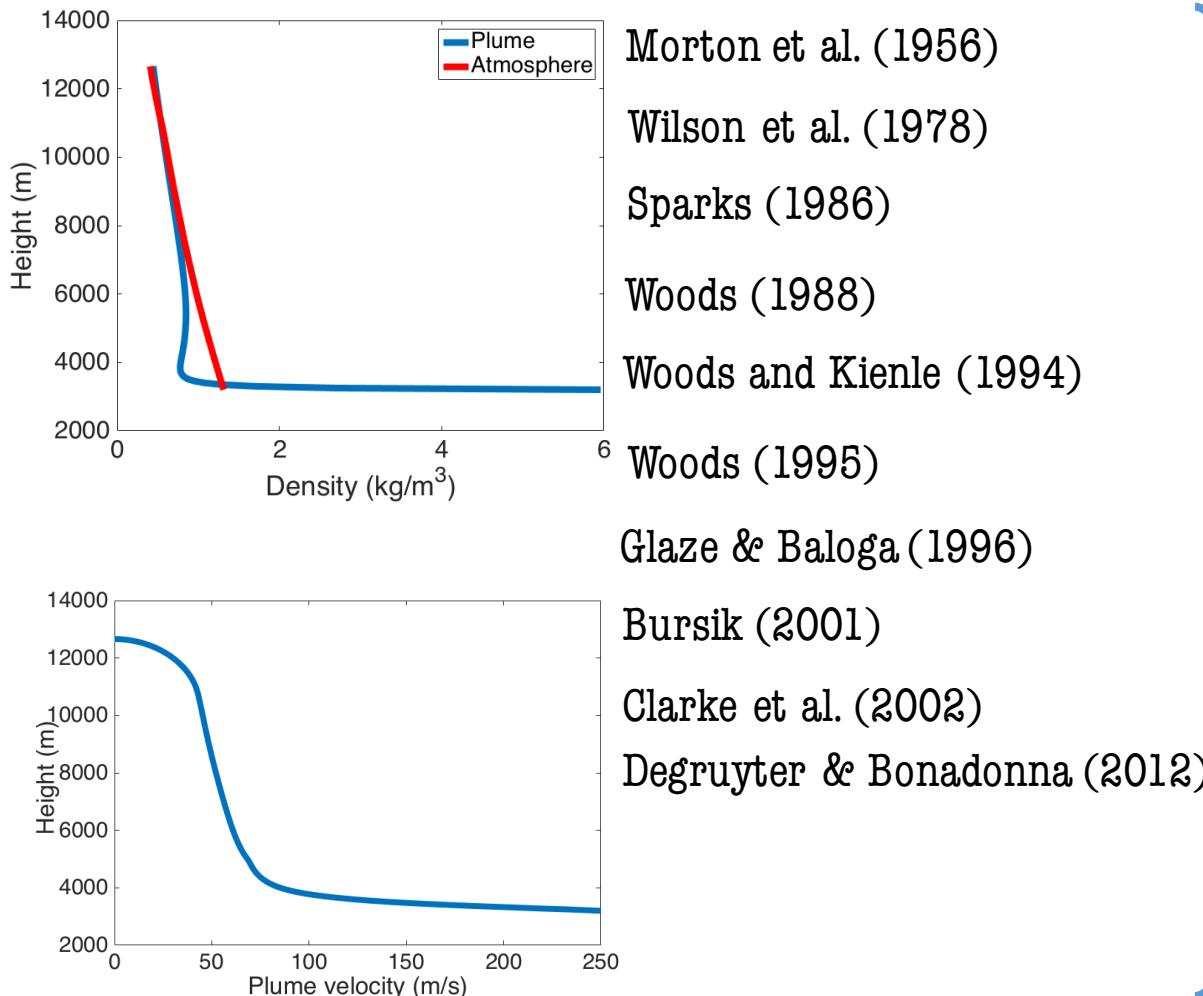
3. Low computational cost

4. Reliable estimation of the NBL



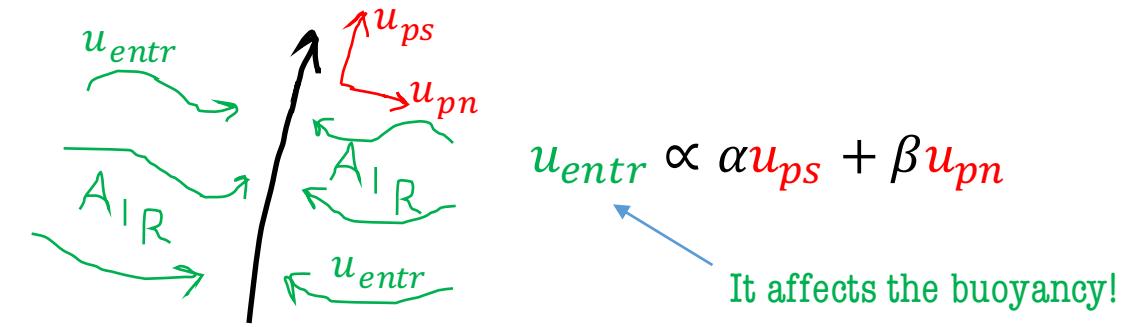
Modelling volcanic plumes

1-D Models



1. Integral models
(steady-state/thermals)

2. Based on the “*entrainment assumption*”



3. Low computational cost

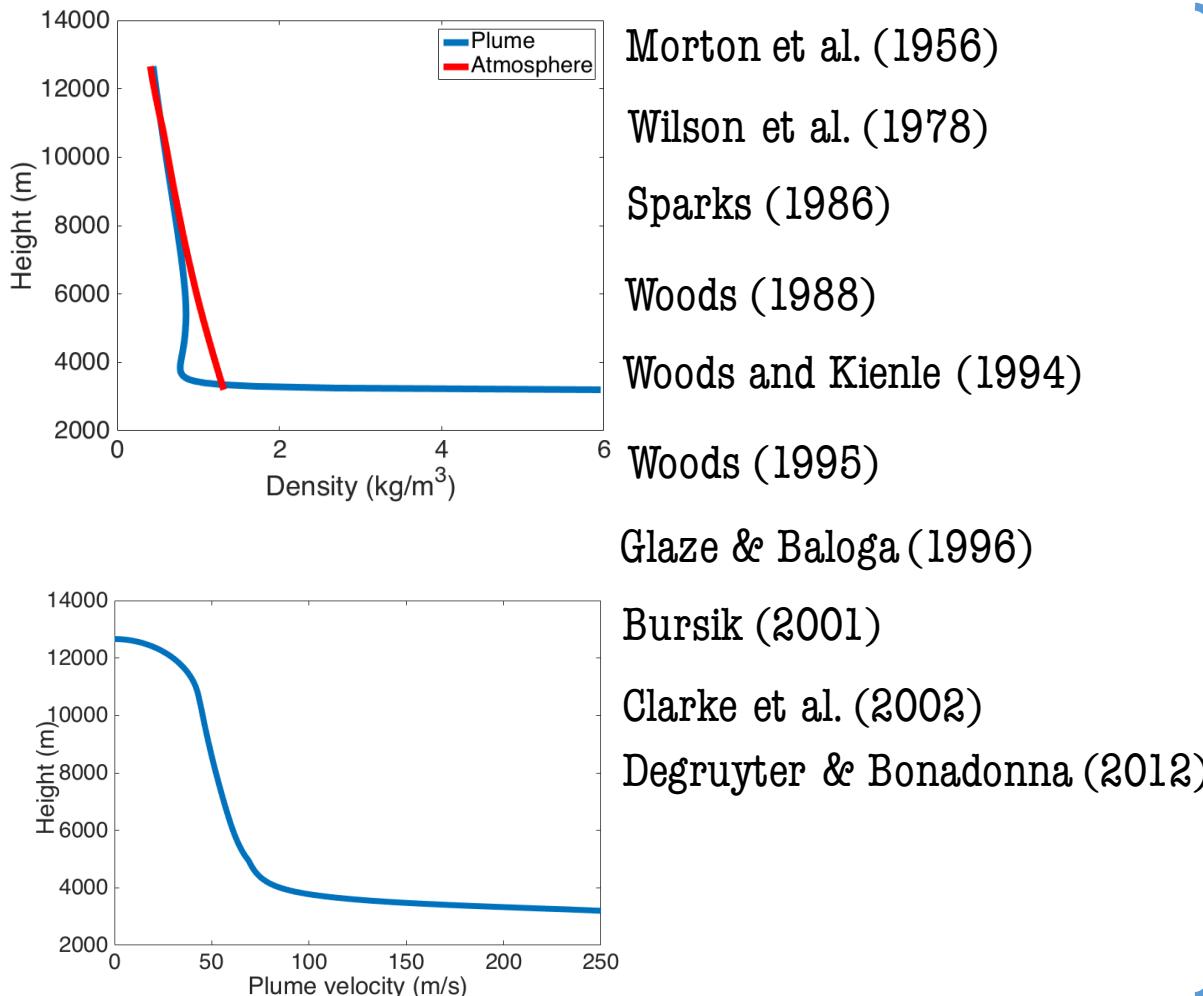
4. Reliable estimation of the NBL

5. No turbulence



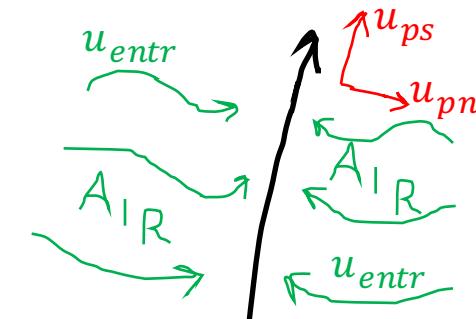
Modelling volcanic plumes

1-D Models



1. Integral models
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2. Based on the “*entrainment assumption*”



$$u_{entr} \propto \alpha u_{ps} + \beta u_{pn}$$

