Algorithms lab

Connecting Cities

Schedule

Please fetch the problem sheet in the front

16:15 - 17:00: solving the 3 problems algorithmically

17:00 - 17:10: break

17:10 - 18:00: discussing solutions followed by Q&A

Threefold Problem Set: Roads

Kalina Petrova, Meghana M. Reddy with some slides by Hafsteinn Einarsson November 30, 2022

Exercise – Connecting Cities

As a first step toward building a reliable infrastructure, the people of AlgoLand built a skeleton of the road network. The skeleton of the road network is just a list of possible roads, some of which will be actually built. Moreover, the list of possible roads is such that between every two cities in AlgoLand there exists exactly one path connecting them. You want to start building as many roads as possible at the same time.

There is a constraint, though: to avoid too much disruption you do not want to build two roads ending in the same city.

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Goal: Find a largest set of vertex disjoint edges.

Goal: Find a largest matching.

Goal

Find a largest matching

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BGL: $O(VE) = O(n^2)$.

Goal

Find a largest matching

BGL:
$$O(VE) = O(n^2)$$
 .

Points There are two test sets:

- 1. For the first set, worth 30 points, you may assume that the total number of cities is at most 500.
- 2. For the second set, worth 70 points, the total number of cities is at most 10^6 .

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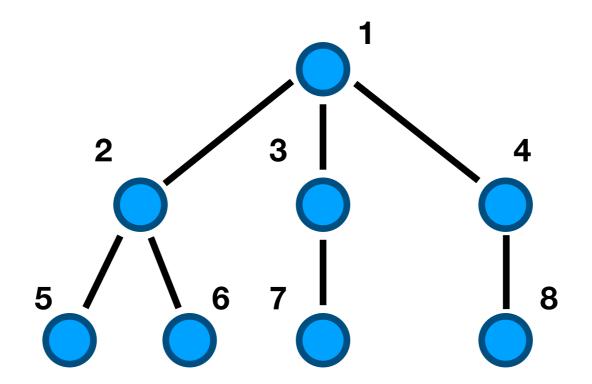


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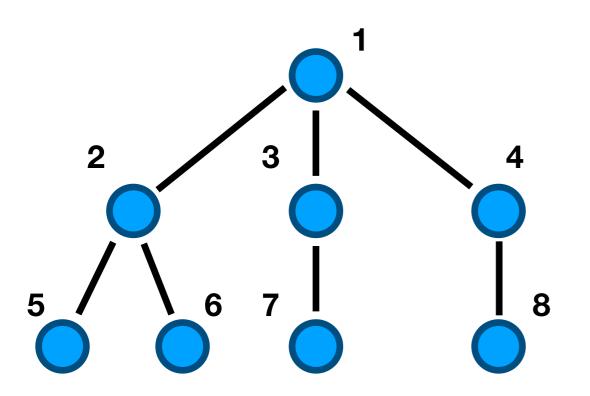
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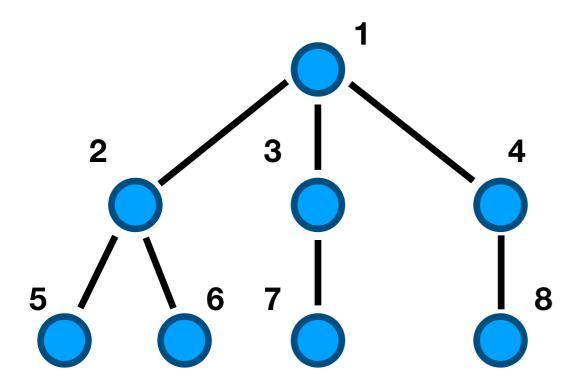
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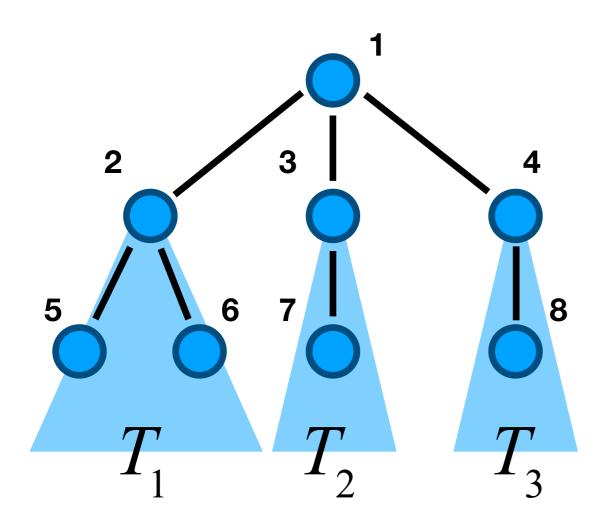


Input graph is a tree

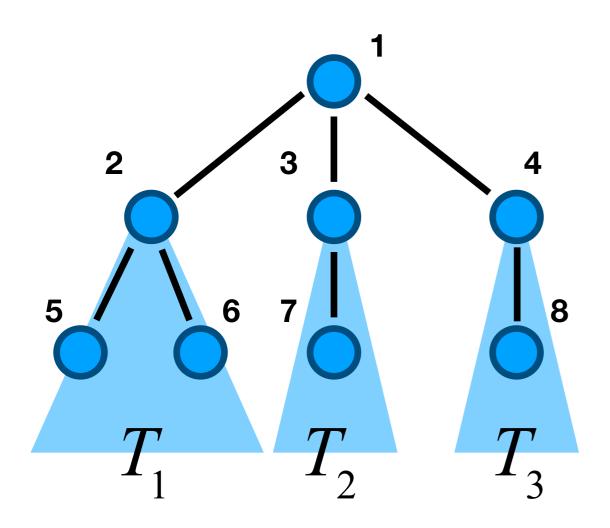




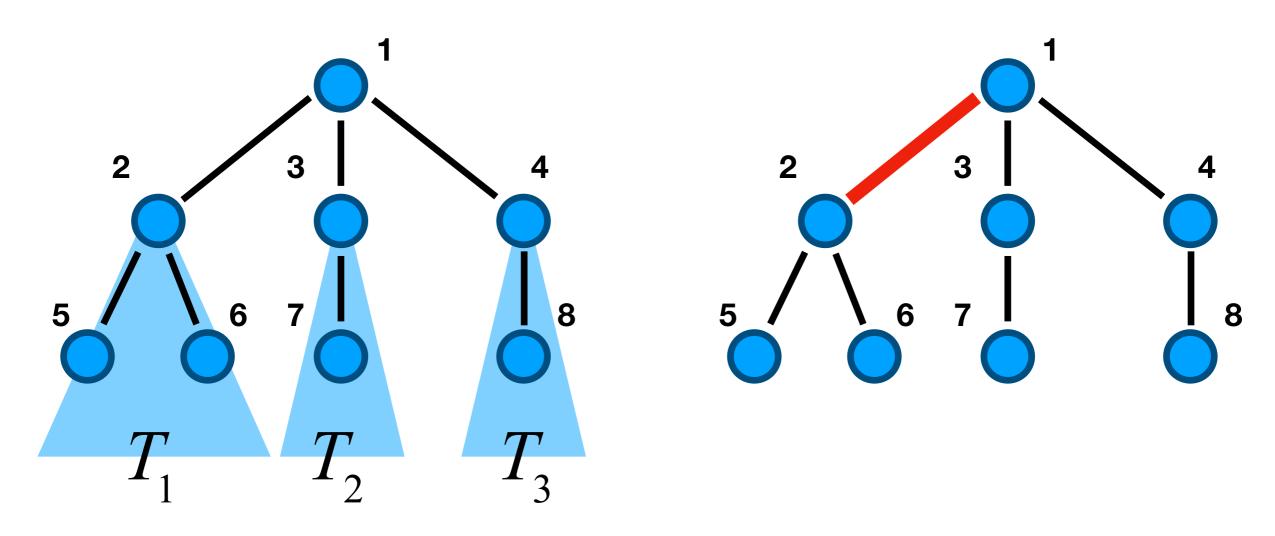
1. Don't take any edge incident to vertex 1.



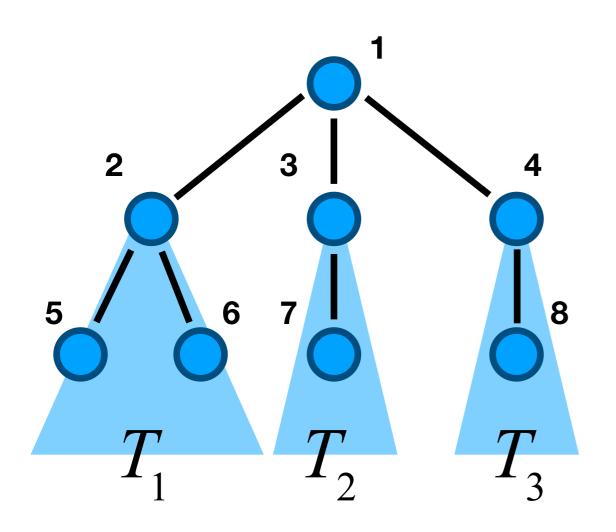
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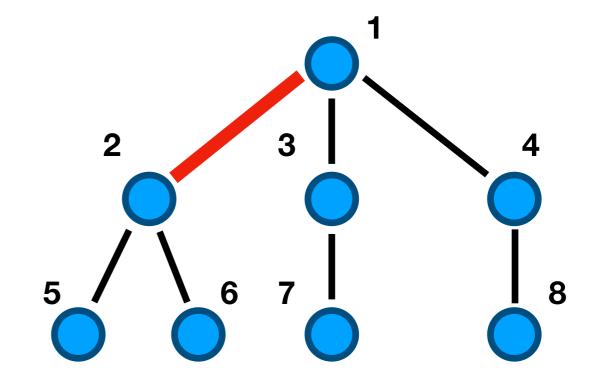


- 1. Don't take any edge incident to vertex 1.
- Maximum matching in each subtree can be found independently.



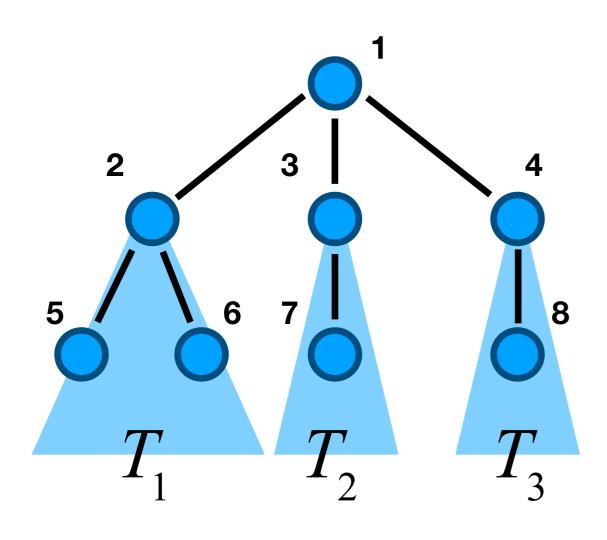
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- 2. Maximum matching in each subtree can be found independently.

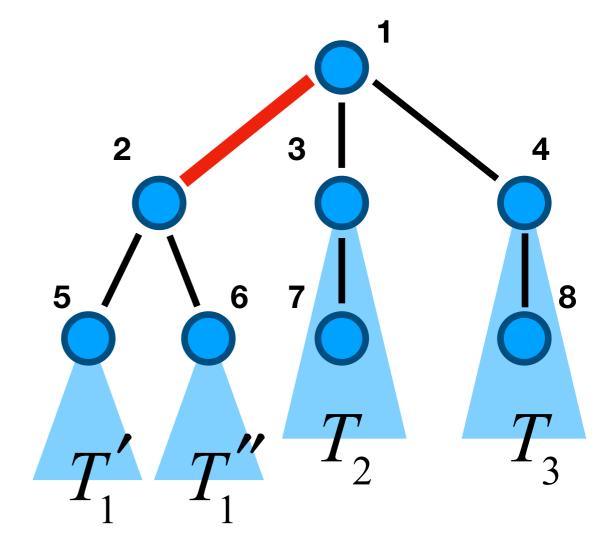




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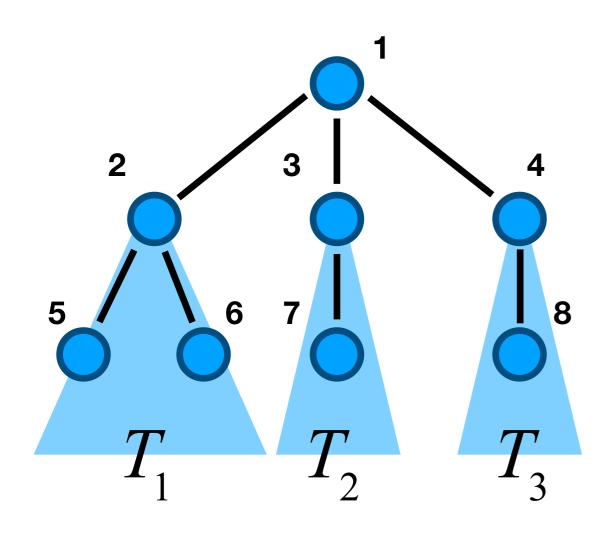
 Take an edge incident to a child of vertex 1.

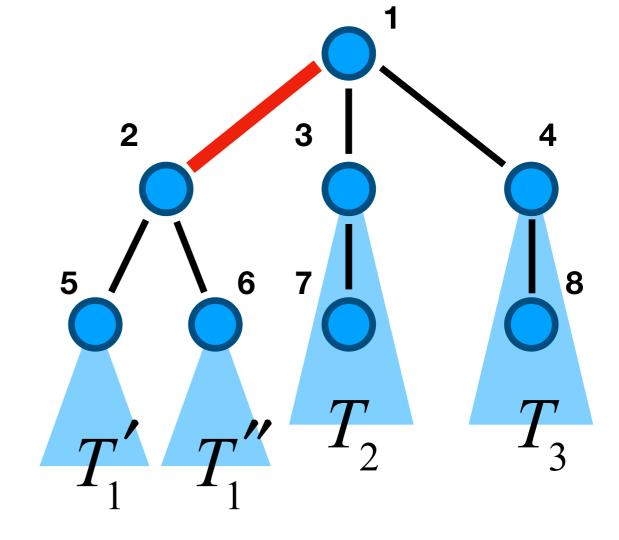




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- Take an edge incident to a child of vertex 1.
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Formulation as a DP

- Let c(v) denote the set of children of v in the tree
- Let M(v) denote the **size of the largest matching** in the subtree rooted at v

$$M(v) = \max \begin{cases} \sum_{w \in c(v)} M(w) \\ \max_{a \in c(v)} 1 + \sum_{w \in c(v) \setminus a} M(w) + \sum_{w' \in c(a)} M(w') \end{cases}$$

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```
\sum M(w)
                        \max_{a \in c(v)} 1 + \sum_{w \in c(v) \setminus a} M(w) + \sum_{w' \in c(a)} M(w')
matching(v) {
   S = 0;
   for all w in c(v) : S = S + M(w);
   M(v) = S;
   for all a in c(v):
      S = 1;
       for all w in c(v)\a:
          S = S + M(w);
       for all w' in c(a):
          S = S + M(w');
      M(v) = max(M(v),S);
```

}

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```

}

Can be $\mathcal{O}(n^2)$ if v has n-1 children.

