The Barnes-Hut N-Body Approximation

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Why Newtonian N-Body?

- For some important problems, GR is not a significant correction
 - Finite speed of gravity is not relevant
 - Bodies all have v << c, no gravitational waves
 - Curvature of space is small
 - Universal expansion can be added manually
- GR-based calculations become difficult for manybody interactions
- Can be coupled with fluid dynamics simulations, or field approaches (particle in cell)
- Also useful for Björk concerts

Problem: N-Body Simulation

 Compute accelerations of N bodies, each by summing the influence of the N-1 other bodies

$$oldsymbol{a_n} = \sum_{i=1}^N rac{Gm_i}{r_{ni}^3} oldsymbol{r_{ni}}$$

- Each step is thus ½ * N * (N-1) ~
 O(N²) operations
 - But to realize ½ improvement adds
 ¼ * N * (N-1) memory requirement
- Time-domain advance via Euler, explicit RK, leapfrog, etc, etc.

Why optimize?

- A galaxy contains ~10¹¹ stars
- Blue Waters is $\sim 10 \text{ Pflops} = 10^{13} \text{ operations/sec}$
- At O(N²): ~10²² operations
 - Step takes 109 seconds or ~30 years
- At O(N log(n)): ~10¹² operations
 - Step takes 0.1 seconds!*

*Restrictions apply. See caveats later.

Barnes-Hut Overview

Far-away masses pull in roughly the same direction



Why not consolidate them into one?

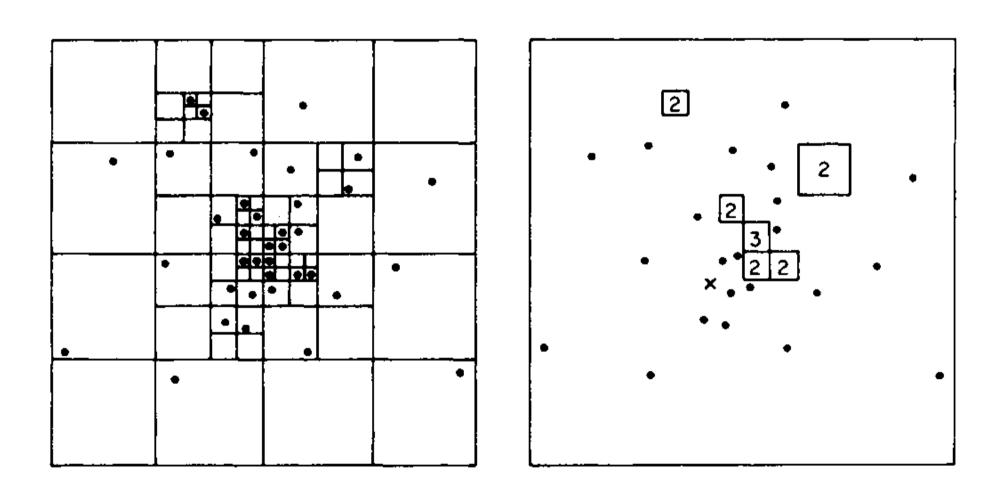


- Group by "cells." Keep track of the center of mass and total mass of each cell
- Then, if a cell is small "enough" to consolidate, we can look up its CM and avoid touching all its children