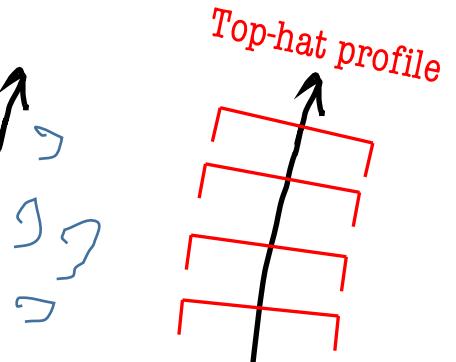
It affects the buoyancy!

3. Low computational cost

4. Reliable estimation of the NBL

5. No turbulence

6. “Fake” multiphase flow





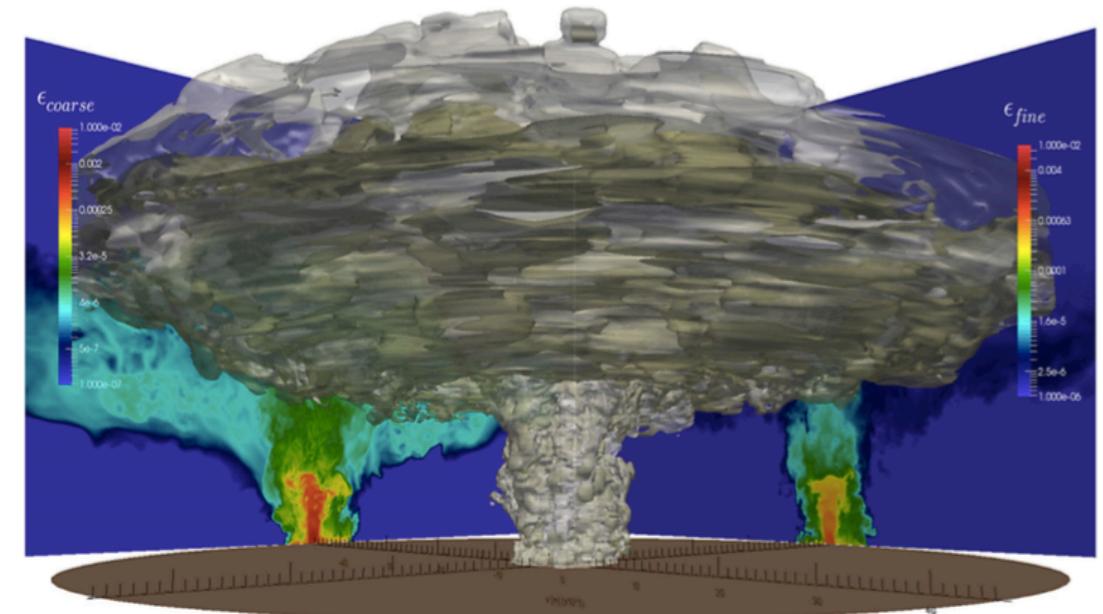
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Department of Earth Sciences

Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)

3-D Models



- | | |
|-------|---|
| ATHAM | Oberhuber et al. (1998); Herzog et al. (2003) |
| SK-3D | Suzuki et al. (2005); Herzog et al. (2003) |
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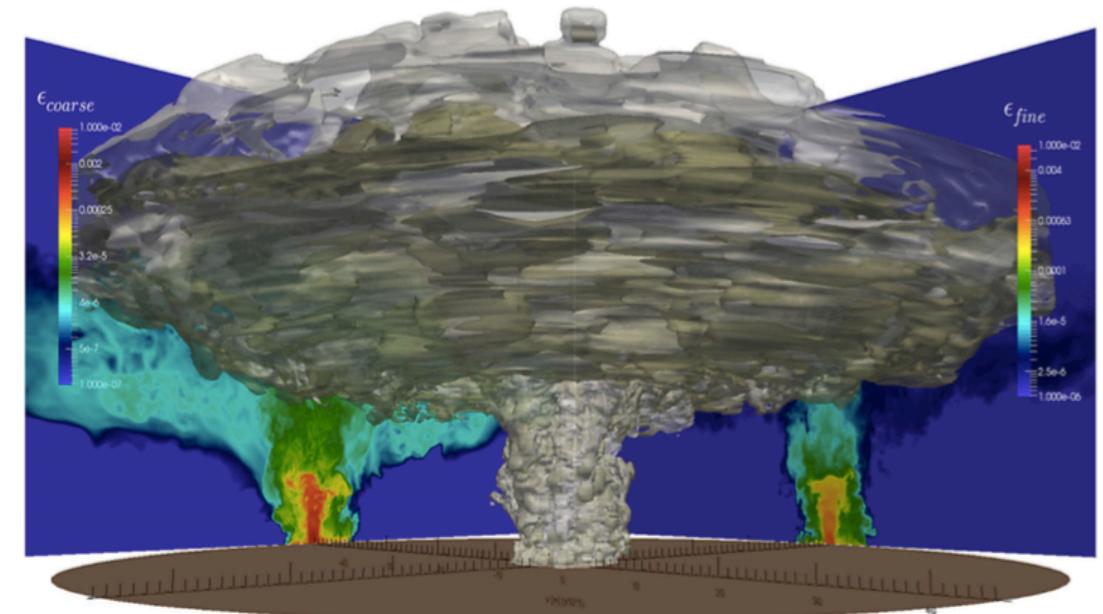
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)