```
\sum M(w)
M(v) = \max \left\{ \max_{a \in c(v)} 1 + \sum_{w \in c(v) \setminus a} M(w) + \sum_{w' \in c(a)} M(w') \right\}
matching(v) {
   S = 0;
   for all w in c(v) : S = S + M(w);
   M(v) = S; M'(v) = S;
   for all a in c(v):
       S = 1 + M'(v) - M(a);
       for all w' in c(a):
```

S = S + M(w');

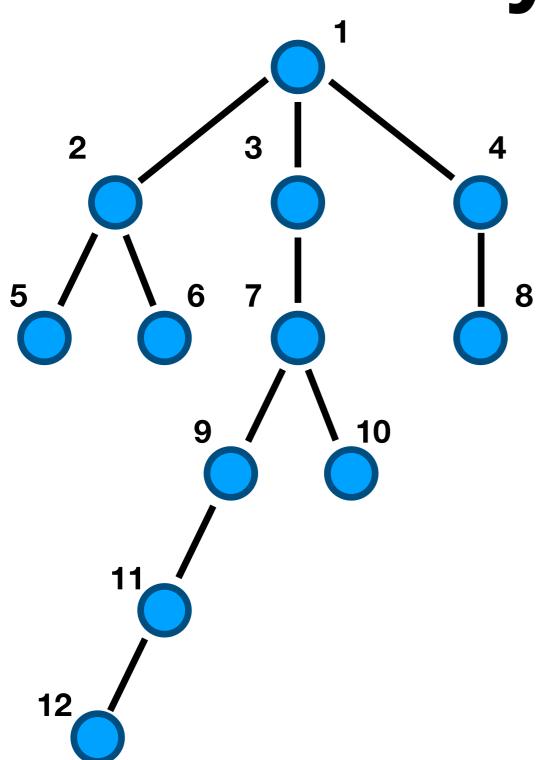
M(v) = max(M(v),S);

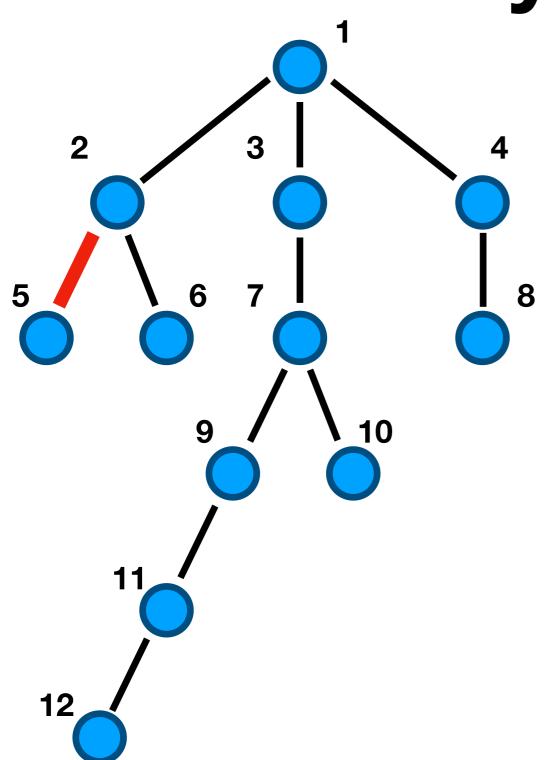
}

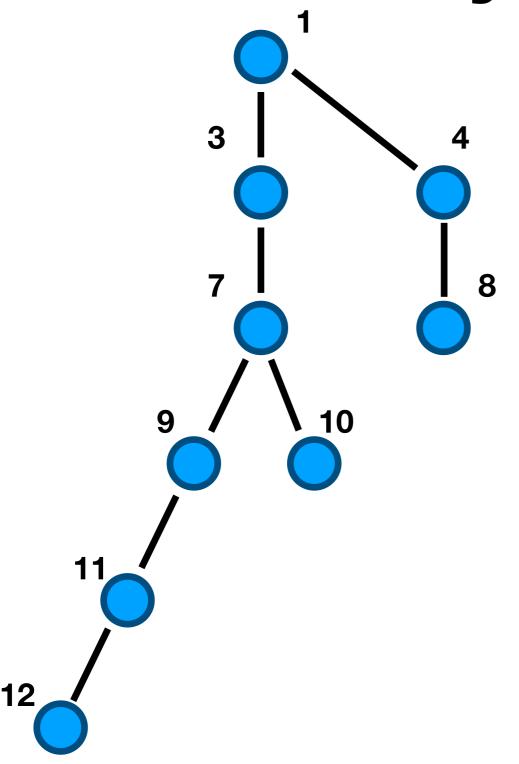
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\sum M(w)
                                               w \in c(v)
M(v) = \max
                          \max_{a \in c(v)} 1 + \sum_{x \in c(v)} M(x) + \sum_{x \in c(v)} M(x)
                                        w \in c(v) \setminus a
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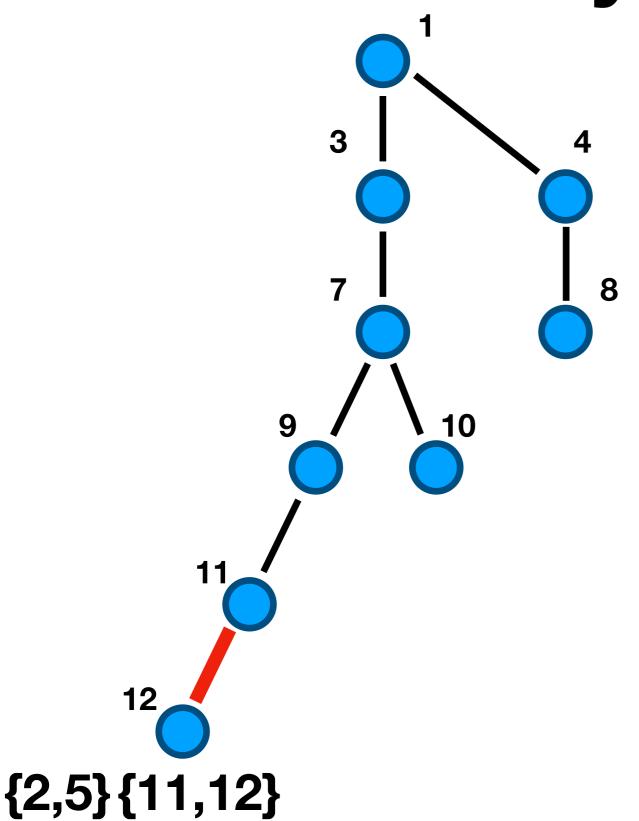
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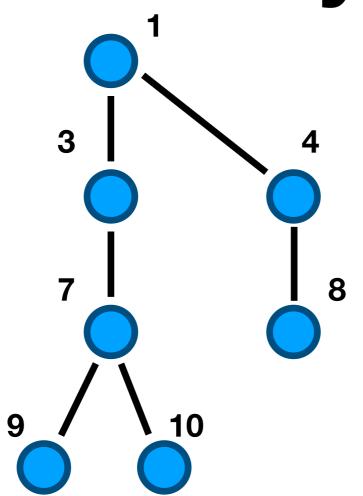
The running time is linear

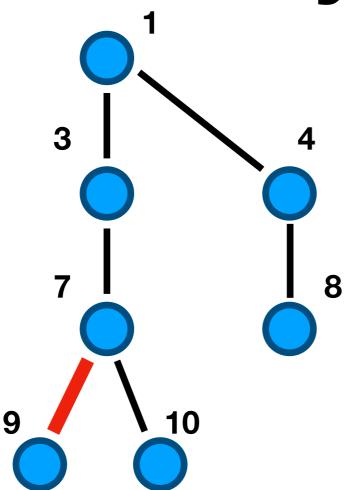


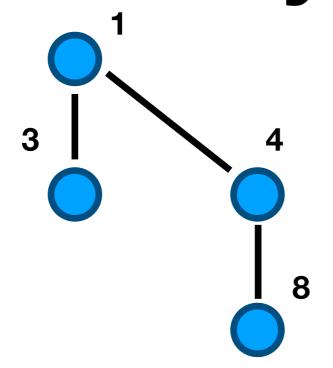