Building the tree

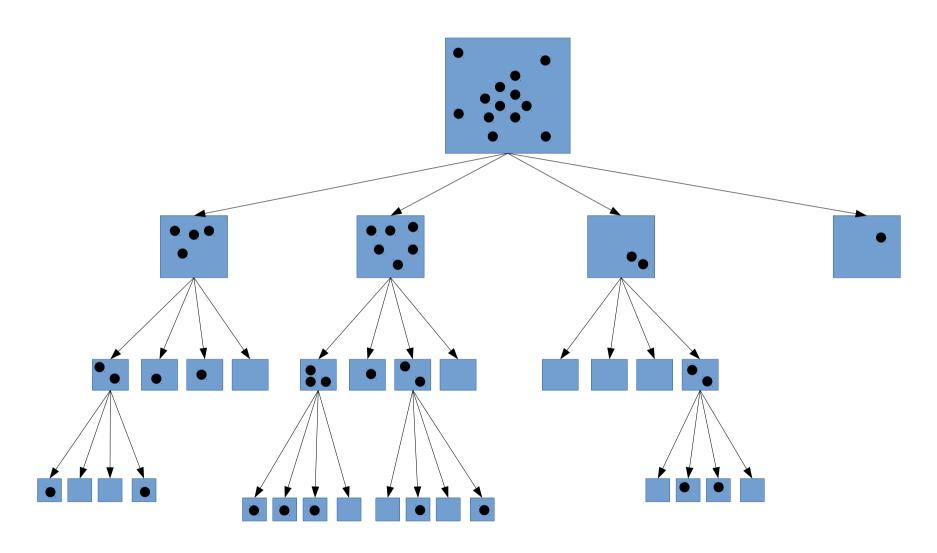
- Add bodies to cells recursively to build a tree
- To add a body:
 - Start by adding the body to the root cell
 - Add the body to the cell's CM and mass
 - If the cell already encloses a body:
 - If the cell has no children, add them and propagate the body it currently encloses
 - · Add the new body to the appropriate child and repeat if it is occupied
- Thus, there will be O(N) leaf cells always have one body at most, and a tree of larger cells
- Complexity is O(log N) per body, total O(N log(N))

2D Tree Example

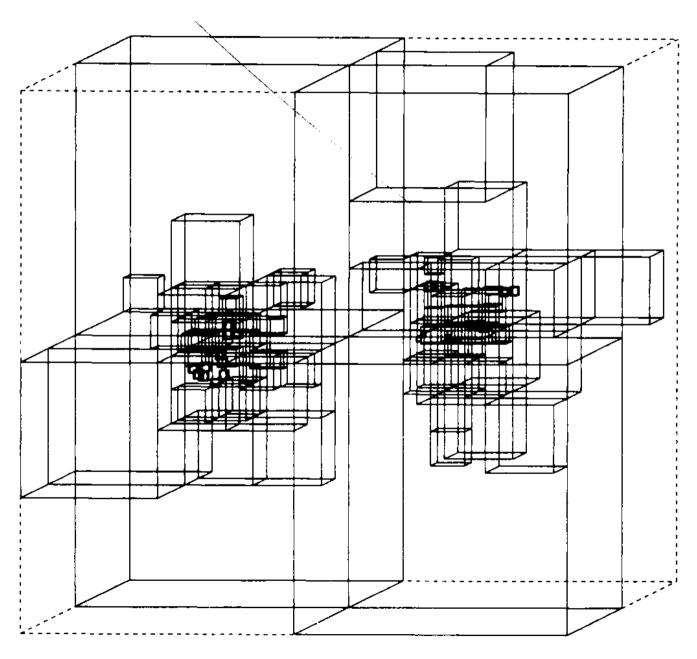


Images: Barnes & Hut

2D Tree in Memory



3D Tree



Step Algorithm

- To compute influence on a body:
 - Recursively walk the tree, summing the effect of child cells to obtain the effect of larger cells
 - When the diameter of the cell becomes less than a certain factor of its distance away, disregard its children and use its COM and mass
 - The total influence is the acceleration due to the root cell
- Only O(log N) cells have radii large enough to be summed

Step Algorithm: Details

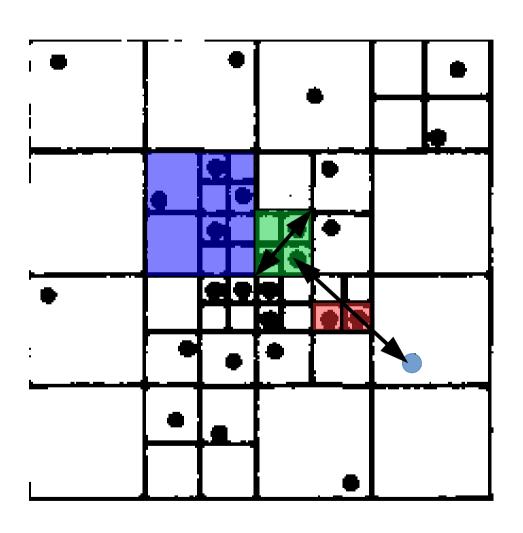
```
• From the original paper (in LISP):
(define (acceleration particle ensemble)
  (cond ((singleton? ensemble)
      (newton-accel particle (the-element ensemble)))
      ((< (/ (diameter ensemble)
          (distance particle (centroid ensemble)))
        theta)
      (newton-accel particle (centroid ensemble)))
      (else
      (reduce sum-vector
          (map (lambda (e) (acceleration particle e))
             (subdivisions ensemble))))))
```