3-D Models



ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
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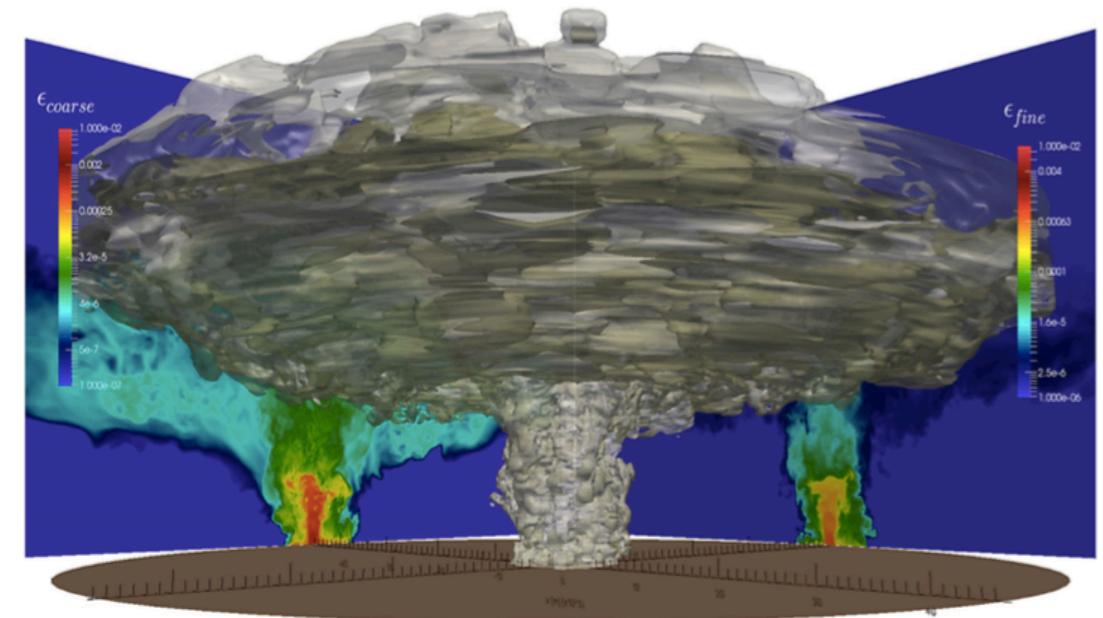
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)
3. Real multiphase flow

3-D Models



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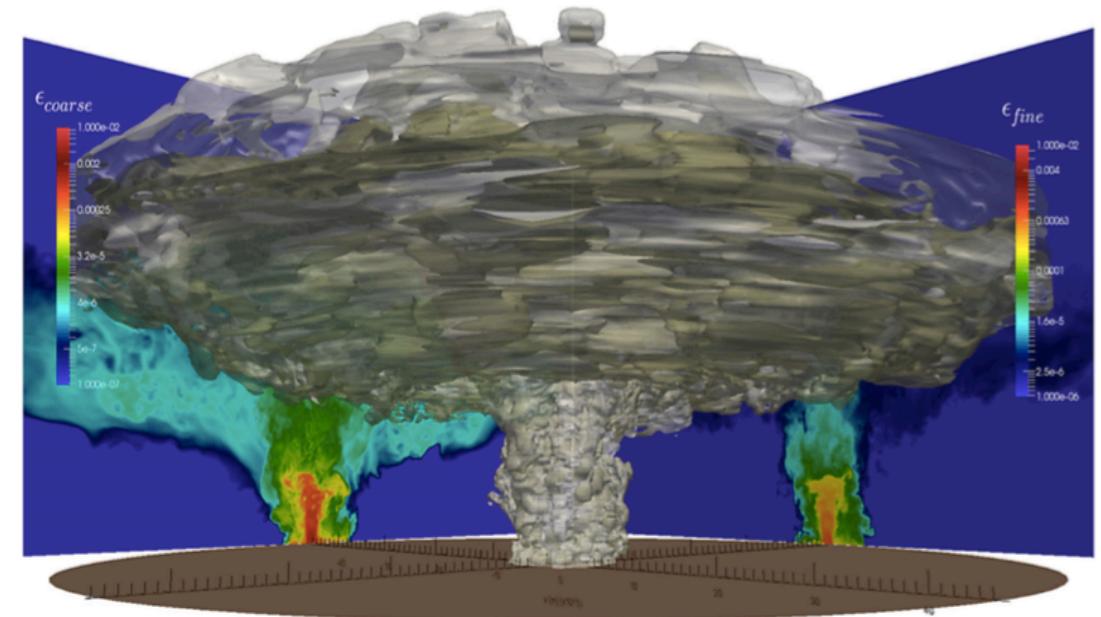
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)
3. Real multiphase flow
4. Computationally heavy

3-D Models



ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
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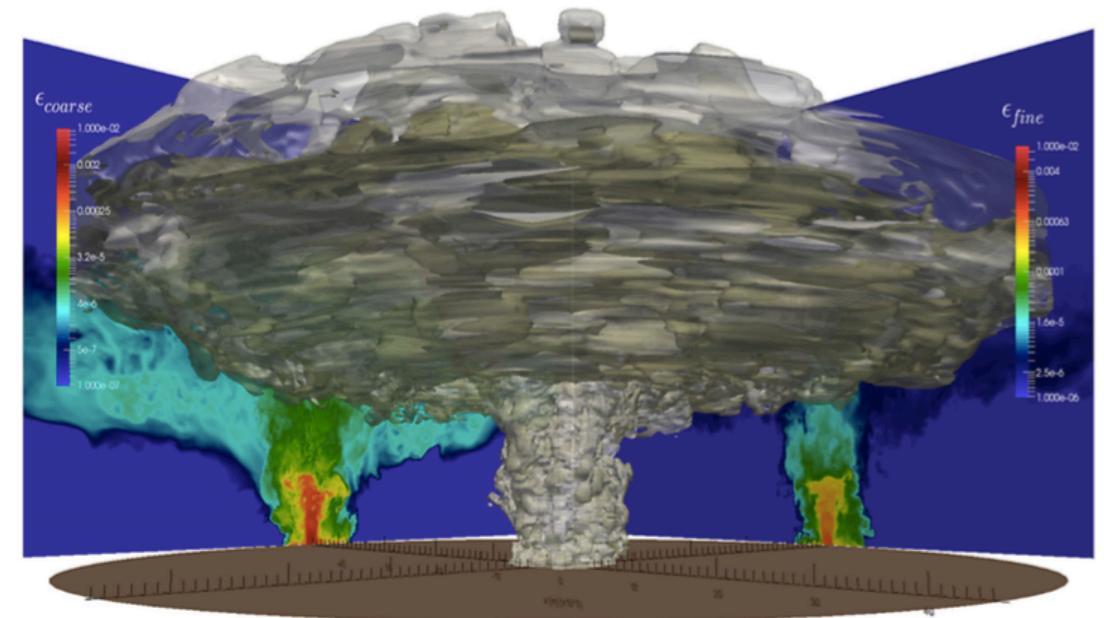
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)
3. Real multiphase flow
4. Computationally heavy
5. Good description of the microphysics

3-D Models



ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
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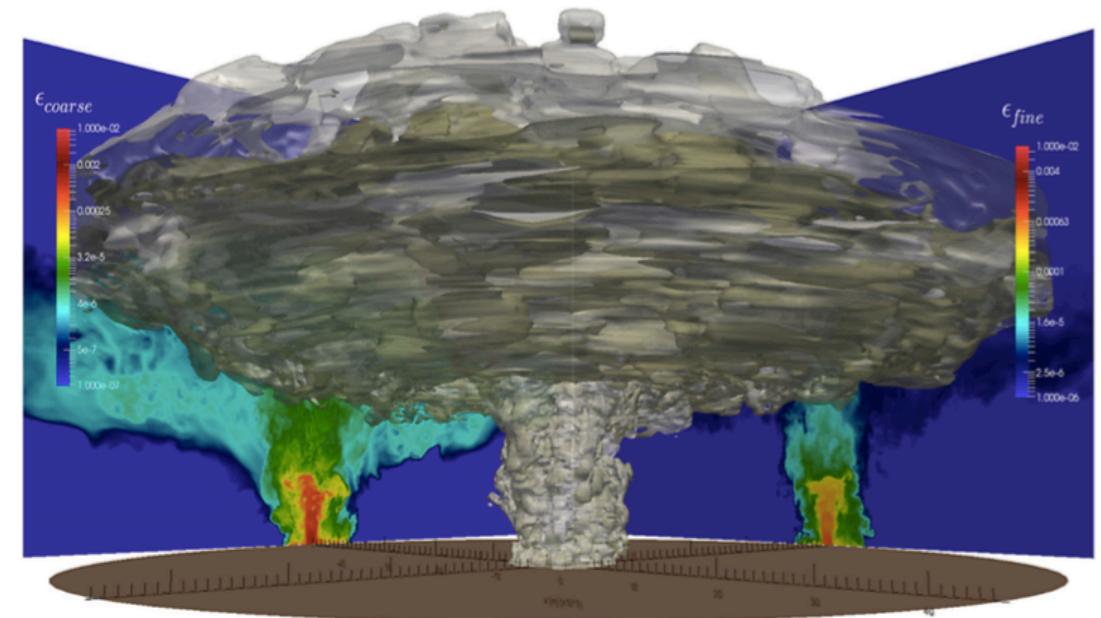
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)
3. Real multiphase flow
4. Computationally heavy
5. Good description of the microphysics
6. Plume + cloud + sedimentation