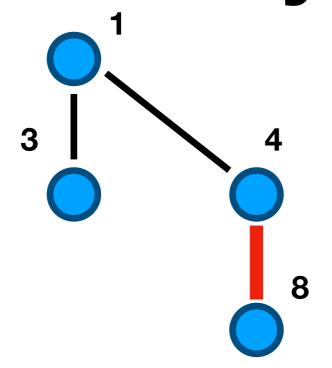




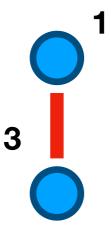


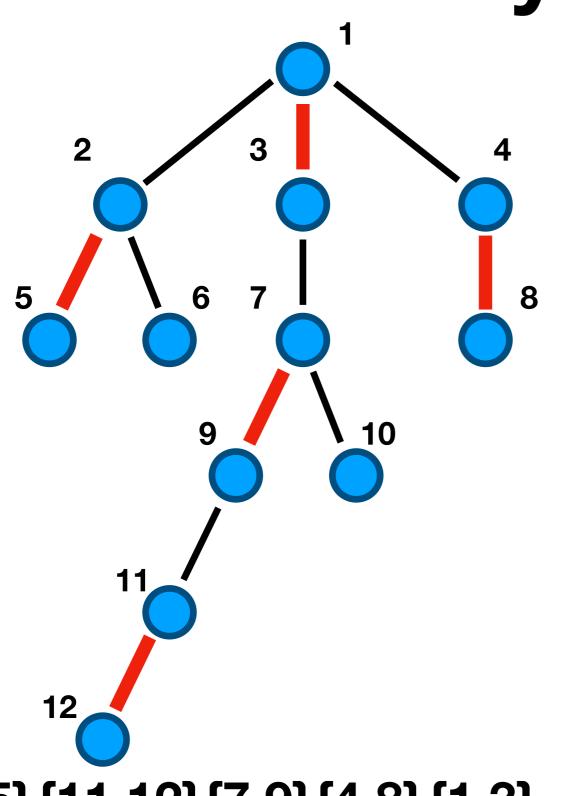








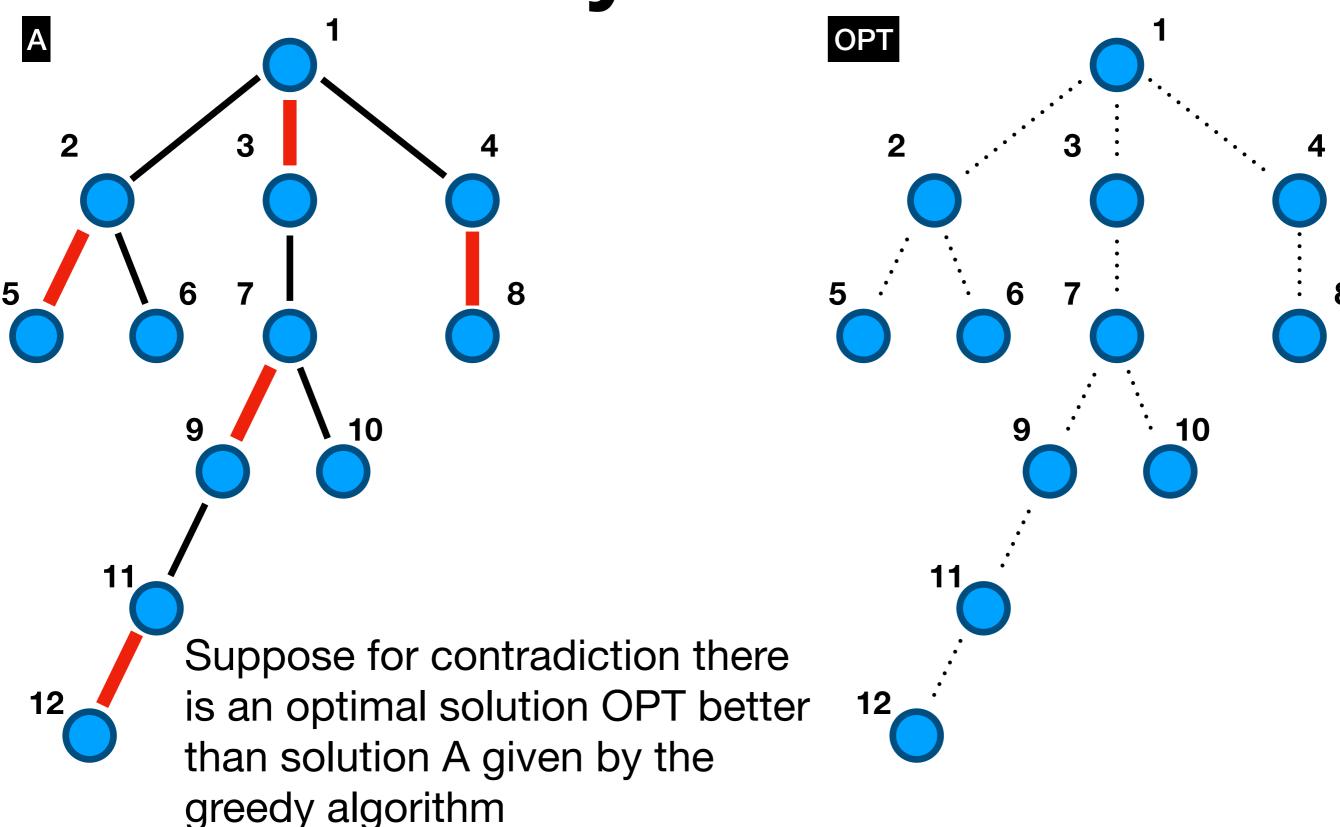


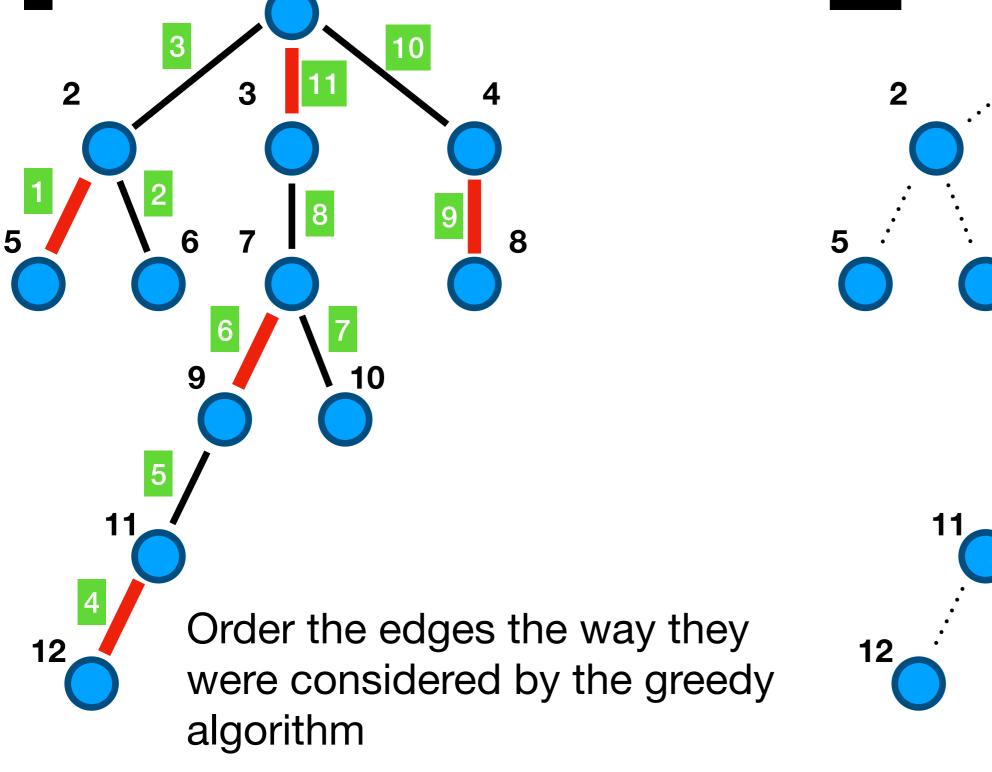


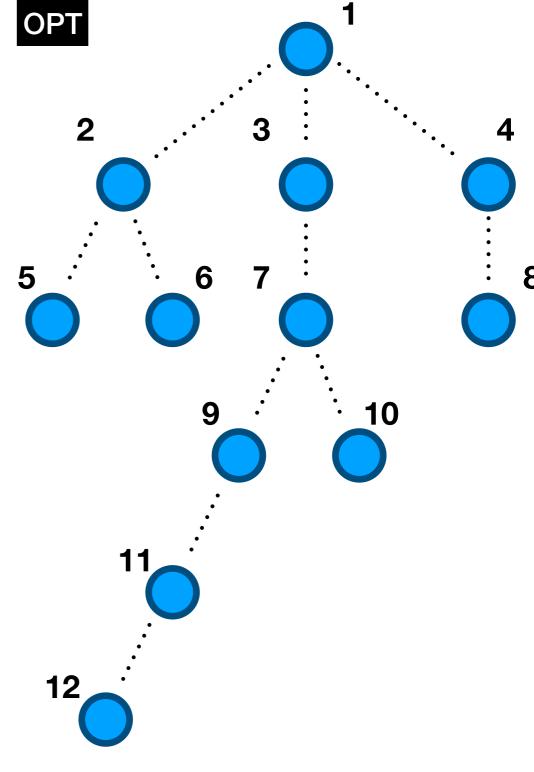
Repeat: Take an edge which contains a leaf and remove its endpoints and all edges incident to the parent.

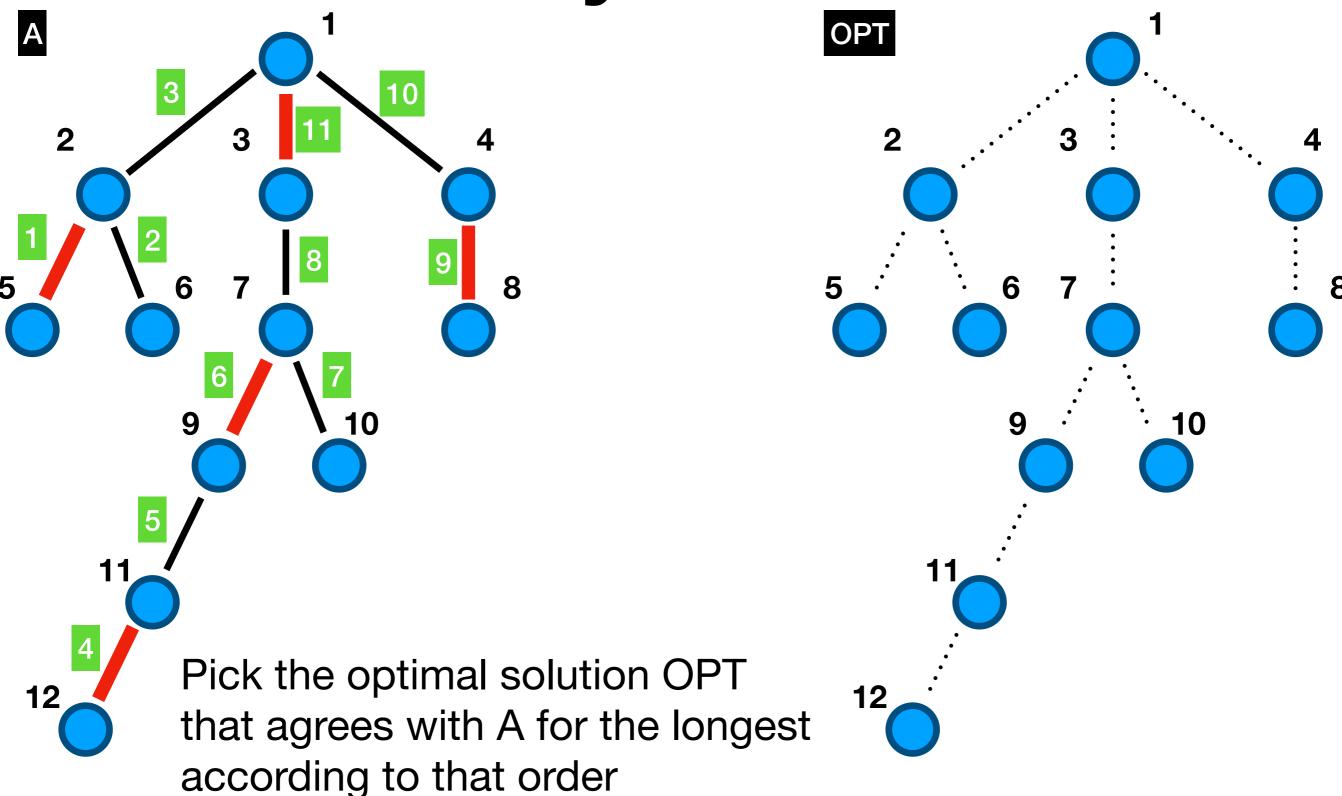
Correctness can be proven by using the exchange argument (see slides about Greedy Algorithms)

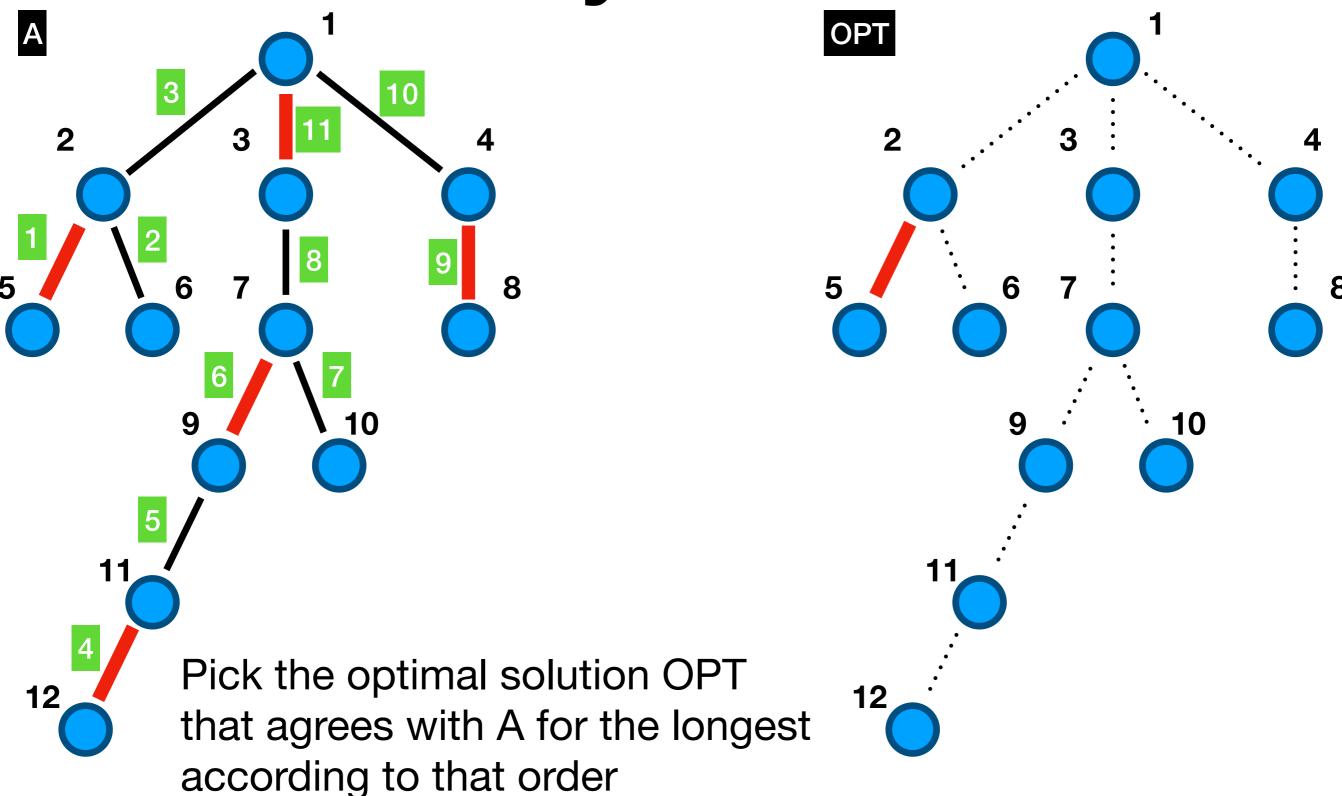
{2,5}{11,12}{7,9}{4,8}{1,3}

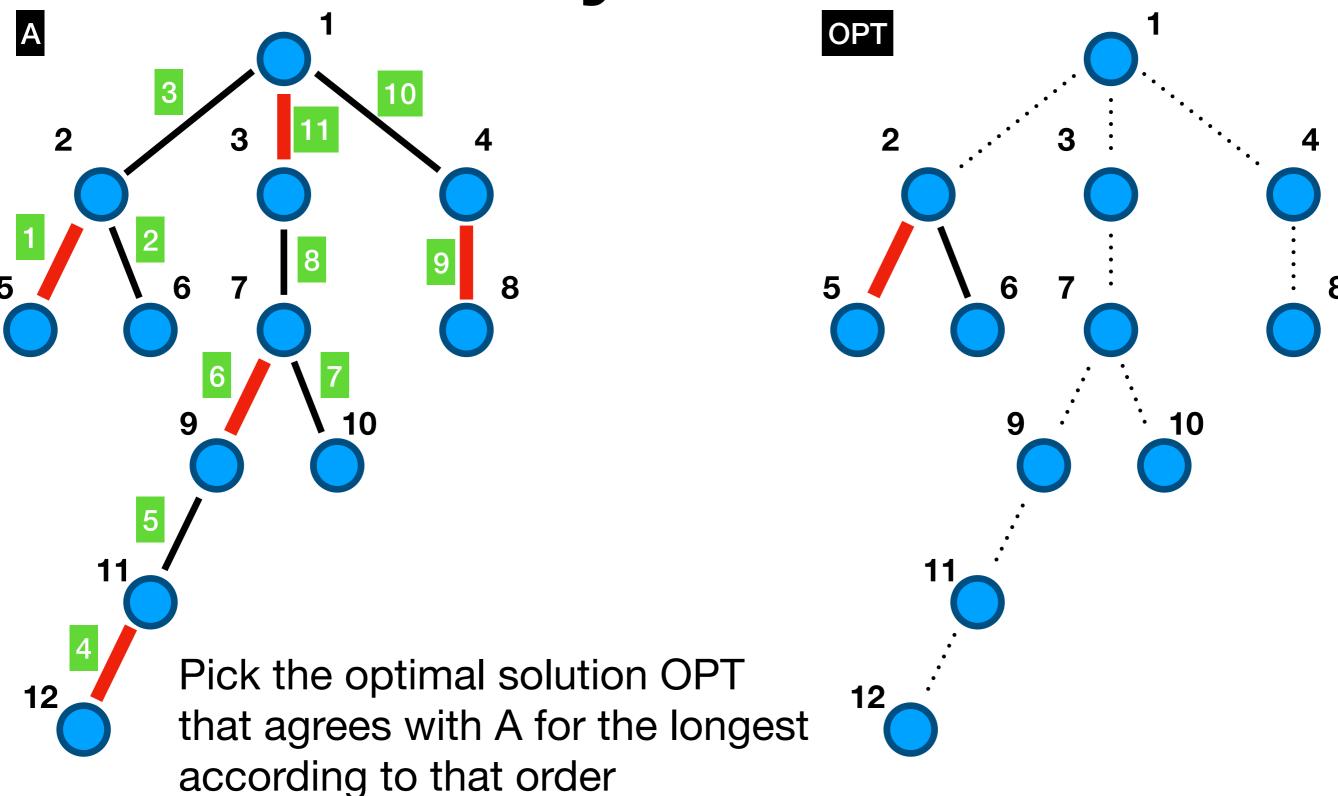


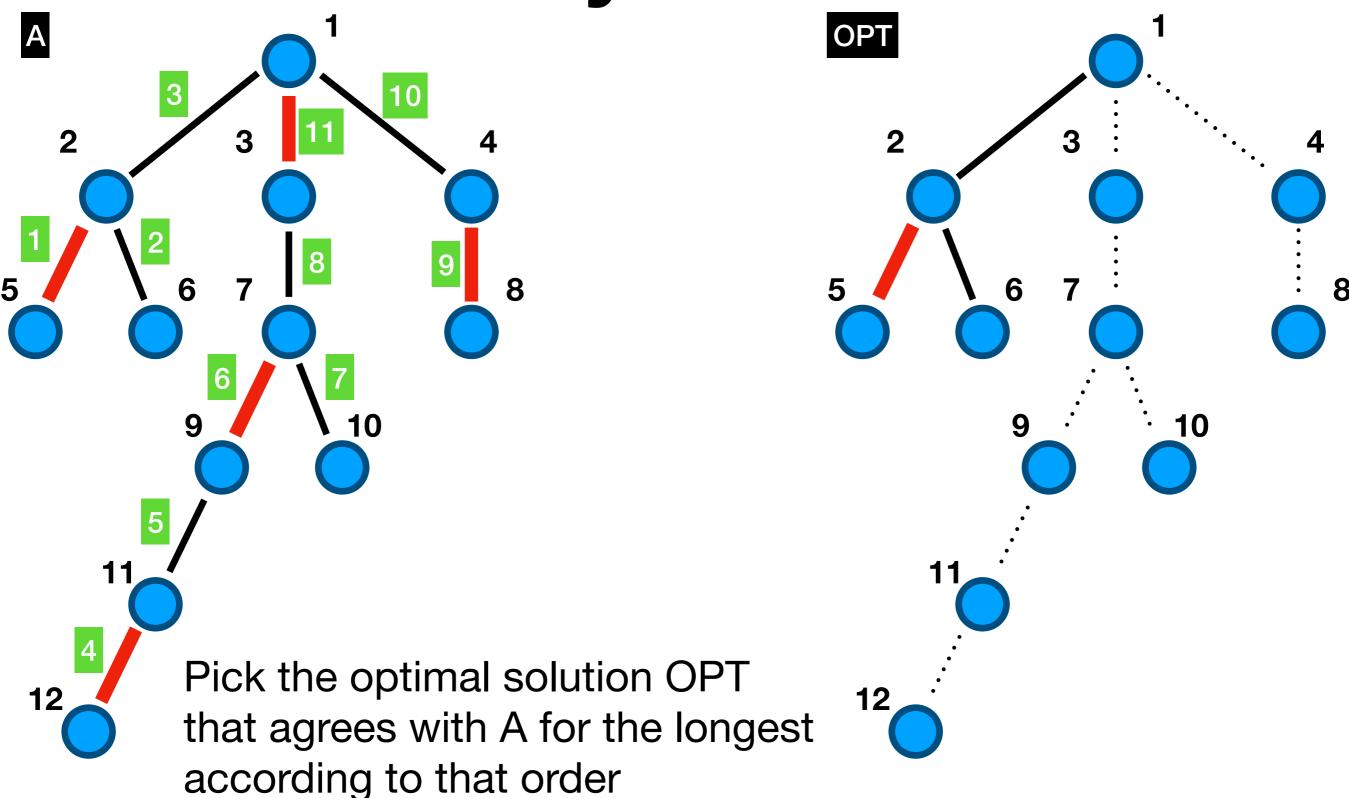


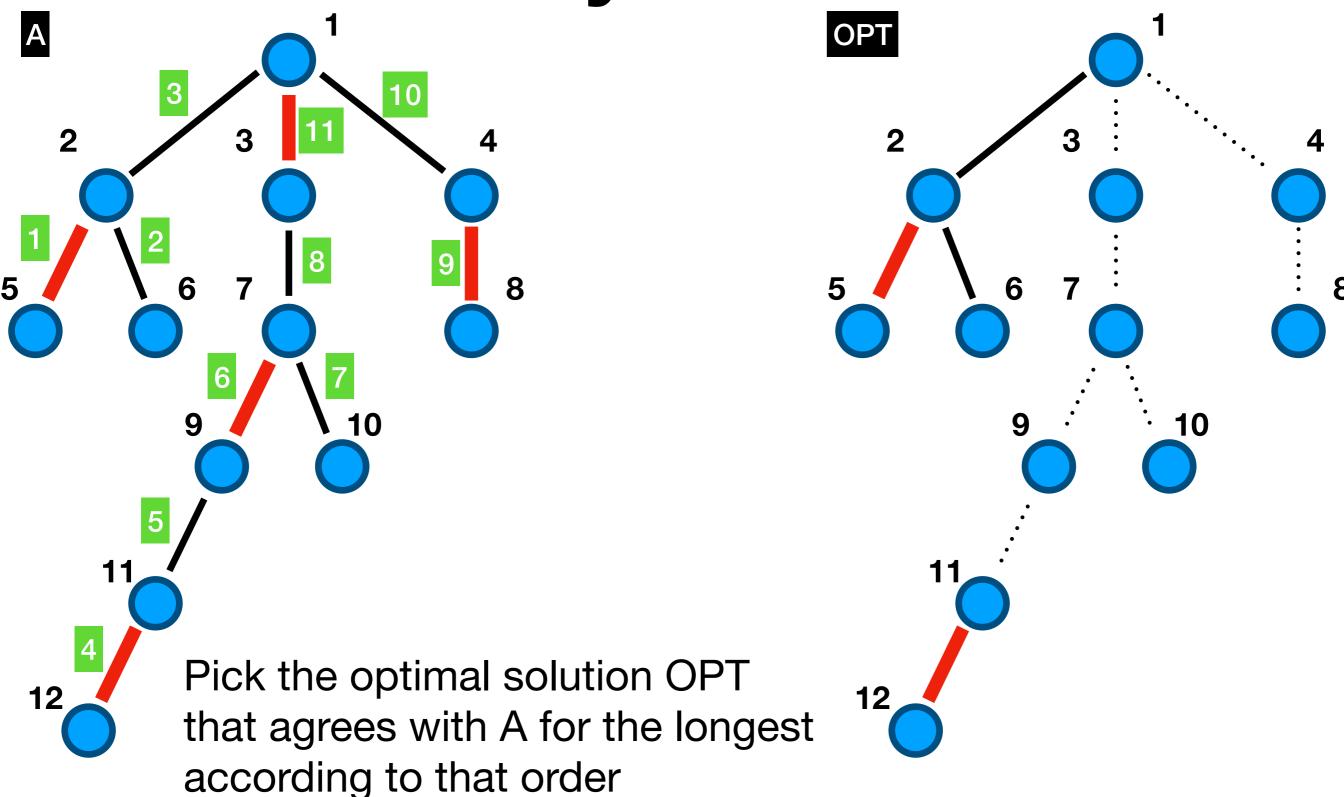


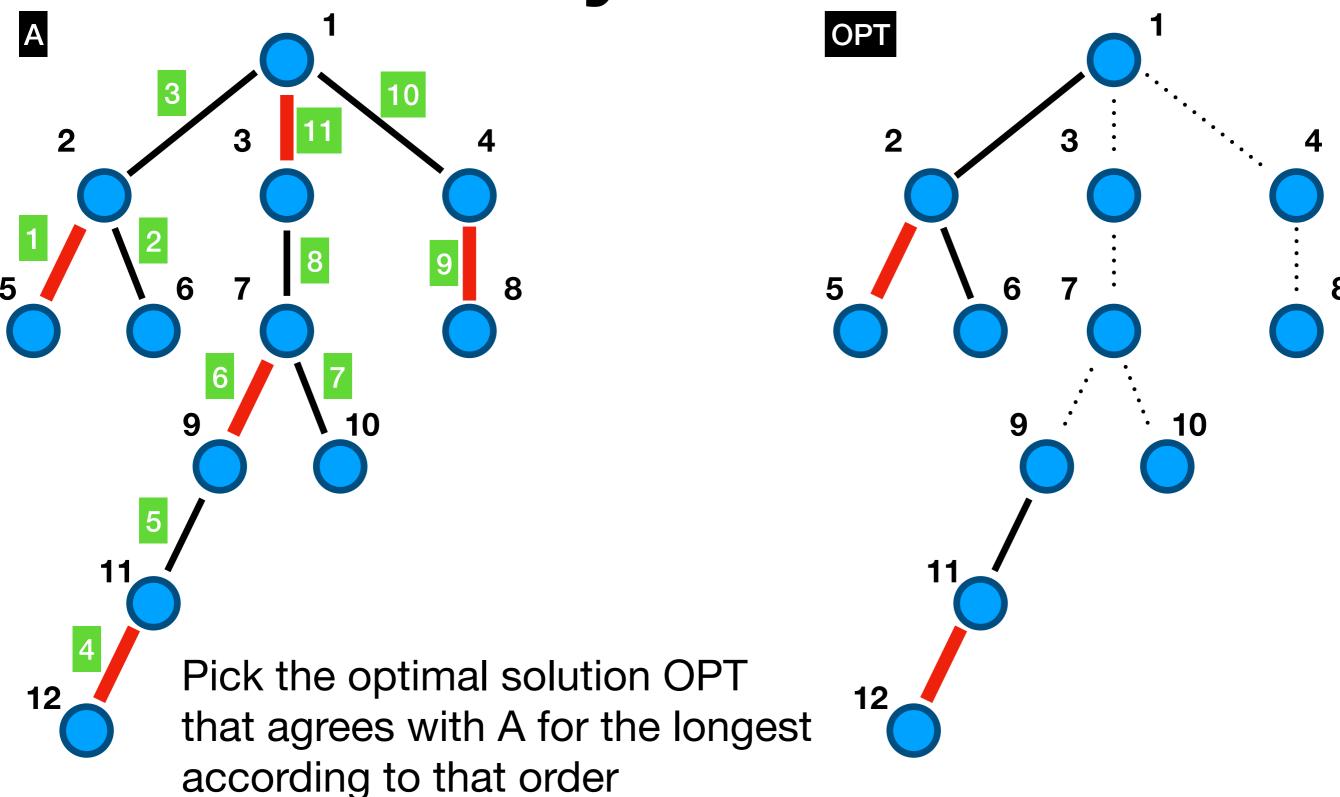




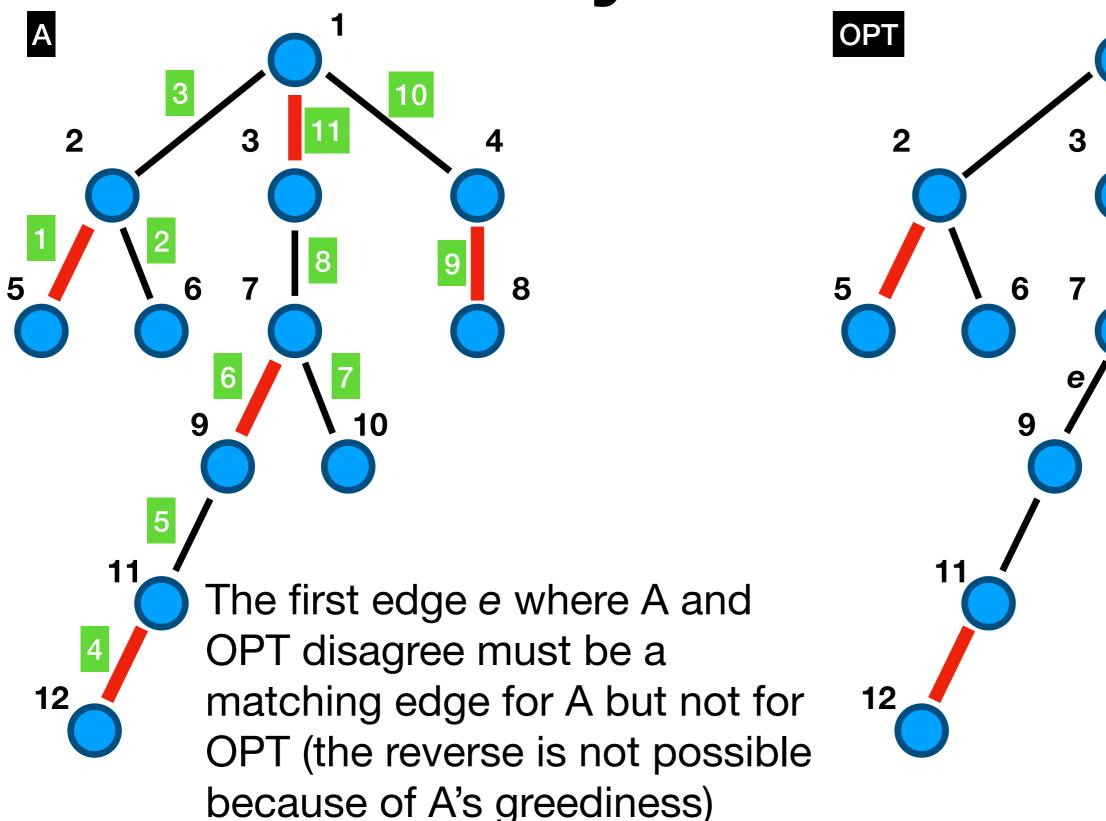


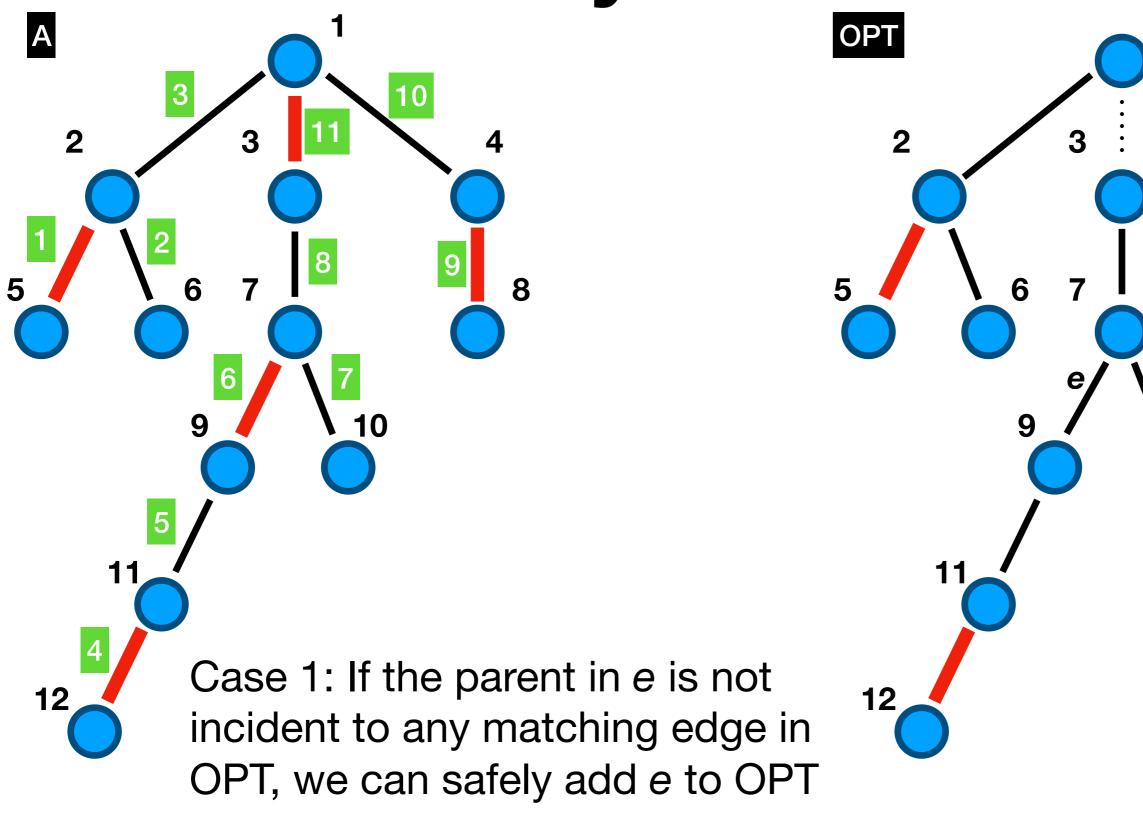


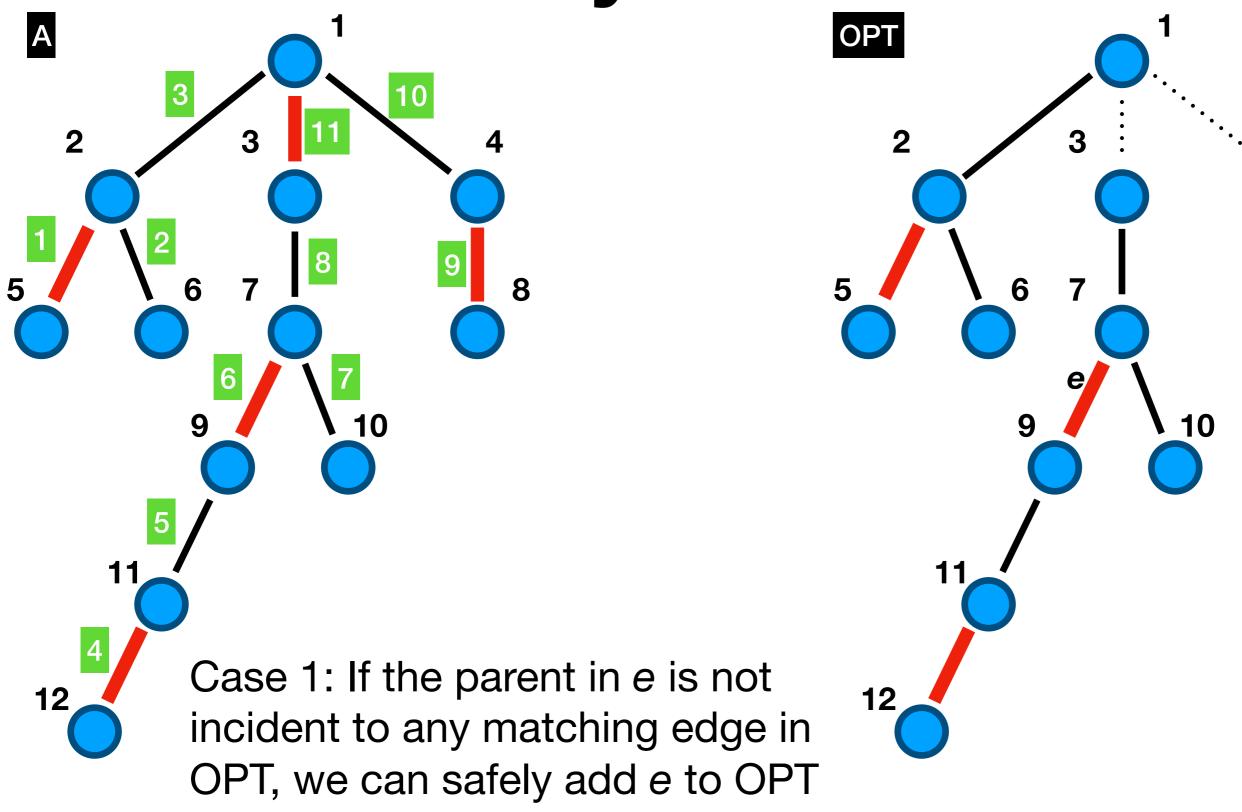


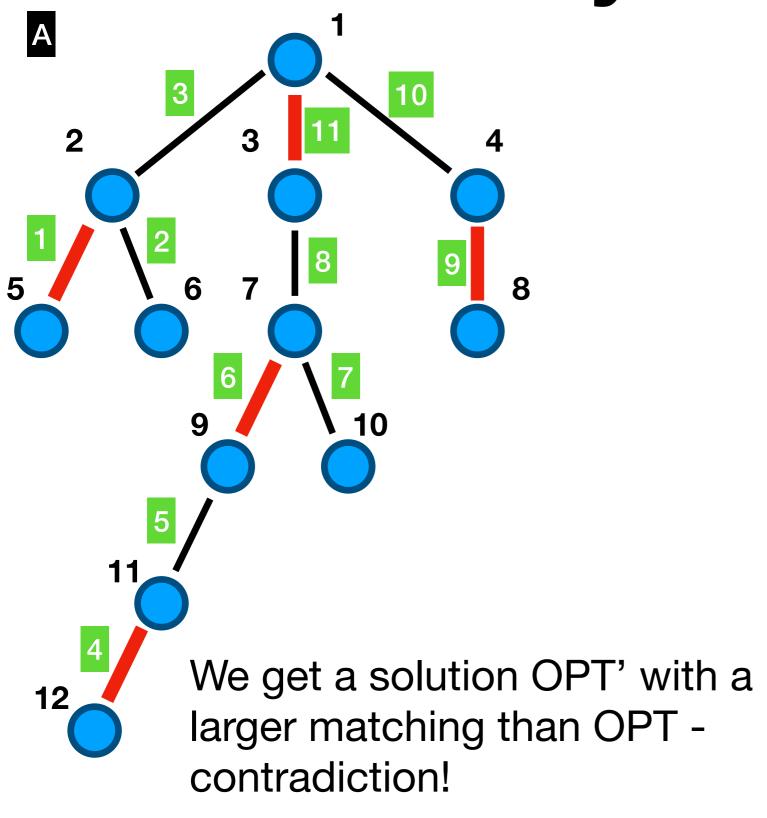


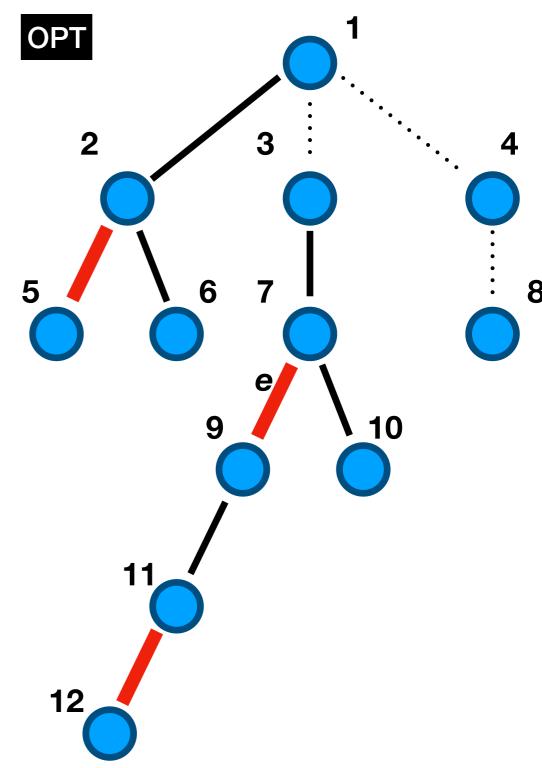
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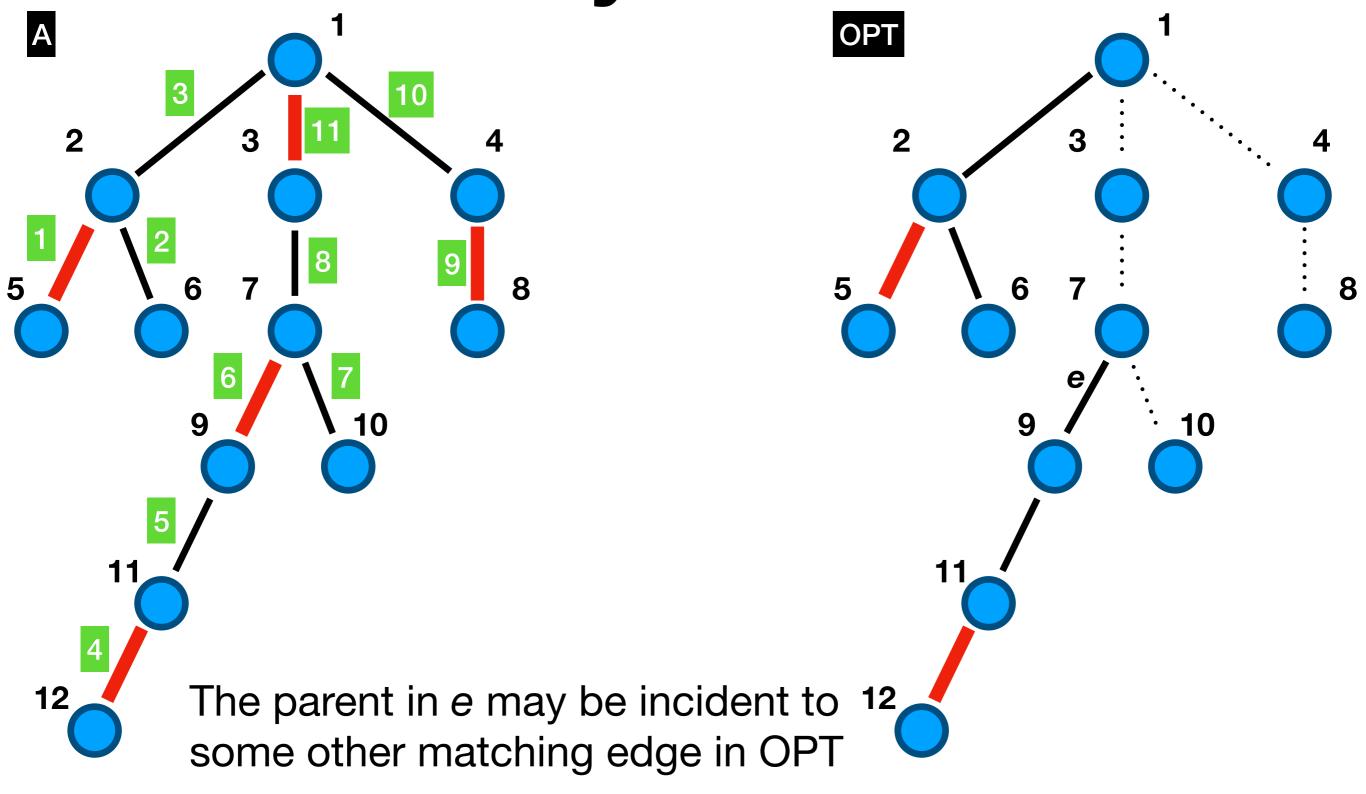