Step Algorithm: Translation

Perhaps more readable:

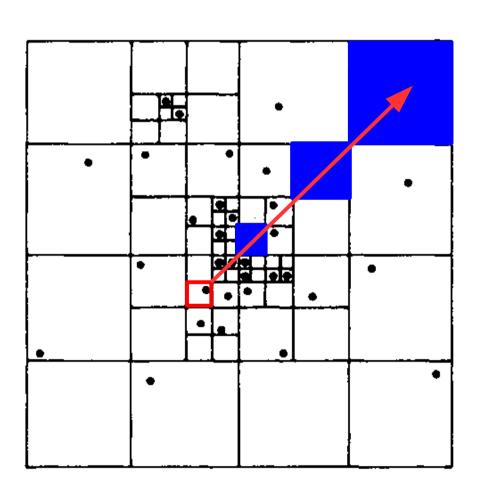
```
def find_accel(self, body, cell):
    """"Finds the gravitational effect on 'body' of whatever is inside 'cell'"""
    if (cell.children is None) or (cell.diameter / norm(body.pos - cell.COM) < self.theta):
        return self.newton_accel(body, cell.COM, cell.mass)
    else:
        return sum([self.find_accel(body, child) for child in cell.children])</pre>
```

Step Example



- Red squares are added just as N² algorithm would
- Green square uses COM of three bodies since diameter is smaller than distance as shown
- Further squares lump more space together into groups of similar subtended angle

O(log(N)) Boxes are Counted



- Each "ring" of 12 boxes triples the area covered
- Thus N operations covers C*3^{N/12} units of area
- So necessary operations go as log₃(N/12)~log(N) with area
- Similar effect in 3D

Parallelization Notes

- The tree-building half of the algorithm is difficult to efficiently parallelize
 - The tree cannot easily be accessed in parallel
 - The first N levels of the tree can be precomputed, and the construction of the rest of the tree passed to 8^N threads
 - However, resulting cells can be very unbalanced
- The rest of the algorithm, however, just needs to read the tree and update the locations, which are independent and thus easy to parallelize

Parallel Version

Construct tree:

- Split list of N particles among available processors, and compute lists of what resides in the first 8^m sub-trees
- Dynamically load-balance the computation of each of the 8^m sub-trees across available threads
- Merge sub-trees (m*8^m operations in 1 thread)

Compute forces:

- Trivially parallel if each thread has full tree access
 - Tree takes O(N log(N)) memory! May have to be split
- Otherwise request elements of others' subtrees as necessary
- Update velocities/positions
 - Trivially parallel

Links

- Original Paper:
 - Barnes & Hut, "A hierarchical O(N log N) force-calculation algorithm,"
 - Nature 324, 446 449 (04 December 1986); doi:10.1038/324446a0
 - http://www.nature.com/nature/journal/v324/n6096/abs/324446a0.html
- Parallel examples:
 - https://scala-blitz.github.io/home/documentation/examples//barneshut.html
 - http://ta.twi.tudelft.nl/PA/onderwijs/week13-14/Nbody.html
- Gravitational interaction speed:
 - https://arxiv.org/abs/gr-qc/9909087
- Notable N-body simulations:
 - http://hipacc.ucsc.edu/Bolshoi/
 - http://wwwmpa.mpa-garching.mpg.de/millennium/
- Björk concert:
 - "Dark Matter," Bestival 2011
 - https://www.youtube.com/watch?v=dkagu0qWBio