3-D Models



ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
SK-3D	Suzuki et al. (2005); Herzog et al. (2003)
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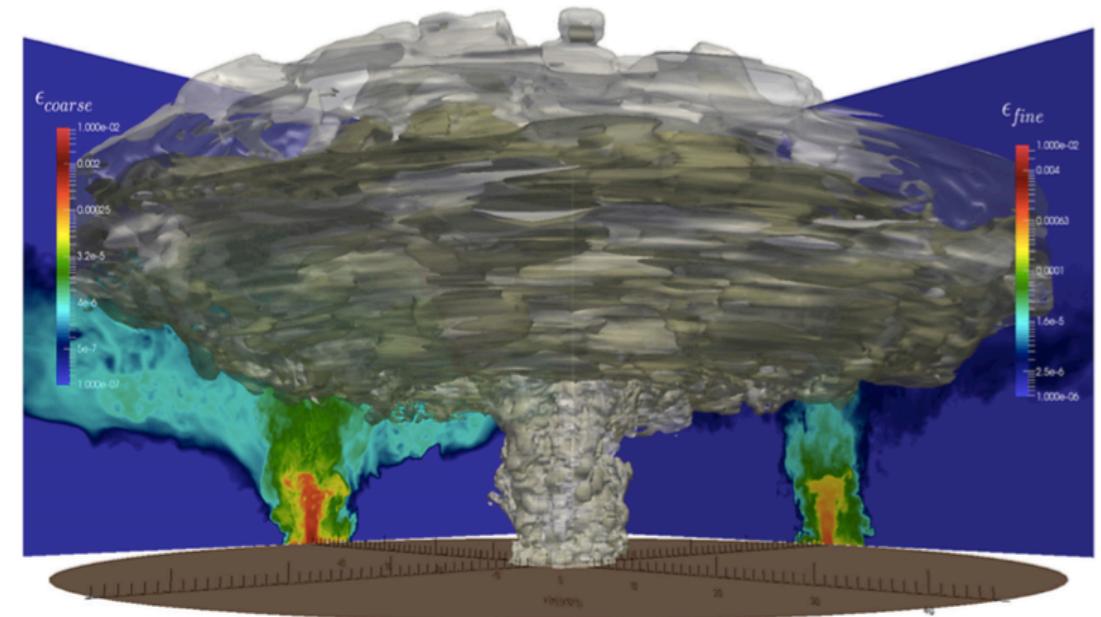
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Modelling volcanic plumes

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)
3. Real multiphase flow
4. Computationally heavy
5. Good description of the microphysics
6. Plume + cloud + sedimentation
7. No steady-state

3-D Models



ATHAM	Oberhuber et al. (1998); Herzog et al. (2003)
SK-3D	Suzuki et al. (2005); Herzog et al. (2003)
PDAC	Neri et al. (2003); Esposti Ongaro et al., (2007)
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Modelling volcanic plumes

3-D Models

1. Eulerian (voxel) / Lagrangian (tracking)
2. “Complete” description of turbulence (LES)



3. Real multiphase flow

4. Computationally heavy

“Results of the eruptive column model inter-comparison study”
Costa et al. (2016)

5. Good description of the microphysics

ATHAM Oberhuber et al. (1998); Herzog et al. (2003)

SK-3D Suzuki et al. (2005), Herzog et al. (2005)

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ASHEE Cerminara et al. (2016)



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The 1D model you are going to use in the exercise

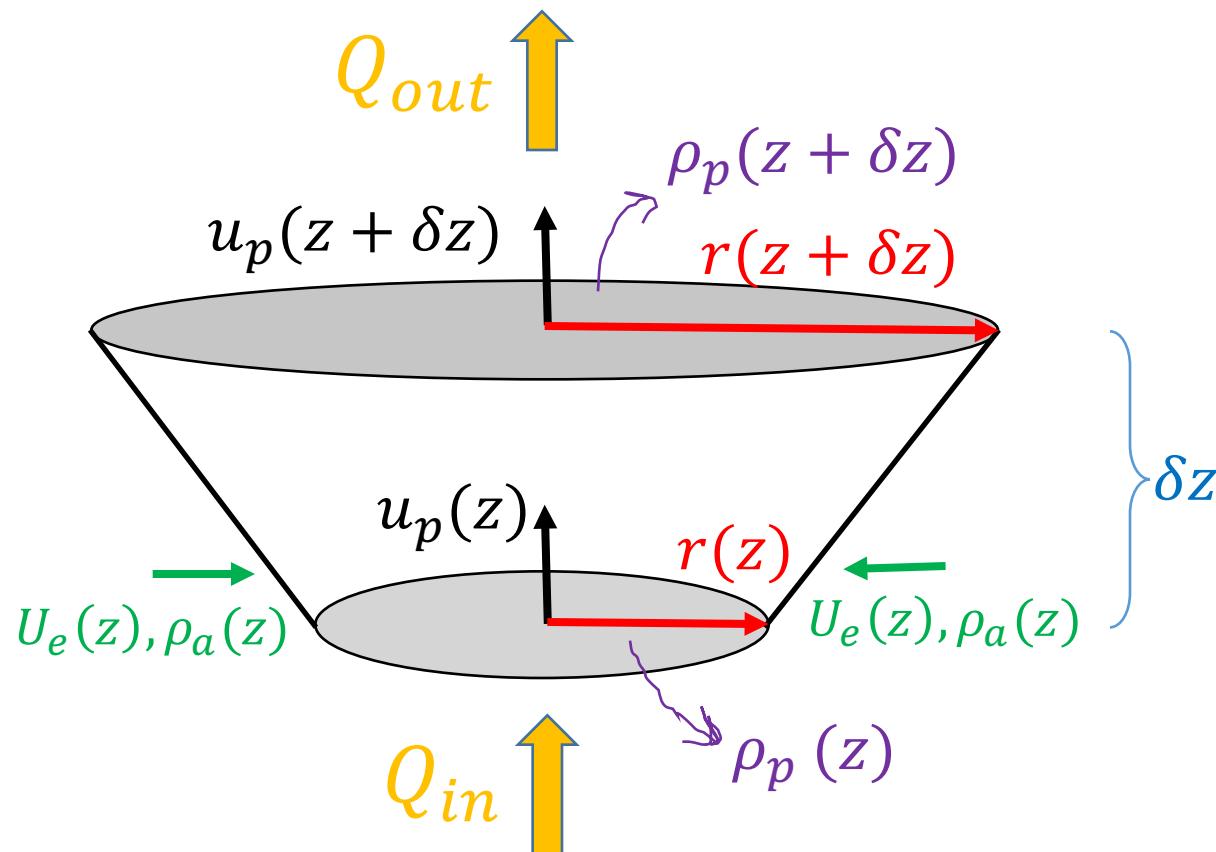
Degruyter & Bonadonna (2012)



1-D steady state plume models

Example:

