ALTEGRAD Project Presentation: Cellular Component Ontology Prediction

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1. Introduction

 Proteins are essential biomolecules that play important roles in living organisms, including acting as enzymes and providing structural support.

• The **structure of proteins is determined by the sequence of amino acids**, which fold to form a 3D structure that determines their specific chemical functionality, but the exact details of this process are not yet fully understood.

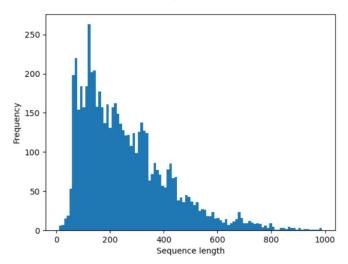
We propose to study and apply machine learning/deep learning techniques to classify 6k+ proteins into
 18 different classes, each representing a characteristic of a protein

Two different types of models where implemented: sequence based and structure based models will be
used for the classification task

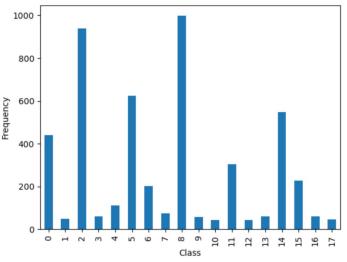
2.1. Methodology - Data Used

- This project aims to classify a dataset of 6,111 proteins into 18 different classes, each representing a characteristic of the protein.
- Some of the proteins are labeled (4888) while others are not (1223).
- For **sequence based models**, we used the sequence of each protein and the labels associated.
- For structure based models, we used edges, attributes of the edges, attributes of the nodes, graph indicators and labels for the proteins
- The goal of the project is to predict the class label of proteins that have not been labeled.

2.2. Methodology - Data Analysis



Distribution of the sequence length over training and testing set



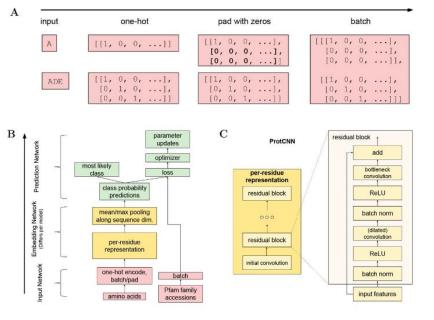
Distribution of the number of examples per class over training set

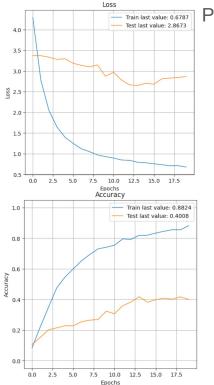
- For **sequence base** models, we will use a sequence length of 512.
- We will also change the sampling method during training by taking a **weighted random sampler** to get an evenly distributed dataset.

- 1. Modifications made on the sequence baseline
 - Modify the number of n-grams:
 - Trying with 3 to 7 n-grams taken into account => decrease of the performances

- Modify the classifier used in the sequence baseline
 - Initially: Logistic regression
 - Change using Support Vector Machine
 - Change using Decision Tree

2. Protein Computational Neural Network (ProtCNN)

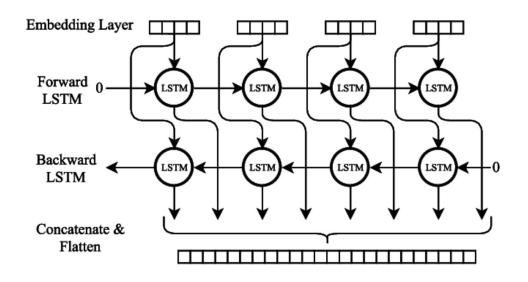




Problem: overfitting

- Added cross validation (Kfold =5)
- Added class weight
- Intended up/downsampling
- Added more regularization
- Early Stopping

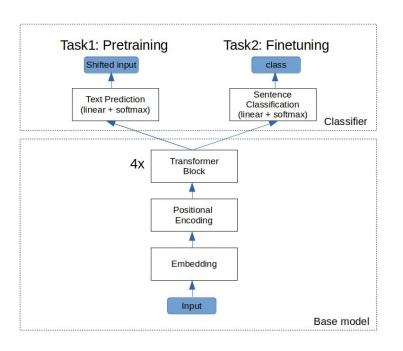
3. Bidirectional Long Short Term Memory (BiLSTM)



Problem: overfitting

- Added cross validation (Kfold =5)
- Added class weight
- Intended up/downsampling
- Added more regularization
- Early Stopping
- Added dropout

4. Fine-tuning pretrained models (Transfer Learning)



- Use a ProtBERT pretrained model on BFD dataset (2.1 billion sequences).
- Adding a classifier head automatically with Hugging Face AutoModelForClassification.
- Freezing the pretrained model.
- Using a starting learning rate of 10⁻³ with a decay of 10 every 5 epochs. We train for 25 epochs.

2.4. Methodology - Structure based models

Model $h^{(k)}_{t+1,v}$

$$\mathscr{G} = (V, E, \{h_v^0\}_{v \in V}, \{q_e^0\}_{e \in E})$$

$$\{h_{t-1,u}^{(k)}||e_{u,v}\}_{u\in\bar{N}_{t-1}\{v\}}\} =$$

$$\{V, E, \{h_v^o\}_{v \in V}, \{q_e^o\}_{e \in E}\}$$
 $\{v, \{h_{t-1,u}^{(k)} | | e_{u,v}\}_{u \in \bar{N}_v \cup \{v\}}\} = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(u,u)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(u,u)}^{(k)} \cdot (V_t^{(k)}) = \sum_{u \in \bar{N}_v \cup \{v$

layers.