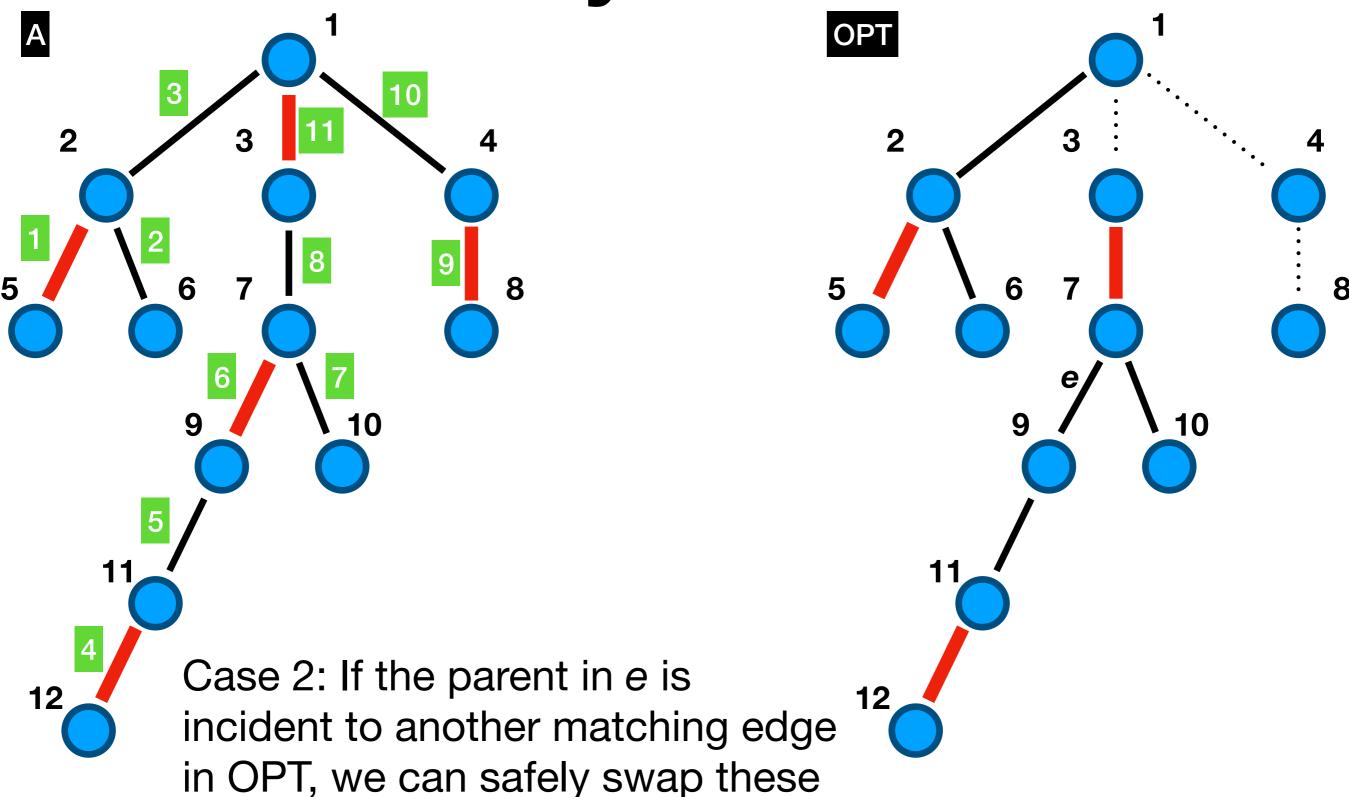


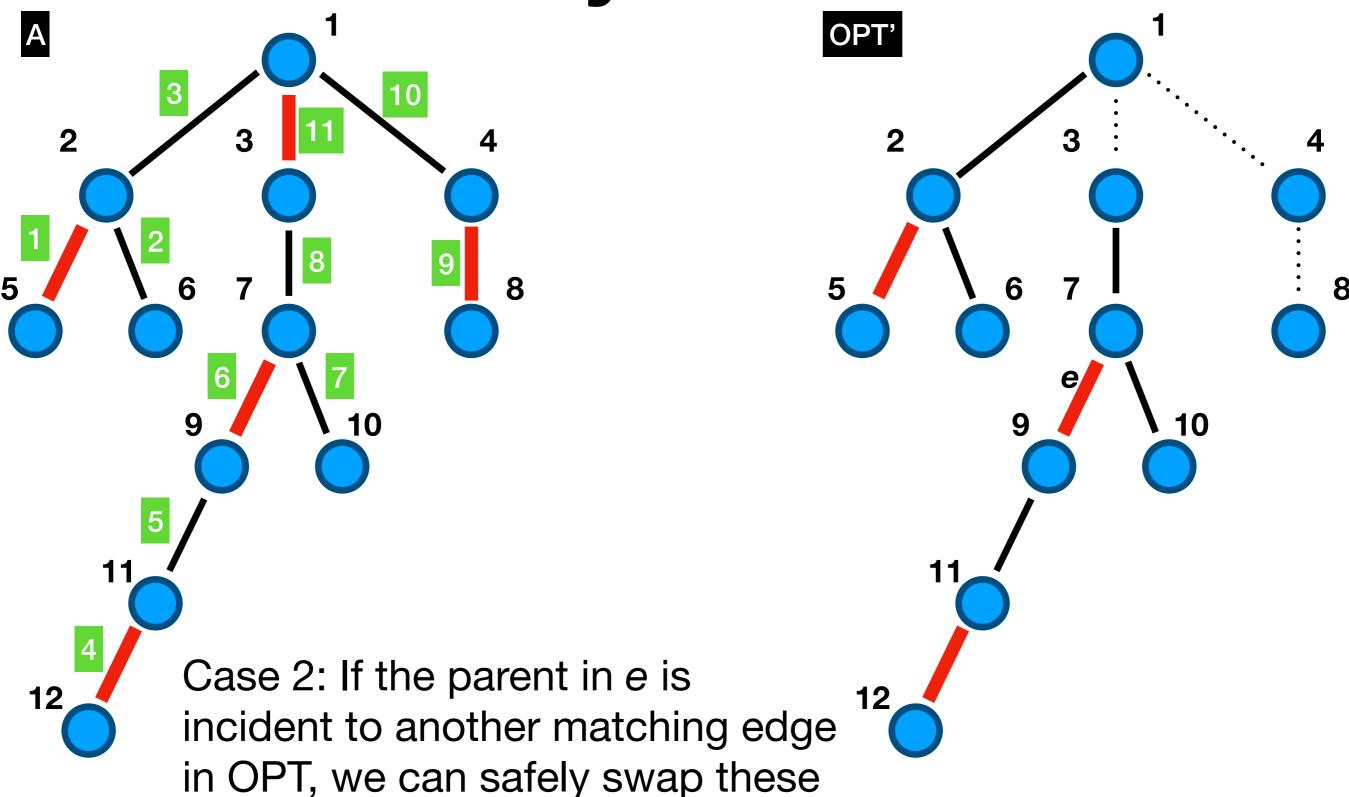


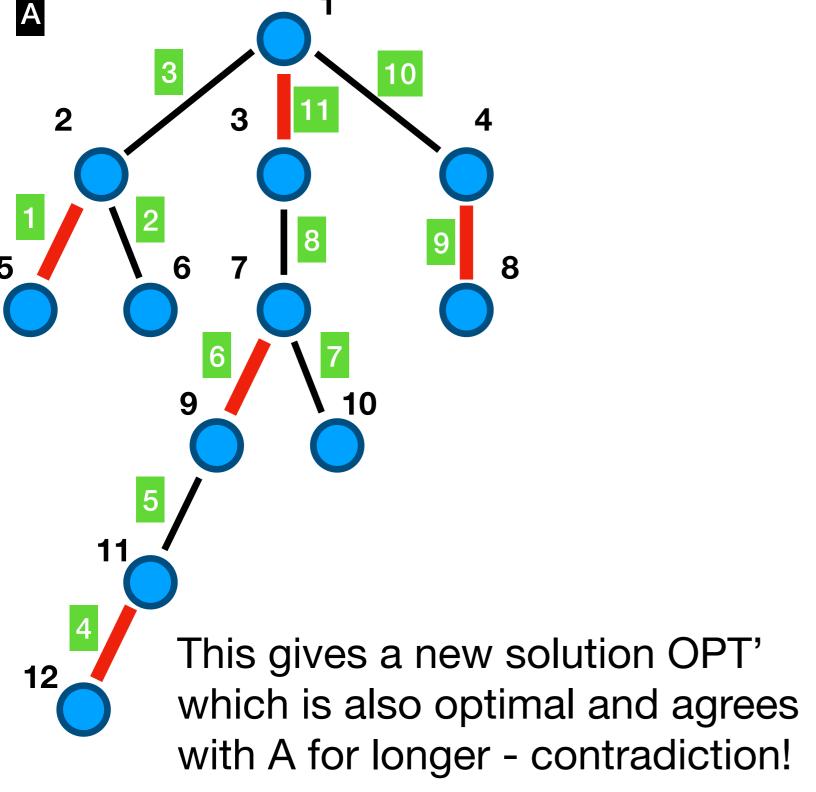


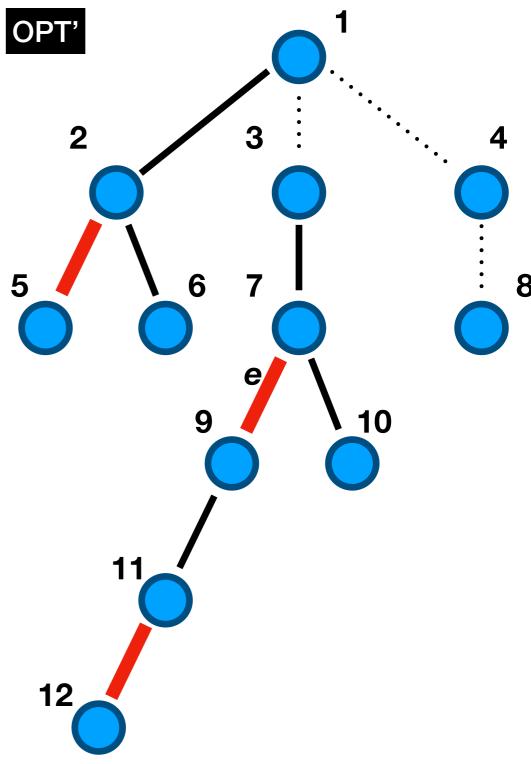












Exercise 2

Exercise – Consecutive Constructions

The basic roads in Algoland are already built, but the road network still needs to be extended.

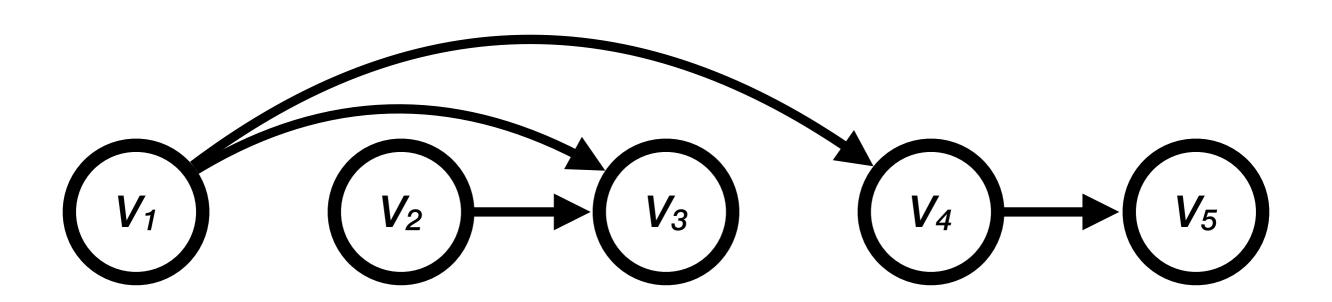
The roads to be constructed now are in a more difficult terrain, so, if possible, you want to build them in consecutive intervals. A single construction team with all the heavy equipment can start building the next road in the same city just after finishing the previous one.

The rules are as follows:

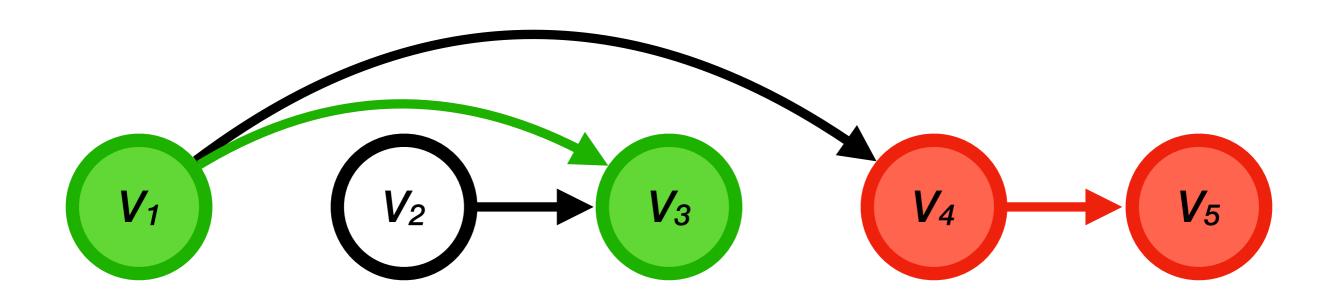
- You can use as many teams as you need for operating the construction.
- Each team will start in some city *u*, and then build a road to a city with larger number *v*. After finishing the construction the team will be in *v*. Then it might build another road to a city with even larger number, and so on.