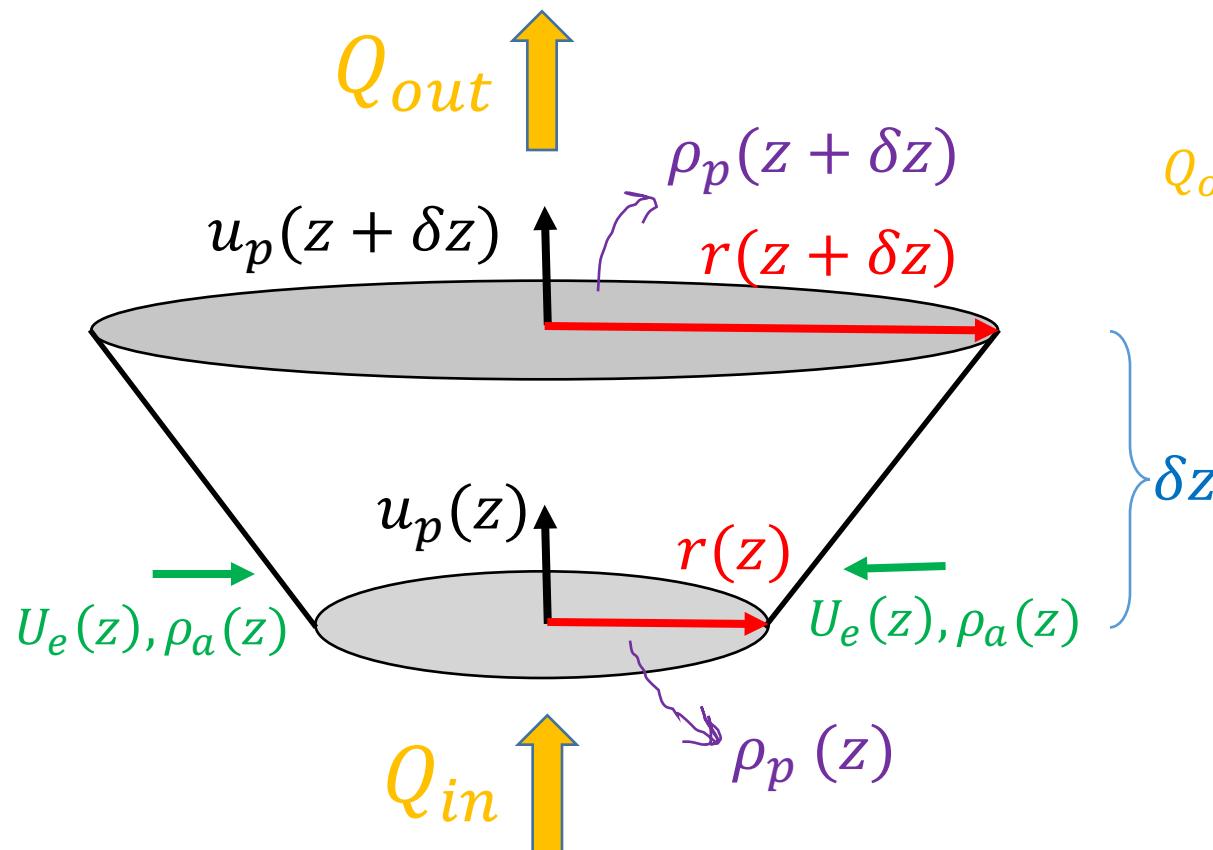
mass flow rate balance in the control volume





1-D steady state plume models

Example:
mass flow rate balance in the control volume



Mass flow rate (inward)

$$Q_{in} = \{\rho(z) \cdot u_p(z)\} \cdot \{\pi \cdot [r(z)]^2\}$$

Mass flow rate (outward)

$$Q_{out} = \{\rho(z + \delta z) \cdot u_p(z + \delta z)\} \cdot \{\pi \cdot [r(z + \delta z)]^2\}$$

Variation in the δz (entrainment)

$$\Delta Q = 2\pi r(z) U_e \rho_a \delta z$$

Balance equation

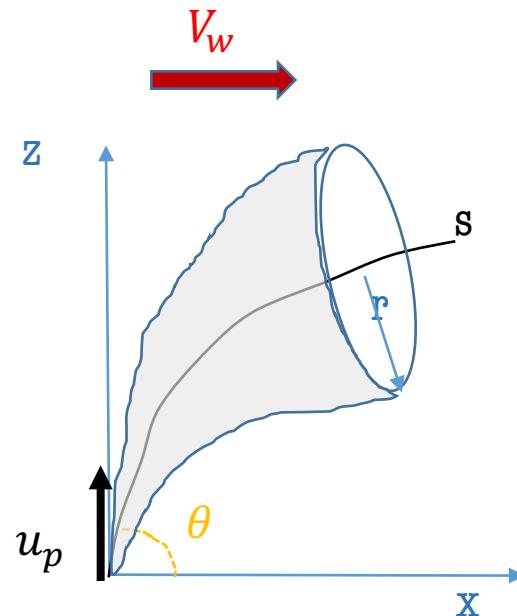
$$Q_{out} - Q_{in} = \Delta Q$$

Limit for $\delta z \rightarrow 0$

$$\boxed{\frac{d}{dz} (\rho_p \pi r^2 u_p) = 2\pi r \rho_a U_e}$$



Model of
Degruyter &
Bonadonna
(2013)



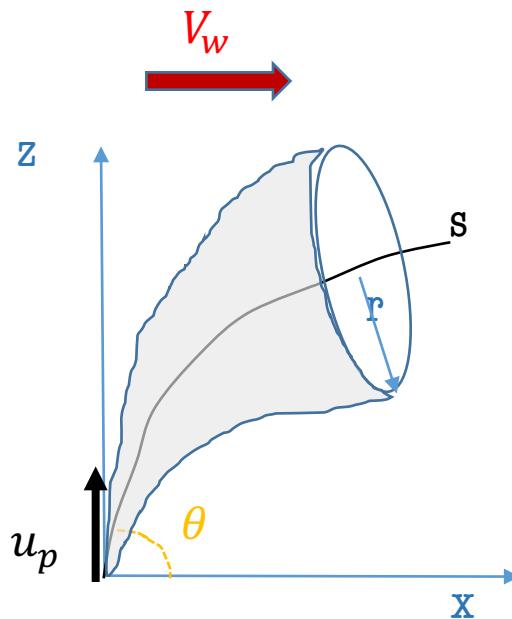
1-D steady state plume models

Mass flow rates

$$\left[\begin{array}{ll} \frac{d}{ds} (Q_d) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_d) = 2\pi r \rho_{ad} \phi_{ad} U_e & \text{Dry air} \\ \frac{d}{ds} (Q_v) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_v) = 2\pi r \rho_{av} \phi_{av} U_e - \lambda \rho_p \phi_v \pi r^2 & \text{Water vapor} \\ \frac{d}{ds} (Q_l) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_l) = \lambda \rho_p \phi_l \pi r^2 & \text{Liquid water} \\ \frac{d}{ds} (Q_s) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_s) = 0 & \text{Solid} \end{array} \right]$$



Model of
Degruyter &
Bonadonna
(2013)

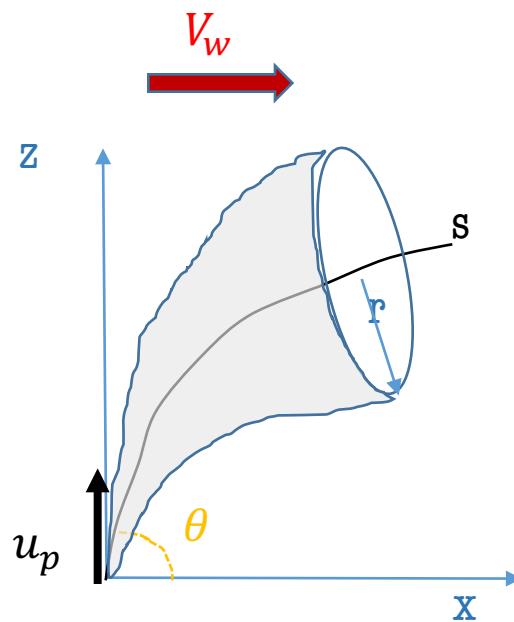


1-D steady state plume models

Mass flow rates	$\frac{d}{ds} (Q_d) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_d) = 2\pi r \rho_{ad} \phi_{ad} U_e$ $\frac{d}{ds} (Q_v) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_v) = 2\pi r \rho_{av} \phi_{av} U_e - \lambda \rho_p \phi_v \pi r^2$ $\frac{d}{ds} (Q_l) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_l) = \lambda \rho_p \phi_l \pi r^2$ $\frac{d}{ds} (Q_s) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_s) = 0$	Dry air Water vapor Liquid water Solid
Momentum flow rates	$\frac{d}{ds} (W_z) = \frac{d}{ds} (\rho_p \pi r^2 u_p^2 \sin(\theta)) = (\rho_a - \rho_p) g \pi r^2$ $\frac{d}{ds} (W_x) = \frac{d}{ds} (\rho_p \pi r^2 u_p^2 \cos(\theta)) = 2\pi \rho_a U_e r V_w$	Along z-direction Along x-direction



