Maple Script

Set up

```
> restart;
   with(LinearAlgebra):
   with (PDEtools):
   with (plots):
   with(CodeGeneration):
   declare(h1(t,x),eta1(t,x),h2(t,x),eta2(t,x)):
   constants:=constants,H1,H2,m2,m3,sigma1,sigma2:
                            h1(t,x) will now be displayed as h1
                             \eta l(t, x) will now be displayed as \eta l
                             h2(t,x) will now be displayed as h2
                            \eta 2(t, x) will now be displayed as \eta 2
                                                                                               (1.1)
> A:=Matrix(7,7,[[h1(t,x)^2/2,-h1(t,x)^2/2/m2,0,h1(t,x),-h1(t,x)]
   /m2,-1/m2,0],
   [0,h2(t,x)^2/2/m2,-(h2(t,x)-1)^2/2/m3,0,h2(t,x)/m2,1/m2,-(h2(t,x)/m2)]
   x)-1)/m3],
    [h1(t,x),-h1(t,x),0,1,-1,0,0],
    [0,h2(t,x),-(h2(t,x)-1),0,1,0,-1],
   [1,-1,0,0,0,0,0],
   [0,1,-1,0,0,0,0],
   [h1(t,x)^3/6, (h2(t,x)^3-h1(t,x)^3)/6/m2, (-(h2(t,x)-1)^3)/6/m3,
   h1(t,x)^2/2, (h2(t,x)^2-h1(t,x)^2)/2/m2, (h2(t,x)-h1(t,x))/m2, (-1)^2/m2
   (h2(t,x)-1)^2)/2/m3]]);
   a := Vector(7, [0,0,0,0,-diff(h1(t,x),x$3)*sigma1,-diff(h2(t,x),x$))
   x$3) *sigma2,Q]);
A := \left[ \left[ \frac{1}{2} h I^2, -\frac{1}{2} \frac{h I^2}{m 2}, 0, h I, -\frac{h I}{m 2}, -\frac{1}{m 2}, 0 \right],
    \left[0, \frac{1}{2}, \frac{h2^2}{m2}, -\frac{1}{2}, \frac{(h2-1)^2}{m3}, 0, \frac{h2}{m2}, \frac{1}{m2}, -\frac{h2-1}{m3}\right],
   [h1, -h1, 0, 1, -1, 0, 0],
   [0, h2, -h2 + 1, 0, 1, 0, -1],
 1, -1, 0, 0, 0, 0, 0, 0
 \left[0, 1, -1, 0, 0, 0, 0\right]
    \left[\frac{1}{6}hI^3, \frac{1}{6}\frac{h2^3-hI^3}{m2}, -\frac{1}{6}\frac{(h2-1)^3}{m3}, \frac{1}{2}hI^2, \frac{1}{2}\frac{h2^2-hI^2}{m2}, \frac{h2-hI}{m2}, \right]
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-\frac{1}{2} \frac{(h2-1)^2}{m3}
                               a := \begin{vmatrix} 0 \\ 0 \\ -hI_{x, x, x} \sigma I \\ -h2_{x, x, x} \sigma 2 \\ O \end{vmatrix}
                                                                                 (1.2)
\begin{bmatrix} u1 = p1x/2*y^2 + c1*y \\ u2 = p2x/(2*m2)*y^2 + c2/m2*y + c3/m2 \\ u3 = p3x/(2*m3)*(y-1)^2 + c4/m3*(y-1) \\ b = [p1x,p2x,p3x,c1,c2,c3,c4] \end{bmatrix}
 Solving and building solutions
 > b:=factor(MatrixInverse(A).a):
   u1:=collect(b[1]*y^2/2+b[4]*y,y,factor):
   u2 := collect(b[2]*y^2/2/m2+b[5]*y/m2+b[6]/m2,y,factor):
   u3:=collect(b[3]*(y-1)^2/2/m3+b[7]*(y-1)/m3,y,factor):
 > u1_steady = simplify(eval(u1, [sigma1 = 0, sigma2 = 0])) : 
   u2 steady = simplify(eval(u2, [sigma1 = 0, sigma2 = 0])):
   u3 steady = simplify(eval(u3, [sigma1 = 0, sigma2 = 0])):
> evolution eqn 1:=collect(int(u1,y=0..h1(t,x)), {diff(h1(t,x),
   x$3), diff(h2(\overline{t},x),x$3)}, factor): #NOTE: These equations still
   need to be differentated by x.
   evolution eqn 2:=collect(int(u3,y=h2(t,x)..1), {diff(h1(t,x),
   x$3),diff(h2(t,x),x$3)},factor):#NOTE: These equations still
   need to be differentated by x.
   evolution eqn 1 diff:=diff(evolution eqn 1, x):
   evolution eqn 2 diff:=diff(evolution eqn 2, x):
   evolution eqn 1 delta:=eval(evolution eqn 1, {h1(t,x)=H1+delta*
   eta1(t,x),h2(t,x)=H2+delta*eta2(t,x)):
   evolution eqn 2 delta:=eval(evolution eqn 2,{h1(t,x)=H1+delta*
   eta1(t,x),h2(\overline{t},\overline{x})=H2+delta*eta2(t,x)}):
   evolution_eqn_1_linear:=diff(etal(t,x),t)+diff(coeff(taylor
    (evolution_eqn_1_delta,delta,2),delta,1),x):
   evolution eqn 2 linear:=diff(eta2(t,x),t)-diff(coeff(taylor
    (evolution eqn 2 delta, delta, 2), delta, 1), x):
```