- To avoid disruptions each city can be visited at most once by at most one team. Starting or finishing in a city counts as a visit.
- You want to build as many roads as possible.

Goal: Given a directed acyclic graph *G*, find the maximum number of edges that can be packed in vertex-disjoint paths in *G*.

Example

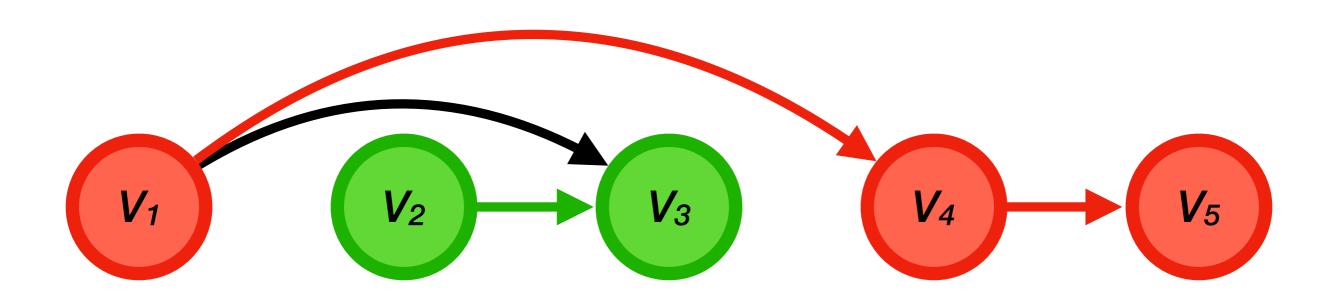


Greedy Strategy



Extend as much as possible

Optimal Solution



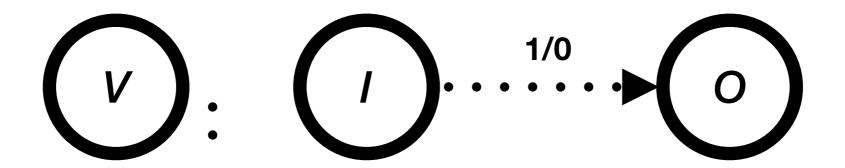
Three edges

Modelling with Flow

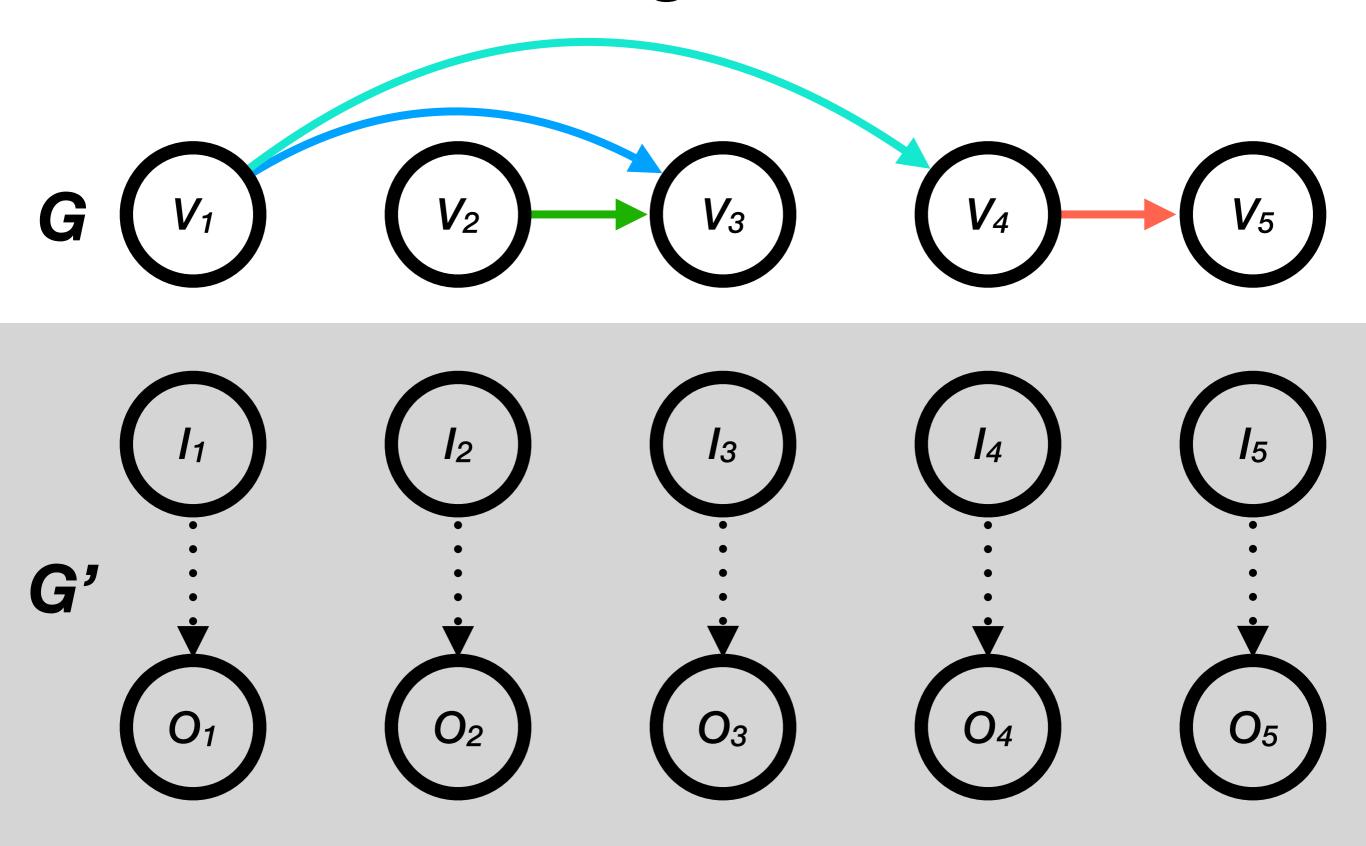
Model each team as a unit flow

Each edge is of capacity 1 and cost -1

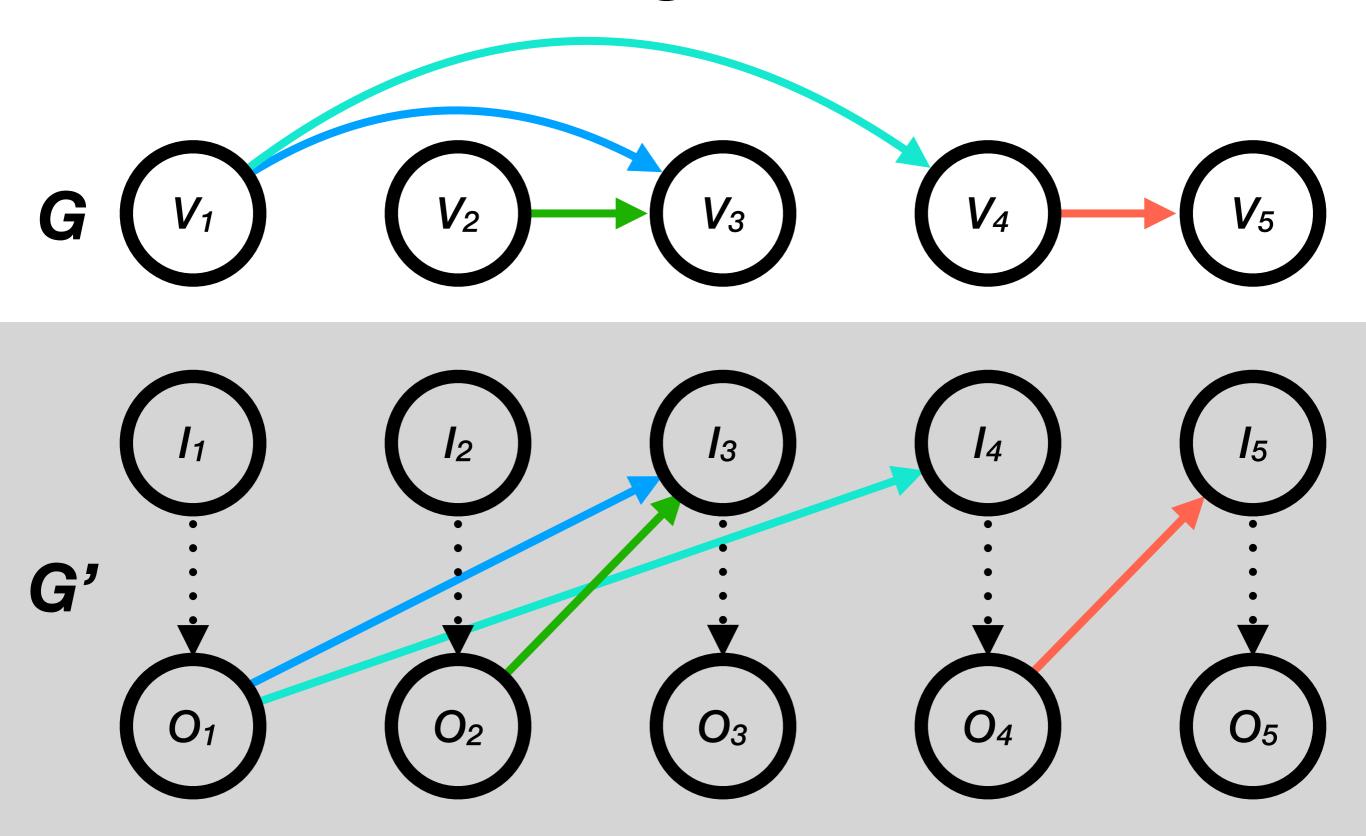
Vertex-disjoint paths: vertices are of capacity 1



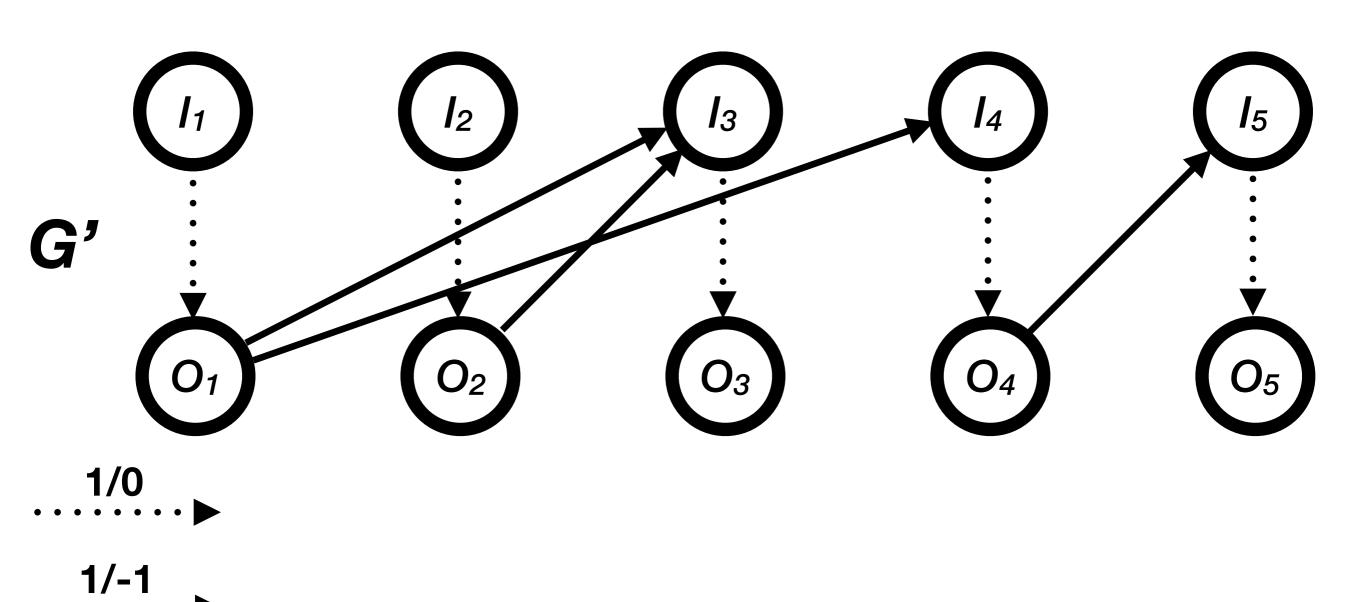
Doubling Vertices



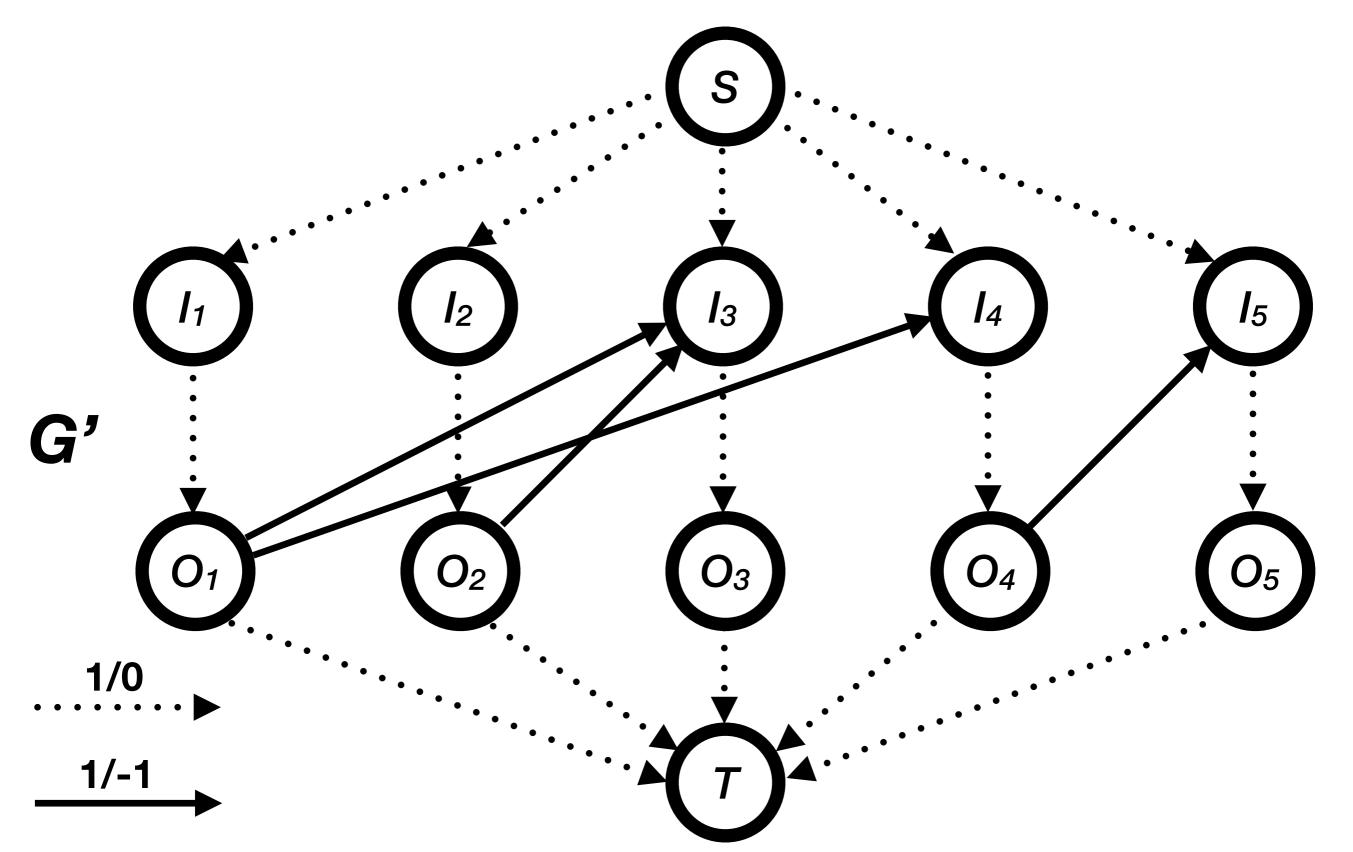
Doubling Vertices



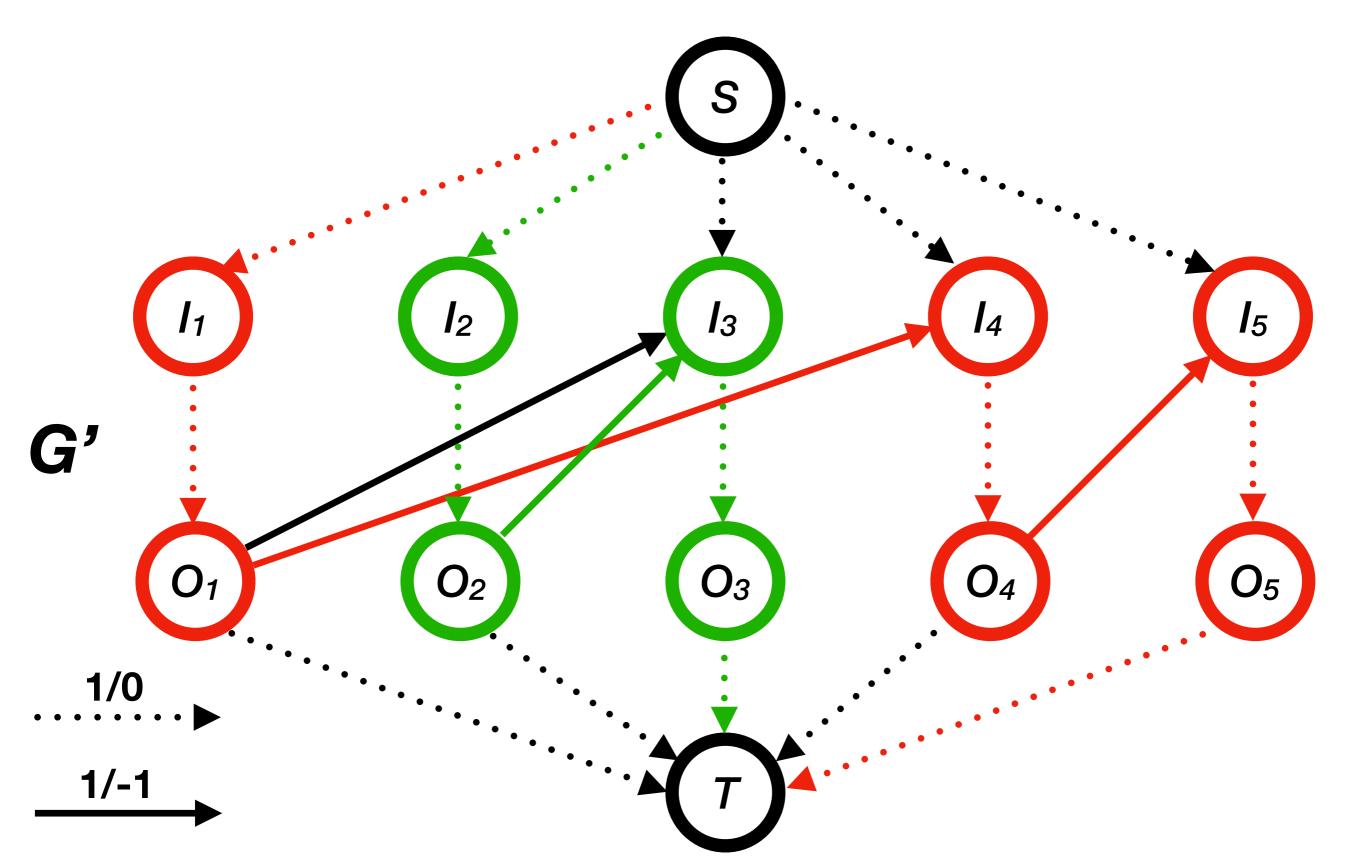
Adding S, T, Capacity and Cost



Adding S, T, Capacity and Cost



Flow Network



Do we need min-cost max-flow?

Do we need to compute a min-cost flow?

Only solid edges contribute to the cost.

Each vertex is incident to at most one solid edge.