Model of
Degruyter &
Bonadonna
(2013)



1-D steady state plume models

Mass flow rates	$\frac{d}{ds} (Q_d) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_d) = 2\pi r \rho_{ad} \phi_{ad} U_e$ $\frac{d}{ds} (Q_v) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_v) = 2\pi r \rho_{av} \phi_{av} U_e - \lambda \rho_p \phi_v \pi r^2$ $\frac{d}{ds} (Q_l) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_l) = \lambda \rho_p \phi_l \pi r^2$ $\frac{d}{ds} (Q_s) = \frac{d}{ds} (\rho_p \pi r^2 u_p \phi_s) = 0$	Dry air Water vapor Liquid water Solid
Momentum flow rates	$\frac{d}{ds} (W_z) = \frac{d}{ds} (\rho_p \pi r^2 u_p^2 \sin(\theta)) = (\rho_a - \rho_p) g \pi r^2$ $\frac{d}{ds} (W_x) = \frac{d}{ds} (\rho_p \pi r^2 u_p^2 \cos(\theta)) = 2\pi \rho_a U_e r V_w$	Along z-direction Along x-direction
Heat flow rate	$\frac{d}{ds} (H) = \frac{d}{ds} (\rho_p \pi r^2 u_p C_p T) = 2\pi \rho_a U_e r C_a T_a - \rho_p \pi r^2 u_p g \sin(\theta) + \lambda \cdot \frac{d}{ds} (Q_l)$	



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Exercise 2: roll up your sleeves!
It is time for Matlab!



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End of the lesson
[Thank you for your attention]

{ for any question or doubt Eduardo.Rossi@unige.ch }



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For those of you who need
more physical justifications
to some of the formula
used in the lesson



Hydrostatic pressure

[...the algebra continues]

$$0 = -g \cdot \hat{\mathbf{z}} - \frac{P(z + \Delta z) \cdot V}{m \cdot \Delta z} \hat{\mathbf{z}} + \frac{P(z) \cdot V}{m \cdot \Delta z} \hat{\mathbf{z}}$$

$$\frac{P(z + \Delta z)}{\Delta z} \hat{\mathbf{z}} - \frac{P(z)}{\Delta z} \hat{\mathbf{z}} = -\frac{mg}{V} \cdot \hat{\mathbf{z}}$$

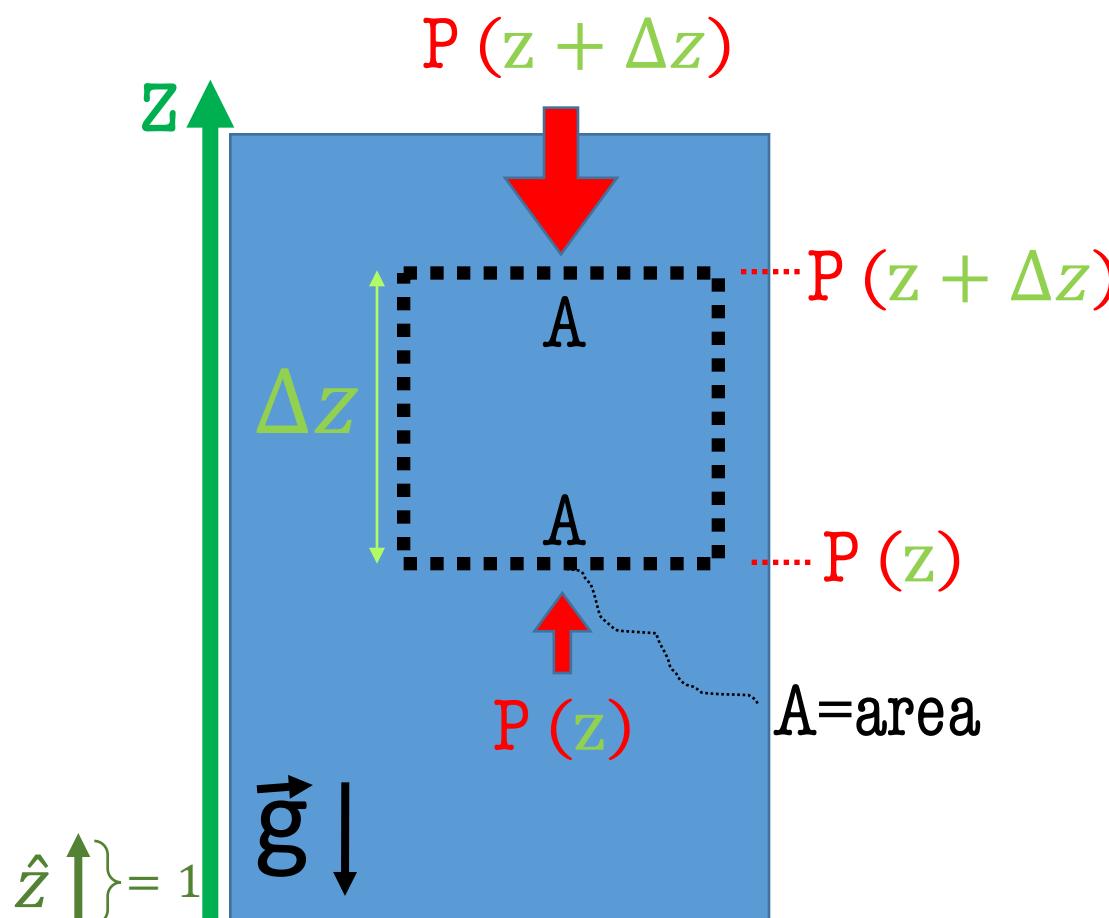
$$\frac{P(z + \Delta z) - P(z)}{\Delta z} \hat{\mathbf{z}} = -\frac{mg}{V} \cdot \hat{\mathbf{z}}$$

$$\frac{P(z + \Delta z) - P(z)}{\Delta z} \hat{\mathbf{z}} = -\rho_F \cdot g \cdot \hat{\mathbf{z}}$$

Limit for $\Delta z \rightarrow 0$

We take the limit for an infinitesimal box (i.e. $\Delta z \rightarrow 0$)

$$\lim_{\Delta z \rightarrow 0} \frac{P(z + \Delta z) - P(z)}{\Delta z} \hat{\mathbf{z}} = -\rho_F \cdot g \cdot \hat{\mathbf{z}}$$