Group Norm

Group Norm

$$\begin{aligned} \text{ATT}(h_{t-1,v}^{(k)}, \{h_{t-1,u}^{(k)} || e_{u,v}\}_{u \in \bar{N}_v \cup \{v\}}) = \\ \sum_{u \in \bar{N}_v \cup \{v\}} \alpha_{t,(v,u)}^{(k)} \cdot (V_t^{(k)}[h_{t-1,u}^{(k)} || e_{u,v}]) \end{aligned}$$

$$\alpha_{t,(v,u)}^{(k)} = \text{SoftMax}\left(\frac{(Q_t^{(k)}h_{t-1,v}^{(k)}) \cdot (K_t^{(k)}[h_{t-1,u}^{(k)}||e_{u,v}])}{\sqrt{d}}\right)$$

Cross Attention
$$V$$

$$\downarrow Q$$

$$h^{(k)}_{t,v} \qquad \{h^{(k)}_{t,u} \mid\mid e_{u,v}\}_{u \in N_v \cup \{v\}}$$

 $\hat{\mathbf{y}}_{\mathcal{G}} = \operatorname{softmax} (\mathbf{We}_{\mathcal{G}} + \mathbf{b})$

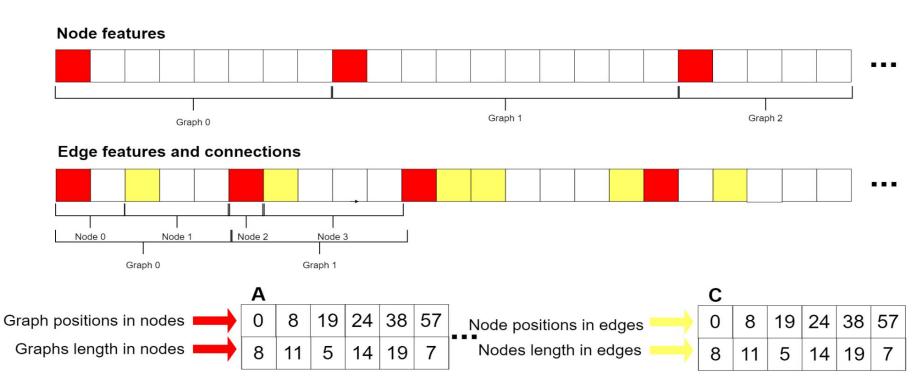
 $\mathbf{e}_{\mathsf{v}} = \left| \mathbf{h}_{0,\mathsf{v}}^{(1)}; \mathbf{h}_{0,\mathsf{v}}^{(2)}; ...; \mathbf{h}_{0,\mathsf{v}}^{(K)} \right|, \forall \mathsf{v} \in \mathcal{V}$

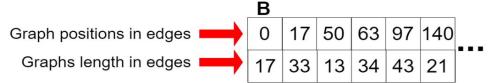
Input : [B, L+1, NF+NE]

K Transformer blocks. T Transformer encoder

2.4. Methodology - Structure based models

Preprocessing





2.4. Methodology - Structure based models

Preprocessing

- We construct an array D of size [E,K,|V|,L] = [Epochs, n_blocks, n_nodes, n_neighbors],
 - B[:, :, v, :] is a tensor with entries sampled U{0, ..., B[v,1]}, where B[v,1]} represents the number of neighbors of node v.
- We add D[...] + B[:,0] to obtain the positions of the generated node neighbors in the edge features and connections array. We access the values of the edge connections array for these indices and obtain the neighbors' node positions in node features.
- To create a batch, we shuffle [A, B, C], and concatenate sequentially graphs until the total number nodes in the batch overpass the max batch node length. We need to update the positions of graphs in sliced A and B arrays and nodes in sliced C array relative to the starting graph and node in the batch.
- A batch is composed of the node and edge features, the updated sliced array A B graphs positions in node and edge features, and the updated sliced array C of nodes positions in edge features and edge connections, the sequence of labels corresponding to the graph found in the batch, the neighbors position list in nodes features and edge features for all nodes in the batch and blocks in the model.

3.1. Results - Metrics used

Multi-class log: Mainly focused on as it is the one used in kaggle

$$-\frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{C} y_{ij} \log(p_{ij})$$

Accuracy: In order to have a more concrete idea of what we were predicting

3.2. Results - On sequence-based models

Sequence-Based models						
		Modified	Modified			
	Sequence baseline	sequence	sequence	ProtCNN	BiLSTM	ProtBERT
		baseline -	baseline -			
		SVM	decision tree			
Loss	1.67	1.61	1.92	2.2	2.1	2.35
Accuracy	50.7%	48.3%	38.2%	38.5%	35%	20%

4. Conclusion

We tried several methods for sequence and structure based models.

 We didn't manage to beat largely the sequence baseline (only a very low increase of performances with SVM classifier)

We think that our poor results mainly come from the sampling of the data.

5. References

- [1] Maxwell L. Bileschi, David Belanger, Drew Bryant, Theo Sanderson, Brandon Carter, D. Sculley, Mark A. DePristo, and Lucy J. Colwell. Using deep learning to annotate the protein universe. May 2019.
- [2] Protein sequence classification (2022). https://deepnote.com/@ronakv/protein-sequence-classification- 33797a33-7311-48d3-8794-79a1ee26f406.
- [3] Ahmed Elnaggar, Michael Heinzinger, Christian Dallago, Ghalia Re- hawi, Yu Wang, Llion Jones, Tom Gibbs, Tamas Feher, Christoph An- gerer, Martin Steinegger, DEBSINDHU BHOWMIK, and Burkhard Rost. Prottrans: Towards cracking the language of life's code through self-supervised deep learning and high performance comput- ing. *bioRxiv*, 2020.
- [4] Dai Quoc Nguyen, Tu Dinh Nguyen, and Dinh Phung. Universal graph transformer self-attention networks, 2019.