Matching

Do we need min-cost max-flow?

Do we need to compute a min-cost flow?

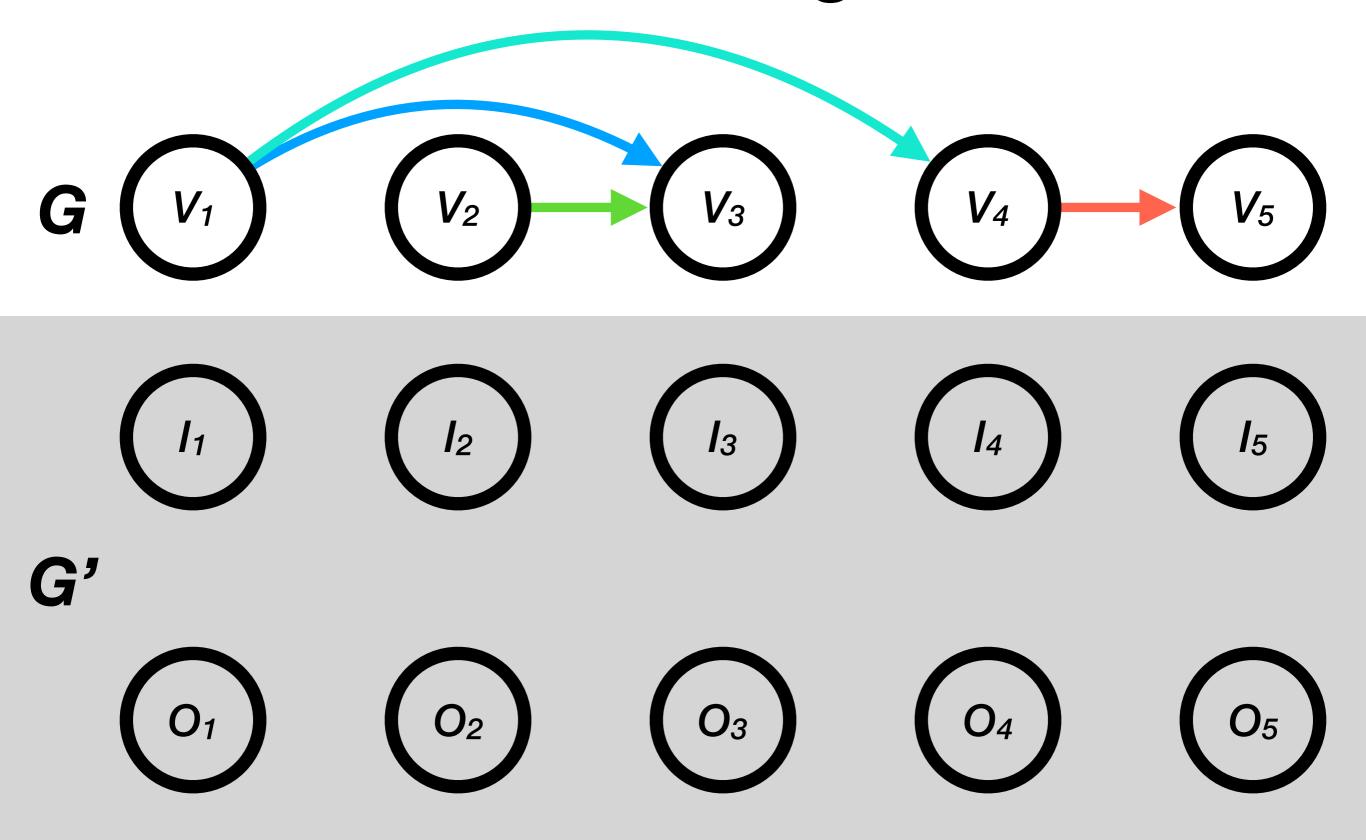
Only solid edges contribute to the cost.

Each vertex is incident to at most one solid edge.

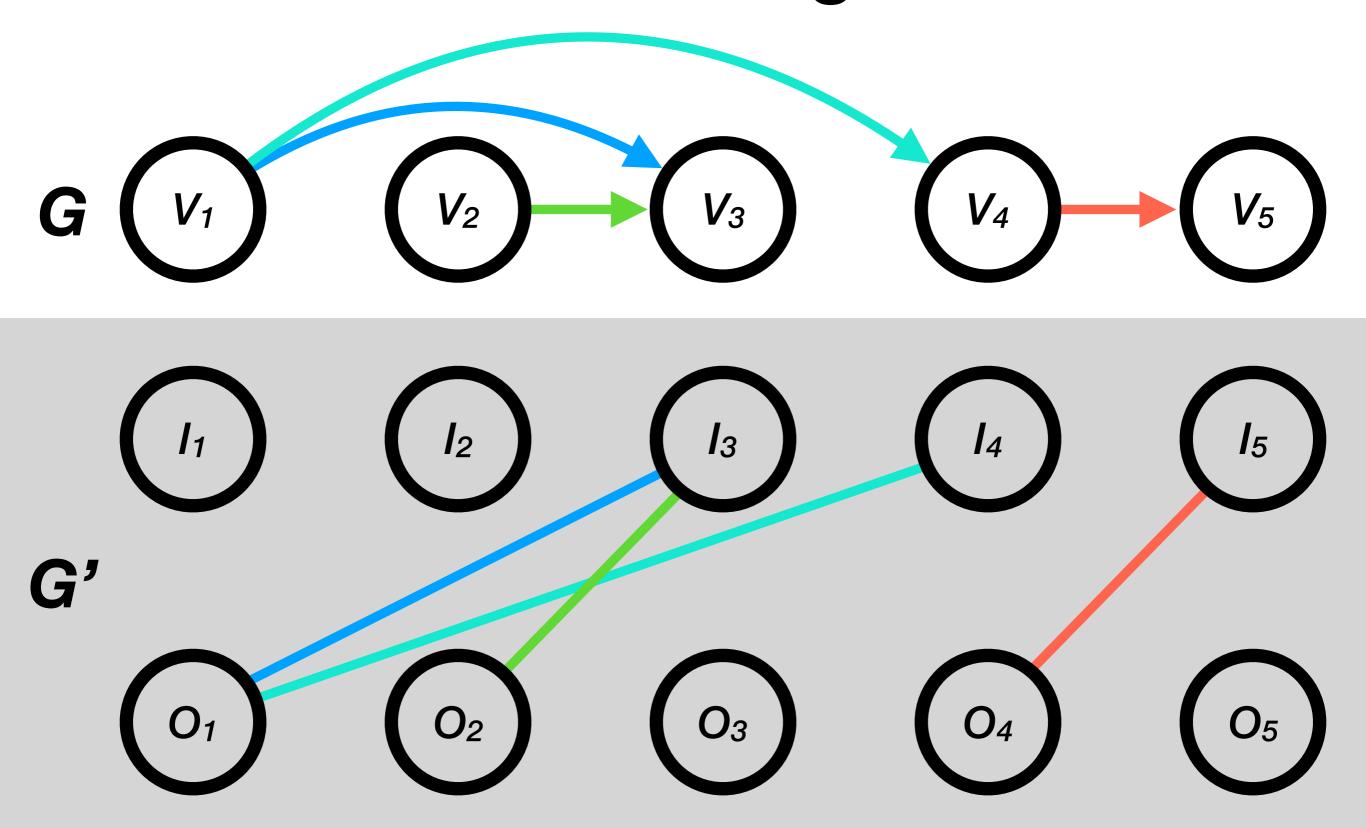
Lemma

There is a 1-1 correspondence between solutions in G with k edges and matchings in G of size k.

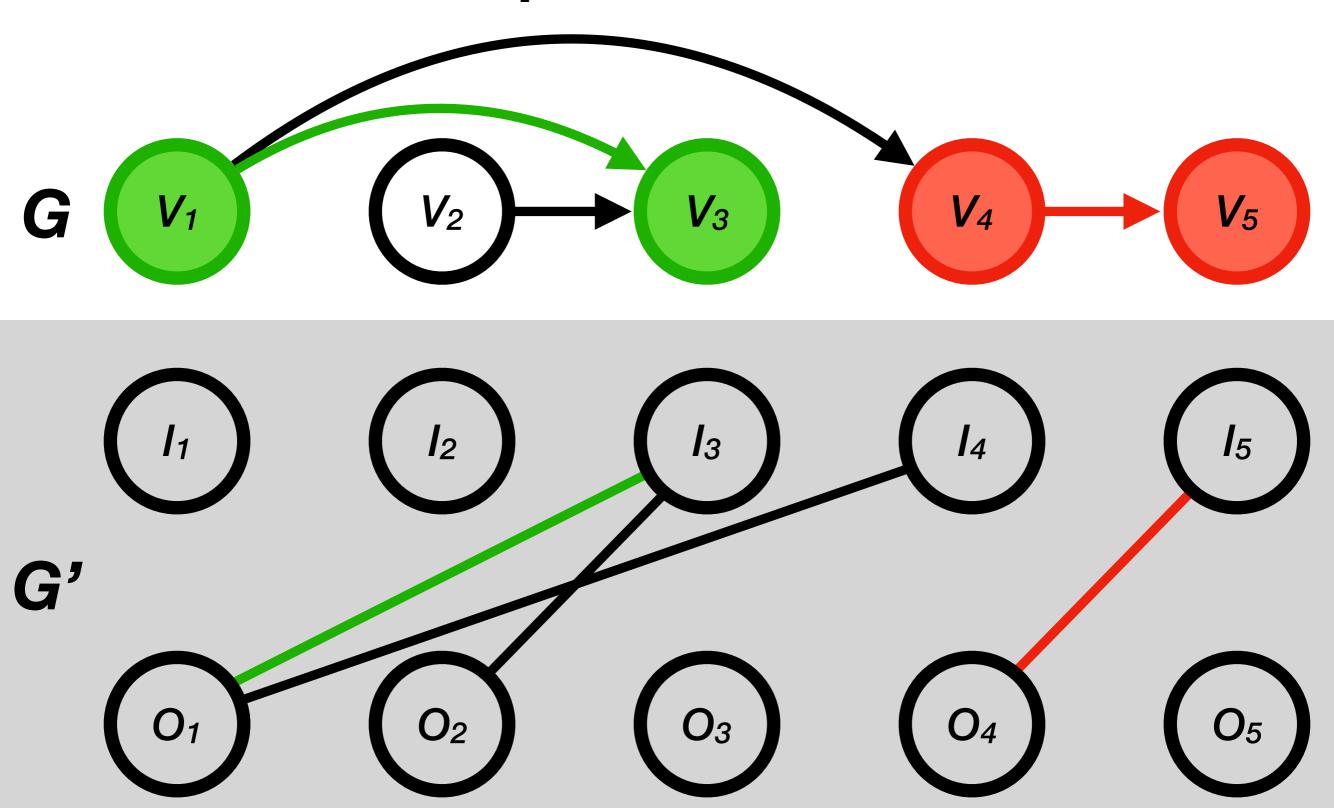
Modeling



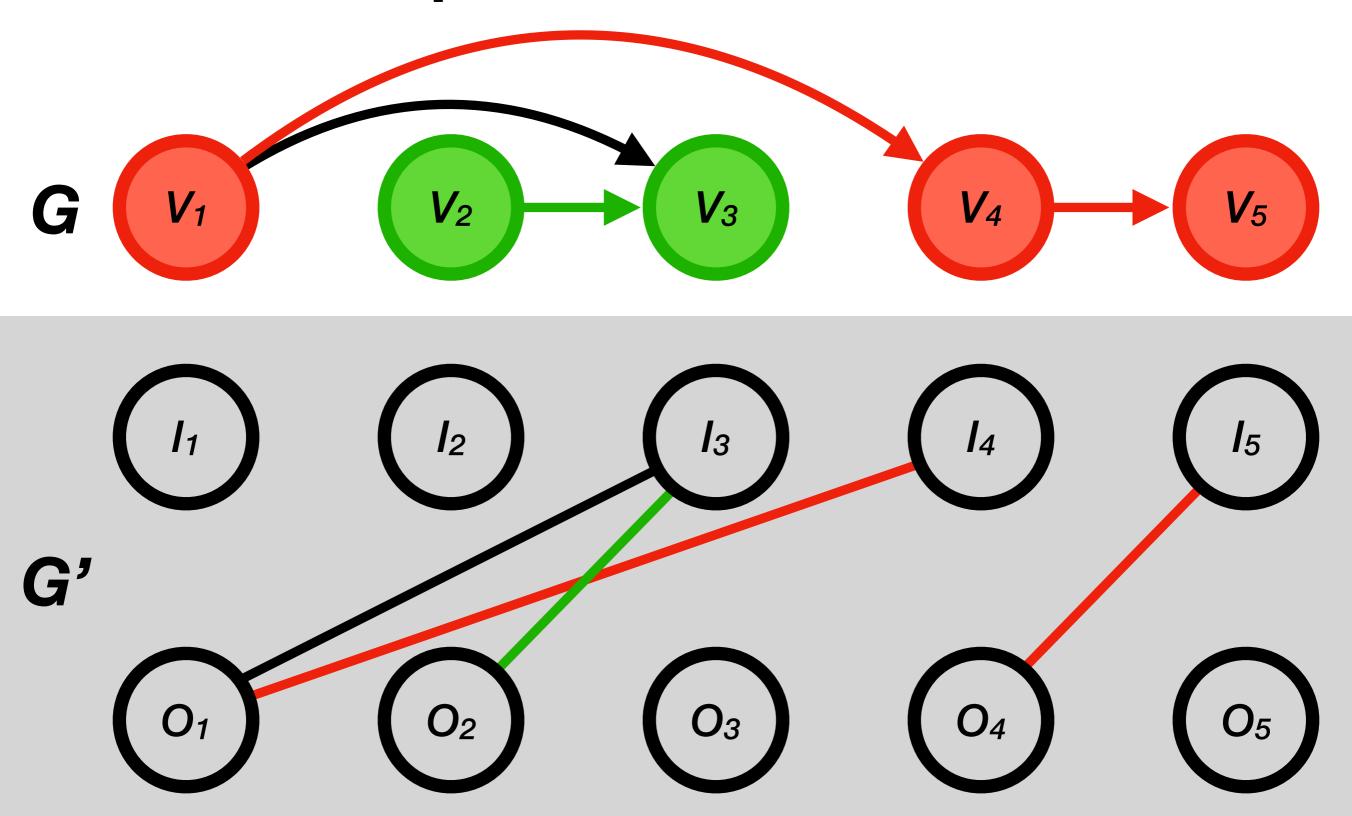
Modeling



Sub-optimal Solution



Optimal Solution



Exercise 3

Exercise – *Missing Roads*

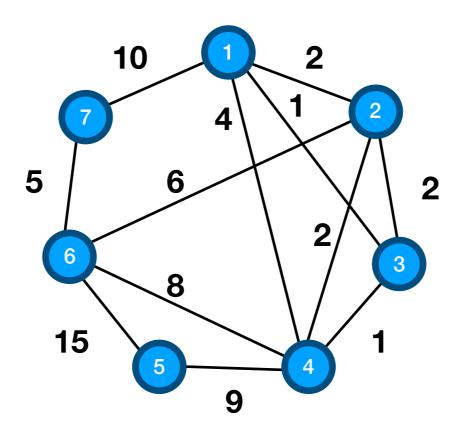
A lot of roads were built in Algoland, but some of them are still missing. Since many accidents happened last year at construction sites, the government decided to decrease the risk of injury by using a separate construction team for each road. However, as the road-building equipment makes a lot of noise when it is started, no two construction teams are allowed to start building from the same city. There is no problem though in two construction teams ending the road in the same city. A team assigned for one road can *choose* from which city will it start the construction.