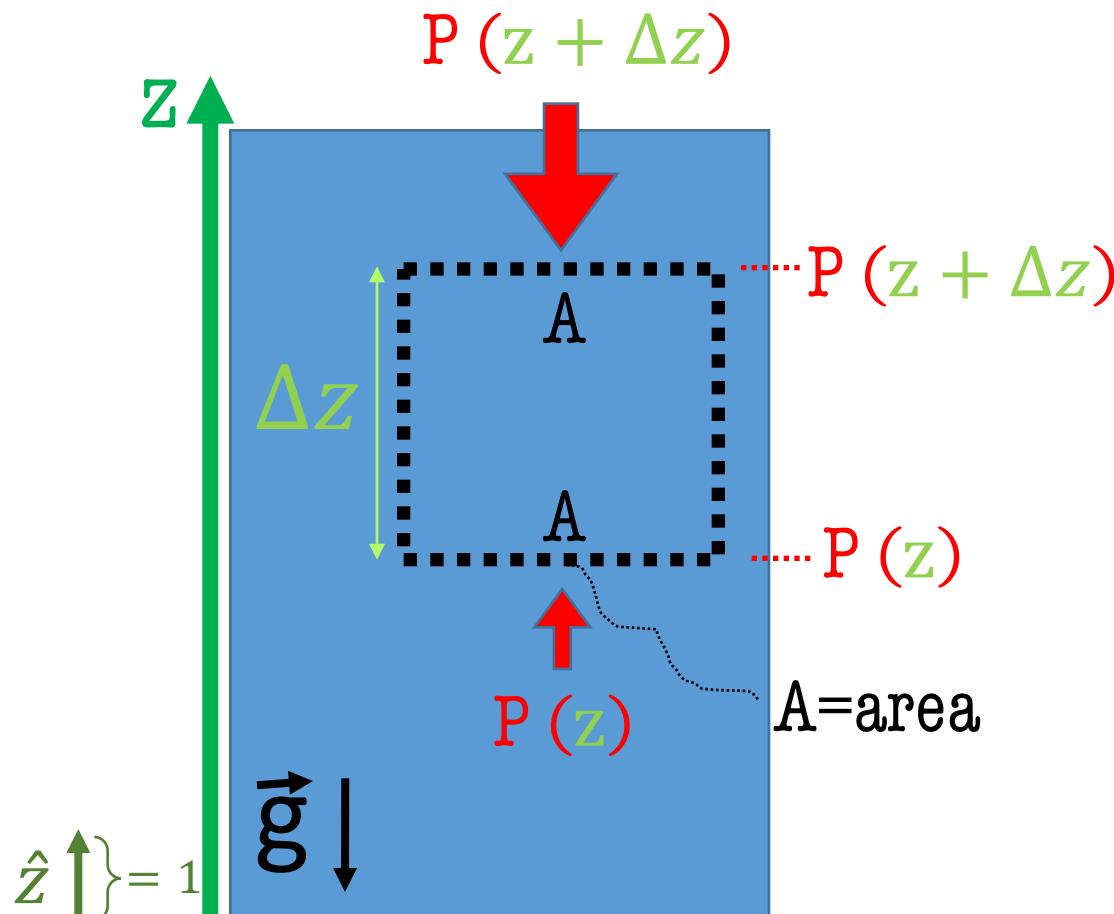


Hydrostatic pressure

[...the limit continues]

We take the limit for an infinitesimal box (i.e. $\Delta z \rightarrow 0$)

$$\lim_{\Delta z \rightarrow 0} \frac{P(z + \Delta z) - P(z)}{\Delta z} \hat{\mathbf{z}} = -\rho_F \cdot g \cdot \hat{\mathbf{z}}$$



Hydrostatic pressure

$$\frac{\partial P}{\partial z} \hat{\mathbf{z}} = -\rho_F \cdot g \cdot \hat{\mathbf{z}}$$

Case 1: $\rho_F = \text{constant}$

Stevin's law

Case 2: $\rho_F \neq \text{constant}$

Barometric law



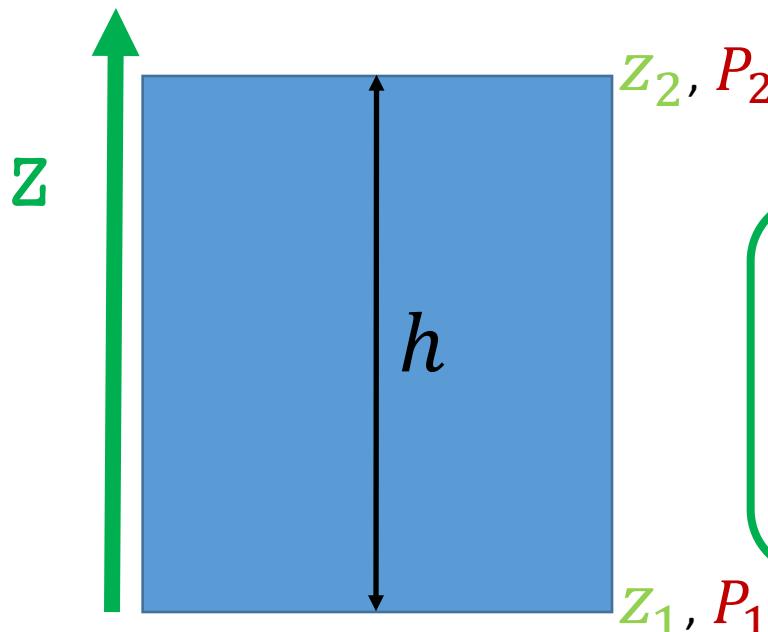
Hydrostatic pressure for a constant density

Hydrostatic pressure

$$\frac{\partial P}{\partial z} \hat{\mathbf{z}} = -\rho_F \cdot g \hat{\mathbf{z}}$$

Case 1: $\rho_F = \text{constant}$

$$\frac{\partial P}{\partial z} \hat{\mathbf{z}} = -\rho_F \cdot g \hat{\mathbf{z}} \rightarrow \int_{P_1}^{P_2} dP = -\rho_F \cdot g \int_{z_1}^{z_2} dz \rightarrow P_2 - P_1 = -\rho_F \cdot g \cdot (z_2 - z_1)$$



Stevin's law $P_2 - P_1 = -\rho_F \cdot g \cdot (z_2 - z_1)$

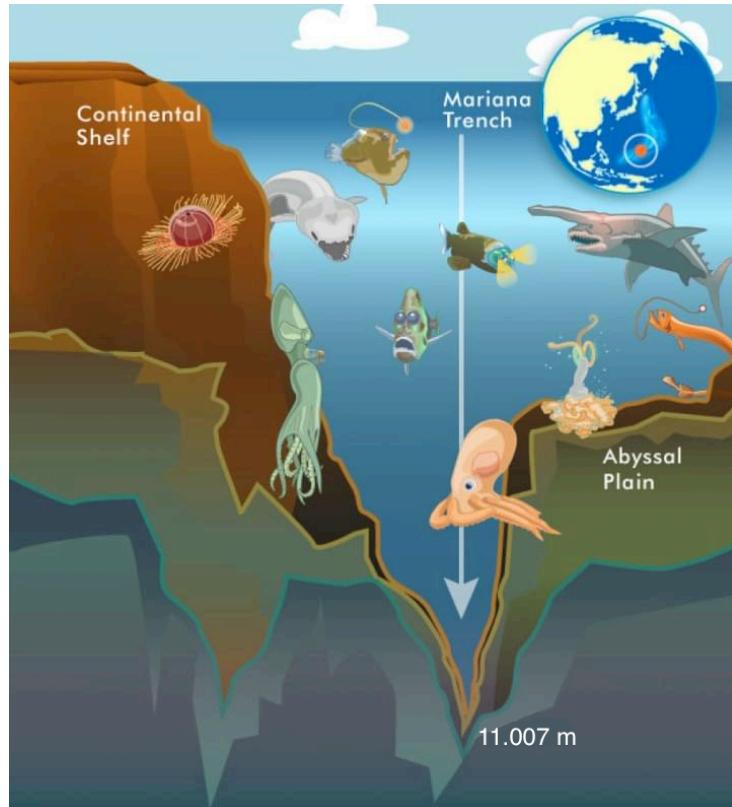
$$P_2 = P_1 - \rho_F \cdot g \cdot h$$



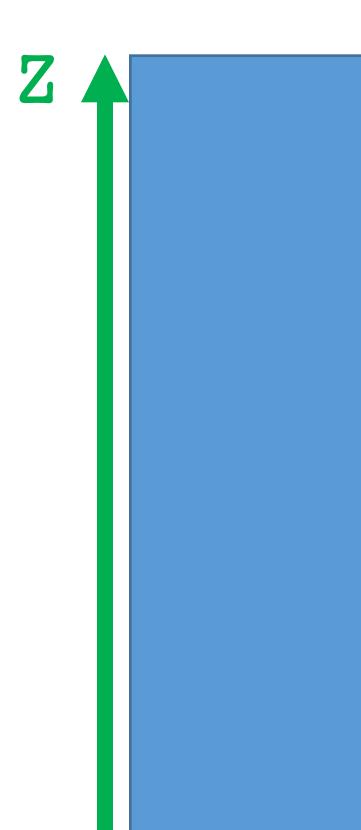
Application of Stevin's law

Stevin's law $P_2 - P_1 = -\rho_F \cdot g \cdot (z_2 - z_1)$

Example What is the pressure at the bottom of the Marianas trench?