Dispersion Relation

```
> evolution_eqn_1_normal_modes:=simplify(eval
  (evolution_eqn_1_linear,{eta1(t,x)=A_1*exp(omega*t+I*k*x),eta2
  (t,x)=A_2*exp(omega*t+I*k*x)})/exp(omega*t+I*k*x)):
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```
evolution eqn 2 normal modes:=simplify(eval
  (evolution eqn \overline{2} linear, {eta1(t,x)=A_1*exp(omega*t+I*k*x),eta2
   (t,x)=A 2*exp(omega*t+I*k*x))/exp(omega*t+I*k*x):
  M:=Matrix(2,2,[coeff(evolution eqn 1 normal modes,A 1),coeff
  (evolution eqn 1 normal modes, A 2), coeff
  (evolution eqn 2 normal modes, A 1), coeff
   (evolution eqn 2 normal modes, A 2)]):
  dispersionRelation:=collect(Determinant(M),omega) = 0:
  #eigenvalues linear:=solve(dispersionRelation,omega):
  #eigenvalues linear real:=[Re(eigenvalues linear[1]), Re
  (eigenvalues linear[2])]:
Plotting the Dispersion Relation
> #plot(eval(eigenvalues linear real, [H1=5/12, H2=7/12, Q=1, m2=0.4,
  m3=0.4, sigma1=1, sigma2=1]), k=\overline{0}..5);
> #plot(max(eval(eigenvalues linear real,[H1=5/12,H2=7/12,Q=1,m2=
  0.4, m3=0.4, sigma1=1, sigma2=1])), k=0...5);
> #plot3d(eval(eigenvalues linear real,[H1=5/12,H2=7/12,sigma1=1,
  sigma2=1,Q=1,m3=0.4]),k=\overline{0}...5,m2=1...0.1,title="Dispersion
  Relation Plot");
> #contourplot(max(eval(eigenvalues linear real,[H1=5/12,H2=7/12,
  sigma1=1, sigma2=1, Q=1, k=1])), m2=0...3, m3=0...3, title="Dispersion"
  Relation Plot", filledregions = true, coloring = ["White",
  "DarkViolet"],contours=[0]);
> #interactiveparams(plot,[eigenvalues linear real,k=0..1],H1=0.
  .1, H2=0..1, sigma1=0..2, sigma2=0..2, Q=0..10, m2=0..2, m3=0..2);
> #interactiveparams(contourplot,[max(eigenvalues linear real),
  m2=0..1,m3=0..1,filledregions = true, coloring = ["White",
  "DarkViolet"],contours=[0]],H1=0..1,H2=0..1,siqma1=0..2,siqma2=
  0..2,Q=0..50,k=0..10);
```

▼ Determining the Eigenvalues of the Matrices

Linear

```
 \begin{bmatrix} \eta_t + Q \ G \cdot \begin{pmatrix} \eta_{1x} \\ \eta_{2x} \end{pmatrix} + F \cdot \begin{pmatrix} \eta_{1xxxx} \\ \eta_{2xxxx} \end{pmatrix} = 0 
 \begin{bmatrix} \text{Surface Tension} \\ > F = \text{linear} := \text{simplify} (\text{Matrix}(2, 2, [\text{coeff} (\text{evolution eqn 1 linear}, \text{diff}(\text{eta1}(t, x), x\$4)), \text{coeff} (\text{evolution eqn 2 linear}, \text{diff}(\text{eta2}(t, x), x\$4)), \text{coeff} (\text{evolution eqn 2 linear}, \text{diff}(\text{eta1}(t, x), x\$4)), \text{coeff} (\text{evolution eqn 2 linear}, \text{diff}(\text{eta2}(t, x), x\$4))]): \\ \text{simplify} (\text{Eigenvalues}(F_{\text{linear}}): \\ \end{bmatrix} 
 \begin{bmatrix} Flux \\ > g = \text{linear} := \text{simplify} ([\text{coeff}(\text{evolution eqn 1 linear}, Q), \text{coeff} (\text{evolution eqn 2 linear}, Q)]): \\ \text{General equation} \\ \text{General equa
```

```
G linear[2,1]):
   eigenvalues linear:=simplify(Eigenvalues(G linear)):
Non-linear
h t + (g*Q + f 1*h 1xxx + f 2*h 2xxx) x = 0
> g nonlinear:=[coeff(evolution eqn 1, Q),-coeff
   (evolution eqn 2, Q)]:
   G nonlinear:=Matrix(2,2,[Physics[diff](q nonlinear,h1(t,x)),
   Physics[diff](g nonlinear,h2(t,x))]):
   simplify(G nonlinear[1,2]*G nonlinear[2,1]):
   eigenvalues nonlinear := Eigenvalues(G nonlinear):
   interface1:=0.4+(2^{(-5)})*\cos(x):
   interface2:=0.6+(2^{(-5)})*\cos(x+theta):
> plot(eval([0,interface1,interface2,1],theta = 0),x=0..2*Pi,
   title="Interfaces"):
> plot(eval(eigenvalues nonlinear,eval([h1(t,x)=interface1,h2
   (t,x)=interface2, m2=0.8, m3=0.6], theta = 0)), x=0..2*Pi, title=
   "Eigenvalues"):
> interactiveparams(plot,[eval(eigenvalues nonlinear,[h1(t,x)=
   interface1,h2(t,x)=interface2,m2=0.8,m3=\overline{0}.6]),x=0..2*Pi,
   title="Eigenvalues"], theta=0..Pi):
```