There is not a lot of time and all roads must be built simultaneously, but you need to pay attention to the budget. Thus, given a construction cost for each potential road, estimate the minimum possible cost of building at least k of them, without starting a construction of more than one road at each city. Each given possible road has a cost between 1 and 100.

Goal: Given an undirected graph G and an integer k find a set of vertices $\{v_1,...,v_k\}$ and edges $\{e_1,...,e_k\}$ s.t.

- vertex *v_i* is incident to *e_i*
- the sum of edge costs is the smallest possible

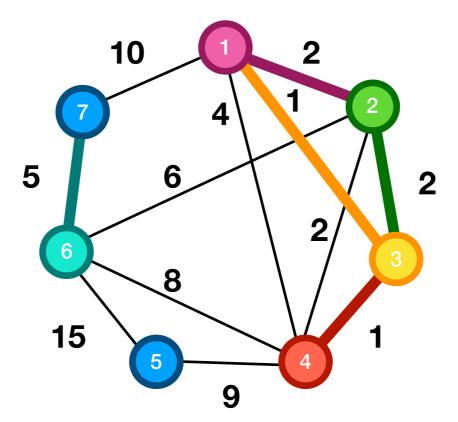
Example



Goal: Given an undirected graph G and an integer k find a set of vertices $\{v_1, ..., v_k\}$ and edges $\{e_1, ..., e_k\}$ s.t.

- vertex *v_i* is incident to *e_i*
- the sum of edge costs is the smallest possible

k=5

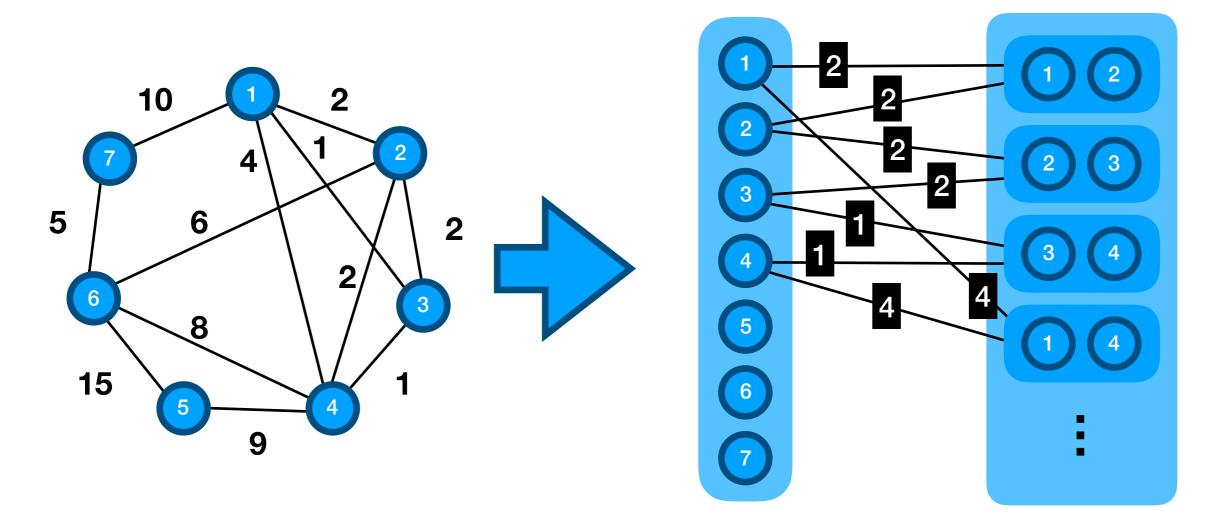