Credits: www.travel365.it



$$z_2 = 11.000 \text{ m}$$
$$P_2 = 10^5 \text{ Pa}$$

$$P_1 = 10^5 \text{ Pa} +$$
$$10^3 \frac{\text{kg}}{\text{m}^3} \cdot 10 \frac{\text{m}}{\text{s}^2} \cdot 1.1 \cdot 10^4 \text{ m} = 1.1 \cdot 10^8 \text{ Pa}$$

$P_1 \approx 1000 P_2!$

$$z_1 = 0 \text{ m}$$
$$P_1 = ?$$



Hydrostatic pressure for a variable density

Hydrostatic pressure

$$\frac{\partial P}{\partial z} \hat{\mathbf{z}} = -\rho_F(z) \cdot g \hat{\mathbf{z}}$$

Case 2: $\rho_F \neq \text{constant}$

Perfect gas law: $P = \rho_F \cdot \frac{RT}{\mu}$

$$\frac{\partial(\rho_F(z) \frac{RT}{\mu})}{\partial z} \hat{\mathbf{z}} = -\rho_F(z) \cdot g \hat{\mathbf{z}} \rightarrow \frac{\partial(\rho_F(z))}{\partial z} \hat{\mathbf{z}} = -\frac{\mu g}{RT} \rho_F(z) \hat{\mathbf{z}}$$

$$\frac{d\rho_F}{\rho_F} = -\frac{\mu g}{RT} dz \rightarrow \int_{\rho_a}^{\rho_b} \frac{d\rho_F}{\rho_F} = -\frac{\mu g}{RT} \int_{z_a}^{z_b} dz \rightarrow \log \rho_b - \log \rho_a = -\frac{\mu g}{RT} (z_b - z_a)$$

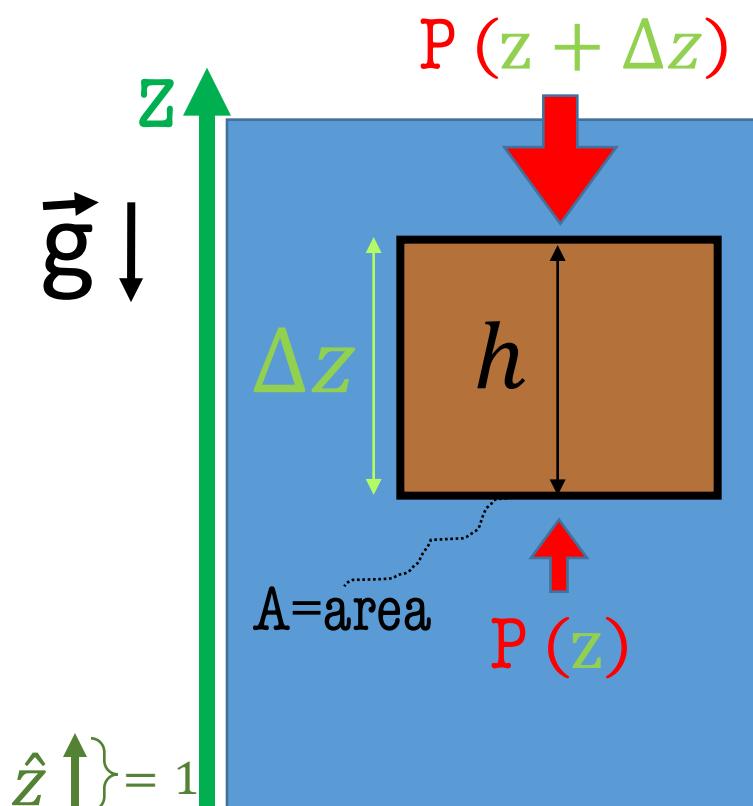
$$\log \frac{\rho_b}{\rho_a} = -\frac{\mu g}{RT} (z_b - z_a) \rightarrow \rho_b = \rho_a \cdot e^{-\frac{\mu g}{RT} (z_b - z_a)}$$

Barometric law

*Be careful! Here we assumed that the temperature is NOT a function of z ... which is not true!



Archimedes' principle and buoyancy



Stevin's law $P_2 = P_1 - \rho_F g h$

Newton's law $\vec{a} = \frac{1}{m} (\vec{F}_g + \vec{F}_P)$

$$ma \hat{z} = -mg \hat{z} - [P(z + \Delta z) - P(z)] A \hat{z}$$

Stevin's law

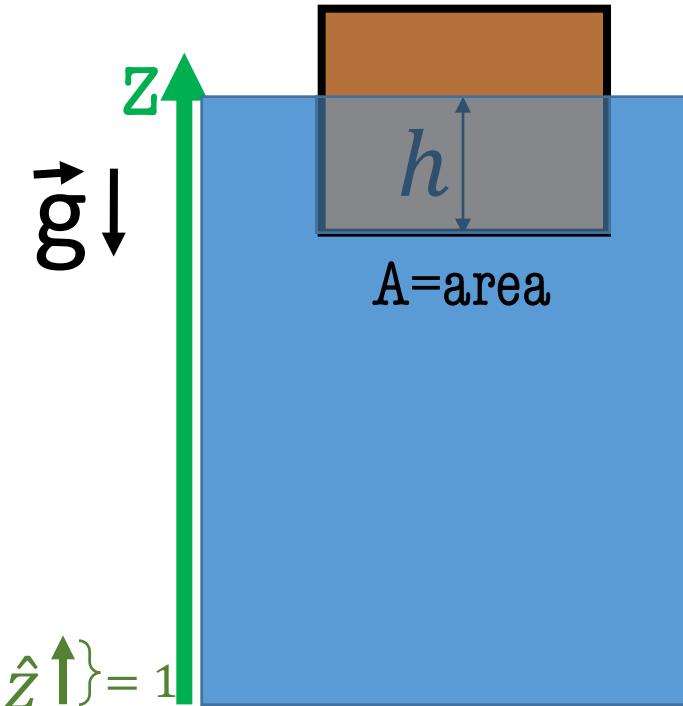
$$ma \hat{z} = -mg \hat{z} - [-\rho_F g h] A \hat{z} \rightarrow ma \hat{z} = -mg \hat{z} + \rho_F g V \hat{z}$$

Archimedes' principle

$$a \hat{z} = -g \hat{z} + \rho_F g \frac{V}{m} \hat{z} \rightarrow a \hat{z} = -g \hat{z} + g \frac{\rho_F}{\rho_p} \hat{z}$$

$$a \hat{z} = -g \left[1 - \frac{\rho_F}{\rho_p} \right] \hat{z}$$

Buoyancy



The “Duck” problem

$$ma \hat{\mathbf{z}} = -mg \hat{\mathbf{z}} + \rho_F g V_{sub} \hat{\mathbf{z}}$$

There is no net acceleration:

$$0 \hat{\mathbf{z}} = -mg \hat{\mathbf{z}} + \rho_F g V_{sub} \hat{\mathbf{z}}$$

$$m = \frac{\rho_F g V_{sub}}{g} \rightarrow m = \rho_F \cdot V_{sub}$$

Referring to the figure aside: $m = \rho_F \cdot (A \cdot h)$

And what about the mass of the duck?

$$m_{duck} = \rho_F \cdot V_{ds}$$