Goal: Given an undirected graph G and an integer k find a set of vertices $\{v_1, \ldots, v_k\}$ and edges $\{e_1, \ldots, e_k\}$ s.t.

- vertex *v_i* is incident to *e_i*
- the sum of edge costs is the smallest possible

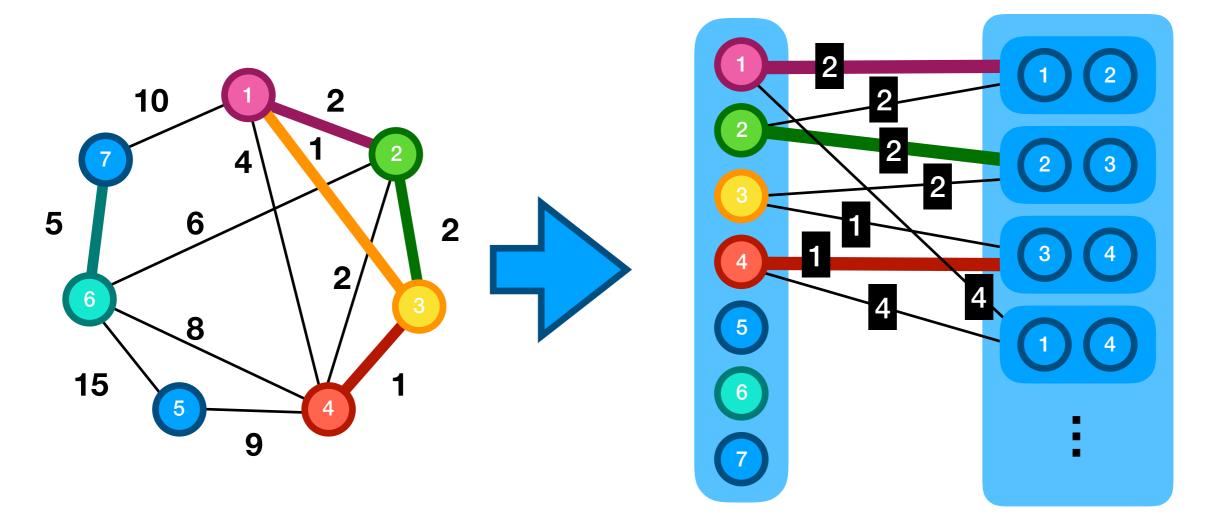
Create an **auxiliary bipartite** graph B:

- One side contains vertices of G
- The other side contains edges (as vertices)
- Connect a vertex v to an edge e if they are connected in G



Create an **auxiliary bipartite** graph B:

- One side contains vertices of G
- The other side contains edges (as vertices)
- Connect a vertex v to an edge e if they are connected in G



Goal: find cheapest matching of size k in B

Goal: find cheapest matching of size *k* in *B*

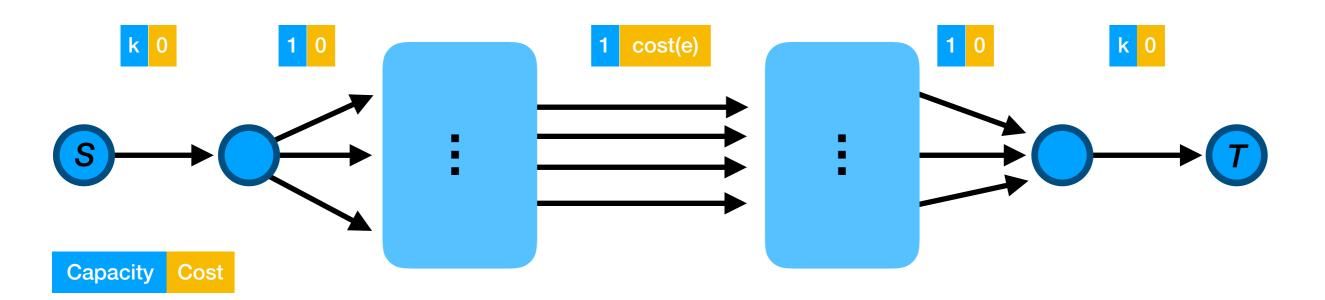
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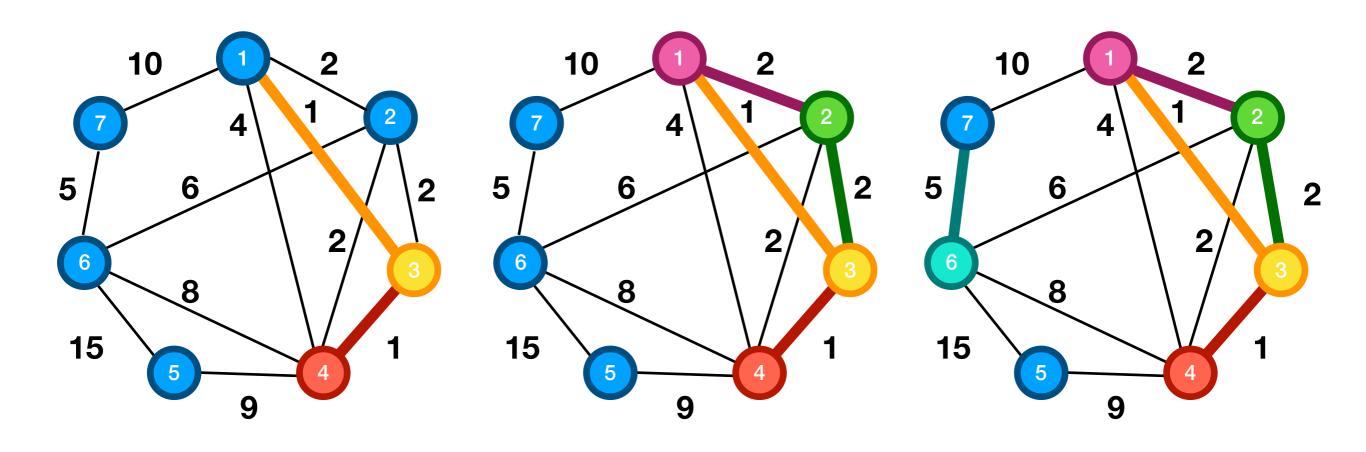
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Greedy Solution



- "Prim's algorithm for minimum spanning tree": $O(m + n \log n)$
- sort the edges by their costs
- add them one by one
- skip edges that make a component have more edges than vertices